



Sun Performance Library Reference Manual

Sun™ Studio 10

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Sun Performance Library[™] Reference Manual

Sun[™] Studio 10

This reference manual is a PDF version of the section 3P man pages. For additional information, see the *Sun Performance Library User's Guide*, available on `docs.sun.com`, or the *LAPACK Users' Guide*, available from the Society for Industrial and Applied Mathematics (SIAM).

[available_threads](#) - available_threads - returns information about current thread usage

[blas_dpermute](#) - blas_dpermute - permutes a real (double precision) array in terms of the permutation vector P, output by dsortv

[blas_dsort](#) - blas_dsort - sorts a real (double precision) vector X in increasing or decreasing order using quick sort algorithm

[blas_dsortv](#) - blas_dsortv - sorts a real (double precision) vector X in increasing or decreasing order using quick sort algorithm and overwrite P with the permutation vector

[blas_ipermute](#) - blas_ipermute - permutes an integer array in terms of the permutation vector P, output by dsortv

[blas_isort](#) - blas_isort - sorts an integer vector X in increasing or decreasing order using quick sort algorithm

[blas_isortv](#) - blas_isortv - sorts a real vector X in increasing or decreasing order using quick sort algorithm and overwrite P with the permutation vector

[blas_spermute](#) - blas_spermute - permutes a real array in terms of the permutation vector P, output by dsortv

[blas_ssort](#) - blas_ssort - sorts a real vector X in increasing or decreasing order using quick sort algorithm

[blas_ssortv](#) - blas_ssortv - sorts a real vector X in increasing or decreasing order using quick sort algorithm and overwrite P with the permutation vector

[caxpy](#) - caxpy - compute $y := \alpha * x + y$

[caxpyi](#) - caxpyi - Compute $y := \alpha * x + y$

[cbcomm](#) - cbcomm - block coordinate matrix-matrix multiply

[cbdimm](#) - cbdimm - block diagonal format matrix-matrix multiply

[cbdism](#) - cbdism - block diagonal format triangular solve

[cbdsqr](#) - cbdsqr - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B.

[cbelmm](#) - cbelmm - block Ellpack format matrix-matrix multiply

[cbelsm](#) - cbelsm - block Ellpack format triangular solve

[cbsemm](#) - cbsemm - block sparse column matrix-matrix multiply

[cbscsm](#) - cbscsm - block sparse column format triangular solve

[cbsrmm](#) - cbsrmm - block sparse row format matrix-matrix multiply

[cbsrsm](#) - cbsrsm - block sparse row format triangular solve

[ccnvcor](#) - ccnvcor - compute the convolution or correlation of complex vectors

[ccnvcor2](#) - ccnvcor2 - compute the convolution or correlation of complex matrices

[ccoomm](#) - ccoomm - coordinate matrix-matrix multiply

[ccopy](#) - ccopy - Copy x to y

[ccscmm](#) - ccscmm - compressed sparse column format matrix-matrix multiply

[ccscsm](#) - ccscsm - compressed sparse column format triangular solve

[ccsrmm](#) - ccsrmm - compressed sparse row format matrix-matrix multiply

[ccsrsm](#) - ccsrsm - compressed sparse row format triangular solve

[cdiamm](#) - cdiamm - diagonal format matrix-matrix multiply

[cdiasm](#) - cdiasm - diagonal format triangular solve

[cdotc](#) - cdotc - compute the dot product of two vectors conjg(x) and y.

[cdotci](#) - cdotci - Compute the complex conjugated indexed dot product.

[cdotu](#) - cdotu - compute the dot product of two vectors x and y.

[cdotui](#) - cdotui - Compute the complex unconjugated indexed dot product.

[cellmm](#) - cellmm - Ellpack format matrix-matrix multiply

[cellsm](#) - cellsm - Ellpack format triangular solve

[cfft2b](#) - cfft2b - compute a periodic sequence from its Fourier coefficients. The xFFT operations are unnormalized, so a call of xFFT2F followed by a call of xFFT2B will multiply the input sequence by $M*N$.

[cfft2f](#) - cfft2f - compute the Fourier coefficients of a periodic sequence. The xFFT operations are unnormalized, so a call of xFFT2F followed by a call of xFFT2B will multiply the input sequence by $M*N$.

[cfft2i](#) - cfft2i - initialize the array WSAVE, which is used in both the forward and backward transforms.

[cfft3b](#) - cfft3b - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of CFFT3F followed by a call of CFFT3B will multiply the input sequence by $M*N*K$.

[cfft3f](#) - cfft3f - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of CFFT3F followed by a call of CFFT3B will multiply the input sequence by $M*N*K$.

[cfft3i](#) - cfft3i - initialize the array WSAVE, which is used in both CFFT3F and CFFT3B.

[cftfb](#) - cftfb - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of CFFTF followed by a call of CFFTB will multiply the input sequence by N .

[cftfc](#) - cftfc - initialize the trigonometric weight and factor tables or compute the Fast Fourier transform (forward or inverse) of a complex sequence.

[cftfc2](#) - cftfc2 - initialize the trigonometric weight and factor tables or compute the two-dimensional Fast Fourier Transform (forward or inverse) of a two-dimensional complex array.

[cftfc3](#) - cftfc3 - initialize the trigonometric weight and factor tables or compute the three-dimensional Fast Fourier Transform (forward or inverse) of a three-dimensional complex array.

[cftfcm](#) - cftfcm - initialize the trigonometric weight and factor tables or compute the one-dimensional Fast Fourier Transform (forward or inverse) of a set of data sequences stored in a two-dimensional complex array.

[cftff](#) - cftff - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of CFFTF followed by a call of CFFTB will multiply the input sequence by N .

[cftfi](#) - cftfi - initialize the array WSAVE, which is used in both CFFTF and CFFTB.

[cffttop](#) - cffttop - compute the length of the closest fast FFT

[cfft](#) - cfft - initialize the trigonometric weight and factor tables or compute the inverse Fast Fourier Transform of a complex sequence as follows.

[cfft2](#) - cfft2 - initialize the trigonometric weight and factor tables or compute the two-dimensional inverse Fast Fourier Transform of a two-dimensional complex array.

[cfft3](#) - cfft3 - initialize the trigonometric weight and factor tables or compute the three-dimensional inverse Fast Fourier Transform of a three-dimensional complex array.

[cfftsm](#) - cfftsm - initialize the trigonometric weight and factor tables or compute the one-dimensional inverse Fast Fourier Transform of a set of complex data sequences stored in a two-dimensional array.

[cgbbd](#) - cgbbd - reduce a complex general m-by-n band matrix A to real upper bidiagonal form B by a unitary transformation

[cgbcn](#) - cgbcn - estimate the reciprocal of the condition number of a complex general band matrix A, in either the 1-norm or the infinity-norm,

[cgbequ](#) - cgbequ - compute row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number

[cgbm](#) - cgbm - perform one of the matrix-vector operations $y := \alpha * A * x + \beta * y$, or $y := \alpha * A' * x + \beta * y$, or $y := \alpha * \text{conj}(A') * x + \beta * y$

[cgbrfs](#) - cgbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution

[cgbsv](#) - cgbsv - compute the solution to a complex system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices

[cgbsvx](#) - cgbsvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A ** T * X = B$, or $A ** H * X = B$,

[cgbt2](#) - cgbt2 - compute an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges

[cgbtrf](#) - cgbtrf - compute an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges

[cgbrs](#) - cgbrs - solve a system of linear equations $A * X = B$, $A ** T * X = B$, or $A ** H * X = B$ with a general band matrix A using the LU factorization computed by CGBTRF

[cgebak](#) - cgebak - form the right or left eigenvectors of a complex general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by CGEBAL

[cgebal](#) - cgebal - balance a general complex matrix A

[cgebrd](#) - cgebrd - reduce a general complex M-by-N matrix A to upper or lower bidiagonal form B by a unitary transformation

[cgecon](#) - cgecon - estimate the reciprocal of the condition number of a general complex matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by CGETRF

[cgeequ](#) - cgeequ - compute row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number

[cgees](#) - cgees - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z

[cgeesx](#) - cgeesx - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z

[cgeev](#) - cgeev - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

[cgeevx](#) - cgeevx - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

[cgegs](#) - cgegs - routine is deprecated and has been replaced by routine CGGES

[cgegv](#) - cgegv - routine is deprecated and has been replaced by routine CGGEV

[cgehrd](#) - cgehrd - reduce a complex general matrix A to upper Hessenberg form H by a unitary similarity transformation

[cgelqf](#) - cgelqf - compute an LQ factorization of a complex M-by-N matrix A

[cgels](#) - cgels - solve overdetermined or underdetermined complex linear systems involving an M-by-N matrix A, or its conjugate-transpose, using a QR or LQ factorization of A

[cgelsd](#) - cgelsd - compute the minimum-norm solution to a real linear least squares problem

[cgelss](#) - cgelss - compute the minimum norm solution to a complex linear least squares problem

[cgelsx](#) - cgelsx - routine is deprecated and has been replaced by routine CGELSY

[cgelsy](#) - cgelsy - compute the minimum-norm solution to a complex linear least squares problem

[cgemm](#) - cgemm - perform one of the matrix-matrix operations $C := \alpha * op(A) * op(B) + \beta * C$

[cgemv](#) - cgemv - perform one of the matrix-vector operations $y := \alpha * A * x + \beta * y$, or $y := \alpha * A' * x + \beta * y$, or $y := \alpha * conjg(A') * x + \beta * y$

[cgeqlf](#) - cgeqlf - compute a QL factorization of a complex M-by-N matrix A

[cgeqp3](#) - cgeqp3 - compute a QR factorization with column pivoting of a matrix A

[cgeqpf](#) - cgeqpf - routine is deprecated and has been replaced by routine CGEQP3

[cgeqrf](#) - cgeqrf - compute a QR factorization of a complex M-by-N matrix A

[cgerc](#) - cgerc - perform the rank 1 operation $A := \alpha * x * \text{conj}(y') + A$

[cgerfs](#) - cgerfs - improve the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution

[cgerqf](#) - cgerqf - compute an RQ factorization of a complex M-by-N matrix A

[cgeru](#) - cgeru - perform the rank 1 operation $A := \alpha * x * y' + A$

[cgesdd](#) - cgesdd - compute the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors, by using divide-and-conquer method

[cgesv](#) - cgesv - compute the solution to a complex system of linear equations $A * X = B$,

[cgesvd](#) - cgesvd - compute the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors

[cgesvx](#) - cgesvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$,

[cgetf2](#) - cgetf2 - compute an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges

[cgetrf](#) - cgetrf - compute an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges

[cgetri](#) - cgetri - compute the inverse of a matrix using the LU factorization computed by CGETRF

[cgetrs](#) - cgetrs - solve a system of linear equations $A * X = B$, $A ** T * X = B$, or $A ** H * X = B$ with a general N-by-N matrix A using the LU factorization computed by CGETRF

[cggbak](#) - cggbak - form the right or left eigenvectors of a complex generalized eigenvalue problem $A * x = \lambda * B * x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by CGGBAL

[cggbal](#) - cggbal - balance a pair of general complex matrices (A,B)

[cgges](#) - cgges - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the generalized complex Schur form (S, T), and optionally left and/or right Schur vectors (VSL and VSR)

[cggesx](#) - cggesx - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the complex Schur form (S,T),

[cggev](#) - cggev - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors

[cggevz](#) - cggevz - compute for a pair of N-by-N complex nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors

[cggglm](#) - cggglm - solve a general Gauss-Markov linear model (GLM) problem

[cgghrd](#) - cgghrd - reduce a pair of complex matrices (A,B) to generalized upper Hessenberg form using unitary transformations, where A is a general matrix and B is upper triangular

[cgglse](#) - cgglse - solve the linear equality-constrained least squares (LSE) problem

[cggqrf](#) - cggqrf - compute a generalized QR factorization of an N-by-M matrix A and an N-by-P matrix B.

[cggrqf](#) - cggrqf - compute a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B

[cggsvd](#) - cggsvd - compute the generalized singular value decomposition (GSVD) of an M-by-N complex matrix A and P-by-N complex matrix B

[cggsvp](#) - cggsvp - compute unitary matrices U, V and Q such that $N-K-L \times K \times L \times U^* \times A^* \times Q = K \times (0 \ A12 \ A13)$ if $M-K-L \geq 0$

[cgssco](#) - cgssco - General sparse solver condition number estimate.

[cgssda](#) - cgssda - Deallocate working storage for the general sparse solver.

[cgssfa](#) - cgssfa - General sparse solver numeric factorization.

[cgssfs](#) - cgssfs - General sparse solver one call interface.

[cgssin](#) - cgssin - Initialize the general sparse solver.

[cgssor](#) - cgssor - General sparse solver ordering and symbolic factorization.

[cgssps](#) - cgssps - Print general sparse solver statics.

[cgssrp](#) - cgssrp - Return permutation used by the general sparse solver.

[cgsssl](#) - cgsssl - Solve routine for the general sparse solver.

[cgssuo](#) - cgssuo - User supplied permutation for ordering used in the general sparse solver.

[cgtcon](#) - cgtcon - estimate the reciprocal of the condition number of a complex tridiagonal matrix A using the LU factorization as computed by CGTTRF

[cgthr](#) - cgthr - Gathers specified elements from y into x.

[cgthrz](#) - cgthrz - Gather and zero.

[cgtfrs](#) - cgtfrs - improve the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution

[cgtsv](#) - cgtsv - solve the equation $A * X = B$,

[cgtsvx](#) - cgtsvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

[cgtrf](#) - cgtrf - compute an LU factorization of a complex tridiagonal matrix A using elimination with partial pivoting and row interchanges

[cgtrs](#) - cgtrs - solve one of the systems of equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

[chbev](#) - chbev - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

[chbevd](#) - chbevd - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

[chbevz](#) - chbevz - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

[chbgst](#) - chbgst - reduce a complex Hermitian-definite banded generalized eigenproblem $A * x = \lambda * B * x$ to standard form $C * y = \lambda * y$,

[chbgv](#) - chbgv - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A * x = (\lambda * B) * x$

[chbgvd](#) - chbgvd - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A * x = (\lambda * B) * x$

[chbgvx](#) - chbgvx - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A * x = (\lambda * B) * x$

[chbmV](#) - chbmV - perform the matrix-vector operation $y := \alpha * A * x + \beta * y$

[chbtrd](#) - chbtrd - reduce a complex Hermitian band matrix A to real symmetric tridiagonal form T by a unitary similarity transformation

[checon](#) - checon - estimate the reciprocal of the condition number of a complex Hermitian matrix A using the factorization $A = U*D*U**H$ or $A = L*D*L**H$ computed by CHETRF

[cheev](#) - cheev - compute all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

[cheevd](#) - cheevd - compute all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

[cheevr](#) - cheevr - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian tridiagonal matrix T

[cheevx](#) - cheevx - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

[chegs2](#) - chesg2 - reduce a complex Hermitian-definite generalized eigenproblem to standard form

[chegst](#) - chesgt - reduce a complex Hermitian-definite generalized eigenproblem to standard form

[chegv](#) - chegv - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(lambda)*B*x$, $A*Bx=(lambda)*x$, or $B*A*x=(lambda)*x$

[chegvd](#) - chegvd - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(lambda)*B*x$, $A*Bx=(lambda)*x$, or $B*A*x=(lambda)*x$

[chegvx](#) - chegvx - compute selected eigenvalues, and optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(lambda)*B*x$, $A*Bx=(lambda)*x$, or $B*A*x=(lambda)*x$

[chemm](#) - chemm - perform one of the matrix-matrix operations $C := alpha*A*B + beta*C$ or $C := alpha*B*A + beta*C$

[chemv](#) - chemv - perform the matrix-vector operation $y := alpha*A*x + beta*y$

[cher](#) - cher - perform the hermitian rank 1 operation $A := alpha*x*conjg(x') + A$

[cher2](#) - cher2 - perform the hermitian rank 2 operation $A := alpha*x*conjg(y') + conjg(alpha)*y*conjg(x') + A$

[cher2k](#) - cher2k - perform one of the Hermitian rank 2k operations $C := alpha*A*conjg(B') + conjg(alpha)*B*conjg(A') + beta*C$ or $C := alpha*conjg(A')*B + conjg(alpha)*conjg(B')*A + beta*C$

[cherfs](#) - cherfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite, and provides error bounds and backward error estimates for the solution

[cherk](#) - cherk - perform one of the Hermitian rank k operations $C := alpha*A*conjg(A') + beta*C$ or $C := alpha*conjg(A')*A + beta*C$

[chesv](#) - chesv - compute the solution to a complex system of linear equations $A * X = B$,

[chesvx](#) - chesvx - use the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$,

[chetf2](#) - chetf2 - compute the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method

[chetrd](#) - chetrd - reduce a complex Hermitian matrix A to real symmetric tridiagonal form T by a unitary similarity transformation

[chetrf](#) - chetrf - compute the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method

[chetri](#) - chetri - compute the inverse of a complex Hermitian indefinite matrix A using the factorization $A = U * D * U ** H$ or $A = L * D * L ** H$ computed by CHETRF

[chetrs](#) - chetrs - solve a system of linear equations $A * X = B$ with a complex Hermitian matrix A using the factorization $A = U * D * U ** H$ or $A = L * D * L ** H$ computed by CHETRF

[chgeqz](#) - chgeqz - implement a single-shift version of the QZ method for finding the generalized eigenvalues $w(i) = \text{ALPHA}(i) / \text{BETA}(i)$ of the equation $\det(A - w(i) B) = 0$. If JOB='S', then the pair (A,B) is simultaneously reduced to Schur form (i. e., A and B are both upper triangular) by applying one unitary transformation (usually called Q) on the left and another (usually called Z) on the right

[chpcon](#) - chpcon - estimate the reciprocal of the condition number of a complex Hermitian packed matrix A using the factorization $A = U * D * U ** H$ or $A = L * D * L ** H$ computed by CHPTRF

[chpev](#) - chpev - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix in packed storage

[chpevd](#) - chpevd - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage

[chpevx](#) - chpevx - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage

[chpgst](#) - chpgst - reduce a complex Hermitian-definite generalized eigenproblem to standard form, using packed storage

[chpgv](#) - chpgv - compute all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A * x = (\text{lambda}) * B * x$, $A * B x = (\text{lambda}) * x$, or $B * A * x = (\text{lambda}) * x$

[chpgvd](#) - chpgvd - compute all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A * x = (\text{lambda}) * B * x$, $A * B x = (\text{lambda}) * x$, or $B * A * x = (\text{lambda}) * x$

[chpgvx](#) - chpgvx - compute selected eigenvalues and, optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A * x = (\text{lambda}) * B * x$, $A * B x = (\text{lambda}) * x$, or $B * A * x = (\text{lambda}) * x$

[chpmv](#) - chpmv - perform the matrix-vector operation $y := \text{alpha} * A * x + \text{beta} * y$

[chpr](#) - chpr - perform the hermitian rank 1 operation $A := \alpha * x * \text{conjg}(x') + A$

[chpr2](#) - chpr2 - perform the Hermitian rank 2 operation $A := \alpha * x * \text{conjg}(y') + \text{conjg}(\alpha) * y * \text{conjg}(x') + A$

[chprfs](#) - chprfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite and packed, and provides error bounds and backward error estimates for the solution

[chpsv](#) - chpsv - compute the solution to a complex system of linear equations $A * X = B$,

[chpsvx](#) - chpsvx - use the diagonal pivoting factorization $A = U * D * U^{**H}$ or $A = L * D * L^{**H}$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N Hermitian matrix stored in packed format and X and B are N-by-NRHS matrices

[chptrd](#) - chptrd - reduce a complex Hermitian matrix A stored in packed form to real symmetric tridiagonal form T by a unitary similarity transformation

[chptrf](#) - chptrf - compute the factorization of a complex Hermitian packed matrix A using the Bunch-Kaufman diagonal pivoting method

[chptri](#) - chptri - compute the inverse of a complex Hermitian indefinite matrix A in packed storage using the factorization $A = U * D * U^{**H}$ or $A = L * D * L^{**H}$ computed by CHPTRF

[chptrs](#) - chptrs - solve a system of linear equations $A * X = B$ with a complex Hermitian matrix A stored in packed format using the factorization $A = U * D * U^{**H}$ or $A = L * D * L^{**H}$ computed by CHPTRF

[chsein](#) - chsein - use inverse iteration to find specified right and/or left eigenvectors of a complex upper Hessenberg matrix H

[chseqr](#) - chseqr - compute the eigenvalues of a complex upper Hessenberg matrix H, and, optionally, the matrices T and Z from the Schur decomposition $H = Z * T * Z^{**H}$, where T is an upper triangular matrix (the Schur form), and Z is the unitary matrix of Schur vectors

[cjadmm](#) - cjadmm - Jagged diagonal matrix-matrix multiply (modified Ellpack)

[cjadrp](#) - cjadrp - right permutation of a jagged diagonal matrix

[cjadsm](#) - cjadsm - Jagged-diagonal format triangular solve

[clarz](#) - clarz - apply a complex elementary reflector H to a complex M-by-N matrix C, from either the left or the right

[clarzb](#) - clarzb - apply a complex block reflector H or its transpose H^{**H} to a complex distributed M-by-N C from the left or the right

[clarzt](#) - clarzt - form the triangular factor T of a complex block reflector H of order $> n$, which is defined as a product of k elementary reflectors

[clatzm](#) - clatzm - routine is deprecated and has been replaced by routine CUNMRZ

[cosqb](#) - cosqb - synthesize a Fourier sequence from its representation in terms of a cosine series with odd wave numbers. The COSQ operations are unnormalized inverses of themselves, so a call to COSQF followed by a call to COSQB will multiply the input sequence by $4 * N$.

[cosqf](#) - cosqf - compute the Fourier coefficients in a cosine series representation with only odd wave numbers. The COSQ operations are unnormalized inverses of themselves, so a call to COSQF followed by a call to COSQB will multiply the input sequence by $4 * N$.

[cosqi](#) - cosqi - initialize the array WSAVE, which is used in both COSQF and COSQB.

[cost](#) - cost - compute the discrete Fourier cosine transform of an even sequence. The COST transforms are unnormalized inverses of themselves, so a call of COST followed by another call of COST will multiply the input sequence by $2 * (N-1)$.

[costi](#) - costi - initialize the array WSAVE, which is used in COST.

[cpbcon](#) - cpbcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite band matrix using the Cholesky factorization $A = U^{**}H*U$ or $A = L*L^{**}H$ computed by CPBTRF

[cpbequ](#) - cpbequ - compute row and column scalings intended to equilibrate a Hermitian positive definite band matrix A and reduce its condition number (with respect to the two-norm)

[cpbrfs](#) - cpbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and banded, and provides error bounds and backward error estimates for the solution

[cpbstf](#) - cpbstf - compute a split Cholesky factorization of a complex Hermitian positive definite band matrix A

[cpbsv](#) - cpbsv - compute the solution to a complex system of linear equations $A * X = B$,

[cpbsvx](#) - cpbsvx - use the Cholesky factorization $A = U^{**}H*U$ or $A = L*L^{**}H$ to compute the solution to a complex system of linear equations $A * X = B$,

[cpbtf2](#) - cpbtf2 - compute the Cholesky factorization of a complex Hermitian positive definite band matrix A

[cpbtrf](#) - cpbtrf - compute the Cholesky factorization of a complex Hermitian positive definite band matrix A

[cpbtrs](#) - cpbtrs - solve a system of linear equations $A*X = B$ with a Hermitian positive definite band matrix A using the Cholesky factorization $A = U^{**}H*U$ or $A = L*L^{**}H$ computed by CPBTRF

[cpocon](#) - cpocon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite matrix using the Cholesky factorization $A = U^{**}H*U$ or $A = L*L^{**}H$ computed by CPOTRF

[cpoequ](#) - cpoequ - compute row and column scalings intended to equilibrate a Hermitian positive definite matrix A and reduce its condition number (with respect to the two-norm)

[cporfs](#) - cporfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite,

[cposv](#) - cposv - compute the solution to a complex system of linear equations $A * X = B$,

[cposvx](#) - cposvx - use the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ to compute the solution to a complex system of linear equations $A * X = B$,

[cpotf2](#) - cpotf2 - compute the Cholesky factorization of a complex Hermitian positive definite matrix A

[cpotrf](#) - cpotrf - compute the Cholesky factorization of a complex Hermitian positive definite matrix A

[cpotri](#) - cpotri - compute the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by CPOTRF

[cpotrs](#) - cpotrs - solve a system of linear equations $A*X = B$ with a Hermitian positive definite matrix A using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by CPOTRF

[cppcon](#) - cppcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite packed matrix using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by CPPTRF

[cppequ](#) - cppequ - compute row and column scalings intended to equilibrate a Hermitian positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm)

[cprfs](#) - cprfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and packed, and provides error bounds and backward error estimates for the solution

[cppsv](#) - cppsv - compute the solution to a complex system of linear equations $A * X = B$,

[cppsvx](#) - cppsvx - use the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ to compute the solution to a complex system of linear equations $A * X = B$,

[cpptrf](#) - cpptrf - compute the Cholesky factorization of a complex Hermitian positive definite matrix A stored in packed format

[cpptri](#) - cpptri - compute the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by CPPTRF

[cpptrs](#) - cpptrs - solve a system of linear equations $A*X = B$ with a Hermitian positive definite matrix A in packed storage using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by CPPTRF

[cptcon](#) - cptcon - compute the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite tridiagonal matrix using the factorization $A = L*D*L**H$ or $A = U**H*D*U$ computed by CPTTRF

[cpteqr](#) - cpteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix

by first factoring the matrix using SPTTRF and then calling CBDSQR to compute the singular values of the bidiagonal factor

[cptrfs](#) - cptrfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution

[cptsv](#) - cptsv - compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N Hermitian positive definite tridiagonal matrix, and X and B are N-by-NRHS matrices.

[cptsvx](#) - cptsvx - use the factorization $A = L * D * L ** H$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N Hermitian positive definite tridiagonal matrix and X and B are N-by-NRHS matrices

[cpttrf](#) - cpttrf - compute the $L * D * L'$ factorization of a complex Hermitian positive definite tridiagonal matrix A

[cpttrs](#) - cpttrs - solve a tridiagonal system of the form $A * X = B$ using the factorization $A = U' * D * U$ or $A = L * D * L'$ computed by CPTTRF

[cptts2](#) - cptts2 - solve a tridiagonal system of the form $A * X = B$ using the factorization $A = U' * D * U$ or $A = L * D * L'$ computed by CPTTRF

[crot](#) - crot - apply a plane rotation, where the cos (C) is real and the sin (S) is complex, and the vectors X and Y are complex

[crotg](#) - crotg - Construct a Given's plane rotation

[cscal](#) - cscal - Compute $y := \alpha * y$

[csctr](#) - csctr - Scatters elements from x into y.

[cskymm](#) - cskymm - Skyline format matrix-matrix multiply

[cskysm](#) - cskysm - Skyline format triangular solve

[cspcon](#) - cspcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex symmetric packed matrix A using the factorization $A = U * D * U ** T$ or $A = L * D * L ** T$ computed by CSPTRF

[csprfs](#) - csprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution

[cspsv](#) - cspsv - compute the solution to a complex system of linear equations $A * X = B$,

[cspsvx](#) - cspsvx - use the diagonal pivoting factorization $A = U * D * U ** T$ or $A = L * D * L ** T$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices

[csptf](#) - csptf - compute the factorization of a complex symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method

[csptri](#) - csptri - compute the inverse of a complex symmetric indefinite matrix A in packed storage using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by CSPTRF

[csptrs](#) - csptrs - solve a system of linear equations $A*X = B$ with a complex symmetric matrix A stored in packed format using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by CSPTRF

[csrot](#) - csrot - Apply a plane rotation.

[csscal](#) - csscal - Compute $y := \alpha * y$

[cstedc](#) - cstedc - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method

[cstegr](#) - cstegr - Compute $T\text{-}\sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation

[cstein](#) - cstein - compute the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration

[csteqr](#) - csteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method

[cstsv](#) - cstsv - compute the solution to a complex system of linear equations $A * X = B$ where A is a symmetric tridiagonal matrix

[csttrf](#) - csttrf - compute the factorization of a complex symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method

[csttrs](#) - csttrs - computes the solution to a complex system of linear equations $A * X = B$

[cswap](#) - cswap - Exchange vectors x and y.

[csycon](#) - csycon - estimate the reciprocal of the condition number (in the 1-norm) of a complex symmetric matrix A using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by CSYTRF

[csymm](#) - csymm - perform one of the matrix-matrix operations $C := \alpha*A*B + \beta*C$ or $C := \alpha*B*A + \beta*C$

[csyr2k](#) - csyr2k - perform one of the symmetric rank 2k operations $C := \alpha*A*B' + \alpha*B*A' + \beta*C$ or $C := \alpha*A'*B + \alpha*B'*A + \beta*C$

[csyrfs](#) - csyrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution

[csyrk](#) - csyrk - perform one of the symmetric rank k operations $C := \alpha * A * A' + \beta * C$ or $C := \alpha * A' * A + \beta * C$

[csysv](#) - csysv - compute the solution to a complex system of linear equations $A * X = B$,

[csysvx](#) - csysvx - use the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$,

[csytf2](#) - csytf2 - compute the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

[csytrf](#) - csytrf - compute the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

[csytri](#) - csytri - compute the inverse of a complex symmetric indefinite matrix A using the factorization $A = U * D * U' * T$ or $A = L * D * L' * T$ computed by CSYTRF

[csytrs](#) - csytrs - solve a system of linear equations $A * X = B$ with a complex symmetric matrix A using the factorization $A = U * D * U' * T$ or $A = L * D * L' * T$ computed by CSYTRF

[ctbcon](#) - ctbcon - estimate the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm

[ctbmV](#) - ctbmv - perform one of the matrix-vector operations $x := A * x$, or $x := A' * x$, or $x := \text{conjg}(A') * x$

[ctbrfs](#) - ctbrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix

[ctbsv](#) - ctbsv - solve one of the systems of equations $A * x = b$, or $A' * x = b$, or $\text{conjg}(A') * x = b$

[ctbtrs](#) - ctbtrs - solve a triangular system of the form $A * X = B$, $A' * X = B$, or $A' * H * X = B$,

[ctgevc](#) - ctgevc - compute some or all of the right and/or left generalized eigenvectors of a pair of complex upper triangular matrices (A,B)

[ctgexc](#) - ctgexc - reorder the generalized Schur decomposition of a complex matrix pair (A,B), using an unitary equivalence transformation $(A, B) := Q * (A, B) * Z'$, so that the diagonal block of (A, B) with row index IFST is moved to row ILST

[ctgsen](#) - ctgsen - reorder the generalized Schur decomposition of a complex matrix pair (A, B) (in terms of an unitary equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the pair (A,B)

[ctgsja](#) - ctgsja - compute the generalized singular value decomposition (GSVD) of two complex upper triangular (or trapezoidal) matrices A and B

[ctgsna](#) - ctgsna - estimate reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A,

B)

[ctgsyl](#) - ctgsyl - solve the generalized Sylvester equation

[ctpcon](#) - ctpcon - estimate the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm

[ctpmv](#) - ctpmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$

[ctprfs](#) - ctprfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix

[ctpsv](#) - ctpsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A')*x = b$

[ctptri](#) - ctptri - compute the inverse of a complex upper or lower triangular matrix A stored in packed format

[ctptrs](#) - ctptrs - solve a triangular system of the form $A * X = B$, $A**T * X = B$, or $A**H * X = B$,

[ctrans](#) - ctrans - transpose and scale source matrix

[ctrcon](#) - ctrcon - estimate the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm

[ctrevc](#) - ctrevc - compute some or all of the right and/or left eigenvectors of a complex upper triangular matrix T

[ctrex](#) - ctrex - reorder the Schur factorization of a complex matrix $A = Q*T*Q**H$, so that the diagonal element of T with row index IFST is moved to row ILST

[ctrmm](#) - ctrmm - perform one of the matrix-matrix operations $B := \alpha*\text{op}(A)*B$, or $B := \alpha*B*\text{op}(A)$ where alpha is a scalar, B is an m by n matrix, A is a unit, or non-unit, upper or lower triangular matrix and $\text{op}(A)$ is one of $\text{op}(A) = A$ or $\text{op}(A) = A'$ or $\text{op}(A) = \text{conjg}(A')$

[ctrmv](#) - ctrmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$

[ctrfs](#) - ctrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix

[ctrsen](#) - ctrsen - reorder the Schur factorization of a complex matrix $A = Q*T*Q**H$, so that a selected cluster of eigenvalues appears in the leading positions on the diagonal of the upper triangular matrix T, and the leading columns of Q form an orthonormal basis of the corresponding right invariant subspace

[ctrsm](#) - ctrsm - solve one of the matrix equations $\text{op}(A)*X = \alpha*B$, or $X*\text{op}(A) = \alpha*B$

[ctrzna](#) - ctrzna - estimate reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a complex upper triangular matrix T (or of any matrix $Q*T*Q**H$ with Q unitary)

[ctrsv](#) - ctrsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A)*x = b$

[ctrsyl](#) - ctrsyl - solve the complex Sylvester matrix equation

[ctri2](#) - ctri2 - compute the inverse of a complex upper or lower triangular matrix

[ctrtri](#) - ctrtri - compute the inverse of a complex upper or lower triangular matrix A

[ctrtrs](#) - ctrtrs - solve a triangular system of the form $A * X = B$, $A**T * X = B$, or $A**H * X = B$,

[ctzrqf](#) - ctzrqf - routine is deprecated and has been replaced by routine CTZRZF

[ctzrzf](#) - ctzrzf - reduce the M-by-N ($M \leq N$) complex upper trapezoidal matrix A to upper triangular form by means of unitary transformations

[cung2l](#) - cung2l - generate an m by n complex matrix Q with orthonormal columns,

[cung2r](#) - cung2r - generate an m by n complex matrix Q with orthonormal columns,

[cungbr](#) - cungbr - generate one of the complex unitary matrices Q or $P**H$ determined by CGEBRD when reducing a complex matrix A to bidiagonal form

[cunghr](#) - cunghr - generate a complex unitary matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N, as returned by CGEHRD

[cungl2](#) - cungl2 - generate an m-by-n complex matrix Q with orthonormal rows,

[cunglq](#) - cunglq - generate an M-by-N complex matrix Q with orthonormal rows,

[cungql](#) - cungql - generate an M-by-N complex matrix Q with orthonormal columns,

[cungqr](#) - cungqr - generate an M-by-N complex matrix Q with orthonormal columns,

[cungr2](#) - cungr2 - generate an m by n complex matrix Q with orthonormal rows,

[cungrq](#) - cungrq - generate an M-by-N complex matrix Q with orthonormal rows,

[cungrt](#) - cungrt - generate a complex unitary matrix Q which is defined as the product of n-1 elementary reflectors of order N, as returned by CHETRD

[cunmbr](#) - cunmbr - VECT = 'Q', CUNMBR overwrites the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[cunmhr](#) - cunmhr - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[cunml2](#) - cunml2 - overwrite the general complex m-by-n matrix C with Q * C if SIDE = 'L' and TRANS = 'N', or Q'* C if SIDE = 'L' and TRANS = 'C', or C * Q if SIDE = 'R' and TRANS = 'N', or C * Q' if SIDE = 'R' and TRANS = 'C',

[cunmlq](#) - cunmlq - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[cunmq1](#) - cunmq1 - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[cunmqr](#) - cunmqr - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[cunmr2](#) - cunmr2 - overwrite the general complex m-by-n matrix C with Q * C if SIDE = 'L' and TRANS = 'N', or Q'* C if SIDE = 'L' and TRANS = 'C', or C * Q if SIDE = 'R' and TRANS = 'N', or C * Q' if SIDE = 'R' and TRANS = 'C',

[cunmrq](#) - cunmrq - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[cunmrz](#) - cunmrz - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[cunmtr](#) - cunmtr - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[cupgtr](#) - cupgtr - generate a complex unitary matrix Q which is defined as the product of n-1 elementary reflectors H(i) of order n, as returned by CHPTRD using packed storage

[cupmtr](#) - cupmtr - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[cvbrmm](#) - cvbrmm - variable block sparse row format matrix-matrix multiply

[cvbrsm](#) - cvbrsm - variable block sparse row format triangular solve

[cvmul](#) - cvmul - compute the scaled product of complex vectors

[dasum](#) - dasum - Return the sum of the absolute values of a vector x.

[daxpy](#) - daxpy - compute $y := \alpha * x + y$

[daxpyi](#) - daxpyi - Compute $y := \alpha * x + y$

[dbcomm](#) - dbcomm - block coordinate matrix-matrix multiply

[dbdimm](#) - dbdimm - block diagonal format matrix-matrix multiply

[dbdism](#) - dbdism - block diagonal format triangular solve

[dbdsdc](#) - dbdsdc - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B

[dbdsqr](#) - dbdsqr - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B.

[dbelmm](#) - dbelmm - block Ellpack format matrix-matrix multiply

[dbelsm](#) - dbelsm - block Ellpack format triangular solve

[dbscmm](#) - dbscmm - block sparse column matrix-matrix multiply

[dbscsm](#) - dbscsm - block sparse column format triangular solve

[dbsrmm](#) - dbsrmm - block sparse row format matrix-matrix multiply

[dbsrsm](#) - dbsrsm - block sparse row format triangular solve

[dcnvcor](#) - dcnvcor - compute the convolution or correlation of real vectors

[dcnvcor2](#) - dcnvcor2 - compute the convolution or correlation of real matrices

[dcoomm](#) - dcoomm - coordinate matrix-matrix multiply

[dcopy](#) - dcopy - Copy x to y

[dcosqb](#) - dcosqb - synthesize a Fourier sequence from its representation in terms of a cosine series with odd wave numbers. The COSQ operations are unnormalized inverses of themselves, so a call to COSQF followed by a call to COSQB will multiply the input sequence by $4 * N$.

[dcosqf](#) - dcosqf - compute the Fourier coefficients in a cosine series representation with only odd wave numbers. The COSQ operations are unnormalized inverses of themselves, so a call to COSQF followed by a call to COSQB will multiply the input sequence by $4 * N$.

[dcosqi](#) - dcosqi - initialize the array WSAVE, which is used in both COSQF and COSQB.

[dcost](#) - dcost - compute the discrete Fourier cosine transform of an even sequence. The COST transforms are unnormalized inverses of themselves, so a call of COST followed by another call of COST will multiply the input sequence by $2 * (N-1)$.

[dcosti](#) - dcosti - initialize the array WSAVE, which is used in COST.

[dcscmm](#) - dcscmm - compressed sparse column format matrix-matrix multiply

[dcscsm](#) - dcscsm - compressed sparse column format triangular solve

[dcstrmm](#) - dcstrmm - compressed sparse row format matrix-matrix multiply

[dcstrsm](#) - dcstrsm - compressed sparse row format triangular solve

[ddiamm](#) - ddiamm - diagonal format matrix-matrix multiply

[ddiasm](#) - ddiasm - diagonal format triangular solve

[ddisna](#) - ddisna - compute the reciprocal condition numbers for the eigenvectors of a real symmetric or complex Hermitian matrix or for the left or right singular vectors of a general m-by-n matrix

[ddot](#) - ddot - compute the dot product of two vectors x and y.

[ddoti](#) - ddoti - Compute the indexed dot product.

[dellmm](#) - dellmm - Ellpack format matrix-matrix multiply

[dellsm](#) - dellsm - Ellpack format triangular solve

[dezftb](#) - dezftb - computes a periodic sequence from its Fourier coefficients. DEZFTB is a simplified but slower version of DFFTB.

[dezftf](#) - dezftf - computes the Fourier coefficients of a periodic sequence. DEZFTF is a simplified but slower version of DFFTF.

[dezfti](#) - dezfti - initializes the array WSAVE, which is used in both DEZFTF and DEZFTB.

[dffft2b](#) - dffft2b - compute a periodic sequence from its Fourier coefficients. The DFFFT operations are unnormalized, so a call of DFFFT2F followed by a call of DFFFT2B will multiply the input sequence by $M*N$.

[dffft2f](#) - dffft2f - compute the Fourier coefficients of a periodic sequence. The DFFFT operations are unnormalized, so a call of DFFFT2F followed by a call of DFFFT2B will multiply the input sequence by $M*N$.

[dffft2i](#) - dffft2i - initialize the array WSAVE, which is used in both the forward and backward transforms.

[dffft3b](#) - dffft3b - compute a periodic sequence from its Fourier coefficients. The DFFFT operations are unnormalized, so a call of DFFFT3F followed by a call of DFFFT3B will multiply the input sequence by $M*N*K$.

[dffft3f](#) - dffft3f - compute the Fourier coefficients of a real periodic sequence. The DFFFT operations are unnormalized, so a call of DFFFT3F followed by a call of DFFFT3B will multiply the input sequence by $M*N*K$.

[dffft3i](#) - dffft3i - initialize the array WSAVE, which is used in both DFFFT3F and DFFFT3B.

[dffftb](#) - dffftb - compute a periodic sequence from its Fourier coefficients. The DFFFT operations are unnormalized, so a call

of DFFTF followed by a call of DFFTB will multiply the input sequence by N.

[dfft](#) - dfft - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of DFFTF followed by a call of DFFTB will multiply the input sequence by N.

[dfti](#) - dfti - initialize the array WSAVE, which is used in both DFFTF and DFFTB.

[dfftpt](#) - dfftpt - compute the length of the closest fast FFT

[dftz](#) - dftz - initialize the trigonometric weight and factor tables or compute the forward Fast Fourier Transform of a double precision sequence.

[dftz2](#) - dftz2 - initialize the trigonometric weight and factor tables or compute the two-dimensional forward Fast Fourier Transform of a two-dimensional double precision array.

[dftz3](#) - dftz3 - initialize the trigonometric weight and factor tables or compute the three-dimensional forward Fast Fourier Transform of a three-dimensional double complex array.

[dftzm](#) - dftzm - initialize the trigonometric weight and factor tables or compute the one-dimensional forward Fast Fourier Transform of a set of double precision data sequences stored in a two-dimensional array.

[dgbbrd](#) - dgbbrd - reduce a real general m-by-n band matrix A to upper bidiagonal form B by an orthogonal transformation

[dgbcon](#) - dgbcon - estimate the reciprocal of the condition number of a real general band matrix A, in either the 1-norm or the infinity-norm,

[dgbequ](#) - dgbequ - compute row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number

[dgbmv](#) - dgbmv - perform one of the matrix-vector operations $y := \alpha * A * x + \beta * y$ or $y := \alpha * A' * x + \beta * y$

[dgbfrs](#) - dgbfrs - improve the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution

[dgbsv](#) - dgbsv - compute the solution to a real system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices

[dgbsvx](#) - dgbsvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

[dgbtf2](#) - dgbtf2 - compute an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges

[dgbtrf](#) - dgbtrf - compute an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges

[dgbtrs](#) - dgbtrs - solve a system of linear equations $A * X = B$ or $A' * X = B$ with a general band matrix A using the LU

factorization computed by DGBTRF

[dgebak](#) - dgebak - form the right or left eigenvectors of a real general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by DGEBAL

[dgebal](#) - dgebal - balance a general real matrix A

[dgebrd](#) - dgebrd - reduce a general real M-by-N matrix A to upper or lower bidiagonal form B by an orthogonal transformation

[dgecon](#) - dgecon - estimate the reciprocal of the condition number of a general real matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by DGETRF

[dgeequ](#) - dgeequ - compute row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number

[dgees](#) - dgees - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z

[dgeesx](#) - dgeesx - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z

[dgeev](#) - dgeev - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

[dgeevx](#) - dgeevx - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

[dgegs](#) - dgegs - routine is deprecated and has been replaced by routine SGGES

[dgev](#) - dgev - routine is deprecated and has been replaced by routine SGGEV

[dgehrd](#) - dgehrd - reduce a real general matrix A to upper Hessenberg form H by an orthogonal similarity transformation

[dgelqf](#) - dgelqf - compute an LQ factorization of a real M-by-N matrix A

[dgels](#) - dgels - solve overdetermined or underdetermined real linear systems involving an M-by-N matrix A, or its transpose, using a QR or LQ factorization of A

[dgelsd](#) - dgelsd - compute the minimum-norm solution to a real linear least squares problem

[dgelss](#) - dgelss - compute the minimum norm solution to a real linear least squares problem

[dgelsx](#) - dgelsx - routine is deprecated and has been replaced by routine DGELSY

[dgesly](#) - dgesly - compute the minimum-norm solution to a real linear least squares problem

[dgemm](#) - dgemm - perform one of the matrix-matrix operations $C := \alpha * op(A) * op(B) + \beta * C$

[dgemv](#) - dgemv - perform one of the matrix-vector operations $y := \alpha * A * x + \beta * y$ or $y := \alpha * A' * x + \beta * y$

[dgeqlf](#) - dgeqlf - compute a QL factorization of a real M-by-N matrix A

[dgeqp3](#) - dgeqp3 - compute a QR factorization with column pivoting of a matrix A

[dgeqpf](#) - dgeqpf - routine is deprecated and has been replaced by routine DGEQP3

[dgeqrf](#) - dgeqrf - compute a QR factorization of a real M-by-N matrix A

[dger](#) - dger - perform the rank 1 operation $A := \alpha * x * y' + A$

[dgerfs](#) - dgerfs - improve the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution

[dgerqf](#) - dgerqf - compute an RQ factorization of a real M-by-N matrix A

[dgesdd](#) - dgesdd - compute the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and right singular vectors

[dgesv](#) - dgesv - compute the solution to a real system of linear equations $A * X = B$,

[dgesvd](#) - dgesvd - compute the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and/or right singular vectors

[dgesvx](#) - dgesvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$,

[dgetf2](#) - dgetf2 - compute an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges

[dgetrf](#) - dgetrf - compute an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges

[dgetri](#) - dgetri - compute the inverse of a matrix using the LU factorization computed by DGETRF

[dgetrs](#) - dgetrs - solve a system of linear equations $A * X = B$ or $A' * X = B$ with a general N-by-N matrix A using the LU factorization computed by DGETRF

[dggbak](#) - dggbak - form the right or left eigenvectors of a real generalized eigenvalue problem $A * x = \lambda * B * x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by DGGBAL

[dggbal](#) - dggbal - balance a pair of general real matrices (A,B)

[dgges](#) - dgges - compute for a pair of N-by-N real nonsymmetric matrices (A,B),

[dggesx](#) - dggesx - compute for a pair of N-by-N real nonsymmetric matrices (A,B), the generalized eigenvalues, the real Schur form (S,T), and,

[dggev](#) - dggev - compute for a pair of N-by-N real nonsymmetric matrices (A,B)

[dggevz](#) - dggez - compute for a pair of N-by-N real nonsymmetric matrices (A,B)

[dggglm](#) - dggglm - solve a general Gauss-Markov linear model (GLM) problem

[dgghrd](#) - dgghrd - reduce a pair of real matrices (A,B) to generalized upper Hessenberg form using orthogonal transformations, where A is a general matrix and B is upper triangular

[dggls](#) - dggls - solve the linear equality-constrained least squares (LSE) problem

[dggqr](#) - dggqr - compute a generalized QR factorization of an N-by-M matrix A and an N-by-P matrix B.

[dggqrq](#) - dggqrq - compute a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B

[dggsvd](#) - dggsvd - compute the generalized singular value decomposition (GSVD) of an M-by-N real matrix A and P-by-N real matrix B

[dggsvp](#) - dggsvp - compute orthogonal matrices U, V and Q such that $N \times K \times L \times K \times L \times U^T \times A \times Q = K \times (0 \ A_{12} \ A_{13})$ if $M \times K \times L \gg 0$

[dgssco](#) - dgssco - General sparse solver condition number estimate.

[dgssda](#) - dgssda - Deallocate working storage for the general sparse solver.

[dgssfa](#) - dgssfa - General sparse solver numeric factorization.

[dgssfs](#) - dgssfs - General sparse solver one call interface.

[dgssin](#) - dgssin - Initialize the general sparse solver.

[dgssor](#) - dgssor - General sparse solver ordering and symbolic factorization.

[dgssps](#) - dgssps - Print general sparse solver statics.

[dgssrp](#) - dgssrp - Return permutation used by the general sparse solver.

[dgsssl](#) - dgsssl - Solve routine for the general sparse solver.

[dgssuo](#) - dgssuo - User supplied permutation for ordering used in the general sparse solver.

[dgtcon](#) - dgtcon - estimate the reciprocal of the condition number of a real tridiagonal matrix A using the LU factorization as computed by DGTRF

[dgthr](#) - dgthr - Gathers specified elements from y into x.

[dgthrz](#) - dgthrz - Gather and zero.

[dgtrfs](#) - dgtrfs - improve the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution

[dgtsv](#) - dgtsv - solve the equation $A * X = B$,

[dgtsvx](#) - dgtsvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$ or $A ** T * X = B$,

[dgtrf](#) - dgtrf - compute an LU factorization of a real tridiagonal matrix A using elimination with partial pivoting and row interchanges

[dgtrs](#) - dgtrs - solve one of the systems of equations $A * X = B$ or $A ** X = B$,

[dhgeqz](#) - dhgeqz - implement a single-/double-shift version of the QZ method for finding the generalized eigenvalues $w(j) = (\text{ALPHAR}(j) + i * \text{ALPHAI}(j)) / \text{BETAR}(j)$ of the equation $\det(A - w(i) B) = 0$ In addition, the pair A,B may be reduced to generalized Schur form

[dhsein](#) - dhsein - use inverse iteration to find specified right and/or left eigenvectors of a real upper Hessenberg matrix H

[dhseqr](#) - dhseqr - compute the eigenvalues of a real upper Hessenberg matrix H and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z ** T$, where T is an upper quasi-triangular matrix (the Schur form), and Z is the orthogonal matrix of Schur vectors

[djadmm](#) - djadmm - Jagged diagonal matrix-matrix multiply (modified Ellpack)

[djadrp](#) - djadrp - right permutation of a jagged diagonal matrix

[djadsm](#) - djadsm - Jagged-diagonal format triangular solve

[dlagtf](#) - dlagtf - factorize the matrix $(T - \text{lambda} * I)$, where T is an n by n tridiagonal matrix and lambda is a scalar, as $T - \text{lambda} * I = \text{PLU}$

[dlamrg](#) - dlamrg - will create a permutation list which will merge the elements of A (which is composed of two

independently sorted sets) into a single set which is sorted in ascending order

[dlarz](#) - dlarz - applies a real elementary reflector H to a real M-by-N matrix C, from either the left or the right

[dlarzb](#) - dlarzb - applies a real block reflector H or its transpose H^{**T} to a real distributed M-by-N C from the left or the right

[dlarzt](#) - dlarzt - form the triangular factor T of a real block reflector H of order $> n$, which is defined as a product of k elementary reflectors

[dlasrt](#) - dlasrt - the numbers in D in increasing order (if ID = 'I') or in decreasing order (if ID = 'D')

[dlatzm](#) - dlatzm - routine is deprecated and has been replaced by routine SORMRZ

[dnrm2](#) - dnm2 - Return the Euclidian norm of a vector.

[dopgtr](#) - dopgtr - generate a real orthogonal matrix Q which is defined as the product of n-1 elementary reflectors H(i) of order n, as returned by SSPTRD using packed storage

[dopmtr](#) - dopmtr - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[dorg2l](#) - dorg2l - generate an m by n real matrix Q with orthonormal columns,

[dorg2r](#) - dorg2r - generate an m by n real matrix Q with orthonormal columns,

[dorgbr](#) - dorgbr - generate one of the real orthogonal matrices Q or P^{**T} determined by SGEBRD when reducing a real matrix A to bidiagonal form

[dorghr](#) - dorghr - generate a real orthogonal matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N, as returned by SGEHRD

[dorgl2](#) - dorgl2 - generate an m by n real matrix Q with orthonormal rows,

[dorglq](#) - dorglq - generate an M-by-N real matrix Q with orthonormal rows,

[dorgql](#) - dorgql - generate an M-by-N real matrix Q with orthonormal columns,

[dorgqr](#) - dorgqr - generate an M-by-N real matrix Q with orthonormal columns,

[dorg2](#) - dorg2 - generate an m by n real matrix Q with orthonormal rows,

[dorgq](#) - dorgq - generate an M-by-N real matrix Q with orthonormal rows,

[dorgtr](#) - dorgtr - generate a real orthogonal matrix Q which is defined as the product of n-1 elementary reflectors of order N, as returned by SSYTRD

[dormbr](#) - dormbr - VECT = 'Q', DORMBR overwrites the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[dormhr](#) - dormhr - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[dormlq](#) - dormlq - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[dormql](#) - dormql - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[dormqr](#) - dormqr - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[dormrq](#) - dormrq - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[dormrz](#) - dormrz - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[dormtr](#) - dormtr - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[dpbcon](#) - dpbcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite band matrix using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by DPBTRF

[dpbequ](#) - dpbequ - compute row and column scalings intended to equilibrate a symmetric positive definite band matrix A and reduce its condition number (with respect to the two-norm)

[dpbrfs](#) - dpbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and banded, and provides error bounds and backward error estimates for the solution

[dpbstf](#) - dpbstf - compute a split Cholesky factorization of a real symmetric positive definite band matrix A

[dpbsv](#) - dpbsv - compute the solution to a real system of linear equations $A * X = B$,

[dpbsvx](#) - dpbsvx - use the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ to compute the solution to a real system of linear equations $A * X = B$,

[dpbtf2](#) - dpbtf2 - compute the Cholesky factorization of a real symmetric positive definite band matrix A

[dpbtrf](#) - dpbtrf - compute the Cholesky factorization of a real symmetric positive definite band matrix A

[dpbtrs](#) - dpbtrs - solve a system of linear equations $A * X = B$ with a symmetric positive definite band matrix A using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by DPBTRF

[dpocon](#) - dpocon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite

matrix using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by DPOTRF

[dpoequ](#) - dpoequ - compute row and column scalings intended to equilibrate a symmetric positive definite matrix A and reduce its condition number (with respect to the two-norm)

[dporfs](#) - dporfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite,

[dposv](#) - dposv - compute the solution to a real system of linear equations $A * X = B$,

[dposvx](#) - dposvx - use the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ to compute the solution to a real system of linear equations $A * X = B$,

[dpotf2](#) - dpotf2 - compute the Cholesky factorization of a real symmetric positive definite matrix A

[dpotrf](#) - dpotrf - compute the Cholesky factorization of a real symmetric positive definite matrix A

[dpotri](#) - dpotri - compute the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by DPOTRF

[dpotrs](#) - dpotrs - solve a system of linear equations $A*X = B$ with a symmetric positive definite matrix A using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by DPOTRF

[dppcon](#) - dppcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite packed matrix using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by DPPTRF

[dppequ](#) - dppequ - compute row and column scalings intended to equilibrate a symmetric positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm)

[dpprfs](#) - dpprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and packed, and provides error bounds and backward error estimates for the solution

[dppsv](#) - dppsv - compute the solution to a real system of linear equations $A * X = B$,

[dppsvx](#) - dppsvx - use the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ to compute the solution to a real system of linear equations $A * X = B$,

[dpptrf](#) - dpptrf - compute the Cholesky factorization of a real symmetric positive definite matrix A stored in packed format

[dpptri](#) - dpptri - compute the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by DPPTRF

[dpptrs](#) - dpptrs - solve a system of linear equations $A*X = B$ with a symmetric positive definite matrix A in packed storage using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by DPPTRF

[dptcon](#) - dptcon - compute the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite tridiagonal matrix using the factorization $A = L^*D^*L^{**T}$ or $A = U^{**T}D^*U$ computed by DPTTRF

[dpteqr](#) - dpteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using DPTTRF, and then calling DBDSQR to compute the singular values of the bidiagonal factor

[dptrfs](#) - dptrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution

[dptsv](#) - dptsv - compute the solution to a real system of linear equations $A^*X = B$, where A is an N-by-N symmetric positive definite tridiagonal matrix, and X and B are N-by-NRHS matrices.

[dptsvx](#) - dptsvx - use the factorization $A = L^*D^*L^{**T}$ to compute the solution to a real system of linear equations $A^*X = B$, where A is an N-by-N symmetric positive definite tridiagonal matrix and X and B are N-by-NRHS matrices

[dpttrf](#) - dpttrf - compute the L^*D^*L' factorization of a real symmetric positive definite tridiagonal matrix A

[dpttrs](#) - dpttrs - solve a tridiagonal system of the form $A^*X = B$ using the L^*D^*L' factorization of A computed by DPTTRF

[dptts2](#) - dptts2 - solve a tridiagonal system of the form $A^*X = B$ using the L^*D^*L' factorization of A computed by DPTTRF

[dqdota](#) - dqdota - compute a double precision constant plus an extended precision constant plus the extended precision dot product of two double precision vectors x and y.

[dqdoti](#) - dqdoti - compute a constant plus the extended precision dot product of two double precision vectors x and y.

[drot](#) - drot - Apply a Given's rotation constructed by SROTG.

[drotg](#) - drotg - Construct a Given's plane rotation

[droti](#) - droti - Apply an indexed Givens rotation.

[drotm](#) - drotm - Apply a Gentleman's modified Given's rotation constructed by SROTMG.

[drotmg](#) - drotmg - Construct a Gentleman's modified Given's plane rotation

[dsbev](#) - dsbev - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

[dsbevd](#) - dsbevd - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

[dsbevz](#) - dsbevz - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

[dsbgst](#) - dsbgst - reduce a real symmetric-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$,

[dsbgv](#) - dsbgv - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x = \lambda*B*x$

[dsbgvd](#) - dsbgvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x = \lambda*B*x$

[dsbgvx](#) - dsbgvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x = \lambda*B*x$

[dsbmv](#) - dsbmv - perform the matrix-vector operation $y := \alpha*A*x + \beta*y$

[dsbtrd](#) - dsbtrd - reduce a real symmetric band matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation

[dscal](#) - dscal - Compute $y := \alpha * y$

[dsctr](#) - dsctr - Scatters elements from x into y.

[dsdot](#) - dsdot - compute the double precision dot product of two single precision vectors x and y.

[dsecnd](#) - dsecnd - return the user time for a process in seconds

[dsinqb](#) - dsinqb - synthesize a Fourier sequence from its representation in terms of a sine series with odd wave numbers. The SING operations are unnormalized inverses of themselves, so a call to SINGF followed by a call to SINGB will multiply the input sequence by $4 * N$.

[dsinqf](#) - dsinqf - compute the Fourier coefficients in a sine series representation with only odd wave numbers. The SING operations are unnormalized inverses of themselves, so a call to SINGF followed by a call to SINGB will multiply the input sequence by $4 * N$.

[dsinqi](#) - dsinqi - initialize the array xWSAVE, which is used in both SINGF and SINGB.

[dsint](#) - dsint - compute the discrete Fourier sine transform of an odd sequence. The SINT transforms are unnormalized inverses of themselves, so a call of SINT followed by another call of SINT will multiply the input sequence by $2 * (N+1)$.

[dsinti](#) - dsinti - initialize the array WSAVE, which is used in subroutine SINT.

[dskymm](#) - dskymm - Skyline format matrix-matrix multiply

[dskysm](#) - dskysm - Skyline format triangular solve

[dspcon](#) - dspcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric packed matrix A

using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by DSPTRF

[dspev](#) - dspev - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

[dspevd](#) - dspevd - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

[dspevx](#) - dspevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

[dspgst](#) - dspgst - reduce a real symmetric-definite generalized eigenproblem to standard form, using packed storage

[dspgv](#) - dspgv - compute all the eigenvalues and, optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A^*x=(\lambda)^*B^*x$, $A^*Bx=(\lambda)^*x$, or $B^*A^*x=(\lambda)^*x$

[dspgvd](#) - dspgvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A^*x=(\lambda)^*B^*x$, $A^*Bx=(\lambda)^*x$, or $B^*A^*x=(\lambda)^*x$

[dspgvx](#) - dspgvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A^*x=(\lambda)^*B^*x$, $A^*Bx=(\lambda)^*x$, or $B^*A^*x=(\lambda)^*x$

[dspmv](#) - dspmv - perform the matrix-vector operation $y := \alpha^*A^*x + \beta^*y$

[dspr](#) - dspr - perform the symmetric rank 1 operation $A := \alpha^*x^*x' + A$

[dspr2](#) - dspr2 - perform the symmetric rank 2 operation $A := \alpha^*x^*y' + \alpha^*y^*x' + A$

[dsprfs](#) - dsprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution

[dspsv](#) - dspsv - compute the solution to a real system of linear equations $A^* X = B$,

[dspsvx](#) - dspsvx - use the diagonal pivoting factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ to compute the solution to a real system of linear equations $A^* X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices

[dsptrd](#) - dsptrd - reduce a real symmetric matrix A stored in packed form to symmetric tridiagonal form T by an orthogonal similarity transformation

[dsptrf](#) - dsptrf - compute the factorization of a real symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method

[dsptri](#) - dsptri - compute the inverse of a real symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by DSPTRF

[dsptrs](#) - dsptrs - solve a system of linear equations $A^*X = B$ with a real symmetric matrix A stored in packed format using

the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by DSPTRF

[dstebz](#) - dstebz - compute the eigenvalues of a symmetric tridiagonal matrix T

[dstedc](#) - dstedc - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method

[dstegr](#) - dstegr - (a) Compute $T\text{-sigma}_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation

[dstein](#) - dstein - compute the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration

[dsteqr](#) - dsteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method

[dsterf](#) - dsterf - compute all eigenvalues of a symmetric tridiagonal matrix using the Pal-Walker-Kahan variant of the QL or QR algorithm

[dstev](#) - dstev - compute all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A

[dstevd](#) - dstevd - compute all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix

[dstevr](#) - dstevr - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T

[dstevx](#) - dstevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A

[dstsv](#) - dstsv - compute the solution to a system of linear equations $A * X = B$ where A is a symmetric tridiagonal matrix

[dsttrf](#) - dsttrf - compute the factorization of a symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method

[dsttrs](#) - dsttrs - computes the solution to a real system of linear equations $A * X = B$

[dswap](#) - dswap - Exchange vectors x and y.

[dsycon](#) - dsycon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric matrix A using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by DSYTRF

[dsyev](#) - dsyev - compute all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

[dsyevd](#) - dsyevd - compute all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

[dsyevr](#) - dsyevr - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T

[dsyevx](#) - dsyevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

[dsygs2](#) - dsygs2 - reduce a real symmetric-definite generalized eigenproblem to standard form

[dsygst](#) - dsygst - reduce a real symmetric-definite generalized eigenproblem to standard form

[dsygv](#) - dsygv - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

[dsygvd](#) - dsygvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

[dsygvx](#) - dsygvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

[dsymm](#) - dsymm - perform one of the matrix-matrix operations $C := \alpha*A*B + \beta*C$ or $C := \alpha*B*A + \beta*C$

[dsymv](#) - dsymv - perform the matrix-vector operation $y := \alpha*A*x + \beta*y$

[dsyr](#) - dsyr - perform the symmetric rank 1 operation $A := \alpha*x*x' + A$

[dsyr2](#) - dsyr2 - perform the symmetric rank 2 operation $A := \alpha*x*y' + \alpha*y*x' + A$

[dsyr2k](#) - dsyr2k - perform one of the symmetric rank 2k operations $C := \alpha*A*B' + \alpha*B*A' + \beta*C$ or $C := \alpha*A'*B + \alpha*B'*A + \beta*C$

[dsyrf](#) - dsyrf - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution

[dsyrk](#) - dsyrk - perform one of the symmetric rank k operations $C := \alpha*A*A' + \beta*C$ or $C := \alpha*A'*A + \beta*C$

[dsysv](#) - dsysv - compute the solution to a real system of linear equations $A * X = B$,

[dsysvx](#) - dsysvx - use the diagonal pivoting factorization to compute the solution to a real system of linear equations $A * X = B$,

[dsytd2](#) - dsytd2 - reduce a real symmetric matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation

[dsytf2](#) - dsytf2 - compute the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

[dsytrd](#) - dsytrd - reduce a real symmetric matrix A to real symmetric tridiagonal form T by an orthogonal similarity transformation

[dsytrf](#) - dsytrf - compute the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

[dsytri](#) - dsytri - compute the inverse of a real symmetric indefinite matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by DSYTRF

[dsytrs](#) - dsytrs - solve a system of linear equations $A*X = B$ with a real symmetric matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by DSYTRF

[dtbcon](#) - dtbcon - estimate the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm

[dtbmv](#) - dtbmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

[dtbrfs](#) - dtbrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix

[dtbsv](#) - dtbsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

[dtbtrs](#) - dtbtrs - solve a triangular system of the form $A * X = B$ or $A**T * X = B$,

[dtgevc](#) - dtgevc - compute some or all of the right and/or left generalized eigenvectors of a pair of real upper triangular matrices (A,B)

[dtgexc](#) - dtgexc - reorder the generalized real Schur decomposition of a real matrix pair (A,B) using an orthogonal equivalence transformation $(A, B) = Q * (A, B) * Z'$,

[dtgsen](#) - dtgsen - reorder the generalized real Schur decomposition of a real matrix pair (A, B) (in terms of an orthonormal equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix A and the upper triangular B

[dtgsja](#) - dtgsja - compute the generalized singular value decomposition (GSVD) of two real upper triangular (or trapezoidal) matrices A and B

[dtgsna](#) - dtgsna - estimate reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B) in generalized real Schur canonical form (or of any matrix pair $(Q*A*Z', Q*B*Z')$ with orthogonal matrices Q and Z, where Z' denotes the transpose of Z

[dtgsyl](#) - dtgsyl - solve the generalized Sylvester equation

[dtpcon](#) - dtpcon - estimate the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm

[dtpmv](#) - dtpmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

[dtpdfs](#) - dtpdfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a

triangular packed coefficient matrix

[dtpsv](#) - dtpsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

[dtptri](#) - dtptri - compute the inverse of a real upper or lower triangular matrix A stored in packed format

[dtptrs](#) - dtptrs - solve a triangular system of the form $A * X = B$ or $A^{**T} * X = B$,

[dtrans](#) - dtrans - transpose and scale source matrix

[dtrcon](#) - dtrcon - estimate the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm

[dtrevc](#) - dtrevc - compute some or all of the right and/or left eigenvectors of a real upper quasi-triangular matrix T

[dtrexc](#) - dtrexc - reorder the real Schur factorization of a real matrix $A = Q*T*Q^{**T}$, so that the diagonal block of T with row index IFST is moved to row ILST

[dtrmm](#) - dtrmm - perform one of the matrix-matrix operations $B := \alpha * \text{op}(A) * B$, or $B := \alpha * B * \text{op}(A)$

[dtrmv](#) - dtrmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

[dtrrfs](#) - dtrrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix

[dtrsen](#) - dtrsen - reorder the real Schur factorization of a real matrix $A = Q*T*Q^{**T}$, so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix T,

[dtrsm](#) - dtrsm - solve one of the matrix equations $\text{op}(A)*X = \alpha*B$, or $X*\text{op}(A) = \alpha*B$

[dtrsna](#) - dtrsna - estimate reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix T (or of any matrix $Q*T*Q^{**T}$ with Q orthogonal)

[dtrsv](#) - dtrsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

[dtrsyl](#) - dtrsyl - solve the real Sylvester matrix equation

[dtrti2](#) - dtrti2 - compute the inverse of a real upper or lower triangular matrix

[dtrtri](#) - dtrtri - compute the inverse of a real upper or lower triangular matrix A

[dtrtrs](#) - dtrtrs - solve a triangular system of the form $A * X = B$ or $A^{**T} * X = B$,

[dtzrqf](#) - dtzrqf - routine is deprecated and has been replaced by routine STZRZF

[dtzrzf](#) - dtzrzf - reduce the M-by-N ($M \leq N$) real upper trapezoidal matrix A to upper triangular form by means of orthogonal transformations

[dvbrmm](#) - dvbrmm - variable block sparse row format matrix-matrix multiply

[dvbrsm](#) - dvbrsm - variable block sparse row format triangular solve

[dwiener](#) - dwiener - perform Wiener deconvolution of two signals

[dzasum](#) - dzasum - Return the sum of the absolute values of a vector x.

[dznrm2](#) - dznrm2 - Return the Euclidian norm of a vector.

[ezfftb](#) - ezfftb - computes a periodic sequence from its Fourier coefficients. EZFFTB is a simplified but slower version of RFFTB.

[ezfftf](#) - ezfftf - computes the Fourier coefficients of a periodic sequence. EZFFTF is a simplified but slower version of RFFTF.

[ezffti](#) - ezffti - initializes the array WSAVE, which is used in both EZFFTF and EZFFTB.

[fft](#) - fft - Fast Fourier transform subroutines

[icamax](#) - icamax - return the index of the element with largest absolute value.

[idamax](#) - idamax - return the index of the element with largest absolute value.

[ilaenv](#) - ilaenv - The name of the calling subroutine, in either upper case or lower case.

[isamax](#) - isamax - return the index of the element with largest absolute value.

[izamax](#) - izamax - return the index of the element with largest absolute value.

[lsame](#) - lsame - returns .TRUE. if CA is the same letter as CB regardless of case

[rfft2b](#) - rfft2b - compute a periodic sequence from its Fourier coefficients. The RFFT operations are unnormalized, so a call of RFFT2F followed by a call of RFFT2B will multiply the input sequence by $M \cdot N$.

[rfft2f](#) - rfft2f - compute the Fourier coefficients of a periodic sequence. The RFFT operations are unnormalized, so a call of RFFT2F followed by a call of RFFT2B will multiply the input sequence by $M \cdot N$.

[rfft2i](#) - rfft2i - initialize the array WSAVE, which is used in both the forward and backward transforms.

[rfft3b](#) - rfft3b - compute a periodic sequence from its Fourier coefficients. The RFFT operations are unnormalized, so a call of RFFT3F followed by a call of RFFT3B will multiply the input sequence by $M*N*K$.

[rfft3f](#) - rfft3f - compute the Fourier coefficients of a real periodic sequence. The RFFT operations are unnormalized, so a call of RFFT3F followed by a call of RFFT3B will multiply the input sequence by $M*N*K$.

[rfft3i](#) - rfft3i - initialize the array WSAVE, which is used in both RFFT3F and RFFT3B.

[rfftb](#) - rfftb - compute a periodic sequence from its Fourier coefficients. The RFFT operations are unnormalized, so a call of RFFTF followed by a call of RFFTB will multiply the input sequence by N .

[rfftf](#) - rfftf - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of RFFTF followed by a call of RFFTB will multiply the input sequence by N .

[rffti](#) - rffti - initialize the array WSAVE, which is used in both RFFTF and RFFTB.

[rfftopt](#) - rfftopt - compute the length of the closest fast FFT

[sasum](#) - sasum - Return the sum of the absolute values of a vector x .

[saxpy](#) - saxpy - compute $y := \alpha * x + y$

[saxpyi](#) - saxpyi - Compute $y := \alpha * x + y$

[sbcomm](#) - sbcomm - block coordinate matrix-matrix multiply

[sbdimm](#) - sbdimm - block diagonal format matrix-matrix multiply

[sbdism](#) - sbdism - block diagonal format triangular solve

[sbdsdc](#) - sbdsdc - compute the singular value decomposition (SVD) of a real N -by- N (upper or lower) bidiagonal matrix B

[sbdsqr](#) - sbdsqr - compute the singular value decomposition (SVD) of a real N -by- N (upper or lower) bidiagonal matrix B .

[sbelmm](#) - sbelmm - block Ellpack format matrix-matrix multiply

[sbelsm](#) - sbelsm - block Ellpack format triangular solve

[sbscmm](#) - sbscmm - block sparse column matrix-matrix multiply

[sbscsm](#) - sbscsm - block sparse column format triangular solve

[sbsrmm](#) - sbsrmm - block sparse row format matrix-matrix multiply

[sbsrsm](#) - sbsrsm - block sparse row format triangular solve

[scasum](#) - scasum - Return the sum of the absolute values of a vector x.

[scnorm2](#) - scnorm2 - Return the Euclidian norm of a vector.

[scnvcor](#) - scnvcor - compute the convolution or correlation of real vectors

[scnvcor2](#) - scnvcor2 - compute the convolution or correlation of real matrices

[scoomm](#) - scoomm - coordinate matrix-matrix multiply

[scopy](#) - scopy - Copy x to y

[scscmm](#) - scscmm - compressed sparse column format matrix-matrix multiply

[scscsm](#) - scscsm - compressed sparse column format triangular solve

[scsrmm](#) - scsrmm - compressed sparse row format matrix-matrix multiply

[scsrsm](#) - scsrsm - compressed sparse row format triangular solve

[sdiamm](#) - sdiamm - diagonal format matrix-matrix multiply

[sdiasm](#) - sdiasm - diagonal format triangular solve

[sdisna](#) - sdisna - compute the reciprocal condition numbers for the eigenvectors of a real symmetric or complex Hermitian matrix or for the left or right singular vectors of a general m-by-n matrix

[sdot](#) - sdot - compute the dot product of two vectors x and y.

[sdoti](#) - sdoti - Compute the indexed dot product.

[sdsdot](#) - sdsdot - compute a constant plus the double precision dot product of two single precision vectors x and y

[second](#) - second - return the user time for a process in seconds

[sellmm](#) - sellmm - Ellpack format matrix-matrix multiply

[sellsm](#) - sellsm - Ellpack format triangular solve

[sfftc](#) - sfftc - initialize the trigonometric weight and factor tables or compute the forward Fast Fourier Transform of a real sequence.

[sfftc2](#) - sfftc2 - initialize the trigonometric weight and factor tables or compute the two-dimensional forward Fast Fourier Transform of a two-dimensional real array.

[sfftc3](#) - sfftc3 - initialize the trigonometric weight and factor tables or compute the three-dimensional forward Fast Fourier Transform of a three-dimensional complex array.

[sfftcM](#) - sfftcM - initialize the trigonometric weight and factor tables or compute the one-dimensional forward Fast Fourier Transform of a set of real data sequences stored in a two-dimensional array.

[sgbbrd](#) - sgbbrd - reduce a real general m-by-n band matrix A to upper bidiagonal form B by an orthogonal transformation

[sgbcon](#) - sgbcon - estimate the reciprocal of the condition number of a real general band matrix A, in either the 1-norm or the infinity-norm,

[sgbequ](#) - sgbequ - compute row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number

[sgbmV](#) - sgbmv - perform one of the matrix-vector operations $y := \alpha * A * x + \beta * y$ or $y := \alpha * A' * x + \beta * y$

[sgbrfs](#) - sgbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution

[sgbsv](#) - sgbsv - compute the solution to a real system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices

[sgbsvx](#) - sgbsvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

[sgbtf2](#) - sgbtf2 - compute an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges

[sgbtrf](#) - sgbtrf - compute an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges

[sgbtrs](#) - sgbtrs - solve a system of linear equations $A * X = B$ or $A' * X = B$ with a general band matrix A using the LU factorization computed by SGBTRF

[sgebak](#) - sgebak - form the right or left eigenvectors of a real general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by SGEBAL

[sgebal](#) - sgebal - balance a general real matrix A

[sgebrd](#) - sgebrd - reduce a general real M-by-N matrix A to upper or lower bidiagonal form B by an orthogonal transformation

[sgecon](#) - sgecon - estimate the reciprocal of the condition number of a general real matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by SGETRF

[sgeequ](#) - sgeequ - compute row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number

[sgees](#) - sgees - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z

[sgeesx](#) - sgeesx - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z

[sgeev](#) - sgeev - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

[sgeevx](#) - sgeevx - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

[sgegs](#) - sgegs - routine is deprecated and has been replaced by routine SGGES

[sgegv](#) - sgegv - routine is deprecated and has been replaced by routine SGGEV

[sgehrd](#) - sgehrd - reduce a real general matrix A to upper Hessenberg form H by an orthogonal similarity transformation

[sgelqf](#) - sgelqf - compute an LQ factorization of a real M-by-N matrix A

[sgels](#) - sgels - solve overdetermined or underdetermined real linear systems involving an M-by-N matrix A, or its transpose, using a QR or LQ factorization of A

[sgelsd](#) - sgelsd - compute the minimum-norm solution to a real linear least squares problem

[sgelss](#) - sgelss - compute the minimum norm solution to a real linear least squares problem

[sgelsx](#) - sgelsx - routine is deprecated and has been replaced by routine SGELSY

[sgelsy](#) - sgelsy - compute the minimum-norm solution to a real linear least squares problem

[sgemm](#) - sgemm - perform one of the matrix-matrix operations $C := \alpha \text{op}(A) \text{op}(B) + \beta C$

[sgemv](#) - sgemv - perform one of the matrix-vector operations $y := \alpha A x + \beta y$ or $y := \alpha A' x + \beta y$

[sgeqlf](#) - sgeqlf - compute a QL factorization of a real M-by-N matrix A

[sgeqp3](#) - sgeqp3 - compute a QR factorization with column pivoting of a matrix A

[sgeqpf](#) - sgeqpf - routine is deprecated and has been replaced by routine SGEQP3

[sgeqrf](#) - sgeqrf - compute a QR factorization of a real M-by-N matrix A

[sger](#) - sger - perform the rank 1 operation $A := \alpha * x * y' + A$

[sgerfs](#) - sgerfs - improve the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution

[sgerqf](#) - sgerqf - compute an RQ factorization of a real M-by-N matrix A

[sgesdd](#) - sgesdd - compute the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and right singular vectors

[sgesv](#) - sgesv - compute the solution to a real system of linear equations $A * X = B$,

[sgesvd](#) - sgesvd - compute the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and/or right singular vectors

[sgesvx](#) - sgesvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$,

[sgetf2](#) - sgetf2 - compute an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges

[sgetrf](#) - sgetrf - compute an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges

[sgetri](#) - sgetri - compute the inverse of a matrix using the LU factorization computed by SGETRF

[sgetrs](#) - sgetrs - solve a system of linear equations $A * X = B$ or $A' * X = B$ with a general N-by-N matrix A using the LU factorization computed by SGETRF

[sggbak](#) - sggbak - form the right or left eigenvectors of a real generalized eigenvalue problem $A * x = \lambda * B * x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by SGGBAL

[sggbal](#) - sggbal - balance a pair of general real matrices (A,B)

[sgges](#) - sgges - compute for a pair of N-by-N real nonsymmetric matrices (A,B),

[sggesx](#) - sggesx - compute for a pair of N-by-N real nonsymmetric matrices (A,B), the generalized eigenvalues, the real Schur form (S,T), and,

[sggev](#) - sggev - compute for a pair of N-by-N real nonsymmetric matrices (A,B)

[sggevz](#) - sggez - compute for a pair of N-by-N real nonsymmetric matrices (A,B)

[sgglm](#) - sgglm - solve a general Gauss-Markov linear model (GLM) problem

[sgghrd](#) - sgghrd - reduce a pair of real matrices (A,B) to generalized upper Hessenberg form using orthogonal transformations, where A is a general matrix and B is upper triangular

[sgglse](#) - sgglse - solve the linear equality-constrained least squares (LSE) problem

[sggqrf](#) - sgqrf - compute a generalized QR factorization of an N-by-M matrix A and an N-by-P matrix B.

[sggrqf](#) - sggrqf - compute a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B

[sggsvd](#) - sggsvd - compute the generalized singular value decomposition (GSVD) of an M-by-N real matrix A and P-by-N real matrix B

[sggsvp](#) - sggsvp - compute orthogonal matrices U, V and Q such that $N-K-L \times K \times L \times U^* \times A^* \times Q = K \times (0 \ A12 \ A13)$ if $M-K-L \geq 0$

[sgssco](#) - sgssco - General sparse solver condition number estimate.

[sgssda](#) - sgssda - Deallocate working storage for the general sparse solver.

[sgssfa](#) - sgssfa - General sparse solver numeric factorization.

[sgssfs](#) - sgssfs - General sparse solver one call interface.

[sgssin](#) - sgssin - Initialize the general sparse solver.

[sgssor](#) - sgssor - General sparse solver ordering and symbolic factorization.

[sgssps](#) - sgssps - Print general sparse solver statics.

[sgssrp](#) - sgssrp - Return permutation used by the general sparse solver.

[sgsssl](#) - sgsssl - Solve routine for the general sparse solver.

[sgssuo](#) - sgssuo - User supplied permutation for ordering used in the general sparse solver.

[sgtcon](#) - sgtcon - estimate the reciprocal of the condition number of a real tridiagonal matrix A using the LU factorization as computed by SGTRF

[sgthr](#) - sgthr - Gathers specified elements from y into x.

[sgthrz](#) - sgthrz - Gather and zero.

[sgtrfs](#) - sgtrfs - improve the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution

[sgtsv](#) - sgtsv - solve the equation $A * X = B$,

[sgtsvx](#) - sgtsvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$ or $A ** T * X = B$,

[sgttrf](#) - sgttrf - compute an LU factorization of a real tridiagonal matrix A using elimination with partial pivoting and row interchanges

[sgttrs](#) - sgttrs - solve one of the systems of equations $A * X = B$ or $A' * X = B$,

[shgeqz](#) - shgeqz - implement a single-/double-shift version of the QZ method for finding the generalized eigenvalues $w(j) = (\text{ALPHAR}(j) + i * \text{ALPHAI}(j)) / \text{BETAR}(j)$ of the equation $\det(A - w(i) B) = 0$ In addition, the pair A,B may be reduced to generalized Schur form

[shsein](#) - shsein - use inverse iteration to find specified right and/or left eigenvectors of a real upper Hessenberg matrix H

[shseqr](#) - shseqr - compute the eigenvalues of a real upper Hessenberg matrix H and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z ** T$, where T is an upper quasi-triangular matrix (the Schur form), and Z is the orthogonal matrix of Schur vectors

[sinqb](#) - sinqb - synthesize a Fourier sequence from its representation in terms of a sine series with odd wave numbers. The SING operations are unnormalized inverses of themselves, so a call to SINGF followed by a call to SINGB will multiply the input sequence by $4 * N$.

[sinqf](#) - sinqf - compute the Fourier coefficients in a sine series representation with only odd wave numbers. The SING operations are unnormalized inverses of themselves, so a call to SINGF followed by a call to SINGB will multiply the input sequence by $4 * N$.

[sinqi](#) - sinqi - initialize the array xWSAVE, which is used in both SINGF and SINGB.

[sint](#) - sint - compute the discrete Fourier sine transform of an odd sequence. The SINT transforms are unnormalized inverses of themselves, so a call of SINT followed by another call of SINT will multiply the input sequence by $2 * (N+1)$.

[sinti](#) - sinti - initialize the array WSAVE, which is used in subroutine SINT.

[sjadmm](#) - sjadmm - Jagged diagonal matrix-matrix multiply (modified Ellpack)

[sjadrp](#) - sjadrp - right permutation of a jagged diagonal matrix

[sjadsm](#) - sjadsm - Jagged-diagonal format triangular solve

[slagtf](#) - slagtf - factorize the matrix $(T-\lambda I)$, where T is an n by n tridiagonal matrix and λ is a scalar, as $T-\lambda I = PLU$

[slamrg](#) - slamrg - will create a permutation list which will merge the elements of A (which is composed of two independently sorted sets) into a single set which is sorted in ascending order

[slarz](#) - slarz - applies a real elementary reflector H to a real M -by- N matrix C , from either the left or the right

[slarzb](#) - slarzb - applies a real block reflector H or its transpose H^*T to a real distributed M -by- N C from the left or the right

[slarzt](#) - slarzt - form the triangular factor T of a real block reflector H of order $> n$, which is defined as a product of k elementary reflectors

[slasrt](#) - slasrt - the numbers in D in increasing order (if $ID = 'I'$) or in decreasing order (if $ID = 'D'$)

[slatzm](#) - slatzm - routine is deprecated and has been replaced by routine SORMRZ

[snrm2](#) - snrm2 - Return the Euclidian norm of a vector.

[sopgtr](#) - sopgtr - generate a real orthogonal matrix Q which is defined as the product of $n-1$ elementary reflectors $H(i)$ of order n , as returned by SSPTRD using packed storage

[sopmtr](#) - sopmtr - overwrite the general real M -by- N matrix C with $SIDE = 'L'$ $SIDE = 'R'$ $TRANS = 'N'$

[sorg2l](#) - sorg2l - generate an m by n real matrix Q with orthonormal columns,

[sorg2r](#) - sorg2r - generate an m by n real matrix Q with orthonormal columns,

[sorgbr](#) - sorgbr - generate one of the real orthogonal matrices Q or P^*T determined by SGEBRD when reducing a real matrix A to bidiagonal form

[sorghr](#) - sorgbr - generate a real orthogonal matrix Q which is defined as the product of $IHI-ILO$ elementary reflectors of order N , as returned by SGEHRD

[sorgl2](#) - sorgl2 - generate an m by n real matrix Q with orthonormal rows,

[sorglq](#) - sorglq - generate an M -by- N real matrix Q with orthonormal rows,

[sorgql](#) - sorgql - generate an M -by- N real matrix Q with orthonormal columns,

[sorgqr](#) - sorgqr - generate an M-by-N real matrix Q with orthonormal columns,

[sorg2](#) - sorg2 - generate an m by n real matrix Q with orthonormal rows,

[sorgq](#) - sorgq - generate an M-by-N real matrix Q with orthonormal rows,

[sorgtr](#) - sorgtr - generate a real orthogonal matrix Q which is defined as the product of n-1 elementary reflectors of order N, as returned by SSYTRD

[sormbr](#) - sormbr - VECT = 'Q', SORMBR overwrites the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[sormhr](#) - sormhr - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[sormlq](#) - sormlq - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[sormql](#) - sormql - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[sormqr](#) - sormqr - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[sormrq](#) - sormrq - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[sormrz](#) - sormrz - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[sormtr](#) - sormtr - overwrite the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[spbcon](#) - spbcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite band matrix using the Cholesky factorization $A = U^{**}T^{*}U$ or $A = L^{*}L^{**}T$ computed by SPBTRF

[spbequ](#) - spbequ - compute row and column scalings intended to equilibrate a symmetric positive definite band matrix A and reduce its condition number (with respect to the two-norm)

[spbrfs](#) - spbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and banded, and provides error bounds and backward error estimates for the solution

[spbstf](#) - spbstf - compute a split Cholesky factorization of a real symmetric positive definite band matrix A

[spbsv](#) - spbsv - compute the solution to a real system of linear equations $A * X = B$,

[spbsvx](#) - spbsvx - use the Cholesky factorization $A = U^{**}T^{*}U$ or $A = L^{*}L^{**}T$ to compute the solution to a real system of linear equations $A * X = B$,

[spbt2](#) - spbt2 - compute the Cholesky factorization of a real symmetric positive definite band matrix A

[spbtrf](#) - spbtrf - compute the Cholesky factorization of a real symmetric positive definite band matrix A

[spbtrs](#) - spbtrs - solve a system of linear equations $A \cdot X = B$ with a symmetric positive definite band matrix A using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by SPBTRF

[spocon](#) - spocon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite matrix using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by SPOTRF

[spoequ](#) - spoequ - compute row and column scalings intended to equilibrate a symmetric positive definite matrix A and reduce its condition number (with respect to the two-norm)

[spotfs](#) - spotfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite,

[sposv](#) - sposv - compute the solution to a real system of linear equations $A \cdot X = B$,

[sposvx](#) - sposvx - use the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ to compute the solution to a real system of linear equations $A \cdot X = B$,

[spotf2](#) - spotf2 - compute the Cholesky factorization of a real symmetric positive definite matrix A

[spotrf](#) - spotrf - compute the Cholesky factorization of a real symmetric positive definite matrix A

[spotri](#) - spotri - compute the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by SPOTRF

[spotrs](#) - spotrs - solve a system of linear equations $A \cdot X = B$ with a symmetric positive definite matrix A using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by SPOTRF

[sppcon](#) - sppcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite packed matrix using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by SPPTRF

[sppequ](#) - sppequ - compute row and column scalings intended to equilibrate a symmetric positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm)

[spprfs](#) - spprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and packed, and provides error bounds and backward error estimates for the solution

[sppsv](#) - sppsv - compute the solution to a real system of linear equations $A \cdot X = B$,

[sppsvx](#) - sppsvx - use the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ to compute the solution to a real system of linear equations $A \cdot X = B$,

[spptrf](#) - spptrf - compute the Cholesky factorization of a real symmetric positive definite matrix A stored in packed format

[spptri](#) - spptri - compute the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by SPPTRF

[spptrs](#) - spptrs - solve a system of linear equations $A*X = B$ with a symmetric positive definite matrix A in packed storage using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by SPPTRF

[sptcon](#) - sptcon - compute the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite tridiagonal matrix using the factorization $A = L*D*L^{**T}$ or $A = U^{**T}*D*U$ computed by SPTTRF

[spteqr](#) - spteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using SPTTRF, and then calling SBDSQR to compute the singular values of the bidiagonal factor

[sptrfs](#) - sprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution

[sptsv](#) - sptsv - compute the solution to a real system of linear equations $A*X = B$, where A is an N-by-N symmetric positive definite tridiagonal matrix, and X and B are N-by-NRHS matrices.

[sptsvx](#) - sptsvx - use the factorization $A = L*D*L^{**T}$ to compute the solution to a real system of linear equations $A*X = B$, where A is an N-by-N symmetric positive definite tridiagonal matrix and X and B are N-by-NRHS matrices

[spttrf](#) - spttrf - compute the $L*D*L'$ factorization of a real symmetric positive definite tridiagonal matrix A

[spttrs](#) - spttrs - solve a tridiagonal system of the form $A * X = B$ using the $L*D*L'$ factorization of A computed by SPTTRF

[sptts2](#) - sptts2 - solve a tridiagonal system of the form $A * X = B$ using the $L*D*L'$ factorization of A computed by SPTTRF

[srot](#) - srot - Apply a Given's rotation constructed by SROTG.

[srotg](#) - srotg - Construct a Given's plane rotation

[sroti](#) - sroti - Apply an indexed Givens rotation.

[srotm](#) - srotm - Apply a Gentleman's modified Given's rotation constructed by SROTMG.

[srotmg](#) - srotmg - Construct a Gentleman's modified Given's plane rotation

[ssbev](#) - ssbev - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

[ssbevd](#) - ssbevd - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

[ssbevz](#) - ssbevz - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

[ssbgst](#) - ssbgst - reduce a real symmetric-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$,

[ssbgv](#) - ssbgv - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x = (\lambda)*B*x$

[ssbgvd](#) - ssbgvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x = (\lambda)*B*x$

[ssbgvx](#) - ssbgvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x = (\lambda)*B*x$

[ssbmvy](#) - ssbmvy - perform the matrix-vector operation $y := \alpha*A*x + \beta*y$

[ssbtrd](#) - ssbtrd - reduce a real symmetric band matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation

[sscal](#) - sscal - Compute $y := \alpha * y$

[ssctr](#) - ssctr - Scatters elements from x into y.

[sskymm](#) - sskymm - Skyline format matrix-matrix multiply

[sskysm](#) - sskysm - Skyline format triangular solve

[sspcon](#) - sspcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric packed matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by SSPTRF

[sspev](#) - sspev - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

[sspevd](#) - sspevd - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

[sspevx](#) - sspevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

[sspgst](#) - sspgst - reduce a real symmetric-definite generalized eigenproblem to standard form, using packed storage

[sspgv](#) - sspgv - compute all the eigenvalues and, optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x = (\lambda)*B*x$, $A*Bx = (\lambda)*x$, or $B*A*x = (\lambda)*x$

[sspgvd](#) - sspgvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x = (\lambda)*B*x$, $A*Bx = (\lambda)*x$, or $B*A*x = (\lambda)*x$

[sspgvx](#) - sspgvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x = (\lambda)*B*x$, $A*Bx = (\lambda)*x$, or $B*A*x = (\lambda)*x$

[sspmv](#) - sspmv - perform the matrix-vector operation $y := \alpha * A * x + \beta * y$

[sspr](#) - sspr - perform the symmetric rank 1 operation $A := \alpha * x * x' + A$

[sspr2](#) - sspr2 - perform the symmetric rank 2 operation $A := \alpha * x * y' + \alpha * y * x' + A$

[ssprfs](#) - ssprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution

[sspsv](#) - sspsv - compute the solution to a real system of linear equations $A * X = B$,

[sspsvx](#) - sspsvx - use the diagonal pivoting factorization $A = U * D * U ** T$ or $A = L * D * L ** T$ to compute the solution to a real system of linear equations $A * X = B$, where A is an N -by- N symmetric matrix stored in packed format and X and B are N -by- N -RHS matrices

[ssptrd](#) - ssptrd - reduce a real symmetric matrix A stored in packed form to symmetric tridiagonal form T by an orthogonal similarity transformation

[ssptf](#) - ssptf - compute the factorization of a real symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method

[ssptri](#) - ssptri - compute the inverse of a real symmetric indefinite matrix A in packed storage using the factorization $A = U * D * U ** T$ or $A = L * D * L ** T$ computed by SSPTRF

[ssptrs](#) - ssptrs - solve a system of linear equations $A * X = B$ with a real symmetric matrix A stored in packed format using the factorization $A = U * D * U ** T$ or $A = L * D * L ** T$ computed by SSPTRF

[sstebz](#) - sstebz - compute the eigenvalues of a symmetric tridiagonal matrix T

[sstedc](#) - sstedc - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method

[sstegr](#) - sstegr - (a) Compute $T - \sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation

[sstein](#) - sstein - compute the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration

[ssteqr](#) - ssteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method

[ssturf](#) - ssterf - compute all eigenvalues of a symmetric tridiagonal matrix using the Pal-Walker-Kahan variant of the QL or QR algorithm

[sstev](#) - sstev - compute all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A

[ssted](#) - ssted - compute all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix

[sstedr](#) - sstedr - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T

[sstedv](#) - sstedv - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A

[sstsv](#) - sstsv - compute the solution to a system of linear equations $A * X = B$ where A is a symmetric tridiagonal matrix

[ssttrf](#) - ssttrf - compute the factorization of a symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method

[ssttrs](#) - ssttrs - computes the solution to a real system of linear equations $A * X = B$

[sswap](#) - sswap - Exchange vectors x and y.

[ssycon](#) - ssycon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric matrix A using the factorization $A = U * D * U ** T$ or $A = L * D * L ** T$ computed by SSYTRF

[ssyev](#) - ssyev - compute all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

[ssyevd](#) - ssyevd - compute all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

[ssyevr](#) - ssyevr - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T

[ssyevx](#) - ssyevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

[ssygs2](#) - ssygs2 - reduce a real symmetric-definite generalized eigenproblem to standard form

[ssygst](#) - ssygst - reduce a real symmetric-definite generalized eigenproblem to standard form

[ssygv](#) - ssygv - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A * x = (\text{lambda}) * B * x$, $A * B x = (\text{lambda}) * x$, or $B * A * x = (\text{lambda}) * x$

[ssygvd](#) - ssygvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A * x = (\text{lambda}) * B * x$, $A * B x = (\text{lambda}) * x$, or $B * A * x = (\text{lambda}) * x$

[ssygvx](#) - ssygvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A * x = (\text{lambda}) * B * x$, $A * B x = (\text{lambda}) * x$, or $B * A * x = (\text{lambda}) * x$

[ssymm](#) - ssymm - perform one of the matrix-matrix operations $C := \text{alpha} * A * B + \text{beta} * C$ or $C := \text{alpha} * B * A + \text{beta} * C$

[ssymv](#) - ssymv - perform the matrix-vector operation $y := \text{alpha} * A * x + \text{beta} * y$

[ssyr](#) - ssyr - perform the symmetric rank 1 operation $A := \alpha * x * x' + A$

[ssyr2](#) - ssyr2 - perform the symmetric rank 2 operation $A := \alpha * x * y' + \alpha * y * x' + A$

[ssyr2k](#) - ssyr2k - perform one of the symmetric rank 2k operations $C := \alpha * A * B' + \alpha * B * A' + \beta * C$ or $C := \alpha * A' * B + \alpha * B' * A + \beta * C$

[ssyrfs](#) - ssyrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution

[ssyrk](#) - ssyrk - perform one of the symmetric rank k operations $C := \alpha * A * A' + \beta * C$ or $C := \alpha * A' * A + \beta * C$

[ssysv](#) - ssysv - compute the solution to a real system of linear equations $A * X = B$,

[ssysvx](#) - ssysvx - use the diagonal pivoting factorization to compute the solution to a real system of linear equations $A * X = B$,

[ssytd2](#) - ssytd2 - reduce a real symmetric matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation

[ssytf2](#) - ssytf2 - compute the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

[ssytrd](#) - ssytrd - reduce a real symmetric matrix A to real symmetric tridiagonal form T by an orthogonal similarity transformation

[ssytrf](#) - ssytrf - compute the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

[ssytri](#) - ssytri - compute the inverse of a real symmetric indefinite matrix A using the factorization $A = U * D * U ** T$ or $A = L * D * L ** T$ computed by SSYTRF

[ssytrs](#) - ssytrs - solve a system of linear equations $A * X = B$ with a real symmetric matrix A using the factorization $A = U * D * U ** T$ or $A = L * D * L ** T$ computed by SSYTRF

[stbcon](#) - stbcon - estimate the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm

[stbmv](#) - stbmv - perform one of the matrix-vector operations $x := A * x$, or $x := A' * x$

[stbrfs](#) - stbrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix

[stbsv](#) - stbsv - solve one of the systems of equations $A * x = b$, or $A' * x = b$

[stbtrs](#) - stbtrs - solve a triangular system of the form $A * X = B$ or $A ** T * X = B$,

[stgevc](#) - stgevc - compute some or all of the right and/or left generalized eigenvectors of a pair of real upper triangular matrices (A,B)

[stgexc](#) - stgexc - reorder the generalized real Schur decomposition of a real matrix pair (A,B) using an orthogonal equivalence transformation $(A, B) = Q * (A, B) * Z'$,

[stgsen](#) - stgsen - reorder the generalized real Schur decomposition of a real matrix pair (A, B) (in terms of an orthonormal equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix A and the upper triangular B

[stgsja](#) - stgsja - compute the generalized singular value decomposition (GSVD) of two real upper triangular (or trapezoidal) matrices A and B

[stgsna](#) - stgsna - estimate reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B) in generalized real Schur canonical form (or of any matrix pair $(Q*A*Z', Q*B*Z')$ with orthogonal matrices Q and Z, where Z' denotes the transpose of Z

[stgsyl](#) - stgsyl - solve the generalized Sylvester equation

[stpcon](#) - stpcon - estimate the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm

[stpmv](#) - stpmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

[stprfs](#) - stprfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix

[stpsv](#) - stpsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

[stptri](#) - stptri - compute the inverse of a real upper or lower triangular matrix A stored in packed format

[stptrs](#) - stptrs - solve a triangular system of the form $A * X = B$ or $A**T * X = B$,

[strans](#) - strans - transpose and scale source matrix

[strcon](#) - strcon - estimate the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm

[strevc](#) - strevc - compute some or all of the right and/or left eigenvectors of a real upper quasi-triangular matrix T

[strex](#) - strexc - reorder the real Schur factorization of a real matrix $A = Q*T*Q**T$, so that the diagonal block of T with row index IFST is moved to row ILST

[strmm](#) - strmm - perform one of the matrix-matrix operations $B := \alpha*op(A)*B$, or $B := \alpha*B*op(A)$

[strmv](#) - strmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

[strrfs](#) - strrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix

[strsen](#) - strsen - reorder the real Schur factorization of a real matrix $A = Q*T*Q**T$, so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix T,

[strsm](#) - strsm - solve one of the matrix equations $op(A)*X = alpha*B$, or $X*op(A) = alpha*B$

[strsna](#) - strsna - estimate reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix T (or of any matrix $Q*T*Q**T$ with Q orthogonal)

[strsv](#) - strsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

[strsyl](#) - strsyl - solve the real Sylvester matrix equation

[strti2](#) - strti2 - compute the inverse of a real upper or lower triangular matrix

[strtri](#) - strtri - compute the inverse of a real upper or lower triangular matrix A

[strtrs](#) - strtrs - solve a triangular system of the form $A * X = B$ or $A**T * X = B$,

[stzrqf](#) - stzrqf - routine is deprecated and has been replaced by routine STZRZF

[stzrzf](#) - stzrzf - reduce the M-by-N ($M \leq N$) real upper trapezoidal matrix A to upper triangular form by means of orthogonal transformations

[sunperf_version](#) - sunperf_version - gets library information 1i SUBROUTINE SUNPERF_VERSION(VERSION, PATCH, UPDATE) 1i INTEGER VERSION, PATCH, UPDATE 1i

[svbrmm](#) - svbrmm - variable block sparse row format matrix-matrix multiply

[svbrsm](#) - svbrsm - variable block sparse row format triangular solve

[swiener](#) - swiener - perform Wiener deconvolution of two signals

[use_threads](#) - use_threads - Sets the number of threads to use for subsequent parallel regions

[using_threads](#) - using_threads - In a parallel environment, if called from a serial region of the master thread it returns the number of threads available for execution (determined by function OMP_GET_NUM_THREADS). Else, if it is called from a thread in the team executing the parallel region it returns a 1. USING_THREADS subroutine

[vcfftb](#) - vcfftb - compute a periodic sequence from its Fourier coefficients. The VCFFT operations are normalized, so a call of VCFFTF followed by a call of VCFFTB will return the original sequence.

[vcfftf](#) - vcfftf - compute the Fourier coefficients of a periodic sequence. The VCFFT operations are normalized, so a call of VCFFTF followed by a call of VCFFTB will return the original sequence.

[vcffti](#) - vcffti - initialize the array WSAVE, which is used in both VCFFTF and VCFFTB.

[vcosqb](#) - vcosqb - synthesize a Fourier sequence from its representation in terms of a cosine series with odd wave numbers. The VCOSQ operations are normalized, so a call of VCOSQF followed by a call of VCOSQB will return the original sequence.

[vcosqf](#) - vcosqf - compute the Fourier coefficients in a cosine series representation with only odd wave numbers. The VCOSQ operations are normalized, so a call of VCOSQF followed by a call of VCOSQB will return the original sequence.

[vcosqi](#) - vcosqi - initialize the array WSAVE, which is used in both VCOSQF and VCOSQB.

[vcost](#) - vcost - compute the discrete Fourier cosine transform of an even sequence. The VCOST transform is normalized, so a call of VCOST followed by a call of VCOST will return the original sequence.

[vcosti](#) - vcosti - initialize the array WSAVE, which is used in VCOST.

[vdcosqb](#) - vdcosqb - synthesize a Fourier sequence from its representation in terms of a cosine series with odd wave numbers. The VCOSQ operations are normalized, so a call of VCOSQF followed by a call of VCOSQB will return the original sequence.

[vdcosqf](#) - vdcosqf - compute the Fourier coefficients in a cosine series representation with only odd wave numbers. The VCOSQ operations are normalized, so a call of VCOSQF followed by a call of VCOSQB will return the original sequence.

[vdcosqi](#) - vdcosqi - initialize the array WSAVE, which is used in both VCOSQF and VCOSQB.

[vdcost](#) - vdcost - compute the discrete Fourier cosine transform of an even sequence. The VCOST transform is normalized, so a call of VCOST followed by a call of VCOST will return the original sequence.

[vdcosti](#) - vdcosti - initialize the array WSAVE, which is used in VCOST.

[vdfftb](#) - vdfftb - compute a periodic sequence from its Fourier coefficients. The VRFFT operations are normalized, so a call of VRFFTF followed by a call of VRFFTB will return the original sequence.

[vdfftf](#) - vdfftf - compute the Fourier coefficients of a periodic sequence. The VRFFT operations are normalized, so a call of VRFFTF followed by a call of VRFFTB will return the original sequence.

[vdffti](#) - vdffti - initialize the array WSAVE, which is used in both VRFFTF and VRFFTB.

[vdsinqb](#) - vdsinqb - synthesize a Fourier sequence from its representation in terms of a sine series with odd wave numbers. The VSINQ operations are normalized, so a call of VSINQF followed by a call of VSINQB will return the original

sequence.

[vdsinqf](#) - vdsinqf - compute the Fourier coefficients in a sine series representation with only odd wave numbers. The VSINQ operations are normalized, so a call of VSINQF followed by a call of VSINQB will return the original sequence.

[vdsinqi](#) - vdsinqi - initialize the array WSAVE, which is used in both VSINQF and VSINQB.

[vdsint](#) - vdsint - compute the discrete Fourier sine transform of an odd sequence. The VSINT transforms are unnormalized inverses of themselves, so a call of VSINT followed by another call of VSINT will multiply the input sequence by $2 * (N + 1)$. The VSINT transforms are normalized, so a call of VSINT followed by a call of VSINT will return the original sequence.

[vdsinti](#) - vdsinti - initialize the array WSAVE, which is used in subroutine VSINT.

[vrfftb](#) - vrfftb - compute a periodic sequence from its Fourier coefficients. The VRFFT operations are normalized, so a call of VRFFTF followed by a call of VRFFTB will return the original sequence.

[vrfft](#) - vrfft - compute the Fourier coefficients of a periodic sequence. The VRFFT operations are normalized, so a call of VRFFTF followed by a call of VRFFTB will return the original sequence.

[vrffti](#) - vrffti - initialize the array WSAVE, which is used in both VRFFTF and VRFFTB.

[vsinqb](#) - vsinqb - synthesize a Fourier sequence from its representation in terms of a sine series with odd wave numbers. The VSINQ operations are normalized, so a call of VSINQF followed by a call of VSINQB will return the original sequence.

[vsinqf](#) - vsinqf - compute the Fourier coefficients in a sine series representation with only odd wave numbers. The VSINQ operations are normalized, so a call of VSINQF followed by a call of VSINQB will return the original sequence.

[vsinqi](#) - vsinqi - initialize the array WSAVE, which is used in both VSINQF and VSINQB.

[vsint](#) - vsint - compute the discrete Fourier sine transform of an odd sequence. The VSINT transforms are unnormalized inverses of themselves, so a call of VSINT followed by another call of VSINT will multiply the input sequence by $2 * (N + 1)$. The VSINT transforms are normalized, so a call of VSINT followed by a call of VSINT will return the original sequence.

[vsinti](#) - vsinti - initialize the array WSAVE, which is used in subroutine VSINT.

[vzfftb](#) - vzfftb - compute a periodic sequence from its Fourier coefficients. The VZFFT operations are normalized, so a call of VZFFTF followed by a call of VZFFTB will return the original sequence.

[vzfft](#) - vzfft - compute the Fourier coefficients of a periodic sequence. The VZFFT operations are normalized, so a call of VZFFTF followed by a call of VZFFTB will return the original sequence.

[vzffti](#) - vzffti - initialize the array WSAVE, which is used in both VZFFTF and VZFFTB.

[zaxpy](#) - zaxpy - compute $y := \alpha * x + y$

[zaxpyi](#) - zaxpyi - Compute $y := \alpha * x + y$

[zbcmm](#) - zbcmm - block coordinate matrix-matrix multiply

[zbdimm](#) - zbdimm - block diagonal format matrix-matrix multiply

[zbdism](#) - zbdism - block diagonal format triangular solve

[zbdsql](#) - zbdsql - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B.

[zbelmm](#) - zbelmm - block Ellpack format matrix-matrix multiply

[zbelsm](#) - zbelsm - block Ellpack format triangular solve

[zbscmm](#) - zbscmm - block sparse column matrix-matrix multiply

[zbscsm](#) - zbscsm - block sparse column format triangular solve

[zbsrmm](#) - zbsrmm - block sparse row format matrix-matrix multiply

[zbsrsm](#) - zbsrsm - block sparse row format triangular solve

[zcnvcor](#) - zcnvcor - compute the convolution or correlation of complex vectors

[zcnvcor2](#) - zcnvcor2 - compute the convolution or correlation of complex matrices

[zcoomm](#) - zcoomm - coordinate matrix-matrix multiply

[zcopy](#) - zcopy - Copy x to y

[zscmm](#) - zscmm - compressed sparse column format matrix-matrix multiply

[zscsm](#) - zscsm - compressed sparse column format triangular solve

[zsrmm](#) - zsrmm - compressed sparse row format matrix-matrix multiply

[zsrsm](#) - zsrsm - compressed sparse row format triangular solve

[zdiamm](#) - zdiamm - diagonal format matrix-matrix multiply.

[zdiasm](#) - zdiasm - diagonal format triangular solve

[zdotc](#) - zdotc - compute the dot product of two vectors conjg(x) and y.

[zdotci](#) - zdotci - Compute the complex conjugated indexed dot product.

[zdotu](#) - zdotu - compute the dot product of two vectors x and y.

[zdotui](#) - zdotui - Compute the complex unconjugated indexed dot product.

[zdrot](#) - zdrot - Apply a plane rotation.

[zdscal](#) - zdscal - Compute $y := \alpha * y$

[zellmm](#) - zellmm - Ellpack format matrix-matrix multiply

[zellsm](#) - zellsm - Ellpack format triangular solve

[zfft2b](#) - zfft2b - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of ZFFT2F followed by a call of ZFFT2B will multiply the input sequence by $M*N$.

[zfft2f](#) - zfft2f - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of ZFFT2F followed by a call of ZFFT2B will multiply the input sequence by $M*N$.

[zfft2i](#) - zfft2i - initialize the array WSAVE, which is used in both the forward and backward transforms.

[zfft3b](#) - zfft3b - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of ZFFT3F followed by a call of ZFFT3B will multiply the input sequence by $M*N*K$.

[zfft3f](#) - zfft3f - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of ZFFT3F followed by a call of ZFFT3B will multiply the input sequence by $M*N*K$.

[zfft3i](#) - zfft3i - initialize the array WSAVE, which is used in both ZFFT3F and ZFFT3B.

[zfftb](#) - zfftb - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of ZFFTF followed by a call of ZFFTB will multiply the input sequence by N .

[zfftd](#) - zfftd - initialize the trigonometric weight and factor tables or compute the inverse Fast Fourier Transform of a double complex sequence.

[zfftd2](#) - zfftd2 - initialize the trigonometric weight and factor tables or compute the two-dimensional inverse Fast Fourier Transform of a two-dimensional double complex array.

[zfftd3](#) - zfftd3 - initialize the trigonometric weight and factor tables or compute the three-dimensional inverse Fast Fourier

Transform of a three-dimensional double complex array.

[zfftdm](#) - zfftdm - initialize the trigonometric weight and factor tables or compute the one-dimensional inverse Fast Fourier Transform of a set of double complex data sequences stored in a two-dimensional array.

[zfftf](#) - zfftf - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of ZFFTF followed by a call of ZFFTB will multiply the input sequence by N.

[zffti](#) - zffti - initialize the array WSAVE, which is used in both ZFFTF and ZFFTB.

[zfftpt](#) - zfftpt - compute the length of the closest fast FFT

[zfftz](#) - zfftz - initialize the trigonometric weight and factor tables or compute the Fast Fourier transform (forward or inverse) of a double complex sequence.

[zfftz2](#) - zfftz2 - initialize the trigonometric weight and factor tables or compute the two-dimensional Fast Fourier Transform (forward or inverse) of a two-dimensional double complex array.

[zfftz3](#) - zfftz3 - initialize the trigonometric weight and factor tables or compute the three-dimensional Fast Fourier Transform (forward or inverse) of a three-dimensional double complex array.

[zfftzm](#) - zfftzm - initialize the trigonometric weight and factor tables or compute the one-dimensional Fast Fourier Transform (forward or inverse) of a set of data sequences stored in a two-dimensional double complex array.

[zgbbrd](#) - zgbbrd - reduce a complex general m-by-n band matrix A to real upper bidiagonal form B by a unitary transformation

[zgbcon](#) - zgbcon - estimate the reciprocal of the condition number of a complex general band matrix A, in either the 1-norm or the infinity-norm,

[zgbequ](#) - zgbequ - compute row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number

[zgbmv](#) - zgbmv - perform one of the matrix-vector operations $y := \alpha * A * x + \beta * y$, or $y := \alpha * A' * x + \beta * y$, or $y := \alpha * \text{conj}(A') * x + \beta * y$

[zgbfrs](#) - zgbfrs - improve the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution

[zgbsv](#) - zgbsv - compute the solution to a complex system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices

[zgbsvx](#) - zgbsvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A ** T * X = B$, or $A ** H * X = B$,

[zgbtf2](#) - zgbtf2 - compute an LU factorization of a complex m-by-n band matrix A using partial pivoting with row

interchanges

[zgbtrf](#) - zgbtrf - compute an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges

[zgbtrs](#) - zgbtrs - solve a system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$ with a general band matrix A using the LU factorization computed by ZGBTRF

[zgebak](#) - zgebak - form the right or left eigenvectors of a complex general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by ZGEBAL

[zgebal](#) - zgebal - balance a general complex matrix A

[zgebrd](#) - zgebrd - reduce a general complex M-by-N matrix A to upper or lower bidiagonal form B by a unitary transformation

[zgecon](#) - zgecon - estimate the reciprocal of the condition number of a general complex matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by ZGETRF

[zgeequ](#) - zgeequ - compute row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number

[zgees](#) - zgees - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z

[zgeesx](#) - zgeesx - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z

[zgeev](#) - zgeev - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

[zgeevx](#) - zgeevx - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

[zgegs](#) - zgegs - routine is deprecated and has been replaced by routine CGGES

[zgegv](#) - zgegv - routine is deprecated and has been replaced by routine CGGEV

[zgehrd](#) - zgehrd - reduce a complex general matrix A to upper Hessenberg form H by a unitary similarity transformation

[zgelqf](#) - zgelqf - compute an LQ factorization of a complex M-by-N matrix A

[zgels](#) - zgels - solve overdetermined or underdetermined complex linear systems involving an M-by-N matrix A, or its conjugate-transpose, using a QR or LQ factorization of A

[zgelsd](#) - zgelsd - compute the minimum-norm solution to a real linear least squares problem

[zgelss](#) - zgelss - compute the minimum norm solution to a complex linear least squares problem

[zgelsx](#) - zgelsx - routine is deprecated and has been replaced by routine ZGELSY

[zgelsy](#) - zgelsy - compute the minimum-norm solution to a complex linear least squares problem

[zgemm](#) - zgemm - perform one of the matrix-matrix operations $C := \alpha * \text{op}(A) * \text{op}(B) + \beta * C$

[zgemv](#) - zgemv - perform one of the matrix-vector operations $y := \alpha * A * x + \beta * y$, or $y := \alpha * A' * x + \beta * y$, or $y := \alpha * \text{conjg}(A') * x + \beta * y$

[zgeqlf](#) - zgeqlf - compute a QL factorization of a complex M-by-N matrix A

[zgeqp3](#) - zgeqp3 - compute a QR factorization with column pivoting of a matrix A

[zgeqpf](#) - zgeqpf - routine is deprecated and has been replaced by routine ZGEQP3

[zgeqrf](#) - zgeqrf - compute a QR factorization of a complex M-by-N matrix A

[zgerc](#) - zgerc - perform the rank 1 operation $A := \alpha * x * \text{conjg}(y') + A$

[zgerfs](#) - zgerfs - improve the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution

[zgerqf](#) - zgerqf - compute an RQ factorization of a complex M-by-N matrix A

[zgeru](#) - zgeru - perform the rank 1 operation $A := \alpha * x * y' + A$

[zgesdd](#) - zgesdd - compute the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors, by using divide-and-conquer method

[zgesv](#) - zgesv - compute the solution to a complex system of linear equations $A * X = B$,

[zgesvd](#) - zgesvd - compute the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors

[zgesvx](#) - zgesvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$,

[zgetf2](#) - zgetf2 - compute an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges

[zgetrf](#) - zgetrf - compute an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges

[zgetri](#) - zgetri - compute the inverse of a matrix using the LU factorization computed by ZGETRF

[zgetrs](#) - zgetrs - solve a system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$ with a general N-by-N matrix A using the LU factorization computed by ZGETRF

[zggbak](#) - zggbak - form the right or left eigenvectors of a complex generalized eigenvalue problem $A*x = \lambda*B*x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by ZGGBAL

[zggbal](#) - zggbal - balance a pair of general complex matrices (A,B)

[zggges](#) - zggges - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the generalized complex Schur form (S, T), and optionally left and/or right Schur vectors (VSL and VSR)

[zgggesx](#) - zgggesx - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the complex Schur form (S,T),

[zgggev](#) - zgggev - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors

[zgggevz](#) - zgggevz - compute for a pair of N-by-N complex nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors

[zggglm](#) - zggglm - solve a general Gauss-Markov linear model (GLM) problem

[zggghrd](#) - zggghrd - reduce a pair of complex matrices (A,B) to generalized upper Hessenberg form using unitary transformations, where A is a general matrix and B is upper triangular

[zggglse](#) - zggglse - solve the linear equality-constrained least squares (LSE) problem

[zggqrqf](#) - zggqrqf - compute a generalized QR factorization of an N-by-M matrix A and an N-by-P matrix B.

[zgggrqf](#) - zgggrqf - compute a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B

[zgggsvd](#) - zgggsvd - compute the generalized singular value decomposition (GSVD) of an M-by-N complex matrix A and P-by-N complex matrix B

[zgggsvp](#) - zgggsvp - compute unitary matrices U, V and Q such that $N-K-L \begin{matrix} K & L & U^* & A & Q \\ & & & & \end{matrix} = \begin{matrix} K & & & & \\ & 0 & A_{12} & A_{13} & \\ & & & & \end{matrix}$ if $M-K-L \geq 0$

[zggssco](#) - zggssco - General sparse solver condition number estimate.

[zggssda](#) - zggssda - Deallocate working storage for the general sparse solver.

[zggssfa](#) - zggssfa - General sparse solver numeric factorization.

[zgssfs](#) - zgssfs - General sparse solver one call interface.

[zgssin](#) - zgssin - Initialize the general sparse solver.

[zgssor](#) - zgssor - General sparse solver ordering and symbolic factorization.

[zgssps](#) - zgssps - Print general sparse solver statics.

[zgssrp](#) - zgssrp - Return permutation used by the general sparse solver.

[zgsssl](#) - zgsssl - Solve routine for the general sparse solver.

[zgssuo](#) - zgssuo - User supplied permutation for ordering used in the general sparse solver.

[zgtcon](#) - zgtcon - estimate the reciprocal of the condition number of a complex tridiagonal matrix A using the LU factorization as computed by ZGTTRF

[zgtthr](#) - zgtthr - Gathers specified elements from y into x.

[zgtthrz](#) - zgtthrz - Gather and zero.

[zgtfrs](#) - zgtfrs - improve the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution

[zgtsv](#) - zgtsv - solve the equation $A * X = B$,

[zgtsvx](#) - zgtsvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

[zgttrf](#) - zgttrf - compute an LU factorization of a complex tridiagonal matrix A using elimination with partial pivoting and row interchanges

[zgttrs](#) - zgttrs - solve one of the systems of equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

[zhbev](#) - zhbev - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

[zhbevd](#) - zhbevd - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

[zhbevz](#) - zhbevz - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

[zhbgst](#) - zhbgst - reduce a complex Hermitian-definite banded generalized eigenproblem $A * x = \lambda * B * x$ to standard form $C * y = \lambda * y$,

[zhbgv](#) - zhbgv - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

[zhbgvd](#) - zhbgvd - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

[zhbgvx](#) - zhbgvx - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

[zhbmV](#) - zhbmv - perform the matrix-vector operation $y := \alpha*A*x + \beta*y$

[zhbtrd](#) - zhbtrd - reduce a complex Hermitian band matrix A to real symmetric tridiagonal form T by a unitary similarity transformation

[zhecon](#) - zhecon - estimate the reciprocal of the condition number of a complex Hermitian matrix A using the factorization $A = U*D*U**H$ or $A = L*D*L**H$ computed by ZHETRF

[zheev](#) - zheev - compute all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

[zheevd](#) - zheevd - compute all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

[zheevr](#) - zheevr - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian tridiagonal matrix T

[zheevx](#) - zheevx - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

[zhegs2](#) - zhegs2 - reduce a complex Hermitian-definite generalized eigenproblem to standard form

[zhegst](#) - zhegst - reduce a complex Hermitian-definite generalized eigenproblem to standard form

[zhegv](#) - zhegv - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

[zhegvd](#) - zhegvd - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

[zhegvx](#) - zhegvx - compute selected eigenvalues, and optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

[zhemm](#) - zhemm - perform one of the matrix-matrix operations $C := \alpha*A*B + \beta*C$ or $C := \alpha*B*A + \beta*C$

[zhemv](#) - zhemv - perform the matrix-vector operation $y := \alpha*A*x + \beta*y$

[zher](#) - zher - perform the hermitian rank 1 operation $A := \alpha*x*\text{conj}(x') + A$

[zher2](#) - zher2 - perform the hermitian rank 2 operation $A := \alpha * x * \text{conjg}(y') + \text{conjg}(\alpha) * y * \text{conjg}(x') + A$

[zher2k](#) - zher2k - perform one of the Hermitian rank 2k operations $C := \alpha * A * \text{conjg}(B') + \text{conjg}(\alpha) * B * \text{conjg}(A') + \beta * C$ or $C := \alpha * \text{conjg}(A') * B + \text{conjg}(\alpha) * \text{conjg}(B') * A + \beta * C$

[zherfs](#) - zherfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite, and provides error bounds and backward error estimates for the solution

[zherk](#) - zherk - perform one of the Hermitian rank k operations $C := \alpha * A * \text{conjg}(A') + \beta * C$ or $C := \alpha * \text{conjg}(A') * A + \beta * C$

[zhesv](#) - zhesv - compute the solution to a complex system of linear equations $A * X = B$,

[zhesvx](#) - zhesvx - use the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$,

[zhetf2](#) - zhetf2 - compute the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method

[zhetrd](#) - zhetrd - reduce a complex Hermitian matrix A to real symmetric tridiagonal form T by a unitary similarity transformation

[zhetrf](#) - zhetrf - compute the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method

[zhetri](#) - zhetri - compute the inverse of a complex Hermitian indefinite matrix A using the factorization $A = U * D * U ** H$ or $A = L * D * L ** H$ computed by ZHETRF

[zhetrs](#) - zhetrs - solve a system of linear equations $A * X = B$ with a complex Hermitian matrix A using the factorization $A = U * D * U ** H$ or $A = L * D * L ** H$ computed by ZHETRF

[zhgeqz](#) - zhgeqz - implement a single-shift version of the QZ method for finding the generalized eigenvalues $w(i) = \text{ALPHA}(i) / \text{BETA}(i)$ of the equation $\det(A - w(i) B) = 0$ If JOB='S', then the pair (A,B) is simultaneously reduced to Schur form (i. e., A and B are both upper triangular) by applying one unitary transformation (usually called Q) on the left and another (usually called Z) on the right

[zhpcon](#) - zhpcon - estimate the reciprocal of the condition number of a complex Hermitian packed matrix A using the factorization $A = U * D * U ** H$ or $A = L * D * L ** H$ computed by ZHPTRF

[zhpev](#) - zhpev - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix in packed storage

[zhpevd](#) - zhpevd - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage

[zhpevx](#) - zhpevx - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage

[zhpgst](#) - zhpgst - reduce a complex Hermitian-definite generalized eigenproblem to standard form, using packed storage

[zhpgv](#) - zhpgv - compute all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

[zhpgvd](#) - zhpgvd - compute all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

[zhpgvx](#) - zhpgvx - compute selected eigenvalues and, optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

[zhpmv](#) - zhpmv - perform the matrix-vector operation $y := \alpha*A*x + \beta*y$

[zhpr](#) - zhpr - perform the hermitian rank 1 operation $A := \alpha*x*\text{conjg}(x') + A$

[zhpr2](#) - zhpr2 - perform the Hermitian rank 2 operation $A := \alpha*x*\text{conjg}(y') + \text{conjg}(\alpha)*y*\text{conjg}(x') + A$

[zhprfs](#) - zhprfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite and packed, and provides error bounds and backward error estimates for the solution

[zhpsv](#) - zhpsv - compute the solution to a complex system of linear equations $A * X = B$,

[zhpsvx](#) - zhpsvx - use the diagonal pivoting factorization $A = U*D*U**H$ or $A = L*D*L**H$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N Hermitian matrix stored in packed format and X and B are N-by-NRHS matrices

[zhptrd](#) - zhptrd - reduce a complex Hermitian matrix A stored in packed form to real symmetric tridiagonal form T by a unitary similarity transformation

[zhptrf](#) - zhptrf - compute the factorization of a complex Hermitian packed matrix A using the Bunch-Kaufman diagonal pivoting method

[zhptri](#) - zhptri - compute the inverse of a complex Hermitian indefinite matrix A in packed storage using the factorization $A = U*D*U**H$ or $A = L*D*L**H$ computed by ZHPTRF

[zhptrs](#) - zhptrs - solve a system of linear equations $A*X = B$ with a complex Hermitian matrix A stored in packed format using the factorization $A = U*D*U**H$ or $A = L*D*L**H$ computed by ZHPTRF

[zhsein](#) - zhsein - use inverse iteration to find specified right and/or left eigenvectors of a complex upper Hessenberg matrix H

[zhseqr](#) - zhseqr - compute the eigenvalues of a complex upper Hessenberg matrix H, and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z**H$, where T is an upper triangular matrix (the Schur form), and Z is the unitary matrix of Schur vectors

[zjadmm](#) - zjadmm - Jagged diagonal matrix-matrix multiply (modified Ellpack)

[zjadrp](#) - zjadrp - right permutation of a jagged diagonal matrix

[zjadsm](#) - zjadsm - Jagged-diagonal format triangular solve

[zlarz](#) - zlarz - apply a complex elementary reflector H to a complex M-by-N matrix C, from either the left or the right

[zlarzb](#) - zlarzb - apply a complex block reflector H or its transpose H^*H to a complex distributed M-by-N C from the left or the right

[zlarzt](#) - zlarzt - form the triangular factor T of a complex block reflector H of order $> n$, which is defined as a product of k elementary reflectors

[zlatzm](#) - zlatzm - routine is deprecated and has been replaced by routine CUNMRZ

[zpbcon](#) - zpbcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite band matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPBTRF

[zpbegu](#) - zpbegu - compute row and column scalings intended to equilibrate a Hermitian positive definite band matrix A and reduce its condition number (with respect to the two-norm)

[zpbfrs](#) - zpbfrs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and banded, and provides error bounds and backward error estimates for the solution

[zpbstf](#) - zpbstf - compute a split Cholesky factorization of a complex Hermitian positive definite band matrix A

[zpbsv](#) - zpbsv - compute the solution to a complex system of linear equations $A * X = B$,

[zpbsvx](#) - zpbsvx - use the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations $A * X = B$,

[zpbtf2](#) - zpbtf2 - compute the Cholesky factorization of a complex Hermitian positive definite band matrix A

[zpbtrf](#) - zpbtrf - compute the Cholesky factorization of a complex Hermitian positive definite band matrix A

[zpbtrs](#) - zpbtrs - solve a system of linear equations $A * X = B$ with a Hermitian positive definite band matrix A using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPBTRF

[zpocon](#) - zpocon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPOTRF

[zpoegu](#) - zpoegu - compute row and column scalings intended to equilibrate a Hermitian positive definite matrix A and reduce its condition number (with respect to the two-norm)

[zporfs](#) - zporfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite,

[zposv](#) - zposv - compute the solution to a complex system of linear equations $A * X = B$,

[zposvx](#) - zposvx - use the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ to compute the solution to a complex system of linear equations $A * X = B$,

[zpotf2](#) - zpotf2 - compute the Cholesky factorization of a complex Hermitian positive definite matrix A

[zpotrf](#) - zpotrf - compute the Cholesky factorization of a complex Hermitian positive definite matrix A

[zpotri](#) - zpotri - compute the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by ZPOTRF

[zpotrs](#) - zpotrs - solve a system of linear equations $A*X = B$ with a Hermitian positive definite matrix A using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by ZPOTRF

[zppcon](#) - zppcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite packed matrix using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by ZPPTRF

[zppequ](#) - zppequ - compute row and column scalings intended to equilibrate a Hermitian positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm)

[zpprfs](#) - zpprfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and packed, and provides error bounds and backward error estimates for the solution

[zppsv](#) - zppsv - compute the solution to a complex system of linear equations $A * X = B$,

[zppsvx](#) - zppsvx - use the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ to compute the solution to a complex system of linear equations $A * X = B$,

[zpptrf](#) - zpptrf - compute the Cholesky factorization of a complex Hermitian positive definite matrix A stored in packed format

[zpptri](#) - zpptri - compute the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by ZPPTRF

[zpptrs](#) - zpptrs - solve a system of linear equations $A*X = B$ with a Hermitian positive definite matrix A in packed storage using the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ computed by ZPPTRF

[zptcon](#) - zptcon - compute the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite tridiagonal matrix using the factorization $A = L*D*L**H$ or $A = U**H*D*U$ computed by ZPTTRF

[zpteqr](#) - zpteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using SPTTRF and then calling CBDSQR to compute the singular values of the bidiagonal

factor

[zptrfs](#) - zptrfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution

[zptsv](#) - zptsv - compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N Hermitian positive definite tridiagonal matrix, and X and B are N-by-NRHS matrices.

[zptsvx](#) - zptsvx - use the factorization $A = L * D * L^{**} H$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N Hermitian positive definite tridiagonal matrix and X and B are N-by-NRHS matrices

[zpttrf](#) - zpttrf - compute the $L * D * L'$ factorization of a complex Hermitian positive definite tridiagonal matrix A

[zpttrs](#) - zpttrs - solve a tridiagonal system of the form $A * X = B$ using the factorization $A = U' * D * U$ or $A = L * D * L'$ computed by ZPTTRF

[zpts2](#) - zpts2 - solve a tridiagonal system of the form $A * X = B$ using the factorization $A = U' * D * U$ or $A = L * D * L'$ computed by ZPTTRF

[zrot](#) - zrot - apply a plane rotation, where the cos (C) is real and the sin (S) is complex, and the vectors X and Y are complex

[zrotg](#) - zrotg - Construct a Given's plane rotation

[zscal](#) - zscal - Compute $y := \alpha * y$

[zsctr](#) - zsctr - Scatters elements from x into y.

[zskymm](#) - zskymm - Skyline format matrix-matrix multiply

[zskysm](#) - zskysm - Skyline format triangular solve

[zsalcon](#) - zsalcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex symmetric packed matrix A using the factorization $A = U * D * U^{**} T$ or $A = L * D * L^{**} T$ computed by ZSPTRF

[zsprfs](#) - zsprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution

[zpspv](#) - zpspv - compute the solution to a complex system of linear equations $A * X = B$,

[zpsvx](#) - zpsvx - use the diagonal pivoting factorization $A = U * D * U^{**} T$ or $A = L * D * L^{**} T$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices

[zsptrf](#) - zsptrf - compute the factorization of a complex symmetric matrix A stored in packed format using the Bunch-

Kaufman diagonal pivoting method

[zsptri](#) - zsptri - compute the inverse of a complex symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by ZSPTRF

[zsptrs](#) - zsptrs - solve a system of linear equations $A^*X = B$ with a complex symmetric matrix A stored in packed format using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by ZSPTRF

[zstedc](#) - zstedc - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method

[zstegr](#) - zstegr - Compute $T - \sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation

[zstein](#) - zstein - compute the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration

[zsteqr](#) - zsteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method

[zstsv](#) - zstsv - compute the solution to a complex system of linear equations $A^*X = B$ where A is a symmetric tridiagonal matrix

[zsttrf](#) - zsttrf - compute the factorization of a complex symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method

[zsttrs](#) - zsttrs - computes the solution to a complex system of linear equations $A^*X = B$

[zswap](#) - zswap - Exchange vectors x and y.

[zsycon](#) - zsycon - estimate the reciprocal of the condition number (in the 1-norm) of a complex symmetric matrix A using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by ZSYTRF

[zsymm](#) - zsymm - perform one of the matrix-matrix operations $C := \alpha^*A^*B + \beta^*C$ or $C := \alpha^*B^*A + \beta^*C$

[zsy2k](#) - zsy2k - perform one of the symmetric rank 2k operations $C := \alpha^*A^*B' + \alpha^*B^*A' + \beta^*C$ or $C := \alpha^*A^*B + \alpha^*B^*A + \beta^*C$

[zsyrrfs](#) - zsyrrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution

[zsyrrk](#) - zsyrrk - perform one of the symmetric rank k operations $C := \alpha^*A^*A' + \beta^*C$ or $C := \alpha^*A^*A + \beta^*C$

[zsysv](#) - zsysv - compute the solution to a complex system of linear equations $A^*X = B$,

[zsysvx](#) - zsysvx - use the diagonal pivoting factorization to compute the solution to a complex system of linear equations A

* $X = B$,

[zsytf2](#) - zsytf2 - compute the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

[zsytrf](#) - zsytrf - compute the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

[zsytri](#) - zsytri - compute the inverse of a complex symmetric indefinite matrix A using the factorization $A = U * D * U^{**T}$ or $A = L * D * L^{**T}$ computed by ZSYTRF

[zsytrs](#) - zsytrs - solve a system of linear equations $A * X = B$ with a complex symmetric matrix A using the factorization $A = U * D * U^{**T}$ or $A = L * D * L^{**T}$ computed by ZSYTRF

[ztbcon](#) - ztbcon - estimate the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm

[ztbmv](#) - ztbmv - perform one of the matrix-vector operations $x := A * x$, or $x := A' * x$, or $x := \text{conjg}(A') * x$

[ztbrfs](#) - ztbrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix

[ztbsv](#) - ztbsv - solve one of the systems of equations $A * x = b$, or $A' * x = b$, or $\text{conjg}(A') * x = b$

[ztbtrs](#) - ztbtrs - solve a triangular system of the form $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

[ztgevc](#) - ztgevc - compute some or all of the right and/or left generalized eigenvectors of a pair of complex upper triangular matrices (A,B)

[ztgexc](#) - ztgexc - reorder the generalized Schur decomposition of a complex matrix pair (A,B), using an unitary equivalence transformation $(A, B) := Q * (A, B) * Z'$, so that the diagonal block of (A, B) with row index IFST is moved to row ILST

[ztgsen](#) - ztgsen - reorder the generalized Schur decomposition of a complex matrix pair (A, B) (in terms of an unitary equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the pair (A,B)

[ztgsja](#) - ztgsja - compute the generalized singular value decomposition (GSVD) of two complex upper triangular (or trapezoidal) matrices A and B

[ztgsna](#) - ztgsna - estimate reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B)

[ztgsyl](#) - ztgsyl - solve the generalized Sylvester equation

[ztpcon](#) - ztpcon - estimate the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or

the infinity-norm

[ztpmv](#) - ztpmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$

[ztpdfs](#) - ztpdfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix

[ztpsv](#) - ztpsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A')*x = b$

[ztptri](#) - ztptri - compute the inverse of a complex upper or lower triangular matrix A stored in packed format

[ztptrs](#) - ztptrs - solve a triangular system of the form $A * X = B$, $A**T * X = B$, or $A**H * X = B$,

[ztrans](#) - ztrans - transpose and scale source matrix

[ztrcon](#) - ztrcon - estimate the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm

[ztrevc](#) - ztrevc - compute some or all of the right and/or left eigenvectors of a complex upper triangular matrix T

[ztrexc](#) - ztrexc - reorder the Schur factorization of a complex matrix $A = Q*T*Q**H$, so that the diagonal element of T with row index IFST is moved to row ILST

[ztrmm](#) - ztrmm - perform one of the matrix-matrix operations $B := \alpha*\text{op}(A)*B$, or $B := \alpha*B*\text{op}(A)$ where alpha is a scalar, B is an m by n matrix, A is a unit, or non-unit, upper or lower triangular matrix and $\text{op}(A)$ is one of $\text{op}(A) = A$ or $\text{op}(A) = A'$ or $\text{op}(A) = \text{conjg}(A')$

[ztrmv](#) - ztrmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$

[ztrrfs](#) - ztrrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix

[ztrsena](#) - ztrsena - reorder the Schur factorization of a complex matrix $A = Q*T*Q**H$, so that a selected cluster of eigenvalues appears in the leading positions on the diagonal of the upper triangular matrix T, and the leading columns of Q form an orthonormal basis of the corresponding right invariant subspace

[ztrsm](#) - ztrsm - solve one of the matrix equations $\text{op}(A)*X = \alpha*B$, or $X*\text{op}(A) = \alpha*B$

[ztrsna](#) - ztrsna - estimate reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a complex upper triangular matrix T (or of any matrix $Q*T*Q**H$ with Q unitary)

[ztrsv](#) - ztrsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A')*x = b$

[ztrsyl](#) - ztrsyl - solve the complex Sylvester matrix equation

[ztrti2](#) - ztrti2 - compute the inverse of a complex upper or lower triangular matrix

[ztrtri](#) - ztrtri - compute the inverse of a complex upper or lower triangular matrix A

[ztrtrs](#) - ztrtrs - solve a triangular system of the form $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

[ztzrqf](#) - ztzrqf - routine is deprecated and has been replaced by routine CTZRZF

[ztzrzf](#) - ztzrzf - reduce the M-by-N ($M \leq N$) complex upper trapezoidal matrix A to upper triangular form by means of unitary transformations

[zung2l](#) - zung2l - generate an m by n complex matrix Q with orthonormal columns,

[zung2r](#) - zung2r - generate an m by n complex matrix Q with orthonormal columns,

[zungbr](#) - zungbr - generate one of the complex unitary matrices Q or P^{**H} determined by CGEBRD when reducing a complex matrix A to bidiagonal form

[zunghr](#) - zunghr - generate a complex unitary matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N, as returned by CGEHRD

[zungl2](#) - zungl2 - generate an m-by-n complex matrix Q with orthonormal rows,

[zunglq](#) - zunglq - generate an M-by-N complex matrix Q with orthonormal rows,

[zungql](#) - zungql - generate an M-by-N complex matrix Q with orthonormal columns,

[zungqr](#) - zungqr - generate an M-by-N complex matrix Q with orthonormal columns,

[zungr2](#) - zungr2 - generate an m by n complex matrix Q with orthonormal rows,

[zungrq](#) - zungrq - generate an M-by-N complex matrix Q with orthonormal rows,

[zungtr](#) - zungtr - generate a complex unitary matrix Q which is defined as the product of n-1 elementary reflectors of order N, as returned by CHETRD

[zunmbr](#) - zunmbr - VECT = 'Q', ZUNMBR overwrites the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[zunmhr](#) - zunmhr - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[zunml2](#) - zunml2 - overwrite the general complex m-by-n matrix C with $Q * C$ if SIDE = 'L' and TRANS = 'N', or $Q^{*} * C$ if SIDE = 'L' and TRANS = 'C', or $C * Q$ if SIDE = 'R' and TRANS = 'N', or $C * Q^{*}$ if SIDE = 'R' and TRANS = 'C',

[zunmlq](#) - zunmlq - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[zunmqi](#) - zunmqi - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[zunmqr](#) - zunmqr - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[zunmr2](#) - zunmr2 - overwrite the general complex m-by-n matrix C with $Q * C$ if SIDE = 'L' and TRANS = 'N', or $Q^* C$ if SIDE = 'L' and TRANS = 'C', or $C * Q$ if SIDE = 'R' and TRANS = 'N', or $C * Q^*$ if SIDE = 'R' and TRANS = 'C',

[zunmrq](#) - zunmrq - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[zunmrz](#) - zunmrz - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[zunmtr](#) - zunmtr - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[zupgtr](#) - zupgtr - generate a complex unitary matrix Q which is defined as the product of n-1 elementary reflectors H(i) of order n, as returned by CHPTRD using packed storage

[zupmtr](#) - zupmtr - overwrite the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

[zvbrmm](#) - zvbrmm - variable block sparse row format matrix-matrix multiply

[zvbrsm](#) - zvbrsm - variable block sparse row format triangular solve

[zvmul](#) - zvmul - compute the scaled product of complex vectors

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NAME

available_threads - returns information about current thread usage

SYNOPSIS

```
SUBROUTINE AVAILABLE_THREADS(TOTAL, USING)
```

```
INTEGER TOTAL, USING
```

```
SUBROUTINE AVAILABLE_THREADS_64(TOTAL, USING)
```

```
INTEGER*8 TOTAL, USING
```

F95 INTERFACE

```
SUBROUTINE AVAILABLE_THREADS(TOTAL, USING)
```

```
INTEGER :: TOTAL, USING
```

```
SUBROUTINE AVAILABLE_THREADS_64(TOTAL, USING)
```

```
INTEGER(8) :: TOTAL, USING
```

C INTERFACE

```
#include <sunperf.h>
```

```
void available_threads(int *total, int *using);
```

```
void available_threads_64(long *total, long *using);
```

PURPOSE

AVAILABLE_THREADS calls library routine OMP_GET_MAX_THREADS to obtain the maximum value that can be returned by calls to OMP_GET_NUM_THREADS. This value is stored in TOTAL. If OMP_SET_NUM_THREADS is used to changed the number of threads, subsequent calls to AVAILABLE_THREADS, whether calling from a serial region or parallel region, will return

the new value in TOTAL. Also, in a parallel environment, if `available_threads` is called from a serial region of the master thread, it returns the number of threads available for execution (determined by function `OMP_GET_NUM_THREADS`) in argument USING. Else, if it is called from a thread in the team executing the parallel region it returns a 1 in USING. For more information on `OMP_GET_MAX_THREADS`, `OMP_GET_NUM_THREADS`, and `OMP_SET_NUM_THREADS`, see the OpenMP Fortran Application Program Interface document at <http://www.openmp.org>.

ARGUMENTS

TOTAL (output)

Maximum value that can be returned by calls to `USING_THREADS`

USING (output)

If `AVAILABLE_THREADS` is called from a parallel region, `USING = 1`. If `AVAILABLE_THREADS` is called from a serial region, `USING` contains the number of threads available for execution in parallel.

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NAME

blas_dpermute - permutes a real (double precision) array in terms of the permutation vector P, output by dsortv

SYNOPSIS

```
SUBROUTINE BLAS_DPERMUTE (N, P, INCP, X, INCX)
```

```
INTEGER N  
INTEGER P(*)  
INTEGER INCP  
REAL*8 X(*)  
INTEGER INCX
```

```
SUBROUTINE BLAS_DPERMUTE_64 (N, P, INCP, X, INCX)
```

```
INTEGER*8 N  
INTEGER*8 P(*)  
INTEGER*8 INCP  
REAL*8 X(*)  
INTEGER*8 INCX
```

F95 INTERFACE

```
SUBROUTINE PERMUTE (X, P)
```

```
USE SUNPERF
```

```
SUBROUTINE PERMUTE_64 (X, P)
```

```
USE SUNPERF
```

ARGUMENTS

N (input) INTEGER, the number of elements to be permuted in X
If $N \leq 1$, the subroutine returns without trying to permute X.

P (input) INTEGER((N-1)*|INCP|+1), the permutation (index) vector defined follows the same conventions as that for DTYPE SORTV. It records the details of

the interchanges of the elements of X during sorting. That is $X = P*X$. In current implementation, P contains the index of sorted X.

INCP (input) INTEGER, increment for P
INCP must not be zero. INCP could be negative. If $INCP < 0$, the permutation is applied in the opposite direction. That is
If $INCP > 0$,
if $INCP > 0$,
sorted $X((i-1)*INCP+1) = X(P((i-1)*INCP+1))$,
if $INCP < 0$,
sorted $X((N-i)*|INCP|+1) = X(P((i-1)*INCP+1))$;
If $INCP < 0$,
if $INCP > 0$,
sorted $X((i-1)*INCP+1) = X(P((N-i)*|INCP|+1))$.
if $INCP < 0$,
sorted $X((N-i)*|INCP|+1)$
= $X(P((N-i)*|INCP|+1))$.

X (input/output) REAL*8(KIND)((N-1)*|INCP|+1), the array to be permuted. Minimum size $(N-1)*|INCP|+1$ is required

INCP (input) INTEGER, increment for X
INCP must not be zero. INCP could be negative. If $INCP < 0$, X will be permuted in a reverse way (see the description for INCP above).

SEE ALSO

blas_dsortv(3P), blas_dsort(3P)

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NAME

blas_dsort - sorts a real (double precision) vector X in increasing or decreasing order using quick sort algorithm

SYNOPSIS

```
SUBROUTINE BLAS_DSORT (SORT, N, X, INCX)
```

```
INTEGER SORT  
INTEGER N  
REAL*8 X(*)  
INTEGER INCX
```

```
SUBROUTINE BLAS_DSORT_64 (SORT, N, X, INCX)
```

```
INTEGER*8 SORT  
INTEGER*8 N  
REAL*8 X(*)  
INTEGER*8 INCX
```

F95 INTERFACE

```
SUBROUTINE SORT (X [, SORT])
```

```
USE SUNPERF
```

```
SUBROUTINE SORT_64 (X [, SORT])
```

```
USE SUNPERF
```

The functionality of SORT is covered by SORTV

ARGUMENTS

SORT (input) INTEGER, indicating sort directions
SORT = 0, descending
SORT = 1, ascending
SORT = other value, error
SORT is default to 1 for F95 INTERFACE

N (input) INTEGER, the number of elements to be sorted in X

If $N \leq 1$, the subroutine returns without trying to sort X .

X (input/output) REAL*8($(N-1)*|INCX|+1$), the array to be sorted
Minimum size $(N-1)*|INCX|+1$ is required

$INCX$ (input) INTEGER, increment for X
 $INCX$ must not be zero. $INCX$ could be negative. If $INCX < 0$, change the sorting direction defined by $SORT$. That is
If $SORT = 0$, let $SORT = 1$, $INCX = |INCX|$;
If $SORT = 1$, let $SORT = 0$, $INCX = |INCX|$.

SEE ALSO

blas_dsortv(3P), blas_dpermute(3P)

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NAME

blas_dsortv - sorts a real (double precision) vector X in increasing or decreasing order using quick sort algorithm and overwrite P with the permutation vector

SYNOPSIS

```
SUBROUTINE BLAS_DSORTV (SORT, N, X, INCX, P, INCP)
```

```
INTEGER SORT  
INTEGER N  
REAL*8 X(*)  
INTEGER INCX  
INTEGER P(*)  
INTEGER INCP
```

```
SUBROUTINE BLAS_DSORTV_64 (SORT, N, X, INCX, P, INCP)
```

```
INTEGER*8 SORT  
INTEGER*8 N  
REAL*8 X(*)  
INTEGER*8 INCX  
INTEGER*8 P(*)  
INTEGER*8 INCP
```

F95 INTERFACE

```
SUBROUTINE SORTV (X [, SORT] [, P])
```

```
USE SUNPERF
```

```
SUBROUTINE SORTV_64 (X [, SORT] [, P])
```

```
USE SUNPERF
```

SORTV covers the functionality of SORT

ARGUMENTS

SORT (input) INTEGER, indicating sort directions
SORT = 0, descending

SORT = 1, ascending
SORT = other value, error
SORT is default to 1 for F95 INTERFACE

N (input) INTEGER, the number of elements to be sorted in X
If $N \leq 1$, the subroutine returns without trying to sort X.

X (input/output) REAL*8((N-1)*|INCX|+1), the array to be sorted
Minimum size (N-1)*|INCX|+1 is required

INCX (input) INTEGER, increment for X
INCX must not be zero. INCX could be negative. If $INCX < 0$, change the sorting direction defined by SORT. That is
If SORT = 0, let SORT = 1, $INCX = |INCX|$;
If SORT = 1, let SORT = 0, $INCX = |INCX|$.

P (output) INTEGER((N-1)*|INCP|+1), the permutation (index) vector recording the details of the interchanges of the elements of X during sorting. That is $X = P*X$. In this implementation, P contains the index of sorted X.

INCP (input) INTEGER, increment for P
INCP must not be zero. INCP could be negative. If $INCP < 0$, store P(i) in reverse order. That is
If $INCP > 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((i-1)*INCP+1))$,
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1) = X(P((i-1)*INCP+1))$;
If $INCP < 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((N-i)*|INCP|+1))$,
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1) = X(P((N-i)*|INCP|+1))$.

SEE ALSO

blas_dsort(3P), blas_dpermute(3P)

Contents

- [NAME](#)
- [SYNOPSIS](#)
 - [F95 INTERFACE](#)
- [ARGUMENTS](#)
- [SEE ALSO](#)

NAME

blas_ipermute - permutes an integer array in terms of the permutation vector P, output by dsortv

SYNOPSIS

```
SUBROUTINE BLAS_IPERMUTE (N, P, INCP, X, INCX)
```

```
INTEGER N  
INTEGER P(*)  
INTEGER INCP  
INTEGER X(*)  
INTEGER INCX
```

```
SUBROUTINE BLAS_IPERMUTE_64 (N, P, INCP, X, INCX)
```

```
INTEGER*8 N  
INTEGER*8 P(*)  
INTEGER*8 INCP  
INTEGER*8 X(*)  
INTEGER*8 INCX
```

F95 INTERFACE

```
SUBROUTINE PERMUTE (X, P)
```

```
USE SUNPERF
```

```
SUBROUTINE PERMUTE_64 (X, P)
```

```
USE SUNPERF
```

ARGUMENTS

N (input) INTEGER, the number of elements to be permuted in X
If $N \leq 1$, the subroutine returns without trying to permute X.

P (input) INTEGER((N-1)*|INCP|+1), the permutation (index) vector defined follows the same conventions as that for DTYPE SORTV. It records the details of

the interchanges of the elements of X during sorting. That is $X = P * X$. In current implementation, P contains the index of sorted X.

INCP (input) INTEGER, increment for P
INCP must not be zero. INCP could be negative. If $INCP < 0$, the permutation is applied in the opposite direction. That is
If $INCP > 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((i-1)*INCP+1))$,
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1) = X(P((i-1)*INCP+1))$;
If $INCP < 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((N-i)*|INCP|+1))$.
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1)$
= $X(P((N-i)*|INCP|+1))$.

X (input/output) INTEGER(KIND)((N-1)*|INCX|+1), the array to be permuted. Minimum size $(N-1)*|INCX|+1$ is required

INCX (input) INTEGER, increment for X
INCX must not be zero. INCX could be negative. If $INCX < 0$, X will be permuted in a reverse way (see the description for INCP above).

SEE ALSO

blas_isortv(3P), blas_isort(3P)

Contents

- [NAME](#)
- [SYNOPSIS](#)
 - [F95 INTERFACE](#)
- [ARGUMENTS](#)
- [SEE ALSO](#)

NAME

blas_ismrt - sorts an integer vector X in increasing or decreasing order using quick sort algorithm

SYNOPSIS

```
SUBROUTINE BLAS_ISORT (SORT, N, X, INCX)
```

```
INTEGER SORT  
INTEGER N  
INTEGER X(*)  
INTEGER INCX
```

```
SUBROUTINE BLAS_ISORT_64 (SORT, N, X, INCX)
```

```
INTEGER*8 SORT  
INTEGER*8 N  
INTEGER*8 X(*)  
INTEGER*8 INCX
```

F95 INTERFACE

```
SUBROUTINE SORT (X [, SORT])
```

```
USE SUNPERF
```

```
SUBROUTINE SORT_64 (X [, SORT])
```

```
USE SUNPERF
```

The functionality of SORT is covered by SORTV

ARGUMENTS

SORT (input) INTEGER, indicating sort directions
SORT = 0, descending
SORT = 1, ascending
SORT = other value, error
SORT is default to 1 for F95 INTERFACE

N (input) INTEGER, the number of elements to be sorted in X

If $N \leq 1$, the subroutine returns without trying to sort X.

X (input/output) INTEGER($(N-1)*|INCX|+1$), the array to be sorted
Minimum size $(N-1)*|INCX|+1$ is required

INCX (input) INTEGER, increment for X
INCX must not be zero. INCX could be negative. If $INCX < 0$, change the sorting direction defined by SORT. That is
If SORT = 0, let SORT = 1, $INCX = |INCX|$;
If SORT = 1, let SORT = 0, $INCX = |INCX|$.

SEE ALSO

blas_isortv(3P), blas_ipermute(3P)

Contents

- [NAME](#)
- [SYNOPSIS](#)
 - [F95 INTERFACE](#)
- [ARGUMENTS](#)
- [SEE ALSO](#)

NAME

blas_isortv - sorts a real vector X in increasing or decreasing order using quick sort algorithm and overwrite P with the permutation vector

SYNOPSIS

```
SUBROUTINE BLAS_ISORTV (SORT, N, X, INCX, P, INCP)
```

```
INTEGER SORT  
INTEGER N  
INTEGER X(*)  
INTEGER INCX  
INTEGER P(*)  
INTEGER INCP
```

```
SUBROUTINE BLAS_ISORTV_64 (SORT, N, X, INCX, P, INCP)
```

```
INTEGER*8 SORT  
INTEGER*8 N  
INTEGER*8 X(*)  
INTEGER*8 INCX  
INTEGER*8 P(*)  
INTEGER*8 INCP
```

F95 INTERFACE

```
SUBROUTINE SORTV (X [, SORT] [, P])
```

```
USE SUNPERF
```

```
SUBROUTINE SORTV_64 (X [, SORT] [, P])
```

```
USE SUNPERF
```

SORTV covers the functionality of SORT

ARGUMENTS

SORT (input) INTEGER, indicating sort directions
SORT = 0, descending

SORT = 1, ascending
SORT = other value, error
SORT is default to 1 for F95 INTERFACE

N (input) INTEGER, the number of elements to be sorted in X
If $N \leq 1$, the subroutine returns without trying to sort X.

X (input/output) INTEGER $((N-1)*|INCX|+1)$, the array to be sorted
Minimum size $(N-1)*|INCX|+1$ is required

INCX (input) INTEGER, increment for X
INCX must not be zero. INCX could be negative. If $INCX < 0$, change the sorting direction defined by SORT. That is
If SORT = 0, let SORT = 1, $INCX = |INCX|$;
If SORT = 1, let SORT = 0, $INCX = |INCX|$.

P (output) INTEGER $((N-1)*|INCP|+1)$, the permutation (index) vector recording the details of the interchanges of the elements of X during sorting. That is $X = P*X$. In this implementation, P contains the index of sorted X.

INCP (input) INTEGER, increment for P
INCP must not be zero. INCP could be negative. If $INCP < 0$, store P(i) in reverse order. That is
If $INCP > 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((i-1)*INCP+1))$,
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1) = X(P((i-1)*INCP+1))$;
If $INCP < 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((N-i)*|INCP|+1))$,
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1)$
= $X(P((N-i)*|INCP|+1))$.

SEE ALSO

blas_isort(3P), blas_ipermute(3P)

Contents

- [NAME](#)
- [SYNOPSIS](#)
 - [F95 INTERFACE](#)
- [ARGUMENTS](#)
- [SEE ALSO](#)

NAME

blas_spermute - permutes a real array in terms of the permutation vector P, output by dsortv

SYNOPSIS

```
SUBROUTINE BLAS_SPERMUTE (N, P, INCP, X, INCX)
```

```
INTEGER N  
INTEGER P(*)  
INTEGER INCP  
REAL X(*)  
INTEGER INCX
```

```
SUBROUTINE BLAS_SPERMUTE_64 (N, P, INCP, X, INCX)
```

```
INTEGER*8 N  
INTEGER*8 P(*)  
INTEGER*8 INCP  
REAL X(*)  
INTEGER*8 INCX
```

F95 INTERFACE

```
SUBROUTINE PERMUTE (X, P)
```

```
USE SUNPERF
```

```
SUBROUTINE PERMUTE_64 (X, P)
```

```
USE SUNPERF
```

ARGUMENTS

N (input) INTEGER, the number of elements to be permuted in X
If N <= 1, the subroutine returns without trying to permute X.

P (input) INTEGER((N-1)*|INCP|+1), the permutation (index) vector defined follows the same conventions as that for DTYPE SORTV. It records the details of

the interchanges of the elements of X during sorting. That is $X = P * X$. In current implementation, P contains the index of sorted X.

INCP (input) INTEGER, increment for P
INCP must not be zero. INCP could be negative. If $INCP < 0$, the permutation is applied in the opposite direction. That is
If $INCP > 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((i-1)*INCP+1))$,
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1) = X(P((i-1)*INCP+1))$;
If $INCP < 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((N-i)*|INCP|+1))$.
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1)$
= $X(P((N-i)*|INCP|+1))$.

X (input/output) REAL(KIND)((N-1)*|INCX|+1), the array to be permuted. Minimum size (N-1)*|INCX|+1 is required

INCX (input) INTEGER, increment for X
INCX must not be zero. INCX could be negative. If $INCX < 0$, X will be permuted in a reverse way (see the description for INCP above).

SEE ALSO

blas_ssortv(3P), blas_ssort(3P)

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- [NAME](#)
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NAME

blas_ssort - sorts a real vector X in increasing or decreasing order using quick sort algorithm

SYNOPSIS

```
SUBROUTINE BLAS_SSORT (SORT, N, X, INCX)
```

```
INTEGER SORT  
INTEGER N  
REAL X(*)  
INTEGER INCX
```

```
SUBROUTINE BLAS_SSORT_64 (SORT, N, X, INCX)
```

```
INTEGER*8 SORT  
INTEGER*8 N  
REAL X(*)  
INTEGER*8 INCX
```

F95 INTERFACE

```
SUBROUTINE SORT (X [, SORT])
```

```
USE SUNPERF
```

```
SUBROUTINE SORT_64 (X [, SORT])
```

```
USE SUNPERF
```

The functionality of SORT is covered by SORTV

ARGUMENTS

SORT (input) INTEGER, indicating sort directions
SORT = 0, descending
SORT = 1, ascending
SORT = other value, error
SORT is default to 1 for F95 INTERFACE

N (input) INTEGER, the number of elements to be sorted in X

If $N \leq 1$, the subroutine returns without trying to sort X.

X (input/output) REAL($(N-1)*|INCX|+1$), the array to be sorted
Minimum size $(N-1)*|INCX|+1$ is required

INCX (input) INTEGER, increment for X
INCX must not be zero. INCX could be negative. If $INCX < 0$, change the sorting direction defined by SORT. That is
If SORT = 0, let SORT = 1, $INCX = |INCX|$;
If SORT = 1, let SORT = 0, $INCX = |INCX|$.

SEE ALSO

blas_ssortv(3P), blas_spermute(3P)

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- [NAME](#)
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NAME

blas_ssortv - sorts a real vector X in increasing or decreasing order using quick sort algorithm and overwrite P with the permutation vector

SYNOPSIS

```
SUBROUTINE BLAS_SSORTV (SORT, N, X, INCX, P, INCP)
```

```
INTEGER SORT  
INTEGER N  
REAL X(*)  
INTEGER INCX  
INTEGER P(*)  
INTEGER INCP
```

```
SUBROUTINE BLAS_SSORTV_64 (SORT, N, X, INCX, P, INCP)
```

```
INTEGER*8 SORT  
INTEGER*8 N  
REAL X(*)  
INTEGER*8 INCX  
INTEGER*8 P(*)  
INTEGER*8 INCP
```

F95 INTERFACE

```
SUBROUTINE SORTV (X [, SORT] [, P])
```

```
USE SUNPERF
```

```
SUBROUTINE SORTV_64 (X [, SORT] [, P])
```

```
USE SUNPERF
```

SORTV covers the functionality of SORT

ARGUMENTS

SORT (input) INTEGER, indicating sort directions
SORT = 0, descending

SORT = 1, ascending
SORT = other value, error
SORT is default to 1 for F95 INTERFACE

N (input) INTEGER, the number of elements to be sorted in X
If $N \leq 1$, the subroutine returns without trying to sort X.

X (input/output) REAL($(N-1)*|INCX|+1$), the array to be sorted
Minimum size $(N-1)*|INCX|+1$ is required

INCX (input) INTEGER, increment for X
INCX must not be zero. INCX could be negative. If $INCX < 0$, change the sorting direction defined by SORT. That is
If $SORT = 0$, let $SORT = 1$, $INCX = |INCX|$;
If $SORT = 1$, let $SORT = 0$, $INCX = |INCX|$.

P (output) INTEGER($(N-1)*|INCP|+1$), the permutation (index) vector recording the details of the interchanges of the elements of X during sorting. That is $X = P*X$. In this implementation, P contains the index of sorted X.

INCP (input) INTEGER, increment for P
INCP must not be zero. INCP could be negative. If $INCP < 0$, store P(i) in reverse order. That is
If $INCP > 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((i-1)*INCP+1))$,
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1) = X(P((i-1)*INCP+1))$;
If $INCP < 0$,
if $INCX > 0$,
sorted $X((i-1)*INCX+1) = X(P((N-i)*|INCP|+1))$,
if $INCX < 0$,
sorted $X((N-i)*|INCX|+1) = X(P((N-i)*|INCP|+1))$.

SEE ALSO

blas_ssort(3P), blas_spermute(3P)

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 - [F95 INTERFACE](#)
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NAME

caxpy - compute $y := \alpha * x + y$

SYNOPSIS

```
SUBROUTINE CAXPY(N, ALPHA, X, INCX, Y, INCY)
```

```
COMPLEX ALPHA  
COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE CAXPY_64(N, ALPHA, X, INCX, Y, INCY)
```

```
COMPLEX ALPHA  
COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE AXPY([N], ALPHA, X, [INCX], Y, [INCY])
```

```
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE AXPY_64([N], ALPHA, X, [INCX], Y, [INCY])
```

```
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void caxpy(int n, complex *alpha, complex *x, int incx, complex *y, int incy);
```

```
void caxpy_64(long n, complex *alpha, complex *x, long incx, complex *y, long incy);
```

PURPOSE

caxpy compute $y := \alpha * x + y$ where alpha is a scalar and x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

array of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input/output)

array of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$. On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

Contents

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NAME

caxpyi - Compute $y := \alpha * x + y$

SYNOPSIS

```
SUBROUTINE CAXPYI(NZ, A, X, INDX, Y)
```

```
COMPLEX A  
COMPLEX X(*), Y(*)  
INTEGER NZ  
INTEGER INDX(*)
```

```
SUBROUTINE CAXPYI_64(NZ, A, X, INDX, Y)
```

```
COMPLEX A  
COMPLEX X(*), Y(*)  
INTEGER*8 NZ  
INTEGER*8 INDX(*)
```

```
F95 INTERFACE
```

```
SUBROUTINE AXPYI([NZ], [A], X, INDX, Y)
```

```
COMPLEX :: A  
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER :: NZ  
INTEGER, DIMENSION(:) :: INDX
```

```
SUBROUTINE AXPYI_64([NZ], [A], X, INDX, Y)
```

```
COMPLEX :: A  
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER(8) :: NZ  
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

CAXPYI Compute $y := \alpha * x + y$ where α is a scalar, x is a sparse vector, and y is a vector in full storage form

```
do i = 1, n  
  y(indx(i)) = alpha * x(i) + y(indx(i))
```

enddo

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.

Unchanged on exit.

A (input)

On entry, A(LPHA) specifies the scaling value.

Unchanged on exit. A is defaulted to (1.0E0, 0.0E0)

for F95 INTERFACE.

X (input)

Vector containing the values of the compressed form.

Unchanged on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed

form. It is assumed that the elements in INDX are

distinct and greater than zero. Unchanged on exit.

Y (output)

Vector on input which contains the vector Y in full

storage form. On exit, only the elements

corresponding to the indices in INDX have been

modified.

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NAME

cbcomm - block coordinate matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CBCOMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BJNDX, BNNZ, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), BNNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BJNDX(BNNZ)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CBCOMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BJNDX, BNNZ, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), BNNZ, LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BJNDX(BNNZ)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BCOMM(TRANSA,MB,[N],KB,ALPHA,DESCRA,VAL,BINDX, BJNDX,  
* BNNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, N, KB, BNNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BJNDX  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BCOMM_64(TRANSA,MB,[N],KB,ALPHA,DESCRA,VAL,BINDX, BJNDX,  
* BNNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, N, KB, BNNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BJNDX  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void cbcomm(int transa, int mb, int n, int kb, complex
*alpha, int *descra, complex *val, int *bindx, int *bjndx,
int bnnz, int lb, complex *b, int ldb, complex *beta,
complex *c, int ldc);
void cbcomm_64(long transa, long mb, long n, long kb,
complex *alpha, long *descra, complex *val, long *bindx,
long *bjndx, long bnnz, long lb, complex *b, long ldb,
complex *beta, complex *c, long ldc);
```

DESCRIPTION

cbcomm performs one of the matrix-matrix operations

$$C \leftarrow \text{alpha op}(A) B + \text{beta } C$$

where $\text{op}(A)$ is one of

$\text{op}(A) = A$ or $\text{op}(A) = A'$ or $\text{op}(A) = \text{conjg}(A')$
(' indicates matrix transpose),

A is an (mb*lb) by (kb*lb) sparse matrix represented in the block coordinate format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, integer MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, integer KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')

```

5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array of length
                 LB*LB*BNNZ consisting of the non-zero block
                 entries of A, in any order. Each block
                 is stored in standard column-major form.
                 Unchanged on exit.

BINDX(input)    On entry, BINDX is an integer array of length BNNZ
                 consisting of the block row indices of the non-zero
                 block entries of A. Unchanged on exit.

BJNDX(input)    On entry, BJNDX is an integer array of length BNNZ
                 consisting of the block column indices of the non-zero
                 block entries of A. Unchanged on exit.

BNNZ (input)    On entry, integer BNNZ specifies the number of nonzero
                 block entries in A. Unchanged on exit.

LB (input)      On entry, integer LB specifies the dimension of dense
                 blocks composing A. Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading kb*lb by n
                 part of the array B must contain the matrix B, otherwise
                 the leading mb*lb by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading mb*lb by n
                 part of the array C must contain the matrix C, otherwise
                 the leading kb*lb by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta * C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

The all sparse blas matrix-matrix multiply routines for block entry formats are designed so that if *DESCRA*(1) > 0, the routines check the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use just one sparse matrix representation of a general block matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A .

Assume that there is the sparse matrix representation of a general complex matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of *DESCRA* and the result matrix for the sparse representation of A is

<i>DESCRA</i> (1)	<i>DESCRA</i> (2)	<i>DESCRA</i> (3)	RESULT
1	1	0	$\alpha * \text{op}(L+D+L') * B + \beta * C$
1	1	1	$\alpha * \text{op}(L+I+L') * B + \beta * C$
1	2	0	$\alpha * \text{op}(U'+D+U) * B + \beta * C$
1	2	1	$\alpha * \text{op}(U'+I+U) * B + \beta * C$
2	1	0	$\alpha * \text{op}(L+D+\text{conjg}(L')) * B + \beta * C$

2	1	1	$\alpha * \text{op}(L+I+\text{conjg}(L')) * B + \beta * C$
2	2	0	$\alpha * \text{op}(\text{conjg}(U') + D + U) * B + \beta * C$
2	2	1	$\alpha * \text{op}(\text{conjg}(U') + I + U) * B + \beta * C$
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$
4	1	0 or 1	$\alpha * \text{op}(L+D-L') * B + \beta * C$
4	2	0 or 1	$\alpha * \text{op}(U+D-U') * B + \beta * C$
5	1 or 2	0	$\alpha * \text{op}(D) * B + \beta * C$
5	1 or 2	1	$\alpha * B + \beta * C$
6	1	0 or 1	$\alpha * \text{op}(L+D-\text{conjg}(L')) * B + \beta * C$
6	2	0 or 1	$\alpha * \text{op}(U+D-\text{conjg}(U')) * B + \beta * C$

Remarks to the table:

1. the value of `DESCRA(3)` is simply ignored , if `DESCRA(1)=4` or `6` but the diagonal blocks which are referenced in the sparse matrix representation are used;

2. the diagonal blocks which are referenced in the sparse matrix representation are not used, if `DESCRA(3)=1` and `DESCRA(1)` is one of 1, 2, 3 or 5;

3. if `DESCRA(3)` is not 1 and `DESCRA(1)` is one of 1,2, 4 or 6, the type of D should correspond to the chosen value of `DESCRA(1)` .

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NAME

cbdimm - block diagonal format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CBDIMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), BLDA, NBDIAG, LB,  
*                LDB, LDC, LWORK  
INTEGER          IBDIAG(NBDIAG)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BLDA*NBDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE CBDIMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), BLDA, NBDIAG, LB,  
*                LDB, LDC, LWORK  
INTEGER*8        IBDIAG(NBDIAG)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BLDA*NBDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BDIMM(TRANSA,MB, [N], KB, ALPHA, DESCRA, VAL, BLDA,  
*  IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, BLDA, NBDIAG, LB  
INTEGER, DIMENSION(:) ::  DESCRA, IBDIAG  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C  
  
SUBROUTINE BDIMM_64(TRANSA,MB, [N], KB, ALPHA, DESCRA, VAL, BLDA,  
*  IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, BLDA, NBDIAG, LB  
INTEGER*8, DIMENSION(:) ::  DESCRA, IBDIAG  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void cbdimm (int transa, int mb, int n, int kb, complex
*alpha,
  int *descra, complex *val, int blda, int *ibdiag, int
nbdia, int lb, complex *b, int ldb, complex *beta, complex
*c, int ldc);
void cbdimm_64(long transa, long mb, long n, long kb,
  complex *alpha, long *descra, complex *val, long blda,
  long *ibdiag, long nbdia, long lb, complex *b, long ldb,
  complex *beta, complex *c, long ldc)
```

DESCRIPTION

cbdimm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an (mb*lb) by (kb*lb) sparse matrix represented in the block diagonal format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal

```

        6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
        1 : lower
        2 : upper
DESCRA(3) main block diagonal type
        0 : non-unit
        1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
        0 : C/C++ compatible
        1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
        0 : unknown
        1 : no repeated indices

VAL(input)      On entry, two-dimensional LB*LB*BLDA-by-NBDIAG scalar array
                  consisting of the NBDIAG nonzero block diagonal in
                  any order. Each dense block is stored in standard
                  column-major form. Unchanged on exit.

BLDA(input)     On entry, BLDA*LB*LB specifies the leading block dimension
                  of VAL(). Unchanged on exit.

IBDIAG(input)  On entry, integer array of length NBDIAG consisting of the
                  corresponding diagonal offsets of the non-zero
                  block diagonals of A in VAL. Lower triangular
                  block diagonals have negative offsets, the main
                  block diagonal has offset 0, and upper triangular
                  block diagonals have positive offset. Unchanged on exit.

NBDIAG(input)  On entry, NBDIAG specifies the number of non-zero block
                  diagonals in A. Unchanged on exit.

LB (input)     On entry, LB specifies the dimension of dense blocks
                  composing A. Unchanged on exit.

B (input)      Array of DIMENSION ( LDB, N ).
                  Before entry with TRANSA = 0, the leading kb*lb by n
                  part of the array B must contain the matrix B, otherwise
                  the leading mb*lb by n part of the array B must contain the
                  matrix B. Unchanged on exit.

LDB (input)    On entry, LDB specifies the first dimension of B as declared
                  in the calling (sub) program. Unchanged on exit.

BETA (input)   On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION ( LDC, N ).
                  Before entry with TRANSA = 0, the leading mb*lb by n
                  part of the array C must contain the matrix C, otherwise
                  the leading kb*lb by n part of the array C must contain the
                  matrix C. On exit, the array C is overwritten by the matrix
                  ( alpha*op( A ) * B + beta * C ).

LDC (input)    On entry, LDC specifies the first dimension of C as declared
                  in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

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NAME

cbdism - block diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE CBDISM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), BLDA, NBDIAG, LB,  
*                LDB, LDC, LWORK  
INTEGER          IBDIAG(NBDIAG)  
COMPLEX          ALPHA, BETA  
COMPLEX          DV(MB*LB*LB), VAL(LB*LB*BLDA, NBDIAG), B(LDB,*), C(LDC,*),  
*                WORK(LWORK)
```

```
SUBROUTINE CBDISM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), BLDA, NBDIAG, LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        IBDIAG(NBDIAG)  
COMPLEX          ALPHA, BETA  
COMPLEX          DV(MB*LB*LB), VAL(LB*LB*BLDA, NBDIAG), B(LDB,*), C(LDC,*),  
*                   WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BDISM( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BLDA,  
* IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, N, UNITD, BLDA, NBDIAG, LB  
INTEGER, DIMENSION(:) :: DESCRA, IBDIAG  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL, DV  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BDISM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BLDA,  
* IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, N, UNITD, BLDA, NBDIAG, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, IBDIAG  
COMPLEX          ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cbdism (int transa, int mb, int n, int unitd, complex
*dv, complex *alpha, int *descra, complex *val, int blda,
int *ibdiag, int nbdiag, int lb, complex *b, int ldb,
complex *beta, complex *c, int ldc);
void cbdism_64(long transa, long mb, long n, long unitd,
complex *dv, complex *alpha, long *descra, complex *val,
long blda, long *ibdiag, long nbdiag, long lb, complex *b,
long ldb, complex *beta, complex *c, long ldc)
```

DESCRIPTION

cbdism performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose)
```

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) Unchanged on exit.
DV(input)	On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-NBDIAG array consisting of the NBDIAG non-zero block diagonal. Each dense block is stored in standard column-major form. Unchanged on exit.

BLDA(input) On entry, BLDA*LB*LB specifies the leading block dimension of VAL(). Unchanged on exit.

IBDIAG(input) On entry, IBDIAG is an integer array of length NBDIAG consisting of corresponding diagonal offsets of the non-zero block diagonals of A in VAL. Lower triangular block diagonals have negative offsets, the main block diagonal has offset 0, and upper triangular block diagonals have positive offset. Elements of IBDIAG MUST be sorted in increasing order. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block diagonal representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If *DESCRA*(3)=2 , diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine.

WORK(1)=0 on return if the factorization for all diagonal

blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix `A` for solving triangular systems with the upper or lower block triangle of `A`. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix `A` decomposed in the form

$$A = L + D + U$$

where `L` is the strictly block lower triangle of `A`, `U` is the strictly block upper triangle of `A`, `D` is the block diagonal matrix. Let's `I` denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of `A` is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

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NAME

cbdsqr - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B.

SYNOPSIS

```
SUBROUTINE CBDSQR(UPLO, N, NCVT, NRU, NCC, D, E, VT, LDVT, U, LDU, C,
                 LDC, WORK, INFO)
```

```
CHARACTER * 1 UPLO
COMPLEX VT(LDVT,*), U(LDU,*), C(LDC,*)
INTEGER N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL D(*), E(*), WORK(*)
```

```
SUBROUTINE CBDSQR_64(UPLO, N, NCVT, NRU, NCC, D, E, VT, LDVT, U, LDU,
                    C, LDC, WORK, INFO)
```

```
CHARACTER * 1 UPLO
COMPLEX VT(LDVT,*), U(LDU,*), C(LDC,*)
INTEGER*8 N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL D(*), E(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE BDSQR(UPLO, [N], [NCVT], [NRU], [NCC], D, E, VT, [LDVT],
                U, [LDU], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX, DIMENSION(:,*) :: VT, U, C
INTEGER :: N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL, DIMENSION(:) :: D, E, WORK
```

```
SUBROUTINE BDSQR_64(UPLO, [N], [NCVT], [NRU], [NCC], D, E, VT, [LDVT],
                   U, [LDU], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX, DIMENSION(:,*) :: VT, U, C
INTEGER(8) :: N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL, DIMENSION(:) :: D, E, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cbdsqr(char uplo, int n, int ncv, int nru, int ncc,
            float *d, float *e, complex *vt, int ldvt, complex
            *u, int ldu, complex *c, int ldc, int *info);
```

```
void cbdsqr_64(char uplo, long n, long ncv, long nru, long
               ncc, float *d, float *e, complex *vt, long ldvt,
               complex *u, long ldu, complex *c, long ldc, long
               *info);
```

PURPOSE

cbdsqr computes the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B: $B = Q * S * P'$ (P' denotes the transpose of P), where S is a diagonal matrix with non-negative diagonal elements (the singular values of B), and Q and P are orthogonal matrices.

The routine computes S, and optionally computes $U * Q$, $P' * VT$, or $Q' * C$, for given complex input matrices U, VT, and C.

See "Computing Small Singular Values of Bidiagonal Matrices With Guaranteed High Relative Accuracy," by J. Demmel and W. Kahan, LAPACK Working Note #3 (or SIAM J. Sci. Statist. Comput. vol. 11, no. 5, pp. 873-912, Sept 1990) and "Accurate singular values and differential qd algorithms," by B. Parlett and V. Fernando, Technical Report CPAM-554, Mathematics Department, University of California at Berkeley, July 1992 for a detailed description of the algorithm.

ARGUMENTS

UPLO (input)

= 'U': B is upper bidiagonal;
 = 'L': B is lower bidiagonal.

N (input) The order of the matrix B. $N \geq 0$.

NCVT (input)

The number of columns of the matrix VT. $NCVT \geq 0$.

NRU (input)

The number of rows of the matrix U. $NRU \geq 0$.

NCC (input)

The number of columns of the matrix C. $NCC \geq 0$.

D (input/output)

On entry, the n diagonal elements of the bidiagonal matrix B. On exit, if INFO=0, the singular values of B in decreasing order.

E (input/output)

On entry, the elements of E contain the offdiagonal elements of the bidiagonal matrix whose SVD is desired. On normal exit (INFO = 0), E is des-

troyed. If the algorithm does not converge (INFO > 0), D and E will contain the diagonal and super-diagonal elements of a bidiagonal matrix orthogonally equivalent to the one given as input. E(N) is used for workspace.

VT (input/output)

On entry, an N-by-NCVT matrix VT. On exit, VT is overwritten by $P' * VT$. VT is not referenced if NCVT = 0.

LDVT (input)

The leading dimension of the array VT. LDVT \geq max(1,N) if NCVT > 0; LDVT \geq 1 if NCVT = 0.

U (input/output)

On entry, an NRU-by-N matrix U. On exit, U is overwritten by $U * Q$. U is not referenced if NRU = 0.

LDU (input)

The leading dimension of the array U. LDU \geq max(1,NRU).

C (input/output)

On entry, an N-by-NCC matrix C. On exit, C is overwritten by $Q' * C$. C is not referenced if NCC = 0.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,N) if NCC > 0; LDC \geq 1 if NCC = 0.

WORK (workspace)

dimension (4*N)

INFO (output)

= 0: successful exit
< 0: If INFO = -i, the i-th argument had an illegal value
> 0: the algorithm did not converge; D and E contain the elements of a bidiagonal matrix which is orthogonally similar to the input matrix B; if INFO = i, i elements of E have not converged to zero.

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NAME

cbelmm - block Ellpack format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CBELMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BLDA, MAXBNZ, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), BLDA, MAXBNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BLDA,MAXBNZ)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CBELMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BLDA, MAXBNZ, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), BLDA, MAXBNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER*8        BINDX(BLDA,MAXBNZ)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BELMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                BLDA, MAXBNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, BLDA, MAXBNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BELMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BLDA, MAXBNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, BLDA, MAXBNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void cbelmm(int transa, int mb, int n, int kb,
  complex *alpha, int *descra, complex *val,
  int *bindx, int blda, int maxbnz, int lb, complex *b,
  int ldb, complex *beta, complex *c, int ldc);
void cbelmm_64(long transa, long mb, long n, long kb,
  complex *alpha, long *descra, complex *val, long *bindx,
  long blda, long maxbnz, long lb, complex *b, long ldb,
  complex *beta, complex *c, long ldc);
```

DESCRIPTION

cbelmm performs one of the matrix-matrix operations

$$C \leftarrow \text{alpha op}(A) B + \text{beta } C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in the block Ellpack format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input) TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows:
 0 : operate with matrix
 1 : operate with transpose matrix
 2 : operate with the conjugate transpose of matrix.
 2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator

1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-MAXBNZ array consisting of the non-zero blocks, stored column-major within each dense block. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer two-dimensional BLDA-MAXBNZ array such BINDX(i,:) consists of the block column indices of the nonzero blocks in block row i, padded by the integer value i if the number of nonzero blocks is less than MAXBNZ. Unchanged on exit.

BLDA(input) On entry, BLDA specifies the leading dimension of BINDX(:,:). Unchanged on exit.

MAXBNZ (input) On entry, NBDIAG specifies the max number of nonzeros blocks per row. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANS = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANS = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \text{beta} * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

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NAME

cbelsm - block Ellpack format triangular solve

SYNOPSIS

```
SUBROUTINE CBELSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, BINDX, BLDA, MAXBNZ, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, MB, N, UNITD, DESCRA(5), BLDA, MAXBNZ, LB,  
* LDB, LDC, LWORK  
INTEGER BINDX(BLDA,MAXBNZ)  
COMPLEX ALPHA, BETA  
COMPLEX DV(MB*LB*LB), VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*),  
* WORK(LWORK)
```

```
SUBROUTINE CBELSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, BINDX, BLDA, MAXBNZ, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, MB, N, UNITD, DESCRA(5), BLDA, MAXBNZ, LB,  
* LDB, LDC, LWORK  
INTEGER*8 BINDX(BLDA,MAXBNZ)  
COMPLEX ALPHA, BETA  
COMPLEX DV(MB*LB*LB), VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*),  
* WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BELSM( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
* BLDA, MAXBNZ, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, MB, UNITD, BLDA, MAXBNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX  
COMPLEX ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL, DV  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BELSM_64( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
* BLDA, MAXBNZ, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, MB, UNITD, BLDA, MAXBNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX  
COMPLEX ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cbelsm(int transa, int mb, int n, int unitd,
  complex *dv, complex *alpha, int *descra, complex *val,
  int *bindx, int blda, int maxbnz, int lb, complex *b,
  int ldb, complex *beta, complex *c, int ldc);
void cbelsm_64(long transa, long mb, long n, long unitd,
  complex *dv, complex *alpha, long *descra, complex *val,
  long *bindx, long blda, long maxbnz, long lb, complex *b,
  long ldb, complex *beta, complex *c, long ldc);
```

DESCRIPTION

cbelsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block ellpack format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input) Integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:

- 0 : operate with matrix
- 1 : operate with transpose matrix
- 2 : operate with the conjugate transpose of matrix.
- 2 is equivalent to 1 if matrix is real.

Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:

- 1 : Identity matrix (argument DV[] is ignored)
- 2 : Scale on left (row scaling)
- 3 : Scale on right (column scaling)

Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-MAXBNZ array consisting of the non-zero blocks, stored column-major within each dense block. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer two-dimensional BLDA-MAXBNZ array such BINDX(i,:) consists of the block column indices of the nonzero blocks in block row i, padded by the integer value i if the number of nonzero blocks is less than MAXBNZ. The block column indices MUST be sorted in increasing order for each block row. Unchanged on exit.

BLDA(input) On entry, BLDA specifies the leading dimension of BINDX(:,:). Unchanged on exit.

MAXBNZ (input) On entry, MAXBNZ specifies the max number of nonzeros blocks per row. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK \geq MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block ellpack representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If *DESCRA*(3)=2 , diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine.

`WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix `A` for solving triangular systems with the upper or lower block triangle of `A`. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix `A` decomposed in the form

$$A = L + D + U$$

where `L` is the strictly block lower triangle of `A`, `U` is the strictly block upper triangle of `A`, `D` is the block diagonal matrix. Let's `I` denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of `A` is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

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NAME

cbscmm - block sparse column matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CBSCMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(KB), BPNTRE(KB)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CBSCMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LB,  
*               LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(KB), BPNTRE(KB)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where BNNZ = BPNTRE(KB)-BPNTRB(1).

F95 INTERFACE

```
SUBROUTINE BSCMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*               BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSCMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
COMPLEX          ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: VAL
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cbscmm(int transa, int mb, int n, int kb,
  complex *alpha, int *descra, complex *val,
  int *bindx, int *bpntrb, int *bpntre, int lb, complex *b,
  int ldb, complex *beta, complex* c, int ldc);
void cbscmm_64(long transa, long mb, long n, long kb,
  complex *alpha, long *descra, complex *val, long *bindx,
  long *bpntrb, long *bpntre, long lb, complex *b, long ldb,
  complex *beta, complex *c, long ldc);
```

DESCRIPTION

cbscmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in the block sparse column format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
KB(input)	On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular 4 : Skew(Anti)-Symmetric (A=-A') 5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ consisting of the non-zero block entries stored column-major within each dense block where BNNZ = BPNTRE(KB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block row indices of the block entries of A where BNNZ = BPNTRE(KB)-BPNTRB(1). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length KB such that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the J-th block column of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length KB such that BPNTRE(J)-BPNTRB(1) points to location in BINDX of the last block entry of the J-th block column of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta * C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

NOTES/BUGS

It is known that there exists another representation of the block sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block column in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse column format the following calling sequence should be used

```
CALL SBSCMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*           VAL, BINDX, IA, IA(2), LB,  
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

cbscsm - block sparse column format triangular solve

SYNOPSIS

```
SUBROUTINE CBSCSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
COMPLEX          ALPHA, BETA  
COMPLEX          DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CBSCSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
COMPLEX          ALPHA, BETA  
COMPLEX          DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB) - BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSCSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*              BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, N, UNITD, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
COMPLEX        ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL, DV  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSCSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, N, UNITD, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
COMPLEX        ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cbscsm(int transa, int mb, int n, int unitd,
  complex *dv, complex *alpha, int *descra, complex *val,
  int *bindx, int *bpntrb, int *bpntre, int lb, complex *b,
  int ldb, complex *beta, complex *c, int ldc);
void cbscsm_64(long transa, long mb, long n, long unitd,
  complex *dv, complex *alpha, long *descra, complex *val,
  long *bindx, long *bpntrb, long *bpntre, long lb, complex
  *b, long ldb, complex *beta, complex *c, long ldc);
```

DESCRIPTION

dbscsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block sparse column format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block columns in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, integer UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) Unchanged on exit.
DV(input)	On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ
consisting of the non-zero block entries stored
column-major within each dense block where
BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting
of the block row indices of the block entries of A where
BNNZ = BPNTRE(MB)-BPNTRB(1). The block row indices MUST
be sorted in increasing order for each block column.
Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such
that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX
of the first block entry of the J-th block column
of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such
that BPNTRE(J)-BPNTRB(1) points to location in BINDX
of the last block entry of the J-th block column
of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks
composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
 On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK \geq MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 ,the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block sparse column representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.

4. If `DESCRA(3)=2` , the diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = -i` where `i` is the block number for which the LU factorization could not be computed.

5. The source is designed so that the routine only uses necessary block entries from the sparse matrix representation based on `DESCRA(2)` and `DESCRA(3)` . The feature prevents the routine from using entries with incorrect indices.

It also provides a possibility to use the sparse matrix representation of a general matrix `A` for solving triangular systems with the upper or lower triangle of `A`. The user doesn't need to form additional sparse matrix representations for the desired triangle of `A` in this case. It's enough to set the values of `DESCRA(2)` and `DESCRA(3)` . But `DESCRA(1)` must be equal to 3 even in this case.

6. It is known that there exists another representation of the block sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, `IA`, containing the pointers to the beginning of each block column in the arrays `VAL` and `BINDX` is used instead of two arrays `BPNTRB` and `BPNTRE`. To use the routine with this kind of block sparse column format the following calling sequence should be used

```
CALL CBSCSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*           VAL, BINDX, IA, IA(2), LB,  
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

cbsrmm - block sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CBSRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CBSRMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSRMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*               BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSRMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
COMPLEX          ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: VAL
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cbsrmm(int transa, int mb, int n, int kb,
  complex *alpha, int *descra, complex *val,
  int *bindx, int *bpntrb, int *bpntre, int lb, complex *b,
  int ldb, complex *beta, complex* c, int ldc);
void cbsrmm_64(long transa, long mb, long n, long kb,
  complex *alpha, long *descra, complex *val, long *bindx,
  long *bpntrb, long *bpntre, long lb, complex *b, long ldb,
  complex *beta, complex *c, long ldc);
```

DESCRIPTION

cbsrmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in the block sparse row format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
KB(input)	On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular 4 : Skew(Anti)-Symmetric (A=-A') 5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ consisting of the non-zero block entries stored column-major within each dense block where BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the J-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(J)-BPNTRB(1) points to location in BINDX of the last block entry of the J-th block row of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta * C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

NOTES/BUGS

It is known that there exists another representation of the block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse row format the following calling sequence should be used

```
CALL SBSRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*           VAL, BINDX, IA, IA(2), LB,  
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

cbsrsm - block sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE CBSRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
COMPLEX          ALPHA, BETA  
COMPLEX          DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CBSRSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
COMPLEX          ALPHA, BETA  
COMPLEX          DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSRSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*              BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, N, UNITD, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
COMPLEX        ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL, DV  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSRSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                  BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, N, UNITD, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
COMPLEX        ALPHA, BETA
```

```

COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void cbsrsm(int transa, int mb, int n, int unitd,
  complex *dv, complex *alpha, int *descra, complex *val,
  int *bindx, int *bpntrb, int *bpntre, int lb, complex *b,
  int ldb, complex *beta, complex *c, int ldc);
void cbsrsm_64(long transa, long mb, long n, long unitd,
  complex *dv, complex *alpha, long *descra, complex *val,
  long *bindx, long *bpntrb, long *bpntre, long lb, complex
  *b, long ldb, complex *beta, complex *c, long ldc);

```

DESCRIPTION

cbsrsm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C, \quad C \leftarrow -\alpha D \operatorname{op}(A) B + \beta C,$$

$$C \leftarrow \alpha \operatorname{op}(A) D B + \beta C,$$

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block sparse row format and op(A) is one of

op(A) = inv(A) or op(A) = inv(A') or op(A) = inv(conjg(A'))
(inv denotes matrix inverse, ' indicates matrix transpose).

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ
consisting of the non-zero block entries stored
column-major within each dense block where
BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting
of the block column indices of the block entries of A where
BNNZ = BPNTRE(MB)-BPNTRB(1). The block column indices MUST
be sorted in increasing order for each block column.
Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such
that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX
of the first block entry of the J-th block row
of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such
that BPNTRE(J)-BPNTRB(1) points to location in BINDX
of the last block entry of the J-th block row
of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks
composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
 On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block sparse row representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.

4. If `DESCRA(3)=2` , the diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

6. It is known that there exists another representation of the block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, `IA`, containing the pointers to the beginning of each block row in the arrays `VAL` and `BINDX` is used instead of two arrays `BPNTRB` and `BPNTRE`. To use the routine with this kind of block sparse row format the following calling sequence should be used

```
CALL CBSRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*           VAL, BINDX, IA, IA(2), LB,
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

ccnvcor - compute the convolution or correlation of complex vectors

SYNOPSIS

```
SUBROUTINE CCNVCOR(CNVCOR, FOUR, NX, X, IFX, INCX, NY, NPRE, M, Y,
  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, FOUR
COMPLEX X(*), Y(*), Z(*), WORK(*)
INTEGER NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y, NZ,
K, IFZ, INC1Z, INC2Z, LWORK
```

```
SUBROUTINE CCNVCOR_64(CNVCOR, FOUR, NX, X, IFX, INCX, NY, NPRE, M, Y,
  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, FOUR
COMPLEX X(*), Y(*), Z(*), WORK(*)
INTEGER*8 NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y, NZ,
K, IFZ, INC1Z, INC2Z, LWORK
```

F95 INTERFACE

```
SUBROUTINE CNVCOR(CNVCOR, FOUR, NX, X, IFX, [INCX], NY, NPRE, M, Y,
  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, FOUR
COMPLEX, DIMENSION(:) :: X, Y, Z, WORK
INTEGER :: NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y,
NZ, K, IFZ, INC1Z, INC2Z, LWORK
```

```
SUBROUTINE CNVCOR_64(CNVCOR, FOUR, NX, X, IFX, [INCX], NY, NPRE, M,
  Y, IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, FOUR
COMPLEX, DIMENSION(:) :: X, Y, Z, WORK
INTEGER(8) :: NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y,
NZ, K, IFZ, INC1Z, INC2Z, LWORK
```

C INTERFACE

```
#include <sunperf.h>
```

```

void ccnvcor(char cnvcor, char four, int nx, complex *x, int
    ifx, int incx, int ny, int npre, int m, complex
    *y, int ify, int inclx, int inc2y, int nz, int k,
    complex *z, int ifz, int inclz, int inc2z, complex
    *work, int lwork);
void ccnvcor_64(char cnvcor, char four, long nx, complex *x,
    long ifx, long incx, long ny, long npre, long m,
    complex *y, long ify, long inclx, long inc2y, long
    nz, long k, complex *z, long ifz, long inclz, long
    inc2z, complex *work, long lwork);

```

PURPOSE

ccnvcor computes the convolution or correlation of complex vectors.

ARGUMENTS

CNVCOR (input)

CHARACTER
'V' or 'v' if convolution is desired, 'R' or 'r'
if correlation is desired.

FOUR (input)

CHARACTER
'T' or 't' if the Fourier transform method is to
be used, 'D' or 'd' if the computation should be
done directly from the definition. The Fourier
transform method is generally faster, but it may
introduce noticeable errors into certain results,
notably when both the real and imaginary parts of
the filter and data vectors consist entirely of
integers or vectors where elements of either the
filter vector or a given data vector differ signi-
ficantly in magnitude from the 1-norm of the vec-
tor.

NX (input)

Length of the filter vector. NX >= 0. CCNVCOR
will return immediately if NX = 0.

X (input) dimension(*)

Filter vector.

IFX (input)

Index of the first element of X. NX >= IFX >= 1.

INCX (input)

Stride between elements of the filter vector in X.
INCX > 0.

NY (input)

Length of the input vectors. NY >= 0. CCNVCOR
will return immediately if NY = 0.

NPRES (input)

The number of implicit zeros prepended to the Y vectors. NPRES ≥ 0 .

M (input)

Number of input vectors. $M \geq 0$. CCNVCOR will return immediately if $M = 0$.

Y (input) dimension(*)

Input vectors.

IFY (input)

Index of the first element of Y. $NY \geq IFY \geq 1$.

INC1Y (input)

Stride between elements of the input vectors in Y. $INC1Y > 0$.

INC2Y (input)

Stride between the input vectors in Y. $INC2Y > 0$.

NZ (input)

Length of the output vectors. $NZ \geq 0$. CCNVCOR will return immediately if $NZ = 0$. See the Notes section below for information about how this argument interacts with NX and NY to control circular versus end-off shifting.

K (input)

Number of Z vectors. $K \geq 0$. If $K = 0$ then CCNVCOR will return immediately. If $K < M$ then only the first K input vectors will be processed. If $K > M$ then M input vectors will be processed.

Z (output)

dimension(*)

Result vectors.

IFZ (input)

Index of the first element of Z. $NZ \geq IFZ \geq 1$.

INC1Z (input)

Stride between elements of the output vectors in Z. $INC1Z > 0$.

INC2Z (input)

Stride between the output vectors in Z. $INC2Z > 0$.

WORK (input/output)

(input/scratch) dimension(LWORK)

Scratch space. Before the first call to CCNVCOR with particular values of the integer arguments the first element of WORK must be set to zero. If WORK is written between calls to CCNVCOR or if CCNVCOR is called with different values of the integer arguments then the first element of WORK must again be set to zero before each call. If WORK has not been written and the same values of the integer arguments are used then the first element of WORK to zero. This can avoid certain initializations that store their results into WORK, and avoiding the initialization can make CCNVCOR

run faster.

LWORK (input)

Length of WORK. LWORK $\geq 2 * \text{MAX}(\text{NX}, \text{NY} + \text{NPRE}, \text{NZ}) + 8$.

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NAME

ccnvcor2 - compute the convolution or correlation of complex matrices

SYNOPSIS

```
SUBROUTINE CCNVCOR2(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, MX, NX, X, LDX, MY, NY, MPRE, NPRE, Y, LDY, MZ, NZ, Z,  
    LDZ, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
SCRATCHY  
COMPLEX X(LDX,*), Y(LDY,*), Z(LDZ,*), WORK(*)  
INTEGER MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ, LDZ,  
LWORK
```

```
SUBROUTINE CCNVCOR2_64(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, MX, NX, X, LDX, MY, NY, MPRE, NPRE, Y, LDY, MZ, NZ, Z,  
    LDZ, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
SCRATCHY  
COMPLEX X(LDX,*), Y(LDY,*), Z(LDZ,*), WORK(*)  
INTEGER*8 MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ, LDZ,  
LWORK
```

F95 INTERFACE

```
SUBROUTINE CNVCOR2(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, [MX], [NX], X, [LDX], [MY], [NY], MPRE, NPRE, Y, [LDY],  
    [MZ], [NZ], Z, [LDZ], WORK, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, METHOD, TRANSX, SCRATCHX,  
TRANSY, SCRATCHY  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: X, Y, Z  
INTEGER :: MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ,  
LDZ, LWORK
```

```
SUBROUTINE CNVCOR2_64(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, [MX], [NX], X, [LDX], [MY], [NY], MPRE, NPRE, Y, [LDY],  
    [MZ], [NZ], Z, [LDZ], WORK, [LWORK])
```

```

CHARACTER(LEN=1) :: CNVCOR, METHOD, TRANSX, SCRATCHX,
TRANSY, SCRATCHY
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: X, Y, Z
INTEGER(8) :: MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ,
LDZ, LWORK

```

C INTERFACE

```

#include <sunperf.h>

void ccnvcor2(char cnvcor, char method, char transx, char
scratchx, char transy, char scratchy, int mx, int
nx, complex *x, int ldx, int my, int ny, int mpre,
int npre, complex *y, int ldy, int mz, int nz,
complex *z, int ldz, complex *work, int lwork);

void ccnvcor2_64(char cnvcor, char method, char transx, char
scratchx, char transy, char scratchy, long mx,
long nx, complex *x, long ldx, long my, long ny,
long mpre, long npre, complex *y, long ldy, long
mz, long nz, complex *z, long ldz, complex *work,
long lwork);

```

PURPOSE

ccnvcor2 computes the convolution or correlation of complex matrices.

ARGUMENTS

CNVCOR (input)
'V' or 'v' to compute convolution, 'R' or 'r' to compute correlation.

METHOD (input)
'T' or 't' if the Fourier transform method is to be used, 'D' or 'd' to compute directly from the definition.

TRANSX (input)
'N' or 'n' if X is the filter matrix, 'T' or 't' if transpose(X) is the filter matrix.

SCRATCHX (input)
'N' or 'n' if X must be preserved, 'S' or 's' if X can be used as scratch space. The contents of X are undefined after returning from a call in which X is allowed to be used for scratch.

TRANSY (input)
'N' or 'n' if Y is the input matrix, 'T' or 't' if transpose(Y) is the input matrix.

SCRATCHY (input)
'N' or 'n' if Y must be preserved, 'S' or 's' if Y can be used as scratch space. The contents of Y

are undefined after returning from a call in which Y is allowed to be used for scratch.

MX (input)
Number of rows in the filter matrix. $MX \geq 0$.

NX (input)
Number of columns in the filter matrix. $NX \geq 0$.

X (input)
On entry, the filter matrix. Unchanged on exit if SCRATCHX is 'N' or 'n', undefined on exit if SCRATCHX is 'S' or 's'.

LDX (input)
Leading dimension of the array that contains the filter matrix.

MY (input)
Number of rows in the input matrix. $MY \geq 0$.

NY (input)
Number of columns in the input matrix. $NY \geq 0$.

MPRE (input)
Number of implicit zeros to prepend to each row of the input matrix. $MPRE \geq 0$.

NPRES (input)
Number of implicit zeros to prepend to each column of the input matrix. $NPRES \geq 0$.

Y (input)
Input matrix. Unchanged on exit if SCRATCHY is 'N' or 'n', undefined on exit if SCRATCHY is 'S' or 's'.

LDY (input)
Leading dimension of the array that contains the input matrix.

MZ (input)
Number of rows in the output matrix. $MZ \geq 0$.
CCNVCOR2 will return immediately if $MZ = 0$.

NZ (input)
Number of columns in the output matrix. $NZ \geq 0$.
CCNVCOR2 will return immediately if $NZ = 0$.

Z (output)
dimension(LDZ,*)
Result matrix.

LDZ (input)
Leading dimension of the array that contains the result matrix. $LDZ \geq \text{MAX}(1, MZ)$.

WORK (input/output)
(input/scratch) dimension(LWORK)
On entry for the first call to CCNVCOR2, WORK(1) must contain CMLPX(0.0,0.0). After the first call, WORK(1) must be set to CMLPX(0.0,0.0) iff

WORK has been altered since the last call to this subroutine or if the sizes of the arrays have changed.

LWORK (input)

Length of the work vector. The upper bound of the workspace length requirement is $2 * (MYC + NYC) + 15$, where $MYC = \text{MAX}(\text{MAX}(MX, NX), \text{MAX}(MY, NY) + \text{NPRE})$ and $NYC = \text{MAX}(\text{MAX}(MX, NX), \text{MAX}(MY, NY) + \text{MPRE})$. If LWORK indicates a workspace that is too small, the routine will allocate its own workspace. If the FFT is not used, the value of LWORK is unimportant.

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NAME

ccoomm - coordinate matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CCOOMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, K, DESCRA(5), NNZ  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), JNDX(NNZ)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE CCOOMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), NNZ  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), JNDX(NNZ)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE COOMM( TRANSA, M, [N], K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ, B, [LDB], BETA, C, [LDC],  
*                [WORK], [LWORK] )  
INTEGER          TRANSA, M, K, NNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, JNDX  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C  
  
SUBROUTINE COOMM_64( TRANSA, M, [N], K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ, B, [LDB], BETA, C, [LDC],  
*                [WORK], [LWORK] )  
INTEGER*8        TRANSA, M, K, NNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, JNDX  
COMPLEX          ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: VAL
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ccoomm (int transa, int m, int n, int k, complex
*alpha, int *descra, complex *val, int *indx, int *jndx, int
nnz, complex *b, int ldb, complex *beta, complex *c, int
ldc);
void ccoomm_64 (long transa, long m, long n, long k,
complex *alpha, long *descra, complex *val, long *indx,
long *jndx, long nnz, complex *b, long ldb,
complex *beta, complex *c, long ldc);
```

DESCRIPTION

ccoomm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the coordinate format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.

K(input) On entry, integer K specifies the number of columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array.
DESCRA(1) matrix structure
0 : general
1 : symmetric ($A=A'$)
2 : Hermitian ($A= \operatorname{CONJG}(A')$)
3 : Triangular
4 : Skew(Anti)-Symmetric ($A=-A'$)

```

5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL (input)    On entry, VAL is a scalar array array of length
                NNZ consisting of the non-zero entries of A,
                in any order. Unchanged on exit.

INDX (input)   On entry, INDX is an integer array of length NNZ
                consisting of the corresponding row indices of
                the entries of A. Unchanged on exit.

JNDX (input)   On entry, JNDX is an integer array of length NNZ
                consisting of the corresponding column indices of
                the entries of A. Unchanged on exit.

NNZ (input)    On entry, integer NNZ specifies the number of
                non-zero elements in A. Unchanged on exit.

B (input)      Array of DIMENSION ( LDB, N ).
                Before entry with TRANSA = 0, the leading k by n
                part of the array B must contain the matrix B, otherwise
                the leading m by n part of the array B must contain the
                matrix B. Unchanged on exit.

LDB (input)    On entry, LDB specifies the first dimension of B as declared
                in the calling (sub) program. Unchanged on exit.

BETA (input)   On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                Before entry with TRANSA = 0, the leading m by n
                part of the array C must contain the matrix C, otherwise
                the leading k by n part of the array C must contain the
                matrix C. On exit, the array C is overwritten by the matrix
                ( alpha*op( A ) * B + beta*C ).

LDC (input)    On entry, LDC specifies the first dimension of C as declared
                in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN

Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

The all complex sparse blas matrix-matrix multiply routines except the skyline and jagged-diagonal format routines are designed so that if $DESCRA(1) > 0$, the routines check the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A .

Assume that there is the sparse matrix representation of a general complex matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
1	1	0	$\alpha * \text{op}(L+D+L') * B + \beta * C$
1	1	1	$\alpha * \text{op}(L+I+L') * B + \beta * C$
1	2	0	$\alpha * \text{op}(U'+D+U) * B + \beta * C$
1	2	1	$\alpha * \text{op}(U'+I+U) * B + \beta * C$
2	1	0	$\alpha * \text{op}(L+D+\text{conjg}(L')) * B + \beta * C$
2	1	1	$\alpha * \text{op}(L+I+\text{conjg}(L')) * B + \beta * C$
2	2	0	$\alpha * \text{op}(\text{conjg}(U') + D + U) * B + \beta * C$
2	2	1	$\alpha * \text{op}(\text{conjg}(U') + I + U) * B + \beta * C$

3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$
4	1	0 or 1	$\alpha * \text{op}(L-L') * B + \beta * C$
4	2	0 or 1	$\alpha * \text{op}(U-U') * B + \beta * C$
5	1 or 2	0	$\alpha * \text{op}(D) * B + \beta * C$
5	1 or 2	1	$\alpha * B + \beta * C$
6	1	0 or 1	$\alpha * \text{op}(L - \text{conjg}(L')) * B + \beta * C$
6	2	0 or 1	$\alpha * \text{op}(U - \text{conjg}(U')) * B + \beta * C$

Remarks to the table:

1. the value of `DESCRA(3)` is simply ignored and the diagonal entries given in the sparse matrix representation are not used by the routine, if `DESCRA(1) = 4` or `6`;
2. the diagonal entries are not used also, if `DESCRA(3) = 1` and `DESCRA(1)` is one of `1, 2, 3` or `5`;
3. if `DESCRA(3)` is not `1` and `DESCRA(1)` is one of `1, 2, 4` or `6`, the type of `D` should correspond to the chosen value of `DESCRA(1)` .

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NAME

ccopy - Copy x to y

SYNOPSIS

```
SUBROUTINE CCOPY(N, X, INCX, Y, INCY)
```

```
COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE CCOPY_64(N, X, INCX, Y, INCY)
```

```
COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE COPY([N], X, [INCX], Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE COPY_64([N], X, [INCX], Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ccopy(int n, complex *x, int incx, complex *y, int  
incy);
```

```
void ccopy_64(long n, complex *x, long incx, complex *y,  
long incy);
```

PURPOSE

ccopy Copy x to y where x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (output)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$. On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

ccscmm - compressed sparse column format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CCSCMM( TRANSA, M, N, K, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER TRANSA, M, N, K, DESCRA(5),
*      LDB, LDC, LWORK
INTEGER INDX(NNZ), PNTRB(K), PNTRE(K)
COMPLEX ALPHA, BETA
COMPLEX VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE CCSCMM_64( TRANSA, M, N, K, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER*8 TRANSA, M, N, K, DESCRA(5),
*      LDB, LDC, LWORK
INTEGER*8 INDX(NNZ), PNTRB(K), PNTRE(K)
COMPLEX ALPHA, BETA
COMPLEX VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(K)-PNTRB(1).

F95 INTERFACE

```
SUBROUTINE CSCMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,
*  PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )
INTEGER TRANSA, M, K
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
COMPLEX ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL
COMPLEX, DIMENSION(:, :) :: B, C

SUBROUTINE CSCMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,
*  PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )
INTEGER*8 TRANSA, M, K
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
```

```

COMPLEX ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL
COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void ccscmm(int transa, int m, int n, int k, complex *alpha,
int *descra, complex *val, int *indx, int *pntrb, int
*pntrc, complex *b, int ldb, complex *beta, complex* c, int
ldc);

void ccscmm_64(long transa, long m, long n, long k,
complex *alpha, long *descra, complex *val, long *indx, long
*pntrb, long *pntrc, complex *b, long ldb, complex *beta,
complex *c, long ldc);

```

DESCRIPTION

ccscmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the compressed sparse column format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular

```

    4 : Skew(Anti)-Symmetric (A=-A')
    5 : Diagonal
    6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
    1 : lower
    2 : upper
DESCRA(3) main diagonal type
    0 : non-unit
    1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
    0 : C/C++ compatible
    1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
    0 : unknown
    1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array of length
                 NNZ = PNTRE(K)-PNTRB(1) consisting of nonzero
                 entries of A. Unchanged on exit.

INDX(input)     On entry, INDX is an integer array of length
                 NNZ = PNTRE(K)-PNTRB(1) consisting of the row
                 indices of nonzero entries of A.
                 Unchanged on exit.

PNTRB(input)    On entry, PNTRB is an integer array of length K
                 such that PNTRB(J)-PNTRB(1)+1 points to location
                 in VAL of the first nonzero element in column J.
                 Unchanged on exit.

PNTRE(input)    On entry, PNTRE is an integer array of length K
                 such that PNTRE(J)-PNTRB(1) points to location
                 in VAL of the last nonzero element in column J.
                 Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading k by n
                 part of the array B must contain the matrix B, otherwise
                 the leading m by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading m by n
                 part of the array C must contain the matrix C, otherwise
                 the leading k by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta*C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of complex matrices is given in section NOTES/BUGS for the ccoomm manpage.

NOTES/BUGS

It is known that there exists another representation of the compressed sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each column in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of sparse column format the following calling sequence should be used

```
SUBROUTINE CCSCMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, IA, IA(2), B, LDB, BETA,  
*                C, LDC, WORK, LWORK )
```

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NAME

ccscsm - compressed sparse column format triangular solve

SYNOPSIS

```
SUBROUTINE CCSCSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER          TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)
COMPLEX          ALPHA, BETA
COMPLEX          DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE CCSCSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)
COMPLEX          ALPHA, BETA
COMPLEX          DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(M)-PNTRB(1)

F95 INTERFACE

```
SUBROUTINE CSCSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER          TRANSA, M, UNITD
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
COMPLEX          ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C

SUBROUTINE CSCSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER*8        TRANSA, M, UNITD
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
COMPLEX          ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ccscsm(int transa, int mb, int n, int unitd, complex
*dv, complex *alpha, int *descra, complex *val, int *indx,
int *pntrb, int *pntre, complex *b, int ldb, complex *beta,
complex* c, int ldc);
void ccscsm_64(long transa, long mb, long n, long unitd,
complex *dv, complex *alpha, long *descra, complex *val,
long *indx, long *pntrb, long *pntre, complex *b, long ldb,
complex *beta, complex *c, long ldc);
```

DESCRIPTION

ccscsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the compressed sparse column format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic column scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the columns of A have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input) Descriptor argument. Five element integer array:

DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))

Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries of A. If UNITD is 4, VAL contains the scaled matrix A*D (see section NOTES for further details). Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer array of length NNZ = PNTRE(M)-PNTRB(1) consisting of the row indices of nonzero entries of A. Row indices MUST be sorted in increasing order for each column. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such that PNTRB(J)-PNTRB(1)+1 points to location in VAL of the first nonzero element in column J. Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M such that PNTRE(J)-PNTRB(1) points to location in VAL of the last nonzero element in column J. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).

On entry, the leading m by n part of the array C must contain the matrix C . On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M .

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M \cdot N_{\text{CPUS}}$ where N_{CPUS} is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4, the routine scales the columns of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the columns have been scaled. UNITD=3 should be used for the next calls to the routine with overwritten VAL and DV.

`WORK(1)=0` on return if the scaling has been completed successfully, otherwise `WORK(1) = - i` where `i` is the column number which 2-norm is exactly zero.

3. If `DESCRA(3)=1` and `UNITD < 4`, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the CSC representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if `UNITD=4`, the unit diagonal elements MUST be referenced in the CSC representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

5. It is known that there exists another representation of the compressed sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each column in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of sparse column format the following calling sequence should be used

```

SUBROUTINE CCSCSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, IA, IA(2), B, LDB, BETA,
*                 C, LDC, WORK, LWORK )

```

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NAME

ccsrmm - compressed sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CCSRMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, PNTRB, PNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE CCSRMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, PNTRB, PNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(M)-PNTRB(1).

F95 INTERFACE

```
SUBROUTINE CSRMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER          TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C  
  
SUBROUTINE CSRMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8        TRANSA, M, K  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
COMPLEX          ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: VAL
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void ccsrmm(int transa, int m, int n, int k, complex *alpha,
int *descra, complex *val, int *indx, int *pntrb, int
*pntrc, complex *b, int ldb, complex *beta, complex *c, int
ldc);
void ccsrmm_64(long transa, long m, long n, long k,
complex *alpha, long *descra, complex *val, long *indx, long
*pntrb, long *pntrc, complex *b, long ldb, complex *beta,
complex *c, long ldc);
```

DESCRIPTION

ccsrmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the compressed sparse row format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal

```

        6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
        1 : lower
        2 : upper
DESCRA(3) main diagonal type
        0 : non-unit
        1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
        0 : C/C++ compatible
        1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
        0 : unknown
        1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array of length
                 NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries
                 of A. Unchanged on exit.

INDX(input)     On entry, INDX is an integer array of length
                 NNZ = PNTRE(M)-PNTRB(1) consisting of the column
                 indices of nonzero entries of A. Unchanged on exit.

PNTRB(input)    On entry, PNTRB is an integer array of length M such
                 that PNTRB(J)-PNTRB(1)+1 points to location in VAL
                 of the first nonzero element in row J.
                 Unchanged on exit.

PNTRE(input)    On entry, PNTRE is an integer array of length M
                 such that PNTRE(J)-PNTRB(1) points to location
                 in VAL of the last nonzero element in row J.
                 Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading k by n
                 part of the array B must contain the matrix B, otherwise
                 the leading m by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading m by n
                 part of the array C must contain the matrix C, otherwise
                 the leading k by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta * C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible

with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of complex matrices is given in section NOTES/BUGS for the ccoomm manpage.

NOTES/BUGS

It is known that there exists another representation of the compressed sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each row in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of compressed sparse row format the following calling sequence should be used

```
SUBROUTINE CCSRMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, IA, IA(2), B, LDB, BETA,  
*                C, LDC, WORK, LWORK )
```

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NAME

ccsrsm - compressed sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE CCSRSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER          TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)
COMPLEX          ALPHA, BETA
COMPLEX          DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE CCSRSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)
COMPLEX          ALPHA, BETA
COMPLEX          DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

where NNZ = PNTRE(M)-PNTRB(1)
```

F95 INTERFACE

```
SUBROUTINE CSRSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER          TRANSA, M, UNITD
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
COMPLEX          ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C

SUBROUTINE CSRSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER*8        TRANSA, M, UNITD
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
COMPLEX          ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void ccsrsm(int transa, int mb, int n, int unitd, complex
*dv, complex *alpha, int *descra, complex *val, int *indx,
int *pntrb, int *pntre, complex *b, int ldb, complex *beta,
complex* c, int ldc);
void ccsrsm_64(long transa, long mb, long n, long unitd,
complex *dv, complex *alpha, long *descra, complex *val,
long *indx, long *pntrb, long *pntre, complex *b, long ldb,
complex *beta, complex *c, long ldc);
```

DESCRIPTION

ccsrsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the compressed sparse row format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input) On entry, TRANSA indicates how to operate with the sparse matrix:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
4 : Automatic row scaling (see section NOTES for further details)
Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further

details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries
of A. If UNITD is 4, VAL contains the scaled matrix
D*A (see section NOTES for further details).
Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
NNZ = PNTRE(M)-PNTRB(1) consisting of the column
indices of nonzero entries of A. Column indices
MUST be sorted in increasing order for each
row. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such
that PNTRB(J)-PNTRB(1)+1 points to location in VAL
of the first nonzero element in row J.
Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M
such that PNTRE(J)-PNTRB(1) points to location
in VAL of the last nonzero element in row J.
Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C
must contain the matrix C. On exit, the array C is
overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger.
For optimum performance on multiple processors, LWORK $\geq M \cdot N_{\text{CPUS}}$ where N_{CPUS} is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise *WORK*(1) = - i where i is the row number which 2-norm is exactly zero.

3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the CSR representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the CSR representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But *DESCRA*(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

5. It is known that there exists another representation of the compressed sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each row in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of compressed sparse row format the following calling sequence should be used

```

SUBROUTINE CCSRSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, IA, IA(2), B, LDB, BETA, C,
*                LDC, WORK, LWORK )

```

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NAME

cdiamm - diagonal format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CDIAMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, LDA, IDIAG, NDIAG,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, K, DESCRA(5), LDA, NDIAG,  
*                LDB, LDC, LWORK  
INTEGER          IDIAG(NDIAG)  
COMPLEX         ALPHA, BETA  
COMPLEX         VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CDIAMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, LDA, IDIAG, NDIAG,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), LDA, NDIAG,  
*               LDB, LDC, LWORK  
INTEGER*8        IDIAG(NDIAG)  
COMPLEX         ALPHA, BETA  
COMPLEX         VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE DIAMM(TRANSA, M, [N], K, ALPHA, DESCRA, VAL, [LDA],  
*  IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER    TRANSA, M, K, NDIAG  
INTEGER, DIMENSION(:) ::  DESCRA, IDIAG  
COMPLEX   ALPHA, BETA  
COMPLEX, DIMENSION(:, :) ::  VAL, B, C
```

```
SUBROUTINE DIAMM_64(TRANSA, M, [N], K, ALPHA, DESCRA, VAL, [LDA],  
*  IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8  TRANSA, M, K, NDIAG  
INTEGER*8, DIMENSION(:) ::  DESCRA, IDIAG  
COMPLEX   ALPHA, BETA  
COMPLEX, DIMENSION(:, :) ::  VAL, B, C
```

C INTERFACE

```

#include <sunperf.h>

void cdiamm (int transa, int m, int n, int k, complex
*alpha, int *descra, complex *val, int lda, int *idiag, int
ndiag, complex *b, int ldb, complex *beta,
complex *c, int ldc);

void cdiamm_64 (long transa, long m, long n, long k, complex
*alpha, long *descra, complex *val, long lda,
long *idiag, long ndiag, complex *b, long ldb,
complex *beta, complex *c, long ldc);

```

DESCRIPTION

cdiamm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the diagonal format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal 6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$) DESCRA(2) upper/lower triangular indicator 1 : lower

2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) Two-dimensional LDA-by-NDIAG array such that VAL(:,I) consists of non-zero elements on diagonal IDIAG(I) of A. Diagonals in the lower triangular part of A are padded from the top, and those in the upper triangular part are padded from the bottom. Unchanged on exit.

LDA(input) On entry, NDIAG specifies the leading dimension of VAL, must be $\geq \text{MIN}(M,K)$. Unchanged on exit.

IDIAG(input) Integer array of length NDIAG consisting of the corresponding diagonal offsets of the non-zero diagonals of A in VAL. Lower triangular diagonals have negative offsets, the main diagonal has offset 0, and upper triangular diagonals have positive offset. Unchanged on exit.

NDIAG(input) On entry, NDIAG specifies the number of non-zero diagonals in A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \text{beta} * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of complex matrices is given in section NOTES/BUGS for the ccoomm manpage.

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NAME

cdiasm - diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE CDIASM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, LDA, IDIAG, NDIAG,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, M, N, UNITD, DESCRA(5), LDA, NDIAG,  
* LDB, LDC, LWORK  
INTEGER IDIAG(NDIAG)  
COMPLEX ALPHA, BETA  
COMPLEX DV(M), VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CDIASM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, LDA, IDIAG, NDIAG,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, M, N, UNITD, DESCRA(5), LDA, NDIAG,  
* LDB, LDC, LWORK  
INTEGER*8 IDIAG(NDIAG)  
COMPLEX ALPHA, BETA  
COMPLEX DV(M), VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE DIASM(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* [LDA], IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, M, NDIAG  
INTEGER, DIMENSION(:) :: DESCRA, IDIAG  
COMPLEX ALPHA, BETA  
COMPLEX, DIMENSION(:) :: DV  
COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE DIASM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* [LDA], IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, M, NDIAG  
INTEGER*8, DIMENSION(:) :: DESCRA, IDIAG  
COMPLEX ALPHA, BETA  
COMPLEX, DIMENSION(:) :: DV  
COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>

void cdiasm (int transa, int m, int n, int unitd,
             complex *dv, complex *alpha, int *descra, complex *val, int
             lda,
             int *idiag, int ndiag, complex *b, int ldb, complex *beta,
             complex *c, int ldc);
void cdiasm_64 (long transa, long m, long n, long unitd,
               complex *dv, complex *alpha, long *descra, complex *val,
               long lda,
               long *idiag, long ndiag, complex *b, long ldb,
               complex *beta, complex *c, long ldc);
```

DESCRIPTION

cdiasm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C, \quad C \leftarrow \alpha D \operatorname{op}(A) B + \beta C,$$
$$C \leftarrow \alpha \operatorname{op}(A) D B + \beta C,$$

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the diagonal format and op(A) is one of

$$\operatorname{op}(A) = \operatorname{inv}(A) \text{ or } \operatorname{op}(A) = \operatorname{inv}(A') \text{ or } \operatorname{op}(A) = \operatorname{inv}(\operatorname{conjg}(A'))$$

(inv denotes matrix inverse, ' indicates matrix transpose).

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LDA-by-NDIAG array such that VAL(:,I) consists of non-zero elements on diagonal IDIAG(I) of A. Diagonals in the lower triangular part of A are padded from the top, and those in the upper triangular part are padded from the bottom. If UNITD is 4, VAL contains the scaled matrix D*A (see section NOTES for further details). Otherwise, unchanged on exit.

LDA(input) On entry, LDA specifies the leading dimension of VAL and INDX. LDA must be > MIN(M,K). Unchanged on exit.

IDIAG() On entry, IDIAG is an integer array of length NDIAG consisting of the corresponding diagonal offsets of the non-zero diagonals of A in VAL. Lower triangular diagonals have negative offsets, the main diagonal has offset 0, and upper triangular diagonals have positive offset. Elements of IDIAG of MUST be sorted in increasing order. Unchanged on exit.

NDIAG(input) On entry, NDIAG specifies the number of non-zero diagonals in A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is

overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger.
For optimum performance on multiple processors, LWORK $\geq M \cdot N_{\text{CPUS}}$ where N_{CPUS} is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = - i where i is the row number which 2-norm is exactly zero.

3. If `DESCRA(3)=1` and `UNITD < 4`, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the DIA representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if `UNITD=4`, the unit diagonal elements MUST be referenced in the DIA representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

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NAME

cdotc - compute the dot product of two vectors conjg(x) and y.

SYNOPSIS

```
COMPLEX FUNCTION CDOTC(N, X, INCX, Y, INCY)
```

```
COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
COMPLEX FUNCTION CDOTC_64(N, X, INCX, Y, INCY)
```

```
COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
COMPLEX FUNCTION DOTC([N], X, [INCX], Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
COMPLEX FUNCTION DOTC_64([N], X, [INCX], Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
complex cdotc(int n, complex *x, int incx, complex *y, int  
            incy);
```

```
complex cdotc_64(long n, complex *x, long incx, complex *y,  
                long incy);
```

PURPOSE

cdotc compute the dot product of conjg(x) and y where x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If N is not positive then the function returns the value 0.0. Unchanged on exit.

X (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCX}))$. On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$. On entry, the incremented array Y must contain the vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

cdotci - Compute the complex conjugated indexed dot product.

SYNOPSIS

```
COMPLEX FUNCTION CDOTCI(NZ, X, INDX, Y)
```

```
COMPLEX X(*), Y(*)
INTEGER NZ
INTEGER INDX(*)
```

```
COMPLEX FUNCTION CDOTCI_64(NZ, X, INDX, Y)
```

```
COMPLEX X(*), Y(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)
```

```
F95 INTERFACE
```

```
COMPLEX FUNCTION DOTCI([NZ], X, INDX, Y)
```

```
COMPLEX, DIMENSION(:) :: X, Y
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX
```

```
COMPLEX FUNCTION DOTCI_64([NZ], X, INDX, Y)
```

```
COMPLEX, DIMENSION(:) :: X, Y
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

CDOTCI Compute the complex conjugated indexed dot product of a complex sparse vector x stored in compressed form with a complex vector y in full storage form.

```
dot = 0
do i = 1, n
  dot = dot + conjg(x(i)) * y(indx(i))
enddo
```

ARGUMENTS

NZ (input)

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector in compressed form. Unchanged on exit.

INDX (input)

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

Y (input)

Vector in full storage form. Only the elements
corresponding to the indices in INDX will be
accessed.

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NAME

cdotu - compute the dot product of two vectors x and y.

SYNOPSIS

```
COMPLEX FUNCTION CDOTU(N, X, INCX, Y, INCY)
```

```
COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
COMPLEX FUNCTION CDOTU_64(N, X, INCX, Y, INCY)
```

```
COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
COMPLEX FUNCTION DOT([N], X, [INCX], Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
COMPLEX FUNCTION DOT_64([N], X, [INCX], Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
complex cdotu(int n, complex *x, int incx, complex *y, int  
            incy);
```

```
complex cdotu_64(long n, complex *x, long incx, complex *y,  
                long incy);
```

PURPOSE

cdotu compute the dot product of x and y where x and y are

n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If N is not positive then the function returns the value 0.0. Unchanged on exit.

X (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCX}))$. On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$. On entry, the incremented array Y must contain the vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

cdotui - Compute the complex unconjugated indexed dot product.

SYNOPSIS

```
COMPLEX FUNCTION CDOTCI(NZ, X, INDX, Y)
```

```
COMPLEX X(*), Y(*)
INTEGER NZ
INTEGER INDX(*)
```

```
COMPLEX FUNCTION CDOTCI_64(NZ, X, INDX, Y)
```

```
COMPLEX X(*), Y(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)
```

```
F95 INTERFACE
```

```
COMPLEX FUNCTION DOTCI([NZ], X, INDX, Y)
```

```
COMPLEX, DIMENSION(:) :: X, Y
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX
```

```
COMPLEX FUNCTION DOTCI_64([NZ], X, INDX, Y)
```

```
COMPLEX, DIMENSION(:) :: X, Y
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

CDOTUI Compute the complex unconjugated indexed dot product of a complex sparse vector x stored in compressed form with a complex vector y in full storage form.

```
dot = 0
do i = 1, n
  dot = dot + x(i) * y(indx(i))
enddo
```

ARGUMENTS

NZ (input)

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector in compressed form. Unchanged on exit.

INDX (input)

Vector containing the indices of the compressed form. It is assumed that the elements in INDX are distinct and greater than zero. Unchanged on exit.

Y (input)

Vector in full storage form. Only the elements corresponding to the indices in INDX will be accessed.

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NAME

cellmm - Ellpack format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CELLMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, LDA, MAXNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, K, DESCRA(5), LDA, MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(LDA,MAXNZ)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CELLMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                    VAL, INDX, LDA, MAXNZ,  
*                    B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), LDA, MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(LDA,MAXNZ)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE ELLMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, K, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA  
INTEGER, DIMENSION(:, :) :: INDX  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE ELLMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                   [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, M, K, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA  
INTEGER*8, DIMENSION(:, :) :: INDX  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>

void cellmm (int transa, int m, int n, int k, complex
*alpha, int *descra, complex *val, int *indx, int lda, int
maxnz, complex *b, int ldb, complex *beta, complex *c, int
ldc);
void cellmm_64 (long transa, long m, long n, long k, complex
*alpha, long *descra, complex *val, long *indx, long lda,
long maxnz, complex *b, long ldb, complex *beta, complex *c,
long ldc);
```

DESCRIPTION

cellmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the ellpack format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

K(input) On entry, K specifies the number of columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric ($A=A'$)
2 : Hermitian ($A= \operatorname{CONJG}(A')$)
3 : Triangular
4 : Skew(Anti)-Symmetric ($A=-A'$)
5 : Diagonal
6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$)
DESCRA(2) upper/lower triangular indicator

```

        1 : lower
        2 : upper
DESCRA(3) main diagonal type
        0 : non-unit
        1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
        0 : C/C++ compatible
        1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
        0 : unknown
        1 : no repeated indices

VAL(input)      On entry, VAL is a two-dimensional LDA-by-MAXNZ array
                such that VAL(I,:) consists of non-zero elements
                in row I of A, padded by zero values if the row
                contains less than MAXNZ. Unchanged on exit.

INDX(input)     On entry, INDX is an integer two-dimensional
                LDA-by-MAXNZ array such that INDX(I,:)
                consists of the column indices of the
                nonzero elements in row I, padded by the integer
                value I if the number of nonzeros is less than
                MAXNZ. Unchanged on exit.

LDA(input)      On entry, LDA specifies the leading dimension of VAL
                and INDX. Unchanged on exit.

MAXNZ(input)    On entry, MAXNZ specifies the max number of
                nonzeros elements per row. Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                Before entry with TRANSA = 0, the leading k by n
                part of the array B must contain the matrix B, otherwise
                the leading m by n part of the array B must contain the
                matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                Before entry with TRANSA = 0, the leading m by n
                part of the array C must contain the matrix C, otherwise
                the leading k by n part of the array C must contain the
                matrix C. On exit, the array C is overwritten by the matrix
                ( alpha*op( A ) * B + beta*C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN

Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of complex matrices is given in section NOTES/BUGS for the ccoomm manpage.

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NAME

cellsm - Ellpack format triangular solve

SYNOPSIS

```
SUBROUTINE CELLSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, LDA, MAXNZ,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, M, N, UNITD, DESCRA(5), LDA, MAXNZ,  
* LDB, LDC, LWORK  
INTEGER INDX(LDA,MAXNZ)  
COMPLEX ALPHA, BETA  
COMPLEX DV(M), VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CELLSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, LDA, MAXNZ,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, M, N, UNITD, DESCRA(5), LDA, MAXNZ,  
* LDB, LDC, LWORK  
INTEGER*8 INDX(LDA,MAXNZ)  
COMPLEX ALPHA, BETA  
COMPLEX DV(M), VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE ELLSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* INDX, [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, M, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA  
INTEGER, DIMENSION(:, :) :: INDX  
COMPLEX ALPHA, BETA  
COMPLEX, DIMENSION(:) :: DV  
COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE ELLSM_64( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* INDX, [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, M, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA  
INTEGER*8, DIMENSION(:, :) :: INDX  
COMPLEX ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: DV
COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cellsm (int transa, int m, int n, int unitd, complex
*dv, complex *alpha, int *descra, complex *val, int *indx,
int lda, int maxnz, complex *b, int ldb, complex *beta,
complex *c, int ldc);
void cellsm_64 (long transa, long m, long n, long unitd,
complex *dv, complex *alpha, long *descra, complex *val,
long *indx, long lda, long maxnz, complex *b, long ldb,
complex *beta, complex *c, long ldc);
```

DESCRIPTION

zellsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the ellpack/itpack format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LDA-by-MAXNZ array such that VAL(I,:) consists of non-zero elements in row I of A, padded by zero values if the row contains less than MAXNZ. If UNITD is 4, VAL contains the scaled matrix D*A (see section NOTES for further details). Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer two-dimensional LDA-by-MAXNZ array such that INDX(I,:) consists of the column indices of the nonzero elements in row I, padded by the integer value I if the number of nonzeros is less than MAXNZ. The column indices MUST be sorted in increasing order for each row. Unchanged on exit.

LDA(input) On entry, LDA specifies the leading dimension of VAL and INDX. Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of nonzeros elements per row. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M \times N_{\text{CPUS}}$ where N_{CPUS} is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
 2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.
- WORK*(1)=0 on return if the scaling has been completed successfully, otherwise *WORK*(1) = - i where i is the row number which 2-norm is exactly zero.
3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are

each used with the mathematical value 1. The entries of the main diagonal in the ELL representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the ELL representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

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NAME

cffft2b - compute a periodic sequence from its Fourier coefficients. The xFFT operations are unnormalized, so a call of xFFT2F followed by a call of xFFT2B will multiply the input sequence by M*N.

SYNOPSIS

```
SUBROUTINE CFFT2B(M, N, A, LDA, WORK, LWORK)
```

```
COMPLEX A(LDA,*)  
INTEGER M, N, LDA, LWORK  
REAL WORK(*)
```

```
SUBROUTINE CFFT2B_64(M, N, A, LDA, WORK, LWORK)
```

```
COMPLEX A(LDA,*)  
INTEGER*8 M, N, LDA, LWORK  
REAL WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2B([M], [N], A, [LDA], WORK, LWORK)
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, LWORK  
REAL, DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT2B_64([M], [N], A, [LDA], WORK, LWORK)
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, LWORK  
REAL, DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cfft2b(int m, int n, complex *a, int lda, float *work,  
           int lwork);
```

```
void cfft2b_64(long m, long n, complex *a, long lda, float  
              *work, long lwork);
```

ARGUMENTS

M (input) Number of rows to be transformed. These subroutines are most efficient when M is a product of small primes. $M \geq 0$.

N (input) Number of columns to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

A (input/output)

On entry, a two-dimensional array A(M,N) that contains the sequences to be transformed.

LDA (input)

Leading dimension of the array containing the data to be transformed. $LDA \geq M$.

WORK (input)

On input, workspace WORK must have been initialized by CFFT2I.

LWORK (input)

The dimension of the array WORK. $LWORK \geq (4 * (M + N) + 30)$

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NAME

cffft2f - compute the Fourier coefficients of a periodic sequence. The xFFT operations are unnormalized, so a call of xFFT2F followed by a call of xFFT2B will multiply the input sequence by M*N.

SYNOPSIS

```
SUBROUTINE CFFT2F(M, N, A, LDA, WORK, LWORK)
```

```
COMPLEX A(LDA,*)  
INTEGER M, N, LDA, LWORK  
REAL WORK(*)
```

```
SUBROUTINE CFFT2F_64(M, N, A, LDA, WORK, LWORK)
```

```
COMPLEX A(LDA,*)  
INTEGER*8 M, N, LDA, LWORK  
REAL WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2F([M], [N], A, [LDA], WORK, LWORK)
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, LWORK  
REAL, DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT2F_64([M], [N], A, [LDA], WORK, LWORK)
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, LWORK  
REAL, DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cfft2f(int m, int n, complex *a, int lda, float *work,  
           int lwork);
```

```
void cfft2f_64(long m, long n, complex *a, long lda, float  
              *work, long lwork);
```

ARGUMENTS

M (input) Number of rows to be transformed. These subroutines are most efficient when M is a product of small primes. $M \geq 0$.

N (input) Number of columns to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

A (input/output)

On entry, a two-dimensional array A(M,N) that contains the sequences to be transformed.

LDA (input)

Leading dimension of the array containing the data to be transformed. $LDA \geq M$.

WORK (input)

On input, workspace WORK must have been initialized by CFFT2I.

LWORK (input)

The dimension of the array WORK. $LWORK \geq (4 * (M + N) + 30)$

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NAME

cffft2i - initialize the array WSAVE, which is used in both the forward and backward transforms.

SYNOPSIS

```
SUBROUTINE CFFT2I(M, N, WORK)
```

```
INTEGER M, N  
REAL WORK(*)
```

```
SUBROUTINE CFFT2I_64(M, N, WORK)
```

```
INTEGER*8 M, N  
REAL WORK(*)
```

F95 INTERFACE

```
SUBROUTINE CFFT2I(M, N, WORK)
```

```
INTEGER :: M, N  
REAL, DIMENSION(:) :: WORK
```

```
SUBROUTINE CFFT2I_64(M, N, WORK)
```

```
INTEGER(8) :: M, N  
REAL, DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cfft2i(int m, int n, float *work);
```

```
void cfft2i_64(long m, long n, float *work);
```

ARGUMENTS

M (input) Number of rows to be transformed. M >= 0.

N (input) Number of columns to be transformed. N >= 0.

WORK (input/output)

On entry, an array of dimension $(4 * (M + N) + 30)$ or greater. CFFT2I needs to be called only once to initialize array WORK before calling CFFT2F and/or CFFT2B if M, N and WORK remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

cffft3b - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of CFFT3F followed by a call of CFFT3B will multiply the input sequence by $M*N*K$.

SYNOPSIS

```
SUBROUTINE CFFT3B(M, N, K, A, LDA, LD2A, WORK, LWORK)
```

```
COMPLEX A(LDA,LD2A,*)
INTEGER M, N, K, LDA, LD2A, LWORK
REAL WORK(*)
```

```
SUBROUTINE CFFT3B_64(M, N, K, A, LDA, LD2A, WORK, LWORK)
```

```
COMPLEX A(LDA,LD2A,*)
INTEGER*8 M, N, K, LDA, LD2A, LWORK
REAL WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3B([M], [N], [K], A, [LDA], LD2A, WORK, LWORK)
```

```
COMPLEX, DIMENSION(:,:,:) :: A
INTEGER :: M, N, K, LDA, LD2A, LWORK
REAL, DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT3B_64([M], [N], [K], A, [LDA], LD2A, WORK, LWORK)
```

```
COMPLEX, DIMENSION(:,:,:) :: A
INTEGER(8) :: M, N, K, LDA, LD2A, LWORK
REAL, DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cfft3b(int m, int n, int k, complex *a, int lda, int
           ld2a, float *work, int lwork);
```

```
void cfft3b_64(long m, long n, long k, complex *a, long lda,
              long ld2a, float *work, long lwork);
```

ARGUMENTS

- M (input) Number of rows to be transformed. These subroutines are most efficient when M is a product of small primes. $M \geq 0$.
- N (input) Number of columns to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- K (input) Number of planes to be transformed. These subroutines are most efficient when K is a product of small primes. $K \geq 0$.
- A (input/output)
On entry, a three-dimensional array $A(LDA,LD2A,K)$ that contains the sequences to be transformed.
- LDA (input)
Leading dimension of the array containing the data to be transformed. $LDA \geq M$.
- LD2A (input)
Second dimension of the array containing the data to be transformed. $LD2A \geq N$.
- WORK (input)
On input, workspace WORK must have been initialized by CFFT3I.
- LWORK (input)
The dimension of the array WORK. $LWORK \geq (4*(M + N + K) + 45)$.

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NAME

cffft3f - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of CFFT3F followed by a call of CFFT3B will multiply the input sequence by $M*N*K$.

SYNOPSIS

```
SUBROUTINE CFFT3F(M, N, K, A, LDA, LD2A, WORK, LWORK)
```

```
COMPLEX A(LDA,LD2A,*)  
INTEGER M, N, K, LDA, LD2A, LWORK  
REAL WORK(*)
```

```
SUBROUTINE CFFT3F_64(M, N, K, A, LDA, LD2A, WORK, LWORK)
```

```
COMPLEX A(LDA,LD2A,*)  
INTEGER*8 M, N, K, LDA, LD2A, LWORK  
REAL WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3F([M], [N], [K], A, [LDA], LD2A, WORK, LWORK)
```

```
COMPLEX, DIMENSION(:, :, :) :: A  
INTEGER :: M, N, K, LDA, LD2A, LWORK  
REAL, DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT3F_64([M], [N], [K], A, [LDA], LD2A, WORK, LWORK)
```

```
COMPLEX, DIMENSION(:, :, :) :: A  
INTEGER(8) :: M, N, K, LDA, LD2A, LWORK  
REAL, DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cfft3f(int m, int n, int k, complex *a, int lda, int  
           ld2a, float *work, int lwork);
```

```
void cfft3f_64(long m, long n, long k, complex *a, long lda,  
              long ld2a, float *work, long lwork);
```

ARGUMENTS

- M (input) Number of rows to be transformed. These subroutines are most efficient when M is a product of small primes. $M \geq 0$.
- N (input) Number of columns to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- K (input) Number of planes to be transformed. These subroutines are most efficient when K is a product of small primes. $K \geq 0$.
- A (input/output)
On entry, a three-dimensional array A(M,N,K) that contains the sequences to be transformed.
- LDA (input)
Leading dimension of the array containing the data to be transformed. $LDA \geq M$.
- LD2A (input)
Second dimension of the array containing the data to be transformed. $LD2A \geq N$.
- WORK (input)
On input, workspace WORK must have been initialized by CFFT3I.
- LWORK (input)
The dimension of the array WORK. $LWORK \geq (4*(M + N + K) + 45)$.

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NAME

cffft3i - initialize the array WSAVE, which is used in both CFFT3F and CFFT3B.

SYNOPSIS

```
SUBROUTINE CFFT3I(M, N, K, WORK)
```

```
INTEGER M, N, K  
REAL WORK(*)
```

```
SUBROUTINE CFFT3I_64(M, N, K, WORK)
```

```
INTEGER*8 M, N, K  
REAL WORK(*)
```

F95 INTERFACE

```
SUBROUTINE CFFT3I(M, N, K, WORK)
```

```
INTEGER :: M, N, K  
REAL, DIMENSION(:) :: WORK
```

```
SUBROUTINE CFFT3I_64(M, N, K, WORK)
```

```
INTEGER(8) :: M, N, K  
REAL, DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cfft3i(int m, int n, int k, float *work);
```

```
void cfft3i_64(long m, long n, long k, float *work);
```

ARGUMENTS

M (input) Number of rows to be transformed. M >= 0.

N (input) Number of columns to be transformed. N >= 0.

K (input) Number of planes to be transformed. $K \geq 0$.

WORK (input/output)

On entry, an array of dimension $(4*(M + N + K) + 45)$ or greater. CFFT3I needs to be called only once to initialize array WORK before calling CFFT3F and/or CFFT3B if M, N, K and WORK remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

cfftb - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of CFFTF followed by a call of CFFTB will multiply the input sequence by N.

SYNOPSIS

```
SUBROUTINE CFFTB(N, X, WSAVE)
```

```
COMPLEX X(*)
INTEGER N
REAL WSAVE(*)
```

```
SUBROUTINE CFFTB_64(N, X, WSAVE)
```

```
COMPLEX X(*)
INTEGER*8 N
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTB([N], X, WSAVE)
```

```
COMPLEX, DIMENSION(:) :: X
INTEGER :: N
REAL, DIMENSION(:) :: WSAVE
```

```
SUBROUTINE FFTB_64([N], X, WSAVE)
```

```
COMPLEX, DIMENSION(:) :: X
INTEGER(8) :: N
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cfftb(int n, complex *x, float *wsave);
```

```
void cfftb_64(long n, complex *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input) On entry, an array of length N containing the sequence to be transformed.

WSAVE (input/output)
On entry, WSAVE must be an array of dimension $(4 * N + 15)$ or greater and must have been initialized by CFFTI.

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NAME

`cfftc` - initialize the trigonometric weight and factor tables or compute the Fast Fourier transform (forward or inverse) of a complex sequence.

SYNOPSIS

```
SUBROUTINE CFFTC(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N, IFAC(*), LWORK, IERR  
COMPLEX X(*), Y(*)  
REAL SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE CFFTC_64(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N, IFAC(*), LWORK, IERR  
REAL SCALE, TRIGS(*), WORK(*)  
COMPLEX X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE FFT(IOPT, [N], [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT  
INTEGER*4, INTENT(IN), OPTIONAL :: N, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
COMPLEX, INTENT(IN), DIMENSION(:) :: X  
COMPLEX, INTENT(OUT), DIMENSION(:) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT_64(IOPT, [N], [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT  
INTEGER(8), INTENT(IN), OPTIONAL :: N, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
COMPLEX, INTENT(IN), DIMENSION(:) :: X  
COMPLEX, INTENT(OUT), DIMENSION(:) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
```

```

INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>

void cfft_ (int *iopt, int *n, float *scale, complex *x,
           complex *y, float *trigs, int *ifac, float *work,
           int *lwork, int *ierr);

void cfft_64_ (long *iopt, long *n, float *scale, complex
              *x, complex *y, float *trigs, long *ifac, float
              *work, long *lwork, long *ierr);

```

PURPOSE

cfft_ initializes the trigonometric weight and factor tables or computes the Fast Fourier transform (forward or inverse) of a complex sequence as follows:

$$Y(k) = \text{scale} * \sum_{j=0}^{N-1} W * X(j)$$

where

k ranges from 0 to N-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

W = exp(isign*i*j*k*2*pi/N)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table
 and factor table
 IOPT = -1 computes forward FFT
 IOPT = +1 computes inverse FFT

N (input)

Integer specifying length of the input sequence X.
 N is most efficient when it is a product of small
 primes. N >= 0. Unchanged on exit.

SCALE (input)

Real scalar by which transform results are scaled.
 Unchanged on exit. SCALE is defaulted to 1.0 for
 F95 INTERFACE.

X (input) On entry, X is a complex array of dimension at
 least N that contains the sequence to be
 transformed.

Y (output)

Complex array of dimension at least N that con-

tains the transform results. X and Y may be the same array starting at the same memory location. Otherwise, it is assumed that there is no overlap between X and Y in memory.

TRIGS (input/output)

Real array of length $2*N$ that contains the trigonometric weights. The weights are computed when the routine is called with $IOPT = 0$ and they are used in subsequent calls when $IOPT = 1$ or $IOPT = -1$. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 128 that contains the factors of N . The factors are computed when the routine is called with $IOPT = 0$ and they are used in subsequent calls where $IOPT = 1$ or $IOPT = -1$. Unchanged on exit.

WORK (workspace)

Real array of dimension at least $2*N$. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If $LWORK = 0$, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

- 0 = normal return
- 1 = IOPT is not 0, 1 or -1
- 2 = $N < 0$
- 3 = (LWORK is not 0) and (LWORK is less than $2*N$)
- 4 = memory allocation for workspace failed

SEE ALSO

fft

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NAME

cfftc2 - initialize the trigonometric weight and factor tables or compute the two-dimensional Fast Fourier Transform (forward or inverse) of a two-dimensional complex array.

SYNOPSIS

```
SUBROUTINE CFFTC2(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
COMPLEX X(LDX, *), Y(LDY, *)  
REAL SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE CFFTC2_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
REAL SCALE, TRIGS(*), WORK(*)  
COMPLEX X(LDX, *), Y(LDY, *)
```

F95 INTERFACE

```
SUBROUTINE FFT2(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT  
INTEGER*4, INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
COMPLEX, INTENT(IN), DIMENSION(:, :) :: X  
COMPLEX, INTENT(OUT), DIMENSION(:, :) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT2_64(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
COMPLEX, INTENT(IN), DIMENSION(:, :) :: X
COMPLEX, INTENT(OUT), DIMENSION(:, :) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void cfftc2_(int *iopt, int *n1, int *n2, float *scale,
             complex *x, int *ldx, complex *y, int *ldy, float
             *trigs, int *ifac, float *work, int *lwork, int
             *ierr);

void cfftc2_64_(long *iopt, long *n1, long *n2, float
               *scale, complex *x, long *ldx, complex *y, long
               *ldy, float *trigs, long *ifac, float *work, long
               *lwork, long *ierr);

```

PURPOSE

cfftc2 initializes the trigonometric weight and factor tables or computes the two-dimensional Fast Fourier Transform (forward or inverse) of a two-dimensional complex array. In computing the two-dimensional FFT, one-dimensional FFTs are computed along the columns of the input array. One-dimensional FFTs are then computed along the rows of the intermediate results.

$$Y(k1, k2) = \text{scale} * \sum_{j2=0}^{N2-1} \sum_{j1=0}^{N1-1} W2 * W1 * X(j1, j2)$$

where

k1 ranges from 0 to N1-1 and k2 ranges from 0 to N2-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

W1 = exp(isign*i*j1*k1*2*pi/N1)

W2 = exp(isign*i*j2*k2*2*pi/N2)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT
 IOPT = +1 computes inverse FFT

N1 (input)

Integer specifying length of the transform in the first dimension. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)
Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. $N2 \geq 0$. Unchanged on exit.

SCALE (input)
Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) X is a complex array of dimensions (LDX, N2) that contains input data to be transformed.

LDX (input)
Leading dimension of X. $LDX \geq N1$ Unchanged on exit.

Y (output)
Y is a complex array of dimensions (LDY, N2) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)
Leading dimension of Y. If X and Y are the same array, $LDY = LDX$ Else $LDY \geq N1$ Unchanged on exit.

TRIGS (input/output)
Real array of length $2*(N1+N2)$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

IFAC (input/output)
Integer array of dimension at least $2*128$ that contains the factors of N1 and N2. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

WORK (workspace)
Real array of dimension at least $2*MAX(N1,N2)*NCPUS$ where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)
Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)
On exit, integer IERR has one of the following values:
0 = normal return
-1 = IOPT is not 0, 1 or -1

-2 = N1 < 0
-3 = N2 < 0
-4 = (LDX < N1)
-5 = (LDY < N1) or (LDY not equal LDX when X and Y
are same array)
-6 = (LWORK not equal 0) and (LWORK <
2*MAX(N1,N2)*NCPUS)
-7 = memory allocation failed

SEE ALSO

fft

CAUTIONS

On exit, entire output array Y(1:LDY, 1:N2) is overwritten.

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NAME

cfftc3 - initialize the trigonometric weight and factor tables or compute the three-dimensional Fast Fourier Transform (forward or inverse) of a three-dimensional complex array.

SYNOPSIS

```
SUBROUTINE CFFTC3(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,
IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),
LWORK, IERR
COMPLEX X(LDX1, LDX2, *), Y(LDY1, LDY2, *)
REAL SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE CFFTC3_64(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,
IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),
LWORK, IERR
COMPLEX X(LDX1, LDX2, *), Y(LDY1, LDY2, *)
REAL SCALE, TRIGS(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3(IOPT, [N1], [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1], LDY2,
TRIGS,
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT, LDX2, LDY2
INTEGER*4, INTENT(IN), OPTIONAL :: N1, N2, N3, LDX1, LDY1,
LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
COMPLEX, INTENT(IN), DIMENSION(:, :) :: X
COMPLEX, INTENT(OUT), DIMENSION(:, :) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER*4, INTENT(OUT) :: IERR
```

```

SUBROUTINE FFT3_64(IOPT, [N1], [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1],
LDY2, TRIGS,
IFAC, WORK, [LWORK], IERR)

```

```

INTEGER(8), INTENT(IN) :: IOPT, LDX2, LDY2
INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, N3, LDX1, LDY1,
LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
COMPLEX, INTENT(IN), DIMENSION(:,:) :: X
COMPLEX, INTENT(OUT), DIMENSION(:,:) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>

void cfftc3_ (int *iopt, int *n1, int *n2, int *n3, float
*scale, complex *x, int *ldx1, int *ldx2, complex
*y, int *ldy1, int *ldy2, float *trigs, int *ifac,
float *work, int *lwork, int *ierr);

void cfftc3_64_ (long *iopt, long *n1, long *n2, long *n3,
float *scale, complex *x, long *ldx1, long *ldx2,
complex *y, long *ldy1, long *ldy2, float *trigs,
long *ifac, float *work, long *lwork, long *ierr);

```

PURPOSE

cfftc3 initializes the trigonometric weight and factor tables or computes the three-dimensional Fast Fourier Transform (forward or inverse) of a three-dimensional complex array.

$$Y(k_1, k_2, k_3) = \text{scale} * \sum_{j_3=0}^{N_3-1} \sum_{j_2=0}^{N_2-1} \sum_{j_1=0}^{N_1-1} W_3 * W_2 * W_1 * X(j_1, j_2, j_3)$$

where

k₁ ranges from 0 to N₁-1; k₂ ranges from 0 to N₂-1 and k₃ ranges from 0 to N₃-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

W₃ = exp(isign*i*j₃*k₃*2*pi/N₃)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
IOPT = 0 computes the trigonometric weight table and factor table

IOPT = -1 computes forward FFT

IOPT = +1 computes inverse FFT

N1 (input)
Integer specifying length of the transform in the first dimension. N1 is most efficient when it is a product of small primes. $N1 \geq 0$. Unchanged on exit.

N2 (input)
Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. $N2 \geq 0$. Unchanged on exit.

N3 (input)
Integer specifying length of the transform in the third dimension. N3 is most efficient when it is a product of small primes. $N3 \geq 0$. Unchanged on exit.

SCALE (input)
Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) X is a complex array of dimensions (LDX1, LDX2, N3) that contains input data to be transformed.

LDX1 (input)
first dimension of X. $LDX1 \geq N1$ Unchanged on exit.

LDX2 (input)
second dimension of X. $LDX2 \geq N2$ Unchanged on exit.

Y (output)
Y is a complex array of dimensions (LDY1, LDY2, N3) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY1 (input)
first dimension of Y. If X and Y are the same array, $LDY1 = LDX1$ Else $LDY1 \geq N1$ Unchanged on exit.

LDY2 (input)
second dimension of Y. If X and Y are the same array, $LDY2 = LDX2$ Else $LDY2 \geq N2$ Unchanged on exit.

TRIGS (input/output)
Real array of length $2*(N1+N2+N3)$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 3×128 that contains the factors of N_1 , N_2 and N_3 . The factors are computed when the routine is called with $IOPT = 0$ and they are used in subsequent calls when $IOPT = 1$ or $IOPT = -1$. Unchanged on exit.

WORK (workspace)

Real array of dimension at least $(2 \times \text{MAX}(N, N_2, N_3) + 32 \times N_3) \times \text{NCPUS}$ where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see `LWORK`).

LWORK (input)

Integer specifying workspace size. If $\text{LWORK} = 0$, the routine will allocate its own workspace.

IERR (output)

On exit, integer `IERR` has one of the following values:

0 = normal return

-1 = $IOPT$ is not 0, 1 or -1

-2 = $N_1 < 0$

-3 = $N_2 < 0$

-4 = $N_3 < 0$

-5 = ($LDX_1 < N_1$)

-6 = ($LDX_2 < N_2$)

-7 = ($LDY_1 < N_1$) or (LDY_1 not equal LDX_1 when X and Y are same array)

-8 = ($LDY_2 < N_2$) or (LDY_2 not equal LDX_2 when X and Y are same array)

-9 = (LWORK not equal 0) and ($\text{LWORK} < (2 \times \text{MAX}(N, N_2, N_3) + 16 \times N_3) \times \text{NCPUS}$)

-10 = memory allocation failed

SEE ALSO

`fft`

CAUTIONS

This routine uses $Y(N_1+1:LDY_1, :, :)$ as scratch space. Therefore, the original contents of this subarray will be lost upon returning from routine while subarray $Y(1:N_1, 1:N_2, 1:N_3)$ contains the transform results.

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NAME

cffftcm - initialize the trigonometric weight and factor tables or compute the one-dimensional Fast Fourier Transform (forward or inverse) of a set of data sequences stored in a two-dimensional complex array.

SYNOPSIS

```
SUBROUTINE CFFFTCM(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
COMPLEX X(LDX, *), Y(LDY, *)  
REAL SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE CFFFTCM_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
REAL SCALE, TRIGS(*), WORK(*)  
COMPLEX X(LDX, *), Y(LDY, *)
```

F95 INTERFACE

```
SUBROUTINE FFTM(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT  
INTEGER*4, INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
COMPLEX, INTENT(IN), DIMENSION(:,) :: X  
COMPLEX, INTENT(OUT), DIMENSION(:,) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFTM_64(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
COMPLEX, INTENT(IN), DIMENSION(:, :) :: X
COMPLEX, INTENT(OUT), DIMENSION(:, :) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void cfftcm_ (int *iopt, int *n1, int *n2, float *scale,
             complex *x, int *ldx, complex *y, int *ldy, float
             *trigs, int *ifac, float *work, int *lwork, int
             *ierr);

void cfftcm_64_ (long *iopt, long *n1, long *n2, float
               *scale, complex *x, long *ldx, complex *y, long
               *ldy, float *trigs, long *ifac, float *work, long
               *lwork, long *ierr);

```

PURPOSE

cfftcm initializes the trigonometric weight and factor tables or computes the one-dimensional Fast Fourier Transform (forward or inverse) of a set of data sequences stored in a two-dimensional complex array:

$$Y(k,l) = \sum_{j=0}^{N1-1} W * X(j,l)$$

where

k ranges from 0 to N1-1 and l ranges from 0 to N2-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

W = exp(isign*i*j*k*2*pi/N1)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT
 IOPT = +1 computes inverse FFT

N1 (input)

Integer specifying length of the input sequences. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)

Integer specifying number of input sequences. N2 >= 0. Unchanged on exit.

SCALE (input)
 Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) X is a complex array of dimensions (LDX, N2) that contains the sequences to be transformed stored in its columns.

LDX (input)
 Leading dimension of X. LDX >= N1 Unchanged on exit.

Y (output)
 Y is a complex array of dimensions (LDY, N2) that contains the transform results of the input sequences. X and Y can be the same array starting at the same memory location, in which case the input sequences are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)
 Leading dimension of Y. If X and Y are the same array, LDY = LDX Else LDY >= N1 Unchanged on exit.

TRIGS (input/output)
 Real array of length 2*N1 that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

IFAC (input/output)
 Integer array of dimension at least 128 that contains the factors of N1. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

WORK (workspace)
 Real array of dimension at least 2*N1*NCPUS where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)
 Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)
 On exit, integer IERR has one of the following values:
 0 = normal return
 -1 = IOPT is not 0, 1 or -1
 -2 = N1 < 0
 -3 = N2 < 0
 -4 = (LDX < N1)
 -5 = (LDY < N1) or (LDY not equal LDX when X and Y are same array)
 -6 = (LWORK not equal 0) and (LWORK < 2*N1*NCPUS)

-7 = memory allocation failed

SEE ALSO

fft

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NAME

cfftf - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of CFFTF followed by a call of CFFTB will multiply the input sequence by N.

SYNOPSIS

```
SUBROUTINE CFFTF(N, X, WSAVE)
```

```
COMPLEX X(*)
INTEGER N
REAL WSAVE(*)
```

```
SUBROUTINE CFFTF_64(N, X, WSAVE)
```

```
COMPLEX X(*)
INTEGER*8 N
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTF([N], X, WSAVE)
```

```
COMPLEX, DIMENSION(:) :: X
INTEGER :: N
REAL, DIMENSION(:) :: WSAVE
```

```
SUBROUTINE FFTF_64([N], X, WSAVE)
```

```
COMPLEX, DIMENSION(:) :: X
INTEGER(8) :: N
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cfftf(int n, complex *x, float *wsave);
```

```
void cfftf_64(long n, complex *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input) On entry, an array of length N containing the sequence to be transformed.

WSAVE (input)
On entry, WSAVE must be an array of dimension $(4 * N + 15)$ or greater and must have been initialized by CFFTI.

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NAME

cffti - initialize the array WSAVE, which is used in both CFFTF and CFFTB.

SYNOPSIS

```
SUBROUTINE CFFTI(N, WSAVE)
```

```
INTEGER N  
REAL WSAVE(*)
```

```
SUBROUTINE CFFTI_64(N, WSAVE)
```

```
INTEGER*8 N  
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE CFFTI(N, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: WSAVE
```

```
SUBROUTINE CFFTI_64(N, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cffti(int n, float *wsave);
```

```
void cffti_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input/output)

On entry, an array of dimension $(4 * N + 15)$ or greater. CFFTI needs to be called only once to initialize array WORK before calling CFFTF and/or CFFTB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

cfftopt - compute the length of the closest fast FFT

SYNOPSIS

```
INTEGER FUNCTION CFFTOPT(LEN)
```

```
INTEGER LEN
```

```
INTEGER*8 FUNCTION CFFTOPT_64(LEN)
```

```
INTEGER*8 LEN
```

F95 INTERFACE

```
INTEGER FUNCTION CFFTOPT(LEN)
```

```
INTEGER :: LEN
```

```
INTEGER(8) FUNCTION CFFTOPT_64(LEN)
```

```
INTEGER(8) :: LEN
```

C INTERFACE

```
#include <sunperf.h>
```

```
int cfftopt(int len);
```

```
long cfftopt_64(long len);
```

PURPOSE

cfftopt computes the length of the closest fast FFT. Fast Fourier transform algorithms, including those used in Performance Library, work best with vector lengths that are products of small primes. For example, an FFT of length $32=2**5$ will run faster than an FFT of prime length 31 because 32 is a product of small primes and 31 is not. If your application is such that you can taper or zero pad your vector to a larger length then this function may help you

select a better length and run your FFT faster.

CFFTOPT will return an integer no smaller than the input argument N that is the closest number that is the product of small primes. CFFTOPT will return 16 for an input of N=16 and return $18=2*3*3$ for an input of N=17.

Note that the length computed here is not guaranteed to be optimal, only to be a product of small primes. Also, the value returned may change as the underlying FFTs become capable of handling larger primes. For example, passing in N=51 today will return $52=2*2*13$ rather than $51=3*17$ because the FFTs in Performance Library do not have fast radix 17 code. In the future, radix 17 code may be added and then N=51 will return 51.

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NAME

`cffts` - initialize the trigonometric weight and factor tables or compute the inverse Fast Fourier Transform of a complex sequence as follows.

SYNOPSIS

```
SUBROUTINE CFFTS(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N, IFAC(*), LWORK, IERR  
COMPLEX X(*)  
REAL SCALE, Y(*), TRIGS(*), WORK(*)
```

```
SUBROUTINE CFFTS_64(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N, IFAC(*), LWORK, IERR  
REAL SCALE, Y(*), TRIGS(*), WORK(*)  
COMPLEX X(*)
```

F95 INTERFACE

```
SUBROUTINE FFT(IOPT, N, [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT, N  
INTEGER*4, INTENT(IN), OPTIONAL :: LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
COMPLEX, INTENT(IN), DIMENSION(:) :: X  
REAL, INTENT(OUT), DIMENSION(:) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT_64(IOPT, N, [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT, N  
INTEGER(8), INTENT(IN), OPTIONAL :: LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
COMPLEX, INTENT(IN), DIMENSION(:) :: X  
REAL, INTENT(OUT), DIMENSION(:) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
```

```

INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>

void cffts_ (int *iopt, int *n, float *scale, complex *x,
            float *y, float *trigs, int *ifac, float *work,
            int *lwork, int *ierr);

void cffts_64_ (long *iopt, long *n, float *scale, complex
               *x, float *y, float *trigs, long *ifac, float
               *work, long *lwork, long *ierr);

```

PURPOSE

cffts initializes the trigonometric weight and factor tables or computes the inverse Fast Fourier Transform of a complex sequence as follows:

$$Y(k) = \text{scale} * \sum_{j=0}^{N-1} W * X(j)$$

where

k ranges from 0 to N-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

$W = \exp(\text{isign} * i * j * k * 2 * \pi / N)$

In complex-to-real transform of length N, the (N/2+1) complex input data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored. Furthermore, due to symmetries the imaginary of the component of X(0) and X(N/2) (if N is even in the latter) is assumed to be zero and is not referenced.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = 1 computes inverse FFT

N (input)

Integer specifying length of the input sequence X. N is most efficient when it is a product of small primes. N >= 0. Unchanged on exit.

SCALE (input)

Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) On entry, X is a complex array whose first $(N/2+1)$ elements are the input sequence to be transformed.

Y (output)

Real array of dimension at least N that contains the transform results. X and Y may be the same array starting at the same memory location. Otherwise, it is assumed that there is no overlap between X and Y in memory.

TRIGS (input/output)

Real array of length $2*N$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 128 that contains the factors of N. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls where IOPT = 1. Unchanged on exit.

WORK (workspace)

Real array of dimension at least N. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

0 = normal return

-1 = IOPT is not 0 or 1

-2 = $N < 0$

-3 = (LWORK is not 0) and (LWORK is less than N)

-4 = memory allocation for workspace failed

SEE ALSO

fft

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NAME

cffts2 - initialize the trigonometric weight and factor tables or compute the two-dimensional inverse Fast Fourier Transform of a two-dimensional complex array.

SYNOPSIS

```
SUBROUTINE CFFTS2(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
COMPLEX X(LDX, *)  
REAL SCALE, Y(LDY, *), TRIGS(*), WORK(*)
```

```
SUBROUTINE CFFTS2_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
COMPLEX X(LDX, *)  
REAL SCALE, Y(LDY, *), TRIGS(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2(IOPT, N1, [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
& IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT, N1  
INTEGER*4, INTENT(IN), OPTIONAL :: N2, LDX, LDY, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
COMPLEX, INTENT(IN), DIMENSION(:, :) :: X  
REAL, INTENT(OUT), DIMENSION(:, :) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT2_64(IOPT, N1, [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT, N1
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N2, LDX, LDY, LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
COMPLEX, INTENT(IN), DIMENSION(:,) :: X
REAL, INTENT(OUT), DIMENSION(:,) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void cffts2_(int *iopt, int *n1, int *n2, float *scale,
             complex *x, int *ldx, float *y, int *ldy, float
             *trigs, int *ifac, float *work, int *lwork, int
             *ierr);

void cffts2_64_(long *iopt, long *n1, long *n2, float
               *scale, complex *x, long *ldx, float *y, long
               *ldy, float *trigs, long *ifac, float *work, long
               *lwork, long *ierr);

```

PURPOSE

cffts2 initializes the trigonometric weight and factor tables or computes the two-dimensional inverse Fast Fourier Transform of a two-dimensional complex array. In computing the two-dimensional FFT, one-dimensional FFTs are computed along the rows of the input array. One-dimensional FFTs are then computed along the columns of the intermediate results.

$$Y(k_1, k_2) = \text{scale} * \sum_{j_1=0}^{N_1-1} \sum_{j_2=0}^{N_2-1} W_2 * W_1 * X(j_1, j_2)$$

where

k₁ ranges from 0 to N₁-1 and k₂ ranges from 0 to N₂-1

i = sqrt(-1)

isign = 1 for inverse transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

In complex-to-real transform of length N₁, the (N₁/2+1) complex input data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = 1 computes inverse FFT

N1 (input)

Integer specifying length of the transform in the

first dimension. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)

Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. N2 >= 0. Unchanged on exit.

SCALE (input)

Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) X is a complex array of dimensions (LDX, N2) that contains input data to be transformed.

LDX (input)

Leading dimension of X. LDX >= (N1/2 + 1) Unchanged on exit.

Y (output)

Y is a real array of dimensions (LDY, N2) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)

Leading dimension of Y. If X and Y are the same array, LDY = 2*LDX Else LDY >= 2*LDX and LDY must be even. Unchanged on exit.

TRIGS (input/output)

Real array of length 2*(N1+N2) that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 2*128 that contains the factors of N1 and N2. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

WORK (workspace)

Real array of dimension at least MAX(N1,2*N2)*NCPUS, where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

0 = normal return
-1 = IOPT is not 0, 1
-2 = N1 < 0
-3 = N2 < 0
-4 = (LDX < N1/2+1)
-5 = LDY not equal 2*LDX when X and Y are same array
-6 = (LDY < 2*LDX or LDY odd) when X and Y are same array
-7 = (LWORK not equal 0) and (LWORK < MAX(N1,2*N2)*NCPUS)
-8 = memory allocation failed

SEE ALSO

fft

CAUTIONS

Y(N1+1:LDY,:) is used as scratch space. Upon returning, the original contents of Y(N1+1:LDY,:) will be lost, whereas Y(1:N1,1:N2) contains the transform results.

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NAME

cffts3 - initialize the trigonometric weight and factor tables or compute the three-dimensional inverse Fast Fourier Transform of a three-dimensional complex array.

SYNOPSIS

```
SUBROUTINE CFFTS3(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,  
IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),  
LWORK, IERR  
COMPLEX X(LDX1, LDX2, *)  
REAL SCALE, TRIGS(*), WORK(*), Y(LDY1, LDY2, *)
```

```
SUBROUTINE CFFTS3_64(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,  
IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),  
LWORK, IERR  
COMPLEX X(LDX1, LDX2, *)  
REAL SCALE, TRIGS(*), WORK(*), Y(LDY1, LDY2, *)
```

F95 INTERFACE

```
SUBROUTINE FFT3(IOPT, N1, [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1], LDY2,  
TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT, N1, LDX2, LDY2  
INTEGER*4, INTENT(IN), OPTIONAL :: N2, N3, LDX1, LDY1, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
COMPLEX, INTENT(IN), DIMENSION(:, :) :: X  
REAL, INTENT(OUT), DIMENSION(:, :) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT3_64(IOPT, N1, [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1], LDY2,
```

```

TRIGS,
          IFAC, WORK, [LWORK], IERR)

INTEGER(8), INTENT(IN) :: IOPT, N1, LDX2, LDY2
INTEGER(8), INTENT(IN), OPTIONAL :: N2, N3, LDX1, LDY1,
LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
COMPLEX, INTENT(IN), DIMENSION(:,:) :: X
REAL, INTENT(OUT), DIMENSION(:,:) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>

void cffts3_ (int *iopt, int *n1, int *n2, int *n3, float
             *scale, complex *x, int *ldx1, int *ldx2, float
             *y, int *ldy1, int *ldy2, float *trigs, int *ifac,
             float *work, int *lwork, int *ierr);

void cffts3_64_ (long *iopt, long *n1, long *n2, long *n3,
                float *scale, complex *x, long *ldx1, long *ldx2,
                float *y, long *ldy1, long *ldy2, float *trigs,
                long *ifac, float *work, long *lwork, long *ierr);

```

PURPOSE

cffts3 initializes the trigonometric weight and factor tables or computes the three-dimensional inverse Fast Fourier Transform of a three-dimensional complex array.

$$Y(k_1, k_2, k_3) = \text{scale} * \sum_{j_3=0}^{N_3-1} \sum_{j_2=0}^{N_2-1} \sum_{j_1=0}^{N_1-1} W_3 * W_2 * W_1 * X(j_1, j_2, j_3)$$

where

k₁ ranges from 0 to N₁-1; k₂ ranges from 0 to N₂-1 and k₃ ranges from 0 to N₃-1

i = sqrt(-1)

isign = 1 for inverse transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

W₃ = exp(isign*i*j₃*k₃*2*pi/N₃)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = +1 computes inverse FFT

N1 (input)

Integer specifying length of the transform in the first dimension. N₁ is most efficient when it is

a product of small primes. $N1 \geq 0$. Unchanged on exit.

N2 (input)

Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. $N2 \geq 0$. Unchanged on exit.

N3 (input)

Integer specifying length of the transform in the third dimension. N3 is most efficient when it is a product of small primes. $N3 \geq 0$. Unchanged on exit.

SCALE (input)

Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) X is a complex array of dimensions (LDX1, LDX2, N3) that contains input data to be transformed.

LDX1 (input)

first dimension of X. $LDX1 \geq N1/2+1$ Unchanged on exit.

LDX2 (input)

second dimension of X. $LDX2 \geq N2$ Unchanged on exit.

Y (output)

Y is a complex array of dimensions (LDY1, LDY2, N3) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY1 (input)

first dimension of Y. If X and Y are the same array, $LDY1 = 2*LDX1$ Else $LDY1 \geq 2*LDX1$ and LDY1 is even Unchanged on exit.

LDY2 (input)

second dimension of Y. If X and Y are the same array, $LDY2 = LDX2$ Else $LDY2 \geq N2$ Unchanged on exit.

TRIGS (input/output)

Real array of length $2*(N1+N2+N3)$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least $3*128$ that contains the factors of N1, N2 and N3. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls

when IOPT = 1. Unchanged on exit.

WORK (workspace)

Real array of dimension at least $(\text{MAX}(N, 2*N2, 2*N3) + 16*N3) * \text{NCPUS}$ where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

- 0 = normal return
- 1 = IOPT is not 0 or 1
- 2 = $N1 < 0$
- 3 = $N2 < 0$
- 4 = $N3 < 0$
- 5 = $(LDX1 < N1/2+1)$
- 6 = $(LDX2 < N2)$
- 7 = LDY1 not equal $2*LDX1$ when X and Y are same array
- 8 = $(LDY1 < 2*LDX1)$ or (LDY1 is odd) when X and Y are not same array
- 9 = $(LDY2 < N2)$ or (LDY2 not equal LDX2) when X and Y are same array
- 10 = (LWORK not equal 0) and $((LWORK < \text{MAX}(N, 2*N2, 2*N3) + 16*N3)*\text{NCPUS})$
- 11 = memory allocation failed

SEE ALSO

fft

CAUTIONS

This routine uses $Y(N1+1:LDY1, :, :)$ as scratch space. Therefore, the original contents of this subarray will be lost upon returning from routine while subarray $Y(1:N1, 1:N2, 1:N3)$ contains the transform results.

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NAME

cfftsm - initialize the trigonometric weight and factor tables or compute the one-dimensional inverse Fast Fourier Transform of a set of complex data sequences stored in a two-dimensional array.

SYNOPSIS

```
SUBROUTINE CFFTSM(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
COMPLEX X(LDX, *)  
REAL SCALE, Y(LDY, *), TRIGS(*), WORK(*)
```

```
SUBROUTINE CFFTSM_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
REAL SCALE, Y(LDY,*), TRIGS(*), WORK(*)  
COMPLEX X(LDX, *)
```

F95 INTERFACE

```
SUBROUTINE FFTM(IOPT, N1, [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT, N1  
INTEGER*4, INTENT(IN), OPTIONAL :: N2, LDX, LDY, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
COMPLEX, INTENT(IN), DIMENSION(:,) :: X  
REAL, INTENT(OUT), DIMENSION(:,) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFTM_64(IOPT, N1, [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT, N1
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N2, LDX, LDY, LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
COMPLEX, INTENT(IN), DIMENSION(:,) :: X
REAL, INTENT(OUT), DIMENSION(:,) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void cfftsm_ (int *iopt, int *n1, int *n2, float *scale,
             complex *x, int *ldx, float *y, int *ldy, float
             *trigs, int *ifac, float *work, int *lwork, int
             *ierr);

void cfftsm_64_ (long *iopt, long *n1, long *n2, float
                *scale, complex *x, long *ldx, float *y, long
                *ldy, float *trigs, long *ifac, float *work, long
                *lwork, long *ierr);

```

PURPOSE

cfftsm initializes the trigonometric weight and factor tables or computes the one-dimensional inverse Fast Fourier Transform of a set of complex data sequences stored in a two-dimensional array:

$$Y(k,l) = \text{scale} * \sum_{j=0}^{N1-1} W * X(j,l)$$

where

k ranges from 0 to N1-1 and l ranges from 0 to N2-1

i = sqrt(-1)

isign = 1 for inverse transform

W = exp(isign*i*j*k*2*pi/N1)

In complex-to-real transform of length N1, the (N1/2+1) complex input data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored. Furthermore, due to symmetries the imaginary of the component of X(0,0:N2-1) and X(N1/2,0:N2-1) (if N1 is even in the latter) is assumed to be zero and is not referenced.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = 1 computes inverse FFT

N1 (input)

Integer specifying length of the input sequences.

N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)

Integer specifying number of input sequences. N2 >= 0. Unchanged on exit.

SCALE (input)

Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) X is a complex array of dimensions (LDX, N2) that contains the sequences to be transformed stored in its columns in X(0:N1/2, 0:N2-1).

LDX (input)

Leading dimension of X. LDX >= (N1/2+1) Unchanged on exit.

Y (output)

Y is a real array of dimensions (LDY, N2) that contains the transform results of the input sequences in Y(0:N1-1,0:N2-1). X and Y can be the same array starting at the same memory location, in which case the input sequences are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)

Leading dimension of Y. If X and Y are the same array, LDY = 2*LDX Else LDY >= N1 Unchanged on exit.

TRIGS (input/output)

Real array of length 2*N1 that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 128 that contains the factors of N1. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

WORK (workspace)

Real array of dimension at least N1. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:
0 = normal return

-1 = IOPT is not 0 or 1
-2 = N1 < 0
-3 = N2 < 0
-4 = (LDX < N1/2+1)
-5 = (LDY < N1) or (LDY not equal 2*LDX when X and
Y are same array)
-6 = (LWORK not equal 0) and (LWORK < N1)
-7 = memory allocation failed

SEE ALSO

fft

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NAME

cgbbird - reduce a complex general m-by-n band matrix A to real upper bidiagonal form B by a unitary transformation

SYNOPSIS

```
SUBROUTINE CGBBRD(VECT, M, N, NCC, KL, KU, AB, LDAB, D, E, Q, LDQ,  
PT, LDPT, C, LDC, WORK, RWORK, INFO)
```

```
CHARACTER * 1 VECT  
COMPLEX AB(LDAB,*), Q(LDQ,*), PT(LDPT,*), C(LDC,*), WORK(*)  
INTEGER M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL D(*), E(*), RWORK(*)
```

```
SUBROUTINE CGBBRD_64(VECT, M, N, NCC, KL, KU, AB, LDAB, D, E, Q, LDQ,  
PT, LDPT, C, LDC, WORK, RWORK, INFO)
```

```
CHARACTER * 1 VECT  
COMPLEX AB(LDAB,*), Q(LDQ,*), PT(LDPT,*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL D(*), E(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBBRD(VECT, M, [N], [NCC], KL, KU, AB, [LDAB], D, E, Q,  
[LDQ], PT, [LDPT], C, [LDC], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: AB, Q, PT, C  
INTEGER :: M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL, DIMENSION(:) :: D, E, RWORK
```

```
SUBROUTINE GBBRD_64(VECT, M, [N], [NCC], KL, KU, AB, [LDAB], D, E,  
Q, [LDQ], PT, [LDPT], C, [LDC], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: AB, Q, PT, C  
INTEGER(8) :: M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL, DIMENSION(:) :: D, E, RWORK
```

C INTERFACE

```
#include <sunperf.h>

void cgbbrd(char vect, int m, int n, int ncc, int kl, int
            ku, complex *ab, int ldab, float *d, float *e,
            complex *q, int ldq, complex *pt, int ldpt, com-
            plex *c, int ldc, int *info);
void cgbbrd_64(char vect, long m, long n, long ncc, long kl,
               long ku, complex *ab, long ldab, float *d, float
               *e, complex *q, long ldq, complex *pt, long ldpt,
               complex *c, long ldc, long *info);
```

PURPOSE

cgbbrd reduces a complex general m-by-n band matrix A to real upper bidiagonal form B by a unitary transformation: $Q^* A P = B$.

The routine computes B, and optionally forms Q or P', or computes Q^*C for a given matrix C.

ARGUMENTS

VECT (input)

Specifies whether or not the matrices Q and P' are to be formed. = 'N': do not form Q or P';
= 'Q': form Q only;
= 'P': form P' only;
= 'B': form both.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NCC (input)

The number of columns of the matrix C. $NCC \geq 0$.

KL (input)

The number of subdiagonals of the matrix A. $KL \geq 0$.

KU (input)

The number of superdiagonals of the matrix A. $KU \geq 0$.

AB (input/output)

On entry, the m-by-n band matrix A, stored in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array AB as follows:
 $AB(ku+1+i-j, j) = A(i, j)$ for $\max(1, j-ku) \leq i \leq \min(m, j+kl)$. On exit, A is overwritten by values generated during the reduction.

LDAB (input)

The leading dimension of the array A. $LDAB \geq KL+KU+1$.

D (output)
The diagonal elements of the bidiagonal matrix B.

E (output)
The superdiagonal elements of the bidiagonal matrix B.

Q (output)
If VECT = 'Q' or 'B', the m-by-m unitary matrix Q.
If VECT = 'N' or 'P', the array Q is not referenced.

LDQ (input)
The leading dimension of the array Q. LDQ \geq max(1,M) if VECT = 'Q' or 'B'; LDQ \geq 1 otherwise.

PT (output)
If VECT = 'P' or 'B', the n-by-n unitary matrix P'. If VECT = 'N' or 'Q', the array PT is not referenced.

LDPT (input)
The leading dimension of the array PT. LDPT \geq max(1,N) if VECT = 'P' or 'B'; LDPT \geq 1 otherwise.

C (input/output)
On entry, an m-by-ncc matrix C. On exit, C is overwritten by Q'*C. C is not referenced if NCC = 0.

LDC (input)
The leading dimension of the array C. LDC \geq max(1,M) if NCC > 0; LDC \geq 1 if NCC = 0.

WORK (workspace)
dimension(MAX(M,N))

RWORK (workspace)
dimension(MAX(M,N))

INFO (output)
= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

cgbbcon - estimate the reciprocal of the condition number of a complex general band matrix A, in either the 1-norm or the infinity-norm,

SYNOPSIS

```
SUBROUTINE CGBBCON(NORM, N, KL, KU, A, LDA, IPIVOT, ANORM,
                  RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM
COMPLEX A(LDA,*), WORK(*)
INTEGER N, KL, KU, LDA, INFO
INTEGER IPIVOT(*)
REAL ANORM, RCOND
REAL WORK2(*)
```

```
SUBROUTINE CGBBCON_64(NORM, N, KL, KU, A, LDA, IPIVOT, ANORM,
                    RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM
COMPLEX A(LDA,*), WORK(*)
INTEGER*8 N, KL, KU, LDA, INFO
INTEGER*8 IPIVOT(*)
REAL ANORM, RCOND
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GBBCON(NORM, [N], KL, KU, A, [LDA], IPIVOT, ANORM,
                 RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER :: N, KL, KU, LDA, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE GBBCON_64(NORM, [N], KL, KU, A, [LDA], IPIVOT, ANORM,
                   RCOND, [WORK], [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: NORM
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER(8) :: N, KL, KU, LDA, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>

void cgbcon(char norm, int n, int kl, int ku, complex *a,
            int lda, int *ipivot, float anorm, float *rcond,
            int *info);

void cgbcon_64(char norm, long n, long kl, long ku, complex
               *a, long lda, long *ipivot, float anorm, float
               *rcond, long *info);

```

PURPOSE

cgbcon estimates the reciprocal of the condition number of a complex general band matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by CGBTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A)))$$

ARGUMENTS

NORM (input)
 Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
 = '1' or 'O': 1-norm;
 = 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)
 The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
 The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input) Details of the LU factorization of the band matrix A, as computed by CGBTRF. U is stored as an upper triangular band matrix with $KL+KU$ superdiagonals in rows 1 to $KL+KU+1$, and the multipliers used during the factorization are stored in rows $KL+KU+2$ to $2*KL+KU+1$.

LDA (input)
 The leading dimension of the array A. $LDA \geq$

$2*KL+KU+1.$

IPIVOT (input)

The pivot indices; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension($2*N$)

WORK2 (workspace)

dimension (N)

INFO (output)

= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

cgbequ - compute row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number

SYNOPSIS

```
SUBROUTINE CGBEQU(M, N, KL, KU, A, LDA, R, C, ROWCND,  
                 COLCND, AMAX, INFO)
```

```
COMPLEX A(LDA,*)  
INTEGER M, N, KL, KU, LDA, INFO  
REAL ROWCND, COLCND, AMAX  
REAL R(*), C(*)
```

```
SUBROUTINE CGBEQU_64(M, N, KL, KU, A, LDA, R, C,  
                   ROWCND, COLCND, AMAX, INFO)
```

```
COMPLEX A(LDA,*)  
INTEGER*8 M, N, KL, KU, LDA, INFO  
REAL ROWCND, COLCND, AMAX  
REAL R(*), C(*)
```

F95 INTERFACE

```
SUBROUTINE GBEQU([M], [N], KL, KU, A, [LDA], R, C,  
                ROWCND, COLCND, AMAX, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, KL, KU, LDA, INFO  
REAL :: ROWCND, COLCND, AMAX  
REAL, DIMENSION(:) :: R, C
```

```
SUBROUTINE GBEQU_64([M], [N], KL, KU, A, [LDA], R, C,  
                   ROWCND, COLCND, AMAX, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, KL, KU, LDA, INFO  
REAL :: ROWCND, COLCND, AMAX  
REAL, DIMENSION(:) :: R, C
```

C INTERFACE

```
#include <sunperf.h>

void cgbequ(int m, int n, int kl, int ku, complex *a, int
            lda, float *r, float *c, float *rowcnd, float
            *colcnd, float *amax, int *info);
void cgbequ_64(long m, long n, long kl, long ku, complex *a,
              long lda, float *r, float *c, float *rowcnd, float
              *colcnd, float *amax, long *info);
```

PURPOSE

cgbequ computes row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number. R returns the row scale factors and C the column scale factors, chosen to try to make the largest element in each row and column of the matrix B with elements $B(i,j)=R(i)*A(i,j)*C(j)$ have absolute value 1.

R(i) and C(j) are restricted to be between SMLNUM = smallest safe number and BIGNUM = largest safe number. Use of these scaling factors is not guaranteed to reduce the condition number of A but works well in practice.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input) The band matrix A, stored in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array A as follows: $A(ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$.

LDA (input)
The leading dimension of the array A. $LDA \geq KL+KU+1$.

R (output)
If $INFO = 0$, or $INFO > M$, R contains the row scale factors for A.

C (output)
If $INFO = 0$, C contains the column scale factors for A.

ROWCND (output)
If $INFO = 0$ or $INFO > M$, ROWCND contains the ratio of the smallest R(i) to the largest R(i). If

ROWCND \geq 0.1 and AMAX is neither too large nor too small, it is not worth scaling by R.

COLCND (output)

If INFO = 0, COLCND contains the ratio of the smallest C(i) to the largest C(i). If COLCND \geq 0.1, it is not worth scaling by C.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= M: the i-th row of A is exactly zero
> M: the (i-M)-th column of A is exactly zero

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NAME

cgbmv - perform one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A' x + \beta y$, or $y := \alpha \text{conjg}(A') x + \beta y$

SYNOPSIS

```
SUBROUTINE CGBMV(TRANSA, M, N, KL, KU, ALPHA, A, LDA, X, INCX,
                BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), X(*), Y(*)
INTEGER M, N, KL, KU, LDA, INCX, INCY
```

```
SUBROUTINE CGBMV_64(TRANSA, M, N, KL, KU, ALPHA, A, LDA, X,
                   INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), X(*), Y(*)
INTEGER*8 M, N, KL, KU, LDA, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE GBMV([TRANSA], [M], [N], KL, KU, ALPHA, A, [LDA], X,
                [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:) :: X, Y
COMPLEX, DIMENSION(:, :) :: A
INTEGER :: M, N, KL, KU, LDA, INCX, INCY
```

```
SUBROUTINE GBMV_64([TRANSA], [M], [N], KL, KU, ALPHA, A, [LDA],
                  X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:) :: X, Y
COMPLEX, DIMENSION(:, :) :: A
INTEGER(8) :: M, N, KL, KU, LDA, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>

void cgbmv(char transa, int m, int n, int kl, int ku, complex
 *alpha, complex *a, int lda, complex *x, int incx, complex
 *beta, complex *y, int incy);
void cgbmv_64(char transa, long m, long n, long kl, long ku,
 complex *alpha, complex *a, long lda, complex *x,
 long incx, complex *beta, complex *y, long incy);
```

PURPOSE

cgbmv performs one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A' x + \beta y$, or $y := \alpha \text{conjg}(A') x + \beta y$ where α and β are scalars, x and y are vectors and A is an m by n band matrix, with kl sub-diagonals and ku super-diagonals.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $y := \alpha A x + \beta y$.

TRANSA = 'T' or 't' $y := \alpha A' x + \beta y$.

TRANSA = 'C' or 'c' $y := \alpha \text{conjg}(A') x + \beta y$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix A. M must be at least zero. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. N must be at least zero. Unchanged on exit.

KL (input)

On entry, KL specifies the number of sub-diagonals of the matrix A. KL must satisfy $0 \leq KL$. Unchanged on exit.

KU (input)

On entry, KU specifies the number of super-diagonals of the matrix A. KU must satisfy $0 \leq KU$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry, the leading ($kl + ku + 1$) by n part of the array A must contain the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row ($ku + 1$) of the array, the first super-diagonal starting at position 2 in row ku , the first sub-diagonal starting at position 1 in row ($ku + 2$), and so on. Elements in the array A that do not correspond to elements in the band matrix (such as the top left ku by ku triangle) are not referenced. The following program segment will transfer a band matrix from conventional full matrix storage to band storage:

```
      DO 20, J = 1, N
        K = KU + 1 - J
        DO 10, I = MAX( 1, J - KU ), MIN( M, J + KL
          )
          A( K + I, J ) = matrix( I, J )
10      CONTINUE
20     CONTINUE
```

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA must be at least ($kl + ku + 1$). Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$) when TRANSA = 'N' or 'n' and at least ($1 + (m - 1) * \text{abs}(\text{INCX})$) otherwise. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

($1 + (m - 1) * \text{abs}(\text{INCY})$) when TRANSA = 'N' or 'n' and at least ($1 + (n - 1) * \text{abs}(\text{INCY})$) otherwise. Before entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

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NAME

cgbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CGBRFS(TRANSA, N, KL, KU, NRHS, A, LDA, AF, LDAF,
  IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*)
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CGBRFS_64(TRANSA, N, KL, KU, NRHS, A, LDA, AF, LDAF,
  IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GBRFS([TRANSA], [N], KL, KU, [NRHS], A, [LDA], AF,
  [LDAF], IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2],
  [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE GBRFS_64([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  AF, [LDAF], IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
  [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: TRANSA
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void cgbrfs(char transa, int n, int kl, int ku, int nrhs,
            complex *a, int lda, complex *af, int ldaf, int
            *ipivot, complex *b, int ldb, complex *x, int ldx,
            float *ferr, float *berr, int *info);

void cgbrfs_64(char transa, long n, long kl, long ku, long
              nrhs, complex *a, long lda, complex *af, long
              ldaf, long *ipivot, complex *b, long ldb, complex
              *x, long ldx, float *ferr, float *berr, long
              *info);

```

PURPOSE

cgbrfs improves the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)
 Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose)
 TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)
 The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
 The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The original band matrix A, stored in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array A as follows: $A(ku+1+i-j, j) = A(i, j)$ for $\max(1, j-ku) \leq i \leq \min(n, j+kl)$.

LDA (input)
 The leading dimension of the array A. LDA \geq KL+KU+1.

AF (input)
 Details of the LU factorization of the band matrix A, as computed by CGBTRF. U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1.

LDAF (input)
 The leading dimension of the array AF. LDAF \geq 2*KL*KU+1.

IPIVOT (input)
 The pivot indices from CGBTRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input) The right hand side matrix B.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
 On entry, the solution matrix X, as computed by CGBTRS. On exit, the improved solution matrix X.

LDX (input)
 The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(2*N)

WORK2 (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-

gal value

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NAME

cgbsv - compute the solution to a complex system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE CGBSV(N, KL, KU, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*)
INTEGER N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE CGBSV_64(N, KL, KU, NRHS, A, LDA, IPIVOT, B, LDB,
INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*)
INTEGER*8 N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GBSV([N], KL, KU, [NRHS], A, [LDA], IPIVOT, B, [LDB],
[INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GBSV_64([N], KL, KU, [NRHS], A, [LDA], IPIVOT, B,
[LDB], [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void cgbsv(int n, int kl, int ku, int nrhs, complex *a, int
           lda, int *ipivot, complex *b, int ldb, int *info);

void cgbsv_64(long n, long kl, long ku, long nrhs, complex
              *a, long lda, long *ipivot, complex *b, long ldb,
              long *info);

```

PURPOSE

cgbsv computes the solution to a complex system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices.

The LU decomposition with partial pivoting and row interchanges is used to factor A as $A = L * U$, where L is a product of permutation and unit lower triangular matrices with KL subdiagonals, and U is upper triangular with KL+KU superdiagonals. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A. $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A. $KU \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array A as follows:

$$A(KL+KU+1+i-j, j) = A(i, j) \quad \text{for } \max(1, j-KU) \leq i \leq \min(N, j+KL)$$
 On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDA (input)
The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (output)
The pivot indices that define the permutation

matrix P; row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)

On entry, the N-by-NRHS right hand side matrix B.
On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and the solution has not been computed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when M = N = 6, KL = 2, KU = 1:

On entry:

On exit:

	*	*	*	+	+	+		*	*	*	u14	u25	
u36								*	*		u13	u24	u35
u46								*	u12	u23	u34	u45	
u56	a11	a22	a33	a44	a55	a66	u11	u22	u33	u44	u55		
u66	a21	a32	a43	a54	a65	*	m21	m32	m43	m54	m65		
*													
*	a31	a42	a53	a64	*	*	m31	m42	m53	m64	*		
*													

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U because of fill-in resulting from the row interchanges.

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NAME

cgbsvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{*T} * X = B$, or $A^{*H} * X = B$,

SYNOPSIS

```
SUBROUTINE CGBSVX(FACT, TRANSA, N, KL, KU, NRHS, A, LDA, AF,
  LDAF, IPIVOT, EQUED, R, C, B, LDB, X, LDX, RCOND, FERR,
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*)
REAL RCOND
REAL R(*), C(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CGBSVX_64(FACT, TRANSA, N, KL, KU, NRHS, A, LDA, AF,
  LDAF, IPIVOT, EQUED, R, C, B, LDB, X, LDX, RCOND, FERR,
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
REAL RCOND
REAL R(*), C(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GBSVX(FACT, [TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  AF, [LDAF], IPIVOT, EQUED, R, C, B, [LDB], X, [LDX],
  RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: R, C, FERR, BERR, WORK2
```

```

SUBROUTINE GBSVX_64(FACT, [TRANSA], [N], KL, KU, [NRHS], A,
  [LDA], AF, [LDAF], IPIVOT, EQUED, R, C, B, [LDB], X, [LDX],
  RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: R, C, FERR, BERR, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void cgbsvx(char fact, char transa, int n, int kl, int ku,
  int nrhs, complex *a, int lda, complex *af, int
  ldaf, int *ipivot, char equed, float *r, float *c,
  complex *b, int ldb, complex *x, int ldx, float
  *rcond, float *ferr, float *berr, int *info);

```

```

void cgbsvx_64(char fact, char transa, long n, long kl, long
  ku, long nrhs, complex *a, long lda, complex *af,
  long ldaf, long *ipivot, char equed, float *r,
  float *c, complex *b, long ldb, complex *x, long
  ldx, float *rcond, float *ferr, float *berr, long
  *info);

```

PURPOSE

cgbsvx uses the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed by this subroutine:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$TRANS = 'N'$: $diag(R)*A*diag(C) * inv(diag(C))*X = diag(R)*B$

$TRANS = 'T'$: $(diag(R)*A*diag(C))^{**T} * inv(diag(R))*X = diag(C)*B$

$TRANS = 'C'$: $(diag(R)*A*diag(C))^{**H} * inv(diag(R))*X = diag(C)*B$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A is

overwritten by $diag(R)*A*diag(C)$ and B by $diag(R)*B$ (if $TRANS='N'$)

or $diag(C)*B$ (if $TRANS = 'T'$ or $'C'$).

2. If FACT = 'N' or 'E', the LU decomposition is used to factor the matrix A (after equilibration if FACT = 'E') as

$$A = L * U,$$
 where L is a product of permutation and unit lower triangular matrices with KL subdiagonals, and U is upper triangular with KL+KU superdiagonals.
3. If some U(i,i)=0, so that U is exactly singular, then the routine returns with INFO = i. Otherwise, the factored form of A is used to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
4. The system of equations is solved for X using the factored form of A.
5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.
6. If equilibration was used, the matrix X is premultiplied by diag(C) (if TRANS = 'N') or diag(R) (if TRANS = 'T' or 'C') so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF and IPIVOT contain the factored form of A. If EQUED is not 'N', the matrix A has been equilibrated with scaling factors given by R and C. A, AF, and IPIVOT are not modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

TRANSA (input)

Specifies the form of the system of equations. = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)
On entry, the matrix A in band storage, in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array A as follows: $A(KU+1+i-j, j) = A(i, j)$ for $\max(1, j-KU) \leq i \leq \min(N, j+KL)$

If FACT = 'F' and EQUED is not 'N', then A must have been equilibrated by the scaling factors in R and/or C. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if EQUED .ne. 'N', A is scaled as follows:
EQUED = 'R': $A := \text{diag}(R) * A$
EQUED = 'C': $A := A * \text{diag}(C)$
EQUED = 'B': $A := \text{diag}(R) * A * \text{diag}(C)$.

LDA (input)
The leading dimension of the array A. $LDA \geq KL+KU+1$.

AF (input or output)
If FACT = 'F', then AF is an input argument and on entry contains details of the LU factorization of the band matrix A, as computed by CGBTRF. U is stored as an upper triangular band matrix with $KL+KU$ superdiagonals in rows 1 to $KL+KU+1$, and the multipliers used during the factorization are stored in rows $KL+KU+2$ to $2*KL+KU+1$. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns details of the LU factorization of A.

If FACT = 'E', then AF is an output argument and on exit returns details of the LU factorization of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)
The leading dimension of the array AF. $LDAF \geq 2*KL+KU+1$.

IPIVOT (input)

If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the factorization $A = L*U$ as computed by CGBTRF; row i of the matrix was interchanged with row IPIVOT(i).

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = L*U$ of the original matrix A.

If FACT = 'E', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = L*U$ of the equilibrated matrix A.

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'R': Row equilibration, i.e., A has been premultiplied by diag(R). = 'C': Column equilibration, i.e., A has been postmultiplied by diag(C). = 'B': Both row and column equilibration, i.e., A has been replaced by $\text{diag}(R) * A * \text{diag}(C)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

R (input or output)

The row scale factors for A. If EQUED = 'R' or 'B', A is multiplied on the left by diag(R); if EQUED = 'N' or 'C', R is not accessed. R is an input argument if FACT = 'F'; otherwise, R is an output argument. If FACT = 'F' and EQUED = 'R' or 'B', each element of R must be positive.

C (input or output)

The column scale factors for A. If EQUED = 'C' or 'B', A is multiplied on the right by diag(C); if EQUED = 'N' or 'R', C is not accessed. C is an input argument if FACT = 'F'; otherwise, C is an output argument. If FACT = 'F' and EQUED = 'C' or 'B', each element of C must be positive.

B (input/output)

On entry, the right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if TRANSA = 'N' and EQUED = 'R' or 'B', B is overwritten by $\text{diag}(R)*B$; if TRANSA = 'T' or 'C' and EQUED = 'C' or 'B', B is overwritten by $\text{diag}(C)*B$.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that A and B are modified on exit if EQUED .ne. 'N', and the solution to the equilibrated system is $\text{inv}(\text{diag}(C))*X$ if TRANSA = 'N' and EQUED = 'C' or 'B', or $\text{inv}(\text{diag}(R))*X$ if TRANSA = 'T' or 'C' and EQUED = 'R' or 'B'.

LDX (input)
 The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)
 The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(2*N)

WORK2 (workspace)
 dimension(N) On exit, WORK2(1) contains the reciprocal pivot growth factor norm(A)/norm(U). The "max absolute element" norm is used. If WORK2(1) is much less than 1, then the stability of the LU factorization of the (equilibrated) matrix A could be poor. This also means that the solution X, condition estimator RCOND, and forward error bound FERR could be unreliable. If factorization fails with $0 < \text{INFO} \leq N$, then WORK2(1) contains the reciprocal pivot growth factor for the leading INFO columns of A.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, and i is
 <= N: U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned.
 = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would

suggest .

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NAME

cgbtbf2 - compute an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE CGBTF2(M, N, KL, KU, AB, LDAB, IPIV, INFO)
```

```
COMPLEX AB(LDAB,*)  
INTEGER M, N, KL, KU, LDAB, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE CGBTF2_64(M, N, KL, KU, AB, LDAB, IPIV, INFO)
```

```
COMPLEX AB(LDAB,*)  
INTEGER*8 M, N, KL, KU, LDAB, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE GBTF2([M], [N], KL, KU, AB, [LDAB], IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: AB  
INTEGER :: M, N, KL, KU, LDAB, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE GBTF2_64([M], [N], KL, KU, AB, [LDAB], IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: AB  
INTEGER(8) :: M, N, KL, KU, LDAB, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgbtf2(int m, int n, int kl, int ku, complex *ab, int  
          ldab, int *ipiv, int *info);
```

```
void cgbtf2_64(long m, long n, long kl, long ku, complex  
             *ab, long ldab, long *ipiv, long *info);
```

PURPOSE

cgbtf2 computes an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

AB (input/output)
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array AB as follows:
 $AB(kl+ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$

On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDAB (input)
The leading dimension of the array AB. $LDAB \geq 2*KL+KU+1$.

IPIV (output)
The pivot indices; for $1 \leq i \leq \min(M,N)$, row i of the matrix was interchanged with row IPIV(i).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = +i, U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $M = N = 6$, $KL = 2$, $KU = 1$:

On entry:	On exit:
* * * + + +	* * * u14 u25
u36	
* * + + + +	* * u13 u24 u35
u46	
* a12 a23 a34 a45 a56	* u12 u23 u34 u45
u56	
a11 a22 a33 a44 a55 a66	u11 u22 u33 u44 u55
u66	
a21 a32 a43 a54 a65 *	m21 m32 m43 m54 m65
*	
a31 a42 a53 a64 * *	m31 m42 m53 m64 *
*	

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U, because of fill-in resulting from the row interchanges.

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NAME

cgbtrf - compute an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE CGBTRF(M, N, KL, KU, A, LDA, IPIVOT, INFO)
```

```
COMPLEX A(LDA,N)
INTEGER M, N, KL, KU, LDA, INFO
INTEGER IPIVOT(MIN(M,N))
```

```
SUBROUTINE CGBTRF_64(M, N, KL, KU, A, LDA, IPIVOT, INFO)
```

```
COMPLEX A(LDA,N)
INTEGER*8 M, N, KL, KU, LDA, INFO
INTEGER*8 IPIVOT(MIN(M,N))
```

F95 INTERFACE

```
SUBROUTINE GBTRF(M, [N], KL, KU, A, [LDA], IPIVOT, [INFO])
```

```
COMPLEX, DIMENSION(:,:) :: A
INTEGER :: M, N, KL, KU, LDA, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GBTRF_64(M, [N], KL, KU, A, [LDA], IPIVOT, [INFO])
```

```
COMPLEX, DIMENSION(:,:) :: A
INTEGER(8) :: M, N, KL, KU, LDA, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgbtrf(int m, int n, int kl, int ku, complex *a, int
           lda, int *ipivot, int *info);
```

```
void cgbtrf_64(long m, long n, long kl, long ku, complex *a,
              long lda, long *ipivot, long *info);
```

PURPOSE

cgbtrf computes an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

M (input) Integer
The number of rows of the matrix A. $M \geq 0$.

N (input) Integer
The number of columns of the matrix A. $N \geq 0$.

KL (input) Integer
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input) Integer
The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input/output) Complex array of dimension (LDA,N).
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The J-th column of A is stored in the J-th column of the array A as follows:
 $A(KL+KU+1+I-J, J) = A(I, J)$ for $\text{MAX}(1, J-KU) \leq I \leq \text{MIN}(M, J+KL)$
On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDA (input) Integer
The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (output) Integer array of dimension MIN(M,N)
The pivot indices; for $1 \leq I \leq \text{MIN}(M, N)$, row I of the matrix was interchanged with row IPIVOT(I).

INFO (output) Integer
= 0: successful exit
< 0: if INFO = -I, the I-th argument had an illegal value
> 0: if INFO = +I, U(I,I) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equa-

tions.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $M = N = 6$, $KL = 2$, $KU = 1$:

On entry:						On exit:					
* * *	+	+	+			* * *	u14	u25			
u36	* * +	+	+	+		* * u13	u24	u35			
u46	* a12	a23	a34	a45	a56	* u12	u23	u34	u45		
u56	a11	a22	a33	a44	a55	a66	u11	u22	u33	u44	u55
u66	a21	a32	a43	a54	a65	*	m21	m32	m43	m54	m65
*	a31	a42	a53	a64	*	*	m31	m42	m53	m64	*
*											

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U because of fill-in resulting from the row interchanges.

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NAME

cgbtrs - solve a system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$ with a general band matrix A using the LU factorization computed by CGBTRF

SYNOPSIS

```
SUBROUTINE CGBTRS(TRANSA, N, KL, KU, NRHS, A, LDA, IPIVOT, B,
  LDB, INFO)
```

```
CHARACTER * 1 TRANSA
COMPLEX A(LDA,*), B(LDB,*)
INTEGER N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE CGBTRS_64(TRANSA, N, KL, KU, NRHS, A, LDA, IPIVOT,
  B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA
COMPLEX A(LDA,*), B(LDB,*)
INTEGER*8 N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GBTRS([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX, DIMENSION(:,*) :: A, B
INTEGER :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GBTRS_64([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX, DIMENSION(:,*) :: A, B
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void cgbtrs(char transa, int n, int kl, int ku, int nrhs,
            complex *a, int lda, int *ipivot, complex *b, int
            ldb, int *info);
void cgbtrs_64(char transa, long n, long kl, long ku, long
               nrhs, complex *a, long lda, long *ipivot, complex
               *b, long ldb, long *info);
```

PURPOSE

cgbtrs solves a system of linear equations
 $A * X = B$, $A^{*T} * X = B$, or $A^{*H} * X = B$ with a general band matrix A using the LU factorization computed by CGBTRF.

ARGUMENTS

TRANSA (input)
 Specifies the form of the system of equations. =
 'N': $A * X = B$ (No transpose)
 = 'T': $A^{*T} * X = B$ (Transpose)
 = 'C': $A^{*H} * X = B$ (Conjugate transpose)
 TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)
 The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
 The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) Details of the LU factorization of the band matrix A, as computed by CGBTRF. U is stored as an upper triangular band matrix with $KL+KU$ superdiagonals in rows 1 to $KL+KU+1$, and the multipliers used during the factorization are stored in rows $KL+KU+2$ to $2*KL+KU+1$.

LDA (input)
 The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (input)
 The pivot indices; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)
 On entry, the right hand side matrix B. On exit,

the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cgebak - form the right or left eigenvectors of a complex general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by CGEBAL

SYNOPSIS

```
SUBROUTINE CGEBAK(JOB, SIDE, N, ILO, IHI, SCALE, M, V, LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE  
COMPLEX V(LDV,*)  
INTEGER N, ILO, IHI, M, LDV, INFO  
REAL SCALE(*)
```

```
SUBROUTINE CGEBAK_64(JOB, SIDE, N, ILO, IHI, SCALE, M, V, LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE  
COMPLEX V(LDV,*)  
INTEGER*8 N, ILO, IHI, M, LDV, INFO  
REAL SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE GEBAK(JOB, SIDE, [N], ILO, IHI, SCALE, [M], V, [LDV],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE  
COMPLEX, DIMENSION(:, :) :: V  
INTEGER :: N, ILO, IHI, M, LDV, INFO  
REAL, DIMENSION(:) :: SCALE
```

```
SUBROUTINE GEBAK_64(JOB, SIDE, [N], ILO, IHI, SCALE, [M], V, [LDV],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE  
COMPLEX, DIMENSION(:, :) :: V  
INTEGER(8) :: N, ILO, IHI, M, LDV, INFO  
REAL, DIMENSION(:) :: SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgebak(char job, char side, int n, int ilo, int ihi,
            float *scale, int m, complex *v, int ldv, int
            *info);
```

```
void cgebak_64(char job, char side, long n, long ilo, long
               ihi, float *scale, long m, complex *v, long ldv,
               long *info);
```

PURPOSE

cgebak forms the right or left eigenvectors of a complex general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by CGEBAL.

ARGUMENTS

JOB (input)

Specifies the type of backward transformation required: = 'N', do nothing, return immediately; = 'P', do backward transformation for permutation only; = 'S', do backward transformation for scaling only; = 'B', do backward transformations for both permutation and scaling. JOB must be the same as the argument JOB supplied to CGEBAL.

SIDE (input)

= 'R': V contains right eigenvectors;
= 'L': V contains left eigenvectors.

N (input) The number of rows of the matrix V. $N \geq 0$.

ILO (input)

The integer ILO determined by CGEBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

IHI (input)

The integer IHI determined by CGEBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

SCALE (input)

Details of the permutation and scaling factors, as returned by CGEBAL.

M (input) The number of columns of the matrix V. $M \geq 0$.

V (input/output)

On entry, the matrix of right or left eigenvectors to be transformed, as returned by CHSEIN or CTREVC. On exit, V is overwritten by the transformed eigenvectors.

LDV (input)

The leading dimension of the array V. $LDV \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

cgebal - balance a general complex matrix A

SYNOPSIS

```
SUBROUTINE CGEBAL(JOB, N, A, LDA, ILO, IHI, SCALE, INFO)
```

```
CHARACTER * 1 JOB  
COMPLEX A(LDA,*)  
INTEGER N, LDA, ILO, IHI, INFO  
REAL SCALE(*)
```

```
SUBROUTINE CGEBAL_64(JOB, N, A, LDA, ILO, IHI, SCALE, INFO)
```

```
CHARACTER * 1 JOB  
COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, ILO, IHI, INFO  
REAL SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE GEBAL(JOB, [N], A, [LDA], ILO, IHI, SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, ILO, IHI, INFO  
REAL, DIMENSION(:) :: SCALE
```

```
SUBROUTINE GEBAL_64(JOB, [N], A, [LDA], ILO, IHI, SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, ILO, IHI, INFO  
REAL, DIMENSION(:) :: SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgebal(char job, int n, complex *a, int lda, int *ilo,  
            int *ihi, float *scale, int *info);
```

```
void cgebal_64(char job, long n, complex *a, long lda, long
               *ilo, long *ihi, float *scale, long *info);
```

PURPOSE

cgebal balances a general complex matrix A. This involves, first, permuting A by a similarity transformation to isolate eigenvalues in the first 1 to ILO-1 and last IHI+1 to N elements on the diagonal; and second, applying a diagonal similarity transformation to rows and columns ILO to IHI to make the rows and columns as close in norm as possible. Both steps are optional.

Balancing may reduce the 1-norm of the matrix, and improve the accuracy of the computed eigenvalues and/or eigenvectors.

ARGUMENTS

JOB (input)

Specifies the operations to be performed on A:
= 'N': none: simply set ILO = 1, IHI = N,
SCALE(I) = 1.0 for i = 1,...,N; = 'P': permute
only;
= 'S': scale only;
= 'B': both permute and scale.

N (input) The order of the matrix A. N >= 0.

A (input/output)

On entry, the input matrix A. On exit, A is
overwritten by the balanced matrix. If JOB = 'N',
A is not referenced. See Further Details.

LDA (input)

The leading dimension of the array A. LDA >=
max(1,N).

ILO (output)

ILO and IHI are set to integers such that on exit
A(i,j) = 0 if i > j and j = 1,...,ILO-1 or I =
IHI+1,...,N. If JOB = 'N' or 'S', ILO = 1 and IHI
= N.

IHI (output)

ILO and IHI are set to integers such that on exit
A(i,j) = 0 if i > j and j = 1,...,ILO-1 or I =
IHI+1,...,N. If JOB = 'N' or 'S', ILO = 1 and IHI
= N.

SCALE (output)

Details of the permutations and scaling factors
applied to A. If P(j) is the index of the row and
column interchanged with row and column j and D(j)
is the scaling factor applied to row and column j,

then SCALE(j) = P(j) for j = 1,...,ILO-1 = D(j)
 for j = ILO,...,IHI = P(j) for j = IHI+1,...,N.
 The order in which the interchanges are made is N
 to IHI+1, then 1 to ILO-1.

INFO (output)

= 0: successful exit.
 < 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The permutations consist of row and column interchanges which put the matrix in the form

$$P A P = \begin{pmatrix} T1 & X & Y \\ 0 & B & Z \\ 0 & 0 & T2 \end{pmatrix}$$

where T1 and T2 are upper triangular matrices whose eigenvalues lie along the diagonal. The column indices ILO and IHI mark the starting and ending columns of the submatrix B. Balancing consists of applying a diagonal similarity transformation $\text{inv}(D) * B * D$ to make the 1-norms of each row of B and its corresponding column nearly equal. The output matrix is

$$\begin{pmatrix} T1 & X*D & Y \\ 0 & \text{inv}(D)*B*D & \text{inv}(D)*Z \\ 0 & 0 & T2 \end{pmatrix}.$$

Information about the permutations P and the diagonal matrix D is returned in the vector SCALE.

This subroutine is based on the EISPACK routine CBAL.

Modified by Tzu-Yi Chen, Computer Science Division, University of California at Berkeley, USA

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NAME

cgebrd - reduce a general complex M-by-N matrix A to upper or lower bidiagonal form B by a unitary transformation

SYNOPSIS

```
SUBROUTINE CGEBRD(M, N, A, LDA, D, E, TAUQ, TAUP, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAUQ(*), TAUP(*), WORK(*)
INTEGER M, N, LDA, LWORK, INFO
REAL D(*), E(*)
```

```
SUBROUTINE CGEBRD_64(M, N, A, LDA, D, E, TAUQ, TAUP, WORK, LWORK,
INFO)
```

```
COMPLEX A(LDA,*), TAUQ(*), TAUP(*), WORK(*)
INTEGER*8 M, N, LDA, LWORK, INFO
REAL D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE GEBRD([M], [N], A, [LDA], D, E, TAUQ, TAUP, [WORK], [LWORK],
[INFO])
```

```
COMPLEX, DIMENSION(:) :: TAUQ, TAUP, WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER :: M, N, LDA, LWORK, INFO
REAL, DIMENSION(:) :: D, E
```

```
SUBROUTINE GEBRD_64([M], [N], A, [LDA], D, E, TAUQ, TAUP, [WORK],
[LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAUQ, TAUP, WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER(8) :: M, N, LDA, LWORK, INFO
REAL, DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>
```

```

void cgebrd(int m, int n, complex *a, int lda, float *d,
            float *e, complex *tauq, complex *taup, int
            *info);

void cgebrd_64(long m, long n, complex *a, long lda, float
               *d, float *e, complex *tauq, complex *taup, long
               *info);

```

PURPOSE

cgebrd reduces a general complex M-by-N matrix A to upper or lower bidiagonal form B by a unitary transformation: $Q^*H * A * P = B$.

If $m \geq n$, B is upper bidiagonal; if $m < n$, B is lower bidiagonal.

ARGUMENTS

M (input) The number of rows in the matrix A. $M \geq 0$.

N (input) The number of columns in the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N general matrix to be reduced. On exit, if $m \geq n$, the diagonal and the first superdiagonal are overwritten with the upper bidiagonal matrix B; the elements below the diagonal, with the array TAUQ, represent the unitary matrix Q as a product of elementary reflectors, and the elements above the first superdiagonal, with the array TAUP, represent the unitary matrix P as a product of elementary reflectors; if $m < n$, the diagonal and the first subdiagonal are overwritten with the lower bidiagonal matrix B; the elements below the first subdiagonal, with the array TAUQ, represent the unitary matrix Q as a product of elementary reflectors, and the elements above the diagonal, with the array TAUP, represent the unitary matrix P as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

D (output)

The diagonal elements of the bidiagonal matrix B: $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the bidiagonal matrix B: if $m \geq n$, $E(i) = A(i, i+1)$ for $i = 1, 2, \dots, n-1$; if $m < n$, $E(i) = A(i+1, i)$ for $i = 1, 2, \dots, m-1$.

TAUQ (output)

The scalar factors of the elementary reflectors

which represent the unitary matrix Q. See Further Details.

TAUP (output)

The scalar factors of the elementary reflectors which represent the unitary matrix P. See Further Details.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The length of the array WORK. LWORK \geq max(1,M,N). For optimum performance LWORK \geq (M+N)*NB, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrices Q and P are represented as products of elementary reflectors:

If $m \geq n$,

$$Q = H(1) H(2) \dots H(n) \quad \text{and} \quad P = G(1) G(2) \dots G(n-1)$$

Each H(i) and G(i) has the form:

$$H(i) = I - \text{tauq} * v * v' \quad \text{and} \quad G(i) = I - \text{taup} * u * u'$$

where tauq and taup are complex scalars, and v and u are complex vectors; $v(1:i-1) = 0$, $v(i) = 1$, and $v(i+1:m)$ is stored on exit in A(i+1:m,i); $u(1:i) = 0$, $u(i+1) = 1$, and $u(i+2:n)$ is stored on exit in A(i,i+2:n); tauq is stored in TAUQ(i) and taup in TAUP(i).

If $m < n$,

$$Q = H(1) H(2) \dots H(m-1) \quad \text{and} \quad P = G(1) G(2) \dots G(m)$$

Each H(i) and G(i) has the form:

$$H(i) = I - \text{tauq} * v * v' \quad \text{and} \quad G(i) = I - \text{taup} * u * u'$$

where tauq and taup are complex scalars, and v and u are complex vectors; $v(1:i) = 0$, $v(i+1) = 1$, and $v(i+2:m)$ is stored on exit in A(i+2:m,i); $u(1:i-1) = 0$, $u(i) = 1$, and $u(i+1:n)$ is stored on exit in A(i,i+1:n); tauq is stored in TAUQ(i) and taup in TAUP(i).

The contents of A on exit are illustrated by the following examples:

m = 6 and n = 5 (m > n):

```
( d  e  u1  u1  u1 )
u1 )
( v1 d  e  u2  u2 )
u2 )
( v1 v2 d  e  u3 )
u3 )
( v1 v2 v3 d  e )
u4 )
( v1 v2 v3 v4 d )
u5 )
( v1 v2 v3 v4 v5 )
```

m = 5 and n = 6 (m < n):

```
( d  u1  u1  u1  u1
( e  d  u2  u2  u2
( v1 e  d  u3  u3
( v1 v2 e  d  u4
( v1 v2 v3 e  d
```

where d and e denote diagonal and off-diagonal elements of B, v_i denotes an element of the vector defining $H(i)$, and u_i an element of the vector defining $G(i)$.

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NAME

cgecon - estimate the reciprocal of the condition number of a general complex matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by CGETRF

SYNOPSIS

```
SUBROUTINE CGECON(NORM, N, A, LDA, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
REAL ANORM, RCOND  
REAL WORK2(*)
```

```
SUBROUTINE CGECON_64(NORM, N, A, LDA, ANORM, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
REAL ANORM, RCOND  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GECON(NORM, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE GECON_64(NORM, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A
```

```
INTEGER(8) :: N, LDA, INFO
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void cgecon(char norm, int n, complex *a, int lda, float
            anorm, float *rcond, int *info);

void cgecon_64(char norm, long n, complex *a, long lda,
              float anorm, float *rcond, long *info);
```

PURPOSE

cgecon estimates the reciprocal of the condition number of a general complex matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by CGETRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))) .$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The factors L and U from the factorization $A = P * L * U$ as computed by CGETRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cggequ - compute row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number

SYNOPSIS

```
SUBROUTINE CGEEQU(M, N, A, LDA, R, C, ROWCND, COLCND, AMAX,
                  INFO)
```

```
COMPLEX A(LDA,*)
INTEGER M, N, LDA, INFO
REAL ROWCND, COLCND, AMAX
REAL R(*), C(*)
```

```
SUBROUTINE CGEEQU_64(M, N, A, LDA, R, C, ROWCND, COLCND,
                    AMAX, INFO)
```

```
COMPLEX A(LDA,*)
INTEGER*8 M, N, LDA, INFO
REAL ROWCND, COLCND, AMAX
REAL R(*), C(*)
```

F95 INTERFACE

```
SUBROUTINE GEEQU([M], [N], A, [LDA], R, C, ROWCND, COLCND,
                AMAX, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A
INTEGER :: M, N, LDA, INFO
REAL :: ROWCND, COLCND, AMAX
REAL, DIMENSION(:) :: R, C
```

```
SUBROUTINE GEEQU_64([M], [N], A, [LDA], R, C, ROWCND, COLCND,
                   AMAX, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A
INTEGER(8) :: M, N, LDA, INFO
REAL :: ROWCND, COLCND, AMAX
REAL, DIMENSION(:) :: R, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgeequ(int m, int n, complex *a, int lda, float *r,
           float *c, float *rowcnd, float *colcnd, float
           *amax, int *info);
```

```
void cgeequ_64(long m, long n, complex *a, long lda, float
              *r, float *c, float *rowcnd, float *colcnd, float
              *amax, long *info);
```

PURPOSE

cgeequ computes row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number. R returns the row scale factors and C the column scale factors, chosen to try to make the largest element in each row and column of the matrix B with elements $B(i,j)=R(i)*A(i,j)*C(j)$ have absolute value 1.

R(i) and C(j) are restricted to be between SMLNUM = smallest safe number and BIGNUM = largest safe number. Use of these scaling factors is not guaranteed to reduce the condition number of A but works well in practice.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input) The M-by-N matrix whose equilibration factors are to be computed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,M)$.

R (output)
If INFO = 0 or INFO > M, R contains the row scale factors for A.

C (output)
If INFO = 0, C contains the column scale factors for A.

ROWCND (output)
If INFO = 0 or INFO > M, ROWCND contains the ratio of the smallest R(i) to the largest R(i). If ROWCND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by R.

COLCND (output)
If INFO = 0, COLCND contains the ratio of the smallest C(i) to the largest C(i). If COLCND ≥ 0.1 , it is not worth scaling by C.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= M: the i-th row of A is exactly zero
> M: the (i-M)-th column of A is exactly zero

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NAME

cgees - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z

SYNOPSIS

```
SUBROUTINE CGEES(JOBZ, SORTEV, SELECT, N, A, LDA, NOUT, W, Z, LDZ,  
                WORK, LDWORK, WORK2, WORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV  
COMPLEX A(LDA,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL SELECT  
LOGICAL WORK3(*)  
REAL WORK2(*)
```

```
SUBROUTINE CGEES_64(JOBZ, SORTEV, SELECT, N, A, LDA, NOUT, W, Z, LDZ,  
                  WORK, LDWORK, WORK2, WORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV  
COMPLEX A(LDA,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL*8 SELECT  
LOGICAL*8 WORK3(*)  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEES(JOBZ, SORTEV, [SELECT], [N], A, [LDA], [NOUT], W, Z, [LDZ],  
               [WORK], [LDWORK], [WORK2], [WORK3], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: A, Z  
INTEGER :: N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL :: SELECT  
LOGICAL, DIMENSION(:) :: WORK3  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEES_64(JOBZ, SORTEV, [SELECT], [N], A, [LDA], [NOUT], W, Z,  
                  [LDZ], [WORK], [LDWORK], [WORK2], [WORK3], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, SORTEV
COMPLEX, DIMENSION(:) :: W, WORK
COMPLEX, DIMENSION(:, :) :: A, Z
INTEGER(8) :: N, LDA, NOUT, LDZ, LDWORK, INFO
LOGICAL(8) :: SELECT
LOGICAL(8), DIMENSION(:) :: WORK3
REAL, DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>

void cgees(char jobz, char sortev, int(*select)(complex),
           int n, complex *a, int lda, int *nout, complex *w,
           complex *z, int ldz, int *info);

void cgees_64(char jobz, char sortev,
              long(*select)(complex), long n, complex *a, long
              lda, long *nout, complex *w, complex *z, long ldz,
              long *info);

```

PURPOSE

cgees computes for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z. This gives the Schur factorization $A = Z^*T(Z^*H)$.

Optionally, it also orders the eigenvalues on the diagonal of the Schur form so that selected eigenvalues are at the top left. The leading columns of Z then form an orthonormal basis for the invariant subspace corresponding to the selected eigenvalues.

A complex matrix is in Schur form if it is upper triangular.

ARGUMENTS

JOBZ (input)

= 'N': Schur vectors are not computed;
 = 'V': Schur vectors are computed.

SORTEV (input)

Specifies whether or not to order the eigenvalues on the diagonal of the Schur form. = 'N': Eigenvalues are not ordered;
 = 'S': Eigenvalues are ordered (see SELECT).

SELECT (input)

LOGICAL FUNCTION of one COMPLEX argument SELECT must be declared EXTERNAL in the calling subroutine. If SORTEV = 'S', SELECT is used to select eigenvalues to order to the top left of the Schur form. If SORTEV = 'N', SELECT is not referenced. The eigenvalue W(j) is selected if SELECT(W(j)) is true.

N (input) The order of the matrix A. N >= 0.

A (input/output)
 COMPLEX array, dimension(LDA,N) On entry, the N-by-N matrix A. On exit, A has been overwritten by its Schur form T.

LDA (input)
 The leading dimension of the array A. LDA \geq max(1,N).

NOUT (output)
 If SORTEV = 'N', NOUT = 0. If SORTEV = 'S', NOUT = number of eigenvalues for which SELECT is true.

W (output)
 COMPLEX array, dimension(N) W contains the computed eigenvalues, in the same order that they appear on the diagonal of the output Schur form T.

Z (output)
 COMPLEX array, dimension(LDZ,N) If JOBZ = 'V', Z contains the unitary matrix Z of Schur vectors. If JOBZ = 'N', Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. LDZ \geq 1; if JOBZ = 'V', LDZ \geq N.

WORK (workspace)
 COMPLEX array, dimension(LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The dimension of the array WORK. LDWORK \geq max(1,2*N). For good performance, LDWORK must generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
 REAL array, dimension(N)

WORK3 (workspace)
 LOGICAL array, dimension(N) Not referenced if SORTEV = 'N'.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value.
 > 0: if INFO = i, and i is
 <= N: the QR algorithm failed to compute all the eigenvalues; elements 1:ILO-1 and i+1:N of W contain those eigenvalues which have converged; if JOBZ = 'V', Z contains the matrix which reduces A to its partially converged Schur form. = N+1: the eigenvalues could not be reordered because some eigenvalues were too close to separate (the prob-

lem is very ill-conditioned); = N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Schur form no longer satisfy SELECT = .TRUE.. This could also be caused by underflow due to scaling.

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NAME

cgeesx - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z

SYNOPSIS

```
SUBROUTINE CGEESX(JOBZ, SORTEV, SELECT, SENSE, N, A, LDA, NOUT, W, Z,  
                 LDZ, RCONE, RCONV, WORK, LDWORK, WORK2, BWORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV, SENSE  
COMPLEX A(LDA,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL SELECT  
LOGICAL BWORK3(*)  
REAL RCONE, RCONV  
REAL WORK2(*)
```

```
SUBROUTINE CGEESX_64(JOBZ, SORTEV, SELECT, SENSE, N, A, LDA, NOUT, W,  
                    Z, LDZ, RCONE, RCONV, WORK, LDWORK, WORK2, BWORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV, SENSE  
COMPLEX A(LDA,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL*8 SELECT  
LOGICAL*8 BWORK3(*)  
REAL RCONE, RCONV  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEESX(JOBZ, SORTEV, [SELECT], SENSE, [N], A, [LDA], NOUT, W,  
                Z, [LDZ], RCONE, RCONV, [WORK], [LDWORK], [WORK2], [BWORK3],  
                [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV, SENSE  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: A, Z  
INTEGER :: N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL :: SELECT  
LOGICAL, DIMENSION(:) :: BWORK3  
REAL :: RCONE, RCONV
```

```

REAL, DIMENSION(:) :: WORK2

SUBROUTINE GEESX_64(JOBZ, SORTEV, [SELECT], SENSE, [N], A, [LDA], NOUT,
    W, Z, [LDZ], RCONE, RCONV, [WORK], [LDWORK], [WORK2], [BWORK3],
    [INFO])

CHARACTER(LEN=1) :: JOBZ, SORTEV, SENSE
COMPLEX, DIMENSION(:) :: W, WORK
COMPLEX, DIMENSION(:, :) :: A, Z
INTEGER(8) :: N, LDA, NOUT, LDZ, LDWORK, INFO
LOGICAL(8) :: SELECT
LOGICAL(8), DIMENSION(:) :: BWORK3
REAL :: RCONE, RCONV
REAL, DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>

void cgeesx(char jobz, char sortev, int(*select)(complex),
    char sense, int n, complex *a, int lda, int *nout,
    complex *w, complex *z, int ldz, float *rcone,
    float *rconv, int *info);

void cgeesx_64(char jobz, char sortev,
    long(*select)(complex), char sense, long n, com-
    plex *a, long lda, long *nout, complex *w, complex
    *z, long ldz, float *rcone, float *rconv, long
    *info);

```

PURPOSE

cgeesx computes for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z. This gives the Schur factorization $A = Z^*T(Z^*H)$.

Optionally, it also orders the eigenvalues on the diagonal of the Schur form so that selected eigenvalues are at the top left; computes a reciprocal condition number for the average of the selected eigenvalues (RCONDE); and computes a reciprocal condition number for the right invariant subspace corresponding to the selected eigenvalues (RCONDV). The leading columns of Z form an orthonormal basis for this invariant subspace.

For further explanation of the reciprocal condition numbers RCONDE and RCONDV, see Section 4.10 of the LAPACK Users' Guide (where these quantities are called s and sep respectively).

A complex matrix is in Schur form if it is upper triangular.

ARGUMENTS

JOBZ (input)
 = 'N': Schur vectors are not computed;

= 'V': Schur vectors are computed.

SORTEV (input)
 Specifies whether or not to order the eigenvalues on the diagonal of the Schur form. = 'N': Eigenvalues are not ordered;
 = 'S': Eigenvalues are ordered (see SELECT).

SELECT (input)
 LOGICAL FUNCTION of one COMPLEX argument SELECT must be declared EXTERNAL in the calling subroutine. If SORTEV = 'S', SELECT is used to select eigenvalues to order to the top left of the Schur form. If SORTEV = 'N', SELECT is not referenced. An eigenvalue W(j) is selected if SELECT(W(j)) is true.

SENSE (input)
 Determines which reciprocal condition numbers are computed. = 'N': None are computed;
 = 'E': Computed for average of selected eigenvalues only;
 = 'V': Computed for selected right invariant subspace only;
 = 'B': Computed for both. If SENSE = 'E', 'V' or 'B', SORTEV must equal 'S'.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)
 COMPLEX array, dimension(LDA,N) On entry, the N-by-N matrix A. On exit, A is overwritten by its Schur form T.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1,N)$.

NOUT (output)
 If SORTEV = 'N', NOUT = 0. If SORTEV = 'S', NOUT = number of eigenvalues for which SELECT is true.

W (output)
 COMPLEX array, dimension(N) W contains the computed eigenvalues, in the same order that they appear on the diagonal of the output Schur form T.

Z (output)
 COMPLEX array, dimension(LDZ,N) If JOBZ = 'V', Z contains the unitary matrix Z of Schur vectors. If JOBZ = 'N', Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq N$.

RCONE (output)
 If SENSE = 'E' or 'B', RCONE contains the reciprocal condition number for the average of the selected eigenvalues. Not referenced if SENSE = 'N' or 'V'.

RCONV (output)

If SENSE = 'V' or 'B', RCONV contains the reciprocal condition number for the selected right invariant subspace. Not referenced if SENSE = 'N' or 'E'.

WORK (workspace)

COMPLEX array, dimension(LDWORK) On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq max(1,2*N). Also, if SENSE = 'E' or 'V' or 'B', LDWORK \geq 2*NOUT*(N-NOUT), where NOUT is the number of selected eigenvalues computed by this routine. Note that 2*NOUT*(N-NOUT) \leq N*N/2. For good performance, LDWORK must generally be larger.

WORK2 (workspace)

REAL array, dimension(N)

BWORK3 (workspace)

LOGICAL array, dimension(N) Not referenced if SORTEV = 'N'.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, and i is
<= N: the QR algorithm failed to compute all the eigenvalues; elements 1:ILO-1 and i+1:N of W contain those eigenvalues which have converged; if JOBZ = 'V', Z contains the transformation which reduces A to its partially converged Schur form.
= N+1: the eigenvalues could not be reordered because some eigenvalues were too close to separate (the problem is very ill-conditioned);
= N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Schur form no longer satisfy SELECT=.TRUE. This could also be caused by underflow due to scaling.

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NAME

cggeev - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

SYNOPSIS

```
SUBROUTINE CGEEV(JOBVL, JOBVR, N, A, LDA, W, VL, LDVL, VR, LDVR,  
                WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
COMPLEX A(LDA,*), W(*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER N, LDA, LDVL, LDVR, LDWORK, INFO  
REAL WORK2(*)
```

```
SUBROUTINE CGEEV_64(JOBVL, JOBVR, N, A, LDA, W, VL, LDVL, VR, LDVR,  
                   WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
COMPLEX A(LDA,*), W(*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER*8 N, LDA, LDVL, LDVR, LDWORK, INFO  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEEV(JOBVL, JOBVR, [N], A, [LDA], W, VL, [LDVL], VR, [LDVR],  
               [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: A, VL, VR  
INTEGER :: N, LDA, LDVL, LDVR, LDWORK, INFO  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEEV_64(JOBVL, JOBVR, [N], A, [LDA], W, VL, [LDVL], VR,  
                  [LDVR], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: A, VL, VR  
INTEGER(8) :: N, LDA, LDVL, LDVR, LDWORK, INFO  
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>

void cgeev(char jobvl, char jobvr, int n, complex *a, int
           lda, complex *w, complex *vl, int ldvl, complex
           *vr, int ldvr, int *info);
void cgeev_64(char jobvl, char jobvr, long n, complex *a,
              long lda, complex *w, complex *vl, long ldvl, com-
              plex *vr, long ldvr, long *info);
```

PURPOSE

cgeev computes for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors.

The right eigenvector v(j) of A satisfies

$$A * v(j) = \text{lambda}(j) * v(j)$$

where lambda(j) is its eigenvalue.

The left eigenvector u(j) of A satisfies

$$u(j)**H * A = \text{lambda}(j) * u(j)**H$$

where u(j)**H denotes the conjugate transpose of u(j).

The computed eigenvectors are normalized to have Euclidean norm equal to 1 and largest component real.

ARGUMENTS

JOBVL (input)

= 'N': left eigenvectors of A are not computed;
= 'V': left eigenvectors of are computed.

JOBVR (input)

= 'N': right eigenvectors of A are not computed;
= 'V': right eigenvectors of A are computed.

N (input) The order of the matrix A. N >= 0.

A (input/output)

On entry, the N-by-N matrix A. On exit, A has been overwritten.

LDA (input)

The leading dimension of the array A. LDA >= max(1,N).

W (output)

W contains the computed eigenvalues.

VL (input)

If JOBVL = 'V', the left eigenvectors u(j) are stored one after another in the columns of VL, in the same order as their eigenvalues. If JOBVL = 'N', VL is not referenced. u(j) = VL(:,j), the j-th column of VL.

LDVL (input)
 The leading dimension of the array VL. LDVL \geq 1;
 if JOBVL = 'V', LDVL \geq N.

VR (input)
 If JOBVR = 'V', the right eigenvectors $v(j)$ are
 stored one after another in the columns of VR, in
 the same order as their eigenvalues. If JOBVR =
 'N', VR is not referenced. $v(j) = VR(:,j)$, the
 j-th column of VR.

LDVR (input)
 The leading dimension of the array VR. LDVR \geq 1;
 if JOBVR = 'V', LDVR \geq N.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal
 LDWORK.

LDWORK (input)
 The dimension of the array WORK. LDWORK \geq
 $\max(1, 2*N)$. For good performance, LDWORK must
 generally be larger.

If LDWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the WORK array, returns this value as the first
 entry of the WORK array, and no error message
 related to LDWORK is issued by XERBLA.

WORK2 (workspace)
 dimension(2*N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-
 gal value.
 > 0: if INFO = i, the QR algorithm failed to com-
 pute all the eigenvalues, and no eigenvectors have
 been computed; elements and i+1:N of W contain
 eigenvalues which have converged.

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NAME

cgeevx - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

SYNOPSIS

```
SUBROUTINE CGEEVX(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, W, VL,
                 LDVL, VR, LDVR, ILO, IHI, SCALE, ABNRM, RCONE, RCONV, WORK,
                 LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
COMPLEX A(LDA,*), W(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
REAL ABNRM
REAL SCALE(*), RCONE(*), RCONV(*), WORK2(*)
```

```
SUBROUTINE CGEEVX_64(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, W, VL,
                   LDVL, VR, LDVR, ILO, IHI, SCALE, ABNRM, RCONE, RCONV, WORK,
                   LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
COMPLEX A(LDA,*), W(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER*8 N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
REAL ABNRM
REAL SCALE(*), RCONE(*), RCONV(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEEVX(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], W, VL,
                [LDVL], VR, [LDVR], ILO, IHI, SCALE, ABNRM, RCONE, RCONV, [WORK],
                LDWORK, [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
COMPLEX, DIMENSION(:) :: W, WORK
COMPLEX, DIMENSION(:, :) :: A, VL, VR
INTEGER :: N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
REAL :: ABNRM
REAL, DIMENSION(:) :: SCALE, RCONE, RCONV, WORK2
```

```
SUBROUTINE GEEVX_64(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], W,
                   VL, [LDVL], VR, [LDVR], ILO, IHI, SCALE, ABNRM, RCONE, RCONV,
```

```
[WORK], LDWORK, [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: A, VL, VR  
INTEGER(8) :: N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO  
REAL :: ABNRM  
REAL, DIMENSION(:) :: SCALE, RCONE, RCONV, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgeevx (char, char, char, char, int, complex*, int,  
            complex*, complex*, int, complex*, int, int*,  
            int*, float*, float*, float*, float*, int*);
```

```
void cgeevx_64 (char, char, char, char, long, complex*,  
               long, complex*, complex*, long, complex*, long,  
               long*, long*, float*, float*, float*, float*,  
               long*);
```

PURPOSE

cgeevx computes for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors.

Optionally also, it computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors (ILO, IHI, SCALE, and ABNRM), reciprocal condition numbers for the eigenvalues (RCONDE), and reciprocal condition numbers for the right eigenvectors (RCONDV).

The right eigenvector $v(j)$ of A satisfies

$$A * v(j) = \lambda(j) * v(j)$$

where $\lambda(j)$ is its eigenvalue.

The left eigenvector $u(j)$ of A satisfies

$$u(j)**H * A = \lambda(j) * u(j)**H$$

where $u(j)**H$ denotes the conjugate transpose of $u(j)$.

The computed eigenvectors are normalized to have Euclidean norm equal to 1 and largest component real.

Balancing a matrix means permuting the rows and columns to make it more nearly upper triangular, and applying a diagonal similarity transformation $D * A * D^{(-1)}$, where D is a diagonal matrix, to make its rows and columns closer in norm and the condition numbers of its eigenvalues and eigenvectors smaller. The computed reciprocal condition numbers correspond to the balanced matrix. Permuting rows and columns will not change the condition numbers (in exact arithmetic) but diagonal scaling will. For further explanation of balancing, see section 4.10.2 of the LAPACK Users' Guide.

ARGUMENTS

BALANC (input)

Indicates how the input matrix should be diagonally scaled and/or permuted to improve the conditioning of its eigenvalues. = 'N': Do not diagonally scale or permute; = 'P': Perform permutations to make the matrix more nearly upper triangular. Do not diagonally scale; = 'S': Diagonally scale the matrix, ie. replace A by $D*A*D^{*(-1)}$, where D is a diagonal matrix chosen to make the rows and columns of A more equal in norm. Do not permute; = 'B': Both diagonally scale and permute A.

Computed reciprocal condition numbers will be for the matrix after balancing and/or permuting. Permuting does not change condition numbers (in exact arithmetic), but balancing does.

JOBVL (input)

= 'N': left eigenvectors of A are not computed;
= 'V': left eigenvectors of A are computed. If SENSE = 'E' or 'B', JOBVL must = 'V'.

JOBVR (input)

= 'N': right eigenvectors of A are not computed;
= 'V': right eigenvectors of A are computed. If SENSE = 'E' or 'B', JOBVR must = 'V'.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': None are computed;
= 'E': Computed for eigenvalues only;
= 'V': Computed for right eigenvectors only;
= 'B': Computed for eigenvalues and right eigenvectors.

If SENSE = 'E' or 'B', both left and right eigenvectors must also be computed (JOBVL = 'V' and JOBVR = 'V').

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. On exit, A has been overwritten. If JOBVL = 'V' or JOBVR = 'V', A contains the Schur form of the balanced version of the matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

W (output)

W contains the computed eigenvalues.

VL (input)

If JOBVL = 'V', the left eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. If JOBVL = 'N', VL is not referenced. $u(j) = VL(:,j)$, the j-th column of VL.

LDVL (input)
 The leading dimension of the array VL. LDVL \geq 1;
 if JOBVL = 'V', LDVL \geq N.

VR (input)
 If JOBVR = 'V', the right eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. If JOBVR = 'N', VR is not referenced. $v(j) = VR(:,j)$, the j -th column of VR.

LDVR (input)
 The leading dimension of the array VR. LDVR \geq 1;
 if JOBVR = 'V', LDVR \geq N.

ILO (output)
 ILO and IHI are integer values determined when A was balanced. The balanced $A(i,j) = 0$ if $I > J$ and $J = 1, \dots, ILO-1$ or $I = IHI+1, \dots, N$.

IHI (output)
 ILO and IHI are integer values determined when A was balanced. The balanced $A(i,j) = 0$ if $I > J$ and $J = 1, \dots, ILO-1$ or $I = IHI+1, \dots, N$.

SCALE (output)
 Details of the permutations and scaling factors applied when balancing A. If $P(j)$ is the index of the row and column interchanged with row and column j , and $D(j)$ is the scaling factor applied to row and column j , then $SCALE(J) = P(J)$, for $J = 1, \dots, ILO-1 = D(J)$, for $J = ILO, \dots, IHI = P(J)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to IHI+1, then 1 to ILO-1.

ABNRM (output)
 The one-norm of the balanced matrix (the maximum of the sum of absolute values of elements of any column).

RCONE (output)
 RCONE(j) is the reciprocal condition number of the j -th eigenvalue.

RCONV (output)
 RCONV(j) is the reciprocal condition number of the j -th right eigenvector.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (output)
 The dimension of the array WORK. If SENSE = 'N' or 'E', LDWORK \geq $\max(1, 2*N)$, and if SENSE = 'V' or 'B', LDWORK \geq $N*N+2*N$. For good performance, LDWORK must generally be larger.

If LDWORK = -1, then a workspace query is assumed;

the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
dimension(2*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the QR algorithm failed to compute all the eigenvalues, and no eigenvectors or condition numbers have been computed; elements 1:ILO-1 and i+1:N of W contain eigenvalues which have converged.

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NAME

cgges - routine is deprecated and has been replaced by routine CGGES

SYNOPSIS

```
SUBROUTINE CGEGS(JOBVSL, JOBVSR, N, A, LDA, B, LDB, ALPHA, BETA, VSL,
                LDVSL, VSR, LDVSR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VSL(LDVSL,*),
VSR(LDVSR,*), WORK(*)
INTEGER N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL WORK2(*)
```

```
SUBROUTINE CGEGS_64(JOBVSL, JOBVSR, N, A, LDA, B, LDB, ALPHA, BETA,
                   VSL, LDVSL, VSR, LDVSR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VSL(LDVSL,*),
VSR(LDVSR,*), WORK(*)
INTEGER*8 N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEGS(JOBVSL, JOBVSR, [N], A, [LDA], B, [LDB], ALPHA, BETA,
               VSL, [LDVSL], VSR, [LDVSR], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:, :) :: A, B, VSL, VSR
INTEGER :: N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEGS_64(JOBVSL, JOBVSR, [N], A, [LDA], B, [LDB], ALPHA,
                  BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK], [LDWORK], [WORK2],
                  [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:, :) :: A, B, VSL, VSR
```

```
INTEGER(8) :: N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void cgegs(char jobvsl, char jobvsr, int n, complex *a, int
           lda, complex *b, int ldb, complex *alpha, complex
           *beta, complex *vsl, int ldvsl, complex *vsr, int
           ldvsr, int *info);

void cgegs_64(char jobvsl, char jobvsr, long n, complex *a,
             long lda, complex *b, long ldb, complex *alpha,
             complex *beta, complex *vsl, long ldvsl, complex
             *vsr, long ldvsr, long *info);
```

PURPOSE

cgegs routine is deprecated and has been replaced by routine CGGES.

CGEGS computes for a pair of N-by-N complex nonsymmetric matrices A, B: the generalized eigenvalues (alpha, beta), the complex Schur form (A, B), and optionally left and/or right Schur vectors (VSL and VSR).

(If only the generalized eigenvalues are needed, use the driver CGEGV instead.)

A generalized eigenvalue for a pair of matrices (A,B) is, roughly speaking, a scalar w or a ratio $\alpha/\beta = w$, such that $A - wB$ is singular. It is usually represented as the pair (alpha,beta), as there is a reasonable interpretation for $\beta=0$, and even for both being zero. A good beginning reference is the book, "Matrix Computations", by G. Golub & C. van Loan (Johns Hopkins U. Press)

The (generalized) Schur form of a pair of matrices is the result of multiplying both matrices on the left by one unitary matrix and both on the right by another unitary matrix, these two unitary matrices being chosen so as to bring the pair of matrices into upper triangular form with the diagonal elements of B being non-negative real numbers (this is also called complex Schur form.)

The left and right Schur vectors are the columns of VSL and VSR, respectively, where VSL and VSR are the unitary matrices which reduce A and B to Schur form:

Schur form of (A,B) = ((VSL)**H A (VSR), (VSL)**H B (VSR))

ARGUMENTS

JOBVSL (input)
= 'N': do not compute the left Schur vectors;
= 'V': compute the left Schur vectors.

JOBVSR (input)
 = 'N': do not compute the right Schur vectors;
 = 'V': compute the right Schur vectors.

N (input) The order of the matrices A, B, VSL, and VSR. N
 >= 0.

A (input/output)
 On entry, the first of the pair of matrices whose
 generalized eigenvalues and (optionally) Schur
 vectors are to be computed. On exit, the general-
 ized Schur form of A.

LDA (input)
 The leading dimension of A. LDA >= max(1,N).

B (input/output)
 On entry, the second of the pair of matrices whose
 generalized eigenvalues and (optionally) Schur
 vectors are to be computed. On exit, the general-
 ized Schur form of B.

LDB (input)
 The leading dimension of B. LDB >= max(1,N).

ALPHA (output)
 On exit, ALPHA(j)/BETA(j), j=1,...,N, will be the
 generalized eigenvalues. ALPHA(j), j=1,...,N and
 BETA(j), j=1,...,N are the diagonals of the com-
 plex Schur form (A,B) output by CGEGS. The
 BETA(j) will be non-negative real.

Note: the quotients ALPHA(j)/BETA(j) may easily
 over- or underflow, and BETA(j) may even be zero.
 Thus, the user should avoid naively computing the
 ratio alpha/beta. However, ALPHA will be always
 less than and usually comparable with norm(A) in
 magnitude, and BETA always less than and usually
 comparable with norm(B).

BETA (output)
 See the description of ALPHA.

VSL (input)
 If JOBVSL = 'V', VSL will contain the left Schur
 vectors. (See "Purpose", above.) Not referenced
 if JOBVSL = 'N'.

LDVSL (input)
 The leading dimension of the matrix VSL. LDVSL >=
 1, and if JOBVSL = 'V', LDVSL >= N.

VSR (input)
 If JOBVSR = 'V', VSR will contain the right Schur
 vectors. (See "Purpose", above.) Not referenced
 if JOBVSR = 'N'.

LDVSR (input)
 The leading dimension of the matrix VSR. LDVSR >=
 1, and if JOBVSR = 'V', LDVSR >= N.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
The dimension of the array WORK. LDWORK \geq max(1,2*N). For good performance, LDWORK must generally be larger. To compute the optimal value of LDWORK, call ILAENV to get blocksizes (for CGEQRF, CUNMQR, and CUNGQR.) Then compute: NB as the MAX of the blocksizes for CGEQRF, CUNMQR, and CUNGQR; the optimal LDWORK is N*(NB+1).

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
dimension(3*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
=1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHA(j) and BETA(j) should be correct for j=INFO+1,...,N. > N: errors that usually indicate LAPACK problems:
=N+1: error return from CGGBAL
=N+2: error return from CGEQRF
=N+3: error return from CUNMQR
=N+4: error return from CUNGQR
=N+5: error return from CGGHRD
=N+6: error return from CHGEQZ (other than failed iteration) =N+7: error return from CGGBAK (computing VSL)
=N+8: error return from CGGBAK (computing VSR)
=N+9: error return from CLASCL (various places)

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NAME

cggev - routine is deprecated and has been replaced by routine CGGEV

SYNOPSIS

```
SUBROUTINE CGEGV(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHA, BETA, VL,
                 LDVL, VR, LDVR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VL(LDVL,*),
VR(LDVR,*), WORK(*)
INTEGER N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL WORK2(*)
```

```
SUBROUTINE CGEGV_64(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHA, BETA, VL,
                   LDVL, VR, LDVR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VL(LDVL,*),
VR(LDVR,*), WORK(*)
INTEGER*8 N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEGV(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHA, BETA,
               VL, [LDVL], VR, [LDVR], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:, :) :: A, B, VL, VR
INTEGER :: N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEGV_64(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHA,
                  BETA, VL, [LDVL], VR, [LDVR], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
```

```
COMPLEX, DIMENSION(:, :) :: A, B, VL, VR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgegv(char jobvl, char jobvr, int n, complex *a, int
           lda, complex *b, int ldb, complex *alpha, complex
           *beta, complex *vl, int ldvl, complex *vr, int
           ldvr, int *info);
```

```
void cgegv_64(char jobvl, char jobvr, long n, complex *a,
              long lda, complex *b, long ldb, complex *alpha,
              complex *beta, complex *vl, long ldvl, complex
              *vr, long ldvr, long *info);
```

PURPOSE

cgegv routine is deprecated and has been replaced by routine CGGEV.

CGEGV computes for a pair of N-by-N complex nonsymmetric matrices A and B, the generalized eigenvalues (alpha, beta), and optionally, the left and/or right generalized eigenvectors (VL and VR).

A generalized eigenvalue for a pair of matrices (A,B) is, roughly speaking, a scalar w or a ratio $\alpha/\beta = w$, such that $A - wB$ is singular. It is usually represented as the pair (alpha,beta), as there is a reasonable interpretation for $\beta=0$, and even for both being zero. A good beginning reference is the book, "Matrix Computations", by G. Golub & C. van Loan (Johns Hopkins U. Press)

A right generalized eigenvector corresponding to a generalized eigenvalue w for a pair of matrices (A,B) is a vector r such that $(A - w B) r = 0$. A left generalized eigenvector is a vector l such that $l^*H * (A - w B) = 0$, where l^*H is the conjugate-transpose of l .

Note: this routine performs "full balancing" on A and B. See "Further Details", below.

ARGUMENTS

JOBVL (input)

```
= 'N': do not compute the left generalized eigen-
      vectors;
= 'V': compute the left generalized eigenvectors.
```

JOBVR (input)

```
= 'N': do not compute the right generalized
      eigenvectors;
= 'V': compute the right generalized eigenvec-
```

tors.

N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)

On entry, the first of the pair of matrices whose generalized eigenvalues and (optionally) generalized eigenvectors are to be computed. On exit, the contents will have been destroyed. (For a description of the contents of A on exit, see "Further Details", below.)

LDA (input)

The leading dimension of A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the second of the pair of matrices whose generalized eigenvalues and (optionally) generalized eigenvectors are to be computed. On exit, the contents will have been destroyed. (For a description of the contents of B on exit, see "Further Details", below.)

LDB (input)

The leading dimension of B. $LDB \geq \max(1, N)$.

ALPHA (output)

On exit, $ALPHA(j)/VL(j)$, $j=1, \dots, N$, will be the generalized eigenvalues.

Note: the quotients $ALPHA(j)/VL(j)$ may easily overflow or underflow, and $VL(j)$ may even be zero. Thus, the user should avoid naively computing the ratio α/β . However, ALPHA will be always less than and usually comparable with $\text{norm}(A)$ in magnitude, and VL always less than and usually comparable with $\text{norm}(B)$.

VL (output)

If $JOBVL = 'V'$, the left generalized eigenvectors. (See "Purpose", above.) Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha=\beta=0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if $JOBVL = 'N'$.

BETA (output)

If $JOBVL = 'V'$, the left generalized eigenvectors. (See "Purpose", above.) Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha=\beta=0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if $JOBVL = 'N'$.

LDVL (input)

The leading dimension of the matrix VL. $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (output)

If JOBVR = 'V', the right generalized eigenvectors. (See "Purpose", above.) Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha=\beta=0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if JOBVR = 'N'.

LDVR (input)

The leading dimension of the matrix VR. LDVR ≥ 1 , and if JOBVR = 'V', LDVR $\geq N$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK $\geq \max(1, 2*N)$. For good performance, LDWORK must generally be larger. To compute the optimal value of LDWORK, call ILAENV to get block sizes (for CGEQRF, CUNMQR, and CUNGQR.) Then compute: NB as the MAX of the block sizes for CGEQRF, CUNMQR, and CUNGQR; The optimal LDWORK is $\text{MAX}(2*N, N*(NB+1))$.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)

dimension(8*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
=1,...,N: The QZ iteration failed. No eigenvectors have been calculated, but ALPHA(j) and VL(j) should be correct for $j=\text{INFO}+1, \dots, N$. > N: errors that usually indicate LAPACK problems:
=N+1: error return from CGGBAL
=N+2: error return from CGEQRF
=N+3: error return from CUNMQR
=N+4: error return from CUNGQR
=N+5: error return from CGGHRD
=N+6: error return from CHGEQZ (other than failed iteration) =N+7: error return from CTGEVC
=N+8: error return from CGGBAK (computing VL)
=N+9: error return from CGGBAK (computing VR)
=N+10: error return from CLASCL (various calls)

FURTHER DETAILS

Balancing

This driver calls CGGBAL to both permute and scale rows and columns of A and B. The permutations PL and PR are chosen

so that PL^*A^*PR and PL^*B^*R will be upper triangular except for the diagonal blocks $A(i:j,i:j)$ and $B(i:j,i:j)$, with i and j as close together as possible. The diagonal scaling matrices DL and DR are chosen so that the pair $DL^*PL^*A^*PR^*DR$, $DL^*PL^*B^*PR^*DR$ have elements close to one (except for the elements that start out zero.)

After the eigenvalues and eigenvectors of the balanced matrices have been computed, CGGBAK transforms the eigenvectors back to what they would have been (in perfect arithmetic) if they had not been balanced.

Contents of A and B on Exit

If any eigenvectors are computed (either $JOBVL='V'$ or $JOBVR='V'$ or both), then on exit the arrays A and B will contain the complex Schur form[*] of the "balanced" versions of A and B. If no eigenvectors are computed, then only the diagonal blocks will be correct.

[*] In other words, upper triangular form.

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NAME

cgehrd - reduce a complex general matrix A to upper Hessenberg form H by a unitary similarity transformation

SYNOPSIS

```
SUBROUTINE CGEHRD(N, ILO, IHI, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORKIN(*)  
INTEGER N, ILO, IHI, LDA, LWORKIN, INFO
```

```
SUBROUTINE CGEHRD_64(N, ILO, IHI, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORKIN(*)  
INTEGER*8 N, ILO, IHI, LDA, LWORKIN, INFO
```

F95 INTERFACE

```
SUBROUTINE GEHRD([N], ILO, IHI, A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORKIN  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: N, ILO, IHI, LDA, LWORKIN, INFO
```

```
SUBROUTINE GEHRD_64([N], ILO, IHI, A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORKIN  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: N, ILO, IHI, LDA, LWORKIN, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgehrd(int n, int ilo, int ihi, complex *a, int lda,  
complex *tau, int *info);
```

```
void cgehrd_64(long n, long ilo, long ihi, complex *a, long  
lda, complex *tau, long *info);
```

PURPOSE

cgehrd reduces a complex general matrix A to upper Hessenberg form H by a unitary similarity transformation: $Q' * A * Q = H$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to CGEBAL; otherwise they should be set to 1 and N respectively. See Further Details.

IHI (input)

See the description of ILO.

A (input/output)

On entry, the N-by-N general matrix to be reduced. On exit, the upper triangle and the first subdiagonal of A are overwritten with the upper Hessenberg matrix H, and the elements below the first subdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details). Elements 1:ILO-1 and IHI:N-1 of TAU are set to zero.

WORKIN (workspace)

On exit, if INFO = 0, WORKIN(1) returns the optimal LWORKIN.

LWORKIN (input)

The length of the array WORKIN. $LWORKIN \geq \max(1, N)$. For optimum performance $LWORKIN \geq N * NB$, where NB is the optimal blocksize.

If LWORKIN = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORKIN array, returns this value as the first entry of the WORKIN array, and no error message related to LWORKIN is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-

gal value.

FURTHER DETAILS

The matrix Q is represented as a product of $(ihi-ilo)$ elementary reflectors

$$Q = H(ilo) H(ilo+1) \dots H(ihi-1).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a complex scalar, and v is a complex vector with $v(1:i) = 0$, $v(i+1) = 1$ and $v(ihi+1:n) = 0$; $v(i+2:ihi)$ is stored on exit in $A(i+2:ihi,i)$, and τ in $TAU(i)$.

The contents of A are illustrated by the following example, with $n = 7$, $ilo = 2$ and $ihi = 6$:

on entry,

on exit,

```
( a a a a a a a ) ( a a h h h h
a ) ( a a a a a a a ) ( a h h h
h a ) ( a a a a a a a ) ( h h h
h h h ) ( a a a a a a a ) ( v2 h
h h h h ) ( a a a a a a a ) ( v2
v3 h h h h ) ( a a a a a a ) (
v2 v3 v4 h h h ) ( a ) (
a )
```

where a denotes an element of the original matrix A , h denotes a modified element of the upper Hessenberg matrix H , and v_i denotes an element of the vector defining $H(i)$.

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NAME

cgelqf - compute an LQ factorization of a complex M-by-N matrix A

SYNOPSIS

```
SUBROUTINE CGELQF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE CGELQF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GELQF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE GELQF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: M, N, LDA, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgelqf(int m, int n, complex *a, int lda, complex *tau,  
           int *info);
```

```
void cgelqf_64(long m, long n, complex *a, long lda, complex  
              *tau, long *info);
```

PURPOSE

cgelqf computes an LQ factorization of a complex M-by-N matrix A: $A = L * Q$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the elements on and below the diagonal of the array contain the m-by-min(m,n) lower trapezoidal matrix L (L is lower triangular if $m \leq n$); the elements above the diagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, M)$. For optimum performance $LDWORK \geq M * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(k)' \dots H(2)' H(1)', \text{ where } k = \min(m, n).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $\text{conjg}(v(i+1:n))$ is stored on exit in $A(i,i+1:n)$, and tau in $TAU(i)$.

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NAME

cgels - solve overdetermined or underdetermined complex linear systems involving an M-by-N matrix A, or its conjugate-transpose, using a QR or LQ factorization of A

SYNOPSIS

```
SUBROUTINE CGELS(TRANSA, M, N, NRHS, A, LDA, B, LDB, WORK, LDWORK,  
                INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE CGELS_64(TRANSA, M, N, NRHS, A, LDA, B, LDB, WORK, LDWORK,  
                  INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GELS([TRANSA], [M], [N], [NRHS], A, [LDA], B, [LDB], [WORK],  
              LDWORK, [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE GELS_64([TRANSA], [M], [N], [NRHS], A, [LDA], B, [LDB],  
                 [WORK], LDWORK, [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: M, N, NRHS, LDA, LDB, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```

void cgels (char, int, int, int, complex*, int, complex*,
            int, int*);

void cgels_64 (char, long, long, long, complex*, long, com-
              plex*, long, long*);

```

PURPOSE

cgels solves overdetermined or underdetermined complex linear systems involving an M-by-N matrix A, or its conjugate-transpose, using a QR or LQ factorization of A. It is assumed that A has full rank.

The following options are provided:

1. If TRANS = 'N' and $m \geq n$: find the least squares solution of
 an overdetermined system, i.e., solve the least squares problem

$$\text{minimize } \| B - A * X \|^2.$$

2. If TRANS = 'N' and $m < n$: find the minimum norm solution of
 an underdetermined system $A * X = B$.

3. If TRANS = 'C' and $m \geq n$: find the minimum norm solution of
 an undetermined system $A^{*H} * X = B$.

4. If TRANS = 'C' and $m < n$: find the least squares solution of
 an overdetermined system, i.e., solve the least squares problem

$$\text{minimize } \| B - A^{*H} * X \|^2.$$

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

ARGUMENTS

TRANSA (input)
 = 'N': the linear system involves A;
 = 'C': the linear system involves A^{*H} .

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. if $M \geq N$, A is overwritten by details of its QR factorization as returned by CGEQRF; if $M < N$, A is overwritten by details of its LQ factorization as returned by CGELQF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)

On entry, the matrix B of right hand side vectors, stored columnwise; B is M-by-NRHS if TRANSA = 'N', or N-by-NRHS if TRANSA = 'C'. On exit, B is overwritten by the solution vectors, stored columnwise: if TRANSA = 'N' and $m \geq n$, rows 1 to n of B contain the least squares solution vectors; the residual sum of squares for the solution in each column is given by the sum of squares of elements N+1 to M in that column; if TRANSA = 'N' and $m < n$, rows 1 to N of B contain the minimum norm solution vectors; if TRANSA = 'C' and $m \geq n$, rows 1 to M of B contain the minimum norm solution vectors; if TRANSA = 'C' and $m < n$, rows 1 to M of B contain the least squares solution vectors; the residual sum of squares for the solution in each column is given by the sum of squares of elements M+1 to N in that column.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, M, N)$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (output)

The dimension of the array WORK. $LDWORK \geq \max(1, MN + \max(MN, NRHS))$. For optimal performance, $LDWORK \geq \max(1, MN + \max(MN, NRHS) * NB)$. where $MN = \min(M, N)$ and NB is the optimum block size.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cgelsd - compute the minimum-norm solution to a real linear least squares problem

SYNOPSIS

```
SUBROUTINE CGELSD(M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK, WORK,  
                 LWORK, RWORK, IWORK, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER IWORK(*)  
REAL RCOND  
REAL S(*), RWORK(*)
```

```
SUBROUTINE CGELSD_64(M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK,  
                   WORK, LWORK, RWORK, IWORK, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER*8 IWORK(*)  
REAL RCOND  
REAL S(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSD([M], [N], [NRHS], A, [LDA], B, [LDB], S, RCOND,  
                RANK, [WORK], [LWORK], [RWORK], [IWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL :: RCOND  
REAL, DIMENSION(:) :: S, RWORK
```

```
SUBROUTINE GELSD_64([M], [N], [NRHS], A, [LDA], B, [LDB], S, RCOND,  
                   RANK, [WORK], [LWORK], [RWORK], [IWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK
```

```
COMPLEX, DIMENSION(:,:) :: A, B
INTEGER(8) :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL :: RCOND
REAL, DIMENSION(:) :: S, RWORK
```

C INTERFACE

```
#include <sunperf.h>
void cgelsd(int m, int n, int nrhs, complex *a, int lda,
            complex *b, int ldb, float *s, float rcond, int
            *rank, int *info);

void cgelsd_64(long m, long n, long nrhs, complex *a, long
               lda, complex *b, long ldb, float *s, float rcond,
               long *rank, long *info);
```

PURPOSE

cgelsd computes the minimum-norm solution to a real linear least squares problem:

minimize 2-norm(| b - A*x |)
using the singular value decomposition (SVD) of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The problem is solved in three steps:

- (1) Reduce the coefficient matrix A to bidiagonal form with Householder transformations, reducing the original problem into a "bidiagonal least squares problem" (BLS)
- (2) Solve the BLS using a divide and conquer approach.
- (3) Apply back all the Householder transformations to solve the original least squares problem.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

M (input) The number of rows of the matrix A. M >= 0.

N (input) The number of columns of the matrix A. N >= 0.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS \geq 0.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A has been destroyed.

LDA (input)
 The leading dimension of the array A. LDA \geq max(1,M).

B (input/output)
 On entry, the M-by-NRHS right hand side matrix B. On exit, B is overwritten by the N-by-NRHS solution matrix X. If $m \geq n$ and RANK = n, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements n+1:m in that column.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,M,N).

S (output)
 The singular values of A in decreasing order. The condition number of A in the 2-norm = S(1)/S(min(m,n)).

RCOND (input)
 RCOND is used to determine the effective rank of A. Singular values S(i) \leq RCOND*S(1) are treated as zero. If RCOND < 0, machine precision is used instead.

RANK (output)
 The effective rank of A, i.e., the number of singular values which are greater than RCOND*S(1).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq 1. The exact minimum amount of workspace needed depends on M, N and NRHS. If $M \geq N$, LWORK $\geq 2*N + N*NRHS$. If $M < N$, LWORK $\geq 2*M + M*NRHS$. For good performance, LWORK should generally be larger.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
 If $M \geq N$, LRWORK $\geq 8*N + 2*N*SMLSIZ + 8*N*NLVL + N*NRHS$. If $M < N$, LRWORK $\geq 8*M + 2*M*SMLSIZ + 8*M*NLVL + M*NRHS$. SMLSIZ is returned by ILAENV

and is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25), and $NLVL = \text{INT}(\text{LOG}_2(\text{MIN}(M,N)/(\text{SMLSIZ}+1))) + 1$

IWORK (workspace)

$LIWORK \geq 3 * \text{MINMN} * NLVL + 11 * \text{MINMN}$, where $\text{MINMN} = \text{MIN}(M,N)$.

INFO (output)

= 0: successful exit

< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value.

> 0: the algorithm for computing the SVD failed to converge; if $\text{INFO} = i$, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

FURTHER DETAILS

Based on contributions by

Ming Gu and Ren-Cang Li, Computer Science Division,
University of California at Berkeley, USA

Osni Marques, LBNL/NERSC, USA

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NAME

cgelss - compute the minimum norm solution to a complex linear least squares problem

SYNOPSIS

```
SUBROUTINE CGELSS(M, N, NRHS, A, LDA, B, LDB, SING, RCOND, IRANK,  
                WORK, LDWORK, WORK2, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL RCOND  
REAL SING(*), WORK2(*)
```

```
SUBROUTINE CGELSS_64(M, N, NRHS, A, LDA, B, LDB, SING, RCOND, IRANK,  
                   WORK, LDWORK, WORK2, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL RCOND  
REAL SING(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GELSS([M], [N], [NRHS], A, [LDA], B, [LDB], SING, RCOND,  
                IRANK, [WORK], [LDWORK], [WORK2], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: SING, WORK2
```

```
SUBROUTINE GELSS_64([M], [N], [NRHS], A, [LDA], B, [LDB], SING,  
                   RCOND, IRANK, [WORK], [LDWORK], [WORK2], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER(8) :: M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: SING, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void cgelss(int m, int n, int nrhs, complex *a, int lda,
            complex *b, int ldb, float *sing, float rcond, int
            *irank, int *info);
void cgelss_64(long m, long n, long nrhs, complex *a, long
               lda, complex *b, long ldb, float *sing, float
               rcond, long *irank, long *info);
```

PURPOSE

cgelss computes the minimum norm solution to a complex linear least squares problem:

Minimize 2-norm($| b - A*x |$).

using the singular value decomposition (SVD) of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the first $\min(m,n)$ rows of A are overwritten with its right singular vectors, stored rowwise.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, B is overwritten by the N-by-NRHS solution matrix X. If $m \geq n$ and $IRANK = n$, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements $n+1:m$ in that column.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, M, N)$.

SING (output)
The singular values of A in decreasing order. The condition number of A in the 2-norm = $SING(1)/SING(\min(m, n))$.

RCOND (input)
RCOND is used to determine the effective rank of A. Singular values $SING(i) \leq RCOND * SING(1)$ are treated as zero. If $RCOND < 0$, machine precision is used instead.

IRANK (output)
The effective rank of A, i.e., the number of singular values which are greater than $RCOND * SING(1)$.

WORK (workspace)
On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LDWORK.

LDWORK (input)
The dimension of the array WORK. $LDWORK \geq 1$, and also: $LDWORK \geq 2 * \min(M, N) + \max(M, N, NRHS)$ For good performance, LDWORK should generally be larger.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
 $\text{dimension}(5 * \min(M, N))$

INFO (output)
= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value.
> 0: the algorithm for computing the SVD failed to converge; if $INFO = i$, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

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NAME

cgelsx - routine is deprecated and has been replaced by routine CGELSY

SYNOPSIS

```
SUBROUTINE CGELSX(M, N, NRHS, A, LDA, B, LDB, JPIVOT, RCOND, IRANK,  
  WORK, WORK2, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER JPIVOT(*)  
REAL RCOND  
REAL WORK2(*)
```

```
SUBROUTINE CGELSX_64(M, N, NRHS, A, LDA, B, LDB, JPIVOT, RCOND,  
  IRANK, WORK, WORK2, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER*8 JPIVOT(*)  
REAL RCOND  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GELSX([M], [N], [NRHS], A, [LDA], B, [LDB], JPIVOT, RCOND,  
  IRANK, [WORK], [WORK2], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER, DIMENSION(:) :: JPIVOT  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE GELSX_64([M], [N], [NRHS], A, [LDA], B, [LDB], JPIVOT,  
  RCOND, IRANK, [WORK], [WORK2], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER(8) :: M, N, NRHS, LDA, LDB, IRANK, INFO
```

```

INTEGER(8), DIMENSION(:) :: JPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>
void cgelsx(int m, int n, int nrhs, complex *a, int lda,
           complex *b, int ldb, int *jpivot, float rcond, int
           *irank, int *info);

void cgelsx_64(long m, long n, long nrhs, complex *a, long
              lda, complex *b, long ldb, long *jpivot, float
              rcond, long *irank, long *info);

```

PURPOSE

cgelsx routine is deprecated and has been replaced by routine CGELSY.

CGELSX computes the minimum-norm solution to a complex linear least squares problem:

$$\text{minimize } || A * X - B ||$$

using a complete orthogonal factorization of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The routine first computes a QR factorization with column pivoting:

$$A * P = Q * \begin{bmatrix} R11 & R12 \\ 0 & R22 \end{bmatrix}$$

with R11 defined as the largest leading submatrix whose estimated condition number is less than 1/RCOND. The order of R11, RANK, is the effective rank of A.

Then, R22 is considered to be negligible, and R12 is annihilated by unitary transformations from the right, arriving at the complete orthogonal factorization:

$$A * P = Q * \begin{bmatrix} T11 & 0 \\ 0 & 0 \end{bmatrix} * Z$$

The minimum-norm solution is then

$$X = P * Z' \begin{bmatrix} \text{inv}(T11)*Q1'*B \\ 0 \end{bmatrix}$$

where Q1 consists of the first RANK columns of Q.

ARGUMENTS

M (input) The number of rows of the matrix A. M >= 0.

N (input) The number of columns of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number

of columns of matrices B and X. NRHS \geq 0.

A (input/output)

On entry, the M-by-N matrix A. On exit, A has been overwritten by details of its complete orthogonal factorization.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,M).

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, the N-by-NRHS solution matrix X. If $m \geq n$ and IRANK = n, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements N+1:M in that column.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,M,N).

JPIVOT (input/output)

On entry, if JPIVOT(i) \neq 0, the i-th column of A is an initial column, otherwise it is a free column. Before the QR factorization of A, all initial columns are permuted to the leading positions; only the remaining free columns are moved as a result of column pivoting during the factorization. On exit, if JPIVOT(i) = k, then the i-th column of A*P was the k-th column of A.

RCOND (input)

RCOND is used to determine the effective rank of A, which is defined as the order of the largest leading triangular submatrix R11 in the QR factorization with pivoting of A, whose estimated condition number $< 1/\text{RCOND}$.

IRANK (output)

The effective rank of A, i.e., the order of the submatrix R11. This is the same as the order of the submatrix T11 in the complete orthogonal factorization of A.

WORK (workspace)

(min(M,N) + max(N, 2*min(M,N)+NRHS)),

WORK2 (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cgelsy - compute the minimum-norm solution to a complex linear least squares problem

SYNOPSIS

```
SUBROUTINE CGELSY(M, N, NRHS, A, LDA, B, LDB, JPVT, RCOND, RANK,  
                WORK, LWORK, RWORK, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER JPVT(*)  
REAL RCOND  
REAL RWORK(*)
```

```
SUBROUTINE CGELSY_64(M, N, NRHS, A, LDA, B, LDB, JPVT, RCOND, RANK,  
                   WORK, LWORK, RWORK, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER*8 JPVT(*)  
REAL RCOND  
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSY([M], [N], [NRHS], A, [LDA], B, [LDB], JPVT, RCOND,  
                RANK, [WORK], [LWORK], [RWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER, DIMENSION(:) :: JPVT  
REAL :: RCOND  
REAL, DIMENSION(:) :: RWORK
```

```
SUBROUTINE GELSY_64([M], [N], [NRHS], A, [LDA], B, [LDB], JPVT,  
                   RCOND, RANK, [WORK], [LWORK], [RWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK
```

```

COMPLEX, DIMENSION(:, :) :: A, B
INTEGER(8) :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO
INTEGER(8), DIMENSION(:) :: JPVT
REAL :: RCOND
REAL, DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>
void cgelsy(int m, int n, int nrhs, complex *a, int lda,
            complex *b, int ldb, int *jpvt, float rcond, int
            *rank, int *info);

void cgelsy_64(long m, long n, long nrhs, complex *a, long
              lda, complex *b, long ldb, long *jpvt, float
              rcond, long *rank, long *info);

```

PURPOSE

cgelsy computes the minimum-norm solution to a complex linear least squares problem:

minimize $\|A * X - B\|$
using a complete orthogonal factorization of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The routine first computes a QR factorization with column pivoting:

$$A * P = Q * \begin{bmatrix} R11 & R12 \\ 0 & R22 \end{bmatrix}$$

with R11 defined as the largest leading submatrix whose estimated condition number is less than 1/RCOND. The order of R11, RANK, is the effective rank of A.

Then, R22 is considered to be negligible, and R12 is annihilated by unitary transformations from the right, arriving at the complete orthogonal factorization:

$$A * P = Q * \begin{bmatrix} T11 & 0 \\ 0 & 0 \end{bmatrix} * Z$$

The minimum-norm solution is then

$$X = P * Z' \begin{bmatrix} \text{inv}(T11) * Q1' * B \\ 0 \end{bmatrix}$$

where Q1 consists of the first RANK columns of Q.

This routine is basically identical to the original xGELSX except three differences:

- o The permutation of matrix B (the right hand side) is faster and more simple.
- o The call to the subroutine xGEQPF has been substituted by the call to the subroutine xGEQP3. This subroutine is a Blas-3 version of the QR factorization with column pivoting.
- o Matrix B (the right hand side) is updated with Blas-3.

ARGUMENTS

- M (input) The number of rows of the matrix A. $M \geq 0$.
- N (input) The number of columns of the matrix A. $N \geq 0$.
- NRHS (input)
The number of right hand sides, i.e., the number of columns of matrices B and X. $NRHS \geq 0$.
- A (input/output)
On entry, the M-by-N matrix A. On exit, A has been overwritten by details of its complete orthogonal factorization.
- LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.
- B (input/output)
On entry, the M-by-NRHS right hand side matrix B. On exit, the N-by-NRHS solution matrix X.
- LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, M, N)$.
- JPVT (input/output)
On entry, if $JPVT(i) \neq 0$, the i-th column of A is permuted to the front of AP, otherwise column i is a free column. On exit, if $JPVT(i) = k$, then the i-th column of A^*P was the k-th column of A.
- RCOND (input)
RCOND is used to determine the effective rank of A, which is defined as the order of the largest leading triangular submatrix R11 in the QR factorization with pivoting of A, whose estimated condition number $< 1/RCOND$.
- RANK (output)
The effective rank of A, i.e., the order of the submatrix R11. This is the same as the order of the submatrix T11 in the complete orthogonal factorization of A.
- WORK (workspace)
On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.
- LWORK (input)
The dimension of the array WORK. The unblocked strategy requires that: $LWORK \geq MN + \max(2*MN, N+1, MN+NRHS)$ where $MN = \min(M, N)$. The block algorithm requires that: $LWORK \geq MN + \max(2*MN, NB*(N+1), MN+MN*NB, MN+NB*NRHS)$ where NB is an upper bound on the blocksize returned by ILAENV for the routines CGEQP3, CTZRZF, CTZRQF, CUNMQR, and CUNMRZ.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
dimension(2*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by

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E. Quintana-Orti, Depto. de Informatica, Universidad Jaime I, Spain

G. Quintana-Orti, Depto. de Informatica, Universidad Jaime I, Spain

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NAME

cgemm - perform one of the matrix-matrix operations $C := \alpha * \text{op}(A) * \text{op}(B) + \beta * C$

SYNOPSIS

```
SUBROUTINE CGEMM(TRANSA, TRANSB, M, N, K, ALPHA, A, LDA, B, LDB,
  BETA, C, LDC)
```

```
CHARACTER * 1 TRANSA, TRANSB
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER M, N, K, LDA, LDB, LDC
```

```
SUBROUTINE CGEMM_64(TRANSA, TRANSB, M, N, K, ALPHA, A, LDA, B, LDB,
  BETA, C, LDC)
```

```
CHARACTER * 1 TRANSA, TRANSB
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 M, N, K, LDA, LDB, LDC
```

F95 INTERFACE

```
SUBROUTINE GEMM([TRANSA], [TRANSB], [M], [N], [K], ALPHA, A, [LDA],
  B, [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: TRANSA, TRANSB
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:, :) :: A, B, C
INTEGER :: M, N, K, LDA, LDB, LDC
```

```
SUBROUTINE GEMM_64([TRANSA], [TRANSB], [M], [N], [K], ALPHA, A, [LDA],
  B, [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: TRANSA, TRANSB
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:, :) :: A, B, C
INTEGER(8) :: M, N, K, LDA, LDB, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```

void cgemmm(char transa, char transb, int m, int n, int k,
            complex *alpha, complex *a, int lda, complex *b,
            int ldb, complex *beta, complex *c, int ldc);

void cgemmm_64(char transa, char transb, long m, long n, long
               k, complex *alpha, complex *a, long lda, complex
               *b, long ldb, complex *beta, complex *c, long
               ldc);

```

PURPOSE

cgemmm performs one of the matrix-matrix operations

$$C := \alpha * \text{op}(A) * \text{op}(B) + \beta * C$$

where $\text{op}(X)$ is one of

$\text{op}(X) = X$ or $\text{op}(X) = X'$ or $\text{op}(X) = \text{conjg}(X')$, α and β are scalars, and A , B and C are matrices, with $\text{op}(A)$ an m by k matrix, $\text{op}(B)$ a k by n matrix and C an m by n matrix.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n', $\text{op}(A) = A$.

TRANSA = 'T' or 't', $\text{op}(A) = A'$.

TRANSA = 'C' or 'c', $\text{op}(A) = \text{conjg}(A')$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

TRANSB (input)

On entry, TRANSB specifies the form of $\text{op}(B)$ to be used in the matrix multiplication as follows:

TRANSB = 'N' or 'n', $\text{op}(B) = B$.

TRANSB = 'T' or 't', $\text{op}(B) = B'$.

TRANSB = 'C' or 'c', $\text{op}(B) = \text{conjg}(B')$.

Unchanged on exit.

TRANSB is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix $\text{op}(A)$ and of the matrix C . $M \geq$

0. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix $op(B)$ and the number of columns of the matrix C. $N \geq 0$. Unchanged on exit.

K (input)

On entry, K specifies the number of columns of the matrix $op(A)$ and the number of rows of the matrix $op(B)$. $K \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

COMPLEX array of DIMENSION (LDA, ka), where ka is K when TRANS = 'N' or 'n', and is M otherwise. Before entry with TRANS = 'N' or 'n', the leading M by K part of the array A must contain the matrix A, otherwise the leading K by M part of the array A must contain the matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When TRANS = 'N' or 'n' then $LDA \geq \max(1, M)$, otherwise $LDA \geq \max(1, K)$. Unchanged on exit.

B (input)

COMPLEX array of DIMENSION (LDB, kb), where kb is n when TRANS = 'N' or 'n', and is k otherwise. Before entry with TRANS = 'N' or 'n', the leading k by n part of the array B must contain the matrix B, otherwise the leading n by k part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. When TRANS = 'N' or 'n' then $LDB \geq \max(1, k)$, otherwise $LDB \geq \max(1, n)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then C need not be set on input. Unchanged on exit.

C (input/output)

COMPLEX array of DIMENSION (LDC, n). Before entry, the leading m by n part of the array C must contain the matrix C, except when beta is zero, in which case C need not be set on entry. On exit, the array C is overwritten by the m by n matrix ($\alpha * op(A) * op(B) + \beta * C$).

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. $LDC \geq \max(1, m)$. Unchanged on exit.

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NAME

cgemv - perform one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A' x + \beta y$, or $y := \alpha \text{conjg}(A) x + \beta y$

SYNOPSIS

```
SUBROUTINE CGEMV(TRANSA, M, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA  
COMPLEX ALPHA, BETA  
COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER M, N, LDA, INCX, INCY
```

```
SUBROUTINE CGEMV_64(TRANSA, M, N, ALPHA, A, LDA, X, INCX, BETA, Y,  
    INCY)
```

```
CHARACTER * 1 TRANSA  
COMPLEX ALPHA, BETA  
COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER*8 M, N, LDA, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE GEMV([TRANSA], [M], [N], ALPHA, A, [LDA], X, [INCX], BETA,  
    Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, INCX, INCY
```

```
SUBROUTINE GEMV_64([TRANSA], [M], [N], ALPHA, A, [LDA], X, [INCX],  
    BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>

void cgemv(char transa, int m, int n, complex *alpha, complex
 *a, int lda, complex *x, int incx, complex
 *beta, complex *y, int incy);
void cgemv_64(char transa, long m, long n, complex *alpha,
 complex *a, long lda, complex *x, long incx, complex
 *beta, complex *y, long incy);
```

PURPOSE

cgemv performs one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A' x + \beta y$, or $y := \alpha \text{conjg}(A') x + \beta y$ where α and β are scalars, x and y are vectors and A is an m by n matrix.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $y := \alpha A x + \beta y$.

TRANSA = 'T' or 't' $y := \alpha A' x + \beta y$.

TRANSA = 'C' or 'c' $y := \alpha \text{conjg}(A') x + \beta y$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry, the leading m by n part of the array A must contain the matrix of coefficients. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, m)$. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$) when TRANSA = 'N' or 'n' and at least ($1 + (m - 1) * \text{abs}(\text{INCX})$) otherwise. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

($1 + (m - 1) * \text{abs}(\text{INCY})$) when TRANSA = 'N' or 'n' and at least ($1 + (n - 1) * \text{abs}(\text{INCY})$) otherwise. Before entry with BETA non-zero, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

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NAME

cgeqlf - compute a QL factorization of a complex M-by-N matrix A

SYNOPSIS

```
SUBROUTINE CGEQLF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE CGEQLF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GEQLF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE GEQLF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: M, N, LDA, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgeqlf(int m, int n, complex *a, int lda, complex *tau,  
           int *info);
```

```
void cgeqlf_64(long m, long n, complex *a, long lda, complex  
              *tau, long *info);
```

PURPOSE

cgeqlf computes a QL factorization of a complex M-by-N matrix A: $A = Q * L$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $m \geq n$, the lower triangle of the subarray $A(m-n+1:m, 1:n)$ contains the N-by-N lower triangular matrix L; if $m < n$, the elements on and below the $(n-m)$ -th superdiagonal contain the M-by-N lower trapezoidal matrix L; the remaining elements, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(k) \dots H(2) H(1)$, where $k = \min(m, n)$.
Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a complex scalar, and v is a complex vector with $v(m-k+i+1:m) = 0$ and $v(m-k+i) = 1$; $v(1:m-k+i-1)$ is stored on exit in $A(1:m-k+i-1, n-k+i)$, and τ in $TAU(i)$.

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NAME

cgeqp3 - compute a QR factorization with column pivoting of a matrix A

SYNOPSIS

```
SUBROUTINE CGEQP3(M, N, A, LDA, JPVT, TAU, WORK, LWORK, RWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)
INTEGER M, N, LDA, LWORK, INFO
INTEGER JPVT(*)
REAL RWORK(*)
```

```
SUBROUTINE CGEQP3_64(M, N, A, LDA, JPVT, TAU, WORK, LWORK, RWORK,
INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)
INTEGER*8 M, N, LDA, LWORK, INFO
INTEGER*8 JPVT(*)
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQP3([M], [N], A, [LDA], JPVT, TAU, [WORK], [LWORK],
[RWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER :: M, N, LDA, LWORK, INFO
INTEGER, DIMENSION(:) :: JPVT
REAL, DIMENSION(:) :: RWORK
```

```
SUBROUTINE GEQP3_64([M], [N], A, [LDA], JPVT, TAU, [WORK], [LWORK],
[RWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER(8) :: M, N, LDA, LWORK, INFO
INTEGER(8), DIMENSION(:) :: JPVT
REAL, DIMENSION(:) :: RWORK
```

C INTERFACE

```
#include <sunperf.h>

void cgeqp3(int m, int n, complex *a, int lda, int *jpvt,
            complex *tau, int *info);

void cgeqp3_64(long m, long n, complex *a, long lda, long
               *jpvt, complex *tau, long *info);
```

PURPOSE

cgeqp3 computes a QR factorization with column pivoting of a matrix A: $A^*P = Q^*R$ using Level 3 BLAS.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the upper triangle of the array contains the $\min(M,N)$ -by-N upper trapezoidal matrix R; the elements below the diagonal, together with the array TAU, represent the unitary matrix Q as a product of $\min(M,N)$ elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

JPVT (input/output)

On entry, if $JPVT(J) \neq 0$, the J-th column of A is permuted to the front of A*P (a leading column); if $JPVT(J)=0$, the J-th column of A is a free column. On exit, if $JPVT(J)=K$, then the J-th column of A*P was the K-th column of A.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

On exit, if $INFO=0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq N+1$. For optimal performance $LWORK \geq (N+1)*NB$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message

related to LWORK is issued by XERBLA.

RWORK (workspace)
dimension(2*N)

INFO (output)
= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m,n).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real/complex scalar, and v is a real/complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$, and τ in $TAU(i)$.

Based on contributions by

G. Quintana-Orti, Depto. de Informatica, Universidad Jaime I, Spain

X. Sun, Computer Science Dept., Duke University, USA

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NAME

cgeqpf - routine is deprecated and has been replaced by routine CGEQP3

SYNOPSIS

```
SUBROUTINE CGEQPF(M, N, A, LDA, JPIVOT, TAU, WORK, WORK2, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)
INTEGER M, N, LDA, INFO
INTEGER JPIVOT(*)
REAL WORK2(*)
```

```
SUBROUTINE CGEQPF_64(M, N, A, LDA, JPIVOT, TAU, WORK, WORK2, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)
INTEGER*8 M, N, LDA, INFO
INTEGER*8 JPIVOT(*)
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEQPF([M], [N], A, [LDA], JPIVOT, TAU, [WORK], [WORK2],
  [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER :: M, N, LDA, INFO
INTEGER, DIMENSION(:) :: JPIVOT
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEQPF_64([M], [N], A, [LDA], JPIVOT, TAU, [WORK], [WORK2],
  [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER(8) :: M, N, LDA, INFO
INTEGER(8), DIMENSION(:) :: JPIVOT
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>

void cgeqpf(int m, int n, complex *a, int lda, int *jpivot,
            complex *tau, int *info);

void cgeqpf_64(long m, long n, complex *a, long lda, long
               *jpivot, complex *tau, long *info);
```

PURPOSE

cgeqpf routine is deprecated and has been replaced by routine CGEQP3.

CGEQPF computes a QR factorization with column pivoting of a complex M-by-N matrix A: $A*P = Q*R$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$

A (input/output)

On entry, the M-by-N matrix A. On exit, the upper triangle of the array contains the $\min(M,N)$ -by-N upper triangular matrix R; the elements below the diagonal, together with the array TAU, represent the unitary matrix Q as a product of $\min(m,n)$ elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

JPIVOT (input/output)

On entry, if JPIVOT(i) $\neq 0$, the i-th column of A is permuted to the front of A*P (a leading column); if JPIVOT(i) = 0, the i-th column of A is a free column. On exit, if JPIVOT(i) = k, then the i-th column of A*P was the k-th column of A.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

dimension(N)

WORK2 (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n)$$

Each $H(i)$ has the form

$$H = I - \tau * v * v'$$

where τ is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$.

The matrix P is represented in `jpvt` as follows: If `jpvt(j) = i` then the j th column of P is the i th canonical unit vector.

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NAME

cgeqrf - compute a QR factorization of a complex M-by-N matrix A

SYNOPSIS

```
SUBROUTINE CGEQRF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE CGEQRF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GEQRF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE GEQRF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: M, N, LDA, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgeqrf(int m, int n, complex *a, int lda, complex *tau,  
           int *info);
```

```
void cgeqrf_64(long m, long n, complex *a, long lda, complex  
              *tau, long *info);
```

PURPOSE

cgeqrf computes a QR factorization of a complex M-by-N matrix A: $A = Q * R$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the elements on and above the diagonal of the array contain the min(M,N)-by-N upper trapezoidal matrix R (R is upper triangular if $m \geq n$); the elements below the diagonal, with the array TAU, represent the unitary matrix Q as a product of min(m,n) elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m, n).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$, and tau in $TAU(i)$.

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NAME

cgerc - perform the rank 1 operation $A := \alpha x \text{conjg}(y') + A$

SYNOPSIS

```
SUBROUTINE CGERC(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
COMPLEX ALPHA  
COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER M, N, INCX, INCY, LDA
```

```
SUBROUTINE CGERC_64(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
COMPLEX ALPHA  
COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER*8 M, N, INCX, INCY, LDA
```

F95 INTERFACE

```
SUBROUTINE GERC([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, INCX, INCY, LDA
```

```
SUBROUTINE GERC_64([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, INCX, INCY, LDA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgerc(int m, int n, complex *alpha, complex *x, int  
          incx, complex *y, int incy, complex *a, int lda);
```

```
void cgerc_64(long m, long n, complex *alpha, complex *x,  
             long incx, complex *y, long incy, complex *a, long
```

lda);

PURPOSE

cgerc performs the rank 1 operation $A := \alpha x \text{conjg}(y') + A$ where α is a scalar, x is an m element vector, y is an n element vector and A is an m by n matrix.

ARGUMENTS

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (m - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the m element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

Y (input)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

A (input/output)

Before entry, the leading m by n part of the array A must contain the matrix of coefficients. On exit, A is overwritten by the updated matrix.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, m)$. Unchanged on exit.

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NAME

cgerfs - improve the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CGERFS(TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,  
X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CGERFS_64(TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,  
LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GERFS([TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT,  
B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE GERFS_64([TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],  
IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX, DIMENSION(:) :: WORK
```

```
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>
void cgerfs(char transa, int n, int nrhs, complex *a, int
            lda, complex *af, int ldaf, int *ipivot, complex
            *b, int ldb, complex *x, int ldx, float *ferr,
            float *berr, int *info);

void cgerfs_64(char transa, long n, long nrhs, complex *a,
               long lda, complex *af, long ldaf, long *ipivot,
               complex *b, long ldb, complex *x, long ldx, float
               *ferr, float *berr, long *info);
```

PURPOSE

cgerfs improves the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The original N-by-N matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)

The factors L and U from the factorization $A = P * L * U$ as computed by CGETRF.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

IPIVOT (input)

The pivot indices from CGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by
CGETRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq
max(1,N).

FERR (output)
The estimated forward error bound for each solu-
tion vector X(j) (the j-th column of the solution
matrix X). If XTRUE is the true solution
corresponding to X(j), FERR(j) is an estimated
upper bound for the magnitude of the largest ele-
ment in (X(j) - XTRUE) divided by the magnitude of
the largest element in X(j). The estimate is as
reliable as the estimate for RCOND, and is almost
always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each
solution vector X(j) (i.e., the smallest relative
change in any element of A or B that makes X(j) an
exact solution).

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an
illegal value

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NAME

cgerqf - compute an RQ factorization of a complex M-by-N matrix A

SYNOPSIS

```
SUBROUTINE CGERQF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE CGERQF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GERQF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE GERQF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: M, N, LDA, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgerqf(int m, int n, complex *a, int lda, complex *tau,  
           int *info);
```

```
void cgerqf_64(long m, long n, complex *a, long lda, complex  
              *tau, long *info);
```

PURPOSE

cgerqf computes an RQ factorization of a complex M-by-N matrix A: $A = R * Q$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $m \leq n$, the upper triangle of the subarray A(1:m,n-m+1:n) contains the M-by-M upper triangular matrix R; if $m > n$, the elements on and above the (m-n)-th subdiagonal contain the M-by-N upper trapezoidal matrix R; the remaining elements, with the array TAU, represent the unitary matrix Q as a product of $\min(m,n)$ elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1,M)$. For optimum performance $LDWORK \geq M * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(1)' H(2)' \dots H(k)'$, where $k = \min(m,n)$.
Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where τ is a complex scalar, and v is a complex vector with $v(n-k+i+1:n) = 0$ and $v(n-k+i) = 1$; $\text{conjg}(v(1:n-k+i-1))$ is stored on exit in $A(m-k+i,1:n-k+i-1)$, and τ in $\text{TAU}(i)$.

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NAME

cgeru - perform the rank 1 operation $A := \alpha x y' + A$

SYNOPSIS

```
SUBROUTINE CGERU(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
COMPLEX ALPHA  
COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER M, N, INCX, INCY, LDA
```

```
SUBROUTINE CGERU_64(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
COMPLEX ALPHA  
COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER*8 M, N, INCX, INCY, LDA
```

F95 INTERFACE

```
SUBROUTINE GER([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, INCX, INCY, LDA
```

```
SUBROUTINE GER_64([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, INCX, INCY, LDA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgeru(int m, int n, complex *alpha, complex *x, int  
          incx, complex *y, int incy, complex *a, int lda);
```

```
void cgeru_64(long m, long n, complex *alpha, complex *x,  
             long incx, complex *y, long incy, complex *a, long  
             lda);
```

PURPOSE

cgeru performs the rank 1 operation $A := \alpha x y' + A$ where α is a scalar, x is an m element vector, y is an n element vector and A is an m by n matrix.

ARGUMENTS

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (m - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the m element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

Y (input)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

A (input/output)

Before entry, the leading m by n part of the array A must contain the matrix of coefficients. On exit, A is overwritten by the updated matrix.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, m)$. Unchanged on exit.

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NAME

cgesdd - compute the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors, by using divide-and-conquer method

SYNOPSIS

```
SUBROUTINE CGESDD(JOBZ, M, N, A, LDA, S, U, LDU, VT, LDVT, WORK,  
                 LWORK, RWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOBZ  
COMPLEX A(LDA,*), U(LDU,*), VT(LDVT,*), WORK(*)  
INTEGER M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER IWORK(*)  
REAL S(*), RWORK(*)
```

```
SUBROUTINE CGESDD_64(JOBZ, M, N, A, LDA, S, U, LDU, VT, LDVT, WORK,  
                   LWORK, RWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOBZ  
COMPLEX A(LDA,*), U(LDU,*), VT(LDVT,*), WORK(*)  
INTEGER*8 M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER*8 IWORK(*)  
REAL S(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GESDD(JOBZ, [M], [N], A, [LDA], S, U, [LDU], VT, [LDVT],  
                [WORK], [LWORK], [RWORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, U, VT  
INTEGER :: M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: S, RWORK
```

```
SUBROUTINE GESDD_64(JOBZ, [M], [N], A, [LDA], S, U, [LDU], VT, [LDVT],  
                  [WORK], [LWORK], [RWORK], [IWORK], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:,:) :: A, U, VT
INTEGER(8) :: M, N, LDA, LDU, LDVT, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: S, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void cgesdd(char jobz, int m, int n, complex *a, int lda,
            float *s, complex *u, int ldu, complex *vt, int
            ldvt, int *info);

void cgesdd_64(char jobz, long m, long n, complex *a, long
              lda, float *s, complex *u, long ldu, complex *vt,
              long ldvt, long *info);

```

PURPOSE

cgesdd computes the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors, by using divide-and-conquer method. The SVD is written

$$= U * SIGMA * conjugate-transpose(V)$$

where SIGMA is an M-by-N matrix which is zero except for its min(m,n) diagonal elements, U is an M-by-M unitary matrix, and V is an N-by-N unitary matrix. The diagonal elements of SIGMA are the singular values of A; they are real and non-negative, and are returned in descending order. The first min(m,n) columns of U and V are the left and right singular vectors of A.

Note that the routine returns VT = V**H, not V.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)

Specifies options for computing all or part of the matrix U:

= 'A': all M columns of U and all N rows of V**H are returned in the arrays U and VT; = 'S': the first min(M,N) columns of U and the first min(M,N) rows of V**H are returned in the arrays U and VT; = 'O': If M >= N, the first N columns of U are overwritten on the array A and all rows of V**H are returned in the array VT; otherwise, all

columns of U are returned in the array U and the first M rows of V**H are overwritten on the array A; = 'N': no columns of U or rows of V**H are computed.

M (input) The number of rows of the input matrix A. $M \geq 0$.

N (input) The number of columns of the input matrix A. $N \geq 0$.

A (input/output)
On entry, the M-by-N matrix A. On exit, if JOBZ = 'O', A is overwritten with the first N columns of U (the left singular vectors, stored columnwise) if $M \geq N$; A is overwritten with the first M rows of V**H (the right singular vectors, stored rowwise) otherwise. if JOBZ .ne. 'O', the contents of A are destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.

S (output)
The singular values of A, sorted so that $S(i) \geq S(i+1)$.

U (output)
 $UCOL = M$ if JOBZ = 'A' or JOBZ = 'O' and $M < N$; $UCOL = \min(M, N)$ if JOBZ = 'S'. If JOBZ = 'A' or JOBZ = 'O' and $M < N$, U contains the M-by-M unitary matrix U; if JOBZ = 'S', U contains the first $\min(M, N)$ columns of U (the left singular vectors, stored columnwise); if JOBZ = 'O' and $M \geq N$, or JOBZ = 'N', U is not referenced.

LDU (input)
The leading dimension of the array U. $LDU \geq 1$; if JOBZ = 'S' or 'A' or JOBZ = 'O' and $M < N$, $LDU \geq M$.

VT (output)
If JOBZ = 'A' or JOBZ = 'O' and $M \geq N$, VT contains the N-by-N unitary matrix V**H; if JOBZ = 'S', VT contains the first $\min(M, N)$ rows of V**H (the right singular vectors, stored rowwise); if JOBZ = 'O' and $M < N$, or JOBZ = 'N', VT is not referenced.

LDVT (input)
The leading dimension of the array VT. $LDVT \geq 1$; if JOBZ = 'A' or JOBZ = 'O' and $M \geq N$, $LDVT \geq N$; if JOBZ = 'S', $LDVT \geq \min(M, N)$.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. $LWORK \geq 1$. If $LWORK = -1$, then a workspace query is assumed. In

this case, the routine only calculates the optimal size of the work array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued. The minimum workspace size requirement is as follows:

```
If M >= N and M >= (MIN(M,N)*17/9):
  if JOBZ = 'N', LWORK >= 3*N
  if JOBZ = 'O', LWORK >= 2*N*N + 3*N
  if JOBZ = 'S', LWORK >= N*N + 3*N
  if JOBZ = 'A', LWORK >= N*N + 2*N + M Else if M
>= N and M >= (MIN(M,N)*5/3):
  if JOBZ = 'O', LWORK >= 2*N + M + N*N
  else LWORK >= 2*N + M Else if M >=N:
  if JOBZ = 'O', LWORK >= 2*N + M + N*N
  else LWORK >= 2*N + M Else if M < N and N >=
(MIN(M,N)*17/9):
  if JOBZ = 'N', LWORK >= 3*M
  if JOBZ = 'O', LWORK >= 2*M*M + 3*M
  if JOBZ = 'S', LWORK >= M*M + 3*M
  if JOBZ = 'A', LWORK >= M*M + 2*M + N Else if M
< N and N >= (MIN(M,N)*5/3):
  if JOBZ = 'O', LWORK >= 2*M + N + M*M
  else LWORK >= 2*M + N Else if M < N:
  if JOBZ = 'O', LWORK >= 2*M + N + M*M
  else LWORK >= 2*M + N
```

RWORK (workspace)

The size of workspace RWORK is not checked in the routine. If JOBZ = 'N', RWORK must be at least $7 \cdot \min(M,N)$. Otherwise, RWORK must be at least $5 \cdot \min(M,N) \cdot \min(M,N) + 5 \cdot \min(M,N)$

IWORK (workspace)

dimension($8 \cdot \min(M,N)$)

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: The updating process of SBDSDC did not converge.

FURTHER DETAILS

Based on contributions by

Ming Gu and Huan Ren, Computer Science Division, University of California at Berkeley, USA

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NAME

cgsv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CGESV(N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*)
INTEGER N, NRHS, LDA, LDB, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE CGESV_64(N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*)
INTEGER*8 N, NRHS, LDA, LDB, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GESV([N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
COMPLEX, DIMENSION(:,*) :: A, B
INTEGER :: N, NRHS, LDA, LDB, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GESV_64([N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
COMPLEX, DIMENSION(:,*) :: A, B
INTEGER(8) :: N, NRHS, LDA, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgsv(int n, int nrhs, complex *a, int lda, int
          *ipivot, complex *b, int ldb, int *info);
```

```
void cgsv_64(long n, long nrhs, complex *a, long lda, long
            *ipivot, complex *b, long ldb, long *info);
```

PURPOSE

cgsv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N matrix and X and B are N-by-NRHS matrices.

The LU decomposition with partial pivoting and row interchanges is used to factor A as

$$A = P * L * U,$$

where P is a permutation matrix, L is unit lower triangular, and U is upper triangular. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the N-by-N coefficient matrix A. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

IPIVOT (output)

The pivot indices that define the permutation matrix P; row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)

On entry, the N-by-NRHS matrix of right hand side matrix B. On exit, if $INFO = 0$, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, $U(i,i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution could not be computed.

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NAME

cgesvd - compute the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors

SYNOPSIS

```
SUBROUTINE CGESVD(JOBU, JOBVT, M, N, A, LDA, SING, U, LDU, VT, LDVT,  
  WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBU, JOBVT  
COMPLEX A(LDA,*), U(LDU,*), VT(LDVT,*), WORK(*)  
INTEGER M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL SING(*), WORK2(*)
```

```
SUBROUTINE CGESVD_64(JOBU, JOBVT, M, N, A, LDA, SING, U, LDU, VT,  
  LDVT, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBU, JOBVT  
COMPLEX A(LDA,*), U(LDU,*), VT(LDVT,*), WORK(*)  
INTEGER*8 M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL SING(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GESVD(JOBU, JOBVT, [M], [N], A, [LDA], SING, U, [LDU], VT,  
  [LDVT], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBVT  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, U, VT  
INTEGER :: M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL, DIMENSION(:) :: SING, WORK2
```

```
SUBROUTINE GESVD_64(JOBU, JOBVT, [M], [N], A, [LDA], SING, U, [LDU],  
  VT, [LDVT], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBVT  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, U, VT  
INTEGER(8) :: M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL, DIMENSION(:) :: SING, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void cgesvd(char jobu, char jobvt, int m, int n, complex *a,
            int lda, float *sing, complex *u, int ldu, complex
            *vt, int ldvt, int *info);
void cgesvd_64(char jobu, char jobvt, long m, long n, com-
               plex *a, long lda, float *sing, complex *u, long
               ldu, complex *vt, long ldvt, long *info);
```

PURPOSE

cgesvd computes the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors. The SVD is written

$$= U * SIGMA * \text{conjugate-transpose}(V)$$

where SIGMA is an M-by-N matrix which is zero except for its $\min(m,n)$ diagonal elements, U is an M-by-M unitary matrix, and V is an N-by-N unitary matrix. The diagonal elements of SIGMA are the singular values of A; they are real and non-negative, and are returned in descending order. The first $\min(m,n)$ columns of U and V are the left and right singular vectors of A.

Note that the routine returns V^{*H} , not V.

ARGUMENTS

JOBU (input)

Specifies options for computing all or part of the matrix U:

= 'A': all M columns of U are returned in array U:

= 'S': the first $\min(m,n)$ columns of U (the left singular vectors) are returned in the array U; =

'O': the first $\min(m,n)$ columns of U (the left singular vectors) are overwritten on the array A;

= 'N': no columns of U (no left singular vectors) are computed.

JOBVT (input)

Specifies options for computing all or part of the matrix V^{*H} :

= 'A': all N rows of V^{*H} are returned in the array VT;

= 'S': the first $\min(m,n)$ rows of V^{*H} (the right singular vectors) are returned in the array VT; =

'O': the first $\min(m,n)$ rows of V^{*H} (the right singular vectors) are overwritten on the array A;

= 'N': no rows of V^{*H} (no right singular vectors) are computed.

JOBVT and JOBVT cannot both be 'O'.

M (input) The number of rows of the input matrix A. $M \geq 0$.

N (input) The number of columns of the input matrix A. $N \geq 0$.

A (input/output)
On entry, the M-by-N matrix A. On exit, if JOBU = 'O', A is overwritten with the first $\min(m,n)$ columns of U (the left singular vectors, stored columnwise); if JOBVT = 'O', A is overwritten with the first $\min(m,n)$ rows of V^*H (the right singular vectors, stored rowwise); if JOBU .ne. 'O' and JOBVT .ne. 'O', the contents of A are destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,M)$.

SING (output)
The singular values of A, sorted so that $SING(i) \geq SING(i+1)$.

U (input) (LDU,M) if JOBU = 'A' or (LDU, $\min(M,N)$) if JOBU = 'S'. If JOBU = 'A', U contains the M-by-M unitary matrix U; if JOBU = 'S', U contains the first $\min(m,n)$ columns of U (the left singular vectors, stored columnwise); if JOBU = 'N' or 'O', U is not referenced.

LDU (input)
The leading dimension of the array U. $LDU \geq 1$; if JOBU = 'S' or 'A', $LDU \geq M$.

VT (input)
If JOBVT = 'A', VT contains the N-by-N unitary matrix V^*H ; if JOBVT = 'S', VT contains the first $\min(m,n)$ rows of V^*H (the right singular vectors, stored rowwise); if JOBVT = 'N' or 'O', VT is not referenced.

LDVT (input)
The leading dimension of the array VT. $LDVT \geq 1$; if JOBVT = 'A', $LDVT \geq N$; if JOBVT = 'S', $LDVT \geq \min(M,N)$.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
The dimension of the array WORK. $LDWORK \geq 1$. $LDWORK \geq 2 \cdot \min(M,N) + \max(M,N)$ For good performance, LDWORK should generally be larger.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
 $\text{DIMENSION}(5 \cdot \min(M,N))$. On exit, if INFO > 0, WORK2(1: $\min(M,N)$ -1) contains the unconverged

superdiagonal elements of an upper bidiagonal matrix B whose diagonal is in $SING$ (not necessarily sorted). B satisfies $A = U * B * VT$, so it has the same singular values as A , and singular vectors related by U and VT .

INFO (output)

= 0: successful exit.
< 0: if $INFO = -i$, the i -th argument had an illegal value.
> 0: if $CBDSQR$ did not converge, $INFO$ specifies how many superdiagonals of an intermediate bidiagonal form B did not converge to zero. See the description of $WORK2$ above for details.

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NAME

cgsvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CGESVX(FACT, TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
    EQUED, R, C, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
    WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*)
REAL RCOND
REAL R(*), C(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CGESVX_64(FACT, TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
    EQUED, R, C, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
    WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
REAL RCOND
REAL R(*), C(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GESVX(FACT, [TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],
    IPIVOT, EQUED, R, C, B, [LDB], X, [LDX], RCOND, FERR,
    BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:,:) :: A, AF, B, X
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: R, C, FERR, BERR, WORK2
```

```

SUBROUTINE GESVX_64(FACT, [TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],
    IPIVOT, EQUED, R, C, B, [LDB], X, [LDX], RCOND, FERR,
    BERR, [WORK], [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: R, C, FERR, BERR, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void cgesvx(char fact, char transa, int n, int nrhs, complex
    *a, int lda, complex *af, int ldaf, int *ipivot,
    char equed, float *r, float *c, complex *b, int
    ldb, complex *x, int ldx, float *rcond, float
    *ferr, float *berr, int *info);

```

```

void cgesvx_64(char fact, char transa, long n, long nrhs,
    complex *a, long lda, complex *af, long ldaf, long
    *ipivot, char equed, float *r, float *c, complex
    *b, long ldb, complex *x, long ldx, float *rcond,
    float *ferr, float *berr, long *info);

```

PURPOSE

cgesvx uses the LU factorization to compute the solution to a complex system of linear equations

$A * X = B$, where A is an N -by- N matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$TRANS = 'N'$: $diag(R)*A*diag(C) *inv(diag(C))*X = diag(R)*B$

$TRANS = 'T'$: $(diag(R)*A*diag(C))^*T *inv(diag(R))*X = diag(C)*B$

$TRANS = 'C'$: $(diag(R)*A*diag(C))^*H *inv(diag(R))*X = diag(C)*B$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A is

overwritten by $diag(R)*A*diag(C)$ and B by $diag(R)*B$ (if $TRANS='N'$)

or $diag(C)*B$ (if $TRANS = 'T'$ or $'C'$).

2. If $FACT = 'N'$ or $'E'$, the LU decomposition is used to factor the

matrix A (after equilibration if FACT = 'E') as
A = P * L * U,
where P is a permutation matrix, L is a unit lower triangular
matrix, and U is upper triangular.

3. If some $U(i,i)=0$, so that U is exactly singular, then the routine

returns with INFO = i. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.

5. Iterative refinement is applied to improve the computed solution

matrix and calculate error bounds and backward error estimates for it.

6. If equilibration was used, the matrix X is premultiplied by

diag(C) (if TRANS = 'N') or diag(R) (if TRANS = 'T' or 'C') so

that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF and IPIVOT contain the factored form of A. If EQUED is not 'N', the matrix A has been equilibrated with scaling factors given by R and C. A, AF, and IPIVOT are not modified. = 'N': The matrix A will be copied to AF and factored.

= 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

TRANS (input)

Specifies the form of the system of equations:

= 'N': $A * X = B$ (No transpose)

= 'T': $A^{**T} * X = B$ (Transpose)

= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANS is defaulted to 'N' for F95 INTERFACE.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)
 On entry, the N-by-N matrix A. If FACT = 'F' and EQUED is not 'N', then A must have been equilibrated by the scaling factors in R and/or C. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if EQUED .ne. 'N', A is scaled as follows:
 EQUED = 'R': A := diag(R) * A
 EQUED = 'C': A := A * diag(C)
 EQUED = 'B': A := diag(R) * A * diag(C).

LDA (input)
 The leading dimension of the array A. LDA >= max(1,N).

AF (input or output)
 If FACT = 'F', then AF is an input argument and on entry contains the factors L and U from the factorization $A = P*L*U$ as computed by CGETRF. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the factors L and U from the factorization $A = P*L*U$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the factors L and U from the factorization $A = P*L*U$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)
 The leading dimension of the array AF. LDAF >= max(1,N).

IPIVOT (input or output)
 If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the factorization $A = P*L*U$ as computed by CGETRF; row i of the matrix was interchanged with row IPIVOT(i).

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = P*L*U$ of the original matrix A.

If FACT = 'E', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = P*L*U$ of the equilibrated matrix A.

EQUED (input or output)
 Specifies the form of equilibration that was done.
 = 'N': No equilibration (always true if FACT = 'N').

= 'R': Row equilibration, i.e., A has been premultiplied by $\text{diag}(R)$. = 'C': Column equilibration, i.e., A has been postmultiplied by $\text{diag}(C)$. = 'B': Both row and column equilibration, i.e., A has been replaced by $\text{diag}(R) * A * \text{diag}(C)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

R (input or output)

The row scale factors for A. If EQUED = 'R' or 'B', A is multiplied on the left by $\text{diag}(R)$; if EQUED = 'N' or 'C', R is not accessed. R is an input argument if FACT = 'F'; otherwise, R is an output argument. If FACT = 'F' and EQUED = 'R' or 'B', each element of R must be positive.

C (input or output)

The column scale factors for A. If EQUED = 'C' or 'B', A is multiplied on the right by $\text{diag}(C)$; if EQUED = 'N' or 'R', C is not accessed. C is an input argument if FACT = 'F'; otherwise, C is an output argument. If FACT = 'F' and EQUED = 'C' or 'B', each element of C must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if TRANSA = 'N' and EQUED = 'R' or 'B', B is overwritten by $\text{diag}(R)*B$; if TRANSA = 'T' or 'C' and EQUED = 'C' or 'B', B is overwritten by $\text{diag}(C)*B$.

LDB (input)

The leading dimension of the array B. LDB \geq $\max(1,N)$.

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that A and B are modified on exit if EQUED \neq 'N', and the solution to the equilibrated system is $\text{inv}(\text{diag}(C))*X$ if TRANSA = 'N' and EQUED = 'C' or 'B', or $\text{inv}(\text{diag}(R))*X$ if TRANSA = 'T' or 'C' and EQUED = 'R' or 'B'.

LDX (input)

The leading dimension of the array X. LDX \geq $\max(1,N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated

upper bound for the magnitude of the largest element in $(X(j) - X_{TRUE})$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for $RCOND$, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(2*N) On exit, $WORK2(1)$ contains the reciprocal pivot growth factor $\text{norm}(A)/\text{norm}(U)$. The "max absolute element" norm is used. If $WORK2(1)$ is much less than 1, then the stability of the LU factorization of the (equilibrated) matrix A could be poor. This also means that the solution X , condition estimator $RCOND$, and forward error bound $FERR$ could be unreliable. If factorization fails with $0 < INFO \leq N$, then $WORK2(1)$ contains the reciprocal pivot growth factor for the leading $INFO$ columns of A .

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, and i is
 $\leq N$: $U(i,i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution and error bounds could not be computed. $RCOND = 0$ is returned.
 $= N+1$: U is nonsingular, but $RCOND$ is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of $RCOND$ would suggest.

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NAME

cgetf2 - compute an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE CGETF2(M, N, A, LDA, IPIV, INFO)
```

```
COMPLEX A(LDA,*)  
INTEGER M, N, LDA, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE CGETF2_64(M, N, A, LDA, IPIV, INFO)
```

```
COMPLEX A(LDA,*)  
INTEGER*8 M, N, LDA, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE GETF2([M], [N], A, [LDA], IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE GETF2_64([M], [N], A, [LDA], IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgetf2(int m, int n, complex *a, int lda, int *ipiv,  
           int *info);
```

```
void cgetf2_64(long m, long n, complex *a, long lda, long  
              *ipiv, long *info);
```

PURPOSE

cgetf2 computes an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges.

The factorization has the form

$$A = P * L * U$$

where P is a permutation matrix, L is lower triangular with unit diagonal elements (lower trapezoidal if $m > n$), and U is upper triangular (upper trapezoidal if $m < n$).

This is the right-looking Level 2 BLAS version of the algorithm.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the m by n matrix to be factored. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

IPIV (output)

The pivot indices; for $1 \leq i \leq \min(M,N)$, row i of the matrix was interchanged with row IPIV(i).

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value
> 0: if INFO = k, U(k,k) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

cgetrf - compute an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE CGETRF(M, N, A, LDA, IPIVOT, INFO)
```

```
COMPLEX A(LDA,*)  
INTEGER M, N, LDA, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CGETRF_64(M, N, A, LDA, IPIVOT, INFO)
```

```
COMPLEX A(LDA,*)  
INTEGER*8 M, N, LDA, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GETRF([M], [N], A, [LDA], IPIVOT, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GETRF_64([M], [N], A, [LDA], IPIVOT, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgetrf(int m, int n, complex *a, int lda, int *ipivot,  
           int *info);
```

```
void cgetrf_64(long m, long n, complex *a, long lda, long  
              *ipivot, long *info);
```

PURPOSE

cgetrf computes an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges.

The factorization has the form

$$A = P * L * U$$

where P is a permutation matrix, L is lower triangular with unit diagonal elements (lower trapezoidal if $m > n$), and U is upper triangular (upper trapezoidal if $m < n$).

This is the right-looking Level 3 BLAS version of the algorithm.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix to be factored. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

IPIVOT (output)

The pivot indices; for $1 \leq i \leq \min(M, N)$, row i of the matrix was interchanged with row IPIVOT(i).

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, $U(i, i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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cgetri - compute the inverse of a matrix using the LU factorization computed by CGETRF

SYNOPSIS

```
SUBROUTINE CGETRI(N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), WORK(*)
INTEGER N, LDA, LDWORK, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE CGETRI_64(N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
COMPLEX A(LDA,*), WORK(*)
INTEGER*8 N, LDA, LDWORK, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GETRI([N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER :: N, LDA, LDWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GETRI_64([N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER(8) :: N, LDA, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgetri(int n, complex *a, int lda, int *ipivot, int
           *info);
```

```
void cgetri_64(long n, complex *a, long lda, long *ipivot,
              long *info);
```

PURPOSE

cgetri computes the inverse of a matrix using the LU factorization computed by CGETRF.

This method inverts U and then computes $\text{inv}(A)$ by solving the system $\text{inv}(A)*L = \text{inv}(U)$ for $\text{inv}(A)$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the factors L and U from the factorization $A = P*L*U$ as computed by CGETRF. On exit, if $\text{INFO} = 0$, the inverse of the original matrix A.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

The pivot indices from CGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row $\text{IPIVOT}(i)$.

WORK (workspace)

On exit, if $\text{INFO} = 0$, then $\text{WORK}(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $\text{LDWORK} \geq \max(1, N)$. For optimal performance $\text{LDWORK} \geq N*NB$, where NB is the optimal blocksize returned by ILAENV.

If $\text{LDWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if $\text{INFO} = -i$, the i-th argument had an illegal value

> 0: if $\text{INFO} = i$, $U(i, i)$ is exactly zero; the matrix is singular and its inverse could not be computed.

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NAME

cgetrs - solve a system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$ with a general N-by-N matrix A using the LU factorization computed by CGETRF

SYNOPSIS

```
SUBROUTINE CGETRS(TRANSA, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CGETRS_64(TRANSA, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GETRS([TRANSA], [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GETRS_64([TRANSA], [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void cgetrs(char transa, int n, int nrhs, complex *a, int
           lda, int *ipivot, complex *b, int ldb, int *info);

void cgetrs_64(char transa, long n, long nrhs, complex *a,
              long lda, long *ipivot, complex *b, long ldb, long
              *info);

```

PURPOSE

cgetrs solves a system of linear equations
 $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$ with a general N-by-N matrix A using the LU factorization computed by CGETRF.

ARGUMENTS

TRANSA (input)
 Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose)
 TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The factors L and U from the factorization $A = P * L * U$ as computed by CGETRF.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)
 The pivot indices from CGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)
 On entry, the right hand side matrix B. On exit, the solution matrix X.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cggbak - form the right or left eigenvectors of a complex generalized eigenvalue problem $A*x = \lambda*B*x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by CGGBAL

SYNOPSIS

```
SUBROUTINE CGGBAK(JOB, SIDE, N, ILO, IHI, LSCALE, RSCALE, M, V, LDV,
INFO)
```

```
CHARACTER * 1 JOB, SIDE
COMPLEX V(LDV,*)
INTEGER N, ILO, IHI, M, LDV, INFO
REAL LSCALE(*), RSCALE(*)
```

```
SUBROUTINE CGGBAK_64(JOB, SIDE, N, ILO, IHI, LSCALE, RSCALE, M, V,
LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE
COMPLEX V(LDV,*)
INTEGER*8 N, ILO, IHI, M, LDV, INFO
REAL LSCALE(*), RSCALE(*)
```

F95 INTERFACE

```
SUBROUTINE GGBAK(JOB, SIDE, [N], ILO, IHI, LSCALE, RSCALE, [M], V,
[LDV], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE
COMPLEX, DIMENSION(:, :) :: V
INTEGER :: N, ILO, IHI, M, LDV, INFO
REAL, DIMENSION(:) :: LSCALE, RSCALE
```

```
SUBROUTINE GGBAK_64(JOB, SIDE, [N], ILO, IHI, LSCALE, RSCALE, [M], V,
[LDV], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE
COMPLEX, DIMENSION(:, :) :: V
INTEGER(8) :: N, ILO, IHI, M, LDV, INFO
```

REAL, DIMENSION(:) :: LSCALE, RSCALE

C INTERFACE

```
#include <sunperf.h>
```

```
void cggbak(char job, char side, int n, int ilo, int ihi,  
           float *lscale, float *rscale, int m, complex *v,  
           int ldv, int *info);
```

```
void cggbak_64(char job, char side, long n, long ilo, long  
              ihi, float *lscale, float *rscale, long m, complex  
              *v, long ldv, long *info);
```

PURPOSE

cggbak forms the right or left eigenvectors of a complex generalized eigenvalue problem $A*x = \lambda*B*x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by CGGBAL.

ARGUMENTS

JOB (input)

Specifies the type of backward transformation required:

= 'N': do nothing, return immediately;

= 'P': do backward transformation for permutation only;

= 'S': do backward transformation for scaling only;

= 'B': do backward transformations for both permutation and scaling. JOB must be the same as the argument JOB supplied to CGGBAL.

SIDE (input)

= 'R': V contains right eigenvectors;

= 'L': V contains left eigenvectors.

N (input) The number of rows of the matrix V. $N \geq 0$.

ILO (input)

The integers ILO and IHI determined by CGGBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

IHI (input)

The integers ILO and IHI determined by CGGBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

LSCALE (input)

Details of the permutations and/or scaling factors applied to the left side of A and B, as returned by CGGBAL.

RSCALE (input)

Details of the permutations and/or scaling factors applied to the right side of A and B, as returned

by CGGBAL.

M (input) The number of columns of the matrix V. $M \geq 0$.

V (input/output)

On entry, the matrix of right or left eigenvectors to be transformed, as returned by CTGEVC. On exit, V is overwritten by the transformed eigenvectors.

LDV (input)

The leading dimension of the matrix V. $LDV \geq \max(1, N)$.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

See R.C. Ward, Balancing the generalized eigenvalue problem, SIAM J. Sci. Stat. Comp. 2 (1981), 141-152.

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NAME

cggbal - balance a pair of general complex matrices (A,B)

SYNOPSIS

```
SUBROUTINE CGGBAL(JOB, N, A, LDA, B, LDB, ILO, IHI, LSCALE, RSCALE,  
WORK, INFO)
```

```
CHARACTER * 1 JOB  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, LDA, LDB, ILO, IHI, INFO  
REAL LSCALE(*), RSCALE(*), WORK(*)
```

```
SUBROUTINE CGGBAL_64(JOB, N, A, LDA, B, LDB, ILO, IHI, LSCALE,  
RSCALE, WORK, INFO)
```

```
CHARACTER * 1 JOB  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, LDA, LDB, ILO, IHI, INFO  
REAL LSCALE(*), RSCALE(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGBAL(JOB, [N], A, [LDA], B, [LDB], ILO, IHI, LSCALE,  
RSCALE, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: N, LDA, LDB, ILO, IHI, INFO  
REAL, DIMENSION(:) :: LSCALE, RSCALE, WORK
```

```
SUBROUTINE GGBAL_64(JOB, [N], A, [LDA], B, [LDB], ILO, IHI, LSCALE,  
RSCALE, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: N, LDA, LDB, ILO, IHI, INFO  
REAL, DIMENSION(:) :: LSCALE, RSCALE, WORK
```

C INTERFACE

```
#include <sunperf.h>

void cggbal(char job, int n, complex *a, int lda, complex
            *b, int ldb, int *ilo, int *ihi, float *lscale,
            float *rscale, int *info);

void cggbal_64(char job, long n, complex *a, long lda, com-
               plex *b, long ldb, long *ilo, long *ihi, float
               *lscale, float *rscale, long *info);
```

PURPOSE

cggbal balances a pair of general complex matrices (A,B). This involves, first, permuting A and B by similarity transformations to isolate eigenvalues in the first 1 to ILO\$-1 and last IHI+1 to N elements on the diagonal; and second, applying a diagonal similarity transformation to rows and columns ILO to IHI to make the rows and columns as close in norm as possible. Both steps are optional.

Balancing may reduce the 1-norm of the matrices, and improve the accuracy of the computed eigenvalues and/or eigenvectors in the generalized eigenvalue problem $A*x = \lambda*B*x$.

ARGUMENTS

JOB (input)

Specifies the operations to be performed on A and B:

= 'N': none: simply set ILO = 1, IHI = N, LSCALE(I) = 1.0 and RSCALE(I) = 1.0 for i=1,...,N;
 = 'P': permute only;
 = 'S': scale only;
 = 'B': both permute and scale.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the input matrix A. On exit, A is overwritten by the balanced matrix. If JOB = 'N', A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input) On entry, the input matrix B. On exit, B is overwritten by the balanced matrix. If JOB = 'N', B is not referenced.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

ILO (output)

ILO and IHI are set to integers such that on exit

$A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1, \dots, ILO-1$ or $i = IHI+1, \dots, N$. If $JOB = 'N'$ or $'S'$, $ILO = 1$ and $IHI = N$.

IHI (output)

ILO and IHI are set to integers such that on exit $A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1, \dots, ILO-1$ or $i = IHI+1, \dots, N$.

LSCALE (input)

Details of the permutations and scaling factors applied to the left side of A and B. If $P(j)$ is the index of the row interchanged with row j , and $D(j)$ is the scaling factor applied to row j , then $LSCALE(j) = P(j)$ for $J = 1, \dots, ILO-1$ and $D(j)$ for $J = ILO, \dots, IHI$; $LSCALE(j) = P(j)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

RSCALE (input)

Details of the permutations and scaling factors applied to the right side of A and B. If $P(j)$ is the index of the column interchanged with column j , and $D(j)$ is the scaling factor applied to column j , then $RSCALE(j) = P(j)$ for $J = 1, \dots, ILO-1$ and $D(j)$ for $J = ILO, \dots, IHI$; $RSCALE(j) = P(j)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

WORK (workspace)

dimension(6*N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value.

FURTHER DETAILS

See R.C. WARD, Balancing the generalized eigenvalue problem, SIAM J. Sci. Stat. Comp. 2 (1981), 141-152.

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NAME

cgges - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the generalized complex Schur form (S, T), and optionally left and/or right Schur vectors (VSL and VSR)

SYNOPSIS

```
SUBROUTINE CGGES(JOBVSL, JOBVSR, SORT, SELCTG, N, A, LDA, B, LDB,
                SDIM, ALPHA, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LWORK, RWORK,
                BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VSL(LDVSL,*),
VSR(LDVSR,*), WORK(*)
INTEGER N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL SELCTG
LOGICAL BWORK(*)
REAL RWORK(*)
```

```
SUBROUTINE CGGES_64(JOBVSL, JOBVSR, SORT, SELCTG, N, A, LDA, B, LDB,
                  SDIM, ALPHA, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LWORK, RWORK,
                  BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VSL(LDVSL,*),
VSR(LDVSR,*), WORK(*)
INTEGER*8 N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL*8 SELCTG
LOGICAL*8 BWORK(*)
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGES(JOBVSL, JOBVSR, SORT, [SELCTG], [N], A, [LDA], B, [LDB],
                SDIM, ALPHA, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK], [LWORK],
                [RWORK], [BWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:, :) :: A, B, VSL, VSR
INTEGER :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
```

```

LOGICAL :: SELCTG
LOGICAL, DIMENSION(:) :: BWORK
REAL, DIMENSION(:) :: RWORK

SUBROUTINE GGES_64(JOBVSL, JOBVSR, SORT, [SELCTG], [N], A, [LDA], B,
  [LDB], SDIM, ALPHA, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK],
  [LWORK], [RWORK], [BWORK], [INFO])

CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:, :) :: A, B, VSL, VSR
INTEGER(8) :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL(8) :: SELCTG
LOGICAL(8), DIMENSION(:) :: BWORK
REAL, DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>

void cggges(char jobvsl, char jobvsr, char sort,
  int(*selctg)(complex,complex), int n, complex *a,
  int lda, complex *b, int ldb, int *sdim, complex
  *alpha, complex *beta, complex *vsl, int ldvsl,
  complex *vsr, int ldvsr, int *info);

void cggges_64(char jobvsl, char jobvsr, char sort,
  long(*selctg)(complex,complex), long n, complex
  *a, long lda, complex *b, long ldb, long *sdim,
  complex *alpha, complex *beta, complex *vsl, long
  ldvsl, complex *vsr, long ldvsr, long *info);

```

PURPOSE

cggges computes for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the generalized complex Schur form (S, T), and optionally left and/or right Schur vectors (VSL and VSR). This gives the generalized Schur factorization

$$(A,B) = ((VSL)*S*(VSR)**H, (VSL)*T*(VSR)**H)$$

where (VSR)**H is the conjugate-transpose of VSR.

Optionally, it also orders the eigenvalues so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper triangular matrix S and the upper triangular matrix T. The leading columns of VSL and VSR then form an unitary basis for the corresponding left and right eigenspaces (deflating subspaces).

(If only the generalized eigenvalues are needed, use the driver CGGEV instead, which is faster.)

A generalized eigenvalue for a pair of matrices (A,B) is a scalar w or a ratio alpha/beta = w, such that A - w*B is singular. It is usually represented as the pair (alpha,beta), as there is a reasonable interpretation for beta=0, and even for both being zero.

A pair of matrices (S,T) is in generalized complex Schur form if S and T are upper triangular and, in addition, the diagonal elements of T are non-negative real numbers.

ARGUMENTS

JOBVSL (input)

= 'N': do not compute the left Schur vectors;
= 'V': compute the left Schur vectors.

JOBVSR (input)

= 'N': do not compute the right Schur vectors;
= 'V': compute the right Schur vectors.

SORT (input)

Specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form. =
'N': Eigenvalues are not ordered;
'S': Eigenvalues are ordered (see SELCTG).

SELCTG (input)

LOGICAL FUNCTION of two COMPLEX arguments SELCTG must be declared EXTERNAL in the calling subroutine. If SORT = 'N', SELCTG is not referenced. If SORT = 'S', SELCTG is used to select eigenvalues to sort to the top left of the Schur form. An eigenvalue ALPHA(j)/BETA(j) is selected if SELCTG(ALPHA(j),BETA(j)) is true.

Note that a selected complex eigenvalue may no longer satisfy SELCTG(ALPHA(j),BETA(j)) = .TRUE. after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned), in this case INFO is set to N+2 (See INFO below).

N (input) The order of the matrices A, B, VSL, and VSR. N
>= 0.

A (input/output)

On entry, the first of the pair of matrices. On exit, A has been overwritten by its generalized Schur form S.

LDA (input)

The leading dimension of A. LDA >= max(1,N).

B (input/output)

On entry, the second of the pair of matrices. On exit, B has been overwritten by its generalized Schur form T.

LDB (input)

The leading dimension of B. LDB >= max(1,N).

SDIM (output)

If SORT = 'N', SDIM = 0. If SORT = 'S', SDIM = number of eigenvalues (after sorting) for which SELCTG is true.

ALPHA (output)

On exit, ALPHA(j)/BETA(j), $j=1,\dots,N$, will be the generalized eigenvalues. ALPHA(j), $j=1,\dots,N$ and BETA(j), $j=1,\dots,N$ are the diagonals of the complex Schur form (A,B) output by CGGES. The BETA(j) will be non-negative real.

Note: the quotients ALPHA(j)/BETA(j) may easily over- or underflow, and BETA(j) may even be zero. Thus, the user should avoid naively computing the ratio alpha/beta. However, ALPHA will be always less than and usually comparable with norm(A) in magnitude, and BETA always less than and usually comparable with norm(B).

BETA (output)

See description of ALPHA.

VSL (input)

If JOBVSL = 'V', VSL will contain the left Schur vectors. Not referenced if JOBVSL = 'N'.

LDVSL (input)

The leading dimension of the matrix VSL. LDVSL ≥ 1 , and if JOBVSL = 'V', LDVSL $\geq N$.

VSR (input)

If JOBVSR = 'V', VSR will contain the right Schur vectors. Not referenced if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR ≥ 1 , and if JOBVSR = 'V', LDVSR $\geq N$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK $\geq \max(1,2*N)$. For good performance, LWORK must generally be larger.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

dimension(8*N)

BWORK (workspace)

dimension(N) Not referenced if SORT = 'N'.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
=1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHA(j) and BETA(j) should be

correct for $j=INFO+1, \dots, N$. $> N$: $=N+1$: other
than QZ iteration failed in CHGEQZ
 $=N+2$: after reordering, roundoff changed values of
some complex eigenvalues so that leading eigen-
values in the Generalized Schur form no longer
satisfy `SELCTG=.TRUE.` This could also be caused
due to scaling. $=N+3$: reordering failed in
CTGSEN.

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NAME

cggesx - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the complex Schur form (S,T),

SYNOPSIS

```
SUBROUTINE CGGESX(JOBVSL, JOBVSR, SORT, SELCTG, SENSE, N, A, LDA, B,
  LDB, SDIM, ALPHA, BETA, VSL, LDVSL, VSR, LDVSR, RCONDE, RCONDV,
  WORK, LWORK, RWORK, IWORK, LIWORK, BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT, SENSE
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VSL(LDVSL,*),
VSR(LDVSR,*), WORK(*)
INTEGER N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL SELCTG
LOGICAL BWORK(*)
REAL RCONDE(*), RCONDV(*), RWORK(*)
```

```
SUBROUTINE CGGESX_64(JOBVSL, JOBVSR, SORT, SELCTG, SENSE, N, A, LDA,
  B, LDB, SDIM, ALPHA, BETA, VSL, LDVSL, VSR, LDVSR, RCONDE,
  RCONDV, WORK, LWORK, RWORK, IWORK, LIWORK, BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT, SENSE
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VSL(LDVSL,*),
VSR(LDVSR,*), WORK(*)
INTEGER*8 N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK,
INFO
INTEGER*8 IWORK(*)
LOGICAL*8 SELCTG
LOGICAL*8 BWORK(*)
REAL RCONDE(*), RCONDV(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGESX(JOBVSL, JOBVSR, SORT, [SELCTG], SENSE, [N], A, [LDA],
  B, [LDB], SDIM, ALPHA, BETA, VSL, [LDVSL], VSR, [LDVSR], RCONDE,
  RCONDV, [WORK], [LWORK], [RWORK], [IWORK], [LIWORK], [BWORK],
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT, SENSE
```

```

COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:,:) :: A, B, VSL, VSR
INTEGER :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK,
INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL :: SELCTG
LOGICAL, DIMENSION(:) :: BWORK
REAL, DIMENSION(:) :: RCONDE, RCONDV, RWORK
SUBROUTINE GGESX_64(JOBVSL, JOBVSR, SORT, [SELCTG], SENSE, [N], A, [LDA],
    B, [LDB], SDIM, ALPHA, BETA, VSL, [LDVSL], VSR, [LDVSR], RCONDE,
    RCONDV, [WORK], [LWORK], [RWORK], [IWORK], [LIWORK], [BWORK],
    [INFO])

```

```

CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT, SENSE
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:,:) :: A, B, VSL, VSR
INTEGER(8) :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK,
LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8) :: SELCTG
LOGICAL(8), DIMENSION(:) :: BWORK
REAL, DIMENSION(:) :: RCONDE, RCONDV, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void cgesx(char jobvsl, char jobvsr, char sort,
    int(*selctg)(complex,complex), char sense, int n,
    complex *a, int lda, complex *b, int ldb, int
    *sdim, complex *alpha, complex *beta, complex
    *vsl, int ldvsl, complex *vsr, int ldvsr, float
    *rconde, float *rcondv, int *info);

void cgesx_64(char jobvsl, char jobvsr, char sort,
    long(*selctg)(complex,complex), char sense, long
    n, complex *a, long lda, complex *b, long ldb,
    long *sdim, complex *alpha, complex *beta, complex
    *vsl, long ldvsl, complex *vsr, long ldvsr, float
    *rconde, float *rcondv, long *info);

```

PURPOSE

cgesx computes for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the complex Schur form (S,T), and, optionally, the left and/or right matrices of Schur vectors (VSL and VSR). This gives the generalized Schur factorization $A,B = ((VSL) S (VSR)**H, (VSL) T (VSR)**H)$

where (VSR)**H is the conjugate-transpose of VSR.

Optionally, it also orders the eigenvalues so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper triangular matrix S and the upper triangular matrix T; computes a reciprocal condition number for the average of the selected eigenvalues (RCONDE); and computes a reciprocal condition number for the right and left deflating subspaces corresponding to the selected

eigenvalues (RCONDV). The leading columns of VSL and VSR then form an orthonormal basis for the corresponding left and right eigenspaces (deflating subspaces).

A generalized eigenvalue for a pair of matrices (A,B) is a scalar w or a ratio $\alpha/\beta = w$, such that $A - w*B$ is singular. It is usually represented as the pair (α,β) , as there is a reasonable interpretation for $\beta=0$ or for both being zero.

A pair of matrices (S,T) is in generalized complex Schur form if T is upper triangular with non-negative diagonal and S is upper triangular.

ARGUMENTS

JOBVSL (input)

= 'N': do not compute the left Schur vectors;
= 'V': compute the left Schur vectors.

JOBVSR (input)

= 'N': do not compute the right Schur vectors;
= 'V': compute the right Schur vectors.

SORT (input)

Specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form. = 'N': Eigenvalues are not ordered;
= 'S': Eigenvalues are ordered (see SELCTG).

SELCTG (input)

LOGICAL FUNCTION of two COMPLEX arguments SELCTG must be declared EXTERNAL in the calling subroutine. If SORT = 'N', SELCTG is not referenced. If SORT = 'S', SELCTG is used to select eigenvalues to sort to the top left of the Schur form. Note that a selected complex eigenvalue may no longer satisfy $SELCTG(ALPHA(j),BETA(j)) = .TRUE.$ after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned), in this case INFO is set to N+3 see INFO below).

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N' : None are computed;
= 'E' : Computed for average of selected eigenvalues only;
= 'V' : Computed for selected deflating subspaces only;
= 'B' : Computed for both. If SENSE = 'E', 'V', or 'B', SORT must equal 'S'.

N (input) The order of the matrices A, B, VSL, and VSR. $N \geq 0$.

A (input/output)

On entry, the first of the pair of matrices. On exit, A has been overwritten by its generalized

Schur form S.

LDA (input)

The leading dimension of A. LDA \geq max(1,N).

B (input/output)

On entry, the second of the pair of matrices. On exit, B has been overwritten by its generalized Schur form T.

LDB (input)

The leading dimension of B. LDB \geq max(1,N).

SDIM (output)

If SORT = 'N', SDIM = 0. If SORT = 'S', SDIM = number of eigenvalues (after sorting) for which SELCTG is true.

ALPHA (output)

On exit, ALPHA(j)/BETA(j), $j=1,\dots,N$, will be the generalized eigenvalues. ALPHA(j) and BETA(j), $j=1,\dots,N$ are the diagonals of the complex Schur form (S,T). BETA(j) will be non-negative real.

Note: the quotients ALPHA(j)/BETA(j) may easily over- or underflow, and BETA(j) may even be zero. Thus, the user should avoid naively computing the ratio alpha/beta. However, ALPHA will be always less than and usually comparable with norm(A) in magnitude, and BETA always less than and usually comparable with norm(B).

BETA (output)

See description of ALPHA.

VSL (input)

If JOBVSL = 'V', VSL will contain the left Schur vectors. Not referenced if JOBVSL = 'N'.

LDVSL (input)

The leading dimension of the matrix VSL. LDVSL \geq 1, and if JOBVSL = 'V', LDVSL \geq N.

VSR (input)

If JOBVSR = 'V', VSR will contain the right Schur vectors. Not referenced if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR \geq 1, and if JOBVSR = 'V', LDVSR \geq N.

RCONDE (output)

If SENSE = 'E' or 'B', RCONDE(1) and RCONDE(2) contain the reciprocal condition numbers for the average of the selected eigenvalues. Not referenced if SENSE = 'N' or 'V'.

RCONDV (output)

If SENSE = 'V' or 'B', RCONDV(1) and RCONDV(2) contain the reciprocal condition number for the selected deflating subspaces. Not referenced if

SENSE = 'N' or 'E'.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK $\geq 2*N$.
If SENSE = 'E', 'V', or 'B', LWORK $\geq \text{MAX}(2*N, 2*SDIM*(N-SDIM))$.

RWORK (workspace)

dimension(8*N) Real workspace.

IWORK (workspace/output)

Not referenced if SENSE = 'N'. On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array WORK. LIWORK $\geq N+2$.

BWORK (workspace)

dimension(N) Not referenced if SORT = 'N'.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

= 1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHA(j) and BETA(j) should be correct for j=INFO+1,...,N. > N: =N+1: other than QZ iteration failed in CHGEQZ

=N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Generalized Schur form no longer satisfy SELCTG=.TRUE. This could also be caused due to scaling. =N+3: reordering failed in CTGSEN.

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NAME

cggev - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors

SYNOPSIS

```
SUBROUTINE CGGEV(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHA, BETA, VL,  
                LDVL, VR, LDVR, WORK, LWORK, RWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VL(LDVL,*),  
VR(LDVR,*), WORK(*)  
INTEGER N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
REAL RWORK(*)
```

```
SUBROUTINE CGGEV_64(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHA, BETA, VL,  
                  LDVL, VR, LDVR, WORK, LWORK, RWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VL(LDVL,*),  
VR(LDVR,*), WORK(*)  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGEV(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHA, BETA,  
               VL, [LDVL], VR, [LDVR], [WORK], [LWORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK  
COMPLEX, DIMENSION(:, :) :: A, B, VL, VR  
INTEGER :: N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
REAL, DIMENSION(:) :: RWORK
```

```
SUBROUTINE GGEV_64(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHA,  
                  BETA, VL, [LDVL], VR, [LDVR], [WORK], [LWORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK  
COMPLEX, DIMENSION(:, :) :: A, B, VL, VR
```

```
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, LWORK, INFO
REAL, DIMENSION(:) :: RWORK
```

C INTERFACE

```
#include <sunperf.h>
void cggev(char jobvl, char jobvr, int n, complex *a, int
           lda, complex *b, int ldb, complex *alpha, complex
           *beta, complex *vl, int ldvl, complex *vr, int
           ldvr, int *info);

void cggev_64(char jobvl, char jobvr, long n, complex *a,
             long lda, complex *b, long ldb, complex *alpha,
             complex *beta, complex *vl, long ldvl, complex
             *vr, long ldvr, long *info);
```

PURPOSE

cggev computes for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors.

A generalized eigenvalue for a pair of matrices (A,B) is a scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β) , as there is a reasonable interpretation for $\beta=0$, and even for both being zero.

The right generalized eigenvector $v(j)$ corresponding to the generalized eigenvalue $\lambda(j)$ of (A,B) satisfies

$$A * v(j) = \lambda(j) * B * v(j).$$

The left generalized eigenvector $u(j)$ corresponding to the generalized eigenvalues $\lambda(j)$ of (A,B) satisfies

$$u(j)**H * A = \lambda(j) * u(j)**H * B$$

where $u(j)**H$ is the conjugate-transpose of $u(j)$.

ARGUMENTS

JOBVL (input)
= 'N': do not compute the left generalized eigenvectors;
= 'V': compute the left generalized eigenvectors.

JOBVR (input)
= 'N': do not compute the right generalized eigenvectors;
= 'V': compute the right generalized eigenvectors.

N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)
On entry, the matrix A in the pair (A,B). On

exit, A has been overwritten.

LDA (input)

The leading dimension of A. $LDA \geq \max(1,N)$.

B (input/output)

On entry, the matrix B in the pair (A,B). On exit, B has been overwritten.

LDB (input)

The leading dimension of B. $LDB \geq \max(1,N)$.

ALPHA (output)

On exit, $ALPHA(j)/BETA(j)$, $j=1,\dots,N$, will be the generalized eigenvalues.

Note: the quotients $ALPHA(j)/BETA(j)$ may easily overflow or underflow, and $BETA(j)$ may even be zero. Thus, the user should avoid naively computing the ratio $alpha/beta$. However, ALPHA will be always less than and usually comparable with $norm(A)$ in magnitude, and BETA always less than and usually comparable with $norm(B)$.

BETA (output)

See description of ALPHA.

VL (input)

If $JOBVL = 'V'$, the left generalized eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. Each eigenvector will be scaled so the largest component will have $abs(real\ part) + abs(imag.\ part) = 1$. Not referenced if $JOBVL = 'N'$.

LDVL (input)

The leading dimension of the matrix VL. $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (input)

If $JOBVR = 'V'$, the right generalized eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. Each eigenvector will be scaled so the largest component will have $abs(real\ part) + abs(imag.\ part) = 1$. Not referenced if $JOBVR = 'N'$.

LDVR (input)

The leading dimension of the matrix VR. $LDVR \geq 1$, and if $JOBVR = 'V'$, $LDVR \geq N$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1,2*N)$. For good performance, LWORK must generally be larger.

If $LWORK = -1$, then a workspace query is assumed;

the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
dimension(8*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
=1,...,N: The QZ iteration failed. No eigenvectors have been calculated, but ALPHA(j) and BETA(j) should be correct for j=INFO+1,...,N. >
N: =N+1: other than QZ iteration failed in SHGEQZ,
=N+2: error return from STGEVC.

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NAME

cggev_x - compute for a pair of N-by-N complex nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors

SYNOPSIS

```
SUBROUTINE CGGEVX(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, B, LDB,
    ALPHA, BETA, VL, LDVL, VR, LDVR, ILO, IHI, LSCALE, RSCALE, ABNRM,
    BBNRM, RCONDE, RCONDV, WORK, LWORK, RWORK, IWORK, BWORK, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VL(LDVL,*),
VR(LDVR,*), WORK(*)
INTEGER N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER IWORK(*)
LOGICAL BWORK(*)
REAL ABNRM, BBNRM
REAL LSCALE(*), RSCALE(*), RCONDE(*), RCONDV(*), RWORK(*)
```

```
SUBROUTINE CGGEVX_64(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, B, LDB,
    ALPHA, BETA, VL, LDVL, VR, LDVR, ILO, IHI, LSCALE, RSCALE, ABNRM,
    BBNRM, RCONDE, RCONDV, WORK, LWORK, RWORK, IWORK, BWORK, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), VL(LDVL,*),
VR(LDVR,*), WORK(*)
INTEGER*8 N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER*8 IWORK(*)
LOGICAL*8 BWORK(*)
REAL ABNRM, BBNRM
REAL LSCALE(*), RSCALE(*), RCONDE(*), RCONDV(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGEVX(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], B, [LDB],
    ALPHA, BETA, VL, [LDVL], VR, [LDVR], ILO, IHI, LSCALE, RSCALE,
    ABNRM, BBNRM, RCONDE, RCONDV, [WORK], [LWORK], [RWORK], [IWORK],
    [BWORK], [INFO])
```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:, :) :: A, B, VL, VR
INTEGER :: N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL, DIMENSION(:) :: BWORK
REAL :: ABNRM, BBNRM
REAL, DIMENSION(:) :: LSCALE, RSCALE, RCONDE, RCONDV, RWORK
SUBROUTINE GGEVX_64(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], B,
    [LDB], ALPHA, BETA, VL, [LDVL], VR, [LDVR], ILO, IHI, LSCALE,
    RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, [WORK], [LWORK], [RWORK],
    [IWORK], [BWORK], [INFO])

```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:, :) :: A, B, VL, VR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8), DIMENSION(:) :: BWORK
REAL :: ABNRM, BBNRM
REAL, DIMENSION(:) :: LSCALE, RSCALE, RCONDE, RCONDV, RWORK

```

C INTERFACE

```
#include <sunperf.h>
```

```

void cggevx(char balanc, char jobvl, char jobvr, char sense,
    int n, complex *a, int lda, complex *b, int ldb,
    complex *alpha, complex *beta, complex *vl, int
    ldvl, complex *vr, int ldvr, int *ilo, int *ihi,
    float *lscale, float *rscale, float *abnrm, float
    *bbnrm, float *rconde, float *rcondv, int *info);

```

```

void cggevx_64(char balanc, char jobvl, char jobvr, char
    sense, long n, complex *a, long lda, complex *b,
    long ldb, complex *alpha, complex *beta, complex
    *vl, long ldvl, complex *vr, long ldvr, long *ilo,
    long *ihi, float *lscale, float *rscale, float
    *abnrm, float *bbnrm, float *rconde, float
    *rcondv, long *info);

```

PURPOSE

cggevx computes for a pair of N-by-N complex nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors.

Optionally, it also computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors (ILO, IHI, LSCALE, RSCALE, ABNRM, and BBNRM), reciprocal condition numbers for the eigenvalues (RCONDE), and reciprocal condition numbers for the right eigenvectors (RCONDV).

A generalized eigenvalue for a pair of matrices (A,B) is a scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β), as there is a reasonable interpretation for $\beta=0$, and even for both being zero.

The right eigenvector $v(j)$ corresponding to the eigenvalue $\lambda(j)$ of (A,B) satisfies

$$A * v(j) = \text{lambda}(j) * B * v(j) .$$

The left eigenvector $u(j)$ corresponding to the eigenvalue $\text{lambda}(j)$ of (A,B) satisfies

$$u(j)**H * A = \text{lambda}(j) * u(j)**H * B.$$

where $u(j)**H$ is the conjugate-transpose of $u(j)$.

ARGUMENTS

BALANC (input)

Specifies the balance option to be performed:
 = 'N': do not diagonally scale or permute;
 = 'P': permute only;
 = 'S': scale only;
 = 'B': both permute and scale. Computed reciprocal condition numbers will be for the matrices after permuting and/or balancing. Permuting does not change condition numbers (in exact arithmetic), but balancing does.

JOBVL (input)

= 'N': do not compute the left generalized eigenvectors;
 = 'V': compute the left generalized eigenvectors.

JOBVR (input)

= 'N': do not compute the right generalized eigenvectors;
 = 'V': compute the right generalized eigenvectors.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': none are computed;
 = 'E': computed for eigenvalues only;
 = 'V': computed for eigenvectors only;
 = 'B': computed for eigenvalues and eigenvectors.

N (input) The order of the matrices A, B, VL, and VR. N >= 0.

A (input/output)

On entry, the matrix A in the pair (A,B). On exit, A has been overwritten. If JOBVL='V' or JOBVR='V' or both, then A contains the first part of the complex Schur form of the "balanced" versions of the input A and B.

LDA (input)

The leading dimension of A. LDA >= max(1,N).

B (input/output)

On entry, the matrix B in the pair (A,B). On exit, B has been overwritten. If JOBVL='V' or JOBVR='V' or both, then B contains the second part of the complex Schur form of the "balanced" versions of the input A and B.

LDB (input)

The leading dimension of B. LDB >= max(1,N).

ALPHA (output)

On exit, ALPHA(j)/BETA(j), $j=1,\dots,N$, will be the generalized eigenvalues.

Note: the quotient ALPHA(j)/BETA(j) may easily over- or underflow, and BETA(j) may even be zero. Thus, the user should avoid naively computing the ratio ALPHA/BETA. However, ALPHA will be always less than and usually comparable with norm(A) in magnitude, and BETA always less than and usually comparable with norm(B).

BETA (output)

See description of ALPHA.

VL (output)

If JOBVL = 'V', the left generalized eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if JOBVL = 'N'.

LDVL (input)

The leading dimension of the matrix VL. LDVL ≥ 1 , and if JOBVL = 'V', LDVL $\geq N$.

VR (input)

If JOBVR = 'V', the right generalized eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if JOBVR = 'N'.

LDVR (input)

The leading dimension of the matrix VR. LDVR ≥ 1 , and if JOBVR = 'V', LDVR $\geq N$.

ILO (output)

ILO is an integer value such that on exit $A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1,\dots,ILO-1$ or $i = IHI+1,\dots,N$. If BALANC = 'N' or 'S', ILO = 1 and IHI = N.

IHI (output)

IHI is an integer value such that on exit $A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1,\dots,ILO-1$ or $i = IHI+1,\dots,N$. If BALANC = 'N' or 'S', ILO = 1 and IHI = N.

LSCALE (output)

Details of the permutations and scaling factors applied to the left side of A and B. If PL(j) is the index of the row interchanged with row j, and DL(j) is the scaling factor applied to row j, then LSCALE(j) = PL(j) for $j = 1,\dots,ILO-1$ = DL(j) for $j = ILO,\dots,IHI$ = PL(j) for $j = IHI+1,\dots,N$. The order in which the interchanges are made is N to IHI+1, then 1 to ILO-1.

RSCALE (output)
 Details of the permutations and scaling factors applied to the right side of A and B. If PR(j) is the index of the column interchanged with column j, and DR(j) is the scaling factor applied to column j, then RSCALE(j) = PR(j) for j = 1,...,ILO-1 = DR(j) for j = ILO,...,IHI = PR(j) for j = IHI+1,...,N The order in which the interchanges are made is N to IHI+1, then 1 to ILO-1.

ABNRM (output)
 The one-norm of the balanced matrix A.

BBNRM (output)
 The one-norm of the balanced matrix B.

RCONDE (output)
 If SENSE = 'E' or 'B', the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. If SENSE = 'V', RCONDE is not referenced.

RCONDV (output)
 If JOB = 'V' or 'B', the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. If the eigenvalues cannot be reordered to compute RCONDV(j), RCONDV(j) is set to 0; this can only occur when the true value would be very small anyway. If SENSE = 'E', RCONDV is not referenced. Not referenced if JOB = 'E'.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq max(1,2*N). If SENSE = 'N' or 'E', LWORK \geq 2*N. If SENSE = 'V' or 'B', LWORK \geq 2*N*N+2*N.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
 dimension(6*N) Real workspace.

IWORK (workspace)
 dimension(N+2) If SENSE = 'E', IWORK is not referenced.

BWORK (workspace)
 dimension(N) If SENSE = 'N', BWORK is not referenced.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value.
 = 1,...,N: The QZ iteration failed. No eigenvec-

tors have been calculated, but ALPHA(j) and BETA(j) should be correct for j=INFO+1,...,N. >
N: =N+1: other than QZ iteration failed in CHGEQZ.
=N+2: error return from CTGEVC.

FURTHER DETAILS

Balancing a matrix pair (A,B) includes, first, permuting rows and columns to isolate eigenvalues, second, applying diagonal similarity transformation to the rows and columns to make the rows and columns as close in norm as possible. The computed reciprocal condition numbers correspond to the balanced matrix. Permuting rows and columns will not change the condition numbers (in exact arithmetic) but diagonal scaling will. For further explanation of balancing, see section 4.11.1.2 of LAPACK Users' Guide.

An approximate error bound on the chordal distance between the i-th computed generalized eigenvalue w and the corresponding exact eigenvalue lambda is
$$\text{hord}(w, \lambda) \leq \text{EPS} * \text{norm}(\text{ABNRM}, \text{BBNRM}) / \text{RCONDE}(I)$$

An approximate error bound for the angle between the i-th computed eigenvector VL(i) or VR(i) is given by
$$\text{PS} * \text{norm}(\text{ABNRM}, \text{BBNRM}) / \text{DIF}(i).$$

For further explanation of the reciprocal condition numbers RCONDE and RCONDV, see section 4.11 of LAPACK User's Guide.

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NAME

cgglm - solve a general Gauss-Markov linear model (GLM) problem

SYNOPSIS

```
SUBROUTINE CGGLM(N, M, P, A, LDA, B, LDB, D, X, Y, WORK, LDWORK,  
INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), D(*), X(*), Y(*), WORK(*)  
INTEGER N, M, P, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE CGGLM_64(N, M, P, A, LDA, B, LDB, D, X, Y, WORK, LDWORK,  
INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), D(*), X(*), Y(*), WORK(*)  
INTEGER*8 N, M, P, LDA, LDB, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GGGLM([N], [M], [P], A, [LDA], B, [LDB], D, X, Y, [WORK],  
[LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: D, X, Y, WORK  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: N, M, P, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE GGGLM_64([N], [M], [P], A, [LDA], B, [LDB], D, X, Y, [WORK],  
[LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: D, X, Y, WORK  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: N, M, P, LDA, LDB, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgglm(int n, int m, int p, complex *a, int lda, com-  
plex *b, int ldb, complex *d, complex *x, complex  
*y, int *info);
```

```
void cgglm_64(long n, long m, long p, complex *a, long lda,
```

```
complex *b, long ldb, complex *d, complex *x, com-
plex *y, long *info);
```

PURPOSE

cgglm solves a general Gauss-Markov linear model (GLM) problem:

$$\underset{x}{\text{minimize}} \quad || y ||_2 \quad \text{subject to} \quad d = A*x + B*y$$

where A is an N-by-M matrix, B is an N-by-P matrix, and d is a given N-vector. It is assumed that $M \leq N \leq M+P$, and

$$\text{rank}(A) = M \quad \text{and} \quad \text{rank}(A \ B) = N.$$

Under these assumptions, the constrained equation is always consistent, and there is a unique solution x and a minimal 2-norm solution y, which is obtained using a generalized QR factorization of A and B.

In particular, if matrix B is square nonsingular, then the problem GLM is equivalent to the following weighted linear least squares problem

$$\underset{x}{\text{minimize}} \quad || \text{inv}(B)*(d-A*x) ||_2$$

where $\text{inv}(B)$ denotes the inverse of B.

ARGUMENTS

N (input) The number of rows of the matrices A and B. $N \geq 0$.

M (input) The number of columns of the matrix A. $0 \leq M \leq N$.

P (input) The number of columns of the matrix B. $P \geq N-M$.

A (input/output)
On entry, the N-by-M matrix A. On exit, A is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)
On entry, the N-by-P matrix B. On exit, B is destroyed.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1,N)$.

D (input/output)

On entry, D is the left hand side of the GLM equation. On exit, D is destroyed.

X (output)

On exit, X and Y are the solutions of the GLM problem.

Y (output)

On exit, X and Y are the solutions of the GLM problem.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq $\max(1, N+M+P)$. For optimum performance, LDWORK \geq $M+\min(N,P)+\max(N,P)*NB$, where NB is an upper bound for the optimal blocksizes for CGEQRF, CGERQF, CUNMQR and CUNMRQ.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

cgghrd - reduce a pair of complex matrices (A,B) to generalized upper Hessenberg form using unitary transformations, where A is a general matrix and B is upper triangular

SYNOPSIS

```
SUBROUTINE CGGHRD(COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB, Q, LDQ,
  Z, LDZ, INFO)
```

```
CHARACTER * 1 COMPQ, COMPZ
COMPLEX A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
INTEGER N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO
```

```
SUBROUTINE CGGHRD_64(COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB, Q,
  LDQ, Z, LDZ, INFO)
```

```
CHARACTER * 1 COMPQ, COMPZ
COMPLEX A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
INTEGER*8 N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO
```

F95 INTERFACE

```
SUBROUTINE GGHRD(COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB], Q,
  [LDQ], Z, [LDZ], [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ, COMPZ
COMPLEX, DIMENSION(:,:) :: A, B, Q, Z
INTEGER :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO
```

```
SUBROUTINE GGHRD_64(COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB],
  Q, [LDQ], Z, [LDZ], [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ, COMPZ
COMPLEX, DIMENSION(:,:) :: A, B, Q, Z
INTEGER(8) :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```

void cgghrd(char compq, char compz, int n, int ilo, int ihi,
            complex *a, int lda, complex *b, int ldb, complex
            *q, int ldq, complex *z, int ldz, int *info);

void cgghrd_64(char compq, char compz, long n, long ilo,
              long ihi, complex *a, long lda, complex *b, long
              ldb, complex *q, long ldq, complex *z, long ldz,
              long *info);

```

PURPOSE

cgghrd reduces a pair of complex matrices (A,B) to generalized upper Hessenberg form using unitary transformations, where A is a general matrix and B is upper triangular: $Q' * A * Z = H$ and $Q' * B * Z = T$, where H is upper Hessenberg, T is upper triangular, and Q and Z are unitary, and ' ' means conjugate transpose.

The unitary matrices Q and Z are determined as products of Givens rotations. They may either be formed explicitly, or they may be postmultiplied into input matrices Q1 and Z1, so that

$$Q1 * A * Z1' = (Q1 * Q) * H * (Z1 * Z)'$$

ARGUMENTS

COMPQ (input)

= 'N': do not compute Q;
 = 'I': Q is initialized to the unit matrix, and the unitary matrix Q is returned; = 'V': Q must contain a unitary matrix Q1 on entry, and the product $Q1 * Q$ is returned.

COMPZ (input)

= 'N': do not compute Q;
 = 'I': Q is initialized to the unit matrix, and the unitary matrix Q is returned; = 'V': Q must contain a unitary matrix Q1 on entry, and the product $Q1 * Q$ is returned.

N (input) The order of the matrices A and B. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to CGGBAL; otherwise they should be set to 1 and N respectively. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)

See description of ILO.

A (input/output)

On entry, the N-by-N general matrix to be reduced. On exit, the upper triangle and the first

subdiagonal of A are overwritten with the upper Hessenberg matrix H, and the rest is set to zero.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)

On entry, the N-by-N upper triangular matrix B. On exit, the upper triangular matrix $T = Q' B Z$. The elements below the diagonal are set to zero.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

Q (input/output)

If COMPQ='N': Q is not referenced. If COMPQ='I': on entry, Q need not be set, and on exit it contains the unitary matrix Q, where Q' is the product of the Givens transformations which are applied to A and B on the left. If COMPQ='V': on entry, Q must contain a unitary matrix Q1, and on exit this is overwritten by Q1*Q.

LDQ (input)

The leading dimension of the array Q. LDQ \geq N if COMPQ='V' or 'I'; LDQ \geq 1 otherwise.

Z (input/output)

If COMPZ='N': Z is not referenced. If COMPZ='I': on entry, Z need not be set, and on exit it contains the unitary matrix Z, which is the product of the Givens transformations which are applied to A and B on the right. If COMPZ='V': on entry, Z must contain a unitary matrix Z1, and on exit this is overwritten by Z1*Z.

LDZ (input)

The leading dimension of the array Z. LDZ \geq N if COMPZ='V' or 'I'; LDZ \geq 1 otherwise.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

This routine reduces A to Hessenberg and B to triangular form by an unblocked reduction, as described in *_Matrix Computations_*, by Golub and van Loan (Johns Hopkins Press).

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NAME

cgglse - solve the linear equality-constrained least squares (LSE) problem

SYNOPSIS

```
SUBROUTINE CGGLSE(M, N, P, A, LDA, B, LDB, C, D, X, WORK, LDWORK,  
INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), C(*), D(*), X(*), WORK(*)  
INTEGER M, N, P, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE CGGLSE_64(M, N, P, A, LDA, B, LDB, C, D, X, WORK, LDWORK,  
INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), C(*), D(*), X(*), WORK(*)  
INTEGER*8 M, N, P, LDA, LDB, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GGLSE([M], [N], [P], A, [LDA], B, [LDB], C, D, X, [WORK],  
[LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: C, D, X, WORK  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: M, N, P, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE GGLSE_64([M], [N], [P], A, [LDA], B, [LDB], C, D, X, [WORK],  
[LDWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: C, D, X, WORK  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: M, N, P, LDA, LDB, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgglse(int m, int n, int p, complex *a, int lda, com-  
plex *b, int ldb, complex *c, complex *d, complex  
*x, int *info);
```

```
void cgglse_64(long m, long n, long p, complex *a, long lda,
```

```
complex *b, long ldb, complex *c, complex *d, com-
plex *x, long *info);
```

PURPOSE

cgglse solves the linear equality-constrained least squares (LSE) problem:

$$\text{minimize } || c - A*x ||_2 \quad \text{subject to } B*x = d$$

where A is an M-by-N matrix, B is a P-by-N matrix, c is a given M-vector, and d is a given P-vector. It is assumed that

$P \leq N \leq M+P$, and

$$\text{rank}(B) = P \text{ and } \text{rank} \begin{pmatrix} A \\ B \end{pmatrix} = N.$$

These conditions ensure that the LSE problem has a unique solution, which is obtained using a GRQ factorization of the matrices B and A.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

P (input) The number of rows of the matrix B. $0 \leq P \leq N \leq M+P$.

A (input/output)
On entry, the M-by-N matrix A. On exit, A is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
On entry, the P-by-N matrix B. On exit, B is destroyed.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, P)$.

C (input/output)
On entry, C contains the right hand side vector for the least squares part of the LSE problem. On exit, the residual sum of squares for the solution is given by the sum of squares of elements N-P+1 to M of vector C.

D (input/output)
On entry, D contains the right hand side vector

for the constrained equation. On exit, D is destroyed.

X (output)

On exit, X is the solution of the LSE problem.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq max(1,M+N+P). For optimum performance LDWORK \geq P+min(M,N)+max(M,N)*NB, where NB is an upper bound for the optimal block sizes for CGEQRF, CGERQF, CUNMQR and CUNMRQ.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

cggqrf - compute a generalized QR factorization of an N-by-M matrix A and an N-by-P matrix B.

SYNOPSIS

```
SUBROUTINE CGGQRF(N, M, P, A, LDA, TAU, B, LDB, TAUB, WORK, LWORK,
                 INFO)
```

```
COMPLEX A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
INTEGER N, M, P, LDA, LDB, LWORK, INFO
```

```
SUBROUTINE CGGQRF_64(N, M, P, A, LDA, TAU, B, LDB, TAUB, WORK,
                    LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
INTEGER*8 N, M, P, LDA, LDB, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GGQRF([N], [M], [P], A, [LDA], TAU, B, [LDB], TAUB, [WORK],
                 [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, TAUB, WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER :: N, M, P, LDA, LDB, LWORK, INFO
```

```
SUBROUTINE GGQRF_64([N], [M], [P], A, [LDA], TAU, B, [LDB], TAUB,
                   [WORK], [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, TAUB, WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER(8) :: N, M, P, LDA, LDB, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cggqrf(int n, int m, int p, complex *a, int lda, complex *tau,
            complex *b, int ldb, complex *taub, int *info);
```


The leading dimension of the array A. LDA \geq max(1,N).

TAUA (output)

The scalar factors of the elementary reflectors which represent the unitary matrix Q (see Further Details).

B (input/output)

On entry, the N-by-P matrix B. On exit, if $N \leq P$, the upper triangle of the subarray B(1:N,P-N+1:P) contains the N-by-N upper triangular matrix T; if $N > P$, the elements on and above the (N-P)-th subdiagonal contain the N-by-P upper trapezoidal matrix T; the remaining elements, with the array TAUB, represent the unitary matrix Z as a product of elementary reflectors (see Further Details).

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

TAUB (output)

The scalar factors of the elementary reflectors which represent the unitary matrix Z (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,N,M,P). For optimum performance LWORK \geq max(N,M,P)*max(NB1,NB2,NB3), where NB1 is the optimal blocksize for the QR factorization of an N-by-M matrix, NB2 is the optimal blocksize for the RQ factorization of an N-by-P matrix, and NB3 is the optimal blocksize for a call of CUNMQR.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(n,m).$$

Each H(i) has the form

$$H(i) = I - \text{taua} * v * v'$$

where taua is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:n)$ is stored on exit in $A(i+1:n,i)$, and taua in $\text{TAUA}(i)$.

To form Q explicitly, use LAPACK subroutine CUNGQR.

To use Q to update another matrix, use LAPACK subroutine CUNMQR.

The matrix Z is represented as a product of elementary reflectors

$$Z = H(1) H(2) \dots H(k), \text{ where } k = \min(n,p).$$

Each $H(i)$ has the form

$$H(i) = I - \text{taub} * v * v'$$

where taub is a complex scalar, and v is a complex vector with $v(p-k+i+1:p) = 0$ and $v(p-k+i) = 1$; $v(1:p-k+i-1)$ is stored on exit in $B(n-k+i,1:p-k+i-1)$, and taub in $\text{TAUB}(i)$.

To form Z explicitly, use LAPACK subroutine CUNGRQ.

To use Z to update another matrix, use LAPACK subroutine CUNMRQ.

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NAME

cggrqf - compute a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B

SYNOPSIS

```
SUBROUTINE CGGRQF(M, P, N, A, LDA, TAU, B, LDB, TAUB, WORK, LWORK,
                 INFO)
```

```
COMPLEX A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
INTEGER M, P, N, LDA, LDB, LWORK, INFO
```

```
SUBROUTINE CGGRQF_64(M, P, N, A, LDA, TAU, B, LDB, TAUB, WORK,
                    LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
INTEGER*8 M, P, N, LDA, LDB, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GGRQF([M], [P], [N], A, [LDA], TAU, B, [LDB], TAUB, [WORK],
                 [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, TAUB, WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER :: M, P, N, LDA, LDB, LWORK, INFO
```

```
SUBROUTINE GGRQF_64([M], [P], [N], A, [LDA], TAU, B, [LDB], TAUB,
                   [WORK], [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, TAUB, WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER(8) :: M, P, N, LDA, LDB, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cggrqf(int m, int p, int n, complex *a, int lda, complex *tau,
            complex *b, int ldb, complex *taub, int *info);
```


LDA (input)
 The leading dimension of the array A. LDA \geq max(1,M).

TAUA (output)
 The scalar factors of the elementary reflectors which represent the unitary matrix Q (see Further Details).

B (input/output)
 On entry, the P-by-N matrix B. On exit, the elements on and above the diagonal of the array contain the min(P,N)-by-N upper trapezoidal matrix T (T is upper triangular if P \geq N); the elements below the diagonal, with the array TAUB, represent the unitary matrix Z as a product of elementary reflectors (see Further Details).

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,P).

TAUB (output)
 The scalar factors of the elementary reflectors which represent the unitary matrix Z (see Further Details).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq max(1,N,M,P). For optimum performance LWORK \geq max(N,M,P)*max(NB1,NB2,NB3), where NB1 is the optimal blocksize for the RQ factorization of an M-by-N matrix, NB2 is the optimal blocksize for the QR factorization of a P-by-N matrix, and NB3 is the optimal blocksize for a call of CUNMRQ.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO=-i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m,n).$$

Each H(i) has the form

$$H(i) = I - \text{tau} \cdot v \cdot v'$$

where taua is a complex scalar, and v is a complex vector with $v(n-k+i+1:n) = 0$ and $v(n-k+i) = 1$; $v(1:n-k+i-1)$ is stored on exit in $A(m-k+i,1:n-k+i-1)$, and taua in $TAUA(i)$. To form Q explicitly, use LAPACK subroutine CUNGRQ. To use Q to update another matrix, use LAPACK subroutine CUNMRQ.

The matrix Z is represented as a product of elementary reflectors

$$Z = H(1) H(2) \dots H(k), \text{ where } k = \min(p,n).$$

Each $H(i)$ has the form

$$H(i) = I - \text{taub} * v * v'$$

where taub is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:p)$ is stored on exit in $B(i+1:p,i)$, and taub in $TAUB(i)$. To form Z explicitly, use LAPACK subroutine CUNGQR. To use Z to update another matrix, use LAPACK subroutine CUNMQR.

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NAME

cggsvd - compute the generalized singular value decomposition (GSVD) of an M-by-N complex matrix A and P-by-N complex matrix B

SYNOPSIS

```
SUBROUTINE CGGSVD(JOBU, JOBV, JOBQ, M, N, P, K, L, A, LDA, B, LDB,  
    ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, WORK2, IWORK3, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ  
COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*), Q(LDQ,*),  
WORK(*)  
INTEGER M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER IWORK3(*)  
REAL ALPHA(*), BETA(*), WORK2(*)
```

```
SUBROUTINE CGGSVD_64(JOBU, JOBV, JOBQ, M, N, P, K, L, A, LDA, B, LDB,  
    ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, WORK2, IWORK3, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ  
COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*), Q(LDQ,*),  
WORK(*)  
INTEGER*8 M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER*8 IWORK3(*)  
REAL ALPHA(*), BETA(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GGSVD(JOBU, JOBV, JOBQ, [M], [N], [P], K, L, A, [LDA], B,  
    [LDB], ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK], [WORK2],  
    IWORK3, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B, U, V, Q  
INTEGER :: M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER, DIMENSION(:) :: IWORK3  
REAL, DIMENSION(:) :: ALPHA, BETA, WORK2
```

```
SUBROUTINE GGSVD_64(JOBU, JOBV, JOBQ, [M], [N], [P], K, L, A, [LDA],  
    B, [LDB], ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK],
```

```
[WORK2], IWORK3, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B, U, V, Q  
INTEGER(8) :: M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER(8), DIMENSION(:) :: IWORK3  
REAL, DIMENSION(:) :: ALPHA, BETA, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cggsvd(char jobu, char jobv, char jobq, int m, int n,  
            int p, int *k, int *l, complex *a, int lda, com-  
            plex *b, int ldb, float *alpha, float *beta, com-  
            plex *u, int ldu, complex *v, int ldv, complex *q,  
            int ldq, int *iwork3, int *info);
```

```
void cggsvd_64(char jobu, char jobv, char jobq, long m, long  
               n, long p, long *k, long *l, complex *a, long lda,  
               complex *b, long ldb, float *alpha, float *beta,  
               complex *u, long ldu, complex *v, long ldv, com-  
               plex *q, long ldq, long *iwork3, long *info);
```

PURPOSE

cggsvd computes the generalized singular value decomposition (GSVD) of an M-by-N complex matrix A and P-by-N complex matrix B:

$$U'A*Q = D1*(0 R), \quad V'*B*Q = D2*(0 R)$$

where U, V and Q are unitary matrices, and Z' means the conjugate transpose of Z. Let K+L = the effective numerical rank of the matrix (A',B')', then R is a (K+L)-by-(K+L) non-singular upper triangular matrix, D1 and D2 are M-by-(K+L) and P-by-(K+L) "diagonal" matrices and of the following structures, respectively:

If M-K-L >= 0,

$$D1 = \begin{array}{cc} & K & L \\ & K & (I & 0) \\ & & L & (0 & C) \\ M-K-L & & & (0 & 0) \end{array}$$

$$D2 = \begin{array}{cc} & K & L \\ & L & (0 & S) \\ P-L & & & (0 & 0) \end{array}$$

$$(0 R) = \begin{array}{ccc} & N-K-L & K & L \\ & K & (0 & R11 & R12) \\ & & L & (0 & 0 & R22) \end{array}$$

where

```
C = diag( ALPHA(K+1), ... , ALPHA(K+L) ),  
S = diag( BETA(K+1), ... , BETA(K+L) ),  
C**2 + S**2 = I.
```

R is stored in A(1:K+L,N-K-L+1:N) on exit.
 If M-K-L < 0,

$$D1 = \begin{matrix} & & K & M-K & K+L-M \\ & K & (& I & 0 & 0 &) \\ M-K & (& 0 & C & 0 &) \end{matrix}$$

$$D2 = \begin{matrix} & & K & M-K & K+L-M \\ M-K & (& 0 & S & 0 &) \\ K+L-M & (& 0 & 0 & I &) \\ P-L & (& 0 & 0 & 0 &) \end{matrix}$$

$$(\begin{matrix} 0 & R \end{matrix}) = \begin{matrix} & & N-K-L & K & M-K & K+L-M \\ & K & (& 0 & R11 & R12 & R13 &) \\ & M-K & (& 0 & 0 & R22 & R23 &) \\ & K+L-M & (& 0 & 0 & 0 & R33 &) \end{matrix}$$

where

$$C = \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(M)),$$

$$S = \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(M)),$$

$$C^{**2} + S^{**2} = I.$$

(R11 R12 R13) is stored in A(1:M, N-K-L+1:N), and R33 is stored
 (0 R22 R23)
 in B(M-K+1:L,N+M-K-L+1:N) on exit.

The routine computes C, S, R, and optionally the unitary transformation matrices U, V and Q.

In particular, if B is an N-by-N nonsingular matrix, then the GSVD of A and B implicitly gives the SVD of A*inv(B):

$$A * \text{inv}(B) = U * (D1 * \text{inv}(D2)) * V'$$

If (A',B')' has orthonormal columns, then the GSVD of A and B is also equal to the CS decomposition of A and B. Furthermore, the GSVD can be used to derive the solution of the eigenvalue problem:

$$A' * A x = \text{lambda} * B' * B x.$$

In some literature, the GSVD of A and B is presented in the form

$$U' * A * X = (\begin{matrix} 0 & D1 \end{matrix}), \quad V' * B * X = (\begin{matrix} 0 & D2 \end{matrix})$$

where U and V are orthogonal and X is nonsingular, and D1 and D2 are ``diagonal''. The former GSVD form can be converted to the latter form by taking the nonsingular matrix X as

$$X = Q * \begin{pmatrix} I & 0 \\ 0 & \text{inv}(R) \end{pmatrix}$$

ARGUMENTS

JOBV (input)
 = 'U': Unitary matrix U is computed;
 = 'N': U is not computed.

JOBV (input)
 = 'V': Unitary matrix V is computed;
 = 'N': V is not computed.

JOBQ (input)
 = 'Q': Unitary matrix Q is computed;
 = 'N': Q is not computed.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

K (output)
 On exit, K and L specify the dimension of the sub-blocks described in Purpose. $K + L =$ effective numerical rank of (A',B')'.

L (output)
 On exit, K and L specify the dimension of the sub-blocks described in Purpose. $K + L =$ effective numerical rank of (A',B')'.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A contains the triangular matrix R, or part of R. See Purpose for details.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
 On entry, the P-by-N matrix B. On exit, B contains part of the triangular matrix R if $M - K - L < 0$. See Purpose for details.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, P)$.

ALPHA (output)
 On exit, ALPHA and BETA contain the generalized singular value pairs of A and B; $ALPHA(1:K) = 1$, $ALPHA(K+1:K+L) = C$, $BETA(1:K) = 0$, and if $M - K - L \geq 0$, $ALPHA(K+1:K+L) = C$, $BETA(K+1:K+L) = S$, or if $M - K - L < 0$, $ALPHA(K+1:M) = C$, $ALPHA(M+1:K+L) = 0$, $BETA(K+1:M) = S$, $BETA(M+1:K+L) = 1$ and $ALPHA(K+L+1:N) = 0$, $BETA(K+L+1:N) = 0$.

BETA (output)
 See description of ALPHA.

U (output)
 If JOBU = 'U', U contains the M-by-M unitary matrix U. If JOBU = 'N', U is not referenced.

LDU (input)
 The leading dimension of the array U. $LDU \geq$

max(1,M) if JOBU = 'U'; LDU >= 1 otherwise.

V (output)

If JOBV = 'V', V contains the P-by-P unitary matrix V. If JOBV = 'N', V is not referenced.

LDV (input)

The leading dimension of the array V. LDV >= max(1,P) if JOBV = 'V'; LDV >= 1 otherwise.

Q (output)

If JOBQ = 'Q', Q contains the N-by-N unitary matrix Q. If JOBQ = 'N', Q is not referenced.

LDQ (input)

The leading dimension of the array Q. LDQ >= max(1,N) if JOBQ = 'Q'; LDQ >= 1 otherwise.

WORK (workspace)

dimension(MAX(3*N,M,P)+N)

WORK2 (workspace)

dimension(2*N)

IWORK3 (output)

dimension(N) On exit, IWORK3 stores the sorting information. More precisely, the following loop will sort ALPHA for I = K+1, min(M,K+L) swap ALPHA(I) and ALPHA(IWORK3(I)) endfor such that ALPHA(1) >= ALPHA(2) >= ... >= ALPHA(N).

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: if INFO = 1, the Jacobi-type procedure failed to converge. For further details, see subroutine CTGSJA.

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NAME

cggsvp - compute unitary matrices U, V and Q such that $N-K-L$ $K \ L \ U^*A^*Q = K \ (\ 0 \ A12 \ A13 \)$ if $M-K-L \geq 0$

SYNOPSIS

```
SUBROUTINE CGGSVP(JOBU, JOBV, JOBQ, M, P, N, A, LDA, B, LDB, TOLA,
  TOLB, K, L, U, LDU, V, LDV, Q, LDQ, IWORK, RWORK, TAU, WORK,
  INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*), Q(LDQ,*),
TAU(*), WORK(*)
INTEGER M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER IWORK(*)
REAL TOLA, TOLB
REAL RWORK(*)
```

```
SUBROUTINE CGGSVP_64(JOBU, JOBV, JOBQ, M, P, N, A, LDA, B, LDB, TOLA,
  TOLB, K, L, U, LDU, V, LDV, Q, LDQ, IWORK, RWORK, TAU, WORK,
  INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*), Q(LDQ,*),
TAU(*), WORK(*)
INTEGER*8 M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER*8 IWORK(*)
REAL TOLA, TOLB
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGSVP(JOBU, JOBV, JOBQ, [M], [P], [N], A, [LDA], B, [LDB],
  TOLA, TOLB, K, L, U, [LDU], V, [LDV], Q, [LDQ], [IWORK], [RWORK],
  [TAU], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A, B, U, V, Q
INTEGER :: M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
```

```

INTEGER, DIMENSION(:) :: IWORK
REAL :: TOLA, TOLB
REAL, DIMENSION(:) :: RWORK

SUBROUTINE GGSVP_64(JOBU, JOBV, JOBQ, [M], [P], [N], A, [LDA], B,
  [LDB], TOLA, TOLB, K, L, U, [LDU], V, [LDV], Q, [LDQ], [IWORK],
  [RWORK], [TAU], [WORK], [INFO])

CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:,:) :: A, B, U, V, Q
INTEGER(8) :: M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL :: TOLA, TOLB
REAL, DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>

void cggsvp(char jobu, char jobv, char jobq, int m, int p,
  int n, complex *a, int lda, complex *b, int ldb,
  float tola, float tolb, int *k, int *l, complex
  *u, int ldu, complex *v, int ldv, complex *q, int
  ldq, int *info);

void cggsvp_64(char jobu, char jobv, char jobq, long m, long
  p, long n, complex *a, long lda, complex *b, long
  ldb, float tola, float tolb, long *k, long *l,
  complex *u, long ldu, complex *v, long ldv, com-
  plex *q, long ldq, long *info);

```

PURPOSE

cggsvp computes unitary matrices U, V and Q such that

$$\begin{array}{r}
 \begin{array}{ccc}
 & L & (\begin{array}{ccc} 0 & 0 & A23 \end{array}) \\
 M-K-L & (\begin{array}{ccc} 0 & 0 & 0 \end{array})
 \end{array} \\
 \\
 = \begin{array}{ccc}
 & N-K-L & K & L \\
 K & (\begin{array}{ccc} 0 & A12 & A13 \end{array}) & \text{if } M-K-L < 0; \\
 M-K & (\begin{array}{ccc} 0 & 0 & A23 \end{array})
 \end{array} \\
 \\
 V' * B * Q = \begin{array}{ccc}
 & N-K-L & K & L \\
 L & (\begin{array}{ccc} 0 & 0 & B13 \end{array}) \\
 P-L & (\begin{array}{ccc} 0 & 0 & 0 \end{array})
 \end{array}
 \end{array}$$

where the K-by-K matrix A12 and L-by-L matrix B13 are non-singular upper triangular; A23 is L-by-L upper triangular if M-K-L >= 0, otherwise A23 is (M-K)-by-L upper trapezoidal. K+L = the effective numerical rank of the (M+P)-by-N matrix (A',B')'. Z' denotes the conjugate transpose of Z.

This decomposition is the preprocessing step for computing the Generalized Singular Value Decomposition (GSVD), see subroutine CCGSVD.

ARGUMENTS

JOBV (input)
 = 'U': Unitary matrix U is computed;
 = 'N': U is not computed.

JOBQ (input)
 = 'Q': Unitary matrix Q is computed;
 = 'N': Q is not computed.

M (input) The number of rows of the matrix A. $M \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A contains the triangular (or trapezoidal) matrix described in the Purpose section.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1,M)$.

B (input/output)
 On entry, the P-by-N matrix B. On exit, B contains the triangular matrix described in the Purpose section.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1,P)$.

TOLA (input)
 TOLA and TOLB are the thresholds to determine the effective numerical rank of matrix B and a sub-block of A. Generally, they are set to $TOLA = \max(M,N) * \text{norm}(A) * \text{MACHEPS}$, $TOLB = \max(P,N) * \text{norm}(B) * \text{MACHEPS}$. The size of TOLA and TOLB may affect the size of backward errors of the decomposition.

TOLB (input)
 See description of TOLA.

K (output)
 On exit, K and L specify the dimension of the sub-blocks described in Purpose section. $K + L = \text{effective numerical rank of } (A',B)'$.

L (output)
 See the description of K.

U (input) If JOBV = 'U', U contains the unitary matrix U. If JOBV = 'N', U is not referenced.

LDU (input)
 The leading dimension of the array U. $LDU \geq \max(1,M)$ if JOBV = 'U'; $LDU \geq 1$ otherwise.

V (input) If JOBV = 'V', V contains the unitary matrix V.
If JOBV = 'N', V is not referenced.

LDV (input)
The leading dimension of the array V. LDV \geq
 $\max(1,P)$ if JOBV = 'V'; LDV \geq 1 otherwise.

Q (input) If JOBQ = 'Q', Q contains the unitary matrix Q.
If JOBQ = 'N', Q is not referenced.

LDQ (input)
The leading dimension of the array Q. LDQ \geq
 $\max(1,N)$ if JOBQ = 'Q'; LDQ \geq 1 otherwise.

IWORK (workspace)
dimension(N)

RWORK (workspace)
dimension(2*N)

TAU (workspace)
dimension(N)

WORK (workspace)
dimension($\max(3*N,M,P)$)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The subroutine uses LAPACK subroutine CGEQPF for the QR factorization with column pivoting to detect the effective numerical rank of the a matrix. It may be replaced by a better rank determination strategy.

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NAME

cgssco - General sparse solver condition number estimate.

SYNOPSIS

```
SUBROUTINE CGSSCO ( COND, HANDLE, IER )
```

```
INTEGER          IER
REAL             COND
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSCO - Condition number estimate.

PARAMETERS

COND - REAL

On exit, an estimate of the condition number of the factored matrix. Must be called after the numerical factorization subroutine, [CGSSFA\(\)](#).

HANDLE(150) - DOUBLE PRECISION array

On entry, [HANDLE\(*\)](#) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-700 : Invalid calling sequence - need to call CGSSFA first.

-710 : Condition number estimate not available (not implemented for this HANDLE's matrix type).

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NAME

cgssda - Deallocate working storage for the general sparse solver.

SYNOPSIS

```
SUBROUTINE CGSSDA ( HANDLE, IER )  
  
INTEGER          IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSDA - Deallocate dynamically allocated working storage.

PARAMETERS

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

none

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NAME

cgssfa - General sparse solver numeric factorization.

SYNOPSIS

```
SUBROUTINE CGSSFA ( NEQNS, COLSTR, ROWIND, VALUES, HANDLE, IER )
```

```
INTEGER          NEQNS, COLSTR(*), ROWIND(*), IER
```

```
COMPLEX          VALUES(*)
```

```
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSFA - Numeric factorization of a sparse matrix.

PARAMETERS

NEQNS - INTEGER

On entry, **NEQNS** specifies the number of equations in coefficient matrix. Unchanged on exit.

COLSTR(*) - INTEGER array

On entry, **COLSTR**(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure. Unchanged on exit.

ROWIND(*) - INTEGER array

On entry, **ROWIND**(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

VALUES(*) - COMPLEX array

On entry, **VALUES**(*) is an array of size COLSTR(NEQNS+1)-1, containing the numeric values of the sparse matrix to be factored. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, **HANDLE**(*) is an array containing

information needed by the solver, and must be passed unchanged to each sparse solver subroutine.
Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 300 : Invalid calling sequence - need to call CGSSOR first.
- 301 : Failure to dynamically allocate memory.
- 666 : Internal error.

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NAME

cgssfs - General sparse solver one call interface.

SYNOPSIS

```
SUBROUTINE CGSSFS ( MTXTYP, PIVOT , NEQNS, COLSTR, ROWIND,
                   VALUES, NRHS , RHS , LDRHS , ORDMTHD,
                   OUTUNT, MSGLVL, HANDLE, IER )
```

```
CHARACTER*2      MTXTYP
CHARACTER*1      PIVOT
INTEGER          NEQNS, COLSTR(*), ROWIND(*), NRHS, LDRHS,
                OUTUNT, MSGLVL, IER
CHARACTER*3      ORDMTHD
COMPLEX          VALUES(*), RHS(*)
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSFS - General sparse solver one call interface.

PARAMETERS

MTXTYP - CHARACTER*2
On entry, MTXTYP specifies the coefficient matrix type. Specifically, the valid options are:

- 'sp' or 'SP' - symmetric structure, Hermitian positive definite values
- 'ss' or 'SS' - symmetric structure, symmetric values
- 'su' or 'SU' - symmetric structure, unsymmetric values
- 'uu' or 'UU' - unsymmetric structure, unsymmetric values

Unchanged on exit.

PIVOT - CHARACTER*1
On entry, pivot specifies whether or not pivoting is used in the course of the numeric factorization. The valid options are:

'n' or 'N' - no pivoting is used
(Pivoting is not supported for this release).

Unchanged on exit.

NEQNS - INTEGER
On entry, NEQNS specifies the number of equations in the coefficient matrix. NEQNS must be at least one.
Unchanged on exit.

COLSTR(*) - INTEGER array
On entry, COLSTR(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure.
Unchanged on exit.

ROWIND(*) - INTEGER array
On entry, ROWIND(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

VALUES(*) - COMPLEX array
On entry, VALUES(*) is an array of size COLSTR(NEQNS+1)-1, containing the non-zero numeric values of the sparse matrix to be factored.
Unchanged on exit.

NRHS - INTEGER
On entry, NRHS specifies the number of right hand sides to solve for. Unchanged on exit.

RHS(*) - COMPLEX array
On entry, RHS(LDRHS,NRHS) contains the NRHS right hand sides. On exit, it contains the solutions.

LDRHS - INTEGER
On entry, LDRHS specifies the leading dimension of the RHS array. Unchanged on exit.

ORDMTHD - CHARACTER*3
On entry, ORDMTHD specifies the fill-reducing ordering to be used by the sparse solver. Specifically, the valid options are:

'nat' or 'NAT' - natural ordering (no ordering)
'mmd' or 'MMD' - multiple minimum degree
'gnd' or 'GND' - general nested dissection
'uso' or 'USO' - user specified ordering (see CGSSUO)

Unchanged on exit.

OUTUNT - INTEGER
Output unit. Unchanged on exit.

MSGLVL - INTEGER
Message level.

0 - no output from solver.
(No messages supported for this release.)

Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array of containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine.
Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 101 : Failure to dynamically allocate memory.
- 102 : Invalid matrix type.
- 103 : Invalid pivot option.
- 104 : Number of nonzeros is less than NEQNS.
- 105 : NEQNS < 1
- 106 : Invalid matrix structure.
- 201 : Failure to dynamically allocate memory.
- 301 : Failure to dynamically allocate memory.
- 401 : Failure to dynamically allocate memory.
- 402 : NRHS < 1
- 403 : NEQNS > LDRHS
- 666 : Internal error.

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NAME

cgssin - Initialize the general sparse solver.

SYNOPSIS

```
SUBROUTINE CGSSIN ( MTXTYP, PIVOT, NEQNS, COLSTR, ROWIND, OUTUNT,  
                  MSGLVL, HANDLE, IER )
```

```
CHARACTER*2      MTXTYP  
CHARACTER*1      PIVOT  
INTEGER          NEQNS, COLSTR(*), ROWIND(*), OUTUNT, MSGLVL, IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSIN - Initialize the sparse solver and input the matrix structure.

PARAMETERS

MTXTYP - CHARACTER*2
On entry, MTXTYP specifies the coefficient matrix type. Specifically, the valid options are:

- 'sp' or 'SP' - symmetric structure, Hermitian positive definite values
- 'ss' or 'SS' - symmetric structure, symmetric values
- 'su' or 'SU' - symmetric structure, unsymmetric values
- 'uu' or 'UU' - unsymmetric structure, unsymmetric values

Unchanged on exit.

PIVOT - CHARACTER*1
On entry, PIVOT specifies whether or not pivoting is used in the course of the numeric factorization. The valid options are:

- 'n' or 'N' - no pivoting is used
(Pivoting is not supported for this release).

Unchanged on exit.

NEQNS - INTEGER
On entry, NEQNS specifies the number of equations in the coefficient matrix. NEQNS must be at least one. Unchanged on exit.

COLSTR(*) - INTEGER array
On entry, COLSTR(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure. Unchanged on exit.

ROWIND(*) - INTEGER array
On entry, ROWIND(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, HANDLE(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

OUTUNT - INTEGER
Output unit. Unchanged on exit.

MSGLVL - INTEGER
Message level.

0 - no output from solver.
(No messages supported for this release.)

Unchanged on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-101 : Failure to dynamically allocate memory.
-102 : Invalid matrix type.
-103 : Invalid pivot option.
-104 : Number of nonzeros less than NEQNS.
-105 : NEQNS < 1
-106 : Invalid matrix structure.

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NAME

cgssor - General sparse solver ordering and symbolic factorization.

SYNOPSIS

```
SUBROUTINE CGSSOR ( ORDMTHD, HANDLE, IER )
```

```
CHARACTER*3      ORDMTHD
INTEGER          IER
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSOR - Orders and symbolically factors a sparse matrix.

PARAMETERS

ORDMTHD - CHARACTER*3

On entry, ORDMTHD specifies the fill-reducing ordering to be used by the sparse solver. Specifically, the valid options are:

'nat' or 'NAT' - natural ordering (no ordering)
'mmd' or 'MMD' - multiple minimum degree
'gnd' or 'GND' - general nested dissection
'uso' or 'USO' - user specified ordering (see CGSSUO)

Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero

integer. Error numbers set by this subroutine:

- 200 : Invalid calling sequence - need to call CGSSIN first.
- 201 : Failure to dynamically allocate memory.
- 666 : Internal error.

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NAME

cgssps - Print general sparse solver statics.

SYNOPSIS

```
SUBROUTINE CGSSPS ( HANDLE, IER )
```

```
INTEGER          IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSPS - Print solver statistics.

PARAMETERS

HANDLE(150) - DOUBLE PRECISION array

On entry, [HANDLE\(*\)](#) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-800 : Invalid calling sequence - need to call CGSSSL first.
-899 : Printed solver statistics not supported this release.

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NAME

cgssrp - Return permutation used by the general sparse solver.

SYNOPSIS

```
SUBROUTINE CGSSRP ( PERM, HANDLE, IER )
```

```
INTEGER          PERM(*), IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSRP - Returns the permutation used by the solver for the fill-reducing ordering.

PARAMETERS

PERM(NEQNS) - INTEGER array

Undefined on entry. PERM(NEQNS) is the permutation array used by the sparse solver for the fill-reducing ordering. Modified on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-600 : Invalid calling sequence - need to call CGSSOR first.

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NAME

cgsssl - Solve routine for the general sparse solver.

SYNOPSIS

```
SUBROUTINE CGSSSL ( NRHS, RHS, LDRHS, HANDLE, IER )
```

```
INTEGER          NRHS, LDRHS, IER
```

```
COMPLEX          RHS(LDRHS,NRHS)
```

```
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSSL - Triangular solve of a factored sparse matrix.

PARAMETERS

NRHS - INTEGER

On entry, NRHS specifies the number of right hand sides to solve for. Unchanged on exit.

RHS(LDRHS,*) - COMPLEX array

On entry, RHS(LDRHS,NRHS) contains the NRHS right hand sides. On exit, it contains the solutions.

LDRHS - INTEGER

On entry, LDRHS specifies the leading dimension of the RHS array. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-400 : Invalid calling sequence - need to call CGSSFA first.
-401 : Failure to dynamically allocate memory.
-402 : NRHS < 1
-403 : NEQNS > LDRHS

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NAME

cgssuo - User supplied permutation for ordering used in the general sparse solver.

SYNOPSIS

```
SUBROUTINE CGSSUO ( PERM, HANDLE, IER )
```

```
INTEGER          PERM(*), IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

CGSSUO - User supplied permutation for ordering. Must be called after **CGSSIN()** (sparse solver initialization) and before **CGSSOR()** (sparse solver ordering).

PARAMETERS

PERM(NEQNS) - INTEGER array
On entry, PERM(NEQNS) is a permutation array supplied by the user for the fill-reducing ordering. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, **HANDLE(*)** is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-500 : Invalid calling sequence - need to call CGSSIN first.

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NAME

cgtcon - estimate the reciprocal of the condition number of a complex tridiagonal matrix A using the LU factorization as computed by CGTTRF

SYNOPSIS

```
SUBROUTINE CGTCON(NORM, N, LOW, DIAG, UP1, UP2, IPIVOT, ANORM, RCOND,
                 WORK, INFO)
```

```
CHARACTER * 1 NORM
COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*), WORK(*)
INTEGER N, INFO
INTEGER IPIVOT(*)
REAL ANORM, RCOND
```

```
SUBROUTINE CGTCON_64(NORM, N, LOW, DIAG, UP1, UP2, IPIVOT, ANORM,
                    RCOND, WORK, INFO)
```

```
CHARACTER * 1 NORM
COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*), WORK(*)
INTEGER*8 N, INFO
INTEGER*8 IPIVOT(*)
REAL ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE GTCON(NORM, [N], LOW, DIAG, UP1, UP2, IPIVOT, ANORM,
                RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: NORM
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP1, UP2, WORK
INTEGER :: N, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL :: ANORM, RCOND
```

```
SUBROUTINE GTCON_64(NORM, [N], LOW, DIAG, UP1, UP2, IPIVOT, ANORM,
                   RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: NORM
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP1, UP2, WORK
INTEGER(8) :: N, INFO
```

```
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>
void cgtcon(char norm, int n, complex *low, complex *diag,
            complex *up1, complex *up2, int *ipivot, float
            anorm, float *rcond, int *info);

void cgtcon_64(char norm, long n, complex *low, complex
              *diag, complex *up1, complex *up2, long *ipivot,
              float anorm, float *rcond, long *info);
```

PURPOSE

cgtcon estimates the reciprocal of the condition number of a complex tridiagonal matrix A using the LU factorization as computed by CGTTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

LOW (input)

The (n-1) multipliers that define the matrix L from the LU factorization of A as computed by CGTTRF.

DIAG (input)

The n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UP1 (input)

The (n-1) elements of the first superdiagonal of U.

UP2 (input)

The (n-2) elements of the second superdiagonal of U.

IPIVOT (input)

The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(ANORM * AINVNM)$, where AINVNM is an estimate of the 1-norm of $inv(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cgthr - Gathers specified elements from y into x.

SYNOPSIS

```
SUBROUTINE CGTHR(NZ, Y, X, INDX)

COMPLEX Y(*), X(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE CGTHR_64(NZ, Y, X, INDX)

COMPLEX Y(*), X(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE GTHR([NZ], Y, X, INDX)

COMPLEX, DIMENSION(:) :: Y, X
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE GTHR_64([NZ], Y, X, INDX)

COMPLEX, DIMENSION(:) :: Y, X
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

CGTHR - Gathers the specified elements from a vector y in full storage form into a vector x in compressed form. Only the elements of y whose indices are listed in indx are referenced.

```
do i = 1, n
  x(i) = y(indx(i))
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

Y (input)

Vector in full storage form. Unchanged on exit.

X (output)

Vector in compressed form. Contains elements of y
whose indices are listed in indx on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

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NAME

cgthrz - Gather and zero.

SYNOPSIS

```
SUBROUTINE CGTHRZ(NZ, Y, X, INDX)

COMPLEX Y(*), X(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE CGTHRZ_64(NZ, Y, X, INDX)

COMPLEX Y(*), X(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE GTHRZ([NZ], Y, X, INDX)

COMPLEX, DIMENSION(:) :: Y, X
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE GTHRZ_64([NZ], Y, X, INDX)

COMPLEX, DIMENSION(:) :: Y, X
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

CGTHRZ - Gathers the specified elements from a vector y in full storage form into a vector x in compressed form. The gathered elements of y are set to zero. Only the elements of y whose indices are listed in indx are referenced.

```
do i = 1, n
  x(i) = y(indx(i))
  y(indx(i)) = 0
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

Y (input/output)

Vector in full storage form. Gathered elements are
set to zero.

X (output)

Vector in compressed form. Contains elements of y
whose indices are listed in indx on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

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NAME

cgtrfs - improve the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CGTRFS(TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF, UPF1,  
    UPF2, IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*), UPF1(*),  
UPF2(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
INTEGER IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CGTRFS_64(TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF,  
    UPF1, UPF2, IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2,  
    INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*), UPF1(*),  
UPF2(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GTRFS([TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF, DIAGF,  
    UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],  
    [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,  
UPF2, WORK  
COMPLEX, DIMENSION(:, :) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```

SUBROUTINE GTRFS_64([TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
    DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
    [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: TRANSA
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, WORK
COMPLEX, DIMENSION(:,:) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void cgtrfs(char transa, int n, int nrhs, complex *low, com-
    plex *diag, complex *up, complex *lowf, complex
    *diagf, complex *upf1, complex *upf2, int *ipivot,
    complex *b, int ldb, complex *x, int ldx, float
    *ferr, float *berr, int *info);

```

```

void cgtrfs_64(char transa, long n, long nrhs, complex *low,
    complex *diag, complex *up, complex *lowf, complex
    *diagf, complex *upf1, complex *upf2, long
    *ipivot, complex *b, long ldb, complex *x, long
    ldx, float *ferr, float *berr, long *info);

```

PURPOSE

cgtrfs improves the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:

= 'N': $A * X = B$ (No transpose)

= 'T': $A^{*T} * X = B$ (Transpose)

= 'C': $A^{*H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input)

The (n-1) subdiagonal elements of A.

DIAG (input)

The diagonal elements of A.

UP (input)
The (n-1) superdiagonal elements of A.

LOWF (input)
The (n-1) multipliers that define the matrix L from the LU factorization of A as computed by CGTTRF.

DIAGF (input)
The n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UPF1 (input)
The (n-1) elements of the first superdiagonal of U.

UPF2 (input)
The (n-2) elements of the second superdiagonal of U.

IPIVOT (input)
The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by CGTTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cgtsv - solve the equation $A \cdot X = B$,

SYNOPSIS

```
SUBROUTINE CGTSV(N, NRHS, LOW, DIAG, UP, B, LDB, INFO)
```

```
COMPLEX LOW(*), DIAG(*), UP(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO
```

```
SUBROUTINE CGTSV_64(N, NRHS, LOW, DIAG, UP, B, LDB, INFO)
```

```
COMPLEX LOW(*), DIAG(*), UP(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE GTSV([N], [NRHS], LOW, DIAG, UP, B, [LDB], [INFO])
```

```
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO
```

```
SUBROUTINE GTSV_64([N], [NRHS], LOW, DIAG, UP, B, [LDB], [INFO])
```

```
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgtsv(int n, int nrhs, complex *low, complex *diag,  
          complex *up, complex *b, int ldb, int *info);
```

```
void cgtsv_64(long n, long nrhs, complex *low, complex  
             *diag, complex *up, complex *b, long ldb, long  
             *info);
```

PURPOSE

cgtsv solves the equation

where A is an N-by-N tridiagonal matrix, by Gaussian elimination with partial pivoting.

Note that the equation $A^*X = B$ may be solved by interchanging the order of the arguments DU and DL.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input/output)
On entry, LOW must contain the (n-1) subdiagonal elements of A. On exit, LOW is overwritten by the (n-2) elements of the second superdiagonal of the upper triangular matrix U from the LU factorization of A, in LOW(1), ..., LOW(n-2).

DIAG (input/output)
On entry, DIAG must contain the diagonal elements of A. On exit, DIAG is overwritten by the n diagonal elements of U.

UP (input/output)
On entry, UP must contain the (n-1) superdiagonal elements of A. On exit, UP is overwritten by the (n-1) elements of the first superdiagonal of U.

B (input/output)
On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1,N)$.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, U(i,i) is exactly zero, and the solution has not been computed. The factorization has not been completed unless $i = N$.

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NAME

cgtsvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE CGTSVX(FACT, TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
  WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA
COMPLEX LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*), UPF1(*),
UPF2(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*)
REAL RCOND
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CGTSVX_64(FACT, TRANSA, N, NRHS, LOW, DIAG, UP, LOWF,
  DIAGF, UPF1, UPF2, IPIVOT, B, LDB, X, LDX, RCOND, FERR, BERR,
  WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA
COMPLEX LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*), UPF1(*),
UPF2(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
REAL RCOND
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GTSVX(FACT, [TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
  DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR,
  [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, WORK
COMPLEX, DIMENSION(:,:) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
```

```

INTEGER, DIMENSION(:) :: IPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: FERR, BERR, WORK2

SUBROUTINE GTSVX_64(FACT, [TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
    DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR,
    [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, TRANSA
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void cgtsvx(char fact, char transa, int n, int nrhs, complex
    *low, complex *diag, complex *up, complex *lowf,
    complex *diagf, complex *upf1, complex *upf2, int
    *ipivot, complex *b, int ldb, complex *x, int ldx,
    float *rcond, float *ferr, float *berr, int
    *info);

void cgtsvx_64(char fact, char transa, long n, long nrhs,
    complex *low, complex *diag, complex *up, complex
    *lowf, complex *diagf, complex *upf1, complex
    *upf2, long *ipivot, complex *b, long ldb, complex
    *x, long ldx, float *rcond, float *ferr, float
    *berr, long *info);

```

PURPOSE

cgtsvx uses the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{*T} * X = B$, or $A^{*H} * X = B$, where A is a tridiagonal matrix of order N and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the LU decomposition is used to factor the matrix A
 - as $A = L * U$, where L is a product of permutation and unit lower bidiagonal matrices and U is upper triangular with nonzeros in only the main diagonal and first two superdiagonals.
2. If some $U(i,i)=0$, so that U is exactly singular, then the routine
 - returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': LOWF, DIAGF, UPF1, UPF2, and IPIVOT contain the factored form of A; LOW, DIAG, UP, LOWF, DIAGF, UPF1, UPF2 and IPIVOT will not be modified. = 'N': The matrix will be copied to LOWF, DIAGF, and UPF1 and factored.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input)

The (n-1) subdiagonal elements of A.

DIAG (input)

The n diagonal elements of A.

UP (input)

The (n-1) superdiagonal elements of A.

LOWF (input or output)

If FACT = 'F', then LOWF is an input argument and on entry contains the (n-1) multipliers that define the matrix L from the LU factorization of A as computed by CGTTRF.

If FACT = 'N', then LOWF is an output argument and

on exit contains the (n-1) multipliers that define the matrix L from the LU factorization of A.

DIAGF (input or output)

If FACT = 'F', then DIAGF is an input argument and on entry contains the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

If FACT = 'N', then DIAGF is an output argument and on exit contains the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UPF1 (input or output)

If FACT = 'F', then UPF1 is an input argument and on entry contains the (n-1) elements of the first superdiagonal of U.

If FACT = 'N', then UPF1 is an output argument and on exit contains the (n-1) elements of the first superdiagonal of U.

UPF2 (input or output)

If FACT = 'F', then UPF2 is an input argument and on entry contains the (n-2) elements of the second superdiagonal of U.

If FACT = 'N', then UPF2 is an output argument and on exit contains the (n-2) elements of the second superdiagonal of U.

IPIVOT (input/output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the LU factorization of A as computed by CGTTRF.

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the LU factorization of A; row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine

precision (in particular, if $RCOND = 0$), the matrix is singular to working precision. This condition is indicated by a return code of $INFO > 0$.

FERR (output)

The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for $RCOND$, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension($2*N$)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, and i is
<= N : $U(i,i)$ is exactly zero. The factorization has not been completed unless $i = N$, but the factor U is exactly singular, so the solution and error bounds could not be computed. $RCOND = 0$ is returned. = $N+1$: U is nonsingular, but $RCOND$ is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of $RCOND$ would suggest.

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NAME

cgtrfs - compute an LU factorization of a complex tridiagonal matrix A using elimination with partial pivoting and row interchanges

SYNOPSIS

```
SUBROUTINE CGTTRF(N, LOW, DIAG, UP1, UP2, IPIVOT, INFO)
```

```
COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CGTTRF_64(N, LOW, DIAG, UP1, UP2, IPIVOT, INFO)
```

```
COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GTTRF([N], LOW, DIAG, UP1, UP2, IPIVOT, [INFO])
```

```
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP1, UP2  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GTTRF_64([N], LOW, DIAG, UP1, UP2, IPIVOT, [INFO])
```

```
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP1, UP2  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cgtrfs(int n, complex *low, complex *diag, complex  
*up1, complex *up2, int *ipivot, int *info);
```

```
void cgtrfs_64(long n, complex *low, complex *diag, complex  
*up1, complex *up2, long *ipivot, long *info);
```

PURPOSE

cgtrf computes an LU factorization of a complex tridiagonal matrix A using elimination with partial pivoting and row interchanges.

The factorization has the form

$$A = L * U$$

where L is a product of permutation and unit lower bidiagonal matrices and U is upper triangular with nonzeros in only the main diagonal and first two superdiagonals.

ARGUMENTS

N (input) The order of the matrix A.

LOW (input/output)

On entry, LOW must contain the (n-1) sub-diagonal elements of A.

On exit, LOW is overwritten by the (n-1) multipliers that define the matrix L from the LU factorization of A.

DIAG (input/output)

On entry, DIAG must contain the diagonal elements of A.

On exit, DIAG is overwritten by the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UP1 (input/output)

On entry, UP1 must contain the (n-1) super-diagonal elements of A.

On exit, UP1 is overwritten by the (n-1) elements of the first super-diagonal of U.

UP2 (output)

On exit, UP2 is overwritten by the (n-2) elements of the second super-diagonal of U.

IPIVOT (output)

The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, U(k,k) is exactly zero. The factorization has been completed, but the factor U

is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

cgtrfs - solve one of the systems of equations $A * X = B$,
 $A^{*T} * X = B$, or $A^{*H} * X = B$,

SYNOPSIS

```
SUBROUTINE CGTTRS(TRANSA, N, NRHS, LOW, DIAG, UP1, UP2, IPIVOT, B,  
LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CGTTRS_64(TRANSA, N, NRHS, LOW, DIAG, UP1, UP2, IPIVOT, B,  
LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GTTRS([TRANSA], [N], [NRHS], LOW, DIAG, UP1, UP2, IPIVOT,  
B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP1, UP2  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GTTRS_64([TRANSA], [N], [NRHS], LOW, DIAG, UP1, UP2,  
IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX, DIMENSION(:) :: LOW, DIAG, UP1, UP2  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void cgttrs(char transa, int n, int nrhs, complex *low, complex
 *diag, complex *up1, complex *up2, int
 *ipivot, complex *b, int ldb, int *info);
void cgttrs_64(char transa, long n, long nrhs, complex *low,
 complex *diag, complex *up1, complex *up2, long
 *ipivot, complex *b, long ldb, long *info);
```

PURPOSE

cgttrs solves one of the systems of equations
 $A * X = B$, $A^{*T} * X = B$, or $A^{*H} * X = B$, with a tri-
diagonal matrix A using the LU factorization computed by
CGTTRF.

ARGUMENTS

TRANSA (input)
Specifies the form of the system of equations. =
'N': $A * X = B$ (No transpose)
= 'T': $A^{*T} * X = B$ (Transpose)
= 'C': $A^{*H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A.

NRHS (input)
The number of right hand sides, i.e., the number
of columns of the matrix B. NRHS \geq 0.

LOW (input)
The (n-1) multipliers that define the matrix L
from the LU factorization of A.

DIAG (input)
The n diagonal elements of the upper triangular
matrix U from the LU factorization of A.

UP1 (input)
The (n-1) elements of the first super-diagonal of
U.

UP2 (input)
The (n-2) elements of the second super-diagonal of
U.

IPIVOT (input)
The pivot indices; for $1 \leq i \leq n$, row i of the
matrix was interchanged with row IPIVOT(i).
IPIVOT(i) will always be either i or i+1;
IPIVOT(i) = i indicates a row interchange was not
required.

B (input/output)

On entry, the matrix of right hand side vectors B.
On exit, B is overwritten by the solution vectors X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value

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NAME

chbev - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

SYNOPSIS

```
SUBROUTINE CHBEV(JOBZ, UPLO, N, KD, A, LDA, W, Z, LDZ, WORK,  
                WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)  
INTEGER N, KD, LDA, LDZ, INFO  
REAL W(*), WORK2(*)
```

```
SUBROUTINE CHBEV_64(JOBZ, UPLO, N, KD, A, LDA, W, Z, LDZ, WORK,  
                  WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, KD, LDA, LDZ, INFO  
REAL W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HBEV(JOBZ, UPLO, [N], KD, A, [LDA], W, Z, [LDZ], [WORK],  
               [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, Z  
INTEGER :: N, KD, LDA, LDZ, INFO  
REAL, DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HBEV_64(JOBZ, UPLO, [N], KD, A, [LDA], W, Z, [LDZ],  
                  [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, Z  
INTEGER(8) :: N, KD, LDA, LDZ, INFO  
REAL, DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void chbev(char jobz, char uplo, int n, int kd, complex *a,
           int lda, float *w, complex *z, int ldz, int
           *info);
void chbev_64(char jobz, char uplo, long n, long kd, complex
              *a, long lda, float *w, complex *z, long ldz, long
              *info);
```

PURPOSE

chbev computes all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

A (input/output)
On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, A is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of the tridiagonal matrix T are returned in rows KD and $KD+1$ of A, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the first two rows of A.

LDA (input)
The leading dimension of the array A. $LDA \geq KD + 1$.

W (output)
If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the

orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

dimension(N)

WORK2 (workspace)

dimension(max(1,3*N-2))

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

chbevd - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

SYNOPSIS

```
SUBROUTINE CHBEVD(JOBZ, UPLO, N, KD, AB, LDAB, W, Z, LDZ, WORK,  
                 LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AB(LDAB,*), Z(LDZ,*), WORK(*)  
INTEGER N, KD, LDAB, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHBEVD_64(JOBZ, UPLO, N, KD, AB, LDAB, W, Z, LDZ, WORK,  
                   LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AB(LDAB,*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, KD, LDAB, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBEVD(JOBZ, UPLO, [N], KD, AB, [LDAB], W, Z, [LDZ], [WORK],  
                [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: AB, Z  
INTEGER :: N, KD, LDAB, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HBEVD_64(JOBZ, UPLO, [N], KD, AB, [LDAB], W, Z, [LDZ],  
                   [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: AB, Z
```

```
INTEGER(8) :: N, KD, LDAB, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: W, RWORK
```

C INTERFACE

```
#include <sunperf.h>
void chbevd(char jobz, char uplo, int n, int kd, complex
            *ab, int ldab, float *w, complex *z, int ldz, int
            *info);

void chbevd_64(char jobz, char uplo, long n, long kd, com-
               plex *ab, long ldab, float *w, complex *z, long
               ldz, long *info);
```

PURPOSE

chbevd computes all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

AB (input/output)
On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.
On exit, AB is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of

the tridiagonal matrix T are returned in rows KD and KD+1 of AB, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the first two rows of AB.

LDAB (input)

The leading dimension of the array AB. LDAB \geq KD + 1.

W (output)

If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If N \leq 1, LWORK must be at least 1. If JOBZ = 'N' and N $>$ 1, LWORK must be at least N. If JOBZ = 'V' and N $>$ 1, LWORK must be at least $2*N**2$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

dimension (LRWORK) On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)

The dimension of array RWORK. If N \leq 1, LRWORK must be at least 1. If JOBZ = 'N' and N $>$ 1, LRWORK must be at least N. If JOBZ = 'V' and N $>$ 1, LRWORK must be at least $1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of array IWORK. If JOBZ = 'N' or N \leq 1, LIWORK must be at least 1. If JOBZ = 'V' and N $>$ 1, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

chbevz - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

SYNOPSIS

```
SUBROUTINE CHBEVZ(JOBZ, RANGE, UPLO, N, KD, A, LDA, Q, LDQ, VL,
                 VU, IL, IU, ABTOL, NFOUND, W, Z, LDZ, WORK, WORK2, IWORK3, IFAIL,
                 INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(LDA,*), Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER IWORK3(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL W(*), WORK2(*)
```

```
SUBROUTINE CHBEVZ_64(JOBZ, RANGE, UPLO, N, KD, A, LDA, Q, LDQ, VL,
                   VU, IL, IU, ABTOL, NFOUND, W, Z, LDZ, WORK, WORK2, IWORK3, IFAIL,
                   INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(LDA,*), Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER*8 N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER*8 IWORK3(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HBEVZ(JOBZ, RANGE, UPLO, [N], KD, A, [LDA], Q, [LDQ],
                VL, VU, IL, IU, ABTOL, [NFOUND], W, Z, [LDZ], [WORK], [WORK2],
                [IWORK3], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, Q, Z
INTEGER :: N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK3, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK2
```

```

SUBROUTINE HBEVX_64(JOBZ, RANGE, UPLO, [N], KD, A, [LDA], Q, [LDQ],
    VL, VU, IL, IU, ABTOL, [NFOUND], W, Z, [LDZ], [WORK], [WORK2],
    [IWORK3], IFAIL, [INFO])

```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, Q, Z
INTEGER(8) :: N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK3, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void chbevz(char jobz, char range, char uplo, int n, int kd,
    complex *a, int lda, complex *q, int ldq, float
    vl, float vu, int il, int iu, float abtol, int
    *nfound, float *w, complex *z, int ldz, int
    *ifail, int *info);

```

```

void chbevz_64(char jobz, char range, char uplo, long n,
    long kd, complex *a, long lda, complex *q, long
    ldq, float vl, float vu, long il, long iu, float
    abtol, long *nfound, float *w, complex *z, long
    ldz, long *ifail, long *info);

```

PURPOSE

chbevz computes selected eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

= 'A': all eigenvalues will be found;
 = 'V': all eigenvalues in the half-open interval
 (VL,VU] will be found; = 'I': the IL-th through
 IU-th eigenvalues will be found.

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. N >= 0.

KD (input)

The number of superdiagonals of the matrix A if
 UPLO = 'U', or the number of subdiagonals if UPLO

= 'L'. KD >= 0.

A (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first KD+1 rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$.

On exit, A is overwritten by values generated during the reduction to tridiagonal form.

LDA (input)

The leading dimension of the array A. LDA >= KD + 1.

Q (output)

If JOBZ = 'V', the N-by-N unitary matrix used in the reduction to tridiagonal form. If JOBZ = 'N', the array Q is not referenced.

LDQ (input)

The leading dimension of the array Q. If JOBZ = 'V', then LDQ >= max(1,N).

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; IL = 1 and IU = 0 if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; IL = 1 and IU = 0 if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where |T| is the 1-norm of the

tridiagonal matrix obtained by reducing A to tri-diagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2*SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)

The first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if $INFO = 0$, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, NFOUND)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension(N)

WORK2 (workspace)

dimension(7*N)

IWORK3 (workspace)

dimension(5*N)

IFAIL (output)

If JOBZ = 'V', then if $INFO = 0$, the first NFOUND elements of IFAIL are zero. If $INFO > 0$, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, then i eigenvectors failed to

converge. Their indices are stored in array
IFAIL.

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NAME

chbgst - reduce a complex Hermitian-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$,

SYNOPSIS

```
SUBROUTINE CHBGST(VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X, LDX,
                 WORK, RWORK, INFO)
```

```
CHARACTER * 1 VECT, UPLO
COMPLEX AB(LDAB,*), BB(LDBB,*), X(LDX,*), WORK(*)
INTEGER N, KA, KB, LDAB, LDBB, LDX, INFO
REAL RWORK(*)
```

```
SUBROUTINE CHBGST_64(VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X,
                    LDX, WORK, RWORK, INFO)
```

```
CHARACTER * 1 VECT, UPLO
COMPLEX AB(LDAB,*), BB(LDBB,*), X(LDX,*), WORK(*)
INTEGER*8 N, KA, KB, LDAB, LDBB, LDX, INFO
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBGST(VECT, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], X,
                [LDX], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: AB, BB, X
INTEGER :: N, KA, KB, LDAB, LDBB, LDX, INFO
REAL, DIMENSION(:) :: RWORK
```

```
SUBROUTINE HBGST_64(VECT, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],
                   X, [LDX], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: AB, BB, X
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDX, INFO
REAL, DIMENSION(:) :: RWORK
```

C INTERFACE

```
#include <sunperf.h>

void chbgst(char vect, char uplo, int n, int ka, int kb,
            complex *ab, int ldab, complex *bb, int ldbb, com-
            plex *x, int ldx, int *info);
void chbgst_64(char vect, char uplo, long n, long ka, long
              kb, complex *ab, long ldab, complex *bb, long
              ldbb, complex *x, long ldx, long *info);
```

PURPOSE

chbgst reduces a complex Hermitian-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$, such that C has the same bandwidth as A.

B must have been previously factorized as $S**H*S$ by CPBSTF, using a split Cholesky factorization. A is overwritten by $C = X**H*A*X$, where $X = S**(-1)*Q$ and Q is a unitary matrix chosen to preserve the bandwidth of A.

ARGUMENTS

VECT (input)
= 'N': do not form the transformation matrix X;
= 'V': form X.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KA \geq 0$.

KB (input)
The number of superdiagonals of the matrix B if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KA \geq KB \geq 0$.

AB (input/output)
On entry, the upper or lower triangle of the Her-
mitian band matrix A, stored in the first $ka+1$
rows of the array. The j-th column of A is stored
in the j-th column of the array AB as follows: if
UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-$
 $ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$
for $j \leq i \leq \min(n,j+ka)$.
On exit, the transformed matrix $X**H*A*X$, stored
in the same format as A.

LDAB (input)

The leading dimension of the array AB. LDAB \geq KA+1.

BB (input)

The banded factor S from the split Cholesky factorization of B, as returned by CPBSTF, stored in the first kb+1 rows of the array.

LDBB (input)

The leading dimension of the array BB. LDBB \geq KB+1.

X (output)

If VECT = 'V', the n-by-n matrix X. If VECT = 'N', the array X is not referenced.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N) if VECT = 'V'; LDX \geq 1 otherwise.

WORK (workspace)

dimension(N)

RWORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

chbgv - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

SYNOPSIS

```
SUBROUTINE CHBGV(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
                LDZ, WORK, RWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AB(LDAB,*), BB(LDBB,*), Z(LDZ,*), WORK(*)  
INTEGER N, KA, KB, LDAB, LDBB, LDZ, INFO  
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHBGV_64(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
                  LDZ, WORK, RWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AB(LDAB,*), BB(LDBB,*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, KA, KB, LDAB, LDBB, LDZ, INFO  
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBGV(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], W,  
               Z, [LDZ], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: AB, BB, Z  
INTEGER :: N, KA, KB, LDAB, LDBB, LDZ, INFO  
REAL, DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HBGV_64(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],  
                  W, Z, [LDZ], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: AB, BB, Z  
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDZ, INFO  
REAL, DIMENSION(:) :: W, RWORK
```

C INTERFACE

```
#include <sunperf.h>

void chbgv(char jobz, char uplo, int n, int ka, int kb, complex *ab, int ldab, complex *bb, int ldbb, float *w, complex *z, int ldz, int *info);
void chbgv_64(char jobz, char uplo, long n, long ka, long kb, complex *ab, long ldab, complex *bb, long ldbb, float *w, complex *z, long ldz, long *info);
```

PURPOSE

chbgv computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$. Here A and B are assumed to be Hermitian and banded, and B is also positive definite.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangles of A and B are stored;
= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KA \geq 0$.

KB (input)
The number of superdiagonals of the matrix B if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KB \geq 0$.

AB (input/output)
On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $ka+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+ka)$.

On exit, the contents of AB are destroyed.

LDAB (input)
The leading dimension of the array AB. $LDAB \geq KA+1$.

BB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix B, stored in the first kb+1 rows of the array. The j-th column of B is stored in the j-th column of the array BB as follows: if UPLO = 'U', $BB(kb+1+i-j,j) = B(i,j)$ for $\max(1,j-kb) \leq i \leq j$; if UPLO = 'L', $BB(1+i-j,j) = B(i,j)$ for $j \leq i \leq \min(n,j+kb)$.

On exit, the factor S from the split Cholesky factorization $B = S^*H^*S$, as returned by CPBSTF.

LDBB (input)

The leading dimension of the array BB. LDBB \geq KB+1.

W (output)

If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with W(i). The eigenvectors are normalized so that $Z^*H^*B^*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq N.

WORK (workspace)

dimension(N)

RWORK (workspace)

dimension(3*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is:
<= N: the algorithm failed to converge: i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq N$, then CPBSTF returned INFO = i: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

chbgvd - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

SYNOPSIS

```
SUBROUTINE CHBGVD(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
  LDZ, WORK, LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AB(LDAB,*), BB(LDBB,*), Z(LDZ,*), WORK(*)  
INTEGER N, KA, KB, LDAB, LDBB, LDZ, LWORK, LRWORK, LIWORK,  
INFO  
INTEGER IWORK(*)  
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHBGVD_64(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
  LDZ, WORK, LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AB(LDAB,*), BB(LDBB,*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, KA, KB, LDAB, LDBB, LDZ, LWORK, LRWORK, LIWORK,  
INFO  
INTEGER*8 IWORK(*)  
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBGVD(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], W,  
  Z, [LDZ], [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK],  
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: AB, BB, Z  
INTEGER :: N, KA, KB, LDAB, LDBB, LDZ, LWORK, LRWORK,  
LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, RWORK
```

```

SUBROUTINE HBGVD_64(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],
    W, Z, [LDZ], [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK],
    [INFO])

```

```

CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: AB, BB, Z
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDZ, LWORK, LRWORK,
LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: W, RWORK

```

C INTERFACE

```
#include <sunperf.h>
```

```

void chbgvd(char jobz, char uplo, int n, int ka, int kb,
    complex *ab, int ldab, complex *bb, int ldbb,
    float *w, complex *z, int ldz, int *info);

```

```

void chbgvd_64(char jobz, char uplo, long n, long ka, long
    kb, complex *ab, long ldab, complex *bb, long
    ldbb, float *w, complex *z, long ldz, long *info);

```

PURPOSE

chbgvd computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$. Here A and B are assumed to be Hermitian and banded, and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)

```

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

```

UPLO (input)

```

= 'U': Upper triangles of A and B are stored;
= 'L': Lower triangles of A and B are stored.

```

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)

```

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO

```

= 'L'. KA >= 0.
 KB (input) The number of superdiagonals of the matrix B if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. KB >= 0.

AB (input/output)
 On entry, the upper or lower triangle of the Her-
 mitian band matrix A, stored in the first ka+1
 rows of the array. The j-th column of A is stored
 in the j-th column of the array AB as follows: if
 UPLO = 'U', AB(ka+1+i-j,j) = A(i,j) for max(1,j-
 ka)<=i<=j; if UPLO = 'L', AB(1+i-j,j) = A(i,j)
 for j<=i<=min(n,j+ka).

 On exit, the contents of AB are destroyed.

LDAB (input)
 The leading dimension of the array AB. LDAB >=
 KA+1.

BB (input/output)
 On entry, the upper or lower triangle of the Her-
 mitian band matrix B, stored in the first kb+1
 rows of the array. The j-th column of B is stored
 in the j-th column of the array BB as follows: if
 UPLO = 'U', BB(kb+1+i-j,j) = B(i,j) for max(1,j-
 kb)<=i<=j; if UPLO = 'L', BB(1+i-j,j) = B(i,j)
 for j<=i<=min(n,j+kb).

 On exit, the factor S from the split Cholesky fac-
 torization $B = S^*H^*S$, as returned by CPBSTF.

LDBB (input)
 The leading dimension of the array BB. LDBB >=
 KB+1.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the
 matrix Z of eigenvectors, with the i-th column of
 Z holding the eigenvector associated with W(i).
 The eigenvectors are normalized so that $Z^*H^*B^*Z = I$.
 If JOBZ = 'N', then Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. LDZ >= 1,
 and if JOBZ = 'V', LDZ >= N.

WORK (workspace)
 On exit, if INFO=0, WORK(1) returns the optimal
 LWORK.

LWORK (input)
 The dimension of the array WORK. If $N \leq 1$,
 LWORK >= 1. If JOBZ = 'N' and $N > 1$, LWORK >= N.
 If JOBZ = 'V' and $N > 1$, LWORK >= $2*N^2$.

 If LWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the WORK array, returns this value as the first

entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

On exit, if INFO=0, RWORK(1) returns the optimal LWORK.

LRWORK (input)

The dimension of array RWORK. If $N \leq 1$, LRWORK ≥ 1 . If JOBZ = 'N' and $N > 1$, LRWORK $\geq N$. If JOBZ = 'V' and $N > 1$, LRWORK $\geq 1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO=0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of array IWORK. If JOBZ = 'N' or $N \leq 1$, LIWORK ≥ 1 . If JOBZ = 'V' and $N > 1$, LIWORK $\geq 3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is:
<= N: the algorithm failed to converge: i off-diagonal elements of an intermediate tridiagonal form did not converge to zero;
> N: if INFO = N + i, for $1 \leq i \leq N$, then CPBSTF returned INFO = i: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

chbgvx - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

SYNOPSIS

```
SUBROUTINE CHBGVX(JOBZ, RANGE, UPLO, N, KA, KB, AB, LDAB, BB, LDBB,
  Q, LDQ, VL, VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, RWORK, IWORK,
  IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX AB(LDAB,*), BB(LDBB,*), Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHBGVX_64(JOBZ, RANGE, UPLO, N, KA, KB, AB, LDAB, BB,
  LDBB, Q, LDQ, VL, VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, RWORK,
  IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX AB(LDAB,*), BB(LDBB,*), Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER*8 N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER*8 IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBGVX(JOBZ, RANGE, UPLO, [N], KA, KB, AB, [LDAB], BB,
  [LDBB], Q, [LDQ], VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK],
  [RWORK], [IWORK], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: AB, BB, Q, Z
INTEGER :: N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
```

```

REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, RWORK

SUBROUTINE HBGVX_64(JOBZ, RANGE, UPLO, [N], KA, KB, AB, [LDAB], BB,
  [LDBB], Q, [LDQ], VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK],
  [RWORK], [IWORK], IFAIL, [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: AB, BB, Q, Z
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ,
INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void chbgvx(char jobz, char range, char uplo, int n, int ka,
  int kb, complex *ab, int ldab, complex *bb, int
  ldbb, complex *q, int ldq, float vl, float vu, int
  il, int iu, float abstol, int *m, float *w, com-
  plex *z, int ldz, int *ifail, int *info);

void chbgvx_64(char jobz, char range, char uplo, long n,
  long ka, long kb, complex *ab, long ldab, complex
  *bb, long ldbb, complex *q, long ldq, float vl,
  float vu, long il, long iu, float abstol, long *m,
  float *w, complex *z, long ldz, long *ifail, long
  *info);

```

PURPOSE

chbgvx computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$. Here A and B are assumed to be Hermitian and banded, and B is also positive definite. Eigenvalues and eigenvectors can be selected by specifying either all eigenvalues, a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found;
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found; = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangles of A and B are stored;

= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KA \geq 0$.

KB (input)
The number of superdiagonals of the matrix B if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KB \geq 0$.

AB (input/output)
On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $ka+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j, j) = A(i, j)$ for $\max(1, j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+ka)$.

On exit, the contents of AB are destroyed.

LDAB (input)
The leading dimension of the array AB. $LDAB \geq KA+1$.

BB (input/output)
On entry, the upper or lower triangle of the Hermitian band matrix B, stored in the first $kb+1$ rows of the array. The j -th column of B is stored in the j -th column of the array BB as follows: if UPLO = 'U', $BB(kb+1+i-j, j) = B(i, j)$ for $\max(1, j-kb) \leq i \leq j$; if UPLO = 'L', $BB(1+i-j, j) = B(i, j)$ for $j \leq i \leq \min(n, j+kb)$.

On exit, the factor S from the split Cholesky factorization $B = S^*H^*S$, as returned by CPBSTF.

LDBB (input)
The leading dimension of the array BB. $LDBB \geq KB+1$.

Q (output)
If JOBZ = 'V', the n -by- n matrix used in the reduction of $A^*x = (\lambda)B^*x$ to standard form, i.e. $C^*x = (\lambda)x$, and consequently C to tridiagonal form. If JOBZ = 'N', the array Q is not referenced.

LDQ (input)
The leading dimension of the array Q. If JOBZ = 'N', $LDQ \geq 1$. If JOBZ = 'V', $LDQ \geq \max(1, N)$.

VL (input)
If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing AP to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2 * SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

If $INFO = 0$, the eigenvalues in ascending order.

Z (input)

If $JOBZ = 'V'$, then if $INFO = 0$, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized so that $Z^* H B Z = I$. If $JOBZ = 'N'$, then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if $JOBZ = 'V'$, $LDZ \geq N$.

WORK (workspace)

dimension(N)

RWORK (workspace)

dimension(7*N)

IWORK (workspace)
dimension(5*N)

IFAIL (output)
If JOBZ = 'V', then if INFO = 0, the first M elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is:
<= N: then i eigenvectors failed to converge. Their indices are stored in array IFAIL. > N: if INFO = N + i, for 1 <= i <= N, then CPBSTF returned INFO = i: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

chbmv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE CHBMV(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y,  
                INCY)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA, BETA  
COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER N, K, LDA, INCX, INCY
```

```
SUBROUTINE CHBMV_64(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y,  
                  INCY)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA, BETA  
COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER*8 N, K, LDA, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE HBMV(UPLO, [N], K, ALPHA, A, [LDA], X, [INCX], BETA,  
              Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, K, LDA, INCX, INCY
```

```
SUBROUTINE HBMV_64(UPLO, [N], K, ALPHA, A, [LDA], X, [INCX],  
                  BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, K, LDA, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>

void chbmvm(char uplo, int n, int k, complex *alpha, complex
            *a, int lda, complex *x, int incx, complex *beta,
            complex *y, int incy);
void chbmvm_64(char uplo, long n, long k, complex *alpha,
               complex *a, long lda, complex *x, long incx, com-
               plex *beta, complex *y, long incy);
```

PURPOSE

chbmvm performs the matrix-vector operation $y := \alpha A x + \beta y$ where α and β are scalars, x and y are n element vectors and A is an n by n hermitian band matrix, with k super-diagonals.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the band matrix A is being supplied as follows:

UPLO = 'U' or 'u' The upper triangular part of A is being supplied.

UPLO = 'L' or 'l' The lower triangular part of A is being supplied.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

K (input)

On entry, K specifies the number of super-diagonals of the matrix A . K must satisfy $0 \leq K$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading $(k + 1)$ by n part of the array A must contain the upper triangular band part of the hermitian matrix, supplied column by column, with the leading diagonal of the matrix in row $(k + 1)$ of the array, the first super-diagonal starting at position 2 in row k , and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer the upper triangular part of a hermitian band matrix from

conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the hermitian matrix, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer the lower triangular part of a hermitian band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Note that the imaginary parts of the diagonal elements need not be set and are assumed to be zero. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA \geq (k + 1). Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)). Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

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NAME

chbtrd - reduce a complex Hermitian band matrix A to real symmetric tridiagonal form T by a unitary similarity transformation

SYNOPSIS

```
SUBROUTINE CHBTRD(VECT, UPLO, N, KD, AB, LDAB, D, E, Q, LDQ, WORK,  
INFO)
```

```
CHARACTER * 1 VECT, UPLO  
COMPLEX AB(LDAB,*), Q(LDQ,*), WORK(*)  
INTEGER N, KD, LDAB, LDQ, INFO  
REAL D(*), E(*)
```

```
SUBROUTINE CHBTRD_64(VECT, UPLO, N, KD, AB, LDAB, D, E, Q, LDQ, WORK,  
INFO)
```

```
CHARACTER * 1 VECT, UPLO  
COMPLEX AB(LDAB,*), Q(LDQ,*), WORK(*)  
INTEGER*8 N, KD, LDAB, LDQ, INFO  
REAL D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE HBTRD(VECT, UPLO, [N], KD, AB, [LDAB], D, E, Q, [LDQ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: AB, Q  
INTEGER :: N, KD, LDAB, LDQ, INFO  
REAL, DIMENSION(:) :: D, E
```

```
SUBROUTINE HBTRD_64(VECT, UPLO, [N], KD, AB, [LDAB], D, E, Q, [LDQ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: AB, Q
```

```
INTEGER(8) :: N, KD, LDAB, LDQ, INFO
REAL, DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>

void chbtrd(char vect, char uplo, int n, int kd, complex
            *ab, int ldab, float *d, float *e, complex *q, int
            ldq, int *info);
void chbtrd_64(char vect, char uplo, long n, long kd, com-
               plex *ab, long ldab, float *d, float *e, complex
               *q, long ldq, long *info);
```

PURPOSE

chbtrd reduces a complex Hermitian band matrix A to real symmetric tridiagonal form T by a unitary similarity transformation: $Q^*H * A * Q = T$.

ARGUMENTS

VECT (input)
= 'N': do not form Q;
= 'V': form Q;
= 'U': update a matrix X, by forming $X*Q$.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)
On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. On exit, the diagonal elements of AB are overwritten by the diagonal elements of the tridiagonal matrix T; if $KD > 0$, the elements on the first superdiagonal (if UPLO = 'U') or the first subdiagonal (if UPLO = 'L') are overwritten by the off-diagonal elements of T; the rest of AB is overwritten by values generated during the reduction.

LDAB (input)
The leading dimension of the array AB. $LDAB \geq KD+1$.

D (output)
The diagonal elements of the tridiagonal matrix T.

E (output)
The off-diagonal elements of the tridiagonal matrix T: $E(i) = T(i,i+1)$ if UPLO = 'U'; $E(i) = T(i+1,i)$ if UPLO = 'L'.

Q (input/output)
On entry, if VECT = 'U', then Q must contain an N-by-N matrix X; if VECT = 'N' or 'V', then Q need not be set.

On exit: if VECT = 'V', Q contains the N-by-N unitary matrix Q; if VECT = 'U', Q contains the product $X*Q$; if VECT = 'N', the array Q is not referenced.

LDQ (input)
The leading dimension of the array Q. LDQ \geq 1, and LDQ \geq N if VECT = 'V' or 'U'.

WORK (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Modified by Linda Kaufman, Bell Labs.

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NAME

checon - estimate the reciprocal of the condition number of a complex Hermitian matrix A using the factorization $A = U^*D^*U^*H$ or $A = L^*D^*L^*H$ computed by CHETRF

SYNOPSIS

```
SUBROUTINE CHECON(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*)  
REAL ANORM, RCOND
```

```
SUBROUTINE CHECON_64(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK,  
INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*)  
REAL ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE HECON(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL :: ANORM, RCOND
```

```
SUBROUTINE HECON_64(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A
```

```
INTEGER(8) :: N, LDA, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>
void checon(char uplo, int n, complex *a, int lda, int
            *ipivot, float anorm, float *rcond, int *info);

void checon_64(char uplo, long n, complex *a, long lda, long
              *ipivot, float anorm, float *rcond, long *info);
```

PURPOSE

checon estimates the reciprocal of the condition number of a complex Hermitian matrix A using the factorization $A = U^*D^*U^{**H}$ or $A = L^*D^*L^{**H}$ computed by CHETRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U^*D^*U^{**H}$;
= 'L': Lower triangular, form is $A = L^*D^*L^{**H}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CHETRF.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by CHETRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cheev - compute all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

SYNOPSIS

```
SUBROUTINE CHEEV(JOBZ, UPLO, N, A, LDA, W, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, LDWORK, INFO  
REAL W(*), WORK2(*)
```

```
SUBROUTINE CHEEV_64(JOBZ, UPLO, N, A, LDA, W, WORK, LDWORK, WORK2,  
INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, LDWORK, INFO  
REAL W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE CHEEV(JOBZ, UPLO, [N], A, [LDA], W, [WORK], [LDWORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE CHEEV_64(JOBZ, UPLO, [N], A, [LDA], W, [WORK], [LDWORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void cheev(char jobz, char uplo, int n, complex *a, int lda,
           float *w, int *info);

void cheev_64(char jobz, char uplo, long n, complex *a, long
              lda, float *w, long *info);
```

PURPOSE

cheev computes all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)
 On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, if JOBZ = 'V', then if INFO = 0, A contains the orthonormal eigenvectors of the matrix A. If JOBZ = 'N', then on exit the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The length of the array WORK. $LDWORK \geq \max(1, 2*N-1)$. For optimal efficiency, $LDWORK \geq (NB+1)*N$, where NB is the blocksize for CHETRD returned by ILAENV.
 If LDWORK = -1, then a workspace query is assumed;

the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)

dimension(max(1,3*N-2))

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

cheevd - compute all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

SYNOPSIS

```
SUBROUTINE CHEEVD(JOBZ, UPLO, N, A, LDA, W, WORK, LWORK, RWORK,  
  LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHEEVD_64(JOBZ, UPLO, N, A, LDA, W, WORK, LWORK, RWORK,  
  LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HEEVD(JOBZ, UPLO, [N], A, [LDA], W, [WORK], [LWORK],  
  [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HEEVD_64(JOBZ, UPLO, [N], A, [LDA], W, [WORK], [LWORK],  
  [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
```

```
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:,:) :: A
INTEGER(8) :: N, LDA, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: W, RWORK
```

C INTERFACE

```
#include <sunperf.h>
void cheevd(char jobz, char uplo, int n, complex *a, int
            lda, float *w, int *info);

void cheevd_64(char jobz, char uplo, long n, complex *a,
              long lda, float *w, long *info);
```

PURPOSE

cheevd computes all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)
On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, if JOBZ = 'V', then if INFO = 0, A contains the orthonormal eigenvectors of the matrix A. If JOBZ = 'N', then on exit the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The length of the array WORK. If $N \leq 1$, LWORK must be at least 1. If JOBZ = 'N' and $N > 1$, LWORK must be at least $N + 1$. If JOBZ = 'V' and $N > 1$, LWORK must be at least $2*N + N**2$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
 dimension (LRWORK) On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)
 The dimension of the array RWORK. If $N \leq 1$, LRWORK must be at least 1. If JOBZ = 'N' and $N > 1$, LRWORK must be at least N . If JOBZ = 'V' and $N > 1$, LRWORK must be at least $1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)
 On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
 The dimension of the array IWORK. If $N \leq 1$, LIWORK must be at least 1. If JOBZ = 'N' and $N > 1$, LIWORK must be at least 1. If JOBZ = 'V' and $N > 1$, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

FURTHER DETAILS

Based on contributions by
Jeff Rutter, Computer Science Division, University of
California
at Berkeley, USA

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NAME

cheevr - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian tridiagonal matrix T

SYNOPSIS

```
SUBROUTINE CHEEVR(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
                 ABSTOL, M, W, Z, LDZ, ISUPPZ, WORK, LWORK, RWORK, LRWORK, IWORK,
                 LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)
INTEGER N, LDA, IL, IU, M, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER ISUPPZ(*), IWORK(*)
REAL VL, VU, ABSTOL
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHEEVR_64(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
                   ABSTOL, M, W, Z, LDZ, ISUPPZ, WORK, LWORK, RWORK, LRWORK, IWORK,
                   LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)
INTEGER*8 N, LDA, IL, IU, M, LDZ, LWORK, LRWORK, LIWORK,
INFO
INTEGER*8 ISUPPZ(*), IWORK(*)
REAL VL, VU, ABSTOL
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HEEVR(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
                ABSTOL, M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [RWORK], [LRWORK],
                [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, Z
INTEGER :: N, LDA, IL, IU, M, LDZ, LWORK, LRWORK, LIWORK,
INFO
```

```

INTEGER, DIMENSION(:) :: ISUPPZ, IWORK
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, RWORK

SUBROUTINE HEEVR_64(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
    ABSTOL, M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [RWORK], [LRWORK],
    [IWORK], [LIWORK], [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, Z
INTEGER(8) :: N, LDA, IL, IU, M, LDZ, LWORK, LRWORK, LIWORK,
INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void cheevr(char jobz, char range, char uplo, int n, complex
    *a, int lda, float vl, float vu, int il, int iu,
    float abstol, int *m, float *w, complex *z, int
    ldz, int *isuppz, int *info);

void cheevr_64(char jobz, char range, char uplo, long n,
    complex *a, long lda, float vl, float vu, long il,
    long iu, float abstol, long *m, float *w, complex
    *z, long ldz, long *isuppz, long *info);

```

PURPOSE

cheevr computes selected eigenvalues and, optionally, eigenvectors of a complex Hermitian tridiagonal matrix T. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

Whenever possible, CHEEVR calls CSTEGR to compute the eigenspectrum using Relatively Robust Representations. CSTEGR computes eigenvalues by the dqds algorithm, while orthogonal eigenvectors are computed from various "good" L D L^T representations (also known as Relatively Robust Representations). Gram-Schmidt orthogonalization is avoided as far as possible. More specifically, the various steps of the algorithm are as follows. For the i-th unreduced block of T,

- (a) Compute $T - \sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation,
- (b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high relative accuracy by the dqds algorithm,
- (c) If there is a cluster of close eigenvalues, "choose" σ_i close to the cluster, and go to step (a),
- (d) Given the approximate eigenvalue λ_j of $L_i D_i L_i^T$, compute the corresponding eigenvector by forming a

rank-revealing twisted factorization.
The desired accuracy of the output can be specified by the input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB//CSD-97-971, UC Berkeley, May 1997.

Note 1 : CHEEVR calls CSTEGR when the full spectrum is requested on machines which conform to the ieee-754 floating point standard. CHEEVR calls SSTEGBZ and CSTEIN on non-ieee machines and when partial spectrum requests are made.

Normal execution of CSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not handle NaNs and infinities in the ieee standard default manner.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)
On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

VL (input)
If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$.

Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|) ,$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

If high relative accuracy is important, set ABSTOL to SLAMCH('Safe minimum'). Doing so will guarantee that eigenvalues are computed to high relative accuracy when possible in future releases. The current code does not make any guarantees about high relative accuracy, but future releases will. See J. Barlow and J. Demmel, "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7, for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (output)

If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N',

then Z is not referenced. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. LDZ ≥ 1 , and if JOBZ = 'V', LDZ $\geq \max(1, N)$.

ISUPPZ (output)

The support of the eigenvectors in Z, i.e., the indices indicating the nonzero elements in Z. The i-th eigenvector is nonzero only in elements ISUPPZ(2*i-1) through ISUPPZ(2*i).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The length of the array WORK. LWORK $\geq \max(1, 2*N)$. For optimal efficiency, LWORK $\geq (NB+1)*N$, where NB is the max of the blocksize for CHETRD and for CUNMTR as returned by ILAENV.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

On exit, if INFO = 0, RWORK(1) returns the optimal (and minimal) LRWORK.

LRWORK (input)

The length of the array RWORK. LRWORK $\geq \max(1, 24*N)$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal (and minimal) LIWORK.

LIWORK (input)

The dimension of the array IWORK. LIWORK $\geq \max(1, 10*N)$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value
> 0: Internal error

FURTHER DETAILS

Based on contributions by

Inderjit Dhillon, IBM Almaden, USA

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Ken Stanley, Computer Science Division, University of
California at Berkeley, USA

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NAME

cheevx - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

SYNOPSIS

```
SUBROUTINE CHEEVX(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
                  ABTOL, NFOUND, W, Z, LDZ, WORK, LDWORK, WORK2, IWORK3, IFAIL,
                  INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)
INTEGER N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER IWORK3(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL W(*), WORK2(*)
```

```
SUBROUTINE CHEEVX_64(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
                    ABTOL, NFOUND, W, Z, LDZ, WORK, LDWORK, WORK2, IWORK3, IFAIL,
                    INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)
INTEGER*8 N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER*8 IWORK3(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HEEVX(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
                ABTOL, [NFOUND], W, Z, [LDZ], [WORK], [LDWORK], [WORK2], [IWORK3],
                IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, Z
INTEGER :: N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER, DIMENSION(:) :: IWORK3, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK2
```

```

SUBROUTINE HEEVX_64(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
  ABTOL, [NFOUND], W, Z, [LDZ], [WORK], [LDWORK], [WORK2], [IWORK3],
  IFAIL, [INFO])

```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, Z
INTEGER(8) :: N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK3, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void cheevx(char jobz, char range, char uplo, int n, complex
  *a, int lda, float vl, float vu, int il, int iu,
  float abtol, int *nfound, float *w, complex *z,
  int ldz, int *ifail, int *info);

```

```

void cheevx_64(char jobz, char range, char uplo, long n,
  complex *a, long lda, float vl, float vu, long il,
  long iu, float abtol, long *nfound, float *w, com-
  plex *z, long ldz, long *ifail, long *info);

```

PURPOSE

cheevx computes selected eigenvalues and, optionally, eigen-
vectors of a complex Hermitian matrix A. Eigenvalues and
eigenvectors can be selected by specifying either a range of
values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval
(VL,VU] will be found. = 'I': the IL-th through
IU-th eigenvalues will be found.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. N >= 0.

A (input/output)
On entry, the Hermitian matrix A. If UPLO = 'U',
the leading N-by-N upper triangular part of A con-
tains the upper triangular part of the matrix A.
If UPLO = 'L', the leading N-by-N lower triangular
part of A contains the lower triangular part of

the matrix A. On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a, b]$ of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2 * SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)
 On normal exit, the first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least max(1,NFOUND) columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)
 The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The length of the array WORK. LDWORK >= max(1,2*N). For optimal efficiency, LDWORK >= (NB+1)*N, where NB is the max of the blocksize for CHETRD and for CUNMTR as returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
 dimension(7*N)

IWORK3 (workspace)
 dimension(5*N)

IFAIL (output)
 If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

chegs2 - reduce a complex Hermitian-definite generalized eigenproblem to standard form

SYNOPSIS

```
SUBROUTINE CHEGS2(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER ITYPE, N, LDA, LDB, INFO
```

```
SUBROUTINE CHEGS2_64(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 ITYPE, N, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE HEGS2(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: ITYPE, N, LDA, LDB, INFO
```

```
SUBROUTINE HEGS2_64(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: ITYPE, N, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chegs2(int itype, char uplo, int n, complex *a, int  
lda, complex *b, int ldb, int *info);
```

```
void chegs2_64(long itype, char uplo, long n, complex *a,  
long lda, complex *b, long ldb, long *info);
```

PURPOSE

chegs2 reduces a complex Hermitian-definite generalized eigenproblem to standard form.

If ITYPE = 1, the problem is $A*x = \lambda*B*x$, and A is overwritten by $\text{inv}(U')*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L')$. If ITYPE = 2 or 3, the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U'$ or $L'*A*L$.

B must have been previously factorized as $U'*U$ or $L*L'$ by CPOTRF.

ARGUMENTS

ITYPE (input)

= 1: compute $\text{inv}(U')*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L')$;
= 2 or 3: compute $U*A*U'$ or $L'*A*L$.

UPLO (input)

Specifies whether the upper or lower triangular part of the Hermitian matrix A is stored, and how B has been factorized. = 'U': Upper triangular
= 'L': Lower triangular

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading n by n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n by n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the transformed matrix, stored in the same format as A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input) The triangular factor from the Cholesky factorization of B, as returned by CPOTRF.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

chegst - reduce a complex Hermitian-definite generalized eigenproblem to standard form

SYNOPSIS

```
SUBROUTINE CHEGST(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER ITYPE, N, LDA, LDB, INFO
```

```
SUBROUTINE CHEGST_64(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 ITYPE, N, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE HEGST(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: ITYPE, N, LDA, LDB, INFO
```

```
SUBROUTINE HEGST_64(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: ITYPE, N, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chegst(int itype, char uplo, int n, complex *a, int  
lda, complex *b, int ldb, int *info);
```

```
void chegst_64(long itype, char uplo, long n, complex *a,  
long lda, complex *b, long ldb, long *info);
```

PURPOSE

chegst reduces a complex Hermitian-definite generalized eigenproblem to standard form.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $\text{inv}(U^{*H})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{*H})$

If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U^{*H}$ or $L^{*H}*A*L$.

B must have been previously factorized as $U^{*H}*U$ or $L*L^{*H}$ by CPOTRF.

ARGUMENTS

$ITYPE$ (input)
= 1: compute $\text{inv}(U^{*H})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{*H})$;
= 2 or 3: compute $U*A*U^{*H}$ or $L^{*H}*A*L$.

$UPLO$ (input)
= 'U': Upper triangle of A is stored and B is factored as $U^{*H}*U$; = 'L': Lower triangle of A is stored and B is factored as $L*L^{*H}$.

N (input) The order of the matrices A and B . $N \geq 0$.

A (input/output)
On entry, the Hermitian matrix A . If $UPLO = 'U'$, the leading N -by- N upper triangular part of A contains the upper triangular part of the matrix A , and the strictly lower triangular part of A is not referenced. If $UPLO = 'L'$, the leading N -by- N lower triangular part of A contains the lower triangular part of the matrix A , and the strictly upper triangular part of A is not referenced.

On exit, if $INFO = 0$, the transformed matrix, stored in the same format as A .

LDA (input)
The leading dimension of the array A . $LDA \geq \max(1, N)$.

B (input) The triangular factor from the Cholesky factorization of B , as returned by CPOTRF.

LDB (input)
The leading dimension of the array B . $LDB \geq \max(1, N)$.

$INFO$ (output)
= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

chegv - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE CHEGV(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,
                LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER ITYPE, N, LDA, LDB, LDWORK, INFO
REAL W(*), WORK2(*)
```

```
SUBROUTINE CHEGV_64(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,
                  LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER*8 ITYPE, N, LDA, LDB, LDWORK, INFO
REAL W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HEGV(ITYPE, JOBZ, UPLO, N, A, [LDA], B, [LDB], W, [WORK],
               [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER :: ITYPE, N, LDA, LDB, LDWORK, INFO
REAL, DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HEGV_64(ITYPE, JOBZ, UPLO, N, A, [LDA], B, [LDB], W, [WORK],
                  [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER(8) :: ITYPE, N, LDA, LDB, LDWORK, INFO
```

```
REAL, DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chegv(int itype, char jobz, char uplo, int n, complex  
*a, int lda, complex *b, int ldb, float *w, int  
*info);
```

```
void chegv_64(long itype, char jobz, char uplo, long n, com-  
plex *a, long lda, complex *b, long ldb, float *w,  
long *info);
```

PURPOSE

chegv computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*B*x=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian and B is also positive definite.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

= 1: $A*x = (\lambda)*B*x$

= 2: $A*B*x = (\lambda)*x$

= 3: $B*A*x = (\lambda)*x$

JOBZ (input)

= 'N': Compute eigenvalues only;

= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangles of A and B are stored;

= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.

On exit, if JOBZ = 'V', then if INFO = 0, A contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^H*B*Z = I$; if ITYPE = 3, $Z^H*inv(B)*Z = I$. If JOBZ = 'N', then on exit the upper triangle (if UPLO='U') or the lower triangle (if UPLO='L') of A, including the diagonal, is destroyed.

LDA (input)
 The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)
 On entry, the Hermitian positive definite matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if INFO \leq N, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*H^*U$ or $B = L^*L^*H$.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

W (output)
 If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The length of the array WORK. LDWORK \geq max(1,2*N-1). For optimal efficiency, LDWORK \geq (NB+1)*N, where NB is the blocksize for CHETRD returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
 dimension(max(1,3*N-2))

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: CPOTRF or CHEEV returned an error code:
 \leq N: if INFO = i, CHEEV failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; $>$ N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

chegvd - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE CHEGVD(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                 LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER ITYPE, N, LDA, LDB, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHEGVD_64(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                   LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 ITYPE, N, LDA, LDB, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HEGVD(ITYPE, JOBZ, UPLO, [N], A, [LDA], B, [LDB], W, [WORK],  
                [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER :: ITYPE, N, LDA, LDB, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HEGVD_64(ITYPE, JOBZ, UPLO, [N], A, [LDA], B, [LDB], W,  
                   [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER(8) :: ITYPE, N, LDA, LDB, LWORK, LRWORK, LIWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void chegvd(int itype, char jobz, char uplo, int n, complex
    *a, int lda, complex *b, int ldb, float *w, int
    *info);

void chegvd_64(long itype, char jobz, char uplo, long n,
    complex *a, long lda, complex *b, long ldb, float
    *w, long *info);

```

PURPOSE

chegvd computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)*B*x$
- = 2: $A*B*x = (\lambda)*x$
- = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

- = 'U': Upper triangles of A and B are stored;
- = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U',

the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.

On exit, if JOBZ = 'V', then if INFO = 0, A contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^*H*B*Z = I$; if ITYPE = 3, $Z^*H*inv(B)*Z = I$. If JOBZ = 'N', then on exit the upper triangle (if UPLO='U') or the lower triangle (if UPLO='L') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)

On entry, the Hermitian matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if INFO \leq N, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*H*U$ or $B = L*L^*H$.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

W (output)

If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The length of the array WORK. If N \leq 1, LWORK \geq 1. If JOBZ = 'N' and N > 1, LWORK \geq N + 1. If JOBZ = 'V' and N > 1, LWORK \geq 2*N + N**2.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)

The dimension of the array RWORK. If N \leq 1, LRWORK \geq 1. If JOBZ = 'N' and N > 1, LRWORK \geq

N. If JOBZ = 'V' and $N > 1$, LRWORK $\geq 1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If $N \leq 1$, LIWORK ≥ 1 . If JOBZ = 'N' and $N > 1$, LIWORK ≥ 1 . If JOBZ = 'V' and $N > 1$, LIWORK $\geq 3 + 5*N$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: CPOTRF or CHEEVD returned an error code:
<= N: if INFO = i, CHEEVD failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

chegvx - compute selected eigenvalues, and optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*Bx=(\lambda)x$, or $B*A*x=(\lambda)x$

SYNOPSIS

```
SUBROUTINE CHEGVX(ITYPE, JOBZ, RANGE, UPLO, N, A, LDA, B, LDB, VL,
                 VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, LWORK, RWORK, IWORK,
                 IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(LDA,*), B(LDB,*), Z(LDZ,*), WORK(*)
INTEGER ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHEGVX_64(ITYPE, JOBZ, RANGE, UPLO, N, A, LDA, B, LDB, VL,
                   VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, LWORK, RWORK, IWORK,
                   IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(LDA,*), B(LDB,*), Z(LDZ,*), WORK(*)
INTEGER*8 ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER*8 IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HEGVX(ITYPE, JOBZ, RANGE, UPLO, [N], A, [LDA], B, [LDB],
                VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [LWORK], [RWORK],
                [IWORK], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B, Z
INTEGER :: ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
```

```

INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, RWORK

SUBROUTINE HEGVX_64(ITYPE, JOBZ, RANGE, UPLO, [N], A, [LDA], B, [LDB],
    VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [LWORK], [RWORK],
    [IWORK], IFAIL, [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B, Z
INTEGER(8) :: ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void chegvx(int itype, char jobz, char range, char uplo, int
    n, complex *a, int lda, complex *b, int ldb, float
    vl, float vu, int il, int iu, float abstol, int
    *m, float *w, complex *z, int ldz, int *ifail, int
    *info);

void chegvx_64(long itype, char jobz, char range, char uplo,
    long n, complex *a, long lda, complex *b, long
    ldb, float vl, float vu, long il, long iu, float
    abstol, long *m, float *w, complex *z, long ldz,
    long *ifail, long *info);

```

PURPOSE

chegvx computes selected eigenvalues, and optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*B*x=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian and B is also positive definite. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

ITYPE (input)
 Specifies the problem type to be solved:
 = 1: $A*x = (\lambda)*B*x$
 = 2: $A*B*x = (\lambda)*x$
 = 3: $B*A*x = (\lambda)*x$

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found.

= 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)

= 'U': Upper triangles of A and B are stored;
= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.

On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)

On entry, the Hermitian matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if INFO $\leq N$, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*H^*U$ or $B = L^*L^*H$.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of

the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if $RANGE = 'A'$ or $'V'$.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If $ABSTOL$ is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when $ABSTOL$ is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting $ABSTOL$ to $2*SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If $RANGE = 'A'$, $M = N$, and if $RANGE = 'I'$, $M = IU - IL + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (output)

If $JOBZ = 'N'$, then Z is not referenced. If $JOBZ = 'V'$, then if $INFO = 0$, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i -th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized as follows: if $ITYPE = 1$ or 2 , $Z^T B Z = I$; if $ITYPE = 3$, $Z^T \text{inv}(B) Z = I$.

If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in $IFAIL$. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z ; if $RANGE = 'V'$, the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z . $LDZ \geq 1$, and if $JOBZ = 'V'$, $LDZ \geq \max(1, N)$.

WORK (workspace/output)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LWORK$.

LWORK (input)

The length of the array WORK. LWORK \geq $\max(1, 2*N-1)$. For optimal efficiency, LWORK \geq $(NB+1)*N$, where NB is the blocksize for CHETRD returned by ILAENV.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
dimension(7*N)

IWORK (workspace)
dimension(5*N)

IFAIL (output)
If JOBZ = 'V', then if INFO = 0, the first M elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: CPOTRF or CHEEVX returned an error code:
<= N: if INFO = i, CHEEVX failed to converge; i eigenvectors failed to converge. Their indices are stored in array IFAIL. > N: if INFO = N + i, for 1 <= i <= N, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

chemm - perform one of the matrix-matrix operations $C := \alpha A * B + \beta C$ or $C := \alpha B * A + \beta C$

SYNOPSIS

```
SUBROUTINE CHEMM(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                LDC)
```

```
CHARACTER * 1 SIDE, UPLO
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER M, N, LDA, LDB, LDC
```

```
SUBROUTINE CHEMM_64(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                   LDC)
```

```
CHARACTER * 1 SIDE, UPLO
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 M, N, LDA, LDB, LDC
```

F95 INTERFACE

```
SUBROUTINE HEMM(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
               BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:, :) :: A, B, C
INTEGER :: M, N, LDA, LDB, LDC
```

```
SUBROUTINE HEMM_64(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
                  BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:, :) :: A, B, C
INTEGER(8) :: M, N, LDA, LDB, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chemm(char side, char uplo, int m, int n, complex
           *alpha, complex *a, int lda, complex *b, int ldb,
           complex *beta, complex *c, int ldc);
```

```
void chemm_64(char side, char uplo, long m, long n, complex
              *alpha, complex *a, long lda, complex *b, long
              ldb, complex *beta, complex *c, long ldc);
```

PURPOSE

chemm performs one of the matrix-matrix operations $C := \alpha A^*B + \beta C$ or $C := \alpha B^*A + \beta C$ where alpha and beta are scalars, A is an hermitian matrix and B and C are m by n matrices.

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether the hermitian matrix A appears on the left or right in the operation as follows:

SIDE = 'L' or 'l' $C := \alpha A^*B + \beta C$,

SIDE = 'R' or 'r' $C := \alpha B^*A + \beta C$,

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the hermitian matrix A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of the hermitian matrix is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of the hermitian matrix is to be referenced.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of the matrix C. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix C. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

COMPLEX array of DIMENSION (LDA, ka), where ka is m when SIDE = 'L' or 'l' and is n other-

wise.

Before entry with `SIDE = 'L' or 'l'`, the `m` by `m` part of the array `A` must contain the hermitian matrix, such that when `UPLO = 'U' or 'u'`, the leading `m` by `m` upper triangular part of the array `A` must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of `A` is not referenced, and when `UPLO = 'L' or 'l'`, the leading `m` by `m` lower triangular part of the array `A` must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of `A` is not referenced.

Before entry with `SIDE = 'R' or 'r'`, the `n` by `n` part of the array `A` must contain the hermitian matrix, such that when `UPLO = 'U' or 'u'`, the leading `n` by `n` upper triangular part of the array `A` must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of `A` is not referenced, and when `UPLO = 'L' or 'l'`, the leading `n` by `n` lower triangular part of the array `A` must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of `A` is not referenced.

Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of `A` as declared in the calling (sub) program. When `SIDE = 'L' or 'l'` then `LDA >= max(1, m)`, otherwise `LDA >= max(1, n)`. Unchanged on exit.

B (input)

COMPLEX array of DIMENSION (`LDB, n`). Before entry, the leading `m` by `n` part of the array `B` must contain the matrix `B`. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of `B` as declared in the calling (sub) program. LDB must be at least `max(1, m)`. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then `C` need not be set on input. Unchanged on exit.

C (input/output)

COMPLEX array of DIMENSION (`LDC, n`).

Before entry, the leading `m` by `n` part of the array `C` must contain the matrix `C`, except when beta is zero, in which case `C` need not be set on entry.

On exit, the array C is overwritten by the m by n updated matrix.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. LDC must be at least $\max(1, m)$. Unchanged on exit.

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NAME

chemv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE CHEMV(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA, BETA  
COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER N, LDA, INCX, INCY
```

```
SUBROUTINE CHEMV_64(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA, BETA  
COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER*8 N, LDA, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE HEMV(UPLO, [N], ALPHA, A, [LDA], X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INCX, INCY
```

```
SUBROUTINE HEMV_64(UPLO, [N], ALPHA, A, [LDA], X, [INCX], BETA, Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chemv(char uplo, int n, complex *alpha, complex *a, int
          lda, complex *x, int incx, complex *beta, complex
          *y, int incy);
```

```
void chemv_64(char uplo, long n, complex *alpha, complex *a,
              long lda, complex *x, long incx, complex *beta,
              complex *y, long incy);
```

PURPOSE

chemv performs the matrix-vector operation $y := \alpha A x + \beta y$ where α and β are scalars, x and y are n element vectors and A is an n by n hermitian matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of A is not referenced. Note that the imaginary parts of the diagonal elements need not be set and are assumed to be zero. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)). Before entry, the incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX <> 0. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

cher - perform the hermitian rank 1 operation $A := \alpha * x * \text{conjg}(x') + A$

SYNOPSIS

```
SUBROUTINE CHER(UPLO, N, ALPHA, X, INCX, A, LDA)
```

```
CHARACTER * 1 UPLO  
COMPLEX X(*), A(LDA,*)  
INTEGER N, INCX, LDA  
REAL ALPHA
```

```
SUBROUTINE CHER_64(UPLO, N, ALPHA, X, INCX, A, LDA)
```

```
CHARACTER * 1 UPLO  
COMPLEX X(*), A(LDA,*)  
INTEGER*8 N, INCX, LDA  
REAL ALPHA
```

F95 INTERFACE

```
SUBROUTINE HER(UPLO, [N], ALPHA, X, [INCX], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: X  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, INCX, LDA  
REAL :: ALPHA
```

```
SUBROUTINE HER_64(UPLO, [N], ALPHA, X, [INCX], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: X  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, INCX, LDA  
REAL :: ALPHA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cher(char uplo, int n, float alpha, complex *x, int
```

```

        incx, complex *a, int lda);

void cher_64(char uplo, long n, float alpha, complex *x,
            long incx, complex *a, long lda);

```

PURPOSE

cher performs the hermitian rank 1 operation $A := \alpha x \text{conjg}(x') + A$ where alpha is a real scalar, x is an n element vector and A is an n by n hermitian matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

A (input/output)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of A is not referenced. On exit, the upper triangular part of the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of A is not referenced. On exit, the lower triangular part of

the array A is overwritten by the lower triangular part of the updated matrix. Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

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NAME

cher2 - perform the hermitian rank 2 operation $A := \alpha * x * \text{conjg}(y') + \text{conjg}(\alpha) * y * \text{conjg}(x') + A$

SYNOPSIS

```
SUBROUTINE CHER2(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA  
COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER N, INCX, INCY, LDA
```

```
SUBROUTINE CHER2_64(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA  
COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER*8 N, INCX, INCY, LDA
```

F95 INTERFACE

```
SUBROUTINE HER2(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, INCX, INCY, LDA
```

```
SUBROUTINE HER2_64(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, INCX, INCY, LDA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cher2(char uplo, int n, complex *alpha, complex *x, int
```

```

        incx, complex *y, int incy, complex *a, int lda);

void cher2_64(char uplo, long n, complex *alpha, complex *x,
             long incx, complex *y, long incy, complex *a, long
             lda);

```

PURPOSE

cher2 performs the hermitian rank 2 operation $A := \alpha x \text{conjg}(y') + \text{conjg}(\alpha) y \text{conjg}(x') + A$ where α is a scalar, x and y are n element vectors and A is an n by n hermitian matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

A (input/output)

Before entry with UPLO = 'U' or 'u', the leading

n by n upper triangular part of the array A must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of A is not referenced. On exit, the upper triangular part of the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of A is not referenced. On exit, the lower triangular part of the array A is overwritten by the lower triangular part of the updated matrix. Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

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NAME

cher2k - perform one of the Hermitian rank 2k operations $C := \alpha A \text{conjg}(B') + \text{conjg}(\alpha) B \text{conjg}(A') + \beta C$ or $C := \alpha \text{conjg}(A') B + \text{conjg}(\alpha) \text{conjg}(B') A + \beta C$

SYNOPSIS

```
SUBROUTINE CHER2K(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA, C,
                 LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
COMPLEX ALPHA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER N, K, LDA, LDB, LDC
REAL BETA
```

```
SUBROUTINE CHER2K_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA,
                    C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
COMPLEX ALPHA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 N, K, LDA, LDB, LDC
REAL BETA
```

F95 INTERFACE

```
SUBROUTINE HER2K(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B, [LDB],
                BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
COMPLEX :: ALPHA
COMPLEX, DIMENSION(:, :) :: A, B, C
INTEGER :: N, K, LDA, LDB, LDC
REAL :: BETA
```

```
SUBROUTINE HER2K_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B,
                   [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
COMPLEX :: ALPHA
```

```
COMPLEX, DIMENSION(:,:) :: A, B, C
INTEGER(8) :: N, K, LDA, LDB, LDC
REAL :: BETA
```

C INTERFACE

```
#include <sunperf.h>
void cher2k(char uplo, char transa, int n, int k, complex*
    alpha, complex *a, int lda, complex *b, int ldb,
    float beta, complex *c, int ldc);

void cher2k_64(char uplo, char transa, long n, long k, com-
    plex *alpha, complex *a, long lda, complex *b,
    long ldb, float beta, complex *c, long ldc);
```

PURPOSE

cher2k performs one of the Hermitian rank 2k operations $C := \alpha A \text{conjg}(B') + \text{conjg}(\alpha) B \text{conjg}(A') + \beta C$ or $C := \alpha \text{conjg}(A') B + \text{conjg}(\alpha) \text{conjg}(B') A + \beta C$ where α and β are scalars with β real, C is an n by n Hermitian matrix and A and B are n by k matrices in the first case and k by n matrices in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A \text{conjg}(B') + \text{conjg}(\alpha) B \text{conjg}(A') + \beta C$.

TRANSA = 'C' or 'c' $C := \alpha \text{conjg}(A') B + \text{conjg}(\alpha) \text{conjg}(B') A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C. N must be at least zero. Unchanged on exit.

K (input)
On entry with `TRANSA = 'N' or 'n'`, K specifies the number of columns of the matrices A and B, and on entry with `TRANSA = 'C' or 'c'`, K specifies the number of rows of the matrices A and B. K must be at least zero. Unchanged on exit.

ALPHA (input)
On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)
COMPLEX array of DIMENSION (LDA, ka), where ka is k when `TRANSA = 'N' or 'n'`, and is n otherwise. Before entry with `TRANSA = 'N' or 'n'`, the leading n by k part of the array A must contain the matrix A, otherwise the leading k by n part of the array A must contain the matrix A. Unchanged on exit.

LDA (input)
On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When `TRANSA = 'N' or 'n'` then LDA must be at least $\max(1, n)$, otherwise LDA must be at least $\max(1, k)$. Unchanged on exit.

B (input)
COMPLEX array of DIMENSION (LDB, kb), where kb is k when `TRANSA = 'N' or 'n'`, and is n otherwise. Before entry with `TRANSA = 'N' or 'n'`, the leading n by k part of the array B must contain the matrix B, otherwise the leading k by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)
On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. When `TRANSA = 'N' or 'n'` then LDB must be at least $\max(1, n)$, otherwise LDB must be at least $\max(1, k)$. Unchanged on exit.

BETA (input)
On entry, BETA specifies the scalar beta. Unchanged on exit.

C (input/output)
COMPLEX array of DIMENSION (LDC, n).

Before entry with `UPLO = 'U' or 'u'`, the leading n by n upper triangular part of the array C must contain the upper triangular part of the Hermitian matrix and the strictly lower triangular part of C is not referenced. On exit, the upper triangular part of the array C is overwritten by the upper triangular part of the updated matrix.

Before entry with `UPLO = 'L' or 'l'`, the lead-

ing n by n lower triangular part of the array C must contain the lower triangular part of the Hermitian matrix and the strictly upper triangular part of C is not referenced. On exit, the lower triangular part of the array C is overwritten by the lower triangular part of the updated matrix.

Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. LDC must be at least $\max(1, n)$. Unchanged on exit.

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NAME

cherfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CHERFS(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CHERFS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,  
  X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HERFS(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT, B,  
  [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE HERFS_64(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT,  
  B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: FERR, BERR, WORK2
C INTERFACE
#include <sunperf.h>

void cherfs(char uplo, int n, int nrhs, complex *a, int lda,
            complex *af, int ldaf, int *ipivot, complex *b,
            int ldb, complex *x, int ldx, float *ferr, float
            *berr, int *info);

void cherfs_64(char uplo, long n, long nrhs, complex *a,
              long lda, complex *af, long ldaf, long *ipivot,
              complex *b, long ldb, complex *x, long ldx, float
              *ferr, float *berr, long *info);

```

PURPOSE

cherfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)
 The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^*H$ or $A = L*D*L^*H$ as computed by CHETRF.

LDAF (input)
 The leading dimension of the array AF. LDAF \geq max(1,N).

IPIVOT (input)
 Details of the interchanges and the block structure of D as determined by CHETRF.

B (input) The right hand side matrix B.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
 On entry, the solution matrix X, as computed by CHETRS. On exit, the improved solution matrix X.

LDX (input)
 The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(2*N)

WORK2 (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cherk - perform one of the Hermitian rank k operations C
:= alpha*A*conjg(A') + beta*C or C := alpha*conjg(A')*A
+ beta*C

SYNOPSIS

```
SUBROUTINE CHERK(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
COMPLEX A(LDA,*), C(LDC,*)  
INTEGER N, K, LDA, LDC  
REAL ALPHA, BETA
```

```
SUBROUTINE CHERK_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
COMPLEX A(LDA,*), C(LDC,*)  
INTEGER*8 N, K, LDA, LDC  
REAL ALPHA, BETA
```

F95 INTERFACE

```
SUBROUTINE HERK(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA, C,  
[LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
COMPLEX, DIMENSION(:,:) :: A, C  
INTEGER :: N, K, LDA, LDC  
REAL :: ALPHA, BETA
```

```
SUBROUTINE HERK_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA,  
C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
COMPLEX, DIMENSION(:,:) :: A, C  
INTEGER(8) :: N, K, LDA, LDC  
REAL :: ALPHA, BETA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cherk(char uplo, char transa, int n, int k, float
           alpha, complex *a, int lda, float beta, complex
           *c, int ldc);
```

```
void cherk_64(char uplo, char transa, long n, long k, float
              alpha, complex *a, long lda, float beta, complex
              *c, long ldc);
```

PURPOSE

cherk performs one of the Hermitian rank k operations $C := \alpha A \text{conjg}(A') + \beta C$ or $C := \alpha \text{conjg}(A') A + \beta C$ where α and β are real scalars, C is an n by n Hermitian matrix and A is an n by k matrix in the first case and a k by n matrix in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A \text{conjg}(A') + \beta C$.

TRANSA = 'C' or 'c' $C := \alpha \text{conjg}(A') A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrix A , and on entry with TRANSA = 'C' or 'c', K specifies the number of rows of the matrix A . K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

A (input)

COMPLEX array of DIMENSION (LDA, ka),
where ka is k when TRANSA = 'N' or 'n', and is
n otherwise. Before entry with TRANSA = 'N' or
'n', the leading n by k part of the array A
must contain the matrix A, otherwise the leading
k by n part of the array A must contain the
matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A
as declared in the calling (sub) program.
When TRANSA = 'N' or 'n' then LDA must be at
least $\max(1, n)$, otherwise LDA must be at
least $\max(1, k)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta.
Unchanged on exit.

C (input/output)

COMPLEX array of DIMENSION (LDC, n).

Before entry with UPLO = 'U' or 'u', the lead-
ing n by n upper triangular part of the array C
must contain the upper triangular part of the
Hermitian matrix and the strictly lower triangu-
lar part of C is not referenced. On exit, the
upper triangular part of the array C is overwrit-
ten by the upper triangular part of the updated
matrix.

Before entry with UPLO = 'L' or 'l', the lead-
ing n by n lower triangular part of the array C
must contain the lower triangular part of the
Hermitian matrix and the strictly upper triangu-
lar part of C is not referenced. On exit, the
lower triangular part of the array C is overwrit-
ten by the lower triangular part of the updated
matrix.

Note that the imaginary parts of the diagonal ele-
ments need not be set, they are assumed to be
zero, and on exit they are set to zero.

LDC (input)

On entry, LDC specifies the first dimension of C
as declared in the calling (sub) program.
LDC must be at least $\max(1, n)$. Unchanged
on exit.

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NAME

chesv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CHESV(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK, LDWORK,
                INFO)
```

```
CHARACTER * 1 UPLO
COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER N, NRHS, LDA, LDB, LDWORK, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE CHESV_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK,
                  LDWORK, INFO)
```

```
CHARACTER * 1 UPLO
COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER*8 N, NRHS, LDA, LDB, LDWORK, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HESV(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],
               [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER :: N, NRHS, LDA, LDB, LDWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HESV_64(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],
                  [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER(8) :: N, NRHS, LDA, LDB, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void chesv(char uplo, int n, int nrhs, complex *a, int lda,
           int *ipivot, complex *b, int ldb, int *info);
void chesv_64(char uplo, long n, long nrhs, complex *a, long
              lda, long *ipivot, complex *b, long ldb, long
              *info);
```

PURPOSE

chesv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N Hermitian matrix and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{**H}$, if UPLO = 'U', or

$A = L * D * L^{**H}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U * D * U^{**H}$ or $A = L * D * L^{**H}$ as computed by CHETRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D , as determined by CHETRF. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B .
On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LDWORK$.

LDWORK (input)

The length of $WORK$. $LDWORK \geq 1$, and for best performance $LDWORK \geq N \cdot NB$, where NB is the optimal blocksize for CHETRF.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $WORK$ array, returns this value as the first entry of the $WORK$ array, and no error message related to $LDWORK$ is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

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NAME

chesvx - use the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CHESVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,
  LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER IPIVOT(*)
REAL RCOND
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CHESVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
  B, LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER*8 IPIVOT(*)
REAL RCOND
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HESVX(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],
  IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK],
  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE HESVX_64(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],
```

```
IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, AF, B, X  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL :: RCOND  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chesvx(char fact, char uplo, int n, int nrhs, complex  
*a, int lda, complex *af, int ldaf, int *ipivot,  
complex *b, int ldb, complex *x, int ldx, float  
*rcond, float *ferr, float *berr, int *info);
```

```
void chesvx_64(char fact, char uplo, long n, long nrhs, com-  
plex *a, long lda, complex *af, long ldaf, long  
*ipivot, complex *b, long ldb, complex *x, long  
ldx, float *rcond, float *ferr, float *berr, long  
*info);
```

PURPOSE

chesvx uses the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$, where A is an N -by- N Hermitian matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the diagonal pivoting method is used to factor A .

The form of the factorization is

$A = U * D * U^{*H}$, if $UPLO = 'U'$, or

$A = L * D * L^{*H}$, if $UPLO = 'L'$,

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices, and D is Hermitian and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than machine precision,

$INFO = N+1$ is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described

below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. A, AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^*H$ or $A = L*D*L^*H$ as computed by CHETRF.

If FACT = 'N', then AF is an output argument and on exit returns the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^*H$ or $A = L*D*L^*H$.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq$

max(1,N).

IPIVOT (input or output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by CHETRF. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

If FACT = 'N', then IPIVOT is an output argument and on exit contains details of the interchanges and the block structure of D, as determined by CHETRF.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)

The leading dimension of the array X. LDX >= max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of WORK. LDWORK $\geq 2*N$, and for best performance LDWORK $\geq N*NB$, where NB is the optimal blocksize for CHETRF.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned.
= N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

chetf2 - compute the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE CHETF2(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE CHETF2_64(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE HETF2(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE HETF2_64(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chetf2(char uplo, int n, complex *a, int lda, int
```

```

        *ipiv, int *info);

void chetf2_64(char uplo, long n, complex *a, long lda, long
        *ipiv, long *info);

```

PURPOSE

chetf2 computes the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U' \quad \text{or} \quad A = L^*D^*L'$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, U' is the conjugate transpose of U, and D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the Hermitian matrix A is stored:

= 'U': Upper triangular
 = 'L': Lower triangular

N (input) The order of the matrix A. N >= 0.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading n-by-n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n-by-n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. LDA >= max(1,N).

IPIV (output)

Details of the interchanges and the block structure of D. If IPIV(k) > 0, then rows and columns k and IPIV(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIV(k) = IPIV(k-1) < 0, then rows and columns k-1 and -IPIV(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIV(k) = IPIV(k+1) < 0, then rows and columns k+1 and

-IPIV(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

INFO (output)

= 0: successful exit
 < 0: if INFO = -k, the k-th argument had an illegal value
 > 0: if INFO = k, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

1-96 - Based on modifications by

J. Lewis, Boeing Computer Services Company

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

chetrd - reduce a complex Hermitian matrix A to real symmetric tridiagonal form T by a unitary similarity transformation

SYNOPSIS

```
SUBROUTINE CHETRD(UPLO, N, A, LDA, D, E, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER N, LDA, LWORK, INFO  
REAL D(*), E(*)
```

```
SUBROUTINE CHETRD_64(UPLO, N, A, LDA, D, E, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 N, LDA, LWORK, INFO  
REAL D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE HETRD(UPLO, [N], A, [LDA], D, E, TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: D, E
```

```
SUBROUTINE HETRD_64(UPLO, [N], A, [LDA], D, E, TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>

void chetrd(char uplo, int n, complex *a, int lda, float *d,
            float *e, complex *tau, int *info);

void chetrd_64(char uplo, long n, complex *a, long lda,
               float *d, float *e, complex *tau, long *info);
```

PURPOSE

chetrd reduces a complex Hermitian matrix A to real symmetric tridiagonal form T by a unitary similarity transformation: $Q^*H * A * Q = T$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

D (output)

The diagonal elements of the tridiagonal matrix T:
 $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i, i+1)$ if UPLO = 'U', $E(i) =$

A(i+1,i) if UPLO = 'L'.

TAU (output)
The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. LWORK >= 1. For optimum performance LWORK >= N*N, where N is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with v(i+1:n) = 0 and v(i) = 1; v(1:i-1) is stored on exit in A(1:i-1,i+1), and tau in TAU(i).

If UPLO = 'L', the matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with v(1:i) = 0 and v(i+1) = 1; v(i+2:n) is stored on exit in A(i+2:n,i), and tau in TAU(i).

The contents of A on exit are illustrated by the following examples with n = 5:

if UPLO = 'U': (d e v2 v3 v4)	if UPLO = 'L': (d
--	------------------------------

$$\begin{array}{l}
) \\
 (\quad d \quad e \quad v_3 \quad v_4 \quad) \quad \quad \quad (\quad e \quad d \\
) \\
 (\quad \quad d \quad e \quad v_4 \quad) \quad \quad \quad (\quad v_1 \quad e \quad d \\
) \\
 (\quad \quad \quad d \quad e \quad) \quad \quad \quad (\quad v_1 \quad v_2 \quad e \quad d \\
) \\
 (\quad \quad \quad \quad d \quad) \quad \quad \quad (\quad v_1 \quad v_2 \quad v_3 \quad e \quad d \\
)
 \end{array}$$

where d and e denote diagonal and off-diagonal elements of T , and v_i denotes an element of the vector defining $H(i)$.

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NAME

chetrf - compute the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE CHETRF(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, LDWORK, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CHETRF_64(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, LDWORK, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HETRF(UPLO, [N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HETRF_64(UPLO, [N], A, [LDA], IPIVOT, [WORK], [LDWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void chetrf(char uplo, int n, complex *a, int lda, int
            *ipivot, int *info);

void chetrf_64(char uplo, long n, complex *a, long lda, long
               *ipivot, long *info);
```

PURPOSE

chetrf computes the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method. The form of the factorization is

$$A = U*D*U**H \quad \text{or} \quad A = L*D*L**H$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. N >= 0.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. LDA >= max(1,N).

IPIVOT (output)

Details of the interchanges and the block structure of D. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and

$D(k-1:k, k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1, k:k+1)$ is a 2-by-2 diagonal block.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LDWORK$.

LDWORK (input)

The length of WORK. $LDWORK \geq 1$. For best performance $LDWORK \geq N * NB$, where NB is the block size returned by $ILAENV$.

INFO (output)

= 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value
 > 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

If $UPLO = 'U'$, then $A = U * D * U'$, where

$U = P(n) * U(n) * \dots * P(k) * U(k) * \dots$,
 i.e., U is a product of terms $P(k) * U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by $IPIVOT(k)$, and $U(k)$ is a unit upper triangular matrix, such that if the diagonal block $D(k)$ is of order s ($s = 1$ or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(1:k-1, k)$. If $s = 2$, the upper triangle of $D(k)$ overwrites $A(k-1, k-1)$, $A(k-1, k)$, and $A(k, k)$, and v overwrites $A(1:k-2, k-1:k)$.

If $UPLO = 'L'$, then $A = L * D * L'$, where

$L = P(1) * L(1) * \dots * P(k) * L(k) * \dots$,
 i.e., L is a product of terms $P(k) * L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by $IPIVOT(k)$, and $L(k)$ is a unit lower triangular matrix, such that if the diagonal block $D(k)$ is of order s ($s = 1$ or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(k+1:n,k)$. If $s = 2$, the lower triangle of $D(k)$ overwrites $A(k,k)$, $A(k+1,k)$, and $A(k+1,k+1)$, and v overwrites $A(k+2:n,k:k+1)$.

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NAME

chetri - compute the inverse of a complex Hermitian indefinite matrix A using the factorization $A = U^*D^*U^*H$ or $A = L^*D^*L^*H$ computed by CHETRF

SYNOPSIS

```
SUBROUTINE CHETRI(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CHETRI_64(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HETRI(UPLO, [N], A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HETRI_64(UPLO, [N], A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void chetri(char uplo, int n, complex *a, int lda, int
            *ipivot, int *info);

void chetri_64(char uplo, long n, complex *a, long lda, long
               *ipivot, long *info);

```

PURPOSE

chetri computes the inverse of a complex Hermitian indefinite matrix A using the factorization $A = U*D*U**H$ or $A = L*D*L**H$ computed by CHETRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U*D*U**H$;
 = 'L': Lower triangular, form is $A = L*D*L**H$.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CHETRF.

On exit, if INFO = 0, the (Hermitian) inverse of the original matrix. If UPLO = 'U', the upper triangular part of the inverse is formed and the part of A below the diagonal is not referenced; if UPLO = 'L' the lower triangular part of the inverse is formed and the part of A above the diagonal is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by CHETRF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

chetrs - solve a system of linear equations $A \cdot X = B$ with a complex Hermitian matrix A using the factorization $A = U \cdot D \cdot U^* \cdot H$ or $A = L \cdot D \cdot L^* \cdot H$ computed by CHETRF

SYNOPSIS

```
SUBROUTINE CHETRS(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CHETRS_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HETRS(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HETRS_64(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chetrs(char uplo, int n, int nrhs, complex *a, int lda,
```

```

        int *ipivot, complex *b, int ldb, int *info);

void chetrs_64(char uplo, long n, long nrhs, complex *a,
              long lda, long *ipivot, complex *b, long ldb, long
              *info);

```

PURPOSE

chetrs solves a system of linear equations $A \cdot X = B$ with a complex Hermitian matrix A using the factorization $A = U \cdot D \cdot U^* \cdot H$ or $A = L \cdot D \cdot L^* \cdot H$ computed by CHETRF.

ARGUMENTS

UPLO (input)
 Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U \cdot D \cdot U^* \cdot H$;
 = 'L': Lower triangular, form is $A = L \cdot D \cdot L^* \cdot H$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CHETRF.

LDA (input)
 The leading dimension of the array A . $LDA \geq \max(1, N)$.

IPIVOT (input)
 Details of the interchanges and the block structure of D as determined by CHETRF.

B (input/output)
 On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)
 The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)
 = 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

chgeqz - implement a single-shift version of the QZ method for finding the generalized eigenvalues $w(i)=\text{ALPHA}(i)/\text{BETA}(i)$ of the equation $\det(A-w(i)B) = 0$. If `JOB='S'`, then the pair (A,B) is simultaneously reduced to Schur form (i.e., A and B are both upper triangular) by applying one unitary transformation (usually called Q) on the left and another (usually called Z) on the right.

SYNOPSIS

```
SUBROUTINE CHGEQZ(JOB, COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB,
                 ALPHA, BETA, Q, LDQ, Z, LDZ, WORK, LWORK, RWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ, COMPZ
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), Q(LDQ,*),
Z(LDZ,*), WORK(*)
INTEGER N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL RWORK(*)
```

```
SUBROUTINE CHGEQZ_64(JOB, COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB,
                   ALPHA, BETA, Q, LDQ, Z, LDZ, WORK, LWORK, RWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ, COMPZ
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), Q(LDQ,*),
Z(LDZ,*), WORK(*)
INTEGER*8 N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HGEQZ(JOB, COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB],
                ALPHA, BETA, Q, [LDQ], Z, [LDZ], [WORK], [LWORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ, COMPZ
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:, :) :: A, B, Q, Z
INTEGER :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL, DIMENSION(:) :: RWORK
```

```

SUBROUTINE HGEQZ_64(JOB, COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B,
  [LDB], ALPHA, BETA, Q, [LDQ], Z, [LDZ], [WORK], [LWORK], [RWORK],
  [INFO])

```

```

CHARACTER(LEN=1) :: JOB, COMPQ, COMPZ
COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:, :) :: A, B, Q, Z
INTEGER(8) :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL, DIMENSION(:) :: RWORK

```

C INTERFACE

```
#include <sunperf.h>
```

```

void chgeqz(char job, char compq, char compz, int n, int
  ilo, int ihi, complex *a, int lda, complex *b, int
  ldb, complex *alpha, complex *beta, complex *q,
  int ldq, complex *z, int ldz, int *info);

```

```

void chgeqz_64(char job, char compq, char compz, long n,
  long ilo, long ihi, complex *a, long lda, complex
  *b, long ldb, complex *alpha, complex *beta, com-
  plex *q, long ldq, complex *z, long ldz, long
  *info);

```

PURPOSE

chgeqz implements a single-shift version of the QZ method for finding the generalized eigenvalues $w(i)=\text{ALPHA}(i)/\text{BETA}(i)$ of the equation A are then $\text{ALPHA}(1), \dots, \text{ALPHA}(N)$, and of B are $\text{BETA}(1), \dots, \text{BETA}(N)$.

If $\text{JOB}='S'$ and COMPQ and COMPZ are 'V' or 'I', then the unitary transformations used to reduce (A,B) are accumulated into the arrays Q and Z s.t.:

$(\text{in}) A(\text{in}) Z(\text{in})^* = Q(\text{out}) A(\text{out}) Z(\text{out})^*$

Ref: C.B. Moler & G.W. Stewart, "An Algorithm for Generalized Matrixigenvalue Problems", SIAM J. Numer. Anal., 10(1973), p. 241--256.

ARGUMENTS

JOB (input)

= 'E': compute only ALPHA and BETA. A and B will not necessarily be put into generalized Schur form. = 'S': put A and B into generalized Schur form, as well as computing ALPHA and BETA.

COMPQ (input)

= 'N': do not modify Q .
 = 'V': multiply the array Q on the right by the conjugate transpose of the unitary transformation that is applied to the left side of A and B to reduce them to Schur form. = 'I': like $\text{COMPQ}='V'$, except that Q will be initialized to the identity first.

COMPZ (input)
 = 'N': do not modify Z.
 = 'V': multiply the array Z on the right by the unitary transformation that is applied to the right side of A and B to reduce them to Schur form. = 'I': like COMPZ='V', except that Z will be initialized to the identity first.

N (input) The order of the matrices A, B, Q, and Z. $N \geq 0$.

ILO (input)
 It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)
 It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

A (input) On entry, the N-by-N upper Hessenberg matrix A. Elements below the subdiagonal must be zero. If JOB='S', then on exit A and B will have been simultaneously reduced to upper triangular form. If JOB='E', then on exit A will have been destroyed.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input) On entry, the N-by-N upper triangular matrix B. Elements below the diagonal must be zero. If JOB='S', then on exit A and B will have been simultaneously reduced to upper triangular form. If JOB='E', then on exit B will have been destroyed.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, N)$.

ALPHA (output)
 The diagonal elements of A when the pair (A,B) has been reduced to Schur form. ALPHA(i)/BETA(i) $i=1, \dots, N$ are the generalized eigenvalues.

BETA (output)
 The diagonal elements of B when the pair (A,B) has been reduced to Schur form. ALPHA(i)/BETA(i) $i=1, \dots, N$ are the generalized eigenvalues. A and B are normalized so that BETA(1), ..., BETA(N) are non-negative real numbers.

Q (input/output)
 If COMPQ='N', then Q will not be referenced. If COMPQ='V' or 'I', then the conjugate transpose of the unitary transformations which are applied to A and B on the left will be applied to the array Q on the right.

LDQ (input)

The leading dimension of the array Q. LDQ \geq 1.
If COMPQ='V' or 'I', then LDQ \geq N.

Z (input/output)

If COMPZ='N', then Z will not be referenced. If COMPZ='V' or 'I', then the unitary transformations which are applied to A and B on the right will be applied to the array Z on the right.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1.
If COMPZ='V' or 'I', then LDZ \geq N.

WORK (workspace)

On exit, if INFO \geq 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,N).

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
= 1,...,N: the QZ iteration did not converge. (A,B) is not in Schur form, but ALPHA(i) and BETA(i), i=INFO+1,...,N should be correct.
= N+1,...,2*N: the shift calculation failed. (A,B) is not in Schur form, but ALPHA(i) and BETA(i), i=INFO-N+1,...,N should be correct.
> 2*N: various "impossible" errors.

FURTHER DETAILS

We assume that complex ABS works as long as its value is less than overflow.

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NAME

chpcon - estimate the reciprocal of the condition number of a complex Hermitian packed matrix A using the factorization $A = U^*D^*U^{**H}$ or $A = L^*D^*L^{**H}$ computed by CHPTRF

SYNOPSIS

```
SUBROUTINE CHPCON(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)  
REAL ANORM, RCOND
```

```
SUBROUTINE CHPCON_64(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
REAL ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE HPCON(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL :: ANORM, RCOND
```

```
SUBROUTINE HPCON_64(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>

void chpcon(char uplo, int n, complex *a, int *ipivot, float
            anorm, float *rcond, int *info);

void chpcon_64(char uplo, long n, complex *a, long *ipivot,
               float anorm, float *rcond, long *info);
```

PURPOSE

chpcon estimates the reciprocal of the condition number of a complex Hermitian packed matrix A using the factorization $A = U^*D*U^{**H}$ or $A = L^*D*L^{**H}$ computed by CHPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
 Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U^*D*U^{**H}$;
 = 'L': Lower triangular, form is $A = L^*D*L^{**H}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) COMPLEX array, dimension $(N*(N+1)/2)$
 The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CHPTRF, stored as a packed triangular matrix.

IPIVOT (input) (input) INTEGER array, dimension (N)
 Details of the interchanges and the block structure of D as determined by CHPTRF.

ANORM (input)
 The 1-norm of the original matrix A.

RCOND (output)
 The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)
 COMPLEX array, dimension $(2*N)$

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

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NAME

chpev - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix in packed storage

SYNOPSIS

```
SUBROUTINE CHPEV(JOBZ, UPLO, N, A, W, Z, LDZ, WORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(*), Z(LDZ,*), WORK(*)  
INTEGER N, LDZ, INFO  
REAL W(*), WORK2(*)
```

```
SUBROUTINE CHPEV_64(JOBZ, UPLO, N, A, W, Z, LDZ, WORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX A(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDZ, INFO  
REAL W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPEV(JOBZ, UPLO, [N], A, W, Z, [LDZ], [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
COMPLEX, DIMENSION(:, :) :: Z  
INTEGER :: N, LDZ, INFO  
REAL, DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HPEV_64(JOBZ, UPLO, [N], A, W, Z, [LDZ], [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
COMPLEX, DIMENSION(:, :) :: Z  
INTEGER(8) :: N, LDZ, INFO  
REAL, DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chpev(char jobz, char uplo, int n, complex *a, float
          *w, complex *z, int ldz, int *info);
```

```
void chpev_64(char jobz, char uplo, long n, complex *a,
             float *w, complex *z, long ldz, long *info);
```

PURPOSE

chpev computes all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix in packed storage.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$
On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, A is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

W (output) REAL array, dimension (N)
If INFO = 0, the eigenvalues in ascending order.

Z (input) COMPLEX array, dimension (LDZ, N)
If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with $W(i)$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)
The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace)
COMPLEX array, dimension $(\max(1, 2*N-1))$

WORK2 (workspace)

REAL array, dimension(max(1,3*N-2))

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

chpevd - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage

SYNOPSIS

```
SUBROUTINE CHPEVD(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, LWORK, RWORK,  
  LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AP(*), Z(LDZ,*), WORK(*)  
INTEGER N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHPEVD_64(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, LWORK,  
  RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AP(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HPEVD(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [LWORK],  
  [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: AP, WORK  
COMPLEX, DIMENSION(:, :) :: Z  
INTEGER :: N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HPEVD_64(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [LWORK],  
  [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: AP, WORK  
COMPLEX, DIMENSION(:, :) :: Z
```

```
INTEGER(8) :: N, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: W, RWORK
```

C INTERFACE

```
#include <sunperf.h>
void chpevd(char jobz, char uplo, int n, complex *ap, float
            *w, complex *z, int ldz, int *info);

void chpevd_64(char jobz, char uplo, long n, complex *ap,
              float *w, complex *z, long ldz, long *info);
```

PURPOSE

chpevd computes all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output) COMPLEX array, dimension $(N*(N+1)/2)$
On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, AP is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

W (output) REAL array, dimension (N)
If INFO = 0, the eigenvalues in ascending order.

Z (input) COMPLEX array, dimension (LDZ, N)
If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)
The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

WORK (workspace) COMPLEX array, dimension (LWORK)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of array WORK. If N <= 1, LWORK must be at least 1. If JOBZ = 'N' and N > 1, LWORK must be at least N. If JOBZ = 'V' and N > 1, LWORK must be at least 2*N.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
REAL array, dimension (LRWORK) On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)
The dimension of array RWORK. If N <= 1, LRWORK must be at least 1. If JOBZ = 'N' and N > 1, LRWORK must be at least N. If JOBZ = 'V' and N > 1, LRWORK must be at least 1 + 5*N + 2*N**2.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output) INTEGER array, dimension (LIWORK)
On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
The dimension of array IWORK. If JOBZ = 'N' or N <= 1, LIWORK must be at least 1. If JOBZ = 'V' and N > 1, LIWORK must be at least 3 + 5*N.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-

gal value.

> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

chpevx - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage

SYNOPSIS

```
SUBROUTINE CHPEVX(JOBZ, RANGE, UPLO, N, A, VL, VU, IL, IU, ABTOL,
                 NFOUND, W, Z, LDZ, WORK, WORK2, IWORK3, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(*), Z(LDZ,*), WORK(*)
INTEGER N, IL, IU, NFOUND, LDZ, INFO
INTEGER IWORK3(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL W(*), WORK2(*)
```

```
SUBROUTINE CHPEVX_64(JOBZ, RANGE, UPLO, N, A, VL, VU, IL, IU, ABTOL,
                   NFOUND, W, Z, LDZ, WORK, WORK2, IWORK3, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX A(*), Z(LDZ,*), WORK(*)
INTEGER*8 N, IL, IU, NFOUND, LDZ, INFO
INTEGER*8 IWORK3(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPEVX(JOBZ, RANGE, UPLO, [N], A, VL, VU, IL, IU, ABTOL,
                [NFOUND], W, Z, [LDZ], [WORK], [WORK2], [IWORK3], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: A, WORK
COMPLEX, DIMENSION(:, :) :: Z
INTEGER :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK3, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HPEVX_64(JOBZ, RANGE, UPLO, [N], A, VL, VU, IL, IU, ABTOL,
                   [NFOUND], W, Z, [LDZ], [WORK], [WORK2], [IWORK3], IFAIL, [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: A, WORK
COMPLEX, DIMENSION(:, :) :: Z
INTEGER(8) :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK3, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void chpevx(char jobz, char range, char uplo, int n, complex
            *a, float vl, float vu, int il, int iu, float
            abtol, int *nfound, float *w, complex *z, int ldz,
            int *ifail, int *info);

void chpevx_64(char jobz, char range, char uplo, long n,
               complex *a, float vl, float vu, long il, long iu,
               float abtol, long *nfound, float *w, complex *z,
               long ldz, long *ifail, long *info);

```

PURPOSE

chpevx computes selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage. Eigenvalues/vectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found;
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found; = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$
 On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.
 On exit, A is overwritten by values generated during the reduction to tridiagonal form. If UPLO =

'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2 * SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output) REAL array, dimension (N)

If $INFO = 0$, the selected eigenvalues in ascending

order.

Z (input) COMPLEX array, dimension (LDZ, max(1,M))
If JOBZ = 'V', then if INFO = 0, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least max(1,NFOUND) columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)
The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

WORK (workspace)
COMPLEX array, dimension(2*N)

WORK2 (workspace)
REAL array, dimension(7*N)

IWORK3 (workspace)
INTEGER array, dimension (5*N), dimension(5*N)

IFAIL (output)
If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

chpgst - reduce a complex Hermitian-definite generalized eigenproblem to standard form, using packed storage

SYNOPSIS

```
SUBROUTINE CHPGST(ITYPE, UPLO, N, AP, BP, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), BP(*)  
INTEGER ITYPE, N, INFO
```

```
SUBROUTINE CHPGST_64(ITYPE, UPLO, N, AP, BP, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), BP(*)  
INTEGER*8 ITYPE, N, INFO
```

F95 INTERFACE

```
SUBROUTINE HPGST(ITYPE, UPLO, [N], AP, BP, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP, BP  
INTEGER :: ITYPE, N, INFO
```

```
SUBROUTINE HPGST_64(ITYPE, UPLO, [N], AP, BP, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP, BP  
INTEGER(8) :: ITYPE, N, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chpgst(int itype, char uplo, int n, complex *ap, complex *bp, int *info);
```

```
void chpgst_64(long itype, char uplo, long n, complex *ap, complex *bp, long *info);
```

PURPOSE

chpgst reduces a complex Hermitian-definite generalized eigenproblem to standard form, using packed storage.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $\text{inv}(U^{*H})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{*H})$

If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U^{*H}$ or $L^{*H}*A*L$.

B must have been previously factorized as $U^{*H}*U$ or $L*L^{*H}$ by `CPPTRF`.

ARGUMENTS

`ITYPE` (input)
= 1: compute $\text{inv}(U^{*H})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{*H})$;
= 2 or 3: compute $U*A*U^{*H}$ or $L^{*H}*A*L$.

`UPLO` (input)
= 'U': Upper triangle of A is stored and B is factored as $U^{*H}*U$; = 'L': Lower triangle of A is stored and B is factored as $L*L^{*H}$.

`N` (input) The order of the matrices A and B . $N \geq 0$.

`AP` (input/output) COMPLEX array, dimension $(N*(N+1)/2)$
On entry, the upper or lower triangle of the Hermitian matrix A , packed columnwise in a linear array. The j -th column of A is stored in the array `AP` as follows: if `UPLO = 'U'`, $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if `UPLO = 'L'`, $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, if `INFO = 0`, the transformed matrix, stored in the same format as A .

`BP` (input) COMPLEX array, dimension $(N*(N+1)/2)$
The triangular factor from the Cholesky factorization of B , stored in the same format as A , as returned by `CPPTRF`.

`INFO` (output)
= 0: successful exit
< 0: if `INFO = -i`, the i -th argument had an illegal value

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NAME

chpgv - compute all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*Bx=(\lambda)x$, or $B*A*x=(\lambda)x$

SYNOPSIS

```
SUBROUTINE CHPGV(ITYPE, JOBZ, UPLO, N, A, B, W, Z, LDZ, WORK, WORK2,
                INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
COMPLEX A(*), B(*), Z(LDZ,*), WORK(*)
INTEGER ITYPE, N, LDZ, INFO
REAL W(*), WORK2(*)
```

```
SUBROUTINE CHPGV_64(ITYPE, JOBZ, UPLO, N, A, B, W, Z, LDZ, WORK,
                   WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
COMPLEX A(*), B(*), Z(LDZ,*), WORK(*)
INTEGER*8 ITYPE, N, LDZ, INFO
REAL W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPGV(ITYPE, JOBZ, UPLO, [N], A, B, W, Z, [LDZ], [WORK],
               [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX, DIMENSION(:) :: A, B, WORK
COMPLEX, DIMENSION(:, :) :: Z
INTEGER :: ITYPE, N, LDZ, INFO
REAL, DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HPGV_64(ITYPE, JOBZ, UPLO, [N], A, B, W, Z, [LDZ], [WORK],
                  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX, DIMENSION(:) :: A, B, WORK
COMPLEX, DIMENSION(:, :) :: Z
INTEGER(8) :: ITYPE, N, LDZ, INFO
```

```
REAL, DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chpgv(int itype, char jobz, char uplo, int n, complex  
*a, complex *b, float *w, complex *z, int ldz, int  
*info);
```

```
void chpgv_64(long itype, char jobz, char uplo, long n, com-  
plex *a, complex *b, float *w, complex *z, long  
ldz, long *info);
```

PURPOSE

chpgv computes all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*B*x=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian, stored in packed format, and B is also positive definite.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)*B*x$
- = 2: $A*B*x = (\lambda)*x$
- = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

- = 'U': Upper triangles of A and B are stored;
- = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of A are destroyed.

B (input/output) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array B as follows: if UPLO = 'U', $B(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $B(i +$

$(j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U^*H*U$ or $B = L*L^*H$, in the same storage format as B.

W (output) REAL array, dimension (N)
If INFO = 0, the eigenvalues in ascending order.

Z (input) COMPLEX array, dimension (LDZ, N)
If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^*H*B*Z = I$; if ITYPE = 3, $Z^*H*inv(B)*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)
The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)
COMPLEX array, dimension(MAX(1,2*N-1))

WORK2 (workspace)
REAL array, dimension(MAX(1,3*N-2))

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: CPPTRF or CHPEV returned an error code:
<= N: if INFO = i, CHPEV failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero;
> N: if INFO = N + i, for $1 \leq i \leq n$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

chpgvd - compute all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*Bx=(\lambda)x$, or $B*A*x=(\lambda)x$

SYNOPSIS

```
SUBROUTINE CHPGVD(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,  
                 LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AP(*), BP(*), Z(LDZ,*), WORK(*)  
INTEGER ITYPE, N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHPGVD_64(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,  
                   LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
COMPLEX AP(*), BP(*), Z(LDZ,*), WORK(*)  
INTEGER*8 ITYPE, N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HPGVD(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ], [WORK],  
                [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX, DIMENSION(:) :: AP, BP, WORK  
COMPLEX, DIMENSION(:, :) :: Z  
INTEGER :: ITYPE, N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HPGVD_64(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ],  
                   [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX, DIMENSION(:) :: AP, BP, WORK
COMPLEX, DIMENSION(:,:) :: Z
INTEGER(8) :: ITYPE, N, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void chpgvd(int itype, char jobz, char uplo, int n, complex
            *ap, complex *bp, float *w, complex *z, int ldz,
            int *info);

void chpgvd_64(long itype, char jobz, char uplo, long n,
              complex *ap, complex *bp, float *w, complex *z,
              long ldz, long *info);

```

PURPOSE

chpgvd computes all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian, stored in packed format, and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

ITYPE (input)
 Specifies the problem type to be solved:
 = 1: $A*x = (\lambda)*B*x$
 = 2: $A*B*x = (\lambda)*x$
 = 3: $B*A*x = (\lambda)*x$

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
 = 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

AP (input/output) COMPLEX array, dimension $(N*(N+1)/2)$
 On entry, the upper or lower triangle of the Her-

mitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of AP are destroyed.

BP (input/output) COMPLEX array, dimension $(N*(N+1)/2)$
On entry, the upper or lower triangle of the Hermitian matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPLO = 'U', $BP(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $BP(i + (j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U**H*U$ or $B = L*L**H$, in the same storage format as B.

W (output) REAL array, dimension (N)
If INFO = 0, the eigenvalues in ascending order.

Z (input) COMPLEX array, dimension (LDZ, N)
If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z**H*B*Z = I$; if ITYPE = 3, $Z**H*inv(B)*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)
The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace) COMPLEX array, dimension (LWORK)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of array WORK. If $N \leq 1$, $LWORK \geq 1$. If JOBZ = 'N' and $N > 1$, $LWORK \geq N$. If JOBZ = 'V' and $N > 1$, $LWORK \geq 2*N$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace) REAL array, dimension (LRWORK)
On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)
The dimension of array RWORK. If $N \leq 1$, $LRWORK \geq 1$. If JOBZ = 'N' and $N > 1$, $LRWORK \geq N$. If JOBZ = 'V' and $N > 1$, $LRWORK \geq 1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of

the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output) INTEGER array, dimension (LIWORK)
On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
The dimension of array IWORK. If JOBZ = 'N' or N <= 1, LIWORK >= 1. If JOBZ = 'V' and N > 1, LIWORK >= 3 + 5*N.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: CPPTRF or CHPEVD returned an error code:
<= N: if INFO = i, CHPEVD failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not convergeto zero; > N: if INFO = N + i, for 1 <= i <= n, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

chpgvx - compute selected eigenvalues and, optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*Bx=(\lambda)x$, or $B*A*x=(\lambda)x$

SYNOPSIS

```
SUBROUTINE CHPGVX(ITYPE, JOBZ, RANGE, UPLO, N, AP, BP, VL, VU, IL,
                 IU, ABSTOL, M, W, Z, LDZ, WORK, RWORK, IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX AP(*), BP(*), Z(LDZ,*), WORK(*)
INTEGER ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL W(*), RWORK(*)
```

```
SUBROUTINE CHPGVX_64(ITYPE, JOBZ, RANGE, UPLO, N, AP, BP, VL, VU, IL,
                   IU, ABSTOL, M, W, Z, LDZ, WORK, RWORK, IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
COMPLEX AP(*), BP(*), Z(LDZ,*), WORK(*)
INTEGER*8 ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER*8 IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HPGVX(ITYPE, JOBZ, RANGE, UPLO, [N], AP, BP, VL, VU, IL,
                IU, ABSTOL, M, W, Z, [LDZ], [WORK], [RWORK], [IWORK], IFAIL,
                [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: AP, BP, WORK
COMPLEX, DIMENSION(:, :) :: Z
INTEGER :: ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
```

```

REAL, DIMENSION(:) :: W, RWORK

SUBROUTINE HPGVX_64(ITYPE, JOBZ, RANGE, UPLO, [N], AP, BP, VL, VU,
    IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [RWORK], [IWORK], IFAIL,
    [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX, DIMENSION(:) :: AP, BP, WORK
COMPLEX, DIMENSION(:, :) :: Z
INTEGER(8) :: ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void chpgvx(int itype, char jobz, char range, char uplo, int
    n, complex *ap, complex *bp, float vl, float vu,
    int il, int iu, float abstol, int *m, float *w,
    complex *z, int ldz, int *ifail, int *info);

void chpgvx_64(long itype, char jobz, char range, char uplo,
    long n, complex *ap, complex *bp, float vl, float
    vu, long il, long iu, float abstol, long *m, float
    *w, complex *z, long ldz, long *ifail, long
    *info);

```

PURPOSE

chpgvx computes selected eigenvalues and, optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian, stored in packed format, and B is also positive definite. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

ITYPE (input)
 Specifies the problem type to be solved:
 = 1: $A*x = (\lambda)*B*x$
 = 2: $A*B*x = (\lambda)*x$
 = 3: $B*A*x = (\lambda)*x$

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found;
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found; = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

AP (input/output) COMPLEX array, dimension $(N*(N+1)/2)$
 On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.
 On exit, the contents of AP are destroyed.

BP (input/output) COMPLEX array, dimension $(N*(N+1)/2)$
 On entry, the upper or lower triangle of the Hermitian matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPLO = 'U', $BP(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $BP(i + (j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.
 On exit, the triangular factor U or L from the Cholesky factorization $B = U**H*U$ or $B = L*L**H$, in the same storage format as B.

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABSTOL (input)
 The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|) ,$$
 where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS*|T|$ will be

used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing AP to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2*SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output) REAL array, dimension (N)

On normal exit, the first M elements contain the selected eigenvalues in ascending order.

Z (input) COMPLEX array, dimension (LDZ, N)

If JOBZ = 'N', then Z is not referenced. If JOBZ = 'V', then if $INFO = 0$, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized as follows: if $ITYPE = 1$ or 2 , $Z^H B Z = I$; if $ITYPE = 3$, $Z^H \text{inv}(B) Z = I$.

If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

WORK (workspace)

COMPLEX array, dimension($2*N$)

RWORK (workspace)

REAL array, dimension($7*N$)

IWORK (workspace)

INTEGER array, dimension($5*N$)

IFAIL (output)

If JOBZ = 'V', then if $INFO = 0$, the first M elements of IFAIL are zero. If $INFO > 0$, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an ille-

gal value
> 0: CPPTRF or CHPEVX returned an error code:
<= N: if INFO = i, CHPEVX failed to converge; i
eigenvectors failed to converge. Their indices
are stored in array IFAIL. > N: if INFO = N +
i, for 1 <= i <= n, then the leading minor of
order i of B is not positive definite. The fac-
torization of B could not be completed and no
eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

chpmv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE CHPMV(UPLO, N, ALPHA, A, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA, BETA  
COMPLEX A(*), X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE CHPMV_64(UPLO, N, ALPHA, A, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA, BETA  
COMPLEX A(*), X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE HPMV(UPLO, [N], ALPHA, A, X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: A, X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE HPMV_64(UPLO, [N], ALPHA, A, X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: A, X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chpmv(char uplo, int n, complex *alpha, complex *a,  
           complex *x, int incx, complex *beta, complex *y,  
           int incy);
```

```
void chpmv_64(char uplo, long n, complex *alpha, complex *a,
              complex *x, long incx, complex *beta, complex *y,
              long incy);
```

PURPOSE

chpmv performs the matrix-vector operation $y := \alpha A x + \beta y$ where α and β are scalars, x and y are n element vectors and A is an n by n hermitian matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array A as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in A .

UPLO = 'L' or 'l' The lower triangular part of A is supplied in A .

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

(($n * (n + 1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular part of the hermitian matrix packed sequentially, column by column, so that $A(1)$ contains $a(1, 1)$, $A(2)$ and $A(3)$ contain $a(1, 2)$ and $a(2, 2)$ respectively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular part of the hermitian matrix packed sequentially, column by column, so that $A(1)$ contains $a(1, 1)$, $A(2)$ and $A(3)$ contain $a(2, 1)$ and $a(3, 1)$ respectively, and so on. Note that the imaginary parts of the diagonal elements need not be set and are assumed to be zero. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX \neq 0. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

chpr - perform the hermitian rank 1 operation $A := \alpha * x * \text{conjg}(x') + A$

SYNOPSIS

```
SUBROUTINE CHPR(UPLO, N, ALPHA, X, INCX, A)
```

```
CHARACTER * 1 UPLO  
COMPLEX X(*), A(*)  
INTEGER N, INCX  
REAL ALPHA
```

```
SUBROUTINE CHPR_64(UPLO, N, ALPHA, X, INCX, A)
```

```
CHARACTER * 1 UPLO  
COMPLEX X(*), A(*)  
INTEGER*8 N, INCX  
REAL ALPHA
```

F95 INTERFACE

```
SUBROUTINE HPR(UPLO, [N], ALPHA, X, [INCX], A)
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: X, A  
INTEGER :: N, INCX  
REAL :: ALPHA
```

```
SUBROUTINE HPR_64(UPLO, [N], ALPHA, X, [INCX], A)
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: X, A  
INTEGER(8) :: N, INCX  
REAL :: ALPHA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chpr(char uplo, int n, float alpha, complex *x, int  
incx, complex *a);
```

```
void chpr_64(char uplo, long n, float alpha, complex *x,
             long incx, complex *a);
```

PURPOSE

chpr performs the hermitian rank 1 operation $A := \alpha x x^* \text{conjg}(x) + A$ where alpha is a real scalar, x is an n element vector and A is an n by n hermitian matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array A as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in A.

UPLO = 'L' or 'l' The lower triangular part of A is supplied in A.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

A (input/output)

$(n * (n + 1) / 2)$. Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular part of the hermitian matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(1, 2) and a(2, 2) respectively, and so on. On exit, the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular part of the hermitian matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on.

On exit, the array A is overwritten by the lower triangular part of the updated matrix. Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

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NAME

chpr2 - perform the Hermitian rank 2 operation $A := \alpha * x * \text{conjg}(y') + \text{conjg}(\alpha) * y * \text{conjg}(x') + A$

SYNOPSIS

```
SUBROUTINE CHPR2(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA  
COMPLEX X(*), Y(*), AP(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE CHPR2_64(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
```

```
CHARACTER * 1 UPLO  
COMPLEX ALPHA  
COMPLEX X(*), Y(*), AP(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE HPR2(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], AP)
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y, AP  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE HPR2_64(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], AP)
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX :: ALPHA  
COMPLEX, DIMENSION(:) :: X, Y, AP  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chpr2(char uplo, int n, complex *alpha, complex *x, int  
incx, complex *y, int incy, complex *ap);
```

```
void chpr2_64(char uplo, long n, complex *alpha, complex *x,
             long incx, complex *y, long incy, complex *ap);
```

PURPOSE

chpr2 performs the Hermitian rank 2 operation $A := \alpha x \text{conjg}(y') + \text{conjg}(\alpha) y \text{conjg}(x') + A$ where α is a scalar, x and y are n element vectors and A is an n by n hermitian matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array AP as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in AP .

UPLO = 'L' or 'l' The lower triangular part of A is supplied in AP .

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y . $\text{INCY} \neq 0$. Unchanged on exit.

AP (input/output)

$((n * (n + 1)) / 2)$. Before entry with UPLO = 'U' or 'u', the array AP must contain the upper triangular part of the hermitian matrix packed sequentially, column by column, so that $AP(1)$ contains $a(1, 1)$, $AP(2)$ and $AP(3)$ contain $a(1,$

1, 2) and a(2, 2) respectively, and so on. On exit, the array AP is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the array AP must contain the lower triangular part of the hermitian matrix packed sequentially, column by column, so that AP(1) contains a(1, 1), AP(2) and AP(3) contain a(2, 1) and a(3, 1) respectively, and so on. On exit, the array AP is overwritten by the lower triangular part of the updated matrix. Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

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NAME

chprfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CHPRFS(UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX, FERR,
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*)
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CHPRFS_64(UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX,
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPRFS(UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X, [LDX],
  FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX, DIMENSION(:) :: A, AF, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE HPRFS_64(UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X,
  [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

COMPLEX, DIMENSION(:) :: A, AF, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void chprfs(char uplo, int n, int nrhs, complex *a, complex
            *af, int *ipivot, complex *b, int ldb, complex *x,
            int ldx, float *ferr, float *berr, int *info);

void chprfs_64(char uplo, long n, long nrhs, complex *a,
               complex *af, long *ipivot, complex *b, long ldb,
               complex *x, long ldx, float *ferr, float *berr,
               long *info);

```

PURPOSE

chprfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) COMPLEX array, dimension $(N*(N+1)/2)$
 The upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i, j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i, j)$ for $j \leq i \leq n$.

AF (input) COMPLEX array, dimension $(N*(N+1)/2)$
 The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U**H$ or $A = L*D*L**H$ as computed by CHPTRF, stored as a packed triangular matrix.

IPIVOT (input) INTEGER array, dimension (N)
 Details of the interchanges and the block structure of D as determined by CHPTRF.

B (input) COMPLEX array, dimension (LDB,NRHS)
 The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

X (input/output) COMPLEX array, dimension (LDX,NRHS)
On entry, the solution matrix X, as computed by
CHPTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq
max(1,N).

FERR (output) REAL array, dimension (NRHS)
The estimated forward error bound for each solu-
tion vector X(j) (the j-th column of the solution
matrix X). If XTRUE is the true solution
corresponding to X(j), FERR(j) is an estimated
upper bound for the magnitude of the largest ele-
ment in (X(j) - XTRUE) divided by the magnitude of
the largest element in X(j). The estimate is as
reliable as the estimate for RCOND, and is almost
always a slight overestimate of the true error.

BERR (output) REAL array, dimension (NRHS)
The componentwise relative backward error of each
solution vector X(j) (i.e., the smallest relative
change in any element of A or B that makes X(j) an
exact solution).

WORK (workspace)
COMPLEX array, dimension(2*N)

WORK2 (workspace)
REAL array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

chpsv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CHPSV(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CHPSV_64(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HPSV(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HPSV_64(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chpsv(char uplo, int n, int nrhs, complex *a, int
           *ipivot, complex *b, int ldb, int *info);
```

```
void chpsv_64(char uplo, long n, long nrhs, complex *a, long
              *ipivot, complex *b, long ldb, long *info);
```

PURPOSE

chpsv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N Hermitian matrix stored in packed format and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{*H}$, if UPLO = 'U', or

$A = L * D * L^{*H}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{*H}$ or $A = L*D*L^{*H}$ as computed by CHPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (output) INTEGER array, dimension (N)

Details of the interchanges and the block structure of D, as determined by CHPTRF. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged, and $D(k,k)$ is a 1-by-1 diagonal

block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

B (input/output) COMPLEX array, dimension (LDB, NRHS)
On entry, the N-by-NRHS right hand side matrix B.
On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)
The leading dimension of the array B. LDB >= max(1, N).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when N = 4, UPLO = 'U':

Two-dimensional storage of the Hermitian matrix A:

```
  a11 a12 a13 a14
    a22 a23 a24
      a33 a34   (aij = conjg(aji))
        a44
```

Packed storage of the upper triangle of A:

```
A = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

chpsvx - use the diagonal pivoting factorization $A = U^*D^*U^{**H}$ or $A = L^*D^*L^{**H}$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N Hermitian matrix stored in packed format and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE CHPSVX(FACT, UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX,
                 RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*)
REAL RCOND
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CHPSVX_64(FACT, UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X,
                    LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
REAL RCOND
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPSVX(FACT, UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X,
                [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX, DIMENSION(:) :: A, AF, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL :: RCOND
```

```

REAL, DIMENSION(:) :: FERR, BERR, WORK2

SUBROUTINE HPSVX_64(FACT, UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB],
    X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX, DIMENSION(:) :: A, AF, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void chpsvx(char fact, char uplo, int n, int nrhs, complex
    *a, complex *af, int *ipivot, complex *b, int ldb,
    complex *x, int ldx, float *rcond, float *ferr,
    float *berr, int *info);

void chpsvx_64(char fact, char uplo, long n, long nrhs, com-
    plex *a, complex *af, long *ipivot, complex *b,
    long ldb, complex *x, long ldx, float *rcond,
    float *ferr, float *berr, long *info);

```

PURPOSE

chpsvx uses the diagonal pivoting factorization $A = U*D*U^{*H}$ or $A = L*D*L^{*H}$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N Hermitian matrix stored in packed format and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'N', the diagonal pivoting method is used to factor A as

$A = U * D * U^{*H}$, if UPLO = 'U', or

$A = L * D * L^{*H}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices and D is Hermitian and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with INFO = i. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described

below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) COMPLEX array, dimension $(N*(N+1)/2)$

The upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

AF (input or output) COMPLEX array, dimension $(N*(N+1)/2)$

If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**H}$ or $A = L*D*L^{**H}$ as computed by CHPTRF, stored as a packed triangular matrix in the same storage format as A.

If FACT = 'N', then AF is an output argument and on exit contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**H}$ or $A = L*D*L^{**H}$ as computed by CHPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (input or output) INTEGER array, dimension (N)

If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by CHPTRF. If $IPIVOT(k) > 0$, then rows and columns k

and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

If FACT = 'N', then IPIVOT is an output argument and on exit contains details of the interchanges and the block structure of D, as determined by CHPTRF.

B (input) COMPLEX array, dimension (LDB,NRHS)
The N-by-NRHS right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

X (output) COMPLEX array, dimension (LDX,NRHS)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)
The leading dimension of the array X. LDX >= max(1,N).

RCOND (output)
The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output) REAL array, dimension (NRHS)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) (output) REAL array, dimension (NRHS)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
COMPLEX array, dimension(2*N)

WORK2 (workspace)
REAL array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when N = 4, UPLO = 'U':

Two-dimensional storage of the Hermitian matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34 (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

```
A = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

chptrd - reduce a complex Hermitian matrix A stored in packed form to real symmetric tridiagonal form T by a unitary similarity transformation

SYNOPSIS

```
SUBROUTINE CHPTRD(UPLO, N, AP, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), TAU(*)  
INTEGER N, INFO  
REAL D(*), E(*)
```

```
SUBROUTINE CHPTRD_64(UPLO, N, AP, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), TAU(*)  
INTEGER*8 N, INFO  
REAL D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE HPTRD(UPLO, [N], AP, D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP, TAU  
INTEGER :: N, INFO  
REAL, DIMENSION(:) :: D, E
```

```
SUBROUTINE HPTRD_64(UPLO, [N], AP, D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP, TAU  
INTEGER(8) :: N, INFO  
REAL, DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>
```

```

void chptrd(char uplo, int n, complex *ap, float *d, float
            *e, complex *tau, int *info);

void chptrd_64(char uplo, long n, complex *ap, float *d,
              float *e, complex *tau, long *info);

```

PURPOSE

chptrd reduces a complex Hermitian matrix A stored in packed form to real symmetric tridiagonal form T by a unitary similarity transformation: $Q^*H * A * Q = T$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors. See Further Details.

D (output) REAL array, dimension (N)

The diagonal elements of the tridiagonal matrix T:
 $D(i) = A(i,i)$.

E (output) REAL array, dimension (N-1)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i,i+1)$ if UPLO = 'U', $E(i) = A(i+1,i)$ if UPLO = 'L'.

TAU (output) COMPLEX array, dimension (N-1)

The scalar factors of the elementary reflectors (see Further Details).

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-

gal value

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with $v(i+1:n) = 0$ and $v(i) = 1$; $v(1:i-1)$ is stored on exit in AP, overwriting $A(1:i-1,i+1)$, and tau is stored in TAU(i).

If UPLO = 'L', the matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with $v(1:i) = 0$ and $v(i+1) = 1$; $v(i+2:n)$ is stored on exit in AP, overwriting $A(i+2:n,i)$, and tau is stored in TAU(i).

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NAME

chptrf - compute the factorization of a complex Hermitian packed matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE CHPTRF(UPLO, N, A, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CHPTRF_64(UPLO, N, A, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HPTRF(UPLO, [N], A, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HPTRF_64(UPLO, [N], A, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chptrf(char uplo, int n, complex *a, int *ipivot, int
            *info);
```

```
void chptrf_64(char uplo, long n, complex *a, long *ipivot,
               long *info);
```

PURPOSE

chptrf computes the factorization of a complex Hermitian packed matrix A using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U^*H \quad \text{or} \quad A = L^*D^*L^*H$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$
On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i, j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i, j)$ for $j \leq i \leq n$.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L, stored as a packed triangular matrix overwriting A (see below for further details).

IPIVOT (output) INTEGER array, dimension (N)
Details of the interchanges and the block structure of D. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged and $D(k, k)$ is a 1-by-1 diagonal block. If UPLO = 'U' and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns k-1 and $-IPIVOT(k)$ were interchanged and $D(k-1:k, k-1:k)$ is a 2-by-2 diagonal block. If UPLO = 'L' and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns k+1 and $-IPIVOT(k)$ were interchanged and $D(k:k+1, k:k+1)$ is a 2-by-2 diagonal block.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

5-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

chptri - compute the inverse of a complex Hermitian indefinite matrix A in packed storage using the factorization $A = U^*D^*U^*H$ or $A = L^*D^*L^*H$ computed by CHPTRF

SYNOPSIS

```
SUBROUTINE CHPTRI(UPLO, N, A, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CHPTRI_64(UPLO, N, A, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HPTRI(UPLO, [N], A, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HPTRI_64(UPLO, [N], A, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chptri(char uplo, int n, complex *a, int *ipivot, int  
*info);
```

```
void chptri_64(char uplo, long n, complex *a, long *ipivot,
              long *info);
```

PURPOSE

chptri computes the inverse of a complex Hermitian indefinite matrix A in packed storage using the factorization $A = U^*D^*U^{**H}$ or $A = L^*D^*L^{**H}$ computed by CHPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U^*D^*U^{**H}$;
= 'L': Lower triangular, form is $A = L^*D^*L^{**H}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CHPTRF, stored as a packed triangular matrix.

On exit, if INFO = 0, the (Hermitian) inverse of the original matrix, stored as a packed triangular matrix. The j-th column of $\text{inv}(A)$ is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = \text{inv}(A)(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = \text{inv}(A)(i,j)$ for $j \leq i \leq n$.

IPIVOT (input) INTEGER array, dimension (N)

Details of the interchanges and the block structure of D as determined by CHPTRF.

WORK (workspace)

COMPLEX array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

chptrs - solve a system of linear equations $A \cdot X = B$ with a complex Hermitian matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^* \cdot H$ or $A = L \cdot D \cdot L^* \cdot H$ computed by `CHPTRF`

SYNOPSIS

```
SUBROUTINE CHPTRS(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CHPTRS_64(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HPTRS(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HPTRS_64(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void chptrs(char uplo, int n, int nrhs, complex *a, int
            *ipivot, complex *b, int ldb, int *info);
```

```
void chptrs_64(char uplo, long n, long nrhs, complex *a,
               long *ipivot, complex *b, long ldb, long *info);
```

PURPOSE

chptrs solves a system of linear equations $A \cdot X = B$ with a complex Hermitian matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^* \cdot H$ or $A = L \cdot D \cdot L^* \cdot H$ computed by CHPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U \cdot D \cdot U^* \cdot H$;
= 'L': Lower triangular, form is $A = L \cdot D \cdot L^* \cdot H$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) COMPLEX array, dimension $(N \cdot (N+1) / 2)$

The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CHPTRF, stored as a packed triangular matrix.

IPIVOT (input) INTEGER array, dimension (N)

Details of the interchanges and the block structure of D as determined by CHPTRF.

B (input/output) COMPLEX array, dimension (LDB, NRHS)

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

chsein - use inverse iteration to find specified right and/or left eigenvectors of a complex upper Hessenberg matrix H

SYNOPSIS

```
SUBROUTINE CHSEIN(SIDE, EIGSRC, INITV, SELECT, N, H, LDH, W, VL,  
    LDVL, VR, LDVR, MM, M, WORK, RWORK, IFAILL, IFAILR, INFO)
```

```
CHARACTER * 1 SIDE, EIGSRC, INITV  
COMPLEX H(LDH,*), W(*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER N, LDH, LDVL, LDVR, MM, M, INFO  
INTEGER IFAILL(*), IFAILR(*)  
LOGICAL SELECT(*)  
REAL RWORK(*)
```

```
SUBROUTINE CHSEIN_64(SIDE, EIGSRC, INITV, SELECT, N, H, LDH, W, VL,  
    LDVL, VR, LDVR, MM, M, WORK, RWORK, IFAILL, IFAILR, INFO)
```

```
CHARACTER * 1 SIDE, EIGSRC, INITV  
COMPLEX H(LDH,*), W(*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER*8 N, LDH, LDVL, LDVR, MM, M, INFO  
INTEGER*8 IFAILL(*), IFAILR(*)  
LOGICAL*8 SELECT(*)  
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HSEIN(SIDE, EIGSRC, INITV, SELECT, [N], H, [LDH], W, VL,  
    [LDVL], VR, [LDVR], MM, M, [WORK], [RWORK], IFAILL, IFAILR, [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, EIGSRC, INITV  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: H, VL, VR  
INTEGER :: N, LDH, LDVL, LDVR, MM, M, INFO  
INTEGER, DIMENSION(:) :: IFAILL, IFAILR  
LOGICAL, DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: RWORK
```

```

SUBROUTINE HSEIN_64(SIDE, EIGSRC, INITV, SELECT, [N], H, [LDH], W,
    VL, [LDVL], VR, [LDVR], MM, M, [WORK], [RWORK], IFAILL, IFAILR,
    [INFO])

```

```

CHARACTER(LEN=1) :: SIDE, EIGSRC, INITV
COMPLEX, DIMENSION(:) :: W, WORK
COMPLEX, DIMENSION(:, :) :: H, VL, VR
INTEGER(8) :: N, LDH, LDVL, LDVR, MM, M, INFO
INTEGER(8), DIMENSION(:) :: IFAILL, IFAILR
LOGICAL(8), DIMENSION(:) :: SELECT
REAL, DIMENSION(:) :: RWORK

```

C INTERFACE

```
#include <sunperf.h>
```

```

void chsein(char side, char eigsrc, char initv, int *select,
    int n, complex *h, int ldh, complex *w, complex
    *vl, int ldvl, complex *vr, int ldvr, int mm, int
    *m, int *ifaill, int *ifailr, int *info);

```

```

void chsein_64(char side, char eigsrc, char initv, long
    *select, long n, complex *h, long ldh, complex *w,
    complex *vl, long ldvl, complex *vr, long ldvr,
    long mm, long *m, long *ifaill, long *ifailr, long
    *info);

```

PURPOSE

chsein uses inverse iteration to find specified right and/or left eigenvectors of a complex upper Hessenberg matrix H.

The right eigenvector x and the left eigenvector y of the matrix H corresponding to an eigenvalue w are defined by:

$$H * x = w * x, \quad y^{*h} * H = w * y^{*h}$$

where y**h denotes the conjugate transpose of the vector y.

ARGUMENTS

SIDE (input)

```

= 'R': compute right eigenvectors only;
= 'L': compute left eigenvectors only;
= 'B': compute both right and left eigenvectors.

```

EIGSRC (input)

Specifies the source of eigenvalues supplied in W:
= 'Q': the eigenvalues were found using CHSEQR;
thus, if H has zero subdiagonal elements, and so is block-triangular, then the j-th eigenvalue can be assumed to be an eigenvalue of the block containing the j-th row/column. This property allows CHSEIN to perform inverse iteration on just one diagonal block. = 'N': no assumptions are made on the correspondence between eigenvalues and diagonal blocks. In this case, CHSEIN must always perform inverse iteration using the whole matrix H.

INITV (input)
= 'N': no initial vectors are supplied;
= 'U': user-supplied initial vectors are stored in
the arrays VL and/or VR.

SELECT (input)
Specifies the eigenvectors to be computed. To
select the eigenvector corresponding to the eigen-
value $W(j)$, SELECT(j) must be set to .TRUE..

N (input) The order of the matrix H. $N \geq 0$.

H (input) The upper Hessenberg matrix H.

LDH (input)
The leading dimension of the array H. $LDH \geq$
 $\max(1,N)$.

W (input/output)
On entry, the eigenvalues of H. On exit, the real
parts of W may have been altered since close
eigenvalues are perturbed slightly in searching
for independent eigenvectors.

VL (input/output)
On entry, if INITV = 'U' and SIDE = 'L' or 'B', VL
must contain starting vectors for the inverse
iteration for the left eigenvectors; the starting
vector for each eigenvector must be in the same
column in which the eigenvector will be stored.
On exit, if SIDE = 'L' or 'B', the left eigenvec-
tors specified by SELECT will be stored consecu-
tively in the columns of VL, in the same order as
their eigenvalues. If SIDE = 'R', VL is not
referenced.

LDVL (input)
The leading dimension of the array VL. $LDVL \geq$
 $\max(1,N)$ if SIDE = 'L' or 'B'; $LDVL \geq 1$ other-
wise.

VR (input/output)
On entry, if INITV = 'U' and SIDE = 'R' or 'B', VR
must contain starting vectors for the inverse
iteration for the right eigenvectors; the starting
vector for each eigenvector must be in the same
column in which the eigenvector will be stored.
On exit, if SIDE = 'R' or 'B', the right eigenvec-
tors specified by SELECT will be stored consecu-
tively in the columns of VR, in the same order as
their eigenvalues. If SIDE = 'L', VR is not
referenced.

LDVR (input)
The leading dimension of the array VR. $LDVR \geq$
 $\max(1,N)$ if SIDE = 'R' or 'B'; $LDVR \geq 1$ other-
wise.

MM (input)
The number of columns in the arrays VL and/or VR.

MM >= M.

M (output)

The number of columns in the arrays VL and/or VR required to store the eigenvectors (= the number of .TRUE. elements in SELECT).

WORK (workspace)

dimension(N*N)

RWORK (workspace)

dimension(N)

IFAILL (output)

If SIDE = 'L' or 'B', IFAILL(i) = j > 0 if the left eigenvector in the i-th column of VL (corresponding to the eigenvalue w(j)) failed to converge; IFAILL(i) = 0 if the eigenvector converged satisfactorily. If SIDE = 'R', IFAILL is not referenced.

IFAILR (output)

If SIDE = 'R' or 'B', IFAILR(i) = j > 0 if the right eigenvector in the i-th column of VR (corresponding to the eigenvalue w(j)) failed to converge; IFAILR(i) = 0 if the eigenvector converged satisfactorily. If SIDE = 'L', IFAILR is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, i is the number of eigenvectors which failed to converge; see IFAILL and IFAILR for further details.

FURTHER DETAILS

Each eigenvector is normalized so that the element of largest magnitude has magnitude 1; here the magnitude of a complex number (x,y) is taken to be $|x|+|y|$.

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NAME

chseqr - compute the eigenvalues of a complex upper Hessenberg matrix H, and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z^*H$, where T is an upper triangular matrix (the Schur form), and Z is the unitary matrix of Schur vectors

SYNOPSIS

```
SUBROUTINE CHSEQR(JOB, COMPZ, N, ILO, IHI, H, LDH, W, Z, LDZ, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPZ  
COMPLEX H(LDH,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER N, ILO, IHI, LDH, LDZ, LWORK, INFO
```

```
SUBROUTINE CHSEQR_64(JOB, COMPZ, N, ILO, IHI, H, LDH, W, Z, LDZ,  
WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPZ  
COMPLEX H(LDH,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, ILO, IHI, LDH, LDZ, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE HSEQR(JOB, COMPZ, N, ILO, IHI, H, [LDH], W, Z, [LDZ],  
[WORK], LWORK, [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPZ  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: H, Z  
INTEGER :: N, ILO, IHI, LDH, LDZ, LWORK, INFO
```

```
SUBROUTINE HSEQR_64(JOB, COMPZ, N, ILO, IHI, H, [LDH], W, Z, [LDZ],  
[WORK], LWORK, [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPZ  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: H, Z  
INTEGER(8) :: N, ILO, IHI, LDH, LDZ, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>

void chseqr (char, char, int, int, int, complex*, int, complex*, complex*, int, int*);

void chseqr_64 (char, char, long, long, long, complex*, long, complex*, complex*, long, long*);
```

PURPOSE

chseqr computes the eigenvalues of a complex upper Hessenberg matrix H, and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z^*H$, where T is an upper triangular matrix (the Schur form), and Z is the unitary matrix of Schur vectors.

Optionally Z may be postmultiplied into an input unitary matrix Q, so that this routine can give the Schur factorization of a matrix A which has been reduced to the Hessenberg form H by the unitary matrix Q: $A = Q^*H^*Q^*H = (QZ)^*T^*(QZ)^*H$.

ARGUMENTS

JOB (input)
 = 'E': compute eigenvalues only;
 = 'S': compute eigenvalues and the Schur form T.

COMPZ (input)
 = 'N': no Schur vectors are computed;
 = 'I': Z is initialized to the unit matrix and the matrix Z of Schur vectors of H is returned; = 'V': Z must contain an unitary matrix Q on entry, and the product Q*Z is returned.

N (input) The order of the matrix H. $N \geq 0$.

ILO (input)
 It is assumed that H is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to CGEBAL, and then passed to CGEHRD when the matrix output by CGEBAL is reduced to Hessenberg form. Otherwise ILO and IHI should be set to 1 and N respectively. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)
 See the description of ILO.

H (input/output)
 On entry, the upper Hessenberg matrix H. On exit, if JOB = 'S', H contains the upper triangular matrix T from the Schur decomposition (the Schur form). If JOB = 'E', the contents of H are unspecified on exit.

LDH (input)
 The leading dimension of the array H. LDH \geq max(1,N).

W (output)
 The computed eigenvalues. If JOB = 'S', the eigenvalues are stored in the same order as on the diagonal of the Schur form returned in H, with $W(i) = H(i,i)$.

Z (input) If COMPZ = 'N': Z is not referenced.
 If COMPZ = 'I': on entry, Z need not be set, and on exit, Z contains the unitary matrix Z of the Schur vectors of H. If COMPZ = 'V': on entry Z must contain an N-by-N matrix Q, which is assumed to be equal to the unit matrix except for the submatrix Z(ILO:IHI,ILO:IHI); on exit Z contains Q*Z. Normally Q is the unitary matrix generated by CUNGHR after the call to CGEHRD which formed the Hessenberg matrix H.

LDZ (input)
 The leading dimension of the array Z. LDZ \geq max(1,N) if COMPZ = 'I' or 'V'; LDZ \geq 1 otherwise.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (output)
 The dimension of the array WORK. LWORK \geq max(1,N).

 If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, CHSEQR failed to compute all the eigenvalues in a total of $30*(IHI-ILO+1)$ iterations; elements 1:ilo-1 and i+1:n of W contain those eigenvalues which have been successfully computed.

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NAME

cjadmm - Jagged diagonal matrix-matrix multiply (modified Ellpack)

SYNOPSIS

```
SUBROUTINE CJADMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, PNTR, MAXNZ, IPERM,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, K, DESCRA(5), MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CJADMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                    VAL, INDX, PNTR, MAXNZ, IPERM,  
*                    B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ is the number of non-zero elements.

F95 INTERFACE

```
SUBROUTINE JADMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, K, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE JADMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                    PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, M, K, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM
```

```

COMPLEX ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL
COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void cjadmm (int transa, int m, int n, int k, complex
*alpha, int *descra, complex *val, int *indx, int *pntr, int
maxnz, int *iperm, complex *b, int ldb, complex *beta,
complex *c, int ldc)

void cjadmm_64(long transa, long m, long n, long k, complex
*alpha, long *descra, complex *val, long *indx, long *pntr,
long maxnz, long *iperm, complex *b, long ldb, complex
*beta, complex *c, long ldc);

```

DESCRIPTION

cjadmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the jagged diagonal format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular

4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
 NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of entries of A.
 VAL can be viewed as a column major ordering of a
 row permutation of the Ellpack representation of A,
 where the Ellpack representation is permuted so that
 the rows are non-increasing in the number of nonzero
 entries. Values added for padding in Ellpack are
 not included in the Jagged-Diagonal format.
 Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
 NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of the column
 indices of the corresponding entries in VAL.
 Unchanged on exit.

PNTR(input) On entry, PNTR is an integer array of length
 MAXNZ+1, where PNTR(I)-PNTR(1)+1 points to
 the location in VAL of the first element
 in the row-permuted Ellpack representation of A.
 Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of
 nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length M
 such that I = IPERM(I'), where row I in the
 original Ellpack representation corresponds
 to row I' in the permuted representation.
 If IPERM(1) = 0, it is assumed by convention that
 IPERM(I) = I. IPERM is used to determine the order
 in which rows of C are updated. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise

the leading k by n part of the array C must contain the matrix C . On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \beta * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

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NAME

cjadrp - right permutation of a jagged diagonal matrix

SYNOPSIS

```
SUBROUTINE CJADRP( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*                IPERM, WORK, LWORK )
INTEGER        TRANSP, M, K, MAXNZ, LWORK
INTEGER        INDX(*), PNTR(MAXNZ+1), IPERM(K), WORK(LWORK)
COMPLEX        VAL(*)
```

```
SUBROUTINE CJADRP_64( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*                   IPERM, WORK, LWORK )
INTEGER*8      TRANSP, M, K, MAXNZ, LWORK
INTEGER*8      INDX(*), PNTR(MAXNZ+1), IPERM(K), WORK(LWORK)
COMPLEX        VAL(*)
```

F95 INTERFACE

```
SUBROUTINE JADRP( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*              IPERM, [WORK], [LWORK] )
INTEGER TRANSP, M, K, MAXNZ
INTEGER, DIMENSION(:) :: INDX, PNTR, IPERM
COMPLEX, DIMENSION(:) :: VAL
```

```
SUBROUTINE JADRP_64( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*                  IPERM, [WORK], [LWORK] )
INTEGER*8 TRANSP, M, K, MAXNZ
INTEGER*8, DIMENSION(:) :: INDX, PNTR, IPERM
COMPLEX, DIMENSION(:) :: VAL
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cjadrp (int transp, int m, int k, complex *val, int
*indx, int *pntr, int maxnz, int *iperm);
```

```
void cjadrp_64 (long transp, long m, long k, complex *val,
long *indx, long *pntr, long maxnz, long *iperm);
```

DESCRIPTION

cjadrp performs one of the matrix-matrix operations

$A \leftarrow A P$ or $A \leftarrow A P'$ (' indicates matrix transpose)

where A is an M -by- K sparse matrix represented in the jagged diagonal format, the permutation matrix P is represented by an integer vector $IPERM$, such that $IPERM(I)$ is equal to the position of the only nonzero element in row I of permutation matrix P .
NOTE: In order to get a symmetrically permuted jagged diagonal matrix $P A P'$, one can explicitly permute the columns $P A$ by calling

```
CJADRP(0, M, M, VAL, INDX, PNTR, MAXNZ, IPERM, WORK, LWORK)
```

where parameters VAL , $INDX$, $PNTR$, $MAXNZ$, $IPERM$ are the representation of A in the jagged diagonal format. The operation makes sense if the original matrix A is square.

ARGUMENTS

TRANSP(input) $TRANSP$ indicates how to operate with the permutation matrix:
 0 : operate with matrix
 1 : operate with transpose matrix
 Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A . Unchanged on exit.

K(input) On entry, K specifies the number of columns in the matrix A . Unchanged on exit.

VAL(input/output) On entry, VAL is a scalar array of length $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ consisting of entries of A . VAL can be viewed as a column major ordering of a row permutation of the Ellpack representation of A , where the Ellpack representation is permuted so that the rows are non-increasing in the number of nonzero entries. Values added for padding in Ellpack are not included in the Jagged-Diagonal format.
On exit, VAL contains non-zero entries of the output permuted jagged diagonal matrix.

INDX(input/output) On entry, $INDX$ is an integer array of length $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ consisting of the column indices of the corresponding entries in VAL .
On exit, $INDX$ is overwritten by the column indices of the output permuted jagged diagonal matrix.

PNTR(input) On entry, $PNTR$ is an integer array of length $MAXNZ+1$, where $PNTR(I)-PNTR(1)+1$ points to the location in VAL of the first element in the row-permuted Ellpack representation of A .
Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length K such that $I = \text{IPERM}(I')$. Array IPERM represents a permutation P, such that IPERM(I) is equal to the position of the only nonzero element in row I of permutation matrix P. For example, if

$$P = \begin{pmatrix} | & 0 & 0 & 1 & | \\ | & 1 & 0 & 0 & | \\ | & 0 & 1 & 0 & | \end{pmatrix}$$

then IPERM = (3, 1, 2). Unchanged on exit.

WORK(workspace) Scratch array of length LWORK. LWORK should be at least K.

LWORK(input) On entry, LWORK specifies the length of the array WORK. If LWORK=0, the routine is to allocate workspace needed. If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the array WORK, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

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NAME

cjadsm - Jagged-diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE CJADSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, PNTR, MAXNZ, IPERM,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, UNITD, DESCRA(5), MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
COMPLEX         ALPHA, BETA  
COMPLEX         DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE CJADSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, PNTR, MAXNZ, IPERM,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8       TRANSA, M, N, UNITD, DESCRA(5), MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER*8       INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
COMPLEX         ALPHA, BETA  
COMPLEX         DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ is the number of non-zero elements

F95 INTERFACE

```
SUBROUTINE JADSM(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
*                PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
COMPLEX         ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL, DV  
COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE JADSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
*                PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8       TRANSA, M, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
COMPLEX         ALPHA, BETA
```

```
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cjadsm (int transa, int m, int n, int unitd, complex
*dv, complex *alpha, int *descra, complex *val, int *indx,
int *pntr, int maxnz, int *iperm, complex *b, int ldb,
complex *beta, complex *c, int ldc)
void cjadsm_64(long transa, long m, long n, long unitd,
complex *dv, complex *alpha, long *descra, complex *val,
long *indx, long *pntr, long maxnz, long *iperm, complex
*b, long ldb, complex *beta, complex *c, long ldc);
```

DESCRIPTION

cjadsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the jagged-diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of entries of A.
VAL can be viewed as a column major ordering of a
row permutation of the Ellpack representation of A,
where the Ellpack representation is permuted so that
the rows are non-increasing in the number of nonzero
entries. Values added for padding in Ellpack are
not included in the Jagged-Diagonal format.
Unchanged on exit if UNITD is not equal to 4.

INDX(input) On entry, INDX is an integer array of length
NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of the column
indices of the corresponding entries in VAL.
Unchanged on exit.

PNTR(input) On entry, PNTR is an integer array of length
MAXNZ+1, where PNTR(I)-PNTR(1)+1 points to
the location in VAL of the first element
in the row-permuted Ellpack representation of A.
Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of
nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length M
such that I = IPERM(I'), where row I in the
original Ellpack representation corresponds
to row I' in the permuted representation.
If IPERM(1) = 0, it is assumed by convention that
IPERM(I) = I. IPERM is used to determine the order
in which rows of C are updated. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B

must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least 2*M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq 2*M*N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:
<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If UNITD =4, the routine scales the rows of the sparse matrix A such that their 2-norms are one. The scaling may

improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = - i where i is the row number which 2-norm is exactly zero.

3. If DESCRA(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the JAD representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the JAD representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But DESCRA(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	alpha*op(L+I)*B+beta*C
3	1	0	alpha*op(L+D)*B+beta*C
3	2	1	alpha*op(U+I)*B+beta*C
3	2	0	alpha*op(U+D)*B+beta*C

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NAME

clarz - applie a complex elementary reflector H to a complex M-by-N matrix C, from either the left or the right

SYNOPSIS

```
SUBROUTINE CLARZ(SIDE, M, N, L, V, INCV, TAU, C, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
COMPLEX TAU  
COMPLEX V(*), C(LDC,*), WORK(*)  
INTEGER M, N, L, INCV, LDC
```

```
SUBROUTINE CLARZ_64(SIDE, M, N, L, V, INCV, TAU, C, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
COMPLEX TAU  
COMPLEX V(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, L, INCV, LDC
```

F95 INTERFACE

```
SUBROUTINE LARZ(SIDE, [M], [N], L, V, [INCV], TAU, C, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
COMPLEX :: TAU  
COMPLEX, DIMENSION(:) :: V, WORK  
COMPLEX, DIMENSION(:,:) :: C  
INTEGER :: M, N, L, INCV, LDC
```

```
SUBROUTINE LARZ_64(SIDE, [M], [N], L, V, [INCV], TAU, C, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
COMPLEX :: TAU  
COMPLEX, DIMENSION(:) :: V, WORK  
COMPLEX, DIMENSION(:,:) :: C  
INTEGER(8) :: M, N, L, INCV, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```
void clarz(char side, int m, int n, int l, complex *v, int
          incv, complex *tau, complex *c, int ldc);
```

```
void clarz_64(char side, long m, long n, long l, complex *v,
             long incv, complex *tau, complex *c, long ldc);
```

PURPOSE

clarz applies a complex elementary reflector H to a complex M-by-N matrix C, from either the left or the right. H is represented in the form

$$H = I - \tau * v * v'$$

where tau is a complex scalar and v is a complex vector.

If tau = 0, then H is taken to be the unit matrix.

To apply H' (the conjugate transpose of H), supply conjg(tau) instead tau.

H is a product of k elementary reflectors as returned by CTZRZF.

ARGUMENTS

SIDE (input)

= 'L': form $H * C$
= 'R': form $C * H$

M (input) The number of rows of the matrix C.

N (input) The number of columns of the matrix C.

L (input) The number of entries of the vector V containing the meaningful part of the Householder vectors. If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L \geq 0$.

V (input) The vector v in the representation of H as returned by CTZRZF. V is not used if TAU = 0.

INCV (input)

The increment between elements of v. INCV $\neq 0$.

TAU (input)

The value tau in the representation of H.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by the matrix $H * C$ if SIDE = 'L', or $C * H$ if SIDE = 'R'.

LDC (input)

The leading dimension of the array C. LDC \geq

`max(1,M).`

`WORK (workspace)`

`(N) if SIDE = 'L' or (M) if SIDE = 'R'`

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

clarzb - applie a complex block reflector H or its transpose H^*H to a complex distributed M-by-N C from the left or the right

SYNOPSIS

```
SUBROUTINE CLARZB(SIDE, TRANS, DIRECT, STOREV, M, N, K, L, V, LDV, T,
  LDT, C, LDC, WORK, LDWORK)
```

```
CHARACTER * 1 SIDE, TRANS, DIRECT, STOREV
COMPLEX V(LDV,*), T(LDT,*), C(LDC,*), WORK(LDWORK,*)
INTEGER M, N, K, L, LDV, LDT, LDC, LDWORK
```

```
SUBROUTINE CLARZB_64(SIDE, TRANS, DIRECT, STOREV, M, N, K, L, V, LDV,
  T, LDT, C, LDC, WORK, LDWORK)
```

```
CHARACTER * 1 SIDE, TRANS, DIRECT, STOREV
COMPLEX V(LDV,*), T(LDT,*), C(LDC,*), WORK(LDWORK,*)
INTEGER*8 M, N, K, L, LDV, LDT, LDC, LDWORK
```

F95 INTERFACE

```
SUBROUTINE LARZB(SIDE, TRANS, DIRECT, STOREV, [M], [N], K, L, V, [LDV],
  T, [LDT], C, [LDC], [WORK], [LDWORK])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS, DIRECT, STOREV
COMPLEX, DIMENSION(:,:) :: V, T, C, WORK
INTEGER :: M, N, K, L, LDV, LDT, LDC, LDWORK
```

```
SUBROUTINE LARZB_64(SIDE, TRANS, DIRECT, STOREV, [M], [N], K, L, V,
  [LDV], T, [LDT], C, [LDC], [WORK], [LDWORK])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS, DIRECT, STOREV
COMPLEX, DIMENSION(:,:) :: V, T, C, WORK
INTEGER(8) :: M, N, K, L, LDV, LDT, LDC, LDWORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void clarzb(char side, char trans, char direct, char storev,
            int m, int n, int k, int l, complex *v, int ldv,
            complex *t, int ldt, complex *c, int ldc, int
            ldwork);
```

```
void clarzb_64(char side, char trans, char direct, char
               storev, long m, long n, long k, long l, complex
               *v, long ldv, complex *t, long ldt, complex *c,
               long ldc, long ldwork);
```

PURPOSE

clarzb applies a complex block reflector H or its transpose H^*H to a complex distributed M -by- N C from the left or the right.

Currently, only STOREV = 'R' and DIRECT = 'B' are supported.

ARGUMENTS

SIDE (input)

= 'L': apply H or H' from the Left
 = 'R': apply H or H' from the Right

TRANS (input)

= 'N': apply H (No transpose)
 = 'C': apply H' (Conjugate transpose)

DIRECT (input)

Indicates how H is formed from a product of elementary reflectors = 'F': $H = H(1) H(2) \dots H(k)$ (Forward, not supported yet)
 = 'B': $H = H(k) \dots H(2) H(1)$ (Backward)

STOREV (input)

Indicates how the vectors which define the elementary reflectors are stored:
 = 'C': Columnwise (not supported yet)
 = 'R': Rowwise

M (input) The number of rows of the matrix C .

N (input) The number of columns of the matrix C .

K (input) The order of the matrix T (= the number of elementary reflectors whose product defines the block reflector).

L (input) The number of columns of the matrix V containing the meaningful part of the Householder reflectors. If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L \geq 0$.

V (input) If STOREV = 'C', $NV = K$; if STOREV = 'R', $NV = L$.

LDV (input)

The leading dimension of the array V. If STOREV = 'C', LDV \geq L; if STOREV = 'R', LDV \geq K.

T (input) The triangular K-by-K matrix T in the representation of the block reflector.

LDT (input)
The leading dimension of the array T. LDT \geq K.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by H*C or H'*C or C*H or C'H'.

LDC (input)
The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)
dimension(MAX(M,N),K)

LDWORK (input)
The leading dimension of the array WORK. If SIDE = 'L', LDWORK \geq max(1,N); if SIDE = 'R', LDWORK \geq max(1,M).

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

clarzt - form the triangular factor T of a complex block reflector H of order > n, which is defined as a product of k elementary reflectors

SYNOPSIS

```
SUBROUTINE CLARZT(DIRECT, STOREV, N, K, V, LDV, TAU, T, LDT)
```

```
CHARACTER * 1 DIRECT, STOREV  
COMPLEX V(LDV,*), TAU(*), T(LDT,*)  
INTEGER N, K, LDV, LDT
```

```
SUBROUTINE CLARZT_64(DIRECT, STOREV, N, K, V, LDV, TAU, T, LDT)
```

```
CHARACTER * 1 DIRECT, STOREV  
COMPLEX V(LDV,*), TAU(*), T(LDT,*)  
INTEGER*8 N, K, LDV, LDT
```

F95 INTERFACE

```
SUBROUTINE LARZT(DIRECT, STOREV, N, K, V, [LDV], TAU, T, [LDT])
```

```
CHARACTER(LEN=1) :: DIRECT, STOREV  
COMPLEX, DIMENSION(:) :: TAU  
COMPLEX, DIMENSION(:, :) :: V, T  
INTEGER :: N, K, LDV, LDT
```

```
SUBROUTINE LARZT_64(DIRECT, STOREV, N, K, V, [LDV], TAU, T, [LDT])
```

```
CHARACTER(LEN=1) :: DIRECT, STOREV  
COMPLEX, DIMENSION(:) :: TAU  
COMPLEX, DIMENSION(:, :) :: V, T  
INTEGER(8) :: N, K, LDV, LDT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void clarzt(char direct, char storev, int n, int k, complex  
            *v, int ldv, complex *tau, complex *t, int ldt);
```

```
void clarzt_64(char direct, char storev, long n, long k,
               complex *v, long ldv, complex *tau, complex *t,
               long ldt);
```

PURPOSE

clarzt forms the triangular factor T of a complex block reflector H of order $> n$, which is defined as a product of k elementary reflectors.

If $DIRECT = 'F'$, $H = H(1) H(2) \dots H(k)$ and T is upper triangular;

If $DIRECT = 'B'$, $H = H(k) \dots H(2) H(1)$ and T is lower triangular.

If $STOREV = 'C'$, the vector which defines the elementary reflector $H(i)$ is stored in the i -th column of the array V , and

$$H = I - V * T * V'$$

If $STOREV = 'R'$, the vector which defines the elementary reflector $H(i)$ is stored in the i -th row of the array V , and

$$H = I - V' * T * V$$

Currently, only $STOREV = 'R'$ and $DIRECT = 'B'$ are supported.

ARGUMENTS

DIRECT (input)

Specifies the order in which the elementary reflectors are multiplied to form the block reflector:
 = 'F': $H = H(1) H(2) \dots H(k)$ (Forward, not supported yet)
 = 'B': $H = H(k) \dots H(2) H(1)$ (Backward)

STOREV (input)

Specifies how the vectors which define the elementary reflectors are stored (see also Further Details):
 = 'R': rowwise

N (input) The order of the block reflector H . $N \geq 0$.

K (input) The order of the triangular factor T (= the number of elementary reflectors). $K \geq 1$.

V (input) (LDV,K) if $STOREV = 'C'$ (LDV,N) if $STOREV = 'R'$
 The matrix V . See further details.

LDV (input)

The leading dimension of the array V . If $STOREV =$

'C', LDV >= max(1,N); if STOREV = 'R', LDV >= K.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i).

T (input)

The k by k triangular factor T of the block reflector. If DIRECT = 'F', T is upper triangular; if DIRECT = 'B', T is lower triangular. The rest of the array is not used.

LDT (input)

The leading dimension of the array T. LDT >= K.

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

The shape of the matrix V and the storage of the vectors which define the H(i) is best illustrated by the following example with n = 5 and k = 3. The elements equal to 1 are not stored; the corresponding array elements are modified but restored on exit. The rest of the array is not used.

DIRECT = 'F' and STOREV = 'C': DIRECT = 'F' and STOREV = 'R':

<pre> (v1 v2 v3) (v1 v2 v3)) V = (v1 v2 v3) . . 1) . 1) (v1 v2 v3) (v1 v2 v3) . . . 1 . . . 1 . . 1 </pre>	<pre> _____V_____ (v1 v1 v1 v1 v1 1 (v2 v2 v2 v2 v2 . (v3 v3 v3 v3 v3 . </pre>
---	---

DIRECT = 'B' and STOREV = 'C': DIRECT = 'B' and STOREV = 'R':

<pre> 1 . 1 . . 1 v2 v2 v2) v3 v3 v3) . . . (v1 v2 v3) V = (v1 v2 v3) (v1 v2 v3) </pre>	<pre> _____V_____ / (1 v1 v1 v1 v1 v1) (. 1 v2 v2 (. . 1 . . . v3 v3 </pre>
---	---

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NAME

clatzm - routine is deprecated and has been replaced by routine CUNMRZ

SYNOPSIS

```
SUBROUTINE CLATZM(SIDE, M, N, V, INCV, TAU, C1, C2, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
COMPLEX TAU  
COMPLEX V(*), C1(LDC,*), C2(LDC,*), WORK(*)  
INTEGER M, N, INCV, LDC
```

```
SUBROUTINE CLATZM_64(SIDE, M, N, V, INCV, TAU, C1, C2, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
COMPLEX TAU  
COMPLEX V(*), C1(LDC,*), C2(LDC,*), WORK(*)  
INTEGER*8 M, N, INCV, LDC
```

F95 INTERFACE

```
SUBROUTINE LATZM(SIDE, [M], [N], V, [INCV], TAU, C1, C2, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
COMPLEX :: TAU  
COMPLEX, DIMENSION(:) :: V, WORK  
COMPLEX, DIMENSION(:,:) :: C1, C2  
INTEGER :: M, N, INCV, LDC
```

```
SUBROUTINE LATZM_64(SIDE, [M], [N], V, [INCV], TAU, C1, C2, [LDC],  
[WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
COMPLEX :: TAU  
COMPLEX, DIMENSION(:) :: V, WORK  
COMPLEX, DIMENSION(:,:) :: C1, C2  
INTEGER(8) :: M, N, INCV, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```

void clatzm(char side, int m, int n, complex *v, int incv,
            complex *tau, complex *c1, complex *c2, int ldc);

void clatzm_64(char side, long m, long n, complex *v, long
               incv, complex *tau, complex *c1, complex *c2, long
               ldc);

```

PURPOSE

clatzm routine is deprecated and has been replaced by routine CUNMRZ.

CLATZM applies a Householder matrix generated by CTZRQF to a matrix.

Let $P = I - \tau \cdot u \cdot u'$, $u = \begin{pmatrix} 1 \\ v \end{pmatrix}$,

where v is an $(m-1)$ vector if $SIDE = 'L'$, or a $(n-1)$ vector if $SIDE = 'R'$.

If $SIDE$ equals $'L'$, let

$$C = \begin{bmatrix} C1 & 1 \\ C2 & \end{bmatrix} \begin{matrix} 1 \\ m-1 \\ n \end{matrix}$$

Then C is overwritten by $P \cdot C$.

If $SIDE$ equals $'R'$, let

$$C = \begin{bmatrix} C1, & C2 \end{bmatrix} \begin{matrix} m \\ 1 & n-1 \end{matrix}$$

Then C is overwritten by $C \cdot P$.

ARGUMENTS

$SIDE$ (input)

= $'L'$: form $P \cdot C$
 = $'R'$: form $C \cdot P$

M (input) The number of rows of the matrix C .

N (input) The number of columns of the matrix C .

V (input) $(1 + (M-1) \cdot \text{abs}(\text{INCV}))$ if $SIDE = 'L'$ $(1 + (N-1) \cdot \text{abs}(\text{INCV}))$ if $SIDE = 'R'$ The vector v in the representation of P . V is not used if $\text{TAU} = 0$.

INCV (input)

The increment between elements of v . $\text{INCV} \neq 0$

TAU (input)

The value τ in the representation of P .

$C1$ (input/output)

(LDC, N) if $SIDE = 'L'$ $(M, 1)$ if $SIDE = 'R'$ On entry, the n -vector $C1$ if $SIDE = 'L'$, or the m -vector $C1$ if $SIDE = 'R'$.

On exit, the first row of P*C if SIDE = 'L', or
the first column of C*P if SIDE = 'R'.

C2 (input/output)

(LDC, N) if SIDE = 'L' (LDC, N-1) if SIDE = 'R'
On entry, the (m - 1) x n matrix C2 if SIDE = 'L',
or the m x (n - 1) matrix C2 if SIDE = 'R'.

On exit, rows 2:m of P*C if SIDE = 'L', or columns
2:m of C*P if SIDE = 'R'.

LDC (input)

The leading dimension of the arrays C1 and C2.
LDC >= max(1,M).

WORK (workspace)

(N) if SIDE = 'L' (M) if SIDE = 'R'

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NAME

cosqb - synthesize a Fourier sequence from its representation in terms of a cosine series with odd wave numbers. The COSQ operations are unnormalized inverses of themselves, so a call to COSQF followed by a call to COSQB will multiply the input sequence by $4 * N$.

SYNOPSIS

```
SUBROUTINE COSQB(N, X, WSAVE)
```

```
INTEGER N  
REAL X(*), WSAVE(*)
```

```
SUBROUTINE COSQB_64(N, X, WSAVE)
```

```
INTEGER*8 N  
REAL X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQB(N, X, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE COSQB_64(N, X, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cosqb(int n, float *x, float *wsave);
```

```
void cosqb_64(long n, float *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the quarter-wave cosine synthesis of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$ that has been initialized by COSQI.

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NAME

cosqf - compute the Fourier coefficients in a cosine series representation with only odd wave numbers. The COSQ operations are unnormalized inverses of themselves, so a call to COSQF followed by a call to COSQB will multiply the input sequence by 4 * N.

SYNOPSIS

```
SUBROUTINE COSQF(N, X, WSAVE)
```

```
INTEGER N  
REAL X(*), WSAVE(*)
```

```
SUBROUTINE COSQF_64(N, X, WSAVE)
```

```
INTEGER*8 N  
REAL X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQF(N, X, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE COSQF_64(N, X, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cosqf(int n, float *x, float *wsave);
```

```
void cosqf_64(long n, float *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the quarter-wave cosine transform of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$ that has been initialized by COSQI.

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NAME

cosqi - initialize the array WSAVE, which is used in both COSQF and COSQB.

SYNOPSIS

```
SUBROUTINE COSQI(N, WSAVE)
```

```
INTEGER N  
REAL WSAVE(*)
```

```
SUBROUTINE COSQI_64(N, WSAVE)
```

```
INTEGER*8 N  
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQI(N, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: WSAVE
```

```
SUBROUTINE COSQI_64(N, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cosqi(int n, float *wsave);
```

```
void cosqi_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. The method is most efficient when N is a product of small primes.

WSAVE (input)

On entry, an array of dimension $(3 * N + 15)$ or greater. COSQI needs to be called only once to initialize WSAVE before calling COSQF and/or COSQB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

cost - compute the discrete Fourier cosine transform of an even sequence. The COST transforms are unnormalized inverses of themselves, so a call of COST followed by another call of COST will multiply the input sequence by $2 * (N-1)$.

SYNOPSIS

```
SUBROUTINE COST(N, X, WSAVE)
```

```
INTEGER N  
REAL X(*), WSAVE(*)
```

```
SUBROUTINE COST_64(N, X, WSAVE)
```

```
INTEGER*8 N  
REAL X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COST(N, X, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE COST_64(N, X, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cost(int n, float *x, float *wsave);
```

```
void cost_64(long n, float *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when $N - 1$ is a product of small primes. $N \geq 2$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the cosine transform of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$, initialized by COSTI.

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NAME

costi - initialize the array WSAVE, which is used in COST.

SYNOPSIS

```
SUBROUTINE COSTI(N, WSAVE)
```

```
INTEGER N  
REAL WSAVE(*)
```

```
SUBROUTINE COSTI_64(N, WSAVE)
```

```
INTEGER*8 N  
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSTI(N, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: WSAVE
```

```
SUBROUTINE COSTI_64(N, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void costi(int n, float *wsave);
```

```
void costi_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. The method is most efficient when N - 1 is a product of small primes. N >= 2.

WSAVE (input)

On entry, an array of dimension $(3 * N + 15)$ or greater. COSTI is called once to initialize WSAVE before calling COST and need not be called again between calls to COST if N and WSAVE remain unchanged. Thus, subsequent transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

cpbcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite band matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by CPBTRF

SYNOPSIS

```
SUBROUTINE CPBCON(UPLO, N, KD, A, LDA, ANORM, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, KD, LDA, INFO  
REAL ANORM, RCOND  
REAL WORK2(*)
```

```
SUBROUTINE CPBCON_64(UPLO, N, KD, A, LDA, ANORM, RCOND, WORK,  
WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, KD, LDA, INFO  
REAL ANORM, RCOND  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PBCON(UPLO, [N], KD, A, [LDA], ANORM, RCOND, [WORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, KD, LDA, INFO  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE PBCON_64(UPLO, [N], KD, A, [LDA], ANORM, RCOND, [WORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A
INTEGER(8) :: N, KD, LDA, INFO
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK2
C INTERFACE
#include <sunperf.h>

void cpbcon(char uplo, int n, int kd, complex *a, int lda,
            float anorm, float *rcond, int *info);

void cpbcon_64(char uplo, long n, long kd, complex *a, long
               lda, float anorm, float *rcond, long *info);

```

PURPOSE

cpbcon estimates the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite band matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by CPBTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangular factor stored in A;
 = 'L': Lower triangular factor stored in A.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of sub-diagonals if UPLO = 'L'. $KD \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ of the band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of U or L is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = U(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = L(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

LDA (input)
 The leading dimension of the array A. $LDA \geq KD+1$.

ANORM (input)
 The 1-norm (or infinity-norm) of the Hermitian band matrix A.

RCOND (output)
 The reciprocal of the condition number of the

matrix A, computed as $RCOND = 1/(ANORM * AINVNM)$,
where AINVNM is an estimate of the 1-norm of
inv(A) computed in this routine.

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

cpbequ - compute row and column scalings intended to equilibrate a Hermitian positive definite band matrix A and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE CPBEQU(UPLO, N, KD, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER N, KD, LDA, INFO  
REAL SCOND, AMAX  
REAL SCALE(*)
```

```
SUBROUTINE CPBEQU_64(UPLO, N, KD, A, LDA, SCALE, SCOND, AMAX,  
INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER*8 N, KD, LDA, INFO  
REAL SCOND, AMAX  
REAL SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE PBEQU(UPLO, [N], KD, A, [LDA], SCALE, SCOND, AMAX,  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, KD, LDA, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: SCALE
```

```
SUBROUTINE PBEQU_64(UPLO, [N], KD, A, [LDA], SCALE, SCOND, AMAX,  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, KD, LDA, INFO  
REAL :: SCOND, AMAX
```

REAL, DIMENSION(:) :: SCALE

C INTERFACE

```
#include <sunperf.h>
```

```
void cpbequ(char uplo, int n, int kd, complex *a, int lda,  
            float *scale, float *scond, float *amax, int  
            *info);
```

```
void cpbequ_64(char uplo, long n, long kd, complex *a, long  
               lda, float *scale, float *scond, float *amax, long  
               *info);
```

PURPOSE

cpbequ computes row and column scalings intended to equilibrate a Hermitian positive definite band matrix A and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i) = 1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j) = S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular of A is stored;
= 'L': Lower triangular of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input) The upper or lower triangle of the Hermitian band matrix A, stored in the first KD+1 rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

SCALE (output)

If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)

If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND

≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

cpbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and banded, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CPBRFS(UPLO, N, KD, NRHS, A, LDA, AF, LDAF, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CPBRFS_64(UPLO, N, KD, NRHS, A, LDA, AF, LDAF, B, LDB,  
  X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PBRFS(UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF], B,  
  [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, AF, B, X  
INTEGER :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE PBRFS_64(UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF],  
  B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, AF, B, X  
INTEGER(8) :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
```

REAL, DIMENSION(:) :: FERR, BERR, WORK2

C INTERFACE

```
#include <sunperf.h>
```

```
void cpbrfs(char uplo, int n, int kd, int nrhs, complex *a,  
            int lda, complex *af, int ldaf, complex *b, int  
            ldb, complex *x, int ldx, float *ferr, float  
            *berr, int *info);
```

```
void cpbrfs_64(char uplo, long n, long kd, long nrhs, com-  
               plex *a, long lda, complex *af, long ldaf, complex  
               *b, long ldb, complex *x, long ldx, float *ferr,  
               float *berr, long *info);
```

PURPOSE

cpbrfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and banded, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number
of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The upper or lower triangle of the Hermitian band
matrix A, stored in the first $KD+1$ rows of the
array. The j -th column of A is stored in the j -th
column of the array A as follows: if UPLO = 'U',
 $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if
UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for
 $j \leq i \leq \min(n, j+kd)$.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $KD+1$.

AF (input)

The triangular factor U or L from the Cholesky
factorization $A = U^*H^*U$ or $A = L^*L^*H$ of the band
matrix A as computed by CPBTRF, in the same
storage format as A (see A).

LDAF (input)
The leading dimension of the array AF. LDAF \geq KD+1.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by CPBTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cpbstf - compute a split Cholesky factorization of a complex Hermitian positive definite band matrix A

SYNOPSIS

```
SUBROUTINE CPBSTF(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AB(LDAB,*)  
INTEGER N, KD, LDAB, INFO
```

```
SUBROUTINE CPBSTF_64(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AB(LDAB,*)  
INTEGER*8 N, KD, LDAB, INFO
```

F95 INTERFACE

```
SUBROUTINE PBSTF(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: AB  
INTEGER :: N, KD, LDAB, INFO
```

```
SUBROUTINE PBSTF_64(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: AB  
INTEGER(8) :: N, KD, LDAB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpbstf(char uplo, int n, int kd, complex *ab, int ldab,  
            int *info);
```

```
void cpbstf_64(char uplo, long n, long kd, complex *ab, long  
               ldab, long *info);
```

PURPOSE

cpbstf computes a split Cholesky factorization of a complex Hermitian positive definite band matrix A.

This routine is designed to be used in conjunction with CHBGST.

The factorization has the form $A = S^*H^*S$ where S is a band matrix of the same bandwidth as A and the following structure:

$$S = \begin{pmatrix} U & \\ & (M \ L) \end{pmatrix}$$

where U is upper triangular of order $m = (n+kd)/2$, and L is lower triangular of order $n-m$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $kd+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the factor S from the split Cholesky factorization $A = S^*H^*S$. See Further Details.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq kd+1$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the factorization could not be completed, because the updated element $a(i, i)$ was negative; the matrix A is not positive definite.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 7$, $KD = 2$:

```
S = ( s11  s12  s13           )
      (      s22  s23  s24       )
      (           s33  s34       )
      (           s44           )
      (           s53  s54  s55   )
      (           s64  s65  s66   )
      (           s75  s76  s77 )
```

If $UPLO = 'U'$, the array AB holds:

```
on entry:                                on exit:

*      *  a13  a24  a35  a46  a57  *      *  s13  s24  s53'
s64' s75'
*  a12  a23  a34  a45  a56  a67  *  s12  s23  s34  s54'
s65' s76' a11  a22  a33  a44  a55  a66  a77  s11  s22  s33
s44  s55  s66  s77
```

If $UPLO = 'L'$, the array AB holds:

```
on entry:                                on exit:

a11  a22  a33  a44  a55  a66  a77  s11  s22  s33  s44  s55
s66  s77  a21  a32  a43  a54  a65  a76  *  s12' s23' s34'
s54  s65  s76  * a31  a42  a53  a64  a64  *      *  s13'
s24' s53  s64  s75  *      *
```

Array elements marked * are not used by the routine; $s12'$ denotes $\text{conjg}(s12)$; the diagonal elements of S are real.

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NAME

cpbsv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CPBSV(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE CPBSV_64(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE PBSV(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,*) :: A, B  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE PBSV_64(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpbsv(char uplo, int n, int kd, int nrhs, complex *a,  
int lda, complex *b, int ldb, int *info);
```

```
void cpbsv_64(char uplo, long n, long kd, long nrhs, complex
```

```
*a, long lda, complex *b, long ldb, long *info);
```

PURPOSE

cpbsv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N Hermitian positive definite band matrix and X and B are N-by-NRHS matrices.

The Cholesky decomposition is used to factor A as

$A = U^{**H} * U$, if UPLO = 'U', or

$A = L * L^{**H}$, if UPLO = 'L',

where U is an upper triangular band matrix, and L is a lower triangular band matrix, with the same number of superdiagonals or subdiagonals as A. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(KD+1+i-j, j) = A(i, j)$ for $\max(1, j-KD) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(N, j+KD)$. See below for further details.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{**H}U$ or $A = L*L^{**H}$ of the band matrix A, in the same storage format as A.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when N = 6, KD = 2, and UPLO = 'U':

On entry:	On exit:
* * a13 a24 a35 a46	* * u13 u24 u35
u46	
* a12 a23 a34 a45 a56	* u12 u23 u34 u45
u56	
a11 a22 a33 a44 a55 a66	u11 u22 u33 u44 u55
u66	

Similarly, if UPLO = 'L' the format of A is as follows:

On entry:	On exit:
a11 a22 a33 a44 a55 a66	l11 l22 l33 l44 l55
l66	
a21 a32 a43 a54 a65 *	l21 l32 l43 l54 l65
*	
a31 a42 a53 a64 * *	l31 l42 l53 l64 *
*	

Array elements marked * are not used by the routine.

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NAME

cpbsvx - use the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CPBSVX(FACT, UPLO, N, KD, NRHS, A, LDA, AF, LDAF,
    EQUED, S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2,
    INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL RCOND
REAL S(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CPBSVX_64(FACT, UPLO, N, KD, NRHS, A, LDA, AF, LDAF,
    EQUED, S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2,
    INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL RCOND
REAL S(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PBSVX(FACT, UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF],
    EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],
    [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL :: RCOND
REAL, DIMENSION(:) :: S, FERR, BERR, WORK2
```

```

SUBROUTINE PBSVX_64(FACT, UPLO, [N], KD, [NRHS], A, [LDA], AF,
    [LDAF], EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR,
    [WORK], [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL :: RCOND
REAL, DIMENSION(:) :: S, FERR, BERR, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void cpbsvx(char fact, char uplo, int n, int kd, int nrhs,
    complex *a, int lda, complex *af, int ldaf, char
    equed, float *s, complex *b, int ldb, complex *x,
    int ldx, float *rcond, float *ferr, float *berr,
    int *info);

```

```

void cpbsvx_64(char fact, char uplo, long n, long kd, long
    nrhs, complex *a, long lda, complex *af, long
    ldaf, char equed, float *s, complex *b, long ldb,
    complex *x, long ldx, float *rcond, float *ferr,
    float *berr, long *info);

```

PURPOSE

cpbsvx uses the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations

$A * X = B$, where A is an N -by- N Hermitian positive definite band matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$) as

$$A = U^*H * U, \quad \text{if } UPLO = 'U', \text{ or}$$

$$A = L * L^*H, \quad \text{if } UPLO = 'L',$$

where U is an upper triangular band matrix, and L is a lower

triangular band matrix.

3. If the leading i -by- i principal minor is not positive

definite,
 then the routine returns with INFO = i. Otherwise, the factored form of A is used to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.

5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

6. If equilibration was used, the matrix X is premultiplied by diag(S) so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF contains the factored form of A. If EQUED = 'Y', the matrix A has been equilibrated with scaling factors given by S. A and AF will not be modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. N >= 0.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. KD >= 0.

NRHS (input)

The number of right-hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)

On entry, the upper or lower triangle of the Her-

mitian band matrix A, stored in the first KD+1 rows of the array, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix $\text{diag}(S)*A*\text{diag}(S)$. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(KD+1+i-j,j) = A(i,j)$ for $\max(1,j-KD) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(N,j+KD)$. See below for further details.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S)*A*\text{diag}(S)$.

LDA (input)

The leading dimension of the array A. LDA \geq KD+1.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ of the band matrix A, in the same storage format as A (see A). If EQUED = 'Y', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF \geq KD+1.

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

X (output)
 If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is $\text{inv}(\text{diag}(S))*X$.

LDX (input)
 The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)
 The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(2*N)

WORK2 (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, and i is
 <= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is non-singular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 6$, $KD = 2$, and $UPLO = 'U'$:

Two-dimensional storage of the Hermitian matrix A:

```
a11 a12 a13
    a22 a23 a24
        a33 a34 a35
            a44 a45 a46
                a55 a56
(aij=conjg(aji))          a66
```

Band storage of the upper triangle of A:

```
*   *   a13 a24 a35 a46
*   a12 a23 a34 a45 a56
a11 a22 a33 a44 a55 a66
```

Similarly, if $UPLO = 'L'$ the format of A is as follows:

```
a11 a22 a33 a44 a55 a66
a21 a32 a43 a54 a65 *
a31 a42 a53 a64 *   *
```

Array elements marked * are not used by the routine.

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NAME

cpbtf2 - compute the Cholesky factorization of a complex Hermitian positive definite band matrix A

SYNOPSIS

```
SUBROUTINE CPBTF2(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AB(LDAB,*)  
INTEGER N, KD, LDAB, INFO
```

```
SUBROUTINE CPBTF2_64(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AB(LDAB,*)  
INTEGER*8 N, KD, LDAB, INFO
```

F95 INTERFACE

```
SUBROUTINE PBTf2(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: AB  
INTEGER :: N, KD, LDAB, INFO
```

```
SUBROUTINE PBTf2_64(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: AB  
INTEGER(8) :: N, KD, LDAB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpbtf2(char uplo, int n, int kd, complex *ab, int ldab,  
            int *info);
```

```
void cpbtf2_64(char uplo, long n, long kd, complex *ab, long  
               ldab, long *info);
```

PURPOSE

cpbtf2 computes the Cholesky factorization of a complex Hermitian positive definite band matrix A.

The factorization has the form

$A = U' * U$, if UPLO = 'U', or

$A = L * L'$, if UPLO = 'L',

where U is an upper triangular matrix, U' is the conjugate transpose of U, and L is lower triangular.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the Hermitian matrix A is stored:

= 'U': Upper triangular

= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of super-diagonals of the matrix A if UPLO = 'U', or the number of sub-diagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first KD+1 rows of the array. The j-th column of A is stored in the j-th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U' * U$ or $A = L * L'$ of the band matrix A, in the same storage format as A.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq KD+1$.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, the leading minor of order k is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 6$, $KD = 2$, and $UPLD = 'U'$:

On entry:						On exit:				
* *	a13	a24	a35	a46		* *	u13	u24	u35	
u46										
* a12	a23	a34	a45	a56		* u12	u23	u34	u45	
u56										
a11	a22	a33	a44	a55	a66	u11	u22	u33	u44	u55
u66										

Similarly, if $UPLD = 'L'$ the format of A is as follows:

On entry:						On exit:				
a11	a22	a33	a44	a55	a66	l11	l22	l33	l44	l55
l66										
a21	a32	a43	a54	a65	*	l21	l32	l43	l54	l65
*										
a31	a42	a53	a64	*	*	l31	l42	l53	l64	*
*										

Array elements marked * are not used by the routine.

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NAME

cpbtrf - compute the Cholesky factorization of a complex Hermitian positive definite band matrix A

SYNOPSIS

```
SUBROUTINE CPBTRF(UPLO, N, KD, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER N, KD, LDA, INFO
```

```
SUBROUTINE CPBTRF_64(UPLO, N, KD, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER*8 N, KD, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE PBTRF(UPLO, [N], KD, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, KD, LDA, INFO
```

```
SUBROUTINE PBTRF_64(UPLO, [N], KD, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, KD, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpbtrf(char uplo, int n, int kd, complex *a, int lda,  
            int *info);
```

```
void cpbtrf_64(char uplo, long n, long kd, complex *a, long  
               lda, long *info);
```

PURPOSE

cpbtrf computes the Cholesky factorization of a complex Hermitian positive definite band matrix A.

The factorization has the form

$A = U^{*H} * U$, if UPLO = 'U', or

$A = L * L^{*H}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{*H}U$ or $A = L * L^{*H}$ of the band matrix A, in the same storage format as A.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The band storage scheme is illustrated by the following

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NAME

cpbtrs - solve a system of linear equations $A \cdot X = B$ with a Hermitian positive definite band matrix A using the Cholesky factorization $A = U \cdot H \cdot U$ or $A = L \cdot L \cdot H$ computed by CPBTRF

SYNOPSIS

```
SUBROUTINE CPBTRS(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE CPBTRS_64(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE PBTRS(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE PBTRS_64(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpbtrs(char uplo, int n, int kd, int nrhs, complex *a,  
int lda, complex *b, int ldb, int *info);
```

```
void cpbtrs_64(char uplo, long n, long kd, long nrhs, com-  
plex *a, long lda, complex *b, long ldb, long
```

```
*info);
```

PURPOSE

cpbtrs solves a system of linear equations $A \cdot X = B$ with a Hermitian positive definite band matrix A using the Cholesky factorization $A = U \cdot U^H$ or $A = L \cdot L^H$ computed by CPBTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular factor stored in A;
= 'L': Lower triangular factor stored in A.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number
of columns of the matrix B. $NRHS \geq 0$.

A (input) The triangular factor U or L from the Cholesky
factorization $A = U \cdot U^H$ or $A = L \cdot L^H$ of the band
matrix A, stored in the first $KD+1$ rows of the
array. The j-th column of U or L is stored in the
j-th column of the array A as follows: if UPLO
= 'U', $A(kd+1+i-j, j) = U(i, j)$ for $\max(1, j-
kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = L(i, j)$
for $j \leq i \leq \min(n, j+kd)$.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $KD+1$.

B (input/output)

On entry, the right hand side matrix B. On exit,
the solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq$
 $\max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

cpocon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by CPOTRF

SYNOPSIS

```
SUBROUTINE CPOCON(UPLO, N, A, LDA, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
REAL ANORM, RCOND  
REAL WORK2(*)
```

```
SUBROUTINE CPOCON_64(UPLO, N, A, LDA, ANORM, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
REAL ANORM, RCOND  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE POCON(UPLO, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE POCON_64(UPLO, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK
```

```
COMPLEX, DIMENSION(:,:) :: A
INTEGER(8) :: N, LDA, INFO
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void cpocon(char uplo, int n, complex *a, int lda, float
            anorm, float *rcond, int *info);

void cpocon_64(char uplo, long n, complex *a, long lda,
              float anorm, float *rcond, long *info);
```

PURPOSE

cpocon estimates the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$ computed by CPOTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$, as computed by CPOTRF.

LDA (input)
The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

ANORM (input)
The 1-norm (or infinity-norm) of the Hermitian matrix A.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cpoequ - compute row and column scalings intended to equilibrate a Hermitian positive definite matrix A and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE CPOEQU(N, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO  
REAL SCOND, AMAX  
REAL SCALE(*)
```

```
SUBROUTINE CPOEQU_64(N, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO  
REAL SCOND, AMAX  
REAL SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE POEQU([N], A, [LDA], SCALE, SCOND, AMAX, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: SCALE
```

```
SUBROUTINE POEQU_64([N], A, [LDA], SCALE, SCOND, AMAX, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpoequ(int n, complex *a, int lda, float *scale, float  
           *scond, float *amax, int *info);
```

```
void cpoequ_64(long n, complex *a, long lda, float *scale,
               float *scond, float *amax, long *info);
```

PURPOSE

cpoequ computes row and column scalings intended to equilibrate a Hermitian positive definite matrix A and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i) = 1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j) = S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

A (input) The N-by-N Hermitian positive definite matrix whose scaling factors are to be computed. Only the diagonal elements of A are referenced.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

SCALE (output)
If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)
If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)
Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

cporfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite,

SYNOPSIS

```
SUBROUTINE CPORFS(UPLO, N, NRHS, A, LDA, AF, LDAF, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CPORFS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PORFS(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE PORFS_64(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, AF, B, X  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void cporfs(char uplo, int n, int nrhs, complex *a, int lda,
            complex *af, int ldaf, complex *b, int ldb, com-
            plex *x, int ldx, float *ferr, float *berr, int
            *info);

void cporfs_64(char uplo, long n, long nrhs, complex *a,
              long lda, complex *af, long ldaf, complex *b, long
              ldb, complex *x, long ldx, float *ferr, float
              *berr, long *info);
```

PURPOSE

cporfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)
The triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$, as computed by CPOTRF.

LDAF (input)
The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by CPOTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cposv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CPOSV(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE CPOSV_64(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE POSV(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,*) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE POSV_64(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cposv(char uplo, int n, int nrhs, complex *a, int lda,  
          complex *b, int ldb, int *info);
```

```
void cposv_64(char uplo, long n, long nrhs, complex *a, long  
             lda, complex *b, long ldb, long *info);
```

PURPOSE

cposv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N Hermitian positive definite matrix and X and B are N-by-NRHS matrices.

The Cholesky decomposition is used to factor A as

$A = U^{*}H*U$, if UPLO = 'U', or

$A = L * L^{*}H$, if UPLO = 'L',

where U is an upper triangular matrix and L is a lower triangular matrix. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{*}H*U$ or $A = L*L^{*}H$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i of

A is not positive definite, so the factorization could not be completed, and the solution has not been computed.

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NAME

cposvx - use the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CPOSVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, EQUED,  
  S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL RCOND  
REAL S(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CPOSVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, EQUED,  
  S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL RCOND  
REAL S(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE POSVX(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],  
  EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],  
  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: S, FERR, BERR, WORK2
```

```
SUBROUTINE POSVX_64(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],  
  EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],  
  [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL :: RCOND
REAL, DIMENSION(:) :: S, FERR, BERR, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void cposvx(char fact, char uplo, int n, int nrhs, complex
           *a, int lda, complex *af, int ldaf, char equed,
           float *s, complex *b, int ldb, complex *x, int
           ldx, float *rcond, float *ferr, float *berr, int
           *info);

```

```

void cposvx_64(char fact, char uplo, long n, long nrhs, com-
              plex *a, long lda, complex *af, long ldaf, char
              equed, float *s, complex *b, long ldb, complex *x,
              long ldx, float *rcond, float *ferr, float *berr,
              long *info);

```

PURPOSE

cposvx uses the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations

$A * X = B$, where A is an N -by- N Hermitian positive definite matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A

is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$)

as

$$A = U^*H^*U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L^*H, \text{ if } UPLO = 'L',$$

where U is an upper triangular matrix and L is a lower triangular

matrix.

3. If the leading i -by- i principal minor is not positive definite,

then the routine returns with $INFO = i$. Otherwise, the factored

form of A is used to estimate the condition number of the matrix

A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.

5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

6. If equilibration was used, the matrix X is premultiplied by diag(S) so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF contains the factored form of A. If EQUED = 'Y', the matrix A has been equilibrated with scaling factors given by S. A and AF will not be modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)

On entry, the Hermitian matrix A, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix diag(S)*A*diag(S). If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced. A

is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S)*A*\text{diag}(S)$.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$, in the same storage format as A. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix $\text{diag}(S)*A*\text{diag}(S)$.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF \geq max(1,N).

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output)

On entry, the N-by-NRHS righthand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations.

Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is $\text{inv}(\text{diag}(S)) * X$.

LDX (input)

The leading dimension of the array X. $\text{LDX} \geq \max(1, N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if $\text{RCOND} = 0$), the matrix is singular to working precision. This condition is indicated by a return code of $\text{INFO} > 0$.

FERR (output)

The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If XTRUE is the true solution corresponding to $X(j)$, $\text{FERR}(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - \text{XTRUE})$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension($2 * N$)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value
> 0: if $\text{INFO} = i$, and i is
<= N : the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. $\text{RCOND} = 0$ is returned. = $N+1$: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

cpotf2 - compute the Cholesky factorization of a complex Hermitian positive definite matrix A

SYNOPSIS

```
SUBROUTINE CPOTF2(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE CPOTF2_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE POTF2(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE POTF2_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpotf2(char uplo, int n, complex *a, int lda, int  
*info);
```

```
void cpotf2_64(char uplo, long n, complex *a, long lda, long  
*info);
```

PURPOSE

cpotf2 computes the Cholesky factorization of a complex Hermitian positive definite matrix A.

The factorization has the form

$A = U^* U$, if UPLO = 'U', or

$A = L L^*$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the Hermitian matrix A is stored. = 'U': Upper triangular
= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading n by n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n by n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^*U$ or $A = L L^*$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, the leading minor of order k is not positive definite, and the factorization could not be completed.

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NAME

cpotrf - compute the Cholesky factorization of a complex Hermitian positive definite matrix A

SYNOPSIS

```
SUBROUTINE CPOTRF(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE CPOTRF_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE POTRF(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE POTRF_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpotrf(char uplo, int n, complex *a, int lda, int  
*info);
```

```
void cpotrf_64(char uplo, long n, complex *a, long lda, long  
*info);
```

PURPOSE

cpotrf computes the Cholesky factorization of a complex Hermitian positive definite matrix A.

The factorization has the form

$A = U^{*H} * U$, if UPLO = 'U', or

$A = L * L^{*H}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

This is the block version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{*H}U$ or $A = L^{*H}L$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

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NAME

cpotri - compute the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$ computed by CPOTRF

SYNOPSIS

```
SUBROUTINE CPOTRI(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE CPOTRI_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE POTRI(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE POTRI_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpotri(char uplo, int n, complex *a, int lda, int  
*info);
```

```
void cpotri_64(char uplo, long n, complex *a, long lda, long  
*info);
```

PURPOSE

cpotri computes the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by CPOTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$, as computed by CPOTRF. On exit, the upper or lower triangle of the (Hermitian) inverse of A, overwriting the input factor U or L.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, the (i,i) element of the factor U or L is zero, and the inverse could not be computed.

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NAME

cpotrs - solve a system of linear equations $A \cdot X = B$ with a Hermitian positive definite matrix A using the Cholesky factorization $A = U \cdot H \cdot U$ or $A = L \cdot L^* \cdot H$ computed by CPOTRF

SYNOPSIS

```
SUBROUTINE CPOTRS(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE CPOTRS_64(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE POTRS(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE POTRS_64(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpotrs(char uplo, int n, int nrhs, complex *a, int lda,  
            complex *b, int ldb, int *info);
```

```
void cpotrs_64(char uplo, long n, long nrhs, complex *a,  
               long lda, complex *b, long ldb, long *info);
```

PURPOSE

cpotrs solves a system of linear equations $A \cdot X = B$ with a Hermitian positive definite matrix A using the Cholesky factorization $A = U^*H \cdot U$ or $A = L \cdot L^*H$ computed by CPOTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U^*H \cdot U$ or $A = L \cdot L^*H$, as computed by CPOTRF.

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

B (input/output)

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

cppcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite packed matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by CPPTRF

SYNOPSIS

```
SUBROUTINE CPPCON(UPLO, N, A, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
REAL ANORM, RCOND  
REAL WORK2(*)
```

```
SUBROUTINE CPPCON_64(UPLO, N, A, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
REAL ANORM, RCOND  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PPCON(UPLO, [N], A, ANORM, RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE PPCON_64(UPLO, [N], A, ANORM, RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>

void cppcon(char uplo, int n, complex *a, float anorm, float
             *rcond, int *info);
void cppcon_64(char uplo, long n, complex *a, float anorm,
               float *rcond, long *info);
```

PURPOSE

cppcon estimates the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite packed matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by CPPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) COMPLEX array, dimension $(N*(N+1)/2)$

The triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$, packed columnwise in a linear array. The j-th column of U or L is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = U(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = L(i,j)$ for $j \leq i \leq n$.

ANORM (input)

The 1-norm (or infinity-norm) of the Hermitian matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

COMPLEX array, dimension $(2*N)$

WORK2 (workspace)

REAL array, dimension (N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cppequ - compute row and column scalings intended to equilibrate a Hermitian positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE CPPEQU(UPLO, N, A, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*)  
INTEGER N, INFO  
REAL SCOND, AMAX  
REAL SCALE(*)
```

```
SUBROUTINE CPPEQU_64(UPLO, N, A, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*)  
INTEGER*8 N, INFO  
REAL SCOND, AMAX  
REAL SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE PPEQU(UPLO, [N], A, SCALE, SCOND, AMAX, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
INTEGER :: N, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: SCALE
```

```
SUBROUTINE PPEQU_64(UPLO, [N], A, SCALE, SCOND, AMAX, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
INTEGER(8) :: N, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: SCALE
```

C INTERFACE

```
#include <sunperf.h>

void cppequ(char uplo, int n, complex *a, float *scale,
            float *scond, float *amax, int *info);
void cppequ_64(char uplo, long n, complex *a, float *scale,
              float *scond, float *amax, long *info);
```

PURPOSE

cppequ computes row and column scalings intended to equilibrate a Hermitian positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i)=1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j)=S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) COMPLEX array, dimension $(N*(N+1)/2)$
The upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

SCALE (output) REAL array, dimension (N)
If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)
If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)
Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

cpprfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CPPRFS(UPLO, N, NRHS, A, AF, B, LDB, X, LDX, FERR, BERR,  
                 WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CPPRFS_64(UPLO, N, NRHS, A, AF, B, LDB, X, LDX, FERR,  
                   BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PPRFS(UPLO, [N], [NRHS], A, AF, B, [LDB], X, [LDX], FERR,  
                BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, AF, WORK  
COMPLEX, DIMENSION(:, :) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE PPRFS_64(UPLO, [N], [NRHS], A, AF, B, [LDB], X, [LDX], FERR,  
                   BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, AF, WORK  
COMPLEX, DIMENSION(:, :) :: B, X  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

REAL, DIMENSION(:) :: FERR, BERR, WORK2

C INTERFACE

```
#include <sunperf.h>
```

```
void cprfs(char uplo, int n, int nrhs, complex *a, complex  
          *af, complex *b, int ldb, complex *x, int ldx,  
          float *ferr, float *berr, int *info);
```

```
void cprfs_64(char uplo, long n, long nrhs, complex *a,  
             complex *af, complex *b, long ldb, complex *x,  
             long ldx, float *ferr, float *berr, long *info);
```

PURPOSE

cprfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) COMPLEX array, dimension $(N*(N+1)/2)$

The upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

AF (input) COMPLEX array, dimension $(N*(N+1)/2)$

The triangular factor U or L from the Cholesky factorization $A = U*H*U$ or $A = L*L*H$, as computed by SPPTRF/CPPTFR, packed columnwise in a linear array in the same format as A (see A).

B (input) COMPLEX array, dimension $(LDB, NRHS)$

The right hand side matrix B.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (input/output) COMPLEX array, dimension $(LDX, NRHS)$

On entry, the solution matrix X, as computed by CPPTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

FERR (output) REAL array, dimension (NRHS)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) REAL array, dimension (NRHS)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
COMPLEX array, dimension(2*N)

WORK2 (workspace)
REAL array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cppsv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CPPSV(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO
```

```
SUBROUTINE CPPSV_64(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE PPSV(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO
```

```
SUBROUTINE PPSV_64(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cppsv(char uplo, int n, int nrhs, complex *a, complex  
          *b, int ldb, int *info);
```

```
void cppsv_64(char uplo, long n, long nrhs, complex *a, complex *b, long ldb, long *info);
```

PURPOSE

cppsv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N -by- N Hermitian positive definite matrix stored in packed format and X and B are N -by- $NRHS$ matrices.

The Cholesky decomposition is used to factor A as

$A = U^{*}H*U$, if $UPLO = 'U'$, or

$A = L * L^{*}H$, if $UPLO = 'L'$,

where U is an upper triangular matrix and L is a lower triangular matrix. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A , packed columnwise in a linear array. The j -th column of A is stored in the array A as follows: if $UPLO = 'U'$, $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if $UPLO = 'L'$, $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, if $INFO = 0$, the factor U or L from the Cholesky factorization $A = U^{*}H*U$ or $A = L*L^{*}H$, in the same storage format as A .

B (input/output) COMPLEX array, dimension $(LDB, NRHS)$

On entry, the N -by- $NRHS$ right hand side matrix B . On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an ille-

gal value
> 0: if INFO = i, the leading minor of order i of
A is not positive definite, so the factorization
could not be completed, and the solution has not
been computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following
example when N = 4, UPLO = 'U':

Two-dimensional storage of the Hermitian matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34 (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

```
A = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

cppsvx - use the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CPPSVX(FACT, UPLO, N, NRHS, A, AF, EQUED, S, B, LDB,
  X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
REAL RCOND
REAL S(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CPPSVX_64(FACT, UPLO, N, NRHS, A, AF, EQUED, S, B,
  LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
REAL RCOND
REAL S(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PPSVX(FACT, UPLO, [N], [NRHS], A, AF, EQUED, S, B,
  [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX, DIMENSION(:) :: A, AF, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
REAL :: RCOND
REAL, DIMENSION(:) :: S, FERR, BERR, WORK2
```

```
SUBROUTINE PPSVX_64(FACT, UPLO, [N], [NRHS], A, AF, EQUED, S, B,
  [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX, DIMENSION(:) :: A, AF, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
REAL :: RCOND
REAL, DIMENSION(:) :: S, FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>
void cppsvox(char fact, char uplo, int n, int nrhs, complex
             *a, complex *af, char equed, float *s, complex *b,
             int ldb, complex *x, int ldx, float *rcond, float
             *ferr, float *berr, int *info);

void cppsvox_64(char fact, char uplo, long n, long nrhs, com-
                plex *a, complex *af, char equed, float *s, com-
                plex *b, long ldb, complex *x, long ldx, float
                *rcond, float *ferr, float *berr, long *info);

```

PURPOSE

cppsvx uses the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations

$A * X = B$, where A is an N -by- N Hermitian positive definite matrix stored in packed format and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$) as

$$A = U^* * U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L', \text{ if } UPLO = 'L',$$

where U is an upper triangular matrix, L is a lower triangular

matrix, and $'$ indicates conjugate transpose.

3. If the leading i -by- i principal minor is not positive definite,

then the routine returns with $INFO = i$. Otherwise, the factored

form of A is used to estimate the condition number of the matrix

- A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
4. The system of equations is solved for X using the factored form of A.
5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.
6. If equilibration was used, the matrix X is premultiplied by $\text{diag}(S)$ so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF contains the factored form of A. If EQUED = 'Y', the matrix A has been equilibrated with scaling factors given by S. A and AF will not be modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $\text{NRHS} \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix $\text{diag}(S)*A*\text{diag}(S)$. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S) * A * \text{diag}(S)$.

AF (input or output) COMPLEX array, dimension $(N*(N+1)/2)$
If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U * H * U$ or $A = L * L * H$, in the same storage format as A. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * H * U$ or $A = L * L * H$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * H * U$ or $A = L * L * H$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

EQUED (input or output)
Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output) REAL array, dimension (N)
The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output) COMPLEX array, dimension (LDB, NRHS)
On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (output) COMPLEX array, dimension (LDX, NRHS)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is $\text{inv}(\text{diag}(S)) * X$.

LDX (input)
The leading dimension of the array X. $LDX \geq \max(1, N)$.

RCOND (output)
The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If

RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output) REAL array, dimension (NRHS)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) REAL array, dimension (NRHS)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

COMPLEX array, dimension(2*N)

WORK2 (workspace)

REAL array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when N = 4, UPLO = 'U':

Two-dimensional storage of the Hermitian matrix A:

```
  a11 a12 a13 a14
    a22 a23 a24
      a33 a34   (aij = conjg(aji))
        a44
```

Packed storage of the upper triangle of A:

```
A = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```


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NAME

cpptrf - compute the Cholesky factorization of a complex Hermitian positive definite matrix A stored in packed format

SYNOPSIS

```
SUBROUTINE CPPTRF(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*)  
INTEGER N, INFO
```

```
SUBROUTINE CPPTRF_64(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*)  
INTEGER*8 N, INFO
```

F95 INTERFACE

```
SUBROUTINE PPTRF(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
INTEGER :: N, INFO
```

```
SUBROUTINE PPTRF_64(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
INTEGER(8) :: N, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpptrf(char uplo, int n, complex *a, int *info);
```

```
void cpptrf_64(char uplo, long n, complex *a, long *info);
```

PURPOSE

cpptrf computes the Cholesky factorization of a complex Hermitian positive definite matrix A stored in packed format.

The factorization has the form

$A = U^{*H} * U$, if UPLO = 'U', or

$A = L * L^{*H}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{*H} * U$ or $A = L * L^{*H}$, in the same storage format as A.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, UPLO = 'U':

Two-dimensional storage of the Hermitian matrix A:

```
a11 a12 a13 a14
  a22 a23 a24
    a33 a34      (aij = conjg(aji))
      a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

cpptri - compute the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$ computed by CPPTRF

SYNOPSIS

```
SUBROUTINE CPPTRI(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*)  
INTEGER N, INFO
```

```
SUBROUTINE CPPTRI_64(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*)  
INTEGER*8 N, INFO
```

F95 INTERFACE

```
SUBROUTINE PPTRI(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
INTEGER :: N, INFO
```

```
SUBROUTINE PPTRI_64(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
INTEGER(8) :: N, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpptri(char uplo, int n, complex *a, int *info);
```

```
void cpptri_64(char uplo, long n, complex *a, long *info);
```

PURPOSE

cpptri computes the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$ computed by CPPTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular factor is stored in A;
= 'L': Lower triangular factor is stored in A.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$, packed columnwise as a linear array. The j-th column of U or L is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = U(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = L(i,j)$ for $j \leq i \leq n$.

On exit, the upper or lower triangle of the (Hermitian) inverse of A, overwriting the input factor U or L.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the (i,i) element of the factor U or L is zero, and the inverse could not be computed.

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NAME

cpptrs - solve a system of linear equations $A^*X = B$ with a Hermitian positive definite matrix A in packed storage using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by CPPTRF

SYNOPSIS

```
SUBROUTINE CPPTRS(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO
```

```
SUBROUTINE CPPTRS_64(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE PPTRS(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO
```

```
SUBROUTINE PPTRS_64(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpptrs(char uplo, int n, int nrhs, complex *a, complex  
            *b, int ldb, int *info);
```

```
void cpptrs_64(char uplo, long n, long nrhs, complex *a,
               complex *b, long ldb, long *info);
```

PURPOSE

cpptrs solves a system of linear equations $A \cdot X = B$ with a Hermitian positive definite matrix A in packed storage using the Cholesky factorization $A = U \cdot U^H$ or $A = L \cdot L^H$ computed by CPPTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) COMPLEX array, dimension $(N \cdot (N+1) / 2)$

The triangular factor U or L from the Cholesky factorization $A = U \cdot U^H$ or $A = L \cdot L^H$, packed columnwise in a linear array. The j -th column of U or L is stored in the array A as follows: if $UPLO = 'U'$, $A(i + (j-1) \cdot j / 2) = U(i, j)$ for $1 \leq i \leq j$; if $UPLO = 'L'$, $A(i + (j-1) \cdot (2n-j) / 2) = L(i, j)$ for $j \leq i \leq n$.

B (input/output) COMPLEX array, dimension $(LDB, NRHS)$

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

cptcon - compute the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite tridiagonal matrix using the factorization $A = L^*D^*L^*H$ or $A = U^*H^*D^*U$ computed by CPTTRF

SYNOPSIS

```
SUBROUTINE CPTCON(N, D, E, ANORM, RCOND, WORK, INFO)
```

```
COMPLEX E(*)
INTEGER N, INFO
REAL ANORM, RCOND
REAL D(*), WORK(*)
```

```
SUBROUTINE CPTCON_64(N, D, E, ANORM, RCOND, WORK, INFO)
```

```
COMPLEX E(*)
INTEGER*8 N, INFO
REAL ANORM, RCOND
REAL D(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTCON([N], D, E, ANORM, RCOND, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: E
INTEGER :: N, INFO
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: D, WORK
```

```
SUBROUTINE PTCON_64([N], D, E, ANORM, RCOND, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: E
INTEGER(8) :: N, INFO
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: D, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cptcon(int n, float *d, complex *e, float anorm, float
            *rcond, int *info);
```

```
void cptcon_64(long n, float *d, complex *e, float anorm,
              float *rcond, long *info);
```

PURPOSE

cptcon computes the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite tridiagonal matrix using the factorization $A = L^*D^*L^{**}H$ or $A = U^{**}H^*D^*U$ computed by CPTTRF.

Norm(inv(A)) is computed by a direct method, and the reciprocal of the condition number is computed as

$$RCOND = 1 / (ANORM * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the factorization of A, as computed by CPTTRF.

E (input) The (n-1) off-diagonal elements of the unit bidiagonal factor U or L from the factorization of A, as computed by CPTTRF.

ANORM (input)
The 1-norm of the original matrix A.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $RCOND = 1 / (ANORM * AINVNM)$, where AINVNM is the 1-norm of inv(A) computed in this routine.

WORK (workspace)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The method used is described in Nicholas J. Higham, "Efficient Algorithms for Computing the Condition Number of a Tridiagonal Matrix", SIAM J. Sci. Stat. Comput., Vol. 7, No. 1, January 1986.

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cpteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using SPTTRF and then calling CBDSQR to compute the singular values of the bidiagonal factor

SYNOPSIS

```
SUBROUTINE CPTEQR(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
COMPLEX Z(LDZ,*)  
INTEGER N, LDZ, INFO  
REAL D(*), E(*), WORK(*)
```

```
SUBROUTINE CPTEQR_64(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
COMPLEX Z(LDZ,*)  
INTEGER*8 N, LDZ, INFO  
REAL D(*), E(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTEQR(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX, DIMENSION(:, :) :: Z  
INTEGER :: N, LDZ, INFO  
REAL, DIMENSION(:) :: D, E, WORK
```

```
SUBROUTINE PTEQR_64(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX, DIMENSION(:, :) :: Z  
INTEGER(8) :: N, LDZ, INFO  
REAL, DIMENSION(:) :: D, E, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```

void cpteqr(char compz, int n, float *d, float *e, complex
            *z, int ldz, int *info);

void cpteqr_64(char compz, long n, float *d, float *e, complex
               *z, long ldz, long *info);

```

PURPOSE

cpteqr computes all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using SPTTRF and then calling CBDSQR to compute the singular values of the bidiagonal factor.

This routine computes the eigenvalues of the positive definite tridiagonal matrix to high relative accuracy. This means that if the eigenvalues range over many orders of magnitude in size, then the small eigenvalues and corresponding eigenvectors will be computed more accurately than, for example, with the standard QR method.

The eigenvectors of a full or band positive definite Hermitian matrix can also be found if CHETRD, CHPTRD, or CHBTRD has been used to reduce this matrix to tridiagonal form. (The reduction to tridiagonal form, however, may preclude the possibility of obtaining high relative accuracy in the small eigenvalues of the original matrix, if these eigenvalues range over many orders of magnitude.)

ARGUMENTS

COMPZ (input)

= 'N': Compute eigenvalues only.
 = 'V': Compute eigenvectors of original Hermitian matrix also. Array Z contains the unitary matrix used to reduce the original matrix to tridiagonal form. = 'I': Compute eigenvectors of tridiagonal matrix also.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix. On normal exit, D contains the eigenvalues, in descending order.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input)

On entry, if COMPZ = 'V', the unitary matrix used in the reduction to tridiagonal form. On exit, if COMPZ = 'V', the orthonormal eigenvectors of the original Hermitian matrix; if COMPZ = 'I', the orthonormal eigenvectors of the tridiagonal

matrix. If INFO > 0 on exit, Z contains the eigenvectors associated with only the stored eigenvalues. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1, and if COMPZ = 'V' or 'I', LDZ >= max(1,N).

WORK (workspace)

dimension(4*N)

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, and i is: <= N the Cholesky factorization of the matrix could not be performed because the i-th principal minor was not positive definite. > N the SVD algorithm failed to converge; if INFO = N+i, i off-diagonal elements of the bidiagonal factor did not converge to zero.

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cptrfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CPTRFS(UPLO, N, NRHS, D, E, DF, EF, B, LDB, X,  
                  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX E(*), EF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
REAL D(*), DF(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CPTRFS_64(UPLO, N, NRHS, D, E, DF, EF, B, LDB,  
                    X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX E(*), EF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
REAL D(*), DF(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PTRFS(UPLO, [N], [NRHS], D, E, DF, EF, B, [LDB],  
                X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: E, EF, WORK  
COMPLEX, DIMENSION(:, :) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL, DIMENSION(:) :: D, DF, FERR, BERR, WORK2
```

```
SUBROUTINE PTRFS_64(UPLO, [N], [NRHS], D, E, DF, EF, B,  
                   [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: E, EF, WORK  
COMPLEX, DIMENSION(:, :) :: B, X  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

REAL, DIMENSION(:) :: D, DF, FERR, BERR, WORK2

C INTERFACE

```
#include <sunperf.h>
```

```
void cptrfs(char uplo, int n, int nrhs, float *d, complex  
*e, float *df, complex *ef, complex *b, int ldb,  
complex *x, int ldx, float *ferr, float *berr, int  
*info);
```

```
void cptrfs_64(char uplo, long n, long nrhs, float *d, com-  
plex *e, float *df, complex *ef, complex *b, long  
ldb, complex *x, long ldx, float *ferr, float  
*berr, long *info);
```

PURPOSE

cptrfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

Specifies whether the superdiagonal or the subdiagonal of the tridiagonal matrix A is stored and the form of the factorization:

= 'U': E is the superdiagonal of A, and $A = U^*H^*D*U$;

= 'L': E is the subdiagonal of A, and $A = L^*D*L^*H$. (The two forms are equivalent if A is real.)

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

D (input) The n real diagonal elements of the tridiagonal matrix A.

E (input) The (n-1) off-diagonal elements of the tridiagonal matrix A (see UPLO).

DF (input)

The n diagonal elements of the diagonal matrix D from the factorization computed by CPTTRF.

EF (input)

The (n-1) off-diagonal elements of the unit bidiagonal factor U or L from the factorization computed by CPTTRF (see UPLO).

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by CPTTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
The forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j).

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
dimension(N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cptsv - compute the solution to a complex system of linear equations $A^*X = B$, where A is an N-by-N Hermitian positive definite tridiagonal matrix, and X and B are N-by-NRHS matrices.

SYNOPSIS

```
SUBROUTINE CPTSV(N, NRHS, D, E, B, LDB, INFO)
```

```
COMPLEX E(*), B(LDB,*)
INTEGER N, NRHS, LDB, INFO
REAL D(*)
```

```
SUBROUTINE CPTSV_64(N, NRHS, D, E, B, LDB, INFO)
```

```
COMPLEX E(*), B(LDB,*)
INTEGER*8 N, NRHS, LDB, INFO
REAL D(*)
```

F95 INTERFACE

```
SUBROUTINE PTVS([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
COMPLEX, DIMENSION(:) :: E
COMPLEX, DIMENSION(:, :) :: B
INTEGER :: N, NRHS, LDB, INFO
REAL, DIMENSION(:) :: D
```

```
SUBROUTINE PTVS_64([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
COMPLEX, DIMENSION(:) :: E
COMPLEX, DIMENSION(:, :) :: B
INTEGER(8) :: N, NRHS, LDB, INFO
REAL, DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cptsv(int n, int nrhs, float *d, complex *e, complex
          *b, int ldb, int *info);
```

```
void cptsv_64(long n, long nrhs, float *d, complex *e, complex *b, long ldb, long *info);
```

PURPOSE

cptsv computes the solution to a complex system of linear equations $A \cdot X = B$, where A is an N -by- N Hermitian positive definite tridiagonal matrix, and X and B are N -by- $NRHS$ matrices.

A is factored as $A = L \cdot D \cdot L^* \cdot H$, and the factored form of A is then used to solve the system of equations.

ARGUMENTS

N (input) The order of the matrix A . $N \geq 0$.

$NRHS$ (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A . On exit, the n diagonal elements of the diagonal matrix D from the factorization $A = L \cdot D \cdot L^* \cdot H$.

E (input/output)

On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix A . On exit, the $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the $L \cdot D \cdot L^* \cdot H$ factorization of A . E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the $U \cdot H \cdot D \cdot U$ factorization of A .

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B . On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

$INFO$ (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, the leading minor of order i is not positive definite, and the solution has not been computed. The factorization has not been completed unless $i = N$.

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NAME

cptsvx - use the factorization $A = L*D*L^*H$ to compute the solution to a complex system of linear equations $A*X = B$, where A is an N-by-N Hermitian positive definite tridiagonal matrix and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE CPTSVX(FACT, N, NRHS, D, E, DF, EF, B, LDB, X,  
                 LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT  
COMPLEX E(*), EF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
REAL RCOND  
REAL D(*), DF(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CPTSVX_64(FACT, N, NRHS, D, E, DF, EF, B, LDB,  
                    X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT  
COMPLEX E(*), EF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
REAL RCOND  
REAL D(*), DF(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PTSVX(FACT, [N], [NRHS], D, E, DF, EF, B, [LDB],  
                X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT  
COMPLEX, DIMENSION(:) :: E, EF, WORK  
COMPLEX, DIMENSION(:, :) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: D, DF, FERR, BERR, WORK2
```

```
SUBROUTINE PTSVX_64(FACT, [N], [NRHS], D, E, DF, EF, B,  
                  [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT
```

```

COMPLEX, DIMENSION(:) :: E, EF, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
REAL :: RCOND
REAL, DIMENSION(:) :: D, DF, FERR, BERR, WORK2
C INTERFACE
#include <sunperf.h>

void cptsvx(char fact, int n, int nrhs, float *d, complex
            *e, float *df, complex *ef, complex *b, int ldb,
            complex *x, int ldx, float *rcond, float *ferr,
            float *berr, int *info);

void cptsvx_64(char fact, long n, long nrhs, float *d, com-
               plex *e, float *df, complex *ef, complex *b, long
               ldb, complex *x, long ldx, float *rcond, float
               *ferr, float *berr, long *info);

```

PURPOSE

cptsvx uses the factorization $A = L^*D^*L^{**}H$ to compute the solution to a complex system of linear equations $A^*X = B$, where A is an N -by- N Hermitian positive definite tridiagonal matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If `FACT = 'N'`, the matrix A is factored as $A = L^*D^*L^{**}H$, where L is a unit lower bidiagonal matrix and D is diagonal. The factorization can also be regarded as having the form $A = U^{**}H^*D^*U$.
2. If the leading i -by- i principal minor is not positive definite, then the routine returns with `INFO = i`. Otherwise, the factored form of A is used to estimate the condition number of the matrix
 - A. If the reciprocal of the condition number is less than machine precision, `INFO = N+1` is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
3. The system of equations is solved for X using the factored form of A .
4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry. = 'F': On entry, DF and EF contain the factored form of A. D, E, DF, and EF will not be modified. = 'N': The matrix A will be copied to DF and EF and factored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

D (input) The n diagonal elements of the tridiagonal matrix A.

E (input) The (n-1) subdiagonal elements of the tridiagonal matrix A.

DF (input or output)

If FACT = 'F', then DF is an input argument and on entry contains the n diagonal elements of the diagonal matrix D from the L^*D*L^{**H} factorization of A. If FACT = 'N', then DF is an output argument and on exit contains the n diagonal elements of the diagonal matrix D from the L^*D*L^{**H} factorization of A.

EF (input or output)

If FACT = 'F', then EF is an input argument and on entry contains the (n-1) subdiagonal elements of the unit bidiagonal factor L from the L^*D*L^{**H} factorization of A. If FACT = 'N', then EF is an output argument and on exit contains the (n-1) subdiagonal elements of the unit bidiagonal factor L from the L^*D*L^{**H} factorization of A.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)

The leading dimension of the array X. $LDX \geq \max(1,N)$.

RCOND (output)

The reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension(N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, and i is
<= N : the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. $RCOND = 0$ is returned. = $N+1$: U is non-singular, but $RCOND$ is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of $RCOND$ would suggest.

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NAME

cpttrf - compute the L*D*L' factorization of a complex Hermitian positive definite tridiagonal matrix A

SYNOPSIS

```
SUBROUTINE CPTTRF(N, D, E, INFO)
```

```
COMPLEX E(*)  
INTEGER N, INFO  
REAL D(*)
```

```
SUBROUTINE CPTTRF_64(N, D, E, INFO)
```

```
COMPLEX E(*)  
INTEGER*8 N, INFO  
REAL D(*)
```

F95 INTERFACE

```
SUBROUTINE PTTRF([N], D, E, [INFO])
```

```
COMPLEX, DIMENSION(:) :: E  
INTEGER :: N, INFO  
REAL, DIMENSION(:) :: D
```

```
SUBROUTINE PTTRF_64([N], D, E, [INFO])
```

```
COMPLEX, DIMENSION(:) :: E  
INTEGER(8) :: N, INFO  
REAL, DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpttrf(int n, float *d, complex *e, int *info);
```

```
void cpttrf_64(long n, float *d, complex *e, long *info);
```

PURPOSE

cpttrf computes the L^*D^*L' factorization of a complex Hermitian positive definite tridiagonal matrix A. The factorization may also be regarded as having the form $A = U^*D^*U$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the L^*D^*L' factorization of A.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A. On exit, the (n-1) subdiagonal elements of the unit bidiagonal factor L from the L^*D^*L' factorization of A. E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the U^*D^*U factorization of A.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, the leading minor of order k is not positive definite; if $k < N$, the factorization could not be completed, while if $k = N$, the factorization was completed, but $D(N) = 0$.

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cpttrs - solve a tridiagonal system of the form $A * X = B$ using the factorization $A = U'*D*U$ or $A = L*D*L'$ computed by CPTTRF

SYNOPSIS

```
SUBROUTINE CPTTRS(UPLO, N, NRHS, D, E, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX E(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
REAL D(*)
```

```
SUBROUTINE CPTTRS_64(UPLO, N, NRHS, D, E, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX E(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
REAL D(*)
```

F95 INTERFACE

```
SUBROUTINE PTTRS(UPLO, [N], [NRHS], D, E, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: E  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: D
```

```
SUBROUTINE PTTRS_64(UPLO, [N], [NRHS], D, E, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: E  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cpttrs(char uplo, int n, int nrhs, float *d, complex
            *e, complex *b, int ldb, int *info);
```

```
void cpttrs_64(char uplo, long n, long nrhs, float *d, com-
               plex *e, complex *b, long ldb, long *info);
```

PURPOSE

cpttrs solves a tridiagonal system of the form

$A * X = B$ using the factorization $A = U * D * U$ or $A = L * D * L$ computed by CPTTRF. D is a diagonal matrix specified in the vector D , U (or L) is a unit bidiagonal matrix whose superdiagonal (subdiagonal) is specified in the vector E , and X and B are N by $NRHS$ matrices.

ARGUMENTS

UPLO (input)

Specifies the form of the factorization and whether the vector E is the superdiagonal of the upper bidiagonal factor U or the subdiagonal of the lower bidiagonal factor L . = 'U': $A = U * D * U$, E is the superdiagonal of U
= 'L': $A = L * D * L$, E is the subdiagonal of L

N (input) The order of the tridiagonal matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the factorization $A = U * D * U$ or $A = L * D * L$.

E (input) If $UPLO = 'U'$, the $(n-1)$ superdiagonal elements of the unit bidiagonal factor U from the factorization $A = U * D * U$. If $UPLO = 'L'$, the $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the factorization $A = L * D * L$.

B (input/output)

On entry, the right hand side vectors B for the system of linear equations. On exit, the solution vectors, X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -k$, the k -th argument had an illegal value

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cptts2 - solve a tridiagonal system of the form $A * X = B$ using the factorization $A = U * D * U$ or $A = L * D * L'$ computed by CPTTRF

SYNOPSIS

```
SUBROUTINE CPTTS2(IUPLO, N, NRHS, D, E, B, LDB)
```

```
COMPLEX E(*), B(LDB,*)
INTEGER IUPLO, N, NRHS, LDB
REAL D(*)
```

```
SUBROUTINE CPTTS2_64(IUPLO, N, NRHS, D, E, B, LDB)
```

```
COMPLEX E(*), B(LDB,*)
INTEGER*8 IUPLO, N, NRHS, LDB
REAL D(*)
```

F95 INTERFACE

```
SUBROUTINE CPTTS2(IUPLO, N, NRHS, D, E, B, LDB)
```

```
COMPLEX, DIMENSION(:) :: E
COMPLEX, DIMENSION(:, :) :: B
INTEGER :: IUPLO, N, NRHS, LDB
REAL, DIMENSION(:) :: D
```

```
SUBROUTINE CPTTS2_64(IUPLO, N, NRHS, D, E, B, LDB)
```

```
COMPLEX, DIMENSION(:) :: E
COMPLEX, DIMENSION(:, :) :: B
INTEGER(8) :: IUPLO, N, NRHS, LDB
REAL, DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cptts2(int iuplo, int n, int nrhs, float *d, complex
            *e, complex *b, int ldb);
```

```
void cptts2_64(long iuplo, long n, long nrhs, float *d, com-
```

plex *e, complex *b, long ldb);

PURPOSE

cptts2 solves a tridiagonal system of the form

$A * X = B$ using the factorization $A = U'D*U$ or $A = L*D*L'$ computed by CPTTRF. D is a diagonal matrix specified in the vector D, U (or L) is a unit bidiagonal matrix whose superdiagonal (subdiagonal) is specified in the vector E, and X and B are N by NRHS matrices.

ARGUMENTS

IUPLO (input)

Specifies the form of the factorization and whether the vector E is the superdiagonal of the upper bidiagonal factor U or the subdiagonal of the lower bidiagonal factor L. = 1: $A = U'D*U$, E is the superdiagonal of U
= 0: $A = L*D*L'$, E is the subdiagonal of L

N (input) The order of the tridiagonal matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the factorization $A = U'D*U$ or $A = L*D*L'$.

E (input) If IUPLO = 1, the (n-1) superdiagonal elements of the unit bidiagonal factor U from the factorization $A = U'D*U$. If IUPLO = 0, the (n-1) subdiagonal elements of the unit bidiagonal factor L from the factorization $A = L*D*L'$.

B (input/output)

On entry, the right hand side vectors B for the system of linear equations. On exit, the solution vectors, X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

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NAME

crot - apply a plane rotation, where the cos (C) is real and the sin (S) is complex, and the vectors X and Y are complex

SYNOPSIS

```
SUBROUTINE CROT(N, X, INCX, Y, INCY, C, S)
```

```
COMPLEX S  
COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY  
REAL C
```

```
SUBROUTINE CROT_64(N, X, INCX, Y, INCY, C, S)
```

```
COMPLEX S  
COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY  
REAL C
```

F95 INTERFACE

```
SUBROUTINE ROT([N], X, [INCX], Y, [INCY], C, S)
```

```
COMPLEX :: S  
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY  
REAL :: C
```

```
SUBROUTINE ROT_64([N], X, [INCX], Y, [INCY], C, S)
```

```
COMPLEX :: S  
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY  
REAL :: C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void crot(int n, complex *x, int incx, complex *y, int incy,  
         float c, complex *s);
```

```
void crot_64(long n, complex *x, long incx, complex *y, long
            incy, float c, complex *s);
```

PURPOSE

`crot` applies a plane rotation, where the `cos (C)` is real and the `sin (S)` is complex, and the vectors `X` and `Y` are complex.

ARGUMENTS

`N` (input)
The number of elements in the vectors `X` and `Y`.

`X` (input/output)
On input, the vector `X`. On output, `X` is overwritten with $C*X + S*Y$.

`INCX` (input)
The increment between successive values of `X`.

`Y` (input/output)
On input, the vector `Y`. On output, `Y` is overwritten with $-CONJG(S)*X + C*Y$.

`INCY` (input)
The increment between successive values of `Y`.

`C` (input)

`S` (input)
`C` and `S` define a rotation
$$\begin{bmatrix} C & S \\ -conjg(S) & C \end{bmatrix}$$
where $C*C + S*CONJG(S) = 1.0$.

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NAME

crotg - Construct a Given's plane rotation

SYNOPSIS

```
SUBROUTINE CROTG(A, B, C, S)
```

```
COMPLEX A, B, S  
REAL C
```

```
SUBROUTINE CROTG_64(A, B, C, S)
```

```
COMPLEX A, B, S  
REAL C
```

F95 INTERFACE

```
SUBROUTINE ROTG(A, B, C, S)
```

```
COMPLEX :: A, B, S  
REAL :: C
```

```
SUBROUTINE ROTG_64(A, B, C, S)
```

```
COMPLEX :: A, B, S  
REAL :: C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void crotg(complex *a, complex *b, float *c, complex *s);
```

```
void crotg_64(complex *a, complex *b, float *c, complex *s);
```

PURPOSE

crotg Construct a Given's plane rotation that will annihilate an element of a vector.

ARGUMENTS

A (input/output)

On entry, A contains the entry in the first vector that corresponds to the element to be annihilated in the second vector. On exit, contains the nonzero element of the rotated vector.

B (input)

On entry, B contains the entry to be annihilated in the second vector. Unchanged on exit.

C (output)

On exit, C and S are the elements of the rotation matrix that will be applied to annihilate B.

S (output)

On exit, C and S are the elements of the rotation matrix that will be applied to annihilate B.

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NAME

cscal - Compute $y := \alpha * y$

SYNOPSIS

```
SUBROUTINE CSCAL(N, ALPHA, Y, INCY)

COMPLEX ALPHA
COMPLEX Y(*)
INTEGER N, INCY

SUBROUTINE CSCAL_64(N, ALPHA, Y, INCY)

COMPLEX ALPHA
COMPLEX Y(*)
INTEGER*8 N, INCY
```

F95 INTERFACE

```
SUBROUTINE SCAL([N], ALPHA, Y, [INCY])

COMPLEX :: ALPHA
COMPLEX, DIMENSION(:) :: Y
INTEGER :: N, INCY

SUBROUTINE SCAL_64([N], ALPHA, Y, [INCY])

COMPLEX :: ALPHA
COMPLEX, DIMENSION(:) :: Y
INTEGER(8) :: N, INCY
```

C INTERFACE

```
#include <sunperf.h>

void cscal(int n, complex *alpha, complex *y, int incy);

void cscal_64(long n, complex *alpha, complex *y, long
            incy);
```

PURPOSE

cscal Compute $y := \text{alpha} * y$ where alpha is a scalar and y is an n-vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * INCY). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. This routine returns immediately if INCY is less than or equal to zero. Unchanged on exit.

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NAME

csctr - Scatters elements from x into y.

SYNOPSIS

```
SUBROUTINE CSCTR(NZ, X, INDX, Y)

COMPLEX X(*), Y(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE CSCTR_64(NZ, X, INDX, Y)

COMPLEX X(*), Y(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE SCTR([NZ], X, INDX, Y)

COMPLEX, DIMENSION(:) :: X, Y
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE SCTR_64([NZ], X, INDX, Y)

COMPLEX, DIMENSION(:) :: X, Y
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

CSCTR - Scatters the components of a sparse vector x stored in compressed form into specified components of a vector y in full storage form.

```
do i = 1, n
  y(indx(i)) = x(i)
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector containing the values to be scattered from
compressed form into full storage form. Unchanged
on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

Y (output)

Vector whose elements specified by indx have been
set to the corresponding entries of x. Only the
elements corresponding to the indices in indx have
been modified.

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NAME

cskymm - Skyline format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CSKYMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, PNTR, B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER          PNTR(*),  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE CSKYMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, PNTR, B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER*8        PNTR(*),  
COMPLEX          ALPHA, BETA  
COMPLEX          VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTR(K+1)-PNTR(1) (upper triangular)
 NNZ = PNTR(M+1)-PNTR(1) (lower triangular)
 PNTR() size = (K+1) (upper triangular)
 PNTR() size = (M+1) (lower triangular)

F95 INTERFACE

```
SUBROUTINE SKYMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL,  
*                PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, PNTR  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL  
COMPLEX, DIMENSION(:, :) :: B, C  
  
SUBROUTINE SKYMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL,  
*                PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, M, K  
INTEGER*8, DIMENSION(:) :: DESCRA, PNTR
```

```

COMPLEX ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL
COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void cskymm (int transa, int m, int n, int k, complex
*alpha, int *descra, complex *val, int *pntr, complex *b,
int ldb, complex *beta,
complex *c, int ldc);

void cskymm_64 (long transa, long m, long n, long k,
complex *alpha, long *descra, complex *val,
long *pntr, complex *b, long ldb, complex *beta,
complex *c, long ldc);

```

DESCRIPTION

cskymm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the skyline format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.

K(input) On entry, integer K specifies the number of columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array.
DESCRA(1) matrix structure
0 : general (NOT SUPPORTED)
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))

3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array consisting of the nonzeros of A in skyline profile form. Row-oriented if DESCRA(2) = 1 (lower triangular), column oriented if DESCRA(2) = 2 (upper triangular). Unchanged on exit.

PNTR (input) On entry, INDX is an integer array of length M+1 (lower triangular) or K+1 (upper triangular) such that PNTR(I)-PNTR(1)+1 points to the location in VAL of the first element of the skyline profile in row (column) I. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are

implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

The SKY data structure is not supported for a general matrix structure (*DESCRA*(1)=0).

Also not supported:

1. lower triangular matrix *A* of size *m* by *n* where $m > n$
2. upper triangular matrix *A* of size *m* by *n* where $m < n$

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NAME

cskysm - Skyline format triangular solve

SYNOPSIS

```
SUBROUTINE CSKYSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*               VAL, PNTR,
*               B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER        TRANSA, M, N, UNITD, DESCRA(5),
*               LDB, LDC, LWORK
INTEGER        PNTR(*),
COMPLEX        ALPHA, BETA
COMPLEX        DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE CSKYSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*               VAL, PNTR,
*               B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER*8      TRANSA, M, N, UNITD, DESCRA(5),
*               LDB, LDC, LWORK
INTEGER*8      PNTR(*),
COMPLEX        ALPHA, BETA
COMPLEX        DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTR(M+1)-PNTR(1)
PNTR() size = (M+1)

F95 INTERFACE

```
SUBROUTINE SKYSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,
*               PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER        TRANSA, M, UNITD
INTEGER, DIMENSION(:) :: DESCRA, PNTR
COMPLEX        ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C

SUBROUTINE SKYSM_64( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA,
*               VAL, PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER*8      TRANSA, M, UNITD
INTEGER*8, DIMENSION(:) :: DESCRA, PNTR
```

```

COMPLEX    ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```
#include <sunperf.h>
```

```

void cskysm (int transa, int m, int n, int unitd, complex
*dv, complex *alpha, int *descra, complex *val, int *pntr,
complex *b, int ldb, complex *beta, complex *c, int ldc);
void cskysm_64 (long transa, long m, long n, long unitd,
complex *dv, complex *alpha, long *descra, complex *val,
long *pntr, complex *b, long ldb, complex *beta, complex *c,
long ldc);

```

DESCRIPTION

cskysm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C, \quad C \leftarrow -\alpha D \operatorname{op}(A) B + \beta C,$$

$$C \leftarrow \alpha \operatorname{op}(A) D B + \beta C,$$

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the skyline format and op(A) is one of

op(A) = inv(A) or op(A) = inv(A') or op(A) = inv(conjg(A'))
(inv denotes matrix inverse, ' indicates matrix transpose).

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:

- 0 : operate with matrix
- 1 : operate with transpose matrix
- 2 : operate with the conjugate transpose of matrix.

2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:

- 1 : Identity matrix (argument DV[] is ignored)
- 2 : Scale on left (row scaling)
- 3 : Scale on right (column scaling)
- 4 : Automatic row or column scaling (see section NOTES for further details)

Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the

diagonal entries of the scaling matrix D.
If UNITD is 4, DV contains diagonal matrix by which the rows (columns) have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array.
DESCRA(1) matrix structure
0 : general (NOT SUPPORTED)
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-unit
1 : unit

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL contains the nonzeros of A in skyline profile form. Row-oriented if DESCRA(2) = 1 (lower triangular), column oriented if DESCRA(2) = 2 (upper triangular). Unchanged on exit if UNITD is not 4. Otherwise, VAL contains entries of D*A or A*D (see section NOTES for further details).

PNTR (input) On entry, INDX is an integer array of length M+1 such that PNTR(I)-PNTR(1)+1 points to the location in VAL of the first element of the skyline profile in row (column) I. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK

should be at least M.

For good performance, LWORK should generally be larger.
For optimum performance on multiple processors, LWORK
>=M*N_CPUS where N_CPUS is the maximum number of
processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the
routine only calculates the optimum size of the WORK array,
returns this value as the first entry of the WORK array,
and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS)
Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4 , the routine scales the rows of A if *DESCRA*(2)=1 (lower triangular), and the columns of A if *DESCRA*(2)=2 (upper triangular) such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in this particular case. On exit, DV matrix stored as a vector contains the diagonal matrix by which the rows (columns) have been scaled. UNITD=2 if *DESCRA*(2)=1 and UNITD=3 if *DESCRA*(2)=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise *WORK*(1) = -i where i is the row (column) number which 2-norm is exactly zero.

3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the skyline representation of a sparse matrix don't need to be referenced in this usage but they need to be 1.0 if they are referenced. However if UNITD=4, the unit diagonal elements with the mathematical value 1

MUST be referenced in the skyline representation.

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NAME

cspcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex symmetric packed matrix A using the factorization $A = U*D*U^{*T}$ or $A = L*D*L^{*T}$ computed by CSPTRF

SYNOPSIS

```
SUBROUTINE CSPCON(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)  
REAL ANORM, RCOND
```

```
SUBROUTINE CSPCON_64(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
REAL ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE SPCON(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL :: ANORM, RCOND
```

```
SUBROUTINE SPCON_64(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>

void cspcon(char uplo, int n, complex *a, int *ipivot, float
            anorm, float *rcond, int *info);
void cspcon_64(char uplo, long n, complex *a, long *ipivot,
              float anorm, float *rcond, long *info);
```

PURPOSE

cspcon estimates the reciprocal of the condition number (in the 1-norm) of a complex symmetric packed matrix A using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by CSPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U*D*U^{**T}$;
= 'L': Lower triangular, form is $A = L*D*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) Complex array, dimension $(N*(N+1)/2)$ The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CSPTRF, stored as a packed triangular matrix.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by CSPTRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

Complex array, dimension $(2*N)$

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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csprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CSPRFS(UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX, FERR,  
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
INTEGER IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CSPRFS_64(UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE SPRFS(UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X, [LDX],  
  FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: A, AF, WORK  
COMPLEX, DIMENSION(:, :) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE SPRFS_64(UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X,  
  [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

COMPLEX, DIMENSION(:) :: A, AF, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void csprfs(char uplo, int n, int nrhs, complex *a, complex
            *af, int *ipivot, complex *b, int ldb, complex *x,
            int ldx, float *ferr, float *berr, int *info);

void csprfs_64(char uplo, long n, long nrhs, complex *a,
              complex *af, long *ipivot, complex *b, long ldb,
              complex *x, long ldx, float *ferr, float *berr,
              long *info);

```

PURPOSE

csprfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) Complex array, dimension $(N*(N+1)/2)$ The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i, j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i, j)$ for $j < i \leq n$.

AF (input)
 Complex array, dimension $(N*(N+1)/2)$ The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^*T$ or $A = L*D*L^*T$ as computed by CSPTRF, stored as a packed triangular matrix.

IPIVOT (input)
 Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by CSPTRF.

B (input) Complex array, dimension (LDB,NRHS) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
Complex array, dimension (LDX,NRHS) On entry, the solution matrix X, as computed by CSPTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
Real array, dimension (NRHS) The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
Real array, dimension (NRHS) The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
Complex array, dimension(2*N)

WORK2 (workspace)
Integer array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cspsv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CSPSV(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CSPSV_64(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SPSV(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SPSV_64(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cspsv(char uplo, int n, int nrhs, complex *ap, int
           *ipivot, complex *b, int ldb, int *info);
```

```
void cspsv_64(char uplo, long n, long nrhs, complex *ap,
              long *ipivot, complex *b, long ldb, long *info);
```

PURPOSE

cspsv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{**T}$, if UPLO = 'U', or

$A = L * D * L^{**T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

AP (input/output)

Complex array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by CSPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (output)

Integer array, dimension (N) Details of the interchanges and the block structure of D, as determined by CSPTRF. If IPIVOT(k) > 0, then rows

and columns k and $\text{IPIVOT}(k)$ were interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $\text{UPL}O = 'U'$ and $\text{IPIVOT}(k) = \text{IPIVOT}(k-1) < 0$, then rows and columns $k-1$ and $-\text{IPIVOT}(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $\text{UPL}O = 'L'$ and $\text{IPIVOT}(k) = \text{IPIVOT}(k+1) < 0$, then rows and columns $k+1$ and $-\text{IPIVOT}(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output)

Complex array, dimension $(\text{LDB}, \text{NRHS})$. On entry, the N -by- NRHS right hand side matrix B . On exit, if $\text{INFO} = 0$, the N -by- NRHS solution matrix X .

LDB (input)

The leading dimension of the array B . $\text{LDB} \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value
> 0: if $\text{INFO} = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, $\text{UPL}O = 'U'$:

Two-dimensional storage of the symmetric matrix A :

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34   (aij = aji)
            a44
```

Packed storage of the upper triangle of A :

```
AP = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

cspsvx - use the diagonal pivoting factorization $A = U^*D*U^{**T}$ or $A = L^*D*L^{**T}$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE CSPSVX(FACT, UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX,
                  RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*)
REAL RCOND
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CSPSVX_64(FACT, UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X,
                    LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
REAL RCOND
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE SPSVX(FACT, UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X,
                [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX, DIMENSION(:) :: A, AF, WORK
COMPLEX, DIMENSION(:, :) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL :: RCOND
```

```

REAL, DIMENSION(:) :: FERR, BERR, WORK2

SUBROUTINE SPSVX_64(FACT, UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB],
    X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX, DIMENSION(:) :: A, AF, WORK
COMPLEX, DIMENSION(:,:) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL :: RCOND
REAL, DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void cspsvx(char fact, char uplo, int n, int nrhs, complex
    *a, complex *af, int *ipivot, complex *b, int ldb,
    complex *x, int ldx, float *rcond, float *ferr,
    float *berr, int *info);

void cspsvx_64(char fact, char uplo, long n, long nrhs, com-
    plex *a, complex *af, long *ipivot, complex *b,
    long ldb, complex *x, long ldx, float *rcond,
    float *ferr, float *berr, long *info);

```

PURPOSE

cspsvx uses the diagonal pivoting factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N -by- N symmetric matrix stored in packed format and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the diagonal pivoting method is used to factor A as

$$A = U * D * U^{**T}, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * D * L^{**T}, \text{ if } UPLO = 'L',$$

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices and D is symmetric and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than machine precision,

$INFO = N+1$ is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described

below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. A, AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) Complex array, dimension $(N*(N+1)/2)$ The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j < i \leq n$. See below for further details.

AF (input or output)

Complex array, dimension $(N*(N+1)/2)$ If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by CSPTRF, stored as a packed triangular matrix in the same storage format as A.

If FACT = 'N', then AF is an output argument and on exit contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by CSPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (input or output)

Integer array, dimension (N) If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by CSPTRF. If IPIVOT(k)

> 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

If FACT = 'N', then IPIVOT is an output argument and on exit contains details of the interchanges and the block structure of D, as determined by CSPTRF.

B (input) Complex array, dimension (LDB,NRHS) The N-by-NRHS right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

X (output)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)
Complex array, dimension (LDX,NRHS) The leading dimension of the array X. LDX >= max(1,N).

RCOND (output)
The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)
Complex array, dimension (NRHS) The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
Complex array, dimension (NRHS) The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
Complex array, dimension(2*N)

WORK2 (workspace)

Integer array, dimension(N)

INFO (output)

```
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.
```

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, $UPLO = 'U'$:

Two-dimensional storage of the symmetric matrix A:

```
  a11 a12 a13 a14
    a22 a23 a24
      a33 a34   (aij = aji)
        a44
```

Packed storage of the upper triangle of A:

```
A = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

csptrf - compute the factorization of a complex symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE CSPTRF(UPLO, N, AP, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CSPTRF_64(UPLO, N, AP, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRF(UPLO, [N], AP, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SPTRF_64(UPLO, [N], AP, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csptf(char uplo, int n, complex *ap, int *ipivot, int
           *info);
```

```
void csptf_64(char uplo, long n, complex *ap, long *ipivot,
              long *info);
```

PURPOSE

csptf computes the factorization of a complex symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U^{*T} \text{ or } A = L^*D^*L^{*T}$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)
Complex array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L, stored as a packed triangular matrix overwriting A (see below for further details).

IPIVOT (output)
Integer array, dimension (N) Details of the interchanges and the block structure of D. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged and $D(k,k)$ is a 1-by-1 diagonal block. If UPLO = 'U' and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns k-1 and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If UPLO = 'L' and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns k+1 and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an

illegal value
 > 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

5-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

csptri - compute the inverse of a complex symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^*T$ or $A = L^*D^*L^*T$ computed by CSPTRF

SYNOPSIS

```
SUBROUTINE CSPTRI(UPLO, N, AP, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), WORK(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CSPTRI_64(UPLO, N, AP, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), WORK(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRI(UPLO, [N], AP, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP, WORK  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SPTRI_64(UPLO, [N], AP, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP, WORK  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csptri(char uplo, int n, complex *ap, int *ipivot, int  
            *info);
```

```
void csptri_64(char uplo, long n, complex *ap, long *ipivot,
              long *info);
```

PURPOSE

csptri computes the inverse of a complex symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by CSPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U^*D^*U^{**T}$;
= 'L': Lower triangular, form is $A = L^*D^*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)

Complex array, dimension $(N*(N+1)/2)$ On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CSPTRF, stored as a packed triangular matrix.

On exit, if INFO = 0, the (symmetric) inverse of the original matrix, stored as a packed triangular matrix. The j-th column of $\text{inv}(A)$ is stored in the array AP as follows: if UPLO = 'U', $\text{AP}(i + (j-1)*j/2) = \text{inv}(A)(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $\text{AP}(i + (j-1)*(2n-j)/2) = \text{inv}(A)(i,j)$ for $j \leq i \leq n$.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by CSPTRF.

WORK (workspace)

Complex array, dimension (N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

csptrs - solve a system of linear equations $A \cdot X = B$ with a complex symmetric matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^{*T}$ or $A = L \cdot D \cdot L^{*T}$ computed by CSPTRF

SYNOPSIS

```
SUBROUTINE CSPTRS(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CSPTRS_64(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRS(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SPTRS_64(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csptrs(char uplo, int n, int nrhs, complex *ap, int
            *ipivot, complex *b, int ldb, int *info);
```

```
void csptrs_64(char uplo, long n, long nrhs, complex *ap,
               long *ipivot, complex *b, long ldb, long *info);
```

PURPOSE

csptrs solves a system of linear equations $A \cdot X = B$ with a complex symmetric matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^{**T}$ or $A = L \cdot D \cdot L^{**T}$ computed by CSPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U \cdot D \cdot U^{**T}$;
= 'L': Lower triangular, form is $A = L \cdot D \cdot L^{**T}$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

AP (input)

Complex array, dimension $(N \cdot (N+1)/2)$ The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CSPTRF, stored as a packed triangular matrix.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by CSPTRF.

B (input/output)

Complex array, dimension $(LDB, NRHS)$ On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

csrot - Apply a plane rotation.

SYNOPSIS

```
SUBROUTINE CSROT(N, X, INCX, Y, INCY, C, S)
```

```
REAL C, S  
COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE CSROT_64(N, X, INCX, Y, INCY, C, S)
```

```
REAL C, S  
COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE ROT([N], X, [INCX], Y, [INCY], C, S)
```

```
REAL :: C, S  
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE ROT_64([N], X, [INCX], Y, [INCY], C, S)
```

```
REAL :: C, S  
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csrot(int n, complex *x, int incx, complex *y, int  
          incy, float c, float s);
```

```
void csrot_64(long n, complex *x, long incx, complex *y,  
             long incy, float c, float s);
```

PURPOSE

csrot Apply a plane rotation, where the cos and sin (c and s) are real and the vectors x and y are complex.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input/output)

Before entry, the incremented array X must contain the vector x.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

Y (input/output)

On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

C (input)

On entry, the cosine. Unchanged on exit.

S (input)

On entry, the sin. Unchanged on exit.

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NAME

csscal - Compute $y := \alpha * y$

SYNOPSIS

```
SUBROUTINE CSSCAL(N, ALPHA, Y, INCY)
```

```
COMPLEX Y(*)
INTEGER N, INCY
REAL ALPHA
```

```
SUBROUTINE CSSCAL_64(N, ALPHA, Y, INCY)
```

```
COMPLEX Y(*)
INTEGER*8 N, INCY
REAL ALPHA
```

F95 INTERFACE

```
SUBROUTINE SCAL([N], ALPHA, Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: Y
INTEGER :: N, INCY
REAL :: ALPHA
```

```
SUBROUTINE SCAL_64([N], ALPHA, Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: Y
INTEGER(8) :: N, INCY
REAL :: ALPHA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csscal(int n, float alpha, complex *y, int incy);
```

```
void csscal_64(long n, float alpha, complex *y, long incy);
```

PURPOSE

csscal Compute $y := \alpha * y$ where α is a scalar and y is an n -vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

Y (input/output)

($1 + (n - 1) * \text{INCY}$). On entry, the incremented array Y must contain the vector y . On exit, Y is overwritten by the updated vector y .

INCY (input)

On entry, INCY specifies the increment for the elements of Y. This routine returns immediately if INCY is less than or equal to zero. Unchanged on exit.

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NAME

cstedc - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method

SYNOPSIS

```
SUBROUTINE CSTEDC(COMPZ, N, D, E, Z, LDZ, WORK, LWORK, RWORK, LRWORK,  
                 IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 COMPZ  
COMPLEX Z(LDZ,*), WORK(*)  
INTEGER N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL D(*), E(*), RWORK(*)
```

```
SUBROUTINE CSTEDC_64(COMPZ, N, D, E, Z, LDZ, WORK, LWORK, RWORK,  
                    LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 COMPZ  
COMPLEX Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL D(*), E(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEDC(COMPZ, [N], D, E, Z, [LDZ], [WORK], [LWORK], [RWORK],  
                [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,) :: Z  
INTEGER :: N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: D, E, RWORK
```

```
SUBROUTINE STEDC_64(COMPZ, [N], D, E, Z, [LDZ], [WORK], [LWORK],  
                   [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```

CHARACTER(LEN=1) :: COMPZ
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: Z
INTEGER(8) :: N, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: D, E, RWORK

```

C INTERFACE

```

#include <sunperf.h>
void cstedc(char compz, int n, float *d, float *e, complex
            *z, int ldz, int *info);

void cstedc_64(char compz, long n, float *d, float *e, com-
               plex *z, long ldz, long *info);

```

PURPOSE

cstedc computes all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method. The eigenvectors of a full or band complex Hermitian matrix can also be found if CHETRD or CHPTRD or CHBTRD has been used to reduce this matrix to tridiagonal form.

This code makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none. See SLAED3 for details.

ARGUMENTS

COMPZ (input)
 = 'N': Compute eigenvalues only.
 = 'I': Compute eigenvectors of tridiagonal matrix also.
 = 'V': Compute eigenvectors of original Hermitian matrix also. On entry, Z contains the unitary matrix used to reduce the original matrix to tridiagonal form.

N (input) The dimension of the symmetric tridiagonal matrix.
 N >= 0.

D (input/output)
 On entry, the diagonal elements of the tridiagonal matrix. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)
 On entry, the subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input) On entry, if COMPZ = 'V', then Z contains the

unitary matrix used in the reduction to tridiagonal form. On exit, if INFO = 0, then if COMPZ = 'V', Z contains the orthonormal eigenvectors of the original Hermitian matrix, and if COMPZ = 'I', Z contains the orthonormal eigenvectors of the symmetric tridiagonal matrix. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1. If eigenvectors are desired, then LDZ >= max(1,N).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If COMPZ = 'N' or 'I', or N <= 1, LWORK must be at least 1. If COMPZ = 'V' and N > 1, LWORK must be at least N*N.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

dimension (LRWORK) On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)

The dimension of the array RWORK. If COMPZ = 'N' or N <= 1, LRWORK must be at least 1. If COMPZ = 'V' and N > 1, LRWORK must be at least $1 + 3*N + 2*N*\lg N + 3*N**2$, where $\lg(N)$ = smallest integer k such that $2**k \geq N$. If COMPZ = 'I' and N > 1, LRWORK must be at least $1 + 4*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If COMPZ = 'N' or N <= 1, LIWORK must be at least 1. If COMPZ = 'V' or N > 1, LIWORK must be at least $6 + 6*N + 5*N*\lg N$. If COMPZ = 'I' or N > 1, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: The algorithm failed to compute an eigenvalue while working on the submatrix lying in rows and columns INFO/(N+1) through mod(INFO,N+1).

FURTHER DETAILS

Based on contributions by
Jeff Rutter, Computer Science Division, University of
California
at Berkeley, USA

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NAME

cstegr - Compute $T\text{-}\sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation

SYNOPSIS

```
SUBROUTINE CSTEGR(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M, W,  
  Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
COMPLEX Z(LDZ,*)  
INTEGER N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER ISUPPZ(*), IWORK(*)  
REAL VL, VU, ABSTOL  
REAL D(*), E(*), W(*), WORK(*)
```

```
SUBROUTINE CSTEGR_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
COMPLEX Z(LDZ,*)  
INTEGER*8 N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 ISUPPZ(*), IWORK(*)  
REAL VL, VU, ABSTOL  
REAL D(*), E(*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEGR(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE  
COMPLEX, DIMENSION(:,:) :: Z  
INTEGER :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: ISUPPZ, IWORK  
REAL :: VL, VU, ABSTOL  
REAL, DIMENSION(:) :: D, E, W, WORK
```

```
SUBROUTINE STEGR_64(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL,  
  M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, RANGE
COMPLEX, DIMENSION(:,:) :: Z
INTEGER(8) :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: D, E, W, WORK

```

C INTERFACE

```

#include <sunperf.h>

void cstegr(char jobz, char range, int n, float *d, float
            *e, float vl, float vu, int il, int iu, float
            abstol, int *m, float *w, complex *z, int ldz, int
            *isuppz, int *info);

void cstegr_64(char jobz, char range, long n, float *d,
              float *e, float vl, float vu, long il, long iu,
              float abstol, long *m, float *w, complex *z, long
              ldz, long *isuppz, long *info);

```

PURPOSE

cstegr b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high relative accuracy by the dqds algorithm,

(c) If there is a cluster of close eigenvalues, "choose" σ_i close to the cluster, and go to step (a),

(d) Given the approximate eigenvalue λ_j of $L_i D_i L_i^T$, compute the corresponding eigenvector by forming a rank-revealing twisted factorization.

The desired accuracy of the output can be specified by the input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB/CSD-97-971, UC Berkeley, May 1997.

Note 1 : Currently CSTEGR is only set up to find ALL the n eigenvalues and eigenvectors of T in $O(n^2)$ time

Note 2 : Currently the routine CSTEIN is called when an appropriate σ_i cannot be chosen in step (c) above. CSTEIN invokes modified Gram-Schmidt when eigenvalues are close.

Note 3 : CSTEGR works only on machines which follow ieee-754 floating-point standard in their handling of infinities and NaNs. Normal execution of CSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not conform to the ieee standard.

ARGUMENTS

```

JOBZ (input)
    = 'N': Compute eigenvalues only;

```

= 'V': Compute eigenvalues and eigenvectors.
 RANGE (input)
 = 'A': all eigenvalues will be found.
 = 'V': all eigenvalues in the half-open interval
 (VL,VU] will be found. = 'I': the IL-th through
 IU-th eigenvalues will be found.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)
 On entry, the n diagonal elements of the tridiagonal matrix T . On exit, D is overwritten.

E (input/output)
 On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix T in elements 1 to $N-1$ of E ; $E(N)$ need not be set. On exit, E is overwritten.

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABSTOL (input)
 The absolute error tolerance for the eigenvalues/eigenvectors. IF JOBZ = 'V', the eigenvalues and eigenvectors output have residual norms bounded by ABSTOL, and the dot products between different eigenvectors are bounded by ABSTOL. If ABSTOL is less than $N*EPS*|T|$, then $N*EPS*|T|$ will be used in its place, where EPS is the machine precision and $|T|$ is the 1-norm of the tridiagonal matrix. The eigenvalues are computed to an accuracy of $EPS*|T|$ irrespective of ABSTOL. If high relative accuracy is important, set ABSTOL to DLAMCH('Safe minimum'). See Barlow and Demmel "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7 for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (input/output)

If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix T corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

ISUPPZ (output)

The support of the eigenvectors in Z, i.e., the indices indicating the nonzero elements in Z. The i-th eigenvector is nonzero only in elements ISUPPZ(2*i-1) through ISUPPZ(2*i).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal (and minimal) LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1, 18*N)$

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. $LIWORK \geq \max(1, 10*N)$

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = 1, internal error in SLARRE, if
INFO = 2, internal error in CLARRV.

FURTHER DETAILS

Based on contributions by
Inderjit Dhillon, IBM Almaden, USA
Osni Marques, LBNL/NERSC, USA
Ken Stanley, Computer Science Division, University of
California at Berkeley, USA

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NAME

cstein - compute the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration

SYNOPSIS

```
SUBROUTINE CSTEIN(N, D, E, M, W, IBLOCK, ISPLIT, Z, LDZ, WORK, IWORK,  
                IFAIL, INFO)
```

```
COMPLEX Z(LDZ,*)  
INTEGER N, M, LDZ, INFO  
INTEGER IBLOCK(*), ISPLIT(*), IWORK(*), IFAIL(*)  
REAL D(*), E(*), W(*), WORK(*)
```

```
SUBROUTINE CSTEIN_64(N, D, E, M, W, IBLOCK, ISPLIT, Z, LDZ, WORK,  
                   IWORK, IFAIL, INFO)
```

```
COMPLEX Z(LDZ,*)  
INTEGER*8 N, M, LDZ, INFO  
INTEGER*8 IBLOCK(*), ISPLIT(*), IWORK(*), IFAIL(*)  
REAL D(*), E(*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEIN([N], D, E, [M], W, IBLOCK, ISPLIT, Z, [LDZ], [WORK],  
                [IWORK], IFAIL, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: Z  
INTEGER :: N, M, LDZ, INFO  
INTEGER, DIMENSION(:) :: IBLOCK, ISPLIT, IWORK, IFAIL  
REAL, DIMENSION(:) :: D, E, W, WORK
```

```
SUBROUTINE STEIN_64([N], D, E, [M], W, IBLOCK, ISPLIT, Z, [LDZ],  
                  [WORK], [IWORK], IFAIL, [INFO])
```

```
COMPLEX, DIMENSION(:, :) :: Z  
INTEGER(8) :: N, M, LDZ, INFO  
INTEGER(8), DIMENSION(:) :: IBLOCK, ISPLIT, IWORK, IFAIL  
REAL, DIMENSION(:) :: D, E, W, WORK
```

C INTERFACE

```
#include <sunperf.h>

void cstein(int n, float *d, float *e, int m, float *w, int
            *iblock, int *isplit, complex *z, int ldz, int
            *ifail, int *info);
void cstein_64(long n, float *d, float *e, long m, float *w,
               long *iblock, long *isplit, complex *z, long ldz,
               long *ifail, long *info);
```

PURPOSE

cstein computes the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration.

The maximum number of iterations allowed for each eigenvector is specified by an internal parameter MAXITS (currently set to 5).

Although the eigenvectors are real, they are stored in a complex array, which may be passed to CUNMTR or CUPMTR for back transformation to the eigenvectors of a complex Hermitian matrix which was reduced to tridiagonal form.

ARGUMENTS

- N (input) The order of the matrix. $N \geq 0$.
- D (input) The n diagonal elements of the tridiagonal matrix T.
- E (input) The (n-1) subdiagonal elements of the tridiagonal matrix T, stored in elements 1 to N-1; E(N) need not be set.
- M (input) The number of eigenvectors to be found. $0 \leq M \leq N$.
- W (input) The first M elements of W contain the eigenvalues for which eigenvectors are to be computed. The eigenvalues should be grouped by split-off block and ordered from smallest to largest within the block. (The output array W from SSTEBCZ with ORDER = 'B' is expected here.)
- IBLOCK (input)
The submatrix indices associated with the corresponding eigenvalues in W; IBLOCK(i)=1 if eigenvalue W(i) belongs to the first submatrix from the top, =2 if W(i) belongs to the second submatrix, etc. (The output array IBLOCK from SSTEBCZ is expected here.)
- ISPLIT (input)
The splitting points, at which T breaks up into

submatrices. The first submatrix consists of rows/columns 1 to ISPLIT(1), the second of rows/columns ISPLIT(1)+1 through ISPLIT(2), etc. (The output array ISPLIT from SSTEGBZ is expected here.)

Z (output)

The computed eigenvectors. The eigenvector associated with the eigenvalue W(i) is stored in the i-th column of Z. Any vector which fails to converge is set to its current iterate after MAXITS iterations. The imaginary parts of the eigenvectors are set to zero.

LDZ (input)

The leading dimension of the array Z. LDZ >= max(1,N).

WORK (workspace)

dimension(5*N)

IWORK (workspace)

dimension(N)

IFAIL (output)

On normal exit, all elements of IFAIL are zero. If one or more eigenvectors fail to converge after MAXITS iterations, then their indices are stored in array IFAIL.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, then i eigenvectors failed to converge in MAXITS iterations. Their indices are stored in array IFAIL.

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NAME

csteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method

SYNOPSIS

```
SUBROUTINE CSTEQR(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
COMPLEX Z(LDZ,*)  
INTEGER N, LDZ, INFO  
REAL D(*), E(*), WORK(*)
```

```
SUBROUTINE CSTEQR_64(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
COMPLEX Z(LDZ,*)  
INTEGER*8 N, LDZ, INFO  
REAL D(*), E(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEQR(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX, DIMENSION(:,) :: Z  
INTEGER :: N, LDZ, INFO  
REAL, DIMENSION(:) :: D, E, WORK
```

```
SUBROUTINE STEQR_64(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX, DIMENSION(:,) :: Z  
INTEGER(8) :: N, LDZ, INFO  
REAL, DIMENSION(:) :: D, E, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csteqr(char compz, int n, float *d, float *e, complex  
           *z, int ldz, int *info);
```

```
void csteqr_64(char compz, long n, float *d, float *e, complex *z, long ldz, long *info);
```

PURPOSE

csteqr computes all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method. The eigenvectors of a full or band complex Hermitian matrix can also be found if CHETRD or CHPTRD or CHBTRD has been used to reduce this matrix to tridiagonal form.

ARGUMENTS

COMPZ (input)

= 'N': Compute eigenvalues only.
= 'V': Compute eigenvalues and eigenvectors of the original Hermitian matrix. On entry, Z must contain the unitary matrix used to reduce the original matrix to tridiagonal form. = 'I': Compute eigenvalues and eigenvectors of the tridiagonal matrix. Z is initialized to the identity matrix.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the diagonal elements of the tridiagonal matrix. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input) On entry, if COMPZ = 'V', then Z contains the unitary matrix used in the reduction to tridiagonal form. On exit, if INFO = 0, then if COMPZ = 'V', Z contains the orthonormal eigenvectors of the original Hermitian matrix, and if COMPZ = 'I', Z contains the orthonormal eigenvectors of the symmetric tridiagonal matrix. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if eigenvectors are desired, then $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension($\max(1, 2*N-2)$) If COMPZ = 'N', then WORK is not referenced.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value
> 0: the algorithm has failed to find all the eigenvalues in a total of 30*N iterations; if INFO = i, then i elements of E have not converged to zero; on exit, D and E contain the elements of a symmetric tridiagonal matrix which is unitarily similar to the original matrix.

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NAME

cstsv - compute the solution to a complex system of linear equations $A * X = B$ where A is a symmetric tridiagonal matrix

SYNOPSIS

```
SUBROUTINE CSTSV(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
COMPLEX L(*), D(*), SUBL(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE CSTSV_64(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
COMPLEX L(*), D(*), SUBL(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE STSV([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:) :: L, D, SUBL  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE STSV_64([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:) :: L, D, SUBL  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cstsv(int n, int nrhs, complex *l, complex *d, complex  
          *subl, complex *b, int ldb, int *ipiv, int *info);
```

```
void cstsv_64(long n, long nrhs, complex *l, complex *d,
```

```
complex *subl, complex *b, long ldb, long *ipiv,  
long *info);
```

PURPOSE

cstsv computes the solution to a complex system of linear equations $A * X = B$ where A is a symmetric tridiagonal matrix.

ARGUMENTS

N (input)
The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides in B.

L (input/output)
COMPLEX array, dimension (N-1)
On entry, the n-1 subdiagonal elements of the tridiagonal matrix A. On exit, part of the factorization of A.

D (input/output)
REAL array, dimension (N)
On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the factorization of A.

SUBL (output)
COMPLEX array, dimension (N-2)
On exit, part of the factorization of A.

B (input/output)
The columns of B contain the right hand sides.

LDB (input)
The leading dimension of B as specified in a type or DIMENSION statement.

IPIV (output)
INTEGER array, dimension (N)
On exit, the pivot indices of the factorization.

INFO (output)
INTEGER
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular and division by zero will occur if it is used to solve a system of equations.

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NAME

csstrf - compute the factorization of a complex symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE CSTTRF(N, L, D, SUBL, IPIV, INFO)
```

```
COMPLEX L(*), D(*), SUBL(*)  
INTEGER N, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE CSTTRF_64(N, L, D, SUBL, IPIV, INFO)
```

```
COMPLEX L(*), D(*), SUBL(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE STTRF([N], L, D, SUBL, IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:) :: L, D, SUBL  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE STTRF_64([N], L, D, SUBL, IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:) :: L, D, SUBL  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csstrf(int n, complex *l, complex *d, complex *subl,  
           int *ipiv, int *info);
```

```
void csstrf_64(long n, complex *l, complex *d, complex  
              *subl, long *ipiv, long *info);
```

PURPOSE

csttrf computes the L^*D^*L' factorization of a complex symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method.

ARGUMENTS

N (input) INTEGER
The order of the matrix A. $N \geq 0$.

L (input/output)
COMPLEX array, dimension (N-1)
On entry, the n-1 subdiagonal elements of the tridiagonal matrix A. On exit, part of the factorization of A.

D (input/output)
REAL array, dimension (N)
On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the factorization of A.

SUBL (output)
COMPLEX array, dimension (N-2)
On exit, part of the factorization of A.

IPIV (output)
INTEGER array, dimension (N)
On exit, the pivot indices of the factorization.

INFO (output)
INTEGER
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular and division by zero will occur if it is used to solve a system of equations.

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csttrs - computes the solution to a complex system of linear equations $A * X = B$

SYNOPSIS

```
SUBROUTINE CSTTRS(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
COMPLEX L(*), D(*), SUBL(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE CSTTRS_64(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
COMPLEX L(*), D(*), SUBL(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE STTRS([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:) :: L, D, SUBL  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE STTRS_64([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
COMPLEX, DIMENSION(:) :: L, D, SUBL  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csttrs(int n, int nrhs, complex *l, complex *d, complex  
           *subl, complex *b, int ldb, int *ipiv, int *info);
```

```
void csttrs_64(long n, long nrhs, complex *l, complex *d,  
              complex *subl, complex *b, long ldb, long *ipiv,
```

```
long *info);
```

PURPOSE

csttrs computes the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N symmetric tridiagonal matrix and X and B are N-by-NRHS matrices.

ARGUMENTS

N (input) INTEGER
The order of the matrix A. $N \geq 0$.

NRHS (input)
INTEGER
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

L (input) COMPLEX array, dimension (N-1)
On entry, the subdiagonal elements of L.

D (input) COMPLEX array, dimension (N)
On entry, the diagonal elements of D.

SUBL (input)
COMPLEX array, dimension (N-2)
On entry, the second subdiagonal elements of L.

B (input/output)
COMPLEX array, dimension (LDB, NRHS)
On entry, the N-by-NRHS right hand side matrix B.
On exit, if $INFO = 0$, the N-by-NRHS solution matrix X.

LDB (input)
INTEGER
The leading dimension of the array B. $LDB \geq \max(1, N)$

IPIV (output)
INTEGER array, dimension (N)
Details of the interchanges and block pivot. If $IPIV(K) > 0$, 1 by 1 pivot, and if $IPIV(K) = K + 1$ an interchange done; If $IPIV(K) < 0$, 2 by 2 pivot, no interchange required.

INFO (output)
INTEGER
= 0: successful exit
< 0: if $INFO = -k$, the k-th argument had an illegal value

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NAME

cswap - Exchange vectors x and y.

SYNOPSIS

```
SUBROUTINE CSWAP(N, X, INCX, Y, INCY)
```

```
COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE CSWAP_64(N, X, INCX, Y, INCY)
```

```
COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE SWAP([N], X, [INCX], Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE SWAP_64([N], X, [INCX], Y, [INCY])
```

```
COMPLEX, DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cswap(int n, complex *x, int incx, complex *y, int  
           incy);
```

```
void cswap_64(long n, complex *x, long incx, complex *y,  
             long incy);
```

PURPOSE

cswap Exchange x and y where x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input/output)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x. On exit, the y vector.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input/output)

($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array Y must contain the vector y. On exit, the x vector.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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csycon - estimate the reciprocal of the condition number (in the 1-norm) of a complex symmetric matrix A using the factorization $A = U^*D*U^{**T}$ or $A = L^*D*L^{**T}$ computed by CSYTRF

SYNOPSIS

```
SUBROUTINE CSYCON(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*)  
REAL ANORM, RCOND
```

```
SUBROUTINE CSYCON_64(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK,  
INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*)  
REAL ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE SYCON(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL :: ANORM, RCOND
```

```
SUBROUTINE SYCON_64(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A
```

```
INTEGER(8) :: N, LDA, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>
void csycon(char uplo, int n, complex *a, int lda, int
            *ipivot, float anorm, float *rcond, int *info);

void csycon_64(char uplo, long n, complex *a, long lda, long
              *ipivot, float anorm, float *rcond, long *info);
```

PURPOSE

csycon estimates the reciprocal of the condition number (in the 1-norm) of a complex symmetric matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by CSYTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U*D*U**T$;
= 'L': Lower triangular, form is $A = L*D*L**T$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CSYTRF.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by CSYTRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

csymm - perform one of the matrix-matrix operations $C := \alpha A * B + \beta C$ or $C := \alpha B * A + \beta C$

SYNOPSIS

```
SUBROUTINE CSYMM(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                LDC)
```

```
CHARACTER * 1 SIDE, UPLO
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER M, N, LDA, LDB, LDC
```

```
SUBROUTINE CSYMM_64(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                   LDC)
```

```
CHARACTER * 1 SIDE, UPLO
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 M, N, LDA, LDB, LDC
```

F95 INTERFACE

```
SUBROUTINE SYMM(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
               BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:, :) :: A, B, C
INTEGER :: M, N, LDA, LDB, LDC
```

```
SUBROUTINE SYMM_64(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
                  BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:, :) :: A, B, C
INTEGER(8) :: M, N, LDA, LDB, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csymm(char side, char uplo, int m, int n, complex
           *alpha, complex *a, int lda, complex *b, int ldb,
           complex *beta, complex *c, int ldc);
```

```
void csymm_64(char side, char uplo, long m, long n, complex
              *alpha, complex *a, long lda, complex *b, long
              ldb, complex *beta, complex *c, long ldc);
```

PURPOSE

csymm performs one of the matrix-matrix operations $C := \alpha A^*B + \beta C$ or $C := \alpha B^*A + \beta C$ where α and β are scalars, A is a symmetric matrix and B and C are m by n matrices.

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether the symmetric matrix A appears on the left or right in the operation as follows:

SIDE = 'L' or 'l' $C := \alpha A^*B + \beta C$,

SIDE = 'R' or 'r' $C := \alpha B^*A + \beta C$,

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the symmetric matrix A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of the symmetric matrix is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of the symmetric matrix is to be referenced.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of the matrix C . $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix C . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

COMPLEX array of DIMENSION (LDA, ka), where ka is m when SIDE = 'L' or 'l' and is n other-

wise.

Before entry with SIDE = 'L' or 'l', the m by m part of the array A must contain the symmetric matrix, such that when UPLO = 'U' or 'u', the leading m by m upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading m by m lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced.

Before entry with SIDE = 'R' or 'r', the n by n part of the array A must contain the symmetric matrix, such that when UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced.

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then $LDA \geq \max(1, m)$, otherwise $LDA \geq \max(1, n)$. Unchanged on exit.

B (input)

COMPLEX array of DIMENSION (LDB, n). Before entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. $LDB \geq \max(1, m)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then C need not be set on input. Unchanged on exit.

C (input/output)

COMPLEX array of DIMENSION (LDC, n). Before entry, the leading m by n part of the array C must contain the matrix C, except when beta is zero, in which case C need not be set on entry. On exit, the array C is overwritten by the m by n updated matrix.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program.

LDC \geq max(1, m). Unchanged on exit.

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NAME

csyr2k - perform one of the symmetric rank 2k operations $C := \alpha A^*B' + \alpha B^*A' + \beta C$ or $C := \alpha A^*B + \alpha B^*A + \beta C$

SYNOPSIS

```
SUBROUTINE CSYR2K(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA, C,
                 LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER N, K, LDA, LDB, LDC
```

```
SUBROUTINE CSYR2K_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA,
                    C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
COMPLEX ALPHA, BETA
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 N, K, LDA, LDB, LDC
```

F95 INTERFACE

```
SUBROUTINE SYR2K(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B, [LDB],
                BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:,) :: A, B, C
INTEGER :: N, K, LDA, LDB, LDC
```

```
SUBROUTINE SYR2K_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B,
                   [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
COMPLEX :: ALPHA, BETA
COMPLEX, DIMENSION(:,) :: A, B, C
INTEGER(8) :: N, K, LDA, LDB, LDC
```

C INTERFACE

```
#include <sunperf.h>

void csyr2k(char uplo, char transa, int n, int k, complex
            *alpha, complex *a, int lda, complex *b, int ldb,
            complex *beta, complex *c, int ldc);
void csyr2k_64(char uplo, char transa, long n, long k, com-
               plex *alpha, complex *a, long lda, complex *b,
               long ldb, complex *beta, complex *c, long ldc);
```

PURPOSE

csyr2k performs one of the symmetric rank 2k operations $C := \alpha A^*B' + \alpha B^*A' + \beta C$ or $C := \alpha A^*B + \alpha B^*A + \beta C$ where α and β are scalars, C is an n by n symmetric matrix and A and B are n by k matrices in the first case and k by n matrices in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A^*B' + \alpha B^*A' + \beta C$.

TRANSA = 'T' or 't' $C := \alpha A^*B + \alpha B^*A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrices A and B , and on entry with TRANSA = 'T' or 't', K specifies the number of rows of the matrices A

and B. K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

COMPLEX array of DIMENSION (LDA, ka), where ka is k when TRANSA = 'N' or 'n', and is n otherwise. Before entry with TRANSA = 'N' or 'n', the leading n by k part of the array A must contain the matrix A, otherwise the leading k by n part of the array A must contain the matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When TRANSA = 'N' or 'n' then LDA must be at least $\max(1, n)$, otherwise LDA must be at least $\max(1, k)$. Unchanged on exit.

B (input)

COMPLEX array of DIMENSION (LDB, kb), where kb is k when TRANSA = 'N' or 'n', and is n otherwise. Before entry with TRANSA = 'N' or 'n', the leading n by k part of the array B must contain the matrix B, otherwise the leading k by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. When TRANSA = 'N' or 'n' then LDB must be at least $\max(1, n)$, otherwise LDB must be at least $\max(1, k)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. Unchanged on exit.

C (input/output)

COMPLEX array of DIMENSION (LDC, n).

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array C must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of C is not referenced. On exit, the upper triangular part of the array C is overwritten by the upper triangular part of the updated matrix.

Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array C must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of C is not referenced. On exit, the lower triangular part of the array C is overwritten by the lower triangular part of the updated

matrix.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. LDC must be at least $\max(1, n)$. Unchanged on exit.

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NAME

csyrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE CSYRFS(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CSYRFS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,  
  X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*)  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE SYRFS(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT, B,  
  [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE SYRFS_64(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT,  
  B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: FERR, BERR, WORK2
C INTERFACE
#include <sunperf.h>

void csyrfs(char uplo, int n, int nrhs, complex *a, int lda,
            complex *af, int ldaf, int *ipivot, complex *b,
            int ldb, complex *x, int ldx, float *ferr, float
            *berr, int *info);

void csyrfs_64(char uplo, long n, long nrhs, complex *a,
               long lda, complex *af, long ldaf, long *ipivot,
               complex *b, long ldb, complex *x, long ldx, float
               *ferr, float *berr, long *info);

```

PURPOSE

csyrfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)
 The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^T$ or $A = L*D*L^T$ as computed by CSYTRF.

LDAF (input)
 The leading dimension of the array AF. LDAF \geq max(1,N).

IPIVOT (input)
 Details of the interchanges and the block structure of D as determined by CSYTRF.

B (input) The right hand side matrix B.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
 On entry, the solution matrix X, as computed by CSYTRS. On exit, the improved solution matrix X.

LDX (input)
 The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(2*N)

WORK2 (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

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NAME

csyrk - perform one of the symmetric rank k operations C
:= alpha*A*A' + beta*C or C := alpha*A'*A + beta*C

SYNOPSIS

```
SUBROUTINE CSYRK(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
COMPLEX ALPHA, BETA  
COMPLEX A(LDA,*), C(LDC,*)  
INTEGER N, K, LDA, LDC
```

```
SUBROUTINE CSYRK_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
COMPLEX ALPHA, BETA  
COMPLEX A(LDA,*), C(LDC,*)  
INTEGER*8 N, K, LDA, LDC
```

F95 INTERFACE

```
SUBROUTINE SYRK(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA, C,  
[LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:,*) :: A, C  
INTEGER :: N, K, LDA, LDC
```

```
SUBROUTINE SYRK_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA,  
C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:,*) :: A, C  
INTEGER(8) :: N, K, LDA, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csyrk(char uplo, char transa, int n, int k, complex
```

```

        *alpha, complex *a, int lda, complex *beta, com-
        plex *c, int ldc);

void csyrk_64(char uplo, char transa, long n, long k, com-
        plex *alpha, complex *a, long lda, complex *beta,
        complex *c, long ldc);

```

PURPOSE

csyrk performs one of the symmetric rank k operations $C := \alpha A^T A + \beta C$ or $C := \alpha A A^T + \beta C$ where α and β are scalars, C is an n by n symmetric matrix and A is an n by k matrix in the first case and a k by n matrix in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A^T A + \beta C$.

TRANSA = 'T' or 't' $C := \alpha A A^T + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C. N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrix A, and on entry with TRANSA = 'T' or 't', K specifies the number of rows of the matrix A. K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

COMPLEX array of DIMENSION (LDA, ka),
where ka is k when TRANSA = 'N' or 'n', and is
n otherwise. Before entry with TRANSA = 'N' or
'n', the leading n by k part of the array A
must contain the matrix A, otherwise the leading
k by n part of the array A must contain the
matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A
as declared in the calling (sub) program.
When TRANSA = 'N' or 'n' then LDA must be at
least $\max(1, n)$, otherwise LDA must be at
least $\max(1, k)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta.
Unchanged on exit.

C (input/output)

COMPLEX array of DIMENSION (LDC, n).

Before entry with UPLO = 'U' or 'u', the lead-
ing n by n upper triangular part of the array C
must contain the upper triangular part of the
symmetric matrix and the strictly lower triangu-
lar part of C is not referenced. On exit, the
upper triangular part of the array C is overwrit-
ten by the upper triangular part of the updated
matrix.

Before entry with UPLO = 'L' or 'l', the lead-
ing n by n lower triangular part of the array C
must contain the lower triangular part of the
symmetric matrix and the strictly upper triangu-
lar part of C is not referenced. On exit, the
lower triangular part of the array C is overwrit-
ten by the lower triangular part of the updated
matrix.

LDC (input)

On entry, LDC specifies the first dimension of C
as declared in the calling (sub) program.
LDC must be at least $\max(1, n)$. Unchanged
on exit.

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NAME

csysv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CSYSV(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK, LWORK,
                INFO)
```

```
CHARACTER * 1 UPLO
COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER N, NRHS, LDA, LDB, LWORK, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE CSYSV_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK, LWORK,
                   INFO)
```

```
CHARACTER * 1 UPLO
COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER*8 N, NRHS, LDA, LDB, LWORK, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SYSV(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],
               [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER :: N, NRHS, LDA, LDB, LWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SYSV_64(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],
                  [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER(8) :: N, NRHS, LDA, LDB, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void csysv(char uplo, int n, int nrhs, complex *a, int lda,
           int *ipivot, complex *b, int ldb, int *info);
void csysv_64(char uplo, long n, long nrhs, complex *a, long
              lda, long *ipivot, complex *b, long ldb, long
              *info);
```

PURPOSE

csysv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N symmetric matrix and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{**T}$, if UPLO = 'U', or

$A = L * D * L^{**T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U * D * U^{**T}$ or $A = L * D * L^{**T}$ as computed by CSYTRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D , as determined by CSYTRF. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B .
On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LWORK$.

LWORK (input)

The length of $WORK$. $LWORK \geq 1$, and for best performance $LWORK \geq N*NB$, where NB is the optimal blocksize for CSYTRF.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $WORK$ array, returns this value as the first entry of the $WORK$ array, and no error message related to $LWORK$ is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

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NAME

csysvx - use the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE CSYSVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,  
                 LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER IPIVOT(*)  
REAL RCOND  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CSYSVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT,  
                    B, LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO  
COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER*8 IPIVOT(*)  
REAL RCOND  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE SYSVX(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],  
                IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK],  
                [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL :: RCOND  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE SYSVX_64(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],
```

```
IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, AF, B, X  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL :: RCOND  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csysvx(char fact, char uplo, int n, int nrhs, complex  
*a, int lda, complex *af, int ldaf, int *ipivot,  
complex *b, int ldb, complex *x, int ldx, float  
*rcond, float *ferr, float *berr, int *info);
```

```
void csysvx_64(char fact, char uplo, long n, long nrhs, com-  
plex *a, long lda, complex *af, long ldaf, long  
*ipivot, complex *b, long ldb, complex *x, long  
ldx, float *rcond, float *ferr, float *berr, long  
*info);
```

PURPOSE

csysvx uses the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$, where A is an N -by- N symmetric matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the diagonal pivoting method is used to factor A .

The form of the factorization is

$A = U * D * U^{*T}$, if $UPLO = 'U'$, or

$A = L * D * L^{*T}$, if $UPLO = 'L'$,

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices, and D is symmetric and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than machine precision,

$INFO = N+1$ is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described

below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. A, AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by CSYTRF.

If FACT = 'N', then AF is an output argument and on exit returns the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq$

max(1,N).

IPIVOT (input or output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by CSYTRF. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

If FACT = 'N', then IPIVOT is an output argument and on exit contains details of the interchanges and the block structure of D, as determined by CSYTRF.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)

The leading dimension of the array X. LDX >= max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of WORK. LDWORK $\geq 2*N$, and for best performance LDWORK $\geq N*NB$, where NB is the optimal blocksize for CSYTRF.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned.
= N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

csytf2 - compute the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE CSYTF2(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE CSYTF2_64(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE SYTF2(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE SYTF2_64(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:,) :: A  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csytf2(char uplo, int n, complex *a, int lda, int
```

```

        *ipiv, int *info);

void csytf2_64(char uplo, long n, complex *a, long lda, long
        *ipiv, long *info);

```

PURPOSE

csytf2 computes the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U' \quad \text{or} \quad A = L^*D^*L'$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, U' is the transpose of U, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored:

= 'U': Upper triangular
 = 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading n-by-n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n-by-n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIV (output)

Details of the interchanges and the block structure of D. If IPIV(k) > 0, then rows and columns k and IPIV(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIV(k) = IPIV(k-1) < 0, then rows and columns k-1 and -IPIV(k) were interchanged and D(k-1:k, k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIV(k) = IPIV(k+1) < 0, then rows and columns k+1 and

-IPIV(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

INFO (output)

= 0: successful exit
 < 0: if INFO = -k, the k-th argument had an illegal value
 > 0: if INFO = k, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

1-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

csytrf - compute the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE CSYTRF(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, LDWORK, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CSYTRF_64(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, LDWORK, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRF(UPLO, [N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SYTRF_64(UPLO, [N], A, [LDA], IPIVOT, [WORK], [LDWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```

#include <sunperf.h>

void csytrf(char uplo, int n, complex *a, int lda, int
            *ipivot, int *info);

void csytrf_64(char uplo, long n, complex *a, long lda, long
               *ipivot, long *info);

```

PURPOSE

csytrf computes the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method. The form of the factorization is

$$A = U*D*U^{*T} \quad \text{or} \quad A = L*D*L^{*T}$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and

D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of WORK. LDWORK >=1. For best performance LDWORK >= N*Nb, where Nb is the block size returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

If UPLO = 'U', then $A = U^*D^*U'$, where

$$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots,$$

i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by IPIVOT(k), and $U(k)$ is a unit upper triangular matrix, such that if the diagonal block $D(k)$ is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(1:k-1,k)$. If s = 2, the upper triangle of $D(k)$ overwrites $A(k-1,k-1)$, $A(k-1,k)$, and $A(k,k)$, and v overwrites $A(1:k-2,k-1:k)$.

If UPLO = 'L', then $A = L^*D^*L'$, where

$$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots,$$

i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by IPIVOT(k), and $L(k)$ is a unit lower triangular matrix, such that if the diagonal block $D(k)$ is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(k+1:n,k)$. If $s = 2$, the lower triangle of $D(k)$ overwrites $A(k,k)$, $A(k+1,k)$, and $A(k+1,k+1)$, and v overwrites $A(k+2:n,k:k+1)$.

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NAME

csytri - compute the inverse of a complex symmetric indefinite matrix A using the factorization $A = U*D*U^*T$ or $A = L*D*L^*T$ computed by CSYTRF

SYNOPSIS

```
SUBROUTINE CSYTRI(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CSYTRI_64(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRI(UPLO, [N], A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SYTRI_64(UPLO, [N], A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void csytri(char uplo, int n, complex *a, int lda, int
            *ipivot, int *info);

void csytri_64(char uplo, long n, complex *a, long lda, long
               *ipivot, long *info);

```

PURPOSE

csytri computes the inverse of a complex symmetric indefinite matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by CSYTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U*D*U**T$;
 = 'L': Lower triangular, form is $A = L*D*L**T$.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CSYTRF.

On exit, if INFO = 0, the (symmetric) inverse of the original matrix. If UPLO = 'U', the upper triangular part of the inverse is formed and the part of A below the diagonal is not referenced; if UPLO = 'L' the lower triangular part of the inverse is formed and the part of A above the diagonal is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by CSYTRF.

WORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

csytrs - solve a system of linear equations $A \cdot X = B$ with a complex symmetric matrix A using the factorization $A = U \cdot D \cdot U^* \cdot T$ or $A = L \cdot D \cdot L^* \cdot T$ computed by CSYTRF

SYNOPSIS

```
SUBROUTINE CSYTRS(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE CSYTRS_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRS(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SYTRS_64(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:, :) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void csytrs(char uplo, int n, int nrhs, complex *a, int lda,
```

```

        int *ipivot, complex *b, int ldb, int *info);

void csytrs_64(char uplo, long n, long nrhs, complex *a,
              long lda, long *ipivot, complex *b, long ldb, long
              *info);

```

PURPOSE

csytrs solves a system of linear equations $A \cdot X = B$ with a complex symmetric matrix A using the factorization $A = U \cdot D \cdot U^* \cdot T$ or $A = L \cdot D \cdot L^* \cdot T$ computed by CSYTRF.

ARGUMENTS

UPLO (input)
 Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U \cdot D \cdot U^* \cdot T$;
 = 'L': Lower triangular, form is $A = L \cdot D \cdot L^* \cdot T$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by CSYTRF.

LDA (input)
 The leading dimension of the array A . $LDA \geq \max(1, N)$.

IPIVOT (input)
 Details of the interchanges and the block structure of D as determined by CSYTRF.

B (input/output)
 On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)
 The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)
 = 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

ctbcon - estimate the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE CTBCON(NORM, UPLO, DIAG, N, KD, A, LDA, RCOND, WORK,  
                 WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, KD, LDA, INFO  
REAL RCOND  
REAL WORK2(*)
```

```
SUBROUTINE CTBCON_64(NORM, UPLO, DIAG, N, KD, A, LDA, RCOND, WORK,  
                   WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, KD, LDA, INFO  
REAL RCOND  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TBCON(NORM, UPLO, DIAG, [N], KD, A, [LDA], RCOND, [WORK],  
                [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, KD, LDA, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE TBCON_64(NORM, UPLO, DIAG, [N], KD, A, [LDA], RCOND,  
                  [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX, DIMENSION(:) :: WORK
```

```
COMPLEX, DIMENSION(:, :) :: A
INTEGER(8) :: N, KD, LDA, INFO
REAL :: RCOND
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void ctbcon(char norm, char uplo, char diag, int n, int kd,
            complex *a, int lda, float *rcond, int *info);

void ctbcon_64(char norm, char uplo, char diag, long n, long
               kd, complex *a, long lda, float *rcond, long
               *info);
```

PURPOSE

ctbcon estimates the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first $kd+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)
The leading dimension of the array A. LDA \geq
KD+1.

RCOND (output)
The reciprocal of the condition number of the
matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ctbmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$

SYNOPSIS

```
SUBROUTINE CTBMV(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), Y(*)  
INTEGER N, K, LDA, INCY
```

```
SUBROUTINE CTBMV_64(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), Y(*)  
INTEGER*8 N, K, LDA, INCY
```

F95 INTERFACE

```
SUBROUTINE TBMV(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, K, LDA, INCY
```

```
SUBROUTINE TBMV_64(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, K, LDA, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctbmv(char uplo, char transa, char diag, int n, int k,  
complex *a, int lda, complex *y, int incy);
```

```
void ctbmv_64(char uplo, char transa, char diag, long n,
```

```
long k, complex *a, long lda, complex *y, long
incy);
```

PURPOSE

ctbmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A)*x$ where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular band matrix, with $(k + 1)$ diagonals.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANS (input)

On entry, TRANS specifies the operation to be performed as follows:

TRANS = 'N' or 'n' $x := A*x$.

TRANS = 'T' or 't' $x := A'*x$.

TRANS = 'C' or 'c' $x := \text{conjg}(A)*x$.

Unchanged on exit.

TRANS is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

K (input)

On entry with UPLO = 'U' or 'u', K specifies the number of super-diagonals of the matrix A . On

entry with UPLO = 'L' or 'l', K specifies the number of sub-diagonals of the matrix A. K >= 0. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading (k + 1) by n part of the array A must contain the upper triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (k + 1) of the array, the first super-diagonal starting at position 2 in row k, and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer an upper triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer a lower triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Note that when DIAG = 'U' or 'u' the elements of the array A corresponding to the diagonal elements of the matrix are not referenced, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= (k + 1). Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

ctbrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix

SYNOPSIS

```
SUBROUTINE CTBRFS(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B, LDB,  
X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, KD, NRHS, LDA, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CTBRFS_64(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B,  
LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, KD, NRHS, LDA, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TBRFS(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA],  
B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, B, X  
INTEGER :: N, KD, NRHS, LDA, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE TBRFS_64(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA],  
B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, B, X  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void ctbrfs(char uplo, char transa, char diag, int n, int
            kd, int nrhs, complex *a, int lda, complex *b, int
            ldb, complex *x, int ldx, float *ferr, float
            *berr, int *info);

void ctbrfs_64(char uplo, char transa, char diag, long n,
              long kd, long nrhs, complex *a, long lda, complex
              *b, long ldb, complex *x, long ldx, float *ferr,
              float *berr, long *info);
```

PURPOSE

ctbrfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix.

The solution matrix X must be computed by CTBTRS or some other means before entering this routine. CTBRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first kd+1 rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-$

$j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if $UPLO = 'L'$, $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. If $DIAG = 'U'$, the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A . $LDA \geq KD+1$.

B (input) The right hand side matrix B .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

X (input) The solution matrix X .

LDX (input)

The leading dimension of the array X . $LDX \geq \max(1,N)$.

FERR (output)

The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for $RCOND$, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension($2*N$)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

ctbsv - solve one of the systems of equations $Ax = b$, or $A^T x = b$, or $\text{conjg}(A^T)x = b$

SYNOPSIS

```
SUBROUTINE CTBSV(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), Y(*)  
INTEGER N, K, LDA, INCY
```

```
SUBROUTINE CTBSV_64(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), Y(*)  
INTEGER*8 N, K, LDA, INCY
```

F95 INTERFACE

```
SUBROUTINE TBSV(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, K, LDA, INCY
```

```
SUBROUTINE TBSV_64(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, K, LDA, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctbsv(char uplo, char transa, char diag, int n, int k,  
complex *a, int lda, complex *y, int incy);
```

```
void ctbsv_64(char uplo, char transa, char diag, long n,
```

```
long k, complex *a, long lda, complex *y, long
incy);
```

PURPOSE

ctbsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A)*x = b$ where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular band matrix, with $(k + 1)$ diagonals.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the equations to be solved as follows:

TRANSA = 'N' or 'n' $A*x = b$.

TRANSA = 'T' or 't' $A'*x = b$.

TRANSA = 'C' or 'c' $\text{conjg}(A)*x = b$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A .

N >= 0. Unchanged on exit.

K (input)

On entry with UPLO = 'U' or 'u', K specifies the number of super-diagonals of the matrix A. On entry with UPLO = 'L' or 'l', K specifies the number of sub-diagonals of the matrix A. K >= 0. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading (k + 1) by n part of the array A must contain the upper triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (k + 1) of the array, the first super-diagonal starting at position 2 in row k, and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer an upper triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
  10 CONTINUE
  20 CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer a lower triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
  10 CONTINUE
  20 CONTINUE
```

Note that when DIAG = 'U' or 'u' the elements of the array A corresponding to the diagonal elements of the matrix are not referenced, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= (k + 1). Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element

right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

ctbtrs - solve a triangular system of the form $A * X = B$,
 $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE CTBTRS(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B, LDB,  
INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE CTBTRS_64(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B,  
LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE TBTRS(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA], B,  
[LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE TBTRS_64(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA],  
B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctbtrs(char uplo, char transa, char diag, int n, int  
kd, int nrhs, complex *a, int lda, complex *b, int  
ldb, int *info);
```

```
void ctbtrs_64(char uplo, char transa, char diag, long n,
              long kd, long nrhs, complex *a, long lda, complex
              *b, long ldb, long *info);
```

PURPOSE

ctbtrs solves a triangular system of the form

$A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$

where A is a triangular band matrix of order N, and B is an N-by-NRHS matrix. A check is made to verify that A is non-singular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:

= 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose)

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first $kd+1$ rows of A. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

B (input/output)

On entry, the right hand side matrix B. On exit, if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the i-th diagonal element of A is zero, indicating that the matrix is singular and the solutions X have not been computed.

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NAME

ctgevc - compute some or all of the right and/or left generalized eigenvectors of a pair of complex upper triangular matrices (A,B)

SYNOPSIS

```
SUBROUTINE CTGEVC(SIDE, HOWMNY, SELECT, N, A, LDA, B, LDB, VL, LDVL,  
  VR, LDVR, MM, M, WORK, RWORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
COMPLEX A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL SELECT(*)  
REAL RWORK(*)
```

```
SUBROUTINE CTGEVC_64(SIDE, HOWMNY, SELECT, N, A, LDA, B, LDB, VL,  
  LDVL, VR, LDVR, MM, M, WORK, RWORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
COMPLEX A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL*8 SELECT(*)  
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGEVC(SIDE, HOWMNY, SELECT, [N], A, [LDA], B, [LDB], VL,  
  [LDVL], VR, [LDVR], MM, M, [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B, VL, VR  
INTEGER :: N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL, DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: RWORK
```

```
SUBROUTINE TGEVC_64(SIDE, HOWMNY, SELECT, [N], A, [LDA], B, [LDB],  
  VL, [LDVL], VR, [LDVR], MM, M, [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
COMPLEX, DIMENSION(:) :: WORK
```

```

COMPLEX, DIMENSION(:,:) :: A, B, VL, VR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, MM, M, INFO
LOGICAL(8), DIMENSION(:) :: SELECT
REAL, DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>
void ctgevc(char side, char howmny, int *select, int n, complex *a, int lda, complex *b, int ldb, complex *vl, int ldvl, complex *vr, int ldvr, int mm, int *m, int *info);

void ctgevc_64(char side, char howmny, long *select, long n, complex *a, long lda, complex *b, long ldb, complex *vl, long ldvl, complex *vr, long ldvr, long mm, long *m, long *info);

```

PURPOSE

ctgevc computes some or all of the right and/or left generalized eigenvectors of a pair of complex upper triangular matrices (A,B).

The right generalized eigenvector x and the left generalized eigenvector y of (A,B) corresponding to a generalized eigenvalue w are defined by:

$$(A - wB) * x = 0 \quad \text{and} \quad y^{*H} * (A - wB) = 0$$

where y^{*H} denotes the conjugate transpose of y .

If an eigenvalue w is determined by zero diagonal elements of both A and B , a unit vector is returned as the corresponding eigenvector.

If all eigenvectors are requested, the routine may either return the matrices X and/or Y of right or left eigenvectors of (A,B), or the products $Z*X$ and/or $Q*Y$, where Z and Q are input unitary matrices. If (A,B) was obtained from the generalized Schur factorization of an original pair of matrices

$$(A0, B0) = (Q*A*Z^{*H}, Q*B*Z^{*H}),$$

then $Z*X$ and $Q*Y$ are the matrices of right or left eigenvectors of A .

ARGUMENTS

SIDE (input)

```

= 'R': compute right eigenvectors only;
= 'L': compute left eigenvectors only;
= 'B': compute both right and left eigenvectors.

```

HOWMNY (input)

```

= 'A': compute all right and/or left eigenvectors;
= 'B': compute all right and/or left eigenvectors,
and backtransform them using the input matrices
supplied in VR and/or VL; = 'S': compute selected

```

right and/or left eigenvectors, specified by the logical array SELECT.

SELECT (input)

If HOWMNY='S', SELECT specifies the eigenvectors to be computed. If HOWMNY='A' or 'B', SELECT is not referenced. To select the eigenvector corresponding to the j-th eigenvalue, SELECT(j) must be set to .TRUE..

N (input) The order of the matrices A and B. $N \geq 0$.

A (input) The upper triangular matrix A.

LDA (input)

The leading dimension of array A. $LDA \geq \max(1,N)$.

B (input) The upper triangular matrix B. B must have real diagonal elements.

LDB (input)

The leading dimension of array B. $LDB \geq \max(1,N)$.

VL (input/output)

On entry, if SIDE = 'L' or 'B' and HOWMNY = 'B', VL must contain an N-by-N matrix Q (usually the unitary matrix Q of left Schur vectors returned by CHGEQZ). On exit, if SIDE = 'L' or 'B', VL contains: if HOWMNY = 'A', the matrix Y of left eigenvectors of (A,B); if HOWMNY = 'B', the matrix $Q*Y$; if HOWMNY = 'S', the left eigenvectors of (A,B) specified by SELECT, stored consecutively in the columns of VL, in the same order as their eigenvalues. If SIDE = 'R', VL is not referenced.

LDVL (input)

The leading dimension of array VL. $LDVL \geq \max(1,N)$ if SIDE = 'L' or 'B'; $LDVL \geq 1$ otherwise.

VR (input/output)

On entry, if SIDE = 'R' or 'B' and HOWMNY = 'B', VR must contain an N-by-N matrix Q (usually the unitary matrix Z of right Schur vectors returned by CHGEQZ). On exit, if SIDE = 'R' or 'B', VR contains: if HOWMNY = 'A', the matrix X of right eigenvectors of (A,B); if HOWMNY = 'B', the matrix $Z*X$; if HOWMNY = 'S', the right eigenvectors of (A,B) specified by SELECT, stored consecutively in the columns of VR, in the same order as their eigenvalues. If SIDE = 'L', VR is not referenced.

LDVR (input)

The leading dimension of the array VR. $LDVR \geq \max(1,N)$ if SIDE = 'R' or 'B'; $LDVR \geq 1$ otherwise.

MM (input)

The number of columns in the arrays VL and/or VR.

MM \geq M.

M (output)

The number of columns in the arrays VL and/or VR actually used to store the eigenvectors. If HOWMNY = 'A' or 'B', M is set to N. Each selected eigenvector occupies one column.

WORK (workspace)

dimension(2*N)

RWORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

ctgexc - reorder the generalized Schur decomposition of a complex matrix pair (A,B), using an unitary equivalence transformation $(A, B) := Q * (A, B) * Z'$, so that the diagonal block of (A, B) with row index IFST is moved to row ILST

SYNOPSIS

```
SUBROUTINE CTGEXC(WANTQ, WANTZ, N, A, LDA, B, LDB, Q, LDQ, Z, LDZ,
  IFST, ILST, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
INTEGER N, LDA, LDB, LDQ, LDZ, IFST, ILST, INFO
LOGICAL WANTQ, WANTZ
```

```
SUBROUTINE CTGEXC_64(WANTQ, WANTZ, N, A, LDA, B, LDB, Q, LDQ, Z, LDZ,
  IFST, ILST, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
INTEGER*8 N, LDA, LDB, LDQ, LDZ, IFST, ILST, INFO
LOGICAL*8 WANTQ, WANTZ
```

F95 INTERFACE

```
SUBROUTINE TGEXC(WANTQ, WANTZ, [N], A, [LDA], B, [LDB], Q, [LDQ], Z,
  [LDZ], IFST, ILST, [INFO])
```

```
COMPLEX, DIMENSION(:,:) :: A, B, Q, Z
INTEGER :: N, LDA, LDB, LDQ, LDZ, IFST, ILST, INFO
LOGICAL :: WANTQ, WANTZ
```

```
SUBROUTINE TGEXC_64(WANTQ, WANTZ, [N], A, [LDA], B, [LDB], Q, [LDQ],
  Z, [LDZ], IFST, ILST, [INFO])
```

```
COMPLEX, DIMENSION(:,:) :: A, B, Q, Z
INTEGER(8) :: N, LDA, LDB, LDQ, LDZ, IFST, ILST, INFO
LOGICAL(8) :: WANTQ, WANTZ
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctgexc(int wantq, int wantz, int n, complex *a, int
           lda, complex *b, int ldb, complex *q, int ldq,
           complex *z, int ldz, int *ifst, int *ilst, int
           *info);
```

```
void ctgexc_64(long wantq, long wantz, long n, complex *a,
              long lda, complex *b, long ldb, complex *q, long
              ldq, complex *z, long ldz, long *ifst, long *ilst,
              long *info);
```

PURPOSE

ctgexc reorders the generalized Schur decomposition of a complex matrix pair (A,B), using an unitary equivalence transformation $(A, B) := Q * (A, B) * Z'$, so that the diagonal block of (A, B) with row index IFST is moved to row ILST.

(A, B) must be in generalized Schur canonical form, that is, A and B are both upper triangular.

Optionally, the matrices Q and Z of generalized Schur vectors are updated.

$$Q(\text{in}) * A(\text{in}) * Z(\text{in})' = Q(\text{out}) * A(\text{out}) * Z(\text{out})'$$

$$Q(\text{in}) * B(\text{in}) * Z(\text{in})' = Q(\text{out}) * B(\text{out}) * Z(\text{out})'$$

ARGUMENTS

WANTQ (input)

WANTZ (input)

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the upper triangular matrix A in the pair (A, B). On exit, the updated matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the upper triangular matrix B in the pair (A, B). On exit, the updated matrix B.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

Q (input/output)

On entry, if WANTQ = .TRUE., the unitary matrix Q. On exit, the updated matrix Q. If WANTQ = .FALSE., Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. LDQ \geq 1; If
 WANTQ = .TRUE., LDQ \geq N.

Z (input/output)
 On entry, if WANTZ = .TRUE., the unitary matrix Z.
 On exit, the updated matrix Z. If WANTZ =
 .FALSE., Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. LDZ \geq 1; If
 WANTZ = .TRUE., LDZ \geq N.

IFST (input/output)
 Specify the reordering of the diagonal blocks of
 (A, B). The block with row index IFST is moved to
 row ILST, by a sequence of swapping between adja-
 cent blocks.

ILST (input/output)
 See the description of IFST.

INFO (output)
 =0: Successful exit.
 <0: if INFO = -i, the i-th argument had an ille-
 gal value.
 =1: The transformed matrix pair (A, B) would be
 too far from generalized Schur form; the problem
 is ill- conditioned. (A, B) may have been par-
 tially reordered, and ILST points to the first row
 of the current position of the block being moved.

FURTHER DETAILS

Based on contributions by
 Bo Kagstrom and Peter Poromaa, Department of Computing
 Science,
 Umea University, S-901 87 Umea, Sweden.

[1] B. Kagstrom; A Direct Method for Reordering Eigenvalues
 in the
 Generalized Real Schur Form of a Regular Matrix Pair (A,
 B), in
 M.S. Moonen et al (eds), Linear Algebra for Large Scale
 and
 Real-Time Applications, Kluwer Academic Publ. 1993, pp
 195-218.

[2] B. Kagstrom and P. Poromaa; Computing Eigenspaces with
 Specified
 Eigenvalues of a Regular Matrix Pair (A, B) and Condi-
 tion
 Estimation: Theory, Algorithms and Software, Report
 UMINF - 94.04, Department of Computing Science, Umea
 University,
 S-901 87 Umea, Sweden, 1994. Also as LAPACK Working Note
 87.
 To appear in Numerical Algorithms, 1996.

[3] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK working Note 75. To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

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NAME

ctgsen - reorder the generalized Schur decomposition of a complex matrix pair (A, B) (in terms of an unitary equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the pair (A,B)

SYNOPSIS

```
SUBROUTINE CTGSEN(IJOB, WANTQ, WANTZ, SELECT, N, A, LDA, B, LDB,
    ALPHA, BETA, Q, LDQ, Z, LDZ, M, PL, PR, DIF, WORK, LWORK, IWORK,
    LIWORK, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), Q(LDQ,*),
Z(LDZ,*), WORK(*)
INTEGER IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL WANTQ, WANTZ
LOGICAL SELECT(*)
REAL PL, PR
REAL DIF(*)
```

```
SUBROUTINE CTGSEN_64(IJOB, WANTQ, WANTZ, SELECT, N, A, LDA, B, LDB,
    ALPHA, BETA, Q, LDQ, Z, LDZ, M, PL, PR, DIF, WORK, LWORK, IWORK,
    LIWORK, INFO)
```

```
COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), Q(LDQ,*),
Z(LDZ,*), WORK(*)
INTEGER*8 IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER*8 IWORK(*)
LOGICAL*8 WANTQ, WANTZ
LOGICAL*8 SELECT(*)
REAL PL, PR
REAL DIF(*)
```

F95 INTERFACE

```
SUBROUTINE TGSSEN(IJOB, WANTQ, WANTZ, SELECT, [N], A, [LDA], B, [LDB],
    ALPHA, BETA, Q, [LDQ], Z, [LDZ], M, PL, PR, DIF, [WORK], [LWORK],
```

```

        [IWORK], [LIWORK], [INFO])

COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:,:) :: A, B, Q, Z
INTEGER :: IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL :: WANTQ, WANTZ
LOGICAL, DIMENSION(:) :: SELECT
REAL :: PL, PR
REAL, DIMENSION(:) :: DIF
SUBROUTINE TGSSEN_64(IJOB, WANTQ, WANTZ, SELECT, [N], A, [LDA], B,
        [LDB], ALPHA, BETA, Q, [LDQ], Z, [LDZ], M, PL, PR, DIF, [WORK],
        [LWORK], [IWORK], [LIWORK], [INFO])

COMPLEX, DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX, DIMENSION(:,:) :: A, B, Q, Z
INTEGER(8) :: IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8) :: WANTQ, WANTZ
LOGICAL(8), DIMENSION(:) :: SELECT
REAL :: PL, PR
REAL, DIMENSION(:) :: DIF

```

C INTERFACE

```

#include <sunperf.h>

void ctgsen(int ijob, int wantq, int wantz, int *select, int
        n, complex *a, int lda, complex *b, int ldb, com-
        plex *alpha, complex *beta, complex *q, int ldq,
        complex *z, int ldz, int *m, float *pl, float *pr,
        float *dif, int *info);

void ctgsen_64(long ijob, long wantq, long wantz, long
        *select, long n, complex *a, long lda, complex *b,
        long ldb, complex *alpha, complex *beta, complex
        *q, long ldq, complex *z, long ldz, long *m, float
        *pl, float *pr, float *dif, long *info);

```

PURPOSE

ctgsen reorders the generalized Schur decomposition of a complex matrix pair (A, B) (in terms of an unitary equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the pair (A,B). The leading columns of Q and Z form unitary bases of the corresponding left and right eigenspaces (deflating subspaces). (A, B) must be in generalized Schur canonical form, that is, A and B are both upper triangular.

CTGSEN also computes the generalized eigenvalues

$$w(j) = \text{ALPHA}(j) / \text{BETA}(j)$$

of the reordered matrix pair (A, B).

Optionally, the routine computes estimates of reciprocal

condition numbers for eigenvalues and eigenspaces. These are $\text{Difu}[(A_{11}, B_{11}), (A_{22}, B_{22})]$ and $\text{Difl}[(A_{11}, B_{11}), (A_{22}, B_{22})]$, i.e. the separation(s) between the matrix pairs (A_{11}, B_{11}) and (A_{22}, B_{22}) that correspond to the selected cluster and the eigenvalues outside the cluster, resp., and norms of "projections" onto left and right eigenspaces w.r.t. the selected cluster in the (1,1)-block.

ARGUMENTS

IJOB (input)

Specifies whether condition numbers are required for the cluster of eigenvalues (PL and PR) or the deflating subspaces (Difu and Difl):

=0: Only reorder w.r.t. SELECT. No extras.

=1: Reciprocal of norms of "projections" onto left and right eigenspaces w.r.t. the selected cluster (PL and PR). =2: Upper bounds on Difu and Difl. F-norm-based estimate

($\text{DIF}(1:2)$).

=3: Estimate of Difu and Difl. 1-norm-based estimate

($\text{DIF}(1:2)$). About 5 times as expensive as IJOB = 2. =4: Compute PL, PR and DIF (i.e. 0, 1 and 2 above): Economic version to get it all. =5: Compute PL, PR and DIF (i.e. 0, 1 and 3 above)

WANTQ (input)

WANTZ (input)

SELECT (input)

SELECT specifies the eigenvalues in the selected cluster. To select an eigenvalue $w(j)$, $\text{SELECT}(j)$ must be set to

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the upper triangular matrix A, in generalized Schur canonical form. On exit, A is overwritten by the reordered matrix A.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

B (input/output)

On entry, the upper triangular matrix B, in generalized Schur canonical form. On exit, B is overwritten by the reordered matrix B.

LDB (input)

The leading dimension of the array B. $\text{LDB} \geq \max(1, N)$.

ALPHA (output)

The diagonal elements of A and B, respectively, when the pair (A,B) has been reduced to generalized Schur form. $\text{ALPHA}(i)/\text{BETA}(i)$ $i=1, \dots, N$ are

the generalized eigenvalues.

BETA (output)

See the description of ALPHA.

Q (input/output)

On entry, if WANTQ = .TRUE., Q is an N-by-N matrix. On exit, Q has been postmultiplied by the left unitary transformation matrix which reorders (A, B); The leading M columns of Q form orthonormal bases for the specified pair of left eigenspaces (deflating subspaces). If WANTQ = .FALSE., Q is not referenced.

LDQ (input)

The leading dimension of the array Q. LDQ >= 1.
If WANTQ = .TRUE., LDQ >= N.

Z (input/output)

On entry, if WANTZ = .TRUE., Z is an N-by-N matrix. On exit, Z has been postmultiplied by the left unitary transformation matrix which reorders (A, B); The leading M columns of Z form orthonormal bases for the specified pair of left eigenspaces (deflating subspaces). If WANTZ = .FALSE., Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1.
If WANTZ = .TRUE., LDZ >= N.

M (output)

The dimension of the specified pair of left and right eigenspaces, (deflating subspaces) $0 \leq M \leq N$.

PL (output)

If IJOB = 1, 4, or 5, PL, PR are lower bounds on the reciprocal of the norm of "projections" onto left and right eigenspace with respect to the selected cluster.
 $0 < PL, PR \leq 1$. If M = 0 or M = N, PL = PR = 1.
If IJOB = 0, 2, or 3 PL, PR are not referenced.

PR (output)

See the description of PL.

DIF (output)

If IJOB >= 2, DIF(1:2) store the estimates of Dif_u and Dif_l.
If IJOB = 2 or 4, DIF(1:2) are F-norm-based upper bounds on Dif_u and Dif_l. If IJOB = 3 or 5, DIF(1:2) are 1-norm-based estimates of Dif_u and Dif_l, computed using reversed communication with CLACON. If M = 0 or N, DIF(1:2) = F-norm([A, B]). If IJOB = 0 or 1, DIF is not referenced.

WORK (workspace)

If IJOB = 0, WORK is not referenced. Otherwise, on exit, if INFO = 0, WORK(1) returns the optimal LWORK.

and the first n_1 columns of Q^*U and Z^*W span the corresponding deflating subspaces of (C, D) (Q and Z store Q^*U and Z^*W , resp.).

Note that if the selected eigenvalue is sufficiently ill-conditioned, then its value may differ significantly from its value before reordering.

The reciprocal condition numbers of the left and right eigenspaces spanned by the first n_1 columns of U and W (or Q^*U and Z^*W) may be returned in $DIF(1:2)$, corresponding to $Difu$ and $Difl$, resp.

The $Difu$ and $Difl$ are defined as:
 $ifu[(A_{11}, B_{11}), (A_{22}, B_{22})] = \sigma\text{-min}(Zu)$
 and

where $\sigma\text{-min}(Zu)$ is the smallest singular value of the $(2*n_1*n_2)\text{-by-}(2*n_1*n_2)$ matrix
 $u = [\text{kron}(In_2, A_{11}) \quad \text{-kron}(A_{22}', In_1)]$
 $[\text{kron}(In_2, B_{11}) \quad \text{-kron}(B_{22}', In_1)]$.

Here, In_x is the identity matrix of size n_x and A_{22}' is the transpose of A_{22} . $\text{kron}(X, Y)$ is the Kronecker product between the matrices X and Y .

When $DIF(2)$ is small, small changes in (A, B) can cause large changes in the deflating subspace. An approximate (asymptotic) bound on the maximum angular error in the computed deflating subspaces is $PS * \text{norm}((A, B)) / DIF(2)$,

where EPS is the machine precision.

The reciprocal norm of the projectors on the left and right eigenspaces associated with (A_{11}, B_{11}) may be returned in PL and PR . They are computed as follows. First we compute L and R so that $P^*(A, B)*Q$ is block diagonal, where

$$= \begin{pmatrix} I & -L \\ 0 & I \end{pmatrix} \begin{matrix} n_1 \\ n_2 \end{matrix} \quad \text{and} \quad Q = \begin{pmatrix} I & R \\ 0 & I \end{pmatrix} \begin{matrix} n_1 \\ n_2 \end{matrix}$$

and (L, R) is the solution to the generalized Sylvester equation $11*R - L*A_{22} = -A_{12}$

Then $PL = (F\text{-norm}(L)**2+1)**(-1/2)$ and $PR = (F\text{-norm}(R)**2+1)**(-1/2)$. An approximate (asymptotic) bound on the average absolute error of the selected eigenvalues is $EPS * \text{norm}((A, B)) / PL$.

There are also global error bounds which valid for perturbations up to a certain restriction: A lower bound (x) on the smallest $F\text{-norm}(E, F)$ for which an eigenvalue of (A_{11}, B_{11}) may move and coalesce with an eigenvalue of (A_{22}, B_{22}) under perturbation (E, F) , (i.e. $(A + E, B + F)$), is

$$x = \min(Difu, Difl) / ((1/(PL*PL) + 1/(PR*PR))**(1/2) + 2*\max(1/PL, 1/PR)).$$

An approximate bound on x can be computed from $DIF(1:2)$, PL and PR .

If $y = (F\text{-norm}(E, F) / x) \leq 1$, the angles between the per-

turbed (L', R') and unperturbed (L, R) left and right deflating subspaces associated with the selected cluster in the (1,1)-blocks can be bounded as

```
max-angle(L, L') <= arctan( y * PL / (1 - y * (1 - PL *
PL)**(1/2))
max-angle(R, R') <= arctan( y * PR / (1 - y * (1 - PR *
PR)**(1/2))
```

See LAPACK User's Guide section 4.11 or the following references for more information.

Note that if the default method for computing the Frobenius-norm-based estimate DIF is not wanted (see CLATDF), then the parameter IDIFJB (see below) should be changed from 3 to 4 (routine CLATDF (IJOB = 2 will be used)). See CTGSYL for more details.

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing Science,
Umea University, S-901 87 Umea, Sweden.

References

=====

- [1] B. Kagstrom; A Direct Method for Reordering Eigenvalues in the Generalized Real Schur Form of a Regular Matrix Pair (A, B), in M.S. Moonen et al (eds), Linear Algebra for Large Scale and Real-Time Applications, Kluwer Academic Publ. 1993, pp 195-218.
- [2] B. Kagstrom and P. Poromaa; Computing Eigenspaces with Specified Eigenvalues of a Regular Matrix Pair (A, B) and Condition Estimation: Theory, Algorithms and Software, Report UMINF - 94.04, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, 1994. Also as LAPACK Working Note 87. To appear in Numerical Algorithms, 1996.
- [3] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK working Note 75. To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

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NAME

ctgsja - compute the generalized singular value decomposition (GSVD) of two complex upper triangular (or trapezoidal) matrices A and B

SYNOPSIS

```
SUBROUTINE CTGSJA(JOBV, JOBV, JOBQ, M, P, N, K, L, A, LDA, B, LDB,
  TOLA, TOLB, ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, NCYCLE,
  INFO)
```

```
CHARACTER * 1 JOBV, JOBV, JOBQ
COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*), Q(LDQ,*),
WORK(*)
INTEGER M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE, INFO
REAL TOLA, TOLB
REAL ALPHA(*), BETA(*)
```

```
SUBROUTINE CTGSJA_64(JOBV, JOBV, JOBQ, M, P, N, K, L, A, LDA, B, LDB,
  TOLA, TOLB, ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, NCYCLE,
  INFO)
```

```
CHARACTER * 1 JOBV, JOBV, JOBQ
COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*), Q(LDQ,*),
WORK(*)
INTEGER*8 M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE,
INFO
REAL TOLA, TOLB
REAL ALPHA(*), BETA(*)
```

F95 INTERFACE

```
SUBROUTINE TGSJA(JOBV, JOBV, JOBQ, [M], [P], [N], K, L, A, [LDA], B,
  [LDB], TOLA, TOLB, ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ],
  [WORK], NCYCLE, [INFO])
```

```
CHARACTER(LEN=1) :: JOBV, JOBV, JOBQ
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B, U, V, Q
INTEGER :: M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE,
INFO
REAL :: TOLA, TOLB
```

```
REAL, DIMENSION(:) :: ALPHA, BETA
```

```
SUBROUTINE TGSJA_64(JOBV, JOBV, JOBQ, [M], [P], [N], K, L, A, [LDA],  
    B, [LDB], TOLA, TOLB, ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ],  
    [WORK], NCYCLE, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
```

```
COMPLEX, DIMENSION(:) :: WORK
```

```
COMPLEX, DIMENSION(:,:) :: A, B, U, V, Q
```

```
INTEGER(8) :: M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCY-  
CLE, INFO
```

```
REAL :: TOLA, TOLB
```

```
REAL, DIMENSION(:) :: ALPHA, BETA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctgsja(char jobv, char jobv, char jobq, int m, int p,  
    int n, int k, int l, complex *a, int lda, complex  
    *b, int ldb, float tola, float tolb, float *alpha,  
    float *beta, complex *u, int ldu, complex *v, int  
    ldv, complex *q, int ldq, int *ncycle, int *info);
```

```
void ctgsja_64(char jobv, char jobv, char jobq, long m, long  
    p, long n, long k, long l, complex *a, long lda,  
    complex *b, long ldb, float tola, float tolb,  
    float *alpha, float *beta, complex *u, long ldu,  
    complex *v, long ldv, complex *q, long ldq, long  
    *ncycle, long *info);
```

PURPOSE

ctgsja computes the generalized singular value decomposition (GSVD) of two complex upper triangular (or trapezoidal) matrices A and B.

On entry, it is assumed that matrices A and B have the following forms, which may be obtained by the preprocessing subroutine CCGSVP from a general M-by-N matrix A and P-by-N matrix B:

$$A = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} \\ \begin{matrix} K \\ L \\ M-K-L \end{matrix} & \begin{pmatrix} 0 & A12 & A13 \\ 0 & 0 & A23 \\ 0 & 0 & 0 \end{pmatrix} \end{array} \text{ if } M-K-L \geq 0;$$
$$A = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} \\ \begin{matrix} K \\ M-K \end{matrix} & \begin{pmatrix} 0 & A12 & A13 \\ 0 & 0 & A23 \end{pmatrix} \end{array} \text{ if } M-K-L < 0;$$
$$B = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} \\ \begin{matrix} L \\ P-L \end{matrix} & \begin{pmatrix} 0 & 0 & B13 \\ 0 & 0 & 0 \end{pmatrix} \end{array}$$

where the K-by-K matrix A12 and L-by-L matrix B13 are non-singular upper triangular; A23 is L-by-L upper triangular if M-K-L ≥ 0, otherwise A23 is (M-K)-by-L upper trapezoidal.

On exit,

$$U' * A * Q = D1 * (\begin{matrix} & & 0 & R \end{matrix}), \quad V' * B * Q = D2 * (\begin{matrix} & & 0 & R \end{matrix}),$$

where U, V and Q are unitary matrices, Z' denotes the conjugate transpose of Z, R is a nonsingular upper triangular matrix, and D1 and D2 are ``diagonal'' matrices, which are of the following structures:

If $M-K-L \geq 0$,

$$D1 = \begin{matrix} & & & K & L \\ & & & K & (I & 0) \\ & & & L & (0 & C) \\ & & & M-K-L & (0 & 0) \end{matrix}$$

$$D2 = \begin{matrix} & & & K & L \\ & & & L & (0 & S) \\ & & & P-L & (0 & 0) \end{matrix}$$

$$(\begin{matrix} 0 & R \end{matrix}) = \begin{matrix} & & N-K-L & K & L \\ & & K & (0 & R11 & R12) & K \\ & & L & (0 & 0 & R22) & L \end{matrix}$$

where

$$C = \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(K+L)), \\ S = \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(K+L)), \\ C^{**2} + S^{**2} = I.$$

R is stored in A(1:K+L, N-K-L+1:N) on exit.

If $M-K-L < 0$,

$$D1 = \begin{matrix} & & & K & M-K & K+L-M \\ & & & K & (I & 0 & 0) \\ & & & M-K & (0 & C & 0) \end{matrix}$$

$$D2 = \begin{matrix} & & & K & M-K & K+L-M \\ & & & M-K & (0 & S & 0) \\ & & & K+L-M & (0 & 0 & I) \\ & & & P-L & (0 & 0 & 0) \end{matrix}$$

$$\begin{matrix} & & & N-K-L & K & M-K & K+L-M \\ & & & M-K & (0 & 0 & R22 & R23) \\ & & & K+L-M & (0 & 0 & 0 & R33) \end{matrix}$$

where

$$C = \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(M)), \\ S = \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(M)), \\ C^{**2} + S^{**2} = I.$$

R = (R11 R12 R13) is stored in A(1:M, N-K-L+1:N) and R33 is stored

(0 R22 R23)
in B(M-K+1:L, N+M-K-L+1:N) on exit.

The computation of the unitary transformation matrices U, V or Q is optional. These matrices may either be formed explicitly, or they may be postmultiplied into input matrices U1, V1, or Q1.

CTGSJA essentially uses a variant of Kogbetliantz algorithm to reduce $\min(L, M-K)$ -by- L triangular (or trapezoidal) matrix A_{23} and L -by- L matrix B_{13} to the form:

$$U1' * A_{13} * Q1 = C1 * R1; V1' * B_{13} * Q1 = S1 * R1,$$

where $U1$, $V1$ and $Q1$ are unitary matrix, and Z' is the conjugate transpose of Z . $C1$ and $S1$ are diagonal matrices satisfying

$$C1^{**2} + S1^{**2} = I,$$

and $R1$ is an L -by- L nonsingular upper triangular matrix.

ARGUMENTS

JOBU (input)

= 'U': U must contain a unitary matrix $U1$ on entry, and the product $U1 * U$ is returned; = 'I': U is initialized to the unit matrix, and the unitary matrix U is returned; = 'N': U is not computed.

JOBV (input)

= 'V': V must contain a unitary matrix $V1$ on entry, and the product $V1 * V$ is returned; = 'I': V is initialized to the unit matrix, and the unitary matrix V is returned; = 'N': V is not computed.

JOBQ (input)

= 'Q': Q must contain a unitary matrix $Q1$ on entry, and the product $Q1 * Q$ is returned; = 'I': Q is initialized to the unit matrix, and the unitary matrix Q is returned; = 'N': Q is not computed.

M (input) The number of rows of the matrix A . $M \geq 0$.

P (input) The number of rows of the matrix B . $P \geq 0$.

N (input) The number of columns of the matrices A and B . $N \geq 0$.

K (input) K and L specify the subblocks in the input matrices A and B :
 $A_{23} = A(K+1:\min(K+L, M), N-L+1:N)$ and $B_{13} = B(1:L, N-L+1:N)$ of A and B , whose GSVD is going to be computed by CTGSJA. See the Further Details section below.

L (input) See the description of K .

A (input/output)

On entry, the M -by- N matrix A . On exit, $A(N-K+1:N, 1:\min(K+L, M))$ contains the triangular matrix R or part of R . See Purpose for details.

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, M)$.

B (input/output)

On entry, the P -by- N matrix B . On exit, if necessary, $B(M-K+1:L, N+M-K-L+1:N)$ contains a part of R . See Purpose for details.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,P).

TOLA (input)
TOLA and TOLB are the convergence criteria for the Jacobi-Kogbetliantz iteration procedure. Generally, they are the same as used in the preprocessing step, say TOLA = MAX(M,N)*norm(A)*MACHEPS, TOLB = MAX(P,N)*norm(B)*MACHEPS.

TOLB (input)
See the description of TOLA.

ALPHA (output)
On exit, ALPHA and BETA contain the generalized singular value pairs of A and B; ALPHA(1:K) = 1, BETA(1:K) = 0, and if M-K-L \geq 0, ALPHA(K+1:K+L) = diag(C), BETA(K+1:K+L) = diag(S), or if M-K-L < 0, ALPHA(K+1:M) = C, ALPHA(M+1:K+L) = 0, BETA(K+1:M) = S, BETA(M+1:K+L) = 1. Furthermore, if K+L < N, ALPHA(K+L+1:N) = 0, BETA(K+L+1:N) = 0.

BETA (output)
See the description of ALPHA.

U (input) On entry, if JOBU = 'U', U must contain a matrix U1 (usually the unitary matrix returned by CGGSVP). On exit, if JOBU = 'I', U contains the unitary matrix U; if JOBU = 'U', U contains the product U1*U. If JOBU = 'N', U is not referenced.

LDU (input)
The leading dimension of the array U. LDU \geq max(1,M) if JOBU = 'U'; LDU \geq 1 otherwise.

V (input) On entry, if JOBV = 'V', V must contain a matrix V1 (usually the unitary matrix returned by CGGSVP). On exit, if JOBV = 'I', V contains the unitary matrix V; if JOBV = 'V', V contains the product V1*V. If JOBV = 'N', V is not referenced.

LDV (input)
The leading dimension of the array V. LDV \geq max(1,P) if JOBV = 'V'; LDV \geq 1 otherwise.

Q (input) On entry, if JOBQ = 'Q', Q must contain a matrix Q1 (usually the unitary matrix returned by CGGSVP). On exit, if JOBQ = 'I', Q contains the unitary matrix Q; if JOBQ = 'Q', Q contains the product Q1*Q. If JOBQ = 'N', Q is not referenced.

LDQ (input)
The leading dimension of the array Q. LDQ \geq max(1,N) if JOBQ = 'Q'; LDQ \geq 1 otherwise.

WORK (workspace)
dimension(2*N)

NCYCLE (output)

The number of cycles required for convergence.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

= 1: the procedure does not converge after MAXIT cycles.

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NAME

ctgsna - estimate reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B)

SYNOPSIS

```
SUBROUTINE CTGSNA(JOB, HOWMNT, SELECT, N, A, LDA, B, LDB, VL, LDVL,  
  VR, LDVR, S, DIF, MM, M, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOB, HOWMNT  
COMPLEX A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO  
INTEGER IWORK(*)  
LOGICAL SELECT(*)  
REAL S(*), DIF(*)
```

```
SUBROUTINE CTGSNA_64(JOB, HOWMNT, SELECT, N, A, LDA, B, LDB, VL,  
  LDVL, VR, LDVR, S, DIF, MM, M, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOB, HOWMNT  
COMPLEX A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO  
INTEGER*8 IWORK(*)  
LOGICAL*8 SELECT(*)  
REAL S(*), DIF(*)
```

F95 INTERFACE

```
SUBROUTINE TGSNA(JOB, HOWMNT, SELECT, [N], A, [LDA], B, [LDB], VL,  
  [LDVL], VR, [LDVR], S, DIF, MM, M, [WORK], [LWORK], [IWORK],  
  [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNT  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A, B, VL, VR  
INTEGER :: N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
LOGICAL, DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: S, DIF
```

```

SUBROUTINE TGSNA_64(JOB, HOWMNT, SELECT, [N], A, [LDA], B, [LDB], VL,
    [LDVL], VR, [LDVR], S, DIF, MM, M, [WORK], [LWORK], [IWORK],
    [INFO])

```

```

CHARACTER(LEN=1) :: JOB, HOWMNT
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B, VL, VR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8), DIMENSION(:) :: SELECT
REAL, DIMENSION(:) :: S, DIF

```

C INTERFACE

```
#include <sunperf.h>
```

```

void ctgsna(char job, char howmnt, int *select, int n, com-
    plex *a, int lda, complex *b, int ldb, complex
    *vl, int ldvl, complex *vr, int ldvr, float *s,
    float *dif, int mm, int *m, int *info);

```

```

void ctgsna_64(char job, char howmnt, long *select, long n,
    complex *a, long lda, complex *b, long ldb, com-
    plex *vl, long ldvl, complex *vr, long ldvr, float
    *s, float *dif, long mm, long *m, long *info);

```

PURPOSE

ctgsna estimates reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B).

(A, B) must be in generalized Schur canonical form, that is, A and B are both upper triangular.

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for eigenvalues (S) or eigenvectors (DIF):
 = 'E': for eigenvalues only (S);
 = 'V': for eigenvectors only (DIF);
 = 'B': for both eigenvalues and eigenvectors (S and DIF).

HOWMNT (input)

= 'A': compute condition numbers for all eigenpairs;
 = 'S': compute condition numbers for selected eigenpairs specified by the array SELECT.

SELECT (input)

If HOWMNT = 'S', SELECT specifies the eigenpairs for which condition numbers are required. To select condition numbers for the corresponding j-th eigenvalue and/or eigenvector, SELECT(j) must be set to .TRUE.. If HOWMNT = 'A', SELECT is not referenced.

N (input) The order of the square matrix pair (A, B). N >= 0.

A (input) The upper triangular matrix A in the pair (A,B).

LDA (input)
The leading dimension of the array A. LDA >= max(1,N).

B (input) The upper triangular matrix B in the pair (A, B).

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

VL (input)
If JOB = 'E' or 'B', VL must contain left eigenvectors of (A, B), corresponding to the eigenpairs specified by HOWMNT and SELECT. The eigenvectors must be stored in consecutive columns of VL, as returned by CTGEVC. If JOB = 'V', VL is not referenced.

LDVL (input)
The leading dimension of the array VL. LDVL >= 1; and If JOB = 'E' or 'B', LDVL >= N.

VR (input)
If JOB = 'E' or 'B', VR must contain right eigenvectors of (A, B), corresponding to the eigenpairs specified by HOWMNT and SELECT. The eigenvectors must be stored in consecutive columns of VR, as returned by CTGEVC. If JOB = 'V', VR is not referenced.

LDVR (input)
The leading dimension of the array VR. LDVR >= 1; If JOB = 'E' or 'B', LDVR >= N.

S (output)
If JOB = 'E' or 'B', the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. If JOB = 'V', S is not referenced.

DIF (output)
If JOB = 'V' or 'B', the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. If the eigenvalues cannot be reordered to compute DIF(j), DIF(j) is set to 0; this can only occur when the true value would be very small anyway. For each eigenvalue/vector specified by SELECT, DIF stores a Frobenius norm-based estimate of Difl. If JOB = 'E', DIF is not referenced.

MM (input)
The number of elements in the arrays S and DIF. MM >= M.

M (output)
The number of elements of the arrays S and DIF

[kron(b, In-1) -kron(1, B22)].

Here In-1 is the identity matrix of size n-1 and X' is the conjugate transpose of X. kron(X, Y) is the Kronecker product between the matrices X and Y.

We approximate the smallest singular value of Z1 with an upper bound. This is done by CLATDF.

An approximate error bound for a computed eigenvector VL(i) or VR(i) is given by

$$\text{EPS} * \text{norm}(A, B) / \text{DIF}(i).$$

See ref. [2-3] for more details and further references.

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing Science,
Umea University, S-901 87 Umea, Sweden.

References

=====

[1] B. Kagstrom; A Direct Method for Reordering Eigenvalues in the Generalized Real Schur Form of a Regular Matrix Pair (A, B), in M.S. Moonen et al (eds), Linear Algebra for Large Scale and Real-Time Applications, Kluwer Academic Publ. 1993, pp 195-218.

[2] B. Kagstrom and P. Poromaa; Computing Eigenspaces with Specified Eigenvalues of a Regular Matrix Pair (A, B) and Condition Estimation: Theory, Algorithms and Software, Report UMINF - 94.04, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, 1994. Also as LAPACK Working Note 87.
To appear in Numerical Algorithms, 1996.

[3] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK Working Note 75.
To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

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NAME

ctgsyl - solve the generalized Sylvester equation

SYNOPSIS

```
SUBROUTINE CTGSYL(TRANS, IJOB, M, N, A, LDA, B, LDB, C, LDC, D, LDD,
                  E, LDE, F, LDF, SCALE, DIF, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 TRANS
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*), D(LDD,*), E(LDE,*),
F(LDF,*), WORK(*)
INTEGER IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,
INFO
INTEGER IWORK(*)
REAL SCALE, DIF
```

```
SUBROUTINE CTGSYL_64(TRANS, IJOB, M, N, A, LDA, B, LDB, C, LDC, D,
                    LDD, E, LDE, F, LDF, SCALE, DIF, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 TRANS
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*), D(LDD,*), E(LDE,*),
F(LDF,*), WORK(*)
INTEGER*8 IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,
INFO
INTEGER*8 IWORK(*)
REAL SCALE, DIF
```

F95 INTERFACE

```
SUBROUTINE TGSYL(TRANS, IJOB, [M], [N], A, [LDA], B, [LDB], C, [LDC],
                D, [LDD], E, [LDE], F, [LDF], SCALE, DIF, [WORK], [LWORK], [IWORK],
                [INFO])
```

```
CHARACTER(LEN=1) :: TRANS
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: A, B, C, D, E, F
INTEGER :: IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,
INFO
INTEGER, DIMENSION(:) :: IWORK
REAL :: SCALE, DIF
```

```

SUBROUTINE TGSYL_64(TRANS, IJOB, [M], [N], A, [LDA], B, [LDB], C,
  [LDC], D, [LDD], E, [LDE], F, [LDF], SCALE, DIF, [WORK], [LWORK],
  [IWORK], [INFO])

```

```

CHARACTER(LEN=1) :: TRANS
COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:,:) :: A, B, C, D, E, F
INTEGER(8) :: IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF,
LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL :: SCALE, DIF

```

C INTERFACE

```
#include <sunperf.h>
```

```

void ctgsyl(char trans, int ijob, int m, int n, complex *a,
  int lda, complex *b, int ldb, complex *c, int ldc,
  complex *d, int ldd, complex *e, int lde, complex
  *f, int ldf, float *scale, float *dif, int *info);

```

```

void ctgsyl_64(char trans, long ijob, long m, long n, com-
  plex *a, long lda, complex *b, long ldb, complex
  *c, long ldc, complex *d, long ldd, complex *e,
  long lde, complex *f, long ldf, float *scale,
  float *dif, long *info);

```

PURPOSE

ctgsyl solves the generalized Sylvester equation:

$$\begin{aligned}
 A * R - L * B &= \text{scale} * C & (1) \\
 D * R - L * E &= \text{scale} * F
 \end{aligned}$$

where R and L are unknown m-by-n matrices, (A, D), (B, E) and (C, F) are given matrix pairs of size m-by-m, n-by-n and m-by-n, respectively, with complex entries. A, B, D and E are upper triangular (i.e., (A,D) and (B,E) in generalized Schur form).

The solution (R, L) overwrites (C, F). 0 <= SCALE <= 1 is an output scaling factor chosen to avoid overflow.

In matrix notation (1) is equivalent to solve $Zx = \text{scale} * b$, where Z is defined as

$$Z = \begin{bmatrix} \text{kron}(I_n, A) & -\text{kron}(B', I_m) \\ \text{kron}(I_n, D) & -\text{kron}(E', I_m) \end{bmatrix}, \quad (2)$$

Here I_x is the identity matrix of size x and X' is the conjugate transpose of X. $\text{Kron}(X, Y)$ is the Kronecker product between the matrices X and Y.

If TRANS = 'C', y in the conjugate transposed system $Z' * y = \text{scale} * b$ is solved for, which is equivalent to solve for R and L in

$$\begin{aligned}
 A' * R + D' * L &= \text{scale} * C & (3) \\
 R * B' + L * E' &= \text{scale} * -F
 \end{aligned}$$

This case (TRANS = 'C') is used to compute an one-norm-based estimate of $\text{Dif}[(A,D), (B,E)]$, the separation between the matrix pairs (A,D) and (B,E), using CLACON.

If IJOB \geq 1, CTGSYL computes a Frobenius norm-based estimate of $\text{Dif}[(A,D), (B,E)]$. That is, the reciprocal of a lower bound on the reciprocal of the smallest singular value of Z.

This is a level-3 BLAS algorithm.

ARGUMENTS

TRANS (input)

= 'N': solve the generalized sylvester equation (1).
= 'C': solve the "conjugate transposed" system (3).

IJOB (input)

Specifies what kind of functionality to be performed. =0: solve (1) only.
=1: The functionality of 0 and 3.
=2: The functionality of 0 and 4.
=3: Only an estimate of $\text{Dif}[(A,D), (B,E)]$ is computed. (look ahead strategy is used). =4: Only an estimate of $\text{Dif}[(A,D), (B,E)]$ is computed. (CGECON on sub-systems is used). Not referenced if TRANS = 'C'.

M (input) The order of the matrices A and D, and the row dimension of the matrices C, F, R and L.

N (input) The order of the matrices B and E, and the column dimension of the matrices C, F, R and L.

A (input) The upper triangular matrix A.

LDA (input)

The leading dimension of the array A. LDA \geq max(1, M).

B (input) The upper triangular matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1, N).

C (input/output)

On entry, C contains the right-hand-side of the first matrix equation in (1) or (3). On exit, if IJOB = 0, 1 or 2, C has been overwritten by the solution R. If IJOB = 3 or 4 and TRANS = 'N', C holds R, the solution achieved during the computation of the Dif-estimate.

LDC (input)

The leading dimension of the array C. LDC \geq max(1, M).

D (input) The upper triangular matrix D.

LDD (input)
 The leading dimension of the array D. LDD \geq max(1, M).

E (input) The upper triangular matrix E.

LDE (input)
 The leading dimension of the array E. LDE \geq max(1, N).

F (input/output)
 On entry, F contains the right-hand-side of the second matrix equation in (1) or (3). On exit, if IJOB = 0, 1 or 2, F has been overwritten by the solution L. If IJOB = 3 or 4 and TRANS = 'N', F holds L, the solution achieved during the computation of the Dif-estimate.

LDF (input)
 The leading dimension of the array F. LDF \geq max(1, M).

DIF (output)
 On exit SCALE is the reciprocal of a lower bound of the reciprocal of the Dif-function, i.e. SCALE is an upper bound of Dif[(A,D), (B,E)] = $\sigma_{\min}(Z)$, where Z as in (2). If IJOB = 0 or TRANS = 'C', SCALE is not referenced.

SCALE (output)
 On exit SCALE is the reciprocal of a lower bound of the reciprocal of the Dif-function, i.e. SCALE is an upper bound of Dif[(A,D), (B,E)] = $\sigma_{\min}(Z)$, where Z as in (2). If IJOB = 0 or TRANS = 'C', SCALE is not referenced.

WORK (workspace)
 If IJOB = 0, WORK is not referenced. Otherwise, on exit, if INFO=0 then WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq 1. If IJOB = 1 or 2 and TRANS = 'N', LWORK \geq 2*M*N.

 If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)
 If IJOB = 0, IWORK is not referenced.

INFO (output)
 =0: successful exit
 <0: If INFO = -i, the i-th argument had an illegal value.

>0: (A, D) and (B, E) have common or very close eigenvalues.

FURTHER DETAILS

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing Science,
Umea University, S-901 87 Umea, Sweden.

[1] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK Working Note 75. To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

[2] B. Kagstrom, A Perturbation Analysis of the Generalized Sylvester Equation $(AR - LB, DR - LE) = (C, F)$, SIAM J. Matrix Anal. Appl., 15(4):1045-1060, 1994.

[3] B. Kagstrom and L. Westin, Generalized Schur Methods with Condition Estimators for Solving the Generalized Sylvester Equation, IEEE Transactions on Automatic Control, Vol. 34, No. 7, July 1989, pp 745-751.

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NAME

ctpcn - estimate the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE CTPCON(NORM, UPLO, DIAG, N, A, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
REAL RCOND  
REAL WORK2(*)
```

```
SUBROUTINE CTPCON_64(NORM, UPLO, DIAG, N, A, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
REAL RCOND  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TPCON(NORM, UPLO, DIAG, [N], A, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE TPCON_64(NORM, UPLO, DIAG, [N], A, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX, DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
REAL :: RCOND
```

```
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctpcon(char norm, char uplo, char diag, int n, complex  
*a, float *rcond, int *info);
```

```
void ctpcon_64(char norm, char uplo, char diag, long n, com-  
plex *a, float *rcond, long *info);
```

PURPOSE

ctpcon estimates the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input) COMPLEX array, dimension $(N*(N+1)/2)$

The upper or lower triangular matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

COMPLEX array, dimension $(2*N)$

WORK2 (workspace)

REAL array, dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ctpmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$

SYNOPSIS

```
SUBROUTINE CTPMV(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(*), Y(*)  
INTEGER N, INCY
```

```
SUBROUTINE CTPMV_64(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(*), Y(*)  
INTEGER*8 N, INCY
```

F95 INTERFACE

```
SUBROUTINE TPMV(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: A, Y  
INTEGER :: N, INCY
```

```
SUBROUTINE TPMV_64(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: A, Y  
INTEGER(8) :: N, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctpmv(char uplo, char transa, char diag, int n, complex  
          *a, complex *y, int incy);
```

```
void ctpmv_64(char uplo, char transa, char diag, long n,  
             complex *a, complex *y, long incy);
```

PURPOSE

ctpmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$ where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := \text{conjg}(A')*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

(($n*(n+1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular matrix packed sequentially, column by column, so that $A(1)$ contains $a(1,1)$, $A(2)$ and $A(3)$ contain $a(1,2)$ and $a(2,2)$ respec-

tively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced, but are assumed to be unity. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

ctprfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix

SYNOPSIS

```
SUBROUTINE CTPRFS(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CTPRFS_64(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TPRFS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], X,  
    [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: A, WORK  
COMPLEX, DIMENSION(:, :) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE TPRFS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], X,  
    [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: A, WORK  
COMPLEX, DIMENSION(:, :) :: B, X  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void ctpfrs(char uplo, char transa, char diag, int n, int
  nrhs, complex *a, complex *b, int ldb, complex *x,
  int ldx, float *ferr, float *berr, int *info);
void ctpfrs_64(char uplo, char transa, char diag, long n,
  long nrhs, complex *a, complex *b, long ldb, com-
  plex *x, long ldx, float *ferr, float *berr, long
  *info);
```

PURPOSE

ctpfrs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix.

The solution matrix X must be computed by CTPTRS or some other means before entering this routine. CTPRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) COMPLEX array, dimension $(N*(N+1)/2)$

The upper or lower triangular matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

B (input) COMPLEX array, dimension (LDB,NRHS)
The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

X (input) COMPLEX array, dimension (LDX,NRHS)
The solution matrix X.

LDX (input)
The leading dimension of the array X. LDX >= max(1,N).

FERR (output) REAL array, dimension (NRHS)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) REAL array, dimension (NRHS)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
COMPLEX array, dimension(2*N)

WORK2 (workspace)
REAL array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ctpsv - solve one of the systems of equations $Ax = b$, or $A^T x = b$, or $\text{conjg}(A^T)x = b$

SYNOPSIS

```
SUBROUTINE CTPSV(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(*), Y(*)  
INTEGER N, INCY
```

```
SUBROUTINE CTPSV_64(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(*), Y(*)  
INTEGER*8 N, INCY
```

F95 INTERFACE

```
SUBROUTINE TPSV(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: A, Y  
INTEGER :: N, INCY
```

```
SUBROUTINE TPSV_64(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: A, Y  
INTEGER(8) :: N, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctpsv(char uplo, char transa, char diag, int n, complex  
          *a, complex *y, int incy);
```

```
void ctpsv_64(char uplo, char transa, char diag, long n,  
             complex *a, complex *y, long incy);
```

PURPOSE

ctpsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A)*x = b$ where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular matrix, supplied in packed form.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the equations to be solved as follows:

TRANSA = 'N' or 'n' $A*x = b$.

TRANSA = 'T' or 't' $A'*x = b$.

TRANSA = 'C' or 'c' $\text{conjg}(A)*x = b$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

(($n*(n+1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper

triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(1, 2) and a(2, 2) respectively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced, but are assumed to be unity. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

ctptri - compute the inverse of a complex upper or lower triangular matrix A stored in packed format

SYNOPSIS

```
SUBROUTINE CTPTRI(UPLO, DIAG, N, A, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
COMPLEX A(*)  
INTEGER N, INFO
```

```
SUBROUTINE CTPTRI_64(UPLO, DIAG, N, A, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
COMPLEX A(*)  
INTEGER*8 N, INFO
```

F95 INTERFACE

```
SUBROUTINE TPTRI(UPLO, DIAG, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX, DIMENSION(:) :: A  
INTEGER :: N, INFO
```

```
SUBROUTINE TPTRI_64(UPLO, DIAG, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX, DIMENSION(:) :: A  
INTEGER(8) :: N, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctptri(char uplo, char diag, int n, complex *a, int  
           *info);
```

```
void ctptri_64(char uplo, char diag, long n, complex *a,  
              long *info);
```

PURPOSE

ctptri computes the inverse of a complex upper or lower triangular matrix A stored in packed format.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangular matrix A, stored columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*((2*n-j)/2)) = A(i,j)$ for $j \leq i \leq n$. See below for further details. On exit, the (triangular) inverse of the original matrix, in the same packed storage format.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, $A(i,i)$ is exactly zero. The triangular matrix is singular and its inverse can not be computed.

FURTHER DETAILS

A triangular matrix A can be transferred to packed storage using one of the following program segments:

UPLO = 'U':

```
      JC = 1
      DO 2 J = 1, N
        DO 1 I = 1, J
          A(JC+I-1) = A(I,J)
        1 CONTINUE
        JC = JC + J
      2 CONTINUE
```

UPLO = 'L':

```
      JC = 1
      DO 2 J = 1, N
        DO 1 I = J, N
          A(JC+I-J) =
        1 CONTINUE
        JC = JC + N - J +
      2 CONTINUE
```

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NAME

ctptrs - solve a triangular system of the form $A * X = B$,
 $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE CTPTRS(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO
```

```
SUBROUTINE CTPTRS_64(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE TPTRS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO
```

```
SUBROUTINE TPTRS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: A  
COMPLEX, DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctptrs(char uplo, char transa, char diag, int n, int  
           nrhs, complex *a, complex *b, int ldb, int *info);
```

```
void ctptrs_64(char uplo, char transa, char diag, long n,  
              long nrhs, complex *a, complex *b, long ldb, long
```

```
*info);
```

PURPOSE

ctptrs solves a triangular system of the form

$A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$
where A is a triangular matrix of order N stored in packed
format, and B is an N-by-NRHS matrix. A check is made to
verify that A is nonsingular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number
of columns of the matrix B. $NRHS \geq 0$.

A (input) COMPLEX array, dimension $(N*(N+1)/2)$

The upper or lower triangular matrix A, packed
columnwise in a linear array. The j-th column of
A is stored in the array A as follows: if UPLO =
'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if
UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for
 $j \leq i \leq n$.

B (input/output) COMPLEX array, dimension (LDB,NRHS)

On entry, the right hand side matrix B. On exit,
if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq$
 $\max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value
> 0: if INFO = i, the i-th diagonal element of A
is zero, indicating that the matrix is singular
and the solutions X have not been computed.

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NAME

ctrans - transpose and scale source matrix

SYNOPSIS

```
SUBROUTINE CTRANS(PLACE, SCALE, SOURCE, M, N, DEST)
```

```
CHARACTER * 1 PLACE  
COMPLEX SCALE  
COMPLEX SOURCE(*), DEST(*)  
INTEGER M, N
```

```
SUBROUTINE CTRANS_64(PLACE, SCALE, SOURCE, M, N, DEST)
```

```
CHARACTER * 1 PLACE  
COMPLEX SCALE  
COMPLEX SOURCE(*), DEST(*)  
INTEGER*8 M, N
```

F95 INTERFACE

```
SUBROUTINE TRANS([PLACE], SCALE, SOURCE, M, N, [DEST])
```

```
CHARACTER(LEN=1) :: PLACE  
COMPLEX :: SCALE  
COMPLEX, DIMENSION(:) :: SOURCE, DEST  
INTEGER :: M, N
```

```
SUBROUTINE TRANS_64([PLACE], SCALE, SOURCE, M, N, [DEST])
```

```
CHARACTER(LEN=1) :: PLACE  
COMPLEX :: SCALE  
COMPLEX, DIMENSION(:) :: SOURCE, DEST  
INTEGER(8) :: M, N
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctrans(char place, complex *scale, complex *source, int  
            m, int n, complex *dest);
```

```
void ctrans_64(char place, complex *scale, complex *source,
```

```
long m, long n, complex *dest);
```

PURPOSE

ctrans scales and transposes the source matrix. The $N_2 \times N_1$ result is written into SOURCE when PLACE = 'I' or 'i', and DEST when PLACE = 'O' or 'o'.

```
PLACE = 'I' or 'i': SOURCE = SCALE * SOURCE'
```

```
PLACE = 'O' or 'o': DEST = SCALE * SOURCE'
```

ARGUMENTS

PLACE (input)

Type of transpose. 'I' or 'i' for in-place, 'O' or 'o' for out-of-place. 'I' is default.

SCALE (input)

Scale factor on the SOURCE matrix.

SOURCE (input/output)

on input. Array of (N, M) on output if in-place transpose.

M (input)

Number of rows in the SOURCE matrix on input.

N (input)

Number of columns in the SOURCE matrix on input.

DEST (output)

Scaled and transposed SOURCE matrix if out-of-place transpose. Not referenced if in-place transpose.

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NAME

ctrcon - estimate the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE CTRCON(NORM, UPLO, DIAG, N, A, LDA, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
REAL RCOND  
REAL WORK2(*)
```

```
SUBROUTINE CTRCON_64(NORM, UPLO, DIAG, N, A, LDA, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
REAL RCOND  
REAL WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TRCON(NORM, UPLO, DIAG, [N], A, [LDA], RCOND, [WORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK2
```

```
SUBROUTINE TRCON_64(NORM, UPLO, DIAG, [N], A, [LDA], RCOND, [WORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX, DIMENSION(:) :: WORK
```

```
COMPLEX, DIMENSION(:,:) :: A
INTEGER(8) :: N, LDA, INFO
REAL :: RCOND
REAL, DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void ctrcon(char norm, char uplo, char diag, int n, complex
            *a, int lda, float *rcond, int *info);

void ctrcon_64(char norm, char uplo, char diag, long n, com-
               plex *a, long lda, float *rcond, long *info);
```

PURPOSE

ctrcon estimates the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))) .$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ctrevc - compute some or all of the right and/or left eigenvectors of a complex upper triangular matrix T

SYNOPSIS

```
SUBROUTINE CTREVC(SIDE, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,  
                 LDVR, MM, M, WORK, RWORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
COMPLEX T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL SELECT(*)  
REAL RWORK(*)
```

```
SUBROUTINE CTREVC_64(SIDE, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,  
                    LDVR, MM, M, WORK, RWORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
COMPLEX T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(*)  
INTEGER*8 N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL*8 SELECT(*)  
REAL RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE TREVC(SIDE, HOWMNY, SELECT, [N], T, [LDT], VL, [LDVL], VR,  
                [LDVR], MM, M, [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:, :) :: T, VL, VR  
INTEGER :: N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL, DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: RWORK
```

```
SUBROUTINE TREVC_64(SIDE, HOWMNY, SELECT, [N], T, [LDT], VL, [LDVL],  
                   VR, [LDVR], MM, M, [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY
```

```

COMPLEX, DIMENSION(:) :: WORK
COMPLEX, DIMENSION(:, :) :: T, VL, VR
INTEGER(8) :: N, LDT, LDVL, LDVR, MM, M, INFO
LOGICAL(8), DIMENSION(:) :: SELECT
REAL, DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>
void ctrevc(char side, char howmny, int *select, int n, complex *t, int ldt, complex *vl, int ldvl, complex *vr, int ldvr, int mm, int *m, int *info);

void ctrevc_64(char side, char howmny, long *select, long n, complex *t, long ldt, complex *vl, long ldvl, complex *vr, long ldvr, long mm, long *m, long *info);

```

PURPOSE

ctrevc computes some or all of the right and/or left eigenvectors of a complex upper triangular matrix T.

The right eigenvector x and the left eigenvector y of T corresponding to an eigenvalue w are defined by:

$$T*x = w*x, \quad y'*T = w*y'$$

where y' denotes the conjugate transpose of the vector y.

If all eigenvectors are requested, the routine may either return the matrices X and/or Y of right or left eigenvectors of T, or the products Q*X and/or Q*Y, where Q is an input unitary matrix. If T was obtained from the Schur factorization of an original matrix $A = Q*T*Q'$, then Q*X and Q*Y are the matrices of right or left eigenvectors of A.

ARGUMENTS

SIDE (input)

```

= 'R': compute right eigenvectors only;
= 'L': compute left eigenvectors only;
= 'B': compute both right and left eigenvectors.

```

HOWMNY (input)

```

= 'A': compute all right and/or left eigenvectors;
= 'B': compute all right and/or left eigenvectors, and backtransform them using the input matrices supplied in VR and/or VL;
= 'S': compute selected right and/or left eigenvectors, specified by the logical array SELECT.

```

SELECT (input/output)

```

If HOWMNY = 'S', SELECT specifies the eigenvectors to be computed. If HOWMNY = 'A' or 'B', SELECT is

```

not referenced. To select the eigenvector corresponding to the j -th eigenvalue, `SELECT(j)` must be set to `.TRUE..`

`N` (input) The order of the matrix `T`. $N \geq 0$.

`T` (input/output)
The upper triangular matrix `T`. `T` is modified, but restored on exit.

`LDT` (input)
The leading dimension of the array `T`. $LDT \geq \max(1,N)$.

`VL` (input/output)
On entry, if `SIDE = 'L'` or `'B'` and `HOWMNY = 'B'`, `VL` must contain an N -by- N matrix `Q` (usually the unitary matrix `Q` of Schur vectors returned by `CHSEQR`). On exit, if `SIDE = 'L'` or `'B'`, `VL` contains: if `HOWMNY = 'A'`, the matrix `Y` of left eigenvectors of `T`; `VL` is lower triangular. The i -th column `VL(i)` of `VL` is the eigenvector corresponding to `T(i,i)`. if `HOWMNY = 'B'`, the matrix `Q*Y`; if `HOWMNY = 'S'`, the left eigenvectors of `T` specified by `SELECT`, stored consecutively in the columns of `VL`, in the same order as their eigenvalues. If `SIDE = 'R'`, `VL` is not referenced.

`LDVL` (input)
The leading dimension of the array `VL`. $LDVL \geq \max(1,N)$ if `SIDE = 'L'` or `'B'`; $LDVL \geq 1$ otherwise.

`VR` (input/output)
On entry, if `SIDE = 'R'` or `'B'` and `HOWMNY = 'B'`, `VR` must contain an N -by- N matrix `Q` (usually the unitary matrix `Q` of Schur vectors returned by `CHSEQR`). On exit, if `SIDE = 'R'` or `'B'`, `VR` contains: if `HOWMNY = 'A'`, the matrix `X` of right eigenvectors of `T`; `VR` is upper triangular. The i -th column `VR(i)` of `VR` is the eigenvector corresponding to `T(i,i)`. if `HOWMNY = 'B'`, the matrix `Q*X`; if `HOWMNY = 'S'`, the right eigenvectors of `T` specified by `SELECT`, stored consecutively in the columns of `VR`, in the same order as their eigenvalues. If `SIDE = 'L'`, `VR` is not referenced.

`LDVR` (input)
The leading dimension of the array `VR`. $LDVR \geq \max(1,N)$ if `SIDE = 'R'` or `'B'`; $LDVR \geq 1$ otherwise.

`MM` (input)
The number of columns in the arrays `VL` and/or `VR`. $MM \geq M$.

`M` (output)
The number of columns in the arrays `VL` and/or `VR` actually used to store the eigenvectors. If `HOWMNY = 'A'` or `'B'`, `M` is set to N . Each selected eigenvector occupies one column.

WORK (workspace)
 dimension(2*N)

RWORK (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The algorithm used in this program is basically backward (forward) substitution, with scaling to make the code robust against possible overflow.

Each eigenvector is normalized so that the element of largest magnitude has magnitude 1; here the magnitude of a complex number (x,y) is taken to be $|x| + |y|$.

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NAME

ctrexc - reorder the Schur factorization of a complex matrix $A = Q^*T^*Q^{**}H$, so that the diagonal element of T with row index IFST is moved to row ILST

SYNOPSIS

```
SUBROUTINE CTREXC(COMPQ, N, T, LDT, Q, LDQ, IFST, ILST, INFO)

CHARACTER * 1 COMPQ
COMPLEX T(LDT,*), Q(LDQ,*)
INTEGER N, LDT, LDQ, IFST, ILST, INFO

SUBROUTINE CTREXC_64(COMPQ, N, T, LDT, Q, LDQ, IFST, ILST, INFO)

CHARACTER * 1 COMPQ
COMPLEX T(LDT,*), Q(LDQ,*)
INTEGER*8 N, LDT, LDQ, IFST, ILST, INFO
```

F95 INTERFACE

```
SUBROUTINE TREXC(COMPQ, [N], T, [LDT], Q, [LDQ], IFST, ILST, [INFO])

CHARACTER(LEN=1) :: COMPQ
COMPLEX, DIMENSION(:,:) :: T, Q
INTEGER :: N, LDT, LDQ, IFST, ILST, INFO

SUBROUTINE TREXC_64(COMPQ, [N], T, [LDT], Q, [LDQ], IFST, ILST, [INFO])

CHARACTER(LEN=1) :: COMPQ
COMPLEX, DIMENSION(:,:) :: T, Q
INTEGER(8) :: N, LDT, LDQ, IFST, ILST, INFO
```

C INTERFACE

```
#include <sunperf.h>

void ctrexc(char compq, int n, complex *t, int ldt, complex
            *q, int ldq, int ifst, int ilst, int *info);

void ctrexc_64(char compq, long n, complex *t, long ldt,
               complex *q, long ldq, long ifst, long ilst, long
               *info);
```

PURPOSE

ctrexc reorders the Schur factorization of a complex matrix $A = Q^*TQ^*H$, so that the diagonal element of T with row index IFST is moved to row ILST.

The Schur form T is reordered by a unitary similarity transformation $Z^*H^*T^*Z$, and optionally the matrix Q of Schur vectors is updated by postmultiplying it with Z .

ARGUMENTS

COMPQ (input)

= 'V': update the matrix Q of Schur vectors;
= 'N': do not update Q .

N (input) The order of the matrix T . $N \geq 0$.

T (input/output)

On entry, the upper triangular matrix T . On exit, the reordered upper triangular matrix.

LDT (input)

The leading dimension of the array T . $LDT \geq \max(1, N)$.

Q (input)

On entry, if COMPQ = 'V', the matrix Q of Schur vectors. On exit, if COMPQ = 'V', Q has been postmultiplied by the unitary transformation matrix Z which reorders T . If COMPQ = 'N', Q is not referenced.

LDQ (input)

The leading dimension of the array Q . $LDQ \geq \max(1, N)$.

IFST (input)

Specify the reordering of the diagonal elements of T : The element with row index IFST is moved to row ILST by a sequence of transpositions between adjacent elements. $1 \leq \text{IFST} \leq N$; $1 \leq \text{ILST} \leq N$.

ILST (input)

See the description of IFST.

INFO (output)

= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

ctrmm - perform one of the matrix-matrix operations $B := \alpha * \text{op}(A) * B$, or $B := \alpha * B * \text{op}(A)$ where alpha is a scalar, B is an m by n matrix, A is a unit, or non-unit, upper or lower triangular matrix and op(A) is one of op(A) = A or op(A) = A' or op(A) = conjg(A')

SYNOPSIS

```
SUBROUTINE CTRMM(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
COMPLEX ALPHA
COMPLEX A(LDA,*), B(LDB,*)
INTEGER M, N, LDA, LDB
```

```
SUBROUTINE CTRMM_64(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                   LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
COMPLEX ALPHA
COMPLEX A(LDA,*), B(LDB,*)
INTEGER*8 M, N, LDA, LDB
```

F95 INTERFACE

```
SUBROUTINE TRMM(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A, [LDA],
                B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
COMPLEX :: ALPHA
COMPLEX, DIMENSION(:,*) :: A, B
INTEGER :: M, N, LDA, LDB
```

```
SUBROUTINE TRMM_64(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A,
                  [LDA], B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
COMPLEX :: ALPHA
COMPLEX, DIMENSION(:,*) :: A, B
INTEGER(8) :: M, N, LDA, LDB
```

C INTERFACE

```
#include <sunperf.h>

void ctrmm(char side, char uplo, char transa, char diag, int
           m, int n, complex *alpha, complex *a, int lda,
           complex *b, int ldb);
void ctrmm_64(char side, char uplo, char transa, char diag,
              long m, long n, complex *alpha, complex *a, long
              lda, complex *b, long ldb);
```

PURPOSE

ctrmm performs one of the matrix-matrix operations $B := \alpha * \text{op}(A) * B$, or $B := \alpha * B * \text{op}(A)$ where α is a scalar, B is an m by n matrix, A is a unit, or non-unit, upper or lower triangular matrix and $\text{op}(A)$ is one of $\text{op}(A) = A$ or $\text{op}(A) = A'$ or $\text{op}(A) = \text{conjg}(A')$

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether $\text{op}(A)$ multiplies B from the left or right as follows:

SIDE = 'L' or 'l' $B := \alpha * \text{op}(A) * B$.

SIDE = 'R' or 'r' $B := \alpha * B * \text{op}(A)$.

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the matrix A is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n' $\text{op}(A) = A$.

TRANSA = 'T' or 't' $\text{op}(A) = A'$.

TRANSA = 'C' or 'c' $\text{op}(A) = \text{conjg}(A')$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of B. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of B. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. When alpha is zero then A is not referenced and B need not be set before entry. Unchanged on exit.

A (input)

COMPLEX array of DIMENSION (LDA, k), where k is m when SIDE = 'L' or 'l' and is n when SIDE = 'R' or 'r'.

Before entry with UPLO = 'U' or 'u', the leading k by k upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced.

Before entry with UPLO = 'L' or 'l', the leading k by k lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced.

Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity.

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then $LDA \geq \max(1, M)$, when SIDE = 'R' or 'r' then $LDA \geq \max(1, N)$. Unchanged on exit.

B (input/output)

COMPLEX array of DIMENSION (LDB, n). Before entry, the leading M by N part of the array B must contain the matrix B, and on exit is overwritten by the transformed matrix.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling subprogram. LDB must be at least $\max(1,M)$. Unchanged on exit.

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NAME

ctrmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$

SYNOPSIS

```
SUBROUTINE CTRMV(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), Y(*)  
INTEGER N, LDA, INCY
```

```
SUBROUTINE CTRMV_64(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), Y(*)  
INTEGER*8 N, LDA, INCY
```

F95 INTERFACE

```
SUBROUTINE TRMV(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INCY
```

```
SUBROUTINE TRMV_64(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctrmv(char uplo, char transa, char diag, int n, complex  
          *a, int lda, complex *y, int incy);
```

```
void ctrmv_64(char uplo, char transa, char diag, long n,  
             complex *a, long lda, complex *y, long incy);
```

PURPOSE

ctrmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$ where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := \text{conjg}(A')*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular matrix and the

strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

Y (input/output)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

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NAME

ctrarfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix

SYNOPSIS

```
SUBROUTINE CTRRFS(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDA, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE CTRRFS_64(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDA, LDB, LDX, INFO  
REAL FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TRRFS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, B, X  
INTEGER :: N, NRHS, LDA, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE TRRFS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B,  
  [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: WORK  
COMPLEX, DIMENSION(:,:) :: A, B, X  
INTEGER(8) :: N, NRHS, LDA, LDB, LDX, INFO  
REAL, DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void ctrrfs(char uplo, char transa, char diag, int n, int
            nrhs, complex *a, int lda, complex *b, int ldb,
            complex *x, int ldx, float *ferr, float *berr, int
            *info);

void ctrrfs_64(char uplo, char transa, char diag, long n,
              long nrhs, complex *a, long lda, complex *b, long
              ldb, complex *x, long ldx, float *ferr, float
              *berr, long *info);
```

PURPOSE

ctrrfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix.

The solution matrix X must be computed by CTRTRS or some other means before entering this routine. CTRRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper

triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input) The solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ctrsen - reorder the Schur factorization of a complex matrix $A = Q^*T^*Q^*H$, so that a selected cluster of eigenvalues appears in the leading positions on the diagonal of the upper triangular matrix T, and the leading columns of Q form an orthonormal basis of the corresponding right invariant subspace

SYNOPSIS

```
SUBROUTINE CTRSEN(JOB, COMPQ, SELECT, N, T, LDT, Q, LDQ, W, M, S,  
                SEP, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ  
COMPLEX T(LDT,*), Q(LDQ,*), W(*), WORK(*)  
INTEGER N, LDT, LDQ, M, LWORK, INFO  
LOGICAL SELECT(*)  
REAL S, SEP
```

```
SUBROUTINE CTRSEN_64(JOB, COMPQ, SELECT, N, T, LDT, Q, LDQ, W, M, S,  
                   SEP, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ  
COMPLEX T(LDT,*), Q(LDQ,*), W(*), WORK(*)  
INTEGER*8 N, LDT, LDQ, M, LWORK, INFO  
LOGICAL*8 SELECT(*)  
REAL S, SEP
```

F95 INTERFACE

```
SUBROUTINE TRSEN(JOB, COMPQ, SELECT, [N], T, [LDT], Q, [LDQ], W, M,  
                S, SEP, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: T, Q  
INTEGER :: N, LDT, LDQ, M, LWORK, INFO  
LOGICAL, DIMENSION(:) :: SELECT  
REAL :: S, SEP
```

```
SUBROUTINE TRSEN_64(JOB, COMPQ, SELECT, [N], T, [LDT], Q, [LDQ], W,  
    M, S, SEP, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ  
COMPLEX, DIMENSION(:) :: W, WORK  
COMPLEX, DIMENSION(:, :) :: T, Q  
INTEGER(8) :: N, LDT, LDQ, M, LWORK, INFO  
LOGICAL(8), DIMENSION(:) :: SELECT  
REAL :: S, SEP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctrsen(char job, char compq, int *select, int n, com-  
    plex *t, int ldt, complex *q, int ldq, complex *w,  
    int *m, float *s, float *sep, int *info);
```

```
void ctrsen_64(char job, char compq, long *select, long n,  
    complex *t, long ldt, complex *q, long ldq, com-  
    plex *w, long *m, float *s, float *sep, long  
    *info);
```

PURPOSE

ctrsen reorders the Schur factorization of a complex matrix $A = Q^*TQ^{**H}$, so that a selected cluster of eigenvalues appears in the leading positions on the diagonal of the upper triangular matrix T, and the leading columns of Q form an orthonormal basis of the corresponding right invariant subspace.

Optionally the routine computes the reciprocal condition numbers of the cluster of eigenvalues and/or the invariant subspace.

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for the cluster of eigenvalues (S) or the invariant subspace (SEP):

= 'N': none;

= 'E': for eigenvalues only (S);

= 'V': for invariant subspace only (SEP);

= 'B': for both eigenvalues and invariant subspace (S and SEP).

COMPQ (input)

= 'V': update the matrix Q of Schur vectors;

= 'N': do not update Q.

SELECT (input)

SELECT specifies the eigenvalues in the selected cluster. To select the j-th eigenvalue, SELECT(j) must be set to .TRUE..

N (input) The order of the matrix T. N >= 0.

T (input/output)
 On entry, the upper triangular matrix T. On exit, T is overwritten by the reordered matrix T, with the selected eigenvalues as the leading diagonal elements.

LDT (input)
 The leading dimension of the array T. $LDT \geq \max(1, N)$.

Q (input) On entry, if COMPQ = 'V', the matrix Q of Schur vectors. On exit, if COMPQ = 'V', Q has been postmultiplied by the unitary transformation matrix which reorders T; the leading M columns of Q form an orthonormal basis for the specified invariant subspace. If COMPQ = 'N', Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. $LDQ \geq 1$; and if COMPQ = 'V', $LDQ \geq N$.

W (output)
 The reordered eigenvalues of T, in the same order as they appear on the diagonal of T.

M (output)
 The dimension of the specified invariant subspace. $0 \leq M \leq N$.

S (output)
 If JOB = 'E' or 'B', S is a lower bound on the reciprocal condition number for the selected cluster of eigenvalues. S cannot underestimate the true reciprocal condition number by more than a factor of \sqrt{N} . If $M = 0$ or N , $S = 1$. If JOB = 'N' or 'V', S is not referenced.

SEP (output)
 If JOB = 'V' or 'B', SEP is the estimated reciprocal condition number of the specified invariant subspace. If $M = 0$ or N , $SEP = \text{norm}(T)$. If JOB = 'N' or 'E', SEP is not referenced.

WORK (workspace)
 If JOB = 'N', WORK is not referenced. Otherwise, on exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. If JOB = 'N', $LWORK \geq 1$; if JOB = 'E', $LWORK = M*(N-M)$; if JOB = 'V' or 'B', $LWORK \geq 2*M*(N-M)$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

CTRSEN first collects the selected eigenvalues by computing a unitary transformation Z to move them to the top left corner of T. In other words, the selected eigenvalues are the eigenvalues of T11 in:

$$Z'^*T*Z = \begin{pmatrix} T11 & T12 \\ 0 & T22 \end{pmatrix} \begin{matrix} n1 \\ n2 \end{matrix}$$

where $N = n1+n2$ and Z' means the conjugate transpose of Z. The first $n1$ columns of Z span the specified invariant subspace of T.

If T has been obtained from the Schur factorization of a matrix $A = Q*T*Q'$, then the reordered Schur factorization of A is given by $A = (Q*Z)*(Z'*T*Z)*(Q*Z)'$, and the first $n1$ columns of $Q*Z$ span the corresponding invariant subspace of A.

The reciprocal condition number of the average of the eigenvalues of T11 may be returned in S. S lies between 0 (very badly conditioned) and 1 (very well conditioned). It is computed as follows. First we compute R so that

$$P = \begin{pmatrix} I & R \\ 0 & 0 \end{pmatrix} \begin{matrix} n1 \\ n2 \end{matrix}$$

is the projector on the invariant subspace associated with T11. R is the solution of the Sylvester equation:

$$T11*R - R*T22 = T12.$$

Let $F\text{-norm}(M)$ denote the Frobenius-norm of M and $2\text{-norm}(M)$ denote the two-norm of M. Then S is computed as the lower bound

$$(1 + F\text{-norm}(R)**2)**(-1/2)$$

on the reciprocal of $2\text{-norm}(P)$, the true reciprocal condition number. S cannot underestimate $1 / 2\text{-norm}(P)$ by more than a factor of \sqrt{N} .

An approximate error bound for the computed average of the eigenvalues of T11 is

$$EPS * \text{norm}(T) / S$$

where EPS is the machine precision.

The reciprocal condition number of the right invariant subspace spanned by the first $n1$ columns of Z (or of $Q*Z$) is returned in SEP. SEP is defined as the separation of T11 and T22:

$$\text{sep}(T11, T22) = \text{sigma-min}(C)$$

where $\sigma_{\min}(C)$ is the smallest singular value of the $n_1 \times n_2$ -by- $n_1 \times n_2$ matrix

$$C = \text{kprod}(I(n_2), T_{11}) - \text{kprod}(\text{transpose}(T_{22}), I(n_1))$$

$I(m)$ is an m by m identity matrix, and kprod denotes the Kronecker product. We estimate $\sigma_{\min}(C)$ by the reciprocal of an estimate of the 1-norm of $\text{inverse}(C)$. The true reciprocal 1-norm of $\text{inverse}(C)$ cannot differ from $\sigma_{\min}(C)$ by more than a factor of $\sqrt{n_1 \times n_2}$.

When SEP is small, small changes in T can cause large changes in the invariant subspace. An approximate bound on the maximum angular error in the computed right invariant subspace is

$$\text{EPS} * \text{norm}(T) / \text{SEP}$$

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NAME

ctrsm - solve one of the matrix equations $op(A)X = \alpha B$, or $Xop(A) = \alpha B$

SYNOPSIS

```
SUBROUTINE CTRSM(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
COMPLEX ALPHA
COMPLEX A(LDA,*), B(LDB,*)
INTEGER M, N, LDA, LDB
```

```
SUBROUTINE CTRSM_64(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                   LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
COMPLEX ALPHA
COMPLEX A(LDA,*), B(LDB,*)
INTEGER*8 M, N, LDA, LDB
```

F95 INTERFACE

```
SUBROUTINE TRSM(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A, [LDA],
               B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
COMPLEX :: ALPHA
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER :: M, N, LDA, LDB
```

```
SUBROUTINE TRSM_64(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A,
                  [LDA], B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
COMPLEX :: ALPHA
COMPLEX, DIMENSION(:, :) :: A, B
INTEGER(8) :: M, N, LDA, LDB
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctrsm(char side, char uplo, char transa, char diag, int
           m, int n, complex *alpha, complex *a, int lda,
           complex *b, int ldb);
```

```
void ctrsm_64(char side, char uplo, char transa, char diag,
              long m, long n, complex *alpha, complex *a, long
              lda, complex *b, long ldb);
```

PURPOSE

ctrsm solves one of the matrix equations $op(A)X = \alpha B$, or $Xop(A) = \alpha B$ where α is a scalar, X and B are m by n matrices, A is a unit, or non-unit, upper or lower triangular matrix and $op(A)$ is one of

$op(A) = A$ or $op(A) = A'$ or $op(A) = conjg(A')$.

The matrix X is overwritten on B .

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether $op(A)$ appears on the left or right of X as follows:

SIDE = 'L' or 'l' $op(A)X = \alpha B$.

SIDE = 'R' or 'r' $Xop(A) = \alpha B$.

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the matrix A is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the form of $op(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n' $op(A) = A$.

TRANSA = 'T' or 't' $op(A) = A'$.

TRANSA = 'C' or 'c' $op(A) = conjg(A')$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of B. M \geq 0. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of B. N \geq 0. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. When alpha is zero then A is not referenced and B need not be set before entry. Unchanged on exit.

A (input)

COMPLEX array of DIMENSION (LDA, k), where k is m when SIDE = 'L' or 'l' and is n when SIDE = 'R' or 'r'.

Before entry with UPLO = 'U' or 'u', the leading k by k upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced.

Before entry with UPLO = 'L' or 'l', the leading k by k lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced.

Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity.

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then LDA \geq max(1,M), when SIDE = 'R' or 'r' then LDA \geq max(1,N). Unchanged on exit.

B (input/output)

COMPLEX array of DIMENSION (LDB, n). Before entry, the leading M by N part of the array B must contain the right-hand side matrix B, and on exit is overwritten by the solution matrix X.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling subprogram. LDB \geq max(1,M). Unchanged on exit.

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NAME

ctrсна - estimate reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a complex upper triangular matrix T (or of any matrix $Q^*T^*Q^{**}H$ with Q unitary)

SYNOPSIS

```
SUBROUTINE CTRSNA(JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR, LDVR,
  S, SEP, MM, M, WORK, LDWORK, WORK1, INFO)
```

```
CHARACTER * 1 JOB, HOWMNY
COMPLEX T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(LDWORK,*)
INTEGER N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO
LOGICAL SELECT(*)
REAL S(*), SEP(*), WORK1(*)
```

```
SUBROUTINE CTRSNA_64(JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,
  LDVR, S, SEP, MM, M, WORK, LDWORK, WORK1, INFO)
```

```
CHARACTER * 1 JOB, HOWMNY
COMPLEX T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(LDWORK,*)
INTEGER*8 N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO
LOGICAL*8 SELECT(*)
REAL S(*), SEP(*), WORK1(*)
```

F95 INTERFACE

```
SUBROUTINE TRSNA(JOB, HOWMNY, SELECT, [N], T, [LDT], VL, [LDVL], VR,
  [LDVR], S, SEP, MM, M, [WORK], [LDWORK], [WORK1], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNY
COMPLEX, DIMENSION(:,*) :: T, VL, VR, WORK
INTEGER :: N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO
LOGICAL, DIMENSION(:) :: SELECT
REAL, DIMENSION(:) :: S, SEP, WORK1
```

```
SUBROUTINE TRSNA_64(JOB, HOWMNY, SELECT, [N], T, [LDT], VL, [LDVL],
  VR, [LDVR], S, SEP, MM, M, [WORK], [LDWORK], [WORK1], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNY
COMPLEX, DIMENSION(:,:) :: T, VL, VR, WORK
INTEGER(8) :: N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO
LOGICAL(8), DIMENSION(:) :: SELECT
REAL, DIMENSION(:) :: S, SEP, WORK1
```

C INTERFACE

```
#include <sunperf.h>
void ctrsna(char job, char howmny, int *select, int n, complex *t, int ldt, complex *vl, int ldvl, complex *vr, int ldvr, float *s, float *sep, int mm, int *m, int ldwork, int *info);

void ctrsna_64(char job, char howmny, long *select, long n, complex *t, long ldt, complex *vl, long ldvl, complex *vr, long ldvr, float *s, float *sep, long mm, long *m, long ldwork, long *info);
```

PURPOSE

ctrsna estimates reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a complex upper triangular matrix T (or of any matrix $Q^*T^*Q^{**}H$ with Q unitary).

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for eigenvalues (S) or eigenvectors (SEP):
= 'E': for eigenvalues only (S);
= 'V': for eigenvectors only (SEP);
= 'B': for both eigenvalues and eigenvectors (S and SEP).

HOWMNY (input)

= 'A': compute condition numbers for all eigenpairs;
= 'S': compute condition numbers for selected eigenpairs specified by the array SELECT.

SELECT (input)

If HOWMNY = 'S', SELECT specifies the eigenpairs for which condition numbers are required. To select condition numbers for the j-th eigenpair, SELECT(j) must be set to .TRUE.. If HOWMNY = 'A', SELECT is not referenced.

N (input) The order of the matrix T. N >= 0.

T (input) The upper triangular matrix T.

LDT (input)

The leading dimension of the array T. LDT >= max(1,N).

VL (input)
 If JOB = 'E' or 'B', VL must contain left eigenvectors of T (or of any $Q^*T*Q^{**}H$ with Q unitary), corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors must be stored in consecutive columns of VL, as returned by CHSEIN or CTREVC. If JOB = 'V', VL is not referenced.

LDVL (input)
 The leading dimension of the array VL. LDVL \geq 1; and if JOB = 'E' or 'B', LDVL \geq N.

VR (input)
 If JOB = 'E' or 'B', VR must contain right eigenvectors of T (or of any $Q^*T*Q^{**}H$ with Q unitary), corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors must be stored in consecutive columns of VR, as returned by CHSEIN or CTREVC. If JOB = 'V', VR is not referenced.

LDVR (input)
 The leading dimension of the array VR. LDVR \geq 1; and if JOB = 'E' or 'B', LDVR \geq N.

S (output)
 If JOB = 'E' or 'B', the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. Thus S(j), SEP(j), and the j-th columns of VL and VR all correspond to the same eigenpair (but not in general the j-th eigenpair, unless all eigenpairs are selected). If JOB = 'V', S is not referenced.

SEP (output)
 If JOB = 'V' or 'B', the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. If JOB = 'E', SEP is not referenced.

MM (input)
 The number of elements in the arrays S (if JOB = 'E' or 'B') and/or SEP (if JOB = 'V' or 'B'). MM \geq M.

M (output)
 The number of elements of the arrays S and/or SEP actually used to store the estimated condition numbers. If HOWMNY = 'A', M is set to N.

WORK (workspace)
 dimension(LDWORK,N+1) If JOB = 'E', WORK is not referenced.

LDWORK (input)
 The leading dimension of the array WORK. LDWORK \geq 1; and if JOB = 'V' or 'B', LDWORK \geq N.

WORK1 (workspace)
 dimension(N) If JOB = 'E', WORK1 is not refer-

enced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The reciprocal of the condition number of an eigenvalue λ is defined as

$$S(\lambda) = |v'u| / (\text{norm}(u) * \text{norm}(v))$$

where u and v are the right and left eigenvectors of T corresponding to λ ; v' denotes the conjugate transpose of v , and $\text{norm}(u)$ denotes the Euclidean norm. These reciprocal condition numbers always lie between zero (very badly conditioned) and one (very well conditioned). If $n = 1$, $S(\lambda)$ is defined to be 1.

An approximate error bound for a computed eigenvalue $W(i)$ is given by

$$\text{EPS} * \text{norm}(T) / S(i)$$

where EPS is the machine precision.

The reciprocal of the condition number of the right eigenvector u corresponding to λ is defined as follows. Suppose

$$T = \begin{pmatrix} \lambda & c \\ 0 & T_{22} \end{pmatrix}$$

Then the reciprocal condition number is

$$\text{SEP}(\lambda, T_{22}) = \text{sigma-min}(T_{22} - \lambda I)$$

where sigma-min denotes the smallest singular value. We approximate the smallest singular value by the reciprocal of an estimate of the one-norm of the inverse of $T_{22} - \lambda I$. If $n = 1$, $\text{SEP}(1)$ is defined to be $\text{abs}(T(1,1))$.

An approximate error bound for a computed right eigenvector $VR(i)$ is given by

$$\text{EPS} * \text{norm}(T) / \text{SEP}(i)$$

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NAME

ctrsv - solve one of the systems of equations $Ax = b$, or $A^T x = b$, or $\text{conjg}(A^T)x = b$

SYNOPSIS

```
SUBROUTINE CTRSV(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), Y(*)  
INTEGER N, LDA, INCY
```

```
SUBROUTINE CTRSV_64(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), Y(*)  
INTEGER*8 N, LDA, INCY
```

F95 INTERFACE

```
SUBROUTINE TRSV(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INCY
```

```
SUBROUTINE TRSV_64(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:) :: Y  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctrsv(char uplo, char transa, char diag, int n, complex  
          *a, int lda, complex *y, int incy);
```

```
void ctrsv_64(char uplo, char transa, char diag, long n,  
             complex *a, long lda, complex *y, long incy);
```

PURPOSE

ctrsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A)*x = b$ where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular matrix.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the equations to be solved as follows:

TRANSA = 'N' or 'n' $A*x = b$.

TRANSA = 'T' or 't' $A'*x = b$.

TRANSA = 'C' or 'c' $\text{conjg}(A)*x = b$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading

n by n upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

Y (input/output)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

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NAME

ctrsyl - solve the complex Sylvester matrix equation

SYNOPSIS

```
SUBROUTINE CTRSYL(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C, LDC,
  SCALE, INFO)
```

```
CHARACTER * 1 TRANA, TRANB
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER ISGN, M, N, LDA, LDB, LDC, INFO
REAL SCALE
```

```
SUBROUTINE CTRSYL_64(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C,
  LDC, SCALE, INFO)
```

```
CHARACTER * 1 TRANA, TRANB
COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 ISGN, M, N, LDA, LDB, LDC, INFO
REAL SCALE
```

F95 INTERFACE

```
SUBROUTINE TRSYL(TRANA, TRANB, ISGN, [M], [N], A, [LDA], B, [LDB], C,
  [LDC], SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: TRANA, TRANB
COMPLEX, DIMENSION(:,:) :: A, B, C
INTEGER :: ISGN, M, N, LDA, LDB, LDC, INFO
REAL :: SCALE
```

```
SUBROUTINE TRSYL_64(TRANA, TRANB, ISGN, [M], [N], A, [LDA], B, [LDB],
  C, [LDC], SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: TRANA, TRANB
COMPLEX, DIMENSION(:,:) :: A, B, C
INTEGER(8) :: ISGN, M, N, LDA, LDB, LDC, INFO
REAL :: SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctrsyl(char trana, char tranb, int isgn, int m, int n,
            complex *a, int lda, complex *b, int ldb, complex
            *c, int ldc, float *scale, int *info);
```

```
void ctrsyl_64(char trana, char tranb, long isgn, long m,
               long n, complex *a, long lda, complex *b, long
               ldb, complex *c, long ldc, float *scale, long
               *info);
```

PURPOSE

ctrsyl solves the complex Sylvester matrix equation:

```
op(A)*X + X*op(B) = scale*C or
op(A)*X - X*op(B) = scale*C,
```

where $op(A) = A$ or A^{**H} , and A and B are both upper triangular. A is M -by- M and B is N -by- N ; the right hand side C and the solution X are M -by- N ; and $scale$ is an output scale factor, set ≤ 1 to avoid overflow in X .

ARGUMENTS

TRANA (input)

```
Specifies the option op(A):
= 'N': op(A) = A      (No transpose)
= 'C': op(A) = A**H  (Conjugate transpose)
```

TRANB (input)

```
Specifies the option op(B):
= 'N': op(B) = B      (No transpose)
= 'C': op(B) = B**H  (Conjugate transpose)
```

ISGN (input)

```
Specifies the sign in the equation:
= +1: solve op(A)*X + X*op(B) = scale*C
= -1: solve op(A)*X - X*op(B) = scale*C
```

M (input) The order of the matrix A , and the number of rows in the matrices X and C . $M \geq 0$.

N (input) The order of the matrix B , and the number of columns in the matrices X and C . $N \geq 0$.

A (input) The upper triangular matrix A .

LDA (input)

```
The leading dimension of the array A. LDA  $\geq$ 
max(1,M).
```

B (input) The upper triangular matrix B .

LDB (input)

```
The leading dimension of the array B. LDB  $\geq$ 
max(1,N).
```

C (input/output)

On entry, the M-by-N right hand side matrix C. On exit, C is overwritten by the solution matrix X.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M)

SCALE (output)

The scale factor, scale, set ≤ 1 to avoid overflow in X.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
= 1: A and B have common or very close eigenvalues; perturbed values were used to solve the equation (but the matrices A and B are unchanged).

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NAME

ctrtri2 - compute the inverse of a complex upper or lower triangular matrix

SYNOPSIS

```
SUBROUTINE CTRTRI2(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE CTRTRI2_64(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE TRTRI2(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE TRTRI2_64(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctrtri2(char uplo, char diag, int n, complex *a, int  
            lda, int *info);
```

```
void ctrtri2_64(char uplo, char diag, long n, complex *a,  
               long lda, long *info);
```

PURPOSE

ctrtri2 computes the inverse of a complex upper or lower triangular matrix.

This is the Level 2 BLAS version of the algorithm.

ARGUMENTS

UPLO (input)

Specifies whether the matrix A is upper or lower triangular. = 'U': Upper triangular
= 'L': Lower triangular

DIAG (input)

Specifies whether or not the matrix A is unit triangular. = 'N': Non-unit triangular
= 'U': Unit triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular matrix A. If UPLO = 'U', the leading n by n upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n by n lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

On exit, the (triangular) inverse of the original matrix, in the same storage format.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value

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NAME

ctrtri - compute the inverse of a complex upper or lower triangular matrix A

SYNOPSIS

```
SUBROUTINE CTRTRI(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE CTRTRI_64(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE TRTRI(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE TRTRI_64(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctrtri(char uplo, char diag, int n, complex *a, int  
            lda, int *info);
```

```
void ctrtri_64(char uplo, char diag, long n, complex *a,  
              long lda, long *info);
```

PURPOSE

ctrtri computes the inverse of a complex upper or lower triangular matrix A.

This is the Level 3 BLAS version of the algorithm.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1. On exit, the (triangular) inverse of the original matrix, in the same storage format.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, A(i,i) is exactly zero. The triangular matrix is singular and its inverse can not be computed.

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NAME

ctrtrs - solve a triangular system of the form $A * X = B$,
 $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE CTRTRS(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE CTRTRS_64(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB,  
INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE TRTRS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE TRTRS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B,  
[LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX, DIMENSION(:,:) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctrtrs(char uplo, char transa, char diag, int n, int  
nrhs, complex *a, int lda, complex *b, int ldb,  
int *info);
```

```
void ctrtrs_64(char uplo, char transa, char diag, long n,
              long nrhs, complex *a, long lda, complex *b, long
              ldb, long *info);
```

PURPOSE

ctrtrs solves a triangular system of the form
 $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$

where A is a triangular matrix of order N, and B is an N-by-NRHS matrix. A check is made to verify that A is non-singular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the right hand side matrix B. On exit, if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element of A is zero, indicating that the matrix is singular and the solutions X have not been computed.

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NAME

ctzrqf - routine is deprecated and has been replaced by routine CTZRZF

SYNOPSIS

```
SUBROUTINE CTZRQF(M, N, A, LDA, TAU, INFO)
```

```
COMPLEX A(LDA,*), TAU(*)  
INTEGER M, N, LDA, INFO
```

```
SUBROUTINE CTZRQF_64(M, N, A, LDA, TAU, INFO)
```

```
COMPLEX A(LDA,*), TAU(*)  
INTEGER*8 M, N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE TZRQF([M], [N], A, [LDA], TAU, [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: M, N, LDA, INFO
```

```
SUBROUTINE TZRQF_64([M], [N], A, [LDA], TAU, [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: M, N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctzrqf(int m, int n, complex *a, int lda, complex *tau,  
           int *info);
```

```
void ctzrqf_64(long m, long n, complex *a, long lda, complex  
              *tau, long *info);
```

PURPOSE

ctzrqf routine is deprecated and has been replaced by routine CTZRZF.

CTZRQF reduces the M-by-N ($M \leq N$) complex upper trapezoidal matrix A to upper triangular form by means of unitary transformations.

The upper trapezoidal matrix A is factored as

$$A = \begin{pmatrix} R & 0 \end{pmatrix} * Z,$$

where Z is an N-by-N unitary matrix and R is an M-by-M upper triangular matrix.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq M$.

A (input/output)

On entry, the leading M-by-N upper trapezoidal part of the array A must contain the matrix to be factorized. On exit, the leading M-by-M upper triangular part of A contains the upper triangular matrix R, and elements M+1 to N of the first M rows of A, with the array TAU, represent the unitary matrix Z as a product of M elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The factorization is obtained by Householder's method. The kth transformation matrix, $Z(k)$, whose conjugate transpose is used to introduce zeros into the $(m - k + 1)$ th row of A, is given in the form

$$Z(k) = \begin{pmatrix} I & 0 \\ 0 & T(k) \end{pmatrix},$$

where

$$T(k) = I - \tau u(k) u(k)', \quad u(k) = \begin{pmatrix} 1 \\ \end{pmatrix},$$

$$\begin{pmatrix} 0 \\ z(k) \end{pmatrix}$$

tau is a scalar and $z(k)$ is an $(n - m)$ element vector. tau and $z(k)$ are chosen to annihilate the elements of the kth row of X.

The scalar tau is returned in the kth element of TAU and the vector $u(k)$ in the kth row of A, such that the elements of $z(k)$ are in $a(k, m + 1), \dots, a(k, n)$. The elements of R are returned in the upper triangular part of A.

Z is given by

$$Z = Z(1) * Z(2) * \dots * Z(m).$$

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NAME

ctzrzf - reduce the M-by-N ($M \leq N$) complex upper trapezoidal matrix A to upper triangular form by means of unitary transformations

SYNOPSIS

```
SUBROUTINE CTZRZF(M, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LWORK, INFO
```

```
SUBROUTINE CTZRZF_64(M, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE TZRZF([M], [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, LWORK, INFO
```

```
SUBROUTINE TZRZF_64([M], [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ctzrzf(int m, int n, complex *a, int lda, complex *tau,  
           int *info);
```

```
void ctzrzf_64(long m, long n, complex *a, long lda, complex  
              *tau, long *info);
```

PURPOSE

ctzrzf reduces the M-by-N ($M \leq N$) complex upper trapezoidal matrix A to upper triangular form by means of unitary transformations.

The upper trapezoidal matrix A is factored as

$$A = \begin{pmatrix} R & 0 \end{pmatrix} * Z,$$

where Z is an N-by-N unitary matrix and R is an M-by-M upper triangular matrix.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the leading M-by-N upper trapezoidal part of the array A must contain the matrix to be factorized. On exit, the leading M-by-M upper triangular part of A contains the upper triangular matrix R, and elements M+1 to N of the first M rows of A, with the array TAU, represent the unitary matrix Z as a product of M elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1, M)$. For optimum performance $LWORK \geq M * NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by

A. Petitot, Computer Science Dept., Univ. of Tenn., Knoxville, USA

The factorization is obtained by Householder's method. The kth transformation matrix, $Z(k)$, which is used to introduce zeros into the $(m - k + 1)$ th row of A, is given in the form

$$Z(k) = \begin{pmatrix} I & 0 \\ 0 & T(k) \end{pmatrix},$$

where

$$T(k) = I - \tau u(k)u(k)', \quad u(k) = \begin{pmatrix} 1 \\ 0 \\ z(k) \end{pmatrix},$$

τ is a scalar and $z(k)$ is an $(n - m)$ element vector. τ and $z(k)$ are chosen to annihilate the elements of the kth row of X.

The scalar τ is returned in the kth element of TAU and the vector $u(k)$ in the kth row of A, such that the elements of $z(k)$ are in $a(k, m + 1), \dots, a(k, n)$. The elements of R are returned in the upper triangular part of A.

Z is given by

$$Z = Z(1) * Z(2) * \dots * Z(m).$$

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NAME

cung2l - generate an m by n complex matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE CUNG2L(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, INFO
```

```
SUBROUTINE CUNG2L_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE UNG2L(M, [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: M, N, K, LDA, INFO
```

```
SUBROUTINE UNG2L_64(M, [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: M, N, K, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cung2l(int m, int n, int k, complex *a, int lda, complex *tau, int *info);
```

```
void cung2l_64(long m, long n, long k, complex *a, long lda, complex *tau, long *info);
```

PURPOSE

cung21 L generates an m by n complex matrix Q with orthonormal columns, which is defined as the last n columns of a product of k elementary reflectors of order m

$$Q = H(k) \dots H(2) H(1)$$

as returned by CGEQLF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.

A (input/output)

On entry, the (n-k+i)-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by CGEQLF in the last k columns of its array argument A. On exit, the m-by-n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGEQLF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

cung2r - generate an m by n complex matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE CUNG2R(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, INFO
```

```
SUBROUTINE CUNG2R_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE UNG2R(M, [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, INFO
```

```
SUBROUTINE UNG2R_64(M, [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cung2r(int m, int n, int k, complex *a, int lda, complex *tau, int *info);
```

```
void cung2r_64(long m, long n, long k, complex *a, long lda, complex *tau, long *info);
```

PURPOSE

cung2r R generates an m by n complex matrix Q with orthonormal columns, which is defined as the first n columns of a product of k elementary reflectors of order m

$$Q = H(1) H(2) \dots H(k)$$

as returned by CGEQRF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.

A (input/output)

On entry, the i-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by CGEQRF in the first k columns of its array argument A. On exit, the m by n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGEQRF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

cungbr - generate one of the complex unitary matrices Q or P^*H determined by CGEBRD when reducing a complex matrix A to bidiagonal form

SYNOPSIS

```
SUBROUTINE CUNGBR(VECT, M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT  
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE CUNGBR_64(VECT, M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT  
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGBR(VECT, M, [N], K, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: VECT  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE UNGBR_64(VECT, M, [N], K, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: VECT  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cungbr(char vect, int m, int n, int k, complex *a, int  
lda, complex *tau, int *info);
```

```
void cungr_64(char vect, long m, long n, long k, complex
             *a, long lda, complex *tau, long *info);
```

PURPOSE

cungr generates one of the complex unitary matrices Q or P^{*H} determined by CGEBRD when reducing a complex matrix A to bidiagonal form: $A = Q * B * P^{*H}$. Q and P^{*H} are defined as products of elementary reflectors $H(i)$ or $G(i)$ respectively.

If $VECT = 'Q'$, A is assumed to have been an M -by- K matrix, and Q is of order M :
if $m \geq k$, $Q = H(1) H(2) \dots H(k)$ and CUNGR returns the first n columns of Q , where $m \geq n \geq k$;
if $m < k$, $Q = H(1) H(2) \dots H(m-1)$ and CUNGR returns Q as an M -by- M matrix.

If $VECT = 'P'$, A is assumed to have been a K -by- N matrix, and P^{*H} is of order N :
if $k < n$, $P^{*H} = G(k) \dots G(2) G(1)$ and CUNGR returns the first m rows of P^{*H} , where $n \geq m \geq k$;
if $k \geq n$, $P^{*H} = G(n-1) \dots G(2) G(1)$ and CUNGR returns P^{*H} as an N -by- N matrix.

ARGUMENTS

VECT (input)

Specifies whether the matrix Q or the matrix P^{*H} is required, as defined in the transformation applied by CGEBRD:
= 'Q': generate Q ;
= 'P': generate P^{*H} .

M (input) The number of rows of the matrix Q or P^{*H} to be returned. $M \geq 0$.

N (input) The number of columns of the matrix Q or P^{*H} to be returned. $N \geq 0$. If $VECT = 'Q'$, $M \geq N \geq \min(M, K)$; if $VECT = 'P'$, $N \geq M \geq \min(N, K)$.

K (input) If $VECT = 'Q'$, the number of columns in the original M -by- K matrix reduced by CGEBRD. If $VECT = 'P'$, the number of rows in the original K -by- N matrix reduced by CGEBRD. $K \geq 0$.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by CGEBRD. On exit, the M -by- N matrix Q or P^{*H} .

LDA (input)

The leading dimension of the array A . $LDA \geq M$.

TAU (input)

($\min(M,K)$) if VECT = 'Q' ($\min(N,K)$) if VECT = 'P'
TAU(i) must contain the scalar factor of the elementary reflector H(i) or G(i), which determines Q or P**H, as returned by CGEBRD in its array argument TAUQ or TAUP.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq $\max(1, \min(M,N))$. For optimum performance LWORK \geq $\min(M,N)*NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cunghr - generate a complex unitary matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N, as returned by CGEHRD

SYNOPSIS

```
SUBROUTINE CUNGHR(N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER N, ILO, IHI, LDA, LWORK, INFO
```

```
SUBROUTINE CUNGHR_64(N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 N, ILO, IHI, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGHR([N], ILO, IHI, A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: N, ILO, IHI, LDA, LWORK, INFO
```

```
SUBROUTINE UNGHR_64([N], ILO, IHI, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: N, ILO, IHI, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunghr(int n, int ilo, int ihi, complex *a, int lda,  
complex *tau, int *info);
```

```
void cunghr_64(long n, long ilo, long ihi, complex *a, long  
lda, complex *tau, long *info);
```

PURPOSE

cunghr generates a complex unitary matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N , as returned by CGEHRD:

$$Q = H(\text{ilo}) H(\text{ilo}+1) \dots H(\text{ihi}-1).$$

ARGUMENTS

N (input) The order of the matrix Q . $N \geq 0$.

ILO (input)

ILO and IHI must have the same values as in the previous call of CGEHRD. Q is equal to the unit matrix except in the submatrix $Q(\text{ilo}+1:\text{ihi}, \text{ilo}+1:\text{ihi})$. $1 \leq \text{ILO} \leq \text{IHI} \leq N$, if $N > 0$; $\text{ILO}=1$ and $\text{IHI}=0$, if $N=0$.

IHI (input)

See the description of IHI.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by CGEHRD. On exit, the N -by- N unitary matrix Q .

LDA (input)

The leading dimension of the array A . $\text{LDA} \geq \max(1, N)$.

TAU (input)

$\text{TAU}(i)$ must contain the scalar factor of the elementary reflector $H(i)$, as returned by CGEHRD.

WORK (workspace)

On exit, if $\text{INFO} = 0$, $\text{WORK}(1)$ returns the optimal LWORK .

LWORK (input)

The dimension of the array WORK . $\text{LWORK} \geq \text{IHI}-\text{ILO}$. For optimum performance $\text{LWORK} \geq (\text{IHI}-\text{ILO}) * \text{NB}$, where NB is the optimal blocksize.

If $\text{LWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value

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NAME

cungl2 - generate an m-by-n complex matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE CUNGL2(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, INFO
```

```
SUBROUTINE CUNGL2_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGL2([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, INFO
```

```
SUBROUTINE UNGL2_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cungl2(int m, int n, int k, complex *a, int lda, complex *tau, int *info);
```

```
void cungl2_64(long m, long n, long k, complex *a, long lda, complex *tau, long *info);
```

PURPOSE

cungl2 generates an m-by-n complex matrix Q with orthonormal rows, which is defined as the first m rows of a product of k elementary reflectors of order n

$$Q = H(k)' \dots H(2)' H(1)'$$

as returned by CGELQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $M \geq K \geq 0$.

A (input/output)

On entry, the i-th row must contain the vector which defines the elementary reflector $H(i)$, for $i = 1, 2, \dots, k$, as returned by CGELQF in the first k rows of its array argument A. On exit, the m by n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by CGELQF.

WORK (workspace)

dimension(M)

INFO (output)

= 0: successful exit

< 0: if $INFO = -i$, the i-th argument has an illegal value

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NAME

cunglq - generate an M-by-N complex matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE CUNGLQ(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE CUNGLQ_64(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGLQ(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE UNGLQ_64(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunglq(int m, int n, int k, complex *a, int lda, complex *tau, int *info);
```

```
void cunglq_64(long m, long n, long k, complex *a, long lda, complex *tau, long *info);
```

PURPOSE

cunglq generates an M-by-N complex matrix Q with orthonormal rows, which is defined as the first M rows of a product of K elementary reflectors of order N

$$Q = H(k)' \dots H(2)' H(1)'$$

as returned by CGELQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. M >= 0.

N (input) The number of columns of the matrix Q. N >= M.

K (input) The number of elementary reflectors whose product defines the matrix Q. M >= K >= 0.

A (input/output)

On entry, the i-th row must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGELQF in the first k rows of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. LDA >= max(1,M).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGELQF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK >= max(1,M). For optimum performance LWORK >= M*NB, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit;

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

cungql - generate an M-by-N complex matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE CUNGQL(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE CUNGQL_64(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGQL(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE UNGQL_64(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cungql(int m, int n, int k, complex *a, int lda, complex *tau, int *info);
```

```
void cungql_64(long m, long n, long k, complex *a, long lda, complex *tau, long *info);
```

PURPOSE

cungql generates an M-by-N complex matrix Q with orthonormal columns, which is defined as the last N columns of a product of K elementary reflectors of order M

$$Q = H(k) \dots H(2) H(1)$$

as returned by CGEQLF.

ARGUMENTS

- M (input) The number of rows of the matrix Q. $M \geq 0$.
- N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.
- K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.
- A (input/output)
On entry, the (n-k+i)-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by CGEQLF in the last k columns of its array argument A. On exit, the M-by-N matrix Q.
- LDA (input)
The first dimension of the array A. $LDA \geq \max(1, M)$.
- TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGEQLF.
- WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.
- LWORK (input)
The dimension of the array WORK. $LWORK \geq \max(1, N)$. For optimum performance $LWORK \geq N * NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.
- INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

cungqr - generate an M-by-N complex matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE CUNGQR(M, N, K, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORKIN(*)  
INTEGER M, N, K, LDA, LWORKIN, INFO
```

```
SUBROUTINE CUNGQR_64(M, N, K, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORKIN(*)  
INTEGER*8 M, N, K, LDA, LWORKIN, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGQR(M, [N], [K], A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORKIN  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: M, N, K, LDA, LWORKIN, INFO
```

```
SUBROUTINE UNGQR_64(M, [N], [K], A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORKIN  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: M, N, K, LDA, LWORKIN, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cungqr(int m, int n, int k, complex *a, int lda, complex *tau, int *info);
```

```
void cungqr_64(long m, long n, long k, complex *a, long lda, complex *tau, long *info);
```

PURPOSE

cungqr generates an M-by-N complex matrix Q with orthonormal columns, which is defined as the first N columns of a product of K elementary reflectors of order M

$$Q = H(1) H(2) \dots H(k)$$

as returned by CGEQRF.

ARGUMENTS

M (input) The number of rows of the matrix Q. M >= 0.

N (input) The number of columns of the matrix Q. M >= N >= 0.

K (input) The number of elementary reflectors whose product defines the matrix Q. N >= K >= 0.

A (input/output)

On entry, the i-th column must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGEQRF in the first k columns of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. LDA >= max(1,M).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGEQRF.

WORKIN (workspace)

On exit, if INFO = 0, WORKIN(1) returns the optimal LWORKIN.

LWORKIN (input)

The dimension of the array WORKIN. LWORKIN >= max(1,N). For optimum performance LWORKIN >= N*NB, where NB is the optimal blocksize.

If LWORKIN = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORKIN array, returns this value as the first entry of the WORKIN array, and no error message related to LWORKIN is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

cungr2 - generate an m by n complex matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE CUNGR2(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, INFO
```

```
SUBROUTINE CUNGR2_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGR2([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER :: M, N, K, LDA, INFO
```

```
SUBROUTINE UNGR2_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A  
INTEGER(8) :: M, N, K, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cungr2(int m, int n, int k, complex *a, int lda, complex *tau, int *info);
```

```
void cungr2_64(long m, long n, long k, complex *a, long lda, complex *tau, long *info);
```

PURPOSE

cungr2 generates an m by n complex matrix Q with orthonormal rows, which is defined as the last m rows of a product of k elementary reflectors of order n

$$Q = H(1)' H(2)' \dots H(k)'$$

as returned by CGERQF.

ARGUMENTS

M (input) The number of rows of the matrix Q . $M \geq 0$.

N (input) The number of columns of the matrix Q . $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q . $M \geq K \geq 0$.

A (input/output)

On entry, the $(m-k+i)$ -th row must contain the vector which defines the elementary reflector $H(i)$, for $i = 1, 2, \dots, k$, as returned by CGERQF in the last k rows of its array argument A . On exit, the m -by- n matrix Q .

LDA (input)

The first dimension of the array A . $LDA \geq \max(1, M)$.

TAU (input)

$TAU(i)$ must contain the scalar factor of the elementary reflector $H(i)$, as returned by CGERQF.

WORK (workspace)

dimension(M)

INFO (output)

= 0: successful exit

< 0: if $INFO = -i$, the i -th argument has an illegal value

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NAME

cungrq - generate an M-by-N complex matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE CUNGRQ(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE CUNGRQ_64(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGRQ(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE UNGRQ_64(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cungrq(int m, int n, int k, complex *a, int lda, complex *tau, int *info);
```

```
void cungrq_64(long m, long n, long k, complex *a, long lda, complex *tau, long *info);
```

PURPOSE

cungrq generates an M-by-N complex matrix Q with orthonormal rows, which is defined as the last M rows of a product of K elementary reflectors of order N

$$Q = H(1)' H(2)' \dots H(k)'$$

as returned by CGERQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. M >= 0.

N (input) The number of columns of the matrix Q. N >= M.

K (input) The number of elementary reflectors whose product defines the matrix Q. M >= K >= 0.

A (input/output)

On entry, the (m-k+i)-th row must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGERQF in the last k rows of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. LDA >= max(1,M).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGERQF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK >= max(1,M). For optimum performance LWORK >= M*Nb, where Nb is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

cungtr - generate a complex unitary matrix Q which is defined as the product of n-1 elementary reflectors of order N, as returned by CHETRD

SYNOPSIS

```
SUBROUTINE CUNGTR(UPLO, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER N, LDA, LWORK, INFO
```

```
SUBROUTINE CUNGTR_64(UPLO, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 N, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGTR(UPLO, [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LWORK, INFO
```

```
SUBROUTINE UNGTR_64(UPLO, [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cungtr(char uplo, int n, complex *a, int lda, complex  
            *tau, int *info);
```

```
void cungtr_64(char uplo, long n, complex *a, long lda, com-
```

```
plex *tau, long *info);
```

PURPOSE

cungtr generates a complex unitary matrix Q which is defined as the product of $n-1$ elementary reflectors of order N , as returned by CHETRD:

if UPLO = 'U', $Q = H(n-1) \dots H(2) H(1)$,

if UPLO = 'L', $Q = H(1) H(2) \dots H(n-1)$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A contains elementary reflectors from CHETRD; = 'L': Lower triangle of A contains elementary reflectors from CHETRD.

N (input) The order of the matrix Q . $N \geq 0$.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by CHETRD. On exit, the N -by- N unitary matrix Q .

LDA (input)

The leading dimension of the array A . $LDA \geq N$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by CHETRD.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq N-1$. For optimum performance $LWORK \geq (N-1)*NB$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

cunmbr - VECT = 'Q', CUNMBR overwrites the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE CUNMBR(VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC,
                 WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT, SIDE, TRANS
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE CUNMBR_64(VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC,
                    WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT, SIDE, TRANS
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMBR(VECT, SIDE, [TRANS], [M], [N], K, A, [LDA], TAU, C,
                [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, SIDE, TRANS
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A, C
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMBR_64(VECT, SIDE, [TRANS], [M], [N], K, A, [LDA], TAU,
                   C, [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, SIDE, TRANS
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A, C
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunmbr(char vect, char side, char trans, int m, int n,
```

```

        int k, complex *a, int lda, complex *tau, complex
        *c, int ldc, int *info);

void cunmbr_64(char vect, char side, char trans, long m,
              long n, long k, complex *a, long lda, complex
              *tau, complex *c, long ldc, long *info);

```

PURPOSE

cunmbr VECT = 'Q', CUNMBR overwrites the general complex M-by-N matrix C with

```

                SIDE = 'L'      SIDE = 'R'  TRANS = 'N':
Q * C          C * Q TRANS = 'C':      Q**H * C      C *
Q**H

```

If VECT = 'P', CUNMBR overwrites the general complex M-by-N matrix C with

```

                SIDE = 'L'      SIDE = 'R'
TRANS = 'N':    P * C          C * P
TRANS = 'C':    P**H * C       C * P**H

```

Here Q and P**H are the unitary matrices determined by CGEBRD when reducing a complex matrix A to bidiagonal form: $A = Q * B * P^{**H}$. Q and P**H are defined as products of elementary reflectors H(i) and G(i) respectively.

Let nq = m if SIDE = 'L' and nq = n if SIDE = 'R'. Thus nq is the order of the unitary matrix Q or P**H that is applied.

If VECT = 'Q', A is assumed to have been an NQ-by-K matrix:
if nq >= k, Q = H(1) H(2) . . . H(k);
if nq < k, Q = H(1) H(2) . . . H(nq-1).

If VECT = 'P', A is assumed to have been a K-by-NQ matrix:
if k < nq, P = G(1) G(2) . . . G(k);
if k >= nq, P = G(1) G(2) . . . G(nq-1).

ARGUMENTS

VECT (input)

```

= 'Q': apply Q or Q**H;
= 'P': apply P or P**H.

```

SIDE (input)

```

= 'L': apply Q, Q**H, P or P**H from the Left;
= 'R': apply Q, Q**H, P or P**H from the Right.

```

TRANS (input)

```

= 'N': No transpose, apply Q or P;
= 'C': Conjugate transpose, apply Q**H or P**H.

```

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) If VECT = 'Q', the number of columns in the original matrix reduced by CGEBRD. If VECT = 'P', the number of rows in the original matrix reduced by CGEBRD. $K \geq 0$.

A (input) (LDA,min(nq,K)) if VECT = 'Q' (LDA,nq) if VECT = 'P' The vectors which define the elementary reflectors H(i) and G(i), whose products determine the matrices Q and P, as returned by CGEBRD.

LDA (input)
The leading dimension of the array A. If VECT = 'Q', $LDA \geq \max(1,nq)$; if VECT = 'P', $LDA \geq \max(1,\min(nq,K))$.

TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector H(i) or G(i) which determines Q or P, as returned by CGEBRD in the array argument TAUQ or TAUP.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by $Q*C$ or $Q**H*C$ or $C*Q**H$ or $C*Q$ or $P*C$ or $P**H*C$ or $C*P$ or $C**H$.

LDC (input)
The leading dimension of the array C. $LDC \geq \max(1,M)$.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. If SIDE = 'L', $LWORK \geq \max(1,N)$; if SIDE = 'R', $LWORK \geq \max(1,M)$. For optimum performance $LWORK \geq N*NB$ if SIDE = 'L', and $LWORK \geq M*NB$ if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cunmhr - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE CUNMHR(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C, LDC,  
                WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, ILO, IHI, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE CUNMHR_64(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C,  
                    LDC, WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, ILO, IHI, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMHR(SIDE, [TRANS], [M], [N], ILO, IHI, A, [LDA], TAU, C,  
                [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER :: M, N, ILO, IHI, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMHR_64(SIDE, [TRANS], [M], [N], ILO, IHI, A, [LDA], TAU,  
                   C, [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER(8) :: M, N, ILO, IHI, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunmhr(char side, char trans, int m, int n, int ilo,
```

```

        int ihi, complex *a, int lda, complex *tau, complex *c, int ldc, int *info);

void cummhr_64(char side, char trans, long m, long n, long ilo, long ihi, complex *a, long lda, complex *tau, complex *c, long ldc, long *info);

```

PURPOSE

cummhr overwrites the general complex M-by-N matrix C with
 TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix of order nq, with nq = m if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the product of IHI-ILO elementary reflectors, as returned by CGEHRD:

$Q = H(\text{ilo}) H(\text{ilo}+1) \dots H(\text{ihi}-1).$

ARGUMENTS

SIDE (input)
 = 'L': apply Q or Q**H from the Left;
 = 'R': apply Q or Q**H from the Right.

TRANS (input)
 = 'N': apply Q (No transpose)
 = 'C': apply Q**H (Conjugate transpose)

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

ILO (input)
 ILO and IHI must have the same values as in the previous call of CGEHRD. Q is equal to the unit matrix except in the submatrix Q(ilo+1:ihi,ilo+1:ihi). If SIDE = 'L', then 1 <= ILO <= IHI <= M, if M > 0, and ILO = 1 and IHI = 0, if M = 0; if SIDE = 'R', then 1 <= ILO <= IHI <= N, if N > 0, and ILO = 1 and IHI = 0, if N = 0.

IHI (input)
 See the description of ILO.

A (input) (LDA,M) if SIDE = 'L' (LDA,N) if SIDE = 'R' The vectors which define the elementary reflectors, as returned by CGEHRD.

LDA (input)
 The leading dimension of the array A. LDA >= max(1,M) if SIDE = 'L'; LDA >= max(1,N) if SIDE = 'R'.

TAU (input)
 (M-1) if SIDE = 'L' (N-1) if SIDE = 'R' TAU(i)
 must contain the scalar factor of the elementary
 reflector H(i), as returned by CGEHRD.

C (input/output)
 On entry, the M-by-N matrix C. On exit, C is
 overwritten by Q*C or Q**H*C or C*Q**H or C*Q.

LDC (input)
 The leading dimension of the array C. LDC >=
 max(1,M).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal
 LWORK.

LWORK (input)
 The dimension of the array WORK. If SIDE = 'L',
 LWORK >= max(1,N); if SIDE = 'R', LWORK >=
 max(1,M). For optimum performance LWORK >= N*NB
 if SIDE = 'L', and LWORK >= M*NB if SIDE = 'R',
 where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the WORK array, returns this value as the first
 entry of the WORK array, and no error message
 related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-
 gal value

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NAME

cunml2 - overwrite the general complex m-by-n matrix C with $Q * C$ if SIDE = 'L' and TRANS = 'N', or $Q' * C$ if SIDE = 'L' and TRANS = 'C', or $C * Q$ if SIDE = 'R' and TRANS = 'N', or $C * Q'$ if SIDE = 'R' and TRANS = 'C',

SYNOPSIS

```
SUBROUTINE CUNML2(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
                 INFO)
```

```
CHARACTER * 1 SIDE, TRANS
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER M, N, K, LDA, LDC, INFO
```

```
SUBROUTINE CUNML2_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
                    INFO)
```

```
CHARACTER * 1 SIDE, TRANS
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER*8 M, N, K, LDA, LDC, INFO
```

F95 INTERFACE

```
SUBROUTINE UNML2(SIDE, TRANS, [M], [N], [K], A, [LDA], TAU, C, [LDC],
                [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A, C
INTEGER :: M, N, K, LDA, LDC, INFO
```

```
SUBROUTINE UNML2_64(SIDE, TRANS, [M], [N], [K], A, [LDA], TAU, C,
                   [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A, C
INTEGER(8) :: M, N, K, LDA, LDC, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunml2(char side, char trans, int m, int n, int k, complex *a, int lda, complex *tau, complex *c, int ldc, int *info);
```

```
void cunml2_64(char side, char trans, long m, long n, long k, complex *a, long lda, complex *tau, complex *c, long ldc, long *info);
```

PURPOSE

cunml2 overwrites the general complex m-by-n matrix C with

where Q is a complex unitary matrix defined as the product of k elementary reflectors

$$Q = H(k)' \dots H(2)' H(1)'$$

as returned by CGELQF. Q is of order m if SIDE = 'L' and of order n if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q' from the Left
 = 'R': apply Q or Q' from the Right

TRANS (input)

= 'N': apply Q (No transpose)
 = 'C': apply Q' (Conjugate transpose)

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product defines the matrix Q. If SIDE = 'L', M >= K >= 0; if SIDE = 'R', N >= K >= 0.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The i-th row must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGELQF in the first k rows of its array argument A. A is modified by the routine but restored on exit.

LDA (input)

The leading dimension of the array A. LDA >= max(1,K).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGELQF.

C (input/output)

On entry, the m-by-n matrix C. On exit, C is

overwritten by Q*C or Q'*C or C*Q' or C*Q.

LDC (input)

The leading dimension of the array C. LDC \geq
max(1,M).

WORK (workspace)

(N) if SIDE = 'L', (M) if SIDE = 'R'

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

cunmlq - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE CUNMLQ(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE CUNMLQ_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMLQ(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A, C  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMLQ_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A, C  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunmlq(char side, char trans, int m, int n, int k, com-
```

```

plex *a, int lda, complex *tau, complex *c, int
ldc, int *info);

void cunmlq_64(char side, char trans, long m, long n, long
k, complex *a, long lda, complex *tau, complex *c,
long ldc, long *info);

```

PURPOSE

cunmlq overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C$ $C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
of k elementary reflectors

$$Q = H(k)' \dots H(2)' H(1)'$$

as returned by CGELQF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
= 'R': apply Q or Q^{*H} from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Conjugate transpose, apply Q^{*H} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
if SIDE = 'R', $N \geq K \geq 0$.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
i-th row must contain the vector which defines the
elementary reflector H(i), for $i = 1, 2, \dots, k$, as
returned by CGELQF in the first k rows of its
array argument A. A is modified by the routine
but restored on exit.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, K)$.

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by CGELQF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**H}C$ or C^*Q^{**H} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cunmql - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE CUNMQL(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE CUNMQL_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMQL(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMQL_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunmql(char side, char trans, int m, int n, int k, com-
```

```

plex *a, int lda, complex *tau, complex *c, int
ldc, int *info);

void cunmql_64(char side, char trans, long m, long n, long
k, complex *a, long lda, complex *tau, complex *c,
long ldc, long *info);

```

PURPOSE

cunmql overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
of k elementary reflectors

$$Q = H(k) \dots H(2) H(1)$$

as returned by CGEQLF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**H from the Left;
= 'R': apply Q or Q**H from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Transpose, apply Q**H.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', M >= K >= 0;
if SIDE = 'R', N >= K >= 0.

A (input) The i-th column must contain the vector which
defines the elementary reflector H(i), for i =
1,2,...,k, as returned by CGEQLF in the last k
columns of its array argument A. A is modified by
the routine but restored on exit.

LDA (input)

The leading dimension of the array A. If SIDE =
'L', LDA >= max(1,M); if SIDE = 'R', LDA >=
max(1,N).

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by CGEQLF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**H}C$ or C^*Q^{**H} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cunmqr - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE CUNMQR(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE CUNMQR_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMQR(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMQR_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunmqr(char side, char trans, int m, int n, int k, com-
```

```

plex *a, int lda, complex *tau, complex *c, int
ldc, int *info);

void cunmqr_64(char side, char trans, long m, long n, long
k, complex *a, long lda, complex *tau, complex *c,
long ldc, long *info);

```

PURPOSE

cunmqr overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
of k elementary reflectors

$$Q = H(1) H(2) \dots H(k)$$

as returned by CGEQRF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
= 'R': apply Q or Q^{*H} from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Conjugate transpose, apply Q^{*H} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
if SIDE = 'R', $N \geq K \geq 0$.

A (input) The i-th column must contain the vector which
defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by CGEQRF in the first k
columns of its array argument A. A is modified by
the routine but restored on exit.

LDA (input)

The leading dimension of the array A. If SIDE =
'L', $LDA \geq \max(1, M)$; if SIDE = 'R', $LDA \geq$
 $\max(1, N)$.

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by CGEQRF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**H}*C$ or $C*Q^{**H}$ or $C*Q$.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cunmr2 - overwrite the general complex m-by-n matrix C with $Q * C$ if SIDE = 'L' and TRANS = 'N', or $Q' * C$ if SIDE = 'L' and TRANS = 'C', or $C * Q$ if SIDE = 'R' and TRANS = 'N', or $C * Q'$ if SIDE = 'R' and TRANS = 'C',

SYNOPSIS

```
SUBROUTINE CUNMR2(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
                 INFO)
```

```
CHARACTER * 1 SIDE, TRANS
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER M, N, K, LDA, LDC, INFO
```

```
SUBROUTINE CUNMR2_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
                    INFO)
```

```
CHARACTER * 1 SIDE, TRANS
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER*8 M, N, K, LDA, LDC, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMR2(SIDE, TRANS, [M], [N], [K], A, [LDA], TAU, C, [LDC],
                [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A, C
INTEGER :: M, N, K, LDA, LDC, INFO
```

```
SUBROUTINE UNMR2_64(SIDE, TRANS, [M], [N], [K], A, [LDA], TAU, C,
                   [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS
COMPLEX, DIMENSION(:) :: TAU, WORK
COMPLEX, DIMENSION(:, :) :: A, C
INTEGER(8) :: M, N, K, LDA, LDC, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunmr2(char side, char trans, int m, int n, int k, complex *a, int lda, complex *tau, complex *c, int ldc, int *info);
```

```
void cunmr2_64(char side, char trans, long m, long n, long k, complex *a, long lda, complex *tau, complex *c, long ldc, long *info);
```

PURPOSE

cunmr2 overwrites the general complex m-by-n matrix C with

where Q is a complex unitary matrix defined as the product of k elementary reflectors

$$Q = H(1)' H(2)' \dots H(k)'$$

as returned by CGERQF. Q is of order m if SIDE = 'L' and of order n if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q' from the Left
 = 'R': apply Q or Q' from the Right

TRANS (input)

= 'N': apply Q (No transpose)
 = 'C': apply Q' (Conjugate transpose)

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product defines the matrix Q. If SIDE = 'L', M >= K >= 0; if SIDE = 'R', N >= K >= 0.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The i-th row must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGERQF in the last k rows of its array argument A. A is modified by the routine but restored on exit.

LDA (input)

The leading dimension of the array A. LDA >= max(1,K).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGERQF.

C (input/output)

On entry, the m-by-n matrix C. On exit, C is

overwritten by Q*C or Q'*C or C*Q' or C*Q.

LDC (input)

The leading dimension of the array C. LDC \geq
max(1,M).

WORK (workspace)

(N) if SIDE = 'L', (M) if SIDE = 'R'

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

cunmrq - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE CUNMRQ(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE CUNMRQ_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMRQ(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMRQ_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunmrq(char side, char trans, int m, int n, int k, com-
```

```

plex *a, int lda, complex *tau, complex *c, int
ldc, int *info);

void cunmrq_64(char side, char trans, long m, long n, long
k, complex *a, long lda, complex *tau, complex *c,
long ldc, long *info);

```

PURPOSE

cunmrq overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
of k elementary reflectors

$$Q = H(1)' H(2)' \dots H(k)'$$

as returned by CGERQF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
= 'R': apply Q or Q^{*H} from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Transpose, apply Q^{*H} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
if SIDE = 'R', $N \geq K \geq 0$.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
i-th row must contain the vector which defines the
elementary reflector H(i), for $i = 1, 2, \dots, k$, as
returned by CGERQF in the last k rows of its array
argument A. A is modified by the routine but
restored on exit.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, K)$.

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by CGERQF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**H}*C$ or $C*Q^{**H}$ or $C*Q$.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cunmrz - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE CUNMRZ(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, L, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE CUNMRZ_64(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, L, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE CUNMRZ(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER :: M, N, K, L, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE CUNMRZ_64(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:, :) :: A, C  
INTEGER(8) :: M, N, K, L, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunmrz(char side, char trans, int m, int n, int k, int
           l, complex *a, int lda, complex *tau, complex *c,
           int ldc, int *info);
```

```
void cunmrz_64(char side, char trans, long m, long n, long
              k, long l, complex *a, long lda, complex *tau,
              complex *c, long ldc, long *info);
```

PURPOSE

cunmrz overwrites the general complex M-by-N matrix C with
 TRANS = 'C': $Q^{*H} * C$ $C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
 of k elementary reflectors

$$Q = H(1) H(2) \dots H(k)$$

as returned by CTZRZF. Q is of order M if SIDE = 'L' and of
 order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
 = 'R': apply Q or Q^{*H} from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
 = 'C': Conjugate transpose, apply Q^{*H} .

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
 defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
 if SIDE = 'R', $N \geq K \geq 0$.

L (input) The number of columns of the matrix A containing
 the meaningful part of the Householder reflectors.
 If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L$
 ≥ 0 .

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
 i-th row must contain the vector which defines the
 elementary reflector H(i), for $i = 1, 2, \dots, k$, as
 returned by CTZRZF in the last k rows of its array
 argument A. A is modified by the routine but
 restored on exit.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $\max(1, K)$.

TAU (input)
 TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CTZRZF.

C (input/output)
 On entry, the M-by-N matrix C. On exit, C is overwritten by Q*C or Q**H*C or C*Q**H or C*Q.

LDC (input)
 The leading dimension of the array C. LDC >= max(1,M).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. If SIDE = 'L', LWORK >= max(1,N); if SIDE = 'R', LWORK >= max(1,M). For optimum performance LWORK >= N*NB if SIDE = 'L', and LWORK >= M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by
 A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

cunmtr - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE CUNMTR(SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE CUNMTR_64(SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMTR(SIDE, UPLO, [TRANS], [M], [N], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A, C  
INTEGER :: M, N, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMTR_64(SIDE, UPLO, [TRANS], [M], [N], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
COMPLEX, DIMENSION(:) :: TAU, WORK  
COMPLEX, DIMENSION(:,:) :: A, C  
INTEGER(8) :: M, N, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cunmtr(char side, char uplo, char trans, int m, int n,
```

```

        complex *a, int lda, complex *tau, complex *c, int
        ldc, int *info);

void cummtr_64(char side, char uplo, char trans, long m,
               long n, complex *a, long lda, complex *tau, com-
               plex *c, long ldc, long *info);

```

PURPOSE

cummtr overwrites the general complex M-by-N matrix C with
 TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix of order nq, with nq = m
 if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
 product of nq-1 elementary reflectors, as returned by
 CHETRD:

if UPLO = 'U', $Q = H(nq-1) \dots H(2) H(1)$;

if UPLO = 'L', $Q = H(1) H(2) \dots H(nq-1)$.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
 = 'R': apply Q or Q^{*H} from the Right.

UPLO (input)

= 'U': Upper triangle of A contains elementary
 reflectors from CHETRD; = 'L': Lower triangle of A
 contains elementary reflectors from CHETRD.

TRANS (input)

= 'N': No transpose, apply Q;
 = 'C': Conjugate transpose, apply Q^{*H} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

A (input) (LDA,M) if SIDE = 'L' (LDA,N) if SIDE = 'R' The
 vectors which define the elementary reflectors, as
 returned by CHETRD.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $\max(1,M)$ if SIDE = 'L'; $LDA \geq \max(1,N)$ if SIDE =
 'R'.

TAU (input)

(M-1) if SIDE = 'L' (N-1) if SIDE = 'R' TAU(i)
 must contain the scalar factor of the elementary
 reflector H(i), as returned by CHETRD.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or Q^*H^*C or C^*Q^*H or C^*Q .

LDC (input)
The leading dimension of the array C. $LDC \geq \max(1,M)$.

WORK (workspace)
On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. If $SIDE = 'L'$, $LWORK \geq \max(1,N)$; if $SIDE = 'R'$, $LWORK \geq \max(1,M)$. For optimum performance $LWORK \geq N*NB$ if $SIDE = 'L'$, and $LWORK \geq M*NB$ if $SIDE = 'R'$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

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NAME

cupgtr - generate a complex unitary matrix Q which is defined as the product of n-1 elementary reflectors H(i) of order n, as returned by CHPTRD using packed storage

SYNOPSIS

```
SUBROUTINE CUPGTR(UPLO, N, AP, TAU, Q, LDQ, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), TAU(*), Q(LDQ,*), WORK(*)  
INTEGER N, LDQ, INFO
```

```
SUBROUTINE CUPGTR_64(UPLO, N, AP, TAU, Q, LDQ, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
COMPLEX AP(*), TAU(*), Q(LDQ,*), WORK(*)  
INTEGER*8 N, LDQ, INFO
```

F95 INTERFACE

```
SUBROUTINE UPGTR(UPLO, [N], AP, TAU, Q, [LDQ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP, TAU, WORK  
COMPLEX, DIMENSION(:, :) :: Q  
INTEGER :: N, LDQ, INFO
```

```
SUBROUTINE UPGTR_64(UPLO, [N], AP, TAU, Q, [LDQ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX, DIMENSION(:) :: AP, TAU, WORK  
COMPLEX, DIMENSION(:, :) :: Q  
INTEGER(8) :: N, LDQ, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cupgtr(char uplo, int n, complex *ap, complex *tau,  
            complex *q, int ldq, int *info);
```

```
void cupgtr_64(char uplo, long n, complex *ap, complex *tau,
```

```
complex *q, long ldq, long *info);
```

PURPOSE

cupgtr generates a complex unitary matrix Q which is defined as the product of $n-1$ elementary reflectors $H(i)$ of order n , as returned by CHPTRD using packed storage:
if UPLO = 'U', $Q = H(n-1) \dots H(2) H(1)$,
if UPLO = 'L', $Q = H(1) H(2) \dots H(n-1)$.

ARGUMENTS

UPLO (input)
= 'U': Upper triangular packed storage used in previous call to CHPTRD; = 'L': Lower triangular packed storage used in previous call to CHPTRD.

N (input) The order of the matrix Q . $N \geq 0$.

AP (input)
The vectors which define the elementary reflectors, as returned by CHPTRD.

TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by CHPTRD.

Q (output)
The N -by- N unitary matrix Q .

LDQ (input)
The leading dimension of the array Q . $LDQ \geq \max(1, N)$.

WORK (workspace)
dimension($N-1$)

INFO (output)
= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

cupmtr - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE CUPMTR(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,  
INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
COMPLEX AP(*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, LDC, INFO
```

```
SUBROUTINE CUPMTR_64(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,  
INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
COMPLEX AP(*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, LDC, INFO
```

F95 INTERFACE

```
SUBROUTINE UPMTR(SIDE, UPLO, [TRANS], [M], [N], AP, TAU, C, [LDC],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
COMPLEX, DIMENSION(:) :: AP, TAU, WORK  
COMPLEX, DIMENSION(:,:) :: C  
INTEGER :: M, N, LDC, INFO
```

```
SUBROUTINE UPMTR_64(SIDE, UPLO, [TRANS], [M], [N], AP, TAU, C, [LDC],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
COMPLEX, DIMENSION(:) :: AP, TAU, WORK  
COMPLEX, DIMENSION(:,:) :: C  
INTEGER(8) :: M, N, LDC, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cupmtr(char side, char uplo, char trans, int m, int n,
```

```

        complex *ap, complex *tau, complex *c, int ldc,
        int *info);

void cupmtr_64(char side, char uplo, char trans, long m,
              long n, complex *ap, complex *tau, complex *c,
              long ldc, long *info);

```

PURPOSE

cupmtr overwrites the general complex M-by-N matrix C with
 TRANS = 'C': $Q^{*H} * C$ $C * Q^{*H}$

where Q is a complex unitary matrix of order nq, with nq = m
 if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
 product of nq-1 elementary reflectors, as returned by CHPTRD
 using packed storage:

if UPLO = 'U', $Q = H(nq-1) \dots H(2) H(1)$;

if UPLO = 'L', $Q = H(1) H(2) \dots H(nq-1)$.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
 = 'R': apply Q or Q^{*H} from the Right.

UPLO (input)

= 'U': Upper triangular packed storage used in
 previous call to CHPTRD; = 'L': Lower triangular
 packed storage used in previous call to CHPTRD.

TRANS (input)

= 'N': No transpose, apply Q;
 = 'C': Conjugate transpose, apply Q^{*H} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

AP (input)

$(M*(M+1)/2)$ if SIDE = 'L' $(N*(N+1)/2)$ if SIDE =
 'R' The vectors which define the elementary
 reflectors, as returned by CHPTRD. AP is modified
 by the routine but restored on exit.

TAU (input)

or (N-1) if SIDE = 'R' TAU(i) must contain the
 scalar factor of the elementary reflector H(i), as
 returned by CHPTRD.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is
 overwritten by $Q*C$ or $Q^{*H}*C$ or $C*Q^{*H}$ or $C*Q$.

LDC (input)
The leading dimension of the array C. LDC \geq
max(1,M).

WORK (workspace)
(N) if SIDE = 'L' (M) if SIDE = 'R'

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

cvbrmm - variable block sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE CVBRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,
*                 VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,
*                 B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LDB, LDC, LWORK
INTEGER          INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(KB+1),
*                 BPNTRB(MB), BPNTRE(MB)
COMPLEX         ALPHA, BETA
COMPLEX         VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE CVBRMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,
*                    VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,
*                    B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER*8       TRANSA, MB, N, KB, DESCRA(5), LDB, LDC, LWORK
INTEGER*8       INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(KB+1),
*               BPNTRB(MB), BPNTRE(MB)
COMPLEX         ALPHA, BETA
COMPLEX         VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE VBRMM(TRANSA, MB, [N], KB, ALPHA, DESCRA,
*               VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,
*               B, [LDB], BETA, C,[LDC], [WORK], [LWORK])
INTEGER        TRANSA, MB, KB
INTEGER, DIMENSION(:) :: DESCRA, INDX, BINDX
INTEGER, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE
COMPLEX        ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL
COMPLEX, DIMENSION(:,:) :: B, C

SUBROUTINE VBRMM_64(TRANSA, MB, [N], KB, ALPHA, DESCRA,
*                   VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,
*                   B, [LDB], BETA, C,[LDC], [WORK], [LWORK])
INTEGER*8      TRANSA, MB, KB
```


DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, scalar array VAL of length NNZ consists of the block entries of A where each block entry is a dense rectangular matrix stored column by column where NNZ denotes the total number of point entries in all nonzero block entries of a matrix A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length BNNZ+1 where BNNZ is the number of block entries of the matrix A such that the I-th element of INDX[] points to the location in VAL of the (1,1) element of the I-th block entry. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ is the number block entries of the matrix A. Unchanged on exit.

RPNTR(input) On entry, RPNTR is an integer array of length MB+1 such that RPNTR(I)-RPNTR(1)+1 is the row index of the first point row in the I-th block row. RPNTR(MB+1) is set to M+RPNTR(1) where M is the number of rows in the matrix A. Thus, the number of point rows in the I-th block row is RPNTR(I+1)-RPNTR(I). Unchanged on exit.

CPNTR(input) On entry, CPNTR is an integer array of length KB+1 such that CPNTR(J)-CPNTR(1)+1 is the column index of the first point column in the J-th block column. CPNTR(KB+1) is set to K+CPNTR(1) where K is the number of columns in the matrix A. Thus, the number of point columns in the J-th block column is CPNTR(J+1)-CPNTR(J). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(I)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the I-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(I)-BPNTRB(1) points to location in BINDX of the last block entry of the I-th block row of A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise
 the leading k by n part of the array C must contain the
 matrix C. On exit, the array C is overwritten by the matrix
 (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible
 with NIST FORTRAN Sparse Blas but the sources are different.
 Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN
 Sparse Blas. Besides several new features and routines are
 implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS)
 Standard", University of Tennessee, Knoxville, Tennessee,
 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to
 use just one sparse matrix representation of a general
 complex matrix A for computing matrix-matrix multiply for
 another sparse matrix composed by block triangles and/or
 the main block diagonal of A. The full description of the
 feature for block entry formats is given in section
 NOTES/BUGS for the cbcomm manpage.

NOTES/BUGS

1. For a general matrix (DESCRA(1)=0), array CPNTR can be
 different from RPNTR. For all other matrix types, RPNTR
 must equal CPNTR and a single array can be passed for both
 arguments.

2. It is known that there exists another representation of the variable block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of six array instead of the seven used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the array BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of variable block sparse row format the following calling sequence should be used

```
      SUBROUTINE SVBRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                      VAL, INDX, BINDX, RPNTR, CPNTR, IA, IA(2),  
*                      B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

cvbrsm - variable block sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE CVBRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LDB, LDC, LWORK  
INTEGER          INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(MB+1),  
*                BPNTRB(MB), BPNTRE(MB)  
COMPLEX          ALPHA, BETA  
COMPLEX          DV(*), VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE CVBRSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LDB, LDC, LWORK  
INTEGER*8        INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(MB+1),  
*                BPNTRB(MB), BPNTRE(MB)  
COMPLEX          ALPHA, BETA  
COMPLEX          DV(*), VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE VBRSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, UNITD  
INTEGER, DIMENSION(:) :: DESCRA, INDX, BINDX  
INTEGER, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE  
COMPLEX          ALPHA, BETA  
COMPLEX, DIMENSION(:) :: VAL, DV  
COMPLEX, DIMENSION(:, :) :: B, C  
  
SUBROUTINE VBRSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, UNITD  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, BINDX
```

```

INTEGER*8, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE
COMPLEX ALPHA, BETA
COMPLEX, DIMENSION(:) :: VAL, DV
COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```
#include <sunperf.h>
```

```

void cvbrsm (int transa, int mb, int n, int unitd, complex
*dv, complex *alpha, int *descra, complex *val, int *indx,
int *bindx, int *rpntr, int *cpntr, int *bpntrb, int
*bpntre, complex *b, int ldb, complex *beta, complex *c, int
ldc);

```

```

void cvbrsm_64 (long transa, long mb, long n, long unitd,
complex *dv, complex *alpha, long *descra, complex *val,
long *indx, long *bindx, long *rpntr, long *cpntr, long
*bpntrb, long *bpntre, complex *b, long ldb, complex *beta,
complex *c, long ldc);

```

DESCRIPTION

cvbrsm performs one of the matrix-matrix operations

```

C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,

```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a block diagonal matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the variable block sparse row format and op(A) is one of

```

op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).

```

The number of rows in A is determined as follows

```
m=RPNTR(MB+1)-RPNTR(1).
```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, integer MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.
DV(input)	On entry, array DV contains the block entries of the block diagonal matrix D. The size of the J-th block is

RPNTR(J+1)-RPNTR(J) and each block contains matrix entries stored column-major. The total length of array DV is given by the formula:

$$\text{sum over J from 1 to MB:} \\ ((\text{RPNTR}(J+1)-\text{RPNTR}(J)) * (\text{RPNTR}(J+1)-\text{RPNTR}(J)))$$

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-identity blocks on the main diagonal
1 : identity diagonal blocks
2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, scalar array VAL of length NNZ consists of the block entries of A where each block entry is a dense rectangular matrix stored column by column where NNZ denotes the total number of point entries in all nonzero block entries of the matrix A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length BNNZ+1 where BNNZ is the number of block entries of the matrix A such that the I-th element of INDX[] points to the location in VAL of the (1,1) element of the I-th block entry. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ is the number block entries of the matrix A. Block column indices MUST be sorted in increasing order for each block row. Unchanged on exit.

RPNTR(input) On entry, RPNTR is an integer array of length MB+1 such that RPNTR(I)-RPNTR(1)+1 is the row index of the first point row in the I-th block row. RPNTR(MB+1) is set to M+RPNTR(1) where M is the number of rows in the matrix A. Thus, the number of point rows in the I-th block row is RPNTR(I+1)-RPNTR(I). Unchanged on exit.
NOTE: For the current version CPNTR must equal RPNTR and a single array can be passed for both arguments

CPNTR(input) On entry, CPNTR is integer array of length KB+1 such that CPNTR(J)-CPNTR(1)+1 is the column index of the first point column in the J-th block column. CPNTR(KB+1) is set to K+CPNTR(1) where K is the number of columns in the matrix A. Thus, the number of point columns in the J-th block column is CPNTR(J+1)-CPNTR(J). Unchanged on exit.

NOTE: For the current version CPNTR must equal RPNTR and a single array can be passed for both arguments

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(I)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the I-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(I)-BPNTRB(1) points to location in BINDX of the last block entry of the I-th block row of A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \beta * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK. On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least $M = \text{RPNTR}(\text{MB}+1) - \text{RPNTR}(1)$. For good performance, LWORK should generally be larger. For optimum performance on multiple processors, $LWORK \geq M * N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If `DESCRA(3)=0` , the lower or upper triangular part of each diagonal block is used by the routine depending on `DESCRA(2)`.
3. If `DESCRA(3)=1` , the diagonal blocks in the variable block row representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If `DESCRA(3)=2` , diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.
5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

6. It is known that there exists another representation of the variable block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of six array instead of the seven used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the array BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of variable block sparse row format the following calling sequence should be used

```

SUBROUTINE CVBRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, BINDX, RPNTR, CPNTR, IA, IA(2),
*                 B, LDB, BETA, C, LDC, WORK, LWORK )

```

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NAME

cvmul - compute the scaled product of complex vectors

SYNOPSIS

```
SUBROUTINE CVMUL(N, ALPHA, X, INCX, Y, INCY, BETA, Z, INCZ)
```

```
COMPLEX ALPHA, BETA  
COMPLEX X(*), Y(*), Z(*)  
INTEGER N, INCX, INCY, INCZ
```

```
SUBROUTINE CVMUL_64(N, ALPHA, X, INCX, Y, INCY, BETA, Z, INCZ)
```

```
COMPLEX ALPHA, BETA  
COMPLEX X(*), Y(*), Z(*)  
INTEGER*8 N, INCX, INCY, INCZ
```

F95 INTERFACE

```
SUBROUTINE VMUL([N], ALPHA, X, [INCX], Y, [INCY], BETA, Z, [INCZ])
```

```
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: X, Y, Z  
INTEGER :: N, INCX, INCY, INCZ
```

```
SUBROUTINE VMUL_64([N], ALPHA, X, [INCX], Y, [INCY], BETA, Z, [INCZ])
```

```
COMPLEX :: ALPHA, BETA  
COMPLEX, DIMENSION(:) :: X, Y, Z  
INTEGER(8) :: N, INCX, INCY, INCZ
```

C INTERFACE

```
#include <sunperf.h>
```

```
void cvmul(int n, complex *alpha, complex *x, int incx, complex *y, int incy, complex *beta, complex *z, int incz);
```

```
void cvmul_64(long n, complex *alpha, complex *x, long incx, complex *y, long incy, complex *beta, complex *z, long incz);
```

PURPOSE

cvmul computes the scaled product of complex vectors:
$$z(i) = \text{ALPHA} * x(i) * y(i) + \text{BETA} * z(i)$$
for $1 \leq i \leq N$.

ARGUMENTS

N (input)
Length of the vectors. $N \geq 0$. Returns immediately if $N = 0$.

ALPHA (input)
Scale factor on the multiplicand vectors.

X (input) dimension(*)
Multiplicand vector.

INCX (input)
Stride between elements of the multiplicand vector X.

Y (input) dimension(*)
Multiplicand vector.

INCY (input)
Stride between elements of the multiplicand vector Y.

BETA (input)
Scale factor on the product vector.

Z (input/output) dimension(*)
Product vector. On exit, $z(i) = \text{ALPHA} * x(i) * y(i) + \text{BETA} * z(i)$.

INCZ (input)
Stride between elements of Z.

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NAME

dasum - Return the sum of the absolute values of a vector x.

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DASUM(N, X, INCX)

INTEGER N, INCX
DOUBLE PRECISION X(*)

DOUBLE PRECISION FUNCTION DASUM_64(N, X, INCX)

INTEGER*8 N, INCX
DOUBLE PRECISION X(*)
```

F95 INTERFACE

```
REAL(8) FUNCTION ASUM([N], X, [INCX])

INTEGER :: N, INCX
REAL(8), DIMENSION(:) :: X

REAL(8) FUNCTION ASUM_64([N], X, [INCX])

INTEGER(8) :: N, INCX
REAL(8), DIMENSION(:) :: X
```

C INTERFACE

```
#include <sunperf.h>

double dasum(int n, double *x, int incx);

double dasum_64(long n, double *x, long incx);
```

PURPOSE

dasum Return the sum of the absolute values of x where x is an n-vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero or negative. Unchanged on exit.

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NAME

daxpy - compute $y := \alpha * x + y$

SYNOPSIS

```
SUBROUTINE DAXPY(N, ALPHA, X, INCX, Y, INCY)
```

```
INTEGER N, INCX, INCY  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), Y(*)
```

```
SUBROUTINE DAXPY_64(N, ALPHA, X, INCX, Y, INCY)
```

```
INTEGER*8 N, INCX, INCY  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE AXPY([N], ALPHA, X, [INCX], Y, [INCY])
```

```
INTEGER :: N, INCX, INCY  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X, Y
```

```
SUBROUTINE AXPY_64([N], ALPHA, X, [INCX], Y, [INCY])
```

```
INTEGER(8) :: N, INCX, INCY  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void daxpy(int n, double alpha, double *x, int incx, double  
          *y, int incy);
```

```
void daxpy_64(long n, double alpha, double *x, long incx,  
             double *y, long incy);
```

PURPOSE

daxpy compute $y := \alpha * x + y$ where alpha is a scalar and x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input/output)

($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

daxpyi - Compute $y := \alpha * x + y$

SYNOPSIS

```
SUBROUTINE DAXPYI(NZ, A, X, INDX, Y)
```

```
DOUBLE PRECISION A  
DOUBLE PRECISION X(*), Y(*)  
INTEGER NZ  
INTEGER INDX(*)
```

```
SUBROUTINE DAXPYI_64(NZ, A, X, INDX, Y)
```

```
DOUBLE PRECISION A  
DOUBLE PRECISION X(*), Y(*)  
INTEGER*8 NZ  
INTEGER*8 INDX(*)
```

```
F95 INTERFACE
```

```
SUBROUTINE AXPYI([NZ], [A], X, INDX, Y)
```

```
REAL(8) :: A  
REAL(8), DIMENSION(:) :: X, Y  
INTEGER :: NZ  
INTEGER, DIMENSION(:) :: INDX
```

```
SUBROUTINE AXPYI_64([NZ], [A], X, INDX, Y)
```

```
REAL(8) :: A  
REAL(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: NZ  
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

DAXPYI Compute $y := \alpha * x + y$ where α is a scalar, x is a sparse vector, and y is a vector in full storage form

```
do i = 1, n  
  y(indx(i)) = alpha * x(i) + y(indx(i))
```

enddo

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.

Unchanged on exit.

A (input)

On entry, A(LPHA) specifies the scaling value.

Unchanged on exit. A is defaulted to 1.0D0 for F95
INTERFACE.

X (input)

Vector containing the values of the compressed form.

Unchanged on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

Y (output)

Vector on input which contains the vector Y in full
storage form. On exit, only the elements
corresponding to the indices in INDX have been
modified.

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NAME

dbcomm - block coordinate matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DBCOMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
* VAL, BINDX, BJNDX, BNNZ, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER TRANSA, MB, N, KB, DESCRA(5), BNNZ, LB,  
* LDB, LDC, LWORK  
INTEGER BINDX(BNNZ), BJNDX(BNNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DBCOMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
* VAL, BINDX, BJNDX, BNNZ, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8 TRANSA, MB, N, KB, DESCRA(5), BNNZ, LB,  
* LDB, LDC, LWORK  
INTEGER*8 BINDX(BNNZ), BJNDX(BNNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BCOMM(TRANSA,MB,[N],KB,ALPHA,DESCRA,VAL,BINDX, BJNDX,  
* BNNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER TRANSA, MB, N, KB, BNNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BJNDX  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BCOMM_64(TRANSA,MB,[N],KB,ALPHA,DESCRA,VAL,BINDX, BJNDX,  
* BNNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, MB, N, KB, BNNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BJNDX  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void dbcomm (int transa, int mb, int n, int kb, double
alpha, int* descra, double *val, int *bindx, int *bjndx, int
bnnz, int lb, double *b, int ldb, double beta, double *c,
int ldc);
void dbcomm_64(long transa, long mb, long n, long kb, double
alpha, long *descra, double *val, long *b indx, long *bjndx,
long bnnz, long lb, double *b, long ldb,
double beta, double *c, long ldc);
```

DESCRIPTION

dbcomm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an (mb*lb) by (kb*lb) sparse matrix represented in the block coordinate format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, integer MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, integer KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')

```

5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array of length
                 LB*LB*BNNZ consisting of the non-zero block
                 entries of A, in any order. Each block
                 is stored in standard column-major form.
                 Unchanged on exit.

BINDX(input)    On entry, BINDX is an integer array of length BNNZ
                 consisting of the block row indices of the non-zero
                 block entries of A. Unchanged on exit.

BJNDX(input)    On entry, BJNDX is an integer array of length BNNZ
                 consisting of the block column indices of the non-zero
                 block entries of A. Unchanged on exit.

BNNZ (input)    On entry, integer BNNZ specifies the number of nonzero
                 block entries in A. Unchanged on exit.

LB (input)      On entry, integer LB specifies the dimension of dense
                 blocks composing A. Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading kb*lb by n
                 part of the array B must contain the matrix B, otherwise
                 the leading mb*lb by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading mb*lb by n
                 part of the array C must contain the matrix C, otherwise
                 the leading kb*lb by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta * C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the sbcomm manpage.

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NAME

dbdim - block diagonal format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DBDIMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), BLDA, NBDIAG, LB,  
*                LDB, LDC, LWORK  
INTEGER          IBDIAG(NBDIAG)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BLDA*NBDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DBDIMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), BLDA, NBDIAG, LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        IBDIAG(NBDIAG)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BLDA*NBDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BDIMM(TRANSA,MB, [N], KB, ALPHA, DESCRA, VAL, BLDA,  
*  IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, BLDA, NBDIAG, LB  
INTEGER, DIMENSION(:) ::  DESCRA, IBDIAG  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BDIMM_64(TRANSA,MB, [N], KB, ALPHA, DESCRA, VAL, BLDA,  
*  IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, BLDA, NBDIAG, LB  
INTEGER*8, DIMENSION(:) ::  DESCRA, IBDIAG  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void dbdimm (int transa, int mb, int n, int kb, double
alpha,
  int *descra, double *val, int blda, int *ibdiag, int
nbdia, int lb, double *b, int ldb, double beta, double *c,
int ldc);
void dbdimm_64(long transa, long mb, long n, long kb,
double alpha, long *descra, double *val, long blda,
long *ibdiag, long nbdia, long lb, double *b, long ldb,
double beta, double *c, long ldc)
```

DESCRIPTION

dbdimm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an (mb*lb) by (kb*lb) sparse matrix represented in the block diagonal format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, two-dimensional LB*LB*BLDA-by-NBDIAG scalar array consisting of the NBDIAG nonzero block diagonal in any order. Each dense block is stored in standard column-major form. Unchanged on exit.

BLDA(input) On entry, BLDA*LB*LB specifies the leading block dimension of VAL(). Unchanged on exit.

IBDIAG(input) On entry, integer array of length NBDIAG consisting of the corresponding diagonal offsets of the non-zero block diagonals of A in VAL. Lower triangular block diagonals have negative offsets, the main block diagonal has offset 0, and upper triangular block diagonals have positive offset. Unchanged on exit.

NBDIAG(input) On entry, NBDIAG specifies the number of non-zero block diagonals in A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta * C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the sbcomm manpage.

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NAME

dbdism - block diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE DBDISM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), BLDA, NBDIAG, LB,  
*                LDB, LDC, LWORK  
INTEGER          IBDIAG(NBDIAG)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(MB*LB*LB), VAL(LB*LB*BLDA, NBDIAG), B(LDB,*), C(LDC,*),  
*                WORK(LWORK)
```

```
SUBROUTINE DBDISM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), BLDA, NBDIAG, LB,  
*               LDB, LDC, LWORK  
INTEGER*8        IBDIAG(NBDIAG)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(MB*LB*LB), VAL(LB*LB*BLDA, NBDIAG), B(LDB,*), C(LDC,*),  
*               WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BDISM( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BLDA,  
* IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, N, UNITD, BLDA, NBDIAG, LB  
INTEGER, DIMENSION(:) :: DESCRA, IBDIAG  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BDISM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BLDA,  
* IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, N, UNITD, BLDA, NBDIAG, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, IBDIAG  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dbdism(int transa, int mb, int n, int unitd, double
*dv, double alpha, int *descra, double *val, int blda, int
*ibdiag, int nbdiag, int lb, double *b, int ldb, double
beta, double *c, int ldc);
void dbdism_64(long transa, long mb, long n, long unitd,
double *dv, double alpha, long *descra, double *val, long
blda, long *ibdiag, long nbdiag, long lb, double *b, long
ldb, double beta, double *c, long ldc);
```

DESCRIPTION

dbdism performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose)
```

ARGUMENTS

TRANSA(input) TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-NBDIAG array consisting of the NBDIAG non-zero block diagonal. Each dense block is stored in standard column-major form. Unchanged on exit.

BLDA(input) On entry, BLDA*LB*LB specifies the leading block dimension of VAL(). Unchanged on exit.

IBDIAG(input) On entry, IBDIAG is an integer array of length NBDIAG consisting of corresponding diagonal offsets of the non-zero block diagonals of A in VAL. Lower triangular block diagonals have negative offsets, the main block diagonal has offset 0, and upper triangular block diagonals have positive offset. Elements of IBDIAG MUST be sorted in increasing order. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block diagonal representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If *DESCRA*(3)=2 , diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine.

WORK(1)=0 on return if the factorization for all diagonal

blocks has been completed successfully, otherwise *WORK*(1) =
- i where i is the block number for which the LU
factorization could not be computed.

5. The routine is designed so that it checks the validity of
each sparse block entry given in the sparse blas
representation. Block entries with incorrect indices are not
used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse
matrix representation of a general matrix A for solving
triangular systems with the upper or lower block triangle of
A. But *DESCRA*(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a
general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the
strictly block upper triangle of A, D is the block diagonal
matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of
DESCRA and the result matrix for the sparse representation
of A is

<i>DESCRA</i> (1)	<i>DESCRA</i> (2)	<i>DESCRA</i> (3)	RESULT
3	1	1	alpha*op(L+I)*B+beta*C
3	1	0	alpha*op(L+D)*B+beta*C
3	2	1	alpha*op(U+I)*B+beta*C
3	2	0	alpha*op(U+D)*B+beta*C

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NAME

dbdsdc - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B

SYNOPSIS

```
SUBROUTINE DBSDC(UPLO, COMPQ, N, D, E, U, LDU, VT, LDVT, Q, IQ,  
                WORK, IWORK, INFO)
```

```
CHARACTER * 1 UPLO, COMPQ  
INTEGER N, LDU, LDVT, INFO  
INTEGER IQ(*), IWORK(*)  
DOUBLE PRECISION D(*), E(*), U(LDU,*), VT(LDVT,*), Q(*),  
WORK(*)
```

```
SUBROUTINE DBSDC_64(UPLO, COMPQ, N, D, E, U, LDU, VT, LDVT, Q, IQ,  
                   WORK, IWORK, INFO)
```

```
CHARACTER * 1 UPLO, COMPQ  
INTEGER*8 N, LDU, LDVT, INFO  
INTEGER*8 IQ(*), IWORK(*)  
DOUBLE PRECISION D(*), E(*), U(LDU,*), VT(LDVT,*), Q(*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE BDSDC(UPLO, COMPQ, [N], D, E, U, [LDU], VT, [LDVT], Q, IQ,  
                [WORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, COMPQ  
INTEGER :: N, LDU, LDVT, INFO  
INTEGER, DIMENSION(:) :: IQ, IWORK  
REAL(8), DIMENSION(:) :: D, E, Q, WORK  
REAL(8), DIMENSION(:, :) :: U, VT
```

```
SUBROUTINE BDSDC_64(UPLO, COMPQ, [N], D, E, U, [LDU], VT, [LDVT], Q,  
                   IQ, [WORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, COMPQ  
INTEGER(8) :: N, LDU, LDVT, INFO
```

```
INTEGER(8), DIMENSION(:) :: IQ, IWORK
REAL(8), DIMENSION(:) :: D, E, Q, WORK
REAL(8), DIMENSION(:, :) :: U, VT
```

C INTERFACE

```
#include <sunperf.h>

void dbdsdc(char uplo, char compq, int n, double *d, double
            *e, double *u, int ldu, double *vt, int ldvt,
            double *q, int *iq, int *info);

void dbdsdc_64(char uplo, char compq, long n, double *d,
              double *e, double *u, long ldu, double *vt, long
              ldvt, double *q, long *iq, long *info);
```

PURPOSE

dbdsdc computes the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B: $B = U * S * VT$, using a divide and conquer method, where S is a diagonal matrix with non-negative diagonal elements (the singular values of B), and U and VT are orthogonal matrices of left and right singular vectors, respectively. DBDSDC can be used to compute all singular values, and optionally, singular vectors or singular vectors in compact form.

This code makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none. See SLASD3 for details.

The code currently call SLASDQ if singular values only are desired. However, it can be slightly modified to compute singular values using the divide and conquer method.

ARGUMENTS

UPLO (input)
= 'U': B is upper bidiagonal.
= 'L': B is lower bidiagonal.

COMPQ (input)
Specifies whether singular vectors are to be computed as follows:
= 'N': Compute singular values only;
= 'P': Compute singular values and compute singular vectors in compact form; = 'I': Compute singular values and singular vectors.

N (input) The order of the matrix B. $N \geq 0$.

D (input/output)
On entry, the n diagonal elements of the bidiagonal

nal matrix B. On exit, if INFO=0, the singular values of B.

E (input/output)

On entry, the elements of E contain the offdiagonal elements of the bidiagonal matrix whose SVD is desired. On exit, E has been destroyed.

U (output)

If COMPQ = 'I', then: On exit, if INFO = 0, U contains the left singular vectors of the bidiagonal matrix. For other values of COMPQ, U is not referenced.

LDU (input)

The leading dimension of the array U. LDU \geq 1. If singular vectors are desired, then LDU \geq max(1, N).

VT (output)

If COMPQ = 'I', then: On exit, if INFO = 0, VT contains the right singular vectors of the bidiagonal matrix. For other values of COMPQ, VT is not referenced.

LDVT (input)

The leading dimension of the array VT. LDVT \geq 1. If singular vectors are desired, then LDVT \geq max(1, N).

Q (input) If COMPQ = 'P', then: On exit, if INFO = 0, Q and IQ contain the left and right singular vectors in a compact form, requiring $O(N \log N)$ space instead of $2*N**2$. In particular, Q contains all the REAL data in LDQ \geq $N*(11 + 2*SMLSIZ + 8*INT(LOG_2(N/(SMLSIZ+1))))$ words of memory, where SMLSIZ is returned by ILAENV and is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25). For other values of COMPQ, Q is not referenced.

IQ (output)

If COMPQ = 'P', then: On exit, if INFO = 0, Q and IQ contain the left and right singular vectors in a compact form, requiring $O(N \log N)$ space instead of $2*N**2$. In particular, IQ contains all INTEGER data in LDIQ \geq $N*(3 + 3*INT(LOG_2(N/(SMLSIZ+1))))$ words of memory, where SMLSIZ is returned by ILAENV and is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25). For other values of COMPQ, IQ is not referenced.

WORK (workspace)

If COMPQ = 'N' then LWORK \geq (2 * N). If COMPQ = 'P' then LWORK \geq (6 * N). If COMPQ = 'I' then LWORK \geq (3 * N**2 + 4 * N).

IWORK (workspace)

dimension(8*N)

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: The algorithm failed to compute an singular value. The update process of divide and conquer failed.

FURTHER DETAILS

Based on contributions by

Ming Gu and Huan Ren, Computer Science Division, University of
California at Berkeley, USA

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NAME

dbdsqr - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B.

SYNOPSIS

```
SUBROUTINE DBDSQR(UPLO, N, NCVT, NRU, NCC, D, E, VT, LDVT, U, LDU, C,
                 LDC, WORK, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
DOUBLE PRECISION D(*), E(*), VT(LDVT,*), U(LDU,*), C(LDC,*),
WORK(*)
```

```
SUBROUTINE DBDSQR_64(UPLO, N, NCVT, NRU, NCC, D, E, VT, LDVT, U, LDU,
                    C, LDC, WORK, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER*8 N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
DOUBLE PRECISION D(*), E(*), VT(LDVT,*), U(LDU,*), C(LDC,*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE BDSQR(UPLO, [N], [NCVT], [NRU], [NCC], D, E, VT, [LDVT],
                U, [LDU], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER :: N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL(8), DIMENSION(:) :: D, E, WORK
REAL(8), DIMENSION(:,:) :: VT, U, C
```

```
SUBROUTINE BDSQR_64(UPLO, [N], [NCVT], [NRU], [NCC], D, E, VT, [LDVT],
                   U, [LDU], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER(8) :: N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL(8), DIMENSION(:) :: D, E, WORK
REAL(8), DIMENSION(:,:) :: VT, U, C
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dbdsqr(char uplo, int n, int ncv, int nru, int ncc,
            double *d, double *e, double *vt, int ldvt, double
            *u, int ldu, double *c, int ldc, int *info);

void dbdsqr_64(char uplo, long n, long ncv, long nru, long
               ncc, double *d, double *e, double *vt, long ldvt,
               double *u, long ldu, double *c, long ldc, long
               *info);

```

PURPOSE

dbdsqr computes the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B: $B = Q * S * P'$ (P' denotes the transpose of P), where S is a diagonal matrix with non-negative diagonal elements (the singular values of B), and Q and P are orthogonal matrices.

The routine computes S, and optionally computes $U * Q$, $P' * VT$, or $Q' * C$, for given real input matrices U, VT, and C.

See "Computing Small Singular Values of Bidiagonal Matrices With Guaranteed High Relative Accuracy," by J. Demmel and W. Kahan, LAPACK Working Note #3 (or SIAM J. Sci. Statist. Comput. vol. 11, no. 5, pp. 873-912, Sept 1990) and "Accurate singular values and differential qd algorithms," by B. Parlett and V. Fernando, Technical Report CPAM-554, Mathematics Department, University of California at Berkeley, July 1992 for a detailed description of the algorithm.

ARGUMENTS

UPLO (input)
 = 'U': B is upper bidiagonal;
 = 'L': B is lower bidiagonal.

N (input) The order of the matrix B. $N \geq 0$.

NCVT (input)
 The number of columns of the matrix VT. $NCVT \geq 0$.

NRU (input)
 The number of rows of the matrix U. $NRU \geq 0$.

NCC (input)
 The number of columns of the matrix C. $NCC \geq 0$.

D (input/output)
 On entry, the n diagonal elements of the bidiagonal matrix B. On exit, if INFO=0, the singular values of B in decreasing order.

E (input/output)
 On entry, the elements of E contain the offdiagonal elements of the bidiagonal matrix whose SVD is desired. On normal exit (INFO = 0), E is destroyed. If the algorithm does not converge (INFO

> 0), D and E will contain the diagonal and super-diagonal elements of a bidiagonal matrix orthogonally equivalent to the one given as input. E(N) is used for workspace.

VT (input/output)

On entry, an N-by-NCVT matrix VT. On exit, VT is overwritten by $P' * VT$. VT is not referenced if NCVT = 0.

LDVT (input)

The leading dimension of the array VT. LDVT \geq max(1,N) if NCVT > 0; LDVT \geq 1 if NCVT = 0.

U (input/output)

On entry, an NRU-by-N matrix U. On exit, U is overwritten by $U * Q$. U is not referenced if NRU = 0.

LDU (input)

The leading dimension of the array U. LDU \geq max(1,NRU).

C (input/output)

On entry, an N-by-NCC matrix C. On exit, C is overwritten by $Q' * C$. C is not referenced if NCC = 0.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,N) if NCC > 0; LDC \geq 1 if NCC = 0.

WORK (workspace)

dimension(4*N)

INFO (output)

= 0: successful exit
< 0: If INFO = -i, the i-th argument had an illegal value
> 0: the algorithm did not converge; D and E contain the elements of a bidiagonal matrix which is orthogonally similar to the input matrix B; if INFO = i, i elements of E have not converged to zero.

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NAME

dbelmm - block Ellpack format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DBELMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BLDA, MAXBNZ, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), BLDA, MAXBNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BLDA,MAXBNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DBELMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BLDA, MAXBNZ, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), BLDA, MAXBNZ, LB,  
*               LDB, LDC, LWORK  
INTEGER*8        BINDX(BLDA,MAXBNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BELMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*               BLDA, MAXBNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, KB, BLDA, MAXBNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BELMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BLDA, MAXBNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, KB, BLDA, MAXBNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void dbelmm (int transa, int mb, int n, int kb,
             double alpha, int *descra, double *val,
             int *bindx, int blda, int maxbnz, int lb, double *b, int
             ldb, double beta, double *c, int ldc);
void dbelmm_64(long transa, long mb, long n, long kb, double
alpha, long *descra, double *val, long *bindx, long blda,
long maxbnz, long lb, double *b, long ldb, double beta,
double *c, long ldc);
```

DESCRIPTION

dbelmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in the block Ellpack format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input) TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator

1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-MAXBNZ array consisting of the non-zero blocks, stored column-major within each dense block. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer two-dimensional BLDA-MAXBNZ array such BINDX(i,:) consists of the block column indices of the nonzero blocks in block row i, padded by the integer value i if the number of nonzero blocks is less than MAXBNZ. Unchanged on exit.

BLDA(input) On entry, BLDA specifies the leading dimension of BINDX(:,:). Unchanged on exit.

MAXBNZ (input) On entry, NBDIAG specifies the max number of nonzeros blocks per row. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta * C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the sbcomm manpage.

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NAME

dbelsm - block Ellpack format triangular solve

SYNOPSIS

```
SUBROUTINE DBELSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BLDA, MAXBNZ, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), BLDA, MAXBNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BLDA,MAXBNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(MB*LB*LB), VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*),  
*                WORK(LWORK)
```

```
SUBROUTINE DBELSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BLDA, MAXBNZ, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), BLDA, MAXBNZ, LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BLDA,MAXBNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(MB*LB*LB), VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*),  
*                   WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BELSM( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*               BLDA, MAXBNZ, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, UNITD, BLDA, MAXBNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BELSM_64( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                   BLDA, MAXBNZ, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, UNITD, BLDA, MAXBNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dbelsm (int transa, int mb, int n, int unitd,
double *dv, double alpha, int *descra, double *val,
int *bindx, int blda, int maxbnz, int lb, double *b, int
ldb, double beta, double *c, int ldc);
void dbelsm_64(long transa, long mb, long n, long unitd,
double *dv, double alpha, long *descra, double *val, long
*bindx, long blda, long maxbnz, long lb, double *b, long
ldb, double beta, double *c, long ldc);
```

DESCRIPTION

dbelsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block ellpack format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose)
```

ARGUMENTS

TRANSA(input) Integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-MAXBNZ array consisting of the non-zero blocks, stored column-major within each dense block. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer two-dimensional BLDA-MAXBNZ array such BINDX(i,:) consists of the block column indices of the nonzero blocks in block row i, padded by the integer value i if the number of nonzero blocks is less than MAXBNZ. The block column indices MUST be sorted in increasing order for each block row. Unchanged on exit.

BLDA(input) On entry, BLDA specifies the leading dimension of BINDX(:,:). Unchanged on exit.

MAXBNZ (input) On entry, MAXBNZ specifies the max number of nonzeros blocks per row. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0, the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2).
3. If *DESCRA*(3)=1, the diagonal blocks in the block ellpack representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If *DESCRA*(3)=2, diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine.

WORK(1)=0 on return if the factorization for all diagonal blocks has been completed successfully, otherwise *WORK*(1) = - i where i is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But *DESCRA*(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of *DESCRA* and the result matrix for the sparse representation of A is

<i>DESCRA</i> (1)	<i>DESCRA</i> (2)	<i>DESCRA</i> (3)	RESULT
3	1	1	alpha*op(L+I)*B+beta*C
3	1	0	alpha*op(L+D)*B+beta*C
3	2	1	alpha*op(U+I)*B+beta*C
3	2	0	alpha*op(U+D)*B+beta*C

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NAME

dbscmm - block sparse column matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DBSCMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(KB), BPNTRE(KB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DBSCMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(KB), BPNTRE(KB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(KB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSCMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*               BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSCMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dbscmm(int transa, int mb, int n, int kb,
double alpha, int *descra, double *val,
int *bindx, int *bpntrb, int *bpntre, int lb, double *b,
int ldb, double beta, double *c, int ldc);
void dbscmm_64(long transa, long mb, long n, long kb,
double alpha, long *descra, double *val, long *bindx, long
*bpntrb, long *bpntre, long lb, double *b, long ldb, double
beta, double *c, long ldc);
```

DESCRIPTION

dbscmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in block sparse column format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input) TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows:
 0 : operate with matrix
 1 : operate with transpose matrix
 2 : operate with the conjugate transpose of matrix.
 2 is equivalent to 1 if matrix is real.
 Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ consisting of the non-zero block entries stored column-major within each dense block where BNNZ = BPNTRE(KB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block row indices of the block entries of A where BNNZ = BPNTRE(KB)-BPNTRB(1). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length KB such that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the J-th block column of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length KB such that BPNTRE(J)-BPNTRB(1) points to location in BINDX of the last block entry of the J-th block column of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta * C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the sbcomm manpage.

NOTES/BUGS

It is known that there exists another representation of the block sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block column in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse column format the following calling sequence should be used

```
CALL SBSCMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*           VAL, BINDX, IA, IA(2), LB,  
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

dbscsm - block sparse column format triangular solve

SYNOPSIS

```
SUBROUTINE DBSCSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE DBSCSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB) - BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSCSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, N, UNITD, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C  
  
SUBROUTINE BSCSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, N, UNITD, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dbscsm(int transa, int mb, int n, int unitd,
double *dv, double alpha, int *descra, double *val,
int* bindx, int *bpntrb, int *bpntre, int lb, double *b,
int ldb, double beta, double *c, int ldc);
void dbscsm_64(long transa, long mb, long n, long unitd,
double *dv, double alpha, long *descra, double *val, long
*bindx, long *bpntrb, long *bpntre, long lb, double *b,
long ldb, double beta, double *c, long ldc);
```

DESCRIPTION

dbscsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block sparse column format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block columns in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, integer UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) Unchanged on exit.
DV(input)	On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ
consisting of the non-zero block entries stored
column-major within each dense block where
BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting
of the block row indices of the block entries of A where
BNNZ = BPNTRE(MB)-BPNTRB(1). The block row indices MUST
be sorted in increasing order for each block column.
Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such
that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX
of the first block entry of the J-th block column
of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such
that BPNTRE(J)-BPNTRB(1) points to location in BINDX
of the last block entry of the J-th block column
of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks
composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
 On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block sparse column representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.

4. If `DESCRA(3)=2` , the diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

6. It is known that there exists another representation of the block sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, `IA`, containing the pointers to the beginning of each block column in the arrays `VAL` and `BINDX` is used instead of two arrays `BPNTRB` and `BPNTRE`. To use the routine with this kind of block sparse column format the following calling sequence should be used

```
CALL DBSCSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*           VAL, BINDX, IA, IA(2), LB,
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

dbstrmm - block sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DBSRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DBSRMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSRMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*               BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, KB, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSRMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, KB, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dbsrmm(int transa, int mb, int n, int kb,
double alpha, int *descra, double *val,
int *bindx, int *bpntrb, int *bpntre, int lb, double *b,
int ldb, double beta, double *c, int ldc);
void dbsrmm_64(long transa, long mb, long n, long kb,
double alpha, long *descra, double *val, long *bindx, long
*bpntrb, long *bpntre, long lb, double *b, long ldb, double
beta, double *c, long ldc);
```

DESCRIPTION

dbsrmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in the block sparse row format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
KB(input)	On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular 4 : Skew(Anti)-Symmetric (A=-A') 5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ consisting of the non-zero block entries stored column-major within each dense block where BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the J-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(J)-BPNTRB(1) points to location in BINDX of the last block entry of the J-th block row of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta * C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the sbcomm manpage.

NOTES/BUGS

It is known that there exists another representation of the block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse row format the following calling sequence should be used

```
CALL SBSRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*           VAL, BINDX, IA, IA(2), LB,  
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

dbstrsm - block sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE DBSRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DBSRSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSRSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*              BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, N, UNITD, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSRSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                  BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, N, UNITD, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dbsrsm(int transa, int mb, int n, int unitd,
double *dv, double alpha, int *descra, double *val,
int *bindx, int *bpntrb, int *bpntre, int lb, double *b,
int ldb, double beta, double *c, int ldc);
void dbsrsm_64(long transa, long mb, long n, long unitd,
double *dv, double alpha, long *descra, double *val, long
*bindx, long *bpntrb, long *bpntre, long lb, double *b,
long ldb, double beta, double *c, long ldc);
```

DESCRIPTION

dbsrsm performs one of the matrix-matrix operations

```
C ← alpha op(A) B + beta C,      C ← alpha D op(A) B + beta C,
C ← alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block sparse row format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) = inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ
consisting of the non-zero block entries stored
column-major within each dense block where
BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting
of the block column indices of the block entries of A where
BNNZ = BPNTRE(MB)-BPNTRB(1). The block column indices MUST
be sorted in increasing order for each block column.
Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such
that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX
of the first block entry of the J-th block row
of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such
that BPNTRE(J)-BPNTRB(1) points to location in BINDX
of the last block entry of the J-th block row
of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks
composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
 On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block sparse row representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.

4. If `DESCRA(3)=2` , the diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

6. It is known that there exists another representation of the block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, `IA`, containing the pointers to the beginning of each block row in the arrays `VAL` and `BINDX` is used instead of two arrays `BPNTRB` and `BPNTRE`. To use the routine with this kind of block sparse row format the following calling sequence should be used

```
CALL DBSRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*           VAL, BINDX, IA, IA(2), LB,
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

dcnvcor - compute the convolution or correlation of real vectors

SYNOPSIS

```
SUBROUTINE DCNVCOR(CNVCOR, FOUR, NX, X, IFX, INCX, NY, NPRE, M, Y,
  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, FOUR
INTEGER NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y, NZ,
K, IFZ, INC1Z, INC2Z, LWORK
DOUBLE PRECISION X(*), Y(*), Z(*), WORK(*)
```

```
SUBROUTINE DCNVCOR_64(CNVCOR, FOUR, NX, X, IFX, INCX, NY, NPRE, M, Y,
  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, FOUR
INTEGER*8 NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y, NZ,
K, IFZ, INC1Z, INC2Z, LWORK
DOUBLE PRECISION X(*), Y(*), Z(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE CNVCOR(CNVCOR, FOUR, [NX], X, IFX, [INCX], NY, NPRE, M, Y,
  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, FOUR
INTEGER :: NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y,
NZ, K, IFZ, INC1Z, INC2Z, LWORK
REAL(8), DIMENSION(:) :: X, Y, Z, WORK
```

```
SUBROUTINE CNVCOR_64(CNVCOR, FOUR, [NX], X, IFX, [INCX], NY, NPRE, M,
  Y, IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, FOUR
INTEGER(8) :: NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y,
NZ, K, IFZ, INC1Z, INC2Z, LWORK
REAL(8), DIMENSION(:) :: X, Y, Z, WORK
```

C INTERFACE

```
#include <sunperf.h>

void dcnvcor(char cnvcor, char four, int nx, double *x, int
    ifx, int incx, int ny, int npre, int m, double *y,
    int ify, int inclx, int inc2y, int nz, int k, dou-
    ble *z, int ifz, int inclz, int inc2z, double
    *work, int lwork);
void dcnvcor_64(char cnvcor, char four, long nx, double *x,
    long ifx, long incx, long ny, long npre, long m,
    double *y, long ify, long inclx, long inc2y, long
    nz, long k, double *z, long ifz, long inclz, long
    inc2z, double *work, long lwork);
```

PURPOSE

dcnvcor computes the convolution or correlation of real vectors.

ARGUMENTS

CNVCOR (input)

'V' or 'v' if convolution is desired, 'R' or 'r' if correlation is desired.

FOUR (input)

'T' or 't' if the Fourier transform method is to be used, 'D' or 'd' if the computation should be done directly from the definition. The Fourier transform method is generally faster, but it may introduce noticeable errors into certain results, notably when both the filter and data vectors consist entirely of integers or vectors where elements of either the filter vector or a given data vector differ significantly in magnitude from the 1-norm of the vector.

NX (input)

Length of the filter vector. NX >= 0. DCNVCOR will return immediately if NX = 0.

X (input)

Filter vector.

IFX (input)

Index of the first element of X. NX >= IFX >= 1.

INCX (input)

Stride between elements of the filter vector in X. INCX > 0.

NY (input)

Length of the input vectors. NY >= 0. DCNVCOR will return immediately if NY = 0.

NPRES (input)

The number of implicit zeros prepended to the Y

vectors. NPRE \geq 0.

M (input)
 Number of input vectors. M \geq 0. DCNVCOR will return immediately if M = 0.

Y (input)
 Input vectors.

IFY (input)
 Index of the first element of Y. NY \geq IFY \geq 1.

INC1Y (input)
 Stride between elements of the input vectors in Y. INC1Y $>$ 0.

INC2Y (input)
 Stride between the input vectors in Y. INC2Y $>$ 0.

NZ (input)
 Length of the output vectors. NZ \geq 0. DCNVCOR will return immediately if NZ = 0. See the Notes section below for information about how this argument interacts with NX and NY to control circular versus end-off shifting.

K (input)
 Number of Z vectors. K \geq 0. If K = 0 then DCNVCOR will return immediately. If K $<$ M then only the first K input vectors will be processed. If K $>$ M then M input vectors will be processed.

Z (output)
 Result vectors.

IFZ (input)
 Index of the first element of Z. NZ \geq IFZ \geq 1.

INC1Z (input)
 Stride between elements of the output vectors in Z. INC1Z $>$ 0.

INC2Z (input)
 Stride between the output vectors in Z. INC2Z $>$ 0.

WORK (input/output)
 Scratch space. Before the first call to DCNVCOR with particular values of the integer arguments the first element of WORK must be set to zero. If WORK is written between calls to DCNVCOR or if DCNVCOR is called with different values of the integer arguments then the first element of WORK must again be set to zero before each call. If WORK has not been written and the same values of the integer arguments are used then the first element of WORK to zero. This can avoid certain initializations that store their results into WORK, and avoiding the initialization can make DCNVCOR run faster.

LWORK (input)

Length of WORK. LWORK $\geq 4 \cdot \text{MAX}(\text{NX}, \text{NY}, \text{NZ}) + 15$.

NOTES

If any vector overlaps a writable vector, either because of argument aliasing or ill-chosen values of the various INC arguments, the results are undefined and may vary from one run to the next.

The most common form of the computation, and the case that executes fastest, is applying a filter vector X to a series of vectors stored in the columns of Y with the result placed into the columns of Z. In that case, $\text{INCX} = 1$, $\text{INC1Y} = 1$, $\text{INC2Y} \geq \text{NY}$, $\text{INC1Z} = 1$, $\text{INC2Z} \geq \text{NZ}$. Another common form is applying a filter vector X to a series of vectors stored in the rows of Y and store the result in the row of Z, in which case $\text{INCX} = 1$, $\text{INC1Y} \geq \text{NY}$, $\text{INC2Y} = 1$, $\text{INC1Z} \geq \text{NZ}$, and $\text{INC2Z} = 1$.

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NAME

dcnvcor2 - compute the convolution or correlation of real matrices

SYNOPSIS

```
SUBROUTINE DCNVCOR2(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, MX, NX, X, LDX, MY, NY, MPRE, NPRE, Y, LDY, MZ, NZ, Z,  
    LDZ, WORKIN, LWORK)
```

```
CHARACTER * 1 CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
SCRATCHY  
DOUBLE COMPLEX WORKIN(*)  
INTEGER MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ, LDZ,  
LWORK  
DOUBLE PRECISION X(LDX,*), Y(LDY,*), Z(LDZ,*)
```

```
SUBROUTINE DCNVCOR2_64(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, MX, NX, X, LDX, MY, NY, MPRE, NPRE, Y, LDY, MZ, NZ, Z,  
    LDZ, WORKIN, LWORK)
```

```
CHARACTER * 1 CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
SCRATCHY  
DOUBLE COMPLEX WORKIN(*)  
INTEGER*8 MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ, LDZ,  
LWORK  
DOUBLE PRECISION X(LDX,*), Y(LDY,*), Z(LDZ,*)
```

F95 INTERFACE

```
SUBROUTINE CNVCOR2(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, [MX], [NX], X, [LDX], [MY], [NY], MPRE, NPRE, Y, [LDY],  
    [MZ], [NZ], Z, [LDZ], WORKIN, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, METHOD, TRANSX, SCRATCHX,  
TRANSY, SCRATCHY  
COMPLEX(8), DIMENSION(:) :: WORKIN  
INTEGER :: MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ,  
LDZ, LWORK  
REAL(8), DIMENSION(:, :) :: X, Y, Z
```

```
SUBROUTINE CNVCOR2_64(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,
```

```
SCRATCHY, [MX], [NX], X, [LDX], [MY], [NY], MPRE, NPRES, Y, [LDY],  
[MZ], [NZ], Z, [LDZ], WORKIN, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, METHOD, TRANSX, SCRATCHX,  
TRANSY, SCRATCHY  
COMPLEX(8), DIMENSION(:) :: WORKIN  
INTEGER(8) :: MX, NX, LDX, MY, NY, MPRE, NPRES, LDY, MZ, NZ,  
LDZ, LWORK  
REAL(8), DIMENSION(:, :) :: X, Y, Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dcnvcor2(char cnvcor, char method, char transx, char  
scratchx, char transy, char scratchy, int mx, int  
nx, double *x, int ldx, int my, int ny, int mpre,  
int npre, double *y, int ldy, int mz, int nz, dou-  
ble *z, int ldz, doublecomplex *workin, int  
lwork);
```

```
void dcnvcor2_64(char cnvcor, char method, char transx, char  
scratchx, char transy, char scratchy, long mx,  
long nx, double *x, long ldx, long my, long ny,  
long mpre, long npre, double *y, long ldy, long  
mz, long nz, double *z, long ldz, doublecomplex  
*workin, long lwork);
```

PURPOSE

dcnvcor2 computes the convolution or correlation of real matrices.

ARGUMENTS

CNVCOR (input)

'V' or 'v' to compute convolution, 'R' or 'r' to compute correlation.

METHOD (input)

'T' or 't' if the Fourier transform method is to be used, 'D' or 'd' to compute directly from the definition.

TRANSX (input)

'N' or 'n' if X is the filter matrix, 'T' or 't' if transpose(X) is the filter matrix.

SCRATCHX (input)

'N' or 'n' if X must be preserved, 'S' or 's' if X can be used as scratch space. The contents of X are undefined after returning from a call in which X is allowed to be used for scratch.

TRANSY (input)

'N' or 'n' if Y is the input matrix, 'T' or 't' if transpose(Y) is the input matrix.

SCRATCHY (input)

'N' or 'n' if Y must be preserved, 'S' or 's' if Y can be used as scratch space. The contents of Y are undefined after returning from a call in which Y is allowed to be used for scratch.

MX (input)
Number of rows in the filter matrix. $MX \geq 0$.

NX (input)
Number of columns in the filter matrix. $NX \geq 0$.

X (input) dimension(LDX,NX)
On entry, the filter matrix. Unchanged on exit if SCRATCHX is 'N' or 'n', undefined on exit if SCRATCHX is 'S' or 's'.

LDX (input)
Leading dimension of the array that contains the filter matrix.

MY (input)
Number of rows in the input matrix. $MY \geq 0$.

NY (input)
Number of columns in the input matrix. $NY \geq 0$.

MPRE (input)
Number of implicit zeros to prepend to each row of the input matrix. $MPRE \geq 0$.

NPRE (input)
Number of implicit zeros to prepend to each column of the input matrix. $NPRE \geq 0$.

Y (input) dimension(LDY,*)
Input matrix. Unchanged on exit if SCRATCHY is 'N' or 'n', undefined on exit if SCRATCHY is 'S' or 's'.

LDY (input)
Leading dimension of the array that contains the input matrix.

MZ (input)
Number of rows in the output matrix. $MZ \geq 0$.
DCNVCOR2 will return immediately if $MZ = 0$.

NZ (input)
Number of columns in the output matrix. $NZ \geq 0$.
DCNVCOR2 will return immediately if $NZ = 0$.

Z (output)
dimension(LDZ,*)
Result matrix.

LDZ (input)
Leading dimension of the array that contains the result matrix. $LDZ \geq \text{MAX}(1, MZ)$.

WORKIN (input/output)
(input/scratch) dimension(LWORK)

On entry for the first call to DCNVCOR2, WORKIN(1) must contain 0.0. After the first call, WORKIN(1) must be set to 0.0 iff WORKIN has been altered since the last call to this subroutine or if the sizes of the arrays have changed.

LWORK (input)

Length of the work vector. If the FFT is to be used then for best performance LWORK should be at least 30 words longer than the amount of memory needed to hold the trig tables. If the FFT is not used, the value of LWORK is unimportant.

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NAME

dcoomm - coordinate matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DCOOMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5), NNZ  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), JNDX(NNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE DCOOMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), NNZ  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), JNDX(NNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE COOMM( TRANSA, M, [N], K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ, B, [LDB], BETA, C, [LDC],  
*                [WORK], [LWORK] )  
INTEGER          TRANSA, M, K, NNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, JNDX  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C  
  
SUBROUTINE COOMM_64( TRANSA, M, [N], K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ, B, [LDB], BETA, C, [LDC],  
*                [WORK], [LWORK] )  
INTEGER*8        TRANSA, M, K, NNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, JNDX  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dcoomm (int transa, int m, int n, int k, double alpha,
int *descra, double *val, int *indx, int *jndx, int nnz,
double *b, int ldb, double beta, double *c, int ldc);
void dcoomm_64 (long transa, long m, long n, long k,
double alpha, long *descra, double *val, long *indx,
long *jndx, long nnz, double *b, long ldb,
double beta, double *c, long ldc);
```

DESCRIPTION

dcoomm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the coordinate format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.

K(input) On entry, integer K specifies the number of columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array.
DESCRA(1) matrix structure
0 : general
1 : symmetric ($A=A'$)
2 : Hermitian ($A= \operatorname{CONJG}(A')$)
3 : Triangular
4 : Skew(Anti)-Symmetric ($A=-A'$)
5 : Diagonal

```

        6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
        1 : lower
        2 : upper
DESCRA(3) main diagonal type
        0 : non-unit
        1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
        0 : C/C++ compatible
        1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
        0 : unknown
        1 : no repeated indices

VAL (input)      On entry, VAL is a scalar array array of length
                  NNZ consisting of the non-zero entries of A,
                  in any order. Unchanged on exit.

INDX (input)     On entry, INDX is an integer array of length NNZ
                  consisting of the corresponding row indices of
                  the entries of A. Unchanged on exit.

JNDX (input)     On entry, JNDX is an integer array of length NNZ
                  consisting of the corresponding column indices of
                  the entries of A. Unchanged on exit.

NNZ (input)      On entry, integer NNZ specifies the number of
                  non-zero elements in A. Unchanged on exit.

B (input)        Array of DIMENSION ( LDB, N ).
                  Before entry with TRANSA = 0, the leading k by n
                  part of the array B must contain the matrix B, otherwise
                  the leading m by n part of the array B must contain the
                  matrix B. Unchanged on exit.

LDB (input)      On entry, LDB specifies the first dimension of B as declared
                  in the calling (sub) program. Unchanged on exit.

BETA (input)     On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output)  Array of DIMENSION ( LDC, N ).
                  Before entry with TRANSA = 0, the leading m by n
                  part of the array C must contain the matrix C, otherwise
                  the leading k by n part of the array C must contain the
                  matrix C. On exit, the array C is overwritten by the matrix
                  ( alpha*op( A )* B + beta*C ).

LDC (input)      On entry, LDC specifies the first dimension of C as declared
                  in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are

implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats is given in section NOTES/BUGS for the scoomm manpage.

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NAME

dcopy - Copy x to y

SYNOPSIS

```
SUBROUTINE DCOPY(N, X, INCX, Y, INCY)
```

```
INTEGER N, INCX, INCY  
DOUBLE PRECISION X(*), Y(*)
```

```
SUBROUTINE DCOPY_64(N, X, INCX, Y, INCY)
```

```
INTEGER*8 N, INCX, INCY  
DOUBLE PRECISION X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE COPY([N], X, [INCX], Y, [INCY])
```

```
INTEGER :: N, INCX, INCY  
REAL(8), DIMENSION(:) :: X, Y
```

```
SUBROUTINE COPY_64([N], X, [INCX], Y, [INCY])
```

```
INTEGER(8) :: N, INCX, INCY  
REAL(8), DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dcopy(int n, double *x, int incx, double *y, int incy);
```

```
void dcopy_64(long n, double *x, long incx, double *y, long  
incy);
```

PURPOSE

dcopy Copy x to y where x and y are n-vectors.

ARGUMENTS

- N (input)
On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.
- X (input)
($1 + (n - 1) * \text{abs}(\text{INCX})$). Before entry, the incremented array X must contain the vector x. Unchanged on exit.
- INCX (input)
On entry, INCX specifies the increment for the elements of X. Unchanged on exit.
- Y (output)
($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the vector x.
- INCY (input)
On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

dcosqb - synthesize a Fourier sequence from its representation in terms of a cosine series with odd wave numbers. The COSQ operations are unnormalized inverses of themselves, so a call to COSQF followed by a call to COSQB will multiply the input sequence by $4 * N$.

SYNOPSIS

```
SUBROUTINE DCOSQB(N, X, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION X(*), WSAVE(*)
```

```
SUBROUTINE DCOSQB_64(N, X, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQB([N], X, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE COSQB_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dcosqb(int n, double *x, double *wsave);
```

```
void dcosqb_64(long n, double *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the quarter-wave cosine synthesis of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$ that has been initialized by DCOSQI.

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NAME

dcosqf - compute the Fourier coefficients in a cosine series representation with only odd wave numbers. The COSQ operations are unnormalized inverses of themselves, so a call to COSQF followed by a call to COSQB will multiply the input sequence by $4 * N$.

SYNOPSIS

```
SUBROUTINE DCOSQF(N, X, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION X(*), WSAVE(*)
```

```
SUBROUTINE DCOSQF_64(N, X, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQF([N], X, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE COSQF_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dcosqf(int n, double *x, double *wsave);
```

```
void dcosqf_64(long n, double *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the quarter-wave cosine transform of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$ that has been initialized by DCOSQI.

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NAME

dcosqi - initialize the array WSAVE, which is used in both COSQF and COSQB.

SYNOPSIS

```
SUBROUTINE DCOSQI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE DCOSQI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE COSQI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void dcosqi(int n, double *wsave);

void dcosqi_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. The method is most efficient when N is a product of small primes.

WSAVE (input)

On entry, an array of dimension $(3 * N + 15)$ or greater. DCOSQI needs to be called only once to initialize WSAVE before calling DCOSQF and/or DCOSQB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

dcost - compute the discrete Fourier cosine transform of an even sequence. The COST transforms are unnormalized inverses of themselves, so a call of COST followed by another call of COST will multiply the input sequence by $2 * (N-1)$.

SYNOPSIS

```
SUBROUTINE DCOST(N, X, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION X(*), WSAVE(*)
```

```
SUBROUTINE DCOST_64(N, X, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COST([N], X, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE COST_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dcost(int n, double *x, double *wsave);
```

```
void dcost_64(long n, double *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when $N - 1$ is a product of small primes. $N \geq 2$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the cosine transform of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$, initialized by DCOSTI.

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NAME

dcosti - initialize the array WSAVE, which is used in COST.

SYNOPSIS

```
SUBROUTINE DCOSTI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE DCOSTI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSTI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE COSTI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void dcosti(int n, double *wsave);

void dcosti_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. The method is most efficient when N - 1 is a product of small primes. N >= 2.

WSAVE (input)

On entry, an array of dimension $(3 * N + 15)$ or greater. DCOSTI is called once to initialize WSAVE before calling DCOST and need not be called again between calls to DCOST if N and WSAVE remain unchanged. Thus, subsequent transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

dcscmm - compressed sparse column format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DCSCMM( TRANSA, M, N, K, ALPHA, DESCRA,  
* VAL, INDX, PNTRB, PNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER TRANSA, M, N, K, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER INDX(NNZ), PNTRB(K), PNTRE(K)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DCSCMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
* VAL, INDX, PNTRB, PNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8 TRANSA, M, N, K, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER*8 INDX(NNZ), PNTRB(K), PNTRE(K)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where $NNZ = PNTRE(K) - PNTRB(1)$.

F95 INTERFACE

```
SUBROUTINE CSCMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
* PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE CSCMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
* PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8 TRANSA, M, K  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
```

```

DOUBLE PRECISION    ALPHA, BETA
DOUBLE PRECISION, DIMENSION(:) :: VAL
DOUBLE PRECISION, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void dcscmm(int transa, int m, int n, int k, double alpha,
int *descra, double *val, int *indx, int *pntrb, int *pntre,
double *b, int ldb, double beta, double *c, int ldc);
void dcscmm_64(long transa, long m, long n, long k, double
alpha, long *descra, double *val, long *indx, long *pntrb,
long *pntre, double *b, long ldb, double beta, double *c,
long ldc);

```

DESCRIPTION

dcscmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$$\operatorname{op}(A) = A \quad \text{or} \quad \operatorname{op}(A) = A' \quad \text{or} \quad \operatorname{op}(A) = \operatorname{conjg}(A') \\ \text{(' indicates matrix transpose),}$$

A is an M-by-K sparse matrix represented in the compressed sparse column format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

- TRANSA(input) TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
 - 0 : operate with matrix
 - 1 : operate with transpose matrix
 - 2 : operate with the conjugate transpose of matrix.
 - 2 is equivalent to 1 if matrix is real.
Unchanged on exit.

- M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

- N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

- K(input) On entry, K specifies the number of columns in the matrix A. Unchanged on exit.

- ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
- DESCRA (input) Descriptor argument. Five element integer array:
 - DESCRA(1) matrix structure
 - 0 : general
 - 1 : symmetric (A=A')
 - 2 : Hermitian (A= CONJG(A'))
 - 3 : Triangular
 - 4 : Skew(Anti)-Symmetric (A=-A')
 - 5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, scalar array of length NNZ = PNTRE(K)-PNTRB(1) consisting of nonzero entries of A. Unchanged on exit.

INDX(input) On entry, integer array of length NNZ = PNTRE(K)-PNTRB(1) consisting of the row indices of nonzero entries of A. Unchanged on exit.

PNTRB(input) On entry, integer array of length K such that PNTRB(J)-PNTRB(1)+1 points to location in VAL of the first nonzero element in column J. Unchanged on exit.

PNTRE(input) On entry, integer array of length K such that PNTRE(J)-PNTRB(1) points to location in VAL of the last nonzero element in column J. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A)* B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are

implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats is given in section NOTES/BUGS for the scoomm manpage.

NOTES/BUGS

It is known that there exists another representation of the compressed sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each column in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of sparse column format the following calling sequence should be used

```
SUBROUTINE SCSCMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, IA, IA(2), B, LDB, BETA,  
*                C, LDC, WORK, LWORK )
```

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NAME

dcscsm - compressed sparse column format triangular solve

SYNOPSIS

```
SUBROUTINE DCSCSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, PNTRB, PNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, UNITD, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DCSCSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, INDX, PNTRB, PNTRE,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(M)-PNTRB(1)

F95 INTERFACE

```
SUBROUTINE CSCSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER          TRANSA, M, UNITD  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE CSCSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
*                   PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8        TRANSA, M, UNITD  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dcscsm(int transa, int m, int n, int unitd,
double *dv, double alpha, int *descra, double *val,
int *indx, int *pntrb, int *pntre, double *b,
int ldb, double beta, double* c, int ldc);
void dcscsm_64(long transa, long m, long n, long unitd,
double *dv, double alpha, long *descra, double *val, long
*indx, long *pntrb, long *pntre, double *b, long ldb, double
beta, double *c, long ldc);
```

DESCRIPTION

dcscsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the compressed sparse column format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic column scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the columns of A have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input) Descriptor argument. Five element integer array:

DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))

Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries of A. If UNITD is 4, VAL contains the scaled matrix A*D (see section NOTES for further details). Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer array of length NNZ = PNTRE(M)-PNTRB(1) consisting of the row indices of nonzero entries of A. Row indices MUST be sorted in increasing order for each column. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such that PNTRB(J)-PNTRB(1)+1 points to location in VAL of the first nonzero element in column J. Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M such that PNTRE(J)-PNTRB(1) points to location in VAL of the last nonzero element in column J. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).

On entry, the leading m by n part of the array C must contain the matrix C . On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M .

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M \cdot N_{\text{CPUS}}$ where N_{CPUS} is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4, the routine scales the columns of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the columns have been scaled. UNITD=3 should be used for the next calls to the routine with overwritten VAL and DV.

`WORK(1)=0` on return if the scaling has been completed successfully, otherwise `WORK(1)= - k` where `k` is the column number which 2-norm is exactly zero.

3. If `DESCRA(3)=1` and `UNITD < 4`, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the CSC representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if `UNITD=4`, the unit diagonal elements MUST be referenced in the CSC representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix `A` for solving triangular systems with the upper or lower triangle of `A`. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix `A` decomposed in the form

$$A = L + D + U$$

where `L` is the strictly lower triangle of `A`, `U` is the strictly upper triangle of `A`, `D` is the diagonal matrix. Let's `I` denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of `A` is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

5. It is known that there exists another representation of the compressed sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, `IA`, containing the pointers to the beginning of each column in the arrays `VAL` and `INDX` is used instead of two arrays `PNTRB` and `PNTRE`. To use the routine with this kind of sparse column format the following calling sequence should be used

```

SUBROUTINE DCSCSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, IA, IA(2), B, LDB, BETA,
*                 C, LDC, WORK, LWORK )

```

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NAME

dcsrmm - compressed sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DCSRMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, PNTRB, PNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DCSRMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, PNTRB, PNTRE,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(M)-PNTRB(1)

F95 INTERFACE

```
SUBROUTINE CSRMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*               PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE CSRMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                   PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8 TRANSA, M, K  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dcsrmm(int transa, int m, int n, int k, double alpha,
int *descra, double *val, int *indx, int *pntrb, int *pntre,
double *b, int ldb, double beta, double *c, int ldc);
void dcsrmm_64(long transa, long m, long n, long k, double
alpha, long *descra, double *val, long *indx, long *pntrb,
long *pntre, double *b, long ldb, double beta, double *c,
long ldc);
```

DESCRIPTION

dcsrmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the compressed sparse row format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal 6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$)

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
 NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries
 of A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
 NNZ = PNTRE(M)-PNTRB(1) consisting of the column
 indices of nonzero entries of A. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such
 that PNTRB(J)-PNTRB(1)+1 points to location in VAL
 of the first nonzero element in row J.
 Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M
 such that PNTRE(J)-PNTRB(1) points to location
 in VAL of the last nonzero element in row J.
 Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise
 the leading k by n part of the array C must contain the
 matrix C. On exit, the array C is overwritten by the matrix
 (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible
 with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats is given in section NOTES/BUGS for the scoomm manpage.

NOTES/BUGS

It is known that there exists another representation of the compressed sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each row in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of compressed sparse row format the following calling sequence should be used

```
      SUBROUTINE DCSRMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, IA, IA(2), B, LDB, BETA,  
*                   C, LDC, WORK, LWORK )
```

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NAME

dcsrcsm - compressed sparse row format triangular solve

SYNOPSIS

```

SUBROUTINE DCSRSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER          TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE DCSRSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

where NNZ = PNTRE(M)-PNTRB(1)
```

F95 INTERFACE

```

SUBROUTINE CSRSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )
INTEGER          TRANSA, M, UNITD
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C

SUBROUTINE CSRSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )
INTEGER*8        TRANSA, M, UNITD
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void dcsrsm(int transa, int m, int n, int unitd,
            double *dv, double alpha, int *descra, double *val,
            int *indx, int *pntrb, int *pntre, double *b,
            int ldb, double beta, double* c, int ldc);
void dcsrsm_64(long transa, long m, long n, long unitd,
               double *dv, double alpha, long *descra, double *val, long
               *indx, long *pntrb, long *pntre, double *b, long ldb, double
               beta, double *c, long ldc);
```

DESCRIPTION

zcsrsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the compressed sparse row format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input) On entry, TRANSA indicates how to operate with the sparse matrix:

- 0 : operate with matrix
- 1 : operate with transpose matrix
- 2 : operate with the conjugate transpose of matrix.

2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, UNITD specifies the type of scaling:

- 1 : Identity matrix (argument DV[] is ignored)
- 2 : Scale on left (row scaling)
- 3 : Scale on right (column scaling)
- 4 : Automatic row scaling (see section NOTES for further details)

Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further

details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries
of A. If UNITD is 4, VAL contains the scaled matrix
D*A (see section NOTES for further details).
Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
NNZ = PNTRE(M)-PNTRB(1) consisting of the column
indices of nonzero entries of A. Column indices
MUST be sorted in increasing order for each
row. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such
that PNTRB(J)-PNTRB(1)+1 points to location in VAL
of the first nonzero element in row J.
Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M
such that PNTRE(J)-PNTRB(1) points to location
in VAL of the last nonzero element in row J.
Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C
must contain the matrix C. On exit, the array C is
overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M \cdot N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = -i where i is the row number which 2-norm is exactly zero.

3. If DESCRA(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the CSR representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the CSR representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But DESCRA(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

5. It is known that there exists another representation of the compressed sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each row in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of compressed sparse row format the following calling sequence should be used

```

SUBROUTINE DCSRSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, IA, IA(2), B, LDB, BETA, C,
*                 LDC, WORK, LWORK )

```

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NAME

ddiamm - diagonal format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DDIAMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, LDA, IDIAG, NDIAG,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5), LDA, NDIAG,  
*                LDB, LDC, LWORK  
INTEGER          IDIAG(NDIAG)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DDIAMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, LDA, IDIAG, NDIAG,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), LDA, NDIAG,  
*                   LDB, LDC, LWORK  
INTEGER*8        IDIAG(NDIAG)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE DIAMM(TRANSA, M, [N], K, ALPHA, DESCRA, VAL, [LDA],  
*  IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, K, NDIAG  
INTEGER, DIMENSION(:) :: DESCRA, IDIAG  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE DIAMM_64(TRANSA, M, [N], K, ALPHA, DESCRA, VAL, [LDA],  
*  IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, M, K, NDIAG  
INTEGER*8, DIMENSION(:) :: DESCRA, IDIAG  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```

#include <sunperf.h>

void ddiamm (int transa, int m, int n, int k, double alpha,
int *descra, double *val, int lda, int *idiag, int ndiag,
double *b, int ldb, double beta,
double *c, int ldc);

void ddiamm_64 (long transa, long m, long n, long k, double
alpha, long *descra, double *val, long lda,
long *idiag, long ndiag, double *b, long ldb,
double beta, double *c, long ldc);

```

DESCRIPTION

ddiamm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the diagonal format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal 6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$) DESCRA(2) upper/lower triangular indicator 1 : lower

2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) Two-dimensional LDA-by-NDIAG array such that VAL(:,I) consists of non-zero elements on diagonal IDIAG(I) of A. Diagonals in the lower triangular part of A are padded from the top, and those in the upper triangular part are padded from the bottom. Unchanged on exit.

LDA(input) On entry, NDIAG specifies the leading dimension of VAL, must be $\geq \text{MIN}(M,K)$. Unchanged on exit.

IDIAG(input) Integer array of length NDIAG consisting of the corresponding diagonal offsets of the non-zero diagonals of A in VAL. Lower triangular diagonals have negative offsets, the main diagonal has offset 0, and upper triangular diagonals have positive offset. Unchanged on exit.

NDIAG(input) On entry, NDIAG specifies the number of non-zero diagonals in A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \text{beta} * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of real sparse matrices is given in the manpage for the scoomm manpage.

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NAME

ddiasm - diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE DDIASM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, LDA, IDIAG, NDIAG,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER TRANSA, M, N, UNITD, DESCRA(5), LDA, NDIAG,  
* LDB, LDC, LWORK  
INTEGER IDIAG(NDIAG)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DDIASM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, LDA, IDIAG, NDIAG,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8 TRANSA, M, N, UNITD, DESCRA(5), LDA, NDIAG,  
* LDB, LDC, LWORK  
INTEGER*8 IDIAG(NDIAG)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE DIASM(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* [LDA], IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, M, NDIAG  
INTEGER, DIMENSION(:) :: DESCRA, IDIAG  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: DV  
DOUBLE PRECISION, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE DIASM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* [LDA], IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, M, NDIAG  
INTEGER*8, DIMENSION(:) :: DESCRA, IDIAG  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: DV  
DOUBLE PRECISION, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>

void ddiasm (int transa, int m, int n, int unitd,
             double *dv, double alpha, int *descra, double *val, int
             lda, int *idiag, int ndiag, double *b, int ldb, double beta,
             double *c, int ldc);
void ddiasm_64 (long transa, long m, long n, long unitd,
               double *dv, double alpha, long *descra, double *val, long
               lda,
               long *idiag, long ndiag, double *b, long ldb,
               double beta, double *c, long ldc);
```

DESCRIPTION

ddiasm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which

the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LDA-by-NDIAG array such that VAL(:,I) consists of non-zero elements on diagonal IDIAG(I) of A. Diagonals in the lower triangular part of A are padded from the top, and those in the upper triangular part are padded from the bottom. If UNITD is 4, VAL contains the scaled matrix D*A (see section NOTES for further details). Otherwise, unchanged on exit.

LDA(input) On entry, LDA specifies the leading dimension of VAL and INDX. LDA must be > MIN(M,K). Unchanged on exit.

IDIAG() On entry, IDIAG is an integer array of length NDIAG consisting of the corresponding diagonal offsets of the non-zero diagonals of A in VAL. Lower triangular diagonals have negative offsets, the main diagonal has offset 0, and upper triangular diagonals have positive offset. Elements of IDIAG of MUST be sorted in increasing order. Unchanged on exit.

NDIAG(input) On entry, NDIAG specifies the number of non-zero diagonals in A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M \times N_{\text{CPUS}}$ where N_{CPUS} is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
 2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.
- WORK*(1)=0 on return if the scaling has been completed successfully, otherwise *WORK*(1) = - i where i is the row number which 2-norm is exactly zero.
3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are

each used with the mathematical value 1. The entries of the main diagonal in the DIA representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the DIA representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

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NAME

ddisna - compute the reciprocal condition numbers for the eigenvectors of a real symmetric or complex Hermitian matrix or for the left or right singular vectors of a general m-by-n matrix

SYNOPSIS

```
SUBROUTINE DDISNA(JOB, M, N, D, SEP, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER M, N, INFO  
DOUBLE PRECISION D(*), SEP(*)
```

```
SUBROUTINE DDISNA_64(JOB, M, N, D, SEP, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER*8 M, N, INFO  
DOUBLE PRECISION D(*), SEP(*)
```

F95 INTERFACE

```
SUBROUTINE DISNA(JOB, M, N, D, SEP, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER :: M, N, INFO  
REAL(8), DIMENSION(:) :: D, SEP
```

```
SUBROUTINE DISNA_64(JOB, M, N, D, SEP, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER(8) :: M, N, INFO  
REAL(8), DIMENSION(:) :: D, SEP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ddisna(char job, int m, int n, double *d, double *sep,  
            int *info);
```

```
void ddisna_64(char job, long m, long n, double *d, double  
               *sep, long *info);
```

PURPOSE

ddisna computes the reciprocal condition numbers for the eigenvectors of a real symmetric or complex Hermitian matrix or for the left or right singular vectors of a general m-by-n matrix. The reciprocal condition number is the 'gap' between the corresponding eigenvalue or singular value and the nearest other one.

The bound on the error, measured by angle in radians, in the I-th computed vector is given by

$$\text{SLAMCH}('E') * (\text{ANORM} / \text{SEP}(I))$$

where $\text{ANORM} = 2\text{-norm}(A) = \max(\text{abs}(D(j)))$. $\text{SEP}(I)$ is not allowed to be smaller than $\text{SLAMCH}('E') * \text{ANORM}$ in order to limit the size of the error bound.

SDISNA may also be used to compute error bounds for eigenvectors of the generalized symmetric definite eigenproblem.

ARGUMENTS

JOB (input)

Specifies for which problem the reciprocal condition numbers should be computed:

= 'E': the eigenvectors of a symmetric/Hermitian matrix;

= 'L': the left singular vectors of a general matrix;

= 'R': the right singular vectors of a general matrix.

M (input) The number of rows of the matrix. $M \geq 0$.

N (input) If JOB = 'L' or 'R', the number of columns of the matrix, in which case $N \geq 0$. Ignored if JOB = 'E'.

D (input) dimension ($\min(M,N)$) if JOB = 'L' or 'R' The eigenvalues (if JOB = 'E') or singular values (if JOB = 'L' or 'R') of the matrix, in either increasing or decreasing order. If singular values, they must be non-negative.

SEP (output)

dimension ($\min(M,N)$) if JOB = 'L' or 'R' The reciprocal condition numbers of the vectors.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

ddot - compute the dot product of two vectors x and y.

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DDOT(N, X, INCX, Y, INCY)
```

```
INTEGER N, INCX, INCY  
DOUBLE PRECISION X(*), Y(*)
```

```
DOUBLE PRECISION FUNCTION DDOT_64(N, X, INCX, Y, INCY)
```

```
INTEGER*8 N, INCX, INCY  
DOUBLE PRECISION X(*), Y(*)
```

F95 INTERFACE

```
REAL(8) FUNCTION DOT([N], X, [INCX], Y, [INCY])
```

```
INTEGER :: N, INCX, INCY  
REAL(8), DIMENSION(:) :: X, Y
```

```
REAL(8) FUNCTION DOT_64([N], X, [INCX], Y, [INCY])
```

```
INTEGER(8) :: N, INCX, INCY  
REAL(8), DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
double ddot(int n, double *x, int incx, double *y, int  
            incy);
```

```
double ddot_64(long n, double *x, long incx, double *y, long  
              incy);
```

PURPOSE

ddot compute the dot product of x and y where x and y are

n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If N is not positive then the function returns the value 0.0. Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)). On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input)

(1 + (n - 1) * abs(INCY)). On entry, the incremented array Y must contain the vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

ddoti - Compute the indexed dot product.

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DDOTI(NZ, X, INDX, Y)

DOUBLE PRECISION X(*), Y(*)
INTEGER NZ
INTEGER INDX(*)

DOUBLE PRECISION FUNCTION DDOTI_64(NZ, X, INDX, Y)

DOUBLE PRECISION X(*), Y(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
DOUBLE PRECISION FUNCTION DOTI([NZ], X, INDX, Y)

REAL(8), DIMENSION(:) :: X, Y
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

DOUBLE PRECISION FUNCTION DOTI_64([NZ], X, INDX, Y)

REAL(8), DIMENSION(:) :: X, Y
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

DDOTI Compute the indexed dot product of a real sparse vector *x* stored in compressed form with a real vector *y* in full storage form.

```
dot = 0
do i = 1, n
  dot = dot + x(i) * y(indx(i))
enddo
```

ARGUMENTS

NZ (input)

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector in compressed form. Unchanged on exit.

INDX (input)

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

Y (input)

Vector in full storage form. Only the elements
corresponding to the indices in INDX will be
accessed.

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NAME

dellmm - Ellpack format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DELLMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, LDA, MAXNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5), LDA, MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(LDA,MAXNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DELLMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, LDA, MAXNZ,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), LDA, MAXNZ,  
*                   LDB, LDC, LWORK  
INTEGER*8        INDX(LDA,MAXNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE ELLMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*               [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, M, K, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA  
INTEGER, DIMENSION(:, :) :: INDX  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE ELLMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                   [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, M, K, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA  
INTEGER*8, DIMENSION(:, :) :: INDX  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dellmm (int transa, int m, int n, int k, double alpha,  
int *descra, double *val, int *indx, int lda, int maxnz,  
double *b, int ldb, double beta, double *c, int ldc);
```

```
void dellmm_64 (long transa, long m, long n, long k, double  
alpha, long *descra, double *val, long *indx, long lda, long  
maxnz, double *b, long ldb, double beta, double *c, long  
ldc);
```

DESCRIPTION

dellmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the ellpack format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

K(input) On entry, K specifies the number of columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric ($A=A'$)
2 : Hermitian ($A= \operatorname{CONJG}(A')$)
3 : Triangular
4 : Skew(Anti)-Symmetric ($A=-A'$)
5 : Diagonal
6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$)
DESCRA(2) upper/lower triangular indicator

```

    1 : lower
    2 : upper
DESCRA(3) main diagonal type
    0 : non-unit
    1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
    0 : C/C++ compatible
    1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
    0 : unknown
    1 : no repeated indices

VAL(input)      On entry, VAL is a two-dimensional LDA-by-MAXNZ array
                such that VAL(I,:) consists of non-zero elements
                in row I of A, padded by zero values if the row
                contains less than MAXNZ. Unchanged on exit.

INDX(input)     On entry, INDX is an integer two-dimensional
                LDA-by-MAXNZ array such that INDX(I,:)
                consists of the column indices of the
                nonzero elements in row I, padded by the integer
                value I if the number of nonzeros is less than
                MAXNZ. Unchanged on exit.

LDA(input)      On entry, LDA specifies the leading dimension of VAL
                and INDX. Unchanged on exit.

MAXNZ(input)   On entry, MAXNZ specifies the max number of
                nonzeros elements per row. Unchanged on exit.

B (input)      Array of DIMENSION ( LDB, N ).
                Before entry with TRANSA = 0, the leading k by n
                part of the array B must contain the matrix B, otherwise
                the leading m by n part of the array B must contain the
                matrix B. Unchanged on exit.

LDB (input)    On entry, LDB specifies the first dimension of B as declared
                in the calling (sub) program. Unchanged on exit.

BETA (input)   On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                Before entry with TRANSA = 0, the leading m by n
                part of the array C must contain the matrix C, otherwise
                the leading k by n part of the array C must contain the
                matrix C. On exit, the array C is overwritten by the matrix
                ( alpha*op( A ) * B + beta*C ).

LDC (input)    On entry, LDC specifies the first dimension of C as declared
                in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN

Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats is given in section NOTES/BUGS for the scoomm manpage.

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NAME

dellsm - Ellpack format triangular solve

SYNOPSIS

```
SUBROUTINE DELLSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, LDA, MAXNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, UNITD, DESCRA(5), LDA, MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(LDA,MAXNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DELLSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, INDX, LDA, MAXNZ,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5), LDA, MAXNZ,  
*                   LDB, LDC, LWORK  
INTEGER*8        INDX(LDA,MAXNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE ELLSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
*               INDX, [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, M, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA  
INTEGER, DIMENSION(:, :) :: INDX  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: DV  
DOUBLE PRECISION, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE ELLSM_64( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
*                  INDX, [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, M, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA  
INTEGER*8, DIMENSION(:, :) :: INDX  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: DV
DOUBLE PRECISION, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dellsm (int transa, int m, int n, int unitd, double
*dv, double alpha, int *descra, double *val, int *indx, int
lda, int maxnz, double *b, int ldb, double beta, double *c,
int ldc);
void dellsm_64 (long transa, long m, long n, long unitd,
double *dv, double alpha, long *descra, double *val, long
*indx, long lda, long maxnz, double *b, long ldb, double
beta, double *c, long ldc);
```

DESCRIPTION

dellsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the ellpack/itpack format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LDA-by-MAXNZ array such that VAL(I,:) consists of non-zero elements in row I of A, padded by zero values if the row contains less than MAXNZ. If UNITD is 4, VAL contains the scaled matrix D*A (see section NOTES for further details). Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer two-dimensional LDA-by-MAXNZ array such that INDX(I,:) consists of the column indices of the nonzero elements in row I, padded by the integer value I if the number of nonzeros is less than MAXNZ. The column indices MUST be sorted in increasing order for each row. Unchanged on exit.

LDA(input) On entry, LDA specifies the leading dimension of VAL and INDX. Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of nonzeros elements per row. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M \times N_{\text{CPUS}}$ where N_{CPUS} is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
 2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.
- WORK*(1)=0 on return if the scaling has been completed successfully, otherwise *WORK*(1) = - i where i is the row number which 2-norm is exactly zero.
3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are

each used with the mathematical value 1. The entries of the main diagonal in the ELL representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the ELL representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

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NAME

dezftb - computes a periodic sequence from its Fourier coefficients. DEZFTB is a simplified but slower version of DFFTb.

SYNOPSIS

```
SUBROUTINE DEZFTB(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION AZERO  
DOUBLE PRECISION R(*), A(*), B(*), WSAVE(*)
```

```
SUBROUTINE DEZFTB_64(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION AZERO  
DOUBLE PRECISION R(*), A(*), B(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE DEZFTB(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER :: N  
REAL(8) :: AZERO  
REAL(8), DIMENSION(:) :: R, A, B, WSAVE
```

```
SUBROUTINE DEZFTB_64(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8) :: AZERO  
REAL(8), DIMENSION(:) :: R, A, B, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dezftb(int n, double *r, double azero, double *a, double *b, double *wsave);
```

```
void dezftb_64(long n, double *r, double azero, double *a, double *b, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be synthesized. The method is most efficient when N is the product of small primes. $N \geq 0$.

R (output)
On exit, the Fourier synthesis of the inputs.

AZERO (input)
On entry, the constant Fourier coefficient A0.
Unchanged on exit.

A (input/output)
On entry, array that contains the remaining Fourier coefficients. On exit, these arrays are unchanged.

B (input/output)
On entry, array that contains the remaining Fourier coefficients. On exit, these arrays are unchanged.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$, initialized by DEZFTI.

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NAME

dezftf - computes the Fourier coefficients of a periodic sequence. DEZFTF is a simplified but slower version of DFFTF.

SYNOPSIS

```
SUBROUTINE DEZFTF(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION AZERO  
DOUBLE PRECISION R(*), A(*), B(*), WSAVE(*)
```

```
SUBROUTINE DEZFTF_64(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION AZERO  
DOUBLE PRECISION R(*), A(*), B(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE DEZFTF(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER :: N  
REAL(8) :: AZERO  
REAL(8), DIMENSION(:) :: R, A, B, WSAVE
```

```
SUBROUTINE DEZFTF_64(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8) :: AZERO  
REAL(8), DIMENSION(:) :: R, A, B, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dezftf(int n, double *r, double azero, double *a, double *b, double *wsave);
```

```
void dezftf_64(long n, double *r, double azero, double *a, double *b, double *wsave);
```

ARGUMENTS

- N (input) Length of the sequence to be transformed. The method is most efficient when N is the product of small primes. $N \geq 0$.
- R (input) On entry, a real array of length N containing the sequence to be transformed. On exit, R is unchanged.
- AZERO (output)
On exit, the sum from $i=1$ to $i=n$ of $r(i)/n$.
- A (input/output)
On entry, array that contains the remaining Fourier coefficients. On exit, these arrays are unchanged.
- B (input/output)
On entry, array that contains the remaining Fourier coefficients. On exit, these arrays are unchanged.
- WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$, initialized by DEZFTI.

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NAME

dezfti - initializes the array WSAVE, which is used in both DEZFTF and DEZFTB.

SYNOPSIS

```
SUBROUTINE DEZFTI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE DEZFTI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE DEZFTI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE DEZFTI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void dezfti(int n, double *wsave);

void dezfti_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array with a dimension of at least (3

* N + 15). The same work array can be used for both DEZFTF and DEZFTB as long as N remains unchanged. Different WSAVE arrays are required for different values of N. This initialization does not have to be repeated between calls to DEZFTF or DEZFTB as long as N and WSAVE remain unchanged, thus subsequent transforms can be obtained faster than the first.

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NAME

dffft2b - compute a periodic sequence from its Fourier coefficients. The DFFT operations are unnormalized, so a call of DFFT2F followed by a call of DFFT2B will multiply the input sequence by M*N.

SYNOPSIS

```
SUBROUTINE DFFT2B(PLACE, M, N, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE  
INTEGER M, N, LDA, LDB, LWORK  
DOUBLE PRECISION A(LDA,*), B(2*LDB,*), WORK(*)
```

```
SUBROUTINE DFFT2B_64(PLACE, M, N, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE  
INTEGER*8 M, N, LDA, LDB, LWORK  
DOUBLE PRECISION A(LDA,*), B(2*LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2B(PLACE, [M], [N], A, [LDA], B, [LDB], WORK, LWORK)
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER :: M, N, LDA, LDB, LWORK  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE FFT2B_64(PLACE, [M], [N], A, [LDA], B, [LDB], WORK, LWORK)
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER(8) :: M, N, LDA, LDB, LWORK  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dffft2b(char place, int m, int n, double *a, int lda,  
            double *b, int ldb, double *work, int lwork);
```

```
void dffft2b_64(char place, long m, long n, double *a, long  
               lda, double *b, long ldb, double *work, long
```

lwork);

ARGUMENTS

PLACE (input)

Character. If PLACE = 'I' or 'i' (for in-place) , the input and output data are stored in array A. If PLACE = 'O' or 'o' (for out-of-place), the input data is stored in array B while the output is stored in A.

M (input) Integer specifying the number of rows to be transformed. It is most efficient when M is a product of small primes. $M \geq 0$; when $M = 0$, the subroutine returns immediately without changing any data.

N (input) Integer specifying the number of columns to be transformed. It is most most efficient when N is a product of small primes. $N \geq 0$; when $N = 0$, the subroutine returns immediately without changing any data.

A (input/output)

Real array of dimension (LDA,N). On entry, the two-dimensional array A(LDA,N) contains the input data to be transformed if an in-place transform is requested. Otherwise, it is not referenced. Upon exit, results are stored in A(1:M,1:N).

LDA (input)

Integer specifying the leading dimension of A. If an out-of-place transform is desired $LDA \geq M$. Else if an in-place transform is desired $LDA \geq 2*(M/2+1)$ and LDA must be even.

B (input/output)

Real array of dimension (2*LDB, N). On entry, if an out-of-place transform is requested B contains the input data. Otherwise, B is not referenced. B is unchanged upon exit.

LDB (input)

Integer. If an out-of-place transform is desired, $2*LDB$ is the leading dimension of the array B which contains the data to be transformed and $2*LDB \geq 2*(M/2+1)$. Otherwise it is not referenced.

WORK (input/output)

One-dimensional real array of length at least LWORK. On input, WORK must have been initialized by DFFT2I.

LWORK (input)

Integer. $LWORK \geq (M + 2*N + \text{MAX}(M, 2*N) + 30)$

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NAME

dffft2f - compute the Fourier coefficients of a periodic sequence. The DFFT operations are unnormalized, so a call of DFFFT2F followed by a call of DFFFT2B will multiply the input sequence by $M*N$.

SYNOPSIS

```
SUBROUTINE DFFFT2F(PLACE, FULL, M, N, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE, FULL  
INTEGER M, N, LDA, LDB, LWORK  
DOUBLE PRECISION A(LDA,*), B(2*LDB,*), WORK(*)
```

```
SUBROUTINE DFFFT2F_64(PLACE, FULL, M, N, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE, FULL  
INTEGER*8 M, N, LDA, LDB, LWORK  
DOUBLE PRECISION A(LDA,*), B(2*LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2F(PLACE, FULL, [M], [N], A, [LDA], B, [LDB], WORK,  
LWORK)
```

```
CHARACTER(LEN=1) :: PLACE, FULL  
INTEGER :: M, N, LDA, LDB, LWORK  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE FFT2F_64(PLACE, FULL, [M], [N], A, [LDA], B, [LDB], WORK,  
LWORK)
```

```
CHARACTER(LEN=1) :: PLACE, FULL  
INTEGER(8) :: M, N, LDA, LDB, LWORK  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dffft2f(char place, char full, int m, int n, double *a,  
int lda, double *b, int ldb, double *work, int  
lwork);
```

```
void dfft2f_64(char place, char full, long m, long n, double
    *a, long lda, double *b, long ldb, double *work,
    long lwork);
```

ARGUMENTS

PLACE (input)

Character. If PLACE = 'I' or 'i' (for in-place) , the input and output data are stored in array A. If PLACE = 'O' or 'o' (for out-of-place), the input data is stored in array B while the output is stored in A.

FULL (input)

Indicates whether or not to generate the full result matrix. 'F' or 'f' will cause DFFT2F to generate the full result matrix. Otherwise only a partial matrix that takes advantage of symmetry will be generated.

M (input) Integer specifying the number of rows to be transformed. It is most efficient when M is a product of small primes. $M \geq 0$; when $M = 0$, the subroutine returns immediately without changing any data.

N (input) Integer specifying the number of columns to be transformed. It is most most efficient when N is a product of small primes. $N \geq 0$; when $N = 0$, the subroutine returns immediately without changing any data.

A (input/output)

On entry, a two-dimensional array A(LDA,N) that contains the data to be transformed. Upon exit, A is unchanged if an out-of-place transform is done. If an in-place transform with partial result is requested, A(1:(M/2+1)*2,1:N) will contain the transformed results. If an in-place transform with full result is requested, A(1:2*M,1:N) will contain complete transformed results.

LDA (input)

Leading dimension of the array containing the data to be transformed. LDA must be even if the transformed sequences are to be stored in A.

If PLACE = ('O' or 'o') LDA \geq M

If PLACE = ('I' or 'i') LDA must be even. If FULL = ('F' or 'f'), LDA \geq 2*M

FULL is not ('F' or 'f'), LDA \geq (M/2+1)*2

B (input/output)

Upon exit, a two-dimensional array B(2*LDB,N) that contains the transformed results if an out-of-place transform is done. Otherwise, B is not

used.

If an out-of-place transform is done and FULL is not 'F' or 'f', B(1:(M/2+1)*2,1:N) will contain the partial transformed results. If FULL = 'F' or 'f', B(1:2*M,1:N) will contain the complete transformed results.

LDB (input)

2*LDB is the leading dimension of the array B. If an in-place transform is desired LDB is ignored.

If PLACE is ('O' or 'o') and

FULL is ('F' or 'f'), LDB >= M

FULL is not ('F' or 'f'), LDB >= M/2+1

Note that even though LDB is used in the argument list, 2*LDB is the actual leading dimension of B.

WORK (input/output)

One-dimensional real array of length at least LWORK. On input, WORK must have been initialized by DFFT2I.

LWORK (input)

Integer. LWORK >= (M + 2*N + MAX(M, 2*N) + 30)

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NAME

dffft2i - initialize the array WSAVE, which is used in both the forward and backward transforms.

SYNOPSIS

```
SUBROUTINE DFFT2I(M, N, WORK)
```

```
INTEGER M, N  
DOUBLE PRECISION WORK(*)
```

```
SUBROUTINE DFFT2I_64(M, N, WORK)
```

```
INTEGER*8 M, N  
DOUBLE PRECISION WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2I(M, N, WORK)
```

```
INTEGER :: M, N  
REAL(8), DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT2I_64(M, N, WORK)
```

```
INTEGER(8) :: M, N  
REAL(8), DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dffft2i(int m, int n, double *work);
```

```
void dffft2i_64(long m, long n, double *work);
```

ARGUMENTS

M (input) Number of rows to be transformed. M >= 0.

N (input) Number of columns to be transformed. N >= 0.

WORK (input/output)

On entry, an array of dimension $(M + 2*N + \text{MAX}(M, 2*N) + 30)$ or greater. DFFT2I needs to be called only once to initialize array WORK before calling DFFT2F and/or DFFT2B if M, N and WORK remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

dffft3b - compute a periodic sequence from its Fourier coefficients. The DFFT operations are unnormalized, so a call of DFFT3F followed by a call of DFFT3B will multiply the input sequence by $M*N*K$.

SYNOPSIS

```
SUBROUTINE DFFT3B(PLACE, M, N, K, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE  
INTEGER M, N, K, LDA, LDB, LWORK  
DOUBLE PRECISION A(LDA,N,*), B(2*LDB,N,*), WORK(*)
```

```
SUBROUTINE DFFT3B_64(PLACE, M, N, K, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE  
INTEGER*8 M, N, K, LDA, LDB, LWORK  
DOUBLE PRECISION A(LDA,N,*), B(2*LDB,N,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3B(PLACE, [M], [N], [K], A, [LDA], B, [LDB], WORK,  
LWORK)
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER :: M, N, K, LDA, LDB, LWORK  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:,:) :: A, B
```

```
SUBROUTINE FFT3B_64(PLACE, [M], [N], [K], A, [LDA], B, [LDB], WORK,  
LWORK)
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER(8) :: M, N, K, LDA, LDB, LWORK  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dffft3b(char place, int m, int n, int k, double *a, int  
lda, double *b, int ldb, double *work, int lwork);
```

```
void dfft3b_64(char place, long m, long n, long k, double
    *a, long lda, double *b, long ldb, double *work,
    long lwork);
```

ARGUMENTS

PLACE (input)

Select an in-place ('I' or 'i') or out-of-place ('O' or 'o') transform.

M (input) Integer specifying the number of rows to be transformed. It is most efficient when M is a product of small primes. $M \geq 0$; when $M = 0$, the subroutine returns immediately without changing any data.

N (input) Integer specifying the number of columns to be transformed. It is most efficient when N is a product of small primes. $N \geq 0$; when $N = 0$, the subroutine returns immediately without changing any data.

K (input) Integer specifying the number of planes to be transformed. It is most efficient when K is a product of small primes. $K \geq 0$; when $K = 0$, the subroutine returns immediately without changing any data.

A (input/output)

On entry, the three-dimensional array $A(LDA,N,K)$ contains the data to be transformed if an in-place transform is requested. Otherwise, it is not referenced. Upon exit, results are stored in $A(1:M,1:N,1:K)$.

LDA (input)

Integer specifying the leading dimension of A. If an out-of-place transform is desired $LDA \geq M$. Else if an in-place transform is desired $LDA \geq 2*(M/2+1)$.

B (input/output)

Real array of dimension $B(2*LDB,N,K)$. On entry, if an out-of-place transform is requested $B(1:2*(M/2+1),1:N,1:K)$ contains the input data. Otherwise, B is not referenced. B is unchanged upon exit.

LDB (input)

If an out-of-place transform is desired, $2*LDB$ is the leading dimension of the array B which contains the data to be transformed and $2*LDB \geq 2*(M/2+1)$. Otherwise it is not referenced.

WORK (input/output)

One-dimensional real array of length at least LWORK. On input, WORK must have been initialized by DFFT3I.

LWORK (input)

Integer. LWORK \geq (M + 2*(N + K) + 4*K + 45).

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NAME

dffft3f - compute the Fourier coefficients of a real periodic sequence. The DFFT operations are unnormalized, so a call of DFFT3F followed by a call of DFFT3B will multiply the input sequence by $M*N*K$.

SYNOPSIS

```
SUBROUTINE DFFT3F(PLACE, FULL, M, N, K, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE, FULL  
INTEGER M, N, K, LDA, LDB, LWORK  
DOUBLE PRECISION A(LDA,N,*), B(2*LDB,N,*), WORK(*)
```

```
SUBROUTINE DFFT3F_64(PLACE, FULL, M, N, K, A, LDA, B, LDB, WORK,  
LWORK)
```

```
CHARACTER * 1 PLACE, FULL  
INTEGER*8 M, N, K, LDA, LDB, LWORK  
DOUBLE PRECISION A(LDA,N,*), B(2*LDB,N,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3F(PLACE, FULL, [M], [N], [K], A, [LDA], B, [LDB],  
WORK, LWORK)
```

```
CHARACTER(LEN=1) :: PLACE, FULL  
INTEGER :: M, N, K, LDA, LDB, LWORK  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:,:) :: A, B
```

```
SUBROUTINE FFT3F_64(PLACE, FULL, [M], [N], [K], A, [LDA], B, [LDB],  
WORK, LWORK)
```

```
CHARACTER(LEN=1) :: PLACE, FULL  
INTEGER(8) :: M, N, K, LDA, LDB, LWORK  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dffft3f(char place, char full, int m, int n, int k, dou-  
ble *a, int lda, double *b, int ldb, double *work,
```

```

        int lwork);

void dfft3f_64(char place, char full, long m, long n, long
k, double *a, long lda, double *b, long ldb, double
*work, long lwork);

```

ARGUMENTS

PLACE (input)

Select an in-place ('I' or 'i') or out-of-place ('O' or 'o') transform.

FULL (input)

Select a full ('F' or 'f') or partial (' ') representation of the results. If the caller selects full representation then an MxNxK real array will transform to produce an MxNxK complex array. If the caller does not select full representation then an MxNxK real array will transform to a (M/2+1)xNxK complex array that takes advantage of the symmetry properties of a transformed real sequence.

M (input) Integer specifying the number of rows to be transformed. It is most efficient when M is a product of small primes. M >= 0; when M = 0, the subroutine returns immediately without changing any data.

N (input) Integer specifying the number of columns to be transformed. It is most efficient when N is a product of small primes. N >= 0; when N = 0, the subroutine returns immediately without changing any data.

K (input) Integer specifying the number of planes to be transformed. It is most efficient when K is a product of small primes. K >= 0; when K = 0, the subroutine returns immediately without changing any data.

A (input/output)

On entry, a three-dimensional array A(LDA,N,K) that contains input data to be transformed. On exit, if an in-place transform is done and FULL is not 'F' or 'f', A(1:2*(M/2+1),1:N,1:K) will contain the partial transformed results. If FULL = 'F' or 'f', A(1:2*M,1:N,1:K) will contain the complete transformed results.

LDA (input)

Leading dimension of the array containing the data to be transformed. LDA must be even if the transformed sequences are to be stored in A.

If PLACE = ('O' or 'o') LDA >= M

If PLACE = ('I' or 'i') LDA must be even. If

FULL = ('F' or 'f'), LDA \geq 2*M

FULL is not ('F' or 'f'), LDA \geq 2*(M/2+1)

B (input/output)

Upon exit, a three-dimensional array B(2*LDB,N,K) that contains the transformed results if an out-of-place transform is done. Otherwise, B is not used.

If an out-of-place transform is done and FULL is not 'F' or 'f', B(1:2*(M/2+1),1:N,1:K) will contain the partial transformed results. If FULL = 'F' or 'f', B(1:2*M,1:N,1:K) will contain the complete transformed results.

LDB (input)

2*LDB is the leading dimension of the array B. If an in-place transform is desired LDB is ignored.

If PLACE is ('O' or 'o') and

FULL is ('F' or 'f'), then LDB \geq M

FULL is not ('F' or 'f'), then LDB \geq M/2 + 1

Note that even though LDB is used in the argument list, 2*LDB is the actual leading dimension of B.

WORK (input/output)

One-dimensional real array of length at least LWORK. WORK must have been initialized by DFFT3I.

LWORK (input)

Integer. LWORK \geq (M + 2*(N + K) + 4*K + 45).

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NAME

dffft3i - initialize the array WSAVE, which is used in both DFFT3F and DFFT3B.

SYNOPSIS

```
SUBROUTINE DFFT3I(M, N, K, WORK)
```

```
INTEGER M, N, K  
DOUBLE PRECISION WORK(*)
```

```
SUBROUTINE DFFT3I_64(M, N, K, WORK)
```

```
INTEGER*8 M, N, K  
DOUBLE PRECISION WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3I(M, N, K, WORK)
```

```
INTEGER :: M, N, K  
REAL(8), DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT3I_64(M, N, K, WORK)
```

```
INTEGER(8) :: M, N, K  
REAL(8), DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dffft3i(int m, int n, int k, double *work);
```

```
void dffft3i_64(long m, long n, long k, double *work);
```

ARGUMENTS

M (input) Number of rows to be transformed. M >= 0.

N (input) Number of columns to be transformed. N >= 0.

K (input) Number of planes to be transformed. $K \geq 0$.

WORK (input/output)

On entry, an array of dimension $(M + 2*(N + K) + 30)$ or greater. DFFT3I needs to be called only once to initialize array WORK before calling DFFT3F and/or DFFT3B if M, N, K and WORK remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

dfftb - compute a periodic sequence from its Fourier coefficients. The DFFT operations are unnormalized, so a call of DFFTF followed by a call of DFFTB will multiply the input sequence by N.

SYNOPSIS

```
SUBROUTINE DFFTB(N, X, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION X(*), WSAVE(*)
```

```
SUBROUTINE DFFTB_64(N, X, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTB([N], X, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE FFTB_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dfftb(int n, double *x, double *wsave);
```

```
void dfftb_64(long n, double *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These

subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input) On entry, an array of length N containing the sequence to be transformed.

WSAVE (input)

On entry, WSAVE must be an array of dimension $(2 * N + 15)$ or greater and must have been initialized by DFFTI.

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NAME

dfftf - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of DFFTF followed by a call of DFFTB will multiply the input sequence by N.

SYNOPSIS

```
SUBROUTINE DFFTF(N, X, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION X(*), WSAVE(*)
```

```
SUBROUTINE DFFTF_64(N, X, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE F95_FFTF([N], X, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE F95_FFTF_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dfftf(int n, double *x, double *wsave);
```

```
void dfftf_64(long n, double *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These

subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input) On entry, an array of length N containing the sequence to be transformed.

WSAVE (input)

On entry, WSAVE must be an array of dimension $(2 * N + 15)$ or greater and must have been initialized by DFFTI.

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NAME

dffti - initialize the array WSAVE, which is used in both DFFTF and DFFTB.

SYNOPSIS

```
SUBROUTINE DFFTI(N, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION WSAVE(*)
```

```
SUBROUTINE DFFTI_64(N, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTI(N, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: WSAVE
```

```
SUBROUTINE FFTI_64(N, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dffti(int n, double *wsave);
```

```
void dffti_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array of dimension $(2 * N + 15)$ or greater. DFFTI needs to be called only once to initialize array WORK before calling DFFTF and/or DFFTB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

dfftopt - compute the length of the closest fast FFT

SYNOPSIS

```
INTEGER FUNCTION DFFTOPT(LEN)
```

```
INTEGER LEN
```

```
INTEGER*8 FUNCTION DFFTOPT_64(LEN)
```

```
INTEGER*8 LEN
```

F95 INTERFACE

```
INTEGER FUNCTION DFFTOPT(LEN)
```

```
INTEGER :: LEN
```

```
INTEGER(8) FUNCTION DFFTOPT_64(LEN)
```

```
INTEGER(8) :: LEN
```

C INTERFACE

```
#include <sunperf.h>
```

```
int dfftopt(int len);
```

```
long dfftopt_64(long len);
```

PURPOSE

dfftopt computes the length of the closest fast FFT. Fast Fourier transform algorithms, including those used in Performance Library, work best with vector lengths that are products of small primes. For example, an FFT of length $32=2**5$ will run faster than an FFT of prime length 31 because 32 is a product of small primes and 31 is not. If your application is such that you can taper or zero pad your vector to a larger length then this function may help you

select a better length and run your FFT faster.

DFFTOPT will return an integer no smaller than the input argument N that is the closest number that is the product of small primes. DFFTOPT will return 16 for an input of N=16 and return $18=2*3*3$ for an input of N=17.

Note that the length computed here is not guaranteed to be optimal, only to be a product of small primes. Also, the value returned may change as the underlying

FFTs become capable of handling larger primes. For example, passing in N=51 today will return $52=2*2*13$ rather than $51=3*17$ because the FFTs in Performance Library do not have fast radix 17 code. In the future, radix 17 code may be added

and then N=51 will return 51.

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NAME

dfftz - initialize the trigonometric weight and factor tables or compute the forward Fast Fourier Transform of a double precision sequence.

SYNOPSIS

```
SUBROUTINE DFFTZ(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX Y(*)  
DOUBLE PRECISION X(*), SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE DFFTZ_64(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX Y(*)  
DOUBLE PRECISION X(*), SCALE, TRIGS(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT  
INTEGER, INTENT(IN), OPTIONAL :: N, LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
REAL(8), INTENT(IN), DIMENSION(:) :: X  
COMPLEX(8), INTENT(OUT), DIMENSION(:) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT_64(IOPT, [N], [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT  
INTEGER(8), INTENT(IN), OPTIONAL :: N, LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
REAL(8), INTENT(IN), DIMENSION(:) :: X  
COMPLEX(8), INTENT(OUT), DIMENSION(:) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
```

```

INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>

void dffftz_ (int *iopt, int *n, double *scale, double *x,
             doublecomplex *y, double *trigs, int *ifac, double
             *work, int *lwork, int *ierr);

void dffftz_64_ (long *iopt, long *n, double *scale, double
                *x, doublecomplex *y, double *trigs, long *ifac,
                double *work, long *lwork, long *ierr);

```

PURPOSE

dffftz initializes the trigonometric weight and factor tables or computes the forward Fast Fourier Transform of a double precision sequence as follows:

$$Y(k) = \text{scale} * \sum_{j=0}^{N-1} W * X(j)$$

where

k ranges from 0 to N-1

i = sqrt(-1)

isign = -1 for forward transform

W = exp(isign*i*j*k*2*pi/N)

In real-to-complex transform of length N, the (N/2+1) complex output data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT

N (input)

Integer specifying length of the input sequence X. N is most efficient when it is a product of small primes. N >= 0. Unchanged on exit.

SCALE (input)

Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) On entry, X is a real array whose first N elements contain the sequence to be transformed.

Y (output)
Double complex array whose first $(N/2+1)$ elements contain the transform results. X and Y may be the same array starting at the same memory location, in which case the dimension of X must be at least $2*(N/2+1)$. Otherwise, it is assumed that there is no overlap between X and Y in memory.

TRIGS (input/output)
Double precision array of length $2*N$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = -1. Unchanged on exit.

IFAC (input/output)
Integer array of dimension at least 128 that contains the factors of N. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls where IOPT = -1. Unchanged on exit.

WORK (workspace)
Double precision array of dimension at least N. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)
Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)
On exit, integer IERR has one of the following values:
0 = normal return
-1 = IOPT is not 0 or -1
-2 = $N < 0$
-3 = (LWORK is not 0) and (LWORK is less than N)
-4 = memory allocation for workspace failed

SEE ALSO

fft

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NAME

dfftz2 - initialize the trigonometric weight and factor tables or compute the two-dimensional forward Fast Fourier Transform of a two-dimensional double precision array.

SYNOPSIS

```
SUBROUTINE DFFTZ2(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX Y(LDY, *)  
DOUBLE PRECISION X(LDX, *), SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE DFFTZ2_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX Y(LDY, *)  
DOUBLE PRECISION X(LDX, *), SCALE, TRIGS(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT  
INTEGER, INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
REAL(8), INTENT(IN), DIMENSION(:,:) :: X  
COMPLEX(8), INTENT(OUT), DIMENSION(:,:) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT2_64(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
REAL(8), INTENT(IN), DIMENSION(:,) :: X
COMPLEX(8), INTENT(OUT), DIMENSION(:,) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void dfftz2_(int *iopt, int *n1, int *n2, double *scale,
             double *x, int *ldx, doublecomplex *y, int *ldy,
             double *trigs, int *ifac, double *work, int
             *lwork, int *ierr);

void dfftz2_64_(long *iopt, long *n1, long *n2, double
               *scale, double *x, long *ldx, doublecomplex *y,
               long *ldy, double *trigs, long *ifac, double
               *work, long *lwork, long *ierr);

```

PURPOSE

dfftz2 initializes the trigonometric weight and factor tables or computes the two-dimensional forward Fast Fourier Transform of a two-dimensional double precision array. In computing the two-dimensional FFT, one-dimensional FFTs are computed along the columns of the input array. One-dimensional FFTs are then computed along the rows of the intermediate results.

$$Y(k_1, k_2) = \text{scale} * \sum_{j_2=0}^{N_2-1} \sum_{j_1=0}^{N_1-1} W_2 * W_1 * X(j_1, j_2)$$

where

k₁ ranges from 0 to N₁-1 and k₂ ranges from 0 to N₂-1

i = sqrt(-1)

isign = -1 for forward transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

In real-to-complex transform of length N₁, the (N₁/2+1) complex output data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table
 and factor table
 IOPT = -1 computes forward FFT

N1 (input)

Integer specifying length of the transform in the first dimension. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)

Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes N2 >= 0. Unchanged on exit.

SCALE (input)

Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) X is a double complex array of dimensions (LDX, N2) that contains input data to be transformed. X and Y can be the same array.

LDX (input)

Leading dimension of X. LDX >= N1 if X is not the same array as Y. Else, LDX = 2*LDY. Unchanged on exit.

Y (output)

Y is a double complex array of dimensions (LDY, N2) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)

Leading dimension of Y. LDY >= N1/2+1 Unchanged on exit.

TRIGS (input/output)

Double precision array of length 2*(N1+N2) that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = -1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 2*128 that contains the factors of N1 and N2. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = -1. Unchanged on exit.

WORK (workspace)

Double precision array of dimension at least MAX(N1, 2*N2) where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

0 = normal return

-1 = IOPT is not 0 or -1

-2 = $N1 < 0$

-3 = $N2 < 0$

-4 = ($LDX < N1$) or (LDX not equal $2*LDY$ when X and Y are same array)

-5 = ($LDY < N1/2+1$)

-6 = ($LWORK$ not equal 0) and ($LWORK < MAX(N1, 2*N2)$)

-7 = memory allocation failed

SEE ALSO

fft

CAUTIONS

On exit, output array $Y(1:LDY, 1:N2)$ is overwritten.

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NAME

dfftz3 - initialize the trigonometric weight and factor tables or compute the three-dimensional forward Fast Fourier Transform of a three-dimensional double complex array.

SYNOPSIS

```
SUBROUTINE DFFTZ3(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,
IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),
LWORK, IERR
DOUBLE COMPLEX Y(LDY1, LDY2, *)
DOUBLE PRECISION X(LDX1, LDX2, *), SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE DFFTZ3_64(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,
IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),
LWORK, IERR
DOUBLE COMPLEX Y(LDY1, LDY2, *)
DOUBLE PRECISION X(LDX1, LDX2, *), SCALE, TRIGS(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3(IOPT, [N1], [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1], LDY2,
TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT, LDX2, LDY2
INTEGER, INTENT(IN), OPTIONAL :: N1, N2, N3, LDX1, LDY1,
LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
REAL(8), INTENT(IN), DIMENSION(:,) :: X
COMPLEX(8), INTENT(OUT), DIMENSION(:,) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT3_64(IOPT, [N1], [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1],
```

```

LDY2, TRIGS,
        IFAC, WORK, [LWORK], IERR)

INTEGER(8), INTENT(IN) :: IOPT, LDX2, LDY2
INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, N3, LDX1, LDY1,
LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
REAL(8), INTENT(IN), DIMENSION(:,:) :: X
COMPLEX(8), INTENT(OUT), DIMENSION(:,:) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>

void dffftz3_ (int *iopt, int *n1, int *n2, int *n3, double
              *scale, double *x, int *ldx1, int *ldx2, doublecomplex
              *y, int *ldy1, int *ldy2, double *trigs,
              int *ifac, double *work, int *lwork, int *ierr);

void dffftz3_64_ (long *iopt, long *n1, long *n2, long *n3,
                 double *scale, double *x, long *ldx1, long *ldx2,
                 doublecomplex *y, long *ldy1, long *ldy2, double
                 *trigs, long *ifac, double *work, long *lwork,
                 long *ierr);

```

PURPOSE

dffftz3 initializes the trigonometric weight and factor tables or computes the three-dimensional forward Fast Fourier Transform of a three-dimensional double complex array.

$$Y(k_1, k_2, k_3) = \text{scale} * \sum_{j_3=0}^{N_3-1} \sum_{j_2=0}^{N_2-1} \sum_{j_1=0}^{N_1-1} W_3 * W_2 * W_1 * X(j_1, j_2, j_3)$$

where

k₁ ranges from 0 to N₁-1; k₂ ranges from 0 to N₂-1 and k₃ ranges from 0 to N₃-1

i = sqrt(-1)

isign = -1 for forward transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

W₃ = exp(isign*i*j₃*k₃*2*pi/N₃)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT

N1 (input)

Integer specifying length of the transform in the first dimension. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)

Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. N2 >= 0. Unchanged on exit.

N3 (input)

Integer specifying length of the transform in the third dimension. N3 is most efficient when it is a product of small primes. N3 >= 0. Unchanged on exit.

SCALE (input)

Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) X is a double precision array of dimensions (LDX1, LDX2, N3) that contains input data to be transformed. X can be same array as Y.

LDX1 (input)

first dimension of X. If X is not same array as Y, LDX1 >= N1 Else, LDX1 = 2*LDY1 Unchanged on exit.

LDX2 (input)

second dimension of X. LDX2 >= N2 Unchanged on exit.

Y (output)

Y is a double complex array of dimensions (LDY1, LDY2, N3) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY1 (input)

first dimension of Y. LDY1 >= N1/2+1 Unchanged on exit.

LDY2 (input)

second dimension of Y. If X and Y are the same array, LDY2 = LDX2 Else LDY2 >= N2 Unchanged on exit.

TRIGS (input/output)

Double precision array of length 2*(N1+N2+N3) that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = -1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 3×128 that contains the factors of N_1 , N_2 and N_3 . The factors are computed when the routine is called with $IOPT = 0$ and they are used in subsequent calls when $IOPT = -1$. Unchanged on exit.

WORK (workspace)

Double precision array of dimension at least $(\text{MAX}(N, 2 \times N_2, 2 \times N_3) + 16 \times N_3) \times \text{NCPUS}$ where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If $\text{LWORK} = 0$, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

0 = normal return

-1 = IOPT is not 0 or -1

-2 = $N_1 < 0$

-3 = $N_2 < 0$

-4 = $N_3 < 0$

-5 = ($\text{LDX}_1 < N_1$) or (LDX not equal $2 \times \text{LDY}$ when X and Y are same array)

-6 = ($\text{LDX}_2 < N_2$)

-7 = ($\text{LDY}_1 < N_1/2 + 1$)

-8 = ($\text{LDY}_2 < N_2$) or (LDY_2 not equal LDX_2 when X and Y are same array)

-9 = (LWORK not equal 0) and ($\text{LWORK} < (\text{MAX}(N, 2 \times N_2, 2 \times N_3) + 16 \times N_3)$)

-10 = memory allocation failed

SEE ALSO

fft

CAUTIONS

On exit, output subarray $Y(1:\text{LDY}_1, 1:N_2, 1:N_3)$ is overwritten.

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NAME

dffftzm - initialize the trigonometric weight and factor tables or compute the one-dimensional forward Fast Fourier Transform of a set of double precision data sequences stored in a two-dimensional array.

SYNOPSIS

```
SUBROUTINE DFFFTZM(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR
DOUBLE PRECISION X(LDX, *), SCALE, TRIGS(*), WORK(*)
DOUBLE COMPLEX Y(LDY, *)
```

```
SUBROUTINE DFFFTZM_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR
DOUBLE PRECISION X(LDX, *), SCALE, TRIGS(*), WORK(*)
DOUBLE COMPLEX Y(LDY, *)
```

F95 INTERFACE

```
SUBROUTINE FFTM(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT
INTEGER, INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
REAL(8), INTENT(IN), DIMENSION(:,:) :: X
COMPLEX(8), INTENT(OUT), DIMENSION(:,:) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFTM_64(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
REAL(8), INTENT(IN), DIMENSION(:,) :: X
COMPLEX(8), INTENT(OUT), DIMENSION(:,) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void dffftzm_ (int *iopt, int *m, int *n, double *scale, dou-
    ble *x, int *ldx, doublecomplex *y, int *ldy, dou-
    ble *trigs, int *ifac, double *work, int *lwork,
    int *ierr);

void dffftzm_64_ (long *iopt, long *m, long *n, double
    *scale, double *x, long *ldx, doublecomplex *y,
    long *ldy, double *trigs, long *ifac, double
    *work, long *lwork, long *ierr);

```

PURPOSE

dffftzm initializes the trigonometric weight and factor tables or computes the one-dimensional forward Fast Fourier Transform of a set of double precision data sequences stored in a two-dimensional array:

$$Y(k,l) = \text{scale} * \sum_{j=0}^{N1-1} W * X(j,l)$$

where

k ranges from 0 to N1-1 and l ranges from 0 to N2-1

i = sqrt(-1)

isign = -1 for forward transform

W = exp(isign*i*j*k*2*pi/N1)

In real-to-complex transform of length N1, the (N1/2+1) complex output data points stored are the positive-frequency half of the spectrum of the discrete Fourier transform. The other half can be obtained through complex conjugation and therefore is not stored.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT

N1 (input)

Integer specifying length of the input sequences. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)
Integer specifying number of input sequences. N2
 ≥ 0 . Unchanged on exit.

SCALE (input)
Double precision scalar by which transform results
are scaled. Unchanged on exit. SCALE is
defaulted to 1.0D0 for F95 INTERFACE.

X (input) X is a double precision array of dimensions (LDX,
N2) that contains the sequences to be transformed
stored in its columns.

LDX (input)
Leading dimension of X. If X and Y are the same
array, LDX = 2*LDY Else LDX \geq N1 Unchanged on
exit.

Y (output)
Y is a double complex array of dimensions (LDY,
N2) that contains the transform results of the
input sequences. X and Y can be the same array
starting at the same memory location, in which
case the input sequences are overwritten by their
transform results. Otherwise, it is assumed that
there is no overlap between X and Y in memory.

LDY (input)
Leading dimension of Y. LDY \geq N1/2 + 1 Unchanged
on exit.

TRIGS (input/output)
Double precision array of length 2*N1 that con-
tains the trigonometric weights. The weights are
computed when the routine is called with IOPT = 0
and they are used in subsequent calls when IOPT =
-1. Unchanged on exit.

IFAC (input/output)
Integer array of dimension at least 128 that con-
tains the factors of N1. The factors are computed
when the routine is called with IOPT = 0 and they
are used in subsequent calls when IOPT = -1.
Unchanged on exit.

WORK (workspace)
Double precision array of dimension at least N1.
The user can also choose to have the routine allo-
cate its own workspace (see LWORK).

LWORK (input)
Integer specifying workspace size. If LWORK = 0,
the routine will allocate its own workspace.

IERR (output)
On exit, integer IERR has one of the following
values:
0 = normal return
-1 = IOPT is not 0 or -1
-2 = N1 < 0
-3 = N2 < 0

-4 = (LDX < N1) or (LDX not equal 2*LDY when X and
Y are same array)
-4 = (LDY < N1/2 + 1)
-6 = (LWORK not equal 0) and (LWORK < N1)
-7 = memory allocation failed

SEE ALSO

fft

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NAME

dgbbbrd - reduce a real general m-by-n band matrix A to upper bidiagonal form B by an orthogonal transformation

SYNOPSIS

```
SUBROUTINE DGBBRD(VECT, M, N, NCC, KL, KU, AB, LDAB, D, E, Q, LDQ,  
PT, LDPT, C, LDC, WORK, INFO)
```

```
CHARACTER * 1 VECT  
INTEGER M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
DOUBLE PRECISION AB(LDAB,*), D(*), E(*), Q(LDQ,*),  
PT(LDPT,*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DGBBRD_64(VECT, M, N, NCC, KL, KU, AB, LDAB, D, E, Q, LDQ,  
PT, LDPT, C, LDC, WORK, INFO)
```

```
CHARACTER * 1 VECT  
INTEGER*8 M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
DOUBLE PRECISION AB(LDAB,*), D(*), E(*), Q(LDQ,*),  
PT(LDPT,*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBBRD(VECT, M, [N], [NCC], KL, KU, AB, [LDAB], D, E, Q,  
[LDQ], PT, [LDPT], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT  
INTEGER :: M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:,:) :: AB, Q, PT, C
```

```
SUBROUTINE GBBRD_64(VECT, M, [N], [NCC], KL, KU, AB, [LDAB], D, E,  
Q, [LDQ], PT, [LDPT], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT  
INTEGER(8) :: M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:,:) :: AB, Q, PT, C
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dgbbrd(char vect, int m, int n, int ncc, int kl, int
    ku, double *ab, int ldab, double *d, double *e,
    double *q, int ldq, double *pt, int ldpt, double
    *c, int ldc, int *info);
void dgbbrd_64(char vect, long m, long n, long ncc, long kl,
    long ku, double *ab, long ldab, double *d, double
    *e, double *q, long ldq, double *pt, long ldpt,
    double *c, long ldc, long *info);

```

PURPOSE

dgbbrd reduces a real general m-by-n band matrix A to upper bidiagonal form B by an orthogonal transformation: $Q' * A * P = B$.

The routine computes B, and optionally forms Q or P', or computes $Q'*C$ for a given matrix C.

ARGUMENTS

VECT (input)

Specifies whether or not the matrices Q and P' are to be formed. = 'N': do not form Q or P';
 = 'Q': form Q only;
 = 'P': form P' only;
 = 'B': form both.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NCC (input)

The number of columns of the matrix C. $NCC \geq 0$.

KL (input)

The number of subdiagonals of the matrix A. $KL \geq 0$.

KU (input)

The number of superdiagonals of the matrix A. $KU \geq 0$.

AB (input/output)

DOUBLE PRECISION array, dimension(LDAB,N) On entry, the m-by-n band matrix A, stored in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array AB as follows:
 $AB(ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$. On exit, A is overwritten by values generated during the reduction.

LDAB (input)

The leading dimension of the array A. $LDAB \geq KL+KU+1$.

D (output)
 DOUBLE PRECISION array, dimension(min(M,N)) The diagonal elements of the bidiagonal matrix B.

E (output)
 DOUBLE PRECISION array, dimension(min(M,N)-1) The superdiagonal elements of the bidiagonal matrix B.

Q (output)
 DOUBLE PRECISION array, dimension(LDQ,M) If VECT = 'Q' or 'B', the m-by-m orthogonal matrix Q. If VECT = 'N' or 'P', the array Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. LDQ >= max(1,M) if VECT = 'Q' or 'B'; LDQ >= 1 otherwise.

PT (output)
 DOUBLE PRECISION array, dimension(LDPT,N) If VECT = 'P' or 'B', the n-by-n orthogonal matrix P'. If VECT = 'N' or 'Q', the array PT is not referenced.

LDPT (input)
 The leading dimension of the array PT. LDPT >= max(1,N) if VECT = 'P' or 'B'; LDPT >= 1 otherwise.

C (input/output)
 DOUBLE PRECISION array, dimension(LDC,NCC) On entry, an m-by-ncc matrix C. On exit, C is overwritten by Q'*C. C is not referenced if NCC = 0.

LDC (input)
 The leading dimension of the array C. LDC >= max(1,M) if NCC > 0; LDC >= 1 if NCC = 0.

WORK (workspace)
 DOUBLE PRECISION array, dimension(2*MAX(M,N))

INFO (output)
 = 0: successful exit.
 < 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

dgbcn - estimate the reciprocal of the condition number of a real general band matrix A, in either the 1-norm or the infinity-norm,

SYNOPSIS

```
SUBROUTINE DGBCON(NORM, N, KL, KU, A, LDA, IPIVOT, ANORM,  
                  RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM  
INTEGER N, KL, KU, LDA, INFO  
INTEGER IPIVOT(*), WORK2(*)  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DGBCON_64(NORM, N, KL, KU, A, LDA, IPIVOT, ANORM,  
                    RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM  
INTEGER*8 N, KL, KU, LDA, INFO  
INTEGER*8 IPIVOT(*), WORK2(*)  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBCON(NORM, [N], KL, KU, A, [LDA], IPIVOT, ANORM,  
                RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM  
INTEGER :: N, KL, KU, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, WORK2  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GBCON_64(NORM, [N], KL, KU, A, [LDA], IPIVOT, ANORM,  
                   RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM  
INTEGER(8) :: N, KL, KU, LDA, INFO
```

```
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
void dgbcon(char norm, int n, int kl, int ku, double *a, int
            lda, int *ipivot, double anorm, double *rcond, int
            *info);

void dgbcon_64(char norm, long n, long kl, long ku, double
               *a, long lda, long *ipivot, double anorm, double
               *rcond, long *info);
```

PURPOSE

dgbcon estimates the reciprocal of the condition number of a real general band matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by DGBTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A)))$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)

The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)

The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input) Details of the LU factorization of the band matrix A, as computed by DGBTRF. U is stored as an upper triangular band matrix with $KL+KU$ superdiagonals in rows 1 to $KL+KU+1$, and the multipliers used during the factorization are stored in rows $KL+KU+2$ to $2*KL+KU+1$.

LDA (input)

The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (input)

The pivot indices; for $1 \leq i \leq N$, row i of the matrix was interchanged with row $IPIVOT(i)$.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension (N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dgbequ - compute row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number

SYNOPSIS

```
SUBROUTINE DGBEQU(M, N, KL, KU, A, LDA, R, C, ROWCND,  
COLCND, AMAX, INFO)
```

```
INTEGER M, N, KL, KU, LDA, INFO  
DOUBLE PRECISION ROWCND, COLCND, AMAX  
DOUBLE PRECISION A(LDA,*), R(*), C(*)
```

```
SUBROUTINE DGBEQU_64(M, N, KL, KU, A, LDA, R, C, ROWCND,  
COLCND, AMAX, INFO)
```

```
INTEGER*8 M, N, KL, KU, LDA, INFO  
DOUBLE PRECISION ROWCND, COLCND, AMAX  
DOUBLE PRECISION A(LDA,*), R(*), C(*)
```

F95 INTERFACE

```
SUBROUTINE GBEQU([M], [N], KL, KU, A, [LDA], R, C,  
ROWCND, COLCND, AMAX, [INFO])
```

```
INTEGER :: M, N, KL, KU, LDA, INFO  
REAL(8) :: ROWCND, COLCND, AMAX  
REAL(8), DIMENSION(:) :: R, C  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GBEQU_64([M], [N], KL, KU, A, [LDA], R, C,  
ROWCND, COLCND, AMAX, [INFO])
```

```
INTEGER(8) :: M, N, KL, KU, LDA, INFO  
REAL(8) :: ROWCND, COLCND, AMAX  
REAL(8), DIMENSION(:) :: R, C  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgbequ(int m, int n, int kl, int ku, double *a, int
           lda, double *r, double *c, double *rowcnd, double
           *colcnd, double *amax, int *info);
```

```
void dgbequ_64(long m, long n, long kl, long ku, double *a,
              long lda, double *r, double *c, double *rowcnd,
              double *colcnd, double *amax, long *info);
```

PURPOSE

dgbequ computes row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number. R returns the row scale factors and C the column scale factors, chosen to try to make the largest element in each row and column of the matrix B with elements $B(i,j)=R(i)*A(i,j)*C(j)$ have absolute value 1.

R(i) and C(j) are restricted to be between SMLNUM = smallest safe number and BIGNUM = largest safe number. Use of these scaling factors is not guaranteed to reduce the condition number of A but works well in practice.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input) The band matrix A, stored in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array A as follows: $A(ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$.

LDA (input)
The leading dimension of the array A. $LDA \geq KL+KU+1$.

R (output)
If $INFO = 0$, or $INFO > M$, R contains the row scale factors for A.

C (output)
If $INFO = 0$, C contains the column scale factors for A.

ROWCND (output)
If $INFO = 0$ or $INFO > M$, ROWCND contains the ratio of the smallest R(i) to the largest R(i). If $ROWCND \geq 0.1$ and AMAX is neither too large nor

too small, it is not worth scaling by R.

COLCND (output)

If INFO = 0, COLCND contains the ratio of the smallest C(i) to the largest C(i). If COLCND >= 0.1, it is not worth scaling by C.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= M: the i-th row of A is exactly zero
> M: the (i-M)-th column of A is exactly zero

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NAME

dgbbmv - perform one of the matrix-vector operations $y := \alpha A x + \beta y$ or $y := \alpha A' x + \beta y$

SYNOPSIS

```
SUBROUTINE DGBMV(TRANSA, M, N, KL, KU, ALPHA, A, LDA, X, INCX,
                 BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA
INTEGER M, N, KL, KU, LDA, INCX, INCY
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION A(LDA,*), X(*), Y(*)
```

```
SUBROUTINE DGBMV_64(TRANSA, M, N, KL, KU, ALPHA, A, LDA, X,
                   INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA
INTEGER*8 M, N, KL, KU, LDA, INCX, INCY
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION A(LDA,*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE GBMV([TRANSA], [M], [N], KL, KU, ALPHA, A, [LDA], X,
               [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER :: M, N, KL, KU, LDA, INCX, INCY
REAL(8) :: ALPHA, BETA
REAL(8), DIMENSION(:) :: X, Y
REAL(8), DIMENSION(:,) :: A
```

```
SUBROUTINE GBMV_64([TRANSA], [M], [N], KL, KU, ALPHA, A, [LDA],
                  X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER(8) :: M, N, KL, KU, LDA, INCX, INCY
REAL(8) :: ALPHA, BETA
REAL(8), DIMENSION(:) :: X, Y
REAL(8), DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>

void dgbmv(char transa, int m, int n, int kl, int ku, double
           alpha, double *a, int lda, double *x, int incx,
           double beta, double *y, int incy);
void dgbmv_64(char transa, long m, long n, long kl, long ku,
              double alpha, double *a, long lda, double *x, long
              incx, double beta, double *y, long incy);
```

PURPOSE

dgbmv performs one of the matrix-vector operations $y := \alpha A x + \beta y$ or $y := \alpha A' x + \beta y$, where α and β are scalars, x and y are vectors and A is an m by n band matrix, with kl sub-diagonals and ku super-diagonals.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $y := \alpha A x + \beta y$.

TRANSA = 'T' or 't' $y := \alpha A' x + \beta y$.

TRANSA = 'C' or 'c' $y := \alpha A' x + \beta y$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

KL (input)

On entry, KL specifies the number of sub-diagonals of the matrix A. $KL \geq 0$. Unchanged on exit.

KU (input)

On entry, KU specifies the number of super-diagonals of the matrix A. $KU \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry, the leading $(kl + ku + 1)$ by n

part of the array A must contain the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (ku + 1) of the array, the first super-diagonal starting at position 2 in row ku, the first sub-diagonal starting at position 1 in row (ku + 2), and so on. Elements in the array A that do not correspond to elements in the band matrix (such as the top left ku by ku triangle) are not referenced. The following program segment will transfer a band matrix from conventional full matrix storage to band storage:

```

      DO 20, J = 1, N
        K = KU + 1 - J
        DO 10, I = MAX( 1, J - KU ), MIN( M, J + KL )
          A( K + I, J ) = matrix( I, J )
10     CONTINUE
20    CONTINUE

```

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= (kl + ku + 1). Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)) when TRANSA = 'N' or 'n' and at least (1 + (m - 1) * abs(INCX)) otherwise. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX <> 0. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

(1 + (m - 1) * abs(INCY)) when TRANSA = 'N' or 'n' and at least (1 + (n - 1) * abs(INCY)) otherwise. Before entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

dgbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE DGBRFS(TRANSA, N, KL, KU, NRHS, A, LDA, AF, LDAF,
  IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DGBRFS_64(TRANSA, N, KL, KU, NRHS, A, LDA, AF, LDAF,
  IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER*8 N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBRFS([TRANSA], [N], KL, KU, [NRHS], A, [LDA], AF,
  [LDAF], IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2],
  [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:,:) :: A, AF, B, X
```

```
SUBROUTINE GBRFS_64([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  AF, [LDAF], IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
  [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: TRANSA
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, AF, B, X
C INTERFACE
#include <sunperf.h>

void dgbrfs(char transa, int n, int kl, int ku, int nrhs,
            double *a, int lda, double *af, int ldaf, int
            *ipivot, double *b, int ldb, double *x, int ldx,
            double *ferr, double *berr, int *info);

void dgbrfs_64(char transa, long n, long kl, long ku, long
              nrhs, double *a, long lda, double *af, long ldaf,
              long *ipivot, double *b, long ldb, double *x, long
              ldx, double *ferr, double *berr, long *info);

```

PURPOSE

dgbrfs improves the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)
 Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)
 The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
 The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The original band matrix A, stored in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array A as follows: $A(ku+1+i-j, j) = A(i, j)$ for $\max(1, j-ku) \leq i \leq \min(n, j+kl)$.

LDA (input)

The leading dimension of the array A. LDA \geq KL+KU+1.

AF (input)

Details of the LU factorization of the band matrix A, as computed by DGBTRF. U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1.

LDAF (input)

The leading dimension of the array AF. LDAF \geq 2*KL*KU+1.

IPIVOT (input)

The pivot indices from DGBTRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)

On entry, the solution matrix X, as computed by DGBTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dgbsv - compute the solution to a real system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE DGBSV(N, KL, KU, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
INTEGER N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DGBSV_64(N, KL, KU, NRHS, A, LDA, IPIVOT, B, LDB,  
INFO)
```

```
INTEGER*8 N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GBSV([N], KL, KU, [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
INTEGER :: N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GBSV_64([N], KL, KU, [NRHS], A, [LDA], IPIVOT, B,  
[LDB], [INFO])
```

```
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dgbsv(int n, int kl, int ku, int nrhs, double *a, int
           lda, int *ipivot, double *b, int ldb, int *info);

void dgbsv_64(long n, long kl, long ku, long nrhs, double
              *a, long lda, long *ipivot, double *b, long ldb,
              long *info);

```

PURPOSE

dgbsv computes the solution to a real system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices.

The LU decomposition with partial pivoting and row interchanges is used to factor A as $A = L * U$, where L is a product of permutation and unit lower triangular matrices with KL subdiagonals, and U is upper triangular with KL+KU superdiagonals. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A. $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A. $KU \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array A as follows:

$$A(KL+KU+1+i-j, j) = A(i, j) \quad \text{for } \max(1, j-KU) \leq i \leq \min(N, j+KL)$$
 On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDA (input)
The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (output)
The pivot indices that define the permutation

matrix P; row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)

On entry, the N-by-NRHS right hand side matrix B.
On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and the solution has not been computed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when M = N = 6, KL = 2, KU = 1:

On entry:

On exit:

	*	*	*	+	+	+		*	*	*	u14	u25	
u36													
	*	*	+	+	+	+		*	*		u13	u24	u35
u46													
	*	a12	a23	a34	a45	a56		*	u12	u23	u34	u45	
u56													
	a11	a22	a33	a44	a55	a66		u11	u22	u33	u44	u55	
u66													
	a21	a32	a43	a54	a65	*		m21	m32	m43	m54	m65	
*													
	a31	a42	a53	a64	*	*		m31	m42	m53	m64	*	
*													

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U because of fill-in resulting from the row interchanges.

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NAME

dgbsvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE DGBSVX(FACT, TRANSA, N, KL, KU, NRHS, A, LDA, AF,
  LDAF, IPIVOT, EQUED, R, C, B, LDB, X, LDX, RCOND, FERR,
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
INTEGER N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), R(*), C(*), B(LDB,*),
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DGBSVX_64(FACT, TRANSA, N, KL, KU, NRHS, A, LDA, AF,
  LDAF, IPIVOT, EQUED, R, C, B, LDB, X, LDX, RCOND, FERR,
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
INTEGER*8 N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), R(*), C(*), B(LDB,*),
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBSVX(FACT, [TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  AF, [LDAF], IPIVOT, EQUED, R, C, B, [LDB], X, [LDX],
  RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
INTEGER :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: R, C, FERR, BERR, WORK
REAL(8), DIMENSION(:,:) :: A, AF, B, X
```

```

SUBROUTINE GBSVX_64(FACT, [TRANSA], [N], KL, KU, [NRHS], A,
  [LDA], AF, [LDAF], IPIVOT, EQUED, R, C, B, [LDB], X, [LDX],
  RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: R, C, FERR, BERR, WORK
REAL(8), DIMENSION(:,:) :: A, AF, B, X

```

C INTERFACE

```

#include <sunperf.h>

```

```

void dgbsvx(char fact, char transa, int n, int kl, int ku,
  int nrhs, double *a, int lda, double *af, int
  ldaf, int *ipivot, char equed, double *r, double
  *c, double *b, int ldb, double *x, int ldx, double
  *rcond, double *ferr, double *berr, int *info);

```

```

void dgbsvx_64(char fact, char transa, long n, long kl, long
  ku, long nrhs, double *a, long lda, double *af,
  long ldaf, long *ipivot, char equed, double *r,
  double *c, double *b, long ldb, double *x, long
  ldx, double *rcond, double *ferr, double *berr,
  long *info);

```

PURPOSE

dgbsvx uses the LU factorization to compute the solution to a real system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed by this subroutine:

1. If FACT = 'E', real scaling factors are computed to equilibrate

the system:

TRANS = 'N': $\text{diag}(R) * A * \text{diag}(C) * \text{inv}(\text{diag}(C)) * X = \text{diag}(R) * B$

TRANS = 'T': $(\text{diag}(R) * A * \text{diag}(C))^{**T} * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

TRANS = 'C': $(\text{diag}(R) * A * \text{diag}(C))^{**H} * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A, but if equilibration is used, A is

overwritten by $\text{diag}(R) * A * \text{diag}(C)$ and B by $\text{diag}(R) * B$ (if TRANS='N')

or $\text{diag}(C) * B$ (if TRANS = 'T' or 'C').

2. If FACT = 'N' or 'E', the LU decomposition is used to

factor the
matrix A (after equilibration if FACT = 'E') as
 $A = L * U$,
where L is a product of permutation and unit lower triangular
matrices with KL subdiagonals, and U is upper triangular
with
KL+KU superdiagonals.

3. If some $U(i,i)=0$, so that U is exactly singular, then the routine
returns with INFO = i. Otherwise, the factored form of A
is used

to estimate the condition number of the matrix A. If the
reciprocal of the condition number is less than machine
precision,

INFO = N+1 is returned as a warning, but the routine
still goes on

to solve for X and compute error bounds as described
below.

4. The system of equations is solved for X using the fac-
tored form
of A.

5. Iterative refinement is applied to improve the computed
solution

matrix and calculate error bounds and backward error
estimates
for it.

6. If equilibration was used, the matrix X is premultiplied
by

diag(C) (if TRANS = 'N') or diag(R) (if TRANS = 'T' or
'C') so

that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the
matrix A is supplied on entry, and if not, whether
the matrix A should be equilibrated before it is
factored. = 'F': On entry, AF and IPIVOT contain
the factored form of A. If EQUED is not 'N', the
matrix A has been equilibrated with scaling fac-
tors given by R and C. A, AF, and IPIVOT are not
modified. = 'N': The matrix A will be copied to
AF and factored.

= 'E': The matrix A will be equilibrated if
necessary, then copied to AF and factored.

TRANSA (input)

Specifies the form of the system of equations. =

'N': $A * X = B$ (No transpose)

= 'T': $A^{**T} * X = B$ (Transpose)

= 'C': $A^{**H} * X = B$ (Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A. $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A. $KU \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)
On entry, the matrix A in band storage, in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array A as follows: $A(KU+1+i-j, j) = A(i, j)$ for $\max(1, j-KU) \leq i \leq \min(N, j+KL)$

If FACT = 'F' and EQUED is not 'N', then A must have been equilibrated by the scaling factors in R and/or C. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if EQUED .ne. 'N', A is scaled as follows:
EQUED = 'R': $A := \text{diag}(R) * A$
EQUED = 'C': $A := A * \text{diag}(C)$
EQUED = 'B': $A := \text{diag}(R) * A * \text{diag}(C)$.

LDA (input)
The leading dimension of the array A. $LDA \geq KL+KU+1$.

AF (input or output)
If FACT = 'F', then AF is an input argument and on entry contains details of the LU factorization of the band matrix A, as computed by DGBTRF. U is stored as an upper triangular band matrix with $KL+KU$ superdiagonals in rows 1 to $KL+KU+1$, and the multipliers used during the factorization are stored in rows $KL+KU+2$ to $2*KL+KU+1$. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns details of the LU factorization of A.

If FACT = 'E', then AF is an output argument and on exit returns details of the LU factorization of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)
The leading dimension of the array AF. $LDAF \geq 2*KL+KU+1$.

IPIVOT (input)
If FACT = 'F', then IPIVOT is an input argument

and on entry contains the pivot indices from the factorization $A = L*U$ as computed by DGBTRF; row i of the matrix was interchanged with row $IPIVOT(i)$.

If $FACT = 'N'$, then $IPIVOT$ is an output argument and on exit contains the pivot indices from the factorization $A = L*U$ of the original matrix A .

If $FACT = 'E'$, then $IPIVOT$ is an output argument and on exit contains the pivot indices from the factorization $A = L*U$ of the equilibrated matrix A .

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if $FACT = 'N'$).
= 'R': Row equilibration, i.e., A has been premultiplied by $diag(R)$.
= 'C': Column equilibration, i.e., A has been postmultiplied by $diag(C)$.
= 'B': Both row and column equilibration, i.e., A has been replaced by $diag(R) * A * diag(C)$.
EQUED is an input argument if $FACT = 'F'$; otherwise, it is an output argument.

R (input or output)

The row scale factors for A . If $EQUED = 'R'$ or $'B'$, A is multiplied on the left by $diag(R)$; if $EQUED = 'N'$ or $'C'$, R is not accessed. R is an input argument if $FACT = 'F'$; otherwise, R is an output argument. If $FACT = 'F'$ and $EQUED = 'R'$ or $'B'$, each element of R must be positive.

C (input or output)

The column scale factors for A . If $EQUED = 'C'$ or $'B'$, A is multiplied on the right by $diag(C)$; if $EQUED = 'N'$ or $'R'$, C is not accessed. C is an input argument if $FACT = 'F'$; otherwise, C is an output argument. If $FACT = 'F'$ and $EQUED = 'C'$ or $'B'$, each element of C must be positive.

B (input/output)

On entry, the right hand side matrix B . On exit, if $EQUED = 'N'$, B is not modified; if $TRANS = 'N'$ and $EQUED = 'R'$ or $'B'$, B is overwritten by $diag(R)*B$; if $TRANS = 'T'$ or $'C'$ and $EQUED = 'C'$ or $'B'$, B is overwritten by $diag(C)*B$.

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

X (output)

If $INFO = 0$ or $INFO = N+1$, the N -by- $NRHS$ solution matrix X to the original system of equations. Note that A and B are modified on exit if $EQUED \neq 'N'$, and the solution to the equilibrated system is $inv(diag(C))*X$ if $TRANS = 'N'$ and $EQUED = 'C'$ or $'B'$, or $inv(diag(R))*X$ if $TRANS = 'T'$ or $'C'$ and $EQUED = 'R'$ or $'B'$.

LDX (input)

The leading dimension of the array X. $LDX \geq \max(1, N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N) On exit, WORK(1) contains the reciprocal pivot growth factor $\text{norm}(A)/\text{norm}(U)$. The "max absolute element" norm is used. If WORK(1) is much less than 1, then the stability of the LU factorization of the (equilibrated) matrix A could be poor. This also means that the solution X, condition estimator RCOND, and forward error bound FERR could be unreliable. If factorization fails with $0 < \text{INFO} \leq N$, then WORK(1) contains the reciprocal pivot growth factor for the leading INFO columns of A.

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned.
= N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

dgbtbf2 - compute an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE DGBTF2(M, N, KL, KU, AB, LDAB, IPIV, INFO)
```

```
INTEGER M, N, KL, KU, LDAB, INFO  
INTEGER IPIV(*)  
DOUBLE PRECISION AB(LDAB,*)
```

```
SUBROUTINE DGBTF2_64(M, N, KL, KU, AB, LDAB, IPIV, INFO)
```

```
INTEGER*8 M, N, KL, KU, LDAB, INFO  
INTEGER*8 IPIV(*)  
DOUBLE PRECISION AB(LDAB,*)
```

F95 INTERFACE

```
SUBROUTINE GBTF2([M], [N], KL, KU, AB, [LDAB], IPIV, [INFO])
```

```
INTEGER :: M, N, KL, KU, LDAB, INFO  
INTEGER, DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:, :) :: AB
```

```
SUBROUTINE GBTF2_64([M], [N], KL, KU, AB, [LDAB], IPIV, [INFO])
```

```
INTEGER(8) :: M, N, KL, KU, LDAB, INFO  
INTEGER(8), DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:, :) :: AB
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgbtf2(int m, int n, int kl, int ku, double *ab, int  
           ldab, int *ipiv, int *info);
```

```
void dgbtf2_64(long m, long n, long kl, long ku, double *ab,  
              long ldab, long *ipiv, long *info);
```

PURPOSE

dgbtbf2 computes an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

AB (input/output)
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array AB as follows:
 $AB(kl+ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$

On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDAB (input)
The leading dimension of the array AB. $LDAB \geq 2*KL+KU+1$.

IPIV (output)
The pivot indices; for $1 \leq i \leq \min(M,N)$, row i of the matrix was interchanged with row IPIV(i).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = +i, U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $M = N = 6$, $KL = 2$, $KU = 1$:

On entry:	On exit:
* * * + + +	* * * u14 u25
u36	
* * + + + +	* * u13 u24 u35
u46	
* a12 a23 a34 a45 a56	* u12 u23 u34 u45
u56	
a11 a22 a33 a44 a55 a66	u11 u22 u33 u44 u55
u66	
a21 a32 a43 a54 a65 *	m21 m32 m43 m54 m65
*	
a31 a42 a53 a64 * *	m31 m42 m53 m64 *
*	

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U, because of fill-in resulting from the row interchanges.

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NAME

dgbtrf - compute an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE DGBTRF(M, N, KL, KU, A, LDA, IPIVOT, INFO)
```

```
INTEGER M, N, KL, KU, LDA, INFO  
INTEGER IPIVOT(MIN(M,N))  
DOUBLE PRECISION A(LDA,N)
```

```
SUBROUTINE DGBTRF_64(M, N, KL, KU, A, LDA, IPIVOT, INFO)
```

```
INTEGER*8 M, N, KL, KU, LDA, INFO  
INTEGER*8 IPIVOT(N)  
DOUBLE PRECISION A(LDA,N)
```

F95 INTERFACE

```
SUBROUTINE GBTRF(M, [N], KL, KU, A, [LDA], IPIVOT, [INFO])
```

```
INTEGER :: M, N, KL, KU, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GBTRF_64(M, [N], KL, KU, A, [LDA], IPIVOT, [INFO])
```

```
INTEGER(8) :: M, N, KL, KU, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgbtrf(int m, int n, int kl, int ku, double *a, int  
lda, int *ipivot, int *info);
```

```
void dgbtrf_64(long m, long n, long kl, long ku, double *a,  
long lda, long *ipivot, long *info);
```

PURPOSE

dgbrtf computes an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

M (input) Integer
The number of rows of the matrix A. $M \geq 0$.

N (input) Integer
The number of columns of the matrix A. $N \geq 0$.

KL (input) Integer
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input) Integer
The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input/output) Double precision array of dimension (LDA,N).
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array A as follows:
 $A(KL+KU+1+I-J, J) = A(I, J)$ for $\text{MAX}(1, J-KU) \leq I \leq \text{MIN}(M, J+KL)$

On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDA (input) Integer array of dimension MIN(M,N)
The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (output) Integer array of dimension MIN(M,N)
The pivot indices; for $1 \leq I \leq \text{MIN}(M, N)$, row I of the matrix was interchanged with row IPIVOT(I).

INFO (output) Integer
= 0: successful exit
< 0: if INFO = -I, the I-th argument had an illegal value
> 0: if INFO = +I, U(I,I) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equa-

tions.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $M = N = 6$, $KL = 2$, $KU = 1$:

On entry:						On exit:					
* * *	+	+	+			* * *	u14	u25			
u36	* *	+	+	+	+	* *	u13	u24	u35		
u46	* a12	a23	a34	a45	a56	* u12	u23	u34	u45		
u56	a11	a22	a33	a44	a55	a66	u11	u22	u33	u44	u55
u66	a21	a32	a43	a54	a65	*	m21	m32	m43	m54	m65
*	a31	a42	a53	a64	*	*	m31	m42	m53	m64	*
*											

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U because of fill-in resulting from the row interchanges.

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NAME

dgbtrs - solve a system of linear equations $A * X = B$ or $A' * X = B$ with a general band matrix A using the LU factorization computed by DGBTRF

SYNOPSIS

```
SUBROUTINE DGBTRS(TRANSA, N, KL, KU, NRHS, A, LDA, IPIVOT, B,
  LDB, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DGBTRS_64(TRANSA, N, KL, KU, NRHS, A, LDA, IPIVOT,
  B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER*8 N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GBTRS([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE GBTRS_64([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>

void dgbtrs(char transa, int n, int kl, int ku, int nrhs,
            double *a, int lda, int *ipivot, double *b, int
            ldb, int *info);
void dgbtrs_64(char transa, long n, long kl, long ku, long
               nrhs, double *a, long lda, long *ipivot, double
               *b, long ldb, long *info);
```

PURPOSE

dgbtrs solves a system of linear equations
 $A * X = B$ or $A' * X = B$ with a general band matrix A
 using the LU factorization computed by DGBTRF.

ARGUMENTS

TRANSA (input)
 Specifies the form of the system of equations. =
 'N': $A * X = B$ (No transpose)
 = 'T': $A' * X = B$ (Transpose)
 = 'C': $A' * X = B$ (Conjugate transpose = Tran-
 sponse)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)
 The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
 The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number
 of columns of the matrix B. $NRHS \geq 0$.

A (input) Details of the LU factorization of the band matrix
 A, as computed by DGBTRF. U is stored as an upper
 triangular band matrix with $KL+KU$ superdiagonals
 in rows 1 to $KL+KU+1$, and the multipliers used
 during the factorization are stored in rows
 $KL+KU+2$ to $2*KL+KU+1$.

LDA (input)
 The leading dimension of the array A. $LDA \geq$
 $2*KL+KU+1$.

IPIVOT (input)
 The pivot indices; for $1 \leq i \leq N$, row i of the
 matrix was interchanged with row IPIVOT(i).

B (input/output)
 On entry, the right hand side matrix B. On exit,

the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

dgebak - form the right or left eigenvectors of a real general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by DGBAL

SYNOPSIS

```
SUBROUTINE DGEBAK(JOB, SIDE, N, ILO, IHI, SCALE, M, V, LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE  
INTEGER N, ILO, IHI, M, LDV, INFO  
DOUBLE PRECISION SCALE(*), V(LDV,*)
```

```
SUBROUTINE DGEBAK_64(JOB, SIDE, N, ILO, IHI, SCALE, M, V, LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE  
INTEGER*8 N, ILO, IHI, M, LDV, INFO  
DOUBLE PRECISION SCALE(*), V(LDV,*)
```

F95 INTERFACE

```
SUBROUTINE GEBAK(JOB, SIDE, [N], ILO, IHI, SCALE, [M], V, [LDV],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE  
INTEGER :: N, ILO, IHI, M, LDV, INFO  
REAL(8), DIMENSION(:) :: SCALE  
REAL(8), DIMENSION(:, :) :: V
```

```
SUBROUTINE GEBAK_64(JOB, SIDE, [N], ILO, IHI, SCALE, [M], V, [LDV],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE  
INTEGER(8) :: N, ILO, IHI, M, LDV, INFO  
REAL(8), DIMENSION(:) :: SCALE  
REAL(8), DIMENSION(:, :) :: V
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgebak(char job, char side, int n, int ilo, int ihi,  
double *scale, int m, double *v, int ldv, int
```

```

        *info);

void dgebak_64(char job, char side, long n, long ilo, long
             ihi, double *scale, long m, double *v, long ldv,
             long *info);

```

PURPOSE

dgebak forms the right or left eigenvectors of a real general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by DGEBAL.

ARGUMENTS

JOB (input)

Specifies the type of backward transformation required: = 'N', do nothing, return immediately; = 'P', do backward transformation for permutation only; = 'S', do backward transformation for scaling only; = 'B', do backward transformations for both permutation and scaling. JOB must be the same as the argument JOB supplied to DGEBAL.

SIDE (input)

= 'R': V contains right eigenvectors;
 = 'L': V contains left eigenvectors.

N (input) The number of rows of the matrix V. $N \geq 0$.

ILO (input)

The integers ILO and IHI determined by DGEBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

IHI (input)

See the description for ILO.

SCALE (input)

Details of the permutation and scaling factors, as returned by DGEBAL.

M (input) The number of columns of the matrix V. $M \geq 0$.

V (input/output)

On entry, the matrix of right or left eigenvectors to be transformed, as returned by SHSEIN or STREVC. On exit, V is overwritten by the transformed eigenvectors.

LDV (input)

The leading dimension of the array V. $LDV \geq \max(1,N)$.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-

gal value.

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NAME

dgebal - balance a general real matrix A

SYNOPSIS

```
SUBROUTINE DGBAL(JOB, N, A, LDA, ILO, IHI, SCALE, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER N, LDA, ILO, IHI, INFO  
DOUBLE PRECISION A(LDA,*), SCALE(*)
```

```
SUBROUTINE DGBAL_64(JOB, N, A, LDA, ILO, IHI, SCALE, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER*8 N, LDA, ILO, IHI, INFO  
DOUBLE PRECISION A(LDA,*), SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE GEBAL(JOB, [N], A, [LDA], ILO, IHI, SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER :: N, LDA, ILO, IHI, INFO  
REAL(8), DIMENSION(:) :: SCALE  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GEBAL_64(JOB, [N], A, [LDA], ILO, IHI, SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER(8) :: N, LDA, ILO, IHI, INFO  
REAL(8), DIMENSION(:) :: SCALE  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgebal(char job, int n, double *a, int lda, int *ilo,  
            int *ihi, double *scale, int *info);
```

```
void dgebal_64(char job, long n, double *a, long lda, long
```

```
*ilo, long *ihi, double *scale, long *info);
```

PURPOSE

dgebal balances a general real matrix A. This involves, first, permuting A by a similarity transformation to isolate eigenvalues in the first 1 to ILO-1 and last IHI+1 to N elements on the diagonal; and second, applying a diagonal similarity transformation to rows and columns ILO to IHI to make the rows and columns as close in norm as possible. Both steps are optional.

Balancing may reduce the 1-norm of the matrix, and improve the accuracy of the computed eigenvalues and/or eigenvectors.

ARGUMENTS

JOB (input)

Specifies the operations to be performed on A:
= 'N': none: simply set ILO = 1, IHI = N,
SCALE(I) = 1.0 for i = 1,...,N; = 'P': permute
only;
= 'S': scale only;
= 'B': both permute and scale.

N (input) The order of the matrix A. N >= 0.

A (input/output)

On entry, the input matrix A. On exit, A is
overwritten by the balanced matrix. If JOB = 'N',
A is not referenced. See Further Details.

LDA (input)

The leading dimension of the array A. LDA >=
max(1,N).

ILO (output)

ILO and IHI are set to integers such that on exit
A(i,j) = 0 if i > j and j = 1,...,ILO-1 or i =
IHI+1,...,N. If JOB = 'N' or 'S', ILO = 1 and IHI
= N.

IHI (output)

See the description for ILO.

SCALE (output)

Details of the permutations and scaling factors
applied to A. If P(j) is the index of the row and
column interchanged with row and column j and D(j)
is the scaling factor applied to row and column j,
then SCALE(j) = P(j) for j = 1,...,ILO-1 = D(j)
for j = ILO,...,IHI = P(j) for j = IHI+1,...,N.
The order in which the interchanges are made is N
to IHI+1, then 1 to ILO-1.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The permutations consist of row and column interchanges which put the matrix in the form

$$P A P = \begin{pmatrix} T1 & X & Y \\ 0 & B & Z \\ 0 & 0 & T2 \end{pmatrix}$$

where T1 and T2 are upper triangular matrices whose eigenvalues lie along the diagonal. The column indices ILO and IHI mark the starting and ending columns of the submatrix B. Balancing consists of applying a diagonal similarity transformation $\text{inv}(D) * B * D$ to make the 1-norms of each row of B and its corresponding column nearly equal. The output matrix is

$$\begin{pmatrix} T1 & X*D & Y \\ 0 & \text{inv}(D)*B*D & \text{inv}(D)*Z \\ 0 & 0 & T2 \end{pmatrix}$$

Information about the permutations P and the diagonal matrix D is returned in the vector SCALE.

This subroutine is based on the EISPACK routine BALANC.

Modified by Tzu-Yi Chen, Computer Science Division, University of California at Berkeley, USA

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NAME

dgebrd - reduce a general real M-by-N matrix A to upper or lower bidiagonal form B by an orthogonal transformation

SYNOPSIS

```
SUBROUTINE DGEBRD(M, N, A, LDA, D, E, TAUQ, TAUP, WORK, LWORK, INFO)
```

```
INTEGER M, N, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), D(*), E(*), TAUQ(*), TAUP(*),  
WORK(*)
```

```
SUBROUTINE DGEBRD_64(M, N, A, LDA, D, E, TAUQ, TAUP, WORK, LWORK,  
INFO)
```

```
INTEGER*8 M, N, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), D(*), E(*), TAUQ(*), TAUP(*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEBRD([M], [N], A, [LDA], D, E, TAUQ, TAUP, [WORK], [LWORK],  
[INFO])
```

```
INTEGER :: M, N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: D, E, TAUQ, TAUP, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GEBRD_64([M], [N], A, [LDA], D, E, TAUQ, TAUP, [WORK],  
[LWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: D, E, TAUQ, TAUP, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgebrd(int m, int n, double *a, int lda, double *d,  
double *e, double *tauq, double *taup, int *info);
```

```
void dgebrd_64(long m, long n, double *a, long lda, double
             *d, double *e, double *tauq, double *taup, long
             *info);
```

PURPOSE

dgebrd reduces a general real M-by-N matrix A to upper or lower bidiagonal form B by an orthogonal transformation: $Q^{*T} * A * P = B$.

If $m \geq n$, B is upper bidiagonal; if $m < n$, B is lower bidiagonal.

ARGUMENTS

M (input) The number of rows in the matrix A. $M \geq 0$.

N (input) The number of columns in the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N general matrix to be reduced. On exit, if $m \geq n$, the diagonal and the first superdiagonal are overwritten with the upper bidiagonal matrix B; the elements below the diagonal, with the array TAUQ, represent the orthogonal matrix Q as a product of elementary reflectors, and the elements above the first superdiagonal, with the array TAUP, represent the orthogonal matrix P as a product of elementary reflectors; if $m < n$, the diagonal and the first subdiagonal are overwritten with the lower bidiagonal matrix B; the elements below the first subdiagonal, with the array TAUQ, represent the orthogonal matrix Q as a product of elementary reflectors, and the elements above the diagonal, with the array TAUP, represent the orthogonal matrix P as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

D (output)

The diagonal elements of the bidiagonal matrix B: $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the bidiagonal matrix B: if $m \geq n$, $E(i) = A(i, i+1)$ for $i = 1, 2, \dots, n-1$; if $m < n$, $E(i) = A(i+1, i)$ for $i = 1, 2, \dots, m-1$.

TAUQ (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Q. See Further Details.

TAUP (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix P. See Further Details.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The length of the array WORK. LWORK \geq max(1,M,N). For optimum performance LWORK \geq (M+N)*NB, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrices Q and P are represented as products of elementary reflectors:

If $m \geq n$,

$$Q = H(1) H(2) \dots H(n) \quad \text{and} \quad P = G(1) G(2) \dots G(n-1)$$

Each H(i) and G(i) has the form:

$$H(i) = I - \text{tauq} * v * v' \quad \text{and} \quad G(i) = I - \text{taup} * u * u'$$

where tauq and taup are real scalars, and v and u are real vectors; $v(1:i-1) = 0$, $v(i) = 1$, and $v(i+1:m)$ is stored on exit in A(i+1:m,i); $u(1:i) = 0$, $u(i+1) = 1$, and $u(i+2:n)$ is stored on exit in A(i,i+2:n); tauq is stored in TAUQ(i) and taup in TAUP(i).

If $m < n$,

$$Q = H(1) H(2) \dots H(m-1) \quad \text{and} \quad P = G(1) G(2) \dots G(m)$$

Each H(i) and G(i) has the form:

$$H(i) = I - \text{tauq} * v * v' \quad \text{and} \quad G(i) = I - \text{taup} * u * u'$$

where tauq and taup are real scalars, and v and u are real vectors; $v(1:i) = 0$, $v(i+1) = 1$, and $v(i+2:m)$ is stored on exit in A(i+2:m,i); $u(1:i-1) = 0$, $u(i) = 1$, and $u(i+1:n)$ is stored on exit in A(i,i+1:n); tauq is stored in TAUQ(i) and taup in TAUP(i).

The contents of A on exit are illustrated by the following examples:

m = 6 and n = 5 (m > n):

```
( d  e  u1 u1 u1 )
u1 )
( v1 d  e  u2 u2 )
u2 )
( v1 v2 d  e  u3 )
u3 )
( v1 v2 v3 d  e )
u4 )
( v1 v2 v3 v4 d )
u5 )
( v1 v2 v3 v4 v5 )
```

m = 5 and n = 6 (m < n):

```
( d  u1  u1  u1  u1
( e  d  u2  u2  u2
( v1 e  d  u3  u3
( v1 v2 e  d  u4
( v1 v2 v3 e  d
```

where d and e denote diagonal and off-diagonal elements of B, v_i denotes an element of the vector defining $H(i)$, and u_i an element of the vector defining $G(i)$.

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NAME

dgecon - estimate the reciprocal of the condition number of a general real matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by DGETRF

SYNOPSIS

```
SUBROUTINE DGECON(NORM, N, A, LDA, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM
INTEGER N, LDA, INFO
INTEGER WORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DGECON_64(NORM, N, A, LDA, ANORM, RCOND, WORK, WORK2,
INFO)
```

```
CHARACTER * 1 NORM
INTEGER*8 N, LDA, INFO
INTEGER*8 WORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GECON(NORM, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],
[INFO])
```

```
CHARACTER(LEN=1) :: NORM
INTEGER :: N, LDA, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GECON_64(NORM, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],
[INFO])
```

```
CHARACTER(LEN=1) :: NORM
INTEGER(8) :: N, LDA, INFO
INTEGER(8), DIMENSION(:) :: WORK2
```

```
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
void dgecon(char norm, int n, double *a, int lda, double
            anorm, double *rcond, int *info);

void dgecon_64(char norm, long n, double *a, long lda, dou-
              ble anorm, double *rcond, long *info);
```

PURPOSE

dgecon estimates the reciprocal of the condition number of a general real matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by DGETRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A)))$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The factors L and U from the factorization $A = P * L * U$ as computed by DGETRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension(4*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dgeequ - compute row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number

SYNOPSIS

```
SUBROUTINE DGEEQU(M, N, A, LDA, R, C, ROWCND, COLCND, AMAX,
                  INFO)
```

```
INTEGER M, N, LDA, INFO
DOUBLE PRECISION ROWCND, COLCND, AMAX
DOUBLE PRECISION A(LDA,*), R(*), C(*)
```

```
SUBROUTINE DGEEQU_64(M, N, A, LDA, R, C, ROWCND, COLCND, AMAX,
                    INFO)
```

```
INTEGER*8 M, N, LDA, INFO
DOUBLE PRECISION ROWCND, COLCND, AMAX
DOUBLE PRECISION A(LDA,*), R(*), C(*)
```

F95 INTERFACE

```
SUBROUTINE GEEQU([M], [N], A, [LDA], R, C, ROWCND, COLCND,
                AMAX, [INFO])
```

```
INTEGER :: M, N, LDA, INFO
REAL(8) :: ROWCND, COLCND, AMAX
REAL(8), DIMENSION(:) :: R, C
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GEEQU_64([M], [N], A, [LDA], R, C, ROWCND, COLCND,
                   AMAX, [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO
REAL(8) :: ROWCND, COLCND, AMAX
REAL(8), DIMENSION(:) :: R, C
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgeequ(int m, int n, double *a, int lda, double *r,
```

```

        double *c, double *rowcnd, double *colcnd, double
        *amax, int *info);

void dgeequ_64(long m, long n, double *a, long lda, double
        *r, double *c, double *rowcnd, double *colcnd,
        double *amax, long *info);

```

PURPOSE

dgeequ computes row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number. R returns the row scale factors and C the column scale factors, chosen to try to make the largest element in each row and column of the matrix B with elements $B(i,j)=R(i)*A(i,j)*C(j)$ have absolute value 1.

R(i) and C(j) are restricted to be between SMLNUM = smallest safe number and BIGNUM = largest safe number. Use of these scaling factors is not guaranteed to reduce the condition number of A but works well in practice.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input) The M-by-N matrix whose equilibration factors are to be computed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,M)$.

R (output)
If INFO = 0 or INFO > M, R contains the row scale factors for A.

C (output)
If INFO = 0, C contains the column scale factors for A.

ROWCND (output)
If INFO = 0 or INFO > M, ROWCND contains the ratio of the smallest R(i) to the largest R(i). If ROWCND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by R.

COLCND (output)
If INFO = 0, COLCND contains the ratio of the smallest C(i) to the largest C(i). If COLCND ≥ 0.1 , it is not worth scaling by C.

AMAX (output)
Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= M: the i-th row of A is exactly zero
> M: the (i-M)-th column of A is exactly zero

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NAME

dgees - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z

SYNOPSIS

```
SUBROUTINE DGEES(JOBZ, SORTEV, SELECT, N, A, LDA, NOUT, WR, WI, Z,  
                LDZ, WORK, LDWORK, WORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV  
INTEGER N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL SELECT  
LOGICAL WORK3(*)  
DOUBLE PRECISION A(LDA,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DGEES_64(JOBZ, SORTEV, SELECT, N, A, LDA, NOUT, WR, WI, Z,  
                  LDZ, WORK, LDWORK, WORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV  
INTEGER*8 N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL*8 SELECT  
LOGICAL*8 WORK3(*)  
DOUBLE PRECISION A(LDA,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEES(JOBZ, SORTEV, SELECT, [N], A, [LDA], NOUT, WR, WI, Z,  
               [LDZ], [WORK], [LDWORK], [WORK3], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV  
INTEGER :: N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL :: SELECT  
LOGICAL, DIMENSION(:) :: WORK3  
REAL(8), DIMENSION(:) :: WR, WI, WORK  
REAL(8), DIMENSION(:, :) :: A, Z
```

```
SUBROUTINE GEES_64(JOBZ, SORTEV, SELECT, [N], A, [LDA], NOUT, WR, WI,  
                  Z, [LDZ], [WORK], [LDWORK], [WORK3], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV  
INTEGER(8) :: N, LDA, NOUT, LDZ, LDWORK, INFO
```

```

LOGICAL(8) :: SELECT
LOGICAL(8), DIMENSION(:) :: WORK3
REAL(8), DIMENSION(:) :: WR, WI, WORK
REAL(8), DIMENSION(:, :) :: A, Z

```

C INTERFACE

```

#include <sunperf.h>
void      dgees(char      jobz,      char      sortev,
               int(*select)(double,double), int n, double *a, int
               lda, int *nout, double *wr, double *wi, double *z,
               int ldz, int *info);

void      dgees_64(char      jobz,      char      sortev,
                  long(*select)(double,double), long n, double *a,
                  long lda, long *nout, double *wr, double *wi, dou-
                  ble *z, long ldz, long *info);

```

PURPOSE

dgees computes for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z. This gives the Schur factorization $A = Z^*T^*(Z^{**}T)$.

Optionally, it also orders the eigenvalues on the diagonal of the real Schur form so that selected eigenvalues are at the top left. The leading columns of Z then form an orthonormal basis for the invariant subspace corresponding to the selected eigenvalues.

A matrix is in real Schur form if it is upper quasi-triangular with 1-by-1 and 2-by-2 blocks. 2-by-2 blocks will be standardized in the form

$$\begin{bmatrix} a & b \\ c & a \end{bmatrix}$$

where $b*c < 0$. The eigenvalues of such a block are $a \pm \sqrt{bc}$.

ARGUMENTS

JOBZ (input)

= 'N': Schur vectors are not computed;
 = 'V': Schur vectors are computed.

SORTEV (input)

Specifies whether or not to order the eigenvalues on the diagonal of the Schur form. = 'N': Eigenvalues are not ordered;
 = 'S': Eigenvalues are ordered (see SELECT).

SELECT (input)

LOGICAL FUNCTION of two DOUBLE PRECISION arguments
 SELECT must be declared EXTERNAL in the calling subroutine. If SORTEV = 'S', SELECT is used to select eigenvalues to sort to the top left of the

Schur form. If `SORTEV = 'N'`, `SELECT` is not referenced. An eigenvalue `WR(j)+sqrt(-1)*WI(j)` is selected if `SELECT(WR(j),WI(j))` is true; i.e., if either one of a complex conjugate pair of eigenvalues is selected, then both complex eigenvalues are selected. Note that a selected complex eigenvalue may no longer satisfy `SELECT(WR(j),WI(j)) = .TRUE.` after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned); in this case `INFO` is set to `N+2` (see `INFO` below).

`N` (input) The order of the matrix `A`. `N >= 0`.

`A` (input/output)
DOUBLE PRECISION array, dimension(`LDA`,`N`) On entry, the `N`-by-`N` matrix `A`. On exit, `A` has been overwritten by its real Schur form `T`.

`LDA` (input)
The leading dimension of the array `A`. `LDA >= max(1,N)`.

`NOUT` (output)
If `SORTEV = 'N'`, `NOUT = 0`. If `SORTEV = 'S'`, `NOUT =` number of eigenvalues (after sorting) for which `SELECT` is true. (Complex conjugate pairs for which `SELECT` is true for either eigenvalue count as 2.)

`WR` (output)
`WR` and `WI` contain the real and imaginary parts, respectively, of the computed eigenvalues in the same order that they appear on the diagonal of the output Schur form `T`. Complex conjugate pairs of eigenvalues will appear consecutively with the eigenvalue having the positive imaginary part first.

`WI` (output)
See the description for `WR`.

`Z` (output)
If `JOBZ = 'V'`, `Z` contains the orthogonal matrix `Z` of Schur vectors. If `JOBZ = 'N'`, `Z` is not referenced.

`LDZ` (input)
The leading dimension of the array `Z`. `LDZ >= 1`; if `JOBZ = 'V'`, `LDZ >= N`.

`WORK` (workspace)
On exit, if `INFO = 0`, `WORK(1)` contains the optimal `LDWORK`.

`LDWORK` (input)
The dimension of the array `WORK`. `LDWORK >= max(1,3*N)`. For good performance, `LDWORK` must generally be larger.

If `LDWORK = -1`, then a workspace query is assumed; the routine only calculates the optimal size of the `WORK` array, returns this value as the first

entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK3 (workspace)

dimension(N) Not referenced if SORTEV = 'N'.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: if INFO = i, and i is

<= N: the QR algorithm failed to compute all the eigenvalues; elements 1:ILO-1 and i+1:N of WR and WI contain those eigenvalues which have converged; if JOBZ = 'V', Z contains the matrix which reduces A to its partially converged Schur form. = N+1: the eigenvalues could not be reordered because some eigenvalues were too close to separate (the problem is very ill-conditioned); = N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Schur form no longer satisfy SELECT=.TRUE. This could also be caused by underflow due to scaling.

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NAME

dgeesx - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z

SYNOPSIS

```
SUBROUTINE DGEESX(JOBZ, SORTEV, SELECT, SENSE, N, A, LDA, NOUT, WR,  
  WI, Z, LDZ, SRCONE, RCONV, WORK, LDWORK, IWORK2, LDWRK2, BWORK3,  
  INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV, SENSE  
INTEGER N, LDA, NOUT, LDZ, LDWORK, LDWRK2, INFO  
INTEGER IWORK2(*)  
LOGICAL SELECT  
LOGICAL BWORK3(*)  
DOUBLE PRECISION SRCONE, RCONV  
DOUBLE PRECISION A(LDA,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DGEESX_64(JOBZ, SORTEV, SELECT, SENSE, N, A, LDA, NOUT,  
  WR, WI, Z, LDZ, SRCONE, RCONV, WORK, LDWORK, IWORK2, LDWRK2,  
  BWORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV, SENSE  
INTEGER*8 N, LDA, NOUT, LDZ, LDWORK, LDWRK2, INFO  
INTEGER*8 IWORK2(*)  
LOGICAL*8 SELECT  
LOGICAL*8 BWORK3(*)  
DOUBLE PRECISION SRCONE, RCONV  
DOUBLE PRECISION A(LDA,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEESX(JOBZ, SORTEV, SELECT, SENSE, [N], A, [LDA], NOUT,  
  WR, WI, Z, [LDZ], SRCONE, RCONV, [WORK], [LDWORK], [IWORK2],  
  [LDWRK2], [BWORK3], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV, SENSE  
INTEGER :: N, LDA, NOUT, LDZ, LDWORK, LDWRK2, INFO  
INTEGER, DIMENSION(:) :: IWORK2  
LOGICAL :: SELECT  
LOGICAL, DIMENSION(:) :: BWORK3
```

```

REAL(8) :: SRCONE, RCONV
REAL(8), DIMENSION(:) :: WR, WI, WORK
REAL(8), DIMENSION(:, :) :: A, Z

SUBROUTINE GEEEX_64(JOBZ, SORTEV, SELECT, SENSE, [N], A, [LDA], NOUT,
    WR, WI, Z, [LDZ], SRCONE, RCONV, [WORK], [LDWORK], [IWORK2],
    [LDWRK2], [BWORK3], [INFO])

CHARACTER(LEN=1) :: JOBZ, SORTEV, SENSE
INTEGER(8) :: N, LDA, NOUT, LDZ, LDWORK, LDWRK2, INFO
INTEGER(8), DIMENSION(:) :: IWORK2
LOGICAL(8) :: SELECT
LOGICAL(8), DIMENSION(:) :: BWORK3
REAL(8) :: SRCONE, RCONV
REAL(8), DIMENSION(:) :: WR, WI, WORK
REAL(8), DIMENSION(:, :) :: A, Z

```

C INTERFACE

```

#include <sunperf.h>

void      dgeesx(char      jobz,      char      sortev,
    int(*select)(double,double), char sense, int n,
    double *a, int lda, int *nout, double *wr, double
    *wi, double *z, int ldz, double *srcone, double
    *rconv, int *info);

void      dgeesx_64(char      jobz,      char      sortev,
    long(*select)(double,double), char sense, long n,
    double *a, long lda, long *nout, double *wr, dou-
    ble *wi, double *z, long ldz, double *srcone, dou-
    ble *rconv, long *info);

```

PURPOSE

dgeesx computes for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z. This gives the Schur factorization $A = Z^*T^*(Z^{**}T)$.

Optionally, it also orders the eigenvalues on the diagonal of the real Schur form so that selected eigenvalues are at the top left; computes a reciprocal condition number for the average of the selected eigenvalues (RCONDE); and computes a reciprocal condition number for the right invariant subspace corresponding to the selected eigenvalues (RCONDV). The leading columns of Z form an orthonormal basis for this invariant subspace.

For further explanation of the reciprocal condition numbers RCONDE and RCONDV, see Section 4.10 of the LAPACK Users' Guide (where these quantities are called s and sep respectively).

A real matrix is in real Schur form if it is upper quasi-triangular with 1-by-1 and 2-by-2 blocks. 2-by-2 blocks will be standardized in the form

$$\begin{bmatrix} a & b \\ c & a \end{bmatrix}$$

where $b*c < 0$. The eigenvalues of such a block are $a \pm \sqrt{bc}$.

ARGUMENTS

JOBZ (input)

= 'N': Schur vectors are not computed;
= 'V': Schur vectors are computed.

SORTEV (input)

Specifies whether or not to order the eigenvalues on the diagonal of the Schur form. = 'N': Eigenvalues are not ordered;
= 'S': Eigenvalues are ordered (see SELECT).

SELECT (input)

LOGICAL FUNCTION of two DOUBLE PRECISION arguments
SELECT must be declared EXTERNAL in the calling subroutine. If SORTEV = 'S', SELECT is used to select eigenvalues to sort to the top left of the Schur form. If SORTEV = 'N', SELECT is not referenced. An eigenvalue $WR(j) + \sqrt{-1} * WI(j)$ is selected if $SELECT(WR(j), WI(j))$ is true; i.e., if either one of a complex conjugate pair of eigenvalues is selected, then both are. Note that a selected complex eigenvalue may no longer satisfy $SELECT(WR(j), WI(j)) = .TRUE.$ after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned); in this case INFO may be set to N+3 (see INFO below).

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': None are computed;
= 'E': Computed for average of selected eigenvalues only;
= 'V': Computed for selected right invariant subspace only;
= 'B': Computed for both. If SENSE = 'E', 'V' or 'B', SORTEV must equal 'S'.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. On exit, A is overwritten by its real Schur form T.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

NOUT (output)

If SORTEV = 'N', NOUT = 0. If SORTEV = 'S', NOUT = number of eigenvalues (after sorting) for which SELECT is true. (Complex conjugate pairs for which SELECT is true for either eigenvalue count as 2.)

WR (output)

WR and WI contain the real and imaginary parts, respectively, of the computed eigenvalues, in the same order that they appear on the diagonal of the output Schur form T. Complex conjugate pairs of eigenvalues appear consecutively with the eigenvalue having the positive imaginary part first.

WI (output)

See the description for WR.

Z (output)

If JOBZ = 'V', Z contains the orthogonal matrix Z of Schur vectors. If JOBZ = 'N', Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq N.

SRCONE (output)

If SENSE = 'E' or 'B', SRCONE contains the reciprocal condition number for the average of the selected eigenvalues. Not referenced if SENSE = 'N' or 'V'.

RCONV (output)

If SENSE = 'V' or 'B', RCONV contains the reciprocal condition number for the selected right invariant subspace. Not referenced if SENSE = 'N' or 'E'.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq max(1,3*N). Also, if SENSE = 'E' or 'V' or 'B', LDWORK \geq N+2*NOUT*(N-NOUT), where NOUT is the number of selected eigenvalues computed by this routine. Note that N+2*NOUT*(N-NOUT) \leq N+N*N/2. For good performance, LDWORK must generally be larger.

IWORK2 (workspace/output)

Not referenced if SENSE = 'N' or 'E'. On exit, if INFO = 0, IWORK2(1) returns the optimal LDWRK2.

LDWRK2 (input)

The dimension of the array IWORK2. LDWRK2 \geq 1; if SENSE = 'V' or 'B', LDWRK2 \geq NOUT*(N-NOUT).

BWORK3 (workspace)

dimension(N) Not referenced if SORTEV = 'N'.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, and i is
 \leq N: the QR algorithm failed to compute all the eigenvalues; elements 1:ILO-1 and i+1:N of WR and

WI contain those eigenvalues which have converged;
if JOBZ = 'V', Z contains the transformation which
reduces A to its partially converged Schur form.
= N+1: the eigenvalues could not be reordered
because some eigenvalues were too close to
separate (the problem is very ill-conditioned);
= N+2: after reordering, roundoff changed values of
some complex eigenvalues so that leading eigen-
values in the Schur form no longer satisfy
SELECT=.TRUE. This could also be caused by under-
flow due to scaling.

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dgeev - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

SYNOPSIS

```
SUBROUTINE DGEEV(JOBVL, JOBVR, N, A, LDA, WR, WI, VL, LDVL, VR, LDVR,  
                WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
INTEGER N, LDA, LDVL, LDVR, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), WR(*), WI(*), VL(LDVL,*),  
VR(LDVR,*), WORK(*)
```

```
SUBROUTINE DGEEV_64(JOBVL, JOBVR, N, A, LDA, WR, WI, VL, LDVL, VR,  
                   LDVR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
INTEGER*8 N, LDA, LDVL, LDVR, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), WR(*), WI(*), VL(LDVL,*),  
VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEEV(JOBVL, JOBVR, [N], A, [LDA], WR, WI, VL, [LDVL], VR,  
               [LDVR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
INTEGER :: N, LDA, LDVL, LDVR, LDWORK, INFO  
REAL(8), DIMENSION(:) :: WR, WI, WORK  
REAL(8), DIMENSION(:, :) :: A, VL, VR
```

```
SUBROUTINE GEEV_64(JOBVL, JOBVR, [N], A, [LDA], WR, WI, VL, [LDVL],  
                  VR, [LDVR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
INTEGER(8) :: N, LDA, LDVL, LDVR, LDWORK, INFO  
REAL(8), DIMENSION(:) :: WR, WI, WORK  
REAL(8), DIMENSION(:, :) :: A, VL, VR
```

C INTERFACE

```
#include <sunperf.h>

void dgeev(char jobvl, char jobvr, int n, double *a, int
           lda, double *wr, double *wi, double *vl, int ldvl,
           double *vr, int ldvr, int *info);
void dgeev_64(char jobvl, char jobvr, long n, double *a,
              long lda, double *wr, double *wi, double *vl, long
              ldvl, double *vr, long ldvr, long *info);
```

PURPOSE

dgeev computes for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors.

The right eigenvector $v(j)$ of A satisfies

$$A * v(j) = \text{lambda}(j) * v(j)$$

where $\text{lambda}(j)$ is its eigenvalue.

The left eigenvector $u(j)$ of A satisfies

$$u(j)**H * A = \text{lambda}(j) * u(j)**H$$

where $u(j)**H$ denotes the conjugate transpose of $u(j)$.

The computed eigenvectors are normalized to have Euclidean norm equal to 1 and largest component real.

ARGUMENTS

JOBVL (input)

= 'N': left eigenvectors of A are not computed;
 = 'V': left eigenvectors of A are computed.

JOBVR (input)

= 'N': right eigenvectors of A are not computed;
 = 'V': right eigenvectors of A are computed.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. On exit, A has been overwritten.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

WR (output)

WR and WI contain the real and imaginary parts, respectively, of the computed eigenvalues. Complex conjugate pairs of eigenvalues appear consecutively with the eigenvalue having the positive imaginary part first.

WI (output)

See the description for WR.

VL (output)

If JOBVL = 'V', the left eigenvectors $u(j)$ are

stored one after another in the columns of VL, in the same order as their eigenvalues. If JOBVL = 'N', VL is not referenced. If the j-th eigenvalue is real, then $u(j) = VL(:,j)$, the j-th column of VL. If the j-th and (j+1)-st eigenvalues form a complex conjugate pair, then $u(j) = VL(:,j) + i*VL(:,j+1)$ and $u(j+1) = VL(:,j) - i*VL(:,j+1)$.

LDVL (input)

The leading dimension of the array VL. LDVL ≥ 1 ;
if JOBVL = 'V', LDVL $\geq N$.

VR (input)

If JOBVR = 'V', the right eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. If JOBVR = 'N', VR is not referenced. If the j-th eigenvalue is real, then $v(j) = VR(:,j)$, the j-th column of VR. If the j-th and (j+1)-st eigenvalues form a complex conjugate pair, then $v(j) = VR(:,j) + i*VR(:,j+1)$ and $v(j+1) = VR(:,j) - i*VR(:,j+1)$.

LDVR (input)

The leading dimension of the array VR. LDVR ≥ 1 ;
if JOBVR = 'V', LDVR $\geq N$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK $\geq \max(1, 3*N)$, and if JOBVL = 'V' or JOBVR = 'V', LDWORK $\geq 4*N$. For good performance, LDWORK must generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the QR algorithm failed to compute all the eigenvalues, and no eigenvectors have been computed; elements i+1:N of WR and WI contain eigenvalues which have converged.

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dggeevx - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

SYNOPSIS

```
SUBROUTINE DGEEVX(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, WR, WI, VL,
  LDVL, VR, LDVR, ILO, IHI, SCALE, ABNRM, RCONE, RCONV, WORK,
  LDWORK, IWORK2, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
INTEGER N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
INTEGER IWORK2(*)
DOUBLE PRECISION ABNRM
DOUBLE PRECISION A(LDA,*), WR(*), WI(*), VL(LDVL,*),
VR(LDVR,*), SCALE(*), RCONE(*), RCONV(*), WORK(*)
```

```
SUBROUTINE DGEEVX_64(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, WR, WI,
  VL, LDVL, VR, LDVR, ILO, IHI, SCALE, ABNRM, RCONE, RCONV, WORK,
  LDWORK, IWORK2, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
INTEGER*8 N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
INTEGER*8 IWORK2(*)
DOUBLE PRECISION ABNRM
DOUBLE PRECISION A(LDA,*), WR(*), WI(*), VL(LDVL,*),
VR(LDVR,*), SCALE(*), RCONE(*), RCONV(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEEVX(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], WR, WI,
  VL, [LDVL], VR, [LDVR], ILO, IHI, SCALE, ABNRM, RCONE, RCONV,
  [WORK], [LDWORK], [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
INTEGER :: N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
INTEGER, DIMENSION(:) :: IWORK2
REAL(8) :: ABNRM
REAL(8), DIMENSION(:) :: WR, WI, SCALE, RCONE, RCONV, WORK
REAL(8), DIMENSION(:,:) :: A, VL, VR
```

```

SUBROUTINE GEEVX_64(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], WR,
    WI, VL, [LDVL], VR, [LDVR], ILO, IHI, SCALE, ABNRM, RCONE, RCONV,
    [WORK], [LDWORK], [IWORK2], [INFO])

```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
INTEGER(8) :: N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK2
REAL(8) :: ABNRM
REAL(8), DIMENSION(:) :: WR, WI, SCALE, RCONE, RCONV, WORK
REAL(8), DIMENSION(:,:) :: A, VL, VR

```

C INTERFACE

```
#include <sunperf.h>
```

```

void dgeevx(char balanc, char jobvl, char jobvr, char sense,
    int n, double *a, int lda, double *wr, double *wi,
    double *vl, int ldvl, double *vr, int ldvr, int
    *ilo, int *ihi, double *scale, double *abnrm, dou-
    ble *rcone, double *rconv, int *info);

```

```

void dgeevx_64(char balanc, char jobvl, char jobvr, char
    sense, long n, double *a, long lda, double *wr,
    double *wi, double *vl, long ldvl, double *vr,
    long ldvr, long *ilo, long *ihi, double *scale,
    double *abnrm, double *rcone, double *rconv, long
    *info);

```

PURPOSE

dgeevx computes for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors.

Optionally also, it computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors (ILO, IHI, SCALE, and ABNRM), reciprocal condition numbers for the eigenvalues (RCONDE), and reciprocal condition numbers for the right eigenvectors (RCONDV).

The right eigenvector $v(j)$ of A satisfies

$$A * v(j) = \text{lambda}(j) * v(j)$$

where $\text{lambda}(j)$ is its eigenvalue.

The left eigenvector $u(j)$ of A satisfies

$$u(j)**H * A = \text{lambda}(j) * u(j)**H$$

where $u(j)**H$ denotes the conjugate transpose of $u(j)$.

The computed eigenvectors are normalized to have Euclidean norm equal to 1 and largest component real.

Balancing a matrix means permuting the rows and columns to make it more nearly upper triangular, and applying a diagonal similarity transformation $D * A * D^{*(-1)}$, where D is a diagonal matrix, to make its rows and columns closer in norm and the condition numbers of its eigenvalues and eigenvectors smaller. The computed reciprocal condition numbers correspond to the balanced matrix. Permuting rows and columns will not change the condition numbers (in exact

arithmetic) but diagonal scaling will. For further explanation of balancing, see section 4.10.2 of the LAPACK Users' Guide.

ARGUMENTS

BALANC (input)

Indicates how the input matrix should be diagonally scaled and/or permuted to improve the conditioning of its eigenvalues. = 'N': Do not diagonally scale or permute;
= 'P': Perform permutations to make the matrix more nearly upper triangular. Do not diagonally scale; = 'S': Diagonally scale the matrix, i.e. replace A by $D*A*D^{*(-1)}$, where D is a diagonal matrix chosen to make the rows and columns of A more equal in norm. Do not permute; = 'B': Both diagonally scale and permute A.

Computed reciprocal condition numbers will be for the matrix after balancing and/or permuting. Permuting does not change condition numbers (in exact arithmetic), but balancing does.

JOBVL (input)

= 'N': left eigenvectors of A are not computed;
= 'V': left eigenvectors of A are computed. If SENSE = 'E' or 'B', JOBVL must = 'V'.

JOBVR (input)

= 'N': right eigenvectors of A are not computed;
= 'V': right eigenvectors of A are computed. If SENSE = 'E' or 'B', JOBVR must = 'V'.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': None are computed;
= 'E': Computed for eigenvalues only;
= 'V': Computed for right eigenvectors only;
= 'B': Computed for eigenvalues and right eigenvectors.

If SENSE = 'E' or 'B', both left and right eigenvectors must also be computed (JOBVL = 'V' and JOBVR = 'V').

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. On exit, A has been overwritten. If JOBVL = 'V' or JOBVR = 'V', A contains the real Schur form of the balanced version of the input matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

WR (output)

WR and WI contain the real and imaginary parts,

respectively, of the computed eigenvalues. Complex conjugate pairs of eigenvalues will appear consecutively with the eigenvalue having the positive imaginary part first.

WI (output)

See the description for WR.

VL (output)

If JOBVL = 'V', the left eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. If JOBVL = 'N', VL is not referenced. If the j -th eigenvalue is real, then $u(j) = VL(:,j)$, the j -th column of VL. If the j -th and $(j+1)$ -st eigenvalues form a complex conjugate pair, then $u(j) = VL(:,j) + i*VL(:,j+1)$ and $u(j+1) = VL(:,j) - i*VL(:,j+1)$.

LDVL (input)

The leading dimension of the array VL. LDVL ≥ 1 ; if JOBVL = 'V', LDVL $\geq N$.

VR (output)

If JOBVR = 'V', the right eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. If JOBVR = 'N', VR is not referenced. If the j -th eigenvalue is real, then $v(j) = VR(:,j)$, the j -th column of VR. If the j -th and $(j+1)$ -st eigenvalues form a complex conjugate pair, then $v(j) = VR(:,j) + i*VR(:,j+1)$ and $v(j+1) = VR(:,j) - i*VR(:,j+1)$.

LDVR (input)

The leading dimension of the array VR. LDVR ≥ 1 , and if JOBVR = 'V', LDVR $\geq N$.

ILO (output)

ILO and IHI are integer values determined when A was balanced. The balanced $A(i,j) = 0$ if $I > J$ and $J = 1, \dots, ILO-1$ or $I = IHI+1, \dots, N$.

IHI (output)

See the description of ILO.

SCALE (output)

Details of the permutations and scaling factors applied when balancing A. If $P(j)$ is the index of the row and column interchanged with row and column j , and $D(j)$ is the scaling factor applied to row and column j , then $SCALE(J) = P(J)$, for $J = 1, \dots, ILO-1 = D(J)$, for $J = ILO, \dots, IHI = P(J)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

ABNRM (output)

The one-norm of the balanced matrix (the maximum of the sum of absolute values of elements of any column).

RCONE (output)
 RCONE(j) is the reciprocal condition number of the j-th eigenvalue.

RCONV (output)
 RCONV(j) is the reciprocal condition number of the j-th right eigenvector.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The dimension of the array WORK. If SENSE = 'N' or 'E', LDWORK \geq max(1,2*N), and if JOBVL = 'V' or JOBVR = 'V', LDWORK \geq 3*N. If SENSE = 'V' or 'B', LDWORK \geq N*(N+6). For good performance, LDWORK must generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

IWORK2 (workspace)
 dimension(2*N-2) If SENSE = 'N' or 'E', not referenced.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value.
 > 0: if INFO = i, the QR algorithm failed to compute all the eigenvalues, and no eigenvectors or condition numbers have been computed; elements 1:ILO-1 and i+1:N of WR and WI contain eigenvalues which have converged.

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NAME

dgegs - routine is deprecated and has been replaced by routine SGGES

SYNOPSIS

```
SUBROUTINE DGEYS(JOBVSL, JOBVSR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,  
                BETA, VSL, LDVSL, VSR, LDVSR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR  
INTEGER N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),  
BETA(*), VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
```

```
SUBROUTINE DGEYS_64(JOBVSL, JOBVSR, N, A, LDA, B, LDB, ALPHAR,  
                  ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR  
INTEGER*8 N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),  
BETA(*), VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEYS(JOBVSL, JOBVSR, [N], A, [LDA], B, [LDB], ALPHAR,  
                ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR  
INTEGER :: N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO  
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK  
REAL(8), DIMENSION(:,:) :: A, B, VSL, VSR
```

```
SUBROUTINE GEYS_64(JOBVSL, JOBVSR, [N], A, [LDA], B, [LDB], ALPHAR,  
                  ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR  
INTEGER(8) :: N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO  
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK  
REAL(8), DIMENSION(:,:) :: A, B, VSL, VSR
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dgegs(char jobvsl, char jobvsr, int n, double *a, int
lda, double *b, int ldb, double *alphan, double
*alphai, double *beta, double *vsl, int ldvsl,
double *vsr, int ldvsr, int *info);
void dgegs_64(char jobvsl, char jobvsr, long n, double *a,
long lda, double *b, long ldb, double *alphan,
double *alphai, double *beta, double *vsl, long
ldvsl, double *vsr, long ldvsr, long *info);

```

PURPOSE

dgegs routine is deprecated and has been replaced by routine SGGES.

DGEGS computes for a pair of N-by-N real nonsymmetric matrices A, B: the generalized eigenvalues (alphan +/- alphai*i, beta), the real Schur form (A, B), and optionally left and/or right Schur vectors (VSL and VSR).

(If only the generalized eigenvalues are needed, use the driver DGEV instead.)

A generalized eigenvalue for a pair of matrices (A,B) is, roughly speaking, a scalar w or a ratio alpha/beta = w, such that A - w*B is singular. It is usually represented as the pair (alpha,beta), as there is a reasonable interpretation for beta=0, and even for both being zero. A good beginning reference is the book, "Matrix Computations", by G. Golub & C. van Loan (Johns Hopkins U. Press)

The (generalized) Schur form of a pair of matrices is the result of multiplying both matrices on the left by one orthogonal matrix and both on the right by another orthogonal matrix, these two orthogonal matrices being chosen so as to bring the pair of matrices into (real) Schur form.

A pair of matrices A, B is in generalized real Schur form if B is upper triangular with non-negative diagonal and A is block upper triangular with 1-by-1 and 2-by-2 blocks. 1-by-1 blocks correspond to real generalized eigenvalues, while 2-by-2 blocks of A will be "standardized" by making the corresponding elements of B have the form:

$$\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$$

and the pair of corresponding 2-by-2 blocks in A and B will have a complex conjugate pair of generalized eigenvalues.

The left and right Schur vectors are the columns of VSL and VSR, respectively, where VSL and VSR are the orthogonal matrices which reduce A and B to Schur form:

Schur form of (A,B) = ((VSL)**T A (VSR), (VSL)**T B (VSR))

ARGUMENTS

JOBVSL (input)
 = 'N': do not compute the left Schur vectors;
 = 'V': compute the left Schur vectors.

JOBVSR (input)
 = 'N': do not compute the right Schur vectors;
 = 'V': compute the right Schur vectors.

N (input) The order of the matrices A, B, VSL, and VSR. N
 >= 0.

A (input/output)
 On entry, the first of the pair of matrices whose
 generalized eigenvalues and (optionally) Schur
 vectors are to be computed. On exit, the general-
 ized Schur form of A. Note: to avoid overflow,
 the Frobenius norm of the matrix A should be less
 than the overflow threshold.

LDA (input)
 The leading dimension of A. LDA >= max(1,N).

B (input/output)
 On entry, the second of the pair of matrices whose
 generalized eigenvalues and (optionally) Schur
 vectors are to be computed. On exit, the general-
 ized Schur form of B. Note: to avoid overflow,
 the Frobenius norm of the matrix B should be less
 than the overflow threshold.

LDB (input)
 The leading dimension of B. LDB >= max(1,N).

ALPHAR (output)
 On exit, $(\text{ALPHAR}(j) + \text{ALPHAI}(j)*i)/\text{BETA}(j)$,
 $j=1,\dots,N$, will be the generalized eigenvalues.
 $\text{ALPHAR}(j) + \text{ALPHAI}(j)*i$, $j=1,\dots,N$ and
 $\text{BETA}(j)$, $j=1,\dots,N$ are the diagonals of the com-
 plex Schur form (A,B) that would result if the 2-
 by-2 diagonal blocks of the real Schur form of
 (A,B) were further reduced to triangular form
 using 2-by-2 complex unitary transformations. If
 $\text{ALPHAI}(j)$ is zero, then the j-th eigenvalue is
 real; if positive, then the j-th and (j+1)-st
 eigenvalues are a complex conjugate pair, with
 $\text{ALPHAI}(j+1)$ negative.

Note: the quotients $\text{ALPHAR}(j)/\text{BETA}(j)$ and
 $\text{ALPHAI}(j)/\text{BETA}(j)$ may easily over- or underflow,
 and $\text{BETA}(j)$ may even be zero. Thus, the user
 should avoid naively computing the ratio
 alpha/beta. However, ALPHAR and ALPHAI will be
 always less than and usually comparable with
 norm(A) in magnitude, and BETA always less than
 and usually comparable with norm(B).

ALPHAI (output)
 See the description for ALPHAR.

BETA (output)

See the description for ALPHAR.

VSL (input)

If JOBVSL = 'V', VSL will contain the left Schur vectors. (See "Purpose", above.) Not referenced if JOBVSL = 'N'.

LDVSL (input)

The leading dimension of the matrix VSL. LDVSL ≥ 1 , and if JOBVSL = 'V', LDVSL $\geq N$.

VSR (input)

If JOBVSR = 'V', VSR will contain the right Schur vectors. (See "Purpose", above.) Not referenced if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR ≥ 1 , and if JOBVSR = 'V', LDVSR $\geq N$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK $\geq \max(1, 4*N)$. For good performance, LDWORK must generally be larger. To compute the optimal value of LDWORK, call ILAENV to get blocksizes (for DGEQRF, SORMQR, and SORGQR.) Then compute: NB -- MAX of the blocksizes for DGEQRF, SORMQR, and SORGQR The optimal LDWORK is $2*N + N*(NB+1)$.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for $j=INFO+1, \dots, N$.
> N: errors that usually indicate LAPACK problems:
=N+1: error return from SGBAL
=N+2: error return from DGEQRF
=N+3: error return from SORMQR
=N+4: error return from SORGQR
=N+5: error return from SGGHRD
=N+6: error return from SHGEQZ (other than failed iteration) =N+7: error return from SGGBAK (computing VSL)
=N+8: error return from SGGBAK (computing VSR)
=N+9: error return from SLASCL (various places)

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NAME

dggev - routine is deprecated and has been replaced by routine SGGEV

SYNOPSIS

```
SUBROUTINE DGEGV(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,
                 BETA, VL, LDVL, VR, LDVR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
INTEGER N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

```
SUBROUTINE DGEGV_64(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,
                   BETA, VL, LDVL, VR, LDVR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
INTEGER*8 N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEGV(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHAR,
               ALPHAI, BETA, VL, [LDVL], VR, [LDVR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
INTEGER :: N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL(8), DIMENSION(:, :) :: A, B, VL, VR
```

```
SUBROUTINE GEGV_64(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHAR,
                  ALPHAI, BETA, VL, [LDVL], VR, [LDVR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL(8), DIMENSION(:, :) :: A, B, VL, VR
```

C INTERFACE

```
#include <sunperf.h>

void dgegv(char jobvl, char jobvr, int n, double *a, int
           lda, double *b, int ldb, double *alphan, double
           *alphai, double *beta, double *vl, int ldvl, dou-
           ble *vr, int ldvr, int *info);
void dgegv_64(char jobvl, char jobvr, long n, double *a,
              long lda, double *b, long ldb, double *alphan,
              double *alphai, double *beta, double *vl, long
              ldvl, double *vr, long ldvr, long *info);
```

PURPOSE

dgegv routine is deprecated and has been replaced by routine SGGEV.

DGEGV computes for a pair of n-by-n real nonsymmetric matrices A and B, the generalized eigenvalues ($\alpha \pm i\beta$), and optionally, the left and/or right generalized eigenvectors (VL and VR).

A generalized eigenvalue for a pair of matrices (A,B) is, roughly speaking, a scalar w or a ratio $\alpha/\beta = w$, such that $A - wB$ is singular. It is usually represented as the pair (α, β), as there is a reasonable interpretation for $\beta=0$, and even for both being zero. A good beginning reference is the book, "Matrix Computations", by G. Golub & C. van Loan (Johns Hopkins U. Press)

A right generalized eigenvector corresponding to a generalized eigenvalue w for a pair of matrices (A,B) is a vector r such that $(A - wB)r = 0$. A left generalized eigenvector is a vector l such that $l^*H * (A - wB) = 0$, where l^*H is the conjugate-transpose of l.

Note: this routine performs "full balancing" on A and B -- see "Further Details", below.

ARGUMENTS

JOBVL (input)
= 'N': do not compute the left generalized eigenvectors;
= 'V': compute the left generalized eigenvectors.

JOBVR (input)
= 'N': do not compute the right generalized eigenvectors;
= 'V': compute the right generalized eigenvectors.

N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)

On entry, the first of the pair of matrices whose generalized eigenvalues and (optionally) generalized eigenvectors are to be computed. On exit, the contents will have been destroyed. (For a description of the contents of A on exit, see "Further Details", below.)

LDA (input)

The leading dimension of A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the second of the pair of matrices whose generalized eigenvalues and (optionally) generalized eigenvectors are to be computed. On exit, the contents will have been destroyed. (For a description of the contents of B on exit, see "Further Details", below.)

LDB (input)

The leading dimension of B. $LDB \geq \max(1, N)$.

ALPHAR (output)

On exit, $(ALPHAR(j) + ALPHAI(j)*i)/BETA(j)$, $j=1, \dots, N$, will be the generalized eigenvalues. If $ALPHAI(j)$ is zero, then the j -th eigenvalue is real; if positive, then the j -th and $(j+1)$ -st eigenvalues are a complex conjugate pair, with $ALPHAI(j+1)$ negative.

Note: the quotients $ALPHAR(j)/BETA(j)$ and $ALPHAI(j)/BETA(j)$ may easily over- or underflow, and $BETA(j)$ may even be zero. Thus, the user should avoid naively computing the ratio α/β . However, $ALPHAR$ and $ALPHAI$ will be always less than and usually comparable with $\text{norm}(A)$ in magnitude, and $BETA$ always less than and usually comparable with $\text{norm}(B)$.

ALPHAI (output)

See the description of $ALPHAR$.

BETA (output)

See the description of $ALPHAR$.

VL (output)

If $JOBVL = 'V'$, the left generalized eigenvectors. (See "Purpose", above.) Real eigenvectors take one column, complex take two columns, the first for the real part and the second for the imaginary part. Complex eigenvectors correspond to an eigenvalue with positive imaginary part. Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha=\beta=0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if $JOBVL = 'N'$.

LDVL (input)

The leading dimension of the matrix VL. $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (output)

If JOBVR = 'V', the right generalized eigenvectors. (See "Purpose", above.) Real eigenvectors take one column, complex take two columns, the first for the real part and the second for the imaginary part. Complex eigenvectors correspond to an eigenvalue with positive imaginary part. Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha = \beta = 0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if JOBVR = 'N'.

LDVR (input)

The leading dimension of the matrix VR. LDVR ≥ 1 , and if JOBVR = 'V', LDVR $\geq N$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK $\geq \max(1, 8*N)$. For good performance, LDWORK must generally be larger. To compute the optimal value of LDWORK, call ILAENV to get block sizes (for DGEQRF, SORMQR, and SORGQR.) Then compute: NB -- MAX of the block sizes for DGEQRF, SORMQR, and SORGQR; The optimal LDWORK is: $2*N + \text{MAX}(6*N, N*(NB+1))$.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. No eigenvectors have been calculated, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for $j = \text{INFO} + 1, \dots, N$.
> N: errors that usually indicate LAPACK problems:
=N+1: error return from SGBAL
=N+2: error return from DGEQRF
=N+3: error return from SORMQR
=N+4: error return from SORGQR
=N+5: error return from SGGHRD
=N+6: error return from SHGEQZ (other than failed iteration)
=N+7: error return from STGEVC
=N+8: error return from SGGBAK (computing VL)
=N+9: error return from SGGBAK (computing VR)
=N+10: error return from SLASCL (various calls)

FURTHER DETAILS

Balancing

This driver calls SGBAL to both permute and scale rows and columns of A and B. The permutations PL and PR are chosen so that PL^*A^*PR and PL^*B^*R will be upper triangular except for the diagonal blocks $A(i:j,i:j)$ and $B(i:j,i:j)$, with i and j as close together as possible. The diagonal scaling matrices DL and DR are chosen so that the pair $DL^*PL^*A^*PR^*DR$, $DL^*PL^*B^*PR^*DR$ have elements close to one (except for the elements that start out zero.)

After the eigenvalues and eigenvectors of the balanced matrices have been computed, SGBAK transforms the eigenvectors back to what they would have been (in perfect arithmetic) if they had not been balanced.

Contents of A and B on Exit

If any eigenvectors are computed (either $JOBVL='V'$ or $JOBVR='V'$ or both), then on exit the arrays A and B will contain the real Schur form[*] of the "balanced" versions of A and B. If no eigenvectors are computed, then only the diagonal blocks will be correct.

[*] See SHGEQZ, DGEQS, or read the book "Matrix Computations",

by Golub & van Loan, pub. by Johns Hopkins U. Press.

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NAME

dgehrd - reduce a real general matrix A to upper Hessenberg form H by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE DGEHRD(N, ILO, IHI, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
INTEGER N, ILO, IHI, LDA, LWORKIN, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORKIN(*)
```

```
SUBROUTINE DGEHRD_64(N, ILO, IHI, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
INTEGER*8 N, ILO, IHI, LDA, LWORKIN, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORKIN(*)
```

F95 INTERFACE

```
SUBROUTINE GEHRD([N], ILO, IHI, A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
INTEGER :: N, ILO, IHI, LDA, LWORKIN, INFO  
REAL(8), DIMENSION(:) :: TAU, WORKIN  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GEHRD_64([N], ILO, IHI, A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
INTEGER(8) :: N, ILO, IHI, LDA, LWORKIN, INFO  
REAL(8), DIMENSION(:) :: TAU, WORKIN  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgehrd(int n, int ilo, int ihi, double *a, int lda,  
double *tau, int *info);
```

```
void dgehrd_64(long n, long ilo, long ihi, double *a, long  
lda, double *tau, long *info);
```

PURPOSE

dgehrd reduces a real general matrix A to upper Hessenberg form H by an orthogonal similarity transformation: $Q' * A * Q = H$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to DGEBAL; otherwise they should be set to 1 and N respectively. See Further Details.

IHI (input)

See the description of ILO.

A (input/output)

On entry, the N-by-N general matrix to be reduced. On exit, the upper triangle and the first subdiagonal of A are overwritten with the upper Hessenberg matrix H, and the elements below the first subdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details). Elements 1:ILO-1 and IHI:N-1 of TAU are set to zero.

WORKIN (workspace)

On exit, if INFO = 0, WORKIN(1) returns the optimal LWORKIN.

LWORKIN (input)

The length of the array WORKIN. $LWORKIN \geq \max(1, N)$. For optimum performance $LWORKIN \geq N * NB$, where NB is the optimal blocksize.

If LWORKIN = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORKIN array, returns this value as the first entry of the WORKIN array, and no error message related to LWORKIN is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-

gal value.

FURTHER DETAILS

The matrix Q is represented as a product of $(ihi-ilo)$ elementary reflectors

$$Q = H(ilo) H(ilo+1) \dots H(ihi-1).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real scalar, and v is a real vector with $v(1:i) = 0$, $v(i+1) = 1$ and $v(ihi+1:n) = 0$; $v(i+2:ihi)$ is stored on exit in $A(i+2:ihi,i)$, and τ in $TAU(i)$.

The contents of A are illustrated by the following example, with $n = 7$, $ilo = 2$ and $ihi = 6$:

on entry,

on exit,

```
( a a a a a a a ) ( a a h h h h
a ) ( a a a a a a a ) ( a h h h
h a ) ( a a a a a a a ) ( h h h
h h h ) ( a a a a a a a ) ( v2 h
h h h h ) ( a a a a a a a ) ( v2
v3 h h h h ) ( a a a a a a ) (
v2 v3 v4 h h h ) ( a ) (
a )
```

where a denotes an element of the original matrix A , h denotes a modified element of the upper Hessenberg matrix H , and v_i denotes an element of the vector defining $H(i)$.

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NAME

dgelqf - compute an LQ factorization of a real M-by-N matrix
A

SYNOPSIS

```
SUBROUTINE DGELQF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DGELQF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELQF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GELQF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgelqf(int m, int n, double *a, int lda, double *tau,  
           int *info);
```

```
void dgelqf_64(long m, long n, double *a, long lda, double  
              *tau, long *info);
```

PURPOSE

dgelqf computes an LQ factorization of a real M-by-N matrix
A: $A = L * Q$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the elements on and below the diagonal of the array contain the m-by-min(m,n) lower trapezoidal matrix L (L is lower triangular if $m \leq n$); the elements above the diagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, M)$. For optimum performance $LDWORK \geq M * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(k) \dots H(2) H(1), \text{ where } k = \min(m, n).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with
 $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:n)$ is stored on exit in
 $A(i,i+1:n)$, and tau in $TAU(i)$.

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NAME

dgels - solve overdetermined or underdetermined real linear systems involving an M-by-N matrix A, or its transpose, using a QR or LQ factorization of A

SYNOPSIS

```
SUBROUTINE DGELS(TRANSA, M, N, NRHS, A, LDA, B, LDB, WORK, LDWORK,
                INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER M, N, NRHS, LDA, LDB, LDWORK, INFO
DOUBLE PRECISION A(LDA,*), B(LDB,*), WORK(*)
```

```
SUBROUTINE DGELS_64(TRANSA, M, N, NRHS, A, LDA, B, LDB, WORK, LDWORK,
                   INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER*8 M, N, NRHS, LDA, LDB, LDWORK, INFO
DOUBLE PRECISION A(LDA,*), B(LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELS([TRANSA], [M], [N], [NRHS], A, [LDA], B, [LDB], [WORK],
               LDWORK, [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER :: M, N, NRHS, LDA, LDB, LDWORK, INFO
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE GELS_64([TRANSA], [M], [N], [NRHS], A, [LDA], B, [LDB],
                  [WORK], LDWORK, [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER(8) :: M, N, NRHS, LDA, LDB, LDWORK, INFO
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dgels (char, int, int, int, double*, int, double*, int,
            int*);

void dgels_64 (char, long, long, long, double*, long, double*, long, long*);

```

PURPOSE

dgels solves overdetermined or underdetermined real linear systems involving an M-by-N matrix A, or its transpose, using a QR or LQ factorization of A. It is assumed that A has full rank.

The following options are provided:

1. If TRANS = 'N' and $m \geq n$: find the least squares solution of
an overdetermined system, i.e., solve the least squares problem

$$\text{minimize } \| B - A * X \|^2.$$

2. If TRANS = 'N' and $m < n$: find the minimum norm solution of
an underdetermined system $A * X = B$.

3. If TRANS = 'T' and $m \geq n$: find the minimum norm solution of
an overdetermined system $A^{**T} * X = B$.

4. If TRANS = 'T' and $m < n$: find the least squares solution of
an overdetermined system, i.e., solve the least squares problem

$$\text{minimize } \| B - A^{**T} * X \|^2.$$

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

ARGUMENTS

TRANSA (input)
= 'N': the linear system involves A;
= 'T': the linear system involves A**T.

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS ≥ 0 .

A (input/output)

On entry, the M-by-N matrix A. On exit, if $M \geq N$, A is overwritten by details of its QR factorization as returned by DGEQRF; if $M < N$, A is overwritten by details of its LQ factorization as returned by DGELQF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)

On entry, the matrix B of right hand side vectors, stored columnwise; B is M-by-NRHS if TRANSA = 'N', or N-by-NRHS if TRANSA = 'T'. On exit, B is overwritten by the solution vectors, stored columnwise: if TRANSA = 'N' and $m \geq n$, rows 1 to n of B contain the least squares solution vectors; the residual sum of squares for the solution in each column is given by the sum of squares of elements N+1 to M in that column; if TRANSA = 'N' and $m < n$, rows 1 to N of B contain the minimum norm solution vectors; if TRANSA = 'T' and $m \geq n$, rows 1 to M of B contain the minimum norm solution vectors; if TRANSA = 'T' and $m < n$, rows 1 to M of B contain the least squares solution vectors; the residual sum of squares for the solution in each column is given by the sum of squares of elements M+1 to N in that column.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, M, N)$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (output)

The dimension of the array WORK. $LDWORK \geq \max(1, MN + \max(MN, NRHS))$. For optimal performance, $LDWORK \geq \max(1, MN + \max(MN, NRHS) * NB)$. where $MN = \min(M, N)$ and NB is the optimum block size.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dgelsd - compute the minimum-norm solution to a real linear least squares problem

SYNOPSIS

```
SUBROUTINE DGELSD(M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK, WORK,  
                LWORK, IWORK, INFO)
```

```
INTEGER M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), B(LDB,*), S(*), WORK(*)
```

```
SUBROUTINE DGELSD_64(M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK,  
                   WORK, LWORK, IWORK, INFO)
```

```
INTEGER*8 M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), B(LDB,*), S(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSD([M], [N], [NRHS], A, [LDA], B, [LDB], S, RCOND,  
                RANK, [WORK], [LWORK], [IWORK], [INFO])
```

```
INTEGER :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: S, WORK  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GELSD_64([M], [N], [NRHS], A, [LDA], B, [LDB], S, RCOND,  
                   RANK, [WORK], [LWORK], [IWORK], [INFO])
```

```
INTEGER(8) :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER(8), DIMENSION(:) :: IWORK  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: S, WORK
```

REAL(8), DIMENSION(:, :) :: A, B

C INTERFACE

```
#include <sunperf.h>
```

```
void dgelsd(int m, int n, int nrhs, double *a, int lda, double *b, int ldb, double *s, double rcond, int *rank, int *info);
```

```
void dgelsd_64(long m, long n, long nrhs, double *a, long lda, double *b, long ldb, double *s, double rcond, long *rank, long *info);
```

PURPOSE

dgelsd computes the minimum-norm solution to a real linear least squares problem:

$$\text{minimize } 2\text{-norm}(|b - A*x|)$$

using the singular value decomposition (SVD) of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The problem is solved in three steps:

- (1) Reduce the coefficient matrix A to bidiagonal form with Householder transformations, reducing the original problem into a "bidiagonal least squares problem" (BLS)
- (2) Solve the BLS using a divide and conquer approach.
- (3) Apply back all the Householder transformations to solve the original least squares problem.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

M (input) The number of rows of A. M >= 0.

N (input) The number of columns of A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)

On entry, the M-by-N matrix A. On exit, A has been destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, B is overwritten by the N-by-NRHS solution matrix X. If $m \geq n$ and $RANK = n$, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements $n+1:m$ in that column.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, \max(M, N))$.

S (output)

The singular values of A in decreasing order. The condition number of A in the 2-norm = $S(1)/S(\min(m, n))$.

RCOND (input)

RCOND is used to determine the effective rank of A. Singular values $S(i) \leq RCOND * S(1)$ are treated as zero. If $RCOND < 0$, machine precision is used instead.

RANK (output)

The effective rank of A, i.e., the number of singular values which are greater than $RCOND * S(1)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq 1$. The exact minimum amount of workspace needed depends on M, N and NRHS. As long as LWORK is at least $12 * N + 2 * N * SMLSIZ + 8 * N * NLVL + N * NRHS * (SMLSIZ + 1) ** 2$, if M is greater than or equal to N or $12 * M + 2 * M * SMLSIZ + 8 * M * NLVL + M * NRHS + (SMLSIZ + 1) ** 2$, if M is less than N, the code will execute correctly. SMLSIZ is returned by ILAENV and is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25), and $NLVL = \text{INT}(\text{LOG}_2(\text{MIN}(M, N) / (SMLSIZ + 1))) + 1$. For good performance, LWORK should generally be larger.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)

$LIWORK \geq 3 * \text{MINMN} * NLVL + 11 * \text{MINMN}$, where

MINMN = MIN(M,N).

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: the algorithm for computing the SVD failed to converge; if INFO = i, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

FURTHER DETAILS

Based on contributions by

Ming Gu and Ren-Cang Li, Computer Science Division,
University of California at Berkeley, USA

Osni Marques, LBNL/NERSC, USA

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NAME

dgelss - compute the minimum norm solution to a real linear least squares problem

SYNOPSIS

```
SUBROUTINE DGELSS(M, N, NRHS, A, LDA, B, LDB, SING, RCOND, IRANK,  
                WORK, LDWORK, INFO)
```

```
INTEGER M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), B(LDB,*), SING(*), WORK(*)
```

```
SUBROUTINE DGELSS_64(M, N, NRHS, A, LDA, B, LDB, SING, RCOND, IRANK,  
                   WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), B(LDB,*), SING(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSS([M], [N], [NRHS], A, [LDA], B, [LDB], SING, RCOND,  
               IRANK, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: SING, WORK  
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE GELSS_64([M], [N], [NRHS], A, [LDA], B, [LDB], SING,  
                  RCOND, IRANK, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: SING, WORK  
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgelss(int m, int n, int nrhs, double *a, int lda, dou-
```

```

        ble *b, int ldb, double *sing, double rcond, int
        *irank, int *info);

void dgelss_64(long m, long n, long nrhs, double *a, long
        lda, double *b, long ldb, double *sing, double
        rcond, long *irank, long *info);

```

PURPOSE

dgelss computes the minimum norm solution to a real linear least squares problem:

Minimize 2-norm($| b - A*x |$).

using the singular value decomposition (SVD) of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the first $\min(m,n)$ rows of A are overwritten with its right singular vectors, stored rowwise.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, B is overwritten by the N-by-NRHS solution matrix X. If $m \geq n$ and $IRANK = n$, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements $n+1:m$ in that column.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,\max(M,N))$.

SING (output)

The singular values of A in decreasing order. The condition number of A in the 2-norm = $SING(1)/SING(\min(m,n))$.

RCOND (input)

RCOND is used to determine the effective rank of A. Singular values $SING(i) \leq RCOND * SING(1)$ are treated as zero. If $RCOND < 0$, machine precision is used instead.

IRANK (output)

The effective rank of A, i.e., the number of singular values which are greater than $RCOND * SING(1)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq 1$, and also: $LDWORK \geq 3 * \min(M,N) + \max(2 * \min(M,N), \max(M,N), NRHS)$ For good performance, LDWORK should generally be larger.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value.
> 0: the algorithm for computing the SVD failed to converge; if $INFO = i$, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

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NAME

dgelsx - routine is deprecated and has been replaced by routine DGELSY

SYNOPSIS

```
SUBROUTINE DGELSX(M, N, NRHS, A, LDA, B, LDB, JPIVOT, RCOND, IRANK,  
  WORK, INFO)
```

```
INTEGER M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER JPIVOT(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), B(LDB,*), WORK(*)
```

```
SUBROUTINE DGELSX_64(M, N, NRHS, A, LDA, B, LDB, JPIVOT, RCOND,  
  IRANK, WORK, INFO)
```

```
INTEGER*8 M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER*8 JPIVOT(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), B(LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSX([M], [N], [NRHS], A, [LDA], B, [LDB], JPIVOT, RCOND,  
  IRANK, [WORK], [INFO])
```

```
INTEGER :: M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER, DIMENSION(:) :: JPIVOT  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GELSX_64([M], [N], [NRHS], A, [LDA], B, [LDB], JPIVOT,  
  RCOND, IRANK, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER(8), DIMENSION(:) :: JPIVOT  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>

void dgelsx(int m, int n, int nrhs, double *a, int lda, double
           *b, int ldb, int *jpivot, double rcond, int
           *irank, int *info);
void dgelsx_64(long m, long n, long nrhs, double *a, long
              lda, double *b, long ldb, long *jpivot, double
              rcond, long *irank, long *info);
```

PURPOSE

dgelsx routine is deprecated and has been replaced by routine DGELSY.

DGELSX computes the minimum-norm solution to a real linear least squares problem:

$$\text{minimize } || A * X - B ||$$

using a complete orthogonal factorization of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The routine first computes a QR factorization with column pivoting:

$$A * P = Q * \begin{bmatrix} R11 & R12 \\ 0 & R22 \end{bmatrix}$$

with R11 defined as the largest leading submatrix whose estimated condition number is less than 1/RCOND. The order of R11, RANK, is the effective rank of A.

Then, R22 is considered to be negligible, and R12 is annihilated by orthogonal transformations from the right, arriving at the complete orthogonal factorization:

$$A * P = Q * \begin{bmatrix} T11 & 0 \\ 0 & 0 \end{bmatrix} * Z$$

The minimum-norm solution is then

$$X = P * Z' \begin{bmatrix} \text{inv}(T11)*Q1'*B \\ 0 \end{bmatrix}$$

where Q1 consists of the first RANK columns of Q.

ARGUMENTS

M (input) The number of rows of the matrix A. M >= 0.

N (input) The number of columns of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of matrices B and X. NRHS >= 0.

A (input/output)

On entry, the M-by-N matrix A. On exit, A has been overwritten by details of its complete

orthogonal factorization.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,M).

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, the N-by-NRHS solution matrix X. If $m \geq n$ and IRANK = n, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements N+1:M in that column.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,M,N).

JPIVOT (input/output)

On entry, if JPIVOT(i) \neq 0, the i-th column of A is an initial column, otherwise it is a free column. Before the QR factorization of A, all initial columns are permuted to the leading positions; only the remaining free columns are moved as a result of column pivoting during the factorization. On exit, if JPIVOT(i) = k, then the i-th column of A*P was the k-th column of A.

RCOND (input)

RCOND is used to determine the effective rank of A, which is defined as the order of the largest leading triangular submatrix R11 in the QR factorization with pivoting of A, whose estimated condition number $< 1/\text{RCOND}$.

IRANK (output)

The effective rank of A, i.e., the order of the submatrix R11. This is the same as the order of the submatrix T11 in the complete orthogonal factorization of A.

WORK (workspace)

(max(min(M,N)+3*N, 2*min(M,N)+NRHS)),

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dgelsy - compute the minimum-norm solution to a real linear least squares problem

SYNOPSIS

```
SUBROUTINE DGELSY(M, N, NRHS, A, LDA, B, LDB, JPVT, RCOND, RANK,
                 WORK, LWORK, INFO)
```

```
INTEGER M, N, NRHS, LDA, LDB, RANK, LWORK, INFO
INTEGER JPVT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), B(LDB,*), WORK(*)
```

```
SUBROUTINE DGELSY_64(M, N, NRHS, A, LDA, B, LDB, JPVT, RCOND, RANK,
                    WORK, LWORK, INFO)
```

```
INTEGER*8 M, N, NRHS, LDA, LDB, RANK, LWORK, INFO
INTEGER*8 JPVT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), B(LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSY([M], [N], [NRHS], A, [LDA], B, [LDB], JPVT, RCOND,
                RANK, [WORK], [LWORK], [INFO])
```

```
INTEGER :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO
INTEGER, DIMENSION(:) :: JPVT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GELSY_64([M], [N], [NRHS], A, [LDA], B, [LDB], JPVT,
                   RCOND, RANK, [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO
INTEGER(8), DIMENSION(:) :: JPVT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: WORK
```

REAL(8), DIMENSION(:, :) :: A, B

C INTERFACE

```
#include <sunperf.h>
```

```
void dgelsy(int m, int n, int nrhs, double *a, int lda, double *b, int ldb, int *jpvt, double rcond, int *rank, int *info);
```

```
void dgelsy_64(long m, long n, long nrhs, double *a, long lda, double *b, long ldb, long *jpvt, double rcond, long *rank, long *info);
```

PURPOSE

dgelsy computes the minimum-norm solution to a real linear least squares problem:

$$\text{minimize } || A * X - B ||$$

using a complete orthogonal factorization of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The routine first computes a QR factorization with column pivoting:

$$A * P = Q * \begin{bmatrix} R11 & R12 \\ 0 & R22 \end{bmatrix}$$

with R11 defined as the largest leading submatrix whose estimated condition number is less than 1/RCOND. The order of R11, RANK, is the effective rank of A.

Then, R22 is considered to be negligible, and R12 is annihilated by orthogonal transformations from the right, arriving at the complete orthogonal factorization:

$$A * P = Q * \begin{bmatrix} T11 & 0 \\ 0 & 0 \end{bmatrix} * Z$$

The minimum-norm solution is then

$$X = P * Z' * \begin{bmatrix} \text{inv}(T11) * Q1' * B \\ 0 \end{bmatrix}$$

where Q1 consists of the first RANK columns of Q.

This routine is basically identical to the original xGELSX except three differences:

- o The call to the subroutine xGEQPF has been substituted by the

- the call to the subroutine xGEQP3. This subroutine is a Blas-3

- version of the QR factorization with column pivoting.

- o Matrix B (the right hand side) is updated with Blas-3.

- o The permutation of matrix B (the right hand side) is faster and

- more simple.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of matrices B and X. $NRHS \geq 0$.

A (input/output)
On entry, the M-by-N matrix A. On exit, A has been overwritten by details of its complete orthogonal factorization.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
On entry, the M-by-NRHS right hand side matrix B. On exit, the N-by-NRHS solution matrix X.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, M, N)$.

JPVT (input/output)
On entry, if $JPVT(i) \neq 0$, the i-th column of A is permuted to the front of AP, otherwise column i is a free column. On exit, if $JPVT(i) = k$, then the i-th column of AP was the k-th column of A.

RCOND (input)
RCOND is used to determine the effective rank of A, which is defined as the order of the largest leading triangular submatrix R11 in the QR factorization with pivoting of A, whose estimated condition number $< 1/RCOND$.

RANK (output)
The effective rank of A, i.e., the order of the submatrix R11. This is the same as the order of the submatrix T11 in the complete orthogonal factorization of A.

WORK (workspace)
On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. The unblocked strategy requires that: $LWORK \geq \max(MN + 3*N + 1, 2*MN + NRHS)$, where $MN = \min(M, N)$. The block algorithm requires that: $LWORK \geq \max(MN + 2*N + NB*(N+1), 2*MN + NB*NRHS)$, where NB is an upper bound on the blocksize returned by ILAENV for the routines DGEQP3, STZRZF, STZRQF, SORMQR, and SORMRZ.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message

related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: If INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

Based on contributions by

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NAME

dgemm - perform one of the matrix-matrix operations C :=
alpha*op(A)*op(B) + beta*C

SYNOPSIS

```
SUBROUTINE DGEMM(TRANSA, TRANSB, M, N, K, ALPHA, A, LDA, B, LDB,  
                  BETA, C, LDC)
```

```
CHARACTER * 1 TRANSA, TRANSB  
INTEGER M, N, K, LDA, LDB, LDC  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*)
```

```
SUBROUTINE DGEMM_64(TRANSA, TRANSB, M, N, K, ALPHA, A, LDA, B, LDB,  
                    BETA, C, LDC)
```

```
CHARACTER * 1 TRANSA, TRANSB  
INTEGER*8 M, N, K, LDA, LDB, LDC  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE GEMM([TRANSA], [TRANSB], [M], [N], [K], ALPHA, A, [LDA],  
                B, [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: TRANSA, TRANSB  
INTEGER :: M, N, K, LDA, LDB, LDC  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:, :) :: A, B, C
```

```
SUBROUTINE GEMM_64([TRANSA], [TRANSB], [M], [N], [K], ALPHA, A, [LDA],  
                  B, [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: TRANSA, TRANSB  
INTEGER(8) :: M, N, K, LDA, LDB, LDC  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:, :) :: A, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgemm(char transa, char transb, int m, int n, int k,
           double alpha, double *a, int lda, double *b, int
           ldb, double beta, double *c, int ldc);
```

```
void dgemm_64(char transa, char transb, long m, long n, long
              k, double alpha, double *a, long lda, double *b,
              long ldb, double beta, double *c, long ldc);
```

PURPOSE

dgemm performs one of the matrix-matrix operations $C := \alpha * \text{op}(A) * \text{op}(B) + \beta * C$ where $\text{op}(X)$ is one of

$\text{op}(X) = X$ or $\text{op}(X) = X'$,

alpha and beta are scalars, and A, B and C are matrices, with $\text{op}(A)$ an m by k matrix, $\text{op}(B)$ a k by n matrix and C an m by n matrix.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n', $\text{op}(A) = A$.

TRANSA = 'T' or 't', $\text{op}(A) = A'$.

TRANSA = 'C' or 'c', $\text{op}(A) = A'$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

TRANSB (input)

On entry, TRANSB specifies the form of $\text{op}(B)$ to be used in the matrix multiplication as follows:

TRANSB = 'N' or 'n', $\text{op}(B) = B$.

TRANSB = 'T' or 't', $\text{op}(B) = B'$.

TRANSB = 'C' or 'c', $\text{op}(B) = B'$.

Unchanged on exit.

TRANSB is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix $\text{op}(A)$ and of the matrix C. M must be at least zero. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of

the matrix $op(B)$ and the number of columns of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry, K specifies the number of columns of the matrix $op(A)$ and the number of rows of the matrix $op(B)$. K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

DOUBLE PRECISION array of DIMENSION (LDA, ka), where ka is k when $TRANSA = 'N'$ or $'n'$, and is m otherwise. Before entry with $TRANSA = 'N'$ or $'n'$, the leading m by k part of the array A must contain the matrix A , otherwise the leading k by m part of the array A must contain the matrix A . Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When $TRANSA = 'N'$ or $'n'$ then $LDA \geq \max(1, m)$, otherwise $LDA \geq \max(1, k)$. Unchanged on exit.

B (input)

DOUBLE PRECISION array of DIMENSION (LDB, kb), where kb is n when $TRANSB = 'N'$ or $'n'$, and is k otherwise. Before entry with $TRANSB = 'N'$ or $'n'$, the leading k by n part of the array B must contain the matrix B , otherwise the leading n by k part of the array B must contain the matrix B . Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. When $TRANSB = 'N'$ or $'n'$ then $LDB \geq \max(1, k)$, otherwise $LDB \geq \max(1, n)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar β . When BETA is supplied as zero then C need not be set on input. Unchanged on exit.

C (input/output)

DOUBLE PRECISION array of DIMENSION (LDC, n). Before entry, the leading m by n part of the array C must contain the matrix C , except when β is zero, in which case C need not be set on entry. On exit, the array C is overwritten by the m by n matrix $(\alpha * op(A) * op(B) + \beta * C)$.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. $LDC \geq \max(1, m)$. Unchanged on exit.

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NAME

dgemv - perform one of the matrix-vector operations $y := \alpha A x + \beta y$ or $y := \alpha A' x + \beta y$

SYNOPSIS

```
SUBROUTINE DGEMV(TRANSA, M, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA  
INTEGER M, N, LDA, INCX, INCY  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), X(*), Y(*)
```

```
SUBROUTINE DGEMV_64(TRANSA, M, N, ALPHA, A, LDA, X, INCX, BETA, Y,  
INCY)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 M, N, LDA, INCX, INCY  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE GEMV([TRANSA], [M], [N], ALPHA, A, [LDA], X, [INCX], BETA,  
Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: M, N, LDA, INCX, INCY  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:) :: X, Y  
REAL(8), DIMENSION(:,:) :: A
```

```
SUBROUTINE GEMV_64([TRANSA], [M], [N], ALPHA, A, [LDA], X, [INCX],  
BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: M, N, LDA, INCX, INCY  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:) :: X, Y  
REAL(8), DIMENSION(:,:) :: A
```

C INTERFACE

```
#include <sunperf.h>

void dgemv(char transa, int m, int n, double alpha, double
          *a, int lda, double *x, int incx, double beta,
          double *y, int incy);
void dgemv_64(char transa, long m, long n, double alpha,
             double *a, long lda, double *x, long incx, double
             beta, double *y, long incy);
```

PURPOSE

dgemv performs one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A' x + \beta y$, where α and β are scalars, x and y are vectors and A is an m by n matrix.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $y := \alpha A x + \beta y$.

TRANSA = 'T' or 't' $y := \alpha A' x + \beta y$.

TRANSA = 'C' or 'c' $y := \alpha A' x + \beta y$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry, the leading m by n part of the array A must contain the matrix of coefficients. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, m)$. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$ when TRANSA = 'N' or

'n' and at least $(1 + (m - 1) * \text{abs}(\text{INCX}))$ otherwise. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

$(1 + (m - 1) * \text{abs}(\text{INCY}))$ when $\text{TRANSA} = 'N'$ or 'n' and at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$ otherwise. Before entry with BETA non-zero, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

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NAME

dgeqlf - compute a QL factorization of a real M-by-N matrix
A

SYNOPSIS

```
SUBROUTINE DGEQLF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DGEQLF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQLF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GEQLF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgeqlf(int m, int n, double *a, int lda, double *tau,  
           int *info);
```

```
void dgeqlf_64(long m, long n, double *a, long lda, double  
              *tau, long *info);
```

PURPOSE

dgeqlf computes a QL factorization of a real M-by-N matrix
A: $A = Q * L$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $m \geq n$, the lower triangle of the subarray $A(m-n+1:m, 1:n)$ contains the N-by-N lower triangular matrix L; if $m < n$, the elements on and below the $(n-m)$ -th superdiagonal contain the M-by-N lower trapezoidal matrix L; the remaining elements, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(k) \dots H(2) H(1)$, where $k = \min(m, n)$.
Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real scalar, and v is a real vector with $v(m-k+i+1:m) = 0$ and $v(m-k+i) = 1$; $v(1:m-k+i-1)$ is stored on exit in $A(1:m-k+i-1, n-k+i)$, and τ in $TAU(i)$.

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NAME

dgeqp3 - compute a QR factorization with column pivoting of a matrix A

SYNOPSIS

```
SUBROUTINE DGEQP3(M, N, A, LDA, JPVT, TAU, WORK, LWORK, INFO)

INTEGER M, N, LDA, LWORK, INFO
INTEGER JPVT(*)
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)

SUBROUTINE DGEQP3_64(M, N, A, LDA, JPVT, TAU, WORK, LWORK, INFO)

INTEGER*8 M, N, LDA, LWORK, INFO
INTEGER*8 JPVT(*)
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQP3([M], [N], A, [LDA], JPVT, TAU, [WORK], [LWORK],
  [INFO])

INTEGER :: M, N, LDA, LWORK, INFO
INTEGER, DIMENSION(:) :: JPVT
REAL(8), DIMENSION(:) :: TAU, WORK
REAL(8), DIMENSION(:, :) :: A

SUBROUTINE GEQP3_64([M], [N], A, [LDA], JPVT, TAU, [WORK], [LWORK],
  [INFO])

INTEGER(8) :: M, N, LDA, LWORK, INFO
INTEGER(8), DIMENSION(:) :: JPVT
REAL(8), DIMENSION(:) :: TAU, WORK
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>

void dgeqp3(int m, int n, double *a, int lda, int *jpvt,
```

```

        double *tau, int *info);

void dgeqp3_64(long m, long n, double *a, long lda, long
        *jpvt, double *tau, long *info);

```

PURPOSE

dgeqp3 computes a QR factorization with column pivoting of a matrix A: $A^*P = Q^*R$ using Level 3 BLAS.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the upper triangle of the array contains the $\min(M,N)$ -by-N upper trapezoidal matrix R; the elements below the diagonal, together with the array TAU, represent the orthogonal matrix Q as a product of $\min(M,N)$ elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

JPVT (input/output)

On entry, if $JPVT(J) \neq 0$, the J-th column of A is permuted to the front of A*P (a leading column); if $JPVT(J)=0$, the J-th column of A is a free column. On exit, if $JPVT(J)=K$, then the J-th column of A*P was the the K-th column of A.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

On exit, if $INFO=0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq 3*N+1$. For optimal performance $LWORK \geq 2*N+(N+1)*NB$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.

< 0: if $INFO = -i$, the i-th argument had an ille-

gal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m,n).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real/complex scalar, and v is a real/complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$, and τ in $TAU(i)$.

Based on contributions by

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NAME

dgeqpf - routine is deprecated and has been replaced by routine DGEQP3

SYNOPSIS

```
SUBROUTINE DGEQPF(M, N, A, LDA, JPIVOT, TAU, WORK, INFO)
```

```
INTEGER M, N, LDA, INFO  
INTEGER JPIVOT(*)  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DGEQPF_64(M, N, A, LDA, JPIVOT, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, LDA, INFO  
INTEGER*8 JPIVOT(*)  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQPF([M], [N], A, [LDA], JPIVOT, TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, LDA, INFO  
INTEGER, DIMENSION(:) :: JPIVOT  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GEQPF_64([M], [N], A, [LDA], JPIVOT, TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: JPIVOT  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgeqpf(int m, int n, double *a, int lda, int *jpivot,  
           double *tau, int *info);
```

```
void dgeqpf_64(long m, long n, double *a, long lda, long
               *jpivot, double *tau, long *info);
```

PURPOSE

dgeqpf routine is deprecated and has been replaced by routine DGEQP3.

DGEQPF computes a QR factorization with column pivoting of a real M-by-N matrix A: $A^*P = Q^*R$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$

A (input/output)

On entry, the M-by-N matrix A. On exit, the upper triangle of the array contains the $\min(M,N)$ -by-N upper triangular matrix R; the elements below the diagonal, together with the array TAU, represent the orthogonal matrix Q as a product of $\min(m,n)$ elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

JPIVOT (input/output)

On entry, if $JPIVOT(i) \neq 0$, the i-th column of A is permuted to the front of A^*P (a leading column); if $JPIVOT(i) = 0$, the i-th column of A is a free column. On exit, if $JPIVOT(i) = k$, then the i-th column of A^*P was the k-th column of A.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n)$$

Each $H(i)$ has the form

$$H = I - \tau * v * v'$$

where τ is a real scalar, and v is a real vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$.

The matrix P is represented in $jpvt$ as follows: If

$$jpvt(j) = i$$

then the j th column of P is the i th canonical unit vector.

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NAME

dgeqrf - compute a QR factorization of a real M-by-N matrix
A

SYNOPSIS

```
SUBROUTINE DGEQRF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DGEQRF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQRF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GEQRF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgeqrf(int m, int n, double *a, int lda, double *tau,  
           int *info);
```

```
void dgeqrf_64(long m, long n, double *a, long lda, double  
             *tau, long *info);
```

PURPOSE

dgeqrf computes a QR factorization of a real M-by-N matrix
A: $A = Q * R$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the elements on and above the diagonal of the array contain the min(M,N)-by-N upper trapezoidal matrix R (R is upper triangular if $m \geq n$); the elements below the diagonal, with the array TAU, represent the orthogonal matrix Q as a product of min(m,n) elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m, n).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with
 $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in
 $A(i+1:m,i)$, and tau in $TAU(i)$.

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NAME

dger - perform the rank 1 operation $A := \alpha x y' + A$

SYNOPSIS

```
SUBROUTINE DGER(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
INTEGER M, N, INCX, INCY, LDA  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), Y(*), A(LDA,*)
```

```
SUBROUTINE DGER_64(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
INTEGER*8 M, N, INCX, INCY, LDA  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), Y(*), A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE GER([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
INTEGER :: M, N, INCX, INCY, LDA  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X, Y  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GER_64([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
INTEGER(8) :: M, N, INCX, INCY, LDA  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X, Y  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dger(int m, int n, double alpha, double *x, int incx,  
         double *y, int incy, double *a, int lda);
```

```
void dger_64(long m, long n, double alpha, double *x, long  
            incx, double *y, long incy, double *a, long lda);
```

PURPOSE

dger performs the rank 1 operation $A := \alpha x y' + A$, where α is a scalar, x is an m element vector, y is an n element vector and A is an m by n matrix.

ARGUMENTS

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (m - 1) \cdot \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the m element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

$(1 + (n - 1) \cdot \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

A (input/output)

Before entry, the leading m by n part of the array A must contain the matrix of coefficients. On exit, A is overwritten by the updated matrix.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $\text{LDA} \geq \max(1, m)$. Unchanged on exit.

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NAME

dgerfs - improve the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE DGERFS(TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,  
X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER IPIVOT(*), WORK2(*)  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DGERFS_64(TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,  
LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*), WORK2(*)  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GERFS([TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT,  
B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, WORK2  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK  
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

```
SUBROUTINE GERFS_64([TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],  
IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
```

```
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
void dgerfs(char transa, int n, int nrhs, double *a, int
            lda, double *af, int ldaf, int *ipivot, double *b,
            int ldb, double *x, int ldx, double *ferr, double
            *berr, int *info);

void dgerfs_64(char transa, long n, long nrhs, double *a,
              long lda, double *af, long ldaf, long *ipivot,
              double *b, long ldb, double *x, long ldx, double
              *ferr, double *berr, long *info);
```

PURPOSE

dgerfs improves the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{*T} * X = B$ (Transpose)
= 'C': $A^{*H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The original N-by-N matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)

The factors L and U from the factorization $A = P * L * U$ as computed by DGETRF.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

IPIVOT (input)

The pivot indices from DGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by
DGETRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq
max(1,N).

FERR (output)
The estimated forward error bound for each solu-
tion vector X(j) (the j-th column of the solution
matrix X). If XTRUE is the true solution
corresponding to X(j), FERR(j) is an estimated
upper bound for the magnitude of the largest ele-
ment in (X(j) - XTRUE) divided by the magnitude of
the largest element in X(j). The estimate is as
reliable as the estimate for RCOND, and is almost
always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each
solution vector X(j) (i.e., the smallest relative
change in any element of A or B that makes X(j) an
exact solution).

WORK (workspace)
dimension(3*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

dgerqf - compute an RQ factorization of a real M-by-N matrix
A

SYNOPSIS

```
SUBROUTINE DGERQF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DGERQF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GERQF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GERQF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgerqf(int m, int n, double *a, int lda, double *tau,  
           int *info);
```

```
void dgerqf_64(long m, long n, double *a, long lda, double  
              *tau, long *info);
```

PURPOSE

dgerqf computes an RQ factorization of a real M-by-N matrix
A: $A = R * Q$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $m \leq n$, the upper triangle of the subarray A(1:m,n-m+1:n) contains the M-by-M upper triangular matrix R; if $m \geq n$, the elements on and above the (m-n)-th subdiagonal contain the M-by-N upper trapezoidal matrix R; the remaining elements, with the array TAU, represent the orthogonal matrix Q as a product of $\min(m,n)$ elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1,M)$. For optimum performance $LDWORK \geq M*NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(1) H(2) \dots H(k)$, where $k = \min(m,n)$.
Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real scalar, and v is a real vector with $v(n-k+i+1:n) = 0$ and $v(n-k+i) = 1$; $v(1:n-k+i-1)$ is stored on exit in $A(m-k+i,1:n-k+i-1)$, and τ in $TAU(i)$.

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NAME

dgesdd - compute the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and right singular vectors

SYNOPSIS

```
SUBROUTINE DGESDD(JOBZ, M, N, A, LDA, S, U, LDU, VT, LDVT, WORK,  
                 LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOBZ  
INTEGER M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION A(LDA,*), S(*), U(LDU,*), VT(LDVT,*),  
WORK(*)
```

```
SUBROUTINE DGESDD_64(JOBZ, M, N, A, LDA, S, U, LDU, VT, LDVT, WORK,  
                    LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOBZ  
INTEGER*8 M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION A(LDA,*), S(*), U(LDU,*), VT(LDVT,*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GESDD(JOBZ, [M], [N], A, [LDA], S, U, [LDU], VT, [LDVT],  
                [WORK], [LWORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ  
INTEGER :: M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: S, WORK  
REAL(8), DIMENSION(:, :) :: A, U, VT
```

```
SUBROUTINE GESDD_64(JOBZ, [M], [N], A, [LDA], S, U, [LDU], VT, [LDVT],  
                   [WORK], [LWORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ
```

```
INTEGER(8) :: M, N, LDA, LDU, LDVT, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: S, WORK
REAL(8), DIMENSION(:, :) :: A, U, VT
```

C INTERFACE

```
#include <sunperf.h>
void dgesdd(char jobz, int m, int n, double *a, int lda,
            double *s, double *u, int ldu, double *vt, int
            ldvt, int *info);

void dgesdd_64(char jobz, long m, long n, double *a, long
              lda, double *s, double *u, long ldu, double *vt,
              long ldvt, long *info);
```

PURPOSE

dgesdd computes the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and right singular vectors. If singular vectors are desired, it uses a divide-and-conquer algorithm.

The SVD is written
$$= U * SIGMA * transpose(V)$$

where SIGMA is an M-by-N matrix which is zero except for its min(m,n) diagonal elements, U is an M-by-M orthogonal matrix, and V is an N-by-N orthogonal matrix. The diagonal elements of SIGMA are the singular values of A; they are real and non-negative, and are returned in descending order. The first min(m,n) columns of U and V are the left and right singular vectors of A.

Note that the routine returns VT = V**T, not V.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)

Specifies options for computing all or part of the matrix U:

= 'A': all M columns of U and all N rows of V**T are returned in the arrays U and VT; = 'S': the first min(M,N) columns of U and the first min(M,N) rows of V**T are returned in the arrays U and VT; = 'O': If M >= N, the first N columns of U are overwritten on the array A and all rows of V**T are returned in the array VT; otherwise, all columns of U are returned in the array U and the

first M rows of V**T are overwritten on the array A; = 'N': no columns of U or rows of V**T are computed.

M (input) The number of rows of the input matrix A. $M \geq 0$.

N (input) The number of columns of the input matrix A. $N \geq 0$.

A (input/output)
On entry, the M-by-N matrix A. On exit, if JOBZ = 'O', A is overwritten with the first N columns of U (the left singular vectors, stored columnwise) if $M \geq N$; A is overwritten with the first M rows of V**T (the right singular vectors, stored rowwise) otherwise. if JOBZ .ne. 'O', the contents of A are destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.

S (output)
The singular values of A, sorted so that $S(i) \geq S(i+1)$.

U (output)
 $UCOL = M$ if JOBZ = 'A' or JOBZ = 'O' and $M < N$; $UCOL = \min(M, N)$ if JOBZ = 'S'. If JOBZ = 'A' or JOBZ = 'O' and $M < N$, U contains the M-by-M orthogonal matrix U; if JOBZ = 'S', U contains the first $\min(M, N)$ columns of U (the left singular vectors, stored columnwise); if JOBZ = 'O' and $M \geq N$, or JOBZ = 'N', U is not referenced.

LDU (input)
The leading dimension of the array U. $LDU \geq 1$; if JOBZ = 'S' or 'A' or JOBZ = 'O' and $M < N$, $LDU \geq M$.

VT (output)
If JOBZ = 'A' or JOBZ = 'O' and $M \geq N$, VT contains the N-by-N orthogonal matrix V**T; if JOBZ = 'S', VT contains the first $\min(M, N)$ rows of V**T (the right singular vectors, stored rowwise); if JOBZ = 'O' and $M < N$, or JOBZ = 'N', VT is not referenced.

LDVT (input)
The leading dimension of the array VT. $LDVT \geq 1$; if JOBZ = 'A' or JOBZ = 'O' and $M \geq N$, $LDVT \geq N$; if JOBZ = 'S', $LDVT \geq \min(M, N)$.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK;

LWORK (input)
The dimension of the array WORK. $LWORK \geq 1$. If $LWORK = -1$, then a workspace query is assumed. In this case, the routine only calculates the optimal

size of the work array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued. The minimum workspace size requirement is as follows:

```
If M is much larger than N such that  $M \geq (N * 11/6)$ :
  If JOBZ = 'N', LWORK  $\geq 3*N*N + 7*N$ 
  If JOBZ = 'O', LWORK  $\geq 3*N*N + 7*N + 2*N*N + 2*N$ 
  If JOBZ = 'S', LWORK  $\geq 3*N*N + 7*N + N*N + 2*N$ 
  If JOBZ = 'A', LWORK  $\geq 3*N*N + 7*N + N*N + M + N$ 
If M is at least N but not much larger ( $M < (N * 11/6)$ ):
  If JOBZ = 'N', LWORK  $\geq 1$ 
  If JOBZ = 'O', LWORK  $\geq 3*N*N + 7*N + N*N + 2*N + M$ 
  If JOBZ = 'S', LWORK  $\geq 3*N*N + 7*N + 2*N + M$ 
  If JOBZ = 'A', LWORK  $\geq 3*N*N + 7*N + 2*N + M$ 
If N is much larger than M such that  $N \geq (M * 11/6)$ :
  If JOBZ = 'N', LWORK  $\geq 3*M*M + 7*M$ 
  If JOBZ = 'O', LWORK  $\geq 3*M*M + 7*M + 2*M*M + 2*M$ 
  If JOBZ = 'S', LWORK  $\geq 3*M*M + 7*M + M*M + 2*M$ 
  If JOBZ = 'A', LWORK  $\geq 3*M*M + 7*M + M*M + M + N$ 
If N is larger than M and  $N < (M * 11/6)$ :
  If JOBZ = 'N', LWORK  $\geq 1$ 
  If JOBZ = 'O', LWORK  $\geq 3*M*M + 7*M + M*M + 2*M + N$ 
  If JOBZ = 'S', LWORK  $\geq 3*M*M + 7*M + 2*M + N$ 
  If JOBZ = 'A', LWORK  $\geq 3*M*M + 7*M + 2*M + N$ 
```

IWORK (workspace)
dimension(8*MIN(M,N))

INFO (output)
= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: SBDSDC did not converge, updating process failed.

FURTHER DETAILS

Based on contributions by
Ming Gu and Huan Ren, Computer Science Division, University of
California at Berkeley, USA

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NAME

dgesv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DGESV(N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
INTEGER N, NRHS, LDA, LDB, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DGESV_64(N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
INTEGER*8 N, NRHS, LDA, LDB, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GESV([N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
INTEGER :: N, NRHS, LDA, LDB, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GESV_64([N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDA, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgesv(int n, int nrhs, double *a, int lda, int *ipivot,
           double *b, int ldb, int *info);
```

```
void dgesv_64(long n, long nrhs, double *a, long lda, long
              *ipivot, double *b, long ldb, long *info);
```

PURPOSE

dgesv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N matrix and X and B are N-by-NRHS matrices.

The LU decomposition with partial pivoting and row interchanges is used to factor A as

$$A = P * L * U,$$

where P is a permutation matrix, L is unit lower triangular, and U is upper triangular. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the N-by-N coefficient matrix A. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

IPIVOT (output)

The pivot indices that define the permutation matrix P; row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)

On entry, the N-by-NRHS matrix of right hand side matrix B. On exit, if $INFO = 0$, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, $U(i,i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution could not be computed.

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NAME

dgesvd - compute the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and/or right singular vectors

SYNOPSIS

```
SUBROUTINE DGESVD(JOBU, JOBVT, M, N, A, LDA, SING, U, LDU, VT, LDVT,  
WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBU, JOBVT  
INTEGER M, N, LDA, LDU, LDVT, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), SING(*), U(LDU,*), VT(LDVT,*),  
WORK(*)
```

```
SUBROUTINE DGESVD_64(JOBU, JOBVT, M, N, A, LDA, SING, U, LDU, VT,  
LDVT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBU, JOBVT  
INTEGER*8 M, N, LDA, LDU, LDVT, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), SING(*), U(LDU,*), VT(LDVT,*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GESVD(JOBU, JOBVT, [M], [N], A, [LDA], SING, U, [LDU], VT,  
[LDVT], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBVT  
INTEGER :: M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL(8), DIMENSION(:) :: SING, WORK  
REAL(8), DIMENSION(:, :) :: A, U, VT
```

```
SUBROUTINE GESVD_64(JOBU, JOBVT, [M], [N], A, [LDA], SING, U, [LDU],  
VT, [LDVT], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBVT  
INTEGER(8) :: M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL(8), DIMENSION(:) :: SING, WORK  
REAL(8), DIMENSION(:, :) :: A, U, VT
```

C INTERFACE

```
#include <sunperf.h>

void dgesvd(char jobu, char jobvt, int m, int n, double *a,
            int lda, double *sing, double *u, int ldu, double
            *vt, int ldvt, int *info);
void dgesvd_64(char jobu, char jobvt, long m, long n, double
               *a, long lda, double *sing, double *u, long ldu,
               double *vt, long ldvt, long *info);
```

PURPOSE

dgesvd computes the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and/or right singular vectors. The SVD is written

$$= U * SIGMA * transpose(V)$$

where SIGMA is an M-by-N matrix which is zero except for its min(m,n) diagonal elements, U is an M-by-M orthogonal matrix, and V is an N-by-N orthogonal matrix. The diagonal elements of SIGMA are the singular values of A; they are real and non-negative, and are returned in descending order. The first min(m,n) columns of U and V are the left and right singular vectors of A.

Note that the routine returns V**T, not V.

ARGUMENTS

JOBU (input)

Specifies options for computing all or part of the matrix U:

- = 'A': all M columns of U are returned in array U;
- = 'S': the first min(m,n) columns of U (the left singular vectors) are returned in the array U; =
- 'O': the first min(m,n) columns of U (the left singular vectors) are overwritten on the array A;
- = 'N': no columns of U (no left singular vectors) are computed.

JOBVT (input)

Specifies options for computing all or part of the matrix V**T:

- = 'A': all N rows of V**T are returned in the array VT;
- = 'S': the first min(m,n) rows of V**T (the right singular vectors) are returned in the array VT; =
- 'O': the first min(m,n) rows of V**T (the right singular vectors) are overwritten on the array A;
- = 'N': no rows of V**T (no right singular vectors) are computed.

JOBVT and JOBVT cannot both be 'O'.

M (input) The number of rows of the input matrix A. M >= 0.

N (input) The number of columns of the input matrix A. N >=

0.

A (input/output)

On entry, the M-by-N matrix A. On exit, if JOBU = 'O', A is overwritten with the first min(m,n) columns of U (the left singular vectors, stored columnwise); if JOBVT = 'O', A is overwritten with the first min(m,n) rows of V**T (the right singular vectors, stored rowwise); if JOBU .ne. 'O' and JOBVT .ne. 'O', the contents of A are destroyed.

LDA (input)

The leading dimension of the array A. LDA >= max(1,M).

SING (output)

The singular values of A, sorted so that SING(i) >= SING(i+1).

U (input) (LDU,M) if JOBU = 'A' or (LDU,min(M,N)) if JOBU = 'S'. If JOBU = 'A', U contains the M-by-M orthogonal matrix U; if JOBU = 'S', U contains the first min(m,n) columns of U (the left singular vectors, stored columnwise); if JOBU = 'N' or 'O', U is not referenced.

LDU (input)

The leading dimension of the array U. LDU >= 1; if JOBU = 'S' or 'A', LDU >= M.

VT (input)

If JOBVT = 'A', VT contains the N-by-N orthogonal matrix V**T; if JOBVT = 'S', VT contains the first min(m,n) rows of V**T (the right singular vectors, stored rowwise); if JOBVT = 'N' or 'O', VT is not referenced.

LDVT (input)

The leading dimension of the array VT. LDVT >= 1; if JOBVT = 'A', LDVT >= N; if JOBVT = 'S', LDVT >= min(M,N).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK; if INFO > 0, WORK(2:MIN(M,N)) contains the unconverged superdiagonal elements of an upper bidiagonal matrix B whose diagonal is in SING (not necessarily sorted). B satisfies $A = U * B * VT$, so it has the same singular values as A, and singular vectors related by U and VT.

LDWORK (input)

The dimension of the array WORK. LDWORK >= 1. LDWORK >= MAX(3*MIN(M,N)+MAX(M,N),5*MIN(M,N)). For good performance, LDWORK should generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if SBDSQR did not converge, INFO specifies how many superdiagonals of an intermediate bidiagonal form B did not converge to zero. See the description of WORK above for details.

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NAME

dgesvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DGESVX(FACT, TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
    EQUED, R, C, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
    WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), R(*), C(*), B(LDB,*),
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DGESVX_64(FACT, TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
    EQUED, R, C, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
    WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), R(*), C(*), B(LDB,*),
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GESVX(FACT, [TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],
    IPIVOT, EQUED, R, C, B, [LDB], X, [LDX], RCOND, FERR,
    BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: R, C, FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

```
SUBROUTINE GESVX_64(FACT, [TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],
```

```
IPIVOT, EQUED, R, C, B, [LDB], X, [LDX], RCOND, FERR,  
BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: R, C, FERR, BERR, WORK  
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgesvx(char fact, char transa, int n, int nrhs, double  
*a, int lda, double *af, int ldaf, int *ipivot,  
char equed, double *r, double *c, double *b, int  
ldb, double *x, int ldx, double *rcond, double  
*ferr, double *berr, int *info);
```

```
void dgesvx_64(char fact, char transa, long n, long nrhs,  
double *a, long lda, double *af, long ldaf, long  
*ipivot, char equed, double *r, double *c, double  
*b, long ldb, double *x, long ldx, double *rcond,  
double *ferr, double *berr, long *info);
```

PURPOSE

dgesvx uses the LU factorization to compute the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N matrix and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'E', real scaling factors are computed to equilibrate

the system:

TRANS = 'N': $\text{diag}(R) * A * \text{diag}(C) * \text{inv}(\text{diag}(C)) * X = \text{diag}(R) * B$

TRANS = 'T': $(\text{diag}(R) * A * \text{diag}(C)) ** T * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

TRANS = 'C': $(\text{diag}(R) * A * \text{diag}(C)) ** H * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A, but if equilibration is used, A is

overwritten by $\text{diag}(R) * A * \text{diag}(C)$ and B by $\text{diag}(R) * B$ (if TRANS='N')

or $\text{diag}(C) * B$ (if TRANS = 'T' or 'C').

2. If FACT = 'N' or 'E', the LU decomposition is used to factor the

matrix A (after equilibration if FACT = 'E') as

$A = P * L * U$,

where P is a permutation matrix, L is a unit lower tri-

angular

matrix, and U is upper triangular.

3. If some $U(i,i)=0$, so that U is exactly singular, then the routine

returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

$INFO = N+1$ is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form

of A.

5. Iterative refinement is applied to improve the computed solution

matrix and calculate error bounds and backward error estimates

for it.

6. If equilibration was used, the matrix X is premultiplied by

$\text{diag}(C)$ (if $TRANS = 'N'$) or $\text{diag}(R)$ (if $TRANS = 'T'$ or $'C'$) so

that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF and IPIVOT contain the factored form of A. If EQUED is not 'N', the matrix A has been equilibrated with scaling factors given by R and C. A, AF, and IPIVOT are not modified. = 'N': The matrix A will be copied to AF and factored.

= 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

TRANSA (input)

Specifies the form of the system of equations:

= 'N': $A * X = B$ (No transpose)

= 'T': $A^{**T} * X = B$ (Transpose)

= 'C': $A^{**H} * X = B$ (Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. If FACT = 'F' and EQUED is not 'N', then A must have been equilibrated by the scaling factors in R and/or C. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if EQUED .ne. 'N', A is scaled as follows:
EQUED = 'R': A := diag(R) * A
EQUED = 'C': A := A * diag(C)
EQUED = 'B': A := diag(R) * A * diag(C).

LDA (input)

The leading dimension of the array A. LDA >= max(1,N).

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the factors L and U from the factorization $A = P*L*U$ as computed by DGETRF. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the factors L and U from the factorization $A = P*L*U$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the factors L and U from the factorization $A = P*L*U$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF >= max(1,N).

IPIVOT (input or output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the factorization $A = P*L*U$ as computed by DGETRF; row i of the matrix was interchanged with row IPIVOT(i).

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = P*L*U$ of the original matrix A.

If FACT = 'E', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = P*L*U$ of the equilibrated matrix A.

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'R': Row equilibration, i.e., A has been premultiplied by diag(R). = 'C': Column equilibration, i.e., A has been postmultiplied by diag(C). = 'B': Both row and column equilibra-

tion, i.e., A has been replaced by $\text{diag}(R) * A * \text{diag}(C)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

R (input or output)

The row scale factors for A. If EQUED = 'R' or 'B', A is multiplied on the left by $\text{diag}(R)$; if EQUED = 'N' or 'C', R is not accessed. R is an input argument if FACT = 'F'; otherwise, R is an output argument. If FACT = 'F' and EQUED = 'R' or 'B', each element of R must be positive.

C (input or output)

The column scale factors for A. If EQUED = 'C' or 'B', A is multiplied on the right by $\text{diag}(C)$; if EQUED = 'N' or 'R', C is not accessed. C is an input argument if FACT = 'F'; otherwise, C is an output argument. If FACT = 'F' and EQUED = 'C' or 'B', each element of C must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if TRANSA = 'N' and EQUED = 'R' or 'B', B is overwritten by $\text{diag}(R)*B$; if TRANSA = 'T' or 'C' and EQUED = 'C' or 'B', B is overwritten by $\text{diag}(C)*B$.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that A and B are modified on exit if EQUED .ne. 'N', and the solution to the equilibrated system is $\text{inv}(\text{diag}(C))*X$ if TRANSA = 'N' and EQUED = 'C' or 'B', or $\text{inv}(\text{diag}(R))*X$ if TRANSA = 'T' or 'C' and EQUED = 'R' or 'B'.

LDX (input)

The leading dimension of the array X. $LDX \geq \max(1, N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in X(j). The estimate is as

reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension(4*N) On exit, WORK(1) contains the reciprocal pivot growth factor $\text{norm}(A)/\text{norm}(U)$. The "max absolute element" norm is used. If WORK(1) is much less than 1, then the stability of the LU factorization of the (equilibrated) matrix A could be poor. This also means that the solution X, condition estimator RCOND, and forward error bound FERR could be unreliable. If factorization fails with $0 < \text{INFO} \leq N$, then WORK(1) contains the reciprocal pivot growth factor for the leading INFO columns of A.

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: $U(i,i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned.
= N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

dgetf2 - compute an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE DGETF2(M, N, A, LDA, IPIV, INFO)
```

```
INTEGER M, N, LDA, INFO  
INTEGER IPIV(*)  
DOUBLE PRECISION A(LDA,*)
```

```
SUBROUTINE DGETF2_64(M, N, A, LDA, IPIV, INFO)
```

```
INTEGER*8 M, N, LDA, INFO  
INTEGER*8 IPIV(*)  
DOUBLE PRECISION A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE GETF2([M], [N], A, [LDA], IPIV, [INFO])
```

```
INTEGER :: M, N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GETF2_64([M], [N], A, [LDA], IPIV, [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgetf2(int m, int n, double *a, int lda, int *ipiv, int  
           *info);
```

```
void dgetf2_64(long m, long n, double *a, long lda, long  
              *ipiv, long *info);
```

PURPOSE

dgetf2 computes an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges.

The factorization has the form

$$A = P * L * U$$

where P is a permutation matrix, L is lower triangular with unit diagonal elements (lower trapezoidal if $m > n$), and U is upper triangular (upper trapezoidal if $m < n$).

This is the right-looking Level 2 BLAS version of the algorithm.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the m by n matrix to be factored. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

IPIV (output)

The pivot indices; for $1 \leq i \leq \min(M,N)$, row i of the matrix was interchanged with row IPIV(i).

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value
> 0: if INFO = k, U(k,k) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

dgetrf - compute an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE DGETRF(M, N, A, LDA, IPIVOT, INFO)
```

```
INTEGER M, N, LDA, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION A(LDA,*)
```

```
SUBROUTINE DGETRF_64(M, N, A, LDA, IPIVOT, INFO)
```

```
INTEGER*8 M, N, LDA, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE GETRF([M], [N], A, [LDA], IPIVOT, [INFO])
```

```
INTEGER :: M, N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GETRF_64([M], [N], A, [LDA], IPIVOT, [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgetrf(int m, int n, double *a, int lda, int *ipivot,  
           int *info);
```

```
void dgetrf_64(long m, long n, double *a, long lda, long  
              *ipivot, long *info);
```

PURPOSE

dgetrf computes an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges.

The factorization has the form

$$A = P * L * U$$

where P is a permutation matrix, L is lower triangular with unit diagonal elements (lower trapezoidal if $m > n$), and U is upper triangular (upper trapezoidal if $m < n$).

This is the right-looking Level 3 BLAS version of the algorithm.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix to be factored. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

IPIVOT (output)

The pivot indices; for $1 \leq i \leq \min(M, N)$, row i of the matrix was interchanged with row IPIVOT(i).

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, $U(i, i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

dgetri - compute the inverse of a matrix using the LU factorization computed by DGETRF

SYNOPSIS

```
SUBROUTINE DGETRI(N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
INTEGER N, LDA, LDWORK, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DGETRI_64(N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
INTEGER*8 N, LDA, LDWORK, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GETRI([N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: N, LDA, LDWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE GETRI_64([N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: N, LDA, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgetri(int n, double *a, int lda, int *ipivot, int
            *info);
```

```
void dgetri_64(long n, double *a, long lda, long *ipivot,
               long *info);
```

PURPOSE

dgetri computes the inverse of a matrix using the LU factorization computed by DGETRF.

This method inverts U and then computes $\text{inv}(A)$ by solving the system $\text{inv}(A)*L = \text{inv}(U)$ for $\text{inv}(A)$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the factors L and U from the factorization $A = P*L*U$ as computed by DGETRF. On exit, if $\text{INFO} = 0$, the inverse of the original matrix A.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

The pivot indices from DGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row $\text{IPIVOT}(i)$.

WORK (workspace)

On exit, if $\text{INFO} = 0$, then $\text{WORK}(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $\text{LDWORK} \geq \max(1, N)$. For optimal performance $\text{LDWORK} \geq N*NB$, where NB is the optimal blocksize returned by ILAENV.

If $\text{LDWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if $\text{INFO} = -i$, the i-th argument had an illegal value

> 0: if $\text{INFO} = i$, $U(i, i)$ is exactly zero; the matrix is singular and its inverse could not be computed.

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NAME

dgetrs - solve a system of linear equations $A * X = B$ or $A' * X = B$ with a general N-by-N matrix A using the LU factorization computed by DGETRF

SYNOPSIS

```
SUBROUTINE DGETRS(TRANSA, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DGETRS_64(TRANSA, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GETRS([TRANSA], [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE GETRS_64([TRANSA], [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dgetrs(char transa, int n, int nrhs, double *a, int
            lda, int *ipivot, double *b, int ldb, int *info);

void dgetrs_64(char transa, long n, long nrhs, double *a,
               long lda, long *ipivot, double *b, long ldb, long
               *info);

```

PURPOSE

dgetrs solves a system of linear equations
 $A * X = B$ or $A' * X = B$ with a general N-by-N matrix A
using the LU factorization computed by DGETRF.

ARGUMENTS

TRANSA (input)
Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A' * X = B$ (Transpose)
= 'C': $A' * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The factors L and U from the factorization $A = P * L * U$ as computed by DGETRF.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)
The pivot indices from DGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)
On entry, the right hand side matrix B. On exit, the solution matrix X.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dggbak - form the right or left eigenvectors of a real generalized eigenvalue problem $A*x = \lambda*B*x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by DGBAL

SYNOPSIS

```
SUBROUTINE DGGBAK(JOB, SIDE, N, ILO, IHI, LSCALE, RSCALE, M, V, LDV,
  INFO)
```

```
CHARACTER * 1 JOB, SIDE
INTEGER N, ILO, IHI, M, LDV, INFO
DOUBLE PRECISION LSCALE(*), RSCALE(*), V(LDV,*)
```

```
SUBROUTINE DGGBAK_64(JOB, SIDE, N, ILO, IHI, LSCALE, RSCALE, M, V,
  LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE
INTEGER*8 N, ILO, IHI, M, LDV, INFO
DOUBLE PRECISION LSCALE(*), RSCALE(*), V(LDV,*)
```

F95 INTERFACE

```
SUBROUTINE GGBAK(JOB, SIDE, [N], ILO, IHI, LSCALE, RSCALE, [M], V,
  [LDV], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE
INTEGER :: N, ILO, IHI, M, LDV, INFO
REAL(8), DIMENSION(:) :: LSCALE, RSCALE
REAL(8), DIMENSION(:, :) :: V
```

```
SUBROUTINE GGBAK_64(JOB, SIDE, [N], ILO, IHI, LSCALE, RSCALE, [M], V,
  [LDV], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE
INTEGER(8) :: N, ILO, IHI, M, LDV, INFO
REAL(8), DIMENSION(:) :: LSCALE, RSCALE
REAL(8), DIMENSION(:, :) :: V
```

C INTERFACE

```
#include <sunperf.h>

void dggbak(char job, char side, int n, int ilo, int ihi,
            double *lscale, double *rscale, int m, double *v,
            int ldv, int *info);

void dggbak_64(char job, char side, long n, long ilo, long
              ihi, double *lscale, double *rscale, long m,
              double *v, long ldv, long *info);
```

PURPOSE

dggbak forms the right or left eigenvectors of a real generalized eigenvalue problem $A*x = \lambda*B*x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by DGGBAL.

ARGUMENTS

JOB (input)
Specifies the type of backward transformation required:
= 'N': do nothing, return immediately;
= 'P': do backward transformation for permutation only;
= 'S': do backward transformation for scaling only;
= 'B': do backward transformations for both permutation and scaling. JOB must be the same as the argument JOB supplied to DGGBAL.

SIDE (input)
= 'R': V contains right eigenvectors;
= 'L': V contains left eigenvectors.

N (input) The number of rows of the matrix V. $N \geq 0$.

ILO (input)
The integers ILO and IHI determined by DGGBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

IHI (input)
See the description for ILO.

LSCALE (input)
Details of the permutations and/or scaling factors applied to the left side of A and B, as returned by DGGBAL.

RSCALE (input)
Details of the permutations and/or scaling factors applied to the right side of A and B, as returned by DGGBAL.

M (input) The number of columns of the matrix V. $M \geq 0$.

V (input/output)

On entry, the matrix of right or left eigenvectors to be transformed, as returned by STGEVC. On exit, V is overwritten by the transformed eigenvectors.

LDV (input)

The leading dimension of the matrix V. $LDV \geq \max(1, N)$.

INFO (output)

= 0: successful exit.
< 0: if $INFO = -i$, the i -th argument had an illegal value.

FURTHER DETAILS

See R.C. Ward, Balancing the generalized eigenvalue problem, SIAM J. Sci. Stat. Comp. 2 (1981), 141-152.

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NAME

dggbal - balance a pair of general real matrices (A,B)

SYNOPSIS

```
SUBROUTINE DGGBAL(JOB, N, A, LDA, B, LDB, ILO, IHI, LSCALE, RSCALE,  
                  WORK, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER N, LDA, LDB, ILO, IHI, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), LSCALE(*), RSCALE(*),  
WORK(*)
```

```
SUBROUTINE DGGBAL_64(JOB, N, A, LDA, B, LDB, ILO, IHI, LSCALE,  
                    RSCALE, WORK, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER*8 N, LDA, LDB, ILO, IHI, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), LSCALE(*), RSCALE(*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGBAL(JOB, [N], A, [LDA], B, [LDB], ILO, IHI, LSCALE,  
                RSCALE, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER :: N, LDA, LDB, ILO, IHI, INFO  
REAL(8), DIMENSION(:) :: LSCALE, RSCALE, WORK  
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE GGBAL_64(JOB, [N], A, [LDA], B, [LDB], ILO, IHI, LSCALE,  
                   RSCALE, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER(8) :: N, LDA, LDB, ILO, IHI, INFO  
REAL(8), DIMENSION(:) :: LSCALE, RSCALE, WORK  
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>

void dggbal(char job, int n, double *a, int lda, double *b,
            int ldb, int *ilo, int *ihi, double *lscale, double
            *rscale, int *info);

void dggbal_64(char job, long n, double *a, long lda, double
               *b, long ldb, long *ilo, long *ihi, double
               *lscale, double *rscale, long *info);
```

PURPOSE

dggbal balances a pair of general real matrices (A,B). This involves, first, permuting A and B by similarity transformations to isolate eigenvalues in the first 1 to ILO\$-1 and last IHI+1 to N elements on the diagonal; and second, applying a diagonal similarity transformation to rows and columns ILO to IHI to make the rows and columns as close in norm as possible. Both steps are optional.

Balancing may reduce the 1-norm of the matrices, and improve the accuracy of the computed eigenvalues and/or eigenvectors in the generalized eigenvalue problem $A*x = \lambda*B*x$.

ARGUMENTS

JOB (input)

Specifies the operations to be performed on A and B:
 = 'N': none: simply set ILO = 1, IHI = N, LSCALE(I) = 1.0 and RSCALE(I) = 1.0 for i = 1,...,N.
 = 'P': permute only;
 = 'S': scale only;
 = 'B': both permute and scale.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the input matrix A. On exit, A is overwritten by the balanced matrix. If JOB = 'N', A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input) On entry, the input matrix B. On exit, B is overwritten by the balanced matrix. If JOB = 'N', B is not referenced.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

ILO (output)

ILO and IHI are set to integers such that on exit

$A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1, \dots, ILO-1$ or $i = IHI+1, \dots, N$. If $JOB = 'N'$ or $'S'$, $ILO = 1$ and $IHI = N$.

IHI (output)

See the description for ILO.

LSCALE (input)

Details of the permutations and scaling factors applied to the left side of A and B. If $P(j)$ is the index of the row interchanged with row j , and $D(j)$ is the scaling factor applied to row j , then $LSCALE(j) = P(j)$ for $J = 1, \dots, ILO-1$ and $LSCALE(j) = D(j)$ for $J = ILO, \dots, IHI$. $LSCALE(j) = P(j)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

RSCALE (input)

Details of the permutations and scaling factors applied to the right side of A and B. If $P(j)$ is the index of the column interchanged with column j , and $D(j)$ is the scaling factor applied to column j , then $RSCALE(j) = P(j)$ for $J = 1, \dots, ILO-1$ and $RSCALE(j) = D(j)$ for $J = ILO, \dots, IHI$. $RSCALE(j) = P(j)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

WORK (workspace)

dimension(6*N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value.

FURTHER DETAILS

See R.C. WARD, Balancing the generalized eigenvalue problem, SIAM J. Sci. Stat. Comp. 2 (1981), 141-152.

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NAME

dgges - compute for a pair of N-by-N real nonsymmetric matrices (A,B),

SYNOPSIS

```
SUBROUTINE DGGES(JOBVSL, JOBVSR, SORT, DELCTG, N, A, LDA, B, LDB,
                SDIM, ALPHAR, ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LWORK,
                BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT
INTEGER N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL DELCTG
LOGICAL BWORK(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
```

```
SUBROUTINE DGGES_64(JOBVSL, JOBVSR, SORT, DELCTG, N, A, LDA, B, LDB,
                  SDIM, ALPHAR, ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LWORK,
                  BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT
INTEGER*8 N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL*8 DELCTG
LOGICAL*8 BWORK(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGES(JOBVSL, JOBVSR, SORT, [DELCTG], [N], A, [LDA], B, [LDB],
                SDIM, ALPHAR, ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK],
                [LWORK], [BWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT
INTEGER :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL :: DELCTG
LOGICAL, DIMENSION(:) :: BWORK
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL(8), DIMENSION(:, :) :: A, B, VSL, VSR
```

```
SUBROUTINE GGES_64(JOBVSL, JOBVSR, SORT, [DELCTG], [N], A, [LDA], B,
```

```
[LDB], SDIM, ALPHAR, ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR],
[WORK], [LWORK], [BWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT
INTEGER(8) :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL(8) :: DELCTG
LOGICAL(8), DIMENSION(:) :: BWORK
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL(8), DIMENSION(:,:) :: A, B, VSL, VSR
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgges(char jobvsl, char jobvsr, char sort,
int(*delctg)(double,double,double), int n, double
*a, int lda, double *b, int ldb, int *sdim, double
*alphar, double *alphai, double *beta, double
*vsl, int ldvsl, double *vsr, int ldvsr, int
*info);
```

```
void dgges_64(char jobvsl, char jobvsr, char sort,
long(*delctg)(double,double,double), long n, dou-
ble *a, long lda, double *b, long ldb, long *sdim,
double *alphar, double *alphai, double *beta, dou-
ble *vsl, long ldvsl, double *vsr, long ldvsr,
long *info);
```

PURPOSE

dgges computes for a pair of N-by-N real nonsymmetric matrices (A,B), the generalized eigenvalues, the generalized real Schur form (S,T), optionally, the left and/or right matrices of Schur vectors (VSL and VSR). This gives the generalized Schur factorization

$$(A,B) = ((VSL)*S*(VSR)**T, (VSL)*T*(VSR)**T)$$

Optionally, it also orders the eigenvalues so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix S and the upper triangular matrix T. The leading columns of VSL and VSR then form an orthonormal basis for the corresponding left and right eigenspaces (deflating subspaces).

(If only the generalized eigenvalues are needed, use the driver DGGEV instead, which is faster.)

A generalized eigenvalue for a pair of matrices (A,B) is a scalar w or a ratio alpha/beta = w, such that A - w*B is singular. It is usually represented as the pair (alpha,beta), as there is a reasonable interpretation for beta=0 or both being zero.

A pair of matrices (S,T) is in generalized real Schur form if T is upper triangular with non-negative diagonal and S is block upper triangular with 1-by-1 and 2-by-2 blocks. 1-by-1 blocks correspond to real generalized eigenvalues, while 2-by-2 blocks of S will be "standardized" by making the corresponding elements of T have the form:

[a 0]
[0 b]

and the pair of corresponding 2-by-2 blocks in S and T will have a complex conjugate pair of generalized eigenvalues.

ARGUMENTS

JOBVSL (input)

= 'N': do not compute the left Schur vectors;
= 'V': compute the left Schur vectors.

JOBVSR (input)

= 'N': do not compute the right Schur vectors;
= 'V': compute the right Schur vectors.

SORT (input)

Specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form. = 'N': Eigenvalues are not ordered;
= 'S': Eigenvalues are ordered (see DELCTG);

DELCTG (input)

LOGICAL FUNCTION of three DOUBLE PRECISION arguments DELCTG must be declared EXTERNAL in the calling subroutine. If SORT = 'N', DELCTG is not referenced. If SORT = 'S', DELCTG is used to select eigenvalues to sort to the top left of the Schur form. An eigenvalue $(\text{ALPHAR}(j) + \text{ALPHAI}(j))/\text{BETA}(j)$ is selected if $\text{DELCTG}(\text{ALPHAR}(j), \text{ALPHAI}(j), \text{BETA}(j))$ is true; i.e. if either one of a complex conjugate pair of eigenvalues is selected, then both complex eigenvalues are selected.

Note that in the ill-conditioned case, a selected complex eigenvalue may no longer satisfy $\text{DELCTG}(\text{ALPHAR}(j), \text{ALPHAI}(j), \text{BETA}(j)) = \text{.TRUE.}$ after ordering. INFO is to be set to N+2 in this case.

N (input) The order of the matrices A, B, VSL, and VSR. N ≥ 0 .

A (input/output)

DOUBLE PRECISION array, dimension(LDA,A) On entry, the first of the pair of matrices. On exit, A has been overwritten by its generalized Schur form S.

LDA (input)

The leading dimension of A. LDA $\geq \max(1, N)$.

B (input/output)

DOUBLE PRECISION array, dimension (LDB, N) On entry, the second of the pair of matrices. On exit, B has been overwritten by its generalized Schur form T.

LDB (input)

The leading dimension of B. LDB $\geq \max(1, N)$.

SDIM (output)

If SORT = 'N', SDIM = 0. If SORT = 'S', SDIM = number of eigenvalues (after sorting) for which DELCTG is true. (Complex conjugate pairs for which DELCTG is true for either eigenvalue count as 2.)

ALPHAR (output)

On exit, $(\text{ALPHAR}(j) + \text{ALPHAI}(j)*i)/\text{BETA}(j)$, $j=1,\dots,N$, will be the generalized eigenvalues. $\text{ALPHAR}(j) + \text{ALPHAI}(j)*i$, and $\text{BETA}(j)$, $j=1,\dots,N$ are the diagonals of the complex Schur form (S,T) that would result if the 2-by-2 diagonal blocks of the real Schur form of (A,B) were further reduced to triangular form using 2-by-2 complex unitary transformations. If ALPHAI(j) is zero, then the j-th eigenvalue is real; if positive, then the j-th and (j+1)-st eigenvalues are a complex conjugate pair, with ALPHAI(j+1) negative.

Note: the quotients $\text{ALPHAR}(j)/\text{BETA}(j)$ and $\text{ALPHAI}(j)/\text{BETA}(j)$ may easily over- or underflow, and BETA(j) may even be zero. Thus, the user should avoid naively computing the ratio. However, ALPHAR and ALPHAI will be always less than and usually comparable with norm(A) in magnitude, and BETA always less than and usually comparable with norm(B).

ALPHAI (output)

See the description for ALPHAR.

BETA (output)

See the description for ALPHAR.

VSL (input)

If JOBVSL = 'V', VSL will contain the left Schur vectors. Not referenced if JOBVSL = 'N'.

LDVSL (input)

The leading dimension of the matrix VSL. LDVSL ≥ 1 , and if JOBVSL = 'V', LDVSL $\geq N$.

VSR (input)

If JOBVSR = 'V', VSR will contain the right Schur vectors. Not referenced if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR ≥ 1 , and if JOBVSR = 'V', LDVSR $\geq N$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK $\geq 8*N+16$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message

related to LWORK is issued by XERBLA.

BWORK (workspace)

dimension(N) Not referenced if SORT = 'N'.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

= 1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for j=INFO+1,...,N. >

N: =N+1: other than QZ iteration failed in SHGEQZ.

=N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Generalized Schur form no longer satisfy DELCTG=.TRUE. This could also be caused due to scaling. =N+3: reordering failed in

STGSEN.

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NAME

dggesx - compute for a pair of N-by-N real nonsymmetric matrices (A,B), the generalized eigenvalues, the real Schur form (S,T), and,

SYNOPSIS

```
SUBROUTINE DGGESX(JOBVSL, JOBVSR, SORT, DELCTG, SENSE, N, A, LDA, B,
  LDB, SDIM, ALPHAR, ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR, RCONDE,
  RCONDV, WORK, LWORK, IWORK, LIWORK, BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT, SENSE
INTEGER N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL DELCTG
LOGICAL BWORK(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), VSL(LDVSL,*), VSR(LDVSR,*), RCONDE(*), RCONDV(*),
WORK(*)
```

```
SUBROUTINE DGGESX_64(JOBVSL, JOBVSR, SORT, DELCTG, SENSE, N, A, LDA,
  B, LDB, SDIM, ALPHAR, ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR,
  RCONDE, RCONDV, WORK, LWORK, IWORK, LIWORK, BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT, SENSE
INTEGER*8 N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK,
INFO
INTEGER*8 IWORK(*)
LOGICAL*8 DELCTG
LOGICAL*8 BWORK(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), VSL(LDVSL,*), VSR(LDVSR,*), RCONDE(*), RCONDV(*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGESX(JOBVSL, JOBVSR, SORT, [DELCTG], SENSE, [N], A, [LDA],
  B, [LDB], SDIM, ALPHAR, ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR],
  RCONDE, RCONDV, [WORK], [LWORK], [IWORK], [LIWORK], [BWORK],
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT, SENSE
```

```

INTEGER :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK,
INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL :: DELCTG
LOGICAL, DIMENSION(:) :: BWORK
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, RCONDE,
RCONDV, WORK
REAL(8), DIMENSION(:,:) :: A, B, VSL, VSR
SUBROUTINE GGESX_64(JOBVSL, JOBVSR, SORT, [DELCTG], SENSE, [N], A, [LDA],
B, [LDB], SDIM, ALPHAR, ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR],
RCONDE, RCONDV, [WORK], [LWORK], [IWORK], [LIWORK], [BWORK],
[INFO])

```

```

CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT, SENSE
INTEGER(8) :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK,
LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8) :: DELCTG
LOGICAL(8), DIMENSION(:) :: BWORK
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, RCONDE,
RCONDV, WORK
REAL(8), DIMENSION(:,:) :: A, B, VSL, VSR

```

C INTERFACE

```

#include <sunperf.h>

void dggesx(char jobvsl, char jobvsr, char sort,
int(*delctg)(double,double,double), char sense,
int n, double *a, int lda, double *b, int ldb, int
*sdim, double *alphar, double *alphai, double
*beta, double *vsl, int ldvsl, double *vsr, int
ldvsr, double *rconde, double *rcondv, int *info);

void dggesx_64(char jobvsl, char jobvsr, char sort,
long(*delctg)(double,double,double), char sense,
long n, double *a, long lda, double *b, long ldb,
long *sdim, double *alphar, double *alphai, double
*beta, double *vsl, long ldvsl, double *vsr, long
ldvsr, double *rconde, double *rcondv, long
*info);

```

PURPOSE

dggesx computes for a pair of N-by-N real nonsymmetric matrices (A,B), the generalized eigenvalues, the real Schur form (S,T), and, optionally, the left and/or right matrices of Schur vectors (VSL and VSR). This gives the generalized Schur factorization

$$A, B = ((VSL) S (VSR)**T, (VSL) T (VSR)**T)$$

Optionally, it also orders the eigenvalues so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix S and the upper triangular matrix T; computes a reciprocal condition number for the average of the selected eigenvalues (RCONDE); and computes a reciprocal condition number for the right and left deflating subspaces corresponding to the selected eigenvalues (RCONDV). The leading columns of VSL and VSR

then form an orthonormal basis for the corresponding left and right eigenspaces (deflating subspaces).

A generalized eigenvalue for a pair of matrices (A,B) is a scalar w or a ratio $\alpha/\beta = w$, such that $A - w*B$ is singular. It is usually represented as the pair (α,β) , as there is a reasonable interpretation for $\beta=0$ or for both being zero.

A pair of matrices (S,T) is in generalized real Schur form if T is upper triangular with non-negative diagonal and S is block upper triangular with 1-by-1 and 2-by-2 blocks. 1-by-1 blocks correspond to real generalized eigenvalues, while 2-by-2 blocks of S will be "standardized" by making the corresponding elements of T have the form:

$$\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$$

and the pair of corresponding 2-by-2 blocks in S and T will have a complex conjugate pair of generalized eigenvalues.

ARGUMENTS

JOBVSL (input)

= 'N': do not compute the left Schur vectors;
= 'V': compute the left Schur vectors.

JOBVSR (input)

= 'N': do not compute the right Schur vectors;
= 'V': compute the right Schur vectors.

SORT (input)

Specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form. = 'N': Eigenvalues are not ordered;
= 'S': Eigenvalues are ordered (see DELCTG).

DELCTG (input)

LOGICAL FUNCTION of three DOUBLE PRECISION arguments DELCTG must be declared EXTERNAL in the calling subroutine. If SORT = 'N', DELCTG is not referenced. If SORT = 'S', DELCTG is used to select eigenvalues to sort to the top left of the Schur form. An eigenvalue $(\text{ALPHAR}(j)+\text{ALPHAI}(j))/\text{BETA}(j)$ is selected if $\text{DELCTG}(\text{ALPHAR}(j),\text{ALPHAI}(j),\text{BETA}(j))$ is true; i.e. if either one of a complex conjugate pair of eigenvalues is selected, then both complex eigenvalues are selected. Note that a selected complex eigenvalue may no longer satisfy $\text{DELCTG}(\text{ALPHAR}(j),\text{ALPHAI}(j),\text{BETA}(j)) = \text{.TRUE.}$ after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned), in this case INFO is set to N+3.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N' : None are computed;

= 'E' : Computed for average of selected eigenvalues only;
= 'V' : Computed for selected deflating subspaces only;
= 'B' : Computed for both. If SENSE = 'E', 'V', or 'B', SORT must equal 'S'.

N (input) The order of the matrices A, B, VSL, and VSR. N >= 0.

A (input/output)
DOUBLE PRECISION array, dimension(LDA,N) On entry, the first of the pair of matrices. On exit, A has been overwritten by its generalized Schur form S.

LDA (input)
The leading dimension of A. LDA >= max(1,N).

B (input/output)
DOUBLE PRECISION array, dimension(LDB,N) On entry, the second of the pair of matrices. On exit, B has been overwritten by its generalized Schur form T.

LDB (input)
The leading dimension of B. LDB >= max(1,N).

SDIM (output)
If SORT = 'N', SDIM = 0. If SORT = 'S', SDIM = number of eigenvalues (after sorting) for which DELCTG is true. (Complex conjugate pairs for which DELCTG is true for either eigenvalue count as 2.)

ALPHAR (output)
DOUBLE PRECISION array, dimension(N) On exit, $(\text{ALPHAR}(j) + \text{ALPHAI}(j)*i)/\text{BETA}(j)$, $j=1, \dots, N$, will be the generalized eigenvalues. $\text{ALPHAR}(j) + \text{ALPHAI}(j)*i$ and $\text{BETA}(j)$, $j=1, \dots, N$ are the diagonals of the complex Schur form (S,T) that would result if the 2-by-2 diagonal blocks of the real Schur form of (A,B) were further reduced to triangular form using 2-by-2 complex unitary transformations. If ALPHAI(j) is zero, then the j-th eigenvalue is real; if positive, then the j-th and (j+1)-st eigenvalues are a complex conjugate pair, with ALPHAI(j+1) negative.

Note: the quotients $\text{ALPHAR}(j)/\text{BETA}(j)$ and $\text{ALPHAI}(j)/\text{BETA}(j)$ may easily over- or underflow, and BETA(j) may even be zero. Thus, the user should avoid naively computing the ratio. However, ALPHAR and ALPHAI will be always less than and usually comparable with norm(A) in magnitude, and BETA always less than and usually comparable with norm(B).

ALPHAI (output)
DOUBLE PRECISION array, dimension(N) See the description for ALPHAR.

BETA (output)

DOUBLE PRECISION array, dimension(N) See the description for ALPHAR.

VSL (input)

DOUBLE PRECISION array, dimension(LDVSL,N) If JOBVSL = 'V', VSL will contain the left Schur vectors. Not referenced if JOBVSL = 'N'.

LDVSL (input)

The leading dimension of the matrix VSL. LDVSL ≥ 1 , and if JOBVSL = 'V', LDVSL $\geq N$.

VSR (input)

DOUBLE PRECISION array, dimension(LDVSR,N) If JOBVSR = 'V', VSR will contain the right Schur vectors. Not referenced if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR ≥ 1 , and if JOBVSR = 'V', LDVSR $\geq N$.

RCONDE (output)

If SENSE = 'E' or 'B', RCONDE(1) and RCONDE(2) contain the reciprocal condition numbers for the average of the selected eigenvalues. Not referenced if SENSE = 'N' or 'V'.

RCONDV (output)

If SENSE = 'V' or 'B', RCONDV(1) and RCONDV(2) contain the reciprocal condition numbers for the selected deflating subspaces. Not referenced if SENSE = 'N' or 'E'.

WORK (workspace)

DOUBLE PRECISION array, dimension(LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK $\geq 8*(N+1)+16$. If SENSE = 'E', 'V', or 'B', LWORK $\geq \text{MAX}(8*(N+1)+16, 2*SDIM*(N-SDIM))$.

IWORK (workspace)

INTEGER array, dimension(LIWORK) Not referenced if SENSE = 'N'.

LIWORK (input)

The dimension of the array WORK. LIWORK $\geq N+6$.

BWORK (workspace)

LOGICAL array, dimension(N) Not referenced if SORT = 'N'.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for j=INFO+1,...,N.
> N: =N+1: other than QZ iteration failed in SHGEQZ

=N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Generalized Schur form no longer satisfy DELCTG=.TRUE. This could also be caused due to scaling. =N+3: reordering failed in STGSEN.

Further details =====

An approximate (asymptotic) bound on the average absolute error of the selected eigenvalues is

$EPS * \text{norm}((A, B)) / RCONDE(1).$

An approximate (asymptotic) bound on the maximum angular error in the computed deflating subspaces is

$EPS * \text{norm}((A, B)) / RCONDV(2).$

See LAPACK User's Guide, section 4.11 for more information.

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NAME

dggev - compute for a pair of N-by-N real nonsymmetric matrices (A,B)

SYNOPSIS

```
SUBROUTINE DGGEV(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,  
                BETA, VL, LDVL, VR, LDVR, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
INTEGER N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),  
BETA(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

```
SUBROUTINE DGGEV_64(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,  
                  BETA, VL, LDVL, VR, LDVR, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),  
BETA(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGEV(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHAR,  
              ALPHAI, BETA, VL, [LDVL], VR, [LDVR], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
INTEGER :: N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK  
REAL(8), DIMENSION(:, :) :: A, B, VL, VR
```

```
SUBROUTINE GGEV_64(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHAR,  
                  ALPHAI, BETA, VL, [LDVL], VR, [LDVR], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK  
REAL(8), DIMENSION(:, :) :: A, B, VL, VR
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dggev(char jobvl, char jobvr, int n, double *a, int
    lda, double *b, int ldb, double *alphan, double
    *alphai, double *beta, double *vl, int ldvl, dou-
    ble *vr, int ldvr, int *info);
void dggev_64(char jobvl, char jobvr, long n, double *a,
    long lda, double *b, long ldb, double *alphan,
    double *alphai, double *beta, double *vl, long
    ldvl, double *vr, long ldvr, long *info);

```

PURPOSE

dggev computes for a pair of N-by-N real nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors.

A generalized eigenvalue for a pair of matrices (A,B) is a scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β) , as there is a reasonable interpretation for $\beta=0$, and even for both being zero.

The right eigenvector $v(j)$ corresponding to the eigenvalue $\lambda(j)$ of (A,B) satisfies

$$A * v(j) = \lambda(j) * B * v(j).$$

The left eigenvector $u(j)$ corresponding to the eigenvalue $\lambda(j)$ of (A,B) satisfies

$$u(j)**H * A = \lambda(j) * u(j)**H * B .$$

where $u(j)**H$ is the conjugate-transpose of $u(j)$.

ARGUMENTS

JOBVL (input)
 = 'N': do not compute the left generalized eigen-
 vectors;
 = 'V': compute the left generalized eigenvectors.

JOBVR (input)
 = 'N': do not compute the right generalized
 eigenvectors;
 = 'V': compute the right generalized eigenvec-
 tors.

N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)
 On entry, the matrix A in the pair (A,B). On
 exit, A has been overwritten.

LDA (input)
 The leading dimension of A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the matrix B in the pair (A,B). On exit, B has been overwritten.

LDB (input)

The leading dimension of B. $LDB \geq \max(1,N)$.

ALPHAR (output)

On exit, $(ALPHAR(j) + ALPHAI(j)*i)/BETA(j)$, $j=1,\dots,N$, will be the generalized eigenvalues. If $ALPHAI(j)$ is zero, then the j-th eigenvalue is real; if positive, then the j-th and (j+1)-st eigenvalues are a complex conjugate pair, with $ALPHAI(j+1)$ negative.

Note: the quotients $ALPHAR(j)/BETA(j)$ and $ALPHAI(j)/BETA(j)$ may easily over- or underflow, and $BETA(j)$ may even be zero. Thus, the user should avoid naively computing the ratio α/β . However, $ALPHAR$ and $ALPHAI$ will be always less than and usually comparable with $\text{norm}(A)$ in magnitude, and $BETA$ always less than and usually comparable with $\text{norm}(B)$.

ALPHAI (output)

See the description for $ALPHAR$.

BETA (output)

See the description for $ALPHAR$.

VL (input)

If $JOBVL = 'V'$, the left eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. If the j-th eigenvalue is real, then $u(j) = VL(:,j)$, the j-th column of VL. If the j-th and (j+1)-th eigenvalues form a complex conjugate pair, then $u(j) = VL(:,j) + i*VL(:,j+1)$ and $u(j+1) = VL(:,j) - i*VL(:,j+1)$. Each eigenvector will be scaled so the largest component have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if $JOBVL = 'N'$.

LDVL (input)

The leading dimension of the matrix VL. $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (input)

If $JOBVR = 'V'$, the right eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. If the j-th eigenvalue is real, then $v(j) = VR(:,j)$, the j-th column of VR. If the j-th and (j+1)-th eigenvalues form a complex conjugate pair, then $v(j) = VR(:,j) + i*VR(:,j+1)$ and $v(j+1) = VR(:,j) - i*VR(:,j+1)$. Each eigenvector will be scaled so the largest component have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if $JOBVR = 'N'$.

LDVR (input)

The leading dimension of the matrix VR. LDVR \geq 1,
and if JOBVR = 'V', LDVR \geq N.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal
LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq
 $\max(1, 8*N)$. For good performance, LWORK must gen-
erally be larger.

If LWORK = -1, then a workspace query is assumed;
the routine only calculates the optimal size of
the WORK array, returns this value as the first
entry of the WORK array, and no error message
related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value.

= 1,...,N: The QZ iteration failed. No eigenvec-
tors have been calculated, but ALPHAR(j),
ALPHAI(j), and BETA(j) should be correct for
 $j = \text{INFO} + 1, \dots, N$. > N: =N+1: other than QZ itera-
tion failed in SHGEQZ.

=N+2: error return from STGEVC.

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NAME

dggev_x - compute for a pair of N-by-N real nonsymmetric matrices (A,B)

SYNOPSIS

```
SUBROUTINE DGGEVX(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, B, LDB,  
    ALPHAR, ALPHAI, BETA, VL, LDVL, VR, LDVR, ILO, IHI, LSCALE,  
    RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, WORK, LWORK, IWORK, BWORK,  
    INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE  
INTEGER N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO  
INTEGER IWORK(*)  
LOGICAL BWORK(*)  
DOUBLE PRECISION ABNRM, BBNRM  
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),  
BETA(*), VL(LDVL,*), VR(LDVR,*), LSCALE(*), RSCALE(*),  
RCONDE(*), RCONDV(*), WORK(*)
```

```
SUBROUTINE DGGEVX_64(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, B, LDB,  
    ALPHAR, ALPHAI, BETA, VL, LDVL, VR, LDVR, ILO, IHI, LSCALE,  
    RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, WORK, LWORK, IWORK, BWORK,  
    INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO  
INTEGER*8 IWORK(*)  
LOGICAL*8 BWORK(*)  
DOUBLE PRECISION ABNRM, BBNRM  
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),  
BETA(*), VL(LDVL,*), VR(LDVR,*), LSCALE(*), RSCALE(*),  
RCONDE(*), RCONDV(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGEVX(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], B, [LDB],  
    ALPHAR, ALPHAI, BETA, VL, [LDVL], VR, [LDVR], ILO, IHI, LSCALE,  
    RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, [WORK], [LWORK], [IWORK],  
    [BWORK], [INFO])
```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
INTEGER :: N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL, DIMENSION(:) :: BWORK
REAL(8) :: ABNRM, BBNRM
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, LSCALE,
RSCALE, RCONDE, RCONDV, WORK
REAL(8), DIMENSION(:,:) :: A, B, VL, VR
SUBROUTINE GGEVX_64(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], B,
[LDB], ALPHAR, ALPHAI, BETA, VL, [LDVL], VR, [LDVR], ILO, IHI,
LSCALE, RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, [WORK], [LWORK],
[IWORK], [BWORK], [INFO])

```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8), DIMENSION(:) :: BWORK
REAL(8) :: ABNRM, BBNRM
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, LSCALE,
RSCALE, RCONDE, RCONDV, WORK
REAL(8), DIMENSION(:,:) :: A, B, VL, VR

```

C INTERFACE

```
#include <sunperf.h>
```

```

void dggev(xchar balanc, char jobvl, char jobvr, char sense,
int n, double *a, int lda, double *b, int ldb,
double *alphar, double *alphai, double *beta, dou-
ble *vl, int ldvl, double *vr, int ldvr, int *ilo,
int *ihi, double *lscale, double *rscale, double
*abnrm, double *bbnrm, double *rconde, double
*rcondv, int *info);

```

```

void dggev_64(char balanc, char jobvl, char jobvr, char
sense, long n, double *a, long lda, double *b,
long ldb, double *alphar, double *alphai, double
*beta, double *vl, long ldvl, double *vr, long
ldvr, long *ilo, long *ihi, double *lscale, double
*rscale, double *abnrm, double *bbnrm, double
*rconde, double *rcondv, long *info);

```

PURPOSE

dggev(x) computes for a pair of N-by-N real nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors.

Optionally also, it computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors (ILO, IHI, LSCALE, RSCALE, ABNRM, and BBNRM), reciprocal condition numbers for the eigenvalues (RCONDE), and reciprocal condition numbers for the right eigenvectors (RCONDV).

A generalized eigenvalue for a pair of matrices (A,B) is a scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β) , as there is a reasonable interpretation for $\beta=0$, and even for both being zero.

The right eigenvector $v(j)$ corresponding to the eigenvalue $\lambda(j)$ of (A,B) satisfies

$$A * v(j) = \lambda(j) * B * v(j) .$$

The left eigenvector $u(j)$ corresponding to the eigenvalue $\lambda(j)$ of (A,B) satisfies

$$u(j)**H * A = \lambda(j) * u(j)**H * B.$$

where $u(j)**H$ is the conjugate-transpose of $u(j)$.

ARGUMENTS

BALANC (input)

Specifies the balance option to be performed. =
'N': do not diagonally scale or permute;
'P': permute only;
'S': scale only;
'B': both permute and scale. Computed reciprocal condition numbers will be for the matrices after permuting and/or balancing. Permuting does not change condition numbers (in exact arithmetic), but balancing does.

JOBVL (input)

= 'N': do not compute the left generalized eigenvectors;
'V': compute the left generalized eigenvectors.

JOBVR (input)

= 'N': do not compute the right generalized eigenvectors;
'V': compute the right generalized eigenvectors.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': none are computed;
'E': computed for eigenvalues only;
'V': computed for eigenvectors only;
'B': computed for eigenvalues and eigenvectors.

N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)

On entry, the matrix A in the pair (A,B) . On exit, A has been overwritten. If $JOBVL='V'$ or $JOBVR='V'$ or both, then A contains the first part of the real Schur form of the "balanced" versions of the input A and B.

LDA (input)

The leading dimension of A. $LDA \geq \max(1,N)$.

B (input/output)

On entry, the matrix B in the pair (A,B) . On exit, B has been overwritten. If $JOBVL='V'$ or $JOBVR='V'$ or both, then B contains the second part

of the real Schur form of the "balanced" versions of the input A and B.

LDB (input)

The leading dimension of B. $LDB \geq \max(1, N)$.

ALPHAR (output)

On exit, $(ALPHAR(j) + ALPHAI(j)*i)/BETA(j)$, $j=1, \dots, N$, will be the generalized eigenvalues. If $ALPHAI(j)$ is zero, then the j -th eigenvalue is real; if positive, then the j -th and $(j+1)$ -st eigenvalues are a complex conjugate pair, with $ALPHAI(j+1)$ negative.

Note: the quotients $ALPHAR(j)/BETA(j)$ and $ALPHAI(j)/BETA(j)$ may easily over- or underflow, and $BETA(j)$ may even be zero. Thus, the user should avoid naively computing the ratio $ALPHA/BETA$. However, $ALPHAR$ and $ALPHAI$ will be always less than and usually comparable with $\text{norm}(A)$ in magnitude, and $BETA$ always less than and usually comparable with $\text{norm}(B)$.

ALPHAI (output)

See the description of $ALPHAR$.

BETA (output)

See the description of $ALPHAR$.

VL (output)

If $JOBVL = 'V'$, the left eigenvectors $u(j)$ are stored one after another in the columns of VL , in the same order as their eigenvalues. If the j -th eigenvalue is real, then $u(j) = VL(:, j)$, the j -th column of VL . If the j -th and $(j+1)$ -th eigenvalues form a complex conjugate pair, then $u(j) = VL(:, j) + i*VL(:, j+1)$ and $u(j+1) = VL(:, j) - i*VL(:, j+1)$. Each eigenvector will be scaled so the largest component have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if $JOBVL = 'N'$.

LDVL (input)

The leading dimension of the matrix VL . $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (output)

If $JOBVR = 'V'$, the right eigenvectors $v(j)$ are stored one after another in the columns of VR , in the same order as their eigenvalues. If the j -th eigenvalue is real, then $v(j) = VR(:, j)$, the j -th column of VR . If the j -th and $(j+1)$ -th eigenvalues form a complex conjugate pair, then $v(j) = VR(:, j) + i*VR(:, j+1)$ and $v(j+1) = VR(:, j) - i*VR(:, j+1)$. Each eigenvector will be scaled so the largest component have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if $JOBVR = 'N'$.

LDVR (input)

The leading dimension of the matrix VR . $LDVR \geq 1$,

and if JOBVR = 'V', LDVR >= N.

ILO (output)

ILO and IHI are integer values such that on exit $A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1, \dots, ILO-1$ or $i = IHI+1, \dots, N$. If BALANC = 'N' or 'S', ILO = 1 and IHI = N.

IHI (output)

See the description of ILO.

LSCALE (output)

Details of the permutations and scaling factors applied to the left side of A and B. If PL(j) is the index of the row interchanged with row j, and DL(j) is the scaling factor applied to row j, then LSCALE(j) = PL(j) for $j = 1, \dots, ILO-1$ = DL(j) for $j = ILO, \dots, IHI$ = PL(j) for $j = IHI+1, \dots, N$. The order in which the interchanges are made is N to IHI+1, then 1 to ILO-1.

RSCALE (output)

Details of the permutations and scaling factors applied to the right side of A and B. If PR(j) is the index of the column interchanged with column j, and DR(j) is the scaling factor applied to column j, then RSCALE(j) = PR(j) for $j = 1, \dots, ILO-1$ = DR(j) for $j = ILO, \dots, IHI$ = PR(j) for $j = IHI+1, \dots, N$. The order in which the interchanges are made is N to IHI+1, then 1 to ILO-1.

ABNRM (output)

The one-norm of the balanced matrix A.

BBNRM (output)

The one-norm of the balanced matrix B.

RCONDE (output)

If SENSE = 'E' or 'B', the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. For a complex conjugate pair of eigenvalues two consecutive elements of RCONDE are set to the same value. Thus RCONDE(j), RCONDV(j), and the j-th columns of VL and VR all correspond to the same eigenpair (but not in general the j-th eigenpair, unless all eigenpairs are selected). If SENSE = 'V', RCONDE is not referenced.

RCONDV (output)

If SENSE = 'V' or 'B', the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. For a complex eigenvector two consecutive elements of RCONDV are set to the same value. If the eigenvalues cannot be reordered to compute RCONDV(j), RCONDV(j) is set to 0; this can only occur when the true value would be very small anyway. If SENSE = 'E', RCONDV is not referenced.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,6*N). If SENSE = 'E', LWORK \geq 12*N. If SENSE = 'V' or 'B', LWORK \geq 2*N*N+12*N+16.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)

dimension(N+6) If SENSE = 'E', IWORK is not referenced.

BWORK (workspace)

dimension(N) If SENSE = 'N', BWORK is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. No eigenvectors have been calculated, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for j=INFO+1,...,N. > N: =N+1: other than QZ iteration failed in SHGEQZ.
=N+2: error return from STGEVC.

FURTHER DETAILS

Balancing a matrix pair (A,B) includes, first, permuting rows and columns to isolate eigenvalues, second, applying diagonal similarity transformation to the rows and columns to make the rows and columns as close in norm as possible. The computed reciprocal condition numbers correspond to the balanced matrix. Permuting rows and columns will not change the condition numbers (in exact arithmetic) but diagonal scaling will. For further explanation of balancing, see section 4.11.1.2 of LAPACK Users' Guide.

An approximate error bound on the chordal distance between the i-th computed generalized eigenvalue w and the corresponding exact eigenvalue lambda is

$$\text{hord}(w, \lambda) \leq \text{EPS} * \text{norm}(\text{ABNRM}, \text{BBNRM}) / \text{RCONDE}(I)$$

An approximate error bound for the angle between the i-th computed eigenvector VL(i) or VR(i) is given by

$$\text{PS} * \text{norm}(\text{ABNRM}, \text{BBNRM}) / \text{DIF}(i).$$

For further explanation of the reciprocal condition numbers RCONDE and RCONDV, see section 4.11 of LAPACK User's Guide.

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NAME

dggglm - solve a general Gauss-Markov linear model (GLM) problem

SYNOPSIS

```
SUBROUTINE DGGGLM(N, M, P, A, LDA, B, LDB, D, X, Y, WORK, LDWORK,
                 INFO)
```

```
INTEGER N, M, P, LDA, LDB, LDWORK, INFO
DOUBLE PRECISION A(LDA,*), B(LDB,*), D(*), X(*), Y(*),
WORK(*)
```

```
SUBROUTINE DGGGLM_64(N, M, P, A, LDA, B, LDB, D, X, Y, WORK, LDWORK,
                    INFO)
```

```
INTEGER*8 N, M, P, LDA, LDB, LDWORK, INFO
DOUBLE PRECISION A(LDA,*), B(LDB,*), D(*), X(*), Y(*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGGLM([N], [M], [P], A, [LDA], B, [LDB], D, X, Y, [WORK],
                 [LDWORK], [INFO])
```

```
INTEGER :: N, M, P, LDA, LDB, LDWORK, INFO
REAL(8), DIMENSION(:) :: D, X, Y, WORK
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GGGLM_64([N], [M], [P], A, [LDA], B, [LDB], D, X, Y, [WORK],
                   [LDWORK], [INFO])
```

```
INTEGER(8) :: N, M, P, LDA, LDB, LDWORK, INFO
REAL(8), DIMENSION(:) :: D, X, Y, WORK
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dggglm(int n, int m, int p, double *a, int lda, double
            *b, int ldb, double *d, double *x, double *y, int
            *info);
```

```
void dggglm_64(long n, long m, long p, double *a, long lda,
              double *b, long ldb, double *d, double *x, double
              *y, long *info);
```

PURPOSE

dggglm solves a general Gauss-Markov linear model (GLM) problem:

$$\underset{x}{\text{minimize}} \quad \|y - Ax\|_2 \quad \text{subject to} \quad d = A^*x + B^*y$$

where A is an N-by-M matrix, B is an N-by-P matrix, and d is a given N-vector. It is assumed that $M \leq N \leq M+P$, and

$$\text{rank}(A) = M \quad \text{and} \quad \text{rank}(A \ B) = N.$$

Under these assumptions, the constrained equation is always consistent, and there is a unique solution x and a minimal 2-norm solution y, which is obtained using a generalized QR factorization of A and B.

In particular, if matrix B is square nonsingular, then the problem GLM is equivalent to the following weighted linear least squares problem

$$\underset{x}{\text{minimize}} \quad \| \text{inv}(B) * (d - A^*x) \|_2$$

where inv(B) denotes the inverse of B.

ARGUMENTS

N (input) The number of rows of the matrices A and B. $N \geq 0$.

M (input) The number of columns of the matrix A. $0 \leq M \leq N$.

P (input) The number of columns of the matrix B. $P \geq N - M$.

A (input/output)
On entry, the N-by-M matrix A. On exit, A is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)
On entry, the N-by-P matrix B. On exit, B is destroyed.

LDB (input)
The leading dimension of the array B. $LDB \geq$

max(1,N).

D (input/output)

On entry, D is the left hand side of the GLM equation. On exit, D is destroyed.

X (output)

On exit, X and Y are the solutions of the GLM problem.

Y (output)

See the description of X.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq max(1,N+M+P). For optimum performance, LDWORK \geq M+min(N,P)+max(N,P)*NB, where NB is an upper bound for the optimal blocksizes for SGEQRF, SGERQF, SORMQR and SORMRQ.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

dgghrd - reduce a pair of real matrices (A,B) to generalized upper Hessenberg form using orthogonal transformations, where A is a general matrix and B is upper triangular

SYNOPSIS

```
SUBROUTINE DGGHRD(COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB, Q, LDQ,  
  Z, LDZ, INFO)
```

```
CHARACTER * 1 COMPQ, COMPZ  
INTEGER N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
```

```
SUBROUTINE DGGHRD_64(COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB, Q,  
  LDQ, Z, LDZ, INFO)
```

```
CHARACTER * 1 COMPQ, COMPZ  
INTEGER*8 N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
```

F95 INTERFACE

```
SUBROUTINE GGHRD(COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB], Q,  
  [LDQ], Z, [LDZ], [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ, COMPZ  
INTEGER :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO  
REAL(8), DIMENSION(:,:) :: A, B, Q, Z
```

```
SUBROUTINE GGHRD_64(COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB],  
  Q, [LDQ], Z, [LDZ], [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ, COMPZ  
INTEGER(8) :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO  
REAL(8), DIMENSION(:,:) :: A, B, Q, Z
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dgghrd(char compq, char compz, int n, int ilo, int ihi,
            double *a, int lda, double *b, int ldb, double *q,
            int ldq, double *z, int ldz, int *info);

void dgghrd_64(char compq, char compz, long n, long ilo,
              long ihi, double *a, long lda, double *b, long
              ldb, double *q, long ldq, double *z, long ldz,
              long *info);

```

PURPOSE

dgghrd reduces a pair of real matrices (A,B) to generalized upper Hessenberg form using orthogonal transformations, where A is a general matrix and B is upper triangular: $Q' * A * Z = H$ and $Q' * B * Z = T$, where H is upper Hessenberg, T is upper triangular, and Q and Z are orthogonal, and ' means transpose.

The orthogonal matrices Q and Z are determined as products of Givens rotations. They may either be formed explicitly, or they may be postmultiplied into input matrices Q1 and Z1, so that

$$1 * A * Z1' = (Q1*Q) * H * (Z1*Z)'$$

ARGUMENTS

COMPQ (input)

= 'N': do not compute Q;
 = 'I': Q is initialized to the unit matrix, and the orthogonal matrix Q is returned; = 'V': Q must contain an orthogonal matrix Q1 on entry, and the product Q1*Q is returned.

COMPZ (input)

= 'N': do not compute Z;
 = 'I': Z is initialized to the unit matrix, and the orthogonal matrix Z is returned; = 'V': Z must contain an orthogonal matrix Z1 on entry, and the product Z1*Z is returned.

N (input) The order of the matrices A and B. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to DGGBAL; otherwise they should be set to 1 and N respectively. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)

See the description of ILO.

A (input/output)

On entry, the N-by-N general matrix to be reduced.
 On exit, the upper triangle and the first

subdiagonal of A are overwritten with the upper Hessenberg matrix H, and the rest is set to zero.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)

On entry, the N-by-N upper triangular matrix B. On exit, the upper triangular matrix $T = Q' B Z$. The elements below the diagonal are set to zero.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

Q (input/output)

If COMPQ='N': Q is not referenced.
If COMPQ='I': on entry, Q need not be set, and on exit it contains the orthogonal matrix Q, where Q' is the product of the Givens transformations which are applied to A and B on the left. If COMPQ='V': on entry, Q must contain an orthogonal matrix Q1, and on exit this is overwritten by Q1*Q.

LDQ (input)

The leading dimension of the array Q. LDQ \geq N if COMPQ='V' or 'I'; LDQ \geq 1 otherwise.

Z (input/output)

If COMPZ='N': Z is not referenced.
If COMPZ='I': on entry, Z need not be set, and on exit it contains the orthogonal matrix Z, which is the product of the Givens transformations which are applied to A and B on the right. If COMPZ='V': on entry, Z must contain an orthogonal matrix Z1, and on exit this is overwritten by Z1*Z.

LDZ (input)

The leading dimension of the array Z. LDZ \geq N if COMPZ='V' or 'I'; LDZ \geq 1 otherwise.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

This routine reduces A to Hessenberg and B to triangular form by an unblocked reduction, as described in *Matrix Computations*, by Golub and Van Loan (Johns Hopkins Press.)

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NAME

dgglse - solve the linear equality-constrained least squares (LSE) problem

SYNOPSIS

```
SUBROUTINE DGGLSE(M, N, P, A, LDA, B, LDB, C, D, X, WORK, LDWORK,  
INFO)
```

```
INTEGER M, N, P, LDA, LDB, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(*), D(*), X(*),  
WORK(*)
```

```
SUBROUTINE DGGLSE_64(M, N, P, A, LDA, B, LDB, C, D, X, WORK, LDWORK,  
INFO)
```

```
INTEGER*8 M, N, P, LDA, LDB, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(*), D(*), X(*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGLSE([M], [N], [P], A, [LDA], B, [LDB], C, D, X, [WORK],  
[LDWORK], [INFO])
```

```
INTEGER :: M, N, P, LDA, LDB, LDWORK, INFO  
REAL(8), DIMENSION(:) :: C, D, X, WORK  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GGLSE_64([M], [N], [P], A, [LDA], B, [LDB], C, D, X, [WORK],  
[LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, P, LDA, LDB, LDWORK, INFO  
REAL(8), DIMENSION(:) :: C, D, X, WORK  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgglse(int m, int n, int p, double *a, int lda, double  
*b, int ldb, double *c, double *d, double *x, int  
*info);
```

```
void dgglse_64(long m, long n, long p, double *a, long lda,
              double *b, long ldb, double *c, double *d, double
              *x, long *info);
```

PURPOSE

dgglse solves the linear equality-constrained least squares (LSE) problem:

$$\text{minimize } \| c - A*x \|_2 \quad \text{subject to } B*x = d$$

where A is an M-by-N matrix, B is a P-by-N matrix, c is a given M-vector, and d is a given P-vector. It is assumed that
 $P \leq N \leq M+P$, and

$$\text{rank}(B) = P \text{ and } \text{rank} \begin{pmatrix} A \\ B \end{pmatrix} = N.$$

These conditions ensure that the LSE problem has a unique solution, which is obtained using a GRQ factorization of the matrices B and A.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

P (input) The number of rows of the matrix B. $0 \leq P \leq N \leq M+P$.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A is destroyed.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
 On entry, the P-by-N matrix B. On exit, B is destroyed.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, P)$.

C (input/output)
 On entry, C contains the right hand side vector for the least squares part of the LSE problem. On exit, the residual sum of squares for the solution is given by the sum of squares of elements N-P+1 to M of vector C.

D (input/output)

On entry, D contains the right hand side vector for the constrained equation. On exit, D is destroyed.

X (output)

On exit, X is the solution of the LSE problem.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq $\max(1, M+N+P)$. For optimum performance LDWORK \geq $P + \min(M, N) + \max(M, N) * NB$, where NB is an upper bound for the optimal blocksizes for SGEQRF, SGERQF, SORMQR and SORMRQ.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

dggqrf - compute a generalized QR factorization of an N-by-M matrix A and an N-by-P matrix B.

SYNOPSIS

```
SUBROUTINE DGGQRF(N, M, P, A, LDA, TAUA, B, LDB, TAUB, WORK, LWORK,
  INFO)
```

```
INTEGER N, M, P, LDA, LDB, LWORK, INFO
DOUBLE PRECISION A(LDA,*), TAUA(*), B(LDB,*), TAUB(*),
WORK(*)
```

```
SUBROUTINE DGGQRF_64(N, M, P, A, LDA, TAUA, B, LDB, TAUB, WORK,
  LWORK, INFO)
```

```
INTEGER*8 N, M, P, LDA, LDB, LWORK, INFO
DOUBLE PRECISION A(LDA,*), TAUA(*), B(LDB,*), TAUB(*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGQRF([N], [M], [P], A, [LDA], TAUA, B, [LDB], TAUB, [WORK],
  [LWORK], [INFO])
```

```
INTEGER :: N, M, P, LDA, LDB, LWORK, INFO
REAL(8), DIMENSION(:) :: TAUA, TAUB, WORK
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE GGQRF_64([N], [M], [P], A, [LDA], TAUA, B, [LDB], TAUB,
  [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: N, M, P, LDA, LDB, LWORK, INFO
REAL(8), DIMENSION(:) :: TAUA, TAUB, WORK
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dggqrf(int n, int m, int p, double *a, int lda, double
```


elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

TAUA (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Q (see Further Details).

B (input/output)

On entry, the N-by-P matrix B. On exit, if $N \leq P$, the upper triangle of the subarray B(1:N,P-N+1:P) contains the N-by-N upper triangular matrix T; if $N > P$, the elements on and above the (N-P)-th subdiagonal contain the N-by-P upper trapezoidal matrix T; the remaining elements, with the array TAUB, represent the orthogonal matrix Z as a product of elementary reflectors (see Further Details).

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

TAUB (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Z (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,N,M,P). For optimum performance LWORK \geq max(N,M,P)*max(NB1,NB2,NB3), where NB1 is the optimal blocksize for the QR factorization of an N-by-M matrix, NB2 is the optimal blocksize for the RQ factorization of an N-by-P matrix, and NB3 is the optimal blocksize for a call of SORMQR.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(1) H(2) \dots H(k)$, where $k = \min(n,m)$.

Each $H(i)$ has the form

$$H(i) = I - \text{taua} * v * v'$$

where taua is a real scalar, and v is a real vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:n)$ is stored on exit in $A(i+1:n,i)$, and taua in $\text{TAUA}(i)$.

To form Q explicitly, use LAPACK subroutine `SORGQR`.

To use Q to update another matrix, use LAPACK subroutine `SORMQR`.

The matrix Z is represented as a product of elementary reflectors

$Z = H(1) H(2) \dots H(k)$, where $k = \min(n,p)$.

Each $H(i)$ has the form

$$H(i) = I - \text{taub} * v * v'$$

where taub is a real scalar, and v is a real vector with $v(p-k+i+1:p) = 0$ and $v(p-k+i) = 1$; $v(1:p-k+i-1)$ is stored on exit in $B(n-k+i,1:p-k+i-1)$, and taub in $\text{TAUB}(i)$.

To form Z explicitly, use LAPACK subroutine `SORGRQ`.

To use Z to update another matrix, use LAPACK subroutine `SORMRQ`.

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NAME

dggrqf - compute a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B

SYNOPSIS

```
SUBROUTINE DGGRQF(M, P, N, A, LDA, TAUA, B, LDB, TAUB, WORK, LWORK,
                 INFO)
```

```
INTEGER M, P, N, LDA, LDB, LWORK, INFO
DOUBLE PRECISION A(LDA,*), TAUA(*), B(LDB,*), TAUB(*),
WORK(*)
```

```
SUBROUTINE DGGRQF_64(M, P, N, A, LDA, TAUA, B, LDB, TAUB, WORK,
                    LWORK, INFO)
```

```
INTEGER*8 M, P, N, LDA, LDB, LWORK, INFO
DOUBLE PRECISION A(LDA,*), TAUA(*), B(LDB,*), TAUB(*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGRQF([M], [P], [N], A, [LDA], TAUA, B, [LDB], TAUB, [WORK],
                [LWORK], [INFO])
```

```
INTEGER :: M, P, N, LDA, LDB, LWORK, INFO
REAL(8), DIMENSION(:) :: TAUA, TAUB, WORK
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE GGRQF_64([M], [P], [N], A, [LDA], TAUA, B, [LDB], TAUB,
                   [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: M, P, N, LDA, LDB, LWORK, INFO
REAL(8), DIMENSION(:) :: TAUA, TAUB, WORK
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dggrqf(int m, int p, int n, double *a, int lda, double
```

```

        *taua, double *b, int ldb, double *taub, int
        *info);

void dggrqf_64(long m, long p, long n, double *a, long lda,
        double *taua, double *b, long ldb, double *taub,
        long *info);

```

PURPOSE

dggrqf computes a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B:

$$A = R*Q, \quad B = Z*T*Q,$$

where Q is an N-by-N orthogonal matrix, Z is a P-by-P orthogonal matrix, and R and T assume one of the forms:

$$\text{if } M \leq N, \quad R = \begin{pmatrix} 0 & R_{12} \\ & M \end{pmatrix} \begin{matrix} M \\ M-N \end{matrix}, \quad \text{or if } M > N, \quad R = \begin{pmatrix} R_{11} \\ & (R_{21}) \end{pmatrix} \begin{matrix} M \\ N \end{matrix}$$

where R12 or R21 is upper triangular, and

$$\text{if } P \geq N, \quad T = \begin{pmatrix} T_{11} \\ & 0 \end{pmatrix} \begin{matrix} N \\ P-N \end{matrix}, \quad \text{or if } P < N, \quad T = \begin{pmatrix} T_{11} & T_{12} \\ & P & N-P \end{pmatrix} \begin{matrix} N \\ P \\ N-P \end{matrix}$$

where T11 is upper triangular.

In particular, if B is square and nonsingular, the GRQ factorization of A and B implicitly gives the RQ factorization of $A*inv(B)$:

$$A*inv(B) = (R*inv(T))*Z'$$

where $inv(B)$ denotes the inverse of the matrix B, and Z' denotes the transpose of the matrix Z.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $M \leq N$, the upper triangle of the subarray A(1:M,N-M+1:N) contains the M-by-M upper triangular matrix R; if $M > N$, the elements on and above the (M-N)-th subdiagonal contain the M-by-N upper trapezoidal matrix R; the remaining elements, with

the array TAUA, represent the orthogonal matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. LDA \geq max(1,M).

TAUA (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Q (see Further Details).

B (input/output)

On entry, the P-by-N matrix B. On exit, the elements on and above the diagonal of the array contain the min(P,N)-by-N upper trapezoidal matrix T (T is upper triangular if P \geq N); the elements below the diagonal, with the array TAUB, represent the orthogonal matrix Z as a product of elementary reflectors (see Further Details).

LDB (input)

The leading dimension of the array B. LDB \geq max(1,P).

TAUB (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Z (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,N,M,P). For optimum performance LWORK \geq max(N,M,P)*max(NB1,NB2,NB3), where NB1 is the optimal blocksize for the RQ factorization of an M-by-N matrix, NB2 is the optimal blocksize for the QR factorization of a P-by-N matrix, and NB3 is the optimal blocksize for a call of SORMRQ.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(1) H(2) \dots H(k)$, where $k = \min(m,n)$.

Each $H(i)$ has the form

$$H(i) = I - \text{taua} * v * v'$$

where taua is a real scalar, and v is a real vector with $v(n-k+i+1:n) = 0$ and $v(n-k+i) = 1$; $v(1:n-k+i-1)$ is stored on exit in $A(m-k+i,1:n-k+i-1)$, and taua in $\text{TAUA}(i)$.

To form Q explicitly, use LAPACK subroutine SORGRQ .

To use Q to update another matrix, use LAPACK subroutine SORMRQ .

The matrix Z is represented as a product of elementary reflectors

$Z = H(1) H(2) \dots H(k)$, where $k = \min(p,n)$.

Each $H(i)$ has the form

$$H(i) = I - \text{taub} * v * v'$$

where taub is a real scalar, and v is a real vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:p)$ is stored on exit in $B(i+1:p,i)$, and taub in $\text{TAUB}(i)$.

To form Z explicitly, use LAPACK subroutine SORGQR .

To use Z to update another matrix, use LAPACK subroutine SORMQR .

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NAME

dggsvd - compute the generalized singular value decomposition (GSVD) of an M-by-N real matrix A and P-by-N real matrix B

SYNOPSIS

```
SUBROUTINE DGGSD(JOBU, JOBV, JOBQ, M, N, P, K, L, A, LDA, B, LDB,  
                ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, IWORK3, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ  
INTEGER M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER IWORK3(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),  
U(LDU,*), V(LDV,*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE DGGSD_64(JOBU, JOBV, JOBQ, M, N, P, K, L, A, LDA, B, LDB,  
                  ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, IWORK3, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ  
INTEGER*8 M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER*8 IWORK3(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),  
U(LDU,*), V(LDV,*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGSVD(JOBU, JOBV, JOBQ, [M], [N], [P], K, L, A, [LDA], B,  
                [LDB], ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK], IWORK3,  
                [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ  
INTEGER :: M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER, DIMENSION(:) :: IWORK3  
REAL(8), DIMENSION(:) :: ALPHA, BETA, WORK  
REAL(8), DIMENSION(:, :) :: A, B, U, V, Q
```

```
SUBROUTINE GGSVD_64(JOBU, JOBV, JOBQ, [M], [N], [P], K, L, A, [LDA],  
                  B, [LDB], ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK],  
                  IWORK3, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
```

```

INTEGER(8) :: M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO
INTEGER(8), DIMENSION(:) :: IWORK3
REAL(8), DIMENSION(:) :: ALPHA, BETA, WORK
REAL(8), DIMENSION(:, :) :: A, B, U, V, Q

```

C INTERFACE

```

#include <sunperf.h>
void dggsvd(char jobu, char jobv, char jobq, int m, int n,
            int p, int *k, int *l, double *a, int lda, double
            *b, int ldb, double *alpha, double *beta, double
            *u, int ldu, double *v, int ldv, double *q, int
            ldq, int *iwork3, int *info);

void dggsvd_64(char jobu, char jobv, char jobq, long m, long
               n, long p, long *k, long *l, double *a, long lda,
               double *b, long ldb, double *alpha, double *beta,
               double *u, long ldu, double *v, long ldv, double
               *q, long ldq, long *iwork3, long *info);

```

PURPOSE

dggsvd computes the generalized singular value decomposition (GSVD) of an M-by-N real matrix A and P-by-N real matrix B:

$$U^*A*Q = D1*(\begin{matrix} 0 & R \end{matrix}), \quad V^*B*Q = D2*(\begin{matrix} 0 & R \end{matrix})$$

where U, V and Q are orthogonal matrices, and Z' is the transpose of Z. Let K+L = the effective numerical rank of the matrix (A',B')', then R is a K+L-by-K+L nonsingular upper triangular matrix, D1 and D2 are M-by-(K+L) and P-by-(K+L) "diagonal" matrices and of the following structures, respectively:

If M-K-L >= 0,

$$D1 = \begin{matrix} & & K & L \\ & & \begin{matrix} \text{I} & 0 \end{matrix} \\ & & \begin{matrix} L & 0 \end{matrix} \\ \begin{matrix} M-K-L & 0 & 0 \end{matrix} \end{matrix}$$

$$D2 = \begin{matrix} & & K & L \\ & & \begin{matrix} L & 0 \end{matrix} \\ \begin{matrix} P-L & 0 & 0 \end{matrix} \end{matrix}$$

$$\begin{matrix} \begin{matrix} 0 & R \end{matrix} \end{matrix} = \begin{matrix} & & N-K-L & K & L \\ & & \begin{matrix} 0 & R11 & R12 \end{matrix} \\ & & \begin{matrix} L & 0 & 0 \end{matrix} \\ & & \begin{matrix} 0 & R22 \end{matrix} \end{matrix}$$

where

$$\begin{aligned}
C &= \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(K+L)), \\
S &= \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(K+L)), \\
C^{**2} + S^{**2} &= I.
\end{aligned}$$

R is stored in A(1:K+L,N-K-L+1:N) on exit.

If M-K-L < 0,

$$\begin{aligned}
 D1 &= \begin{matrix} & & K & M-K & K+L-M \\ & K & (I & 0 & 0) \\ M-K & (0 & C & 0 &) \end{matrix} \\
 D2 &= \begin{matrix} & & K & M-K & K+L-M \\ M-K & (0 & S & 0 &) \\ K+L-M & (0 & 0 & I &) \\ P-L & (0 & 0 & 0 &) \end{matrix} \\
 (0 R) &= \begin{matrix} & & N-K-L & K & M-K & K+L-M \\ & K & (0 & R11 & R12 & R13) \\ M-K & (0 & 0 & R22 & R23 &) \\ K+L-M & (0 & 0 & 0 & R33 &) \end{matrix}
 \end{aligned}$$

where

$$\begin{aligned}
 C &= \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(M)), \\
 S &= \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(M)), \\
 C^{**2} + S^{**2} &= I.
 \end{aligned}$$

(R11 R12 R13) is stored in A(1:M, N-K-L+1:N), and R33 is stored

$$\begin{aligned}
 &(0 R22 R23) \\
 &\text{in } B(M-K+1:L, N+M-K-L+1:N) \text{ on exit.}
 \end{aligned}$$

The routine computes C, S, R, and optionally the orthogonal transformation matrices U, V and Q.

In particular, if B is an N-by-N nonsingular matrix, then the GSVD of A and B implicitly gives the SVD of A*inv(B):

$$A \cdot \text{inv}(B) = U \cdot (D1 \cdot \text{inv}(D2)) \cdot V'$$

If (A', B')' has orthonormal columns, then the GSVD of A and B is also equal to the CS decomposition of A and B. Furthermore, the GSVD can be used to derive the solution of the eigenvalue problem:

$$A' \cdot A \cdot x = \text{lambda} \cdot B' \cdot B \cdot x.$$

In some literature, the GSVD of A and B is presented in the form

$$U' \cdot A \cdot X = (0 D1), \quad V' \cdot B \cdot X = (0 D2)$$

where U and V are orthogonal and X is nonsingular, D1 and D2 are ``diagonal''. The former GSVD form can be converted to the latter form by taking the nonsingular matrix X as

$$\begin{aligned}
 X &= Q \cdot \begin{pmatrix} I & 0 \\ 0 & \text{inv}(R) \end{pmatrix}
 \end{aligned}$$

ARGUMENTS

JOBV (input)
 = 'U': Orthogonal matrix U is computed;
 = 'N': U is not computed.

JOBV (input)
 = 'V': Orthogonal matrix V is computed;
 = 'N': V is not computed.

JOBQ (input)
 = 'Q': Orthogonal matrix Q is computed;
 = 'N': Q is not computed.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

K (output)
 On exit, K and L specify the dimension of the sub-blocks described in the Purpose section. $K + L =$ effective numerical rank of $(A',B)'$.

L (output)
 See the description of K.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A contains the triangular matrix R, or part of R. See Purpose for details.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1,M)$.

B (input/output)
 On entry, the P-by-N matrix B. On exit, B contains the triangular matrix R if $M-K-L < 0$. See Purpose for details.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1,P)$.

ALPHA (output)
 On exit, ALPHA and BETA contain the generalized singular value pairs of A and B; $ALPHA(1:K) = 1$, $BETA(1:K) = 0$, and if $M-K-L \geq 0$, $ALPHA(K+1:K+L) = C$,
 $BETA(K+1:K+L) = S$, or if $M-K-L < 0$,
 $ALPHA(K+1:M)=C$, $ALPHA(M+1:K+L)=0$
 $BETA(K+1:M) = S$, $BETA(M+1:K+L) = 1$ and
 $ALPHA(K+L+1:N) = 0$
 $BETA(K+L+1:N) = 0$

BETA (output)
 See the description of ALPHA.

U (output)
 If $JOBU = 'U'$, U contains the M-by-M orthogonal matrix U. If $JOBU = 'N'$, U is not referenced.

LDU (input)
 The leading dimension of the array U. $LDU \geq \max(1,M)$ if $JOBU = 'U'$; $LDU \geq 1$ otherwise.

V (output)
 If $JOBV = 'V'$, V contains the P-by-P orthogonal matrix V. If $JOBV = 'N'$, V is not referenced.

LDV (input)
 The leading dimension of the array V. $LDV \geq \max(1,P)$ if $JOBV = 'V'$; $LDV \geq 1$ otherwise.

Q (output)
If JOBQ = 'Q', Q contains the N-by-N orthogonal matrix Q. If JOBQ = 'N', Q is not referenced.

LDQ (input)
The leading dimension of the array Q. LDQ \geq max(1,N) if JOBQ = 'Q'; LDQ \geq 1 otherwise.

WORK (workspace)
dimension (max(3*N,M,P)+N)

IWORK3 (output)
dimension(N) On exit, IWORK3 stores the sorting information. More precisely, the following loop will sort ALPHA for I = K+1, min(M,K+L) swap ALPHA(I) and ALPHA(IWORK3(I)) endfor such that ALPHA(1) \geq ALPHA(2) \geq ... \geq ALPHA(N).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = 1, the Jacobi-type procedure failed to converge. For further details, see subroutine STGSJA.

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NAME

dggsvp - compute orthogonal matrices U, V and Q such that $N-K-L \times K \times L \times U^T \times A \times Q = K \times (\begin{matrix} 0 & A_{12} & A_{13} \end{matrix})$ if $M-K-L \geq 0$

SYNOPSIS

```
SUBROUTINE DGGSPV(JOBU, JOBV, JOBQ, M, P, N, A, LDA, B, LDB, TOLA,
                 TOLB, K, L, U, LDU, V, LDV, Q, LDQ, IWORK, TAU, WORK, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
INTEGER M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER IWORK(*)
DOUBLE PRECISION TOLA, TOLB
DOUBLE PRECISION A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*),
Q(LDQ,*), TAU(*), WORK(*)
```

```
SUBROUTINE DGGSPV_64(JOBU, JOBV, JOBQ, M, P, N, A, LDA, B, LDB, TOLA,
                   TOLB, K, L, U, LDU, V, LDV, Q, LDQ, IWORK, TAU, WORK, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
INTEGER*8 M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER*8 IWORK(*)
DOUBLE PRECISION TOLA, TOLB
DOUBLE PRECISION A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*),
Q(LDQ,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGSVP(JOBU, JOBV, JOBQ, [M], [P], [N], A, [LDA], B, [LDB],
                TOLA, TOLB, K, L, U, [LDU], V, [LDV], Q, [LDQ], [IWORK], [TAU],
                [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
INTEGER :: M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL(8) :: TOLA, TOLB
REAL(8), DIMENSION(:) :: TAU, WORK
REAL(8), DIMENSION(:,:) :: A, B, U, V, Q
```

```
SUBROUTINE GGSVP_64(JOBU, JOBV, JOBQ, [M], [P], [N], A, [LDA], B,
```

```
[LDB], TOLA, TOLB, K, L, U, [LDU], V, [LDV], Q, [LDQ], [IWORK],
[TAU], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
INTEGER(8) :: M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8) :: TOLA, TOLB
REAL(8), DIMENSION(:) :: TAU, WORK
REAL(8), DIMENSION(:, :) :: A, B, U, V, Q
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dggsvp(char jobu, char jobv, char jobq, int m, int p,
            int n, double *a, int lda, double *b, int ldb,
            double tola, double tolb, int *k, int *l, double
            *u, int ldu, double *v, int ldv, double *q, int
            ldq, int *info);
```

```
void dggsvp_64(char jobu, char jobv, char jobq, long m, long
               p, long n, double *a, long lda, double *b, long
               ldb, double tola, double tolb, long *k, long *l,
               double *u, long ldu, double *v, long ldv, double
               *q, long ldq, long *info);
```

PURPOSE

dggsvp computes orthogonal matrices U, V and Q such that

$$\begin{array}{ccc} & L & (\begin{array}{ccc} 0 & 0 & A23 \end{array}) \\ M-K-L & (\begin{array}{ccc} 0 & 0 & 0 \end{array}) & \end{array}$$

$$= \begin{array}{ccc} & N-K-L & K & L \\ & K & (\begin{array}{ccc} 0 & A12 & A13 \end{array}) & \text{if } M-K-L < 0; \\ M-K & (\begin{array}{ccc} 0 & 0 & A23 \end{array}) & \end{array}$$

$$V' * B * Q = \begin{array}{ccc} & N-K-L & K & L \\ P-L & (\begin{array}{ccc} 0 & 0 & B13 \end{array}) \\ & (\begin{array}{ccc} 0 & 0 & 0 \end{array}) & \end{array}$$

where the K-by-K matrix A12 and L-by-L matrix B13 are non-singular upper triangular; A23 is L-by-L upper triangular if M-K-L >= 0, otherwise A23 is (M-K)-by-L upper trapezoidal. K+L = the effective numerical rank of the (M+P)-by-N matrix (A',B')'. Z' denotes the transpose of Z.

This decomposition is the preprocessing step for computing the Generalized Singular Value Decomposition (GSVD), see subroutine DGGSVD.

ARGUMENTS

JOBU (input)
 = 'U': Orthogonal matrix U is computed;
 = 'N': U is not computed.

JOBV (input)
 = 'V': Orthogonal matrix V is computed;

= 'N': V is not computed.
 JOBQ (input)
 = 'Q': Orthogonal matrix Q is computed;
 = 'N': Q is not computed.

M (input) The number of rows of the matrix A. $M \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A contains the triangular (or trapezoidal) matrix described in the Purpose section.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
 On entry, the P-by-N matrix B. On exit, B contains the triangular matrix described in the Purpose section.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, P)$.

TOLA (input)
 TOLA and TOLB are the thresholds to determine the effective numerical rank of matrix B and a sub-block of A. Generally, they are set to $TOLA = \max(M, N) * \text{norm}(A) * \text{MACHEPS}$, $TOLB = \max(P, N) * \text{norm}(B) * \text{MACHEPS}$. The size of TOLA and TOLB may affect the size of backward errors of the decomposition.

TOLB (input)
 See the description of TOLA.

K (output)
 On exit, K and L specify the dimension of the sub-blocks described in Purpose. $K + L =$ effective numerical rank of $(A', B)'$.

L (output)
 See the description of K.

U (input) If $JOB_U = 'U'$, U contains the orthogonal matrix U. If $JOB_U = 'N'$, U is not referenced.

LDU (input)
 The leading dimension of the array U. $LDU \geq \max(1, M)$ if $JOB_U = 'U'$; $LDU \geq 1$ otherwise.

V (input) If $JOB_V = 'V'$, V contains the orthogonal matrix V. If $JOB_V = 'N'$, V is not referenced.

LDV (input)

The leading dimension of the array V. LDV \geq
max(1,P) if JOBV = 'V'; LDV \geq 1 otherwise.

Q (input) If JOBQ = 'Q', Q contains the orthogonal matrix Q.
If JOBQ = 'N', Q is not referenced.

LDQ (input)
The leading dimension of the array Q. LDQ \geq
max(1,N) if JOBQ = 'Q'; LDQ \geq 1 otherwise.

IWORK (workspace)
dimension(N)

TAU (workspace)
dimension(N)

WORK (workspace)
dimension(MAX(3*N,M,P))

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The subroutine uses LAPACK subroutine SGEQPF for the QR factorization with column pivoting to detect the effective numerical rank of the a matrix. It may be replaced by a better rank determination strategy.

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NAME

dgssco - General sparse solver condition number estimate.

SYNOPSIS

```
SUBROUTINE DGSSCO ( COND, HANDLE, IER )
```

```
INTEGER          IER  
DOUBLE PRECISION COND  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

DGSSCO - Condition number estimate.

PARAMETERS

COND - DOUBLE PRECISION

On exit, an estimate of the condition number of the factored matrix. Must be called after the numerical factorization subroutine, [DGSSFA\(\)](#).

HANDLE(150) - DOUBLE PRECISION array

On entry, [HANDLE\(*\)](#) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-700 : Invalid calling sequence - need to call DGSSFA first.

-710 : Condition number estimate not available (not implemented for this HANDLE's matrix type).

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NAME

dgssda - Deallocate working storage for the general sparse solver.

SYNOPSIS

```
SUBROUTINE ZGSSDA ( HANDLE, IER )  
  
INTEGER          IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSDA - Deallocate dynamically allocated working storage.

PARAMETERS

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine.
Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

none

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NAME

dgssfa - General sparse solver numeric factorization.

SYNOPSIS

```
SUBROUTINE DGSSFA ( NEQNS, COLSTR, ROWIND, VALUES, HANDLE, IER )
```

```
INTEGER          NEQNS, COLSTR(*), ROWIND(*), IER  
DOUBLE PRECISION VALUES(*)  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

DGSSFA - Numeric factorization of a sparse matrix.

PARAMETERS

NEQNS - INTEGER
On entry, **NEQNS** specifies the number of equations in coefficient matrix. Unchanged on exit.

COLSTR(*) - INTEGER array
On entry, **COLSTR**(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure. Unchanged on exit.

ROWIND(*) - INTEGER array
On entry, **ROWIND**(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

VALUES(*) - DOUBLE PRECISION array
On entry, **VALUES**(*) is an array of size COLSTR(NEQNS+1)-1, containing the numeric values of the sparse matrix to be factored. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, **HANDLE**(*) is an array containing

information needed by the solver, and must be passed unchanged to each sparse solver subroutine.
Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 300 : Invalid calling sequence - need to call DGSSOR first.
- 301 : Failure to dynamically allocate memory.
- 666 : Internal error.

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NAME

dgssfs - General sparse solver one call interface.

SYNOPSIS

```
SUBROUTINE DGSSFS ( MTXTYP, PIVOT , NEQNS, COLSTR, ROWIND,
                  VALUES, NRHS , RHS , LDRHS , ORDMTHD,
                  OUTUNT, MSGVLV, HANDLE, IER )
```

```
CHARACTER*2      MTXTYP
CHARACTER*1      PIVOT
INTEGER          NEQNS, COLSTR(*), ROWIND(*), NRHS, LDRHS,
                OUTUNT, MSGVLV, IER
CHARACTER*3      ORDMTHD
DOUBLE PRECISION VALUES(*), RHS(*)
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

DGSSFS - General sparse solver one call interface.

PARAMETERS

MTXTYP - CHARACTER*2
On entry, MTXTYP specifies the coefficient matrix type. Specifically, the valid options are:

- 'sp' or 'SP' - symmetric structure, positive-definite values
- 'ss' or 'SS' - symmetric structure, symmetric values
- 'su' or 'SU' - symmetric structure, unsymmetric values
- 'uu' or 'UU' - unsymmetric structure, unsymmetric values

Unchanged on exit.

PIVOT - CHARACTER*1
On entry, pivot specifies whether or not pivoting is used in the course of the numeric factorization. The valid options are:

'n' or 'N' - no pivoting is used
(Pivoting is not supported for this release).

Unchanged on exit.

NEQNS - INTEGER
On entry, NEQNS specifies the number of equations in the coefficient matrix. NEQNS must be at least one.
Unchanged on exit.

COLSTR(*) - INTEGER array
On entry, COLSTR(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure.
Unchanged on exit.

ROWIND(*) - INTEGER array
On entry, ROWIND(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

VALUES(*) - DOUBLE PRECISION array
On entry, VALUES(*) is an array of size COLSTR(NEQNS+1)-1, containing the non-zero numeric values of the sparse matrix to be factored.
Unchanged on exit.

NRHS - INTEGER
On entry, NRHS specifies the number of right hand sides to solve for. Unchanged on exit.

RHS(*) - DOUBLE PRECISION array
On entry, RHS(LDRHS, NRHS) contains the NRHS right hand sides. On exit, it contains the solutions.

LDRHS - INTEGER
On entry, LDRHS specifies the leading dimension of the RHS array. Unchanged on exit.

ORDMTHD - CHARACTER*3
On entry, ORDMTHD specifies the fill-reducing ordering to be used by the sparse solver. Specifically, the valid options are:

 'nat' or 'NAT' - natural ordering (no ordering)
 'mmd' or 'MMD' - multiple minimum degree
 'gnd' or 'GND' - general nested dissection
 'uso' or 'USO' - user specified ordering (see DGSSUO)

Unchanged on exit.

OUTUNT - INTEGER
Output unit. Unchanged on exit.

MSGLVL - INTEGER
Message level.

 0 - no output from solver.
 (No messages supported for this release.)

Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array of containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 101 : Failure to dynamically allocate memory.
- 102 : Invalid matrix type.
- 103 : Invalid pivot option.
- 104 : Number of nonzeros is less than NEQNS.
- 105 : NEQNS < 1
- 106 : Invalid matrix structure.
- 201 : Failure to dynamically allocate memory.
- 301 : Failure to dynamically allocate memory.
- 401 : Failure to dynamically allocate memory.
- 402 : NRHS < 1
- 403 : NEQNS > LDRHS
- 666 : Internal error.

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NAME

dgssin - Initialize the general sparse solver.

SYNOPSIS

```
SUBROUTINE DGSSIN ( MTXTYP, PIVOT, NEQNS, COLSTR, ROWIND, OUTUNT,  
                  MSGLVL, HANDLE, IER )
```

```
CHARACTER*2      MTXTYP  
CHARACTER*1      PIVOT  
INTEGER          NEQNS, COLSTR(*), ROWIND(*), OUTUNT, MSGLVL, IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

DGSSIN - Initialize the sparse solver and input the matrix structure.

PARAMETERS

MTXTYP - CHARACTER*2
On entry, MTXTYP specifies the coefficient matrix type. Specifically, the valid options are:

- 'sp' or 'SP' - symmetric structure, positive-definite values
- 'ss' or 'SS' - symmetric structure, symmetric values
- 'su' or 'SU' - symmetric structure, unsymmetric values
- 'uu' or 'UU' - unsymmetric structure, unsymmetric values

Unchanged on exit.

PIVOT - CHARACTER*1
On entry, PIVOT specifies whether or not pivoting is used in the course of the numeric factorization. The valid options are:

- 'n' or 'N' - no pivoting is used
(Pivoting is not supported for this release).

Unchanged on exit.

NEQNS - INTEGER

On entry, NEQNS specifies the number of equations in the coefficient matrix. NEQNS must be at least one. Unchanged on exit.

COLSTR(*) - INTEGER array

On entry, COLSTR(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure. Unchanged on exit.

ROWIND(*) - INTEGER array

On entry, ROWIND(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, HANDLE(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

OUTUNT - INTEGER

Output unit. Unchanged on exit.

MSGLVL - INTEGER

Message level.

0 - no output from solver.

(No messages supported for this release.)

Unchanged on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-101 : Failure to dynamically allocate memory.

-102 : Invalid matrix type.

-103 : Invalid pivot option.

-104 : Number of nonzeros less than NEQNS.

-105 : NEQNS < 1

-106 : Invalid matrix structure.

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NAME

dgssor - General sparse solver ordering and symbolic factorization.

SYNOPSIS

```
SUBROUTINE DGSSOR ( ORDMTHD, HANDLE, IER )
```

```
CHARACTER*3      ORDMTHD
INTEGER          IER
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

DGSSOR - Orders and symbolically factors a sparse matrix.

PARAMETERS

ORDMTHD - CHARACTER*3

On entry, ORDMTHD specifies the fill-reducing ordering to be used by the sparse solver. Specifically, the valid options are:

'nat' or 'NAT' - natural ordering (no ordering)
'mmd' or 'MMD' - multiple minimum degree
'gnd' or 'GND' - general nested dissection
'uso' or 'USO' - user specified ordering (see DGSSUO)

Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero

integer. Error numbers set by this subroutine:

- 200 : Invalid calling sequence - need to call DGSSIN first.
- 201 : Failure to dynamically allocate memory.
- 666 : Internal error.

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NAME

dgssps - Print general sparse solver statics.

SYNOPSIS

```
SUBROUTINE DGSSPS ( HANDLE, IER )
```

```
INTEGER          IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

DGSSPS - Print solver statistics.

PARAMETERS

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-800 : Invalid calling sequence - need to call DGSSSL first.
-899 : Printed solver statistics not supported this release.

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NAME

dgssrp - Return permutation used by the general sparse solver.

SYNOPSIS

```
SUBROUTINE DGSSRP ( PERM, HANDLE, IER )
```

```
INTEGER          PERM(*), IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

DGSSRP - Returns the permutation used by the solver for the fill-reducing ordering.

PARAMETERS

PERM(NEQNS) - INTEGER array
Undefined on entry. PERM(NEQNS) is the permutation array used by the sparse solver for the fill-reducing ordering. Modified on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-600 : Invalid calling sequence - need to call DGSSOR first.

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NAME

dgsssl - Solve routine for the general sparse solver.

SYNOPSIS

```
SUBROUTINE DGSSSL ( NRHS, RHS, LDRHS, HANDLE, IER )
```

```
INTEGER          NRHS, LDRHS, IER
DOUBLE PRECISION RHS(LDRHS,NRHS)
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

DGSSSL - Triangular solve of a factored sparse matrix.

PARAMETERS

NRHS - INTEGER
On entry, NRHS specifies the number of right hand sides to solve for. Unchanged on exit.

RHS(LDRHS,*) - DOUBLE PRECISION array
On entry, RHS(LDRHS,NRHS) contains the NRHS right hand sides. On exit, it contains the solutions.

LDRHS - INTEGER
On entry, LDRHS specifies the leading dimension of the RHS array. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, **HANDLE(*)** is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-400 : Invalid calling sequence - need to call DGSSFA first.
-401 : Failure to dynamically allocate memory.
-402 : NRHS < 1
-403 : NEQNS > LDRHS

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NAME

dgssuo - User supplied permutation for ordering used in the general sparse solver.

SYNOPSIS

```
SUBROUTINE DGSSUO ( PERM, HANDLE, IER )
```

```
INTEGER          PERM(*), IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

DGSSUO - User supplied permutation for ordering. Must be called after *DGSSIN*() (sparse solver initialization) and before *DGSSOR*() (sparse solver ordering).

PARAMETERS

PERM(NEQNS) - INTEGER array
On entry, PERM(NEQNS) is a permutation array supplied by the user for the fill-reducing ordering. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-500 : Invalid calling sequence - need to call DGSSIN first.

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NAME

dgicon - estimate the reciprocal of the condition number of a real tridiagonal matrix A using the LU factorization as computed by DGTTRF

SYNOPSIS

```
SUBROUTINE DGTCN(NORM, N, LOW, DIAG, UP1, UP2, IPIVOT, ANORM, RCOND,
                WORK, IWORK2, INFO)
```

```
CHARACTER * 1 NORM
INTEGER N, INFO
INTEGER IPIVOT(*), IWORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION LOW(*), DIAG(*), UP1(*), UP2(*), WORK(*)
```

```
SUBROUTINE DGTCN_64(NORM, N, LOW, DIAG, UP1, UP2, IPIVOT, ANORM,
                   RCOND, WORK, IWORK2, INFO)
```

```
CHARACTER * 1 NORM
INTEGER*8 N, INFO
INTEGER*8 IPIVOT(*), IWORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION LOW(*), DIAG(*), UP1(*), UP2(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GTCON(NORM, [N], LOW, DIAG, UP1, UP2, IPIVOT, ANORM,
                RCOND, [WORK], [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM
INTEGER :: N, INFO
INTEGER, DIMENSION(:) :: IPIVOT, IWORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2, WORK
```

```
SUBROUTINE GTCON_64(NORM, [N], LOW, DIAG, UP1, UP2, IPIVOT, ANORM,
                   RCOND, [WORK], [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM
INTEGER(8) :: N, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, IWORK2
```

```
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2, WORK
```

C INTERFACE

```
#include <sunperf.h>
void dgtcon(char norm, int n, double *low, double *diag,
            double *up1, double *up2, int *ipivot, double
            anorm, double *rcond, int *info);

void dgtcon_64(char norm, long n, double *low, double *diag,
              double *up1, double *up2, long *ipivot, double
              anorm, double *rcond, long *info);
```

PURPOSE

dgtcon estimates the reciprocal of the condition number of a real tridiagonal matrix A using the LU factorization as computed by DGTTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

LOW (input)

The (n-1) multipliers that define the matrix L from the LU factorization of A as computed by DGTTRF.

DIAG (input)

The n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UP1 (input)

The (n-1) elements of the first superdiagonal of U.

UP2 (input)

The (n-2) elements of the second superdiagonal of U.

IPIVOT (input)

The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(ANORM * AINVNM)$, where AINVNM is an estimate of the 1-norm of $inv(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

IWORK2 (workspace)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dgthr - Gathers specified elements from y into x.

SYNOPSIS

```
SUBROUTINE DGTHR(NZ, Y, X, INDX)

DOUBLE PRECISION Y(*), X(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE DGTHR_64(NZ, Y, X, INDX)

DOUBLE PRECISION Y(*), X(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE GTHR([NZ], Y, X, INDX)

REAL(8), DIMENSION(:) :: Y, X
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE GTHR_64([NZ], Y, X, INDX)

REAL(8), DIMENSION(:) :: Y, X
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

DGTHR - Gathers the specified elements from a vector y in full storage form into a vector x in compressed form. Only the elements of y whose indices are listed in indx are referenced.

```
do i = 1, n
  x(i) = y(indx(i))
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

Y (input)

Vector in full storage form. Unchanged on exit.

X (output)

Vector in compressed form. Contains elements of y
whose indices are listed in indx on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

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NAME

dgthrz - Gather and zero.

SYNOPSIS

```
SUBROUTINE DGTHRZ(NZ, Y, X, INDX)

DOUBLE PRECISION Y(*), X(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE DGTHRZ_64(NZ, Y, X, INDX)

DOUBLE PRECISION Y(*), X(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE GTHRZ([NZ], Y, X, INDX)

REAL(8), DIMENSION(:) :: Y, X
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE GTHRZ_64([NZ], Y, X, INDX)

REAL(8), DIMENSION(:) :: Y, X
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

DGTHRZ - Gathers the specified elements from a vector y in full storage form into a vector x in compressed form. The gathered elements of y are set to zero. Only the elements of y whose indices are listed in indx are referenced.

```
do i = 1, n
  x(i) = y(indx(i))
  y(indx(i)) = 0
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

Y (input/output)

Vector in full storage form. Gathered elements are
set to zero.

X (output)

Vector in compressed form. Contains elements of y
whose indices are listed in indx on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

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NAME

dgtrfs - improve the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE DGTRFS(TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF, UPF1,
  UPF2, IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
DOUBLE PRECISION LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*),
UPF1(*), UPF2(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),
WORK(*)
```

```
SUBROUTINE DGTRFS_64(TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2,
  INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
DOUBLE PRECISION LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*),
UPF1(*), UPF2(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GTRFS([TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL(8), DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, FERR, BERR, WORK
REAL(8), DIMENSION(:,:) :: B, X
```

```

SUBROUTINE GTRFS_64([TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
    DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
    [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: TRANSA
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL(8), DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, FERR, BERR, WORK
REAL(8), DIMENSION(:,:) :: B, X

```

C INTERFACE

```
#include <sunperf.h>
```

```

void dgtrfs(char transa, int n, int nrhs, double *low, dou-
    ble *diag, double *up, double *lowf, double
    *diagf, double *upf1, double *upf2, int *ipivot,
    double *b, int ldb, double *x, int ldx, double
    *ferr, double *berr, int *info);

```

```

void dgtrfs_64(char transa, long n, long nrhs, double *low,
    double *diag, double *up, double *lowf, double
    *diagf, double *upf1, double *upf2, long *ipivot,
    double *b, long ldb, double *x, long ldx, double
    *ferr, double *berr, long *info);

```

PURPOSE

dgtrfs improves the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input)

The (n-1) subdiagonal elements of A.

DIAG (input)

The diagonal elements of A.

UP (input)
The (n-1) superdiagonal elements of A.

LOWF (input)
The (n-1) multipliers that define the matrix L from the LU factorization of A as computed by DGTTRF.

DIAGF (input)
The n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UPF1 (input)
The (n-1) elements of the first superdiagonal of U.

UPF2 (input)
The (n-2) elements of the second superdiagonal of U.

IPIVOT (input)
The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by DGTTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dgtsv - solve the equation $A \cdot X = B$,

SYNOPSIS

```
SUBROUTINE DGTSV(N, NRHS, LOW, DIAG, UP, B, LDB, INFO)
```

```
INTEGER N, NRHS, LDB, INFO  
DOUBLE PRECISION LOW(*), DIAG(*), UP(*), B(LDB,*)
```

```
SUBROUTINE DGTSV_64(N, NRHS, LOW, DIAG, UP, B, LDB, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO  
DOUBLE PRECISION LOW(*), DIAG(*), UP(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GTSV([N], [NRHS], LOW, DIAG, UP, B, [LDB], [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: LOW, DIAG, UP  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE GTSV_64([N], [NRHS], LOW, DIAG, UP, B, [LDB], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: LOW, DIAG, UP  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgtsv(int n, int nrhs, double *low, double *diag, double *up, double *b, int ldb, int *info);
```

```
void dgtsv_64(long n, long nrhs, double *low, double *diag, double *up, double *b, long ldb, long *info);
```

PURPOSE

dgtsv solves the equation

where A is an n by n tridiagonal matrix, by Gaussian elimination with partial pivoting.

Note that the equation $A^*X = B$ may be solved by interchanging the order of the arguments DU and DL.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input/output)

On entry, LOW must contain the (n-1) sub-diagonal elements of A.

On exit, LOW is overwritten by the (n-2) elements of the second super-diagonal of the upper triangular matrix U from the LU factorization of A, in $LOW(1), \dots, LOW(n-2)$.

DIAG (input/output)

On entry, DIAG must contain the diagonal elements of A.

On exit, DIAG is overwritten by the n diagonal elements of U.

UP (input/output)

On entry, UP must contain the (n-1) super-diagonal elements of A.

On exit, UP is overwritten by the (n-1) elements of the first super-diagonal of U.

B (input/output)

On entry, the N by NRHS matrix of right hand side matrix B. On exit, if $INFO = 0$, the N by NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit

< 0: if $INFO = -i$, the i-th argument had an illegal value

> 0: if $INFO = i$, $U(i,i)$ is exactly zero, and the solution has not been computed. The factorization has not been completed unless $i = N$.

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NAME

dgtsvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$ or $A^{**T} * X = B$,

SYNOPSIS

```
SUBROUTINE DGTSVX(FACT, TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
  WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*),
UPF1(*), UPF2(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),
WORK(*)
```

```
SUBROUTINE DGTSVX_64(FACT, TRANSA, N, NRHS, LOW, DIAG, UP, LOWF,
  DIAGF, UPF1, UPF2, IPIVOT, B, LDB, X, LDX, RCOND, FERR, BERR,
  WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*),
UPF1(*), UPF2(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GTSVX(FACT, [TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
  DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR,
  [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, FERR, BERR, WORK
```

```

REAL(8), DIMENSION(:, :) :: B, X

SUBROUTINE GTSVX_64(FACT, [TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
    DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR,
    [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, TRANSA
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: B, X

```

C INTERFACE

```

#include <sunperf.h>

void dgtsvx(char fact, char transa, int n, int nrhs, double
    *low, double *diag, double *up, double *lowf, dou-
    ble *diagf, double *upf1, double *upf2, int
    *ipivot, double *b, int ldb, double *x, int ldx,
    double *rcond, double *ferr, double *berr, int
    *info);

void dgtsvx_64(char fact, char transa, long n, long nrhs,
    double *low, double *diag, double *up, double
    *lowf, double *diagf, double *upf1, double *upf2,
    long *ipivot, double *b, long ldb, double *x, long
    ldx, double *rcond, double *ferr, double *berr,
    long *info);

```

PURPOSE

dgtsvx uses the LU factorization to compute the solution to a real system of linear equations $A * X = B$ or $A^{*T} * X = B$, where A is a tridiagonal matrix of order N and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'N', the LU decomposition is used to factor the matrix A
 - as $A = L * U$, where L is a product of permutation and unit lower bidiagonal matrices and U is upper triangular with nonzeros in only the main diagonal and first two superdiagonals.
2. If some $U(i,i)=0$, so that U is exactly singular, then the routine
 - returns with INFO = i. Otherwise, the factored form of A is used to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': LOWF, DIAGF, UPF1, UPF2, and IPIVOT contain the factored form of A; LOW, DIAG, UP, LOWF, DIAGF, UPF1, UPF2 and IPIVOT will not be modified. = 'N': The matrix will be copied to LOWF, DIAGF, and UPF1 and factored.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input)

The (n-1) subdiagonal elements of A.

DIAG (input)

The n diagonal elements of A.

UP (input/output)

The (n-1) superdiagonal elements of A.

LOWF (input or output)

If FACT = 'F', then LOWF is an input argument and on entry contains the (n-1) multipliers that define the matrix L from the LU factorization of A as computed by DGTTRF.

If FACT = 'N', then LOWF is an output argument and on exit contains the (n-1) multipliers that define the matrix L from the LU factorization of A.

DIAGF (input or output)

If FACT = 'F', then DIAGF is an input argument and on entry contains the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

If FACT = 'N', then DIAGF is an output argument and on exit contains the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UPF1 (input or output)

If FACT = 'F', then UPF1 is an input argument and on entry contains the (n-1) elements of the first superdiagonal of U.

If FACT = 'N', then UPF1 is an output argument and on exit contains the (n-1) elements of the first superdiagonal of U.

UPF2 (input or output)

If FACT = 'F', then UPF2 is an input argument and on entry contains the (n-2) elements of the second superdiagonal of U.

If FACT = 'N', then UPF2 is an output argument and on exit contains the (n-2) elements of the second superdiagonal of U.

IPIVOT (input/output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the LU factorization of A as computed by DGTTRF.

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the LU factorization of A; row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)

The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for $RCOND$, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, and i is
<= N : $U(i,i)$ is exactly zero. The factorization has not been completed unless $i = N$, but the factor U is exactly singular, so the solution and error bounds could not be computed. $RCOND = 0$ is returned. = $N+1$: U is nonsingular, but $RCOND$ is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of $RCOND$ would suggest.

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NAME

dgtrrf - compute an LU factorization of a real tridiagonal matrix A using elimination with partial pivoting and row interchanges

SYNOPSIS

```
SUBROUTINE DGTRRF(N, LOW, DIAG, UP1, UP2, IPIVOT, INFO)
```

```
INTEGER N, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION LOW(*), DIAG(*), UP1(*), UP2(*)
```

```
SUBROUTINE DGTRRF_64(N, LOW, DIAG, UP1, UP2, IPIVOT, INFO)
```

```
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION LOW(*), DIAG(*), UP1(*), UP2(*)
```

F95 INTERFACE

```
SUBROUTINE GTTRF([N], LOW, DIAG, UP1, UP2, IPIVOT, [INFO])
```

```
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2
```

```
SUBROUTINE GTTRF_64([N], LOW, DIAG, UP1, UP2, IPIVOT, [INFO])
```

```
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dgtrrf(int n, double *low, double *diag, double *up1,  
           double *up2, int *ipivot, int *info);
```

```
void dgtrrf_64(long n, double *low, double *diag, double  
              *up1, double *up2, long *ipivot, long *info);
```

PURPOSE

dgtrrf computes an LU factorization of a real tridiagonal matrix A using elimination with partial pivoting and row interchanges.

The factorization has the form

$$A = L * U$$

where L is a product of permutation and unit lower bidiagonal matrices and U is upper triangular with nonzeros in only the main diagonal and first two superdiagonals.

ARGUMENTS

N (input) The order of the matrix A.

LOW (input/output)

On entry, LOW must contain the (n-1) sub-diagonal elements of A.

On exit, LOW is overwritten by the (n-1) multipliers that define the matrix L from the LU factorization of A.

DIAG (input/output)

On entry, DIAG must contain the diagonal elements of A.

On exit, DIAG is overwritten by the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UP1 (input/output)

On entry, UP1 must contain the (n-1) super-diagonal elements of A.

On exit, UP1 is overwritten by the (n-1) elements of the first super-diagonal of U.

UP2 (output)

On exit, UP2 is overwritten by the (n-2) elements of the second super-diagonal of U.

IPIVOT (output)

The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, U(k,k) is exactly zero. The factorization has been completed, but the factor U

is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

dgtrrs - solve one of the systems of equations $A*X = B$ or $A'*X = B$,

SYNOPSIS

```
SUBROUTINE DGTTRS(TRANSA, N, NRHS, LOW, DIAG, UP1, UP2, IPIVOT, B,  
LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION LOW(*), DIAG(*), UP1(*), UP2(*), B(LDB,*)
```

```
SUBROUTINE DGTTRS_64(TRANSA, N, NRHS, LOW, DIAG, UP1, UP2, IPIVOT, B,  
LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION LOW(*), DIAG(*), UP1(*), UP2(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GTTRS([TRANSA], [N], [NRHS], LOW, DIAG, UP1, UP2, IPIVOT,  
B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE GTTRS_64([TRANSA], [N], [NRHS], LOW, DIAG, UP1, UP2,  
IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>

void dgttrs(char transa, int n, int nrhs, double *low, double
            *diag, double *up1, double *up2, int *ipivot,
            double *b, int ldb, int *info);
void dgttrs_64(char transa, long n, long nrhs, double *low,
               double *diag, double *up1, double *up2, long
               *ipivot, double *b, long ldb, long *info);
```

PURPOSE

dgttrs solves one of the systems of equations
 $A * X = B$ or $A' * X = B$, with a tridiagonal matrix A using
the LU factorization computed by DGTTRF.

ARGUMENTS

TRANSA (input)
Specifies the form of the system of equations. =
'N': $A * X = B$ (No transpose)
= 'T': $A' * X = B$ (Transpose)
= 'C': $A' * X = B$ (Conjugate transpose = Trans-
pose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A.

NRHS (input)
The number of right hand sides, i.e., the number
of columns of the matrix B. NRHS \geq 0.

LOW (input)
The (n-1) multipliers that define the matrix L
from the LU factorization of A.

DIAG (input)
The n diagonal elements of the upper triangular
matrix U from the LU factorization of A.

UP1 (input)
The (n-1) elements of the first super-diagonal of
U.

UP2 (input)
The (n-2) elements of the second super-diagonal of
U.

IPIVOT (input)
The pivot indices; for $1 \leq i \leq n$, row i of the
matrix was interchanged with row IPIVOT(i).
IPIVOT(i) will always be either i or i+1;
IPIVOT(i) = i indicates a row interchange was not
required.

B (input/output)

On entry, the matrix of right hand side vectors B.
On exit, B is overwritten by the solution vectors X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dhgeqz - implement a single-/double-shift version of the QZ method for finding the generalized eigenvalues $w(j) = (\text{ALPHAR}(j) + i \cdot \text{ALPHAI}(j)) / \text{BETAR}(j)$ of the equation $\det(A - w(i) B) = 0$. In addition, the pair A,B may be reduced to generalized Schur form

SYNOPSIS

```
SUBROUTINE DHGEQZ(JOB, COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB,
                 ALPHAR, ALPHAI, BETA, Q, LDQ, Z, LDZ, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ, COMPZ
INTEGER N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), Q(LDQ,*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DHGEQZ_64(JOB, COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB,
                   ALPHAR, ALPHAI, BETA, Q, LDQ, Z, LDZ, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ, COMPZ
INTEGER*8 N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), Q(LDQ,*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE HGEQZ(JOB, COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB],
                ALPHAR, ALPHAI, BETA, Q, [LDQ], Z, [LDZ], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ, COMPZ
INTEGER :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL(8), DIMENSION(:, :) :: A, B, Q, Z
```

```
SUBROUTINE HGEQZ_64(JOB, COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B,
                   [LDB], ALPHAR, ALPHAI, BETA, Q, [LDQ], Z, [LDZ], [WORK], [LWORK],
                   [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ, COMPZ
```

```
INTEGER(8) :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL(8), DIMENSION(:,:) :: A, B, Q, Z
```

C INTERFACE

```
#include <sunperf.h>

void dhgeqz(char job, char compq, char compz, int n, int
            ilo, int ihi, double *a, int lda, double *b, int
            ldb, double *alphar, double *alphai, double *beta,
            double *q, int ldq, double *z, int ldz, int
            *info);

void dhgeqz_64(char job, char compq, char compz, long n,
              long ilo, long ihi, double *a, long lda, double
              *b, long ldb, double *alphar, double *alphai, dou-
              ble *beta, double *q, long ldq, double *z, long
              ldz, long *info);
```

PURPOSE

dhgeqz implements a single-/double-shift version of the QZ method for finding the generalized eigenvalues B is upper triangular, and A is block upper triangular, where the diagonal blocks are either 1-by-1 or 2-by-2, the 2-by-2 blocks having complex generalized eigenvalues (see the description of the argument JOB.)

If JOB='S', then the pair (A,B) is simultaneously reduced to Schur form by applying one orthogonal transformation (usually called Q) on the left and another (usually called Z) on the right. The 2-by-2 upper-triangular diagonal blocks of B corresponding to 2-by-2 blocks of A will be reduced to positive diagonal matrices. (I.e., if A(j+1,j) is non-zero, then B(j+1,j)=B(j,j+1)=0 and B(j,j) and B(j+1,j+1) will be positive.)

If JOB='E', then at each iteration, the same transformations are computed, but they are only applied to those parts of A and B which are needed to compute ALPHAR, ALPHAI, and BETA.

If JOB='S' and COMPQ and COMPZ are 'V' or 'I', then the orthogonal transformations used to reduce (A,B) are accumulated into the arrays Q and Z s.t.:

(in) A(in) Z(in)* = Q(out) A(out) Z(out)*

Ref: C.B. Moler & G.W. Stewart, "An Algorithm for Generalized Matrix Eigenvalue Problems", SIAM J. Numer. Anal., 10(1973), p. 241--256.

ARGUMENTS

JOB (input)
= 'E': compute only ALPHAR, ALPHAI, and BETA. A and B will not necessarily be put into generalized Schur form. = 'S': put A and B into generalized

Schur form, as well as computing ALPHAR, ALPHAI, and BETA.

COMPQ (input)

= 'N': do not modify Q.
= 'V': multiply the array Q on the right by the transpose of the orthogonal transformation that is applied to the left side of A and B to reduce them to Schur form. = 'I': like COMPQ='V', except that Q will be initialized to the identity first.

COMPZ (input)

= 'N': do not modify Z.
= 'V': multiply the array Z on the right by the orthogonal transformation that is applied to the right side of A and B to reduce them to Schur form. = 'I': like COMPZ='V', except that Z will be initialized to the identity first.

N (input) The order of the matrices A, B, Q, and Z. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)

See the description of ILO.

A (input) On entry, the N-by-N upper Hessenberg matrix A. Elements below the subdiagonal must be zero. If JOB='S', then on exit A and B will have been simultaneously reduced to generalized Schur form. If JOB='E', then on exit A will have been destroyed. The diagonal blocks will be correct, but the off-diagonal portion will be meaningless.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input) On entry, the N-by-N upper triangular matrix B. Elements below the diagonal must be zero. 2-by-2 blocks in B corresponding to 2-by-2 blocks in A will be reduced to positive diagonal form. (I.e., if $A(j+1, j)$ is non-zero, then $B(j+1, j)=B(j, j+1)=0$ and $B(j, j)$ and $B(j+1, j+1)$ will be positive.) If JOB='S', then on exit A and B will have been simultaneously reduced to Schur form. If JOB='E', then on exit B will have been destroyed. Elements corresponding to diagonal blocks of A will be correct, but the off-diagonal portion will be meaningless.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

ALPHAR (output)

ALPHAR(1:N) will be set to real parts of the diagonal elements of A that would result from reducing A and B to Schur form and then further reducing

them both to triangular form using unitary transformations s.t. the diagonal of B was non-negative real. Thus, if A(j,j) is in a 1-by-1 block (i.e., A(j+1,j)=A(j,j+1)=0), then ALPHAR(j)=A(j,j). Note that the (real or complex) values (ALPHAR(j) + i*ALPHAI(j))/BETA(j), j=1,...,N, are the generalized eigenvalues of the matrix pencil A - wB.

ALPHAI (output)

ALPHAI(1:N) will be set to imaginary parts of the diagonal elements of A that would result from reducing A and B to Schur form and then further reducing them both to triangular form using unitary transformations s.t. the diagonal of B was non-negative real. Thus, if A(j,j) is in a 1-by-1 block (i.e., A(j+1,j)=A(j,j+1)=0), then ALPHAR(j)=0. Note that the (real or complex) values (ALPHAR(j) + i*ALPHAI(j))/BETA(j), j=1,...,N, are the generalized eigenvalues of the matrix pencil A - wB.

BETA (output)

BETA(1:N) will be set to the (real) diagonal elements of B that would result from reducing A and B to Schur form and then further reducing them both to triangular form using unitary transformations s.t. the diagonal of B was non-negative real. Thus, if A(j,j) is in a 1-by-1 block (i.e., A(j+1,j)=A(j,j+1)=0), then BETA(j)=B(j,j). Note that the (real or complex) values (ALPHAR(j) + i*ALPHAI(j))/BETA(j), j=1,...,N, are the generalized eigenvalues of the matrix pencil A - wB. (Note that BETA(1:N) will always be non-negative, and no BETAI is necessary.)

Q (input/output)

If COMPQ='N', then Q will not be referenced. If COMPQ='V' or 'I', then the transpose of the orthogonal transformations which are applied to A and B on the left will be applied to the array Q on the right.

LDQ (input)

The leading dimension of the array Q. LDQ >= 1. If COMPQ='V' or 'I', then LDQ >= N.

Z (input/output)

If COMPZ='N', then Z will not be referenced. If COMPZ='V' or 'I', then the orthogonal transformations which are applied to A and B on the right will be applied to the array Z on the right.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1. If COMPZ='V' or 'I', then LDZ >= N.

WORK (workspace)

On exit, if INFO >= 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,N).

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
= 1,...,N: the QZ iteration did not converge. (A,B) is not in Schur form, but ALPHAR(i), ALPHAI(i), and BETA(i), $i=INFO+1, \dots, N$ should be correct. = N+1,...,2*N: the shift calculation failed. (A,B) is not in Schur form, but ALPHAR(i), ALPHAI(i), and BETA(i), $i=INFO-N+1, \dots, N$ should be correct. > 2*N: various "impossible" errors.

FURTHER DETAILS

Iteration counters:

JITER -- counts iterations.

IITER -- counts iterations run since ILAST was last changed. This is therefore reset only when a 1-by-1 or

2-by-2 block deflates off the bottom.

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NAME

dhsein - use inverse iteration to find specified right and/or left eigenvectors of a real upper Hessenberg matrix H

SYNOPSIS

```
SUBROUTINE DHSEIN(SIDE, EIGSRC, INITV, SELECT, N, H, LDH, WR, WI, VL,  
                 LDVL, VR, LDVR, MM, M, WORK, IFAILL, IFAILR, INFO)
```

```
CHARACTER * 1 SIDE, EIGSRC, INITV  
INTEGER N, LDH, LDVL, LDVR, MM, M, INFO  
INTEGER IFAILL(*), IFAILR(*)  
LOGICAL SELECT(*)  
DOUBLE PRECISION H(LDH,*), WR(*), WI(*), VL(LDVL,*),  
VR(LDVR,*), WORK(*)
```

```
SUBROUTINE DHSEIN_64(SIDE, EIGSRC, INITV, SELECT, N, H, LDH, WR, WI,  
                   VL, LDVL, VR, LDVR, MM, M, WORK, IFAILL, IFAILR, INFO)
```

```
CHARACTER * 1 SIDE, EIGSRC, INITV  
INTEGER*8 N, LDH, LDVL, LDVR, MM, M, INFO  
INTEGER*8 IFAILL(*), IFAILR(*)  
LOGICAL*8 SELECT(*)  
DOUBLE PRECISION H(LDH,*), WR(*), WI(*), VL(LDVL,*),  
VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE HSEIN(SIDE, EIGSRC, INITV, SELECT, [N], H, [LDH], WR, WI,  
               VL, [LDVL], VR, [LDVR], MM, M, [WORK], IFAILL, IFAILR, [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, EIGSRC, INITV  
INTEGER :: N, LDH, LDVL, LDVR, MM, M, INFO  
INTEGER, DIMENSION(:) :: IFAILL, IFAILR  
LOGICAL, DIMENSION(:) :: SELECT  
REAL(8), DIMENSION(:) :: WR, WI, WORK  
REAL(8), DIMENSION(:,:) :: H, VL, VR
```

```
SUBROUTINE HSEIN_64(SIDE, EIGSRC, INITV, SELECT, [N], H, [LDH], WR,  
                  WI, VL, [LDVL], VR, [LDVR], MM, M, [WORK], IFAILL, IFAILR, [INFO])
```

```

CHARACTER(LEN=1) :: SIDE, EIGSRC, INITV
INTEGER(8) :: N, LDH, LDVL, LDVR, MM, M, INFO
INTEGER(8), DIMENSION(:) :: IFAILL, IFAILR
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: WR, WI, WORK
REAL(8), DIMENSION(:, :) :: H, VL, VR

```

C INTERFACE

```

#include <sunperf.h>

void dhsein(char side, char eigsrc, char initv, int *select,
            int n, double *h, int ldh, double *wr, double *wi,
            double *vl, int ldvl, double *vr, int ldvr, int
            mm, int *m, int *ifaill, int *ifailr, int *info);

void dhsein_64(char side, char eigsrc, char initv, long
               *select, long n, double *h, long ldh, double *wr,
               double *wi, double *vl, long ldvl, double *vr,
               long ldvr, long mm, long *m, long *ifaill, long
               *ifailr, long *info);

```

PURPOSE

dhsein uses inverse iteration to find specified right and/or left eigenvectors of a real upper Hessenberg matrix H.

The right eigenvector x and the left eigenvector y of the matrix H corresponding to an eigenvalue w are defined by:

$$H * x = w * x, \quad y^{**h} * H = w * y^{**h}$$

where y**h denotes the conjugate transpose of the vector y.

ARGUMENTS

SIDE (input)
 = 'R': compute right eigenvectors only;
 = 'L': compute left eigenvectors only;
 = 'B': compute both right and left eigenvectors.

EIGSRC (input)
 Specifies the source of eigenvalues supplied in (WR,WI):
 = 'Q': the eigenvalues were found using DHSEQR;
 thus, if H has zero subdiagonal elements, and so is block-triangular, then the j-th eigenvalue can be assumed to be an eigenvalue of the block containing the j-th row/column. This property allows DHSEIN to perform inverse iteration on just one diagonal block. = 'N': no assumptions are made on the correspondence between eigenvalues and diagonal blocks. In this case, DHSEIN must always perform inverse iteration using the whole matrix H.

INITV (input)
 = 'N': no initial vectors are supplied;

= 'U': user-supplied initial vectors are stored in the arrays VL and/or VR.

SELECT (input/output)

Specifies the eigenvectors to be computed. To select the real eigenvector corresponding to a real eigenvalue $WR(j)$, $SELECT(j)$ must be set to `.TRUE.` To select the complex eigenvector corresponding to a complex eigenvalue $(WR(j),WI(j))$, with complex conjugate $(WR(j+1),WI(j+1))$, either $SELECT(j)$ or $SELECT(j+1)$ or both must be set to

N (input) The order of the matrix H. $N \geq 0$.

H (input) The upper Hessenberg matrix H.

LDH (input)

The leading dimension of the array H. $LDH \geq \max(1,N)$.

WR (input/output)

On entry, the real and imaginary parts of the eigenvalues of H; a complex conjugate pair of eigenvalues must be stored in consecutive elements of WR and WI. On exit, WR may have been altered since close eigenvalues are perturbed slightly in searching for independent eigenvectors.

WI (input)

See the description of WR.

VL (input/output)

On entry, if $INITV = 'U'$ and $SIDE = 'L'$ or $'B'$, VL must contain starting vectors for the inverse iteration for the left eigenvectors; the starting vector for each eigenvector must be in the same column(s) in which the eigenvector will be stored. On exit, if $SIDE = 'L'$ or $'B'$, the left eigenvectors specified by SELECT will be stored consecutively in the columns of VL, in the same order as their eigenvalues. A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the real part and the second the imaginary part. If $SIDE = 'R'$, VL is not referenced.

LDVL (input)

The leading dimension of the array VL. $LDVL \geq \max(1,N)$ if $SIDE = 'L'$ or $'B'$; $LDVL \geq 1$ otherwise.

VR (input/output)

On entry, if $INITV = 'U'$ and $SIDE = 'R'$ or $'B'$, VR must contain starting vectors for the inverse iteration for the right eigenvectors; the starting vector for each eigenvector must be in the same column(s) in which the eigenvector will be stored. On exit, if $SIDE = 'R'$ or $'B'$, the right eigenvectors specified by SELECT will be stored consecutively in the columns of VR, in the same order as

their eigenvalues. A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the real part and the second the imaginary part. If SIDE = 'L', VR is not referenced.

LDVR (input)

The leading dimension of the array VR. LDVR \geq max(1,N) if SIDE = 'R' or 'B'; LDVR \geq 1 otherwise.

MM (input)

The number of columns in the arrays VL and/or VR. MM \geq M.

M (output)

The number of columns in the arrays VL and/or VR required to store the eigenvectors; each selected real eigenvector occupies one column and each selected complex eigenvector occupies two columns.

WORK (workspace)

dimension((N+2)*N)

IFAILL (output)

If SIDE = 'L' or 'B', IFAILL(i) = j > 0 if the left eigenvector in the i-th column of VL (corresponding to the eigenvalue w(j)) failed to converge; IFAILL(i) = 0 if the eigenvector converged satisfactorily. If the i-th and (i+1)th columns of VL hold a complex eigenvector, then IFAILL(i) and IFAILL(i+1) are set to the same value. If SIDE = 'R', IFAILL is not referenced.

IFAILR (output)

If SIDE = 'R' or 'B', IFAILR(i) = j > 0 if the right eigenvector in the i-th column of VR (corresponding to the eigenvalue w(j)) failed to converge; IFAILR(i) = 0 if the eigenvector converged satisfactorily. If the i-th and (i+1)th columns of VR hold a complex eigenvector, then IFAILR(i) and IFAILR(i+1) are set to the same value. If SIDE = 'L', IFAILR is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, i is the number of eigenvectors which failed to converge; see IFAILL and IFAILR for further details.

FURTHER DETAILS

Each eigenvector is normalized so that the element of largest magnitude has magnitude 1; here the magnitude of a complex number (x,y) is taken to be $|x|+|y|$.

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NAME

dhseqr - compute the eigenvalues of a real upper Hessenberg matrix H and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z^{**T}$, where T is an upper quasi-triangular matrix (the Schur form), and Z is the orthogonal matrix of Schur vectors

SYNOPSIS

```
SUBROUTINE DHSEQR(JOB, COMPZ, N, ILO, IHI, H, LDH, WR, WI, Z, LDZ,
                 WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPZ
INTEGER N, ILO, IHI, LDH, LDZ, LWORK, INFO
DOUBLE PRECISION H(LDH,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DHSEQR_64(JOB, COMPZ, N, ILO, IHI, H, LDH, WR, WI, Z, LDZ,
                    WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPZ
INTEGER*8 N, ILO, IHI, LDH, LDZ, LWORK, INFO
DOUBLE PRECISION H(LDH,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE HSEQR(JOB, COMPZ, N, ILO, IHI, H, [LDH], WR, WI, Z, [LDZ],
                [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPZ
INTEGER :: N, ILO, IHI, LDH, LDZ, LWORK, INFO
REAL(8), DIMENSION(:) :: WR, WI, WORK
REAL(8), DIMENSION(:,:) :: H, Z
```

```
SUBROUTINE HSEQR_64(JOB, COMPZ, N, ILO, IHI, H, [LDH], WR, WI, Z,
                   [LDZ], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPZ
INTEGER(8) :: N, ILO, IHI, LDH, LDZ, LWORK, INFO
REAL(8), DIMENSION(:) :: WR, WI, WORK
REAL(8), DIMENSION(:,:) :: H, Z
```

C INTERFACE

```
#include <sunperf.h>

void dhseqr(char job, char compz, int n, int ilo, int ihi,
            double *h, int ldh, double *wr, double *wi, double
            *z, int ldz, int *info);
void dhseqr_64(char job, char compz, long n, long ilo, long
              ihi, double *h, long ldh, double *wr, double *wi,
              double *z, long ldz, long *info);
```

PURPOSE

dhseqr computes the eigenvalues of a real upper Hessenberg matrix H and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z^{*T}$, where T is an upper quasi-triangular matrix (the Schur form), and Z is the orthogonal matrix of Schur vectors.

Optionally Z may be postmultiplied into an input orthogonal matrix Q , so that this routine can give the Schur factorization of a matrix A which has been reduced to the Hessenberg form H by the orthogonal matrix Q : $A = Q^*H^*Q^{*T} = (QZ)^*T^*(QZ)^{*T}$.

ARGUMENTS

JOB (input)

= 'E': compute eigenvalues only;
 = 'S': compute eigenvalues and the Schur form T .

COMPZ (input)

= 'N': no Schur vectors are computed;
 = 'I': Z is initialized to the unit matrix and the matrix Z of Schur vectors of H is returned; =
 'V': Z must contain an orthogonal matrix Q on entry, and the product Q^*Z is returned.

N (input) The order of the matrix H . $N \geq 0$.

ILO (input)

It is assumed that H is already upper triangular in rows and columns $1:ILO-1$ and $IHI+1:N$. ILO and IHI are normally set by a previous call to SGEBAL, and then passed to SGEHRD when the matrix output by SGEBAL is reduced to Hessenberg form. Otherwise ILO and IHI should be set to 1 and N respectively. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)

See the description of ILO.

H (input/output)

On entry, the upper Hessenberg matrix H . On exit, if JOB = 'S', H contains the upper quasi-triangular matrix T from the Schur decomposition (the Schur form); 2-by-2 diagonal blocks (corresponding to complex conjugate pairs of

eigenvalues) are returned in standard form, with $H(i,i) = H(i+1,i+1)$ and $H(i+1,i)*H(i,i+1) < 0$. If `JOB = 'E'`, the contents of `H` are unspecified on exit.

`LDH` (input)

The leading dimension of the array `H`. `LDH` $\geq \max(1,N)$.

`WR` (output)

The real and imaginary parts, respectively, of the computed eigenvalues. If two eigenvalues are computed as a complex conjugate pair, they are stored in consecutive elements of `WR` and `WI`, say the i -th and $(i+1)$ th, with $WI(i) > 0$ and $WI(i+1) < 0$. If `JOB = 'S'`, the eigenvalues are stored in the same order as on the diagonal of the Schur form returned in `H`, with $WR(i) = H(i,i)$ and, if $H(i:i+1,i:i+1)$ is a 2-by-2 diagonal block, $WI(i) = \sqrt{H(i+1,i)*H(i,i+1)}$ and $WI(i+1) = -WI(i)$.

`WI` (output)

See the description of `WR`.

`Z` (input) If `COMPZ = 'N'`: `Z` is not referenced.

If `COMPZ = 'I'`: on entry, `Z` need not be set, and on exit, `Z` contains the orthogonal matrix `Z` of the Schur vectors of `H`. If `COMPZ = 'V'`: on entry `Z` must contain an N -by- N matrix `Q`, which is assumed to be equal to the unit matrix except for the submatrix $Z(ILO:IHI,ILO:IHI)$; on exit `Z` contains $Q*Z$. Normally `Q` is the orthogonal matrix generated by `DORGHR` after the call to `SGEHRD` which formed the Hessenberg matrix `H`.

`LDZ` (input)

The leading dimension of the array `Z`. `LDZ` $\geq \max(1,N)$ if `COMPZ = 'I'` or `'V'`; `LDZ` ≥ 1 otherwise.

`WORK` (workspace)

On exit, if `INFO = 0`, `WORK(1)` returns the optimal `LWORK`.

`LWORK` (input)

The dimension of the array `WORK`. `LWORK` $\geq \max(1,N)$.

If `LWORK = -1`, then a workspace query is assumed; the routine only calculates the optimal size of the `WORK` array, returns this value as the first entry of the `WORK` array, and no error message related to `LWORK` is issued by `XERBLA`.

`INFO` (output)

= 0: successful exit
< 0: if `INFO = -i`, the i -th argument had an illegal value
> 0: if `INFO = i`, `DHSEQR` failed to compute all of the eigenvalues in a total of $30*(IHI-ILO+1)$ iterations; elements $1:i-1$ and $i+1:n$ of `WR` and `WI` contain those eigenvalues which have been suc-

cessfully computed.

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NAME

djadmm - Jagged diagonal matrix-matrix multiply (modified Ellpack)

SYNOPSIS

```
SUBROUTINE DJADMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, PNTR, MAXNZ, IPERM,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5), MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DJADMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, PNTR, MAXNZ, IPERM,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), MAXNZ,  
*               LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ is the number of non-zero elements.

F95 INTERFACE

```
SUBROUTINE JADMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*               PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, K, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE JADMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                   PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, M, K, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM
```

```

DOUBLE PRECISION    ALPHA, BETA
DOUBLE PRECISION, DIMENSION(:) :: VAL
DOUBLE PRECISION, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void djadmm (int transa, int m, int n, int k, double alpha,
int *descra, double *val, int *indx, int *pntr, int maxnz,
int *iperm, double *b, int ldb, double beta, double *c, int
ldb)

void djadmm_64(long transa, long m, long n, long k, double
alpha, long *descra, double *val, long *indx, long *pntr,
long maxnz, long *iperm, double *b, long ldb, double beta,
double *c, long ldc);

```

DESCRIPTION

djadmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the jagged diagonal format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array. DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular

4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
 NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of entries of A.
 VAL can be viewed as a column major ordering of a
 row permutation of the Ellpack representation of A,
 where the Ellpack representation is permuted so that
 the rows are non-increasing in the number of nonzero
 entries. Values added for padding in Ellpack are
 not included in the Jagged-Diagonal format.
 Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
 NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of the column
 indices of the corresponding entries in VAL.
 Unchanged on exit.

PNTR(input) On entry, PNTR is an integer array of length
 MAXNZ+1, where PNTR(I)-PNTR(1)+1 points to
 the location in VAL of the first element
 in the row-permuted Ellpack representation of A.
 Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of
 nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length M
 such that I = IPERM(I'), where row I in the
 original Ellpack representation corresponds
 to row I' in the permuted representation.
 If IPERM(1) = 0, it is assumed by convention that
 IPERM(I) = I. IPERM is used to determine the order
 in which rows of C are updated. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise

the leading k by n part of the array C must contain the matrix C . On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \beta * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

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NAME

djadrp - right permutation of a jagged diagonal matrix

SYNOPSIS

```
SUBROUTINE DJADRP( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,  
*                IPERM, WORK, LWORK )  
INTEGER          TRANSP, M, K, MAXNZ, LWORK  
INTEGER          INDX(*), PNTR(MAXNZ+1), IPERM(K), WORK(LWORK)  
DOUBLE PRECISION VAL(*)
```

```
SUBROUTINE DJADRP_64( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,  
*                   IPERM, WORK, LWORK )  
INTEGER*8        TRANSP, M, K, MAXNZ, LWORK  
INTEGER*8        INDX(*), PNTR(MAXNZ+1), IPERM(K), WORK(LWORK)  
DOUBLE PRECISION VAL(*)
```

F95 INTERFACE

```
SUBROUTINE JADRP( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,  
*              IPERM, [WORK], [LWORK] )  
INTEGER TRANSP, M, K, MAXNZ  
INTEGER, DIMENSION(:) :: INDX, PNTR, IPERM  
DOUBLE PRECISION, DIMENSION(:) :: VAL
```

```
SUBROUTINE JADRP_64( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,  
*                  IPERM, [WORK], [LWORK] )  
INTEGER*8 TRANSP, M, K, MAXNZ  
INTEGER*8, DIMENSION(:) :: INDX, PNTR, IPERM  
DOUBLE PRECISION, DIMENSION(:) :: VAL
```

C INTERFACE

```
#include <sunperf.h>
```

```
void djadrp (int transp, int m, int k, double *val, int  
*indx, int *pntr, int maxnz, int *iperm);
```

```
void djadrp_64 (long transp, long m, long k, double *val,  
long *indx, long *pntr, long maxnz, long *iperm);
```

DESCRIPTION

djadrp performs one of the matrix-matrix operations

$A \leftarrow A P$ or $A \leftarrow A P'$ (' indicates matrix transpose)

where A is an M -by- K sparse matrix represented in the jagged diagonal format, the permutation matrix P is represented by an integer vector $IPERM$, such that $IPERM(I)$ is equal to the position of the only nonzero element in row I of permutation matrix P .
NOTE: In order to get a symmetrically permuted jagged diagonal matrix $P A P'$, one can explicitly permute the columns $P A$ by calling

```
DJADRP(0, M, M, VAL, INDX, PNTR, MAXNZ, IPERM, WORK, LWORK)
```

where parameters VAL , $INDX$, $PNTR$, $MAXNZ$, $IPERM$ are the representation of A in the jagged diagonal format. The operation makes sense if the original matrix A is square.

ARGUMENTS

TRANSP(input) $TRANSP$ indicates how to operate with the permutation matrix:
 0 : operate with matrix
 1 : operate with transpose matrix
 Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A . Unchanged on exit.

K(input) On entry, K specifies the number of columns in the matrix A . Unchanged on exit.

VAL(input/output) On entry, VAL is a scalar array of length $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ consisting of entries of A . VAL can be viewed as a column major ordering of a row permutation of the Ellpack representation of A , where the Ellpack representation is permuted so that the rows are non-increasing in the number of nonzero entries. Values added for padding in Ellpack are not included in the Jagged-Diagonal format. On exit, VAL contains non-zero entries of the output permuted jagged diagonal matrix.

INDX(input/output) On entry, $INDX$ is an integer array of length $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ consisting of the column indices of the corresponding entries in VAL . On exit, $INDX$ is overwritten by the column indices of the output permuted jagged diagonal matrix.

PNTR(input) On entry, $PNTR$ is an integer array of length $MAXNZ+1$, where $PNTR(I)-PNTR(1)+1$ points to the location in VAL of the first element in the row-permuted Ellpack representation of A . Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of
nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length K
such that $I = \text{IPERM}(I')$.
Array IPERM represents a permutation P, such that
IPERM(I) is equal to the position of the only nonzero
element in row I of permutation matrix P.
For example, if

$$P = \begin{pmatrix} | & 0 & 0 & 1 & | \\ | & 1 & 0 & 0 & | \\ | & 0 & 1 & 0 & | \end{pmatrix}$$

then IPERM = (3, 1, 2). Unchanged on exit.

WORK(workspace) Scratch array of length LWORK. LWORK should be at
least K.

LWORK(input) On entry, LWORK specifies the length of the array WORK.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed;
the routine only calculates the optimal size of the
array WORK, returns this value as the first entry of
the WORK array, and no error message related to LWORK
is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of
OPENMP and it is fully compatible with NIST FORTRAN Sparse
Blas but the sources are different. Libsunperf SPARSE BLAS
is free of bugs found in NIST FORTRAN Sparse Blas. Besides
several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS)
Standard", University of Tennessee, Knoxville, Tennessee,
1996:

<http://www.netlib.org/utk/papers/sparse.ps>

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NAME

djadsm - Jagged-diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE DJADSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, PNTR, MAXNZ, IPERM,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, UNITD, DESCRA(5), MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DJADSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, INDX, PNTR, MAXNZ, IPERM,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5), MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ is the number of non-zero elements

F95 INTERFACE

```
SUBROUTINE JADSM(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
*               PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE JADSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
*                   PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, M, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
DOUBLE PRECISION ALPHA, BETA
```

```
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void djadsm (int transa, int m, int n, int unitd, double
*dv, double alpha, int *descra, double *val, int *indx, int
*pntr, int maxnz, int *iperm, double *b, int ldb, double
beta, double *c, int ldc)
void djadsm_64(long transa, long m, long n, long unitd,
double *dv, double alpha, long *descra, double *val, long
*indx, long *pntr, long maxnz, long *iperm, double *b, long
ldb, double beta, double *c, long ldc);
```

DESCRIPTION

djadsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the jagged-diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of entries of A.
VAL can be viewed as a column major ordering of a row permutation of the Ellpack representation of A, where the Ellpack representation is permuted so that the rows are non-increasing in the number of nonzero entries. Values added for padding in Ellpack are not included in the Jagged-Diagonal format.
Unchanged on exit if UNITD is not equal to 4.

INDX(input) On entry, INDX is an integer array of length
NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of the column indices of the corresponding entries in VAL.
Unchanged on exit.

PNTR(input) On entry, PNTR is an integer array of length
MAXNZ+1, where PNTR(I)-PNTR(1)+1 points to the location in VAL of the first element in the row-permuted Ellpack representation of A.
Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of
nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length M
such that I = IPERM(I'), where row I in the original Ellpack representation corresponds to row I' in the permuted representation.
If IPERM(1) = 0, it is assumed by convention that IPERM(I) = I. IPERM is used to determine the order in which rows of C are updated. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B

must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least 2*M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq 2*M*N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:
<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If UNITD =4, the routine scales the rows of the sparse matrix A such that their 2-norms are one. The scaling may

improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = - i where i is the row number which 2-norm is exactly zero.

3. If DESCRA(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the JAD representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the JAD representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But DESCRA(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	alpha*op(L+I)*B+beta*C
3	1	0	alpha*op(L+D)*B+beta*C
3	2	1	alpha*op(U+I)*B+beta*C
3	2	0	alpha*op(U+D)*B+beta*C

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NAME

dlagtf - factorize the matrix $(T-\lambda I)$, where T is an n by n tridiagonal matrix and λ is a scalar, as $T-\lambda I = \text{PLU}$

SYNOPSIS

```
SUBROUTINE DLAGTF(N, A, LAMBDA, B, C, TOL, D, IN, INFO)
```

```
INTEGER N, INFO
INTEGER IN(*)
DOUBLE PRECISION LAMBDA, TOL
DOUBLE PRECISION A(*), B(*), C(*), D(*)
```

```
SUBROUTINE DLAGTF_64(N, A, LAMBDA, B, C, TOL, D, IN, INFO)
```

```
INTEGER*8 N, INFO
INTEGER*8 IN(*)
DOUBLE PRECISION LAMBDA, TOL
DOUBLE PRECISION A(*), B(*), C(*), D(*)
```

F95 INTERFACE

```
SUBROUTINE LAGTF([N], A, LAMBDA, B, C, TOL, D, IN, [INFO])
```

```
INTEGER :: N, INFO
INTEGER, DIMENSION(:) :: IN
REAL(8) :: LAMBDA, TOL
REAL(8), DIMENSION(:) :: A, B, C, D
```

```
SUBROUTINE LAGTF_64([N], A, LAMBDA, B, C, TOL, D, IN, [INFO])
```

```
INTEGER(8) :: N, INFO
INTEGER(8), DIMENSION(:) :: IN
REAL(8) :: LAMBDA, TOL
REAL(8), DIMENSION(:) :: A, B, C, D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dlagtf(int n, double *a, double lambda, double *b, double *c, double tol, double *d, int *in, int
```

```

        *info);

void dlagtf_64(long n, double *a, double lambda, double *b,
              double *c, double tol, double *d, long *in, long
              *info);

```

PURPOSE

dlagtf factorizes the matrix $(T - \lambda I)$, where T is an n by n tridiagonal matrix and λ is a scalar, as where P is a permutation matrix, L is a unit lower tridiagonal matrix with at most one non-zero sub-diagonal elements per column and U is an upper triangular matrix with at most two non-zero super-diagonal elements per column.

The factorization is obtained by Gaussian elimination with partial pivoting and implicit row scaling.

The parameter LAMBDA is included in the routine so that SLAGTF may be used, in conjunction with SLAGTS, to obtain eigenvectors of T by inverse iteration.

ARGUMENTS

N (input) The order of the matrix T .

A (input/output)

On entry, A must contain the diagonal elements of T .

On exit, A is overwritten by the n diagonal elements of the upper triangular matrix U of the factorization of T .

LAMBDA (input)

On entry, the scalar λ .

B (input/output)

On entry, B must contain the $(n-1)$ super-diagonal elements of T .

On exit, B is overwritten by the $(n-1)$ super-diagonal elements of the matrix U of the factorization of T .

C (input/output)

On entry, C must contain the $(n-1)$ sub-diagonal elements of T .

On exit, C is overwritten by the $(n-1)$ sub-diagonal elements of the matrix L of the factorization of T .

TOL (input/output)

On entry, a relative tolerance used to indicate whether or not the matrix $(T - \lambda I)$ is nearly singular. TOL should normally be chosen as approxi-

mately the largest relative error in the elements of T. For example, if the elements of T are correct to about 4 significant figures, then TOL should be set to about $5 \cdot 10^{-4}$. If TOL is supplied as less than eps, where eps is the relative machine precision, then the value eps is used in place of TOL.

D (output)

On exit, D is overwritten by the (n-2) second super-diagonal elements of the matrix U of the factorization of T.

IN (output)

On exit, IN contains details of the permutation matrix P. If an interchange occurred at the kth step of the elimination, then $IN(k) = 1$, otherwise $IN(k) = 0$. The element $IN(n)$ returns the smallest positive integer j such that

$$\text{abs}(u(j,j)) \cdot \text{le. norm}((T - \text{lambda} \cdot I)(j)) \cdot \text{TOL},$$

where $\text{norm}(A(j))$ denotes the sum of the absolute values of the jth row of the matrix A. If no such j exists then $IN(n)$ is returned as zero. If $IN(n)$ is returned as positive, then a diagonal element of U is small, indicating that $(T - \text{lambda} \cdot I)$ is singular or nearly singular,

INFO (output)

= 0 : successful exit

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NAME

dlamrg - will create a permutation list which will merge the elements of A (which is composed of two independently sorted sets) into a single set which is sorted in ascending order

SYNOPSIS

```
SUBROUTINE DLAMRG(N1, N2, A, TRD1, TRD2, INDEX)
```

```
INTEGER N1, N2, TRD1, TRD2  
INTEGER INDEX(*)  
DOUBLE PRECISION A(*)
```

```
SUBROUTINE DLAMRG_64(N1, N2, A, TRD1, TRD2, INDEX)
```

```
INTEGER*8 N1, N2, TRD1, TRD2  
INTEGER*8 INDEX(*)  
DOUBLE PRECISION A(*)
```

F95 INTERFACE

```
SUBROUTINE LAMRG(N1, N2, A, TRD1, TRD2, INDEX)
```

```
INTEGER :: N1, N2, TRD1, TRD2  
INTEGER, DIMENSION(:) :: INDEX  
REAL(8), DIMENSION(:) :: A
```

```
SUBROUTINE LAMRG_64(N1, N2, A, TRD1, TRD2, INDEX)
```

```
INTEGER(8) :: N1, N2, TRD1, TRD2  
INTEGER(8), DIMENSION(:) :: INDEX  
REAL(8), DIMENSION(:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dlamrg(int n1, int n2, double *a, int trd1, int trd2,  
           int *index);
```

```
void dlamrg_64(long n1, long n2, double *a, long trd1, long  
              trd2, long *index);
```

PURPOSE

dlamrg will create a permutation list which will merge the elements of A (which is composed of two independently sorted sets) into a single set which is sorted in ascending order.

ARGUMENTS

N1 (input)

Length of the first sequence to be merged.

N2 (input)

Length of the second sequence to be merged.

A (input) On entry, the first N1 elements of A contain a list of numbers which are sorted in either ascending or descending order. Likewise for the final N2 elements.

TRD1 (input)

Describes the stride to be taken through the array A for the first N1 elements.

= -1 subset is sorted in descending order.

= 1 subset is sorted in ascending order.

TRD2 (input)

Describes the stride to be taken through the array A for the first N1 elements.

= -1 subset is sorted in descending order.

= 1 subset is sorted in ascending order.

INDEX (output)

On exit this array will contain a permutation such that if $B(I) = A(\text{INDEX}(I))$ for $I=1, N1+N2$, then B will be sorted in ascending order.

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NAME

dlarz - applies a real elementary reflector H to a real M-by-N matrix C, from either the left or the right

SYNOPSIS

```
SUBROUTINE DLARZ(SIDE, M, N, L, V, INCV, TAU, C, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
INTEGER M, N, L, INCV, LDC  
DOUBLE PRECISION TAU  
DOUBLE PRECISION V(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DLARZ_64(SIDE, M, N, L, V, INCV, TAU, C, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
INTEGER*8 M, N, L, INCV, LDC  
DOUBLE PRECISION TAU  
DOUBLE PRECISION V(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE LARZ(SIDE, [M], [N], L, V, [INCV], TAU, C, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
INTEGER :: M, N, L, INCV, LDC  
REAL(8) :: TAU  
REAL(8), DIMENSION(:) :: V, WORK  
REAL(8), DIMENSION(:, :) :: C
```

```
SUBROUTINE LARZ_64(SIDE, [M], [N], L, V, [INCV], TAU, C, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
INTEGER(8) :: M, N, L, INCV, LDC  
REAL(8) :: TAU  
REAL(8), DIMENSION(:) :: V, WORK  
REAL(8), DIMENSION(:, :) :: C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dlarz(char side, int m, int n, int l, double *v, int
          incv, double tau, double *c, int ldc);
```

```
void dlarz_64(char side, long m, long n, long l, double *v,
              long incv, double tau, double *c, long ldc);
```

PURPOSE

dlarz applies a real elementary reflector H to a real M-by-N matrix C, from either the left or the right. H is represented in the form

$$H = I - \tau * v * v'$$

where tau is a real scalar and v is a real vector.

If tau = 0, then H is taken to be the unit matrix.

H is a product of k elementary reflectors as returned by STZRZF.

ARGUMENTS

SIDE (input)

= 'L': form $H * C$
= 'R': form $C * H$

M (input) The number of rows of the matrix C.

N (input) The number of columns of the matrix C.

L (input) The number of entries of the vector V containing the meaningful part of the Householder vectors. If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L \geq 0$.

V (input) The vector v in the representation of H as returned by STZRZF. V is not used if TAU = 0.

INCV (input)

The increment between elements of v. INCV $\neq 0$.

TAU (input)

The value tau in the representation of H.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by the matrix $H * C$ if SIDE = 'L', or $C * H$ if SIDE = 'R'.

LDC (input)

The leading dimension of the array C. LDC $\geq \max(1, M)$.

WORK (workspace)

(N) if SIDE = 'L' or (M) if SIDE = 'R'

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

dlarzb - applies a real block reflector H or its transpose H**T to a real distributed M-by-N C from the left or the right

SYNOPSIS

```
SUBROUTINE DLARZB(SIDE, TRANS, DIRECT, STOREV, M, N, K, L, V, LDV, T,
  LDT, C, LDC, WORK, LDWORK)
```

```
CHARACTER * 1 SIDE, TRANS, DIRECT, STOREV
INTEGER M, N, K, L, LDV, LDT, LDC, LDWORK
DOUBLE PRECISION V(LDV,*), T(LDT,*), C(LDC,*),
WORK(LDWORK,*)
```

```
SUBROUTINE DLARZB_64(SIDE, TRANS, DIRECT, STOREV, M, N, K, L, V, LDV,
  T, LDT, C, LDC, WORK, LDWORK)
```

```
CHARACTER * 1 SIDE, TRANS, DIRECT, STOREV
INTEGER*8 M, N, K, L, LDV, LDT, LDC, LDWORK
DOUBLE PRECISION V(LDV,*), T(LDT,*), C(LDC,*),
WORK(LDWORK,*)
```

F95 INTERFACE

```
SUBROUTINE LARZB(SIDE, TRANS, DIRECT, STOREV, [M], [N], K, L, V, [LDV],
  T, [LDT], C, [LDC], [WORK], [LDWORK])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS, DIRECT, STOREV
INTEGER :: M, N, K, L, LDV, LDT, LDC, LDWORK
REAL(8), DIMENSION(:,:) :: V, T, C, WORK
```

```
SUBROUTINE LARZB_64(SIDE, TRANS, DIRECT, STOREV, [M], [N], K, L, V,
  [LDV], T, [LDT], C, [LDC], [WORK], [LDWORK])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS, DIRECT, STOREV
INTEGER(8) :: M, N, K, L, LDV, LDT, LDC, LDWORK
REAL(8), DIMENSION(:,:) :: V, T, C, WORK
```

C INTERFACE

```

#include <sunperf.h>

void dlarzb(char side, char trans, char direct, char storev,
            int m, int n, int k, int l, double *v, int ldv,
            double *t, int ldt, double *c, int ldc, int
            ldwork);

void dlarzb_64(char side, char trans, char direct, char
               storev, long m, long n, long k, long l, double *v,
               long ldv, double *t, long ldt, double *c, long
               ldc, long ldwork);

```

PURPOSE

dlarzb applies a real block reflector H or its transpose H^*T to a real distributed M -by- N C from the left or the right.

Currently, only `STOREV = 'R'` and `DIRECT = 'B'` are supported.

ARGUMENTS

`SIDE` (input)
 = 'L': apply H or H' from the Left
 = 'R': apply H or H' from the Right

`TRANS` (input)
 = 'N': apply H (No transpose)
 = 'C': apply H' (Transpose)

`DIRECT` (input)
 Indicates how H is formed from a product of elementary reflectors = 'F': $H = H(1) H(2) \dots H(k)$ (Forward, not supported yet)
 = 'B': $H = H(k) \dots H(2) H(1)$ (Backward)

`STOREV` (input)
 Indicates how the vectors which define the elementary reflectors are stored:
 = 'C': Columnwise (not supported yet)
 = 'R': Rowwise

`M` (input) The number of rows of the matrix C .

`N` (input) The number of columns of the matrix C .

`K` (input) The order of the matrix T (= the number of elementary reflectors whose product defines the block reflector).

`L` (input) The number of columns of the matrix V containing the meaningful part of the Householder reflectors. If `SIDE = 'L'`, $M \geq L \geq 0$, if `SIDE = 'R'`, $N \geq L \geq 0$.

V (input) If STOREV = 'C', NV = K; if STOREV = 'R', NV = L.

LDV (input)
The leading dimension of the array V. If STOREV = 'C', LDV \geq L; if STOREV = 'R', LDV \geq K.

T (input) The triangular K-by-K matrix T in the representation of the block reflector.

LDT (input)
The leading dimension of the array T. LDT \geq K.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by H*C or H'*C or C*H or C*H'.

LDC (input)
The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)
dimension(MAX(M,N),K)

LDWORK (input)
The leading dimension of the array WORK. If SIDE = 'L', LDWORK \geq max(1,N); if SIDE = 'R', LDWORK \geq max(1,M).

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

dlarzt - form the triangular factor T of a real block reflector H of order > n, which is defined as a product of k elementary reflectors

SYNOPSIS

```
SUBROUTINE DLARZT(DIRECT, STOREV, N, K, V, LDV, TAU, T, LDT)
```

```
CHARACTER * 1 DIRECT, STOREV  
INTEGER N, K, LDV, LDT  
DOUBLE PRECISION V(LDV,*), TAU(*), T(LDT,*)
```

```
SUBROUTINE DLARZT_64(DIRECT, STOREV, N, K, V, LDV, TAU, T, LDT)
```

```
CHARACTER * 1 DIRECT, STOREV  
INTEGER*8 N, K, LDV, LDT  
DOUBLE PRECISION V(LDV,*), TAU(*), T(LDT,*)
```

F95 INTERFACE

```
SUBROUTINE LARZT(DIRECT, STOREV, N, K, V, [LDV], TAU, T, [LDT])
```

```
CHARACTER(LEN=1) :: DIRECT, STOREV  
INTEGER :: N, K, LDV, LDT  
REAL(8), DIMENSION(:) :: TAU  
REAL(8), DIMENSION(:,:) :: V, T
```

```
SUBROUTINE LARZT_64(DIRECT, STOREV, N, K, V, [LDV], TAU, T, [LDT])
```

```
CHARACTER(LEN=1) :: DIRECT, STOREV  
INTEGER(8) :: N, K, LDV, LDT  
REAL(8), DIMENSION(:) :: TAU  
REAL(8), DIMENSION(:,:) :: V, T
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dlarzt(char direct, char storev, int n, int k, double  
*v, int ldv, double *tau, double *t, int ldt);
```

```
void dlarzt_64(char direct, char storev, long n, long k,
              double *v, long ldv, double *tau, double *t, long
              ldt);
```

PURPOSE

dlarzt forms the triangular factor T of a real block reflector H of order > n, which is defined as a product of k elementary reflectors.

If DIRECT = 'F', H = H(1) H(2) . . . H(k) and T is upper triangular;

If DIRECT = 'B', H = H(k) . . . H(2) H(1) and T is lower triangular.

If STOREV = 'C', the vector which defines the elementary reflector H(i) is stored in the i-th column of the array V, and

$$H = I - V * T * V'$$

If STOREV = 'R', the vector which defines the elementary reflector H(i) is stored in the i-th row of the array V, and

$$H = I - V' * T * V$$

Currently, only STOREV = 'R' and DIRECT = 'B' are supported.

ARGUMENTS

DIRECT (input)

Specifies the order in which the elementary reflectors are multiplied to form the block reflector:
 = 'F': H = H(1) H(2) . . . H(k) (Forward, not supported yet)
 = 'B': H = H(k) . . . H(2) H(1) (Backward)

STOREV (input)

Specifies how the vectors which define the elementary reflectors are stored (see also Further Details):
 = 'R': rowwise

N (input) The order of the block reflector H. N >= 0.

K (input) The order of the triangular factor T (= the number of elementary reflectors). K >= 1.

V (input) (LDV,K) if STOREV = 'C' (LDV,N) if STOREV = 'R'
 The matrix V. See further details.

LDV (input)

The leading dimension of the array V. If STOREV =

'C', LDV >= max(1,N); if STOREV = 'R', LDV >= K.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i).

T (input)

The k by k triangular factor T of the block reflector. If DIRECT = 'F', T is upper triangular; if DIRECT = 'B', T is lower triangular. The rest of the array is not used.

LDT (input)

The leading dimension of the array T. LDT >= K.

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

The shape of the matrix V and the storage of the vectors which define the H(i) is best illustrated by the following example with n = 5 and k = 3. The elements equal to 1 are not stored; the corresponding array elements are modified but restored on exit. The rest of the array is not used.

DIRECT = 'F' and STOREV = 'C': DIRECT = 'F' and STOREV = 'R':

<pre> (v1 v2 v3) V = (v1 v2 v3) . . 1) . 1) (v1 v2 v3) (v1 v2 v3) . . . 1 . . . 1 1 </pre>	<p style="text-align: center;">_____V_____</p> <pre> / (v1 v1 v1 v1 v1 1 (v2 v2 v2 v2 v2 . (v3 v3 v3 v3 v3 . </pre>
--	--

DIRECT = 'B' and STOREV = 'C': DIRECT = 'B' and STOREV = 'R':

<pre> . 1 . . 1 v2 v2 v2) v3 v3 v3) . . . (v1 v2 v3) V = (v1 v2 v3) (v1 v2 v3) </pre>	<p style="text-align: center;">_____V_____</p> <pre> / (1 v1 v1 v1 v1 v1) (. 1 v2 v2 (. . 1 . . . v3 v3 </pre>
---	--

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NAME

dlasrt - the numbers in D in increasing order (if ID = 'I')
or in decreasing order (if ID = 'D')

SYNOPSIS

```
SUBROUTINE DLASRT(ID, N, D, INFO)
```

```
CHARACTER * 1 ID  
INTEGER N, INFO  
DOUBLE PRECISION D(*)
```

```
SUBROUTINE DLASRT_64(ID, N, D, INFO)
```

```
CHARACTER * 1 ID  
INTEGER*8 N, INFO  
DOUBLE PRECISION D(*)
```

F95 INTERFACE

```
SUBROUTINE LASRT(ID, [N], D, [INFO])
```

```
CHARACTER(LEN=1) :: ID  
INTEGER :: N, INFO  
REAL(8), DIMENSION(:) :: D
```

```
SUBROUTINE LASRT_64(ID, [N], D, [INFO])
```

```
CHARACTER(LEN=1) :: ID  
INTEGER(8) :: N, INFO  
REAL(8), DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dlasrt(char id, int n, double *d, int *info);
```

```
void dlasrt_64(char id, long n, double *d, long *info);
```

PURPOSE

dlasrt the numbers in D in increasing order (if ID = 'I') or in decreasing order (if ID = 'D').

Use Quick Sort, reverting to Insertion sort on arrays of size ≤ 20 . Dimension of STACK limits N to about 2^{32} .

ARGUMENTS

ID (input)

= 'I': sort D in increasing order;
= 'D': sort D in decreasing order.

N (input) The length of the array D.

D (input/output)

On entry, the array to be sorted. On exit, D has been sorted into increasing order ($D(1) \leq \dots \leq D(N)$) or into decreasing order ($D(1) \geq \dots \geq D(N)$), depending on ID.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dlatzm - routine is deprecated and has been replaced by routine SORMRZ

SYNOPSIS

```
SUBROUTINE DLATZM(SIDE, M, N, V, INCV, TAU, C1, C2, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
INTEGER M, N, INCV, LDC  
DOUBLE PRECISION TAU  
DOUBLE PRECISION V(*), C1(LDC,*), C2(LDC,*), WORK(*)
```

```
SUBROUTINE DLATZM_64(SIDE, M, N, V, INCV, TAU, C1, C2, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
INTEGER*8 M, N, INCV, LDC  
DOUBLE PRECISION TAU  
DOUBLE PRECISION V(*), C1(LDC,*), C2(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE LATZM(SIDE, [M], [N], V, [INCV], TAU, C1, C2, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
INTEGER :: M, N, INCV, LDC  
REAL(8) :: TAU  
REAL(8), DIMENSION(:) :: V, WORK  
REAL(8), DIMENSION(:, :) :: C1, C2
```

```
SUBROUTINE LATZM_64(SIDE, [M], [N], V, [INCV], TAU, C1, C2, [LDC],  
[WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
INTEGER(8) :: M, N, INCV, LDC  
REAL(8) :: TAU  
REAL(8), DIMENSION(:) :: V, WORK  
REAL(8), DIMENSION(:, :) :: C1, C2
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dlatzm(char side, int m, int n, double *v, int incv,
            double tau, double *c1, double *c2, int ldc);

void dlatzm_64(char side, long m, long n, double *v, long
               incv, double tau, double *c1, double *c2, long
               ldc);

```

PURPOSE

dlatzm routine is deprecated and has been replaced by routine SORMRZ.

SLATZM applies a Householder matrix generated by STZRQF to a matrix.

Let $P = I - \tau \cdot u \cdot u'$, $u = \begin{pmatrix} 1 \\ v \end{pmatrix}$,

where v is an $(m-1)$ vector if $SIDE = 'L'$, or a $(n-1)$ vector if $SIDE = 'R'$.

If $SIDE$ equals $'L'$, let

$$C = \begin{bmatrix} C1 & 1 \\ C2 & \dots & m-1 \\ & & n \end{bmatrix}$$

Then C is overwritten by $P \cdot C$.

If $SIDE$ equals $'R'$, let

$$C = \begin{bmatrix} C1, & C2 \\ & \dots & m \\ & & 1 & \dots & n-1 \end{bmatrix}$$

Then C is overwritten by $C \cdot P$.

ARGUMENTS

$SIDE$ (input)

= $'L'$: form $P * C$
 = $'R'$: form $C * P$

M (input) The number of rows of the matrix C .

N (input) The number of columns of the matrix C .

V (input) $(1 + (M-1) \cdot \text{abs}(\text{INCV}))$ if $SIDE = 'L'$ $(1 + (N-1) \cdot \text{abs}(\text{INCV}))$ if $SIDE = 'R'$ The vector v in the representation of P . V is not used if $\text{TAU} = 0$.

INCV (input)

The increment between elements of v . $\text{INCV} \neq 0$

TAU (input)

The value τ in the representation of P .

$C1$ (input/output)

(LDC, N) if $SIDE = 'L'$ $(M, 1)$ if $SIDE = 'R'$ On entry, the n -vector $C1$ if $SIDE = 'L'$, or the m -vector $C1$ if $SIDE = 'R'$.

On exit, the first row of P*C if SIDE = 'L', or
the first column of C*P if SIDE = 'R'.

C2 (input/output)

(LDC, N) if SIDE = 'L' (LDC, N-1) if SIDE = 'R'
On entry, the (m - 1) x n matrix C2 if SIDE = 'L',
or the m x (n - 1) matrix C2 if SIDE = 'R'.

On exit, rows 2:m of P*C if SIDE = 'L', or columns
2:m of C*P if SIDE = 'R'.

LDC (input)

The leading dimension of the arrays C1 and C2. LDC
>= (1,M).

WORK (workspace)

(N) if SIDE = 'L' (M) if SIDE = 'R'

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NAME

dnrm2 - Return the Euclidian norm of a vector.

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DNRM2(N, X, INCX)
```

```
INTEGER N, INCX  
DOUBLE PRECISION X(*)
```

```
DOUBLE PRECISION FUNCTION DNRM2_64(N, X, INCX)
```

```
INTEGER*8 N, INCX  
DOUBLE PRECISION X(*)
```

F95 INTERFACE

```
REAL(8) FUNCTION NRM2([N], X, [INCX])
```

```
INTEGER :: N, INCX  
REAL(8), DIMENSION(:) :: X
```

```
REAL(8) FUNCTION NRM2_64([N], X, [INCX])
```

```
INTEGER(8) :: N, INCX  
REAL(8), DIMENSION(:) :: X
```

C INTERFACE

```
#include <sunperf.h>
```

```
double dnrm2(int n, double *x, int incx);
```

```
double dnrm2_64(long n, double *x, long incx);
```

PURPOSE

dnrm2 Return the Euclidian norm of a vector x where x is an n-vector.

ARGUMENTS

- N (input)
On entry, N specifies the number of elements in the vector. N must be at least one for the sub-routine to have any visible effect. Unchanged on exit.
- X (input)
(1 + (n - 1) * abs(INCX)). On entry, the incremented array X must contain the vector x. Unchanged on exit.
- INCX (input)
On entry, INCX specifies the increment for the elements of X. If INCX < 1 then DNRM2 returns 0. Unchanged on exit.

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NAME

dopgtr - generate a real orthogonal matrix Q which is defined as the product of $n-1$ elementary reflectors $H(i)$ of order n , as returned by SSPTRD using packed storage

SYNOPSIS

```
SUBROUTINE DOPGTR(UPLO, N, AP, TAU, Q, LDQ, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDQ, INFO  
DOUBLE PRECISION AP(*), TAU(*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE DOPGTR_64(UPLO, N, AP, TAU, Q, LDQ, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDQ, INFO  
DOUBLE PRECISION AP(*), TAU(*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE OPGTR(UPLO, [N], AP, TAU, Q, [LDQ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDQ, INFO  
REAL(8), DIMENSION(:) :: AP, TAU, WORK  
REAL(8), DIMENSION(:, :) :: Q
```

```
SUBROUTINE OPGTR_64(UPLO, [N], AP, TAU, Q, [LDQ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDQ, INFO  
REAL(8), DIMENSION(:) :: AP, TAU, WORK  
REAL(8), DIMENSION(:, :) :: Q
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dopgtr(char uplo, int n, double *ap, double *tau, double *q, int ldq, int *info);
```

```
void dopgtr_64(char uplo, long n, double *ap, double *tau,
```

```
double *q, long ldq, long *info);
```

PURPOSE

dopgtr generates a real orthogonal matrix Q which is defined as the product of $n-1$ elementary reflectors $H(i)$ of order n , as returned by SSPTRD using packed storage:
if UPLO = 'U', $Q = H(n-1) \dots H(2) H(1)$,
if UPLO = 'L', $Q = H(1) H(2) \dots H(n-1)$.

ARGUMENTS

UPLO (input)
= 'U': Upper triangular packed storage used in previous call to SSPTRD; = 'L': Lower triangular packed storage used in previous call to SSPTRD.

N (input) The order of the matrix Q . $N \geq 0$.

AP (input)
The vectors which define the elementary reflectors, as returned by SSPTRD.

TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by SSPTRD.

Q (output)
The N -by- N orthogonal matrix Q .

LDQ (input)
The leading dimension of the array Q . $LDQ \geq \max(1, N)$.

WORK (workspace)
dimension($N-1$)

INFO (output)
= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

dopmtr - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE DOPMTR(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,  
INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
INTEGER M, N, LDC, INFO  
DOUBLE PRECISION AP(*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DOPMTR_64(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,  
INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
INTEGER*8 M, N, LDC, INFO  
DOUBLE PRECISION AP(*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE OPMTR(SIDE, UPLO, [TRANS], [M], [N], AP, TAU, C, [LDC],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
INTEGER :: M, N, LDC, INFO  
REAL(8), DIMENSION(:) :: AP, TAU, WORK  
REAL(8), DIMENSION(:,:) :: C
```

```
SUBROUTINE OPMTR_64(SIDE, UPLO, [TRANS], [M], [N], AP, TAU, C, [LDC],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
INTEGER(8) :: M, N, LDC, INFO  
REAL(8), DIMENSION(:) :: AP, TAU, WORK  
REAL(8), DIMENSION(:,:) :: C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dopmtr(char side, char uplo, char trans, int m, int n,
```

```

        double *ap, double *tau, double *c, int ldc, int
        *info);

void dopmtr_64(char side, char uplo, char trans, long m,
              long n, double *ap, double *tau, double *c, long
              ldc, long *info);

```

PURPOSE

dopmtr overwrites the general real M-by-N matrix C with
 TRANS = 'T': $Q^{*T} * C$ $C * Q^{*T}$

where Q is a real orthogonal matrix of order nq, with nq = m
 if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
 product of nq-1 elementary reflectors, as returned by SSPTRD
 using packed storage:

if UPLO = 'U', Q = H(nq-1) . . . H(2) H(1);

if UPLO = 'L', Q = H(1) H(2) . . . H(nq-1).

ARGUMENTS

SIDE (input)
 = 'L': apply Q or Q^{*T} from the Left;
 = 'R': apply Q or Q^{*T} from the Right.

UPLO (input)
 = 'U': Upper triangular packed storage used in
 previous call to SSPTRD; = 'L': Lower triangular
 packed storage used in previous call to SSPTRD.

TRANS (input)
 = 'N': No transpose, apply Q;
 = 'T': Transpose, apply Q^{*T} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

AP (input)
 (M*(M+1)/2) if SIDE = 'L' (N*(N+1)/2) if SIDE =
 'R' The vectors which define the elementary
 reflectors, as returned by SSPTRD. AP is modified
 by the routine but restored on exit.

TAU (input)
 or (N-1) if SIDE = 'R' TAU(i) must contain the
 scalar factor of the elementary reflector H(i), as
 returned by SSPTRD.

C (input/output)
 On entry, the M-by-N matrix C. On exit, C is
 overwritten by $Q * C$ or $Q^{*T} * C$ or $C * Q^{*T}$ or $C * Q$.

LDC (input)
The leading dimension of the array C. LDC \geq
max(1,M).

WORK (workspace)
(N) if SIDE = 'L' (M) if SIDE = 'R'

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dorg2l - generate an m by n real matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE DORG2L(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER M, N, K, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORG2L_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORG2L([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE ORG2L_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, K, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorg2l(int m, int n, int k, double *a, int lda, double  
*tau, int *info);
```

```
void dorg2l_64(long m, long n, long k, double *a, long lda,  
double *tau, long *info);
```

PURPOSE

dorg2l L generates an m by n real matrix Q with orthonormal columns, which is defined as the last n columns of a product of k elementary reflectors of order m

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGEQLF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.

A (input/output)

On entry, the (n-k+i)-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by SGEQLF in the last k columns of its array argument A. On exit, the m by n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGEQLF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

dorg2r - generate an m by n real matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE DORG2R(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER M, N, K, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORG2R_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORG2R([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE ORG2R_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, K, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorg2r(int m, int n, int k, double *a, int lda, double  
          *tau, int *info);
```

```
void dorg2r_64(long m, long n, long k, double *a, long lda,  
              double *tau, long *info);
```

PURPOSE

dorg2r R generates an m by n real matrix Q with orthonormal columns, which is defined as the first n columns of a product of k elementary reflectors of order m

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGEQRF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.

A (input/output)
On entry, the i-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by SGEQRF in the first k columns of its array argument A. On exit, the m-by-n matrix Q.

LDA (input)
The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGEQRF.

WORK (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

dorgbr - generate one of the real orthogonal matrices Q or P^*T determined by SGEBRD when reducing a real matrix A to bidiagonal form

SYNOPSIS

```
SUBROUTINE DORGBR(VECT, M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT  
INTEGER M, N, K, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORGBR_64(VECT, M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT  
INTEGER*8 M, N, K, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGBR(VECT, M, [N], K, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: VECT  
INTEGER :: M, N, K, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A
```

```
SUBROUTINE ORGBR_64(VECT, M, [N], K, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: VECT  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorgbr(char vect, int m, int n, int k, double *a, int  
lda, double *tau, int *info);
```

```
void dorgbr_64(char vect, long m, long n, long k, double *a,  
              long lda, double *tau, long *info);
```

PURPOSE

dorgbr generates one of the real orthogonal matrices Q or P^{**T} determined by SGEBRD when reducing a real matrix A to bidiagonal form: $A = Q * B * P^{**T}$. Q and P^{**T} are defined as products of elementary reflectors $H(i)$ or $G(i)$ respectively.

If $VECT = 'Q'$, A is assumed to have been an M -by- K matrix, and Q is of order M :
if $m \geq k$, $Q = H(1) H(2) \dots H(k)$ and DORGBR returns the first n columns of Q , where $m \geq n \geq k$;
if $m < k$, $Q = H(1) H(2) \dots H(m-1)$ and DORGBR returns Q as an M -by- M matrix.

If $VECT = 'P'$, A is assumed to have been a K -by- N matrix, and P^{**T} is of order N :
if $k < n$, $P^{**T} = G(k) \dots G(2) G(1)$ and DORGBR returns the first m rows of P^{**T} , where $n \geq m \geq k$;
if $k \geq n$, $P^{**T} = G(n-1) \dots G(2) G(1)$ and DORGBR returns P^{**T} as an N -by- N matrix.

ARGUMENTS

VECT (input)

Specifies whether the matrix Q or the matrix P^{**T} is required, as defined in the transformation applied by SGEBRD:
= 'Q': generate Q ;
= 'P': generate P^{**T} .

M (input) The number of rows of the matrix Q or P^{**T} to be returned. $M \geq 0$.

N (input) The number of columns of the matrix Q or P^{**T} to be returned. $N \geq 0$. If $VECT = 'Q'$, $M \geq N \geq \min(M,K)$; if $VECT = 'P'$, $N \geq M \geq \min(N,K)$.

K (input) If $VECT = 'Q'$, the number of columns in the original M -by- K matrix reduced by SGEBRD. If $VECT = 'P'$, the number of rows in the original K -by- N matrix reduced by SGEBRD. $K \geq 0$.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by SGEBRD. On exit, the M -by- N matrix Q or P^{**T} .

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1,M)$.

TAU (input)

(min(M,K)) if VECT = 'Q' (min(N,K)) if VECT = 'P'
TAU(i) must contain the scalar factor of the elementary reflector H(i) or G(i), which determines Q or P**T, as returned by SGEBRD in its array argument TAUQ or TAUP.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK >= max(1,min(M,N)). For optimum performance LWORK >= min(M,N)*NB, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dorghr - generate a real orthogonal matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N, as returned by SGEHRD

SYNOPSIS

```
SUBROUTINE DORGHR(N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
```

```
INTEGER N, ILO, IHI, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORGHR_64(N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
```

```
INTEGER*8 N, ILO, IHI, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGHR([N], ILO, IHI, A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
INTEGER :: N, ILO, IHI, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE ORGHR_64([N], ILO, IHI, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
INTEGER(8) :: N, ILO, IHI, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorghr(int n, int ilo, int ihi, double *a, int lda,  
double *tau, int *info);
```

```
void dorghr_64(long n, long ilo, long ihi, double *a, long  
lda, double *tau, long *info);
```

PURPOSE

dorghr generates a real orthogonal matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N , as returned by SGEHRD:

$$Q = H(\text{ilo}) H(\text{ilo}+1) \dots H(\text{ihi}-1).$$

ARGUMENTS

N (input) The order of the matrix Q . $N \geq 0$.

ILO (input)

ILO and IHI must have the same values as in the previous call of SGEHRD. Q is equal to the unit matrix except in the submatrix $Q(\text{ilo}+1:\text{ihi}, \text{ilo}+1:\text{ihi})$. $1 \leq \text{ILO} \leq \text{IHI} \leq N$, if $N > 0$; $\text{ILO}=1$ and $\text{IHI}=0$, if $N=0$.

IHI (input)

See the description of ILO.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by SGEHRD. On exit, the N -by- N orthogonal matrix Q .

LDA (input)

The leading dimension of the array A . $\text{LDA} \geq \max(1, N)$.

TAU (input)

$\text{TAU}(i)$ must contain the scalar factor of the elementary reflector $H(i)$, as returned by SGEHRD.

WORK (workspace)

On exit, if $\text{INFO} = 0$, $\text{WORK}(1)$ returns the optimal LWORK .

LWORK (input)

The dimension of the array WORK . $\text{LWORK} \geq \text{IHI}-\text{ILO}$. For optimum performance $\text{LWORK} \geq (\text{IHI}-\text{ILO}) * \text{NB}$, where NB is the optimal blocksize.

If $\text{LWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value

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NAME

dorgl2 - generate an m by n real matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE DORGL2(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER M, N, K, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORGL2_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGL2([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE ORGL2_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, K, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorgl2(int m, int n, int k, double *a, int lda, double  
*tau, int *info);
```

```
void dorgl2_64(long m, long n, long k, double *a, long lda,  
double *tau, long *info);
```

PURPOSE

dorgl2 generates an m by n real matrix Q with orthonormal rows, which is defined as the first m rows of a product of k elementary reflectors of order n

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGELQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $M \geq K \geq 0$.

A (input/output)

On entry, the i-th row must contain the vector which defines the elementary reflector $H(i)$, for $i = 1, 2, \dots, k$, as returned by SGELQF in the first k rows of its array argument A. On exit, the m-by-n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by SGELQF.

WORK (workspace)

dimension(M)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

dorglq - generate an M-by-N real matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE DORGLQ(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, K, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORGLQ_64(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGLQ(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A
```

```
SUBROUTINE ORGLQ_64(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK],  
[INFO])
```

```
INTEGER(8) :: M, N, K, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorglq(int m, int n, int k, double *a, int lda, double  
*tau, int *info);
```

```
void dorglq_64(long m, long n, long k, double *a, long lda,  
double *tau, long *info);
```

PURPOSE

dorglq generates an M-by-N real matrix Q with orthonormal rows, which is defined as the first M rows of a product of K elementary reflectors of order N

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGELQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $M \geq K \geq 0$.

A (input/output)

On entry, the i-th row must contain the vector which defines the elementary reflector $H(i)$, for $i = 1, 2, \dots, k$, as returned by SGELQF in the first k rows of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by SGELQF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, M)$. For optimum performance $LDWORK \geq M \cdot NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

dorgql - generate an M-by-N real matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE DORGQL(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, K, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORGQL_64(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGQL(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE ORGQL_64(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK],  
[INFO])
```

```
INTEGER(8) :: M, N, K, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorgql(int m, int n, int k, double *a, int lda, double  
*tau, int *info);
```

```
void dorgql_64(long m, long n, long k, double *a, long lda,  
double *tau, long *info);
```

PURPOSE

dorgql generates an M-by-N real matrix Q with orthonormal columns, which is defined as the last N columns of a product of K elementary reflectors of order M

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGEQLF.

ARGUMENTS

M (input) The number of rows of the matrix Q. M \geq 0.

N (input) The number of columns of the matrix Q. M \geq N \geq 0.

K (input) The number of elementary reflectors whose product defines the matrix Q. N \geq K \geq 0.

A (input/output)

On entry, the (n-k+i)-th column must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by SGEQLF in the last k columns of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. LDA \geq max(1,M).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGEQLF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq max(1,N). For optimum performance LDWORK \geq N*NB, where NB is the optimal blocksize.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

dorgqr - generate an M-by-N real matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE DORGQR(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, K, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORGQR_64(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGQR(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A
```

```
SUBROUTINE ORGQR_64(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK],  
[INFO])
```

```
INTEGER(8) :: M, N, K, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorgqr(int m, int n, int k, double *a, int lda, double  
*tau, int *info);
```

```
void dorgqr_64(long m, long n, long k, double *a, long lda,  
double *tau, long *info);
```

PURPOSE

dorgqr generates an M-by-N real matrix Q with orthonormal columns, which is defined as the first N columns of a product of K elementary reflectors of order M

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGEQRF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.

A (input/output)

On entry, the i-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by SGEQRF in the first k columns of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGEQRF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N \cdot NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

dorgr2 - generate an m by n real matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE DORGR2(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER M, N, K, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORGR2_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGR2([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE ORGR2_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, K, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorgr2(int m, int n, int k, double *a, int lda, double  
          *tau, int *info);
```

```
void dorgr2_64(long m, long n, long k, double *a, long lda,  
             double *tau, long *info);
```

PURPOSE

dorgqr2 generates an m by n real matrix Q with orthonormal rows, which is defined as the last m rows of a product of k elementary reflectors of order n

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGERQF.

ARGUMENTS

M (input) The number of rows of the matrix Q . $M \geq 0$.

N (input) The number of columns of the matrix Q . $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q . $M \geq K \geq 0$.

A (input/output)

On entry, the $(m-k+i)$ -th row must contain the vector which defines the elementary reflector $H(i)$, for $i = 1, 2, \dots, k$, as returned by SGERQF in the last k rows of its array argument A . On exit, the m by n matrix Q .

LDA (input)

The first dimension of the array A . $LDA \geq \max(1, M)$.

TAU (input)

$TAU(i)$ must contain the scalar factor of the elementary reflector $H(i)$, as returned by SGERQF.

$WORK$ (workspace)

dimension(M)

$INFO$ (output)

= 0: successful exit

< 0: if $INFO = -i$, the i -th argument has an illegal value

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NAME

dorgrq - generate an M-by-N real matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE DORGRQ(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, K, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORGRQ_64(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGRQ(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE ORGRQ_64(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK],  
[INFO])
```

```
INTEGER(8) :: M, N, K, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorgrq(int m, int n, int k, double *a, int lda, double  
*tau, int *info);
```

```
void dorgrq_64(long m, long n, long k, double *a, long lda,  
double *tau, long *info);
```

PURPOSE

dorgqr generates an M-by-N real matrix Q with orthonormal rows, which is defined as the last M rows of a product of K elementary reflectors of order N

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGERQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $M \geq K \geq 0$.

A (input/output)

On entry, the (m-k+i)-th row must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by SGERQF in the last k rows of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGERQF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, M)$. For optimum performance $LDWORK \geq M \cdot NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

dorgtr - generate a real orthogonal matrix Q which is defined as the product of $n-1$ elementary reflectors of order N , as returned by SSYTRD

SYNOPSIS

```
SUBROUTINE DORGTR(UPLO, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DORGTR_64(UPLO, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGTR(UPLO, [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A
```

```
SUBROUTINE ORGTR_64(UPLO, [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dorgtr(char uplo, int n, double *a, int lda, double  
          *tau, int *info);
```

```
void dorgtr_64(char uplo, long n, double *a, long lda, dou-
```

```
ble *tau, long *info);
```

PURPOSE

dorgtr generates a real orthogonal matrix Q which is defined as the product of $n-1$ elementary reflectors of order N , as returned by SSYTRD:

if UPLO = 'U', $Q = H(n-1) \dots H(2) H(1)$,

if UPLO = 'L', $Q = H(1) H(2) \dots H(n-1)$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A contains elementary reflectors from SSYTRD; = 'L': Lower triangle of A contains elementary reflectors from SSYTRD.

N (input) The order of the matrix Q . $N \geq 0$.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by SSYTRD. On exit, the N -by- N orthogonal matrix Q .

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by SSYTRD.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1, N-1)$. For optimum performance $LWORK \geq (N-1)*NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = - i , the i -th argument had an illegal value

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NAME

dormbr - VECT = 'Q', DORMBR overwrites the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE DORMBR(VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC,
                 WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT, SIDE, TRANS
INTEGER M, N, K, LDA, LDC, LWORK, INFO
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DORMBR_64(VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC,
                    WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT, SIDE, TRANS
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMBR(VECT, SIDE, [TRANS], [M], [N], K, A, [LDA], TAU, C,
                [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, SIDE, TRANS
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
REAL(8), DIMENSION(:) :: TAU, WORK
REAL(8), DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMBR_64(VECT, SIDE, [TRANS], [M], [N], K, A, [LDA], TAU,
                   C, [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, SIDE, TRANS
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
REAL(8), DIMENSION(:) :: TAU, WORK
REAL(8), DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dormbr(char vect, char side, char trans, int m, int n,
```

```

        int k, double *a, int lda, double *tau, double *c,
        int ldc, int *info);

void dormbr_64(char vect, char side, char trans, long m,
               long n, long k, double *a, long lda, double *tau,
               double *c, long ldc, long *info);

```

PURPOSE

dormbr VECT = 'Q', DORMBR overwrites the general real M-by-N matrix C with

```

                SIDE = 'L'      SIDE = 'R'  TRANS = 'N':
Q * C          C * Q TRANS = 'T':      Q**T * C      C *
Q**T

```

If VECT = 'P', DORMBR overwrites the general real M-by-N matrix C with

```

                SIDE = 'L'      SIDE = 'R'
TRANS = 'N':    P * C          C * P
TRANS = 'T':    P**T * C       C * P**T

```

Here Q and P**T are the orthogonal matrices determined by SGEHRD when reducing a real matrix A to bidiagonal form: $A = Q * B * P^{**T}$. Q and P**T are defined as products of elementary reflectors H(i) and G(i) respectively.

Let nq = m if SIDE = 'L' and nq = n if SIDE = 'R'. Thus nq is the order of the orthogonal matrix Q or P**T that is applied.

If VECT = 'Q', A is assumed to have been an NQ-by-K matrix:
if nq >= k, Q = H(1) H(2) . . . H(k);
if nq < k, Q = H(1) H(2) . . . H(nq-1).

If VECT = 'P', A is assumed to have been a K-by-NQ matrix:
if k < nq, P = G(1) G(2) . . . G(k);
if k >= nq, P = G(1) G(2) . . . G(nq-1).

ARGUMENTS

VECT (input)

```

= 'Q': apply Q or Q**T;
= 'P': apply P or P**T.

```

SIDE (input)

```

= 'L': apply Q, Q**T, P or P**T from the Left;
= 'R': apply Q, Q**T, P or P**T from the Right.

```

TRANS (input)

```

= 'N': No transpose, apply Q or P;
= 'T': Transpose, apply Q**T or P**T.

```

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) If VECT = 'Q', the number of columns in the original matrix reduced by SGEBRD. If VECT = 'P', the number of rows in the original matrix reduced by SGEBRD. $K \geq 0$.

A (input) (LDA,min(nq,K)) if VECT = 'Q' (LDA,nq) if VECT = 'P' The vectors which define the elementary reflectors H(i) and G(i), whose products determine the matrices Q and P, as returned by SGEBRD.

LDA (input)
The leading dimension of the array A. If VECT = 'Q', $LDA \geq \max(1,nq)$; if VECT = 'P', $LDA \geq \max(1,\min(nq,K))$.

TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector H(i) or G(i) which determines Q or P, as returned by SGEBRD in the array argument TAUQ or TAUP.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by $Q*C$ or $Q**T*C$ or $C*Q**T$ or $C*Q$ or $P*C$ or $P**T*C$ or $C*P$ or $C**T$.

LDC (input)
The leading dimension of the array C. $LDC \geq \max(1,M)$.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. If SIDE = 'L', $LWORK \geq \max(1,N)$; if SIDE = 'R', $LWORK \geq \max(1,M)$. For optimum performance $LWORK \geq N*NB$ if SIDE = 'L', and $LWORK \geq M*NB$ if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dormhr - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE DORMHR(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C, LDC,  
    WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, ILO, IHI, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DORMHR_64(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C,  
    LDC, WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, ILO, IHI, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMHR(SIDE, [TRANS], [M], [N], ILO, IHI, A, [LDA], TAU, C,  
    [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, ILO, IHI, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMHR_64(SIDE, [TRANS], [M], [N], ILO, IHI, A, [LDA], TAU,  
    C, [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, ILO, IHI, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dormhr(char side, char trans, int m, int n, int ilo,
```

```

int ihi, double *a, int lda, double *tau, double
*c, int ldc, int *info);

void dormhr_64(char side, char trans, long m, long n, long
ilo, long ihi, double *a, long lda, double *tau,
double *c, long ldc, long *info);

```

PURPOSE

dormhr overwrites the general real M-by-N matrix C with
TRANS = 'T': $Q^{*T} * C$ $C * Q^{*T}$

where Q is a real orthogonal matrix of order nq, with nq = m
if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
product of IHI-ILO elementary reflectors, as returned by
SGEHRD:

$Q = H(ilo) H(ilo+1) . . . H(ihi-1).$

ARGUMENTS

SIDE (input)
= 'L': apply Q or Q**T from the Left;
= 'R': apply Q or Q**T from the Right.

TRANS (input)
= 'N': No transpose, apply Q;
= 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

ILO (input)
ILO and IHI must have the same values as in the
previous call of SGEHRD. Q is equal to the unit
matrix except in the submatrix
Q(ilo+1:ihi,ilo+1:ihi). If SIDE = 'L', then 1 <=
ILO <= IHI <= M, if M > 0, and ILO = 1 and IHI =
0, if M = 0; if SIDE = 'R', then 1 <= ILO <= IHI
<= N, if N > 0, and ILO = 1 and IHI = 0, if N = 0.

IHI (input)
See the description of ILO.

A (input) (LDA,M) if SIDE = 'L' (LDA,N) if SIDE = 'R' The
vectors which define the elementary reflectors, as
returned by SGEHRD.

LDA (input)
The leading dimension of the array A. LDA >=
max(1,M) if SIDE = 'L'; LDA >= max(1,N) if SIDE =
'R'.

TAU (input)
(M-1) if SIDE = 'L' (N-1) if SIDE = 'R' TAU(i)
must contain the scalar factor of the elementary
reflector H(i), as returned by SGEHRD.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is
overwritten by Q*C or Q**T*C or C*Q**T or C*Q.

LDC (input)
The leading dimension of the array C. LDC >=
max(1,M).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal
LWORK.

LWORK (input)
The dimension of the array WORK. If SIDE = 'L',
LWORK >= max(1,N); if SIDE = 'R', LWORK >=
max(1,M). For optimum performance LWORK >= N*NB
if SIDE = 'L', and LWORK >= M*NB if SIDE = 'R',
where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed;
the routine only calculates the optimal size of
the WORK array, returns this value as the first
entry of the WORK array, and no error message
related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

dormlq - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE DORMLQ(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DORMLQ_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMLQ(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMLQ_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dormlq(char side, char trans, int m, int n, int k, dou-
```

```

        ble *a, int lda, double *tau, double *c, int ldc,
        int *info);

void dormlq_64(char side, char trans, long m, long n, long
        k, double *a, long lda, double *tau, double *c,
        long ldc, long *info);

```

PURPOSE

dormlq overwrites the general real M-by-N matrix C with
TRANS = 'T': $Q^{*T} * C$ $C * Q^{*T}$

where Q is a real orthogonal matrix defined as the product
of k elementary reflectors

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGELQF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*T} from the Left;
= 'R': apply Q or Q^{*T} from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'T': Transpose, apply Q^{*T} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
if SIDE = 'R', $N \geq K \geq 0$.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
i-th row must contain the vector which defines the
elementary reflector H(i), for $i = 1, 2, \dots, k$, as
returned by SGELQF in the first k rows of its
array argument A. A is modified by the routine
but restored on exit.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $\max(1, K)$.

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by SGELQF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dormql - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE DORMQL(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DORMQL_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMQL(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMQL_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dormql(char side, char trans, int m, int n, int k, dou-
```

```

        ble *a, int lda, double *tau, double *c, int ldc,
        int *info);

void dormql_64(char side, char trans, long m, long n, long
        k, double *a, long lda, double *tau, double *c,
        long ldc, long *info);

```

PURPOSE

dormql overwrites the general real M-by-N matrix C with
 TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix defined as the product
 of k elementary reflectors

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGEQLF. Q is of order M if SIDE = 'L' and of
 order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
 = 'R': apply Q or Q**T from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
 = 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
 defines the matrix Q. If SIDE = 'L', M >= K >= 0;
 if SIDE = 'R', N >= K >= 0.

A (input) The i-th column must contain the vector which
 defines the elementary reflector H(i), for i =
 1,2,...,k, as returned by SGEQLF in the last k
 columns of its array argument A. A is modified by
 the routine but restored on exit.

LDA (input)

The leading dimension of the array A. If SIDE =
 'L', LDA >= max(1,M); if SIDE = 'R', LDA >=
 max(1,N).

TAU (input)

TAU(i) must contain the scalar factor of the ele-
 mentary reflector H(i), as returned by SGEQLF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dormqr - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE DORMQR(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DORMQR_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMQR(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMQR_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dormqr(char side, char trans, int m, int n, int k, dou-
```

```

        ble *a, int lda, double *tau, double *c, int ldc,
        int *info);

void dormqr_64(char side, char trans, long m, long n, long
        k, double *a, long lda, double *tau, double *c,
        long ldc, long *info);

```

PURPOSE

dormqr overwrites the general real M-by-N matrix C with
 TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix defined as the product
 of k elementary reflectors

$$Q = H(1) H(2) . . . H(k)$$

as returned by SGEQRF. Q is of order M if SIDE = 'L' and of
 order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
 = 'R': apply Q or Q**T from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
 = 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
 defines the matrix Q. If SIDE = 'L', M >= K >= 0;
 if SIDE = 'R', N >= K >= 0.

A (input) The i-th column must contain the vector which
 defines the elementary reflector H(i), for i =
 1,2,...,k, as returned by SGEQRF in the first k
 columns of its array argument A. A is modified by
 the routine but restored on exit.

LDA (input)

The leading dimension of the array A. If SIDE =
 'L', LDA >= max(1,M); if SIDE = 'R', LDA >=
 max(1,N).

TAU (input)

TAU(i) must contain the scalar factor of the ele-
 mentary reflector H(i), as returned by SGEQRF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dormrq - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE DORMRQ(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DORMRQ_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMRQ(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A, C
```

```
SUBROUTINE ORMRQ_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dormrq(char side, char trans, int m, int n, int k, dou-
```

```

        ble *a, int lda, double *tau, double *c, int ldc,
        int *info);

void dormrq_64(char side, char trans, long m, long n, long
        k, double *a, long lda, double *tau, double *c,
        long ldc, long *info);

```

PURPOSE

dormrq overwrites the general real M-by-N matrix C with
 TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix defined as the product
 of k elementary reflectors

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGERQF. Q is of order M if SIDE = 'L' and of
 order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
 = 'R': apply Q or Q**T from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
 = 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
 defines the matrix Q. If SIDE = 'L', M >= K >= 0;
 if SIDE = 'R', N >= K >= 0.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
 i-th row must contain the vector which defines the
 elementary reflector H(i), for i = 1,2,...,k, as
 returned by SGERQF in the last k rows of its array
 argument A. A is modified by the routine but
 restored on exit.

LDA (input)

The leading dimension of the array A. LDA >=
 max(1,K).

TAU (input)

TAU(i) must contain the scalar factor of the ele-
 mentary reflector H(i), as returned by SGERQF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dormrz - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE DORMRZ(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, L, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DORMRZ_64(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, L, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMRZ(SIDE, TRANS, [M], [N], K, L, A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, L, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A, C
```

```
SUBROUTINE ORMRZ_64(SIDE, TRANS, [M], [N], K, L, A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, L, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dormrz(char side, char trans, int m, int n, int k, int
            l, double *a, int lda, double *tau, double *c, int
            ldc, int *info);
```

```
void dormrz_64(char side, char trans, long m, long n, long
               k, long l, double *a, long lda, double *tau, dou-
               ble *c, long ldc, long *info);
```

PURPOSE

dormrz overwrites the general real M-by-N matrix C with
 TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix defined as the product
 of k elementary reflectors

$$Q = H(1) H(2) . . . H(k)$$

as returned by STZRZF. Q is of order M if SIDE = 'L' and of
 order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
 = 'R': apply Q or Q**T from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
 = 'T': Transpose, apply Q**T.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
 defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
 if SIDE = 'R', $N \geq K \geq 0$.

L (input) The number of columns of the matrix A containing
 the meaningful part of the Householder reflectors.
 If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L$
 ≥ 0 .

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
 i-th row must contain the vector which defines the
 elementary reflector H(i), for $i = 1, 2, \dots, k$, as
 returned by STZRZF in the last k rows of its array
 argument A. A is modified by the routine but
 restored on exit.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $\max(1, K)$.

TAU (input)
 TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by STZRZF.

C (input/output)
 On entry, the M-by-N matrix C. On exit, C is overwritten by Q*C or Q**H*C or C*Q**H or C*Q.

LDC (input)
 The leading dimension of the array C. LDC >= max(1,M).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. If SIDE = 'L', LWORK >= max(1,N); if SIDE = 'R', LWORK >= max(1,M). For optimum performance LWORK >= N*NB if SIDE = 'L', and LWORK >= M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by
 A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

dormtr - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE DORMTR(SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
INTEGER M, N, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE DORMTR_64(SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
INTEGER*8 M, N, LDA, LDC, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMTR(SIDE, UPLO, [TRANS], [M], [N], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
INTEGER :: M, N, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMTR_64(SIDE, UPLO, [TRANS], [M], [N], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
INTEGER(8) :: M, N, LDA, LDC, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dormtr(char side, char uplo, char trans, int m, int n,
```

```

double *a, int lda, double *tau, double *c, int
ldc, int *info);

void dormtr_64(char side, char uplo, char trans, long m,
long n, double *a, long lda, double *tau, double
*c, long ldc, long *info);

```

PURPOSE

dormtr overwrites the general real M-by-N matrix C with
TRANS = 'T': $Q^{*T} * C$ $C * Q^{*T}$

where Q is a real orthogonal matrix of order nq, with nq = m
if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
product of nq-1 elementary reflectors, as returned by
SSYTRD:

if UPLO = 'U', Q = H(nq-1) . . . H(2) H(1);

if UPLO = 'L', Q = H(1) H(2) . . . H(nq-1).

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
= 'R': apply Q or Q**T from the Right.

UPLO (input)

= 'U': Upper triangle of A contains elementary
reflectors from SSYTRD; = 'L': Lower triangle of A
contains elementary reflectors from SSYTRD.

TRANS (input)

= 'N': No transpose, apply Q;
= 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

A (input) (LDA,M) if SIDE = 'L' (LDA,N) if SIDE = 'R' The
vectors which define the elementary reflectors, as
returned by SSYTRD.

LDA (input)

The leading dimension of the array A. LDA >=
max(1,M) if SIDE = 'L'; LDA >= max(1,N) if SIDE =
'R'.

TAU (input)

(M-1) if SIDE = 'L' (N-1) if SIDE = 'R' TAU(i)
must contain the scalar factor of the elementary
reflector H(i), as returned by SSYTRD.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. $LDC \geq \max(1, M)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LWORK$.

LWORK (input)

The dimension of the array WORK. If $SIDE = 'L'$, $LWORK \geq \max(1, N)$; if $SIDE = 'R'$, $LWORK \geq \max(1, M)$. For optimum performance $LWORK \geq N * NB$ if $SIDE = 'L'$, and $LWORK \geq M * NB$ if $SIDE = 'R'$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to $LWORK$ is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if $INFO = -i$, the i-th argument had an illegal value

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NAME

dpbcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite band matrix using the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ computed by DPBTRF

SYNOPSIS

```
SUBROUTINE DPBCON(UPLO, N, KD, A, LDA, ANORM, RCOND, WORK, WORK2,
                 INFO)
```

```
CHARACTER * 1 UPLO
INTEGER N, KD, LDA, INFO
INTEGER WORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DPBCON_64(UPLO, N, KD, A, LDA, ANORM, RCOND, WORK,
                    WORK2, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER*8 N, KD, LDA, INFO
INTEGER*8 WORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PBCON(UPLO, [N], KD, A, [LDA], ANORM, RCOND, [WORK],
                [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER :: N, KD, LDA, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:,:) :: A
```

```
SUBROUTINE PBCON_64(UPLO, [N], KD, A, [LDA], ANORM, RCOND, [WORK],
                   [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

INTEGER(8) :: N, KD, LDA, INFO
INTEGER(8), DIMENSION(:) :: WORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:,:) :: A
C INTERFACE
#include <sunperf.h>

void dpbcon(char uplo, int n, int kd, double *a, int lda,
            double anorm, double *rcond, int *info);

void dpbcon_64(char uplo, long n, long kd, double *a, long
               lda, double anorm, double *rcond, long *info);

```

PURPOSE

dpbcon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite band matrix using the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ computed by DPBTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangular factor stored in A;
 = 'L': Lower triangular factor stored in A.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ of the band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of U or L is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = U(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = L(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

LDA (input)
 The leading dimension of the array A. $LDA \geq KD+1$.

ANORM (input)
 The 1-norm (or infinity-norm) of the symmetric band matrix A.

RCOND (output)
 The reciprocal of the condition number of the

matrix A, computed as $RCOND = 1/(ANORM * AINVNM)$,
where AINVNM is an estimate of the 1-norm of
inv(A) computed in this routine.

WORK (workspace)
dimension(3*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

dpbequ - compute row and column scalings intended to equilibrate a symmetric positive definite band matrix A and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE DPBEQU(UPLO, N, KD, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, LDA, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION A(LDA,*), SCALE(*)
```

```
SUBROUTINE DPBEQU_64(UPLO, N, KD, A, LDA, SCALE, SCOND, AMAX,  
INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, LDA, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION A(LDA,*), SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE PBEQU(UPLO, [N], KD, A, [LDA], SCALE, SCOND, AMAX,  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, LDA, INFO  
REAL(8) :: SCOND, AMAX  
REAL(8), DIMENSION(:) :: SCALE  
REAL(8), DIMENSION(:,) :: A
```

```
SUBROUTINE PBEQU_64(UPLO, [N], KD, A, [LDA], SCALE, SCOND, AMAX,  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, LDA, INFO  
REAL(8) :: SCOND, AMAX  
REAL(8), DIMENSION(:) :: SCALE  
REAL(8), DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>

void dpbequ(char uplo, int n, int kd, double *a, int lda,
            double *scale, double *scond, double *amax, int
            *info);
void dpbequ_64(char uplo, long n, long kd, double *a, long
               lda, double *scale, double *scond, double *amax,
               long *info);
```

PURPOSE

dpbequ computes row and column scalings intended to equilibrate a symmetric positive definite band matrix A and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i) = 1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j) = S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

UPLO (input)
= 'U': Upper triangular of A is stored;
= 'L': Lower triangular of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input) The upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$.

LDA (input)
The leading dimension of the array A. $LDA \geq KD+1$.

SCALE (output)
If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)
If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

dpbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and banded, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE DPBRFS(UPLO, N, KD, NRHS, A, LDA, AF, LDAF, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER WORK2(*)  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DPBRFS_64(UPLO, N, KD, NRHS, A, LDA, AF, LDAF, B, LDB,  
  X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PBRFS(UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF], B,  
  [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK  
REAL(8), DIMENSION(:,:) :: A, AF, B, X
```

```
SUBROUTINE PBRFS_64(UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF],  
  B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
```

```

INTEGER(8), DIMENSION(:) :: WORK2
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, AF, B, X

```

C INTERFACE

```

#include <sunperf.h>
void dpbrfs(char uplo, int n, int kd, int nrhs, double *a,
            int lda, double *af, int ldaf, double *b, int ldb,
            double *x, int ldx, double *ferr, double *berr,
            int *info);

void dpbrfs_64(char uplo, long n, long kd, long nrhs, double
              *a, long lda, double *af, long ldaf, double *b,
              long ldb, double *x, long ldx, double *ferr, dou-
              ble *berr, long *info);

```

PURPOSE

dpbrfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and banded, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

LDA (input)
 The leading dimension of the array A. $LDA \geq KD+1$.

AF (input)
 The triangular factor U or L from the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ of the band matrix A as computed by DPBTRF, in the same storage format as A (see A).

LDAF (input)
 The leading dimension of the array AF. LDAF \geq KD+1.

B (input) The right hand side matrix B.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
 On entry, the solution matrix X, as computed by DPBTRS. On exit, the improved solution matrix X.

LDX (input)
 The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(3*N)

WORK2 (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dpbstf - compute a split Cholesky factorization of a real symmetric positive definite band matrix A

SYNOPSIS

```
SUBROUTINE DPBSTF(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, LDAB, INFO  
DOUBLE PRECISION AB(LDAB,*)
```

```
SUBROUTINE DPBSTF_64(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, LDAB, INFO  
DOUBLE PRECISION AB(LDAB,*)
```

F95 INTERFACE

```
SUBROUTINE PBSTF(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, LDAB, INFO  
REAL(8), DIMENSION(:, :) :: AB
```

```
SUBROUTINE PBSTF_64(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, LDAB, INFO  
REAL(8), DIMENSION(:, :) :: AB
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpbstf(char uplo, int n, int kd, double *ab, int ldab,  
            int *info);
```

```
void dpbstf_64(char uplo, long n, long kd, double *ab, long  
               ldab, long *info);
```

PURPOSE

dpbstf computes a split Cholesky factorization of a real symmetric positive definite band matrix A.

This routine is designed to be used in conjunction with SSBGST.

The factorization has the form $A = S^*T^*S$ where S is a band matrix of the same bandwidth as A and the following structure:

$$S = \begin{pmatrix} U & \\ & (M \ L) \end{pmatrix}$$

where U is upper triangular of order $m = (n+kd)/2$, and L is lower triangular of order $n-m$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $kd+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if
UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$
for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the factor S from the split Cholesky factorization $A = S^*T^*S$. See Further Details.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq kd+1$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the factorization could not be completed, because the updated element $a(i, i)$ was negative; the matrix A is not positive definite.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 7$, $KD = 2$:

```
S = ( s11  s12  s13           )
     (      s22  s23  s24       )
     (           s33  s34       )
     (               s44         )
     (                   s53  s54  s55   )
     (                       s64  s65  s66   )
     (                           s75  s76  s77 )
```

If $UPLO = 'U'$, the array AB holds:

```
on entry:                                on exit:

*   *  a13  a24  a35  a46  a57  *   *   s13  s24  s53
s64  s75
*   a12  a23  a34  a45  a56  a67  *   s12  s23  s34  s54
s65  s76  a11  a22  a33  a44  a55  a66  a77  s11  s22  s33
s44  s55  s66  s77
```

If $UPLO = 'L'$, the array AB holds:

```
on entry:                                on exit:

a11  a22  a33  a44  a55  a66  a77  s11  s22  s33  s44  s55
s66  s77  a21  a32  a43  a54  a65  a76  *   s12  s23  s34
s54  s65  s76  * a31  a42  a53  a64  a64  *   *   s13
s24  s53  s64  s75  *   *
```

Array elements marked * are not used by the routine.

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NAME

dpbsv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DPBSV(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DPBSV_64(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PBSV(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE PBSV_64(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpbsv(char uplo, int n, int kd, int nrhs, double *a,  
int lda, double *b, int ldb, int *info);
```

```
void dpbsv_64(char uplo, long n, long kd, long nrhs, double
```

```
*a, long lda, double *b, long ldb, long *info);
```

PURPOSE

dpbsv computes the solution to a real system of linear equations

$A * X = B$, where A is an N -by- N symmetric positive definite band matrix and X and B are N -by- $NRHS$ matrices.

The Cholesky decomposition is used to factor A as

$A = U^{**T} * U$, if $UPLO = 'U'$, or

$A = L * L^{**T}$, if $UPLO = 'L'$,

where U is an upper triangular band matrix, and L is a lower triangular band matrix, with the same number of superdiagonals or subdiagonals as A . The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A . $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if $UPLO = 'U'$, or the number of subdiagonals if $UPLO = 'L'$. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A , stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if $UPLO = 'U'$, $A(KD+1+i-j,j) = A(i,j)$ for $\max(1,j-KD) \leq i \leq j$; if $UPLO = 'L'$, $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(N,j+KD)$. See below for further details.

On exit, if $INFO = 0$, the triangular factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ of the band matrix A , in the same storage format as A .

LDA (input)

The leading dimension of the array A . $LDA \geq KD+1$.

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B . On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 6$, $KD = 2$, and $UPLO = 'U'$:

On entry:						On exit:					
* *	a13	a24	a35	a46		* *	u13	u24	u35		
u46	* a12	a23	a34	a45	a56	* u12	u23	u34	u45		
u56	a11	a22	a33	a44	a55	a66	u11	u22	u33	u44	u55
u66											

Similarly, if $UPLO = 'L'$ the format of A is as follows:

On entry:						On exit:					
	a11	a22	a33	a44	a55	a66	l11	l22	l33	l44	l55
l66	a21	a32	a43	a54	a65	*	l21	l32	l43	l54	l65
*	a31	a42	a53	a64	*	*	l31	l42	l53	l64	*
*											

Array elements marked * are not used by the routine.

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NAME

dpbsvx - use the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DPBSVX(FACT, UPLO, N, KD, NRHS, A, LDA, AF, LDAF,
    EQUED, S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2,
    INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
INTEGER N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), S(*), B(LDB,*),
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DPBSVX_64(FACT, UPLO, N, KD, NRHS, A, LDA, AF, LDAF,
    EQUED, S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2,
    INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
INTEGER*8 N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), S(*), B(LDB,*),
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PBSVX(FACT, UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF],
    EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],
    [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
INTEGER :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK
```

```

REAL(8), DIMENSION(:,:) :: A, AF, B, X

SUBROUTINE PBSVX_64(FACT, UPLO, [N], KD, [NRHS], A, [LDA], AF,
  [LDAF], EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR,
  [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, UPLO, EQUED
INTEGER(8) :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK
REAL(8), DIMENSION(:,:) :: A, AF, B, X

```

C INTERFACE

```

#include <sunperf.h>

void dpbsvx(char fact, char uplo, int n, int kd, int nrhs,
  double *a, int lda, double *af, int ldaf, char
  equed, double *s, double *b, int ldb, double *x,
  int ldx, double *rcond, double *ferr, double
  *berr, int *info);

void dpbsvx_64(char fact, char uplo, long n, long kd, long
  nrhs, double *a, long lda, double *af, long ldaf,
  char equed, double *s, double *b, long ldb, double
  *x, long ldx, double *rcond, double *ferr, double
  *berr, long *info);

```

PURPOSE

dpbsvx uses the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ to compute the solution to a real system of linear equations

$A * X = B$, where A is an N -by- N symmetric positive definite band matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$) as

$$A = U^*T^*U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L^*T, \text{ if } UPLO = 'L',$$

where U is an upper triangular band matrix, and L is a lower

triangular band matrix.

3. If the leading i -by- i principal minor is not positive definite, then the routine returns with `INFO = i`. Otherwise, the factored form of A is used to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than machine precision, `INFO = N+1` is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
4. The system of equations is solved for X using the factored form of A .
5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.
6. If equilibration was used, the matrix X is premultiplied by `diag(S)` so that it solves the original system before equilibration.

ARGUMENTS

`FACT` (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, `AF` contains the factored form of A . If `EQUED = 'Y'`, the matrix A has been equilibrated with scaling factors given by S . A and `AF` will not be modified. = 'N': The matrix A will be copied to `AF` and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to `AF` and factored.

`UPLO` (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

`N` (input) The number of linear equations, i.e., the order of the matrix A . $N \geq 0$.

`KD` (input)

The number of superdiagonals of the matrix A if `UPLO = 'U'`, or the number of subdiagonals if `UPLO = 'L'`. $KD \geq 0$.

`NRHS` (input)

The number of right-hand sides, i.e., the number of columns of the matrices B and X . `NRHS` ≥ 0 .

`A` (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first KD+1 rows of the array, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix $\text{diag}(S)*A*\text{diag}(S)$. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(KD+1+i-j,j) = A(i,j)$ for $\max(1,j-KD) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(N,j+KD)$. See below for further details.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S)*A*\text{diag}(S)$.

LDA (input)

The leading dimension of the array A. LDA \geq KD+1.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U**T*U$ or $A = L*L**T$ of the band matrix A, in the same storage format as A (see A). If EQUED = 'Y', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**T*U$ or $A = L*L**T$.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**T*U$ or $A = L*L**T$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF \geq KD+1.

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

X (output)
 If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is inv(diag(S))*X.

LDX (input)
 The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)
 The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(3*N)

WORK2 (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, and i is
 <= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is non-singular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would

suggest.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 6$, $KD = 2$, and $UPLO = 'U'$:

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13
    a22 a23 a24
        a33 a34 a35
            a44 a45 a46
                a55 a56
(aij=conjg(aji))          a66
```

Band storage of the upper triangle of A:

```
*   *   a13 a24 a35 a46
*   a12 a23 a34 a45 a56
a11 a22 a33 a44 a55 a66
```

Similarly, if $UPLO = 'L'$ the format of A is as follows:

```
a11 a22 a33 a44 a55 a66
a21 a32 a43 a54 a65 *
a31 a42 a53 a64 * *
```

Array elements marked * are not used by the routine.

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NAME

dpbtf2 - compute the Cholesky factorization of a real symmetric positive definite band matrix A

SYNOPSIS

```
SUBROUTINE DPBTF2(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, LDAB, INFO  
DOUBLE PRECISION AB(LDAB,*)
```

```
SUBROUTINE DPBTF2_64(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, LDAB, INFO  
DOUBLE PRECISION AB(LDAB,*)
```

F95 INTERFACE

```
SUBROUTINE PBTf2(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, LDAB, INFO  
REAL(8), DIMENSION(:, :) :: AB
```

```
SUBROUTINE PBTf2_64(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, LDAB, INFO  
REAL(8), DIMENSION(:, :) :: AB
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpbtf2(char uplo, int n, int kd, double *ab, int ldab,  
            int *info);
```

```
void dpbtf2_64(char uplo, long n, long kd, double *ab, long  
               ldab, long *info);
```

PURPOSE

dpbtf2 computes the Cholesky factorization of a real symmetric positive definite band matrix A.

The factorization has the form

$A = U' * U$, if UPLO = 'U', or

$A = L * L'$, if UPLO = 'L',

where U is an upper triangular matrix, U' is the transpose of U, and L is lower triangular.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored:

= 'U': Upper triangular

= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of super-diagonals of the matrix A if UPLO = 'U', or the number of sub-diagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U' * U$ or $A = L * L'$ of the band matrix A, in the same storage format as A.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq KD+1$.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, the leading minor of order k is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 6$, $KD = 2$, and $UPLO = 'U'$:

On entry:	On exit:
* * a13 a24 a35 a46	* * u13 u24 u35
u46	
* a12 a23 a34 a45 a56	* u12 u23 u34 u45
u56	
a11 a22 a33 a44 a55 a66	u11 u22 u33 u44 u55
u66	

Similarly, if $UPLO = 'L'$ the format of A is as follows:

On entry:	On exit:
a11 a22 a33 a44 a55 a66	l11 l22 l33 l44 l55
l66	
a21 a32 a43 a54 a65 *	l21 l32 l43 l54 l65
*	
a31 a42 a53 a64 * *	l31 l42 l53 l64 *
*	

Array elements marked * are not used by the routine.

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NAME

dpbtrf - compute the Cholesky factorization of a real symmetric positive definite band matrix A

SYNOPSIS

```
SUBROUTINE DPBTRF(UPLO, N, KD, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

```
SUBROUTINE DPBTRF_64(UPLO, N, KD, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE PBTRF(UPLO, [N], KD, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE PBTRF_64(UPLO, [N], KD, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpbtrf(char uplo, int n, int kd, double *a, int lda,  
            int *info);
```

```
void dpbtrf_64(char uplo, long n, long kd, double *a, long  
               lda, long *info);
```

PURPOSE

dpbtrf computes the Cholesky factorization of a real symmetric positive definite band matrix A.

The factorization has the form

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ of the band matrix A, in the same storage format as A.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The band storage scheme is illustrated by the following

example, when $N = 6$, $KD = 2$, and $UPLO = 'U'$:

On entry:	On exit:
* * a13 a24 a35 a46	* * u13 u24 u35
u46	
* a12 a23 a34 a45 a56	* u12 u23 u34 u45
u56	
a11 a22 a33 a44 a55 a66	u11 u22 u33 u44 u55
u66	

Similarly, if $UPLO = 'L'$ the format of A is as follows:

On entry:	On exit:
a11 a22 a33 a44 a55 a66	l11 l22 l33 l44 l55
l66	
a21 a32 a43 a54 a65 *	l21 l32 l43 l54 l65
*	
a31 a42 a53 a64 * *	l31 l42 l53 l64 *
*	

Array elements marked * are not used by the routine.

Contributed by

Peter Mayes and Giuseppe Radicati, IBM ECSEC, Rome, March 23, 1989

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NAME

dpbtrs - solve a system of linear equations $A \cdot X = B$ with a symmetric positive definite band matrix A using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by DPBTRF

SYNOPSIS

```
SUBROUTINE DPBTRS(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DPBTRS_64(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PBTRS(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE PBTRS_64(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpbtrs(char uplo, int n, int kd, int nrhs, double *a,  
int lda, double *b, int ldb, int *info);
```

```
void dpbtrs_64(char uplo, long n, long kd, long nrhs, double  
*a, long lda, double *b, long ldb, long *info);
```

PURPOSE

dpbtrs solves a system of linear equations $A \cdot X = B$ with a symmetric positive definite band matrix A using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by DPBTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular factor stored in A;
= 'L': Lower triangular factor stored in A.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number
of columns of the matrix B. $NRHS \geq 0$.

A (input) The triangular factor U or L from the Cholesky
factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ of the band
matrix A, stored in the first $KD+1$ rows of the
array. The j-th column of U or L is stored in the
j-th column of the array A as follows: if UPLO
= 'U', $A(kd+1+i-j, j) = U(i, j)$ for $\max(1, j-
kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = L(i, j)$
for $j \leq i \leq \min(n, j+kd)$.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $KD+1$.

B (input/output)

On entry, the right hand side matrix B. On exit,
the solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq$
 $\max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

dpocon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite matrix using the Cholesky factorization $A = U^*U$ or $A = L^*L$ computed by DPOTRF

SYNOPSIS

```
SUBROUTINE DPOCON(UPLO, N, A, LDA, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER N, LDA, INFO
INTEGER WORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DPOCON_64(UPLO, N, A, LDA, ANORM, RCOND, WORK, WORK2,
INFO)
```

```
CHARACTER * 1 UPLO
INTEGER*8 N, LDA, INFO
INTEGER*8 WORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE POCON(UPLO, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER :: N, LDA, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE POCON_64(UPLO, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER(8) :: N, LDA, INFO
```

```

INTEGER(8), DIMENSION(:) :: WORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A

```

C INTERFACE

```

#include <sunperf.h>
void dpocon(char uplo, int n, double *a, int lda, double
            anorm, double *rcond, int *info);

void dpocon_64(char uplo, long n, double *a, long lda, dou-
              ble anorm, double *rcond, long *info);

```

PURPOSE

dpocon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite matrix using the Cholesky factorization $A = U^*T^*U$ or $A = L*L^*T$ computed by DPOTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U^*T^*U$ or $A = L*L^*T$, as computed by DPOTRF.

LDA (input)
 The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

ANORM (input)
 The 1-norm (or infinity-norm) of the symmetric matrix A.

RCOND (output)
 The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)
 dimension(3*N)

WORK2 (workspace)
 dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dpoequ - compute row and column scalings intended to equilibrate a symmetric positive definite matrix A and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE DPOEQU(N, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
INTEGER N, LDA, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION A(LDA,*), SCALE(*)
```

```
SUBROUTINE DPOEQU_64(N, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION A(LDA,*), SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE POEQU([N], A, [LDA], SCALE, SCOND, AMAX, [INFO])
```

```
INTEGER :: N, LDA, INFO  
REAL(8) :: SCOND, AMAX  
REAL(8), DIMENSION(:) :: SCALE  
REAL(8), DIMENSION(:,:) :: A
```

```
SUBROUTINE POEQU_64([N], A, [LDA], SCALE, SCOND, AMAX, [INFO])
```

```
INTEGER(8) :: N, LDA, INFO  
REAL(8) :: SCOND, AMAX  
REAL(8), DIMENSION(:) :: SCALE  
REAL(8), DIMENSION(:,:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpoequ(int n, double *a, int lda, double *scale, double  
           *scond, double *amax, int *info);
```

```
void dpoequ_64(long n, double *a, long lda, double *scale,
```

```
double *scond, double *amax, long *info);
```

PURPOSE

dpoequ computes row and column scalings intended to equilibrate a symmetric positive definite matrix A and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i) = 1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j) = S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

A (input) The N-by-N symmetric positive definite matrix whose scaling factors are to be computed. Only the diagonal elements of A are referenced.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

SCALE (output)
If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)
If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)
Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

dporfcs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite,

SYNOPSIS

```
SUBROUTINE DPORFCS(UPLO, N, NRHS, A, LDA, AF, LDAF, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER WORK2(*)  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DPORFCS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PORFCS(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], B, [LDB],  
    X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK  
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

```
SUBROUTINE PORFCS_64(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], B, [LDB],  
    X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2
```

```
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
void dporfs(char uplo, int n, int nrhs, double *a, int lda,
            double *af, int ldaf, double *b, int ldb, double
            *x, int ldx, double *ferr, double *berr, int
            *info);

void dporfs_64(char uplo, long n, long nrhs, double *a, long
              lda, double *af, long ldaf, double *b, long ldb,
              double *x, long ldx, double *ferr, double *berr,
              long *info);
```

PURPOSE

dporfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)

The triangular factor U or L from the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$, as computed by DPOTRF.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by DPOTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
dimension(3*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dposv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DPOSV(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DPOSV_64(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE POSV(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE POSV_64(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dposv(char uplo, int n, int nrhs, double *a, int lda,  
          double *b, int ldb, int *info);
```

```
void dposv_64(char uplo, long n, long nrhs, double *a, long  
             lda, double *b, long ldb, long *info);
```

PURPOSE

dposv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric positive definite matrix and X and B are N-by-NRHS matrices.

The Cholesky decomposition is used to factor A as

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is a lower triangular matrix. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{**T} * U$ or $A = L * L^{**T}$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i of

A is not positive definite, so the factorization could not be completed, and the solution has not been computed.

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NAME

dposvx - use the Cholesky factorization $A = U^*T*U$ or $A = L*L^*T$ to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DPOSVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, EQUED,  
  S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER WORK2(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), S(*), B(LDB,*),  
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DPOSVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, EQUED,  
  S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), S(*), B(LDB,*),  
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE POSVX(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],  
  EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],  
  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK  
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

```
SUBROUTINE POSVX_64(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],  
  EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],
```

```
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK  
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dposvx(char fact, char uplo, int n, int nrhs, double  
    *a, int lda, double *af, int ldaf, char equed,  
    double *s, double *b, int ldb, double *x, int ldx,  
    double *rcond, double *ferr, double *berr, int  
    *info);
```

```
void dposvx_64(char fact, char uplo, long n, long nrhs, dou-  
    ble *a, long lda, double *af, long ldaf, char  
    equed, double *s, double *b, long ldb, double *x,  
    long ldx, double *rcond, double *ferr, double  
    *berr, long *info);
```

PURPOSE

dposvx uses the Cholesky factorization $A = U^{*}T^{*}U$ or $A = L^{*}L^{*}T^{*}$ to compute the solution to a real system of linear equations

$A * X = B$, where A is an N -by- N symmetric positive definite matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A

is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$) as

$$A = U^{*}T^{*} U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L^{*}T^{*}, \text{ if } UPLO = 'L',$$

where U is an upper triangular matrix and L is a lower triangular matrix.

3. If the leading i -by- i principal minor is not positive definite,

then the routine returns with INFO = i. Otherwise, the factored form of A is used to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.
5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.
6. If equilibration was used, the matrix X is premultiplied by diag(S) so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF contains the factored form of A. If EQUED = 'Y', the matrix A has been equilibrated with scaling factors given by S. A and AF will not be modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)

On entry, the symmetric matrix A, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix diag(S)*A*diag(S). If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower tri-

angular part of the matrix A, and the strictly upper triangular part of A is not referenced. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S) * A * \text{diag}(S)$.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U * U^T$ or $A = L * L^T$, in the same storage format as A. If EQUED \neq 'N', then AF is the factored form of the equilibrated matrix $\text{diag}(S) * A * \text{diag}(S)$.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * U^T$ or $A = L * L^T$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * U^T$ or $A = L * L^T$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF \geq max(1,N).

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is $\text{inv}(\text{diag}(S)) * X$.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
 \leq N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is non-singular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

dpotf2 - compute the Cholesky factorization of a real symmetric positive definite matrix A

SYNOPSIS

```
SUBROUTINE DPOTF2(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

```
SUBROUTINE DPOTF2_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE POTF2(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE POTF2_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpotf2(char uplo, int n, double *a, int lda, int  
            *info);
```

```
void dpotf2_64(char uplo, long n, double *a, long lda, long  
              *info);
```

PURPOSE

dpotf2 computes the Cholesky factorization of a real symmetric positive definite matrix A.

The factorization has the form

$A = U^* U$, if UPLO = 'U', or

$A = L L^*$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored. = 'U': Upper triangular
= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading n by n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n by n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^*U$ or $A = L L^*$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value
> 0: if INFO = k, the leading minor of order k is not positive definite, and the factorization could not be completed.

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NAME

dpotrf - compute the Cholesky factorization of a real symmetric positive definite matrix A

SYNOPSIS

```
SUBROUTINE DPOTRF(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

```
SUBROUTINE DPOTRF_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE POTRF(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE POTRF_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpotrf(char uplo, int n, double *a, int lda, int  
            *info);
```

```
void dpotrf_64(char uplo, long n, double *a, long lda, long  
              *info);
```

PURPOSE

dpotrf computes the Cholesky factorization of a real symmetric positive definite matrix A.

The factorization has the form

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

This is the block version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

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dpotri - compute the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ computed by DPOTRF

SYNOPSIS

```
SUBROUTINE DPOTRI(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

```
SUBROUTINE DPOTRI_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE POTRI(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE POTRI_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpotri(char uplo, int n, double *a, int lda, int  
*info);
```

```
void dpotri_64(char uplo, long n, double *a, long lda, long  
*info);
```

PURPOSE

dpotri computes the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^*T*U$ or $A = L*L^*T$ computed by DPOTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular factor U or L from the Cholesky factorization $A = U^*T*U$ or $A = L*L^*T$, as computed by DPOTRF. On exit, the upper or lower triangle of the (symmetric) inverse of A, overwriting the input factor U or L.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, the (i,i) element of the factor U or L is zero, and the inverse could not be computed.

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NAME

dpotrs - solve a system of linear equations $A \cdot X = B$ with a symmetric positive definite matrix A using the Cholesky factorization $A = U \cdot U^T \cdot U$ or $A = L \cdot L^T \cdot T$ computed by DPOTRF

SYNOPSIS

```
SUBROUTINE DPOTRS(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DPOTRS_64(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE POTRS(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE POTRS_64(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpotrs(char uplo, int n, int nrhs, double *a, int lda,  
            double *b, int ldb, int *info);
```

```
void dpotrs_64(char uplo, long n, long nrhs, double *a, long  
               lda, double *b, long ldb, long *info);
```

PURPOSE

dpotrs solves a system of linear equations $A \cdot X = B$ with a symmetric positive definite matrix A using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by DPOTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$, as computed by DPOTRF.

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

B (input/output)

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

dppcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite packed matrix using the Cholesky factorization $A = U^*T*U$ or $A = L*L^*T$ computed by DPPTRF

SYNOPSIS

```
SUBROUTINE DPPCON(UPLO, N, A, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER N, INFO
INTEGER WORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION A(*), WORK(*)
```

```
SUBROUTINE DPPCON_64(UPLO, N, A, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER*8 N, INFO
INTEGER*8 WORK2(*)
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION A(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PPCON(UPLO, [N], A, ANORM, RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER :: N, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: A, WORK
```

```
SUBROUTINE PPCON_64(UPLO, [N], A, ANORM, RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER(8) :: N, INFO
INTEGER(8), DIMENSION(:) :: WORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: A, WORK
```

C INTERFACE

```
#include <sunperf.h>

void dppcon(char uplo, int n, double *a, double anorm, double *rcond, int *info);
void dppcon_64(char uplo, long n, double *a, double anorm, double *rcond, long *info);
```

PURPOSE

dppcon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite packed matrix using the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ computed by DPPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$
The triangular factor U or L from the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$, packed columnwise in a linear array. The j-th column of U or L is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = U(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = L(i,j)$ for $j \leq i \leq n$.

ANORM (input)
The 1-norm (or infinity-norm) of the symmetric matrix A.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

DOUBLE PRECISION array, WORK (workspace)
dimension $(3*N)$

WORK2 (workspace)
INTEGER array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dppequ - compute row and column scalings intended to equilibrate a symmetric positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE DPPEQU(UPLO, N, A, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION A(*), SCALE(*)
```

```
SUBROUTINE DPPEQU_64(UPLO, N, A, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION A(*), SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE PPEQU(UPLO, [N], A, SCALE, SCOND, AMAX, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
REAL(8) :: SCOND, AMAX  
REAL(8), DIMENSION(:) :: A, SCALE
```

```
SUBROUTINE PPEQU_64(UPLO, [N], A, SCALE, SCOND, AMAX, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
REAL(8) :: SCOND, AMAX  
REAL(8), DIMENSION(:) :: A, SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dppequ(char uplo, int n, double *a, double *scale, dou-
```

```

        ble *scond, double *amax, int *info);

void dppequ_64(char uplo, long n, double *a, double *scale,
               double *scond, double *amax, long *info);

```

PURPOSE

dppequ computes row and column scalings intended to equilibrate a symmetric positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i)=1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j)=S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$
 The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

SCALE (output) DOUBLE PRECISION array, dimension (N)
 If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)
 If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)
 Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

dpprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE DPPRFS(UPLO, N, NRHS, A, AF, B, LDB, X, LDX, FERR, BERR,  
                 WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, LDX, INFO  
INTEGER WORK2(*)  
DOUBLE PRECISION A(*), AF(*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE DPPRFS_64(UPLO, N, NRHS, A, AF, B, LDB, X, LDX, FERR,  
                    BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
DOUBLE PRECISION A(*), AF(*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PPRFS(UPLO, [N], [NRHS], A, AF, B, [LDB], X, [LDX], FERR,  
                BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL(8), DIMENSION(:) :: A, AF, FERR, BERR, WORK  
REAL(8), DIMENSION(:, :) :: B, X
```

```
SUBROUTINE PPRFS_64(UPLO, [N], [NRHS], A, AF, B, [LDB], X, [LDX], FERR,  
                   BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

```

INTEGER(8), DIMENSION(:) :: WORK2
REAL(8), DIMENSION(:) :: A, AF, FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: B, X

```

C INTERFACE

```

#include <sunperf.h>
void dpprfs(char uplo, int n, int nrhs, double *a, double
    *af, double *b, int ldb, double *x, int ldx, dou-
    ble *ferr, double *berr, int *info);

void dpprfs_64(char uplo, long n, long nrhs, double *a, dou-
    ble *af, double *b, long ldb, double *x, long ldx,
    double *ferr, double *berr, long *info);

```

PURPOSE

dpprfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$
 The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i, j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i, j)$ for $j \leq i \leq n$.

AF (input) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$
 The triangular factor U or L from the Cholesky factorization $A = U**T*U$ or $A = L*L**T$, as computed by DPPTRF/ZPPTRF, packed columnwise in a linear array in the same format as A (see A).

B (input) DOUBLE PRECISION array, dimension $(LDB, NRHS)$
 The right hand side matrix B.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (input/output) DOUBLE PRECISION array, dimension $(LDX, NRHS)$
 On entry, the solution matrix X, as computed by

DPPTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output) DOUBLE PRECISION array, dimension (NRHS)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) DOUBLE PRECISION array, dimension (NRHS)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

DOUBLE PRECISION array, dimension(3*N)

WORK2 (workspace)

INTEGER array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dppsv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DPPSV(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, INFO  
DOUBLE PRECISION A(*), B(LDB,*)
```

```
SUBROUTINE DPPSV_64(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, INFO  
DOUBLE PRECISION A(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PPSV(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: A  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE PPSV_64(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: A  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dppsv(char uplo, int n, int nrhs, double *a, double *b,  
           int ldb, int *info);
```

```
void dppsv_64(char uplo, long n, long nrhs, double *a, double *b, long ldb, long *info);
```

PURPOSE

dppsv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric positive definite matrix stored in packed format and X and B are N-by-NRHS matrices.

The Cholesky decomposition is used to factor A as

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is a lower triangular matrix. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{**T} * U$ or $A = L * L^{**T}$, in the same storage format as A.

B (input/output) DOUBLE PRECISION array, dimension (LDB,NRHS)

On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-

gal value
> 0: if INFO = i, the leading minor of order i of
A is not positive definite, so the factorization
could not be completed, and the solution has not
been computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following
example when $N = 4$, $UPLO = 'U'$:

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34   (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

```
A = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

dppsvx - use the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T^*$ to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DPPSVX(FACT, UPLO, N, NRHS, A, AF, EQUED, S, B, LDB,
  X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(*), AF(*), S(*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DPPSVX_64(FACT, UPLO, N, NRHS, A, AF, EQUED, S, B,
  LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(*), AF(*), S(*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PPSVX(FACT, UPLO, [N], [NRHS], A, AF, EQUED, S, B,
  [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: A, AF, S, FERR, BERR, WORK
REAL(8), DIMENSION(:,:) :: B, X
```

```
SUBROUTINE PPSVX_64(FACT, UPLO, [N], [NRHS], A, AF, EQUED, S, B,
```

[LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: A, AF, S, FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dppsvx(char fact, char uplo, int n, int nrhs, double
    *a, double *af, char equed, double *s, double *b,
    int ldb, double *x, int ldx, double *rcond, double
    *ferr, double *berr, int *info);
```

```
void dppsvx_64(char fact, char uplo, long n, long nrhs, dou-
    ble *a, double *af, char equed, double *s, double
    *b, long ldb, double *x, long ldx, double *rcond,
    double *ferr, double *berr, long *info);
```

PURPOSE

dppsvx uses the Cholesky factorization $A = U^*T*U$ or $A = L*L^*T$ to compute the solution to a real system of linear equations

$A * X = B$, where A is an N -by- N symmetric positive definite matrix stored in packed format and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$) as

$$A = U^*T*U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L^*T, \text{ if } UPLO = 'L',$$

where U is an upper triangular matrix and L is a lower triangular matrix.

3. If the leading i -by- i principal minor is not positive definite,

then the routine returns with $INFO = i$. Otherwise, the factored

form of A is used to estimate the condition number of the matrix

A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.

5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

6. If equilibration was used, the matrix X is premultiplied by $\text{diag}(S)$ so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF contains the factored form of A. If EQUED = 'Y', the matrix A has been equilibrated with scaling factors given by S. A and AF will not be modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $\text{NRHS} \geq 0$.

A (input/output) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix $\text{diag}(S)*A*\text{diag}(S)$. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED =

'N' on exit.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S) * A * \text{diag}(S)$.

($N * (N + 1) / 2$)

AF (input or output) DOUBLE PRECISION array, dimension

If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U * U$ or $A = L * L'$, in the same storage format as A. If EQUED = 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * U$ or $A = L * L'$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * U$ or $A = L * L'$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output) DOUBLE PRECISION array, dimension (N)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output) DOUBLE PRECISION array, dimension (LDB, NRHS)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (output) DOUBLE PRECISION array, dimension (LDX, NRHS)

If INFO = 0 or INFO = N + 1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is $\text{inv}(\text{diag}(S)) * X$.

LDX (input)

The leading dimension of the array X. $LDX \geq \max(1, N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output) DOUBLE PRECISION array, dimension (NRHS)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) DOUBLE PRECISION array, dimension (NRHS)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
DOUBLE PRECISION array, dimension (3*N)

WORK2 (workspace)
INTEGER array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when N = 4, UPLO = 'U':

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34      (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

dpptrf - compute the Cholesky factorization of a real symmetric positive definite matrix A stored in packed format

SYNOPSIS

```
SUBROUTINE DPPTRF(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
DOUBLE PRECISION A(*)
```

```
SUBROUTINE DPPTRF_64(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
DOUBLE PRECISION A(*)
```

F95 INTERFACE

```
SUBROUTINE PPTRF(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
REAL(8), DIMENSION(:) :: A
```

```
SUBROUTINE PPTRF_64(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
REAL(8), DIMENSION(:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpptrf(char uplo, int n, double *a, int *info);
```

```
void dpptrf_64(char uplo, long n, double *a, long *info);
```

PURPOSE

dpptrf computes the Cholesky factorization of a real symmetric positive definite matrix A stored in packed format.

The factorization has the form

$A = U^{*T} * U$, if UPLO = 'U', or

$A = L * L^{*T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{*T} * U$ or $A = L * L^{*T}$, in the same storage format as A.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, UPLO = 'U':

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13 a14
  a22 a23 a24
    a33 a34      (aij = aji)
      a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

dpptri - compute the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^*T^*U$ or $A = L*L^*T$ computed by DPPTRF

SYNOPSIS

```
SUBROUTINE DPPTRI(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
DOUBLE PRECISION A(*)
```

```
SUBROUTINE DPPTRI_64(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
DOUBLE PRECISION A(*)
```

F95 INTERFACE

```
SUBROUTINE PPTRI(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
REAL(8), DIMENSION(:) :: A
```

```
SUBROUTINE PPTRI_64(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
REAL(8), DIMENSION(:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpptri(char uplo, int n, double *a, int *info);
```

```
void dpptri_64(char uplo, long n, double *a, long *info);
```

PURPOSE

dpptri computes the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by DPPTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular factor is stored in A;
= 'L': Lower triangular factor is stored in A.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$

On entry, the triangular factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$, packed columnwise as a linear array. The j-th column of U or L is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = U(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = L(i,j)$ for $j \leq i \leq n$.

On exit, the upper or lower triangle of the (symmetric) inverse of A, overwriting the input factor U or L.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the (i,i) element of the factor U or L is zero, and the inverse could not be computed.

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NAME

dpptrs - solve a system of linear equations $A \cdot X = B$ with a symmetric positive definite matrix A in packed storage using the Cholesky factorization $A = U \cdot U^T \cdot U$ or $A = L \cdot L^T \cdot T$ computed by DPPTRF

SYNOPSIS

```
SUBROUTINE DPPTRS(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, INFO  
DOUBLE PRECISION A(*), B(LDB,*)
```

```
SUBROUTINE DPPTRS_64(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, INFO  
DOUBLE PRECISION A(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PPTRS(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: A  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE PPTRS_64(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: A  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpptrs(char uplo, int n, int nrhs, double *a, double  
            *b, int ldb, int *info);
```

```
void dpptrs_64(char uplo, long n, long nrhs, double *a, double *b, long ldb, long *info);
```

PURPOSE

dpptrs solves a system of linear equations $A \cdot X = B$ with a symmetric positive definite matrix A in packed storage using the Cholesky factorization $A = U \cdot U^T \cdot U$ or $A = L \cdot L^T \cdot L$ computed by DPPTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) DOUBLE PRECISION array, dimension $(N \cdot (N+1) / 2)$

The triangular factor U or L from the Cholesky factorization $A = U \cdot U^T \cdot U$ or $A = L \cdot L^T \cdot L$, packed columnwise in a linear array. The j -th column of U or L is stored in the array A as follows: if $UPLO = 'U'$, $A(i + (j-1) \cdot j / 2) = U(i, j)$ for $1 \leq i \leq j$; if $UPLO = 'L'$, $A(i + (j-1) \cdot (2n-j) / 2) = L(i, j)$ for $j \leq i \leq n$.

B (input/output) DOUBLE PRECISION array, dimension $(LDB, NRHS)$

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

dptcon - compute the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite tridiagonal matrix using the factorization $A = L*D*L^T$ or $A = U^T*D*U$ computed by DPTTRF

SYNOPSIS

```
SUBROUTINE DPTCON(N, D, E, ANORM, RCOND, WORK, INFO)
```

```
INTEGER N, INFO  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION D(*), E(*), WORK(*)
```

```
SUBROUTINE DPTCON_64(N, D, E, ANORM, RCOND, WORK, INFO)
```

```
INTEGER*8 N, INFO  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION D(*), E(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTCON([N], D, E, ANORM, RCOND, [WORK], [INFO])
```

```
INTEGER :: N, INFO  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: D, E, WORK
```

```
SUBROUTINE PTCON_64([N], D, E, ANORM, RCOND, [WORK], [INFO])
```

```
INTEGER(8) :: N, INFO  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: D, E, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dptcon(int n, double *d, double *e, double anorm, double *rcond, int *info);
```

```
void dptcon_64(long n, double *d, double *e, double anorm,
              double *rcond, long *info);
```

PURPOSE

dptcon computes the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite tridiagonal matrix using the factorization $A = L*D*L^T$ or $A = U^T*D*U$ computed by DPTTRF. $\text{Norm}(\text{inv}(A))$ is computed by a direct method, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the factorization of A, as computed by DPTTRF.

E (input) The (n-1) off-diagonal elements of the unit bidiagonal factor U or L from the factorization of A, as computed by DPTTRF.

ANORM (input)
The 1-norm of the original matrix A.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The method used is described in Nicholas J. Higham, "Efficient Algorithms for Computing the Condition Number of a Tridiagonal Matrix", SIAM J. Sci. Stat. Comput., Vol. 7, No. 1, January 1986.

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NAME

dpTEQR - compute all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using DPTTRF, and then calling DBDSQR to compute the singular values of the bidiagonal factor

SYNOPSIS

```
SUBROUTINE DPTEQR(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
INTEGER N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DPTEQR_64(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
INTEGER*8 N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTEQR(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
INTEGER :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE PTEQR_64(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
INTEGER(8) :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dpTEQR(char compz, int n, double *d, double *e, double  
*z, int ldz, int *info);
```

```
void dpteqr_64(char compz, long n, double *d, double *e,  
              double *z, long ldz, long *info);
```

PURPOSE

dpteqr computes all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using DPTTRF, and then calling DBDSQR to compute the singular values of the bidiagonal factor.

This routine computes the eigenvalues of the positive definite tridiagonal matrix to high relative accuracy. This means that if the eigenvalues range over many orders of magnitude in size, then the small eigenvalues and corresponding eigenvectors will be computed more accurately than, for example, with the standard QR method.

The eigenvectors of a full or band symmetric positive definite matrix can also be found if DSYTRD, DSPTRD, or DSBTRD has been used to reduce this matrix to tridiagonal form. (The reduction to tridiagonal form, however, may preclude the possibility of obtaining high relative accuracy in the small eigenvalues of the original matrix, if these eigenvalues range over many orders of magnitude.)

ARGUMENTS

COMPZ (input)

= 'N': Compute eigenvalues only.
= 'V': Compute eigenvectors of original symmetric matrix also. Array Z contains the orthogonal matrix used to reduce the original matrix to tridiagonal form.
= 'I': Compute eigenvectors of tridiagonal matrix also.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix. On normal exit, D contains the eigenvalues, in descending order.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input)

On entry, if COMPZ = 'V', the orthogonal matrix used in the reduction to tridiagonal form. On exit, if COMPZ = 'V', the orthonormal eigenvectors of the original symmetric matrix; if COMPZ = 'I', the orthonormal eigenvectors of the tridiagonal matrix. If INFO > 0 on exit, Z contains the eigenvectors associated with only the stored

eigenvalues. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if COMPZ = 'V' or 'I', LDZ \geq max(1,N).

WORK (workspace)

dimension(4*N)

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: if INFO = i, and i is: \leq N the Cholesky factorization of the matrix could not be performed because the i-th principal minor was not positive definite. $>$ N the SVD algorithm failed to converge; if INFO = N+i, i off-diagonal elements of the bidiagonal factor did not converge to zero.

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NAME

dptrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE DPTRFS(N, NRHS, D, E, DF, EF, B, LDB, X, LDX,  
                FERR, BERR, WORK, INFO)
```

```
INTEGER N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION D(*), E(*), DF(*), EF(*), B(LDB,*),  
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DPTRFS_64(N, NRHS, D, E, DF, EF, B, LDB, X,  
                   LDX, FERR, BERR, WORK, INFO)
```

```
INTEGER*8 N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION D(*), E(*), DF(*), EF(*), B(LDB,*),  
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTRFS([N], [NRHS], D, E, DF, EF, B, [LDB], X,  
                [LDX], FERR, BERR, [WORK], [INFO])
```

```
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: D, E, DF, EF, FERR, BERR, WORK  
REAL(8), DIMENSION(:,:) :: B, X
```

```
SUBROUTINE PTRFS_64([N], [NRHS], D, E, DF, EF, B, [LDB],  
                   X, [LDX], FERR, BERR, [WORK], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: D, E, DF, EF, FERR, BERR, WORK  
REAL(8), DIMENSION(:,:) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dptrfs(int n, int nrhs, double *d, double *e, double
```

```

        *df, double *ef, double *b, int ldb, double *x,
        int ldx, double *ferr, double *berr, int *info);

void dptrfs_64(long n, long nrhs, double *d, double *e, dou-
        ble *df, double *ef, double *b, long ldb, double
        *x, long ldx, double *ferr, double *berr, long
        *info);

```

PURPOSE

dptrfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

D (input) The n diagonal elements of the tridiagonal matrix A.

E (input) The (n-1) subdiagonal elements of the tridiagonal matrix A.

DF (input)
The n diagonal elements of the diagonal matrix D from the factorization computed by DPTTRF.

EF (input)
The (n-1) subdiagonal elements of the unit bidiagonal factor L from the factorization computed by DPTTRF.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1,N)$.

X (input/output)
On entry, the solution matrix X, as computed by DPTTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. $LDX \geq \max(1,N)$.

FERR (output)
The forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the

magnitude of the largest element in $(X(j) - X_{TRUE})$
divided by the magnitude of the largest element in
 $X(j)$.

BERR (output)

The componentwise relative backward error of each
solution vector $X(j)$ (i.e., the smallest relative
change in any element of A or B that makes $X(j)$ an
exact solution).

WORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

dptsv - compute the solution to a real system of linear equations $A \cdot X = B$, where A is an N -by- N symmetric positive definite tridiagonal matrix, and X and B are N -by- $NRHS$ matrices.

SYNOPSIS

```
SUBROUTINE DPTSV(N, NRHS, D, E, B, LDB, INFO)
```

```
INTEGER N, NRHS, LDB, INFO  
DOUBLE PRECISION D(*), E(*), B(LDB,*)
```

```
SUBROUTINE DPTSV_64(N, NRHS, D, E, B, LDB, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO  
DOUBLE PRECISION D(*), E(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PTVS([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: D, E  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE PTVS_64([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: D, E  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dptsv(int n, int nrhs, double *d, double *e, double *b,  
          int ldb, int *info);
```

```
void dptsv_64(long n, long nrhs, double *d, double *e, dou-  
             ble *b, long ldb, long *info);
```

PURPOSE

dptsv computes the solution to a real system of linear equations $A \cdot X = B$, where A is an N -by- N symmetric positive definite tridiagonal matrix, and X and B are N -by- $NRHS$ matrices.

A is factored as $A = L \cdot D \cdot L^T$, and the factored form of A is then used to solve the system of equations.

ARGUMENTS

N (input) The order of the matrix A . $N \geq 0$.

$NRHS$ (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A . On exit, the n diagonal elements of the diagonal matrix D from the factorization $A = L \cdot D \cdot L^T$.

E (input/output)

On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix A . On exit, the $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the $L \cdot D \cdot L^T$ factorization of A . (E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the $U^T \cdot D \cdot U$ factorization of A .)

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B . On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

$INFO$ (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, the leading minor of order i is not positive definite, and the solution has not been computed. The factorization has not been completed unless $i = N$.

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NAME

dptsvx - use the factorization $A = L*D*L**T$ to compute the solution to a real system of linear equations $A*X = B$, where A is an N-by-N symmetric positive definite tridiagonal matrix and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE DPTSVX(FACT, N, NRHS, D, E, DF, EF, B, LDB, X,  
                 LDX, RCOND, FERR, BERR, WORK, INFO)
```

```
CHARACTER * 1 FACT  
INTEGER N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION D(*), E(*), DF(*), EF(*), B(LDB,*),  
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DPTSVX_64(FACT, N, NRHS, D, E, DF, EF, B, LDB,  
                    X, LDX, RCOND, FERR, BERR, WORK, INFO)
```

```
CHARACTER * 1 FACT  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION D(*), E(*), DF(*), EF(*), B(LDB,*),  
X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTVSX(FACT, [N], [NRHS], D, E, DF, EF, B, [LDB],  
                X, [LDX], RCOND, FERR, BERR, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: FACT  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: D, E, DF, EF, FERR, BERR, WORK  
REAL(8), DIMENSION(:,) :: B, X
```

```
SUBROUTINE PTVSX_64(FACT, [N], [NRHS], D, E, DF, EF, B,  
                   [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: FACT  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

```
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: D, E, DF, EF, FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
void dptsvx(char fact, int n, int nrhs, double *d, double
            *e, double *df, double *ef, double *b, int ldb,
            double *x, int ldx, double *rcond, double *ferr,
            double *berr, int *info);

void dptsvx_64(char fact, long n, long nrhs, double *d, dou-
               ble *e, double *df, double *ef, double *b, long
               ldb, double *x, long ldx, double *rcond, double
               *ferr, double *berr, long *info);
```

PURPOSE

dptsvx uses the factorization $A = L^*D^*L^{**T}$ to compute the solution to a real system of linear equations $A^*X = B$, where A is an N -by- N symmetric positive definite tridiagonal matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the matrix A is factored as $A = L^*D^*L^{**T}$, where L is a unit lower bidiagonal matrix and D is diagonal. The factorization can also be regarded as having the form $A = U^{**T}^*D^*U$.
2. If the leading i -by- i principal minor is not positive definite, then the routine returns with $INFO = i$. Otherwise, the factored form of A is used to estimate the condition number of the matrix A .
 - A. If the reciprocal of the condition number is less than machine precision, $INFO = N+1$ is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
3. The system of equations is solved for X using the factored form of A .
4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)
Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, DF and EF contain the factored form of A. D, E, DF, and EF will not be modified. = 'N': The matrix A will be copied to DF and EF and factored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

D (input) The n diagonal elements of the tridiagonal matrix A.

E (input) The (n-1) subdiagonal elements of the tridiagonal matrix A.

DF (input or output)
If FACT = 'F', then DF is an input argument and on entry contains the n diagonal elements of the diagonal matrix D from the $L^*D^*L^{**T}$ factorization of A. If FACT = 'N', then DF is an output argument and on exit contains the n diagonal elements of the diagonal matrix D from the $L^*D^*L^{**T}$ factorization of A.

EF (input or output)
If FACT = 'F', then EF is an input argument and on entry contains the (n-1) subdiagonal elements of the unit bidiagonal factor L from the $L^*D^*L^{**T}$ factorization of A. If FACT = 'N', then EF is an output argument and on exit contains the (n-1) subdiagonal elements of the unit bidiagonal factor L from the $L^*D^*L^{**T}$ factorization of A.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1,N)$.

X (output)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)
The leading dimension of the array X. $LDX \geq \max(1,N)$.

RCOND (output)
The reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension($2*N$)

INFO (output)

= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value
> 0: if INFO = i , and i is
<= N : the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. $RCOND = 0$ is returned. = $N+1$: U is non-singular, but $RCOND$ is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of $RCOND$ would suggest.

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NAME

dppttrf - compute the L*D*L' factorization of a real symmetric positive definite tridiagonal matrix A

SYNOPSIS

```
SUBROUTINE DPTTRF(N, D, E, INFO)
```

```
INTEGER N, INFO  
DOUBLE PRECISION D(*), E(*)
```

```
SUBROUTINE DPTTRF_64(N, D, E, INFO)
```

```
INTEGER*8 N, INFO  
DOUBLE PRECISION D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE PTTRF([N], D, E, [INFO])
```

```
INTEGER :: N, INFO  
REAL(8), DIMENSION(:) :: D, E
```

```
SUBROUTINE PTTRF_64([N], D, E, [INFO])
```

```
INTEGER(8) :: N, INFO  
REAL(8), DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dppttrf(int n, double *d, double *e, int *info);
```

```
void dppttrf_64(long n, double *d, double *e, long *info);
```

PURPOSE

dppttrf computes the L*D*L' factorization of a real symmetric positive definite tridiagonal matrix A. The factorization

may also be regarded as having the form $A = U'D*U$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the $L'D*L'$ factorization of A.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A. On exit, the (n-1) subdiagonal elements of the unit bidiagonal factor L from the $L'D*L'$ factorization of A. E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the $U'D*U$ factorization of A.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value
> 0: if INFO = k, the leading minor of order k is not positive definite; if $k < N$, the factorization could not be completed, while if $k = N$, the factorization was completed, but $D(N) = 0$.

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NAME

dppttrs - solve a tridiagonal system of the form $A * X = B$ using the L*D*L' factorization of A computed by DPTTRF

SYNOPSIS

```
SUBROUTINE DPTTRS(N, NRHS, D, E, B, LDB, INFO)
```

```
INTEGER N, NRHS, LDB, INFO  
DOUBLE PRECISION D(*), E(*), B(LDB,*)
```

```
SUBROUTINE DPTTRS_64(N, NRHS, D, E, B, LDB, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO  
DOUBLE PRECISION D(*), E(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PTTRS([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: D, E  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE PTTRS_64([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: D, E  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dppttrs(int n, int nrhs, double *d, double *e, double  
             *b, int ldb, int *info);
```

```
void dppttrs_64(long n, long nrhs, double *d, double *e, dou-  
               ble *b, long ldb, long *info);
```

PURPOSE

dpttrs solves a tridiagonal system of the form
 $A * X = B$ using the $L*D*L'$ factorization of A computed by DPTTRF. D is a diagonal matrix specified in the vector D , L is a unit bidiagonal matrix whose subdiagonal is specified in the vector E , and X and B are N by $NRHS$ matrices.

ARGUMENTS

N (input) The order of the tridiagonal matrix A . $N \geq 0$.

$NRHS$ (input)
The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the $L*D*L'$ factorization of A .

E (input) The $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the $L*D*L'$ factorization of A . E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the factorization $A = U'*D*U$.

B (input/output)
On entry, the right hand side vectors B for the system of linear equations. On exit, the solution vectors, X .

LDB (input)
The leading dimension of the array B . $LDB \geq \max(1,N)$.

$INFO$ (output)
= 0: successful exit
< 0: if $INFO = -k$, the k -th argument had an illegal value

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NAME

dptts2 - solve a tridiagonal system of the form $A * X = B$ using the L*D*L' factorization of A computed by DPTTRF

SYNOPSIS

```
SUBROUTINE DPTTS2(N, NRHS, D, E, B, LDB)
```

```
INTEGER N, NRHS, LDB  
DOUBLE PRECISION D(*), E(*), B(LDB,*)
```

```
SUBROUTINE DPTTS2_64(N, NRHS, D, E, B, LDB)
```

```
INTEGER*8 N, NRHS, LDB  
DOUBLE PRECISION D(*), E(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE DPTTS2(N, NRHS, D, E, B, LDB)
```

```
INTEGER :: N, NRHS, LDB  
REAL(8), DIMENSION(:) :: D, E  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE DPTTS2_64(N, NRHS, D, E, B, LDB)
```

```
INTEGER(8) :: N, NRHS, LDB  
REAL(8), DIMENSION(:) :: D, E  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dptts2(int n, int nrhs, double *d, double *e, double  
          *b, int ldb);
```

```
void dptts2_64(long n, long nrhs, double *d, double *e, dou-  
             ble *b, long ldb);
```

PURPOSE

dptts2 solves a tridiagonal system of the form
 $A * X = B$ using the $L*D*L'$ factorization of A computed by DPTTRF. D is a diagonal matrix specified in the vector D , L is a unit bidiagonal matrix whose subdiagonal is specified in the vector E , and X and B are N by $NRHS$ matrices.

ARGUMENTS

N (input) The order of the tridiagonal matrix A . $N \geq 0$.

$NRHS$ (input)
The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the $L*D*L'$ factorization of A .

E (input) The $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the $L*D*L'$ factorization of A . E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the factorization $A = U'*D*U$.

B (input/output)
On entry, the right hand side vectors B for the system of linear equations. On exit, the solution vectors, X .

LDB (input)
The leading dimension of the array B . $LDB \geq \max(1, N)$.

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NAME

dqdots - compute a double precision constant plus an extended precision constant plus the extended precision dot product of two double precision vectors x and y.

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DQDOTA(N, DB, QC, DX, INCX, DY, INCY)
```

```
INTEGER N, INCX, INCY  
REAL * 16 QC  
DOUBLE PRECISION DB  
DOUBLE PRECISION DX(*), DY(*)
```

```
DOUBLE PRECISION FUNCTION DQDOTA_64(N, DB, QC, DX, INCX, DY, INCY)
```

```
INTEGER*8 N, INCX, INCY  
REAL * 16 QC  
DOUBLE PRECISION DB  
DOUBLE PRECISION DX(*), DY(*)
```

F95 INTERFACE

```
REAL(8) FUNCTION DQDOTA(N, DB, QC, DX, INCX, DY, INCY)
```

```
INTEGER :: N, INCX, INCY  
REAL(16) :: QC  
REAL(8) :: DB  
REAL(8), DIMENSION(:) :: DX, DY
```

```
REAL(8) FUNCTION DQDOTA_64(N, DB, QC, DX, INCX, DY, INCY)
```

```
INTEGER(8) :: N, INCX, INCY  
REAL(16) :: QC  
REAL(8) :: DB  
REAL(8), DIMENSION(:) :: DX, DY
```

C INTERFACE

```
#include <sunperf.h>
```

```
double dqdots(int n, double db, long double *qc, double *dx,  
              int incx, double *dy, int incy);
```

```
double dqdota_64(long n, double db, long double *qc, double
    *dx, long incx, double *dy, long incy);
```

PURPOSE

dqdota compute a double precision constant plus an extended precision constant plus the extended precision dot product of two double precision vectors x and y.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If $N \leq 0$ then the function returns the value DB+QC. Unchanged on exit.

DB (input)

On entry, the constant that is added to the dot product before the result is returned. Unchanged on exit.

QC (input/output)

On entry, the extended precision constant to be added to the dot product. On exit, the extended precision result.

DX (input)

On entry, the incremented array DX must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of DX. Unchanged on exit.

DY (input)

On entry, the incremented array DY must contain the vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of DY. Unchanged on exit.

Note:

dqdota does not exist in X86 libraries.

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NAME

dqdoti - compute a constant plus the extended precision dot product of two double precision vectors x and y.

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DQDOTI(N, DB, QC, DX, INCX, DY, INCY)

INTEGER N, INCX, INCY
REAL * 16 QC
DOUBLE PRECISION DB
DOUBLE PRECISION DX(*), DY(*)

DOUBLE PRECISION FUNCTION DQDOTI_64(N, DB, QC, DX, INCX, DY, INCY)

INTEGER*8 N, INCX, INCY
REAL * 16 QC
DOUBLE PRECISION DB
DOUBLE PRECISION DX(*), DY(*)
```

F95 INTERFACE

```
REAL(8) FUNCTION DQDOTI(N, DB, QC, DX, INCX, DY, INCY)

INTEGER :: N, INCX, INCY
REAL(16) :: QC
REAL(8) :: DB
REAL(8), DIMENSION(:) :: DX, DY

REAL(8) FUNCTION DQDOTI_64(N, DB, QC, DX, INCX, DY, INCY)

INTEGER(8) :: N, INCX, INCY
REAL(16) :: QC
REAL(8) :: DB
REAL(8), DIMENSION(:) :: DX, DY
```

C INTERFACE

```
#include <sunperf.h>

double dqdoti(int n, double db, long double *qc, double *dx,
              int incx, double *dy, int incy);
```

```
double dqdoti_64(long n, double db, long double *qc, double
                *dx, long incx, double *dy, long incy);
```

PURPOSE

dqdoti computes a constant plus the double precision dot product of x and y where x and y are double precision n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If $N \leq 0$ then the function returns the value DB. Unchanged on exit.

DB (input)

On entry, the constant that is added to the dot product before the result is returned. Unchanged on exit.

QC (output)

On exit, the extended precision result.

DX (input)

On entry, the incremented array DX must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of DX. Unchanged on exit.

DY (input)

On entry, the incremented array DY must contain the vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of DY. Unchanged on exit.

Note:

dqdoti does not exist in X86 libraries.

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NAME

drot - Apply a Given's rotation constructed by SROTG.

SYNOPSIS

```
SUBROUTINE DROT(N, X, INCX, Y, INCY, C, S)
```

```
INTEGER N, INCX, INCY  
DOUBLE PRECISION C, S  
DOUBLE PRECISION X(*), Y(*)
```

```
SUBROUTINE DROT_64(N, X, INCX, Y, INCY, C, S)
```

```
INTEGER*8 N, INCX, INCY  
DOUBLE PRECISION C, S  
DOUBLE PRECISION X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE ROT([N], X, [INCX], Y, [INCY], C, S)
```

```
INTEGER :: N, INCX, INCY  
REAL(8) :: C, S  
REAL(8), DIMENSION(:) :: X, Y
```

```
SUBROUTINE ROT_64([N], X, [INCX], Y, [INCY], C, S)
```

```
INTEGER(8) :: N, INCX, INCY  
REAL(8) :: C, S  
REAL(8), DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void drot(int n, double *x, int incx, double *y, int incy,  
         double c, double s);
```

```
void drot_64(long n, double *x, long incx, double *y, long  
            incy, double c, double s);
```

PURPOSE

drot Apply a Given's rotation constructed by SROTG.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input/output)

(1 + (n - 1) * abs(INCX)). Before entry, the incremented array X must contain the vector x.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

C (input) On entry, the C rotation value constructed by SROTG. Unchanged on exit.

S (input) On entry, the S rotation value constructed by SROTG. Unchanged on exit.

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NAME

drotg - Construct a Given's plane rotation

SYNOPSIS

```
SUBROUTINE DROTG(A, B, C, S)
```

```
DOUBLE PRECISION A, B, C, S
```

```
SUBROUTINE DROTG_64(A, B, C, S)
```

```
DOUBLE PRECISION A, B, C, S
```

F95 INTERFACE

```
SUBROUTINE ROTG(A, B, C, S)
```

```
REAL(8) :: A, B, C, S
```

```
SUBROUTINE ROTG_64(A, B, C, S)
```

```
REAL(8) :: A, B, C, S
```

C INTERFACE

```
#include <sunperf.h>
```

```
void drotg(double *a, double *b, double *c, double *s);
```

```
void drotg_64(double *a, double *b, double *c, double *s);
```

PURPOSE

drotg Construct a Given's plane rotation that will annihilate an element of a vector.

ARGUMENTS

A (input/output)

On entry, A contains the entry in the first vector that corresponds to the element to be annihilated in the second vector. On exit, contains the nonzero element of the rotated vector.

B (input/output)

On entry, B contains the entry to be annihilated in the second vector. On exit, contains either S or $1/C$ depending on which of the input values of A and B is larger.

C (output)

On exit, C and S are the elements of the rotation matrix that will be applied to annihilate B.

S (output)

See the description of C.

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NAME

droti - Apply an indexed Givens rotation.

SYNOPSIS

```
SUBROUTINE DROTI(NZ, X, INDX, Y, C, S)
```

```
INTEGER NZ  
INTEGER INDX(*)  
DOUBLE PRECISION C, S  
DOUBLE PRECISION X(*), Y(*)
```

```
SUBROUTINE DROTI_64(NZ, X, INDX, Y, C, S)
```

```
INTEGER*8 NZ  
INTEGER*8 INDX(*)  
DOUBLE PRECISION C, S  
DOUBLE PRECISION X(*), Y(*)
```

```
F95 INTERFACE
```

```
SUBROUTINE ROTI([NZ], X, INDX, Y, C, S)
```

```
INTEGER :: NZ  
INTEGER, DIMENSION(:) :: INDX  
REAL(8) :: C, S  
REAL(8), DIMENSION(:) :: X, Y
```

```
SUBROUTINE ROTI_64([NZ], X, INDX, Y, C, S)
```

```
INTEGER(8) :: NZ  
INTEGER(8), DIMENSION(:) :: INDX  
REAL(8) :: C, S  
REAL(8), DIMENSION(:) :: X, Y
```

PURPOSE

DROTI - Applies a Givens rotation to a sparse vector x stored in compressed form and another vector y in full storage form

```
do i = 1, n
```

```
temp = -s * x(i) + c * y(indx(i))
x(i) = c * x(i) + s * y(indx(i))
y(indx(i)) = temp
enddo
```

ARGUMENTS

NZ (input) - INTEGER
Number of elements in the compressed form.
Unchanged on exit.

X (input)
Vector containing the values of the compressed form.

INDX (input) - INTEGER
Vector containing the indices of the compressed form. It is assumed that the elements in INDX are distinct and greater than zero. Unchanged on exit.

Y (input/output)
Vector on input which contains the vector Y in full storage form. On exit, only the elements corresponding to the indices in INDX have been modified.

C (input)
Scalar defining the Givens rotation

S (input)
Scalar defining the Givens rotation

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NAME

drotm - Apply a Gentleman's modified Given's rotation constructed by SROTMG.

SYNOPSIS

```
SUBROUTINE DROTM(N, X, INCX, Y, INCY, PARAM)
```

```
INTEGER N, INCX, INCY  
DOUBLE PRECISION X(*), Y(*), PARAM(*)
```

```
SUBROUTINE DROTM_64(N, X, INCX, Y, INCY, PARAM)
```

```
INTEGER*8 N, INCX, INCY  
DOUBLE PRECISION X(*), Y(*), PARAM(*)
```

F95 INTERFACE

```
SUBROUTINE ROTM([N], X, [INCX], Y, [INCY], PARAM)
```

```
INTEGER :: N, INCX, INCY  
REAL(8), DIMENSION(:) :: X, Y, PARAM
```

```
SUBROUTINE ROTM_64([N], X, [INCX], Y, [INCY], PARAM)
```

```
INTEGER(8) :: N, INCX, INCY  
REAL(8), DIMENSION(:) :: X, Y, PARAM
```

C INTERFACE

```
#include <sunperf.h>
```

```
void drotm(int n, double *x, int incx, double *y, int incy,  
          double *param);
```

```
void drotm_64(long n, double *x, long incx, double *y, long  
            incy, double *param);
```

PURPOSE

drotm Apply a Given's rotation constructed by SROTMG.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the sub-routine to have any visible effect. Unchanged on exit.

X (input/output)

(1 + (n - 1) * abs(INCX)). On entry, the incremented array X must contain the vector x. On exit, X is overwritten by the updated vector x.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

PARAM (input)

On entry, the rotation values constructed by SROTMG. Unchanged on exit.

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NAME

drotmg - Construct a Gentleman's modified Given's plane rotation

SYNOPSIS

```
SUBROUTINE DROTMG(D1, D2, B1, B2, PARAM)
```

```
DOUBLE PRECISION D1, D2, B1, B2  
DOUBLE PRECISION PARAM(*)
```

```
SUBROUTINE DROTMG_64(D1, D2, B1, B2, PARAM)
```

```
DOUBLE PRECISION D1, D2, B1, B2  
DOUBLE PRECISION PARAM(*)
```

F95 INTERFACE

```
SUBROUTINE ROTMG(D1, D2, B1, B2, PARAM)
```

```
REAL(8) :: D1, D2, B1, B2  
REAL(8), DIMENSION(:) :: PARAM
```

```
SUBROUTINE ROTMG_64(D1, D2, B1, B2, PARAM)
```

```
REAL(8) :: D1, D2, B1, B2  
REAL(8), DIMENSION(:) :: PARAM
```

C INTERFACE

```
#include <sunperf.h>
```

```
void drotmg(double d1, double d2, double b1, double b2, double *param);
```

```
void drotmg_64(double d1, double d2, double b1, double b2, double *param);
```

PURPOSE

drotmg Construct Gentleman's modified a Given's plane rotation that will annihilate an element of a vector.

ARGUMENTS

D1 (input/output)

On entry, the first diagonal entry in the H matrix. On exit, changed to reflect the effect of the transformation.

D2 (input/output)

On entry, the second diagonal entry in the H matrix. On exit, changed to reflect the effect of the transformation.

B1 (input/output)

On entry, the first element of the vector to which the H matrix is applied. On exit, changed to reflect the effect of the transformation.

B2 (input)

On entry, the second element of the vector to which the H matrix is applied. Unchanged on exit.

PARAM (output)

On exit, PARAM(1) describes the form of the rotation matrix H, and PARAM(2..5) contain the H matrix.

If PARAM(1) = -2 then H = I and no elements of PARAM are modified.

If PARAM(1) = -1 then PARAM(2) = h11, PARAM(3) = h21, PARAM(4) = h12, and PARAM(5) = h22.

If PARAM(1) = 0 then h11 = h22 = 1, PARAM(3) = h21, and PARAM(4) = h12.

If PARAM(1) = 1 then h12 = 1, h21 = -1, PARAM(2) = h11, and PARAM(5) = h22.

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NAME

dsbev - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

SYNOPSIS

```
SUBROUTINE DSBEV(JOBZ, UPLO, N, KD, A, LDA, W, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, KD, LDA, LDZ, INFO  
DOUBLE PRECISION A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSBEV_64(JOBZ, UPLO, N, KD, A, LDA, W, Z, LDZ, WORK,  
INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, KD, LDA, LDZ, INFO  
DOUBLE PRECISION A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBEV(JOBZ, UPLO, [N], KD, A, [LDA], W, Z, [LDZ], [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, KD, LDA, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:,:) :: A, Z
```

```
SUBROUTINE SBEV_64(JOBZ, UPLO, [N], KD, A, [LDA], W, Z, [LDZ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, KD, LDA, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:,:) :: A, Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsbev(char jobz, char uplo, int n, int kd, double *a,  
int lda, double *w, double *z, int ldz, int
```

```

        *info);

void dsbev_64(char jobz, char uplo, long n, long kd, double
        *a, long lda, double *w, double *z, long ldz, long
        *info);

```

PURPOSE

dsbev computes all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, A is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of the tridiagonal matrix T are returned in rows KD and $KD+1$ of A, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the first two rows of A.

LDA (input)
 The leading dimension of the array A. $LDA \geq KD + 1$.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i -th column of Z holding the eigenvector associated with $W(i)$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1,
and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

dimension(MAX(1,3*N-2))

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

dsbevd - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

SYNOPSIS

```
SUBROUTINE DSBEVD(JOBZ, UPLO, N, KD, AB, LDAB, W, Z, LDZ, WORK,  
                 LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, KD, LDAB, LDZ, LWORK, LIWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION AB(LDAB,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSBEVD_64(JOBZ, UPLO, N, KD, AB, LDAB, W, Z, LDZ, WORK,  
                    LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, KD, LDAB, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION AB(LDAB,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBEVD(JOBZ, UPLO, [N], KD, AB, [LDAB], W, Z, [LDZ], [WORK],  
                [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, KD, LDAB, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: AB, Z
```

```
SUBROUTINE SBEVD_64(JOBZ, UPLO, [N], KD, AB, [LDAB], W, Z, [LDZ],  
                   [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, KD, LDAB, LDZ, LWORK, LIWORK, INFO  
INTEGER(8), DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: AB, Z
```

C INTERFACE

```
#include <sunperf.h>

void dsbevd(char jobz, char uplo, int n, int kd, double *ab,
            int ldab, double *w, double *z, int ldz, int
            *info);
void dsbevd_64(char jobz, char uplo, long n, long kd, double
               *ab, long ldab, double *w, double *z, long ldz,
               long *info);
```

PURPOSE

dsbevd computes all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)
On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, AB is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of the tridiagonal matrix T are returned in rows KD and $KD+1$ of AB, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the

first two rows of AB.

LDAB (input)

The leading dimension of the array AB. LDAB \geq KD + 1.

W (output)

If INFO = 0, the eigenvalues in ascending order.

Z (output)

If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

dimension (LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $N \leq 1$, LWORK must be at least 1. If JOBZ = 'N' and $N > 2$, LWORK must be at least $2*N$. If JOBZ = 'V' and $N > 2$, LWORK must be at least $(1 + 5*N + 2*N**2)$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array LIWORK. If JOBZ = 'N' or $N \leq 1$, LIWORK must be at least 1. If JOBZ = 'V' and $N > 2$, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

dsbevix - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

SYNOPSIS

```
SUBROUTINE DSBEVX(JOBZ, RANGE, UPLO, N, KD, A, LDA, Q, LDQ, VL,
                 VU, IL, IU, ABTOL, NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER IWORK2(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION A(LDA,*), Q(LDQ,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSBEVX_64(JOBZ, RANGE, UPLO, N, KD, A, LDA, Q, LDQ, VL,
                   VU, IL, IU, ABTOL, NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER*8 IWORK2(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION A(LDA,*), Q(LDQ,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBEVX(JOBZ, RANGE, UPLO, [N], KD, A, [LDA], Q, [LDQ],
                VL, VU, IL, IU, ABTOL, NFOUND, W, Z, [LDZ], [WORK], [IWORK2],
                IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK2, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: A, Q, Z
```

```
SUBROUTINE SBEVX_64(JOBZ, RANGE, UPLO, [N], KD, A, [LDA], Q, [LDQ],
                   VL, VU, IL, IU, ABTOL, NFOUND, W, Z, [LDZ], [WORK], [IWORK2],
                   IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
```

```

INTEGER(8) :: N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK2, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: A, Q, Z
C INTERFACE
#include <sunperf.h>

void dsbevx(char jobz, char range, char uplo, int n, int kd,
            double *a, int lda, double *q, int ldq, double vl,
            double vu, int il, int iu, double abtol, int
            *nfound, double *w, double *z, int ldz, int
            *ifail, int *info);

void dsbevx_64(char jobz, char range, char uplo, long n,
               long kd, double *a, long lda, double *q, long ldq,
               double vl, double vu, long il, long iu, double
               abtol, long *nfound, double *w, double *z, long
               ldz, long *ifail, long *info);

```

PURPOSE

dsbevx computes selected eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found;
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found; = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. N >= 0.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. KD >= 0.

A (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first KD+1 rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-$

kd)<=i<=j; if UPLO = 'L', A(1+i-j,j) = A(i,j)
for j<=i<=min(n,j+kd).

On exit, A is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of the tridiagonal matrix T are returned in rows KD and KD+1 of A, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the first two rows of A.

LDA (input)

The leading dimension of the array A. LDA >= KD + 1.

Q (output)

If JOBZ = 'V', the N-by-N orthogonal matrix used in the reduction to tridiagonal form. If JOBZ = 'N', the array Q is not referenced.

LDQ (input)

The leading dimension of the array Q. If JOBZ = 'V', then LDQ >= max(1,N).

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. 1 <= IL <= IU <= N, if N > 0; IL = 1 and IU = 0 if N = 0. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then EPS*|T| will be used in its place, where |T| is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold 2*SLAMCH('S'), not zero. If this routine returns with INFO>0, indicating that some eigenvectors did not converge, try setting ABTOL to 2*SLAMCH('S').

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq \text{NFOUND} \leq N$. If RANGE = 'A', NFOUND = N, and if RANGE = 'I', NFOUND = IU-IL+1.

W (output)

The first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input)

If JOBZ = 'V', then if INFO = 0, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, \text{NFOUND})$ columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $\text{LDZ} \geq 1$, and if JOBZ = 'V', $\text{LDZ} \geq \max(1, N)$.

WORK (workspace)

dimension(7*N)

IWORK2 (workspace)

IFAIL (output)

If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

dsbgst - reduce a real symmetric-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$,

SYNOPSIS

```
SUBROUTINE DSBGST(VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X, LDX,
                 WORK, INFO)
```

```
CHARACTER * 1 VECT, UPLO
INTEGER N, KA, KB, LDAB, LDBB, LDX, INFO
DOUBLE PRECISION AB(LDAB,*), BB(LDBB,*), X(LDX,*), WORK(*)
```

```
SUBROUTINE DSBGST_64(VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X,
                    LDX, WORK, INFO)
```

```
CHARACTER * 1 VECT, UPLO
INTEGER*8 N, KA, KB, LDAB, LDBB, LDX, INFO
DOUBLE PRECISION AB(LDAB,*), BB(LDBB,*), X(LDX,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBGST(VECT, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], X,
                [LDX], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO
INTEGER :: N, KA, KB, LDAB, LDBB, LDX, INFO
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:,:) :: AB, BB, X
```

```
SUBROUTINE SBGST_64(VECT, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],
                   X, [LDX], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDX, INFO
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:,:) :: AB, BB, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsbgst(char vect, char uplo, int n, int ka, int kb,
            double *ab, int ldab, double *bb, int ldbb, double
            *x, int ldx, int *info);
```

```
void dsbgst_64(char vect, char uplo, long n, long ka, long
               kb, double *ab, long ldab, double *bb, long ldbb,
               double *x, long ldx, long *info);
```

PURPOSE

dsbgst reduces a real symmetric-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$, such that C has the same bandwidth as A.

B must have been previously factorized as $S**T*S$ by SPBSTF, using a split Cholesky factorization. A is overwritten by $C = X**T*A*X$, where $X = S**(-1)*Q$ and Q is an orthogonal matrix chosen to preserve the bandwidth of A.

ARGUMENTS

VECT (input)
 = 'N': do not form the transformation matrix X;
 = 'V': form X.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
 The number of superdiagonals of the matrix A if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KA \geq 0$.

KB (input)
 The number of superdiagonals of the matrix B if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KA \geq KB \geq 0$.

AB (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $ka+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+ka)$.

On exit, the transformed matrix $X**T*A*X$, stored in the same format as A.

LDAB (input)
 The leading dimension of the array AB. $LDAB \geq KA+1$.

BB (input)
The banded factor S from the split Cholesky factorization of B, as returned by SPBSTF, stored in the first KB+1 rows of the array.

LDBB (input)
The leading dimension of the array BB. LDBB \geq KB+1.

X (output)
If VECT = 'V', the n-by-n matrix X. If VECT = 'N', the array X is not referenced.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N) if VECT = 'V'; LDX \geq 1 otherwise.

WORK (workspace)
dimension(2*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

dsbgv - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

SYNOPSIS

```
SUBROUTINE DSBGV(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
                LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, KA, KB, LDAB, LDBB, LDZ, INFO  
DOUBLE PRECISION AB(LDAB,*), BB(LDBB,*), W(*), Z(LDZ,*),  
WORK(*)
```

```
SUBROUTINE DSBGV_64(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
                  LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, KA, KB, LDAB, LDBB, LDZ, INFO  
DOUBLE PRECISION AB(LDAB,*), BB(LDBB,*), W(*), Z(LDZ,*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBGV(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], W,  
               Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, KA, KB, LDAB, LDBB, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: AB, BB, Z
```

```
SUBROUTINE SBGV_64(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],  
                  W, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: AB, BB, Z
```

C INTERFACE

```
#include <sunperf.h>

void dsbgv(char jobz, char uplo, int n, int ka, int kb, double
           *ab, int ldab, double *bb, int ldbb, double
           *w, double *z, int ldz, int *info);
void dsbgv_64(char jobz, char uplo, long n, long ka, long
              kb, double *ab, long ldab, double *bb, long ldbb,
              double *w, double *z, long ldz, long *info);
```

PURPOSE

dsbgv computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$. Here A and B are assumed to be symmetric and banded, and B is also positive definite.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
 = 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
 The number of superdiagonals of the matrix A if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KA \geq 0$.

KB (input)
 The number of superdiagonals of the matrix B if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KB \geq 0$.

AB (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $ka+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+ka)$.

On exit, the contents of AB are destroyed.

LDAB (input)
 The leading dimension of the array AB. $LDAB \geq KA+1$.

BB (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix B, stored in the first $kb+1$

rows of the array. The j -th column of B is stored in the j -th column of the array BB as follows: if $UPLO = 'U'$, $BB(kb+1+i-j,j) = B(i,j)$ for $\max(1,j-kb) \leq i \leq j$; if $UPLO = 'L'$, $BB(1+i-j,j) = B(i,j)$ for $j \leq i \leq \min(n,j+kb)$.

On exit, the factor S from the split Cholesky factorization $B = S^*T^*S$, as returned by `SPBSTF`.

`LDBB` (input)

The leading dimension of the array `BB`. `LDBB` \geq `KB+1`.

`W` (output)

If `INFO = 0`, the eigenvalues in ascending order.

`Z` (input)

If `JOBZ = 'V'`, then if `INFO = 0`, `Z` contains the matrix `Z` of eigenvectors, with the i -th column of `Z` holding the eigenvector associated with `W(i)`. The eigenvectors are normalized so that $Z^*T^*B^*Z = I$. If `JOBZ = 'N'`, then `Z` is not referenced.

`LDZ` (input)

The leading dimension of the array `Z`. `LDZ` \geq 1, and if `JOBZ = 'V'`, `LDZ` \geq `N`.

`WORK` (workspace)

dimension($3*N$)

`INFO` (output)

= 0: successful exit
< 0: if `INFO = -i`, the i -th argument had an illegal value
> 0: if `INFO = i`, and i is:
<= `N`: the algorithm failed to converge: i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > `N`: if `INFO = N + i`, for $1 \leq i \leq N$, then `SPBSTF` returned `INFO = i`: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

dsbgvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)B*x$

SYNOPSIS

```
SUBROUTINE DSBGVD(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,
                 LDZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER N, KA, KB, LDAB, LDBB, LDZ, LWORK, LIWORK, INFO
INTEGER IWORK(*)
DOUBLE PRECISION AB(LDAB,*), BB(LDBB,*), W(*), Z(LDZ,*),
WORK(*)
```

```
SUBROUTINE DSBGVD_64(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,
                    LDZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER*8 N, KA, KB, LDAB, LDBB, LDZ, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
DOUBLE PRECISION AB(LDAB,*), BB(LDBB,*), W(*), Z(LDZ,*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBGVD(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], W,
                Z, [LDZ], [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER :: N, KA, KB, LDAB, LDBB, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: AB, BB, Z
```

```
SUBROUTINE SBGVD_64(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],
                    W, Z, [LDZ], [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
```

```

INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDZ, LWORK, LIWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: AB, BB, Z

```

C INTERFACE

```

#include <sunperf.h>
void dsbgvd(char jobz, char uplo, int n, int ka, int kb,
            double *ab, int ldab, double *bb, int ldbb, double
            *w, double *z, int ldz, int *info);

void dsbgvd_64(char jobz, char uplo, long n, long ka, long
              kb, double *ab, long ldab, double *bb, long ldbb,
              double *w, double *z, long ldz, long *info);

```

PURPOSE

dsbgvd computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$. Here A and B are assumed to be symmetric and banded, and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
 = 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KA \geq 0$.

KB (input)
 The number of superdiagonals of the matrix B if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KB \geq 0$.

AB (input/output)
 On entry, the upper or lower triangle of the sym-

metric band matrix A, stored in the first ka+1 rows of the array. The j-th column of A is stored in the j-th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+ka)$.

On exit, the contents of AB are destroyed.

LDAB (input)

The leading dimension of the array AB. LDAB \geq KA+1.

BB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix B, stored in the first kb+1 rows of the array. The j-th column of B is stored in the j-th column of the array BB as follows: if UPLO = 'U', $BB(ka+1+i-j,j) = B(i,j)$ for $\max(1,j-kb) \leq i \leq j$; if UPLO = 'L', $BB(1+i-j,j) = B(i,j)$ for $j \leq i \leq \min(n,j+kb)$.

On exit, the factor S from the split Cholesky factorization $B = S**T*S$, as returned by SPBSTF.

LDBB (input)

The leading dimension of the array BB. LDBB \geq KB+1.

W (output)

If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with W(i). The eigenvectors are normalized so $Z**T*B*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $N \leq 1$, LWORK \geq 1. If JOBZ = 'N' and $N > 1$, LWORK \geq 3*N. If JOBZ = 'V' and $N > 1$, LWORK \geq 1 + 5*N + 2*N**2.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if LIWORK $>$ 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If JOBZ = 'N' or $N \leq 1$, $LIWORK \geq 1$. If JOBZ = 'V' and $N > 1$, $LIWORK \geq 3 + 5*N$.

If $LIWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, and i is:
<= N : the algorithm failed to converge: i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N : if $INFO = N + i$, for $1 \leq i \leq N$, then SPBSTF returned $INFO = i$: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

dsbgvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

SYNOPSIS

```
SUBROUTINE DSBGVX(JOBZ, RANGE, UPLO, N, KA, KB, AB, LDAB, BB, LDBB,
  Q, LDQ, VL, VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, IWORK, IFAIL,
  INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION AB(LDAB,*), BB(LDBB,*), Q(LDQ,*), W(*),
Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSBGVX_64(JOBZ, RANGE, UPLO, N, KA, KB, AB, LDAB, BB,
  LDBB, Q, LDQ, VL, VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, IWORK,
  IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER*8 IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION AB(LDAB,*), BB(LDBB,*), Q(LDQ,*), W(*),
Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBGVX(JOBZ, RANGE, UPLO, [N], KA, KB, AB, [LDAB], BB,
  [LDBB], Q, [LDQ], VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK],
  [IWORK], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, WORK
```

```

REAL(8), DIMENSION(:, :) :: AB, BB, Q, Z

SUBROUTINE SBGVX_64(JOBZ, RANGE, UPLO, [N], KA, KB, AB, [LDAB], BB,
    [LDBB], Q, [LDQ], VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK],
    [IWORK], IFAIL, [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ,
INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: AB, BB, Q, Z

```

C INTERFACE

```

#include <sunperf.h>

void dsbgvx(char jobz, char range, char uplo, int n, int ka,
    int kb, double *ab, int ldab, double *bb, int
    ldbb, double *q, int ldq, double vl, double vu,
    int il, int iu, double abstol, int *m, double *w,
    double *z, int ldz, int *ifail, int *info);

void dsbgvx_64(char jobz, char range, char uplo, long n,
    long ka, long kb, double *ab, long ldab, double
    *bb, long ldbb, double *q, long ldq, double vl,
    double vu, long il, long iu, double abstol, long
    *m, double *w, double *z, long ldz, long *ifail,
    long *info);

```

PURPOSE

dsbgvx computes selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$. Here A and B are assumed to be symmetric and banded, and B is also positive definite. Eigenvalues and eigenvectors can be selected by specifying either all eigenvalues, a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found.
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KA \geq 0$.

KB (input)
 The number of superdiagonals of the matrix B if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KB \geq 0$.

AB (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $ka+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1, j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n, j+ka)$.

On exit, the contents of AB are destroyed.

LDAB (input)
 The leading dimension of the array AB. $LDAB \geq KA+1$.

BB (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix B, stored in the first $kb+1$ rows of the array. The j -th column of B is stored in the j -th column of the array BB as follows: if UPLO = 'U', $BB(ka+1+i-j,j) = B(i,j)$ for $\max(1, j-kb) \leq i \leq j$; if UPLO = 'L', $BB(1+i-j,j) = B(i,j)$ for $j \leq i \leq \min(n, j+kb)$.

On exit, the factor S from the split Cholesky factorization $B = S^*T^*S$, as returned by SPBSTF.

LDBB (input)
 The leading dimension of the array BB. $LDBB \geq KB+1$.

Q (output)
 If JOBZ = 'V', the n -by- n matrix used in the reduction of $A*x = (\lambda)*B*x$ to standard form, i.e. $C*x = (\lambda)*x$, and consequently C to tridiagonal form. If JOBZ = 'N', the array Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. If JOBZ = 'N', $LDQ \geq 1$. If JOBZ = 'V', $LDQ \geq \max(1, N)$.

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2*SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

If $INFO = 0$, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if $INFO = 0$, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized so $Z^*T*B*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension(7*N)

IWORK (workspace/output)

dimension(5*N)

IFAIL (input)

If JOBZ = 'V', then if $INFO = 0$, the first M elements of IFAIL are zero. If $INFO > 0$, then IFAIL contains the indices of the eigenvalues that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0 : successful exit
< 0 : if INFO = -i, the i-th argument had an illegal value
<= N: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in IFAIL. > N
: SPBSTF returned an error code; i.e., if INFO = N + i, for 1 <= i <= N, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

dsbmv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE DSBMV(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y,  
                INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER N, K, LDA, INCX, INCY  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), X(*), Y(*)
```

```
SUBROUTINE DSBMV_64(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y,  
                   INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, K, LDA, INCX, INCY  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE SBMV(UPLO, [N], K, ALPHA, A, [LDA], X, [INCX], BETA,  
               Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, K, LDA, INCX, INCY  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:) :: X, Y  
REAL(8), DIMENSION(:,) :: A
```

```
SUBROUTINE SBMV_64(UPLO, [N], K, ALPHA, A, [LDA], X, [INCX],  
                  BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, K, LDA, INCX, INCY  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:) :: X, Y  
REAL(8), DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>

void dsbmv(char uplo, int n, int k, double alpha, double *a,
           int lda, double *x, int incx, double beta, double
           *y, int incy);
void dsbmv_64(char uplo, long n, long k, double alpha, dou-
              ble *a, long lda, double *x, long incx, double
              beta, double *y, long incy);
```

PURPOSE

dsbmv performs the matrix-vector operation $y := \alpha A x + \beta y$, where α and β are scalars, x and y are n element vectors and A is an n by n symmetric band matrix, with k super-diagonals.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the band matrix A is being supplied as follows:

UPLO = 'U' or 'u' The upper triangular part of A is being supplied.

UPLO = 'L' or 'l' The lower triangular part of A is being supplied.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

K (input)

On entry, K specifies the number of super-diagonals of the matrix A . $K \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading ($k + 1$) by n part of the array A must contain the upper triangular band part of the symmetric matrix, supplied column by column, with the leading diagonal of the matrix in row ($k + 1$) of the array, the first super-diagonal starting at position 2 in row k , and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer the upper triangular part of a symmetric band matrix from

conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the symmetric matrix, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer the lower triangular part of a symmetric band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA \geq (k + 1). Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)). Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX \neq 0. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

dsbtrd - reduce a real symmetric band matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE DSBTRD(VECT, UPLO, N, KD, AB, LDAB, D, E, Q, LDQ, WORK,  
INFO)
```

```
CHARACTER * 1 VECT, UPLO  
INTEGER N, KD, LDAB, LDQ, INFO  
DOUBLE PRECISION AB(LDAB,*), D(*), E(*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE DSBTRD_64(VECT, UPLO, N, KD, AB, LDAB, D, E, Q, LDQ, WORK,  
INFO)
```

```
CHARACTER * 1 VECT, UPLO  
INTEGER*8 N, KD, LDAB, LDQ, INFO  
DOUBLE PRECISION AB(LDAB,*), D(*), E(*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBTRD(VECT, UPLO, [N], KD, AB, [LDAB], D, E, Q, [LDQ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO  
INTEGER :: N, KD, LDAB, LDQ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:,:) :: AB, Q
```

```
SUBROUTINE SBTRD_64(VECT, UPLO, [N], KD, AB, [LDAB], D, E, Q, [LDQ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO  
INTEGER(8) :: N, KD, LDAB, LDQ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:,:) :: AB, Q
```

C INTERFACE

```
#include <sunperf.h>

void dsbtrd(char vect, char uplo, int n, int kd, double *ab,
            int ldab, double *d, double *e, double *q, int
            ldq, int *info);

void dsbtrd_64(char vect, char uplo, long n, long kd, double
               *ab, long ldab, double *d, double *e, double *q,
               long ldq, long *info);
```

PURPOSE

dsbtrd reduces a real symmetric band matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation: $Q^{*T} * A * Q = T$.

ARGUMENTS

VECT (input)
 = 'N': do not form Q;
 = 'V': form Q;
 = 'U': update a matrix X, by forming X*Q.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. On exit, the diagonal elements of AB are overwritten by the diagonal elements of the tridiagonal matrix T; if $KD > 0$, the elements on the first superdiagonal (if UPLO = 'U') or the first subdiagonal (if UPLO = 'L') are overwritten by the off-diagonal elements of T; the rest of AB is overwritten by values generated during the reduction.

LDAB (input)
 The leading dimension of the array AB. $LDAB \geq KD+1$.

D (output)
 The diagonal elements of the tridiagonal matrix T.

E (output)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = T(i,i+1)$ if UPLO = 'U'; $E(i) = T(i+1,i)$ if UPLO = 'L'.

Q (input/output)

On entry, if VECT = 'U', then Q must contain an N-by-N matrix X; if VECT = 'N' or 'V', then Q need not be set.

On exit: if VECT = 'V', Q contains the N-by-N orthogonal matrix Q; if VECT = 'U', Q contains the product $X*Q$; if VECT = 'N', the array Q is not referenced.

LDQ (input)

The leading dimension of the array Q. LDQ ≥ 1 , and LDQ $\geq N$ if VECT = 'V' or 'U'.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Modified by Linda Kaufman, Bell Labs.

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NAME

dscal - Compute $y := \alpha * y$

SYNOPSIS

```
SUBROUTINE DSCAL(N, ALPHA, Y, INCY)

INTEGER N, INCY
DOUBLE PRECISION ALPHA
DOUBLE PRECISION Y(*)

SUBROUTINE DSCAL_64(N, ALPHA, Y, INCY)

INTEGER*8 N, INCY
DOUBLE PRECISION ALPHA
DOUBLE PRECISION Y(*)
```

F95 INTERFACE

```
SUBROUTINE SCAL([N], ALPHA, Y, [INCY])

INTEGER :: N, INCY
REAL(8) :: ALPHA
REAL(8), DIMENSION(:) :: Y

SUBROUTINE SCAL_64([N], ALPHA, Y, [INCY])

INTEGER(8) :: N, INCY
REAL(8) :: ALPHA
REAL(8), DIMENSION(:) :: Y
```

C INTERFACE

```
#include <sunperf.h>

void dscal(int n, double alpha, double *y, int incy);

void dscal_64(long n, double alpha, double *y, long incy);
```

PURPOSE

dscal Compute $y := \text{alpha} * y$ where alpha is a scalar and y is an n-vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * INCY). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. This routine returns immediately if INCY is less than or equal to zero. Unchanged on exit.

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NAME

dsctr - Scatters elements from x into y.

SYNOPSIS

```
SUBROUTINE DSCTR(NZ, X, INDX, Y)

DOUBLE PRECISION X(*), Y(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE DSCTR_64(NZ, X, INDX, Y)

DOUBLE PRECISION X(*), Y(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE SCTR([NZ], X, INDX, Y)

REAL(8), DIMENSION(:) :: X, Y
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE SCTR_64([NZ], X, INDX, Y)

REAL(8), DIMENSION(:) :: X, Y
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

DSCTR - Scatters the components of a sparse vector x stored in compressed form into specified components of a vector y in full storage form.

```
do i = 1, n
  y(indx(i)) = x(i)
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector containing the values to be scattered from
compressed form into full storage form. Unchanged
on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

Y (output)

Vector whose elements specified by indx have been
set to the corresponding entries of x. Only the
elements corresponding to the indices in indx have
been modified.

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NAME

dsdot - compute the double precision dot product of two single precision vectors `x` and `y`.

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DSDOT(N, X, INCX, Y, INCY)
```

```
INTEGER N, INCX, INCY  
REAL X(*), Y(*)
```

```
DOUBLE PRECISION FUNCTION DSDOT_64(N, X, INCX, Y, INCY)
```

```
INTEGER*8 N, INCX, INCY  
REAL X(*), Y(*)
```

F95 INTERFACE

```
REAL(8) FUNCTION DSDOT(N, X, INCX, Y, INCY)
```

```
INTEGER :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y
```

```
REAL(8) FUNCTION DSDOT_64(N, X, INCX, Y, INCY)
```

```
INTEGER(8) :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
double dsdot(int n, float *x, int incx, float *y, int incy);
```

```
double dsdot_64(long n, float *x, long incx, float *y, long  
incy);
```

PURPOSE

dsdot compute the double precision dot product of `x` and `y`

where x and y are single precision n -vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If N is not positive then the function returns the value 0.0. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . INCX must not be zero. Unchanged on exit.

Y (input)

($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array Y must contain the vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y . INCY must not be zero. Unchanged on exit.

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NAME

dsecnd - return the user time for a process in seconds

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DSECND()
```

```
DOUBLE PRECISION FUNCTION DSECND_64()
```

F95 INTERFACE

```
REAL(8) FUNCTION DSECND()
```

```
REAL(8) FUNCTION DSECND_64()
```

C INTERFACE

```
#include <sunperf.h>
```

```
double dsecnd();
```

```
double dsecnd_64();
```

PURPOSE

dsecnd returns the user time for a process in seconds. This version gets the time from the system function ETIME.

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NAME

dsinqb - synthesize a Fourier sequence from its representation in terms of a sine series with odd wave numbers. The SINQ operations are unnormalized inverses of themselves, so a call to SINQF followed by a call to SINQB will multiply the input sequence by $4 * N$.

SYNOPSIS

```
SUBROUTINE DSINQB(N, X, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION X(*), WSAVE(*)
```

```
SUBROUTINE DSINQB_64(N, X, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINQB([N], X, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE SINQB_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsinqb(int n, double *x, double *wsave);
```

```
void dsinqb_64(long n, double *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the quarter-wave sine synthesis of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$ for scalar subroutines, initialized by SINQI.

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NAME

dsinqf - compute the Fourier coefficients in a sine series representation with only odd wave numbers. The SINQ operations are unnormalized inverses of themselves, so a call to SINQF followed by a call to SINQB will multiply the input sequence by 4 * N.

SYNOPSIS

```
SUBROUTINE DSINQF(N, X, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION X(*), WSAVE(*)
```

```
SUBROUTINE DSINQF_64(N, X, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINQF([N], X, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE SINQF_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsinqf(int n, double *x, double *wsave);
```

```
void dsinqf_64(long n, double *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the quarter-wave sine transform of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$ for scalar subroutines, initialized by SINQI.

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NAME

dsinqi - initialize the array xWSAVE, which is used in both SINQF and SINQB.

SYNOPSIS

```
SUBROUTINE DSINQI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE DSINQI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINQI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE SINQI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void dsinqi(int n, double *wsave);

void dsinqi_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. The method is most efficient when N is a product of small primes.

WSAVE (input)

On entry, an array of dimension $(3 * N + 15)$ or greater. SINQI needs to be called only once to initialize WSAVE before calling SINQF and/or SINQB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

dsint - compute the discrete Fourier sine transform of an odd sequence. The SINT transforms are unnormalized inverses of themselves, so a call of SINT followed by another call of SINT will multiply the input sequence by $2 * (N+1)$.

SYNOPSIS

```
SUBROUTINE DSINT(N, X, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION X(*), WSAVE(*)
```

```
SUBROUTINE DSINT_64(N, X, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINT([N], X, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE SINT_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsint(int n, double *x, double *wsave);
```

```
void dsint_64(long n, double *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These

subroutines are most efficient when $N+1$ is a product of small primes. $N \geq 0$.

X (input/output)

On entry, an array of length N containing the sequence to be transformed. On exit, the sine transform of the input.

WSAVE (input/output)

On entry, an array with dimension of at least $\text{int}(2.5 * N + 15)$ initialized by SINTI.

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NAME

dsinti - initialize the array WSAVE, which is used in sub-routine SINT.

SYNOPSIS

```
SUBROUTINE DSINTI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE DSINTI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINTI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE SINTI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void dsinti(int n, double *wsave);

void dsinti_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input/output)

On entry, an array of dimension $(2N + N/2 + 15)$ or greater. SINTI is called once to initialize WSAVE before calling SINT and need not be called again between calls to SINT if N and WSAVE remain unchanged. Thus, subsequent transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

dsymm - Skyline format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DSKYMM( TRANSA, M, N, K, ALPHA, DESCRA,  
* VAL, PNTR,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER TRANSA, M, N, K, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER PNTR(*),  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DSKYMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
* VAL, PNTR,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8 TRANSA, M, N, K, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER*8 PNTR(*),  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
where NNZ = PNTR(K+1)-PNTR(1) (upper triangular)  
NNZ = PNTR(M+1)-PNTR(1) (lower triangular)  
PNTR() size = (K+1) (upper triangular)  
PNTR() size = (M+1) (lower triangular)
```

F95 INTERFACE

```
SUBROUTINE SKYMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL,  
* PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, PNTR  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE SKYMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL,  
* PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
```

```

INTEGER*8      TRANSA, M, K
INTEGER*8, DIMENSION(:) :: DESCRA, PNTR
DOUBLE PRECISION      ALPHA, BETA
DOUBLE PRECISION, DIMENSION(:) :: VAL
DOUBLE PRECISION, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>
void dskymm (int transa, int m, int n, int k, double alpha,
int *descra, double *val, int *pntr, double *b, int ldb,
double beta, double *c, int ldc);

void dskymm_64 (long transa, long m, long n, long k,
double alpha, long *descra, double *val, long *pntr,
double *b, long ldb, double beta, double *c, long ldc);

```

DESCRIPTION

dskymm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
 (' indicates matrix transpose),
 A is an M-by-K sparse matrix represented in the skyline format,
 alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, integer K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array. DESCRA(1) matrix structure 0 : general (NOT SUPPORTED) 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular

```

4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array consisting of
                 the nonzeros of A in skyline profile form.
                 Row-oriented if DESCRA(2) = 1 (lower triangular),
                 column oriented if DESCRA(2) = 2 (upper triangular).
                 Unchanged on exit.

PNTR (input)    On entry, INDX is an integer array of length
                 M+1 (lower triangular) or K+1 (upper triangular)
                 such that PNTR(I)-PNTR(1)+1 points to the
                 location in VAL of the first element of the skyline
                 profile in row (column) I. Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading k by n
                 part of the array B must contain the matrix B, otherwise
                 the leading m by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading m by n
                 part of the array C must contain the matrix C, otherwise
                 the leading k by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta*C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

The SKY data structure is not supported for a general matrix structure (*DESCRA*(1)=0).

Also not supported:

1. lower triangular matrix A of size m by n where $m > n$
2. upper triangular matrix A of size m by n where $m < n$

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NAME

dskysm - Skyline format triangular solve

SYNOPSIS

```
SUBROUTINE DSKYSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, PNTR,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER TRANSA, M, N, UNITD, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER PNTR(*),  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE DSKYSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, PNTR,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8 TRANSA, M, N, UNITD, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER*8 PNTR(*),  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTR(M+1)-PNTR(1)
PNTR() size = (M+1)

F95 INTERFACE

```
SUBROUTINE SKYSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, M, UNITD  
INTEGER, DIMENSION(:) :: DESCRA, PNTR  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE SKYSM_64( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA,  
* VAL, PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, M, UNITD  
INTEGER*8, DIMENSION(:) :: DESCRA, PNTR
```

```
DOUBLE PRECISION    ALPHA, BETA
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void dskysm (int transa, int m, int n, int unitd, double
 *dv, double alpha, int *descra, double *val, int *pntr,
 double *b, int ldb, double beta, double *c, int ldc);
void dskysm_64 (long transa, long m, long n, long unitd,
 double *dv, double alpha, long *descra, double *val, long
 *pntr, double *b, long ldb, double beta, double *c, long
 ldc);
```

DESCRIPTION

dskysm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C, \quad C \leftarrow -\alpha D \operatorname{op}(A) B + \beta C,$$

$$C \leftarrow \alpha \operatorname{op}(A) D B + \beta C,$$

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the skyline format and op(A) is one of

op(A) = inv(A) or op(A) = inv(A') or op(A) = inv(conjg(A'))
(inv denotes matrix inverse, ' indicates matrix transpose).

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
4 : Automatic row or column scaling (see section NOTES for further details)
Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the

diagonal entries of the scaling matrix D.
If UNITD is 4, DV contains diagonal matrix by which
the rows (columns) have been scaled (see section NOTES
for further details). Otherwise, unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array.
DESCRA(1) matrix structure
0 : general (NOT SUPPORTED)
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-unit
1 : unit

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL contains the nonzeros of A in skyline
profile form. Row-oriented if DESCRA(2) = 1 (lower
triangular), column oriented if DESCRA(2) = 2
(upper triangular). Unchanged on exit if UNITD is not 4.
Otherwise, VAL contains entries of D*A or A*D
(see section NOTES for further details).

PNTR (input) On entry, INDX is an integer array of length M+1 such
that PNTR(I)-PNTR(1)+1 points to the location in VAL
of the first element of the skyline profile in
row (column) I. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C
must contain the matrix C. On exit, the array C is
overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared
in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size
of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK

should be at least M.

For good performance, LWORK should generally be larger.
For optimum performance on multiple processors, LWORK
>=M*N_CPUS where N_CPUS is the maximum number of
processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the
routine only calculates the optimum size of the WORK array,
returns this value as the first entry of the WORK array,
and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is
fully compatible with NIST FORTRAN Sparse Blas but the sources are different.
Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas.
Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS)
Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included
in this routine. Such tests must be performed before calling
this routine.

2. If UNITD =4, the routine scales the rows of A if
DESCRA(2)=1 (lower triangular), and the columns of A if
DESCRA(2)=2 (upper triangular) such that their 2-norms are
one. The scaling may improve the accuracy of the computed
solution. Corresponding entries of VAL are changed only in
this particular case. On exit, DV matrix stored as a vector
contains the diagonal matrix by which the rows (columns)
have been scaled. UNITD=2 if *DESCRA*(2)=1 and UNITD=3 if
DESCRA(2)=2 should be used for the next calls to the routine
with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed
successfully, otherwise *WORK*(1) = -i where i is the row
(column) number which 2-norm is exactly zero.

3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are
each used with the mathematical value 1. The entries of the
main diagonal in the skyline representation of a sparse
matrix don't need to be referenced in this usage but they
need to be 1.0 if they are referenced. However if UNITD=4,
the unit diagonal elements with the mathematical value 1

MUST be referenced in the skyline representation.

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NAME

dspscon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric packed matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by DSPTRF

SYNOPSIS

```
SUBROUTINE DSPCON(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, IWORK2,  
INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
INTEGER IPIVOT(*), IWORK2(*)  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION A(*), WORK(*)
```

```
SUBROUTINE DSPCON_64(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, IWORK2,  
INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*), IWORK2(*)  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION A(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPCON(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [IWORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, IWORK2  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: A, WORK
```

```
SUBROUTINE SPCON_64(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK],  
[IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO
```

```
INTEGER(8), DIMENSION(:) :: IPIVOT, IWORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: A, WORK
```

C INTERFACE

```
#include <sunperf.h>
void dspcon(char uplo, int n, double *a, int *ipivot, double
            anorm, double *rcond, int *info);

void dspcon_64(char uplo, long n, double *a, long *ipivot,
              double anorm, double *rcond, long *info);
```

PURPOSE

dspcon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric packed matrix A using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by DSPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U*D*U^{**T}$;
= 'L': Lower triangular, form is $A = L*D*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) Double precision array, dimension $(N*(N+1)/2)$ The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by DSPTRF, stored as a packed triangular matrix.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by DSPTRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

Double precision array, dimension $(2*N)$

IWORK2 (workspace)

Integer array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dspev - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

SYNOPSIS

```
SUBROUTINE DSPEV(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, LDZ, INFO  
DOUBLE PRECISION AP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSPEV_64(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, LDZ, INFO  
DOUBLE PRECISION AP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPEV(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: AP, W, WORK  
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE SPEV_64(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: AP, W, WORK  
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dspev(char jobz, char uplo, int n, double *ap, double  
          *w, double *z, int ldz, int *info);
```

```
void dspev_64(char jobz, char uplo, long n, double *ap, dou-  
             ble *w, double *z, long ldz, long *info);
```

PURPOSE

dspev computes all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, AP is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

W (output)

Double precision array, dimension (N) If INFO = 0, the eigenvalues in ascending order.

Z (output)

Double precision array, dimension (LDZ, N) If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace)

Double precision array, dimension(3*N)

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

dspevd - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

SYNOPSIS

```
SUBROUTINE DSPEVD(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, LWORK, IWORK,
  LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER N, LDZ, LWORK, LIWORK, INFO
INTEGER IWORK(*)
DOUBLE PRECISION AP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSPEVD_64(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, LWORK,
  IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER*8 N, LDZ, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
DOUBLE PRECISION AP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPEVD(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [LWORK],
  [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER :: N, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: AP, W, WORK
REAL(8), DIMENSION(:,:) :: Z
```

```
SUBROUTINE SPEVD_64(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [LWORK],
  [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER(8) :: N, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: AP, W, WORK
REAL(8), DIMENSION(:,:) :: Z
```

C INTERFACE

```
#include <sunperf.h>

void dspevd(char jobz, char uplo, int n, double *ap, double
            *w, double *z, int ldz, int *info);
void dspevd_64(char jobz, char uplo, long n, double *ap,
               double *w, double *z, long ldz, long *info);
```

PURPOSE

dspevd computes all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, AP is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

W (output)

Double precision array, dimension (N) If INFO = 0, the eigenvalues in ascending order.

Z (input) Double precision array, dimension (LDZ, N) If JOBZ

= 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

WORK (workspace)

Real array, dimension (LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If N <= 1, LWORK must be at least 1. If JOBZ = 'N' and N > 1, LWORK must be at least 2*N. If JOBZ = 'V' and N > 1, LWORK must be at least 1 + 6*N + N**2.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

Integer array, dimension (LIWORK) On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If JOBZ = 'N' or N <= 1, LIWORK must be at least 1. If JOBZ = 'V' and N > 1, LIWORK must be at least 3 + 5*N.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

dspevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

SYNOPSIS

```
SUBROUTINE DSPEVX(JOBZ, RANGE, UPLO, N, AP, VL, VU, IL, IU, ABTOL,
                 NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, IL, IU, NFOUND, LDZ, INFO
INTEGER IWORK2(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION AP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSPEVX_64(JOBZ, RANGE, UPLO, N, AP, VL, VU, IL, IU, ABTOL,
                    NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, IL, IU, NFOUND, LDZ, INFO
INTEGER*8 IWORK2(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION AP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPEVX(JOBZ, RANGE, UPLO, [N], AP, VL, VU, IL, IU, ABTOL,
                NFOUND, W, Z, [LDZ], [WORK], [IWORK2], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK2, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: AP, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE SPEVX_64(JOBZ, RANGE, UPLO, [N], AP, VL, VU, IL, IU, ABTOL,
                   NFOUND, W, Z, [LDZ], [WORK], [IWORK2], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK2, IFAIL
```

```

REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: AP, W, WORK
REAL(8), DIMENSION(:, :) :: Z

```

C INTERFACE

```

#include <sunperf.h>
void dspevx(char jobz, char range, char uplo, int n, double
    *ap, double vl, double vu, int il, int iu, double
    abtol, int *nfound, double *w, double *z, int ldz,
    int *ifail, int *info);

void dspevx_64(char jobz, char range, char uplo, long n,
    double *ap, double vl, double vu, long il, long
    iu, double abtol, long *nfound, double *w, double
    *z, long ldz, long *ifail, long *info);

```

PURPOSE

dspevx computes selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage. Eigenvalues/vectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found;
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found; = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)
 Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, AP is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and

first subdiagonal of T overwrite the corresponding elements of A.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing AP to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2 * SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)

Double precision array, dimension (N) If $INFO = 0$, the selected eigenvalues in ascending order.

Z (output)

Double precision array, dimension (LDZ, $\max(1, M)$) If $JOBZ = 'V'$, then if $INFO = 0$, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. If an eigenvector fails to converge, then that column of Z con-

tains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, \text{NFOUND})$ columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq $\max(1, N)$.

WORK (workspace)

Double precision array, dimension(8*N)

IWORK2 (workspace)

Integer array, dimension(5*N)

IFAIL (output)

Integer array, dimension(N) If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

dspgst - reduce a real symmetric-definite generalized eigenproblem to standard form, using packed storage

SYNOPSIS

```
SUBROUTINE DSPGST(ITYPE, UPLO, N, AP, BP, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER ITYPE, N, INFO  
DOUBLE PRECISION AP(*), BP(*)
```

```
SUBROUTINE DSPGST_64(ITYPE, UPLO, N, AP, BP, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 ITYPE, N, INFO  
DOUBLE PRECISION AP(*), BP(*)
```

F95 INTERFACE

```
SUBROUTINE SPGST(ITYPE, UPLO, [N], AP, BP, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: ITYPE, N, INFO  
REAL(8), DIMENSION(:) :: AP, BP
```

```
SUBROUTINE SPGST_64(ITYPE, UPLO, [N], AP, BP, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: ITYPE, N, INFO  
REAL(8), DIMENSION(:) :: AP, BP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dspgst(int itype, char uplo, int n, double *ap, double  
            *bp, int *info);
```

```
void dspgst_64(long itype, char uplo, long n, double *ap,  
              double *bp, long *info);
```

PURPOSE

dspgst reduces a real symmetric-definite generalized eigenproblem to standard form, using packed storage.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $\text{inv}(U^{**T})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{**T})$

If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U^{**T}$ or $L^{**T}*A*L$.

B must have been previously factorized as $U^{**T}*U$ or $L*L^{**T}$ by `SPPTRF`.

ARGUMENTS

`ITYPE` (input)
= 1: compute $\text{inv}(U^{**T})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{**T})$;
= 2 or 3: compute $U*A*U^{**T}$ or $L^{**T}*A*L$.

`UPLO` (input)
= 'U': Upper triangle of A is stored and B is factored as $U^{**T}*U$; = 'L': Lower triangle of A is stored and B is factored as $L*L^{**T}$.

`N` (input) The order of the matrices A and B . $N \geq 0$.

`AP` (input/output)
Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A , packed columnwise in a linear array. The j -th column of A is stored in the array `AP` as follows: if `UPLO = 'U'`, $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if `UPLO = 'L'`, $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, if `INFO = 0`, the transformed matrix, stored in the same format as A .

`BP` (input)
Double precision array, dimension $(N*(N+1)/2)$ The triangular factor from the Cholesky factorization of B , stored in the same format as A , as returned by `SPPTRF`.

`INFO` (output)
= 0: successful exit
< 0: if `INFO = -i`, the i -th argument had an illegal value

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NAME

dspgv - compute all the eigenvalues and, optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE DSPGV(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER ITYPE, N, LDZ, INFO
DOUBLE PRECISION AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSPGV_64(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,
INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER*8 ITYPE, N, LDZ, INFO
DOUBLE PRECISION AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPGV(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ], [WORK],
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER :: ITYPE, N, LDZ, INFO
REAL(8), DIMENSION(:) :: AP, BP, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE SPGV_64(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ], [WORK],
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER(8) :: ITYPE, N, LDZ, INFO
REAL(8), DIMENSION(:) :: AP, BP, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dspgv(int itype, char jobz, char uplo, int n, double
           *ap, double *bp, double *w, double *z, int ldz,
           int *info);

void dspgv_64(long itype, char jobz, char uplo, long n, dou-
              ble *ap, double *bp, double *w, double *z, long
              ldz, long *info);

```

PURPOSE

dspgv computes all the eigenvalues and, optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric, stored in packed format, and B is also positive definite.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)*B*x$
- = 2: $A*B*x = (\lambda)*x$
- = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

- = 'U': Upper triangles of A and B are stored;
- = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

AP (input/output)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of A are destroyed.

BP (input/output)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPLO = 'U', $BP(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $BP(i + (j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U**T*U$ or $B = L*L**T$,

in the same storage format as B.

W (output)

Double precision array, dimension (N) If INFO = 0, the eigenvalues in ascending order.

Z (output)

Double precision array, dimension (LDZ, N) If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^{*T}BZ = I$; if ITYPE = 3, $Z^{*T}inv(B)Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

Double precision array, dimension(3*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: DPPTRF or DSPEV returned an error code:
<= N: if INFO = i, DSPEV failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero. > N: if INFO = n + i, for $1 \leq i \leq n$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

dspgvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE DSPGVD(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,
                 LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER ITYPE, N, LDZ, LWORK, LIWORK, INFO
INTEGER IWORK(*)
DOUBLE PRECISION AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSPGVD_64(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,
                    LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER*8 ITYPE, N, LDZ, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
DOUBLE PRECISION AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPGVD(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ], [WORK],
                [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER :: ITYPE, N, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: AP, BP, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE SPGVD_64(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ],
                   [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER(8) :: ITYPE, N, LDZ, LWORK, LIWORK, INFO
```

```
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: AP, BP, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>

void dspgvd(int itype, char jobz, char uplo, int n, double
            *ap, double *bp, double *w, double *z, int ldz,
            int *info);

void dspgvd_64(long itype, char jobz, char uplo, long n,
              double *ap, double *bp, double *w, double *z, long
              ldz, long *info);
```

PURPOSE

dspgvd computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric, stored in packed format, and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

ITYPE (input)
Specifies the problem type to be solved:
= 1: $A*x = (\lambda)*B*x$
= 2: $A*B*x = (\lambda)*x$
= 3: $B*A*x = (\lambda)*x$

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangles of A and B are stored;
= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

AP (input/output)
Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the

array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of AP are destroyed.

BP (input/output)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPLO = 'U', $BP(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $BP(i + (j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U**T*U$ or $B = L*L**T$, in the same storage format as B.

W (output)

Double precision array, dimension (N) If INFO = 0, the eigenvalues in ascending order.

Z (output)

Double precision array, dimension (LDZ, N) If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z**T*B*Z = I$; if ITYPE = 3, $Z**T*inv(B)*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace/output)

Double precision array, dimension (LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $N \leq 1$, $LWORK \geq 1$. If JOBZ = 'N' and $N > 1$, $LWORK \geq 2*N$. If JOBZ = 'V' and $N > 1$, $LWORK \geq 1 + 6*N + 2*N**2$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

Integer array, dimension (LIWORK) On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If JOBZ = 'N' or $N \leq 1$, $LIWORK \geq 1$. If JOBZ = 'V' and $N > 1$, $LIWORK \geq 3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed;

the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: DPPTRF or DSPEVD returned an error code:
<= N: if INFO = i, DSPEVD failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

dspgvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE DSPGVX(ITYPE, JOBZ, RANGE, UPLO, N, AP, BP, VL, VU, IL,
                 IU, ABSTOL, M, W, Z, LDZ, WORK, IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSPGVX_64(ITYPE, JOBZ, RANGE, UPLO, N, AP, BP, VL, VU, IL,
                   IU, ABSTOL, M, W, Z, LDZ, WORK, IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER*8 IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPGVX(ITYPE, JOBZ, RANGE, UPLO, [N], AP, BP, VL, VU, IL,
                IU, ABSTOL, M, W, Z, [LDZ], [WORK], [IWORK], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: AP, BP, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE SPGVX_64(ITYPE, JOBZ, RANGE, UPLO, [N], AP, BP, VL, VU,
                   IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [IWORK], IFAIL, [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: AP, BP, W, WORK
REAL(8), DIMENSION(:, :) :: Z

```

C INTERFACE

```

#include <sunperf.h>

void dspgvx(int itype, char jobz, char range, char uplo, int
            n, double *ap, double *bp, double vl, double vu,
            int il, int iu, double abstol, int *m, double *w,
            double *z, int ldz, int *ifail, int *info);

void dspgvx_64(long itype, char jobz, char range, char uplo,
              long n, double *ap, double *bp, double vl, double
              vu, long il, long iu, double abstol, long *m, dou-
              ble *w, double *z, long ldz, long *ifail, long
              *info);

```

PURPOSE

dspgvx computes selected eigenvalues, and optionally, eigen-
vectors of a real generalized symmetric-definite eigenprob-
lem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or
 $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric,
stored in packed storage, and B is also positive definite.
Eigenvalues and eigenvectors can be selected by specifying
either a range of values or a range of indices for the
desired eigenvalues.

ARGUMENTS

ITYPE (input)
Specifies the problem type to be solved:
= 1: $A*x = (\lambda)*B*x$
= 2: $A*B*x = (\lambda)*x$
= 3: $B*A*x = (\lambda)*x$

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval
(VL,VU] will be found. = 'I': the IL-th through
IU-th eigenvalues will be found.

UPLO (input)
= 'U': Upper triangle of A and B are stored;
= 'L': Lower triangle of A and B are stored.

N (input) The order of the matrix pencil (A,B). $N \geq 0$.

AP (input/output)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of AP are destroyed.

BP (input/output)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPLO = 'U', $BP(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $BP(i + (j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U**T*U$ or $B = L*L**T$, in the same storage format as B.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|) ,$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2*SLAMCH('S')$.

M (output)
The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)
Double precision array, dimension (N) On normal exit, the first M elements contain the selected eigenvalues in ascending order.

Z (output)
Double precision array, dimension (LDZ, max(1,M))
If JOBZ = 'N', then Z is not referenced. If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^T B Z = I$; if ITYPE = 3, $Z^T \text{inv}(B) Z = I$.

If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. Note: the user must ensure that at least max(1,M) columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)
The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace)
Double precision array, dimension(8*N)

IWORK (workspace)
Integer array, dimension(5*N)

IFAIL (output)
Integer array, dimension (N) If JOBZ = 'V', then if INFO = 0, the first M elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: DPPTRF or DSPEVX returned an error code:
<= N: if INFO = i, DSPEVX failed to converge; i eigenvectors failed to converge. Their indices are stored in array IFAIL. > N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

dspmv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE DSPMV(UPLO, N, ALPHA, A, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INCX, INCY  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(*), X(*), Y(*)
```

```
SUBROUTINE DSPMV_64(UPLO, N, ALPHA, A, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INCX, INCY  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE SPMV(UPLO, N, ALPHA, A, X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INCX, INCY  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:) :: A, X, Y
```

```
SUBROUTINE SPMV_64(UPLO, N, ALPHA, A, X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INCX, INCY  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:) :: A, X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dspmv(char uplo, int n, double alpha, double *a, double  
          *x, int incx, double beta, double *y, int incy);
```

```
void dspmv_64(char uplo, long n, double alpha, double *a,
              double *x, long incx, double beta, double *y, long
              incy);
```

PURPOSE

dspmv performs the matrix-vector operation $y := \alpha A x + \beta y$, where α and β are scalars, x and y are n element vectors and A is an n by n symmetric matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array A as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in A .

UPLO = 'L' or 'l' The lower triangular part of A is supplied in A .

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

$((n*(n+1))/2)$. Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular part of the symmetric matrix packed sequentially, column by column, so that $A(1)$ contains $a(1,1)$, $A(2)$ and $A(3)$ contain $a(1,2)$ and $a(2,2)$ respectively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular part of the symmetric matrix packed sequentially, column by column, so that $A(1)$ contains $a(1,1)$, $A(2)$ and $A(3)$ contain $a(2,1)$ and $a(3,1)$ respectively, and so on. Unchanged on exit.

X (input)

$(1 + (n-1)*\text{abs}(INCX))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . $INCX \neq 0$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

dspr - perform the symmetric rank 1 operation $A := \alpha x x' + A$

SYNOPSIS

```
SUBROUTINE DSPR(UPLO, N, ALPHA, X, INCX, A)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INCX  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), A(*)
```

```
SUBROUTINE DSPR_64(UPLO, N, ALPHA, X, INCX, A)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INCX  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), A(*)
```

F95 INTERFACE

```
SUBROUTINE SPR(UPLO, N, ALPHA, X, [INCX], A)
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INCX  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X, A
```

```
SUBROUTINE SPR_64(UPLO, N, ALPHA, X, [INCX], A)
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INCX  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X, A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dspr(char uplo, int n, double alpha, double *x, int  
incx, double *a);
```

```
void dspr_64(char uplo, long n, double alpha, double *x,
             long incx, double *a);
```

PURPOSE

dspr performs the symmetric rank 1 operation $A := \alpha x x^T + A$, where α is a real scalar, x is an n element vector and A is an n by n symmetric matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array A as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in A .

UPLO = 'L' or 'l' The lower triangular part of A is supplied in A .

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . $\text{INCX} \neq 0$. Unchanged on exit.

A (input/output)

$(n * (n + 1) / 2)$. Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular part of the symmetric matrix packed sequentially, column by column, so that $A(1)$ contains $a(1, 1)$, $A(2)$ and $A(3)$ contain $a(1, 2)$ and $a(2, 2)$ respectively, and so on. On exit, the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular part of the symmetric matrix packed sequentially, column by column, so that $A(1)$ contains $a(1, 1)$, $A(2)$ and $A(3)$ contain $a(2, 1)$ and $a(3, 1)$ respectively, and so on.

On exit, the array A is overwritten by the lower triangular part of the updated matrix.

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NAME

dspr2 - perform the symmetric rank 2 operation $A := \alpha x y' + \alpha y x' + A$

SYNOPSIS

```
SUBROUTINE DSPR2(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INCX, INCY  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), Y(*), AP(*)
```

```
SUBROUTINE DSPR2_64(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INCX, INCY  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), Y(*), AP(*)
```

F95 INTERFACE

```
SUBROUTINE SPR2(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], AP)
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INCX, INCY  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X, Y, AP
```

```
SUBROUTINE SPR2_64(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], AP)
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INCX, INCY  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X, Y, AP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dspr2(char uplo, int n, double alpha, double *x, int  
incx, double *y, int incy, double *ap);
```

```
void dspr2_64(char uplo, long n, double alpha, double *x,
              long incx, double *y, long incy, double *ap);
```

PURPOSE

dspr2 performs the symmetric rank 2 operation $A := \alpha x x^T + \alpha y y^T + A$, where alpha is a scalar, x and y are n element vectors and A is an n by n symmetric matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array AP as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in AP.

UPLO = 'L' or 'l' The lower triangular part of A is supplied in AP.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

Double precision array, dimension $(1 + (n - 1) * \text{abs}(\text{INCX}))$ Before entry, the incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

Double precision array, dimension $(1 + (n - 1) * \text{abs}(\text{INCY}))$ Before entry, the incremented array Y must contain the n element vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

AP (input/output)

Double precision array, dimension $((n * (n + 1)) / 2)$ Before entry with UPLO = 'U' or 'u', the array AP must contain the upper triangular part of the sym-

metric matrix packed sequentially, column by column, so that AP(1) contains a(1, 1), AP(2) and AP(3) contain a(1, 2) and a(2, 2) respectively, and so on. On exit, the array AP is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'U' or 'u', the array AP must contain the lower triangular part of the symmetric matrix packed sequentially, column by column, so that AP(1) contains a(1, 1), AP(2) and AP(3) contain a(2, 1) and a(3, 1) respectively, and so on. On exit, the array AP is overwritten by the lower triangular part of the updated matrix.

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NAME

dsprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE DSPRFS(UPLO, N, NRHS, AP, AF, IPIVOT, B, LDB, X, LDX, FERR,  
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, LDX, INFO  
INTEGER IPIVOT(*), WORK2(*)  
DOUBLE PRECISION AP(*), AF(*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE DSPRFS_64(UPLO, N, NRHS, AP, AF, IPIVOT, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*), WORK2(*)  
DOUBLE PRECISION AP(*), AF(*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPRFS(UPLO, [N], [NRHS], AP, AF, IPIVOT, B, [LDB], X, [LDX],  
  FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, WORK2  
REAL(8), DIMENSION(:) :: A, AF, FERR, BERR, WORK  
REAL(8), DIMENSION(:, :) :: B, X
```

```
SUBROUTINE SPRFS_64(UPLO, [N], [NRHS], AP, AF, IPIVOT, B, [LDB], X, [LDX],  
  FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

```

INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL(8), DIMENSION(:) :: AP, AF, FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: B, X

```

C INTERFACE

```

#include <sunperf.h>
void dsprfs(char uplo, int n, int nrhs, double *ap, double
            *af, int *ipivot, double *b, int ldb, double *x,
            int ldx, double *ferr, double *berr, int *info);

void dsprfs_64(char uplo, long n, long nrhs, double *ap,
              double *af, long *ipivot, double *b, long ldb,
              double *x, long ldx, double *ferr, double *berr,
              long *info);

```

PURPOSE

dsprfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

AP (input)

Double precision array, dimension $(N*(N+1)/2)$ The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

AF (input)

Double precision array, dimension $(N*(N+1)/2)$ The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U**T$ or $A = L*D*L**T$ as computed by DSPTRF, stored as a packed triangular matrix.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by DSPTRF.

B (input) Double precision array, dimension (LDB,NRHS) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

X (input/output)
Double precision array, dimension (LDX,NRHS) On entry, the solution matrix X, as computed by DSPTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX >= max(1,N).

FERR (output)
Double precision array, dimension (NRHS) The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
Double precision array, dimension (NRHS) The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
Double precision array, dimension(3*N)

WORK2 (workspace)
Integer array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dspsv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DSPSV(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION A(*), B(LDB,*)
```

```
SUBROUTINE DSPSV_64(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION A(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SPSV(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: A  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE SPSV_64(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: A  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dspsv(char uplo, int n, int nrhs, double *a, int
           *ipivot, double *b, int ldb, int *info);
```

```
void dspsv_64(char uplo, long n, long nrhs, double *a, long
              *ipivot, double *b, long ldb, long *info);
```

PURPOSE

dspsv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{**T}$, if UPLO = 'U', or

$A = L * D * L^{**T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by DSPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (output)

Integer array, dimension (N) Details of the interchanges and the block structure of D, as determined by DSPTRF. If IPIVOT(k) > 0, then rows

and columns k and $\text{IPIVOT}(k)$ were interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $\text{UPLO} = 'U'$ and $\text{IPIVOT}(k) = \text{IPIVOT}(k-1) < 0$, then rows and columns $k-1$ and $-\text{IPIVOT}(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $\text{UPLO} = 'L'$ and $\text{IPIVOT}(k) = \text{IPIVOT}(k+1) < 0$, then rows and columns $k+1$ and $-\text{IPIVOT}(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output)

Double precision array, dimension (LDB, NRHS) On entry, the N-by-NRHS right hand side matrix B. On exit, if $\text{INFO} = 0$, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $\text{LDB} \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value
> 0: if $\text{INFO} = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, $\text{UPLO} = 'U'$:

Two-dimensional storage of the symmetric matrix A:

```
  a11 a12 a13 a14
    a22 a23 a24
      a33 a34   (aij = aji)
        a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

dspsvx - use the diagonal pivoting factorization $A = U^*D*U^{**T}$ or $A = L^*D*L^{**T}$ to compute the solution to a real system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE DSPSVX(FACT, UPLO, N, NRHS, AP, AF, IPIVOT, B, LDB, X, LDX,
                  RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION AP(*), AF(*), B(LDB,*), X(LDX,*), FERR(*),
BERR(*), WORK(*)
```

```
SUBROUTINE DSPSVX_64(FACT, UPLO, N, NRHS, AP, AF, IPIVOT, B, LDB, X,
                    LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION AP(*), AF(*), B(LDB,*), X(LDX,*), FERR(*),
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPSVX(FACT, UPLO, [N], [NRHS], AP, AF, IPIVOT, B, [LDB], X,
                [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: AP, AF, FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: B, X
```

```
SUBROUTINE DSPSVX_64(FACT, UPLO, [N], [NRHS], AP, AF, IPIVOT, B, [LDB], X,
    [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: AP, AF, FERR, BERR, WORK
REAL(8), DIMENSION(:,:) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dspsvx(char fact, char uplo, int n, int nrhs, double
    *a, double *af, int *ipivot, double *b, int ldb,
    double *x, int ldx, double *rcond, double *ferr,
    double *berr, int *info);
```

```
void dspsvx_64(char fact, char uplo, long n, long nrhs, dou-
    ble *a, double *af, long *ipivot, double *b, long
    ldb, double *x, long ldx, double *rcond, double
    *ferr, double *berr, long *info);
```

PURPOSE

DSPSVX uses the diagonal pivoting factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ to compute the solution to a real system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'N', the diagonal pivoting method is used to factor A as

$$A = U * D * U^{**T}, \text{ if UPLO = 'U', or}$$

$$A = L * D * L^{**T}, \text{ if UPLO = 'L',}$$

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices and D is symmetric and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with INFO = i. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

3. The system of equations is solved for X using the fac-

tored form
of A.
4. Iterative refinement is applied to improve the computed
solution
matrix and calculate error bounds and backward error
estimates
for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. AP, AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

AP (input)

Double precision array, dimension $(N*(N+1)/2)$ The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

AF (input or output)

Double precision array, dimension $(N*(N+1)/2)$ If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by DSPTRF, stored as a packed triangular matrix in the same storage format as A.

If FACT = 'N', then AF is an output argument and on exit contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by DSPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (input or output)

Integer array, dimension (N) If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by DSPTRF. If IPIVOT(k)

> 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

If FACT = 'N', then IPIVOT is an output argument and on exit contains details of the interchanges and the block structure of D, as determined by DSPTRF.

B (input) Double precision array, dimension (LDB, NRHS) The N-by-NRHS right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

X (output)
Double precision array, dimension (LDX, NRHS) If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)
The leading dimension of the array X. LDX >= max(1,N).

RCOND (output)
The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)
Double precision array, dimension (NRHS) The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
Double precision array, dimension (NRHS) The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
Double precision array, dimension(3*N)

```

WORK2 (workspace)
    Integer array, dimension(N)

INFO (output)
    = 0: successful exit
    < 0: if INFO = -i, the i-th argument had an illegal value
    > 0: if INFO = i, and i is
    <= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

```

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, $UPLO = 'U'$:

Two-dimensional storage of the symmetric matrix A:

```

a11 a12 a13 a14
  a22 a23 a24
    a33 a34   (aij = aji)
      a44

```

Packed storage of the upper triangle of A:

```

AP = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]

```

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NAME

dsptrd - reduce a real symmetric matrix A stored in packed form to symmetric tridiagonal form T by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE DSPTRD(UPLO, N, AP, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
DOUBLE PRECISION AP(*), D(*), E(*), TAU(*)
```

```
SUBROUTINE DSPTRD_64(UPLO, N, AP, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
DOUBLE PRECISION AP(*), D(*), E(*), TAU(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRD(UPLO, [N], AP, D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
REAL(8), DIMENSION(:) :: AP, D, E, TAU
```

```
SUBROUTINE SPTRD_64(UPLO, [N], AP, D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
REAL(8), DIMENSION(:) :: AP, D, E, TAU
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsptrd(char uplo, int n, double *ap, double *d, double  
            *e, double *tau, int *info);
```

```
void dsptrd_64(char uplo, long n, double *ap, double *d,
```

```
double *e, double *tau, long *info);
```

PURPOSE

dsptd reduces a real symmetric matrix A stored in packed form to symmetric tridiagonal form T by an orthogonal similarity transformation: $Q^*T * A * Q = T$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors. See Further Details.

D (output)

Double precision array, dimension (N) The diagonal elements of the tridiagonal matrix T: $D(i) = A(i,i)$.

E (output)

Double precision array, dimension (N-1) The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i,i+1)$ if UPLO = 'U', $E(i) = A(i+1,i)$ if UPLO = 'L'.

TAU (output)

Double precision array, dimension (N-1) The scalar factors of the elementary reflectors (see Further Details).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-

gal value

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(i+1:n) = 0$ and $v(i) = 1$; $v(1:i-1)$ is stored on exit in AP, overwriting $A(1:i-1,i+1)$, and tau is stored in TAU(i).

If UPLO = 'L', the matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(1:i) = 0$ and $v(i+1) = 1$; $v(i+2:n)$ is stored on exit in AP, overwriting $A(i+2:n,i)$, and tau is stored in TAU(i).

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NAME

dsptrf - compute the factorization of a real symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE DSPTRF(UPLO, N, AP, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION AP(*)
```

```
SUBROUTINE DSPTRF_64(UPLO, N, AP, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION AP(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRF(UPLO, [N], AP, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: AP
```

```
SUBROUTINE SPTRF_64(UPLO, [N], AP, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: AP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsptf(char uplo, int n, double *ap, int *ipivot, int
           *info);
```

```
void dsptf_64(char uplo, long n, double *ap, long *ipivot,
              long *info);
```

PURPOSE

dsptf computes the factorization of a real symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U^{**T} \quad \text{or} \quad A = L^*D^*L^{**T}$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)
Double precision array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L, stored as a packed triangular matrix overwriting A (see below for further details).

IPIVOT (output)
Integer array, dimension (N) Details of the interchanges and the block structure of D. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged and $D(k,k)$ is a 1-by-1 diagonal block. If UPLO = 'U' and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns k-1 and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If UPLO = 'L' and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns k+1 and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an

illegal value
 > 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

5-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by IPIVOT(k), and $U(k)$ is a unit upper triangular matrix, such that if the diagonal block $D(k)$ is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(1:k-1,k)$. If s = 2, the upper triangle of $D(k)$ overwrites $A(k-1,k-1)$, $A(k-1,k)$, and $A(k,k)$, and v overwrites $A(1:k-2,k-1:k)$.

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by IPIVOT(k), and $L(k)$ is a unit lower triangular matrix, such that if the diagonal block $D(k)$ is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(k+1:n,k)$. If s = 2, the lower triangle of $D(k)$ overwrites $A(k,k)$, $A(k+1,k)$, and $A(k+1,k+1)$, and v overwrites $A(k+2:n,k:k+1)$.

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NAME

dsptri - compute the inverse of a real symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^*T$ or $A = L^*D^*L^*T$ computed by DSPTRF

SYNOPSIS

```
SUBROUTINE DSPTRI(UPLO, N, AP, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION AP(*), WORK(*)
```

```
SUBROUTINE DSPTRI_64(UPLO, N, AP, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION AP(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRI(UPLO, [N], AP, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: AP, WORK
```

```
SUBROUTINE SPTRI_64(UPLO, [N], AP, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: AP, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsptri(char uplo, int n, double *a, int *ipivot, int  
*info);
```

```
void dsptri_64(char uplo, long n, double *a, long *ipivot,
              long *info);
```

PURPOSE

dsptri computes the inverse of a real symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by DSPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U^*D^*U^{**T}$;
= 'L': Lower triangular, form is $A = L^*D^*L^{**T}$.

N (input) The order of the matrix A . $N \geq 0$.

AP (input/output)

Double precision array, dimension $(N*(N+1)/2)$ On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by DSPTRF, stored as a packed triangular matrix.

On exit, if $INFO = 0$, the (symmetric) inverse of the original matrix, stored as a packed triangular matrix. The j -th column of $inv(A)$ is stored in the array AP as follows: if $UPLO = 'U'$, $AP(i + (j-1)*j/2) = inv(A)(i,j)$ for $1 \leq i \leq j$; if $UPLO = 'L'$, $AP(i + (j-1)*(2n-j)/2) = inv(A)(i,j)$ for $j \leq i \leq n$.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by DSPTRF.

WORK (workspace)

Double precision array, dimension (N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

dspttrs - solve a system of linear equations $A \cdot X = B$ with a real symmetric matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^{*T}$ or $A = L \cdot D \cdot L^{*T}$ computed by DSPTRF

SYNOPSIS

```
SUBROUTINE DSPTRS(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION AP(*), B(LDB,*)
```

```
SUBROUTINE DSPTRS_64(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION AP(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SPTRS(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: AP  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE SPTRS_64(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: AP  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dsptrs(char uplo, int n, int nrhs, double *ap, int
            *ipivot, double *b, int ldb, int *info);

void dsptrs_64(char uplo, long n, long nrhs, double *ap,
               long *ipivot, double *b, long ldb, long *info);

```

PURPOSE

dsptrs solves a system of linear equations $A \cdot X = B$ with a real symmetric matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^{**T}$ or $A = L \cdot D \cdot L^{**T}$ computed by DSPTRF.

ARGUMENTS

UPLO (input)
 Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U \cdot D \cdot U^{**T}$;
 = 'L': Lower triangular, form is $A = L \cdot D \cdot L^{**T}$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

AP (input)
 Double precision array, dimension $(N \cdot (N+1) / 2)$ The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by DSPTRF, stored as a packed triangular matrix.

IPIVOT (input)
 Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by DSPTRF.

B (input/output)
 Double precision array, dimension $(LDB, NRHS)$ On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)
 The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)
 = 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

dstebz - compute the eigenvalues of a symmetric tridiagonal matrix T

SYNOPSIS

```
SUBROUTINE DSTEBZ(RANGE, ORDER, N, VL, VU, IL, IU, ABSTOL, D, E, M,  
                 NSPLIT, W, IBLOCK, ISPLIT, WORK, IWORK, INFO)
```

```
CHARACTER * 1 RANGE, ORDER  
INTEGER N, IL, IU, M, NSPLIT, INFO  
INTEGER IBLOCK(*), ISPLIT(*), IWORK(*)  
DOUBLE PRECISION VL, VU, ABSTOL  
DOUBLE PRECISION D(*), E(*), W(*), WORK(*)
```

```
SUBROUTINE DSTEBZ_64(RANGE, ORDER, N, VL, VU, IL, IU, ABSTOL, D, E,  
                   M, NSPLIT, W, IBLOCK, ISPLIT, WORK, IWORK, INFO)
```

```
CHARACTER * 1 RANGE, ORDER  
INTEGER*8 N, IL, IU, M, NSPLIT, INFO  
INTEGER*8 IBLOCK(*), ISPLIT(*), IWORK(*)  
DOUBLE PRECISION VL, VU, ABSTOL  
DOUBLE PRECISION D(*), E(*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEBZ(RANGE, ORDER, N, VL, VU, IL, IU, ABSTOL, D, E, M,  
               NSPLIT, W, IBLOCK, ISPLIT, [WORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: RANGE, ORDER  
INTEGER :: N, IL, IU, M, NSPLIT, INFO  
INTEGER, DIMENSION(:) :: IBLOCK, ISPLIT, IWORK  
REAL(8) :: VL, VU, ABSTOL  
REAL(8), DIMENSION(:) :: D, E, W, WORK
```

```
SUBROUTINE STEBZ_64(RANGE, ORDER, N, VL, VU, IL, IU, ABSTOL, D, E, M,  
                  NSPLIT, W, IBLOCK, ISPLIT, [WORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: RANGE, ORDER  
INTEGER(8) :: N, IL, IU, M, NSPLIT, INFO  
INTEGER(8), DIMENSION(:) :: IBLOCK, ISPLIT, IWORK  
REAL(8) :: VL, VU, ABSTOL
```

```
REAL(8), DIMENSION(:) :: D, E, W, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dstebz(char range, char order, int n, double vl, double  
    vu, int il, int iu, double abstol, double *d,  
    double *e, int *m, int *nsplit, double *w, int  
    *iblock, int *isplit, int *info);
```

```
void dstebz_64(char range, char order, long n, double vl,  
    double vu, long il, long iu, double abstol, double  
    *d, double *e, long *m, long *nsplit, double *w,  
    long *iblock, long *isplit, long *info);
```

PURPOSE

dstebz computes the eigenvalues of a symmetric tridiagonal matrix T. The user may ask for all eigenvalues, all eigenvalues in the half-open interval (VL, VU], or the IL-th through IU-th eigenvalues.

To avoid overflow, the matrix must be scaled so that its largest element is no greater than $\text{overflow}^{1/2} * \text{underflow}^{1/4}$ in absolute value, and for greatest accuracy, it should not be much smaller than that.

See W. Kahan "Accurate Eigenvalues of a Symmetric Tridiagonal Matrix", Report CS41, Computer Science Dept., Stanford University, July 21, 1966.

ARGUMENTS

RANGE (input)

= 'A': ("All") all eigenvalues will be found.
= 'V': ("Value") all eigenvalues in the half-open interval (VL, VU] will be found. = 'I': ("Index") the IL-th through IU-th eigenvalues (of the entire matrix) will be found.

ORDER (input)

= 'B': ("By Block") the eigenvalues will be grouped by split-off block (see IBLOCK, ISPLIT) and ordered from smallest to largest within the block. = 'E': ("Entire matrix") the eigenvalues for the entire matrix will be ordered from smallest to largest.

N (input) The order of the tridiagonal matrix T. $N \geq 0$.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. Eigenvalues less than or equal to VL, or greater than VU, will not be returned. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
See the description of VL.

IL (input)
If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
See the description of IL.

ABSTOL (input)
The absolute tolerance for the eigenvalues. An eigenvalue (or cluster) is considered to be located if it has been determined to lie in an interval whose width is ABSTOL or less. If ABSTOL is less than or equal to zero, then $ULP*|T|$ will be used, where $|T|$ means the 1-norm of T.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero.

D (input) The n diagonal elements of the tridiagonal matrix T.

E (input) The (n-1) off-diagonal elements of the tridiagonal matrix T.

M (output)
The actual number of eigenvalues found. $0 \leq M \leq N$. (See also the description of INFO=2,3.)

NSPLIT (output)
The number of diagonal blocks in the matrix T. $1 \leq NSPLIT \leq N$.

W (output)
On exit, the first M elements of W will contain the eigenvalues. (DSTEBZ may use the remaining N-M elements as workspace.)

IBLOCK (output)
At each row/column j where E(j) is zero or small, the matrix T is considered to split into a block diagonal matrix. On exit, if INFO = 0, IBLOCK(i) specifies to which block (from 1 to the number of blocks) the eigenvalue W(i) belongs. (DSTEBZ may use the remaining N-M elements as workspace.)

ISPLIT (output)
The splitting points, at which T breaks up into submatrices. The first submatrix consists of rows/columns 1 to ISPLIT(1), the second of rows/columns ISPLIT(1)+1 through ISPLIT(2), etc., and the NSPLIT-th consists of rows/columns ISPLIT(NSPLIT-1)+1 through ISPLIT(NSPLIT)=N. (Only the first NSPLIT elements will actually be

used, but since the user cannot know a priori what value NSPLIT will have, N words must be reserved for ISPLIT.)

WORK (workspace)
dimension(4*N)

IWORK (workspace)
dimension(3*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: some or all of the eigenvalues failed to converge or were not computed:
=1 or 3: Bisection failed to converge for some eigenvalues; these eigenvalues are flagged by a negative block number. The effect is that the eigenvalues may not be as accurate as the absolute and relative tolerances. This is generally caused by unexpectedly inaccurate arithmetic. =2 or 3: RANGE='I' only: Not all of the eigenvalues IL:IU were found.
Effect: $M < IU+1-IL$
Cause: non-monotonic arithmetic, causing the Sturm sequence to be non-monotonic. Cure: recalculate, using RANGE='A', and pick out eigenvalues IL:IU. = 4: RANGE='I', and the Gershgorin interval initially used was too small. No eigenvalues were computed.

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NAME

dstedc - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method

SYNOPSIS

```
SUBROUTINE DSTEDC(COMPZ, N, D, E, Z, LDZ, WORK, LWORK, IWORK, LIWORK,
                 INFO)
```

```
CHARACTER * 1 COMPZ
INTEGER N, LDZ, LWORK, LIWORK, INFO
INTEGER IWORK(*)
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSTEDC_64(COMPZ, N, D, E, Z, LDZ, WORK, LWORK, IWORK,
                    LIWORK, INFO)
```

```
CHARACTER * 1 COMPZ
INTEGER*8 N, LDZ, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEDC(COMPZ, N, D, E, Z, [LDZ], [WORK], [LWORK], [IWORK],
                [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ
INTEGER :: N, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: D, E, WORK
REAL(8), DIMENSION(:,:) :: Z
```

```
SUBROUTINE STEDC_64(COMPZ, N, D, E, Z, [LDZ], [WORK], [LWORK], [IWORK],
                   [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ
INTEGER(8) :: N, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
```

```
REAL(8), DIMENSION(:) :: D, E, WORK
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dstedc(char compz, int n, double *d, double *e, double
            *z, int ldz, int *info);
```

```
void dstedc_64(char compz, long n, double *d, double *e,
               double *z, long ldz, long *info);
```

PURPOSE

dstedc computes all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method. The eigenvectors of a full or band real symmetric matrix can also be found if SSYTRD or SSPTRD or SSBTRD has been used to reduce this matrix to tridiagonal form.

This code makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none. See SLAED3 for details.

ARGUMENTS

COMPZ (input)

= 'N': Compute eigenvalues only.
= 'I': Compute eigenvectors of tridiagonal matrix also.
= 'V': Compute eigenvectors of original dense symmetric matrix also. On entry, Z contains the orthogonal matrix used to reduce the original matrix to tridiagonal form.

N (input) The dimension of the symmetric tridiagonal matrix.
N >= 0.

D (input/output)

On entry, the diagonal elements of the tridiagonal matrix. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)

On entry, the subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input) On entry, if COMPZ = 'V', then Z contains the orthogonal matrix used in the reduction to tridiagonal form. On exit, if INFO = 0, then if COMPZ = 'V', Z contains the orthonormal eigenvectors of the original symmetric matrix, and if COMPZ = 'I',

Z contains the orthonormal eigenvectors of the symmetric tridiagonal matrix. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1.
If eigenvectors are desired, then LDZ \geq max(1,N).

WORK (workspace)

dimension (LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If COMPZ = 'N' or $N \leq 1$ then LWORK must be at least 1. If COMPZ = 'V' and $N > 1$ then LWORK must be at least $(1 + 3*N + 2*N*\lg N + 3*N**2)$, where $\lg(N)$ = smallest integer k such that $2**k \geq N$. If COMPZ = 'I' and $N > 1$ then LWORK must be at least $(1 + 4*N + N**2)$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If COMPZ = 'N' or $N \leq 1$ then LIWORK must be at least 1. If COMPZ = 'V' and $N > 1$ then LIWORK must be at least $(6 + 6*N + 5*N*\lg N)$. If COMPZ = 'I' and $N > 1$ then LIWORK must be at least $(3 + 5*N)$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: The algorithm failed to compute an eigenvalue while working on the submatrix lying in rows and columns INFO/(N+1) through mod(INFO,N+1).

FURTHER DETAILS

Based on contributions by

Jeff Rutter, Computer Science Division, University of California

at Berkeley, USA

Modified by Francoise Tisseur, University of Tennessee.

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NAME

dsteqr - (a) Compute $T\text{-}\sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation

SYNOPSIS

```
SUBROUTINE DSTEGR(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M, W,  
  Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
INTEGER N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER ISUPPZ(*), IWORK(*)  
DOUBLE PRECISION VL, VU, ABSTOL  
DOUBLE PRECISION D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSTEGR_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
INTEGER*8 N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 ISUPPZ(*), IWORK(*)  
DOUBLE PRECISION VL, VU, ABSTOL  
DOUBLE PRECISION D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEGR(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE  
INTEGER :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: ISUPPZ, IWORK  
REAL(8) :: VL, VU, ABSTOL  
REAL(8), DIMENSION(:) :: D, E, W, WORK  
REAL(8), DIMENSION(:,:) :: Z
```

```
SUBROUTINE STEGR_64(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL,  
  M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE
```

```

INTEGER(8) :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: D, E, W, WORK
REAL(8), DIMENSION(:, :) :: Z

```

C INTERFACE

```

#include <sunperf.h>
void dstegr(char jobz, char range, int n, double *d, double
            *e, double vl, double vu, int il, int iu, double
            abstol, int *m, double *w, double *z, int ldz, int
            *isuppz, int *info);

void dstegr_64(char jobz, char range, long n, double *d,
              double *e, double vl, double vu, long il, long iu,
              double abstol, long *m, double *w, double *z, long
              ldz, long *isuppz, long *info);

```

PURPOSE

dstegr b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high relative accuracy by the dqds algorithm,

(c) If there is a cluster of close eigenvalues, "choose" σ_i close to the cluster, and go to step (a),

(d) Given the approximate eigenvalue λ_j of $L_i D_i L_i^T$, compute the corresponding eigenvector by forming a rank-revealing twisted factorization.

The desired accuracy of the output can be specified by the input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB/CSD-97-971, UC Berkeley, May 1997.

Note 1 : Currently DSTEGR is only set up to find ALL the n eigenvalues and eigenvectors of T in $O(n^2)$ time

Note 2 : Currently the routine DSTEIN is called when an appropriate σ_i cannot be chosen in step (c) above. DSTEIN invokes modified Gram-Schmidt when eigenvalues are close.

Note 3 : DSTEGR works only on machines which follow ieee-754 floating-point standard in their handling of infinities and NaNs. Normal execution of DSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not conform to the ieee standard.

ARGUMENTS

```

JOBZ (input)
    = 'N': Compute eigenvalues only;
    = 'V': Compute eigenvalues and eigenvectors.

```

RANGE (input)
 = 'A': all eigenvalues will be found.
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)
 On entry, the n diagonal elements of the tridiagonal matrix T. On exit, D is overwritten.

E (input/output)
 On entry, the (n-1) subdiagonal elements of the tridiagonal matrix T in elements 1 to N-1 of E; E(N) need not be set. On exit, E is overwritten.

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 See the description of VL.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 See the description of IL.

ABSTOL (input)
 The absolute error tolerance for the eigenvalues/eigenvectors. If JOBZ = 'V', the eigenvalues and eigenvectors output have residual norms bounded by ABSTOL, and the dot products between different eigenvectors are bounded by ABSTOL. If ABSTOL is less than $N \cdot \text{EPS} \cdot |T|$, then $N \cdot \text{EPS} \cdot |T|$ will be used in its place, where EPS is the machine precision and $|T|$ is the 1-norm of the tridiagonal matrix. The eigenvalues are computed to an accuracy of $\text{EPS} \cdot |T|$ irrespective of ABSTOL. If high relative accuracy is important, set ABSTOL to DLAMCH('Safe minimum'). See Barlow and Demmel "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7 for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)
 The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)
 The first M elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix T corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least max(1,M) columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)
The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

ISUPPZ (output)
The support of the eigenvectors in Z, i.e., the indices indicating the nonzero elements in Z. The i-th eigenvector is nonzero only in elements ISUPPZ(2*i-1) through ISUPPZ(2*i).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal (and minimal) LWORK.

LWORK (input)
The dimension of the array WORK. LWORK >= max(1,18*N)
If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)
On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
The dimension of the array IWORK. LIWORK >= max(1,10*N)

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = 1, internal error in SLARRE, if INFO = 2, internal error in SLARRV.

FURTHER DETAILS

Based on contributions by
Inderjit Dhillon, IBM Almaden, USA

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NAME

dstein - compute the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration

SYNOPSIS

```
SUBROUTINE DSTEIN(N, D, E, M, W, IBLOCK, ISPLIT, Z, LDZ, WORK, IWORK,
                IFAIL, INFO)
```

```
INTEGER N, M, LDZ, INFO
INTEGER IBLOCK(*), ISPLIT(*), IWORK(*), IFAIL(*)
DOUBLE PRECISION D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSTEIN_64(N, D, E, M, W, IBLOCK, ISPLIT, Z, LDZ, WORK,
                   IWORK, IFAIL, INFO)
```

```
INTEGER*8 N, M, LDZ, INFO
INTEGER*8 IBLOCK(*), ISPLIT(*), IWORK(*), IFAIL(*)
DOUBLE PRECISION D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEIN(N, D, E, M, W, IBLOCK, ISPLIT, Z, [LDZ], [WORK],
               [IWORK], IFAIL, [INFO])
```

```
INTEGER :: N, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IBLOCK, ISPLIT, IWORK, IFAIL
REAL(8), DIMENSION(:) :: D, E, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE STEIN_64(N, D, E, M, W, IBLOCK, ISPLIT, Z, [LDZ], [WORK],
                  [IWORK], IFAIL, [INFO])
```

```
INTEGER(8) :: N, M, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IBLOCK, ISPLIT, IWORK, IFAIL
REAL(8), DIMENSION(:) :: D, E, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dstein(int n, double *d, double *e, int m, double *w,
            int *iblock, int *isplit, double *z, int ldz, int
            *ifail, int *info);
```

```
void dstein_64(long n, double *d, double *e, long m, double
               *w, long *iblock, long *isplit, double *z, long
               ldz, long *ifail, long *info);
```

PURPOSE

dstein computes the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration.

The maximum number of iterations allowed for each eigenvector is specified by an internal parameter MAXITS (currently set to 5).

ARGUMENTS

N (input) The order of the matrix. $N \geq 0$.

D (input) The n diagonal elements of the tridiagonal matrix T.

E (input) The (n-1) subdiagonal elements of the tridiagonal matrix T, in elements 1 to N-1. E(N) need not be set.

M (input) The number of eigenvectors to be found. $0 \leq M \leq N$.

W (input) The first M elements of W contain the eigenvalues for which eigenvectors are to be computed. The eigenvalues should be grouped by split-off block and ordered from smallest to largest within the block. (The output array W from DSTEBZ with ORDER = 'B' is expected here.)

IBLOCK (input)
The submatrix indices associated with the corresponding eigenvalues in W; IBLOCK(i)=1 if eigenvalue W(i) belongs to the first submatrix from the top, =2 if W(i) belongs to the second submatrix, etc. (The output array IBLOCK from DSTEBZ is expected here.)

ISPLIT (input)
The splitting points, at which T breaks up into submatrices. The first submatrix consists of rows/columns 1 to ISPLIT(1), the second of rows/columns ISPLIT(1)+1 through ISPLIT(2), etc. (The output array ISPLIT from DSTEBZ is expected here.)

Z (output)
The computed eigenvectors. The eigenvector asso-

ciated with the eigenvalue $W(i)$ is stored in the i -th column of Z . Any vector which fails to converge is set to its current iterate after $MAXITS$ iterations.

LDZ (input)

The leading dimension of the array Z . $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension($5*N$)

IWORK (workspace)

dimension(N)

IFAIL (output)

On normal exit, all elements of $IFAIL$ are zero. If one or more eigenvectors fail to converge after $MAXITS$ iterations, then their indices are stored in array $IFAIL$.

INFO (output)

= 0: successful exit.

< 0: if $INFO = -i$, the i -th argument had an illegal value

> 0: if $INFO = i$, then i eigenvectors failed to converge in $MAXITS$ iterations. Their indices are stored in array $IFAIL$.

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NAME

dsteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method

SYNOPSIS

```
SUBROUTINE DSTEQR(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
INTEGER N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSTEQR_64(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
INTEGER*8 N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEQR(COMPZ, N, D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
INTEGER :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE STEQR_64(COMPZ, N, D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
INTEGER(8) :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsteqr(char compz, int n, double *d, double *e, double  
           *z, int ldz, int *info);
```

```
void dsteqr_64(char compz, long n, double *d, double *e,
```

```
double *z, long ldz, long *info);
```

PURPOSE

dsteqr computes all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method. The eigenvectors of a full or band symmetric matrix can also be found if SSYTRD or SSPTRD or SSBTRD has been used to reduce this matrix to tridiagonal form.

ARGUMENTS

COMPZ (input)

= 'N': Compute eigenvalues only.
= 'V': Compute eigenvalues and eigenvectors of the original symmetric matrix. On entry, Z must contain the orthogonal matrix used to reduce the original matrix to tridiagonal form. = 'I': Compute eigenvalues and eigenvectors of the tridiagonal matrix. Z is initialized to the identity matrix.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the diagonal elements of the tridiagonal matrix. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input) On entry, if COMPZ = 'V', then Z contains the orthogonal matrix used in the reduction to tridiagonal form. On exit, if INFO = 0, then if COMPZ = 'V', Z contains the orthonormal eigenvectors of the original symmetric matrix, and if COMPZ = 'I', Z contains the orthonormal eigenvectors of the symmetric tridiagonal matrix. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if eigenvectors are desired, then $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension($\max(1, 2*N-2)$) If COMPZ = 'N', then WORK is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: the algorithm has failed to find all the

eigenvalues in a total of $30*N$ iterations; if $INFO = i$, then i elements of E have not converged to zero; on exit, D and E contain the elements of a symmetric tridiagonal matrix which is orthogonally similar to the original matrix.

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NAME

dsterf - compute all eigenvalues of a symmetric tridiagonal matrix using the Pal-Walker-Kahan variant of the QL or QR algorithm

SYNOPSIS

```
SUBROUTINE DSTERF(N, D, E, INFO)
```

```
INTEGER N, INFO  
DOUBLE PRECISION D(*), E(*)
```

```
SUBROUTINE DSTERF_64(N, D, E, INFO)
```

```
INTEGER*8 N, INFO  
DOUBLE PRECISION D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE STERF([N], D, E, [INFO])
```

```
INTEGER :: N, INFO  
REAL(8), DIMENSION(:) :: D, E
```

```
SUBROUTINE STERF_64([N], D, E, [INFO])
```

```
INTEGER(8) :: N, INFO  
REAL(8), DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsterf(int n, double *d, double *e, int *info);
```

```
void dsterf_64(long n, double *d, double *e, long *info);
```

PURPOSE

dsterf computes all eigenvalues of a symmetric tridiagonal

matrix using the Pal-Walker-Kahan variant of the QL or QR algorithm.

ARGUMENTS

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)

On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

INFO (output)

= 0: successful exit

< 0: if INFO = $-i$, the i -th argument had an illegal value

> 0: the algorithm failed to find all of the eigenvalues in a total of $30*N$ iterations; if INFO = i , then i elements of E have not converged to zero.

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NAME

dstev - compute all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A

SYNOPSIS

```
SUBROUTINE DSTEV(JOBZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ  
INTEGER N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSTEV_64(JOBZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ  
INTEGER*8 N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEV(JOBZ, N, D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ  
INTEGER :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE STEV_64(JOBZ, N, D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ  
INTEGER(8) :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK  
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dstev(char jobz, int n, double *d, double *e, double  
*z, int ldz, int *info);
```

```
void dstev_64(char jobz, long n, double *d, double *e, dou-  
ble *z, long ldz, long *info);
```

PURPOSE

dstev computes all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A, stored in elements 1 to N-1 of E; E(N) need not be set, but is used by the routine. On exit, the contents of E are destroyed.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with D(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

WORK (workspace)

If JOBZ = 'N', WORK is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of E did not converge to zero.

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NAME

dstevd - compute all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix

SYNOPSIS

```
SUBROUTINE DSTEVD(JOBZ, N, D, E, Z, LDZ, WORK, LWORK, IWORK, LIWORK,
  INFO)
```

```
CHARACTER * 1 JOBZ
INTEGER N, LDZ, LWORK, LIWORK, INFO
INTEGER IWORK(*)
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSTEVD_64(JOBZ, N, D, E, Z, LDZ, WORK, LWORK, IWORK,
  LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ
INTEGER*8 N, LDZ, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
DOUBLE PRECISION D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEVD(JOBZ, N, D, E, Z, [LDZ], [WORK], [LWORK], [IWORK],
  [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ
INTEGER :: N, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: D, E, WORK
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE STEVD_64(JOBZ, N, D, E, Z, [LDZ], [WORK], [LWORK], [IWORK],
  [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ
INTEGER(8) :: N, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: D, E, WORK
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>

void dstevd(char jobz, int n, double *d, double *e, double
            *z, int ldz, int *info);
void dstevd_64(char jobz, long n, double *d, double *e, dou-
               ble *z, long ldz, long *info);
```

PURPOSE

dstevd computes all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)
On entry, the n diagonal elements of the tridiagonal matrix A . On exit, if $INFO = 0$, the eigenvalues in ascending order.

E (input/output)
On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix A , stored in elements 1 to $N-1$ of E ; $E(N)$ need not be set, but is used by the routine. On exit, the contents of E are destroyed.

Z (input) If $JOBZ = 'V'$, then if $INFO = 0$, Z contains the orthonormal eigenvectors of the matrix A , with the i -th column of Z holding the eigenvector associated with $D(i)$. If $JOBZ = 'N'$, then Z is not referenced.

LDZ (input)
The leading dimension of the array Z . $LDZ \geq 1$, and if $JOBZ = 'V'$, $LDZ \geq \max(1, N)$.

WORK (workspace)
dimension (LWORK) On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If JOBZ = 'N' or $N \leq 1$ then LWORK must be at least 1. If JOBZ = 'V' and $N > 1$ then LWORK must be at least $(1 + 4*N + N**2)$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If JOBZ = 'N' or $N \leq 1$ then LIWORK must be at least 1. If JOBZ = 'V' and $N > 1$ then LIWORK must be at least $3+5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of E did not converge to zero.

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NAME

dstevr - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T

SYNOPSIS

```
SUBROUTINE DSTEVR(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M, W,  
  Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
INTEGER N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER ISUPPZ(*), IWORK(*)  
DOUBLE PRECISION VL, VU, ABSTOL  
DOUBLE PRECISION D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSTEVR_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
INTEGER*8 N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 ISUPPZ(*), IWORK(*)  
DOUBLE PRECISION VL, VU, ABSTOL  
DOUBLE PRECISION D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEVR(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE  
INTEGER :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: ISUPPZ, IWORK  
REAL(8) :: VL, VU, ABSTOL  
REAL(8), DIMENSION(:) :: D, E, W, WORK  
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE STEVR_64(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL,  
  M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE
```

```

INTEGER(8) :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: D, E, W, WORK
REAL(8), DIMENSION(:, :) :: Z

```

C INTERFACE

```

#include <sunperf.h>
void dstevr(char jobz, char range, int n, double *d, double
            *e, double vl, double vu, int il, int iu, double
            abstol, int *m, double *w, double *z, int ldz, int
            *isuppz, int *info);

void dstevr_64(char jobz, char range, long n, double *d,
               double *e, double vl, double vu, long il, long iu,
               double abstol, long *m, double *w, double *z, long
               ldz, long *isuppz, long *info);

```

PURPOSE

dstevr computes selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

Whenever possible, DSTEVr calls DSTEGR to compute the eigenspectrum using Relatively Robust Representations. DSTEGR computes eigenvalues by the dqds algorithm, while orthogonal eigenvectors are computed from various "good" L D L^T representations (also known as Relatively Robust Representations). Gram-Schmidt orthogonalization is avoided as far as possible. More specifically, the various steps of the algorithm are as follows. For the i-th unreduced block of T,

- (a) Compute $T - \sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation,
- (b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high relative accuracy by the dqds algorithm,
- (c) If there is a cluster of close eigenvalues, "choose" σ_i close to the cluster, and go to step (a),
- (d) Given the approximate eigenvalue λ_j of $L_i D_i L_i^T$, compute the corresponding eigenvector by forming a rank-revealing twisted factorization.

The desired accuracy of the output can be specified by the input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB//CSD-97-971, UC Berkeley, May 1997.

Note 1 : DSTEVr calls DSTEGR when the full spectrum is requested on machines which conform to the ieee-754 floating point standard. DSTEVr calls DSTEBZ and DSTEIN on non-ieee

machines and
when partial spectrum requests are made.

Normal execution of DSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not handle NaNs and infinities in the ieee standard default manner.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval
(VL,VU] will be found. = 'I': the IL-th through
IU-th eigenvalues will be found.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, D may be multiplied by a constant factor chosen to avoid over/underflow in computing the eigenvalues.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A in elements 1 to N-1 of E; E(N) need not be set. On exit, E may be multiplied by a constant factor chosen to avoid over/underflow in computing the eigenvalues.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$.
Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$ABSTOL + EPS * \max(|a|, |b|)$,

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

If high relative accuracy is important, set ABSTOL to SLAMCH('Safe minimum'). Doing so will guarantee that eigenvalues are computed to high relative accuracy when possible in future releases. The current code does not make any guarantees about high relative accuracy, but future releases will. See J. Barlow and J. Demmel, "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7, for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

ISUPPZ (output)

The support of the eigenvectors in Z, i.e., the indices indicating the nonzero elements in Z. The i-th eigenvector is nonzero only in elements ISUPPZ(2*i-1) through ISUPPZ(2*i).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal (and minimal) LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq 20*N$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of

the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal (and minimal) LIWORK.

LIWORK (input)

The dimension of the array IWORK. LIWORK \geq 10*N.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: Internal error

FURTHER DETAILS

Based on contributions by

Inderjit Dhillon, IBM Almaden, USA

Osni Marques, LBNL/NERSC, USA

Ken Stanley, Computer Science Division, University of California at Berkeley, USA

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NAME

dstevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A

SYNOPSIS

```
SUBROUTINE DSTEVX(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABTOL,
                 NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE
INTEGER N, IL, IU, NFOUND, LDZ, INFO
INTEGER IWORK2(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSTEVX_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU,
                   ABTOL, NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE
INTEGER*8 N, IL, IU, NFOUND, LDZ, INFO
INTEGER*8 IWORK2(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEVX(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABTOL,
                NFOUND, W, Z, [LDZ], [WORK], [IWORK2], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE
INTEGER :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK2, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: D, E, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

```
SUBROUTINE STEVX_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU,
                   ABTOL, NFOUND, W, Z, [LDZ], [WORK], [IWORK2], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE
INTEGER(8) :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK2, IFAIL
```

```
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: D, E, W, WORK
REAL(8), DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
void dstevx(char jobz, char range, int n, double *d, double
    *e, double vl, double vu, int il, int iu, double
    abtol, int *nfound, double *w, double *z, int ldz,
    int *ifail, int *info);

void dstevx_64(char jobz, char range, long n, double *d,
    double *e, double vl, double vu, long il, long iu,
    double abtol, long *nfound, double *w, double *z,
    long ldz, long *ifail, long *info);
```

PURPOSE

dstevx computes selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, D may be multiplied by a constant factor chosen to avoid over/underflow in computing the eigenvalues.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A in elements 1 to N-1 of E; E(N) need not be set. On exit, E may be multiplied by a constant factor chosen to avoid over/underflow in computing the eigenvalues.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
See the description of VL.

IL (input)
If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
See the description of IL.

ABTOL (input)
The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2*SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)
The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)
The first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if $INFO = 0$, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. If an eigenvector fails to converge ($INFO > 0$), then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, NFOUND)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1,
and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)
dimension(5*N)

IWORK2 (workspace)

IFAIL (output)
If JOBZ = 'V', then if INFO = 0, the first NFOUND
elements of IFAIL are zero. If INFO > 0, then
IFAIL contains the indices of the eigenvectors
that failed to converge. If JOBZ = 'N', then
IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value
> 0: if INFO = i, then i eigenvectors failed to
converge. Their indices are stored in array
IFAIL.

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NAME

dstsv - compute the solution to a system of linear equations
 $A * X = B$ where A is a symmetric tridiagonal matrix

SYNOPSIS

```
SUBROUTINE DSTSV(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIV(*)  
DOUBLE PRECISION L(*), D(*), SUBL(*), B(LDB,*)
```

```
SUBROUTINE DSTSV_64(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIV(*)  
DOUBLE PRECISION L(*), D(*), SUBL(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE STSV([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:) :: L, D, SUBL  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE STSV_64([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:) :: L, D, SUBL  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dstsv(int n, int nrhs, double *l, double *d, double  
          *subl, double *b, int ldb, int *ipiv, int *info);
```

```
void dstsv_64(long n, long nrhs, double *l, double *d, dou-  
             ble *subl, double *b, long ldb, long *ipiv, long
```

```
*info);
```

PURPOSE

dstsv computes the solution to a system of linear equations $A * X = B$ where A is a symmetric tridiagonal matrix.

ARGUMENTS

N (input) INTEGER
The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides in B.

L (input/output)
REAL array, dimension (N-1)
On entry, the n-1 subdiagonal elements of the tridiagonal matrix A. On exit, part of the factorization of A.

D (input/output)
REAL array, dimension (N)
On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the factorization of A.

SUBL (output)
REAL array, dimension (N-2)
On exit, part of the factorization of A.

B (input/output)
The columns of B contain the right hand sides.

LDB (input)
The leading dimension of B as specified in a type or DIMENSION statement.

IPIV (output)
INTEGER array, dimension (N)
On exit, the pivot indices of the factorization.

INFO (output)
INTEGER
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular and division by zero will occur if it is used to solve a system of equations.

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NAME

dsttrf - compute the factorization of a symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE DSTTRF(N, L, D, SUBL, IPIV, INFO)
```

```
INTEGER N, INFO  
INTEGER IPIV(*)  
DOUBLE PRECISION L(*), D(*), SUBL(*)
```

```
SUBROUTINE DSTTRF_64(N, L, D, SUBL, IPIV, INFO)
```

```
INTEGER*8 N, INFO  
INTEGER*8 IPIV(*)  
DOUBLE PRECISION L(*), D(*), SUBL(*)
```

F95 INTERFACE

```
SUBROUTINE STTRF([N], L, D, SUBL, IPIV, [INFO])
```

```
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:) :: L, D, SUBL
```

```
SUBROUTINE STTRF_64([N], L, D, SUBL, IPIV, [INFO])
```

```
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:) :: L, D, SUBL
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsttrf(int n, double *l, double *d, double *subl, int  
           *ipiv, int *info);
```

```
void dsttrf_64(long n, double *l, double *d, double *subl,  
              long *ipiv, long *info);
```

PURPOSE

dsttrf computes the L^*D*L' factorization of a real symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method.

ARGUMENTS

N (input) INTEGER
The order of the matrix A. $N \geq 0$.

L (input/output)
REAL array, dimension (N-1)
On entry, the n-1 subdiagonal elements of the tridiagonal matrix A. On exit, part of the factorization of A.

D (input/output)
REAL array, dimension (N)
On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the L^*D*L^*H factorization of A.

SUBL (output)
REAL array, dimension (N-2)
On exit, part of the factorization of A.

IPIV (output)
INTEGER array, dimension (N)
On exit, the pivot indices of the factorization.

INFO (output)
INTEGER
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular and division by zero will occur if it is used to solve a system of equations.

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NAME

dsttrs - computes the solution to a real system of linear equations $A * X = B$

SYNOPSIS

```
SUBROUTINE DSTTRS(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
INTEGER N, NRHS, LDB, INFO
INTEGER IPIV(*)
DOUBLE PRECISION L(*), D(*), SUBL(*), B(LDB,*)
```

```
SUBROUTINE DSTTRS_64(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO
INTEGER*8 IPIV(*)
DOUBLE PRECISION L(*), D(*), SUBL(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE STTRS([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO
INTEGER, DIMENSION(:) :: IPIV
REAL(8), DIMENSION(:) :: L, D, SUBL
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE STTRS_64([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIV
REAL(8), DIMENSION(:) :: L, D, SUBL
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsttrs(int n, int nrhs, double *l, double *d, double
           *subl, double *b, int ldb, int *ipiv, int *info);
```

```
void dsttrs_64(long n, long nrhs, double *l, double *d, dou-
              ble *subl, double *b, long ldb, long *ipiv, long
```

```
*info);
```

PURPOSE

dsttrs computes the solution to a real system of linear equations $A * X = B$, where A is an N-by-N symmetric tridiagonal matrix and X and B are N-by-NRHS matrices.

ARGUMENTS

N (input) INTEGER
The order of the matrix A. $N \geq 0$.

NRHS (input)
INTEGER
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

L (input) REAL array, dimension (N-1)
On entry, the subdiagonal elements of L.

D (input) REAL array, dimension (N)
On entry, the diagonal elements of D.

SUBL (input)
REAL array, dimension (N-2)
On entry, the second subdiagonal elements of L.

B (input/output)
REAL array, dimension (LDB, NRHS)
On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)
INTEGER
The leading dimension of the array B. $LDB \geq \max(1, N)$

IPIV (output)
INTEGER array, dimension (N)
Details of the interchanges and block pivot. If $IPIV(K) > 0$, 1 by 1 pivot, and if $IPIV(K) = K + 1$ an interchange done; If $IPIV(K) < 0$, 2 by 2 pivot, no interchange required.

INFO (output)
INTEGER
= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value

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NAME

dswap - Exchange vectors x and y.

SYNOPSIS

```
SUBROUTINE DSWAP(N, X, INCX, Y, INCY)
```

```
INTEGER N, INCX, INCY  
DOUBLE PRECISION X(*), Y(*)
```

```
SUBROUTINE DSWAP_64(N, X, INCX, Y, INCY)
```

```
INTEGER*8 N, INCX, INCY  
DOUBLE PRECISION X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE SWAP([N], X, [INCX], Y, [INCY])
```

```
INTEGER :: N, INCX, INCY  
REAL(8), DIMENSION(:) :: X, Y
```

```
SUBROUTINE SWAP_64([N], X, [INCX], Y, [INCY])
```

```
INTEGER(8) :: N, INCX, INCY  
REAL(8), DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dswap(int n, double *x, int incx, double *y, int incy);
```

```
void dswap_64(long n, double *x, long incx, double *y, long  
incy);
```

PURPOSE

dswap Exchange x and y where x and y are n-vectors.

ARGUMENTS

- N (input)
On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.
- X (input/output)
($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x. On exit, the y vector.
- INCX (input)
On entry, INCX specifies the increment for the elements of X. Unchanged on exit.
- Y (input/output)
($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array Y must contain the vector y. On exit, the x vector.
- INCY (input)
On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

dsycon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric matrix A using the factorization $A = U^*D*U^{**T}$ or $A = L^*D*L^{**T}$ computed by DSYTRF

SYNOPSIS

```
SUBROUTINE DSYCON(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK,  
                 IWORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*), IWORK2(*)  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DSYCON_64(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK,  
                   IWORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*), IWORK2(*)  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYCON(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
                [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, IWORK2  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYCON_64(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
                  [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO
```

```

INTEGER(8), DIMENSION(:) :: IPIVOT, IWORK2
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A

```

C INTERFACE

```

#include <sunperf.h>
void dsycon(char uplo, int n, double *a, int lda, int
            *ipivot, double anorm, double *rcond, int *info);

void dsycon_64(char uplo, long n, double *a, long lda, long
              *ipivot, double anorm, double *rcond, long *info);

```

PURPOSE

dsycon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric matrix A using the factorization $A = U^*D U^{**T}$ or $A = L^*D L^{**T}$ computed by DSYTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U^*D U^{**T}$;
 = 'L': Lower triangular, form is $A = L^*D L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by DSYTRF.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by DSYTRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{AINVM})$, where AINVM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

IWORK2 (workspace)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dsyev - compute all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

SYNOPSIS

```
SUBROUTINE DSYEV(JOBZ, UPLO, N, A, LDA, W, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), W(*), WORK(*)
```

```
SUBROUTINE DSYEV_64(JOBZ, UPLO, N, A, LDA, W, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, LDA, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYEV(JOBZ, UPLO, N, A, [LDA], W, [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYEV_64(JOBZ, UPLO, N, A, [LDA], W, [WORK], [LDWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, LDA, LDWORK, INFO  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsyev(char jobz, char uplo, int n, double *a, int lda,  
double *w, int *info);
```

```
void dsyev_64(char jobz, char uplo, long n, double *a, long
```

```
lda, double *w, long *info);
```

PURPOSE

dsyev computes all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, if JOBZ = 'V', then if INFO = 0, A contains the orthonormal eigenvectors of the matrix A. If JOBZ = 'N', then on exit the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)

If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of the array WORK. $LDWORK \geq \max(1, 3*N-1)$. For optimal efficiency, $LDWORK \geq (NB+2)*N$, where NB is the blocksize for DSYTRD returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

dsyevd - compute all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

SYNOPSIS

```
SUBROUTINE DSYEVD(JOBZ, UPLO, N, A, LDA, W, WORK, LWORK, IWORK,  
  LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, LDA, LWORK, LIWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION A(LDA,*), W(*), WORK(*)
```

```
SUBROUTINE DSYEVD_64(JOBZ, UPLO, N, A, LDA, W, WORK, LWORK, IWORK,  
  LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, LDA, LWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION A(LDA,*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYEVD(JOBZ, UPLO, N, A, [LDA], W, [WORK], [LWORK], [IWORK],  
  [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, LDA, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYEVD_64(JOBZ, UPLO, N, A, [LDA], W, [WORK], [LWORK],  
  [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, LDA, LWORK, LIWORK, INFO  
INTEGER(8), DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, WORK
```

```
REAL(8), DIMENSION(:,:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsyevd(char jobz, char uplo, int n, double *a, int lda,  
            double *w, int *info);
```

```
void dsyevd_64(char jobz, char uplo, long n, double *a, long  
              lda, double *w, long *info);
```

PURPOSE

dsyevd computes all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

Because of large use of BLAS of level 3, DSYEVD needs N^2 more workspace than DSYEVX.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, if JOBZ = 'V', then if INFO = 0, A contains the orthonormal eigenvectors of the matrix A. If JOBZ = 'N', then on exit the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)
 dimension (LWORK) On exit, if INFO = 0, WORK(1)
 returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. If $N \leq 1$,
 LWORK must be at least 1. If JOBZ = 'N' and $N > 1$,
 LWORK must be at least $2*N+1$. If JOBZ = 'V'
 and $N > 1$, LWORK must be at least $1 + 6*N + 2*N**2$.

If LWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the WORK array, returns this value as the first
 entry of the WORK array, and no error message
 related to LWORK is issued by XERBLA.

IWORK (workspace/output)
 On exit, if INFO = 0, IWORK(1) returns the optimal
 LIWORK.

LIWORK (input)
 The dimension of the array IWORK. If $N \leq 1$,
 LIWORK must be at least 1. If JOBZ = 'N' and $N > 1$,
 LIWORK must be at least 1. If JOBZ = 'V' and
 $N > 1$, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the IWORK array, returns this value as the first
 entry of the IWORK array, and no error message
 related to LIWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-
 gal value
 > 0: if INFO = i, the algorithm failed to con-
 verge; i off-diagonal elements of an intermediate
 tridiagonal form did not converge to zero.

FURTHER DETAILS

Based on contributions by
 Jeff Rutter, Computer Science Division, University of
 California
 at Berkeley, USA
 Modified by Francoise Tisseur, University of Tennessee.

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NAME

dsyevr - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T

SYNOPSIS

```
SUBROUTINE DSYEVR(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
  ABSTOL, M, W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, LDA, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER ISUPPZ(*), IWORK(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSYEVR_64(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
  ABSTOL, M, W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, LDA, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER*8 ISUPPZ(*), IWORK(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYEVR(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
  ABSTOL, M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK],
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, LDA, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: ISUPPZ, IWORK
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: A, Z
```

```
SUBROUTINE SYEVR_64(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
  ABSTOL, M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK],
  [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: N, LDA, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: A, Z

```

C INTERFACE

```
#include <sunperf.h>
```

```

void dsyevr(char jobz, char range, char uplo, int n, double
           *a, int lda, double vl, double vu, int il, int iu,
           double abstol, int *m, double *w, double *z, int
           ldz, int *isuppz, int *info);

```

```

void dsyevr_64(char jobz, char range, char uplo, long n,
              double *a, long lda, double vl, double vu, long
              il, long iu, double abstol, long *m, double *w,
              double *z, long ldz, long *isuppz, long *info);

```

PURPOSE

dsyevr computes selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

Whenever possible, DSYEVR calls DSTEGR to compute the eigenspectrum using Relatively Robust Representations. DSTEGR computes eigenvalues by the dqds algorithm, while orthogonal eigenvectors are computed from various "good" L D L^T representations (also known as Relatively Robust Representations). Gram-Schmidt orthogonalization is avoided as far as possible. More specifically, the various steps of the algorithm are as follows. For the i-th unreduced block of T,

(a) Compute $T - \sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$

is a relatively robust representation,

(b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high

relative accuracy by the dqds algorithm,

(c) If there is a cluster of close eigenvalues, "choose" σ_i

close to the cluster, and go to step (a),

(d) Given the approximate eigenvalue λ_j of $L_i D_i L_i^T$,

compute the corresponding eigenvector by forming a rank-revealing twisted factorization.

The desired accuracy of the output can be specified by the input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB//CSD-97-971, UC Berkeley, May 1997.

Note 1: DSYEVR calls DSTEGR when the full spectrum is requested on machines which conform to the ieee-754 floating

point standard. DSYEVR calls DSTEBZ and DSTEIN on non-ieee machines and when partial spectrum requests are made.

Normal execution of DSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not handle NaNs and infinities in the ieee standard default manner.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$\text{ABSTOL} + \text{EPS} * \max(|a|, |b|),$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $\text{EPS} * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

If high relative accuracy is important, set ABSTOL to SLAMCH('Safe minimum'). Doing so will guarantee that eigenvalues are computed to high relative accuracy when possible in future releases. The current code does not make any guarantees about high relative accuracy, but future releases will. See J. Barlow and J. Demmel, "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7, for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = \text{IU} - \text{IL} + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $\text{LDZ} \geq 1$, and if JOBZ = 'V', $\text{LDZ} \geq \max(1, N)$.

ISUPPZ (output)

The support of the eigenvectors in Z, i.e., the indices indicating the nonzero elements in Z. The i-th eigenvector is nonzero only in elements ISUPPZ(2*i-1) through ISUPPZ(2*i).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,26*N). For optimal efficiency, LWORK \geq (NB+6)*N, where NB is the max of the blocksize for DSYTRD and DORMTR returned by ILAENV.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LWORK.

LIWORK (input)

The dimension of the array IWORK. LIWORK \geq max(1,10*N).

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: Internal error

FURTHER DETAILS

Based on contributions by
Inderjit Dhillon, IBM Almaden, USA
Osni Marques, LBNL/NERSC, USA
Ken Stanley, Computer Science Division, University of
California at Berkeley, USA

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NAME

dsyevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

SYNOPSIS

```
SUBROUTINE DSYEVX(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
  ABTOL, NFOUND, W, Z, LDZ, WORK, LDWORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER IWORK2(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSYEVX_64(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
  ABTOL, NFOUND, W, Z, LDZ, WORK, LDWORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER*8 IWORK2(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYEVX(JOBZ, RANGE, UPLO, N, A, [LDA], VL, VU, IL, IU,
  ABTOL, NFOUND, W, Z, [LDZ], [WORK], [LDWORK], [IWORK2], IFAIL,
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER, DIMENSION(:) :: IWORK2, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: A, Z
```

```
SUBROUTINE SYEVX_64(JOBZ, RANGE, UPLO, N, A, [LDA], VL, VU, IL, IU,
  ABTOL, NFOUND, W, Z, [LDZ], [WORK], [LDWORK], [IWORK2], IFAIL,
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
```

```

INTEGER(8) :: N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK2, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:,:) :: A, Z

```

C INTERFACE

```

#include <sunperf.h>

void dsyevx(char jobz, char range, char uplo, int n, double
            *a, int lda, double vl, double vu, int il, int iu,
            double abtol, int *nfound, double *w, double *z,
            int ldz, int *ifail, int *info);

void dsyevx_64(char jobz, char range, char uplo, long n,
               double *a, long lda, double vl, double vu, long
               il, long iu, double abtol, long *nfound, double
               *w, double *z, long ldz, long *ifail, long *info);

```

PURPOSE

dsyevx computes selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found.
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. N >= 0.

A (input/output)
 On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
 The leading dimension of the array A. LDA >= max(1,N).

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 See the description of VL.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 See the description of IL.

ABTOL (input)
 The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2 * SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)
 The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)
 On normal exit, the first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if $INFO = 0$, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, NFOUND)$ columns are supplied in the array Z;

if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of the array WORK. LDWORK \geq max(1,8*N). For optimal efficiency, LDWORK \geq (NB+3)*N, where NB is the max of the blocksize for DSYTRD and DORMTR returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

IWORK2 (workspace)

IFAIL (output)

If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO $>$ 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

dsygs2 - reduce a real symmetric-definite generalized eigenproblem to standard form

SYNOPSIS

```
SUBROUTINE DSYGS2(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER ITYPE, N, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DSYGS2_64(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 ITYPE, N, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SYGS2(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: ITYPE, N, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE SYGS2_64(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: ITYPE, N, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsygs2(int itype, char uplo, int n, double *a, int lda,  
           double *b, int ldb, int *info);
```

```
void dsygs2_64(long itype, char uplo, long n, double *a,  
              long lda, double *b, long ldb, long *info);
```

PURPOSE

dsygs2 reduces a real symmetric-definite generalized eigenproblem to standard form.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $inv(U')*A*inv(U)$ or $inv(L)*A*inv(L')$.
If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U'$ or $L'*A*L$.

B must have been previously factorized as $U'*U$ or $L*L'$ by SPOTRF.

ARGUMENTS

ITYPE (input)

= 1: compute $inv(U')*A*inv(U)$ or $inv(L)*A*inv(L')$;
= 2 or 3: compute $U*A*U'$ or $L'*A*L$.

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored, and how B has been factorized. = 'U': Upper triangular
= 'L': Lower triangular

N (input) The order of the matrices A and B . $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A . If $UPLO = 'U'$, the leading n by n upper triangular part of A contains the upper triangular part of the matrix A , and the strictly lower triangular part of A is not referenced. If $UPLO = 'L'$, the leading n by n lower triangular part of A contains the lower triangular part of the matrix A , and the strictly upper triangular part of A is not referenced.

On exit, if $INFO = 0$, the transformed matrix, stored in the same format as A .

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

B (input) The triangular factor from the Cholesky factorization of B , as returned by SPOTRF.

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit.
< 0: if $INFO = -i$, the i -th argument had an illegal value.

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NAME

dsygst - reduce a real symmetric-definite generalized eigenproblem to standard form

SYNOPSIS

```
SUBROUTINE DSYGST(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER ITYPE, N, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DSYGST_64(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 ITYPE, N, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SYGST(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: ITYPE, N, LDA, LDB, INFO  
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE SYGST_64(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: ITYPE, N, LDA, LDB, INFO  
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsygst(int itype, char uplo, int n, double *a, int lda,  
            double *b, int ldb, int *info);
```

```
void dsygst_64(long itype, char uplo, long n, double *a,  
              long lda, double *b, long ldb, long *info);
```

PURPOSE

dsgyst reduces a real symmetric-definite generalized eigenproblem to standard form.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $inv(U^{**T})*A*inv(U)$ or $inv(L)*A*inv(L^{**T})$

If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U^{**T}$ or $L^{**T}*A*L$.

B must have been previously factorized as $U^{**T}*U$ or $L*L^{**T}$ by SPOTRF.

ARGUMENTS

$ITYPE$ (input)
= 1: compute $inv(U^{**T})*A*inv(U)$ or $inv(L)*A*inv(L^{**T})$;
= 2 or 3: compute $U*A*U^{**T}$ or $L^{**T}*A*L$.

$UPLO$ (input)
= 'U': Upper triangle of A is stored and B is factored as $U^{**T}*U$; = 'L': Lower triangle of A is stored and B is factored as $L*L^{**T}$.

N (input) The order of the matrices A and B . $N \geq 0$.

A (input/output)
On entry, the symmetric matrix A . If $UPLO = 'U'$, the leading N -by- N upper triangular part of A contains the upper triangular part of the matrix A , and the strictly lower triangular part of A is not referenced. If $UPLO = 'L'$, the leading N -by- N lower triangular part of A contains the lower triangular part of the matrix A , and the strictly upper triangular part of A is not referenced.

On exit, if $INFO = 0$, the transformed matrix, stored in the same format as A .

LDA (input)
The leading dimension of the array A . $LDA \geq \max(1,N)$.

B (input) The triangular factor from the Cholesky factorization of B , as returned by SPOTRF.

LDB (input)
The leading dimension of the array B . $LDB \geq \max(1,N)$.

$INFO$ (output)
= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

dsygv - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE DSYGV(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                LDWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER ITYPE, N, LDA, LDB, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), W(*), WORK(*)
```

```
SUBROUTINE DSYGV_64(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                  LDWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 ITYPE, N, LDA, LDB, LDWORK, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYGV(ITYPE, JOBZ, UPLO, N, A, [LDA], B, [LDB], W, [WORK],  
               [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: ITYPE, N, LDA, LDB, LDWORK, INFO  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE SYGV_64(ITYPE, JOBZ, UPLO, N, A, [LDA], B, [LDB], W, [WORK],  
                  [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: ITYPE, N, LDA, LDB, LDWORK, INFO  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsygv(int itype, char jobz, char uplo, int n, double
          *a, int lda, double *b, int ldb, double *w, int
          *info);
```

```
void dsygv_64(long itype, char jobz, char uplo, long n, dou-
             ble *a, long lda, double *b, long ldb, double *w,
             long *info);
```

PURPOSE

dsygv computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*B*x=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric and B is also positive definite.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:
 = 1: $A*x = (\lambda)*B*x$
 = 2: $A*B*x = (\lambda)*x$
 = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

= 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.

On exit, if JOBZ = 'V', then if INFO = 0, A contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z**T*B*Z = I$; if ITYPE = 3, $Z**T*inv(B)*Z = I$. If JOBZ = 'N', then on exit the upper triangle (if UPLO='U') or the lower triangle (if UPLO='L') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)

On entry, the symmetric positive definite matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if INFO <= N, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*T^*U$ or $B = L^*L^*T$.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

W (output)

If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of the array WORK. LDWORK >= max(1,3*N-1). For optimal efficiency, LDWORK >= (NB+2)*N, where NB is the blocksize for DSYTRD returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: DPOTRF or DSYEV returned an error code:
<= N: if INFO = i, DSYEV failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for 1 <= i <= N, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

dsygvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE DSYGVD(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                 LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER ITYPE, N, LDA, LDB, LWORK, LIWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), W(*), WORK(*)
```

```
SUBROUTINE DSYGVD_64(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                    LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 ITYPE, N, LDA, LDB, LWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYGVD(ITYPE, JOBZ, UPLO, [N], A, [LDA], B, [LDB], W, [WORK],  
                [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: ITYPE, N, LDA, LDB, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, WORK  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE SYGVD_64(ITYPE, JOBZ, UPLO, [N], A, [LDA], B, [LDB], W,  
                   [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: ITYPE, N, LDA, LDB, LWORK, LIWORK, INFO
```

```
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsygvd(int itype, char jobz, char uplo, int n, double
           *a, int lda, double *b, int ldb, double *w, int
           *info);
```

```
void dsygvd_64(long itype, char jobz, char uplo, long n,
              double *a, long lda, double *b, long ldb, double
              *w, long *info);
```

PURPOSE

dsygvd computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

= 1: $A*x = (\lambda)*B*x$

= 2: $A*B*x = (\lambda)*x$

= 3: $B*A*x = (\lambda)*x$

JOBZ (input)

= 'N': Compute eigenvalues only;

= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangles of A and B are stored;

= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of

the matrix A.

On exit, if JOBZ = 'V', then if INFO = 0, A contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^*T*B*Z = I$; if ITYPE = 3, $Z^*T*inv(B)*Z = I$. If JOBZ = 'N', then on exit the upper triangle (if UPLO='U') or the lower triangle (if UPLO='L') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)

On entry, the symmetric matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if INFO \leq N, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*T*U$ or $B = L*L^*T$.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

W (output)

If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $N \leq 1$, LWORK ≥ 1 . If JOBZ = 'N' and $N > 1$, LWORK $\geq 2*N+1$. If JOBZ = 'V' and $N > 1$, LWORK $\geq 1 + 6*N + 2*N**2$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If $N \leq 1$, LIWORK ≥ 1 . If JOBZ = 'N' and $N > 1$, LIWORK ≥ 1 . If JOBZ = 'V' and $N > 1$, LIWORK $\geq 3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of

the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: DPOTRF or DSYEVD returned an error code:
<= N: if INFO = i, DSYEVD failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for 1 <= i <= N, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

dsygvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*Bx=(\lambda)x$, or $B*A*x=(\lambda)x$

SYNOPSIS

```
SUBROUTINE DSYGVX(ITYPE, JOBZ, RANGE, UPLO, N, A, LDA, B, LDB, VL,
                 VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, LWORK, IWORK, IFAIL,
                 INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION A(LDA,*), B(LDB,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE DSYGVX_64(ITYPE, JOBZ, RANGE, UPLO, N, A, LDA, B, LDB, VL,
                    VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, LWORK, IWORK, IFAIL,
                    INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER*8 IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION A(LDA,*), B(LDB,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYGVX(ITYPE, JOBZ, RANGE, UPLO, [N], A, [LDA], B, [LDB],
                VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [LWORK], [IWORK],
                IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:, :) :: A, B, Z
```

```

SUBROUTINE SYGVX_64(ITYPE, JOBZ, RANGE, UPLO, [N], A, [LDA], B, [LDB],
    VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [LWORK], [IWORK],
    IFAIL, [INFO])

```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, WORK
REAL(8), DIMENSION(:,:) :: A, B, Z

```

C INTERFACE

```

#include <sunperf.h>

void dsygvx(int itype, char jobz, char range, char uplo, int
    n, double *a, int lda, double *b, int ldb, double
    vl, double vu, int il, int iu, double abstol, int
    *m, double *w, double *z, int ldz, int *ifail, int
    *info);

void dsygvx_64(long itype, char jobz, char range, char uplo,
    long n, double *a, long lda, double *b, long ldb,
    double vl, double vu, long il, long iu, double
    abstol, long *m, double *w, double *z, long ldz,
    long *ifail, long *info);

```

PURPOSE

dsygvx computes selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*B*x=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric and B is also positive definite. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

ITYPE (input)
 Specifies the problem type to be solved:
 = 1: $A*x = (\lambda)*B*x$
 = 2: $A*B*x = (\lambda)*x$
 = 3: $B*A*x = (\lambda)*x$

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found.
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangle of A and B are stored;
 = 'L': Lower triangle of A and B are stored.

N (input) The order of the matrix pencil (A,B). $N \geq 0$.

A (input/output)
 On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.
 On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)
 On entry, the symmetric matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.
 On exit, if INFO $\leq N$, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*T^*U$ or $B = L^*L^*T$.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1,N)$.

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 See the description of VL.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 See the description of IL.

ABSTOL (input)
 The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$ABSTOL + EPS * \max(|a|, |b|)$,

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2*DLAMCH('S')$, not zero. If this routine returns with $INFO>0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2*SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

On normal exit, the first M elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'N', then Z is not referenced. If JOBZ = 'V', then if $INFO = 0$, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^T B Z = I$; if ITYPE = 3, $Z^T \text{inv}(B) Z = I$. If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

WORK (workspace)

On exit, if $INFO = 0$, WORK(1) returns the optimal LWORK.

LWORK (input)

The length of the array WORK. $LWORK \geq \max(1, 8*N)$. For optimal efficiency, $LWORK \geq (NB+3)*N$, where NB is the blocksize for DSYTRD returned by ILAENV.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)
dimension(5*N)

IFAIL (output)
If JOBZ = 'V', then if INFO = 0, the first M elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: DPOTRF or DSYEVX returned an error code:
<= N: if INFO = i, DSYEVX failed to converge; i eigenvectors failed to converge. Their indices are stored in array IFAIL. > N: if INFO = N + i, for 1 <= i <= N, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

dsymm - perform one of the matrix-matrix operations $C := \alpha A * B + \beta C$ or $C := \alpha B * A + \beta C$

SYNOPSIS

```
SUBROUTINE DSYMM(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                LDC)
```

```
CHARACTER * 1 SIDE, UPLO
INTEGER M, N, LDA, LDB, LDC
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*)
```

```
SUBROUTINE DSYMM_64(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                   LDC)
```

```
CHARACTER * 1 SIDE, UPLO
INTEGER*8 M, N, LDA, LDB, LDC
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE SYMM(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
               BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
INTEGER :: M, N, LDA, LDB, LDC
REAL(8) :: ALPHA, BETA
REAL(8), DIMENSION(:, :) :: A, B, C
```

```
SUBROUTINE SYMM_64(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
                  BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
INTEGER(8) :: M, N, LDA, LDB, LDC
REAL(8) :: ALPHA, BETA
REAL(8), DIMENSION(:, :) :: A, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsymm(char side, char uplo, int m, int n, double alpha,
           double *a, int lda, double *b, int ldb, double
           beta, double *c, int ldc);
```

```
void dsymm_64(char side, char uplo, long m, long n, double
              alpha, double *a, long lda, double *b, long ldb,
              double beta, double *c, long ldc);
```

PURPOSE

dsymm performs one of the matrix-matrix operations $C := \alpha A^*B + \beta C$ or $C := \alpha B^*A + \beta C$ where alpha and beta are scalars, A is a symmetric matrix and B and C are m by n matrices.

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether the symmetric matrix A appears on the left or right in the operation as follows:

SIDE = 'L' or 'l' $C := \alpha A^*B + \beta C$,

SIDE = 'R' or 'r' $C := \alpha B^*A + \beta C$,

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the symmetric matrix A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of the symmetric matrix is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of the symmetric matrix is to be referenced.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of the matrix C. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix C. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

DOUBLE PRECISION array of DIMENSION (LDA, ka), where ka is m when SIDE = 'L' or 'l' and is n

otherwise.

Before entry with SIDE = 'L' or 'l', the m by m part of the array A must contain the symmetric matrix, such that when UPLO = 'U' or 'u', the leading m by m upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading m by m lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced.

Before entry with SIDE = 'R' or 'r', the n by n part of the array A must contain the symmetric matrix, such that when UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced.

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then $LDA \geq \max(1, m)$, otherwise $LDA \geq \max(1, n)$. Unchanged on exit.

B (input)

DOUBLE PRECISION array of DIMENSION (LDB, n). Before entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. $LDB \geq \max(1, m)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then C need not be set on input. Unchanged on exit.

C (input/output)

DOUBLE PRECISION array of DIMENSION (LDC, n). Before entry, the leading m by n part of the array C must contain the matrix C, except when beta is zero, in which case C need not be set on entry. On exit, the array C is overwritten by the m by n updated matrix.

LDC (input)

On entry, LDC specifies the first dimension of C

as declared in the calling (sub) program.
LDC \geq max(1, m). Unchanged on exit.

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NAME

dsymv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE DSYMV(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INCX, INCY  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), X(*), Y(*)
```

```
SUBROUTINE DSYMV_64(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INCX, INCY  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE SYMV(UPLO, [N], ALPHA, A, [LDA], X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INCX, INCY  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:) :: X, Y  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYMV_64(UPLO, [N], ALPHA, A, [LDA], X, [INCX], BETA, Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INCX, INCY  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:) :: X, Y  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsymv(char uplo, int n, double alpha, double *a, int
           lda, double *x, int incx, double beta, double *y,
           int incy);
```

```
void dsymv_64(char uplo, long n, double alpha, double *a,
              long lda, double *x, long incx, double beta, dou-
              ble *y, long incy);
```

PURPOSE

dsymv performs the matrix-vector operation $y := \alpha A x + \beta y$, where α and β are scalars, x and y are n element vectors and A is an n by n symmetric matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the

incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX \neq 0. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

($1 + (n - 1) * \text{abs}(\text{ INCY })$). Before entry, the incremented array Y must contain the n element vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

dsyr - perform the symmetric rank 1 operation $A := \alpha x x' + A$

SYNOPSIS

```
SUBROUTINE DSYR(UPLO, N, ALPHA, X, INCX, A, LDA)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INCX, LDA  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), A(LDA,*)
```

```
SUBROUTINE DSYR_64(UPLO, N, ALPHA, X, INCX, A, LDA)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INCX, LDA  
DOUBLE PRECISION ALPHA  
DOUBLE PRECISION X(*), A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE SYR(UPLO, [N], ALPHA, X, [INCX], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INCX, LDA  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYR_64(UPLO, [N], ALPHA, X, [INCX], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INCX, LDA  
REAL(8) :: ALPHA  
REAL(8), DIMENSION(:) :: X  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsyr(char uplo, int n, double alpha, double *x, int
```

```

        incx, double *a, int lda);

void dsyr_64(char uplo, long n, double alpha, double *x,
             long incx, double *a, long lda);

```

PURPOSE

dsyr performs the symmetric rank 1 operation $A := \alpha x x^T + A$, where α is a real scalar, x is an n element vector and A is an n by n symmetric matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

A (input/output)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced. On exit, the upper triangular part of the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced. On exit, the lower triangular part of

the array A is overwritten by the lower triangular part of the updated matrix.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA \geq max(1, n). Unchanged on exit.

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NAME

dsyr2 - perform the symmetric rank 2 operation $A := \alpha x x' + \alpha y y' + A$

SYNOPSIS

```
SUBROUTINE DSYR2(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
CHARACTER * 1 UPLO
INTEGER N, INCX, INCY, LDA
DOUBLE PRECISION ALPHA
DOUBLE PRECISION X(*), Y(*), A(LDA,*)
```

```
SUBROUTINE DSYR2_64(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
CHARACTER * 1 UPLO
INTEGER*8 N, INCX, INCY, LDA
DOUBLE PRECISION ALPHA
DOUBLE PRECISION X(*), Y(*), A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE SYR2(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER :: N, INCX, INCY, LDA
REAL(8) :: ALPHA
REAL(8), DIMENSION(:) :: X, Y
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYR2_64(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER(8) :: N, INCX, INCY, LDA
REAL(8) :: ALPHA
REAL(8), DIMENSION(:) :: X, Y
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsyr2(char uplo, int n, double alpha, double *x, int
```

```

        incx, double *y, int incy, double *a, int lda);

void dsyr2_64(char uplo, long n, double alpha, double *x,
             long incx, double *y, long incy, double *a, long
             lda);

```

PURPOSE

dsyr2 performs the symmetric rank 2 operation $A := \alpha x x^T + \alpha y y^T + A$, where α is a scalar, x and y are n element vectors and A is an n by n symmetric matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

A (input/output)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric

matrix and the strictly lower triangular part of A is not referenced. On exit, the upper triangular part of the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced. On exit, the lower triangular part of the array A is overwritten by the lower triangular part of the updated matrix.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA \geq max(1, n). Unchanged on exit.

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NAME

dsyr2k - perform one of the symmetric rank 2k operations $C := \alpha A'B' + \alpha B'A' + \beta C$ or $C := \alpha A'A + \alpha B'B + \beta C$

SYNOPSIS

```
SUBROUTINE DSYR2K(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA, C,
                 LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
INTEGER N, K, LDA, LDB, LDC
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*)
```

```
SUBROUTINE DSYR2K_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA,
                    C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
INTEGER*8 N, K, LDA, LDB, LDC
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE SYR2K(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B, [LDB],
                BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
INTEGER :: N, K, LDA, LDB, LDC
REAL(8) :: ALPHA, BETA
REAL(8), DIMENSION(:, :) :: A, B, C
```

```
SUBROUTINE SYR2K_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B,
                   [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
INTEGER(8) :: N, K, LDA, LDB, LDC
REAL(8) :: ALPHA, BETA
REAL(8), DIMENSION(:, :) :: A, B, C
```

C INTERFACE

```
#include <sunperf.h>

void dsyr2k(char uplo, char transa, int n, int k, double
            alpha, double *a, int lda, double *b, int ldb,
            double beta, double *c, int ldc);
void dsyr2k_64(char uplo, char transa, long n, long k, dou-
               ble alpha, double *a, long lda, double *b, long
               ldb, double beta, double *c, long ldc);
```

PURPOSE

dsyr2k performs one of the symmetric rank 2k operations $C := \alpha A^*B' + \alpha B^*A' + \beta C$ or $C := \alpha A^*B + \alpha B^*A + \beta C$ where α and β are scalars, C is an n by n symmetric matrix and A and B are n by k matrices in the first case and k by n matrices in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A^*B' + \alpha B^*A' + \beta C$.

TRANSA = 'T' or 't' $C := \alpha A^*B + \alpha B^*A + \beta C$.

TRANSA = 'C' or 'c' $C := \alpha A^*B + \alpha B^*A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrices A and B ,

and on entry with TRANSA = 'T' or 't' or 'C' or 'c', K specifies the number of rows of the matrices A and B. K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

DOUBLE PRECISION array of DIMENSION (LDA, ka), where ka is k when TRANSA = 'N' or 'n', and is n otherwise. Before entry with TRANSA = 'N' or 'n', the leading n by k part of the array A must contain the matrix A, otherwise the leading k by n part of the array A must contain the matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When TRANSA = 'N' or 'n' then LDA must be at least $\max(1, n)$, otherwise LDA must be at least $\max(1, k)$. Unchanged on exit.

B (input)

DOUBLE PRECISION array of DIMENSION (LDB, kb), where kb is k when TRANSA = 'N' or 'n', and is n otherwise. Before entry with TRANSA = 'N' or 'n', the leading n by k part of the array B must contain the matrix B, otherwise the leading k by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. When TRANSA = 'N' or 'n' then LDB must be at least $\max(1, n)$, otherwise LDB must be at least $\max(1, k)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. Unchanged on exit.

C (input/output)

DOUBLE PRECISION array of DIMENSION (LDC, n).

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array C must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of C is not referenced. On exit, the upper triangular part of the array C is overwritten by the upper triangular part of the updated matrix.

Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array C must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of C is not referenced. On exit, the lower triangular part of the array C is overwritten by the lower triangular part of the updated matrix.

lar part of C is not referenced. On exit, the lower triangular part of the array C is overwritten by the lower triangular part of the updated matrix.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. LDC must be at least $\max(1, n)$. Unchanged on exit.

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NAME

dsyrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE DSYRFS(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB, X,  
                 LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER IPIVOT(*), WORK2(*)  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DSYRFS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,  
                    X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*), WORK2(*)  
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYRFS(UPLO, N, NRHS, A, [LDA], AF, [LDAF], IPIVOT, B, [LDB],  
                X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, WORK2  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK  
REAL(8), DIMENSION(:,:) :: A, AF, B, X
```

```
SUBROUTINE SYRFS_64(UPLO, N, NRHS, A, [LDA], AF, [LDAF], IPIVOT, B,  
                   [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
```

```
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
void dsyrfs(char uplo, int n, int nrhs, double *a, int lda,
            double *af, int ldaf, int *ipivot, double *b, int
            ldb, double *x, int ldx, double *ferr, double
            *berr, int *info);

void dsyrfs_64(char uplo, long n, long nrhs, double *a, long
               lda, double *af, long ldaf, long *ipivot, double
               *b, long ldb, double *x, long ldx, double *ferr,
               double *berr, long *info);
```

PURPOSE

dsyrfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)

The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^T$ or $A = L*D*L^T$ as computed by DSYTRF.

LDAF (input)

The leading dimension of the array AF. LDAF \geq max(1,N).

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by DSYTRF.

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)

On entry, the solution matrix X, as computed by DSYTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dsyrk - perform one of the symmetric rank k operations C
:= alpha*A*A' + beta*C or C := alpha*A'*A + beta*C

SYNOPSIS

```
SUBROUTINE DSYRK(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
INTEGER N, K, LDA, LDC  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), C(LDC,*)
```

```
SUBROUTINE DSYRK_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
INTEGER*8 N, K, LDA, LDC  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION A(LDA,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE SYRK(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA, C,  
[LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
INTEGER :: N, K, LDA, LDC  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:, :) :: A, C
```

```
SUBROUTINE SYRK_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA,  
C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
INTEGER(8) :: N, K, LDA, LDC  
REAL(8) :: ALPHA, BETA  
REAL(8), DIMENSION(:, :) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsyrk(char uplo, char transa, int n, int k, double
```

```

        alpha, double *a, int lda, double beta, double *c,
        int ldc);

void dsyrk_64(char uplo, char transa, long n, long k, double
        alpha, double *a, long lda, double beta, double
        *c, long ldc);

```

PURPOSE

dsyrk performs one of the symmetric rank k operations $C := \alpha A^T A + \beta C$ or $C := \alpha A A^T + \beta C$ where α and β are scalars, C is an n by n symmetric matrix and A is an n by k matrix in the first case and a k by n matrix in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A^T A + \beta C$.

TRANSA = 'T' or 't' $C := \alpha A A^T + \beta C$.

TRANSA = 'C' or 'c' $C := \alpha A^T A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrix A , and on entry with TRANSA = 'T' or 't' or 'C' or 'c', K specifies the number of rows of the matrix A . K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

A (input)

DOUBLE PRECISION array of DIMENSION (LDA, ka),
where ka is k when TRANSA = 'N' or 'n', and is
n otherwise. Before entry with TRANSA = 'N' or
'n', the leading n by k part of the array A
must contain the matrix A, otherwise the leading
k by n part of the array A must contain the
matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A
as declared in the calling (sub) program.
When TRANSA = 'N' or 'n' then LDA must be at
least $\max(1, n)$, otherwise LDA must be at
least $\max(1, k)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta.
Unchanged on exit.

C (input/output)

DOUBLE PRECISION array of DIMENSION (LDC, n).

Before entry with UPLO = 'U' or 'u', the lead-
ing n by n upper triangular part of the array C
must contain the upper triangular part of the
symmetric matrix and the strictly lower triangu-
lar part of C is not referenced. On exit, the
upper triangular part of the array C is overwrit-
ten by the upper triangular part of the updated
matrix.

Before entry with UPLO = 'L' or 'l', the lead-
ing n by n lower triangular part of the array C
must contain the lower triangular part of the
symmetric matrix and the strictly upper triangu-
lar part of C is not referenced. On exit, the
lower triangular part of the array C is overwrit-
ten by the lower triangular part of the updated
matrix.

LDC (input)

On entry, LDC specifies the first dimension of C
as declared in the calling (sub) program.
LDC must be at least $\max(1, n)$. Unchanged
on exit.

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NAME

dsysv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DSYSV(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK, LWORK,  
INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDB, LWORK, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), WORK(*)
```

```
SUBROUTINE DSYSV_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK, LWORK,  
INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDB, LWORK, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYSV(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],  
[LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDB, LWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,) :: A, B
```

```
SUBROUTINE SYSV_64(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],  
[LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDB, LWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>

void dsysv(char uplo, int n, int nrhs, double *a, int lda,
           int *ipivot, double *b, int ldb, int *info);
void dsysv_64(char uplo, long n, long nrhs, double *a, long
              lda, long *ipivot, double *b, long ldb, long
              *info);
```

PURPOSE

dsysv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric matrix and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{**T}$, if UPLO = 'U', or

$A = L * D * L^{**T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U * D * U^{**T}$ or $A = L * D * L^{**T}$ as computed by DSYTRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D , as determined by DSYTRF. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B .
On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LWORK$.

LWORK (input)

The length of $WORK$. $LWORK \geq 1$, and for best performance $LWORK \geq N*NB$, where NB is the optimal blocksize for DSYTRF.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $WORK$ array, returns this value as the first entry of the $WORK$ array, and no error message related to $LWORK$ is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

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NAME

dsysvx - use the diagonal pivoting factorization to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE DSYSVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,
  LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE DSYSVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
  B, LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYSVX(FACT, UPLO, N, NRHS, A, [LDA], AF, [LDAF], IPIVOT,
  B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK], [WORK2],
  [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, AF, B, X
```

```
SUBROUTINE SYSVX_64(FACT, UPLO, N, NRHS, A, [LDA], AF, [LDAF],
  IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK],
  [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: FACT, UPLO
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, AF, B, X

```

C INTERFACE

```

#include <sunperf.h>

void dsysvx(char fact, char uplo, int n, int nrhs, double
            *a, int lda, double *af, int ldaf, int *ipivot,
            double *b, int ldb, double *x, int ldx, double
            *rcond, double *ferr, double *berr, int *info);

void dsysvx_64(char fact, char uplo, long n, long nrhs, dou-
               ble *a, long lda, double *af, long ldaf, long
               *ipivot, double *b, long ldb, double *x, long ldx,
               double *rcond, double *ferr, double *berr, long
               *info);

```

PURPOSE

dsysvx uses the diagonal pivoting factorization to compute the solution to a real system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'N', the diagonal pivoting method is used to factor A.

The form of the factorization is

$A = U * D * U^{*T}$, if UPLO = 'U', or

$A = L * D * L^{*T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices, and D is symmetric and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with INFO = i. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

3. The system of equations is solved for X using the factored form

of A.
4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by DSYTRF.

If FACT = 'N', then AF is an output argument and on exit returns the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

IPIVOT (input or output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges

and the block structure of D , as determined by DSYTRF. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

If $FACT = 'N'$, then $IPIVOT$ is an output argument and on exit contains details of the interchanges and the block structure of D , as determined by DSYTRF.

B (input) The N -by- $NRHS$ right hand side matrix B .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

X (output)

If $INFO = 0$ or $INFO = N+1$, the N -by- $NRHS$ solution matrix X .

LDX (input)

The leading dimension of the array X . $LDX \geq \max(1,N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A . If $RCOND$ is less than the machine precision (in particular, if $RCOND = 0$), the matrix is singular to working precision. This condition is indicated by a return code of $INFO > 0$.

FERR (output)

The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for $RCOND$, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LDWORK$.

LDWORK (input)

The length of $WORK$. $LDWORK \geq 3*N$, and for best

performance LDWORK \geq N*N*NB, where NB is the optimal blocksize for DSYTRF.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

dsytd2 - reduce a real symmetric matrix A to symmetric tri-diagonal form T by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE DSYTD2(UPLO, N, A, LDA, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
DOUBLE PRECISION A(LDA,*), D(*), E(*), TAU(*)
```

```
SUBROUTINE DSYTD2_64(UPLO, N, A, LDA, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION A(LDA,*), D(*), E(*), TAU(*)
```

F95 INTERFACE

```
SUBROUTINE SYTD2(UPLO, N, A, [LDA], D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
REAL(8), DIMENSION(:) :: D, E, TAU  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYTD2_64(UPLO, N, A, [LDA], D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
REAL(8), DIMENSION(:) :: D, E, TAU  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsytd2(char uplo, int n, double *a, int lda, double *d,  
           double *e, double *tau, int *info);
```

```
void dsytd2_64(char uplo, long n, double *a, long lda, double *d, double *e, double *tau, long *info);
```

PURPOSE

dsytd2 reduces a real symmetric matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation: $Q^* A Q = T$.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored:
= 'U': Upper triangular
= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input) On entry, the symmetric matrix A. If UPLO = 'U', the leading n-by-n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n-by-n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

D (output)

The diagonal elements of the tridiagonal matrix T:
 $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i, i+1)$ if UPLO = 'U', $E(i) = A(i+1, i)$ if UPLO = 'L'.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(i+1:n) = 0$ and $v(i) = 1$; $v(1:i-1)$ is stored on exit in $A(1:i-1, i+1)$, and tau in $TAU(i)$.

If UPLO = 'L', the matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(1:i) = 0$ and $v(i+1) = 1$; $v(i+2:n)$ is stored on exit in $A(i+2:n, i)$, and tau in $TAU(i)$.

The contents of A on exit are illustrated by the following examples with $n = 5$:

if UPLO = 'U':	if UPLO = 'L':
(d e v2 v3 v4)	(d
))
(d e v3 v4)	(e d
))
(d e v4)	(v1 e d
))
(d e)	(v1 v2 e d
))
(d)	(v1 v2 v3 e d
))

where d and e denote diagonal and off-diagonal elements of T, and v_i denotes an element of the vector defining H(i).

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NAME

dsytf2 - compute the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE DSYTF2(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
INTEGER IPIV(*)  
DOUBLE PRECISION A(LDA,*)
```

```
SUBROUTINE DSYTF2_64(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIV(*)  
DOUBLE PRECISION A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE SYTF2(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYTF2_64(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsytf2(char uplo, int n, double *a, int lda, int *ipiv,
```

```

        int *info);

void dsytf2_64(char uplo, long n, double *a, long lda, long
        *ipiv, long *info);

```

PURPOSE

dsytf2 computes the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U' \quad \text{or} \quad A = L^*D^*L'$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, U' is the transpose of U, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored:

= 'U': Upper triangular
 = 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading n-by-n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n-by-n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIV (output)

Details of the interchanges and the block structure of D. If IPIV(k) > 0, then rows and columns k and IPIV(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIV(k) = IPIV(k-1) < 0, then rows and columns k-1 and -IPIV(k) were interchanged and D(k-1:k, k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIV(k) = IPIV(k+1) < 0, then rows and columns k+1 and

-IPIV(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

INFO (output)

= 0: successful exit
 < 0: if INFO = -k, the k-th argument had an illegal value
 > 0: if INFO = k, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

1-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

dsytrd - reduce a real symmetric matrix A to real symmetric tridiagonal form T by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE DSYTRD(UPLO, N, A, LDA, D, E, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), D(*), E(*), TAU(*), WORK(*)
```

```
SUBROUTINE DSYTRD_64(UPLO, N, A, LDA, D, E, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), D(*), E(*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRD(UPLO, N, A, [LDA], D, E, TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: D, E, TAU, WORK  
REAL(8), DIMENSION(:,) :: A
```

```
SUBROUTINE SYTRD_64(UPLO, N, A, [LDA], D, E, TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: D, E, TAU, WORK  
REAL(8), DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsytrd(char uplo, int n, double *a, int lda, double *d,
```

```

        double *e, double *tau, int *info);

void dsytrd_64(char uplo, long n, double *a, long lda, double
 *d, double *e, double *tau, long *info);

```

PURPOSE

dsytrd reduces a real symmetric matrix A to real symmetric tridiagonal form T by an orthogonal similarity transformation: $Q^*T * A * Q = T$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

D (output)

The diagonal elements of the tridiagonal matrix T:
 $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i, i+1)$ if UPLO = 'U', $E(i) = A(i+1, i)$ if UPLO = 'L'.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. LWORK ≥ 1 . For optimum performance LWORK $\geq N \cdot NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(i+1:n) = 0$ and $v(i) = 1$; $v(1:i-1)$ is stored on exit in $A(1:i-1, i+1)$, and tau in TAU(i).

If UPLO = 'L', the matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(1:i) = 0$ and $v(i+1) = 1$; $v(i+2:n)$ is stored on exit in $A(i+2:n, i)$, and tau in TAU(i).

The contents of A on exit are illustrated by the following examples with $n = 5$:

if UPLO = 'U':	if UPLO = 'L':
(d e v2 v3 v4)	(d
))
(d e v3 v4)	(e d
))
(d e v4)	(v1 e d
))
(d e)	(v1 v2 e d

$$\begin{pmatrix} & & & & \\ & & & & \\ & & d & & \\ & & & & \\ & & & & \end{pmatrix} \begin{pmatrix} v_1 & v_2 & v_3 & e & d \end{pmatrix}$$

where d and e denote diagonal and off-diagonal elements of T , and v_i denotes an element of the vector defining $H(i)$.

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NAME

dsytrf - compute the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE DSYTRF(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, LDWORK, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DSYTRF_64(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, LDWORK, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRF(UPLO, N, A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYTRF_64(UPLO, N, A, [LDA], IPIVOT, [WORK], [LDWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>

void dsytrf(char uplo, int n, double *a, int lda, int
            *ipivot, int *info);

void dsytrf_64(char uplo, long n, double *a, long lda, long
               *ipivot, long *info);
```

PURPOSE

dsytrf computes the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method. The form of the factorization is

$$A = U*D*U^{**T} \quad \text{or} \quad A = L*D*L^{**T}$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and

D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of WORK. LDWORK >=1. For best performance LDWORK >= N*NB, where NB is the block size returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

If UPLO = 'U', then $A = U^*D^*U'$, where

$$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots,$$

i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by IPIVOT(k), and $U(k)$ is a unit upper triangular matrix, such that if the diagonal block $D(k)$ is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(1:k-1,k)$. If s = 2, the upper triangle of $D(k)$ overwrites $A(k-1,k-1)$, $A(k-1,k)$, and $A(k,k)$, and v overwrites $A(1:k-2,k-1:k)$.

If UPLO = 'L', then $A = L^*D^*L'$, where

$$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots,$$

i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by IPIVOT(k), and $L(k)$ is a unit lower triangular matrix, such that if the diagonal block $D(k)$ is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(k+1:n,k)$. If $s = 2$, the lower triangle of $D(k)$ overwrites $A(k,k)$, $A(k+1,k)$, and $A(k+1,k+1)$, and v overwrites $A(k+2:n,k:k+1)$.

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NAME

dsytri - compute the inverse of a real symmetric indefinite matrix A using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by DSYTRF

SYNOPSIS

```
SUBROUTINE DSYTRI(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DSYTRI_64(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRI(UPLO, N, A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE SYTRI_64(UPLO, N, A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```

void dsytri(char uplo, int n, double *a, int lda, int
            *ipivot, int *info);

void dsytri_64(char uplo, long n, double *a, long lda, long
               *ipivot, long *info);

```

PURPOSE

dsytri computes the inverse of a real symmetric indefinite matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by DSYTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U*D*U**T$;
 = 'L': Lower triangular, form is $A = L*D*L**T$.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by DSYTRF.

On exit, if INFO = 0, the (symmetric) inverse of the original matrix. If UPLO = 'U', the upper triangular part of the inverse is formed and the part of A below the diagonal is not referenced; if UPLO = 'L' the lower triangular part of the inverse is formed and the part of A above the diagonal is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by DSYTRF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

dsytrs - solve a system of linear equations $A \cdot X = B$ with a real symmetric matrix A using the factorization $A = U \cdot D \cdot U^T$ or $A = L \cdot D \cdot L^T$ computed by DSYTRF

SYNOPSIS

```
SUBROUTINE DSYTRS(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DSYTRS_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SYTRS(UPLO, N, NRHS, A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE SYTRS_64(UPLO, N, NRHS, A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dsytrs(char uplo, int n, int nrhs, double *a, int lda,  
            int *ipivot, double *b, int ldb, int *info);
```

```
void dsytrs_64(char uplo, long n, long nrhs, double *a, long
    lda, long *ipivot, double *b, long ldb, long
    *info);
```

PURPOSE

dsytrs solves a system of linear equations $A \cdot X = B$ with a real symmetric matrix A using the factorization $A = U \cdot D \cdot U^{**T}$ or $A = L \cdot D \cdot L^{**T}$ computed by DSYTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U \cdot D \cdot U^{**T}$;
= 'L': Lower triangular, form is $A = L \cdot D \cdot L^{**T}$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by DSYTRF.

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by DSYTRF.

B (input/output)

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

dtbcon - estimate the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE DTBCON(NORM, UPLO, DIAG, N, KD, A, LDA, RCOND, WORK,  
                 WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER N, KD, LDA, INFO  
INTEGER WORK2(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DTBCON_64(NORM, UPLO, DIAG, N, KD, A, LDA, RCOND, WORK,  
                   WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER*8 N, KD, LDA, INFO  
INTEGER*8 WORK2(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TBCON(NORM, UPLO, DIAG, [N], KD, A, [LDA], RCOND, [WORK],  
               [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER :: N, KD, LDA, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TBCON_64(NORM, UPLO, DIAG, [N], KD, A, [LDA], RCOND,  
                  [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER(8) :: N, KD, LDA, INFO
```

```

INTEGER(8), DIMENSION(:) :: WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A

```

C INTERFACE

```

#include <sunperf.h>
void dtbcon(char norm, char uplo, char diag, int n, int kd,
            double *a, int lda, double *rcond, int *info);

void dtbcon_64(char norm, char uplo, char diag, long n, long
               kd, double *a, long lda, double *rcond, long
               *info);

```

PURPOSE

dtbcon estimates the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A)))$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
 = '1' or 'O': 1-norm;
 = 'I': Infinity-norm.

UPL0 (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. N >= 0.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. KD >= 0.

A (input) The upper or lower triangular band matrix A, stored in the first kd+1 rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPL0 = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPL0 = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)
The leading dimension of the array A. LDA \geq
KD+1.

RCOND (output)
The reciprocal of the condition number of the
matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)
dimension(3*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

dtbmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

SYNOPSIS

```
SUBROUTINE DTBMV(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, K, LDA, INCY  
DOUBLE PRECISION A(LDA,*), Y(*)
```

```
SUBROUTINE DTBMV_64(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, K, LDA, INCY  
DOUBLE PRECISION A(LDA,*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TBMV(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, K, LDA, INCY  
REAL(8), DIMENSION(:) :: Y  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TBMV_64(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, K, LDA, INCY  
REAL(8), DIMENSION(:) :: Y  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtbmv(char uplo, char transa, char diag, int n, int k,  
double *a, int lda, double *y, int incy);
```

```
void dtbmv_64(char uplo, char transa, char diag, long n,
```

```
long k, double *a, long lda, double *y, long
incy);
```

PURPOSE

dtbmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular band matrix, with $(k + 1)$ diagonals.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := A'*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

K (input)

On entry with UPLO = 'U' or 'u', K specifies the number of super-diagonals of the matrix A . On

entry with UPLO = 'L' or 'l', K specifies the number of sub-diagonals of the matrix A. K >= 0. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading (k + 1) by n part of the array A must contain the upper triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (k + 1) of the array, the first super-diagonal starting at position 2 in row k, and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer an upper triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer a lower triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Note that when DIAG = 'U' or 'u' the elements of the array A corresponding to the diagonal elements of the matrix are not referenced, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= (k + 1). Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

dtbrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix

SYNOPSIS

```
SUBROUTINE DTBRFS(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B, LDB,  
  X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, KD, NRHS, LDA, LDB, LDX, INFO  
INTEGER WORK2(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE DTBRFS_64(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B,  
  LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, KD, NRHS, LDA, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TBRFS(UPLO, [TRANSA], DIAG, N, KD, NRHS, A, [LDA], B,  
  [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, KD, NRHS, LDA, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK  
REAL(8), DIMENSION(:,:) :: A, B, X
```

```
SUBROUTINE TBRFS_64(UPLO, [TRANSA], DIAG, N, KD, NRHS, A, [LDA],  
  B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2
```

```
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, B, X
```

C INTERFACE

```
#include <sunperf.h>
void dtbrfs(char uplo, char transa, char diag, int n, int
            kd, int nrhs, double *a, int lda, double *b, int
            ldb, double *x, int ldx, double *ferr, double
            *berr, int *info);

void dtbrfs_64(char uplo, char transa, char diag, long n,
              long kd, long nrhs, double *a, long lda, double
              *b, long ldb, double *x, long ldx, double *ferr,
              double *berr, long *info);
```

PURPOSE

dtbrfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix.

The solution matrix X must be computed by DTBTRS or some other means before entering this routine. DTBRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first $kd+1$ rows of the array. The

j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. LDA \geq KD+1.

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input) The solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dtbsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

SYNOPSIS

```
SUBROUTINE DTBSV(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, K, LDA, INCY  
DOUBLE PRECISION A(LDA,*), Y(*)
```

```
SUBROUTINE DTBSV_64(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, K, LDA, INCY  
DOUBLE PRECISION A(LDA,*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TBSV(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, K, LDA, INCY  
REAL(8), DIMENSION(:) :: Y  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TBSV_64(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, K, LDA, INCY  
REAL(8), DIMENSION(:) :: Y  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtbsv(char uplo, char transa, char diag, int n, int k,  
double *a, int lda, double *y, int incy);
```

```
void dtbsv_64(char uplo, char transa, char diag, long n,
```

```
long k, double *a, long lda, double *y, long
incy);
```

PURPOSE

dtbsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular band matrix, with $(k + 1)$ diagonals.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the equations to be solved as follows:

TRANSA = 'N' or 'n' $A*x = b$.

TRANSA = 'T' or 't' $A'*x = b$.

TRANSA = 'C' or 'c' $A'*x = b$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A .

N >= 0. Unchanged on exit.

K (input)

On entry with UPLO = 'U' or 'u', K specifies the number of super-diagonals of the matrix A. On entry with UPLO = 'L' or 'l', K specifies the number of sub-diagonals of the matrix A. K >= 0. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading (k + 1) by n part of the array A must contain the upper triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (k + 1) of the array, the first super-diagonal starting at position 2 in row k, and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer an upper triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
  10 CONTINUE
  20 CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer a lower triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
  10 CONTINUE
  20 CONTINUE
```

Note that when DIAG = 'U' or 'u' the elements of the array A corresponding to the diagonal elements of the matrix are not referenced, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= (k + 1). Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element

right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

dtbtrs - solve a triangular system of the form $A * X = B$
or $A^{**T} * X = B$,

SYNOPSIS

```
SUBROUTINE DTBTRS(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B, LDB,  
INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, KD, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DTBTRS_64(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B,  
LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TBTRS(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA], B,  
[LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE TBTRS_64(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA], B,  
[LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtbtrs(char uplo, char transa, char diag, int n, int  
kd, int nrhs, double *a, int lda, double *b, int  
ldb, int *info);
```

```
void dtbtrs_64(char uplo, char transa, char diag, long n,
              long kd, long nrhs, double *a, long lda, double
              *b, long ldb, long *info);
```

PURPOSE

dtbtrs solves a triangular system of the form

$A * X = B$ or $A^{**T} * X = B$

where A is a triangular band matrix of order N, and B is an N-by NRHS matrix. A check is made to verify that A is non-singular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

TRANSA (input)

Specifies the form the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first $kd+1$ rows of A. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

B (input/output)

On entry, the right hand side matrix B. On exit,

if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element of A is zero, indicating that the matrix is singular and the solutions X have not been computed.

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NAME

dtgevc - compute some or all of the right and/or left generalized eigenvectors of a pair of real upper triangular matrices (A,B)

SYNOPSIS

```
SUBROUTINE DTGEVC(SIDE, HOWMNY, SELECT, N, A, LDA, B, LDB, VL, LDVL,  
  VR, LDVR, MM, M, WORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
INTEGER N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL SELECT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*),  
WORK(*)
```

```
SUBROUTINE DTGEVC_64(SIDE, HOWMNY, SELECT, N, A, LDA, B, LDB, VL,  
  LDVL, VR, LDVR, MM, M, WORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL*8 SELECT(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGEVC(SIDE, HOWMNY, SELECT, N, A, [LDA], B, [LDB], VL,  
  [LDVL], VR, [LDVR], MM, M, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
INTEGER :: N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL, DIMENSION(:) :: SELECT  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:) :: A, B, VL, VR
```

```
SUBROUTINE TGEVC_64(SIDE, HOWMNY, SELECT, N, A, [LDA], B, [LDB], VL,  
  [LDVL], VR, [LDVR], MM, M, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY
```

```

INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, MM, M, INFO
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:,:) :: A, B, VL, VR

```

C INTERFACE

```

#include <sunperf.h>
void dtgevc(char side, char howmny, int *select, int n, double
    *a, int lda, double *b, int ldb, double *vl,
    int ldvl, double *vr, int ldvr, int mm, int *m,
    int *info);

void dtgevc_64(char side, char howmny, long *select, long n,
    double *a, long lda, double *b, long ldb, double
    *vl, long ldvl, double *vr, long ldvr, long mm,
    long *m, long *info);

```

PURPOSE

dtgevc computes some or all of the right and/or left generalized eigenvectors of a pair of real upper triangular matrices (A,B).

The right generalized eigenvector x and the left generalized eigenvector y of (A,B) corresponding to a generalized eigenvalue w are defined by:

$$(A - wB) * x = 0 \quad \text{and} \quad y^{*H} * (A - wB) = 0$$

where y^{*H} denotes the conjugate transpose of y .

If an eigenvalue w is determined by zero diagonal elements of both A and B , a unit vector is returned as the corresponding eigenvector.

If all eigenvectors are requested, the routine may either return the matrices X and/or Y of right or left eigenvectors of (A,B), or the products $Z*X$ and/or $Q*Y$, where Z and Q are input orthogonal matrices. If (A,B) was obtained from the generalized real-Schur factorization of an original pair of matrices

$$(A0, B0) = (Q*A*Z^{*H}, Q*B*Z^{*H}),$$

then $Z*X$ and $Q*Y$ are the matrices of right or left eigenvectors of A .

A must be block upper triangular, with 1-by-1 and 2-by-2 diagonal blocks. Corresponding to each 2-by-2 diagonal block is a complex conjugate pair of eigenvalues and eigenvectors; only one eigenvector of the pair is computed, namely the one corresponding to the eigenvalue with positive imaginary part.

ARGUMENTS

SIDE (input)

= 'R': compute right eigenvectors only;
= 'L': compute left eigenvectors only;
= 'B': compute both right and left eigenvectors.

HOWMNY (input)
= 'A': compute all right and/or left eigenvectors;
= 'B': compute all right and/or left eigenvectors,
and backtransform them using the input matrices
supplied in VR and/or VL; = 'S': compute selected
right and/or left eigenvectors, specified by the
logical array SELECT.

SELECT (input)
If HOWMNY='S', SELECT specifies the eigenvectors
to be computed. If HOWMNY='A' or 'B', SELECT is
not referenced. To select the real eigenvector
corresponding to the real eigenvalue $w(j)$,
SELECT(j) must be set to .TRUE. To select the
complex eigenvector corresponding to a complex
conjugate pair $w(j)$ and $w(j+1)$, either SELECT(j)
or SELECT(j+1) must be set to .TRUE..

N (input) The order of the matrices A and B. $N \geq 0$.

A (input) The upper quasi-triangular matrix A.

LDA (input)
The leading dimension of array A. $LDA \geq \max(1, N)$.

B (input) The upper triangular matrix B. If A has a 2-by-2
diagonal block, then the corresponding 2-by-2
block of B must be diagonal with positive ele-
ments.

LDB (input)
The leading dimension of array B. $LDB \geq \max(1, N)$.

VL (input/output)
On entry, if SIDE = 'L' or 'B' and HOWMNY = 'B',
VL must contain an N-by-N matrix Q (usually the
orthogonal matrix Q of left Schur vectors returned
by SHGEQZ). On exit, if SIDE = 'L' or 'B', VL
contains: if HOWMNY = 'A', the matrix Y of left
eigenvectors of (A,B); if HOWMNY = 'B', the matrix
 $Q*Y$; if HOWMNY = 'S', the left eigenvectors of
(A,B) specified by SELECT, stored consecutively in
the columns of VL, in the same order as their
eigenvalues. If SIDE = 'R', VL is not referenced.

A complex eigenvector corresponding to a complex
eigenvalue is stored in two consecutive columns,
the first holding the real part, and the second
the imaginary part.

LDVL (input)
The leading dimension of array VL. $LDVL \geq \max(1, N)$ if SIDE = 'L' or 'B'; $LDVL \geq 1$ other-
wise.

VR (input/output)

On entry, if SIDE = 'R' or 'B' and HOWMNY = 'B', VR must contain an N-by-N matrix Q (usually the orthogonal matrix Z of right Schur vectors returned by SHGEQZ). On exit, if SIDE = 'R' or 'B', VR contains: if HOWMNY = 'A', the matrix X of right eigenvectors of (A,B); if HOWMNY = 'B', the matrix Z*X; if HOWMNY = 'S', the right eigenvectors of (A,B) specified by SELECT, stored consecutively in the columns of VR, in the same order as their eigenvalues. If SIDE = 'L', VR is not referenced.

A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the real part and the second the imaginary part.

LDVR (input)

The leading dimension of the array VR. LDVR \geq max(1,N) if SIDE = 'R' or 'B'; LDVR \geq 1 otherwise.

MM (input)

The number of columns in the arrays VL and/or VR. MM \geq M.

M (output)

The number of columns in the arrays VL and/or VR actually used to store the eigenvectors. If HOWMNY = 'A' or 'B', M is set to N. Each selected real eigenvector occupies one column and each selected complex eigenvector occupies two columns.

WORK (workspace)

dimension(6*N)

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: the 2-by-2 block (INFO:INFO+1) does not have a complex eigenvalue.

FURTHER DETAILS

Allocation of workspace:

WORK(j) = 1-norm of j-th column of A, above the diagonal

WORK(N+j) = 1-norm of j-th column of B, above the diagonal

WORK(2*N+1:3*N) = real part of eigenvector

WORK(3*N+1:4*N) = imaginary part of eigenvector

WORK(4*N+1:5*N) = real part of back-transformed eigenvector

WORK(5*N+1:6*N) = imaginary part of back-transformed eigenvector

Rowwise vs. columnwise solution methods:

Finding a generalized eigenvector consists basically of solving the singular triangular system

$$(A - w B) x = 0 \quad (\text{for right}) \text{ or: } (A - w B)^H y = 0 \\ (\text{for left})$$

Consider finding the i -th right eigenvector (assume all eigenvalues are real). The equation to be solved is:

$$0 = \sum_{k=j} C(j,k) v(k) = \sum_{k=j} C(j,k) v(k) \quad \text{for } j = i, \dots, 1$$

where $C = (A - w B)$ (The components $v(i+1:n)$ are 0.)

The "rowwise" method is:

```
(1) v(i) := 1
for j = i-1, . . . , 1:
    (2) compute s = - sum_{k=j+1}^i C(j,k) v(k) and
    (3) v(j) := s / C(j,j)
```

Step 2 is sometimes called the "dot product" step, since it is an inner product between the j -th row and the portion of the eigenvector that has been computed so far.

The "columnwise" method consists basically in doing the sums for all the rows in parallel. As each $v(j)$ is computed, the contribution of $v(j)$ times the j -th column of C is added to the partial sums. Since FORTRAN arrays are stored columnwise, this has the advantage that at each step, the elements of C that are accessed are adjacent to one another, whereas with the rowwise method, the elements accessed at a step are spaced LDA (and LDB) words apart.

When finding left eigenvectors, the matrix in question is the transpose of the one in storage, so the rowwise method then actually accesses columns of A and B at each step, and so is the preferred method.

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NAME

dtgexc - reorder the generalized real Schur decomposition of a real matrix pair (A,B) using an orthogonal equivalence transformation $(A, B) = Q * (A, B) * Z'$,

SYNOPSIS

```
SUBROUTINE DTGEXC(WANTQ, WANTZ, N, A, LDA, B, LDB, Q, LDQ, Z, LDZ,
  IFST, ILST, WORK, LWORK, INFO)
```

```
INTEGER N, LDA, LDB, LDQ, LDZ, IFST, ILST, LWORK, INFO
LOGICAL WANTQ, WANTZ
DOUBLE PRECISION A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*),
WORK(*)
```

```
SUBROUTINE DTGEXC_64(WANTQ, WANTZ, N, A, LDA, B, LDB, Q, LDQ, Z, LDZ,
  IFST, ILST, WORK, LWORK, INFO)
```

```
INTEGER*8 N, LDA, LDB, LDQ, LDZ, IFST, ILST, LWORK, INFO
LOGICAL*8 WANTQ, WANTZ
DOUBLE PRECISION A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGEXC(WANTQ, WANTZ, N, A, [LDA], B, [LDB], Q, [LDQ], Z,
  [LDZ], IFST, ILST, [WORK], [LWORK], [INFO])
```

```
INTEGER :: N, LDA, LDB, LDQ, LDZ, IFST, ILST, LWORK, INFO
LOGICAL :: WANTQ, WANTZ
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:,:) :: A, B, Q, Z
```

```
SUBROUTINE TGEXC_64(WANTQ, WANTZ, N, A, [LDA], B, [LDB], Q, [LDQ], Z,
  [LDZ], IFST, ILST, [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: N, LDA, LDB, LDQ, LDZ, IFST, ILST, LWORK, INFO
LOGICAL(8) :: WANTQ, WANTZ
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:,:) :: A, B, Q, Z
```

C INTERFACE

```
#include <sunperf.h>

void dtgexc(int wantq, int wantz, int n, double *a, int lda,
            double *b, int ldb, double *q, int ldq, double *z,
            int ldz, int *ifst, int *ilst, int *info);
void dtgexc_64(long wantq, long wantz, long n, double *a,
               long lda, double *b, long ldb, double *q, long
               ldq, double *z, long ldz, long *ifst, long *ilst,
               long *info);
```

PURPOSE

dtgexc reorders the generalized real Schur decomposition of a real matrix pair (A,B) using an orthogonal equivalence transformation

so that the diagonal block of (A, B) with row index IFST is moved to row ILST.

(A, B) must be in generalized real Schur canonical form (as returned by SGGES), i.e. A is block upper triangular with 1-by-1 and 2-by-2 diagonal blocks. B is upper triangular.

Optionally, the matrices Q and Z of generalized Schur vectors are updated.

$$\begin{aligned} Q(\text{in}) * A(\text{in}) * Z(\text{in})' &= Q(\text{out}) * A(\text{out}) * Z(\text{out})' \\ Q(\text{in}) * B(\text{in}) * Z(\text{in})' &= Q(\text{out}) * B(\text{out}) * Z(\text{out})' \end{aligned}$$

ARGUMENTS

WANTQ (input)

WANTZ (input)

N (input) The order of the matrices A and B. N >= 0.

A (input/output)

On entry, the matrix A in generalized real Schur canonical form. On exit, the updated matrix A, again in generalized real Schur canonical form.

LDA (input)

The leading dimension of the array A. LDA >= max(1,N).

B (input/output)

On entry, the matrix B in generalized real Schur canonical form (A,B). On exit, the updated matrix B, again in generalized real Schur canonical form (A,B).

LDB (input)

The leading dimension of the array B. LDB >=

max(1,N).

Q (input/output)

On entry, if WANTQ = .TRUE., the orthogonal matrix Q. On exit, the updated matrix Q. If WANTQ = .FALSE., Q is not referenced.

LDQ (input)

The leading dimension of the array Q. LDQ >= 1.
If WANTQ = .TRUE., LDQ >= N.

Z (input/output)

On entry, if WANTZ = .TRUE., the orthogonal matrix Z. On exit, the updated matrix Z. If WANTZ = .FALSE., Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1.
If WANTZ = .TRUE., LDZ >= N.

IFST (input/output)

Specify the reordering of the diagonal blocks of (A, B). The block with row index IFST is moved to row ILST, by a sequence of swapping between adjacent blocks. On exit, if IFST pointed on entry to the second row of a 2-by-2 block, it is changed to point to the first row; ILST always points to the first row of the block in its final position (which may differ from its input value by +1 or -1). 1 <= IFST, ILST <= N.

ILST (input/output)

See the description of IFST.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK >= 4*N + 16.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

=0: successful exit.

<0: if INFO = -i, the i-th argument had an illegal value.

=1: The transformed matrix pair (A, B) would be too far from generalized Schur form; the problem is ill-conditioned. (A, B) may have been partially reordered, and ILST points to the first row of the current position of the block being moved.

FURTHER DETAILS

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing
Science,
Umea University, S-901 87 Umea, Sweden.

[1] B. Kagstrom; A Direct Method for Reordering Eigenvalues
in the
Generalized Real Schur Form of a Regular Matrix Pair (A,
B), in
M.S. Moonen et al (eds), Linear Algebra for Large Scale
and
Real-Time Applications, Kluwer Academic Publ. 1993, pp
195-218.

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NAME

dtgsen - reorder the generalized real Schur decomposition of a real matrix pair (A, B) (in terms of an orthonormal equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix A and the upper triangular B

SYNOPSIS

```
SUBROUTINE DTGSEN(IJOB, WANTQ, WANTZ, SELECT, N, A, LDA, B, LDB,
    ALPHAR, ALPHAI, BETA, Q, LDQ, Z, LDZ, M, PL, PR, DIF, WORK,
    LWORK, IWORK, LIWORK, INFO)
```

```
INTEGER IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL WANTQ, WANTZ
LOGICAL SELECT(*)
DOUBLE PRECISION PL, PR
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), Q(LDQ,*), Z(LDZ,*), DIF(*), WORK(*)
```

```
SUBROUTINE DTGSEN_64(IJOB, WANTQ, WANTZ, SELECT, N, A, LDA, B, LDB,
    ALPHAR, ALPHAI, BETA, Q, LDQ, Z, LDZ, M, PL, PR, DIF, WORK,
    LWORK, IWORK, LIWORK, INFO)
```

```
INTEGER*8 IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER*8 IWORK(*)
LOGICAL*8 WANTQ, WANTZ
LOGICAL*8 SELECT(*)
DOUBLE PRECISION PL, PR
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*),
BETA(*), Q(LDQ,*), Z(LDZ,*), DIF(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGSSEN(IJOB, WANTQ, WANTZ, SELECT, N, A, [LDA], B, [LDB],
    ALPHAR, ALPHAI, BETA, Q, [LDQ], Z, [LDZ], M, PL, PR, DIF, [WORK],
    [LWORK], [IWORK], [LIWORK], [INFO])
```

```

INTEGER :: IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL :: WANTQ, WANTZ
LOGICAL, DIMENSION(:) :: SELECT
REAL(8) :: PL, PR
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, DIF, WORK
REAL(8), DIMENSION(:, :) :: A, B, Q, Z
SUBROUTINE DTGSEN_64(IJOB, WANTQ, WANTZ, SELECT, N, A, [LDA], B, [LDB],
ALPHAR, ALPHAI, BETA, Q, [LDQ], Z, [LDZ], M, PL, PR, DIF, [WORK],
[LWORK], [IWORK], [LIWORK], [INFO])

```

```

INTEGER(8) :: IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8) :: WANTQ, WANTZ
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8) :: PL, PR
REAL(8), DIMENSION(:) :: ALPHAR, ALPHAI, BETA, DIF, WORK
REAL(8), DIMENSION(:, :) :: A, B, Q, Z

```

C INTERFACE

```
#include <sunperf.h>
```

```

void dtgsen(int ijob, int wantq, int wantz, int *select, int
n, double *a, int lda, double *b, int ldb, double
*alphar, double *alphai, double *beta, double *q,
int ldq, double *z, int ldz, int *m, double *pl,
double *pr, double *dif, int *info);

```

```

void dtgsen_64(long ijob, long wantq, long wantz, long
*select, long n, double *a, long lda, double *b,
long ldb, double *alphar, double *alphai, double
*beta, double *q, long ldq, double *z, long ldz,
long *m, double *pl, double *pr, double *dif, long
*info);

```

PURPOSE

dtgsen reorders the generalized real Schur decomposition of a real matrix pair (A, B) (in terms of an orthonormal equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix A and the upper triangular B . The leading columns of Q and Z form orthonormal bases of the corresponding left and right eigenspaces (deflating subspaces). (A, B) must be in generalized real Schur canonical form (as returned by SGGES), i.e. A is block upper triangular with 1-by-1 and 2-by-2 diagonal blocks. B is upper triangular.

DTGSEN also computes the generalized eigenvalues

$$w(j) = (\text{ALPHAR}(j) + i*\text{ALPHAI}(j))/\text{BETA}(j)$$

of the reordered matrix pair (A, B) .

Optionally, DTGSEN computes the estimates of reciprocal

condition numbers for eigenvalues and eigenspaces. These are $Difu[(A_{11}, B_{11}), (A_{22}, B_{22})]$ and $Difl[(A_{11}, B_{11}), (A_{22}, B_{22})]$, i.e. the separation(s) between the matrix pairs (A_{11}, B_{11}) and (A_{22}, B_{22}) that correspond to the selected cluster and the eigenvalues outside the cluster, resp., and norms of "projections" onto left and right eigenspaces w.r.t. the selected cluster in the (1,1)-block.

ARGUMENTS

IJOB (input)

Specifies whether condition numbers are required for the cluster of eigenvalues (PL and PR) or the deflating subspaces (Difu and Difl):

=0: Only reorder w.r.t. SELECT. No extras.

=1: Reciprocal of norms of "projections" onto left and right eigenspaces w.r.t. the selected cluster (PL and PR). =2: Upper bounds on Difu and Difl. F-norm-based estimate

(DIF(1:2)).

=3: Estimate of Difu and Difl. 1-norm-based estimate

(DIF(1:2)). About 5 times as expensive as IJOB = 2. =4: Compute PL, PR and DIF (i.e. 0, 1 and 2 above): Economic version to get it all. =5: Compute PL, PR and DIF (i.e. 0, 1 and 3 above)

WANTQ (input)

WANTZ (input)

SELECT (input)

SELECT specifies the eigenvalues in the selected cluster. To select a real eigenvalue $w(j)$, SELECT(j) must be set to $w(j)$ and $w(j+1)$, corresponding to a 2-by-2 diagonal block, either SELECT(j) or SELECT(j+1) or both must be set to either both included in the cluster or both excluded.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the upper quasi-triangular matrix A, with (A, B) in generalized real Schur canonical form. On exit, A is overwritten by the reordered matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the upper triangular matrix B, with (A, B) in generalized real Schur canonical form. On exit, B is overwritten by the reordered matrix B.

LDB (input)

The leading dimension of the array B. $LDB \geq$

max(1,N).

ALPHAR (output)

On exit, $(\text{ALPHAR}(j) + \text{ALPHAI}(j)*i)/\text{BETA}(j)$, $j=1,\dots,N$, will be the generalized eigenvalues. $\text{ALPHAR}(j) + \text{ALPHAI}(j)*i$ and $\text{BETA}(j)$, $j=1,\dots,N$ are the diagonals of the complex Schur form (S,T) that would result if the 2-by-2 diagonal blocks of the real generalized Schur form of (A,B) were further reduced to triangular form using complex unitary transformations. If $\text{ALPHAI}(j)$ is zero, then the j -th eigenvalue is real; if positive, then the j -th and $(j+1)$ -st eigenvalues are a complex conjugate pair, with $\text{ALPHAI}(j+1)$ negative.

ALPHAI (output)

See the description of ALPHAR.

BETA (output)

See the description of ALPHAR.

Q (input/output)

On entry, if $\text{WANTQ} = \text{.TRUE.}$, Q is an N-by-N matrix. On exit, Q has been postmultiplied by the left orthogonal transformation matrix which reorder (A, B); The leading M columns of Q form orthonormal bases for the specified pair of left eigenspaces (deflating subspaces). If $\text{WANTQ} = \text{.FALSE.}$, Q is not referenced.

LDQ (input)

The leading dimension of the array Q. $\text{LDQ} \geq 1$; and if $\text{WANTQ} = \text{.TRUE.}$, $\text{LDQ} \geq N$.

Z (input/output)

On entry, if $\text{WANTZ} = \text{.TRUE.}$, Z is an N-by-N matrix. On exit, Z has been postmultiplied by the left orthogonal transformation matrix which reorder (A, B); The leading M columns of Z form orthonormal bases for the specified pair of left eigenspaces (deflating subspaces). If $\text{WANTZ} = \text{.FALSE.}$, Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $\text{LDZ} \geq 1$; If $\text{WANTZ} = \text{.TRUE.}$, $\text{LDZ} \geq N$.

M (output)

The dimension of the specified pair of left and right eigenspaces (deflating subspaces). $0 \leq M \leq N$.

PL (output)

If $\text{IJOB} = 1, 4$ or 5 , PL, PR are lower bounds on the reciprocal of the norm of "projections" onto left and right eigenspaces with respect to the selected cluster. $0 < \text{PL}, \text{PR} \leq 1$. If $M = 0$ or $M = N$, $\text{PL} = \text{PR} = 1$. If $\text{IJOB} = 0, 2$ or 3 , PL and PR are not referenced.

PR (output)

See the description of PL.

DIF (output)

If IJOB \geq 2, DIF(1:2) store the estimates of Difu and Difl.
If IJOB = 2 or 4, DIF(1:2) are F-norm-based upper bounds on Difu and Difl. If IJOB = 3 or 5, DIF(1:2) are 1-norm-based estimates of Difu and Difl. If M = 0 or N, DIF(1:2) = F-norm([A, B]). If IJOB = 0 or 1, DIF is not referenced.

WORK (workspace)

If IJOB = 0, WORK is not referenced. Otherwise, on exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq $4*N+16$. If IJOB = 1, 2 or 4, LWORK \geq $\text{MAX}(4*N+16, 2*M*(N-M))$. If IJOB = 3 or 5, LWORK \geq $\text{MAX}(4*N+16, 4*M*(N-M))$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

If IJOB = 0, IWORK is not referenced. Otherwise, on exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. LIWORK \geq 1. If IJOB = 1, 2 or 4, LIWORK \geq N+6. If IJOB = 3 or 5, LIWORK \geq $\text{MAX}(2*M*(N-M), N+6)$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

=0: Successful exit.
<0: If INFO = -i, the i-th argument had an illegal value.
=1: Reordering of (A, B) failed because the transformed matrix pair (A, B) would be too far from generalized Schur form; the problem is very ill-conditioned. (A, B) may have been partially reordered. If requested, 0 is returned in DIF(*), PL and PR.

FURTHER DETAILS

DTGSEN first collects the selected eigenvalues by computing orthogonal U and W that move them to the top left corner of

(A, B). In other words, the selected eigenvalues are the eigenvalues of (A11, B11) in:

$$U'(A, B)W = \begin{pmatrix} A11 & A12 & B11 & B12 \\ 0 & A22 & 0 & B22 \end{pmatrix} \begin{matrix} n1 \\ n2 \\ n1 & n2 \\ n1 & n2 \end{matrix}$$

where $N = n1+n2$ and U' means the transpose of U . The first $n1$ columns of U and W span the specified pair of left and right eigenspaces (deflating subspaces) of (A, B).

If (A, B) has been obtained from the generalized real Schur decomposition of a matrix pair $(C, D) = Q*(A, B)*Z'$, then the reordered generalized real Schur form of (C, D) is given by

$$(C, D) = (Q*U)*(U'(A, B)W)*(Z*W)',$$

and the first $n1$ columns of $Q*U$ and $Z*W$ span the corresponding deflating subspaces of (C, D) (Q and Z store $Q*U$ and $Z*W$, resp.).

Note that if the selected eigenvalue is sufficiently ill-conditioned, then its value may differ significantly from its value before reordering.

The reciprocal condition numbers of the left and right eigenspaces spanned by the first $n1$ columns of U and W (or $Q*U$ and $Z*W$) may be returned in $DIF(1:2)$, corresponding to $Difu$ and $Difl$, resp.

The $Difu$ and $Difl$ are defined as:
 $ifu[(A11, B11), (A22, B22)] = \text{sigma-min}(Zu)$
 and

where $\text{sigma-min}(Zu)$ is the smallest singular value of the $(2*n1*n2)$ -by- $(2*n1*n2)$ matrix
 $u = [\text{kron}(In2, A11) \quad -\text{kron}(A22', In1)]$
 $[\text{kron}(In2, B11) \quad -\text{kron}(B22', In1)]$.

Here, Inx is the identity matrix of size nx and $A22'$ is the transpose of $A22$. $\text{kron}(X, Y)$ is the Kronecker product between the matrices X and Y .

When $DIF(2)$ is small, small changes in (A, B) can cause large changes in the deflating subspace. An approximate (asymptotic) bound on the maximum angular error in the computed deflating subspaces is $PS * \text{norm}((A, B)) / DIF(2)$,

where EPS is the machine precision.

The reciprocal norm of the projectors on the left and right eigenspaces associated with (A11, B11) may be returned in PL and PR . They are computed as follows. First we compute L and R so that $P*(A, B)*Q$ is block diagonal, where

$$= \begin{pmatrix} I & -L \\ 0 & I \end{pmatrix} \begin{matrix} n1 \\ n2 \\ n1 & n2 \end{matrix} \quad Q = \begin{pmatrix} I & R \\ 0 & I \end{pmatrix} \begin{matrix} n1 \\ n2 \\ n1 & n2 \end{matrix}$$

and (L, R) is the solution to the generalized Sylvester equation $l1*R - L*A22 = -A12$

Then $PL = (F\text{-norm}(L)**2+1)**(-1/2)$ and $PR = (F\text{-norm}(R)**2+1)**(-1/2)$. An approximate (asymptotic) bound on the average absolute error of the selected eigenvalues is $PS * \text{norm}((A, B)) / PL$.

There are also global error bounds which valid for perturbations up to a certain restriction: A lower bound (x) on the smallest $F\text{-norm}(E,F)$ for which an eigenvalue of (A_{11}, B_{11}) may move and coalesce with an eigenvalue of (A_{22}, B_{22}) under perturbation (E,F) , (i.e. $(A + E, B + F)$), is

$$x = \min(\text{Difu}, \text{Difl}) / ((1/(PL*PL)+1/(PR*PR))**(1/2)+2*\max(1/PL, 1/PR)).$$

An approximate bound on x can be computed from $\text{DIF}(1:2)$, PL and PR .

If $y = (F\text{-norm}(E,F) / x) \leq 1$, the angles between the perturbed (L', R') and unperturbed (L, R) left and right deflating subspaces associated with the selected cluster in the $(1,1)$ -blocks can be bounded as

$$\begin{aligned} \max\text{-angle}(L, L') &\leq \arctan(y * PL / (1 - y * (1 - PL * PL)**(1/2))) \\ \max\text{-angle}(R, R') &\leq \arctan(y * PR / (1 - y * (1 - PR * PR)**(1/2))) \end{aligned}$$

See LAPACK User's Guide section 4.11 or the following references for more information.

Note that if the default method for computing the Frobenius-norm-based estimate DIF is not wanted (see SLATDF), then the parameter IDIFJB (see below) should be changed from 3 to 4 (routine SLATDF ($\text{IJOB} = 2$ will be used)). See DTGSYL for more details.

Based on contributions by

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=====

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NAME

dtgsja - compute the generalized singular value decomposition (GSVD) of two real upper triangular (or trapezoidal) matrices A and B

SYNOPSIS

```
SUBROUTINE DTGSJA(JOBV, JOBQ, M, P, N, K, L, A, LDA, B, LDB,
  TOLA, TOLB, ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, NCYCLE,
  INFO)
```

```
CHARACTER * 1 JOBV, JOBQ
INTEGER M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE, INFO
DOUBLE PRECISION TOLA, TOLB
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
U(LDU,*), V(LDV,*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE DTGSJA_64(JOBV, JOBQ, M, P, N, K, L, A, LDA, B, LDB,
  TOLA, TOLB, ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, NCYCLE,
  INFO)
```

```
CHARACTER * 1 JOBV, JOBQ
INTEGER*8 M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE,
INFO
DOUBLE PRECISION TOLA, TOLB
DOUBLE PRECISION A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
U(LDU,*), V(LDV,*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGSJA(JOBV, JOBQ, M, P, N, K, L, A, [LDA], B, [LDB],
  TOLA, TOLB, ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK],
  NCYCLE, [INFO])
```

```
CHARACTER(LEN=1) :: JOBV, JOBQ
INTEGER :: M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE,
INFO
REAL(8) :: TOLA, TOLB
REAL(8), DIMENSION(:) :: ALPHA, BETA, WORK
REAL(8), DIMENSION(:,:) :: A, B, U, V, Q
```

```
SUBROUTINE TGSJA_64(JOBV, JOBQ, M, P, N, K, L, A, [LDA], B,
```

```
[LDB], TOLA, TOLB, ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ],
[WORK], NCYCLE, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
INTEGER(8) :: M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCY-
CLE, INFO
REAL(8) :: TOLA, TOLB
REAL(8), DIMENSION(:) :: ALPHA, BETA, WORK
REAL(8), DIMENSION(:, :) :: A, B, U, V, Q
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtgsja(char jobu, char jobv, char jobq, int m, int p,
int n, int k, int l, double *a, int lda, double
*b, int ldb, double tola, double tolb, double
*alpha, double *beta, double *u, int ldu, double
*v, int ldv, double *q, int ldq, int *ncycle, int
*info);
```

```
void dtgsja_64(char jobu, char jobv, char jobq, long m, long
p, long n, long k, long l, double *a, long lda,
double *b, long ldb, double tola, double tolb,
double *alpha, double *beta, double *u, long ldu,
double *v, long ldv, double *q, long ldq, long
*ncycle, long *info);
```

PURPOSE

dtgsja computes the generalized singular value decomposition (GSVD) of two real upper triangular (or trapezoidal) matrices A and B.

On entry, it is assumed that matrices A and B have the following forms, which may be obtained by the preprocessing subroutine SGGSPV from a general M-by-N matrix A and P-by-N matrix B:

$$A = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} & \\ \begin{matrix} K \\ L \\ M-K-L \end{matrix} & \begin{pmatrix} 0 & A12 & A13 \\ 0 & 0 & A23 \\ 0 & 0 & 0 \end{pmatrix} & \text{if } M-K-L \geq 0; \end{array}$$

$$A = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} & \\ \begin{matrix} K \\ M-K \end{matrix} & \begin{pmatrix} 0 & A12 & A13 \\ 0 & 0 & A23 \end{pmatrix} & \text{if } M-K-L < 0; \end{array}$$

$$B = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} & \\ \begin{matrix} L \\ P-L \end{matrix} & \begin{pmatrix} 0 & 0 & B13 \\ 0 & 0 & 0 \end{pmatrix} & \end{array}$$

where the K-by-K matrix A12 and L-by-L matrix B13 are non-singular upper triangular; A23 is L-by-L upper triangular if M-K-L ≥ 0, otherwise A23 is (M-K)-by-L upper trapezoidal.

On exit,

$$U^*A*Q = D1*(0 \ R), \quad V^*B*Q = D2*(0 \ R),$$

where U, V and Q are orthogonal matrices, Z' denotes the transpose of Z, R is a nonsingular upper triangular matrix, and D1 and D2 are ``diagonal'' matrices, which are of the following structures:

If $M-K-L \geq 0$,

$$D1 = \begin{pmatrix} & & K & L \\ & K & (I & 0) \\ & & L & (0 & C) \\ M-K-L & (0 & 0) \end{pmatrix}$$

$$D2 = \begin{pmatrix} & & K & L \\ L & (0 & S) \\ P-L & (0 & 0) \end{pmatrix}$$

$$(0 R) = \begin{pmatrix} & & N-K-L & K & L \\ K & (0 & R11 & R12) & K \\ L & (0 & 0 & R22) & L \end{pmatrix}$$

where

$$C = \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(K+L)),$$

$$S = \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(K+L)),$$

$$C^{**2} + S^{**2} = I.$$

R is stored in A(1:K+L,N-K-L+1:N) on exit.

If $M-K-L < 0$,

$$D1 = \begin{pmatrix} & & K & M-K & K+L-M \\ & K & (I & 0 & 0) \\ M-K & (0 & C & 0) \end{pmatrix}$$

$$D2 = \begin{pmatrix} & & K & M-K & K+L-M \\ M-K & (0 & S & 0) \\ K+L-M & (0 & 0 & I) \\ P-L & (0 & 0 & 0) \end{pmatrix}$$

$$\begin{pmatrix} & & N-K-L & K & M-K & K+L-M \\ M-K & (0 & 0 & R22 & R23) \\ K+L-M & (0 & 0 & 0 & R33) \end{pmatrix}$$

where

$$C = \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(M)),$$

$$S = \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(M)),$$

$$C^{**2} + S^{**2} = I.$$

R = (R11 R12 R13) is stored in A(1:M, N-K-L+1:N) and R33 is stored

(0 R22 R23)
in B(M-K+1:L,N+M-K-L+1:N) on exit.

The computation of the orthogonal transformation matrices U, V or Q is optional. These matrices may either be formed explicitly, or they may be postmultiplied into input matrices U1, V1, or Q1.

DTGSJA essentially uses a variant of Kogbetliantz algorithm to reduce min(L,M-K)-by-L triangular (or trapezoidal) matrix A23 and L-by-L matrix B13 to the form:

$U1'*A13*Q1 = C1*R1$; $V1'*B13*Q1 = S1*R1$,
 where $U1$, $V1$ and $Q1$ are orthogonal matrix, and Z' is the
 transpose of Z . $C1$ and $S1$ are diagonal matrices satisfying
 $C1**2 + S1**2 = I$,
 and $R1$ is an L -by- L nonsingular upper triangular matrix.

ARGUMENTS

JOBV (input)

= 'U': U must contain an orthogonal matrix $U1$ on
 entry, and the product $U1*U$ is returned; = 'I': U
 is initialized to the unit matrix, and the orthog-
 onal matrix U is returned; = 'N': U is not com-
 puted.

JOBQ (input)

= 'V': V must contain an orthogonal matrix $V1$ on
 entry, and the product $V1*V$ is returned; = 'I': V
 is initialized to the unit matrix, and the orthog-
 onal matrix V is returned; = 'N': V is not com-
 puted.

JOBQ (input)

= 'Q': Q must contain an orthogonal matrix $Q1$ on
 entry, and the product $Q1*Q$ is returned; = 'I': Q
 is initialized to the unit matrix, and the orthog-
 onal matrix Q is returned; = 'N': Q is not com-
 puted.

M (input) The number of rows of the matrix A. $M \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

K (input) K and L specify the subblocks in the input
 matrices A and B:
 $A23 = A(K+1:MIN(K+L,M),N-L+1:N)$ and $B13 =$
 $B(1:L,N-L+1:N)$ of A and B, whose GSVD is going to
 be computed by DTGSJA. See Further details.

L (input) See the description of K.

A (input/output)

On entry, the M -by- N matrix A. On exit, $A(N-
 K+1:N,1:MIN(K+L,M))$ contains the triangular
 matrix R or part of R. See Purpose for details.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $\max(1,M)$.

B (input/output)

On entry, the P -by- N matrix B. On exit, if neces-
 sary, $B(M-K+1:L,N+M-K-L+1:N)$ contains a part of R.
 See Purpose for details.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,P)$.

TOLA (input)

TOLA and TOLB are the convergence criteria for the Jacobi-Kogbetliantz iteration procedure. Generally, they are the same as used in the preprocessing step, say $TOLA = \max(M,N) \cdot \text{norm}(A) \cdot \text{MACHEPS}$, $TOLB = \max(P,N) \cdot \text{norm}(B) \cdot \text{MACHEPS}$.

TOLB (input)

See the description of TOLA.

ALPHA (output)

On exit, ALPHA and BETA contain the generalized singular value pairs of A and B; $ALPHA(1:K) = 1$, $BETA(1:K) = 0$, and if $M-K-L \geq 0$, $ALPHA(K+1:K+L) = \text{diag}(C)$, $BETA(K+1:K+L) = \text{diag}(S)$, or if $M-K-L < 0$, $ALPHA(K+1:M) = C$, $ALPHA(M+1:K+L) = 0$, $BETA(K+1:M) = S$, $BETA(M+1:K+L) = 1$. Furthermore, if $K+L < N$, $ALPHA(K+L+1:N) = 0$ and $BETA(K+L+1:N) = 0$.

BETA (output)

See the description of ALPHA.

U (input) On entry, if $JOB_U = 'U'$, U must contain a matrix U_1 (usually the orthogonal matrix returned by SGGSV). On exit, if $JOB_U = 'I'$, U contains the orthogonal matrix U; if $JOB_U = 'U'$, U contains the product $U_1 \cdot U$. If $JOB_U = 'N'$, U is not referenced.

LDU (input)

The leading dimension of the array U. $LDU \geq \max(1,M)$ if $JOB_U = 'U'$; $LDU \geq 1$ otherwise.

V (input) On entry, if $JOB_V = 'V'$, V must contain a matrix V_1 (usually the orthogonal matrix returned by SGGSV). On exit, if $JOB_V = 'I'$, V contains the orthogonal matrix V; if $JOB_V = 'V'$, V contains the product $V_1 \cdot V$. If $JOB_V = 'N'$, V is not referenced.

LDV (input)

The leading dimension of the array V. $LDV \geq \max(1,P)$ if $JOB_V = 'V'$; $LDV \geq 1$ otherwise.

Q (input) On entry, if $JOB_Q = 'Q'$, Q must contain a matrix Q_1 (usually the orthogonal matrix returned by SGGSV). On exit, if $JOB_Q = 'I'$, Q contains the orthogonal matrix Q; if $JOB_Q = 'Q'$, Q contains the product $Q_1 \cdot Q$. If $JOB_Q = 'N'$, Q is not referenced.

LDQ (input)

The leading dimension of the array Q. $LDQ \geq \max(1,N)$ if $JOB_Q = 'Q'$; $LDQ \geq 1$ otherwise.

WORK (workspace)

dimension(2*N)

NCYCLE (output)

The number of cycles required for convergence.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

= 1: the procedure does not converge after MAXIT cycles.

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NAME

dtgsna - estimate reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B) in generalized real Schur canonical form (or of any matrix pair (Q*A*Z', Q*B*Z') with orthogonal matrices Q and Z, where Z' denotes the transpose of Z

SYNOPSIS

```
SUBROUTINE DTGSNA(JOB, HOWMNT, SELECT, N, A, LDA, B, LDB, VL, LDVL,
                 VR, LDVR, S, DIF, MM, M, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOB, HOWMNT
INTEGER N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO
INTEGER IWORK(*)
LOGICAL SELECT(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*),
S(*), DIF(*), WORK(*)
```

```
SUBROUTINE DTGSNA_64(JOB, HOWMNT, SELECT, N, A, LDA, B, LDB, VL,
                   LDVL, VR, LDVR, S, DIF, MM, M, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOB, HOWMNT
INTEGER*8 N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO
INTEGER*8 IWORK(*)
LOGICAL*8 SELECT(*)
DOUBLE PRECISION A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*),
S(*), DIF(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGSNA(JOB, HOWMNT, SELECT, [N], A, [LDA], B, [LDB], VL,
                [LDVL], VR, [LDVR], S, DIF, MM, M, [WORK], [LWORK], [IWORK],
                [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNT
INTEGER :: N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL, DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: S, DIF, WORK
```

```

REAL(8), DIMENSION(:, :) :: A, B, VL, VR

SUBROUTINE TGSNA_64(JOB, HOWMNT, SELECT, [N], A, [LDA], B, [LDB], VL,
    [LDVL], VR, [LDVR], S, DIF, MM, M, [WORK], [LWORK], [IWORK],
    [INFO])

CHARACTER(LEN=1) :: JOB, HOWMNT
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: S, DIF, WORK
REAL(8), DIMENSION(:, :) :: A, B, VL, VR

```

C INTERFACE

```

#include <sunperf.h>

void dtgsna(char job, char howmnt, int *select, int n, double
    *a, int lda, double *b, int ldb, double *vl,
    int ldvl, double *vr, int ldvr, double *s, double
    *dif, int mm, int *m, int *info);

void dtgsna_64(char job, char howmnt, long *select, long n,
    double *a, long lda, double *b, long ldb, double
    *vl, long ldvl, double *vr, long ldvr, double *s,
    double *dif, long mm, long *m, long *info);

```

PURPOSE

dtgsna estimates reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B) in generalized real Schur canonical form (or of any matrix pair (Q*A*Z', Q*B*Z') with orthogonal matrices Q and Z, where Z' denotes the transpose of Z.

(A, B) must be in generalized real Schur form (as returned by SGGES), i.e. A is block upper triangular with 1-by-1 and 2-by-2 diagonal blocks. B is upper triangular.

ARGUMENTS

JOB (input)
 Specifies whether condition numbers are required for eigenvalues (S) or eigenvectors (DIF):
 = 'E': for eigenvalues only (S);
 = 'V': for eigenvectors only (DIF);
 = 'B': for both eigenvalues and eigenvectors (S and DIF).

HOWMNT (input)
 = 'A': compute condition numbers for all eigenpairs;
 = 'S': compute condition numbers for selected eigenpairs specified by the array SELECT.

SELECT (input)
 If HOWMNT = 'S', SELECT specifies the eigenpairs

for which condition numbers are required. To select condition numbers for the eigenpair corresponding to a real eigenvalue $w(j)$, `SELECT(j)` must be set to `.TRUE.`. To select condition numbers corresponding to a complex conjugate pair of eigenvalues $w(j)$ and $w(j+1)$, either `SELECT(j)` or `SELECT(j+1)` or both, must be set to `.TRUE.`. If `HOWMNT = 'A'`, `SELECT` is not referenced.

`N` (input) The order of the square matrix pair (A, B). `N` \geq 0.

`A` (input) The upper quasi-triangular matrix A in the pair (A,B).

`LDA` (input)
The leading dimension of the array A. `LDA` \geq `max(1,N)`.

`B` (input) The upper triangular matrix B in the pair (A,B).

`LDB` (input)
The leading dimension of the array B. `LDB` \geq `max(1,N)`.

`VL` (input)
If `JOB = 'E'` or `'B'`, `VL` must contain left eigenvectors of (A, B), corresponding to the eigenpairs specified by `HOWMNT` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VL`, as returned by `DTGEVC`. If `JOB = 'V'`, `VL` is not referenced.

`LDVL` (input)
The leading dimension of the array `VL`. `LDVL` \geq 1.
If `JOB = 'E'` or `'B'`, `LDVL` \geq `N`.

`VR` (input)
If `JOB = 'E'` or `'B'`, `VR` must contain right eigenvectors of (A, B), corresponding to the eigenpairs specified by `HOWMNT` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VR`, as returned by `DTGEVC`. If `JOB = 'V'`, `VR` is not referenced.

`LDVR` (input)
The leading dimension of the array `VR`. `LDVR` \geq 1.
If `JOB = 'E'` or `'B'`, `LDVR` \geq `N`.

`S` (output)
If `JOB = 'E'` or `'B'`, the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. For a complex conjugate pair of eigenvalues two consecutive elements of `S` are set to the same value. Thus `S(j)`, `DIF(j)`, and the `j`-th columns of `VL` and `VR` all correspond to the same eigenpair (but not in general the `j`-th eigenpair, unless all eigenpairs are selected). If `JOB = 'V'`, `S` is not referenced.

`DIF` (output)
If `JOB = 'V'` or `'B'`, the estimated reciprocal con-

dition numbers of the selected eigenvectors, stored in consecutive elements of the array. For a complex eigenvector two consecutive elements of DIF are set to the same value. If the eigenvalues cannot be reordered to compute DIF(j), DIF(j) is set to 0; this can only occur when the true value would be very small anyway. If JOB = 'E', DIF is not referenced.

MM (input)

The number of elements in the arrays S and DIF. MM >= M.

M (output)

The number of elements of the arrays S and DIF used to store the specified condition numbers; for each selected real eigenvalue one element is used, and for each selected complex conjugate pair of eigenvalues, two elements are used. If HOWMNT = 'A', M is set to N.

WORK (workspace)

If JOB = 'E', WORK is not referenced. Otherwise, on exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK >= N. If JOB = 'V' or 'B' LWORK >= 2*N*(N+2)+16. If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)

dimension(N+6) If JOB = 'E', IWORK is not referenced.

INFO (output)

=0: Successful exit
<0: If INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The reciprocal of the condition number of a generalized eigenvalue $w = (a, b)$ is defined as

$$(w) = (|u'Av|^{**2} + |u'Bv|^{**2})^{**1/2} / (norm(u)*norm(v))$$

where u and v are the left and right eigenvectors of (A, B) corresponding to w; |z| denotes the absolute value of the complex number, and norm(u) denotes the 2-norm of the vector u.

The pair (a, b) corresponds to an eigenvalue $w = a/b$ (= u'Av/u'Bv) of the matrix pair (A, B). If both a and b equal zero, then (A B) is singular and S(I) = -1 is returned.

An approximate error bound on the chordal distance between the i-th computed generalized eigenvalue w and the

)

where the generalized eigenvalues $w = s_{11}/t_{11}$ and $\text{conjg}(w) = s_{22}/t_{22}$.

Then the reciprocal condition number $\text{DIF}(i)$ is bounded by

$$\min(d_1, \max(1, |\text{real}(s_{11})/\text{real}(s_{22})|) * d_2)$$

where, $d_1 = \text{Difl}((s_{11}, t_{11}), (s_{22}, t_{22})) = \text{sigma-min}(Z_1)$,
where

Z_1 is the complex 2-by-2 matrix

$$Z_1 = \begin{bmatrix} s_{11} & -s_{22} \\ t_{11} & -t_{22} \end{bmatrix},$$

This is done by computing (using real arithmetic) the roots of the characteristic polynomial $\det(Z_1' * Z_1 - \lambda I)$,

where Z_1' denotes the conjugate transpose of Z_1 and $\det(X)$ denotes

the determinant of X .

and d_2 is an upper bound on $\text{Difl}((S_{11}, T_{11}), (S_{22}, T_{22}))$,
i.e. an

upper bound on $\text{sigma-min}(Z_2)$, where Z_2 is $(2n-2)$ -by- $(2n-2)$

$$Z_2 = \begin{bmatrix} \text{kron}(S_{11}', I_{n-2}) & -\text{kron}(I_2, S_{22}) \\ \text{kron}(T_{11}', I_{n-2}) & -\text{kron}(I_2, T_{22}) \end{bmatrix}$$

Note that if the default method for computing DIF is wanted (see

DLATDF), then the parameter DIFDRI (see below) should be changed

from 3 to 4 (routine $\text{DLATDF}(IJOB = 2)$ will be used). See DTGSYL

for more details.

For each eigenvalue/vector specified by SELECT , DIF stores a Frobenius norm-based estimate of Difl .

An approximate error bound for the i -th computed eigenvector $\text{VL}(i)$ or $\text{VR}(i)$ is given by

$$\text{EPS} * \text{norm}(A, B) / \text{DIF}(i).$$

See ref. [2-3] for more details and further references.

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing Science,

Umea University, S-901 87 Umea, Sweden.

References

=====

[1] B. Kagstrom; A Direct Method for Reordering Eigenvalues in the

Generalized Real Schur Form of a Regular Matrix Pair (A, B) , in

M.S. Moonen et al (eds), Linear Algebra for Large Scale and Real-Time Applications, Kluwer Academic Publ. 1993, pp 195-218.

[2] B. Kagstrom and P. Poromaa; Computing Eigenspaces with Specified Eigenvalues of a Regular Matrix Pair (A, B) and Condition Estimation: Theory, Algorithms and Software, Report UMINF - 94.04, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, 1994. Also as LAPACK Working Note 87. To appear in Numerical Algorithms, 1996.

[3] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK Working Note 75. To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

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NAME

dtgsyl - solve the generalized Sylvester equation

SYNOPSIS

```
SUBROUTINE DTGSYL(TRANS, IJOB, M, N, A, LDA, B, LDB, C, LDC, D, LDD,  
E, LDE, F, LDF, SCALE, DIF, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 TRANS  
INTEGER IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,  
INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION SCALE, DIF  
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*), D(LDD,*),  
E(LDE,*), F(LDF,*), WORK(*)
```

```
SUBROUTINE DTGSYL_64(TRANS, IJOB, M, N, A, LDA, B, LDB, C, LDC, D,  
LDD, E, LDE, F, LDF, SCALE, DIF, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 TRANS  
INTEGER*8 IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,  
INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION SCALE, DIF  
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*), D(LDD,*),  
E(LDE,*), F(LDF,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGSYL(TRANS, IJOB, [M], [N], A, [LDA], B, [LDB], C, [LDC],  
D, [LDD], E, [LDE], F, [LDF], SCALE, DIF, [WORK], [LWORK], [IWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANS  
INTEGER :: IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,  
INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8) :: SCALE, DIF  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:) :: A, B, C, D, E, F
```

```

SUBROUTINE DTGSYL_64(TRANS, IJOB, [M], [N], A, [LDA], B, [LDB], C,
  [LDC], D, [LDD], E, [LDE], F, [LDF], SCALE, DIF, [WORK], [LWORK],
  [IWORK], [INFO])

```

```

CHARACTER(LEN=1) :: TRANS
INTEGER(8) :: IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF,
LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8) :: SCALE, DIF
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A, B, C, D, E, F

```

C INTERFACE

```
#include <sunperf.h>
```

```

void dtgsyl(char trans, int ijob, int m, int n, double *a,
  int lda, double *b, int ldb, double *c, int ldc,
  double *d, int ldd, double *e, int lde, double *f,
  int ldf, double *scale, double *dif, int *info);

```

```

void dtgsyl_64(char trans, long ijob, long m, long n, double
  *a, long lda, double *b, long ldb, double *c, long
  ldc, double *d, long ldd, double *e, long lde,
  double *f, long ldf, double *scale, double *dif,
  long *info);

```

PURPOSE

dtgsyl solves the generalized Sylvester equation:

$$\begin{aligned}
 A * R - L * B &= \text{scale} * C \\
 D * R - L * E &= \text{scale} * F
 \end{aligned}
 \tag{1}$$

where R and L are unknown m-by-n matrices, (A, D), (B, E) and (C, F) are given matrix pairs of size m-by-m, n-by-n and m-by-n, respectively, with real entries. (A, D) and (B, E) must be in generalized (real) Schur canonical form, i.e. A, B are upper quasi triangular and D, E are upper triangular.

The solution (R, L) overwrites (C, F). 0 <= SCALE <= 1 is an output scaling factor chosen to avoid overflow.

In matrix notation (1) is equivalent to solve $Zx = \text{scale} * b$, where Z is defined as

$$Z = \begin{bmatrix} \text{kron}(I_n, A) & -\text{kron}(B', I_m) \\ \text{kron}(I_n, D) & -\text{kron}(E', I_m) \end{bmatrix}
 \tag{2}$$

Here I_k is the identity matrix of size k and X' is the transpose of X. $\text{kron}(X, Y)$ is the Kronecker product between the matrices X and Y.

If TRANS = 'T', DTGSYL solves the transposed system $Z' * y = \text{scale} * b$, which is equivalent to solve for R and L in

$$\begin{aligned}
 A' * R + D' * L &= \text{scale} * C \\
 R * B' + L * E' &= \text{scale} * (-F)
 \end{aligned}
 \tag{3}$$

This case (TRANS = 'T') is used to compute an one-norm-based estimate of $\text{Dif}[(A,D), (B,E)]$, the separation between the matrix pairs (A,D) and (B,E), using SLACON.

If IJOB \geq 1, DTGSYL computes a Frobenius norm-based estimate of $\text{Dif}[(A,D), (B,E)]$. That is, the reciprocal of a lower bound on the reciprocal of the smallest singular value of Z. See [1-2] for more information.

This is a level 3 BLAS algorithm.

ARGUMENTS

TRANS (input)

= 'N', solve the generalized Sylvester equation (1). = 'T', solve the 'transposed' system (3).

IJOB (input)

Specifies what kind of functionality to be performed. =0: solve (1) only.
=1: The functionality of 0 and 3.
=2: The functionality of 0 and 4.
=3: Only an estimate of $\text{Dif}[(A,D), (B,E)]$ is computed. (look ahead strategy IJOB = 1 is used).
=4: Only an estimate of $\text{Dif}[(A,D), (B,E)]$ is computed. (SGECON on sub-systems is used). Not referenced if TRANS = 'T'.

M (input) The order of the matrices A and D, and the row dimension of the matrices C, F, R and L.

N (input) The order of the matrices B and E, and the column dimension of the matrices C, F, R and L.

A (input) The upper quasi triangular matrix A.

LDA (input)

The leading dimension of the array A. LDA \geq max(1, M).

B (input) The upper quasi triangular matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1, N).

C (input/output)

On entry, C contains the right-hand-side of the first matrix equation in (1) or (3). On exit, if IJOB = 0, 1 or 2, C has been overwritten by the solution R. If IJOB = 3 or 4 and TRANS = 'N', C holds R, the solution achieved during the computation of the Dif-estimate.

LDC (input)

The leading dimension of the array C. LDC \geq max(1, M).

D (input) The upper triangular matrix D.

LDD (input)
 The leading dimension of the array D. LDD \geq max(1, M).

E (input) The upper triangular matrix E.

LDE (input)
 The leading dimension of the array E. LDE \geq max(1, N).

F (input/output)
 On entry, F contains the right-hand-side of the second matrix equation in (1) or (3). On exit, if IJOB = 0, 1 or 2, F has been overwritten by the solution L. If IJOB = 3 or 4 and TRANS = 'N', F holds L, the solution achieved during the computation of the Dif-estimate.

LDF (input)
 The leading dimension of the array F. LDF \geq max(1, M).

SCALE (output)
 On exit SCALE is the reciprocal of a lower bound of the reciprocal of the Dif-function, i.e. SCALE is an upper bound of $\text{Dif}[(A,D), (B,E)] = \sigma_{\min}(Z)$, where Z as in (2). If IJOB = 0 or TRANS = 'T', SCALE is not touched.

DIF (output)
 On exit SCALE is the reciprocal of a lower bound of the reciprocal of the Dif-function, i.e. SCALE is an upper bound of $\text{Dif}[(A,D), (B,E)] = \sigma_{\min}(Z)$, where Z as in (2). If IJOB = 0 or TRANS = 'T', SCALE is not touched.

WORK (workspace)
 If IJOB = 0, WORK is not referenced. Otherwise, on exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq 1. If IJOB = 1 or 2 and TRANS = 'N', LWORK \geq 2*M*N.

 If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)
 dimension(M+N+2)

INFO (output)
 =0: successful exit
 <0: If INFO = -i, the i-th argument had an illegal value.
 >0: (A, D) and (B, E) have common or close eigenvalues.

FURTHER DETAILS

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing Science,
Umea University, S-901 87 Umea, Sweden.

[1] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK Working Note 75. To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

[2] B. Kagstrom, A Perturbation Analysis of the Generalized Sylvester Equation $(AR - LB, DR - LE) = (C, F)$, SIAM J. Matrix Anal. Appl., 15(4):1045-1060, 1994

[3] B. Kagstrom and L. Westin, Generalized Schur Methods with Condition Estimators for Solving the Generalized Sylvester Equation, IEEE Transactions on Automatic Control, Vol. 34, No. 7, July 1989, pp 745-751.

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NAME

dtppcon - estimate the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE DTPCON(NORM, UPLO, DIAG, N, A, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER N, INFO  
INTEGER WORK2(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(*), WORK(*)
```

```
SUBROUTINE DTPCON_64(NORM, UPLO, DIAG, N, A, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER*8 N, INFO  
INTEGER*8 WORK2(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION A(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TPCON(NORM, UPLO, DIAG, [N], A, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: A, WORK
```

```
SUBROUTINE TPCON_64(NORM, UPLO, DIAG, [N], A, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: WORK2  
REAL(8) :: RCOND
```

```
REAL(8), DIMENSION(:) :: A, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtpcon(char norm, char uplo, char diag, int n, double  
*a, double *rcond, int *info);
```

```
void dtpcon_64(char norm, char uplo, char diag, long n, dou-  
ble *a, double *rcond, long *info);
```

PURPOSE

dtpcon estimates the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$
The upper or lower triangular matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

DOUBLE PRECISION array, dimension $(3*N)$

WORK2 (workspace)

INTEGER array, dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dtpmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

SYNOPSIS

```
SUBROUTINE DTPMV(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, INCY  
DOUBLE PRECISION A(*), Y(*)
```

```
SUBROUTINE DTPMV_64(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, INCY  
DOUBLE PRECISION A(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TPMV(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, INCY  
REAL(8), DIMENSION(:) :: A, Y
```

```
SUBROUTINE TPMV_64(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, INCY  
REAL(8), DIMENSION(:) :: A, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtpmv(char uplo, char transa, char diag, int n, double  
*a, double *y, int incy);
```

```
void dtpmv_64(char uplo, char transa, char diag, long n,  
double *a, double *y, long incy);
```

PURPOSE

dtpmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := A'*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

(($n*(n+1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular matrix packed sequentially, column by column, so that $A(1)$ contains $a(1,1)$, $A(2)$ and $A(3)$ contain $a(1,2)$ and $a(2,2)$ respec-

tively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced, but are assumed to be unity. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

dtprfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix

SYNOPSIS

```
SUBROUTINE DTPRFS(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, NRHS, LDB, LDX, INFO  
INTEGER WORK2(*)  
DOUBLE PRECISION A(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),  
WORK(*)
```

```
SUBROUTINE DTPRFS_64(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
DOUBLE PRECISION A(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TPRFS(UPLO, [TRANSA], DIAG, [N], NRHS, A, B, [LDB], X, [LDX],  
    FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, NRHS, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL(8), DIMENSION(:) :: A, FERR, BERR, WORK  
REAL(8), DIMENSION(:,:) :: B, X
```

```
SUBROUTINE TPRFS_64(UPLO, [TRANSA], DIAG, [N], NRHS, A, B, [LDB], X,  
    [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2
```

```
REAL(8), DIMENSION(:) :: A, FERR, BERR, WORK
REAL(8), DIMENSION(:,:) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
void dtprfs(char uplo, char transa, char diag, int n, int
            nrhs, double *a, double *b, int ldb, double *x,
            int ldx, double *ferr, double *berr, int *info);

void dtprfs_64(char uplo, char transa, char diag, long n,
              long nrhs, double *a, double *b, long ldb, double
              *x, long ldx, double *ferr, double *berr, long
              *info);
```

PURPOSE

dtprfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix.

The solution matrix X must be computed by DTPTRS or some other means before entering this routine. DTPRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$

The upper or lower triangular matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for

$j \leq i \leq n$. If `DIAG = 'U'`, the diagonal elements of `A` are not referenced and are assumed to be 1.

`B` (input) DOUBLE PRECISION array, dimension (`LDB,NRHS`)
The right hand side matrix `B`.

`LDB` (input)
The leading dimension of the array `B`. `LDB` \geq `max(1,N)`.

`X` (input) DOUBLE PRECISION array, dimension (`LDX,NRHS`)
The solution matrix `X`.

`LDX` (input)
The leading dimension of the array `X`. `LDX` \geq `max(1,N)`.

`FERR` (output) DOUBLE PRECISION array, dimension (`NRHS`)
The estimated forward error bound for each solution vector `X(j)` (the j -th column of the solution matrix `X`). If `XTRUE` is the true solution corresponding to `X(j)`, `FERR(j)` is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in `X(j)`. The estimate is as reliable as the estimate for `RCOND`, and is almost always a slight overestimate of the true error.

`BERR` (output) DOUBLE PRECISION array, dimension (`NRHS`)
The componentwise relative backward error of each solution vector `X(j)` (i.e., the smallest relative change in any element of `A` or `B` that makes `X(j)` an exact solution).

`WORK` (workspace)
DOUBLE PRECISION array, dimension(`3*N`)

`WORK2` (workspace)
INTEGER array, dimension(`N`)

`INFO` (output)
= 0: successful exit
< 0: if `INFO = -i`, the i -th argument had an illegal value

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NAME

dtpsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

SYNOPSIS

```
SUBROUTINE DTPSV(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, INCY  
DOUBLE PRECISION A(*), Y(*)
```

```
SUBROUTINE DTPSV_64(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, INCY  
DOUBLE PRECISION A(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TPSV(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, INCY  
REAL(8), DIMENSION(:) :: A, Y
```

```
SUBROUTINE TPSV_64(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, INCY  
REAL(8), DIMENSION(:) :: A, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtpsv(char uplo, char transa, char diag, int n, double  
          *a, double *y, int incy);
```

```
void dtpsv_64(char uplo, char transa, char diag, long n,  
             double *a, double *y, long incy);
```

PURPOSE

dtpsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular matrix, supplied in packed form.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANS (input)

On entry, TRANS specifies the equations to be solved as follows:

TRANS = 'N' or 'n' $A*x = b$.

TRANS = 'T' or 't' $A'*x = b$.

TRANS = 'C' or 'c' $A'*x = b$.

Unchanged on exit.

TRANS is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

(($n*(n+1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper

triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(1, 2) and a(2, 2) respectively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced, but are assumed to be unity. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

dtptri - compute the inverse of a real upper or lower triangular matrix A stored in packed format

SYNOPSIS

```
SUBROUTINE DTPTRI(UPLO, DIAG, N, A, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER N, INFO  
DOUBLE PRECISION A(*)
```

```
SUBROUTINE DTPTRI_64(UPLO, DIAG, N, A, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER*8 N, INFO  
DOUBLE PRECISION A(*)
```

F95 INTERFACE

```
SUBROUTINE TPTRI(UPLO, DIAG, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER :: N, INFO  
REAL(8), DIMENSION(:) :: A
```

```
SUBROUTINE TPTRI_64(UPLO, DIAG, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER(8) :: N, INFO  
REAL(8), DIMENSION(:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtptri(char uplo, char diag, int n, double *a, int  
            *info);
```

```
void dtptri_64(char uplo, char diag, long n, double *a, long  
              *info);
```

PURPOSE

dtptri computes the inverse of a real upper or lower triangular matrix A stored in packed format.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) DOUBLE PRECISION array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangular matrix A, stored columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*((2*n-j)/2)) = A(i,j)$ for $j \leq i \leq n$. See below for further details. On exit, the (triangular) inverse of the original matrix, in the same packed storage format.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, A(i,i) is exactly zero. The triangular matrix is singular and its inverse can not be computed.

FURTHER DETAILS

A triangular matrix A can be transferred to packed storage using one of the following program segments:

UPLO = 'U':

```
      JC = 1
      DO 2 J = 1, N
        DO 1 I = 1, J
          A(JC+I-1) = A(I,J)
1      CONTINUE
      JC = JC + J
1
2 CONTINUE
```

UPLO = 'L':

```
      JC = 1
      DO 2 J = 1, N
        DO 1 I = J, N
          A(JC+I-J) =
1      CONTINUE
      JC = JC + N - J +
2 CONTINUE
```

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NAME

dtptrs - solve a triangular system of the form $A * X = B$
or $A^{**T} * X = B$,

SYNOPSIS

```
SUBROUTINE DTPTRS(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, NRHS, LDB, INFO  
DOUBLE PRECISION A(*), B(LDB,*)
```

```
SUBROUTINE DTPTRS_64(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, NRHS, LDB, INFO  
DOUBLE PRECISION A(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TPTRS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: A  
REAL(8), DIMENSION(:, :) :: B
```

```
SUBROUTINE TPTRS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: A  
REAL(8), DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtptrs(char uplo, char transa, char diag, int n, int  
nrhs, double *a, double *b, int ldb, int *info);
```

```
void dtptrs_64(char uplo, char transa, char diag, long n,  
long nrhs, double *a, double *b, long ldb, long
```

```
*info);
```

PURPOSE

dtpttrs solves a triangular system of the form

$$A * X = B \text{ or } A^{**T} * X = B$$

where A is a triangular matrix of order N stored in packed format, and B is an N-by-NRHS matrix. A check is made to verify that A is nonsingular.

ARGUMENTS

UPLO (input)

```
= 'U': A is upper triangular;  
= 'L': A is lower triangular.
```

TRANS (input)

```
Specifies the form of the system of equations:  
= 'N': A * X = B (No transpose)  
= 'T': A**T * X = B (Transpose)  
= 'C': A**H * X = B (Conjugate transpose = Transpose)
```

DIAG (input)

```
= 'N': A is non-unit triangular;  
= 'U': A is unit triangular.
```

N (input) The order of the matrix A. N >= 0.

NRHS (input)

```
The number of right hand sides, i.e., the number  
of columns of the matrix B. NRHS >= 0.
```

A (input) DOUBLE PRECISION array, dimension (N*(N+1)/2)

```
The upper or lower triangular matrix A, packed  
columnwise in a linear array. The j-th column of  
A is stored in the array A as follows: if UPLO =  
'U', A(i + (j-1)*j/2) = A(i,j) for 1<=i<=j; if  
UPLO = 'L', A(i + (j-1)*(2*n-j)/2) = A(i,j) for  
j<=i<=n.
```

B (input/output) DOUBLE PRECISION array, dimension (LDB,NRHS)

```
On entry, the right hand side matrix B. On exit,  
if INFO = 0, the solution matrix X.
```

LDB (input)

```
The leading dimension of the array B. LDB >=  
max(1,N).
```

INFO (output)

```
= 0: successful exit  
< 0: if INFO = -i, the i-th argument had an illegal value  
> 0: if INFO = i, the i-th diagonal element of A  
is zero, indicating that the matrix is singular  
and the solutions X have not been computed.
```


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NAME

dtrans - transpose and scale source matrix

SYNOPSIS

```
SUBROUTINE DTRANS(PLACE, SCALE, SOURCE, M, N, DEST)
```

```
CHARACTER * 1 PLACE  
INTEGER M, N  
DOUBLE PRECISION SCALE  
DOUBLE PRECISION SOURCE(*), DEST(*)
```

```
SUBROUTINE DTRANS_64(PLACE, SCALE, SOURCE, M, N, DEST)
```

```
CHARACTER * 1 PLACE  
INTEGER*8 M, N  
DOUBLE PRECISION SCALE  
DOUBLE PRECISION SOURCE(*), DEST(*)
```

F95 INTERFACE

```
SUBROUTINE TRANS([PLACE], SCALE, SOURCE, M, N, [DEST])
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER :: M, N  
REAL(8) :: SCALE  
REAL(8), DIMENSION(:) :: SOURCE, DEST
```

```
SUBROUTINE TRANS_64([PLACE], SCALE, SOURCE, M, N, [DEST])
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER(8) :: M, N  
REAL(8) :: SCALE  
REAL(8), DIMENSION(:) :: SOURCE, DEST
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrans(char place, double scale, double *source, int m,  
            int n, double *dest);
```

```
void dtrans_64(char place, double scale, double *source,
```

```
long m, long n, double *dest);
```

PURPOSE

dtrans scales and transposes the source matrix. The $N_2 \times N_1$ result is written into SOURCE when PLACE = 'I' or 'i', and DEST when PLACE = 'O' or 'o'.

```
PLACE = 'I' or 'i': SOURCE = SCALE * SOURCE'
```

```
PLACE = 'O' or 'o': DEST = SCALE * SOURCE'
```

ARGUMENTS

PLACE (input)

Type of transpose. 'I' or 'i' for in-place, 'O' or 'o' for out-of-place. 'I' is default.

SCALE (input)

Scale factor on the SOURCE matrix.

SOURCE (input/output)

(M, N) on input. Array of (N, M) on output if in-place transpose.

M (input)

Number of rows in the SOURCE matrix on input.

N (input)

Number of columns in the SOURCE matrix on input.

DEST (output)

Scaled and transposed SOURCE matrix if out-of-place transpose. Not referenced if in-place transpose.

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NAME

dtrcon - estimate the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE DTRCON(NORM, UPLO, DIAG, N, A, LDA, RCOND, WORK, WORK2,
                 INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG
INTEGER N, LDA, INFO
INTEGER WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), WORK(*)
```

```
SUBROUTINE DTRCON_64(NORM, UPLO, DIAG, N, A, LDA, RCOND, WORK, WORK2,
                   INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG
INTEGER*8 N, LDA, INFO
INTEGER*8 WORK2(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TRCON(NORM, UPLO, DIAG, [N], A, [LDA], RCOND, [WORK], [WORK2],
                [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG
INTEGER :: N, LDA, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TRCON_64(NORM, UPLO, DIAG, [N], A, [LDA], RCOND, [WORK],
                   [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG
INTEGER(8) :: N, LDA, INFO
```

```
INTEGER(8), DIMENSION(:) :: WORK2
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: WORK
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
void dtrcon(char norm, char uplo, char diag, int n, double
            *a, int lda, double *rcond, int *info);

void dtrcon_64(char norm, char uplo, char diag, long n, double
              *a, long lda, double *rcond, long *info);
```

PURPOSE

dtrcon estimates the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)
dimension(3*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dtrevc - compute some or all of the right and/or left eigenvectors of a real upper quasi-triangular matrix T

SYNOPSIS

```
SUBROUTINE DTREVC(SIDE, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,  
                 LDVR, MM, M, WORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
INTEGER N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL SELECT(*)  
DOUBLE PRECISION T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

```
SUBROUTINE DTREVC_64(SIDE, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,  
                   LDVR, MM, M, WORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
INTEGER*8 N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL*8 SELECT(*)  
DOUBLE PRECISION T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TREVC(SIDE, HOWMNY, SELECT, N, T, [LDT], VL, [LDVL], VR,  
                [LDVR], MM, M, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
INTEGER :: N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL, DIMENSION(:) :: SELECT  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:, :) :: T, VL, VR
```

```
SUBROUTINE TREVC_64(SIDE, HOWMNY, SELECT, N, T, [LDT], VL, [LDVL],  
                   VR, [LDVR], MM, M, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
INTEGER(8) :: N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL(8), DIMENSION(:) :: SELECT  
REAL(8), DIMENSION(:) :: WORK
```

```
REAL(8), DIMENSION(:,:) :: T, VL, VR
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrevc(char side, char howmny, int *select, int n, double *t, int ldt, double *vl, int ldvl, double *vr, int ldvr, int mm, int *m, int *info);
```

```
void dtrevc_64(char side, char howmny, long *select, long n, double *t, long ldt, double *vl, long ldvl, double *vr, long ldvr, long mm, long *m, long *info);
```

PURPOSE

dtrevc computes some or all of the right and/or left eigenvectors of a real upper quasi-triangular matrix T.

The right eigenvector x and the left eigenvector y of T corresponding to an eigenvalue w are defined by:

$$T*x = w*x, \quad y'*T = w*y'$$

where y' denotes the conjugate transpose of the vector y.

If all eigenvectors are requested, the routine may either return the matrices X and/or Y of right or left eigenvectors of T, or the products Q*X and/or Q*Y, where Q is an input orthogonal matrix. If T was obtained from the real-Schur factorization of an original matrix $A = Q*T*Q'$, then Q*X and Q*Y are the matrices of right or left eigenvectors of A.

T must be in Schur canonical form (as returned by SHSEQR), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign. Corresponding to each 2-by-2 diagonal block is a complex conjugate pair of eigenvalues and eigenvectors; only one eigenvector of the pair is computed, namely the one corresponding to the eigenvalue with positive imaginary part.

ARGUMENTS

SIDE (input)

```
= 'R': compute right eigenvectors only;  
= 'L': compute left eigenvectors only;  
= 'B': compute both right and left eigenvectors.
```

HOWMNY (input)

```
= 'A': compute all right and/or left eigenvectors;  
= 'B': compute all right and/or left eigenvectors, and backtransform them using the input matrices supplied in VR and/or VL; = 'S': compute selected right and/or left eigenvectors, specified
```

by the logical array SELECT.

SELECT (input/output)

If HOWMNY = 'S', SELECT specifies the eigenvectors to be computed. If HOWMNY = 'A' or 'B', SELECT is not referenced. To select the real eigenvector corresponding to a real eigenvalue $w(j)$, SELECT(j) must be set to .TRUE.. To select the complex eigenvector corresponding to a complex conjugate pair $w(j)$ and $w(j+1)$, either SELECT(j) or SELECT(j+1) must be set to .TRUE.; then on exit SELECT(j) is .TRUE. and SELECT(j+1) is .FALSE..

N (input) The order of the matrix T. $N \geq 0$.

T (input/output)

The upper quasi-triangular matrix T in Schur canonical form.

LDT (input)

The leading dimension of the array T. $LDT \geq \max(1, N)$.

VL (input/output)

On entry, if SIDE = 'L' or 'B' and HOWMNY = 'B', VL must contain an N-by-N matrix Q (usually the orthogonal matrix Q of Schur vectors returned by SHSEQR). On exit, if SIDE = 'L' or 'B', VL contains: if HOWMNY = 'A', the matrix Y of left eigenvectors of T; VL has the same quasi-lower triangular form as T. If $T(i, i)$ is a real eigenvalue, then the i-th column VL(i) of VL is its corresponding eigenvector. If $T(i:i+1, i:i+1)$ is a 2-by-2 block whose eigenvalues are complex-conjugate eigenvalues of T, then $VL(i) + \sqrt{-1} * VL(i+1)$ is the complex eigenvector corresponding to the eigenvalue with positive real part. if HOWMNY = 'B', the matrix $Q * Y$; if HOWMNY = 'S', the left eigenvectors of T specified by SELECT, stored consecutively in the columns of VL, in the same order as their eigenvalues. A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the real part, and the second the imaginary part. If SIDE = 'R', VL is not referenced.

LDVL (input)

The leading dimension of the array VL. $LDVL \geq \max(1, N)$ if SIDE = 'L' or 'B'; $LDVL \geq 1$ otherwise.

VR (input/output)

On entry, if SIDE = 'R' or 'B' and HOWMNY = 'B', VR must contain an N-by-N matrix Q (usually the orthogonal matrix Q of Schur vectors returned by SHSEQR). On exit, if SIDE = 'R' or 'B', VR contains: if HOWMNY = 'A', the matrix X of right eigenvectors of T; VR has the same quasi-upper triangular form as T. If $T(i, i)$ is a real eigenvalue, then the i-th column VR(i) of VR is its corresponding eigenvector. If $T(i:i+1, i:i+1)$ is a 2-by-2 block whose eigenvalues are complex-

conjugate eigenvalues of T, then $VR(i)+\sqrt{-1}*VR(i+1)$ is the complex eigenvector corresponding to the eigenvalue with positive real part. if HOWMNY = 'B', the matrix Q*X; if HOWMNY = 'S', the right eigenvectors of T specified by SELECT, stored consecutively in the columns of VR, in the same order as their eigenvalues. A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the real part and the second the imaginary part. If SIDE = 'L', VR is not referenced.

LDVR (input)

The leading dimension of the array VR. LDVR \geq max(1,N) if SIDE = 'R' or 'B'; LDVR \geq 1 otherwise.

MM (input)

The number of columns in the arrays VL and/or VR. MM \geq M.

M (output)

The number of columns in the arrays VL and/or VR actually used to store the eigenvectors. If HOWMNY = 'A' or 'B', M is set to N. Each selected real eigenvector occupies one column and each selected complex eigenvector occupies two columns.

WORK (workspace)

dimension(3*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The algorithm used in this program is basically backward (forward) substitution, with scaling to make the code robust against possible overflow.

Each eigenvector is normalized so that the element of largest magnitude has magnitude 1; here the magnitude of a complex number (x,y) is taken to be $|x| + |y|$.

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NAME

dtrexc - reorder the real Schur factorization of a real matrix $A = Q^*TQ^{**}T$, so that the diagonal block of T with row index IFST is moved to row ILST

SYNOPSIS

```
SUBROUTINE DTREXC(COMPQ, N, T, LDT, Q, LDQ, IFST, ILST, WORK, INFO)
```

```
CHARACTER * 1 COMPQ  
INTEGER N, LDT, LDQ, IFST, ILST, INFO  
DOUBLE PRECISION T(LDT,*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE DTREXC_64(COMPQ, N, T, LDT, Q, LDQ, IFST, ILST, WORK,  
INFO)
```

```
CHARACTER * 1 COMPQ  
INTEGER*8 N, LDT, LDQ, IFST, ILST, INFO  
DOUBLE PRECISION T(LDT,*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TREXC(COMPQ, N, T, [LDT], Q, [LDQ], IFST, ILST, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: COMPQ  
INTEGER :: N, LDT, LDQ, IFST, ILST, INFO  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:) :: T, Q
```

```
SUBROUTINE TREXC_64(COMPQ, N, T, [LDT], Q, [LDQ], IFST, ILST, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: COMPQ  
INTEGER(8) :: N, LDT, LDQ, IFST, ILST, INFO  
REAL(8), DIMENSION(:) :: WORK  
REAL(8), DIMENSION(:,:) :: T, Q
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrexc(char compq, int n, double *t, int ldt, double
```

```

        *q, int ldq, int *ifst, int *ilst, int *info);

void dtrexc_64(char compq, long n, double *t, long ldt, double
        *q, long ldq, long *ifst, long *ilst, long
        *info);

```

PURPOSE

dtrexc reorders the real Schur factorization of a real matrix $A = Q^*TQ^{**T}$, so that the diagonal block of T with row index $IFST$ is moved to row $ILST$.

The real Schur form T is reordered by an orthogonal similarity transformation $Z^{**T}T^*Z$, and optionally the matrix Q of Schur vectors is updated by postmultiplying it with Z .

T must be in Schur canonical form (as returned by `SHSEQR`), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign.

ARGUMENTS

COMPQ (input)

= 'V': update the matrix Q of Schur vectors;
 = 'N': do not update Q .

N (input) The order of the matrix T . $N \geq 0$.

T (input/output)

On entry, the upper quasi-triangular matrix T , in Schur canonical form. On exit, the reordered upper quasi-triangular matrix, again in Schur canonical form.

LDT (input)

The leading dimension of the array T . $LDT \geq \max(1, N)$.

Q (input) On entry, if $COMPQ = 'V'$, the matrix Q of Schur vectors. On exit, if $COMPQ = 'V'$, Q has been postmultiplied by the orthogonal transformation matrix Z which reorders T . If $COMPQ = 'N'$, Q is not referenced.

LDQ (input)

The leading dimension of the array Q . $LDQ \geq \max(1, N)$.

IFST (input/output)

Specify the reordering of the diagonal blocks of T . The block with row index $IFST$ is moved to row $ILST$, by a sequence of transpositions between adjacent blocks. On exit, if $IFST$ pointed on entry to the second row of a 2-by-2 block, it is

changed to point to the first row; ILST always points to the first row of the block in its final position (which may differ from its input value by +1 or -1). $1 \leq \text{IFST} \leq N$; $1 \leq \text{ILST} \leq N$.

ILST (input/output)

See the description of IFST.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

= 1: two adjacent blocks were too close to swap (the problem is very ill-conditioned); T may have been partially reordered, and ILST points to the first row of the current position of the block being moved.

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NAME

dtrmm - perform one of the matrix-matrix operations $B := \alpha * \text{op}(A) * B$, or $B := \alpha * B * \text{op}(A)$

SYNOPSIS

```
SUBROUTINE DTRMM(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
INTEGER M, N, LDA, LDB
DOUBLE PRECISION ALPHA
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DTRMM_64(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                   LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
INTEGER*8 M, N, LDA, LDB
DOUBLE PRECISION ALPHA
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TRMM(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A, [LDA],
                B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
INTEGER :: M, N, LDA, LDB
REAL(8) :: ALPHA
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE TRMM_64(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A,
                  [LDA], B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
INTEGER(8) :: M, N, LDA, LDB
REAL(8) :: ALPHA
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrmm(char side, char uplo, char transa, char diag, int
           m, int n, double alpha, double *a, int lda, double
           *b, int ldb);
```

```
void dtrmm_64(char side, char uplo, char transa, char diag,
              long m, long n, double alpha, double *a, long lda,
              double *b, long ldb);
```

PURPOSE

dtrmm performs one of the matrix-matrix operations $B := \alpha * \text{op}(A) * B$, or $B := \alpha * B * \text{op}(A)$ where α is a scalar, B is an m by n matrix, A is a unit, or non-unit, upper or lower triangular matrix and $\text{op}(A)$ is one of

$\text{op}(A) = A$ or $\text{op}(A) = A'$.

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether $\text{op}(A)$ multiplies B from the left or right as follows:

SIDE = 'L' or 'l' $B := \alpha * \text{op}(A) * B$.

SIDE = 'R' or 'r' $B := \alpha * B * \text{op}(A)$.

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the matrix A is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n' $\text{op}(A) = A$.

TRANSA = 'T' or 't' $\text{op}(A) = A'$.

TRANSA = 'C' or 'c' $\text{op}(A) = A'$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of B. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of B. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. When alpha is zero then A is not referenced and B need not be set before entry. Unchanged on exit.

A (input)

DOUBLE PRECISION array of DIMENSION (LDA, k), where k is m when SIDE = 'L' or 'l' and is n when SIDE = 'R' or 'r'.

Before entry with UPLO = 'U' or 'u', the leading k by k upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced.

Before entry with UPLO = 'L' or 'l', the leading k by k lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced.

Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be one. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then $LDA \geq \max(1, m)$, when SIDE = 'R' or 'r' then $LDA \geq \max(1, n)$. Unchanged on exit.

B (input/output)

DOUBLE PRECISION array of DIMENSION (LDB, n). Before entry, the leading m by n part of the array B must contain the matrix B, and on exit is overwritten by the transformed matrix.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program.

LDB \geq max(1, m). Unchanged on exit.

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NAME

dtrmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

SYNOPSIS

```
SUBROUTINE DTRMV(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, LDA, INCY  
DOUBLE PRECISION A(LDA,*), Y(*)
```

```
SUBROUTINE DTRMV_64(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, LDA, INCY  
DOUBLE PRECISION A(LDA,*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TRMV(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, LDA, INCY  
REAL(8), DIMENSION(:) :: Y  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TRMV_64(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, LDA, INCY  
REAL(8), DIMENSION(:) :: Y  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrmv(char uplo, char transa, char diag, int n, double  
          *a, int lda, double *y, int incy);
```

```
void dtrmv_64(char uplo, char transa, char diag, long n,  
             double *a, long lda, double *y, long incy);
```

PURPOSE

dtrmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := A'*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not

referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

Y (input/output)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

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NAME

dtrrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix

SYNOPSIS

```
SUBROUTINE DTRRFS(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, NRHS, LDA, LDB, LDX, INFO  
INTEGER WORK2(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE DTRRFS_64(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, NRHS, LDA, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
DOUBLE PRECISION A(LDA,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TRRFS(UPLO, [TRANSA], DIAG, N, NRHS, A, [LDA], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, NRHS, LDA, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK  
REAL(8), DIMENSION(:,:) :: A, B, X
```

```
SUBROUTINE TRRFS_64(UPLO, [TRANSA], DIAG, N, NRHS, A, [LDA], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, NRHS, LDA, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2
```

```
REAL(8), DIMENSION(:) :: FERR, BERR, WORK
REAL(8), DIMENSION(:, :) :: A, B, X
```

C INTERFACE

```
#include <sunperf.h>
void dtrrfs(char uplo, char transa, char diag, int n, int
            nrhs, double *a, int lda, double *b, int ldb, dou-
            ble *x, int ldx, double *ferr, double *berr, int
            *info);

void dtrrfs_64(char uplo, char transa, char diag, long n,
               long nrhs, double *a, long lda, double *b, long
               ldb, double *x, long ldx, double *ferr, double
               *berr, long *info);
```

PURPOSE

dtrrfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix.

The solution matrix X must be computed by DTRTRS or some other means before entering this routine. DTRRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{*H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower

triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input) The solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

dtrsens - reorder the real Schur factorization of a real matrix $A = Q^*T^*Q^{**}T$, so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix T,

SYNOPSIS

```
SUBROUTINE DTRSEN(JOB, COMPQ, SELECT, N, T, LDT, Q, LDQ, WR, WI, M,
  S, SEP, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ
INTEGER N, LDT, LDQ, M, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL SELECT(*)
DOUBLE PRECISION S, SEP
DOUBLE PRECISION T(LDT,*), Q(LDQ,*), WR(*), WI(*), WORK(*)
```

```
SUBROUTINE DTRSEN_64(JOB, COMPQ, SELECT, N, T, LDT, Q, LDQ, WR, WI,
  M, S, SEP, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ
INTEGER*8 N, LDT, LDQ, M, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
LOGICAL*8 SELECT(*)
DOUBLE PRECISION S, SEP
DOUBLE PRECISION T(LDT,*), Q(LDQ,*), WR(*), WI(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TRSEN(JOB, COMPQ, SELECT, N, T, [LDT], Q, [LDQ], WR, WI,
  M, S, SEP, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ
INTEGER :: N, LDT, LDQ, M, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL, DIMENSION(:) :: SELECT
REAL(8) :: S, SEP
REAL(8), DIMENSION(:) :: WR, WI, WORK
REAL(8), DIMENSION(:, :) :: T, Q
```

```
SUBROUTINE TRSEN_64(JOB, COMPQ, SELECT, N, T, [LDT], Q, [LDQ], WR,
    WI, M, S, SEP, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ
INTEGER(8) :: N, LDT, LDQ, M, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8) :: S, SEP
REAL(8), DIMENSION(:) :: WR, WI, WORK
REAL(8), DIMENSION(:, :) :: T, Q
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrsen(char job, char compq, int *select, int n, double
    *t, int ldt, double *q, int ldq, double *wr, dou-
    ble *wi, int *m, double *s, double *sep, int
    *info);
```

```
void dtrsen_64(char job, char compq, long *select, long n,
    double *t, long ldt, double *q, long ldq, double
    *wr, double *wi, long *m, double *s, double *sep,
    long *info);
```

PURPOSE

dtrsen reorders the real Schur factorization of a real matrix $A = Q^*T^*Q^{**T}$, so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix T , and the leading columns of Q form an orthonormal basis of the corresponding right invariant subspace.

Optionally the routine computes the reciprocal condition numbers of the cluster of eigenvalues and/or the invariant subspace.

T must be in Schur canonical form (as returned by SHSEQR), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign.

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for the cluster of eigenvalues (S) or the invariant subspace (SEP):

- = 'N': none;
- = 'E': for eigenvalues only (S);
- = 'V': for invariant subspace only (SEP);
- = 'B': for both eigenvalues and invariant subspace (S and SEP).

COMPQ (input)

= 'V': update the matrix Q of Schur vectors;
= 'N': do not update Q.

SELECT (input)

SELECT specifies the eigenvalues in the selected cluster. To select a real eigenvalue $w(j)$, SELECT(j) must be set to $w(j)$ and $w(j+1)$, corresponding to a 2-by-2 diagonal block, either SELECT(j) or SELECT(j+1) or both must be set to either both included in the cluster or both excluded.

N (input) The order of the matrix T. $N \geq 0$.

T (input/output)

On entry, the upper quasi-triangular matrix T, in Schur canonical form. On exit, T is overwritten by the reordered matrix T, again in Schur canonical form, with the selected eigenvalues in the leading diagonal blocks.

LDT (input)

The leading dimension of the array T. $LDT \geq \max(1, N)$.

Q (input) On entry, if COMPQ = 'V', the matrix Q of Schur vectors. On exit, if COMPQ = 'V', Q has been postmultiplied by the orthogonal transformation matrix which reorders T; the leading M columns of Q form an orthonormal basis for the specified invariant subspace. If COMPQ = 'N', Q is not referenced.

LDQ (input)

The leading dimension of the array Q. $LDQ \geq 1$; and if COMPQ = 'V', $LDQ \geq N$.

WR (output)

The real and imaginary parts, respectively, of the reordered eigenvalues of T. The eigenvalues are stored in the same order as on the diagonal of T, with $WR(i) = T(i, i)$ and, if $T(i:i+1, i:i+1)$ is a 2-by-2 diagonal block, $WI(i) > 0$ and $WI(i+1) = -WI(i)$. Note that if a complex eigenvalue is sufficiently ill-conditioned, then its value may differ significantly from its value before reordering.

WI (output)

See the description of WR.

M (output)

The dimension of the specified invariant subspace. $0 < M \leq N$.

S (output)

If JOB = 'E' or 'B', S is a lower bound on the reciprocal condition number for the selected cluster of eigenvalues. S cannot underestimate the true reciprocal condition number by more than a factor of \sqrt{N} . If $M = 0$ or N , $S = 1$. If JOB =

'N' or 'V', S is not referenced.

SEP (output)

If JOB = 'V' or 'B', SEP is the estimated reciprocal condition number of the specified invariant subspace. If M = 0 or N, SEP = norm(T). If JOB = 'N' or 'E', SEP is not referenced.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If JOB = 'N', LWORK >= max(1,N); if JOB = 'E', LWORK >= M*(N-M); if JOB = 'V' or 'B', LWORK >= 2*M*(N-M).

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

If JOB = 'N' or 'E', IWORK is not referenced.

LIWORK (input)

The dimension of the array IWORK. If JOB = 'N' or 'E', LIWORK >= 1; if JOB = 'V' or 'B', LIWORK >= M*(N-M).

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
= 1: reordering of T failed because some eigenvalues are too close to separate (the problem is very ill-conditioned); T may have been partially reordered, and WR and WI contain the eigenvalues in the same order as in T; S and SEP (if requested) are set to zero.

FURTHER DETAILS

DTRSEN first collects the selected eigenvalues by computing an orthogonal transformation Z to move them to the top left corner of T. In other words, the selected eigenvalues are the eigenvalues of T11 in:

$$Z'^*T*Z = \begin{pmatrix} T11 & T12 \\ 0 & T22 \end{pmatrix} \begin{matrix} n1 \\ n2 \\ n1 & n2 \end{matrix}$$

where N = n1+n2 and Z' means the transpose of Z. The first

n_1 columns of Z span the specified invariant subspace of T .

If T has been obtained from the real Schur factorization of a matrix $A = Q^*T^*Q'$, then the reordered real Schur factorization of A is given by $A = (Q^*Z)^*(Z'^*T^*Z)^*(Q^*Z)'$, and the first n_1 columns of Q^*Z span the corresponding invariant subspace of A .

The reciprocal condition number of the average of the eigenvalues of T_{11} may be returned in S . S lies between 0 (very badly conditioned) and 1 (very well conditioned). It is computed as follows. First we compute R so that

$$P = \begin{pmatrix} I & R \\ 0 & 0 \end{pmatrix} \begin{matrix} n_1 \\ n_2 \\ n_1 \ n_2 \end{matrix}$$

is the projector on the invariant subspace associated with T_{11} . R is the solution of the Sylvester equation:

$$T_{11}^*R - R^*T_{22} = T_{12}.$$

Let F -norm(M) denote the Frobenius-norm of M and 2 -norm(M) denote the two-norm of M . Then S is computed as the lower bound

$$(1 + F\text{-norm}(R)^2)^{-1/2}$$

on the reciprocal of 2 -norm(P), the true reciprocal condition number. S cannot underestimate $1 / 2$ -norm(P) by more than a factor of \sqrt{N} .

An approximate error bound for the computed average of the eigenvalues of T_{11} is

$$EPS * \text{norm}(T) / S$$

where EPS is the machine precision.

The reciprocal condition number of the right invariant subspace spanned by the first n_1 columns of Z (or of Q^*Z) is returned in SEP . SEP is defined as the separation of T_{11} and T_{22} :

$$\text{sep}(T_{11}, T_{22}) = \sigma\text{-min}(C)$$

where $\sigma\text{-min}(C)$ is the smallest singular value of the $n_1 \times n_2$ -by- $n_1 \times n_2$ matrix

$$C = \text{kprod}(I(n_2), T_{11}) - \text{kprod}(\text{transpose}(T_{22}), I(n_1))$$

$I(m)$ is an m by m identity matrix, and kprod denotes the Kronecker product. We estimate $\sigma\text{-min}(C)$ by the reciprocal of an estimate of the 1-norm of $\text{inverse}(C)$. The true reciprocal 1-norm of $\text{inverse}(C)$ cannot differ from $\sigma\text{-min}(C)$ by more than a factor of $\sqrt{n_1 \times n_2}$.

When SEP is small, small changes in T can cause large changes in the invariant subspace. An approximate bound on the maximum angular error in the computed right invariant subspace is

EPS * norm(T) / SEP

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NAME

dtrsm - solve one of the matrix equations $op(A)X = \alpha B$, or $Xop(A) = \alpha B$

SYNOPSIS

```
SUBROUTINE DTRSM(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
INTEGER M, N, LDA, LDB
DOUBLE PRECISION ALPHA
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DTRSM_64(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                   LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
INTEGER*8 M, N, LDA, LDB
DOUBLE PRECISION ALPHA
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TRSM(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A, [LDA],
               B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
INTEGER :: M, N, LDA, LDB
REAL(8) :: ALPHA
REAL(8), DIMENSION(:, :) :: A, B
```

```
SUBROUTINE TRSM_64(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A,
                  [LDA], B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
INTEGER(8) :: M, N, LDA, LDB
REAL(8) :: ALPHA
REAL(8), DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrsm(char side, char uplo, char transa, char diag, int
           m, int n, double alpha, double *a, int lda, double
           *b, int ldb);
```

```
void dtrsm_64(char side, char uplo, char transa, char diag,
              long m, long n, double alpha, double *a, long lda,
              double *b, long ldb);
```

PURPOSE

dtrsm solves one of the matrix equations $op(A)X = \alpha B$, or $Xop(A) = \alpha B$ where α is a scalar, X and B are m by n matrices, A is a unit, or non-unit, upper or lower triangular matrix and $op(A)$ is one of

$op(A) = A$ or $op(A) = A'$.

The matrix X is overwritten on B .

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether $op(A)$ appears on the left or right of X as follows:

SIDE = 'L' or 'l' $op(A)X = \alpha B$.

SIDE = 'R' or 'r' $Xop(A) = \alpha B$.

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the matrix A is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the form of $op(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n' $op(A) = A$.

TRANSA = 'T' or 't' $op(A) = A'$.

TRANSA = 'C' or 'c' $op(A) = A'$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)
On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

M (input)
On entry, M specifies the number of rows of B. M \geq 0. Unchanged on exit.

N (input)
On entry, N specifies the number of columns of B. N \geq 0. Unchanged on exit.

ALPHA (input)
On entry, ALPHA specifies the scalar alpha. When alpha is zero then A is not referenced and B need not be set before entry. Unchanged on exit.

A (input)
DOUBLE PRECISION array of DIMENSION (LDA, k), where k is m when SIDE = 'L' or 'l' and is n when SIDE = 'R' or 'r'.
Before entry with UPLO = 'U' or 'u', the leading k by k upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced.
Before entry with UPLO = 'L' or 'l', the leading k by k lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced.
Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be one. Unchanged on exit.

LDA (input)
On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then LDA \geq max(1, m), when SIDE = 'R' or 'r' then LDA \geq max(1, n). Unchanged on exit.

B (input/output)
DOUBLE PRECISION array of DIMENSION (LDB, n).
Before entry, the leading m by n part of the array B must contain the right-hand side matrix B, and on exit is overwritten by the solution matrix X.

LDB (input)
On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. LDB

$\geq \max(1, m)$. Unchanged on exit.

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NAME

dtrsna - estimate reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix T (or of any matrix Q^*TQ^{**T} with Q orthogonal)

SYNOPSIS

```
SUBROUTINE DTRSNA(JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR, LDVR,  
  S, SEP, MM, M, WORK, LDWORK, WORK1, INFO)
```

```
CHARACTER * 1 JOB, HOWMNY  
INTEGER N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
INTEGER WORK1(*)  
LOGICAL SELECT(*)  
DOUBLE PRECISION T(LDT,*), VL(LDVL,*), VR(LDVR,*), S(*),  
SEP(*), WORK(LDWORK,*)
```

```
SUBROUTINE DTRSNA_64(JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,  
  LDVR, S, SEP, MM, M, WORK, LDWORK, WORK1, INFO)
```

```
CHARACTER * 1 JOB, HOWMNY  
INTEGER*8 N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
INTEGER*8 WORK1(*)  
LOGICAL*8 SELECT(*)  
DOUBLE PRECISION T(LDT,*), VL(LDVL,*), VR(LDVR,*), S(*),  
SEP(*), WORK(LDWORK,*)
```

F95 INTERFACE

```
SUBROUTINE TRSNA(JOB, HOWMNY, SELECT, N, T, [LDT], VL, [LDVL], VR,  
  [LDVR], S, SEP, MM, M, [WORK], [LDWORK], [WORK1], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNY  
INTEGER :: N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
INTEGER, DIMENSION(:) :: WORK1  
LOGICAL, DIMENSION(:) :: SELECT  
REAL(8), DIMENSION(:) :: S, SEP  
REAL(8), DIMENSION(:, :) :: T, VL, VR, WORK
```

```

SUBROUTINE TRSNA_64(JOB, HOWMNY, SELECT, N, T, [LDT], VL, [LDVL], VR,
  [LDVR], S, SEP, MM, M, [WORK], [LDWORK], [WORK1], [INFO])

```

```

CHARACTER(LEN=1) :: JOB, HOWMNY
INTEGER(8) :: N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: WORK1
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: S, SEP
REAL(8), DIMENSION(:, :) :: T, VL, VR, WORK

```

C INTERFACE

```

#include <sunperf.h>

```

```

void dtrsna(char job, char howmny, int *select, int n, dou-
  ble *t, int ldt, double *vl, int ldvl, double *vr,
  int ldvr, double *s, double *sep, int mm, int *m,
  int ldwork, int *info);

```

```

void dtrsna_64(char job, char howmny, long *select, long n,
  double *t, long ldt, double *vl, long ldvl, double
  *vr, long ldvr, double *s, double *sep, long mm,
  long *m, long ldwork, long *info);

```

PURPOSE

dtrsna estimates reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix T (or of any matrix $Q^*T^*Q^{**}T$ with Q orthogonal).

T must be in Schur canonical form (as returned by DHSEQR), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign.

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for eigenvalues (S) or eigenvectors (SEP):
 = 'E': for eigenvalues only (S);
 = 'V': for eigenvectors only (SEP);
 = 'B': for both eigenvalues and eigenvectors (S and SEP).

HOWMNY (input)

= 'A': compute condition numbers for all eigenpairs;
 = 'S': compute condition numbers for selected eigenpairs specified by the array SELECT.

SELECT (input)

If HOWMNY = 'S', SELECT specifies the eigenpairs for which condition numbers are required. To select condition numbers for the eigenpair corresponding to a real eigenvalue $w(j)$, SELECT(j)

must be set to `.TRUE.` To select condition numbers corresponding to a complex conjugate pair of eigenvalues $w(j)$ and $w(j+1)$, either `SELECT(j)` or `SELECT(j+1)` or both, must be set to `.TRUE.` If `HOWMNY = 'A'`, `SELECT` is not referenced.

`N` (input) The order of the matrix `T`. $N \geq 0$.

`T` (input) The upper quasi-triangular matrix `T`, in Schur canonical form.

`LDT` (input)
The leading dimension of the array `T`. $LDT \geq \max(1, N)$.

`VL` (input)
If `JOB = 'E'` or `'B'`, `VL` must contain left eigenvectors of `T` (or of any Q^*TQ with `Q` orthogonal), corresponding to the eigenpairs specified by `HOWMNY` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VL`, as returned by `DHSEIN` or `DTREVC`. If `JOB = 'V'`, `VL` is not referenced.

`LDVL` (input)
The leading dimension of the array `VL`. $LDVL \geq 1$; and if `JOB = 'E'` or `'B'`, $LDVL \geq N$.

`VR` (input)
If `JOB = 'E'` or `'B'`, `VR` must contain right eigenvectors of `T` (or of any Q^*TQ with `Q` orthogonal), corresponding to the eigenpairs specified by `HOWMNY` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VR`, as returned by `DHSEIN` or `DTREVC`. If `JOB = 'V'`, `VR` is not referenced.

`LDVR` (input)
The leading dimension of the array `VR`. $LDVR \geq 1$; and if `JOB = 'E'` or `'B'`, $LDVR \geq N$.

`S` (output)
If `JOB = 'E'` or `'B'`, the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. For a complex conjugate pair of eigenvalues two consecutive elements of `S` are set to the same value. Thus `S(j)`, `SEP(j)`, and the j -th columns of `VL` and `VR` all correspond to the same eigenpair (but not in general the j -th eigenpair, unless all eigenpairs are selected). If `JOB = 'V'`, `S` is not referenced.

`SEP` (output)
If `JOB = 'V'` or `'B'`, the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. For a complex eigenvector two consecutive elements of `SEP` are set to the same value. If the eigenvalues cannot be reordered to compute `SEP(j)`, `SEP(j)` is set to 0; this can only occur when the true value would be very small anyway. If `JOB = 'E'`, `SEP` is

not referenced.

MM (input)

The number of elements in the arrays S (if JOB = 'E' or 'B') and/or SEP (if JOB = 'V' or 'B'). MM \geq M.

M (output)

The number of elements of the arrays S and/or SEP actually used to store the estimated condition numbers. If HOWMNY = 'A', M is set to N.

WORK (workspace)

dimension(LDWORK,N+1) If JOB = 'E', WORK is not referenced.

LDWORK (input)

The leading dimension of the array WORK. LDWORK \geq 1; and if JOB = 'V' or 'B', LDWORK \geq N.

WORK1 (workspace)

dimension(N) If JOB = 'E', WORK1 is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The reciprocal of the condition number of an eigenvalue lambda is defined as

$$S(\lambda) = |v' * u| / (\text{norm}(u) * \text{norm}(v))$$

where u and v are the right and left eigenvectors of T corresponding to lambda; v' denotes the conjugate-transpose of v, and norm(u) denotes the Euclidean norm. These reciprocal condition numbers always lie between zero (very badly conditioned) and one (very well conditioned). If n = 1, S(lambda) is defined to be 1.

An approximate error bound for a computed eigenvalue W(i) is given by

$$\text{EPS} * \text{norm}(T) / S(i)$$

where EPS is the machine precision.

The reciprocal of the condition number of the right eigenvector u corresponding to lambda is defined as follows. Suppose

$$T = \begin{pmatrix} \lambda & c \\ 0 & T_{22} \end{pmatrix}$$

Then the reciprocal condition number is

$$\text{SEP}(\lambda, T22) = \sigma\text{-min}(T22 - \lambda I)$$

where $\sigma\text{-min}$ denotes the smallest singular value. We approximate the smallest singular value by the reciprocal of an estimate of the one-norm of the inverse of $T22 - \lambda I$. If $n = 1$, $\text{SEP}(1)$ is defined to be $\text{abs}(T(1,1))$.

An approximate error bound for a computed right eigenvector $\text{VR}(i)$ is given by

$$\text{EPS} * \text{norm}(T) / \text{SEP}(i)$$

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NAME

dtrsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

SYNOPSIS

```
SUBROUTINE DTRSV(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, LDA, INCY  
DOUBLE PRECISION A(LDA,*), Y(*)
```

```
SUBROUTINE DTRSV_64(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, LDA, INCY  
DOUBLE PRECISION A(LDA,*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TRSV(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, LDA, INCY  
REAL(8), DIMENSION(:) :: Y  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TRSV_64(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, LDA, INCY  
REAL(8), DIMENSION(:) :: Y  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrsv(char uplo, char transa, char diag, int n, double  
          *a, int lda, double *y, int incy);
```

```
void dtrsv_64(char uplo, char transa, char diag, long n,  
             double *a, long lda, double *y, long incy);
```

PURPOSE

dtrsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular matrix. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the equations to be solved as follows:

TRANSA = 'N' or 'n' $A*x = b$.

TRANSA = 'T' or 't' $A'*x = b$.

TRANSA = 'C' or 'c' $A'*x = b$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must

contain the upper triangular matrix and the strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

Y (input/output)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

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NAME

dtrsyl - solve the real Sylvester matrix equation

SYNOPSIS

```
SUBROUTINE DTRSYL(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C, LDC,
  SCALE, INFO)
```

```
CHARACTER * 1 TRANA, TRANB
INTEGER ISGN, M, N, LDA, LDB, LDC, INFO
DOUBLE PRECISION SCALE
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*)
```

```
SUBROUTINE DTRSYL_64(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C,
  LDC, SCALE, INFO)
```

```
CHARACTER * 1 TRANA, TRANB
INTEGER*8 ISGN, M, N, LDA, LDB, LDC, INFO
DOUBLE PRECISION SCALE
DOUBLE PRECISION A(LDA,*), B(LDB,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE TRSYL(TRANA, TRANB, ISGN, M, N, A, [LDA], B, [LDB], C,
  [LDC], SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: TRANA, TRANB
INTEGER :: ISGN, M, N, LDA, LDB, LDC, INFO
REAL(8) :: SCALE
REAL(8), DIMENSION(:, :) :: A, B, C
```

```
SUBROUTINE TRSYL_64(TRANA, TRANB, ISGN, M, N, A, [LDA], B, [LDB], C,
  [LDC], SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: TRANA, TRANB
INTEGER(8) :: ISGN, M, N, LDA, LDB, LDC, INFO
REAL(8) :: SCALE
REAL(8), DIMENSION(:, :) :: A, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrsyl(char trana, char tranb, int isgn, int m, int n,
           double *a, int lda, double *b, int ldb, double *c,
           int ldc, double *scale, int *info);
```

```
void dtrsyl_64(char trana, char tranb, long isgn, long m,
              long n, double *a, long lda, double *b, long ldb,
              double *c, long ldc, double *scale, long *info);
```

PURPOSE

dtrsyl solves the real Sylvester matrix equation:

```
op(A)*X + X*op(B) = scale*C or
op(A)*X - X*op(B) = scale*C,
```

where $op(A) = A$ or A^{**T} , and A and B are both upper quasi-triangular. A is M -by- M and B is N -by- N ; the right hand side C and the solution X are M -by- N ; and $scale$ is an output scale factor, set ≤ 1 to avoid overflow in X .

A and B must be in Schur canonical form (as returned by SHSEQR), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign.

ARGUMENTS

TRANA (input)

```
Specifies the option op(A):
= 'N': op(A) = A      (No transpose)
= 'T': op(A) = A**T  (Transpose)
= 'C': op(A) = A**H  (Conjugate transpose = Tran-
spose)
```

TRANB (input)

```
Specifies the option op(B):
= 'N': op(B) = B      (No transpose)
= 'T': op(B) = B**T  (Transpose)
= 'C': op(B) = B**H  (Conjugate transpose = Tran-
spose)
```

ISGN (input)

```
Specifies the sign in the equation:
= +1: solve op(A)*X + X*op(B) = scale*C
= -1: solve op(A)*X - X*op(B) = scale*C
```

M (input) The order of the matrix A , and the number of rows in the matrices X and C . $M \geq 0$.

N (input) The order of the matrix B , and the number of columns in the matrices X and C . $N \geq 0$.

A (input) The upper quasi-triangular matrix A , in Schur canonical form.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,M).

B (input) The upper quasi-triangular matrix B, in Schur canonical form.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

C (input/output)
On entry, the M-by-N right hand side matrix C. On exit, C is overwritten by the solution matrix X.

LDC (input)
The leading dimension of the array C. LDC \geq max(1,M)

SCALE (output)
The scale factor, scale, set ≤ 1 to avoid overflow in X.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
= 1: A and B have common or very close eigenvalues; perturbed values were used to solve the equation (but the matrices A and B are unchanged).

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NAME

dtrti2 - compute the inverse of a real upper or lower triangular matrix

SYNOPSIS

```
SUBROUTINE DTRTI2(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

```
SUBROUTINE DTRTI2_64(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE TRTI2(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TRTI2_64(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER(8) :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrti2(char uplo, char diag, int n, double *a, int lda,  
            int *info);
```

```
void dtrti2_64(char uplo, char diag, long n, double *a, long  
               lda, long *info);
```

PURPOSE

dtrti2 computes the inverse of a real upper or lower triangular matrix.

This is the Level 2 BLAS version of the algorithm.

ARGUMENTS

UPLO (input)

Specifies whether the matrix A is upper or lower triangular. = 'U': Upper triangular
= 'L': Lower triangular

DIAG (input)

Specifies whether or not the matrix A is unit triangular. = 'N': Non-unit triangular
= 'U': Unit triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular matrix A. If UPLO = 'U', the leading n by n upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n by n lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

On exit, the (triangular) inverse of the original matrix, in the same storage format.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value

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NAME

dtrtri - compute the inverse of a real upper or lower triangular matrix A

SYNOPSIS

```
SUBROUTINE DTRTRI(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

```
SUBROUTINE DTRTRI_64(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE TRTRI(UPLO, DIAG, N, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TRTRI_64(UPLO, DIAG, N, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER(8) :: N, LDA, INFO  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrtri(char uplo, char diag, int n, double *a, int lda,  
            int *info);
```

```
void dtrtri_64(char uplo, char diag, long n, double *a, long  
               lda, long *info);
```

PURPOSE

dtrtri computes the inverse of a real upper or lower triangular matrix A.

This is the Level 3 BLAS version of the algorithm.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1. On exit, the (triangular) inverse of the original matrix, in the same storage format.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, A(i,i) is exactly zero. The triangular matrix is singular and its inverse can not be computed.

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NAME

dtrtrs - solve a triangular system of the form $A * X = B$
or $A^{**T} * X = B$,

SYNOPSIS

```
SUBROUTINE DTRTRS(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

```
SUBROUTINE DTRTRS_64(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB,  
INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
DOUBLE PRECISION A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TRTRS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:,:) :: A, B
```

```
SUBROUTINE TRTRS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
REAL(8), DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtrtrs(char uplo, char transa, char diag, int n, int  
nrhs, double *a, int lda, double *b, int ldb, int  
*info);
```

```
void dtrtrs_64(char uplo, char transa, char diag, long n,
               long nrhs, double *a, long lda, double *b, long
               ldb, long *info);
```

PURPOSE

dtrtrs solves a triangular system of the form
 $A * X = B$ or $A^{**T} * X = B$

where A is a triangular matrix of order N, and B is an N-by-NRHS matrix. A check is made to verify that A is non-singular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:

= 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the right hand side matrix B. On exit, if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

> 0: if INFO = i, the i-th diagonal element of A
is zero, indicating that the matrix is singular
and the solutions X have not been computed.

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NAME

dtzrqf - routine is deprecated and has been replaced by routine STZRZF

SYNOPSIS

```
SUBROUTINE DTZRQF(M, N, A, LDA, TAU, INFO)
```

```
INTEGER M, N, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*)
```

```
SUBROUTINE DTZRQF_64(M, N, A, LDA, TAU, INFO)
```

```
INTEGER*8 M, N, LDA, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*)
```

F95 INTERFACE

```
SUBROUTINE TZRQF(M, N, A, [LDA], TAU, [INFO])
```

```
INTEGER :: M, N, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TZRQF_64(M, N, A, [LDA], TAU, [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO  
REAL(8), DIMENSION(:) :: TAU  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtzrqf(int m, int n, double *a, int lda, double *tau,  
            int *info);
```

```
void dtzrqf_64(long m, long n, double *a, long lda, double  
              *tau, long *info);
```

PURPOSE

dtzrqf routine is deprecated and has been replaced by routine STZRZF.

STZRQF reduces the M-by-N ($M \leq N$) real upper trapezoidal matrix A to upper triangular form by means of orthogonal transformations.

The upper trapezoidal matrix A is factored as

$$A = \begin{pmatrix} R & 0 \end{pmatrix} * Z,$$

where Z is an N-by-N orthogonal matrix and R is an M-by-M upper triangular matrix.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq M$.

A (input/output)

On entry, the leading M-by-N upper trapezoidal part of the array A must contain the matrix to be factorized. On exit, the leading M-by-M upper triangular part of A contains the upper triangular matrix R, and elements M+1 to N of the first M rows of A, with the array TAU, represent the orthogonal matrix Z as a product of M elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The factorization is obtained by Householder's method. The kth transformation matrix, $Z(k)$, which is used to introduce zeros into the $(m - k + 1)$ th row of A, is given in the form

$$Z(k) = \begin{pmatrix} I & 0 \\ 0 & T(k) \end{pmatrix},$$

where

$$T(k) = I - \tau * u(k) * u(k)', \quad u(k) = \begin{pmatrix} 1 \\ \end{pmatrix},$$

$$\begin{pmatrix} 0 \\ z(k) \end{pmatrix}$$

tau is a scalar and $z(k)$ is an $(n - m)$ element vector. tau and $z(k)$ are chosen to annihilate the elements of the kth row of X.

The scalar tau is returned in the kth element of TAU and the vector $u(k)$ in the kth row of A, such that the elements of $z(k)$ are in $a(k, m + 1), \dots, a(k, n)$. The elements of R are returned in the upper triangular part of A.

Z is given by

$$Z = Z(1) * Z(2) * \dots * Z(m).$$

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NAME

dtzrzf - reduce the M-by-N ($M \leq N$) real upper trapezoidal matrix A to upper triangular form by means of orthogonal transformations

SYNOPSIS

```
SUBROUTINE DTZRZF(M, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
INTEGER M, N, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE DTZRZF_64(M, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LWORK, INFO  
DOUBLE PRECISION A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TZRZF([M], [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

```
SUBROUTINE TZRZF_64([M], [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: TAU, WORK  
REAL(8), DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dtzrzf(int m, int n, double *a, int lda, double *tau,  
            int *info);
```

```
void dtzrzf_64(long m, long n, double *a, long lda, double  
               *tau, long *info);
```

PURPOSE

dtzrzf reduces the M-by-N ($M \leq N$) real upper trapezoidal matrix A to upper triangular form by means of orthogonal transformations.

The upper trapezoidal matrix A is factored as

$$A = (R \ 0) * Z,$$

where Z is an N-by-N orthogonal matrix and R is an M-by-M upper triangular matrix.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the leading M-by-N upper trapezoidal part of the array A must contain the matrix to be factorized. On exit, the leading M-by-M upper triangular part of A contains the upper triangular matrix R, and elements M+1 to N of the first M rows of A, with the array TAU, represent the orthogonal matrix Z as a product of M elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1, M)$. For optimum performance $LWORK \geq M * NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by

A. Petitot, Computer Science Dept., Univ. of Tenn., Knoxville, USA

The factorization is obtained by Householder's method. The kth transformation matrix, $Z(k)$, which is used to introduce zeros into the $(m - k + 1)$ th row of A, is given in the form

$$Z(k) = \begin{pmatrix} I & 0 \\ 0 & T(k) \end{pmatrix},$$

where

$$T(k) = I - \tau u(k) u(k)', \quad u(k) = \begin{pmatrix} 1 \\ 0 \\ z(k) \end{pmatrix},$$

τ is a scalar and $z(k)$ is an $(n - m)$ element vector. τ and $z(k)$ are chosen to annihilate the elements of the kth row of X.

The scalar τ is returned in the kth element of TAU and the vector $u(k)$ in the kth row of A, such that the elements of $z(k)$ are in $a(k, m + 1), \dots, a(k, n)$. The elements of R are returned in the upper triangular part of A.

Z is given by

$$Z = Z(1) * Z(2) * \dots * Z(m).$$

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NAME

dvbrmm - variable block sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE DVBRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,
*                VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LDB, LDC, LWORK
INTEGER          INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(KB+1),
*                BPNTRB(MB), BPNTRE(MB)
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE DVBRMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,
*                   VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,
*                   B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LDB, LDC, LWORK
INTEGER*8        INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(KB+1),
*               BPNTRB(MB), BPNTRE(MB)
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE VBRMM(TRANSA, MB, [N], KB, ALPHA, DESCRA,
*              VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,
*              B, [LDB], BETA, C,[LDC], [WORK], [LWORK])
INTEGER       TRANSA, MB, KB
INTEGER, DIMENSION(:) :: DESCRA, INDX, BINDX
INTEGER, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE
REAL*8       ALPHA, BETA
REAL*8, DIMENSION(:) :: VAL
REAL*8, DIMENSION(:, :) :: B, C

SUBROUTINE VBRMM_64(TRANSA, MB, [N], KB, ALPHA, DESCRA,
*                  VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,
*                  B, [LDB], BETA, C,[LDC], [WORK], [LWORK])
INTEGER*8     TRANSA, MB, KB
```


DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, scalar array VAL of length NNZ consists of the block entries of A where each block entry is a dense rectangular matrix stored column by column where NNZ denotes the total number of point entries in all nonzero block entries of a matrix A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length BNNZ+1 where BNNZ is the number of block entries of the matrix A such that the I-th element of INDX[] points to the location in VAL of the (1,1) element of the I-th block entry. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ is the number block entries of the matrix A. Unchanged on exit.

RPNTR(input) On entry, RPNTR is an integer array of length MB+1 such that RPNTR(I)-RPNTR(1)+1 is the row index of the first point row in the I-th block row. RPNTR(MB+1) is set to M+RPNTR(1) where M is the number of rows in the matrix A. Thus, the number of point rows in the I-th block row is RPNTR(I+1)-RPNTR(I). Unchanged on exit.

CPNTR(input) On entry, CPNTR is an integer array of length KB+1 such that CPNTR(J)-CPNTR(1)+1 is the column index of the first point column in the J-th block column. CPNTR(KB+1) is set to K+CPNTR(1) where K is the number of columns in the matrix A. Thus, the number of point columns in the J-th block column is CPNTR(J+1)-CPNTR(J). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(I)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the I-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(I)-BPNTRB(1) points to location in BINDX of the last block entry of the I-th block row of A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise
 the leading k by n part of the array C must contain the
 matrix C. On exit, the array C is overwritten by the matrix
 (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

NOTES/BUGS

1. For a general matrix (*DESCRA*(1)=0), array CPNTR can be different from RPNTR. For all other matrix types, RPNTR must equal CPNTR and a single array can be passed for both arguments.

2. It is known that there exists another representation of the variable block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of six array instead of the seven used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the array BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of variable block sparse row format the following calling sequence should be used

```
      SUBROUTINE SVBRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                       VAL, INDX, BINDX, RPNTR, CPNTR, IA, IA(2),  
*                       B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

dvbrsm - variable block sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE DVBRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LDB, LDC, LWORK  
INTEGER          INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(MB+1),  
*                BPNTRB(MB), BPNTRE(MB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(*), VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE DVBRSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LDB, LDC, LWORK  
INTEGER*8        INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(MB+1),  
*               BPNTRB(MB), BPNTRE(MB)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION DV(*), VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE VBRSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA,  
*              VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*              B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, UNITD  
INTEGER, DIMENSION(:) :: DESCRA, INDX, BINDX  
INTEGER, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV  
DOUBLE PRECISION, DIMENSION(:, :) :: B, C  
  
SUBROUTINE VBRSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA,  
*                  VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                  B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, UNITD  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, BINDX
```

```

INTEGER*8, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE
DOUBLE PRECISION ALPHA, BETA
DOUBLE PRECISION, DIMENSION(:) :: VAL, DV
DOUBLE PRECISION, DIMENSION(:, :) :: B, C

```

C INTERFACE

```
#include <sunperf.h>
```

```

void dvbrsm (int transa, int mb, int n, int unitd, double
*dv, double alpha, int *descra, double *val, int *indx, int
*bindx, int *rpntr, int *cpntr, int *bpntrb, int *bpntre,
double *b, int ldb, double beta, double *c, int ldc);

```

```

void dvbrsm_64 (long transa, long mb, long n, long unitd,
double *dv, double alpha, long *descra, double *val, long
*indx, long *bindx, long *rpntr, long *cpntr, long *bpntrb,
long *bpntre, double *b, long ldb, double beta, double *c,
long ldc);

```

DESCRIPTION

dvbrsm performs one of the matrix-matrix operations

```

C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,

```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a block diagonal matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the variable block sparse row format and op(A) is one of

```

op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).

```

The number of rows in A is determined as follows

```
m=RPNTR(MB+1)-RPNTR(1).
```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, integer MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.
DV(input)	On entry, array DV contains the block entries of the block diagonal matrix D. The size of the J-th block is RPNTR(J+1)-RPNTR(J) and each block contains matrix

entries stored column-major. The total length of array DV is given by the formula:

$$\text{sum over } J \text{ from } 1 \text{ to } MB: \\ ((RPNTR(J+1)-RPNTR(J))*(RPNTR(J+1)-RPNTR(J)))$$

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:

DESCRA(1) matrix structure

- 0 : general
- 1 : symmetric (A=A')
- 2 : Hermitian (A= CONJG(A'))
- 3 : Triangular
- 4 : Skew(Anti)-Symmetric (A=-A')
- 5 : Diagonal
- 6 : Skew-Hermitian (A= -CONJG(A'))

Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator

- 1 : lower
- 2 : upper

DESCRA(3) main diagonal type

- 0 : non-identity blocks on the main diagonal
- 1 : identity diagonal blocks
- 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)

- 0 : C/C++ compatible
- 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)

- 0 : unknown
- 1 : no repeated indices

VAL(input) On entry, scalar array VAL of length NNZ consists of the block entries of A where each block entry is a dense rectangular matrix stored column by column where NNZ denotes the total number of point entries in all nonzero block entries of the matrix A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length BNNZ+1 where BNNZ is the number of block entries of the matrix A such that the I-th element of INDX[] points to the location in VAL of the (1,1) element of the I-th block entry. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ is the number block entries of the matrix A. Block column indices MUST be sorted in increasing order for each block row. Unchanged on exit.

RPNTR(input) On entry, RPNTR is an integer array of length MB+1 such that RPNTR(I)-RPNTR(1)+1 is the row index of the first point row in the I-th block row. RPNTR(MB+1) is set to M+RPNTR(1) where M is the number of rows in the matrix A.

Thus, the number of point rows in the I-th block row is RPNTR(I+1)-RPNTR(I). Unchanged on exit.

NOTE: For the current version CPNTR must equal RPNTR and a single array can be passed for both arguments

CPNTR(input) On entry, CPNTR is an integer array of length KB+1 such that

CPNTR(J)-CPNTR(1)+1 is the column index of the first point column in the J-th block column. CPNTR(KB+1) is set to K+CPNTR(1) where K is the number of columns in the matrix A. Thus, the number of point columns in the J-th block column is CPNTR(J+1)-CPNTR(J). Unchanged on exit.

NOTE: For the current version CPNTR must equal RPNTR and a single array can be passed for both arguments

- BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(I)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the I-th block row of A. Unchanged on exit.
- BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(I)-BPNTRB(1) points to location in BINDX of the last block entry of the I-th block row of A. Unchanged on exit.
- B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.
- LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.
- BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.
- C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta*C).
- LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.
- WORK(workspace) Scratch array of length LWORK. On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.
- LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least $M = \text{RPNTR}(\text{MB}+1) - \text{RPNTR}(1)$. For good performance, LWORK should generally be larger. For optimum performance on multiple processors, $LWORK \geq M * N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If `DESCRA(3)=0`, the lower or upper triangular part of each diagonal block is used by the routine depending on `DESCRA(2)`.
3. If `DESCRA(3)=1`, the diagonal blocks in the variable block row representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If `DESCRA(3)=2`, diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.
5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
-----------	-----------	-----------	--------

3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

6. It is known that there exists another representation of the variable block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of six array instead of the seven used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the array BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of variable block sparse row format the following calling sequence should be used

```

SUBROUTINE DVBRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, BINDX, RPNTR, CPNTR, IA, IA(2),
*                 B, LDB, BETA, C, LDC, WORK, LWORK )

```

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NAME

dwieners - perform Wiener deconvolution of two signals

SYNOPSIS

```
SUBROUTINE DWIENER(N_POINTS, ACOR, XCOR, FLTR, EROP, ISW, IERR)
```

```
INTEGER N_POINTS, ISW, IERR  
DOUBLE PRECISION ACOR(*), XCOR(*), FLTR(*), EROP(*)
```

```
SUBROUTINE DWIENER_64(N_POINTS, ACOR, XCOR, FLTR, EROP, ISW, IERR)
```

```
INTEGER*8 N_POINTS, ISW, IERR  
DOUBLE PRECISION ACOR(*), XCOR(*), FLTR(*), EROP(*)
```

F95 INTERFACE

```
SUBROUTINE WIENER(N_POINTS, ACOR, XCOR, FLTR, EROP, ISW, IERR)
```

```
INTEGER :: N_POINTS, ISW, IERR  
REAL(8), DIMENSION(:) :: ACOR, XCOR, FLTR, EROP
```

```
SUBROUTINE WIENER_64(N_POINTS, ACOR, XCOR, FLTR, EROP, ISW, IERR)
```

```
INTEGER(8) :: N_POINTS, ISW, IERR  
REAL(8), DIMENSION(:) :: ACOR, XCOR, FLTR, EROP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void dwieners(int n_points, double *acor, double *xcor, double *fltr, double *erop, int *isw, int *ierr);
```

```
void dwieners_64(long n_points, double *acor, double *xcor, double *fltr, double *erop, long *isw, long *ierr);
```

PURPOSE

dwienner performs Wiener deconvolution of two signals.

ARGUMENTS

N_POINTS (input)

On entry, the number of points in the input correlations. Unchanged on exit.

ACOR (input)

On entry, autocorrelation coefficients. Unchanged on exit.

XCOR (input)

On entry, cross-correlation coefficients. Unchanged on exit.

FLTR (output)

On exit, filter coefficients.

EROP (output)

On exit, the prediction error.

ISW (input)

On entry, if ISW .EQ. 0 then perform spiking deconvolution, otherwise perform general deconvolution. Unchanged on exit.

IERR (output)

On exit, the deconvolution was successful iff IERR .EQ. 0, otherwise there was an error.

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NAME

dzasum - Return the sum of the absolute values of a vector x.

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DZASUM(N, X, INCX)

DOUBLE COMPLEX X(*)
INTEGER N, INCX

DOUBLE PRECISION FUNCTION DZASUM_64(N, X, INCX)

DOUBLE COMPLEX X(*)
INTEGER*8 N, INCX
```

F95 INTERFACE

```
REAL(8) FUNCTION ASUM([N], X, [INCX])

COMPLEX(8), DIMENSION(:) :: X
INTEGER :: N, INCX

REAL(8) FUNCTION ASUM_64([N], X, [INCX])

COMPLEX(8), DIMENSION(:) :: X
INTEGER(8) :: N, INCX
```

C INTERFACE

```
#include <sunperf.h>

double dzasum(int n, doublecomplex *x, int incx);

double dzasum_64(long n, doublecomplex *x, long incx);
```

PURPOSE

dzasum Return the sum of the absolute values of the elements of x where x is an n-vector. This is the sum of the abso-

lute values of the real and complex elements and not the sum of the squares of the real and complex elements.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero or negative. Unchanged on exit.

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NAME

dznrm2 - Return the Euclidian norm of a vector.

SYNOPSIS

```
DOUBLE PRECISION FUNCTION DZNRM2(N, X, INCX)

DOUBLE COMPLEX X(*)
INTEGER N, INCX

DOUBLE PRECISION FUNCTION DZNRM2_64(N, X, INCX)

DOUBLE COMPLEX X(*)
INTEGER*8 N, INCX
```

F95 INTERFACE

```
REAL(8) FUNCTION NRM2([N], X, [INCX])

COMPLEX(8), DIMENSION(:) :: X
INTEGER :: N, INCX

REAL(8) FUNCTION NRM2_64([N], X, [INCX])

COMPLEX(8), DIMENSION(:) :: X
INTEGER(8) :: N, INCX
```

C INTERFACE

```
#include <sunperf.h>

double dznrm2(int n, doublecomplex *x, int incx);

double dznrm2_64(long n, doublecomplex *x, long incx);
```

PURPOSE

dznrm2 Return the Euclidian norm of a vector x where x is an n-vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. If $\text{INCX} < 1$ then DZNRM2 returns 0. Unchanged on exit.

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NAME

ezfftb - computes a periodic sequence from its Fourier coefficients. EZFFTB is a simplified but slower version of RFFTB.

SYNOPSIS

```
SUBROUTINE EZFFTB(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER N  
REAL AZERO  
REAL R(*), A(*), B(*), WSAVE(*)
```

```
SUBROUTINE EZFFTB_64(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER*8 N  
REAL AZERO  
REAL R(*), A(*), B(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE EZFFTB(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER :: N  
REAL :: AZERO  
REAL, DIMENSION(:) :: R, A, B, WSAVE
```

```
SUBROUTINE EZFFTB_64(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER(8) :: N  
REAL :: AZERO  
REAL, DIMENSION(:) :: R, A, B, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ezfftb(int n, float *r, float azero, float *a, float  
*b, float *wsave);
```

```
void ezfftb_64(long n, float *r, float azero, float *a,  
float *b, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be synthesized. The method is most efficient when N is the product of small primes. $N \geq 0$.

R (output)
On exit, the Fourier synthesis of the inputs.

AZERO (input)
On entry, the constant Fourier coefficient A0.
Unchanged on exit.

A (input/output)
On entry, arrays that contain the remaining Fourier coefficients. On exit, these arrays are unchanged.

B (input/output)
On entry, arrays that contain the remaining Fourier coefficients. On exit, these arrays are unchanged.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$, initialized by EZFFTI.

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NAME

ezfft - computes the Fourier coefficients of a periodic sequence. EZFFT is a simplified but slower version of RFFT.

SYNOPSIS

```
SUBROUTINE EZFFT(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER N  
REAL AZERO  
REAL R(*), A(*), B(*), WSAVE(*)
```

```
SUBROUTINE EZFFT_64(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER*8 N  
REAL AZERO  
REAL R(*), A(*), B(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE EZFFT(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER :: N  
REAL :: AZERO  
REAL, DIMENSION(:) :: R, A, B, WSAVE
```

```
SUBROUTINE EZFFT_64(N, R, AZERO, A, B, WSAVE)
```

```
INTEGER(8) :: N  
REAL :: AZERO  
REAL, DIMENSION(:) :: R, A, B, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ezfft(int n, float *r, float azero, float *a, float  
          *b, float *wsave);
```

```
void ezfft_64(long n, float *r, float azero, float *a,  
             float *b, float *wsave);
```

ARGUMENTS

- N (input) Length of the sequence to be transformed. The method is most efficient when N is the product of small primes. $N \geq 0$.
- R (input) A real array of length N containing the sequence to be transformed. On exit, R is unchanged.
- AZERO (output)
On exit, the sum from $i=1$ to $i=n$ of $r(i)/n$.
- A (input/output)
On entry, arrays that contain the remaining Fourier coefficients. On exit, these arrays are unchanged.
- B (input/output)
On entry, arrays that contain the remaining Fourier coefficients. On exit, these arrays are unchanged.
- WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$, initialized by EZFFTI.

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NAME

ezffti - initializes the array WSAVE, which is used in both EZFFTF and EZFFTB.

SYNOPSIS

```
SUBROUTINE EZFFTI(N, WSAVE)

INTEGER N
REAL WSAVE(*)

SUBROUTINE EZFFTI_64(N, WSAVE)

INTEGER*8 N
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE EZFFTI(N, WSAVE)

INTEGER :: N
REAL, DIMENSION(:) :: WSAVE

SUBROUTINE EZFFTI_64(N, WSAVE)

INTEGER(8) :: N
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void ezffti(int n, float *wsave);

void ezffti_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array with a dimension of at least (3

* N + 15). The same work array can be used for both EZFFTF and EZFFTB as long as N remains unchanged. Different WSAVE arrays are required for different values of N. This initialization does not have to be repeated between calls to EZFFTF or EZFFTB as long as N and WSAVE remain unchanged, thus subsequent transforms can be obtained faster than the first.

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NAME

fft - Fast Fourier transform subroutines

OVERVIEW

The signal processing software in Sun Performance Library includes a set of routines based on public domain packages FFTPACK and VFFPACK that computes the Fast Fourier Transform. These routines are now being replaced by a new interface (Perflib interface).

MAPPING

Below is a mapping of routines from the FFTPACK interface and the new Perflib interface. See individual man pages for more detail.

FFTPACK interface	Perflib interface
RFFTF (DFFTF)	SFFTC (DFFTZ)
RFFTB (DFFTB)	CFFTS (ZFFTD)
CFFTF (ZFFTF)	CFFTC (ZFFTZ)
EZFFTF (DEZFFTF)	SFFTC (DFFTZ)
EZFFTB (DEZFFTB)	CFFTS (ZFFTD)
CFFTB (ZFFTB)	CFFTC (ZFFTZ)
RFFT2F (DFFT2F)	SFFT2C (DFFT2Z)
RFFT2B (DFFT2B)	CFFT2S (ZFFT2D)
CFFT2F (ZFFT2F)	CFFT2C (ZFFT2Z)
CFFT2B (ZFFT2B)	CFFT2C (ZFFT2Z)
RFFT3F (DFFT3F)	SFFT3C (DFFT3Z)
RFFT3B (DFFT3B)	CFFT3S (ZFFT3D)
CFFT3B (ZFFT3B)	CFFT3C (ZFFT3Z)
CFFT3F (ZFFT3F)	CFFT3C (ZFFT3Z)
VCFFTF (VZFFTF)	CFFTCM (ZFFTZM)
VCFFTB (VZFFTB)	CFFTCM (ZFFTZM)
VRFFTF (VDFFTF)	SFFTCM (DFFTZM)
VRFFTB (VDFFTB)	CFFTCM (ZFFTDM)
RFFTI (DFFTI)	SFFTC (DFFTZ), CFFTS (ZFFTD)
CFFTI (ZFFTI)	CFFTC (ZFFTZ)
EZFFTI (DEZFFTI)	SFFTC (DFFTZ), CFFTS (ZFFTD)

RFFT2I (DFFT2I)	SFFTC2 (DFFTZ2), CFFTS2 (ZFFTD2)
RFFT3I (DFFT3I)	SFFTC3 (DFFTZ3), CFFTS3 (ZFFTD3)
CFFT2I (ZFFT2I)	CFFTC2 (ZFFTZ2)
CFFT3I (ZFFT3I)	CFFTC3 (ZFFTZ3)
VCFFTI (VZFFTI)	CFFTCM (ZFFTZM)
VRFFTI (VDFFTI)	SFFTCM (DFFTZM), CFFTSM (ZFFTDM)

NOTES

Unlike the FFTPACK interface, the Perflib interface does not provide separate routines for initialization. Computation and initialization can be selected by an argument in the calling sequence of each routine. Similar to the FFTPACK routines, the weight and factor tables need to be initialized once for a particular transform length. Once these tables are initialized, they can be used repeatedly to compute the forward and inverse transforms for different data sets until, of course, the transform length is changed. The appropriate transform routine is then called to initialize the tables for the new length.

The Perflib interface gives the user the option of computing the FFT in-place (input overwritten by transform results) or out-of-place (input unchanged) in every routine. When an out-of-place transform is requested, the input and output arrays must not overlap in memory. In-place transforms require that there be perfect overlay between the input and output arrays. That is, the arrays must begin at the same memory location. The routines assume (and therefore do not check) that these conditions are satisfied. In some cases, the dimension(s) of the input and output arrays are related to each other. Below is a summary of requirements of the array dimensions. LDX1 and LDX are leading dimensions of the input arrays and LDY1 and LDY are leading dimensions of the output arrays. LDX2 and LDY2 are the second dimensions of the input and output arrays, respectively. N1 and N2 are the first and second actual dimensions of the problem.

Routine name	in-place	out-of-place
SFFTCM, DFFTZM	LDX = 2*LDY LDY >= N1/2+1	LDX >= N1 LDY >= N1/2+1
CFFTSM, ZFFTDM	LDX >= N1/2+1 LDY = 2*LDX	LDX >= N1/2+1 LDY >= N1
CFFTCM, ZFFTZM	LDX >= N1 LDY = LDX	LDX >= N1 LDY >= N1
SFFTC2, DFFTZ2	LDX = 2*LDY LDY >= N1/2+1	LDX >= N1 LDY >= N1/2+1
CFFTS2, ZFFTD2	LDX >= N1/2+1 LDY = 2*LDX	LDX >= N1/2+1 LDY >= 2*LDX; LDY is even
CFFTC2, ZFFTZ2	LDX >= N1 LDY = LDX	LDX >= N1 LDY >= N1
CFFTS3, ZFFTD3	LDX1 >= N1/2+1	LDX1 >= N1/2+1

```

LDX2 >= N2      LDX2 >= N2
LDY1 = 2*LDX1  LDY1 >= 2*LDX1; LDY1 is
even

LDY2 = LDX2      LDY2 >= N2

CFFTC3, ZFFT3   LDX1 >= N1      LDX1 >= N1
                  LDX2 >= N2      LDX2 >= N2
                  LDY1 = LDX1      LDY1 >= N1
                  LDY2 = LDX2      LDY2 >= N2

SFFTC3, DFFT3   LDX1 = 2*LDY1  LDX1 >= N1
                  LDX2 >= N2      LDX2 >= N2
                  LDY1 >= N1/2+1  LDY1 >= N1/2+1
                  LDY2 = LDX2      LDY2 >= N2

```

In routines that compute transforms between complex and real data type such as SFFTC2 or CFFTS3 even though the transform length is N1, only (N1/2+1) complex data points are referenced or computed. These data points make up the positive-frequency half of the spectrum of the Discrete Fourier Transform. The remaining N1-(N1/2+1) data points can be easily derived since they are complex conjugates and therefore are not stored or referenced.

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NAME

icamax - return the index of the element with largest absolute value.

SYNOPSIS

```
INTEGER FUNCTION ICAMAX(N, X, INCX)
```

```
COMPLEX X(*)  
INTEGER N, INCX
```

```
INTEGER*8 FUNCTION ICAMAX_64(N, X, INCX)
```

```
COMPLEX X(*)  
INTEGER*8 N, INCX
```

F95 INTERFACE

```
INTEGER FUNCTION IAMAX([N], X, [INCX])
```

```
COMPLEX, DIMENSION(:) :: X  
INTEGER :: N, INCX
```

```
INTEGER(8) FUNCTION IAMAX_64([N], X, [INCX])
```

```
COMPLEX, DIMENSION(:) :: X  
INTEGER(8) :: N, INCX
```

C INTERFACE

```
#include <sunperf.h>
```

```
int icamax(int n, complex *x, int incx);
```

```
long icamax_64(long n, complex *x, long incx);
```

PURPOSE

icamax return the index of the element in x with largest

absolute value where x is an n -vector and absolute value is defined as the sum of the absolute value of the real part and the absolute value of the imaginary part.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . INCX must be positive. Unchanged on exit.

NOTES

If the vector contains all NaNs, the function returns 1. If the vector contains valid complex numbers and one or more NaNs, the routine returns the index of the element containing the largest absolute value.

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NAME

idamax - return the index of the element with largest absolute value.

SYNOPSIS

```
INTEGER FUNCTION IDAMAX(N, X, INCX)
```

```
INTEGER N, INCX  
DOUBLE PRECISION X(*)
```

```
INTEGER*8 FUNCTION IDAMAX_64(N, X, INCX)
```

```
INTEGER*8 N, INCX  
DOUBLE PRECISION X(*)
```

F95 INTERFACE

```
INTEGER FUNCTION IAMAX([N], X, [INCX])
```

```
INTEGER :: N, INCX  
REAL(8), DIMENSION(:) :: X
```

```
INTEGER(8) FUNCTION IAMAX_64([N], X, [INCX])
```

```
INTEGER(8) :: N, INCX  
REAL(8), DIMENSION(:) :: X
```

C INTERFACE

```
#include <sunperf.h>
```

```
int idamax(int n, double *x, int incx);
```

```
long idamax_64(long n, double *x, long incx);
```

PURPOSE

idamax return the index of the element in x with largest

absolute value where x is an n -vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . INCX must be positive. Unchanged on exit.

NOTES

If the vector contains all NaNs, the function returns 1. If the vector contains valid floating point numbers and one or more NaNs, the routine returns the index of the element containing the largest absolute value.

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NAME

ilaenv - The name of the calling subroutine, in either upper case or lower case.

SYNOPSIS

```
INTEGER FUNCTION ILAENV(ISPEC, NAME, OPTS, N1, N2, N3, N4)
```

```
CHARACTER * 6 NAME CHARACTER * 4 OPTS  
INTEGER ISPEC, N1, N2, N3, N4
```

```
INTEGER*8 FUNCTION ILAENV_64(ISPEC, NAME, OPTS, N1, N2, N3, N4)
```

```
CHARACTER * 6 NAME CHARACTER * 4 OPTS  
INTEGER*8 ISPEC, N1, N2, N3, N4
```

F95 INTERFACE

```
INTEGER FUNCTION ILAENV(ISPEC, NAME, OPTS, N1, N2, N3, N4)
```

```
CHARACTER(LEN=6) :: NAME CHARACTER(LEN=4) :: OPTS  
INTEGER :: ISPEC, N1, N2, N3, N4
```

```
INTEGER(8) FUNCTION ILAENV_64(ISPEC, NAME, OPTS, N1, N2, N3, N4)
```

```
CHARACTER(LEN=6) :: NAME CHARACTER(LEN=4) :: OPTS  
INTEGER(8) :: ISPEC, N1, N2, N3, N4
```

C INTERFACE

```
#include <sunperf.h>
```

```
int ilaenv(int ispec, char *name, char *opts, int n1, int  
n2, int n3, int n4);
```

```
long ilaenv_64(long ispec, char *name, char *opts, long n1,  
long n2, long n3, long n4);
```

PURPOSE

ilaenv is called from the LAPACK routines to choose problem-dependent parameters for the local environment. See ISPEC for a description of the parameters.

This version provides a set of parameters which should give good, but not optimal, performance on many of the currently available computers. Users are encouraged to modify this subroutine to set the tuning parameters for their particular machine using the option and problem size information in the arguments.

This routine will not function correctly if it is converted to all lower case. Converting it to all upper case is allowed.

ARGUMENTS

ISPEC (input)

Specifies the parameter to be returned as the value of ILAENV. = 1: the optimal blocksize; if this value is 1, an unblocked algorithm will give the best performance. = 2: the minimum block size for which the block routine should be used; if the usable block size is less than this value, an unblocked routine should be used. = 3: the crossover point (in a block routine, for N less than this value, an unblocked routine should be used) = 4: the number of shifts, used in the nonsymmetric eigenvalue routines = 5: the minimum column dimension for blocking to be used; rectangular blocks must have dimension at least k by m, where k is given by ILAENV(2,...) and m by ILAENV(5,...) = 6: the crossover point for the SVD (when reducing an m by n matrix to bidiagonal form, if $\max(m,n)/\min(m,n)$ exceeds this value, a QR factorization is used first to reduce the matrix to a triangular form.) = 7: the number of processors = 8: the crossover point for the multishift QR and QZ methods for nonsymmetric eigenvalue problems. = 9: maximum size of the subproblems at the bottom of the computation tree in the divide-and-conquer algorithm (used by xGELSD and xGESDD) =10: ieee NaN arithmetic can be trusted not to trap =11: infinity arithmetic can be trusted not to trap

NAME (input)

The name of the calling subroutine, in either upper case or lower case.

OPTS (input)

The character options to the subroutine NAME, concatenated into a single character string. For example, UPLO = 'U', TRANS = 'T', and DIAG = 'N' for a triangular routine would be specified as OPTS = 'UTN'.

N1 (input)

INTEGER

```

N2 (input)
      INTEGER
N3 (input)
      INTEGER

N4 (input)
      INTEGER
N1, N2, N3, N4 are problem dimensions for the sub-
routine NAME; these may not all be required.
>= 0: the value of the parameter specified by
ISPEC
< 0: if ILAENV = -k, the k-th argument had an
illegal value.
< 0: if ILAENV = -k, the k-th argument had an
illegal value.

```

FURTHER DETAILS

The following conventions have been used when calling ILAENV from the LAPACK routines:

- 1) OPTS is a concatenation of all of the character options to subroutine NAME, in the same order that they appear in the argument list for NAME, even if they are not used in determining the value of the parameter specified by ISPEC.
- 2) The problem dimensions N1, N2, N3, N4 are specified in the order that they appear in the argument list for NAME. N1 is used first, N2 second, and so on, and unused problem dimensions are passed a value of -1.
- 3) The parameter value returned by ILAENV is checked for validity in the calling subroutine. For example, ILAENV is used to retrieve the optimal blocksize for STRTRI as follows:

```

NB = ILAENV( 1, 'STRTRI', UPLO // DIAG, N, -1, -1, -1 )
IF( NB.LE.1 ) NB = MAX( 1, N )

```

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NAME

isamax - return the index of the element with largest absolute value.

SYNOPSIS

```
INTEGER FUNCTION ISAMAX(N, X, INCX)
```

```
INTEGER N, INCX  
REAL X(*)
```

```
INTEGER*8 FUNCTION ISAMAX_64(N, X, INCX)
```

```
INTEGER*8 N, INCX  
REAL X(*)
```

F95 INTERFACE

```
INTEGER FUNCTION IAMAX([N], X, [INCX])
```

```
INTEGER :: N, INCX  
REAL, DIMENSION(:) :: X
```

```
INTEGER(8) FUNCTION IAMAX_64([N], X, [INCX])
```

```
INTEGER(8) :: N, INCX  
REAL, DIMENSION(:) :: X
```

C INTERFACE

```
#include <sunperf.h>
```

```
int isamax(int n, float *x, int incx);
```

```
long isamax_64(long n, float *x, long incx);
```

PURPOSE

isamax return the index of the element in x with largest

absolute value where x is an n -vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the sub-routine to have any visible effect. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . INCX must be positive. Unchanged on exit.

NOTES

If the vector contains all NaNs, the function returns 1. If the vector contains valid floating point numbers and one or more NaNs, the routine returns the index of the element containing the largest absolute value.

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NAME

izamax - return the index of the element with largest absolute value.

SYNOPSIS

```
INTEGER FUNCTION IZAMAX(N, X, INCX)
```

```
DOUBLE COMPLEX X(*)  
INTEGER N, INCX
```

```
INTEGER*8 FUNCTION IZAMAX_64(N, X, INCX)
```

```
DOUBLE COMPLEX X(*)  
INTEGER*8 N, INCX
```

F95 INTERFACE

```
INTEGER FUNCTION IAMAX([N], X, [INCX])
```

```
COMPLEX(8), DIMENSION(:) :: X  
INTEGER :: N, INCX
```

```
INTEGER(8) FUNCTION IAMAX_64([N], X, [INCX])
```

```
COMPLEX(8), DIMENSION(:) :: X  
INTEGER(8) :: N, INCX
```

C INTERFACE

```
#include <sunperf.h>
```

```
int izamax(int n, doublecomplex *x, int incx);
```

```
long izamax_64(long n, doublecomplex *x, long incx);
```

PURPOSE

izamax return the index of the element in x with largest

absolute value where x is an n -vector and absolute value is defined as the sum of the absolute value of the real part and the absolute value of the imaginary part.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . INCX must be positive. Unchanged on exit.

NOTES

If the vector contains all NaNs, the function returns 1. If the vector contains valid double complex numbers and one or more NaNs, the routine returns the index of the element containing the largest absolute value.

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NAME

lsame - returns `.TRUE.` if CA is the same letter as CB regardless of case

SYNOPSIS

```
LOGICAL FUNCTION LSAME(CA, CB)
```

```
CHARACTER * 1 CA, CB
```

```
LOGICAL*8 FUNCTION LSAME_64(CA, CB)
```

```
CHARACTER * 1 CA, CB
```

F95 INTERFACE

```
LOGICAL FUNCTION LSAME(CA, CB)
```

```
CHARACTER(LEN=1) :: CA, CB
```

```
LOGICAL(8) FUNCTION LSAME_64(CA, CB)
```

```
CHARACTER(LEN=1) :: CA, CB
```

C INTERFACE

```
#include <sunperf.h>
```

```
int lsame(char ca, char cb);
```

```
long lsame_64(char ca, char cb);
```

PURPOSE

lsame returns `.TRUE.` if CA is the same letter as CB regardless of case.

ARGUMENTS

CA (input)

On entry, CA is a single character to compare with
CB. Unchanged on exit.

CB (input)

On entry, CB is a single character to compare with
CA. Unchanged on exit.

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NAME

rffft2b - compute a periodic sequence from its Fourier coefficients. The RFFT operations are unnormalized, so a call of RFFT2F followed by a call of RFFT2B will multiply the input sequence by M*N.

SYNOPSIS

```
SUBROUTINE RFFT2B(PLACE, M, N, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE  
INTEGER M, N, LDA, LDB, LWORK  
REAL A(LDA,*), B(2*LDB,*), WORK(*)
```

```
SUBROUTINE RFFT2B_64(PLACE, M, N, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE  
INTEGER*8 M, N, LDA, LDB, LWORK  
REAL A(LDA,*), B(2*LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2B(PLACE, [M], [N], A, [LDA], B, [LDB], WORK, LWORK)
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER :: M, N, LDA, LDB, LWORK  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE FFT2B_64(PLACE, [M], [N], A, [LDA], B, [LDB], WORK, LWORK)
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER(8) :: M, N, LDA, LDB, LWORK  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void rfft2b(char place, int m, int n, float *a, int lda,  
           float *b, int ldb, float *work, int lwork);
```

```
void rfft2b_64(char place, long m, long n, float *a, long
```

```
lda, float *b, long ldb, float *work, long lwork);
```

ARGUMENTS

PLACE (input)

Character. If PLACE = 'I' or 'i' (for in-place) , the input and output data are stored in array A. If PLACE = 'O' or 'o' (for out-of-place), the input data is stored in array B while the output is stored in A.

M (input) Integer specifying the number of rows to be transformed. It is most efficient when M is a product of small primes. $M \geq 0$; when $M = 0$, the subroutine returns immediately without changing any data.

N (input) Integer specifying the number of columns to be transformed. It is most most efficient when N is a product of small primes. $N \geq 0$; when $N = 0$, the subroutine returns immediately without changing any data.

A (input/output)

Real array of dimension (LDA,N). On entry, the two-dimensional array A(LDA,N) contains the input data to be transformed if an in-place transform is requested. Otherwise, it is not referenced. Upon exit, results are stored in A(1:M,1:N).

LDA (input)

Integer specifying the leading dimension of A. If an out-of-place transform is desired $LDA \geq M$. Else if an in-place transform is desired $LDA \geq 2*(M/2+1)$ and LDA must be even.

B (input/output)

Real array of dimension (2*LDB, N). On entry, if an out-of-place transform is requested B contains the input data. Otherwise, B is not referenced. B is unchanged upon exit.

LDB (input)

Integer. If an out-of-place transform is desired, $2*LDB$ is the leading dimension of the array B which contains the data to be transformed and $2*LDB \geq 2*(M/2+1)$. Otherwise it is not referenced.

WORK (input/output)

One-dimensional real array of length at least LWORK. On input, WORK must have been initialized by RFFT2I.

LWORK (input)

Integer. $LWORK \geq (M + 2*N + \text{MAX}(M, 2*N) + 30)$

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NAME

rffft2f - compute the Fourier coefficients of a periodic sequence. The RFFT operations are unnormalized, so a call of RFFT2F followed by a call of RFFT2B will multiply the input sequence by M*N.

SYNOPSIS

```
SUBROUTINE RFFT2F(PLACE, FULL, M, N, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE, FULL  
INTEGER M, N, LDA, LDB, LWORK  
REAL A(LDA,*), B(2*LDB,*), WORK(*)
```

```
SUBROUTINE RFFT2F_64(PLACE, FULL, M, N, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE, FULL  
INTEGER*8 M, N, LDA, LDB, LWORK  
REAL A(LDA,*), B(2*LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2F(PLACE, FULL, [M], [N], A, [LDA], B, [LDB], WORK,  
LWORK)
```

```
CHARACTER(LEN=1) :: PLACE, FULL  
INTEGER :: M, N, LDA, LDB, LWORK  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE FFT2F_64(PLACE, FULL, [M], [N], A, [LDA], B, [LDB], WORK,  
LWORK)
```

```
CHARACTER(LEN=1) :: PLACE, FULL  
INTEGER(8) :: M, N, LDA, LDB, LWORK  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void rfft2f(char place, char full, int m, int n, float *a,  
int lda, float *b, int ldb, float *work, int
```

```

        lwork);

void rfft2f_64(char place, char full, long m, long n, float
        *a, long lda, float *b, long ldb, float *work,
        long lwork);

```

ARGUMENTS

PLACE (input)

Character. If PLACE = 'I' or 'i' (for in-place) , the input and output data are stored in array A. If PLACE = 'O' or 'o' (for out-of-place), the input data is stored in array B while the output is stored in A.

FULL (input)

Indicates whether or not to generate the full result matrix. 'F' or 'f' will cause RFFT2F to generate the full result matrix. Otherwise only a partial matrix that takes advantage of symmetry will be generated.

M (input) Integer specifying the number of rows to be transformed. It is most efficient when M is a product of small primes. $M \geq 0$; when $M = 0$, the subroutine returns immediately without changing any data.

N (input) Integer specifying the number of columns to be transformed. It is most most efficient when N is a product of small primes. $N \geq 0$; when $N = 0$, the subroutine returns immediately without changing any data.

A (input/output)

On entry, a two-dimensional array A(LDA,N) that contains the data to be transformed. Upon exit, A is unchanged if an out-of-place transform is done. If an in-place transform with partial result is requested, $A(1:(M/2+1)*2,1:N)$ will contain the transformed results. If an in-place transform with full result is requested, $A(1:2*M,1:N)$ will contain complete transformed results.

LDA (input)

Leading dimension of the array containing the data to be transformed. LDA must be even if the transformed sequences are to be stored in A.

If PLACE = ('O' or 'o') $LDA \geq M$

If PLACE = ('I' or 'i') LDA must be even. If

FULL = ('F' or 'f'), $LDA \geq 2*M$

FULL is not ('F' or 'f'), $LDA \geq (M/2+1)*2$

B (input/output)

Upon exit, a two-dimensional array B(2*LDB,N) that contains the transformed results if an out-of-place transform is done. Otherwise, B is not used.

If an out-of-place transform is done and FULL is not 'F' or 'f', $B(1:(M/2+1)*2,1:N)$ will contain

the partial transformed results. If FULL = 'F' or 'f', B(1:2*M,1:N) will contain the complete transformed results.

LDB (input)

2*LDB is the leading dimension of the array B. If an in-place transform is desired LDB is ignored. If PLACE is ('O' or 'o') and FULL is ('F' or 'f'), LDB >= M
FULL is not ('F' or 'f'), LDB >= M/2+1
Note that even though LDB is used in the argument list, 2*LDB is the actual leading dimension of B.

WORK (input/output)

One-dimensional real array of length at least LWORK. On input, WORK must have been initialized by RFFT2I.

LWORK (input)

Integer. LWORK >= (M + 2*N + MAX(M, 2*N) + 30)

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NAME

rffft2i - initialize the array WSAVE, which is used in both the forward and backward transforms.

SYNOPSIS

```
SUBROUTINE RFFT2I(M, N, WORK)
```

```
INTEGER M, N  
REAL WORK(*)
```

```
SUBROUTINE RFFT2I_64(M, N, WORK)
```

```
INTEGER*8 M, N  
REAL WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2I(M, N, WORK)
```

```
INTEGER :: M, N  
REAL, DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT2I_64(M, N, WORK)
```

```
INTEGER(8) :: M, N  
REAL, DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void rfft2i(int m, int n, float *work);
```

```
void rfft2i_64(long m, long n, float *work);
```

ARGUMENTS

M (input) Number of rows to be transformed. M >= 0.

N (input) Number of columns to be transformed. N >= 0.

WORK (input/output)

On entry, an array of dimension $(M + 2*N + \text{MAX}(M, 2*N) + 30)$ or greater. RFFT2I needs to be called only once to initialize array WORK before calling RFFT2F and/or RFFT2B if M, N and WORK remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

rfft3b - compute a periodic sequence from its Fourier coefficients. The RFFT operations are unnormalized, so a call of RFFT3F followed by a call of RFFT3B will multiply the input sequence by $M*N*K$.

SYNOPSIS

```
SUBROUTINE RFFT3B(PLACE, M, N, K, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE  
INTEGER M, N, K, LDA, LDB, LWORK  
REAL A(LDA,N,*), B(2*LDB,N,*), WORK(*)
```

```
SUBROUTINE RFFT3B_64(PLACE, M, N, K, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE  
INTEGER*8 M, N, K, LDA, LDB, LWORK  
REAL A(LDA,N,*), B(2*LDB,N,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3B(PLACE, [M], [N], [K], A, [LDA], B, [LDB], WORK,  
LWORK)
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER :: M, N, K, LDA, LDB, LWORK  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,:,:) :: A, B
```

```
SUBROUTINE FFT3B_64(PLACE, [M], [N], [K], A, [LDA], B, [LDB], WORK,  
LWORK)
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER(8) :: M, N, K, LDA, LDB, LWORK  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void rfft3b(char place, int m, int n, int k, float *a, int  
lda, float *b, int ldb, float *work, int lwork);
```

```
void rfft3b_64(char place, long m, long n, long k, float *a,
               long lda, float *b, long ldb, float *work, long
               lwork);
```

ARGUMENTS

PLACE (input)

Select an in-place ('I' or 'i') or out-of-place ('O' or 'o') transform.

M (input) Integer specifying the number of rows to be transformed. It is most efficient when M is a product of small primes. $M \geq 0$; when $M = 0$, the subroutine returns immediately without changing any data.

N (input) Integer specifying the number of columns to be transformed. It is most efficient when N is a product of small primes. $N \geq 0$; when $N = 0$, the subroutine returns immediately without changing any data.

K (input) Integer specifying the number of planes to be transformed. It is most efficient when K is a product of small primes. $K \geq 0$; when $K = 0$, the subroutine returns immediately without changing any data.

A (input/output)

On entry, the three-dimensional array $A(LDA,N,K)$ contains the data to be transformed if an in-place transform is requested. Otherwise, it is not referenced. Upon exit, results are stored in $A(1:M,1:N,1:K)$.

LDA (input)

Integer specifying the leading dimension of A. If an out-of-place transform is desired $LDA \geq M$. Else if an in-place transform is desired $LDA \geq 2*(M/2+1)$.

B (input/output)

Real array of dimension $B(2*LDB,N,K)$. On entry, if an out-of-place transform is requested $B(1:2*(M/2+1),1:N,1:K)$ contains the input data. Otherwise, B is not referenced. B is unchanged upon exit.

LDB (input)

If an out-of-place transform is desired, $2*LDB$ is the leading dimension of the array B which contains the data to be transformed and $2*LDB \geq 2*(M/2+1)$. Otherwise it is not referenced.

WORK (input/output)

One-dimensional real array of length at least $LWORK$. On input, WORK must have been initialized by RFFT3I.

LWORK (input)

Integer. LWORK $\geq (M + 2*(N + K) + 4*K + 45)$.

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NAME

ffft3f - compute the Fourier coefficients of a real periodic sequence. The RFFT operations are unnormalized, so a call of RFFT3F followed by a call of RFFT3B will multiply the input sequence by $M*N*K$.

SYNOPSIS

```
SUBROUTINE RFFT3F(PLACE, FULL, M, N, K, A, LDA, B, LDB, WORK, LWORK)
```

```
CHARACTER * 1 PLACE, FULL  
INTEGER M, N, K, LDA, LDB, LWORK  
REAL A(LDA,N,*), B(2*LDB,N,*), WORK(*)
```

```
SUBROUTINE RFFT3F_64(PLACE, FULL, M, N, K, A, LDA, B, LDB, WORK,  
LWORK)
```

```
CHARACTER * 1 PLACE, FULL  
INTEGER*8 M, N, K, LDA, LDB, LWORK  
REAL A(LDA,N,*), B(2*LDB,N,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3F(PLACE, FULL, [M], [N], [K], A, [LDA], B, [LDB],  
WORK, LWORK)
```

```
CHARACTER(LEN=1) :: PLACE, FULL  
INTEGER :: M, N, K, LDA, LDB, LWORK  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:, :, :) :: A, B
```

```
SUBROUTINE FFT3F_64(PLACE, FULL, [M], [N], [K], A, [LDA], B, [LDB],  
WORK, LWORK)
```

```
CHARACTER(LEN=1) :: PLACE, FULL  
INTEGER(8) :: M, N, K, LDA, LDB, LWORK  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:, :, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void rfft3f(char place, char full, int m, int n, int k,
```

```

float *a, int lda, float *b, int ldb, float *work,
int lwork);

void rfft3f_64(char place, char full, long m, long n, long
k, float *a, long lda, float *b, long ldb, float
*work, long lwork);

```

ARGUMENTS

PLACE (input)

Select an in-place ('I' or 'i') or out-of-place ('O' or 'o') transform.

FULL (input)

Select a full ('F' or 'f') or partial (' ') representation of the results. If the caller selects full representation then an MxNxK real array will transform to produce an MxNxK complex array. If the caller does not select full representation then an MxNxK real array will transform to a (M/2+1)xNxK complex array that takes advantage of the symmetry properties of a transformed real sequence.

M (input) Integer specifying the number of rows to be transformed. It is most efficient when M is a product of small primes. $M \geq 0$; when $M = 0$, the subroutine returns immediately without changing any data.

N (input) Integer specifying the number of columns to be transformed. It is most efficient when N is a product of small primes. $N \geq 0$; when $N = 0$, the subroutine returns immediately without changing any data.

K (input) Integer specifying the number of planes to be transformed. It is most efficient when K is a product of small primes. $K \geq 0$; when $K = 0$, the subroutine returns immediately without changing any data.

A (input/output)

On entry, a three-dimensional array A(LDA,N,K) that contains input data to be transformed. On exit, if an in-place transform is done and FULL is not 'F' or 'f', A(1:2*(M/2+1),1:N,1:K) will contain the partial transformed results. If FULL = 'F' or 'f', A(1:2*M,1:N,1:K) will contain the complete transformed results.

LDA (input)

Leading dimension of the array containing the data to be transformed. LDA must be even if the transformed sequences are to be stored in A.

If PLACE = ('O' or 'o') LDA \geq M

If PLACE = ('I' or 'i') LDA must be even. If

FULL = ('F' or 'f'), LDA \geq 2*M

FULL is not ('F' or 'f'), LDA \geq 2*(M/2+1)

B (input/output)

Upon exit, a three-dimensional array $B(2*LDB,N,K)$ that contains the transformed results if an out-of-place transform is done. Otherwise, B is not used.

If an out-of-place transform is done and FULL is not 'F' or 'f', $B(1:2*(M/2+1),1:N,1:K)$ will contain the partial transformed results. If FULL = 'F' or 'f', $B(1:2*M,1:N,1:K)$ will contain the complete transformed results.

LDB (input)

$2*LDB$ is the leading dimension of the array B. If an in-place transform is desired LDB is ignored.

If PLACE is ('O' or 'o') and

FULL is ('F' or 'f'), then $LDB \geq M$

FULL is not ('F' or 'f'), then $LDB \geq M/2 + 1$

Note that even though LDB is used in the argument list, $2*LDB$ is the actual leading dimension of B.

WORK (input/output)

One-dimensional real array of length at least LWORK. WORK must have been initialized by RFFT3I.

LWORK (input)

Integer. $LWORK \geq (M + 2*(N + K) + 4*K + 45)$.

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rffft3i - initialize the array WSAVE, which is used in both RFFT3F and RFFT3B.

SYNOPSIS

```
SUBROUTINE RFFT3I(M, N, K, WORK)
```

```
INTEGER M, N, K  
REAL WORK(*)
```

```
SUBROUTINE RFFT3I_64(M, N, K, WORK)
```

```
INTEGER*8 M, N, K  
REAL WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3I(M, N, K, WORK)
```

```
INTEGER :: M, N, K  
REAL, DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT3I_64(M, N, K, WORK)
```

```
INTEGER(8) :: M, N, K  
REAL, DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void rfft3i(int m, int n, int k, float *work);
```

```
void rfft3i_64(long m, long n, long k, float *work);
```

ARGUMENTS

M (input) Number of rows to be transformed. M >= 0.

N (input) Number of columns to be transformed. N >= 0.

K (input) Number of planes to be transformed. $K \geq 0$.

WORK (input/output)

On entry, an array of dimension $(M + 2*(N + K) + 4*K + 45)$ or greater. RFFT3I needs to be called only once to initialize array WORK before calling RFFT3F and/or RFFT3B if M, N, K and WORK remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

rfftb - compute a periodic sequence from its Fourier coefficients. The RFFT operations are unnormalized, so a call of RFFTF followed by a call of RFFTB will multiply the input sequence by N.

SYNOPSIS

```
SUBROUTINE RFFTB(N, X, WSAVE)
```

```
INTEGER N  
REAL X(*), WSAVE(*)
```

```
SUBROUTINE RFFTB_64(N, X, WSAVE)
```

```
INTEGER*8 N  
REAL X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTB([N], X, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE FFTB_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void rfftb(int n, float *x, float *wsave);
```

```
void rfftb_64(long n, float *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These

subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input) On entry, an array of length N containing the sequence to be transformed.

WSAVE (input)

On entry, WSAVE must be an array of dimension $(2 * N + 15)$ or greater and must have been initialized by RFFTI.

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NAME

rfftf - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of RFFTF followed by a call of RFFTB will multiply the input sequence by N.

SYNOPSIS

```
SUBROUTINE RFFTF(N, X, WSAVE)
```

```
INTEGER N  
REAL X(*), WSAVE(*)
```

```
SUBROUTINE RFFTF_64(N, X, WSAVE)
```

```
INTEGER*8 N  
REAL X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFFTF([N], X, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE FFFTF_64([N], X, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void rfftf(int n, float *x, float *wsave);
```

```
void rfftf_64(long n, float *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These

subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input) On entry, an array of length N containing the sequence to be transformed.

WSAVE (input)

On entry, WSAVE must be an array of dimension $(2 * N + 15)$ or greater and must have been initialized by RFFTI.

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NAME

rffti - initialize the array WSAVE, which is used in both RFFTF and RFFTB.

SYNOPSIS

```
SUBROUTINE RFFTI(N, WSAVE)
```

```
INTEGER N  
REAL WSAVE(*)
```

```
SUBROUTINE RFFTI_64(N, WSAVE)
```

```
INTEGER*8 N  
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTI(N, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: WSAVE
```

```
SUBROUTINE FFTI_64(N, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void rffti(int n, float *wsave);
```

```
void rffti_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array of dimension $(2 * N + 15)$ or greater. RFFTI needs to be called only once to initialize array WORK before calling RFFTF and/or RFFTB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

rfftopt - compute the length of the closest fast FFT

SYNOPSIS

```
INTEGER FUNCTION RFFTOPT(LEN)
```

```
INTEGER LEN
```

```
INTEGER*8 FUNCTION RFFTOPT_64(LEN)
```

```
INTEGER*8 LEN
```

F95 INTERFACE

```
INTEGER FUNCTION RFFTOPT(LEN)
```

```
INTEGER :: LEN
```

```
INTEGER(8) FUNCTION RFFTOPT_64(LEN)
```

```
INTEGER(8) :: LEN
```

C INTERFACE

```
#include <sunperf.h>
```

```
int rfftopt(int len);
```

```
long rfftopt_64(long len);
```

PURPOSE

rfftopt computes the length of the closest fast FFT. Fast Fourier transform algorithms, including those used in Performance Library, work best with vector lengths that are products of small primes. For example, an FFT of length $32=2**5$ will run faster than an FFT of prime length 31 because 32 is a product of small primes and 31 is not. If your application is such that you can taper or zero pad your vector to a larger length then this function may help you

select a better length and run your FFT faster.

RFFTOPT will return an integer no smaller than the input argument N that is the closest number that is the product of small primes. RFFTOPT will return 16 for an input of N=16 and return $18=2*3*3$ for an input of N=17.

Note that the length computed here is not guaranteed to be optimal, only to be a product of small primes. Also, the value returned may change as the underlying

FFTs become capable of handling larger primes. For example, passing in N=51 today will return $52=2*2*13$ rather than $51=3*17$ because the FFTs in Performance Library do not have fast radix 17 code. In the future, radix 17 code may be added

and then N=51 will return 51.

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NAME

`sasum` - Return the sum of the absolute values of a vector `x`.

SYNOPSIS

```
REAL FUNCTION SASUM(N, X, INCX)
```

```
INTEGER N, INCX  
REAL X(*)
```

```
REAL FUNCTION SASUM_64(N, X, INCX)
```

```
INTEGER*8 N, INCX  
REAL X(*)
```

F95 INTERFACE

```
REAL FUNCTION ASUM([N], X, [INCX])
```

```
INTEGER :: N, INCX  
REAL, DIMENSION(:) :: X
```

```
REAL FUNCTION ASUM_64([N], X, [INCX])
```

```
INTEGER(8) :: N, INCX  
REAL, DIMENSION(:) :: X
```

C INTERFACE

```
#include <sunperf.h>
```

```
float sasum(int n, float *x, int incx);
```

```
float sasum_64(long n, float *x, long incx);
```

PURPOSE

`sasum` Return the sum of the absolute values of `x` where `x` is an `n`-vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero or negative. Unchanged on exit.

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NAME

saxpy - compute $y := \alpha * x + y$

SYNOPSIS

```
SUBROUTINE SAXPY(N, ALPHA, X, INCX, Y, INCY)
```

```
INTEGER N, INCX, INCY  
REAL ALPHA  
REAL X(*), Y(*)
```

```
SUBROUTINE SAXPY_64(N, ALPHA, X, INCX, Y, INCY)
```

```
INTEGER*8 N, INCX, INCY  
REAL ALPHA  
REAL X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE AXPY([N], ALPHA, X, [INCX], Y, [INCY])
```

```
INTEGER :: N, INCX, INCY  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X, Y
```

```
SUBROUTINE AXPY_64([N], ALPHA, X, [INCX], Y, [INCY])
```

```
INTEGER(8) :: N, INCX, INCY  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void saxpy(int n, float alpha, float *x, int incx, float *y,  
          int incy);
```

```
void saxpy_64(long n, float alpha, float *x, long incx,  
             float *y, long incy);
```

PURPOSE

saxpy compute $y := \alpha * x + y$ where alpha is a scalar and x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input/output)

($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

saxpyi - Compute $y := \alpha * x + y$

SYNOPSIS

```
SUBROUTINE SAXPYI(NZ, A, X, INDX, Y)
```

```
REAL A  
REAL X(*), Y(*)  
INTEGER NZ  
INTEGER INDX(*)
```

```
SUBROUTINE SAXPYI_64(NZ, A, X, INDX, Y)
```

```
REAL A  
REAL X(*), Y(*)  
INTEGER*8 NZ  
INTEGER*8 INDX(*)
```

```
F95 INTERFACE
```

```
SUBROUTINE AXPYI([NZ], [A], X, INDX, Y)
```

```
REAL :: A  
REAL, DIMENSION(:) :: X, Y  
INTEGER :: NZ  
INTEGER, DIMENSION(:) :: INDX
```

```
SUBROUTINE AXPYI_64([NZ], [A], X, INDX, Y)
```

```
REAL :: A  
REAL, DIMENSION(:) :: X, Y  
INTEGER(8) :: NZ  
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

SAXPYI Compute $y := \alpha * x + y$ where α is a scalar, x is a sparse vector, and y is a vector in full storage form

```
do i = 1, n  
  y(indx(i)) = alpha * x(i) + y(indx(i))
```

enddo

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.

Unchanged on exit.

A (input)

On entry, A(LPHA) specifies the scaling value.

Unchanged on exit. A is defaulted to 1.0E0 for F95
INTERFACE.

X (input)

Vector containing the values of the compressed form.

Unchanged on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

Y (output)

Vector on input which contains the vector Y in full
storage form. On exit, only the elements
corresponding to the indices in INDX have been
modified.

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NAME

sbcomm - block coordinate matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SBCOMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BJNDX, BNNZ, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), BNNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BJNDX(BNNZ)  
REAL             ALPHA, BETA  
REAL             VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SBCOMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BJNDX, BNNZ, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), BNNZ, LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BJNDX(BNNZ)  
REAL             ALPHA, BETA  
REAL             VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BCOMM(TRANSA,MB,[N],KB,ALPHA,DESCRA,VAL,BINDX, BJNDX,  
* BNNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, N, KB, BNNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BJNDX  
REAL             ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BCOMM_64(TRANSA,MB,[N],KB,ALPHA,DESCRA,VAL,BINDX, BJNDX,  
* BNNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, N, KB, BNNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BJNDX  
REAL             ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void sbcomm (int transa, int mb, int n, int kb, float alpha,
int* descra, float *val, int *bindx, int *bjndx, int bnnz,
int lb, float *b, int ldb, float beta, float *c, int ldc);

void sbcomm_64(long transa, long mb, long n, long kb, float
alpha, long *descra, float *val, long *bindx, long *bjndx,
long bnnz, long lb, float *b, long ldb,
float beta, float *c, long ldc);
```

DESCRIPTION

cbcomm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an (mb*lb) by (kb*lb) sparse matrix represented in the block coordinate format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, integer MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, integer KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')

```

5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array of length
                 LB*LB*BNNZ consisting of the non-zero block
                 entries of A, in any order. Each block
                 is stored in standard column-major form.
                 Unchanged on exit.

BINDX(input)    On entry, BINDX is an integer array of length BNNZ
                 consisting of the block row indices of the non-zero
                 block entries of A. Unchanged on exit.

BJNDX(input)    On entry, BJNDX is an integer array of length BNNZ
                 consisting of the block column indices of the non-zero
                 block entries of A. Unchanged on exit.

BNNZ (input)    On entry, integer BNNZ specifies the number of nonzero
                 block entries in A. Unchanged on exit.

LB (input)      On entry, integer LB specifies the dimension of dense
                 blocks composing A. Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading kb*lb by n
                 part of the array B must contain the matrix B, otherwise
                 the leading mb*lb by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading mb*lb by n
                 part of the array C must contain the matrix C, otherwise
                 the leading kb*lb by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta * C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

The all sparse blas matrix-matrix multiply routines for block entry formats are designed so that if *DESCRA*(1) > 0, the routines check the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use just one sparse matrix representation of a general block matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A .

Assume that there is the sparse matrix representation of a general real matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of *DESCRA* and the result matrix for the sparse representation of A is

<i>DESCRA</i> (1)	<i>DESCRA</i> (2)	<i>DESCRA</i> (3)	RESULT
1 or 2	1	0	$\alpha * \text{op}(L+D+L') * B + \beta * C$
1 or 2	1	1	$\alpha * \text{op}(L+I+L') * B + \beta * C$
1 or 2	2	0	$\alpha * \text{op}(U'+D+U) * B + \beta * C$
1 or 2	2	1	$\alpha * \text{op}(U'+I+U) * B + \beta * C$
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$

3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$
4 or 6	1	0 or 1	$\alpha * \text{op}(L+D-L') * B + \beta * C$
4 or 6	2	0 or 1	$\alpha * \text{op}(U+D-U') * B + \beta * C$
5	1 or 2	0	$\alpha * \text{op}(D) * B + \beta * C$
5	1 or 2	1	$\alpha * B + \beta * C$

Remarks to the table:

1. the value of `DESCRA(3)` is simply ignored , if `DESCRA(1)=4 or 6` but the diagonal blocks which are referenced in the sparse matrix representation are used;
2. the diagonal blocks which are referenced in the sparse matrix representation are not used, if `DESCRA(3)=1` and `DESCRA(1)` is one of 1, 2, 3 or 5;
3. if `DESCRA(3)` is not 1 and `DESCRA(1)` is one of 1,2, 4 or 6, the type of D should correspond to the choosen value of `DESCRA(1)` .

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NAME

sbdim - block diagonal format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SBDIMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
* VAL, BLDA, IBDIAG, NBDIAG, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, MB, N, KB, DESCRA(5), BLDA, NBDIAG, LB,  
* LDB, LDC, LWORK  
INTEGER IBDIAG(NBDIAG)  
REAL ALPHA, BETA  
REAL VAL(LB*LB*BLDA*NBDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SBDIMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
* VAL, BLDA, IBDIAG, NBDIAG, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, MB, N, KB, DESCRA(5), BLDA, NBDIAG, LB,  
* LDB, LDC, LWORK  
INTEGER*8 IBDIAG(NBDIAG)  
REAL ALPHA, BETA  
REAL VAL(LB*LB*BLDA*NBDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BDIMM(TRANSA,MB, [N], KB, ALPHA, DESCRA, VAL, BLDA,  
* IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, MB, KB, BLDA, NBDIAG, LB  
INTEGER, DIMENSION(:) :: DESCRA, IBDIAG  
REAL ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BDIMM_64(TRANSA,MB, [N], KB, ALPHA, DESCRA, VAL, BLDA,  
* IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, MB, KB, BLDA, NBDIAG, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, IBDIAG  
REAL ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void sbdimm (int transa, int mb, int n, int kb, float alpha,
  int *descra, float *val, int blda, int *ibdiag, int nbdiag,
  int lb, float *b, int ldb, float *beta, float *c, int ldc);

void sbdimm_64(long transa, long mb, long n, long kb,
  float alpha, long *descra, float *val, long blda,
  long *ibdiag, long nbdiag, long lb, float *b, long ldb,
  float *beta, float *c, long ldc);
```

DESCRIPTION

sbdimm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an $(mb \times lb)$ by $(kb \times lb)$ sparse matrix represented in the block coordinate format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric ($A=A'$)
2 : Hermitian ($A= \operatorname{CONJG}(A')$)
3 : Triangular
4 : Skew(Anti)-Symmetric ($A=-A'$)
5 : Diagonal
6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$)

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, two-dimensional LB*LB*BLDA-by-NBDIAG array consisting of the NBDIAG nonzero block diagonal in any order. Each dense block is stored in standard column-major form. Unchanged on exit.

BLDA(input) On entry, BLDA*LB*LB specifies the leading block dimension of VAL(). Unchanged on exit.

IBDIAG(input) On entry, integer array of length NBDIAG consisting of the corresponding diagonal offsets of the non-zero block diagonals of A in VAL. Lower triangular block diagonals have negative offsets, the main block diagonal has offset 0, and upper triangular block diagonals have positive offset. Unchanged on exit.

NBDIAG(input) On entry, NBDIAG specifies the number of non-zero block diagonals in A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the sbcomm manpage.

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NAME

sbdism - block diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE SBDISM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, BLDA, IBDIAG, NBDIAG, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, MB, N, UNITD, DESCRA(5), BLDA, NBDIAG, LB,  
* LDB, LDC, LWORK  
INTEGER IBDIAG(NBDIAG)  
REAL ALPHA, BETA  
REAL DV(MB*LB*LB), VAL(LB*LB*BLDA, NBDIAG), B(LDB,*), C(LDC,*),  
* WORK(LWORK)
```

```
SUBROUTINE SBDISM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, BLDA, IBDIAG, NBDIAG, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, MB, N, UNITD, DESCRA(5), BLDA, NBDIAG, LB,  
* LDB, LDC, LWORK  
INTEGER*8 IBDIAG(NBDIAG)  
REAL ALPHA, BETA  
REAL DV(MB*LB*LB), VAL(LB*LB*BLDA, NBDIAG), B(LDB,*), C(LDC,*),  
* WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BDISM( TRANSA, MB,[N], UNITD, DV, ALPHA, DESCRA, VAL, BLDA,  
* IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, MB, N, UNITD, BLDA, NBDIAG, LB  
INTEGER, DIMENSION(:) :: DESCRA, IBDIAG  
REAL ALPHA, BETA  
REAL, DIMENSION(:) :: VAL, DV  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BDISM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BLDA,  
* IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, MB, N, UNITD, BLDA, NBDIAG, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, IBDIAG  
REAL ALPHA, BETA
```

```
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sbdism (int transa, int mb, int n, int unitd, float
*dv, float alpha, int *descra, float *val, int blda, int
*ibdiag, int nbdiag, int lb, float *b, int ldb, float beta,
float *c, int ldc);
void sbdism_64(long transa, long mb, long n, long unitd,
float *dv, float alpha, long *descra, float *val, long blda,
long *ibdiag, long nbdiag, long lb, float *b, long ldb,
float beta, float *c, long ldc);
```

DESCRIPTION

sbdism performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose)
```

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in matrix the A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) Unchanged on exit.
DV(input)	On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-NBDIAG array consisting of the NBDIAG non-zero block diagonal. Each dense block is stored in standard column-major form. Unchanged on exit.

BLDA(input) On entry, BLDA*LB*LB specifies the leading block dimension of VAL(). Unchanged on exit.

IBDIAG(input) On entry, IBDIAG is an integer array of length NBDIAG consisting of corresponding diagonal offsets of the non-zero block diagonals of A in VAL. Lower triangular block diagonals have negative offsets, the main block diagonal has offset 0, and upper triangular block diagonals have positive offset. Elements of IBDIAG MUST be sorted in increasing order. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block diagonal representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If *DESCRA*(3)=2 , diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine.

WORK(1)=0 on return if the factorization for all diagonal

blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix `A` for solving triangular systems with the upper or lower block triangle of `A`. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix `A` decomposed in the form

$$A = L + D + U$$

where `L` is the strictly block lower triangle of `A`, `U` is the strictly block upper triangle of `A`, `D` is the block diagonal matrix. Let's `I` denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of `A` is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

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NAME

sbdsdc - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B

SYNOPSIS

```
SUBROUTINE SBSDSC(UPLO, COMPQ, N, D, E, U, LDU, VT, LDVT, Q, IQ,  
  WORK, IWORK, INFO)
```

```
CHARACTER * 1 UPLO, COMPQ  
INTEGER N, LDU, LDVT, INFO  
INTEGER IQ(*), IWORK(*)  
REAL D(*), E(*), U(LDU,*), VT(LDVT,*), Q(*), WORK(*)
```

```
SUBROUTINE SBSDSC_64(UPLO, COMPQ, N, D, E, U, LDU, VT, LDVT, Q, IQ,  
  WORK, IWORK, INFO)
```

```
CHARACTER * 1 UPLO, COMPQ  
INTEGER*8 N, LDU, LDVT, INFO  
INTEGER*8 IQ(*), IWORK(*)  
REAL D(*), E(*), U(LDU,*), VT(LDVT,*), Q(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE BDSDC(UPLO, COMPQ, [N], D, E, U, [LDU], VT, [LDVT], Q, IQ,  
  [WORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, COMPQ  
INTEGER :: N, LDU, LDVT, INFO  
INTEGER, DIMENSION(:) :: IQ, IWORK  
REAL, DIMENSION(:) :: D, E, Q, WORK  
REAL, DIMENSION(:,) :: U, VT
```

```
SUBROUTINE BDSDC_64(UPLO, COMPQ, [N], D, E, U, [LDU], VT, [LDVT], Q,  
  IQ, [WORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, COMPQ  
INTEGER(8) :: N, LDU, LDVT, INFO  
INTEGER(8), DIMENSION(:) :: IQ, IWORK  
REAL, DIMENSION(:) :: D, E, Q, WORK
```

```
REAL, DIMENSION(:, :) :: U, VT
```

C INTERFACE

```
#include <sunperf.h>

void sbdsdc(char uplo, char compq, int n, float *d, float
            *e, float *u, int ldu, float *vt, int ldvt, float
            *q, int *iq, int *info);
void sbdsdc_64(char uplo, char compq, long n, float *d,
               float *e, float *u, long ldu, float *vt, long
               ldvt, float *q, long *iq, long *info);
```

PURPOSE

sbdsdc computes the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B: $B = U * S * VT$, using a divide and conquer method, where S is a diagonal matrix with non-negative diagonal elements (the singular values of B), and U and VT are orthogonal matrices of left and right singular vectors, respectively. SBDSDC can be used to compute all singular values, and optionally, singular vectors or singular vectors in compact form.

This code makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none. See SLASD3 for details.

The code currently call SLASDQ if singular values only are desired. However, it can be slightly modified to compute singular values using the divide and conquer method.

ARGUMENTS

UPLO (input)

= 'U': B is upper bidiagonal.
= 'L': B is lower bidiagonal.

COMPQ (input)

Specifies whether singular vectors are to be computed as follows:
= 'N': Compute singular values only;
= 'P': Compute singular values and compute singular vectors in compact form; = 'I': Compute singular values and singular vectors.

N (input) The order of the matrix B. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the bidiagonal matrix B. On exit, if INFO=0, the singular values of B.

E (input/output)

On entry, the elements of E contain the offdiagonal elements of the bidiagonal matrix whose SVD is desired. On exit, E has been destroyed.

U (output)

If COMPQ = 'I', then: On exit, if INFO = 0, U contains the left singular vectors of the bidiagonal matrix. For other values of COMPQ, U is not referenced.

LDU (input)

The leading dimension of the array U. LDU >= 1. If singular vectors are desired, then LDU >= max(1, N).

VT (output)

If COMPQ = 'I', then: On exit, if INFO = 0, VT contains the right singular vectors of the bidiagonal matrix. For other values of COMPQ, VT is not referenced.

LDVT (input)

The leading dimension of the array VT. LDVT >= 1. If singular vectors are desired, then LDVT >= max(1, N).

Q (input) If COMPQ = 'P', then: On exit, if INFO = 0, Q and IQ contain the left and right singular vectors in a compact form, requiring $O(N \log N)$ space instead of $2*N**2$. In particular, Q contains all the REAL data in LDQ >= $N*(11 + 2*SMLSIZ + 8*INT(LOG_2(N/(SMLSIZ+1))))$ words of memory, where SMLSIZ is returned by ILAENV and is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25). For other values of COMPQ, Q is not referenced.

IQ (output)

If COMPQ = 'P', then: On exit, if INFO = 0, Q and IQ contain the left and right singular vectors in a compact form, requiring $O(N \log N)$ space instead of $2*N**2$. In particular, IQ contains all INTEGER data in LDIQ >= $N*(3 + 3*INT(LOG_2(N/(SMLSIZ+1))))$ words of memory, where SMLSIZ is returned by ILAENV and is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25). For other values of COMPQ, IQ is not referenced.

WORK (workspace)

If COMPQ = 'N' then LWORK >= (2 * N). If COMPQ = 'P' then LWORK >= (6 * N). If COMPQ = 'I' then LWORK >= (3 * N**2 + 4 * N).

IWORK (workspace)

dimension(8*N)

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: The algorithm failed to compute an singular value. The update process of divide and conquer failed.

FURTHER DETAILS

Based on contributions by
Ming Gu and Huan Ren, Computer Science Division, Univer-
sity of
California at Berkeley, USA

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NAME

sbdsqr - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B.

SYNOPSIS

```
SUBROUTINE SBDSQR(UPLO, N, NCVT, NRU, NCC, D, E, VT, LDVT, U, LDU, C,
                 LDC, WORK, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL D(*), E(*), VT(LDVT,*), U(LDU,*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SBDSQR_64(UPLO, N, NCVT, NRU, NCC, D, E, VT, LDVT, U, LDU,
                    C, LDC, WORK, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER*8 N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL D(*), E(*), VT(LDVT,*), U(LDU,*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE BDSQR(UPLO, [N], [NCVT], [NRU], [NCC], D, E, VT, [LDVT],
                U, [LDU], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER :: N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL, DIMENSION(:) :: D, E, WORK
REAL, DIMENSION(:, :) :: VT, U, C
```

```
SUBROUTINE BDSQR_64(UPLO, [N], [NCVT], [NRU], [NCC], D, E, VT, [LDVT],
                   U, [LDU], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER(8) :: N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO
REAL, DIMENSION(:) :: D, E, WORK
REAL, DIMENSION(:, :) :: VT, U, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sbdsqr(char uplo, int n, int ncv, int nru, int ncc,
```

```

float *d, float *e, float *vt, int ldvt, float *u,
int ldu, float *c, int ldc, int *info);

void sbdsqr_64(char uplo, long n, long ncv, long nru, long
ncc, float *d, float *e, float *vt, long ldvt,
float *u, long ldu, float *c, long ldc, long
*info);

```

PURPOSE

sbdsqr computes the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B: $B = Q * S * P'$ (P' denotes the transpose of P), where S is a diagonal matrix with non-negative diagonal elements (the singular values of B), and Q and P are orthogonal matrices.

The routine computes S, and optionally computes $U * Q$, $P' * VT$, or $Q' * C$, for given real input matrices U, VT, and C.

See "Computing Small Singular Values of Bidiagonal Matrices With Guaranteed High Relative Accuracy," by J. Demmel and W. Kahan, LAPACK Working Note #3 (or SIAM J. Sci. Statist. Comput. vol. 11, no. 5, pp. 873-912, Sept 1990) and "Accurate singular values and differential qd algorithms," by B. Parlett and V. Fernando, Technical Report CPAM-554, Mathematics Department, University of California at Berkeley, July 1992 for a detailed description of the algorithm.

ARGUMENTS

UPLO (input)

= 'U': B is upper bidiagonal;
= 'L': B is lower bidiagonal.

N (input) The order of the matrix B. $N \geq 0$.

NCVT (input)

The number of columns of the matrix VT. $NCVT \geq 0$.

NRU (input)

The number of rows of the matrix U. $NRU \geq 0$.

NCC (input)

The number of columns of the matrix C. $NCC \geq 0$.

D (input/output)

On entry, the n diagonal elements of the bidiagonal matrix B. On exit, if INFO=0, the singular values of B in decreasing order.

E (input/output)

On entry, the elements of E contain the offdiagonal elements of the bidiagonal matrix whose SVD is desired. On normal exit (INFO = 0), E is destroyed. If the algorithm does not converge (INFO > 0), D and E will contain the diagonal and

superdiagonal elements of a bidiagonal matrix orthogonally equivalent to the one given as input. E(N) is used for workspace.

VT (input/output)

On entry, an N-by-NCVT matrix VT. On exit, VT is overwritten by $P' * VT$. VT is not referenced if NCVT = 0.

LDVT (input)

The leading dimension of the array VT. LDVT \geq max(1,N) if NCVT > 0; LDVT \geq 1 if NCVT = 0.

U (input/output)

On entry, an NRU-by-N matrix U. On exit, U is overwritten by $U * Q$. U is not referenced if NRU = 0.

LDU (input)

The leading dimension of the array U. LDU \geq max(1,NRU).

C (input/output)

On entry, an N-by-NCC matrix C. On exit, C is overwritten by $Q' * C$. C is not referenced if NCC = 0.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,N) if NCC > 0; LDC \geq 1 if NCC = 0.

WORK (workspace)

dimension(4*N)

INFO (output)

= 0: successful exit
< 0: If INFO = -i, the i-th argument had an illegal value
> 0: the algorithm did not converge; D and E contain the elements of a bidiagonal matrix which is orthogonally similar to the input matrix B; if INFO = i, i elements of E have not converged to zero.

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NAME

sbelmm - block Ellpack format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SBELMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BLDA, MAXBNZ, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), BLDA, MAXBNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BLDA,MAXBNZ)  
REAL             ALPHA, BETA  
REAL             VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SBELMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BLDA, MAXBNZ, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), BLDA, MAXBNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER*8        BINDX(BLDA,MAXBNZ)  
REAL             ALPHA, BETA  
REAL             VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BELMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                BLDA, MAXBNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, BLDA, MAXBNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX  
REAL             ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BELMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BLDA, MAXBNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, BLDA, MAXBNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX  
REAL             ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void sbelmm (int transa, int mb, int n, int kb,
  float alpha, int *descra, float *val,
  int *bindx, int blda, int maxbnz, int lb, float *b, int
  ldb, float beta, float *c, int ldc);
void sbelmm_64(long transa, long mb, long n, long kb, float
  alpha, long *descra, float *val, long *bindx, long blda,
  long maxbnz, long lb, float *b, long ldb, float beta, float
  *c, long ldc);
```

DESCRIPTION

sbelmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in block Ellpack format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input) TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows:
 0 : operate with matrix
 1 : operate with transpose matrix
 2 : operate with the conjugate transpose of matrix.
 2 is equivalent to 1 if matrix is real.
 Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator

1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-MAXBNZ array consisting of the non-zero blocks, stored column-major within each dense block. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer two-dimensional BLDA-MAXBNZ array such BINDX(i,:) consists of the block column indices of the nonzero blocks in block row i, padded by the integer value i if the number of nonzero blocks is less than MAXBNZ. Unchanged on exit.

BLDA(input) On entry, BLDA specifies the leading dimension of BINDX(:,:). Unchanged on exit.

MAXBNZ (input) On entry, NBDIAG specifies the max number of nonzeros blocks per row. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANS = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANS = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * op(A) * B + \beta * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the sbcomm manpage.

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NAME

sbelsm - block Ellpack format triangular solve

SYNOPSIS

```
SUBROUTINE SBELSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BLDA, MAXBNZ, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), BLDA, MAXBNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BLDA,MAXBNZ)  
REAL             ALPHA, BETA  
REAL             DV(MB*LB*LB), VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*),  
*                WORK(LWORK)
```

```
SUBROUTINE SBELSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BLDA, MAXBNZ, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), BLDA, MAXBNZ, LB,  
*               LDB, LDC, LWORK  
INTEGER*8        BINDX(BLDA,MAXBNZ)  
REAL             ALPHA, BETA  
REAL             DV(MB*LB*LB), VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*),  
*               WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BELSM( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*               BLDA, MAXBNZ, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, UNITD, BLDA, MAXBNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX  
REAL             ALPHA, BETA  
REAL, DIMENSION(:) :: VAL, DV  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BELSM_64( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                   BLDA, MAXBNZ, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, UNITD, BLDA, MAXBNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX  
REAL             ALPHA, BETA
```

```
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sbelsm (int transa, int mb, int n, int unitd,
             float *dv, float alpha, int *descra, float *val,
             int *bindx, int blda, int maxbnz, int lb, float *b, int
             ldb, float beta, float *c, int ldc);
void sbelsm_64(long transa, long mb, long n, long unitd,
               float *dv, float alpha, long *descra, float *val, long
               *bindx, long blda, long maxbnz, long lb, float *b, long
               ldb, float beta, float *c, long ldc);
```

DESCRIPTION

sbelsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block ellpack format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input) Integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-MAXBNZ array consisting of the non-zero blocks, stored column-major within each dense block. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer two-dimensional BLDA-MAXBNZ array such BINDX(i,:) consists of the block column indices of the nonzero blocks in block row i, padded by the integer value i if the number of nonzero blocks is less than MAXBNZ. The block column indices MUST be sorted in increasing order for each block row. Unchanged on exit.

BLDA(input) On entry, BLDA specifies the leading dimension of BINDX(:,:). Unchanged on exit.

MAXBNZ (input) On entry, MAXBNZ specifies the max number of nonzeros blocks per row. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block ellpack representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If *DESCRA*(3)=2 , diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine.

WORK(1)=0 on return if the factorization for all diagonal blocks has been completed successfully, otherwise *WORK*(1) = - i where i is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But *DESCRA*(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of *DESCRA* and the result matrix for the sparse representation of A is

<i>DESCRA</i> (1)	<i>DESCRA</i> (2)	<i>DESCRA</i> (3)	RESULT
3	1	1	alpha*op(L+I)*B+beta*C
3	1	0	alpha*op(L+D)*B+beta*C
3	2	1	alpha*op(U+I)*B+beta*C
3	2	0	alpha*op(U+D)*B+beta*C

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NAME

sbscmm - block sparse column matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SBSCMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(KB), BPNTRE(KB)  
REAL             ALPHA, BETA  
REAL             VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SBSCMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(KB), BPNTRE(KB)  
REAL             ALPHA, BETA  
REAL             VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(KB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSCMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*               BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, KB, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
REAL          ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSCMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, KB, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
REAL          ALPHA, BETA
```

```

REAL, DIMENSION(:) :: VAL
REAL, DIMENSION(:, :) :: B, C

```

C INTERFACE

```
#include <sunperf.h>
```

```

void sbscmm(int transa, int mb, int n, int kb,
float alpha, int *descra, float *val,
int *bindx, int *bpntrb, int *bpntre, int lb, float *b,
int ldb, float beta, float *c, int ldc);
void sbscmm_64(long transa, long mb, long n, long kb, float
alpha, long *descra, float *val, long *bindx, long *bpntrb,
long *bpntre, long lb, float *b, long ldb, float beta,
float *c, long ldc);

```

DESCRIPTION

sbscmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in the block sparse column format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
KB(input)	On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular 4 : Skew(Anti)-Symmetric (A=-A') 5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ consisting of the non-zero block entries stored column-major within each dense block where BNNZ = BPNTRE(KB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block row indices of the block entries of A where BNNZ = BPNTRE(KB)-BPNTRB(1). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length KB such that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the J-th block column of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length KB such that BPNTRE(J)-BPNTRB(1) points to location in BINDX of the last block entry of the J-th block column of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta * C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the sbcomm manpage.

NOTES/BUGS

It is known that there exists another representation of the block sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block column in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse column format the following calling sequence should be used

```
CALL SBSCMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*           VAL, BINDX, IA, IA(2), LB,  
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

sbscsm - block sparse column format triangular solve

SYNOPSIS

```
SUBROUTINE SBSCSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
REAL             ALPHA, BETA  
REAL             DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SBSCSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
REAL             ALPHA, BETA  
REAL             DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB) - BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSCSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*              BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, N, UNITD, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
REAL          ALPHA, BETA  
REAL, DIMENSION(:) :: VAL, DV  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSCSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                  BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, N, UNITD, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
REAL          ALPHA, BETA
```

```
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sbscsm(int transa, int mb, int n, int unitd,
float *dv, float alpha, int *descra, float *val,
int *bindx, int *bpntrb, int *bpntre, int lb, float *b,
int ldb, float beta, float* c, int ldc);
void sbscsm_64(long transa, long mb, long n, long unitd,
float *dv, float alpha, long *descra, float *val, long
*bindx, long *bpntrb, long *bpntre, long lb, float *b, long
ldb, float beta, float *c, long ldc);
```

DESCRIPTION

sbscsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block sparse column format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block columns in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ
consisting of the non-zero block entries stored
column-major within each dense block where
BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting
of the block row indices of the block entries of A where
BNNZ = BPNTRE(MB)-BPNTRB(1). The block row indices MUST
be sorted in increasing order for each block column.
Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such
that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX
of the first block entry of the J-th block column
of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such
that BPNTRE(J)-BPNTRB(1) points to location in BINDX
of the last block entry of the J-th block column
of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks
composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
 On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block sparse column representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.

4. If `DESCRA(3)=2` , the diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

6. It is known that there exists another representation of the block sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, `IA`, containing the pointers to the beginning of each block column in the arrays `VAL` and `BINDX` is used instead of two arrays `BPNTRB` and `BPNTRE`. To use the routine with this kind of block sparse column format the following calling sequence should be used

```
CALL SBSCSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*           VAL, BINDX, IA, IA(2), LB,
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

sbsrmm - block sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SBSRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
REAL             ALPHA, BETA  
REAL             VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SBSRMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
REAL             ALPHA, BETA  
REAL             VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSRMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*               BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
REAL             ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSRMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
REAL             ALPHA, BETA
```

```
REAL, DIMENSION(:) :: VAL
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sbsrmm(int transa, int mb, int n, int kb,
float alpha, int *descra, float *val, int *bindx,
int *bpntrb, int *bpntre, int lb, float *b,
int ldb, float beta, float *c, int ldc);
void sbsrmm_64(long transa, long mb, long n, long kb, float
alpha, long *descra, float *val, long *bindx, long *bpntrb,
long *bpntre, long lb, float *b, long ldb, float beta,
float *c, long ldc);
```

DESCRIPTION

sbsrmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in the block sparse row format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
KB(input)	On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular 4 : Skew(Anti)-Symmetric (A=-A') 5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ consisting of the non-zero block entries stored column-major within each dense block where BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the J-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(J)-BPNTRB(1) points to location in BINDX of the last block entry of the J-th block row of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta * C).

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the sbcomm manpage.

NOTES/BUGS

It is known that there exists another representation of the block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse row format the following calling sequence should be used

```
CALL SBSRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*           VAL, BINDX, IA, IA(2), LB,  
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

sbsrsm - block sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE SBSRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
REAL             ALPHA, BETA  
REAL             DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SBSRSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
REAL             ALPHA, BETA  
REAL             DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSRSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*               BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, N, UNITD, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
REAL          ALPHA, BETA  
REAL, DIMENSION(:) :: VAL, DV  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSRSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, N, UNITD, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
REAL          ALPHA, BETA
```

```
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sbsrsm(int transa, int mb, int n, int unitd,
float *dv, float alpha, int *descra, float *val,
int *bindx, int *bpntrb, int *bpntre, int lb, float *b,
int ldb, float beta, float* c, int ldc);
void sbsrsm_64(long transa, long mb, long n, long unitd,
float *dv, float alpha, long *descra, float *val, long
*bindx, long *bpntrb, long *bpntre, long lb, float *b, long
ldb, float beta, float *c, long ldc);
```

DESCRIPTION

sbsrsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block sparse row format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form.

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-identity blocks on the main diagonal
 1 : identity diagonal blocks
 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ
consisting of the non-zero block entries stored
column-major within each dense block where
BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting
of the block column indices of the block entries of A where
BNNZ = BPNTRE(MB)-BPNTRB(1). The block column indices MUST
be sorted in increasing order for each block column.
Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such
that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX
of the first block entry of the J-th block row
of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such
that BPNTRE(J)-BPNTRB(1) points to location in BINDX
of the last block entry of the J-th block row
of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks
composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 On entry, the leading mb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
 On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK >=MB*LB*N_CPUS where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If *DESCRA*(3)=0 , the lower or upper triangular part of each diagonal block is used by the routine depending on *DESCRA*(2) .
3. If *DESCRA*(3)=1 , the diagonal blocks in the block sparse row representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.

4. If `DESCRA(3)=2` , the diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

6. It is known that there exists another representation of the block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, `IA`, containing the pointers to the beginning of each block row in the arrays `VAL` and `BINDX` is used instead of two arrays `BPNTRB` and `BPNTRE`. To use the routine with this kind of block sparse row format the following calling sequence should be used

```
CALL SBSRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*           VAL, BINDX, IA, IA(2), LB,
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

scasum - Return the sum of the absolute values of a vector x.

SYNOPSIS

```
REAL FUNCTION SCASUM(N, X, INCX)
```

```
COMPLEX X(*)  
INTEGER N, INCX
```

```
REAL FUNCTION SCASUM_64(N, X, INCX)
```

```
COMPLEX X(*)  
INTEGER*8 N, INCX
```

F95 INTERFACE

```
REAL FUNCTION ASUM([N], X, [INCX])
```

```
COMPLEX, DIMENSION(:) :: X  
INTEGER :: N, INCX
```

```
REAL FUNCTION ASUM_64([N], X, [INCX])
```

```
COMPLEX, DIMENSION(:) :: X  
INTEGER(8) :: N, INCX
```

C INTERFACE

```
#include <sunperf.h>
```

```
float scasum(int n, complex *x, int incx);
```

```
float scasum_64(long n, complex *x, long incx);
```

PURPOSE

scasum Return the sum of the absolute values of the elements of x where x is an n-vector. This is the sum of the abso-

lute values of the real and complex elements and not the sum of the squares of the real and complex elements.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero or negative. Unchanged on exit.

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NAME

scnrm2 - Return the Euclidian norm of a vector.

SYNOPSIS

```
REAL FUNCTION SCNRM2(N, X, INCX)
```

```
COMPLEX X(*)  
INTEGER N, INCX
```

```
REAL FUNCTION SCNRM2_64(N, X, INCX)
```

```
COMPLEX X(*)  
INTEGER*8 N, INCX
```

F95 INTERFACE

```
REAL FUNCTION NRM2([N], X, [INCX])
```

```
COMPLEX, DIMENSION(:) :: X  
INTEGER :: N, INCX
```

```
REAL FUNCTION NRM2_64([N], X, [INCX])
```

```
COMPLEX, DIMENSION(:) :: X  
INTEGER(8) :: N, INCX
```

C INTERFACE

```
#include <sunperf.h>
```

```
float scnrm2(int n, complex *x, int incx);
```

```
float scnrm2_64(long n, complex *x, long incx);
```

PURPOSE

scnrm2 Return the Euclidian norm of a vector x where x is an n-vector.

ARGUMENTS

- N (input)
On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.
- X (input)
(1 + (n - 1) * abs(INCX)). On entry, the incremented array X must contain the vector x. Unchanged on exit.
- INCX (input)
On entry, INCX specifies the increment for the elements of X. If INCX < 1 then SCNRM2 returns 0. Unchanged on exit.

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NAME

scnvcor - compute the convolution or correlation of real vectors

SYNOPSIS

```
SUBROUTINE SCNVCOR(CNVCOR, FOUR, NX, X, IFX, INCX, NY, NPRE, M, Y,
  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, FOUR
INTEGER NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y, NZ,
K, IFZ, INC1Z, INC2Z, LWORK
REAL X(*), Y(*), Z(*), WORK(*)
```

```
SUBROUTINE SCNVCOR_64(CNVCOR, FOUR, NX, X, IFX, INCX, NY, NPRE, M, Y,
  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, FOUR
INTEGER*8 NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y, NZ,
K, IFZ, INC1Z, INC2Z, LWORK
REAL X(*), Y(*), Z(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE CNVCOR(CNVCOR, FOUR, [NX], X, IFX, [INCX], NY, NPRE, M, Y,
  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, FOUR
INTEGER :: NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y,
NZ, K, IFZ, INC1Z, INC2Z, LWORK
REAL, DIMENSION(:) :: X, Y, Z, WORK
```

```
SUBROUTINE CNVCOR_64(CNVCOR, FOUR, [NX], X, IFX, [INCX], NY, NPRE, M,
  Y, IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, FOUR
INTEGER(8) :: NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y,
NZ, K, IFZ, INC1Z, INC2Z, LWORK
REAL, DIMENSION(:) :: X, Y, Z, WORK
```

C INTERFACE

```
#include <sunperf.h>

void scnvcor(char cnvcor, char four, int nx, float *x, int
    ifx, int incx, int ny, int npre, int m, float *y,
    int ify, int inclx, int inc2y, int nz, int k,
    float *z, int ifz, int inclz, int inc2z, float
    *work, int lwork);
void scnvcor_64(char cnvcor, char four, long nx, float *x,
    long ifx, long incx, long ny, long npre, long m,
    float *y, long ify, long inclx, long inc2y, long
    nz, long k, float *z, long ifz, long inclz, long
    inc2z, float *work, long lwork);
```

PURPOSE

scnvcor computes the convolution or correlation of real vectors.

ARGUMENTS

CNVCOR (input)

'V' or 'v' if convolution is desired, 'R' or 'r' if correlation is desired.

FOUR (input)

'T' or 't' if the Fourier transform method is to be used, 'D' or 'd' if the computation should be done directly from the definition. The Fourier transform method is generally faster, but it may introduce noticeable errors into certain results, notably when both the filter and data vectors consist entirely of integers or vectors where elements of either the filter vector or a given data vector differ significantly in magnitude from the 1-norm of the vector.

NX (input)

Length of the filter vector. NX >= 0. SCNVCOR will return immediately if NX = 0.

X (input)

Filter vector.

IFX (input)

Index of the first element of X. NX >= IFX >= 1.

INCX (input)

Stride between elements of the filter vector in X. INCX > 0.

NY (input)

Length of the input vectors. NY >= 0. SCNVCOR will return immediately if NY = 0.

NPRES (input)

The number of implicit zeros prepended to the Y

vectors. NPRE \geq 0.

M (input)
 Number of input vectors. M \geq 0. SCNVCOR will return immediately if M = 0.

Y (input)
 Input vectors.

IFY (input)
 Index of the first element of Y. NY \geq IFY \geq 1.

INC1Y (input)
 Stride between elements of the input vectors in Y. INC1Y $>$ 0.

INC2Y (input)
 Stride between the input vectors in Y. INC2Y $>$ 0.

NZ (input)
 Length of the output vectors. NZ \geq 0. SCNVCOR will return immediately if NZ = 0. See the Notes section below for information about how this argument interacts with NX and NY to control circular versus end-off shifting.

K (input)
 Number of Z vectors. K \geq 0. If K = 0 then SCNVCOR will return immediately. If K $<$ M then only the first K input vectors will be processed. If K $>$ M then M input vectors will be processed.

Z (output)
 Result vectors.

IFZ (input)
 Index of the first element of Z. NZ \geq IFZ \geq 1.

INC1Z (input)
 Stride between elements of the output vectors in Z. INC1Z $>$ 0.

INC2Z (input)
 Stride between the output vectors in Z. INC2Z $>$ 0.

WORK (input/output)
 Scratch space. Before the first call to SCNVCOR with particular values of the integer arguments the first element of WORK must be set to zero. If WORK is written between calls to SCNVCOR or if SCNVCOR is called with different values of the integer arguments then the first element of WORK must again be set to zero before each call. If WORK has not been written and the same values of the integer arguments are used then the first element of WORK to zero. This can avoid certain initializations that store their results into WORK, and avoiding the initialization can make SCNVCOR run faster.

LWORK (input)

Length of WORK. LWORK $\geq 4 \cdot \max(NX, NPRE + NY, NZ) + 15$.

NOTES

If any vector overlaps a writable vector, either because of argument aliasing or ill-chosen values of the various INC arguments, the results are undefined and may vary from one run to the next.

The most common form of the computation, and the case that executes fastest, is applying a filter vector X to a series of vectors stored in the columns of Y with the result placed into the columns of Z. In that case, $INCX = 1$, $INC1Y = 1$, $INC2Y \geq NY$, $INC1Z = 1$, $INC2Z \geq NZ$. Another common form is applying a filter vector X to a series of vectors stored in the rows of Y and store the result in the row of Z, in which case $INCX = 1$, $INC1Y \geq NY$, $INC2Y = 1$, $INC1Z \geq NZ$, and $INC2Z = 1$.

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NAME

scnvcor2 - compute the convolution or correlation of real matrices

SYNOPSIS

```
SUBROUTINE SCNVCOR2(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, MX, NX, X, LDX, MY, NY, MPRE, NPRE, Y, LDY, MZ, NZ, Z,  
    LDZ, WORKIN, LWORK)
```

```
CHARACTER * 1 CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
SCRATCHY  
COMPLEX WORKIN(*)  
INTEGER MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ, LDZ,  
LWORK  
REAL X(LDX,*), Y(LDY,*), Z(LDZ,*)
```

```
SUBROUTINE SCNVCOR2_64(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, MX, NX, X, LDX, MY, NY, MPRE, NPRE, Y, LDY, MZ, NZ, Z,  
    LDZ, WORKIN, LWORK)
```

```
CHARACTER * 1 CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
SCRATCHY  
COMPLEX WORKIN(*)  
INTEGER*8 MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ, LDZ,  
LWORK  
REAL X(LDX,*), Y(LDY,*), Z(LDZ,*)
```

F95 INTERFACE

```
SUBROUTINE CNVCOR2(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, [MX], [NX], X, [LDX], [MY], [NY], MPRE, NPRE, Y, [LDY],  
    [MZ], [NZ], Z, [LDZ], WORKIN, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, METHOD, TRANSX, SCRATCHX,  
TRANSY, SCRATCHY  
COMPLEX, DIMENSION(:) :: WORKIN  
INTEGER :: MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ,  
LDZ, LWORK  
REAL, DIMENSION(:,:) :: X, Y, Z
```

```
SUBROUTINE CNVCOR2_64(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,
```

```
SCRATCHY, [MX], [NX], X, [LDX], [MY], [NY], MPRE, NPRE, Y, [LDY],  
[MZ], [NZ], Z, [LDZ], WORKIN, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, METHOD, TRANSX, SCRATCHX,  
TRANSY, SCRATCHY  
COMPLEX, DIMENSION(:) :: WORKIN  
INTEGER(8) :: MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ,  
LDZ, LWORK  
REAL, DIMENSION(:, :) :: X, Y, Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void scnvcor2(char cnvcor, char method, char transx, char  
scratchx, char transy, char scratchy, int mx, int  
nx, float *x, int ldx, int my, int ny, int mpre,  
int npre, float *y, int ldy, int mz, int nz, float  
*z, int ldz, complex *workin, int lwork);
```

```
void scnvcor2_64(char cnvcor, char method, char transx, char  
scratchx, char transy, char scratchy, long mx,  
long nx, float *x, long ldx, long my, long ny,  
long mpre, long npre, float *y, long ldy, long mz,  
long nz, float *z, long ldz, complex *workin, long  
lwork);
```

PURPOSE

scnvcor2 computes the convolution or correlation of real matrices.

ARGUMENTS

CNVCOR (input)

'V' or 'v' to compute convolution, 'R' or 'r' to compute correlation.

METHOD (input)

'T' or 't' if the Fourier transform method is to be used, 'D' or 'd' to compute directly from the definition.

TRANSX (input)

'N' or 'n' if X is the filter matrix, 'T' or 't' if transpose(X) is the filter matrix.

SCRATCHX (input)

'N' or 'n' if X must be preserved, 'S' or 's' if X can be used as scratch space. The contents of X are undefined after returning from a call in which X is allowed to be used for scratch.

TRANSY (input)

'N' or 'n' if Y is the input matrix, 'T' or 't' if transpose(Y) is the input matrix.

SCRATCHY (input)

'N' or 'n' if Y must be preserved, 'S' or 's' if Y can be used as scratch space. The contents of Y are undefined after returning from a call in which Y is allowed to be used for scratch.

MX (input)
Number of rows in the filter matrix. $MX \geq 0$.

NX (input)
Number of columns in the filter matrix. $NX \geq 0$.

X (input) dimension(LDX,NX)
On entry, the filter matrix. Unchanged on exit if SCRATCHX is 'N' or 'n', undefined on exit if SCRATCHX is 'S' or 's'.

LDX (input)
Leading dimension of the array that contains the filter matrix.

MY (input)
Number of rows in the input matrix. $MY \geq 0$.

NY (input)
Number of columns in the input matrix. $NY \geq 0$.

MPRE (input)
Number of implicit zeros to prepend to each row of the input matrix. $MPRE \geq 0$.

NPRE (input)
Number of implicit zeros to prepend to each column of the input matrix. $NPRE \geq 0$.

Y (input) dimension(LDY,*)
Input matrix. Unchanged on exit if SCRATCHY is 'N' or 'n', undefined on exit if SCRATCHY is 'S' or 's'.

LDY (input)
Leading dimension of the array that contains the input matrix.

MZ (input)
Number of rows in the output matrix. $MZ \geq 0$.
SCNVCOR2 will return immediately if $MZ = 0$.

NZ (input)
Number of columns in the output matrix. $NZ \geq 0$.
SCNVCOR2 will return immediately if $NZ = 0$.

Z (output)
dimension(LDZ,*)
Result matrix.

LDZ (input)
Leading dimension of the array that contains the result matrix. $LDZ \geq \text{MAX}(1, MZ)$.

WORKIN (input/output)
(input/scratch) dimension(LWORK)
On entry for the first call to SCNVCOR2,

REAL(WORKIN(1)) must contain 0.0. After the first call, REAL(WORKIN(1)) must be set to 0.0 iff WORKIN has been altered since the last call to this subroutine or if the sizes of the arrays have changed.

LWORK (input)

Length of the work vector. The upper bound of the workspace length requirement is $2 * (MYC + NYC) + 15$, where $MYC = \text{MAX}(\text{MAX}(MX, NX), \text{MAX}(MY, NY) + \text{NPRE})$ and $NYC = \text{MAX}(\text{MAX}(MX, NX), \text{MAX}(MY, NY) + \text{MPRE})$. If LWORK indicates a workspace that is too small, the routine will allocate its own workspace. If the FFT is not used, the value of LWORK is unimportant.

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NAME

scoomm - coordinate matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SCOOMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5), NNZ  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), JNDX(NNZ)  
DOUBLE PRECISION ALPHA, BETA  
DOUBLE PRECISION VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SCOOMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, JNDX, NNZ,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), NNZ  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), JNDX(NNZ)  
REAL             ALPHA, BETA  
REAL             VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE COOMM( TRANSA, M, [N], K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ, B, [LDB], BETA, C, [LDC],  
*                [WORK], [LWORK] )  
INTEGER          TRANSA, M, K, NNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, JNDX  
REAL             ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE COOMM_64( TRANSA, M, [N], K, ALPHA, DESCRA,  
*                   VAL, INDX, JNDX, NNZ, B, [LDB], BETA, C, [LDC],  
*                   [WORK], [LWORK] )  
INTEGER*8        TRANSA, M, K, NNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, JNDX  
REAL             ALPHA, BETA
```

```
REAL, DIMENSION(:) :: VAL
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void scoomm (int transa, int m, int n, int k, float alpha,
int *descra, float *val, int *indx, int *jndx, int nnz,
float *b, int ldb, float beta, float *c, int ldc);
void scoomm_64 (long transa, long m, long n, long k,
float alpha, long *descra, float *val, long *indx,
long *jndx, long nnz, float *b, long ldb,
float beta, float *c, long ldc);
```

DESCRIPTION

scoomm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the coordinate format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.

K(input) On entry, integer K specifies the number of columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array.
DESCRA(1) matrix structure
0 : general
1 : symmetric ($A=A'$)
2 : Hermitian ($A= \operatorname{CONJG}(A')$)
3 : Triangular
4 : Skew(Anti)-Symmetric ($A=-A'$)
5 : Diagonal

```

        6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
        1 : lower
        2 : upper
DESCRA(3) main diagonal type
        0 : non-unit
        1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
        0 : C/C++ compatible
        1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
        0 : unknown
        1 : no repeated indices

VAL (input)    On entry, VAL is a scalar array array of length
                NNZ consisting of the non-zero entries of A,
                in any order. Unchanged on exit.

INDX (input)   On entry, INDX is an integer array of length NNZ
                consisting of the corresponding row indices of
                the entries of A. Unchanged on exit.

JNDX (input)   On entry, JNDX is an integer array of length NNZ
                consisting of the corresponding column indices of
                the entries of A. Unchanged on exit.

NNZ (input)    On entry, integer NNZ specifies the number of
                non-zero elements in A. Unchanged on exit.

B (input)      Array of DIMENSION ( LDB, N ).
                Before entry with TRANSA = 0, the leading k by n
                part of the array B must contain the matrix B, otherwise
                the leading m by n part of the array B must contain the
                matrix B. Unchanged on exit.

LDB (input)    On entry, LDB specifies the first dimension of B as declared
                in the calling (sub) program. Unchanged on exit.

BETA (input)   On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                Before entry with TRANSA = 0, the leading m by n
                part of the array C must contain the matrix C, otherwise
                the leading k by n part of the array C must contain the
                matrix C. On exit, the array C is overwritten by the matrix
                ( alpha*op( A )* B + beta*C ).

LDC (input)    On entry, LDC specifies the first dimension of C as declared
                in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are

implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

The all sparse blas matrix-matrix multiply routines except the skyline and jagged-diagonal format routines are designed so that if *DESCRA*(1) > 0, the routines check the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A .

Assume that there is the sparse matrix representation of a general real matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of *DESCRA* and the result matrix for the sparse representation of A is

<i>DESCRA</i> (1)	<i>DESCRA</i> (2)	<i>DESCRA</i> (3)	RESULT
1 or 2	1	0	$\alpha * \text{op}(L+D+L') * B + \beta * C$
1 or 2	1	1	$\alpha * \text{op}(L+I+L') * B + \beta * C$
1 or 2	2	0	$\alpha * \text{op}(U'+D+U) * B + \beta * C$
1 or 2	2	1	$\alpha * \text{op}(U'+I+U) * B + \beta * C$
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$
4 or 6	1	0 or 1	$\alpha * \text{op}(L-L') * B + \beta * C$

4 or 6	2	0 or 1	$\alpha * \text{op}(U-U') * B + \beta * C$
5	1 or 2	0	$\alpha * \text{op}(D) * B + \beta * C$
5	1 or 2	1	$\alpha * B + \beta * C$

Remarks to the table:

1. the value of `DESCRA(3)` is simply ignored and the diagonal entries given in the sparse matrix representation are not used by the routine, if `DESCRA(1) = 4 or 6`;
2. the diagonal entries are not used also, if `DESCRA(3) = 1` and `DESCRA(1)` is one of 1, 2, 3 or 5;
3. if `DESCRA(3)` is not 1 and `DESCRA(1)` is one of 1, 2, 4 or 6, the type of D should correspond to the chosen value of `DESCRA(1)` .

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NAME

scopy - Copy x to y

SYNOPSIS

```
SUBROUTINE SCOPY(N, X, INCX, Y, INCY)
```

```
INTEGER N, INCX, INCY  
REAL X(*), Y(*)
```

```
SUBROUTINE SCOPY_64(N, X, INCX, Y, INCY)
```

```
INTEGER*8 N, INCX, INCY  
REAL X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE COPY([N], X, [INCX], Y, [INCY])
```

```
INTEGER :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y
```

```
SUBROUTINE COPY_64([N], X, [INCX], Y, [INCY])
```

```
INTEGER(8) :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void scopy(int n, float *x, int incx, float *y, int incy);
```

```
void scopy_64(long n, float *x, long incx, float *y, long  
incy);
```

PURPOSE

scopy Copy x to y where x and y are n-vectors.

ARGUMENTS

- N (input)
On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.
- X (input)
($1 + (n - 1) * \text{abs}(\text{INCX})$). Before entry, the incremented array X must contain the vector x. Unchanged on exit.
- INCX (input)
On entry, INCX specifies the increment for the elements of X. Unchanged on exit.
- Y (output)
($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the vector x.
- INCY (input)
On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

scscmm - compressed sparse column format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SCSCMM( TRANSA, M, N, K, ALPHA, DESCRA,  
* VAL, INDX, PNTRB, PNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, M, N, K, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER INDX(NNZ), PNTRB(K), PNTRE(K)  
REAL ALPHA, BETA  
REAL VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE SCSCMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
* VAL, INDX, PNTRB, PNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, M, N, K, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER*8 INDX(NNZ), PNTRB(K), PNTRE(K)  
REAL ALPHA, BETA  
REAL VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(K)-PNTRB(1)

F95 INTERFACE

```
SUBROUTINE CSCMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
* PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
REAL ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C  
  
SUBROUTINE CSCMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
* PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8 TRANSA, M, K  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
```

```

REAL    ALPHA, BETA
REAL, DIMENSION(:) :: VAL
REAL, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void scscmm(int transa, int m, int n, int k, float alpha,
int *descra, float *val, int *indx, int *pntrb, int *pntre,
float *b, int ldb, float *beta, float *c, int ldc);
void scscmm_64(long transa, long m, long n, long k, float
alpha, long *descra, float *val, long *indx, long *pntrb,
long *pntre, float *b, long ldb, float *beta, float *c, long
ldc);

```

DESCRIPTION

scscmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the compressed sparse column format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
 NNZ = PNTRE(K)-PNTRB(1) consisting of nonzero
 entries of A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
 NNZ = PNTRE(K)-PNTRB(1) consisting of the row
 indices of nonzero entries of A.
 Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length K
 such that PNTRB(J)-PNTRB(1)+1 points to location
 in VAL of the first nonzero element in column J.
 Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length K
 such that PNTRE(J)-PNTRB(1) points to location
 in VAL of the last nonzero element in column J.
 Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise
 the leading k by n part of the array C must contain the
 matrix C. On exit, the array C is overwritten by the matrix
 (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of real sparse matrices is given in the manpage for the scoomm manpage.

NOTES/BUGS

It is known that there exists another representation of the compressed sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each column in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of sparse column format the following calling sequence should be used

```
      SUBROUTINE SCSCMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, IA, IA(2), B, LDB, BETA,  
*                   C, LDC, WORK, LWORK )
```

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NAME

scscsm - compressed sparse column format triangular solve

SYNOPSIS

```
SUBROUTINE SCSCSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER          TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)
REAL             ALPHA, BETA
REAL             DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE SCSCSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)
REAL             ALPHA, BETA
REAL             DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(M)-PNTRB(1)

F95 INTERFACE

```
SUBROUTINE CSCSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )
INTEGER          TRANSA, M, UNITD
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
REAL             ALPHA, BETA
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C

SUBROUTINE CSCSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )
INTEGER*8        TRANSA, M, UNITD
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
REAL             ALPHA, BETA
```

```
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void scscsm(int transa, int m, int n, int unitd,
float *dv, float alpha, int *descra, float *val,
int *indx, int *pntrb, int *pntre, float *b,
int ldb, float beta, float* c, int ldc);
void scscsm_64(long transa, long m, long n, long unitd,
float *dv, float alpha, long *descra, float *val, long
*indx, long *pntrb, long *pntre, float *b, long ldb, float
beta, float *c, long ldc);
```

DESCRIPTION

scscsm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C, \quad C \leftarrow -\alpha D \operatorname{op}(A) B + \beta C,$$
$$C \leftarrow \alpha \operatorname{op}(A) D B + \beta C,$$

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the compressed sparse column format and op(A) is one of

op(A) = inv(A) or op(A) = inv(A') or op(A) = inv(conjg(A'))
(inv denotes matrix inverse, ' indicates matrix transpose).

ARGUMENTS

TRANSA(input) On entry, integer TRANSA indicates how to operate with the sparse matrix:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
4 : Automatic column scaling (see section NOTES for further details)
Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the columns of A have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input) Descriptor argument. Five element integer array:

DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))

Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries of A. If UNITD is 4, VAL contains the scaled matrix A*D (see section NOTES for further details). Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer array of length NNZ = PNTRE(M)-PNTRB(1) consisting of the row indices of nonzero entries of A. Row indices MUST be sorted in increasing order for each column. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such that PNTRB(J)-PNTRB(1)+1 points to location in VAL of the first nonzero element in column J. Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M such that PNTRE(J)-PNTRB(1) points to location in VAL of the last nonzero element in column J. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).

On entry, the leading m by n part of the array C must contain the matrix C . On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M .

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M*N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4, the routine scales the columns of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the columns have been scaled. UNITD=3 should be used for the next calls to the routine with overwritten VAL and DV.

`WORK(1)=0` on return if the scaling has been completed successfully, otherwise `WORK(1) = - i` where `i` is the column number which 2-norm is exactly zero.

3. If `DESCRA(3)=1` and `UNITD < 4`, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the CSC representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if `UNITD=4`, the unit diagonal elements MUST be referenced in the CSC representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

5. It is known that there exists another representation of the compressed sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each column in the arrays VAL and INDX is used instead of two arrays `PNTRB` and `PNTRE`. To use the routine with this kind of sparse column format the following calling sequence should be used

```

SUBROUTINE SCSCSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, IA, IA(2), B, LDB, BETA,
*                 C, LDC, WORK, LWORK )

```

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NAME

scsrmm - compressed sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SCSRMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, PNTRB, PNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)  
REAL             ALPHA, BETA  
REAL             VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE SCSRMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                    VAL, INDX, PNTRB, PNTRE,  
*                    B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)  
REAL             ALPHA, BETA  
REAL             VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(M)-PNTRB(1).

F95 INTERFACE

```
SUBROUTINE CSRMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER          TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
REAL             ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C  
  
SUBROUTINE CSRMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                    PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8        TRANSA, M, K  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
REAL             ALPHA, BETA
```

```
REAL, DIMENSION(:) :: VAL
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void scsrmm(int transa, int m, int n, int k, float alpha,
int *descra, float *val, int *indx, int *pntrb, int *pntre,
float *b, int ldb, float *beta, float *c, int ldc);
void scsrmm_64(long transa, long m, long n, long k, float
alpha, long *descra, float *val, long *indx, long *pntrb,
long *pntre, float *b, long ldb, float *beta, float *c, long
ldc);
```

DESCRIPTION

scsrmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the compressed sparse row format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal 6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$)

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
 NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries
 of A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
 NNZ = PNTRE(M)-PNTRB(1) consisting of the column
 indices of nonzero entries of A. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such
 that PNTRB(J)-PNTRB(1)+1 points to location in VAL
 of the first nonzero element in row J.
 Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M
 such that PNTRE(J)-PNTRB(1) points to location
 in VAL of the last nonzero element in row J.
 Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise
 the leading k by n part of the array C must contain the
 matrix C. On exit, the array C is overwritten by the matrix
 (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible
 with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats is given in section NOTES/BUGS for the scoomm manpage.

NOTES/BUGS

It is known that there exists another representation of the compressed sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each row in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of compressed sparse row format the following calling sequence should be used

```
SUBROUTINE SCSRMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, IA, IA(2), B, LDB, BETA,  
*                C, LDC, WORK, LWORK )
```

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NAME

scsrsm - compressed sparse row format triangular solve

SYNOPSIS

```

SUBROUTINE SCSRSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER          TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)
REAL             ALPHA, BETA
REAL             DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE SCSRSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTRB, PNTRE,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5),
*                LDB, LDC, LWORK
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)
REAL             ALPHA, BETA
REAL             DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

where NNZ = PNTRE(M)-PNTRB(1)
```

F95 INTERFACE

```

SUBROUTINE CSRSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )
INTEGER          TRANSA, M, UNITD
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
REAL             ALPHA, BETA
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C

SUBROUTINE CSRSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )
INTEGER*8        TRANSA, M, UNITD
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
REAL             ALPHA, BETA
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void scsrsm(int transa, int m, int n, int unitd,
  float *dv, float alpha, int *descra, float *val,
  int *indx, int *pntrb, int *pntre, float *b,
  int ldb, float beta, float* c, int ldc);
void scsrsm_64(long transa, long m, long n, long unitd,
  float *dv, float alpha, long *descra, float *val, long
  *indx, long *pntrb, long *pntre, float *b, long ldb, float
  beta, float *c, long ldc);
```

DESCRIPTION

scsrsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the compressed sparse row format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input) On entry, TRANSA indicates how to operate with the sparse matrix:

- 0 : operate with matrix
- 1 : operate with transpose matrix
- 2 : operate with the conjugate transpose of matrix.

2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, UNITD specifies the type of scaling:

- 1 : Identity matrix (argument DV[] is ignored)
- 2 : Scale on left (row scaling)
- 3 : Scale on right (column scaling)
- 4 : Automatic row scaling (see section NOTES for further details)

Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further

details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries
of A. If UNITD is 4, VAL contains the scaled matrix
D*A (see section NOTES for further details).
Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
NNZ = PNTRE(M)-PNTRB(1) consisting of the column
indices of nonzero entries of A. Column indices
MUST be sorted in increasing order for each
row. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such
that PNTRB(J)-PNTRB(1)+1 points to location in VAL
of the first nonzero element in row J.
Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M
such that PNTRE(J)-PNTRB(1) points to location
in VAL of the last nonzero element in row J.
Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C
must contain the matrix C. On exit, the array C is
overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M \cdot N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = - i where i is the row number which 2-norm is exactly zero.

3. If DESCRA(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the CSR representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the CSR representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But DESCRA(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

5. It is known that there exists another representation of the compressed sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each row in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of compressed sparse row format the following calling sequence should be used

```

SUBROUTINE SCSRSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, IA, IA(2), B, LDB, BETA, C,
*                 LDC, WORK, LWORK )

```

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NAME

sdiamm - diagonal format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SDIAMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, LDA, IDIAG, NDIAG,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, K, DESCRA(5), LDA, NDIAG,  
*                LDB, LDC, LWORK  
INTEGER          IDIAG(NDIAG)  
REAL             ALPHA, BETA  
REAL            VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE SDIAMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, LDA, IDIAG, NDIAG,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), LDA, NDIAG,  
*                LDB, LDC, LWORK  
INTEGER*8        IDIAG(NDIAG)  
REAL             ALPHA, BETA
```

F95 INTERFACE

```
SUBROUTINE DIAMM(TRANSA, M, [N], K, ALPHA, DESCRA, VAL, [LDA],  
*  IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, K, NDIAG  
INTEGER, DIMENSION(:) ::  DESCRA, IDIAG  
REAL             ALPHA, BETA  
REAL, DIMENSION(:, :) ::  VAL, B, C
```

```
SUBROUTINE DIAMM_64(TRANSA, M, [N], K, ALPHA, DESCRA, VAL, [LDA],  
*  IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, M, K, NDIAG  
INTEGER*8, DIMENSION(:) ::  DESCRA, IDIAG  
REAL             ALPHA, BETA  
REAL, DIMENSION(:, :) ::  VAL, B, C
```

C INTERFACE

```

#include <sunperf.h>

void sdiamm (int transa, int m, int n, int k, double alpha,
int *descra, float *val, int lda, int *idiag, int ndiag,
float *b, int ldb, float beta,
float *c, int ldc);

void sdiamm_64 (long transa, long m, long n, long k, float
alpha, long *descra, float *val, long lda,
long *idiag, long ndiag, float *b, long ldb,
float beta, float *c, long ldc);

```

DESCRIPTION

sdiamm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the diagonal format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal 6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$) DESCRA(2) upper/lower triangular indicator 1 : lower

2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) Two-dimensional LDA-by-NDIAG array such that VAL(:,I) consists of non-zero elements on diagonal IDIAG(I) of A. Diagonals in the lower triangular part of A are padded from the top, and those in the upper triangular part are padded from the bottom. Unchanged on exit.

LDA(input) On entry, NDIAG specifies the leading dimension of VAL, must be $\geq \text{MIN}(M,K)$. Unchanged on exit.

IDIAG(input) Integer array of length NDIAG consisting of the corresponding diagonal offsets of the non-zero diagonals of A in VAL. Lower triangular diagonals have negative offsets, the main diagonal has offset 0, and upper triangular diagonals have positive offset. Unchanged on exit.

NDIAG(input) On entry, NDIAG specifies the number of non-zero diagonals in A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \text{beta} * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats is given in section NOTES/BUGS for the scoomm manpage.

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NAME

sdiasm - diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE SDIASM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, LDA, IDIAG, NDIAG,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, M, N, UNITD, DESCRA(5), LDA, NDIAG,  
* LDB, LDC, LWORK  
INTEGER IDIAG(NDIAG)  
REAL ALPHA, BETA  
REAL DV(M), VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SDIASM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, LDA, IDIAG, NDIAG,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, M, N, UNITD, DESCRA(5), LDA, NDIAG,  
* LDB, LDC, LWORK  
INTEGER*8 IDIAG(NDIAG)  
REAL ALPHA, BETA  
REAL DV(M), VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE DIASM(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* [LDA], IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, M, NDIAG  
INTEGER, DIMENSION(:) :: DESCRA, IDIAG  
REAL ALPHA, BETA  
REAL, DIMENSION(:) :: DV  
REAL, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE DIASM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* [LDA], IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, M, NDIAG  
INTEGER*8, DIMENSION(:) :: DESCRA, IDIAG  
REAL ALPHA, BETA  
REAL, DIMENSION(:) :: DV  
REAL, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>

void sdiasm (int transa, int m, int n, int unitd,
             float *dv, float alpha, int *descra, float *val, int lda,
             int *idiag, int ndiag, float *b, int ldb, float beta,
             float *c, int ldc);
void sdiasm_64 (long transa, long m, long n, long unitd,
               float *dv, float alpha, long *descra, float *val, long lda,
               long *idiag, long ndiag, float *b, long ldb,
               float beta, float *c, long ldc);
```

DESCRIPTION

sdiasm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details)

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LDA-by-NDIAG array such that VAL(:,I) consists of non-zero elements on diagonal IDIAG(I) of A. Diagonals in the lower triangular part of A are padded from the top, and those in the upper triangular part are padded from the bottom. If UNITD is 4, VAL contains the scaled matrix D*A (see section NOTES for further details). Otherwise, unchanged on exit.

LDA(input) On entry, LDA specifies the leading dimension of VAL and INDX. LDA must be > MIN(M,K). Unchanged on exit.

IDIAG() On entry, IDIAG is an integer array of length NDIAG consisting of the corresponding diagonal offsets of the non-zero diagonals of A in VAL. Lower triangular diagonals have negative offsets, the main diagonal has offset 0, and upper triangular diagonals have positive offset. Elements of IDIAG of MUST be sorted in increasing order. Unchanged on exit.

NDIAG(input) On entry, NDIAG specifies the number of non-zero diagonals in A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M \cdot N_{\text{CPUS}}$ where N_{CPUS} is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
 2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.
- WORK*(1)=0 on return if the scaling has been completed successfully, otherwise *WORK*(1) = - i where i is the row number which 2-norm is exactly zero.
3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the

main diagonal in the DIA representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the DIA representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

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NAME

sdisna - compute the reciprocal condition numbers for the eigenvectors of a real symmetric or complex Hermitian matrix or for the left or right singular vectors of a general m-by-n matrix

SYNOPSIS

```
SUBROUTINE SDISNA(JOB, M, N, D, SEP, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER M, N, INFO  
REAL D(*), SEP(*)
```

```
SUBROUTINE SDISNA_64(JOB, M, N, D, SEP, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER*8 M, N, INFO  
REAL D(*), SEP(*)
```

F95 INTERFACE

```
SUBROUTINE DISNA(JOB, M, N, D, SEP, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER :: M, N, INFO  
REAL, DIMENSION(:) :: D, SEP
```

```
SUBROUTINE DISNA_64(JOB, M, N, D, SEP, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER(8) :: M, N, INFO  
REAL, DIMENSION(:) :: D, SEP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sdisna(char job, int m, int n, float *d, float *sep,  
            int *info);
```

```
void sdisna_64(char job, long m, long n, float *d, float  
               *sep, long *info);
```

PURPOSE

sdisna computes the reciprocal condition numbers for the eigenvectors of a real symmetric or complex Hermitian matrix or for the left or right singular vectors of a general m-by-n matrix. The reciprocal condition number is the 'gap' between the corresponding eigenvalue or singular value and the nearest other one.

The bound on the error, measured by angle in radians, in the I-th computed vector is given by

$$\text{SLAMCH}('E') * (\text{ANORM} / \text{SEP}(I))$$

where $\text{ANORM} = 2\text{-norm}(A) = \max(\text{abs}(D(j)))$. $\text{SEP}(I)$ is not allowed to be smaller than $\text{SLAMCH}('E') * \text{ANORM}$ in order to limit the size of the error bound.

SDISNA may also be used to compute error bounds for eigenvectors of the generalized symmetric definite eigenproblem.

ARGUMENTS

JOB (input)

Specifies for which problem the reciprocal condition numbers should be computed:

= 'E': the eigenvectors of a symmetric/Hermitian matrix;

= 'L': the left singular vectors of a general matrix;

= 'R': the right singular vectors of a general matrix.

M (input) The number of rows of the matrix. $M \geq 0$.

N (input) If JOB = 'L' or 'R', the number of columns of the matrix, in which case $N \geq 0$. Ignored if JOB = 'E'.

D (input) dimension ($\min(M,N)$) if JOB = 'L' or 'R' The eigenvalues (if JOB = 'E') or singular values (if JOB = 'L' or 'R') of the matrix, in either increasing or decreasing order. If singular values, they must be non-negative.

SEP (output)

dimension ($\min(M,N)$) if JOB = 'L' or 'R' The reciprocal condition numbers of the vectors.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

sdot - compute the dot product of two vectors x and y.

SYNOPSIS

```
REAL FUNCTION SDOT(N, X, INCX, Y, INCY)
```

```
INTEGER N, INCX, INCY  
REAL X(*), Y(*)
```

```
REAL FUNCTION SDOT_64(N, X, INCX, Y, INCY)
```

```
INTEGER*8 N, INCX, INCY  
REAL X(*), Y(*)
```

F95 INTERFACE

```
REAL FUNCTION DOT([N], X, [INCX], Y, [INCY])
```

```
INTEGER :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y
```

```
REAL FUNCTION DOT_64([N], X, [INCX], Y, [INCY])
```

```
INTEGER(8) :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
float sdot(int n, float *x, int incx, float *y, int incy);
```

```
float sdot_64(long n, float *x, long incx, float *y, long  
incy);
```

PURPOSE

sdot compute the dot product of x and y where x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If N is not positive then the function returns the value 0.0. Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)). On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input)

(1 + (n - 1) * abs(INCY)). On entry, the incremented array Y must contain the vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

sdoti - Compute the indexed dot product.

SYNOPSIS

```
REAL FUNCTION SDOTI(NZ, X, INDX, Y)

REAL X(*), Y(*)
INTEGER NZ
INTEGER INDX(*)

REAL FUNCTION SDOTI_64(NZ, X, INDX, Y)

REAL X(*), Y(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
REAL FUNCTION DOTI([NZ], X, INDX, Y)

REAL, DIMENSION(:) :: X, Y
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

REAL FUNCTION DOTI_64([NZ], X, INDX, Y)

REAL, DIMENSION(:) :: X, Y
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

SDOTI Compute the indexed dot product of a real sparse vector x stored in compressed form with a real vector y in full storage form.

```
dot = 0
do i = 1, n
  dot = dot + x(i) * y(indx(i))
enddo
```

ARGUMENTS

NZ (input)

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector in compressed form. Unchanged on exit.

INDX (input)

Vector containing the indices of the compressed form. It is assumed that the elements in INDX are distinct and greater than zero. Unchanged on exit.

Y (input)

Vector in full storage form. Only the elements corresponding to the indices in INDX will be accessed.

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NAME

sdsdot - compute a constant plus the double precision dot product of two single precision vectors x and y

SYNOPSIS

```
REAL FUNCTION SDSDOT(N, SB, SX, INCX, SY, INCY)
```

```
INTEGER N, INCX, INCY
```

```
REAL SB
```

```
REAL SX(*), SY(*)
```

```
REAL FUNCTION SDSDOT_64(N, SB, SX, INCX, SY, INCY)
```

```
INTEGER*8 N, INCX, INCY
```

```
REAL SB
```

```
REAL SX(*), SY(*)
```

F95 INTERFACE

```
REAL FUNCTION SDSDOT(N, SB, SX, INCX, SY, INCY)
```

```
INTEGER :: N, INCX, INCY
```

```
REAL :: SB
```

```
REAL, DIMENSION(:) :: SX, SY
```

```
REAL FUNCTION SDSDOT_64(N, SB, SX, INCX, SY, INCY)
```

```
INTEGER(8) :: N, INCX, INCY
```

```
REAL :: SB
```

```
REAL, DIMENSION(:) :: SX, SY
```

C INTERFACE

```
#include <sunperf.h>
```

```
float sdsdot(int n, float sb, float *sx, int incx, float *sy, int incy);
```

```
float sdsdot_64(long n, float sb, float *sx, long incx, float *sy, long incy);
```

PURPOSE

sdsdot Computes a constant plus the double precision dot product of x and y where x and y are single precision n -vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If N is not positive then the function returns the value 0.0. Unchanged on exit.

SB (input)

On entry, the constant that is added to the dot product before the result is returned. Unchanged on exit.

SX (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array SX must contain the vector x . Unchanged on exit.

$INCX$ (input)

On entry, $INCX$ specifies the increment for the elements of SX . Unchanged on exit.

SY (input)

($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array SY must contain the vector y . Unchanged on exit.

$INCY$ (input)

On entry, $INCY$ specifies the increment for the elements of SY . Unchanged on exit.

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NAME

second - return the user time for a process in seconds

SYNOPSIS

```
REAL FUNCTION SECOND()
```

```
REAL FUNCTION SECOND_64()
```

F95 INTERFACE

```
REAL FUNCTION SECOND()
```

```
REAL FUNCTION SECOND_64()
```

C INTERFACE

```
#include <sunperf.h>
```

```
float second();
```

```
float second_64();
```

PURPOSE

second returns the user time for a process in seconds. This version gets the time from the system function ETIME.

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NAME

sellmm - Ellpack format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SELLMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, LDA, MAXNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, K, DESCRA(5), LDA, MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(LDA,MAXNZ)  
REAL             ALPHA, BETA  
REAL             VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SELLMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, LDA, MAXNZ,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), LDA, MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(LDA,MAXNZ)  
REAL             ALPHA, BETA  
REAL             VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE ELLMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*               [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, M, K, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA  
INTEGER, DIMENSION(:, :) :: INDX  
REAL          ALPHA, BETA  
REAL, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE ELLMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                   [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, M, K, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA  
INTEGER*8, DIMENSION(:, :) :: INDX  
REAL          ALPHA, BETA  
REAL, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sellmm (int transa, int m, int n, int k, float alpha,  
int *descra, float *val, int *indx, int lda, int maxnz,  
float *b, int ldb, float beta, float *c, int ldc);
```

```
void sellmm_64 (long transa, long m, long n, long k, float  
alpha, long *descra, float *val, long *indx, long lda, long  
maxnz, float *b, long ldb, float beta, float *c, long ldc);
```

DESCRIPTION

sellmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the ellpack format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array. DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal 6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$) DESCRA(2) upper/lower triangular indicator 1 : lower

2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LDA-by-MAXNZ array such that VAL(I,:) consists of non-zero elements in row I of A, padded by zero values if the row contains less than MAXNZ. Unchanged on exit.

INDX(input) On entry, INDX is an integer two-dimensional LDA-by-MAXNZ array such that INDX(I,:) consists of the column indices of the nonzero elements in row I, padded by the integer value I if the number of nonzeros is less than MAXNZ. Unchanged on exit.

LDA(input) On entry, LDA specifies the leading dimension of VAL and INDX. Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of nonzeros elements per row. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \text{beta} * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are

implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats is given in section NOTES/BUGS for the scoomm manpage.

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NAME

sellsm - Ellpack format triangular solve

SYNOPSIS

```
SUBROUTINE SELLSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, LDA, MAXNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, M, N, UNITD, DESCRA(5), LDA, MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(LDA,MAXNZ)  
REAL             ALPHA, BETA  
REAL             DV(M), VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SELLSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, INDX, LDA, MAXNZ,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5), LDA, MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(LDA,MAXNZ)  
REAL             ALPHA, BETA  
REAL             DV(M), VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE ELLSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
*               INDX, [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA  
INTEGER, DIMENSION(:, :) :: INDX  
REAL             ALPHA, BETA  
REAL, DIMENSION(:) :: DV  
REAL, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE ELLSM_64( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
*                   INDX, [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, M, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA  
INTEGER*8, DIMENSION(:, :) :: INDX  
REAL             ALPHA, BETA
```

```

REAL, DIMENSION(:) :: DV
REAL, DIMENSION(:, :) :: VAL, B, C

```

C INTERFACE

```
#include <sunperf.h>
```

```

void sellsm (int transa, int m, int n, int unitd, float *dv,
float alpha, int *descra, float *val, int *indx, int lda,
int maxnz, float *b, int ldb, float beta, float *c, int
ldc);
void sellsm_64 (long transa, long m, long n, long unitd,
float *dv, float alpha, long *descra, float *val, long
*indx, long lda, long maxnz, float *b, long ldb, float beta,
float *c, long ldc);

```

DESCRIPTION

sellsm performs one of the matrix-matrix operations

```

C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,

```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the ellpack/itpack format and op(A) is one of

```

op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).

```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LDA-by-MAXNZ array such that VAL(I,:) consists of non-zero elements in row I of A, padded by zero values if the row contains less than MAXNZ. If UNITD is 4, VAL contains the scaled matrix D*A (see section NOTES for further details). Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer two-dimensional LDA-by-MAXNZ array such that INDX(I,:) consists of the column indices of the nonzero elements in row I, padded by the integer value I if the number of nonzeros is less than MAXNZ. The column indices MUST be sorted in increasing order for each row. Unchanged on exit.

LDA(input) On entry, LDA specifies the leading dimension of VAL and INDX. Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of nonzeros elements per row. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M \times N_{\text{CPUS}}$ where N_{CPUS} is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
 2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.
- WORK*(1)=0 on return if the scaling has been completed successfully, otherwise *WORK*(1) = - i where i is the row number which 2-norm is exactly zero.
3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are

each used with the mathematical value 1. The entries of the main diagonal in the ELL representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the ELL representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

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NAME

sfftfc - initialize the trigonometric weight and factor tables or compute the forward Fast Fourier Transform of a real sequence.

SYNOPSIS

```
SUBROUTINE SFFTFC(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N, IFAC(*), LWORK, IERR  
COMPLEX Y(*)  
REAL X(*), SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE SFFTFC_64(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N, IFAC(*), LWORK, IERR  
REAL X(*), SCALE, TRIGS(*), WORK(*)  
COMPLEX Y(*)
```

F95 INTERFACE

```
SUBROUTINE FFT(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT  
INTEGER*4, INTENT(IN), OPTIONAL :: N, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
REAL, INTENT(IN), DIMENSION(:) :: X  
COMPLEX, INTENT(OUT), DIMENSION(:) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT_64(IOPT, [N], [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT  
INTEGER(8), INTENT(IN), OPTIONAL :: N, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
REAL, INTENT(IN), DIMENSION(:) :: X  
COMPLEX, INTENT(OUT), DIMENSION(:) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
```

```

INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>

void sfftc_ (int *iopt, int *n, float *scale, float *x, complex *y, float *trigs, int *ifac, float *work, int *lwork, int *ierr);

void sfftc_64_ (long *iopt, long *n, float *scale, float *x, complex *y, float *trigs, long *ifac, float *work, long *lwork, long *ierr);

```

PURPOSE

sfftc initializes the trigonometric weight and factor tables or computes the forward Fast Fourier Transform of a real sequence as follows:

$$Y(k) = \text{scale} * \sum_{j=0}^{N-1} W * X(j)$$

where

k ranges from 0 to N-1

i = sqrt(-1)

isign = -1 for forward transform

W = exp(isign*i*j*k*2*pi/N)

In real-to-complex transform of length N, the (N/2+1) complex output data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT

N (input)

Integer specifying length of the input sequence X. N is most efficient when it is a product of small primes. N >= 0. Unchanged on exit.

SCALE (input)

Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) On entry, X is a real array whose first N elements contain the sequence to be transformed.

Y (output)

Complex array whose first $(N/2+1)$ elements contain the transform results. X and Y may be the same array starting at the same memory location, in which case the dimension of X must be at least $2*(N/2+1)$. Otherwise, it is assumed that there is no overlap between X and Y in memory.

TRIGS (input/output)

Real array of length $2*N$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = -1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 128 that contains the factors of N. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls where IOPT = -1. Unchanged on exit.

WORK (workspace)

Real array of dimension at least N. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

- 0 = normal return
- 1 = IOPT is not 0 or -1
- 2 = $N < 0$
- 3 = (LWORK is not 0) and (LWORK is less than N)
- 4 = memory allocation for workspace failed

SEE ALSO

fft

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NAME

sfputc2 - initialize the trigonometric weight and factor tables or compute the two-dimensional forward Fast Fourier Transform of a two-dimensional real array.

SYNOPSIS

```
SUBROUTINE SFFTC2(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
COMPLEX Y(LDY, *)  
REAL X(LDX, *), SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE SFFTC2_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
REAL X(LDX, *), SCALE, TRIGS(*), WORK(*)  
COMPLEX Y(LDY, *)
```

F95 INTERFACE

```
SUBROUTINE FFT2(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
& IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT  
INTEGER*4, INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
REAL, INTENT(IN), DIMENSION(:,:) :: X  
COMPLEX, INTENT(OUT), DIMENSION(:,:) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT2_64(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
REAL, INTENT(IN), DIMENSION(:,:) :: X
COMPLEX, INTENT(OUT), DIMENSION(:,:) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void sfftc2_(int *iopt, int *n1, int *n2, float *scale,
             float *x, int *ldx, complex *y, int *ldy, float
             *trigs, int *ifac, float *work, int *lwork, int
             *ierr);

void sfftc2_64_(long *iopt, long *n1, long *n2, float
               *scale, float *x, long *ldx, complex *y, long
               *ldy, float *trigs, long *ifac, float *work, long
               *lwork, long *ierr);

```

PURPOSE

sfftc2 initializes the trigonometric weight and factor tables or computes the two-dimensional real array. In computing the two-dimensional FFT, one-dimensional FFTs are computed along the columns of the input array. One-dimensional FFTs are then computed along the rows of the intermediate results.

$$Y(k_1, k_2) = \text{scale} * \sum_{j_2=0}^{N_2-1} \sum_{j_1=0}^{N_1-1} W_2 * W_1 * X(j_1, j_2)$$

where

k₁ ranges from 0 to N₁-1 and k₂ ranges from 0 to N₂-1

i = sqrt(-1)

isign = -1 for forward transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

In real-to-complex transform of length N₁, the (N₁/2+1) complex output data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT

N1 (input)

Integer specifying length of the transform in the

first dimension. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)

Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes N2 >= 0. Unchanged on exit.

SCALE (input)

Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) X is a complex array of dimensions (LDX, N2) that contains input data to be transformed. X and Y can be the same array.

LDX (input)

Leading dimension of X. LDX >= N1 if X is not the same array as Y. Else, LDX = 2*LDY. Unchanged on exit.

Y (output)

Y is a complex array of dimensions (LDY, N2) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)

Leading dimension of Y. LDY >= N1/2+1 Unchanged on exit.

TRIGS (input/output)

Real array of length 2*(N1+N2) that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = -1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 2*128 that contains the factors of N1 and N2. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = -1. Unchanged on exit.

WORK (workspace)

Real array of dimension at least MAX(N1, 2*N2)*NCPUS, where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

0 = normal return
-1 = IOPT is not 0 or -1
-2 = N1 < 0
-3 = N2 < 0
-4 = (LDX < N1) or (LDX not equal 2*LDY when X and Y are same array)
-5 = (LDY < N1/2+1)
-6 = (LWORK not equal 0) and (LWORK < MAX(N1,2*N2)*NCPUS)
-7 = memory allocation failed

SEE ALSO

fft

CAUTIONS

Y(N1/2+1:LDY,:) is used as scratch space. Upon returning, the original contents of Y(N1/2+1:LDY,:) will be lost, whereas Y(1:N1/2+1,1:N2) contains the transform results.

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NAME

sfputc3 - initialize the trigonometric weight and factor tables or compute the three-dimensional forward Fast Fourier Transform of a three-dimensional complex array.

SYNOPSIS

```
SUBROUTINE SFFTC3(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,
IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),
LWORK, IERR
COMPLEX Y(LDY1, LDY2, *)
REAL X(LDX1, LDX2, *), SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE SFFTC3_64(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,
IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),
LWORK, IERR
COMPLEX Y(LDY1, LDY2, *)
REAL X(LDX1, LDX2, *), SCALE, TRIGS(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3(IOPT, [N1], [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1], LDY2,
TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT, LDX2, LDY2
INTEGER*4, INTENT(IN), OPTIONAL :: N1, N2, N3, LDX1, LDY1,
LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
REAL, INTENT(IN), DIMENSION(:,:) :: X
COMPLEX, INTENT(OUT), DIMENSION(:,:) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT3_64(IOPT, [N1], [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1],
```

LDY2, TRIGS, IFAC, WORK, [LWORK], IERR)

```
INTEGER(8), INTENT(IN) :: IOPT, LDX2, LDY2
INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, N3, LDX1, LDY1,
LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
REAL, INTENT(IN), DIMENSION(:,:) :: X
COMPLEX, INTENT(OUT), DIMENSION(:,:) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sfftc3_ (int *iopt, int *n1, int *n2, int *n3, float
*scale, float *x, int *ldx1, int *ldx2, complex
*y, int *ldy1, int *ldy2, float *trigs, int *ifac,
float *work, int *lwork, int *ierr);
```

```
void sfftc3_64_ (long *iopt, long *n1, long *n2, long *n3,
float *scale, float *x, long *ldx1, long *ldx2,
complex *y, long *ldy1, long *ldy2, float *trigs,
long *ifac, float *work, long *lwork, long *ierr);
```

PURPOSE

sfftc3 initializes the trigonometric weight and factor tables or computes the three-dimensional forward Fast Fourier Transform of a three-dimensional complex array.

$$Y(k_1, k_2, k_3) = \text{scale} * \sum_{j_3=0}^{N_3-1} \sum_{j_2=0}^{N_2-1} \sum_{j_1=0}^{N_1-1} W_3 * W_2 * W_1 * X(j_1, j_2, j_3)$$

where

k₁ ranges from 0 to N₁-1; k₂ ranges from 0 to N₂-1 and k₃ ranges from 0 to N₃-1

i = sqrt(-1)

isign = -1 for forward transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

W₃ = exp(isign*i*j₃*k₃*2*pi/N₃)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
IOPT = 0 computes the trigonometric weight table and factor table
IOPT = -1 computes forward FFT

N1 (input)

Integer specifying length of the transform in the first dimension. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on

exit.

N2 (input)

Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. $N2 \geq 0$. Unchanged on exit.

N3 (input)

Integer specifying length of the transform in the third dimension. N3 is most efficient when it is a product of small primes. $N3 \geq 0$. Unchanged on exit.

SCALE (input)

Real scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0 for F95 INTERFACE.

X (input) X is a real array of dimensions (LDX1, LDX2, N3) that contains input data to be transformed. X can be same array as Y.

LDX1 (input)

first dimension of X. If X is not same array as Y, $LDX1 \geq N1$ Else, $LDX1 = 2*LDY1$ Unchanged on exit.

LDX2 (input)

second dimension of X. $LDX2 \geq N2$ Unchanged on exit.

Y (output)

Y is a complex array of dimensions (LDY1, LDY2, N3) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY1 (input)

first dimension of Y. $LDY1 \geq N1/2+1$ Unchanged on exit.

LDY2 (input)

second dimension of Y. If X and Y are the same array, $LDY2 = LDX2$ Else $LDY2 \geq N2$ Unchanged on exit.

TRIGS (input/output)

Real array of length $2*(N1+N2+N3)$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = -1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least $3*128$ that contains the factors of N1, N2 and N3. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent

calls when IOPT = -1. Unchanged on exit.

WORK (workspace)

Real array of dimension at least $(\text{MAX}(N, 2*N2, 2*N3) + 16*N3) * \text{NCPUS}$ where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

- 0 = normal return
- 1 = IOPT is not 0 or -1
- 2 = $N1 < 0$
- 3 = $N2 < 0$
- 4 = $N3 < 0$
- 5 = $(LDX1 < N1)$ or $(LDX \text{ not equal } 2*LDY \text{ when } X \text{ and } Y \text{ are same array})$
- 6 = $(LDX2 < N2)$
- 7 = $(LDY1 < N1/2+1)$
- 8 = $(LDY2 < N2)$ or $(LDY2 \text{ not equal } LDX2 \text{ when } X \text{ and } Y \text{ are same array})$
- 9 = $(LWORK \text{ not equal } 0)$ and $(LWORK < (\text{MAX}(N, 2*N2, 2*N3) + 16*N3)*\text{NCPUS})$
- 10 = memory allocation failed

SEE ALSO

fft

CAUTIONS

This routine uses $Y((N1/2+1)+1:LDY1, :, :)$ as scratch space. Therefore, the original contents of this subarray will be lost upon returning from routine while subarray $Y(1:N1/2+1, 1:N2, 1:N3)$ contains the transform results.

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NAME

sfftcm - initialize the trigonometric weight and factor tables or compute the one-dimensional forward Fast Fourier Transform of a set of real data sequences stored in a two-dimensional array.

SYNOPSIS

```
SUBROUTINE SFFTCM(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
REAL X(LDX, *), SCALE, TRIGS(*), WORK(*)  
COMPLEX Y(LDY, *)
```

```
SUBROUTINE SFFTCM_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
REAL X(LDX, *), SCALE, TRIGS(*), WORK(*)  
COMPLEX Y(LDY, *)
```

F95 INTERFACE

```
SUBROUTINE FFTM(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER*4, INTENT(IN) :: IOPT  
INTEGER*4, INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK  
REAL, INTENT(IN), OPTIONAL :: SCALE  
REAL, INTENT(IN), DIMENSION(:,:) :: X  
COMPLEX, INTENT(OUT), DIMENSION(:,:) :: Y  
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER*4, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL, INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER*4, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFTM_64(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK
REAL, INTENT(IN), OPTIONAL :: SCALE
REAL, INTENT(IN), DIMENSION(:,:) :: X
COMPLEX, INTENT(OUT), DIMENSION(:,:) :: Y
REAL, INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL, INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void sfftcmm_(int *iopt, int *n1, int *n2, float *scale,
              float *x, int *ldx, complex *y, int *ldy, float
              *trigs, int *ifac, float *work, int *lwork, int
              *ierr);

void sfftcmm_64_(long *iopt, long *n1, long *n2, float
                 *scale, float *x, long *ldx, complex *y, long
                 *ldy, float *trigs, long *ifac, float *work, long
                 *lwork, long *ierr);

```

PURPOSE

sfftcmm initializes the trigonometric weight and factor tables or computes the one-dimensional forward Fast Fourier Transform of a set of real data sequences stored in a two-dimensional array:

$$Y(k,l) = \text{scale} * \sum_{j=0}^{N1-1} W * X(j,l)$$

where

k ranges from 0 to N1-1 and l ranges from 0 to N2-1

i = sqrt(-1)

isign = -1 for forward transform

W = exp(isign*i*j*k*2*pi/N1)

In real-to-complex transform of length N1, the (N1/2+1) complex output data points stored are the positive-frequency half of the spectrum of the discrete Fourier transform. The other half can be obtained through complex conjugation and therefore is not stored.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT

N1 (input)

Integer specifying length of the input sequences. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)
Integer specifying number of input sequences. N2
>= 0. Unchanged on exit.

SCALE (input)
Real scalar by which transform results are scaled.
Unchanged on exit. SCALE is defaulted to 1.0 for
F95 INTERFACE.

X (input) X is a real array of dimensions (LDX, N2) that
contains the sequences to be transformed stored in
its columns.

LDX (input)
Leading dimension of X. If X and Y are the same
array, LDX = 2*LDY Else LDX >= N1 Unchanged on
exit.

Y (output)
Y is a complex array of dimensions (LDY, N2) that
contains the transform results of the input
sequences. X and Y can be the same array starting
at the same memory location, in which case the
input sequences are overwritten by their transform
results. Otherwise, it is assumed that there is
no overlap between X and Y in memory.

LDY (input)
Leading dimension of Y. LDY >= N1/2 + 1 Unchanged
on exit.

TRIGS (input/output)
Real array of length 2*N1 that contains the tri-
gonometric weights. The weights are computed when
the routine is called with IOPT = 0 and they are
used in subsequent calls when IOPT = -1.
Unchanged on exit.

IFAC (input/output)
Integer array of dimension at least 128 that con-
tains the factors of N1. The factors are computed
when the routine is called with IOPT = 0 and they
are used in subsequent calls when IOPT = -1.
Unchanged on exit.

WORK (workspace)
Real array of dimension at least N1. The user can
also choose to have the routine allocate its own
workspace (see LWORK).

LWORK (input)
Integer specifying workspace size. If LWORK = 0,
the routine will allocate its own workspace.

IERR (output)
On exit, integer IERR has one of the following
values:
0 = normal return
-1 = IOPT is not 0 or -1
-2 = N1 < 0
-3 = N2 < 0

-4 = (LDX < N1) or (LDX not equal 2*LDY when X and
Y are same array)
-4 = (LDY < N1/2 + 1)
-6 = (LWORK not equal 0) and (LWORK < N1)
-7 = memory allocation failed

SEE ALSO

fft

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NAME

sgbbrd - reduce a real general m-by-n band matrix A to upper bidiagonal form B by an orthogonal transformation

SYNOPSIS

```
SUBROUTINE SGBBRD(VECT, M, N, NCC, KL, KU, AB, LDAB, D, E, Q, LDQ,  
PT, LDPT, C, LDC, WORK, INFO)
```

```
CHARACTER * 1 VECT  
INTEGER M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL AB(LDAB,*), D(*), E(*), Q(LDQ,*), PT(LDPT,*), C(LDC,*),  
WORK(*)
```

```
SUBROUTINE SGBBRD_64(VECT, M, N, NCC, KL, KU, AB, LDAB, D, E, Q, LDQ,  
PT, LDPT, C, LDC, WORK, INFO)
```

```
CHARACTER * 1 VECT  
INTEGER*8 M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL AB(LDAB,*), D(*), E(*), Q(LDQ,*), PT(LDPT,*), C(LDC,*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBBRD(VECT, M, [N], [NCC], KL, KU, AB, [LDAB], D, E, Q,  
[LDQ], PT, [LDPT], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT  
INTEGER :: M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL, DIMENSION(:) :: D, E, WORK  
REAL, DIMENSION(:,) :: AB, Q, PT, C
```

```
SUBROUTINE GBBRD_64(VECT, M, [N], [NCC], KL, KU, AB, [LDAB], D, E,  
Q, [LDQ], PT, [LDPT], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT  
INTEGER(8) :: M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL, DIMENSION(:) :: D, E, WORK  
REAL, DIMENSION(:,) :: AB, Q, PT, C
```

C INTERFACE

```
#include <sunperf.h>
```

```

void sgbbbrd(char vect, int m, int n, int ncc, int kl, int
    ku, float *ab, int ldab, float *d, float *e, float
    *q, int ldq, float *pt, int ldpt, float *c, int
    ldc, int *info);
void sgbbbrd_64(char vect, long m, long n, long ncc, long kl,
    long ku, float *ab, long ldab, float *d, float *e,
    float *q, long ldq, float *pt, long ldpt, float
    *c, long ldc, long *info);

```

PURPOSE

sgbbbrd reduces a real general m-by-n band matrix A to upper bidiagonal form B by an orthogonal transformation: $Q' * A * P = B$.

The routine computes B, and optionally forms Q or P', or computes $Q'*C$ for a given matrix C.

ARGUMENTS

VECT (input)

Specifies whether or not the matrices Q and P' are to be formed. = 'N': do not form Q or P';
 = 'Q': form Q only;
 = 'P': form P' only;
 = 'B': form both.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NCC (input)

The number of columns of the matrix C. $NCC \geq 0$.

KL (input)

The number of subdiagonals of the matrix A. $KL \geq 0$.

KU (input)

The number of superdiagonals of the matrix A. $KU \geq 0$.

AB (input/output)

REAL array, dimension(LDAB,N) On entry, the m-by-n band matrix A, stored in rows 1 to KL+KU+1. The j-th column of A is stored in the j-th column of the array AB as follows: $AB(ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$. On exit, A is overwritten by values generated during the reduction.

LDAB (input)

The leading dimension of the array A. $LDAB \geq KL+KU+1$.

D (output)
 REAL array, dimension(min(M,N)) The diagonal elements of the bidiagonal matrix B.

E (output)
 REAL array, dimension(min(M,N)-1) The superdiagonal elements of the bidiagonal matrix B.

Q (output)
 REAL array, dimension(LDQ,M) If VECT = 'Q' or 'B', the m-by-m orthogonal matrix Q. If VECT = 'N' or 'P', the array Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. LDQ >= max(1,M) if VECT = 'Q' or 'B'; LDQ >= 1 otherwise.

PT (output)
 REAL array, dimension(LDPT,N) If VECT = 'P' or 'B', the n-by-n orthogonal matrix P'. If VECT = 'N' or 'Q', the array PT is not referenced.

LDPT (input)
 The leading dimension of the array PT. LDPT >= max(1,N) if VECT = 'P' or 'B'; LDPT >= 1 otherwise.

C (input/output)
 REAL array, dimension(LDC,NCC) On entry, an m-by-ncc matrix C. On exit, C is overwritten by Q'*C. C is not referenced if NCC = 0.

LDC (input)
 The leading dimension of the array C. LDC >= max(1,M) if NCC > 0; LDC >= 1 if NCC = 0.

WORK (workspace)
 REAL array, dimension(2*MAX(M,N))

INFO (output)
 = 0: successful exit.
 < 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

sgbcon - estimate the reciprocal of the condition number of a real general band matrix A, in either the 1-norm or the infinity-norm,

SYNOPSIS

```
SUBROUTINE SGBCON(NORM, N, KL, KU, A, LDA, IPIVOT, ANORM,
                 RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM
INTEGER N, KL, KU, LDA, INFO
INTEGER IPIVOT(*), WORK2(*)
REAL ANORM, RCOND
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE SGBCON_64(NORM, N, KL, KU, A, LDA, IPIVOT, ANORM,
                    RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM
INTEGER*8 N, KL, KU, LDA, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
REAL ANORM, RCOND
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBCON(NORM, [N], KL, KU, A, [LDA], IPIVOT, ANORM,
                RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM
INTEGER :: N, KL, KU, LDA, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GBCON_64(NORM, [N], KL, KU, A, [LDA], IPIVOT, ANORM,
                   RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM
INTEGER(8) :: N, KL, KU, LDA, INFO
```

```
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
void sgbcon(char norm, int n, int kl, int ku, float *a, int
            lda, int *ipivot, float anorm, float *rcond, int
            *info);

void sgbcon_64(char norm, long n, long kl, long ku, float
               *a, long lda, long *ipivot, float anorm, float
               *rcond, long *info);
```

PURPOSE

sgbcon estimates the reciprocal of the condition number of a real general band matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by SGBTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A)))$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)

The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)

The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input) Details of the LU factorization of the band matrix A, as computed by SGBTRF. U is stored as an upper triangular band matrix with $KL+KU$ superdiagonals in rows 1 to $KL+KU+1$, and the multipliers used during the factorization are stored in rows $KL+KU+2$ to $2*KL+KU+1$.

LDA (input)

The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (input)

The pivot indices; for $1 \leq i \leq N$, row i of the matrix was interchanged with row $IPIVOT(i)$.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension (N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sgbequ - compute row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number

SYNOPSIS

```
SUBROUTINE SGBEQU(M, N, KL, KU, A, LDA, R, C, ROWCND,  
                  COLCND, AMAX, INFO)
```

```
INTEGER M, N, KL, KU, LDA, INFO  
REAL ROWCND, COLCND, AMAX  
REAL A(LDA,*), R(*), C(*)
```

```
SUBROUTINE SGBEQU_64(M, N, KL, KU, A, LDA, R, C, ROWCND,  
                    COLCND, AMAX, INFO)
```

```
INTEGER*8 M, N, KL, KU, LDA, INFO  
REAL ROWCND, COLCND, AMAX  
REAL A(LDA,*), R(*), C(*)
```

F95 INTERFACE

```
SUBROUTINE GBEQU([M], [N], KL, KU, A, [LDA], R, C,  
                ROWCND, COLCND, AMAX, [INFO])
```

```
INTEGER :: M, N, KL, KU, LDA, INFO  
REAL :: ROWCND, COLCND, AMAX  
REAL, DIMENSION(:) :: R, C  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE GBEQU_64([M], [N], KL, KU, A, [LDA], R, C,  
                  ROWCND, COLCND, AMAX, [INFO])
```

```
INTEGER(8) :: M, N, KL, KU, LDA, INFO  
REAL :: ROWCND, COLCND, AMAX  
REAL, DIMENSION(:) :: R, C  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgbequ(int m, int n, int kl, int ku, float *a, int lda,
           float *r, float *c, float *rowcnd, float *colcnd,
           float *amax, int *info);
```

```
void sgbequ_64(long m, long n, long kl, long ku, float *a,
              long lda, float *r, float *c, float *rowcnd, float
              *colcnd, float *amax, long *info);
```

PURPOSE

sgbequ computes row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number. R returns the row scale factors and C the column scale factors, chosen to try to make the largest element in each row and column of the matrix B with elements $B(i,j)=R(i)*A(i,j)*C(j)$ have absolute value 1.

R(i) and C(j) are restricted to be between SMLNUM = smallest safe number and BIGNUM = largest safe number. Use of these scaling factors is not guaranteed to reduce the condition number of A but works well in practice.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

KL (input)

The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)

The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input) The band matrix A, stored in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array A as follows: $A(ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$.

LDA (input)

The leading dimension of the array A. $LDA \geq KL+KU+1$.

R (output)

If $INFO = 0$, or $INFO > M$, R contains the row scale factors for A.

C (output)

If $INFO = 0$, C contains the column scale factors for A.

ROWCND (output)

If $INFO = 0$ or $INFO > M$, ROWCND contains the ratio of the smallest R(i) to the largest R(i). If $ROWCND \geq 0.1$ and AMAX is neither too large nor

too small, it is not worth scaling by R.

COLCND (output)

If INFO = 0, COLCND contains the ratio of the smallest C(i) to the largest C(i). If COLCND >= 0.1, it is not worth scaling by C.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= M: the i-th row of A is exactly zero
> M: the (i-M)-th column of A is exactly zero

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NAME

sgbmv - perform one of the matrix-vector operations $y := \alpha A x + \beta y$ or $y := \alpha A' x + \beta y$

SYNOPSIS

```
SUBROUTINE SGBMV(TRANSA, M, N, KL, KU, ALPHA, A, LDA, X, INCX,  
                BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA  
INTEGER M, N, KL, KU, LDA, INCX, INCY  
REAL ALPHA, BETA  
REAL A(LDA,*), X(*), Y(*)
```

```
SUBROUTINE SGBMV_64(TRANSA, M, N, KL, KU, ALPHA, A, LDA, X,  
                   INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 M, N, KL, KU, LDA, INCX, INCY  
REAL ALPHA, BETA  
REAL A(LDA,*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE GBMV([TRANSA], [M], [N], KL, KU, ALPHA, A, [LDA], X,  
               [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: M, N, KL, KU, LDA, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GBMV_64([TRANSA], [M], [N], KL, KU, ALPHA, A, [LDA],  
                  X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: M, N, KL, KU, LDA, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>

void sgbmv(char transa, int m, int n, int kl, int ku, float
           alpha, float *a, int lda, float *x, int incx,
           float beta, float *y, int incy);
void sgbmv_64(char transa, long m, long n, long kl, long ku,
              float alpha, float *a, long lda, float *x, long
              incx, float beta, float *y, long incy);
```

PURPOSE

sgbmv performs one of the matrix-vector operations $y := \alpha A x + \beta y$ or $y := \alpha A' x + \beta y$, where α and β are scalars, x and y are vectors and A is an m by n band matrix, with kl sub-diagonals and ku super-diagonals.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $y := \alpha A x + \beta y$.

TRANSA = 'T' or 't' $y := \alpha A' x + \beta y$.

TRANSA = 'C' or 'c' $y := \alpha A' x + \beta y$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

KL (input)

On entry, KL specifies the number of sub-diagonals of the matrix A. $KL \geq 0$. Unchanged on exit.

KU (input)

On entry, KU specifies the number of super-diagonals of the matrix A. $KU \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry, the leading $(kl + ku + 1)$ by n

part of the array A must contain the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (ku + 1) of the array, the first super-diagonal starting at position 2 in row ku, the first sub-diagonal starting at position 1 in row (ku + 2), and so on. Elements in the array A that do not correspond to elements in the band matrix (such as the top left ku by ku triangle) are not referenced. The following program segment will transfer a band matrix from conventional full matrix storage to band storage:

```

      DO 20, J = 1, N
        K = KU + 1 - J
        DO 10, I = MAX( 1, J - KU ), MIN( M, J + KL )
          A( K + I, J ) = matrix( I, J )
10     CONTINUE
20    CONTINUE

```

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= (kl + ku + 1). Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)) when TRANSA = 'N' or 'n' and at least (1 + (m - 1) * abs(INCX)) otherwise. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX <> 0. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

(1 + (m - 1) * abs(INCY)) when TRANSA = 'N' or 'n' and at least (1 + (n - 1) * abs(INCY)) otherwise. Before entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

sgbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE SGBRFS(TRANSA, N, KL, KU, NRHS, A, LDA, AF, LDAF,
  IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),
BERR(*), WORK(*)
```

```
SUBROUTINE SGBRFS_64(TRANSA, N, KL, KU, NRHS, A, LDA, AF, LDAF,
  IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER*8 N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBRFS([TRANSA], [N], KL, KU, [NRHS], A, [LDA], AF,
  [LDAF], IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2],
  [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL, DIMENSION(:) :: FERR, BERR, WORK
REAL, DIMENSION(:,:) :: A, AF, B, X
```

```
SUBROUTINE GBRFS_64([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  AF, [LDAF], IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
  [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: TRANSA
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL, DIMENSION(:) :: FERR, BERR, WORK
REAL, DIMENSION(:, :) :: A, AF, B, X

```

C INTERFACE

```

#include <sunperf.h>

void sgbrfs(char transa, int n, int kl, int ku, int nrhs,
            float *a, int lda, float *af, int ldaf, int
            *ipivot, float *b, int ldb, float *x, int ldx,
            float *ferr, float *berr, int *info);

void sgbrfs_64(char transa, long n, long kl, long ku, long
              nrhs, float *a, long lda, float *af, long ldaf,
              long *ipivot, float *b, long ldb, float *x, long
              ldx, float *ferr, float *berr, long *info);

```

PURPOSE

sgbrfs improves the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)

The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)

The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The original band matrix A, stored in rows 1 to $KL+KU+1$. The j -th column of A is stored in the j -th column of the array A as follows: $A(ku+1+i-j, j) = A(i, j)$ for $\max(1, j-ku) \leq i \leq \min(n, j+kl)$.

LDA (input)

The leading dimension of the array A. LDA \geq KL+KU+1.

AF (input)

Details of the LU factorization of the band matrix A, as computed by SGBTRF. U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1.

LDAF (input)

The leading dimension of the array AF. LDAF \geq 2*KL*KU+1.

IPIVOT (input)

The pivot indices from SGBTRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)

On entry, the solution matrix X, as computed by SGBTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sgbsv - compute the solution to a real system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE SGBSV(N, KL, KU, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
INTEGER N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SGBSV_64(N, KL, KU, NRHS, A, LDA, IPIVOT, B, LDB,  
INFO)
```

```
INTEGER*8 N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GBSV([N], KL, KU, [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
INTEGER :: N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GBSV_64([N], KL, KU, [NRHS], A, [LDA], IPIVOT, B,  
[LDB], [INFO])
```

```
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```

void sgbsv(int n, int kl, int ku, int nrhs, float *a, int
           lda, int *ipivot, float *b, int ldb, int *info);

void sgbsv_64(long n, long kl, long ku, long nrhs, float *a,
              long lda, long *ipivot, float *b, long ldb, long
              *info);

```

PURPOSE

sgbsv computes the solution to a real system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices.

The LU decomposition with partial pivoting and row interchanges is used to factor A as $A = L * U$, where L is a product of permutation and unit lower triangular matrices with KL subdiagonals, and U is upper triangular with KL+KU superdiagonals. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A. $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A. $KU \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array A as follows:

$$A(KL+KU+1+i-j, j) = A(i, j) \quad \text{for } \max(1, j-KU) \leq i \leq \min(N, j+KL)$$
 On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDA (input)
The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (output)
The pivot indices that define the permutation

matrix P; row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)

On entry, the N-by-NRHS right hand side matrix B.
On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and the solution has not been computed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when M = N = 6, KL = 2, KU = 1:

On entry:

On exit:

	*	*	*	+	+	+		*	*	*	u14	u25			
u36								*	*		u13	u24	u35		
u46								*			u12	u23	u34	u45	
u56											u11	u22	u33	u44	u55
u66															
	a21	a32	a43	a54	a65	*		m21	m32	m43	m54	m65			
*															
	a31	a42	a53	a64	*	*		m31	m42	m53	m64	*			
*															

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U because of fill-in resulting from the row interchanges.

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NAME

sgbsvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE SGBSVX(FACT, TRANSA, N, KL, KU, NRHS, A, LDA, AF,
  LDAF, IPIVOT, EQUED, R, C, B, LDB, X, LDX, RCOND, FERR,
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
INTEGER N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
REAL RCOND
REAL A(LDA,*), AF(LDAF,*), R(*), C(*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE SGBSVX_64(FACT, TRANSA, N, KL, KU, NRHS, A, LDA, AF,
  LDAF, IPIVOT, EQUED, R, C, B, LDB, X, LDX, RCOND, FERR,
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
INTEGER*8 N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
REAL RCOND
REAL A(LDA,*), AF(LDAF,*), R(*), C(*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBSVX(FACT, [TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  AF, [LDAF], IPIVOT, EQUED, R, C, B, [LDB], X, [LDX],
  RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
INTEGER :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: R, C, FERR, BERR, WORK
REAL, DIMENSION(:,) :: A, AF, B, X
```

```

SUBROUTINE GBSVX_64(FACT, [TRANSA], [N], KL, KU, [NRHS], A,
  [LDA], AF, [LDAF], IPIVOT, EQUED, R, C, B, [LDB], X, [LDX],
  RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: R, C, FERR, BERR, WORK
REAL, DIMENSION(:,:) :: A, AF, B, X

```

C INTERFACE

```

#include <sunperf.h>

```

```

void sgbsvx(char fact, char transa, int n, int kl, int ku,
  int nrhs, float *a, int lda, float *af, int ldaf,
  int *ipivot, char equed, float *r, float *c, float
  *b, int ldb, float *x, int ldx, float *rcond,
  float *ferr, float *berr, int *info);

```

```

void sgbsvx_64(char fact, char transa, long n, long kl, long
  ku, long nrhs, float *a, long lda, float *af, long
  ldaf, long *ipivot, char equed, float *r, float
  *c, float *b, long ldb, float *x, long ldx, float
  *rcond, float *ferr, float *berr, long *info);

```

PURPOSE

sgbsvx uses the LU factorization to compute the solution to a real system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed by this subroutine:

1. If FACT = 'E', real scaling factors are computed to equilibrate

the system:

TRANS = 'N': $\text{diag}(R) * A * \text{diag}(C) * \text{inv}(\text{diag}(C)) * X = \text{diag}(R) * B$

TRANS = 'T': $(\text{diag}(R) * A * \text{diag}(C))^{**T} * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

TRANS = 'C': $(\text{diag}(R) * A * \text{diag}(C))^{**H} * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A, but if equilibration is used, A is

overwritten by $\text{diag}(R) * A * \text{diag}(C)$ and B by $\text{diag}(R) * B$ (if TRANS='N')

or $\text{diag}(C) * B$ (if TRANS = 'T' or 'C').

2. If FACT = 'N' or 'E', the LU decomposition is used to factor the

matrix A (after equilibration if FACT = 'E') as

$$A = L * U,$$
where L is a product of permutation and unit lower triangular matrices with KL subdiagonals, and U is upper triangular with KL+KU superdiagonals.

3. If some $U(i,i)=0$, so that U is exactly singular, then the routine returns with INFO = i. Otherwise, the factored form of A is used to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
4. The system of equations is solved for X using the factored form of A.
5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.
6. If equilibration was used, the matrix X is premultiplied by $\text{diag}(C)$ (if TRANS = 'N') or $\text{diag}(R)$ (if TRANS = 'T' or 'C') so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF and IPIVOT contain the factored form of A. If EQUED is not 'N', the matrix A has been equilibrated with scaling factors given by R and C. A, AF, and IPIVOT are not modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

TRANS (input)

Specifies the form of the system of equations. = 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Transpose)

TRANS is defaulted to 'N' for F95 INTERFACE.

N (input) The number of linear equations, i.e., the order of

the matrix A. $N \geq 0$.

KL (input)

The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)

The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)

On entry, the matrix A in band storage, in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array A as follows: $A(KU+1+i-j, j) = A(i, j)$ for $\max(1, j-KU) \leq i \leq \min(N, j+kl)$

If FACT = 'F' and EQUED is not 'N', then A must have been equilibrated by the scaling factors in R and/or C. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if EQUED .ne. 'N', A is scaled as follows:
EQUED = 'R': $A := \text{diag}(R) * A$
EQUED = 'C': $A := A * \text{diag}(C)$
EQUED = 'B': $A := \text{diag}(R) * A * \text{diag}(C)$.

LDA (input)

The leading dimension of the array A. $LDA \geq KL+KU+1$.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains details of the LU factorization of the band matrix A, as computed by SGBTRF. U is stored as an upper triangular band matrix with $KL+KU$ superdiagonals in rows 1 to $KL+KU+1$, and the multipliers used during the factorization are stored in rows $KL+KU+2$ to $2*KL+KU+1$. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns details of the LU factorization of A.

If FACT = 'E', then AF is an output argument and on exit returns details of the LU factorization of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. $LDAF \geq 2*KL+KU+1$.

IPIVOT (input)

If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the

factorization $A = L*U$ as computed by SGBTRF; row i of the matrix was interchanged with row IPIVOT(i).

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = L*U$ of the original matrix A.

If FACT = 'E', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = L*U$ of the equilibrated matrix A.

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'R': Row equilibration, i.e., A has been premultiplied by diag(R).
= 'C': Column equilibration, i.e., A has been postmultiplied by diag(C).
= 'B': Both row and column equilibration, i.e., A has been replaced by $\text{diag}(R) * A * \text{diag}(C)$.
EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

R (input or output)

The row scale factors for A. If EQUED = 'R' or 'B', A is multiplied on the left by diag(R); if EQUED = 'N' or 'C', R is not accessed. R is an input argument if FACT = 'F'; otherwise, R is an output argument. If FACT = 'F' and EQUED = 'R' or 'B', each element of R must be positive.

C (input or output)

The column scale factors for A. If EQUED = 'C' or 'B', A is multiplied on the right by diag(C); if EQUED = 'N' or 'R', C is not accessed. C is an input argument if FACT = 'F'; otherwise, C is an output argument. If FACT = 'F' and EQUED = 'C' or 'B', each element of C must be positive.

B (input/output)

On entry, the right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if TRANSA = 'N' and EQUED = 'R' or 'B', B is overwritten by $\text{diag}(R)*B$; if TRANSA = 'T' or 'C' and EQUED = 'C' or 'B', B is overwritten by $\text{diag}(C)*B$.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that A and B are modified on exit if EQUED .ne. 'N', and the solution to the equilibrated system is $\text{inv}(\text{diag}(C))*X$ if TRANSA = 'N' and EQUED = 'C' or 'B', or $\text{inv}(\text{diag}(R))*X$ if TRANSA = 'T' or 'C' and EQUED = 'R' or 'B'.

LDX (input)

The leading dimension of the array X. $LDX \geq$

max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N) On exit, WORK(1) contains the reciprocal pivot growth factor norm(A)/norm(U). The "max absolute element" norm is used. If WORK(1) is much less than 1, then the stability of the LU factorization of the (equilibrated) matrix A could be poor. This also means that the solution X, condition estimator RCOND, and forward error bound FERR could be unreliable. If factorization fails with 0 < INFO <= N, then WORK(1) contains the reciprocal pivot growth factor for the leading INFO columns of A.

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

sgbtf2 - compute an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE SGBTF2(M, N, KL, KU, AB, LDAB, IPIV, INFO)
```

```
INTEGER M, N, KL, KU, LDAB, INFO  
INTEGER IPIV(*)  
REAL AB(LDAB,*)
```

```
SUBROUTINE SGBTF2_64(M, N, KL, KU, AB, LDAB, IPIV, INFO)
```

```
INTEGER*8 M, N, KL, KU, LDAB, INFO  
INTEGER*8 IPIV(*)  
REAL AB(LDAB,*)
```

F95 INTERFACE

```
SUBROUTINE GBTF2([M], [N], KL, KU, AB, [LDAB], IPIV, [INFO])
```

```
INTEGER :: M, N, KL, KU, LDAB, INFO  
INTEGER, DIMENSION(:) :: IPIV  
REAL, DIMENSION(:, :) :: AB
```

```
SUBROUTINE GBTF2_64([M], [N], KL, KU, AB, [LDAB], IPIV, [INFO])
```

```
INTEGER(8) :: M, N, KL, KU, LDAB, INFO  
INTEGER(8), DIMENSION(:) :: IPIV  
REAL, DIMENSION(:, :) :: AB
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgbtf2(int m, int n, int kl, int ku, float *ab, int  
          ldab, int *ipiv, int *info);
```

```
void sgbtf2_64(long m, long n, long kl, long ku, float *ab,  
             long ldab, long *ipiv, long *info);
```

PURPOSE

sgbtf2 computes an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

AB (input/output)
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array AB as follows:
 $AB(kl+ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$

On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDAB (input)
The leading dimension of the array AB. $LDAB \geq 2*KL+KU+1$.

IPIV (output)
The pivot indices; for $1 \leq i \leq \min(M,N)$, row i of the matrix was interchanged with row IPIV(i).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = +i, U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $M = N = 6$, $KL = 2$, $KU = 1$:

On entry:

On exit:

	*	*	*	+	+	+		*	*	*	u14	u25	
u36													
	*	*	+	+	+	+		*	*		u13	u24	u35
u46													
	*	a12	a23	a34	a45	a56		*	u12	u23	u34	u45	
u56													
	a11	a22	a33	a44	a55	a66		u11	u22	u33	u44	u55	
u66													
	a21	a32	a43	a54	a65	*		m21	m32	m43	m54	m65	
*													
	a31	a42	a53	a64	*	*		m31	m42	m53	m64	*	
*													

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U, because of fill-in resulting from the row interchanges.

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NAME

sgbtrf - compute an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE SGBTRF(M, N, KL, KU, A, LDA, IPIVOT, INFO)
```

```
INTEGER M, N, KL, KU, LDA, INFO  
INTEGER IPIVOT(MIN(M,N))  
REAL A(LDA, N)
```

```
SUBROUTINE SGBTRF_64(M, N, KL, KU, A, LDA, IPIVOT, INFO)
```

```
INTEGER*8 M, N, KL, KU, LDA, INFO  
INTEGER*8 IPIVOT(MIN(M,N))  
REAL A(LDA,N)
```

F95 INTERFACE

```
SUBROUTINE GBTRF(M, [N], KL, KU, A, [LDA], IPIVOT, [INFO])
```

```
INTEGER :: M, N, KL, KU, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE GBTRF_64(M, [N], KL, KU, A, [LDA], IPIVOT, [INFO])
```

```
INTEGER(8) :: M, N, KL, KU, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgbtrf(int m, int n, int kl, int ku, float *a, int lda,  
           int *ipivot, int *info);
```

```
void sgbtrf_64(long m, long n, long kl, long ku, float *a,  
              long lda, long *ipivot, long *info);
```

PURPOSE

sgbtrf computes an LU factorization of a real m-by-n band matrix A using partial pivoting with row interchanges.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

M (input) Integer
The number of rows of the matrix A. $M \geq 0$.

N (input) Integer
The number of columns of the matrix A. $N \geq 0$.

KL (input) Integer
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input) Integer
The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input/output) Real array of dimension (LDA, N).
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array A as follows:
 $A(KL+KU+1+I-J, J) = A(I, J)$ for $\text{MAX}(1, J-KU) \leq I \leq \text{MIN}(M, J+KL)$
On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDA (input) Integer
The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (output) Integer array of dimension MIN(M,N)
The pivot indices; for $1 \leq I \leq \text{MIN}(M, N)$, row I of the matrix was interchanged with row IPIVOT(I).

INFO (output) Integer
= 0: successful exit
< 0: if INFO = -I, the I-th argument had an illegal value
> 0: if INFO = +I, U(I,I) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equa-

tions.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $M = N = 6$, $KL = 2$, $KU = 1$:

On entry:						On exit:					
* * *	+	+	+			* * *	u14	u25			
u36	* * +	+	+	+		* * *	u13	u24	u35		
u46	* a12	a23	a34	a45	a56	* u12	u23	u34	u45		
u56	a11	a22	a33	a44	a55	a66	u11	u22	u33	u44	u55
u66	a21	a32	a43	a54	a65	*	m21	m32	m43	m54	m65
*	a31	a42	a53	a64	*	*	m31	m42	m53	m64	*
*											

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U because of fill-in resulting from the row interchanges.

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NAME

sgbtrs - solve a system of linear equations $A * X = B$ or $A' * X = B$ with a general band matrix A using the LU factorization computed by SGBTRF

SYNOPSIS

```
SUBROUTINE SGBTRS(TRANSA, N, KL, KU, NRHS, A, LDA, IPIVOT, B,
  LDB, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER IPIVOT(*)
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SGBTRS_64(TRANSA, N, KL, KU, NRHS, A, LDA, IPIVOT,
  B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER*8 N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER*8 IPIVOT(*)
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GBTRS([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:,:) :: A, B
```

```
SUBROUTINE GBTRS_64([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>

void sgbtrs(char transa, int n, int kl, int ku, int nrhs,
            float *a, int lda, int *ipivot, float *b, int ldb,
            int *info);
void sgbtrs_64(char transa, long n, long kl, long ku, long nrhs,
               float *a, long lda, long *ipivot, float *b,
               long ldb, long *info);
```

PURPOSE

sgbtrs solves a system of linear equations
 $A * X = B$ or $A' * X = B$ with a general band matrix A
 using the LU factorization computed by SGBTRF.

ARGUMENTS

TRANSA (input)
 Specifies the form of the system of equations. =
 'N': $A * X = B$ (No transpose)
 = 'T': $A' * X = B$ (Transpose)
 = 'C': $A' * X = B$ (Conjugate transpose = Tran-
 sponse)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)
 The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
 The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number
 of columns of the matrix B. $NRHS \geq 0$.

A (input) Details of the LU factorization of the band matrix
 A, as computed by SGBTRF. U is stored as an upper
 triangular band matrix with $KL+KU$ superdiagonals
 in rows 1 to $KL+KU+1$, and the multipliers used
 during the factorization are stored in rows
 $KL+KU+2$ to $2*KL+KU+1$.

LDA (input)
 The leading dimension of the array A. $LDA \geq$
 $2*KL+KU+1$.

IPIVOT (input)
 The pivot indices; for $1 \leq i \leq N$, row i of the
 matrix was interchanged with row IPIVOT(i).

B (input/output)
 On entry, the right hand side matrix B. On exit,

the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

sgebak - form the right or left eigenvectors of a real general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by SGEBAL

SYNOPSIS

```
SUBROUTINE SGEBAK(JOB, SIDE, N, ILO, IHI, SCALE, M, V, LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE  
INTEGER N, ILO, IHI, M, LDV, INFO  
REAL SCALE(*), V(LDV,*)
```

```
SUBROUTINE SGEBAK_64(JOB, SIDE, N, ILO, IHI, SCALE, M, V, LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE  
INTEGER*8 N, ILO, IHI, M, LDV, INFO  
REAL SCALE(*), V(LDV,*)
```

F95 INTERFACE

```
SUBROUTINE GEBAK(JOB, SIDE, [N], ILO, IHI, SCALE, [M], V, [LDV],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE  
INTEGER :: N, ILO, IHI, M, LDV, INFO  
REAL, DIMENSION(:) :: SCALE  
REAL, DIMENSION(:,) :: V
```

```
SUBROUTINE GEBAK_64(JOB, SIDE, [N], ILO, IHI, SCALE, [M], V, [LDV],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE  
INTEGER(8) :: N, ILO, IHI, M, LDV, INFO  
REAL, DIMENSION(:) :: SCALE  
REAL, DIMENSION(:,) :: V
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgebak(char job, char side, int n, int ilo, int ihi,  
float *scale, int m, float *v, int ldv, int
```

```

        *info);

void sgebak_64(char job, char side, long n, long ilo, long
             ihi, float *scale, long m, float *v, long ldv,
             long *info);

```

PURPOSE

sgebak forms the right or left eigenvectors of a real general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by SGEBAL.

ARGUMENTS

JOB (input)

Specifies the type of backward transformation required: = 'N', do nothing, return immediately; = 'P', do backward transformation for permutation only; = 'S', do backward transformation for scaling only; = 'B', do backward transformations for both permutation and scaling. JOB must be the same as the argument JOB supplied to SGEBAL.

SIDE (input)

= 'R': V contains right eigenvectors;
 = 'L': V contains left eigenvectors.

N (input) The number of rows of the matrix V. $N \geq 0$.

ILO (input)

The integers ILO and IHI determined by SGEBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

IHI (input)

See the description for ILO.

SCALE (input)

Details of the permutation and scaling factors, as returned by SGEBAL.

M (input) The number of columns of the matrix V. $M \geq 0$.

V (input/output)

On entry, the matrix of right or left eigenvectors to be transformed, as returned by SHSEIN or STREVC. On exit, V is overwritten by the transformed eigenvectors.

LDV (input)

The leading dimension of the array V. $LDV \geq \max(1,N)$.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-

gal value.

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NAME

sgebal - balance a general real matrix A

SYNOPSIS

```
SUBROUTINE SGBAL(JOB, N, A, LDA, ILO, IHI, SCALE, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER N, LDA, ILO, IHI, INFO  
REAL A(LDA,*), SCALE(*)
```

```
SUBROUTINE SGBAL_64(JOB, N, A, LDA, ILO, IHI, SCALE, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER*8 N, LDA, ILO, IHI, INFO  
REAL A(LDA,*), SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE GEBAL(JOB, [N], A, [LDA], ILO, IHI, SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER :: N, LDA, ILO, IHI, INFO  
REAL, DIMENSION(:) :: SCALE  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GEBAL_64(JOB, [N], A, [LDA], ILO, IHI, SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER(8) :: N, LDA, ILO, IHI, INFO  
REAL, DIMENSION(:) :: SCALE  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgebal(char job, int n, float *a, int lda, int *ilo,  
            int *ihi, float *scale, int *info);
```

```
void sgebal_64(char job, long n, float *a, long lda, long
```

```
*ilo, long *ihi, float *scale, long *info);
```

PURPOSE

sgebal balances a general real matrix A. This involves, first, permuting A by a similarity transformation to isolate eigenvalues in the first 1 to ILO-1 and last IHI+1 to N elements on the diagonal; and second, applying a diagonal similarity transformation to rows and columns ILO to IHI to make the rows and columns as close in norm as possible. Both steps are optional.

Balancing may reduce the 1-norm of the matrix, and improve the accuracy of the computed eigenvalues and/or eigenvectors.

ARGUMENTS

JOB (input)

Specifies the operations to be performed on A:
= 'N': none: simply set ILO = 1, IHI = N,
SCALE(I) = 1.0 for i = 1,...,N; = 'P': permute
only;
= 'S': scale only;
= 'B': both permute and scale.

N (input) The order of the matrix A. N >= 0.

A (input/output)

On entry, the input matrix A. On exit, A is
overwritten by the balanced matrix. If JOB = 'N',
A is not referenced. See Further Details.

LDA (input)

The leading dimension of the array A. LDA >=
max(1,N).

ILO (output)

ILO and IHI are set to integers such that on exit
A(i,j) = 0 if i > j and j = 1,...,ILO-1 or i =
IHI+1,...,N. If JOB = 'N' or 'S', ILO = 1 and IHI
= N.

IHI (output)

See the description for ILO.

SCALE (output)

Details of the permutations and scaling factors
applied to A. If P(j) is the index of the row and
column interchanged with row and column j and D(j)
is the scaling factor applied to row and column j,
then SCALE(j) = P(j) for j = 1,...,ILO-1 = D(j)
for j = ILO,...,IHI = P(j) for j = IHI+1,...,N.
The order in which the interchanges are made is N
to IHI+1, then 1 to ILO-1.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The permutations consist of row and column interchanges which put the matrix in the form

$$P A P = \begin{pmatrix} T1 & X & Y \\ 0 & B & Z \\ 0 & 0 & T2 \end{pmatrix}$$

where T1 and T2 are upper triangular matrices whose eigenvalues lie along the diagonal. The column indices ILO and IHI mark the starting and ending columns of the submatrix B. Balancing consists of applying a diagonal similarity transformation $\text{inv}(D) * B * D$ to make the 1-norms of each row of B and its corresponding column nearly equal. The output matrix is

$$\begin{pmatrix} T1 & X*D & Y \\ 0 & \text{inv}(D)*B*D & \text{inv}(D)*Z \\ 0 & 0 & T2 \end{pmatrix}$$

Information about the permutations P and the diagonal matrix D is returned in the vector SCALE.

This subroutine is based on the EISPACK routine BALANC.

Modified by Tzu-Yi Chen, Computer Science Division, University of California at Berkeley, USA

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NAME

sgebrd - reduce a general real M-by-N matrix A to upper or lower bidiagonal form B by an orthogonal transformation

SYNOPSIS

```
SUBROUTINE SGEBRD(M, N, A, LDA, D, E, TAUQ, TAUP, WORK, LWORK, INFO)
```

```
INTEGER M, N, LDA, LWORK, INFO  
REAL A(LDA,*), D(*), E(*), TAUQ(*), TAUP(*), WORK(*)
```

```
SUBROUTINE SGEBRD_64(M, N, A, LDA, D, E, TAUQ, TAUP, WORK, LWORK,  
INFO)
```

```
INTEGER*8 M, N, LDA, LWORK, INFO  
REAL A(LDA,*), D(*), E(*), TAUQ(*), TAUP(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEBRD([M], [N], A, [LDA], D, E, TAUQ, TAUP, [WORK], [LWORK],  
[INFO])
```

```
INTEGER :: M, N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: D, E, TAUQ, TAUP, WORK  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE GEBRD_64([M], [N], A, [LDA], D, E, TAUQ, TAUP, [WORK],  
[LWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: D, E, TAUQ, TAUP, WORK  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgebrd(int m, int n, float *a, int lda, float *d, float  
*e, float *tauq, float *taup, int *info);
```

```
void sgebrd_64(long m, long n, float *a, long lda, float *d,
```

```
float *e, float *tauq, float *taup, long *info);
```

PURPOSE

sgebrd reduces a general real M-by-N matrix A to upper or lower bidiagonal form B by an orthogonal transformation: $Q^{*T} * A * P = B$.

If $m \geq n$, B is upper bidiagonal; if $m < n$, B is lower bidiagonal.

ARGUMENTS

M (input) The number of rows in the matrix A. $M \geq 0$.

N (input) The number of columns in the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N general matrix to be reduced. On exit, if $m \geq n$, the diagonal and the first superdiagonal are overwritten with the upper bidiagonal matrix B; the elements below the diagonal, with the array TAUQ, represent the orthogonal matrix Q as a product of elementary reflectors, and the elements above the first superdiagonal, with the array TAUP, represent the orthogonal matrix P as a product of elementary reflectors; if $m < n$, the diagonal and the first subdiagonal are overwritten with the lower bidiagonal matrix B; the elements below the first subdiagonal, with the array TAUQ, represent the orthogonal matrix Q as a product of elementary reflectors, and the elements above the diagonal, with the array TAUP, represent the orthogonal matrix P as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

D (output)

The diagonal elements of the bidiagonal matrix B: $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the bidiagonal matrix B: if $m \geq n$, $E(i) = A(i, i+1)$ for $i = 1, 2, \dots, n-1$; if $m < n$, $E(i) = A(i+1, i)$ for $i = 1, 2, \dots, m-1$.

TAUQ (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Q. See Further Details.

TAUP (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix P. See

Further Details.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The length of the array WORK. LWORK \geq max(1,M,N). For optimum performance LWORK \geq (M+N)*NB, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrices Q and P are represented as products of elementary reflectors:

If $m \geq n$,

$$Q = H(1) H(2) \dots H(n) \quad \text{and} \quad P = G(1) G(2) \dots G(n-1)$$

Each H(i) and G(i) has the form:

$$H(i) = I - \tau_{\text{uq}} * v * v' \quad \text{and} \quad G(i) = I - \tau_{\text{up}} * u * u'$$

where τ_{uq} and τ_{up} are real scalars, and v and u are real vectors; $v(1:i-1) = 0$, $v(i) = 1$, and $v(i+1:m)$ is stored on exit in A(i+1:m,i); $u(1:i) = 0$, $u(i+1) = 1$, and $u(i+2:n)$ is stored on exit in A(i,i+2:n); τ_{uq} is stored in TAUQ(i) and τ_{up} in TAUP(i).

If $m < n$,

$$Q = H(1) H(2) \dots H(m-1) \quad \text{and} \quad P = G(1) G(2) \dots G(m)$$

Each H(i) and G(i) has the form:

$$H(i) = I - \tau_{\text{uq}} * v * v' \quad \text{and} \quad G(i) = I - \tau_{\text{up}} * u * u'$$

where τ_{uq} and τ_{up} are real scalars, and v and u are real vectors; $v(1:i) = 0$, $v(i+1) = 1$, and $v(i+2:m)$ is stored on exit in A(i+2:m,i); $u(1:i-1) = 0$, $u(i) = 1$, and $u(i+1:n)$ is stored on exit in A(i,i+1:n); τ_{uq} is stored in TAUQ(i) and τ_{up} in TAUP(i).

The contents of A on exit are illustrated by the following examples:

$m = 6$ and $n = 5$ ($m > n$):

(d e u1 u1 u1)

$m = 5$ and $n = 6$ ($m < n$):

(d u1 u1 u1 u1)

```

u1 )
( v1 d e u2 u2 )      ( e d u2 u2 u2
u2 )
( v1 v2 d e u3 )      ( v1 e d u3 u3
u3 )
( v1 v2 v3 d e )      ( v1 v2 e d u4
u4 )
( v1 v2 v3 v4 d )      ( v1 v2 v3 e d
u5 )
( v1 v2 v3 v4 v5 )

```

where d and e denote diagonal and off-diagonal elements of B, v_i denotes an element of the vector defining $H(i)$, and u_i an element of the vector defining $G(i)$.

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NAME

sgecon - estimate the reciprocal of the condition number of a general real matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by SGETRF

SYNOPSIS

```
SUBROUTINE SGECON(NORM, N, A, LDA, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM  
INTEGER N, LDA, INFO  
INTEGER WORK2(*)  
REAL ANORM, RCOND  
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE SGECON_64(NORM, N, A, LDA, ANORM, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM  
INTEGER*8 N, LDA, INFO  
INTEGER*8 WORK2(*)  
REAL ANORM, RCOND  
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GECON(NORM, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GECON_64(NORM, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: WORK2
```

```
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
void sgecon(char norm, int n, float *a, int lda, float
            anorm, float *rcond, int *info);

void sgecon_64(char norm, long n, float *a, long lda, float
              anorm, float *rcond, long *info);
```

PURPOSE

sgecon estimates the reciprocal of the condition number of a general real matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by SGETRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A)))$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The factors L and U from the factorization $A = P * L * U$ as computed by SGETRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension(4*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sgeequ - compute row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number

SYNOPSIS

```
SUBROUTINE SGEEQU(M, N, A, LDA, R, C, ROWCND, COLCND, AMAX,
                  INFO)
```

```
INTEGER M, N, LDA, INFO
REAL ROWCND, COLCND, AMAX
REAL A(LDA,*), R(*), C(*)
```

```
SUBROUTINE SGEEQU_64(M, N, A, LDA, R, C, ROWCND, COLCND, AMAX,
                    INFO)
```

```
INTEGER*8 M, N, LDA, INFO
REAL ROWCND, COLCND, AMAX
REAL A(LDA,*), R(*), C(*)
```

F95 INTERFACE

```
SUBROUTINE GEEQU([M], [N], A, [LDA], R, C, ROWCND, COLCND,
                AMAX, [INFO])
```

```
INTEGER :: M, N, LDA, INFO
REAL :: ROWCND, COLCND, AMAX
REAL, DIMENSION(:) :: R, C
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE GEEQU_64([M], [N], A, [LDA], R, C, ROWCND, COLCND,
                  AMAX, [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO
REAL :: ROWCND, COLCND, AMAX
REAL, DIMENSION(:) :: R, C
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgeequ(int m, int n, float *a, int lda, float *r, float
```

```

        *c, float *rowcnd, float *colcnd, float *amax, int
        *info);

void sgeequ_64(long m, long n, float *a, long lda, float *r,
              float *c, float *rowcnd, float *colcnd, float
              *amax, long *info);

```

PURPOSE

sgeequ computes row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number. R returns the row scale factors and C the column scale factors, chosen to try to make the largest element in each row and column of the matrix B with elements $B(i,j)=R(i)*A(i,j)*C(j)$ have absolute value 1.

R(i) and C(j) are restricted to be between SMLNUM = smallest safe number and BIGNUM = largest safe number. Use of these scaling factors is not guaranteed to reduce the condition number of A but works well in practice.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input) The M-by-N matrix whose equilibration factors are to be computed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,M)$.

R (output)
If INFO = 0 or INFO > M, R contains the row scale factors for A.

C (output)
If INFO = 0, C contains the column scale factors for A.

ROWCND (output)
If INFO = 0 or INFO > M, ROWCND contains the ratio of the smallest R(i) to the largest R(i). If ROWCND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by R.

COLCND (output)
If INFO = 0, COLCND contains the ratio of the smallest C(i) to the largest C(i). If COLCND ≥ 0.1 , it is not worth scaling by C.

AMAX (output)
Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= M: the i-th row of A is exactly zero
> M: the (i-M)-th column of A is exactly zero

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NAME

sgees - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z

SYNOPSIS

```
SUBROUTINE SGEES(JOBZ, SORTEV, SELECT, N, A, LDA, NOUT, WR, WI, Z,  
                LDZ, WORK, LDWORK, WORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV  
INTEGER N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL SELECT  
LOGICAL WORK3(*)  
REAL A(LDA,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SGEES_64(JOBZ, SORTEV, SELECT, N, A, LDA, NOUT, WR, WI, Z,  
                  LDZ, WORK, LDWORK, WORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV  
INTEGER*8 N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL*8 SELECT  
LOGICAL*8 WORK3(*)  
REAL A(LDA,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEES(JOBZ, SORTEV, SELECT, [N], A, [LDA], NOUT, WR, WI, Z,  
               [LDZ], [WORK], [LDWORK], [WORK3], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV  
INTEGER :: N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL :: SELECT  
LOGICAL, DIMENSION(:) :: WORK3  
REAL, DIMENSION(:) :: WR, WI, WORK  
REAL, DIMENSION(:,) :: A, Z
```

```
SUBROUTINE GEES_64(JOBZ, SORTEV, SELECT, [N], A, [LDA], NOUT, WR, WI,  
                  Z, [LDZ], [WORK], [LDWORK], [WORK3], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV  
INTEGER(8) :: N, LDA, NOUT, LDZ, LDWORK, INFO
```

```

LOGICAL(8) :: SELECT
LOGICAL(8), DIMENSION(:) :: WORK3
REAL, DIMENSION(:) :: WR, WI, WORK
REAL, DIMENSION(:,) :: A, Z

```

C INTERFACE

```

#include <sunperf.h>
void      sgees(char      jobz,      char      sortev,
               int(*select)(float,float), int n, float *a, int
               lda, int *nout, float *wr, float *wi, float *z,
               int ldz, int *info);

void      sgees_64(char      jobz,      char      sortev,
                   long(*select)(float,float), long n, float *a, long
                   lda, long *nout, float *wr, float *wi, float *z,
                   long ldz, long *info);

```

PURPOSE

sgees computes for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z. This gives the Schur factorization $A = Z^*T^*(Z^{**}T)$.

Optionally, it also orders the eigenvalues on the diagonal of the real Schur form so that selected eigenvalues are at the top left. The leading columns of Z then form an orthonormal basis for the invariant subspace corresponding to the selected eigenvalues.

A matrix is in real Schur form if it is upper quasi-triangular with 1-by-1 and 2-by-2 blocks. 2-by-2 blocks will be standardized in the form

$$\begin{bmatrix} a & b \\ c & a \end{bmatrix}$$

where $b*c < 0$. The eigenvalues of such a block are $a \pm \sqrt{bc}$.

ARGUMENTS

JOBZ (input)

```

= 'N': Schur vectors are not computed;
= 'V': Schur vectors are computed.

```

SORTEV (input)

```

Specifies whether or not to order the eigenvalues
on the diagonal of the Schur form. = 'N': Eigen-
values are not ordered;
= 'S': Eigenvalues are ordered (see SELECT).

```

SELECT (input)

```

LOGICAL FUNCTION of two REAL arguments SELECT must
be declared EXTERNAL in the calling subroutine.
If SORTEV = 'S', SELECT is used to select eigen-
values to sort to the top left of the Schur form.

```

If `SORTEV = 'N'`, `SELECT` is not referenced. An eigenvalue `WR(j)+sqrt(-1)*WI(j)` is selected if `SELECT(WR(j),WI(j))` is true; i.e., if either one of a complex conjugate pair of eigenvalues is selected, then both complex eigenvalues are selected. Note that a selected complex eigenvalue may no longer satisfy `SELECT(WR(j),WI(j)) = .TRUE.` after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned); in this case `INFO` is set to `N+2` (see `INFO` below).

`N` (input) The order of the matrix `A`. `N` \geq 0.

`A` (input/output)
REAL array, dimension `(LDA,N)` On entry, the `N`-by-`N` matrix `A`. On exit, `A` has been overwritten by its real Schur form `T`.

`LDA` (input)
The leading dimension of the array `A`. `LDA` \geq `max(1,N)`.

`NOUT` (output)
If `SORTEV = 'N'`, `NOUT = 0`. If `SORTEV = 'S'`, `NOUT` = number of eigenvalues (after sorting) for which `SELECT` is true. (Complex conjugate pairs for which `SELECT` is true for either eigenvalue count as 2.)

`WR` (output)
`WR` and `WI` contain the real and imaginary parts, respectively, of the computed eigenvalues in the same order that they appear on the diagonal of the output Schur form `T`. Complex conjugate pairs of eigenvalues will appear consecutively with the eigenvalue having the positive imaginary part first.

`WI` (output)
See the description for `WR`.

`Z` (output)
If `JOBZ = 'V'`, `Z` contains the orthogonal matrix `Z` of Schur vectors. If `JOBZ = 'N'`, `Z` is not referenced.

`LDZ` (input)
The leading dimension of the array `Z`. `LDZ` \geq 1; if `JOBZ = 'V'`, `LDZ` \geq `N`.

`WORK` (workspace)
On exit, if `INFO = 0`, `WORK(1)` contains the optimal `LDWORK`.

`LDWORK` (input)
The dimension of the array `WORK`. `LDWORK` \geq `max(1,3*N)`. For good performance, `LDWORK` must generally be larger.

If `LDWORK = -1`, then a workspace query is assumed; the routine only calculates the optimal size of the `WORK` array, returns this value as the first

entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK3 (workspace)

dimension(N) Not referenced if SORTEV = 'N'.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: if INFO = i, and i is

<= N: the QR algorithm failed to compute all the eigenvalues; elements 1:ILO-1 and i+1:N of WR and WI contain those eigenvalues which have converged; if JOBZ = 'V', Z contains the matrix which reduces A to its partially converged Schur form. = N+1: the eigenvalues could not be reordered because some eigenvalues were too close to separate (the problem is very ill-conditioned); = N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Schur form no longer satisfy SELECT=.TRUE. This could also be caused by underflow due to scaling.

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NAME

sgeesx - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z

SYNOPSIS

```
SUBROUTINE SGEESX(JOBZ, SORTEV, SELECT, SENSE, N, A, LDA, NOUT, WR,  
  WI, Z, LDZ, SRCONE, RCONV, WORK, LDWORK, IWORK2, LDWRK2, BWORK3,  
  INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV, SENSE  
INTEGER N, LDA, NOUT, LDZ, LDWORK, LDWRK2, INFO  
INTEGER IWORK2(*)  
LOGICAL SELECT  
LOGICAL BWORK3(*)  
REAL SRCONE, RCONV  
REAL A(LDA,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SGEESX_64(JOBZ, SORTEV, SELECT, SENSE, N, A, LDA, NOUT,  
  WR, WI, Z, LDZ, SRCONE, RCONV, WORK, LDWORK, IWORK2, LDWRK2,  
  BWORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV, SENSE  
INTEGER*8 N, LDA, NOUT, LDZ, LDWORK, LDWRK2, INFO  
INTEGER*8 IWORK2(*)  
LOGICAL*8 SELECT  
LOGICAL*8 BWORK3(*)  
REAL SRCONE, RCONV  
REAL A(LDA,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEESX(JOBZ, SORTEV, SELECT, SENSE, [N], A, [LDA], NOUT,  
  WR, WI, Z, [LDZ], SRCONE, RCONV, [WORK], [LDWORK], [IWORK2],  
  [LDWRK2], [BWORK3], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV, SENSE  
INTEGER :: N, LDA, NOUT, LDZ, LDWORK, LDWRK2, INFO  
INTEGER, DIMENSION(:) :: IWORK2  
LOGICAL :: SELECT  
LOGICAL, DIMENSION(:) :: BWORK3
```

```

REAL :: SRCONE, RCONV
REAL, DIMENSION(:) :: WR, WI, WORK
REAL, DIMENSION(:,) :: A, Z

SUBROUTINE GSEESX_64(JOBZ, SORTEV, SELECT, SENSE, [N], A, [LDA], NOUT,
    WR, WI, Z, [LDZ], SRCONE, RCONV, [WORK], [LDWORK], [IWORK2],
    [LDWRK2], [BWORK3], [INFO])

CHARACTER(LEN=1) :: JOBZ, SORTEV, SENSE
INTEGER(8) :: N, LDA, NOUT, LDZ, LDWORK, LDWRK2, INFO
INTEGER(8), DIMENSION(:) :: IWORK2
LOGICAL(8) :: SELECT
LOGICAL(8), DIMENSION(:) :: BWORK3
REAL :: SRCONE, RCONV
REAL, DIMENSION(:) :: WR, WI, WORK
REAL, DIMENSION(:,) :: A, Z

```

C INTERFACE

```

#include <sunperf.h>

void      sgeesx(char      jobz,      char      sortev,
    int(*select)(float,float), char sense, int n,
    float *a, int lda, int *nout, float *wr, float
    *wi, float *z, int ldz, float *srcone, float
    *rconv, int *info);

void      sgeesx_64(char      jobz,      char      sortev,
    long(*select)(float,float), char sense, long n,
    float *a, long lda, long *nout, float *wr, float
    *wi, float *z, long ldz, float *srcone, float
    *rconv, long *info);

```

PURPOSE

sgeesx computes for an N-by-N real nonsymmetric matrix A, the eigenvalues, the real Schur form T, and, optionally, the matrix of Schur vectors Z. This gives the Schur factorization $A = Z^*T^*(Z^{**}T)$.

Optionally, it also orders the eigenvalues on the diagonal of the real Schur form so that selected eigenvalues are at the top left; computes a reciprocal condition number for the average of the selected eigenvalues (RCONDE); and computes a reciprocal condition number for the right invariant subspace corresponding to the selected eigenvalues (RCONDV). The leading columns of Z form an orthonormal basis for this invariant subspace.

For further explanation of the reciprocal condition numbers RCONDE and RCONDV, see Section 4.10 of the LAPACK Users' Guide (where these quantities are called s and sep respectively).

A real matrix is in real Schur form if it is upper quasi-triangular with 1-by-1 and 2-by-2 blocks. 2-by-2 blocks will be standardized in the form

$$\begin{bmatrix} a & b \\ c & a \end{bmatrix}$$

where $b*c < 0$. The eigenvalues of such a block are $a \pm \sqrt{bc}$.

ARGUMENTS

JOBZ (input)

= 'N': Schur vectors are not computed;
= 'V': Schur vectors are computed.

SORTEV (input)

Specifies whether or not to order the eigenvalues on the diagonal of the Schur form. = 'N': Eigenvalues are not ordered;
= 'S': Eigenvalues are ordered (see SELECT).

SELECT (input)

LOGICAL FUNCTION of two REAL arguments SELECT must be declared EXTERNAL in the calling subroutine. If SORTEV = 'S', SELECT is used to select eigenvalues to sort to the top left of the Schur form. If SORTEV = 'N', SELECT is not referenced. An eigenvalue $WR(j) + \sqrt{-1} * WI(j)$ is selected if $SELECT(WR(j), WI(j))$ is true; i.e., if either one of a complex conjugate pair of eigenvalues is selected, then both are. Note that a selected complex eigenvalue may no longer satisfy $SELECT(WR(j), WI(j)) = .TRUE.$ after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned); in this case INFO may be set to N+3 (see INFO below).

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': None are computed;
= 'E': Computed for average of selected eigenvalues only;
= 'V': Computed for selected right invariant subspace only;
= 'B': Computed for both. If SENSE = 'E', 'V' or 'B', SORTEV must equal 'S'.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

REAL array, dimension (LDA,N) On entry, the N-by-N matrix A. On exit, A is overwritten by its real Schur form T.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

NOUT (output)

If SORTEV = 'N', NOUT = 0. If SORTEV = 'S', NOUT = number of eigenvalues (after sorting) for which SELECT is true. (Complex conjugate pairs for which SELECT is true for either eigenvalue count as 2.)

WR (output)
 WR and WI contain the real and imaginary parts, respectively, of the computed eigenvalues, in the same order that they appear on the diagonal of the output Schur form T. Complex conjugate pairs of eigenvalues appear consecutively with the eigenvalue having the positive imaginary part first.

WI (output)
 See the description for WR.

Z (output)
 If JOBZ = 'V', Z contains the orthogonal matrix Z of Schur vectors. If JOBZ = 'N', Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= N.

SRCONE (output)
 If SENSE = 'E' or 'B', SRCONE contains the reciprocal condition number for the average of the selected eigenvalues. Not referenced if SENSE = 'N' or 'V'.

RCONV (output)
 If SENSE = 'V' or 'B', RCONV contains the reciprocal condition number for the selected right invariant subspace. Not referenced if SENSE = 'N' or 'E'.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The dimension of the array WORK. LDWORK >= max(1,3*N). Also, if SENSE = 'E' or 'V' or 'B', LDWORK >= N+2*NOUT*(N-NOUT), where NOUT is the number of selected eigenvalues computed by this routine. Note that N+2*NOUT*(N-NOUT) <= N+N*N/2. For good performance, LDWORK must generally be larger.

IWORK2 (workspace/output)
 Not referenced if SENSE = 'N' or 'E'. On exit, if INFO = 0, IWORK2(1) returns the optimal LDWRK2.

LDWRK2 (input)
 The dimension of the array IWORK2. LDWRK2 >= 1; if SENSE = 'V' or 'B', LDWRK2 >= NOUT*(N-NOUT).

BWORK3 (workspace)
 dimension(N) Not referenced if SORTEV = 'N'.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value.
 > 0: if INFO = i, and i is
 <= N: the QR algorithm failed to compute all the

eigenvalues; elements 1:ILO-1 and i+1:N of WR and WI contain those eigenvalues which have converged; if JOBZ = 'V', Z contains the transformation which reduces A to its partially converged Schur form. = N+1: the eigenvalues could not be reordered because some eigenvalues were too close to separate (the problem is very ill-conditioned); = N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Schur form no longer satisfy SELECT=.TRUE. This could also be caused by underflow due to scaling.

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NAME

sgeev - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

SYNOPSIS

```
SUBROUTINE SGEEV(JOBVL, JOBVR, N, A, LDA, WR, WI, VL, LDVL, VR, LDVR,
                WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
INTEGER N, LDA, LDVL, LDVR, LDWORK, INFO
REAL A(LDA,*), WR(*), WI(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

```
SUBROUTINE SGEEV_64(JOBVL, JOBVR, N, A, LDA, WR, WI, VL, LDVL, VR,
                   LDVR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
INTEGER*8 N, LDA, LDVL, LDVR, LDWORK, INFO
REAL A(LDA,*), WR(*), WI(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEEV(JOBVL, JOBVR, [N], A, [LDA], WR, WI, VL, [LDVL], VR,
               [LDVR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
INTEGER :: N, LDA, LDVL, LDVR, LDWORK, INFO
REAL, DIMENSION(:) :: WR, WI, WORK
REAL, DIMENSION(:,) :: A, VL, VR
```

```
SUBROUTINE GEEV_64(JOBVL, JOBVR, [N], A, [LDA], WR, WI, VL, [LDVL],
                  VR, [LDVR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
INTEGER(8) :: N, LDA, LDVL, LDVR, LDWORK, INFO
REAL, DIMENSION(:) :: WR, WI, WORK
REAL, DIMENSION(:,) :: A, VL, VR
```

C INTERFACE

```
#include <sunperf.h>
```

```

void sgeev(char jobvl, char jobvr, int n, float *a, int lda,
           float *wr, float *wi, float *vl, int ldvl, float
           *vr, int ldvr, int *info);

void sgeev_64(char jobvl, char jobvr, long n, float *a, long
              lda, float *wr, float *wi, float *vl, long ldvl,
              float *vr, long ldvr, long *info);

```

PURPOSE

sgeev computes for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors.

The right eigenvector $v(j)$ of A satisfies

$$A * v(j) = \text{lambda}(j) * v(j)$$

where $\text{lambda}(j)$ is its eigenvalue.

The left eigenvector $u(j)$ of A satisfies

$$u(j)**H * A = \text{lambda}(j) * u(j)**H$$

where $u(j)**H$ denotes the conjugate transpose of $u(j)$.

The computed eigenvectors are normalized to have Euclidean norm equal to 1 and largest component real.

ARGUMENTS

JOBVL (input)

= 'N': left eigenvectors of A are not computed;
 = 'V': left eigenvectors of A are computed.

JOBVR (input)

= 'N': right eigenvectors of A are not computed;
 = 'V': right eigenvectors of A are computed.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. On exit, A has been overwritten.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

WR (output)

WR and WI contain the real and imaginary parts, respectively, of the computed eigenvalues. Complex conjugate pairs of eigenvalues appear consecutively with the eigenvalue having the positive imaginary part first.

WI (output)

See the description for WR.

VL (output)

If JOBVL = 'V', the left eigenvectors $u(j)$ are stored one after another in the columns of VL, in

the same order as their eigenvalues. If `JOBVL = 'N'`, `VL` is not referenced. If the j -th eigenvalue is real, then $u(j) = VL(:,j)$, the j -th column of `VL`. If the j -th and $(j+1)$ -st eigenvalues form a complex conjugate pair, then $u(j) = VL(:,j) + i*VL(:,j+1)$ and $u(j+1) = VL(:,j) - i*VL(:,j+1)$.

`LDVL` (input)

The leading dimension of the array `VL`. `LDVL` ≥ 1 ;
if `JOBVL = 'V'`, `LDVL` $\geq N$.

`VR` (input)

If `JOBVR = 'V'`, the right eigenvectors $v(j)$ are stored one after another in the columns of `VR`, in the same order as their eigenvalues. If `JOBVR = 'N'`, `VR` is not referenced. If the j -th eigenvalue is real, then $v(j) = VR(:,j)$, the j -th column of `VR`. If the j -th and $(j+1)$ -st eigenvalues form a complex conjugate pair, then $v(j) = VR(:,j) + i*VR(:,j+1)$ and $v(j+1) = VR(:,j) - i*VR(:,j+1)$.

`LDVR` (input)

The leading dimension of the array `VR`. `LDVR` ≥ 1 ;
if `JOBVR = 'V'`, `LDVR` $\geq N$.

`WORK` (workspace)

On exit, if `INFO = 0`, `WORK(1)` returns the optimal `LDWORK`.

`LDWORK` (input)

The dimension of the array `WORK`. `LDWORK` $\geq \max(1, 3*N)$, and if `JOBVL = 'V'` or `JOBVR = 'V'`, `LDWORK` $\geq 4*N$. For good performance, `LDWORK` must generally be larger.

If `LDWORK = -1`, then a workspace query is assumed; the routine only calculates the optimal size of the `WORK` array, returns this value as the first entry of the `WORK` array, and no error message related to `LDWORK` is issued by `XERBLA`.

`INFO` (output)

= 0: successful exit
< 0: if `INFO = -i`, the i -th argument had an illegal value.
> 0: if `INFO = i`, the QR algorithm failed to compute all the eigenvalues, and no eigenvectors have been computed; elements $i+1:N$ of `WR` and `WI` contain eigenvalues which have converged.

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NAME

sgeevx - compute for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

SYNOPSIS

```
SUBROUTINE SGEEVX(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, WR, WI, VL,
  LDVL, VR, LDVR, ILO, IHI, SCALE, ABNRM, RCONE, RCONV, WORK,
  LDWORK, IWORK2, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
INTEGER N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
INTEGER IWORK2(*)
REAL ABNRM
REAL A(LDA,*), WR(*), WI(*), VL(LDVL,*), VR(LDVR,*),
SCALE(*), RCONE(*), RCONV(*), WORK(*)
```

```
SUBROUTINE SGEEVX_64(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, WR, WI,
  VL, LDVL, VR, LDVR, ILO, IHI, SCALE, ABNRM, RCONE, RCONV, WORK,
  LDWORK, IWORK2, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
INTEGER*8 N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
INTEGER*8 IWORK2(*)
REAL ABNRM
REAL A(LDA,*), WR(*), WI(*), VL(LDVL,*), VR(LDVR,*),
SCALE(*), RCONE(*), RCONV(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEEVX(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], WR, WI,
  VL, [LDVL], VR, [LDVR], ILO, IHI, SCALE, ABNRM, RCONE, RCONV,
  [WORK], [LDWORK], [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
INTEGER :: N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
INTEGER, DIMENSION(:) :: IWORK2
REAL :: ABNRM
REAL, DIMENSION(:) :: WR, WI, SCALE, RCONE, RCONV, WORK
REAL, DIMENSION(:, :) :: A, VL, VR
```

```

SUBROUTINE GEEVX_64(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], WR,
    WI, VL, [LDVL], VR, [LDVR], ILO, IHI, SCALE, ABNRM, RCONE, RCONV,
    [WORK], [LDWORK], [IWORK2], [INFO])

```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
INTEGER(8) :: N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK2
REAL :: ABNRM
REAL, DIMENSION(:) :: WR, WI, SCALE, RCONE, RCONV, WORK
REAL, DIMENSION(:,) :: A, VL, VR

```

C INTERFACE

```

#include <sunperf.h>

```

```

void sggeevx(char balanc, char jobvl, char jobvr, char sense,
    int n, float *a, int lda, float *wr, float *wi,
    float *vl, int ldvl, float *vr, int ldvr, int
    *ilo, int *ihi, float *scale, float *abnrm, float
    *rcone, float *rconv, int *info);

```

```

void sggeevx_64(char balanc, char jobvl, char jobvr, char
    sense, long n, float *a, long lda, float *wr,
    float *wi, float *vl, long ldvl, float *vr, long
    ldvr, long *ilo, long *ihi, float *scale, float
    *abnrm, float *rcone, float *rconv, long *info);

```

PURPOSE

sggeevx computes for an N-by-N real nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors.

Optionally also, it computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors (ILO, IHI, SCALE, and ABNRM), reciprocal condition numbers for the eigenvalues (RCONDE), and reciprocal condition numbers for the right eigenvectors (RCONDV).

The right eigenvector $v(j)$ of A satisfies

$$A * v(j) = \text{lambda}(j) * v(j)$$

where $\text{lambda}(j)$ is its eigenvalue.

The left eigenvector $u(j)$ of A satisfies

$$u(j)**H * A = \text{lambda}(j) * u(j)**H$$

where $u(j)**H$ denotes the conjugate transpose of $u(j)$.

The computed eigenvectors are normalized to have Euclidean norm equal to 1 and largest component real.

Balancing a matrix means permuting the rows and columns to make it more nearly upper triangular, and applying a diagonal similarity transformation $D * A * D^{(-1)}$, where D is a diagonal matrix, to make its rows and columns closer in norm and the condition numbers of its eigenvalues and eigenvectors smaller. The computed reciprocal condition numbers correspond to the balanced matrix. Permuting rows and columns will not change the condition numbers (in exact arithmetic) but diagonal scaling will. For further explana-

tion of balancing, see section 4.10.2 of the LAPACK Users' Guide.

ARGUMENTS

BALANC (input)

Indicates how the input matrix should be diagonally scaled and/or permuted to improve the conditioning of its eigenvalues. = 'N': Do not diagonally scale or permute;
= 'P': Perform permutations to make the matrix more nearly upper triangular. Do not diagonally scale; = 'S': Diagonally scale the matrix, i.e. replace A by $D*A*D^{*(-1)}$, where D is a diagonal matrix chosen to make the rows and columns of A more equal in norm. Do not permute; = 'B': Both diagonally scale and permute A.

Computed reciprocal condition numbers will be for the matrix after balancing and/or permuting. Permuting does not change condition numbers (in exact arithmetic), but balancing does.

JOBVL (input)

= 'N': left eigenvectors of A are not computed;
= 'V': left eigenvectors of A are computed. If SENSE = 'E' or 'B', JOBVL must = 'V'.

JOBVR (input)

= 'N': right eigenvectors of A are not computed;
= 'V': right eigenvectors of A are computed. If SENSE = 'E' or 'B', JOBVR must = 'V'.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': None are computed;
= 'E': Computed for eigenvalues only;
= 'V': Computed for right eigenvectors only;
= 'B': Computed for eigenvalues and right eigenvectors.

If SENSE = 'E' or 'B', both left and right eigenvectors must also be computed (JOBVL = 'V' and JOBVR = 'V').

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. On exit, A has been overwritten. If JOBVL = 'V' or JOBVR = 'V', A contains the real Schur form of the balanced version of the input matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

WR (output)

WR and WI contain the real and imaginary parts, respectively, of the computed eigenvalues. Com-

plex conjugate pairs of eigenvalues will appear consecutively with the eigenvalue having the positive imaginary part first.

WI (output)

See the description for WR.

VL (output)

If JOBVL = 'V', the left eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. If JOBVL = 'N', VL is not referenced. If the j -th eigenvalue is real, then $u(j) = VL(:,j)$, the j -th column of VL. If the j -th and $(j+1)$ -st eigenvalues form a complex conjugate pair, then $u(j) = VL(:,j) + i*VL(:,j+1)$ and $u(j+1) = VL(:,j) - i*VL(:,j+1)$.

LDVL (input)

The leading dimension of the array VL. LDVL ≥ 1 ; if JOBVL = 'V', LDVL $\geq N$.

VR (output)

If JOBVR = 'V', the right eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. If JOBVR = 'N', VR is not referenced. If the j -th eigenvalue is real, then $v(j) = VR(:,j)$, the j -th column of VR. If the j -th and $(j+1)$ -st eigenvalues form a complex conjugate pair, then $v(j) = VR(:,j) + i*VR(:,j+1)$ and $v(j+1) = VR(:,j) - i*VR(:,j+1)$.

LDVR (input)

The leading dimension of the array VR. LDVR ≥ 1 , and if JOBVR = 'V', LDVR $\geq N$.

ILO (output)

ILO and IHI are integer values determined when A was balanced. The balanced $A(i,j) = 0$ if $I > J$ and $J = 1, \dots, ILO-1$ or $I = IHI+1, \dots, N$.

IHI (output)

See the description of ILO.

SCALE (output)

Details of the permutations and scaling factors applied when balancing A. If $P(j)$ is the index of the row and column interchanged with row and column j , and $D(j)$ is the scaling factor applied to row and column j , then $SCALE(J) = P(J)$, for $J = 1, \dots, ILO-1 = D(J)$, for $J = ILO, \dots, IHI = P(J)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

ABNRM (output)

The one-norm of the balanced matrix (the maximum of the sum of absolute values of elements of any column).

RCONE (output)

RCONE(j) is the reciprocal condition number of the j-th eigenvalue.

RCONV (output)

RCONV(j) is the reciprocal condition number of the j-th right eigenvector.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. If SENSE = 'N' or 'E', LDWORK \geq max(1,2*N), and if JOBVL = 'V' or JOBVR = 'V', LDWORK \geq 3*N. If SENSE = 'V' or 'B', LDWORK \geq N*(N+6). For good performance, LDWORK must generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

IWORK2 (workspace)

dimension(2*N-2) If SENSE = 'N' or 'E', not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the QR algorithm failed to compute all the eigenvalues, and no eigenvectors or condition numbers have been computed; elements 1:ILO-1 and i+1:N of WR and WI contain eigenvalues which have converged.

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NAME

sgegs - routine is deprecated and has been replaced by routine SGGES

SYNOPSIS

```
SUBROUTINE SGECS(JOBVSL, JOBVSR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,
                BETA, VSL, LDVSL, VSR, LDVSR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR
INTEGER N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
```

```
SUBROUTINE SGECS_64(JOBVSL, JOBVSR, N, A, LDA, B, LDB, ALPHAR,
                   ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR
INTEGER*8 N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEGS(JOBVSL, JOBVSR, [N], A, [LDA], B, [LDB], ALPHAR,
                ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR
INTEGER :: N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL, DIMENSION(:,:) :: A, B, VSL, VSR
```

```
SUBROUTINE GEGS_64(JOBVSL, JOBVSR, [N], A, [LDA], B, [LDB], ALPHAR,
                  ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR
INTEGER(8) :: N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL, DIMENSION(:,:) :: A, B, VSL, VSR
```

C INTERFACE

```
#include <sunperf.h>
```

```

void sgegs(char jobvsl, char jobvsr, int n, float *a, int
lda, float *b, int ldb, float *alphan, float
*alphai, float *beta, float *vsl, int ldvsl, float
*vsvr, int ldvsr, int *info);
void sgegs_64(char jobvsl, char jobvsr, long n, float *a,
long lda, float *b, long ldb, float *alphan, float
*alphai, float *beta, float *vsl, long ldvsl,
float *vsvr, long ldvsr, long *info);

```

PURPOSE

sgegs routine is deprecated and has been replaced by routine SGGES.

SGEGS computes for a pair of N-by-N real nonsymmetric matrices A, B: the generalized eigenvalues (alphan +/- alphai*i, beta), the real Schur form (A, B), and optionally left and/or right Schur vectors (VSL and VSR).

(If only the generalized eigenvalues are needed, use the driver SGEV instead.)

A generalized eigenvalue for a pair of matrices (A,B) is, roughly speaking, a scalar w or a ratio alpha/beta = w, such that A - w*B is singular. It is usually represented as the pair (alpha,beta), as there is a reasonable interpretation for beta=0, and even for both being zero. A good beginning reference is the book, "Matrix Computations", by G. Golub & C. van Loan (Johns Hopkins U. Press)

The (generalized) Schur form of a pair of matrices is the result of multiplying both matrices on the left by one orthogonal matrix and both on the right by another orthogonal matrix, these two orthogonal matrices being chosen so as to bring the pair of matrices into (real) Schur form.

A pair of matrices A, B is in generalized real Schur form if B is upper triangular with non-negative diagonal and A is block upper triangular with 1-by-1 and 2-by-2 blocks. 1-by-1 blocks correspond to real generalized eigenvalues, while 2-by-2 blocks of A will be "standardized" by making the corresponding elements of B have the form:

$$\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$$

and the pair of corresponding 2-by-2 blocks in A and B will have a complex conjugate pair of generalized eigenvalues.

The left and right Schur vectors are the columns of VSL and VSR, respectively, where VSL and VSR are the orthogonal matrices which reduce A and B to Schur form:

Schur form of (A,B) = ((VSL)**T A (VSR), (VSL)**T B (VSR))

ARGUMENTS

JOBVSL (input)
 = 'N': do not compute the left Schur vectors;
 = 'V': compute the left Schur vectors.

JOBVSR (input)
 = 'N': do not compute the right Schur vectors;
 = 'V': compute the right Schur vectors.

N (input) The order of the matrices A, B, VSL, and VSR. N
 >= 0.

A (input/output)
 On entry, the first of the pair of matrices whose
 generalized eigenvalues and (optionally) Schur
 vectors are to be computed. On exit, the general-
 ized Schur form of A. Note: to avoid overflow,
 the Frobenius norm of the matrix A should be less
 than the overflow threshold.

LDA (input)
 The leading dimension of A. LDA >= max(1,N).

B (input/output)
 On entry, the second of the pair of matrices whose
 generalized eigenvalues and (optionally) Schur
 vectors are to be computed. On exit, the general-
 ized Schur form of B. Note: to avoid overflow,
 the Frobenius norm of the matrix B should be less
 than the overflow threshold.

LDB (input)
 The leading dimension of B. LDB >= max(1,N).

ALPHAR (output)
 On exit, $(\text{ALPHAR}(j) + \text{ALPHAI}(j)*i)/\text{BETA}(j)$,
 $j=1,\dots,N$, will be the generalized eigenvalues.
 $\text{ALPHAR}(j) + \text{ALPHAI}(j)*i$, $j=1,\dots,N$ and
 $\text{BETA}(j)$, $j=1,\dots,N$ are the diagonals of the com-
 plex Schur form (A,B) that would result if the 2-
 by-2 diagonal blocks of the real Schur form of
 (A,B) were further reduced to triangular form
 using 2-by-2 complex unitary transformations. If
 $\text{ALPHAI}(j)$ is zero, then the j-th eigenvalue is
 real; if positive, then the j-th and (j+1)-st
 eigenvalues are a complex conjugate pair, with
 $\text{ALPHAI}(j+1)$ negative.

Note: the quotients $\text{ALPHAR}(j)/\text{BETA}(j)$ and
 $\text{ALPHAI}(j)/\text{BETA}(j)$ may easily over- or underflow,
 and $\text{BETA}(j)$ may even be zero. Thus, the user
 should avoid naively computing the ratio
 alpha/beta. However, ALPHAR and ALPHAI will be
 always less than and usually comparable with
 norm(A) in magnitude, and BETA always less than
 and usually comparable with norm(B).

ALPHAI (output)
 See the description for ALPHAR.

BETA (output)

See the description for ALPHAR.

VSL (input)

If JOBVSL = 'V', VSL will contain the left Schur vectors. (See "Purpose", above.) Not referenced if JOBVSL = 'N'.

LDVSL (input)

The leading dimension of the matrix VSL. LDVSL ≥ 1 , and if JOBVSL = 'V', LDVSL $\geq N$.

VSR (input)

If JOBVSR = 'V', VSR will contain the right Schur vectors. (See "Purpose", above.) Not referenced if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR ≥ 1 , and if JOBVSR = 'V', LDVSR $\geq N$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK $\geq \max(1, 4*N)$. For good performance, LDWORK must generally be larger. To compute the optimal value of LDWORK, call ILAENV to get blocksizes (for SGEQRF, SORMQR, and SORGQR.) Then compute: NB -- MAX of the blocksizes for SGEQRF, SORMQR, and SORGQR The optimal LDWORK is $2*N + N*(NB+1)$.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for $j=INFO+1, \dots, N$.
> N: errors that usually indicate LAPACK problems:
=N+1: error return from SGBAL
=N+2: error return from SGEQRF
=N+3: error return from SORMQR
=N+4: error return from SORGQR
=N+5: error return from SGGHRD
=N+6: error return from SHGEQZ (other than failed iteration) =N+7: error return from SGGBAK (computing VSL)
=N+8: error return from SGGBAK (computing VSR)
=N+9: error return from SLASCL (various places)

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NAME

sggev - routine is deprecated and has been replaced by routine SGGEV

SYNOPSIS

```
SUBROUTINE SGGEV(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,
                 BETA, VL, LDVL, VR, LDVR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
INTEGER N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
VL(LDVL,*), VR(LDVR,*), WORK(*)
```

```
SUBROUTINE SGGEV_64(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,
                   BETA, VL, LDVL, VR, LDVR, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
INTEGER*8 N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
VL(LDVL,*), VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEGV(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHAR,
                ALPHAI, BETA, VL, [LDVL], VR, [LDVR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
INTEGER :: N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL, DIMENSION(:, :) :: A, B, VL, VR
```

```
SUBROUTINE GEGV_64(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHAR,
                  ALPHAI, BETA, VL, [LDVL], VR, [LDVR], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL, DIMENSION(:, :) :: A, B, VL, VR
```

C INTERFACE

```
#include <sunperf.h>

void sgegv(char jobvl, char jobvr, int n, float *a, int lda,
           float *b, int ldb, float *alphar, float *alphai,
           float *beta, float *vl, int ldvl, float *vr, int
           ldvr, int *info);
void sgegv_64(char jobvl, char jobvr, long n, float *a, long
              lda, float *b, long ldb, float *alphar, float
              *alphai, float *beta, float *vl, long ldvl, float
              *vr, long ldvr, long *info);
```

PURPOSE

sgegv routine is deprecated and has been replaced by routine SGGEV.

SGEGV computes for a pair of n-by-n real nonsymmetric matrices A and B, the generalized eigenvalues ($\alpha \pm i\beta$), and optionally, the left and/or right generalized eigenvectors (VL and VR).

A generalized eigenvalue for a pair of matrices (A,B) is, roughly speaking, a scalar w or a ratio $\alpha/\beta = w$, such that $A - wB$ is singular. It is usually represented as the pair (α, β), as there is a reasonable interpretation for $\beta=0$, and even for both being zero. A good beginning reference is the book, "Matrix Computations", by G. Golub & C. van Loan (Johns Hopkins U. Press)

A right generalized eigenvector corresponding to a generalized eigenvalue w for a pair of matrices (A,B) is a vector r such that $(A - wB)r = 0$. A left generalized eigenvector is a vector l such that $l^*H * (A - wB) = 0$, where l^*H is the conjugate-transpose of l.

Note: this routine performs "full balancing" on A and B -- see "Further Details", below.

ARGUMENTS

JOBVL (input)
= 'N': do not compute the left generalized eigenvectors;
= 'V': compute the left generalized eigenvectors.

JOBVR (input)
= 'N': do not compute the right generalized eigenvectors;
= 'V': compute the right generalized eigenvectors.

N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)

On entry, the first of the pair of matrices whose generalized eigenvalues and (optionally) generalized eigenvectors are to be computed. On exit, the contents will have been destroyed. (For a description of the contents of A on exit, see "Further Details", below.)

LDA (input)

The leading dimension of A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the second of the pair of matrices whose generalized eigenvalues and (optionally) generalized eigenvectors are to be computed. On exit, the contents will have been destroyed. (For a description of the contents of B on exit, see "Further Details", below.)

LDB (input)

The leading dimension of B. $LDB \geq \max(1, N)$.

ALPHAR (output)

On exit, $(ALPHAR(j) + ALPHAI(j)*i)/BETA(j)$, $j=1, \dots, N$, will be the generalized eigenvalues. If $ALPHAI(j)$ is zero, then the j -th eigenvalue is real; if positive, then the j -th and $(j+1)$ -st eigenvalues are a complex conjugate pair, with $ALPHAI(j+1)$ negative.

Note: the quotients $ALPHAR(j)/BETA(j)$ and $ALPHAI(j)/BETA(j)$ may easily over- or underflow, and $BETA(j)$ may even be zero. Thus, the user should avoid naively computing the ratio α/β . However, $ALPHAR$ and $ALPHAI$ will be always less than and usually comparable with $\text{norm}(A)$ in magnitude, and $BETA$ always less than and usually comparable with $\text{norm}(B)$.

ALPHAI (output)

See the description of $ALPHAR$.

BETA (output)

See the description of $ALPHAR$.

VL (output)

If $JOBVL = 'V'$, the left generalized eigenvectors. (See "Purpose", above.) Real eigenvectors take one column, complex take two columns, the first for the real part and the second for the imaginary part. Complex eigenvectors correspond to an eigenvalue with positive imaginary part. Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha=\beta=0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if $JOBVL = 'N'$.

LDVL (input)

The leading dimension of the matrix VL. $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (output)

If JOBVR = 'V', the right generalized eigenvectors. (See "Purpose", above.) Real eigenvectors take one column, complex take two columns, the first for the real part and the second for the imaginary part. Complex eigenvectors correspond to an eigenvalue with positive imaginary part. Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha = \beta = 0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if JOBVR = 'N'.

LDVR (input)

The leading dimension of the matrix VR. LDVR ≥ 1 , and if JOBVR = 'V', LDVR $\geq N$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK $\geq \max(1, 8*N)$. For good performance, LDWORK must generally be larger. To compute the optimal value of LDWORK, call ILAENV to get block sizes (for SGEQRF, SORMQR, and SORGQR.) Then compute: NB -- MAX of the block sizes for SGEQRF, SORMQR, and SORGQR; The optimal LDWORK is: $2*N + \text{MAX}(6*N, N*(NB+1))$.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. No eigenvectors have been calculated, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for $j = \text{INFO} + 1, \dots, N$.
> N: errors that usually indicate LAPACK problems:
=N+1: error return from SGBAL
=N+2: error return from SGEQRF
=N+3: error return from SORMQR
=N+4: error return from SORGQR
=N+5: error return from SGGHRD
=N+6: error return from SHGEQZ (other than failed iteration)
=N+7: error return from STGEVC
=N+8: error return from SGGBAK (computing VL)
=N+9: error return from SGGBAK (computing VR)
=N+10: error return from SLASCL (various calls)

FURTHER DETAILS

Balancing

This driver calls SGGBAL to both permute and scale rows and columns of A and B. The permutations PL and PR are chosen so that PL^*A^*PR and PL^*B^*R will be upper triangular except for the diagonal blocks $A(i:j,i:j)$ and $B(i:j,i:j)$, with i and j as close together as possible. The diagonal scaling matrices DL and DR are chosen so that the pair $DL^*PL^*A^*PR^*DR$, $DL^*PL^*B^*PR^*DR$ have elements close to one (except for the elements that start out zero.)

After the eigenvalues and eigenvectors of the balanced matrices have been computed, SGGBAK transforms the eigenvectors back to what they would have been (in perfect arithmetic) if they had not been balanced.

Contents of A and B on Exit

If any eigenvectors are computed (either $JOBVL='V'$ or $JOBVR='V'$ or both), then on exit the arrays A and B will contain the real Schur form[*] of the "balanced" versions of A and B. If no eigenvectors are computed, then only the diagonal blocks will be correct.

[*] See SHGEQZ, SGEQS, or read the book "Matrix Computations",

by Golub & van Loan, pub. by Johns Hopkins U. Press.

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NAME

sgehrd - reduce a real general matrix A to upper Hessenberg form H by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE SGEHRD(N, ILO, IHI, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
INTEGER N, ILO, IHI, LDA, LWORKIN, INFO  
REAL A(LDA,*), TAU(*), WORKIN(*)
```

```
SUBROUTINE SGEHRD_64(N, ILO, IHI, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
INTEGER*8 N, ILO, IHI, LDA, LWORKIN, INFO  
REAL A(LDA,*), TAU(*), WORKIN(*)
```

F95 INTERFACE

```
SUBROUTINE GEHRD([N], ILO, IHI, A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
INTEGER :: N, ILO, IHI, LDA, LWORKIN, INFO  
REAL, DIMENSION(:) :: TAU, WORKIN  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE GEHRD_64([N], ILO, IHI, A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
INTEGER(8) :: N, ILO, IHI, LDA, LWORKIN, INFO  
REAL, DIMENSION(:) :: TAU, WORKIN  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgehrd(int n, int ilo, int ihi, float *a, int lda,  
float *tau, int *info);
```

```
void sgehrd_64(long n, long ilo, long ihi, float *a, long  
lda, float *tau, long *info);
```

PURPOSE

sgehrd reduces a real general matrix A to upper Hessenberg form H by an orthogonal similarity transformation: $Q' * A * Q = H$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to SGEBAL; otherwise they should be set to 1 and N respectively. See Further Details.

IHI (input)

See the description of ILO.

A (input/output)

On entry, the N-by-N general matrix to be reduced. On exit, the upper triangle and the first subdiagonal of A are overwritten with the upper Hessenberg matrix H, and the elements below the first subdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details). Elements 1:ILO-1 and IHI:N-1 of TAU are set to zero.

WORKIN (workspace)

On exit, if INFO = 0, WORKIN(1) returns the optimal LWORKIN.

LWORKIN (input)

The length of the array WORKIN. $LWORKIN \geq \max(1, N)$. For optimum performance $LWORKIN \geq N * NB$, where NB is the optimal blocksize.

If LWORKIN = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORKIN array, returns this value as the first entry of the WORKIN array, and no error message related to LWORKIN is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-

gal value.

FURTHER DETAILS

The matrix Q is represented as a product of $(ihi-ilo)$ elementary reflectors

$$Q = H(ilo) H(ilo+1) \dots H(ihi-1).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real scalar, and v is a real vector with $v(1:i) = 0$, $v(i+1) = 1$ and $v(ihi+1:n) = 0$; $v(i+2:ihi)$ is stored on exit in $A(i+2:ihi,i)$, and τ in $TAU(i)$.

The contents of A are illustrated by the following example, with $n = 7$, $ilo = 2$ and $ihi = 6$:

on entry,

on exit,

```
( a a a a a a a ) ( a a h h h h
a ) ( a a a a a a a ) ( a h h h
h a ) ( a a a a a a a ) ( h h h
h h h ) ( a a a a a a a ) ( v2 h
h h h h ) ( a a a a a a a ) ( v2
v3 h h h h ) ( a a a a a a ) (
v2 v3 v4 h h h ) ( a ) (
a )
```

where a denotes an element of the original matrix A , h denotes a modified element of the upper Hessenberg matrix H , and v_i denotes an element of the vector defining $H(i)$.

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NAME

sgelqf - compute an LQ factorization of a real M-by-N matrix
A

SYNOPSIS

```
SUBROUTINE SGELQF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SGELQF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELQF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GELQF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgelqf(int m, int n, float *a, int lda, float *tau, int  
*info);
```

```
void sgelqf_64(long m, long n, float *a, long lda, float  
*tau, long *info);
```

PURPOSE

sgelqf computes an LQ factorization of a real M-by-N matrix A: $A = L * Q$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the elements on and below the diagonal of the array contain the m-by-min(m,n) lower trapezoidal matrix L (L is lower triangular if $m \leq n$); the elements above the diagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, M)$. For optimum performance $LDWORK \geq M * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(k) \dots H(2) H(1), \text{ where } k = \min(m, n).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with
 $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:n)$ is stored on exit in
 $A(i,i+1:n)$, and tau in $TAU(i)$.

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NAME

sgels - solve overdetermined or underdetermined real linear systems involving an M-by-N matrix A, or its transpose, using a QR or LQ factorization of A

SYNOPSIS

```
SUBROUTINE SGELS(TRANSA, M, N, NRHS, A, LDA, B, LDB, WORK, LDWORK,  
INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER M, N, NRHS, LDA, LDB, LDWORK, INFO  
REAL A(LDA,*), B(LDB,*), WORK(*)
```

```
SUBROUTINE SGELS_64(TRANSA, M, N, NRHS, A, LDA, B, LDB, WORK, LDWORK,  
INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 M, N, NRHS, LDA, LDB, LDWORK, INFO  
REAL A(LDA,*), B(LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELS([TRANSA], [M], [N], [NRHS], A, [LDA], B, [LDB], [WORK],  
LDWORK, [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: M, N, NRHS, LDA, LDB, LDWORK, INFO  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE GELS_64([TRANSA], [M], [N], [NRHS], A, [LDA], B, [LDB],  
[WORK], LDWORK, [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: M, N, NRHS, LDA, LDB, LDWORK, INFO  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```

void sgels (char, int, int, int, float*, int, float*, int,
            int*);

void sgels_64 (char, long, long, long, float*, long, float*,
              long, long*);

```

PURPOSE

sgels solves overdetermined or underdetermined real linear systems involving an M-by-N matrix A, or its transpose, using a QR or LQ factorization of A. It is assumed that A has full rank.

The following options are provided:

1. If TRANS = 'N' and $m \geq n$: find the least squares solution of
 an overdetermined system, i.e., solve the least squares problem

$$\text{minimize } \| B - A * X \|^2.$$

2. If TRANS = 'N' and $m < n$: find the minimum norm solution of
 an underdetermined system $A * X = B$.

3. If TRANS = 'T' and $m \geq n$: find the minimum norm solution of
 an undetermined system $A^{**T} * X = B$.

4. If TRANS = 'T' and $m < n$: find the least squares solution of
 an overdetermined system, i.e., solve the least squares problem

$$\text{minimize } \| B - A^{**T} * X \|^2.$$

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

ARGUMENTS

TRANSA (input)
 = 'N': the linear system involves A;
 = 'T': the linear system involves A**T.
 TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS ≥ 0 .

A (input/output)

On entry, the M-by-N matrix A. On exit, if $M \geq N$, A is overwritten by details of its QR factorization as returned by SGEQRF; if $M < N$, A is overwritten by details of its LQ factorization as returned by SGELQF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)

On entry, the matrix B of right hand side vectors, stored columnwise; B is M-by-NRHS if TRANSA = 'N', or N-by-NRHS if TRANSA = 'T'. On exit, B is overwritten by the solution vectors, stored columnwise: if TRANSA = 'N' and $m \geq n$, rows 1 to n of B contain the least squares solution vectors; the residual sum of squares for the solution in each column is given by the sum of squares of elements N+1 to M in that column; if TRANSA = 'N' and $m < n$, rows 1 to N of B contain the minimum norm solution vectors; if TRANSA = 'T' and $m \geq n$, rows 1 to M of B contain the minimum norm solution vectors; if TRANSA = 'T' and $m < n$, rows 1 to M of B contain the least squares solution vectors; the residual sum of squares for the solution in each column is given by the sum of squares of elements M+1 to N in that column.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, M, N)$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (output)

The dimension of the array WORK. $LDWORK \geq \max(1, MN + \max(MN, NRHS))$. For optimal performance, $LDWORK \geq \max(1, MN + \max(MN, NRHS) * NB)$, where $MN = \min(M, N)$ and NB is the optimum block size.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sgelsd - compute the minimum-norm solution to a real linear least squares problem

SYNOPSIS

```
SUBROUTINE SGELSD(M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK, WORK,  
                 LWORK, IWORK, INFO)
```

```
INTEGER M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER IWORK(*)  
REAL RCOND  
REAL A(LDA,*), B(LDB,*), S(*), WORK(*)
```

```
SUBROUTINE SGELSD_64(M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK,  
                    WORK, LWORK, IWORK, INFO)
```

```
INTEGER*8 M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER*8 IWORK(*)  
REAL RCOND  
REAL A(LDA,*), B(LDB,*), S(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSD([M], [N], [NRHS], A, [LDA], B, [LDB], S, RCOND,  
                RANK, [WORK], [LWORK], [IWORK], [INFO])
```

```
INTEGER :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL :: RCOND  
REAL, DIMENSION(:) :: S, WORK  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE GELSD_64([M], [N], [NRHS], A, [LDA], B, [LDB], S, RCOND,  
                   RANK, [WORK], [LWORK], [IWORK], [INFO])
```

```
INTEGER(8) :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER(8), DIMENSION(:) :: IWORK  
REAL :: RCOND  
REAL, DIMENSION(:) :: S, WORK
```

REAL, DIMENSION(:,:) :: A, B

C INTERFACE

```
#include <sunperf.h>
```

```
void sgelsd(int m, int n, int nrhs, float *a, int lda, float  
           *b, int ldb, float *s, float rcond, int *rank, int  
           *info);
```

```
void sgelsd_64(long m, long n, long nrhs, float *a, long  
              lda, float *b, long ldb, float *s, float rcond,  
              long *rank, long *info);
```

PURPOSE

sgelsd computes the minimum-norm solution to a real linear least squares problem:

$$\text{minimize } 2\text{-norm}(|b - A*x|)$$

using the singular value decomposition (SVD) of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The problem is solved in three steps:

- (1) Reduce the coefficient matrix A to bidiagonal form with Householder transformations, reducing the original problem into a "bidiagonal least squares problem" (BLS)
- (2) Solve the BLS using a divide and conquer approach.
- (3) Apply back all the Householder transformations to solve the original least squares problem.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

M (input) The number of rows of A. M >= 0.

N (input) The number of columns of A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)

On entry, the M-by-N matrix A. On exit, A has been destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, B is overwritten by the N-by-NRHS solution matrix X. If $m \geq n$ and $RANK = n$, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements $n+1:m$ in that column.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, \max(M, N))$.

S (output)

The singular values of A in decreasing order. The condition number of A in the 2-norm = $S(1)/S(\min(m, n))$.

RCOND (input)

RCOND is used to determine the effective rank of A. Singular values $S(i) \leq RCOND * S(1)$ are treated as zero. If $RCOND < 0$, machine precision is used instead.

RANK (output)

The effective rank of A, i.e., the number of singular values which are greater than $RCOND * S(1)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq 1$. The exact minimum amount of workspace needed depends on M, N and NRHS. As long as LWORK is at least $12 * N + 2 * N * SMLSIZ + 8 * N * NLVL + N * NRHS * (SMLSIZ + 1) ** 2$, if M is greater than or equal to N or $12 * M + 2 * M * SMLSIZ + 8 * M * NLVL + M * NRHS + (SMLSIZ + 1) ** 2$, if M is less than N, the code will execute correctly. SMLSIZ is returned by ILAENV and is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25), and $NLVL = \text{INT}(\text{LOG}_2(\text{MIN}(M, N) / (SMLSIZ + 1))) + 1$. For good performance, LWORK should generally be larger.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)

$LIWORK \geq 3 * \text{MINMN} * NLVL + 11 * \text{MINMN}$, where

MINMN = MIN(M,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: the algorithm for computing the SVD failed to converge; if INFO = i, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

FURTHER DETAILS

Based on contributions by

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University of California at Berkeley, USA

Osni Marques, LBNL/NERSC, USA

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NAME

sgelss - compute the minimum norm solution to a real linear least squares problem

SYNOPSIS

```
SUBROUTINE SGELSS(M, N, NRHS, A, LDA, B, LDB, SING, RCOND, IRANK,  
                 WORK, LDWORK, INFO)
```

```
INTEGER M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL RCOND  
REAL A(LDA,*), B(LDB,*), SING(*), WORK(*)
```

```
SUBROUTINE SGELSS_64(M, N, NRHS, A, LDA, B, LDB, SING, RCOND, IRANK,  
                    WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL RCOND  
REAL A(LDA,*), B(LDB,*), SING(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSS([M], [N], [NRHS], A, [LDA], B, [LDB], SING, RCOND,  
                IRANK, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: SING, WORK  
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GELSS_64([M], [N], [NRHS], A, [LDA], B, [LDB], SING,  
                   RCOND, IRANK, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: SING, WORK  
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgelss(int m, int n, int nrhs, float *a, int lda, float
```

```

        *b, int ldb, float *sing, float rcond, int *irank,
        int *info);

void sgelss_64(long m, long n, long nrhs, float *a, long
        lda, float *b, long ldb, float *sing, float rcond,
        long *irank, long *info);

```

PURPOSE

sgelss computes the minimum norm solution to a real linear least squares problem:

Minimize 2-norm($| b - A*x |$).

using the singular value decomposition (SVD) of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the first $\min(m,n)$ rows of A are overwritten with its right singular vectors, stored rowwise.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, B is overwritten by the N-by-NRHS solution matrix X. If $m \geq n$ and $IRANK = n$, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements $n+1:m$ in that column.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,\max(M,N))$.

SING (output)

The singular values of A in decreasing order. The condition number of A in the 2-norm = $SING(1)/SING(\min(m,n))$.

RCOND (input)

RCOND is used to determine the effective rank of A. Singular values $SING(i) \leq RCOND * SING(1)$ are treated as zero. If $RCOND < 0$, machine precision is used instead.

IRANK (output)

The effective rank of A, i.e., the number of singular values which are greater than $RCOND * SING(1)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq 1$, and also: $LDWORK \geq 3 * \min(M,N) + \max(2 * \min(M,N), \max(M,N), NRHS)$ For good performance, LDWORK should generally be larger.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value.
> 0: the algorithm for computing the SVD failed to converge; if $INFO = i$, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

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NAME

sgelsx - routine is deprecated and has been replaced by routine SGELSY

SYNOPSIS

```
SUBROUTINE SGELSX(M, N, NRHS, A, LDA, B, LDB, JPIVOT, RCOND, IRANK,  
  WORK, INFO)
```

```
INTEGER M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER JPIVOT(*)  
REAL RCOND  
REAL A(LDA,*), B(LDB,*), WORK(*)
```

```
SUBROUTINE SGELSX_64(M, N, NRHS, A, LDA, B, LDB, JPIVOT, RCOND,  
  IRANK, WORK, INFO)
```

```
INTEGER*8 M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER*8 JPIVOT(*)  
REAL RCOND  
REAL A(LDA,*), B(LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSX([M], [N], [NRHS], A, [LDA], B, [LDB], JPIVOT, RCOND,  
  IRANK, [WORK], [INFO])
```

```
INTEGER :: M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER, DIMENSION(:) :: JPIVOT  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE GELSX_64([M], [N], [NRHS], A, [LDA], B, [LDB], JPIVOT,  
  RCOND, IRANK, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER(8), DIMENSION(:) :: JPIVOT  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>

void sgelsx(int m, int n, int nrhs, float *a, int lda, float
            *b, int ldb, int *jpivot, float rcond, int *irank,
            int *info);
void sgelsx_64(long m, long n, long nrhs, float *a, long
               lda, float *b, long ldb, long *jpivot, float
               rcond, long *irank, long *info);
```

PURPOSE

sgelsx routine is deprecated and has been replaced by routine SGELSY.

SGELSX computes the minimum-norm solution to a real linear least squares problem:

$$\text{minimize } || A * X - B ||$$

using a complete orthogonal factorization of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The routine first computes a QR factorization with column pivoting:

$$A * P = Q * \begin{bmatrix} R11 & R12 \\ 0 & R22 \end{bmatrix}$$

with R11 defined as the largest leading submatrix whose estimated condition number is less than 1/RCOND. The order of R11, RANK, is the effective rank of A.

Then, R22 is considered to be negligible, and R12 is annihilated by orthogonal transformations from the right, arriving at the complete orthogonal factorization:

$$A * P = Q * \begin{bmatrix} T11 & 0 \\ 0 & 0 \end{bmatrix} * Z$$

The minimum-norm solution is then

$$X = P * Z' \begin{bmatrix} \text{inv}(T11)*Q1'*B \\ 0 \end{bmatrix}$$

where Q1 consists of the first RANK columns of Q.

ARGUMENTS

M (input) The number of rows of the matrix A. M >= 0.

N (input) The number of columns of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of matrices B and X. NRHS >= 0.

A (input/output)

On entry, the M-by-N matrix A. On exit, A has been overwritten by details of its complete

orthogonal factorization.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,M).

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, the N-by-NRHS solution matrix X. If $m \geq n$ and IRANK = n, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements N+1:M in that column.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,M,N).

JPIVOT (input/output)

On entry, if JPIVOT(i) \neq 0, the i-th column of A is an initial column, otherwise it is a free column. Before the QR factorization of A, all initial columns are permuted to the leading positions; only the remaining free columns are moved as a result of column pivoting during the factorization. On exit, if JPIVOT(i) = k, then the i-th column of A*P was the k-th column of A.

RCOND (input)

RCOND is used to determine the effective rank of A, which is defined as the order of the largest leading triangular submatrix R11 in the QR factorization with pivoting of A, whose estimated condition number $< 1/\text{RCOND}$.

IRANK (output)

The effective rank of A, i.e., the order of the submatrix R11. This is the same as the order of the submatrix T11 in the complete orthogonal factorization of A.

WORK (workspace)

(max(min(M,N)+3*N, 2*min(M,N)+NRHS)),

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sgelsy - compute the minimum-norm solution to a real linear least squares problem

SYNOPSIS

```
SUBROUTINE SGELSY(M, N, NRHS, A, LDA, B, LDB, JPVT, RCOND, RANK,  
                WORK, LWORK, INFO)
```

```
INTEGER M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER JPVT(*)  
REAL RCOND  
REAL A(LDA,*), B(LDB,*), WORK(*)
```

```
SUBROUTINE SGELSY_64(M, N, NRHS, A, LDA, B, LDB, JPVT, RCOND, RANK,  
                   WORK, LWORK, INFO)
```

```
INTEGER*8 M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER*8 JPVT(*)  
REAL RCOND  
REAL A(LDA,*), B(LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSY([M], [N], [NRHS], A, [LDA], B, [LDB], JPVT, RCOND,  
                RANK, [WORK], [LWORK], [INFO])
```

```
INTEGER :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER, DIMENSION(:) :: JPVT  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE GELSY_64([M], [N], [NRHS], A, [LDA], B, [LDB], JPVT,  
                   RCOND, RANK, [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER(8), DIMENSION(:) :: JPVT  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK
```

REAL, DIMENSION(:,:) :: A, B

C INTERFACE

```
#include <sunperf.h>

void sgelsy(int m, int n, int nrhs, float *a, int lda, float
           *b, int ldb, int *jpvt, float rcond, int *rank,
           int *info);
void sgelsy_64(long m, long n, long nrhs, float *a, long
              lda, float *b, long ldb, long *jpvt, float rcond,
              long *rank, long *info);
```

PURPOSE

sgelsy computes the minimum-norm solution to a real linear least squares problem:

minimize $\| A * X - B \|^2$

using a complete orthogonal factorization of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The routine first computes a QR factorization with column pivoting:

$$A * P = Q * \begin{bmatrix} R11 & R12 \\ 0 & R22 \end{bmatrix}$$

with R11 defined as the largest leading submatrix whose estimated condition number is less than 1/RCOND. The order of R11, RANK, is the effective rank of A.

Then, R22 is considered to be negligible, and R12 is annihilated by orthogonal transformations from the right, arriving at the complete orthogonal factorization:

$$A * P = Q * \begin{bmatrix} T11 & 0 \\ 0 & 0 \end{bmatrix} * Z$$

The minimum-norm solution is then

$$X = P * Z' * \begin{bmatrix} \text{inv}(T11) * Q1' * B \\ 0 \end{bmatrix}$$

where Q1 consists of the first RANK columns of Q.

This routine is basically identical to the original xGELSX except three differences:

- o The call to the subroutine xGEQPF has been substituted by the

- the call to the subroutine xGEQP3. This subroutine is a Blas-3

- version of the QR factorization with column pivoting.

- o Matrix B (the right hand side) is updated with Blas-3.

- o The permutation of matrix B (the right hand side) is faster and

- more simple.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of matrices B and X. $NRHS \geq 0$.

A (input/output)
On entry, the M-by-N matrix A. On exit, A has been overwritten by details of its complete orthogonal factorization.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
On entry, the M-by-NRHS right hand side matrix B. On exit, the N-by-NRHS solution matrix X.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, M, N)$.

JPVT (input/output)
On entry, if $JPVT(i) \neq 0$, the i-th column of A is permuted to the front of AP, otherwise column i is a free column. On exit, if $JPVT(i) = k$, then the i-th column of AP was the k-th column of A.

RCOND (input)
RCOND is used to determine the effective rank of A, which is defined as the order of the largest leading triangular submatrix R11 in the QR factorization with pivoting of A, whose estimated condition number $< 1/RCOND$.

RANK (output)
The effective rank of A, i.e., the order of the submatrix R11. This is the same as the order of the submatrix T11 in the complete orthogonal factorization of A.

WORK (workspace)
On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. The unblocked strategy requires that: $LWORK \geq \max(MN + 3*N + 1, 2*MN + NRHS)$, where $MN = \min(M, N)$. The block algorithm requires that: $LWORK \geq \max(MN + 2*N + NB*(N+1), 2*MN + NB*NRHS)$, where NB is an upper bound on the blocksize returned by ILAENV for the routines SGEQP3, STZRZF, STZRQF, SORMQR, and SORMRZ.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message

related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: If INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

Based on contributions by

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E. Quintana-Orti, Depto. de Informatica, Universidad Jaime I, Spain

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NAME

sgemm - perform one of the matrix-matrix operations C :=
alpha*op(A)*op(B) + beta*C

SYNOPSIS

```
SUBROUTINE SGEMM(TRANSA, TRANSB, M, N, K, ALPHA, A, LDA, B, LDB,  
                  BETA, C, LDC)
```

```
CHARACTER * 1 TRANSA, TRANSB  
INTEGER M, N, K, LDA, LDB, LDC  
REAL ALPHA, BETA  
REAL A(LDA,*), B(LDB,*), C(LDC,*)
```

```
SUBROUTINE SGEMM_64(TRANSA, TRANSB, M, N, K, ALPHA, A, LDA, B, LDB,  
                    BETA, C, LDC)
```

```
CHARACTER * 1 TRANSA, TRANSB  
INTEGER*8 M, N, K, LDA, LDB, LDC  
REAL ALPHA, BETA  
REAL A(LDA,*), B(LDB,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE GEMM([TRANSA], [TRANSB], [M], [N], [K], ALPHA, A, [LDA],  
                B, [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: TRANSA, TRANSB  
INTEGER :: M, N, K, LDA, LDB, LDC  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:,:) :: A, B, C
```

```
SUBROUTINE GEMM_64([TRANSA], [TRANSB], [M], [N], [K], ALPHA, A, [LDA],  
                  B, [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: TRANSA, TRANSB  
INTEGER(8) :: M, N, K, LDA, LDB, LDC  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:,:) :: A, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgemm(char transa, char transb, int m, int n, int k,
           float alpha, float *a, int lda, float *b, int ldb,
           float beta, float *c, int ldc);
```

```
void sgemm_64(char transa, char transb, long m, long n, long
              k, float alpha, float *a, long lda, float *b, long
              ldb, float beta, float *c, long ldc);
```

PURPOSE

sgemm performs one of the matrix-matrix operations $C := \alpha * \text{op}(A) * \text{op}(B) + \beta * C$ where $\text{op}(X)$ is one of

$\text{op}(X) = X$ or $\text{op}(X) = X'$,

alpha and beta are scalars, and A, B and C are matrices, with $\text{op}(A)$ an m by k matrix, $\text{op}(B)$ a k by n matrix and C an m by n matrix.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n', $\text{op}(A) = A$.

TRANSA = 'T' or 't', $\text{op}(A) = A'$.

TRANSA = 'C' or 'c', $\text{op}(A) = A'$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

TRANSB (input)

On entry, TRANSB specifies the form of $\text{op}(B)$ to be used in the matrix multiplication as follows:

TRANSB = 'N' or 'n', $\text{op}(B) = B$.

TRANSB = 'T' or 't', $\text{op}(B) = B'$.

TRANSB = 'C' or 'c', $\text{op}(B) = B'$.

Unchanged on exit.

TRANSB is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix $\text{op}(A)$ and of the matrix C. M must be at least zero. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of

the matrix $op(B)$ and the number of columns of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry, K specifies the number of columns of the matrix $op(A)$ and the number of rows of the matrix $op(B)$. K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

REAL array of DIMENSION (LDA, ka), where ka is k when $TRANS A = 'N'$ or $'n'$, and is m otherwise. Before entry with $TRANS A = 'N'$ or $'n'$, the leading m by k part of the array A must contain the matrix A , otherwise the leading k by m part of the array A must contain the matrix A . Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When $TRANS A = 'N'$ or $'n'$ then $LDA \geq \max(1, m)$, otherwise $LDA \geq \max(1, k)$. Unchanged on exit.

B (input)

REAL array of DIMENSION (LDB, kb), where kb is n when $TRANS B = 'N'$ or $'n'$, and is k otherwise. Before entry with $TRANS B = 'N'$ or $'n'$, the leading k by n part of the array B must contain the matrix B , otherwise the leading n by k part of the array B must contain the matrix B . Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. When $TRANS B = 'N'$ or $'n'$ then $LDB \geq \max(1, k)$, otherwise $LDB \geq \max(1, n)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then C need not be set on input. Unchanged on exit.

C (input/output)

REAL array of DIMENSION (LDC, n). Before entry, the leading m by n part of the array C must contain the matrix C , except when beta is zero, in which case C need not be set on entry. On exit, the array C is overwritten by the m by n matrix $(\alpha * op(A) * op(B) + \beta * C)$.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. $LDC \geq \max(1, m)$. Unchanged on exit.

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NAME

sgemv - perform one of the matrix-vector operations $y := \alpha A x + \beta y$ or $y := \alpha A' x + \beta y$

SYNOPSIS

```
SUBROUTINE SGEMV(TRANSA, M, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA  
INTEGER M, N, LDA, INCX, INCY  
REAL ALPHA, BETA  
REAL A(LDA,*), X(*), Y(*)
```

```
SUBROUTINE SGEMV_64(TRANSA, M, N, ALPHA, A, LDA, X, INCX, BETA, Y,  
INCY)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 M, N, LDA, INCX, INCY  
REAL ALPHA, BETA  
REAL A(LDA,*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE GEMV([TRANSA], [M], [N], ALPHA, A, [LDA], X, [INCX], BETA,  
Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: M, N, LDA, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GEMV_64([TRANSA], [M], [N], ALPHA, A, [LDA], X, [INCX],  
BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: M, N, LDA, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>

void sgemv(char transa, int m, int n, float alpha, float *a,
           int lda, float *x, int incx, float beta, float *y,
           int incy);
void sgemv_64(char transa, long m, long n, float alpha,
              float *a, long lda, float *x, long incx, float
              beta, float *y, long incy);
```

PURPOSE

sgemv performs one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A^T x + \beta y$, where α and β are scalars, x and y are vectors and A is an m by n matrix.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $y := \alpha A x + \beta y$.

TRANSA = 'T' or 't' $y := \alpha A^T x + \beta y$.

TRANSA = 'C' or 'c' $y := \alpha A^T x + \beta y$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry, the leading m by n part of the array A must contain the matrix of coefficients. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, m)$. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(INCX))$ when TRANSA = 'N' or

'n' and at least $(1 + (m - 1) * \text{abs}(\text{INCX}))$ otherwise. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

$(1 + (m - 1) * \text{abs}(\text{INCY}))$ when $\text{TRANSA} = 'N'$ or 'n' and at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$ otherwise. Before entry with BETA non-zero, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

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NAME

sgeqlf - compute a QL factorization of a real M-by-N matrix A

SYNOPSIS

```
SUBROUTINE SGEQLF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SGEQLF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQLF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GEQLF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgeqlf(int m, int n, float *a, int lda, float *tau, int  
           *info);
```

```
void sgeqlf_64(long m, long n, float *a, long lda, float  
              *tau, long *info);
```

PURPOSE

sgeqlf computes a QL factorization of a real M-by-N matrix
A: $A = Q * L$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $m \geq n$, the lower triangle of the subarray $A(m-n+1:m, 1:n)$ contains the N-by-N lower triangular matrix L; if $m < n$, the elements on and below the $(n-m)$ -th superdiagonal contain the M-by-N lower trapezoidal matrix L; the remaining elements, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(k) \dots H(2) H(1)$, where $k = \min(m, n)$.
Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real scalar, and v is a real vector with $v(m-k+i+1:m) = 0$ and $v(m-k+i) = 1$; $v(1:m-k+i-1)$ is stored on exit in $A(1:m-k+i-1, n-k+i)$, and τ in $TAU(i)$.

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NAME

sgeqp3 - compute a QR factorization with column pivoting of a matrix A

SYNOPSIS

```
SUBROUTINE SGEQP3(M, N, A, LDA, JPVT, TAU, WORK, LWORK, INFO)

INTEGER M, N, LDA, LWORK, INFO
INTEGER JPVT(*)
REAL A(LDA,*), TAU(*), WORK(*)

SUBROUTINE SGEQP3_64(M, N, A, LDA, JPVT, TAU, WORK, LWORK, INFO)

INTEGER*8 M, N, LDA, LWORK, INFO
INTEGER*8 JPVT(*)
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQP3([M], [N], A, [LDA], JPVT, TAU, [WORK], [LWORK],
  [INFO])

INTEGER :: M, N, LDA, LWORK, INFO
INTEGER, DIMENSION(:) :: JPVT
REAL, DIMENSION(:) :: TAU, WORK
REAL, DIMENSION(:,) :: A

SUBROUTINE GEQP3_64([M], [N], A, [LDA], JPVT, TAU, [WORK], [LWORK],
  [INFO])

INTEGER(8) :: M, N, LDA, LWORK, INFO
INTEGER(8), DIMENSION(:) :: JPVT
REAL, DIMENSION(:) :: TAU, WORK
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>

void sgeqp3(int m, int n, float *a, int lda, int *jpvt,
```

```

float *tau, int *info);

void sgeqp3_64(long m, long n, float *a, long lda, long
*jpvt, float *tau, long *info);

```

PURPOSE

sgeqp3 computes a QR factorization with column pivoting of a matrix A: $A^*P = Q^*R$ using Level 3 BLAS.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the upper triangle of the array contains the $\min(M,N)$ -by-N upper trapezoidal matrix R; the elements below the diagonal, together with the array TAU, represent the orthogonal matrix Q as a product of $\min(M,N)$ elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

JPVT (input/output)

On entry, if $JPVT(J) \neq 0$, the J-th column of A is permuted to the front of A*P (a leading column); if $JPVT(J)=0$, the J-th column of A is a free column. On exit, if $JPVT(J)=K$, then the J-th column of A*P was the the K-th column of A.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

On exit, if $INFO=0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq 3*N+1$. For optimal performance $LWORK \geq 2*N+(N+1)*NB$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if $INFO = -i$, the i-th argument had an ille-

gal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m,n).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real/complex scalar, and v is a real/complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$, and τ in $TAU(i)$.

Based on contributions by

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NAME

sgeqpf - routine is deprecated and has been replaced by routine SGEQP3

SYNOPSIS

```
SUBROUTINE SGEQPF(M, N, A, LDA, JPIVOT, TAU, WORK, INFO)
```

```
INTEGER M, N, LDA, INFO
INTEGER JPIVOT(*)
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SGEQPF_64(M, N, A, LDA, JPIVOT, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, LDA, INFO
INTEGER*8 JPIVOT(*)
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQPF([M], [N], A, [LDA], JPIVOT, TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, LDA, INFO
INTEGER, DIMENSION(:) :: JPIVOT
REAL, DIMENSION(:) :: TAU, WORK
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GEQPF_64([M], [N], A, [LDA], JPIVOT, TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO
INTEGER(8), DIMENSION(:) :: JPIVOT
REAL, DIMENSION(:) :: TAU, WORK
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgeqpf(int m, int n, float *a, int lda, int *jpivot,
           float *tau, int *info);
```

```
void sgeqpf_64(long m, long n, float *a, long lda, long
              *jpivot, float *tau, long *info);
```

PURPOSE

sgeqpf routine is deprecated and has been replaced by routine SGEQP3.

SGEQPF computes a QR factorization with column pivoting of a real M-by-N matrix A: $A^*P = Q^*R$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$

A (input/output)

On entry, the M-by-N matrix A. On exit, the upper triangle of the array contains the $\min(M,N)$ -by-N upper triangular matrix R; the elements below the diagonal, together with the array TAU, represent the orthogonal matrix Q as a product of $\min(m,n)$ elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

JPIVOT (input/output)

On entry, if $JPIVOT(i) \neq 0$, the i-th column of A is permuted to the front of A^*P (a leading column); if $JPIVOT(i) = 0$, the i-th column of A is a free column. On exit, if $JPIVOT(i) = k$, then the i-th column of A^*P was the k-th column of A.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n)$$

Each $H(i)$ has the form

$$H = I - \tau * v * v'$$

where τ is a real scalar, and v is a real vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$.

The matrix P is represented in $jpvt$ as follows: If

$$jpvt(j) = i$$

then the j th column of P is the i th canonical unit vector.

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NAME

sgeqrf - compute a QR factorization of a real M-by-N matrix
A

SYNOPSIS

```
SUBROUTINE SGEQRF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SGEQRF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQRF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE GEQRF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgeqrf(int m, int n, float *a, int lda, float *tau, int  
*info);
```

```
void sgeqrf_64(long m, long n, float *a, long lda, float  
*tau, long *info);
```

PURPOSE

sgeqrf computes a QR factorization of a real M-by-N matrix A:
 $A = Q * R$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the elements on and above the diagonal of the array contain the min(M,N)-by-N upper trapezoidal matrix R (R is upper triangular if $m \geq n$); the elements below the diagonal, with the array TAU, represent the orthogonal matrix Q as a product of min(m,n) elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m, n).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with
 $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in
 $A(i+1:m,i)$, and tau in $TAU(i)$.

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NAME

sger - perform the rank 1 operation $A := \alpha x y' + A$

SYNOPSIS

```
SUBROUTINE SGER(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
INTEGER M, N, INCX, INCY, LDA  
REAL ALPHA  
REAL X(*), Y(*), A(LDA,*)
```

```
SUBROUTINE SGER_64(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
INTEGER*8 M, N, INCX, INCY, LDA  
REAL ALPHA  
REAL X(*), Y(*), A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE GER([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
INTEGER :: M, N, INCX, INCY, LDA  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GER_64([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
INTEGER(8) :: M, N, INCX, INCY, LDA  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sger(int m, int n, float alpha, float *x, int incx,  
         float *y, int incy, float *a, int lda);
```

```
void sger_64(long m, long n, float alpha, float *x, long  
            incx, float *y, long incy, float *a, long lda);
```

PURPOSE

sger performs the rank 1 operation $A := \alpha x y' + A$, where α is a scalar, x is an m element vector, y is an n element vector and A is an m by n matrix.

ARGUMENTS

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (m - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the m element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

A (input/output)

Before entry, the leading m by n part of the array A must contain the matrix of coefficients. On exit, A is overwritten by the updated matrix.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $\text{LDA} \geq \max(1, m)$. Unchanged on exit.

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NAME

sgerfs - improve the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE SGERFS(TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,  
X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER IPIVOT(*), WORK2(*)  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE SGERFS_64(TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,  
LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*), WORK2(*)  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GERFS([TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT,  
B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, WORK2  
REAL, DIMENSION(:) :: FERR, BERR, WORK  
REAL, DIMENSION(:,:) :: A, AF, B, X
```

```
SUBROUTINE GERFS_64([TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],  
IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
```

```
REAL, DIMENSION(:) :: FERR, BERR, WORK
REAL, DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
void sgerfs(char transa, int n, int nrhs, float *a, int lda,
            float *af, int ldaf, int *ipivot, float *b, int
            ldb, float *x, int ldx, float *ferr, float *berr,
            int *info);

void sgerfs_64(char transa, long n, long nrhs, float *a,
              long lda, float *af, long ldaf, long *ipivot,
              float *b, long ldb, float *x, long ldx, float
              *ferr, float *berr, long *info);
```

PURPOSE

sgerfs improves the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{*T} * X = B$ (Transpose)
= 'C': $A^{*H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The original N-by-N matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)

The factors L and U from the factorization $A = P * L * U$ as computed by SGETRF.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

IPIVOT (input)

The pivot indices from SGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by
SGETRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq
max(1,N).

FERR (output)
The estimated forward error bound for each solu-
tion vector X(j) (the j-th column of the solution
matrix X). If XTRUE is the true solution
corresponding to X(j), FERR(j) is an estimated
upper bound for the magnitude of the largest ele-
ment in (X(j) - XTRUE) divided by the magnitude of
the largest element in X(j). The estimate is as
reliable as the estimate for RCOND, and is almost
always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each
solution vector X(j) (i.e., the smallest relative
change in any element of A or B that makes X(j) an
exact solution).

WORK (workspace)
dimension(3*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

sgerqf - compute an RQ factorization of a real M-by-N matrix
A

SYNOPSIS

```
SUBROUTINE SGERQF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SGERQF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GERQF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GERQF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgerqf(int m, int n, float *a, int lda, float *tau, int  
           *info);
```

```
void sgerqf_64(long m, long n, float *a, long lda, float  
              *tau, long *info);
```

PURPOSE

sgerqf computes an RQ factorization of a real M-by-N matrix
A: $A = R * Q$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $m \leq n$, the upper triangle of the subarray A(1:m,n-m+1:n) contains the M-by-M upper triangular matrix R; if $m \geq n$, the elements on and above the (m-n)-th subdiagonal contain the M-by-N upper trapezoidal matrix R; the remaining elements, with the array TAU, represent the orthogonal matrix Q as a product of $\min(m,n)$ elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1,M)$. For optimum performance $LDWORK \geq M * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(1) H(2) \dots H(k)$, where $k = \min(m,n)$.
Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real scalar, and v is a real vector with $v(n-k+i+1:n) = 0$ and $v(n-k+i) = 1$; $v(1:n-k+i-1)$ is stored on exit in $A(m-k+i, 1:n-k+i-1)$, and τ in $TAU(i)$.

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NAME

sgesdd - compute the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and right singular vectors

SYNOPSIS

```
SUBROUTINE SGESDD(JOBZ, M, N, A, LDA, S, U, LDU, VT, LDVT, WORK,  
                 LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOBZ  
INTEGER M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER IWORK(*)  
REAL A(LDA,*), S(*), U(LDU,*), VT(LDVT,*), WORK(*)
```

```
SUBROUTINE SGESDD_64(JOBZ, M, N, A, LDA, S, U, LDU, VT, LDVT, WORK,  
                   LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOBZ  
INTEGER*8 M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER*8 IWORK(*)  
REAL A(LDA,*), S(*), U(LDU,*), VT(LDVT,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GESDD(JOBZ, [M], [N], A, [LDA], S, U, [LDU], VT, [LDVT],  
                [WORK], [LWORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ  
INTEGER :: M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: S, WORK  
REAL, DIMENSION(:, :) :: A, U, VT
```

```
SUBROUTINE GESDD_64(JOBZ, [M], [N], A, [LDA], S, U, [LDU], VT, [LDVT],  
                  [WORK], [LWORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ  
INTEGER(8) :: M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER(8), DIMENSION(:) :: IWORK
```

```
REAL, DIMENSION(:) :: S, WORK
REAL, DIMENSION(:,:) :: A, U, VT
```

C INTERFACE

```
#include <sunperf.h>

void sgesdd(char jobz, int m, int n, float *a, int lda,
            float *s, float *u, int ldu, float *vt, int ldvt,
            int *info);
void sgesdd_64(char jobz, long m, long n, float *a, long
               lda, float *s, float *u, long ldu, float *vt, long
               ldvt, long *info);
```

PURPOSE

sgesdd computes the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and right singular vectors. If singular vectors are desired, it uses a divide-and-conquer algorithm.

The SVD is written
$$= U * SIGMA * \text{transpose}(V)$$

where SIGMA is an M-by-N matrix which is zero except for its min(m,n) diagonal elements, U is an M-by-M orthogonal matrix, and V is an N-by-N orthogonal matrix. The diagonal elements of SIGMA are the singular values of A; they are real and non-negative, and are returned in descending order. The first min(m,n) columns of U and V are the left and right singular vectors of A.

Note that the routine returns $VT = V^{*T}$, not V.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)

Specifies options for computing all or part of the matrix U:

= 'A': all M columns of U and all N rows of V^{*T} are returned in the arrays U and VT; = 'S': the first min(M,N) columns of U and the first min(M,N) rows of V^{*T} are returned in the arrays U and VT; = 'O': If $M \geq N$, the first N columns of U are overwritten on the array A and all rows of V^{*T} are returned in the array VT; otherwise, all columns of U are returned in the array U and the first M rows of V^{*T} are overwritten on the array A; = 'N': no columns of U or rows of V^{*T} are

computed.

M (input) The number of rows of the input matrix A. $M \geq 0$.

N (input) The number of columns of the input matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if JOBZ = 'O', A is overwritten with the first N columns of U (the left singular vectors, stored columnwise) if $M \geq N$; A is overwritten with the first M rows of V^*T (the right singular vectors, stored rowwise) otherwise. If JOBZ .ne. 'O', the contents of A are destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

S (output)

The singular values of A, sorted so that $S(i) \geq S(i+1)$.

U (output)

UCOL = M if JOBZ = 'A' or JOBZ = 'O' and $M < N$; UCOL = $\min(M, N)$ if JOBZ = 'S'. If JOBZ = 'A' or JOBZ = 'O' and $M < N$, U contains the M-by-M orthogonal matrix U; if JOBZ = 'S', U contains the first $\min(M, N)$ columns of U (the left singular vectors, stored columnwise); if JOBZ = 'O' and $M \geq N$, or JOBZ = 'N', U is not referenced.

LDU (input)

The leading dimension of the array U. $LDU \geq 1$; if JOBZ = 'S' or 'A' or JOBZ = 'O' and $M < N$, $LDU \geq M$.

VT (output)

If JOBZ = 'A' or JOBZ = 'O' and $M \geq N$, VT contains the N-by-N orthogonal matrix V^*T ; if JOBZ = 'S', VT contains the first $\min(M, N)$ rows of V^*T (the right singular vectors, stored rowwise); if JOBZ = 'O' and $M < N$, or JOBZ = 'N', VT is not referenced.

LDVT (input)

The leading dimension of the array VT. $LDVT \geq 1$; if JOBZ = 'A' or JOBZ = 'O' and $M \geq N$, $LDVT \geq N$; if JOBZ = 'S', $LDVT \geq \min(M, N)$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK;

LWORK (input)

The dimension of the array WORK. $LWORK \geq 1$. If $LWORK = -1$, then a workspace query is assumed. In this case, the routine only calculates the optimal size of the work array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued. The minimum

workspace size requirement is as follows:

```
If M is much larger than N such that  $M \geq (N * 11/6)$ :
  If JOBZ = 'N',  $LWORK \geq 3*N*N + 7*N$ 
  If JOBZ = 'O',  $LWORK \geq 3*N*N + 7*N + 2*N*N + 2*N$ 
  If JOBZ = 'S',  $LWORK \geq 3*N*N + 7*N + N*N + 2*N$ 
  If JOBZ = 'A',  $LWORK \geq 3*N*N + 7*N + N*N + M + N$ 
If M is at least N but not much larger ( $M < (N * 11/6)$ ):
  If JOBZ = 'N',  $LWORK \geq 1$ 
  If JOBZ = 'O',  $LWORK \geq 3*N*N + 7*N + N*N + 2*N + M$ 
  If JOBZ = 'S',  $LWORK \geq 3*N*N + 7*N + 2*N + M$ 
  If JOBZ = 'A',  $LWORK \geq 3*N*N + 7*N + 2*N + M$ 
If N is much larger than M such that  $N \geq (M * 11/6)$ :
  If JOBZ = 'N',  $LWORK \geq 3*M*M + 7*M$ 
  If JOBZ = 'O',  $LWORK \geq 3*M*M + 7*M + 2*M*M + 2*M$ 
  If JOBZ = 'S',  $LWORK \geq 3*M*M + 7*M + M*M + 2*M$ 
  If JOBZ = 'A',  $LWORK \geq 3*M*M + 7*M + M*M + M + N$ 
If N is larger than M and  $N < (M * 11/6)$ :
  If JOBZ = 'N',  $LWORK \geq 1$ 
  If JOBZ = 'O',  $LWORK \geq 3*M*M + 7*M + M*M + 2*M + N$ 
  If JOBZ = 'S',  $LWORK \geq 3*M*M + 7*M + 2*M + N$ 
  If JOBZ = 'A',  $LWORK \geq 3*M*M + 7*M + 2*M + N$ 
```

```
IWORK (workspace)
  dimension(8*MIN(M,N))
```

```
INFO (output)
  = 0: successful exit.
  < 0: if INFO = -i, the i-th argument had an illegal value.
  > 0: SBDSDC did not converge, updating process failed.
```

FURTHER DETAILS

Based on contributions by
Ming Gu and Huan Ren, Computer Science Division, University of
California at Berkeley, USA

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NAME

sgesv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SGESV(N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
INTEGER N, NRHS, LDA, LDB, INFO
INTEGER IPIVOT(*)
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SGESV_64(N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
INTEGER*8 N, NRHS, LDA, LDB, INFO
INTEGER*8 IPIVOT(*)
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GESV([N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
INTEGER :: N, NRHS, LDA, LDB, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GESV_64([N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDA, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgesv(int n, int nrhs, float *a, int lda, int *ipivot,
           float *b, int ldb, int *info);
```

```
void sgesv_64(long n, long nrhs, float *a, long lda, long
              *ipivot, float *b, long ldb, long *info);
```

PURPOSE

sgesv computes the solution to a real system of linear equations

$A * X = B$, where A is an N -by- N matrix and X and B are N -by- $NRHS$ matrices.

The LU decomposition with partial pivoting and row interchanges is used to factor A as

$$A = P * L * U,$$

where P is a permutation matrix, L is unit lower triangular, and U is upper triangular. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

N (input) The number of linear equations, i.e., the order of the matrix A . $N \geq 0$.

$NRHS$ (input)
The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input/output)
On entry, the N -by- N coefficient matrix A . On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)
The leading dimension of the array A . $LDA \geq \max(1,N)$.

$IPIVOT$ (output)
The pivot indices that define the permutation matrix P ; row i of the matrix was interchanged with row $IPIVOT(i)$.

B (input/output)
On entry, the N -by- $NRHS$ matrix of right hand side matrix B . On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)
The leading dimension of the array B . $LDB \geq \max(1,N)$.

$INFO$ (output)
= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, $U(i,i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution could not be computed.

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NAME

sgesvd - compute the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and/or right singular vectors

SYNOPSIS

```
SUBROUTINE SGESVD(JOBU, JOBVT, M, N, A, LDA, SING, U, LDU, VT, LDVT,  
                WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBU, JOBVT  
INTEGER M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL A(LDA,*), SING(*), U(LDU,*), VT(LDVT,*), WORK(*)
```

```
SUBROUTINE SGESVD_64(JOBU, JOBVT, M, N, A, LDA, SING, U, LDU, VT,  
                   LDVT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBU, JOBVT  
INTEGER*8 M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL A(LDA,*), SING(*), U(LDU,*), VT(LDVT,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GESVD(JOBU, JOBVT, [M], [N], A, [LDA], SING, U, [LDU], VT,  
                [LDVT], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBVT  
INTEGER :: M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL, DIMENSION(:) :: SING, WORK  
REAL, DIMENSION(:,) :: A, U, VT
```

```
SUBROUTINE GESVD_64(JOBU, JOBVT, [M], [N], A, [LDA], SING, U, [LDU],  
                   VT, [LDVT], [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBVT  
INTEGER(8) :: M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL, DIMENSION(:) :: SING, WORK  
REAL, DIMENSION(:,) :: A, U, VT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgesvd(char jobu, char jobvt, int m, int n, float *a,
            int lda, float *sing, float *u, int ldu, float
            *vt, int ldvt, int *info);
```

```
void sgesvd_64(char jobu, char jobvt, long m, long n, float
               *a, long lda, float *sing, float *u, long ldu,
               float *vt, long ldvt, long *info);
```

PURPOSE

sgesvd computes the singular value decomposition (SVD) of a real M-by-N matrix A, optionally computing the left and/or right singular vectors. The SVD is written

$$= U * \text{SIGMA} * \text{transpose}(V)$$

where SIGMA is an M-by-N matrix which is zero except for its min(m,n) diagonal elements, U is an M-by-M orthogonal matrix, and V is an N-by-N orthogonal matrix. The diagonal elements of SIGMA are the singular values of A; they are real and non-negative, and are returned in descending order. The first min(m,n) columns of U and V are the left and right singular vectors of A.

Note that the routine returns V**T, not V.

ARGUMENTS

JOBU (input)

Specifies options for computing all or part of the matrix U:

= 'A': all M columns of U are returned in array U;

= 'S': the first min(m,n) columns of U (the left singular vectors) are returned in the array U; =

'O': the first min(m,n) columns of U (the left singular vectors) are overwritten on the array A;

= 'N': no columns of U (no left singular vectors) are computed.

JOBVT (input)

Specifies options for computing all or part of the matrix V**T:

= 'A': all N rows of V**T are returned in the array VT;

= 'S': the first min(m,n) rows of V**T (the right singular vectors) are returned in the array VT; =

'O': the first min(m,n) rows of V**T (the right singular vectors) are overwritten on the array A;

= 'N': no rows of V**T (no right singular vectors) are computed.

JOBVT and JOBUT cannot both be 'O'.

M (input) The number of rows of the input matrix A. M >= 0.

N (input) The number of columns of the input matrix A. N >=

0.

A (input/output)
 On entry, the M-by-N matrix A. On exit, if JOBU = 'O', A is overwritten with the first min(m,n) columns of U (the left singular vectors, stored columnwise); if JOBVT = 'O', A is overwritten with the first min(m,n) rows of V**T (the right singular vectors, stored rowwise); if JOBU .ne. 'O' and JOBVT .ne. 'O', the contents of A are destroyed.

LDA (input)
 The leading dimension of the array A. LDA >= max(1,M).

SING (output)
 The singular values of A, sorted so that SING(i) >= SING(i+1).

U (input) (LDU,M) if JOBU = 'A' or (LDU,min(M,N)) if JOBU = 'S'. If JOBU = 'A', U contains the M-by-M orthogonal matrix U; if JOBU = 'S', U contains the first min(m,n) columns of U (the left singular vectors, stored columnwise); if JOBU = 'N' or 'O', U is not referenced.

LDU (input)
 The leading dimension of the array U. LDU >= 1; if JOBU = 'S' or 'A', LDU >= M.

VT (input)
 If JOBVT = 'A', VT contains the N-by-N orthogonal matrix V**T; if JOBVT = 'S', VT contains the first min(m,n) rows of V**T (the right singular vectors, stored rowwise); if JOBVT = 'N' or 'O', VT is not referenced.

LDVT (input)
 The leading dimension of the array VT. LDVT >= 1; if JOBVT = 'A', LDVT >= N; if JOBVT = 'S', LDVT >= min(M,N).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK; if INFO > 0, WORK(2:MIN(M,N)) contains the unconverged superdiagonal elements of an upper bidiagonal matrix B whose diagonal is in SING (not necessarily sorted). B satisfies $A = U * B * VT$, so it has the same singular values as A, and singular vectors related by U and VT.

LDWORK (input)
 The dimension of the array WORK. LDWORK >= 1. LDWORK >= MAX(3*MIN(M,N)+MAX(M,N),5*MIN(M,N)). For good performance, LDWORK should generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if SBDSQR did not converge, INFO specifies how many superdiagonals of an intermediate bidiagonal form B did not converge to zero. See the description of WORK above for details.

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NAME

sgesvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SGESVX(FACT, TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
    EQUED, R, C, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
    WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
REAL RCOND
REAL A(LDA,*), AF(LDAF,*), R(*), C(*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE SGESVX_64(FACT, TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
    EQUED, R, C, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
    WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
REAL RCOND
REAL A(LDA,*), AF(LDAF,*), R(*), C(*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GESVX(FACT, [TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],
    IPIVOT, EQUED, R, C, B, [LDB], X, [LDX], RCOND, FERR,
    BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: R, C, FERR, BERR, WORK
REAL, DIMENSION(:, :) :: A, AF, B, X
```

```
SUBROUTINE GESVX_64(FACT, [TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],
```

```
IPIVOT, EQUED, R, C, B, [LDB], X, [LDX], RCOND, FERR,
BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: R, C, FERR, BERR, WORK
REAL, DIMENSION(:,:) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgesvx(char fact, char transa, int n, int nrhs, float
    *a, int lda, float *af, int ldaf, int *ipivot,
    char equed, float *r, float *c, float *b, int ldb,
    float *x, int ldx, float *rcond, float *ferr,
    float *berr, int *info);
```

```
void sgesvx_64(char fact, char transa, long n, long nrhs,
    float *a, long lda, float *af, long ldaf, long
    *ipivot, char equed, float *r, float *c, float *b,
    long ldb, float *x, long ldx, float *rcond, float
    *ferr, float *berr, long *info);
```

PURPOSE

sgesvx uses the LU factorization to compute the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N matrix and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'E', real scaling factors are computed to equilibrate

the system:

TRANS = 'N': $\text{diag}(R) * A * \text{diag}(C) * \text{inv}(\text{diag}(C)) * X = \text{diag}(R) * B$

TRANS = 'T': $(\text{diag}(R) * A * \text{diag}(C))^{**T} * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

TRANS = 'C': $(\text{diag}(R) * A * \text{diag}(C))^{**H} * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A, but if equilibration is used, A is

overwritten by $\text{diag}(R) * A * \text{diag}(C)$ and B by $\text{diag}(R) * B$ (if TRANS='N')

or $\text{diag}(C) * B$ (if TRANS = 'T' or 'C').

2. If FACT = 'N' or 'E', the LU decomposition is used to factor the

matrix A (after equilibration if FACT = 'E') as

$A = P * L * U$,

where P is a permutation matrix, L is a unit lower tri-

angular

matrix, and U is upper triangular.

3. If some $U(i,i)=0$, so that U is exactly singular, then the routine

returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

$INFO = N+1$ is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form

of A.

5. Iterative refinement is applied to improve the computed solution

matrix and calculate error bounds and backward error estimates

for it.

6. If equilibration was used, the matrix X is premultiplied by

$\text{diag}(C)$ (if $TRANS = 'N'$) or $\text{diag}(R)$ (if $TRANS = 'T'$ or $'C'$) so

that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF and IPIVOT contain the factored form of A. If EQUED is not 'N', the matrix A has been equilibrated with scaling factors given by R and C. A, AF, and IPIVOT are not modified. = 'N': The matrix A will be copied to AF and factored.

= 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

TRANSA (input)

Specifies the form of the system of equations:

= 'N': $A * X = B$ (No transpose)

= 'T': $A^{**T} * X = B$ (Transpose)

= 'C': $A^{**H} * X = B$ (Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. If FACT = 'F' and EQUED is not 'N', then A must have been equilibrated by the scaling factors in R and/or C. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if EQUED .ne. 'N', A is scaled as follows:
EQUED = 'R': A := diag(R) * A
EQUED = 'C': A := A * diag(C)
EQUED = 'B': A := diag(R) * A * diag(C).

LDA (input)

The leading dimension of the array A. LDA >= max(1,N).

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the factors L and U from the factorization $A = P*L*U$ as computed by SGETRF. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the factors L and U from the factorization $A = P*L*U$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the factors L and U from the factorization $A = P*L*U$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF >= max(1,N).

IPIVOT (input or output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the factorization $A = P*L*U$ as computed by SGETRF; row i of the matrix was interchanged with row IPIVOT(i).

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = P*L*U$ of the original matrix A.

If FACT = 'E', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = P*L*U$ of the equilibrated matrix A.

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'R': Row equilibration, i.e., A has been premultiplied by diag(R). = 'C': Column equilibration, i.e., A has been postmultiplied by diag(C). = 'B': Both row and column equilibra-

tion, i.e., A has been replaced by $\text{diag}(R) * A * \text{diag}(C)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

R (input or output)

The row scale factors for A. If EQUED = 'R' or 'B', A is multiplied on the left by $\text{diag}(R)$; if EQUED = 'N' or 'C', R is not accessed. R is an input argument if FACT = 'F'; otherwise, R is an output argument. If FACT = 'F' and EQUED = 'R' or 'B', each element of R must be positive.

C (input or output)

The column scale factors for A. If EQUED = 'C' or 'B', A is multiplied on the right by $\text{diag}(C)$; if EQUED = 'N' or 'R', C is not accessed. C is an input argument if FACT = 'F'; otherwise, C is an output argument. If FACT = 'F' and EQUED = 'C' or 'B', each element of C must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if TRANSA = 'N' and EQUED = 'R' or 'B', B is overwritten by $\text{diag}(R)*B$; if TRANSA = 'T' or 'C' and EQUED = 'C' or 'B', B is overwritten by $\text{diag}(C)*B$.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that A and B are modified on exit if EQUED .ne. 'N', and the solution to the equilibrated system is $\text{inv}(\text{diag}(C))*X$ if TRANSA = 'N' and EQUED = 'C' or 'B', or $\text{inv}(\text{diag}(R))*X$ if TRANSA = 'T' or 'C' and EQUED = 'R' or 'B'.

LDX (input)

The leading dimension of the array X. $LDX \geq \max(1, N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in X(j). The estimate is as

reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension(4*N) On exit, WORK(1) contains the reciprocal pivot growth factor $\text{norm}(A)/\text{norm}(U)$. The "max absolute element" norm is used. If WORK(1) is much less than 1, then the stability of the LU factorization of the (equilibrated) matrix A could be poor. This also means that the solution X, condition estimator RCOND, and forward error bound FERR could be unreliable. If factorization fails with $0 < \text{INFO} \leq N$, then WORK(1) contains the reciprocal pivot growth factor for the leading INFO columns of A.

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: $U(i,i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

sgetf2 - compute an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE SGETF2(M, N, A, LDA, IPIV, INFO)
```

```
INTEGER M, N, LDA, INFO  
INTEGER IPIV(*)  
REAL A(LDA,*)
```

```
SUBROUTINE SGETF2_64(M, N, A, LDA, IPIV, INFO)
```

```
INTEGER*8 M, N, LDA, INFO  
INTEGER*8 IPIV(*)  
REAL A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE GETF2([M], [N], A, [LDA], IPIV, [INFO])
```

```
INTEGER :: M, N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE GETF2_64([M], [N], A, [LDA], IPIV, [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgetf2(int m, int n, float *a, int lda, int *ipiv, int  
          *info);
```

```
void sgetf2_64(long m, long n, float *a, long lda, long  
             *ipiv, long *info);
```

PURPOSE

sgetf2 computes an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges.

The factorization has the form

$$A = P * L * U$$

where P is a permutation matrix, L is lower triangular with unit diagonal elements (lower trapezoidal if $m > n$), and U is upper triangular (upper trapezoidal if $m < n$).

This is the right-looking Level 2 BLAS version of the algorithm.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the m by n matrix to be factored. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

IPIV (output)

The pivot indices; for $1 \leq i \leq \min(M,N)$, row i of the matrix was interchanged with row IPIV(i).

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value
> 0: if INFO = k, U(k,k) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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sgetrf - compute an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE SGETRF(M, N, A, LDA, IPIVOT, INFO)
```

```
INTEGER M, N, LDA, INFO  
INTEGER IPIVOT(*)  
REAL A(LDA,*)
```

```
SUBROUTINE SGETRF_64(M, N, A, LDA, IPIVOT, INFO)
```

```
INTEGER*8 M, N, LDA, INFO  
INTEGER*8 IPIVOT(*)  
REAL A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE GETRF([M], [N], A, [LDA], IPIVOT, [INFO])
```

```
INTEGER :: M, N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE GETRF_64([M], [N], A, [LDA], IPIVOT, [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgetrf(int m, int n, float *a, int lda, int *ipivot,  
           int *info);
```

```
void sgetrf_64(long m, long n, float *a, long lda, long  
              *ipivot, long *info);
```

PURPOSE

sgetrf computes an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges.

The factorization has the form

$$A = P * L * U$$

where P is a permutation matrix, L is lower triangular with unit diagonal elements (lower trapezoidal if $m > n$), and U is upper triangular (upper trapezoidal if $m < n$).

This is the right-looking Level 3 BLAS version of the algorithm.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix to be factored. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

IPIVOT (output)

The pivot indices; for $1 \leq i \leq \min(M, N)$, row i of the matrix was interchanged with row IPIVOT(i).

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, $U(i, i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

sgetri - compute the inverse of a matrix using the LU factorization computed by SGETRF

SYNOPSIS

```
SUBROUTINE SGETRI(N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
INTEGER N, LDA, LDWORK, INFO  
INTEGER IPIVOT(*)  
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE SGETRI_64(N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
INTEGER*8 N, LDA, LDWORK, INFO  
INTEGER*8 IPIVOT(*)  
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GETRI([N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: N, LDA, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE GETRI_64([N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
INTEGER(8) :: N, LDA, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgetri(int n, float *a, int lda, int *ipivot, int  
           *info);
```

```
void sgetri_64(long n, float *a, long lda, long *ipivot,  
              long *info);
```

PURPOSE

sgetri computes the inverse of a matrix using the LU factorization computed by SGETRF.

This method inverts U and then computes $\text{inv}(A)$ by solving the system $\text{inv}(A)*L = \text{inv}(U)$ for $\text{inv}(A)$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the factors L and U from the factorization $A = P*L*U$ as computed by SGETRF. On exit, if $\text{INFO} = 0$, the inverse of the original matrix A.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

The pivot indices from SGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row $\text{IPIVOT}(i)$.

WORK (workspace)

On exit, if $\text{INFO} = 0$, then $\text{WORK}(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $\text{LDWORK} \geq \max(1, N)$. For optimal performance $\text{LDWORK} \geq N*\text{NB}$, where NB is the optimal blocksize returned by ILAENV.

If $\text{LDWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if $\text{INFO} = -i$, the i-th argument had an illegal value

> 0: if $\text{INFO} = i$, $U(i, i)$ is exactly zero; the matrix is singular and its inverse could not be computed.

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NAME

sgetrs - solve a system of linear equations $A * X = B$ or $A' * X = B$ with a general N-by-N matrix A using the LU factorization computed by SGETRF

SYNOPSIS

```
SUBROUTINE SGETRS(TRANSA, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SGETRS_64(TRANSA, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GETRS([TRANSA], [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GETRS_64([TRANSA], [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```

void sgetrs(char transa, int n, int nrhs, float *a, int lda,
            int *ipivot, float *b, int ldb, int *info);

void sgetrs_64(char transa, long n, long nrhs, float *a,
               long lda, long *ipivot, float *b, long ldb, long
               *info);

```

PURPOSE

sgetrs solves a system of linear equations
 $A * X = B$ or $A' * X = B$ with a general N-by-N matrix A
using the LU factorization computed by SGETRF.

ARGUMENTS

TRANSA (input)
Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A' * X = B$ (Transpose)
= 'C': $A' * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The factors L and U from the factorization $A = P * L * U$ as computed by SGETRF.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)
The pivot indices from SGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)
On entry, the right hand side matrix B. On exit, the solution matrix X.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sggbak - form the right or left eigenvectors of a real generalized eigenvalue problem $A*x = \lambda*B*x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by SGBAL

SYNOPSIS

```
SUBROUTINE SGGBAK(JOB, SIDE, N, ILO, IHI, LSCALE, RSCALE, M, V, LDV,
                 INFO)
```

```
CHARACTER * 1 JOB, SIDE
INTEGER N, ILO, IHI, M, LDV, INFO
REAL LSCALE(*), RSCALE(*), V(LDV,*)
```

```
SUBROUTINE SGGBAK_64(JOB, SIDE, N, ILO, IHI, LSCALE, RSCALE, M, V,
                    LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE
INTEGER*8 N, ILO, IHI, M, LDV, INFO
REAL LSCALE(*), RSCALE(*), V(LDV,*)
```

F95 INTERFACE

```
SUBROUTINE GGBAK(JOB, SIDE, [N], ILO, IHI, LSCALE, RSCALE, [M], V,
                [LDV], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE
INTEGER :: N, ILO, IHI, M, LDV, INFO
REAL, DIMENSION(:) :: LSCALE, RSCALE
REAL, DIMENSION(:, :) :: V
```

```
SUBROUTINE GGBAK_64(JOB, SIDE, [N], ILO, IHI, LSCALE, RSCALE, [M], V,
                   [LDV], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE
INTEGER(8) :: N, ILO, IHI, M, LDV, INFO
REAL, DIMENSION(:) :: LSCALE, RSCALE
REAL, DIMENSION(:, :) :: V
```

C INTERFACE

```
#include <sunperf.h>

void sggbak(char job, char side, int n, int ilo, int ihi,
            float *lscale, float *rscale, int m, float *v, int
            ldv, int *info);

void sggbak_64(char job, char side, long n, long ilo, long
              ihi, float *lscale, float *rscale, long m, float
              *v, long ldv, long *info);
```

PURPOSE

sggbak forms the right or left eigenvectors of a real generalized eigenvalue problem $A*x = \lambda*B*x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by SGGBAL.

ARGUMENTS

JOB (input)
Specifies the type of backward transformation required:
= 'N': do nothing, return immediately;
= 'P': do backward transformation for permutation only;
= 'S': do backward transformation for scaling only;
= 'B': do backward transformations for both permutation and scaling. JOB must be the same as the argument JOB supplied to SGGBAL.

SIDE (input)
= 'R': V contains right eigenvectors;
= 'L': V contains left eigenvectors.

N (input) The number of rows of the matrix V. $N \geq 0$.

ILO (input)
The integers ILO and IHI determined by SGGBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

IHI (input)
See the description for ILO.

LSCALE (input)
Details of the permutations and/or scaling factors applied to the left side of A and B, as returned by SGGBAL.

RSCALE (input)
Details of the permutations and/or scaling factors applied to the right side of A and B, as returned by SGGBAL.

M (input) The number of columns of the matrix V. $M \geq 0$.

V (input/output)

On entry, the matrix of right or left eigenvectors to be transformed, as returned by STGEVC. On exit, V is overwritten by the transformed eigenvectors.

LDV (input)

The leading dimension of the matrix V. $LDV \geq \max(1, N)$.

INFO (output)

= 0: successful exit.
< 0: if $INFO = -i$, the i -th argument had an illegal value.

FURTHER DETAILS

See R.C. Ward, Balancing the generalized eigenvalue problem, SIAM J. Sci. Stat. Comp. 2 (1981), 141-152.

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NAME

sggbal - balance a pair of general real matrices (A,B)

SYNOPSIS

```
SUBROUTINE SGGBAL(JOB, N, A, LDA, B, LDB, ILO, IHI, LSCALE, RSCALE,  
                  WORK, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER N, LDA, LDB, ILO, IHI, INFO  
REAL A(LDA,*), B(LDB,*), LSCALE(*), RSCALE(*), WORK(*)
```

```
SUBROUTINE SGGBAL_64(JOB, N, A, LDA, B, LDB, ILO, IHI, LSCALE,  
                    RSCALE, WORK, INFO)
```

```
CHARACTER * 1 JOB  
INTEGER*8 N, LDA, LDB, ILO, IHI, INFO  
REAL A(LDA,*), B(LDB,*), LSCALE(*), RSCALE(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGBAL(JOB, [N], A, [LDA], B, [LDB], ILO, IHI, LSCALE,  
                RSCALE, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER :: N, LDA, LDB, ILO, IHI, INFO  
REAL, DIMENSION(:) :: LSCALE, RSCALE, WORK  
REAL, DIMENSION(:,:) :: A, B
```

```
SUBROUTINE GGBAL_64(JOB, [N], A, [LDA], B, [LDB], ILO, IHI, LSCALE,  
                   RSCALE, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
INTEGER(8) :: N, LDA, LDB, ILO, IHI, INFO  
REAL, DIMENSION(:) :: LSCALE, RSCALE, WORK  
REAL, DIMENSION(:,:) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sggbal(char job, int n, float *a, int lda, float *b,
            int ldb, int *ilo, int *ihi, float *lscale, float
            *rscale, int *info);
```

```
void sggbal_64(char job, long n, float *a, long lda, float
               *b, long ldb, long *ilo, long *ihi, float *lscale,
               float *rscale, long *info);
```

PURPOSE

sggbal balances a pair of general real matrices (A,B). This involves, first, permuting A and B by similarity transformations to isolate eigenvalues in the first 1 to ILO-1 and last IHI+1 to N elements on the diagonal; and second, applying a diagonal similarity transformation to rows and columns ILO to IHI to make the rows and columns as close in norm as possible. Both steps are optional.

Balancing may reduce the 1-norm of the matrices, and improve the accuracy of the computed eigenvalues and/or eigenvectors in the generalized eigenvalue problem $A*x = \lambda*B*x$.

ARGUMENTS

JOB (input)

Specifies the operations to be performed on A and B:
= 'N': none: simply set ILO = 1, IHI = N, LSCALE(I) = 1.0 and RSCALE(I) = 1.0 for i = 1,...,N.
= 'P': permute only;
= 'S': scale only;
= 'B': both permute and scale.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the input matrix A. On exit, A is overwritten by the balanced matrix. If JOB = 'N', A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input) On entry, the input matrix B. On exit, B is overwritten by the balanced matrix. If JOB = 'N', B is not referenced.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

ILO (output)

ILO and IHI are set to integers such that on exit $A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1, \dots, ILO-1$ or $i = IHI+1, \dots, N$. If JOB = 'N' or

'S', ILO = 1 and IHI = N.

IHI (output)

See the description for ILO.

LSCALE (input)

Details of the permutations and scaling factors applied to the left side of A and B. If $P(j)$ is the index of the row interchanged with row j , and $D(j)$ is the scaling factor applied to row j , then $LSCALE(j) = P(j)$ for $J = 1, \dots, ILO-1 = D(j)$ for $J = ILO, \dots, IHI = P(j)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

RSCALE (input)

Details of the permutations and scaling factors applied to the right side of A and B. If $P(j)$ is the index of the column interchanged with column j , and $D(j)$ is the scaling factor applied to column j , then $LSCALE(j) = P(j)$ for $J = 1, \dots, ILO-1 = D(j)$ for $J = ILO, \dots, IHI = P(j)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

WORK (workspace)

dimension(6*N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

See R.C. WARD, Balancing the generalized eigenvalue problem, SIAM J. Sci. Stat. Comp. 2 (1981), 141-152.

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NAME

sgges - compute for a pair of N-by-N real nonsymmetric matrices (A,B),

SYNOPSIS

```
SUBROUTINE SGGES(JOBVSL, JOBVSR, SORT, SELCTG, N, A, LDA, B, LDB,
                SDIM, ALPHAR, ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LWORK,
                BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT
INTEGER N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL SELCTG
LOGICAL BWORK(*)
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
```

```
SUBROUTINE SGGES_64(JOBVSL, JOBVSR, SORT, SELCTG, N, A, LDA, B, LDB,
                   SDIM, ALPHAR, ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LWORK,
                   BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT
INTEGER*8 N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL*8 SELCTG
LOGICAL*8 BWORK(*)
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGES(JOBVSL, JOBVSR, SORT, [SELCTG], [N], A, [LDA], B, [LDB],
                SDIM, ALPHAR, ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK],
                [LWORK], [BWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT
INTEGER :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL :: SELCTG
LOGICAL, DIMENSION(:) :: BWORK
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL, DIMENSION(:, :) :: A, B, VSL, VSR
```

```
SUBROUTINE GGES_64(JOBVSL, JOBVSR, SORT, [SELCTG], [N], A, [LDA], B,
```

```
[LDB], SDIM, ALPHAR, ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR],  
[WORK], [LWORK], [BWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT  
INTEGER(8) :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO  
LOGICAL(8) :: SELCTG  
LOGICAL(8), DIMENSION(:) :: BWORK  
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK  
REAL, DIMENSION(:,:) :: A, B, VSL, VSR
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sggcs(char jobvsl, char jobvsr, char sort,  
int(*selctg)(float,float,float), int n, float *a,  
int lda, float *b, int ldb, int *sdim, float  
*alphar, float *alphai, float *beta, float *vsl,  
int ldvsl, float *vsr, int ldvsr, int *info);
```

```
void sggcs_64(char jobvsl, char jobvsr, char sort,  
long(*selctg)(float,float,float), long n, float  
*a, long lda, float *b, long ldb, long *sdim,  
float *alphar, float *alphai, float *beta, float  
*vsl, long ldvsl, float *vsr, long ldvsr, long  
*info);
```

PURPOSE

sggcs computes for a pair of N-by-N real nonsymmetric matrices (A,B), the generalized eigenvalues, the generalized real Schur form (S,T), optionally, the left and/or right matrices of Schur vectors (VSL and VSR). This gives the generalized Schur factorization

$$(A,B) = ((VSL)*S*(VSR)**T, (VSL)*T*(VSR)**T)$$

Optionally, it also orders the eigenvalues so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix S and the upper triangular matrix T. The leading columns of VSL and VSR then form an orthonormal basis for the corresponding left and right eigenspaces (deflating subspaces).

(If only the generalized eigenvalues are needed, use the driver SGGEV instead, which is faster.)

A generalized eigenvalue for a pair of matrices (A,B) is a scalar w or a ratio alpha/beta = w, such that A - w*B is singular. It is usually represented as the pair (alpha,beta), as there is a reasonable interpretation for beta=0 or both being zero.

A pair of matrices (S,T) is in generalized real Schur form if T is upper triangular with non-negative diagonal and S is block upper triangular with 1-by-1 and 2-by-2 blocks. 1-by-1 blocks correspond to real generalized eigenvalues, while 2-by-2 blocks of S will be "standardized" by making the corresponding elements of T have the form:

$$\begin{bmatrix} a & 0 \end{bmatrix}$$

[0 b]

and the pair of corresponding 2-by-2 blocks in S and T will have a complex conjugate pair of generalized eigenvalues.

ARGUMENTS

JOBVSL (input)

= 'N': do not compute the left Schur vectors;
= 'V': compute the left Schur vectors.

JOBVSR (input)

= 'N': do not compute the right Schur vectors;
= 'V': compute the right Schur vectors.

SORT (input)

Specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form. = 'N': Eigenvalues are not ordered;
= 'S': Eigenvalues are ordered (see SELCTG);

SELCTG (input)

LOGICAL FUNCTION of three REAL arguments SELCTG must be declared EXTERNAL in the calling subroutine. If SORT = 'N', SELCTG is not referenced. If SORT = 'S', SELCTG is used to select eigenvalues to sort to the top left of the Schur form. An eigenvalue $(\text{ALPHAR}(j)+\text{ALPHAI}(j))/\text{BETA}(j)$ is selected if $\text{SELCTG}(\text{ALPHAR}(j),\text{ALPHAI}(j),\text{BETA}(j))$ is true; i.e. if either one of a complex conjugate pair of eigenvalues is selected, then both complex eigenvalues are selected.

Note that in the ill-conditioned case, a selected complex eigenvalue may no longer satisfy $\text{SELCTG}(\text{ALPHAR}(j),\text{ALPHAI}(j),\text{BETA}(j)) = \text{.TRUE.}$ after ordering. INFO is to be set to N+2 in this case.

N (input) The order of the matrices A, B, VSL, and VSR. N ≥ 0 .

A (input/output)

On entry, the first of the pair of matrices. On exit, A has been overwritten by its generalized Schur form S.

LDA (input)

The leading dimension of A. LDA $\geq \max(1,N)$.

B (input/output)

On entry, the second of the pair of matrices. On exit, B has been overwritten by its generalized Schur form T.

LDB (input)

The leading dimension of B. LDB $\geq \max(1,N)$.

SDIM (output)

If SORT = 'N', SDIM = 0. If SORT = 'S', SDIM =

number of eigenvalues (after sorting) for which SELECTG is true. (Complex conjugate pairs for which SELECTG is true for either eigenvalue count as 2.)

ALPHAR (output)

On exit, $(\text{ALPHAR}(j) + \text{ALPHAI}(j)*i)/\text{BETA}(j)$, $j=1,\dots,N$, will be the generalized eigenvalues. $\text{ALPHAR}(j) + \text{ALPHAI}(j)*i$, and $\text{BETA}(j)$, $j=1,\dots,N$ are the diagonals of the complex Schur form (S,T) that would result if the 2-by-2 diagonal blocks of the real Schur form of (A,B) were further reduced to triangular form using 2-by-2 complex unitary transformations. If $\text{ALPHAI}(j)$ is zero, then the j -th eigenvalue is real; if positive, then the j -th and $(j+1)$ -st eigenvalues are a complex conjugate pair, with $\text{ALPHAI}(j+1)$ negative.

Note: the quotients $\text{ALPHAR}(j)/\text{BETA}(j)$ and $\text{ALPHAI}(j)/\text{BETA}(j)$ may easily over- or underflow, and $\text{BETA}(j)$ may even be zero. Thus, the user should avoid naively computing the ratio. However, ALPHAR and ALPHAI will be always less than and usually comparable with $\text{norm}(A)$ in magnitude, and BETA always less than and usually comparable with $\text{norm}(B)$.

ALPHAI (output)

See the description for ALPHAR.

BETA (output)

See the description for ALPHAR.

VSL (input)

If $\text{JOBVSL} = 'V'$, VSL will contain the left Schur vectors. Not referenced if $\text{JOBVSL} = 'N'$.

LDVSL (input)

The leading dimension of the matrix VSL. $\text{LDVSL} \geq 1$, and if $\text{JOBVSL} = 'V'$, $\text{LDVSL} \geq N$.

VSR (input)

If $\text{JOBVSR} = 'V'$, VSR will contain the right Schur vectors. Not referenced if $\text{JOBVSR} = 'N'$.

LDVSR (input)

The leading dimension of the matrix VSR. $\text{LDVSR} \geq 1$, and if $\text{JOBVSR} = 'V'$, $\text{LDVSR} \geq N$.

WORK (workspace)

On exit, if $\text{INFO} = 0$, $\text{WORK}(1)$ returns the optimal LWORK .

LWORK (input)

The dimension of the array WORK. $\text{LWORK} \geq 8*N+16$.

If $\text{LWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

BWORK (workspace)
dimension(N) Not referenced if SORT = 'N'.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for j=INFO+1,...,N. >
N: =N+1: other than QZ iteration failed in SHGEQZ.
=N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Generalized Schur form no longer satisfy SELCTG=.TRUE. This could also be caused due to scaling. =N+3: reordering failed in STGSEN.

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NAME

sggesx - compute for a pair of N-by-N real nonsymmetric matrices (A,B), the generalized eigenvalues, the real Schur form (S,T), and,

SYNOPSIS

```
SUBROUTINE SGGESX(JOBVSL, JOBVSR, SORT, SELCTG, SENSE, N, A, LDA, B,
  LDB, SDIM, ALPHAR, ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR, RCONDE,
  RCONDV, WORK, LWORK, IWORK, LIWORK, BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT, SENSE
INTEGER N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL SELCTG
LOGICAL BWORK(*)
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), RCONDE(*), RCONDV(*), WORK(*)
```

```
SUBROUTINE SGGESX_64(JOBVSL, JOBVSR, SORT, SELCTG, SENSE, N, A, LDA,
  B, LDB, SDIM, ALPHAR, ALPHAI, BETA, VSL, LDVSL, VSR, LDVSR,
  RCONDE, RCONDV, WORK, LWORK, IWORK, LIWORK, BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT, SENSE
INTEGER*8 N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK,
INFO
INTEGER*8 IWORK(*)
LOGICAL*8 SELCTG
LOGICAL*8 BWORK(*)
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), RCONDE(*), RCONDV(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGESX(JOBVSL, JOBVSR, SORT, [SELCTG], SENSE, [N], A, [LDA],
  B, [LDB], SDIM, ALPHAR, ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR],
  RCONDE, RCONDV, [WORK], [LWORK], [IWORK], [LIWORK], [BWORK],
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT, SENSE
INTEGER :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK,
INFO
```

```

INTEGER, DIMENSION(:) :: IWORK
LOGICAL :: SELCTG
LOGICAL, DIMENSION(:) :: BWORK
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, RCONDE, RCONDV,
WORK
REAL, DIMENSION(:, :) :: A, B, VSL, VSR
SUBROUTINE GGESX_64(JOBVSL, JOBVSR, SORT, [SELCTG], SENSE, [N], A, [LDA],
    B, [LDB], SDIM, ALPHAR, ALPHAI, BETA, VSL, [LDVSL], VSR, [LDVSR],
    RCONDE, RCONDV, [WORK], [LWORK], [IWORK], [LIWORK], [BWORK],
    [INFO])

CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT, SENSE
INTEGER(8) :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK,
LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8) :: SELCTG
LOGICAL(8), DIMENSION(:) :: BWORK
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, RCONDE, RCONDV,
WORK
REAL, DIMENSION(:, :) :: A, B, VSL, VSR

```

C INTERFACE

```

#include <sunperf.h>

void ssgesx(char jobvsl, char jobvsr, char sort,
    int(*selctg)(float,float,float), char sense, int
    n, float *a, int lda, float *b, int ldb, int
    *sdim, float *alphar, float *alphai, float *beta,
    float *vsl, int ldvsl, float *vsr, int ldvsr,
    float *rconde, float *rcondv, int *info);

void ssgesx_64(char jobvsl, char jobvsr, char sort,
    long(*selctg)(float,float,float), char sense, long
    n, float *a, long lda, float *b, long ldb, long
    *sdim, float *alphar, float *alphai, float *beta,
    float *vsl, long ldvsl, float *vsr, long ldvsr,
    float *rconde, float *rcondv, long *info);

```

PURPOSE

sggesx computes for a pair of N-by-N real nonsymmetric matrices (A,B), the generalized eigenvalues, the real Schur form (S,T), and, optionally, the left and/or right matrices of Schur vectors (VSL and VSR). This gives the generalized Schur factorization

$$A,B) = ((VSL) S (VSR)**T, (VSL) T (VSR)**T)$$

Optionally, it also orders the eigenvalues so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix S and the upper triangular matrix T; computes a reciprocal condition number for the average of the selected eigenvalues (RCONDE); and computes a reciprocal condition number for the right and left deflating subspaces corresponding to the selected eigenvalues (RCONDV). The leading columns of VSL and VSR then form an orthonormal basis for the corresponding left and right eigenspaces (deflating subspaces).

A generalized eigenvalue for a pair of matrices (A,B) is a scalar w or a ratio $\alpha/\beta = w$, such that $A - w*B$ is singular. It is usually represented as the pair (α,β) , as there is a reasonable interpretation for $\beta=0$ or for both being zero.

A pair of matrices (S,T) is in generalized real Schur form if T is upper triangular with non-negative diagonal and S is block upper triangular with 1-by-1 and 2-by-2 blocks. 1-by-1 blocks correspond to real generalized eigenvalues, while 2-by-2 blocks of S will be "standardized" by making the corresponding elements of T have the form:

$$\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$$

and the pair of corresponding 2-by-2 blocks in S and T will have a complex conjugate pair of generalized eigenvalues.

ARGUMENTS

JOBVSL (input)

= 'N': do not compute the left Schur vectors;
= 'V': compute the left Schur vectors.

JOBVSR (input)

= 'N': do not compute the right Schur vectors;
= 'V': compute the right Schur vectors.

SORT (input)

Specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form. = 'N': Eigenvalues are not ordered;
= 'S': Eigenvalues are ordered (see SELCTG).

SELCTG (input)

LOGICAL FUNCTION of three REAL arguments SELCTG must be declared EXTERNAL in the calling subroutine. If SORT = 'N', SELCTG is not referenced. If SORT = 'S', SELCTG is used to select eigenvalues to sort to the top left of the Schur form. An eigenvalue $(\text{ALPHAR}(j)+\text{ALPHAI}(j))/\text{BETA}(j)$ is selected if $\text{SELCTG}(\text{ALPHAR}(j),\text{ALPHAI}(j),\text{BETA}(j))$ is true; i.e. if either one of a complex conjugate pair of eigenvalues is selected, then both complex eigenvalues are selected. Note that a selected complex eigenvalue may no longer satisfy $\text{SELCTG}(\text{ALPHAR}(j),\text{ALPHAI}(j),\text{BETA}(j)) = \text{.TRUE.}$ after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned), in this case INFO is set to N+3.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N' : None are computed;
= 'E' : Computed for average of selected eigenvalues only;
= 'V' : Computed for selected deflating subspaces only;

= 'B' : Computed for both. If SENSE = 'E', 'V',
or 'B', SORT must equal 'S'.

N (input) The order of the matrices A, B, VSL, and VSR. N
>= 0.

A (input/output)
REAL array, dimension(LDA,N) On entry, the first
of the pair of matrices. On exit, A has been
overwritten by its generalized Schur form S.

LDA (input)
The leading dimension of A. LDA >= max(1,N).

B (input/output)
REAL array, dimension(LDB,N) On entry, the second
of the pair of matrices. On exit, B has been
overwritten by its generalized Schur form T.

LDB (input)
The leading dimension of B. LDB >= max(1,N).

SDIM (output)
If SORT = 'N', SDIM = 0. If SORT = 'S', SDIM =
number of eigenvalues (after sorting) for which
SELCTG is true. (Complex conjugate pairs for
which SELCTG is true for either eigenvalue count
as 2.)

ALPHAR (output)
REAL array, dimension(N) On exit, (ALPHAR(j) +
ALPHAI(j)*i)/BETA(j), j=1,...,N, will be the gen-
eralized eigenvalues. ALPHAR(j) + ALPHAI(j)*i and
BETA(j), j=1,...,N are the diagonals of the com-
plex Schur form (S,T) that would result if the 2-
by-2 diagonal blocks of the real Schur form of
(A,B) were further reduced to triangular form
using 2-by-2 complex unitary transformations. If
ALPHAI(j) is zero, then the j-th eigenvalue is
real; if positive, then the j-th and (j+1)-st
eigenvalues are a complex conjugate pair, with
ALPHAI(j+1) negative.

Note: the quotients ALPHAR(j)/BETA(j) and
ALPHAI(j)/BETA(j) may easily over- or underflow,
and BETA(j) may even be zero. Thus, the user
should avoid naively computing the ratio. How-
ever, ALPHAR and ALPHAI will be always less than
and usually comparable with norm(A) in magnitude,
and BETA always less than and usually comparable
with norm(B).

ALPHAI (output)
REAL array, dimension(N) See the description for
ALPHAR.

BETA (output)
REAL array, dimension(N) See the description for
ALPHAR.

VSL (input)

REAL array, dimension(LDVSL,N) If JOBVSL = 'V', VSL will contain the left Schur vectors. Not referenced if JOBVSL = 'N'.

LDVSL (input)

The leading dimension of the matrix VSL. LDVSL \geq 1, and if JOBVSL = 'V', LDVSL \geq N.

VSR (input)

REAL array, dimension(LDVSR,N) If JOBVSR = 'V', VSR will contain the right Schur vectors. Not referenced if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR \geq 1, and if JOBVSR = 'V', LDVSR \geq N.

RCONDE (output)

If SENSE = 'E' or 'B', RCONDE(1) and RCONDE(2) contain the reciprocal condition numbers for the average of the selected eigenvalues. Not referenced if SENSE = 'N' or 'V'.

RCONDV (output)

If SENSE = 'V' or 'B', RCONDV(1) and RCONDV(2) contain the reciprocal condition numbers for the selected deflating subspaces. Not referenced if SENSE = 'N' or 'E'.

WORK (workspace)

REAL array, dimension(LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq $8*(N+1)+16$. If SENSE = 'E', 'V', or 'B', LWORK \geq $\text{MAX}(8*(N+1)+16, 2*SDIM*(N-SDIM))$.

IWORK (workspace)

INTEGER array, dimension(LIWORK) Not referenced if SENSE = 'N'.

LIWORK (input)

The dimension of the array WORK. LIWORK \geq N+6.

BWORK (workspace)

LOGICAL array, dimension(N) Not referenced if SORT = 'N'.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for $j=\text{INFO}+1, \dots, N$.
> N: =N+1: other than QZ iteration failed in SHGEQZ
=N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Generalized Schur form no longer satisfy SELCTG=.TRUE. This could also be

caused due to scaling. =N+3: reordering failed in STGSEN.

Further details =====

An approximate (asymptotic) bound on the average absolute error of the selected eigenvalues is

$$\text{EPS} * \text{norm}((A, B)) / \text{RCONDE}(1).$$

An approximate (asymptotic) bound on the maximum angular error in the computed deflating subspaces is

$$\text{EPS} * \text{norm}((A, B)) / \text{RCONDV}(2).$$

See LAPACK User's Guide, section 4.11 for more information.

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NAME

sggev - compute for a pair of N-by-N real nonsymmetric matrices (A,B)

SYNOPSIS

```
SUBROUTINE SGGEV(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,  
                BETA, VL, LDVL, VR, LDVR, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
INTEGER N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),  
VL(LDVL,*), VR(LDVR,*), WORK(*)
```

```
SUBROUTINE SGGEV_64(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHAR, ALPHAI,  
                  BETA, VL, LDVL, VR, LDVR, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),  
VL(LDVL,*), VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGEV(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHAR,  
              ALPHAI, BETA, VL, [LDVL], VR, [LDVR], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
INTEGER :: N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK  
REAL, DIMENSION(:,) :: A, B, VL, VR
```

```
SUBROUTINE GGEV_64(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHAR,  
                  ALPHAI, BETA, VL, [LDVL], VR, [LDVR], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, LWORK, INFO  
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK  
REAL, DIMENSION(:,) :: A, B, VL, VR
```

C INTERFACE

```
#include <sunperf.h>
```

```

void sggev(char jobvl, char jobvr, int n, float *a, int lda,
           float *b, int ldb, float *alphan, float *alphai,
           float *beta, float *vl, int ldvl, float *vr, int
           ldvr, int *info);
void sggev_64(char jobvl, char jobvr, long n, float *a, long
             lda, float *b, long ldb, float *alphan, float
             *alphai, float *beta, float *vl, long ldvl, float
             *vr, long ldvr, long *info);

```

PURPOSE

sggev computes for a pair of N-by-N real nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors.

A generalized eigenvalue for a pair of matrices (A,B) is a scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β) , as there is a reasonable interpretation for $\beta=0$, and even for both being zero.

The right eigenvector $v(j)$ corresponding to the eigenvalue $\lambda(j)$ of (A,B) satisfies

$$A * v(j) = \lambda(j) * B * v(j).$$

The left eigenvector $u(j)$ corresponding to the eigenvalue $\lambda(j)$ of (A,B) satisfies

$$u(j)**H * A = \lambda(j) * u(j)**H * B .$$

where $u(j)**H$ is the conjugate-transpose of $u(j)$.

ARGUMENTS

JOBVL (input)
 = 'N': do not compute the left generalized eigenvectors;
 = 'V': compute the left generalized eigenvectors.

JOBVR (input)
 = 'N': do not compute the right generalized eigenvectors;
 = 'V': compute the right generalized eigenvectors.

N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)
 On entry, the matrix A in the pair (A,B). On exit, A has been overwritten.

LDA (input)
 The leading dimension of A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the matrix B in the pair (A,B). On exit, B has been overwritten.

LDB (input)

The leading dimension of B. $LDB \geq \max(1,N)$.

ALPHAR (output)

On exit, $(ALPHAR(j) + ALPHAI(j)*i)/BETA(j)$, $j=1,\dots,N$, will be the generalized eigenvalues. If $ALPHAI(j)$ is zero, then the j-th eigenvalue is real; if positive, then the j-th and (j+1)-st eigenvalues are a complex conjugate pair, with $ALPHAI(j+1)$ negative.

Note: the quotients $ALPHAR(j)/BETA(j)$ and $ALPHAI(j)/BETA(j)$ may easily over- or underflow, and $BETA(j)$ may even be zero. Thus, the user should avoid naively computing the ratio α/β . However, $ALPHAR$ and $ALPHAI$ will be always less than and usually comparable with $\text{norm}(A)$ in magnitude, and $BETA$ always less than and usually comparable with $\text{norm}(B)$.

ALPHAI (output)

See the description for $ALPHAR$.

BETA (output)

See the description for $ALPHAR$.

VL (input)

If $JOBVL = 'V'$, the left eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. If the j-th eigenvalue is real, then $u(j) = VL(:,j)$, the j-th column of VL. If the j-th and (j+1)-th eigenvalues form a complex conjugate pair, then $u(j) = VL(:,j) + i*VL(:,j+1)$ and $u(j+1) = VL(:,j) - i*VL(:,j+1)$. Each eigenvector will be scaled so the largest component have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if $JOBVL = 'N'$.

LDVL (input)

The leading dimension of the matrix VL. $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (input)

If $JOBVR = 'V'$, the right eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. If the j-th eigenvalue is real, then $v(j) = VR(:,j)$, the j-th column of VR. If the j-th and (j+1)-th eigenvalues form a complex conjugate pair, then $v(j) = VR(:,j) + i*VR(:,j+1)$ and $v(j+1) = VR(:,j) - i*VR(:,j+1)$. Each eigenvector will be scaled so the largest component have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if $JOBVR = 'N'$.

LDVR (input)
 The leading dimension of the matrix VR. LDVR \geq 1,
 and if JOBVR = 'V', LDVR \geq N.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal
 LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq
 max(1,8*N). For good performance, LWORK must gen-
 erally be larger.

If LWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the WORK array, returns this value as the first
 entry of the WORK array, and no error message
 related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-
 gal value.
 = 1,...,N: The QZ iteration failed. No eigenvec-
 tors have been calculated, but ALPHAR(j),
 ALPHAI(j), and BETA(j) should be correct for
 j=INFO+1,...,N. > N: =N+1: other than QZ itera-
 tion failed in SHGEQZ.
 =N+2: error return from STGEVC.

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NAME

sggev_x - compute for a pair of N-by-N real nonsymmetric matrices (A,B)

SYNOPSIS

```
SUBROUTINE SGGEVX(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, B, LDB,  
    ALPHAR, ALPHAI, BETA, VL, LDVL, VR, LDVR, ILO, IHI, LSCALE,  
    RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, WORK, LWORK, IWORK, BWORK,  
    INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE  
INTEGER N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO  
INTEGER IWORK(*)  
LOGICAL BWORK(*)  
REAL ABNRM, BBNRM  
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),  
VL(LDVL,*), VR(LDVR,*), LSCALE(*), RSCALE(*), RCONDE(*),  
RCONDV(*), WORK(*)
```

```
SUBROUTINE SGGEVX_64(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, B, LDB,  
    ALPHAR, ALPHAI, BETA, VL, LDVL, VR, LDVR, ILO, IHI, LSCALE,  
    RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, WORK, LWORK, IWORK, BWORK,  
    INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO  
INTEGER*8 IWORK(*)  
LOGICAL*8 BWORK(*)  
REAL ABNRM, BBNRM  
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),  
VL(LDVL,*), VR(LDVR,*), LSCALE(*), RSCALE(*), RCONDE(*),  
RCONDV(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGEVX(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], B, [LDB],  
    ALPHAR, ALPHAI, BETA, VL, [LDVL], VR, [LDVR], ILO, IHI, LSCALE,  
    RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, [WORK], [LWORK], [IWORK],  
    [BWORK], [INFO])
```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
INTEGER :: N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL, DIMENSION(:) :: BWORK
REAL :: ABNRM, BBNRM
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, LSCALE, RSCALE,
RCONDE, RCONDV, WORK
REAL, DIMENSION(:,:) :: A, B, VL, VR
SUBROUTINE GGEVX_64(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], B,
[LDB], ALPHAR, ALPHAI, BETA, VL, [LDVL], VR, [LDVR], ILO, IHI,
LSCALE, RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, [WORK], [LWORK],
[IWORK], [BWORK], [INFO])

```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8), DIMENSION(:) :: BWORK
REAL :: ABNRM, BBNRM
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, LSCALE, RSCALE,
RCONDE, RCONDV, WORK
REAL, DIMENSION(:,:) :: A, B, VL, VR

```

C INTERFACE

```

#include <sunperf.h>

void sggevxx(char balanc, char jobvl, char jobvr, char sense,
int n, float *a, int lda, float *b, int ldb, float
*alphar, float *alphai, float *beta, float *vl,
int ldvl, float *vr, int ldvr, int *ilo, int *ihi,
float *lscale, float *rscale, float *abnrm, float
*bbnrm, float *rconde, float *rcondv, int *info);

void sggevxx_64(char balanc, char jobvl, char jobvr, char
sense, long n, float *a, long lda, float *b, long
ldb, float *alphar, float *alphai, float *beta,
float *vl, long ldvl, float *vr, long ldvr, long
*ilo, long *ihi, float *lscale, float *rscale,
float *abnrm, float *bbnrm, float *rconde, float
*rcondv, long *info);

```

PURPOSE

sggevxx computes for a pair of N-by-N real nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors.

Optionally also, it computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors (ILO, IHI, LSCALE, RSCALE, ABNRM, and BBNRM), reciprocal condition numbers for the eigenvalues (RCONDE), and reciprocal condition numbers for the right eigenvectors (RCONDV).

A generalized eigenvalue for a pair of matrices (A,B) is a scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β) , as there is a reasonable interpretation for $\beta=0$, and even for both being zero.

The right eigenvector $v(j)$ corresponding to the eigenvalue

lambda(j) of (A,B) satisfies

$$A * v(j) = \text{lambda}(j) * B * v(j) .$$

The left eigenvector u(j) corresponding to the eigenvalue lambda(j) of (A,B) satisfies

$$u(j)**H * A = \text{lambda}(j) * u(j)**H * B.$$

where u(j)**H is the conjugate-transpose of u(j).

ARGUMENTS

BALANC (input)

Specifies the balance option to be performed. =
= 'N': do not diagonally scale or permute;
= 'P': permute only;
= 'S': scale only;
= 'B': both permute and scale. Computed reciprocal condition numbers will be for the matrices after permuting and/or balancing. Permuting does not change condition numbers (in exact arithmetic), but balancing does.

JOBVL (input)

= 'N': do not compute the left generalized eigenvectors;
= 'V': compute the left generalized eigenvectors.

JOBVR (input)

= 'N': do not compute the right generalized eigenvectors;
= 'V': compute the right generalized eigenvectors.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': none are computed;
= 'E': computed for eigenvalues only;
= 'V': computed for eigenvectors only;
= 'B': computed for eigenvalues and eigenvectors.

N (input) The order of the matrices A, B, VL, and VR. N >= 0.

A (input/output)

On entry, the matrix A in the pair (A,B). On exit, A has been overwritten. If JOBVL='V' or JOBVR='V' or both, then A contains the first part of the real Schur form of the "balanced" versions of the input A and B.

LDA (input)

The leading dimension of A. LDA >= max(1,N).

B (input/output)

On entry, the matrix B in the pair (A,B). On exit, B has been overwritten. If JOBVL='V' or JOBVR='V' or both, then B contains the second part of the real Schur form of the "balanced" versions

of the input A and B.

LDB (input)

The leading dimension of B. $LDB \geq \max(1,N)$.

ALPHAR (output)

On exit, $(ALPHAR(j) + ALPHAI(j)*i)/BETA(j)$, $j=1,\dots,N$, will be the generalized eigenvalues. If $ALPHAI(j)$ is zero, then the j -th eigenvalue is real; if positive, then the j -th and $(j+1)$ -st eigenvalues are a complex conjugate pair, with $ALPHAI(j+1)$ negative.

Note: the quotients $ALPHAR(j)/BETA(j)$ and $ALPHAI(j)/BETA(j)$ may easily over- or underflow, and $BETA(j)$ may even be zero. Thus, the user should avoid naively computing the ratio $ALPHA/BETA$. However, $ALPHAR$ and $ALPHAI$ will be always less than and usually comparable with $\text{norm}(A)$ in magnitude, and $BETA$ always less than and usually comparable with $\text{norm}(B)$.

ALPHAI (output)

See the description of $ALPHAR$.

BETA (output)

See the description of $ALPHAR$.

VL (output)

If $JOBVL = 'V'$, the left eigenvectors $u(j)$ are stored one after another in the columns of VL , in the same order as their eigenvalues. If the j -th eigenvalue is real, then $u(j) = VL(:,j)$, the j -th column of VL . If the j -th and $(j+1)$ -th eigenvalues form a complex conjugate pair, then $u(j) = VL(:,j) + i*VL(:,j+1)$ and $u(j+1) = VL(:,j) - i*VL(:,j+1)$. Each eigenvector will be scaled so the largest component have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if $JOBVL = 'N'$.

LDVL (input)

The leading dimension of the matrix VL . $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (output)

If $JOBVR = 'V'$, the right eigenvectors $v(j)$ are stored one after another in the columns of VR , in the same order as their eigenvalues. If the j -th eigenvalue is real, then $v(j) = VR(:,j)$, the j -th column of VR . If the j -th and $(j+1)$ -th eigenvalues form a complex conjugate pair, then $v(j) = VR(:,j) + i*VR(:,j+1)$ and $v(j+1) = VR(:,j) - i*VR(:,j+1)$. Each eigenvector will be scaled so the largest component have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$. Not referenced if $JOBVR = 'N'$.

LDVR (input)

The leading dimension of the matrix VR . $LDVR \geq 1$, and if $JOBVR = 'V'$, $LDVR \geq N$.

ILO (output)

ILO and IHI are integer values such that on exit $A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1, \dots, ILO-1$ or $i = IHI+1, \dots, N$. If `BALANC = 'N'` or `'S'`, $ILO = 1$ and $IHI = N$.

IHI (output)

See the description of ILO.

LSCALE (output)

Details of the permutations and scaling factors applied to the left side of A and B. If $PL(j)$ is the index of the row interchanged with row j , and $DL(j)$ is the scaling factor applied to row j , then $LSCALE(j) = PL(j)$ for $j = 1, \dots, ILO-1 = DL(j)$ for $j = ILO, \dots, IHI = PL(j)$ for $j = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

RSCALE (output)

Details of the permutations and scaling factors applied to the right side of A and B. If $PR(j)$ is the index of the column interchanged with column j , and $DR(j)$ is the scaling factor applied to column j , then $RSCALE(j) = PR(j)$ for $j = 1, \dots, ILO-1 = DR(j)$ for $j = ILO, \dots, IHI = PR(j)$ for $j = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

ABNRM (output)

The one-norm of the balanced matrix A.

BBNRM (output)

The one-norm of the balanced matrix B.

RCONDE (output)

If `SENSE = 'E'` or `'B'`, the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. For a complex conjugate pair of eigenvalues two consecutive elements of `RCONDE` are set to the same value. Thus $RCONDE(j)$, $RCONDV(j)$, and the j -th columns of `VL` and `VR` all correspond to the same eigenpair (but not in general the j -th eigenpair, unless all eigenpairs are selected). If `SENSE = 'V'`, `RCONDE` is not referenced.

RCONDV (output)

If `SENSE = 'V'` or `'B'`, the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. For a complex eigenvector two consecutive elements of `RCONDV` are set to the same value. If the eigenvalues cannot be reordered to compute $RCONDV(j)$, $RCONDV(j)$ is set to 0; this can only occur when the true value would be very small anyway. If `SENSE = 'E'`, `RCONDV` is not referenced.

WORK (workspace)

On exit, if `INFO = 0`, `WORK(1)` returns the optimal

LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq $\max(1, 6*N)$. If SENSE = 'E', LWORK \geq $12*N$. If SENSE = 'V' or 'B', LWORK \geq $2*N*N+12*N+16$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)

dimension(N+6) If SENSE = 'E', IWORK is not referenced.

BWORK (workspace)

dimension(N) If SENSE = 'N', BWORK is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. No eigenvectors have been calculated, but ALPHAR(j), ALPHAI(j), and BETA(j) should be correct for $j=INFO+1, \dots, N$.
> N: =N+1: other than QZ iteration failed in SHGEQZ.
=N+2: error return from STGEVC.

FURTHER DETAILS

Balancing a matrix pair (A,B) includes, first, permuting rows and columns to isolate eigenvalues, second, applying diagonal similarity transformation to the rows and columns to make the rows and columns as close in norm as possible. The computed reciprocal condition numbers correspond to the balanced matrix. Permuting rows and columns will not change the condition numbers (in exact arithmetic) but diagonal scaling will. For further explanation of balancing, see section 4.11.1.2 of LAPACK Users' Guide.

An approximate error bound on the chordal distance between the i-th computed generalized eigenvalue w and the corresponding exact eigenvalue λ is $\text{hord}(w, \lambda) \leq \text{EPS} * \text{norm}(\text{ABNRM}, \text{BBNRM}) / \text{RCONDE}(i)$
An approximate error bound for the angle between the i-th computed eigenvector $VL(i)$ or $VR(i)$ is given by $\text{PS} * \text{norm}(\text{ABNRM}, \text{BBNRM}) / \text{DIF}(i)$.

For further explanation of the reciprocal condition numbers RCONDE and RCONDV, see section 4.11 of LAPACK User's Guide.

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NAME

sggglm - solve a general Gauss-Markov linear model (GLM) problem

SYNOPSIS

```
SUBROUTINE SGGGLM(N, M, P, A, LDA, B, LDB, D, X, Y, WORK, LDWORK,  
INFO)
```

```
INTEGER N, M, P, LDA, LDB, LDWORK, INFO  
REAL A(LDA,*), B(LDB,*), D(*), X(*), Y(*), WORK(*)
```

```
SUBROUTINE SGGGLM_64(N, M, P, A, LDA, B, LDB, D, X, Y, WORK, LDWORK,  
INFO)
```

```
INTEGER*8 N, M, P, LDA, LDB, LDWORK, INFO  
REAL A(LDA,*), B(LDB,*), D(*), X(*), Y(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGGLM([N], [M], [P], A, [LDA], B, [LDB], D, X, Y, [WORK],  
[LDWORK], [INFO])
```

```
INTEGER :: N, M, P, LDA, LDB, LDWORK, INFO  
REAL, DIMENSION(:) :: D, X, Y, WORK  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE GGGLM_64([N], [M], [P], A, [LDA], B, [LDB], D, X, Y, [WORK],  
[LDWORK], [INFO])
```

```
INTEGER(8) :: N, M, P, LDA, LDB, LDWORK, INFO  
REAL, DIMENSION(:) :: D, X, Y, WORK  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sggglm(int n, int m, int p, float *a, int lda, float  
*b, int ldb, float *d, float *x, float *y, int  
*info);
```

```
void sggglm_64(long n, long m, long p, float *a, long lda,
```

```
float *b, long ldb, float *d, float *x, float *y,  
long *info);
```

PURPOSE

sggglm solves a general Gauss-Markov linear model (GLM) problem:

$$\underset{x}{\text{minimize}} \quad || y ||_2 \quad \text{subject to} \quad d = A*x + B*y$$

where A is an N-by-M matrix, B is an N-by-P matrix, and d is a given N-vector. It is assumed that $M \leq N \leq M+P$, and

$$\text{rank}(A) = M \quad \text{and} \quad \text{rank}(A \ B) = N.$$

Under these assumptions, the constrained equation is always consistent, and there is a unique solution x and a minimal 2-norm solution y, which is obtained using a generalized QR factorization of A and B.

In particular, if matrix B is square nonsingular, then the problem GLM is equivalent to the following weighted linear least squares problem

$$\underset{x}{\text{minimize}} \quad || \text{inv}(B)*(d-A*x) ||_2$$

where $\text{inv}(B)$ denotes the inverse of B.

ARGUMENTS

N (input) The number of rows of the matrices A and B. $N \geq 0$.

M (input) The number of columns of the matrix A. $0 \leq M \leq N$.

P (input) The number of columns of the matrix B. $P \geq N-M$.

A (input/output)
On entry, the N-by-M matrix A. On exit, A is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)
On entry, the N-by-P matrix B. On exit, B is destroyed.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1,N)$.

D (input/output)

On entry, D is the left hand side of the GLM equation. On exit, D is destroyed.

X (output)

On exit, X and Y are the solutions of the GLM problem.

Y (output)

See the description of X.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq max(1,N+M+P). For optimum performance, LDWORK \geq M+min(N,P)+max(N,P)*NB, where NB is an upper bound for the optimal blocksizes for SGEQRF, SGERQF, SORMQR and SORMRQ.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

sgghrd - reduce a pair of real matrices (A,B) to generalized upper Hessenberg form using orthogonal transformations, where A is a general matrix and B is upper triangular

SYNOPSIS

```
SUBROUTINE SGGHRD(COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB, Q, LDQ,  
  Z, LDZ, INFO)
```

```
CHARACTER * 1 COMPQ, COMPZ  
INTEGER N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO  
REAL A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
```

```
SUBROUTINE SGGHRD_64(COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB, Q,  
  LDQ, Z, LDZ, INFO)
```

```
CHARACTER * 1 COMPQ, COMPZ  
INTEGER*8 N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO  
REAL A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
```

F95 INTERFACE

```
SUBROUTINE GGHRD(COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB], Q,  
  [LDQ], Z, [LDZ], [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ, COMPZ  
INTEGER :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO  
REAL, DIMENSION(:,:) :: A, B, Q, Z
```

```
SUBROUTINE GGHRD_64(COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB],  
  Q, [LDQ], Z, [LDZ], [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ, COMPZ  
INTEGER(8) :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO  
REAL, DIMENSION(:,:) :: A, B, Q, Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgghrd(char compq, char compz, int n, int ilo, int ihi,
            float *a, int lda, float *b, int ldb, float *q,
            int ldq, float *z, int ldz, int *info);
```

```
void sgghrd_64(char compq, char compz, long n, long ilo,
               long ihi, float *a, long lda, float *b, long ldb,
               float *q, long ldq, float *z, long ldz, long
               *info);
```

PURPOSE

sgghrd reduces a pair of real matrices (A,B) to generalized upper Hessenberg form using orthogonal transformations, where A is a general matrix and B is upper triangular: $Q' * A * Z = H$ and $Q' * B * Z = T$, where H is upper Hessenberg, T is upper triangular, and Q and Z are orthogonal, and ' ' means transpose.

The orthogonal matrices Q and Z are determined as products of Givens rotations. They may either be formed explicitly, or they may be postmultiplied into input matrices Q1 and Z1, so that

$$1 * A * Z1' = (Q1*Q) * H * (Z1*Z)'$$

ARGUMENTS

COMPQ (input)

= 'N': do not compute Q;
 = 'I': Q is initialized to the unit matrix, and the orthogonal matrix Q is returned; = 'V': Q must contain an orthogonal matrix Q1 on entry, and the product Q1*Q is returned.

COMPZ (input)

= 'N': do not compute Z;
 = 'I': Z is initialized to the unit matrix, and the orthogonal matrix Z is returned; = 'V': Z must contain an orthogonal matrix Z1 on entry, and the product Z1*Z is returned.

N (input) The order of the matrices A and B. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to SGGBAL; otherwise they should be set to 1 and N respectively. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)

See the description of ILO.

A (input/output)

On entry, the N-by-N general matrix to be reduced. On exit, the upper triangle and the first

subdiagonal of A are overwritten with the upper Hessenberg matrix H, and the rest is set to zero.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)

On entry, the N-by-N upper triangular matrix B. On exit, the upper triangular matrix $T = Q' B Z$. The elements below the diagonal are set to zero.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

Q (input/output)

If COMPQ='N': Q is not referenced.
If COMPQ='I': on entry, Q need not be set, and on exit it contains the orthogonal matrix Q, where Q' is the product of the Givens transformations which are applied to A and B on the left. If COMPQ='V': on entry, Q must contain an orthogonal matrix Q1, and on exit this is overwritten by Q1*Q.

LDQ (input)

The leading dimension of the array Q. LDQ \geq N if COMPQ='V' or 'I'; LDQ \geq 1 otherwise.

Z (input/output)

If COMPZ='N': Z is not referenced.
If COMPZ='I': on entry, Z need not be set, and on exit it contains the orthogonal matrix Z, which is the product of the Givens transformations which are applied to A and B on the right. If COMPZ='V': on entry, Z must contain an orthogonal matrix Z1, and on exit this is overwritten by Z1*Z.

LDZ (input)

The leading dimension of the array Z. LDZ \geq N if COMPZ='V' or 'I'; LDZ \geq 1 otherwise.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

This routine reduces A to Hessenberg and B to triangular form by an unblocked reduction, as described in *_Matrix Computations_*, by Golub and Van Loan (Johns Hopkins Press.)

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NAME

sgglse - solve the linear equality-constrained least squares (LSE) problem

SYNOPSIS

```
SUBROUTINE SGGLSE(M, N, P, A, LDA, B, LDB, C, D, X, WORK, LDWORK,  
INFO)
```

```
INTEGER M, N, P, LDA, LDB, LDWORK, INFO  
REAL A(LDA,*), B(LDB,*), C(*), D(*), X(*), WORK(*)
```

```
SUBROUTINE SGGLSE_64(M, N, P, A, LDA, B, LDB, C, D, X, WORK, LDWORK,  
INFO)
```

```
INTEGER*8 M, N, P, LDA, LDB, LDWORK, INFO  
REAL A(LDA,*), B(LDB,*), C(*), D(*), X(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGLSE([M], [N], [P], A, [LDA], B, [LDB], C, D, X, [WORK],  
[LDWORK], [INFO])
```

```
INTEGER :: M, N, P, LDA, LDB, LDWORK, INFO  
REAL, DIMENSION(:) :: C, D, X, WORK  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE GGLSE_64([M], [N], [P], A, [LDA], B, [LDB], C, D, X, [WORK],  
[LDWORK], [INFO])
```

```
INTEGER(8) :: M, N, P, LDA, LDB, LDWORK, INFO  
REAL, DIMENSION(:) :: C, D, X, WORK  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgglse(int m, int n, int p, float *a, int lda, float  
*b, int ldb, float *c, float *d, float *x, int  
*info);
```

```
void sgglse_64(long m, long n, long p, float *a, long lda,
```

```
float *b, long ldb, float *c, float *d, float *x,  
long *info);
```

PURPOSE

sgglse solves the linear equality-constrained least squares (LSE) problem:

$$\text{minimize } || c - A*x ||_2 \quad \text{subject to } B*x = d$$

where A is an M-by-N matrix, B is a P-by-N matrix, c is a given M-vector, and d is a given P-vector. It is assumed that

$P \leq N \leq M+P$, and

$$\text{rank}(B) = P \text{ and } \text{rank} \begin{pmatrix} A \\ B \end{pmatrix} = N.$$

These conditions ensure that the LSE problem has a unique solution, which is obtained using a GRQ factorization of the matrices B and A.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

P (input) The number of rows of the matrix B. $0 \leq P \leq N \leq M+P$.

A (input/output)
On entry, the M-by-N matrix A. On exit, A is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
On entry, the P-by-N matrix B. On exit, B is destroyed.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, P)$.

C (input/output)
On entry, C contains the right hand side vector for the least squares part of the LSE problem. On exit, the residual sum of squares for the solution is given by the sum of squares of elements N-P+1 to M of vector C.

D (input/output)
On entry, D contains the right hand side vector

for the constrained equation. On exit, D is destroyed.

X (output)

On exit, X is the solution of the LSE problem.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq max(1,M+N+P). For optimum performance LDWORK \geq P+min(M,N)+max(M,N)*NB, where NB is an upper bound for the optimal block sizes for SGEQRF, SGERQF, SORMQR and SORMRQ.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

sggqrf - compute a generalized QR factorization of an N-by-M matrix A and an N-by-P matrix B.

SYNOPSIS

```
SUBROUTINE SGGQRF(N, M, P, A, LDA, TAU, B, LDB, TAUB, WORK, LWORK,
                 INFO)
```

```
INTEGER N, M, P, LDA, LDB, LWORK, INFO
REAL A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
```

```
SUBROUTINE SGGQRF_64(N, M, P, A, LDA, TAU, B, LDB, TAUB, WORK,
                    LWORK, INFO)
```

```
INTEGER*8 N, M, P, LDA, LDB, LWORK, INFO
REAL A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGQRF([N], [M], [P], A, [LDA], TAU, B, [LDB], TAUB, [WORK],
                [LWORK], [INFO])
```

```
INTEGER :: N, M, P, LDA, LDB, LWORK, INFO
REAL, DIMENSION(:) :: TAU, TAUB, WORK
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GGQRF_64([N], [M], [P], A, [LDA], TAU, B, [LDB], TAUB,
                   [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: N, M, P, LDA, LDB, LWORK, INFO
REAL, DIMENSION(:) :: TAU, TAUB, WORK
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sggqrf(int n, int m, int p, float *a, int lda, float
           *tau, float *b, int ldb, float *taub, int *info);
```

```
void sggqrf_64(long n, long m, long p, float *a, long lda,
              float *taua, float *b, long ldb, float *taub, long
              *info);
```

PURPOSE

sggqrf computes a generalized QR factorization of an N-by-M matrix A and an N-by-P matrix B:

$$A = Q^*R, \quad B = Q^*T^*Z,$$

where Q is an N-by-N orthogonal matrix, Z is a P-by-P orthogonal matrix, and R and T assume one of the forms:

$$\text{if } N \geq M, \quad R = \begin{pmatrix} R_{11} & & \\ & & \\ & & \\ & 0 & \end{pmatrix} \begin{matrix} M \\ \\ \\ N-M \\ M \end{matrix}, \quad \text{or if } N < M, \quad R = \begin{pmatrix} R_{11} & R_{12} \\ & \\ & \\ & 0 & \end{pmatrix} \begin{matrix} N \\ M-N \\ \\ M \end{matrix}$$

where R11 is upper triangular, and

$$\text{if } N \leq P, \quad T = \begin{pmatrix} 0 & T_{12} \\ & \\ & \\ & 0 & \end{pmatrix} \begin{matrix} N \\ P-N \\ N \\ \\ \end{matrix}, \quad \text{or if } N > P, \quad T = \begin{pmatrix} T_{11} \\ & \\ & \\ & T_{21} \\ & & & \end{pmatrix} \begin{matrix} P \\ \\ \\ P \\ P \end{matrix}$$

where T12 or T21 is upper triangular.

In particular, if B is square and nonsingular, the GQR factorization of A and B implicitly gives the QR factorization of $\text{inv}(B)^*A$:

$$\text{inv}(B)^*A = Z'*(\text{inv}(T)^*R)$$

where $\text{inv}(B)$ denotes the inverse of the matrix B, and Z' denotes the transpose of the matrix Z.

ARGUMENTS

N (input) The number of rows of the matrices A and B. N >= 0.

M (input) The number of columns of the matrix A. M >= 0.

P (input) The number of columns of the matrix B. P >= 0.

A (input/output)

On entry, the N-by-M matrix A. On exit, the elements on and above the diagonal of the array contain the $\min(N,M)$ -by-M upper trapezoidal matrix R (R is upper triangular if $N \geq M$); the elements below the diagonal, with the array TAUA, represent the orthogonal matrix Q as a product of $\min(N,M)$ elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. LDA >=

max(1,N).

TAUA (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Q (see Further Details).

B (input/output)

On entry, the N-by-P matrix B. On exit, if $N \leq P$, the upper triangle of the subarray B(1:N,P-N+1:P) contains the N-by-N upper triangular matrix T; if $N > P$, the elements on and above the (N-P)-th subdiagonal contain the N-by-P upper trapezoidal matrix T; the remaining elements, with the array TAUB, represent the orthogonal matrix Z as a product of elementary reflectors (see Further Details).

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

TAUB (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Z (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1,N,M,P)$. For optimum performance $LWORK \geq \max(N,M,P) * \max(NB1,NB2,NB3)$, where NB1 is the optimal blocksize for the QR factorization of an N-by-M matrix, NB2 is the optimal blocksize for the RQ factorization of an N-by-P matrix, and NB3 is the optimal blocksize for a call of SORMQR.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(n,m).$$

Each H(i) has the form

$$H(i) = I - \tau v v'$$

where taua is a real scalar, and v is a real vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:n)$ is stored on exit in $A(i+1:n,i)$, and taua in $TAUA(i)$.
To form Q explicitly, use LAPACK subroutine SORGQR.
To use Q to update another matrix, use LAPACK subroutine SORMQR.

The matrix Z is represented as a product of elementary reflectors

$$Z = H(1) H(2) \dots H(k), \text{ where } k = \min(n,p).$$

Each $H(i)$ has the form

$$H(i) = I - \text{taub} * v * v'$$

where taub is a real scalar, and v is a real vector with $v(p-k+i+1:p) = 0$ and $v(p-k+i) = 1$; $v(1:p-k+i-1)$ is stored on exit in $B(n-k+i,1:p-k+i-1)$, and taub in $TAUB(i)$.
To form Z explicitly, use LAPACK subroutine SORGRQ.
To use Z to update another matrix, use LAPACK subroutine SORMRQ.

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NAME

sggrqf - compute a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B

SYNOPSIS

```
SUBROUTINE SGGRQF(M, P, N, A, LDA, TAUA, B, LDB, TAUB, WORK, LWORK,
                 INFO)
```

```
INTEGER M, P, N, LDA, LDB, LWORK, INFO
REAL A(LDA,*), TAUA(*), B(LDB,*), TAUB(*), WORK(*)
```

```
SUBROUTINE SGGRQF_64(M, P, N, A, LDA, TAUA, B, LDB, TAUB, WORK,
                    LWORK, INFO)
```

```
INTEGER*8 M, P, N, LDA, LDB, LWORK, INFO
REAL A(LDA,*), TAUA(*), B(LDB,*), TAUB(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGRQF([M], [P], [N], A, [LDA], TAUA, B, [LDB], TAUB, [WORK],
                 [LWORK], [INFO])
```

```
INTEGER :: M, P, N, LDA, LDB, LWORK, INFO
REAL, DIMENSION(:) :: TAUA, TAUB, WORK
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE GGRQF_64([M], [P], [N], A, [LDA], TAUA, B, [LDB], TAUB,
                   [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: M, P, N, LDA, LDB, LWORK, INFO
REAL, DIMENSION(:) :: TAUA, TAUB, WORK
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sggrqf(int m, int p, int n, float *a, int lda, float
            *taua, float *b, int ldb, float *taub, int *info);
```

```
void sggrqf_64(long m, long p, long n, float *a, long lda,
              float *taua, float *b, long ldb, float *taub, long
              *info);
```

PURPOSE

sggrqf computes a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B:

$$A = R*Q, \quad B = Z*T*Q,$$

where Q is an N-by-N orthogonal matrix, Z is a P-by-P orthogonal matrix, and R and T assume one of the forms:

$$\text{if } M \leq N, \quad R = \begin{pmatrix} 0 & R_{12} \\ & \end{pmatrix} \begin{matrix} M \\ M-N \end{matrix}, \quad \text{or if } M > N, \quad R = \begin{pmatrix} R_{11} \\ & R_{21} \end{pmatrix} \begin{matrix} N \\ N \end{matrix}$$

where R12 or R21 is upper triangular, and

$$\text{if } P \geq N, \quad T = \begin{pmatrix} T_{11} \\ & 0 \end{pmatrix} \begin{matrix} N \\ P-N \end{matrix}, \quad \text{or if } P < N, \quad T = \begin{pmatrix} T_{11} & T_{12} \\ & \end{pmatrix} \begin{matrix} P \\ N-P \end{matrix}$$

where T11 is upper triangular.

In particular, if B is square and nonsingular, the GRQ factorization of A and B implicitly gives the RQ factorization of $A*\text{inv}(B)$:

$$A*\text{inv}(B) = (R*\text{inv}(T))*Z'$$

where $\text{inv}(B)$ denotes the inverse of the matrix B, and Z' denotes the transpose of the matrix Z.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $M \leq N$, the upper triangle of the subarray A(1:M,N-M+1:N) contains the M-by-M upper triangular matrix R; if $M > N$, the elements on and above the (M-N)-th subdiagonal contain the M-by-N upper trapezoidal matrix R; the remaining elements, with the array TAUA, represent the orthogonal matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. LDA \geq max(1,M).

TAUA (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Q (see Further Details).

B (input/output)

On entry, the P-by-N matrix B. On exit, the elements on and above the diagonal of the array contain the min(P,N)-by-N upper trapezoidal matrix T (T is upper triangular if P \geq N); the elements below the diagonal, with the array TAUB, represent the orthogonal matrix Z as a product of elementary reflectors (see Further Details).

LDB (input)

The leading dimension of the array B. LDB \geq max(1,P).

TAUB (output)

The scalar factors of the elementary reflectors which represent the orthogonal matrix Z (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,N,M,P). For optimum performance LWORK \geq max(N,M,P)*max(NB1,NB2,NB3), where NB1 is the optimal blocksize for the RQ factorization of an M-by-N matrix, NB2 is the optimal blocksize for the QR factorization of a P-by-N matrix, and NB3 is the optimal blocksize for a call of SORMRQ.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m,n).$$

Each H(i) has the form

$$H(i) = I - \tau v v'$$

where taua is a real scalar, and v is a real vector with $v(n-k+i+1:n) = 0$ and $v(n-k+i) = 1$; $v(1:n-k+i-1)$ is stored on exit in $A(m-k+i,1:n-k+i-1)$, and taua in $TAUA(i)$. To form Q explicitly, use LAPACK subroutine SORGRQ. To use Q to update another matrix, use LAPACK subroutine SORMRQ.

The matrix Z is represented as a product of elementary reflectors

$$Z = H(1) H(2) \dots H(k), \text{ where } k = \min(p,n).$$

Each $H(i)$ has the form

$$H(i) = I - \text{taub} * v * v'$$

where taub is a real scalar, and v is a real vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:p)$ is stored on exit in $B(i+1:p,i)$, and taub in $TAUB(i)$. To form Z explicitly, use LAPACK subroutine SORGQR. To use Z to update another matrix, use LAPACK subroutine SORMQR.

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NAME

sggsvd - compute the generalized singular value decomposition (GSVD) of an M-by-N real matrix A and P-by-N real matrix B

SYNOPSIS

```
SUBROUTINE SGGSV(DJOBU, JOBV, JOBQ, M, N, P, K, L, A, LDA, B, LDB,
  ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, IWORK3, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
INTEGER M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO
INTEGER IWORK3(*)
REAL A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), U(LDU,*),
V(LDV,*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE SGGSV_64(DJOBU, JOBV, JOBQ, M, N, P, K, L, A, LDA, B, LDB,
  ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, IWORK3, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
INTEGER*8 M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO
INTEGER*8 IWORK3(*)
REAL A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), U(LDU,*),
V(LDV,*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGSVD(DJOBU, JOBV, JOBQ, [M], [N], [P], K, L, A, [LDA], B,
  [LDB], ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK], IWORK3,
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
INTEGER :: M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO
INTEGER, DIMENSION(:) :: IWORK3
REAL, DIMENSION(:) :: ALPHA, BETA, WORK
REAL, DIMENSION(:,:) :: A, B, U, V, Q
```

```
SUBROUTINE GGSVD_64(DJOBU, JOBV, JOBQ, [M], [N], [P], K, L, A, [LDA],
  B, [LDB], ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK],
  IWORK3, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
```

```

INTEGER(8) :: M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO
INTEGER(8), DIMENSION(:) :: IWORK3
REAL, DIMENSION(:) :: ALPHA, BETA, WORK
REAL, DIMENSION(:, :) :: A, B, U, V, Q

```

C INTERFACE

```

#include <sunperf.h>
void sggsvd(char jobu, char jobv, char jobq, int m, int n,
            int p, int *k, int *l, float *a, int lda, float
            *b, int ldb, float *alpha, float *beta, float *u,
            int ldu, float *v, int ldv, float *q, int ldq, int
            *iwork3, int *info);

void sggsvd_64(char jobu, char jobv, char jobq, long m, long
               n, long p, long *k, long *l, float *a, long lda,
               float *b, long ldb, float *alpha, float *beta,
               float *u, long ldu, float *v, long ldv, float *q,
               long ldq, long *iwork3, long *info);

```

PURPOSE

sggsvd computes the generalized singular value decomposition (GSVD) of an M-by-N real matrix A and P-by-N real matrix B:

$$U^*A*Q = D1*(\begin{matrix} 0 & R \end{matrix}), \quad V^*B*Q = D2*(\begin{matrix} 0 & R \end{matrix})$$

where U, V and Q are orthogonal matrices, and Z' is the transpose of Z. Let K+L = the effective numerical rank of the matrix (A',B')', then R is a K+L-by-K+L nonsingular upper triangular matrix, D1 and D2 are M-by-(K+L) and P-by-(K+L) "diagonal" matrices and of the following structures, respectively:

If M-K-L >= 0,

$$D1 = \begin{matrix} & & & K & L \\ & & & K & (\begin{matrix} I & 0 \end{matrix}) \\ & & & L & (\begin{matrix} 0 & C \end{matrix}) \\ & & M-K-L & (\begin{matrix} 0 & 0 \end{matrix}) \end{matrix}$$

$$D2 = \begin{matrix} & & & K & L \\ & & & L & (\begin{matrix} 0 & S \end{matrix}) \\ & & P-L & (\begin{matrix} 0 & 0 \end{matrix}) \end{matrix}$$

$$\begin{matrix} (\begin{matrix} 0 & R \end{matrix}) = K & (\begin{matrix} 0 & R11 & R12 \end{matrix}) \\ & L & (\begin{matrix} 0 & 0 & R22 \end{matrix}) \end{matrix}$$

where

$$\begin{aligned}
C &= \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(K+L)), \\
S &= \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(K+L)), \\
C^{**2} + S^{**2} &= I.
\end{aligned}$$

R is stored in A(1:K+L,N-K-L+1:N) on exit.

If M-K-L < 0,

$$\begin{aligned}
 D1 &= \begin{array}{ccc} & K & M-K & K+L-M \\ K & (I & 0 & 0) \\ M-K & (0 & C & 0) \end{array} \\
 D2 &= \begin{array}{ccc} & K & M-K & K+L-M \\ M-K & (0 & S & 0) \\ K+L-M & (0 & 0 & I) \\ P-L & (0 & 0 & 0) \end{array} \\
 (0 R) &= \begin{array}{cccc} & N-K-L & K & M-K & K+L-M \\ K & (0 & R11 & R12 & R13) \\ M-K & (0 & 0 & R22 & R23) \\ K+L-M & (0 & 0 & 0 & R33) \end{array}
 \end{aligned}$$

where

$$\begin{aligned}
 C &= \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(M)), \\
 S &= \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(M)), \\
 C^{**2} + S^{**2} &= I.
 \end{aligned}$$

(R11 R12 R13) is stored in A(1:M, N-K-L+1:N), and R33 is stored

$$\begin{aligned}
 &(0 R22 R23) \\
 &\text{in } B(M-K+1:L, N+M-K-L+1:N) \text{ on exit.}
 \end{aligned}$$

The routine computes C, S, R, and optionally the orthogonal transformation matrices U, V and Q.

In particular, if B is an N-by-N nonsingular matrix, then the GSVD of A and B implicitly gives the SVD of A*inv(B):

$$A * \text{inv}(B) = U * (D1 * \text{inv}(D2)) * V'$$

If (A', B')' has orthonormal columns, then the GSVD of A and B is also equal to the CS decomposition of A and B. Furthermore, the GSVD can be used to derive the solution of the eigenvalue problem:

$$A' * A x = \text{lambda} * B' * B x.$$

In some literature, the GSVD of A and B is presented in the form

$$U' * A * X = (0 D1), \quad V' * B * X = (0 D2)$$

where U and V are orthogonal and X is nonsingular, D1 and D2 are ``diagonal''. The former GSVD form can be converted to the latter form by taking the nonsingular matrix X as

$$\begin{aligned}
 X &= Q * (I \quad 0) \\
 &\quad (0 \text{ inv}(R)).
 \end{aligned}$$

ARGUMENTS

JOBV (input)
 = 'U': Orthogonal matrix U is computed;
 = 'N': U is not computed.

JOBV (input)
 = 'V': Orthogonal matrix V is computed;
 = 'N': V is not computed.

JOBQ (input)
 = 'Q': Orthogonal matrix Q is computed;
 = 'N': Q is not computed.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

K (output)
 On exit, K and L specify the dimension of the sub-blocks described in the Purpose section. $K + L =$ effective numerical rank of $(A',B)'$.

L (output)
 See the description of K.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A contains the triangular matrix R, or part of R. See Purpose for details.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1,M)$.

B (input/output)
 On entry, the P-by-N matrix B. On exit, B contains the triangular matrix R if $M-K-L < 0$. See Purpose for details.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1,P)$.

ALPHA (output)
 On exit, ALPHA and BETA contain the generalized singular value pairs of A and B; $ALPHA(1:K) = 1$, $BETA(1:K) = 0$, and if $M-K-L \geq 0$, $ALPHA(K+1:K+L) = C$, $BETA(K+1:K+L) = S$, or if $M-K-L < 0$, $ALPHA(K+1:M)=C$, $ALPHA(M+1:K+L)=0$, $BETA(K+1:M) = S$, $BETA(M+1:K+L) = 1$ and $ALPHA(K+L+1:N) = 0$, $BETA(K+L+1:N) = 0$.

BETA (output)
 See the description of ALPHA.

U (output)
 If $JOBU = 'U'$, U contains the M-by-M orthogonal matrix U. If $JOBU = 'N'$, U is not referenced.

LDU (input)
 The leading dimension of the array U. $LDU \geq \max(1,M)$ if $JOBU = 'U'$; $LDU \geq 1$ otherwise.

V (output)
 If $JOBV = 'V'$, V contains the P-by-P orthogonal matrix V. If $JOBV = 'N'$, V is not referenced.

LDV (input)
 The leading dimension of the array V. $LDV \geq \max(1,P)$ if $JOBV = 'V'$; $LDV \geq 1$ otherwise.

Q (output)
If JOBQ = 'Q', Q contains the N-by-N orthogonal matrix Q. If JOBQ = 'N', Q is not referenced.

LDQ (input)
The leading dimension of the array Q. LDQ \geq max(1,N) if JOBQ = 'Q'; LDQ \geq 1 otherwise.

WORK (workspace)
dimension (max(3*N,M,P)+N)

IWORK3 (output)
dimension(N) On exit, IWORK3 stores the sorting information. More precisely, the following loop will sort ALPHA for I = K+1, min(M,K+L) swap ALPHA(I) and ALPHA(IWORK3(I)) endfor such that ALPHA(1) \geq ALPHA(2) \geq ... \geq ALPHA(N).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = 1, the Jacobi-type procedure failed to converge. For further details, see subroutine STGSJA.

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NAME

sggsvp - compute orthogonal matrices U, V and Q such that $N-K-L \times K \times L \times U^T \times A \times Q = K \times (\begin{matrix} 0 & A_{12} & A_{13} \end{matrix})$ if $M-K-L \geq 0$

SYNOPSIS

```
SUBROUTINE SGGSPV(JOBU, JOBV, JOBQ, M, P, N, A, LDA, B, LDB, TOLA,
                 TOLB, K, L, U, LDU, V, LDV, Q, LDQ, IWORK, TAU, WORK, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
INTEGER M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER IWORK(*)
REAL TOLA, TOLB
REAL A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*), Q(LDQ,*),
TAU(*), WORK(*)
```

```
SUBROUTINE SGGSPV_64(JOBU, JOBV, JOBQ, M, P, N, A, LDA, B, LDB, TOLA,
                   TOLB, K, L, U, LDU, V, LDV, Q, LDQ, IWORK, TAU, WORK, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
INTEGER*8 M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER*8 IWORK(*)
REAL TOLA, TOLB
REAL A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*), Q(LDQ,*),
TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGSVP(JOBU, JOBV, JOBQ, [M], [P], [N], A, [LDA], B, [LDB],
                TOLA, TOLB, K, L, U, [LDU], V, [LDV], Q, [LDQ], [IWORK], [TAU],
                [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
INTEGER :: M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL :: TOLA, TOLB
REAL, DIMENSION(:) :: TAU, WORK
REAL, DIMENSION(:,:) :: A, B, U, V, Q
```

```
SUBROUTINE GGSVP_64(JOBU, JOBV, JOBQ, [M], [P], [N], A, [LDA], B,
```

```
[LDB], TOLA, TOLB, K, L, U, [LDU], V, [LDV], Q, [LDQ], [IWORK],
[TAU], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
INTEGER(8) :: M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL :: TOLA, TOLB
REAL, DIMENSION(:) :: TAU, WORK
REAL, DIMENSION(:, :) :: A, B, U, V, Q
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sggsvp(char jobu, char jobv, char jobq, int m, int p,
            int n, float *a, int lda, float *b, int ldb, float
            tola, float tolb, int *k, int *l, float *u, int
            ldu, float *v, int ldv, float *q, int ldq, int
            *info);
```

```
void sggsvp_64(char jobu, char jobv, char jobq, long m, long
               p, long n, float *a, long lda, float *b, long ldb,
               float tola, float tolb, long *k, long *l, float
               *u, long ldu, float *v, long ldv, float *q, long
               ldq, long *info);
```

PURPOSE

sggsvp computes orthogonal matrices U, V and Q such that

$$\begin{array}{ccc} & L & (\begin{array}{ccc} 0 & 0 & A23 \end{array}) \\ M-K-L & (\begin{array}{ccc} 0 & 0 & 0 \end{array}) & \end{array}$$

$$= \begin{array}{ccc} & N-K-L & K & L \\ & K & (\begin{array}{ccc} 0 & A12 & A13 \end{array}) & \text{if } M-K-L < 0; \\ M-K & (\begin{array}{ccc} 0 & 0 & A23 \end{array}) & \end{array}$$

$$V' * B * Q = \begin{array}{ccc} & N-K-L & K & L \\ L & (\begin{array}{ccc} 0 & 0 & B13 \end{array}) & \\ P-L & (\begin{array}{ccc} 0 & 0 & 0 \end{array}) & \end{array}$$

where the K-by-K matrix A12 and L-by-L matrix B13 are non-singular upper triangular; A23 is L-by-L upper triangular if M-K-L >= 0, otherwise A23 is (M-K)-by-L upper trapezoidal. K+L = the effective numerical rank of the (M+P)-by-N matrix (A',B')'. Z' denotes the transpose of Z.

This decomposition is the preprocessing step for computing the Generalized Singular Value Decomposition (GSVD), see subroutine SGGSD.

ARGUMENTS

JOBU (input)
 = 'U': Orthogonal matrix U is computed;
 = 'N': U is not computed.

JOBV (input)
 = 'V': Orthogonal matrix V is computed;

= 'N': V is not computed.
 JOBQ (input)
 = 'Q': Orthogonal matrix Q is computed;
 = 'N': Q is not computed.

M (input) The number of rows of the matrix A. $M \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A contains the triangular (or trapezoidal) matrix described in the Purpose section.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
 On entry, the P-by-N matrix B. On exit, B contains the triangular matrix described in the Purpose section.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, P)$.

TOLA (input)
 TOLA and TOLB are the thresholds to determine the effective numerical rank of matrix B and a sub-block of A. Generally, they are set to $TOLA = \max(M, N) * \text{norm}(A) * \text{MACHEPS}$, $TOLB = \max(P, N) * \text{norm}(B) * \text{MACHEPS}$. The size of TOLA and TOLB may affect the size of backward errors of the decomposition.

TOLB (input)
 See the description of TOLA.

K (output)
 On exit, K and L specify the dimension of the sub-blocks described in Purpose. $K + L =$ effective numerical rank of $(A', B)'$.

L (output)
 See the description of K.

U (input) If JOBU = 'U', U contains the orthogonal matrix U. If JOBU = 'N', U is not referenced.

LDU (input)
 The leading dimension of the array U. $LDU \geq \max(1, M)$ if JOBU = 'U'; $LDU \geq 1$ otherwise.

V (input) If JOBV = 'V', V contains the orthogonal matrix V. If JOBV = 'N', V is not referenced.

LDV (input)

The leading dimension of the array V. LDV \geq
max(1,P) if JOBV = 'V'; LDV \geq 1 otherwise.

Q (input) If JOBQ = 'Q', Q contains the orthogonal matrix Q.
If JOBQ = 'N', Q is not referenced.

LDQ (input)
The leading dimension of the array Q. LDQ \geq
max(1,N) if JOBQ = 'Q'; LDQ \geq 1 otherwise.

IWORK (workspace)
dimension(N)

TAU (workspace)
dimension(N)

WORK (workspace)
dimension(MAX(3*N,M,P))

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The subroutine uses LAPACK subroutine SGEQPF for the QR factorization with column pivoting to detect the effective numerical rank of the a matrix. It may be replaced by a better rank determination strategy.

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NAME

sgssco - General sparse solver condition number estimate.

SYNOPSIS

```
SUBROUTINE SGSSCO ( COND, HANDLE, IER )
```

```
INTEGER          IER
REAL             COND
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSCO - Condition number estimate.

PARAMETERS

COND - REAL

On exit, an estimate of the condition number of the factored matrix. Must be called after the numerical factorization subroutine, [SGSSFA\(\)](#).

HANDLE(150) - DOUBLE PRECISION array

On entry, [HANDLE\(*\)](#) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-700 : Invalid calling sequence - need to call SGSSFA first.

-710 : Condition number estimate not available (not implemented for this HANDLE's matrix type).

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NAME

sgssda - Deallocate working storage for the general sparse solver.

SYNOPSIS

```
SUBROUTINE SGSSDA ( HANDLE, IER )  
  
INTEGER          IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSDA - Deallocate dynamically allocated working storage.

PARAMETERS

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine.
Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

none

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- [SYNOPSIS](#)
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- [PARAMETERS](#)

NAME

sgssfa - General sparse solver numeric factorization.

SYNOPSIS

```
SUBROUTINE SGSSFA ( NEQNS, COLSTR, ROWIND, VALUES, HANDLE, IER )
```

```
INTEGER          NEQNS, COLSTR(*), ROWIND(*), IER
```

```
REAL             VALUES(*)
```

```
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSFA - Numeric factorization of a sparse matrix.

PARAMETERS

NEQNS - INTEGER

On entry, **NEQNS** specifies the number of equations in coefficient matrix. Unchanged on exit.

COLSTR(*) - INTEGER array

On entry, **COLSTR**(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure. Unchanged on exit.

ROWIND(*) - INTEGER array

On entry, **ROWIND**(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

VALUES(*) - REAL array

On entry, **VALUES**(*) is an array of size COLSTR(NEQNS+1)-1, containing the numeric values of the sparse matrix to be factored. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, **HANDLE**(*) is an array containing

information needed by the solver, and must be passed unchanged to each sparse solver subroutine.
Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 300 : Invalid calling sequence - need to call SGSSOR first.
- 301 : Failure to dynamically allocate memory.
- 666 : Internal error.

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NAME

sgssfs - General sparse solver one call interface.

SYNOPSIS

```
SUBROUTINE SGSSFS ( MTXTYP, PIVOT , NEQNS, COLSTR, ROWIND,
                   VALUES, NRHS , RHS , LDRHS , ORDMTHD,
                   OUTUNT, MSGLVL, HANDLE, IER )
```

```
CHARACTER*2      MTXTYP
CHARACTER*1      PIVOT
INTEGER          NEQNS, COLSTR(*), ROWIND(*), NRHS, LDRHS,
                OUTUNT, MSGLVL, IER
CHARACTER*3      ORDMTHD
REAL             VALUES(*), RHS(*)
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSFS - General sparse solver one call interface.

PARAMETERS

MTXTYP - CHARACTER*2
On entry, MTXTYP specifies the coefficient matrix type. Specifically, the valid options are:

- 'sp' or 'SP' - symmetric structure, positive-definite values
- 'ss' or 'SS' - symmetric structure, symmetric values
- 'su' or 'SU' - symmetric structure, unsymmetric values
- 'uu' or 'UU' - unsymmetric structure, unsymmetric values

Unchanged on exit.

PIVOT - CHARACTER*1
On entry, pivot specifies whether or not pivoting is used in the course of the numeric factorization. The valid options are:

'n' or 'N' - no pivoting is used
(Pivoting is not supported for this release).

Unchanged on exit.

NEQNS - INTEGER
On entry, NEQNS specifies the number of equations in the coefficient matrix. NEQNS must be at least one.
Unchanged on exit.

COLSTR(*) - INTEGER array
On entry, COLSTR(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure.
Unchanged on exit.

ROWIND(*) - INTEGER array
On entry, ROWIND(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

VALUES(*) - REAL array
On entry, VALUES(*) is an array of size COLSTR(NEQNS+1)-1, containing the non-zero numeric values of the sparse matrix to be factored.
Unchanged on exit.

NRHS - INTEGER
On entry, NRHS specifies the number of right hand sides to solve for. Unchanged on exit.

RHS(*) - REAL array
On entry, RHS(LDRHS,NRHS) contains the NRHS right hand sides. On exit, it contains the solutions.

LDRHS - INTEGER
On entry, LDRHS specifies the leading dimension of the RHS array. Unchanged on exit.

ORDMTHD - CHARACTER*3
On entry, ORDMTHD specifies the fill-reducing ordering to be used by the sparse solver. Specifically, the valid options are:

'nat' or 'NAT' - natural ordering (no ordering)
'mmd' or 'MMD' - multiple minimum degree
'gnd' or 'GND' - general nested dissection
'uso' or 'USO' - user specified ordering (see SGSSUO)

Unchanged on exit.

OUTUNT - INTEGER
Output unit. Unchanged on exit.

MSGLVL - INTEGER
Message level.

0 - no output from solver.
(No messages supported for this release.)

Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array of containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine.
Modified on exit.

IER

- INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 101 : Failure to dynamically allocate memory.
- 102 : Invalid matrix type.
- 103 : Invalid pivot option.
- 104 : Number of nonzeros is less than NEQNS.
- 105 : NEQNS < 1
- 106 : Invalid matrix structure.
- 201 : Failure to dynamically allocate memory.
- 301 : Failure to dynamically allocate memory.
- 401 : Failure to dynamically allocate memory.
- 402 : NRHS < 1
- 403 : NEQNS > LDRHS
- 666 : Internal error.

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NAME

sgssin - Initialize the general sparse solver.

SYNOPSIS

```
SUBROUTINE SGSSIN ( MTXTYP, PIVOT, NEQNS, COLSTR, ROWIND, OUTUNT,  
                  MSGGLVL, HANDLE, IER )
```

```
CHARACTER*2      MTXTYP  
CHARACTER*1      PIVOT  
INTEGER          NEQNS, COLSTR(*), ROWIND(*), OUTUNT, MSGGLVL, IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSIN - Initialize the sparse solver and input the matrix structure.

PARAMETERS

MTXTYP - CHARACTER*2
On entry, MTXTYP specifies the coefficient matrix type. Specifically, the valid options are:

- 'sp' or 'SP' - symmetric structure, positive-definite values
- 'ss' or 'SS' - symmetric structure, symmetric values
- 'su' or 'SU' - symmetric structure, unsymmetric values
- 'uu' or 'UU' - unsymmetric structure, unsymmetric values

Unchanged on exit.

PIVOT - CHARACTER*1
On entry, PIVOT specifies whether or not pivoting is used in the course of the numeric factorization. The valid options are:

- 'n' or 'N' - no pivoting is used
(Pivoting is not supported for this release).

Unchanged on exit.

NEQNS - INTEGER
On entry, NEQNS specifies the number of equations in the coefficient matrix. NEQNS must be at least one. Unchanged on exit.

COLSTR(*) - INTEGER array
On entry, COLSTR(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure. Unchanged on exit.

ROWIND(*) - INTEGER array
On entry, ROWIND(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, HANDLE(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

OUTUNT - INTEGER
Output unit. Unchanged on exit.

MSGLVL - INTEGER
Message level.

0 - no output from solver.
(No messages supported for this release.)

Unchanged on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 101 : Failure to dynamically allocate memory.
- 102 : Invalid matrix type.
- 103 : Invalid pivot option.
- 104 : Number of nonzeros less than NEQNS.
- 105 : NEQNS < 1
- 106 : Invalid matrix structure.

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NAME

sgssor - General sparse solver ordering and symbolic factorization.

SYNOPSIS

```
SUBROUTINE SGSSOR ( ORDMTHD, HANDLE, IER )
```

```
CHARACTER*3      ORDMTHD
INTEGER          IER
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSOR - Orders and symbolically factors a sparse matrix.

PARAMETERS

ORDMTHD - CHARACTER*3

On entry, ORDMTHD specifies the fill-reducing ordering to be used by the sparse solver. Specifically, the valid options are:

'nat' or 'NAT' - natural ordering (no ordering)
'mmd' or 'MMD' - multiple minimum degree
'gnd' or 'GND' - general nested dissection
'uso' or 'USO' - user specified ordering (see SGSSUO)

Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero

integer. Error numbers set by this subroutine:

- 200 : Invalid calling sequence - need to call SGSSIN first.
- 201 : Failure to dynamically allocate memory.
- 666 : Internal error.

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NAME

sgssps - Print general sparse solver statics.

SYNOPSIS

```
SUBROUTINE SGSSPS ( HANDLE, IER )
```

```
INTEGER          IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSPS - Print solver statistics.

PARAMETERS

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-800 : Invalid calling sequence - need to call SGSSSL first.
-899 : Printed solver statistics not supported this release.

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NAME

sgssrp - Return permutation used by the general sparse solver.

SYNOPSIS

```
SUBROUTINE SGSSRP ( PERM, HANDLE, IER )
```

```
INTEGER          PERM(*), IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSRP - Returns the permutation used by the solver for the fill-reducing ordering.

PARAMETERS

PERM(NEQNS) - INTEGER array

Undefined on entry. PERM(NEQNS) is the permutation array used by the sparse solver for the fill-reducing ordering. Modified on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-600 : Invalid calling sequence - need to call SGSSOR first.

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NAME

sgsssl - Solve routine for the general sparse solver.

SYNOPSIS

```
SUBROUTINE SGSSSL ( NRHS, RHS, LDRHS, HANDLE, IER )
```

```
INTEGER          NRHS, LDRHS, IER
```

```
REAL             RHS(LDRHS,NRHS)
```

```
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSSL - Triangular solve of a factored sparse matrix.

PARAMETERS

NRHS - INTEGER

On entry, NRHS specifies the number of right hand sides to solve for. Unchanged on exit.

RHS(LDRHS,*) - REAL array

On entry, RHS(LDRHS,NRHS) contains the NRHS right hand sides. On exit, it contains the solutions.

LDRHS - INTEGER

On entry, LDRHS specifies the leading dimension of the RHS array. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, **HANDLE(*)** is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-400 : Invalid calling sequence - need to call SGSSFA first.
-401 : Failure to dynamically allocate memory.
-402 : NRHS < 1
-403 : NEQNS > LDRHS

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NAME

sgssuo - User supplied permutation for ordering used in the general sparse solver.

SYNOPSIS

```
SUBROUTINE SGSSUO ( PERM, HANDLE, IER )
```

```
INTEGER          PERM(*), IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

SGSSUO - User supplied permutation for ordering. Must be called after *SGSSIN*() (sparse solver initialization) and before *SGSSOR*() (sparse solver ordering).

PARAMETERS

PERM(NEQNS) - INTEGER array
On entry, PERM(NEQNS) is a permutation array supplied by the user for the fill-reducing ordering. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-500 : Invalid calling sequence - need to call SGSSIN first.

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NAME

sgtcon - estimate the reciprocal of the condition number of a real tridiagonal matrix A using the LU factorization as computed by SGTTRF

SYNOPSIS

```
SUBROUTINE SGTCON(NORM, N, LOW, DIAG, UP1, UP2, IPIVOT, ANORM, RCOND,  
                WORK, IWORK2, INFO)
```

```
CHARACTER * 1 NORM  
INTEGER N, INFO  
INTEGER IPIVOT(*), IWORK2(*)  
REAL ANORM, RCOND  
REAL LOW(*), DIAG(*), UP1(*), UP2(*), WORK(*)
```

```
SUBROUTINE SGTCON_64(NORM, N, LOW, DIAG, UP1, UP2, IPIVOT, ANORM,  
                   RCOND, WORK, IWORK2, INFO)
```

```
CHARACTER * 1 NORM  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*), IWORK2(*)  
REAL ANORM, RCOND  
REAL LOW(*), DIAG(*), UP1(*), UP2(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GTCON(NORM, [N], LOW, DIAG, UP1, UP2, IPIVOT, ANORM,  
                RCOND, [WORK], [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, IWORK2  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: LOW, DIAG, UP1, UP2, WORK
```

```
SUBROUTINE GTCON_64(NORM, [N], LOW, DIAG, UP1, UP2, IPIVOT, ANORM,  
                   RCOND, [WORK], [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT, IWORK2
```

```
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: LOW, DIAG, UP1, UP2, WORK
```

C INTERFACE

```
#include <sunperf.h>
void sgtcon(char norm, int n, float *low, float *diag, float
            *up1, float *up2, int *ipivot, float anorm, float
            *rcond, int *info);

void sgtcon_64(char norm, long n, float *low, float *diag,
              float *up1, float *up2, long *ipivot, float anorm,
              float *rcond, long *info);
```

PURPOSE

sgtcon estimates the reciprocal of the condition number of a real tridiagonal matrix A using the LU factorization as computed by SGTTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

LOW (input)

The (n-1) multipliers that define the matrix L from the LU factorization of A as computed by SGTTRF.

DIAG (input)

The n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UP1 (input)

The (n-1) elements of the first superdiagonal of U.

UP2 (input)

The (n-2) elements of the second superdiagonal of U.

IPIVOT (input)

The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(ANORM * AINVNM)$, where AINVNM is an estimate of the 1-norm of $inv(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

IWORK2 (workspace)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sgthr - Gathers specified elements from y into x.

SYNOPSIS

```
SUBROUTINE SGTHR(NZ, Y, X, INDX)

REAL Y(*), X(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE SGTHR_64(NZ, Y, X, INDX)

REAL Y(*), X(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE GTHR([NZ], Y, X, INDX)

REAL, DIMENSION(:) :: Y, X
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE GTHR_64([NZ], Y, X, INDX)

REAL, DIMENSION(:) :: Y, X
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

SGTHR - Gathers the specified elements from a vector y in full storage form into a vector x in compressed form. Only the elements of y whose indices are listed in indx are referenced.

```
do i = 1, n
  x(i) = y(indx(i))
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

Y (input)

Vector in full storage form. Unchanged on exit.

X (output)

Vector in compressed form. Contains elements of y
whose indices are listed in indx on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

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NAME

sgthrz - Gather and zero.

SYNOPSIS

```
SUBROUTINE SGTHRZ(NZ, Y, X, INDX)

REAL Y(*), X(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE SGTHRZ_64(NZ, Y, X, INDX)

REAL Y(*), X(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE GTHRZ([NZ], Y, X, INDX)

REAL, DIMENSION(:) :: Y, X
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE GTHRZ_64([NZ], Y, X, INDX)

REAL, DIMENSION(:) :: Y, X
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

SGTHRZ - Gathers the specified elements from a vector y in full storage form into a vector x in compressed form. The gathered elements of y are set to zero. Only the elements of y whose indices are listed in indx are referenced.

```
do i = 1, n
  x(i) = y(indx(i))
  y(indx(i)) = 0
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

Y (input/output)

Vector in full storage form. Gathered elements are
set to zero.

X (output)

Vector in compressed form. Contains elements of y
whose indices are listed in indx on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

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NAME

sgtrfs - improve the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE SGTRFS(TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF, UPF1,
  UPF2, IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
REAL LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*), UPF1(*),
UPF2(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE SGTRFS_64(TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2,
  INFO)
```

```
CHARACTER * 1 TRANSA
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
REAL LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*), UPF1(*),
UPF2(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GTRFS([TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL, DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, FERR, BERR, WORK
REAL, DIMENSION(:, :) :: B, X
```

```
SUBROUTINE GTRFS_64([TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
  DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
```

```
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2  
REAL, DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,  
UPF2, FERR, BERR, WORK  
REAL, DIMENSION(:, :) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgtrfs(char transa, int n, int nrhs, float *low, float  
*diag, float *up, float *lowf, float *diagf, float  
*upf1, float *upf2, int *ipivot, float *b, int  
ldb, float *x, int ldx, float *ferr, float *berr,  
int *info);
```

```
void sgtrfs_64(char transa, long n, long nrhs, float *low,  
float *diag, float *up, float *lowf, float *diagf,  
float *upf1, float *upf2, long *ipivot, float *b,  
long ldb, float *x, long ldx, float *ferr, float  
*berr, long *info);
```

PURPOSE

sgtrfs improves the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input)

The (n-1) subdiagonal elements of A.

DIAG (input)

The diagonal elements of A.

UP (input)

The (n-1) superdiagonal elements of A.

LOWF (input)
 The (n-1) multipliers that define the matrix L from the LU factorization of A as computed by SGTTRF.

DIAGF (input)
 The n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UPF1 (input)
 The (n-1) elements of the first superdiagonal of U.

UPF2 (input)
 The (n-2) elements of the second superdiagonal of U.

IPIVOT (input)
 The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

B (input) The right hand side matrix B.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (input/output)
 On entry, the solution matrix X, as computed by SGTTRS. On exit, the improved solution matrix X.

LDX (input)
 The leading dimension of the array X. $LDX \geq \max(1, N)$.

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(3*N)

WORK2 (workspace)
 dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sgtsv - solve the equation $A \cdot X = B$,

SYNOPSIS

```
SUBROUTINE SGTSV(N, NRHS, LOW, DIAG, UP, B, LDB, INFO)
```

```
INTEGER N, NRHS, LDB, INFO  
REAL LOW(*), DIAG(*), UP(*), B(LDB,*)
```

```
SUBROUTINE SGTSV_64(N, NRHS, LOW, DIAG, UP, B, LDB, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO  
REAL LOW(*), DIAG(*), UP(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GTSV([N], [NRHS], LOW, DIAG, UP, B, [LDB], [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: LOW, DIAG, UP  
REAL, DIMENSION(:,) :: B
```

```
SUBROUTINE GTSV_64([N], [NRHS], LOW, DIAG, UP, B, [LDB], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: LOW, DIAG, UP  
REAL, DIMENSION(:,) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgtsv(int n, int nrhs, float *low, float *diag, float  
          *up, float *b, int ldb, int *info);
```

```
void sgtsv_64(long n, long nrhs, float *low, float *diag,  
             float *up, float *b, long ldb, long *info);
```

PURPOSE

sgtsv solves the equation

where A is an n by n tridiagonal matrix, by Gaussian elimination with partial pivoting.

Note that the equation $A^T X = B$ may be solved by interchanging the order of the arguments DU and DL.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input/output)
On entry, LOW must contain the (n-1) sub-diagonal elements of A.

On exit, LOW is overwritten by the (n-2) elements of the second super-diagonal of the upper triangular matrix U from the LU factorization of A, in $LOW(1), \dots, LOW(n-2)$.

DIAG (input/output)
On entry, DIAG must contain the diagonal elements of A.

On exit, DIAG is overwritten by the n diagonal elements of U.

UP (input/output)
On entry, UP must contain the (n-1) super-diagonal elements of A.

On exit, UP is overwritten by the (n-1) elements of the first super-diagonal of U.

B (input/output)
On entry, the N by NRHS matrix of right hand side matrix B. On exit, if $INFO = 0$, the N by NRHS solution matrix X.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)
= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, $U(i,i)$ is exactly zero, and the solution has not been computed. The factorization has not been completed unless $i = N$.

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NAME

sgtsvx - use the LU factorization to compute the solution to a real system of linear equations $A * X = B$ or $A^{**T} * X = B$,

SYNOPSIS

```
SUBROUTINE SGTSVX(FACT, TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
  WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
REAL RCOND
REAL LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*), UPF1(*),
UPF2(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE SGTSVX_64(FACT, TRANSA, N, NRHS, LOW, DIAG, UP, LOWF,
  DIAGF, UPF1, UPF2, IPIVOT, B, LDB, X, LDX, RCOND, FERR, BERR,
  WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
REAL RCOND
REAL LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*), UPF1(*),
UPF2(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GTSVX(FACT, [TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
  DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR,
  [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, FERR, BERR, WORK
REAL, DIMENSION(:,) :: B, X
```

```

SUBROUTINE GTSVX_64(FACT, [TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
    DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR,
    [WORK], [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: FACT, TRANSA
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF, UPF1,
UPF2, FERR, BERR, WORK
REAL, DIMENSION(:, :) :: B, X

```

C INTERFACE

```

#include <sunperf.h>

```

```

void sgtsvx(char fact, char transa, int n, int nrhs, float
    *low, float *diag, float *up, float *lowf, float
    *diagf, float *upf1, float *upf2, int *ipivot,
    float *b, int ldb, float *x, int ldx, float
    *rcond, float *ferr, float *berr, int *info);

```

```

void sgtsvx_64(char fact, char transa, long n, long nrhs,
    float *low, float *diag, float *up, float *lowf,
    float *diagf, float *upf1, float *upf2, long
    *ipivot, float *b, long ldb, float *x, long ldx,
    float *rcond, float *ferr, float *berr, long
    *info);

```

PURPOSE

sgtsvx uses the LU factorization to compute the solution to a real system of linear equations $A * X = B$ or $A^{**T} * X = B$, where A is a tridiagonal matrix of order N and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'N', the LU decomposition is used to factor the matrix A as $A = L * U$, where L is a product of permutation and unit lower bidiagonal matrices and U is upper triangular with nonzeros in only the main diagonal and first two superdiagonals.
2. If some $U(i,i)=0$, so that U is exactly singular, then the routine returns with INFO = i. Otherwise, the factored form of A is used to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described

below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': LOWF, DIAGF, UPF1, UPF2, and IPIVOT contain the factored form of A; LOW, DIAG, UP, LOWF, DIAGF, UPF1, UPF2 and IPIVOT will not be modified. = 'N': The matrix will be copied to LOWF, DIAGF, and UPF1 and factored.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{*H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input)

The (n-1) subdiagonal elements of A.

DIAG (input)

The n diagonal elements of A.

UP (input/output)

The (n-1) superdiagonal elements of A.

LOWF (input or output)

If FACT = 'F', then LOWF is an input argument and on entry contains the (n-1) multipliers that define the matrix L from the LU factorization of A as computed by SGTTRF.

If FACT = 'N', then LOWF is an output argument and on exit contains the (n-1) multipliers that define the matrix L from the LU factorization of A.

DIAGF (input or output)

If FACT = 'F', then DIAGF is an input argument and on entry contains the n diagonal elements of the upper triangular matrix U from the LU factoriza-

tion of A.

If FACT = 'N', then DIAGF is an output argument and on exit contains the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UPF1 (input or output)

If FACT = 'F', then UPF1 is an input argument and on entry contains the (n-1) elements of the first superdiagonal of U.

If FACT = 'N', then UPF1 is an output argument and on exit contains the (n-1) elements of the first superdiagonal of U.

UPF2 (input or output)

If FACT = 'F', then UPF2 is an input argument and on entry contains the (n-2) elements of the second superdiagonal of U.

If FACT = 'N', then UPF2 is an output argument and on exit contains the (n-2) elements of the second superdiagonal of U.

IPIVOT (input/output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the LU factorization of A as computed by SGTRF.

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the LU factorization of A; row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)

The estimated forward error bound for each solu-

tion vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for $RCOND$, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension($3*N$)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, and i is
<= N : $U(i,i)$ is exactly zero. The factorization has not been completed unless $i = N$, but the factor U is exactly singular, so the solution and error bounds could not be computed. $RCOND = 0$ is returned. = $N+1$: U is nonsingular, but $RCOND$ is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of $RCOND$ would suggest.

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NAME

sgttrf - compute an LU factorization of a real tridiagonal matrix A using elimination with partial pivoting and row interchanges

SYNOPSIS

```
SUBROUTINE SGTTRF(N, LOW, DIAG, UP1, UP2, IPIVOT, INFO)
```

```
INTEGER N, INFO  
INTEGER IPIVOT(*)  
REAL LOW(*), DIAG(*), UP1(*), UP2(*)
```

```
SUBROUTINE SGTTRF_64(N, LOW, DIAG, UP1, UP2, IPIVOT, INFO)
```

```
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
REAL LOW(*), DIAG(*), UP1(*), UP2(*)
```

F95 INTERFACE

```
SUBROUTINE GTTRF([N], LOW, DIAG, UP1, UP2, IPIVOT, [INFO])
```

```
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: LOW, DIAG, UP1, UP2
```

```
SUBROUTINE GTTRF_64([N], LOW, DIAG, UP1, UP2, IPIVOT, [INFO])
```

```
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: LOW, DIAG, UP1, UP2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sgttrf(int n, float *low, float *diag, float *up1,  
           float *up2, int *ipivot, int *info);
```

```
void sgttrf_64(long n, float *low, float *diag, float *up1,  
              float *up2, long *ipivot, long *info);
```

PURPOSE

sgttrf computes an LU factorization of a real tridiagonal matrix A using elimination with partial pivoting and row interchanges.

The factorization has the form

$$A = L * U$$

where L is a product of permutation and unit lower bidiagonal matrices and U is upper triangular with nonzeros in only the main diagonal and first two superdiagonals.

ARGUMENTS

N (input) The order of the matrix A.

LOW (input/output)

On entry, LOW must contain the (n-1) sub-diagonal elements of A.

On exit, LOW is overwritten by the (n-1) multipliers that define the matrix L from the LU factorization of A.

DIAG (input/output)

On entry, DIAG must contain the diagonal elements of A.

On exit, DIAG is overwritten by the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UP1 (input/output)

On entry, UP1 must contain the (n-1) super-diagonal elements of A.

On exit, UP1 is overwritten by the (n-1) elements of the first super-diagonal of U.

UP2 (output)

On exit, UP2 is overwritten by the (n-2) elements of the second super-diagonal of U.

IPIVOT (output)

The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, U(k,k) is exactly zero. The factorization has been completed, but the factor U

is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

sgttrs - solve one of the systems of equations $A^*X = B$ or $A'^*X = B$,

SYNOPSIS

```
SUBROUTINE SGTTRS(TRANSA, N, NRHS, LOW, DIAG, UP1, UP2, IPIVOT, B,  
LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)  
REAL LOW(*), DIAG(*), UP1(*), UP2(*), B(LDB,*)
```

```
SUBROUTINE SGTTRS_64(TRANSA, N, NRHS, LOW, DIAG, UP1, UP2, IPIVOT, B,  
LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)  
REAL LOW(*), DIAG(*), UP1(*), UP2(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE GTTRS([TRANSA], [N], [NRHS], LOW, DIAG, UP1, UP2, IPIVOT,  
B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: LOW, DIAG, UP1, UP2  
REAL, DIMENSION(:,) :: B
```

```
SUBROUTINE GTTRS_64([TRANSA], [N], [NRHS], LOW, DIAG, UP1, UP2,  
IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: LOW, DIAG, UP1, UP2  
REAL, DIMENSION(:,) :: B
```

C INTERFACE

```
#include <sunperf.h>

void sgttrs(char transa, int n, int nrhs, float *low, float
            *diag, float *up1, float *up2, int *ipivot, float
            *b, int ldb, int *info);
void sgttrs_64(char transa, long n, long nrhs, float *low,
               float *diag, float *up1, float *up2, long *ipivot,
               float *b, long ldb, long *info);
```

PURPOSE

sgttrs solves one of the systems of equations
 $A * X = B$ or $A' * X = B$, with a tridiagonal matrix A using
the LU factorization computed by SGTTRF.

ARGUMENTS

TRANSA (input)
Specifies the form of the system of equations. =
'N': $A * X = B$ (No transpose)
= 'T': $A' * X = B$ (Transpose)
= 'C': $A' * X = B$ (Conjugate transpose = Trans-
pose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A.

NRHS (input)
The number of right hand sides, i.e., the number
of columns of the matrix B. NRHS \geq 0.

LOW (input)
The (n-1) multipliers that define the matrix L
from the LU factorization of A.

DIAG (input)
The n diagonal elements of the upper triangular
matrix U from the LU factorization of A.

UP1 (input)
The (n-1) elements of the first super-diagonal of
U.

UP2 (input)
The (n-2) elements of the second super-diagonal of
U.

IPIVOT (input)
The pivot indices; for $1 \leq i \leq n$, row i of the
matrix was interchanged with row IPIVOT(i).
IPIVOT(i) will always be either i or i+1;
IPIVOT(i) = i indicates a row interchange was not
required.

B (input/output)

On entry, the matrix of right hand side vectors B.
On exit, B is overwritten by the solution vectors X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

shgeqz - implement a single-/double-shift version of the QZ method for finding the generalized eigenvalues $w(j) = (\text{ALPHAR}(j) + i \cdot \text{ALPHAI}(j)) / \text{BETAR}(j)$ of the equation $\det(A - w(i) B) = 0$. In addition, the pair A,B may be reduced to generalized Schur form

SYNOPSIS

```
SUBROUTINE SHGEQZ(JOB, COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB,
                 ALPHAR, ALPHAI, BETA, Q, LDQ, Z, LDZ, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ, COMPZ
INTEGER N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
Q(LDQ,*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SHGEQZ_64(JOB, COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB,
                   ALPHAR, ALPHAI, BETA, Q, LDQ, Z, LDZ, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ, COMPZ
INTEGER*8 N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
Q(LDQ,*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE HGEQZ(JOB, COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB],
                ALPHAR, ALPHAI, BETA, Q, [LDQ], Z, [LDZ], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ, COMPZ
INTEGER :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL, DIMENSION(:, :) :: A, B, Q, Z
```

```
SUBROUTINE HGEQZ_64(JOB, COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B,
                   [LDB], ALPHAR, ALPHAI, BETA, Q, [LDQ], Z, [LDZ], [WORK], [LWORK],
                   [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ, COMPZ
```

```
INTEGER(8) :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, WORK
REAL, DIMENSION(:,:) :: A, B, Q, Z
```

C INTERFACE

```
#include <sunperf.h>

void shgeqz(char job, char compq, char compz, int n, int
            ilo, int ihi, float *a, int lda, float *b, int
            ldb, float *alphar, float *alphai, float *beta,
            float *q, int ldq, float *z, int ldz, int *info);

void shgeqz_64(char job, char compq, char compz, long n,
              long ilo, long ihi, float *a, long lda, float *b,
              long ldb, float *alphar, float *alphai, float
              *beta, float *q, long ldq, float *z, long ldz,
              long *info);
```

PURPOSE

shgeqz implements a single-/double-shift version of the QZ method for finding the generalized eigenvalues B is upper triangular, and A is block upper triangular, where the diagonal blocks are either 1-by-1 or 2-by-2, the 2-by-2 blocks having complex generalized eigenvalues (see the description of the argument JOB.)

If JOB='S', then the pair (A,B) is simultaneously reduced to Schur form by applying one orthogonal transformation (usually called Q) on the left and another (usually called Z) on the right. The 2-by-2 upper-triangular diagonal blocks of B corresponding to 2-by-2 blocks of A will be reduced to positive diagonal matrices. (I.e., if A(j+1,j) is non-zero, then B(j+1,j)=B(j,j+1)=0 and B(j,j) and B(j+1,j+1) will be positive.)

If JOB='E', then at each iteration, the same transformations are computed, but they are only applied to those parts of A and B which are needed to compute ALPHAR, ALPHAI, and BETA.

If JOB='S' and COMPQ and COMPZ are 'V' or 'I', then the orthogonal transformations used to reduce (A,B) are accumulated into the arrays Q and Z s.t.:

(in) A(in) Z(in)* = Q(out) A(out) Z(out)*

Ref: C.B. Moler & G.W. Stewart, "An Algorithm for Generalized Matrix Eigenvalue Problems", SIAM J. Numer. Anal., 10(1973), p. 241--256.

ARGUMENTS

JOB (input)
= 'E': compute only ALPHAR, ALPHAI, and BETA. A and B will not necessarily be put into generalized Schur form. = 'S': put A and B into generalized Schur form, as well as computing ALPHAR, ALPHAI,

and BETA.

COMPQ (input)

= 'N': do not modify Q.
= 'V': multiply the array Q on the right by the transpose of the orthogonal transformation that is applied to the left side of A and B to reduce them to Schur form. = 'I': like COMPQ='V', except that Q will be initialized to the identity first.

COMPZ (input)

= 'N': do not modify Z.
= 'V': multiply the array Z on the right by the orthogonal transformation that is applied to the right side of A and B to reduce them to Schur form. = 'I': like COMPZ='V', except that Z will be initialized to the identity first.

N (input) The order of the matrices A, B, Q, and Z. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)

See the description of ILO.

A (input) On entry, the N-by-N upper Hessenberg matrix A. Elements below the subdiagonal must be zero. If JOB='S', then on exit A and B will have been simultaneously reduced to generalized Schur form. If JOB='E', then on exit A will have been destroyed. The diagonal blocks will be correct, but the off-diagonal portion will be meaningless.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input) On entry, the N-by-N upper triangular matrix B. Elements below the diagonal must be zero. 2-by-2 blocks in B corresponding to 2-by-2 blocks in A will be reduced to positive diagonal form. (I.e., if $A(j+1, j)$ is non-zero, then $B(j+1, j)=B(j, j+1)=0$ and $B(j, j)$ and $B(j+1, j+1)$ will be positive.) If JOB='S', then on exit A and B will have been simultaneously reduced to Schur form. If JOB='E', then on exit B will have been destroyed. Elements corresponding to diagonal blocks of A will be correct, but the off-diagonal portion will be meaningless.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

ALPHAR (output)

ALPHAR(1:N) will be set to real parts of the diagonal elements of A that would result from reducing A and B to Schur form and then further reducing

them both to triangular form using unitary transformations s.t. the diagonal of B was non-negative real. Thus, if A(j,j) is in a 1-by-1 block (i.e., A(j+1,j)=A(j,j+1)=0), then ALPHAR(j)=A(j,j). Note that the (real or complex) values (ALPHAR(j) + i*ALPHAI(j))/BETA(j), j=1,...,N, are the generalized eigenvalues of the matrix pencil A - wB.

ALPHAI (output)

ALPHAI(1:N) will be set to imaginary parts of the diagonal elements of A that would result from reducing A and B to Schur form and then further reducing them both to triangular form using unitary transformations s.t. the diagonal of B was non-negative real. Thus, if A(j,j) is in a 1-by-1 block (i.e., A(j+1,j)=A(j,j+1)=0), then ALPHAR(j)=0. Note that the (real or complex) values (ALPHAR(j) + i*ALPHAI(j))/BETA(j), j=1,...,N, are the generalized eigenvalues of the matrix pencil A - wB.

BETA (output)

BETA(1:N) will be set to the (real) diagonal elements of B that would result from reducing A and B to Schur form and then further reducing them both to triangular form using unitary transformations s.t. the diagonal of B was non-negative real. Thus, if A(j,j) is in a 1-by-1 block (i.e., A(j+1,j)=A(j,j+1)=0), then BETA(j)=B(j,j). Note that the (real or complex) values (ALPHAR(j) + i*ALPHAI(j))/BETA(j), j=1,...,N, are the generalized eigenvalues of the matrix pencil A - wB. (Note that BETA(1:N) will always be non-negative, and no BETAI is necessary.)

Q (input/output)

If COMPQ='N', then Q will not be referenced. If COMPQ='V' or 'I', then the transpose of the orthogonal transformations which are applied to A and B on the left will be applied to the array Q on the right.

LDQ (input)

The leading dimension of the array Q. LDQ >= 1.
If COMPQ='V' or 'I', then LDQ >= N.

Z (input/output)

If COMPZ='N', then Z will not be referenced. If COMPZ='V' or 'I', then the orthogonal transformations which are applied to A and B on the right will be applied to the array Z on the right.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1.
If COMPZ='V' or 'I', then LDZ >= N.

WORK (workspace)

On exit, if INFO >= 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,N).

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
= 1,...,N: the QZ iteration did not converge. (A,B) is not in Schur form, but ALPHAR(i), ALPHAI(i), and BETA(i), $i=INFO+1, \dots, N$ should be correct. = N+1,...,2*N: the shift calculation failed. (A,B) is not in Schur form, but ALPHAR(i), ALPHAI(i), and BETA(i), $i=INFO-N+1, \dots, N$ should be correct. > 2*N: various "impossible" errors.

FURTHER DETAILS

Iteration counters:

JITER -- counts iterations.
IITER -- counts iterations run since ILAST was last changed. This is therefore reset only when a 1-by-1 or 2-by-2 block deflates off the bottom.

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NAME

shsein - use inverse iteration to find specified right and/or left eigenvectors of a real upper Hessenberg matrix H

SYNOPSIS

```
SUBROUTINE SHSEIN(SIDE, EIGSRC, INITV, SELECT, N, H, LDH, WR, WI, VL,
                 LDVL, VR, LDVR, MM, M, WORK, IFAILL, IFAILR, INFO)
```

```
CHARACTER * 1 SIDE, EIGSRC, INITV
INTEGER N, LDH, LDVL, LDVR, MM, M, INFO
INTEGER IFAILL(*), IFAILR(*)
LOGICAL SELECT(*)
REAL H(LDH,*), WR(*), WI(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

```
SUBROUTINE SHSEIN_64(SIDE, EIGSRC, INITV, SELECT, N, H, LDH, WR, WI,
                    VL, LDVL, VR, LDVR, MM, M, WORK, IFAILL, IFAILR, INFO)
```

```
CHARACTER * 1 SIDE, EIGSRC, INITV
INTEGER*8 N, LDH, LDVL, LDVR, MM, M, INFO
INTEGER*8 IFAILL(*), IFAILR(*)
LOGICAL*8 SELECT(*)
REAL H(LDH,*), WR(*), WI(*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE HSEIN(SIDE, EIGSRC, INITV, SELECT, [N], H, [LDH], WR, WI,
                VL, [LDVL], VR, [LDVR], MM, M, [WORK], IFAILL, IFAILR, [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, EIGSRC, INITV
INTEGER :: N, LDH, LDVL, LDVR, MM, M, INFO
INTEGER, DIMENSION(:) :: IFAILL, IFAILR
LOGICAL, DIMENSION(:) :: SELECT
REAL, DIMENSION(:) :: WR, WI, WORK
REAL, DIMENSION(:, :) :: H, VL, VR
```

```
SUBROUTINE HSEIN_64(SIDE, EIGSRC, INITV, SELECT, [N], H, [LDH], WR,
                   WI, VL, [LDVL], VR, [LDVR], MM, M, [WORK], IFAILL, IFAILR, [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, EIGSRC, INITV
```

```

INTEGER(8) :: N, LDH, LDVL, LDVR, MM, M, INFO
INTEGER(8), DIMENSION(:) :: IFAILL, IFAILR
LOGICAL(8), DIMENSION(:) :: SELECT
REAL, DIMENSION(:) :: WR, WI, WORK
REAL, DIMENSION(:, :) :: H, VL, VR

```

C INTERFACE

```

#include <sunperf.h>
void shsein(char side, char eigsrc, char initv, int *select,
            int n, float *h, int ldh, float *wr, float *wi,
            float *vl, int ldvl, float *vr, int ldvr, int mm,
            int *m, int *ifaill, int *ifailr, int *info);

void shsein_64(char side, char eigsrc, char initv, long
               *select, long n, float *h, long ldh, float *wr,
               float *wi, float *vl, long ldvl, float *vr, long
               ldvr, long mm, long *m, long *ifaill, long
               *ifailr, long *info);

```

PURPOSE

shsein uses inverse iteration to find specified right and/or left eigenvectors of a real upper Hessenberg matrix H.

The right eigenvector x and the left eigenvector y of the matrix H corresponding to an eigenvalue w are defined by:

$$H * x = w * x, \quad y^{*h} * H = w * y^{*h}$$

where y**h denotes the conjugate transpose of the vector y.

ARGUMENTS

SIDE (input)

```

= 'R': compute right eigenvectors only;
= 'L': compute left eigenvectors only;
= 'B': compute both right and left eigenvectors.

```

EIGSRC (input)

```

Specifies the source of eigenvalues supplied in
(WR,WI):
= 'Q': the eigenvalues were found using SHSEQR;
thus, if H has zero subdiagonal elements, and so
is block-triangular, then the j-th eigenvalue can
be assumed to be an eigenvalue of the block con-
taining the j-th row/column. This property allows
SHSEIN to perform inverse iteration on just one
diagonal block. = 'N': no assumptions are made on
the correspondence between eigenvalues and diago-
nal blocks. In this case, SHSEIN must always per-
form inverse iteration using the whole matrix H.

```

INITV (input)

```

= 'N': no initial vectors are supplied;
= 'U': user-supplied initial vectors are stored in
the arrays VL and/or VR.

```

SELECT (input/output)

Specifies the eigenvectors to be computed. To select the real eigenvector corresponding to a real eigenvalue $WR(j)$, $SELECT(j)$ must be set to `.TRUE.`. To select the complex eigenvector corresponding to a complex eigenvalue $(WR(j),WI(j))$, with complex conjugate $(WR(j+1),WI(j+1))$, either $SELECT(j)$ or $SELECT(j+1)$ or both must be set to

N (input) The order of the matrix H. $N \geq 0$.

H (input) The upper Hessenberg matrix H.

LDH (input)

The leading dimension of the array H. $LDH \geq \max(1,N)$.

WR (input/output)

On entry, the real and imaginary parts of the eigenvalues of H; a complex conjugate pair of eigenvalues must be stored in consecutive elements of WR and WI. On exit, WR may have been altered since close eigenvalues are perturbed slightly in searching for independent eigenvectors.

WI (input)

See the description of WR.

VL (input/output)

On entry, if $INITV = 'U'$ and $SIDE = 'L'$ or $'B'$, VL must contain starting vectors for the inverse iteration for the left eigenvectors; the starting vector for each eigenvector must be in the same column(s) in which the eigenvector will be stored. On exit, if $SIDE = 'L'$ or $'B'$, the left eigenvectors specified by SELECT will be stored consecutively in the columns of VL, in the same order as their eigenvalues. A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the real part and the second the imaginary part. If $SIDE = 'R'$, VL is not referenced.

LDVL (input)

The leading dimension of the array VL. $LDVL \geq \max(1,N)$ if $SIDE = 'L'$ or $'B'$; $LDVL \geq 1$ otherwise.

VR (input/output)

On entry, if $INITV = 'U'$ and $SIDE = 'R'$ or $'B'$, VR must contain starting vectors for the inverse iteration for the right eigenvectors; the starting vector for each eigenvector must be in the same column(s) in which the eigenvector will be stored. On exit, if $SIDE = 'R'$ or $'B'$, the right eigenvectors specified by SELECT will be stored consecutively in the columns of VR, in the same order as their eigenvalues. A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the

real part and the second the imaginary part. If SIDE = 'L', VR is not referenced.

LDVR (input)

The leading dimension of the array VR. LDVR \geq max(1,N) if SIDE = 'R' or 'B'; LDVR \geq 1 otherwise.

MM (input)

The number of columns in the arrays VL and/or VR. MM \geq M.

M (output)

The number of columns in the arrays VL and/or VR required to store the eigenvectors; each selected real eigenvector occupies one column and each selected complex eigenvector occupies two columns.

WORK (workspace)

dimension((N+2)*N)

IFAILL (output)

If SIDE = 'L' or 'B', IFAILL(i) = j > 0 if the left eigenvector in the i-th column of VL (corresponding to the eigenvalue w(j)) failed to converge; IFAILL(i) = 0 if the eigenvector converged satisfactorily. If the i-th and (i+1)th columns of VL hold a complex eigenvector, then IFAILL(i) and IFAILL(i+1) are set to the same value. If SIDE = 'R', IFAILL is not referenced.

IFAILR (output)

If SIDE = 'R' or 'B', IFAILR(i) = j > 0 if the right eigenvector in the i-th column of VR (corresponding to the eigenvalue w(j)) failed to converge; IFAILR(i) = 0 if the eigenvector converged satisfactorily. If the i-th and (i+1)th columns of VR hold a complex eigenvector, then IFAILR(i) and IFAILR(i+1) are set to the same value. If SIDE = 'L', IFAILR is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, i is the number of eigenvectors which failed to converge; see IFAILL and IFAILR for further details.

FURTHER DETAILS

Each eigenvector is normalized so that the element of largest magnitude has magnitude 1; here the magnitude of a complex number (x,y) is taken to be $|x|+|y|$.

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NAME

shseqr - compute the eigenvalues of a real upper Hessenberg matrix H and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z^{**T}$, where T is an upper quasi-triangular matrix (the Schur form), and Z is the orthogonal matrix of Schur vectors

SYNOPSIS

```
SUBROUTINE SHSEQR(JOB, COMPZ, N, ILO, IHI, H, LDH, WR, WI, Z, LDZ,  
                WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPZ  
INTEGER N, ILO, IHI, LDH, LDZ, LWORK, INFO  
REAL H(LDH,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SHSEQR_64(JOB, COMPZ, N, ILO, IHI, H, LDH, WR, WI, Z, LDZ,  
                   WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPZ  
INTEGER*8 N, ILO, IHI, LDH, LDZ, LWORK, INFO  
REAL H(LDH,*), WR(*), WI(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE HSEQR(JOB, COMPZ, N, ILO, IHI, H, [LDH], WR, WI, Z, [LDZ],  
                [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPZ  
INTEGER :: N, ILO, IHI, LDH, LDZ, LWORK, INFO  
REAL, DIMENSION(:) :: WR, WI, WORK  
REAL, DIMENSION(:, :) :: H, Z
```

```
SUBROUTINE HSEQR_64(JOB, COMPZ, N, ILO, IHI, H, [LDH], WR, WI, Z,  
                   [LDZ], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPZ  
INTEGER(8) :: N, ILO, IHI, LDH, LDZ, LWORK, INFO  
REAL, DIMENSION(:) :: WR, WI, WORK  
REAL, DIMENSION(:, :) :: H, Z
```

C INTERFACE

```
#include <sunperf.h>

void shseqr(char job, char compz, int n, int ilo, int ihi,
            float *h, int ldh, float *wr, float *wi, float *z,
            int ldz, int *info);
void shseqr_64(char job, char compz, long n, long ilo, long
               ihi, float *h, long ldh, float *wr, float *wi,
               float *z, long ldz, long *info);
```

PURPOSE

shseqr computes the eigenvalues of a real upper Hessenberg matrix H and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z^{*T}$, where T is an upper quasi-triangular matrix (the Schur form), and Z is the orthogonal matrix of Schur vectors.

Optionally Z may be postmultiplied into an input orthogonal matrix Q , so that this routine can give the Schur factorization of a matrix A which has been reduced to the Hessenberg form H by the orthogonal matrix Q : $A = Q^*H^*Q^{*T} = (QZ)^*T^*(QZ)^{*T}$.

ARGUMENTS

JOB (input)

= 'E': compute eigenvalues only;
 = 'S': compute eigenvalues and the Schur form T .

COMPZ (input)

= 'N': no Schur vectors are computed;
 = 'I': Z is initialized to the unit matrix and the matrix Z of Schur vectors of H is returned; =
 'V': Z must contain an orthogonal matrix Q on entry, and the product Q^*Z is returned.

N (input) The order of the matrix H . $N \geq 0$.

ILO (input)

It is assumed that H is already upper triangular in rows and columns $1:ILO-1$ and $IHI+1:N$. ILO and IHI are normally set by a previous call to SGEBAL, and then passed to SGEHRD when the matrix output by SGEBAL is reduced to Hessenberg form. Otherwise ILO and IHI should be set to 1 and N respectively. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

IHI (input)

See the description of ILO .

H (input/output)

On entry, the upper Hessenberg matrix H . On exit, if $JOB = 'S'$, H contains the upper quasi-triangular matrix T from the Schur decomposition (the Schur form); 2-by-2 diagonal blocks (corresponding to complex conjugate pairs of

eigenvalues) are returned in standard form, with $H(i,i) = H(i+1,i+1)$ and $H(i+1,i)*H(i,i+1) < 0$. If `JOB = 'E'`, the contents of `H` are unspecified on exit.

`LDH` (input)

The leading dimension of the array `H`. `LDH` \geq $\max(1,N)$.

`WR` (output)

The real and imaginary parts, respectively, of the computed eigenvalues. If two eigenvalues are computed as a complex conjugate pair, they are stored in consecutive elements of `WR` and `WI`, say the i -th and $(i+1)$ th, with $WI(i) > 0$ and $WI(i+1) < 0$. If `JOB = 'S'`, the eigenvalues are stored in the same order as on the diagonal of the Schur form returned in `H`, with $WR(i) = H(i,i)$ and, if $H(i:i+1,i:i+1)$ is a 2-by-2 diagonal block, $WI(i) = \sqrt{H(i+1,i)*H(i,i+1)}$ and $WI(i+1) = -WI(i)$.

`WI` (output)

See the description of `WR`.

`Z` (input) If `COMPZ = 'N'`: `Z` is not referenced.

If `COMPZ = 'I'`: on entry, `Z` need not be set, and on exit, `Z` contains the orthogonal matrix `Z` of the Schur vectors of `H`. If `COMPZ = 'V'`: on entry `Z` must contain an N -by- N matrix `Q`, which is assumed to be equal to the unit matrix except for the submatrix $Z(ILO:IHI,ILO:IHI)$; on exit `Z` contains $Q*Z$. Normally `Q` is the orthogonal matrix generated by `SORGHR` after the call to `SGEHRD` which formed the Hessenberg matrix `H`.

`LDZ` (input)

The leading dimension of the array `Z`. `LDZ` \geq $\max(1,N)$ if `COMPZ = 'I'` or `'V'`; `LDZ` \geq 1 otherwise.

`WORK` (workspace)

On exit, if `INFO = 0`, `WORK(1)` returns the optimal `LWORK`.

`LWORK` (input)

The dimension of the array `WORK`. `LWORK` \geq $\max(1,N)$.

If `LWORK = -1`, then a workspace query is assumed; the routine only calculates the optimal size of the `WORK` array, returns this value as the first entry of the `WORK` array, and no error message related to `LWORK` is issued by `XERBLA`.

`INFO` (output)

= 0: successful exit
< 0: if `INFO = -i`, the i -th argument had an illegal value
> 0: if `INFO = i`, `SHSEQR` failed to compute all of the eigenvalues in a total of $30*(IHI-ILO+1)$ iterations; elements $1:i-1$ and $i+1:n$ of `WR` and `WI` contain those eigenvalues which have been suc-

cessfully computed.

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NAME

sinqb - synthesize a Fourier sequence from its representation in terms of a sine series with odd wave numbers. The SINQ operations are unnormalized inverses of themselves, so a call to SINQF followed by a call to SINQB will multiply the input sequence by $4 * N$.

SYNOPSIS

```
SUBROUTINE SINQB(N, X, WSAVE)
```

```
INTEGER N  
REAL X(*), WSAVE(*)
```

```
SUBROUTINE SINQB_64(N, X, WSAVE)
```

```
INTEGER*8 N  
REAL X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINQB(N, X, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE SINQB_64(N, X, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sinqb(int n, float *x, float *wsave);
```

```
void sinqb_64(long n, float *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the quarter-wave sine synthesis of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$ for scalar subroutines, initialized by SINQI.

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NAME

sinqf - compute the Fourier coefficients in a sine series representation with only odd wave numbers. The SINO operations are unnormalized inverses of themselves, so a call to SINO followed by a call to SINQB will multiply the input sequence by 4 * N.

SYNOPSIS

```
SUBROUTINE SINF(N, X, WSAVE)
```

```
INTEGER N  
REAL X(*), WSAVE(*)
```

```
SUBROUTINE SINF_64(N, X, WSAVE)
```

```
INTEGER*8 N  
REAL X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINF(N, X, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE SINF_64(N, X, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sinqf(int n, float *x, float *wsave);
```

```
void sinqf_64(long n, float *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input/output)
On entry, an array of length N containing the sequence to be transformed. On exit, the quarter-wave sine transform of the input.

WSAVE (input)
On entry, an array with dimension of at least $(3 * N + 15)$ for scalar subroutines, initialized by SINQI.

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NAME

`sinqi` - initialize the array `xWSAVE`, which is used in both `SINQF` and `SINQB`.

SYNOPSIS

```
SUBROUTINE SINQI(N, WSAVE)
```

```
INTEGER N  
REAL WSAVE(*)
```

```
SUBROUTINE SINQI_64(N, WSAVE)
```

```
INTEGER*8 N  
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINQI(N, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: WSAVE
```

```
SUBROUTINE SINQI_64(N, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sinqi(int n, float *wsave);
```

```
void sinqi_64(long n, float *wsave);
```

ARGUMENTS

`N` (input) Length of the sequence to be transformed. The method is most efficient when `N` is a product of small primes.

WSAVE (input)

On entry, an array of dimension $(3 * N + 15)$ or greater. SINQI needs to be called only once to initialize WSAVE before calling SINQF and/or SINQB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

sint - compute the discrete Fourier sine transform of an odd sequence. The SINT transforms are unnormalized inverses of themselves, so a call of SINT followed by another call of SINT will multiply the input sequence by $2 * (N+1)$.

SYNOPSIS

```
SUBROUTINE SINT(N, X, WSAVE)
```

```
INTEGER N  
REAL X(*), WSAVE(*)
```

```
SUBROUTINE SINT_64(N, X, WSAVE)
```

```
INTEGER*8 N  
REAL X(*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINT(N, X, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

```
SUBROUTINE SINT_64(N, X, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: X, WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sint(int n, float *x, float *wsave);
```

```
void sint_64(long n, float *x, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These

subroutines are most efficient when $N+1$ is a product of small primes. $N \geq 0$.

X (input/output)

On entry, an array of length N containing the sequence to be transformed. On exit, the sine transform of the input.

WSAVE (input/output)

On entry, an array with dimension of at least $\text{int}(2.5 * N + 15)$ initialized by SINTI.

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NAME

sinti - initialize the array WSAVE, which is used in subroutine SINT.

SYNOPSIS

```
SUBROUTINE SINTI(N, WSAVE)
```

```
INTEGER N  
REAL WSAVE(*)
```

```
SUBROUTINE SINTI_64(N, WSAVE)
```

```
INTEGER*8 N  
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINTI(N, WSAVE)
```

```
INTEGER :: N  
REAL, DIMENSION(:) :: WSAVE
```

```
SUBROUTINE SINTI_64(N, WSAVE)
```

```
INTEGER(8) :: N  
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sinti(int n, float *wsave);
```

```
void sinti_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input/output)

On entry, an array of dimension $(2N + N/2 + 15)$ or greater. SINTI is called once to initialize WSAVE before calling SINT and need not be called again between calls to SINT if N and WSAVE remain unchanged. Thus, subsequent transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

sjadmm - Jagged diagonal matrix-matrix multiply (modified Ellpack)

SYNOPSIS

```
SUBROUTINE SJADMM( TRANSA, M, N, K, ALPHA, DESCRA,  
* VAL, INDX, PNTR, MAXNZ, IPERM,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, M, N, K, DESCRA(5), MAXNZ,  
* LDB, LDC, LWORK  
INTEGER INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
REAL ALPHA, BETA  
REAL VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SJADMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
* VAL, INDX, PNTR, MAXNZ, IPERM,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, M, N, K, DESCRA(5), MAXNZ,  
* LDB, LDC, LWORK  
INTEGER*8 INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
REAL ALPHA, BETA  
REAL VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ is the number of non-zero elements.

F95 INTERFACE

```
SUBROUTINE JADMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
* PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, M, K, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
REAL ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE JADMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
* PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, M, K, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM
```

```

REAL    ALPHA, BETA
REAL, DIMENSION(:) :: VAL
REAL, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void sjadmm (int transa, int m, int n, int k, float alpha,
int *descra, float *val, int *indx, int *pntr, int maxnz,
int *iperm, float *b, int ldb, float beta, float *c, int
ldb)

void sjadmm_64(long transa, long m, long n, long k, float
alpha, long *descra, float *val, long *indx, long *pntr,
long maxnz, long *iperm, float *b, long ldb, float beta,
float *c, long ldc);

```

DESCRIPTION

sjadmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \text{op}(A) B + \beta C$$

where $\text{op}(A)$ is one of

$\text{op}(A) = A$ or $\text{op}(A) = A'$ or $\text{op}(A) = \text{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the jagged diagonal format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \text{CONJG}(A')$) 3 : Triangular

4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
 NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of entries of A.
 VAL can be viewed as a column major ordering of a
 row permutation of the Ellpack representation of A,
 where the Ellpack representation is permuted so that
 the rows are non-increasing in the number of nonzero
 entries. Values added for padding in Ellpack are
 not included in the Jagged-Diagonal format.
 Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
 NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of the column
 indices of the corresponding entries in VAL.
 Unchanged on exit.

PNTR(input) On entry, PNTR is an integer array of length
 MAXNZ+1, where PNTR(I)-PNTR(1)+1 points to
 the location in VAL of the first element
 in the row-permuted Ellpack representation of A.
 Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of
 nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length M
 such that I = IPERM(I'), where row I in the
 original Ellpack representation corresponds
 to row I' in the permuted representation.
 If IPERM(1) = 0, it is assumed by convention that
 IPERM(I) = I. IPERM is used to determine the order
 in which rows of C are updated. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise

the leading k by n part of the array C must contain the matrix C . On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \beta * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

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NAME

sjadrp - right permutation of a jagged diagonal matrix

SYNOPSIS

```
SUBROUTINE SJADRP( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*                IPERM, WORK, LWORK )
INTEGER        TRANSP, M, K, MAXNZ, LWORK
INTEGER        INDX(*), PNTR(MAXNZ+1), IPERM(K), WORK(LWORK)
REAL           VAL(*)
```

```
SUBROUTINE SJADRP_64( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*                   IPERM, WORK, LWORK )
INTEGER*8      TRANSP, M, K, MAXNZ, LWORK
INTEGER*8      INDX(*), PNTR(MAXNZ+1), IPERM(K), WORK(LWORK)
REAL           VAL(*)
```

F95 INTERFACE

```
SUBROUTINE JADRP( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*               IPERM, [WORK], [LWORK] )
INTEGER TRANSP, M, K, MAXNZ
INTEGER, DIMENSION(:) :: INDX, PNTR, IPERM
REAL, DIMENSION(:) :: VAL
```

```
SUBROUTINE JADRP_64( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*                   IPERM, [WORK], [LWORK] )
INTEGER*8 TRANSP, M, K, MAXNZ
INTEGER*8, DIMENSION(:) :: INDX, PNTR, IPERM
REAL, DIMENSION(:) :: VAL
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sjadrp (int transp, int m, int k, float *val, int
*indx, int *pntr, int maxnz, int *iperms);
```

```
void sjadrp_64 (long transp, long m, long k, float *val,
long *indx, long *pntr, long maxnz, long *iperms);
```

DESCRIPTION

sjadrp performs one of the matrix-matrix operations

```
A <- A P   or   A <- A P'
                                     ( ' indicates matrix transpose)
```

where A is an M-by-K sparse matrix represented in the jagged diagonal format, the permutation matrix P is represented by an integer vector IPERM, such that IPERM(I) is equal to the position of the only nonzero element in row I of permutation matrix P. NOTE: In order to get a symmetrically permuted jagged diagonal matrix P A P', one can explicitly permute the columns P A by calling

```
SJADRP(0, M, M, VAL, INDX, PNTR, MAXNZ, IPERM, WORK, LWORK)
```

where parameters VAL, INDX, PNTR, MAXNZ, IPERM are the representation of A in the jagged diagonal format. The operation makes sense if the original matrix A is square.

ARGUMENTS

TRANSP(input) TRANSP indicates how to operate with the permutation matrix:
 0 : operate with matrix
 1 : operate with transpose matrix
 Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

K(input) On entry, K specifies the number of columns in the matrix A. Unchanged on exit.

VAL(input/output) On entry, VAL is a scalar array of length NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of entries of A. VAL can be viewed as a column major ordering of a row permutation of the Ellpack representation of A, where the Ellpack representation is permuted so that the rows are non-increasing in the number of nonzero entries. Values added for padding in Ellpack are not included in the Jagged-Diagonal format. On exit, VAL contains non-zero entries of the output permuted jagged diagonal matrix.

INDX(input/output) On entry, INDX is an integer array of length NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of the column indices of the corresponding entries in VAL. On exit, INDX is overwritten by the column indices of the output permuted jagged diagonal matrix.

PNTR(input) On entry, PNTR is an integer array of length MAXNZ+1, where PNTR(I)-PNTR(1)+1 points to the location in VAL of the first element in the row-permuted Ellpack representation of A. Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length K such that $I = \text{IPERM}(I')$. Array IPERM represents a permutation P, such that $\text{IPERM}(I)$ is equal to the position of the only nonzero element in row I of permutation matrix P. For example, if

$$P = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

then $\text{IPERM} = (3, 1, 2)$. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK. LWORK should be at least K.

LWORK(input) On entry, LWORK specifies the length of the array WORK. If $\text{LWORK}=0$, the routine is to allocate workspace needed. If $\text{LWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the array WORK, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

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NAME

sjadsm - Jagged-diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE SJADSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTR, MAXNZ, IPERM,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER          TRANSA, M, N, UNITD, DESCRA(5), MAXNZ,
*                LDB, LDC, LWORK
INTEGER          INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)
REAL             ALPHA, BETA
REAL            DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE SJADSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                VAL, INDX, PNTR, MAXNZ, IPERM,
*                B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5), MAXNZ,
*                LDB, LDC, LWORK
INTEGER*8        INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)
REAL             ALPHA, BETA
REAL            DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ is the number of non-zero elements

F95 INTERFACE

```
SUBROUTINE JADSM(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER          TRANSA, M, MAXNZ
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM
REAL             ALPHA, BETA
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C

SUBROUTINE JADSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,
*                PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER*8        TRANSA, M, MAXNZ
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM
REAL             ALPHA, BETA
```

```
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sjadsm (int transa, int m, int n, int unitd, float *dv,
float alpha, int *descra, float *val, int *indx, int *pntr,
int maxnz, int *iperm, float *b, int ldb, float beta, float
*c, int ldc)
void sjadsm_64(long transa, long m, long n, long unitd,
float *dv, float alpha, long *descra, float *val, long
*indx, long *pntr, long maxnz, long *iperm, float *b, long
ldb, float beta, float *c, long ldc);
```

DESCRIPTION

sjadsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in jagged-diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of entries of A.
VAL can be viewed as a column major ordering of a
row permutation of the Ellpack representation of A,
where the Ellpack representation is permuted so that
the rows are non-increasing in the number of nonzero
entries. Values added for padding in Ellpack are
not included in the Jagged-Diagonal format.
Unchanged on exit if UNITD is not equal to 4.

INDX(input) On entry, INDX is an integer array of length
NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of the column
indices of the corresponding entries in VAL.
Unchanged on exit.

PNTR(input) On entry, PNTR is an integer array of length
MAXNZ+1, where PNTR(I)-PNTR(1)+1 points to
the location in VAL of the first element
in the row-permuted Ellpack representation of A.
Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of
nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length M
such that I = IPERM(I'), where row I in the
original Ellpack representation corresponds
to row I' in the permuted representation.
If IPERM(1) = 0, it is assumed by convention that
IPERM(I) = I. IPERM is used to determine the order
in which rows of C are updated. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B

must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least 2*M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq 2*M*N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:
<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If UNITD =4, the routine scales the rows of the sparse matrix A such that their 2-norms are one. The scaling may

improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = - i where i is the row number which 2-norm is exactly zero.

3. If DESCRA(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the JAD representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the JAD representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But DESCRA(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	alpha*op(L+I)*B+beta*C
3	1	0	alpha*op(L+D)*B+beta*C
3	2	1	alpha*op(U+I)*B+beta*C
3	2	0	alpha*op(U+D)*B+beta*C

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NAME

slagtf - factorize the matrix $(T-\lambda I)$, where T is an n by n tridiagonal matrix and λ is a scalar, as $T-\lambda I = PLU$

SYNOPSIS

```
SUBROUTINE SLAGTF(N, A, LAMBDA, B, C, TOL, D, IN, INFO)
```

```
INTEGER N, INFO
INTEGER IN(*)
REAL LAMBDA, TOL
REAL A(*), B(*), C(*), D(*)
```

```
SUBROUTINE SLAGTF_64(N, A, LAMBDA, B, C, TOL, D, IN, INFO)
```

```
INTEGER*8 N, INFO
INTEGER*8 IN(*)
REAL LAMBDA, TOL
REAL A(*), B(*), C(*), D(*)
```

F95 INTERFACE

```
SUBROUTINE LAGTF([N], A, LAMBDA, B, C, TOL, D, IN, [INFO])
```

```
INTEGER :: N, INFO
INTEGER, DIMENSION(:) :: IN
REAL :: LAMBDA, TOL
REAL, DIMENSION(:) :: A, B, C, D
```

```
SUBROUTINE LAGTF_64([N], A, LAMBDA, B, C, TOL, D, IN, [INFO])
```

```
INTEGER(8) :: N, INFO
INTEGER(8), DIMENSION(:) :: IN
REAL :: LAMBDA, TOL
REAL, DIMENSION(:) :: A, B, C, D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void slagtf(int n, float *a, float lambda, float *b, float
            *c, float tol, float *d, int *in, int *info);
```

```

void slagtf_64(long n, float *a, float lambda, float *b,
              float *c, float tol, float *d, long *in, long
              *info);

```

PURPOSE

slagtf factorizes the matrix $(T - \lambda I)$, where T is an n by n tridiagonal matrix and λ is a scalar, as where P is a permutation matrix, L is a unit lower tridiagonal matrix with at most one non-zero sub-diagonal elements per column and U is an upper triangular matrix with at most two non-zero super-diagonal elements per column.

The factorization is obtained by Gaussian elimination with partial pivoting and implicit row scaling.

The parameter LAMBDA is included in the routine so that SLAGTF may be used, in conjunction with SLAGTS, to obtain eigenvectors of T by inverse iteration.

ARGUMENTS

N (input) The order of the matrix T .

A (input/output)

On entry, A must contain the diagonal elements of T .

On exit, A is overwritten by the n diagonal elements of the upper triangular matrix U of the factorization of T .

LAMBDA (input)

On entry, the scalar λ .

B (input/output)

On entry, B must contain the $(n-1)$ super-diagonal elements of T .

On exit, B is overwritten by the $(n-1)$ super-diagonal elements of the matrix U of the factorization of T .

C (input/output)

On entry, C must contain the $(n-1)$ sub-diagonal elements of T .

On exit, C is overwritten by the $(n-1)$ sub-diagonal elements of the matrix L of the factorization of T .

TOL (input/output)

On entry, a relative tolerance used to indicate whether or not the matrix $(T - \lambda I)$ is nearly singular. TOL should normally be chosen as approximately the largest relative error in the elements

of T. For example, if the elements of T are correct to about 4 significant figures, then TOL should be set to about $5 \cdot 10^{-4}$. If TOL is supplied as less than eps, where eps is the relative machine precision, then the value eps is used in place of TOL.

D (output)

On exit, D is overwritten by the (n-2) second super-diagonal elements of the matrix U of the factorization of T.

IN (output)

On exit, IN contains details of the permutation matrix P. If an interchange occurred at the kth step of the elimination, then $IN(k) = 1$, otherwise $IN(k) = 0$. The element $IN(n)$ returns the smallest positive integer j such that

$$\text{abs}(u(j,j)) \cdot \text{le. norm}(T - \lambda I)(j) \cdot \text{TOL},$$

where $\text{norm}(A(j))$ denotes the sum of the absolute values of the jth row of the matrix A. If no such j exists then $IN(n)$ is returned as zero. If $IN(n)$ is returned as positive, then a diagonal element of U is small, indicating that $(T - \lambda I)$ is singular or nearly singular,

INFO (output)

= 0 : successful exit

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NAME

slamrg - will create a permutation list which will merge the elements of A (which is composed of two independently sorted sets) into a single set which is sorted in ascending order

SYNOPSIS

```
SUBROUTINE SLAMRG(N1, N2, A, TRD1, TRD2, INDEX)
```

```
INTEGER N1, N2, TRD1, TRD2  
INTEGER INDEX(*)  
REAL A(*)
```

```
SUBROUTINE SLAMRG_64(N1, N2, A, TRD1, TRD2, INDEX)
```

```
INTEGER*8 N1, N2, TRD1, TRD2  
INTEGER*8 INDEX(*)  
REAL A(*)
```

F95 INTERFACE

```
SUBROUTINE LAMRG(N1, N2, A, TRD1, TRD2, INDEX)
```

```
INTEGER :: N1, N2, TRD1, TRD2  
INTEGER, DIMENSION(:) :: INDEX  
REAL, DIMENSION(:) :: A
```

```
SUBROUTINE LAMRG_64(N1, N2, A, TRD1, TRD2, INDEX)
```

```
INTEGER(8) :: N1, N2, TRD1, TRD2  
INTEGER(8), DIMENSION(:) :: INDEX  
REAL, DIMENSION(:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void slamrg(int n1, int n2, float *a, int trd1, int trd2,  
            int *index);
```

```
void slamrg_64(long n1, long n2, float *a, long trd1, long  
               trd2, long *index);
```

PURPOSE

slamrg will create a permutation list which will merge the elements of A (which is composed of two independently sorted sets) into a single set which is sorted in ascending order.

ARGUMENTS

N1 (input)
Length of the first sequence to be merged.

N2 (input)
Length of the second sequence to be merged.

A (input) On entry, the first N1 elements of A contain a list of numbers which are sorted in either ascending or descending order. Likewise for the final N2 elements.

TRD1 (input)
Describes the stride to be taken through the array A for the first N1 elements.
= -1 subset is sorted in descending order.
= 1 subset is sorted in ascending order.

TRD2 (input)
Describes the stride to be taken through the array A for the first N1 elements.
= -1 subset is sorted in descending order.
= 1 subset is sorted in ascending order.

INDEX (output)
On exit this array will contain a permutation such that if $B(I) = A(\text{INDEX}(I))$ for $I=1, N1+N2$, then B will be sorted in ascending order.

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NAME

slarz - applies a real elementary reflector H to a real M-by-N matrix C, from either the left or the right

SYNOPSIS

```
SUBROUTINE SLARZ(SIDE, M, N, L, V, INCV, TAU, C, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
INTEGER M, N, L, INCV, LDC  
REAL TAU  
REAL V(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SLARZ_64(SIDE, M, N, L, V, INCV, TAU, C, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
INTEGER*8 M, N, L, INCV, LDC  
REAL TAU  
REAL V(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE LARZ(SIDE, [M], [N], L, V, [INCV], TAU, C, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
INTEGER :: M, N, L, INCV, LDC  
REAL :: TAU  
REAL, DIMENSION(:) :: V, WORK  
REAL, DIMENSION(:,) :: C
```

```
SUBROUTINE LARZ_64(SIDE, [M], [N], L, V, [INCV], TAU, C, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
INTEGER(8) :: M, N, L, INCV, LDC  
REAL :: TAU  
REAL, DIMENSION(:) :: V, WORK  
REAL, DIMENSION(:,) :: C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void slarz(char side, int m, int n, int l, float *v, int
          incv, float tau, float *c, int ldc);
```

```
void slarz_64(char side, long m, long n, long l, float *v,
             long incv, float tau, float *c, long ldc);
```

PURPOSE

slarz applies a real elementary reflector H to a real M-by-N matrix C, from either the left or the right. H is represented in the form

$$H = I - \tau * v * v'$$

where tau is a real scalar and v is a real vector.

If tau = 0, then H is taken to be the unit matrix.

H is a product of k elementary reflectors as returned by STZRZF.

ARGUMENTS

SIDE (input)

= 'L': form $H * C$
= 'R': form $C * H$

M (input) The number of rows of the matrix C.

N (input) The number of columns of the matrix C.

L (input) The number of entries of the vector V containing the meaningful part of the Householder vectors. If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L \geq 0$.

V (input) The vector v in the representation of H as returned by STZRZF. V is not used if TAU = 0.

INCV (input)

The increment between elements of v. INCV $\neq 0$.

TAU (input)

The value tau in the representation of H.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by the matrix $H * C$ if SIDE = 'L', or $C * H$ if SIDE = 'R'.

LDC (input)

The leading dimension of the array C. LDC $\geq \max(1, M)$.

WORK (workspace)

(N) if SIDE = 'L' or (M) if SIDE = 'R'

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

slarzb - applies a real block reflector H or its transpose H**T to a real distributed M-by-N C from the left or the right

SYNOPSIS

```
SUBROUTINE SLARZB(SIDE, TRANS, DIRECT, STOREV, M, N, K, L, V, LDV, T,
                 LDT, C, LDC, WORK, LDWORK)
```

```
CHARACTER * 1 SIDE, TRANS, DIRECT, STOREV
INTEGER M, N, K, L, LDV, LDT, LDC, LDWORK
REAL V(LDV,*), T(LDT,*), C(LDC,*), WORK(LDWORK,*)
```

```
SUBROUTINE SLARZB_64(SIDE, TRANS, DIRECT, STOREV, M, N, K, L, V, LDV,
                    T, LDT, C, LDC, WORK, LDWORK)
```

```
CHARACTER * 1 SIDE, TRANS, DIRECT, STOREV
INTEGER*8 M, N, K, L, LDV, LDT, LDC, LDWORK
REAL V(LDV,*), T(LDT,*), C(LDC,*), WORK(LDWORK,*)
```

F95 INTERFACE

```
SUBROUTINE LARZB(SIDE, TRANS, DIRECT, STOREV, [M], [N], K, L, V, [LDV],
                T, [LDT], C, [LDC], [WORK], [LDWORK])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS, DIRECT, STOREV
INTEGER :: M, N, K, L, LDV, LDT, LDC, LDWORK
REAL, DIMENSION(:,:) :: V, T, C, WORK
```

```
SUBROUTINE LARZB_64(SIDE, TRANS, DIRECT, STOREV, [M], [N], K, L, V,
                   [LDV], T, [LDT], C, [LDC], [WORK], [LDWORK])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS, DIRECT, STOREV
INTEGER(8) :: M, N, K, L, LDV, LDT, LDC, LDWORK
REAL, DIMENSION(:,:) :: V, T, C, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```

void slarzb(char side, char trans, char direct, char storev,
            int m, int n, int k, int l, float *v, int ldv,
            float *t, int ldt, float *c, int ldc, int ldwork);

void slarzb_64(char side, char trans, char direct, char
               storev, long m, long n, long k, long l, float *v,
               long ldv, float *t, long ldt, float *c, long ldc,
               long ldwork);

```

PURPOSE

slarzb applies a real block reflector H or its transpose H^*T to a real distributed M -by- N C from the left or the right.

Currently, only STOREV = 'R' and DIRECT = 'B' are supported.

ARGUMENTS

SIDE (input)
 = 'L': apply H or H' from the Left
 = 'R': apply H or H' from the Right

TRANS (input)
 = 'N': apply H (No transpose)
 = 'C': apply H' (Transpose)

DIRECT (input)
 Indicates how H is formed from a product of elementary reflectors = 'F': $H = H(1) H(2) \dots H(k)$ (Forward, not supported yet)
 = 'B': $H = H(k) \dots H(2) H(1)$ (Backward)

STOREV (input)
 Indicates how the vectors which define the elementary reflectors are stored:
 = 'C': Columnwise (not supported yet)
 = 'R': Rowwise

M (input) The number of rows of the matrix C .

N (input) The number of columns of the matrix C .

K (input) The order of the matrix T (= the number of elementary reflectors whose product defines the block reflector).

L (input) The number of columns of the matrix V containing the meaningful part of the Householder reflectors. If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L \geq 0$.

V (input) If STOREV = 'C', $NV = K$; if STOREV = 'R', $NV = L$.

LDV (input)
 The leading dimension of the array V . If STOREV =

'C', LDV \geq L; if STOREV = 'R', LDV \geq K.

T (input) The triangular K-by-K matrix T in the representation of the block reflector.

LDT (input)
The leading dimension of the array T. LDT \geq K.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by H*C or H'*C or C*H or C*H'.

LDC (input)
The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)
dimension(MAX(M,N),K)

LDWORK (input)
The leading dimension of the array WORK. If SIDE = 'L', LDWORK \geq max(1,N); if SIDE = 'R', LDWORK \geq max(1,M).

FURTHER DETAILS

Based on contributions by
A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

slarzt - form the triangular factor T of a real block reflector H of order > n, which is defined as a product of k elementary reflectors

SYNOPSIS

```
SUBROUTINE SLARZT(DIRECT, STOREV, N, K, V, LDV, TAU, T, LDT)
```

```
CHARACTER * 1 DIRECT, STOREV  
INTEGER N, K, LDV, LDT  
REAL V(LDV,*), TAU(*), T(LDT,*)
```

```
SUBROUTINE SLARZT_64(DIRECT, STOREV, N, K, V, LDV, TAU, T, LDT)
```

```
CHARACTER * 1 DIRECT, STOREV  
INTEGER*8 N, K, LDV, LDT  
REAL V(LDV,*), TAU(*), T(LDT,*)
```

F95 INTERFACE

```
SUBROUTINE LARZT(DIRECT, STOREV, N, K, V, [LDV], TAU, T, [LDT])
```

```
CHARACTER(LEN=1) :: DIRECT, STOREV  
INTEGER :: N, K, LDV, LDT  
REAL, DIMENSION(:) :: TAU  
REAL, DIMENSION(:,) :: V, T
```

```
SUBROUTINE LARZT_64(DIRECT, STOREV, N, K, V, [LDV], TAU, T, [LDT])
```

```
CHARACTER(LEN=1) :: DIRECT, STOREV  
INTEGER(8) :: N, K, LDV, LDT  
REAL, DIMENSION(:) :: TAU  
REAL, DIMENSION(:,) :: V, T
```

C INTERFACE

```
#include <sunperf.h>
```

```
void slarzt(char direct, char storev, int n, int k, float  
*v, int ldv, float *tau, float *t, int ldt);
```

```
void slarzt_64(char direct, char storev, long n, long k,
              float *v, long ldv, float *tau, float *t, long
              ldt);
```

PURPOSE

slarzt forms the triangular factor T of a real block reflector H of order $> n$, which is defined as a product of k elementary reflectors.

If DIRECT = 'F', $H = H(1) H(2) \dots H(k)$ and T is upper triangular;

If DIRECT = 'B', $H = H(k) \dots H(2) H(1)$ and T is lower triangular.

If STOREV = 'C', the vector which defines the elementary reflector H(i) is stored in the i-th column of the array V, and

$$H = I - V * T * V'$$

If STOREV = 'R', the vector which defines the elementary reflector H(i) is stored in the i-th row of the array V, and

$$H = I - V' * T * V$$

Currently, only STOREV = 'R' and DIRECT = 'B' are supported.

ARGUMENTS

DIRECT (input)

Specifies the order in which the elementary reflectors are multiplied to form the block reflector:
 = 'F': $H = H(1) H(2) \dots H(k)$ (Forward, not supported yet)
 = 'B': $H = H(k) \dots H(2) H(1)$ (Backward)

STOREV (input)

Specifies how the vectors which define the elementary reflectors are stored (see also Further Details):
 = 'R': rowwise

N (input) The order of the block reflector H. $N \geq 0$.

K (input) The order of the triangular factor T (= the number of elementary reflectors). $K \geq 1$.

V (input) (LDV,K) if STOREV = 'C' (LDV,N) if STOREV = 'R'
 The matrix V. See further details.

LDV (input)

The leading dimension of the array V. If STOREV =

'C', LDV >= max(1,N); if STOREV = 'R', LDV >= K.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i).

T (input)

The k by k triangular factor T of the block reflector. If DIRECT = 'F', T is upper triangular; if DIRECT = 'B', T is lower triangular. The rest of the array is not used.

LDT (input)

The leading dimension of the array T. LDT >= K.

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

The shape of the matrix V and the storage of the vectors which define the H(i) is best illustrated by the following example with n = 5 and k = 3. The elements equal to 1 are not stored; the corresponding array elements are modified but restored on exit. The rest of the array is not used.

DIRECT = 'F' and STOREV = 'C': DIRECT = 'F' and STOREV = 'R':

<pre> (v1 v2 v3) (v1 v2 v3)) V = (v1 v2 v3) . . 1) . 1) (v1 v2 v3) (v1 v2 v3) . . . 1 . . . 1 . . 1 </pre>	<pre> _____V_____ (v1 v1 v1 v1 v1 1 (v2 v2 v2 v2 v2 . (v3 v3 v3 v3 v3 . </pre>
---	---

DIRECT = 'B' and STOREV = 'C': DIRECT = 'B' and STOREV = 'R':

<pre> 1 . 1 . . 1 v2 v2 v2) v3 v3 v3) . . . (v1 v2 v3) V = (v1 v2 v3) (v1 v2 v3) </pre>	<pre> _____V_____ / (1 v1 v1 v1 v1 v1) (. 1 v2 v2 (. . 1 . . . v3 v3 </pre>
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NAME

slasrt - the numbers in D in increasing order (if ID = 'I')
or in decreasing order (if ID = 'D')

SYNOPSIS

```
SUBROUTINE SLASRT(ID, N, D, INFO)
```

```
CHARACTER * 1 ID  
INTEGER N, INFO  
REAL D(*)
```

```
SUBROUTINE SLASRT_64(ID, N, D, INFO)
```

```
CHARACTER * 1 ID  
INTEGER*8 N, INFO  
REAL D(*)
```

F95 INTERFACE

```
SUBROUTINE LASRT(ID, [N], D, [INFO])
```

```
CHARACTER(LEN=1) :: ID  
INTEGER :: N, INFO  
REAL, DIMENSION(:) :: D
```

```
SUBROUTINE LASRT_64(ID, [N], D, [INFO])
```

```
CHARACTER(LEN=1) :: ID  
INTEGER(8) :: N, INFO  
REAL, DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void slasrt(char id, int n, float *d, int *info);
```

```
void slasrt_64(char id, long n, float *d, long *info);
```

PURPOSE

slasrt the numbers in D in increasing order (if ID = 'I') or in decreasing order (if ID = 'D').

Use Quick Sort, reverting to Insertion sort on arrays of size ≤ 20 . Dimension of STACK limits N to about 2^{32} .

ARGUMENTS

ID (input)

= 'I': sort D in increasing order;
= 'D': sort D in decreasing order.

N (input) The length of the array D.

D (input/output)

On entry, the array to be sorted. On exit, D has been sorted into increasing order ($D(1) \leq \dots \leq D(N)$) or into decreasing order ($D(1) \geq \dots \geq D(N)$), depending on ID.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

slatzm - routine is deprecated and has been replaced by routine SORMRZ

SYNOPSIS

```
SUBROUTINE SLATZM(SIDE, M, N, V, INCV, TAU, C1, C2, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
INTEGER M, N, INCV, LDC  
REAL TAU  
REAL V(*), C1(LDC,*), C2(LDC,*), WORK(*)
```

```
SUBROUTINE SLATZM_64(SIDE, M, N, V, INCV, TAU, C1, C2, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
INTEGER*8 M, N, INCV, LDC  
REAL TAU  
REAL V(*), C1(LDC,*), C2(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE LATZM(SIDE, [M], [N], V, [INCV], TAU, C1, C2, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
INTEGER :: M, N, INCV, LDC  
REAL :: TAU  
REAL, DIMENSION(:) :: V, WORK  
REAL, DIMENSION(:, :) :: C1, C2
```

```
SUBROUTINE LATZM_64(SIDE, [M], [N], V, [INCV], TAU, C1, C2, [LDC],  
[WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
INTEGER(8) :: M, N, INCV, LDC  
REAL :: TAU  
REAL, DIMENSION(:) :: V, WORK  
REAL, DIMENSION(:, :) :: C1, C2
```

C INTERFACE

```
#include <sunperf.h>
```

```

void slatzm(char side, int m, int n, float *v, int incv,
            float tau, float *c1, float *c2, int ldc);

void slatzm_64(char side, long m, long n, float *v, long
               incv, float tau, float *c1, float *c2, long ldc);

```

PURPOSE

slatzm routine is deprecated and has been replaced by routine SORMRZ.

SLATZM applies a Householder matrix generated by STZRQF to a matrix.

Let $P = I - \tau \cdot u \cdot u'$, $u = \begin{pmatrix} 1 \\ v \end{pmatrix}$,

where v is an $(m-1)$ vector if $SIDE = 'L'$, or a $(n-1)$ vector if $SIDE = 'R'$.

If $SIDE$ equals $'L'$, let

$$C = \begin{bmatrix} C1 & 1 \\ C2 & m-1 \\ & n \end{bmatrix}$$

Then C is overwritten by $P \cdot C$.

If $SIDE$ equals $'R'$, let

$$C = \begin{bmatrix} C1 & C2 \\ 1 & n-1 \end{bmatrix} \begin{matrix} m \\ \end{matrix}$$

Then C is overwritten by $C \cdot P$.

ARGUMENTS

$SIDE$ (input)

= $'L'$: form $P \cdot C$
 = $'R'$: form $C \cdot P$

M (input) The number of rows of the matrix C .

N (input) The number of columns of the matrix C .

V (input) $(1 + (M-1) \cdot \text{abs}(\text{INCV}))$ if $SIDE = 'L'$ $(1 + (N-1) \cdot \text{abs}(\text{INCV}))$ if $SIDE = 'R'$ The vector v in the representation of P . V is not used if $\text{TAU} = 0$.

INCV (input)

The increment between elements of v . $\text{INCV} \neq 0$

TAU (input)

The value τ in the representation of P .

$C1$ (input/output)

(LDC, N) if $SIDE = 'L'$ $(M, 1)$ if $SIDE = 'R'$ On entry, the n -vector $C1$ if $SIDE = 'L'$, or the m -vector $C1$ if $SIDE = 'R'$.

On exit, the first row of $P \cdot C$ if $SIDE = 'L'$, or

the first column of C*P if SIDE = 'R'.

C2 (input/output)

(LDC, N) if SIDE = 'L' (LDC, N-1) if SIDE = 'R'
On entry, the $(m - 1) \times n$ matrix C2 if SIDE = 'L',
or the $m \times (n - 1)$ matrix C2 if SIDE = 'R'.

On exit, rows 2:m of P*C if SIDE = 'L', or columns
2:m of C*P if SIDE = 'R'.

LDC (input)

The leading dimension of the arrays C1 and C2. LDC
>= (1,M).

WORK (workspace)

(N) if SIDE = 'L' (M) if SIDE = 'R'

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NAME

snrm2 - Return the Euclidian norm of a vector.

SYNOPSIS

```
REAL FUNCTION SNRM2(N, X, INCX)
```

```
INTEGER N, INCX  
REAL X(*)
```

```
REAL FUNCTION SNRM2_64(N, X, INCX)
```

```
INTEGER*8 N, INCX  
REAL X(*)
```

F95 INTERFACE

```
REAL FUNCTION NRM2([N], X, [INCX])
```

```
INTEGER :: N, INCX  
REAL, DIMENSION(:) :: X
```

```
REAL FUNCTION NRM2_64([N], X, [INCX])
```

```
INTEGER(8) :: N, INCX  
REAL, DIMENSION(:) :: X
```

C INTERFACE

```
#include <sunperf.h>
```

```
float snrm2(int n, float *x, int incx);
```

```
float snrm2_64(long n, float *x, long incx);
```

PURPOSE

snrm2 Return the Euclidian norm of a vector x where x is an n-vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)). On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. If INCX < 1 then SNRM2 returns 0. Unchanged on exit.

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NAME

sopgtr - generate a real orthogonal matrix Q which is defined as the product of $n-1$ elementary reflectors $H(i)$ of order n , as returned by SSPTRD using packed storage

SYNOPSIS

```
SUBROUTINE SOPGTR(UPLO, N, AP, TAU, Q, LDQ, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDQ, INFO  
REAL AP(*), TAU(*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE SOPGTR_64(UPLO, N, AP, TAU, Q, LDQ, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDQ, INFO  
REAL AP(*), TAU(*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE OPGTR(UPLO, [N], AP, TAU, Q, [LDQ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDQ, INFO  
REAL, DIMENSION(:) :: AP, TAU, WORK  
REAL, DIMENSION(:,) :: Q
```

```
SUBROUTINE OPGTR_64(UPLO, [N], AP, TAU, Q, [LDQ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDQ, INFO  
REAL, DIMENSION(:) :: AP, TAU, WORK  
REAL, DIMENSION(:,) :: Q
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sopgtr(char uplo, int n, float *ap, float *tau, float  
           *q, int ldq, int *info);
```

```
void sopgtr_64(char uplo, long n, float *ap, float *tau,
```

```
float *q, long ldq, long *info);
```

PURPOSE

sopgtr generates a real orthogonal matrix Q which is defined as the product of $n-1$ elementary reflectors $H(i)$ of order n , as returned by SSPTRD using packed storage:
if UPLO = 'U', $Q = H(n-1) \dots H(2) H(1)$,
if UPLO = 'L', $Q = H(1) H(2) \dots H(n-1)$.

ARGUMENTS

UPLO (input)
= 'U': Upper triangular packed storage used in previous call to SSPTRD; = 'L': Lower triangular packed storage used in previous call to SSPTRD.

N (input) The order of the matrix Q . $N \geq 0$.

AP (input)
The vectors which define the elementary reflectors, as returned by SSPTRD.

TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by SSPTRD.

Q (output)
The N -by- N orthogonal matrix Q .

LDQ (input)
The leading dimension of the array Q . $LDQ \geq \max(1, N)$.

WORK (workspace)
dimension($N-1$)

INFO (output)
= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

sopmtr - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE SOPMTR(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,  
INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
INTEGER M, N, LDC, INFO  
REAL AP(*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SOPMTR_64(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,  
INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
INTEGER*8 M, N, LDC, INFO  
REAL AP(*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE OPMTR(SIDE, UPLO, [TRANS], [M], [N], AP, TAU, C, [LDC],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
INTEGER :: M, N, LDC, INFO  
REAL, DIMENSION(:) :: AP, TAU, WORK  
REAL, DIMENSION(:,) :: C
```

```
SUBROUTINE OPMTR_64(SIDE, UPLO, [TRANS], [M], [N], AP, TAU, C, [LDC],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
INTEGER(8) :: M, N, LDC, INFO  
REAL, DIMENSION(:) :: AP, TAU, WORK  
REAL, DIMENSION(:,) :: C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sopmtr(char side, char uplo, char trans, int m, int n,
```

```

float *ap, float *tau, float *c, int ldc, int
*info);

void sopmtr_64(char side, char uplo, char trans, long m,
long n, float *ap, float *tau, float *c, long ldc,
long *info);

```

PURPOSE

sopmtr overwrites the general real M-by-N matrix C with
TRANS = 'T': $Q^{*T} * C$ $C * Q^{*T}$

where Q is a real orthogonal matrix of order nq, with nq = m
if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
product of nq-1 elementary reflectors, as returned by SSPTRD
using packed storage:

if UPLO = 'U', Q = H(nq-1) . . . H(2) H(1);

if UPLO = 'L', Q = H(1) H(2) . . . H(nq-1).

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*T} from the Left;
= 'R': apply Q or Q^{*T} from the Right.

UPLO (input)

= 'U': Upper triangular packed storage used in
previous call to SSPTRD; = 'L': Lower triangular
packed storage used in previous call to SSPTRD.

TRANS (input)

= 'N': No transpose, apply Q;
= 'T': Transpose, apply Q^{*T} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

AP (input)

(M*(M+1)/2) if SIDE = 'L' (N*(N+1)/2) if SIDE =
'R' The vectors which define the elementary
reflectors, as returned by SSPTRD. AP is modified
by the routine but restored on exit.

TAU (input)

or (N-1) if SIDE = 'R' TAU(i) must contain the
scalar factor of the elementary reflector H(i), as
returned by SSPTRD.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is
overwritten by $Q * C$ or $Q^{*T} * C$ or $C * Q^{*T}$ or $C * Q$.

LDC (input)
The leading dimension of the array C. LDC \geq
max(1,M).

WORK (workspace)
(N) if SIDE = 'L' (M) if SIDE = 'R'

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sorg2l - generate an m by n real matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE SORG2L(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER M, N, K, LDA, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORG2L_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORG2L([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORG2L_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, K, LDA, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorg2l(int m, int n, int k, float *a, int lda, float  
*tau, int *info);
```

```
void sorg2l_64(long m, long n, long k, float *a, long lda,  
float *tau, long *info);
```

PURPOSE

sorg21 L generates an m by n real matrix Q with orthonormal columns, which is defined as the last n columns of a product of k elementary reflectors of order m

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGEQLF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.

A (input/output)

On entry, the (n-k+i)-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by SGEQLF in the last k columns of its array argument A. On exit, the m by n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGEQLF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

sorg2r - generate an m by n real matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE SORG2R(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER M, N, K, LDA, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORG2R_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORG2R([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORG2R_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, K, LDA, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorg2r(int m, int n, int k, float *a, int lda, float  
          *tau, int *info);
```

```
void sorg2r_64(long m, long n, long k, float *a, long lda,  
             float *tau, long *info);
```

PURPOSE

sorg2r R generates an m by n real matrix Q with orthonormal columns, which is defined as the first n columns of a product of k elementary reflectors of order m

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGEQRF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.

A (input/output)

On entry, the i-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by SGEQRF in the first k columns of its array argument A. On exit, the m-by-n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGEQRF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

sorgbr - generate one of the real orthogonal matrices Q or P^*T determined by SGEBRD when reducing a real matrix A to bidiagonal form

SYNOPSIS

```
SUBROUTINE SORGBR(VECT, M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT  
INTEGER M, N, K, LDA, LWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORGBR_64(VECT, M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT  
INTEGER*8 M, N, K, LDA, LWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGBR(VECT, M, [N], K, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: VECT  
INTEGER :: M, N, K, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORGBR_64(VECT, M, [N], K, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: VECT  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorgbr(char vect, int m, int n, int k, float *a, int  
lda, float *tau, int *info);
```

```
void sorgbr_64(char vect, long m, long n, long k, float *a,
               long lda, float *tau, long *info);
```

PURPOSE

sorgbr generates one of the real orthogonal matrices Q or P^{**T} determined by SGEBRD when reducing a real matrix A to bidiagonal form: $A = Q * B * P^{**T}$. Q and P^{**T} are defined as products of elementary reflectors $H(i)$ or $G(i)$ respectively.

If $VECT = 'Q'$, A is assumed to have been an M -by- K matrix, and Q is of order M :
if $m \geq k$, $Q = H(1) H(2) \dots H(k)$ and SORGBR returns the first n columns of Q , where $m \geq n \geq k$;
if $m < k$, $Q = H(1) H(2) \dots H(m-1)$ and SORGBR returns Q as an M -by- M matrix.

If $VECT = 'P'$, A is assumed to have been a K -by- N matrix, and P^{**T} is of order N :
if $k < n$, $P^{**T} = G(k) \dots G(2) G(1)$ and SORGBR returns the first m rows of P^{**T} , where $n \geq m \geq k$;
if $k \geq n$, $P^{**T} = G(n-1) \dots G(2) G(1)$ and SORGBR returns P^{**T} as an N -by- N matrix.

ARGUMENTS

VECT (input)

Specifies whether the matrix Q or the matrix P^{**T} is required, as defined in the transformation applied by SGEBRD:
= 'Q': generate Q ;
= 'P': generate P^{**T} .

M (input) The number of rows of the matrix Q or P^{**T} to be returned. $M \geq 0$.

N (input) The number of columns of the matrix Q or P^{**T} to be returned. $N \geq 0$. If $VECT = 'Q'$, $M \geq N \geq \min(M,K)$; if $VECT = 'P'$, $N \geq M \geq \min(N,K)$.

K (input) If $VECT = 'Q'$, the number of columns in the original M -by- K matrix reduced by SGEBRD. If $VECT = 'P'$, the number of rows in the original K -by- N matrix reduced by SGEBRD. $K \geq 0$.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by SGEBRD. On exit, the M -by- N matrix Q or P^{**T} .

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1,M)$.

TAU (input)

(min(M,K)) if VECT = 'Q' (min(N,K)) if VECT = 'P'
TAU(i) must contain the scalar factor of the elementary reflector H(i) or G(i), which determines Q or P**T, as returned by SGEBRD in its array argument TAUQ or TAUP.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK >= max(1,min(M,N)). For optimum performance LWORK >= min(M,N)*NB, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sorghr - generate a real orthogonal matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N , as returned by SGEHRD

SYNOPSIS

```
SUBROUTINE SORGHR(N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
```

```
INTEGER N, ILO, IHI, LDA, LWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORGHR_64(N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
```

```
INTEGER*8 N, ILO, IHI, LDA, LWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGHR([N], ILO, IHI, A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
INTEGER :: N, ILO, IHI, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE ORGHR_64([N], ILO, IHI, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
INTEGER(8) :: N, ILO, IHI, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorghr(int n, int ilo, int ihi, float *a, int lda,  
float *tau, int *info);
```

```
void sorghr_64(long n, long ilo, long ihi, float *a, long  
lda, float *tau, long *info);
```

PURPOSE

sorghr generates a real orthogonal matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N , as returned by SGEHRD:

$$Q = H(\text{ilo}) H(\text{ilo}+1) \dots H(\text{ihi}-1).$$

ARGUMENTS

N (input) The order of the matrix Q . $N \geq 0$.

ILO (input)

ILO and IHI must have the same values as in the previous call of SGEHRD. Q is equal to the unit matrix except in the submatrix $Q(\text{ilo}+1:\text{ihi}, \text{ilo}+1:\text{ihi})$. $1 \leq \text{ILO} \leq \text{IHI} \leq N$, if $N > 0$; $\text{ILO}=1$ and $\text{IHI}=0$, if $N=0$.

IHI (input)

See the description of ILO.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by SGEHRD. On exit, the N -by- N orthogonal matrix Q .

LDA (input)

The leading dimension of the array A . $\text{LDA} \geq \max(1, N)$.

TAU (input)

$\text{TAU}(i)$ must contain the scalar factor of the elementary reflector $H(i)$, as returned by SGEHRD.

WORK (workspace)

On exit, if $\text{INFO} = 0$, $\text{WORK}(1)$ returns the optimal LWORK .

LWORK (input)

The dimension of the array WORK . $\text{LWORK} \geq \text{IHI}-\text{ILO}$. For optimum performance $\text{LWORK} \geq (\text{IHI}-\text{ILO}) * \text{NB}$, where NB is the optimal blocksize.

If $\text{LWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value

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NAME

sorgl2 - generate an m by n real matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE SORGL2(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER M, N, K, LDA, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORGL2_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGL2([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORGL2_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, K, LDA, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorgl2(int m, int n, int k, float *a, int lda, float  
          *tau, int *info);
```

```
void sorgl2_64(long m, long n, long k, float *a, long lda,  
             float *tau, long *info);
```

PURPOSE

sorgl2 generates an m by n real matrix Q with orthonormal rows, which is defined as the first m rows of a product of k elementary reflectors of order n

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGELQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $M \geq K \geq 0$.

A (input/output)

On entry, the i-th row must contain the vector which defines the elementary reflector $H(i)$, for $i = 1, 2, \dots, k$, as returned by SGELQF in the first k rows of its array argument A. On exit, the m-by-n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by SGELQF.

WORK (workspace)

dimension(M)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

sorglq - generate an M-by-N real matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE SORGLQ(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, K, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORGLQ_64(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGLQ(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORGLQ_64(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK],  
[INFO])
```

```
INTEGER(8) :: M, N, K, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorglq(int m, int n, int k, float *a, int lda, float  
*tau, int *info);
```

```
void sorglq_64(long m, long n, long k, float *a, long lda,  
float *tau, long *info);
```

PURPOSE

sorglq generates an M-by-N real matrix Q with orthonormal rows, which is defined as the first M rows of a product of K elementary reflectors of order N

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGELQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $M \geq K \geq 0$.

A (input/output)

On entry, the i-th row must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by SGELQF in the first k rows of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGELQF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, M)$. For optimum performance $LDWORK \geq M \cdot NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

sorgql - generate an M-by-N real matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE SORGQL(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, K, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORGQL_64(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGQL(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORGQL_64(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK],  
[INFO])
```

```
INTEGER(8) :: M, N, K, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorgql(int m, int n, int k, float *a, int lda, float  
*tau, int *info);
```

```
void sorgql_64(long m, long n, long k, float *a, long lda,  
float *tau, long *info);
```

PURPOSE

sorgql generates an M-by-N real matrix Q with orthonormal columns, which is defined as the last N columns of a product of K elementary reflectors of order M

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGEQLF.

ARGUMENTS

- M (input) The number of rows of the matrix Q. $M \geq 0$.
- N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.
- K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.
- A (input/output)
On entry, the (n-k+i)-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by SGEQLF in the last k columns of its array argument A. On exit, the M-by-N matrix Q.
- LDA (input)
The first dimension of the array A. $LDA \geq \max(1, M)$.
- TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGEQLF.
- WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.
- LDWORK (input)
The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N * NB$, where NB is the optimal blocksize.
- If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.
- INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

sorgqr - generate an M-by-N real matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE SORGQR(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, K, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORGQR_64(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGQR(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORGQR_64(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK],  
[INFO])
```

```
INTEGER(8) :: M, N, K, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorgqr(int m, int n, int k, float *a, int lda, float  
*tau, int *info);
```

```
void sorgqr_64(long m, long n, long k, float *a, long lda,  
float *tau, long *info);
```

PURPOSE

sorgqr generates an M-by-N real matrix Q with orthonormal columns, which is defined as the first N columns of a product of K elementary reflectors of order M

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGEQRF.

ARGUMENTS

M (input) The number of rows of the matrix Q. M \geq 0.

N (input) The number of columns of the matrix Q. M \geq N \geq 0.

K (input) The number of elementary reflectors whose product defines the matrix Q. N \geq K \geq 0.

A (input/output)

On entry, the i-th column must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by SGEQRF in the first k columns of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. LDA \geq max(1,M).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGEQRF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq max(1,N). For optimum performance LDWORK \geq N*NB, where NB is the optimal blocksize.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

sorgr2 - generate an m by n real matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE SORGR2(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER M, N, K, LDA, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORGR2_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGR2([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORGR2_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
INTEGER(8) :: M, N, K, LDA, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorgr2(int m, int n, int k, float *a, int lda, float  
          *tau, int *info);
```

```
void sorgr2_64(long m, long n, long k, float *a, long lda,  
             float *tau, long *info);
```

PURPOSE

sorgr2 generates an m by n real matrix Q with orthonormal rows, which is defined as the last m rows of a product of k elementary reflectors of order n

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGERQF.

ARGUMENTS

M (input) The number of rows of the matrix Q . $M \geq 0$.

N (input) The number of columns of the matrix Q . $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q . $M \geq K \geq 0$.

A (input/output)

On entry, the $(m-k+i)$ -th row must contain the vector which defines the elementary reflector $H(i)$, for $i = 1, 2, \dots, k$, as returned by SGERQF in the last k rows of its array argument A . On exit, the m by n matrix Q .

LDA (input)

The first dimension of the array A . $LDA \geq \max(1, M)$.

TAU (input)

$TAU(i)$ must contain the scalar factor of the elementary reflector $H(i)$, as returned by SGERQF.

WORK (workspace)

dimension(M)

INFO (output)

= 0: successful exit

< 0: if $INFO = -i$, the i -th argument has an illegal value

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NAME

sorghq - generate an M-by-N real matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE SORGRQ(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER M, N, K, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORGRQ_64(M, N, K, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
INTEGER*8 M, N, K, LDA, LDWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGRQ(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
INTEGER :: M, N, K, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORGRQ_64(M, [N], [K], A, [LDA], TAU, [WORK], [LDWORK],  
[INFO])
```

```
INTEGER(8) :: M, N, K, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorghq(int m, int n, int k, float *a, int lda, float  
*tau, int *info);
```

```
void sorghq_64(long m, long n, long k, float *a, long lda,  
float *tau, long *info);
```

PURPOSE

sorghq generates an M-by-N real matrix Q with orthonormal rows, which is defined as the last M rows of a product of K elementary reflectors of order N

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGERQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $M \geq K \geq 0$.

A (input/output)

On entry, the (m-k+i)-th row must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by SGERQF in the last k rows of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by SGERQF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, M)$. For optimum performance $LDWORK \geq M \cdot NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

sorgtr - generate a real orthogonal matrix Q which is defined as the product of n-1 elementary reflectors of order N, as returned by SSYTRD

SYNOPSIS

```
SUBROUTINE SORGTR(UPLO, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, LWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE SORGTR_64(UPLO, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, LWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORGTR(UPLO, [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE ORGTR_64(UPLO, [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sorgtr(char uplo, int n, float *a, int lda, float *tau,  
            int *info);
```

```
void sorgtr_64(char uplo, long n, float *a, long lda, float
```

```
*tau, long *info);
```

PURPOSE

sorgtr generates a real orthogonal matrix Q which is defined as the product of $n-1$ elementary reflectors of order N , as returned by SSYTRD:

if UPLO = 'U', $Q = H(n-1) \dots H(2) H(1)$,

if UPLO = 'L', $Q = H(1) H(2) \dots H(n-1)$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A contains elementary reflectors from SSYTRD; = 'L': Lower triangle of A contains elementary reflectors from SSYTRD.

N (input) The order of the matrix Q . $N \geq 0$.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by SSYTRD. On exit, the N -by- N orthogonal matrix Q .

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by SSYTRD.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1, N-1)$. For optimum performance $LWORK \geq (N-1)*NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = - i , the i -th argument had an illegal value

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NAME

sormbr - VECT = 'Q', SORMBR overwrites the general real M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE SORMBR(VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC,
                 WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT, SIDE, TRANS
INTEGER M, N, K, LDA, LDC, LWORK, INFO
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SORMBR_64(VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC,
                    WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT, SIDE, TRANS
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMBR(VECT, SIDE, [TRANS], [M], [N], K, A, [LDA], TAU, C,
                [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, SIDE, TRANS
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
REAL, DIMENSION(:) :: TAU, WORK
REAL, DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMBR_64(VECT, SIDE, [TRANS], [M], [N], K, A, [LDA], TAU,
                   C, [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, SIDE, TRANS
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
REAL, DIMENSION(:) :: TAU, WORK
REAL, DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sormbr(char vect, char side, char trans, int m, int n,
```

```

        int k, float *a, int lda, float *tau, float *c,
        int ldc, int *info);

void sormbr_64(char vect, char side, char trans, long m,
              long n, long k, float *a, long lda, float *tau,
              float *c, long ldc, long *info);

```

PURPOSE

sormbr VECT = 'Q', SORMBR overwrites the general real M-by-N matrix C with

```

                SIDE = 'L'      SIDE = 'R'  TRANS = 'N':
Q * C          C * Q TRANS = 'T':      Q**T * C      C *
Q**T

```

If VECT = 'P', SORMBR overwrites the general real M-by-N matrix C with

```

                SIDE = 'L'      SIDE = 'R'
TRANS = 'N':    P * C          C * P
TRANS = 'T':    P**T * C       C * P**T

```

Here Q and P**T are the orthogonal matrices determined by SGEHRD when reducing a real matrix A to bidiagonal form: $A = Q * B * P^{**T}$. Q and P**T are defined as products of elementary reflectors H(i) and G(i) respectively.

Let nq = m if SIDE = 'L' and nq = n if SIDE = 'R'. Thus nq is the order of the orthogonal matrix Q or P**T that is applied.

If VECT = 'Q', A is assumed to have been an NQ-by-K matrix:
if nq >= k, Q = H(1) H(2) . . . H(k);
if nq < k, Q = H(1) H(2) . . . H(nq-1).

If VECT = 'P', A is assumed to have been a K-by-NQ matrix:
if k < nq, P = G(1) G(2) . . . G(k);
if k >= nq, P = G(1) G(2) . . . G(nq-1).

ARGUMENTS

VECT (input)

```

= 'Q': apply Q or Q**T;
= 'P': apply P or P**T.

```

SIDE (input)

```

= 'L': apply Q, Q**T, P or P**T from the Left;
= 'R': apply Q, Q**T, P or P**T from the Right.

```

TRANS (input)

```

= 'N': No transpose, apply Q or P;
= 'T': Transpose, apply Q**T or P**T.

```

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) If VECT = 'Q', the number of columns in the original matrix reduced by SGEBRD. If VECT = 'P', the number of rows in the original matrix reduced by SGEBRD. $K \geq 0$.

A (input) (LDA,min(nq,K)) if VECT = 'Q' (LDA,nq) if VECT = 'P' The vectors which define the elementary reflectors H(i) and G(i), whose products determine the matrices Q and P, as returned by SGEBRD.

LDA (input)
The leading dimension of the array A. If VECT = 'Q', $LDA \geq \max(1,nq)$; if VECT = 'P', $LDA \geq \max(1,\min(nq,K))$.

TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector H(i) or G(i) which determines Q or P, as returned by SGEBRD in the array argument TAUQ or TAUP.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by $Q*C$ or $Q**T*C$ or $C*Q**T$ or $C*Q$ or $P*C$ or $P**T*C$ or $C*P$ or $C**T$.

LDC (input)
The leading dimension of the array C. $LDC \geq \max(1,M)$.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. If SIDE = 'L', $LWORK \geq \max(1,N)$; if SIDE = 'R', $LWORK \geq \max(1,M)$. For optimum performance $LWORK \geq N*NB$ if SIDE = 'L', and $LWORK \geq M*NB$ if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sormhr - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE SORMHR(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C, LDC,  
                WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, ILO, IHI, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SORMHR_64(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C,  
                   LDC, WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, ILO, IHI, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMHR(SIDE, [TRANS], [M], [N], ILO, IHI, A, [LDA], TAU, C,  
                [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, ILO, IHI, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMHR_64(SIDE, [TRANS], [M], [N], ILO, IHI, A, [LDA], TAU,  
                   C, [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, ILO, IHI, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sormhr(char side, char trans, int m, int n, int ilo,
```

```

        int ihi, float *a, int lda, float *tau, float *c,
        int ldc, int *info);

void sormhr_64(char side, char trans, long m, long n, long
        ilo, long ihi, float *a, long lda, float *tau,
        float *c, long ldc, long *info);

```

PURPOSE

sormhr overwrites the general real M-by-N matrix C with
 TRANS = 'T': $Q^{*T} * C$ $C * Q^{*T}$

where Q is a real orthogonal matrix of order nq, with nq = m
 if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
 product of IHI-ILO elementary reflectors, as returned by
 SGEHRD:

$Q = H(ilo) H(ilo+1) . . . H(ihi-1).$

ARGUMENTS

SIDE (input)
 = 'L': apply Q or Q**T from the Left;
 = 'R': apply Q or Q**T from the Right.

TRANS (input)
 = 'N': No transpose, apply Q;
 = 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

ILO (input)
 ILO and IHI must have the same values as in the
 previous call of SGEHRD. Q is equal to the unit
 matrix except in the submatrix
 $Q(ilo+1:ihi,ilo+1:ihi)$. If SIDE = 'L', then $1 \leq$
 $ILO \leq IHI \leq M$, if M > 0, and ILO = 1 and IHI =
 0, if M = 0; if SIDE = 'R', then $1 \leq ILO \leq IHI$
 $\leq N$, if N > 0, and ILO = 1 and IHI = 0, if N = 0.

IHI (input)
 See the description of ILO.

A (input) (LDA,M) if SIDE = 'L' (LDA,N) if SIDE = 'R' The
 vectors which define the elementary reflectors, as
 returned by SGEHRD.

LDA (input)
 The leading dimension of the array A. LDA >=
 $\max(1,M)$ if SIDE = 'L'; LDA >= $\max(1,N)$ if SIDE =
 'R'.

TAU (input)
 (M-1) if SIDE = 'L' (N-1) if SIDE = 'R' TAU(i)
 must contain the scalar factor of the elementary
 reflector H(i), as returned by SGEHRD.

C (input/output)
 On entry, the M-by-N matrix C. On exit, C is
 overwritten by Q*C or Q**T*C or C*Q**T or C*Q.

LDC (input)
 The leading dimension of the array C. LDC >=
 max(1,M).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal
 LWORK.

LWORK (input)
 The dimension of the array WORK. If SIDE = 'L',
 LWORK >= max(1,N); if SIDE = 'R', LWORK >=
 max(1,M). For optimum performance LWORK >= N*NB
 if SIDE = 'L', and LWORK >= M*NB if SIDE = 'R',
 where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the WORK array, returns this value as the first
 entry of the WORK array, and no error message
 related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-
 gal value

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NAME

sormlq - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE SORMLQ(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SORMLQ_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMLQ(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMLQ_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sormlq(char side, char trans, int m, int n, int k,
```

```

float *a, int lda, float *tau, float *c, int ldc,
int *info);

void sormlq_64(char side, char trans, long m, long n, long
k, float *a, long lda, float *tau, float *c, long
ldc, long *info);

```

PURPOSE

sormlq overwrites the general real M-by-N matrix C with
TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix defined as the product
of k elementary reflectors

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGELQF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
= 'R': apply Q or Q**T from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', M >= K >= 0;
if SIDE = 'R', N >= K >= 0.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
i-th row must contain the vector which defines the
elementary reflector H(i), for i = 1,2,...,k, as
returned by SGELQF in the first k rows of its
array argument A. A is modified by the routine
but restored on exit.

LDA (input)

The leading dimension of the array A. LDA >=
max(1,K).

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by SGELQF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sormql - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE SORMQL(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SORMQL_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMQL(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:, :) :: A, C
```

```
SUBROUTINE ORMQL_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:, :) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sormql(char side, char trans, int m, int n, int k,
```

```

float *a, int lda, float *tau, float *c, int ldc,
int *info);

void sormql_64(char side, char trans, long m, long n, long
k, float *a, long lda, float *tau, float *c, long
ldc, long *info);

```

PURPOSE

sormql overwrites the general real M-by-N matrix C with
TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix defined as the product
of k elementary reflectors

$$Q = H(k) \dots H(2) H(1)$$

as returned by SGEQLF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
= 'R': apply Q or Q**T from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', M >= K >= 0;
if SIDE = 'R', N >= K >= 0.

A (input) The i-th column must contain the vector which
defines the elementary reflector H(i), for i =
1,2,...,k, as returned by SGEQLF in the last k
columns of its array argument A. A is modified by
the routine but restored on exit.

LDA (input)

The leading dimension of the array A. If SIDE =
'L', LDA >= max(1,M); if SIDE = 'R', LDA >=
max(1,N).

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by SGEQLF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. $LDC \geq \max(1, M)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $SIDE = 'L'$, $LWORK \geq \max(1, N)$; if $SIDE = 'R'$, $LWORK \geq \max(1, M)$. For optimum performance $LWORK \geq N*NB$ if $SIDE = 'L'$, and $LWORK \geq M*NB$ if $SIDE = 'R'$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

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NAME

sormqr - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE SORMQR(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SORMQR_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMQR(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMQR_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sormqr(char side, char trans, int m, int n, int k,
```

```

float *a, int lda, float *tau, float *c, int ldc,
int *info);

void sormqr_64(char side, char trans, long m, long n, long
k, float *a, long lda, float *tau, float *c, long
ldc, long *info);

```

PURPOSE

sormqr overwrites the general real M-by-N matrix C with
TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix defined as the product
of k elementary reflectors

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGEQRF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
= 'R': apply Q or Q**T from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', M >= K >= 0;
if SIDE = 'R', N >= K >= 0.

A (input) The i-th column must contain the vector which
defines the elementary reflector H(i), for i =
1,2,...,k, as returned by SGEQRF in the first k
columns of its array argument A. A is modified by
the routine but restored on exit.

LDA (input)

The leading dimension of the array A. If SIDE =
'L', LDA >= max(1,M); if SIDE = 'R', LDA >=
max(1,N).

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by SGEQRF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sormrq - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE SORMRQ(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SORMRQ_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMQRQ(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMQRQ_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sormrq(char side, char trans, int m, int n, int k,
```

```

float *a, int lda, float *tau, float *c, int ldc,
int *info);

void sormrq_64(char side, char trans, long m, long n, long
k, float *a, long lda, float *tau, float *c, long
ldc, long *info);

```

PURPOSE

sormrq overwrites the general real M-by-N matrix C with
TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix defined as the product
of k elementary reflectors

$$Q = H(1) H(2) \dots H(k)$$

as returned by SGERQF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
= 'R': apply Q or Q**T from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', M >= K >= 0;
if SIDE = 'R', N >= K >= 0.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
i-th row must contain the vector which defines the
elementary reflector H(i), for i = 1,2,...,k, as
returned by SGERQF in the last k rows of its array
argument A. A is modified by the routine but
restored on exit.

LDA (input)

The leading dimension of the array A. LDA >=
max(1,K).

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by SGERQF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sormrz - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE SORMRZ(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC, WORK,  
                LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER M, N, K, L, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SORMRZ_64(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC,  
                   WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
INTEGER*8 M, N, K, L, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMZRZ(SIDE, TRANS, [M], [N], K, L, A, [LDA], TAU, C, [LDC],  
                [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER :: M, N, K, L, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMZRZ_64(SIDE, TRANS, [M], [N], K, L, A, [LDA], TAU, C,  
                   [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
INTEGER(8) :: M, N, K, L, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sormrz(char side, char trans, int m, int n, int k, int
           l, float *a, int lda, float *tau, float *c, int
           ldc, int *info);
```

```
void sormrz_64(char side, char trans, long m, long n, long
              k, long l, float *a, long lda, float *tau, float
              *c, long ldc, long *info);
```

PURPOSE

sormrz overwrites the general real M-by-N matrix C with
 TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix defined as the product
 of k elementary reflectors

$$Q = H(1) H(2) \dots H(k)$$

as returned by STZRZF. Q is of order M if SIDE = 'L' and of
 order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
 = 'R': apply Q or Q**T from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
 = 'T': Transpose, apply Q**T.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
 defines the matrix Q. If SIDE = 'L', M >= K >= 0;
 if SIDE = 'R', N >= K >= 0.

L (input) The number of columns of the matrix A containing
 the meaningful part of the Householder reflectors.
 If SIDE = 'L', M >= L >= 0, if SIDE = 'R', N >= L
 >= 0.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
 i-th row must contain the vector which defines the
 elementary reflector H(i), for i = 1,2,...,k, as
 returned by STZRZF in the last k rows of its array
 argument A. A is modified by the routine but
 restored on exit.

LDA (input)

The leading dimension of the array A. LDA >=
 max(1,K).

TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by STZRZF.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by Q*C or Q**H*C or C*Q**H or C*Q.

LDC (input)
The leading dimension of the array C. LDC >= max(1,M).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. If SIDE = 'L', LWORK >= max(1,N); if SIDE = 'R', LWORK >= max(1,M). For optimum performance LWORK >= N*NB if SIDE = 'L', and LWORK >= M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by
A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

sormtr - overwrite the general real M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE SORMTR(SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
INTEGER M, N, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

```
SUBROUTINE SORMTR_64(SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
INTEGER*8 M, N, LDA, LDC, LWORK, INFO  
REAL A(LDA,*), TAU(*), C(LDC,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ORMTR(SIDE, UPLO, [TRANS], [M], [N], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
INTEGER :: M, N, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

```
SUBROUTINE ORMTR_64(SIDE, UPLO, [TRANS], [M], [N], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
INTEGER(8) :: M, N, LDA, LDC, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,:) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sormtr(char side, char uplo, char trans, int m, int n,
```

```

float *a, int lda, float *tau, float *c, int ldc,
int *info);

void sormtr_64(char side, char uplo, char trans, long m,
long n, float *a, long lda, float *tau, float *c,
long ldc, long *info);

```

PURPOSE

sormtr overwrites the general real M-by-N matrix C with
TRANS = 'T': $Q^{**T} * C$ $C * Q^{**T}$

where Q is a real orthogonal matrix of order nq, with nq = m
if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
product of nq-1 elementary reflectors, as returned by
SSYTRD:

if UPLO = 'U', Q = H(nq-1) . . . H(2) H(1);

if UPLO = 'L', Q = H(1) H(2) . . . H(nq-1).

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**T from the Left;
= 'R': apply Q or Q**T from the Right.

UPLO (input)

= 'U': Upper triangle of A contains elementary
reflectors from SSYTRD; = 'L': Lower triangle of A
contains elementary reflectors from SSYTRD.

TRANS (input)

= 'N': No transpose, apply Q;
= 'T': Transpose, apply Q**T.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

A (input) (LDA,M) if SIDE = 'L' (LDA,N) if SIDE = 'R' The
vectors which define the elementary reflectors, as
returned by SSYTRD.

LDA (input)

The leading dimension of the array A. LDA >=
max(1,M) if SIDE = 'L'; LDA >= max(1,N) if SIDE =
'R'.

TAU (input)

(M-1) if SIDE = 'L' (N-1) if SIDE = 'R' TAU(i)
must contain the scalar factor of the elementary
reflector H(i), as returned by SSYTRD.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**T}C$ or C^*Q^{**T} or C^*Q .

LDC (input)

The leading dimension of the array C. $LDC \geq \max(1,M)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LWORK$.

LWORK (input)

The dimension of the array WORK. If $SIDE = 'L'$, $LWORK \geq \max(1,N)$; if $SIDE = 'R'$, $LWORK \geq \max(1,M)$. For optimum performance $LWORK \geq N*NB$ if $SIDE = 'L'$, and $LWORK \geq M*NB$ if $SIDE = 'R'$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to $LWORK$ is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if $INFO = -i$, the i-th argument had an illegal value

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NAME

spbcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite band matrix using the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ computed by SPBTRF

SYNOPSIS

```
SUBROUTINE SPBCON(UPLO, N, KD, A, LDA, ANORM, RCOND, WORK, WORK2,
                 INFO)
```

```
CHARACTER * 1 UPLO
INTEGER N, KD, LDA, INFO
INTEGER WORK2(*)
REAL ANORM, RCOND
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE SPBCON_64(UPLO, N, KD, A, LDA, ANORM, RCOND, WORK,
                    WORK2, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER*8 N, KD, LDA, INFO
INTEGER*8 WORK2(*)
REAL ANORM, RCOND
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PBCON(UPLO, [N], KD, A, [LDA], ANORM, RCOND, [WORK],
                [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER :: N, KD, LDA, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:,:) :: A
```

```
SUBROUTINE PBCON_64(UPLO, [N], KD, A, [LDA], ANORM, RCOND, [WORK],
                   [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

INTEGER(8) :: N, KD, LDA, INFO
INTEGER(8), DIMENSION(:) :: WORK2
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:,:) :: A
C INTERFACE
#include <sunperf.h>

void spbcon(char uplo, int n, int kd, float *a, int lda,
            float anorm, float *rcond, int *info);

void spbcon_64(char uplo, long n, long kd, float *a, long
               lda, float anorm, float *rcond, long *info);

```

PURPOSE

spbcon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite band matrix using the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ computed by SPBTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangular factor stored in A;
 = 'L': Lower triangular factor stored in A.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ of the band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of U or L is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = U(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = L(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

LDA (input)
 The leading dimension of the array A. $LDA \geq KD+1$.

ANORM (input)
 The 1-norm (or infinity-norm) of the symmetric band matrix A.

RCOND (output)
 The reciprocal of the condition number of the

matrix A, computed as $RCOND = 1/(ANORM * AINVNM)$,
where AINVNM is an estimate of the 1-norm of
inv(A) computed in this routine.

WORK (workspace)
dimension(3*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

spbequ - compute row and column scalings intended to equilibrate a symmetric positive definite band matrix A and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE SPBEQU(UPLO, N, KD, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, LDA, INFO  
REAL SCOND, AMAX  
REAL A(LDA,*), SCALE(*)
```

```
SUBROUTINE SPBEQU_64(UPLO, N, KD, A, LDA, SCALE, SCOND, AMAX,  
INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, LDA, INFO  
REAL SCOND, AMAX  
REAL A(LDA,*), SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE PBEQU(UPLO, [N], KD, A, [LDA], SCALE, SCOND, AMAX,  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, LDA, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: SCALE  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE PBEQU_64(UPLO, [N], KD, A, [LDA], SCALE, SCOND, AMAX,  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, LDA, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: SCALE  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>

void spbequ(char uplo, int n, int kd, float *a, int lda,
            float *scale, float *scond, float *amax, int
            *info);
void spbequ_64(char uplo, long n, long kd, float *a, long
               lda, float *scale, float *scond, float *amax, long
               *info);
```

PURPOSE

spbequ computes row and column scalings intended to equilibrate a symmetric positive definite band matrix A and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i) = 1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j) = S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

UPLO (input)
= 'U': Upper triangular of A is stored;
= 'L': Lower triangular of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input) The upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$.

LDA (input)
The leading dimension of the array A. $LDA \geq KD+1$.

SCALE (output)
If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)
If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

spbrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and banded, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE SPBRFS(UPLO, N, KD, NRHS, A, LDA, AF, LDAF, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER WORK2(*)  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE SPBRFS_64(UPLO, N, KD, NRHS, A, LDA, AF, LDAF, B, LDB,  
  X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PBRFS(UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF], B,  
  [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL, DIMENSION(:) :: FERR, BERR, WORK  
REAL, DIMENSION(:,:) :: A, AF, B, X
```

```
SUBROUTINE PBRFS_64(UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF],  
  B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
```

```
INTEGER(8), DIMENSION(:) :: WORK2
REAL, DIMENSION(:) :: FERR, BERR, WORK
REAL, DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
void spbrfs(char uplo, int n, int kd, int nrhs, float *a,
            int lda, float *af, int ldaf, float *b, int ldb,
            float *x, int ldx, float *ferr, float *berr, int
            *info);

void spbrfs_64(char uplo, long n, long kd, long nrhs, float
               *a, long lda, float *af, long ldaf, float *b, long
               ldb, float *x, long ldx, float *ferr, float *berr,
               long *info);
```

PURPOSE

spbrfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and banded, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number
of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The upper or lower triangle of the symmetric band
matrix A, stored in the first $KD+1$ rows of the
array. The j-th column of A is stored in the j-th
column of the array A as follows: if UPLO = 'U',
 $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if
UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for
 $j \leq i \leq \min(n, j+kd)$.

LDA (input)
The leading dimension of the array A. $LDA \geq$
 $KD+1$.

AF (input)
The triangular factor U or L from the Cholesky
factorization $A = U^*T^*U$ or $A = L^*L^*T$ of the band
matrix A as computed by SPBTRF, in the same
storage format as A (see A).

LDAF (input)
The leading dimension of the array AF. LDAF \geq KD+1.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by SPBTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
dimension(3*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

spbstf - compute a split Cholesky factorization of a real symmetric positive definite band matrix A

SYNOPSIS

```
SUBROUTINE SPBSTF(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, LDAB, INFO  
REAL AB(LDAB,*)
```

```
SUBROUTINE SPBSTF_64(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, LDAB, INFO  
REAL AB(LDAB,*)
```

F95 INTERFACE

```
SUBROUTINE PBSTF(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, LDAB, INFO  
REAL, DIMENSION(:, :) :: AB
```

```
SUBROUTINE PBSTF_64(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, LDAB, INFO  
REAL, DIMENSION(:, :) :: AB
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spbstf(char uplo, int n, int kd, float *ab, int ldab,  
            int *info);
```

```
void spbstf_64(char uplo, long n, long kd, float *ab, long  
               ldab, long *info);
```

PURPOSE

spbstf computes a split Cholesky factorization of a real symmetric positive definite band matrix A.

This routine is designed to be used in conjunction with SSBGST.

The factorization has the form $A = S^*T^*S$ where S is a band matrix of the same bandwidth as A and the following structure:

$$S = \begin{pmatrix} U & \\ & (M \ L) \end{pmatrix}$$

where U is upper triangular of order $m = (n+kd)/2$, and L is lower triangular of order $n-m$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $kd+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if
UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$
for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the factor S from the split Cholesky factorization $A = S^*T^*S$. See Further Details.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq kd+1$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the factorization could not be completed, because the updated element $a(i, i)$ was negative; the matrix A is not positive definite.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 7$, $KD = 2$:

```
S = ( s11  s12  s13           )
     (      s22  s23  s24       )
     (           s33  s34       )
     (           s44           )
     (           s53  s54  s55   )
     (           s64  s65  s66   )
     (           s75  s76  s77 )
```

If $UPLO = 'U'$, the array AB holds:

```
on entry:                                on exit:

*      *  a13  a24  a35  a46  a57  *      *  s13  s24  s53
s64  s75
*      a12  a23  a34  a45  a56  a67  *      s12  s23  s34  s54
s65  s76  a11  a22  a33  a44  a55  a66  a77  s11  s22  s33
s44  s55  s66  s77
```

If $UPLO = 'L'$, the array AB holds:

```
on entry:                                on exit:

a11  a22  a33  a44  a55  a66  a77  s11  s22  s33  s44  s55
s66  s77  a21  a32  a43  a54  a65  a76  *  s12  s23  s34
s54  s65  s76  *  a31  a42  a53  a64  a64  *      *  s13
s24  s53  s64  s75  *      *
```

Array elements marked * are not used by the routine.

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NAME

spbsv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SPBSV(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SPBSV_64(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PBSV(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE PBSV_64(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spbsv(char uplo, int n, int kd, int nrhs, float *a, int  
lda, float *b, int ldb, int *info);
```

```
void spbsv_64(char uplo, long n, long kd, long nrhs, float
```

```
*a, long lda, float *b, long ldb, long *info);
```

PURPOSE

spbsv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric positive definite band matrix and X and B are N-by-NRHS matrices.

The Cholesky decomposition is used to factor A as

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular band matrix, and L is a lower triangular band matrix, with the same number of superdiagonals or subdiagonals as A. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(KD+1+i-j,j) = A(i,j)$ for $\max(1,j-KD) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(N,j+KD)$. See below for further details.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ of the band matrix A, in the same storage format as A.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when N = 6, KD = 2, and UPLO = 'U':

On entry:	On exit:
* * a13 a24 a35 a46	* * u13 u24 u35
u46	
* a12 a23 a34 a45 a56	* u12 u23 u34 u45
u56	
a11 a22 a33 a44 a55 a66	u11 u22 u33 u44 u55
u66	

Similarly, if UPLO = 'L' the format of A is as follows:

On entry:	On exit:
a11 a22 a33 a44 a55 a66	l11 l22 l33 l44 l55
l66	
a21 a32 a43 a54 a65 *	l21 l32 l43 l54 l65
*	
a31 a42 a53 a64 * *	l31 l42 l53 l64 *
*	

Array elements marked * are not used by the routine.

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NAME

spbsvx - use the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SPBSVX(FACT, UPLO, N, KD, NRHS, A, LDA, AF, LDAF,
    EQUED, S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2,
    INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
INTEGER N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER WORK2(*)
REAL RCOND
REAL A(LDA,*), AF(LDAF,*), S(*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE SPBSVX_64(FACT, UPLO, N, KD, NRHS, A, LDA, AF, LDAF,
    EQUED, S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2,
    INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
INTEGER*8 N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 WORK2(*)
REAL RCOND
REAL A(LDA,*), AF(LDAF,*), S(*), B(LDB,*), X(LDX,*),
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PBSVX(FACT, UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF],
    EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],
    [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
INTEGER :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: S, FERR, BERR, WORK
```

```

REAL, DIMENSION(:, :) :: A, AF, B, X

SUBROUTINE PBSVX_64(FACT, UPLO, [N], KD, [NRHS], A, [LDA], AF,
  [LDAF], EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR,
  [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, UPLO, EQUED
INTEGER(8) :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: S, FERR, BERR, WORK
REAL, DIMENSION(:, :) :: A, AF, B, X

```

C INTERFACE

```

#include <sunperf.h>

void spbsvx(char fact, char uplo, int n, int kd, int nrhs,
  float *a, int lda, float *af, int ldaf, char
  equed, float *s, float *b, int ldb, float *x, int
  ldx, float *rcond, float *ferr, float *berr, int
  *info);

void spbsvx_64(char fact, char uplo, long n, long kd, long
  nrhs, float *a, long lda, float *af, long ldaf,
  char equed, float *s, float *b, long ldb, float
  *x, long ldx, float *rcond, float *ferr, float
  *berr, long *info);

```

PURPOSE

spbsvx uses the Cholesky factorization $A = U^{*}T^{*}U$ or $A = L^{*}L^{*}T^{*}$ to compute the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric positive definite band matrix and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'E', real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A, but if equilibration is used, A is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If FACT = 'N' or 'E', the Cholesky decomposition is used to

factor the matrix A (after equilibration if FACT = 'E') as

$$A = U^{*}T^{*} * U, \text{ if UPLO} = 'U', \text{ or}$$

$$A = L * L^{*}T^{*}, \text{ if UPLO} = 'L',$$

where U is an upper triangular band matrix, and L is a lower

triangular band matrix.

3. If the leading i -by- i principal minor is not positive definite, then the routine returns with `INFO = i`. Otherwise, the factored form of A is used to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than machine precision, `INFO = N+1` is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
4. The system of equations is solved for X using the factored form of A .
5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.
6. If equilibration was used, the matrix X is premultiplied by `diag(S)` so that it solves the original system before equilibration.

ARGUMENTS

`FACT` (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored.

- = 'F': On entry, `AF` contains the factored form of A . If `EQUED = 'Y'`, the matrix A has been equilibrated with scaling factors given by S . A and `AF` will not be modified.
- = 'N': The matrix A will be copied to `AF` and factored.
- = 'E': The matrix A will be equilibrated if necessary, then copied to `AF` and factored.

`UPLO` (input)

- = 'U': Upper triangle of A is stored;
- = 'L': Lower triangle of A is stored.

`N` (input) The number of linear equations, i.e., the order of the matrix A . $N \geq 0$.

`KD` (input)

The number of superdiagonals of the matrix A if `UPLO = 'U'`, or the number of subdiagonals if `UPLO = 'L'`. $KD \geq 0$.

`NRHS` (input)

The number of right-hand sides, i.e., the number of columns of the matrices B and X . `NRHS` ≥ 0 .

`A` (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first KD+1 rows of the array, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix $\text{diag}(S)*A*\text{diag}(S)$. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(KD+1+i-j,j) = A(i,j)$ for $\max(1,j-KD) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(N,j+KD)$. See below for further details.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S)*A*\text{diag}(S)$.

LDA (input)

The leading dimension of the array A. LDA \geq KD+1.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U**T*U$ or $A = L*L**T$ of the band matrix A, in the same storage format as A (see A). If EQUED = 'Y', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**T*U$ or $A = L*L**T$.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**T*U$ or $A = L*L**T$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF \geq KD+1.

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

X (output)
 If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is inv(diag(S))*X.

LDX (input)
 The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)
 The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(3*N)

WORK2 (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, and i is
 <= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is non-singular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would

suggest.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 6$, $KD = 2$, and $UPLO = 'U'$:

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13
      a22 a23 a24
            a33 a34 a35
                  a44 a45 a46
                        a55 a56
(aij=conjg(aji))          a66
```

Band storage of the upper triangle of A:

```
*      *   a13 a24 a35 a46
*   a12 a23 a34 a45 a56
a11 a22 a33 a44 a55 a66
```

Similarly, if $UPLO = 'L'$ the format of A is as follows:

```
a11 a22 a33 a44 a55 a66
a21 a32 a43 a54 a65 *
a31 a42 a53 a64 *  *
```

Array elements marked * are not used by the routine.

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NAME

spbtf2 - compute the Cholesky factorization of a real symmetric positive definite band matrix A

SYNOPSIS

```
SUBROUTINE SPBTF2(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, LDAB, INFO  
REAL AB(LDAB,*)
```

```
SUBROUTINE SPBTF2_64(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, LDAB, INFO  
REAL AB(LDAB,*)
```

F95 INTERFACE

```
SUBROUTINE PBTf2(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, LDAB, INFO  
REAL, DIMENSION(:, :) :: AB
```

```
SUBROUTINE PBTf2_64(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, LDAB, INFO  
REAL, DIMENSION(:, :) :: AB
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spbtf2(char uplo, int n, int kd, float *ab, int ldab,  
            int *info);
```

```
void spbtf2_64(char uplo, long n, long kd, float *ab, long  
               ldab, long *info);
```

PURPOSE

spbtf2 computes the Cholesky factorization of a real symmetric positive definite band matrix A.

The factorization has the form

$A = U' * U$, if UPLO = 'U', or

$A = L * L'$, if UPLO = 'L',

where U is an upper triangular matrix, U' is the transpose of U, and L is lower triangular.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored:

= 'U': Upper triangular

= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of super-diagonals of the matrix A if UPLO = 'U', or the number of sub-diagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U' * U$ or $A = L * L'$ of the band matrix A, in the same storage format as A.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq KD+1$.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, the leading minor of order k is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 6$, $KD = 2$, and $UPLD = 'U'$:

On entry:						On exit:				
* *	a13	a24	a35	a46		* *	u13	u24	u35	
u46										
* a12	a23	a34	a45	a56		* u12	u23	u34	u45	
u56										
a11	a22	a33	a44	a55	a66	u11	u22	u33	u44	u55
u66										

Similarly, if $UPLD = 'L'$ the format of A is as follows:

On entry:						On exit:				
a11	a22	a33	a44	a55	a66	l11	l22	l33	l44	l55
l66										
a21	a32	a43	a54	a65	*	l21	l32	l43	l54	l65
*										
a31	a42	a53	a64	*	*	l31	l42	l53	l64	*
*										

Array elements marked * are not used by the routine.

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NAME

spbtrf - compute the Cholesky factorization of a real symmetric positive definite band matrix A

SYNOPSIS

```
SUBROUTINE SPBTRF(UPLO, N, KD, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, LDA, INFO  
REAL A(LDA,*)
```

```
SUBROUTINE SPBTRF_64(UPLO, N, KD, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, LDA, INFO  
REAL A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE PBTRF(UPLO, [N], KD, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE PBTRF_64(UPLO, [N], KD, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spbtrf(char uplo, int n, int kd, float *a, int lda, int  
           *info);
```

```
void spbtrf_64(char uplo, long n, long kd, float *a, long  
              lda, long *info);
```

PURPOSE

spbtrf computes the Cholesky factorization of a real symmetric positive definite band matrix A.

The factorization has the form

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ of the band matrix A, in the same storage format as A.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The band storage scheme is illustrated by the following

example, when $N = 6$, $KD = 2$, and $UPLO = 'U'$:

On entry:	On exit:
* * a13 a24 a35 a46	* * u13 u24 u35
u46	
* a12 a23 a34 a45 a56	* u12 u23 u34 u45
u56	
a11 a22 a33 a44 a55 a66	u11 u22 u33 u44 u55
u66	

Similarly, if $UPLO = 'L'$ the format of A is as follows:

On entry:	On exit:
a11 a22 a33 a44 a55 a66	l11 l22 l33 l44 l55
l66	
a21 a32 a43 a54 a65 *	l21 l32 l43 l54 l65
*	
a31 a42 a53 a64 * *	l31 l42 l53 l64 *
*	

Array elements marked * are not used by the routine.

Contributed by

Peter Mayes and Giuseppe Radicati, IBM ECSEC, Rome, March
23, 1989

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NAME

spbtrs - solve a system of linear equations $A \cdot X = B$ with a symmetric positive definite band matrix A using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by SPBTRF

SYNOPSIS

```
SUBROUTINE SPBTRS(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, KD, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SPBTRS_64(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PBTRS(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE PBTRS_64(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spbtrs(char uplo, int n, int kd, int nrhs, float *a,  
int lda, float *b, int ldb, int *info);
```

```
void spbtrs_64(char uplo, long n, long kd, long nrhs, float  
*a, long lda, float *b, long ldb, long *info);
```

PURPOSE

spbtrs solves a system of linear equations $A \cdot X = B$ with a symmetric positive definite band matrix A using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by SPBTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular factor stored in A;
= 'L': Lower triangular factor stored in A.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number
of columns of the matrix B. $NRHS \geq 0$.

A (input) The triangular factor U or L from the Cholesky
factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ of the band
matrix A, stored in the first $KD+1$ rows of the
array. The j -th column of U or L is stored in the
 j -th column of the array A as follows: if UPLO
= 'U', $A(kd+1+i-j, j) = U(i, j)$ for $\max(1, j-
kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = L(i, j)$
for $j \leq i \leq \min(n, j+kd)$.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $KD+1$.

B (input/output)

On entry, the right hand side matrix B. On exit,
the solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq$
 $\max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

spocon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite matrix using the Cholesky factorization $A = U^{**T}U$ or $A = L^{**T}L$ computed by SPOTRF

SYNOPSIS

```
SUBROUTINE SPOCON(UPLO, N, A, LDA, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
INTEGER WORK2(*)  
REAL ANORM, RCOND  
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE SPOCON_64(UPLO, N, A, LDA, ANORM, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
INTEGER*8 WORK2(*)  
REAL ANORM, RCOND  
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE POCON(UPLO, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE POCON_64(UPLO, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO
```

```

INTEGER(8), DIMENSION(:) :: WORK2
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:, :) :: A

```

C INTERFACE

```

#include <sunperf.h>
void spocon(char uplo, int n, float *a, int lda, float
            anorm, float *rcond, int *info);

void spocon_64(char uplo, long n, float *a, long lda, float
              anorm, float *rcond, long *info);

```

PURPOSE

spocon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite matrix using the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ computed by SPOTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$, as computed by SPOTRF.

LDA (input)
 The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

ANORM (input)
 The 1-norm (or infinity-norm) of the symmetric matrix A.

RCOND (output)
 The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)
 dimension(3*N)

WORK2 (workspace)
 dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

spoequ - compute row and column scalings intended to equilibrate a symmetric positive definite matrix A and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE SPOEQU(N, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
INTEGER N, LDA, INFO  
REAL SCOND, AMAX  
REAL A(LDA,*), SCALE(*)
```

```
SUBROUTINE SPOEQU_64(N, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
INTEGER*8 N, LDA, INFO  
REAL SCOND, AMAX  
REAL A(LDA,*), SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE POEQU([N], A, [LDA], SCALE, SCOND, AMAX, [INFO])
```

```
INTEGER :: N, LDA, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: SCALE  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE POEQU_64([N], A, [LDA], SCALE, SCOND, AMAX, [INFO])
```

```
INTEGER(8) :: N, LDA, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: SCALE  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spoequ(int n, float *a, int lda, float *scale, float  
           *scond, float *amax, int *info);
```

```
void spoequ_64(long n, float *a, long lda, float *scale,
```

```
float *scond, float *amax, long *info);
```

PURPOSE

spoequ computes row and column scalings intended to equilibrate a symmetric positive definite matrix A and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i) = 1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j) = S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

A (input) The N-by-N symmetric positive definite matrix whose scaling factors are to be computed. Only the diagonal elements of A are referenced.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

SCALE (output)
If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)
If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)
Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

sporfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite,

SYNOPSIS

```
SUBROUTINE SPORFS(UPLO, N, NRHS, A, LDA, AF, LDAF, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER WORK2(*)  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE SPORFS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PORFS(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL, DIMENSION(:) :: FERR, BERR, WORK  
REAL, DIMENSION(:, :) :: A, AF, B, X
```

```
SUBROUTINE PORFS_64(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2
```

```
REAL, DIMENSION(:) :: FERR, BERR, WORK
REAL, DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
void sporfs(char uplo, int n, int nrhs, float *a, int lda,
            float *af, int ldaf, float *b, int ldb, float *x,
            int ldx, float *ferr, float *berr, int *info);

void sporfs_64(char uplo, long n, long nrhs, float *a, long
               lda, float *af, long ldaf, float *b, long ldb,
               float *x, long ldx, float *ferr, float *berr, long
               *info);
```

PURPOSE

sporfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)

The triangular factor U or L from the Cholesky factorization $A = U^*T*U$ or $A = L*L^*T$, as computed by SPOTRF.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by
SPOTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq
max(1,N).

FERR (output)
The estimated forward error bound for each solu-
tion vector X(j) (the j-th column of the solution
matrix X). If XTRUE is the true solution
corresponding to X(j), FERR(j) is an estimated
upper bound for the magnitude of the largest ele-
ment in (X(j) - XTRUE) divided by the magnitude of
the largest element in X(j). The estimate is as
reliable as the estimate for RCOND, and is almost
always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each
solution vector X(j) (i.e., the smallest relative
change in any element of A or B that makes X(j) an
exact solution).

WORK (workspace)
dimension(3*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an
illegal value

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NAME

sposv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SPOSV(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SPOSV_64(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE POSV(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE POSV_64(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sposv(char uplo, int n, int nrhs, float *a, int lda,  
           float *b, int ldb, int *info);
```

```
void sposv_64(char uplo, long n, long nrhs, float *a, long  
              lda, float *b, long ldb, long *info);
```

PURPOSE

sposv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric positive definite matrix and X and B are N-by-NRHS matrices.

The Cholesky decomposition is used to factor A as

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is a lower triangular matrix. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{**T} * U$ or $A = L * L^{**T}$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i of

A is not positive definite, so the factorization could not be completed, and the solution has not been computed.

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NAME

sposvx - use the Cholesky factorization $A = U^*T*U$ or $A = L*L^*T$ to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SPOSVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, EQUED,  
  S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER WORK2(*)  
REAL RCOND  
REAL A(LDA,*), AF(LDAF,*), S(*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE SPOSVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, EQUED,  
  S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
REAL RCOND  
REAL A(LDA,*), AF(LDAF,*), S(*), B(LDB,*), X(LDX,*),  
FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE POSVX(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],  
  EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],  
  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL :: RCOND  
REAL, DIMENSION(:) :: S, FERR, BERR, WORK  
REAL, DIMENSION(:, :) :: A, AF, B, X
```

```
SUBROUTINE POSVX_64(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],  
  EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],
```

```
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2  
REAL :: RCOND  
REAL, DIMENSION(:) :: S, FERR, BERR, WORK  
REAL, DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sposvx(char fact, char uplo, int n, int nrhs, float *a,  
            int lda, float *af, int ldaf, char equed, float  
            *s, float *b, int ldb, float *x, int ldx, float  
            *rcond, float *ferr, float *berr, int *info);
```

```
void sposvx_64(char fact, char uplo, long n, long nrhs,  
               float *a, long lda, float *af, long ldaf, char  
               equed, float *s, float *b, long ldb, float *x,  
               long ldx, float *rcond, float *ferr, float *berr,  
               long *info);
```

PURPOSE

sposvx uses the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ to compute the solution to a real system of linear equations

$A * X = B$, where A is an N -by- N symmetric positive definite matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$) as

$$A = U^*T^*U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L^*T, \text{ if } UPLO = 'L',$$

where U is an upper triangular matrix and L is a lower triangular matrix.

3. If the leading i -by- i principal minor is not positive definite,

then the routine returns with $INFO = i$. Otherwise, the

factored

form of A is used to estimate the condition number of the matrix

A. If the reciprocal of the condition number is less than machine

precision, INFO = N+1 is returned as a warning, but the routine

still goes on to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.

5. Iterative refinement is applied to improve the computed solution

matrix and calculate error bounds and backward error estimates for it.

6. If equilibration was used, the matrix X is premultiplied by

diag(S) so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF contains the factored form of A. If EQUED = 'Y', the matrix A has been equilibrated with scaling factors given by S. A and AF will not be modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)

On entry, the symmetric matrix A, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix diag(S)*A*diag(S). If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly

upper triangular part of A is not referenced. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S) * A * \text{diag}(S)$.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U * U^T$ or $A = L * L^T$, in the same storage format as A. If EQUED \neq 'N', then AF is the factored form of the equilibrated matrix $\text{diag}(S) * A * \text{diag}(S)$.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * U^T$ or $A = L * L^T$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * U^T$ or $A = L * L^T$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF \geq max(1,N).

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution

matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is $\text{inv}(\text{diag}(S)) * X$.

LDX (input)

The leading dimension of the array X. $\text{LDX} \geq \max(1, N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if $\text{RCOND} = 0$), the matrix is singular to working precision. This condition is indicated by a return code of $\text{INFO} > 0$.

FERR (output)

The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If XTRUE is the true solution corresponding to $X(j)$, $\text{FERR}(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - \text{XTRUE})$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value
> 0: if $\text{INFO} = i$, and i is
<= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. $\text{RCOND} = 0$ is returned. = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

spotf2 - compute the Cholesky factorization of a real symmetric positive definite matrix A

SYNOPSIS

```
SUBROUTINE SPOTF2(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
REAL A(LDA,*)
```

```
SUBROUTINE SPOTF2_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
REAL A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE POTF2(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE POTF2_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spotf2(char uplo, int n, float *a, int lda, int *info);
```

```
void spotf2_64(char uplo, long n, float *a, long lda, long  
*info);
```

PURPOSE

spotf2 computes the Cholesky factorization of a real symmetric positive definite matrix A.

The factorization has the form

$A = U' * U$, if UPLO = 'U', or

$A = L * L'$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored. = 'U':

Upper triangular

= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading n by n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n by n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U' * U$ or $A = L * L'$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, the leading minor of order k is not positive definite, and the factorization could not be completed.

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NAME

spotrf - compute the Cholesky factorization of a real symmetric positive definite matrix A

SYNOPSIS

```
SUBROUTINE SPOTRF(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
REAL A(LDA,*)
```

```
SUBROUTINE SPOTRF_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
REAL A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE POTRF(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE POTRF_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spotrf(char uplo, int n, float *a, int lda, int *info);
```

```
void spotrf_64(char uplo, long n, float *a, long lda, long  
*info);
```

PURPOSE

spotrf computes the Cholesky factorization of a real symmetric positive definite matrix A.

The factorization has the form

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

This is the block version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

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NAME

spotri - compute the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^{**}T$ computed by SPOTRF

SYNOPSIS

```
SUBROUTINE SPOTRI(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
REAL A(LDA,*)
```

```
SUBROUTINE SPOTRI_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
REAL A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE POTRI(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE POTRI_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spotri(char uplo, int n, float *a, int lda, int *info);
```

```
void spotri_64(char uplo, long n, float *a, long lda, long  
*info);
```

PURPOSE

spotri computes the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by SPOTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$, as computed by SPOTRF. On exit, the upper or lower triangle of the (symmetric) inverse of A, overwriting the input factor U or L.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, the (i,i) element of the factor U or L is zero, and the inverse could not be computed.

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NAME

spotrs - solve a system of linear equations $A \cdot X = B$ with a symmetric positive definite matrix A using the Cholesky factorization $A = U \cdot U^T \cdot U$ or $A = L \cdot L^T \cdot L$ computed by SPOTRF

SYNOPSIS

```
SUBROUTINE SPOTRS(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SPOTRS_64(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE POTRS(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE POTRS_64(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spotrs(char uplo, int n, int nrhs, float *a, int lda,  
            float *b, int ldb, int *info);
```

```
void spotrs_64(char uplo, long n, long nrhs, float *a, long  
              lda, float *b, long ldb, long *info);
```

PURPOSE

spotrs solves a system of linear equations $A \cdot X = B$ with a symmetric positive definite matrix A using the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$ computed by SPOTRF.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U \cdot U^T$ or $A = L \cdot L^T$, as computed by SPOTRF.

LDA (input)
The leading dimension of the array A . $LDA \geq \max(1, N)$.

B (input/output)
On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)
The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)
= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

sppcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite packed matrix using the Cholesky factorization $A = U^*T*U$ or $A = L*L^*T$ computed by SPPTRF

SYNOPSIS

```
SUBROUTINE SPPCON(UPLO, N, A, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
INTEGER WORK2(*)  
REAL ANORM, RCOND  
REAL A(*), WORK(*)
```

```
SUBROUTINE SPPCON_64(UPLO, N, A, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
INTEGER*8 WORK2(*)  
REAL ANORM, RCOND  
REAL A(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PPCON(UPLO, [N], A, ANORM, RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: A, WORK
```

```
SUBROUTINE PPCON_64(UPLO, [N], A, ANORM, RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: WORK2  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: A, WORK
```

C INTERFACE

```
#include <sunperf.h>

void sppcon(char uplo, int n, float *a, float anorm, float
            *rcond, int *info);
void sppcon_64(char uplo, long n, float *a, float anorm,
              float *rcond, long *info);
```

PURPOSE

sppcon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite packed matrix using the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$ computed by SPPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) REAL array, dimension $(N*(N+1)/2)$

The triangular factor U or L from the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T$, packed columnwise in a linear array. The j-th column of U or L is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = U(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = L(i,j)$ for $j \leq i \leq n$.

ANORM (input)

The 1-norm (or infinity-norm) of the symmetric matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

REAL array, WORK (workspace)

dimension(3*N)

WORK2 (workspace)

INTEGER array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sppequ - compute row and column scalings intended to equilibrate a symmetric positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE SPPEQU(UPLO, N, A, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
REAL SCOND, AMAX  
REAL A(*), SCALE(*)
```

```
SUBROUTINE SPPEQU_64(UPLO, N, A, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
REAL SCOND, AMAX  
REAL A(*), SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE PPEQU(UPLO, [N], A, SCALE, SCOND, AMAX, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: A, SCALE
```

```
SUBROUTINE PPEQU_64(UPLO, [N], A, SCALE, SCOND, AMAX, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
REAL :: SCOND, AMAX  
REAL, DIMENSION(:) :: A, SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sppequ(char uplo, int n, float *a, float *scale, float
```

```

        *scond, float *amax, int *info);

void sppequ_64(char uplo, long n, float *a, float *scale,
              float *scond, float *amax, long *info);

```

PURPOSE

sppequ computes row and column scalings intended to equilibrate a symmetric positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i)=1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j)=S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) REAL array, dimension $(N*(N+1)/2)$

The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

SCALE (output) REAL array, dimension (N)

If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)

If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, the i-th diagonal element is nonpositive.

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spprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE SPPRFS(UPLO, N, NRHS, A, AF, B, LDB, X, LDX, FERR, BERR,  
                WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, LDX, INFO  
INTEGER WORK2(*)  
REAL A(*), AF(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),  
WORK(*)
```

```
SUBROUTINE SPPRFS_64(UPLO, N, NRHS, A, AF, B, LDB, X, LDX, FERR,  
                   BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
REAL A(*), AF(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PPRFS(UPLO, [N], [NRHS], A, AF, B, [LDB], X, [LDX], FERR,  
                BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL, DIMENSION(:) :: A, AF, FERR, BERR, WORK  
REAL, DIMENSION(:,) :: B, X
```

```
SUBROUTINE PPRFS_64(UPLO, [N], [NRHS], A, AF, B, [LDB], X, [LDX], FERR,  
                   BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

```

INTEGER(8), DIMENSION(:) :: WORK2
REAL, DIMENSION(:) :: A, AF, FERR, BERR, WORK
REAL, DIMENSION(:, :) :: B, X

```

C INTERFACE

```

#include <sunperf.h>
void spprfs(char uplo, int n, int nrhs, float *a, float *af,
            float *b, int ldb, float *x, int ldx, float *ferr,
            float *berr, int *info);

void spprfs_64(char uplo, long n, long nrhs, float *a, float
               *af, float *b, long ldb, float *x, long ldx, float
               *ferr, float *berr, long *info);

```

PURPOSE

spprfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) REAL array, dimension $(N*(N+1)/2)$
 The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i, j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i, j)$ for $j \leq i \leq n$.

AF (input) REAL array, dimension $(N*(N+1)/2)$
 The triangular factor U or L from the Cholesky factorization $A = U**T*U$ or $A = L*L**T$, as computed by SPSTRF/CPSTRF, packed columnwise in a linear array in the same format as A (see A).

B (input) REAL array, dimension $(LDB, NRHS)$
 The right hand side matrix B.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (input/output) REAL array, dimension $(LDX, NRHS)$
 On entry, the solution matrix X, as computed by

SPPTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output) REAL array, dimension (NRHS)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) REAL array, dimension (NRHS)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

REAL array, dimension(3*N)

WORK2 (workspace)

INTEGER array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sppsv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SPPSV(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, INFO  
REAL A(*), B(LDB,*)
```

```
SUBROUTINE SPPSV_64(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, INFO  
REAL A(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PPSV(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: A  
REAL, DIMENSION(:,) :: B
```

```
SUBROUTINE PPSV_64(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: A  
REAL, DIMENSION(:,) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sppsv(char uplo, int n, int nrhs, float *a, float *b,  
           int ldb, int *info);
```

```
void sppsv_64(char uplo, long n, long nrhs, float *a, float
             *b, long ldb, long *info);
```

PURPOSE

sppsv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric positive definite matrix stored in packed format and X and B are N-by-NRHS matrices.

The Cholesky decomposition is used to factor A as

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is a lower triangular matrix. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output) REAL array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{**T} * U$ or $A = L * L^{**T}$, in the same storage format as A.

B (input/output) REAL array, dimension (LDB, NRHS)

On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-

gal value
> 0: if INFO = i, the leading minor of order i of
A is not positive definite, so the factorization
could not be completed, and the solution has not
been computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following
example when $N = 4$, $UPLO = 'U'$:

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34   (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

```
A = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

sppsvx - use the Cholesky factorization $A = U^*T^*U$ or $A = L^*L^*T^*$ to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SPPSVX(FACT, UPLO, N, NRHS, A, AF, EQUED, S, B, LDB,
  X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER WORK2(*)
REAL RCOND
REAL A(*), AF(*), S(*), B(LDB,*), X(LDX,*), FERR(*),
BERR(*), WORK(*)
```

```
SUBROUTINE SPPSVX_64(FACT, UPLO, N, NRHS, A, AF, EQUED, S, B,
  LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 WORK2(*)
REAL RCOND
REAL A(*), AF(*), S(*), B(LDB,*), X(LDX,*), FERR(*),
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PPSVX(FACT, UPLO, [N], [NRHS], A, AF, EQUED, S, B,
  [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: A, AF, S, FERR, BERR, WORK
REAL, DIMENSION(:,:) :: B, X
```

```
SUBROUTINE PPSVX_64(FACT, UPLO, [N], [NRHS], A, AF, EQUED, S, B,
```

[LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: A, AF, S, FERR, BERR, WORK
REAL, DIMENSION(:, :) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sppsvx(char fact, char uplo, int n, int nrhs, float *a,
            float *af, char equed, float *s, float *b, int
            ldb, float *x, int ldx, float *rcond, float *ferr,
            float *berr, int *info);
```

```
void sppsvx_64(char fact, char uplo, long n, long nrhs,
               float *a, float *af, char equed, float *s, float
               *b, long ldb, float *x, long ldx, float *rcond,
               float *ferr, float *berr, long *info);
```

PURPOSE

sppsvx uses the Cholesky factorization $A = U^*T*U$ or $A = L*L^*T$ to compute the solution to a real system of linear equations

$A * X = B$, where A is an N -by- N symmetric positive definite matrix stored in packed format and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A

is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$)

as

$$A = U^*T*U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L^*T, \text{ if } UPLO = 'L',$$

where U is an upper triangular matrix and L is a lower triangular

matrix.

3. If the leading i -by- i principal minor is not positive definite,

then the routine returns with $INFO = i$. Otherwise, the factored

form of A is used to estimate the condition number of the matrix

A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.

5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

6. If equilibration was used, the matrix X is premultiplied by diag(S) so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF contains the factored form of A. If EQUED = 'Y', the matrix A has been equilibrated with scaling factors given by S. A and AF will not be modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output) REAL array, dimension (N*(N+1)/2)

On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix $\text{diag}(S)*A*\text{diag}(S)$. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED =

'N' on exit.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S) * A * \text{diag}(S)$.

AF (input or output) REAL array, dimension $(N * (N + 1) / 2)$
If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U * U$ or $A = L * L'$, in the same storage format as A. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * U$ or $A = L * L'$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * U$ or $A = L * L'$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

EQUED (input or output)
Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output) REAL array, dimension (N)
The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output) REAL array, dimension (LDB, NRHS)
On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (output) REAL array, dimension (LDX, NRHS)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is $\text{inv}(\text{diag}(S)) * X$.

LDX (input)
The leading dimension of the array X. $LDX \geq \max(1, N)$.

RCOND (output)
The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If

RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output) REAL array, dimension (NRHS)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) REAL array, dimension (NRHS)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

REAL array, dimension (3*N)

WORK2 (workspace)

INTEGER array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when N = 4, UPLO = 'U':

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34 (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

spptrf - compute the Cholesky factorization of a real symmetric positive definite matrix A stored in packed format

SYNOPSIS

```
SUBROUTINE SPPTRF(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
REAL A(*)
```

```
SUBROUTINE SPPTRF_64(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
REAL A(*)
```

F95 INTERFACE

```
SUBROUTINE PPTRF(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
REAL, DIMENSION(:) :: A
```

```
SUBROUTINE PPTRF_64(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
REAL, DIMENSION(:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spptrf(char uplo, int n, float *a, int *info);
```

```
void spptrf_64(char uplo, long n, float *a, long *info);
```

PURPOSE

spptrf computes the Cholesky factorization of a real symmetric positive definite matrix A stored in packed format.

The factorization has the form

$A = U^{**T} * U$, if UPLO = 'U', or

$A = L * L^{**T}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) REAL array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$, in the same storage format as A.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, UPLO = 'U':

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13 a14
   a22 a23 a24
     a33 a34   (aij = aji)
       a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

spptri - compute the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^*T^*U$ or $A = L*L^*T$ computed by SPPTRF

SYNOPSIS

```
SUBROUTINE SPPTRI(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
REAL A(*)
```

```
SUBROUTINE SPPTRI_64(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
REAL A(*)
```

F95 INTERFACE

```
SUBROUTINE PPTRI(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
REAL, DIMENSION(:) :: A
```

```
SUBROUTINE PPTRI_64(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
REAL, DIMENSION(:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spptri(char uplo, int n, float *a, int *info);
```

```
void spptri_64(char uplo, long n, float *a, long *info);
```

PURPOSE

spptri computes the inverse of a real symmetric positive definite matrix A using the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$ computed by SPPTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular factor is stored in A;
= 'L': Lower triangular factor is stored in A.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) REAL array, dimension $(N*(N+1))/2$

On entry, the triangular factor U or L from the Cholesky factorization $A = U^{**T}U$ or $A = L*L^{**T}$, packed columnwise as a linear array. The j-th column of U or L is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = U(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = L(i,j)$ for $j \leq i \leq n$.

On exit, the upper or lower triangle of the (symmetric) inverse of A, overwriting the input factor U or L.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the (i,i) element of the factor U or L is zero, and the inverse could not be computed.

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NAME

spptrs - solve a system of linear equations $A \cdot X = B$ with a symmetric positive definite matrix A in packed storage using the Cholesky factorization $A = U \cdot U^T \cdot U$ or $A = L \cdot L^T \cdot T$ computed by SPPTRF

SYNOPSIS

```
SUBROUTINE SPPTRS(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, INFO  
REAL A(*), B(LDB,*)
```

```
SUBROUTINE SPPTRS_64(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, INFO  
REAL A(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PPTRS(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: A  
REAL, DIMENSION(:,) :: B
```

```
SUBROUTINE PPTRS_64(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: A  
REAL, DIMENSION(:,) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spptrs(char uplo, int n, int nrhs, float *a, float *b,  
            int ldb, int *info);
```

```
void spptrs_64(char uplo, long n, long nrhs, float *a, float
               *b, long ldb, long *info);
```

PURPOSE

spptrs solves a system of linear equations $A \cdot X = B$ with a symmetric positive definite matrix A in packed storage using the Cholesky factorization $A = U \cdot U^T \cdot U$ or $A = L \cdot L^T \cdot L$ computed by SPPTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) REAL array, dimension $(N \cdot (N+1) / 2)$

The triangular factor U or L from the Cholesky factorization $A = U \cdot U^T \cdot U$ or $A = L \cdot L^T \cdot L$, packed columnwise in a linear array. The j -th column of U or L is stored in the array A as follows: if $UPLO = 'U'$, $A(i + (j-1) \cdot j / 2) = U(i, j)$ for $1 \leq i \leq j$; if $UPLO = 'L'$, $A(i + (j-1) \cdot (2n-j) / 2) = L(i, j)$ for $j \leq i \leq n$.

B (input/output)

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

sptcon - compute the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite tridiagonal matrix using the factorization $A = L*D*L^*T$ or $A = U^*T*D*U$ computed by SPTTRF

SYNOPSIS

```
SUBROUTINE SPTCON(N, D, E, ANORM, RCOND, WORK, INFO)
```

```
INTEGER N, INFO
REAL ANORM, RCOND
REAL D(*), E(*), WORK(*)
```

```
SUBROUTINE SPTCON_64(N, D, E, ANORM, RCOND, WORK, INFO)
```

```
INTEGER*8 N, INFO
REAL ANORM, RCOND
REAL D(*), E(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTCON([N], D, E, ANORM, RCOND, [WORK], [INFO])
```

```
INTEGER :: N, INFO
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: D, E, WORK
```

```
SUBROUTINE PTCON_64([N], D, E, ANORM, RCOND, [WORK], [INFO])
```

```
INTEGER(8) :: N, INFO
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: D, E, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sptcon(int n, float *d, float *e, float anorm, float
           *rcond, int *info);
```

```
void sptcon_64(long n, float *d, float *e, float anorm,
               float *rcond, long *info);
```

PURPOSE

sptcon computes the reciprocal of the condition number (in the 1-norm) of a real symmetric positive definite tridiagonal matrix using the factorization $A = L*D*L^T$ or $A = U^T*D*U$ computed by SPTTRF.

Norm(inv(A)) is computed by a direct method, and the reciprocal of the condition number is computed as

$$RCOND = 1 / (ANORM * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the factorization of A, as computed by SPTTRF.

E (input) The (n-1) off-diagonal elements of the unit bidiagonal factor U or L from the factorization of A, as computed by SPTTRF.

ANORM (input)
The 1-norm of the original matrix A.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(ANORM * AINVNM)$, where AINVNM is the 1-norm of inv(A) computed in this routine.

WORK (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The method used is described in Nicholas J. Higham, "Efficient Algorithms for Computing the Condition Number of a Tridiagonal Matrix", SIAM J. Sci. Stat. Comput., Vol. 7, No. 1, January 1986.

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NAME

spteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using SPTTRF, and then calling SBDSQR to compute the singular values of the bidiagonal factor

SYNOPSIS

```
SUBROUTINE SPTEQR(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
INTEGER N, LDZ, INFO  
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SPTEQR_64(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
INTEGER*8 N, LDZ, INFO  
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTEQR(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
INTEGER :: N, LDZ, INFO  
REAL, DIMENSION(:) :: D, E, WORK  
REAL, DIMENSION(:, :) :: Z
```

```
SUBROUTINE PTEQR_64(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
INTEGER(8) :: N, LDZ, INFO  
REAL, DIMENSION(:) :: D, E, WORK  
REAL, DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spteqr(char compz, int n, float *d, float *e, float *z,  
            int ldz, int *info);
```

```
void spteqr_64(char compz, long n, float *d, float *e, float
              *z, long ldz, long *info);
```

PURPOSE

spteqr computes all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using SPTTRF, and then calling SBDSQR to compute the singular values of the bidiagonal factor.

This routine computes the eigenvalues of the positive definite tridiagonal matrix to high relative accuracy. This means that if the eigenvalues range over many orders of magnitude in size, then the small eigenvalues and corresponding eigenvectors will be computed more accurately than, for example, with the standard QR method.

The eigenvectors of a full or band symmetric positive definite matrix can also be found if SSYTRD, SSPTRD, or SSBTRD has been used to reduce this matrix to tridiagonal form. (The reduction to tridiagonal form, however, may preclude the possibility of obtaining high relative accuracy in the small eigenvalues of the original matrix, if these eigenvalues range over many orders of magnitude.)

ARGUMENTS

COMPZ (input)

= 'N': Compute eigenvalues only.
= 'V': Compute eigenvectors of original symmetric matrix also. Array Z contains the orthogonal matrix used to reduce the original matrix to tridiagonal form.
= 'I': Compute eigenvectors of tridiagonal matrix also.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix. On normal exit, D contains the eigenvalues, in descending order.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input)

On entry, if COMPZ = 'V', the orthogonal matrix used in the reduction to tridiagonal form. On exit, if COMPZ = 'V', the orthonormal eigenvectors of the original symmetric matrix; if COMPZ = 'I', the orthonormal eigenvectors of the tridiagonal matrix. If INFO > 0 on exit, Z contains the eigenvectors associated with only the stored

eigenvalues. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if COMPZ = 'V' or 'I', LDZ \geq max(1,N).

WORK (workspace)

dimension(4*N)

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, and i is: \leq N the Cholesky factorization of the matrix could not be performed because the i-th principal minor was not positive definite. $>$ N the SVD algorithm failed to converge; if INFO = N+i, i off-diagonal elements of the bidiagonal factor did not converge to zero.

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NAME

sptrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE SPTRFS(N, NRHS, D, E, DF, EF, B, LDB, X, LDX,  
    FERR, BERR, WORK, INFO)
```

```
INTEGER N, NRHS, LDB, LDX, INFO  
REAL D(*), E(*), DF(*), EF(*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE SPTRFS_64(N, NRHS, D, E, DF, EF, B, LDB, X,  
    LDX, FERR, BERR, WORK, INFO)
```

```
INTEGER*8 N, NRHS, LDB, LDX, INFO  
REAL D(*), E(*), DF(*), EF(*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTRFS([N], [NRHS], D, E, DF, EF, B, [LDB], X,  
    [LDX], FERR, BERR, [WORK], [INFO])
```

```
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL, DIMENSION(:) :: D, E, DF, EF, FERR, BERR, WORK  
REAL, DIMENSION(:,) :: B, X
```

```
SUBROUTINE PTRFS_64([N], [NRHS], D, E, DF, EF, B, [LDB],  
    X, [LDX], FERR, BERR, [WORK], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, LDX, INFO  
REAL, DIMENSION(:) :: D, E, DF, EF, FERR, BERR, WORK  
REAL, DIMENSION(:,) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sptrfs(int n, int nrhs, float *d, float *e, float *df,
```

```

float *ef, float *b, int ldb, float *x, int ldx,
float *ferr, float *berr, int *info);

void spttrfs_64(long n, long nrhs, float *d, float *e, float
*df, float *ef, float *b, long ldb, float *x, long
ldx, float *ferr, float *berr, long *info);

```

PURPOSE

spttrfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

D (input) The n diagonal elements of the tridiagonal matrix A.

E (input) The (n-1) subdiagonal elements of the tridiagonal matrix A.

DF (input)
The n diagonal elements of the diagonal matrix D from the factorization computed by SPTTRF.

EF (input)
The (n-1) subdiagonal elements of the unit bidiagonal factor L from the factorization computed by SPTTRF.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (input/output)
On entry, the solution matrix X, as computed by SPTTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. $LDX \geq \max(1, N)$.

FERR (output)
The forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$.

divided by the magnitude of the largest element in $X(j)$.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sptsv - compute the solution to a real system of linear equations $A \cdot X = B$, where A is an N -by- N symmetric positive definite tridiagonal matrix, and X and B are N -by- $NRHS$ matrices.

SYNOPSIS

```
SUBROUTINE SPTSV(N, NRHS, D, E, B, LDB, INFO)
```

```
INTEGER N, NRHS, LDB, INFO  
REAL D(*), E(*), B(LDB,*)
```

```
SUBROUTINE SPTSV_64(N, NRHS, D, E, B, LDB, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO  
REAL D(*), E(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PTVS([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: D, E  
REAL, DIMENSION(:, :) :: B
```

```
SUBROUTINE PTVS_64([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: D, E  
REAL, DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sptsv(int n, int nrhs, float *d, float *e, float *b,  
          int ldb, int *info);
```

```
void sptsv_64(long n, long nrhs, float *d, float *e, float  
             *b, long ldb, long *info);
```

PURPOSE

sptsv computes the solution to a real system of linear equations $A \cdot X = B$, where A is an N -by- N symmetric positive definite tridiagonal matrix, and X and B are N -by- $NRHS$ matrices.

A is factored as $A = L \cdot D \cdot L^{**T}$, and the factored form of A is then used to solve the system of equations.

ARGUMENTS

N (input) The order of the matrix A . $N \geq 0$.

$NRHS$ (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A . On exit, the n diagonal elements of the diagonal matrix D from the factorization $A = L \cdot D \cdot L^{**T}$.

E (input/output)

On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix A . On exit, the $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the $L \cdot D \cdot L^{**T}$ factorization of A . (E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the $U^{**T} \cdot D \cdot U$ factorization of A .)

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B . On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

$INFO$ (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, the leading minor of order i is not positive definite, and the solution has not been computed. The factorization has not been completed unless $i = N$.

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NAME

sptsvx - use the factorization $A = L*D*L**T$ to compute the solution to a real system of linear equations $A*X = B$, where A is an N-by-N symmetric positive definite tridiagonal matrix and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE SPTSVX(FACT, N, NRHS, D, E, DF, EF, B, LDB, X,  
                 LDX, RCOND, FERR, BERR, WORK, INFO)
```

```
CHARACTER * 1 FACT  
INTEGER N, NRHS, LDB, LDX, INFO  
REAL RCOND  
REAL D(*), E(*), DF(*), EF(*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE SPTSVX_64(FACT, N, NRHS, D, E, DF, EF, B, LDB,  
                    X, LDX, RCOND, FERR, BERR, WORK, INFO)
```

```
CHARACTER * 1 FACT  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
REAL RCOND  
REAL D(*), E(*), DF(*), EF(*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTVSX(FACT, [N], [NRHS], D, E, DF, EF, B, [LDB],  
                X, [LDX], RCOND, FERR, BERR, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: FACT  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL :: RCOND  
REAL, DIMENSION(:) :: D, E, DF, EF, FERR, BERR, WORK  
REAL, DIMENSION(:,:) :: B, X
```

```
SUBROUTINE PTVSX_64(FACT, [N], [NRHS], D, E, DF, EF, B,  
                   [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: FACT  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

```
REAL :: RCOND
REAL, DIMENSION(:) :: D, E, DF, EF, FERR, BERR, WORK
REAL, DIMENSION(:,:) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
void sptsvx(char fact, int n, int nrhs, float *d, float *e,
            float *df, float *ef, float *b, int ldb, float *x,
            int ldx, float *rcond, float *ferr, float *berr,
            int *info);

void sptsvx_64(char fact, long n, long nrhs, float *d, float
              *e, float *df, float *ef, float *b, long ldb,
              float *x, long ldx, float *rcond, float *ferr,
              float *berr, long *info);
```

PURPOSE

sptsvx uses the factorization $A = L^*D*L^{**T}$ to compute the solution to a real system of linear equations $A*X = B$, where A is an N -by- N symmetric positive definite tridiagonal matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the matrix A is factored as $A = L^*D*L^{**T}$, where L is a unit lower bidiagonal matrix and D is diagonal. The factorization can also be regarded as having the form $A = U^{**T}*D*U$.
2. If the leading i -by- i principal minor is not positive definite, then the routine returns with $INFO = i$. Otherwise, the factored form of A is used to estimate the condition number of the matrix A .
 - A. If the reciprocal of the condition number is less than machine precision, $INFO = N+1$ is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
3. The system of equations is solved for X using the factored form of A .
4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)
Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, DF and EF contain the factored form of A. D, E, DF, and EF will not be modified. = 'N': The matrix A will be copied to DF and EF and factored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

D (input) The n diagonal elements of the tridiagonal matrix A.

E (input) The (n-1) subdiagonal elements of the tridiagonal matrix A.

DF (input or output)
If FACT = 'F', then DF is an input argument and on entry contains the n diagonal elements of the diagonal matrix D from the L^*D*L^{**T} factorization of A. If FACT = 'N', then DF is an output argument and on exit contains the n diagonal elements of the diagonal matrix D from the L^*D*L^{**T} factorization of A.

EF (input or output)
If FACT = 'F', then EF is an input argument and on entry contains the (n-1) subdiagonal elements of the unit bidiagonal factor L from the L^*D*L^{**T} factorization of A. If FACT = 'N', then EF is an output argument and on exit contains the (n-1) subdiagonal elements of the unit bidiagonal factor L from the L^*D*L^{**T} factorization of A.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1,N)$.

X (output)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)
The leading dimension of the array X. $LDX \geq \max(1,N)$.

RCOND (output)
The reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension($2*N$)

INFO (output)

= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value
> 0: if INFO = i , and i is
<= N : the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. $RCOND = 0$ is returned. = $N+1$: U is non-singular, but $RCOND$ is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of $RCOND$ would suggest.

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NAME

sptrtf - compute the L*D*L' factorization of a real symmetric positive definite tridiagonal matrix A

SYNOPSIS

```
SUBROUTINE SPTRTF(N, D, E, INFO)
```

```
INTEGER N, INFO  
REAL D(*), E(*)
```

```
SUBROUTINE SPTRTF_64(N, D, E, INFO)
```

```
INTEGER*8 N, INFO  
REAL D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE PTTRF([N], D, E, [INFO])
```

```
INTEGER :: N, INFO  
REAL, DIMENSION(:) :: D, E
```

```
SUBROUTINE PTTRF_64([N], D, E, [INFO])
```

```
INTEGER(8) :: N, INFO  
REAL, DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sptrtf(int n, float *d, float *e, int *info);
```

```
void sptrtf_64(long n, float *d, float *e, long *info);
```

PURPOSE

sptrtf computes the L*D*L' factorization of a real symmetric positive definite tridiagonal matrix A. The factorization

may also be regarded as having the form $A = U'D*U$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the $L'D*L'$ factorization of A.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A. On exit, the (n-1) subdiagonal elements of the unit bidiagonal factor L from the $L'D*L'$ factorization of A. E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the $U'D*U$ factorization of A.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value
> 0: if INFO = k, the leading minor of order k is not positive definite; if $k < N$, the factorization could not be completed, while if $k = N$, the factorization was completed, but $D(N) = 0$.

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NAME

spttrs - solve a tridiagonal system of the form $A * X = B$ using the L*D*L' factorization of A computed by SPTTRF

SYNOPSIS

```
SUBROUTINE SPTTRS(N, NRHS, D, E, B, LDB, INFO)
```

```
INTEGER N, NRHS, LDB, INFO  
REAL D(*), E(*), B(LDB,*)
```

```
SUBROUTINE SPTTRS_64(N, NRHS, D, E, B, LDB, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO  
REAL D(*), E(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE PTTRS([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: D, E  
REAL, DIMENSION(:, :) :: B
```

```
SUBROUTINE PTTRS_64([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: D, E  
REAL, DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void spttrs(int n, int nrhs, float *d, float *e, float *b,  
           int ldb, int *info);
```

```
void spttrs_64(long n, long nrhs, float *d, float *e, float  
              *b, long ldb, long *info);
```

PURPOSE

spttrs solves a tridiagonal system of the form
 $A * X = B$ using the $L*D*L'$ factorization of A computed by SPTTRF. D is a diagonal matrix specified in the vector D , L is a unit bidiagonal matrix whose subdiagonal is specified in the vector E , and X and B are N by $NRHS$ matrices.

ARGUMENTS

N (input) The order of the tridiagonal matrix A . $N \geq 0$.

$NRHS$ (input)
The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the $L*D*L'$ factorization of A .

E (input) The $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the $L*D*L'$ factorization of A . E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the factorization $A = U'*D*U$.

B (input/output)
On entry, the right hand side vectors B for the system of linear equations. On exit, the solution vectors, X .

LDB (input)
The leading dimension of the array B . $LDB \geq \max(1,N)$.

$INFO$ (output)
= 0: successful exit
< 0: if $INFO = -k$, the k -th argument had an illegal value

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NAME

sptts2 - solve a tridiagonal system of the form $A * X = B$
using the L*D*L' factorization of A computed by SPTTRF

SYNOPSIS

```
SUBROUTINE SPTTS2(N, NRHS, D, E, B, LDB)
```

```
INTEGER N, NRHS, LDB  
REAL D(*), E(*), B(LDB,*)
```

```
SUBROUTINE SPTTS2_64(N, NRHS, D, E, B, LDB)
```

```
INTEGER*8 N, NRHS, LDB  
REAL D(*), E(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SPTTS2(N, NRHS, D, E, B, LDB)
```

```
INTEGER :: N, NRHS, LDB  
REAL, DIMENSION(:) :: D, E  
REAL, DIMENSION(:,) :: B
```

```
SUBROUTINE SPTTS2_64(N, NRHS, D, E, B, LDB)
```

```
INTEGER(8) :: N, NRHS, LDB  
REAL, DIMENSION(:) :: D, E  
REAL, DIMENSION(:,) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sptts2(int n, int nrhs, float *d, float *e, float *b,  
           int ldb);
```

```
void sptts2_64(long n, long nrhs, float *d, float *e, float  
              *b, long ldb);
```

PURPOSE

sptts2 solves a tridiagonal system of the form
 $A * X = B$ using the $L*D*L'$ factorization of A computed by SPTTRF. D is a diagonal matrix specified in the vector D , L is a unit bidiagonal matrix whose subdiagonal is specified in the vector E , and X and B are N by $NRHS$ matrices.

ARGUMENTS

- N (input) The order of the tridiagonal matrix A . $N \geq 0$.
- $NRHS$ (input)
The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.
- D (input) The n diagonal elements of the diagonal matrix D from the $L*D*L'$ factorization of A .
- E (input) The $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the $L*D*L'$ factorization of A . E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the factorization $A = U'*D*U$.
- B (input/output)
On entry, the right hand side vectors B for the system of linear equations. On exit, the solution vectors, X .
- LDB (input)
The leading dimension of the array B . $LDB \geq \max(1, N)$.

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NAME

srot - Apply a Given's rotation constructed by SROTG.

SYNOPSIS

```
SUBROUTINE SROT(N, X, INCX, Y, INCY, C, S)
```

```
INTEGER N, INCX, INCY  
REAL C, S  
REAL X(*), Y(*)
```

```
SUBROUTINE SROT_64(N, X, INCX, Y, INCY, C, S)
```

```
INTEGER*8 N, INCX, INCY  
REAL C, S  
REAL X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE ROT([N], X, [INCX], Y, [INCY], C, S)
```

```
INTEGER :: N, INCX, INCY  
REAL :: C, S  
REAL, DIMENSION(:) :: X, Y
```

```
SUBROUTINE ROT_64([N], X, [INCX], Y, [INCY], C, S)
```

```
INTEGER(8) :: N, INCX, INCY  
REAL :: C, S  
REAL, DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void srot(int n, float *x, int incx, float *y, int incy,  
         float c, float s);
```

```
void srot_64(long n, float *x, long incx, float *y, long  
            incy, float c, float s);
```

PURPOSE

srot Apply a Given's rotation constructed by SROTG.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input/output)

(1 + (n - 1) * abs(INCX)). Before entry, the incremented array X must contain the vector x.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

C (input) On entry, the C rotation value constructed by SROTG. Unchanged on exit.

S (input) On entry, the S rotation value constructed by SROTG. Unchanged on exit.

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NAME

srotg - Construct a Given's plane rotation

SYNOPSIS

```
SUBROUTINE SROTG(A, B, C, S)
```

```
REAL A, B, C, S
```

```
SUBROUTINE SROTG_64(A, B, C, S)
```

```
REAL A, B, C, S
```

F95 INTERFACE

```
SUBROUTINE ROTG(A, B, C, S)
```

```
REAL :: A, B, C, S
```

```
SUBROUTINE ROTG_64(A, B, C, S)
```

```
REAL :: A, B, C, S
```

C INTERFACE

```
#include <sunperf.h>
```

```
void srotg(float *a, float *b, float *c, float *s);
```

```
void srotg_64(float *a, float *b, float *c, float *s);
```

PURPOSE

srotg Construct a Given's plane rotation that will annihilate an element of a vector.

ARGUMENTS

A (input/output)

On entry, A contains the entry in the first vector that corresponds to the element to be annihilated in the second vector. On exit, contains the nonzero element of the rotated vector.

B (input/output)

On entry, B contains the entry to be annihilated in the second vector. On exit, contains either S or $1/C$ depending on which of the input values of A and B is larger.

C (output)

On exit, C and S are the elements of the rotation matrix that will be applied to annihilate B.

S (output)

See the description of C.

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NAME

sroti - Apply an indexed Givens rotation.

SYNOPSIS

```
SUBROUTINE SROTI(NZ, X, INDX, Y, C, S)
```

```
INTEGER NZ  
INTEGER INDX(*)  
REAL C, S  
REAL X(*), Y(*)
```

```
SUBROUTINE SROTI_64(NZ, X, INDX, Y, C, S)
```

```
INTEGER*8 NZ  
INTEGER*8 INDX(*)  
REAL C, S  
REAL X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE ROTI([NZ], X, INDX, Y, C, S)
```

```
INTEGER :: NZ  
INTEGER, DIMENSION(:) :: INDX  
REAL :: C, S  
REAL, DIMENSION(:) :: X, Y
```

```
SUBROUTINE ROTI_64([NZ], X, INDX, Y, C, S)
```

```
INTEGER(8) :: NZ  
INTEGER(8), DIMENSION(:) :: INDX  
REAL :: C, S  
REAL, DIMENSION(:) :: X, Y
```

PURPOSE

SROTI - Applies a Givens rotation to a sparse vector x stored in compressed form and another vector y in full storage form

```
do i = 1, n
```

```
temp = -s * x(i) + c * y(indx(i))
x(i) = c * x(i) + s * y(indx(i))
y(indx(i)) = temp
enddo
```

ARGUMENTS

NZ (input) - INTEGER
Number of elements in the compressed form.
Unchanged on exit.

X (input)
Vector containing the values of the compressed form.

INDX (input) - INTEGER
Vector containing the indices of the compressed form. It is assumed that the elements in INDX are distinct and greater than zero. Unchanged on exit.

Y (input/output)
Vector on input which contains the vector Y in full storage form. On exit, only the elements corresponding to the indices in INDX have been modified.

C (input)
Scalar defining the Givens rotation

S (input)
Scalar defining the Givens rotation

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NAME

srotm - Apply a Gentleman's modified Given's rotation constructed by SROTMG.

SYNOPSIS

```
SUBROUTINE SROTM(N, X, INCX, Y, INCY, PARAM)
```

```
INTEGER N, INCX, INCY  
REAL X(*), Y(*), PARAM(*)
```

```
SUBROUTINE SROTM_64(N, X, INCX, Y, INCY, PARAM)
```

```
INTEGER*8 N, INCX, INCY  
REAL X(*), Y(*), PARAM(*)
```

F95 INTERFACE

```
SUBROUTINE ROTM([N], X, [INCX], Y, [INCY], PARAM)
```

```
INTEGER :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y, PARAM
```

```
SUBROUTINE ROTM_64([N], X, [INCX], Y, [INCY], PARAM)
```

```
INTEGER(8) :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y, PARAM
```

C INTERFACE

```
#include <sunperf.h>
```

```
void srotm(int n, float *x, int incx, float *y, int incy,  
          float *param);
```

```
void srotm_64(long n, float *x, long incx, float *y, long  
            incy, float *param);
```

PURPOSE

srotm Apply a Given's rotation constructed by SROTMG.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the sub-routine to have any visible effect. Unchanged on exit.

X (input/output)

(1 + (n - 1) * abs(INCX)). On entry, the incremented array X must contain the vector x. On exit, X is overwritten by the updated vector x.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

PARAM (input)

On entry, the rotation values constructed by SROTMG. Unchanged on exit.

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NAME

srotmg - Construct a Gentleman's modified Given's plane rotation

SYNOPSIS

```
SUBROUTINE SROTMG(D1, D2, B1, B2, PARAM)
```

```
REAL D1, D2, B1, B2  
REAL PARAM(*)
```

```
SUBROUTINE SROTMG_64(D1, D2, B1, B2, PARAM)
```

```
REAL D1, D2, B1, B2  
REAL PARAM(*)
```

F95 INTERFACE

```
SUBROUTINE ROTMG(D1, D2, B1, B2, PARAM)
```

```
REAL :: D1, D2, B1, B2  
REAL, DIMENSION(:) :: PARAM
```

```
SUBROUTINE ROTMG_64(D1, D2, B1, B2, PARAM)
```

```
REAL :: D1, D2, B1, B2  
REAL, DIMENSION(:) :: PARAM
```

C INTERFACE

```
#include <sunperf.h>
```

```
void srotmg(float d1, float d2, float b1, float b2, float  
           *param);
```

```
void srotmg_64(float d1, float d2, float b1, float b2, float  
             *param);
```

PURPOSE

srotmg Construct Gentleman's modified a Given's plane rotation that will annihilate an element of a vector.

ARGUMENTS

D1 (input/output)
On entry, the first diagonal entry in the H matrix. On exit, changed to reflect the effect of the transformation.

D2 (input/output)
On entry, the second diagonal entry in the H matrix. On exit, changed to reflect the effect of the transformation.

B1 (input/output)
On entry, the first element of the vector to which the H matrix is applied. On exit, changed to reflect the effect of the transformation.

B2 (input)
On entry, the second element of the vector to which the H matrix is applied. Unchanged on exit.

PARAM (output)
On exit, PARAM(1) describes the form of the rotation matrix H, and PARAM(2..5) contain the H matrix.

If PARAM(1) = -2 then H = I and no elements of PARAM are modified.

If PARAM(1) = -1 then PARAM(2) = h11, PARAM(3) = h21, PARAM(4) = h12, and PARAM(5) = h22.

If PARAM(1) = 0 then h11 = h22 = 1, PARAM(3) = h21, and PARAM(4) = h12.

If PARAM(1) = 1 then h12 = 1, h21 = -1, PARAM(2) = h11, and PARAM(5) = h22.

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NAME

ssbev - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

SYNOPSIS

```
SUBROUTINE SSBEV(JOBZ, UPLO, N, KD, A, LDA, W, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, KD, LDA, LDZ, INFO  
REAL A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSBEV_64(JOBZ, UPLO, N, KD, A, LDA, W, Z, LDZ, WORK,  
INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, KD, LDA, LDZ, INFO  
REAL A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBEV(JOBZ, UPLO, [N], KD, A, [LDA], W, Z, [LDZ], [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, KD, LDA, LDZ, INFO  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:,) :: A, Z
```

```
SUBROUTINE SBEV_64(JOBZ, UPLO, [N], KD, A, [LDA], W, Z, [LDZ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, KD, LDA, LDZ, INFO  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:,) :: A, Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssbev(char jobz, char uplo, int n, int kd, float *a,  
int lda, float *w, float *z, int ldz, int *info);
```

```

void ssbev_64(char jobz, char uplo, long n, long kd, float
             *a, long lda, float *w, float *z, long ldz, long
             *info);

```

PURPOSE

ssbev computes all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, A is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of the tridiagonal matrix T are returned in rows KD and $KD+1$ of A, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the first two rows of A.

LDA (input)
 The leading dimension of the array A. $LDA \geq KD + 1$.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i -th column of Z holding the eigenvector associated with $W(i)$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1,
and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

dimension(MAX(1,3*N-2))

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

ssbevd - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

SYNOPSIS

```
SUBROUTINE SSBEVD(JOBZ, UPLO, N, KD, AB, LDAB, W, Z, LDZ, WORK,  
                 LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, KD, LDAB, LDZ, LWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL AB(LDAB,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSBEVD_64(JOBZ, UPLO, N, KD, AB, LDAB, W, Z, LDZ, WORK,  
                   LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, KD, LDAB, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL AB(LDAB,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBEVD(JOBZ, UPLO, [N], KD, AB, [LDAB], W, Z, [LDZ], [WORK],  
                [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, KD, LDAB, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:,) :: AB, Z
```

```
SUBROUTINE SBEVD_64(JOBZ, UPLO, [N], KD, AB, [LDAB], W, Z, [LDZ],  
                   [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, KD, LDAB, LDZ, LWORK, LIWORK, INFO  
INTEGER(8), DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:,) :: AB, Z
```

C INTERFACE

```
#include <sunperf.h>

void ssbevd(char jobz, char uplo, int n, int kd, float *ab,
            int ldab, float *w, float *z, int ldz, int *info);
void ssbevd_64(char jobz, char uplo, long n, long kd, float
               *ab, long ldab, float *w, float *z, long ldz, long
               *info);
```

PURPOSE

ssbevd computes all the eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, AB is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of the tridiagonal matrix T are returned in rows KD and $KD+1$ of AB, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the first two rows of AB.

LDAB (input)
 The leading dimension of the array AB. LDAB \geq KD + 1.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

Z (output)
 If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)
 dimension (LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. If $N \leq 1$, LWORK must be at least 1. If JOBZ = 'N' and $N > 2$, LWORK must be at least $2*N$. If JOBZ = 'V' and $N > 2$, LWORK must be at least $(1 + 5*N + 2*N**2)$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)
 On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
 The dimension of the array LIWORK. If JOBZ = 'N' or $N \leq 1$, LIWORK must be at least 1. If JOBZ = 'V' and $N > 2$, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

ssbevz - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A

SYNOPSIS

```
SUBROUTINE SSBEVZ(JOBZ, RANGE, UPLO, N, KD, A, LDA, Q, LDQ, VL,
                 VU, IL, IU, ABTOL, NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER IWORK2(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL A(LDA,*), Q(LDQ,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSBEVZ_64(JOBZ, RANGE, UPLO, N, KD, A, LDA, Q, LDQ, VL,
                    VU, IL, IU, ABTOL, NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER*8 IWORK2(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL A(LDA,*), Q(LDQ,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBEVZ(JOBZ, RANGE, UPLO, [N], KD, A, [LDA], Q, [LDQ],
                VL, VU, IL, IU, ABTOL, NFOUND, W, Z, [LDZ], [WORK], [IWORK2],
                IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK2, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: A, Q, Z
```

```
SUBROUTINE SBEVZ_64(JOBZ, RANGE, UPLO, [N], KD, A, [LDA], Q, [LDQ],
                   VL, VU, IL, IU, ABTOL, NFOUND, W, Z, [LDZ], [WORK], [IWORK2],
                   IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
```

```

INTEGER(8) :: N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK2, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:,) :: A, Q, Z

```

C INTERFACE

```

#include <sunperf.h>

void ssbevz(char jobz, char range, char uplo, int n, int kd,
            float *a, int lda, float *q, int ldq, float vl,
            float vu, int il, int iu, float abtol, int
            *nfound, float *w, float *z, int ldz, int *ifail,
            int *info);

void ssbevz_64(char jobz, char range, char uplo, long n,
               long kd, float *a, long lda, float *q, long ldq,
               float vl, float vu, long il, long iu, float abtol,
               long *nfound, float *w, float *z, long ldz, long
               *ifail, long *info);

```

PURPOSE

ssbevz computes selected eigenvalues and, optionally, eigenvectors of a real symmetric band matrix A. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found;
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found; = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. N >= 0.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. KD >= 0.

A (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first KD+1 rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-$

kd)<=i<=j; if UPLO = 'L', A(1+i-j,j) = A(i,j)
for j<=i<=min(n,j+kd).

On exit, A is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of the tridiagonal matrix T are returned in rows KD and KD+1 of A, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the first two rows of A.

LDA (input)

The leading dimension of the array A. LDA >= KD + 1.

Q (output)

If JOBZ = 'V', the N-by-N orthogonal matrix used in the reduction to tridiagonal form. If JOBZ = 'N', the array Q is not referenced.

LDQ (input)

The leading dimension of the array Q. If JOBZ = 'V', then LDQ >= max(1,N).

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. 1 <= IL <= IU <= N, if N > 0; IL = 1 and IU = 0 if N = 0. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then EPS*|T| will be used in its place, where |T| is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold 2*SLAMCH('S'), not zero. If this routine returns with INFO>0, indicating that some eigenvectors did not converge, try setting ABTOL to 2*SLAMCH('S').

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq \text{NFOUND} \leq N$. If RANGE = 'A', NFOUND = N, and if RANGE = 'I', NFOUND = IU-IL+1.

W (output)

The first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, \text{NFOUND})$ columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $\text{LDZ} \geq 1$, and if JOBZ = 'V', $\text{LDZ} \geq \max(1, N)$.

WORK (workspace)

dimension(7*N)

IWORK2 (workspace)

IFAIL (output)

If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

ssbgst - reduce a real symmetric-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$,

SYNOPSIS

```
SUBROUTINE SSBGST(VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X, LDX,
                 WORK, INFO)
```

```
CHARACTER * 1 VECT, UPLO
INTEGER N, KA, KB, LDAB, LDBB, LDX, INFO
REAL AB(LDAB,*), BB(LDBB,*), X(LDX,*), WORK(*)
```

```
SUBROUTINE SSBGST_64(VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X,
                    LDX, WORK, INFO)
```

```
CHARACTER * 1 VECT, UPLO
INTEGER*8 N, KA, KB, LDAB, LDBB, LDX, INFO
REAL AB(LDAB,*), BB(LDBB,*), X(LDX,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBGST(VECT, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], X,
                [LDX], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO
INTEGER :: N, KA, KB, LDAB, LDBB, LDX, INFO
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:, :) :: AB, BB, X
```

```
SUBROUTINE SBGST_64(VECT, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],
                   X, [LDX], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDX, INFO
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:, :) :: AB, BB, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssbgst(char vect, char uplo, int n, int ka, int kb,
            float *ab, int ldab, float *bb, int ldbb, float
            *x, int ldx, int *info);
```

```
void ssbgst_64(char vect, char uplo, long n, long ka, long
               kb, float *ab, long ldab, float *bb, long ldbb,
               float *x, long ldx, long *info);
```

PURPOSE

ssbgst reduces a real symmetric-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$, such that C has the same bandwidth as A.

B must have been previously factorized as $S**T*S$ by SPBSTF, using a split Cholesky factorization. A is overwritten by $C = X**T*A*X$, where $X = S**(-1)*Q$ and Q is an orthogonal matrix chosen to preserve the bandwidth of A.

ARGUMENTS

VECT (input)
 = 'N': do not form the transformation matrix X;
 = 'V': form X.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
 The number of superdiagonals of the matrix A if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KA \geq 0$.

KB (input)
 The number of superdiagonals of the matrix B if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KA \geq KB \geq 0$.

AB (input/output)
 On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $ka+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+ka)$.

On exit, the transformed matrix $X**T*A*X$, stored in the same format as A.

LDAB (input)
 The leading dimension of the array AB. $LDAB \geq KA+1$.

BB (input)
The banded factor S from the split Cholesky factorization of B, as returned by SPBSTF, stored in the first KB+1 rows of the array.

LDBB (input)
The leading dimension of the array BB. LDBB \geq KB+1.

X (output)
If VECT = 'V', the n-by-n matrix X. If VECT = 'N', the array X is not referenced.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N) if VECT = 'V'; LDX \geq 1 otherwise.

WORK (workspace)
dimension(2*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

ssbgv - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)B*x$

SYNOPSIS

```
SUBROUTINE SSBGV(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,
                LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER N, KA, KB, LDAB, LDBB, LDZ, INFO
REAL AB(LDAB,*), BB(LDBB,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSBGV_64(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,
                   LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER*8 N, KA, KB, LDAB, LDBB, LDZ, INFO
REAL AB(LDAB,*), BB(LDBB,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBGV(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], W,
                Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER :: N, KA, KB, LDAB, LDBB, LDZ, INFO
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:,:) :: AB, BB, Z
```

```
SUBROUTINE SBGV_64(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],
                  W, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDZ, INFO
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:,:) :: AB, BB, Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssbgv(char jobz, char uplo, int n, int ka, int kb,
           float *ab, int ldab, float *bb, int ldbb, float
           *w, float *z, int ldz, int *info);
```

```
void ssbgv_64(char jobz, char uplo, long n, long ka, long
              kb, float *ab, long ldab, float *bb, long ldbb,
              float *w, float *z, long ldz, long *info);
```

PURPOSE

ssbgv computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$. Here A and B are assumed to be symmetric and banded, and B is also positive definite.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)

The number of superdiagonals of the matrix A if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KA \geq 0$.

KB (input)

The number of superdiagonals of the matrix B if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KB \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $ka+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+ka)$.

On exit, the contents of AB are destroyed.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq KA+1$.

BB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix B, stored in the first $kb+1$ rows of the array. The j -th column of B is stored

in the j-th column of the array BB as follows: if
UPLO = 'U', $BB(kb+1+i-j,j) = B(i,j)$ for $\max(1,j-kb) \leq i \leq j$; if UPLO = 'L', $BB(1+i-j,j) = B(i,j)$
for $j \leq i \leq \min(n, j+kb)$.

On exit, the factor S from the split Cholesky factorization $B = S^*T^*S$, as returned by SPBSTF.

LDBB (input)

The leading dimension of the array BB. LDBB \geq KB+1.

W (output)

If INFO = 0, the eigenvalues in ascending order.

Z (input)

If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with W(i). The eigenvectors are normalized so that $Z^*T^*B^*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq N.

WORK (workspace)

dimension(3*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is:
<= N: the algorithm failed to converge: i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq N$, then SPBSTF returned INFO = i: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

ssbgvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

SYNOPSIS

```
SUBROUTINE SSBGVD(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
                LDZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, KA, KB, LDAB, LDBB, LDZ, LWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL AB(LDAB,*), BB(LDBB,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSBGVD_64(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
                   LDZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, KA, KB, LDAB, LDBB, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL AB(LDAB,*), BB(LDBB,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBGVD(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], W,  
                Z, [LDZ], [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, KA, KB, LDAB, LDBB, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:, :) :: AB, BB, Z
```

```
SUBROUTINE SBGVD_64(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],  
                   W, Z, [LDZ], [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDZ, LWORK, LIWORK,  
INFO
```

```
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: AB, BB, Z
```

C INTERFACE

```
#include <sunperf.h>

void ssbgvd(char jobz, char uplo, int n, int ka, int kb,
            float *ab, int ldab, float *bb, int ldbb, float
            *w, float *z, int ldz, int *info);

void ssbgvd_64(char jobz, char uplo, long n, long ka, long
               kb, float *ab, long ldab, float *bb, long ldbb,
               float *w, float *z, long ldz, long *info);
```

PURPOSE

ssbgvd computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)B*x$. Here A and B are assumed to be symmetric and banded, and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangles of A and B are stored;
= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KA \geq 0$.

KB (input)
The number of superdiagonals of the matrix B if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KB \geq 0$.

AB (input/output)
On entry, the upper or lower triangle of the sym-

metric band matrix A, stored in the first ka+1 rows of the array. The j-th column of A is stored in the j-th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+ka)$.

On exit, the contents of AB are destroyed.

LDAB (input)

The leading dimension of the array AB. LDAB \geq KA+1.

BB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix B, stored in the first kb+1 rows of the array. The j-th column of B is stored in the j-th column of the array BB as follows: if UPLO = 'U', $BB(ka+1+i-j,j) = B(i,j)$ for $\max(1,j-kb) \leq i \leq j$; if UPLO = 'L', $BB(1+i-j,j) = B(i,j)$ for $j \leq i \leq \min(n,j+kb)$.

On exit, the factor S from the split Cholesky factorization $B = S^*T^*S$, as returned by SPBSTF.

LDBB (input)

The leading dimension of the array BB. LDBB \geq KB+1.

W (output)

If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with W(i). The eigenvectors are normalized so $Z^*T^*B^*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $N \leq 1$, LWORK \geq 1. If JOBZ = 'N' and $N > 1$, LWORK \geq 3*N. If JOBZ = 'V' and $N > 1$, LWORK \geq 1 + 5*N + 2*N**2.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if LIWORK $>$ 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If JOBZ = 'N' or $N \leq 1$, $LIWORK \geq 1$. If JOBZ = 'V' and $N > 1$, $LIWORK \geq 3 + 5*N$.

If $LIWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, and i is:
<= N: the algorithm failed to converge: i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if $INFO = N + i$, for $1 \leq i \leq N$, then SPBSTF returned $INFO = i$: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

ssbgvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)B*x$

SYNOPSIS

```
SUBROUTINE SSBGVX(JOBZ, RANGE, UPLO, N, KA, KB, AB, LDAB, BB, LDBB,
  Q, LDQ, VL, VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, IWORK, IFAIL,
  INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL AB(LDAB,*), BB(LDBB,*), Q(LDQ,*), W(*), Z(LDZ,*),
WORK(*)
```

```
SUBROUTINE SSBGVX_64(JOBZ, RANGE, UPLO, N, KA, KB, AB, LDAB, BB,
  LDBB, Q, LDQ, VL, VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, IWORK,
  IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER*8 IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL AB(LDAB,*), BB(LDBB,*), Q(LDQ,*), W(*), Z(LDZ,*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBGVX(JOBZ, RANGE, UPLO, [N], KA, KB, AB, [LDAB], BB,
  [LDBB], Q, [LDQ], VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK],
  [IWORK], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, WORK
```

```

REAL, DIMENSION(:, :) :: AB, BB, Q, Z

SUBROUTINE SBGVX_64(JOBZ, RANGE, UPLO, [N], KA, KB, AB, [LDAB], BB,
    [LDBB], Q, [LDQ], VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK],
    [IWORK], IFAIL, [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ,
INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: AB, BB, Q, Z

```

C INTERFACE

```

#include <sunperf.h>

void ssbgvx(char jobz, char range, char uplo, int n, int ka,
    int kb, float *ab, int ldab, float *bb, int ldbb,
    float *q, int ldq, float vl, float vu, int il, int
    iu, float abstol, int *m, float *w, float *z, int
    ldz, int *ifail, int *info);

void ssbgvx_64(char jobz, char range, char uplo, long n,
    long ka, long kb, float *ab, long ldab, float *bb,
    long ldbb, float *q, long ldq, float vl, float vu,
    long il, long iu, float abstol, long *m, float *w,
    float *z, long ldz, long *ifail, long *info);

```

PURPOSE

ssbgvx computes selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$. Here A and B are assumed to be symmetric and banded, and B is also positive definite. Eigenvalues and eigenvectors can be selected by specifying either all eigenvalues, a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found.
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
 The number of superdiagonals of the matrix A if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. KA >= 0.

KB (input)
 The number of superdiagonals of the matrix B if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. KB >= 0.

AB (input/output)
 On entry, the upper or lower triangle of the sym-
 metric band matrix A, stored in the first ka+1
 rows of the array. The j-th column of A is stored
 in the j-th column of the array AB as follows: if
 UPLO = 'U', AB(ka+1+i-j,j) = A(i,j) for max(1,j-
 ka)<=i<=j; if UPLO = 'L', AB(1+i-j,j) = A(i,j)
 for j<=i<=min(n,j+ka).

On exit, the contents of AB are destroyed.

LDAB (input)
 The leading dimension of the array AB. LDAB >=
 KA+1.

BB (input/output)
 On entry, the upper or lower triangle of the sym-
 metric band matrix B, stored in the first kb+1
 rows of the array. The j-th column of B is stored
 in the j-th column of the array BB as follows: if
 UPLO = 'U', BB(ka+1+i-j,j) = B(i,j) for max(1,j-
 kb)<=i<=j; if UPLO = 'L', BB(1+i-j,j) = B(i,j)
 for j<=i<=min(n,j+kb).

On exit, the factor S from the split Cholesky fac-
 torization $B = S^*T^*S$, as returned by SPBSTF.

LDBB (input)
 The leading dimension of the array BB. LDBB >=
 KB+1.

Q (output)
 If JOBZ = 'V', the n-by-n matrix used in the
 reduction of $A*x = (\text{lambda})*B*x$ to standard form,
 i.e. $C*x = (\text{lambda})*x$, and consequently C to tri-
 diagonal form. If JOBZ = 'N', the array Q is not
 referenced.

LDQ (input)
 The leading dimension of the array Q. If JOBZ =
 'N', LDQ >= 1. If JOBZ = 'V', LDQ >= max(1,N).

VL (input)
 If RANGE='V', the lower and upper bounds of the
 interval to be searched for eigenvalues. VL < VU.
 Not referenced if RANGE = 'A' or 'I'.

VU (input)
 See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2 * SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

If $INFO = 0$, the eigenvalues in ascending order.

Z (input)

If JOBZ = 'V', then if $INFO = 0$, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized so $Z^* T B Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension(7*N)

IWORK (workspace/output)

dimension(5*N)

IFAIL (output)

If JOBZ = 'V', then if $INFO = 0$, the first M elements of IFAIL are zero. If $INFO > 0$, then IFAIL contains the indices of the eigenvalues that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0 : successful exit
< 0 : if INFO = -i, the i-th argument had an illegal value
<= N: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in IFAIL. > N : SPBSTF returned an error code; i.e., if INFO = N + i, for 1 <= i <= N, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

ssbmv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE SSBMV(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y,  
                INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER N, K, LDA, INCX, INCY  
REAL ALPHA, BETA  
REAL A(LDA,*), X(*), Y(*)
```

```
SUBROUTINE SSBMV_64(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y,  
                  INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, K, LDA, INCX, INCY  
REAL ALPHA, BETA  
REAL A(LDA,*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE SBMV(UPLO, [N], K, ALPHA, A, [LDA], X, [INCX], BETA,  
               Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, K, LDA, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SBMV_64(UPLO, [N], K, ALPHA, A, [LDA], X, [INCX],  
                  BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, K, LDA, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>

void ssbmv(char uplo, int n, int k, float alpha, float *a,
           int lda, float *x, int incx, float beta, float *y,
           int incy);
void ssbmv_64(char uplo, long n, long k, float alpha, float
              *a, long lda, float *x, long incx, float beta,
              float *y, long incy);
```

PURPOSE

ssbmv performs the matrix-vector operation $y := \alpha A x + \beta y$, where α and β are scalars, x and y are n element vectors and A is an n by n symmetric band matrix, with k super-diagonals.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the band matrix A is being supplied as follows:

UPLO = 'U' or 'u' The upper triangular part of A is being supplied.

UPLO = 'L' or 'l' The lower triangular part of A is being supplied.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

K (input)

On entry, K specifies the number of super-diagonals of the matrix A . $K \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading ($k + 1$) by n part of the array A must contain the upper triangular band part of the symmetric matrix, supplied column by column, with the leading diagonal of the matrix in row ($k + 1$) of the array, the first super-diagonal starting at position 2 in row k , and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer the upper triangular part of a symmetric band matrix from

conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the symmetric matrix, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer the lower triangular part of a symmetric band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA \geq (k + 1). Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)). Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX \neq 0. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

ssbtrd - reduce a real symmetric band matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE SSBTRD(VECT, UPLO, N, KD, AB, LDAB, D, E, Q, LDQ, WORK,  
INFO)
```

```
CHARACTER * 1 VECT, UPLO  
INTEGER N, KD, LDAB, LDQ, INFO  
REAL AB(LDAB,*), D(*), E(*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE SSBTRD_64(VECT, UPLO, N, KD, AB, LDAB, D, E, Q, LDQ, WORK,  
INFO)
```

```
CHARACTER * 1 VECT, UPLO  
INTEGER*8 N, KD, LDAB, LDQ, INFO  
REAL AB(LDAB,*), D(*), E(*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SBTRD(VECT, UPLO, [N], KD, AB, [LDAB], D, E, Q, [LDQ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO  
INTEGER :: N, KD, LDAB, LDQ, INFO  
REAL, DIMENSION(:) :: D, E, WORK  
REAL, DIMENSION(:, :) :: AB, Q
```

```
SUBROUTINE SBTRD_64(VECT, UPLO, [N], KD, AB, [LDAB], D, E, Q, [LDQ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO  
INTEGER(8) :: N, KD, LDAB, LDQ, INFO  
REAL, DIMENSION(:) :: D, E, WORK  
REAL, DIMENSION(:, :) :: AB, Q
```

C INTERFACE

```
#include <sunperf.h>

void ssbtrd(char vect, char uplo, int n, int kd, float *ab,
           int ldab, float *d, float *e, float *q, int ldq,
           int *info);

void ssbtrd_64(char vect, char uplo, long n, long kd, float
              *ab, long ldab, float *d, float *e, float *q, long
              ldq, long *info);
```

PURPOSE

ssbtrd reduces a real symmetric band matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation: $Q^{*T} * A * Q = T$.

ARGUMENTS

VECT (input)

= 'N': do not form Q;
 = 'V': form Q;
 = 'U': update a matrix X, by forming X*Q.

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the symmetric band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. On exit, the diagonal elements of AB are overwritten by the diagonal elements of the tridiagonal matrix T; if $KD > 0$, the elements on the first superdiagonal (if UPLO = 'U') or the first subdiagonal (if UPLO = 'L') are overwritten by the off-diagonal elements of T; the rest of AB is overwritten by values generated during the reduction.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq KD+1$.

D (output)

The diagonal elements of the tridiagonal matrix T.

E (output)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = T(i,i+1)$ if UPLO = 'U'; $E(i) = T(i+1,i)$ if UPLO = 'L'.

Q (input/output)

On entry, if VECT = 'U', then Q must contain an N-by-N matrix X; if VECT = 'N' or 'V', then Q need not be set.

On exit: if VECT = 'V', Q contains the N-by-N orthogonal matrix Q; if VECT = 'U', Q contains the product $X*Q$; if VECT = 'N', the array Q is not referenced.

LDQ (input)

The leading dimension of the array Q. LDQ ≥ 1 , and LDQ $\geq N$ if VECT = 'V' or 'U'.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Modified by Linda Kaufman, Bell Labs.

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NAME

sscal - Compute $y := \alpha * y$

SYNOPSIS

```
SUBROUTINE SSCAL(N, ALPHA, Y, INCY)

INTEGER N, INCY
REAL ALPHA
REAL Y(*)

SUBROUTINE SSCAL_64(N, ALPHA, Y, INCY)

INTEGER*8 N, INCY
REAL ALPHA
REAL Y(*)
```

F95 INTERFACE

```
SUBROUTINE SCAL([N], ALPHA, Y, [INCY])

INTEGER :: N, INCY
REAL :: ALPHA
REAL, DIMENSION(:) :: Y

SUBROUTINE SCAL_64([N], ALPHA, Y, [INCY])

INTEGER(8) :: N, INCY
REAL :: ALPHA
REAL, DIMENSION(:) :: Y
```

C INTERFACE

```
#include <sunperf.h>

void sscal(int n, float alpha, float *y, int incy);

void sscal_64(long n, float alpha, float *y, long incy);
```

PURPOSE

sscal Compute $y := \text{alpha} * y$ where alpha is a scalar and y is an n-vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * INCY). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. This routine returns immediately if INCY is less than or equal to zero. Unchanged on exit.

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NAME

ssctr - Scatters elements from x into y.

SYNOPSIS

```
SUBROUTINE SSCTR(NZ, X, INDX, Y)

REAL X(*), Y(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE SSCTR_64(NZ, X, INDX, Y)

REAL X(*), Y(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE SCTR([NZ], X, INDX, Y)

REAL, DIMENSION(:) :: X, Y
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE SCTR_64([NZ], X, INDX, Y)

REAL, DIMENSION(:) :: X, Y
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

SSCTR - Scatters the components of a sparse vector x stored in compressed form into specified components of a vector y in full storage form.

```
do i = 1, n
  y(indx(i)) = x(i)
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector containing the values to be scattered from
compressed form into full storage form. Unchanged
on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

Y (output)

Vector whose elements specified by indx have been
set to the corresponding entries of x. Only the
elements corresponding to the indices in indx have
been modified.

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NAME

sskymm - Skyline format matrix-matrix multiply

SYNOPSIS

```

SUBROUTINE SSKYMM( TRANSA, M, N, K, ALPHA, DESCRA,
*               VAL, PNTR,
*               B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER        TRANSA, M, N, K, DESCRA(5),
*               LDB, LDC, LWORK
INTEGER        PNTR(*),
REAL           ALPHA, BETA
REAL           VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE SSKYMM_64( TRANSA, M, N, K, ALPHA, DESCRA,
*               VAL, PNTR,
*               B, LDB, BETA, C, LDC, WORK, LWORK )
INTEGER*8      TRANSA, M, N, K, DESCRA(5),
*               LDB, LDC, LWORK
INTEGER*8      PNTR(*),
REAL           ALPHA, BETA
REAL           VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

```

where NNZ = PNTR(K+1)-PNTR(1) (upper triangular)
NNZ = PNTR(M+1)-PNTR(1) (lower triangular)
PNTR() size = (K+1) (upper triangular)
PNTR() size = (M+1) (lower triangular)

F95 INTERFACE

```

SUBROUTINE SKYMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL,
*               PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER        TRANSA, M, K
INTEGER, DIMENSION(:) :: DESCRA, PNTR
REAL           ALPHA, BETA
REAL, DIMENSION(:) :: VAL
REAL, DIMENSION(:, :) :: B, C

SUBROUTINE SKYMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL,
*               PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])

```

```

INTEGER*8      TRANSA, M, K
INTEGER*8, DIMENSION(:) :: DESCRA, PNTR
REAL          ALPHA, BETA
REAL, DIMENSION(:) :: VAL
REAL, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>
void sskymm (int transa, int m, int n, int k, float alpha,
int *descra, float *val, int *pntr, float *b, int ldb, float
beta, float *c, int ldc);

void sskymm_64 (long transa, long m, long n, long k,
float alpha, long *descra, float *val, long *pntr,
float *b, long ldb, float beta, float *c, long ldc);

```

DESCRIPTION

sskymm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
 (' indicates matrix transpose),
 A is an M-by-K sparse matrix represented in the skyline format,
 alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, integer K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array. DESCRA(1) matrix structure 0 : general (NOT SUPPORTED) 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular

```

4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array consisting of the
nonzeros of A in skyline profile form.
Row-oriented if DESCRA(2) = 1 (lower triangular),
column oriented if DESCRA(2) = 2 (upper triangular).
Unchanged on exit.

PNTR (input)    On entry, INDX is an integer array of length
M+1 (lower triangular) or K+1 (upper triangular)
such that PNTR(I)-PNTR(1)+1 points to the
location in VAL of the first element of the skyline
profile in row (column) I. Unchanged on exit.

B (input)      Array of DIMENSION ( LDB, N ).
Before entry with TRANSA = 0, the leading k by n
part of the array B must contain the matrix B, otherwise
the leading m by n part of the array B must contain the
matrix B. Unchanged on exit.

LDB (input)    On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input)   On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION ( LDC, N ).
Before entry with TRANSA = 0, the leading m by n
part of the array C must contain the matrix C, otherwise
the leading k by n part of the array C must contain the
matrix C. On exit, the array C is overwritten by the matrix
( alpha*op( A ) * B + beta*C ).

LDC (input)    On entry, LDC specifies the first dimension of C as declared
in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

The SKY data structure is not supported for a general matrix structure (*DESCRA*(1)=0).

Also not supported:

1. lower triangular matrix A of size m by n where $m > n$
2. upper triangular matrix A of size m by n where $m < n$

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NAME

sskysm - Skyline format triangular solve

SYNOPSIS

```
SUBROUTINE SSKYSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, PNTR,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, M, N, UNITD, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER PNTR(*),  
REAL ALPHA, BETA  
REAL DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE SSKYSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, PNTR,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, M, N, UNITD, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER*8 PNTR(*),  
REAL ALPHA, BETA  
REAL DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTR(M+1)-PNTR(1)
PNTR() size = (M+1)

F95 INTERFACE

```
SUBROUTINE SKYSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,  
* PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, M, UNITD  
INTEGER, DIMENSION(:) :: DESCRA, PNTR  
REAL ALPHA, BETA  
REAL, DIMENSION(:) :: VAL, DV  
REAL, DIMENSION(:, :) :: B, C  
  
SUBROUTINE SKYSM_64( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA,  
* VAL, PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, M, UNITD  
INTEGER*8, DIMENSION(:) :: DESCRA, PNTR
```

```

REAL    ALPHA, BETA
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void sskysm (int transa, int m, int n, int unitd, float *dv,
float alpha, int *descra, float *val, int *pntr, float *b,
int ldb, float beta, float *c, int ldc);
void sskysm_64 (long transa, long m, long n, long unitd,
float *dv, float alpha, long *descra, float *val, long
*pntr, float *b, long ldb, float beta, float *c, long ldc);

```

DESCRIPTION

sskysm performs one of the matrix-matrix operations

```

C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,

```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the skyline format and op(A) is one of

```

op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).

```

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, integer UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row or column scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the diagonal entries of the scaling matrix D.

If UNITD is 4, DV contains diagonal matrix by which the rows (columns) have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array.
DESCRA(1) matrix structure
0 : general (NOT SUPPORTED)
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-unit
1 : unit

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL contains the nonzeros of A in skyline profile form. Row-oriented if DESCRA(2) = 1 (lower triangular), column oriented if DESCRA(2) = 2 (upper triangular). Unchanged on exit if UNITD is not 4. Otherwise, VAL contains entries of D*A or A*D (see section NOTES for further details).

PNTR (input) On entry, INDX is an integer array of length M+1 such that PNTR(I)-PNTR(1)+1 points to the location in VAL of the first element of the skyline profile in row (column) I. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger.
For optimum performance on multiple processors, LWORK
>=M*N_CPUS where N_CPUS is the maximum number of
processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the
routine only calculates the optimum size of the WORK array,
returns this value as the first entry of the WORK array,
and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is
fully compatible with NIST FORTRAN Sparse Blas but the sources are different.
Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas.
Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS)
Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included
in this routine. Such tests must be performed before calling
this routine.

2. If UNITD =4, the routine scales the rows of A if
DESCRA(2)=1 (lower triangular), and the columns of A if
DESCRA(2)=2 (upper triangular) such that their 2-norms are
one. The scaling may improve the accuracy of the computed
solution. Corresponding entries of VAL are changed only in
this particular case. On exit, DV matrix stored as a vector
contains the diagonal matrix by which the rows (columns)
have been scaled. UNITD=2 if *DESCRA*(2)=1 and UNITD=3 if
DESCRA(2)=2 should be used for the next calls to the routine
with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed
successfully, otherwise *WORK*(1) = -i where i is the row
(column) number which 2-norm is exactly zero.

3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are
each used with the mathematical value 1. The entries of the
main diagonal in the skyline representation of a sparse
matrix don't need to be referenced in this usage but they
need to be 1.0 if they are referenced. However if UNITD=4,
the unit diagonal elements with the mathematical value 1
MUST be referenced in the skyline representation.

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NAME

sspcon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric packed matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by SSPTRF

SYNOPSIS

```
SUBROUTINE SSPCON(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, IWORK2,  
INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
INTEGER IPIVOT(*), IWORK2(*)  
REAL ANORM, RCOND  
REAL A(*), WORK(*)
```

```
SUBROUTINE SSPCON_64(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, IWORK2,  
INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*), IWORK2(*)  
REAL ANORM, RCOND  
REAL A(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPCON(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [IWORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, IWORK2  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: A, WORK
```

```
SUBROUTINE SPCON_64(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK],  
[IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO
```

```
INTEGER(8), DIMENSION(:) :: IPIVOT, IWORK2
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: A, WORK
```

C INTERFACE

```
#include <sunperf.h>
void sspcon(char uplo, int n, float *a, int *ipivot, float
            anorm, float *rcond, int *info);

void sspcon_64(char uplo, long n, float *a, long *ipivot,
              float anorm, float *rcond, long *info);
```

PURPOSE

sspcon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric packed matrix A using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by SSPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U*D*U^{**T}$;
= 'L': Lower triangular, form is $A = L*D*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) Real array, dimension $(N*(N+1)/2)$ The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by SSPTRF, stored as a packed triangular matrix.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by SSPTRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

Real array, dimension $(2*N)$

IWORK2 (workspace)

Integer array, dimension $(2*N)$

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sspev - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

SYNOPSIS

```
SUBROUTINE SSPEV(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, LDZ, INFO  
REAL AP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSPEV_64(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, LDZ, INFO  
REAL AP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPEV(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, LDZ, INFO  
REAL, DIMENSION(:) :: AP, W, WORK  
REAL, DIMENSION(:,) :: Z
```

```
SUBROUTINE SPEV_64(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, LDZ, INFO  
REAL, DIMENSION(:) :: AP, W, WORK  
REAL, DIMENSION(:,) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sspev(char jobz, char uplo, int n, float *ap, float *w,  
          float *z, int ldz, int *info);
```

```
void sspev_64(char jobz, char uplo, long n, float *ap, float  
             *w, float *z, long ldz, long *info);
```

PURPOSE

sspev computes all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)

Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, AP is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

W (output)

Real array, dimension (N) If INFO = 0, the eigenvalues in ascending order.

Z (output)

Real array, dimension (LDZ, N) If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace)

Real array, dimension(3*N)

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

sspevd - compute all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

SYNOPSIS

```
SUBROUTINE SSPEVD(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, LWORK, IWORK,
                 LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER N, LDZ, LWORK, LIWORK, INFO
INTEGER IWORK(*)
REAL AP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSPEVD_64(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, LWORK,
                    IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER*8 N, LDZ, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
REAL AP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPEVD(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [LWORK],
                 [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER :: N, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: AP, W, WORK
REAL, DIMENSION(:,) :: Z
```

```
SUBROUTINE SPEVD_64(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [LWORK],
                   [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER(8) :: N, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: AP, W, WORK
REAL, DIMENSION(:,) :: Z
```

C INTERFACE

```
#include <sunperf.h>

void sspevd(char jobz, char uplo, int n, float *ap, float
            *w, float *z, int ldz, int *info);
void sspevd_64(char jobz, char uplo, long n, float *ap,
               float *w, float *z, long ldz, long *info);
```

PURPOSE

sspevd computes all the eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)
Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, AP is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

W (output)
Real array, dimension (N) If INFO = 0, the eigenvalues in ascending order.

Z (input) Real array, dimension (LDZ, N) If JOBZ = 'V', then

if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

Real array, dimension (LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $N \leq 1$, LWORK must be at least 1. If JOBZ = 'N' and $N > 1$, LWORK must be at least $2*N$. If JOBZ = 'V' and $N > 1$, LWORK must be at least $1 + 6*N + N**2$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

Integer array, dimension (LIWORK) On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If JOBZ = 'N' or $N \leq 1$, LIWORK must be at least 1. If JOBZ = 'V' and $N > 1$, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

sspevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage

SYNOPSIS

```
SUBROUTINE SSPEVX(JOBZ, RANGE, UPLO, N, AP, VL, VU, IL, IU, ABTOL,
                 NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, IL, IU, NFOUND, LDZ, INFO
INTEGER IWORK2(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL AP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSPEVX_64(JOBZ, RANGE, UPLO, N, AP, VL, VU, IL, IU, ABTOL,
                   NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, IL, IU, NFOUND, LDZ, INFO
INTEGER*8 IWORK2(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL AP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPEVX(JOBZ, RANGE, UPLO, [N], AP, VL, VU, IL, IU, ABTOL,
                [NFOUND], W, Z, [LDZ], [WORK], [IWORK2], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK2, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: AP, W, WORK
REAL, DIMENSION(:, :) :: Z
```

```
SUBROUTINE SPEVX_64(JOBZ, RANGE, UPLO, [N], AP, VL, VU, IL, IU, ABTOL,
                   [NFOUND], W, Z, [LDZ], [WORK], [IWORK2], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK2, IFAIL
```

```
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: AP, W, WORK
REAL, DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
void sspevx(char jobz, char range, char uplo, int n, float
            *ap, float vl, float vu, int il, int iu, float
            abtol, int *nfound, float *w, float *z, int ldz,
            int *ifail, int *info);

void sspevx_64(char jobz, char range, char uplo, long n,
               float *ap, float vl, float vu, long il, long iu,
               float abtol, long *nfound, float *w, float *z,
               long ldz, long *ifail, long *info);
```

PURPOSE

sspevx computes selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A in packed storage. Eigenvalues/vectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
= 'A': all eigenvalues will be found;
= 'V': all eigenvalues in the half-open interval (VL,VU] will be found; = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)
Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, AP is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and

first subdiagonal of T overwrite the corresponding elements of A.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing AP to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2 * SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)

Real array, dimension (N) If $INFO = 0$, the selected eigenvalues in ascending order.

Z (output)

Real array, dimension (LDZ, max(1,M)) If $JOBZ = 'V'$, then if $INFO = 0$, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. If an eigenvector fails to converge, then that column of Z con-

tains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, \text{NFOUND})$ columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq $\max(1, N)$.

WORK (workspace)

Real array, dimension(8*N)

IWORK2 (workspace)

Integer array, dimension (5*N)

IFAIL (output)

Integer array, dimension (N) If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

sspgst - reduce a real symmetric-definite generalized eigenproblem to standard form, using packed storage

SYNOPSIS

```
SUBROUTINE SSPGST(ITYPE, UPLO, N, AP, BP, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER ITYPE, N, INFO  
REAL AP(*), BP(*)
```

```
SUBROUTINE SSPGST_64(ITYPE, UPLO, N, AP, BP, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 ITYPE, N, INFO  
REAL AP(*), BP(*)
```

F95 INTERFACE

```
SUBROUTINE SPGST(ITYPE, UPLO, [N], AP, BP, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: ITYPE, N, INFO  
REAL, DIMENSION(:) :: AP, BP
```

```
SUBROUTINE SPGST_64(ITYPE, UPLO, [N], AP, BP, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: ITYPE, N, INFO  
REAL, DIMENSION(:) :: AP, BP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sspgst(int itype, char uplo, int n, float *ap, float  
          *bp, int *info);
```

```
void sspgst_64(long itype, char uplo, long n, float *ap,  
              float *bp, long *info);
```

PURPOSE

sspgst reduces a real symmetric-definite generalized eigenproblem to standard form, using packed storage.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $\text{inv}(U^{**T})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{**T})$

If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U^{**T}$ or $L^{**T}*A*L$.

B must have been previously factorized as $U^{**T}*U$ or $L*L^{**T}$ by `SPTRF`.

ARGUMENTS

`ITYPE` (input)
= 1: compute $\text{inv}(U^{**T})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{**T})$;
= 2 or 3: compute $U*A*U^{**T}$ or $L^{**T}*A*L$.

`UPLO` (input)
= 'U': Upper triangle of A is stored and B is factored as $U^{**T}*U$; = 'L': Lower triangle of A is stored and B is factored as $L*L^{**T}$.

`N` (input) The order of the matrices A and B . $N \geq 0$.

`AP` (input/output)
Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A , packed columnwise in a linear array. The j -th column of A is stored in the array `AP` as follows:
if `UPLO = 'U'`, $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if `UPLO = 'L'`, $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, if `INFO = 0`, the transformed matrix, stored in the same format as A .

`BP` (input)
Real array, dimension $(N*(N+1)/2)$ The triangular factor from the Cholesky factorization of B , stored in the same format as A , as returned by `SPTRF`.

`INFO` (output)
= 0: successful exit
< 0: if `INFO = -i`, the i -th argument had an illegal value

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NAME

sspgv - compute all the eigenvalues and, optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE SSPGV(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER ITYPE, N, LDZ, INFO
REAL AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSPGV_64(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,
INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER*8 ITYPE, N, LDZ, INFO
REAL AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPGV(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ], [WORK],
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER :: ITYPE, N, LDZ, INFO
REAL, DIMENSION(:) :: AP, BP, W, WORK
REAL, DIMENSION(:,) :: Z
```

```
SUBROUTINE SPGV_64(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ], [WORK],
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER(8) :: ITYPE, N, LDZ, INFO
REAL, DIMENSION(:) :: AP, BP, W, WORK
REAL, DIMENSION(:,) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```

void sspgv(int itype, char jobz, char uplo, int n, float
          *ap, float *bp, float *w, float *z, int ldz, int
          *info);

void sspgv_64(long itype, char jobz, char uplo, long n,
             float *ap, float *bp, float *w, float *z, long
             ldz, long *info);

```

PURPOSE

sspgv computes all the eigenvalues and, optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric, stored in packed format, and B is also positive definite.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)*B*x$
- = 2: $A*B*x = (\lambda)*x$
- = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

- = 'U': Upper triangles of A and B are stored;
- = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

AP (input/output)

Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of AP are destroyed.

BP (input/output)

Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPLO = 'U', $BP(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $BP(i + (j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U**T*U$ or $B = L*L**T$,

in the same storage format as B.

W (output)

Real array, dimension (N) If INFO = 0, the eigenvalues in ascending order.

Z (output)

Real array, dimension (LDZ, N) If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^T B Z = I$; if ITYPE = 3, $Z^T \text{inv}(B) Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

Real array, dimension(3*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: SPPTRF or SSPEV returned an error code:
<= N: if INFO = i, SSPEV failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero. > N: if INFO = n + i, for 1 \leq i \leq n, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

sspgvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE SSPGVD(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,  
                 LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER ITYPE, N, LDZ, LWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSPGVD_64(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,  
                   LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 ITYPE, N, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPGVD(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ], [WORK],  
                [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: ITYPE, N, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: AP, BP, W, WORK  
REAL, DIMENSION(:, :) :: Z
```

```
SUBROUTINE SPGVD_64(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ],  
                   [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: ITYPE, N, LDZ, LWORK, LIWORK, INFO
```

```
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: AP, BP, W, WORK
REAL, DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>

void sspgvd(int itype, char jobz, char uplo, int n, float
           *ap, float *bp, float *w, float *z, int ldz, int
           *info);

void sspgvd_64(long itype, char jobz, char uplo, long n,
              float *ap, float *bp, float *w, float *z, long
              ldz, long *info);
```

PURPOSE

sspgvd computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*B*x=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric, stored in packed format, and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

ITYPE (input)
Specifies the problem type to be solved:
= 1: $A*x = (\lambda)*B*x$
= 2: $A*B*x = (\lambda)*x$
= 3: $B*A*x = (\lambda)*x$

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPL0 (input)
= 'U': Upper triangles of A and B are stored;
= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

AP (input/output)
Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows:

if UPLO = 'U', AP(i + (j-1)*j/2) = A(i,j) for 1<=i<=j; if UPLO = 'L', AP(i + (j-1)*(2*n-j)/2) = A(i,j) for j<=i<=n.

On exit, the contents of AP are destroyed.

BP (input/output)

Real array, dimension (N*(N+1)/2) On entry, the upper or lower triangle of the symmetric matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPLO = 'U', BP(i + (j-1)*j/2) = B(i,j) for 1<=i<=j; if UPLO = 'L', BP(i + (j-1)*(2*n-j)/2) = B(i,j) for j<=i<=n.

On exit, the triangular factor U or L from the Cholesky factorization $B = U^*T*U$ or $B = L*L^*T$, in the same storage format as B.

W (output)

Real array, dimension (N) If INFO = 0, the eigenvalues in ascending order.

Z (output)

Real array, dimension (LDZ, N) If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^*T*B*Z = I$; if ITYPE = 3, $Z^*T*inv(B)*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

WORK (workspace/output)

Real array, dimension (LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $N \leq 1$, LWORK >= 1. If JOBZ = 'N' and $N > 1$, LWORK >= 2*N. If JOBZ = 'V' and $N > 1$, LWORK >= 1 + 6*N + 2*N**2.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

Integer array, dimension (LIWORK) On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If JOBZ = 'N' or $N \leq 1$, LIWORK >= 1. If JOBZ = 'V' and $N > 1$, LIWORK >= 3 + 5*N.

If LIWORK = -1, then a workspace query is assumed;

the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: SPPTRF or SSPEVD returned an error code:
<= N: if INFO = i, SSPEVD failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

sspgvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE SSPGVX(ITYPE, JOBZ, RANGE, UPLO, N, AP, BP, VL, VU, IL,
  IU, ABSTOL, M, W, Z, LDZ, WORK, IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSPGVX_64(ITYPE, JOBZ, RANGE, UPLO, N, AP, BP, VL, VU, IL,
  IU, ABSTOL, M, W, Z, LDZ, WORK, IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER*8 IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL AP(*), BP(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPGVX(ITYPE, JOBZ, RANGE, UPLO, [N], AP, BP, VL, VU, IL,
  IU, ABSTOL, M, W, Z, [LDZ], [WORK], [IWORK], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: AP, BP, W, WORK
REAL, DIMENSION(:, :) :: Z
```

```
SUBROUTINE SPGVX_64(ITYPE, JOBZ, RANGE, UPLO, [N], AP, BP, VL, VU,
  IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [IWORK], IFAIL, [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: AP, BP, W, WORK
REAL, DIMENSION(:,:) :: Z

```

C INTERFACE

```
#include <sunperf.h>
```

```

void sspgvx(int itype, char jobz, char range, char uplo, int
           n, float *ap, float *bp, float vl, float vu, int
           il, int iu, float abstol, int *m, float *w, float
           *z, int ldz, int *ifail, int *info);

```

```

void sspgvx_64(long itype, char jobz, char range, char uplo,
              long n, float *ap, float *bp, float vl, float vu,
              long il, long iu, float abstol, long *m, float *w,
              float *z, long ldz, long *ifail, long *info);

```

PURPOSE

sspgvx computes selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric, stored in packed storage, and B is also positive definite. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)*B*x$
- = 2: $A*B*x = (\lambda)*x$
- = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

- = 'A': all eigenvalues will be found.
- = 'V': all eigenvalues in the half-open interval $(VL, VU]$ will be found.
- = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)

- = 'U': Upper triangle of A and B are stored;
- = 'L': Lower triangle of A and B are stored.

N (input) The order of the matrix pencil (A,B). $N \geq 0$.

AP (input/output)

Real array, dimension $(N*(N+1)/2)$ On entry, the

upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of AP are destroyed.

BP (input/output)

Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPLO = 'U', $BP(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $BP(i + (j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U**T*U$ or $B = L*L**T$, in the same storage format as B.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|) ,$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2*SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

Real array, dimension (N) On normal exit, the first M elements contain the selected eigenvalues in ascending order.

Z (output)

Real array, dimension (LDZ, max(1,M)) If JOBZ = 'N', then Z is not referenced. If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^T B Z = I$; if ITYPE = 3, $Z^T \text{inv}(B) Z = I$.

If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. Note: the user must ensure that at least max(1,M) columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace)

Real array, dimension(8*N)

IWORK (workspace)

INTEGER array, dimension(5*N)

IFAIL (output)

INTEGER array, dimension (N) If JOBZ = 'V', then if INFO = 0, the first M elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: SPPTRF or SSPEVX returned an error code:
<= N: if INFO = i, SSPEVX failed to converge; i eigenvectors failed to converge. Their indices are stored in array IFAIL. > N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

sspmv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE SSPMV(UPLO, N, ALPHA, A, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INCX, INCY  
REAL ALPHA, BETA  
REAL A(*), X(*), Y(*)
```

```
SUBROUTINE SSPMV_64(UPLO, N, ALPHA, A, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INCX, INCY  
REAL ALPHA, BETA  
REAL A(*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE SPMV(UPLO, N, ALPHA, A, X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: A, X, Y
```

```
SUBROUTINE SPMV_64(UPLO, N, ALPHA, A, X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: A, X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sspmv(char uplo, int n, float alpha, float *a, float  
*x, int incx, float beta, float *y, int incy);
```

```
void sspmv_64(char uplo, long n, float alpha, float *a,
             float *x, long incx, float beta, float *y, long
             incy);
```

PURPOSE

sspmv performs the matrix-vector operation $y := \alpha A x + \beta y$, where α and β are scalars, x and y are n element vectors and A is an n by n symmetric matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array A as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in A .

UPLO = 'L' or 'l' The lower triangular part of A is supplied in A .

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

$((n*(n+1))/2)$. Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular part of the symmetric matrix packed sequentially, column by column, so that $A(1)$ contains $a(1,1)$, $A(2)$ and $A(3)$ contain $a(1,2)$ and $a(2,2)$ respectively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular part of the symmetric matrix packed sequentially, column by column, so that $A(1)$ contains $a(1,1)$, $A(2)$ and $A(3)$ contain $a(2,1)$ and $a(3,1)$ respectively, and so on. Unchanged on exit.

X (input)

$(1 + (n-1)*\text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . $\text{INCX} \neq 0$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

sspr - perform the symmetric rank 1 operation $A := \alpha x x' + A$

SYNOPSIS

```
SUBROUTINE SSPR(UPLO, N, ALPHA, X, INCX, A)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INCX  
REAL ALPHA  
REAL X(*), A(*)
```

```
SUBROUTINE SSPR_64(UPLO, N, ALPHA, X, INCX, A)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INCX  
REAL ALPHA  
REAL X(*), A(*)
```

F95 INTERFACE

```
SUBROUTINE SPR(UPLO, N, ALPHA, X, [INCX], A)
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INCX  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X, A
```

```
SUBROUTINE SPR_64(UPLO, N, ALPHA, X, [INCX], A)
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INCX  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X, A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sspr(char uplo, int n, float alpha, float *x, int incx,  
          float *a);
```

```
void sspr_64(char uplo, long n, float alpha, float *x, long
            incx, float *a);
```

PURPOSE

sspr performs the symmetric rank 1 operation $A := \alpha x x^T + A$, where α is a real scalar, x is an n element vector and A is an n by n symmetric matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array A as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in A .

UPLO = 'L' or 'l' The lower triangular part of A is supplied in A .

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . $\text{INCX} \neq 0$. Unchanged on exit.

A (input/output)

$((n * (n + 1)) / 2)$. Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular part of the symmetric matrix packed sequentially, column by column, so that $A(1)$ contains $a(1, 1)$, $A(2)$ and $A(3)$ contain $a(1, 2)$ and $a(2, 2)$ respectively, and so on. On exit, the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular part of the symmetric matrix packed sequentially, column by column, so that $A(1)$ contains $a(1, 1)$, $A(2)$ and $A(3)$ contain $a(2, 1)$ and $a(3, 1)$ respectively, and so on.

On exit, the array A is overwritten by the lower triangular part of the updated matrix.

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NAME

sspr2 - perform the symmetric rank 2 operation $A := \alpha x x' + \alpha y y' + A$

SYNOPSIS

```
SUBROUTINE SSPR2(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INCX, INCY  
REAL ALPHA  
REAL X(*), Y(*), AP(*)
```

```
SUBROUTINE SSPR2_64(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INCX, INCY  
REAL ALPHA  
REAL X(*), Y(*), AP(*)
```

F95 INTERFACE

```
SUBROUTINE SPR2(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], AP)
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INCX, INCY  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X, Y, AP
```

```
SUBROUTINE SPR2_64(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], AP)
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INCX, INCY  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X, Y, AP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sspr2(char uplo, int n, float alpha, float *x, int  
incx, float *y, int incy, float *ap);
```

```
void sspr2_64(char uplo, long n, float alpha, float *x, long
    incx, float *y, long incy, float *ap);
```

PURPOSE

sspr2 performs the symmetric rank 2 operation $A := \alpha x x^T + \alpha y y^T + A$, where alpha is a scalar, x and y are n element vectors and A is an n by n symmetric matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array A as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in AP.

UPLO = 'L' or 'l' The lower triangular part of A is supplied in AP.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

Real array, dimension $(1 + (n - 1) \cdot \text{abs}(\text{INCX}))$
Before entry, the incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

Real array, dimension $(1 + (n - 1) \cdot \text{abs}(\text{INCY}))$
Before entry, the incremented array Y must contain the n element vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

AP (input/output)

Real array, dimension $((n \cdot (n + 1)) / 2)$ Before entry with UPLO = 'U' or 'u', the array AP must contain the upper triangular part of the symmetric matrix packed sequentially, column by column, so that AP(1) contains a(1, 1), AP(2) and AP(3

) contain $a(1, 2)$ and $a(2, 2)$ respectively, and so on. On exit, the array A is overwritten by the upper triangular part of the updated matrix. Before entry with `UPLO = 'L' or 'l'`, the array AP must contain the lower triangular part of the symmetric matrix packed sequentially, column by column, so that `AP(1)` contains $a(1, 1)$, `AP(2)` and `AP(3)` contain $a(2, 1)$ and $a(3, 1)$ respectively, and so on. On exit, the array AP is overwritten by the lower triangular part of the updated matrix.

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NAME

ssprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE SSPRFS(UPLO, N, NRHS, AP, AF, IPIVOT, B, LDB, X, LDX, FERR,  
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, LDX, INFO  
INTEGER IPIVOT(*), WORK2(*)  
REAL AP(*), AF(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),  
WORK(*)
```

```
SUBROUTINE SSPRFS_64(UPLO, N, NRHS, AP, AF, IPIVOT, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*), WORK2(*)  
REAL AP(*), AF(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),  
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPRFS(UPLO, [N], [NRHS], AP, AF, IPIVOT, B, [LDB], X, [LDX],  
  FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, WORK2  
REAL, DIMENSION(:) :: AP, AF, FERR, BERR, WORK  
REAL, DIMENSION(:,) :: B, X
```

```
SUBROUTINE SPRFS_64(UPLO, [N], [NRHS], AP, AF, IPIVOT, B, [LDB], X, [LDX],  
  FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

```

INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL, DIMENSION(:) :: AP, AF, FERR, BERR, WORK
REAL, DIMENSION(:, :) :: B, X

```

C INTERFACE

```

#include <sunperf.h>
void ssprfs(char uplo, int n, int nrhs, float *ap, float
            *af, int *ipivot, float *b, int ldb, float *x, int
            ldX, float *ferr, float *berr, int *info);

void ssprfs_64(char uplo, long n, long nrhs, float *ap,
               float *af, long *ipivot, float *b, long ldb, float
               *x, long ldX, float *ferr, float *berr, float
               *work, long *iwork, long *info);

```

PURPOSE

ssprfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) Real array, dimension $(N*(N+1)/2)$ The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

AF (input)
 Real array, dimension $(N*(N+1)/2)$ The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^T$ or $A = L*D*L^T$ as computed by SSPTRF, stored as a packed triangular matrix.

IPIVOT (input)
 Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by SSPTRF.

B (input) Real array, dimension (LDB, NRHS) The right hand

side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)

Real array, dimension (LDX,NRHS) On entry, the solution matrix X, as computed by SSPTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

Real array, dimension (NRHS) The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

Real array, dimension (NRHS) The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

Real array, dimension(3*N)

WORK2 (workspace)

Integer array, dimension(N)

INFO (output) Integer

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

sspsv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SSPSV(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)  
REAL AP(*), B(LDB,*)
```

```
SUBROUTINE SSPSV_64(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)  
REAL AP(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SPSV(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: AP  
REAL, DIMENSION(:, :) :: B
```

```
SUBROUTINE SPSV_64(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: AP  
REAL, DIMENSION(:, :) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sspsv(char uplo, int n, int nrhs, float *ap, int
           *ipivot, float *b, int ldb, int *info);
```

```
void sspsv_64(char uplo, long n, long nrhs, float *ap, long
              *ipivot, float *b, long ldb, long *info);
```

PURPOSE

sspsv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{**T}$, if UPLO = 'U', or

$A = L * D * L^{**T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

AP (input/output)

Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by SSPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (output)

Integer array, dimension (N) Details of the interchanges and the block structure of D, as determined by SSPTRF. If IPIVOT(k) > 0, then rows

and columns k and $\text{IPIVOT}(k)$ were interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $\text{UPL}O = 'U'$ and $\text{IPIVOT}(k) = \text{IPIVOT}(k-1) < 0$, then rows and columns $k-1$ and $-\text{IPIVOT}(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $\text{UPL}O = 'L'$ and $\text{IPIVOT}(k) = \text{IPIVOT}(k+1) < 0$, then rows and columns $k+1$ and $-\text{IPIVOT}(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output)

Real array, dimension (LDB,NRHS) On entry, the N-by-NRHS right hand side matrix B. On exit, if $\text{INFO} = 0$, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $\text{LDB} \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i-th argument had an illegal value
> 0: if $\text{INFO} = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, $\text{UPL}O = 'U'$:

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13 a14
  a22 a23 a24
    a33 a34   (aij = aji)
      a44
```

Packed storage of the upper triangle of A:

```
AP = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

sspsvx - use the diagonal pivoting factorization $A = U^*D*U^{**T}$ or $A = L*D*L^{**T}$ to compute the solution to a real system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE SSPSVX(FACT, UPLO, N, NRHS, AP, AF, IPIVOT, B, LDB, X, LDX,
                 RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*), WORK2(*)
REAL RCOND
REAL AP(*), AF(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),
WORK(*)
```

```
SUBROUTINE SSPSVX_64(FACT, UPLO, N, NRHS, AP, AF, IPIVOT, B, LDB, X,
                    LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*), WORK2(*)
REAL RCOND
REAL AP(*), AF(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*),
WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPSVX(FACT, UPLO, [N], [NRHS], AP, AF, IPIVOT, B, [LDB], X,
                [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT, WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: AP, AF, FERR, BERR, WORK
REAL, DIMENSION(:, :) :: B, X
```

```
SUBROUTINE SPSVX_64(FACT, UPLO, [N], [NRHS], AP, AF, IPIVOT, B, [LDB], X,  
    [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2  
REAL :: RCOND  
REAL, DIMENSION(:) :: AP, AF, FERR, BERR, WORK  
REAL, DIMENSION(:, :) :: B, X
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sspsvx(char fact, char uplo, int n, int nrhs, float  
    *ap, float *af, int *ipivot, float *b, int ldb,  
    float *x, int ldx, float *rcond, float *ferr,  
    float *berr, int *info);
```

```
void sspsvx_64(char fact, char uplo, long n, long nrhs,  
    float *ap, float *af, long *ipivot, float *b, long  
    ldb, float *x, long ldx, float *rcond, float  
    *ferr, float *berr, long *info);
```

PURPOSE

SSPSVX uses the diagonal pivoting factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ to compute the solution to a real system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'N', the diagonal pivoting method is used to factor A as

$A = U * D * U^{**T}$, if UPLO = 'U', or
 $A = L * D * L^{**T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices and D is symmetric and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with INFO = i. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

3. The system of equations is solved for X using the fac-

tored form
of A.
4. Iterative refinement is applied to improve the computed
solution
matrix and calculate error bounds and backward error
estimates
for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. AP, AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

AP (input)

Real array, dimension $(N*(N+1)/2)$ The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j < i \leq n$. See below for further details.

AF (input or output)

Real array, dimension $(N*(N+1)/2)$ If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by SSPTRF, stored as a packed triangular matrix in the same storage format as A.

If FACT = 'N', then AF is an output argument and on exit contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by SSPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (input or output)

Integer array, dimension (N) If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by SSPTRF. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were

interchanged and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

If $FACT = 'N'$, then $IPIVOT$ is an output argument and on exit contains details of the interchanges and the block structure of D , as determined by $SSPTRF$.

B (input) Real array, dimension $(LDB, NRHS)$ The N -by- $NRHS$ right hand side matrix B .

LDB (input)
The leading dimension of the array B . $LDB \geq \max(1, N)$.

X (output)
Real array, dimension $(LDX, NRHS)$ If $INFO = 0$ or $INFO = N+1$, the N -by- $NRHS$ solution matrix X .

LDX (input)
The leading dimension of the array X . $LDX \geq \max(1, N)$.

RCOND (output)
The estimate of the reciprocal condition number of the matrix A . If $RCOND$ is less than the machine precision (in particular, if $RCOND = 0$), the matrix is singular to working precision. This condition is indicated by a return code of $INFO > 0$.

FERR (output)
Real array, dimension $(NRHS)$ The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for $RCOND$, and is almost always a slight overestimate of the true error.

BERR (output)
Real array, dimension $(NRHS)$ The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)
Real array, dimension $(3*N)$

WORK2 (workspace)
Integer array, dimension (N)

INFO (output)

```
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.
```

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, $UPLO = 'U'$:

Two-dimensional storage of the symmetric matrix A:

```
  a11 a12 a13 a14
    a22 a23 a24
      a33 a34   (aij = aji)
        a44
```

Packed storage of the upper triangle of A:

```
AP = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

ssptrd - reduce a real symmetric matrix A stored in packed form to symmetric tridiagonal form T by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE SSPTRD(UPLO, N, AP, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
REAL AP(*), D(*), E(*), TAU(*)
```

```
SUBROUTINE SSPTRD_64(UPLO, N, AP, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
REAL AP(*), D(*), E(*), TAU(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRD(UPLO, [N], AP, D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
REAL, DIMENSION(:) :: AP, D, E, TAU
```

```
SUBROUTINE SPTRD_64(UPLO, [N], AP, D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
REAL, DIMENSION(:) :: AP, D, E, TAU
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssptrd(char uplo, int n, float *ap, float *d, float *e,  
           float *tau, int *info);
```

```
void ssptrd_64(char uplo, long n, float *ap, float *d, float
```

```
*e, float *tau, long *info);
```

PURPOSE

ssptrd reduces a real symmetric matrix A stored in packed form to symmetric tridiagonal form T by an orthogonal similarity transformation: $Q^*T * A * Q = T$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input)

Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors. See Further Details.

D (output)

Real array, dimension (N) The diagonal elements of the tridiagonal matrix T: $D(i) = A(i,i)$.

E (output)

Real array, dimension (N-1) The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i,i+1)$ if UPLO = 'U', $E(i) = A(i+1,i)$ if UPLO = 'L'.

TAU (output)

Real array, dimension (N-1) The scalar factors of the elementary reflectors (see Further Details).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(i+1:n) = 0$ and $v(i) = 1$; $v(1:i-1)$ is stored on exit in AP, overwriting $A(1:i-1,i+1)$, and tau is stored in TAU(i).

If UPLO = 'L', the matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(1:i) = 0$ and $v(i+1) = 1$; $v(i+2:n)$ is stored on exit in AP, overwriting $A(i+2:n,i)$, and tau is stored in TAU(i).

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NAME

ssptrf - compute the factorization of a real symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE SSPTRF(UPLO, N, AP, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
INTEGER IPIVOT(*)  
REAL AP(*)
```

```
SUBROUTINE SSPTRF_64(UPLO, N, AP, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
REAL AP(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRF(UPLO, [N], AP, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: AP
```

```
SUBROUTINE SPTRF_64(UPLO, [N], AP, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: AP
```

C INTERFACE

```
#include <sunperf.h>
```

```

void ssptrf(char uplo, int n, float *ap, int *ipivot, int
           *info);

void ssptrf_64(char uplo, long n, float *ap, long *ipivot,
              long *info);

```

PURPOSE

ssptrf computes the factorization of a real symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U^{**T} \quad \text{or} \quad A = L^*D^*L^{**T}$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)

Real array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L, stored as a packed triangular matrix overwriting A (see below for further details).

IPIVOT (output)

Integer array, dimension (N) Details of the interchanges and the block structure of D. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an

illegal value
 > 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

5-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

ssptri - compute the inverse of a real symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^*T$ or $A = L^*D^*L^*T$ computed by SSPTRF

SYNOPSIS

```
SUBROUTINE SSPTRI(UPLO, N, AP, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INFO  
INTEGER IPIVOT(*)  
REAL AP(*), WORK(*)
```

```
SUBROUTINE SSPTRI_64(UPLO, N, AP, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
REAL AP(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRI(UPLO, [N], AP, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: AP, WORK
```

```
SUBROUTINE SPTRI_64(UPLO, [N], AP, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: AP, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssptri(char uplo, int n, float *a, int *ipivot, int  
*info);
```

```
void ssptri_64(char uplo, long n, float *a, long *ipivot,
              long *info);
```

PURPOSE

ssptri computes the inverse of a real symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by SSPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U^*D^*U^{**T}$;
= 'L': Lower triangular, form is $A = L^*D^*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)

Real array, dimension $(N*(N+1)/2)$ On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by SSPTRF, stored as a packed triangular matrix.

On exit, if INFO = 0, the (symmetric) inverse of the original matrix, stored as a packed triangular matrix. The j-th column of $\text{inv}(A)$ is stored in the array AP as follows: if UPLO = 'U', $\text{AP}(i + (j-1)*j/2) = \text{inv}(A)(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $\text{AP}(i + (j-1)*(2n-j)/2) = \text{inv}(A)(i,j)$ for $j \leq i \leq n$.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by SSPTRF.

WORK (workspace)

Real array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

ssptrs - solve a system of linear equations $A \cdot X = B$ with a real symmetric matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^{**T}$ or $A = L \cdot D \cdot L^{**T}$ computed by SSPTRF

SYNOPSIS

```
SUBROUTINE SSPTRS(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)  
REAL AP(*), B(LDB,*)
```

```
SUBROUTINE SSPTRS_64(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)  
REAL AP(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SPTRS(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: AP  
REAL, DIMENSION(:,) :: B
```

```
SUBROUTINE SPTRS_64(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: AP  
REAL, DIMENSION(:,) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssptrs(char uplo, int n, int nrhs, float *ap, int
            *ipivot, float *b, int ldb, int *info);
```

```
void ssptrs_64(char uplo, long n, long nrhs, float *ap, long
               *ipivot, float *b, long ldb, long *info);
```

PURPOSE

ssptrs solves a system of linear equations $A \cdot X = B$ with a real symmetric matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^T$ or $A = L \cdot D \cdot L^T$ computed by SSPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U \cdot D \cdot U^T$;
= 'L': Lower triangular, form is $A = L \cdot D \cdot L^T$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

AP (input)

Real array, dimension $(N \cdot (N+1) / 2)$ The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by SSPTRF, stored as a packed triangular matrix.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by SSPTRF.

B (input/output)

Real array, dimension $(LDB, NRHS)$ On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

sstebz - compute the eigenvalues of a symmetric tridiagonal matrix T

SYNOPSIS

```
SUBROUTINE SSTEBZ(RANGE, ORDER, N, VL, VU, IL, IU, ABSTOL, D, E, M,  
                 NSPLIT, W, IBLOCK, ISPLIT, WORK, IWORK, INFO)
```

```
CHARACTER * 1 RANGE, ORDER  
INTEGER N, IL, IU, M, NSPLIT, INFO  
INTEGER IBLOCK(*), ISPLIT(*), IWORK(*)  
REAL VL, VU, ABSTOL  
REAL D(*), E(*), W(*), WORK(*)
```

```
SUBROUTINE SSTEBZ_64(RANGE, ORDER, N, VL, VU, IL, IU, ABSTOL, D, E,  
                    M, NSPLIT, W, IBLOCK, ISPLIT, WORK, IWORK, INFO)
```

```
CHARACTER * 1 RANGE, ORDER  
INTEGER*8 N, IL, IU, M, NSPLIT, INFO  
INTEGER*8 IBLOCK(*), ISPLIT(*), IWORK(*)  
REAL VL, VU, ABSTOL  
REAL D(*), E(*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEBZ(RANGE, ORDER, N, VL, VU, IL, IU, ABSTOL, D, E, M,  
                NSPLIT, W, IBLOCK, ISPLIT, [WORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: RANGE, ORDER  
INTEGER :: N, IL, IU, M, NSPLIT, INFO  
INTEGER, DIMENSION(:) :: IBLOCK, ISPLIT, IWORK  
REAL :: VL, VU, ABSTOL  
REAL, DIMENSION(:) :: D, E, W, WORK
```

```
SUBROUTINE STEBZ_64(RANGE, ORDER, N, VL, VU, IL, IU, ABSTOL, D, E, M,  
                   NSPLIT, W, IBLOCK, ISPLIT, [WORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: RANGE, ORDER  
INTEGER(8) :: N, IL, IU, M, NSPLIT, INFO  
INTEGER(8), DIMENSION(:) :: IBLOCK, ISPLIT, IWORK  
REAL :: VL, VU, ABSTOL
```

REAL, DIMENSION(:) :: D, E, W, WORK

C INTERFACE

```
#include <sunperf.h>
```

```
void sstebz(char range, char order, int n, float vl, float  
vu, int il, int iu, float abstol, float *d, float  
*e, int *m, int *nsplit, float *w, int *iblock,  
int *isplit, int *info);
```

```
void sstebz_64(char range, char order, long n, float vl,  
float vu, long il, long iu, float abstol, float  
*d, float *e, long *m, long *nsplit, float *w,  
long *iblock, long *isplit, long *info);
```

PURPOSE

sstebz computes the eigenvalues of a symmetric tridiagonal matrix T. The user may ask for all eigenvalues, all eigenvalues in the half-open interval (VL, VU], or the IL-th through IU-th eigenvalues.

To avoid overflow, the matrix must be scaled so that its largest element is no greater than $\text{overflow}^{1/2} * \text{underflow}^{1/4}$ in absolute value, and for greatest accuracy, it should not be much smaller than that.

See W. Kahan "Accurate Eigenvalues of a Symmetric Tridiagonal Matrix", Report CS41, Computer Science Dept., Stanford University, July 21, 1966.

ARGUMENTS

RANGE (input)

= 'A': ("All") all eigenvalues will be found.
= 'V': ("Value") all eigenvalues in the half-open interval (VL, VU] will be found. = 'I': ("Index") the IL-th through IU-th eigenvalues (of the entire matrix) will be found.

ORDER (input)

= 'B': ("By Block") the eigenvalues will be grouped by split-off block (see IBLOCK, ISPLIT) and ordered from smallest to largest within the block. = 'E': ("Entire matrix") the eigenvalues for the entire matrix will be ordered from smallest to largest.

N (input) The order of the tridiagonal matrix T. $N \geq 0$.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. Eigenvalues less than or equal to VL, or greater than VU, will not be returned. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
See the description of VL.

IL (input)
If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
See the description of IL.

ABSTOL (input)
The absolute tolerance for the eigenvalues. An eigenvalue (or cluster) is considered to be located if it has been determined to lie in an interval whose width is ABSTOL or less. If ABSTOL is less than or equal to zero, then $ULP*|T|$ will be used, where $|T|$ means the 1-norm of T.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero.

D (input) The n diagonal elements of the tridiagonal matrix T.

E (input) The (n-1) off-diagonal elements of the tridiagonal matrix T.

M (output)
The actual number of eigenvalues found. $0 \leq M \leq N$. (See also the description of INFO=2,3.)

NSPLIT (output)
The number of diagonal blocks in the matrix T. $1 \leq NSPLIT \leq N$.

W (output)
On exit, the first M elements of W will contain the eigenvalues. (SSTEBZ may use the remaining N-M elements as workspace.)

IBLOCK (output)
At each row/column j where E(j) is zero or small, the matrix T is considered to split into a block diagonal matrix. On exit, if INFO = 0, IBLOCK(i) specifies to which block (from 1 to the number of blocks) the eigenvalue W(i) belongs. (SSTEBZ may use the remaining N-M elements as workspace.)

ISPLIT (output)
The splitting points, at which T breaks up into submatrices. The first submatrix consists of rows/columns 1 to ISPLIT(1), the second of rows/columns ISPLIT(1)+1 through ISPLIT(2), etc., and the NSPLIT-th consists of rows/columns ISPLIT(NSPLIT-1)+1 through ISPLIT(NSPLIT)=N. (Only the first NSPLIT elements will actually be

used, but since the user cannot know a priori what value NSPLIT will have, N words must be reserved for ISPLIT.)

WORK (workspace)
dimension(4*N)

IWORK (workspace)
dimension(3*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: some or all of the eigenvalues failed to converge or were not computed:
=1 or 3: Bisection failed to converge for some eigenvalues; these eigenvalues are flagged by a negative block number. The effect is that the eigenvalues may not be as accurate as the absolute and relative tolerances. This is generally caused by unexpectedly inaccurate arithmetic. =2 or 3: RANGE='I' only: Not all of the eigenvalues IL:IU were found.
Effect: $M < IU+1-IL$
Cause: non-monotonic arithmetic, causing the Sturm sequence to be non-monotonic. Cure: recalculate, using RANGE='A', and pick out eigenvalues IL:IU. = 4: RANGE='I', and the Gershgorin interval initially used was too small. No eigenvalues were computed.

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NAME

sstedc - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method

SYNOPSIS

```
SUBROUTINE SSTEDC(COMPZ, N, D, E, Z, LDZ, WORK, LWORK, IWORK, LIWORK,
                 INFO)
```

```
CHARACTER * 1 COMPZ
INTEGER N, LDZ, LWORK, LIWORK, INFO
INTEGER IWORK(*)
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSTEDC_64(COMPZ, N, D, E, Z, LDZ, WORK, LWORK, IWORK,
                    LIWORK, INFO)
```

```
CHARACTER * 1 COMPZ
INTEGER*8 N, LDZ, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEDC(COMPZ, N, D, E, Z, [LDZ], [WORK], [LWORK], [IWORK],
                [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ
INTEGER :: N, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: D, E, WORK
REAL, DIMENSION(:,) :: Z
```

```
SUBROUTINE STEDC_64(COMPZ, N, D, E, Z, [LDZ], [WORK], [LWORK], [IWORK],
                   [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ
INTEGER(8) :: N, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
```

```
REAL, DIMENSION(:) :: D, E, WORK
REAL, DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>

void sstedc(char compz, int n, float *d, float *e, float *z,
            int ldz, int *info);
void sstedc_64(char compz, long n, float *d, float *e, float
              *z, long ldz, long *info);
```

PURPOSE

sstedc computes all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method. The eigenvectors of a full or band real symmetric matrix can also be found if SSYTRD or SSPTRD or SSBTRD has been used to reduce this matrix to tridiagonal form.

This code makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none. See SLAED3 for details.

ARGUMENTS

COMPZ (input)
= 'N': Compute eigenvalues only.
= 'I': Compute eigenvectors of tridiagonal matrix also.
= 'V': Compute eigenvectors of original dense symmetric matrix also. On entry, Z contains the orthogonal matrix used to reduce the original matrix to tridiagonal form.

N (input) The dimension of the symmetric tridiagonal matrix.
N >= 0.

D (input/output)
On entry, the diagonal elements of the tridiagonal matrix. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)
On entry, the subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input) On entry, if COMPZ = 'V', then Z contains the orthogonal matrix used in the reduction to tridiagonal form. On exit, if INFO = 0, then if COMPZ = 'V', Z contains the orthonormal eigenvectors of the original symmetric matrix, and if COMPZ = 'I',

Z contains the orthonormal eigenvectors of the symmetric tridiagonal matrix. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1.
If eigenvectors are desired, then LDZ \geq max(1,N).

WORK (workspace)

dimension (LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If COMPZ = 'N' or $N \leq 1$ then LWORK must be at least 1. If COMPZ = 'V' and $N > 1$ then LWORK must be at least $(1 + 3*N + 2*N*\lg N + 3*N**2)$, where $\lg(N)$ = smallest integer k such that $2**k \geq N$. If COMPZ = 'I' and $N > 1$ then LWORK must be at least $(1 + 4*N + N**2)$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If COMPZ = 'N' or $N \leq 1$ then LIWORK must be at least 1. If COMPZ = 'V' and $N > 1$ then LIWORK must be at least $(6 + 6*N + 5*N*\lg N)$. If COMPZ = 'I' and $N > 1$ then LIWORK must be at least $(3 + 5*N)$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: The algorithm failed to compute an eigenvalue while working on the submatrix lying in rows and columns INFO/(N+1) through mod(INFO,N+1).

FURTHER DETAILS

Based on contributions by

Jeff Rutter, Computer Science Division, University of California

at Berkeley, USA

Modified by Francoise Tisseur, University of Tennessee.

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NAME

sstegr - (a) Compute $T\text{-}\sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation

SYNOPSIS

```
SUBROUTINE SSTEGR(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M, W,  
                 Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
INTEGER N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER ISUPPZ(*), IWORK(*)  
REAL VL, VU, ABSTOL  
REAL D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSTEGR_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M,  
                   W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
INTEGER*8 N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 ISUPPZ(*), IWORK(*)  
REAL VL, VU, ABSTOL  
REAL D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEGR(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL, M,  
                W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE  
INTEGER :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: ISUPPZ, IWORK  
REAL :: VL, VU, ABSTOL  
REAL, DIMENSION(:) :: D, E, W, WORK  
REAL, DIMENSION(:,) :: Z
```

```
SUBROUTINE STEGR_64(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL,  
                   M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE
```

```

INTEGER(8) :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: D, E, W, WORK
REAL, DIMENSION(:, :) :: Z

```

C INTERFACE

```

#include <sunperf.h>
void sstegr(char jobz, char range, int n, float *d, float
            *e, float vl, float vu, int il, int iu, float
            abstol, int *m, float *w, float *z, int ldz, int
            *isuppz, int *info);

void sstegr_64(char jobz, char range, long n, float *d,
               float *e, float vl, float vu, long il, long iu,
               float abstol, long *m, float *w, float *z, long
               ldz, long *isuppz, long *info);

```

PURPOSE

sstegr b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high relative accuracy by the dqds algorithm,
(c) If there is a cluster of close eigenvalues, "choose" σ_i close to the cluster, and go to step (a),
(d) Given the approximate eigenvalue λ_j of $L_i D_i L_i^T$, compute the corresponding eigenvector by forming a rank-revealing twisted factorization.

The desired accuracy of the output can be specified by the input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB/CSD-97-971, UC Berkeley, May 1997.

Note 1 : Currently SSTEGR is only set up to find ALL the n eigenvalues and eigenvectors of T in $O(n^2)$ time

Note 2 : Currently the routine SSTEIN is called when an appropriate σ_i cannot be chosen in step (c) above. SSTEIN invokes modified Gram-Schmidt when eigenvalues are close.

Note 3 : SSTEGR works only on machines which follow ieee-754 floating-point standard in their handling of infinities and NaNs. Normal execution of SSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not conform to the ieee standard.

ARGUMENTS

```

JOBZ (input)
    = 'N': Compute eigenvalues only;
    = 'V': Compute eigenvalues and eigenvectors.

```

RANGE (input)
 = 'A': all eigenvalues will be found.
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)
 On entry, the n diagonal elements of the tridiagonal matrix T. On exit, D is overwritten.

E (input/output)
 On entry, the (n-1) subdiagonal elements of the tridiagonal matrix T in elements 1 to N-1 of E; E(N) need not be set. On exit, E is overwritten.

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 See the description of VL.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 See the description of IL.

ABSTOL (input)
 The absolute error tolerance for the eigenvalues/eigenvectors. If JOBZ = 'V', the eigenvalues and eigenvectors output have residual norms bounded by ABSTOL, and the dot products between different eigenvectors are bounded by ABSTOL. If ABSTOL is less than $N \cdot \text{EPS} \cdot |T|$, then $N \cdot \text{EPS} \cdot |T|$ will be used in its place, where EPS is the machine precision and $|T|$ is the 1-norm of the tridiagonal matrix. The eigenvalues are computed to an accuracy of $\text{EPS} \cdot |T|$ irrespective of ABSTOL. If high relative accuracy is important, set ABSTOL to DLAMCH('Safe minimum'). See Barlow and Demmel "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7 for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)
 The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)
 The first M elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix T corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least max(1,M) columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)
The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

ISUPPZ (output)
The support of the eigenvectors in Z, i.e., the indices indicating the nonzero elements in Z. The i-th eigenvector is nonzero only in elements ISUPPZ(2*i-1) through ISUPPZ(2*i).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal (and minimal) LWORK.

LWORK (input)
The dimension of the array WORK. LWORK >= max(1,18*N)
If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)
On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
The dimension of the array IWORK. LIWORK >= max(1,10*N)

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = 1, internal error in SLARRE, if INFO = 2, internal error in SLARRV.

FURTHER DETAILS

Based on contributions by
Inderjit Dhillon, IBM Almaden, USA

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NAME

sstein - compute the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration

SYNOPSIS

```
SUBROUTINE SSTEIN(N, D, E, M, W, IBLOCK, ISPLIT, Z, LDZ, WORK, IWORK,
  IFAIL, INFO)
```

```
INTEGER N, M, LDZ, INFO
INTEGER IBLOCK(*), ISPLIT(*), IWORK(*), IFAIL(*)
REAL D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSTEIN_64(N, D, E, M, W, IBLOCK, ISPLIT, Z, LDZ, WORK,
  IWORK, IFAIL, INFO)
```

```
INTEGER*8 N, M, LDZ, INFO
INTEGER*8 IBLOCK(*), ISPLIT(*), IWORK(*), IFAIL(*)
REAL D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEIN(N, D, E, M, W, IBLOCK, ISPLIT, Z, [LDZ], [WORK],
  [IWORK], IFAIL, [INFO])
```

```
INTEGER :: N, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IBLOCK, ISPLIT, IWORK, IFAIL
REAL, DIMENSION(:) :: D, E, W, WORK
REAL, DIMENSION(:, :) :: Z
```

```
SUBROUTINE STEIN_64(N, D, E, M, W, IBLOCK, ISPLIT, Z, [LDZ], [WORK],
  [IWORK], IFAIL, [INFO])
```

```
INTEGER(8) :: N, M, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IBLOCK, ISPLIT, IWORK, IFAIL
REAL, DIMENSION(:) :: D, E, W, WORK
REAL, DIMENSION(:, :) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sstein(int n, float *d, float *e, int m, float *w, int
            *iblock, int *isplit, float *z, int ldz, int
            *ifail, int *info);
```

```
void sstein_64(long n, float *d, float *e, long m, float *w,
               long *iblock, long *isplit, float *z, long ldz,
               long *ifail, long *info);
```

PURPOSE

sstein computes the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration.

The maximum number of iterations allowed for each eigenvector is specified by an internal parameter MAXITS (currently set to 5).

ARGUMENTS

N (input) The order of the matrix. $N \geq 0$.

D (input) The n diagonal elements of the tridiagonal matrix T.

E (input) The (n-1) subdiagonal elements of the tridiagonal matrix T, in elements 1 to N-1. E(N) need not be set.

M (input) The number of eigenvectors to be found. $0 \leq M \leq N$.

W (input) The first M elements of W contain the eigenvalues for which eigenvectors are to be computed. The eigenvalues should be grouped by split-off block and ordered from smallest to largest within the block. (The output array W from SSTEBSZ with ORDER = 'B' is expected here.)

IBLOCK (input)
The submatrix indices associated with the corresponding eigenvalues in W; IBLOCK(i)=1 if eigenvalue W(i) belongs to the first submatrix from the top, =2 if W(i) belongs to the second submatrix, etc. (The output array IBLOCK from SSTEBSZ is expected here.)

ISPLIT (input)
The splitting points, at which T breaks up into submatrices. The first submatrix consists of rows/columns 1 to ISPLIT(1), the second of rows/columns ISPLIT(1)+1 through ISPLIT(2), etc. (The output array ISPLIT from SSTEBSZ is expected here.)

Z (output)
The computed eigenvectors. The eigenvector asso-

ciated with the eigenvalue $W(i)$ is stored in the i -th column of Z . Any vector which fails to converge is set to its current iterate after $MAXITS$ iterations.

LDZ (input)

The leading dimension of the array Z . $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension($5*N$)

IWORK (workspace)

dimension(N)

IFAIL (output)

On normal exit, all elements of $IFAIL$ are zero. If one or more eigenvectors fail to converge after $MAXITS$ iterations, then their indices are stored in array $IFAIL$.

INFO (output)

= 0: successful exit.

< 0: if $INFO = -i$, the i -th argument had an illegal value

> 0: if $INFO = i$, then i eigenvectors failed to converge in $MAXITS$ iterations. Their indices are stored in array $IFAIL$.

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NAME

ssteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method

SYNOPSIS

```
SUBROUTINE SSTEQR(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ
INTEGER N, LDZ, INFO
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSTEQR_64(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ
INTEGER*8 N, LDZ, INFO
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEQR(COMPZ, N, D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ
INTEGER :: N, LDZ, INFO
REAL, DIMENSION(:) :: D, E, WORK
REAL, DIMENSION(:,) :: Z
```

```
SUBROUTINE STEQR_64(COMPZ, N, D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ
INTEGER(8) :: N, LDZ, INFO
REAL, DIMENSION(:) :: D, E, WORK
REAL, DIMENSION(:,) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssteqr(char compz, int n, float *d, float *e, float *z,
            int ldz, int *info);
```

```
void ssteqr_64(char compz, long n, float *d, float *e, float
```

```
*z, long ldz, long *info);
```

PURPOSE

ssteqr computes all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method. The eigenvectors of a full or band symmetric matrix can also be found if SSYTRD or SSPTRD or SSBTRD has been used to reduce this matrix to tridiagonal form.

ARGUMENTS

COMPZ (input)

= 'N': Compute eigenvalues only.
= 'V': Compute eigenvalues and eigenvectors of the original symmetric matrix. On entry, Z must contain the orthogonal matrix used to reduce the original matrix to tridiagonal form. = 'I': Compute eigenvalues and eigenvectors of the tridiagonal matrix. Z is initialized to the identity matrix.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the diagonal elements of the tridiagonal matrix. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input) On entry, if COMPZ = 'V', then Z contains the orthogonal matrix used in the reduction to tridiagonal form. On exit, if INFO = 0, then if COMPZ = 'V', Z contains the orthonormal eigenvectors of the original symmetric matrix, and if COMPZ = 'I', Z contains the orthonormal eigenvectors of the symmetric tridiagonal matrix. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if eigenvectors are desired, then $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension($\max(1, 2*N-2)$) If COMPZ = 'N', then WORK is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: the algorithm has failed to find all the

eigenvalues in a total of $30*N$ iterations; if $INFO = i$, then i elements of E have not converged to zero; on exit, D and E contain the elements of a symmetric tridiagonal matrix which is orthogonally similar to the original matrix.

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NAME

ssterf - compute all eigenvalues of a symmetric tridiagonal matrix using the Pal-Walker-Kahan variant of the QL or QR algorithm

SYNOPSIS

```
SUBROUTINE SSTERF(N, D, E, INFO)
```

```
INTEGER N, INFO  
REAL D(*), E(*)
```

```
SUBROUTINE SSTERF_64(N, D, E, INFO)
```

```
INTEGER*8 N, INFO  
REAL D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE STERF([N], D, E, [INFO])
```

```
INTEGER :: N, INFO  
REAL, DIMENSION(:) :: D, E
```

```
SUBROUTINE STERF_64([N], D, E, [INFO])
```

```
INTEGER(8) :: N, INFO  
REAL, DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssterf(int n, float *d, float *e, int *info);
```

```
void ssterf_64(long n, float *d, float *e, long *info);
```

PURPOSE

ssterf computes all eigenvalues of a symmetric tridiagonal

matrix using the Pal-Walker-Kahan variant of the QL or QR algorithm.

ARGUMENTS

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix. On exit, if $INFO = 0$, the eigenvalues in ascending order.

E (input/output)

On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: the algorithm failed to find all of the eigenvalues in a total of $30*N$ iterations; if $INFO = i$, then i elements of E have not converged to zero.

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NAME

sstev - compute all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A

SYNOPSIS

```
SUBROUTINE SSTEVE(JOBZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ  
INTEGER N, LDZ, INFO  
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSTEVE_64(JOBZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 JOBZ  
INTEGER*8 N, LDZ, INFO  
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEV(JOBZ, N, D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ  
INTEGER :: N, LDZ, INFO  
REAL, DIMENSION(:) :: D, E, WORK  
REAL, DIMENSION(:,) :: Z
```

```
SUBROUTINE STEV_64(JOBZ, N, D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ  
INTEGER(8) :: N, LDZ, INFO  
REAL, DIMENSION(:) :: D, E, WORK  
REAL, DIMENSION(:,) :: Z
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sstev(char jobz, int n, float *d, float *e, float *z,  
int ldz, int *info);
```

```
void sstev_64(char jobz, long n, float *d, float *e, float  
*z, long ldz, long *info);
```

PURPOSE

sstev computes all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A, stored in elements 1 to N-1 of E; E(N) need not be set, but is used by the routine. On exit, the contents of E are destroyed.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with D(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace)

If JOBZ = 'N', WORK is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of E did not converge to zero.

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NAME

sstevd - compute all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix

SYNOPSIS

```
SUBROUTINE SSTEVD(JOBZ, N, D, E, Z, LDZ, WORK, LWORK, IWORK, LIWORK,
  INFO)
```

```
CHARACTER * 1 JOBZ
INTEGER N, LDZ, LWORK, LIWORK, INFO
INTEGER IWORK(*)
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSTEVD_64(JOBZ, N, D, E, Z, LDZ, WORK, LWORK, IWORK,
  LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ
INTEGER*8 N, LDZ, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
REAL D(*), E(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEVD(JOBZ, N, D, E, Z, [LDZ], [WORK], [LWORK], [IWORK],
  [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ
INTEGER :: N, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: D, E, WORK
REAL, DIMENSION(:,) :: Z
```

```
SUBROUTINE STEVD_64(JOBZ, N, D, E, Z, [LDZ], [WORK], [LWORK], [IWORK],
  [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ
INTEGER(8) :: N, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: D, E, WORK
REAL, DIMENSION(:,) :: Z
```

C INTERFACE

```
#include <sunperf.h>

void sstevd(char jobz, int n, float *d, float *e, float *z,
            int ldz, int *info);
void sstevd_64(char jobz, long n, float *d, float *e, float
               *z, long ldz, long *info);
```

PURPOSE

sstevd computes all eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)
On entry, the n diagonal elements of the tridiagonal matrix A . On exit, if $INFO = 0$, the eigenvalues in ascending order.

E (input/output)
On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix A , stored in elements 1 to $N-1$ of E ; $E(N)$ need not be set, but is used by the routine. On exit, the contents of E are destroyed.

Z (input) If $JOBZ = 'V'$, then if $INFO = 0$, Z contains the orthonormal eigenvectors of the matrix A , with the i -th column of Z holding the eigenvector associated with $D(i)$. If $JOBZ = 'N'$, then Z is not referenced.

LDZ (input)
The leading dimension of the array Z . $LDZ \geq 1$, and if $JOBZ = 'V'$, $LDZ \geq \max(1, N)$.

WORK (workspace)
dimension (LWORK) On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If JOBZ = 'N' or $N \leq 1$ then LWORK must be at least 1. If JOBZ = 'V' and $N > 1$ then LWORK must be at least $(1 + 4*N + N**2)$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If JOBZ = 'N' or $N \leq 1$ then LIWORK must be at least 1. If JOBZ = 'V' and $N > 1$ then LIWORK must be at least $3+5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of E did not converge to zero.

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NAME

sstevr - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T

SYNOPSIS

```
SUBROUTINE SSTEVR(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M, W,  
  Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
INTEGER N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER ISUPPZ(*), IWORK(*)  
REAL VL, VU, ABSTOL  
REAL D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSTEVR_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
INTEGER*8 N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 ISUPPZ(*), IWORK(*)  
REAL VL, VU, ABSTOL  
REAL D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEVR(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE  
INTEGER :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: ISUPPZ, IWORK  
REAL :: VL, VU, ABSTOL  
REAL, DIMENSION(:) :: D, E, W, WORK  
REAL, DIMENSION(:, :) :: Z
```

```
SUBROUTINE STEVR_64(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL,  
  M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE
```

```

INTEGER(8) :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: D, E, W, WORK
REAL, DIMENSION(:,:) :: Z

```

C INTERFACE

```

#include <sunperf.h>
void sstevr(char jobz, char range, int n, float *d, float
            *e, float vl, float vu, int il, int iu, float
            abstol, int *m, float *w, float *z, int ldz, int
            *isuppz, int *info);

void sstevr_64(char jobz, char range, long n, float *d,
               float *e, float vl, float vu, long il, long iu,
               float abstol, long *m, float *w, float *z, long
               ldz, long *isuppz, long *info);

```

PURPOSE

sstevr computes selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

Whenever possible, SSTEVR calls SSTEGR to compute the eigenspectrum using Relatively Robust Representations. SSTEGR computes eigenvalues by the dqds algorithm, while orthogonal eigenvectors are computed from various "good" L D L^T representations (also known as Relatively Robust Representations). Gram-Schmidt orthogonalization is avoided as far as possible. More specifically, the various steps of the algorithm are as follows. For the i-th unreduced block of T,

- (a) Compute $T - \sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation,
- (b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high relative accuracy by the dqds algorithm,
- (c) If there is a cluster of close eigenvalues, "choose" σ_i close to the cluster, and go to step (a),
- (d) Given the approximate eigenvalue λ_j of $L_i D_i L_i^T$, compute the corresponding eigenvector by forming a rank-revealing twisted factorization.

The desired accuracy of the output can be specified by the input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB//CSD-97-971, UC Berkeley, May 1997.

Note 1 : SSTEVR calls SSTEGR when the full spectrum is requested on machines which conform to the ieee-754 floating point standard. SSTEVR calls SSTEGBZ and SSTEIN on non-ieee

machines and
when partial spectrum requests are made.

Normal execution of SSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not handle NaNs and infinities in the ieee standard default manner.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval
(VL,VU] will be found. = 'I': the IL-th through
IU-th eigenvalues will be found.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, D may be multiplied by a constant factor chosen to avoid over/underflow in computing the eigenvalues.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A in elements 1 to N-1 of E; E(N) need not be set. On exit, E may be multiplied by a constant factor chosen to avoid over/underflow in computing the eigenvalues.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$.
Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$ABSTOL + EPS * \max(|a|, |b|)$,

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

If high relative accuracy is important, set ABSTOL to SLAMCH('Safe minimum'). Doing so will guarantee that eigenvalues are computed to high relative accuracy when possible in future releases. The current code does not make any guarantees about high relative accuracy, but future releases will. See J. Barlow and J. Demmel, "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7, for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

ISUPPZ (output)

The support of the eigenvectors in Z, i.e., the indices indicating the nonzero elements in Z. The i-th eigenvector is nonzero only in elements ISUPPZ(2*i-1) through ISUPPZ(2*i).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal (and minimal) LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq 20*N$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of

the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal (and minimal) LIWORK.

LIWORK (input)

The dimension of the array IWORK. LIWORK $\geq 10 \cdot N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: Internal error

FURTHER DETAILS

Based on contributions by

Inderjit Dhillon, IBM Almaden, USA

Osni Marques, LBNL/NERSC, USA

Ken Stanley, Computer Science Division, University of California at Berkeley, USA

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NAME

sstevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A

SYNOPSIS

```
SUBROUTINE SSTEVDX(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABTOL,
                  NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE
INTEGER N, IL, IU, NFOUND, LDZ, INFO
INTEGER IWORK2(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSTEVDX_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU,
                     ABTOL, NFOUND, W, Z, LDZ, WORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE
INTEGER*8 N, IL, IU, NFOUND, LDZ, INFO
INTEGER*8 IWORK2(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL D(*), E(*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEVDX(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABTOL,
                 NFOUND, W, Z, [LDZ], [WORK], [IWORK2], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE
INTEGER :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK2, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: D, E, W, WORK
REAL, DIMENSION(:, :) :: Z
```

```
SUBROUTINE STEVDX_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU,
                    ABTOL, NFOUND, W, Z, [LDZ], [WORK], [IWORK2], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE
INTEGER(8) :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK2, IFAIL
```

```
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: D, E, W, WORK
REAL, DIMENSION(:,:) :: Z
```

C INTERFACE

```
#include <sunperf.h>
void sstevx(char jobz, char range, int n, float *d, float
            *e, float vl, float vu, int il, int iu, float
            abtol, int *nfound, float *w, float *z, int ldz,
            int *ifail, int *info);

void sstevx_64(char jobz, char range, long n, float *d,
               float *e, float vl, float vu, long il, long iu,
               float abtol, long *nfound, float *w, float *z,
               long ldz, long *ifail, long *info);
```

PURPOSE

sstevx computes selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix A. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, D may be multiplied by a constant factor chosen to avoid over/underflow in computing the eigenvalues.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A in elements 1 to N-1 of E; E(N) need not be set. On exit, E may be multiplied by a constant factor chosen to avoid over/underflow in computing the eigenvalues.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
See the description of VL.

IL (input)
If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
See the description of IL.

ABTOL (input)
The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2*SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)
The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)
The first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if $INFO = 0$, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. If an eigenvector fails to converge ($INFO > 0$), then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, NFOUND)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1,
and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)
dimension(5*N)

IWORK2 (workspace)

IFAIL (output)
If JOBZ = 'V', then if INFO = 0, the first NFOUND
elements of IFAIL are zero. If INFO > 0, then
IFAIL contains the indices of the eigenvectors
that failed to converge. If JOBZ = 'N', then
IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value
> 0: if INFO = i, then i eigenvectors failed to
converge. Their indices are stored in array
IFAIL.

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NAME

sstsv - compute the solution to a system of linear equations
 $A * X = B$ where A is a symmetric tridiagonal matrix

SYNOPSIS

```
SUBROUTINE SSTSVM(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIV(*)  
REAL L(*), D(*), SUBL(*), B(LDB,*)
```

```
SUBROUTINE SSTSVM_64(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIV(*)  
REAL L(*), D(*), SUBL(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE STSMV([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIV  
REAL, DIMENSION(:) :: L, D, SUBL  
REAL, DIMENSION(:,) :: B
```

```
SUBROUTINE STSMV_64([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIV  
REAL, DIMENSION(:) :: L, D, SUBL  
REAL, DIMENSION(:,) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sstsv(int n, int nrhs, float *l, float *d, float *subl,  
          float *b, int ldb, int *ipiv, int *info);
```

```
void sstsv_64(long n, long nrhs, float *l, float *d, float  
             *subl, float *b, long ldb, long *ipiv, long
```

```
*info);
```

PURPOSE

sstsv computes the solution to a system of linear equations $A * X = B$ where A is a symmetric tridiagonal matrix.

ARGUMENTS

N (input) INTEGER
The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides in B.

L (input/output)
REAL array, dimension (N-1)
On entry, the n-1 subdiagonal elements of the tridiagonal matrix A. On exit, part of the factorization of A.

D (input/output)
REAL array, dimension (N)
On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the factorization of A.

SUBL (output)
REAL array, dimension (N-2)
On exit, part of the factorization of A.

B (input/output)
The columns of B contain the right hand sides.

LDB (input)
The leading dimension of B as specified in a type or DIMENSION statement.

IPIV (output)
INTEGER array, dimension (N)
On exit, the pivot indices of the factorization.

INFO (output)
INTEGER
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular and division by zero will occur if it is used to solve a system of equations.

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NAME

ssttrf - compute the factorization of a symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE SSTTRF(N, L, D, SUBL, IPIV, INFO)

INTEGER N, INFO
INTEGER IPIV(*)
REAL L(*), D(*), SUBL(*)

SUBROUTINE SSTTRF_64(N, L, D, SUBL, IPIV, INFO)

INTEGER*8 N, INFO
INTEGER*8 IPIV(*)
REAL L(*), D(*), SUBL(*)
```

F95 INTERFACE

```
SUBROUTINE STTRF([N], L, D, SUBL, IPIV, [INFO])

INTEGER :: N, INFO
INTEGER, DIMENSION(:) :: IPIV
REAL, DIMENSION(:) :: L, D, SUBL

SUBROUTINE STTRF_64([N], L, D, SUBL, IPIV, [INFO])

INTEGER(8) :: N, INFO
INTEGER(8), DIMENSION(:) :: IPIV
REAL, DIMENSION(:) :: L, D, SUBL
```

C INTERFACE

```
#include <sunperf.h>

void ssttrf(int n, float *l, float *d, float *subl, int
           *ipiv, int *info);

void ssttrf_64(long n, float *l, float *d, float *subl, long
              *ipiv, long *info);
```

PURPOSE

ssstrf computes the L^*D*L' factorization of a real symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method.

ARGUMENTS

N (input) INTEGER
The order of the matrix A. $N \geq 0$.

L (input/output)
REAL array, dimension (N-1)
On entry, the n-1 subdiagonal elements of the tridiagonal matrix A. On exit, part of the factorization of A.

D (input/output)
REAL array, dimension (N)
On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the L^*D*L^*H factorization of A.

SUBL (output)
REAL array, dimension (N-2)
On exit, part of the factorization of A.

IPIV (output)
INTEGER array, dimension (N)
On exit, the pivot indices of the factorization.

INFO (output)
INTEGER
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular and division by zero will occur if it is used to solve a system of equations.

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NAME

ssttrs - computes the solution to a real system of linear equations $A * X = B$

SYNOPSIS

```
SUBROUTINE SSTTRS(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
INTEGER N, NRHS, LDB, INFO
INTEGER IPIV(*)
REAL L(*), D(*), SUBL(*), B(LDB,*)
```

```
SUBROUTINE SSTTRS_64(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
INTEGER*8 N, NRHS, LDB, INFO
INTEGER*8 IPIV(*)
REAL L(*), D(*), SUBL(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE STTRS([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
INTEGER :: N, NRHS, LDB, INFO
INTEGER, DIMENSION(:) :: IPIV
REAL, DIMENSION(:) :: L, D, SUBL
REAL, DIMENSION(:,) :: B
```

```
SUBROUTINE STTRS_64([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
INTEGER(8) :: N, NRHS, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIV
REAL, DIMENSION(:) :: L, D, SUBL
REAL, DIMENSION(:,) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssttrs(int n, int nrhs, float *l, float *d, float
           *subl, float *b, int ldb, int *ipiv, int *info);
```

```
void ssttrs_64(long n, long nrhs, float *l, float *d, float
              *subl, float *b, long ldb, long *ipiv, long
```

```
*info);
```

PURPOSE

ssttrs computes the solution to a real system of linear equations $A * X = B$, where A is an N-by-N symmetric tridiagonal matrix and X and B are N-by-NRHS matrices.

ARGUMENTS

N (input) INTEGER
The order of the matrix A. $N \geq 0$.

NRHS (input)
INTEGER
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

L (input) REAL array, dimension (N-1)
On entry, the subdiagonal elements of L.

D (input) REAL array, dimension (N)
On entry, the diagonal elements of D.

SUBL (input)
REAL array, dimension (N-2)
On entry, the second subdiagonal elements of L.

B (input/output)
REAL array, dimension (LDB, NRHS)
On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)
INTEGER
The leading dimension of the array B. $LDB \geq \max(1, N)$

IPIV (output)
INTEGER array, dimension (N)
Details of the interchanges and block pivot. If $IPIV(K) > 0$, 1 by 1 pivot, and if $IPIV(K) = K + 1$ an interchange done; If $IPIV(K) < 0$, 2 by 2 pivot, no interchange required.

INFO (output)
INTEGER
= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value

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NAME

sswap - Exchange vectors x and y.

SYNOPSIS

```
SUBROUTINE SSWAP(N, X, INCX, Y, INCY)
```

```
INTEGER N, INCX, INCY  
REAL X(*), Y(*)
```

```
SUBROUTINE SSWAP_64(N, X, INCX, Y, INCY)
```

```
INTEGER*8 N, INCX, INCY  
REAL X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE SWAP([N], X, [INCX], Y, [INCY])
```

```
INTEGER :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y
```

```
SUBROUTINE SWAP_64([N], X, [INCX], Y, [INCY])
```

```
INTEGER(8) :: N, INCX, INCY  
REAL, DIMENSION(:) :: X, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void sswap(int n, float *x, int incx, float *y, int incy);
```

```
void sswap_64(long n, float *x, long incx, float *y, long  
incy);
```

PURPOSE

sswap Exchange x and y where x and y are n-vectors.

ARGUMENTS

- N (input)
On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.
- X (input/output)
($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x. On exit, the y vector.
- INCX (input)
On entry, INCX specifies the increment for the elements of X. Unchanged on exit.
- Y (input/output)
($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array Y must contain the vector y. On exit, the x vector.
- INCY (input)
On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

ssycon - estimate the reciprocal of the condition number (in the 1-norm) of a real symmetric matrix A using the factorization $A = U^*D*U^{**T}$ or $A = L^*D*L^{**T}$ computed by SSYTRF

SYNOPSIS

```
SUBROUTINE SSYCON(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK,  
                 IWORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*), IWORK2(*)  
REAL ANORM, RCOND  
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE SSYCON_64(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK,  
                   IWORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*), IWORK2(*)  
REAL ANORM, RCOND  
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYCON(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
                [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, IWORK2  
REAL :: ANORM, RCOND  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SYCON_64(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
                  [IWORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO
```

```
INTEGER(8), DIMENSION(:) :: IPIVOT, IWORK2
REAL :: ANORM, RCOND
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
void ssyscon(char uplo, int n, float *a, int lda, int
             *ipivot, float anorm, float *rcond, int *info);

void ssyscon_64(char uplo, long n, float *a, long lda, long
               *ipivot, float anorm, float *rcond, long *info);
```

PURPOSE

ssyscon estimates the reciprocal of the condition number (in the 1-norm) of a real symmetric matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by SSYTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U*D*U**T$;
= 'L': Lower triangular, form is $A = L*D*L**T$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by SSYTRF.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by SSYTRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{AINVM})$, where AINVM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

IWORK2 (workspace)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ssyev - compute all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

SYNOPSIS

```
SUBROUTINE SSYEV(JOBZ, UPLO, N, A, LDA, W, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, LDA, LDWORK, INFO  
REAL A(LDA,*), W(*), WORK(*)
```

```
SUBROUTINE SSYEV_64(JOBZ, UPLO, N, A, LDA, W, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, LDA, LDWORK, INFO  
REAL A(LDA,*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYEV(JOBZ, UPLO, N, A, [LDA], W, [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SYEV_64(JOBZ, UPLO, N, A, [LDA], W, [WORK], [LDWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, LDA, LDWORK, INFO  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssyev(char jobz, char uplo, int n, float *a, int lda,  
float *w, int *info);
```

```
void ssyev_64(char jobz, char uplo, long n, float *a, long
```

```
lda, float *w, long *info);
```

PURPOSE

ssyev computes all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, if JOBZ = 'V', then if INFO = 0, A contains the orthonormal eigenvectors of the matrix A. If JOBZ = 'N', then on exit the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)

If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of the array WORK. $LDWORK \geq \max(1, 3*N-1)$. For optimal efficiency, $LDWORK \geq (NB+2)*N$, where NB is the blocksize for SSYTRD returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

ssyevd - compute all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

SYNOPSIS

```
SUBROUTINE SSYEVD(JOBZ, UPLO, N, A, LDA, W, WORK, LWORK, IWORK,  
                LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER N, LDA, LWORK, LIWORK, INFO  
INTEGER IWORK(*)  
REAL A(LDA,*), W(*), WORK(*)
```

```
SUBROUTINE SSYEVD_64(JOBZ, UPLO, N, A, LDA, W, WORK, LWORK, IWORK,  
                   LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 N, LDA, LWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
REAL A(LDA,*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYEVD(JOBZ, UPLO, N, A, [LDA], W, [WORK], [LWORK], [IWORK],  
                [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: N, LDA, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SYEVD_64(JOBZ, UPLO, N, A, [LDA], W, [WORK], [LWORK],  
                   [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: N, LDA, LWORK, LIWORK, INFO  
INTEGER(8), DIMENSION(:) :: IWORK  
REAL, DIMENSION(:) :: W, WORK
```

```
REAL, DIMENSION(:,:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssyevd(char jobz, char uplo, int n, float *a, int lda,  
            float *w, int *info);
```

```
void ssyevd_64(char jobz, char uplo, long n, float *a, long  
              lda, float *w, long *info);
```

PURPOSE

ssyevd computes all eigenvalues and, optionally, eigenvectors of a real symmetric matrix A. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

Because of large use of BLAS of level 3, SSYEVD needs N^2 more workspace than SSYEVX.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, if JOBZ = 'V', then if INFO = 0, A contains the orthonormal eigenvectors of the matrix A. If JOBZ = 'N', then on exit the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)
 dimension (LWORK) On exit, if INFO = 0, WORK(1)
 returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. If $N \leq 1$,
 LWORK must be at least 1. If JOBZ = 'N' and $N > 1$,
 LWORK must be at least $2*N+1$. If JOBZ = 'V'
 and $N > 1$, LWORK must be at least $1 + 6*N + 2*N**2$.

If LWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the WORK array, returns this value as the first
 entry of the WORK array, and no error message
 related to LWORK is issued by XERBLA.

IWORK (workspace/output)
 On exit, if INFO = 0, IWORK(1) returns the optimal
 LIWORK.

LIWORK (input)
 The dimension of the array IWORK. If $N \leq 1$,
 LIWORK must be at least 1. If JOBZ = 'N' and $N > 1$,
 LIWORK must be at least 1. If JOBZ = 'V' and
 $N > 1$, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the IWORK array, returns this value as the first
 entry of the IWORK array, and no error message
 related to LIWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-
 gal value
 > 0: if INFO = i, the algorithm failed to con-
 verge; i off-diagonal elements of an intermediate
 tridiagonal form did not converge to zero.

FURTHER DETAILS

Based on contributions by
 Jeff Rutter, Computer Science Division, University of
 California
 at Berkeley, USA
 Modified by Francoise Tisseur, University of Tennessee.

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NAME

ssyevr - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T

SYNOPSIS

```
SUBROUTINE SSYEVR(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
                 ABSTOL, M, W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, LDA, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER ISUPPZ(*), IWORK(*)
REAL VL, VU, ABSTOL
REAL A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSYEVR_64(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
                   ABSTOL, M, W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, LDA, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER*8 ISUPPZ(*), IWORK(*)
REAL VL, VU, ABSTOL
REAL A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYEVR(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
                ABSTOL, M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK],
                [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, LDA, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: ISUPPZ, IWORK
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: A, Z
```

```
SUBROUTINE SYEVR_64(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
                   ABSTOL, M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK],
                   [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: N, LDA, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: A, Z

```

C INTERFACE

```

#include <sunperf.h>

void ssyevr(char jobz, char range, char uplo, int n, float
            *a, int lda, float vl, float vu, int il, int iu,
            float abstol, int *m, float *w, float *z, int ldz,
            int *isuppz, int *info);

void ssyevr_64(char jobz, char range, char uplo, long n,
              float *a, long lda, float vl, float vu, long il,
              long iu, float abstol, long *m, float *w, float
              *z, long ldz, long *isuppz, long *info);

```

PURPOSE

ssyevr computes selected eigenvalues and, optionally, eigenvectors of a real symmetric tridiagonal matrix T. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

Whenever possible, SSYEVR calls SSTEGR to compute the eigenspectrum using Relatively Robust Representations. SSTEGR computes eigenvalues by the dqds algorithm, while orthogonal eigenvectors are computed from various "good" L D L^T representations (also known as Relatively Robust Representations). Gram-Schmidt orthogonalization is avoided as far as possible. More specifically, the various steps of the algorithm are as follows. For the i-th unreduced block of T,

- (a) Compute $T - \sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation,
- (b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high relative accuracy by the dqds algorithm,
- (c) If there is a cluster of close eigenvalues, "choose" σ_i close to the cluster, and go to step (a),
- (d) Given the approximate eigenvalue λ_j of $L_i D_i L_i^T$, compute the corresponding eigenvector by forming a rank-revealing twisted factorization.

The desired accuracy of the output can be specified by the input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB//CSD-97-971, UC Berkeley, May 1997.

Note 1: SSYEVR calls SSTEGR when the full spectrum is requested on machines which conform to the ieee-754 floating

point standard. SSYEVR calls SSTEGBZ and SSTEIN on non-ieee machines and when partial spectrum requests are made.

Normal execution of SSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not handle NaNs and infinities in the ieee standard default manner.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)

See the description of VL.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

See the description of IL.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$\text{ABSTOL} + \text{EPS} * \max(|a|, |b|),$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $\text{EPS} * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

If high relative accuracy is important, set ABSTOL to SLAMCH('Safe minimum'). Doing so will guarantee that eigenvalues are computed to high relative accuracy when possible in future releases. The current code does not make any guarantees about high relative accuracy, but future releases will. See J. Barlow and J. Demmel, "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7, for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = \text{IU} - \text{IL} + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $\text{LDZ} \geq 1$, and if JOBZ = 'V', $\text{LDZ} \geq \max(1, N)$.

ISUPPZ (output)

The support of the eigenvectors in Z, i.e., the indices indicating the nonzero elements in Z. The i-th eigenvector is nonzero only in elements ISUPPZ(2*i-1) through ISUPPZ(2*i).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,26*N). For optimal efficiency, LWORK \geq (NB+6)*N, where NB is the max of the blocksize for SSYTRD and SORMTR returned by ILAENV.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LWORK.

LIWORK (input)

The dimension of the array IWORK. LIWORK \geq max(1,10*N).

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: Internal error

FURTHER DETAILS

Based on contributions by
Inderjit Dhillon, IBM Almaden, USA
Osni Marques, LBNL/NERSC, USA
Ken Stanley, Computer Science Division, University of
California at Berkeley, USA

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NAME

ssyevx - compute selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A

SYNOPSIS

```
SUBROUTINE SSYEVX(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
                 ABTOL, NFOUND, W, Z, LDZ, WORK, LDWORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER IWORK2(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSYEVX_64(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
                   ABTOL, NFOUND, W, Z, LDZ, WORK, LDWORK, IWORK2, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER*8 IWORK2(*), IFAIL(*)
REAL VL, VU, ABTOL
REAL A(LDA,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYEVX(JOBZ, RANGE, UPLO, N, A, [LDA], VL, VU, IL, IU,
                ABTOL, NFOUND, W, Z, [LDZ], [WORK], [LDWORK], [IWORK2], IFAIL,
                [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER, DIMENSION(:) :: IWORK2, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:,) :: A, Z
```

```
SUBROUTINE SYEVX_64(JOBZ, RANGE, UPLO, N, A, [LDA], VL, VU, IL, IU,
                   ABTOL, NFOUND, W, Z, [LDZ], [WORK], [LDWORK], [IWORK2], IFAIL,
                   [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
```

```

INTEGER(8) :: N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK2, IFAIL
REAL :: VL, VU, ABTOL
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: A, Z

```

C INTERFACE

```

#include <sunperf.h>

void ssyevx(char jobz, char range, char uplo, int n, float
           *a, int lda, float vl, float vu, int il, int iu,
           float abtol, int *nfound, float *w, float *z, int
           ldz, int *ifail, int *info);

void ssyevx_64(char jobz, char range, char uplo, long n,
              float *a, long lda, float vl, float vu, long il,
              long iu, float abtol, long *nfound, float *w,
              float *z, long ldz, long *ifail, long *info);

```

PURPOSE

ssyevx computes selected eigenvalues and, optionally, eigenvectors of a real symmetric matrix A. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found.
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. N >= 0.

A (input/output)
 On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
 The leading dimension of the array A. LDA >= max(1,N).

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 See the description of VL.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 See the description of IL.

ABTOL (input)
 The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2 * SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)
 The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)
 On normal exit, the first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if $INFO = 0$, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, NFOUND)$ columns are supplied in the array Z;

if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of the array WORK. LDWORK \geq max(1,8*N). For optimal efficiency, LDWORK \geq (NB+3)*N, where NB is the max of the blocksize for SSYTRD and SORMTR returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

IWORK2 (workspace)

IFAIL (output)

If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO $>$ 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

ssygs2 - reduce a real symmetric-definite generalized eigenproblem to standard form

SYNOPSIS

```
SUBROUTINE SSYGS2(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER ITYPE, N, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SSYGS2_64(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 ITYPE, N, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SYGS2(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: ITYPE, N, LDA, LDB, INFO  
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE SYGS2_64(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: ITYPE, N, LDA, LDB, INFO  
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssygs2(int itype, char uplo, int n, float *a, int lda,  
           float *b, int ldb, int *info);
```

```
void ssygs2_64(long itype, char uplo, long n, float *a, long  
              lda, float *b, long ldb, long *info);
```

PURPOSE

ssygs2 reduces a real symmetric-definite generalized eigenproblem to standard form.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $inv(U')*A*inv(U)$ or $inv(L)*A*inv(L')$. If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U'$ or $L'*A*L$.

B must have been previously factorized as $U'*U$ or $L*L'$ by SPOTRF.

ARGUMENTS

ITYPE (input)

= 1: compute $inv(U')*A*inv(U)$ or $inv(L)*A*inv(L')$;
= 2 or 3: compute $U*A*U'$ or $L'*A*L$.

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored, and how B has been factorized. = 'U': Upper triangular
= 'L': Lower triangular

N (input) The order of the matrices A and B . $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A . If $UPLO = 'U'$, the leading n by n upper triangular part of A contains the upper triangular part of the matrix A , and the strictly lower triangular part of A is not referenced. If $UPLO = 'L'$, the leading n by n lower triangular part of A contains the lower triangular part of the matrix A , and the strictly upper triangular part of A is not referenced.

On exit, if $INFO = 0$, the transformed matrix, stored in the same format as A .

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

B (input) The triangular factor from the Cholesky factorization of B , as returned by SPOTRF.

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit.
< 0: if $INFO = -i$, the i -th argument had an illegal value.

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NAME

ssygst - reduce a real symmetric-definite generalized eigenproblem to standard form

SYNOPSIS

```
SUBROUTINE SSYGST(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER ITYPE, N, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SSYGST_64(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 ITYPE, N, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SYGST(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: ITYPE, N, LDA, LDB, INFO  
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE SYGST_64(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: ITYPE, N, LDA, LDB, INFO  
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssygst(int itype, char uplo, int n, float *a, int lda,  
           float *b, int ldb, int *info);
```

```
void ssygst_64(long itype, char uplo, long n, float *a, long  
              lda, float *b, long ldb, long *info);
```

PURPOSE

ssygst reduces a real symmetric-definite generalized eigenproblem to standard form.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $\text{inv}(U^{**T})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{**T})$

If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U^{**T}$ or $L^{**T}*A*L$.

B must have been previously factorized as $U^{**T}*U$ or $L*L^{**T}$ by SPOTRF.

ARGUMENTS

$ITYPE$ (input)

= 1: compute $\text{inv}(U^{**T})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{**T})$;
= 2 or 3: compute $U*A*U^{**T}$ or $L^{**T}*A*L$.

$UPLO$ (input)

= 'U': Upper triangle of A is stored and B is factored as $U^{**T}*U$; = 'L': Lower triangle of A is stored and B is factored as $L*L^{**T}$.

N (input) The order of the matrices A and B . $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A . If $UPLO = 'U'$, the leading N -by- N upper triangular part of A contains the upper triangular part of the matrix A , and the strictly lower triangular part of A is not referenced. If $UPLO = 'L'$, the leading N -by- N lower triangular part of A contains the lower triangular part of the matrix A , and the strictly upper triangular part of A is not referenced.

On exit, if $INFO = 0$, the transformed matrix, stored in the same format as A .

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

B (input) The triangular factor from the Cholesky factorization of B , as returned by SPOTRF.

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

$INFO$ (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

ssygv - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE SSYGV(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                LDWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER ITYPE, N, LDA, LDB, LDWORK, INFO  
REAL A(LDA,*), B(LDB,*), W(*), WORK(*)
```

```
SUBROUTINE SSYGV_64(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                  LDWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
INTEGER*8 ITYPE, N, LDA, LDB, LDWORK, INFO  
REAL A(LDA,*), B(LDB,*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYGV(ITYPE, JOBZ, UPLO, N, A, [LDA], B, [LDB], W, [WORK],  
               [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER :: ITYPE, N, LDA, LDB, LDWORK, INFO  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE SYGV_64(ITYPE, JOBZ, UPLO, N, A, [LDA], B, [LDB], W, [WORK],  
                  [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
INTEGER(8) :: ITYPE, N, LDA, LDB, LDWORK, INFO  
REAL, DIMENSION(:) :: W, WORK  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```

void ssygv(int itype, char jobz, char uplo, int n, float *a,
           int lda, float *b, int ldb, float *w, int *info);

void ssygv_64(long itype, char jobz, char uplo, long n,
              float *a, long lda, float *b, long ldb, float *w,
              long *info);

```

PURPOSE

ssygv computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*B*x=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric and B is also positive definite.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)*B*x$
- = 2: $A*B*x = (\lambda)*x$
- = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

- = 'U': Upper triangles of A and B are stored;
- = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.

On exit, if JOBZ = 'V', then if INFO = 0, A contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z**T*B*Z = I$; if ITYPE = 3, $Z**T*inv(B)*Z = I$. If JOBZ = 'N', then on exit the upper triangle (if UPLO='U') or the lower triangle (if UPLO='L') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)

On entry, the symmetric positive definite matrix

B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if INFO <= N, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*T^*U$ or $B = L^*L^*T$.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

W (output)

If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The length of the array WORK. LDWORK >= max(1,3*N-1). For optimal efficiency, LDWORK >= (NB+2)*N, where NB is the blocksize for SSYTRD returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: SPOTRF or SSYEV returned an error code:
<= N: if INFO = i, SSYEV failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for 1 <= i <= N, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

ssygvd - compute all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE SSYGVD(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,
                 LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER ITYPE, N, LDA, LDB, LWORK, LIWORK, INFO
INTEGER IWORK(*)
REAL A(LDA,*), B(LDB,*), W(*), WORK(*)
```

```
SUBROUTINE SSYGVD_64(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,
                    LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
INTEGER*8 ITYPE, N, LDA, LDB, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
REAL A(LDA,*), B(LDB,*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYGVD(ITYPE, JOBZ, UPLO, [N], A, [LDA], B, [LDB], W, [WORK],
                [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER :: ITYPE, N, LDA, LDB, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE SYGVD_64(ITYPE, JOBZ, UPLO, [N], A, [LDA], B, [LDB], W,
                   [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
INTEGER(8) :: ITYPE, N, LDA, LDB, LWORK, LIWORK, INFO
```

```
INTEGER(8), DIMENSION(:) :: IWORK
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>

void ssygvd(int itype, char jobz, char uplo, int n, float
            *a, int lda, float *b, int ldb, float *w, int
            *info);

void ssygvd_64(long itype, char jobz, char uplo, long n,
               float *a, long lda, float *b, long ldb, float *w,
               long *info);
```

PURPOSE

ssygvd computes all the eigenvalues, and optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:
= 1: $A*x = (\lambda)*B*x$
= 2: $A*B*x = (\lambda)*x$
= 3: $B*A*x = (\lambda)*x$

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangles of A and B are stored;
= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of

the matrix A.

On exit, if JOBZ = 'V', then if INFO = 0, A contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^T B Z = I$; if ITYPE = 3, $Z^T \text{inv}(B) Z = I$. If JOBZ = 'N', then on exit the upper triangle (if UPLO='U') or the lower triangle (if UPLO='L') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)

On entry, the symmetric matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if INFO \leq N, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^T U$ or $B = L L^T$.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

W (output)

If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $N \leq 1$, LWORK ≥ 1 . If JOBZ = 'N' and $N > 1$, LWORK $\geq 2*N+1$. If JOBZ = 'V' and $N > 1$, LWORK $\geq 1 + 6*N + 2*N^2$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If $N \leq 1$, LIWORK ≥ 1 . If JOBZ = 'N' and $N > 1$, LIWORK ≥ 1 . If JOBZ = 'V' and $N > 1$, LIWORK $\geq 3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of

the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: SPOTRF or SSYEVD returned an error code:
<= N: if INFO = i, SSYEVD failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

ssygvx - compute selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*Bx=(\lambda)x$, or $B*A*x=(\lambda)x$

SYNOPSIS

```
SUBROUTINE SSYGVX(ITYPE, JOBZ, RANGE, UPLO, N, A, LDA, B, LDB, VL,
                 VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, LWORK, IWORK, IFAIL,
                 INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL A(LDA,*), B(LDB,*), W(*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE SSYGVX_64(ITYPE, JOBZ, RANGE, UPLO, N, A, LDA, B, LDB, VL,
                    VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, LWORK, IWORK, IFAIL,
                    INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
INTEGER*8 ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER*8 IWORK(*), IFAIL(*)
REAL VL, VU, ABSTOL
REAL A(LDA,*), B(LDB,*), W(*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYGVX(ITYPE, JOBZ, RANGE, UPLO, [N], A, [LDA], B, [LDB],
                VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [LWORK], [IWORK],
                IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER :: ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: A, B, Z
```

```

SUBROUTINE SYGVX_64(ITYPE, JOBZ, RANGE, UPLO, [N], A, [LDA], B, [LDB],
    VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [LWORK], [IWORK],
    IFAIL, [INFO])

```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
INTEGER(8) :: ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL :: VL, VU, ABSTOL
REAL, DIMENSION(:) :: W, WORK
REAL, DIMENSION(:, :) :: A, B, Z

```

C INTERFACE

```

#include <sunperf.h>

```

```

void ssygvx(int itype, char jobz, char range, char uplo, int
    n, float *a, int lda, float *b, int ldb, float vl,
    float vu, int il, int iu, float abstol, int *m,
    float *w, float *z, int ldz, int *ifail, int
    *info);

```

```

void ssygvx_64(long itype, char jobz, char range, char uplo,
    long n, float *a, long lda, float *b, long ldb,
    float vl, float vu, long il, long iu, float
    abstol, long *m, float *w, float *z, long ldz,
    long *ifail, long *info);

```

PURPOSE

ssygvx computes selected eigenvalues, and optionally, eigenvectors of a real generalized symmetric-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*B*x=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be symmetric and B is also positive definite. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)*B*x$
- = 2: $A*B*x = (\lambda)*x$
- = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

- = 'A': all eigenvalues will be found.
- = 'V': all eigenvalues in the half-open interval (VL,VU] will be found.
- = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangle of A and B are stored;
 = 'L': Lower triangle of A and B are stored.

N (input) The order of the matrix pencil (A,B). $N \geq 0$.

A (input/output)
 On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.
 On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)
 On entry, the symmetric matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.
 On exit, if INFO $\leq N$, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*T^*U$ or $B = L^*L^*T$.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1,N)$.

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 See the description of VL.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 See the description of IL.

ABSTOL (input)
 The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$ABSTOL + EPS * \max(|a|, |b|)$,

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2*DLAMCH('S')$, not zero. If this routine returns with $INFO>0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2*SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

On normal exit, the first M elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'N', then Z is not referenced. If JOBZ = 'V', then if $INFO = 0$, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized as follows: if $ITYPE = 1$ or 2 , $Z^*T*B*Z = I$; if $ITYPE = 3$, $Z^*T*inv(B)*Z = I$. If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

WORK (workspace)

On exit, if $INFO = 0$, WORK(1) returns the optimal LWORK.

LWORK (input)

The length of the array WORK. $LWORK \geq \max(1, 8*N)$. For optimal efficiency, $LWORK \geq (NB+3)*N$, where NB is the blocksize for SSYTRD returned by ILAENV.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)
dimension(5*N)

IFAIL (output)
If JOBZ = 'V', then if INFO = 0, the first M elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: SPOTRF or SSYEVX returned an error code:
<= N: if INFO = i, SSYEVX failed to converge; i eigenvectors failed to converge. Their indices are stored in array IFAIL. > N: if INFO = N + i, for 1 <= i <= N, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

ssymm - perform one of the matrix-matrix operations $C := \alpha * A * B + \beta * C$ or $C := \alpha * B * A + \beta * C$

SYNOPSIS

```
SUBROUTINE SSYMM(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                LDC)
```

```
CHARACTER * 1 SIDE, UPLO
INTEGER M, N, LDA, LDB, LDC
REAL ALPHA, BETA
REAL A(LDA,*), B(LDB,*), C(LDC,*)
```

```
SUBROUTINE SSYMM_64(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                   LDC)
```

```
CHARACTER * 1 SIDE, UPLO
INTEGER*8 M, N, LDA, LDB, LDC
REAL ALPHA, BETA
REAL A(LDA,*), B(LDB,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE SYMM(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
               BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
INTEGER :: M, N, LDA, LDB, LDC
REAL :: ALPHA, BETA
REAL, DIMENSION(:, :) :: A, B, C
```

```
SUBROUTINE SYMM_64(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
                  BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
INTEGER(8) :: M, N, LDA, LDB, LDC
REAL :: ALPHA, BETA
REAL, DIMENSION(:, :) :: A, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssymm(char side, char uplo, int m, int n, float alpha,
           float *a, int lda, float *b, int ldb, float beta,
           float *c, int ldc);
```

```
void ssymm_64(char side, char uplo, long m, long n, float
              alpha, float *a, long lda, float *b, long ldb,
              float beta, float *c, long ldc);
```

PURPOSE

ssymm performs one of the matrix-matrix operations $C := \alpha A^*B + \beta C$ or $C := \alpha B^*A + \beta C$ where alpha and beta are scalars, A is a symmetric matrix and B and C are m by n matrices.

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether the symmetric matrix A appears on the left or right in the operation as follows:

SIDE = 'L' or 'l' $C := \alpha A^*B + \beta C$,

SIDE = 'R' or 'r' $C := \alpha B^*A + \beta C$,

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the symmetric matrix A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of the symmetric matrix is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of the symmetric matrix is to be referenced.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of the matrix C. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix C. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

REAL array of DIMENSION (LDA, ka), where ka is m when SIDE = 'L' or 'l' and is n otherwise.

Before entry with SIDE = 'L' or 'l', the m by m part of the array A must contain the symmetric matrix, such that when UPLO = 'U' or 'u', the leading m by m upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading m by m lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced.

Before entry with SIDE = 'R' or 'r', the n by n part of the array A must contain the symmetric matrix, such that when UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced.

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then $LDA \geq \max(1, m)$, otherwise $LDA \geq \max(1, n)$. Unchanged on exit.

B (input)

REAL array of DIMENSION (LDB, n). Before entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. $LDB \geq \max(1, m)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then C need not be set on input. Unchanged on exit.

C (input/output)

REAL array of DIMENSION (LDC, n). Before entry, the leading m by n part of the array C must contain the matrix C, except when beta is zero, in which case C need not be set on entry. On exit, the array C is overwritten by the m by n updated matrix.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. $LDC \geq \max(1, m)$. Unchanged on exit.

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NAME

ssymv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE SSYMV(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INCX, INCY  
REAL ALPHA, BETA  
REAL A(LDA,*), X(*), Y(*)
```

```
SUBROUTINE SSYMV_64(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INCX, INCY  
REAL ALPHA, BETA  
REAL A(LDA,*), X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE SYMV(UPLO, [N], ALPHA, A, [LDA], X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SYMV_64(UPLO, [N], ALPHA, A, [LDA], X, [INCX], BETA, Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INCX, INCY  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:) :: X, Y  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssymv(char uplo, int n, float alpha, float *a, int lda,
           float *x, int incx, float beta, float *y, int
           incy);
```

```
void ssymv_64(char uplo, long n, float alpha, float *a, long
              lda, float *x, long incx, float beta, float *y,
              long incy);
```

PURPOSE

ssymv performs the matrix-vector operation $y := \alpha A x + \beta y$, where α and β are scalars, x and y are n element vectors and A is an n by n symmetric matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the

incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX \neq 0. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

($1 + (n - 1) * \text{abs}(\text{ INCY })$). Before entry, the incremented array Y must contain the n element vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

ssyr - perform the symmetric rank 1 operation $A := \alpha x x' + A$

SYNOPSIS

```
SUBROUTINE SSYR(UPLO, N, ALPHA, X, INCX, A, LDA)
```

```
CHARACTER * 1 UPLO  
INTEGER N, INCX, LDA  
REAL ALPHA  
REAL X(*), A(LDA,*)
```

```
SUBROUTINE SSYR_64(UPLO, N, ALPHA, X, INCX, A, LDA)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, INCX, LDA  
REAL ALPHA  
REAL X(*), A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE SYR(UPLO, [N], ALPHA, X, [INCX], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, INCX, LDA  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE SYR_64(UPLO, [N], ALPHA, X, [INCX], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, INCX, LDA  
REAL :: ALPHA  
REAL, DIMENSION(:) :: X  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssyr(char uplo, int n, float alpha, float *x, int incx,
```

```

float *a, int lda);

void ssyr_64(char uplo, long n, float alpha, float *x, long
incx, float *a, long lda);

```

PURPOSE

ssyr performs the symmetric rank 1 operation $A := \alpha x x^T + A$, where α is a real scalar, x is an n element vector and A is an n by n symmetric matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

A (input/output)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced. On exit, the upper triangular part of the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced. On exit, the lower triangular part of

the array A is overwritten by the lower triangular part of the updated matrix.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA \geq max(1, n). Unchanged on exit.

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NAME

ssyr2 - perform the symmetric rank 2 operation $A := \alpha x x' + \alpha y y' + A$

SYNOPSIS

```
SUBROUTINE SSYR2(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
CHARACTER * 1 UPLO
INTEGER N, INCX, INCY, LDA
REAL ALPHA
REAL X(*), Y(*), A(LDA,*)
```

```
SUBROUTINE SSYR2_64(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
CHARACTER * 1 UPLO
INTEGER*8 N, INCX, INCY, LDA
REAL ALPHA
REAL X(*), Y(*), A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE SYR2(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER :: N, INCX, INCY, LDA
REAL :: ALPHA
REAL, DIMENSION(:) :: X, Y
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SYR2_64(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER(8) :: N, INCX, INCY, LDA
REAL :: ALPHA
REAL, DIMENSION(:) :: X, Y
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssyr2(char uplo, int n, float alpha, float *x, int
```

```

        incx, float *y, int incy, float *a, int lda);

void ssyr2_64(char uplo, long n, float alpha, float *x, long
        incx, float *y, long incy, float *a, long lda);

```

PURPOSE

ssyr2 performs the symmetric rank 2 operation $A := \alpha x x^T + \alpha y y^T + A$, where alpha is a scalar, x and y are n element vectors and A is an n by n symmetric matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

A (input/output)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A

is not referenced. On exit, the upper triangular part of the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced. On exit, the lower triangular part of the array A is overwritten by the lower triangular part of the updated matrix.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

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NAME

ssyr2k - perform one of the symmetric rank 2k operations $C := \alpha A^*B' + \alpha B^*A' + \beta C$ or $C := \alpha A^*B + \alpha B^*A + \beta C$

SYNOPSIS

```
SUBROUTINE SSYR2K(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA, C,
                 LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
INTEGER N, K, LDA, LDB, LDC
REAL ALPHA, BETA
REAL A(LDA,*), B(LDB,*), C(LDC,*)
```

```
SUBROUTINE SSYR2K_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA,
                    C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
INTEGER*8 N, K, LDA, LDB, LDC
REAL ALPHA, BETA
REAL A(LDA,*), B(LDB,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE SYR2K(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B, [LDB],
                BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
INTEGER :: N, K, LDA, LDB, LDC
REAL :: ALPHA, BETA
REAL, DIMENSION(:,:) :: A, B, C
```

```
SUBROUTINE SYR2K_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B,
                   [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
INTEGER(8) :: N, K, LDA, LDB, LDC
REAL :: ALPHA, BETA
REAL, DIMENSION(:,:) :: A, B, C
```

C INTERFACE

```
#include <sunperf.h>

void ssyr2k(char uplo, char transa, int n, int k, float
    alpha, float *a, int lda, float *b, int ldb, float
    beta, float *c, int ldc);
void ssyr2k_64(char uplo, char transa, long n, long k, float
    alpha, float *a, long lda, float *b, long ldb,
    float beta, float *c, long ldc);
```

PURPOSE

ssyr2k performs one of the symmetric rank 2k operations $C := \alpha A^*B' + \alpha B^*A' + \beta C$ or $C := \alpha A^*B + \alpha B^*A + \beta C$ where α and β are scalars, C is an n by n symmetric matrix and A and B are n by k matrices in the first case and k by n matrices in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A^*B' + \alpha B^*A' + \beta C$.

TRANSA = 'T' or 't' $C := \alpha A^*B + \alpha B^*A + \beta C$.

TRANSA = 'C' or 'c' $C := \alpha A^*B + \alpha B^*A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrices A and B ,

and on entry with TRANSA = 'T' or 't' or 'C' or 'c', K specifies the number of rows of the matrices A and B. K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

REAL array of DIMENSION (LDA, ka), where ka is k when TRANSA = 'N' or 'n', and is n otherwise. Before entry with TRANSA = 'N' or 'n', the leading n by k part of the array A must contain the matrix A, otherwise the leading k by n part of the array A must contain the matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When TRANSA = 'N' or 'n' then LDA must be at least $\max(1, n)$, otherwise LDA must be at least $\max(1, k)$. Unchanged on exit.

B (input)

REAL array of DIMENSION (LDB, kb), where kb is k when TRANSA = 'N' or 'n', and is n otherwise. Before entry with TRANSA = 'N' or 'n', the leading n by k part of the array B must contain the matrix B, otherwise the leading k by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. When TRANSA = 'N' or 'n' then LDB must be at least $\max(1, n)$, otherwise LDB must be at least $\max(1, k)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. Unchanged on exit.

C (input/output)

REAL array of DIMENSION (LDC, n).

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array C must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of C is not referenced. On exit, the upper triangular part of the array C is overwritten by the upper triangular part of the updated matrix.

Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array C must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of C is not referenced. On exit, the lower triangular part of the array C is overwritten by the lower triangular part of the updated matrix.

lar part of C is not referenced. On exit, the lower triangular part of the array C is overwritten by the lower triangular part of the updated matrix.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. LDC must be at least $\max(1, n)$. Unchanged on exit.

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NAME

ssyrfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE SSYRFS(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB, X,  
                 LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER IPIVOT(*), WORK2(*)  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE SSYRFS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,  
                    X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*), WORK2(*)  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYRFS(UPLO, N, NRHS, A, [LDA], AF, [LDAF], IPIVOT, B, [LDB],  
                X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, WORK2  
REAL, DIMENSION(:) :: FERR, BERR, WORK  
REAL, DIMENSION(:,:) :: A, AF, B, X
```

```
SUBROUTINE SYRFS_64(UPLO, N, NRHS, A, [LDA], AF, [LDAF], IPIVOT, B,  
                   [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
```

```
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL, DIMENSION(:) :: FERR, BERR, WORK
REAL, DIMENSION(:, :) :: A, AF, B, X
```

C INTERFACE

```
#include <sunperf.h>
void ssyrfs(char uplo, int n, int nrhs, float *a, int lda,
            float *af, int ldaf, int *ipivot, float *b, int
            ldb, float *x, int ldx, float *ferr, float *berr,
            int *info);

void ssyrfs_64(char uplo, long n, long nrhs, float *a, long
               lda, float *af, long ldaf, long *ipivot, float *b,
               long ldb, float *x, long ldx, float *ferr, float
               *berr, long *info);
```

PURPOSE

ssyrfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)

The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^T$ or $A = L*D*L^T$ as computed by SSYTRF.

LDAF (input)

The leading dimension of the array AF. LDAF \geq
max(1,N).

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by SSYTRF.

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

X (input/output)

On entry, the solution matrix X, as computed by SSYTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq
max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ssyrk - perform one of the symmetric rank k operations C
:= alpha*A*A' + beta*C or C := alpha*A'*A + beta*C

SYNOPSIS

```
SUBROUTINE SSYRK(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
INTEGER N, K, LDA, LDC  
REAL ALPHA, BETA  
REAL A(LDA,*), C(LDC,*)
```

```
SUBROUTINE SSYRK_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
INTEGER*8 N, K, LDA, LDC  
REAL ALPHA, BETA  
REAL A(LDA,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE SYRK(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA, C,  
[LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
INTEGER :: N, K, LDA, LDC  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:, :) :: A, C
```

```
SUBROUTINE SYRK_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA,  
C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
INTEGER(8) :: N, K, LDA, LDC  
REAL :: ALPHA, BETA  
REAL, DIMENSION(:, :) :: A, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssyrk(char uplo, char transa, int n, int k, float
```

```

        alpha, float *a, int lda, float beta, float *c,
        int ldc);

void ssyrk_64(char uplo, char transa, long n, long k, float
        alpha, float *a, long lda, float beta, float *c,
        long ldc);

```

PURPOSE

ssyrk performs one of the symmetric rank k operations $C := \alpha A A^T + \beta C$ or $C := \alpha A^T A + \beta C$ where α and β are scalars, C is an n by n symmetric matrix and A is an n by k matrix in the first case and a k by n matrix in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A A^T + \beta C$.

TRANSA = 'T' or 't' $C := \alpha A^T A + \beta C$.

TRANSA = 'C' or 'c' $C := \alpha A^T A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrix A , and on entry with TRANSA = 'T' or 't' or 'C' or 'c', K specifies the number of rows of the matrix A . K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

A (input)

REAL array of DIMENSION (LDA, ka),
where ka is k when TRANSA = 'N' or 'n', and is
n otherwise. Before entry with TRANSA = 'N' or
'n', the leading n by k part of the array A
must contain the matrix A, otherwise the leading
k by n part of the array A must contain the
matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A
as declared in the calling (sub) program.
When TRANSA = 'N' or 'n' then LDA must be at
least $\max(1, n)$, otherwise LDA must be at
least $\max(1, k)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta.
Unchanged on exit.

C (input/output)

REAL array of DIMENSION (LDC, n).

Before entry with UPLO = 'U' or 'u', the lead-
ing n by n upper triangular part of the array C
must contain the upper triangular part of the
symmetric matrix and the strictly lower triangu-
lar part of C is not referenced. On exit, the
upper triangular part of the array C is overwrit-
ten by the upper triangular part of the updated
matrix.

Before entry with UPLO = 'L' or 'l', the lead-
ing n by n lower triangular part of the array C
must contain the lower triangular part of the
symmetric matrix and the strictly upper triangu-
lar part of C is not referenced. On exit, the
lower triangular part of the array C is overwrit-
ten by the lower triangular part of the updated
matrix.

LDC (input)

On entry, LDC specifies the first dimension of C
as declared in the calling (sub) program.
LDC must be at least $\max(1, n)$. Unchanged
on exit.

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NAME

ssysv - compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SSVS(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK, LWORK,
                INFO)
```

```
CHARACTER * 1 UPLO
INTEGER N, NRHS, LDA, LDB, LWORK, INFO
INTEGER IPIVOT(*)
REAL A(LDA,*), B(LDB,*), WORK(*)
```

```
SUBROUTINE SSVS_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK,
                  LWORK, INFO)
```

```
CHARACTER * 1 UPLO
INTEGER*8 N, NRHS, LDA, LDB, LWORK, INFO
INTEGER*8 IPIVOT(*)
REAL A(LDA,*), B(LDB,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SSVS(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],
                [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER :: N, NRHS, LDA, LDB, LWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE SSVS_64(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],
                  [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
INTEGER(8) :: N, NRHS, LDA, LDB, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>

void ssysv(char uplo, int n, int nrhs, float *a, int lda,
           int *ipivot, float *b, int ldb, int *info);
void ssysv_64(char uplo, long n, long nrhs, float *a, long
              lda, long *ipivot, float *b, long ldb, long
              *info);
```

PURPOSE

ssysv computes the solution to a real system of linear equations

$A * X = B$, where A is an N-by-N symmetric matrix and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{**T}$, if UPLO = 'U', or

$A = L * D * L^{**T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U * D * U^{**T}$ or $A = L * D * L^{**T}$ as computed by SSYTRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D , as determined by SSYTRF. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B .
On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LWORK$.

LWORK (input)

The length of $WORK$. $LWORK \geq 1$, and for best performance $LWORK \geq N*NB$, where NB is the optimal blocksize for SSYTRF.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $WORK$ array, returns this value as the first entry of the $WORK$ array, and no error message related to $LWORK$ is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

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NAME

ssysvx - use the diagonal pivoting factorization to compute the solution to a real system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE SSVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,  
               LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER IPIVOT(*), WORK2(*)  
REAL RCOND  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

```
SUBROUTINE SSVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT,  
                  B, LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER*8 IPIVOT(*), WORK2(*)  
REAL RCOND  
REAL A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*), FERR(*),  
BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYSVX(FACT, UPLO, N, NRHS, A, [LDA], AF, [LDAF], IPIVOT,  
                B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK], [WORK2],  
                [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT, WORK2  
REAL :: RCOND  
REAL, DIMENSION(:) :: FERR, BERR, WORK  
REAL, DIMENSION(:, :) :: A, AF, B, X
```

```
SUBROUTINE SYSVX_64(FACT, UPLO, N, NRHS, A, [LDA], AF, [LDAF],  
                   IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK],  
                   [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: FACT, UPLO
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT, WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: FERR, BERR, WORK
REAL, DIMENSION(:, :) :: A, AF, B, X

```

C INTERFACE

```

#include <sunperf.h>

void ssysvx(char fact, char uplo, int n, int nrhs, float *a,
            int lda, float *af, int ldaf, int *ipivot, float
            *b, int ldb, float *x, int ldx, float *rcond,
            float *ferr, float *berr, int *info);

void ssysvx_64(char fact, char uplo, long n, long nrhs,
               float *a, long lda, float *af, long ldaf, long
               *ipivot, float *b, long ldb, float *x, long ldx,
               float *rcond, float *ferr, float *berr, long
               *info);

```

PURPOSE

ssysvx uses the diagonal pivoting factorization to compute the solution to a real system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'N', the diagonal pivoting method is used to factor A.

The form of the factorization is

$A = U * D * U^{*T}$, if UPLO = 'U', or

$A = L * D * L^{*T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices, and D is symmetric and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with INFO = i. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

3. The system of equations is solved for X using the factored form

of A.
4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by SSYTRF.

If FACT = 'N', then AF is an output argument and on exit returns the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

IPIVOT (input or output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges

and the block structure of D , as determined by SSYTRF. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

If $FACT = 'N'$, then $IPIVOT$ is an output argument and on exit contains details of the interchanges and the block structure of D , as determined by SSYTRF.

B (input) The N -by- $NRHS$ right hand side matrix B .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

X (output)

If $INFO = 0$ or $INFO = N+1$, the N -by- $NRHS$ solution matrix X .

LDX (input)

The leading dimension of the array X . $LDX \geq \max(1,N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A . If $RCOND$ is less than the machine precision (in particular, if $RCOND = 0$), the matrix is singular to working precision. This condition is indicated by a return code of $INFO > 0$.

FERR (output)

The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If $XTRUE$ is the true solution corresponding to $X(j)$, $FERR(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for $RCOND$, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LDWORK$.

LDWORK (input)

The length of $WORK$. $LDWORK \geq 3*N$, and for best

performance LDWORK $\geq N \cdot NB$, where NB is the optimal blocksize for SSYTRF.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

ssytd2 - reduce a real symmetric matrix A to symmetric tri-diagonal form T by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE SSYTD2(UPLO, N, A, LDA, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
REAL A(LDA,*), D(*), E(*), TAU(*)
```

```
SUBROUTINE SSYTD2_64(UPLO, N, A, LDA, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
REAL A(LDA,*), D(*), E(*), TAU(*)
```

F95 INTERFACE

```
SUBROUTINE SYTD2(UPLO, N, A, [LDA], D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
REAL, DIMENSION(:) :: D, E, TAU  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SYTD2_64(UPLO, N, A, [LDA], D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
REAL, DIMENSION(:) :: D, E, TAU  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssytd2(char uplo, int n, float *a, int lda, float *d,  
           float *e, float *tau, int *info);
```

```
void ssytd2_64(char uplo, long n, float *a, long lda, float
               *d, float *e, float *tau, long *info);
```

PURPOSE

ssytd2 reduces a real symmetric matrix A to symmetric tridiagonal form T by an orthogonal similarity transformation: $Q^* A Q = T$.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored:
= 'U': Upper triangular
= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input) On entry, the symmetric matrix A. If UPLO = 'U', the leading n-by-n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n-by-n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

D (output)

The diagonal elements of the tridiagonal matrix T:
 $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i, i+1)$ if UPLO = 'U', $E(i) = A(i+1, i)$ if UPLO = 'L'.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(i+1:n) = 0$ and $v(i) = 1$; $v(1:i-1)$ is stored on exit in $A(1:i-1, i+1)$, and tau in $TAU(i)$.

If UPLO = 'L', the matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(1:i) = 0$ and $v(i+1) = 1$; $v(i+2:n)$ is stored on exit in $A(i+2:n, i)$, and tau in $TAU(i)$.

The contents of A on exit are illustrated by the following examples with $n = 5$:

if UPLO = 'U': $\begin{pmatrix} d & e & v_2 & v_3 & v_4 \\ & d & e & v_3 & v_4 \\ & & d & e & v_4 \\ & & & d & e \\ & & & & d \end{pmatrix}$	if UPLO = 'L': $\begin{pmatrix} d \\ e & d \\ v_1 & e & d \\ v_1 & v_2 & e & d \\ v_1 & v_2 & v_3 & e & d \end{pmatrix}$
---	---

where d and e denote diagonal and off-diagonal elements of T, and v_i denotes an element of the vector defining H(i).

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NAME

ssytf2 - compute the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE SSYTF2(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
INTEGER IPIV(*)  
REAL A(LDA,*)
```

```
SUBROUTINE SSYTF2_64(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIV(*)  
REAL A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE SYTF2(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE SYTF2_64(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssytf2(char uplo, int n, float *a, int lda, int *ipiv,
```

```

        int *info);

void ssytf2_64(char uplo, long n, float *a, long lda, long
        *ipiv, long *info);

```

PURPOSE

ssytf2 computes the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U' \quad \text{or} \quad A = L^*D^*L'$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, U' is the transpose of U, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored:

= 'U': Upper triangular
 = 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading n-by-n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n-by-n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIV (output)

Details of the interchanges and the block structure of D. If IPIV(k) > 0, then rows and columns k and IPIV(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIV(k) = IPIV(k-1) < 0, then rows and columns k-1 and -IPIV(k) were interchanged and D(k-1:k, k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIV(k) = IPIV(k+1) < 0, then rows and columns k+1 and

-IPIV(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

INFO (output)

= 0: successful exit
 < 0: if INFO = -k, the k-th argument had an illegal value
 > 0: if INFO = k, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

1-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

ssytrd - reduce a real symmetric matrix A to real symmetric tridiagonal form T by an orthogonal similarity transformation

SYNOPSIS

```
SUBROUTINE SSYTRD(UPLO, N, A, LDA, D, E, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, LWORK, INFO  
REAL A(LDA,*), D(*), E(*), TAU(*), WORK(*)
```

```
SUBROUTINE SSYTRD_64(UPLO, N, A, LDA, D, E, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, LWORK, INFO  
REAL A(LDA,*), D(*), E(*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRD(UPLO, N, A, [LDA], D, E, TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: D, E, TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SYTRD_64(UPLO, N, A, [LDA], D, E, TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: D, E, TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssytrd(char uplo, int n, float *a, int lda, float *d,
```

```

float *e, float *tau, int *info);

void ssytrd_64(char uplo, long n, float *a, long lda, float
*d, float *e, float *tau, long *info);

```

PURPOSE

ssytrd reduces a real symmetric matrix A to real symmetric tridiagonal form T by an orthogonal similarity transformation: $Q^*T * A * Q = T$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the orthogonal matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

D (output)

The diagonal elements of the tridiagonal matrix T:
 $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i, i+1)$ if UPLO = 'U', $E(i) = A(i+1, i)$ if UPLO = 'L'.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. LWORK ≥ 1 . For optimum performance LWORK $\geq N \cdot NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(i+1:n) = 0$ and $v(i) = 1$; $v(1:i-1)$ is stored on exit in $A(1:i-1, i+1)$, and tau in TAU(i).

If UPLO = 'L', the matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a real scalar, and v is a real vector with $v(1:i) = 0$ and $v(i+1) = 1$; $v(i+2:n)$ is stored on exit in $A(i+2:n, i)$, and tau in TAU(i).

The contents of A on exit are illustrated by the following examples with $n = 5$:

if UPLO = 'U':	if UPLO = 'L':
(d e v2 v3 v4)	(d
))
(d e v3 v4)	(e d
))
(d e v4)	(v1 e d
))
(d e)	(v1 v2 e d

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NAME

ssytrf - compute the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE SSYTRF(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, LDWORK, INFO  
INTEGER IPIVOT(*)  
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE SSYTRF_64(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, LDWORK, INFO  
INTEGER*8 IPIVOT(*)  
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRF(UPLO, N, A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SYTRF_64(UPLO, N, A, [LDA], IPIVOT, [WORK], [LDWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```

#include <sunperf.h>

void ssytrf(char uplo, int n, float *a, int lda, int
            *ipivot, int *info);

void ssytrf_64(char uplo, long n, float *a, long lda, long
               *ipivot, long *info);

```

PURPOSE

ssytrf computes the factorization of a real symmetric matrix A using the Bunch-Kaufman diagonal pivoting method. The form of the factorization is

$$A = U*D*U^{*T} \quad \text{or} \quad A = L*D*L^{*T}$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and

$D(k-1:k, k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1, k:k+1)$ is a 2-by-2 diagonal block.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LDWORK$.

$LDWORK$ (input)

The length of $WORK$. $LDWORK \geq 1$. For best performance $LDWORK \geq N * NB$, where NB is the block size returned by $ILAENV$.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $WORK$ array, returns this value as the first entry of the $WORK$ array, and no error message related to $LDWORK$ is issued by $XERBLA$.

INFO (output)

= 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value
 > 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

If $UPLO = 'U'$, then $A = U * D * U'$, where

$$U = P(n) * U(n) * \dots * P(k) * U(k) * \dots,$$

i.e., U is a product of terms $P(k) * U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by $IPIVOT(k)$, and $U(k)$ is a unit upper triangular matrix, such that if the diagonal block $D(k)$ is of order s ($s = 1$ or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(1:k-1, k)$. If $s = 2$, the upper triangle of $D(k)$ overwrites $A(k-1, k-1)$, $A(k-1, k)$, and $A(k, k)$, and v overwrites $A(1:k-2, k-1:k)$.

If $UPLO = 'L'$, then $A = L * D * L'$, where

$$L = P(1) * L(1) * \dots * P(k) * L(k) * \dots,$$

i.e., L is a product of terms $P(k) * L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by $IPIVOT(k)$, and $L(k)$ is a unit lower triangular matrix, such that if the diagonal block $D(k)$ is of order s ($s = 1$ or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(k+1:n,k)$. If $s = 2$, the lower triangle of $D(k)$ overwrites $A(k,k)$, $A(k+1,k)$, and $A(k+1,k+1)$, and v overwrites $A(k+2:n,k:k+1)$.

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NAME

ssytri - compute the inverse of a real symmetric indefinite matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by SSYTRF

SYNOPSIS

```
SUBROUTINE SSYTRI(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*)  
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE SSYTRI_64(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*)  
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRI(UPLO, N, A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE SYTRI_64(UPLO, N, A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```

void ssytri(char uplo, int n, float *a, int lda, int
            *ipivot, int *info);

void ssytri_64(char uplo, long n, float *a, long lda, long
               *ipivot, long *info);

```

PURPOSE

ssytri computes the inverse of a real symmetric indefinite matrix A using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by SSYTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U*D*U^{**T}$;
 = 'L': Lower triangular, form is $A = L*D*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by SSYTRF.

On exit, if INFO = 0, the (symmetric) inverse of the original matrix. If UPLO = 'U', the upper triangular part of the inverse is formed and the part of A below the diagonal is not referenced; if UPLO = 'L' the lower triangular part of the inverse is formed and the part of A above the diagonal is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by SSYTRF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

ssytrs - solve a system of linear equations $A \cdot X = B$ with a real symmetric matrix A using the factorization $A = U \cdot D \cdot U^T$ or $A = L \cdot D \cdot L^T$ computed by SSYTRF

SYNOPSIS

```
SUBROUTINE SSYTRS(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE SSYTRS_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE SYTRS(UPLO, N, NRHS, A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A, B
```

```
SUBROUTINE SYTRS_64(UPLO, N, NRHS, A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL, DIMENSION(:, :) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ssytrs(char uplo, int n, int nrhs, float *a, int lda,  
            int *ipivot, float *b, int ldb, int *info);
```

```

void ssytrs_64(char uplo, long n, long nrhs, float *a, long
               lda, long *ipivot, float *b, long ldb, long
               *info);

```

PURPOSE

ssytrs solves a system of linear equations $A \cdot X = B$ with a real symmetric matrix A using the factorization $A = U \cdot D \cdot U^{**T}$ or $A = L \cdot D \cdot L^{**T}$ computed by SSYTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U \cdot D \cdot U^{**T}$;
 = 'L': Lower triangular, form is $A = L \cdot D \cdot L^{**T}$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by SSYTRF.

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by SSYTRF.

B (input/output)

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

stbcon - estimate the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE STBCON(NORM, UPLO, DIAG, N, KD, A, LDA, RCOND, WORK,  
                 WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER N, KD, LDA, INFO  
INTEGER WORK2(*)  
REAL RCOND  
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE STBCON_64(NORM, UPLO, DIAG, N, KD, A, LDA, RCOND, WORK,  
                   WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER*8 N, KD, LDA, INFO  
INTEGER*8 WORK2(*)  
REAL RCOND  
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TBCON(NORM, UPLO, DIAG, [N], KD, A, [LDA], RCOND, [WORK],  
                [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER :: N, KD, LDA, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE TBCON_64(NORM, UPLO, DIAG, [N], KD, A, [LDA], RCOND,  
                  [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER(8) :: N, KD, LDA, INFO
```

```

INTEGER(8), DIMENSION(:) :: WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:,:) :: A

```

C INTERFACE

```

#include <sunperf.h>
void stbcon(char norm, char uplo, char diag, int n, int kd,
            float *a, int lda, float *rcond, int *info);

void stbcon_64(char norm, char uplo, char diag, long n, long
              kd, float *a, long lda, float *rcond, long *info);

```

PURPOSE

stbcon estimates the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
 = '1' or 'O': 1-norm;
 = 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first $kd+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. LDA \geq KD+1.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

stbmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

SYNOPSIS

```
SUBROUTINE STBMV(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, K, LDA, INCY  
REAL A(LDA,*), Y(*)
```

```
SUBROUTINE STBMV_64(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, K, LDA, INCY  
REAL A(LDA,*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TBMV(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, K, LDA, INCY  
REAL, DIMENSION(:) :: Y  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE TBMV_64(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, K, LDA, INCY  
REAL, DIMENSION(:) :: Y  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stbmv(char uplo, char transa, char diag, int n, int k,  
float *a, int lda, float *y, int incy);
```

```
void stbmv_64(char uplo, char transa, char diag, long n,
```

```
long k, float *a, long lda, float *y, long incy);
```

PURPOSE

stbmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular band matrix, with $(k + 1)$ diagonals.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := A'*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

K (input)

On entry with UPLO = 'U' or 'u', K specifies the number of super-diagonals of the matrix A . On

entry with UPLO = 'L' or 'l', K specifies the number of sub-diagonals of the matrix A. K >= 0. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading (k + 1) by n part of the array A must contain the upper triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (k + 1) of the array, the first super-diagonal starting at position 2 in row k, and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer an upper triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer a lower triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Note that when DIAG = 'U' or 'u' the elements of the array A corresponding to the diagonal elements of the matrix are not referenced, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= (k + 1). Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

stbrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix

SYNOPSIS

```
SUBROUTINE STBRFS(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B, LDB,  
X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, KD, NRHS, LDA, LDB, LDX, INFO  
INTEGER WORK2(*)  
REAL A(LDA,*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE STBRFS_64(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B,  
LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, KD, NRHS, LDA, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
REAL A(LDA,*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TBRFS(UPLO, [TRANSA], DIAG, N, KD, NRHS, A, [LDA], B,  
[LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, KD, NRHS, LDA, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL, DIMENSION(:) :: FERR, BERR, WORK  
REAL, DIMENSION(:,) :: A, B, X
```

```
SUBROUTINE TBRFS_64(UPLO, [TRANSA], DIAG, N, KD, NRHS, A, [LDA],  
B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2  
REAL, DIMENSION(:) :: FERR, BERR, WORK  
REAL, DIMENSION(:,) :: A, B, X
```

C INTERFACE

```
#include <sunperf.h>

void stbrfs(char uplo, char transa, char diag, int n, int
            kd, int nrhs, float *a, int lda, float *b, int
            ldb, float *x, int ldx, float *ferr, float *berr,
            int *info);

void stbrfs_64(char uplo, char transa, char diag, long n,
               long kd, long nrhs, float *a, long lda, float *b,
               long ldb, float *x, long ldx, float *ferr, float
               *berr, long *info);
```

PURPOSE

stbrfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix.

The solution matrix X must be computed by STBTRS or some other means before entering this routine. STBRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first kd+1 rows of the array. The j-th column of A is stored in the j-th column of

the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. LDA \geq KD+1.

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input) The solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

stbsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

SYNOPSIS

```
SUBROUTINE STBSV(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, K, LDA, INCY  
REAL A(LDA,*), Y(*)
```

```
SUBROUTINE STBSV_64(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, K, LDA, INCY  
REAL A(LDA,*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TBSV(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, K, LDA, INCY  
REAL, DIMENSION(:) :: Y  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE TBSV_64(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, K, LDA, INCY  
REAL, DIMENSION(:) :: Y  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stbsv(char uplo, char transa, char diag, int n, int k,  
float *a, int lda, float *y, int incy);
```

```
void stbsv_64(char uplo, char transa, char diag, long n,
```

```
long k, float *a, long lda, float *y, long incy);
```

PURPOSE

stbsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular band matrix, with $(k + 1)$ diagonals.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the equations to be solved as follows:

TRANSA = 'N' or 'n' $A*x = b$.

TRANSA = 'T' or 't' $A'*x = b$.

TRANSA = 'C' or 'c' $A'*x = b$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

K (input)

On entry with UPLO = 'U' or 'u', K specifies the number of super-diagonals of the matrix A. On entry with UPLO = 'L' or 'l', K specifies the number of sub-diagonals of the matrix A. $K \geq 0$. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading ($k + 1$) by n part of the array A must contain the upper triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row ($k + 1$) of the array, the first super-diagonal starting at position 2 in row k, and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer an upper triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading ($k + 1$) by n part of the array A must contain the lower triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer a lower triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Note that when DIAG = 'U' or 'u' the elements of the array A corresponding to the diagonal elements of the matrix are not referenced, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq (k + 1)$. Unchanged on exit.

Y (input/output)

($1 + (n - 1) * \text{abs}(\text{INCY})$). Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwrit-

ten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

stbtrs - solve a triangular system of the form $A * X = B$
or $A^{**T} * X = B$,

SYNOPSIS

```
SUBROUTINE STBTRS(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B, LDB,  
INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, KD, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE STBTRS_64(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B,  
LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TBTRS(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA], B,  
[LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE TBTRS_64(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA], B,  
[LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stbtrs(char uplo, char transa, char diag, int n, int  
kd, int nrhs, float *a, int lda, float *b, int  
ldb, int *info);
```

```
void stbtrs_64(char uplo, char transa, char diag, long n,
              long kd, long nrhs, float *a, long lda, float *b,
              long ldb, long *info);
```

PURPOSE

stbtrs solves a triangular system of the form

$A * X = B$ or $A^{**T} * X = B$

where A is a triangular band matrix of order N, and B is an N-by NRHS matrix. A check is made to verify that A is non-singular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

TRANSA (input)

Specifies the form the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose = Transpose)

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first $kd+1$ rows of A. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

B (input/output)

On entry, the right hand side matrix B. On exit,

if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element of A is zero, indicating that the matrix is singular and the solutions X have not been computed.

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NAME

stgevc - compute some or all of the right and/or left generalized eigenvectors of a pair of real upper triangular matrices (A,B)

SYNOPSIS

```
SUBROUTINE STGEVC(SIDE, HOWMNY, SELECT, N, A, LDA, B, LDB, VL, LDVL,  
  VR, LDVR, MM, M, WORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
INTEGER N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL SELECT(*)  
REAL A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

```
SUBROUTINE STGEVC_64(SIDE, HOWMNY, SELECT, N, A, LDA, B, LDB, VL,  
  LDVL, VR, LDVR, MM, M, WORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL*8 SELECT(*)  
REAL A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGEVC(SIDE, HOWMNY, SELECT, N, A, [LDA], B, [LDB], VL,  
  [LDVL], VR, [LDVR], MM, M, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
INTEGER :: N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL, DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,:) :: A, B, VL, VR
```

```
SUBROUTINE TGEVC_64(SIDE, HOWMNY, SELECT, N, A, [LDA], B, [LDB], VL,  
  [LDVL], VR, [LDVR], MM, M, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, MM, M, INFO  
LOGICAL(8), DIMENSION(:) :: SELECT
```

```
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:,:) :: A, B, VL, VR
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stgevc(char side, char howmny, int *select, int n,
            float *a, int lda, float *b, int ldb, float *vl,
            int ldvl, float *vr, int ldvr, int mm, int *m, int
            *info);
```

```
void stgevc_64(char side, char howmny, long *select, long n,
               float *a, long lda, float *b, long ldb, float *vl,
               long ldvl, float *vr, long ldvr, long mm, long *m,
               long *info);
```

PURPOSE

stgevc computes some or all of the right and/or left generalized eigenvectors of a pair of real upper triangular matrices (A,B).

The right generalized eigenvector x and the left generalized eigenvector y of (A,B) corresponding to a generalized eigenvalue w are defined by:

$$(A - wB) * x = 0 \quad \text{and} \quad y^{*H} * (A - wB) = 0$$

where y^{*H} denotes the conjugate transpose of y .

If an eigenvalue w is determined by zero diagonal elements of both A and B , a unit vector is returned as the corresponding eigenvector.

If all eigenvectors are requested, the routine may either return the matrices X and/or Y of right or left eigenvectors of (A,B), or the products $Z*X$ and/or $Q*Y$, where Z and Q are input orthogonal matrices. If (A,B) was obtained from the generalized real-Schur factorization of an original pair of matrices

$$(A0, B0) = (Q*A*Z^{*H}, Q*B*Z^{*H}),$$

then $Z*X$ and $Q*Y$ are the matrices of right or left eigenvectors of A .

A must be block upper triangular, with 1-by-1 and 2-by-2 diagonal blocks. Corresponding to each 2-by-2 diagonal block is a complex conjugate pair of eigenvalues and eigenvectors; only one eigenvector of the pair is computed, namely the one corresponding to the eigenvalue with positive imaginary part.

ARGUMENTS

```
SIDE (input)
    = 'R': compute right eigenvectors only;
```

= 'L': compute left eigenvectors only;
 = 'B': compute both right and left eigenvectors.

HOWMNY (input)
 = 'A': compute all right and/or left eigenvectors;
 = 'B': compute all right and/or left eigenvectors,
 and backtransform them using the input matrices
 supplied in VR and/or VL; = 'S': compute selected
 right and/or left eigenvectors, specified by the
 logical array SELECT.

SELECT (input)
 If HOWMNY='S', SELECT specifies the eigenvectors
 to be computed. If HOWMNY='A' or 'B', SELECT is
 not referenced. To select the real eigenvector
 corresponding to the real eigenvalue $w(j)$,
 SELECT(j) must be set to .TRUE. To select the
 complex eigenvector corresponding to a complex
 conjugate pair $w(j)$ and $w(j+1)$, either SELECT(j)
 or SELECT(j+1) must be set to .TRUE..

N (input) The order of the matrices A and B. $N \geq 0$.

A (input) The upper quasi-triangular matrix A.

LDA (input)
 The leading dimension of array A. $LDA \geq \max(1, N)$.

B (input) The upper triangular matrix B. If A has a 2-by-2
 diagonal block, then the corresponding 2-by-2
 block of B must be diagonal with positive ele-
 ments.

LDB (input)
 The leading dimension of array B. $LDB \geq \max(1, N)$.

VL (input/output)
 On entry, if SIDE = 'L' or 'B' and HOWMNY = 'B',
 VL must contain an N-by-N matrix Q (usually the
 orthogonal matrix Q of left Schur vectors returned
 by SHGEQZ). On exit, if SIDE = 'L' or 'B', VL
 contains: if HOWMNY = 'A', the matrix Y of left
 eigenvectors of (A,B); if HOWMNY = 'B', the matrix
 $Q*Y$; if HOWMNY = 'S', the left eigenvectors of
 (A,B) specified by SELECT, stored consecutively in
 the columns of VL, in the same order as their
 eigenvalues. If SIDE = 'R', VL is not referenced.

A complex eigenvector corresponding to a complex
 eigenvalue is stored in two consecutive columns,
 the first holding the real part, and the second
 the imaginary part.

LDVL (input)
 The leading dimension of array VL. $LDVL \geq \max(1, N)$ if SIDE = 'L' or 'B'; $LDVL \geq 1$ other-
 wise.

VR (input/output)
 On entry, if SIDE = 'R' or 'B' and HOWMNY = 'B',

VR must contain an N-by-N matrix Q (usually the orthogonal matrix Z of right Schur vectors returned by SHGEQZ). On exit, if SIDE = 'R' or 'B', VR contains: if HOWMNY = 'A', the matrix X of right eigenvectors of (A,B); if HOWMNY = 'B', the matrix Z*X; if HOWMNY = 'S', the right eigenvectors of (A,B) specified by SELECT, stored consecutively in the columns of VR, in the same order as their eigenvalues. If SIDE = 'L', VR is not referenced.

A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the real part and the second the imaginary part.

LDVR (input)

The leading dimension of the array VR. LDVR \geq max(1,N) if SIDE = 'R' or 'B'; LDVR \geq 1 otherwise.

MM (input)

The number of columns in the arrays VL and/or VR. MM \geq M.

M (output)

The number of columns in the arrays VL and/or VR actually used to store the eigenvectors. If HOWMNY = 'A' or 'B', M is set to N. Each selected real eigenvector occupies one column and each selected complex eigenvector occupies two columns.

WORK (workspace)

dimension(6*N)

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: the 2-by-2 block (INFO:INFO+1) does not have a complex eigenvalue.

FURTHER DETAILS

Allocation of workspace:

WORK(j) = 1-norm of j-th column of A, above the diagonal

WORK(N+j) = 1-norm of j-th column of B, above the diagonal

WORK(2*N+1:3*N) = real part of eigenvector

WORK(3*N+1:4*N) = imaginary part of eigenvector

WORK(4*N+1:5*N) = real part of back-transformed eigenvector

WORK(5*N+1:6*N) = imaginary part of back-transformed eigenvector

Rowwise vs. columnwise solution methods:

Finding a generalized eigenvector consists basically of solving the singular triangular system

$$(A - w B) x = 0 \quad (\text{for right}) \text{ or: } (A - w B)^{**H} y = 0 \\ (\text{for left})$$

Consider finding the i -th right eigenvector (assume all eigenvalues are real). The equation to be solved is:

$$0 = \sum_{k=j}^{i-1} C(j,k) v(k) = \sum_{k=j}^{i-1} C(j,k) v(k) \quad \text{for } j = i, \dots, 1$$

where $C = (A - w B)$ (The components $v(i+1:n)$ are 0.)

The "rowwise" method is:

```
(1) v(i) := 1
for j = i-1, . . . , 1:
    (2) compute s = - sum C(j,k) v(k) and
                k=j+1
    (3) v(j) := s / C(j,j)
```

Step 2 is sometimes called the "dot product" step, since it is an inner product between the j -th row and the portion of the eigenvector that has been computed so far.

The "columnwise" method consists basically in doing the sums for all the rows in parallel. As each $v(j)$ is computed, the contribution of $v(j)$ times the j -th column of C is added to the partial sums. Since FORTRAN arrays are stored columnwise, this has the advantage that at each step, the elements of C that are accessed are adjacent to one another, whereas with the rowwise method, the elements accessed at a step are spaced LDA (and LDB) words apart.

When finding left eigenvectors, the matrix in question is the transpose of the one in storage, so the rowwise method then actually accesses columns of A and B at each step, and so is the preferred method.

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NAME

stgexc - reorder the generalized real Schur decomposition of a real matrix pair (A,B) using an orthogonal equivalence transformation $(A, B) = Q * (A, B) * Z'$,

SYNOPSIS

```
SUBROUTINE STGEXC(WANTQ, WANTZ, N, A, LDA, B, LDB, Q, LDQ, Z, LDZ,
  IFST, ILST, WORK, LWORK, INFO)
```

```
INTEGER N, LDA, LDB, LDQ, LDZ, IFST, ILST, LWORK, INFO
LOGICAL WANTQ, WANTZ
REAL A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*), WORK(*)
```

```
SUBROUTINE STGEXC_64(WANTQ, WANTZ, N, A, LDA, B, LDB, Q, LDQ, Z, LDZ,
  IFST, ILST, WORK, LWORK, INFO)
```

```
INTEGER*8 N, LDA, LDB, LDQ, LDZ, IFST, ILST, LWORK, INFO
LOGICAL*8 WANTQ, WANTZ
REAL A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGEXC(WANTQ, WANTZ, N, A, [LDA], B, [LDB], Q, [LDQ], Z,
  [LDZ], IFST, ILST, [WORK], [LWORK], [INFO])
```

```
INTEGER :: N, LDA, LDB, LDQ, LDZ, IFST, ILST, LWORK, INFO
LOGICAL :: WANTQ, WANTZ
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:, :) :: A, B, Q, Z
```

```
SUBROUTINE TGEXC_64(WANTQ, WANTZ, N, A, [LDA], B, [LDB], Q, [LDQ], Z,
  [LDZ], IFST, ILST, [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: N, LDA, LDB, LDQ, LDZ, IFST, ILST, LWORK, INFO
LOGICAL(8) :: WANTQ, WANTZ
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:, :) :: A, B, Q, Z
```

C INTERFACE

```
#include <sunperf.h>

void stgexc(int wantq, int wantz, int n, float *a, int lda,
           float *b, int ldb, float *q, int ldq, float *z,
           int ldz, int *ifst, int *ilst, int *info);

void stgexc_64(long wantq, long wantz, long n, float *a,
              long lda, float *b, long ldb, float *q, long ldq,
              float *z, long ldz, long *ifst, long *ilst, long
              *info);
```

PURPOSE

stgexc reorders the generalized real Schur decomposition of a real matrix pair (A,B) using an orthogonal equivalence transformation

so that the diagonal block of (A, B) with row index IFST is moved to row ILST.

(A, B) must be in generalized real Schur canonical form (as returned by SGGES), i.e. A is block upper triangular with 1-by-1 and 2-by-2 diagonal blocks. B is upper triangular.

Optionally, the matrices Q and Z of generalized Schur vectors are updated.

$$Q(\text{in}) * A(\text{in}) * Z(\text{in})' = Q(\text{out}) * A(\text{out}) * Z(\text{out})'$$

$$Q(\text{in}) * B(\text{in}) * Z(\text{in})' = Q(\text{out}) * B(\text{out}) * Z(\text{out})'$$

ARGUMENTS

WANTQ (input)

WANTZ (input)

N (input) The order of the matrices A and B. N >= 0.

A (input/output)

On entry, the matrix A in generalized real Schur canonical form. On exit, the updated matrix A, again in generalized real Schur canonical form.

LDA (input)

The leading dimension of the array A. LDA >= max(1,N).

B (input/output)

On entry, the matrix B in generalized real Schur canonical form (A,B). On exit, the updated matrix B, again in generalized real Schur canonical form (A,B).

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

Q (input/output)
 On entry, if WANTQ = .TRUE., the orthogonal matrix Q. On exit, the updated matrix Q. If WANTQ = .FALSE., Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. LDQ >= 1.
 If WANTQ = .TRUE., LDQ >= N.

Z (input/output)
 On entry, if WANTZ = .TRUE., the orthogonal matrix Z. On exit, the updated matrix Z. If WANTZ = .FALSE., Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. LDZ >= 1.
 If WANTZ = .TRUE., LDZ >= N.

IFST (input/output)
 Specify the reordering of the diagonal blocks of (A, B). The block with row index IFST is moved to row ILST, by a sequence of swapping between adjacent blocks. On exit, if IFST pointed on entry to the second row of a 2-by-2 block, it is changed to point to the first row; ILST always points to the first row of the block in its final position (which may differ from its input value by +1 or -1). 1 <= IFST, ILST <= N.

ILST (input/output)
 See the description of IFST.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK >= 4*N + 16.
 If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
 =0: successful exit.
 <0: if INFO = -i, the i-th argument had an illegal value.
 =1: The transformed matrix pair (A, B) would be too far from generalized Schur form; the problem is ill-conditioned. (A, B) may have been partially reordered, and ILST points to the first row of the current position of the block being moved.

FURTHER DETAILS

Based on contributions by
 Bo Kagstrom and Peter Poromaa, Department of Computing
 Science,

Umea University, S-901 87 Umea, Sweden.

- [1] B. Kagstrom; A Direct Method for Reordering Eigenvalues in the Generalized Real Schur Form of a Regular Matrix Pair (A, B), in M.S. Moonen et al (eds), Linear Algebra for Large Scale and Real-Time Applications, Kluwer Academic Publ. 1993, pp 195-218.

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NAME

stgsen - reorder the generalized real Schur decomposition of a real matrix pair (A, B) (in terms of an orthonormal equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix A and the upper triangular B

SYNOPSIS

```
SUBROUTINE STGSEN(IJOB, WANTQ, WANTZ, SELECT, N, A, LDA, B, LDB,
    ALPHAR, ALPHAI, BETA, Q, LDQ, Z, LDZ, M, PL, PR, DIF, WORK,
    LWORK, IWORK, LIWORK, INFO)
```

```
INTEGER IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL WANTQ, WANTZ
LOGICAL SELECT(*)
REAL PL, PR
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
Q(LDQ,*), Z(LDZ,*), DIF(*), WORK(*)
```

```
SUBROUTINE STGSEN_64(IJOB, WANTQ, WANTZ, SELECT, N, A, LDA, B, LDB,
    ALPHAR, ALPHAI, BETA, Q, LDQ, Z, LDZ, M, PL, PR, DIF, WORK,
    LWORK, IWORK, LIWORK, INFO)
```

```
INTEGER*8 IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER*8 IWORK(*)
LOGICAL*8 WANTQ, WANTZ
LOGICAL*8 SELECT(*)
REAL PL, PR
REAL A(LDA,*), B(LDB,*), ALPHAR(*), ALPHAI(*), BETA(*),
Q(LDQ,*), Z(LDZ,*), DIF(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGSSEN(IJOB, WANTQ, WANTZ, SELECT, N, A, [LDA], B, [LDB],
    ALPHAR, ALPHAI, BETA, Q, [LDQ], Z, [LDZ], M, PL, PR, DIF, [WORK],
    [LWORK], [IWORK], [LIWORK], [INFO])
```

```

INTEGER :: IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL :: WANTQ, WANTZ
LOGICAL, DIMENSION(:) :: SELECT
REAL :: PL, PR
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, DIF, WORK
REAL, DIMENSION(:,) :: A, B, Q, Z
SUBROUTINE TSGEN_64(IJOB, WANTQ, WANTZ, SELECT, N, A, [LDA], B, [LDB],
ALPHAR, ALPHAI, BETA, Q, [LDQ], Z, [LDZ], M, PL, PR, DIF, [WORK],
[LWORK], [IWORK], [LIWORK], [INFO])

```

```

INTEGER(8) :: IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8) :: WANTQ, WANTZ
LOGICAL(8), DIMENSION(:) :: SELECT
REAL :: PL, PR
REAL, DIMENSION(:) :: ALPHAR, ALPHAI, BETA, DIF, WORK
REAL, DIMENSION(:,) :: A, B, Q, Z

```

C INTERFACE

```
#include <sunperf.h>
```

```

void stgsen(int ijob, int wantq, int wantz, int *select, int
n, float *a, int lda, float *b, int ldb, float
*alphar, float *alphai, float *beta, float *q, int
ldq, float *z, int ldz, int *m, float *pl, float
*pr, float *dif, int *info);

```

```

void stgsen_64(long ijob, long wantq, long wantz, long
*select, long n, float *a, long lda, float *b,
long ldb, float *alphar, float *alphai, float
*beta, float *q, long ldq, float *z, long ldz,
long *m, float *pl, float *pr, float *dif, long
*info);

```

PURPOSE

stgsen reorders the generalized real Schur decomposition of a real matrix pair (A, B) (in terms of an orthonormal equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix A and the upper triangular B. The leading columns of Q and Z form orthonormal bases of the corresponding left and right eigenspaces (deflating subspaces). (A, B) must be in generalized real Schur canonical form (as returned by SGGES), i.e. A is block upper triangular with 1-by-1 and 2-by-2 diagonal blocks. B is upper triangular.

STGSEN also computes the generalized eigenvalues

$$w(j) = (\text{ALPHAR}(j) + i*\text{ALPHAI}(j))/\text{BETA}(j)$$

of the reordered matrix pair (A, B).

Optionally, STGSEN computes the estimates of reciprocal

condition numbers for eigenvalues and eigenspaces. These are $\text{Difu}[(A_{11}, B_{11}), (A_{22}, B_{22})]$ and $\text{Difl}[(A_{11}, B_{11}), (A_{22}, B_{22})]$, i.e. the separation(s) between the matrix pairs (A_{11}, B_{11}) and (A_{22}, B_{22}) that correspond to the selected cluster and the eigenvalues outside the cluster, resp., and norms of "projections" onto left and right eigenspaces w.r.t. the selected cluster in the (1,1)-block.

ARGUMENTS

IJOB (input)

Specifies whether condition numbers are required for the cluster of eigenvalues (PL and PR) or the deflating subspaces (Difu and Difl):

=0: Only reorder w.r.t. SELECT. No extras.

=1: Reciprocal of norms of "projections" onto left and right eigenspaces w.r.t. the selected cluster (PL and PR). =2: Upper bounds on Difu and Difl. F-norm-based estimate

(DIF(1:2)).

=3: Estimate of Difu and Difl. 1-norm-based estimate

(DIF(1:2)). About 5 times as expensive as IJOB = 2. =4: Compute PL, PR and DIF (i.e. 0, 1 and 2 above): Economic version to get it all. =5: Compute PL, PR and DIF (i.e. 0, 1 and 3 above)

WANTQ (input)

WANTZ (input)

SELECT (input)

SELECT specifies the eigenvalues in the selected cluster. To select a real eigenvalue $w(j)$, SELECT(j) must be set to $w(j)$ and $w(j+1)$, corresponding to a 2-by-2 diagonal block, either SELECT(j) or SELECT(j+1) or both must be set to either both included in the cluster or both excluded.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the upper quasi-triangular matrix A, with (A, B) in generalized real Schur canonical form. On exit, A is overwritten by the reordered matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the upper triangular matrix B, with (A, B) in generalized real Schur canonical form. On exit, B is overwritten by the reordered matrix B.

LDB (input)

The leading dimension of the array B. $LDB \geq$

max(1,N).

ALPHAR (output)

On exit, $(\text{ALPHAR}(j) + \text{ALPHAI}(j)*i)/\text{BETA}(j)$, $j=1,\dots,N$, will be the generalized eigenvalues. $\text{ALPHAR}(j) + \text{ALPHAI}(j)*i$ and $\text{BETA}(j)$, $j=1,\dots,N$ are the diagonals of the complex Schur form (S,T) that would result if the 2-by-2 diagonal blocks of the real generalized Schur form of (A,B) were further reduced to triangular form using complex unitary transformations. If $\text{ALPHAI}(j)$ is zero, then the j -th eigenvalue is real; if positive, then the j -th and $(j+1)$ -st eigenvalues are a complex conjugate pair, with $\text{ALPHAI}(j+1)$ negative.

ALPHAI (output)

See the description of ALPHAR.

BETA (output)

See the description of ALPHAR.

Q (input/output)

On entry, if $\text{WANTQ} = \text{.TRUE.}$, Q is an N-by-N matrix. On exit, Q has been postmultiplied by the left orthogonal transformation matrix which reorder (A, B); The leading M columns of Q form orthonormal bases for the specified pair of left eigenspaces (deflating subspaces). If $\text{WANTQ} = \text{.FALSE.}$, Q is not referenced.

LDQ (input)

The leading dimension of the array Q. $\text{LDQ} \geq 1$; and if $\text{WANTQ} = \text{.TRUE.}$, $\text{LDQ} \geq N$.

Z (input/output)

On entry, if $\text{WANTZ} = \text{.TRUE.}$, Z is an N-by-N matrix. On exit, Z has been postmultiplied by the left orthogonal transformation matrix which reorder (A, B); The leading M columns of Z form orthonormal bases for the specified pair of left eigenspaces (deflating subspaces). If $\text{WANTZ} = \text{.FALSE.}$, Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $\text{LDZ} \geq 1$; If $\text{WANTZ} = \text{.TRUE.}$, $\text{LDZ} \geq N$.

M (output)

The dimension of the specified pair of left and right eigenspaces (deflating subspaces). $0 \leq M \leq N$.

PL (output)

If $\text{IJOB} = 1, 4$ or 5 , PL, PR are lower bounds on the reciprocal of the norm of "projections" onto left and right eigenspaces with respect to the selected cluster. $0 < \text{PL}, \text{PR} \leq 1$. If $M = 0$ or $M = N$, $\text{PL} = \text{PR} = 1$. If $\text{IJOB} = 0, 2$ or 3 , PL and PR are not referenced.

PR (output)

See the description of PL.

DIF (output)

If IJOB \geq 2, DIF(1:2) store the estimates of Difu and Difl.
If IJOB = 2 or 4, DIF(1:2) are F-norm-based upper bounds on Difu and Difl. If IJOB = 3 or 5, DIF(1:2) are 1-norm-based estimates of Difu and Difl. If M = 0 or N, DIF(1:2) = F-norm([A, B]). If IJOB = 0 or 1, DIF is not referenced.

WORK (workspace)

If IJOB = 0, WORK is not referenced. Otherwise, on exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq $4*N+16$. If IJOB = 1, 2 or 4, LWORK \geq $\text{MAX}(4*N+16, 2*M*(N-M))$. If IJOB = 3 or 5, LWORK \geq $\text{MAX}(4*N+16, 4*M*(N-M))$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

If IJOB = 0, IWORK is not referenced. Otherwise, on exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. LIWORK \geq 1. If IJOB = 1, 2 or 4, LIWORK \geq N+6. If IJOB = 3 or 5, LIWORK \geq $\text{MAX}(2*M*(N-M), N+6)$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

=0: Successful exit.
<0: If INFO = -i, the i-th argument had an illegal value.
=1: Reordering of (A, B) failed because the transformed matrix pair (A, B) would be too far from generalized Schur form; the problem is very ill-conditioned. (A, B) may have been partially reordered. If requested, 0 is returned in DIF(*), PL and PR.

FURTHER DETAILS

STGSEN first collects the selected eigenvalues by computing orthogonal U and W that move them to the top left corner of

(A, B). In other words, the selected eigenvalues are the eigenvalues of (A11, B11) in:

$$U'*(A, B)*W = \begin{pmatrix} (A11 & A12) & (B11 & B12) & n1 \\ (0 & A22) & (0 & B22) & n2 \\ n1 & n2 & n1 & n2 \end{pmatrix}$$

where $N = n1+n2$ and U' means the transpose of U . The first $n1$ columns of U and W span the specified pair of left and right eigenspaces (deflating subspaces) of (A, B).

If (A, B) has been obtained from the generalized real Schur decomposition of a matrix pair $(C, D) = Q*(A, B)*Z'$, then the reordered generalized real Schur form of (C, D) is given by

$$(C, D) = (Q*U)*(U'*(A, B)*W)*(Z*W)',$$

and the first $n1$ columns of $Q*U$ and $Z*W$ span the corresponding deflating subspaces of (C, D) (Q and Z store $Q*U$ and $Z*W$, resp.).

Note that if the selected eigenvalue is sufficiently ill-conditioned, then its value may differ significantly from its value before reordering.

The reciprocal condition numbers of the left and right eigenspaces spanned by the first $n1$ columns of U and W (or $Q*U$ and $Z*W$) may be returned in $DIF(1:2)$, corresponding to $Difu$ and $Difl$, resp.

The $Difu$ and $Difl$ are defined as:
 $ifu[(A11, B11), (A22, B22)] = \text{sigma-min}(Zu)$
 and

where $\text{sigma-min}(Zu)$ is the smallest singular value of the $(2*n1*n2)$ -by- $(2*n1*n2)$ matrix
 $u = [\text{kron}(In2, A11) \quad -\text{kron}(A22', In1)]$
 $[\text{kron}(In2, B11) \quad -\text{kron}(B22', In1)]$.

Here, Inx is the identity matrix of size nx and $A22'$ is the transpose of $A22$. $\text{kron}(X, Y)$ is the Kronecker product between the matrices X and Y .

When $DIF(2)$ is small, small changes in (A, B) can cause large changes in the deflating subspace. An approximate (asymptotic) bound on the maximum angular error in the computed deflating subspaces is $PS * \text{norm}((A, B)) / DIF(2)$,

where EPS is the machine precision.

The reciprocal norm of the projectors on the left and right eigenspaces associated with (A11, B11) may be returned in PL and PR . They are computed as follows. First we compute L and R so that $P*(A, B)*Q$ is block diagonal, where

$$= \begin{pmatrix} (I & -L) & n1 \\ (0 & I) & n2 \\ n1 & n2 \end{pmatrix} \quad Q = \begin{pmatrix} (I & R) & n1 \\ (0 & I) & n2 \\ n1 & n2 \end{pmatrix}$$

and (L, R) is the solution to the generalized Sylvester equation $l1*R - L*A22 = -A12$

Then $PL = (F\text{-norm}(L)**2+1)**(-1/2)$ and $PR = (F\text{-norm}(R)**2+1)**(-1/2)$. An approximate (asymptotic) bound on the average absolute error of the selected eigenvalues is $PS * \text{norm}((A, B)) / PL$.

There are also global error bounds which valid for perturbations up to a certain restriction: A lower bound (x) on the smallest $F\text{-norm}(E,F)$ for which an eigenvalue of (A_{11}, B_{11}) may move and coalesce with an eigenvalue of (A_{22}, B_{22}) under perturbation (E,F) , (i.e. $(A + E, B + F)$), is

$$x = \min(\text{Difu}, \text{Difl}) / ((1/(PL*PL) + 1/(PR*PR))**(1/2) + 2*\max(1/PL, 1/PR)).$$

An approximate bound on x can be computed from $\text{DIF}(1:2)$, PL and PR .

If $y = (F\text{-norm}(E,F) / x) \leq 1$, the angles between the perturbed (L', R') and unperturbed (L, R) left and right deflating subspaces associated with the selected cluster in the $(1,1)$ -blocks can be bounded as

$$\begin{aligned} \max\text{-angle}(L, L') &\leq \arctan(y * PL / (1 - y * (1 - PL * PL)**(1/2))) \\ \max\text{-angle}(R, R') &\leq \arctan(y * PR / (1 - y * (1 - PR * PR)**(1/2))) \end{aligned}$$

See LAPACK User's Guide section 4.11 or the following references for more information.

Note that if the default method for computing the Frobenius-norm-based estimate DIF is not wanted (see SLATDF), then the parameter IDIFJB (see below) should be changed from 3 to 4 (routine SLATDF ($\text{IJOB} = 2$ will be used)). See STGSYL for more details.

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing Science,
Umea University, S-901 87 Umea, Sweden.

References

=====

[1] B. Kagstrom; A Direct Method for Reordering Eigenvalues in the Generalized Real Schur Form of a Regular Matrix Pair (A, B) , in M.S. Moonen et al (eds), Linear Algebra for Large Scale and Real-Time Applications, Kluwer Academic Publ. 1993, pp 195-218.

[2] B. Kagstrom and P. Poromaa; Computing Eigenspaces with Specified Eigenvalues of a Regular Matrix Pair (A, B) and Condition Estimation: Theory, Algorithms and Software, Report UMINF - 94.04, Department of Computing Science, Umea

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1996.

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NAME

stgsja - compute the generalized singular value decomposition (GSVD) of two real upper triangular (or trapezoidal) matrices A and B

SYNOPSIS

```
SUBROUTINE STGSJA(JOBV, JOBQ, M, P, N, K, L, A, LDA, B, LDB,
  TOLA, TOLB, ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, NCYCLE,
  INFO)
```

```
CHARACTER * 1 JOBV, JOBQ
INTEGER M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE, INFO
REAL TOLA, TOLB
REAL A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), U(LDU,*),
V(LDV,*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE STGSJA_64(JOBV, JOBQ, M, P, N, K, L, A, LDA, B, LDB,
  TOLA, TOLB, ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, NCYCLE,
  INFO)
```

```
CHARACTER * 1 JOBV, JOBQ
INTEGER*8 M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE,
INFO
REAL TOLA, TOLB
REAL A(LDA,*), B(LDB,*), ALPHA(*), BETA(*), U(LDU,*),
V(LDV,*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGSJA(JOBV, JOBQ, M, P, N, K, L, A, [LDA], B, [LDB],
  TOLA, TOLB, ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK],
  NCYCLE, [INFO])
```

```
CHARACTER(LEN=1) :: JOBV, JOBQ
INTEGER :: M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE,
INFO
REAL :: TOLA, TOLB
REAL, DIMENSION(:) :: ALPHA, BETA, WORK
REAL, DIMENSION(:, :) :: A, B, U, V, Q
```

```
SUBROUTINE TGSJA_64(JOBV, JOBQ, M, P, N, K, L, A, [LDA], B,
```

```
[LDB], TOLA, TOLB, ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ],
[WORK], NCYCLE, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
INTEGER(8) :: M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCY-
CLE, INFO
REAL :: TOLA, TOLB
REAL, DIMENSION(:) :: ALPHA, BETA, WORK
REAL, DIMENSION(:, :) :: A, B, U, V, Q
```

C INTERFACE

```
#include <sunperf.h>

void stgsja(char jobu, char jobv, char jobq, int m, int p,
            int n, int k, int l, float *a, int lda, float *b,
            int ldb, float tola, float tolb, float *alpha,
            float *beta, float *u, int ldu, float *v, int ldv,
            float *q, int ldq, int *ncycle, int *info);

void stgsja_64(char jobu, char jobv, char jobq, long m, long
               p, long n, long k, long l, float *a, long lda,
               float *b, long ldb, float tola, float tolb, float
               *alpha, float *beta, float *u, long ldu, float *v,
               long ldv, float *q, long ldq, long *ncycle, long
               *info);
```

PURPOSE

stgsja computes the generalized singular value decomposition (GSVD) of two real upper triangular (or trapezoidal) matrices A and B.

On entry, it is assumed that matrices A and B have the following forms, which may be obtained by the preprocessing subroutine SGGSPV from a general M-by-N matrix A and P-by-N matrix B:

$$A = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} & \\ \begin{matrix} K \\ L \\ M-K-L \end{matrix} & \begin{pmatrix} 0 & A12 & A13 \\ 0 & 0 & A23 \\ 0 & 0 & 0 \end{pmatrix} & \text{if } M-K-L \geq 0; \end{array}$$

$$A = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} & \\ \begin{matrix} K \\ M-K \end{matrix} & \begin{pmatrix} 0 & A12 & A13 \\ 0 & 0 & A23 \end{pmatrix} & \text{if } M-K-L < 0; \end{array}$$

$$B = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} & \\ \begin{matrix} L \\ P-L \end{matrix} & \begin{pmatrix} 0 & 0 & B13 \\ 0 & 0 & 0 \end{pmatrix} & \end{array}$$

where the K-by-K matrix A12 and L-by-L matrix B13 are non-singular upper triangular; A23 is L-by-L upper triangular if M-K-L ≥ 0, otherwise A23 is (M-K)-by-L upper trapezoidal.

On exit,

$$U' * A * Q = D1 * (\begin{matrix} 0 & R \end{matrix}), \quad V' * B * Q = D2 * (\begin{matrix} 0 & R \end{matrix}),$$

where U, V and Q are orthogonal matrices, Z' denotes the

transpose of Z, R is a nonsingular upper triangular matrix, and D1 and D2 are ``diagonal'' matrices, which are of the following structures:

If $M-K-L \geq 0$,

$$D1 = \begin{matrix} & & K & L \\ & K & (I & 0) \\ & & L & (0 & C) \\ M-K-L & (0 & 0) \end{matrix}$$

$$D2 = \begin{matrix} & & K & L \\ L & (0 & S) \\ P-L & (0 & 0) \end{matrix}$$

$$\begin{matrix} & & N-K-L & K & L \\ (0 R) & = & K & (0 & R11 & R12) & K \\ & & L & (0 & 0 & R22) & L \end{matrix}$$

where

$$\begin{aligned} C &= \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(K+L)), \\ S &= \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(K+L)), \\ C^{**2} + S^{**2} &= I. \end{aligned}$$

R is stored in $A(1:K+L, N-K-L+1:N)$ on exit.

If $M-K-L < 0$,

$$D1 = \begin{matrix} & & K & M-K & K+L-M \\ & K & (I & 0 & 0) \\ M-K & (0 & C & 0) \end{matrix}$$

$$D2 = \begin{matrix} & & K & M-K & K+L-M \\ M-K & (0 & S & 0) \\ K+L-M & (0 & 0 & I) \\ P-L & (0 & 0 & 0) \end{matrix}$$

$$\begin{matrix} & & N-K-L & K & M-K & K+L-M \\ M-K & (0 & 0 & R22 & R23) \\ K+L-M & (0 & 0 & 0 & R33) \end{matrix}$$

where

$$\begin{aligned} C &= \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(M)), \\ S &= \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(M)), \\ C^{**2} + S^{**2} &= I. \end{aligned}$$

$R = (R11 \ R12 \ R13)$ is stored in $A(1:M, N-K-L+1:N)$ and $R33$ is stored

$(0 \ R22 \ R23)$
in $B(M-K+1:L, N+M-K-L+1:N)$ on exit.

The computation of the orthogonal transformation matrices U, V or Q is optional. These matrices may either be formed explicitly, or they may be postmultiplied into input matrices U1, V1, or Q1.

STGSJA essentially uses a variant of Kogbetliantz algorithm to reduce $\min(L, M-K)$ -by-L triangular (or trapezoidal) matrix A23 and L-by-L matrix B13 to the form:

$U1' * A13 * Q1 = C1 * R1$; $V1' * B13 * Q1 = S1 * R1$,
where U1, V1 and Q1 are orthogonal matrix, and Z' is the

transpose of Z. C1 and S1 are diagonal matrices satisfying
 $C1^{**2} + S1^{**2} = I$,
and R1 is an L-by-L nonsingular upper triangular matrix.

ARGUMENTS

JOBV (input)
= 'U': U must contain an orthogonal matrix U1 on entry, and the product U1*U is returned; = 'I': U is initialized to the unit matrix, and the orthogonal matrix U is returned; = 'N': U is not computed.

JOBV (input)
= 'V': V must contain an orthogonal matrix V1 on entry, and the product V1*V is returned; = 'I': V is initialized to the unit matrix, and the orthogonal matrix V is returned; = 'N': V is not computed.

JOBQ (input)
= 'Q': Q must contain an orthogonal matrix Q1 on entry, and the product Q1*Q is returned; = 'I': Q is initialized to the unit matrix, and the orthogonal matrix Q is returned; = 'N': Q is not computed.

M (input) The number of rows of the matrix A. $M \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

K (input) K and L specify the subblocks in the input matrices A and B:
 $A23 = A(K+1:MIN(K+L,M),N-L+1:N)$ and $B13 = B(1:L,N-L+1:N)$ of A and B, whose GSVD is going to be computed by STGSJA. See Further details.

L (input) See the description of K.

A (input/output)
On entry, the M-by-N matrix A. On exit, $A(N-K+1:N,1:MIN(K+L,M))$ contains the triangular matrix R or part of R. See Purpose for details.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,M)$.

B (input/output)
On entry, the P-by-N matrix B. On exit, if necessary, $B(M-K+1:L,N+M-K-L+1:N)$ contains a part of R. See Purpose for details.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1,P)$.

TOLA (input)

TOLA and TOLB are the convergence criteria for the Jacobi-Kogbetliantz iteration procedure. Generally, they are the same as used in the preprocessing step, say $TOLA = \max(M,N) * \text{norm}(A) * \text{MACHEPS}$, $TOLB = \max(P,N) * \text{norm}(B) * \text{MACHEPS}$.

TOLB (input)

See the description of TOLA.

ALPHA (output)

On exit, ALPHA and BETA contain the generalized singular value pairs of A and B; $ALPHA(1:K) = 1$, $BETA(1:K) = 0$, and if $M-K-L \geq 0$, $ALPHA(K+1:K+L) = \text{diag}(C)$, $BETA(K+1:K+L) = \text{diag}(S)$, or if $M-K-L < 0$, $ALPHA(K+1:M) = C$, $ALPHA(M+1:K+L) = 0$, $BETA(K+1:M) = S$, $BETA(M+1:K+L) = 1$. Furthermore, if $K+L < N$, $ALPHA(K+L+1:N) = 0$ and $BETA(K+L+1:N) = 0$.

BETA (output)

See the description of ALPHA.

U (input) On entry, if $JOBU = 'U'$, U must contain a matrix U_1 (usually the orthogonal matrix returned by SGGSPV). On exit, if $JOBU = 'I'$, U contains the orthogonal matrix U; if $JOBU = 'U'$, U contains the product $U_1 * U$. If $JOBU = 'N'$, U is not referenced.

LDU (input)

The leading dimension of the array U. $LDU \geq \max(1,M)$ if $JOBU = 'U'$; $LDU \geq 1$ otherwise.

V (input) On entry, if $JOBV = 'V'$, V must contain a matrix V_1 (usually the orthogonal matrix returned by SGGSPV). On exit, if $JOBV = 'I'$, V contains the orthogonal matrix V; if $JOBV = 'V'$, V contains the product $V_1 * V$. If $JOBV = 'N'$, V is not referenced.

LDV (input)

The leading dimension of the array V. $LDV \geq \max(1,P)$ if $JOBV = 'V'$; $LDV \geq 1$ otherwise.

Q (input) On entry, if $JOBQ = 'Q'$, Q must contain a matrix Q_1 (usually the orthogonal matrix returned by SGGSPV). On exit, if $JOBQ = 'I'$, Q contains the orthogonal matrix Q; if $JOBQ = 'Q'$, Q contains the product $Q_1 * Q$. If $JOBQ = 'N'$, Q is not referenced.

LDQ (input)

The leading dimension of the array Q. $LDQ \geq \max(1,N)$ if $JOBQ = 'Q'$; $LDQ \geq 1$ otherwise.

WORK (workspace)

dimension(2*N)

NCYCLE (output)

The number of cycles required for convergence.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.
= 1: the procedure does not converge after MAXIT cycles.

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NAME

stgsna - estimate reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B) in generalized real Schur canonical form (or of any matrix pair (Q*A*Z', Q*B*Z') with orthogonal matrices Q and Z, where Z' denotes the transpose of Z

SYNOPSIS

```
SUBROUTINE STGSNA(JOB, HOWMNT, SELECT, N, A, LDA, B, LDB, VL, LDVL,
                 VR, LDVR, S, DIF, MM, M, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOB, HOWMNT
INTEGER N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO
INTEGER IWORK(*)
LOGICAL SELECT(*)
REAL A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*), S(*),
DIF(*), WORK(*)
```

```
SUBROUTINE STGSNA_64(JOB, HOWMNT, SELECT, N, A, LDA, B, LDB, VL,
                   LDVL, VR, LDVR, S, DIF, MM, M, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOB, HOWMNT
INTEGER*8 N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO
INTEGER*8 IWORK(*)
LOGICAL*8 SELECT(*)
REAL A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*), S(*),
DIF(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGSNA(JOB, HOWMNT, SELECT, [N], A, [LDA], B, [LDB], VL,
                [LDVL], VR, [LDVR], S, DIF, MM, M, [WORK], [LWORK], [IWORK],
                [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNT
INTEGER :: N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL, DIMENSION(:) :: SELECT
REAL, DIMENSION(:) :: S, DIF, WORK
```

```
REAL, DIMENSION(:, :) :: A, B, VL, VR
```

```
SUBROUTINE TGSNA_64(JOB, HOWMNT, SELECT, [N], A, [LDA], B, [LDB], VL,  
    [LDVL], VR, [LDVR], S, DIF, MM, M, [WORK], [LWORK], [IWORK],  
    [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNT  
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO  
INTEGER(8), DIMENSION(:) :: IWORK  
LOGICAL(8), DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: S, DIF, WORK  
REAL, DIMENSION(:, :) :: A, B, VL, VR
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stgsna(char job, char howmnt, int *select, int n, float  
    *a, int lda, float *b, int ldb, float *vl, int  
    ldvl, float *vr, int ldvr, float *s, float *dif,  
    int mm, int *m, int *info);
```

```
void stgsna_64(char job, char howmnt, long *select, long n,  
    float *a, long lda, float *b, long ldb, float *vl,  
    long ldvl, float *vr, long ldvr, float *s, float  
    *dif, long mm, long *m, long *info);
```

PURPOSE

stgsna estimates reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B) in generalized real Schur canonical form (or of any matrix pair (Q*A*Z', Q*B*Z') with orthogonal matrices Q and Z, where Z' denotes the transpose of Z.

(A, B) must be in generalized real Schur form (as returned by SGGES), i.e. A is block upper triangular with 1-by-1 and 2-by-2 diagonal blocks. B is upper triangular.

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for eigenvalues (S) or eigenvectors (DIF):
= 'E': for eigenvalues only (S);
= 'V': for eigenvectors only (DIF);
= 'B': for both eigenvalues and eigenvectors (S and DIF).

HOWMNT (input)

= 'A': compute condition numbers for all eigenpairs;
= 'S': compute condition numbers for selected eigenpairs specified by the array SELECT.

SELECT (input)

If HOWMNT = 'S', SELECT specifies the eigenpairs

for which condition numbers are required. To select condition numbers for the eigenpair corresponding to a real eigenvalue $w(j)$, `SELECT(j)` must be set to `.TRUE.`. To select condition numbers corresponding to a complex conjugate pair of eigenvalues $w(j)$ and $w(j+1)$, either `SELECT(j)` or `SELECT(j+1)` or both, must be set to `.TRUE.`. If `HOWMNT = 'A'`, `SELECT` is not referenced.

`N` (input) The order of the square matrix pair (A, B). `N` \geq 0.

`A` (input) The upper quasi-triangular matrix A in the pair (A,B).

`LDA` (input)
The leading dimension of the array A. `LDA` \geq `max(1,N)`.

`B` (input) The upper triangular matrix B in the pair (A,B).

`LDB` (input)
The leading dimension of the array B. `LDB` \geq `max(1,N)`.

`VL` (input)
If `JOB = 'E'` or `'B'`, `VL` must contain left eigenvectors of (A, B), corresponding to the eigenpairs specified by `HOWMNT` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VL`, as returned by `STGEVC`. If `JOB = 'V'`, `VL` is not referenced.

`LDVL` (input)
The leading dimension of the array `VL`. `LDVL` \geq 1.
If `JOB = 'E'` or `'B'`, `LDVL` \geq `N`.

`VR` (input)
If `JOB = 'E'` or `'B'`, `VR` must contain right eigenvectors of (A, B), corresponding to the eigenpairs specified by `HOWMNT` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VR`, as returned by `STGEVC`. If `JOB = 'V'`, `VR` is not referenced.

`LDVR` (input)
The leading dimension of the array `VR`. `LDVR` \geq 1.
If `JOB = 'E'` or `'B'`, `LDVR` \geq `N`.

`S` (output)
If `JOB = 'E'` or `'B'`, the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. For a complex conjugate pair of eigenvalues two consecutive elements of `S` are set to the same value. Thus `S(j)`, `DIF(j)`, and the `j`-th columns of `VL` and `VR` all correspond to the same eigenpair (but not in general the `j`-th eigenpair, unless all eigenpairs are selected). If `JOB = 'V'`, `S` is not referenced.

`DIF` (output)
If `JOB = 'V'` or `'B'`, the estimated reciprocal con-

dition numbers of the selected eigenvectors, stored in consecutive elements of the array. For a complex eigenvector two consecutive elements of DIF are set to the same value. If the eigenvalues cannot be reordered to compute DIF(j), DIF(j) is set to 0; this can only occur when the true value would be very small anyway. If JOB = 'E', DIF is not referenced.

MM (input)

The number of elements in the arrays S and DIF. MM >= M.

M (output)

The number of elements of the arrays S and DIF used to store the specified condition numbers; for each selected real eigenvalue one element is used, and for each selected complex conjugate pair of eigenvalues, two elements are used. If HOWMNT = 'A', M is set to N.

WORK (workspace)

If JOB = 'E', WORK is not referenced. Otherwise, on exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK >= N. If JOB = 'V' or 'B' LWORK >= 2*N*(N+2)+16. If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)

dimension(N+6) If JOB = 'E', IWORK is not referenced.

INFO (output)

=0: Successful exit
<0: If INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The reciprocal of the condition number of a generalized eigenvalue $w = (a, b)$ is defined as

$$(w) = (|u'Av|^{**2} + |u'Bv|^{**2})^{**1/2} / (norm(u)*norm(v))$$

where u and v are the left and right eigenvectors of (A, B) corresponding to w; |z| denotes the absolute value of the complex number, and norm(u) denotes the 2-norm of the vector u.

The pair (a, b) corresponds to an eigenvalue $w = a/b$ (= $u'Av/u'Bv$) of the matrix pair (A, B). If both a and b equal zero, then (A B) is singular and S(I) = -1 is returned.

An approximate error bound on the chordal distance between the i-th computed generalized eigenvalue w and the

)

where the generalized eigenvalues $w = s_{11}/t_{11}$ and $\text{conjg}(w) = s_{22}/t_{22}$.

Then the reciprocal condition number $\text{DIF}(i)$ is bounded by

$$\min(d_1, \max(1, |\text{real}(s_{11})/\text{real}(s_{22})|) * d_2)$$

where, $d_1 = \text{Difl}((s_{11}, t_{11}), (s_{22}, t_{22})) = \text{sigma-min}(Z_1)$,
where

Z_1 is the complex 2-by-2 matrix

$$Z_1 = \begin{bmatrix} s_{11} & -s_{22} \\ t_{11} & -t_{22} \end{bmatrix},$$

This is done by computing (using real arithmetic) the roots of the characteristic polynomial $\det(Z_1' * Z_1 - \lambda I)$,

where Z_1' denotes the conjugate transpose of Z_1 and $\det(X)$ denotes

the determinant of X .

and d_2 is an upper bound on $\text{Difl}((S_{11}, T_{11}), (S_{22}, T_{22}))$,
i.e. an

upper bound on $\text{sigma-min}(Z_2)$, where Z_2 is $(2n-2)$ -by- $(2n-2)$

$$Z_2 = \begin{bmatrix} \text{kron}(S_{11}', I_{n-2}) & -\text{kron}(I_2, S_{22}) \\ \text{kron}(T_{11}', I_{n-2}) & -\text{kron}(I_2, T_{22}) \end{bmatrix}$$

Note that if the default method for computing DIF is wanted (see

SLATDF), then the parameter DIFDRI (see below) should be changed

from 3 to 4 (routine $\text{SLATDF}(\text{IJOB} = 2)$ will be used). See STGSYL

for more details.

For each eigenvalue/vector specified by SELECT , DIF stores a Frobenius norm-based estimate of Difl .

An approximate error bound for the i -th computed eigenvector $\text{VL}(i)$ or $\text{VR}(i)$ is given by

$$\text{EPS} * \text{norm}(A, B) / \text{DIF}(i).$$

See ref. [2-3] for more details and further references.

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing Science,

Umea University, S-901 87 Umea, Sweden.

References

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[1] B. Kagstrom; A Direct Method for Reordering Eigenvalues in the

Generalized Real Schur Form of a Regular Matrix Pair (A, B) , in

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[2] B. Kagstrom and P. Poromaa; Computing Eigenspaces with Specified Eigenvalues of a Regular Matrix Pair (A, B) and Condition Estimation: Theory, Algorithms and Software, Report UMINF - 94.04, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, 1994. Also as LAPACK Working Note 87. To appear in Numerical Algorithms, 1996.

[3] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK Working Note 75. To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

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NAME

stgsyl - solve the generalized Sylvester equation

SYNOPSIS

```
SUBROUTINE STGSYL(TRANS, IJOB, M, N, A, LDA, B, LDB, C, LDC, D, LDD,  
E, LDE, F, LDF, SCALE, DIF, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 TRANS  
INTEGER IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,  
INFO  
INTEGER IWORK(*)  
REAL SCALE, DIF  
REAL A(LDA,*), B(LDB,*), C(LDC,*), D(LDD,*), E(LDE,*),  
F(LDF,*), WORK(*)
```

```
SUBROUTINE STGSYL_64(TRANS, IJOB, M, N, A, LDA, B, LDB, C, LDC, D,  
LDD, E, LDE, F, LDF, SCALE, DIF, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 TRANS  
INTEGER*8 IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,  
INFO  
INTEGER*8 IWORK(*)  
REAL SCALE, DIF  
REAL A(LDA,*), B(LDB,*), C(LDC,*), D(LDD,*), E(LDE,*),  
F(LDF,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGSYL(TRANS, IJOB, [M], [N], A, [LDA], B, [LDB], C, [LDC],  
D, [LDD], E, [LDE], F, [LDF], SCALE, DIF, [WORK], [LWORK], [IWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANS  
INTEGER :: IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,  
INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL :: SCALE, DIF  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:, :) :: A, B, C, D, E, F
```

```

SUBROUTINE STGSYL_64(TRANS, IJOB, [M], [N], A, [LDA], B, [LDB], C,
    [LDC], D, [LDD], E, [LDE], F, [LDF], SCALE, DIF, [WORK], [LWORK],
    [IWORK], [INFO])

```

```

CHARACTER(LEN=1) :: TRANS
INTEGER(8) :: IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF,
LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL :: SCALE, DIF
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:, :) :: A, B, C, D, E, F

```

C INTERFACE

```

#include <sunperf.h>

void stgsyl(char trans, int ijob, int m, int n, float *a,
    int lda, float *b, int ldb, float *c, int ldc,
    float *d, int ldd, float *e, int lde, float *f,
    int ldf, float *scale, float *dif, int *info);

void stgsyl_64(char trans, long ijob, long m, long n, float
    *a, long lda, float *b, long ldb, float *c, long
    ldc, float *d, long ldd, float *e, long lde, float
    *f, long ldf, float *scale, float *dif, long
    *info);

```

PURPOSE

stgsyl solves the generalized Sylvester equation:

$$\begin{aligned}
 A * R - L * B &= \text{scale} * C & (1) \\
 D * R - L * E &= \text{scale} * F
 \end{aligned}$$

where R and L are unknown m-by-n matrices, (A, D), (B, E) and (C, F) are given matrix pairs of size m-by-m, n-by-n and m-by-n, respectively, with real entries. (A, D) and (B, E) must be in generalized (real) Schur canonical form, i.e. A, B are upper quasi triangular and D, E are upper triangular.

The solution (R, L) overwrites (C, F). 0 <= SCALE <= 1 is an output scaling factor chosen to avoid overflow.

In matrix notation (1) is equivalent to solve $Zx = \text{scale} * b$, where Z is defined as

$$Z = \begin{bmatrix} \text{kron}(I_n, A) & -\text{kron}(B', I_m) \\ \text{kron}(I_n, D) & -\text{kron}(E', I_m) \end{bmatrix} \quad (2)$$

Here I_k is the identity matrix of size k and X' is the transpose of X. $\text{kron}(X, Y)$ is the Kronecker product between the matrices X and Y.

If TRANS = 'T', STGSYL solves the transposed system $Z' * y = \text{scale} * b$, which is equivalent to solve for R and L in

$$\begin{aligned}
 A' * R + D' * L &= \text{scale} * C & (3) \\
 R * B' + L * E' &= \text{scale} * (-F)
 \end{aligned}$$

This case (TRANS = 'T') is used to compute an one-norm-based estimate of $\text{Dif}[(A,D), (B,E)]$, the separation between the matrix pairs (A,D) and (B,E), using SLACON.

If IJOB \geq 1, STGSYL computes a Frobenius norm-based estimate of $\text{Dif}[(A,D), (B,E)]$. That is, the reciprocal of a lower bound on the reciprocal of the smallest singular value of Z. See [1-2] for more information.

This is a level 3 BLAS algorithm.

ARGUMENTS

TRANS (input)

= 'N', solve the generalized Sylvester equation (1). = 'T', solve the 'transposed' system (3).

IJOB (input)

Specifies what kind of functionality to be performed. =0: solve (1) only.
=1: The functionality of 0 and 3.
=2: The functionality of 0 and 4.
=3: Only an estimate of $\text{Dif}[(A,D), (B,E)]$ is computed. (look ahead strategy IJOB = 1 is used).
=4: Only an estimate of $\text{Dif}[(A,D), (B,E)]$ is computed. (SGECON on sub-systems is used). Not referenced if TRANS = 'T'.

M (input) The order of the matrices A and D, and the row dimension of the matrices C, F, R and L.

N (input) The order of the matrices B and E, and the column dimension of the matrices C, F, R and L.

A (input) The upper quasi triangular matrix A.

LDA (input)

The leading dimension of the array A. LDA \geq max(1, M).

B (input) The upper quasi triangular matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1, N).

C (input/output)

On entry, C contains the right-hand-side of the first matrix equation in (1) or (3). On exit, if IJOB = 0, 1 or 2, C has been overwritten by the solution R. If IJOB = 3 or 4 and TRANS = 'N', C holds R, the solution achieved during the computation of the Dif-estimate.

LDC (input)

The leading dimension of the array C. LDC \geq max(1, M).

D (input) The upper triangular matrix D.

LDD (input)
 The leading dimension of the array D. LDD \geq max(1, M).

E (input) The upper triangular matrix E.

LDE (input)
 The leading dimension of the array E. LDE \geq max(1, N).

F (input/output)
 On entry, F contains the right-hand-side of the second matrix equation in (1) or (3). On exit, if IJOB = 0, 1 or 2, F has been overwritten by the solution L. If IJOB = 3 or 4 and TRANS = 'N', F holds L, the solution achieved during the computation of the Dif-estimate.

LDF (input)
 The leading dimension of the array F. LDF \geq max(1, M).

DIF (output)
 On exit SCALE is the reciprocal of a lower bound of the reciprocal of the Dif-function, i.e. SCALE is an upper bound of $\text{Dif}[(A,D), (B,E)] = \sigma_{\min}(Z)$, where Z as in (2). If IJOB = 0 or TRANS = 'T', SCALE is not touched.

SCALE (output)
 On exit SCALE is the reciprocal of a lower bound of the reciprocal of the Dif-function, i.e. SCALE is an upper bound of $\text{Dif}[(A,D), (B,E)] = \sigma_{\min}(Z)$, where Z as in (2). If IJOB = 0 or TRANS = 'T', SCALE is not touched.

WORK (workspace)
 If IJOB = 0, WORK is not referenced. Otherwise, on exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq 1. If IJOB = 1 or 2 and TRANS = 'N', LWORK \geq 2*M*N.

 If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)
 dimension(M+N+2)

INFO (output)
 =0: successful exit
 <0: If INFO = -i, the i-th argument had an illegal value.
 >0: (A, D) and (B, E) have common or close eigenvalues.

FURTHER DETAILS

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing Science,
Umea University, S-901 87 Umea, Sweden.

[1] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK Working Note 75. To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

[2] B. Kagstrom, A Perturbation Analysis of the Generalized Sylvester Equation $(AR - LB, DR - LE) = (C, F)$, SIAM J. Matrix Anal. Appl., 15(4):1045-1060, 1994

[3] B. Kagstrom and L. Westin, Generalized Schur Methods with Condition Estimators for Solving the Generalized Sylvester Equation, IEEE Transactions on Automatic Control, Vol. 34, No. 7, July 1989, pp 745-751.

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NAME

stpcon - estimate the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE STPCON(NORM, UPLO, DIAG, N, A, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER N, INFO  
INTEGER WORK2(*)  
REAL RCOND  
REAL A(*), WORK(*)
```

```
SUBROUTINE STPCON_64(NORM, UPLO, DIAG, N, A, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER*8 N, INFO  
INTEGER*8 WORK2(*)  
REAL RCOND  
REAL A(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TPCON(NORM, UPLO, DIAG, [N], A, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL :: RCOND  
REAL, DIMENSION(:) :: A, WORK
```

```
SUBROUTINE TPCON_64(NORM, UPLO, DIAG, [N], A, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: WORK2  
REAL :: RCOND
```

```
REAL, DIMENSION(:) :: A, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stpcon(char norm, char uplo, char diag, int n, float  
*a, float *rcond, int *info);
```

```
void stpcon_64(char norm, char uplo, char diag, long n,  
float *a, float *rcond, long *info);
```

PURPOSE

stpcon estimates the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input) REAL array, dimension $(N*(N+1)/2)$

The upper or lower triangular matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

REAL array, dimension $(3*N)$

WORK2 (workspace)

INTEGER array, dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

stpmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

SYNOPSIS

```
SUBROUTINE STPMV(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, INCY  
REAL A(*), Y(*)
```

```
SUBROUTINE STPMV_64(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, INCY  
REAL A(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TPMV(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, INCY  
REAL, DIMENSION(:) :: A, Y
```

```
SUBROUTINE TPMV_64(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, INCY  
REAL, DIMENSION(:) :: A, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stpmv(char uplo, char transa, char diag, int n, float  
          *a, float *y, int incy);
```

```
void stpmv_64(char uplo, char transa, char diag, long n,  
             float *a, float *y, long incy);
```

PURPOSE

stpmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := A'*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

(($n*(n+1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular matrix packed sequentially, column by column, so that $A(1)$ contains $a(1,1)$, $A(2)$ and $A(3)$ contain $a(1,2)$ and $a(2,2)$ respec-

tively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced, but are assumed to be unity. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

stprfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix

SYNOPSIS

```
SUBROUTINE STPRFS(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, NRHS, LDB, LDX, INFO  
INTEGER WORK2(*)  
REAL A(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE STPRFS_64(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
REAL A(*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TPRFS(UPLO, [TRANSA], DIAG, [N], NRHS, A, B, [LDB], X, [LDX],  
    FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, NRHS, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL, DIMENSION(:) :: A, FERR, BERR, WORK  
REAL, DIMENSION(:,) :: B, X
```

```
SUBROUTINE TPRFS_64(UPLO, [TRANSA], DIAG, [N], NRHS, A, B, [LDB], X,  
    [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2  
REAL, DIMENSION(:) :: A, FERR, BERR, WORK  
REAL, DIMENSION(:,) :: B, X
```

C INTERFACE

```
#include <sunperf.h>

void stprfs(char uplo, char transa, char diag, int n, int
  nrhs, float *a, float *b, int ldb, float *x, int
  ldx, float *ferr, float *berr, int *info);
void stprfs_64(char uplo, char transa, char diag, long n,
  long nrhs, float *a, float *b, long ldb, float *x,
  long ldx, float *ferr, float *berr, long *info);
```

PURPOSE

stprfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix.

The solution matrix X must be computed by STPTRS or some other means before entering this routine. STPRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': A * X = B (No transpose)
= 'T': A**T * X = B (Transpose)
= 'C': A**H * X = B (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input) REAL array, dimension (N*(N+1)/2)

The upper or lower triangular matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

B (input) REAL array, dimension (LDB,NRHS)
The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

X (input) REAL array, dimension (LDX,NRHS)
The solution matrix X.

LDX (input)
The leading dimension of the array X. LDX >= max(1,N).

FERR (output) REAL array, dimension (NRHS)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) REAL array, dimension (NRHS)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
REAL array, dimension(3*N)

WORK2 (workspace)
INTEGER array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

stpsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

SYNOPSIS

```
SUBROUTINE STPSV(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, INCY  
REAL A(*), Y(*)
```

```
SUBROUTINE STPSV_64(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, INCY  
REAL A(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TPSV(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, INCY  
REAL, DIMENSION(:) :: A, Y
```

```
SUBROUTINE TPSV_64(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, INCY  
REAL, DIMENSION(:) :: A, Y
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stpsv(char uplo, char transa, char diag, int n, float  
          *a, float *y, int incy);
```

```
void stpsv_64(char uplo, char transa, char diag, long n,  
             float *a, float *y, long incy);
```

PURPOSE

stpsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular matrix, supplied in packed form.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANS (input)

On entry, TRANS specifies the equations to be solved as follows:

TRANS = 'N' or 'n' $A*x = b$.

TRANS = 'T' or 't' $A'*x = b$.

TRANS = 'C' or 'c' $A'*x = b$.

Unchanged on exit.

TRANS is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

(($n*(n+1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper

triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(1, 2) and a(2, 2) respectively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced, but are assumed to be unity. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

stptri - compute the inverse of a real upper or lower triangular matrix A stored in packed format

SYNOPSIS

```
SUBROUTINE STPTRI(UPLO, DIAG, N, A, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER N, INFO  
REAL A(*)
```

```
SUBROUTINE STPTRI_64(UPLO, DIAG, N, A, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER*8 N, INFO  
REAL A(*)
```

F95 INTERFACE

```
SUBROUTINE TPTRI(UPLO, DIAG, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER :: N, INFO  
REAL, DIMENSION(:) :: A
```

```
SUBROUTINE TPTRI_64(UPLO, DIAG, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER(8) :: N, INFO  
REAL, DIMENSION(:) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stptri(char uplo, char diag, int n, float *a, int  
            *info);
```

```
void stptri_64(char uplo, char diag, long n, float *a, long  
              *info);
```

PURPOSE

stptri computes the inverse of a real upper or lower triangular matrix A stored in packed format.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) REAL array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangular matrix A, stored columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*((2*n-j)/2)) = A(i,j)$ for $j \leq i \leq n$. See below for further details. On exit, the (triangular) inverse of the original matrix, in the same packed storage format.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, $A(i,i)$ is exactly zero. The triangular matrix is singular and its inverse can not be computed.

FURTHER DETAILS

A triangular matrix A can be transferred to packed storage using one of the following program segments:

UPLO = 'U':

```
      JC = 1
      DO 2 J = 1, N
        DO 1 I = 1, J
          A(JC+I-1) = A(I,J)
1      CONTINUE
      JC = JC + J
1
2 CONTINUE
```

UPLO = 'L':

```
      JC = 1
      DO 2 J = 1, N
        DO 1 I = J, N
          A(JC+I-J) =
1      CONTINUE
      JC = JC + N - J +
2 CONTINUE
```

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NAME

stptrs - solve a triangular system of the form $A * X = B$
or $A^{**T} * X = B$,

SYNOPSIS

```
SUBROUTINE STPTRS(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, NRHS, LDB, INFO  
REAL A(*), B(LDB,*)
```

```
SUBROUTINE STPTRS_64(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, NRHS, LDB, INFO  
REAL A(*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TPTRS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: A  
REAL, DIMENSION(:,) :: B
```

```
SUBROUTINE TPTRS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL, DIMENSION(:) :: A  
REAL, DIMENSION(:,) :: B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stptrs(char uplo, char transa, char diag, int n, int  
nrhs, float *a, float *b, int ldb, int *info);
```

```
void stptrs_64(char uplo, char transa, char diag, long n,  
long nrhs, float *a, float *b, long ldb, long
```

```
*info);
```

PURPOSE

stptrs solves a triangular system of the form

$$A * X = B \text{ or } A^{**T} * X = B$$

where A is a triangular matrix of order N stored in packed format, and B is an N-by-NRHS matrix. A check is made to verify that A is nonsingular.

ARGUMENTS

UPLO (input)

```
= 'U': A is upper triangular;  
= 'L': A is lower triangular.
```

TRANS (input)

```
Specifies the form of the system of equations:  
= 'N': A * X = B (No transpose)  
= 'T': A**T * X = B (Transpose)  
= 'C': A**H * X = B (Conjugate transpose = Transpose)
```

DIAG (input)

```
= 'N': A is non-unit triangular;  
= 'U': A is unit triangular.
```

N (input) The order of the matrix A. N >= 0.

NRHS (input)

```
The number of right hand sides, i.e., the number  
of columns of the matrix B. NRHS >= 0.
```

A (input) REAL array, dimension (N*(N+1)/2)

```
The upper or lower triangular matrix A, packed  
columnwise in a linear array. The j-th column of  
A is stored in the array A as follows: if UPLO =  
'U', A(i + (j-1)*j/2) = A(i,j) for 1<=i<=j; if  
UPLO = 'L', A(i + (j-1)*(2*n-j)/2) = A(i,j) for  
j<=i<=n.
```

B (input/output) REAL array,

```
On entry, the right hand side matrix B. On exit,  
if INFO = 0, the solution matrix X.
```

LDB (input)

```
The leading dimension of the array B. LDB >=  
max(1,N).
```

INFO (output)

```
= 0: successful exit  
< 0: if INFO = -i, the i-th argument had an illegal value  
> 0: if INFO = i, the i-th diagonal element of A  
is zero, indicating that the matrix is singular  
and the solutions X have not been computed.
```


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NAME

strans - transpose and scale source matrix

SYNOPSIS

```
SUBROUTINE STRANS(PLACE, SCALE, SOURCE, M, N, DEST)
```

```
CHARACTER * 1 PLACE  
INTEGER M, N  
REAL SCALE  
REAL SOURCE(*), DEST(*)
```

```
SUBROUTINE STRANS_64(PLACE, SCALE, SOURCE, M, N, DEST)
```

```
CHARACTER * 1 PLACE  
INTEGER*8 M, N  
REAL SCALE  
REAL SOURCE(*), DEST(*)
```

F95 INTERFACE

```
SUBROUTINE TRANS([PLACE], SCALE, SOURCE, M, N, [DEST])
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER :: M, N  
REAL :: SCALE  
REAL, DIMENSION(:) :: SOURCE, DEST
```

```
SUBROUTINE TRANS_64([PLACE], SCALE, SOURCE, M, N, [DEST])
```

```
CHARACTER(LEN=1) :: PLACE  
INTEGER(8) :: M, N  
REAL :: SCALE  
REAL, DIMENSION(:) :: SOURCE, DEST
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strans(char place, float scale, float *source, int m,  
            int n, float *dest);
```

```
void strans_64(char place, float scale, float *source, long
```

```
m, long n, float *dest);
```

PURPOSE

strans scales and transposes the source matrix. The $N_2 \times N_1$ result is written into SOURCE when PLACE = 'I' or 'i', and DEST when PLACE = 'O' or 'o'.

```
PLACE = 'I' or 'i': SOURCE = SCALE * SOURCE'
```

```
PLACE = 'O' or 'o': DEST = SCALE * SOURCE'
```

ARGUMENTS

PLACE (input)

Type of transpose. 'I' or 'i' for in-place, 'O' or 'o' for out-of-place. 'I' is default.

SCALE (input)

Scale factor on the SOURCE matrix.

SOURCE (input/output)

(M, N) on input. Array of (N, M) on output if in-place transpose.

M (input)

Number of rows in the SOURCE matrix on input.

N (input)

Number of columns in the SOURCE matrix on input.

DEST (output)

Scaled and transposed SOURCE matrix if out-of-place transpose. Not referenced if in-place transpose.

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NAME

strcon - estimate the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE STRCON(NORM, UPLO, DIAG, N, A, LDA, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER N, LDA, INFO  
INTEGER WORK2(*)  
REAL RCOND  
REAL A(LDA,*), WORK(*)
```

```
SUBROUTINE STRCON_64(NORM, UPLO, DIAG, N, A, LDA, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
INTEGER*8 N, LDA, INFO  
INTEGER*8 WORK2(*)  
REAL RCOND  
REAL A(LDA,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TRCON(NORM, UPLO, DIAG, [N], A, [LDA], RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL :: RCOND  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE TRCON_64(NORM, UPLO, DIAG, [N], A, [LDA], RCOND, [WORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
INTEGER(8) :: N, LDA, INFO
```

```
INTEGER(8), DIMENSION(:) :: WORK2
REAL :: RCOND
REAL, DIMENSION(:) :: WORK
REAL, DIMENSION(:,:) :: A
```

C INTERFACE

```
#include <sunperf.h>
void strcon(char norm, char uplo, char diag, int n, float
            *a, int lda, float *rcond, int *info);

void strcon_64(char norm, char uplo, char diag, long n,
              float *a, long lda, float *rcond, long *info);
```

PURPOSE

strcon estimates the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))) .$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

RCOND (output)

The reciprocal of the condition number of the matrix A , computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

strevc - compute some or all of the right and/or left eigenvectors of a real upper quasi-triangular matrix T

SYNOPSIS

```
SUBROUTINE STREVC(SIDE, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,  
                LDVR, MM, M, WORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
INTEGER N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL SELECT(*)  
REAL T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

```
SUBROUTINE STREVC_64(SIDE, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,  
                   LDVR, MM, M, WORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY  
INTEGER*8 N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL*8 SELECT(*)  
REAL T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TREVC(SIDE, HOWMNY, SELECT, N, T, [LDT], VL, [LDVL], VR,  
                [LDVR], MM, M, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
INTEGER :: N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL, DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,) :: T, VL, VR
```

```
SUBROUTINE TREVC_64(SIDE, HOWMNY, SELECT, N, T, [LDT], VL, [LDVL],  
                   VR, [LDVR], MM, M, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY  
INTEGER(8) :: N, LDT, LDVL, LDVR, MM, M, INFO  
LOGICAL(8), DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: WORK
```

REAL, DIMENSION(:,:) :: T, VL, VR

C INTERFACE

```
#include <sunperf.h>
```

```
void strevc(char side, char howmny, int *select, int n,
            float *t, int ldt, float *vl, int ldvl, float *vr,
            int ldvr, int mm, int *m, int *info);
void strevc_64(char side, char howmny, long *select, long n,
              float *t, long ldt, float *vl, long ldvl, float
              *vr, long ldvr, long mm, long *m, long *info);
```

PURPOSE

strevc computes some or all of the right and/or left eigenvectors of a real upper quasi-triangular matrix T.

The right eigenvector x and the left eigenvector y of T corresponding to an eigenvalue w are defined by:

$$T*x = w*x, \quad y'*T = w*y'$$

where y' denotes the conjugate transpose of the vector y.

If all eigenvectors are requested, the routine may either return the matrices X and/or Y of right or left eigenvectors of T, or the products Q*X and/or Q*Y, where Q is an input orthogonal matrix. If T was obtained from the real-Schur factorization of an original matrix $A = Q*T*Q'$, then Q*X and Q*Y are the matrices of right or left eigenvectors of A.

T must be in Schur canonical form (as returned by SHSEQR), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign. Corresponding to each 2-by-2 diagonal block is a complex conjugate pair of eigenvalues and eigenvectors; only one eigenvector of the pair is computed, namely the one corresponding to the eigenvalue with positive imaginary part.

ARGUMENTS

SIDE (input)

- = 'R': compute right eigenvectors only;
- = 'L': compute left eigenvectors only;
- = 'B': compute both right and left eigenvectors.

HOWMNY (input)

- = 'A': compute all right and/or left eigenvectors;
- = 'B': compute all right and/or left eigenvectors, and backtransform them using the input matrices supplied in VR and/or VL;
- = 'S': compute selected right and/or left eigenvectors, specified

by the logical array SELECT.

SELECT (input/output)

If HOWMNY = 'S', SELECT specifies the eigenvectors to be computed. If HOWMNY = 'A' or 'B', SELECT is not referenced. To select the real eigenvector corresponding to a real eigenvalue $w(j)$, SELECT(j) must be set to .TRUE.. To select the complex eigenvector corresponding to a complex conjugate pair $w(j)$ and $w(j+1)$, either SELECT(j) or SELECT(j+1) must be set to .TRUE.; then on exit SELECT(j) is .TRUE. and SELECT(j+1) is .FALSE..

N (input) The order of the matrix T. $N \geq 0$.

T (input/output)

The upper quasi-triangular matrix T in Schur canonical form.

LDT (input)

The leading dimension of the array T. $LDT \geq \max(1, N)$.

VL (input/output)

On entry, if SIDE = 'L' or 'B' and HOWMNY = 'B', VL must contain an N-by-N matrix Q (usually the orthogonal matrix Q of Schur vectors returned by SHSEQR). On exit, if SIDE = 'L' or 'B', VL contains: if HOWMNY = 'A', the matrix Y of left eigenvectors of T; VL has the same quasi-lower triangular form as T. If $T(i, i)$ is a real eigenvalue, then the i-th column VL(i) of VL is its corresponding eigenvector. If $T(i:i+1, i:i+1)$ is a 2-by-2 block whose eigenvalues are complex-conjugate eigenvalues of T, then $VL(i) + \sqrt{-1} * VL(i+1)$ is the complex eigenvector corresponding to the eigenvalue with positive real part. if HOWMNY = 'B', the matrix $Q * Y$; if HOWMNY = 'S', the left eigenvectors of T specified by SELECT, stored consecutively in the columns of VL, in the same order as their eigenvalues. A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the real part, and the second the imaginary part. If SIDE = 'R', VL is not referenced.

LDVL (input)

The leading dimension of the array VL. $LDVL \geq \max(1, N)$ if SIDE = 'L' or 'B'; $LDVL \geq 1$ otherwise.

VR (input/output)

On entry, if SIDE = 'R' or 'B' and HOWMNY = 'B', VR must contain an N-by-N matrix Q (usually the orthogonal matrix Q of Schur vectors returned by SHSEQR). On exit, if SIDE = 'R' or 'B', VR contains: if HOWMNY = 'A', the matrix X of right eigenvectors of T; VR has the same quasi-upper triangular form as T. If $T(i, i)$ is a real eigenvalue, then the i-th column VR(i) of VR is its corresponding eigenvector. If $T(i:i+1, i:i+1)$ is a 2-by-2 block whose eigenvalues are complex-

conjugate eigenvalues of T, then $VR(i)+\sqrt{-1}*VR(i+1)$ is the complex eigenvector corresponding to the eigenvalue with positive real part. if HOWMNY = 'B', the matrix Q*X; if HOWMNY = 'S', the right eigenvectors of T specified by SELECT, stored consecutively in the columns of VR, in the same order as their eigenvalues. A complex eigenvector corresponding to a complex eigenvalue is stored in two consecutive columns, the first holding the real part and the second the imaginary part. If SIDE = 'L', VR is not referenced.

LDVR (input)

The leading dimension of the array VR. LDVR \geq max(1,N) if SIDE = 'R' or 'B'; LDVR \geq 1 otherwise.

MM (input)

The number of columns in the arrays VL and/or VR. MM \geq M.

M (output)

The number of columns in the arrays VL and/or VR actually used to store the eigenvectors. If HOWMNY = 'A' or 'B', M is set to N. Each selected real eigenvector occupies one column and each selected complex eigenvector occupies two columns.

WORK (workspace)

dimension(3*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The algorithm used in this program is basically backward (forward) substitution, with scaling to make the code robust against possible overflow.

Each eigenvector is normalized so that the element of largest magnitude has magnitude 1; here the magnitude of a complex number (x,y) is taken to be $|x| + |y|$.

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NAME

strex - reorder the real Schur factorization of a real matrix $A = Q^*TQ^{**T}$, so that the diagonal block of T with row index IFST is moved to row ILST

SYNOPSIS

```
SUBROUTINE STREXC(COMPQ, N, T, LDT, Q, LDQ, IFST, ILST, WORK, INFO)
```

```
CHARACTER * 1 COMPQ  
INTEGER N, LDT, LDQ, IFST, ILST, INFO  
REAL T(LDT,*), Q(LDQ,*), WORK(*)
```

```
SUBROUTINE STREXC_64(COMPQ, N, T, LDT, Q, LDQ, IFST, ILST, WORK,  
INFO)
```

```
CHARACTER * 1 COMPQ  
INTEGER*8 N, LDT, LDQ, IFST, ILST, INFO  
REAL T(LDT,*), Q(LDQ,*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TREXC(COMPQ, N, T, [LDT], Q, [LDQ], IFST, ILST, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: COMPQ  
INTEGER :: N, LDT, LDQ, IFST, ILST, INFO  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,:) :: T, Q
```

```
SUBROUTINE TREXC_64(COMPQ, N, T, [LDT], Q, [LDQ], IFST, ILST, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: COMPQ  
INTEGER(8) :: N, LDT, LDQ, IFST, ILST, INFO  
REAL, DIMENSION(:) :: WORK  
REAL, DIMENSION(:,:) :: T, Q
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strexc(char compq, int n, float *t, int ldt, float *q,
```

```

        int ldq, int *ifst, int *ilst, int *info);

void strexc_64(char compq, long n, float *t, long ldt, float
        *q, long ldq, long *ifst, long *ilst, long *info);

```

PURPOSE

strexc reorders the real Schur factorization of a real matrix $A = Q^*T^*Q^{**}T$, so that the diagonal block of T with row index IFST is moved to row ILST.

The real Schur form T is reordered by an orthogonal similarity transformation $Z^{**}T^*T^*Z$, and optionally the matrix Q of Schur vectors is updated by postmultiplying it with Z .

T must be in Schur canonical form (as returned by SHSEQR), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign.

ARGUMENTS

COMPQ (input)

= 'V': update the matrix Q of Schur vectors;
 = 'N': do not update Q .

N (input) The order of the matrix T . $N \geq 0$.

T (input/output)

On entry, the upper quasi-triangular matrix T , in Schur Schur canonical form. On exit, the reordered upper quasi-triangular matrix, again in Schur canonical form.

LDT (input)

The leading dimension of the array T . $LDT \geq \max(1, N)$.

Q (input) On entry, if COMPQ = 'V', the matrix Q of Schur vectors. On exit, if COMPQ = 'V', Q has been postmultiplied by the orthogonal transformation matrix Z which reorders T . If COMPQ = 'N', Q is not referenced.

LDQ (input)

The leading dimension of the array Q . $LDQ \geq \max(1, N)$.

IFST (input/output)

Specify the reordering of the diagonal blocks of T . The block with row index IFST is moved to row ILST, by a sequence of transpositions between adjacent blocks. On exit, if IFST pointed on entry to the second row of a 2-by-2 block, it is changed to point to the first row; ILST always

points to the first row of the block in its final position (which may differ from its input value by +1 or -1). $1 \leq \text{IFST} \leq N$; $1 \leq \text{ILST} \leq N$.

ILST (input/output)

See the description of IFST.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

= 1: two adjacent blocks were too close to swap (the problem is very ill-conditioned); T may have been partially reordered, and ILST points to the first row of the current position of the block being moved.

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NAME

strmm - perform one of the matrix-matrix operations $B := \alpha * \text{op}(A) * B$, or $B := \alpha * B * \text{op}(A)$

SYNOPSIS

```
SUBROUTINE STRMM(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
INTEGER M, N, LDA, LDB
REAL ALPHA
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE STRMM_64(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                  LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
INTEGER*8 M, N, LDA, LDB
REAL ALPHA
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TRMM(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A, [LDA],
               B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
INTEGER :: M, N, LDA, LDB
REAL :: ALPHA
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE TRMM_64(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A,
                  [LDA], B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
INTEGER(8) :: M, N, LDA, LDB
REAL :: ALPHA
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strmm(char side, char uplo, char transa, char diag, int
           m, int n, float alpha, float *a, int lda, float
           *b, int ldb);
```

```
void strmm_64(char side, char uplo, char transa, char diag,
              long m, long n, float alpha, float *a, long lda,
              float *b, long ldb);
```

PURPOSE

strmm performs one of the matrix-matrix operations $B := \alpha * \text{op}(A) * B$, or $B := \alpha * B * \text{op}(A)$ where α is a scalar, B is an m by n matrix, A is a unit, or non-unit, upper or lower triangular matrix and $\text{op}(A)$ is one of

$\text{op}(A) = A$ or $\text{op}(A) = A'$.

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether $\text{op}(A)$ multiplies B from the left or right as follows:

SIDE = 'L' or 'l' $B := \alpha * \text{op}(A) * B$.

SIDE = 'R' or 'r' $B := \alpha * B * \text{op}(A)$.

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the matrix A is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n' $\text{op}(A) = A$.

TRANSA = 'T' or 't' $\text{op}(A) = A'$.

TRANSA = 'C' or 'c' $\text{op}(A) = A'$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of B. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of B. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. When alpha is zero then A is not referenced and B need not be set before entry. Unchanged on exit.

A (input)

REAL array of DIMENSION (LDA, k), where k is m when SIDE = 'L' or 'l' and is n when SIDE = 'R' or 'r'.

Before entry with UPLO = 'U' or 'u', the leading k by k upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced.

Before entry with UPLO = 'L' or 'l', the leading k by k lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced.

Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be one. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then $LDA \geq \max(1, m)$, when SIDE = 'R' or 'r' then $LDA \geq \max(1, n)$. Unchanged on exit.

B (input/output)

REAL array of DIMENSION (LDB, n). Before entry, the leading m by n part of the array B must contain the matrix B, and on exit is overwritten by the transformed matrix.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program.

LDB \geq max(1, m). Unchanged on exit.

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NAME

strmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$

SYNOPSIS

```
SUBROUTINE STRMV(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, LDA, INCY  
REAL A(LDA,*), Y(*)
```

```
SUBROUTINE STRMV_64(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, LDA, INCY  
REAL A(LDA,*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TRMV(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, LDA, INCY  
REAL, DIMENSION(:) :: Y  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE TRMV_64(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, LDA, INCY  
REAL, DIMENSION(:) :: Y  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strmv(char uplo, char transa, char diag, int n, float  
          *a, int lda, float *y, int incy);
```

```
void strmv_64(char uplo, char transa, char diag, long n,  
             float *a, long lda, float *y, long incy);
```

PURPOSE

strmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := A'*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not

referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

Y (input/output)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

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NAME

strrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix

SYNOPSIS

```
SUBROUTINE STRRFS(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, NRHS, LDA, LDB, LDX, INFO  
INTEGER WORK2(*)  
REAL A(LDA,*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

```
SUBROUTINE STRRFS_64(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, NRHS, LDA, LDB, LDX, INFO  
INTEGER*8 WORK2(*)  
REAL A(LDA,*), B(LDB,*), X(LDX,*), FERR(*), BERR(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TRRFS(UPLO, [TRANSA], DIAG, N, NRHS, A, [LDA], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, NRHS, LDA, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: WORK2  
REAL, DIMENSION(:) :: FERR, BERR, WORK  
REAL, DIMENSION(:, :) :: A, B, X
```

```
SUBROUTINE TRRFS_64(UPLO, [TRANSA], DIAG, N, NRHS, A, [LDA], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, NRHS, LDA, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: WORK2  
REAL, DIMENSION(:) :: FERR, BERR, WORK  
REAL, DIMENSION(:, :) :: A, B, X
```

C INTERFACE

```
#include <sunperf.h>

void strrfs(char uplo, char transa, char diag, int n, int
            nrhs, float *a, int lda, float *b, int ldb, float
            *x, int ldx, float *ferr, float *berr, int *info);
void strrfs_64(char uplo, char transa, char diag, long n,
               long nrhs, float *a, long lda, float *b, long ldb,
               float *x, long ldx, float *ferr, float *berr, long
               *info);
```

PURPOSE

strrfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix.

The solution matrix X must be computed by STRTRS or some other means before entering this routine. STRRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{*H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U',

the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input) The solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(3*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

strsen - reorder the real Schur factorization of a real matrix $A = Q^*T^*Q^{**}T$, so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix T,

SYNOPSIS

```
SUBROUTINE STRSEN(JOB, COMPQ, SELECT, N, T, LDT, Q, LDQ, WR, WI, M,
  S, SEP, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ
INTEGER N, LDT, LDQ, M, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL SELECT(*)
REAL S, SEP
REAL T(LDT,*), Q(LDQ,*), WR(*), WI(*), WORK(*)
```

```
SUBROUTINE STRSEN_64(JOB, COMPQ, SELECT, N, T, LDT, Q, LDQ, WR, WI,
  M, S, SEP, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ
INTEGER*8 N, LDT, LDQ, M, LWORK, LIWORK, INFO
INTEGER*8 IWORK(*)
LOGICAL*8 SELECT(*)
REAL S, SEP
REAL T(LDT,*), Q(LDQ,*), WR(*), WI(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TRSEN(JOB, COMPQ, SELECT, N, T, [LDT], Q, [LDQ], WR, WI,
  M, S, SEP, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ
INTEGER :: N, LDT, LDQ, M, LWORK, LIWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL, DIMENSION(:) :: SELECT
REAL :: S, SEP
REAL, DIMENSION(:) :: WR, WI, WORK
REAL, DIMENSION(:, :) :: T, Q
```

```
SUBROUTINE TRSEN_64(JOB, COMPQ, SELECT, N, T, [LDT], Q, [LDQ], WR,  
    WI, M, S, SEP, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ  
INTEGER(8) :: N, LDT, LDQ, M, LWORK, LIWORK, INFO  
INTEGER(8), DIMENSION(:) :: IWORK  
LOGICAL(8), DIMENSION(:) :: SELECT  
REAL :: S, SEP  
REAL, DIMENSION(:) :: WR, WI, WORK  
REAL, DIMENSION(:, :) :: T, Q
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strsen(char job, char compq, int *select, int n, float  
    *t, int ldt, float *q, int ldq, float *wr, float  
    *wi, int *m, float *s, float *sep, int *info);
```

```
void strsen_64(char job, char compq, long *select, long n,  
    float *t, long ldt, float *q, long ldq, float *wr,  
    float *wi, long *m, float *s, float *sep, long  
    *info);
```

PURPOSE

strsen reorders the real Schur factorization of a real matrix $A = Q^*T^*Q^{**}T$, so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper quasi-triangular matrix T , and the leading columns of Q form an orthonormal basis of the corresponding right invariant subspace.

Optionally the routine computes the reciprocal condition numbers of the cluster of eigenvalues and/or the invariant subspace.

T must be in Schur canonical form (as returned by SHSEQR), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign.

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for the cluster of eigenvalues (S) or the invariant subspace (SEP):

= 'N': none;

= 'E': for eigenvalues only (S);

= 'V': for invariant subspace only (SEP);

= 'B': for both eigenvalues and invariant subspace (S and SEP).

COMPQ (input)

= 'V': update the matrix Q of Schur vectors;

= 'N': do not update Q.

SELECT (input)

SELECT specifies the eigenvalues in the selected cluster. To select a real eigenvalue $w(j)$, SELECT(j) must be set to $w(j)$ and $w(j+1)$, corresponding to a 2-by-2 diagonal block, either SELECT(j) or SELECT(j+1) or both must be set to either both included in the cluster or both excluded.

N (input) The order of the matrix T. $N \geq 0$.

T (input/output)

On entry, the upper quasi-triangular matrix T, in Schur canonical form. On exit, T is overwritten by the reordered matrix T, again in Schur canonical form, with the selected eigenvalues in the leading diagonal blocks.

LDT (input)

The leading dimension of the array T. $LDT \geq \max(1,N)$.

Q (input) On entry, if COMPQ = 'V', the matrix Q of Schur vectors. On exit, if COMPQ = 'V', Q has been postmultiplied by the orthogonal transformation matrix which reorders T; the leading M columns of Q form an orthonormal basis for the specified invariant subspace. If COMPQ = 'N', Q is not referenced.

LDQ (input)

The leading dimension of the array Q. $LDQ \geq 1$; and if COMPQ = 'V', $LDQ \geq N$.

WR (output)

The real and imaginary parts, respectively, of the reordered eigenvalues of T. The eigenvalues are stored in the same order as on the diagonal of T, with $WR(i) = T(i,i)$ and, if $T(i:i+1,i:i+1)$ is a 2-by-2 diagonal block, $WI(i) > 0$ and $WI(i+1) = -WI(i)$. Note that if a complex eigenvalue is sufficiently ill-conditioned, then its value may differ significantly from its value before reordering.

WI (output)

See the description of WR.

M (output)

The dimension of the specified invariant subspace. $0 < M \leq N$.

S (output)

If JOB = 'E' or 'B', S is a lower bound on the reciprocal condition number for the selected cluster of eigenvalues. S cannot underestimate the true reciprocal condition number by more than a factor of \sqrt{N} . If $M = 0$ or N , $S = 1$. If JOB = 'N' or 'V', S is not referenced.

SEP (output)

If JOB = 'V' or 'B', SEP is the estimated reciprocal condition number of the specified invariant subspace. If M = 0 or N, SEP = norm(T). If JOB = 'N' or 'E', SEP is not referenced.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If JOB = 'N', LWORK \geq max(1,N); if JOB = 'E', LWORK \geq M*(N-M); if JOB = 'V' or 'B', LWORK \geq 2*M*(N-M).

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

If JOB = 'N' or 'E', IWORK is not referenced.

LIWORK (input)

The dimension of the array IWORK. If JOB = 'N' or 'E', LIWORK \geq 1; if JOB = 'V' or 'B', LIWORK \geq M*(N-M).

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
= 1: reordering of T failed because some eigenvalues are too close to separate (the problem is very ill-conditioned); T may have been partially reordered, and WR and WI contain the eigenvalues in the same order as in T; S and SEP (if requested) are set to zero.

FURTHER DETAILS

STRSEN first collects the selected eigenvalues by computing an orthogonal transformation Z to move them to the top left corner of T. In other words, the selected eigenvalues are the eigenvalues of T11 in:

$$Z'^*T*Z = \begin{pmatrix} T11 & T12 \\ 0 & T22 \end{pmatrix} \begin{matrix} n1 \\ n2 \end{matrix}$$

n1 n2

where N = n1+n2 and Z' means the transpose of Z. The first n1 columns of Z span the specified invariant subspace of T.

If T has been obtained from the real Schur factorization of

a matrix $A = Q^*T^*Q'$, then the reordered real Schur factorization of A is given by $A = (Q^*Z)^*(Z'^*T^*Z)^*(Q^*Z)'$, and the first n_1 columns of Q^*Z span the corresponding invariant subspace of A .

The reciprocal condition number of the average of the eigenvalues of T_{11} may be returned in S . S lies between 0 (very badly conditioned) and 1 (very well conditioned). It is computed as follows. First we compute R so that

$$P = \begin{pmatrix} I & R \\ 0 & 0 \end{pmatrix} \begin{matrix} n_1 \\ n_2 \\ n_1 \ n_2 \end{matrix}$$

is the projector on the invariant subspace associated with T_{11} . R is the solution of the Sylvester equation:

$$T_{11}^*R - R^*T_{22} = T_{12}.$$

Let $F\text{-norm}(M)$ denote the Frobenius-norm of M and $2\text{-norm}(M)$ denote the two-norm of M . Then S is computed as the lower bound

$$(1 + F\text{-norm}(R)^2)^{-1/2}$$

on the reciprocal of $2\text{-norm}(P)$, the true reciprocal condition number. S cannot underestimate $1 / 2\text{-norm}(P)$ by more than a factor of \sqrt{N} .

An approximate error bound for the computed average of the eigenvalues of T_{11} is

$$EPS * \text{norm}(T) / S$$

where EPS is the machine precision.

The reciprocal condition number of the right invariant subspace spanned by the first n_1 columns of Z (or of Q^*Z) is returned in SEP . SEP is defined as the separation of T_{11} and T_{22} :

$$\text{sep}(T_{11}, T_{22}) = \text{sigma-min}(C)$$

where $\text{sigma-min}(C)$ is the smallest singular value of the $n_1 \times n_2$ -by- $n_1 \times n_2$ matrix

$$C = \text{kprod}(I(n_2), T_{11}) - \text{kprod}(\text{transpose}(T_{22}), I(n_1))$$

$I(m)$ is an m by m identity matrix, and kprod denotes the Kronecker product. We estimate $\text{sigma-min}(C)$ by the reciprocal of an estimate of the 1-norm of $\text{inverse}(C)$. The true reciprocal 1-norm of $\text{inverse}(C)$ cannot differ from $\text{sigma-min}(C)$ by more than a factor of $\sqrt{n_1 \times n_2}$.

When SEP is small, small changes in T can cause large changes in the invariant subspace. An approximate bound on the maximum angular error in the computed right invariant subspace is

$$EPS * \text{norm}(T) / SEP$$

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NAME

strsm - solve one of the matrix equations $op(A)X = \alpha B$, or $Xop(A) = \alpha B$

SYNOPSIS

```
SUBROUTINE STRSM(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
INTEGER M, N, LDA, LDB
REAL ALPHA
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE STRSM_64(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                   LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
INTEGER*8 M, N, LDA, LDB
REAL ALPHA
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TRSM(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A, [LDA],
                B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
INTEGER :: M, N, LDA, LDB
REAL :: ALPHA
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE TRSM_64(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A,
                  [LDA], B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
INTEGER(8) :: M, N, LDA, LDB
REAL :: ALPHA
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strsm(char side, char uplo, char transa, char diag, int
           m, int n, float alpha, float *a, int lda, float
           *b, int ldb);
```

```
void strsm_64(char side, char uplo, char transa, char diag,
              long m, long n, float alpha, float *a, long lda,
              float *b, long ldb);
```

PURPOSE

strsm solves one of the matrix equations $op(A)X = \alpha B$, or $Xop(A) = \alpha B$ where α is a scalar, X and B are m by n matrices, A is a unit, or non-unit, upper or lower triangular matrix and $op(A)$ is one of

$op(A) = A$ or $op(A) = A'$.

The matrix X is overwritten on B .

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether $op(A)$ appears on the left or right of X as follows:

SIDE = 'L' or 'l' $op(A)X = \alpha B$.

SIDE = 'R' or 'r' $Xop(A) = \alpha B$.

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the matrix A is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the form of $op(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n' $op(A) = A$.

TRANSA = 'T' or 't' $op(A) = A'$.

TRANSA = 'C' or 'c' $op(A) = A'$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of B. M \geq 0. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of B. N \geq 0. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. When alpha is zero then A is not referenced and B need not be set before entry. Unchanged on exit.

A (input)

REAL array of DIMENSION (LDA, k), where k is m when SIDE = 'L' or 'l' and is n when SIDE = 'R' or 'r'.

Before entry with UPLO = 'U' or 'u', the leading k by k upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced.

Before entry with UPLO = 'L' or 'l', the leading k by k lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced.

Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be one. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then LDA \geq max(1, m), when SIDE = 'R' or 'r' then LDA \geq max(1, n). Unchanged on exit.

B (input/output)

REAL array of DIMENSION (LDB, n). Before entry, the leading m by n part of the array B must contain the right-hand side matrix B, and on exit is overwritten by the solution matrix X.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. LDB

$\geq \max(1, m)$. Unchanged on exit.

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NAME

strsna - estimate reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix T (or of any matrix Q^*TQ^{**T} with Q orthogonal)

SYNOPSIS

```
SUBROUTINE STRSNA(JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR, LDVR,  
  S, SEP, MM, M, WORK, LDWORK, WORK1, INFO)
```

```
CHARACTER * 1 JOB, HOWMNY  
INTEGER N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
INTEGER WORK1(*)  
LOGICAL SELECT(*)  
REAL T(LDT,*), VL(LDVL,*), VR(LDVR,*), S(*), SEP(*),  
WORK(LDWORK,*)
```

```
SUBROUTINE STRSNA_64(JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,  
  LDVR, S, SEP, MM, M, WORK, LDWORK, WORK1, INFO)
```

```
CHARACTER * 1 JOB, HOWMNY  
INTEGER*8 N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
INTEGER*8 WORK1(*)  
LOGICAL*8 SELECT(*)  
REAL T(LDT,*), VL(LDVL,*), VR(LDVR,*), S(*), SEP(*),  
WORK(LDWORK,*)
```

F95 INTERFACE

```
SUBROUTINE TRSNA(JOB, HOWMNY, SELECT, N, T, [LDT], VL, [LDVL], VR,  
  [LDVR], S, SEP, MM, M, [WORK], [LDWORK], [WORK1], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNY  
INTEGER :: N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
INTEGER, DIMENSION(:) :: WORK1  
LOGICAL, DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: S, SEP  
REAL, DIMENSION(:, :) :: T, VL, VR, WORK
```

```
SUBROUTINE TRSNA_64(JOB, HOWMNY, SELECT, N, T, [LDT], VL, [LDVL], VR,  
  [LDVR], S, SEP, MM, M, [WORK], [LDWORK], [WORK1], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNY  
INTEGER(8) :: N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: WORK1  
LOGICAL(8), DIMENSION(:) :: SELECT  
REAL, DIMENSION(:) :: S, SEP  
REAL, DIMENSION(:, :) :: T, VL, VR, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strсна(char job, char howmny, int *select, int n, float  
  *t, int ldt, float *vl, int ldvl, float *vr, int  
  ldvr, float *s, float *sep, int mm, int *m, int  
  ldwork, int *info);
```

```
void strсна_64(char job, char howmny, long *select, long n,  
  float *t, long ldt, float *vl, long ldvl, float  
  *vr, long ldvr, float *s, float *sep, long mm,  
  long *m, long ldwork, long *info);
```

PURPOSE

strсна estimates reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix T (or of any matrix Q^*TQ with Q orthogonal).

T must be in Schur canonical form (as returned by SHSEQR), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign.

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for eigenvalues (S) or eigenvectors (SEP):
= 'E': for eigenvalues only (S);
= 'V': for eigenvectors only (SEP);
= 'B': for both eigenvalues and eigenvectors (S and SEP).

HOWMNY (input)

= 'A': compute condition numbers for all eigenpairs;
= 'S': compute condition numbers for selected eigenpairs specified by the array SELECT.

SELECT (input)

If HOWMNY = 'S', SELECT specifies the eigenpairs for which condition numbers are required. To select condition numbers for the eigenpair corresponding to a real eigenvalue $w(j)$, SELECT(j)

must be set to `.TRUE.` To select condition numbers corresponding to a complex conjugate pair of eigenvalues $w(j)$ and $w(j+1)$, either `SELECT(j)` or `SELECT(j+1)` or both, must be set to `.TRUE.` If `HOWMNY = 'A'`, `SELECT` is not referenced.

`N` (input) The order of the matrix `T`. $N \geq 0$.

`T` (input) The upper quasi-triangular matrix `T`, in Schur canonical form.

`LDT` (input)
The leading dimension of the array `T`. $LDT \geq \max(1, N)$.

`VL` (input)
If `JOB = 'E'` or `'B'`, `VL` must contain left eigenvectors of `T` (or of any Q^*TQ with `Q` orthogonal), corresponding to the eigenpairs specified by `HOWMNY` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VL`, as returned by `SHSEIN` or `STREVC`. If `JOB = 'V'`, `VL` is not referenced.

`LDVL` (input)
The leading dimension of the array `VL`. $LDVL \geq 1$; and if `JOB = 'E'` or `'B'`, $LDVL \geq N$.

`VR` (input)
If `JOB = 'E'` or `'B'`, `VR` must contain right eigenvectors of `T` (or of any Q^*TQ with `Q` orthogonal), corresponding to the eigenpairs specified by `HOWMNY` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VR`, as returned by `SHSEIN` or `STREVC`. If `JOB = 'V'`, `VR` is not referenced.

`LDVR` (input)
The leading dimension of the array `VR`. $LDVR \geq 1$; and if `JOB = 'E'` or `'B'`, $LDVR \geq N$.

`S` (output)
If `JOB = 'E'` or `'B'`, the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. For a complex conjugate pair of eigenvalues two consecutive elements of `S` are set to the same value. Thus `S(j)`, `SEP(j)`, and the j -th columns of `VL` and `VR` all correspond to the same eigenpair (but not in general the j -th eigenpair, unless all eigenpairs are selected). If `JOB = 'V'`, `S` is not referenced.

`SEP` (output)
If `JOB = 'V'` or `'B'`, the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. For a complex eigenvector two consecutive elements of `SEP` are set to the same value. If the eigenvalues cannot be reordered to compute `SEP(j)`, `SEP(j)` is set to 0; this can only occur when the true value would be very small anyway. If `JOB = 'E'`, `SEP` is

not referenced.

MM (input)

The number of elements in the arrays S (if JOB = 'E' or 'B') and/or SEP (if JOB = 'V' or 'B'). MM \geq M.

M (output)

The number of elements of the arrays S and/or SEP actually used to store the estimated condition numbers. If HOWMNY = 'A', M is set to N.

WORK (workspace)

dimension(LDWORK,N+1) If JOB = 'E', WORK is not referenced.

LDWORK (input)

The leading dimension of the array WORK. LDWORK \geq 1; and if JOB = 'V' or 'B', LDWORK \geq N.

WORK1 (workspace)

dimension(N) If JOB = 'E', WORK1 is not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The reciprocal of the condition number of an eigenvalue lambda is defined as

$$S(\lambda) = |v' * u| / (\text{norm}(u) * \text{norm}(v))$$

where u and v are the right and left eigenvectors of T corresponding to lambda; v' denotes the conjugate-transpose of v, and norm(u) denotes the Euclidean norm. These reciprocal condition numbers always lie between zero (very badly conditioned) and one (very well conditioned). If n = 1, S(lambda) is defined to be 1.

An approximate error bound for a computed eigenvalue W(i) is given by

$$\text{EPS} * \text{norm}(T) / S(i)$$

where EPS is the machine precision.

The reciprocal of the condition number of the right eigenvector u corresponding to lambda is defined as follows. Suppose

$$T = \begin{pmatrix} \lambda & c \\ 0 & T_{22} \end{pmatrix}$$

Then the reciprocal condition number is

$$\text{SEP}(\lambda, T22) = \sigma\text{-min}(T22 - \lambda I)$$

where $\sigma\text{-min}$ denotes the smallest singular value. We approximate the smallest singular value by the reciprocal of an estimate of the one-norm of the inverse of $T22 - \lambda I$. If $n = 1$, $\text{SEP}(1)$ is defined to be $\text{abs}(T(1,1))$.

An approximate error bound for a computed right eigenvector $\text{VR}(i)$ is given by

$$\text{EPS} * \text{norm}(T) / \text{SEP}(i)$$

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NAME

strsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$

SYNOPSIS

```
SUBROUTINE STRSV(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, LDA, INCY  
REAL A(LDA,*), Y(*)
```

```
SUBROUTINE STRSV_64(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, LDA, INCY  
REAL A(LDA,*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE TRSV(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, LDA, INCY  
REAL, DIMENSION(:) :: Y  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE TRSV_64(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, LDA, INCY  
REAL, DIMENSION(:) :: Y  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strsv(char uplo, char transa, char diag, int n, float  
          *a, int lda, float *y, int incy);
```

```
void strsv_64(char uplo, char transa, char diag, long n,  
             float *a, long lda, float *y, long incy);
```

PURPOSE

strsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular matrix. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANS (input)

On entry, TRANS specifies the equations to be solved as follows:

TRANS = 'N' or 'n' $A*x = b$.

TRANS = 'T' or 't' $A'*x = b$.

TRANS = 'C' or 'c' $A'*x = b$.

Unchanged on exit.

TRANS is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must

contain the upper triangular matrix and the strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

Y (input/output)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

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NAME

strsyl - solve the real Sylvester matrix equation

SYNOPSIS

```
SUBROUTINE STRSYL(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C, LDC,
  SCALE, INFO)
```

```
CHARACTER * 1 TRANA, TRANB
INTEGER ISGN, M, N, LDA, LDB, LDC, INFO
REAL SCALE
REAL A(LDA,*), B(LDB,*), C(LDC,*)
```

```
SUBROUTINE STRSYL_64(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C,
  LDC, SCALE, INFO)
```

```
CHARACTER * 1 TRANA, TRANB
INTEGER*8 ISGN, M, N, LDA, LDB, LDC, INFO
REAL SCALE
REAL A(LDA,*), B(LDB,*), C(LDC,*)
```

F95 INTERFACE

```
SUBROUTINE TRSYL(TRANA, TRANB, ISGN, M, N, A, [LDA], B, [LDB], C,
  [LDC], SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: TRANA, TRANB
INTEGER :: ISGN, M, N, LDA, LDB, LDC, INFO
REAL :: SCALE
REAL, DIMENSION(:,) :: A, B, C
```

```
SUBROUTINE TRSYL_64(TRANA, TRANB, ISGN, M, N, A, [LDA], B, [LDB], C,
  [LDC], SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: TRANA, TRANB
INTEGER(8) :: ISGN, M, N, LDA, LDB, LDC, INFO
REAL :: SCALE
REAL, DIMENSION(:,) :: A, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strsyl(char trana, char tranb, int isgn, int m, int n,
           float *a, int lda, float *b, int ldb, float *c,
           int ldc, float *scale, int *info);
```

```
void strsyl_64(char trana, char tranb, long isgn, long m,
              long n, float *a, long lda, float *b, long ldb,
              float *c, long ldc, float *scale, long *info);
```

PURPOSE

strsyl solves the real Sylvester matrix equation:

```
op(A)*X + X*op(B) = scale*C or
op(A)*X - X*op(B) = scale*C,
```

where $op(A) = A$ or A^{**T} , and A and B are both upper quasi-triangular. A is M -by- M and B is N -by- N ; the right hand side C and the solution X are M -by- N ; and $scale$ is an output scale factor, set ≤ 1 to avoid overflow in X .

A and B must be in Schur canonical form (as returned by SHSEQR), that is, block upper triangular with 1-by-1 and 2-by-2 diagonal blocks; each 2-by-2 diagonal block has its diagonal elements equal and its off-diagonal elements of opposite sign.

ARGUMENTS

TRANA (input)

```
Specifies the option op(A):
= 'N': op(A) = A      (No transpose)
= 'T': op(A) = A**T  (Transpose)
= 'C': op(A) = A**H  (Conjugate transpose = Tran-
spose)
```

TRANB (input)

```
Specifies the option op(B):
= 'N': op(B) = B      (No transpose)
= 'T': op(B) = B**T  (Transpose)
= 'C': op(B) = B**H  (Conjugate transpose = Tran-
spose)
```

ISGN (input)

```
Specifies the sign in the equation:
= +1: solve op(A)*X + X*op(B) = scale*C
= -1: solve op(A)*X - X*op(B) = scale*C
```

M (input) The order of the matrix A , and the number of rows in the matrices X and C . $M \geq 0$.

N (input) The order of the matrix B , and the number of columns in the matrices X and C . $N \geq 0$.

A (input) The upper quasi-triangular matrix A , in Schur canonical form.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,M).

B (input) The upper quasi-triangular matrix B, in Schur canonical form.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

C (input/output)
On entry, the M-by-N right hand side matrix C. On exit, C is overwritten by the solution matrix X.

LDC (input)
The leading dimension of the array C. LDC \geq max(1,M)

SCALE (output)
The scale factor, scale, set ≤ 1 to avoid overflow in X.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
= 1: A and B have common or very close eigenvalues; perturbed values were used to solve the equation (but the matrices A and B are unchanged).

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NAME

strti2 - compute the inverse of a real upper or lower triangular matrix

SYNOPSIS

```
SUBROUTINE STRTI2(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER N, LDA, INFO  
REAL A(LDA,*)
```

```
SUBROUTINE STRTI2_64(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER*8 N, LDA, INFO  
REAL A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE TRTI2(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE TRTI2_64(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER(8) :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strti2(char uplo, char diag, int n, float *a, int lda,  
            int *info);
```

```
void strti2_64(char uplo, char diag, long n, float *a, long  
               lda, long *info);
```

PURPOSE

strti2 computes the inverse of a real upper or lower triangular matrix.

This is the Level 2 BLAS version of the algorithm.

ARGUMENTS

UPLO (input)

Specifies whether the matrix A is upper or lower triangular. = 'U': Upper triangular
= 'L': Lower triangular

DIAG (input)

Specifies whether or not the matrix A is unit triangular. = 'N': Non-unit triangular
= 'U': Unit triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular matrix A. If UPLO = 'U', the leading n by n upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n by n lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

On exit, the (triangular) inverse of the original matrix, in the same storage format.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value

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NAME

strtri - compute the inverse of a real upper or lower triangular matrix A

SYNOPSIS

```
SUBROUTINE STRTRI(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER N, LDA, INFO  
REAL A(LDA,*)
```

```
SUBROUTINE STRTRI_64(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
INTEGER*8 N, LDA, INFO  
REAL A(LDA,*)
```

F95 INTERFACE

```
SUBROUTINE TRTRI(UPLO, DIAG, N, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

```
SUBROUTINE TRTRI_64(UPLO, DIAG, N, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
INTEGER(8) :: N, LDA, INFO  
REAL, DIMENSION(:, :) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strtri(char uplo, char diag, int n, float *a, int lda,  
            int *info);
```

```
void strtri_64(char uplo, char diag, long n, float *a, long  
               lda, long *info);
```

PURPOSE

strtri computes the inverse of a real upper or lower triangular matrix A.

This is the Level 3 BLAS version of the algorithm.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1. On exit, the (triangular) inverse of the original matrix, in the same storage format.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, A(i,i) is exactly zero. The triangular matrix is singular and its inverse can not be computed.

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NAME

strtrs - solve a triangular system of the form $A * X = B$
or $A^{**T} * X = B$,

SYNOPSIS

```
SUBROUTINE STRTRS(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER N, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

```
SUBROUTINE STRTRS_64(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB,  
INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
REAL A(LDA,*), B(LDB,*)
```

F95 INTERFACE

```
SUBROUTINE TRTRS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER :: N, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

```
SUBROUTINE TRTRS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
REAL, DIMENSION(:,) :: A, B
```

C INTERFACE

```
#include <sunperf.h>
```

```
void strtrs(char uplo, char transa, char diag, int n, int  
nrhs, float *a, int lda, float *b, int ldb, int  
*info);
```

```
void strtrs_64(char uplo, char transa, char diag, long n,
              long nrhs, float *a, long lda, float *b, long ldb,
              long *info);
```

PURPOSE

strtrs solves a triangular system of the form
 $A * X = B$ or $A^{**T} * X = B$

where A is a triangular matrix of order N, and B is an N-by-NRHS matrix. A check is made to verify that A is non-singular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{*H} * X = B$ (Conjugate transpose = Transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the right hand side matrix B. On exit, if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

> 0: if INFO = i, the i-th diagonal element of A
is zero, indicating that the matrix is singular
and the solutions X have not been computed.

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NAME

stzrqf - routine is deprecated and has been replaced by routine STZRZF

SYNOPSIS

```
SUBROUTINE STZRQF(M, N, A, LDA, TAU, INFO)
```

```
INTEGER M, N, LDA, INFO  
REAL A(LDA,*), TAU(*)
```

```
SUBROUTINE STZRQF_64(M, N, A, LDA, TAU, INFO)
```

```
INTEGER*8 M, N, LDA, INFO  
REAL A(LDA,*), TAU(*)
```

F95 INTERFACE

```
SUBROUTINE TZRQF(M, N, A, [LDA], TAU, [INFO])
```

```
INTEGER :: M, N, LDA, INFO  
REAL, DIMENSION(:) :: TAU  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE TZRQF_64(M, N, A, [LDA], TAU, [INFO])
```

```
INTEGER(8) :: M, N, LDA, INFO  
REAL, DIMENSION(:) :: TAU  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stzrqf(int m, int n, float *a, int lda, float *tau, int  
           *info);
```

```
void stzrqf_64(long m, long n, float *a, long lda, float  
             *tau, long *info);
```

PURPOSE

stzrqf routine is deprecated and has been replaced by routine STZRZF.

STZRQF reduces the M-by-N ($M \leq N$) real upper trapezoidal matrix A to upper triangular form by means of orthogonal transformations.

The upper trapezoidal matrix A is factored as

$$A = \begin{pmatrix} R & 0 \end{pmatrix} * Z,$$

where Z is an N-by-N orthogonal matrix and R is an M-by-M upper triangular matrix.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq M$.

A (input/output)

On entry, the leading M-by-N upper trapezoidal part of the array A must contain the matrix to be factorized. On exit, the leading M-by-M upper triangular part of A contains the upper triangular matrix R, and elements M+1 to N of the first M rows of A, with the array TAU, represent the orthogonal matrix Z as a product of M elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The factorization is obtained by Householder's method. The kth transformation matrix, $Z(k)$, which is used to introduce zeros into the $(m - k + 1)$ th row of A, is given in the form

$$Z(k) = \begin{pmatrix} I & 0 \\ 0 & T(k) \end{pmatrix},$$

where

$$T(k) = I - \tau * u(k) * u(k)', \quad u(k) = \begin{pmatrix} 1 \\ \end{pmatrix},$$

$$\begin{pmatrix} 0 \\ z(k) \end{pmatrix}$$

tau is a scalar and $z(k)$ is an $(n - m)$ element vector. tau and $z(k)$ are chosen to annihilate the elements of the kth row of X.

The scalar tau is returned in the kth element of TAU and the vector $u(k)$ in the kth row of A, such that the elements of $z(k)$ are in $a(k, m + 1), \dots, a(k, n)$. The elements of R are returned in the upper triangular part of A.

Z is given by

$$Z = Z(1) * Z(2) * \dots * Z(m).$$

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NAME

stzrzf - reduce the M-by-N ($M \leq N$) real upper trapezoidal matrix A to upper triangular form by means of orthogonal transformations

SYNOPSIS

```
SUBROUTINE STZRF(M, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
INTEGER M, N, LDA, LWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

```
SUBROUTINE STZRF_64(M, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
INTEGER*8 M, N, LDA, LWORK, INFO  
REAL A(LDA,*), TAU(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE TZRF([M], [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
INTEGER :: M, N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

```
SUBROUTINE TZRF_64([M], [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
INTEGER(8) :: M, N, LDA, LWORK, INFO  
REAL, DIMENSION(:) :: TAU, WORK  
REAL, DIMENSION(:,) :: A
```

C INTERFACE

```
#include <sunperf.h>
```

```
void stzrzf(int m, int n, float *a, int lda, float *tau, int  
           *info);
```

```
void stzrzf_64(long m, long n, float *a, long lda, float  
              *tau, long *info);
```

PURPOSE

stzrzf reduces the M-by-N ($M \leq N$) real upper trapezoidal matrix A to upper triangular form by means of orthogonal transformations.

The upper trapezoidal matrix A is factored as

$$A = \begin{pmatrix} R & 0 \end{pmatrix} * Z,$$

where Z is an N-by-N orthogonal matrix and R is an M-by-M upper triangular matrix.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the leading M-by-N upper trapezoidal part of the array A must contain the matrix to be factorized. On exit, the leading M-by-M upper triangular part of A contains the upper triangular matrix R, and elements M+1 to N of the first M rows of A, with the array TAU, represent the orthogonal matrix Z as a product of M elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1, M)$. For optimum performance $LWORK \geq M * NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by

A. Petitot, Computer Science Dept., Univ. of Tenn., Knoxville, USA

The factorization is obtained by Householder's method. The kth transformation matrix, $Z(k)$, which is used to introduce zeros into the $(m - k + 1)$ th row of A, is given in the form

$$Z(k) = \begin{pmatrix} I & 0 \\ 0 & T(k) \end{pmatrix},$$

where

$$T(k) = I - \tau u(k)u(k)', \quad u(k) = \begin{pmatrix} 1 \\ 0 \\ z(k) \end{pmatrix},$$

τ is a scalar and $z(k)$ is an $(n - m)$ element vector. τ and $z(k)$ are chosen to annihilate the elements of the kth row of X.

The scalar τ is returned in the kth element of TAU and the vector $u(k)$ in the kth row of A, such that the elements of $z(k)$ are in $a(k, m + 1), \dots, a(k, n)$. The elements of R are returned in the upper triangular part of A.

Z is given by

$$Z = Z(1) * Z(2) * \dots * Z(m).$$

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NAME

sunperf_version - gets library information

F95 INTERFACE

C INTERFACE

```
#include <sunperf.h>
```

The C version of sunperf_version also return a pointer to the version string.

```
char *sunperf_version(int *version, int *patch, int *update);
```

```
char *sunperf_version_64(long *version, long *patch, long *update);
```

ARGUMENTS

VERSION (output)
Version number of library

PATCH (output)
Patch number of library

Update number of library

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NAME

svbrmm - variable block sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE SVBRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LDB, LDC, LWORK  
INTEGER          INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(KB+1),  
*                BPNTRB(MB), BPNTRE(MB)  
REAL             ALPHA, BETA  
REAL             VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE SVBRMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LDB, LDC, LWORK  
INTEGER*8        INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(KB+1),  
*               BPNTRB(MB), BPNTRE(MB)  
REAL             ALPHA, BETA  
REAL             VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE VBRMM(TRANSA, MB, [N], KB, ALPHA, DESCRA,  
*              VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*              B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, KB  
INTEGER, DIMENSION(:) :: DESCRA, INDX, BINDX  
INTEGER, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE  
REAL          ALPHA, BETA  
REAL, DIMENSION(:) :: VAL  
REAL, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE VBRMM_64(TRANSA, MB, [N], KB, ALPHA, DESCRA,  
*                   VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*                   B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB
```


DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, scalar array VAL of length NNZ consists of the block entries of A where each block entry is a dense rectangular matrix stored column by column where NNZ denotes the total number of point entries in all nonzero block entries of a matrix A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length BNNZ+1 where BNNZ is the number of block entries of the matrix A such that the I-th element of INDX[] points to the location in VAL of the (1,1) element of the I-th block entry. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ is the number block entries of the matrix A. Unchanged on exit.

RPNTR(input) On entry, RPNTR is an integer array of length MB+1 such that RPNTR(I)-RPNTR(1)+1 is the row index of the first point row in the I-th block row. RPNTR(MB+1) is set to M+RPNTR(1) where M is the number of rows in the matrix A. Thus, the number of point rows in the I-th block row is RPNTR(I+1)-RPNTR(I). Unchanged on exit.

CPNTR(input) On entry, CPNTR is an integer array of length KB+1 such that CPNTR(J)-CPNTR(1)+1 is the column index of the first point column in the J-th block column. CPNTR(KB+1) is set to K+CPNTR(1) where K is the number of columns in the matrix A. Thus, the number of point columns in the J-th block column is CPNTR(J+1)-CPNTR(J). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(I)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the I-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(I)-BPNTRB(1) points to location in BINDX of the last block entry of the I-th block row of A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise
 the leading k by n part of the array C must contain the
 matrix C. On exit, the array C is overwritten by the matrix
 (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible
 with NIST FORTRAN Sparse Blas but the sources are different.
 Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN
 Sparse Blas. Besides several new features and routines are
 implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS)
 Standard", University of Tennessee, Knoxville, Tennessee,
 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to
 use just one sparse matrix representation of a general
 matrix A for computing matrix-matrix multiply for another
 sparse matrix composed by block triangles and/or the main
 block diagonal of A. The full description of the feature for
 block entry formats is given in section NOTES/BUGS for the
 sbcomm manpage.

NOTES/BUGS

1. For a general matrix (*DESCRA*(1)=0), array CPNTR can be
 different from RPNTR. For all other matrix types, RPNTR
 must equal CPNTR and a single array can be passed for both
 arguments.

2. It is known that there exists another representation of the variable block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of six array instead of the seven used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the array BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of variable block sparse row format the following calling sequence should be used

```
      SUBROUTINE SVBRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                      VAL, INDX, BINDX, RPNTR, CPNTR, IA, IA(2),  
*                      B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

svbrsm - variable block sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE SVBRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER TRANSA, MB, N, UNITD, DESCRA(5), LDB, LDC, LWORK  
INTEGER INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(MB+1),  
* BPNTRB(MB), BPNTRE(MB)  
REAL ALPHA, BETA  
REAL DV(*), VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE SVBRSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK )  
INTEGER*8 TRANSA, MB, N, UNITD, DESCRA(5), LDB, LDC, LWORK  
INTEGER*8 INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(MB+1),  
* BPNTRB(MB), BPNTRE(MB)  
REAL ALPHA, BETA  
REAL DV(*), VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE VBRSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
* B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER TRANSA, MB, UNITD  
INTEGER, DIMENSION(:) :: DESCRA, INDX, BINDX  
INTEGER, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE  
REAL ALPHA, BETA  
REAL, DIMENSION(:) :: VAL, DV  
REAL, DIMENSION(:, :) :: B, C  
  
SUBROUTINE VBRSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
* B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, MB, UNITD  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, BINDX
```

```

INTEGER*8, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE
REAL    ALPHA, BETA
REAL, DIMENSION(:) :: VAL, DV
REAL, DIMENSION(:, :) :: B, C

```

C INTERFACE

```
#include <sunperf.h>
```

```

void svbrsm (int transa, int mb, int n, int unitd, float
*dv, float alpha, int *descra, float *val, int *indx, int
*bindx, int *rpntr, int *cpntr, int *bpntrb, int *bpntre,
float *b, int ldb, float beta, float *c, int ldc);

```

```

void svbrsm_64 (long transa, long mb, long n, long unitd,
float *dv, float alpha, long *descra, float *val, long
*indx, long *bindx, long *rpntr, long *cpntr, long *bpntrb,
long *bpntre, float *b, long ldb, float beta, float *c,
long ldc);

```

DESCRIPTION

svbrsm performs one of the matrix-matrix operations

```

C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,

```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a block diagonal matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the variable block sparse row format and op(A) is one of

```

op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).

```

The number of rows in A is determined as follows

```
m=RPNTR(MB+1)-RPNTR(1).
```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, integer MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.
DV(input)	On entry, array DV contains the block entries of the block diagonal matrix D. The size of the J-th block is RPNTR(J+1)-RPNTR(J) and each block contains matrix

entries stored column-major. The total length of array DV is given by the formula:

$$\text{sum over } J \text{ from } 1 \text{ to } MB: \\ ((RPNTR(J+1)-RPNTR(J))*(RPNTR(J+1)-RPNTR(J)))$$

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:

DESCRA(1) matrix structure

- 0 : general
- 1 : symmetric (A=A')
- 2 : Hermitian (A= CONJG(A'))
- 3 : Triangular
- 4 : Skew(Anti)-Symmetric (A=-A')
- 5 : Diagonal
- 6 : Skew-Hermitian (A= -CONJG(A'))

Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator

- 1 : lower
- 2 : upper

DESCRA(3) main diagonal type

- 0 : non-identity blocks on the main diagonal
- 1 : identity diagonal blocks
- 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)

- 0 : C/C++ compatible
- 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)

- 0 : unknown
- 1 : no repeated indices

VAL(input) On entry, scalar array VAL of length NNZ consists of the block entries of A where each block entry is a dense rectangular matrix stored column by column where NNZ denotes the total number of point entries in all nonzero block entries of the matrix A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length BNNZ+1 where BNNZ is the number of block entries of the matrix A such that the I-th element of INDX[] points to the location in VAL of the (1,1) element of the I-th block entry. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ is the number block entries of the matrix A. Block column indices MUST be sorted in increasing order for each block row. Unchanged on exit.

RPNTR(input) On entry, RPNTR is an integer array of length MB+1 such that RPNTR(I)-RPNTR(1)+1 is the row index of the first point row in the I-th block row. RPNTR(MB+1) is set to M+RPNTR(1) where M is the number of rows in the matrix A.

Thus, the number of point rows in the I-th block row is RPNTR(I+1)-RPNTR(I). Unchanged on exit.

NOTE: For the current version CPNTR must equal RPNTR and a single array can be passed for both arguments

CPNTR(input) On entry, CPNTR is integer array of length KB+1 such that

CPNTR(J)-CPNTR(1)+1 is the column index of the first point column in the J-th block column. CPNTR(KB+1) is set to K+CPNTR(1) where K is the number of columns in the matrix A. Thus, the number of point columns in the J-th block column is CPNTR(J+1)-CPNTR(J). Unchanged on exit.

NOTE: For the current version CPNTR must equal RPNTR and a single array can be passed for both arguments

- BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(I)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the I-th block row of A. Unchanged on exit.
- BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(I)-BPNTRB(1) points to location in BINDX of the last block entry of the I-th block row of A. Unchanged on exit.
- B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.
- LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.
- BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.
- C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix (alpha*op(A) * B + beta*C).
- LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.
- WORK(workspace) Scratch array of length LWORK. On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.
- LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least $M = \text{RPNTR}(\text{MB}+1) - \text{RPNTR}(1)$. For good performance, LWORK should generally be larger. For optimum performance on multiple processors, $\text{LWORK} \geq M * \text{N_CPUS}$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If `DESCRA(3)= 0` , the lower or upper triangular part of each diagonal block is used by the routine depending on `DESCRA(2)`.
3. If `DESCRA(3)=1` , the diagonal blocks in the variable block row representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If `DESCRA(3)=2` , diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.
5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
------------------------	------------------------	------------------------	--------

3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

6. It is known that there exists another representation of the variable block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of six array instead of the seven used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the array BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of the variable block sparse row format the following calling sequence should be used

```

SUBROUTINE SVBRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, BINDX, RPNTR, CPNTR, IA, IA(2),
*                 B, LDB, BETA, C, LDC, WORK, LWORK )

```

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NAME

swiener - perform Wiener deconvolution of two signals

SYNOPSIS

```
SUBROUTINE SWIENER(N_POINTS, ACOR, XCOR, FLTR, EROP, ISW, IERR)
```

```
INTEGER N_POINTS, ISW, IERR  
REAL ACOR(*), XCOR(*), FLTR(*), EROP(*)
```

```
SUBROUTINE SWIENER_64(N_POINTS, ACOR, XCOR, FLTR, EROP, ISW, IERR)
```

```
INTEGER*8 N_POINTS, ISW, IERR  
REAL ACOR(*), XCOR(*), FLTR(*), EROP(*)
```

F95 INTERFACE

```
SUBROUTINE WIENER(N_POINTS, ACOR, XCOR, FLTR, EROP, ISW, IERR)
```

```
INTEGER :: N_POINTS, ISW, IERR  
REAL, DIMENSION(:) :: ACOR, XCOR, FLTR, EROP
```

```
SUBROUTINE WIENER_64(N_POINTS, ACOR, XCOR, FLTR, EROP, ISW, IERR)
```

```
INTEGER(8) :: N_POINTS, ISW, IERR  
REAL, DIMENSION(:) :: ACOR, XCOR, FLTR, EROP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void swiener(int n_points, float *acor, float *xcor, float  
            *fltr, float *erop, int *isw, int *ierr);
```

```
void swiener_64(long n_points, float *acor, float *xcor,  
               float *fltr, float *erop, long *isw, long *ierr);
```

PURPOSE

swiener performs Wiener deconvolution of two signals.

ARGUMENTS

N_POINTS (input)
On entry, the number of points in the input correlations. Unchanged on exit.

ACOR (input)
On entry, autocorrelation coefficients. Unchanged on exit.

XCOR (input)
On entry, cross-correlation coefficients. Unchanged on exit.

FLTR (output)
On exit, filter coefficients.

EROP (output)
On exit, the prediction error.

ISW (input)
On entry, if ISW .EQ. 0 then perform spiking deconvolution, otherwise perform general deconvolution. Unchanged on exit.

IERR (output)
On exit, the deconvolution was successful iff IERR .EQ. 0, otherwise there was an error.

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NAME

`use_threads` - Sets the number of threads to use for subsequent parallel regions

SYNOPSIS

```
SUBROUTINE USE_THREADS(NTHREADS)
```

```
INTEGER NTHREADS
```

```
SUBROUTINE USE_THREADS_64(NTHREADS)
```

```
INTEGER*8 NTHREADS
```

F95 INTERFACE

```
SUBROUTINE USE_THREADS(NTHREADS)
```

```
INTEGER :: NTHREADS
```

```
SUBROUTINE USE_THREADS_64(NTHREADS)
```

```
INTEGER(8) :: NTHREADS
```

C INTERFACE

```
#include <sunperf.h>
```

```
void use_threads(int nthreads);
```

```
void use_threads_64(long nthreads);
```

PURPOSE

`USE_THREADS(NTHREADS)` sets the number of threads to `MAX(1,NTHREADS)` to use for subsequent parallel regions by calling library routine `OMP_SET_NUM_THREADS` which is part of the OpenMP Fortran Application Program Interface. From the OpenMP Fortran Application Program Interface which can be found at the official OpenMP website, <http://www.openmp.org/>,

`OMP_SET_NUM_THREADS(scalar_integer_expression)`, where

scalar_integer_expression = MAX(1,NTHREADS), is described as follows: "The effect of this function depends on whether dynamic adjustment of the number of threads is enabled. If dynamic adjustment is disabled, the value of the scalar_integer_expression is used as the number of threads for all subsequent parallel regions prior to the next call to this function; otherwise, the value is used as the maximum number of threads that will be used. This function has effect only when called from serial portions of the program. If it is called from a portion of the program where the OMP_IN_PARALLEL function returns .TRUE., the behavior of this function is unspecified."

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NAME

`using_threads` - In a parallel environment, if called from a serial region of the master thread it returns the number of threads available for execution (determined by function `OMP_GET_NUM_THREADS`). Else, if it is called from a thread in the team executing the parallel region it returns a 1.

`USING_THREADS` subroutine

SYNOPSIS

```
INTEGER FUNCTION USING_THREADS()
```

```
INTEGER*8 FUNCTION USING_THREADS_64()
```

F95 INTERFACE

```
INTEGER FUNCTION USING_THREADS()
```

```
INTEGER(8) FUNCTION USING_THREADS_64()
```

C INTERFACE

```
#include <sunperf.h>
```

```
int using_threads();
```

```
long using_threads_64();
```

PURPOSE

In a parallel environment, if called from a serial region of the master thread `USING_THREADS` returns the number of threads available for execution. This number is determined by function call `OMP_GET_NUM_THREADS` (See the specifications for the OpenMP Fortran Application Program Interface at <http://www.openmp.org> for more details on `OMP_GET_NUM_THREADS`). Else, if it is called from a thread in the team executing the parallel region, it returns a 1. A user routine can call `using_threads` to determine if it is already in a parallel region. If this is the case, a 1 is

returned and the routine can choose the serial path instead of going parallel, thus avoiding nested parallelism.

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NAME

vcfftb - compute a periodic sequence from its Fourier coefficients. The VCFFT operations are normalized, so a call of VCFFTF followed by a call of VCFFTB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VCFFTB(M, N, X, XT, MDIMX, ROWCOL, WSAVE)
```

```
CHARACTER * 1 ROWCOL  
COMPLEX X(MDIMX,*), XT(MDIMX,*), WSAVE(*)  
INTEGER M, N, MDIMX
```

```
SUBROUTINE VCFFTB_64(M, N, X, XT, MDIMX, ROWCOL, WSAVE)
```

```
CHARACTER * 1 ROWCOL  
COMPLEX X(MDIMX,*), XT(MDIMX,*), WSAVE(*)  
INTEGER*8 M, N, MDIMX
```

F95 INTERFACE

```
SUBROUTINE FFTB([M], [N], X, XT, [MDIMX], ROWCOL, WSAVE)
```

```
CHARACTER(LEN=1) :: ROWCOL  
COMPLEX, DIMENSION(:) :: WSAVE  
COMPLEX, DIMENSION(:,:) :: X, XT  
INTEGER :: M, N, MDIMX
```

```
SUBROUTINE FFTB_64([M], [N], X, XT, [MDIMX], ROWCOL, WSAVE)
```

```
CHARACTER(LEN=1) :: ROWCOL  
COMPLEX, DIMENSION(:) :: WSAVE  
COMPLEX, DIMENSION(:,:) :: X, XT  
INTEGER(8) :: M, N, MDIMX
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vcfftb(int m, int n, complex *x, complex *xt, int  
           mdimx, char rowcol, complex *wsave);
```

```
void vcfftb_64(long m, long n, complex *x, complex *xt, long
```

```
mdimx, char rowcol, complex *wsave);
```

ARGUMENTS

M (input) If ROWCOL = 'R' or 'r', M is the number of sequences to be transformed. Otherwise, M is the length of the sequences to be transformed. M >= 0.

N (input) If ROWCOL = 'R' or 'r', N is the length of the sequences to be transformed. Otherwise, N is the number of sequences to be transformed. N >= 0.

X (input) On entry, if ROWCOL = 'R' or 'r' X(MDIMX,N) is an array whose first M rows contain the sequences to be transformed. Otherwise, X(MDIMX,N) contains data sequences of length M stored in N columns of X.

XT (input)
A work array. The size of this workspace depends on the number of threads that are used to execute this routine. There are various functions that can be used to determine the number of threads available (get_env, available_threads, etc). The appropriate amount, which is (number of threads * length of data sequences), can then be dynamically allocated for XT from the driver routine. If XT can only be allocated statically, then the size of XT should be (length of data sequences * number of sequences).

MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. MDIMX >= M.

ROWCOL (input)
Indicates whether to transform rows ('R' or 'r') or columns ('C' or 'c').

WSAVE (input/output)
On entry, an array of dimension (L2+15) or greater, where L2 = 2*M if ROWCOL = ('R' or 'r'). Otherwise, L2 = 2*N. WSAVE is initialized by VCFFTI.

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NAME

vcfftf - compute the Fourier coefficients of a periodic sequence. The VCFFT operations are normalized, so a call of VCFFTF followed by a call of VCFFTB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VCFFTF(M, N, X, XT, MDIMX, ROWCOL, WSAVE)
```

```
CHARACTER * 1 ROWCOL  
COMPLEX X(MDIMX,*), XT(MDIMX,*), WSAVE(*)  
INTEGER M, N, MDIMX
```

```
SUBROUTINE VCFFTF_64(M, N, X, XT, MDIMX, ROWCOL, WSAVE)
```

```
CHARACTER * 1 ROWCOL  
COMPLEX X(MDIMX,*), XT(MDIMX,*), WSAVE(*)  
INTEGER*8 M, N, MDIMX
```

F95 INTERFACE

```
SUBROUTINE FFTF([M], [N], X, XT, [MDIMX], ROWCOL, WSAVE)
```

```
CHARACTER(LEN=1) :: ROWCOL  
COMPLEX, DIMENSION(:) :: WSAVE  
COMPLEX, DIMENSION(:,:) :: X, XT  
INTEGER :: M, N, MDIMX
```

```
SUBROUTINE FFTF_64([M], [N], X, XT, [MDIMX], ROWCOL, WSAVE)
```

```
CHARACTER(LEN=1) :: ROWCOL  
COMPLEX, DIMENSION(:) :: WSAVE  
COMPLEX, DIMENSION(:,:) :: X, XT  
INTEGER(8) :: M, N, MDIMX
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vcfftf(int m, int n, complex *x, complex *xt, int  
           mdimx, char rowcol, complex *wsave);
```

```
void vcfftf_64(long m, long n, complex *x, complex *xt, long
```

```
mdimx, char rowcol, complex *wsave);
```

ARGUMENTS

M (input) If ROWCOL = 'R' or 'r', M is the number of sequences to be transformed. Otherwise, M is the length of the sequences to be transformed. M >= 0.

N (input) If ROWCOL = 'R' or 'r', N is the length of the sequences to be transformed. Otherwise, N is the number of sequences to be transformed. N >= 0.

X (input) On entry, if ROWCOL = 'R' or 'r' X(MDIMX,N) is an array whose first M rows contain the sequences to be transformed. Otherwise, X(MDIMX,N) contains data sequences of length M stored in N columns of X.

XT (input)
A work array. The size of this workspace depends on the number of threads that are used to execute this routine. There are various functions that can be used to determine the number of threads available (get_env, available_threads, etc). The appropriate amount, which is (number of threads * length of data sequences), can then be dynamically allocated for XT from the driver routine. If XT can only be allocated statically, then the size of XT should be (length of data sequences * number of sequences).

MDIMX (input)
Leading dimension of the arrays X. MDIMX >= M.

ROWCOL (input)
Indicates whether data sequences in X are stored row-wise ('R' or 'r') or column-wise ('C' or 'c').

WSAVE (input/output)
On entry, an array of dimension (L2+15) or greater, where L2 = 2*M if ROWCOL = ('R' or 'r'). Otherwise, L2 = 2*N. WSAVE is initialized by VCFFTI.

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NAME

vcfffti - initialize the array WSAVE, which is used in both VCFFTF and VCFFTB.

SYNOPSIS

```
SUBROUTINE VCFFTI(N, WSAVE)

COMPLEX WSAVE(*)
INTEGER N

SUBROUTINE VCFFTI_64(N, WSAVE)

COMPLEX WSAVE(*)
INTEGER*8 N
```

F95 INTERFACE

```
SUBROUTINE VFFTI(N, WSAVE)

COMPLEX, DIMENSION(:) :: WSAVE
INTEGER :: N

SUBROUTINE VFFTI_64(N, WSAVE)

COMPLEX, DIMENSION(:) :: WSAVE
INTEGER(8) :: N
```

C INTERFACE

```
#include <sunperf.h>

void vcffti(int n, complex *wsave);

void vcffti_64(long n, complex *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array of dimension $(2*N + 15)$ or greater. VCFFTI needs to be called only once to initialize WSAVE before calling VCFFTF and/or VCFFTB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

`vcosqb` - synthesize a Fourier sequence from its representation in terms of a cosine series with odd wave numbers. The VCOSQ operations are normalized, so a call of VCOSQF followed by a call of VCOSQB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VCOSQB(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VCOSQB_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQB([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

```
SUBROUTINE COSQB_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vcosqb(int m, int n, float *x, float *xt, int mdimx,  
           float *wsave);
```

```
void vcosqb_64(long m, long n, float *x, float *xt, long  
              mdimx, float *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input/output)
On entry, the rows contain the sequences to be transformed. On exit, the quarter-wave cosine synthesis of the input.
- XT (input)
A work array.
- MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input)
On entry, an array of dimension $(2 * N + 15)$ or greater initialized by VCOSQI.

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NAME

`vcosqf` - compute the Fourier coefficients in a cosine series representation with only odd wave numbers. The VCOSQ operations are normalized, so a call of VCOSQF followed by a call of VCOSQB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VCOSQF(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VCOSQF_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQF([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

```
SUBROUTINE COSQF_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vcosqf(int m, int n, float *x, float *xt, int mdimx,  
           float *wsave);
```

```
void vcosqf_64(long m, long n, float *x, float *xt, long  
              mdimx, float *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input/output) On entry, an array of length N containing the sequence to be transformed. For VCOSQF, a real two-dimensional array with dimensions of (MDIMX x N) whose rows contain the sequences to be transformed. On exit, the quarter-wave cosine transform of the input.
- XT (input) A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input) Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input) On entry, an array of dimension $(2 * N + 15)$ or greater initialized by VCOSTI.

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NAME

vcosqi - initialize the array WSAVE, which is used in both VCOSQF and VCOSQB.

SYNOPSIS

```
SUBROUTINE VCOSQI(N, WSAVE)

INTEGER N
REAL WSAVE(*)

SUBROUTINE VCOSQI_64(N, WSAVE)

INTEGER*8 N
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VCOSQI(N, WSAVE)

INTEGER :: N
REAL, DIMENSION(:) :: WSAVE

SUBROUTINE VCOSQI_64(N, WSAVE)

INTEGER(8) :: N
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vcosqi(int n, float *wsave);

void vcosqi_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. The method is most efficient when N is a product of small primes.

WSAVE (input)

On entry, an array of dimension $(2 * N + 15)$ or greater. VCOSQI needs to be called only once to initialize WSAVE before calling VCOSQF and/or VCOSQB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

`vcost` - compute the discrete Fourier cosine transform of an even sequence. The `VCOST` transform is normalized, so a call of `VCOST` followed by a call of `VCOST` will return the original sequence.

SYNOPSIS

```
SUBROUTINE VCOST(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VCOST_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COST([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:, :) :: X, XT
```

```
SUBROUTINE COST_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:, :) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vcost(int m, int n, float *x, float *xt, int mdimx,  
          float *wsave);
```

```
void vcost_64(long m, long n, float *x, float *xt, long  
             mdimx, float *wsave);
```

ARGUMENTS

- M (input)
The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when $N - 1$ is a product of small primes. $N \geq 2$.
- X (input/output)
On entry, an array of length N containing the sequence to be transformed. For VCOST, a real two-dimensional array with dimensions of (MDIMX x (N+1)) whose rows contain the sequences to be transformed. On exit, the cosine transform of the input.
- XT (input)
A real two-dimensional work array with dimensions of (MDIMX x (N-1)).
- MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input)
On entry, an array of dimension $(2 * N + 15)$ or greater initialized by VCOSTI.

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NAME

`vcosti` - initialize the array `WSAVE`, which is used in `VCOST`.

SYNOPSIS

```
SUBROUTINE VCOSTI(N, WSAVE)

INTEGER N
REAL WSAVE(*)

SUBROUTINE VCOSTI_64(N, WSAVE)

INTEGER*8 N
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VCOSTI(N, WSAVE)

INTEGER :: N
REAL, DIMENSION(:) :: WSAVE

SUBROUTINE VCOSTI_64(N, WSAVE)

INTEGER(8) :: N
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vcosti(int n, float *wsave);

void vcosti_64(long n, float *wsave);
```

ARGUMENTS

`N` (input) Length of the sequence to be transformed. The method is most efficient when `N - 1` is a product of small primes. `N >= 2`.

WSAVE (input)

On entry, an array of dimension $(2 * N + 15)$ or greater. VCOSTI is called once to initialize WSAVE before calling VCOST and need not be called again between calls to VCOST if N and WSAVE remain unchanged. Thus, subsequent transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

`vdcosqb` - synthesize a Fourier sequence from its representation in terms of a cosine series with odd wave numbers. The VCOSQ operations are normalized, so a call of VCOSQF followed by a call of VCOSQB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VDCOSQB(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VDCOSQB_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQB([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

```
SUBROUTINE COSQB_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vdcosqb(int m, int n, double *x, double *xt, int mdimx,  
             double *wsave);
```

```
void vdcosqb_64(long m, long n, double *x, double *xt, long  
               mdimx, double *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input/output)
On entry, the rows contain the sequences to be transformed. On exit, the quarter-wave cosine synthesis of the input.
- XT (input)
A work array.
- MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input)
On entry, an array of dimension $(2 * N + 15)$ or greater initialized by VCOSQI.

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NAME

vdcosqf - compute the Fourier coefficients in a cosine series representation with only odd wave numbers. The VCOSQ operations are normalized, so a call of VCOSQF followed by a call of VCOSQB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VDCOSQF(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VDCOSQF_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COSQF([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

```
SUBROUTINE COSQF_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vdcosqf(int m, int n, double *x, double *xt, int mdimx,  
            double *wsave);
```

```
void vdcosqf_64(long m, long n, double *x, double *xt, long  
               mdimx, double *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input/output) On entry, an array of length N containing the sequence to be transformed. For VCOSQF, a real two-dimensional array with dimensions of (MDIMX x N) whose rows contain the sequences to be transformed. On exit, the quarter-wave cosine transform of the input.
- XT (input) A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input) Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input) On entry, an array of dimension $(2 * N + 15)$ or greater initialized by VCOSQI.

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NAME

`vdcosqi` - initialize the array `WSAVE`, which is used in both `VCOSQF` and `VCOSQB`.

SYNOPSIS

```
SUBROUTINE VDCOSQI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE VDCOSQI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VCOSQI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE VCOSQI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vdcosqi(int n, double *wsave);

void vdcosqi_64(long n, double *wsave);
```

ARGUMENTS

`N` (input) Length of the sequence to be transformed. The method is most efficient when `N` is a product of small primes.

WSAVE (input)

On entry, an array of dimension $(2 * N + 15)$ or greater. VDCOSQI needs to be called only once to initialize WSAVE before calling VDCOSQF and/or VDCOSQB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

vdcost - compute the discrete Fourier cosine transform of an even sequence. The VCOST transform is normalized, so a call of VCOST followed by a call of VCOST will return the original sequence.

SYNOPSIS

```
SUBROUTINE VDCOST(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VDCOST_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE COST([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

```
SUBROUTINE COST_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vdcost(int m, int n, double *x, double *xt, int mdimx,  
           double *wsave);
```

```
void vdcost_64(long m, long n, double *x, double *xt, long  
              mdimx, double *wsave);
```

ARGUMENTS

- M (input)
The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when $N - 1$ is a product of small primes. $N \geq 2$.
- X (input/output)
On entry, an array of length N containing the sequence to be transformed. For VCOST, a real two-dimensional array with dimensions of (MDIMX x (N+1)) whose rows contain the sequences to be transformed. On exit, the cosine transform of the input.
- XT (input)
A real two-dimensional work array with dimensions of (MDIMX x (N-1)).
- MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input)
On entry, an array of dimension $(2 * N + 15)$ or greater initialized by VDCOSTI.

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NAME

vdcosti - initialize the array WSAVE, which is used in VCOST.

SYNOPSIS

```
SUBROUTINE VDCOSTI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE VDCOSTI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VCOSTI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE VCOSTI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vdcosti(int n, double *wsave);

void vdcosti_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. The method is most efficient when $N - 1$ is a product of small primes. $N \geq 2$.

WSAVE (input)

On entry, an array of dimension $(2 * N + 15)$ or greater. VDCOSTI is called once to initialize WSAVE before calling VDCOST and need not be called again between calls to VDCOST if N and WSAVE remain unchanged. Thus, subsequent transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

vdfftb - compute a periodic sequence from its Fourier coefficients. The VRFFT operations are normalized, so a call of VRFFT followed by a call of VRFTB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VDFFTB(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VDFFTB_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTB([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

```
SUBROUTINE FFTB_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vdfftb(int m, int n, double *x, double *xt, int mdimx,  
           double *wsave);
```

```
void vdfftb_64(long m, long n, double *x, double *xt, long  
             mdimx, double *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input) On entry, an array of length N containing the sequence to be transformed. For VRFFTF, a real two-dimensional array X(M,N) whose rows contain the sequences to be transformed.
- XT (input)
A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input)
On entry, an array of dimension (N+15) or greater initialized by VRFFTI.

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NAME

vdfftf - compute the Fourier coefficients of a periodic sequence. The VRFFT operations are normalized, so a call of VRFFT followed by a call of VRFTB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VDFFTF(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VDFFTF_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTF([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

```
SUBROUTINE FFTF_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vdfftf(int m, int n, double *x, double *xt, int mdimx,  
           double *wsave);
```

```
void vdfftf_64(long m, long n, double *x, double *xt, long  
             mdimx, double *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input) On entry, an array of length N containing the sequence to be transformed. For VRRFFTF, a real two-dimensional array X(M,N) whose rows contain the sequences to be transformed.
- XT (input) A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input) Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input) On entry, an array of dimension (N+15) or greater initialized by VRRFFTI.

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NAME

vdfffti - initialize the array WSAVE, which is used in both VRFFTF and VRFFTB.

SYNOPSIS

```
SUBROUTINE VDFFTI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE VDFFTI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VFFTI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE VFFTI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vdfffti(int n, double *wsave);

void vdfffti_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array of dimension $(N + 15)$ or greater. VRFFTI needs to be called only once to initialize WSAVE before calling VRFFTF and/or VRFFTB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

`vdsmq` - synthesize a Fourier sequence from its representation in terms of a sine series with odd wave numbers. The `VSMQ` operations are normalized, so a call of `VSMQ` followed by a call of `VSMQ` will return the original sequence.

SYNOPSIS

```
SUBROUTINE VDSINQB(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VDSINQB_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINQB([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

```
SUBROUTINE SINQB_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vdsinqb(int m, int n, double *x, double *xt, int mdimx,  
            double *wsave);
```

```
void vdsinqb_64(long m, long n, double *x, double *xt, long  
              mdimx, double *wsave);
```

ARGUMENTS

- M (input)
The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input/output)
On entry, a real two-dimensional array with dimensions of (MDIMX x N) whose rows contain the sequences to be transformed. On exit, the quarter-wave sine synthesis of the input.
- XT (input)
A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input)
On entry, an array with dimension of at least $(2 * N + 15)$ for vector subroutines, initialized by VSINQI.

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NAME

vdsinqf - compute the Fourier coefficients in a sine series representation with only odd wave numbers. The VSINQ operations are normalized, so a call of VSINQF followed by a call of VSINQB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VDSINQF(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VDSINQF_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINQF([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

```
SUBROUTINE SINQF_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:, :) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vdsinqf(int m, int n, double *x, double *xt, int mdimx,  
            double *wsave);
```

```
void vdsinqf_64(long m, long n, double *x, double *xt, long  
              mdimx, double *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input/output) On entry, an array of length N containing the sequence to be transformed. For VSINQF, a real two-dimensional array with dimensions of (MDIMX x N) whose rows contain the sequences to be transformed. On exit, the quarter-wave sine transform of the input.
- XT (input) A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input) Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input) On entry, an array with dimension of at least $(2 * N + 15)$, initialized by VSINQI.

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NAME

`vdsinqi` - initialize the array `WSAVE`, which is used in both `VSINQF` and `VSINQB`.

SYNOPSIS

```
SUBROUTINE VDSINQI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE VDSINQI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VSINQI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE VSINQI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vdsinqi(int n, double *wsave);

void vdsinqi_64(long n, double *wsave);
```

ARGUMENTS

`N` (input) Length of the sequence to be transformed. The method is most efficient when `N` is a product of small primes.

WSAVE (input)

On entry, an array with a dimension of at least $(2 * N + 15)$. The same work array can be used for both VSINQF and VSINQB as long as N remains unchanged. Different WSAVE arrays are required for different values of N. This initialization does not have to be repeated between calls to VSINQF or VSINQB as long as N and WSAVE remain unchanged, thus subsequent transforms can be obtained faster than the first.

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NAME

vdsint - compute the discrete Fourier sine transform of an odd sequence. The VSINT transforms are unnormalized inverses of themselves, so a call of VSINT followed by another call of VSINT will multiply the input sequence by 2 * (N+1). The VSINT transforms are normalized, so a call of VSINT followed by a call of VSINT will return the original sequence.

SYNOPSIS

```
SUBROUTINE VDSINT(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VDSINT_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
DOUBLE PRECISION X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINT([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:,:) :: X, XT
```

```
SUBROUTINE SINT_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL(8), DIMENSION(:) :: WSAVE  
REAL(8), DIMENSION(:,:) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vdsint(int m, int n, double *x, double *xt, int mdimx,  
           double *wsave);
```

```
void vdsint_64(long m, long n, double *x, double *xt, long  
              mdimx, double *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when $N+1$ is a product of small primes. $N \geq 0$.
- X (input/output) On entry, a real two-dimensional array with dimensions of (MDIMX x (N+1)) whose rows contain the sequences to be transformed. On exit, the sine transform of the input.
- XT (input/output) A real two-dimensional work array with dimensions of (MDIMX x (N+1)).
- MDIMX (input) Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input) On entry, an array with dimension of at least $\text{int}(2.5 * N + 15)$ initialized by VSINTI.

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NAME

vdsinti - initialize the array WSAVE, which is used in sub-routine VSINT.

SYNOPSIS

```
SUBROUTINE VDSINTI(N, WSAVE)

INTEGER N
DOUBLE PRECISION WSAVE(*)

SUBROUTINE VDSINTI_64(N, WSAVE)

INTEGER*8 N
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VSINTI(N, WSAVE)

INTEGER :: N
REAL(8), DIMENSION(:) :: WSAVE

SUBROUTINE VSINTI_64(N, WSAVE)

INTEGER(8) :: N
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vdsinti(int n, double *wsave);

void vdsinti_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array of dimension $(2N + N/2 + 15)$ or greater. VSINTI is called once to initialize WSAVE before calling VSINT and need not be called again between calls to VSINT if N and WSAVE remain unchanged. Thus, subsequent transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

vrfftb - compute a periodic sequence from its Fourier coefficients. The VRFFT operations are normalized, so a call of VRFFTF followed by a call of VRFFTB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VRFFTB(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VRFFTB_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTB([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

```
SUBROUTINE FFTB_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vrfftb(int m, int n, float *x, float *xt, int mdimx,  
           float *wsave);
```

```
void vrfftb_64(long m, long n, float *x, float *xt, long  
              mdimx, float *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input) On entry, an array of length N containing the sequence to be transformed. For VRFFTF, a real two-dimensional array X(M,N) whose rows contain the sequences to be transformed.
- XT (input)
A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input)
On entry, an array of dimension (N+15) or greater initialized by VRFFTI.

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NAME

vrfftf - compute the Fourier coefficients of a periodic sequence. The VRFFT operations are normalized, so a call of VRFFTF followed by a call of VRFFTB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VRFFTF(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VRFFTF_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTF([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

```
SUBROUTINE FFTF_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vrfftf(int m, int n, float *x, float *xt, int mdimx,  
           float *wsave);
```

```
void vrfftf_64(long m, long n, float *x, float *xt, long  
             mdimx, float *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input) On entry, an array of length N containing the sequence to be transformed. For VRRFFTF, a real two-dimensional array X(M,N) whose rows contain the sequences to be transformed.
- XT (input) A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input) Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input) On entry, an array of dimension (N+15) or greater initialized by VRRFFTI.

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vrfffti - initialize the array WSAVE, which is used in both VRFFTF and VRFFTB.

SYNOPSIS

```
SUBROUTINE VRFFTI(N, WSAVE)

INTEGER N
REAL WSAVE(*)

SUBROUTINE VRFFTI_64(N, WSAVE)

INTEGER*8 N
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VFFTI(N, WSAVE)

INTEGER :: N
REAL, DIMENSION(:) :: WSAVE

SUBROUTINE VFFTI_64(N, WSAVE)

INTEGER(8) :: N
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vrffti(int n, float *wsave);

void vrffti_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array of dimension $(N + 15)$ or greater. VRFFTI needs to be called only once to initialize WSAVE before calling VRFFTF and/or VRFFTB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

`vsinqb` - synthesize a Fourier sequence from its representation in terms of a sine series with odd wave numbers. The `VSINQ` operations are normalized, so a call of `VSINQF` followed by a call of `VSINQB` will return the original sequence.

SYNOPSIS

```
SUBROUTINE VSINQB(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VSINQB_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINQB([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

```
SUBROUTINE SINQB_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vsinqb(int m, int n, float *x, float *xt, int mdimx,  
           float *wsave);
```

```
void vsinqb_64(long m, long n, float *x, float *xt, long  
             mdimx, float *wsave);
```

ARGUMENTS

- M (input)
The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input/output)
On entry, a real two-dimensional array with dimensions of (MDIMX x N) whose rows contain the sequences to be transformed. On exit, the quarter-wave sine synthesis of the input.
- XT (input)
A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input)
On entry, an array with dimension of at least $(2 * N + 15)$ for vector subroutines, initialized by VSINQI.

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NAME

vsinqf - compute the Fourier coefficients in a sine series representation with only odd wave numbers. The VSINQ operations are normalized, so a call of VSINQF followed by a call of VSINQB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VSINQF(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VSINQF_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINQF([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

```
SUBROUTINE SINQF_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vsinqf(int m, int n, float *x, float *xt, int mdimx,  
           float *wsave);
```

```
void vsinqf_64(long m, long n, float *x, float *xt, long  
              mdimx, float *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- X (input/output) On entry, an array of length N containing the sequence to be transformed. For VSINQF, a real two-dimensional array with dimensions of (MDIMX x N) whose rows contain the sequences to be transformed. On exit, the quarter-wave sine transform of the input.
- XT (input) A real two-dimensional work array with dimensions of (MDIMX x N).
- MDIMX (input) Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input) On entry, an array with dimension of at least $(2 * N + 15)$, initialized by VSINQI.

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NAME

vsinqi - initialize the array WSAVE, which is used in both VSINQF and VSINQB.

SYNOPSIS

```
SUBROUTINE VSINQI(N, WSAVE)

INTEGER N
REAL WSAVE(*)

SUBROUTINE VSINQI_64(N, WSAVE)

INTEGER*8 N
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VSINQI(N, WSAVE)

INTEGER :: N
REAL, DIMENSION(:) :: WSAVE

SUBROUTINE VSINQI_64(N, WSAVE)

INTEGER(8) :: N
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vsinqi(int n, float *wsave);

void vsinqi_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. The method is most efficient when N is a product of small primes.

WSAVE (input)

On entry, an array with a dimension of at least $(2 * N + 15)$. The same work array can be used for both VSINQF and VSINQB as long as N remains unchanged. Different WSAVE arrays are required for different values of N. This initialization does not have to be repeated between calls to VSINQF or VSINQB as long as N and WSAVE remain unchanged, thus subsequent transforms can be obtained faster than the first.

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NAME

vsint - compute the discrete Fourier sine transform of an odd sequence. The VSINT transforms are unnormalized inverses of themselves, so a call of VSINT followed by another call of VSINT will multiply the input sequence by 2 * (N+1). The VSINT transforms are normalized, so a call of VSINT followed by a call of VSINT will return the original sequence.

SYNOPSIS

```
SUBROUTINE VSINT(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

```
SUBROUTINE VSINT_64(M, N, X, XT, MDIMX, WSAVE)
```

```
INTEGER*8 M, N, MDIMX  
REAL X(MDIMX,*), XT(MDIMX,*), WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE SINT([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

```
SUBROUTINE SINT_64([M], [N], X, XT, [MDIMX], WSAVE)
```

```
INTEGER(8) :: M, N, MDIMX  
REAL, DIMENSION(:) :: WSAVE  
REAL, DIMENSION(:,) :: X, XT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vsint(int m, int n, float *x, float *xt, int mdimx,  
          float *wsave);
```

```
void vsint_64(long m, long n, float *x, float *xt, long  
             mdimx, float *wsave);
```

ARGUMENTS

- M (input) The number of sequences to be transformed. $M \geq 0$.
- N (input) Length of the sequence to be transformed. These subroutines are most efficient when $N+1$ is a product of small primes. $N \geq 0$.
- X (input/output) On entry, a real two-dimensional array with dimensions of (MDIMX x (N+1)) whose rows contain the sequences to be transformed. On exit, the sine transform of the input.
- XT (input/output) A real two-dimensional work array with dimensions of (MDIMX x (N+1)).
- MDIMX (input) Leading dimension of the arrays X and XT as specified in a dimension or type statement. $MDIMX \geq M$.
- WSAVE (input) On entry, an array with dimension of at least $\text{int}(2.5 * N + 15)$ initialized by VSINTI.

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NAME

vsinti - initialize the array WSAVE, which is used in sub-routine VSINT.

SYNOPSIS

```
SUBROUTINE VSINTI(N, WSAVE)

INTEGER N
REAL WSAVE(*)

SUBROUTINE VSINTI_64(N, WSAVE)

INTEGER*8 N
REAL WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE VSINTI(N, WSAVE)

INTEGER :: N
REAL, DIMENSION(:) :: WSAVE

SUBROUTINE VSINTI_64(N, WSAVE)

INTEGER(8) :: N
REAL, DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>

void vsinti(int n, float *wsave);

void vsinti_64(long n, float *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array of dimension $(2N + N/2 + 15)$ or greater. VSINTI is called once to initialize WSAVE before calling VSINT and need not be called again between calls to VSINT if N and WSAVE remain unchanged. Thus, subsequent transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

vzfftb - compute a periodic sequence from its Fourier coefficients. The VZFFT operations are normalized, so a call of VZFFTF followed by a call of VZFFTB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VZFFTB(M, N, X, XT, MDIMX, ROWCOL, WSAVE)
```

```
CHARACTER * 1 ROWCOL  
DOUBLE COMPLEX X(MDIMX,*), XT(MDIMX,*), WSAVE(*)  
INTEGER M, N, MDIMX
```

```
SUBROUTINE VZFFTB_64(M, N, X, XT, MDIMX, ROWCOL, WSAVE)
```

```
CHARACTER * 1 ROWCOL  
DOUBLE COMPLEX X(MDIMX,*), XT(MDIMX,*), WSAVE(*)  
INTEGER*8 M, N, MDIMX
```

F95 INTERFACE

```
SUBROUTINE FFTB([M], [N], X, XT, [MDIMX], ROWCOL, WSAVE)
```

```
CHARACTER(LEN=1) :: ROWCOL  
COMPLEX(8), DIMENSION(:) :: WSAVE  
COMPLEX(8), DIMENSION(:, :) :: X, XT  
INTEGER :: M, N, MDIMX
```

```
SUBROUTINE FFTB_64([M], [N], X, XT, [MDIMX], ROWCOL, WSAVE)
```

```
CHARACTER(LEN=1) :: ROWCOL  
COMPLEX(8), DIMENSION(:) :: WSAVE  
COMPLEX(8), DIMENSION(:, :) :: X, XT  
INTEGER(8) :: M, N, MDIMX
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vzfftb(int m, int n, doublecomplex *x, doublecomplex  
            *xt, int mdimx, char rowcol, doublecomplex  
            *wsave);
```

```
void vzfftb_64(long m, long n, doublecomplex *x, doublecomplex *xt, long mdimx, char rowcol, doublecomplex *wsave);
```

ARGUMENTS

M (input) The number of sequences to be transformed. M \geq 0.

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. N \geq 0.

X (input) On entry, the rows contain the sequences to be transformed.

XT (input)
A work array.

MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. MDIMX \geq M.

ROWCOL (input)
Indicates whether to transform rows ('R' or 'r') or columns ('C' or 'c').

WSAVE (input/output)
On entry, an array of dimension (K+15) or greater, where K = M if ROWCOL = ('R' or 'r'). Otherwise, K = N. WSAVE is initialized by VZFFTI.

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NAME

vzfftf - compute the Fourier coefficients of a periodic sequence. The VZFFT operations are normalized, so a call of VZFFTF followed by a call of VZFFTB will return the original sequence.

SYNOPSIS

```
SUBROUTINE VZFFTF(M, N, X, XT, MDIMX, ROWCOL, WSAVE)
```

```
CHARACTER * 1 ROWCOL  
DOUBLE COMPLEX X(MDIMX,*), XT(MDIMX,*), WSAVE(*)  
INTEGER M, N, MDIMX
```

```
SUBROUTINE VZFFTF_64(M, N, X, XT, MDIMX, ROWCOL, WSAVE)
```

```
CHARACTER * 1 ROWCOL  
DOUBLE COMPLEX X(MDIMX,*), XT(MDIMX,*), WSAVE(*)  
INTEGER*8 M, N, MDIMX
```

F95 INTERFACE

```
SUBROUTINE F95_VZFFTF([M], [N], X, XT, [MDIMX], ROWCOL, WSAVE)
```

```
CHARACTER(LEN=1) :: ROWCOL  
COMPLEX(8), DIMENSION(:) :: WSAVE  
COMPLEX(8), DIMENSION(:,:) :: X, XT  
INTEGER :: M, N, MDIMX
```

```
SUBROUTINE F95_VZFFTF_64([M], [N], X, XT, [MDIMX], ROWCOL, WSAVE)
```

```
CHARACTER(LEN=1) :: ROWCOL  
COMPLEX(8), DIMENSION(:) :: WSAVE  
COMPLEX(8), DIMENSION(:,:) :: X, XT  
INTEGER(8) :: M, N, MDIMX
```

C INTERFACE

```
#include <sunperf.h>
```

```
void vzfftf(int m, int n, doublecomplex *x, doublecomplex  
           *xt, int mdimx, char rowcol, doublecomplex  
           *wsave);
```

```
void vzfft64(long m, long n, doublecomplex *x, doublecomplex *xt, long mdimx, char rowcol, doublecomplex *wsave);
```

ARGUMENTS

M (input) The number of sequences to be transformed. M \geq 0.

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. N \geq 0.

X (input) On entry, an array X(M,N) whose rows contain the sequences to be transformed.

XT (input)
A work array.

MDIMX (input)
Leading dimension of the arrays X and XT as specified in a dimension or type statement. MDIMX \geq M.

ROWCOL (input)
Indicates whether to transform rows ('R' or 'r') or columns ('C' or 'c').

WSAVE (input/output)
On entry, an array of dimension (K+15) or greater, where K = M if ROWCOL = ('R' or 'r'). Otherwise, K = N. WSAVE is initialized by VZFFTI.

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NAME

vzfffti - initialize the array WSAVE, which is used in both VZFFTF and VZFFTB.

SYNOPSIS

```
SUBROUTINE VZFFTI(N, WSAVE)

DOUBLE COMPLEX WSAVE(*)
INTEGER N

SUBROUTINE VZFFTI_64(N, WSAVE)

DOUBLE COMPLEX WSAVE(*)
INTEGER*8 N
```

F95 INTERFACE

```
SUBROUTINE VFFTI(N, WSAVE)

COMPLEX(8), DIMENSION(:) :: WSAVE
INTEGER :: N

SUBROUTINE VFFTI_64(N, WSAVE)

COMPLEX(8), DIMENSION(:) :: WSAVE
INTEGER(8) :: N
```

C INTERFACE

```
#include <sunperf.h>

void vzfffti(int n, doublecomplex *wsave);

void vzfffti_64(long n, doublecomplex *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input)

On entry, an array of dimension $(N + 15)$ or greater. VZFFTI needs to be called only once to initialize WSAVE before calling VZFFTF and/or VZFFTB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

zaxpy - compute $y := \alpha * x + y$

SYNOPSIS

```
SUBROUTINE ZAXPY(N, ALPHA, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE ZAXPY_64(N, ALPHA, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE AXPY([N], ALPHA, X, [INCX], Y, [INCY])
```

```
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE AXPY_64([N], ALPHA, X, [INCX], Y, [INCY])
```

```
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zaxpy(int n, doublecomplex *alpha, doublecomplex *x,  
          int incx, doublecomplex *y, int incy);
```

```
void zaxpy_64(long n, doublecomplex *alpha, doublecomplex  
             *x, long incx, doublecomplex *y, long incy);
```

PURPOSE

zaxpy compute $y := \alpha * x + y$ where alpha is a scalar and x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

array of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input/output)

array of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$. On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

zaxpyi - Compute $y := \alpha * x + y$

SYNOPSIS

```
SUBROUTINE ZAXPYI(NZ, A, X, INDX, Y)
```

```
DOUBLE COMPLEX A  
DOUBLE COMPLEX X(*), Y(*)  
INTEGER NZ  
INTEGER INDX(*)
```

```
SUBROUTINE ZAXPYI_64(NZ, A, X, INDX, Y)
```

```
DOUBLE COMPLEX A  
DOUBLE COMPLEX X(*), Y(*)  
INTEGER*8 NZ  
INTEGER*8 INDX(*)
```

```
F95 INTERFACE
```

```
SUBROUTINE AXPYI([NZ], [A], X, INDX, Y)
```

```
COMPLEX(8) :: A  
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER :: NZ  
INTEGER, DIMENSION(:) :: INDX
```

```
SUBROUTINE AXPYI_64([NZ], [A], X, INDX, Y)
```

```
COMPLEX(8) :: A  
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: NZ  
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

ZAXPYI Compute $y := \alpha * x + y$ where α is a scalar, x is a sparse vector, and y is a vector in full storage form

```
do i = 1, n  
  y(indx(i)) = alpha * x(i) + y(indx(i))
```

enddo

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.

Unchanged on exit.

A (input)

On entry, A(LPHA) specifies the scaling value.

Unchanged on exit. A is defaulted to (1.0D0,0.0D0)

for F95 INTERFACE.

X (input)

Vector containing the values of the compressed form.

Unchanged on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed

form. It is assumed that the elements in INDX are

distinct and greater than zero. Unchanged on exit.

Y (output)

Vector on input which contains the vector Y in full

storage form. On exit, only the elements

corresponding to the indices in INDX have been

modified.

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NAME

zbcmm - block coordinate matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZBCOMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
* VAL, BINDX, BJNDX, BNNZ, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER TRANSA, MB, N, KB, DESCRA(5), BNNZ, LB,  
* LDB, LDC, LWORK  
INTEGER BINDX(BNNZ), BJNDX(BNNZ)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZBCOMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
* VAL, BINDX, BJNDX, BNNZ, LB,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8 TRANSA, MB, N, KB, DESCRA(5), BNNZ, LB,  
* LDB, LDC, LWORK  
INTEGER*8 BINDX(BNNZ), BJNDX(BNNZ)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BCOMM(TRANSA,MB,[N],KB,ALPHA,DESCRA,VAL,BINDX, BJNDX,  
* BNNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER TRANSA, MB, N, KB, BNNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BJNDX  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BCOMM_64(TRANSA,MB,[N],KB,ALPHA,DESCRA,VAL,BINDX, BJNDX,  
* BNNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, MB, N, KB, BNNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BJNDX  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void zbcomm(int transa, int mb, int n, int kb, doublecomplex
*alpha, int *descra, doublecomplex *val, int *bindx, int
*bjndx, int bnnz, int lb,
doublecomplex *b, int ldb, doublecomplex *beta,
doublecomplex *c, int ldc);
void zbcomm_64(long transa, long mb, long n, long kb,
complex *alpha, long *descra, doublecomplex *val, long
*bindx, long *bjndx, long bnnz, long lb, doublecomplex *b,
long ldb,
doublecomplex *beta, doublecomplex *c, long ldc);
```

DESCRIPTION

cbcomm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an (mb*lb) by (kb*lb) sparse matrix represented in the block coordinate format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')

```

5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input)      On entry, scalar array of length LB*LB*BNNZ consisting of
                 the non-zero block entries of A, in any order.
                 Each block is stored in standard column-major form.
                 Unchanged on exit.

BINDX(input)    On entry, integer array of length BNNZ consisting of the
                 block row indices of the non-zero block entries of A.
                 Unchanged on exit.

BJNDX(input)    On entry, integer array of length BNNZ consisting of the
                 block column indices of the non-zero block entries of A.
                 Unchanged on exit.

BNNZ (input)    On entry, BNNZ specifies the number of nonzero block
                 entries in A. Unchanged on exit.

LB (input)      On entry, LB specifies the dimension of dense blocks
                 composing A. Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading kb*lb by n
                 part of the array B must contain the matrix B, otherwise
                 the leading mb*lb by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading mb*lb by n
                 part of the array C must contain the matrix C, otherwise
                 the leading kb*lb by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta*C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

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NAME

zbdimm - block diagonal format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZBDIMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), BLDA, NBDIAG, LB,  
*                LDB, LDC, LWORK  
INTEGER          IBDIAG(NBDIAG)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LB*LB*BLDA*NBDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZBDIMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), BLDA, NBDIAG, LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        IBDIAG(NBDIAG)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LB*LB*BLDA*NBDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BDIMM(TRANSA,MB, [N], KB, ALPHA, DESCRA, VAL, BLDA,  
*  IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, BLDA, NBDIAG, LB  
INTEGER, DIMENSION(:) ::  DESCRA, IBDIAG  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BDIMM_64(TRANSA,MB, [N], KB, ALPHA, DESCRA, VAL, BLDA,  
*  IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, BLDA, NBDIAG, LB  
INTEGER*8, DIMENSION(:) ::  DESCRA, IBDIAG  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void zbdimm (int transa, int mb, int n, int kb,
doublecomplex *alpha,
int *descra, doublecomplex *val, int blda, int *ibdiag, int
nbdia, int lb, doublecomplex *b, int ldb, doublecomplex
*beta, doublecomplex *c, int ldc);
void zbdimm_64(long transa, long mb, long n, long kb,
doublecomplex *alpha, long *descra, doublecomplex *val,
long blda,
long *ibdiag, long nbdia, long lb, doublecomplex *b, long
ldb,
doublecomplex *beta, doublecomplex *c, long ldc)
```

DESCRIPTION

zbdimm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),
A is an (mb*lb) by (kb*lb) sparse matrix represented in the block
coordinate format, alpha and beta are scalars, C and B are dense
matrices.

ARGUMENTS

TRANSA(input) TRANSA specifies the form of $\operatorname{op}(A)$ to be used in
the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows
in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns
in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in
the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular

```

    4 : Skew(Anti)-Symmetric (A=-A')
    5 : Diagonal
    6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
    1 : lower
    2 : upper
DESCRA(3) main block diagonal type
    0 : non-unit
    1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
    0 : C/C++ compatible
    1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
    0 : unknown
    1 : no repeated indices

VAL(input)      On entry, two-dimensional LB*LB*BLDA-by-NBDIAG scalar array
                  consisting of the NBDIAG nonzero block diagonal in
                  any order. Each dense block is stored in standard
                  column-major form. Unchanged on exit.

BLDA(input)     On entry, BLDA*LB*LB specifies the leading block dimension
                  of VAL(). Unchanged on exit.

IBDIAG(input)  On entry, integer array of length NBDIAG consisting of the
                  corresponding diagonal offsets of the non-zero
                  block diagonals of A in VAL. Lower triangular
                  block diagonals have negative offsets, the main
                  block diagonal has offset 0, and upper triangular
                  block diagonals have positive offset. Unchanged on exit.

NBDIAG(input)  On entry, NBDIAG specifies the number of non-zero block
                  diagonals in A. Unchanged on exit.

LB (input)     On entry, LB specifies the dimension of dense blocks
                  composing A. Unchanged on exit.

B (input)      Array of DIMENSION ( LDB, N ).
                  Before entry with TRANSA = 0, the leading kb*lb by n
                  part of the array B must contain the matrix B, otherwise
                  the leading mb*lb by n part of the array B must contain the
                  matrix B. Unchanged on exit.

LDB (input)    On entry, LDB specifies the first dimension of B as declared
                  in the calling (sub) program. Unchanged on exit.

BETA (input)   On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION ( LDC, N ).
                  Before entry with TRANSA = 0, the leading mb*lb by n
                  part of the array C must contain the matrix C, otherwise
                  the leading kb*lb by n part of the array C must contain the
                  matrix C. On exit, the array C is overwritten by the matrix
                  ( alpha*op( A ) * B + beta*C ).

LDC (input)    On entry, LDC specifies the first dimension of C as declared
                  in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

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NAME

zbdism - block diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE ZBDISM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*               VAL, BLDA, IBDIAG, NBDIAG, LB,  
*               B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER        TRANSA, MB, N, UNITD, DESCRA(5), BLDA, NBDIAG, LB,  
*               LDB, LDC, LWORK  
INTEGER        IBDIAG(NBDIAG)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX DV(MB*LB*LB), VAL(LB*LB*BLDA, NBDIAG), B(LDB,*), C(LDC,*),  
*               WORK(LWORK)
```

```
SUBROUTINE ZBDISM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BLDA, IBDIAG, NBDIAG, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8       TRANSA, MB, N, UNITD, DESCRA(5), BLDA, NBDIAG, LB,  
*               LDB, LDC, LWORK  
INTEGER*8       IBDIAG(NBDIAG)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX DV(MB*LB*LB), VAL(LB*LB*BLDA, NBDIAG), B(LDB,*), C(LDC,*),  
*               WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BDISM( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BLDA,  
*               IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, N, UNITD, BLDA, NBDIAG, LB  
INTEGER, DIMENSION(:) :: DESCRA, IBDIAG  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BDISM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BLDA,  
*                   IBDIAG, NBDIAG, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8       TRANSA, MB, N, UNITD, BLDA, NBDIAG, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, IBDIAG  
DOUBLE COMPLEX ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void zbdism (int transa, int mb, int n, int unitd,
doublecomplex *dv, doublecomplex *alpha, int *descra,
doublecomplex *val, int blda, int *ibdiag, int nbdiag, int
lb, doublecomplex *b, int ldb, doublecomplex *beta,
doublecomplex *c, int ldc);

void zbdism_64(long transa, long mb, long n, long unitd,
complex *dv, doublecomplex *alpha, long *descra,
doublecomplex *val, long blda, long *ibdiag, long nbdiag,
long lb, doublecomplex *b, long ldb, doublecomplex *beta,
doublecomplex *c, long ldc)
```

DESCRIPTION

zbdism performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose)
```

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix A. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) Unchanged on exit.
DV(input)	On entry, DV is an array of length MB*LB*LB consisting

of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-identity blocks on the main diagonal
1 : identity diagonal blocks
2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-NBDIAG array consisting of the NBDIAG non-zero block diagonal. Each dense block is stored in standard column-major form. Unchanged on exit.

BLDA(input) On entry, BLDA*LB*LB specifies the leading block dimension of VAL(). Unchanged on exit.

IBDIAG(input) On entry, IBDIAG is an integer array of length NBDIAG consisting of corresponding diagonal offsets of the non-zero block diagonals of A in VAL. Lower triangular block diagonals have negative offsets, the main block diagonal has offset 0, and upper triangular block diagonals have positive offset. Elements of IBDIAG MUST be sorted in increasing order. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading mb*lb by n part of the array C

must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least MB*LB.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, $LWORK \geq MB*LB*N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If `DESCRA(3)=0` , the lower or upper triangular part of each diagonal block is used by the routine depending on `DESCRA(2)` .
3. If `DESCRA(3)=1` , the diagonal blocks in the block diagonal representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If `DESCRA(3)=2` , diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is

used by the routine.

`WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix `A` for solving triangular systems with the upper or lower block triangle of `A`. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix `A` decomposed in the form

$$A = L + D + U$$

where `L` is the strictly block lower triangle of `A`, `U` is the strictly block upper triangle of `A`, `D` is the block diagonal matrix. Let's `I` denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of `A` is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

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NAME

zbdsql - compute the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B.

SYNOPSIS

```
SUBROUTINE ZBDSQR(UPLO, N, NCVT, NRU, NCC, D, E, VT, LDVT, U, LDU, C,  
LDC, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX VT(LDVT,*), U(LDU,*), C(LDC,*)  
INTEGER N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO  
DOUBLE PRECISION D(*), E(*), WORK(*)
```

```
SUBROUTINE ZBDSQR_64(UPLO, N, NCVT, NRU, NCC, D, E, VT, LDVT, U, LDU,  
C, LDC, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX VT(LDVT,*), U(LDU,*), C(LDC,*)  
INTEGER*8 N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO  
DOUBLE PRECISION D(*), E(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE BDSQR(UPLO, [N], [NCVT], [NRU], [NCC], D, E, VT, [LDVT],  
U, [LDU], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: VT, U, C  
INTEGER :: N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK
```

```
SUBROUTINE BDSQR_64(UPLO, [N], [NCVT], [NRU], [NCC], D, E, VT, [LDVT],  
U, [LDU], C, [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: VT, U, C  
INTEGER(8) :: N, NCVT, NRU, NCC, LDVT, LDU, LDC, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zbdsqr(char uplo, int n, int ncvt, int nru, int ncc,
            double *d, double *e, doublecomplex *vt, int ldvt,
            doublecomplex *u, int ldu, doublecomplex *c, int
            ldc, int *info);
void zbdsqr_64(char uplo, long n, long ncvt, long nru, long
               ncc, double *d, double *e, doublecomplex *vt, long
               ldvt, doublecomplex *u, long ldu, doublecomplex
               *c, long ldc, long *info);

```

PURPOSE

zbdsqr computes the singular value decomposition (SVD) of a real N-by-N (upper or lower) bidiagonal matrix B: $B = Q * S * P'$ (P' denotes the transpose of P), where S is a diagonal matrix with non-negative diagonal elements (the singular values of B), and Q and P are orthogonal matrices.

The routine computes S, and optionally computes $U * Q$, $P' * VT$, or $Q' * C$, for given complex input matrices U, VT, and C.

See "Computing Small Singular Values of Bidiagonal Matrices With Guaranteed High Relative Accuracy," by J. Demmel and W. Kahan, LAPACK Working Note #3 (or SIAM J. Sci. Statist. Comput. vol. 11, no. 5, pp. 873-912, Sept 1990) and "Accurate singular values and differential qd algorithms," by B. Parlett and V. Fernando, Technical Report CPAM-554, Mathematics Department, University of California at Berkeley, July 1992 for a detailed description of the algorithm.

ARGUMENTS

UPLO (input)

= 'U': B is upper bidiagonal;
 = 'L': B is lower bidiagonal.

N (input) The order of the matrix B. $N \geq 0$.

NCVT (input)

The number of columns of the matrix VT. $NCVT \geq 0$.

NRU (input)

The number of rows of the matrix U. $NRU \geq 0$.

NCC (input)

The number of columns of the matrix C. $NCC \geq 0$.

D (input/output)

On entry, the n diagonal elements of the bidiagonal matrix B. On exit, if INFO=0, the singular values of B in decreasing order.

E (input/output)

On entry, the elements of E contain the offdiagonal elements of the bidiagonal matrix whose SVD

is desired. On normal exit (INFO = 0), E is destroyed. If the algorithm does not converge (INFO > 0), D and E will contain the diagonal and super-diagonal elements of a bidiagonal matrix orthogonally equivalent to the one given as input. E(N) is used for workspace.

VT (input/output)

On entry, an N-by-NCVT matrix VT. On exit, VT is overwritten by $P' * VT$. VT is not referenced if NCVT = 0.

LDVT (input)

The leading dimension of the array VT. LDVT \geq max(1,N) if NCVT > 0; LDVT \geq 1 if NCVT = 0.

U (input/output)

On entry, an NRU-by-N matrix U. On exit, U is overwritten by $U * Q$. U is not referenced if NRU = 0.

LDU (input)

The leading dimension of the array U. LDU \geq max(1,NRU).

C (input/output)

On entry, an N-by-NCC matrix C. On exit, C is overwritten by $Q' * C$. C is not referenced if NCC = 0.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,N) if NCC > 0; LDC \geq 1 if NCC = 0.

WORK (workspace)

dimension (4*N)

INFO (output)

= 0: successful exit
< 0: If INFO = -i, the i-th argument had an illegal value
> 0: the algorithm did not converge; D and E contain the elements of a bidiagonal matrix which is orthogonally similar to the input matrix B; if INFO = i, i elements of E have not converged to zero.

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NAME

zbelmm - block Ellpack format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZBELMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BLDA, MAXBNZ, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), BLDA, MAXBNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BLDA,MAXBNZ)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZBELMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BLDA, MAXBNZ, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), BLDA, MAXBNZ, LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BLDA,MAXBNZ)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BELMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                BLDA, MAXBNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, BLDA, MAXBNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BELMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BLDA, MAXBNZ, LB, B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, BLDA, MAXBNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void zbelmm(int transa, int mb, int n, int kb,
  doublecomplex *alpha, int *descra, doublecomplex *val,
  int *bindx, int blda, int maxbnz, int lb, doublecomplex *b,
  int ldb, doublecomplex *beta, doublecomplex *c, int ldc);
void zbelmm_64(long transa, long mb, long n, long kb,
  doublecomplex *alpha, long *descra, doublecomplex *val, long
  *bindx, long blda, long maxbnz, long lb, doublecomplex *b,
  long ldb, doublecomplex *beta, doublecomplex *c, long ldc);
```

DESCRIPTION

zbelmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in block Ellpack format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input) TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows:
 0 : operate with matrix
 1 : operate with transpose matrix
 2 : operate with the conjugate transpose of matrix.
 2 is equivalent to 1 if matrix is real.
 Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
 0 : general
 1 : symmetric (A=A')
 2 : Hermitian (A= CONJG(A'))
 3 : Triangular
 4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator

1 : lower
 2 : upper
 DESCRA(3) main block diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-MAXBNZ array consisting of the non-zero blocks, stored column-major within each dense block. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer two-dimensional BLDA-MAXBNZ array such BINDX(i,:) consists of the block column indices of the nonzero blocks in block row i, padded by the integer value i if the number of nonzero blocks is less than MAXBNZ. Unchanged on exit.

BLDA(input) On entry, BLDA specifies the leading dimension of BINDX(:,:). Unchanged on exit.

MAXBNZ (input) On entry, MAXBNZ specifies the max number of nonzeros blocks per row. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading kb*lb by n part of the array B must contain the matrix B, otherwise the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading mb*lb by n part of the array C must contain the matrix C, otherwise the leading kb*lb by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \text{beta} * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

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NAME

zbelism - block Ellpack format triangular solve

SYNOPSIS

```
SUBROUTINE ZBELSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BLDA, MAXBNZ, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), BLDA, MAXBNZ, LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BLDA,MAXBNZ)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  DV(MB*LB*LB), VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*),  
*                WORK(LWORK)
```

```
SUBROUTINE ZBELSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BLDA, MAXBNZ, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), BLDA, MAXBNZ, LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BLDA,MAXBNZ)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  DV(MB*LB*LB), VAL(LB*LB*BLDA*MAXBNZ), B(LDB,*), C(LDC,*),  
*                   WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE BELSM( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*               BLDA, MAXBNZ, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, UNITD, BLDA, MAXBNZ, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BELSM_64( TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                   BLDA, MAXBNZ, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, UNITD, BLDA, MAXBNZ, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX  
DOUBLE COMPLEX  ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zbelism(int transa, int mb, int n, int unitd,
doublecomplex *dv, doublecomplex *alpha, int *descra,
doublecomplex *val,
int *bindx, int blda, int maxbnz, int lb, doublecomplex *b,
int ldb, doublecomplex *beta, doublecomplex *c, int ldc);
```

```
void zbelism_64(long transa, long mb, long n, long unitd,
doublecomplex *dv, doublecomplex *alpha, long *descra,
doublecomplex *val, long *bindx, long blda, long maxbnz,
long lb, doublecomplex *b, long ldb, doublecomplex *beta,
doublecomplex *c, long ldc);
```

DESCRIPTION

zbelism performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block ellpack format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	Integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, integer UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) Unchanged on exit.
DV(input)	On entry, DV is an array of length MB*LB*LB consisting

of the elements of the diagonal blocks of the matrix D.
The size of each square block is LB-by-LB and each
block is stored in standard column-major form.
Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-identity blocks on the main diagonal
1 : identity diagonal blocks
2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LB*LB*BLDA-by-MAXBNZ
array consisting of the non-zero blocks, stored
column-major within each dense block. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer two-dimensional BLDA-MAXBNZ
array such BINDX(i,:) consists of the block column indices
of the nonzero blocks in block row i, padded by the integer
value i if the number of nonzero blocks is less than MAXBNZ.
The block column indices MUST be sorted in increasing order
for each block row. Unchanged on exit.

BLDA(input) On entry, BLDA specifies the leading dimension of BINDX(:,:).
Unchanged on exit.

MAXBNZ (input) On entry, MAXBNZ specifies the max number of nonzeros
blocks per row. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks
composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).

On entry, the leading $mb*lb$ by n part of the array C must contain the matrix C . On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least $MB*LB$.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, $LWORK \geq MB*LB*N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If $DESCRA(3)=0$, the lower or upper triangular part of each diagonal block is used by the routine depending on $DESCRA(2)$.
3. If $DESCRA(3)=1$, the diagonal blocks in the block ellpack representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If $DESCRA(3)=2$, diagonal blocks are considered as dense

matrices and the LU factorization with partial pivoting is used by the routine.

`WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix `A` for solving triangular systems with the upper or lower block triangle of `A`. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix `A` decomposed in the form

$$A = L + D + U$$

where `L` is the strictly block lower triangle of `A`, `U` is the strictly block upper triangle of `A`, `D` is the block diagonal matrix. Let's `I` denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of `A` is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

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NAME

zbscmm - block sparse column matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZBSCMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(KB), BPNTRE(KB)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZBSCMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(KB), BPNTRE(KB)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(KB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSCMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*               BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSCMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE COMPLEX  ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void zbscmm(int transa, int mb, int n, int kb,
  doublecomplex *alpha, int *descra, doublecomplex *val,
  int *bindx, int *bpntrb, int *bpntre, int lb, doublecomplex
*b,
  int ldb, doublecomplex *beta, doublecomplex* c, int ldc);

void zbscmm_64(long transa, long mb, long n, long kb,
  doublecomplex *alpha, long *descra, doublecomplex *val, long
*bindx, long *bpntrb, long *bpntre, long lb, doublecomplex
*b, long ldb, doublecomplex *beta, doublecomplex *c, long
ldc);
```

DESCRIPTION

zbscmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in the block sparse column format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
KB(input)	On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A'))

```

3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array of length LB*LB*BNNZ
                 consisting of the non-zero block entries stored
                 column-major within each dense block where
                 BNNZ = BPNTRE(KB)-BPNTRB(1). Unchanged on exit.

BINDX(input)    On entry, BINDX is an integer array of length BNNZ consisting
                 of the block row indices of the block entries of A where
                 BNNZ = BPNTRE(KB)-BPNTRB(1). Unchanged on exit.

BPNTRB(input)   On entry, BPNTRB is an integer array of length KB such
                 that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX
                 of the first block entry of the J-th block column
                 of A. Unchanged on exit.

BPNTRE(input)   On entry, BPNTRE is an integer array of length KB such
                 that BPNTRE(J)-BPNTRB(1) points to location in BINDX
                 of the last block entry of the J-th block column
                 of A. Unchanged on exit.

LB (input)      On entry, LB specifies the dimension of dense blocks
                 composing A. Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading kb*lb by n
                 part of the array B must contain the matrix B, otherwise
                 the leading mb*lb by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading mb*lb by n
                 part of the array C must contain the matrix C, otherwise
                 the leading kb*lb by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta * C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

```

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

NOTES/BUGS

It is known that there exists another representation of the block sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block column in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse column format the following calling sequence should be used

```
CALL ZBSCMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*           VAL, BINDX, IA, IA(2), LB,  
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

zbscsm - block sparse column format triangular solve

SYNOPSIS

```
SUBROUTINE ZBSCSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZBSCSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB) - BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSCSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*              BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, N, UNITD, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSCSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                  BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, N, UNITD, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE COMPLEX ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zbscsm(int transa, int mb, int n, int unitd,
doublecomplex *dv, doublecomplex *alpha, int *descra,
doublecomplex *val,
int *bindx, int *bpntrb, int *bpntre, int lb, doublecomplex
*b,
int ldb, doublecomplex *beta, doublecomplex* c, int ldc);
```

```
void zbscsm_64(long transa, long mb, long n, long unitd,
doublecomplex *dv, doublecomplex *alpha, long *descra,
doublecomplex *val, long *bindx, long *bpntrb, long *bpntre,
long lb, doublecomplex *b, long ldb, doublecomplex *beta,
doublecomplex *c, long ldc);
```

DESCRIPTION

zbscsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block sparse column format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block columns in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, integer UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-identity blocks on the main diagonal
1 : identity diagonal blocks
2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ consisting of the non-zero block entries stored column-major within each dense block where BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block row indices of the block entries of A where BNNZ = BPNTRE(MB)-BPNTRB(1). The block row indices MUST be sorted in increasing order for each block column. Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the J-th block column of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(J)-BPNTRB(1) points to location in BINDX of the last block entry of the J-th block column of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared

in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading $mb*lb$ by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least $MB*LB$.

For good performance, LWORK should generally be larger.
For optimum performance on multiple processors, LWORK $\geq MB*LB*N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:
<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If `DESCRA(3)=0` , the lower or upper triangular part of each diagonal block is used by the routine depending on `DESCRA(2)` .
3. If `DESCRA(3)=1` , the diagonal blocks in the block sparse

column representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.

4. If `DESCRA(3)=2` , the diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

6. It is known that there exists another representation of the block sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block column in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse column format the following calling sequence should be used

```
CALL ZBSCSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*           VAL, BINDX, IA, IA(2), LB,
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

zbsrmm - block sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZBSRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, KB, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZBSRMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, KB, DESCRA(5), LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSRMM( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*               BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, MB, KB, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE BSRMM_64( TRANSA, MB, [N], KB, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, MB, KB, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE COMPLEX  ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void zbsrmm(int transa, int mb, int n, int kb,
doublecomplex *alpha, int *descra, doublecomplex *val,
int *bindx, int *bpntrb, int *bpntre, int lb, doublecomplex
*b,
int ldb, doublecomplex *beta, doublecomplex* c, int ldc);

void zbsrmm_64(long transa, long mb, long n, long kb,
doublecomplex *alpha, long *descra, doublecomplex *val, long
*bindx, long *bpntrb, long *bpntre, long lb, doublecomplex
*b, long ldb, doublecomplex *beta, doublecomplex *c, long
ldc);
```

DESCRIPTION

zbsrmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is an (mb*lb) by (kb*lb) sparse matrix represented in the block sparse row format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

ARGUMENTS

TRANSA(input) TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))

```

3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array of length LB*LB*BNNZ
                  consisting of the non-zero block entries stored
                  column-major within each dense block where
                  BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input)    On entry, BINDX is an integer array of length BNNZ consisting
                  of the block column indices of the block entries of A where
                  BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BPNTRB(input)   On entry, BPNTRB is an integer array of length MB such
                  that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX
                  of the first block entry of the J-th block row
                  of A. Unchanged on exit.

BPNTRE(input)   On entry, BPNTRE is an integer array of length MB such
                  that BPNTRE(J)-BPNTRB(1) points to location in BINDX
                  of the last block entry of the J-th block row
                  of A. Unchanged on exit.

LB (input)      On entry, LB specifies the dimension of dense blocks
                  composing A. Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                  Before entry with TRANSA = 0, the leading kb*lb by n
                  part of the array B must contain the matrix B, otherwise
                  the leading mb*lb by n part of the array B must contain the
                  matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                  in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION ( LDC, N ).
                  Before entry with TRANSA = 0, the leading mb*lb by n
                  part of the array C must contain the matrix C, otherwise
                  the leading kb*lb by n part of the array C must contain the
                  matrix C. On exit, the array C is overwritten by the matrix
                  ( alpha*op( A ) * B + beta*C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                  in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

```

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general complex matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

NOTES/BUGS

It is known that there exists another representation of the block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse row format the following calling sequence should be used

```
CALL ZBSRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*           VAL, BINDX, IA, IA(2), LB,  
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

zbsrsm - block sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE ZBSRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                LDB, LDC, LWORK  
INTEGER          BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZBSRSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, BINDX, BPNTRB, BPNTRE, LB,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, MB, N, UNITD, DESCRA(5), LB,  
*                   LDB, LDC, LWORK  
INTEGER*8        BINDX(BNNZ), BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  DV(MB*LB*LB), VAL(LB*LB*BNNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where: BNNZ = BPNTRE(MB)-BPNTRB(1)

F95 INTERFACE

```
SUBROUTINE BSRSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*              BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, MB, N, UNITD, LB  
INTEGER, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C  
  
SUBROUTINE BSRSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA, VAL, BINDX,  
*                   BPNTRB, BPNTRE, LB, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, MB, N, UNITD, LB  
INTEGER*8, DIMENSION(:) :: DESCRA, BINDX, BPNTRB, BPNTRE  
DOUBLE COMPLEX ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zbsrsm(int transa, int mb, int n, int unitd,
doublecomplex *dv, doublecomplex *alpha, int *descra,
doublecomplex *val,
int *bindx, int *bpntrb, int *bpntre, int lb, doublecomplex
*b,
int ldb, doublecomplex *beta, doublecomplex* c, int ldc);
```

```
void zbsrsm_64(long transa, long mb, long n, long unitd,
doublecomplex *dv, doublecomplex *alpha, long *descra,
doublecomplex *val, long *bindx, long *bpntrb, long *bpntre,
long lb, doublecomplex *b, long ldb, doublecomplex *beta,
doublecomplex *c, long ldc);
```

DESCRIPTION

zbsrsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are mb*lb by n dense matrices, D is a block diagonal matrix, A is a sparse mb*lb by mb*lb unit, or non-unit, upper or lower triangular matrix represented in the block sparse row format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, integer UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) Unchanged on exit.

DV(input) On entry, DV is an array of length MB*LB*LB consisting of the elements of the diagonal blocks of the matrix D. The size of each square block is LB-by-LB and each block is stored in standard column-major form. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-identity blocks on the main diagonal
1 : identity diagonal blocks
2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length LB*LB*BNNZ consisting of the non-zero block entries stored column-major within each dense block where BNNZ = BPNTRE(MB)-BPNTRB(1). Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ = BPNTRE(MB)-BPNTRB(1). The block column indices MUST be sorted in increasing order for each block column. Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(J)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the J-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(J)-BPNTRB(1) points to location in BINDX of the last block entry of the J-th block row of A. Unchanged on exit.

LB (input) On entry, LB specifies the dimension of dense blocks composing A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading mb*lb by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared

in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading $mb \times lb$ by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least $MB \times LB$.

For good performance, LWORK should generally be larger.
For optimum performance on multiple processors, LWORK $\geq MB \times LB \times N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:
<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If `DESCRA(3)=0`, the lower or upper triangular part of each diagonal block is used by the routine depending on `DESCRA(2)`.
3. If `DESCRA(3)=1`, the diagonal blocks in the block sparse

row representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.

4. If `DESCRA(3)=2` , the diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.

5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

6. It is known that there exists another representation of the block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the arrays VAL and BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of block sparse row format the following calling sequence should be used

```
CALL ZBSRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*           VAL, BINDX, IA, IA(2), LB,
*           B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

zcnvcor - compute the convolution or correlation of complex vectors

SYNOPSIS

```
SUBROUTINE ZCNVCOR(CNVCOR, FOUR, NX, X, IFX, INCX, NY, NPRE, M, Y,
                  IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, FOUR
DOUBLE COMPLEX X(*), Y(*), Z(*), WORK(*)
INTEGER NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y, NZ,
K, IFZ, INC1Z, INC2Z, LWORK
```

```
SUBROUTINE ZCNVCOR_64(CNVCOR, FOUR, NX, X, IFX, INCX, NY, NPRE, M, Y,
                    IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, LWORK)
```

```
CHARACTER * 1 CNVCOR, FOUR
DOUBLE COMPLEX X(*), Y(*), Z(*), WORK(*)
INTEGER*8 NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y, NZ,
K, IFZ, INC1Z, INC2Z, LWORK
```

F95 INTERFACE

```
SUBROUTINE CNVCOR(CNVCOR, FOUR, [NX], X, IFX, [INCX], NY, NPRE, M, Y,
                IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, FOUR
COMPLEX(8), DIMENSION(:) :: X, Y, Z, WORK
INTEGER :: NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y,
NZ, K, IFZ, INC1Z, INC2Z, LWORK
```

```
SUBROUTINE CNVCOR_64(CNVCOR, FOUR, [NX], X, IFX, [INCX], NY, NPRE, M,
                    Y, IFY, INC1Y, INC2Y, NZ, K, Z, IFZ, INC1Z, INC2Z, WORK, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, FOUR
COMPLEX(8), DIMENSION(:) :: X, Y, Z, WORK
INTEGER(8) :: NX, IFX, INCX, NY, NPRE, M, IFY, INC1Y, INC2Y,
NZ, K, IFZ, INC1Z, INC2Z, LWORK
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zcnvcor(char cnvcor, char four, int nx, doublecomplex
    *x, int ifx, int incx, int ny, int npre, int m,
    doublecomplex *y, int ify, int inclx, int inc2y,
    int nz, int k, doublecomplex *z, int ifz, int
    inclz, int inc2z, doublecomplex *work, int lwork);
void zcnvcor_64(char cnvcor, char four, long nx, doublecom-
    plex *x, long ifx, long incx, long ny, long npre,
    long m, doublecomplex *y, long ify, long inclx,
    long inc2y, long nz, long k, doublecomplex *z,
    long ifz, long inclz, long inc2z, doublecomplex
    *work, long lwork);

```

PURPOSE

zcnvcor computes the convolution or correlation of complex vectors.

ARGUMENTS

CNVCOR (input)

'V' or 'v' if convolution is desired, 'R' or 'r' if correlation is desired.

FOUR (input)

'T' or 't' if the Fourier transform method is to be used, 'D' or 'd' if the computation should be done directly from the definition. The Fourier transform method is generally faster, but it may introduce noticeable errors into certain results, notably when both the real and imaginary parts of the filter and data vectors consist entirely of integers or vectors where elements of either the filter vector or a given data vector differ significantly in magnitude from the 1-norm of the vector.

NX (input)

Length of the filter vector. $NX \geq 0$. ZCNVCOR will return immediately if $NX = 0$.

X (input) dimension(*)

Filter vector.

IFX (input)

Index of the first element of X. $NX \geq IFX \geq 1$.

INCX (input)

Stride between elements of the filter vector in X. $INCX > 0$.

NY (input)

Length of the input vectors. $NY \geq 0$. ZCNVCOR will return immediately if $NY = 0$.

NPRES (input)

The number of implicit zeros prepended to the Y vectors. NPRES \geq 0.

M (input)

Number of input vectors. $M \geq 0$. ZCNVCOR will return immediately if $M = 0$.

Y (input) dimension(*)

Input vectors.

IFY (input)

Index of the first element of Y. $NY \geq IFY \geq 1$.

INC1Y (input)

Stride between elements of the input vectors in Y. $INC1Y > 0$.

INC2Y (input)

Stride between the input vectors in Y. $INC2Y > 0$.

NZ (input)

Length of the output vectors. $NZ \geq 0$. ZCNVCOR will return immediately if $NZ = 0$. See the Notes section below for information about how this argument interacts with NX and NY to control circular versus end-off shifting.

K (input)

Number of Z vectors. $K \geq 0$. If $K = 0$ then ZCNVCOR will return immediately. If $K < M$ then only the first K input vectors will be processed. If $K > M$ then M input vectors will be processed.

Z (output)

dimension(*)
Result vectors.

IFZ (input)

Index of the first element of Z. $NZ \geq IFZ \geq 1$.

INC1Z (input)

Stride between elements of the output vectors in Z. $INC1Z > 0$.

INC2Z (input)

Stride between the output vectors in Z. $INC2Z > 0$.

WORK (input/output)

(input/scratch) dimension(LWORK)
Scratch space. Before the first call to ZCNVCOR with particular values of the integer arguments the first element of WORK must be set to zero. If WORK is written between calls to ZCNVCOR or if ZCNVCOR is called with different values of the integer arguments then the first element of WORK must again be set to zero before each call. If WORK has not been written and the same values of the integer arguments are used then the first element of WORK to zero. This can avoid certain initializations that store their results into WORK,

and avoiding the initialization can make ZCNVCOR
run faster.

LWORK (input)

Length of WORK. LWORK $\geq 2 \cdot \text{MAX}(\text{NX}, \text{NY}, \text{NZ}) + 8$.

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NAME

zcnvcor2 - compute the convolution or correlation of complex matrices

SYNOPSIS

```
SUBROUTINE ZCNVCOR2(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, MX, NX, X, LDX, MY, NY, MPRE, NPRES, Y, LDY, MZ, NZ, Z,  
    LDZ, WORKIN, LWORK)
```

```
CHARACTER * 1 CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
SCRATCHY  
DOUBLE COMPLEX X(LDX,*), Y(LDY,*), Z(LDZ,*), WORKIN(*)  
INTEGER MX, NX, LDX, MY, NY, MPRE, NPRES, LDY, MZ, NZ, LDZ,  
LWORK
```

```
SUBROUTINE ZCNVCOR2_64(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, MX, NX, X, LDX, MY, NY, MPRE, NPRES, Y, LDY, MZ, NZ, Z,  
    LDZ, WORKIN, LWORK)
```

```
CHARACTER * 1 CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
SCRATCHY  
DOUBLE COMPLEX X(LDX,*), Y(LDY,*), Z(LDZ,*), WORKIN(*)  
INTEGER*8 MX, NX, LDX, MY, NY, MPRE, NPRES, LDY, MZ, NZ, LDZ,  
LWORK
```

F95 INTERFACE

```
SUBROUTINE CNVCOR2(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, [MX], [NX], X, [LDX], [MY], [NY], MPRE, NPRES, Y, [LDY],  
    [MZ], [NZ], Z, [LDZ], WORKIN, [LWORK])
```

```
CHARACTER(LEN=1) :: CNVCOR, METHOD, TRANSX, SCRATCHX,  
TRANSY, SCRATCHY  
COMPLEX(8), DIMENSION(:) :: WORKIN  
COMPLEX(8), DIMENSION(:,:) :: X, Y, Z  
INTEGER :: MX, NX, LDX, MY, NY, MPRE, NPRES, LDY, MZ, NZ,  
LDZ, LWORK
```

```
SUBROUTINE CNVCOR2_64(CNVCOR, METHOD, TRANSX, SCRATCHX, TRANSY,  
    SCRATCHY, [MX], [NX], X, [LDX], [MY], [NY], MPRE, NPRES, Y, [LDY],  
    [MZ], [NZ], Z, [LDZ], WORKIN, [LWORK])
```

```

CHARACTER(LEN=1) :: CNVCOR, METHOD, TRANSX, SCRATCHX,
TRANSY, SCRATCHY
COMPLEX(8), DIMENSION(:) :: WORKIN
COMPLEX(8), DIMENSION(:,:) :: X, Y, Z
INTEGER(8) :: MX, NX, LDX, MY, NY, MPRE, NPRE, LDY, MZ, NZ,
LDZ, LWORK

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zcnvcor2(char cnvcor, char method, char transx, char
scratchx, char transy, char scratchy, int mx, int
nx, doublecomplex *x, int ldx, int my, int ny, int
mpre, int npre, doublecomplex *y, int ldy, int mz,
int nz, doublecomplex *z, int ldz, doublecomplex
*workin, int lwork);

```

```

void zcnvcor2_64(char cnvcor, char method, char transx, char
scratchx, char transy, char scratchy, long mx,
long nx, doublecomplex *x, long ldx, long my, long
ny, long mpre, long npre, doublecomplex *y, long
ldy, long mz, long nz, doublecomplex *z, long ldz,
doublecomplex *workin, long lwork);

```

PURPOSE

zcnvcor2 computes the convolution or correlation of complex matrices.

ARGUMENTS

CNVCOR (input)
'V' or 'v' to compute convolution, 'R' or 'r' to compute correlation.

METHOD (input)
'T' or 't' if the Fourier transform method is to be used, 'D' or 'd' to compute directly from the definition.

TRANSX (input)
'N' or 'n' if X is the filter matrix, 'T' or 't' if transpose(X) is the filter matrix.

SCRATCHX (input)
'N' or 'n' if X must be preserved, 'S' or 's' if X can be used as scratch space. The contents of X are undefined after returning from a call in which X is allowed to be used for scratch.

TRANSY (input)
'N' or 'n' if Y is the input matrix, 'T' or 't' if transpose(Y) is the input matrix.

SCRATCHY (input)
'N' or 'n' if Y must be preserved, 'S' or 's' if Y can be used as scratch space. The contents of Y

are undefined after returning from a call in which Y is allowed to be used for scratch.

MX (input)
Number of rows in the filter matrix. $MX \geq 0$.

NX (input)
Number of columns in the filter matrix. $NX \geq 0$.

X (input) dimension(LDX,NX)
On entry, the filter matrix. Unchanged on exit if SCRATCHX is 'N' or 'n', undefined on exit if SCRATCHX is 'S' or 's'.

LDX (input)
Leading dimension of the array that contains the filter matrix.

MY (input)
Number of rows in the input matrix. $MY \geq 0$.

NY (input)
Number of columns in the input matrix. $NY \geq 0$.

MPRE (input)
Number of implicit zeros to prepend to each row of the input matrix. $MPRE \geq 0$.

NPRE (input)
Number of implicit zeros to prepend to each column of the input matrix. $NPRE \geq 0$.

Y (input) dimension(LDY,*)
Input matrix. Unchanged on exit if SCRATCHY is 'N' or 'n', undefined on exit if SCRATCHY is 'S' or 's'.

LDY (input)
Leading dimension of the array that contains the input matrix.

MZ (input)
Number of rows in the output matrix. $MZ \geq 0$.
ZCNVCOR2 will return immediately if $MZ = 0$.

NZ (input)
Number of columns in the output matrix. $NZ \geq 0$.
ZCNVCOR2 will return immediately if $NZ = 0$.

Z (output)
dimension(LDZ,*)
Result matrix.

LDZ (input)
Leading dimension of the array that contains the result matrix. $LDZ \geq \text{MAX}(1, MZ)$.

WORKIN (input/output)
(input/scratch) dimension(LWORK)
On entry for the first call to ZCNVCOR2, WORKIN(1) must contain $\text{CPLX}(0.0, 0.0)$. After the first

call, WORKIN(1) must be set to CMPLX(0.0,0.0) iff WORKIN has been altered since the last call to this subroutine or if the sizes of the arrays have changed.

LWORK (input)

Length of the work vector. If the FFT is to be used then for best performance LWORK should be at least 30 words longer than the amount of memory needed to hold the trig tables. If the FFT is not used, the value of LWORK is unimportant.

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NAME

zcoomm - coordinate matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZCOOMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5), NNZ  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), JNDX(NNZ)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZCOOMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, JNDX, NNZ,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), NNZ  
*                LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), JNDX(NNZ)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE COOMM( TRANSA, M, [N], K, ALPHA, DESCRA,  
*                VAL, INDX, JNDX, NNZ, B, [LDB], BETA, C, [LDC],  
*                [WORK], [LWORK] )  
INTEGER          TRANSA, M, K, NNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, JNDX  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE COOMM_64( TRANSA, M, [N], K, ALPHA, DESCRA,  
*                   VAL, INDX, JNDX, NNZ, B, [LDB], BETA, C, [LDC],  
*                   [WORK], [LWORK] )  
INTEGER*8        TRANSA, M, K, NNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, JNDX  
DOUBLE COMPLEX  ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void zcoomm (int transa, int m, int n, int k, doublecomplex
*alpha, int *descra, doublecomplex *val, int *indx, int
*jndx, int nnz, doublecomplex *b, int ldb, doublecomplex
*beta, doublecomplex *c, int ldc);
void zcoomm_64 (long transa, long m, long n, long k,
doublecomplex *alpha, long *descra, doublecomplex *val,
long *indx,
long *jndx, long nnz, doublecomplex *b, long ldb,
doublecomplex *beta, doublecomplex *c, long ldc);
```

DESCRIPTION

zcoomm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),
A is an M-by-K sparse matrix represented in the coordinate format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, integer K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array. DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular

```

4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL (input)    On entry, VAL is a scalar array array of length
NNZ consisting of the non-zero entries of A,
in any order. Unchanged on exit.

INDX (input)   On entry, INDX is an integer array of length NNZ
consisting of the corresponding row indices of
the entries of A. Unchanged on exit.

JNDX (input)   On entry, JNDX is an integer array of length NNZ
consisting of the corresponding column indices of
the entries of A. Unchanged on exit.

NNZ (input)    On entry, integer NNZ specifies the number of
non-zero elements in A. Unchanged on exit.

B (input)      Array of DIMENSION ( LDB, N ).
Before entry with  TRANSA = 0,  the leading k by n
part of the array B must contain the matrix B,  otherwise
the leading m by n part of the array B must contain the
matrix B. Unchanged on exit.

LDB (input)    On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input)   On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
Before entry with  TRANSA = 0,  the leading m by n
part of the array C must contain the matrix C,  otherwise
the leading k by n part of the array C must contain the
matrix C. On exit, the array C  is overwritten by the matrix
( alpha*op( A ) * B  + beta*C ).

LDC (input)    On entry, LDC specifies the first dimension of C as declared
in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different.

Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas.
Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of complex matrices is given in section NOTES/BUGS for the ccoomm manpage.

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NAME

zcopy - Copy x to y

SYNOPSIS

```
SUBROUTINE ZCOPY(N, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE ZCOPY_64(N, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE COPY([N], X, [INCX], Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE COPY_64([N], X, [INCX], Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zcopy(int n, doublecomplex *x, int incx, doublecomplex  
          *y, int incy);
```

```
void zcopy_64(long n, doublecomplex *x, long incx, double-  
             lecomplex *y, long incy);
```

PURPOSE

zcopy Copy x to y where x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (output)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$. On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

zcscmm - compressed sparse column format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZCSCMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, PNTRB, PNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTRB(K), PNTRE(K)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZCSCMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, PNTRB, PNTRE,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5),  
*               LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTRB(K), PNTRE(K)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(K)-PNTRB(1)

F95 INTERFACE

```
SUBROUTINE CSCMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
* PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE CSCMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
* PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8 TRANSA, M, K  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE
```

```

DOUBLE COMPLEX    ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: VAL
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void zcscmm(int transa, int m, int n, int k, doublecomplex
*alpha, int *descra, doublecomplex *val, int *indx, int
*pntrb, int *pntre, doublecomplex *b, int ldb,
doublecomplex *beta, doublecomplex* c, int ldc);

void zcscmm_64(long transa, long m, long n, long k,
doublecomplex *alpha, long *descra, doublecomplex *val, long
*indx, long *pntrb, long *pntre, doublecomplex *b, long ldb,
doublecomplex *beta, doublecomplex *c, long ldc);

```

DESCRIPTION

zcscmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the compressed sparse column format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric (A=A') 2 : Hermitian (A= CONJG(A')) 3 : Triangular

```

    4 : Skew(Anti)-Symmetric (A=-A')
    5 : Diagonal
    6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
    1 : lower
    2 : upper
DESCRA(3) main diagonal type
    0 : non-unit
    1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
    0 : C/C++ compatible
    1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
    0 : unknown
    1 : no repeated indices

VAL(input)      On entry, VAL is a scalar array of length
                 NNZ = PNTRE(K)-PNTRB(1) consisting of nonzero
                 entries of A. Unchanged on exit.

INDX(input)     On entry, INDX is an integer array of length
                 NNZ = PNTRE(K)-PNTRB(1) consisting of the row
                 indices of nonzero entries of A.
                 Unchanged on exit.

PNTRB(input)    On entry, PNTRB is an integer array of length K
                 such that PNTRB(J)-PNTRB(1)+1 points to location
                 in VAL of the first nonzero element in column J.
                 Unchanged on exit.

PNTRE(input)    On entry, PNTRE is an integer array of length K
                 such that PNTRE(J)-PNTRB(1) points to location
                 in VAL of the last nonzero element in column J.
                 Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading k by n
                 part of the array B must contain the matrix B, otherwise
                 the leading m by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading m by n
                 part of the array C must contain the matrix C, otherwise
                 the leading k by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta*C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of complex matrices is given in section NOTES/BUGS for the ccoomm manpage.

NOTES/BUGS

It is known that there exists another representation of the compressed sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each column in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of sparse column format the following calling sequence should be used

```
SUBROUTINE ZCSCMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, IA, IA(2), B, LDB, BETA,  
*                C, LDC, WORK, LWORK )
```

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NAME

zcscsm - compressed sparse column format triangular solve

SYNOPSIS

```
SUBROUTINE ZCSCSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, PNTRB, PNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, UNITD, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZCSCSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                   VAL, INDX, PNTRB, PNTRE,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, UNITD, DESCRA(5),  
*                   LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(M)-PNTRB(1)

F95 INTERFACE

```
SUBROUTINE CSCSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
*               PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER TRANSA, M, UNITD  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE CSCSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
*                   PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8 TRANSA, M, UNITD  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE COMPLEX ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void zcscsm(int transa, int m, int n, int unitd,
  doublecomplex *dv, doublecomplex *alpha, int *descra,
  doublecomplex *val,
  int *indx, int *pntrb, int *pntre, doublecomplex *b,
  int ldb, doublecomplex *beta, doublecomplex* c, int ldc);

void zcscsm_64(long transa, long m, long n, long unitd,
  doublecomplex *dv, doublecomplex *alpha, long *descra,
  doublecomplex *val, long *indx, long *pntrb, long *pntre,
  doublecomplex *b, long ldb, doublecomplex *beta,
  doublecomplex *c, long ldc);
```

DESCRIPTION

zcscsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the compressed sparse column format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic column scaling (see section NOTES for further details) Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which the columns of A have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))

Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-unit
1 : unit

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries of A. If UNITD is 4, VAL contains the scaled matrix A*D (see section NOTES for further details). Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer array of length NNZ = PNTRE(M)-PNTRB(1) consisting of the row indices of nonzero entries of A. Row indices MUST be sorted in increasing order for each column. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such that PNTRB(J)-PNTRB(1)+1 points to location in VAL of the first nonzero element in column J. Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M such that PNTRE(J)-PNTRB(1) points to location in VAL of the last nonzero element in column J. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 On entry, the leading m by n part of the array C
 must contain the matrix C. On exit, the array C is
 overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
 On exit, if LWORK= -1, WORK(1) returns the optimum size
 of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK
 should be at least M.

 For good performance, LWORK should generally be larger.
 For optimum performance on multiple processors, LWORK
 >=M*N_CPUS where N_CPUS is the maximum number of
 processors available to the program.

 If LWORK=0, the routine is to allocate workspace needed.

 If LWORK = -1, then a workspace query is assumed; the
 routine only calculates the optimum size of the WORK array,
 returns this value as the first entry of the WORK array,
 and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If UNITD =4, the routine scales the columns of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by

which the columns have been scaled. UNITD=3 should be used for the next calls to the routine with overwritten VAL and DV.

`WORK(1)=0` on return if the scaling has been completed successfully, otherwise `WORK(1) = - i` where `i` is the column number which 2-norm is exactly zero.

3. If `DESCRA(3)=1` and `UNITD < 4`, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the CSC representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if `UNITD=4`, the unit diagonal elements MUST be referenced in the CSC representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	<code>alpha*op(L+I)*B+beta*C</code>
3	1	0	<code>alpha*op(L+D)*B+beta*C</code>
3	2	1	<code>alpha*op(U+I)*B+beta*C</code>
3	2	0	<code>alpha*op(U+D)*B+beta*C</code>

5. It is known that there exists another representation of the compressed sparse column format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each column in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of sparse column format the following calling sequence should be used

```
SUBROUTINE ZCSCSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, IA, IA(2), B, LDB, BETA,
```

* C, LDC, WORK, LWORK)

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NAME

zcsrmm - compressed sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZCSRMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, PNTRB, PNTRE,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZCSRMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, PNTRB, PNTRE,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5),  
*                   LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(M)-PNTRB(1)

F95 INTERFACE

```
SUBROUTINE CSRMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*               PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER          TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE COMPLEX   ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE CSRMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                   PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8        TRANSA, M, K  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE COMPLEX   ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zcsrmm(int transa, int m, int n, int k, doublecomplex
*alpha, int *descra, doublecomplex *val, int *indx, int
*pntrb, int *pntre, doublecomplex *b, int ldb,
doublecomplex *beta, doublecomplex* c, int ldc);
void zcsrmm_64(long transa, long m, long n, long k,
doublecomplex *alpha, long *descra, doublecomplex *val, long
*indx, long *pntrb, long *pntre, doublecomplex *b, long ldb,
doublecomplex *beta, doublecomplex *c, long ldc);
```

DESCRIPTION

zcsrmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the compressed sparse row format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal

6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
 NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries
 of A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
 NNZ = PNTRE(M)-PNTRB(1) consisting of the column
 indices of nonzero entries of A. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such
 that PNTRB(J)-PNTRB(1)+1 points to location in VAL
 of the first nonzero element in row J.
 Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M
 such that PNTRE(J)-PNTRB(1) points to location
 in VAL of the last nonzero element in row J.
 Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise
 the leading k by n part of the array C must contain the
 matrix C. On exit, the array C is overwritten by the matrix
 (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible

with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of complex matrices is given in section NOTES/BUGS for the ccoomm manpage.

NOTES/BUGS

It is known that there exists another representation of the compressed sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each row in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of compressed sparse row format the following calling sequence should be used

```
      SUBROUTINE ZCSRMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, IA, IA(2), B, LDB, BETA,  
*                   C, LDC, WORK, LWORK )
```

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NAME

zcsrsm - compressed sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE ZCSRSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, PNTRB, PNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER TRANSA, M, N, UNITD, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZCSRSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, PNTRB, PNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8 TRANSA, M, N, UNITD, DESCRA(5),  
* LDB, LDC, LWORK  
INTEGER*8 INDX(NNZ), PNTRB(M), PNTRE(M)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTRE(M)-PNTRB(1)

F95 INTERFACE

```
SUBROUTINE CSRSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
* PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER TRANSA, M, UNITD  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE CSRSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
* PNTRB, PNTRE, B, [LDB], BETA, C, [LDC], [WORK], [LWORK] )  
INTEGER*8 TRANSA, M, UNITD  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTRB, PNTRE  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>

void zcsrsm(int transa, int m, int n, int unitd,
  doublecomplex *dv, doublecomplex *alpha, int *descra,
  doublecomplex *val,
  int *indx, int *pntrb, int *pntre, doublecomplex *b,
  int ldb, doublecomplex *beta, doublecomplex* c, int ldc);

void zcsrsm_64(long transa, long m, long n, long unitd,
  doublecomplex *dv, doublecomplex *alpha, long *descra,
  doublecomplex *val, long *indx, long *pntrb, long *pntre,
  doublecomplex *b, long ldb, doublecomplex *beta,
  doublecomplex *c, long ldc);
```

DESCRIPTION

zcsrsm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C, \quad C \leftarrow \alpha D \operatorname{op}(A) B + \beta C,$$
$$C \leftarrow \alpha \operatorname{op}(A) D B + \beta C,$$

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the compressed sparse row format and $\operatorname{op}(A)$ is one of

$$\operatorname{op}(A) = \operatorname{inv}(A) \text{ or } \operatorname{op}(A) = \operatorname{inv}(A') \text{ or } \operatorname{op}(A) = \operatorname{inv}(\operatorname{conjg}(A'))$$

(inv denotes matrix inverse, ' indicates matrix transpose).

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.
DV(input)	On entry, DV is an array of length M consisting of the

diagonal entries of the diagonal scaling matrix D.
If UNITD is 4, DV contains diagonal matrix by which
the rows have been scaled (see section NOTES for further
details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
NNZ = PNTRE(M)-PNTRB(1) consisting of nonzero entries
of A. If UNITD is 4, VAL contains the scaled matrix
D*A (see section NOTES for further details).
Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
NNZ = PNTRE(M)-PNTRB(1) consisting of the column
indices of nonzero entries of A. Column indices
MUST be sorted in increasing order for each
row. Unchanged on exit.

PNTRB(input) On entry, PNTRB is an integer array of length M such
that PNTRB(J)-PNTRB(1)+1 points to location in VAL
of the first nonzero element in row J.
Unchanged on exit.

PNTRE(input) On entry, PNTRE is an integer array of length M
such that PNTRE(J)-PNTRB(1) points to location
in VAL of the last nonzero element in row J.
Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B
must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C

must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M * N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = - i where i is the row number which 2-norm is exactly zero.

3. If DESCRA(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the CSR representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the CSR representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But DESCRA(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a

general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	alpha*op(L+I)*B+beta*C
3	1	0	alpha*op(L+D)*B+beta*C
3	2	1	alpha*op(U+I)*B+beta*C
3	2	0	alpha*op(U+D)*B+beta*C

5. It is known that there exists another representation of the compressed sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of three array instead of the four used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each row in the arrays VAL and INDX is used instead of two arrays PNTRB and PNTRE. To use the routine with this kind of compressed sparse row format the following calling sequence should be used

```
SUBROUTINE ZCSRSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
*                VAL, INDX, IA, IA(2), B, LDB, BETA, C,  
*                LDC, WORK, LWORK )
```

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NAME

zdiamm - diagonal format matrix-matrix multiply.

SYNOPSIS

```
SUBROUTINE ZDIAMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, LDA, IDIAG, NDIAG,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5), LDA, NDIAG,  
*                LDB, LDC, LWORK  
INTEGER          IDIAG(NDIAG)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZDIAMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, LDA, IDIAG, NDIAG,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), LDA, NDIAG,  
*                   LDB, LDC, LWORK  
INTEGER*8        IDIAG(NDIAG)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE DIAMM(TRANSA, M, [N], K, ALPHA, DESCRA, VAL, [LDA],  
*              IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, M, K, NDIAG  
INTEGER, DIMENSION(:) :: DESCRA, IDIAG  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE DIAMM_64(TRANSA, M, [N], K, ALPHA, DESCRA, VAL, [LDA],  
*                  IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, M, K, NDIAG  
INTEGER*8, DIMENSION(:) :: DESCRA, IDIAG  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```

#include <sunperf.h>

void zdiamm (int transa, int m, int n, int k, doublecomplex
*alpha, int *descra, doublecomplex *val, int lda, int
*idiag, int ndiag, doublecomplex *b, int ldb, doublecomplex
*beta,
doublecomplex *c, int ldc);

void zdiamm_64 (long transa, long m, long n, long k,
doublecomplex *alpha, long *descra, doublecomplex *val, long
lda,
long *idiag, long ndiag, doublecomplex *b, long ldb,
doublecomplex *beta, doublecomplex *c, long ldc);

```

DESCRIPTION

zdiamm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the diagonal format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular 4 : Skew(Anti)-Symmetric ($A=-A'$) 5 : Diagonal 6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$)

DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper

DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit

DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) Two-dimensional LDA-by-NDIAG array such that VAL(:,I) consists of non-zero elements on diagonal IDIAG(I) of A. Diagonals in the lower triangular part of A are padded from the top, and those in the upper triangular part are padded from the bottom. Unchanged on exit.

LDA(input) On entry, NDIAG specifies the leading dimension of VAL, must be $\geq \text{MIN}(M,K)$. Unchanged on exit.

IDIAG(input) Integer array of length NDIAG consisting of the corresponding diagonal offsets of the non-zero diagonals of A in VAL. Lower triangular diagonals have negative offsets, the main diagonal has offset 0, and upper triangular diagonals have positive offset. Unchanged on exit.

NDIAG(input) On entry, NDIAG specifies the number of non-zero diagonals in A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \text{beta} * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of complex matrices is given in section NOTES/BUGS for the ccoomm manpage.

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NAME

zdiasm - diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE ZDIASM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*               VAL, LDA, IDIAG, NDIAG,
*               B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER        TRANSA, M, N, UNITD, DESCRA(5), LDA, NDIAG,
*               LDB, LDC, LWORK
INTEGER        IDIAG(NDIAG)
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX DV(M), VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE ZDIASM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                   VAL, LDA, IDIAG, NDIAG,
*                   B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER*8      TRANSA, M, N, UNITD, DESCRA(5), LDA, NDIAG,
*               LDB, LDC, LWORK
INTEGER*8      IDIAG(NDIAG)
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX DV(M), VAL(LDA,NDIAG), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE DIASM(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,
* [LDA], IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER        TRANSA, M, NDIAG
INTEGER, DIMENSION(:) :: DESCRA, IDIAG
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: DV
DOUBLE COMPLEX, DIMENSION(:, :) :: VAL, B, C

SUBROUTINE DIASM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,
* [LDA], IDIAG, NDIAG, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER*8      TRANSA, M, NDIAG
INTEGER*8, DIMENSION(:) :: DESCRA, IDIAG
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: DV
DOUBLE COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>

void zdiasm (int transa, int m, int n, int unitd,
             doublecomplex *dv, doublecomplex *alpha, int *descra,
             doublecomplex *val, int lda,
             int *idiag, int ndiag, doublecomplex *b, int ldb,
             doublecomplex *beta,
             doublecomplex *c, int ldc);
void zdiasm_64 (long transa, long m, long n, long unitd,
               doublecomplex *dv, doublecomplex *alpha, long *descra,
               doublecomplex *val,
               long lda, long *idiag, long ndiag, doublecomplex *b, long
               ldb,
               doublecomplex *beta, doublecomplex *c, long ldc);
```

DESCRIPTION

zdiasm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C, \quad C \leftarrow -\alpha D \operatorname{op}(A) B + \beta C,$$
$$C \leftarrow \alpha \operatorname{op}(A) D B + \beta C,$$

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the diagonal format and $\operatorname{op}(A)$ is one of

$$\operatorname{op}(A) = \operatorname{inv}(A) \text{ or } \operatorname{op}(A) = \operatorname{inv}(A') \text{ or } \operatorname{op}(A) = \operatorname{inv}(\operatorname{conjg}(A'))$$

(inv denotes matrix inverse, ' indicates matrix transpose).

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LDA-by-NDIAG array such that VAL(:,I) consists of non-zero elements on diagonal IDIAG(I) of A. Diagonals in the lower triangular part of A are padded from the top, and those in the upper triangular part are padded from the bottom. If UNITD is 4, VAL contains the scaled matrix D*A (see section NOTES for further details). Otherwise, unchanged on exit.

LDA(input) On entry, LDA specifies the leading dimension of VAL and INDX. LDA must be > MIN(M,K). Unchanged on exit.

IDIAG() On entry, IDIAG is an integer array of length NDIAG consisting of the corresponding diagonal offsets of the non-zero diagonals of A in VAL. Lower triangular diagonals have negative offsets, the main diagonal has offset 0, and upper triangular diagonals have positive offset. Elements of IDIAG of MUST be sorted in increasing order. Unchanged on exit.

NDIAG(input) On entry, NDIAG specifies the number of non-zero diagonals in A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).

On entry, the leading m by n part of the array C must contain the matrix C . On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M .

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M * N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = - i where i is the row

number which 2-norm is exactly zero.

3. If `DESCRA(3)=1` and `UNITD < 4`, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the DIA representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if `UNITD=4`, the unit diagonal elements MUST be referenced in the DIA representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

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NAME

zdotc - compute the dot product of two vectors conjg(x) and y.

SYNOPSIS

```
DOUBLE COMPLEX FUNCTION ZDOTC(N, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
DOUBLE COMPLEX FUNCTION ZDOTC_64(N, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
COMPLEX(8) FUNCTION DOTC([N], X, [INCX], Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
COMPLEX(8) FUNCTION DOTC_64([N], X, [INCX], Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
doublecomplex zdotc(int n, doublecomplex *x, int incx, double-  
complex *y, int incy);
```

```
doublecomplex zdotc_64(long n, doublecomplex *x, long incx,  
doublecomplex *y, long incy);
```

PURPOSE

zdotc compute the dot product of conjg(x) and y where x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If N is not positive then the function returns the value 0.0. Unchanged on exit.

X (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCX}))$. On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$. On entry, the incremented array Y must contain the vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

zdotci - Compute the complex conjugated indexed dot product.

SYNOPSIS

```
DOUBLE COMPLEX FUNCTION ZDOTCI(NZ, X, INDX, Y)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER NZ  
INTEGER INDX(*)
```

```
DOUBLE COMPLEX FUNCTION ZDOTCI_64(NZ, X, INDX, Y)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER*8 NZ  
INTEGER*8 INDX(*)
```

```
F95 INTERFACE
```

```
DOUBLE COMPLEX FUNCTION DOTCI([NZ], X, INDX, Y)
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER :: NZ  
INTEGER, DIMENSION(:) :: INDX
```

```
DOUBLE COMPLEX FUNCTION DOTCI_64([NZ], X, INDX, Y)
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: NZ  
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

ZDOTCI Compute the complex conjugated indexed dot product of a complex sparse vector x stored in compressed form with a complex vector y in full storage form.

```
dot = 0  
do i = 1, n  
  dot = dot + conjg(x(i)) * y(indx(i))  
enddo
```

ARGUMENTS

NZ (input)

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector in compressed form. Unchanged on exit.

INDX (input)

Vector containing the indices of the compressed form. It is assumed that the elements in INDX are distinct and greater than zero. Unchanged on exit.

Y (input)

Vector in full storage form. Only the elements corresponding to the indices in INDX will be accessed.

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NAME

zdotu - compute the dot product of two vectors x and y.

SYNOPSIS

```
DOUBLE COMPLEX FUNCTION ZDOTU(N, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
DOUBLE COMPLEX FUNCTION ZDOTU_64(N, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
COMPLEX(8) FUNCTION DOT([N], X, [INCX], Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
COMPLEX(8) FUNCTION DOT_64([N], X, [INCX], Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
doublecomplex zdotu(int n, doublecomplex *x, int incx, doublecomplex *y, int incy);
```

```
doublecomplex zdotu_64(long n, doublecomplex *x, long incx, doublecomplex *y, long incy);
```

PURPOSE

zdotu compute the dot product of x and y where x and y are

n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. If N is not positive then the function returns the value 0.0. Unchanged on exit.

X (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCX}))$. On entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input)

of DIMENSION at least $(1 + (n - 1) * \text{abs}(\text{INCY}))$. On entry, the incremented array Y must contain the vector y. Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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NAME

zdotui - Compute the complex unconjugated indexed dot product.

SYNOPSIS

```
DOUBLE COMPLEX FUNCTION CDOTCI(NZ, X, INDX, Y)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER NZ  
INTEGER INDX(*)
```

```
DOUBLE COMPLEX FUNCTION CDOTCI_64(NZ, X, INDX, Y)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER*8 NZ  
INTEGER*8 INDX(*)
```

```
F95 INTERFACE
```

```
DOUBLE COMPLEX FUNCTION DOTCI([NZ], X, INDX, Y)
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER :: NZ  
INTEGER, DIMENSION(:) :: INDX
```

```
DOUBLE COMPLEX FUNCTION DOTCI_64([NZ], X, INDX, Y)
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: NZ  
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

ZDOTUI Compute the complex unconjugated indexed dot product of a complex sparse vector x stored in compressed form with a complex vector y in full storage form.

```
dot = 0  
do i = 1, n  
  dot = dot + x(i) * y(indx(i))  
enddo
```

ARGUMENTS

NZ (input)

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector in compressed form. Unchanged on exit.

INDX (input)

Vector containing the indices of the compressed form. It is assumed that the elements in INDX are distinct and greater than zero. Unchanged on exit.

Y (input)

Vector in full storage form. Only the elements corresponding to the indices in INDX will be accessed.

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zdrot - Apply a plane rotation.

SYNOPSIS

```
SUBROUTINE ZDROT(N, X, INCX, Y, INCY, C, S)
```

```
DOUBLE PRECISION C, S  
DOUBLE COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE ZDROT_64(N, X, INCX, Y, INCY, C, S)
```

```
DOUBLE PRECISION C, S  
DOUBLE COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE ROT([N], X, [INCX], Y, [INCY], C, S)
```

```
REAL(8) :: C, S  
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE ROT_64([N], X, [INCX], Y, [INCY], C, S)
```

```
REAL(8) :: C, S  
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zdrot(int n, doublecomplex *x, int incx, doublecomplex  
          *y, int incy, double c, double s);
```

```
void zdrot_64(long n, doublecomplex *x, long incx, double-  
             lecomplex *y, long incy, double c, double s);
```

PURPOSE

zdrot Apply a plane rotation, where the cos and sin (c and s) are real and the vectors x and y are complex.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input/output)

Before entry, the incremented array CX must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of CX. INCX must not be zero. Unchanged on exit.

Y (input/output)

On entry, the incremented array CY must contain the vector y. On exit, CY is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of CY. INCY must not be zero. Unchanged on exit.

C (input)

On entry, the cosine. Unchanged on exit.

S (input)

On entry, the sin. Unchanged on exit.

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NAME

zdscal - Compute $y := \alpha * y$

SYNOPSIS

```
SUBROUTINE ZDSCAL(N, ALPHA, Y, INCY)
```

```
DOUBLE COMPLEX Y(*)
INTEGER N, INCY
DOUBLE PRECISION ALPHA
```

```
SUBROUTINE ZDSCAL_64(N, ALPHA, Y, INCY)
```

```
DOUBLE COMPLEX Y(*)
INTEGER*8 N, INCY
DOUBLE PRECISION ALPHA
```

F95 INTERFACE

```
SUBROUTINE SCAL([N], ALPHA, Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: Y
INTEGER :: N, INCY
REAL(8) :: ALPHA
```

```
SUBROUTINE SCAL_64([N], ALPHA, Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: Y
INTEGER(8) :: N, INCY
REAL(8) :: ALPHA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zdscal(int n, double alpha, doublecomplex *y, int
            incy);
```

```
void zdscal_64(long n, double alpha, doublecomplex *y, long
              incy);
```

PURPOSE

zdscal Compute $y := \alpha * y$ where alpha is a scalar and y is an n-vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * INCY). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. This routine returns immediately if INCY is less than or equal to zero. Unchanged on exit.

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NAME

zellmm - Ellpack format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZELLM( TRANSA, M, N, K, ALPHA, DESCRA,  
*              VAL, INDX, LDA, MAXNZ,  
*              B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER       TRANSA, M, N, K, DESCRA(5), LDA, MAXNZ,  
*              LDB, LDC, LWORK  
INTEGER       INDX(LDA,MAXNZ)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZELLM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, LDA, MAXNZ,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8      TRANSA, M, N, K, DESCRA(5), LDA, MAXNZ,  
*              LDB, LDC, LWORK  
INTEGER*8      INDX(LDA,MAXNZ)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE ELLMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*               [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, M, K, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA  
INTEGER, DIMENSION(:, :) :: INDX  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

```
SUBROUTINE ELLMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                   [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, M, K, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA  
INTEGER*8, DIMENSION(:, :) :: INDX  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zellmm (int transa, int m, int n, int k, doublecomplex  
*alpha, int *descra, doublecomplex *val, int *indx, int lda,  
int maxnz, doublecomplex *b, int ldb, doublecomplex *beta,  
doublecomplex *c, int ldc);  
void zellmm_64 (long transa, long m, long n, long k,  
doublecomplex *alpha, long *descra, doublecomplex *val, long  
*indx, long lda, long maxnz, doublecomplex *b, long ldb,  
doublecomplex *beta, doublecomplex *c, long ldc);
```

DESCRIPTION

zellmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the ellpack format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input) TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

K(input) On entry, K specifies the number of columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric ($A=A'$)
2 : Hermitian ($A= \operatorname{CONJG}(A')$)
3 : Triangular
4 : Skew(Anti)-Symmetric ($A=-A'$)
5 : Diagonal
6 : Skew-Hermitian ($A= -\operatorname{CONJG}(A')$)
DESCRA(2) upper/lower triangular indicator

```

    1 : lower
    2 : upper
DESCRA(3) main diagonal type
    0 : non-unit
    1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
    0 : C/C++ compatible
    1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
    0 : unknown
    1 : no repeated indices

VAL(input)      On entry, VAL is a two-dimensional LDA-by-MAXNZ array
                 such that VAL(I,:) consists of non-zero elements
                 in row I of A, padded by zero values if the row
                 contains less than MAXNZ. Unchanged on exit.

INDX(input)     On entry, INDX is an integer two-dimensional
                 LDA-by-MAXNZ array such that INDX(I,:)
                 consists of the column indices of the
                 nonzero elements in row I, padded by the integer
                 value I if the number of nonzeros is less than
                 MAXNZ. Unchanged on exit.

LDA(input)      On entry, LDA specifies the leading dimension of VAL
                 and INDX. Unchanged on exit.

MAXNZ(input)    On entry, MAXNZ specifies the max number of
                 nonzeros elements per row. Unchanged on exit.

B (input)       Array of DIMENSION ( LDB, N ).
                 Before entry with TRANSA = 0, the leading k by n
                 part of the array B must contain the matrix B, otherwise
                 the leading m by n part of the array B must contain the
                 matrix B. Unchanged on exit.

LDB (input)     On entry, LDB specifies the first dimension of B as declared
                 in the calling (sub) program. Unchanged on exit.

BETA (input)    On entry, BETA specifies the scalar beta. Unchanged on exit.
C(input/output) Array of DIMENSION ( LDC, N ).
                 Before entry with TRANSA = 0, the leading m by n
                 part of the array C must contain the matrix C, otherwise
                 the leading k by n part of the array C must contain the
                 matrix C. On exit, the array C is overwritten by the matrix
                 ( alpha*op( A ) * B + beta*C ).

LDC (input)     On entry, LDC specifies the first dimension of C as declared
                 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN

Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by triangles and/or the main diagonal of A. The full description of the feature for point entry formats in the case of complex matrices is given in section NOTES/BUGS for the ccoomm manpage.

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NAME

zellsm - Ellpack format triangular solve

SYNOPSIS

```
SUBROUTINE ZELLSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*               VAL, INDX, LDA, MAXNZ,
*               B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER        TRANSA, M, N, UNITD, DESCRA(5), LDA, MAXNZ,
*             LDB, LDC, LWORK
INTEGER        INDX(LDA,MAXNZ)
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX DV(M), VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE ZELLSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*                   VAL, INDX, LDA, MAXNZ,
*                   B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER*8      TRANSA, M, N, UNITD, DESCRA(5), LDA, MAXNZ,
*             LDB, LDC, LWORK
INTEGER*8      INDX(LDA,MAXNZ)
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX DV(M), VAL(LDA,MAXNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE ELLSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,
*             INDX, [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER      TRANSA, M, MAXNZ
INTEGER, DIMENSION(:) :: DESCRA
INTEGER, DIMENSION(:, :) :: INDX
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: DV
DOUBLE COMPLEX, DIMENSION(:, :) :: VAL, B, C

SUBROUTINE ELLSM_64( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,
*             INDX, [LDA], MAXNZ, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER*8    TRANSA, M, MAXNZ
INTEGER*8, DIMENSION(:) :: DESCRA
INTEGER*8, DIMENSION(:, :) :: INDX
DOUBLE COMPLEX ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: DV
DOUBLE COMPLEX, DIMENSION(:, :) :: VAL, B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zellsm (int transa, int m, int n, int unitd,
doublecomplex *dv, doublecomplex *alpha, int *descra,
doublecomplex *val, int *indx, int lda, int maxnz,
doublecomplex *b, int ldb, doublecomplex *beta,
doublecomplex *c, int ldc);
```

```
void zellsm_64 (long transa, long m, long n, long unitd,
doublecomplex *dv, doublecomplex *alpha, long *descra,
doublecomplex *val, long *indx, long lda, long maxnz,
doublecomplex *b, long ldb, doublecomplex *beta,
doublecomplex *c, long ldc);
```

DESCRIPTION

zellsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the ellpack/itpack format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
UNITD(input)	On entry, UNITD specifies the type of scaling: 1 : Identity matrix (argument DV[] is ignored) 2 : Scale on left (row scaling) 3 : Scale on right (column scaling) 4 : Automatic row scaling (see section NOTES for further details) Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a two-dimensional LDA-by-MAXNZ array such that VAL(I,:) consists of non-zero elements in row I of A, padded by zero values if the row contains less than MAXNZ. If UNITD is 4, VAL contains the scaled matrix D*A (see section NOTES for further details). Otherwise, unchanged on exit.

INDX(input) On entry, INDX is an integer two-dimensional LDA-by-MAXNZ array such that INDX(I,:) consists of the column indices of the nonzero elements in row I, padded by the integer value I if the number of nonzeros is less than MAXNZ. The column indices MUST be sorted in increasing order for each row. Unchanged on exit.

LDA(input) On entry, LDA specifies the leading dimension of VAL and INDX. Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of nonzeros elements per row. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).

On entry, the leading m by n part of the array C must contain the matrix C . On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M .

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, LWORK $\geq M * N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If UNITD =4, the routine scales the rows of A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = -i where i is the row

number which 2-norm is exactly zero.

3. If `DESCRA(3)=1` and `UNITD < 4`, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the ELL representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if `UNITD=4`, the unit diagonal elements MUST be referenced in the ELL representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

<code>DESCRA(1)</code>	<code>DESCRA(2)</code>	<code>DESCRA(3)</code>	RESULT
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

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NAME

zfft2b - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of ZFFT2F followed by a call of ZFFT2B will multiply the input sequence by $M*N$.

SYNOPSIS

```
SUBROUTINE ZFFT2B(M, N, A, LDA, WORK, LWORK)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER M, N, LDA, LWORK  
DOUBLE PRECISION WORK(*)
```

```
SUBROUTINE ZFFT2B_64(M, N, A, LDA, WORK, LWORK)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 M, N, LDA, LWORK  
DOUBLE PRECISION WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2B([M], [N], A, [LDA], WORK, LWORK)
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, LWORK  
REAL(8), DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT2B_64([M], [N], A, [LDA], WORK, LWORK)
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, LWORK  
REAL(8), DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zfft2b(int m, int n, doublecomplex *a, int lda, double  
*work, int lwork);
```

```
void zfft2b_64(long m, long n, doublecomplex *a, long lda,  
double *work, long lwork);
```

ARGUMENTS

M (input) Number of rows to be transformed. These subroutines are most efficient when M is a product of small primes. $M \geq 0$.

N (input) Number of columns to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

A (input/output)

On entry, a two-dimensional array A(M,N) that contains the sequences to be transformed.

LDA (input)

Leading dimension of the array containing the data to be transformed. $LDA \geq M$.

WORK (input)

On entry, an array with dimension of at least LWORK. WORK must have been initialized by ZFFT2I.

LWORK (input)

The dimension of the array WORK. $LWORK \geq (4 * (M + N) + 30)$

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NAME

zfft2f - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of ZFFT2F followed by a call of ZFFT2B will multiply the input sequence by M*N.

SYNOPSIS

```
SUBROUTINE ZFFT2F(M, N, A, LDA, WORK, LWORK)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER M, N, LDA, LWORK  
DOUBLE PRECISION WORK(*)
```

```
SUBROUTINE ZFFT2F_64(M, N, A, LDA, WORK, LWORK)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 M, N, LDA, LWORK  
DOUBLE PRECISION WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2F([M], [N], A, [LDA], WORK, LWORK)
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, LWORK  
REAL(8), DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT2F_64([M], [N], A, [LDA], WORK, LWORK)
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, LWORK  
REAL(8), DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zfft2f(int m, int n, doublecomplex *a, int lda, double  
*work, int lwork);
```

```
void zfft2f_64(long m, long n, doublecomplex *a, long lda,  
double *work, long lwork);
```

ARGUMENTS

M (input) Number of rows to be transformed. These subroutines are most efficient when M is a product of small primes. $M \geq 0$.

N (input) Number of columns to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

A (input/output)

On entry, a two-dimensional array A(M,N) that contains the sequences to be transformed.

LDA (input)

Leading dimension of the array containing the data to be transformed. $LDA \geq M$.

WORK (input)

On input, workspace WORK must have been initialized by ZFFT2I.

LWORK (input)

The dimension of the array WORK. $LWORK \geq (4 * (M + N) + 30)$

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NAME

zfft2i - initialize the array WSAVE, which is used in both the forward and backward transforms.

SYNOPSIS

```
SUBROUTINE ZFFT2I(M, N, WORK)
```

```
INTEGER M, N  
DOUBLE PRECISION WORK(*)
```

```
SUBROUTINE ZFFT2I_64(M, N, WORK)
```

```
INTEGER*8 M, N  
DOUBLE PRECISION WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ZFFT2I(M, N, WORK)
```

```
INTEGER :: M, N  
REAL(8), DIMENSION(:) :: WORK
```

```
SUBROUTINE ZFFT2I_64(M, N, WORK)
```

```
INTEGER(8) :: M, N  
REAL(8), DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zfft2i(int m, int n, double *work);
```

```
void zfft2i_64(long m, long n, double *work);
```

ARGUMENTS

M (input) Number of rows to be transformed. M >= 0.

N (input) Number of columns to be transformed. N >= 0.

WORK (input/output)

On entry, an array of dimension $(4 * (M + N) + 30)$ or greater. ZFFT2I needs to be called only once to initialize array WORK before calling ZFFT2F and/or ZFFT2B if M, N and WORK remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

zfft3b - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of ZFFT3F followed by a call of ZFFT3B will multiply the input sequence by $M*N*K$.

SYNOPSIS

```
SUBROUTINE ZFFT3B(M, N, K, A, LDA, LD2A, WORK, LWORK)
```

```
DOUBLE COMPLEX A(LDA,LD2A,*)  
INTEGER M, N, K, LDA, LD2A, LWORK  
DOUBLE PRECISION WORK(*)
```

```
SUBROUTINE ZFFT3B_64(M, N, K, A, LDA, LD2A, WORK, LWORK)
```

```
DOUBLE COMPLEX A(LDA,LD2A,*)  
INTEGER*8 M, N, K, LDA, LD2A, LWORK  
DOUBLE PRECISION WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3B([M], [N], [K], A, [LDA], LD2A, WORK, LWORK)
```

```
COMPLEX(8), DIMENSION(:, :, :) :: A  
INTEGER :: M, N, K, LDA, LD2A, LWORK  
REAL(8), DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT3B_64([M], [N], [K], A, [LDA], LD2A, WORK, LWORK)
```

```
COMPLEX(8), DIMENSION(:, :, :) :: A  
INTEGER(8) :: M, N, K, LDA, LD2A, LWORK  
REAL(8), DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zfft3b(int m, int n, int k, doublecomplex *a, int lda,  
           int ld2a, double *work, int lwork);
```

```
void zfft3b_64(long m, long n, long k, doublecomplex *a,  
              long lda, long ld2a, double *work, long lwork);
```

ARGUMENTS

- M (input) Number of rows to be transformed. These subroutines are most efficient when M is a product of small primes. $M \geq 0$.
- N (input) Number of columns to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- K (input) Number of planes to be transformed. These subroutines are most efficient when K is a product of small primes. $K \geq 0$.
- A (input/output)
On entry, a three-dimensional array $A(LDA,LD2A,K)$ that contains the sequences to be transformed.
- LDA (input)
Leading dimension of the array containing the data to be transformed. $LDA \geq M$.
- LD2A (input)
Second dimension of the array containing the data to be transformed. $LD2A \geq N$.
- WORK (input)
On input, workspace WORK must have been initialized by ZFFT3I.
- LWORK (input)
The dimension of the array WORK. $LWORK \geq (4*(M + N + K) + 45)$.

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NAME

zfft3f - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of ZFFT3F followed by a call of ZFFT3B will multiply the input sequence by $M*N*K$.

SYNOPSIS

```
SUBROUTINE ZFFT3F(M, N, K, A, LDA, LD2A, WORK, LWORK)
```

```
DOUBLE COMPLEX A(LDA,LD2A,*)  
INTEGER M, N, K, LDA, LD2A, LWORK  
DOUBLE PRECISION WORK(*)
```

```
SUBROUTINE ZFFT3F_64(M, N, K, A, LDA, LD2A, WORK, LWORK)
```

```
DOUBLE COMPLEX A(LDA,LD2A,*)  
INTEGER*8 M, N, K, LDA, LD2A, LWORK  
DOUBLE PRECISION WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3F([M], [N], [K], A, [LDA], LD2A, WORK, LWORK)
```

```
COMPLEX(8), DIMENSION(:, :, :) :: A  
INTEGER :: M, N, K, LDA, LD2A, LWORK  
REAL(8), DIMENSION(:) :: WORK
```

```
SUBROUTINE FFT3F_64([M], [N], [K], A, [LDA], LD2A, WORK, LWORK)
```

```
COMPLEX(8), DIMENSION(:, :, :) :: A  
INTEGER(8) :: M, N, K, LDA, LD2A, LWORK  
REAL(8), DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zfft3f(int m, int n, int k, doublecomplex *a, int lda,  
           int ld2a, double *work, int lwork);
```

```
void zfft3f_64(long m, long n, long k, doublecomplex *a,  
              long lda, long ld2a, double *work, long lwork);
```

ARGUMENTS

- M (input) Number of rows to be transformed. These subroutines are most efficient when M is a product of small primes. $M \geq 0$.
- N (input) Number of columns to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.
- K (input) Number of planes to be transformed. These subroutines are most efficient when K is a product of small primes. $K \geq 0$.
- A (input/output)
On entry, a three-dimensional array A(M,N,K) that contains the sequences to be transformed.
- LDA (input)
Leading dimension of the array containing the data to be transformed. $LDA \geq M$.
- LD2A (input)
Second dimension of the array containing the data to be transformed. $LD2A \geq N$.
- WORK (input)
On input, workspace WORK must have been initialized by ZFFT3I.
- LWORK (input)
The dimension of the array WORK. $LWORK \geq (4*(M + N + K) + 45)$.

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NAME

zfft3i - initialize the array WSAVE, which is used in both ZFFT3F and ZFFT3B.

SYNOPSIS

```
SUBROUTINE ZFFT3I(M, N, K, WORK)
```

```
INTEGER M, N, K  
DOUBLE PRECISION WORK(*)
```

```
SUBROUTINE ZFFT3I_64(M, N, K, WORK)
```

```
INTEGER*8 M, N, K  
DOUBLE PRECISION WORK(*)
```

F95 INTERFACE

```
SUBROUTINE ZFFT3I(M, N, K, WORK)
```

```
INTEGER :: M, N, K  
REAL(8), DIMENSION(:) :: WORK
```

```
SUBROUTINE ZFFT3I_64(M, N, K, WORK)
```

```
INTEGER(8) :: M, N, K  
REAL(8), DIMENSION(:) :: WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zfft3i(int m, int n, int k, double *work);
```

```
void zfft3i_64(long m, long n, long k, double *work);
```

ARGUMENTS

M (input) Number of rows to be transformed. M >= 0.

N (input) Number of columns to be transformed. N >= 0.

K (input) Number of planes to be transformed. $K \geq 0$.

WORK (input/output)

On entry, an array of dimension $(4 \cdot (M + N + K) + 45)$ or greater. ZFFT3I needs to be called only once to initialize array WORK before calling ZFFT3F and/or ZFFT3B if M, N, K and WORK remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

zfftb - compute a periodic sequence from its Fourier coefficients. The FFT operations are unnormalized, so a call of ZFFTF followed by a call of ZFFTB will multiply the input sequence by N.

SYNOPSIS

```
SUBROUTINE ZFFTB(N, X, WSAVE)
```

```
DOUBLE COMPLEX X(*)  
INTEGER N  
DOUBLE PRECISION WSAVE(*)
```

```
SUBROUTINE ZFFTB_64(N, X, WSAVE)
```

```
DOUBLE COMPLEX X(*)  
INTEGER*8 N  
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE FFTB([N], X, WSAVE)
```

```
COMPLEX(8), DIMENSION(:) :: X  
INTEGER :: N  
REAL(8), DIMENSION(:) :: WSAVE
```

```
SUBROUTINE FFTB_64([N], X, WSAVE)
```

```
COMPLEX(8), DIMENSION(:) :: X  
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zfftb(int n, doublecomplex *x, double *wsave);
```

```
void zfftb_64(long n, doublecomplex *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input) On entry, an array of length N containing the sequence to be transformed.

WSAVE (input/output)
On entry, WSAVE must be an array of dimension $(4 * N + 15)$ or greater and must have been initialized by ZFFTI.

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NAME

zfftd - initialize the trigonometric weight and factor tables or compute the inverse Fast Fourier Transform of a double complex sequence.

SYNOPSIS

```
SUBROUTINE ZFFTD(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX X(*)  
DOUBLE PRECISION SCALE, Y(*), TRIGS(*), WORK(*)
```

```
SUBROUTINE ZFFTD_64(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N, IFAC(*), LWORK, IERR  
DOUBLE PRECISION SCALE, Y(*), TRIGS(*), WORK(*)  
DOUBLE COMPLEX X(*)
```

F95 INTERFACE

```
SUBROUTINE FFT(IOPT, N, [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT, N  
INTEGER, INTENT(IN), OPTIONAL :: LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
COMPLEX(8), INTENT(IN), DIMENSION(:) :: X  
REAL(8), INTENT(OUT), DIMENSION(:) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT_64(IOPT, N, [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT, N  
INTEGER(8), INTENT(IN), OPTIONAL :: LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
COMPLEX(8), INTENT(IN), DIMENSION(:) :: X  
REAL(8), INTENT(OUT), DIMENSION(:) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
```

```

INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>

void zfftd_ (int *iopt, int *n, double *scale, doublecomplex
            *x, double *y, double *trigs, int *ifac, double
            *work, int *lwork, int *ierr);

void zfftd_64_ (long *iopt, long *n, double *scale, doublecomplex
               *x, double *y, double *trigs, long
               *ifac, double *work, long *lwork, long *ierr);

```

PURPOSE

zfftd initializes the trigonometric weight and factor tables or computes the inverse Fast Fourier Transform of a double complex sequence as follows:

$$Y(k) = \text{scale} * \sum_{j=0}^{N-1} W * X(j)$$

where

k ranges from 0 to N-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

$W = \exp(\text{isign} * i * j * k * 2 * \pi / N)$

In complex-to-real transform of length N, the (N/2+1) complex input data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored. Furthermore, due to symmetries the imaginary of the component of X(0) and X(N/2) (if N is even in the latter) is assumed to be zero and is not referenced.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = 1 computes inverse FFT

N (input)

Integer specifying length of the input sequence X. N is most efficient when it is a product of small primes. N >= 0. Unchanged on exit.

SCALE (input)

Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) On entry, X is a double complex array whose first (N/2+1) elements are the input sequence to be transformed.

Y (output)
Double precision array of dimension at least N that contains the transform results. X and Y may be the same array starting at the same memory location. Otherwise, it is assumed that there is no overlap between X and Y in memory.

TRIGS (input/output)
Double precision array of length 2*N that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

IFAC (input/output)
Integer array of dimension at least 128 that contains the factors of N. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls where IOPT = 1. Unchanged on exit.

WORK (workspace)
Double precision array of dimension at least N. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)
Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)
On exit, integer IERR has one of the following values:
0 = normal return
-1 = IOPT is not 0 or 1
-2 = N < 0
-3 = (LWORK is not 0) and (LWORK is less than N)
-4 = memory allocation for workspace failed

SEE ALSO

fft

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NAME

zfftd2 - initialize the trigonometric weight and factor tables or compute the two-dimensional inverse Fast Fourier Transform of a two-dimensional double complex array.

SYNOPSIS

```
SUBROUTINE ZFFTD2(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX X(LDX, *)  
DOUBLE PRECISION SCALE, Y(LDY, *), TRIGS(*), WORK(*)
```

```
SUBROUTINE ZFFTD2_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX X(LDX, *)  
DOUBLE PRECISION SCALE, Y(LDY, *), TRIGS(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT2(IOPT, N1, [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT, N1  
INTEGER, INTENT(IN), OPTIONAL :: N2, LDX, LDY, LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
COMPLEX(8), INTENT(IN), DIMENSION(:,:) :: X  
REAL(8), INTENT(OUT), DIMENSION(:,:) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT2_64(IOPT, N1, [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT, N1
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N2, LDX, LDY, LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
COMPLEX(8), INTENT(IN), DIMENSION(:, :) :: X
REAL(8), INTENT(OUT), DIMENSION(:, :) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void zfftd2_(int *iopt, int *n1, int *n2, double *scale,
             doublecomplex *x, int *ldx, double *y, int *ldy,
             double *trigs, int *ifac, double *work, int
             *lwork, int *ierr);

void zfftd2_64_(long *iopt, long *n1, long *n2, double
               *scale, doublecomplex *x, long *ldx, double *y,
               long *ldy, double *trigs, long *ifac, double
               *work, long *lwork, long *ierr);

```

PURPOSE

zfftd2 initializes the trigonometric weight and factor tables or computes the two-dimensional inverse Fast Fourier Transform of a two-dimensional double complex array. In computing the two-dimensional FFT, one-dimensional FFTs are computed along the rows of the input array. One-dimensional FFTs are then computed along the columns of the intermediate results.

$$Y(k_1, k_2) = \text{scale} * \sum_{j_1=0}^{N_1-1} \sum_{j_2=0}^{N_2-1} W_2 * W_1 * X(j_1, j_2)$$

where

k₁ ranges from 0 to N₁-1 and k₂ ranges from 0 to N₂-1

i = sqrt(-1)

isign = 1 for inverse transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

In complex-to-real transform of length N₁, the (N₁/2+1) complex input data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table
 and factor table
 IOPT = 1 computes inverse FFT

N1 (input)

Integer specifying length of the transform in the first dimension. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)

Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. N2 >= 0. Unchanged on exit.

SCALE (input)

Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) X is a double complex array of dimensions (LDX, N2) that contains input data to be transformed.

LDX (input)

Leading dimension of X. LDX >= (N1/2 + 1) Unchanged on exit.

Y (output)

Y is a double precision array of dimensions (LDY, N2) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)

Leading dimension of Y. If X and Y are the same array, LDY = 2*LDX Else LDY >= 2*LDX and LDY must be even. Unchanged on exit.

TRIGS (input/output)

Double precision array of length 2*(N1+N2) that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 2*128 that contains the factors of N1 and N2. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

WORK (workspace)

Double precision array of dimension at least MAX(N1,2*N2) where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

0 = normal return

-1 = IOPT is not 0, 1

-2 = $N1 < 0$

-3 = $N2 < 0$

-4 = $(LDX < N1/2+1)$

-5 = LDY not equal $2*LDX$ when X and Y are same array

-6 = $(LDY < 2*LDX$ or LDY odd) when X and Y are same array

-7 = (LWORK not equal 0) and $(LWORK < MAX(N1, 2*N2))$

-8 = memory allocation failed

SEE ALSO

fft

CAUTIONS

On exit, output subarray $Y(1:LDY, 1:N2)$ is overwritten.

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NAME

zfftd3 - initialize the trigonometric weight and factor tables or compute the three-dimensional inverse Fast Fourier Transform of a three-dimensional double complex array.

SYNOPSIS

```
SUBROUTINE ZFFTD3(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,
IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),
LWORK, IERR
DOUBLE COMPLEX X(LDX1, LDX2, *)
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*), Y(LDY1, LDY2, *)
```

```
SUBROUTINE ZFFTD3_64(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,
IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),
LWORK, IERR
DOUBLE COMPLEX X(LDX1, LDX2, *)
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*), Y(LDY1, LDY2, *)
```

F95 INTERFACE

```
SUBROUTINE FFT3(IOPT, N1, [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1], LDY2,
TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT, N1, LDX2, LDY2
INTEGER, INTENT(IN), OPTIONAL :: N2, N3, LDX1, LDY1, LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
COMPLEX(8), INTENT(IN), DIMENSION(:,) :: X
REAL(8), INTENT(OUT), DIMENSION(:,) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT3_64(IOPT, N1, [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1], LDY2,
TRIGS, IFAC, WORK, [LWORK], IERR)
```

```

INTEGER(8), INTENT(IN) :: IOPT, N1, LDX2, LDY2
INTEGER(8), INTENT(IN), OPTIONAL :: N2, N3, LDX1, LDY1,
LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
COMPLEX(8), INTENT(IN), DIMENSION(:, :) :: X
REAL(8), INTENT(OUT), DIMENSION(:, :) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void zfftd3_ (int *iopt, int *n1, int *n2, int *n3, double
             *scale, doublecomplex *x, int *ldx1, int *ldx2,
             double *y, int *ldy1, int *ldy2, double *trigs,
             int *ifac, double *work, int *lwork, int *ierr);

void zfftd3_64_ (long *iopt, long *n1, long *n2, long *n3,
               double *scale, doublecomplex *x, long *ldx1, long
               *ldx2, double *y, long *ldy1, long *ldy2, double
               *trigs, long *ifac, double *work, long *lwork,
               long *ierr);

```

PURPOSE

zfftd3 initializes the trigonometric weight and factor tables or computes the three-dimensional inverse Fast Fourier Transform of a three-dimensional double complex array.

$$Y(k_1, k_2, k_3) = \text{scale} * \sum_{j_3=0}^{N_3-1} \sum_{j_2=0}^{N_2-1} \sum_{j_1=0}^{N_1-1} W_3 * W_2 * W_1 * X(j_1, j_2, j_3)$$

where

k₁ ranges from 0 to N₁-1; k₂ ranges from 0 to N₂-1 and k₃ ranges from 0 to N₃-1

i = sqrt(-1)

isign = 1 for inverse transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

W₃ = exp(isign*i*j₃*k₃*2*pi/N₃)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = +1 computes inverse FFT

N1 (input)

Integer specifying length of the transform in the first dimension. N₁ is most efficient when it is

a product of small primes. $N1 \geq 0$. Unchanged on exit.

N2 (input)

Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. $N2 \geq 0$. Unchanged on exit.

N3 (input)

Integer specifying length of the transform in the third dimension. N3 is most efficient when it is a product of small primes. $N3 \geq 0$. Unchanged on exit.

SCALE (input)

Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) X is a double complex array of dimensions (LDX1, LDX2, N3) that contains input data to be transformed.

LDX1 (input)

first dimension of X. $LDX1 \geq N1/2+1$ Unchanged on exit.

LDX2 (input)

second dimension of X. $LDX2 \geq N2$ Unchanged on exit.

Y (output)

Y is a double complex array of dimensions (LDY1, LDY2, N3) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY1 (input)

first dimension of Y. If X and Y are the same array, $LDY1 = 2*LDX1$ Else $LDY1 \geq 2*LDX1$ and LDY1 is even Unchanged on exit.

LDY2 (input)

second dimension of Y. If X and Y are the same array, $LDY2 = LDX2$ Else $LDY2 \geq N2$ Unchanged on exit.

TRIGS (input/output)

Double precision array of length $2*(N1+N2+N3)$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least $3*128$ that contains the factors of N1, N2 and N3. The fac-

tors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

WORK (workspace)

Double precision array of dimension at least $(\text{MAX}(N, 2*N2, 2*N3) + 16*N3) * \text{NCPUS}$ where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

- 0 = normal return
- 1 = IOPT is not 0 or 1
- 2 = N1 < 0
- 3 = N2 < 0
- 4 = N3 < 0
- 5 = (LDX1 < N1/2+1)
- 6 = (LDX2 < N2)
- 7 = LDY1 not equal 2*LDX1 when X and Y are same array
- 8 = (LDY1 < 2*LDX1) or (LDY1 is odd) when X and Y are not same array
- 9 = (LDY2 < N2) or (LDY2 not equal LDX2) when X and Y are same array
- 10 = (LWORK not equal 0) and ((LWORK < $\text{MAX}(N, 2*N2, 2*N3) + 16*N3) * \text{NCPUS}$)
- 11 = memory allocation failed

SEE ALSO

fft

CAUTIONS

On exit, output subarray Y(1:LDY1, 1:N2, 1:N3) is overwritten.

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NAME

zfftdm - initialize the trigonometric weight and factor tables or compute the one-dimensional inverse Fast Fourier Transform of a set of double complex data sequences stored in a two-dimensional array.

SYNOPSIS

```
SUBROUTINE ZFFTDM(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX X(LDX, *)  
DOUBLE PRECISION SCALE, Y(LDY, *), TRIGS(*), WORK(*)
```

```
SUBROUTINE ZFFTDM_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX X(LDX, *)  
DOUBLE PRECISION SCALE, Y(LDY,*), TRIGS(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFTM(IOPT, N1, [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT, N1  
INTEGER, INTENT(IN), OPTIONAL :: N2, LDX, LDY, LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
COMPLEX(8), INTENT(IN), DIMENSION(:,*) :: X  
REAL(8), INTENT(OUT), DIMENSION(:,*) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFTM_64(IOPT, N1, [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT, N1
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N2, LDX, LDY, LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
COMPLEX(8), INTENT(IN), DIMENSION(:, :) :: X
REAL(8), INTENT(OUT), DIMENSION(:, :) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void zfftdm_ (int *iopt, int *m, int *n, double *scale,
             doublecomplex *x, int *ldx, double *y, int *ldy,
             double *trigs, int *ifac, double *work, int
             *lwork, int *ierr);

void zfftdm_64_ (long *iopt, long *m, long *n, double
                *scale, doublecomplex *x, long *ldx, double *y,
                long *ldy, double *trigs, long *ifac, double
                *work, long *lwork, long *ierr);

```

PURPOSE

zfftdm initializes the trigonometric weight and factor tables or computes the one-dimensional inverse Fast Fourier Transform of a set of double complex data sequences stored in a two-dimensional array:

$$Y(k,l) = \text{scale} * \sum_{j=0}^{N1-1} W * X(j,l)$$

where

k ranges from 0 to N1-1 and l ranges from 0 to N2-1

i = sqrt(-1)

isign = 1 for inverse transform

W = exp(isign*i*j*k*2*pi/N1)

In complex-to-real transform of length N1, the (N1/2+1) complex input data points stored are the positive-frequency half of the spectrum of the Discrete Fourier Transform. The other half can be obtained through complex conjugation and therefore is not stored. Furthermore, due to symmetries the imaginary of the component of X(0,0:N2-1) and X(N1/2,0:N2-1) (if N1 is even in the latter) is assumed to be zero and is not referenced.

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = 1 computes inverse FFT

N1 (input)

Integer specifying length of the input sequences.

N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)

Integer specifying number of input sequences. N2 >= 0. Unchanged on exit.

SCALE (input)

Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) X is a double complex array of dimensions (LDX, N2) that contains the sequences to be transformed stored in its columns in X(0:N1/2, 0:N2-1).

LDX (input)

Leading dimension of X. LDX >= (N1/2+1) Unchanged on exit.

Y (output)

Y is a double precision array of dimensions (LDY, N2) that contains the transform results of the input sequences in Y(0:N1-1,0:N2-1). X and Y can be the same array starting at the same memory location, in which case the input sequences are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)

Leading dimension of Y. If X and Y are the same array, LDY = 2*LDX Else LDY >= N1 Unchanged on exit.

TRIGS (input/output)

double precision array of length 2*N1 that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 128 that contains the factors of N1. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1. Unchanged on exit.

WORK (workspace)

double precision array of dimension at least N1. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:
0 = normal return

-1 = IOPT is not 0 or 1
-2 = N1 < 0
-3 = N2 < 0
-4 = (LDX < N1/2+1)
-5 = (LDY < N1) or (LDY not equal 2*LDX when X and
Y are same array)
-6 = (LWORK not equal 0) and (LWORK < N1)
-7 = memory allocation failed

SEE ALSO

fft

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NAME

zfftf - compute the Fourier coefficients of a periodic sequence. The FFT operations are unnormalized, so a call of ZFFTF followed by a call of ZFFTB will multiply the input sequence by N.

SYNOPSIS

```
SUBROUTINE ZFFTF(N, X, WSAVE)
```

```
DOUBLE COMPLEX X(*)  
INTEGER N  
DOUBLE PRECISION WSAVE(*)
```

```
SUBROUTINE ZFFTF_64(N, X, WSAVE)
```

```
DOUBLE COMPLEX X(*)  
INTEGER*8 N  
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE F95_ZFFTF([N], X, WSAVE)
```

```
COMPLEX(8), DIMENSION(:) :: X  
INTEGER :: N  
REAL(8), DIMENSION(:) :: WSAVE
```

```
SUBROUTINE F95_ZFFTF_64([N], X, WSAVE)
```

```
COMPLEX(8), DIMENSION(:) :: X  
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zfftf(int n, doublecomplex *x, double *wsave);
```

```
void zfftf_64(long n, doublecomplex *x, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. These subroutines are most efficient when N is a product of small primes. $N \geq 0$.

X (input) On entry, an array of length N containing the sequence to be transformed.

WSAVE (input)
On entry, WSAVE must be an array of dimension $(4 * N + 15)$ or greater and must have been initialized by ZFFTI.

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NAME

zfffti - initialize the array WSAVE, which is used in both ZFFTF and ZFFTB.

SYNOPSIS

```
SUBROUTINE ZFFTI(N, WSAVE)
```

```
INTEGER N  
DOUBLE PRECISION WSAVE(*)
```

```
SUBROUTINE ZFFTI_64(N, WSAVE)
```

```
INTEGER*8 N  
DOUBLE PRECISION WSAVE(*)
```

F95 INTERFACE

```
SUBROUTINE ZFFTI(N, WSAVE)
```

```
INTEGER :: N  
REAL(8), DIMENSION(:) :: WSAVE
```

```
SUBROUTINE ZFFTI_64(N, WSAVE)
```

```
INTEGER(8) :: N  
REAL(8), DIMENSION(:) :: WSAVE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zffti(int n, double *wsave);
```

```
void zffti_64(long n, double *wsave);
```

ARGUMENTS

N (input) Length of the sequence to be transformed. N >= 0.

WSAVE (input/output)

On entry, an array of dimension $(4 * N + 15)$ or greater. ZFFTI needs to be called only once to initialize array WORK before calling ZFFTF and/or ZFFTB if N and WSAVE remain unchanged between these calls. Thus, subsequent transforms or inverse transforms of same size can be obtained faster than the first since they do not require initialization of the workspace.

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NAME

zfftopt - compute the length of the closest fast FFT

SYNOPSIS

```
INTEGER FUNCTION ZFFTOPT(LEN)
```

```
INTEGER LEN
```

```
INTEGER*8 FUNCTION ZFFTOPT_64(LEN)
```

```
INTEGER*8 LEN
```

F95 INTERFACE

```
INTEGER FUNCTION ZFFTOPT(LEN)
```

```
INTEGER :: LEN
```

```
INTEGER(8) FUNCTION ZFFTOPT_64(LEN)
```

```
INTEGER(8) :: LEN
```

C INTERFACE

```
#include <sunperf.h>
```

```
int zfftopt(int len);
```

```
long zfftopt_64(long len);
```

PURPOSE

zfftopt computes the length of the closest fast FFT. Fast Fourier transform algorithms, including those used in Performance Library, work best with vector lengths that are products of small primes. For example, an FFT of length $32=2**5$ will run faster than an FFT of prime length 31 because 32 is a product of small primes and 31 is not. If your application is such that you can taper or zero pad your vector to a larger length then this function may help you

select a better length and run your FFT faster.

ZFFTOPT will return an integer no smaller than the input argument N that is the closest number that is the product of small primes. ZFFTOPT will return 16 for an input of N=16 and return $18=2*3*3$ for an input of N=17.

Note that the length computed here is not guaranteed to be optimal, only to be a product of small primes. Also, the value returned may change as the underlying

FFTs become capable of handling larger primes. For example, passing in N=51 today will return $52=2*2*13$ rather than $51=3*17$ because the FFTs in Performance Library do not have fast radix 17 code. In the future, radix 17 code may be added

and then N=51 will return 51.

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NAME

zfftz - initialize the trigonometric weight and factor tables or compute the Fast Fourier transform (forward or inverse) of a double complex sequence.

SYNOPSIS

```
SUBROUTINE ZFFTZ(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX X(*), Y(*)  
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE ZFFTZ_64(IOPT, N, SCALE, X, Y, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N, IFAC(*), LWORK, IERR  
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*)  
DOUBLE COMPLEX X(*), Y(*)
```

F95 INTERFACE

```
SUBROUTINE FFT(IOPT, [N], [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT  
INTEGER, INTENT(IN), OPTIONAL :: N, LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
COMPLEX(8), INTENT(IN), DIMENSION(:) :: X  
COMPLEX(8), INTENT(OUT), DIMENSION(:) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT_64(IOPT, [N], [SCALE], X, Y, TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT  
INTEGER(8), INTENT(IN), OPTIONAL :: N, LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
COMPLEX(8), INTENT(IN), DIMENSION(:) :: X  
COMPLEX(8), INTENT(OUT), DIMENSION(:) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
```

```
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zfftz_ (int *iopt, int *n, double *scale, doublecomplex
            *x, doublecomplex *y, double *trigs, int *ifac,
            double *work, int *lwork, int *ierr);
```

```
void zfftz_64_ (long *iopt, long *n, double *scale, double
               lecomplex *x, doublecomplex *y, double *trigs,
               long *ifac, double *work, long *lwork, long
               *ierr);
```

PURPOSE

zfftz initializes the trigonometric weight and factor tables or computes the Fast Fourier transform (forward or inverse) of a double complex sequence as follows:

$$Y(k) = \text{scale} * \sum_{j=0}^{N-1} W * X(j)$$

where

k ranges from 0 to N-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

W = exp(isign*i*j*k*2*pi/N)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
IOPT = 0 computes the trigonometric weight table and factor table
IOPT = -1 computes forward FFT
IOPT = +1 computes inverse FFT

N (input)

Integer specifying length of the input sequence X. N is most efficient when it is a product of small primes. N >= 0. Unchanged on exit.

SCALE (input)

Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) On entry, X is a double complex array of dimension at least N that contains the sequence to be transformed.

Y (output)

Double complex array of dimension at least N that contains the transform results. X and Y may be the same array starting at the same memory location. Otherwise, it is assumed that there is no overlap between X and Y in memory.

TRIGS (input/output)

Double precision array of length 2*N that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 128 that contains the factors of N. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls where IOPT = 1 or IOPT = -1. Unchanged on exit.

WORK (workspace)

Double precision array of dimension at least 2*N. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:

0 = normal return
-1 = IOPT is not 0, 1 or -1
-2 = N < 0
-3 = (LWORK is not 0) and (LWORK is less than 2*N)
-4 = memory allocation for workspace failed

SEE ALSO

fft

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NAME

zfftz2 - initialize the trigonometric weight and factor tables or compute the two-dimensional Fast Fourier Transform (forward or inverse) of a two-dimensional double complex array.

SYNOPSIS

```
SUBROUTINE ZFFTZ2(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX X(LDX, *), Y(LDY, *)  
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE ZFFTZ2_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*)  
DOUBLE COMPLEX X(LDX, *), Y(LDY, *)
```

F95 INTERFACE

```
SUBROUTINE FFT2(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT  
INTEGER, INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
COMPLEX(8), INTENT(IN), DIMENSION(:,*) :: X  
COMPLEX(8), INTENT(OUT), DIMENSION(:,*) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFT2_64(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```

INTEGER(8), INTENT(IN) :: IOPT
INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
COMPLEX(8), INTENT(IN), DIMENSION(:, :) :: X
COMPLEX(8), INTENT(OUT), DIMENSION(:, :) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void zfftz2_ (int *iopt, int *n1, int *n2, double *scale,
             doublecomplex *x, int *ldx, doublecomplex *y, int
             *ldy, double *trigs, int *ifac, double *work, int
             *lwork, int *ierr);

void zfftz2_64_ (long *iopt, long *n1, long *n2, double
                *scale, doublecomplex *x, long *ldx, doublecomplex
                *y, long *ldy, double *trigs, long *ifac, double
                *work, long *lwork, long *ierr);

```

PURPOSE

zfftz2 initializes the trigonometric weight and factor tables or computes the two-dimensional Fast Fourier Transform (forward or inverse) of a two-dimensional double complex array. In computing the two-dimensional FFT, one-dimensional FFTs are computed along the columns of the input array. One-dimensional FFTs are then computed along the rows of the intermediate results.

$$Y(k_1, k_2) = \text{scale} * \sum_{j_2=0}^{N_2-1} \sum_{j_1=0}^{N_1-1} W_2 * W_1 * X(j_1, j_2)$$

where

k₁ ranges from 0 to N₁-1 and k₂ ranges from 0 to N₂-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT
 IOPT = +1 computes inverse FFT

N1 (input)

Integer specifying length of the transform in the first dimension. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on

exit.

N2 (input)

Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. $N2 \geq 0$. Unchanged on exit.

SCALE (input)

Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) X is a double complex array of dimensions (LDX, N2) that contains input data to be transformed.

LDX (input)

Leading dimension of X. $LDX \geq N1$ Unchanged on exit.

Y (output)

Y is a double complex array of dimensions (LDY, N2) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)

Leading dimension of Y. If X and Y are the same array, $LDY = LDX$ Else $LDY \geq N1$ Unchanged on exit.

TRIGS (input/output)

Double precision array of length $2*(N1+N2)$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least $2*128$ that contains the factors of N1 and N2. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

WORK (workspace)

Double precision array of dimension at least $2*MAX(N1,N2)*NCPUS$ where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)

Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)

On exit, integer IERR has one of the following values:
0 = normal return

-1 = IOPT is not 0, 1 or -1
-2 = N1 < 0
-3 = N2 < 0
-4 = (LDX < N1)
-5 = (LDY < N1) or (LDY not equal LDX when X and Y
are same array)
-6 = (LWORK not equal 0) and (LWORK <
2*MAX(N1,N2)*NCPUS)
-7 = memory allocation failed

SEE ALSO

fft

CAUTIONS

On exit, entire output array Y(1:LDY, 1:N2) is overwritten.

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NAME

zfftz3 - initialize the trigonometric weight and factor tables or compute the three-dimensional Fast Fourier Transform (forward or inverse) of a three-dimensional double complex array.

SYNOPSIS

```
SUBROUTINE ZFFTZ3(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,  
IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),  
LWORK, IERR  
DOUBLE COMPLEX X(LDX1, LDX2, *), Y(LDY1, LDY2, *)  
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE ZFFTZ3_64(IOPT, N1, N2, N3, SCALE, X, LDX1, LDX2, Y, LDY1, LDY2, TRIGS,  
IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, N3, LDX1, LDX2, LDY1, LDY2, IFAC(*),  
LWORK, IERR  
DOUBLE COMPLEX X(LDX1, LDX2, *), Y(LDY1, LDY2, *)  
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE FFT3(IOPT, [N1], [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1], LDY2,  
TRIGS, IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT, LDX2, LDY2  
INTEGER, INTENT(IN), OPTIONAL :: N1, N2, N3, LDX1, LDY1,  
LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
COMPLEX(8), INTENT(IN), DIMENSION(:,*) :: X  
COMPLEX(8), INTENT(OUT), DIMENSION(:,*) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER, INTENT(OUT) :: IERR
```

```

SUBROUTINE FFT3_64(IOPT, [N1], [N2], [N3], [SCALE], X, [LDX1], LDX2, Y, [LDY1],
LDY2, TRIGS, IFAC, WORK, [LWORK], IERR)

```

```

INTEGER(8), INTENT(IN) :: IOPT, LDX2, LDY2
INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, N3, LDX1, LDY1,
LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
COMPLEX(8), INTENT(IN), DIMENSION(:,:) :: X
COMPLEX(8), INTENT(OUT), DIMENSION(:,:) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>

void zfftz3_ (int *iopt, int *n1, int *n2, int *n3, double
             *scale, doublecomplex *x, int *ldx1, int *ldx2,
             doublecomplex *y, int *ldy1, int *ldy2, double
             *trigs, int *ifac, double *work, int *lwork, int
             *ierr);

void zfftz3_64_ (long *iopt, long *n1, long *n2, long *n3,
                double *scale, doublecomplex *x, long *ldx1, long
                *ldx2, doublecomplex *y, long *ldy1, long *ldy2,
                double *trigs, long *ifac, double *work, long
                *lwork, long *ierr);

```

PURPOSE

zfftz3 initializes the trigonometric weight and factor tables or computes the three-dimensional Fast Fourier Transform (forward or inverse) of a three-dimensional double complex array.

$$Y(k_1, k_2, k_3) = \text{scale} * \sum_{j_3=0}^{N_3-1} \sum_{j_2=0}^{N_2-1} \sum_{j_1=0}^{N_1-1} W_3 * W_2 * W_1 * X(j_1, j_2, j_3)$$

where

k₁ ranges from 0 to N₁-1; k₂ ranges from 0 to N₂-1 and k₃ ranges from 0 to N₃-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

W₁ = exp(isign*i*j₁*k₁*2*pi/N₁)

W₂ = exp(isign*i*j₂*k₂*2*pi/N₂)

W₃ = exp(isign*i*j₃*k₃*2*pi/N₃)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
IOPT = 0 computes the trigonometric weight table
and factor table

IOPT = -1 computes forward FFT

IOPT = +1 computes inverse FFT

N1 (input)
Integer specifying length of the transform in the first dimension. N1 is most efficient when it is a product of small primes. N1 \geq 0. Unchanged on exit.

N2 (input)
Integer specifying length of the transform in the second dimension. N2 is most efficient when it is a product of small primes. N2 \geq 0. Unchanged on exit.

N3 (input)
Integer specifying length of the transform in the third dimension. N3 is most efficient when it is a product of small primes. N3 \geq 0. Unchanged on exit.

SCALE (input)
Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) X is a double complex array of dimensions (LDX1, LDX2, N3) that contains input data to be transformed.

LDX1 (input)
first dimension of X. LDX1 \geq N1 Unchanged on exit.

LDX2 (input)
second dimension of X. LDX2 \geq N2 Unchanged on exit.

Y (output)
Y is a double complex array of dimensions (LDY1, LDY2, N3) that contains the transform results. X and Y can be the same array starting at the same memory location, in which case the input data are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY1 (input)
first dimension of Y. If X and Y are the same array, LDY1 = LDX1 Else LDY1 \geq N1 Unchanged on exit.

LDY2 (input)
second dimension of Y. If X and Y are the same array, LDY2 = LDX2 Else LDY2 \geq N2 Unchanged on exit.

TRIGS (input/output)
Double precision array of length $2*(N1+N2+N3)$ that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

IFAC (input/output)

Integer array of dimension at least 3×128 that contains the factors of N_1 , N_2 and N_3 . The factors are computed when the routine is called with $IOPT = 0$ and they are used in subsequent calls when $IOPT = 1$ or $IOPT = -1$. Unchanged on exit.

WORK (workspace)

Double precision array of dimension at least $(2 \times \text{MAX}(N, N_2, N_3) + 32 \times N_3) \times \text{NCPUS}$ where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see `LWORK`).

LWORK (input)

Integer specifying workspace size. If $\text{LWORK} = 0$, the routine will allocate its own workspace.

IERR (output)

On exit, integer `IERR` has one of the following values:

0 = normal return

-1 = $IOPT$ is not 0, 1 or -1

-2 = $N_1 < 0$

-3 = $N_2 < 0$

-4 = $N_3 < 0$

-5 = ($LDX_1 < N_1$)

-6 = ($LDX_2 < N_2$)

-7 = ($LDY_1 < N_1$) or (LDY_1 not equal LDX_1 when X and Y are same array)

-8 = ($LDY_2 < N_2$) or (LDY_2 not equal LDX_2 when X and Y are same array)

-9 = (LWORK not equal 0) and ($\text{LWORK} < (2 \times \text{MAX}(N, N_2, N_3) + 16 \times N_3) \times \text{NCPUS}$)

-10 = memory allocation failed

SEE ALSO

`fft`

CAUTIONS

On exit, output subarray $Y(1:LDY_1, 1:N_2, 1:N_3)$ is overwritten.

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NAME

zfftzm - initialize the trigonometric weight and factor tables or compute the one-dimensional Fast Fourier Transform (forward or inverse) of a set of data sequences stored in a two-dimensional double complex array.

SYNOPSIS

```
SUBROUTINE ZFFTZM(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE COMPLEX X(LDX, *), Y(LDY, *)  
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*)
```

```
SUBROUTINE ZFFTZM_64(IOPT, N1, N2, SCALE, X, LDX, Y, LDY, TRIGS, IFAC, WORK, LWORK, IERR)
```

```
INTEGER*8 IOPT, N1, N2, LDX, LDY, IFAC(*), LWORK, IERR  
DOUBLE PRECISION SCALE, TRIGS(*), WORK(*)  
DOUBLE COMPLEX X(LDX, *), Y(LDY, *)
```

F95 INTERFACE

```
SUBROUTINE FFTM(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS,  
IFAC, WORK, [LWORK], IERR)
```

```
INTEGER, INTENT(IN) :: IOPT  
INTEGER, INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK  
REAL(8), INTENT(IN), OPTIONAL :: SCALE  
COMPLEX(8), INTENT(IN), DIMENSION(:,*) :: X  
COMPLEX(8), INTENT(OUT), DIMENSION(:,*) :: Y  
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS  
INTEGER, INTENT(INOUT), DIMENSION(:) :: IFAC  
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK  
INTEGER, INTENT(OUT) :: IERR
```

```
SUBROUTINE FFTM_64(IOPT, [N1], [N2], [SCALE], X, [LDX], Y, [LDY], TRIGS, IFAC, WORK,  
[LWORK], IERR)
```

```
INTEGER(8), INTENT(IN) :: IOPT
```

```

INTEGER(8), INTENT(IN), OPTIONAL :: N1, N2, LDX, LDY, LWORK
REAL(8), INTENT(IN), OPTIONAL :: SCALE
COMPLEX(8), INTENT(IN), DIMENSION(:, :) :: X
COMPLEX(8), INTENT(OUT), DIMENSION(:, :) :: Y
REAL(8), INTENT(INOUT), DIMENSION(:) :: TRIGS
INTEGER(8), INTENT(INOUT), DIMENSION(:) :: IFAC
REAL(8), INTENT(OUT), DIMENSION(:) :: WORK
INTEGER(8), INTENT(OUT) :: IERR

```

C INTERFACE

```

#include <sunperf.h>
void zfftzm_ (int *iopt, int *m, int *n, double *scale,
             doublecomplex *x, int *ldx, doublecomplex *y, int
             *ldy, double *trigs, int *ifac, double *work, int
             *lwork, int *ierr);

void zfftzm_64_ (long *iopt, long *m, long *n, double
                *scale, doublecomplex *x, long *ldx, doublecomplex
                *y, long *ldy, double *trigs, long *ifac, double
                *work, long *lwork, long *ierr);

```

PURPOSE

zfftzm initializes the trigonometric weight and factor tables or computes the one-dimensional Fast Fourier Transform (forward or inverse) of a set of data sequences stored in a two-dimensional double complex array:

$$Y(k,l) = \sum_{j=0}^{N1-1} W * X(j,l)$$

where

k ranges from 0 to N1-1 and l ranges from 0 to N2-1

i = sqrt(-1)

isign = 1 for inverse transform or -1 for forward transform

W = exp(isign*i*j*k*2*pi/N1)

ARGUMENTS

IOPT (input)

Integer specifying the operation to be performed:
 IOPT = 0 computes the trigonometric weight table and factor table
 IOPT = -1 computes forward FFT
 IOPT = +1 computes inverse FFT

N1 (input)

Integer specifying length of the input sequences. N1 is most efficient when it is a product of small primes. N1 >= 0. Unchanged on exit.

N2 (input)

Integer specifying number of input sequences. N2 >= 0. Unchanged on exit.

SCALE (input)
 Double precision scalar by which transform results are scaled. Unchanged on exit. SCALE is defaulted to 1.0D0 for F95 INTERFACE.

X (input) X is a double complex array of dimensions (LDX, N2) that contains the sequences to be transformed stored in its columns.

LDX (input)
 Leading dimension of X. LDX >= N1 Unchanged on exit.

Y (output)
 Y is a double complex array of dimensions (LDY, N2) that contains the transform results of the input sequences. X and Y can be the same array starting at the same memory location, in which case the input sequences are overwritten by their transform results. Otherwise, it is assumed that there is no overlap between X and Y in memory.

LDY (input)
 Leading dimension of Y. If X and Y are the same array, LDY = LDX Else LDY >= N1 Unchanged on exit.

TRIGS (input/output)
 Double precision array of length 2*N1 that contains the trigonometric weights. The weights are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

IFAC (input/output)
 Integer array of dimension at least 128 that contains the factors of N1. The factors are computed when the routine is called with IOPT = 0 and they are used in subsequent calls when IOPT = 1 or IOPT = -1. Unchanged on exit.

WORK (workspace)
 Double precision array of dimension at least 2*N1*NCPUS where NCPUS is the number of threads used to execute the routine. The user can also choose to have the routine allocate its own workspace (see LWORK).

LWORK (input)
 Integer specifying workspace size. If LWORK = 0, the routine will allocate its own workspace.

IERR (output)
 On exit, integer IERR has one of the following values:
 0 = normal return
 -1 = IOPT is not 0, 1 or -1
 -2 = N1 < 0
 -3 = N2 < 0
 -4 = (LDX < N1)
 -5 = (LDY < N1) or (LDY not equal LDX when X and Y are same array)

-6 = (LWORK not equal 0) and (LWORK < 2*N1*NCPUS)
-7 = memory allocation failed

SEE ALSO

fft

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NAME

zgbbrd - reduce a complex general m-by-n band matrix A to real upper bidiagonal form B by a unitary transformation

SYNOPSIS

```
SUBROUTINE ZGBBRD(VECT, M, N, NCC, KL, KU, AB, LDAB, D, E, Q, LDQ,  
PT, LDPT, C, LDC, WORK, RWORK, INFO)
```

```
CHARACTER * 1 VECT  
DOUBLE COMPLEX AB(LDAB,*), Q(LDQ,*), PT(LDPT,*), C(LDC,*),  
WORK(*)  
INTEGER M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
DOUBLE PRECISION D(*), E(*), RWORK(*)
```

```
SUBROUTINE ZGBBRD_64(VECT, M, N, NCC, KL, KU, AB, LDAB, D, E, Q, LDQ,  
PT, LDPT, C, LDC, WORK, RWORK, INFO)
```

```
CHARACTER * 1 VECT  
DOUBLE COMPLEX AB(LDAB,*), Q(LDQ,*), PT(LDPT,*), C(LDC,*),  
WORK(*)  
INTEGER*8 M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
DOUBLE PRECISION D(*), E(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GBBRD(VECT, M, [N], [NCC], KL, KU, AB, [LDAB], D, E, Q,  
[LDQ], PT, [LDPT], C, [LDC], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: AB, Q, PT, C  
INTEGER :: M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO  
REAL(8), DIMENSION(:) :: D, E, RWORK
```

```
SUBROUTINE GBBRD_64(VECT, M, [N], [NCC], KL, KU, AB, [LDAB], D, E,  
Q, [LDQ], PT, [LDPT], C, [LDC], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: AB, Q, PT, C  
INTEGER(8) :: M, N, NCC, KL, KU, LDAB, LDQ, LDPT, LDC, INFO
```

```
REAL(8), DIMENSION(:) :: D, E, RWORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgbbrd(char vect, int m, int n, int ncc, int kl, int ku, doublecomplex *ab, int ldab, double *d, double *e, doublecomplex *q, int ldq, doublecomplex *pt, int ldpt, doublecomplex *c, int ldc, int *info);
```

```
void zgbbrd_64(char vect, long m, long n, long ncc, long kl, long ku, doublecomplex *ab, long ldab, double *d, double *e, doublecomplex *q, long ldq, doublecomplex *pt, long ldpt, doublecomplex *c, long ldc, long *info);
```

PURPOSE

zgbbrd reduces a complex general m-by-n band matrix A to real upper bidiagonal form B by a unitary transformation: $Q' * A * P = B$.

The routine computes B, and optionally forms Q or P', or computes $Q'*C$ for a given matrix C.

ARGUMENTS

VECT (input)

Specifies whether or not the matrices Q and P' are to be formed. = 'N': do not form Q or P';

= 'Q': form Q only;

= 'P': form P' only;

= 'B': form both.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NCC (input)

The number of columns of the matrix C. $NCC \geq 0$.

KL (input)

The number of subdiagonals of the matrix A. $KL \geq 0$.

KU (input)

The number of superdiagonals of the matrix A. $KU \geq 0$.

AB (input/output)

On entry, the m-by-n band matrix A, stored in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array AB as follows: $AB(ku+1+i-j, j) = A(i, j)$ for $\max(1, j-ku) \leq i \leq \min(m, j+kl)$. On exit, A is overwritten by values generated during the reduction.

LDAB (input)
The leading dimension of the array A. LDAB \geq KL+KU+1.

D (output)
The diagonal elements of the bidiagonal matrix B.

E (output)
The superdiagonal elements of the bidiagonal matrix B.

Q (output)
If VECT = 'Q' or 'B', the m-by-m unitary matrix Q.
If VECT = 'N' or 'P', the array Q is not referenced.

LDQ (input)
The leading dimension of the array Q. LDQ \geq max(1,M) if VECT = 'Q' or 'B'; LDQ \geq 1 otherwise.

PT (output)
If VECT = 'P' or 'B', the n-by-n unitary matrix P'. If VECT = 'N' or 'Q', the array PT is not referenced.

LDPT (input)
The leading dimension of the array PT. LDPT \geq max(1,N) if VECT = 'P' or 'B'; LDPT \geq 1 otherwise.

C (input/output)
On entry, an m-by-ncc matrix C. On exit, C is overwritten by Q'*C. C is not referenced if NCC = 0.

LDC (input)
The leading dimension of the array C. LDC \geq max(1,M) if NCC > 0; LDC \geq 1 if NCC = 0.

WORK (workspace)
dimension(MAX(M,N))

RWORK (workspace)
dimension(MAX(M,N))

INFO (output)
= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

zgbcon - estimate the reciprocal of the condition number of a complex general band matrix A, in either the 1-norm or the infinity-norm,

SYNOPSIS

```
SUBROUTINE ZGBCON(NORM, N, KL, KU, A, LDA, IPIVOT, ANORM,  
                 RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, KL, KU, LDA, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZGBCON_64(NORM, N, KL, KU, A, LDA, IPIVOT, ANORM,  
                    RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, KL, KU, LDA, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GBCON(NORM, [N], KL, KU, A, [LDA], IPIVOT, ANORM,  
                RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, KL, KU, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE GBCON_64(NORM, [N], KL, KU, A, [LDA], IPIVOT, ANORM,  
                   RCOND, [WORK], [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: NORM
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: N, KL, KU, LDA, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zgbcon(char norm, int n, int kl, int ku, doublecomplex
            *a, int lda, int *ipivot, double anorm, double
            *rcond, int *info);

void zgbcon_64(char norm, long n, long kl, long ku, doublecomplex
              *a, long lda, long *ipivot, double
              anorm, double *rcond, long *info);

```

PURPOSE

zgbcon estimates the reciprocal of the condition number of a complex general band matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by ZGBTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)
 Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
 = '1' or 'O': 1-norm;
 = 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)
 The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
 The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input) Details of the LU factorization of the band matrix A, as computed by ZGBTRF. U is stored as an upper triangular band matrix with $KL+KU$ superdiagonals in rows 1 to $KL+KU+1$, and the multipliers used during the factorization are stored in rows $KL+KU+2$ to $2*KL+KU+1$.

LDA (input)
 The leading dimension of the array A. $LDA \geq$

$2*KL+KU+1$.

IPIVOT (input)

The pivot indices; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension($2*N$)

WORK2 (workspace)

dimension (N)

INFO (output)

= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

zgbequ - compute row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number

SYNOPSIS

```
SUBROUTINE ZGBEQU(M, N, KL, KU, A, LDA, R, C, ROWCND,  
                 COLCND, AMAX, INFO)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER M, N, KL, KU, LDA, INFO  
DOUBLE PRECISION ROWCND, COLCND, AMAX  
DOUBLE PRECISION R(*), C(*)
```

```
SUBROUTINE ZGBEQU_64(M, N, KL, KU, A, LDA, R, C, ROWCND,  
                   COLCND, AMAX, INFO)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 M, N, KL, KU, LDA, INFO  
DOUBLE PRECISION ROWCND, COLCND, AMAX  
DOUBLE PRECISION R(*), C(*)
```

F95 INTERFACE

```
SUBROUTINE GBEQU([M], [N], KL, KU, A, [LDA], R, C,  
                ROWCND, COLCND, AMAX, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, KL, KU, LDA, INFO  
REAL(8) :: ROWCND, COLCND, AMAX  
REAL(8), DIMENSION(:) :: R, C
```

```
SUBROUTINE GBEQU_64([M], [N], KL, KU, A, [LDA], R, C,  
                  ROWCND, COLCND, AMAX, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, KL, KU, LDA, INFO  
REAL(8) :: ROWCND, COLCND, AMAX  
REAL(8), DIMENSION(:) :: R, C
```

C INTERFACE

```

#include <sunperf.h>

void zgbequ(int m, int n, int kl, int ku, doublecomplex *a,
            int lda, double *r, double *c, double *rowcnd,
            double *colcnd, double *amax, int *info);
void zgbequ_64(long m, long n, long kl, long ku, doublecom-
               plex *a, long lda, double *r, double *c, double
               *rowcnd, double *colcnd, double *amax, long
               *info);

```

PURPOSE

zgbequ computes row and column scalings intended to equilibrate an M-by-N band matrix A and reduce its condition number. R returns the row scale factors and C the column scale factors, chosen to try to make the largest element in each row and column of the matrix B with elements $B(i,j)=R(i)*A(i,j)*C(j)$ have absolute value 1.

R(i) and C(j) are restricted to be between SMLNUM = smallest safe number and BIGNUM = largest safe number. Use of these scaling factors is not guaranteed to reduce the condition number of A but works well in practice.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input) The band matrix A, stored in rows 1 to KL+KU+1. The j-th column of A is stored in the j-th column of the array A as follows: $A(ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$.

LDA (input)
The leading dimension of the array A. $LDA \geq KL+KU+1$.

R (output)
If INFO = 0, or INFO > M, R contains the row scale factors for A.

C (output)
If INFO = 0, C contains the column scale factors for A.

ROWCND (output)
If INFO = 0 or INFO > M, ROWCND contains the ratio

of the smallest $R(i)$ to the largest $R(i)$. If $ROWCND \geq 0.1$ and $AMAX$ is neither too large nor too small, it is not worth scaling by R .

COLCND (output)

If $INFO = 0$, $COLCND$ contains the ratio of the smallest $C(i)$ to the largest $C(i)$. If $COLCND \geq 0.1$, it is not worth scaling by C .

AMAX (output)

Absolute value of largest matrix element. If $AMAX$ is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, and i is
<= M : the i -th row of A is exactly zero
> M : the $(i-M)$ -th column of A is exactly zero

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NAME

zgbmv - perform one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A' x + \beta y$, or $y := \alpha \text{conjg}(A') x + \beta y$

SYNOPSIS

```
SUBROUTINE ZGBMV(TRANSA, M, N, KL, KU, ALPHA, A, LDA, X, INCX,
                BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), X(*), Y(*)
INTEGER M, N, KL, KU, LDA, INCX, INCY
```

```
SUBROUTINE ZGBMV_64(TRANSA, M, N, KL, KU, ALPHA, A, LDA, X,
                  INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), X(*), Y(*)
INTEGER*8 M, N, KL, KU, LDA, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE GBMV([TRANSA], [M], [N], KL, KU, ALPHA, A, [LDA], X,
               [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:) :: X, Y
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER :: M, N, KL, KU, LDA, INCX, INCY
```

```
SUBROUTINE GBMV_64([TRANSA], [M], [N], KL, KU, ALPHA, A, [LDA],
                  X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:) :: X, Y
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: M, N, KL, KU, LDA, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>

void zgbmv(char transa, int m, int n, int kl, int ku, doublecomplex *alpha, doublecomplex *a, int lda, doublecomplex *x, int incx, doublecomplex *beta, doublecomplex *y, int incy);

void zgbmv_64(char transa, long m, long n, long kl, long ku, doublecomplex *alpha, doublecomplex *a, long lda, doublecomplex *x, long incx, doublecomplex *beta, doublecomplex *y, long incy);
```

PURPOSE

zgbmv performs one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A^T x + \beta y$, or $y := \alpha \text{conjg}(A) x + \beta y$ where α and β are scalars, x and y are vectors and A is an m by n band matrix, with kl sub-diagonals and ku super-diagonals.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $y := \alpha A x + \beta y$.

TRANSA = 'T' or 't' $y := \alpha A^T x + \beta y$.

TRANSA = 'C' or 'c' $y := \alpha \text{conjg}(A) x + \beta y$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix A. M must be at least zero. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. N must be at least zero. Unchanged on exit.

KL (input)

On entry, KL specifies the number of sub-diagonals of the matrix A. KL must satisfy $0 \leq KL$. Unchanged on exit.

KU (input)

On entry, KU specifies the number of super-diagonals of the matrix A. KU must satisfy $0 \leq KU$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α .

Unchanged on exit.

A (input)

Before entry, the leading (kl + ku + 1) by n part of the array A must contain the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (ku + 1) of the array, the first super-diagonal starting at position 2 in row ku, the first sub-diagonal starting at position 1 in row (ku + 2), and so on. Elements in the array A that do not correspond to elements in the band matrix (such as the top left ku by ku triangle) are not referenced. The following program segment will transfer a band matrix from conventional full matrix storage to band storage:

```
      DO 20, J = 1, N
        K = KU + 1 - J
        DO 10, I = MAX( 1, J - KU ), MIN( M, J + KL
          )
          A( K + I, J ) = matrix( I, J )
10      CONTINUE
20     CONTINUE
```

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA must be at least (kl + ku + 1). Unchanged on exit.

X (input)

(1 + (n - 1) * abs(INCX)) when TRANSA = 'N' or 'n' and at least (1 + (m - 1) * abs(INCX)) otherwise. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

(1 + (m - 1) * abs(INCY)) when TRANSA = 'N' or 'n' and at least (1 + (n - 1) * abs(INCY)) otherwise. Before entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

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NAME

zgbtrfs - improve the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZGBRFS(TRANSA, N, KL, KU, NRHS, A, LDA, AF, LDAF,
  IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZGBRFS_64(TRANSA, N, KL, KU, NRHS, A, LDA, AF, LDAF,
  IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER*8 N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GBRFS([TRANSA], [N], KL, KU, [NRHS], A, [LDA], AF,
  [LDAF], IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2],
  [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE GBRFS_64([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
```

```
AF, [LDAF], IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, AF, B, X  
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgbrfs(char transa, int n, int kl, int ku, int nrhs,  
doublecomplex *a, int lda, doublecomplex *af, int  
ldaf, int *ipivot, doublecomplex *b, int ldb,  
doublecomplex *x, int ldx, double *ferr, double  
*berr, int *info);
```

```
void zgbrfs_64(char transa, long n, long kl, long ku, long  
nrhs, doublecomplex *a, long lda, doublecomplex  
*af, long ldaf, long *ipivot, doublecomplex *b,  
long ldb, doublecomplex *x, long ldx, double  
*ferr, double *berr, long *info);
```

PURPOSE

zgbrfs improves the computed solution to a system of linear equations when the coefficient matrix is banded, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{*T} * X = B$ (Transpose)
= 'C': $A^{*H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)

The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)

The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The original band matrix A, stored in rows 1 to $KL+KU+1$. The j-th column of A is stored in the

j-th column of the array A as follows: $A(ku+1+i-j, j) = A(i, j)$ for $\max(1, j-ku) \leq i \leq \min(n, j+kl)$.

LDA (input)

The leading dimension of the array A. LDA \geq KL+KU+1.

AF (input)

Details of the LU factorization of the band matrix A, as computed by ZGBTRF. U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1.

LDAF (input)

The leading dimension of the array AF. LDAF \geq 2*KL*KU+1.

IPIVOT (input)

The pivot indices from ZGBTRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)

On entry, the solution matrix X, as computed by ZGBTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zgbsv - compute the solution to a complex system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE ZGBSV(N, KL, KU, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZGBSV_64(N, KL, KU, NRHS, A, LDA, IPIVOT, B, LDB,  
INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GBSV([N], KL, KU, [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GBSV_64([N], KL, KU, [NRHS], A, [LDA], IPIVOT, B,  
[LDB], [INFO])
```

```
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zgbsv(int n, int kl, int ku, int nrhs, doublecomplex
          *a, int lda, int *ipivot, doublecomplex *b, int
          ldb, int *info);

void zgbsv_64(long n, long kl, long ku, long nrhs, double-
             lecomplex *a, long lda, long *ipivot, doublecom-
             plex *b, long ldb, long *info);

```

PURPOSE

zgbsv computes the solution to a complex system of linear equations $A * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices.

The LU decomposition with partial pivoting and row interchanges is used to factor A as $A = L * U$, where L is a product of permutation and unit lower triangular matrices with KL subdiagonals, and U is upper triangular with KL+KU superdiagonals. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array A as follows:
 $A(KL+KU+1+i-j, j) = A(i, j)$ for $\max(1, j-KU) \leq i \leq \min(N, j+KL)$
 On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDA (input)
The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (output)

The pivot indices that define the permutation matrix P; row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)

On entry, the N-by-NRHS right hand side matrix B.
On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and the solution has not been computed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when M = N = 6, KL = 2, KU = 1:

On entry:

On exit:

	*	*	*	+	+	+		*	*	*	u14	u25		
u36								*	*		u13	u24	u35	
u46								*			u12	u23	u34	u45
u56	a11	a22	a33	a44	a55	a66		u11	u22	u33	u44	u55		
u66	a21	a32	a43	a54	a65	*		m21	m32	m43	m54	m65		
*														
*	a31	a42	a53	a64	*	*		m31	m42	m53	m64	*		
*														

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U because of fill-in resulting from the row interchanges.

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NAME

zgbsvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE ZGBSVX(FACT, TRANSA, N, KL, KU, NRHS, A, LDA, AF,
                 LDAF, IPIVOT, EQUED, R, C, B, LDB, X, LDX, RCOND, FERR,
                 BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION R(*), C(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZGBSVX_64(FACT, TRANSA, N, KL, KU, NRHS, A, LDA, AF,
                   LDAF, IPIVOT, EQUED, R, C, B, LDB, X, LDX, RCOND, FERR,
                   BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER*8 N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION R(*), C(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GBSVX(FACT, [TRANSA], [N], KL, KU, [NRHS], A, [LDA],
               AF, [LDAF], IPIVOT, EQUED, R, C, B, [LDB], X, [LDX],
               RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```

REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: R, C, FERR, BERR, WORK2

SUBROUTINE GBSVX_64(FACT, [TRANSA], [N], KL, KU, [NRHS], A,
  [LDA], AF, [LDAF], IPIVOT, EQUED, R, C, B, [LDB], X, [LDX],
  RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: R, C, FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zgbsvx(char fact, char transa, int n, int kl, int ku,
  int nrhs, doublecomplex *a, int lda, doublecomplex
  *af, int ldaf, int *ipivot, char equed, double *r,
  double *c, doublecomplex *b, int ldb, doublecom-
  plex *x, int ldx, double *rcond, double *ferr,
  double *berr, int *info);

void zgbsvx_64(char fact, char transa, long n, long kl, long
  ku, long nrhs, doublecomplex *a, long lda, doub-
  lecomplex *af, long ldaf, long *ipivot, char
  equed, double *r, double *c, doublecomplex *b,
  long ldb, doublecomplex *x, long ldx, double
  *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zgbsvx uses the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$, where A is a band matrix of order N with KL subdiagonals and KU superdiagonals, and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed by this subroutine:

1. If FACT = 'E', real scaling factors are computed to equilibrate

the system:

TRANS = 'N': $\text{diag}(R) * A * \text{diag}(C) * \text{inv}(\text{diag}(C)) * X = \text{diag}(R) * B$

TRANS = 'T': $(\text{diag}(R) * A * \text{diag}(C))^{**T} * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

TRANS = 'C': $(\text{diag}(R) * A * \text{diag}(C))^{**H} * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A, but if equilibration is used, A is

overwritten by $\text{diag}(R)*A*\text{diag}(C)$ and B by $\text{diag}(R)*B$ (if $\text{TRANS}='N'$)
or $\text{diag}(C)*B$ (if $\text{TRANS} = 'T'$ or $'C'$).

2. If $\text{FACT} = 'N'$ or $'E'$, the LU decomposition is used to factor the

matrix A (after equilibration if $\text{FACT} = 'E'$) as

$$A = L * U,$$

where L is a product of permutation and unit lower triangular

matrices with KL subdiagonals, and U is upper triangular with

KL+KU superdiagonals.

3. If some $U(i,i)=0$, so that U is exactly singular, then the routine

returns with $\text{INFO} = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

$\text{INFO} = N+1$ is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form

of A.

5. Iterative refinement is applied to improve the computed solution

matrix and calculate error bounds and backward error estimates

for it.

6. If equilibration was used, the matrix X is premultiplied by

$\text{diag}(C)$ (if $\text{TRANS} = 'N'$) or $\text{diag}(R)$ (if $\text{TRANS} = 'T'$ or $'C'$) so

that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = $'F'$: On entry, AF and IPIVOT contain the factored form of A. If EQUED is not $'N'$, the matrix A has been equilibrated with scaling factors given by R and C. A, AF, and IPIVOT are not modified. = $'N'$: The matrix A will be copied to AF and factored.

= $'E'$: The matrix A will be equilibrated if necessary, then copied to AF and factored.

TRANSA (input)

Specifies the form of the system of equations. =

'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)
On entry, the matrix A in band storage, in rows 1 to $KL+KU+1$. The j-th column of A is stored in the j-th column of the array A as follows: $A(KU+1+i-j, j) = A(i, j)$ for $\max(1, j-KU) \leq i \leq \min(N, j+kl)$

If FACT = 'F' and EQUED is not 'N', then A must have been equilibrated by the scaling factors in R and/or C. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if EQUED .ne. 'N', A is scaled as follows:
EQUED = 'R': $A := \text{diag}(R) * A$
EQUED = 'C': $A := A * \text{diag}(C)$
EQUED = 'B': $A := \text{diag}(R) * A * \text{diag}(C)$.

LDA (input)
The leading dimension of the array A. $LDA \geq KL+KU+1$.

AF (input or output)
If FACT = 'F', then AF is an input argument and on entry contains details of the LU factorization of the band matrix A, as computed by ZGBTRF. U is stored as an upper triangular band matrix with $KL+KU$ superdiagonals in rows 1 to $KL+KU+1$, and the multipliers used during the factorization are stored in rows $KL+KU+2$ to $2*KL+KU+1$. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns details of the LU factorization of A.

If FACT = 'E', then AF is an output argument and on exit returns details of the LU factorization of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF \geq 2*KL+KU+1.

IPIVOT (input)

If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the factorization $A = L*U$ as computed by ZGBTRF; row i of the matrix was interchanged with row IPIVOT(i).

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = L*U$ of the original matrix A.

If FACT = 'E', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = L*U$ of the equilibrated matrix A.

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').

= 'R': Row equilibration, i.e., A has been premultiplied by diag(R). = 'C': Column equilibration, i.e., A has been postmultiplied by diag(C). = 'B': Both row and column equilibration, i.e., A has been replaced by $\text{diag}(R) * A * \text{diag}(C)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

R (input or output)

The row scale factors for A. If EQUED = 'R' or 'B', A is multiplied on the left by diag(R); if EQUED = 'N' or 'C', R is not accessed. R is an input argument if FACT = 'F'; otherwise, R is an output argument. If FACT = 'F' and EQUED = 'R' or 'B', each element of R must be positive.

C (input or output)

The column scale factors for A. If EQUED = 'C' or 'B', A is multiplied on the right by diag(C); if EQUED = 'N' or 'R', C is not accessed. C is an input argument if FACT = 'F'; otherwise, C is an output argument. If FACT = 'F' and EQUED = 'C' or 'B', each element of C must be positive.

B (input/output)

On entry, the right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if TRANSA = 'N' and EQUED = 'R' or 'B', B is overwritten by $\text{diag}(R)*B$; if TRANSA = 'T' or 'C' and EQUED = 'C' or 'B', B is overwritten by $\text{diag}(C)*B$.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations.

Note that A and B are modified on exit if EQUED .ne. 'N', and the solution to the equilibrated system is $\text{inv}(\text{diag}(C))*X$ if TRANSA = 'N' and EQUED = 'C' or 'B', or $\text{inv}(\text{diag}(R))*X$ if TRANSA = 'T' or 'C' and EQUED = 'R' or 'B'.

LDX (input)

The leading dimension of the array X. $\text{LDX} \geq \max(1, N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if $\text{RCOND} = 0$), the matrix is singular to working precision. This condition is indicated by a return code of $\text{INFO} > 0$.

FERR (output)

The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If XTRUE is the true solution corresponding to $X(j)$, $\text{FERR}(j)$ is an estimated upper bound for the magnitude of the largest element in $(X(j) - \text{XTRUE})$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension($2*N$)

WORK2 (workspace)

dimension(N) On exit, $\text{WORK2}(1)$ contains the reciprocal pivot growth factor $\text{norm}(A)/\text{norm}(U)$. The "max absolute element" norm is used. If $\text{WORK2}(1)$ is much less than 1, then the stability of the LU factorization of the (equilibrated) matrix A could be poor. This also means that the solution X, condition estimator RCOND, and forward error bound FERR could be unreliable. If factorization fails with $0 < \text{INFO} \leq N$, then $\text{WORK2}(1)$ contains the reciprocal pivot growth factor for the leading INFO columns of A.

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value
> 0: if $\text{INFO} = i$, and i is
<= N: $U(i,i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution and error bounds could not be computed. $\text{RCOND} = 0$ is returned. = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to

working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

zgbtf2 - compute an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE ZGBTF2(M, N, KL, KU, AB, LDAB, IPIV, INFO)
```

```
DOUBLE COMPLEX AB(LDAB,*)
INTEGER M, N, KL, KU, LDAB, INFO
INTEGER IPIV(*)
```

```
SUBROUTINE ZGBTF2_64(M, N, KL, KU, AB, LDAB, IPIV, INFO)
```

```
DOUBLE COMPLEX AB(LDAB,*)
INTEGER*8 M, N, KL, KU, LDAB, INFO
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE GBTF2([M], [N], KL, KU, AB, [LDAB], IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:,*) :: AB
INTEGER :: M, N, KL, KU, LDAB, INFO
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE GBTF2_64([M], [N], KL, KU, AB, [LDAB], IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:,*) :: AB
INTEGER(8) :: M, N, KL, KU, LDAB, INFO
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgbtf2(int m, int n, int kl, int ku, doublecomplex *ab,
           int ldab, int *ipiv, int *info);
```

```
void zgbtf2_64(long m, long n, long kl, long ku, doublecom-
              plex *ab, long ldab, long *ipiv, long *info);
```

PURPOSE

zgbtf2 computes an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

KL (input)
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
The number of superdiagonals within the band of A.
 $KU \geq 0$.

AB (input/output)
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array AB as follows:
 $AB(kl+ku+1+i-j,j) = A(i,j)$ for $\max(1,j-ku) \leq i \leq \min(m,j+kl)$

On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDAB (input)
The leading dimension of the array AB. $LDAB \geq 2*KL+KU+1$.

IPIV (output)
The pivot indices; for $1 \leq i \leq \min(M,N)$, row i of the matrix was interchanged with row IPIV(i).

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = +i, U(i,i) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $M = N = 6$, $KL = 2$, $KU = 1$:

On entry:

On exit:

	*	*	*	+	+	+		*	*	*	u14	u25	
u36													
	*	*	+	+	+	+		*	*		u13	u24	u35
u46													
	*	a12	a23	a34	a45	a56		*	u12	u23	u34	u45	
u56													
	a11	a22	a33	a44	a55	a66		u11	u22	u33	u44	u55	
u66													
	a21	a32	a43	a54	a65	*		m21	m32	m43	m54	m65	
*													
	a31	a42	a53	a64	*	*		m31	m42	m53	m64	*	
*													

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U, because of fill-in resulting from the row interchanges.

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NAME

zgbtrf - compute an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE ZGBTRF(M, N, KL, KU, A, LDA, IPIVOT, INFO)
```

```
DOUBLE COMPLEX A(LDA,N)
INTEGER M, N, KL, KU, LDA, INFO
INTEGER IPIVOT(MIN(M,N))
```

```
SUBROUTINE ZGBTRF_64(M, N, KL, KU, A, LDA, IPIVOT, INFO)
```

```
DOUBLE COMPLEX A(LDA,N)
INTEGER*8 M, N, KL, KU, LDA, INFO
INTEGER*8 IPIVOT(MIN(M,N))
```

F95 INTERFACE

```
SUBROUTINE GBTRF(M, [N], KL, KU, A, [LDA], IPIVOT, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER :: M, N, KL, KU, LDA, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GBTRF_64(M, [N], KL, KU, A, [LDA], IPIVOT, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: M, N, KL, KU, LDA, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgbtrf(int m, int n, int kl, int ku, doublecomplex *a,
           int lda, int *ipivot, int *info);
```

```
void zgbtrf_64(long m, long n, long kl, long ku, doublecom-
              plex *a, long lda, long *ipivot, long *info);
```

PURPOSE

zgbtrf computes an LU factorization of a complex m-by-n band matrix A using partial pivoting with row interchanges.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

M (input) Integer
The number of rows of the matrix A. $M \geq 0$.

N (input) Integer
The number of columns of the matrix A. $N \geq 0$.

KL (input) Integer
The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input) Integer
The number of superdiagonals within the band of A.
 $KU \geq 0$.

A (input/output) Double complex array of dimension (LDA,N).
On entry, the matrix A in band storage, in rows KL+1 to 2*KL+KU+1; rows 1 to KL of the array need not be set. The j-th column of A is stored in the j-th column of the array A as follows:
$$A(KL+KU+1+I-J,J) = A(I,J) \quad \text{for} \quad \text{MAX}(1,J-KU) \leq I \leq \text{MIN}(M,J+KL)$$

On exit, details of the factorization: U is stored as an upper triangular band matrix with KL+KU superdiagonals in rows 1 to KL+KU+1, and the multipliers used during the factorization are stored in rows KL+KU+2 to 2*KL+KU+1. See below for further details.

LDA (input) Integer
The leading dimension of the array A. $LDA \geq 2*KL+KU+1$.

IPIVOT (output) Integer array of dimension MIN(M,N)
The pivot indices; for $1 \leq I \leq \text{min}(M,N)$, row I of the matrix was interchanged with row IPIVOT(I).

INFO (output) Integer
= 0: successful exit
< 0: if INFO = -I, the I-th argument had an illegal value
> 0: if INFO = +I, U(I,I) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equa-

tions.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $M = N = 6$, $KL = 2$, $KU = 1$:

On entry:						On exit:					
* * *	+	+	+			* * *	u14	u25			
u36	* *	+	+	+	+	* *	u13	u24	u35		
u46	* a12	a23	a34	a45	a56	* u12	u23	u34	u45		
u56	a11	a22	a33	a44	a55	a66	u11	u22	u33	u44	u55
u66	a21	a32	a43	a54	a65	*	m21	m32	m43	m54	m65
*	a31	a42	a53	a64	*	*	m31	m42	m53	m64	*
*											

Array elements marked * are not used by the routine; elements marked + need not be set on entry, but are required by the routine to store elements of U because of fill-in resulting from the row interchanges.

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NAME

zgbtrs - solve a system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$ with a general band matrix A using the LU factorization computed by ZGBTRF

SYNOPSIS

```
SUBROUTINE ZGBTRS(TRANSA, N, KL, KU, NRHS, A, LDA, IPIVOT, B,
  LDB, INFO)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX A(LDA,*), B(LDB,*)
INTEGER N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZGBTRS_64(TRANSA, N, KL, KU, NRHS, A, LDA, IPIVOT,
  B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX A(LDA,*), B(LDB,*)
INTEGER*8 N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GBTRS([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX(8), DIMENSION(:,*) :: A, B
INTEGER :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GBTRS_64([TRANSA], [N], KL, KU, [NRHS], A, [LDA],
  IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX(8), DIMENSION(:,*) :: A, B
INTEGER(8) :: N, KL, KU, NRHS, LDA, LDB, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void zgbtrs(char transa, int n, int kl, int ku, int nrhs,
            doublecomplex *a, int lda, int *ipivot, doublecom-
            plex *b, int ldb, int *info);
void zgbtrs_64(char transa, long n, long kl, long ku, long
               nrhs, doublecomplex *a, long lda, long *ipivot,
               doublecomplex *b, long ldb, long *info);
```

PURPOSE

zgbtrs solves a system of linear equations
 $A * X = B$, $A^{*T} * X = B$, or $A^{*H} * X = B$ with a gen-
 eral band matrix A using the LU factorization computed by
 ZGBTRF.

ARGUMENTS

TRANSA (input)
 Specifies the form of the system of equations. =
 'N': $A * X = B$ (No transpose)
 = 'T': $A^{*T} * X = B$ (Transpose)
 = 'C': $A^{*H} * X = B$ (Conjugate transpose)
 TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

KL (input)
 The number of subdiagonals within the band of A.
 $KL \geq 0$.

KU (input)
 The number of superdiagonals within the band of A.
 $KU \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number
 of columns of the matrix B. $NRHS \geq 0$.

A (input) Details of the LU factorization of the band matrix
 A, as computed by ZGBTRF. U is stored as an upper
 triangular band matrix with $KL+KU$ superdiagonals
 in rows 1 to $KL+KU+1$, and the multipliers used
 during the factorization are stored in rows
 $KL+KU+2$ to $2*KL+KU+1$.

LDA (input)
 The leading dimension of the array A. $LDA \geq$
 $2*KL+KU+1$.

IPIVOT (input)
 The pivot indices; for $1 \leq i \leq N$, row i of the
 matrix was interchanged with row IPIVOT(i).

B (input/output)
 On entry, the right hand side matrix B. On exit,

the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

zgebak - form the right or left eigenvectors of a complex general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by ZGEBAL

SYNOPSIS

```
SUBROUTINE ZGEBAK(JOB, SIDE, N, ILO, IHI, SCALE, M, V, LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE  
DOUBLE COMPLEX V(LDV,*)  
INTEGER N, ILO, IHI, M, LDV, INFO  
DOUBLE PRECISION SCALE(*)
```

```
SUBROUTINE ZGEBAK_64(JOB, SIDE, N, ILO, IHI, SCALE, M, V, LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE  
DOUBLE COMPLEX V(LDV,*)  
INTEGER*8 N, ILO, IHI, M, LDV, INFO  
DOUBLE PRECISION SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE GEBAK(JOB, SIDE, [N], ILO, IHI, SCALE, [M], V, [LDV],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE  
COMPLEX(8), DIMENSION(:, :) :: V  
INTEGER :: N, ILO, IHI, M, LDV, INFO  
REAL(8), DIMENSION(:) :: SCALE
```

```
SUBROUTINE GEBAK_64(JOB, SIDE, [N], ILO, IHI, SCALE, [M], V, [LDV],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE  
COMPLEX(8), DIMENSION(:, :) :: V  
INTEGER(8) :: N, ILO, IHI, M, LDV, INFO  
REAL(8), DIMENSION(:) :: SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zgebak(char job, char side, int n, int ilo, int ihi,
            double *scale, int m, doublecomplex *v, int ldv,
            int *info);

void zgebak_64(char job, char side, long n, long ilo, long
              ihi, double *scale, long m, doublecomplex *v, long
              ldv, long *info);

```

PURPOSE

zgebak forms the right or left eigenvectors of a complex general matrix by backward transformation on the computed eigenvectors of the balanced matrix output by ZGEBAL.

ARGUMENTS

JOB (input)

Specifies the type of backward transformation required: = 'N', do nothing, return immediately; = 'P', do backward transformation for permutation only; = 'S', do backward transformation for scaling only; = 'B', do backward transformations for both permutation and scaling. JOB must be the same as the argument JOB supplied to ZGEBAL.

SIDE (input)

= 'R': V contains right eigenvectors;
 = 'L': V contains left eigenvectors.

N (input) The number of rows of the matrix V. $N \geq 0$.

ILO (input)

The integer ILO determined by ZGEBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

IHI (input)

The integer IHI determined by ZGEBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

SCALE (input)

Details of the permutation and scaling factors, as returned by ZGEBAL.

M (input) The number of columns of the matrix V. $M \geq 0$.

V (input/output)

On entry, the matrix of right or left eigenvectors to be transformed, as returned by CHSEIN or CTREVC. On exit, V is overwritten by the transformed eigenvectors.

LDV (input)

The leading dimension of the array V. $LDV \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

zgebal - balance a general complex matrix A

SYNOPSIS

```
SUBROUTINE ZGEBAL(JOB, N, A, LDA, ILO, IHI, SCALE, INFO)
```

```
CHARACTER * 1 JOB  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, LDA, ILO, IHI, INFO  
DOUBLE PRECISION SCALE(*)
```

```
SUBROUTINE ZGEBAL_64(JOB, N, A, LDA, ILO, IHI, SCALE, INFO)
```

```
CHARACTER * 1 JOB  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, ILO, IHI, INFO  
DOUBLE PRECISION SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE GEBAL(JOB, [N], A, [LDA], ILO, IHI, SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, ILO, IHI, INFO  
REAL(8), DIMENSION(:) :: SCALE
```

```
SUBROUTINE GEBAL_64(JOB, [N], A, [LDA], ILO, IHI, SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, ILO, IHI, INFO  
REAL(8), DIMENSION(:) :: SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgebal(char job, int n, doublecomplex *a, int lda, int  
            *ilo, int *ihi, double *scale, int *info);
```

```
void zgebal_64(char job, long n, doublecomplex *a, long lda,
              long *ilo, long *ihi, double *scale, long *info);
```

PURPOSE

zgebal balances a general complex matrix A. This involves, first, permuting A by a similarity transformation to isolate eigenvalues in the first 1 to ILO-1 and last IHI+1 to N elements on the diagonal; and second, applying a diagonal similarity transformation to rows and columns ILO to IHI to make the rows and columns as close in norm as possible. Both steps are optional.

Balancing may reduce the 1-norm of the matrix, and improve the accuracy of the computed eigenvalues and/or eigenvectors.

ARGUMENTS

JOB (input)

Specifies the operations to be performed on A:
= 'N': none: simply set ILO = 1, IHI = N,
SCALE(I) = 1.0 for i = 1,...,N; = 'P': permute
only;
= 'S': scale only;
= 'B': both permute and scale.

N (input) The order of the matrix A. N >= 0.

A (input/output)

On entry, the input matrix A. On exit, A is
overwritten by the balanced matrix. If JOB = 'N',
A is not referenced. See Further Details.

LDA (input)

The leading dimension of the array A. LDA >=
max(1,N).

ILO (output)

ILO and IHI are set to integers such that on exit
A(i,j) = 0 if i > j and j = 1,...,ILO-1 or I =
IHI+1,...,N. If JOB = 'N' or 'S', ILO = 1 and IHI
= N.

IHI (output)

ILO and IHI are set to integers such that on exit
A(i,j) = 0 if i > j and j = 1,...,ILO-1 or I =
IHI+1,...,N. If JOB = 'N' or 'S', ILO = 1 and IHI
= N.

SCALE (output)

Details of the permutations and scaling factors
applied to A. If P(j) is the index of the row and
column interchanged with row and column j and D(j)
is the scaling factor applied to row and column j,

then SCALE(j) = P(j) for j = 1,...,ILO-1 = D(j)
 for j = ILO,...,IHI = P(j) for j = IHI+1,...,N.
 The order in which the interchanges are made is N
 to IHI+1, then 1 to ILO-1.

INFO (output)

= 0: successful exit.
 < 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The permutations consist of row and column interchanges which put the matrix in the form

$$P A P = \begin{pmatrix} T1 & X & Y \\ 0 & B & Z \\ 0 & 0 & T2 \end{pmatrix}$$

where T1 and T2 are upper triangular matrices whose eigenvalues lie along the diagonal. The column indices ILO and IHI mark the starting and ending columns of the submatrix B. Balancing consists of applying a diagonal similarity transformation $\text{inv}(D) * B * D$ to make the 1-norms of each row of B and its corresponding column nearly equal. The output matrix is

$$\begin{pmatrix} T1 & X*D & Y \\ 0 & \text{inv}(D)*B*D & \text{inv}(D)*Z \\ 0 & 0 & T2 \end{pmatrix}.$$

Information about the permutations P and the diagonal matrix D is returned in the vector SCALE.

This subroutine is based on the EISPACK routine CBAL.

Modified by Tzu-Yi Chen, Computer Science Division, University of California at Berkeley, USA

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NAME

zgebrd - reduce a general complex M-by-N matrix A to upper or lower bidiagonal form B by a unitary transformation

SYNOPSIS

```
SUBROUTINE ZGEBRD(M, N, A, LDA, D, E, TAUQ, TAUP, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAUQ(*), TAUP(*), WORK(*)
INTEGER M, N, LDA, LWORK, INFO
DOUBLE PRECISION D(*), E(*)
```

```
SUBROUTINE ZGEBRD_64(M, N, A, LDA, D, E, TAUQ, TAUP, WORK, LWORK,
INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAUQ(*), TAUP(*), WORK(*)
INTEGER*8 M, N, LDA, LWORK, INFO
DOUBLE PRECISION D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE GEBRD([M], [N], A, [LDA], D, E, TAUQ, TAUP, [WORK], [LWORK],
[INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAUQ, TAUP, WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER :: M, N, LDA, LWORK, INFO
REAL(8), DIMENSION(:) :: D, E
```

```
SUBROUTINE GEBRD_64([M], [N], A, [LDA], D, E, TAUQ, TAUP, [WORK],
[LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAUQ, TAUP, WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: M, N, LDA, LWORK, INFO
REAL(8), DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zgebrd(int m, int n, doublecomplex *a, int lda, double
           *d, double *e, doublecomplex *tauq, doublecomplex
           *taup, int *info);

void zgebrd_64(long m, long n, doublecomplex *a, long lda,
              double *d, double *e, doublecomplex *tauq, doublecomplex
              *taup, long *info);

```

PURPOSE

zgebrd reduces a general complex M-by-N matrix A to upper or lower bidiagonal form B by a unitary transformation: $Q^*H * A * P = B$.

If $m \geq n$, B is upper bidiagonal; if $m < n$, B is lower bidiagonal.

ARGUMENTS

M (input) The number of rows in the matrix A. $M \geq 0$.

N (input) The number of columns in the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N general matrix to be reduced. On exit, if $m \geq n$, the diagonal and the first superdiagonal are overwritten with the upper bidiagonal matrix B; the elements below the diagonal, with the array TAUQ, represent the unitary matrix Q as a product of elementary reflectors, and the elements above the first superdiagonal, with the array TAUP, represent the unitary matrix P as a product of elementary reflectors; if $m < n$, the diagonal and the first subdiagonal are overwritten with the lower bidiagonal matrix B; the elements below the first subdiagonal, with the array TAUQ, represent the unitary matrix Q as a product of elementary reflectors, and the elements above the diagonal, with the array TAUP, represent the unitary matrix P as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

D (output)

The diagonal elements of the bidiagonal matrix B: $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the bidiagonal matrix B: if $m \geq n$, $E(i) = A(i, i+1)$ for $i = 1, 2, \dots, n-1$; if $m < n$, $E(i) = A(i+1, i)$ for $i = 1, 2, \dots, m-1$.

TAUQ (output)

The scalar factors of the elementary reflectors

which represent the unitary matrix Q. See Further Details.

TAUP (output)

The scalar factors of the elementary reflectors which represent the unitary matrix P. See Further Details.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The length of the array WORK. LWORK \geq max(1,M,N). For optimum performance LWORK \geq (M+N)*NB, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrices Q and P are represented as products of elementary reflectors:

If $m \geq n$,

$$Q = H(1) H(2) \dots H(n) \quad \text{and} \quad P = G(1) G(2) \dots G(n-1)$$

Each H(i) and G(i) has the form:

$$H(i) = I - \text{tauq} * v * v' \quad \text{and} \quad G(i) = I - \text{taup} * u * u'$$

where tauq and taup are complex scalars, and v and u are complex vectors; $v(1:i-1) = 0$, $v(i) = 1$, and $v(i+1:m)$ is stored on exit in A(i+1:m,i); $u(1:i) = 0$, $u(i+1) = 1$, and $u(i+2:n)$ is stored on exit in A(i,i+2:n); tauq is stored in TAUQ(i) and taup in TAUP(i).

If $m < n$,

$$Q = H(1) H(2) \dots H(m-1) \quad \text{and} \quad P = G(1) G(2) \dots G(m)$$

Each H(i) and G(i) has the form:

$$H(i) = I - \text{tauq} * v * v' \quad \text{and} \quad G(i) = I - \text{taup} * u * u'$$

where tauq and taup are complex scalars, and v and u are complex vectors; $v(1:i) = 0$, $v(i+1) = 1$, and $v(i+2:m)$ is stored on exit in A(i+2:m,i); $u(1:i-1) = 0$, $u(i) = 1$, and $u(i+1:n)$ is stored on exit in A(i,i+1:n); tauq is stored in TAUQ(i) and taup in TAUP(i).

The contents of A on exit are illustrated by the following examples:

m = 6 and n = 5 (m > n):

```
( d e u1 u1 u1 )
u1 )
( v1 d e u2 u2 )
u2 )
( v1 v2 d e u3 )
u3 )
( v1 v2 v3 d e )
u4 )
( v1 v2 v3 v4 d )
u5 )
( v1 v2 v3 v4 v5 )
```

m = 5 and n = 6 (m < n):

```
( d u1 u1 u1 u1
( e d u2 u2 u2
( v1 e d u3 u3
( v1 v2 e d u4
( v1 v2 v3 e d
```

where d and e denote diagonal and off-diagonal elements of B, v_i denotes an element of the vector defining $H(i)$, and u_i an element of the vector defining $G(i)$.

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NAME

zgecon - estimate the reciprocal of the condition number of a general complex matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by ZGETRF

SYNOPSIS

```
SUBROUTINE ZGECON(NORM, N, A, LDA, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZGECON_64(NORM, N, A, LDA, ANORM, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GECON(NORM, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE GECON_64(NORM, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A
```

```
INTEGER(8) :: N, LDA, INFO
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void zgecon(char norm, int n, doublecomplex *a, int lda,
            double anorm, double *rcond, int *info);

void zgecon_64(char norm, long n, doublecomplex *a, long
              lda, double anorm, double *rcond, long *info);
```

PURPOSE

zgecon estimates the reciprocal of the condition number of a general complex matrix A, in either the 1-norm or the infinity-norm, using the LU factorization computed by ZGETRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The factors L and U from the factorization $A = P * L * U$ as computed by ZGETRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zgeequ - compute row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number

SYNOPSIS

```
SUBROUTINE ZGEEQU(M, N, A, LDA, R, C, ROWCND, COLCND, AMAX,
                 INFO)
```

```
DOUBLE COMPLEX A(LDA,*)
INTEGER M, N, LDA, INFO
DOUBLE PRECISION ROWCND, COLCND, AMAX
DOUBLE PRECISION R(*), C(*)
```

```
SUBROUTINE ZGEEQU_64(M, N, A, LDA, R, C, ROWCND, COLCND, AMAX,
                    INFO)
```

```
DOUBLE COMPLEX A(LDA,*)
INTEGER*8 M, N, LDA, INFO
DOUBLE PRECISION ROWCND, COLCND, AMAX
DOUBLE PRECISION R(*), C(*)
```

F95 INTERFACE

```
SUBROUTINE GEEQU([M], [N], A, [LDA], R, C, ROWCND, COLCND,
                AMAX, [INFO])
```

```
COMPLEX(8), DIMENSION(:,:) :: A
INTEGER :: M, N, LDA, INFO
REAL(8) :: ROWCND, COLCND, AMAX
REAL(8), DIMENSION(:) :: R, C
```

```
SUBROUTINE GEEQU_64([M], [N], A, [LDA], R, C, ROWCND, COLCND,
                   AMAX, [INFO])
```

```
COMPLEX(8), DIMENSION(:,:) :: A
INTEGER(8) :: M, N, LDA, INFO
REAL(8) :: ROWCND, COLCND, AMAX
REAL(8), DIMENSION(:) :: R, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgeequ(int m, int n, doublecomplex *a, int lda, double
           *r, double *c, double *rowcnd, double *colcnd,
           double *amax, int *info);
```

```
void zgeequ_64(long m, long n, doublecomplex *a, long lda,
              double *r, double *c, double *rowcnd, double
              *colcnd, double *amax, long *info);
```

PURPOSE

zgeequ computes row and column scalings intended to equilibrate an M-by-N matrix A and reduce its condition number. R returns the row scale factors and C the column scale factors, chosen to try to make the largest element in each row and column of the matrix B with elements $B(i,j)=R(i)*A(i,j)*C(j)$ have absolute value 1.

R(i) and C(j) are restricted to be between SMLNUM = smallest safe number and BIGNUM = largest safe number. Use of these scaling factors is not guaranteed to reduce the condition number of A but works well in practice.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input) The M-by-N matrix whose equilibration factors are to be computed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

R (output)

If INFO = 0 or INFO > M, R contains the row scale factors for A.

C (output)

If INFO = 0, C contains the column scale factors for A.

ROWCND (output)

If INFO = 0 or INFO > M, ROWCND contains the ratio of the smallest R(i) to the largest R(i). If ROWCND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by R.

COLCND (output)

If INFO = 0, COLCND contains the ratio of the smallest C(i) to the largest C(i). If COLCND ≥ 0.1 , it is not worth scaling by C.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= M: the i-th row of A is exactly zero
> M: the (i-M)-th column of A is exactly zero

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NAME

zgees - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z

SYNOPSIS

```
SUBROUTINE ZGEES(JOBZ, SORTEV, SELECT, N, A, LDA, NOUT, W, Z, LDZ,  
                WORK, LDWORK, WORK2, WORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV  
DOUBLE COMPLEX A(LDA,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL SELECT  
LOGICAL WORK3(*)  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZGEES_64(JOBZ, SORTEV, SELECT, N, A, LDA, NOUT, W, Z, LDZ,  
                   WORK, LDWORK, WORK2, WORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV  
DOUBLE COMPLEX A(LDA,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL*8 SELECT  
LOGICAL*8 WORK3(*)  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEES(JOBZ, SORTEV, [SELECT], [N], A, [LDA], [NOUT], W, Z, [LDZ],  
               [WORK], [LDWORK], [WORK2], [WORK3], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV  
COMPLEX(8), DIMENSION(:) :: W, WORK  
COMPLEX(8), DIMENSION(:, :) :: A, Z  
INTEGER :: N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL :: SELECT  
LOGICAL, DIMENSION(:) :: WORK3  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEES_64(JOBZ, SORTEV, [SELECT], [N], A, [LDA], [NOUT], W, Z,  
                  [LDZ], [WORK], [LDWORK], [WORK2], [WORK3], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, SORTEV
COMPLEX(8), DIMENSION(:) :: W, WORK
COMPLEX(8), DIMENSION(:, :) :: A, Z
INTEGER(8) :: N, LDA, NOUT, LDZ, LDWORK, INFO
LOGICAL(8) :: SELECT
LOGICAL(8), DIMENSION(:) :: WORK3
REAL(8), DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>

void      zgees(char      jobz,      char      sortev,
               int(*select)(doublecomplex), int n, doublecomplex
               *a, int lda, int *nout, doublecomplex *w, double-
               complex *z, int ldz, int *info);

void      zgees_64(char      jobz,      char      sortev,
                   long(*select)(doublecomplex), long n, doublecom-
                   plex *a, long lda, long *nout, doublecomplex *w,
                   doublecomplex *z, long ldz, long *info);

```

PURPOSE

zgees computes for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z. This gives the Schur factorization $A = Z^*T^*(Z^{**}H)$.

Optionally, it also orders the eigenvalues on the diagonal of the Schur form so that selected eigenvalues are at the top left. The leading columns of Z then form an orthonormal basis for the invariant subspace corresponding to the selected eigenvalues.

A complex matrix is in Schur form if it is upper triangular.

ARGUMENTS

JOBZ (input)

= 'N': Schur vectors are not computed;
 = 'V': Schur vectors are computed.

SORTEV (input)

Specifies whether or not to order the eigenvalues on the diagonal of the Schur form. = 'N': Eigenvalues are not ordered;
 = 'S': Eigenvalues are ordered (see SELECT).

SELECT (input)

LOGICAL FUNCTION of one DOUBLE COMPLEX argument SELECT must be declared EXTERNAL in the calling subroutine. If SORTEV = 'S', SELECT is used to select eigenvalues to order to the top left of the Schur form. If SORTEV = 'N', SELECT is not referenced. The eigenvalue W(j) is selected if SELECT(W(j)) is true.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)
 DOUBLE COMPLEX array, dimension(LDA,N) On entry, the N-by-N matrix A. On exit, A has been overwritten by its Schur form T.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1,N)$.

NOUT (output)
 If SORTEV = 'N', NOUT = 0. If SORTEV = 'S', NOUT = number of eigenvalues for which SELECT is true.

W (output)
 DOUBLE COMPLEX array, dimension(N) W contains the computed eigenvalues, in the same order that they appear on the diagonal of the output Schur form T.

Z (output)
 DOUBLE COMPLEX array, dimension (LDZ, N) If JOBZ = 'V', Z contains the unitary matrix Z of Schur vectors. If JOBZ = 'N', Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. $LDZ \geq 1$; if JOBZ = 'V', $LDZ \geq N$.

WORK (workspace)
 DOUBLE COMPLEX array, dimension(LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The dimension of the array WORK. $LDWORK \geq \max(1,2*N)$. For good performance, LDWORK must generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
 DOUBLE PRECISION array, dimension(N)

WORK3 (workspace)
 LOGICAL array, dimension(N) Not referenced if SORTEV = 'N'.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value.
 > 0: if INFO = i, and i is
 <= N: the QR algorithm failed to compute all the eigenvalues; elements 1:ILO-1 and i+1:N of W contain those eigenvalues which have converged; if JOBZ = 'V', Z contains the matrix which reduces A to its partially converged Schur form. = N+1: the eigenvalues could not be reordered because some

eigenvalues were too close to separate (the problem is very ill-conditioned); = N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Schur form no longer satisfy SELECT = .TRUE.. This could also be caused by underflow due to scaling.

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NAME

zgeesx - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z

SYNOPSIS

```
SUBROUTINE ZGEESX(JOBZ, SORTEV, SELECT, SENSE, N, A, LDA, NOUT, W, Z,  
                 LDZ, RCONE, RCONV, WORK, LDWORK, WORK2, BWORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV, SENSE  
DOUBLE COMPLEX A(LDA,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL SELECT  
LOGICAL BWORK3(*)  
DOUBLE PRECISION RCONE, RCONV  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZGEESX_64(JOBZ, SORTEV, SELECT, SENSE, N, A, LDA, NOUT, W,  
                   Z, LDZ, RCONE, RCONV, WORK, LDWORK, WORK2, BWORK3, INFO)
```

```
CHARACTER * 1 JOBZ, SORTEV, SENSE  
DOUBLE COMPLEX A(LDA,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL*8 SELECT  
LOGICAL*8 BWORK3(*)  
DOUBLE PRECISION RCONE, RCONV  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEESX(JOBZ, SORTEV, [SELECT], SENSE, [N], A, [LDA], NOUT, W,  
                Z, [LDZ], RCONE, RCONV, [WORK], [LDWORK], [WORK2], [BWORK3],  
                [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, SORTEV, SENSE  
COMPLEX(8), DIMENSION(:) :: W, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, Z  
INTEGER :: N, LDA, NOUT, LDZ, LDWORK, INFO  
LOGICAL :: SELECT  
LOGICAL, DIMENSION(:) :: BWORK3  
REAL(8) :: RCONE, RCONV
```

```

REAL(8), DIMENSION(:) :: WORK2

SUBROUTINE GEESX_64(JOBZ, SORTEV, [SELECT], SENSE, [N], A, [LDA], NOUT,
    W, Z, [LDZ], RCONE, RCONV, [WORK], [LDWORK], [WORK2], [BWORK3],
    [INFO])

CHARACTER(LEN=1) :: JOBZ, SORTEV, SENSE
COMPLEX(8), DIMENSION(:) :: W, WORK
COMPLEX(8), DIMENSION(:, :) :: A, Z
INTEGER(8) :: N, LDA, NOUT, LDZ, LDWORK, INFO
LOGICAL(8) :: SELECT
LOGICAL(8), DIMENSION(:) :: BWORK3
REAL(8) :: RCONE, RCONV
REAL(8), DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>

void      zgeesx(char      jobz,      char      sortev,
    int(*select)(doublecomplex), char sense, int n,
    doublecomplex *a, int lda, int *nout, doublecom-
    plex *w, doublecomplex *z, int ldz, double *rcone,
    double *rconv, int *info);

void      zgeesx_64(char      jobz,      char      sortev,
    long(*select)(doublecomplex), char sense, long n,
    doublecomplex *a, long lda, long *nout, doublecom-
    plex *w, doublecomplex *z, long ldz, double
    *rcone, double *rconv, long *info);

```

PURPOSE

zgeesx computes for an N-by-N complex nonsymmetric matrix A, the eigenvalues, the Schur form T, and, optionally, the matrix of Schur vectors Z. This gives the Schur factorization $A = Z^*T(Z^*H)$.

Optionally, it also orders the eigenvalues on the diagonal of the Schur form so that selected eigenvalues are at the top left; computes a reciprocal condition number for the average of the selected eigenvalues (RCONDE); and computes a reciprocal condition number for the right invariant subspace corresponding to the selected eigenvalues (RCONDV). The leading columns of Z form an orthonormal basis for this invariant subspace.

For further explanation of the reciprocal condition numbers RCONDE and RCONDV, see Section 4.10 of the LAPACK Users' Guide (where these quantities are called s and sep respectively).

A complex matrix is in Schur form if it is upper triangular.

ARGUMENTS

JOBZ (input)

= 'N': Schur vectors are not computed;
 = 'V': Schur vectors are computed.

SORTEV (input)
 Specifies whether or not to order the eigenvalues on the diagonal of the Schur form. = 'N': Eigenvalues are not ordered;
 = 'S': Eigenvalues are ordered (see SELECT).

SELECT (input)
 LOGICAL FUNCTION of one DOUBLE COMPLEX argument SELECT must be declared EXTERNAL in the calling subroutine. If SORTEV = 'S', SELECT is used to select eigenvalues to order to the top left of the Schur form. If SORTEV = 'N', SELECT is not referenced. An eigenvalue W(j) is selected if SELECT(W(j)) is true.

SENSE (input)
 Determines which reciprocal condition numbers are computed. = 'N': None are computed;
 = 'E': Computed for average of selected eigenvalues only;
 = 'V': Computed for selected right invariant subspace only;
 = 'B': Computed for both. If SENSE = 'E', 'V' or 'B', SORTEV must equal 'S'.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)
 DOUBLE COMPLEX array, dimension(LDA, N) On entry, the N-by-N matrix A. On exit, A is overwritten by its Schur form T.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

NOUT (output)
 If SORTEV = 'N', NOUT = 0. If SORTEV = 'S', NOUT = number of eigenvalues for which SELECT is true.

W (output)
 DOUBLE COMPLEX array, dimension(N) W contains the computed eigenvalues, in the same order that they appear on the diagonal of the output Schur form T.

Z (output)
 DOUBLE COMPLEX array, dimension(LDZ, N) If JOBZ = 'V', Z contains the unitary matrix Z of Schur vectors. If JOBZ = 'N', Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq N$.

RCONE (output)
 If SENSE = 'E' or 'B', RCONE contains the reciprocal condition number for the average of the selected eigenvalues. Not referenced if SENSE = 'N' or 'V'.

RCONV (output)

If SENSE = 'V' or 'B', RCONV contains the reciprocal condition number for the selected right invariant subspace. Not referenced if SENSE = 'N' or 'E'.

WORK (workspace)

DOUBLE COMPLEX array, dimension(LDWORK) On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq $\max(1, 2*N)$. Also, if SENSE = 'E' or 'V' or 'B', LDWORK $\geq 2*NOUT*(N-NOUT)$, where NOUT is the number of selected eigenvalues computed by this routine. Note that $2*NOUT*(N-NOUT) \leq N*N/2$. For good performance, LDWORK must generally be larger.

WORK2 (workspace)

DOUBLE PRECISION array, dimension(N)

BWORK3 (workspace)

LOGICAL array, dimension(N) Not referenced if SORTEV = 'N'.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, and i is
<= N: the QR algorithm failed to compute all the eigenvalues; elements 1:ILO-1 and i+1:N of W contain those eigenvalues which have converged; if JOBZ = 'V', Z contains the transformation which reduces A to its partially converged Schur form.
= N+1: the eigenvalues could not be reordered because some eigenvalues were too close to separate (the problem is very ill-conditioned);
= N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Schur form no longer satisfy SELECT=.TRUE. This could also be caused by underflow due to scaling.

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NAME

zgeev - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

SYNOPSIS

```
SUBROUTINE ZGEEV(JOBVL, JOBVR, N, A, LDA, W, VL, LDVL, VR, LDVR,  
                WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
DOUBLE COMPLEX A(LDA,*), W(*), VL(LDVL,*), VR(LDVR,*),  
WORK(*)  
INTEGER N, LDA, LDVL, LDVR, LDWORK, INFO  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZGEEV_64(JOBVL, JOBVR, N, A, LDA, W, VL, LDVL, VR, LDVR,  
                   WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR  
DOUBLE COMPLEX A(LDA,*), W(*), VL(LDVL,*), VR(LDVR,*),  
WORK(*)  
INTEGER*8 N, LDA, LDVL, LDVR, LDWORK, INFO  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEEV(JOBVL, JOBVR, [N], A, [LDA], W, VL, [LDVL], VR, [LDVR],  
               [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
COMPLEX(8), DIMENSION(:) :: W, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, VL, VR  
INTEGER :: N, LDA, LDVL, LDVR, LDWORK, INFO  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEEV_64(JOBVL, JOBVR, [N], A, [LDA], W, VL, [LDVL], VR,  
                  [LDVR], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR  
COMPLEX(8), DIMENSION(:) :: W, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, VL, VR
```

```
INTEGER(8) :: N, LDA, LDVL, LDVR, LDWORK, INFO
REAL(8), DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void zgeev(char jobvl, char jobvr, int n, doublecomplex *a,
           int lda, doublecomplex *w, doublecomplex *vl, int
           ldvl, doublecomplex *vr, int ldvr, int *info);

void zgeev_64(char jobvl, char jobvr, long n, doublecomplex
              *a, long lda, doublecomplex *w, doublecomplex *vl,
              long ldvl, doublecomplex *vr, long ldvr, long
              *info);
```

PURPOSE

zgeev computes for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors.

The right eigenvector $v(j)$ of A satisfies

$$A * v(j) = \text{lambda}(j) * v(j)$$

where $\text{lambda}(j)$ is its eigenvalue.

The left eigenvector $u(j)$ of A satisfies

$$u(j)**H * A = \text{lambda}(j) * u(j)**H$$

where $u(j)**H$ denotes the conjugate transpose of $u(j)$.

The computed eigenvectors are normalized to have Euclidean norm equal to 1 and largest component real.

ARGUMENTS

JOBVL (input)

= 'N': left eigenvectors of A are not computed;
= 'V': left eigenvectors of are computed.

JOBVR (input)

= 'N': right eigenvectors of A are not computed;
= 'V': right eigenvectors of A are computed.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. On exit, A has been overwritten.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)

W contains the computed eigenvalues.

VL (output)

If JOBVL = 'V', the left eigenvectors $u(j)$ are stored one after another in the columns of VL, in

the same order as their eigenvalues. If `JOBVL = 'N'`, `VL` is not referenced. `u(j) = VL(:,j)`, the `j`-th column of `VL`.

`LDVL` (input)

The leading dimension of the array `VL`. `LDVL >= 1`;
if `JOBVL = 'V'`, `LDVL >= N`.

`VR` (input)

If `JOBVR = 'V'`, the right eigenvectors `v(j)` are stored one after another in the columns of `VR`, in the same order as their eigenvalues. If `JOBVR = 'N'`, `VR` is not referenced. `v(j) = VR(:,j)`, the `j`-th column of `VR`.

`LDVR` (input)

The leading dimension of the array `VR`. `LDVR >= 1`;
if `JOBVR = 'V'`, `LDVR >= N`.

`WORK` (workspace)

On exit, if `INFO = 0`, `WORK(1)` returns the optimal `LDWORK`.

`LDWORK` (input)

The dimension of the array `WORK`. `LDWORK >= max(1,2*N)`. For good performance, `LDWORK` must generally be larger.

If `LDWORK = -1`, then a workspace query is assumed; the routine only calculates the optimal size of the `WORK` array, returns this value as the first entry of the `WORK` array, and no error message related to `LDWORK` is issued by `XERBLA`.

`WORK2` (workspace)

`dimension(2*N)`

`INFO` (output)

`= 0`: successful exit
`< 0`: if `INFO = -i`, the `i`-th argument had an illegal value.
`> 0`: if `INFO = i`, the QR algorithm failed to compute all the eigenvalues, and no eigenvectors have been computed; elements and `i+1:N` of `W` contain eigenvalues which have converged.

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NAME

zgeevx - compute for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors

SYNOPSIS

```
SUBROUTINE ZGEEVX(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, W, VL,
                 LDVL, VR, LDVR, ILO, IHI, SCALE, ABNRM, RCONE, RCONV, WORK,
                 LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
DOUBLE COMPLEX A(LDA,*), W(*), VL(LDVL,*), VR(LDVR,*),
WORK(*)
INTEGER N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
DOUBLE PRECISION ABNRM
DOUBLE PRECISION SCALE(*), RCONE(*), RCONV(*), WORK2(*)
```

```
SUBROUTINE ZGEEVX_64(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, W, VL,
                   LDVL, VR, LDVR, ILO, IHI, SCALE, ABNRM, RCONE, RCONV, WORK,
                   LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
DOUBLE COMPLEX A(LDA,*), W(*), VL(LDVL,*), VR(LDVR,*),
WORK(*)
INTEGER*8 N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
DOUBLE PRECISION ABNRM
DOUBLE PRECISION SCALE(*), RCONE(*), RCONV(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEEVX(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], W, VL,
                [LDVL], VR, [LDVR], ILO, IHI, SCALE, ABNRM, RCONE, RCONV, [WORK],
                LDWORK, [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
COMPLEX(8), DIMENSION(:) :: W, WORK
COMPLEX(8), DIMENSION(:,:) :: A, VL, VR
INTEGER :: N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
REAL(8) :: ABNRM
REAL(8), DIMENSION(:) :: SCALE, RCONE, RCONV, WORK2
```

```

SUBROUTINE GEEVX_64(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], W,
    VL, [LDVL], VR, [LDVR], ILO, IHI, SCALE, ABNRM, RCONE, RCONV,
    [WORK], LDWORK, [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
COMPLEX(8), DIMENSION(:) :: W, WORK
COMPLEX(8), DIMENSION(:, :) :: A, VL, VR
INTEGER(8) :: N, LDA, LDVL, LDVR, ILO, IHI, LDWORK, INFO
REAL(8) :: ABNRM
REAL(8), DIMENSION(:) :: SCALE, RCONE, RCONV, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zgeevx (char, char, char, char, int, doublecomplex*,
    int, doublecomplex*, doublecomplex*, int, doublecomplex*,
    int, int*, int*, double*, double*,
    double*, double*, int*);

```

```

void zgeevx_64 (char, char, char, char, long, doublecomplex*,
    long, doublecomplex*, doublecomplex*, long,
    doublecomplex*, long, long*, long*, double*, double*,
    double*, double*, double*, long*);

```

PURPOSE

zgeevx computes for an N-by-N complex nonsymmetric matrix A, the eigenvalues and, optionally, the left and/or right eigenvectors.

Optionally also, it computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors (ILO, IHI, SCALE, and ABNRM), reciprocal condition numbers for the eigenvalues (RCONDE), and reciprocal condition numbers for the right eigenvectors (RCONDV).

The right eigenvector $v(j)$ of A satisfies

$$A * v(j) = \text{lambda}(j) * v(j)$$

where $\text{lambda}(j)$ is its eigenvalue.

The left eigenvector $u(j)$ of A satisfies

$$u(j)**H * A = \text{lambda}(j) * u(j)**H$$

where $u(j)**H$ denotes the conjugate transpose of $u(j)$.

The computed eigenvectors are normalized to have Euclidean norm equal to 1 and largest component real.

Balancing a matrix means permuting the rows and columns to make it more nearly upper triangular, and applying a diagonal similarity transformation $D * A * D^{(-1)}$, where D is a diagonal matrix, to make its rows and columns closer in norm and the condition numbers of its eigenvalues and eigenvectors smaller. The computed reciprocal condition numbers correspond to the balanced matrix. Permuting rows and columns will not change the condition numbers (in exact arithmetic) but diagonal scaling will. For further explanation of balancing, see section 4.10.2 of the LAPACK Users' Guide.

ARGUMENTS

BALANC (input)

Indicates how the input matrix should be diagonally scaled and/or permuted to improve the conditioning of its eigenvalues. = 'N': Do not diagonally scale or permute;
= 'P': Perform permutations to make the matrix more nearly upper triangular. Do not diagonally scale; = 'S': Diagonally scale the matrix, ie. replace A by $D*A*D^{*-1}$, where D is a diagonal matrix chosen to make the rows and columns of A more equal in norm. Do not permute; = 'B': Both diagonally scale and permute A.

Computed reciprocal condition numbers will be for the matrix after balancing and/or permuting. Permuting does not change condition numbers (in exact arithmetic), but balancing does.

JOBVL (input)

= 'N': left eigenvectors of A are not computed;
= 'V': left eigenvectors of A are computed. If SENSE = 'E' or 'B', JOBVL must = 'V'.

JOBVR (input)

= 'N': right eigenvectors of A are not computed;
= 'V': right eigenvectors of A are computed. If SENSE = 'E' or 'B', JOBVR must = 'V'.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': None are computed;
= 'E': Computed for eigenvalues only;
= 'V': Computed for right eigenvectors only;
= 'B': Computed for eigenvalues and right eigenvectors.

If SENSE = 'E' or 'B', both left and right eigenvectors must also be computed (JOBVL = 'V' and JOBVR = 'V').

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the N-by-N matrix A. On exit, A has been overwritten. If JOBVL = 'V' or JOBVR = 'V', A contains the Schur form of the balanced version of the matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)

W contains the computed eigenvalues.

VL (output)

If JOBVL = 'V', the left eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. If JOBVL = 'N', VL is not referenced. $u(j) = VL(:,j)$, the j -th column of VL.

LDVL (input)

The leading dimension of the array VL. LDVL ≥ 1 ;
if JOBVL = 'V', LDVL $\geq N$.

VR (input)

If JOBVR = 'V', the right eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. If JOBVR = 'N', VR is not referenced. $v(j) = VR(:,j)$, the j -th column of VR.

LDVR (input)

The leading dimension of the array VR. LDVR ≥ 1 ;
if JOBVR = 'V', LDVR $\geq N$.

ILO (output)

ILO and IHI are integer values determined when A was balanced. The balanced $A(i,j) = 0$ if $I > J$ and $J = 1, \dots, ILO-1$ or $I = IHI+1, \dots, N$.

IHI (output)

ILO and IHI are integer values determined when A was balanced. The balanced $A(i,j) = 0$ if $I > J$ and $J = 1, \dots, ILO-1$ or $I = IHI+1, \dots, N$.

SCALE (output)

Details of the permutations and scaling factors applied when balancing A. If $P(j)$ is the index of the row and column interchanged with row and column j , and $D(j)$ is the scaling factor applied to row and column j , then $SCALE(J) = P(J)$, for $J = 1, \dots, ILO-1 = D(J)$, for $J = ILO, \dots, IHI = P(J)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

ABNRM (output)

The one-norm of the balanced matrix (the maximum of the sum of absolute values of elements of any column).

RCONE (output)

RCONE(j) is the reciprocal condition number of the j -th eigenvalue.

RCONV (output)

RCONV(j) is the reciprocal condition number of the j -th right eigenvector.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (output)

The dimension of the array WORK. If SENSE = 'N'

or 'E', LDWORK $\geq \max(1, 2*N)$, and if SENSE = 'V' or 'B', LDWORK $\geq N*N+2*N$. For good performance, LDWORK must generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
dimension(2*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the QR algorithm failed to compute all the eigenvalues, and no eigenvectors or condition numbers have been computed; elements 1:ILO-1 and i+1:N of W contain eigenvalues which have converged.

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NAME

zgegs - routine is deprecated and has been replaced by routine CGGES

SYNOPSIS

```
SUBROUTINE ZGEGS(JOBVSL, JOBVSR, N, A, LDA, B, LDB, ALPHA, BETA, VSL,
                LDVSL, VSR, LDVSR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
INTEGER N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZGEGS_64(JOBVSL, JOBVSR, N, A, LDA, B, LDB, ALPHA, BETA,
                   VSL, LDVSL, VSR, LDVSR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
INTEGER*8 N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEGS(JOBVSL, JOBVSR, [N], A, [LDA], B, [LDB], ALPHA, BETA,
               VSL, [LDVSL], VSR, [LDVSR], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, VSL, VSR
INTEGER :: N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEGS_64(JOBVSL, JOBVSR, [N], A, [LDA], B, [LDB], ALPHA,
                  BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK], [LDWORK], [WORK2],
                  [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, VSL, VSR
```

```
INTEGER(8) :: N, LDA, LDB, LDVSL, LDVSR, LDWORK, INFO
REAL(8), DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void zgges(char jobvsl, char jobvsr, int n, doublecomplex
    *a, int lda, doublecomplex *b, int ldb, doublecom-
    plex *alpha, doublecomplex *beta, doublecomplex
    *vsl, int ldvsl, doublecomplex *vsr, int ldvsr,
    int *info);

void zgges_64(char jobvsl, char jobvsr, long n, doublecom-
    plex *a, long lda, doublecomplex *b, long ldb,
    doublecomplex *alpha, doublecomplex *beta, doub-
    lecomplex *vsl, long ldvsl, doublecomplex *vsr,
    long ldvsr, long *info);
```

PURPOSE

zgges routine is deprecated and has been replaced by routine CGGES.

ZGEGS computes for a pair of N-by-N complex nonsymmetric matrices A, B: the generalized eigenvalues (alpha, beta), the complex Schur form (A, B), and optionally left and/or right Schur vectors (VSL and VSR).

(If only the generalized eigenvalues are needed, use the driver ZGEGV instead.)

A generalized eigenvalue for a pair of matrices (A,B) is, roughly speaking, a scalar w or a ratio alpha/beta = w, such that A - w*B is singular. It is usually represented as the pair (alpha,beta), as there is a reasonable interpretation for beta=0, and even for both being zero. A good beginning reference is the book, "Matrix Computations", by G. Golub & C. van Loan (Johns Hopkins U. Press)

The (generalized) Schur form of a pair of matrices is the result of multiplying both matrices on the left by one unitary matrix and both on the right by another unitary matrix, these two unitary matrices being chosen so as to bring the pair of matrices into upper triangular form with the diagonal elements of B being non-negative real numbers (this is also called complex Schur form.)

The left and right Schur vectors are the columns of VSL and VSR, respectively, where VSL and VSR are the unitary matrices which reduce A and B to Schur form:

Schur form of (A,B) = ((VSL)**H A (VSR), (VSL)**H B (VSR))

ARGUMENTS

JOBVSL (input)

= 'N': do not compute the left Schur vectors;
 = 'V': compute the left Schur vectors.

JOBVSR (input)
 = 'N': do not compute the right Schur vectors;
 = 'V': compute the right Schur vectors.

N (input) The order of the matrices A, B, VSL, and VSR. N
 >= 0.

A (input/output)
 On entry, the first of the pair of matrices whose
 generalized eigenvalues and (optionally) Schur
 vectors are to be computed. On exit, the general-
 ized Schur form of A.

LDA (input)
 The leading dimension of A. LDA >= max(1,N).

B (input/output)
 On entry, the second of the pair of matrices whose
 generalized eigenvalues and (optionally) Schur
 vectors are to be computed. On exit, the general-
 ized Schur form of B.

LDB (input)
 The leading dimension of B. LDB >= max(1,N).

ALPHA (output)
 On exit, ALPHA(j)/BETA(j), j=1,...,N, will be the
 generalized eigenvalues. ALPHA(j), j=1,...,N and
 BETA(j), j=1,...,N are the diagonals of the com-
 plex Schur form (A,B) output by ZGEGS. The
 BETA(j) will be non-negative real.

Note: the quotients ALPHA(j)/BETA(j) may easily
 over- or underflow, and BETA(j) may even be zero.
 Thus, the user should avoid naively computing the
 ratio alpha/beta. However, ALPHA will be always
 less than and usually comparable with norm(A) in
 magnitude, and BETA always less than and usually
 comparable with norm(B).

BETA (output)
 See the description of ALPHA.

VSL (input)
 If JOBVSL = 'V', VSL will contain the left Schur
 vectors. (See "Purpose", above.) Not referenced
 if JOBVSL = 'N'.

LDVSL (input)
 The leading dimension of the matrix VSL. LDVSL >=
 1, and if JOBVSL = 'V', LDVSL >= N.

VSR (input)
 If JOBVSR = 'V', VSR will contain the right Schur
 vectors. (See "Purpose", above.) Not referenced
 if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR \geq 1, and if JOBVSR = 'V', LDVSR \geq N.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq max(1,2*N). For good performance, LDWORK must generally be larger. To compute the optimal value of LDWORK, call ILAENV to get blocksizes (for ZGEQRF, CUNMQR, and CUNGQR.) Then compute: NB as the MAX of the blocksizes for ZGEQRF, CUNMQR, and CUNGQR; the optimal LDWORK is N*(NB+1).

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)

dimension(3*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
=1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHA(j) and BETA(j) should be correct for j=INFO+1,...,N. > N: errors that usually indicate LAPACK problems:
=N+1: error return from CGGBAL
=N+2: error return from ZGEQRF
=N+3: error return from CUNMQR
=N+4: error return from CUNGQR
=N+5: error return from CGGHRD
=N+6: error return from CHGEQZ (other than failed iteration) =N+7: error return from CGGBAK (computing VSL)
=N+8: error return from CGGBAK (computing VSR)
=N+9: error return from CLASCL (various places)

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NAME

zgegv - routine is deprecated and has been replaced by routine CGGEV

SYNOPSIS

```
SUBROUTINE ZGEGV(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHA, BETA, VL,
                LDVL, VR, LDVR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZGEGV_64(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHA, BETA, VL,
                  LDVL, VR, LDVR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER*8 N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEGV(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHA, BETA,
               VL, [LDVL], VR, [LDVR], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, VL, VR
INTEGER :: N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEGV_64(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHA,
                  BETA, VL, [LDVL], VR, [LDVR], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
```

```
COMPLEX(8), DIMENSION(:, :) :: A, B, VL, VR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, LDWORK, INFO
REAL(8), DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>

void zgegv(char jobvl, char jobvr, int n, doublecomplex *a,
           int lda, doublecomplex *b, int ldb, doublecomplex
           *alpha, doublecomplex *beta, doublecomplex *vl,
           int ldvl, doublecomplex *vr, int ldvr, int *info);

void zgegv_64(char jobvl, char jobvr, long n, doublecomplex
              *a, long lda, doublecomplex *b, long ldb, doublecomplex
              *alpha, doublecomplex *beta, doublecomplex *vl, long ldvl,
              doublecomplex *vr, long ldvr, long *info);
```

PURPOSE

zgegv routine is deprecated and has been replaced by routine CGGEV.

ZGEGV computes for a pair of N-by-N complex nonsymmetric matrices A and B, the generalized eigenvalues (alpha, beta), and optionally, the left and/or right generalized eigenvectors (VL and VR).

A generalized eigenvalue for a pair of matrices (A,B) is, roughly speaking, a scalar w or a ratio $\alpha/\beta = w$, such that $A - wB$ is singular. It is usually represented as the pair (alpha,beta), as there is a reasonable interpretation for $\beta=0$, and even for both being zero. A good beginning reference is the book, "Matrix Computations", by G. Golub & C. van Loan (Johns Hopkins U. Press)

A right generalized eigenvector corresponding to a generalized eigenvalue w for a pair of matrices (A,B) is a vector r such that $(A - w B) r = 0$. A left generalized eigenvector is a vector l such that $l^*H * (A - w B) = 0$, where l^*H is the conjugate-transpose of l.

Note: this routine performs "full balancing" on A and B. See "Further Details", below.

ARGUMENTS

JOBVL (input)
= 'N': do not compute the left generalized eigenvectors;
= 'V': compute the left generalized eigenvectors.

JOBVR (input)
= 'N': do not compute the right generalized eigenvectors;

= 'V': compute the right generalized eigenvectors.
N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)
On entry, the first of the pair of matrices whose generalized eigenvalues and (optionally) generalized eigenvectors are to be computed. On exit, the contents will have been destroyed. (For a description of the contents of A on exit, see "Further Details", below.)

LDA (input)
The leading dimension of A. $LDA \geq \max(1, N)$.

B (input/output)
On entry, the second of the pair of matrices whose generalized eigenvalues and (optionally) generalized eigenvectors are to be computed. On exit, the contents will have been destroyed. (For a description of the contents of B on exit, see "Further Details", below.)

LDB (input)
The leading dimension of B. $LDB \geq \max(1, N)$.

ALPHA (output)
On exit, $ALPHA(j)/VL(j)$, $j=1, \dots, N$, will be the generalized eigenvalues.

Note: the quotients $ALPHA(j)/VL(j)$ may easily overflow or underflow, and $VL(j)$ may even be zero. Thus, the user should avoid naively computing the ratio α/β . However, ALPHA will be always less than and usually comparable with $\text{norm}(A)$ in magnitude, and VL always less than and usually comparable with $\text{norm}(B)$.

BETA (output)
If $JOBVL = 'V'$, the left generalized eigenvectors. (See "Purpose", above.) Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha=\beta=0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if $JOBVL = 'N'$.

VL (output)
If $JOBVL = 'V'$, the left generalized eigenvectors. (See "Purpose", above.) Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha=\beta=0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if $JOBVL = 'N'$.

LDVL (input)
The leading dimension of the matrix VL. $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (output)

If JOBVR = 'V', the right generalized eigenvectors. (See "Purpose", above.) Each eigenvector will be scaled so the largest component will have $\text{abs}(\text{real part}) + \text{abs}(\text{imag. part}) = 1$, *except* that for eigenvalues with $\alpha=\beta=0$, a zero vector will be returned as the corresponding eigenvector. Not referenced if JOBVR = 'N'.

LDVR (input)

The leading dimension of the matrix VR. LDVR ≥ 1 , and if JOBVR = 'V', LDVR $\geq N$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK $\geq \max(1, 2*N)$. For good performance, LDWORK must generally be larger. To compute the optimal value of LDWORK, call ILAENV to get block sizes (for ZGEQRF, CUNMQR, and CUNGQR.) Then compute: NB as the MAX of the block sizes for ZGEQRF, CUNMQR, and CUNGQR; The optimal LDWORK is $\text{MAX}(2*N, N*(NB+1))$.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)

dimension(8*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
=1,...,N: The QZ iteration failed. No eigenvectors have been calculated, but ALPHA(j) and VL(j) should be correct for $j=\text{INFO}+1, \dots, N$. > N: errors that usually indicate LAPACK problems:
=N+1: error return from CGGBAL
=N+2: error return from ZGEQRF
=N+3: error return from CUNMQR
=N+4: error return from CUNGQR
=N+5: error return from CGGHRD
=N+6: error return from CHGEQZ (other than failed iteration) =N+7: error return from CTGEVC
=N+8: error return from CGGBAK (computing VL)
=N+9: error return from CGGBAK (computing VR)
=N+10: error return from CLASCL (various calls)

FURTHER DETAILS

Balancing

This driver calls CGGBAL to both permute and scale rows and columns of A and B. The permutations PL and PR are chosen

so that PL^*A^*PR and PL^*B^*R will be upper triangular except for the diagonal blocks $A(i:j,i:j)$ and $B(i:j,i:j)$, with i and j as close together as possible. The diagonal scaling matrices DL and DR are chosen so that the pair $DL^*PL^*A^*PR^*DR$, $DL^*PL^*B^*PR^*DR$ have elements close to one (except for the elements that start out zero.)

After the eigenvalues and eigenvectors of the balanced matrices have been computed, CGGBAK transforms the eigenvectors back to what they would have been (in perfect arithmetic) if they had not been balanced.

Contents of A and B on Exit

If any eigenvectors are computed (either $JOBVL='V'$ or $JOBVR='V'$ or both), then on exit the arrays A and B will contain the complex Schur form[*] of the "balanced" versions of A and B. If no eigenvectors are computed, then only the diagonal blocks will be correct.

[*] In other words, upper triangular form.

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NAME

zgehrd - reduce a complex general matrix A to upper Hessenberg form H by a unitary similarity transformation

SYNOPSIS

```
SUBROUTINE ZGHRD(N, ILO, IHI, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORKIN(*)  
INTEGER N, ILO, IHI, LDA, LWORKIN, INFO
```

```
SUBROUTINE ZGHRD_64(N, ILO, IHI, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORKIN(*)  
INTEGER*8 N, ILO, IHI, LDA, LWORKIN, INFO
```

F95 INTERFACE

```
SUBROUTINE GEHRD([N], ILO, IHI, A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORKIN  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, ILO, IHI, LDA, LWORKIN, INFO
```

```
SUBROUTINE GEHRD_64([N], ILO, IHI, A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORKIN  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, ILO, IHI, LDA, LWORKIN, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgehrd(int n, int ilo, int ihi, doublecomplex *a, int  
lda, doublecomplex *tau, int *info);
```

```
void zgehrd_64(long n, long ilo, long ihi, doublecomplex *a,  
long lda, doublecomplex *tau, long *info);
```

PURPOSE

zgehrd reduces a complex general matrix A to upper Hessenberg form H by a unitary similarity transformation: $Q' * A * Q = H$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to ZGEBAL; otherwise they should be set to 1 and N respectively. See Further Details.

IHI (input)

See the description of ILO.

A (input/output)

On entry, the N-by-N general matrix to be reduced. On exit, the upper triangle and the first subdiagonal of A are overwritten with the upper Hessenberg matrix H, and the elements below the first subdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details). Elements 1:ILO-1 and IHI:N-1 of TAU are set to zero.

WORKIN (workspace)

On exit, if INFO = 0, WORKIN(1) returns the optimal LWORKIN.

LWORKIN (input)

The length of the array WORKIN. $LWORKIN \geq \max(1, N)$. For optimum performance $LWORKIN \geq N * NB$, where NB is the optimal blocksize.

If LWORKIN = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORKIN array, returns this value as the first entry of the WORKIN array, and no error message related to LWORKIN is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-

gal value.

FURTHER DETAILS

The matrix Q is represented as a product of $(ihi-ilo)$ elementary reflectors

$$Q = H(ilo) H(ilo+1) \dots H(ihi-1).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a complex scalar, and v is a complex vector with $v(1:i) = 0$, $v(i+1) = 1$ and $v(ihi+1:n) = 0$; $v(i+2:ihi)$ is stored on exit in $A(i+2:ihi,i)$, and τ in $TAU(i)$.

The contents of A are illustrated by the following example, with $n = 7$, $ilo = 2$ and $ihi = 6$:

on entry,

on exit,

```
( a a a a a a a ) ( a a h h h h
a ) ( a a a a a a a ) ( a h h h
h a ) ( a a a a a a a ) ( h h h
h h h ) ( a a a a a a a ) ( v2 h
h h h h ) ( a a a a a a a ) ( v2
v3 h h h h ) ( a a a a a a ) (
v2 v3 v4 h h h ) ( a ) (
a )
```

where a denotes an element of the original matrix A , h denotes a modified element of the upper Hessenberg matrix H , and v_i denotes an element of the vector defining $H(i)$.

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NAME

zgelqf - compute an LQ factorization of a complex M-by-N matrix A

SYNOPSIS

```
SUBROUTINE ZGELQF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE ZGELQF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GELQF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE GELQF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgelqf(int m, int n, doublecomplex *a, int lda, doublecomplex *tau, int *info);
```

```
void zgelqf_64(long m, long n, doublecomplex *a, long lda, doublecomplex *tau, long *info);
```

PURPOSE

zgelqf computes an LQ factorization of a complex M-by-N matrix A: $A = L * Q$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the elements on and below the diagonal of the array contain the m-by-min(m,n) lower trapezoidal matrix L (L is lower triangular if $m \leq n$); the elements above the diagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, M)$. For optimum performance $LDWORK \geq M * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(k)' \dots H(2)' H(1)', \text{ where } k = \min(m, n).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $\text{conjg}(v(i+1:n))$ is stored on exit in $A(i,i+1:n)$, and tau in $TAU(i)$.

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NAME

zgels - solve overdetermined or underdetermined complex linear systems involving an M-by-N matrix A, or its conjugate-transpose, using a QR or LQ factorization of A

SYNOPSIS

```
SUBROUTINE ZGELS(TRANSA, M, N, NRHS, A, LDA, B, LDB, WORK, LDWORK,  
                INFO)
```

```
CHARACTER * 1 TRANSA  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE ZGELS_64(TRANSA, M, N, NRHS, A, LDA, B, LDB, WORK, LDWORK,  
                   INFO)
```

```
CHARACTER * 1 TRANSA  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GELS([TRANSA], [M], [N], [NRHS], A, [LDA], B, [LDB], [WORK],  
               LDWORK, [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE GELS_64([TRANSA], [M], [N], [NRHS], A, [LDA], B, [LDB],  
                  [WORK], LDWORK, [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER(8) :: M, N, NRHS, LDA, LDB, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zgels (char, int, int, int, doublecomplex*, int, doublecomplex*, int, int*);

void zgels_64 (char, long, long, long, doublecomplex*, long, doublecomplex*, long, long*);

```

PURPOSE

zgels solves overdetermined or underdetermined complex linear systems involving an M-by-N matrix A, or its conjugate-transpose, using a QR or LQ factorization of A. It is assumed that A has full rank.

The following options are provided:

1. If TRANS = 'N' and $m \geq n$: find the least squares solution of
an overdetermined system, i.e., solve the least squares problem

$$\text{minimize } \| B - A * X \|^2.$$

2. If TRANS = 'N' and $m < n$: find the minimum norm solution of
an underdetermined system $A * X = B$.

3. If TRANS = 'C' and $m \geq n$: find the minimum norm solution of
an undetermined system $A^{*H} * X = B$.

4. If TRANS = 'C' and $m < n$: find the least squares solution of
an overdetermined system, i.e., solve the least squares problem

$$\text{minimize } \| B - A^{*H} * X \|^2.$$

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

ARGUMENTS

TRANSA (input)
= 'N': the linear system involves A;
= 'C': the linear system involves A^{*H} .

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. if $M \geq N$, A is overwritten by details of its QR factorization as returned by ZGEQRF; if $M < N$, A is overwritten by details of its LQ factorization as returned by ZGELQF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)

On entry, the matrix B of right hand side vectors, stored columnwise; B is M-by-NRHS if TRANSA = 'N', or N-by-NRHS if TRANSA = 'C'. On exit, B is overwritten by the solution vectors, stored columnwise: if TRANSA = 'N' and $m \geq n$, rows 1 to n of B contain the least squares solution vectors; the residual sum of squares for the solution in each column is given by the sum of squares of elements N+1 to M in that column; if TRANSA = 'N' and $m < n$, rows 1 to N of B contain the minimum norm solution vectors; if TRANSA = 'C' and $m \geq n$, rows 1 to M of B contain the minimum norm solution vectors; if TRANSA = 'C' and $m < n$, rows 1 to M of B contain the least squares solution vectors; the residual sum of squares for the solution in each column is given by the sum of squares of elements M+1 to N in that column.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, M, N)$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (output)

The dimension of the array WORK. $LDWORK \geq \max(1, MN + \max(MN, NRHS))$. For optimal performance, $LDWORK \geq \max(1, MN + \max(MN, NRHS) * NB)$. where $MN = \min(M, N)$ and NB is the optimum block size.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zgelsd - compute the minimum-norm solution to a real linear least squares problem

SYNOPSIS

```
SUBROUTINE ZGELSD(M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK, WORK,  
                LWORK, RWORK, IWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION S(*), RWORK(*)
```

```
SUBROUTINE ZGELSD_64(M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK,  
                   WORK, LWORK, RWORK, IWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION S(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSD([M], [N], [NRHS], A, [LDA], B, [LDB], S, RCOND,  
                RANK, [WORK], [LWORK], [RWORK], [IWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: S, RWORK
```

```
SUBROUTINE GELSD_64([M], [N], [NRHS], A, [LDA], B, [LDB], S, RCOND,  
                   RANK, [WORK], [LWORK], [RWORK], [IWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK
```

```

COMPLEX(8), DIMENSION(:, :) :: A, B
INTEGER(8) :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: S, RWORK

```

C INTERFACE

```

#include <sunperf.h>
void zgelsd(int m, int n, int nrhs, doublecomplex *a, int
            lda, doublecomplex *b, int ldb, double *s, double
            rcond, int *rank, int *info);

void zgelsd_64(long m, long n, long nrhs, doublecomplex *a,
              long lda, doublecomplex *b, long ldb, double *s,
              double rcond, long *rank, long *info);

```

PURPOSE

zgelsd computes the minimum-norm solution to a real linear least squares problem:

minimize 2-norm(| b - A*x |)
using the singular value decomposition (SVD) of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The problem is solved in three steps:

- (1) Reduce the coefficient matrix A to bidiagonal form with Householder transformations, reducing the original problem into a "bidiagonal least squares problem" (BLS)
- (2) Solve the BLS using a divide and conquer approach.
- (3) Apply back all the Householder transformations to solve the original least squares problem.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

M (input) The number of rows of the matrix A. M >= 0.

N (input) The number of columns of the matrix A. N >= 0.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS \geq 0.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A has been destroyed.

LDA (input)
 The leading dimension of the array A. LDA \geq max(1,M).

B (input/output)
 On entry, the M-by-NRHS right hand side matrix B. On exit, B is overwritten by the N-by-NRHS solution matrix X. If $m \geq n$ and RANK = n, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements n+1:m in that column.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,M,N).

S (output)
 The singular values of A in decreasing order. The condition number of A in the 2-norm = S(1)/S(min(m,n)).

RCOND (input)
 RCOND is used to determine the effective rank of A. Singular values S(i) \leq RCOND*S(1) are treated as zero. If RCOND < 0, machine precision is used instead.

RANK (output)
 The effective rank of A, i.e., the number of singular values which are greater than RCOND*S(1).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq 1. The exact minimum amount of workspace needed depends on M, N and NRHS. If $M \geq N$, LWORK $\geq 2*N + N*NRHS$. If $M < N$, LWORK $\geq 2*M + M*NRHS$. For good performance, LWORK should generally be larger.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
 If $M \geq N$, LRWORK $\geq 8*N + 2*N*SMLSIZ + 8*N*NLVL + N*NRHS$. If $M < N$, LRWORK $\geq 8*M + 2*M*SMLSIZ + 8*M*NLVL + M*NRHS$. SMLSIZ is returned by ILAENV

and is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25), and $NLVL = \text{INT}(\text{LOG}_2(\text{MIN}(M,N)/(\text{SMLSIZ}+1))) + 1$

IWORK (workspace)

$LIWORK \geq 3 * \text{MINMN} * NLVL + 11 * \text{MINMN}$, where $\text{MINMN} = \text{MIN}(M,N)$.

INFO (output)

= 0: successful exit

< 0: if $\text{INFO} = -i$, the i -th argument had an illegal value.

> 0: the algorithm for computing the SVD failed to converge; if $\text{INFO} = i$, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

FURTHER DETAILS

Based on contributions by

Ming Gu and Ren-Cang Li, Computer Science Division,
University of California at Berkeley, USA

Osni Marques, LBNL/NERSC, USA

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NAME

zgelss - compute the minimum norm solution to a complex linear least squares problem

SYNOPSIS

```
SUBROUTINE ZGELSS(M, N, NRHS, A, LDA, B, LDB, SING, RCOND, IRANK,  
                WORK, LDWORK, WORK2, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION SING(*), WORK2(*)
```

```
SUBROUTINE ZGELSS_64(M, N, NRHS, A, LDA, B, LDB, SING, RCOND, IRANK,  
                   WORK, LDWORK, WORK2, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION SING(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GELSS([M], [N], [NRHS], A, [LDA], B, [LDB], SING, RCOND,  
                IRANK, [WORK], [LDWORK], [WORK2], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: SING, WORK2
```

```
SUBROUTINE GELSS_64([M], [N], [NRHS], A, [LDA], B, [LDB], SING,  
                   RCOND, IRANK, [WORK], [LDWORK], [WORK2], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, B  
INTEGER(8) :: M, N, NRHS, LDA, LDB, IRANK, LDWORK, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: SING, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void zgelss(int m, int n, int nrhs, doublecomplex *a, int
           lda, doublecomplex *b, int ldb, double *sing, dou-
           ble rcond, int *irank, int *info);
void zgelss_64(long m, long n, long nrhs, doublecomplex *a,
              long lda, doublecomplex *b, long ldb, double
              *sing, double rcond, long *irank, long *info);
```

PURPOSE

zgelss computes the minimum norm solution to a complex linear least squares problem:

Minimize 2-norm(| b - A*x |).

using the singular value decomposition (SVD) of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

ARGUMENTS

M (input) The number of rows of the matrix A. M >= 0.

N (input) The number of columns of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)

On entry, the M-by-N matrix A. On exit, the first min(m,n) rows of A are overwritten with its right singular vectors, stored rowwise.

LDA (input)

The leading dimension of the array A. LDA >= max(1,M).

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, B is overwritten by the N-by-NRHS solution matrix X. If m >= n and IRANK = n, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements n+1:m in that column.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,M,N).

SING (output)
The singular values of A in decreasing order. The condition number of A in the 2-norm = SING(1)/SING(min(m,n)).

RCOND (input)
RCOND is used to determine the effective rank of A. Singular values SING(i) \leq RCOND*SING(1) are treated as zero. If RCOND $<$ 0, machine precision is used instead.

IRANK (output)
The effective rank of A, i.e., the number of singular values which are greater than RCOND*SING(1).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
The dimension of the array WORK. LDWORK \geq 1, and also: LDWORK \geq 2*min(M,N) + max(M,N,NRHS) For good performance, LDWORK should generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
dimension(5*min(M,N))

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: the algorithm for computing the SVD failed to converge; if INFO = i, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

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NAME

zgelsx - routine is deprecated and has been replaced by routine ZGELSY

SYNOPSIS

```
SUBROUTINE ZGELSX(M, N, NRHS, A, LDA, B, LDB, JPIVOT, RCOND, IRANK,  
                WORK, WORK2, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER JPIVOT(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZGELSX_64(M, N, NRHS, A, LDA, B, LDB, JPIVOT, RCOND,  
                   IRANK, WORK, WORK2, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER*8 JPIVOT(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GELSX([M], [N], [NRHS], A, [LDA], B, [LDB], JPIVOT, RCOND,  
                IRANK, [WORK], [WORK2], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, IRANK, INFO  
INTEGER, DIMENSION(:) :: JPIVOT  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE GELSX_64([M], [N], [NRHS], A, [LDA], B, [LDB], JPIVOT,  
                   RCOND, IRANK, [WORK], [WORK2], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER(8) :: M, N, NRHS, LDA, LDB, IRANK, INFO
```

```

INTEGER(8), DIMENSION(:) :: JPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>
void zgelsx(int m, int n, int nrhs, doublecomplex *a, int
            lda, doublecomplex *b, int ldb, int *jpivot, dou-
            ble rcond, int *irank, int *info);

void zgelsx_64(long m, long n, long nrhs, doublecomplex *a,
              long lda, doublecomplex *b, long ldb, long
              *jpivot, double rcond, long *irank, long *info);

```

PURPOSE

zgelsx routine is deprecated and has been replaced by routine ZGELSY.

ZGELSX computes the minimum-norm solution to a complex linear least squares problem:

$$\text{minimize } || A * X - B ||$$

using a complete orthogonal factorization of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The routine first computes a QR factorization with column pivoting:

$$A * P = Q * \begin{bmatrix} R11 & R12 \\ 0 & R22 \end{bmatrix}$$

with R11 defined as the largest leading submatrix whose estimated condition number is less than 1/RCOND. The order of R11, RANK, is the effective rank of A.

Then, R22 is considered to be negligible, and R12 is annihilated by unitary transformations from the right, arriving at the complete orthogonal factorization:

$$A * P = Q * \begin{bmatrix} T11 & 0 \\ 0 & 0 \end{bmatrix} * Z$$

The minimum-norm solution is then

$$X = P * Z' \begin{bmatrix} \text{inv}(T11) * Q1' * B \\ 0 \end{bmatrix}$$

where Q1 consists of the first RANK columns of Q.

ARGUMENTS

M (input) The number of rows of the matrix A. M >= 0.

N (input) The number of columns of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number

of columns of matrices B and X. NRHS \geq 0.

A (input/output)

On entry, the M-by-N matrix A. On exit, A has been overwritten by details of its complete orthogonal factorization.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,M).

B (input/output)

On entry, the M-by-NRHS right hand side matrix B. On exit, the N-by-NRHS solution matrix X. If $m \geq n$ and IRANK = n, the residual sum-of-squares for the solution in the i-th column is given by the sum of squares of elements N+1:M in that column.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,M,N).

JPIVOT (input/output)

On entry, if JPIVOT(i) \neq 0, the i-th column of A is an initial column, otherwise it is a free column. Before the QR factorization of A, all initial columns are permuted to the leading positions; only the remaining free columns are moved as a result of column pivoting during the factorization. On exit, if JPIVOT(i) = k, then the i-th column of A*P was the k-th column of A.

RCOND (input)

RCOND is used to determine the effective rank of A, which is defined as the order of the largest leading triangular submatrix R11 in the QR factorization with pivoting of A, whose estimated condition number $< 1/\text{RCOND}$.

IRANK (output)

The effective rank of A, i.e., the order of the submatrix R11. This is the same as the order of the submatrix T11 in the complete orthogonal factorization of A.

WORK (workspace)

(min(M,N) + max(N, 2*min(M,N)+NRHS)),

WORK2 (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zgelsy - compute the minimum-norm solution to a complex linear least squares problem

SYNOPSIS

```
SUBROUTINE ZGELSY(M, N, NRHS, A, LDA, B, LDB, JPVT, RCOND, RANK,  
                WORK, LWORK, RWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER JPVT(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZGELSY_64(M, N, NRHS, A, LDA, B, LDB, JPVT, RCOND, RANK,  
                   WORK, LWORK, RWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER*8 JPVT(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GELSY([M], [N], [NRHS], A, [LDA], B, [LDB], JPVT, RCOND,  
                RANK, [WORK], [LWORK], [RWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO  
INTEGER, DIMENSION(:) :: JPVT  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: RWORK
```

```
SUBROUTINE GELSY_64([M], [N], [NRHS], A, [LDA], B, [LDB], JPVT,  
                   RCOND, RANK, [WORK], [LWORK], [RWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK
```

```

COMPLEX(8), DIMENSION(:, :) :: A, B
INTEGER(8) :: M, N, NRHS, LDA, LDB, RANK, LWORK, INFO
INTEGER(8), DIMENSION(:) :: JPVT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>
void zgelsy(int m, int n, int nrhs, doublecomplex *a, int
            lda, doublecomplex *b, int ldb, int *jpvt, double
            rcond, int *rank, int *info);

void zgelsy_64(long m, long n, long nrhs, doublecomplex *a,
               long lda, doublecomplex *b, long ldb, long *jpvt,
               double rcond, long *rank, long *info);

```

PURPOSE

zgelsy computes the minimum-norm solution to a complex linear least squares problem:

minimize $\|A * X - B\|$
using a complete orthogonal factorization of A. A is an M-by-N matrix which may be rank-deficient.

Several right hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the M-by-NRHS right hand side matrix B and the N-by-NRHS solution matrix X.

The routine first computes a QR factorization with column pivoting:

$$A * P = Q * \begin{bmatrix} R11 & R12 \\ 0 & R22 \end{bmatrix}$$

with R11 defined as the largest leading submatrix whose estimated condition number is less than 1/RCOND. The order of R11, RANK, is the effective rank of A.

Then, R22 is considered to be negligible, and R12 is annihilated by unitary transformations from the right, arriving at the complete orthogonal factorization:

$$A * P = Q * \begin{bmatrix} T11 & 0 \\ 0 & 0 \end{bmatrix} * Z$$

The minimum-norm solution is then

$$X = P * Z' \begin{bmatrix} \text{inv}(T11) * Q1' * B \\ 0 \end{bmatrix}$$

where Q1 consists of the first RANK columns of Q.

This routine is basically identical to the original xGELSX except three differences:

- o The permutation of matrix B (the right hand side) is faster and more simple.
- o The call to the subroutine xGEQPF has been substituted by the call to the subroutine xGEQP3. This subroutine is a Blas-3 version of the QR factorization with column pivoting.
- o Matrix B (the right hand side) is updated with Blas-3.

ARGUMENTS

- M (input) The number of rows of the matrix A. $M \geq 0$.
- N (input) The number of columns of the matrix A. $N \geq 0$.
- NRHS (input)
The number of right hand sides, i.e., the number of columns of matrices B and X. $NRHS \geq 0$.
- A (input/output)
On entry, the M-by-N matrix A. On exit, A has been overwritten by details of its complete orthogonal factorization.
- LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.
- B (input/output)
On entry, the M-by-NRHS right hand side matrix B. On exit, the N-by-NRHS solution matrix X.
- LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, M, N)$.
- JPVT (input/output)
On entry, if $JPVT(i) \neq 0$, the i-th column of A is permuted to the front of AP, otherwise column i is a free column. On exit, if $JPVT(i) = k$, then the i-th column of A^*P was the k-th column of A.
- RCOND (input)
RCOND is used to determine the effective rank of A, which is defined as the order of the largest leading triangular submatrix R11 in the QR factorization with pivoting of A, whose estimated condition number $< 1/RCOND$.
- RANK (output)
The effective rank of A, i.e., the order of the submatrix R11. This is the same as the order of the submatrix T11 in the complete orthogonal factorization of A.
- WORK (workspace)
On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.
- LWORK (input)
The dimension of the array WORK. The unblocked strategy requires that: $LWORK \geq MN + \max(2*MN, N+1, MN+NRHS)$ where $MN = \min(M, N)$. The block algorithm requires that: $LWORK \geq MN + \max(2*MN, NB*(N+1), MN+MN*NB, MN+NB*NRHS)$ where NB is an upper bound on the blocksize returned by ILAENV for the routines ZGEP3, CTZRZF, CTZRQF, CUNMQR, and CUNMRZ.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
dimension(2*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by

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E. Quintana-Orti, Depto. de Informatica, Universidad Jaime I, Spain

G. Quintana-Orti, Depto. de Informatica, Universidad Jaime I, Spain

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NAME

zgemm - perform one of the matrix-matrix operations $C := \alpha * op(A) * op(B) + \beta * C$

SYNOPSIS

```
SUBROUTINE ZGEMM(TRANSA, TRANSB, M, N, K, ALPHA, A, LDA, B, LDB,
  BETA, C, LDC)
```

```
CHARACTER * 1 TRANSA, TRANSB
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER M, N, K, LDA, LDB, LDC
```

```
SUBROUTINE ZGEMM_64(TRANSA, TRANSB, M, N, K, ALPHA, A, LDA, B, LDB,
  BETA, C, LDC)
```

```
CHARACTER * 1 TRANSA, TRANSB
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 M, N, K, LDA, LDB, LDC
```

F95 INTERFACE

```
SUBROUTINE GEMM([TRANSA], [TRANSB], [M], [N], [K], ALPHA, A, [LDA],
  B, [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: TRANSA, TRANSB
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:,*) :: A, B, C
INTEGER :: M, N, K, LDA, LDB, LDC
```

```
SUBROUTINE GEMM_64([TRANSA], [TRANSB], [M], [N], [K], ALPHA, A, [LDA],
  B, [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: TRANSA, TRANSB
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:,*) :: A, B, C
INTEGER(8) :: M, N, K, LDA, LDB, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zgemm(char transa, char transb, int m, int n, int k,
           doublecomplex *alpha, doublecomplex *a, int lda,
           doublecomplex *b, int ldb, doublecomplex *beta,
           doublecomplex *c, int ldc);
void zgemm_64(char transa, char transb, long m, long n, long k,
              doublecomplex *alpha, doublecomplex *a, long lda,
              doublecomplex *b, long ldb, doublecomplex *beta,
              doublecomplex *c, long ldc);

```

PURPOSE

zgemm performs one of the matrix-matrix operations

$$C := \alpha * \text{op}(A) * \text{op}(B) + \beta * C$$

where $\text{op}(X)$ is one of

$\text{op}(X) = X$ or $\text{op}(X) = X'$ or $\text{op}(X) = \text{conjg}(X')$, α and β are scalars, and A , B and C are matrices, with $\text{op}(A)$ an m by k matrix, $\text{op}(B)$ a k by n matrix and C an m by n matrix.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n', $\text{op}(A) = A$.

TRANSA = 'T' or 't', $\text{op}(A) = A'$.

TRANSA = 'C' or 'c', $\text{op}(A) = \text{conjg}(A')$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

TRANSB (input)

On entry, TRANSB specifies the form of $\text{op}(B)$ to be used in the matrix multiplication as follows:

TRANSB = 'N' or 'n', $\text{op}(B) = B$.

TRANSB = 'T' or 't', $\text{op}(B) = B'$.

TRANSB = 'C' or 'c', $\text{op}(B) = \text{conjg}(B')$.

Unchanged on exit.

TRANSB is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix $\text{op}(A)$ and of the matrix C . $M \geq$

0. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix $op(B)$ and the number of columns of the matrix C. $N \geq 0$. Unchanged on exit.

K (input)

On entry, K specifies the number of columns of the matrix $op(A)$ and the number of rows of the matrix $op(B)$. $K \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

COMPLEX*16 array of DIMENSION (LDA, ka), where ka is K when TRANSA = 'N' or 'n', and is M otherwise. Before entry with TRANSA = 'N' or 'n', the leading M by K part of the array A must contain the matrix A, otherwise the leading K by M part of the array A must contain the matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When TRANSA = 'N' or 'n' then $LDA \geq \max(1, M)$, otherwise $LDA \geq \max(1, K)$. Unchanged on exit.

B (input)

COMPLEX*16 array of DIMENSION (LDB, kb), where kb is n when TRANSB = 'N' or 'n', and is k otherwise. Before entry with TRANSB = 'N' or 'n', the leading k by n part of the array B must contain the matrix B, otherwise the leading n by k part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. When TRANSB = 'N' or 'n' then $LDB \geq \max(1, k)$, otherwise $LDB \geq \max(1, n)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then C need not be set on input. Unchanged on exit.

C (input/output)

COMPLEX*16 array of DIMENSION (LDC, n). Before entry, the leading m by n part of the array C must contain the matrix C, except when beta is zero, in which case C need not be set on entry. On exit, the array C is overwritten by the m by n matrix $(\alpha * op(A) * op(B) + \beta * C)$.

LDC (input)

On entry, LDC specifies the first dimension of C

as declared in the calling (sub) program.
LDC \geq max(1, m). Unchanged on exit.

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NAME

zgenv - perform one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A' x + \beta y$, or $y := \alpha \text{conjg}(A') x + \beta y$

SYNOPSIS

```
SUBROUTINE ZGEMV(TRANSA, M, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 TRANSA  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER M, N, LDA, INCX, INCY
```

```
SUBROUTINE ZGEMV_64(TRANSA, M, N, ALPHA, A, LDA, X, INCX, BETA, Y,  
    INCY)
```

```
CHARACTER * 1 TRANSA  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER*8 M, N, LDA, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE GEMV([TRANSA], [M], [N], ALPHA, A, [LDA], X, [INCX], BETA,  
    Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, INCX, INCY
```

```
SUBROUTINE GEMV_64([TRANSA], [M], [N], ALPHA, A, [LDA], X, [INCX],  
    BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>

void zgemv(char transa, int m, int n, doublecomplex *alpha,
           doublecomplex *a, int lda, doublecomplex *x, int
           incx, doublecomplex *beta, doublecomplex *y, int
           incy);

void zgemv_64(char transa, long m, long n, doublecomplex
              *alpha, doublecomplex *a, long lda, doublecomplex
              *x, long incx, doublecomplex *beta, doublecomplex
              *y, long incy);
```

PURPOSE

zgemv performs one of the matrix-vector operations $y := \alpha A x + \beta y$, or $y := \alpha A' x + \beta y$, or $y := \alpha \text{conjg}(A) x + \beta y$ where α and β are scalars, x and y are vectors and A is an m by n matrix.

ARGUMENTS

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $y := \alpha A x + \beta y$.

TRANSA = 'T' or 't' $y := \alpha A' x + \beta y$.

TRANSA = 'C' or 'c' $y := \alpha \text{conjg}(A) x + \beta y$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry, the leading m by n part of the array A must contain the matrix of coefficients. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, m)$. Unchanged on exit.

X (input)
(1 + (n - 1) * abs(INCX)) when TRANSA = 'N' or 'n' and at least (1 + (m - 1) * abs(INCX)) otherwise. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)
On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

BETA (input)
On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)
(1 + (m - 1) * abs(INCY)) when TRANSA = 'N' or 'n' and at least (1 + (n - 1) * abs(INCY)) otherwise. Before entry with BETA non-zero, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)
On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

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NAME

zgeqlf - compute a QL factorization of a complex M-by-N matrix A

SYNOPSIS

```
SUBROUTINE ZGEQLF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE ZGEQLF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GEQLF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE GEQLF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgeqlf(int m, int n, doublecomplex *a, int lda, doublecomplex *tau, int *info);
```

```
void zgeqlf_64(long m, long n, doublecomplex *a, long lda, doublecomplex *tau, long *info);
```

PURPOSE

zgeqlf computes a QL factorization of a complex M-by-N matrix A: $A = Q * L$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $m \geq n$, the lower triangle of the subarray $A(m-n+1:m, 1:n)$ contains the N-by-N lower triangular matrix L; if $m < n$, the elements on and below the (n-m)-th superdiagonal contain the M-by-N lower trapezoidal matrix L; the remaining elements, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(k) \dots H(2) H(1)$, where $k = \min(m, n)$.
Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a complex scalar, and v is a complex vector with $v(m-k+i+1:m) = 0$ and $v(m-k+i) = 1$; $v(1:m-k+i-1)$ is stored on exit in $A(1:m-k+i-1, n-k+i)$, and τ in $TAU(i)$.

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NAME

zgeqp3 - compute a QR factorization with column pivoting of a matrix A

SYNOPSIS

```
SUBROUTINE ZGEQP3(M, N, A, LDA, JPVT, TAU, WORK, LWORK, RWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)
INTEGER M, N, LDA, LWORK, INFO
INTEGER JPVT(*)
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZGEQP3_64(M, N, A, LDA, JPVT, TAU, WORK, LWORK, RWORK,
INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)
INTEGER*8 M, N, LDA, LWORK, INFO
INTEGER*8 JPVT(*)
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GEQP3([M], [N], A, [LDA], JPVT, TAU, [WORK], [LWORK],
[RWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:,:) :: A
INTEGER :: M, N, LDA, LWORK, INFO
INTEGER, DIMENSION(:) :: JPVT
REAL(8), DIMENSION(:) :: RWORK
```

```
SUBROUTINE GEQP3_64([M], [N], A, [LDA], JPVT, TAU, [WORK], [LWORK],
[RWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:,:) :: A
INTEGER(8) :: M, N, LDA, LWORK, INFO
INTEGER(8), DIMENSION(:) :: JPVT
REAL(8), DIMENSION(:) :: RWORK
```

C INTERFACE

```
#include <sunperf.h>

void zgeqp3(int m, int n, doublecomplex *a, int lda, int
           *jpvt, doublecomplex *tau, int *info);

void zgeqp3_64(long m, long n, doublecomplex *a, long lda,
              long *jpvt, doublecomplex *tau, long *info);
```

PURPOSE

zgeqp3 computes a QR factorization with column pivoting of a matrix A: $A^*P = Q^*R$ using Level 3 BLAS.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the upper triangle of the array contains the $\min(M,N)$ -by-N upper trapezoidal matrix R; the elements below the diagonal, together with the array TAU, represent the unitary matrix Q as a product of $\min(M,N)$ elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

JPVT (input/output)

On entry, if $JPVT(J) \neq 0$, the J-th column of A is permuted to the front of A*P (a leading column); if $JPVT(J)=0$, the J-th column of A is a free column. On exit, if $JPVT(J)=K$, then the J-th column of A*P was the K-th column of A.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

On exit, if $INFO=0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq N+1$. For optimal performance $LWORK \geq (N+1)*NB$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message

related to LWORK is issued by XERBLA.

RWORK (workspace)
dimension(2*N)

INFO (output)
= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m,n).$$

Each $H(i)$ has the form

$$H(i) = I - \tau * v * v'$$

where τ is a real/complex scalar, and v is a real/complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$, and τ in $TAU(i)$.

Based on contributions by

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X. Sun, Computer Science Dept., Duke University, USA

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NAME

zgeqpf - routine is deprecated and has been replaced by routine ZGEQP3

SYNOPSIS

```
SUBROUTINE ZGEQPF(M, N, A, LDA, JPIVOT, TAU, WORK, WORK2, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)
INTEGER M, N, LDA, INFO
INTEGER JPIVOT(*)
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZGEQPF_64(M, N, A, LDA, JPIVOT, TAU, WORK, WORK2, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)
INTEGER*8 M, N, LDA, INFO
INTEGER*8 JPIVOT(*)
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GEQPF([M], [N], A, [LDA], JPIVOT, TAU, [WORK], [WORK2],
  [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER :: M, N, LDA, INFO
INTEGER, DIMENSION(:) :: JPIVOT
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE GEQPF_64([M], [N], A, [LDA], JPIVOT, TAU, [WORK], [WORK2],
  [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: M, N, LDA, INFO
INTEGER(8), DIMENSION(:) :: JPIVOT
REAL(8), DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>

void zgeqpf(int m, int n, doublecomplex *a, int lda, int
           *jpivot, doublecomplex *tau, int *info);

void zgeqpf_64(long m, long n, doublecomplex *a, long lda,
              long *jpivot, doublecomplex *tau, long *info);
```

PURPOSE

zgeqpf routine is deprecated and has been replaced by routine ZGEQP3.

ZGEQPF computes a QR factorization with column pivoting of a complex M-by-N matrix A: $A*P = Q*R$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$

A (input/output)

On entry, the M-by-N matrix A. On exit, the upper triangle of the array contains the $\min(M,N)$ -by-N upper triangular matrix R; the elements below the diagonal, together with the array TAU, represent the unitary matrix Q as a product of $\min(m,n)$ elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

JPIVOT (input/output)

On entry, if $JPIVOT(i) \neq 0$, the i-th column of A is permuted to the front of $A*P$ (a leading column); if $JPIVOT(i) = 0$, the i-th column of A is a free column. On exit, if $JPIVOT(i) = k$, then the i-th column of $A*P$ was the k-th column of A.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

dimension(N)

WORK2 (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n)$$

Each $H(i)$ has the form

$$H = I - \tau * v * v'$$

where τ is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$.

The matrix P is represented in $jpvt$ as follows: If $jpvt(j) = i$ then the j th column of P is the i th canonical unit vector.

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NAME

zgeqrf - compute a QR factorization of a complex M-by-N matrix A

SYNOPSIS

```
SUBROUTINE ZGEQRF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE ZGEQRF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GEQRF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE GEQRF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgeqrf(int m, int n, doublecomplex *a, int lda, doublecomplex *tau, int *info);
```

```
void zgeqrf_64(long m, long n, doublecomplex *a, long lda, doublecomplex *tau, long *info);
```

PURPOSE

zgeqrf computes a QR factorization of a complex M-by-N matrix A: $A = Q * R$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, the elements on and above the diagonal of the array contain the min(M,N)-by-N upper trapezoidal matrix R (R is upper triangular if $m \geq n$); the elements below the diagonal, with the array TAU, represent the unitary matrix Q as a product of min(m,n) elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1, N)$. For optimum performance $LDWORK \geq N * NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m, n).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:m)$ is stored on exit in $A(i+1:m,i)$, and tau in $TAU(i)$.

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NAME

zgerc - perform the rank 1 operation $A := \alpha x \text{conjg}(y') + A$

SYNOPSIS

```
SUBROUTINE ZGERC(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER M, N, INCX, INCY, LDA
```

```
SUBROUTINE ZGERC_64(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER*8 M, N, INCX, INCY, LDA
```

F95 INTERFACE

```
SUBROUTINE GER([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, INCX, INCY, LDA
```

```
SUBROUTINE GER_64([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, INCX, INCY, LDA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgerc(int m, int n, doublecomplex *alpha, doublecomplex  
          *x, int incx, doublecomplex *y, int incy, doublecomplex *a, int lda);
```

```
void zgerc_64(long m, long n, doublecomplex *alpha, doublecomplex *a, int lda);
```

```
lecomplex *x, long incx, doublecomplex *y, long
incy, doublecomplex *a, long lda);
```

PURPOSE

zgerc performs the rank 1 operation $A := \alpha x \text{conjg}(y') + A$ where α is a scalar, x is an m element vector, y is an n element vector and A is an m by n matrix.

ARGUMENTS

- M (input)
On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.
- N (input)
On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.
- ALPHA (input)
On entry, ALPHA specifies the scalar α . Unchanged on exit.
- X (input)
($1 + (m - 1) * \text{abs}(\text{INCX})$). Before entry, the incremented array X must contain the m element vector x . Unchanged on exit.
- INCX (input)
On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.
- Y (input)
($1 + (n - 1) * \text{abs}(\text{INCY})$). Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.
- INCY (input)
On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.
- A (input/output)
Before entry, the leading m by n part of the array A must contain the matrix of coefficients. On exit, A is overwritten by the updated matrix.
- LDA (input)
On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, m)$. Unchanged on exit.

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NAME

zgerfs - improve the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZGERFS(TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,
  X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZGERFS_64(TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,
  LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GERFS([TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT,
  B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE GERFS_64([TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],
  IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: TRANSA
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
C INTERFACE
#include <sunperf.h>

void zgerfs(char transa, int n, int nrhs, doublecomplex *a,
            int lda, doublecomplex *af, int ldaf, int *ipivot,
            doublecomplex *b, int ldb, doublecomplex *x, int
            ldx, double *ferr, double *berr, int *info);

void zgerfs_64(char transa, long n, long nrhs, doublecomplex
               *a, long lda, doublecomplex *af, long ldaf, long
               *ipivot, doublecomplex *b, long ldb, doublecomplex
               *x, long ldx, double *ferr, double *berr, long
               *info);

```

PURPOSE

zgerfs improves the computed solution to a system of linear equations and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{*T} * X = B$ (Transpose)
 = 'C': $A^{*H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The original N-by-N matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)

The factors L and U from the factorization $A = P * L * U$ as computed by ZGETRF.

LDAF (input)

The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

IPIVOT (input)

The pivot indices from ZGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row $IPIVOT(i)$.

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (input/output)

On entry, the solution matrix X, as computed by ZGETRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. $LDX \geq \max(1, N)$.

FERR (output)

The estimated forward error bound for each solution vector $X(j)$ (the j -th column of the solution matrix X). If XTRUE is the true solution corresponding to $X(j)$, FERR(j) is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension($2 * N$)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

zgerqf - compute an RQ factorization of a complex M-by-N matrix A

SYNOPSIS

```
SUBROUTINE ZGERQF(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE ZGERQF_64(M, N, A, LDA, TAU, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GERQF([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, LDWORK, INFO
```

```
SUBROUTINE GERQF_64([M], [N], A, [LDA], TAU, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgerqf(int m, int n, doublecomplex *a, int lda, doublecomplex *tau, int *info);
```

```
void zgerqf_64(long m, long n, doublecomplex *a, long lda, doublecomplex *tau, long *info);
```

PURPOSE

zgerqf computes an RQ factorization of a complex M-by-N matrix A: $A = R * Q$.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $m \leq n$, the upper triangle of the subarray A(1:m,n-m+1:n) contains the M-by-M upper triangular matrix R; if $m > n$, the elements on and above the (m-n)-th subdiagonal contain the M-by-N upper trapezoidal matrix R; the remaining elements, with the array TAU, represent the unitary matrix Q as a product of $\min(m,n)$ elementary reflectors (see Further Details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

TAU (output)

The scalar factors of the elementary reflectors (see Further Details).

WORK (workspace)

On exit, if $INFO = 0$, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq \max(1,M)$. For optimum performance $LDWORK \geq M*NB$, where NB is the optimal blocksize.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$Q = H(1)' H(2)' \dots H(k)'$, where $k = \min(m,n)$.
Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where τ is a complex scalar, and v is a complex vector with $v(n-k+i+1:n) = 0$ and $v(n-k+i) = 1$; $\text{conjg}(v(1:n-k+i-1))$ is stored on exit in $A(m-k+i,1:n-k+i-1)$, and τ in $\text{TAU}(i)$.

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NAME

zgeru - perform the rank 1 operation $A := \alpha x x' + A$

SYNOPSIS

```
SUBROUTINE ZGERU(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER M, N, INCX, INCY, LDA
```

```
SUBROUTINE ZGERU_64(M, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER*8 M, N, INCX, INCY, LDA
```

F95 INTERFACE

```
SUBROUTINE GER([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, INCX, INCY, LDA
```

```
SUBROUTINE GER_64([M], [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, INCX, INCY, LDA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgeru(int m, int n, doublecomplex *alpha, doublecomplex  
          *x, int incx, doublecomplex *y, int incy, doublecomplex *a, int lda);
```

```
void zgeru_64(long m, long n, doublecomplex *alpha, doublecomplex *x, long incx, doublecomplex *y, long
```

```
incy, doublecomplex *a, long lda);
```

PURPOSE

zgeru performs the rank 1 operation $A := \alpha x y' + A$ where α is a scalar, x is an m element vector, y is an n element vector and A is an m by n matrix.

ARGUMENTS

M (input)

On entry, M specifies the number of rows of the matrix A. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (m - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the m element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

Y (input)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged on exit.

A (input/output)

Before entry, the leading m by n part of the array A must contain the matrix of coefficients. On exit, A is overwritten by the updated matrix.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, m)$. Unchanged on exit.

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NAME

zgesdd - compute the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors, by using divide-and-conquer method

SYNOPSIS

```
SUBROUTINE ZGESDD(JOBZ, M, N, A, LDA, S, U, LDU, VT, LDVT, WORK,  
LWORK, RWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOBZ  
DOUBLE COMPLEX A(LDA,*), U(LDU,*), VT(LDVT,*), WORK(*)  
INTEGER M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION S(*), RWORK(*)
```

```
SUBROUTINE ZGESDD_64(JOBZ, M, N, A, LDA, S, U, LDU, VT, LDVT, WORK,  
LWORK, RWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOBZ  
DOUBLE COMPLEX A(LDA,*), U(LDU,*), VT(LDVT,*), WORK(*)  
INTEGER*8 M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION S(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GESDD(JOBZ, [M], [N], A, [LDA], S, U, [LDU], VT, [LDVT],  
[WORK], [LWORK], [RWORK], [IWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, U, VT  
INTEGER :: M, N, LDA, LDU, LDVT, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: S, RWORK
```

```
SUBROUTINE GESDD_64(JOBZ, [M], [N], A, [LDA], S, U, [LDU], VT, [LDVT],  
[WORK], [LWORK], [RWORK], [IWORK], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, U, VT
INTEGER(8) :: M, N, LDA, LDU, LDVT, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: S, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zgesdd(char jobz, int m, int n, doublecomplex *a, int
            lda, double *s, doublecomplex *u, int ldu, doub-
            lecomplex *vt, int ldvt, int *info);

void zgesdd_64(char jobz, long m, long n, doublecomplex *a,
              long lda, double *s, doublecomplex *u, long ldu,
              doublecomplex *vt, long ldvt, long *info);

```

PURPOSE

zgesdd computes the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors, by using divide-and-conquer method. The SVD is written

$$= U * SIGMA * conjugate-transpose(V)$$

where SIGMA is an M-by-N matrix which is zero except for its min(m,n) diagonal elements, U is an M-by-M unitary matrix, and V is an N-by-N unitary matrix. The diagonal elements of SIGMA are the singular values of A; they are real and non-negative, and are returned in descending order. The first min(m,n) columns of U and V are the left and right singular vectors of A.

Note that the routine returns VT = V**H, not V.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)

Specifies options for computing all or part of the matrix U:

= 'A': all M columns of U and all N rows of V**H are returned in the arrays U and VT; = 'S': the first min(M,N) columns of U and the first min(M,N) rows of V**H are returned in the arrays U and VT; = 'O': If M >= N, the first N columns of U are overwritten on the array A and all rows of V**H are returned in the array VT; otherwise, all

columns of U are returned in the array U and the first M rows of V**H are overwritten on the array A; = 'N': no columns of U or rows of V**H are computed.

M (input) The number of rows of the input matrix A. $M \geq 0$.

N (input) The number of columns of the input matrix A. $N \geq 0$.

A (input/output)
On entry, the M-by-N matrix A. On exit, if JOBZ = 'O', A is overwritten with the first N columns of U (the left singular vectors, stored columnwise) if $M \geq N$; A is overwritten with the first M rows of V**H (the right singular vectors, stored rowwise) otherwise. if JOBZ .ne. 'O', the contents of A are destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.

S (output)
The singular values of A, sorted so that $S(i) \geq S(i+1)$.

U (output)
 $UCOL = M$ if JOBZ = 'A' or JOBZ = 'O' and $M < N$; $UCOL = \min(M, N)$ if JOBZ = 'S'. If JOBZ = 'A' or JOBZ = 'O' and $M < N$, U contains the M-by-M unitary matrix U; if JOBZ = 'S', U contains the first $\min(M, N)$ columns of U (the left singular vectors, stored columnwise); if JOBZ = 'O' and $M \geq N$, or JOBZ = 'N', U is not referenced.

LDU (input)
The leading dimension of the array U. $LDU \geq 1$; if JOBZ = 'S' or 'A' or JOBZ = 'O' and $M < N$, $LDU \geq M$.

VT (output)
If JOBZ = 'A' or JOBZ = 'O' and $M \geq N$, VT contains the N-by-N unitary matrix V**H; if JOBZ = 'S', VT contains the first $\min(M, N)$ rows of V**H (the right singular vectors, stored rowwise); if JOBZ = 'O' and $M < N$, or JOBZ = 'N', VT is not referenced.

LDVT (input)
The leading dimension of the array VT. $LDVT \geq 1$; if JOBZ = 'A' or JOBZ = 'O' and $M \geq N$, $LDVT \geq N$; if JOBZ = 'S', $LDVT \geq \min(M, N)$.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. $LWORK \geq 1$. If $LWORK = -1$, then a workspace query is assumed. In

this case, the routine only calculates the optimal size of the work array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued. The minimum workspace size requirement is as follows:

```

If M >= N and M >= (MIN(M,N)*17/9):
  if JOBZ = 'N', LWORK >= 3*N
  if JOBZ = 'O', LWORK >= 2*N*N + 3*N
  if JOBZ = 'S', LWORK >= N*N + 3*N
  if JOBZ = 'A', LWORK >= N*N + 2*N + M Else if M
>= N and M >= (MIN(M,N)*5/3):
  if JOBZ = 'O', LWORK >= 2*N + M + N*N
  else LWORK >= 2*N + M Else if M >=N:
  if JOBZ = 'O', LWORK >= 2*N + M + N*N
  else LWORK >= 2*N + M Else if M < N and N >=
(MIN(M,N)*17/9):
  if JOBZ = 'N', LWORK >= 3*M
  if JOBZ = 'O', LWORK >= 2*M*M + 3*M
  if JOBZ = 'S', LWORK >= M*M + 3*M
  if JOBZ = 'A', LWORK >= M*M + 2*M + N Else if M
< N and N >= (MIN(M,N)*5/3):
  if JOBZ = 'O', LWORK >= 2*M + N + M*M
  else LWORK >= 2*M + N Else if M < N:
  if JOBZ = 'O', LWORK >= 2*M + N + M*M
  else LWORK >= 2*M + N

```

RWORK (workspace)

```

If JOBZ = 'N', RWORK must be at least 7*min(M,N).
Otherwise, RWORK must be at least
5*min(M,N)*min(M,N) + 5*min(M,N)

```

IWORK (workspace)

```

dimension(8*MIN(M,N))

```

INFO (output)

```

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: The updating process of SBDSDC did not converge.

```

FURTHER DETAILS

Based on contributions by

Ming Gu and Huan Ren, Computer Science Division, University of California at Berkeley, USA

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NAME

zgesv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZGESV(N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZGESV_64(N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GESV([N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GESV_64([N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgesv(int n, int nrhs, doublecomplex *a, int lda, int  
          *ipivot, doublecomplex *b, int ldb, int *info);
```

```
void zgesv_64(long n, long nrhs, doublecomplex *a, long lda,  
             long *ipivot, doublecomplex *b, long ldb, long  
             *info);
```

PURPOSE

zgesv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N matrix and X and B are N-by-NRHS matrices.

The LU decomposition with partial pivoting and row interchanges is used to factor A as

$$A = P * L * U,$$

where P is a permutation matrix, L is unit lower triangular, and U is upper triangular. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the N-by-N coefficient matrix A. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

IPIVOT (output)

The pivot indices that define the permutation matrix P; row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)

On entry, the N-by-NRHS matrix of right hand side matrix B. On exit, if $INFO = 0$, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, $U(i,i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution could not be computed.

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NAME

zgesvd - compute the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors

SYNOPSIS

```
SUBROUTINE ZGESVD(JOBU, JOBVT, M, N, A, LDA, SING, U, LDU, VT, LDVT,  
                WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBU, JOBVT  
DOUBLE COMPLEX A(LDA,*), U(LDU,*), VT(LDVT,*), WORK(*)  
INTEGER M, N, LDA, LDU, LDVT, LDWORK, INFO  
DOUBLE PRECISION SING(*), WORK2(*)
```

```
SUBROUTINE ZGESVD_64(JOBU, JOBVT, M, N, A, LDA, SING, U, LDU, VT,  
                    LDVT, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBU, JOBVT  
DOUBLE COMPLEX A(LDA,*), U(LDU,*), VT(LDVT,*), WORK(*)  
INTEGER*8 M, N, LDA, LDU, LDVT, LDWORK, INFO  
DOUBLE PRECISION SING(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GESVD(JOBU, JOBVT, [M], [N], A, [LDA], SING, U, [LDU], VT,  
                [LDVT], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBVT  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, U, VT  
INTEGER :: M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL(8), DIMENSION(:) :: SING, WORK2
```

```
SUBROUTINE GESVD_64(JOBU, JOBVT, [M], [N], A, [LDA], SING, U, [LDU],  
                   VT, [LDVT], [WORK], [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBVT  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, U, VT  
INTEGER(8) :: M, N, LDA, LDU, LDVT, LDWORK, INFO  
REAL(8), DIMENSION(:) :: SING, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void zgesvd(char jobu, char jobvt, int m, int n, doublecomplex
 *a, int lda, double *sing, doublecomplex *u,
 int ldu, doublecomplex *vt, int ldvt, int *info);
void zgesvd_64(char jobu, char jobvt, long m, long n, doublecomplex
 *a, long lda, double *sing, doublecomplex
 *u, long ldu, doublecomplex *vt, long ldvt,
 long *info);
```

PURPOSE

zgesvd computes the singular value decomposition (SVD) of a complex M-by-N matrix A, optionally computing the left and/or right singular vectors. The SVD is written

$$= U * SIGMA * conjugate-transpose(V)$$

where SIGMA is an M-by-N matrix which is zero except for its min(m,n) diagonal elements, U is an M-by-M unitary matrix, and V is an N-by-N unitary matrix. The diagonal elements of SIGMA are the singular values of A; they are real and non-negative, and are returned in descending order. The first min(m,n) columns of U and V are the left and right singular vectors of A.

Note that the routine returns V**H, not V.

ARGUMENTS

JOBU (input)

Specifies options for computing all or part of the matrix U:

- = 'A': all M columns of U are returned in array U;
- = 'S': the first min(m,n) columns of U (the left singular vectors) are returned in the array U; =
- 'O': the first min(m,n) columns of U (the left singular vectors) are overwritten on the array A;
- = 'N': no columns of U (no left singular vectors) are computed.

JOBVT (input)

Specifies options for computing all or part of the matrix V**H:

- = 'A': all N rows of V**H are returned in the array VT;
- = 'S': the first min(m,n) rows of V**H (the right singular vectors) are returned in the array VT; =
- 'O': the first min(m,n) rows of V**H (the right singular vectors) are overwritten on the array A;
- = 'N': no rows of V**H (no right singular vectors) are computed.

JOBVT and JOBVT cannot both be 'O'.

M (input) The number of rows of the input matrix A. $M \geq 0$.

N (input) The number of columns of the input matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if JOBU = 'O', A is overwritten with the first $\min(m,n)$ columns of U (the left singular vectors, stored columnwise); if JOBVT = 'O', A is overwritten with the first $\min(m,n)$ rows of V^*H (the right singular vectors, stored rowwise); if JOBU .ne. 'O' and JOBVT .ne. 'O', the contents of A are destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

SING (output)

The singular values of A, sorted so that $SING(i) \geq SING(i+1)$.

U (input) (LDU,M) if JOBU = 'A' or (LDU, $\min(M,N)$) if JOBU = 'S'. If JOBU = 'A', U contains the M-by-M unitary matrix U; if JOBU = 'S', U contains the first $\min(m,n)$ columns of U (the left singular vectors, stored columnwise); if JOBU = 'N' or 'O', U is not referenced.

LDU (input)

The leading dimension of the array U. $LDU \geq 1$; if JOBU = 'S' or 'A', $LDU \geq M$.

VT (input)

If JOBVT = 'A', VT contains the N-by-N unitary matrix V^*H ; if JOBVT = 'S', VT contains the first $\min(m,n)$ rows of V^*H (the right singular vectors, stored rowwise); if JOBVT = 'N' or 'O', VT is not referenced.

LDVT (input)

The leading dimension of the array VT. $LDVT \geq 1$; if JOBVT = 'A', $LDVT \geq N$; if JOBVT = 'S', $LDVT \geq \min(M,N)$.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $LDWORK \geq 1$. $LDWORK \geq 2 * \min(M,N) + \max(M,N)$ For good performance, LDWORK should generally be larger.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)

DIMENSION(5* $\min(M,N)$). On exit, if INFO > 0,

WORK2(1:MIN(M,N)-1) contains the unconverged superdiagonal elements of an upper bidiagonal matrix B whose diagonal is in SING (not necessarily sorted). B satisfies $A = U * B * VT$, so it has the same singular values as A, and singular vectors related by U and VT.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if CBDSQR did not converge, INFO specifies how many superdiagonals of an intermediate bidiagonal form B did not converge to zero. See the description of WORK2 above for details.

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NAME

zgesvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZGESVX(FACT, TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
    EQUED, R, C, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
    WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION R(*), C(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZGESVX_64(FACT, TRANSA, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
    EQUED, R, C, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
    WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA, EQUED
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION R(*), C(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GESVX(FACT, [TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],
    IPIVOT, EQUED, R, C, B, [LDB], X, [LDX], RCOND, FERR,
    BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, AF, B, X
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
```

```

REAL(8), DIMENSION(:) :: R, C, FERR, BERR, WORK2

SUBROUTINE GESVX_64(FACT, [TRANSA], [N], [NRHS], A, [LDA], AF, [LDAF],
    IPIVOT, EQUED, R, C, B, [LDB], X, [LDX], RCOND, FERR,
    BERR, [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, TRANSA, EQUED
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: R, C, FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zgesvx(char fact, char transa, int n, int nrhs, doublecomplex *a, int lda, doublecomplex *af, int ldaf, int *ipivot, char equed, double *r, double *c, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *rcond, double *ferr, double *berr, int *info);

void zgesvx_64(char fact, char transa, long n, long nrhs, doublecomplex *a, long lda, doublecomplex *af, long ldaf, long *ipivot, char equed, double *r, double *c, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zgesvx uses the LU factorization to compute the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N matrix and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'E', real scaling factors are computed to equilibrate

the system:

TRANS = 'N': $\text{diag}(R) * A * \text{diag}(C) * \text{inv}(\text{diag}(C)) * X = \text{diag}(R) * B$

TRANS = 'T': $(\text{diag}(R) * A * \text{diag}(C)) ** T * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

TRANS = 'C': $(\text{diag}(R) * A * \text{diag}(C)) ** H * \text{inv}(\text{diag}(R)) * X = \text{diag}(C) * B$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A, but if equilibration is used, A is

overwritten by $\text{diag}(R) * A * \text{diag}(C)$ and B by $\text{diag}(R) * B$ (if TRANS='N')

or $\text{diag}(C)*B$ (if $\text{TRANS} = 'T'$ or $'C'$).

2. If $\text{FACT} = 'N'$ or $'E'$, the LU decomposition is used to factor the matrix A (after equilibration if $\text{FACT} = 'E'$) as

$$A = P * L * U,$$

where P is a permutation matrix, L is a unit lower triangular matrix, and U is upper triangular.

3. If some $U(i,i)=0$, so that U is exactly singular, then the routine returns with $\text{INFO} = i$. Otherwise, the factored form of A is used to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision, $\text{INFO} = N+1$ is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.

5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

6. If equilibration was used, the matrix X is premultiplied by $\text{diag}(C)$ (if $\text{TRANS} = 'N'$) or $\text{diag}(R)$ (if $\text{TRANS} = 'T'$ or $'C'$) so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF and IPIVOT contain the factored form of A. If EQUED is not 'N', the matrix A has been equilibrated with scaling factors given by R and C. A, AF, and IPIVOT are not modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

TRANS (input)

Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose)

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)
 On entry, the N-by-N matrix A. If FACT = 'F' and EQUED is not 'N', then A must have been equilibrated by the scaling factors in R and/or C. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if EQUED .ne. 'N', A is scaled as follows:
 EQUED = 'R': A := diag(R) * A
 EQUED = 'C': A := A * diag(C)
 EQUED = 'B': A := diag(R) * A * diag(C).

LDA (input)
 The leading dimension of the array A. LDA >= max(1,N).

AF (input or output)
 If FACT = 'F', then AF is an input argument and on entry contains the factors L and U from the factorization $A = P*L*U$ as computed by ZGETRF. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the factors L and U from the factorization $A = P*L*U$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the factors L and U from the factorization $A = P*L*U$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)
 The leading dimension of the array AF. LDAF >= max(1,N).

IPIVOT (input or output)
 If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the factorization $A = P*L*U$ as computed by ZGETRF; row i of the matrix was interchanged with row IPIVOT(i).

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = P*L*U$ of the original matrix A.

If FACT = 'E', then IPIVOT is an output argument and on exit contains the pivot indices from the factorization $A = P*L*U$ of the equilibrated matrix A.

EQUED (input or output)
 Specifies the form of equilibration that was done.
 = 'N': No equilibration (always true if FACT = 'N').

= 'R': Row equilibration, i.e., A has been premultiplied by $\text{diag}(R)$. = 'C': Column equilibration, i.e., A has been postmultiplied by $\text{diag}(C)$. = 'B': Both row and column equilibration, i.e., A has been replaced by $\text{diag}(R) * A * \text{diag}(C)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

R (input or output)

The row scale factors for A. If EQUED = 'R' or 'B', A is multiplied on the left by $\text{diag}(R)$; if EQUED = 'N' or 'C', R is not accessed. R is an input argument if FACT = 'F'; otherwise, R is an output argument. If FACT = 'F' and EQUED = 'R' or 'B', each element of R must be positive.

C (input or output)

The column scale factors for A. If EQUED = 'C' or 'B', A is multiplied on the right by $\text{diag}(C)$; if EQUED = 'N' or 'R', C is not accessed. C is an input argument if FACT = 'F'; otherwise, C is an output argument. If FACT = 'F' and EQUED = 'C' or 'B', each element of C must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if TRANSA = 'N' and EQUED = 'R' or 'B', B is overwritten by $\text{diag}(R)*B$; if TRANSA = 'T' or 'C' and EQUED = 'C' or 'B', B is overwritten by $\text{diag}(C)*B$.

LDB (input)

The leading dimension of the array B. LDB \geq $\max(1,N)$.

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that A and B are modified on exit if EQUED \neq 'N', and the solution to the equilibrated system is $\text{inv}(\text{diag}(C))*X$ if TRANSA = 'N' and EQUED = 'C' or 'B', or $\text{inv}(\text{diag}(R))*X$ if TRANSA = 'T' or 'C' and EQUED = 'R' or 'B'.

LDX (input)

The leading dimension of the array X. LDX \geq $\max(1,N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated

upper bound for the magnitude of the largest element in $(X(j) - X_{TRUE})$ divided by the magnitude of the largest element in $X(j)$. The estimate is as reliable as the estimate for $RCOND$, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector $X(j)$ (i.e., the smallest relative change in any element of A or B that makes $X(j)$ an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(2*N) On exit, $WORK2(1)$ contains the reciprocal pivot growth factor $\text{norm}(A)/\text{norm}(U)$. The "max absolute element" norm is used. If $WORK2(1)$ is much less than 1, then the stability of the LU factorization of the (equilibrated) matrix A could be poor. This also means that the solution X , condition estimator $RCOND$, and forward error bound $FERR$ could be unreliable. If factorization fails with $0 < INFO \leq N$, then $WORK2(1)$ contains the reciprocal pivot growth factor for the leading $INFO$ columns of A .

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, and i is
≤ N : $U(i,i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, so the solution and error bounds could not be computed. $RCOND = 0$ is returned. = $N+1$: U is nonsingular, but $RCOND$ is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of $RCOND$ would suggest.

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NAME

zgetf2 - compute an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE ZGETF2(M, N, A, LDA, IPIV, INFO)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER M, N, LDA, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE ZGETF2_64(M, N, A, LDA, IPIV, INFO)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 M, N, LDA, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE GETF2([M], [N], A, [LDA], IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE GETF2_64([M], [N], A, [LDA], IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgetf2(int m, int n, doublecomplex *a, int lda, int  
          *ipiv, int *info);
```

```
void zgetf2_64(long m, long n, doublecomplex *a, long lda,  
              long *ipiv, long *info);
```

PURPOSE

zgetf2 computes an LU factorization of a general m-by-n matrix A using partial pivoting with row interchanges.

The factorization has the form

$$A = P * L * U$$

where P is a permutation matrix, L is lower triangular with unit diagonal elements (lower trapezoidal if $m > n$), and U is upper triangular (upper trapezoidal if $m < n$).

This is the right-looking Level 2 BLAS version of the algorithm.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the m by n matrix to be factored. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,M)$.

IPIV (output)

The pivot indices; for $1 \leq i \leq \min(M,N)$, row i of the matrix was interchanged with row IPIV(i).

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value
> 0: if INFO = k, U(k,k) is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

zgetrf - compute an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges

SYNOPSIS

```
SUBROUTINE ZGETRF(M, N, A, LDA, IPIVOT, INFO)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER M, N, LDA, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZGETRF_64(M, N, A, LDA, IPIVOT, INFO)
```

```
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 M, N, LDA, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GETRF([M], [N], A, [LDA], IPIVOT, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GETRF_64([M], [N], A, [LDA], IPIVOT, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgetrf(int m, int n, doublecomplex *a, int lda, int  
           *ipivot, int *info);
```

```
void zgetrf_64(long m, long n, doublecomplex *a, long lda,  
              long *ipivot, long *info);
```

PURPOSE

zgetrf computes an LU factorization of a general M-by-N matrix A using partial pivoting with row interchanges.

The factorization has the form

$$A = P * L * U$$

where P is a permutation matrix, L is lower triangular with unit diagonal elements (lower trapezoidal if $m > n$), and U is upper triangular (upper trapezoidal if $m < n$).

This is the right-looking Level 3 BLAS version of the algorithm.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix to be factored. On exit, the factors L and U from the factorization $A = P*L*U$; the unit diagonal elements of L are not stored.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

IPIVOT (output)

The pivot indices; for $1 \leq i \leq \min(M, N)$, row i of the matrix was interchanged with row IPIVOT(i).

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, $U(i, i)$ is exactly zero. The factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

zgetri - compute the inverse of a matrix using the LU factorization computed by ZGETRF

SYNOPSIS

```
SUBROUTINE ZGETRI(N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), WORK(*)
INTEGER N, LDA, LDWORK, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZGETRI_64(N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), WORK(*)
INTEGER*8 N, LDA, LDWORK, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GETRI([N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER :: N, LDA, LDWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GETRI_64([N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: N, LDA, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgetri(int n, doublecomplex *a, int lda, int *ipivot,
            int *info);
```

```
void zgetri_64(long n, doublecomplex *a, long lda, long
               *ipivot, long *info);
```

PURPOSE

zgetri computes the inverse of a matrix using the LU factorization computed by ZGETRF.

This method inverts U and then computes $\text{inv}(A)$ by solving the system $\text{inv}(A)*L = \text{inv}(U)$ for $\text{inv}(A)$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the factors L and U from the factorization $A = P*L*U$ as computed by ZGETRF. On exit, if $\text{INFO} = 0$, the inverse of the original matrix A.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

The pivot indices from ZGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row $\text{IPIVOT}(i)$.

WORK (workspace)

On exit, if $\text{INFO} = 0$, then $\text{WORK}(1)$ returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. $\text{LDWORK} \geq \max(1, N)$. For optimal performance $\text{LDWORK} \geq N*NB$, where NB is the optimal blocksize returned by ILAENV.

If $\text{LDWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if $\text{INFO} = -i$, the i-th argument had an illegal value

> 0: if $\text{INFO} = i$, $U(i, i)$ is exactly zero; the matrix is singular and its inverse could not be computed.

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NAME

zgetrs - solve a system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$ with a general N-by-N matrix A using the LU factorization computed by ZGETRF

SYNOPSIS

```
SUBROUTINE ZGETRS(TRANSA, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZGETRS_64(TRANSA, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GETRS([TRANSA], [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GETRS_64([TRANSA], [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zgetrs(char transa, int n, int nrhs, doublecomplex *a,
            int lda, int *ipivot, doublecomplex *b, int ldb,
            int *info);

void zgetrs_64(char transa, long n, long nrhs, doublecomplex
               *a, long lda, long *ipivot, doublecomplex *b, long
               ldb, long *info);

```

PURPOSE

zgetrs solves a system of linear equations
 $A * X = B$, $A^{*T} * X = B$, or $A^{*H} * X = B$ with a general N-by-N matrix A using the LU factorization computed by ZGETRF.

ARGUMENTS

TRANSA (input)
 Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{*T} * X = B$ (Transpose)
 = 'C': $A^{*H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The factors L and U from the factorization $A = P * L * U$ as computed by ZGETRF.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)
 The pivot indices from ZGETRF; for $1 \leq i \leq N$, row i of the matrix was interchanged with row IPIVOT(i).

B (input/output)
 On entry, the right hand side matrix B. On exit, the solution matrix X.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zggbak - form the right or left eigenvectors of a complex generalized eigenvalue problem $A*x = \lambda*B*x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by ZGGBAL

SYNOPSIS

```
SUBROUTINE ZGGBAK(JOB, SIDE, N, ILO, IHI, LSCALE, RSCALE, M, V, LDV,
INFO)
```

```
CHARACTER * 1 JOB, SIDE
DOUBLE COMPLEX V(LDV,*)
INTEGER N, ILO, IHI, M, LDV, INFO
DOUBLE PRECISION LSCALE(*), RSCALE(*)
```

```
SUBROUTINE ZGGBAK_64(JOB, SIDE, N, ILO, IHI, LSCALE, RSCALE, M, V,
LDV, INFO)
```

```
CHARACTER * 1 JOB, SIDE
DOUBLE COMPLEX V(LDV,*)
INTEGER*8 N, ILO, IHI, M, LDV, INFO
DOUBLE PRECISION LSCALE(*), RSCALE(*)
```

F95 INTERFACE

```
SUBROUTINE GGBAK(JOB, SIDE, [N], ILO, IHI, LSCALE, RSCALE, [M], V,
[LDV], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE
COMPLEX(8), DIMENSION(:,:) :: V
INTEGER :: N, ILO, IHI, M, LDV, INFO
REAL(8), DIMENSION(:) :: LSCALE, RSCALE
```

```
SUBROUTINE GGBAK_64(JOB, SIDE, [N], ILO, IHI, LSCALE, RSCALE, [M], V,
[LDV], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, SIDE
COMPLEX(8), DIMENSION(:,:) :: V
INTEGER(8) :: N, ILO, IHI, M, LDV, INFO
```

REAL(8), DIMENSION(:) :: LSCALE, RSCALE

C INTERFACE

```
#include <sunperf.h>
```

```
void zggbak(char job, char side, int n, int ilo, int ihi,  
            double *lscale, double *rscale, int m, doublecom-  
            plex *v, int ldv, int *info);
```

```
void zggbak_64(char job, char side, long n, long ilo, long  
              ihi, double *lscale, double *rscale, long m, doub-  
              lecomplex *v, long ldv, long *info);
```

PURPOSE

zggbak forms the right or left eigenvectors of a complex generalized eigenvalue problem $A*x = \lambda*B*x$, by backward transformation on the computed eigenvectors of the balanced pair of matrices output by ZGGBAL.

ARGUMENTS

JOB (input)

Specifies the type of backward transformation required:

= 'N': do nothing, return immediately;

= 'P': do backward transformation for permutation only;

= 'S': do backward transformation for scaling only;

= 'B': do backward transformations for both permutation and scaling. JOB must be the same as the argument JOB supplied to ZGGBAL.

SIDE (input)

= 'R': V contains right eigenvectors;

= 'L': V contains left eigenvectors.

N (input) The number of rows of the matrix V. $N \geq 0$.

ILO (input)

The integers ILO and IHI determined by ZGGBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

IHI (input)

The integers ILO and IHI determined by ZGGBAL. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; $ILO=1$ and $IHI=0$, if $N=0$.

LSCALE (input)

Details of the permutations and/or scaling factors applied to the left side of A and B, as returned by ZGGBAL.

RSCALE (input)

Details of the permutations and/or scaling factors applied to the right side of A and B, as returned

by ZGGBAL.

M (input) The number of columns of the matrix V. $M \geq 0$.

V (input/output)

On entry, the matrix of right or left eigenvectors to be transformed, as returned by CTGEEV. On exit, V is overwritten by the transformed eigenvectors.

LDV (input)

The leading dimension of the matrix V. $LDV \geq \max(1, N)$.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

See R.C. Ward, Balancing the generalized eigenvalue problem, SIAM J. Sci. Stat. Comp. 2 (1981), 141-152.

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NAME

zggbal - balance a pair of general complex matrices (A,B)

SYNOPSIS

```
SUBROUTINE ZGGBAL(JOB, N, A, LDA, B, LDB, ILO, IHI, LSCALE, RSCALE,  
WORK, INFO)
```

```
CHARACTER * 1 JOB  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, LDA, LDB, ILO, IHI, INFO  
DOUBLE PRECISION LSCALE(*), RSCALE(*), WORK(*)
```

```
SUBROUTINE ZGGBAL_64(JOB, N, A, LDA, B, LDB, ILO, IHI, LSCALE,  
RSCALE, WORK, INFO)
```

```
CHARACTER * 1 JOB  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, LDA, LDB, ILO, IHI, INFO  
DOUBLE PRECISION LSCALE(*), RSCALE(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGBAL(JOB, [N], A, [LDA], B, [LDB], ILO, IHI, LSCALE,  
RSCALE, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, LDA, LDB, ILO, IHI, INFO  
REAL(8), DIMENSION(:) :: LSCALE, RSCALE, WORK
```

```
SUBROUTINE GGBAL_64(JOB, [N], A, [LDA], B, [LDB], ILO, IHI, LSCALE,  
RSCALE, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, LDA, LDB, ILO, IHI, INFO  
REAL(8), DIMENSION(:) :: LSCALE, RSCALE, WORK
```

C INTERFACE

```

#include <sunperf.h>

void zggbal(char job, int n, doublecomplex *a, int lda,
            doublecomplex *b, int ldb, int *ilo, int *ihi,
            double *lscale, double *rscale, int *info);

void zggbal_64(char job, long n, doublecomplex *a, long lda,
              doublecomplex *b, long ldb, long *ilo, long *ihi,
              double *lscale, double *rscale, long *info);

```

PURPOSE

zggbal balances a pair of general complex matrices (A,B). This involves, first, permuting A and B by similarity transformations to isolate eigenvalues in the first 1 to ILO\$-1 and last IHI+1 to N elements on the diagonal; and second, applying a diagonal similarity transformation to rows and columns ILO to IHI to make the rows and columns as close in norm as possible. Both steps are optional.

Balancing may reduce the 1-norm of the matrices, and improve the accuracy of the computed eigenvalues and/or eigenvectors in the generalized eigenvalue problem $A*x = \lambda*B*x$.

ARGUMENTS

JOB (input)

Specifies the operations to be performed on A and B:
 = 'N': none: simply set ILO = 1, IHI = N, LSCALE(I) = 1.0 and RSCALE(I) = 1.0 for i=1,...,N;
 = 'P': permute only;
 = 'S': scale only;
 = 'B': both permute and scale.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the input matrix A. On exit, A is overwritten by the balanced matrix. If JOB = 'N', A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input) On entry, the input matrix B. On exit, B is overwritten by the balanced matrix. If JOB = 'N', B is not referenced.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

ILO (output)

ILO and IHI are set to integers such that on exit

$A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1, \dots, ILO-1$ or $i = IHI+1, \dots, N$. If $JOB = 'N'$ or $'S'$, $ILO = 1$ and $IHI = N$.

IHI (output)

ILO and IHI are set to integers such that on exit $A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1, \dots, ILO-1$ or $i = IHI+1, \dots, N$.

LSCALE (input)

Details of the permutations and scaling factors applied to the left side of A and B. If $P(j)$ is the index of the row interchanged with row j , and $D(j)$ is the scaling factor applied to row j , then $LSCALE(j) = P(j)$ for $J = 1, \dots, ILO-1$ and $D(j)$ for $J = ILO, \dots, IHI$; $LSCALE(j) = P(j)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

RSCALE (input)

Details of the permutations and scaling factors applied to the right side of A and B. If $P(j)$ is the index of the column interchanged with column j , and $D(j)$ is the scaling factor applied to column j , then $RSCALE(j) = P(j)$ for $J = 1, \dots, ILO-1$ and $D(j)$ for $J = ILO, \dots, IHI$; $RSCALE(j) = P(j)$ for $J = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

WORK (workspace)

dimension(6*N)

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value.

FURTHER DETAILS

See R.C. WARD, Balancing the generalized eigenvalue problem, SIAM J. Sci. Stat. Comp. 2 (1981), 141-152.

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NAME

zggres - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the generalized complex Schur form (S, T), and optionally left and/or right Schur vectors (VSL and VSR)

SYNOPSIS

```
SUBROUTINE ZGGES(JOBVSL, JOBVSR, SORT, DELZTG, N, A, LDA, B, LDB,
                SDIM, ALPHA, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LWORK, RWORK,
                BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
INTEGER N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL DELZTG
LOGICAL BWORK(*)
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZGGES_64(JOBVSL, JOBVSR, SORT, DELZTG, N, A, LDA, B, LDB,
                   SDIM, ALPHA, BETA, VSL, LDVSL, VSR, LDVSR, WORK, LWORK, RWORK,
                   BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
INTEGER*8 N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL*8 DELZTG
LOGICAL*8 BWORK(*)
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGES(JOBVSL, JOBVSR, SORT, [DELZTG], [N], A, [LDA], B, [LDB],
                SDIM, ALPHA, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK], [LWORK],
                [RWORK], [BWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, VSL, VSR
INTEGER :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
```

```

LOGICAL :: DELZTG
LOGICAL, DIMENSION(:) :: BWORK
REAL(8), DIMENSION(:) :: RWORK

SUBROUTINE GGES_64(JOBVSL, JOBVSR, SORT, [DELZTG], [N], A, [LDA], B,
  [LDB], SDIM, ALPHA, BETA, VSL, [LDVSL], VSR, [LDVSR], [WORK],
  [LWORK], [RWORK], [BWORK], [INFO])

CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, VSL, VSR
INTEGER(8) :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
LOGICAL(8) :: DELZTG
LOGICAL(8), DIMENSION(:) :: BWORK
REAL(8), DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zgges(char jobvsl, char jobvsr, char sort,
  int(*delztg)(doublecomplex,doublecomplex), int n,
  doublecomplex *a, int lda, doublecomplex *b, int
  ldb, int *sdim, doublecomplex *alpha, doublecom-
  plex *beta, doublecomplex *vsl, int ldvsl, doub-
  lecomplex *vsr, int ldvsr, int *info);

void zgges_64(char jobvsl, char jobvsr, char sort,
  long(*delztg)(doublecomplex,doublecomplex), long
  n, doublecomplex *a, long lda, doublecomplex *b,
  long ldb, long *sdim, doublecomplex *alpha, doub-
  lecomplex *beta, doublecomplex *vsl, long ldvsl,
  doublecomplex *vsr, long ldvsr, long *info);

```

PURPOSE

zgges computes for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the generalized complex Schur form (S, T), and optionally left and/or right Schur vectors (VSL and VSR). This gives the generalized Schur factorization

$$(A,B) = ((VSL)*S*(VSR)**H, (VSL)*T*(VSR)**H)$$

where (VSR)**H is the conjugate-transpose of VSR.

Optionally, it also orders the eigenvalues so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper triangular matrix S and the upper triangular matrix T. The leading columns of VSL and VSR then form an unitary basis for the corresponding left and right eigenspaces (deflating subspaces).

(If only the generalized eigenvalues are needed, use the driver ZGGEV instead, which is faster.)

A generalized eigenvalue for a pair of matrices (A,B) is a scalar w or a ratio alpha/beta = w, such that A - w*B is singular. It is usually represented as the pair

(alpha,beta), as there is a reasonable interpretation for beta=0, and even for both being zero.

A pair of matrices (S,T) is in generalized complex Schur form if S and T are upper triangular and, in addition, the diagonal elements of T are non-negative real numbers.

ARGUMENTS

JOBVSL (input)

= 'N': do not compute the left Schur vectors;
= 'V': compute the left Schur vectors.

JOBVSR (input)

= 'N': do not compute the right Schur vectors;
= 'V': compute the right Schur vectors.

SORT (input)

Specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form. = 'N': Eigenvalues are not ordered;
= 'S': Eigenvalues are ordered (see DELZTG).

DELZTG (input)

LOGICAL FUNCTION of two DOUBLE COMPLEX arguments DELZTG must be declared EXTERNAL in the calling subroutine. If SORT = 'N', DELZTG is not referenced. If SORT = 'S', DELZTG is used to select eigenvalues to sort to the top left of the Schur form. An eigenvalue ALPHA(j)/BETA(j) is selected if DELZTG(ALPHA(j),BETA(j)) is true.

Note that a selected complex eigenvalue may no longer satisfy DELZTG(ALPHA(j),BETA(j)) = .TRUE. after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned), in this case INFO is set to N+2 (See INFO below).

N (input) The order of the matrices A, B, VSL, and VSR. N >= 0.

A (input/output)

DOUBLE COMPLEX array, dimension(LDA, N) On entry, the first of the pair of matrices. On exit, A has been overwritten by its generalized Schur form S.

LDA (input)

The leading dimension of A. LDA >= max(1,N).

B (input/output)

DOUBLE COMPLEX array, dimension(LDB,N) On entry, the second of the pair of matrices. On exit, B has been overwritten by its generalized Schur form T.

LDB (input)

The leading dimension of B. LDB >= max(1,N).

SDIM (output)

If SORT = 'N', SDIM = 0. If SORT = 'S', SDIM = number of eigenvalues (after sorting) for which DELZTG is true.

ALPHA (output)

On exit, ALPHA(j)/BETA(j), j=1,...,N, will be the generalized eigenvalues. ALPHA(j), j=1,...,N and BETA(j), j=1,...,N are the diagonals of the complex Schur form (A,B) output by ZGGES. The BETA(j) will be non-negative real.

Note: the quotients ALPHA(j)/BETA(j) may easily over- or underflow, and BETA(j) may even be zero. Thus, the user should avoid naively computing the ratio alpha/beta. However, ALPHA will be always less than and usually comparable with norm(A) in magnitude, and BETA always less than and usually comparable with norm(B).

BETA (output)

See description of ALPHA.

VSL (input)

DOUBLE COMPLEX array, dimension(LDVSL, N) If JOBVSL = 'V', VSL will contain the left Schur vectors. Not referenced if JOBVSL = 'N'.

LDVSL (input)

The leading dimension of the matrix VSL. LDVSL >= 1, and if JOBVSL = 'V', LDVSL >= N.

VSR (input)

DOUBLE COMPLEX array, dimension(LDVSR,N) If JOBVSR = 'V', VSR will contain the right Schur vectors. Not referenced if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR >= 1, and if JOBVSR = 'V', LDVSR >= N.

WORK (workspace)

DOUBLE COMPLEX array, dimension(LWORK) On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK >= max(1,2*N). For good performance, LWORK must generally be larger.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

DOUBLE PRECISION array, dimension(8*N)

BWORK (workspace)

LOGICAL array, dimension(N) Not referenced if SORT = 'N'.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
=1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHA(j) and BETA(j) should be correct for j=INFO+1,...,N. > N: =N+1: other than QZ iteration failed in CHGEQZ
=N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Generalized Schur form no longer satisfy DELZTG=.TRUE. This could also be caused due to scaling. =N+3: reordering failed in CTGSEN.

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NAME

zggsex - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the complex Schur form (S,T),

SYNOPSIS

```
SUBROUTINE ZGGESX(JOBVSL, JOBVSR, SORT, DELCTG, SENSE, N, A, LDA, B,
  LDB, SDIM, ALPHA, BETA, VSL, LDVSL, VSR, LDVSR, RCONDE, RCONDV,
  WORK, LWORK, RWORK, IWORK, LIWORK, BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT, SENSE
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
INTEGER N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL DELCTG
LOGICAL BWORK(*)
DOUBLE PRECISION RCONDE(*), RCONDV(*), RWORK(*)
```

```
SUBROUTINE ZGGESX_64(JOBVSL, JOBVSR, SORT, DELCTG, SENSE, N, A, LDA,
  B, LDB, SDIM, ALPHA, BETA, VSL, LDVSL, VSR, LDVSR, RCONDE,
  RCONDV, WORK, LWORK, RWORK, IWORK, LIWORK, BWORK, INFO)
```

```
CHARACTER * 1 JOBVSL, JOBVSR, SORT, SENSE
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VSL(LDVSL,*), VSR(LDVSR,*), WORK(*)
INTEGER*8 N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK,
INFO
INTEGER*8 IWORK(*)
LOGICAL*8 DELCTG
LOGICAL*8 BWORK(*)
DOUBLE PRECISION RCONDE(*), RCONDV(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGESX(JOBVSL, JOBVSR, SORT, [DELCTG], SENSE, [N], A, [LDA],
  B, [LDB], SDIM, ALPHA, BETA, VSL, [LDVSL], VSR, [LDVSR], RCONDE,
  RCONDV, [WORK], [LWORK], [RWORK], [IWORK], [LIWORK], [BWORK],
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT, SENSE
```

```

COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, VSL, VSR
INTEGER :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, LIWORK,
INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL :: DELCTG
LOGICAL, DIMENSION(:) :: BWORK
REAL(8), DIMENSION(:) :: RCONDE, RCONDV, RWORK
SUBROUTINE GGESX_64(JOBVSL, JOBVSR, SORT, [DELCTG], SENSE, [N], A, [LDA],
    B, [LDB], SDIM, ALPHA, BETA, VSL, [LDVSL], VSR, [LDVSR], RCONDE,
    RCONDV, [WORK], [LWORK], [RWORK], [IWORK], [LIWORK], [BWORK],
    [INFO])

```

```

CHARACTER(LEN=1) :: JOBVSL, JOBVSR, SORT, SENSE
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, VSL, VSR
INTEGER(8) :: N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK,
LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8) :: DELCTG
LOGICAL(8), DIMENSION(:) :: BWORK
REAL(8), DIMENSION(:) :: RCONDE, RCONDV, RWORK

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zgesx(char jobvsl, char jobvsr, char sort,
    int(*delctg)(doublecomplex,doublecomplex), char
    sense, int n, doublecomplex *a, int lda, doub-
    lecomplex *b, int ldb, int *sdim, doublecomplex
    *alpha, doublecomplex *beta, doublecomplex *vsl,
    int ldvsl, doublecomplex *vsr, int ldvsr, double
    *rconde, double *rcondv, int *info);

```

```

void zgesx_64(char jobvsl, char jobvsr, char sort,
    long(*delctg)(doublecomplex,doublecomplex), char
    sense, long n, doublecomplex *a, long lda, doub-
    lecomplex *b, long ldb, long *sdim, doublecomplex
    *alpha, doublecomplex *beta, doublecomplex *vsl,
    long ldvsl, doublecomplex *vsr, long ldvsr, double
    *rconde, double *rcondv, long *info);

```

PURPOSE

zgesx computes for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, the complex Schur form (S,T), and, optionally, the left and/or right matrices of Schur vectors (VSL and VSR). This gives the generalized Schur factorization $A,B) = ((VSL) S (VSR)**H, (VSL) T (VSR)**H)$

where (VSR)**H is the conjugate-transpose of VSR.

Optionally, it also orders the eigenvalues so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the upper triangular matrix S and the upper triangular matrix T; computes a reciprocal condition number for the average of the selected eigenvalues (RCONDE); and

computes a reciprocal condition number for the right and left deflating subspaces corresponding to the selected eigenvalues (RCONDV). The leading columns of VSL and VSR then form an orthonormal basis for the corresponding left and right eigenspaces (deflating subspaces).

A generalized eigenvalue for a pair of matrices (A,B) is a scalar w or a ratio $\alpha/\beta = w$, such that $A - w*B$ is singular. It is usually represented as the pair (α,β), as there is a reasonable interpretation for $\beta=0$ or for both being zero.

A pair of matrices (S,T) is in generalized complex Schur form if T is upper triangular with non-negative diagonal and S is upper triangular.

ARGUMENTS

JOBVSL (input)

= 'N': do not compute the left Schur vectors;
= 'V': compute the left Schur vectors.

JOBVSR (input)

= 'N': do not compute the right Schur vectors;
= 'V': compute the right Schur vectors.

SORT (input)

Specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form. = 'N': Eigenvalues are not ordered;
= 'S': Eigenvalues are ordered (see DELCTG).

DELCTG (input)

LOGICAL FUNCTION of two DOUBLE COMPLEX arguments DELCTG must be declared EXTERNAL in the calling subroutine. If SORT = 'N', DELCTG is not referenced. If SORT = 'S', DELCTG is used to select eigenvalues to sort to the top left of the Schur form. Note that a selected complex eigenvalue may no longer satisfy $DELCTG(ALPHA(j),BETA(j)) = .TRUE.$ after ordering, since ordering may change the value of complex eigenvalues (especially if the eigenvalue is ill-conditioned), in this case INFO is set to N+3 see INFO below).

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N' : None are computed;
= 'E' : Computed for average of selected eigenvalues only;
= 'V' : Computed for selected deflating subspaces only;
= 'B' : Computed for both. If SENSE = 'E', 'V', or 'B', SORT must equal 'S'.

N (input) The order of the matrices A, B, VSL, and VSR. $N \geq 0$.

A (input/output)

DOUBLE COMPLEX array, dimension(LDA,N) On entry, the first of the pair of matrices. On exit, A has been overwritten by its generalized Schur form S.

LDA (input)

The leading dimension of A. LDA \geq max(1,N).

B (input/output)

DOUBLE COMPLEX array, dimension(LDB,N) On entry, the second of the pair of matrices. On exit, B has been overwritten by its generalized Schur form T.

LDB (input)

The leading dimension of B. LDB \geq max(1,N).

SDIM (output)

If SORT = 'N', SDIM = 0. If SORT = 'S', SDIM = number of eigenvalues (after sorting) for which DELCTG is true.

ALPHA (output)

On exit, ALPHA(j)/BETA(j), j=1,...,N, will be the generalized eigenvalues. ALPHA(j) and BETA(j), j=1,...,N are the diagonals of the complex Schur form (S,T). BETA(j) will be non-negative real.

Note: the quotients ALPHA(j)/BETA(j) may easily over- or underflow, and BETA(j) may even be zero. Thus, the user should avoid naively computing the ratio alpha/beta. However, ALPHA will be always less than and usually comparable with norm(A) in magnitude, and BETA always less than and usually comparable with norm(B).

BETA (output)

See description of ALPHA.

VSL (input)

If JOBVSL = 'V', VSL will contain the left Schur vectors. Not referenced if JOBVSL = 'N'.

LDVSL (input)

The leading dimension of the matrix VSL. LDVSL \geq 1, and if JOBVSL = 'V', LDVSL \geq N.

VSR (input)

If JOBVSR = 'V', VSR will contain the right Schur vectors. Not referenced if JOBVSR = 'N'.

LDVSR (input)

The leading dimension of the matrix VSR. LDVSR \geq 1, and if JOBVSR = 'V', LDVSR \geq N.

RCONDE (output)

If SENSE = 'E' or 'B', RCONDE(1) and RCONDE(2) contain the reciprocal condition numbers for the average of the selected eigenvalues. Not referenced if SENSE = 'N' or 'V'.

RCONDV (output)
 If SENSE = 'V' or 'B', RCONDV(1) and RCONDV(2) contain the reciprocal condition number for the selected deflating subspaces. Not referenced if SENSE = 'N' or 'E'.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK $\geq 2*N$.
 If SENSE = 'E', 'V', or 'B', LWORK $\geq \text{MAX}(2*N, 2*SDIM*(N-SDIM))$.

RWORK (workspace)
 dimension(8*N) Real workspace.

IWORK (workspace/output)
 Not referenced if SENSE = 'N'. On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
 The dimension of the array WORK. LIWORK $\geq N+2$.

BWORK (workspace)
 dimension(N) Not referenced if SORT = 'N'.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value.
 = 1,...,N: The QZ iteration failed. (A,B) are not in Schur form, but ALPHA(j) and BETA(j) should be correct for j=INFO+1,...,N. > N: =N+1: other than QZ iteration failed in CHGEQZ
 =N+2: after reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the Generalized Schur form no longer satisfy DELCTG=.TRUE. This could also be caused due to scaling. =N+3: reordering failed in CTGSEN.

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NAME

zggev - compute for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors

SYNOPSIS

```
SUBROUTINE ZGGEV(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHA, BETA, VL,
                LDVL, VR, LDVR, WORK, LWORK, RWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER N, LDA, LDB, LDVL, LDVR, LWORK, INFO
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZGGEV_64(JOBVL, JOBVR, N, A, LDA, B, LDB, ALPHA, BETA, VL,
                  LDVL, VR, LDVR, WORK, LWORK, RWORK, INFO)
```

```
CHARACTER * 1 JOBVL, JOBVR
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER*8 N, LDA, LDB, LDVL, LDVR, LWORK, INFO
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGEV(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHA, BETA,
               VL, [LDVL], VR, [LDVR], [WORK], [LWORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, VL, VR
INTEGER :: N, LDA, LDB, LDVL, LDVR, LWORK, INFO
REAL(8), DIMENSION(:) :: RWORK
```

```
SUBROUTINE GGEV_64(JOBVL, JOBVR, [N], A, [LDA], B, [LDB], ALPHA,
                  BETA, VL, [LDVL], VR, [LDVR], [WORK], [LWORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBVL, JOBVR
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, VL, VR
```

```
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, LWORK, INFO
REAL(8), DIMENSION(:) :: RWORK
```

C INTERFACE

```
#include <sunperf.h>
void zggev(char jobvl, char jobvr, int n, doublecomplex *a,
           int lda, doublecomplex *b, int ldb, doublecomplex
           *alpha, doublecomplex *beta, doublecomplex *vl,
           int ldvl, doublecomplex *vr, int ldvr, int *info);

void zggev_64(char jobvl, char jobvr, long n, doublecomplex
              *a, long lda, doublecomplex *b, long ldb, doublecomplex
              *alpha, doublecomplex *beta, doublecomplex *vl, long ldvl,
              doublecomplex *vr, long ldvr, long *info);
```

PURPOSE

zggev computes for a pair of N-by-N complex nonsymmetric matrices (A,B), the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors.

A generalized eigenvalue for a pair of matrices (A,B) is a scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β) , as there is a reasonable interpretation for $\beta=0$, and even for both being zero.

The right generalized eigenvector $v(j)$ corresponding to the generalized eigenvalue $\lambda(j)$ of (A,B) satisfies

$$A * v(j) = \lambda(j) * B * v(j).$$

The left generalized eigenvector $u(j)$ corresponding to the generalized eigenvalues $\lambda(j)$ of (A,B) satisfies

$$u(j)**H * A = \lambda(j) * u(j)**H * B$$

where $u(j)**H$ is the conjugate-transpose of $u(j)$.

ARGUMENTS

JOBVL (input)
= 'N': do not compute the left generalized eigenvectors;
= 'V': compute the left generalized eigenvectors.

JOBVR (input)
= 'N': do not compute the right generalized eigenvectors;
= 'V': compute the right generalized eigenvectors.

N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)
 On entry, the matrix A in the pair (A,B). On exit, A has been overwritten.

LDA (input)
 The leading dimension of A. $LDA \geq \max(1,N)$.

B (input/output)
 On entry, the matrix B in the pair (A,B). On exit, B has been overwritten.

LDB (input)
 The leading dimension of B. $LDB \geq \max(1,N)$.

ALPHA (output)
 On exit, $ALPHA(j)/BETA(j)$, $j=1,\dots,N$, will be the generalized eigenvalues.

Note: the quotients $ALPHA(j)/BETA(j)$ may easily over- or underflow, and $BETA(j)$ may even be zero. Thus, the user should avoid naively computing the ratio α/β . However, ALPHA will be always less than and usually comparable with $norm(A)$ in magnitude, and BETA always less than and usually comparable with $norm(B)$.

BETA (output)
 See description of ALPHA.

VL (output)
 If $JOBVL = 'V'$, the left generalized eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. Each eigenvector will be scaled so the largest component will have $abs(real\ part) + abs(imag.\ part) = 1$. Not referenced if $JOBVL = 'N'$.

LDVL (input)
 The leading dimension of the matrix VL. $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (output)
 If $JOBVR = 'V'$, the right generalized eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. Each eigenvector will be scaled so the largest component will have $abs(real\ part) + abs(imag.\ part) = 1$. Not referenced if $JOBVR = 'N'$.

LDVR (input)
 The leading dimension of the matrix VR. $LDVR \geq 1$, and if $JOBVR = 'V'$, $LDVR \geq N$.

WORK (workspace)
 On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. $LWORK \geq \max(1,2*N)$. For good performance, LWORK must generally be larger.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
dimension(8*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
=1,...,N: The QZ iteration failed. No eigenvectors have been calculated, but ALPHA(j) and BETA(j) should be correct for j=INFO+1,...,N. >
N: =N+1: other than QZ iteration failed in SHGEQZ,
=N+2: error return from STGEVC.

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NAME

zggev_x - compute for a pair of N-by-N complex nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors

SYNOPSIS

```
SUBROUTINE ZGGEVX(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, B, LDB,
    ALPHA, BETA, VL, LDVL, VR, LDVR, ILO, IHI, LSCALE, RSCALE, ABNRM,
    BBNRM, RCONDE, RCONDV, WORK, LWORK, RWORK, IWORK, BWORK, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER IWORK(*)
LOGICAL BWORK(*)
DOUBLE PRECISION ABNRM, BBNRM
DOUBLE PRECISION LSCALE(*), RSCALE(*), RCONDE(*), RCONDV(*),
RWORK(*)
```

```
SUBROUTINE ZGGEVX_64(BALANC, JOBVL, JOBVR, SENSE, N, A, LDA, B, LDB,
    ALPHA, BETA, VL, LDVL, VR, LDVR, ILO, IHI, LSCALE, RSCALE, ABNRM,
    BBNRM, RCONDE, RCONDV, WORK, LWORK, RWORK, IWORK, BWORK, INFO)
```

```
CHARACTER * 1 BALANC, JOBVL, JOBVR, SENSE
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER*8 N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER*8 IWORK(*)
LOGICAL*8 BWORK(*)
DOUBLE PRECISION ABNRM, BBNRM
DOUBLE PRECISION LSCALE(*), RSCALE(*), RCONDE(*), RCONDV(*),
RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGEVX(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], B, [LDB],
    ALPHA, BETA, VL, [LDVL], VR, [LDVR], ILO, IHI, LSCALE, RSCALE,
    ABNRM, BBNRM, RCONDE, RCONDV, [WORK], [LWORK], [RWORK], [IWORK],
```

```

[BWORK], [INFO])

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, VL, VR
INTEGER :: N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL, DIMENSION(:) :: BWORK
REAL(8) :: ABNRM, BBNRM
REAL(8), DIMENSION(:) :: LSCALE, RSCALE, RCONDE, RCONDV,
RWORK
SUBROUTINE GGEVX_64(BALANC, JOBVL, JOBVR, SENSE, [N], A, [LDA], B,
[LDB], ALPHA, BETA, VL, [LDVL], VR, [LDVR], ILO, IHI, LSCALE,
RSCALE, ABNRM, BBNRM, RCONDE, RCONDV, [WORK], [LWORK], [RWORK],
[IWORK], [BWORK], [INFO])

```

```

CHARACTER(LEN=1) :: BALANC, JOBVL, JOBVR, SENSE
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, VL, VR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, ILO, IHI, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8), DIMENSION(:) :: BWORK
REAL(8) :: ABNRM, BBNRM
REAL(8), DIMENSION(:) :: LSCALE, RSCALE, RCONDE, RCONDV,
RWORK

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zggevxx(char balanc, char jobvl, char jobvr, char sense,
int n, doublecomplex *a, int lda, doublecomplex
*b, int ldb, doublecomplex *alpha, doublecomplex
*beta, doublecomplex *vl, int ldvl, doublecomplex
*vr, int ldvr, int *ilo, int *ihi, double *lscale,
double *rscale, double *abnrm, double *bbnrm, dou-
ble *rconde, double *rcondv, int *info);

```

```

void zggevxx_64(char balanc, char jobvl, char jobvr, char
sense, long n, doublecomplex *a, long lda, doub-
lecomplex *b, long ldb, doublecomplex *alpha,
doublecomplex *beta, doublecomplex *vl, long ldvl,
doublecomplex *vr, long ldvr, long *ilo, long
*ihi, double *lscale, double *rscale, double
*abnrm, double *bbnrm, double *rconde, double
*rcondv, long *info);

```

PURPOSE

zggevxx computes for a pair of N-by-N complex nonsymmetric matrices (A,B) the generalized eigenvalues, and optionally, the left and/or right generalized eigenvectors.

Optionally, it also computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors (ILO, IHI, LSCALE, RSCALE, ABNRM, and BBNRM), reciprocal condition numbers for the eigenvalues (RCONDE), and reciprocal condition numbers for the right eigenvectors (RCONDV).

A generalized eigenvalue for a pair of matrices (A,B) is a

scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β) , as there is a reasonable interpretation for $\beta=0$, and even for both being zero.

The right eigenvector $v(j)$ corresponding to the eigenvalue $\lambda(j)$ of (A, B) satisfies

$$A * v(j) = \lambda(j) * B * v(j) .$$

The left eigenvector $u(j)$ corresponding to the eigenvalue $\lambda(j)$ of (A, B) satisfies

$$u(j)**H * A = \lambda(j) * u(j)**H * B .$$

where $u(j)**H$ is the conjugate-transpose of $u(j)$.

ARGUMENTS

BALANC (input)

Specifies the balance option to be performed:
= 'N': do not diagonally scale or permute;
= 'P': permute only;
= 'S': scale only;
= 'B': both permute and scale. Computed reciprocal condition numbers will be for the matrices after permuting and/or balancing. Permuting does not change condition numbers (in exact arithmetic), but balancing does.

JOBVL (input)

= 'N': do not compute the left generalized eigenvectors;
= 'V': compute the left generalized eigenvectors.

JOBVR (input)

= 'N': do not compute the right generalized eigenvectors;
= 'V': compute the right generalized eigenvectors.

SENSE (input)

Determines which reciprocal condition numbers are computed. = 'N': none are computed;
= 'E': computed for eigenvalues only;
= 'V': computed for eigenvectors only;
= 'B': computed for eigenvalues and eigenvectors.

N (input) The order of the matrices A, B, VL, and VR. $N \geq 0$.

A (input/output)

On entry, the matrix A in the pair (A, B) . On exit, A has been overwritten. If JOBVL='V' or JOBVR='V' or both, then A contains the first part of the complex Schur form of the "balanced" versions of the input A and B.

LDA (input)

The leading dimension of A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the matrix B in the pair (A, B) . On exit, B has been overwritten. If JOBVL='V' or

JOBVR='V' or both, then B contains the second part of the complex Schur form of the "balanced" versions of the input A and B.

LDB (input)

The leading dimension of B. $LDB \geq \max(1,N)$.

ALPHA (output)

On exit, $ALPHA(j)/BETA(j)$, $j=1,\dots,N$, will be the generalized eigenvalues.

Note: the quotient $ALPHA(j)/BETA(j)$ may easily overflow or underflow, and $BETA(j)$ may even be zero. Thus, the user should avoid naively computing the ratio $ALPHA/BETA$. However, $ALPHA$ will be always less than and usually comparable with $norm(A)$ in magnitude, and $BETA$ always less than and usually comparable with $norm(B)$.

BETA (output)

See description of ALPHA.

VL (output)

If $JOBVL = 'V'$, the left generalized eigenvectors $u(j)$ are stored one after another in the columns of VL, in the same order as their eigenvalues. Each eigenvector will be scaled so the largest component will have $abs(\text{real part}) + abs(\text{imag. part}) = 1$. Not referenced if $JOBVL = 'N'$.

LDVL (input)

The leading dimension of the matrix VL. $LDVL \geq 1$, and if $JOBVL = 'V'$, $LDVL \geq N$.

VR (output)

If $JOBVR = 'V'$, the right generalized eigenvectors $v(j)$ are stored one after another in the columns of VR, in the same order as their eigenvalues. Each eigenvector will be scaled so the largest component will have $abs(\text{real part}) + abs(\text{imag. part}) = 1$. Not referenced if $JOBVR = 'N'$.

LDVR (input)

The leading dimension of the matrix VR. $LDVR \geq 1$, and if $JOBVR = 'V'$, $LDVR \geq N$.

ILO (output)

ILO is an integer value such that on exit $A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1,\dots,ILO-1$ or $i = IHI+1,\dots,N$. If $BALANC = 'N'$ or $'S'$, $ILO = 1$ and $IHI = N$.

IHI (output)

IHI is an integer value such that on exit $A(i,j) = 0$ and $B(i,j) = 0$ if $i > j$ and $j = 1,\dots,ILO-1$ or $i = IHI+1,\dots,N$. If $BALANC = 'N'$ or $'S'$, $ILO = 1$ and $IHI = N$.

LSCALE (output)

Details of the permutations and scaling factors applied to the left side of A and B. If $PL(j)$ is

the index of the row interchanged with row j , and $DL(j)$ is the scaling factor applied to row j , then $LSCALE(j) = PL(j)$ for $j = 1, \dots, ILO-1$ and $DL(j)$ for $j = ILO, \dots, IHI$; $PL(j) = PL(j)$ for $j = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

RSCALE (output)

Details of the permutations and scaling factors applied to the right side of A and B . If $PR(j)$ is the index of the column interchanged with column j , and $DR(j)$ is the scaling factor applied to column j , then $RSCALE(j) = PR(j)$ for $j = 1, \dots, ILO-1$ and $DR(j)$ for $j = ILO, \dots, IHI$; $PR(j) = PR(j)$ for $j = IHI+1, \dots, N$. The order in which the interchanges are made is N to $IHI+1$, then 1 to $ILO-1$.

ABNRM (output)

The one-norm of the balanced matrix A .

BBNRM (output)

The one-norm of the balanced matrix B .

RCONDE (output)

If $SENSE = 'E'$ or $'B'$, the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. If $SENSE = 'V'$, RCONDE is not referenced.

RCONDV (output)

If $JOB = 'V'$ or $'B'$, the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. If the eigenvalues cannot be reordered to compute RCONDV(j), RCONDV(j) is set to 0; this can only occur when the true value would be very small anyway. If $SENSE = 'E'$, RCONDV is not referenced. Not referenced if $JOB = 'E'$.

WORK (workspace)

On exit, if $INFO = 0$, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK $\geq \max(1, 2*N)$. If $SENSE = 'N'$ or $'E'$, LWORK $\geq 2*N$. If $SENSE = 'V'$ or $'B'$, LWORK $\geq 2*N*N+2*N$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

dimension(6*N) Real workspace.

IWORK (workspace)

dimension(N+2) If $SENSE = 'E'$, IWORK is not referenced.

BWORK (workspace)

dimension(N) If $SENSE = 'N'$, BWORK is not refer-

enced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
= 1,...,N: The QZ iteration failed. No eigenvectors have been calculated, but ALPHA(j) and BETA(j) should be correct for j=INFO+1,...,N. >
N: =N+1: other than QZ iteration failed in CHGEQZ.
=N+2: error return from CTGEVC.

FURTHER DETAILS

Balancing a matrix pair (A,B) includes, first, permuting rows and columns to isolate eigenvalues, second, applying diagonal similarity transformation to the rows and columns to make the rows and columns as close in norm as possible. The computed reciprocal condition numbers correspond to the balanced matrix. Permuting rows and columns will not change the condition numbers (in exact arithmetic) but diagonal scaling will. For further explanation of balancing, see section 4.11.1.2 of LAPACK Users' Guide.

An approximate error bound on the chordal distance between the i-th computed generalized eigenvalue w and the corresponding exact eigenvalue lambda is
$$\text{hord}(w, \lambda) \leq \text{EPS} * \text{norm}(\text{ABNRM}, \text{BBNRM}) / \text{RCONDE}(I)$$

An approximate error bound for the angle between the i-th computed eigenvector VL(i) or VR(i) is given by
$$\text{PS} * \text{norm}(\text{ABNRM}, \text{BBNRM}) / \text{DIF}(i).$$

For further explanation of the reciprocal condition numbers RCONDE and RCONDV, see section 4.11 of LAPACK User's Guide.

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NAME

zggglm - solve a general Gauss-Markov linear model (GLM) problem

SYNOPSIS

```
SUBROUTINE ZGGGLM(N, M, P, A, LDA, B, LDB, D, X, Y, WORK, LDWORK,  
INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), D(*), X(*), Y(*), WORK(*)  
INTEGER N, M, P, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE ZGGGLM_64(N, M, P, A, LDA, B, LDB, D, X, Y, WORK, LDWORK,  
INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), D(*), X(*), Y(*), WORK(*)  
INTEGER*8 N, M, P, LDA, LDB, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GGGLM([N], [M], [P], A, [LDA], B, [LDB], D, X, Y, [WORK],  
[LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: D, X, Y, WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER :: N, M, P, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE GGGLM_64([N], [M], [P], A, [LDA], B, [LDB], D, X, Y, [WORK],  
[LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: D, X, Y, WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER(8) :: N, M, P, LDA, LDB, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zggglm(int n, int m, int p, doublecomplex *a, int lda,  
doublecomplex *b, int ldb, doublecomplex *d, doublecomplex *x,  
doublecomplex *y, int *info);
```

```
void zggglm_64(long n, long m, long p, doublecomplex *a,
```

```

long lda, doublecomplex *b, long ldb, doublecom-
plex *d, doublecomplex *x, doublecomplex *y, long
*info);

```

PURPOSE

zggglm solves a general Gauss-Markov linear model (GLM) problem:

$$\underset{x}{\text{minimize}} \quad || y ||_2 \quad \text{subject to} \quad d = A*x + B*y$$

where A is an N-by-M matrix, B is an N-by-P matrix, and d is a given N-vector. It is assumed that $M \leq N \leq M+P$, and

$$\text{rank}(A) = M \quad \text{and} \quad \text{rank}(A \ B) = N.$$

Under these assumptions, the constrained equation is always consistent, and there is a unique solution x and a minimal 2-norm solution y, which is obtained using a generalized QR factorization of A and B.

In particular, if matrix B is square nonsingular, then the problem GLM is equivalent to the following weighted linear least squares problem

$$\underset{x}{\text{minimize}} \quad || \text{inv}(B)*(d-A*x) ||_2$$

where inv(B) denotes the inverse of B.

ARGUMENTS

N (input) The number of rows of the matrices A and B. $N \geq 0$.

M (input) The number of columns of the matrix A. $0 \leq M \leq N$.

P (input) The number of columns of the matrix B. $P \geq N-M$.

A (input/output)
On entry, the N-by-M matrix A. On exit, A is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)
On entry, the N-by-P matrix B. On exit, B is destroyed.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1,N)$.

D (input/output)
On entry, D is the left hand side of the GLM equation. On exit, D is destroyed.

X (output)
On exit, X and Y are the solutions of the GLM problem.

Y (output)
On exit, X and Y are the solutions of the GLM problem.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
The dimension of the array WORK. LDWORK \geq $\max(1, N+M+P)$. For optimum performance, LDWORK \geq $M+\min(N,P)+\max(N,P)*NB$, where NB is an upper bound for the optimal blocksizes for CGEQRF, CGERQF, CUNMQR and CUNMRQ.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)
= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

zgghrd - reduce a pair of complex matrices (A,B) to generalized upper Hessenberg form using unitary transformations, where A is a general matrix and B is upper triangular

SYNOPSIS

```
SUBROUTINE ZGGHRD(COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB, Q, LDQ,  
  Z, LDZ, INFO)
```

```
CHARACTER * 1 COMPQ, COMPZ  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)  
INTEGER N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO
```

```
SUBROUTINE ZGGHRD_64(COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB, Q,  
  LDQ, Z, LDZ, INFO)
```

```
CHARACTER * 1 COMPQ, COMPZ  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)  
INTEGER*8 N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO
```

F95 INTERFACE

```
SUBROUTINE GGHRD(COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB], Q,  
  [LDQ], Z, [LDZ], [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ, COMPZ  
COMPLEX(8), DIMENSION(:,*) :: A, B, Q, Z  
INTEGER :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO
```

```
SUBROUTINE GGHRD_64(COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB],  
  Q, [LDQ], Z, [LDZ], [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ, COMPZ  
COMPLEX(8), DIMENSION(:,*) :: A, B, Q, Z  
INTEGER(8) :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgghrd(char compq, char compz, int n, int ilo, int ihi,
            doublecomplex *a, int lda, doublecomplex *b, int
            ldb, doublecomplex *q, int ldq, doublecomplex *z,
            int ldz, int *info);
```

```
void zgghrd_64(char compq, char compz, long n, long ilo,
               long ihi, doublecomplex *a, long lda, doublecom-
               plex *b, long ldb, doublecomplex *q, long ldq,
               doublecomplex *z, long ldz, long *info);
```

PURPOSE

zgghrd reduces a pair of complex matrices (A,B) to generalized upper Hessenberg form using unitary transformations, where A is a general matrix and B is upper triangular: $Q' * A * Z = H$ and $Q' * B * Z = T$, where H is upper Hessenberg, T is upper triangular, and Q and Z are unitary, and ' ' means conjugate transpose.

The unitary matrices Q and Z are determined as products of Givens rotations. They may either be formed explicitly, or they may be postmultiplied into input matrices Q1 and Z1, so that

$$1 * A * Z1' = (Q1*Q) * H * (Z1*Z)'$$

ARGUMENTS

COMPQ (input)

= 'N': do not compute Q;
 = 'I': Q is initialized to the unit matrix, and the unitary matrix Q is returned;
 = 'V': Q must contain a unitary matrix Q1 on entry, and the product $Q1*Q$ is returned.

COMPZ (input)

= 'N': do not compute Q;
 = 'I': Q is initialized to the unit matrix, and the unitary matrix Q is returned;
 = 'V': Q must contain a unitary matrix Q1 on entry, and the product $Q1*Q$ is returned.

N (input) The order of the matrices A and B. $N \geq 0$.

ILO (input)

It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to ZGGBAL; otherwise they should be set to 1 and N respectively. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)

See description of ILO.

A (input/output)

On entry, the N-by-N general matrix to be reduced.

On exit, the upper triangle and the first subdiagonal of A are overwritten with the upper Hessenberg matrix H, and the rest is set to zero.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)

On entry, the N-by-N upper triangular matrix B. On exit, the upper triangular matrix $T = Q' B Z$. The elements below the diagonal are set to zero.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

Q (input/output)

If COMPQ='N': Q is not referenced.
If COMPQ='I': on entry, Q need not be set, and on exit it contains the unitary matrix Q, where Q' is the product of the Givens transformations which are applied to A and B on the left. If COMPQ='V': on entry, Q must contain a unitary matrix Q1, and on exit this is overwritten by Q1*Q.

LDQ (input)

The leading dimension of the array Q. LDQ \geq N if COMPQ='V' or 'I'; LDQ \geq 1 otherwise.

Z (input/output)

If COMPZ='N': Z is not referenced.
If COMPZ='I': on entry, Z need not be set, and on exit it contains the unitary matrix Z, which is the product of the Givens transformations which are applied to A and B on the right. If COMPZ='V': on entry, Z must contain a unitary matrix Z1, and on exit this is overwritten by Z1*Z.

LDZ (input)

The leading dimension of the array Z. LDZ \geq N if COMPZ='V' or 'I'; LDZ \geq 1 otherwise.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

This routine reduces A to Hessenberg and B to triangular form by an unblocked reduction, as described in Matrix Computations, by Golub and van Loan (Johns Hopkins Press).

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NAME

zgglse - solve the linear equality-constrained least squares (LSE) problem

SYNOPSIS

```
SUBROUTINE ZGGLSE(M, N, P, A, LDA, B, LDB, C, D, X, WORK, LDWORK,  
INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(*), D(*), X(*), WORK(*)  
INTEGER M, N, P, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE ZGGLSE_64(M, N, P, A, LDA, B, LDB, C, D, X, WORK, LDWORK,  
INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(*), D(*), X(*), WORK(*)  
INTEGER*8 M, N, P, LDA, LDB, LDWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GGLSE([M], [N], [P], A, [LDA], B, [LDB], C, D, X, [WORK],  
[LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: C, D, X, WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER :: M, N, P, LDA, LDB, LDWORK, INFO
```

```
SUBROUTINE GGLSE_64([M], [N], [P], A, [LDA], B, [LDB], C, D, X, [WORK],  
[LDWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: C, D, X, WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER(8) :: M, N, P, LDA, LDB, LDWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgglse(int m, int n, int p, doublecomplex *a, int lda,  
doublecomplex *b, int ldb, doublecomplex *c, doublecomplex *d, doublecomplex *x, int *info);
```

```
void zgglse_64(long m, long n, long p, doublecomplex *a,
```

```

long lda, doublecomplex *b, long ldb, doublecom-
plex *c, doublecomplex *d, doublecomplex *x, long
*info);

```

PURPOSE

zgglse solves the linear equality-constrained least squares (LSE) problem:

$$\text{minimize } || c - A*x ||_2 \quad \text{subject to } B*x = d$$

where A is an M-by-N matrix, B is a P-by-N matrix, c is a given M-vector, and d is a given P-vector. It is assumed that

$P \leq N \leq M+P$, and

$$\text{rank}(B) = P \text{ and } \text{rank} \begin{pmatrix} A \\ B \end{pmatrix} = N.$$

These conditions ensure that the LSE problem has a unique solution, which is obtained using a GRQ factorization of the matrices B and A.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

P (input) The number of rows of the matrix B. $0 \leq P \leq N \leq M+P$.

A (input/output)
On entry, the M-by-N matrix A. On exit, A is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
On entry, the P-by-N matrix B. On exit, B is destroyed.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, P)$.

C (input/output)
On entry, C contains the right hand side vector for the least squares part of the LSE problem. On exit, the residual sum of squares for the solution is given by the sum of squares of elements N-P+1 to M of vector C.

D (input/output)

On entry, D contains the right hand side vector for the constrained equation. On exit, D is destroyed.

X (output)

On exit, X is the solution of the LSE problem.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)

The dimension of the array WORK. LDWORK \geq $\max(1, M+N+P)$. For optimum performance LDWORK \geq $P + \min(M, N) + \max(M, N) * NB$, where NB is an upper bound for the optimal blocksizes for CGEQRF, CGERQF, CUNMQR and CUNMRQ.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

zggqrf - compute a generalized QR factorization of an N-by-M matrix A and an N-by-P matrix B.

SYNOPSIS

```
SUBROUTINE ZGGQRF(N, M, P, A, LDA, TAU, B, LDB, TAUB, WORK, LWORK,
                 INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
INTEGER N, M, P, LDA, LDB, LWORK, INFO
```

```
SUBROUTINE ZGGQRF_64(N, M, P, A, LDA, TAU, B, LDB, TAUB, WORK,
                    LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
INTEGER*8 N, M, P, LDA, LDB, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GGQRF([N], [M], [P], A, [LDA], TAU, B, [LDB], TAUB, [WORK],
                 [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, TAUB, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B
INTEGER :: N, M, P, LDA, LDB, LWORK, INFO
```

```
SUBROUTINE GGQRF_64([N], [M], [P], A, [LDA], TAU, B, [LDB], TAUB,
                    [WORK], [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, TAUB, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B
INTEGER(8) :: N, M, P, LDA, LDB, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zggqrf(int n, int m, int p, doublecomplex *a, int lda,
            doublecomplex *tau, doublecomplex *b, int ldb,
            doublecomplex *taub, int *info);
```


The leading dimension of the array A. LDA \geq max(1,N).

TAUA (output)

The scalar factors of the elementary reflectors which represent the unitary matrix Q (see Further Details).

B (input/output)

On entry, the N-by-P matrix B. On exit, if $N \leq P$, the upper triangle of the subarray B(1:N,P-N+1:P) contains the N-by-N upper triangular matrix T; if $N > P$, the elements on and above the (N-P)-th subdiagonal contain the N-by-P upper trapezoidal matrix T; the remaining elements, with the array TAUB, represent the unitary matrix Z as a product of elementary reflectors (see Further Details).

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

TAUB (output)

The scalar factors of the elementary reflectors which represent the unitary matrix Z (see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,N,M,P). For optimum performance LWORK \geq max(N,M,P)*max(NB1,NB2,NB3), where NB1 is the optimal blocksize for the QR factorization of an N-by-M matrix, NB2 is the optimal blocksize for the RQ factorization of an N-by-P matrix, and NB3 is the optimal blocksize for a call of CUNMQR.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(n,m).$$

Each H(i) has the form

$$H(i) = I - \text{taua} * v * v'$$

where taua is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:n)$ is stored on exit in $A(i+1:n,i)$, and taua in $\text{TAUA}(i)$.

To form Q explicitly, use LAPACK subroutine CUNGQR.

To use Q to update another matrix, use LAPACK subroutine CUNMQR.

The matrix Z is represented as a product of elementary reflectors

$$Z = H(1) H(2) \dots H(k), \text{ where } k = \min(n,p).$$

Each $H(i)$ has the form

$$H(i) = I - \text{taub} * v * v'$$

where taub is a complex scalar, and v is a complex vector with $v(p-k+i+1:p) = 0$ and $v(p-k+i) = 1$; $v(1:p-k+i-1)$ is stored on exit in $B(n-k+i,1:p-k+i-1)$, and taub in $\text{TAUB}(i)$.

To form Z explicitly, use LAPACK subroutine CUNGRQ.

To use Z to update another matrix, use LAPACK subroutine CUNMRQ.

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NAME

zggrqf - compute a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B

SYNOPSIS

```
SUBROUTINE ZGGRQF(M, P, N, A, LDA, TAU, B, LDB, TAUB, WORK, LWORK,
                 INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
INTEGER M, P, N, LDA, LDB, LWORK, INFO
```

```
SUBROUTINE ZGGRQF_64(M, P, N, A, LDA, TAU, B, LDB, TAUB, WORK,
                    LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), B(LDB,*), TAUB(*), WORK(*)
INTEGER*8 M, P, N, LDA, LDB, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE GGRQF([M], [P], [N], A, [LDA], TAU, B, [LDB], TAUB, [WORK],
                 [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, TAUB, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B
INTEGER :: M, P, N, LDA, LDB, LWORK, INFO
```

```
SUBROUTINE GGRQF_64([M], [P], [N], A, [LDA], TAU, B, [LDB], TAUB,
                    [WORK], [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, TAUB, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B
INTEGER(8) :: M, P, N, LDA, LDB, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zggrqf(int m, int p, int n, doublecomplex *a, int lda,
            doublecomplex *tau, doublecomplex *b, int ldb,
            doublecomplex *taub, int *info);
```

```
void zggrqf_64(long m, long p, long n, doublecomplex *a,
               long lda, doublecomplex *taua, doublecomplex *b,
               long ldb, doublecomplex *taub, long *info);
```

PURPOSE

zggrqf computes a generalized RQ factorization of an M-by-N matrix A and a P-by-N matrix B:

$$A = R*Q, \quad B = Z*T*Q,$$

where Q is an N-by-N unitary matrix, Z is a P-by-P unitary matrix, and R and T assume one of the forms:

$$\text{if } M \leq N, \quad R = \begin{pmatrix} 0 & R_{12} \\ & \end{pmatrix} \begin{matrix} M \\ M-N \end{matrix}, \quad \text{or if } M > N, \quad R = \begin{pmatrix} R_{11} \\ & \end{pmatrix} \begin{matrix} M \\ N \end{matrix}$$

where R12 or R21 is upper triangular, and

$$\text{if } P \geq N, \quad T = \begin{pmatrix} T_{11} \\ & \end{pmatrix} \begin{matrix} N \\ N \end{matrix}, \quad \text{or if } P < N, \quad T = \begin{pmatrix} T_{11} & T_{12} \\ & \end{pmatrix} \begin{matrix} P \\ N-P \end{matrix}$$

where T11 is upper triangular.

In particular, if B is square and nonsingular, the GRQ factorization of A and B implicitly gives the RQ factorization of $A*inv(B)$:

$$A*inv(B) = (R*inv(T))*Z'$$

where $inv(B)$ denotes the inverse of the matrix B, and Z' denotes the conjugate transpose of the matrix Z.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the M-by-N matrix A. On exit, if $M \leq N$, the upper triangle of the subarray $A(1:M, N-M+1:N)$ contains the M-by-M upper triangular matrix R; if $M > N$, the elements on and above the (M-N)-th subdiagonal contain the M-by-N upper trapezoidal matrix R; the remaining elements, with the array TAUA, represent the unitary matrix Q as a product of elementary reflectors (see Further Details).

LDA (input)
 The leading dimension of the array A. LDA \geq max(1,M).

TAUA (output)
 The scalar factors of the elementary reflectors which represent the unitary matrix Q (see Further Details).

B (input/output)
 On entry, the P-by-N matrix B. On exit, the elements on and above the diagonal of the array contain the min(P,N)-by-N upper trapezoidal matrix T (T is upper triangular if P \geq N); the elements below the diagonal, with the array TAUB, represent the unitary matrix Z as a product of elementary reflectors (see Further Details).

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,P).

TAUB (output)
 The scalar factors of the elementary reflectors which represent the unitary matrix Z (see Further Details).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq max(1,N,M,P). For optimum performance LWORK \geq max(N,M,P)*max(NB1,NB2,NB3), where NB1 is the optimal blocksize for the RQ factorization of an M-by-N matrix, NB2 is the optimal blocksize for the QR factorization of a P-by-N matrix, and NB3 is the optimal blocksize for a call of CUNMRQ.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO=-i, the i-th argument had an illegal value.

FURTHER DETAILS

The matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(k), \text{ where } k = \min(m,n).$$

Each H(i) has the form

$$H(i) = I - \text{tau} \cdot v \cdot v'$$

where taua is a complex scalar, and v is a complex vector with $v(n-k+i+1:n) = 0$ and $v(n-k+i) = 1$; $v(1:n-k+i-1)$ is stored on exit in $A(m-k+i,1:n-k+i-1)$, and taua in $TAUA(i)$. To form Q explicitly, use LAPACK subroutine CUNGRQ. To use Q to update another matrix, use LAPACK subroutine CUNMRQ.

The matrix Z is represented as a product of elementary reflectors

$$Z = H(1) H(2) \dots H(k), \text{ where } k = \min(p,n).$$

Each $H(i)$ has the form

$$H(i) = I - \text{taub} * v * v'$$

where taub is a complex scalar, and v is a complex vector with $v(1:i-1) = 0$ and $v(i) = 1$; $v(i+1:p)$ is stored on exit in $B(i+1:p,i)$, and taub in $TAUB(i)$. To form Z explicitly, use LAPACK subroutine CUNGQR. To use Z to update another matrix, use LAPACK subroutine CUNMQR.

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NAME

zggsvd - compute the generalized singular value decomposition (GSVD) of an M-by-N complex matrix A and P-by-N complex matrix B

SYNOPSIS

```
SUBROUTINE ZGGSVD(JOBU, JOBV, JOBQ, M, N, P, K, L, A, LDA, B, LDB,  
    ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, WORK2, IWORK3, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*),  
Q(LDQ,*), WORK(*)  
INTEGER M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER IWORK3(*)  
DOUBLE PRECISION ALPHA(*), BETA(*), WORK2(*)
```

```
SUBROUTINE ZGGSVD_64(JOBU, JOBV, JOBQ, M, N, P, K, L, A, LDA, B, LDB,  
    ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, WORK2, IWORK3, INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*),  
Q(LDQ,*), WORK(*)  
INTEGER*8 M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER*8 IWORK3(*)  
DOUBLE PRECISION ALPHA(*), BETA(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GGSVD(JOBU, JOBV, JOBQ, [M], [N], [P], K, L, A, [LDA], B,  
    [LDB], ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK], [WORK2],  
    IWORK3, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B, U, V, Q  
INTEGER :: M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER, DIMENSION(:) :: IWORK3  
REAL(8), DIMENSION(:) :: ALPHA, BETA, WORK2
```

```
SUBROUTINE GGSVD_64(JOBU, JOBV, JOBQ, [M], [N], [P], K, L, A, [LDA],  
    B, [LDB], ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ], [WORK],
```

```
[WORK2], IWORK3, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B, U, V, Q  
INTEGER(8) :: M, N, P, K, L, LDA, LDB, LDU, LDV, LDQ, INFO  
INTEGER(8), DIMENSION(:) :: IWORK3  
REAL(8), DIMENSION(:) :: ALPHA, BETA, WORK2
```

C INTERFACE

```
#include <sunperf.h>  
  
void zggsvd(char jobu, char jobv, char jobq, int m, int n,  
            int p, int *k, int *l, doublecomplex *a, int lda,  
            doublecomplex *b, int ldb, double *alpha, double  
            *beta, doublecomplex *u, int ldu, doublecomplex  
            *v, int ldv, doublecomplex *q, int ldq, int  
            *iwork3, int *info);  
  
void zggsvd_64(char jobu, char jobv, char jobq, long m, long  
               n, long p, long *k, long *l, doublecomplex *a,  
               long lda, doublecomplex *b, long ldb, double  
               *alpha, double *beta, doublecomplex *u, long ldu,  
               doublecomplex *v, long ldv, doublecomplex *q, long  
               ldq, long *iwork3, long *info);
```

PURPOSE

zggsvd computes the generalized singular value decomposition (GSVD) of an M-by-N complex matrix A and P-by-N complex matrix B:

$$U' * A * Q = D1 * \begin{pmatrix} 0 & R \end{pmatrix}, \quad V' * B * Q = D2 * \begin{pmatrix} 0 & R \end{pmatrix}$$

where U, V and Q are unitary matrices, and Z' means the conjugate transpose of Z. Let K+L = the effective numerical rank of the matrix (A', B')', then R is a (K+L)-by-(K+L) non-singular upper triangular matrix, D1 and D2 are M-by-(K+L) and P-by-(K+L) "diagonal" matrices and of the following structures, respectively:

If M-K-L >= 0,

$$D1 = \begin{matrix} & & & K & L \\ & & & K & (I & 0) \\ & & & L & (0 & C) \\ & & M-K-L & (0 & 0) \end{matrix}$$

$$D2 = \begin{matrix} & & & K & L \\ & & & L & (0 & S) \\ & & P-L & (0 & 0) \end{matrix}$$

$$\begin{pmatrix} 0 & R \end{pmatrix} = \begin{matrix} & & & N-K-L & K & L \\ & & & K & (0 & R11 & R12) \\ & & & L & (0 & 0 & R22) \end{matrix}$$

where

```
C = diag( ALPHA(K+1), ... , ALPHA(K+L) ),  
S = diag( BETA(K+1), ... , BETA(K+L) ),
```

$C^{**2} + S^{**2} = I.$
 R is stored in A(1:K+L,N-K-L+1:N) on exit.

If $M-K-L < 0,$

$$D1 = \begin{matrix} & & K & M-K & K+L-M \\ & K & (& I & 0 & 0 &) \\ M-K & (& 0 & C & 0 & &) \end{matrix}$$

$$D2 = \begin{matrix} & & K & M-K & K+L-M \\ M-K & (& 0 & S & 0 &) \\ K+L-M & (& 0 & 0 & I &) \\ P-L & (& 0 & 0 & 0 &) \end{matrix}$$

$$\begin{matrix} & & N-K-L & K & M-K & K+L-M \\ (& 0 & R &) = & K & (& 0 & R11 & R12 & R13 &) \\ & & M-K & (& 0 & 0 & R22 & R23 &) \\ & & K+L-M & (& 0 & 0 & 0 & R33 &) \end{matrix}$$

where

$C = \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(M)),$
 $S = \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(M)),$
 $C^{**2} + S^{**2} = I.$

(R11 R12 R13) is stored in A(1:M, N-K-L+1:N), and R33 is stored
 (0 R22 R23)
 in B(M-K+1:L,N+M-K-L+1:N) on exit.

The routine computes C, S, R, and optionally the unitary transformation matrices U, V and Q.

In particular, if B is an N-by-N nonsingular matrix, then the GSVD of A and B implicitly gives the SVD of $A \cdot \text{inv}(B)$:

$$A \cdot \text{inv}(B) = U \cdot (D1 \cdot \text{inv}(D2)) \cdot V'$$

If (A',B')' has orthonormal columns, then the GSVD of A and B is also equal to the CS decomposition of A and B. Furthermore, the GSVD can be used to derive the solution of the eigenvalue problem:

$$A' \cdot A \cdot x = \text{lambda} \cdot B' \cdot B \cdot x.$$

In some literature, the GSVD of A and B is presented in the form

$$U' \cdot A \cdot X = (0 D1), \quad V' \cdot B \cdot X = (0 D2)$$

where U and V are orthogonal and X is nonsingular, and D1 and D2 are ``diagonal''. The former GSVD form can be converted to the latter form by taking the nonsingular matrix X as

$$X = Q \cdot \begin{pmatrix} I & 0 \\ 0 & \text{inv}(R) \end{pmatrix}$$

ARGUMENTS

JOBV (input)
 = 'U': Unitary matrix U is computed;
 = 'N': U is not computed.

JOBV (input)

= 'V': Unitary matrix V is computed;
 = 'N': V is not computed.

JOBQ (input)
 = 'Q': Unitary matrix Q is computed;
 = 'N': Q is not computed.

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

K (output)
 On exit, K and L specify the dimension of the sub-blocks described in Purpose. $K + L =$ effective numerical rank of (A',B')'.

L (output)
 On exit, K and L specify the dimension of the sub-blocks described in Purpose. $K + L =$ effective numerical rank of (A',B')'.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A contains the triangular matrix R, or part of R. See Purpose for details.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
 On entry, the P-by-N matrix B. On exit, B contains part of the triangular matrix R if $M - K - L < 0$. See Purpose for details.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, P)$.

ALPHA (output)
 On exit, ALPHA and BETA contain the generalized singular value pairs of A and B; $ALPHA(1:K) = 1$, $ALPHA(K+1:K+L) = C$, $BETA(1:K) = 0$, and if $M - K - L \geq 0$, $ALPHA(K+1:K+L) = C$, $BETA(K+1:K+L) = S$, or if $M - K - L < 0$, $ALPHA(K+1:M) = C$, $ALPHA(M+1:K+L) = 0$, $BETA(K+1:M) = S$, $BETA(M+1:K+L) = 1$ and $ALPHA(K+L+1:N) = 0$, $BETA(K+L+1:N) = 0$.

BETA (output)
 See description of ALPHA.

U (output)
 If $JOB_U = 'U'$, U contains the M-by-M unitary matrix U. If $JOB_U = 'N'$, U is not referenced.

LDU (input)
 The leading dimension of the array U. LDU \geq max(1,M) if JOBU = 'U'; LDU \geq 1 otherwise.

V (output)
 If JOBV = 'V', V contains the P-by-P unitary matrix V. If JOBV = 'N', V is not referenced.

LDV (input)
 The leading dimension of the array V. LDV \geq max(1,P) if JOBV = 'V'; LDV \geq 1 otherwise.

Q (output)
 If JOBQ = 'Q', Q contains the N-by-N unitary matrix Q. If JOBQ = 'N', Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. LDQ \geq max(1,N) if JOBQ = 'Q'; LDQ \geq 1 otherwise.

WORK (workspace)
 dimension(MAX(3*N,M,P)+N)

WORK2 (workspace)
 dimension(2*N)

IWORK3 (output)
 dimension(N) On exit, IWORK3 stores the sorting information. More precisely, the following loop will sort ALPHA for I = K+1, min(M,K+L) swap ALPHA(I) and ALPHA(IWORK3(I)) endfor such that ALPHA(1) \geq ALPHA(2) \geq ... \geq ALPHA(N).

INFO (output)
 = 0: successful exit.
 < 0: if INFO = -i, the i-th argument had an illegal value.
 > 0: if INFO = 1, the Jacobi-type procedure failed to converge. For further details, see subroutine CTGSJA.

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NAME

zggsvp - compute unitary matrices U, V and Q such that $N-K-L$ $U^*A^*Q = K \begin{pmatrix} 0 & A12 & A13 \end{pmatrix}$ if $M-K-L \geq 0$

SYNOPSIS

```
SUBROUTINE ZGGSVP(JOBU, JOBV, JOBQ, M, P, N, A, LDA, B, LDB, TOLA,
  TOLB, K, L, U, LDU, V, LDV, Q, LDQ, IWORK, RWORK, TAU, WORK,
  INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
DOUBLE COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*),
Q(LDQ,*), TAU(*), WORK(*)
INTEGER M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER IWORK(*)
DOUBLE PRECISION TOLA, TOLB
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZGGSVP_64(JOBU, JOBV, JOBQ, M, P, N, A, LDA, B, LDB, TOLA,
  TOLB, K, L, U, LDU, V, LDV, Q, LDQ, IWORK, RWORK, TAU, WORK,
  INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
DOUBLE COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*),
Q(LDQ,*), TAU(*), WORK(*)
INTEGER*8 M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER*8 IWORK(*)
DOUBLE PRECISION TOLA, TOLB
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE GGSVP(JOBU, JOBV, JOBQ, [M], [P], [N], A, [LDA], B, [LDB],
  TOLA, TOLB, K, L, U, [LDU], V, [LDV], Q, [LDQ], [IWORK], [RWORK],
  [TAU], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, U, V, Q
INTEGER :: M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
```

```

INTEGER, DIMENSION(:) :: IWORK
REAL(8) :: TOLA, TOLB
REAL(8), DIMENSION(:) :: RWORK

SUBROUTINE GGSVP_64(JOBV, JOBV, JOBQ, [M], [P], [N], A, [LDA], B,
    [LDB], TOLA, TOLB, K, L, U, [LDU], V, [LDV], Q, [LDQ], [IWORK],
    [RWORK], [TAU], [WORK], [INFO])

CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, U, V, Q
INTEGER(8) :: M, P, N, LDA, LDB, K, L, LDU, LDV, LDQ, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8) :: TOLA, TOLB
REAL(8), DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zggsvp(char jobv, char jobv, char jobq, int m, int p,
    int n, doublecomplex *a, int lda, doublecomplex
    *b, int ldb, double tola, double tol, int *k, int
    *l, doublecomplex *u, int ldu, doublecomplex *v,
    int ldv, doublecomplex *q, int ldq, int *info);

void zggsvp_64(char jobv, char jobv, char jobq, long m, long
    p, long n, doublecomplex *a, long lda, doublecom-
    plex *b, long ldb, double tola, double tol, long
    *k, long *l, doublecomplex *u, long ldu, doub-
    lecomplex *v, long ldv, doublecomplex *q, long
    ldq, long *info);

```

PURPOSE

zggsvp computes unitary matrices U, V and Q such that

$$\begin{array}{c}
 \begin{array}{ccc}
 L & (& 0 & 0 & A23 &) \\
 M-K-L & (& 0 & 0 & 0 &)
 \end{array} \\
 \\
 \begin{array}{c}
 \begin{array}{ccc}
 N-K-L & K & L \\
 = & K & (& 0 & A12 & A13 &) & \text{if } M-K-L < 0; \\
 M-K & (& 0 & 0 & A23 &)
 \end{array} \\
 \\
 V' * B * Q = \begin{array}{ccc}
 N-K-L & K & L \\
 L & (& 0 & 0 & B13 &) \\
 P-L & (& 0 & 0 & 0 &)
 \end{array}
 \end{array}$$

where the K-by-K matrix A12 and L-by-L matrix B13 are non-singular upper triangular; A23 is L-by-L upper triangular if M-K-L >= 0, otherwise A23 is (M-K)-by-L upper trapezoidal. K+L = the effective numerical rank of the (M+P)-by-N matrix (A',B')'. Z' denotes the conjugate transpose of Z.

This decomposition is the preprocessing step for computing the Generalized Singular Value Decomposition (GSVD), see subroutine ZGGSVD.

ARGUMENTS

JOBU (input)
 = 'U': Unitary matrix U is computed;
 = 'N': U is not computed.

JOBV (input)
 = 'V': Unitary matrix V is computed;
 = 'N': V is not computed.

JOBQ (input)
 = 'Q': Unitary matrix Q is computed;
 = 'N': Q is not computed.

M (input) The number of rows of the matrix A. $M \geq 0$.

P (input) The number of rows of the matrix B. $P \geq 0$.

N (input) The number of columns of the matrices A and B. $N \geq 0$.

A (input/output)
 On entry, the M-by-N matrix A. On exit, A contains the triangular (or trapezoidal) matrix described in the Purpose section.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, M)$.

B (input/output)
 On entry, the P-by-N matrix B. On exit, B contains the triangular matrix described in the Purpose section.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, P)$.

TOLA (input)
 TOLA and TOLB are the thresholds to determine the effective numerical rank of matrix B and a sub-block of A. Generally, they are set to $TOLA = \max(M, N) * \text{norm}(A) * \text{MACHEPS}$, $TOLB = \max(P, N) * \text{norm}(B) * \text{MACHEPS}$. The size of TOLA and TOLB may affect the size of backward errors of the decomposition.

TOLB (input)
 See description of TOLA.

K (output)
 On exit, K and L specify the dimension of the sub-blocks described in Purpose section. $K + L = \text{effective numerical rank of } (A', B)'$.

L (output)
 See the description of K.

U (input) If JOBU = 'U', U contains the unitary matrix U. If JOBU = 'N', U is not referenced.

LDU (input)
 The leading dimension of the array U. LDU \geq
 max(1,M) if JOBU = 'U'; LDU \geq 1 otherwise.

V (input) If JOBV = 'V', V contains the unitary matrix V.
 If JOBV = 'N', V is not referenced.

LDV (input)
 The leading dimension of the array V. LDV \geq
 max(1,P) if JOBV = 'V'; LDV \geq 1 otherwise.

Q (input) If JOBQ = 'Q', Q contains the unitary matrix Q.
 If JOBQ = 'N', Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. LDQ \geq
 max(1,N) if JOBQ = 'Q'; LDQ \geq 1 otherwise.

IWORK (workspace)
 dimension(N)

RWORK (workspace)
 dimension(2*N)

TAU (workspace)
 dimension(N)

WORK (workspace)
 dimension(MAX(3*N,M,P))

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value.

FURTHER DETAILS

The subroutine uses LAPACK subroutine CGEQPF for the QR factorization with column pivoting to detect the effective numerical rank of the a matrix. It may be replaced by a better rank determination strategy.

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NAME

zgssco - General sparse solver condition number estimate.

SYNOPSIS

```
SUBROUTINE ZGSSCO ( COND, HANDLE, IER )
```

```
INTEGER          IER  
DOUBLE PRECISION COND  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSCO - Condition number estimate.

PARAMETERS

COND - DOUBLE PRECISION

On exit, an estimate of the condition number of the factored matrix. Must be called after the numerical factorization subroutine, [ZGSSFA\(\)](#).

HANDLE(150) - DOUBLE PRECISION array

On entry, [HANDLE\(*\)](#) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-700 : Invalid calling sequence - need to call ZGSSFA first.

-710 : Condition number estimate not available (not implemented for this HANDLE's matrix type).

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NAME

zgssda - Deallocate working storage for the general sparse solver.

SYNOPSIS

```
SUBROUTINE ZGSSDA ( HANDLE, IER )  
  
INTEGER          IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSDA - Deallocate dynamically allocated working storage.

PARAMETERS

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine.
Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

none

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NAME

zgssfa - General sparse solver numeric factorization.

SYNOPSIS

```
SUBROUTINE ZGSSFA ( NEQNS, COLSTR, ROWIND, VALUES, HANDLE, IER )
```

```
INTEGER          NEQNS, COLSTR(*), ROWIND(*), IER
DOUBLE COMPLEX   VALUES(*)
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSFA - Numeric factorization of a sparse matrix.

PARAMETERS

NEQNS - INTEGER
On entry, **NEQNS** specifies the number of equations in coefficient matrix. Unchanged on exit.

COLSTR(*) - INTEGER array
On entry, **COLSTR**(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure. Unchanged on exit.

ROWIND(*) - INTEGER array
On entry, **ROWIND**(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

VALUES(*) - DOUBLE COMPLEX array
On entry, **VALUES**(*) is an array of size COLSTR(NEQNS+1)-1, containing the numeric values of the sparse matrix to be factored. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, **HANDLE**(*) is an array containing

information needed by the solver, and must be passed unchanged to each sparse solver subroutine.
Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 300 : Invalid calling sequence - need to call ZGSSOR first.
- 301 : Failure to dynamically allocate memory.
- 666 : Internal error.

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NAME

zgssfs - General sparse solver one call interface.

SYNOPSIS

```
SUBROUTINE ZGSSFS ( MTXTYP, PIVOT , NEQNS, COLSTR, ROWIND,
                   VALUES, NRHS , RHS , LDRHS , ORDMTHD,
                   OUTUNT, MSGVLV, HANDLE, IER )
```

```
CHARACTER*2      MTXTYP
CHARACTER*1      PIVOT
INTEGER          NEQNS, COLSTR(*), ROWIND(*), NRHS, LDRHS,
                OUTUNT, MSGVLV, IER
CHARACTER*3      ORDMTHD
DOUBLE COMPLEX  VALUES(*), RHS(*)
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSFS - General sparse solver one call interface.

PARAMETERS

MTXTYP - CHARACTER*2
On entry, MTXTYP specifies the coefficient matrix type. Specifically, the valid options are:

- 'sp' or 'SP' - symmetric structure, Hermitian positive definite values
- 'ss' or 'SS' - symmetric structure, symmetric values
- 'su' or 'SU' - symmetric structure, unsymmetric values
- 'uu' or 'UU' - unsymmetric structure, unsymmetric values

Unchanged on exit.

PIVOT - CHARACTER*1
On entry, pivot specifies whether or not pivoting is used in the course of the numeric factorization. The valid options are:

'n' or 'N' - no pivoting is used
(Pivoting is not supported for this release).

Unchanged on exit.

NEQNS - INTEGER
On entry, NEQNS specifies the number of equations in the coefficient matrix. NEQNS must be at least one.
Unchanged on exit.

COLSTR(*) - INTEGER array
On entry, COLSTR(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure.
Unchanged on exit.

ROWIND(*) - INTEGER array
On entry, ROWIND(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

VALUES(*) - DOUBLE COMPLEX array
On entry, VALUES(*) is an array of size COLSTR(NEQNS+1)-1, containing the non-zero numeric values of the sparse matrix to be factored.
Unchanged on exit.

NRHS - INTEGER
On entry, NRHS specifies the number of right hand sides to solve for. Unchanged on exit.

RHS(*) - DOUBLE COMPLEX array
On entry, RHS(LDRHS,NRHS) contains the NRHS right hand sides. On exit, it contains the solutions.

LDRHS - INTEGER
On entry, LDRHS specifies the leading dimension of the RHS array. Unchanged on exit.

ORDMTHD - CHARACTER*3
On entry, ORDMTHD specifies the fill-reducing ordering to be used by the sparse solver. Specifically, the valid options are:

'nat' or 'NAT' - natural ordering (no ordering)
'mmd' or 'MMD' - multiple minimum degree
'gnd' or 'GND' - general nested dissection
'uso' or 'USO' - user specified ordering (see ZGSSUO)

Unchanged on exit.

OUTUNT - INTEGER
Output unit. Unchanged on exit.

MSGLVL - INTEGER
Message level.

0 - no output from solver.
(No messages supported for this release.)

Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array of containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 101 : Failure to dynamically allocate memory.
- 102 : Invalid matrix type.
- 103 : Invalid pivot option.
- 104 : Number of nonzeros is less than NEQNS.
- 105 : NEQNS < 1
- 106 : Invalid matrix structure.
- 201 : Failure to dynamically allocate memory.
- 301 : Failure to dynamically allocate memory.
- 401 : Failure to dynamically allocate memory.
- 402 : NRHS < 1
- 403 : NEQNS > LDRHS
- 666 : Internal error.

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NAME

zgssin - Initialize the general sparse solver.

SYNOPSIS

```
SUBROUTINE ZGSSIN ( MTXTYP, PIVOT, NEQNS, COLSTR, ROWIND, OUTUNT,  
                  MSGLVL, HANDLE, IER )
```

```
CHARACTER*2      MTXTYP  
CHARACTER*1      PIVOT  
INTEGER          NEQNS, COLSTR(*), ROWIND(*), OUTUNT, MSGLVL, IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSIN - Initialize the sparse solver and input the matrix structure.

PARAMETERS

MTXTYP - CHARACTER*2
On entry, MTXTYP specifies the coefficient matrix type. Specifically, the valid options are:

- 'sp' or 'SP' - symmetric structure, Hermitian positive definite values
- 'ss' or 'SS' - symmetric structure, symmetric values
- 'su' or 'SU' - symmetric structure, unsymmetric values
- 'uu' or 'UU' - unsymmetric structure, unsymmetric values

Unchanged on exit.

PIVOT - CHARACTER*1
On entry, PIVOT specifies whether or not pivoting is used in the course of the numeric factorization. The valid options are:

- 'n' or 'N' - no pivoting is used
(Pivoting is not supported for this release).

Unchanged on exit.

NEQNS - INTEGER
On entry, NEQNS specifies the number of equations in the coefficient matrix. NEQNS must be at least one. Unchanged on exit.

COLSTR(*) - INTEGER array
On entry, COLSTR(*) is an array of size (NEQNS+1), containing the pointers of the matrix structure. Unchanged on exit.

ROWIND(*) - INTEGER array
On entry, ROWIND(*) is an array of size COLSTR(NEQNS+1)-1, containing the indices of the matrix structure. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, HANDLE(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

OUTUNT - INTEGER
Output unit. Unchanged on exit.

MSGLVL - INTEGER
Message level.

0 - no output from solver.
(No messages supported for this release.)

Unchanged on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-101 : Failure to dynamically allocate memory.
-102 : Invalid matrix type.
-103 : Invalid pivot option.
-104 : Number of nonzeros less than NEQNS.
-105 : NEQNS < 1
-106 : Invalid matrix structure.

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NAME

zgssor - General sparse solver ordering and symbolic factorization.

SYNOPSIS

```
SUBROUTINE ZGSSOR ( ORDMTHD, HANDLE, IER )
```

```
CHARACTER*3      ORDMTHD
INTEGER          IER
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSOR - Orders and symbolically factors a sparse matrix.

PARAMETERS

ORDMTHD - CHARACTER*3

On entry, ORDMTHD specifies the fill-reducing ordering to be used by the sparse solver. Specifically, the valid options are:

'nat' or 'NAT' - natural ordering (no ordering)
'mmd' or 'MMD' - multiple minimum degree
'gnd' or 'GND' - general nested dissection
'uso' or 'USO' - user specified ordering (see ZGSSUO)

Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero

integer. Error numbers set by this subroutine:

- 200 : Invalid calling sequence - need to call ZGSSIN first.
- 201 : Failure to dynamically allocate memory.
- 666 : Internal error.

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NAME

zgssps - Print general sparse solver statics.

SYNOPSIS

```
SUBROUTINE ZGSSPS ( HANDLE, IER )  
  
INTEGER          IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSPS - Print solver statistics.

PARAMETERS

HANDLE(150) - DOUBLE PRECISION array
On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

- 800 : Invalid calling sequence - need to call ZGSSSL first.
- 899 : Printed solver statistics not supported this release.

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NAME

zgssrp - Return permutation used by the general sparse solver.

SYNOPSIS

```
SUBROUTINE ZGSSRP ( PERM, HANDLE, IER )
```

```
INTEGER          PERM(*), IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSRP - Returns the permutation used by the solver for the fill-reducing ordering.

PARAMETERS

PERM(NEQNS) - INTEGER array

Undefined on entry. PERM(NEQNS) is the permutation array used by the sparse solver for the fill-reducing ordering. Modified on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-600 : Invalid calling sequence - need to call ZGSSOR first.

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NAME

zgsssl - Solve routine for the general sparse solver.

SYNOPSIS

```
SUBROUTINE ZGSSSL ( NRHS, RHS, LDRHS, HANDLE, IER )
```

```
INTEGER          NRHS, LDRHS, IER
```

```
DOUBLE COMPLEX   RHS(LDRHS,NRHS)
```

```
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSSL - Triangular solve of a factored sparse matrix.

PARAMETERS

NRHS - INTEGER

On entry, NRHS specifies the number of right hand sides to solve for. Unchanged on exit.

RHS(LDRHS,*) - DOUBLE COMPLEX array

On entry, RHS(LDRHS,NRHS) contains the NRHS right hand sides. On exit, it contains the solutions.

LDRHS - INTEGER

On entry, LDRHS specifies the leading dimension of the RHS array. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array

On entry, *HANDLE*(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER

Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-400 : Invalid calling sequence - need to call ZGSSFA first.
-401 : Failure to dynamically allocate memory.
-402 : NRHS < 1
-403 : NEQNS > LDRHS

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NAME

zgssuo - User supplied permutation for ordering used in the general sparse solver.

SYNOPSIS

```
SUBROUTINE ZGSSUO ( PERM, HANDLE, IER )
```

```
INTEGER          PERM(*), IER  
DOUBLE PRECISION HANDLE(150)
```

PURPOSE

ZGSSUO - User supplied permutation for ordering. Must be called after **ZGSSIN**() (sparse solver initialization) and before **ZGSSOR**() (sparse solver ordering).

PARAMETERS

PERM(NEQNS) - INTEGER array
On entry, PERM(NEQNS) is a permutation array supplied by the user for the fill-reducing ordering. Unchanged on exit.

HANDLE(150) - DOUBLE PRECISION array
On entry, **HANDLE**(*) is an array containing information needed by the solver, and must be passed unchanged to each sparse solver subroutine. Modified on exit.

IER - INTEGER
Error number. If no error encountered, unchanged on exit. If error encountered, it is set to a non-zero integer. Error numbers set by this subroutine:

-500 : Invalid calling sequence - need to call ZGSSIN first.

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NAME

zgtcon - estimate the reciprocal of the condition number of a complex tridiagonal matrix A using the LU factorization as computed by ZGTTTF

SYNOPSIS

```
SUBROUTINE ZGTCON(NORM, N, LOW, DIAG, UP1, UP2, IPIVOT, ANORM, RCOND,
                 WORK, INFO)
```

```
CHARACTER * 1 NORM
DOUBLE COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*), WORK(*)
INTEGER N, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION ANORM, RCOND
```

```
SUBROUTINE ZGTCON_64(NORM, N, LOW, DIAG, UP1, UP2, IPIVOT, ANORM,
                    RCOND, WORK, INFO)
```

```
CHARACTER * 1 NORM
DOUBLE COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*), WORK(*)
INTEGER*8 N, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE GTCON(NORM, [N], LOW, DIAG, UP1, UP2, IPIVOT, ANORM,
                RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: NORM
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2, WORK
INTEGER :: N, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8) :: ANORM, RCOND
```

```
SUBROUTINE GTCON_64(NORM, [N], LOW, DIAG, UP1, UP2, IPIVOT, ANORM,
                   RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: NORM
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2, WORK
INTEGER(8) :: N, INFO
```

```
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>
void zgtcon(char norm, int n, doublecomplex *low, doublecom-
    plex *diag, doublecomplex *up1, doublecomplex
    *up2, int *ipivot, double anorm, double *rcond,
    int *info);

void zgtcon_64(char norm, long n, doublecomplex *low, doub-
    lecomplex *diag, doublecomplex *up1, doublecomplex
    *up2, long *ipivot, double anorm, double *rcond,
    long *info);
```

PURPOSE

zgtcon estimates the reciprocal of the condition number of a complex tridiagonal matrix A using the LU factorization as computed by ZGTTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

N (input) The order of the matrix A. $N \geq 0$.

LOW (input)

The (n-1) multipliers that define the matrix L from the LU factorization of A as computed by ZGTTRF.

DIAG (input)

The n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UP1 (input)

The (n-1) elements of the first superdiagonal of U.

UP2 (input)

The (n-2) elements of the second superdiagonal of U.

IPIVOT (input)

The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not

required.

ANORM (input)

If NORM = '1' or 'O', the 1-norm of the original matrix A. If NORM = 'I', the infinity-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(ANORM * AINVNM)$, where AINVNM is an estimate of the 1-norm of $inv(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zgthr - Gathers specified elements from y into x.

SYNOPSIS

```
SUBROUTINE ZGTHR(NZ, Y, X, INDX)

DOUBLE COMPLEX Y(*), X(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE ZGTHR_64(NZ, Y, X, INDX)

DOUBLE COMPLEX Y(*), X(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE GTHR([NZ], Y, X, INDX)

COMPLEX(8), DIMENSION(:) :: Y, X
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE GTHR_64([NZ], Y, X, INDX)

COMPLEX(8), DIMENSION(:) :: Y, X
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

ZGTHR - Gathers the specified elements from a vector y in full storage form into a vector x in compressed form. Only the elements of y whose indices are listed in indx are referenced.

```
do i = 1, n
  x(i) = y(indx(i))
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

Y (input)

Vector in full storage form. Unchanged on exit.

X (output)

Vector in compressed form. Contains elements of y
whose indices are listed in indx on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

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NAME

zgthrz - Gather and zero.

SYNOPSIS

```
SUBROUTINE ZGTHRZ(NZ, Y, X, INDX)

DOUBLE COMPLEX Y(*), X(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE ZGTHRZ_64(NZ, Y, X, INDX)

DOUBLE COMPLEX Y(*), X(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE GTHRZ([NZ], Y, X, INDX)

COMPLEX(8), DIMENSION(:) :: Y, X
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE GTHRZ_64([NZ], Y, X, INDX)

COMPLEX(8), DIMENSION(:) :: Y, X
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

ZGTHRZ - Gathers the specified elements from a vector y in full storage form into a vector x in compressed form. The gathered elements of y are set to zero. Only the elements of y whose indices are listed in indx are referenced.

```
do i = 1, n
  x(i) = y(indx(i))
  y(indx(i)) = 0
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

Y (input/output)

Vector in full storage form. Gathered elements are
set to zero.

X (output)

Vector in compressed form. Contains elements of y
whose indices are listed in indx on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

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NAME

zgtrfs - improve the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZGTRFS(TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF, UPF1,
  UPF2, IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*),
UPF1(*), UPF2(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZGTRFS_64(TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, LDB, X, LDX, FERR, BERR, WORK, WORK2,
  INFO)
```

```
CHARACTER * 1 TRANSA
DOUBLE COMPLEX LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*),
UPF1(*), UPF2(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GTRFS([TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF,
UPF1, UPF2, WORK
COMPLEX(8), DIMENSION(:,:) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```

SUBROUTINE GTRFS_64([TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
    DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], FERR, BERR, [WORK],
    [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: TRANSA
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF,
UPF1, UPF2, WORK
COMPLEX(8), DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zgtrfs(char transa, int n, int nrhs, doublecomplex
    *low, doublecomplex *diag, doublecomplex *up,
    doublecomplex *lowf, doublecomplex *diagf, doublecomplex
    *upf1, doublecomplex *upf2, int *ipivot,
    doublecomplex *b, int ldb, doublecomplex *x, int
    ldx, double *ferr, double *berr, int *info);

```

```

void zgtrfs_64(char transa, long n, long nrhs, doublecomplex
    *low, doublecomplex *diag, doublecomplex *up,
    doublecomplex *lowf, doublecomplex *diagf, doublecomplex
    *upf1, doublecomplex *upf2, long
    *ipivot, doublecomplex *b, long ldb, doublecomplex
    *x, long ldx, double *ferr, double *berr, long
    *info);

```

PURPOSE

zgtrfs improves the computed solution to a system of linear equations when the coefficient matrix is tridiagonal, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

TRANSA (input)

Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input)

The (n-1) subdiagonal elements of A.

DIAG (input)
The diagonal elements of A.

UP (input)
The (n-1) superdiagonal elements of A.

LOWF (input)
The (n-1) multipliers that define the matrix L from the LU factorization of A as computed by ZGTTRF.

DIAGF (input)
The n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UPF1 (input)
The (n-1) elements of the first superdiagonal of U.

UPF2 (input)
The (n-2) elements of the second superdiagonal of U.

IPIVOT (input)
The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (input/output)
On entry, the solution matrix X, as computed by ZGTTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. $LDX \geq \max(1, N)$.

FERR (output)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in $(X(j) - XTRUE)$ divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zgtsv - solve the equation $A \cdot X = B$,

SYNOPSIS

```
SUBROUTINE ZGTSV(N, NRHS, LOW, DIAG, UP, B, LDB, INFO)
```

```
DOUBLE COMPLEX LOW(*), DIAG(*), UP(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO
```

```
SUBROUTINE ZGTSV_64(N, NRHS, LOW, DIAG, UP, B, LDB, INFO)
```

```
DOUBLE COMPLEX LOW(*), DIAG(*), UP(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE GTSV([N], [NRHS], LOW, DIAG, UP, B, [LDB], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO
```

```
SUBROUTINE GTSV_64([N], [NRHS], LOW, DIAG, UP, B, [LDB], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgtsv(int n, int nrhs, doublecomplex *low, doublecom-  
plex *diag, doublecomplex *up, doublecomplex *b,  
int ldb, int *info);
```

```
void zgtsv_64(long n, long nrhs, doublecomplex *low, doub-  
lecomplex *diag, doublecomplex *up, doublecomplex  
*b, long ldb, long *info);
```

PURPOSE

zgtsv solves the equation

where A is an N-by-N tridiagonal matrix, by Gaussian elimination with partial pivoting.

Note that the equation $A'X = B$ may be solved by interchanging the order of the arguments DU and DL.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input/output)
On entry, LOW must contain the (n-1) subdiagonal elements of A. On exit, LOW is overwritten by the (n-2) elements of the second superdiagonal of the upper triangular matrix U from the LU factorization of A, in LOW(1), ..., LOW(n-2).

DIAG (input/output)
On entry, DIAG must contain the diagonal elements of A. On exit, DIAG is overwritten by the n diagonal elements of U.

UP (input/output)
On entry, UP must contain the (n-1) superdiagonal elements of A. On exit, UP is overwritten by the (n-1) elements of the first superdiagonal of U.

B (input/output)
On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, U(i,i) is exactly zero, and the solution has not been computed. The factorization has not been completed unless $i = N$.

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NAME

zgtsvx - use the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE ZGTSVX(FACT, TRANSA, N, NRHS, LOW, DIAG, UP, LOWF, DIAGF,
  UPF1, UPF2, IPIVOT, B, LDB, X, LDX, RCOND, FERR, BERR, WORK,
  WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA
DOUBLE COMPLEX LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*),
UPF1(*), UPF2(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZGTSVX_64(FACT, TRANSA, N, NRHS, LOW, DIAG, UP, LOWF,
  DIAGF, UPF1, UPF2, IPIVOT, B, LDB, X, LDX, RCOND, FERR, BERR,
  WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, TRANSA
DOUBLE COMPLEX LOW(*), DIAG(*), UP(*), LOWF(*), DIAGF(*),
UPF1(*), UPF2(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE GTSVX(FACT, [TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
  DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR,
  [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, TRANSA
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF,
UPF1, UPF2, WORK
COMPLEX(8), DIMENSION(:,:) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
```

```

INTEGER, DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

SUBROUTINE ZGTSVX_64(FACT, [TRANSA], [N], [NRHS], LOW, DIAG, UP, LOWF,
    DIAGF, UPF1, UPF2, IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR,
    [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, TRANSA
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP, LOWF, DIAGF,
UPF1, UPF2, WORK
COMPLEX(8), DIMENSION(:,:) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zgtsvx(char fact, char transa, int n, int nrhs, doublecomplex *low, doublecomplex *diag, doublecomplex *up, doublecomplex *lowf, doublecomplex *diagf, doublecomplex *upf1, doublecomplex *upf2, int *ipivot, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *rcond, double *ferr, double *berr, int *info);

void zgtsvx_64(char fact, char transa, long n, long nrhs, doublecomplex *low, doublecomplex *diag, doublecomplex *up, doublecomplex *lowf, doublecomplex *diagf, doublecomplex *upf1, doublecomplex *upf2, long *ipivot, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zgtsvx uses the LU factorization to compute the solution to a complex system of linear equations $A * X = B$, $A^{*T} * X = B$, or $A^{*H} * X = B$, where A is a tridiagonal matrix of order N and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the LU decomposition is used to factor the matrix A as $A = L * U$, where L is a product of permutation and unit lower bidiagonal matrices and U is upper triangular with nonzeros in only the main diagonal and first two superdiagonals.
2. If some $U(i,i)=0$, so that U is exactly singular, then the routine

returns with INFO = i. Otherwise, the factored form of A is used to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on

to solve for X and compute error bounds as described below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution

matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': LOWF, DIAGF, UPF1, UPF2, and IPIVOT contain the factored form of A; LOW, DIAG, UP, LOWF, DIAGF, UPF1, UPF2 and IPIVOT will not be modified. = 'N': The matrix will be copied to LOWF, DIAGF, and UPF1 and factored.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

LOW (input)

The (n-1) subdiagonal elements of A.

DIAG (input)

The n diagonal elements of A.

UP (input/output)

The (n-1) superdiagonal elements of A.

LOWF (input or output)

If FACT = 'F', then LOWF is an input argument and on entry contains the (n-1) multipliers that define the matrix L from the LU factorization of A as computed by ZGTTRF.

If FACT = 'N', then LOWF is an output argument and on exit contains the (n-1) multipliers that define the matrix L from the LU factorization of A.

DIAGF (input or output)

If FACT = 'F', then DIAGF is an input argument and on entry contains the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

If FACT = 'N', then DIAGF is an output argument and on exit contains the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UPF1 (input or output)

If FACT = 'F', then UPF1 is an input argument and on entry contains the (n-1) elements of the first superdiagonal of U.

If FACT = 'N', then UPF1 is an output argument and on exit contains the (n-1) elements of the first superdiagonal of U.

UPF2 (input or output)

If FACT = 'F', then UPF2 is an input argument and on entry contains the (n-2) elements of the second superdiagonal of U.

If FACT = 'N', then UPF2 is an output argument and on exit contains the (n-2) elements of the second superdiagonal of U.

IPIVOT (input/output)

If FACT = 'F', then IPIVOT is an input argument and on entry contains the pivot indices from the LU factorization of A as computed by ZGTRF.

If FACT = 'N', then IPIVOT is an output argument and on exit contains the pivot indices from the LU factorization of A; row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of

the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: U(i,i) is exactly zero. The factorization has not been completed unless i = N, but the factor U is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

zgttrf - compute an LU factorization of a complex tridiagonal matrix A using elimination with partial pivoting and row interchanges

SYNOPSIS

```
SUBROUTINE ZGTTRF(N, LOW, DIAG, UP1, UP2, IPIVOT, INFO)
```

```
DOUBLE COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*)
INTEGER N, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZGTTRF_64(N, LOW, DIAG, UP1, UP2, IPIVOT, INFO)
```

```
DOUBLE COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*)
INTEGER*8 N, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GTTRF([N], LOW, DIAG, UP1, UP2, IPIVOT, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2
INTEGER :: N, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GTTRF_64([N], LOW, DIAG, UP1, UP2, IPIVOT, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2
INTEGER(8) :: N, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zgttrf(int n, doublecomplex *low, doublecomplex *diag,
           doublecomplex *up1, doublecomplex *up2, int
           *ipivot, int *info);
```

```
void zgttrf_64(long n, doublecomplex *low, doublecomplex
              *diag, doublecomplex *up1, doublecomplex *up2,
```

```
long *ipivot, long *info);
```

PURPOSE

zgttrf computes an LU factorization of a complex tridiagonal matrix A using elimination with partial pivoting and row interchanges.

The factorization has the form

$$A = L * U$$

where L is a product of permutation and unit lower bidiagonal matrices and U is upper triangular with nonzeros in only the main diagonal and first two superdiagonals.

ARGUMENTS

N (input) The order of the matrix A.

LOW (input/output)

On entry, LOW must contain the (n-1) sub-diagonal elements of A.

On exit, LOW is overwritten by the (n-1) multipliers that define the matrix L from the LU factorization of A.

DIAG (input/output)

On entry, DIAG must contain the diagonal elements of A.

On exit, DIAG is overwritten by the n diagonal elements of the upper triangular matrix U from the LU factorization of A.

UP1 (input/output)

On entry, UP1 must contain the (n-1) super-diagonal elements of A.

On exit, UP1 is overwritten by the (n-1) elements of the first super-diagonal of U.

UP2 (output)

On exit, UP2 is overwritten by the (n-2) elements of the second super-diagonal of U.

IPIVOT (output)

The pivot indices; for $1 \leq i \leq n$, row i of the matrix was interchanged with row IPIVOT(i). IPIVOT(i) will always be either i or i+1; IPIVOT(i) = i indicates a row interchange was not required.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value
> 0: if INFO = k, U(k,k) is exactly zero. The

factorization has been completed, but the factor U is exactly singular, and division by zero will occur if it is used to solve a system of equations.

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NAME

zgttrs - solve one of the systems of equations $A * X = B$,
 $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE ZGTTRS(TRANSA, N, NRHS, LOW, DIAG, UP1, UP2, IPIVOT, B,  
LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
DOUBLE COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZGTTRS_64(TRANSA, N, NRHS, LOW, DIAG, UP1, UP2, IPIVOT, B,  
LDB, INFO)
```

```
CHARACTER * 1 TRANSA  
DOUBLE COMPLEX LOW(*), DIAG(*), UP1(*), UP2(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE GTTRS([TRANSA], [N], [NRHS], LOW, DIAG, UP1, UP2, IPIVOT,  
B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2  
COMPLEX(8), DIMENSION(:,) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE GTTRS_64([TRANSA], [N], [NRHS], LOW, DIAG, UP1, UP2,  
IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: TRANSA  
COMPLEX(8), DIMENSION(:) :: LOW, DIAG, UP1, UP2  
COMPLEX(8), DIMENSION(:,) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void zgtrtrs(char transa, int n, int nrhs, doublecomplex
             *low, doublecomplex *diag, doublecomplex *up1,
             doublecomplex *up2, int *ipivot, doublecomplex *b,
             int ldb, int *info);
void zgtrtrs_64(char transa, long n, long nrhs, doublecomplex
               *low, doublecomplex *diag, doublecomplex *up1,
               doublecomplex *up2, long *ipivot, doublecomplex
               *b, long ldb, long *info);
```

PURPOSE

zgtrtrs solves one of the systems of equations
 $A * X = B$, $A^{*T} * X = B$, or $A^{*H} * X = B$, with a tri-
diagonal matrix A using the LU factorization computed by
ZGTTRF.

ARGUMENTS

TRANSA (input)
Specifies the form of the system of equations. =
'N': $A * X = B$ (No transpose)
= 'T': $A^{*T} * X = B$ (Transpose)
= 'C': $A^{*H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input) The order of the matrix A.

NRHS (input)
The number of right hand sides, i.e., the number
of columns of the matrix B. NRHS \geq 0.

LOW (input)
The (n-1) multipliers that define the matrix L
from the LU factorization of A.

DIAG (input)
The n diagonal elements of the upper triangular
matrix U from the LU factorization of A.

UP1 (input)
The (n-1) elements of the first super-diagonal of
U.

UP2 (input)
The (n-2) elements of the second super-diagonal of
U.

IPIVOT (input)
The pivot indices; for $1 \leq i \leq n$, row i of the
matrix was interchanged with row IPIVOT(i).
IPIVOT(i) will always be either i or i+1;
IPIVOT(i) = i indicates a row interchange was not
required.

B (input/output)

On entry, the matrix of right hand side vectors B.
On exit, B is overwritten by the solution vectors X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value

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NAME

zhbev - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

SYNOPSIS

```
SUBROUTINE ZHBEV(JOBZ, UPLO, N, KD, A, LDA, W, Z, LDZ, WORK,  
                WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)  
INTEGER N, KD, LDA, LDZ, INFO  
DOUBLE PRECISION W(*), WORK2(*)
```

```
SUBROUTINE ZHBEV_64(JOBZ, UPLO, N, KD, A, LDA, W, Z, LDZ, WORK,  
                   WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, KD, LDA, LDZ, INFO  
DOUBLE PRECISION W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HBEV(JOBZ, UPLO, [N], KD, A, [LDA], W, Z, [LDZ], [WORK],  
               [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, Z  
INTEGER :: N, KD, LDA, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HBEV_64(JOBZ, UPLO, [N], KD, A, [LDA], W, Z, [LDZ],  
                  [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, Z  
INTEGER(8) :: N, KD, LDA, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void zhbev(char jobz, char uplo, int n, int kd, doublecomplex
           *a, int lda, double *w, doublecomplex *z, int
           ldz, int *info);
void zhbev_64(char jobz, char uplo, long n, long kd, doublecomplex
              *a, long lda, double *w, doublecomplex
              *z, long ldz, long *info);
```

PURPOSE

zhbev computes all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

A (input/output)
On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, A is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of the tridiagonal matrix T are returned in rows KD and $KD+1$ of A, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the first two rows of A.

LDA (input)
The leading dimension of the array A. $LDA \geq KD + 1$.

W (output)
If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the

orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

dimension(N)

WORK2 (workspace)

dimension(max(1,3*N-2))

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

zhbevd - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

SYNOPSIS

```
SUBROUTINE ZHBEVD(JOBZ, UPLO, N, KD, AB, LDAB, W, Z, LDZ, WORK,  
                 LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AB(LDAB,*), Z(LDZ,*), WORK(*)  
INTEGER N, KD, LDAB, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHBEVD_64(JOBZ, UPLO, N, KD, AB, LDAB, W, Z, LDZ, WORK,  
                   LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AB(LDAB,*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, KD, LDAB, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBEVD(JOBZ, UPLO, [N], KD, AB, [LDAB], W, Z, [LDZ], [WORK],  
                [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: AB, Z  
INTEGER :: N, KD, LDAB, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HBEVD_64(JOBZ, UPLO, [N], KD, AB, [LDAB], W, Z, [LDZ],  
                   [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: AB, Z
```

```
INTEGER(8) :: N, KD, LDAB, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: W, RWORK
```

C INTERFACE

```
#include <sunperf.h>
void zhbevd(char jobz, char uplo, int n, int kd, doublecom-
  plex *ab, int ldab, double *w, doublecomplex *z,
  int ldz, int *info);

void zhbevd_64(char jobz, char uplo, long n, long kd, doub-
  lecomplex *ab, long ldab, double *w, doublecomplex
  *z, long ldz, long *info);
```

PURPOSE

zhbevd computes all the eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$.

On exit, AB is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the first superdiagonal and the diagonal of

the tridiagonal matrix T are returned in rows KD and KD+1 of AB, and if UPLO = 'L', the diagonal and first subdiagonal of T are returned in the first two rows of AB.

LDAB (input)

The leading dimension of the array AB. LDAB \geq KD + 1.

W (output)

If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If N \leq 1, LWORK must be at least 1. If JOBZ = 'N' and N $>$ 1, LWORK must be at least N. If JOBZ = 'V' and N $>$ 1, LWORK must be at least $2*N**2$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

dimension (LRWORK) On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)

The dimension of array RWORK. If N \leq 1, LRWORK must be at least 1. If JOBZ = 'N' and N $>$ 1, LRWORK must be at least N. If JOBZ = 'V' and N $>$ 1, LRWORK must be at least $1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of array IWORK. If JOBZ = 'N' or N \leq 1, LIWORK must be at least 1. If JOBZ = 'V' and N $>$ 1, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

zhbevz - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian band matrix A

SYNOPSIS

```
SUBROUTINE ZHBEVX(JOBZ, RANGE, UPLO, N, KD, A, LDA, Q, LDQ, VL,
                 VU, IL, IU, ABTOL, NFOUND, W, Z, LDZ, WORK, WORK2, IWORK3, IFAIL,
                 INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX A(LDA,*), Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER IWORK3(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION W(*), WORK2(*)
```

```
SUBROUTINE ZHBEVX_64(JOBZ, RANGE, UPLO, N, KD, A, LDA, Q, LDQ, VL,
                   VU, IL, IU, ABTOL, NFOUND, W, Z, LDZ, WORK, WORK2, IWORK3, IFAIL,
                   INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX A(LDA,*), Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER*8 N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER*8 IWORK3(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HBEVX(JOBZ, RANGE, UPLO, [N], KD, A, [LDA], Q, [LDQ],
                VL, VU, IL, IU, ABTOL, [NFOUND], W, Z, [LDZ], [WORK], [WORK2],
                [IWORK3], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, Q, Z
INTEGER :: N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK3, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: W, WORK2
```

```

SUBROUTINE HBEVX_64(JOBZ, RANGE, UPLO, [N], KD, A, [LDA], Q, [LDQ],
  VL, VU, IL, IU, ABTOL, [NFOUND], W, Z, [LDZ], [WORK], [WORK2],
  [IWORK3], IFAIL, [INFO])

```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, Q, Z
INTEGER(8) :: N, KD, LDA, LDQ, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK3, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: W, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhbevz(char jobz, char range, char uplo, int n, int kd,
  doublecomplex *a, int lda, doublecomplex *q, int
  ldq, double vl, double vu, int il, int iu, double
  abtol, int *nfound, double *w, doublecomplex *z,
  int ldz, int *ifail, int *info);

```

```

void zhbevz_64(char jobz, char range, char uplo, long n,
  long kd, doublecomplex *a, long lda, doublecomplex
  *q, long ldq, double vl, double vu, long il, long
  iu, double abtol, long *nfound, double *w, doub-
  lecomplex *z, long ldz, long *ifail, long *info);

```

PURPOSE

zhbevz computes selected eigenvalues and, optionally, eigen-
vectors of a complex Hermitian band matrix A. Eigenvalues
and eigenvectors can be selected by specifying either a
range of values or a range of indices for the desired eigen-
values.

ARGUMENTS

JOBZ (input)

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)

= 'A': all eigenvalues will be found;
= 'V': all eigenvalues in the half-open interval
(VL,VU] will be found; = 'I': the IL-th through
IU-th eigenvalues will be found.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. N >= 0.

KD (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO

= 'L'. KD >= 0.

A (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first KD+1 rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$.

On exit, A is overwritten by values generated during the reduction to tridiagonal form.

LDA (input)

The leading dimension of the array A. LDA >= KD + 1.

Q (output)

If JOBZ = 'V', the N-by-N unitary matrix used in the reduction to tridiagonal form. If JOBZ = 'N', the array Q is not referenced.

LDQ (input)

The leading dimension of the array Q. If JOBZ = 'V', then LDQ >= max(1,N).

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; IL = 1 and IU = 0 if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; IL = 1 and IU = 0 if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where |T| is the 1-norm of the

tridiagonal matrix obtained by reducing A to tri-diagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2*SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)

The first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if $INFO = 0$, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, NFOUND)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension(N)

WORK2 (workspace)

dimension(7*N)

IWORK3 (workspace)

dimension(5*N)

IFAIL (output)

If JOBZ = 'V', then if $INFO = 0$, the first NFOUND elements of IFAIL are zero. If $INFO > 0$, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, then i eigenvectors failed to

converge. Their indices are stored in array
IFAIL.

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NAME

zhhgst - reduce a complex Hermitian-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$,

SYNOPSIS

```
SUBROUTINE ZHHGST(VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X, LDX,
                 WORK, RWORK, INFO)
```

```
CHARACTER * 1 VECT, UPLO
DOUBLE COMPLEX AB(LDAB,*), BB(LDBB,*), X(LDX,*), WORK(*)
INTEGER N, KA, KB, LDAB, LDBB, LDX, INFO
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZHHGST_64(VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X,
                    LDX, WORK, RWORK, INFO)
```

```
CHARACTER * 1 VECT, UPLO
DOUBLE COMPLEX AB(LDAB,*), BB(LDBB,*), X(LDX,*), WORK(*)
INTEGER*8 N, KA, KB, LDAB, LDBB, LDX, INFO
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBGST(VECT, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], X,
                [LDX], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: AB, BB, X
INTEGER :: N, KA, KB, LDAB, LDBB, LDX, INFO
REAL(8), DIMENSION(:) :: RWORK
```

```
SUBROUTINE HBGST_64(VECT, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],
                   X, [LDX], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: AB, BB, X
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDX, INFO
REAL(8), DIMENSION(:) :: RWORK
```

C INTERFACE

```
#include <sunperf.h>

void zhbgst(char vect, char uplo, int n, int ka, int kb,
            doublecomplex *ab, int ldab, doublecomplex *bb,
            int ldbb, doublecomplex *x, int ldx, int *info);
void zhbgst_64(char vect, char uplo, long n, long ka, long
               kb, doublecomplex *ab, long ldab, doublecomplex
               *bb, long ldbb, doublecomplex *x, long ldx, long
               *info);
```

PURPOSE

zhbgst reduces a complex Hermitian-definite banded generalized eigenproblem $A*x = \lambda*B*x$ to standard form $C*y = \lambda*y$, such that C has the same bandwidth as A .

B must have been previously factorized as $S**H*S$ by CPBSTF, using a split Cholesky factorization. A is overwritten by $C = X**H*A*X$, where $X = S**(-1)*Q$ and Q is a unitary matrix chosen to preserve the bandwidth of A .

ARGUMENTS

VECT (input)

= 'N': do not form the transformation matrix X ;
= 'V': form X .

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrices A and B . $N \geq 0$.

KA (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KA \geq 0$.

KB (input)

The number of superdiagonals of the matrix B if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KA \geq KB \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A , stored in the first $ka+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1, j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n, j+ka)$.

On exit, the transformed matrix $X**H*A*X$, stored in the same format as A .

LDAB (input)
The leading dimension of the array AB. LDAB \geq KA+1.

BB (input)
The banded factor S from the split Cholesky factorization of B, as returned by CPBSTF, stored in the first kb+1 rows of the array.

LDBB (input)
The leading dimension of the array BB. LDBB \geq KB+1.

X (output)
If VECT = 'V', the n-by-n matrix X. If VECT = 'N', the array X is not referenced.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N) if VECT = 'V'; LDX \geq 1 otherwise.

WORK (workspace)
dimension(N)

RWORK (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

zbgv - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

SYNOPSIS

```
SUBROUTINE ZHBGV(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
                LDZ, WORK, RWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AB(LDAB,*), BB(LDBB,*), Z(LDZ,*), WORK(*)  
INTEGER N, KA, KB, LDAB, LDBB, LDZ, INFO  
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHBGV_64(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
                  LDZ, WORK, RWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AB(LDAB,*), BB(LDBB,*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, KA, KB, LDAB, LDBB, LDZ, INFO  
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBGV(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], W,  
               Z, [LDZ], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: AB, BB, Z  
INTEGER :: N, KA, KB, LDAB, LDBB, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HBGV_64(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],  
                  W, Z, [LDZ], [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: AB, BB, Z  
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, RWORK
```

C INTERFACE

```
#include <sunperf.h>

void zhbv(char jobz, char uplo, int n, int ka, int kb,
doublecomplex *ab, int ldab, doublecomplex *bb,
int ldbb, double *w, doublecomplex *z, int ldz,
int *info);

void zhbv_64(char jobz, char uplo, long n, long ka, long
kb, doublecomplex *ab, long ldab, doublecomplex
*bb, long ldbb, double *w, doublecomplex *z, long
ldz, long *info);
```

PURPOSE

zhbv computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $Ax=(\lambda)Bx$. Here A and B are assumed to be Hermitian and banded, and B is also positive definite.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangles of A and B are stored;
= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B . $N \geq 0$.

KA (input)
The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KA \geq 0$.

KB (input)
The number of superdiagonals of the matrix B if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KB \geq 0$.

AB (input/output)
On entry, the upper or lower triangle of the Hermitian band matrix A , stored in the first $ka+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+ka)$.
On exit, the contents of AB are destroyed.

LDAB (input)
The leading dimension of the array AB . $LDAB \geq$

KA+1.

BB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix B, stored in the first kb+1 rows of the array. The j-th column of B is stored in the j-th column of the array BB as follows: if UPLO = 'U', $BB(kb+1+i-j,j) = B(i,j)$ for $\max(1,j-kb) \leq i \leq j$; if UPLO = 'L', $BB(1+i-j,j) = B(i,j)$ for $j \leq i \leq \min(n,j+kb)$.

On exit, the factor S from the split Cholesky factorization $B = S^*H^*S$, as returned by CPBSTF.

LDBB (input)

The leading dimension of the array BB. LDBB \geq KB+1.

W (output)

If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with W(i). The eigenvectors are normalized so that $Z^*H^*B^*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq N.

WORK (workspace)

dimension(N)

RWORK (workspace)

dimension(3*N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is:
<= N: the algorithm failed to converge: i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq N$, then CPBSTF returned INFO = i: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

zhhgvd - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

SYNOPSIS

```
SUBROUTINE ZHHGVD(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
  LDZ, WORK, LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AB(LDAB,*), BB(LDBB,*), Z(LDZ,*), WORK(*)  
INTEGER N, KA, KB, LDAB, LDBB, LDZ, LWORK, LRWORK, LIWORK,  
INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHHGVD_64(JOBZ, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, W, Z,  
  LDZ, WORK, LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AB(LDAB,*), BB(LDBB,*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, KA, KB, LDAB, LDBB, LDZ, LWORK, LRWORK, LIWORK,  
INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBGVD(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB], W,  
  Z, [LDZ], [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK],  
  [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: AB, BB, Z  
INTEGER :: N, KA, KB, LDAB, LDBB, LDZ, LWORK, LRWORK,  
LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, RWORK
```

```

SUBROUTINE HBGVD_64(JOBZ, UPLO, [N], KA, KB, AB, [LDAB], BB, [LDBB],
    W, Z, [LDZ], [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK],
    [INFO])

```

```

CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: AB, BB, Z
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDZ, LWORK, LRWORK,
LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: W, RWORK

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhbzgvd(char jobz, char uplo, int n, int ka, int kb,
    doublecomplex *ab, int ldab, doublecomplex *bb,
    int ldbb, double *w, doublecomplex *z, int ldz,
    int *info);

```

```

void zhbzgvd_64(char jobz, char uplo, long n, long ka, long
    kb, doublecomplex *ab, long ldab, doublecomplex
    *bb, long ldbb, double *w, doublecomplex *z, long
    ldz, long *info);

```

PURPOSE

zhbzgvd computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)B*x$. Here A and B are assumed to be Hermitian and banded, and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
 = 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B . $N \geq 0$.

KA (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. KA >= 0.

KB (input)

The number of superdiagonals of the matrix B if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. KB >= 0.

AB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first ka+1 rows of the array. The j-th column of A is stored in the j-th column of the array AB as follows: if UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+ka)$.

On exit, the contents of AB are destroyed.

LDAB (input)

The leading dimension of the array AB. LDAB >= KA+1.

BB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix B, stored in the first kb+1 rows of the array. The j-th column of B is stored in the j-th column of the array BB as follows: if UPLO = 'U', $BB(kb+1+i-j,j) = B(i,j)$ for $\max(1,j-kb) \leq i \leq j$; if UPLO = 'L', $BB(1+i-j,j) = B(i,j)$ for $j \leq i \leq \min(n,j+kb)$.

On exit, the factor S from the split Cholesky factorization $B = S^*H^*S$, as returned by CPBSTF.

LDBB (input)

The leading dimension of the array BB. LDBB >= KB+1.

W (output)

If INFO = 0, the eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with W(i). The eigenvectors are normalized so that $Z^*H^*B^*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= N.

WORK (workspace)

On exit, if INFO=0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If $N \leq 1$, LWORK >= 1. If JOBZ = 'N' and $N > 1$, LWORK >= N. If JOBZ = 'V' and $N > 1$, LWORK >= $2*N**2$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

On exit, if INFO=0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)

The dimension of array RWORK. If $N \leq 1$, LRWORK ≥ 1 . If JOBZ = 'N' and $N > 1$, LRWORK $\geq N$. If JOBZ = 'V' and $N > 1$, LRWORK $\geq 1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO=0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of array IWORK. If JOBZ = 'N' or $N \leq 1$, LIWORK ≥ 1 . If JOBZ = 'V' and $N > 1$, LIWORK $\geq 3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is:
<= N: the algorithm failed to converge: i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq N$, then CPBSTF returned INFO = i: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

zhbgvx - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)*B*x$

SYNOPSIS

```
SUBROUTINE ZHBGVX(JOBZ, RANGE, UPLO, N, KA, KB, AB, LDAB, BB, LDBB,
  Q, LDQ, VL, VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, RWORK, IWORK,
  IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX AB(LDAB,*), BB(LDBB,*), Q(LDQ,*), Z(LDZ,*),
WORK(*)
INTEGER N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHBGVX_64(JOBZ, RANGE, UPLO, N, KA, KB, AB, LDAB, BB,
  LDBB, Q, LDQ, VL, VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, RWORK,
  IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX AB(LDAB,*), BB(LDBB,*), Q(LDQ,*), Z(LDZ,*),
WORK(*)
INTEGER*8 N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER*8 IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HBGVX(JOBZ, RANGE, UPLO, [N], KA, KB, AB, [LDAB], BB,
  [LDBB], Q, [LDQ], VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK],
  [RWORK], [IWORK], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: AB, BB, Q, Z
```

```

INTEGER :: N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, RWORK

SUBROUTINE HBGVX_64(JOBZ, RANGE, UPLO, [N], KA, KB, AB, [LDAB], BB,
  [LDBB], Q, [LDQ], VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK],
  [RWORK], [IWORK], IFAIL, [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: AB, BB, Q, Z
INTEGER(8) :: N, KA, KB, LDAB, LDBB, LDQ, IL, IU, M, LDZ,
INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zhbgvx(char jobz, char range, char uplo, int n, int ka,
  int kb, doublecomplex *ab, int ldab, doublecomplex
  *bb, int ldbb, doublecomplex *q, int ldq, double
  vl, double vu, int il, int iu, double abstol, int
  *m, double *w, doublecomplex *z, int ldz, int
  *ifail, int *info);

void zhbgvx_64(char jobz, char range, char uplo, long n,
  long ka, long kb, doublecomplex *ab, long ldab,
  doublecomplex *bb, long ldbb, doublecomplex *q,
  long ldq, double vl, double vu, long il, long iu,
  double abstol, long *m, double *w, doublecomplex
  *z, long ldz, long *ifail, long *info);

```

PURPOSE

zhbgvx computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite banded eigenproblem, of the form $A*x=(\lambda)B*x$. Here A and B are assumed to be Hermitian and banded, and B is also positive definite. Eigenvalues and eigenvectors can be selected by specifying either all eigenvalues, a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found;
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found; = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

KA (input)
 The number of superdiagonals of the matrix A if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KA \geq 0$.

KB (input)
 The number of superdiagonals of the matrix B if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KB \geq 0$.

AB (input/output)
 On entry, the upper or lower triangle of the Her-
 mitian band matrix A, stored in the first $ka+1$
 rows of the array. The j -th column of A is stored
 in the j -th column of the array AB as follows: if
 UPLO = 'U', $AB(ka+1+i-j,j) = A(i,j)$ for $\max(1,j-$
 $ka) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$
 for $j \leq i \leq \min(n,j+ka)$.

 On exit, the contents of AB are destroyed.

LDAB (input)
 The leading dimension of the array AB. $LDAB \geq$
 $KA+1$.

BB (input/output)
 On entry, the upper or lower triangle of the Her-
 mitian band matrix B, stored in the first $kb+1$
 rows of the array. The j -th column of B is stored
 in the j -th column of the array BB as follows: if
 UPLO = 'U', $BB(kb+1+i-j,j) = B(i,j)$ for $\max(1,j-$
 $kb) \leq i \leq j$; if UPLO = 'L', $BB(1+i-j,j) = B(i,j)$
 for $j \leq i \leq \min(n,j+kb)$.

 On exit, the factor S from the split Cholesky fac-
 torization $B = S^*H^*S$, as returned by CPBSTF.

LDBB (input)
 The leading dimension of the array BB. $LDBB \geq$
 $KB+1$.

Q (output)
 If JOBZ = 'V', the n -by- n matrix used in the
 reduction of $A*x = (\lambda)*B*x$ to standard form,
 i.e. $C*x = (\lambda)*x$, and consequently C to tri-
 diagonal form. If JOBZ = 'N', the array Q is not
 referenced.

LDQ (input)
 The leading dimension of the array Q. If JOBZ =
 'N', $LDQ \geq 1$. If JOBZ = 'V', $LDQ \geq \max(1,N)$.

VL (input)
 If RANGE='V', the lower and upper bounds of the
 interval to be searched for eigenvalues. $VL < VU$.

Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing AP to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2 * SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

If $INFO = 0$, the eigenvalues in ascending order.

Z (input)

If $JOBZ = 'V'$, then if $INFO = 0$, Z contains the matrix Z of eigenvectors, with the i-th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized so that $Z^* H B Z = I$. If $JOBZ = 'N'$, then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if $JOBZ = 'V'$, $LDZ \geq N$.

WORK (workspace)

dimension(N)

RWORK (workspace)
dimension(7*N)

IWORK (workspace)
dimension(5*N)

IFAIL (output)
If JOBZ = 'V', then if INFO = 0, the first M elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is:
<= N: then i eigenvectors failed to converge. Their indices are stored in array IFAIL. > N: if INFO = N + i, for 1 <= i <= N, then CPBSTF returned INFO = i: B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

zgbmv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE ZGBMV(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y,  
                INCY)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER N, K, LDA, INCX, INCY
```

```
SUBROUTINE ZGBMV_64(UPLO, N, K, ALPHA, A, LDA, X, INCX, BETA, Y,  
                  INCY)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER*8 N, K, LDA, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE HGBMV(UPLO, [N], K, ALPHA, A, [LDA], X, [INCX], BETA,  
                Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, K, LDA, INCX, INCY
```

```
SUBROUTINE HGBMV_64(UPLO, [N], K, ALPHA, A, [LDA], X, [INCX],  
                   BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, K, LDA, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>

void zhbmv(char uplo, int n, int k, doublecomplex *alpha,
           doublecomplex *a, int lda, doublecomplex *x, int
           incx, doublecomplex *beta, doublecomplex *y, int
           incy);

void zhbmv_64(char uplo, long n, long k, doublecomplex
              *alpha, doublecomplex *a, long lda, doublecomplex
              *x, long incx, doublecomplex *beta, doublecomplex
              *y, long incy);
```

PURPOSE

zhbmv performs the matrix-vector operation $y := \alpha A x + \beta y$ where α and β are scalars, x and y are n element vectors and A is an n by n hermitian band matrix, with k super-diagonals.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the band matrix A is being supplied as follows:

UPLO = 'U' or 'u' The upper triangular part of A is being supplied.

UPLO = 'L' or 'l' The lower triangular part of A is being supplied.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

K (input)

On entry, K specifies the number of super-diagonals of the matrix A . K must satisfy $0 \leq K$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading $(k + 1)$ by n part of the array A must contain the upper triangular band part of the hermitian matrix, supplied column by column, with the leading diagonal of the matrix in row $(k + 1)$ of the array, the first super-diagonal starting at position 2 in row k , and so on. The top left k by k triangle of the array A is not referenced. The

following program segment will transfer the upper triangular part of a hermitian band matrix from conventional full matrix storage to band storage:

```
      DO 20, J = 1, N
        M = K + 1 - J
        DO 10, I = MAX( 1, J - K ), J
          A( M + I, J ) = matrix( I, J )
10     CONTINUE
20    CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading ($k + 1$) by n part of the array A must contain the lower triangular band part of the hermitian matrix, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer the lower triangular part of a hermitian band matrix from conventional full matrix storage to band storage:

```
      DO 20, J = 1, N
        M = 1 - J
        DO 10, I = J, MIN( N, J + K )
          A( M + I, J ) = matrix( I, J )
10     CONTINUE
20    CONTINUE
```

Note that the imaginary parts of the diagonal elements need not be set and are assumed to be zero. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq (k + 1)$. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX must not be zero. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. Unchanged on exit.

Y (input/output)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY must not be zero. Unchanged

on exit.

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NAME

zhbtrd - reduce a complex Hermitian band matrix A to real symmetric tridiagonal form T by a unitary similarity transformation

SYNOPSIS

```
SUBROUTINE ZHBTRD(VECT, UPLO, N, KD, AB, LDAB, D, E, Q, LDQ, WORK,  
INFO)
```

```
CHARACTER * 1 VECT, UPLO  
DOUBLE COMPLEX AB(LDAB,*), Q(LDQ,*), WORK(*)  
INTEGER N, KD, LDAB, LDQ, INFO  
DOUBLE PRECISION D(*), E(*)
```

```
SUBROUTINE ZHBTRD_64(VECT, UPLO, N, KD, AB, LDAB, D, E, Q, LDQ, WORK,  
INFO)
```

```
CHARACTER * 1 VECT, UPLO  
DOUBLE COMPLEX AB(LDAB,*), Q(LDQ,*), WORK(*)  
INTEGER*8 N, KD, LDAB, LDQ, INFO  
DOUBLE PRECISION D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE HBTRD(VECT, UPLO, [N], KD, AB, [LDAB], D, E, Q, [LDQ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,) :: AB, Q  
INTEGER :: N, KD, LDAB, LDQ, INFO  
REAL(8), DIMENSION(:) :: D, E
```

```
SUBROUTINE HBTRD_64(VECT, UPLO, [N], KD, AB, [LDAB], D, E, Q, [LDQ],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,) :: AB, Q
```

```
INTEGER(8) :: N, KD, LDAB, LDQ, INFO
REAL(8), DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhbtrd(char vect, char uplo, int n, int kd, doublecomplex
            *ab, int ldab, double *d, double *e, doublecomplex
            *q, int ldq, int *info);
void zhbtrd_64(char vect, char uplo, long n, long kd, doublecomplex
               *ab, long ldab, double *d, double *e, doublecomplex
               *q, long ldq, long *info);
```

PURPOSE

zhbtrd reduces a complex Hermitian band matrix A to real symmetric tridiagonal form T by a unitary similarity transformation: $Q^*H * A * Q = T$.

ARGUMENTS

VECT (input)

- = 'N': do not form Q;
- = 'V': form Q;
- = 'U': update a matrix X, by forming $X*Q$.

UPLO (input)

- = 'U': Upper triangle of A is stored;
- = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. On exit, the diagonal elements of AB are overwritten by the diagonal elements of the tridiagonal matrix T; if $KD > 0$, the elements on the first superdiagonal (if UPLO = 'U') or the first subdiagonal (if UPLO = 'L') are overwritten by the off-diagonal elements of T; the rest of AB is overwritten by values generated during the reduction.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq KD+1$.

D (output)
The diagonal elements of the tridiagonal matrix T.

E (output)
The off-diagonal elements of the tridiagonal matrix T: $E(i) = T(i,i+1)$ if UPLO = 'U'; $E(i) = T(i+1,i)$ if UPLO = 'L'.

Q (input/output)
On entry, if VECT = 'U', then Q must contain an N-by-N matrix X; if VECT = 'N' or 'V', then Q need not be set.

On exit: if VECT = 'V', Q contains the N-by-N unitary matrix Q; if VECT = 'U', Q contains the product $X*Q$; if VECT = 'N', the array Q is not referenced.

LDQ (input)
The leading dimension of the array Q. $LDQ \geq 1$, and $LDQ \geq N$ if VECT = 'V' or 'U'.

WORK (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Modified by Linda Kaufman, Bell Labs.

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NAME

zhecon - estimate the reciprocal of the condition number of a complex Hermitian matrix A using the factorization $A = U^*D*U^*H$ or $A = L^*D*L^*H$ computed by ZHETRF

SYNOPSIS

```
SUBROUTINE ZHECON(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(LDA,*), WORK(*)
INTEGER N, LDA, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION ANORM, RCOND
```

```
SUBROUTINE ZHECON_64(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK,
INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(LDA,*), WORK(*)
INTEGER*8 N, LDA, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE HECON(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER :: N, LDA, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8) :: ANORM, RCOND
```

```
SUBROUTINE HECON_64(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
```

```
INTEGER(8) :: N, LDA, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>
void zhecon(char uplo, int n, doublecomplex *a, int lda, int
            *ipivot, double anorm, double *rcond, int *info);

void zhecon_64(char uplo, long n, doublecomplex *a, long
              lda, long *ipivot, double anorm, double *rcond,
              long *info);
```

PURPOSE

zhecon estimates the reciprocal of the condition number of a complex Hermitian matrix A using the factorization $A = U^*D^*U^{**H}$ or $A = L^*D^*L^{**H}$ computed by ZHETRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U^*D^*U^{**H}$;
= 'L': Lower triangular, form is $A = L^*D^*L^{**H}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZHETRF.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by ZHETRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{AINVM})$, where AINVM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zheev - compute all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

SYNOPSIS

```
SUBROUTINE ZHEEV(JOBZ, UPLO, N, A, LDA, W, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
DOUBLE COMPLEX A(LDA,*), WORK(*)
INTEGER N, LDA, LDWORK, INFO
DOUBLE PRECISION W(*), WORK2(*)
```

```
SUBROUTINE ZHEEV_64(JOBZ, UPLO, N, A, LDA, W, WORK, LDWORK, WORK2,
INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
DOUBLE COMPLEX A(LDA,*), WORK(*)
INTEGER*8 N, LDA, LDWORK, INFO
DOUBLE PRECISION W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HEEV(JOBZ, UPLO, [N], A, [LDA], W, [WORK], [LDWORK],
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER :: N, LDA, LDWORK, INFO
REAL(8), DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HEEV_64(JOBZ, UPLO, [N], A, [LDA], W, [WORK], [LDWORK],
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: N, LDA, LDWORK, INFO
REAL(8), DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void zheev(char jobz, char uplo, int n, doublecomplex *a,
           int lda, double *w, int *info);

void zheev_64(char jobz, char uplo, long n, doublecomplex
              *a, long lda, double *w, long *info);
```

PURPOSE

zheev computes all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)
 On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, if JOBZ = 'V', then if INFO = 0, A contains the orthonormal eigenvectors of the matrix A. If JOBZ = 'N', then on exit the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The length of the array WORK. $LDWORK \geq \max(1, 2*N-1)$. For optimal efficiency, $LDWORK \geq (NB+1)*N$, where NB is the blocksize for ZHETRD returned by ILAENV.
 If LDWORK = -1, then a workspace query is assumed;

the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)

dimension(max(1,3*N-2))

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

zheevd - compute all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

SYNOPSIS

```
SUBROUTINE ZHEEVD(JOBZ, UPLO, N, A, LDA, W, WORK, LWORK, RWORK,  
                 LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHEEVD_64(JOBZ, UPLO, N, A, LDA, W, WORK, LWORK, RWORK,  
                   LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HEEVD(JOBZ, UPLO, [N], A, [LDA], W, [WORK], [LWORK],  
                [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HEEVD_64(JOBZ, UPLO, [N], A, [LDA], W, [WORK], [LWORK],  
                   [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
```

```
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: N, LDA, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: W, RWORK
```

C INTERFACE

```
#include <sunperf.h>
void zheevd(char jobz, char uplo, int n, doublecomplex *a,
            int lda, double *w, int *info);

void zheevd_64(char jobz, char uplo, long n, doublecomplex
               *a, long lda, double *w, long *info);
```

PURPOSE

zheevd computes all eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)
On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, if JOBZ = 'V', then if INFO = 0, A contains the orthonormal eigenvectors of the matrix A. If JOBZ = 'N', then on exit the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, N)$.

W (output)
 If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The length of the array WORK. If $N \leq 1$, LWORK must be at least 1. If JOBZ = 'N' and $N > 1$, LWORK must be at least $N + 1$. If JOBZ = 'V' and $N > 1$, LWORK must be at least $2*N + N**2$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
 dimension (LRWORK) On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)
 The dimension of the array RWORK. If $N \leq 1$, LRWORK must be at least 1. If JOBZ = 'N' and $N > 1$, LRWORK must be at least N . If JOBZ = 'V' and $N > 1$, LRWORK must be at least $1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)
 On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
 The dimension of the array IWORK. If $N \leq 1$, LIWORK must be at least 1. If JOBZ = 'N' and $N > 1$, LIWORK must be at least 1. If JOBZ = 'V' and $N > 1$, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

FURTHER DETAILS

Based on contributions by
Jeff Rutter, Computer Science Division, University of
California
at Berkeley, USA

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NAME

zheevr - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian tridiagonal matrix T

SYNOPSIS

```
SUBROUTINE ZHEEVR(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
  ABSTOL, M, W, Z, LDZ, ISUPPZ, WORK, LWORK, RWORK, LRWORK, IWORK,
  LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)
INTEGER N, LDA, IL, IU, M, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER ISUPPZ(*), IWORK(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHEEVR_64(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
  ABSTOL, M, W, Z, LDZ, ISUPPZ, WORK, LWORK, RWORK, LRWORK, IWORK,
  LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)
INTEGER*8 N, LDA, IL, IU, M, LDZ, LWORK, LRWORK, LIWORK,
INFO
INTEGER*8 ISUPPZ(*), IWORK(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HEEVR(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
  ABSTOL, M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [RWORK], [LRWORK],
  [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, Z
INTEGER :: N, LDA, IL, IU, M, LDZ, LWORK, LRWORK, LIWORK,
INFO
```

```

INTEGER, DIMENSION(:) :: ISUPPZ, IWORK
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, RWORK

SUBROUTINE HEEVR_64(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
    ABSTOL, M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [RWORK], [LRWORK],
    [IWORK], [LIWORK], [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, Z
INTEGER(8) :: N, LDA, IL, IU, M, LDZ, LWORK, LRWORK, LIWORK,
INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zheevr(char jobz, char range, char uplo, int n, doublecomplex
    *a, int lda, double vl, double vu, int il, int iu, double abstol, int
    *m, double *w, doublecomplex *z, int ldz, int *isuppz, int
    *info);

void zheevr_64(char jobz, char range, char uplo, long n, doublecomplex
    *a, long lda, double vl, double vu, long il, long iu, double abstol, long
    *m, double *w, doublecomplex *z, long ldz, long *isuppz, long
    *info);

```

PURPOSE

zheevr computes selected eigenvalues and, optionally, eigenvectors of a complex Hermitian tridiagonal matrix T. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

Whenever possible, ZHEEVR calls CSTEGR to compute the eigenspectrum using Relatively Robust Representations. CSTEGR computes eigenvalues by the dqds algorithm, while orthogonal eigenvectors are computed from various "good" L D L^T representations (also known as Relatively Robust Representations). Gram-Schmidt orthogonalization is avoided as far as possible. More specifically, the various steps of the algorithm are as follows. For the i-th unreduced block of T,

- (a) Compute $T - \sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation,
- (b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high relative accuracy by the dqds algorithm,
- (c) If there is a cluster of close eigenvalues, "choose" σ_i close to the cluster, and go to step (a),
- (d) Given the approximate eigenvalue λ_j of $L_i D_i$

L_i^T ,
compute the corresponding eigenvector by forming a
rank-revealing twisted factorization.
The desired accuracy of the output can be specified by the
input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB//CSD-97-971, UC Berkeley, May 1997.

Note 1 : ZHEEVR calls CSTEGR when the full spectrum is requested on machines which conform to the ieee-754 floating point standard. ZHEEVR calls SSTEGBZ and CSTEIN on non-ieee machines and when partial spectrum requests are made.

Normal execution of CSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not handle NaNs and infinities in the ieee standard default manner.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)
On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A. On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

VL (input)
If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$.
Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABSTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

If high relative accuracy is important, set ABSTOL to SLAMCH('Safe minimum'). Doing so will guarantee that eigenvalues are computed to high relative accuracy when possible in future releases. The current code does not make any guarantees about high relative accuracy, but future releases will. See J. Barlow and J. Demmel, "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7, for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (input)

If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected

eigenvalues, with the i -th column of Z holding the eigenvector associated with $W(i)$. If $JOBZ = 'N'$, then Z is not referenced. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z ; if $RANGE = 'V'$, the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z . $LDZ \geq 1$, and if $JOBZ = 'V'$, $LDZ \geq \max(1, N)$.

ISUPPZ (output)

The support of the eigenvectors in Z , i.e., the indices indicating the nonzero elements in Z . The i -th eigenvector is nonzero only in elements $ISUPPZ(2*i-1)$ through $ISUPPZ(2*i)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LWORK$.

LWORK (input)

The length of the array $WORK$. $LWORK \geq \max(1, 2*N)$. For optimal efficiency, $LWORK \geq (NB+1)*N$, where NB is the max of the blocksize for $ZHETRD$ and for $CUNMTR$ as returned by $ILAENV$.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $WORK$ array, returns this value as the first entry of the $WORK$ array, and no error message related to $LWORK$ is issued by $XERBLA$.

RWORK (workspace)

On exit, if $INFO = 0$, $RWORK(1)$ returns the optimal (and minimal) $LRWORK$.

LRWORK (input)

The length of the array $RWORK$. $LRWORK \geq \max(1, 24*N)$.

If $LRWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $RWORK$ array, returns this value as the first entry of the $RWORK$ array, and no error message related to $LRWORK$ is issued by $XERBLA$.

IWORK (workspace/output)

On exit, if $INFO = 0$, $IWORK(1)$ returns the optimal (and minimal) $LIWORK$.

LIWORK (input)

The dimension of the array $IWORK$. $LIWORK \geq \max(1, 10*N)$.

If $LIWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $IWORK$ array, returns this value as the first entry of the $IWORK$ array, and no error message related to $LIWORK$ is issued by $XERBLA$.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: Internal error

FURTHER DETAILS

Based on contributions by
Inderjit Dhillon, IBM Almaden, USA
Osni Marques, LBNL/NERSC, USA
Ken Stanley, Computer Science Division, University of
California at Berkeley, USA

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NAME

zheevx - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A

SYNOPSIS

```
SUBROUTINE ZHEEVX(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
  ABTOL, NFOUND, W, Z, LDZ, WORK, LDWORK, WORK2, IWORK3, IFAIL,
  INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)
INTEGER N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER IWORK3(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION W(*), WORK2(*)
```

```
SUBROUTINE ZHEEVX_64(JOBZ, RANGE, UPLO, N, A, LDA, VL, VU, IL, IU,
  ABTOL, NFOUND, W, Z, LDZ, WORK, LDWORK, WORK2, IWORK3, IFAIL,
  INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX A(LDA,*), Z(LDZ,*), WORK(*)
INTEGER*8 N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER*8 IWORK3(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABTOL
DOUBLE PRECISION W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HEEVX(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
  ABTOL, [NFOUND], W, Z, [LDZ], [WORK], [LDWORK], [WORK2], [IWORK3],
  IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, Z
INTEGER :: N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER, DIMENSION(:) :: IWORK3, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: W, WORK2
```

```

SUBROUTINE HEEVX_64(JOBZ, RANGE, UPLO, [N], A, [LDA], VL, VU, IL, IU,
    ABTOL, [NFOUND], W, Z, [LDZ], [WORK], [LDWORK], [WORK2], [IWORK3],
    IFAIL, [INFO])

```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, Z
INTEGER(8) :: N, LDA, IL, IU, NFOUND, LDZ, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK3, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: W, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zheevx(char jobz, char range, char uplo, int n, doublecomplex
    *a, int lda, double vl, double vu, int il, int iu, double abtol, int
    *nfound, double *w, doublecomplex *z, int ldz, int *ifail, int *info);

```

```

void zheevx_64(char jobz, char range, char uplo, long n, doublecomplex
    *a, long lda, double vl, double vu, long il, long iu, double abtol, long
    *nfound, double *w, doublecomplex *z, long ldz, long *ifail, long
    *info);

```

PURPOSE

zheevx computes selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A. Eigenvalues and eigenvectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)

```

= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

```

RANGE (input)

```

= 'A': all eigenvalues will be found.
= 'V': all eigenvalues in the half-open interval (VL,VU] will be found.
= 'I': the IL-th through IU-th eigenvalues will be found.

```

UPLO (input)

```

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

```

N (input) The order of the matrix A. N >= 0.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower tri-

angular part of A contains the lower triangular part of the matrix A. On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a, b]$ of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS * |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2 * SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting ABTOL to $2 * SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output)
 On normal exit, the first NFOUND elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least max(1,NFOUND) columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)
 The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The length of the array WORK. LDWORK >= max(1,2*N). For optimal efficiency, LDWORK >= (NB+1)*N, where NB is the max of the blocksize for ZHETRD and for CUNMTR as returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
 dimension(7*N)

IWORK3 (workspace)
 dimension(5*N)

IFAIL (output)
 If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

zhegs2 - reduce a complex Hermitian-definite generalized eigenproblem to standard form

SYNOPSIS

```
SUBROUTINE ZHEGS2(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER ITYPE, N, LDA, LDB, INFO
```

```
SUBROUTINE ZHEGS2_64(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 ITYPE, N, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE HEGS2(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: ITYPE, N, LDA, LDB, INFO
```

```
SUBROUTINE HEGS2_64(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: ITYPE, N, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhegs2(int itype, char uplo, int n, doublecomplex *a,  
           int lda, doublecomplex *b, int ldb, int *info);
```

```
void zhegs2_64(long itype, char uplo, long n, doublecomplex  
              *a, long lda, doublecomplex *b, long ldb, long  
              *info);
```

PURPOSE

zhegs2 reduces a complex Hermitian-definite generalized eigenproblem to standard form.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $\text{inv}(U')*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L')$.
If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U'$ or $L'*A*L$.

B must have been previously factorized as $U'*U$ or $L'*L'$ by CPOTRF.

ARGUMENTS

$ITYPE$ (input)

= 1: compute $\text{inv}(U')*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L')$;
= 2 or 3: compute $U*A*U'$ or $L'*A*L$.

$UPLO$ (input)

Specifies whether the upper or lower triangular part of the Hermitian matrix A is stored, and how B has been factorized. = 'U': Upper triangular
= 'L': Lower triangular

N (input) The order of the matrices A and B . $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A . If $UPLO = 'U'$, the leading n by n upper triangular part of A contains the upper triangular part of the matrix A , and the strictly lower triangular part of A is not referenced. If $UPLO = 'L'$, the leading n by n lower triangular part of A contains the lower triangular part of the matrix A , and the strictly upper triangular part of A is not referenced.

On exit, if $INFO = 0$, the transformed matrix, stored in the same format as A .

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

B (input) The triangular factor from the Cholesky factorization of B , as returned by CPOTRF.

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

$INFO$ (output)

= 0: successful exit.
< 0: if $INFO = -i$, the i -th argument had an illegal value.

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NAME

zhegst - reduce a complex Hermitian-definite generalized eigenproblem to standard form

SYNOPSIS

```
SUBROUTINE ZHEGST(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER ITYPE, N, LDA, LDB, INFO
```

```
SUBROUTINE ZHEGST_64(ITYPE, UPLO, N, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 ITYPE, N, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE HEGST(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: ITYPE, N, LDA, LDB, INFO
```

```
SUBROUTINE HEGST_64(ITYPE, UPLO, N, A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: ITYPE, N, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhegst(int itype, char uplo, int n, doublecomplex *a,  
           int lda, doublecomplex *b, int ldb, int *info);
```

```
void zhegst_64(long itype, char uplo, long n, doublecomplex  
              *a, long lda, doublecomplex *b, long ldb, long  
              *info);
```

PURPOSE

zhegst reduces a complex Hermitian-definite generalized eigenproblem to standard form.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $inv(U^{*H})*A*inv(U)$ or $inv(L)*A*inv(L^{*H})$

If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U^{*H}$ or $L^{*H}*A*L$.

B must have been previously factorized as $U^{*H}*U$ or $L*L^{*H}$ by CPOTRF.

ARGUMENTS

$ITYPE$ (input)
= 1: compute $inv(U^{*H})*A*inv(U)$ or $inv(L)*A*inv(L^{*H})$;
= 2 or 3: compute $U*A*U^{*H}$ or $L^{*H}*A*L$.

$UPLO$ (input)
= 'U': Upper triangle of A is stored and B is factored as $U^{*H}*U$; = 'L': Lower triangle of A is stored and B is factored as $L*L^{*H}$.

N (input) The order of the matrices A and B . $N \geq 0$.

A (input/output)
On entry, the Hermitian matrix A . If $UPLO = 'U'$, the leading N -by- N upper triangular part of A contains the upper triangular part of the matrix A , and the strictly lower triangular part of A is not referenced. If $UPLO = 'L'$, the leading N -by- N lower triangular part of A contains the lower triangular part of the matrix A , and the strictly upper triangular part of A is not referenced.

On exit, if $INFO = 0$, the transformed matrix, stored in the same format as A .

LDA (input)
The leading dimension of the array A . $LDA \geq \max(1,N)$.

B (input) The triangular factor from the Cholesky factorization of B , as returned by CPOTRF.

LDB (input)
The leading dimension of the array B . $LDB \geq \max(1,N)$.

$INFO$ (output)
= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zhegv - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE ZHEGV(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,
                LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER ITYPE, N, LDA, LDB, LDWORK, INFO
DOUBLE PRECISION W(*), WORK2(*)
```

```
SUBROUTINE ZHEGV_64(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,
                  LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER*8 ITYPE, N, LDA, LDB, LDWORK, INFO
DOUBLE PRECISION W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HEGV(ITYPE, JOBZ, UPLO, N, A, [LDA], B, [LDB], W, [WORK],
               [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, B
INTEGER :: ITYPE, N, LDA, LDB, LDWORK, INFO
REAL(8), DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HEGV_64(ITYPE, JOBZ, UPLO, N, A, [LDA], B, [LDB], W, [WORK],
                  [LDWORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, B
INTEGER(8) :: ITYPE, N, LDA, LDB, LDWORK, INFO
```

```
REAL(8), DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhegv(int itype, char jobz, char uplo, int n, doublecomplex *a, int lda, doublecomplex *b, int ldb, double *w, int *info);
```

```
void zhegv_64(long itype, char jobz, char uplo, long n, doublecomplex *a, long lda, doublecomplex *b, long ldb, double *w, long *info);
```

PURPOSE

zhegv computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian and B is also positive definite.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

= 1: $A*x = (\lambda)*B*x$

= 2: $A*B*x = (\lambda)*x$

= 3: $B*A*x = (\lambda)*x$

JOBZ (input)

= 'N': Compute eigenvalues only;

= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

= 'U': Upper triangles of A and B are stored;

= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.

On exit, if JOBZ = 'V', then if INFO = 0, A contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z**H*B*Z = I$; if ITYPE = 3, $Z**H*inv(B)*Z = I$. If JOBZ = 'N', then on exit the upper triangle (if UPLO='U') or the lower triangle (if UPLO='L') of A, including the diagonal, is destroyed.

LDA (input)
 The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)
 On entry, the Hermitian positive definite matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if INFO \leq N, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*H^*U$ or $B = L^*L^*H$.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

W (output)
 If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
 The length of the array WORK. LDWORK \geq max(1,2*N-1). For optimal efficiency, LDWORK \geq (NB+1)*N, where NB is the blocksize for ZHETRD returned by ILAENV.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
 dimension(max(1,3*N-2))

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: CPOTRF or ZHEEV returned an error code:
 \leq N: if INFO = i, ZHEEV failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; $>$ N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

zhegvd - compute all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE ZHEGVD(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER ITYPE, N, LDA, LDB, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHEGVD_64(ITYPE, JOBZ, UPLO, N, A, LDA, B, LDB, W, WORK,  
                  LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)  
INTEGER*8 ITYPE, N, LDA, LDB, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HEGVD(ITYPE, JOBZ, UPLO, [N], A, [LDA], B, [LDB], W, [WORK],  
                [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, B  
INTEGER :: ITYPE, N, LDA, LDB, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HEGVD_64(ITYPE, JOBZ, UPLO, [N], A, [LDA], B, [LDB], W,  
                  [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B
INTEGER(8) :: ITYPE, N, LDA, LDB, LWORK, LRWORK, LIWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zhegvd(int itype, char jobz, char uplo, int n, double-
    lecomplex *a, int lda, doublecomplex *b, int ldb,
    double *w, int *info);

void zhegvd_64(long itype, char jobz, char uplo, long n,
    doublecomplex *a, long lda, doublecomplex *b, long
    ldb, double *w, long *info);

```

PURPOSE

zhegvd computes all the eigenvalues, and optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian and B is also positive definite. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)*B*x$
- = 2: $A*B*x = (\lambda)*x$
- = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

- = 'U': Upper triangles of A and B are stored;
- = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U',

the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.

On exit, if JOBZ = 'V', then if INFO = 0, A contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^*H*B*Z = I$; if ITYPE = 3, $Z^*H*inv(B)*Z = I$. If JOBZ = 'N', then on exit the upper triangle (if UPLO='U') or the lower triangle (if UPLO='L') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input/output)

On entry, the Hermitian matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if INFO \leq N, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*H*U$ or $B = L*L^*H$.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

W (output)

If INFO = 0, the eigenvalues in ascending order.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The length of the array WORK. If N \leq 1, LWORK \geq 1. If JOBZ = 'N' and N > 1, LWORK \geq N + 1. If JOBZ = 'V' and N > 1, LWORK \geq 2*N + N**2.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)

The dimension of the array RWORK. If N \leq 1, LRWORK \geq 1. If JOBZ = 'N' and N > 1, LRWORK \geq

N. If JOBZ = 'V' and $N > 1$, LRWORK $\geq 1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If $N \leq 1$, LIWORK ≥ 1 . If JOBZ = 'N' and $N > 1$, LIWORK ≥ 1 . If JOBZ = 'V' and $N > 1$, LIWORK $\geq 3 + 5*N$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: CPOTRF or ZHEEVD returned an error code:
<= N: if INFO = i, ZHEEVD failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

zhegvx - compute selected eigenvalues, and optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$

SYNOPSIS

```
SUBROUTINE ZHEGVX( ITYPE, JOBZ, RANGE, UPLO, N, A, LDA, B, LDB, VL,
                  VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, LWORK, RWORK, IWORK,
                  IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX A(LDA,*), B(LDB,*), Z(LDZ,*), WORK(*)
INTEGER ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHEGVX_64( ITYPE, JOBZ, RANGE, UPLO, N, A, LDA, B, LDB, VL,
                    VU, IL, IU, ABSTOL, M, W, Z, LDZ, WORK, LWORK, RWORK, IWORK,
                    IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX A(LDA,*), B(LDB,*), Z(LDZ,*), WORK(*)
INTEGER*8 ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
INTEGER*8 IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HEGVX( ITYPE, JOBZ, RANGE, UPLO, [N], A, [LDA], B, [LDB],
                 VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [LWORK], [RWORK],
                 [IWORK], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, Z
INTEGER :: ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK, INFO
```

```

INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, RWORK

SUBROUTINE HEGVX_64(ITYPE, JOBZ, RANGE, UPLO, [N], A, [LDA], B, [LDB],
    VL, VU, IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [LWORK], [RWORK],
    [IWORK], IFAIL, [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, Z
INTEGER(8) :: ITYPE, N, LDA, LDB, IL, IU, M, LDZ, LWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zhegvx(int itype, char jobz, char range, char uplo, int
    n, doublecomplex *a, int lda, doublecomplex *b,
    int ldb, double vl, double vu, int il, int iu,
    double abstol, int *m, double *w, doublecomplex
    *z, int ldz, int *ifail, int *info);

void zhegvx_64(long itype, char jobz, char range, char uplo,
    long n, doublecomplex *a, long lda, doublecomplex
    *b, long ldb, double vl, double vu, long il, long
    iu, double abstol, long *m, double *w, doublecom-
    plex *z, long ldz, long *ifail, long *info);

```

PURPOSE

zhegvx computes selected eigenvalues, and optionally, eigen-
vectors of a complex generalized Hermitian-definite eigen-
problem, of the form $A*x=(\lambda)*B*x$, $A*B*x=(\lambda)*x$, or
 $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian
and B is also positive definite. Eigenvalues and eigenvec-
tors can be selected by specifying either a range of values
or a range of indices for the desired eigenvalues.

ARGUMENTS

ITYPE (input)
Specifies the problem type to be solved:
= 1: $A*x = (\lambda)*B*x$
= 2: $A*B*x = (\lambda)*x$
= 3: $B*A*x = (\lambda)*x$

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
= 'A': all eigenvalues will be found.

= 'V': all eigenvalues in the half-open interval (VL,VU] will be found. = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)

= 'U': Upper triangles of A and B are stored;
= 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A.

On exit, the lower triangle (if UPLO='L') or the upper triangle (if UPLO='U') of A, including the diagonal, is destroyed.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

B (input/output)

On entry, the Hermitian matrix B. If UPLO = 'U', the leading N-by-N upper triangular part of B contains the upper triangular part of the matrix B. If UPLO = 'L', the leading N-by-N lower triangular part of B contains the lower triangular part of the matrix B.

On exit, if $INFO \leq N$, the part of B containing the matrix is overwritten by the triangular factor U or L from the Cholesky factorization $B = U^*H^*U$ or $B = L^*L^*H$.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of

the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if $RANGE = 'A'$ or $'V'$.

ABSTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval $[a,b]$ of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If $ABSTOL$ is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when $ABSTOL$ is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with $INFO > 0$, indicating that some eigenvectors did not converge, try setting $ABSTOL$ to $2*SLAMCH('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If $RANGE = 'A'$, $M = N$, and if $RANGE = 'I'$, $M = IU - IL + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (output)

If $JOBZ = 'N'$, then Z is not referenced. If $JOBZ = 'V'$, then if $INFO = 0$, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i -th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized as follows: if $ITYPE = 1$ or 2 , $Z^T B Z = I$; if $ITYPE = 3$, $Z^T \text{inv}(B) Z = I$.

If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in $IFAIL$. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z ; if $RANGE = 'V'$, the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z . $LDZ \geq 1$, and if $JOBZ = 'V'$, $LDZ \geq \max(1, N)$.

WORK (workspace/output)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LWORK$.

LWORK (input)

The length of the array WORK. LWORK \geq $\max(1, 2*N-1)$. For optimal efficiency, LWORK \geq $(NB+1)*N$, where NB is the blocksize for ZHETRD returned by ILAENV.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
dimension(7*N)

IWORK (workspace)
dimension(5*N)

IFAIL (output)
If JOBZ = 'V', then if INFO = 0, the first M elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: CPOTRF or ZHEEVX returned an error code:
<= N: if INFO = i, ZHEEVX failed to converge; i eigenvectors failed to converge. Their indices are stored in array IFAIL. > N: if INFO = N + i, for $1 \leq i \leq N$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

zhemm - perform one of the matrix-matrix operations $C := \alpha A * B + \beta C$ or $C := \alpha B * A + \beta C$

SYNOPSIS

```
SUBROUTINE ZHEMM(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                LDC)
```

```
CHARACTER * 1 SIDE, UPLO
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER M, N, LDA, LDB, LDC
```

```
SUBROUTINE ZHEMM_64(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                   LDC)
```

```
CHARACTER * 1 SIDE, UPLO
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 M, N, LDA, LDB, LDC
```

F95 INTERFACE

```
SUBROUTINE HEMM(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
               BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:,*) :: A, B, C
INTEGER :: M, N, LDA, LDB, LDC
```

```
SUBROUTINE HEMM_64(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
                  BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:,*) :: A, B, C
INTEGER(8) :: M, N, LDA, LDB, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhemm(char side, char uplo, int m, int n, doublecomplex
    *alpha, doublecomplex *a, int lda, doublecomplex
    *b, int ldb, doublecomplex *beta, doublecomplex
    *c, int ldc);
void zhemm_64(char side, char uplo, long m, long n, doub-
    lecomplex *alpha, doublecomplex *a, long lda,
    doublecomplex *b, long ldb, doublecomplex *beta,
    doublecomplex *c, long ldc);

```

PURPOSE

zhemm performs one of the matrix-matrix operations $C := \alpha A^*B + \beta C$ or $C := \alpha B^*A + \beta C$ where α and β are scalars, A is an hermitian matrix and B and C are m by n matrices.

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether the hermitian matrix A appears on the left or right in the operation as follows:

SIDE = 'L' or 'l' $C := \alpha A^*B + \beta C$,

SIDE = 'R' or 'r' $C := \alpha B^*A + \beta C$,

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the hermitian matrix A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of the hermitian matrix is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of the hermitian matrix is to be referenced.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of the matrix C . $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix C . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

COMPLEX*16 array of DIMENSION (LDA, ka), where ka is m when SIDE = 'L' or 'l' and is n otherwise.

Before entry with SIDE = 'L' or 'l', the m by m part of the array A must contain the hermitian matrix, such that when UPLO = 'U' or 'u', the leading m by m upper triangular part of the array A must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading m by m lower triangular part of the array A must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of A is not referenced.

Before entry with SIDE = 'R' or 'r', the n by n part of the array A must contain the hermitian matrix, such that when UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of A is not referenced.

Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then $LDA \geq \max(1, m)$, otherwise $LDA \geq \max(1, n)$. Unchanged on exit.

B (input)

COMPLEX*16 array of DIMENSION (LDB, n). Before entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. LDB must be at least $\max(1, m)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then C need not be set on input. Unchanged on exit.

C (input/output)

COMPLEX*16 array of DIMENSION (LDC, n).

Before entry, the leading m by n part of the array C must contain the matrix C, except when beta is zero, in which case C need not be set on

entry.

On exit, the array C is overwritten by the m by n updated matrix.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. LDC must be at least $\max(1, m)$. Unchanged on exit.

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NAME

zhemv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE ZHEMV(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER N, LDA, INCX, INCY
```

```
SUBROUTINE ZHEMV_64(UPLO, N, ALPHA, A, LDA, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(LDA,*), X(*), Y(*)  
INTEGER*8 N, LDA, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE HEMV(UPLO, [N], ALPHA, A, [LDA], X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INCX, INCY
```

```
SUBROUTINE HEMV_64(UPLO, [N], ALPHA, A, [LDA], X, [INCX], BETA, Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhemv(char uplo, int n, doublecomplex *alpha, doublecomplex *a, int lda, doublecomplex *x, int incx, doublecomplex *beta, doublecomplex *y, int incy);
```

```
void zhemv_64(char uplo, long n, doublecomplex *alpha, doublecomplex *a, long lda, doublecomplex *x, long incx, doublecomplex *beta, doublecomplex *y, long incy);
```

PURPOSE

zhemv performs the matrix-vector operation $y := \alpha A x + \beta y$ where α and β are scalars, x and y are n element vectors and A is an n by n hermitian matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of A is not referenced. Note that the imaginary parts of the diagonal elements need not be set and are assumed to be zero. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

X (input)
(1 + (n - 1) * abs(INCX)). Before entry, the incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)
On entry, INCX specifies the increment for the elements of X. INCX <> 0. Unchanged on exit.

BETA (input)
On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)
(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)
On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

zher - perform the hermitian rank 1 operation $A := \alpha * x * \text{conjg}(x') + A$

SYNOPSIS

```
SUBROUTINE ZHER(UPLO, N, ALPHA, X, INCX, A, LDA)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX X(*), A(LDA,*)  
INTEGER N, INCX, LDA  
DOUBLE PRECISION ALPHA
```

```
SUBROUTINE ZHER_64(UPLO, N, ALPHA, X, INCX, A, LDA)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX X(*), A(LDA,*)  
INTEGER*8 N, INCX, LDA  
DOUBLE PRECISION ALPHA
```

F95 INTERFACE

```
SUBROUTINE HER(UPLO, [N], ALPHA, X, [INCX], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: X  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, INCX, LDA  
REAL(8) :: ALPHA
```

```
SUBROUTINE HER_64(UPLO, [N], ALPHA, X, [INCX], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: X  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, INCX, LDA  
REAL(8) :: ALPHA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zher(char uplo, int n, double alpha, doublecomplex *x,
```

```

        int incx, doublecomplex *a, int lda);

void zher_64(char uplo, long n, double alpha, doublecomplex
            *x, long incx, doublecomplex *a, long lda);

```

PURPOSE

zher performs the hermitian rank 1 operation $A := \alpha x \text{conjg}(x') + A$ where alpha is a real scalar, x is an n element vector and A is an n by n hermitian matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

A (input/output)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of A is not referenced. On exit, the upper triangular part of the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of A is not referenced. On exit, the lower triangular part of

the array A is overwritten by the lower triangular part of the updated matrix. Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA \geq max(1, n). Unchanged on exit.

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NAME

zher2 - perform the hermitian rank 2 operation $A := \alpha * x * \text{conjg}(y') + \text{conjg}(\alpha) * y * \text{conjg}(x') + A$

SYNOPSIS

```
SUBROUTINE ZHER2(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER N, INCX, INCY, LDA
```

```
SUBROUTINE ZHER2_64(UPLO, N, ALPHA, X, INCX, Y, INCY, A, LDA)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*), A(LDA,*)  
INTEGER*8 N, INCX, INCY, LDA
```

F95 INTERFACE

```
SUBROUTINE HER2(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:,) :: A  
INTEGER :: N, INCX, INCY, LDA
```

```
SUBROUTINE HER2_64(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], A, [LDA])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y  
COMPLEX(8), DIMENSION(:,) :: A  
INTEGER(8) :: N, INCX, INCY, LDA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zher2(char uplo, int n, doublecomplex *alpha, doub-
```

```

        lecomplex *x, int incx, doublecomplex *y, int
        incy, doublecomplex *a, int lda);

void zher2_64(char uplo, long n, doublecomplex *alpha, doub-
        lecomplex *x, long incx, doublecomplex *y, long
        incy, doublecomplex *a, long lda);

```

PURPOSE

zher2 performs the hermitian rank 2 operation $A := \alpha x \text{conjg}(y') + \text{conjg}(\alpha) y \text{conjg}(x') + A$ where α is a scalar, x and y are n element vectors and A is an n by n hermitian matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of A is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of A is to be referenced.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (n - 1) \cdot \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

$(1 + (n - 1) \cdot \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

A (input/output)

Before entry with `UPLO = 'U' or 'u'`, the leading `n` by `n` upper triangular part of the array `A` must contain the upper triangular part of the hermitian matrix and the strictly lower triangular part of `A` is not referenced. On exit, the upper triangular part of the array `A` is overwritten by the upper triangular part of the updated matrix. Before entry with `UPLO = 'L' or 'l'`, the leading `n` by `n` lower triangular part of the array `A` must contain the lower triangular part of the hermitian matrix and the strictly upper triangular part of `A` is not referenced. On exit, the lower triangular part of the array `A` is overwritten by the lower triangular part of the updated matrix. Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

`LDA` (input)

On entry, `LDA` specifies the first dimension of `A` as declared in the calling (sub) program. `LDA` \geq `max(1, n)`. Unchanged on exit.

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NAME

zher2k - perform one of the Hermitian rank 2k operations $C := \alpha A \text{conjg}(B') + \text{conjg}(\alpha) B \text{conjg}(A') + \beta C$ or $C := \alpha \text{conjg}(A') B + \text{conjg}(\alpha) \text{conjg}(B') A + \beta C$

SYNOPSIS

```
SUBROUTINE ZHER2K(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA, C,
  LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
DOUBLE COMPLEX ALPHA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER N, K, LDA, LDB, LDC
DOUBLE PRECISION BETA
```

```
SUBROUTINE ZHER2K_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA,
  C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
DOUBLE COMPLEX ALPHA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 N, K, LDA, LDB, LDC
DOUBLE PRECISION BETA
```

F95 INTERFACE

```
SUBROUTINE HER2K(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B, [LDB],
  BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
COMPLEX(8) :: ALPHA
COMPLEX(8), DIMENSION(:,:) :: A, B, C
INTEGER :: N, K, LDA, LDB, LDC
REAL(8) :: BETA
```

```
SUBROUTINE HER2K_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B,
  [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
COMPLEX(8) :: ALPHA
```

```
COMPLEX(8), DIMENSION(:, :) :: A, B, C
INTEGER(8) :: N, K, LDA, LDB, LDC
REAL(8) :: BETA
```

C INTERFACE

```
#include <sunperf.h>
void zher2k(char uplo, char transa, int n, int k, doublecomplex
    *alpha, doublecomplex *a, int lda, doublecomplex
    *b, int ldb, double beta, doublecomplex *c,
    int ldc);

void zher2k_64(char uplo, char transa, long n, long k, doublecomplex
    *alpha, doublecomplex *a, long lda,
    doublecomplex *b, long ldb, double beta, doublecomplex
    *c, long ldc);
```

PURPOSE

zher2k performs one of the Hermitian rank 2k operations $C := \alpha A \text{conjg}(B') + \text{conjg}(\alpha) B \text{conjg}(A') + \beta C$ or $C := \alpha \text{conjg}(A') B + \text{conjg}(\alpha) \text{conjg}(B') A + \beta C$ where α and β are scalars with β real, C is an n by n Hermitian matrix and A and B are n by k matrices in the first case and k by n matrices in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A \text{conjg}(B') + \text{conjg}(\alpha) B \text{conjg}(A') + \beta C$.

TRANSA = 'C' or 'c' $C := \alpha \text{conjg}(A') B + \text{conjg}(\alpha) \text{conjg}(B') A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C.

N must be at least zero. Unchanged on exit.

K (input)

On entry with `TRANSA = 'N' or 'n'`, K specifies the number of columns of the matrices A and B, and on entry with `TRANSA = 'C' or 'c'`, K specifies the number of rows of the matrices A and B. K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

A (input)

COMPLEX*16 array of DIMENSION (LDA, ka), where ka is k when `TRANSA = 'N' or 'n'`, and is n otherwise. Before entry with `TRANSA = 'N' or 'n'`, the leading n by k part of the array A must contain the matrix A, otherwise the leading k by n part of the array A must contain the matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When `TRANSA = 'N' or 'n'` then LDA must be at least $\max(1, n)$, otherwise LDA must be at least $\max(1, k)$. Unchanged on exit.

B (input)

COMPLEX*16 array of DIMENSION (LDB, kb), where kb is k when `TRANSA = 'N' or 'n'`, and is n otherwise. Before entry with `TRANSA = 'N' or 'n'`, the leading n by k part of the array B must contain the matrix B, otherwise the leading k by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. When `TRANSA = 'N' or 'n'` then LDB must be at least $\max(1, n)$, otherwise LDB must be at least $\max(1, k)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. Unchanged on exit.

C (input/output)

COMPLEX*16 array of DIMENSION (LDC, n).

Before entry with `UPLO = 'U' or 'u'`, the leading n by n upper triangular part of the array C must contain the upper triangular part of the Hermitian matrix and the strictly lower triangular part of C is not referenced. On exit, the upper triangular part of the array C is overwritten by the upper triangular part of the updated matrix.

Before entry with `UPLO = 'L' or 'l'`, the leading `n` by `n` lower triangular part of the array `C` must contain the lower triangular part of the Hermitian matrix and the strictly upper triangular part of `C` is not referenced. On exit, the lower triangular part of the array `C` is overwritten by the lower triangular part of the updated matrix.

Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

LDC (input)

On entry, LDC specifies the first dimension of `C` as declared in the calling (sub) program. LDC must be at least $\max(1, n)$. Unchanged on exit.

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NAME

zherfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZHERFS(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB, X,  
  LDY, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDY,*),  
WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDY, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZHERFS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,  
  X, LDY, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDY,*),  
WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDY, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HERFS(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT, B,  
  [LDB], X, [LDY], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDY, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE HERFS_64(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], IPIVOT,  
  B, [LDB], X, [LDY], FERR, BERR, [WORK], [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zherfs(char uplo, int n, int nrhs, doublecomplex *a,
            int lda, doublecomplex *af, int ldaf, int *ipivot,
            doublecomplex *b, int ldb, doublecomplex *x, int
            ldx, double *ferr, double *berr, int *info);

void zherfs_64(char uplo, long n, long nrhs, doublecomplex
              *a, long lda, doublecomplex *af, long ldaf, long
              *ipivot, doublecomplex *b, long ldb, doublecomplex
              *x, long ldx, double *ferr, double *berr, long
              *info);

```

PURPOSE

zherfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)
 The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factori-

zation $A = U^*D*U^{**H}$ or $A = L*D*L^{**H}$ as computed by ZHETRF.

LDAF (input)

The leading dimension of the array AF. LDAF \geq max(1,N).

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by ZHETRF.

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)

On entry, the solution matrix X, as computed by ZHETRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zherk - perform one of the Hermitian rank k operations C
:= alpha*A*conjg(A') + beta*C or C := alpha*conjg(A')*A
+ beta*C

SYNOPSIS

```
SUBROUTINE ZHERK(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
DOUBLE COMPLEX A(LDA,*), C(LDC,*)  
INTEGER N, K, LDA, LDC  
DOUBLE PRECISION ALPHA, BETA
```

```
SUBROUTINE ZHERK_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
DOUBLE COMPLEX A(LDA,*), C(LDC,*)  
INTEGER*8 N, K, LDA, LDC  
DOUBLE PRECISION ALPHA, BETA
```

F95 INTERFACE

```
SUBROUTINE HERK(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA, C,  
[LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
COMPLEX(8), DIMENSION(:,*) :: A, C  
INTEGER :: N, K, LDA, LDC  
REAL(8) :: ALPHA, BETA
```

```
SUBROUTINE HERK_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA,  
C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
COMPLEX(8), DIMENSION(:,*) :: A, C  
INTEGER(8) :: N, K, LDA, LDC  
REAL(8) :: ALPHA, BETA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zherk(char uplo, char transa, int n, int k, double
alpha, doublecomplex *a, int lda, double beta,
doublecomplex *c, int ldc);
```

```
void zherk_64(char uplo, char transa, long n, long k, double
alpha, doublecomplex *a, long lda, double beta,
doublecomplex *c, long ldc);
```

PURPOSE

zherk performs one of the Hermitian rank k operations $C := \alpha A \text{conjg}(A') + \beta C$ or $C := \alpha \text{conjg}(A') A + \beta C$ where α and β are real scalars, C is an n by n Hermitian matrix and A is an n by k matrix in the first case and a k by n matrix in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A \text{conjg}(A') + \beta C$.

TRANSA = 'C' or 'c' $C := \alpha \text{conjg}(A') A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C. N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrix A, and on entry with TRANSA = 'C' or 'c', K specifies the number of rows of the matrix A. K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

A (input)

COMPLEX*16 array of DIMENSION (LDA, ka),
where ka is k when TRANSA = 'N' or 'n', and is
n otherwise. Before entry with TRANSA = 'N' or
'n', the leading n by k part of the array A
must contain the matrix A, otherwise the leading
k by n part of the array A must contain the
matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A
as declared in the calling (sub) program.
When TRANSA = 'N' or 'n' then LDA must be at
least max(1, n), otherwise LDA must be at
least max(1, k). Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta.
Unchanged on exit.

C (input/output)

COMPLEX*16 array of DIMENSION (LDC, n).

Before entry with UPLO = 'U' or 'u', the lead-
ing n by n upper triangular part of the array C
must contain the upper triangular part of the
Hermitian matrix and the strictly lower triangu-
lar part of C is not referenced. On exit, the
upper triangular part of the array C is overwrit-
ten by the upper triangular part of the updated
matrix.

Before entry with UPLO = 'L' or 'l', the lead-
ing n by n lower triangular part of the array C
must contain the lower triangular part of the
Hermitian matrix and the strictly upper triangu-
lar part of C is not referenced. On exit, the
lower triangular part of the array C is overwrit-
ten by the lower triangular part of the updated
matrix.

Note that the imaginary parts of the diagonal ele-
ments need not be set, they are assumed to be
zero, and on exit they are set to zero.

LDC (input)

On entry, LDC specifies the first dimension of C
as declared in the calling (sub) program.
LDC must be at least max(1, n). Unchanged
on exit.

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NAME

zhesv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZHESV(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK, LDWORK,
                INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER N, NRHS, LDA, LDB, LDWORK, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZHESV_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK,
                  LDWORK, INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER*8 N, NRHS, LDA, LDB, LDWORK, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HESV(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],
               [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B
INTEGER :: N, NRHS, LDA, LDB, LDWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HESV_64(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],
                  [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B
INTEGER(8) :: N, NRHS, LDA, LDB, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void zhesv(char uplo, int n, int nrhs, doublecomplex *a, int
           lda, int *ipivot, doublecomplex *b, int ldb, int
           *info);
void zhesv_64(char uplo, long n, long nrhs, doublecomplex
              *a, long lda, long *ipivot, doublecomplex *b, long
              ldb, long *info);
```

PURPOSE

zhesv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N Hermitian matrix and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{*H}$, if UPLO = 'U', or

$A = L * D * L^{*H}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U * D * U^{*H}$ or $A = L * D * L^{*H}$ as computed by ZHETRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D , as determined by ZHETRF. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B .
On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LDWORK$.

LDWORK (input)

The length of $WORK$. $LDWORK \geq 1$, and for best performance $LDWORK \geq N*NB$, where NB is the optimal blocksize for ZHETRF.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $WORK$ array, returns this value as the first entry of the $WORK$ array, and no error message related to $LDWORK$ is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

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NAME

zhesvx - use the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZHESVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,
  LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZHESVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT,
  B, LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HESVX(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],
  IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK],
  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```

SUBROUTINE HESVX_64(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],
    IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK],
    [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhesvx(char fact, char uplo, int n, int nrhs, doublecomplex *a, int lda, doublecomplex *af, int ldaf, int *ipivot, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *rcond, double *ferr, double *berr, int *info);

```

```

void zhesvx_64(char fact, char uplo, long n, long nrhs, doublecomplex *a, long lda, doublecomplex *af, long ldaf, long *ipivot, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zhesvx uses the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$, where A is an N -by- N Hermitian matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the diagonal pivoting method is used to factor A .

The form of the factorization is

$A = U * D * U^{*H}$, if $UPLO = 'U'$, or

$A = L * D * L^{*H}$, if $UPLO = 'L'$,

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices, and D is Hermitian and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. A, AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U^*D U^*H$ or $A = L^*D L^*H$ as computed by ZHETRF.

If FACT = 'N', then AF is an output argument and on exit returns the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U^*D U^*H$ or $A = L^*D L^*H$.

LDAF (input)
The leading dimension of the array AF. LDAF \geq max(1,N).

IPIVOT (input or output)
If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by ZHETRF. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

If FACT = 'N', then IPIVOT is an output argument and on exit contains details of the interchanges and the block structure of D, as determined by ZHETRF.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (output)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)
The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
The length of WORK. LDWORK $\geq 2*N$, and for best performance LDWORK $\geq N*NB$, where NB is the optimal blocksize for ZHETRF.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

zhetf2 - compute the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE ZHETF2(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE ZHETF2_64(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE HETF2(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE HETF2_64(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhetf2(char uplo, int n, doublecomplex *a, int lda, int
```

```

        *ipiv, int *info);

void zhetf2_64(char uplo, long n, doublecomplex *a, long
        lda, long *ipiv, long *info);

```

PURPOSE

zhetf2 computes the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U' \quad \text{or} \quad A = L^*D^*L'$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, U' is the conjugate transpose of U, and D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the Hermitian matrix A is stored:

= 'U': Upper triangular
 = 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading n-by-n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n-by-n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIV (output)

Details of the interchanges and the block structure of D. If IPIV(k) > 0, then rows and columns k and IPIV(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIV(k) = IPIV(k-1) < 0, then rows and columns k-1 and -IPIV(k) were interchanged and D(k-1:k, k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIV(k) = IPIV(k+1) < 0, then rows and columns k+1 and

-IPIV(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

INFO (output)

= 0: successful exit
 < 0: if INFO = -k, the k-th argument had an illegal value
 > 0: if INFO = k, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

1-96 - Based on modifications by

J. Lewis, Boeing Computer Services Company

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

zhetrd - reduce a complex Hermitian matrix A to real symmetric tridiagonal form T by a unitary similarity transformation

SYNOPSIS

```
SUBROUTINE ZHETRD(UPLO, N, A, LDA, D, E, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER N, LDA, LWORK, INFO  
DOUBLE PRECISION D(*), E(*)
```

```
SUBROUTINE ZHETRD_64(UPLO, N, A, LDA, D, E, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 N, LDA, LWORK, INFO  
DOUBLE PRECISION D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE HETRD(UPLO, [N], A, [LDA], D, E, TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: D, E
```

```
SUBROUTINE HETRD_64(UPLO, [N], A, [LDA], D, E, TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, LWORK, INFO  
REAL(8), DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>

void zhetrd(char uplo, int n, doublecomplex *a, int lda,
            double *d, double *e, doublecomplex *tau, int
            *info);
void zhetrd_64(char uplo, long n, doublecomplex *a, long
               lda, double *d, double *e, doublecomplex *tau,
               long *info);
```

PURPOSE

zhetrd reduces a complex Hermitian matrix A to real symmetric tridiagonal form T by a unitary similarity transformation: $Q^*H * A * Q = T$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors. See Further Details.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

D (output)

The diagonal elements of the tridiagonal matrix T:
 $D(i) = A(i, i)$.

E (output)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i, i+1)$ if UPLO = 'U', $E(i) =$

A(i+1,i) if UPLO = 'L'.

TAU (output)

The scalar factors of the elementary reflectors
(see Further Details).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal
LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq 1. For
optimum performance LWORK \geq N*NB, where NB is the
optimal blocksize.

If LWORK = -1, then a workspace query is assumed;
the routine only calculates the optimal size of
the WORK array, returns this value as the first
entry of the WORK array, and no error message
related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of
elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector
with $v(i+1:n) = 0$ and $v(i) = 1$; $v(1:i-1)$ is stored on exit
in
A(1:i-1,i+1), and tau in TAU(i).

If UPLO = 'L', the matrix Q is represented as a product of
elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector
with $v(1:i) = 0$ and $v(i+1) = 1$; $v(i+2:n)$ is stored on exit
in A(i+2:n,i), and tau in TAU(i).

The contents of A on exit are illustrated by the following
examples with n = 5:

if UPLO = 'U':

(d e v2 v3 v4)

if UPLO = 'L':

(d

$$\begin{array}{l}
) \\
 (\quad d \quad e \quad v_3 \quad v_4 \quad) \quad \quad \quad (\quad e \quad d \\
) \\
 (\quad \quad d \quad e \quad v_4 \quad) \quad \quad \quad (\quad v_1 \quad e \quad d \\
) \\
 (\quad \quad \quad d \quad e \quad) \quad \quad \quad (\quad v_1 \quad v_2 \quad e \quad d \\
) \\
 (\quad \quad \quad \quad d \quad) \quad \quad \quad (\quad v_1 \quad v_2 \quad v_3 \quad e \quad d \\
)
 \end{array}$$

where d and e denote diagonal and off-diagonal elements of T , and v_i denotes an element of the vector defining $H(i)$.

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NAME

zhetrf - compute the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE ZHETRF(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, LDWORK, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZHETRF_64(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, LDWORK, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HETRF(UPLO, [N], A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HETRF_64(UPLO, [N], A, [LDA], IPIVOT, [WORK], [LDWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void zhtrf(char uplo, int n, doublecomplex *a, int lda, int
           *ipivot, int *info);

void zhtrf_64(char uplo, long n, doublecomplex *a, long
              lda, long *ipivot, long *info);
```

PURPOSE

zhtrf computes the factorization of a complex Hermitian matrix A using the Bunch-Kaufman diagonal pivoting method. The form of the factorization is

$$A = U^*D^*U^{*H} \quad \text{or} \quad A = L^*D^*L^{*H}$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. N >= 0.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. LDA >= max(1,N).

IPIVOT (output)

Details of the interchanges and the block structure of D. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and

$D(k-1:k, k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1, k:k+1)$ is a 2-by-2 diagonal block.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LDWORK$.

LDWORK (input)

The length of WORK. $LDWORK \geq 1$. For best performance $LDWORK \geq N * NB$, where NB is the block size returned by $ILAENV$.

INFO (output)

= 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value
 > 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

If $UPLO = 'U'$, then $A = U * D * U'$, where

$U = P(n) * U(n) * \dots * P(k) * U(k) * \dots$,
 i.e., U is a product of terms $P(k) * U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by $IPIVOT(k)$, and $U(k)$ is a unit upper triangular matrix, such that if the diagonal block $D(k)$ is of order s ($s = 1$ or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(1:k-1, k)$. If $s = 2$, the upper triangle of $D(k)$ overwrites $A(k-1, k-1)$, $A(k-1, k)$, and $A(k, k)$, and v overwrites $A(1:k-2, k-1:k)$.

If $UPLO = 'L'$, then $A = L * D * L'$, where

$L = P(1) * L(1) * \dots * P(k) * L(k) * \dots$,
 i.e., L is a product of terms $P(k) * L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by $IPIVOT(k)$, and $L(k)$ is a unit lower triangular matrix, such that if the diagonal block $D(k)$ is of order s ($s = 1$ or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(k+1:n,k)$. If $s = 2$, the lower triangle of $D(k)$ overwrites $A(k,k)$, $A(k+1,k)$, and $A(k+1,k+1)$, and v overwrites $A(k+2:n,k:k+1)$.

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NAME

zhetri - compute the inverse of a complex Hermitian indefinite matrix A using the factorization $A = U*D*U^*H$ or $A = L*D*L^*H$ computed by ZHETRF

SYNOPSIS

```
SUBROUTINE ZHETRI(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZHETRI_64(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HETRI(UPLO, [N], A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HETRI_64(UPLO, [N], A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,) :: A  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhetri(char uplo, int n, doublecomplex *a, int lda, int
            *ipivot, int *info);

void zhetri_64(char uplo, long n, doublecomplex *a, long
               lda, long *ipivot, long *info);

```

PURPOSE

zhetri computes the inverse of a complex Hermitian indefinite matrix A using the factorization $A = U*D*U**H$ or $A = L*D*L**H$ computed by ZHETRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U*D*U**H$;
 = 'L': Lower triangular, form is $A = L*D*L**H$.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZHETRF.

On exit, if INFO = 0, the (Hermitian) inverse of the original matrix. If UPLO = 'U', the upper triangular part of the inverse is formed and the part of A below the diagonal is not referenced; if UPLO = 'L' the lower triangular part of the inverse is formed and the part of A above the diagonal is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by ZHETRF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

zhetrz - solve a system of linear equations $A \cdot X = B$ with a complex Hermitian matrix A using the factorization $A = U \cdot D \cdot U^* \cdot H$ or $A = L \cdot D \cdot L^* \cdot H$ computed by ZHETRF

SYNOPSIS

```
SUBROUTINE ZHETRS(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZHETRS_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HETRS(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HETRS_64(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhetrz(char uplo, int n, int nrhs, doublecomplex *a,
```

```

        int lda, int *ipivot, doublecomplex *b, int ldb,
        int *info);

void zhetrs_64(char uplo, long n, long nrhs, doublecomplex
        *a, long lda, long *ipivot, doublecomplex *b, long
        ldb, long *info);

```

PURPOSE

zhetrs solves a system of linear equations $A \cdot X = B$ with a complex Hermitian matrix A using the factorization $A = U \cdot D \cdot U^* \cdot H$ or $A = L \cdot D \cdot L^* \cdot H$ computed by ZHETRF.

ARGUMENTS

UPLO (input)
 Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U \cdot D \cdot U^* \cdot H$;
 = 'L': Lower triangular, form is $A = L \cdot D \cdot L^* \cdot H$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZHETRF.

LDA (input)
 The leading dimension of the array A . $LDA \geq \max(1, N)$.

IPIVOT (input)
 Details of the interchanges and the block structure of D as determined by ZHETRF.

B (input/output)
 On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)
 The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)
 = 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

zhgeqz - implement a single-shift version of the QZ method for finding the generalized eigenvalues $w(i)=\text{ALPHA}(i)/\text{BETA}(i)$ of the equation $\det(A-w(i)B) = 0$. If `JOB='S'`, then the pair (A,B) is simultaneously reduced to Schur form (i.e., A and B are both upper triangular) by applying one unitary transformation (usually called Q) on the left and another (usually called Z) on the right.

SYNOPSIS

```
SUBROUTINE ZHGEQZ(JOB, COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB,
                 ALPHA, BETA, Q, LDQ, Z, LDZ, WORK, LWORK, RWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ, COMPZ
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZHGEQZ_64(JOB, COMPQ, COMPZ, N, ILO, IHI, A, LDA, B, LDB,
                    ALPHA, BETA, Q, LDQ, Z, LDZ, WORK, LWORK, RWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ, COMPZ
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER*8 N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HGEQZ(JOB, COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B, [LDB],
                 ALPHA, BETA, Q, [LDQ], Z, [LDZ], [WORK], [LWORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ, COMPZ
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, Q, Z
INTEGER :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL(8), DIMENSION(:) :: RWORK
```

```

SUBROUTINE HGEQZ_64(JOB, COMPQ, COMPZ, [N], ILO, IHI, A, [LDA], B,
  [LDB], ALPHA, BETA, Q, [LDQ], Z, [LDZ], [WORK], [LWORK], [RWORK],
  [INFO])

```

```

CHARACTER(LEN=1) :: JOB, COMPQ, COMPZ
COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, Q, Z
INTEGER(8) :: N, ILO, IHI, LDA, LDB, LDQ, LDZ, LWORK, INFO
REAL(8), DIMENSION(:) :: RWORK

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhgeqz(char job, char compq, char compz, int n, int
  ilo, int ihi, doublecomplex *a, int lda, doub-
  lecomplex *b, int ldb, doublecomplex *alpha, doub-
  lecomplex *beta, doublecomplex *q, int ldq, doub-
  lecomplex *z, int ldz, int *info);

```

```

void zhgeqz_64(char job, char compq, char compz, long n,
  long ilo, long ihi, doublecomplex *a, long lda,
  doublecomplex *b, long ldb, doublecomplex *alpha,
  doublecomplex *beta, doublecomplex *q, long ldq,
  doublecomplex *z, long ldz, long *info);

```

PURPOSE

zhgeqz implements a single-shift version of the QZ method for finding the generalized eigenvalues $w(i)=\text{ALPHA}(i)/\text{BETA}(i)$ of the equation A are then $\text{ALPHA}(1), \dots, \text{ALPHA}(N)$, and of B are $\text{BETA}(1), \dots, \text{BETA}(N)$.

If $\text{JOB}='S'$ and COMPQ and COMPZ are 'V' or 'I', then the unitary transformations used to reduce (A,B) are accumulated into the arrays Q and Z s.t.:

(in) $A(\text{in}) Z(\text{in})^* = Q(\text{out}) A(\text{out}) Z(\text{out})^*$

Ref: C.B. Moler & G.W. Stewart, "An Algorithm for Generalized Matrix Eigenvalue Problems", SIAM J. Numer. Anal., 10(1973), p. 241--256.

ARGUMENTS

JOB (input)

= 'E': compute only ALPHA and BETA. A and B will not necessarily be put into generalized Schur form. = 'S': put A and B into generalized Schur form, as well as computing ALPHA and BETA.

COMPQ (input)

= 'N': do not modify Q.
 = 'V': multiply the array Q on the right by the conjugate transpose of the unitary transformation that is applied to the left side of A and B to reduce them to Schur form. = 'I': like $\text{COMPQ}='V'$, except that Q will be initialized to the identity first.

COMPZ (input)
 = 'N': do not modify Z.
 = 'V': multiply the array Z on the right by the unitary transformation that is applied to the right side of A and B to reduce them to Schur form.
 = 'I': like COMPZ='V', except that Z will be initialized to the identity first.

N (input) The order of the matrices A, B, Q, and Z. $N \geq 0$.

ILO (input)
 It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)
 It is assumed that A is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

A (input) On entry, the N-by-N upper Hessenberg matrix A. Elements below the subdiagonal must be zero. If JOB='S', then on exit A and B will have been simultaneously reduced to upper triangular form. If JOB='E', then on exit A will have been destroyed.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input) On entry, the N-by-N upper triangular matrix B. Elements below the diagonal must be zero. If JOB='S', then on exit A and B will have been simultaneously reduced to upper triangular form. If JOB='E', then on exit B will have been destroyed.

LDB (input)
 The leading dimension of the array B. $LDB \geq \max(1, N)$.

ALPHA (output)
 The diagonal elements of A when the pair (A,B) has been reduced to Schur form. ALPHA(i)/BETA(i) $i=1, \dots, N$ are the generalized eigenvalues.

BETA (output)
 The diagonal elements of B when the pair (A,B) has been reduced to Schur form. ALPHA(i)/BETA(i) $i=1, \dots, N$ are the generalized eigenvalues. A and B are normalized so that BETA(1), ..., BETA(N) are non-negative real numbers.

Q (input/output)
 If COMPQ='N', then Q will not be referenced. If COMPQ='V' or 'I', then the conjugate transpose of the unitary transformations which are applied to A and B on the left will be applied to the array Q on the right.

LDQ (input)
 The leading dimension of the array Q. LDQ \geq 1.
 If COMPQ='V' or 'I', then LDQ \geq N.

Z (input/output)
 If COMPZ='N', then Z will not be referenced. If
 COMPZ='V' or 'I', then the unitary transformations
 which are applied to A and B on the right will be
 applied to the array Z on the right.

LDZ (input)
 The leading dimension of the array Z. LDZ \geq 1.
 If COMPZ='V' or 'I', then LDZ \geq N.

WORK (workspace)
 On exit, if INFO \geq 0, WORK(1) returns the optimal
 LWORK.

LWORK (input)
 The dimension of the array WORK. LWORK \geq
 max(1,N).

If LWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the WORK array, returns this value as the first
 entry of the WORK array, and no error message
 related to LWORK is issued by XERBLA.

RWORK (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-
 gal value
 = 1,...,N: the QZ iteration did not converge.
 (A,B) is not in Schur form, but ALPHA(i) and
 BETA(i), i=INFO+1,...,N should be correct. =
 N+1,...,2*N: the shift calculation failed. (A,B)
 is not in Schur form, but ALPHA(i) and BETA(i),
 i=INFO-N+1,...,N should be correct. > 2*N:
 various "impossible" errors.

FURTHER DETAILS

We assume that complex ABS works as long as its value is
 less than overflow.

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NAME

zhpcn - estimate the reciprocal of the condition number of a complex Hermitian packed matrix A using the factorization $A = U^*D^*U^*H$ or $A = L^*D^*L^*H$ computed by ZHPTRF

SYNOPSIS

```
SUBROUTINE ZHPCON(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION ANORM, RCOND
```

```
SUBROUTINE ZHPCON_64(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE HPCON(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8) :: ANORM, RCOND
```

```
SUBROUTINE HPCON_64(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8) :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>

void zhpcon(char uplo, int n, doublecomplex *a, int *ipivot,
            double anorm, double *rcond, int *info);

void zhpcon_64(char uplo, long n, doublecomplex *a, long
               *ipivot, double anorm, double *rcond, long *info);
```

PURPOSE

zhpcon estimates the reciprocal of the condition number of a complex Hermitian packed matrix A using the factorization $A = U^*D*U^{**H}$ or $A = L^*D*L^{**H}$ computed by ZHPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
 Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U^*D*U^{**H}$;
 = 'L': Lower triangular, form is $A = L^*D*L^{**H}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$
 The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZHPTRF, stored as a packed triangular matrix.

IPIVOT (input) INTEGER array, dimension (N)
 Details of the interchanges and the block structure of D as determined by ZHPTRF.

ANORM (input)
 The 1-norm of the original matrix A.

RCOND (output)
 The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)
 COMPLEX*16 array, dimension $(2*N)$

INFO (output)
 = 0: successful exit
 < 0: if $\text{INFO} = -i$, the i-th argument had an illegal value

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NAME

zhpev - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix in packed storage

SYNOPSIS

```
SUBROUTINE ZHPEV(JOBZ, UPLO, N, A, W, Z, LDZ, WORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX A(*), Z(LDZ,*), WORK(*)  
INTEGER N, LDZ, INFO  
DOUBLE PRECISION W(*), WORK2(*)
```

```
SUBROUTINE ZHPEV_64(JOBZ, UPLO, N, A, W, Z, LDZ, WORK, WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX A(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDZ, INFO  
DOUBLE PRECISION W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPEV(JOBZ, UPLO, [N], A, W, Z, [LDZ], [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
COMPLEX(8), DIMENSION(:,) :: Z  
INTEGER :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HPEV_64(JOBZ, UPLO, [N], A, W, Z, [LDZ], [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
COMPLEX(8), DIMENSION(:,) :: Z  
INTEGER(8) :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhpev(char jobz, char uplo, int n, doublecomplex *a,
           double *w, doublecomplex *z, int ldz, int *info);

void zhpev_64(char jobz, char uplo, long n, doublecomplex
              *a, double *w, doublecomplex *z, long ldz, long
              *info);

```

PURPOSE

zhpev computes all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix in packed storage.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$
 On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.
 On exit, A is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

W (output) DOUBLE PRECISION array, dimension (N)
 If INFO = 0, the eigenvalues in ascending order.

Z (input) COMPLEX*16 array, dimension (LDZ, N)
 If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with $W(i)$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace)
 COMPLEX*16 array, dimension $(\max(1, 2*N-1))$

WORK2 (workspace)
DOUBLE PRECISION array, dimension(max(1,3*N-2))

INFO (output)
= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

zhpevd - compute all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage

SYNOPSIS

```
SUBROUTINE ZHPEVD(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, LWORK, RWORK,  
  LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AP(*), Z(LDZ,*), WORK(*)  
INTEGER N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHPEVD_64(JOBZ, UPLO, N, AP, W, Z, LDZ, WORK, LWORK,  
  RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AP(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HPEVD(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [LWORK],  
  [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: AP, WORK  
COMPLEX(8), DIMENSION(:, :) :: Z  
INTEGER :: N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HPEVD_64(JOBZ, UPLO, [N], AP, W, Z, [LDZ], [WORK], [LWORK],  
  [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: AP, WORK  
COMPLEX(8), DIMENSION(:, :) :: Z
```

```
INTEGER(8) :: N, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: W, RWORK
```

C INTERFACE

```
#include <sunperf.h>
void zhpevd(char jobz, char uplo, int n, doublecomplex *ap,
            double *w, doublecomplex *z, int ldz, int *info);

void zhpevd_64(char jobz, char uplo, long n, doublecomplex
              *ap, double *w, doublecomplex *z, long ldz, long
              *info);
```

PURPOSE

zhpevd computes all the eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage. If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$
On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, AP is overwritten by values generated during the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

W (output) DOUBLE PRECISION array, dimension (N)
 If INFO = 0, the eigenvalues in ascending order.

Z (input) COMPLEX*16 array, dimension (LDZ, N)
 If JOBZ = 'V', then if INFO = 0, Z contains the orthonormal eigenvectors of the matrix A, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

WORK (workspace) COMPLEX*16 array, dimension (LWORK)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of array WORK. If N <= 1, LWORK must be at least 1. If JOBZ = 'N' and N > 1, LWORK must be at least N. If JOBZ = 'V' and N > 1, LWORK must be at least 2*N.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)
 DOUBLE PRECISION array, dimension (LRWORK) On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)
 The dimension of array RWORK. If N <= 1, LRWORK must be at least 1. If JOBZ = 'N' and N > 1, LRWORK must be at least N. If JOBZ = 'V' and N > 1, LRWORK must be at least 1 + 5*N + 2*N**2.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output) INTEGER array, dimension (LIWORK)
 On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
 The dimension of array IWORK. If JOBZ = 'N' or N <= 1, LIWORK must be at least 1. If JOBZ = 'V' and N > 1, LIWORK must be at least 3 + 5*N.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the algorithm failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

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NAME

zhpevx - compute selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage

SYNOPSIS

```
SUBROUTINE ZHPEVX(JOBZ, RANGE, UPLO, N, A, VL, VU, IL, IU, ABTOL,  
                 NFOUND, W, Z, LDZ, WORK, WORK2, IWORK3, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO  
DOUBLE COMPLEX A(*), Z(LDZ,*), WORK(*)  
INTEGER N, IL, IU, NFOUND, LDZ, INFO  
INTEGER IWORK3(*), IFAIL(*)  
DOUBLE PRECISION VL, VU, ABTOL  
DOUBLE PRECISION W(*), WORK2(*)
```

```
SUBROUTINE ZHPEVX_64(JOBZ, RANGE, UPLO, N, A, VL, VU, IL, IU, ABTOL,  
                   NFOUND, W, Z, LDZ, WORK, WORK2, IWORK3, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO  
DOUBLE COMPLEX A(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, IL, IU, NFOUND, LDZ, INFO  
INTEGER*8 IWORK3(*), IFAIL(*)  
DOUBLE PRECISION VL, VU, ABTOL  
DOUBLE PRECISION W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPEVX(JOBZ, RANGE, UPLO, [N], A, VL, VU, IL, IU, ABTOL,  
                [NFOUND], W, Z, [LDZ], [WORK], [WORK2], [IWORK3], IFAIL, [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
COMPLEX(8), DIMENSION(:, :) :: Z  
INTEGER :: N, IL, IU, NFOUND, LDZ, INFO  
INTEGER, DIMENSION(:) :: IWORK3, IFAIL  
REAL(8) :: VL, VU, ABTOL  
REAL(8), DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HPEVX_64(JOBZ, RANGE, UPLO, [N], A, VL, VU, IL, IU, ABTOL,  
                   [NFOUND], W, Z, [LDZ], [WORK], [WORK2], [IWORK3], IFAIL, [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: A, WORK
COMPLEX(8), DIMENSION(:, :) :: Z
INTEGER(8) :: N, IL, IU, NFOUND, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK3, IFAIL
REAL(8) :: VL, VU, ABTOL
REAL(8), DIMENSION(:) :: W, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zhpevx(char jobz, char range, char uplo, int n, doublecomplex
 *a, double vl, double vu, int il, int iu, double abtol, int *nfound, double
 *w, doublecomplex *z, int ldz, int *ifail, int *info);

void zhpevx_64(char jobz, char range, char uplo, long n, doublecomplex
 *a, double vl, double vu, long il, long iu, double abtol, long *nfound, double
 *w, doublecomplex *z, long ldz, long *ifail, long *info);

```

PURPOSE

zhpevx computes selected eigenvalues and, optionally, eigenvectors of a complex Hermitian matrix A in packed storage. Eigenvalues/vectors can be selected by specifying either a range of values or a range of indices for the desired eigenvalues.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;
 = 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
 = 'A': all eigenvalues will be found;
 = 'V': all eigenvalues in the half-open interval (VL,VU] will be found; = 'I': the IL-th through IU-th eigenvalues will be found.

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$
 On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i, j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i, j)$ for $j \leq i \leq n$.
 On exit, A is overwritten by values generated dur-

ing the reduction to tridiagonal form. If UPLO = 'U', the diagonal and first superdiagonal of the tridiagonal matrix T overwrite the corresponding elements of A, and if UPLO = 'L', the diagonal and first subdiagonal of T overwrite the corresponding elements of A.

VL (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

VU (input)

If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. VL < VU. Not referenced if RANGE = 'A' or 'I'.

IL (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)

If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABTOL (input)

The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABTOL is less than or equal to zero, then $EPS*|T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing A to tridiagonal form.

Eigenvalues will be computed most accurately when ABTOL is set to twice the underflow threshold $2*SLAMCH('S')$, not zero. If this routine returns with INFO>0, indicating that some eigenvectors did not converge, try setting ABTOL to $2*SLAMCH('S')$.

See "Computing Small Singular Values of Bidiagonal Matrices with Guaranteed High Relative Accuracy," by Demmel and Kahan, LAPACK Working Note #3.

NFOUND (output)

The total number of eigenvalues found. $0 \leq NFOUND \leq N$. If RANGE = 'A', $NFOUND = N$, and if RANGE = 'I', $NFOUND = IU - IL + 1$.

W (output) DOUBLE PRECISION array, dimension (N)

If INFO = 0, the selected eigenvalues in ascending order.

Z (input) COMPLEX*16 array, dimension (LDZ, max(1,M))
If JOBZ = 'V', then if INFO = 0, the first NFOUND columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least max(1,NFOUND) columns are supplied in the array Z; if RANGE = 'V', the exact value of NFOUND is not known in advance and an upper bound must be used.

LDZ (input)
The leading dimension of the array Z. LDZ >= 1, and if JOBZ = 'V', LDZ >= max(1,N).

WORK (workspace)
COMPLEX*16 array, dimension(2*N)

WORK2 (workspace)
DOUBLE PRECISION array, dimension(7*N)

IWORK3 (workspace)
INTEGER array, dimension(5*N)

IFAIL (output) INTEGER array, dimension (N)
If JOBZ = 'V', then if INFO = 0, the first NFOUND elements of IFAIL are zero. If INFO > 0, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, then i eigenvectors failed to converge. Their indices are stored in array IFAIL.

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NAME

zhpgst - reduce a complex Hermitian-definite generalized eigenproblem to standard form, using packed storage

SYNOPSIS

```
SUBROUTINE ZHPGST(ITYPE, UPLO, N, AP, BP, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), BP(*)  
INTEGER ITYPE, N, INFO
```

```
SUBROUTINE ZHPGST_64(ITYPE, UPLO, N, AP, BP, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), BP(*)  
INTEGER*8 ITYPE, N, INFO
```

F95 INTERFACE

```
SUBROUTINE HPGST(ITYPE, UPLO, [N], AP, BP, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP, BP  
INTEGER :: ITYPE, N, INFO
```

```
SUBROUTINE HPGST_64(ITYPE, UPLO, [N], AP, BP, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP, BP  
INTEGER(8) :: ITYPE, N, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhpgst(int itype, char uplo, int n, doublecomplex *ap,  
            doublecomplex *bp, int *info);
```

```
void zhpgst_64(long itype, char uplo, long n, doublecomplex  
               *ap, doublecomplex *bp, long *info);
```

PURPOSE

zhpgst reduces a complex Hermitian-definite generalized eigenproblem to standard form, using packed storage.

If $ITYPE = 1$, the problem is $A*x = \lambda*B*x$, and A is overwritten by $\text{inv}(U^{**H})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{**H})$

If $ITYPE = 2$ or 3 , the problem is $A*B*x = \lambda*x$ or $B*A*x = \lambda*x$, and A is overwritten by $U*A*U^{**H}$ or $L^{**H}*A*L$.

B must have been previously factorized as $U^{**H}*U$ or $L*L^{**H}$ by `CPPTRF`.

ARGUMENTS

`ITYPE` (input)
= 1: compute $\text{inv}(U^{**H})*A*\text{inv}(U)$ or $\text{inv}(L)*A*\text{inv}(L^{**H})$;
= 2 or 3: compute $U*A*U^{**H}$ or $L^{**H}*A*L$.

`UPLO` (input)
= 'U': Upper triangle of A is stored and B is factored as $U^{**H}*U$; = 'L': Lower triangle of A is stored and B is factored as $L*L^{**H}$.

`N` (input) The order of the matrices A and B . $N \geq 0$.

`AP` (input/output) `COMPLEX*16` array, dimension $(N*(N+1)/2)$
On entry, the upper or lower triangle of the Hermitian matrix A , packed columnwise in a linear array. The j -th column of A is stored in the array `AP` as follows: if `UPLO = 'U'`, $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if `UPLO = 'L'`, $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, if `INFO = 0`, the transformed matrix, stored in the same format as A .

`BP` (input) `COMPLEX*16` array, dimension $(N*(N+1)/2)$
The triangular factor from the Cholesky factorization of B , stored in the same format as A , as returned by `CPPTRF`.

`INFO` (output)
= 0: successful exit
< 0: if `INFO = -i`, the i -th argument had an illegal value

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NAME

zhpgv - compute all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*Bx=(\lambda)x$, or $B*A*x=(\lambda)x$

SYNOPSIS

```
SUBROUTINE ZHPGV(ITYPE, JOBZ, UPLO, N, A, B, W, Z, LDZ, WORK, WORK2,
                INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
DOUBLE COMPLEX A(*), B(*), Z(LDZ,*), WORK(*)
INTEGER ITYPE, N, LDZ, INFO
DOUBLE PRECISION W(*), WORK2(*)
```

```
SUBROUTINE ZHPGV_64(ITYPE, JOBZ, UPLO, N, A, B, W, Z, LDZ, WORK,
                   WORK2, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO
DOUBLE COMPLEX A(*), B(*), Z(LDZ,*), WORK(*)
INTEGER*8 ITYPE, N, LDZ, INFO
DOUBLE PRECISION W(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPGV(ITYPE, JOBZ, UPLO, [N], A, B, W, Z, [LDZ], [WORK],
               [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX(8), DIMENSION(:) :: A, B, WORK
COMPLEX(8), DIMENSION(:, :) :: Z
INTEGER :: ITYPE, N, LDZ, INFO
REAL(8), DIMENSION(:) :: W, WORK2
```

```
SUBROUTINE HPGV_64(ITYPE, JOBZ, UPLO, [N], A, B, W, Z, [LDZ], [WORK],
                  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX(8), DIMENSION(:) :: A, B, WORK
COMPLEX(8), DIMENSION(:, :) :: Z
INTEGER(8) :: ITYPE, N, LDZ, INFO
```

```
REAL(8), DIMENSION(:) :: W, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhpgv(int itype, char jobz, char uplo, int n, doublecomplex *a, doublecomplex *b, double *w, doublecomplex *z, int ldz, int *info);
```

```
void zhpgv_64(long itype, char jobz, char uplo, long n, doublecomplex *a, doublecomplex *b, double *w, doublecomplex *z, long ldz, long *info);
```

PURPOSE

zhpgv computes all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*B*x=(\lambda)x$, or $B*A*x=(\lambda)x$. Here A and B are assumed to be Hermitian, stored in packed format, and B is also positive definite.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)B*x$
- = 2: $A*B*x = (\lambda)x$
- = 3: $B*A*x = (\lambda)x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

- = 'U': Upper triangles of A and B are stored;
- = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of A are destroyed.

B (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array B as follows: if UPLO = 'U', $B(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $B(i +$

$(j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U^*H*U$ or $B = L*L^*H$, in the same storage format as B.

W (output) DOUBLE PRECISION array, dimension (N)
If INFO = 0, the eigenvalues in ascending order.

Z (input) COMPLEX*16 array, dimension (LDZ, N)
If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z^*H*B*Z = I$; if ITYPE = 3, $Z^*H*inv(B)*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)
The leading dimension of the array Z. LDZ \geq 1, and if JOBZ = 'V', LDZ \geq max(1,N).

WORK (workspace)
COMPLEX*16 array, dimension(MAX(1,2*N-1))

WORK2 (workspace)
DOUBLE PRECISION array, dimension(MAX(1,3*N-2))

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: CPPTRF or ZHPEV returned an error code:
<= N: if INFO = i, ZHPEV failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not converge to zero; > N: if INFO = N + i, for $1 \leq i \leq n$, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

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NAME

zhpgvd - compute all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*Bx=(\lambda)x$, or $B*A*x=(\lambda)x$

SYNOPSIS

```
SUBROUTINE ZHPGVD(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,  
                 LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AP(*), BP(*), Z(LDZ,*), WORK(*)  
INTEGER ITYPE, N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHPGVD_64(ITYPE, JOBZ, UPLO, N, AP, BP, W, Z, LDZ, WORK,  
                   LWORK, RWORK, LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, UPLO  
DOUBLE COMPLEX AP(*), BP(*), Z(LDZ,*), WORK(*)  
INTEGER*8 ITYPE, N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HPGVD(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ], [WORK],  
                [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, UPLO  
COMPLEX(8), DIMENSION(:) :: AP, BP, WORK  
COMPLEX(8), DIMENSION(:,:) :: Z  
INTEGER :: ITYPE, N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: W, RWORK
```

```
SUBROUTINE HPGVD_64(ITYPE, JOBZ, UPLO, [N], AP, BP, W, Z, [LDZ],  
                   [WORK], [LWORK], [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, UPLO
COMPLEX(8), DIMENSION(:) :: AP, BP, WORK
COMPLEX(8), DIMENSION(:, :) :: Z
INTEGER(8) :: ITYPE, N, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zhpgvd(int itype, char jobz, char uplo, int n, doublecomplex *ap, doublecomplex *bp, double *w, doublecomplex *z, int ldz, int *info);

void zhpgvd_64(long itype, char jobz, char uplo, long n, doublecomplex *ap, doublecomplex *bp, double *w, doublecomplex *z, long ldz, long *info);

```

PURPOSE

zhpgvd computes all the eigenvalues and, optionally, the eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian, stored in packed format, and B is also positive definite.

If eigenvectors are desired, it uses a divide and conquer algorithm.

The divide and conquer algorithm makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none.

ARGUMENTS

ITYPE (input)

Specifies the problem type to be solved:

- = 1: $A*x = (\lambda)*B*x$
- = 2: $A*B*x = (\lambda)*x$
- = 3: $B*A*x = (\lambda)*x$

JOBZ (input)

- = 'N': Compute eigenvalues only;
- = 'V': Compute eigenvalues and eigenvectors.

UPLO (input)

- = 'U': Upper triangles of A and B are stored;
- = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

AP (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Her-

mitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of AP are destroyed.

BP (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$
On entry, the upper or lower triangle of the Hermitian matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPLO = 'U', $BP(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $BP(i + (j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U**H*U$ or $B = L*L**H$, in the same storage format as B.

W (output) DOUBLE PRECISION array, dimension (N)
If INFO = 0, the eigenvalues in ascending order.

Z (input) COMPLEX*16 array, dimension (LDZ, N)
If JOBZ = 'V', then if INFO = 0, Z contains the matrix Z of eigenvectors. The eigenvectors are normalized as follows: if ITYPE = 1 or 2, $Z**H*B*Z = I$; if ITYPE = 3, $Z**H*inv(B)*Z = I$. If JOBZ = 'N', then Z is not referenced.

LDZ (input)
The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1,N)$.

WORK (workspace) COMPLEX*16 array, dimension (LWORK)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of array WORK. If $N \leq 1$, $LWORK \geq 1$. If JOBZ = 'N' and $N > 1$, $LWORK \geq N$. If JOBZ = 'V' and $N > 1$, $LWORK \geq 2*N$.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace) DOUBLE PRECISION array, dimension (LRWORK)
On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)
The dimension of array RWORK. If $N \leq 1$, $LRWORK \geq 1$. If JOBZ = 'N' and $N > 1$, $LRWORK \geq N$. If JOBZ = 'V' and $N > 1$, $LRWORK \geq 1 + 5*N + 2*N**2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of

the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output) INTEGER array, dimension (LIWORK)
On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)
The dimension of array IWORK. If JOBZ = 'N' or N <= 1, LIWORK >= 1. If JOBZ = 'V' and N > 1, LIWORK >= 3 + 5*N.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: CPPTRF or ZHPEVD returned an error code:
<= N: if INFO = i, ZHPEVD failed to converge; i off-diagonal elements of an intermediate tridiagonal form did not convergeto zero; > N: if INFO = N + i, for 1 <= i <= n, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by
Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

zhpgvx - compute selected eigenvalues and, optionally, eigenvectors of a complex generalized Hermitian-definite eigenproblem, of the form $A*x=(\lambda)B*x$, $A*Bx=(\lambda)x$, or $B*A*x=(\lambda)x$

SYNOPSIS

```
SUBROUTINE ZHPGVX(ITYPE, JOBZ, RANGE, UPLO, N, AP, BP, VL, VU, IL,
                 IU, ABSTOL, M, W, Z, LDZ, WORK, RWORK, IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX AP(*), BP(*), Z(LDZ,*), WORK(*)
INTEGER ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION W(*), RWORK(*)
```

```
SUBROUTINE ZHPGVX_64(ITYPE, JOBZ, RANGE, UPLO, N, AP, BP, VL, VU, IL,
                   IU, ABSTOL, M, W, Z, LDZ, WORK, RWORK, IWORK, IFAIL, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE, UPLO
DOUBLE COMPLEX AP(*), BP(*), Z(LDZ,*), WORK(*)
INTEGER*8 ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER*8 IWORK(*), IFAIL(*)
DOUBLE PRECISION VL, VU, ABSTOL
DOUBLE PRECISION W(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HPGVX(ITYPE, JOBZ, RANGE, UPLO, [N], AP, BP, VL, VU, IL,
                IU, ABSTOL, M, W, Z, [LDZ], [WORK], [RWORK], [IWORK], IFAIL,
                [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: AP, BP, WORK
COMPLEX(8), DIMENSION(:, :) :: Z
INTEGER :: ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
```

```

REAL(8), DIMENSION(:) :: W, RWORK

SUBROUTINE HPGVX_64(ITYPE, JOBZ, RANGE, UPLO, [N], AP, BP, VL, VU,
    IL, IU, ABSTOL, M, W, Z, [LDZ], [WORK], [RWORK], [IWORK], IFAIL,
    [INFO])

CHARACTER(LEN=1) :: JOBZ, RANGE, UPLO
COMPLEX(8), DIMENSION(:) :: AP, BP, WORK
COMPLEX(8), DIMENSION(:,:) :: Z
INTEGER(8) :: ITYPE, N, IL, IU, M, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IWORK, IFAIL
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: W, RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zhpgvx(int itype, char jobz, char range, char uplo, int
    n, doublecomplex *ap, doublecomplex *bp, double
    vl, double vu, int il, int iu, double abstol, int
    *m, double *w, doublecomplex *z, int ldz, int
    *ifail, int *info);

void zhpgvx_64(long itype, char jobz, char range, char uplo,
    long n, doublecomplex *ap, doublecomplex *bp, dou-
    ble vl, double vu, long il, long iu, double
    abstol, long *m, double *w, doublecomplex *z, long
    ldz, long *ifail, long *info);

```

PURPOSE

zhpgvx computes selected eigenvalues and, optionally, eigen-
vectors of a complex generalized Hermitian-definite eigen-
problem, of the form $A*x=(\lambda)*B*x$, $A*Bx=(\lambda)*x$, or
 $B*A*x=(\lambda)*x$. Here A and B are assumed to be Hermitian,
stored in packed format, and B is also positive definite.
Eigenvalues and eigenvectors can be selected by specifying
either a range of values or a range of indices for the
desired eigenvalues.

ARGUMENTS

ITYPE (input)
Specifies the problem type to be solved:
= 1: $A*x = (\lambda)*B*x$
= 2: $A*B*x = (\lambda)*x$
= 3: $B*A*x = (\lambda)*x$

JOBZ (input)
= 'N': Compute eigenvalues only;
= 'V': Compute eigenvalues and eigenvectors.

RANGE (input)
= 'A': all eigenvalues will be found;
= 'V': all eigenvalues in the half-open interval
(VL,VU] will be found; = 'I': the IL-th through

IU-th eigenvalues will be found.

UPL0 (input)
 = 'U': Upper triangles of A and B are stored;
 = 'L': Lower triangles of A and B are stored.

N (input) The order of the matrices A and B. $N \geq 0$.

AP (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$
 On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPL0 = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPL0 = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the contents of AP are destroyed.

BP (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$
 On entry, the upper or lower triangle of the Hermitian matrix B, packed columnwise in a linear array. The j-th column of B is stored in the array BP as follows: if UPL0 = 'U', $BP(i + (j-1)*j/2) = B(i,j)$ for $1 \leq i \leq j$; if UPL0 = 'L', $BP(i + (j-1)*(2*n-j)/2) = B(i,j)$ for $j \leq i \leq n$.

On exit, the triangular factor U or L from the Cholesky factorization $B = U**H*U$ or $B = L*L**H$, in the same storage format as B.

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$.
 Not referenced if RANGE = 'A' or 'I'.

VU (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$.
 Not referenced if RANGE = 'A' or 'I'.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABSTOL (input)
 The absolute error tolerance for the eigenvalues. An approximate eigenvalue is accepted as converged when it is determined to lie in an interval [a,b] of width less than or equal to

$$ABSTOL + EPS * \max(|a|, |b|),$$

where EPS is the machine precision. If ABSTOL is

less than or equal to zero, then $\text{EPS} \cdot |T|$ will be used in its place, where $|T|$ is the 1-norm of the tridiagonal matrix obtained by reducing AP to tridiagonal form.

Eigenvalues will be computed most accurately when ABSTOL is set to twice the underflow threshold $2 \cdot \text{SLAMCH}('S')$, not zero. If this routine returns with $\text{INFO} > 0$, indicating that some eigenvectors did not converge, try setting ABSTOL to $2 \cdot \text{SLAMCH}('S')$.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = \text{IU} - \text{IL} + 1$.

W (output) DOUBLE PRECISION array, dimension (N)

On normal exit, the first M elements contain the selected eigenvalues in ascending order.

Z (input) COMPLEX*16 array, dimension (LDZ, N)

If JOBZ = 'N', then Z is not referenced. If JOBZ = 'V', then if $\text{INFO} = 0$, the first M columns of Z contain the orthonormal eigenvectors of the matrix A corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with $W(i)$. The eigenvectors are normalized as follows: if $\text{ITYPE} = 1$ or 2 , $Z^* H B Z = I$; if $\text{ITYPE} = 3$, $Z^* H \text{inv}(B) Z = I$.

If an eigenvector fails to converge, then that column of Z contains the latest approximation to the eigenvector, and the index of the eigenvector is returned in IFAIL. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $\text{LDZ} \geq 1$, and if JOBZ = 'V', $\text{LDZ} \geq \max(1, N)$.

WORK (workspace)

COMPLEX*16 array, dimension(2*N)

RWORK (workspace)

DOUBLE PRECISION array, dimension(7*N)

IWORK (workspace)

INTEGER array, dimension(5*N)

IFAIL (output)

If JOBZ = 'V', then if $\text{INFO} = 0$, the first M elements of IFAIL are zero. If $\text{INFO} > 0$, then IFAIL contains the indices of the eigenvectors that failed to converge. If JOBZ = 'N', then IFAIL is not referenced.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value
> 0: CPPTRF or ZHPEVX returned an error code:
<= N: if INFO = i, ZHPEVX failed to converge; i eigenvectors failed to converge. Their indices are stored in array IFAIL. > N: if INFO = N + i, for 1 <= i <= n, then the leading minor of order i of B is not positive definite. The factorization of B could not be completed and no eigenvalues or eigenvectors were computed.

FURTHER DETAILS

Based on contributions by

Mark Fahey, Department of Mathematics, Univ. of Kentucky,
USA

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NAME

zhpmv - perform the matrix-vector operation $y := \alpha A x + \beta y$

SYNOPSIS

```
SUBROUTINE ZHPMV(UPLO, N, ALPHA, A, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(*), X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE ZHPMV_64(UPLO, N, ALPHA, A, X, INCX, BETA, Y, INCY)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(*), X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE HPMV(UPLO, [N], ALPHA, A, X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: A, X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE HPMV_64(UPLO, [N], ALPHA, A, X, [INCX], BETA, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: A, X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhpmv(char uplo, int n, doublecomplex *alpha, double-  
lecomplex *a, doublecomplex *x, int incx, double-  
lecomplex *beta, doublecomplex *y, int incy);
```

```
void zhpmv_64(char uplo, long n, doublecomplex *alpha, doublecomplex *a, doublecomplex *x, long incx, doublecomplex *beta, doublecomplex *y, long incy);
```

PURPOSE

zhpmv performs the matrix-vector operation $y := \alpha A x + \beta y$ where α and β are scalars, x and y are n element vectors and A is an n by n hermitian matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array A as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in A .

UPLO = 'L' or 'l' The lower triangular part of A is supplied in A .

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

(($n * (n + 1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular part of the hermitian matrix packed sequentially, column by column, so that $A(1)$ contains $a(1, 1)$, $A(2)$ and $A(3)$ contain $a(1, 2)$ and $a(2, 2)$ respectively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular part of the hermitian matrix packed sequentially, column by column, so that $A(1)$ contains $a(1, 1)$, $A(2)$ and $A(3)$ contain $a(2, 1)$ and $a(3, 1)$ respectively, and so on. Note that the imaginary parts of the diagonal elements need not be set and are assumed to be zero. Unchanged on exit.

X (input)

($1 + (n - 1) * \text{abs}(\text{INCX})$). Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. INCX \neq 0. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then Y need not be set on input. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

zhpr - perform the hermitian rank 1 operation $A := \alpha x x^* + A$

SYNOPSIS

```
SUBROUTINE ZHPR(UPLO, N, ALPHA, X, INCX, A)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX X(*), A(*)  
INTEGER N, INCX  
DOUBLE PRECISION ALPHA
```

```
SUBROUTINE ZHPR_64(UPLO, N, ALPHA, X, INCX, A)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX X(*), A(*)  
INTEGER*8 N, INCX  
DOUBLE PRECISION ALPHA
```

F95 INTERFACE

```
SUBROUTINE HPR(UPLO, [N], ALPHA, X, [INCX], A)
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: X, A  
INTEGER :: N, INCX  
REAL(8) :: ALPHA
```

```
SUBROUTINE HPR_64(UPLO, [N], ALPHA, X, [INCX], A)
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: X, A  
INTEGER(8) :: N, INCX  
REAL(8) :: ALPHA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhpr(char uplo, int n, double alpha, doublecomplex *x,  
          int incx, doublecomplex *a);
```

```
void zhpr_64(char uplo, long n, double alpha, doublecomplex
*x, long incx, doublecomplex *a);
```

PURPOSE

zhpr performs the hermitian rank 1 operation $A := \alpha x x^* \text{conjg}(x) + A$ where alpha is a real scalar, x is an n element vector and A is an n by n hermitian matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array A as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in A.

UPLO = 'L' or 'l' The lower triangular part of A is supplied in A.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

X (input)

$(1 + (n - 1) * \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x. Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X. $\text{INCX} \neq 0$. Unchanged on exit.

A (input/output)

$(n * (n + 1) / 2)$. Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular part of the hermitian matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(1, 2) and a(2, 2) respectively, and so on. On exit, the array A is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular part of the hermitian matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on.

On exit, the array A is overwritten by the lower triangular part of the updated matrix. Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

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NAME

zhpr2 - perform the Hermitian rank 2 operation $A := \alpha * x * \text{conjg}(y') + \text{conjg}(\alpha) * y * \text{conjg}(x') + A$

SYNOPSIS

```
SUBROUTINE ZHPR2(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*), AP(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE ZHPR2_64(UPLO, N, ALPHA, X, INCX, Y, INCY, AP)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX ALPHA  
DOUBLE COMPLEX X(*), Y(*), AP(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE HPR2(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], AP)
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y, AP  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE HPR2_64(UPLO, [N], ALPHA, X, [INCX], Y, [INCY], AP)
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8) :: ALPHA  
COMPLEX(8), DIMENSION(:) :: X, Y, AP  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhpr2(char uplo, int n, doublecomplex *alpha, doublecomplex *x, int incx, doublecomplex *y, int incy, doublecomplex *ap);
```

```
void zhpr2_64(char uplo, long n, doublecomplex *alpha, doublecomplex *x, long incx, doublecomplex *y, long incy, doublecomplex *ap);
```

PURPOSE

zhpr2 performs the Hermitian rank 2 operation $A := \alpha x \text{conjg}(y') + \text{conjg}(\alpha) y \text{conjg}(x') + A$ where α is a scalar, x and y are n element vectors and A is an n by n hermitian matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the matrix A is supplied in the packed array AP as follows:

UPLO = 'U' or 'u' The upper triangular part of A is supplied in AP .

UPLO = 'L' or 'l' The lower triangular part of A is supplied in AP .

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

X (input)

$(1 + (n - 1) \cdot \text{abs}(\text{INCX}))$. Before entry, the incremented array X must contain the n element vector x . Unchanged on exit.

INCX (input)

On entry, INCX specifies the increment for the elements of X . $\text{INCX} \neq 0$. Unchanged on exit.

Y (input)

$(1 + (n - 1) \cdot \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector y . Unchanged on exit.

INCY (input)

On entry, INCY specifies the increment for the elements of Y . $\text{INCY} \neq 0$. Unchanged on exit.

AP (input/output)

$((n \cdot (n + 1)) / 2)$. Before entry with UPLO = 'U' or 'u', the array AP must contain the upper

triangular part of the hermitian matrix packed sequentially, column by column, so that AP(1) contains a(1, 1), AP(2) and AP(3) contain a(1, 2) and a(2, 2) respectively, and so on. On exit, the array AP is overwritten by the upper triangular part of the updated matrix. Before entry with UPLO = 'L' or 'l', the array AP must contain the lower triangular part of the hermitian matrix packed sequentially, column by column, so that AP(1) contains a(1, 1), AP(2) and AP(3) contain a(2, 1) and a(3, 1) respectively, and so on. On exit, the array AP is overwritten by the lower triangular part of the updated matrix. Note that the imaginary parts of the diagonal elements need not be set, they are assumed to be zero, and on exit they are set to zero.

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NAME

zhprfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZHPRFS(UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX, FERR,  
  BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZHPRFS_64(UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPRFS(UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X, [LDX],  
  FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, AF, WORK  
COMPLEX(8), DIMENSION(:, :) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE HPRFS_64(UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X,  
  [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

COMPLEX(8), DIMENSION(:) :: A, AF, WORK
COMPLEX(8), DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zhprfs(char uplo, int n, int nrhs, doublecomplex *a,
            doublecomplex *af, int *ipivot, doublecomplex *b,
            int ldb, doublecomplex *x, int ldx, double *ferr,
            double *berr, int *info);

void zhprfs_64(char uplo, long n, long nrhs, doublecomplex
              *a, doublecomplex *af, long *ipivot, doublecomplex
              *b, long ldb, doublecomplex *x, long ldx, double
              *ferr, double *berr, long *info);

```

PURPOSE

zhprfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian indefinite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$
 The upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i, j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i, j)$ for $j \leq i \leq n$.

AF (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$
 The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^*H$ or $A = L*D*L^*H$ as computed by ZHPTRF, stored as a packed triangular matrix.

IPIVOT (input) INTEGER array, dimension (N)
 Details of the interchanges and the block structure of D as determined by ZHPTRF.

B (input) COMPLEX*16 array, dimension (LDB, NRHS)

The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

X (input/output) COMPLEX*16 array, dimension (LDX,NRHS)

On entry, the solution matrix X, as computed by
ZHPTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq
max(1,N).

FERR (output) DOUBLE PRECISION array, dimension (NRHS)

The estimated forward error bound for each solu-
tion vector X(j) (the j-th column of the solution
matrix X). If XTRUE is the true solution
corresponding to X(j), FERR(j) is an estimated
upper bound for the magnitude of the largest ele-
ment in (X(j) - XTRUE) divided by the magnitude of
the largest element in X(j). The estimate is as
reliable as the estimate for RCOND, and is almost
always a slight overestimate of the true error.

BERR (output) DOUBLE PRECISION array, dimension (NRHS)

The componentwise relative backward error of each
solution vector X(j) (i.e., the smallest relative
change in any element of A or B that makes X(j) an
exact solution).

WORK (workspace)

COMPLEX*16 array, dimension(2*N)

WORK2 (workspace)

DOUBLE PRECISION array, dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

zhpsv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZHPSV(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZHPSV_64(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HPSV(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HPSV_64(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhpsv(char uplo, int n, int nrhs, doublecomplex *a, int
           *ipivot, doublecomplex *b, int ldb, int *info);

void zhpsv_64(char uplo, long n, long nrhs, doublecomplex
              *a, long *ipivot, doublecomplex *b, long ldb, long
              *info);

```

PURPOSE

zhpsv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N Hermitian matrix stored in packed format and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{*H}$, if UPLO = 'U', or

$A = L * D * L^{*H}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{*H}$ or $A = L*D*L^{*H}$ as computed by ZHPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (output) INTEGER array, dimension (N)

Details of the interchanges and the block structure of D, as determined by ZHPTRF. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were

interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output) COMPLEX*16 array, dimension (LDB, NRHS)
On entry, the N-by-NRHS right hand side matrix B.
On exit, if $INFO = 0$, the N-by-NRHS solution matrix X.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)
= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, $UPLO = 'U'$:

Two-dimensional storage of the Hermitian matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34 (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

zhpsvx - use the diagonal pivoting factorization $A = U^*D^*U^{**}H$ or $A = L^*D^*L^{**}H$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N Hermitian matrix stored in packed format and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE ZHPSVX(FACT, UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX,
                 RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZHPSVX_64(FACT, UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X,
                   LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE HPSVX(FACT, UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X,
                [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX(8), DIMENSION(:) :: A, AF, WORK
COMPLEX(8), DIMENSION(:, :) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
```

```

REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

SUBROUTINE HPSVX_64(FACT, UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB],
    X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX(8), DIMENSION(:) :: A, AF, WORK
COMPLEX(8), DIMENSION(:,:) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zhpsvx(char fact, char uplo, int n, int nrhs, doublecomplex *a, doublecomplex *af, int *ipivot, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *rcond, double *ferr, double *berr, int *info);

void zhpsvx_64(char fact, char uplo, long n, long nrhs, doublecomplex *a, doublecomplex *af, long *ipivot, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zhpsvx uses the diagonal pivoting factorization $A = U^*D^*U^{**H}$ or $A = L^*D^*L^{**H}$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N -by- N Hermitian matrix stored in packed format and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the diagonal pivoting method is used to factor A as

$$A = U * D * U^{**H}, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * D * L^{**H}, \text{ if } UPLO = 'L',$$

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices and D is Hermitian and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than machine precision,

$INFO = N+1$ is returned as a warning, but the routine

still goes on
to solve for X and compute error bounds as described
below.

3. The system of equations is solved for X using the factored form
of A.

4. Iterative refinement is applied to improve the computed
solution
matrix and calculate error bounds and backward error
estimates
for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A
has been supplied on entry. = 'F': On entry, AF
and IPIVOT contain the factored form of A. AF and
IPIVOT will not be modified. = 'N': The matrix A
will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of
the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number
of columns of the matrices B and X. $NRHS \geq 0$.

A (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$

The upper or lower triangle of the Hermitian
matrix A, packed columnwise in a linear array.
The j-th column of A is stored in the array A as
follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$
for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2)$
 $= A(i,j)$ for $j \leq i \leq n$. See below for further
details.

AF (input or output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

If FACT = 'F', then AF is an input argument and on
entry contains the block diagonal matrix D and the
multipliers used to obtain the factor U or L from
the factorization $A = U*D*U**H$ or $A = L*D*L**H$ as
computed by ZHPTRF, stored as a packed triangular
matrix in the same storage format as A.

If FACT = 'N', then AF is an output argument and
on exit contains the block diagonal matrix D and
the multipliers used to obtain the factor U or L
from the factorization $A = U*D*U**H$ or $A =$
 $L*D*L**H$ as computed by ZHPTRF, stored as a packed
triangular matrix in the same storage format as A.

IPIVOT (input or output) INTEGER array, dimension (N)

If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by ZHPTRF. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

If FACT = 'N', then IPIVOT is an output argument and on exit contains details of the interchanges and the block structure of D, as determined by ZHPTRF.

B (input) COMPLEX*16 array, dimension (LDB,NRHS)
The N-by-NRHS right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

X (output) COMPLEX*16 array, dimension (LDX,NRHS)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)
The leading dimension of the array X. LDX >= max(1,N).

RCOND (output)
The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output) DOUBLE PRECISION array, dimension (NRHS)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) DOUBLE PRECISION array, dimension (NRHS)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
COMPLEX*16 array, dimension(2*N)

DOUBLE PRECISION array, WORK2 (workspace)
dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, $UPLO = 'U'$:

Two-dimensional storage of the Hermitian matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34    (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

zhptrd - reduce a complex Hermitian matrix A stored in packed form to real symmetric tridiagonal form T by a unitary similarity transformation

SYNOPSIS

```
SUBROUTINE ZHPTRD(UPLO, N, AP, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), TAU(*)  
INTEGER N, INFO  
DOUBLE PRECISION D(*), E(*)
```

```
SUBROUTINE ZHPTRD_64(UPLO, N, AP, D, E, TAU, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), TAU(*)  
INTEGER*8 N, INFO  
DOUBLE PRECISION D(*), E(*)
```

F95 INTERFACE

```
SUBROUTINE HPTRD(UPLO, [N], AP, D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP, TAU  
INTEGER :: N, INFO  
REAL(8), DIMENSION(:) :: D, E
```

```
SUBROUTINE HPTRD_64(UPLO, [N], AP, D, E, TAU, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP, TAU  
INTEGER(8) :: N, INFO  
REAL(8), DIMENSION(:) :: D, E
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhpztrd(char uplo, int n, doublecomplex *ap, double *d,
             double *e, doublecomplex *tau, int *info);

void zhpztrd_64(char uplo, long n, doublecomplex *ap, double
                *d, double *e, doublecomplex *tau, long *info);

```

PURPOSE

zhpztrd reduces a complex Hermitian matrix A stored in packed form to real symmetric tridiagonal form T by a unitary similarity transformation: $Q^*H * A * Q = T$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$. On exit, if UPLO = 'U', the diagonal and first superdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements above the first superdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors; if UPLO = 'L', the diagonal and first subdiagonal of A are overwritten by the corresponding elements of the tridiagonal matrix T, and the elements below the first subdiagonal, with the array TAU, represent the unitary matrix Q as a product of elementary reflectors. See Further Details.

D (output) DOUBLE PRECISION array, dimension (N)

The diagonal elements of the tridiagonal matrix T:
 $D(i) = A(i,i)$.

E (output) DOUBLE PRECISION array, dimension (N-1)

The off-diagonal elements of the tridiagonal matrix T: $E(i) = A(i,i+1)$ if UPLO = 'U', $E(i) = A(i+1,i)$ if UPLO = 'L'.

TAU (output) COMPLEX*16 array, dimension (N-1)

The scalar factors of the elementary reflectors (see Further Details).

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-

gal value

FURTHER DETAILS

If UPLO = 'U', the matrix Q is represented as a product of elementary reflectors

$$Q = H(n-1) \dots H(2) H(1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with $v(i+1:n) = 0$ and $v(i) = 1$; $v(1:i-1)$ is stored on exit in AP, overwriting $A(1:i-1,i+1)$, and tau is stored in TAU(i).

If UPLO = 'L', the matrix Q is represented as a product of elementary reflectors

$$Q = H(1) H(2) \dots H(n-1).$$

Each H(i) has the form

$$H(i) = I - \tau * v * v'$$

where tau is a complex scalar, and v is a complex vector with $v(1:i) = 0$ and $v(i+1) = 1$; $v(i+2:n)$ is stored on exit in AP, overwriting $A(i+2:n,i)$, and tau is stored in TAU(i).

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NAME

zhptrf - compute the factorization of a complex Hermitian packed matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE ZHPTRF(UPLO, N, A, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZHPTRF_64(UPLO, N, A, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HPTRF(UPLO, [N], A, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HPTRF_64(UPLO, [N], A, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zhptrf(char uplo, int n, doublecomplex *a, int *ipivot,
            int *info);

void zhptrf_64(char uplo, long n, doublecomplex *a, long
               *ipivot, long *info);

```

PURPOSE

zhptrf computes the factorization of a complex Hermitian packed matrix A using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U^*H \quad \text{or} \quad A = L^*D^*L^*H$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is Hermitian and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i, j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i, j)$ for $j \leq i \leq n$.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L, stored as a packed triangular matrix overwriting A (see below for further details).

IPIVOT (output) INTEGER array, dimension (N)

Details of the interchanges and the block structure of D. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged and $D(k, k)$ is a 1-by-1 diagonal block. If UPLO = 'U' and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns k-1 and $-IPIVOT(k)$ were interchanged and $D(k-1:k, k-1:k)$ is a 2-by-2 diagonal block. If UPLO = 'L' and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns k+1 and $-IPIVOT(k)$ were interchanged and $D(k:k+1, k:k+1)$ is a 2-by-2 diagonal block.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

5-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

zhptri - compute the inverse of a complex Hermitian indefinite matrix A in packed storage using the factorization $A = U^*D^*U^{**H}$ or $A = L^*D^*L^{**H}$ computed by ZHPTRF

SYNOPSIS

```
SUBROUTINE ZHPTRI(UPLO, N, A, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZHPTRI_64(UPLO, N, A, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HPTRI(UPLO, [N], A, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HPTRI_64(UPLO, [N], A, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhptri(char uplo, int n, doublecomplex *a, int *ipivot,  
            int *info);
```

```
void zhptri_64(char uplo, long n, doublecomplex *a, long
               *ipivot, long *info);
```

PURPOSE

zhptri computes the inverse of a complex Hermitian indefinite matrix A in packed storage using the factorization $A = U^*D^*U^{**H}$ or $A = L^*D^*L^{**H}$ computed by ZHPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U^*D^*U^{**H}$;
= 'L': Lower triangular, form is $A = L^*D^*L^{**H}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZHPTRF, stored as a packed triangular matrix.

On exit, if INFO = 0, the (Hermitian) inverse of the original matrix, stored as a packed triangular matrix. The j-th column of $\text{inv}(A)$ is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = \text{inv}(A)(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = \text{inv}(A)(i,j)$ for $j \leq i \leq n$.

IPIVOT (input) INTEGER array, dimension (N)

Details of the interchanges and the block structure of D as determined by ZHPTRF.

WORK (workspace)

COMPLEX*16 array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

zhptrs - solve a system of linear equations $A \cdot X = B$ with a complex Hermitian matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^* \cdot H$ or $A = L \cdot D \cdot L^* \cdot H$ computed by ZHPTRF

SYNOPSIS

```
SUBROUTINE ZHPTRS(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZHPTRS_64(UPLO, N, NRHS, A, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE HPTRS(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE HPTRS_64(UPLO, [N], [NRHS], A, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zhptrs(char uplo, int n, int nrhs, doublecomplex *a,
            int *ipivot, doublecomplex *b, int ldb, int
            *info);
```

```
void zhptrs_64(char uplo, long n, long nrhs, doublecomplex
               *a, long *ipivot, doublecomplex *b, long ldb, long
               *info);
```

PURPOSE

zhptrs solves a system of linear equations $A \cdot X = B$ with a complex Hermitian matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^* \cdot H$ or $A = L \cdot D \cdot L^* \cdot H$ computed by ZHPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U \cdot D \cdot U^* \cdot H$;
 = 'L': Lower triangular, form is $A = L \cdot D \cdot L^* \cdot H$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) COMPLEX*16 array, dimension $(N \cdot (N+1) / 2)$

The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZHPTRF, stored as a packed triangular matrix.

IPIVOT (input) INTEGER array, dimension (N)

Details of the interchanges and the block structure of D as determined by ZHPTRF.

B (input/output) COMPLEX*16 array, dimension $(LDB, NRHS)$

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

zhsein - use inverse iteration to find specified right and/or left eigenvectors of a complex upper Hessenberg matrix H

SYNOPSIS

```
SUBROUTINE ZHSEIN(SIDE, EIGSRC, INITV, SELECT, N, H, LDH, W, VL,  
                LDVL, VR, LDVR, MM, M, WORK, RWORK, IFAILL, IFAILR, INFO)
```

```
CHARACTER * 1 SIDE, EIGSRC, INITV  
DOUBLE COMPLEX H(LDH,*), W(*), VL(LDVL,*), VR(LDVR,*),  
WORK(*)  
INTEGER N, LDH, LDVL, LDVR, MM, M, INFO  
INTEGER IFAILL(*), IFAILR(*)  
LOGICAL SELECT(*)  
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZHSEIN_64(SIDE, EIGSRC, INITV, SELECT, N, H, LDH, W, VL,  
                   LDVL, VR, LDVR, MM, M, WORK, RWORK, IFAILL, IFAILR, INFO)
```

```
CHARACTER * 1 SIDE, EIGSRC, INITV  
DOUBLE COMPLEX H(LDH,*), W(*), VL(LDVL,*), VR(LDVR,*),  
WORK(*)  
INTEGER*8 N, LDH, LDVL, LDVR, MM, M, INFO  
INTEGER*8 IFAILL(*), IFAILR(*)  
LOGICAL*8 SELECT(*)  
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE HSEIN(SIDE, EIGSRC, INITV, SELECT, [N], H, [LDH], W, VL,  
                [LDVL], VR, [LDVR], MM, M, [WORK], [RWORK], IFAILL, IFAILR, [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, EIGSRC, INITV  
COMPLEX(8), DIMENSION(:) :: W, WORK  
COMPLEX(8), DIMENSION(:,:) :: H, VL, VR  
INTEGER :: N, LDH, LDVL, LDVR, MM, M, INFO  
INTEGER, DIMENSION(:) :: IFAILL, IFAILR  
LOGICAL, DIMENSION(:) :: SELECT
```

```

REAL(8), DIMENSION(:) :: RWORK

SUBROUTINE HSEIN_64(SIDE, EIGSRC, INITV, SELECT, [N], H, [LDH], W,
    VL, [LDVL], VR, [LDVR], MM, M, [WORK], [RWORK], IFAILL, IFAILR,
    [INFO])

CHARACTER(LEN=1) :: SIDE, EIGSRC, INITV
COMPLEX(8), DIMENSION(:) :: W, WORK
COMPLEX(8), DIMENSION(:,:) :: H, VL, VR
INTEGER(8) :: N, LDH, LDVL, LDVR, MM, M, INFO
INTEGER(8), DIMENSION(:) :: IFAILL, IFAILR
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>

void zhsein(char side, char eigsrc, char initv, int *select,
    int n, doublecomplex *h, int ldh, doublecomplex
    *w, doublecomplex *vl, int ldvl, doublecomplex
    *vr, int ldvr, int mm, int *m, int *ifaill, int
    *ifailr, int *info);

void zhsein_64(char side, char eigsrc, char initv, long
    *select, long n, doublecomplex *h, long ldh, doub-
    lecomplex *w, doublecomplex *vl, long ldvl, doub-
    lecomplex *vr, long ldvr, long mm, long *m, long
    *ifaill, long *ifailr, long *info);

```

PURPOSE

zhsein uses inverse iteration to find specified right and/or left eigenvectors of a complex upper Hessenberg matrix H.

The right eigenvector x and the left eigenvector y of the matrix H corresponding to an eigenvalue w are defined by:

$$H * x = w * x, \quad y^{*h} * H = w * y^{*h}$$

where y**h denotes the conjugate transpose of the vector y.

ARGUMENTS

SIDE (input)
 = 'R': compute right eigenvectors only;
 = 'L': compute left eigenvectors only;
 = 'B': compute both right and left eigenvectors.

EIGSRC (input)
 Specifies the source of eigenvalues supplied in W:
 = 'Q': the eigenvalues were found using ZHSEQR;
 thus, if H has zero subdiagonal elements, and so is block-triangular, then the j-th eigenvalue can be assumed to be an eigenvalue of the block containing the j-th row/column. This property allows ZHSEIN to perform inverse iteration on just one

diagonal block. = 'N': no assumptions are made on the correspondence between eigenvalues and diagonal blocks. In this case, ZHSEIN must always perform inverse iteration using the whole matrix H.

INITV (input)

= 'N': no initial vectors are supplied;
= 'U': user-supplied initial vectors are stored in the arrays VL and/or VR.

SELECT (input)

Specifies the eigenvectors to be computed. To select the eigenvector corresponding to the eigenvalue $W(j)$, SELECT(j) must be set to .TRUE..

N (input) The order of the matrix H. $N \geq 0$.

H (input) The upper Hessenberg matrix H.

LDH (input)

The leading dimension of the array H. $LDH \geq \max(1,N)$.

W (input/output)

On entry, the eigenvalues of H. On exit, the real parts of W may have been altered since close eigenvalues are perturbed slightly in searching for independent eigenvectors.

VL (input/output)

On entry, if INITV = 'U' and SIDE = 'L' or 'B', VL must contain starting vectors for the inverse iteration for the left eigenvectors; the starting vector for each eigenvector must be in the same column in which the eigenvector will be stored. On exit, if SIDE = 'L' or 'B', the left eigenvectors specified by SELECT will be stored consecutively in the columns of VL, in the same order as their eigenvalues. If SIDE = 'R', VL is not referenced.

LDVL (input)

The leading dimension of the array VL. $LDVL \geq \max(1,N)$ if SIDE = 'L' or 'B'; $LDVL \geq 1$ otherwise.

VR (input/output)

On entry, if INITV = 'U' and SIDE = 'R' or 'B', VR must contain starting vectors for the inverse iteration for the right eigenvectors; the starting vector for each eigenvector must be in the same column in which the eigenvector will be stored. On exit, if SIDE = 'R' or 'B', the right eigenvectors specified by SELECT will be stored consecutively in the columns of VR, in the same order as their eigenvalues. If SIDE = 'L', VR is not referenced.

LDVR (input)

The leading dimension of the array VR. $LDVR \geq \max(1,N)$ if SIDE = 'R' or 'B'; $LDVR \geq 1$ otherwise.

wise.

MM (input)

The number of columns in the arrays VL and/or VR.
MM \geq M.

M (output)

The number of columns in the arrays VL and/or VR
required to store the eigenvectors (= the number
of .TRUE. elements in SELECT).

WORK (workspace)

dimension(N*N)

RWORK (workspace)

dimension(N)

IFAILL (output)

If SIDE = 'L' or 'B', IFAILL(i) = j > 0 if the
left eigenvector in the i-th column of VL
(corresponding to the eigenvalue w(j)) failed to
converge; IFAILL(i) = 0 if the eigenvector con-
verged satisfactorily. If SIDE = 'R', IFAILL is
not referenced.

IFAILR (output)

If SIDE = 'R' or 'B', IFAILR(i) = j > 0 if the
right eigenvector in the i-th column of VR
(corresponding to the eigenvalue w(j)) failed to
converge; IFAILR(i) = 0 if the eigenvector con-
verged satisfactorily. If SIDE = 'L', IFAILR is
not referenced.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value
> 0: if INFO = i, i is the number of eigenvectors
which failed to converge; see IFAILL and IFAILR
for further details.

FURTHER DETAILS

Each eigenvector is normalized so that the element of larg-
est magnitude has magnitude 1; here the magnitude of a com-
plex number (x,y) is taken to be $|x|+|y|$.

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NAME

zhseqr - compute the eigenvalues of a complex upper Hessenberg matrix H, and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z^* H$, where T is an upper triangular matrix (the Schur form), and Z is the unitary matrix of Schur vectors

SYNOPSIS

```
SUBROUTINE ZHSEQR(JOB, COMPZ, N, ILO, IHI, H, LDH, W, Z, LDZ, WORK,  
                LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPZ  
DOUBLE COMPLEX H(LDH,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER N, ILO, IHI, LDH, LDZ, LWORK, INFO
```

```
SUBROUTINE ZHSEQR_64(JOB, COMPZ, N, ILO, IHI, H, LDH, W, Z, LDZ,  
                   WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPZ  
DOUBLE COMPLEX H(LDH,*), W(*), Z(LDZ,*), WORK(*)  
INTEGER*8 N, ILO, IHI, LDH, LDZ, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE HSEQR(JOB, COMPZ, N, ILO, IHI, H, [LDH], W, Z, [LDZ],  
                [WORK], LWORK, [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPZ  
COMPLEX(8), DIMENSION(:) :: W, WORK  
COMPLEX(8), DIMENSION(:,:) :: H, Z  
INTEGER :: N, ILO, IHI, LDH, LDZ, LWORK, INFO
```

```
SUBROUTINE HSEQR_64(JOB, COMPZ, N, ILO, IHI, H, [LDH], W, Z, [LDZ],  
                   [WORK], LWORK, [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPZ  
COMPLEX(8), DIMENSION(:) :: W, WORK  
COMPLEX(8), DIMENSION(:,:) :: H, Z  
INTEGER(8) :: N, ILO, IHI, LDH, LDZ, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>

void zhseqr (char, char, int, int, int, doublecomplex*, int,
            doublecomplex*, doublecomplex*, int, int*);

void zhseqr_64 (char, char, long, long, long, doublecom-
               plex*, long, doublecomplex*, doublecomplex*, long,
               long*);
```

PURPOSE

zhseqr computes the eigenvalues of a complex upper Hessenberg matrix H, and, optionally, the matrices T and Z from the Schur decomposition $H = Z T Z^* H$, where T is an upper triangular matrix (the Schur form), and Z is the unitary matrix of Schur vectors.

Optionally Z may be postmultiplied into an input unitary matrix Q, so that this routine can give the Schur factorization of a matrix A which has been reduced to the Hessenberg form H by the unitary matrix Q: $A = Q^* H Q^* H = (QZ)^* T (QZ)^* H$.

ARGUMENTS

JOB (input)
 = 'E': compute eigenvalues only;
 = 'S': compute eigenvalues and the Schur form T.

COMPZ (input)
 = 'N': no Schur vectors are computed;
 = 'I': Z is initialized to the unit matrix and the matrix Z of Schur vectors of H is returned; = 'V': Z must contain an unitary matrix Q on entry, and the product Q*Z is returned.

N (input) The order of the matrix H. $N \geq 0$.

ILO (input)
 It is assumed that H is already upper triangular in rows and columns 1:ILO-1 and IHI+1:N. ILO and IHI are normally set by a previous call to CGEBAL, and then passed to CGEHRD when the matrix output by CGEBAL is reduced to Hessenberg form. Otherwise ILO and IHI should be set to 1 and N respectively. $1 \leq ILO \leq IHI \leq N$, if $N > 0$; ILO=1 and IHI=0, if $N=0$.

IHI (input)
 See the description of ILO.

H (input/output)
 On entry, the upper Hessenberg matrix H. On exit, if JOB = 'S', H contains the upper triangular matrix T from the Schur decomposition (the Schur form). If JOB = 'E', the contents of H are

unspecified on exit.

LDH (input)

The leading dimension of the array H. LDH \geq max(1,N).

W (output)

The computed eigenvalues. If JOB = 'S', the eigenvalues are stored in the same order as on the diagonal of the Schur form returned in H, with $W(i) = H(i,i)$.

Z (input) If COMPZ = 'N': Z is not referenced.

If COMPZ = 'I': on entry, Z need not be set, and on exit, Z contains the unitary matrix Z of the Schur vectors of H. If COMPZ = 'V': on entry Z must contain an N-by-N matrix Q, which is assumed to be equal to the unit matrix except for the submatrix Z(ILO:IHI,ILO:IHI); on exit Z contains $Q*Z$. Normally Q is the unitary matrix generated by CUNGHR after the call to CGEHRD which formed the Hessenberg matrix H.

LDZ (input)

The leading dimension of the array Z. LDZ \geq max(1,N) if COMPZ = 'I' or 'V'; LDZ \geq 1 otherwise.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (output)

The dimension of the array WORK. LWORK \geq max(1,N).

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, ZHSEQR failed to compute all the eigenvalues in a total of $30*(IHI-ILO+1)$ iterations; elements 1:i-1 and i+1:n of W contain those eigenvalues which have been successfully computed.

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NAME

zjadmm - Jagged diagonal matrix-matrix multiply (modified Ellpack)

SYNOPSIS

```
SUBROUTINE ZJADMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, INDX, PNTR, MAXNZ, IPERM,  
*                B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5), MAXNZ,  
*                LDB, LDC, LWORK  
INTEGER          INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZJADMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                   VAL, INDX, PNTR, MAXNZ, IPERM,  
*                   B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5), MAXNZ,  
*                   LDB, LDC, LWORK  
INTEGER*8        INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ is the number of non-zero elements.

F95 INTERFACE

```
SUBROUTINE JADMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*               PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER        TRANSA, M, K, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE JADMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL, INDX,  
*                   PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8      TRANSA, M, K, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM
```

```

DOUBLE COMPLEX    ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: VAL
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zjadmm (int transa, int m, int n, int k, doublecomplex
*alpha, int *descra, doublecomplex *val, int *indx, int
*pntr, int maxnz, int *iperm, doublecomplex *b, int ldb,
doublecomplex *beta, doublecomplex *c, int ldc)

```

```

void zjadmm_64(long transa, long m, long n, long k,
doublecomplex *alpha, long *descra, doublecomplex *val, long
*indx, long *pntr, long maxnz, long *iperm, doublecomplex
*b, long ldb, doublecomplex *beta, doublecomplex *c, long
ldc);

```

DESCRIPTION

zjadmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the jagged diagonal format, alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array: DESCRA(1) matrix structure 0 : general 1 : symmetric ($A=A'$) 2 : Hermitian ($A= \operatorname{CONJG}(A')$) 3 : Triangular

4 : Skew(Anti)-Symmetric (A=-A')
 5 : Diagonal
 6 : Skew-Hermitian (A= -CONJG(A'))
 DESCRA(2) upper/lower triangular indicator
 1 : lower
 2 : upper
 DESCRA(3) main diagonal type
 0 : non-unit
 1 : unit
 DESCRA(4) Array base (NOT IMPLEMENTED)
 0 : C/C++ compatible
 1 : Fortran compatible
 DESCRA(5) repeated indices? (NOT IMPLEMENTED)
 0 : unknown
 1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length
 NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of entries of A.
 VAL can be viewed as a column major ordering of a
 row permutation of the Ellpack representation of A,
 where the Ellpack representation is permuted so that
 the rows are non-increasing in the number of nonzero
 entries. Values added for padding in Ellpack are
 not included in the Jagged-Diagonal format.
 Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length
 NNZ=PNTR(MAXNZ+1)-PNTR(1)+1 consisting of the column
 indices of the corresponding entries in VAL.
 Unchanged on exit.

PNTR(input) On entry, PNTR is an integer array of length
 MAXNZ+1, where PNTR(I)-PNTR(1)+1 points to
 the location in VAL of the first element
 in the row-permuted Ellpack representation of A.
 Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of
 nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length M
 such that I = IPERM(I'), where row I in the
 original Ellpack representation corresponds
 to row I' in the permuted representation.
 If IPERM(1) = 0, it is assumed by convention that
 IPERM(I) = I. IPERM is used to determine the order
 in which rows of C are updated. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise

the leading k by n part of the array C must contain the matrix C . On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \beta * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

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NAME

zjadrp - right permutation of a jagged diagonal matrix

SYNOPSIS

```
SUBROUTINE ZJADRP( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*                IPERM, WORK, LWORK )
INTEGER        TRANSP, M, K, MAXNZ, LWORK
INTEGER        INDX(*), PNTR(MAXNZ+1), IPERM(K), WORK(LWORK)
DOUBLE COMPLEX VAL(*)
```

```
SUBROUTINE ZJADRP_64( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*                   IPERM, WORK, LWORK )
INTEGER*8      TRANSP, M, K, MAXNZ, LWORK
INTEGER*8      INDX(*), PNTR(MAXNZ+1), IPERM(K), WORK(LWORK)
DOUBLE COMPLEX VAL(*)
```

F95 INTERFACE

```
SUBROUTINE JADRP( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*               IPERM, [WORK], [LWORK] )
INTEGER TRANSP, M, K, MAXNZ
INTEGER, DIMENSION(:) :: INDX, PNTR, IPERM
DOUBLE COMPLEX, DIMENSION(:) :: VAL
```

```
SUBROUTINE JADRP_64( TRANSP, M, K, VAL, INDX, PNTR, MAXNZ,
*                   IPERM, [WORK], [LWORK] )
INTEGER*8 TRANSP, M, K, MAXNZ
INTEGER*8, DIMENSION(:) :: INDX, PNTR, IPERM
DOUBLE COMPLEX, DIMENSION(:) :: VAL
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zjadrp (int transp, int m, int k, doublecomplex *val,
int *indx, int *pntr, int maxnz, int *iperml);
```

```
void zjadrp_64 (long transp, long m, long k, doublecomplex
*val, long *indx, long *pntr, long maxnz, long *iperml);
```

DESCRIPTION

zjadrp performs one of the matrix-matrix operations

$A \leftarrow A P$ or $A \leftarrow A P'$ (' indicates matrix transpose)

where A is an M -by- K sparse matrix represented in the jagged diagonal format, the permutation matrix P is represented by an integer vector $IPERM$, such that $IPERM(I)$ is equal to the position of the only nonzero element in row I of permutation matrix P .
NOTE: In order to get a symmetrically permuted jagged diagonal matrix $P A P'$, one can explicitly permute the columns $P A$ by calling

```
ZJADRP(0, M, M, VAL, INDX, PNTR, MAXNZ, IPERM, WORK, LWORK)
```

where parameters VAL , $INDX$, $PNTR$, $MAXNZ$, $IPERM$ are the representation of A in the jagged diagonal format. The operation makes sense if the original matrix A is square.

ARGUMENTS

TRANSP(input) $TRANSP$ indicates how to operate with the permutation matrix:
 0 : operate with matrix
 1 : operate with transpose matrix
 Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A . Unchanged on exit.

K(input) On entry, K specifies the number of columns in the matrix A . Unchanged on exit.

VAL(input/output) On entry, VAL is a scalar array of length $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ consisting of entries of A . VAL can be viewed as a column major ordering of a row permutation of the Ellpack representation of A , where the Ellpack representation is permuted so that the rows are non-increasing in the number of nonzero entries. Values added for padding in Ellpack are not included in the Jagged-Diagonal format.
On exit, VAL contains non-zero entries of the output permuted jagged diagonal matrix.

INDX(input/output) On entry, $INDX$ is an integer array of length $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ consisting of the column indices of the corresponding entries in VAL .
On exit, $INDX$ is overwritten by the column indices of the output permuted jagged diagonal matrix.

PNTR(input) On entry, $PNTR$ is an integer array of length $MAXNZ+1$, where $PNTR(I)-PNTR(1)+1$ points to the location in VAL of the first element in the row-permuted Ellpack representation of A .
Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of
nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length K
such that $I = \text{IPERM}(I')$.
Array IPERM represents a permutation P, such that
IPERM(I) is equal to the position of the only nonzero
element in row I of permutation matrix P.
For example, if

$$P = \begin{pmatrix} | & 0 & 0 & 1 & | \\ | & 1 & 0 & 0 & | \\ | & 0 & 1 & 0 & | \end{pmatrix}$$

then IPERM = (3, 1, 2). Unchanged on exit.

WORK(workspace) Scratch array of length LWORK. LWORK should be at
least K.

LWORK(input) On entry, LWORK specifies the length of the array WORK.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed;
the routine only calculates the optimal size of the
array WORK, returns this value as the first entry of
the WORK array, and no error message related to LWORK
is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of
OPENMP and it is fully compatible with NIST FORTRAN Sparse
Blas but the sources are different. Libsunperf SPARSE BLAS
is free of bugs found in NIST FORTRAN Sparse Blas. Besides
several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS)
Standard", University of Tennessee, Knoxville, Tennessee,
1996:

<http://www.netlib.org/utk/papers/sparse.ps>

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NAME

zjadsm - Jagged-diagonal format triangular solve

SYNOPSIS

```
SUBROUTINE ZJADSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, PNTR, MAXNZ, IPERM,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER TRANSA, M, N, UNITD, DESCRA(5), MAXNZ,  
* LDB, LDC, LWORK  
INTEGER INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZJADSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, PNTR, MAXNZ, IPERM,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8 TRANSA, M, N, UNITD, DESCRA(5), MAXNZ,  
* LDB, LDC, LWORK  
INTEGER*8 INDX(NNZ), PNTR(MAXNZ+1), IPERM(M)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ is the number of non-zero elements

F95 INTERFACE

```
SUBROUTINE JADSM(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
* PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER TRANSA, M, MAXNZ  
INTEGER, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE JADSM_64(TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL, INDX,  
* PNTR, MAXNZ, IPERM, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, M, MAXNZ  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, PNTR, IPERM  
DOUBLE COMPLEX ALPHA, BETA
```

```
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zjadsm (int transa, int m, int n, int unitd,
doublecomplex *dv, doublecomplex *alpha, int *descra,
doublecomplex *val, int *indx, int *pntr, int maxnz, int
*iperm, doublecomplex *b, int ldb, doublecomplex *beta,
doublecomplex *c, int ldc)
```

```
void zjadsm_64(long transa, long m, long n, long unitd,
doublecomplex *dv, doublecomplex *alpha, long *descra,
doublecomplex *val, long *indx, long *pntr, long maxnz,
long *iperm, doublecomplex *b, long ldb, doublecomplex
*beta, doublecomplex *c, long ldc);
```

DESCRIPTION

zjadsm performs one of the matrix-matrix operations

```
C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,
```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the jagged-diagonal format and op(A) is one of

```
op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).
```

ARGUMENTS

TRANSA(input) TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

M(input) On entry, M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, UNITD specifies the type of scaling:
1 : Identity matrix (argument DV[] is ignored)
2 : Scale on left (row scaling)
3 : Scale on right (column scaling)
4 : Automatic row scaling (see section NOTES for further details)
Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the diagonal entries of the diagonal scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which the rows have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL is a scalar array of length $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ consisting of entries of A. VAL can be viewed as a column major ordering of a row permutation of the Ellpack representation of A, where the Ellpack representation is permuted so that the rows are non-increasing in the number of nonzero entries. Values added for padding in Ellpack are not included in the Jagged-Diagonal format. Unchanged on exit if UNITD is not equal to 4.

INDX(input) On entry, INDX is an integer array of length $NNZ=PNTR(MAXNZ+1)-PNTR(1)+1$ consisting of the column indices of the corresponding entries in VAL. Unchanged on exit.

PNTR(input) On entry, PNTR is an integer array of length MAXNZ+1, where $PNTR(I)-PNTR(1)+1$ points to the location in VAL of the first element in the row-permuted Ellpack representation of A. Unchanged on exit.

MAXNZ(input) On entry, MAXNZ specifies the max number of nonzeros elements per row. Unchanged on exit.

IPERM(input) On entry, IPERM is an integer array of length M such that $I = IPERM(I')$, where row I in the original Ellpack representation corresponds to row I' in the permuted representation. If $IPERM(1) = 0$, it is assumed by convention that $IPERM(I) = I$. IPERM is used to determine the order in which rows of C are updated. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 On entry, the leading m by n part of the array B
 must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 On entry, the leading m by n part of the array C
 must contain the matrix C. On exit, the array C is
 overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
 On exit, if LWORK= -1, WORK(1) returns the optimum size
 of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK
 should be at least 2*M.

 For good performance, LWORK should generally be larger.
 For optimum performance on multiple processors, LWORK
 $\geq 2 * M * N_CPUS$ where N_CPUS is the maximum number of
 processors available to the program.

 If LWORK=0, the routine is to allocate workspace needed.

 If LWORK = -1, then a workspace query is assumed; the
 routine only calculates the optimum size of the WORK array,
 returns this value as the first entry of the WORK array,
 and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4, the routine scales the rows of the sparse matrix A such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in the particular case. On return DV matrix stored as a vector contains the diagonal matrix by which the rows have been scaled. UNITD=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise WORK(1) = - i where i is the row number which 2-norm is exactly zero.

3. If DESCRA(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the JAD representation of a sparse matrix do not need to be 1.0 in this usage. They are not used by the routine in these cases. But if UNITD=4, the unit diagonal elements MUST be referenced in the JAD representation.

4. The routine is designed so that it checks the validity of each sparse entry given in the sparse blas representation. Entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower triangle of A. But DESCRA(1) MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly lower triangle of A, U is the strictly upper triangle of A, D is the diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of DESCRA and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	alpha*op(L+I)*B+beta*C
3	1	0	alpha*op(L+D)*B+beta*C
3	2	1	alpha*op(U+I)*B+beta*C
3	2	0	alpha*op(U+D)*B+beta*C

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NAME

zlarz - applie a complex elementary reflector H to a complex M-by-N matrix C, from either the left or the right

SYNOPSIS

```
SUBROUTINE ZLARZ(SIDE, M, N, L, V, INCV, TAU, C, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
DOUBLE COMPLEX TAU  
DOUBLE COMPLEX V(*), C(LDC,*), WORK(*)  
INTEGER M, N, L, INCV, LDC
```

```
SUBROUTINE ZLARZ_64(SIDE, M, N, L, V, INCV, TAU, C, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
DOUBLE COMPLEX TAU  
DOUBLE COMPLEX V(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, L, INCV, LDC
```

F95 INTERFACE

```
SUBROUTINE LARZ(SIDE, [M], [N], L, V, [INCV], TAU, C, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
COMPLEX(8) :: TAU  
COMPLEX(8), DIMENSION(:) :: V, WORK  
COMPLEX(8), DIMENSION(:,) :: C  
INTEGER :: M, N, L, INCV, LDC
```

```
SUBROUTINE LARZ_64(SIDE, [M], [N], L, V, [INCV], TAU, C, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
COMPLEX(8) :: TAU  
COMPLEX(8), DIMENSION(:) :: V, WORK  
COMPLEX(8), DIMENSION(:,) :: C  
INTEGER(8) :: M, N, L, INCV, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zlarz(char side, int m, int n, int l, doublecomplex *v,
          int incv, doublecomplex *tau, doublecomplex *c,
          int ldc);
```

```
void zlarz_64(char side, long m, long n, long l, doublecom-
              plex *v, long incv, doublecomplex *tau, doublecom-
              plex *c, long ldc);
```

PURPOSE

zlarz applies a complex elementary reflector H to a complex M-by-N matrix C, from either the left or the right. H is represented in the form

$$H = I - \tau * v * v'$$

where tau is a complex scalar and v is a complex vector.

If tau = 0, then H is taken to be the unit matrix.

To apply H' (the conjugate transpose of H), supply conjg(tau) instead tau.

H is a product of k elementary reflectors as returned by CTZRZF.

ARGUMENTS

SIDE (input)

= 'L': form $H * C$
 = 'R': form $C * H$

M (input) The number of rows of the matrix C.

N (input) The number of columns of the matrix C.

L (input) The number of entries of the vector V containing the meaningful part of the Householder vectors. If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L \geq 0$.

V (input) The vector v in the representation of H as returned by CTZRZF. V is not used if TAU = 0.

INCV (input)

The increment between elements of v. INCV \neq 0.

TAU (input)

The value tau in the representation of H.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by the matrix $H * C$ if SIDE = 'L', or $C * H$ if SIDE = 'R'.

LDC (input)

The leading dimension of the array C. LDC \geq
max(1,M).

WORK (workspace)

(N) if SIDE = 'L' or (M) if SIDE = 'R'

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

zlarzb - apply a complex block reflector H or its transpose H^*H to a complex distributed M-by-N C from the left or the right

SYNOPSIS

```
SUBROUTINE ZLARZB(SIDE, TRANS, DIRECT, STOREV, M, N, K, L, V, LDV, T,
                 LDT, C, LDC, WORK, LDWORK)
```

```
CHARACTER * 1 SIDE, TRANS, DIRECT, STOREV
DOUBLE COMPLEX V(LDV,*), T(LDT,*), C(LDC,*), WORK(LDWORK,*)
INTEGER M, N, K, L, LDV, LDT, LDC, LDWORK
```

```
SUBROUTINE ZLARZB_64(SIDE, TRANS, DIRECT, STOREV, M, N, K, L, V, LDV,
                   T, LDT, C, LDC, WORK, LDWORK)
```

```
CHARACTER * 1 SIDE, TRANS, DIRECT, STOREV
DOUBLE COMPLEX V(LDV,*), T(LDT,*), C(LDC,*), WORK(LDWORK,*)
INTEGER*8 M, N, K, L, LDV, LDT, LDC, LDWORK
```

F95 INTERFACE

```
SUBROUTINE LARZB(SIDE, TRANS, DIRECT, STOREV, [M], [N], K, L, V, [LDV],
               T, [LDT], C, [LDC], [WORK], [LDWORK])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS, DIRECT, STOREV
COMPLEX(8), DIMENSION(:,*) :: V, T, C, WORK
INTEGER :: M, N, K, L, LDV, LDT, LDC, LDWORK
```

```
SUBROUTINE LARZB_64(SIDE, TRANS, DIRECT, STOREV, [M], [N], K, L, V,
                  [LDV], T, [LDT], C, [LDC], [WORK], [LDWORK])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS, DIRECT, STOREV
COMPLEX(8), DIMENSION(:,*) :: V, T, C, WORK
INTEGER(8) :: M, N, K, L, LDV, LDT, LDC, LDWORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zlarzb(char side, char trans, char direct, char storev,
           int m, int n, int k, int l, doublecomplex *v, int
           ldv, doublecomplex *t, int ldt, doublecomplex *c,
           int ldc, int ldwork);
```

```
void zlarzb_64(char side, char trans, char direct, char
              storev, long m, long n, long k, long l, doublecom-
              plex *v, long ldv, doublecomplex *t, long ldt,
              doublecomplex *c, long ldc, long ldwork);
```

PURPOSE

zlarzb applies a complex block reflector H or its transpose H^*H to a complex distributed M -by- N C from the left or the right.

Currently, only STOREV = 'R' and DIRECT = 'B' are supported.

ARGUMENTS

SIDE (input)

= 'L': apply H or H' from the Left
 = 'R': apply H or H' from the Right

TRANS (input)

= 'N': apply H (No transpose)
 = 'C': apply H' (Conjugate transpose)

DIRECT (input)

Indicates how H is formed from a product of elementary reflectors = 'F': $H = H(1) H(2) \dots H(k)$ (Forward, not supported yet)
 = 'B': $H = H(k) \dots H(2) H(1)$ (Backward)

STOREV (input)

Indicates how the vectors which define the elementary reflectors are stored:
 = 'C': Columnwise (not supported yet)
 = 'R': Rowwise

M (input) The number of rows of the matrix C .

N (input) The number of columns of the matrix C .

K (input) The order of the matrix T (= the number of elementary reflectors whose product defines the block reflector).

L (input) The number of columns of the matrix V containing the meaningful part of the Householder reflectors. If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L \geq 0$.

V (input) If STOREV = 'C', $NV = K$; if STOREV = 'R', $NV = L$.

LDV (input)

The leading dimension of the array V. If STOREV = 'C', LDV \geq L; if STOREV = 'R', LDV \geq K.

T (input) The triangular K-by-K matrix T in the representation of the block reflector.

LDT (input)
The leading dimension of the array T. LDT \geq K.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by H*C or H'*C or C*H or C'H'.

LDC (input)
The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)
dimension(MAX(M,N),K)

LDWORK (input)
The leading dimension of the array WORK. If SIDE = 'L', LDWORK \geq max(1,N); if SIDE = 'R', LDWORK \geq max(1,M).

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

zlarzt - form the triangular factor T of a complex block reflector H of order > n, which is defined as a product of k elementary reflectors

SYNOPSIS

```
SUBROUTINE ZLARZT(DIRECT, STOREV, N, K, V, LDV, TAU, T, LDT)
```

```
CHARACTER * 1 DIRECT, STOREV  
DOUBLE COMPLEX V(LDV,*), TAU(*), T(LDT,*)  
INTEGER N, K, LDV, LDT
```

```
SUBROUTINE ZLARZT_64(DIRECT, STOREV, N, K, V, LDV, TAU, T, LDT)
```

```
CHARACTER * 1 DIRECT, STOREV  
DOUBLE COMPLEX V(LDV,*), TAU(*), T(LDT,*)  
INTEGER*8 N, K, LDV, LDT
```

F95 INTERFACE

```
SUBROUTINE LARZT(DIRECT, STOREV, N, K, V, [LDV], TAU, T, [LDT])
```

```
CHARACTER(LEN=1) :: DIRECT, STOREV  
COMPLEX(8), DIMENSION(:) :: TAU  
COMPLEX(8), DIMENSION(:, :) :: V, T  
INTEGER :: N, K, LDV, LDT
```

```
SUBROUTINE LARZT_64(DIRECT, STOREV, N, K, V, [LDV], TAU, T, [LDT])
```

```
CHARACTER(LEN=1) :: DIRECT, STOREV  
COMPLEX(8), DIMENSION(:) :: TAU  
COMPLEX(8), DIMENSION(:, :) :: V, T  
INTEGER(8) :: N, K, LDV, LDT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zlarzt(char direct, char storev, int n, int k, doublecomplex *v, int ldv, doublecomplex *tau, doublecomplex *t)
```

```

        lecomplex *t, int ldt);

void zlarzt_64(char direct, char storev, long n, long k,
              doublecomplex *v, long ldv, doublecomplex *tau,
              doublecomplex *t, long ldt);

```

PURPOSE

zlarzt forms the triangular factor T of a complex block reflector H of order $> n$, which is defined as a product of k elementary reflectors.

If $DIRECT = 'F'$, $H = H(1) H(2) \dots H(k)$ and T is upper triangular;

If $DIRECT = 'B'$, $H = H(k) \dots H(2) H(1)$ and T is lower triangular.

If $STOREV = 'C'$, the vector which defines the elementary reflector $H(i)$ is stored in the i -th column of the array V , and

$$H = I - V * T * V'$$

If $STOREV = 'R'$, the vector which defines the elementary reflector $H(i)$ is stored in the i -th row of the array V , and

$$H = I - V' * T * V$$

Currently, only $STOREV = 'R'$ and $DIRECT = 'B'$ are supported.

ARGUMENTS

DIRECT (input)

Specifies the order in which the elementary reflectors are multiplied to form the block reflector:

= 'F': $H = H(1) H(2) \dots H(k)$ (Forward, not supported yet)

= 'B': $H = H(k) \dots H(2) H(1)$ (Backward)

STOREV (input)

Specifies how the vectors which define the elementary reflectors are stored (see also Further Details):

= 'R': rowwise

N (input) The order of the block reflector H . $N \geq 0$.

K (input) The order of the triangular factor T (= the number of elementary reflectors). $K \geq 1$.

V (input) (LDV,K) if $STOREV = 'C'$ (LDV,N) if $STOREV = 'R'$
The matrix V . See further details.

LDV (input)

The leading dimension of the array V . If $STOREV =$

'C', LDV >= max(1,N); if STOREV = 'R', LDV >= K.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i).

T (input)

The k by k triangular factor T of the block reflector. If DIRECT = 'F', T is upper triangular; if DIRECT = 'B', T is lower triangular. The rest of the array is not used.

LDT (input)

The leading dimension of the array T. LDT >= K.

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

The shape of the matrix V and the storage of the vectors which define the H(i) is best illustrated by the following example with n = 5 and k = 3. The elements equal to 1 are not stored; the corresponding array elements are modified but restored on exit. The rest of the array is not used.

DIRECT = 'F' and STOREV = 'C': DIRECT = 'F' and STOREV = 'R':

<pre> (v1 v2 v3) V = (v1 v2 v3) . . 1) . 1) (v1 v2 v3) (v1 v2 v3) . . . 1 . . . 1 1 </pre>	<pre> _____V_____ / (v1 v1 v1 v1 v1 1 (v2 v2 v2 v2 v2 . (v3 v3 v3 v3 v3 . </pre>
--	---

DIRECT = 'B' and STOREV = 'C': DIRECT = 'B' and STOREV = 'R':

<pre> . 1 . . 1 v2 v2 v2) v3 v3 v3) . . . (v1 v2 v3) V = (v1 v2 v3) (v1 v2 v3) </pre>	<pre> _____V_____ / (1 v1 v1 v1 v1 v1) (. 1 v2 v2 (. . 1 . . . v3 v3 </pre>
---	---

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NAME

zlatzm - routine is deprecated and has been replaced by routine CUNMRZ

SYNOPSIS

```
SUBROUTINE ZLATZM(SIDE, M, N, V, INCV, TAU, C1, C2, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
DOUBLE COMPLEX TAU  
DOUBLE COMPLEX V(*), C1(LDC,*), C2(LDC,*), WORK(*)  
INTEGER M, N, INCV, LDC
```

```
SUBROUTINE ZLATZM_64(SIDE, M, N, V, INCV, TAU, C1, C2, LDC, WORK)
```

```
CHARACTER * 1 SIDE  
DOUBLE COMPLEX TAU  
DOUBLE COMPLEX V(*), C1(LDC,*), C2(LDC,*), WORK(*)  
INTEGER*8 M, N, INCV, LDC
```

F95 INTERFACE

```
SUBROUTINE LATZM(SIDE, [M], [N], V, [INCV], TAU, C1, C2, [LDC], [WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
COMPLEX(8) :: TAU  
COMPLEX(8), DIMENSION(:) :: V, WORK  
COMPLEX(8), DIMENSION(:,:) :: C1, C2  
INTEGER :: M, N, INCV, LDC
```

```
SUBROUTINE LATZM_64(SIDE, [M], [N], V, [INCV], TAU, C1, C2, [LDC],  
[WORK])
```

```
CHARACTER(LEN=1) :: SIDE  
COMPLEX(8) :: TAU  
COMPLEX(8), DIMENSION(:) :: V, WORK  
COMPLEX(8), DIMENSION(:,:) :: C1, C2  
INTEGER(8) :: M, N, INCV, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zlatzm(char side, int m, int n, doublecomplex *v, int
    incv, doublecomplex *tau, doublecomplex *c1, doublecomplex *c2, int ldc);
```

```
void zlatzm_64(char side, long m, long n, doublecomplex *v,
    long incv, doublecomplex *tau, doublecomplex *c1, doublecomplex *c2, long ldc);
```

PURPOSE

zlatzm routine is deprecated and has been replaced by routine CUNMRZ.

CLATZM applies a Householder matrix generated by CTZRQF to a matrix.

Let $P = I - \tau \cdot u \cdot u'$, $u = \begin{pmatrix} 1 \\ v \end{pmatrix}$,

where v is an $(m-1)$ vector if $SIDE = 'L'$, or a $(n-1)$ vector if $SIDE = 'R'$.

If $SIDE$ equals $'L'$, let

$$C = \begin{bmatrix} C1 & 1 \\ C2 & m-1 \end{bmatrix}$$

n

Then C is overwritten by $P \cdot C$.

If $SIDE$ equals $'R'$, let

$$C = \begin{bmatrix} C1, C2 & m \\ 1 & n-1 \end{bmatrix}$$

Then C is overwritten by $C \cdot P$.

ARGUMENTS

$SIDE$ (input)

= $'L'$: form $P \cdot C$
 = $'R'$: form $C \cdot P$

M (input) The number of rows of the matrix C .

N (input) The number of columns of the matrix C .

V (input) $(1 + (M-1) \cdot \text{abs}(\text{INCV}))$ if $SIDE = 'L'$ $(1 + (N-1) \cdot \text{abs}(\text{INCV}))$ if $SIDE = 'R'$ The vector v in the representation of P . V is not used if $\text{TAU} = 0$.

INCV (input)

The increment between elements of v . $\text{INCV} \neq 0$

TAU (input)

The value τ in the representation of P .

$C1$ (input/output)

(LDC, N) if $SIDE = 'L'$ $(M, 1)$ if $SIDE = 'R'$ On entry, the n -vector $C1$ if $SIDE = 'L'$, or the m -vector $C1$ if $SIDE = 'R'$.

On exit, the first row of P*C if SIDE = 'L', or
the first column of C*P if SIDE = 'R'.

C2 (input/output)

(LDC, N) if SIDE = 'L' (LDC, N-1) if SIDE = 'R'
On entry, the (m - 1) x n matrix C2 if SIDE = 'L',
or the m x (n - 1) matrix C2 if SIDE = 'R'.

On exit, rows 2:m of P*C if SIDE = 'L', or columns
2:m of C*P if SIDE = 'R'.

LDC (input)

The leading dimension of the arrays C1 and C2.
LDC \geq max(1,M).

WORK (workspace)

(N) if SIDE = 'L' (M) if SIDE = 'R'

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NAME

zpbcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite band matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPBTRF

SYNOPSIS

```
SUBROUTINE ZPBCON(UPLO, N, KD, A, LDA, ANORM, RCOND, WORK, WORK2,
                 INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(LDA,*), WORK(*)
INTEGER N, KD, LDA, INFO
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZPBCON_64(UPLO, N, KD, A, LDA, ANORM, RCOND, WORK,
                    WORK2, INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(LDA,*), WORK(*)
INTEGER*8 N, KD, LDA, INFO
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PBCON(UPLO, [N], KD, A, [LDA], ANORM, RCOND, [WORK],
                [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER :: N, KD, LDA, INFO
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE PBCON_64(UPLO, [N], KD, A, [LDA], ANORM, RCOND, [WORK],
                   [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: N, KD, LDA, INFO
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zpbcon(char uplo, int n, int kd, doublecomplex *a, int
            lda, double anorm, double *rcond, int *info);

void zpbcon_64(char uplo, long n, long kd, doublecomplex *a,
              long lda, double anorm, double *rcond, long
              *info);

```

PURPOSE

zpbcon estimates the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite band matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPBTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangular factor stored in A;
 = 'L': Lower triangular factor stored in A.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
 The number of superdiagonals of the matrix A if UPLO = 'U', or the number of sub-diagonals if UPLO = 'L'. $KD \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ of the band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of U or L is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = U(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = L(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

LDA (input)
 The leading dimension of the array A. $LDA \geq KD+1$.

ANORM (input)
 The 1-norm (or infinity-norm) of the Hermitian band matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A , computed as $RCOND = 1/(ANORM * AINVNM)$, where $AINVNM$ is an estimate of the 1-norm of $inv(A)$ computed in this routine.

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zpbequ - compute row and column scalings intended to equilibrate a Hermitian positive definite band matrix A and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE ZPBEQU(UPLO, N, KD, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, KD, LDA, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION SCALE(*)
```

```
SUBROUTINE ZPBEQU_64(UPLO, N, KD, A, LDA, SCALE, SCOND, AMAX,  
INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, KD, LDA, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE PBEQU(UPLO, [N], KD, A, [LDA], SCALE, SCOND, AMAX,  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, KD, LDA, INFO  
REAL(8) :: SCOND, AMAX  
REAL(8), DIMENSION(:) :: SCALE
```

```
SUBROUTINE PBEQU_64(UPLO, [N], KD, A, [LDA], SCALE, SCOND, AMAX,  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, KD, LDA, INFO  
REAL(8) :: SCOND, AMAX
```

REAL(8), DIMENSION(:) :: SCALE

C INTERFACE

```
#include <sunperf.h>
```

```
void zpbequ(char uplo, int n, int kd, doublecomplex *a, int  
    lda, double *scale, double *scond, double *amax,  
    int *info);
```

```
void zpbequ_64(char uplo, long n, long kd, doublecomplex *a,  
    long lda, double *scale, double *scond, double  
    *amax, long *info);
```

PURPOSE

zpbequ computes row and column scalings intended to equilibrate a Hermitian positive definite band matrix A and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i) = 1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j) = S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular of A is stored;
= 'L': Lower triangular of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input) The upper or lower triangle of the Hermitian band matrix A, stored in the first KD+1 rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

SCALE (output)

If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)

If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND

>= 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)

Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

zpbtrfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and banded, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZPBRFS(UPLO, N, KD, NRHS, A, LDA, AF, LDAF, B, LDB, X,  
                 LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
WORK(*)  
INTEGER N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZPBRFS_64(UPLO, N, KD, NRHS, A, LDA, AF, LDAF, B, LDB,  
                    X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
WORK(*)  
INTEGER*8 N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PBRFS(UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF], B,  
                [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X  
INTEGER :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE PBRFS_64(UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF],  
                   B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK
```

```

COMPLEX(8), DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>
void zpbrfs(char uplo, int n, int kd, int nrhs, doublecom-
  plex *a, int lda, doublecomplex *af, int ldaf,
  doublecomplex *b, int ldb, doublecomplex *x, int
  ldx, double *ferr, double *berr, int *info);

void zpbrfs_64(char uplo, long n, long kd, long nrhs, doub-
  lecomplex *a, long lda, doublecomplex *af, long
  ldaf, doublecomplex *b, long ldb, doublecomplex
  *x, long ldx, double *ferr, double *berr, long
  *info);

```

PURPOSE

zpbrfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and banded, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)
 The number of superdiagonals of the matrix A if
 UPLO = 'U', or the number of subdiagonals if UPLO
 = 'L'. $KD \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number
 of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The upper or lower triangle of the Hermitian band
 matrix A, stored in the first $KD+1$ rows of the
 array. The j -th column of A is stored in the j -th
 column of the array A as follows: if UPLO = 'U',
 $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if
 UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for
 $j <= i <= \min(n, j+kd)$.

LDA (input)
 The leading dimension of the array A. $LDA \geq$
 $KD+1$.

AF (input)
 The triangular factor U or L from the Cholesky
 factorization $A = U^*H^*U$ or $A = L^*L^*H$ of the band
 matrix A as computed by ZPBTRF, in the same

storage format as A (see A).

LDAF (input)

The leading dimension of the array AF. LDAF \geq KD+1.

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)

On entry, the solution matrix X, as computed by ZPBTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zpbstf - compute a split Cholesky factorization of a complex Hermitian positive definite band matrix A

SYNOPSIS

```
SUBROUTINE ZPBSTF(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AB(LDAB,*)  
INTEGER N, KD, LDAB, INFO
```

```
SUBROUTINE ZPBSTF_64(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AB(LDAB,*)  
INTEGER*8 N, KD, LDAB, INFO
```

F95 INTERFACE

```
SUBROUTINE PBSTF(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: AB  
INTEGER :: N, KD, LDAB, INFO
```

```
SUBROUTINE PBSTF_64(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: AB  
INTEGER(8) :: N, KD, LDAB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpbstf(char uplo, int n, int kd, doublecomplex *ab, int  
          ldab, int *info);
```

```
void zpbstf_64(char uplo, long n, long kd, doublecomplex  
          *ab, long ldab, long *info);
```

PURPOSE

zpbstf computes a split Cholesky factorization of a complex Hermitian positive definite band matrix A.

This routine is designed to be used in conjunction with CHBGST.

The factorization has the form $A = S^*H^*S$ where S is a band matrix of the same bandwidth as A and the following structure:

$$S = \begin{pmatrix} U & \\ & (M \ L) \end{pmatrix}$$

where U is upper triangular of order $m = (n+kd)/2$, and L is lower triangular of order $n-m$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $kd+1$ rows of the array. The j -th column of A is stored in the j -th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the factor S from the split Cholesky factorization $A = S^*H^*S$. See Further Details.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq kd+1$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the factorization could not be completed, because the updated element $a(i, i)$ was negative; the matrix A is not positive definite.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 7$, $KD = 2$:

```
S = ( s11  s12  s13           )
     (      s22  s23  s24       )
     (           s33  s34       )
     (           s44           )
     (           s53  s54  s55   )
     (           s64  s65  s66   )
     (           s75  s76  s77 )
```

If $UPLO = 'U'$, the array AB holds:

```
on entry:                on exit:

*   *  a13  a24  a35  a46  a57  *   *  s13  s24  s53'
s64' s75'
*   a12  a23  a34  a45  a56  a67  *   s12  s23  s34  s54'
s65' s76' a11  a22  a33  a44  a55  a66  a77  s11  s22  s33
s44  s55  s66  s77
```

If $UPLO = 'L'$, the array AB holds:

```
on entry:                on exit:

a11  a22  a33  a44  a55  a66  a77  s11  s22  s33  s44  s55
s66  s77  a21  a32  a43  a54  a65  a76  *  s12' s23' s34'
s54  s65  s76  * a31  a42  a53  a64  a64  *   *   s13'
s24' s53  s64  s75  *   *
```

Array elements marked * are not used by the routine; $s12'$ denotes $\text{conjg}(s12)$; the diagonal elements of S are real.

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NAME

zpbsv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZPBSV(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE ZPBSV_64(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE PBSV(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE PBSV_64(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpbsv(char uplo, int n, int kd, int nrhs, doublecomplex  
*a, int lda, doublecomplex *b, int ldb, int  
*info);
```

```
void zpbsv_64(char uplo, long n, long kd, long nrhs, doublecomplex *a, long lda, doublecomplex *b, long ldb, long *info);
```

PURPOSE

zpbsv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N -by- N Hermitian positive definite band matrix and X and B are N -by- $NRHS$ matrices.

The Cholesky decomposition is used to factor A as

$A = U^{*H} * U$, if $UPLO = 'U'$, or

$A = L * L^{*H}$, if $UPLO = 'L'$,

where U is an upper triangular band matrix, and L is a lower triangular band matrix, with the same number of superdiagonals or subdiagonals as A . The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A . $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if $UPLO = 'U'$, or the number of subdiagonals if $UPLO = 'L'$. $KD \geq 0$.

$NRHS$ (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A , stored in the first $KD+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if $UPLO = 'U'$, $A(KD+1+i-j,j) = A(i,j)$ for $\max(1,j-KD) \leq i \leq j$; if $UPLO = 'L'$, $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(N,j+KD)$. See below for further details.

On exit, if $INFO = 0$, the triangular factor U or L from the Cholesky factorization $A = U^{*H}U$ or $A = L * L^{*H}$ of the band matrix A , in the same storage format as A .

LDA (input)

The leading dimension of the array A . $LDA \geq KD+1$.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B.
On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when N = 6, KD = 2, and UPLO = 'U':

On entry:

```
      *   *   a13 a24 a35 a46
u46  *   a12 a23 a34 a45 a56
u56  a11 a22 a33 a44 a55 a66
u66
```

On exit:

```
      *   *   u13 u24 u35
      *   u12 u23 u34 u45
      u11 u22 u33 u44 u55
      u66
```

Similarly, if UPLO = 'L' the format of A is as follows:

On entry:

```
      a11 a22 a33 a44 a55 a66
l66  a21 a32 a43 a54 a56 *
      *   a31 a42 a53 a64 *   *
      *
```

On exit:

```
      l11 l22 l33 l44 l55
      l21 l32 l43 l54 l65
      l31 l42 l53 l64 *
```

Array elements marked * are not used by the routine.

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NAME

zpbsvx - use the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZPBSVX(FACT, UPLO, N, KD, NRHS, A, LDA, AF, LDAF,
    EQUED, S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2,
    INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
DOUBLE PRECISION RCOND
DOUBLE PRECISION S(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZPBSVX_64(FACT, UPLO, N, KD, NRHS, A, LDA, AF, LDAF,
    EQUED, S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2,
    INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),
WORK(*)
INTEGER*8 N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
DOUBLE PRECISION RCOND
DOUBLE PRECISION S(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PBSVX(FACT, UPLO, [N], KD, [NRHS], A, [LDA], AF, [LDAF],
    EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],
    [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL(8) :: RCOND
```

```

REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK2

SUBROUTINE PBSVX_64(FACT, UPLO, [N], KD, [NRHS], A, [LDA], AF,
  [LDAF], EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR,
  [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER(8) :: N, KD, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zpbsvx(char fact, char uplo, int n, int kd, int nrhs,
  doublecomplex *a, int lda, doublecomplex *af, int
  ldaf, char equed, double *s, doublecomplex *b, int
  ldb, doublecomplex *x, int ldx, double *rcond,
  double *ferr, double *berr, int *info);

void zpbsvx_64(char fact, char uplo, long n, long kd, long
  nrhs, doublecomplex *a, long lda, doublecomplex
  *af, long ldaf, char equed, double *s, doublecom-
  plex *b, long ldb, doublecomplex *x, long ldx,
  double *rcond, double *ferr, double *berr, long
  *info);

```

PURPOSE

zpbsvx uses the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations

$A * X = B$, where A is an N -by- N Hermitian positive definite band matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$) as

$$A = U^*H * U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L^*H, \text{ if } UPLO = 'L',$$

where U is an upper triangular band matrix, and L is a

lower
triangular band matrix.

3. If the leading i -by- i principal minor is not positive definite,
then the routine returns with `INFO = i`. Otherwise, the factored form of A is used to estimate the condition number of the matrix
A. If the reciprocal of the condition number is less than machine precision, `INFO = N+1` is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
4. The system of equations is solved for X using the factored form of A .
5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.
6. If equilibration was used, the matrix X is premultiplied by `diag(S)` so that it solves the original system before equilibration.

ARGUMENTS

`FACT` (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, `AF` contains the factored form of A . If `EQUED = 'Y'`, the matrix A has been equilibrated with scaling factors given by S . A and `AF` will not be modified. = 'N': The matrix A will be copied to `AF` and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to `AF` and factored.

`UPLO` (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

`N` (input) The number of linear equations, i.e., the order of the matrix A . $N \geq 0$.

`KD` (input)

The number of superdiagonals of the matrix A if `UPLO = 'U'`, or the number of subdiagonals if `UPLO = 'L'`. $KD \geq 0$.

`NRHS` (input)

The number of right-hand sides, i.e., the number of columns of the matrices B and X . $NRHS \geq 0$.

A (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first KD+1 rows of the array, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix $\text{diag}(S)*A*\text{diag}(S)$. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(KD+1+i-j,j) = A(i,j)$ for $\max(1,j-KD) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(N,j+KD)$. See below for further details.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S)*A*\text{diag}(S)$.

LDA (input)

The leading dimension of the array A. LDA \geq KD+1.

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ of the band matrix A, in the same storage format as A (see A). If EQUED = 'Y', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF \geq KD+1.

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)
 The leading dimension of the array B. LDB \geq max(1,N).

X (output)
 If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is inv(diag(S))*X.

LDX (input)
 The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)
 The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)
 The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
 The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 dimension(2*N)

WORK2 (workspace)
 dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, and i is
 <= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is non-singular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution

can be more accurate than the value of RCOND would suggest.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 6$, $KD = 2$, and $UPLO = 'U'$:

Two-dimensional storage of the Hermitian matrix A:

```
a11 a12 a13
      a22 a23 a24
            a33 a34 a35
                  a44 a45 a46
                        a55 a56
(aij=conjg(aji))          a66
```

Band storage of the upper triangle of A:

```
*      *   a13 a24 a35 a46
*   a12 a23 a34 a45 a56
a11 a22 a33 a44 a55 a66
```

Similarly, if $UPLO = 'L'$ the format of A is as follows:

```
a11 a22 a33 a44 a55 a66
a21 a32 a43 a54 a65 *
a31 a42 a53 a64 *   *
```

Array elements marked * are not used by the routine.

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NAME

zpbtf2 - compute the Cholesky factorization of a complex Hermitian positive definite band matrix A

SYNOPSIS

```
SUBROUTINE ZPBTf2(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AB(LDAB,*)  
INTEGER N, KD, LDAB, INFO
```

```
SUBROUTINE ZPBTf2_64(UPLO, N, KD, AB, LDAB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AB(LDAB,*)  
INTEGER*8 N, KD, LDAB, INFO
```

F95 INTERFACE

```
SUBROUTINE PBTf2(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: AB  
INTEGER :: N, KD, LDAB, INFO
```

```
SUBROUTINE PBTf2_64(UPLO, [N], KD, AB, [LDAB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: AB  
INTEGER(8) :: N, KD, LDAB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpbtf2(char uplo, int n, int kd, doublecomplex *ab, int  
          ldab, int *info);
```

```
void zpbtf2_64(char uplo, long n, long kd, doublecomplex  
          *ab, long ldab, long *info);
```

PURPOSE

zpbtf2 computes the Cholesky factorization of a complex Hermitian positive definite band matrix A.

The factorization has the form

$A = U' * U$, if UPLO = 'U', or

$A = L * L'$, if UPLO = 'L',

where U is an upper triangular matrix, U' is the conjugate transpose of U, and L is lower triangular.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the Hermitian matrix A is stored:

= 'U': Upper triangular

= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of super-diagonals of the matrix A if UPLO = 'U', or the number of sub-diagonals if UPLO = 'L'. $KD \geq 0$.

AB (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first KD+1 rows of the array. The j-th column of A is stored in the j-th column of the array AB as follows: if UPLO = 'U', $AB(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $AB(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U' * U$ or $A = L * L'$ of the band matrix A, in the same storage format as A.

LDAB (input)

The leading dimension of the array AB. $LDAB \geq KD+1$.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, the leading minor of order k is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The band storage scheme is illustrated by the following example, when $N = 6$, $KD = 2$, and $UPLD = 'U'$:

On entry:	On exit:
* * a13 a24 a35 a46	* * u13 u24 u35
u46	
* a12 a23 a34 a45 a56	* u12 u23 u34 u45
u56	
a11 a22 a33 a44 a55 a66	u11 u22 u33 u44 u55
u66	

Similarly, if $UPLD = 'L'$ the format of A is as follows:

On entry:	On exit:
a11 a22 a33 a44 a55 a66	l11 l22 l33 l44 l55
l66	
a21 a32 a43 a54 a65 *	l21 l32 l43 l54 l65
*	
a31 a42 a53 a64 * *	l31 l42 l53 l64 *
*	

Array elements marked * are not used by the routine.

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NAME

zpbtrf - compute the Cholesky factorization of a complex Hermitian positive definite band matrix A

SYNOPSIS

```
SUBROUTINE ZPBTRF(UPLO, N, KD, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, KD, LDA, INFO
```

```
SUBROUTINE ZPBTRF_64(UPLO, N, KD, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, KD, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE PBTRF(UPLO, [N], KD, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A  
INTEGER :: N, KD, LDA, INFO
```

```
SUBROUTINE PBTRF_64(UPLO, [N], KD, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A  
INTEGER(8) :: N, KD, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpbtrf(char uplo, int n, int kd, doublecomplex *a, int  
lda, int *info);
```

```
void zpbtrf_64(char uplo, long n, long kd, doublecomplex *a,  
long lda, long *info);
```

PURPOSE

zpbtrf computes the Cholesky factorization of a complex Hermitian positive definite band matrix A.

The factorization has the form

$A = U^{*H} * U$, if UPLO = 'U', or

$A = L * L^{*H}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if UPLO = 'U', or the number of subdiagonals if UPLO = 'L'. $KD \geq 0$.

A (input/output)

On entry, the upper or lower triangle of the Hermitian band matrix A, stored in the first $KD+1$ rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{*H}U$ or $A = L * L^{*H}$ of the band matrix A, in the same storage format as A.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The band storage scheme is illustrated by the following

example, when $N = 6$, $KD = 2$, and $UPLO = 'U'$:

On entry:

On exit:

```
      *      *      a13  a24  a35  a46      *      *      u13  u24  u35
u46
      *      a12  a23  a34  a45  a56      *      u12  u23  u34  u45
u56
      a11  a22  a33  a44  a55  a66      u11  u22  u33  u44  u55
u66
```

Similarly, if $UPLO = 'L'$ the format of A is as follows:

On entry:

On exit:

```
      a11  a22  a33  a44  a55  a66      111  122  133  144  155
166
      a21  a32  a43  a54  a65  *      121  132  143  154  165
*
      a31  a42  a53  a64  *      *      131  142  153  164  *
*
```

Array elements marked * are not used by the routine.

Contributed by

Peter Mayes and Giuseppe Radicati, IBM ECSEC, Rome, March
23, 1989

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NAME

zpbtrs - solve a system of linear equations $A \cdot X = B$ with a Hermitian positive definite band matrix A using the Cholesky factorization $A = U \cdot H \cdot U$ or $A = L \cdot L \cdot H$ computed by ZPBTRF

SYNOPSIS

```
SUBROUTINE ZPBTRS(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE ZPBTRS_64(UPLO, N, KD, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE PBTRS(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE PBTRS_64(UPLO, [N], KD, [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpbtrs(char uplo, int n, int kd, int nrhs, doublecom-  
plex *a, int lda, doublecomplex *b, int ldb, int  
*info);
```

```
void zpbtrs_64(char uplo, long n, long kd, long nrhs, doub-
```

```
lecomplex *a, long lda, doublecomplex *b, long
ldb, long *info);
```

PURPOSE

zpbtrs solves a system of linear equations $A \cdot X = B$ with a Hermitian positive definite band matrix A using the Cholesky factorization $A = U \cdot U^H$ or $A = L \cdot L^H$ computed by ZPBTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular factor stored in A;
= 'L': Lower triangular factor stored in A.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals of the matrix A if
UPLO = 'U', or the number of subdiagonals if UPLO
= 'L'. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number
of columns of the matrix B. $NRHS \geq 0$.

A (input) The triangular factor U or L from the Cholesky
factorization $A = U \cdot U^H$ or $A = L \cdot L^H$ of the band
matrix A, stored in the first $KD+1$ rows of the
array. The j -th column of U or L is stored in the
 j -th column of the array A as follows: if UPLO
= 'U', $A(kd+1+i-j, j) = U(i, j)$ for $\max(1, j-
kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j, j) = L(i, j)$
for $j \leq i \leq \min(n, j+kd)$.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $KD+1$.

B (input/output)

On entry, the right hand side matrix B. On exit,
the solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq$
 $\max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an
illegal value

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NAME

zpocon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPOTRF

SYNOPSIS

```
SUBROUTINE ZPOCON(UPLO, N, A, LDA, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZPOCON_64(UPLO, N, A, LDA, ANORM, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE POCON(UPLO, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A  
INTEGER :: N, LDA, INFO  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE POCON_64(UPLO, [N], A, [LDA], ANORM, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK
```

```
COMPLEX(8), DIMENSION(:,:) :: A
INTEGER(8) :: N, LDA, INFO
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void zpocon(char uplo, int n, doublecomplex *a, int lda,
            double anorm, double *rcond, int *info);

void zpocon_64(char uplo, long n, doublecomplex *a, long
              lda, double anorm, double *rcond, long *info);
```

PURPOSE

zpocon estimates the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPOTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$, as computed by ZPOTRF.

LDA (input)
The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

ANORM (input)
The 1-norm (or infinity-norm) of the Hermitian matrix A.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zpoequ - compute row and column scalings intended to equilibrate a Hermitian positive definite matrix A and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE ZPOEQU(N, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
DOUBLE COMPLEX A(LDA,*)
INTEGER N, LDA, INFO
DOUBLE PRECISION SCOND, AMAX
DOUBLE PRECISION SCALE(*)
```

```
SUBROUTINE ZPOEQU_64(N, A, LDA, SCALE, SCOND, AMAX, INFO)
```

```
DOUBLE COMPLEX A(LDA,*)
INTEGER*8 N, LDA, INFO
DOUBLE PRECISION SCOND, AMAX
DOUBLE PRECISION SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE POEQU([N], A, [LDA], SCALE, SCOND, AMAX, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER :: N, LDA, INFO
REAL(8) :: SCOND, AMAX
REAL(8), DIMENSION(:) :: SCALE
```

```
SUBROUTINE POEQU_64([N], A, [LDA], SCALE, SCOND, AMAX, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A
INTEGER(8) :: N, LDA, INFO
REAL(8) :: SCOND, AMAX
REAL(8), DIMENSION(:) :: SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpoequ(int n, doublecomplex *a, int lda, double *scale,
            double *scond, double *amax, int *info);
```

```
void zpoequ_64(long n, doublecomplex *a, long lda, double
               *scale, double *scond, double *amax, long *info);
```

PURPOSE

zpoequ computes row and column scalings intended to equilibrate a Hermitian positive definite matrix A and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i) = 1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j) = S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

A (input) The N-by-N Hermitian positive definite matrix whose scaling factors are to be computed. Only the diagonal elements of A are referenced.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

SCALE (output)
If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)
If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)
Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

zporfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite,

SYNOPSIS

```
SUBROUTINE ZPORFS(UPLO, N, NRHS, A, LDA, AF, LDAF, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZPORFS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, B, LDB, X, LDX,  
  FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PORFS(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE PORFS_64(UPLO, [N], [NRHS], A, [LDA], AF, [LDAF], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
```

```
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>
void zporfs(char uplo, int n, int nrhs, doublecomplex *a,
            int lda, doublecomplex *af, int ldaf, doublecom-
            plex *b, int ldb, doublecomplex *x, int ldx, dou-
            ble *ferr, double *berr, int *info);

void zporfs_64(char uplo, long n, long nrhs, doublecomplex
               *a, long lda, doublecomplex *af, long ldaf, doub-
               lecomplex *b, long ldb, doublecomplex *x, long
               ldx, double *ferr, double *berr, long *info);
```

PURPOSE

zporfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)
The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)
The triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$, as computed by ZPOTRF.

LDAF (input)
The leading dimension of the array AF. $LDAF \geq \max(1, N)$.

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by
ZPOTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq
max(1,N).

FERR (output)
The estimated forward error bound for each solu-
tion vector X(j) (the j-th column of the solution
matrix X). If XTRUE is the true solution
corresponding to X(j), FERR(j) is an estimated
upper bound for the magnitude of the largest ele-
ment in (X(j) - XTRUE) divided by the magnitude of
the largest element in X(j). The estimate is as
reliable as the estimate for RCOND, and is almost
always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each
solution vector X(j) (i.e., the smallest relative
change in any element of A or B that makes X(j) an
exact solution).

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an
illegal value

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NAME

zposv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZPOSV(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE ZPOSV_64(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE POSV(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE POSV_64(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zposv(char uplo, int n, int nrhs, doublecomplex *a, int  
          lda, doublecomplex *b, int ldb, int *info);
```

```
void zposv_64(char uplo, long n, long nrhs, doublecomplex  
             *a, long lda, doublecomplex *b, long ldb, long  
             *info);
```

PURPOSE

zposv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N Hermitian positive definite matrix and X and B are N-by-NRHS matrices.

The Cholesky decomposition is used to factor A as

$A = U^{*}H * U$, if UPLO = 'U', or

$A = L * L^{*}H$, if UPLO = 'L',

where U is an upper triangular matrix and L is a lower triangular matrix. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{*}H * U$ or $A = L * L^{*}H$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i of

A is not positive definite, so the factorization could not be completed, and the solution has not been computed.

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NAME

zposvx - use the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZPOSVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, EQUED,  
  S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION S(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZPOSVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, EQUED,  
  S, B, LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION S(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE POSVX(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],  
  EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],  
  [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK2
```

```
SUBROUTINE POSVX_64(FACT, UPLO, [N], [NRHS], A, [LDA], AF, [LDAF],  
  EQUED, S, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK],
```

```

        [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK2
C INTERFACE
#include <sunperf.h>

void zposvx(char fact, char uplo, int n, int nrhs, doublecomplex *a, int lda, doublecomplex *af, int ldaf, char equed, double *s, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *rcond, double *ferr, double *berr, int *info);

void zposvx_64(char fact, char uplo, long n, long nrhs, doublecomplex *a, long lda, doublecomplex *af, long ldaf, char equed, double *s, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zposvx uses the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations

$A * X = B$, where A is an N -by- N Hermitian positive definite matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$) as

$$A = U^*H^*U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L^*H, \text{ if } UPLO = 'L',$$

where U is an upper triangular matrix and L is a lower triangular matrix.

3. If the leading i -by- i principal minor is not positive definite,

then the routine returns with INFO = i. Otherwise, the factored form of A is used to estimate the condition number of the matrix A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.
5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.
6. If equilibration was used, the matrix X is premultiplied by diag(S) so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF contains the factored form of A. If EQUED = 'Y', the matrix A has been equilibrated with scaling factors given by S. A and AF will not be modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input/output)

On entry, the Hermitian matrix A, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix diag(S)*A*diag(S). If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower tri-

angular part of the matrix A, and the strictly upper triangular part of A is not referenced. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED = 'N' on exit.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S) * A * \text{diag}(S)$.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U * H * U$ or $A = L * L * H$, in the same storage format as A. If EQUED \neq 'N', then AF is the factored form of the equilibrated matrix $\text{diag}(S) * A * \text{diag}(S)$.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * H * U$ or $A = L * L * H$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U * H * U$ or $A = L * L * H$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

LDAF (input)

The leading dimension of the array AF. LDAF \geq max(1,N).

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output)

On entry, the N-by-NRHS righthand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (output)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is $\text{inv}(\text{diag}(S))*X$.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO $>$ 0.

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
 \leq N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is non-singular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

zpotf2 - compute the Cholesky factorization of a complex Hermitian positive definite matrix A

SYNOPSIS

```
SUBROUTINE ZPOTF2(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE ZPOTF2_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE POTF2(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE POTF2_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpotf2(char uplo, int n, doublecomplex *a, int lda, int  
*info);
```

```
void zpotf2_64(char uplo, long n, doublecomplex *a, long  
lda, long *info);
```

PURPOSE

zpotf2 computes the Cholesky factorization of a complex Hermitian positive definite matrix A.

The factorization has the form

$A = U^* U$, if UPLO = 'U', or

$A = L L^*$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the Hermitian matrix A is stored. = 'U': Upper triangular
= 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading n by n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n by n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^*U$ or $A = L L^*$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value
> 0: if INFO = k, the leading minor of order k is not positive definite, and the factorization could not be completed.

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NAME

zpotrf - compute the Cholesky factorization of a complex Hermitian positive definite matrix A

SYNOPSIS

```
SUBROUTINE ZPOTRF(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE ZPOTRF_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE POTRF(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE POTRF_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpotrf(char uplo, int n, doublecomplex *a, int lda, int  
           *info);
```

```
void zpotrf_64(char uplo, long n, doublecomplex *a, long  
             lda, long *info);
```

PURPOSE

zpotrf computes the Cholesky factorization of a complex Hermitian positive definite matrix A.

The factorization has the form

$A = U^{*H} * U$, if UPLO = 'U', or

$A = L * L^{*H}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

This is the block version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the Hermitian matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{*H}U$ or $A = L^{*H}L$.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

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NAME

zpotri - compute the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPOTRF

SYNOPSIS

```
SUBROUTINE ZPOTRI(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE ZPOTRI_64(UPLO, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE POTRI(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE POTRI_64(UPLO, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpotri(char uplo, int n, doublecomplex *a, int lda, int  
*info);
```

```
void zpotri_64(char uplo, long n, doublecomplex *a, long  
lda, long *info);
```

PURPOSE

zpotri computes the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$ computed by ZPOTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$, as computed by ZPOTRF. On exit, the upper or lower triangle of the (Hermitian) inverse of A, overwriting the input factor U or L.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value
> 0: if $INFO = i$, the (i,i) element of the factor U or L is zero, and the inverse could not be computed.

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NAME

zpotrs - solve a system of linear equations $A \cdot X = B$ with a Hermitian positive definite matrix A using the Cholesky factorization $A = U \cdot H \cdot U$ or $A = L \cdot L^* \cdot H$ computed by ZPOTRF

SYNOPSIS

```
SUBROUTINE ZPOTRS(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE ZPOTRS_64(UPLO, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE POTRS(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE POTRS_64(UPLO, [N], [NRHS], A, [LDA], B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpotrs(char uplo, int n, int nrhs, doublecomplex *a,  
            int lda, doublecomplex *b, int ldb, int *info);
```

```
void zpotrs_64(char uplo, long n, long nrhs, doublecomplex  
               *a, long lda, doublecomplex *b, long ldb, long  
               *info);
```

PURPOSE

zpotrs solves a system of linear equations $A \cdot X = B$ with a Hermitian positive definite matrix A using the Cholesky factorization $A = U \cdot U^H$ or $A = L \cdot L^H$ computed by ZPOTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The triangular factor U or L from the Cholesky factorization $A = U \cdot U^H$ or $A = L \cdot L^H$, as computed by ZPOTRF.

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, N)$.

B (input/output)

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

zppcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite packed matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPPTRF

SYNOPSIS

```
SUBROUTINE ZPPCON(UPLO, N, A, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZPPCON_64(UPLO, N, A, ANORM, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
DOUBLE PRECISION ANORM, RCOND  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PPCON(UPLO, [N], A, ANORM, RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE PPCON_64(UPLO, [N], A, ANORM, RCOND, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
REAL(8) :: ANORM, RCOND  
REAL(8), DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>

void zppcon(char uplo, int n, doublecomplex *a, double
            anorm, double *rcond, int *info);
void zppcon_64(char uplo, long n, doublecomplex *a, double
              anorm, double *rcond, long *info);
```

PURPOSE

zppcon estimates the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite packed matrix using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ computed by ZPPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$

The triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$, packed columnwise in a linear array. The j-th column of U or L is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = U(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = L(i,j)$ for $j \leq i \leq n$.

ANORM (input)

The 1-norm (or infinity-norm) of the Hermitian matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

COMPLEX*16 array, dimension $(2*N)$

WORK2 (workspace)

DOUBLE PRECISION array, dimension (N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zppequ - compute row and column scalings intended to equilibrate a Hermitian positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm)

SYNOPSIS

```
SUBROUTINE ZPPEQU(UPLO, N, A, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*)  
INTEGER N, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION SCALE(*)
```

```
SUBROUTINE ZPPEQU_64(UPLO, N, A, SCALE, SCOND, AMAX, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*)  
INTEGER*8 N, INFO  
DOUBLE PRECISION SCOND, AMAX  
DOUBLE PRECISION SCALE(*)
```

F95 INTERFACE

```
SUBROUTINE PPEQU(UPLO, [N], A, SCALE, SCOND, AMAX, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER :: N, INFO  
REAL(8) :: SCOND, AMAX  
REAL(8), DIMENSION(:) :: SCALE
```

```
SUBROUTINE PPEQU_64(UPLO, [N], A, SCALE, SCOND, AMAX, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER(8) :: N, INFO  
REAL(8) :: SCOND, AMAX  
REAL(8), DIMENSION(:) :: SCALE
```

C INTERFACE

```
#include <sunperf.h>

void zppequ(char uplo, int n, doublecomplex *a, double
            *scale, double *scond, double *amax, int *info);
void zppequ_64(char uplo, long n, doublecomplex *a, double
            *scale, double *scond, double *amax, long *info);
```

PURPOSE

zppequ computes row and column scalings intended to equilibrate a Hermitian positive definite matrix A in packed storage and reduce its condition number (with respect to the two-norm). S contains the scale factors, $S(i)=1/\sqrt{A(i,i)}$, chosen so that the scaled matrix B with elements $B(i,j)=S(i)*A(i,j)*S(j)$ has ones on the diagonal. This choice of S puts the condition number of B within a factor N of the smallest possible condition number over all possible diagonal scalings.

ARGUMENTS

UPLO (input)
= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$
The upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

SCALE (output) DOUBLE PRECISION array, dimension (N)
If INFO = 0, SCALE contains the scale factors for A.

SCOND (output)
If INFO = 0, SCALE contains the ratio of the smallest SCALE(i) to the largest SCALE(i). If SCOND ≥ 0.1 and AMAX is neither too large nor too small, it is not worth scaling by SCALE.

AMAX (output)
Absolute value of largest matrix element. If AMAX is very close to overflow or very close to underflow, the matrix should be scaled.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element is nonpositive.

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NAME

zpprfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZPPRFS(UPLO, N, NRHS, A, AF, B, LDB, X, LDX, FERR, BERR,  
                WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZPPRFS_64(UPLO, N, NRHS, A, AF, B, LDB, X, LDX, FERR,  
                   BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PPRFS(UPLO, [N], [NRHS], A, AF, B, [LDB], X, [LDX], FERR,  
                BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, AF, WORK  
COMPLEX(8), DIMENSION(:, :) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE PPRFS_64(UPLO, [N], [NRHS], A, AF, B, [LDB], X, [LDX], FERR,  
                   BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, AF, WORK  
COMPLEX(8), DIMENSION(:, :) :: B, X  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

```
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpprfs(char uplo, int n, int nrhs, doublecomplex *a,  
            doublecomplex *af, doublecomplex *b, int ldb,  
            doublecomplex *x, int ldx, double *ferr, double  
            *berr, int *info);
```

```
void zpprfs_64(char uplo, long n, long nrhs, doublecomplex  
               *a, doublecomplex *af, doublecomplex *b, long ldb,  
               doublecomplex *x, long ldx, double *ferr, double  
               *berr, long *info);
```

PURPOSE

zpprfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$

The upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

AF (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$

The triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$, as computed by DPPTRF/ZPPTRF, packed columnwise in a linear array in the same format as A (see A).

B (input) COMPLEX*16 array, dimension (LDB,NRHS)

The right hand side matrix B.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

X (input/output) COMPLEX*16 array, dimension (LDX,NRHS)

On entry, the solution matrix X, as computed by ZPPTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. $LDX \geq \max(1, N)$.

FERR (output) DOUBLE PRECISION array, dimension (NRHS)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) DOUBLE PRECISION array, dimension (NRHS)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

COMPLEX*16 array, dimension(2*N)

WORK2 (workspace)

DOUBLE PRECISION array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zppsv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZPPSV(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO
```

```
SUBROUTINE ZPPSV_64(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE PPSV(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO
```

```
SUBROUTINE PPSV_64(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zppsv(char uplo, int n, int nrhs, doublecomplex *a,  
           doublecomplex *b, int ldb, int *info);
```

```
void zpssv_64(char uplo, long n, long nrhs, doublecomplex
             *a, doublecomplex *b, long ldb, long *info);
```

PURPOSE

zpssv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N Hermitian positive definite matrix stored in packed format and X and B are N-by-NRHS matrices.

The Cholesky decomposition is used to factor A as

$A = U^{*}H*U$, if UPLO = 'U', or

$A = L * L^{*}H$, if UPLO = 'L',

where U is an upper triangular matrix and L is a lower triangular matrix. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, if INFO = 0, the factor U or L from the Cholesky factorization $A = U^{*}H*U$ or $A = L*L^{*}H$, in the same storage format as A.

B (input/output) COMPLEX*16 array, dimension (LDB,NRHS)

On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-

gal value
> 0: if INFO = i, the leading minor of order i of
A is not positive definite, so the factorization
could not be completed, and the solution has not
been computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following
example when N = 4, UPLO = 'U':

Two-dimensional storage of the Hermitian matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34 (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

```
A = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

zppsvx - use the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZPPSVX(FACT, UPLO, N, NRHS, A, AF, EQUED, S, B, LDB,
  X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
DOUBLE PRECISION RCOND
DOUBLE PRECISION S(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZPPSVX_64(FACT, UPLO, N, NRHS, A, AF, EQUED, S, B,
  LDB, X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO, EQUED
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
DOUBLE PRECISION RCOND
DOUBLE PRECISION S(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PPSVX(FACT, UPLO, [N], [NRHS], A, AF, EQUED, S, B,
  [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX(8), DIMENSION(:) :: A, AF, WORK
COMPLEX(8), DIMENSION(:, :) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK2
```

```
SUBROUTINE PPSVX_64(FACT, UPLO, [N], [NRHS], A, AF, EQUED, S, B,
  [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: FACT, UPLO, EQUED
COMPLEX(8), DIMENSION(:) :: A, AF, WORK
COMPLEX(8), DIMENSION(:,:) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: S, FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>
void zppsvx(char fact, char uplo, int n, int nrhs, doublecomplex *a, doublecomplex *af, char equed, double *s, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *rcond, double *ferr, double *berr, int *info);

void zppsvx_64(char fact, char uplo, long n, long nrhs, doublecomplex *a, doublecomplex *af, char equed, double *s, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zppsvx uses the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^*H$ to compute the solution to a complex system of linear equations

$A * X = B$, where A is an N -by- N Hermitian positive definite matrix stored in packed format and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'E'$, real scaling factors are computed to equilibrate

the system:

$$\text{diag}(S) * A * \text{diag}(S) * \text{inv}(\text{diag}(S)) * X = \text{diag}(S) * B$$

Whether or not the system will be equilibrated depends on the

scaling of the matrix A , but if equilibration is used, A

is

overwritten by $\text{diag}(S)*A*\text{diag}(S)$ and B by $\text{diag}(S)*B$.

2. If $FACT = 'N'$ or $'E'$, the Cholesky decomposition is used to

factor the matrix A (after equilibration if $FACT = 'E'$)

as

$$A = U^* * U, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * L', \text{ if } UPLO = 'L',$$

where U is an upper triangular matrix, L is a lower triangular

matrix, and $'$ indicates conjugate transpose.

3. If the leading i -by- i principal minor is not positive definite,

then the routine returns with $INFO = i$. Otherwise, the factored

form of A is used to estimate the condition number of the matrix

A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

4. The system of equations is solved for X using the factored form of A.

5. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

6. If equilibration was used, the matrix X is premultiplied by $\text{diag}(S)$ so that it solves the original system before equilibration.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of the matrix A is supplied on entry, and if not, whether the matrix A should be equilibrated before it is factored. = 'F': On entry, AF contains the factored form of A. If EQUED = 'Y', the matrix A has been equilibrated with scaling factors given by S. A and AF will not be modified. = 'N': The matrix A will be copied to AF and factored. = 'E': The matrix A will be equilibrated if necessary, then copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array, except if FACT = 'F' and EQUED = 'Y', then A must contain the equilibrated matrix $\text{diag}(S)*A*\text{diag}(S)$. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details. A is not modified if FACT = 'F' or 'N', or if FACT = 'E' and EQUED =

'N' on exit.

On exit, if FACT = 'E' and EQUED = 'Y', A is overwritten by $\text{diag}(S) * A * \text{diag}(S)$.

AF (input or output) COMPLEX*16 array, dimension $(N*(N+1)/2)$
If FACT = 'F', then AF is an input argument and on entry contains the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$, in the same storage format as A. If EQUED .ne. 'N', then AF is the factored form of the equilibrated matrix A.

If FACT = 'N', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ of the original matrix A.

If FACT = 'E', then AF is an output argument and on exit returns the triangular factor U or L from the Cholesky factorization $A = U**H*U$ or $A = L*L**H$ of the equilibrated matrix A (see the description of A for the form of the equilibrated matrix).

EQUED (input or output)

Specifies the form of equilibration that was done.
= 'N': No equilibration (always true if FACT = 'N').
= 'Y': Equilibration was done, i.e., A has been replaced by $\text{diag}(S) * A * \text{diag}(S)$. EQUED is an input argument if FACT = 'F'; otherwise, it is an output argument.

S (input or output) DOUBLE PRECISION array, dimension (N)

The scale factors for A; not accessed if EQUED = 'N'. S is an input argument if FACT = 'F'; otherwise, S is an output argument. If FACT = 'F' and EQUED = 'Y', each element of S must be positive.

B (input/output) COMPLEX*16 array, dimension (LDB, NRHS)

On entry, the N-by-NRHS right hand side matrix B. On exit, if EQUED = 'N', B is not modified; if EQUED = 'Y', B is overwritten by $\text{diag}(S) * B$.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

X (output) COMPLEX*16 array, dimension (LDX, NRHS)

If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X to the original system of equations. Note that if EQUED = 'Y', A and B are modified on exit, and the solution to the equilibrated system is $\text{inv}(\text{diag}(S)) * X$.

LDX (input)

The leading dimension of the array X. $LDX \geq \max(1, N)$.

RCOND (output)

The estimate of the reciprocal condition number of the matrix A after equilibration (if done). If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output) DOUBLE PRECISION array, dimension (NRHS)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) DOUBLE PRECISION array, dimension (NRHS)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
COMPLEX*16 array, dimension(2*N)

WORK2 (workspace)
DOUBLE PRECISION array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when N = 4, UPLO = 'U':

Two-dimensional storage of the Hermitian matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34      (aij = conjg(aji))
            a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

zpptrf - compute the Cholesky factorization of a complex Hermitian positive definite matrix A stored in packed format

SYNOPSIS

```
SUBROUTINE ZPPTRF(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*)  
INTEGER N, INFO
```

```
SUBROUTINE ZPPTRF_64(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*)  
INTEGER*8 N, INFO
```

F95 INTERFACE

```
SUBROUTINE PPTRF(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER :: N, INFO
```

```
SUBROUTINE PPTRF_64(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER(8) :: N, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpptrf(char uplo, int n, doublecomplex *a, int *info);
```

```
void zpptrf_64(char uplo, long n, doublecomplex *a, long  
*info);
```

PURPOSE

zpptrf computes the Cholesky factorization of a complex Hermitian positive definite matrix A stored in packed format.

The factorization has the form

$A = U^{*H} * U$, if UPLO = 'U', or

$A = L * L^{*H}$, if UPLO = 'L',

where U is an upper triangular matrix and L is lower triangular.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangle of the Hermitian matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, if INFO = 0, the triangular factor U or L from the Cholesky factorization $A = U^{*H}U$ or $A = L*L^{*H}$, in the same storage format as A.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the leading minor of order i is not positive definite, and the factorization could not be completed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when $N = 4$, UPLO = 'U':

Two-dimensional storage of the Hermitian matrix A:

```
  a11 a12 a13 a14
    a22 a23 a24
      a33 a34   (aij = conjg(aji))
        a44
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

zpptri - compute the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$ computed by ZPPTRF

SYNOPSIS

```
SUBROUTINE ZPPTRI(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*)  
INTEGER N, INFO
```

```
SUBROUTINE ZPPTRI_64(UPLO, N, A, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*)  
INTEGER*8 N, INFO
```

F95 INTERFACE

```
SUBROUTINE PPTRI(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER :: N, INFO
```

```
SUBROUTINE PPTRI_64(UPLO, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER(8) :: N, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpptri(char uplo, int n, doublecomplex *a, int *info);
```

```
void zpptri_64(char uplo, long n, doublecomplex *a, long  
*info);
```

PURPOSE

zpptri computes the inverse of a complex Hermitian positive definite matrix A using the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$ computed by ZPPTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangular factor is stored in A;
= 'L': Lower triangular factor is stored in A.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the triangular factor U or L from the Cholesky factorization $A = U^*H^*U$ or $A = L^*L^{**}H$, packed columnwise as a linear array. The j-th column of U or L is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = U(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = L(i,j)$ for $j \leq i \leq n$.

On exit, the upper or lower triangle of the (Hermitian) inverse of A, overwriting the input factor U or L.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the (i,i) element of the factor U or L is zero, and the inverse could not be computed.

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NAME

zpptrs - solve a system of linear equations $A \cdot X = B$ with a Hermitian positive definite matrix A in packed storage using the Cholesky factorization $A = U \cdot U^H$ or $A = L \cdot L^H$ computed by ZPPTRF

SYNOPSIS

```
SUBROUTINE ZPPTRS(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO
```

```
SUBROUTINE ZPPTRS_64(UPLO, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE PPTRS(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO
```

```
SUBROUTINE PPTRS_64(UPLO, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpptrs(char uplo, int n, int nrhs, doublecomplex *a,  
            doublecomplex *b, int ldb, int *info);
```

```
void zpptrs_64(char uplo, long n, long nrhs, doublecomplex
              *a, doublecomplex *b, long ldb, long *info);
```

PURPOSE

zpptrs solves a system of linear equations $A \cdot X = B$ with a Hermitian positive definite matrix A in packed storage using the Cholesky factorization $A = U \cdot U^H$ or $A = L \cdot L^H$ computed by ZPPTRF.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) COMPLEX*16 array, dimension $(N \cdot (N+1) / 2)$

The triangular factor U or L from the Cholesky factorization $A = U \cdot U^H$ or $A = L \cdot L^H$, packed columnwise in a linear array. The j -th column of U or L is stored in the array A as follows: if $UPLO = 'U'$, $A(i + (j-1) \cdot j / 2) = U(i, j)$ for $1 \leq i \leq j$; if $UPLO = 'L'$, $A(i + (j-1) \cdot (2n-j) / 2) = L(i, j)$ for $j \leq i \leq n$.

B (input/output) COMPLEX*16 array, dimension $(LDB, NRHS)$

On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

zptcon - compute the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite tridiagonal matrix using the factorization $A = L^*D*L^*H$ or $A = U^*H^*D*U$ computed by ZPTTRF

SYNOPSIS

```
SUBROUTINE ZPTCON(N, D, E, ANORM, RCOND, WORK, INFO)
```

```
DOUBLE COMPLEX E(*)
INTEGER N, INFO
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION D(*), WORK(*)
```

```
SUBROUTINE ZPTCON_64(N, D, E, ANORM, RCOND, WORK, INFO)
```

```
DOUBLE COMPLEX E(*)
INTEGER*8 N, INFO
DOUBLE PRECISION ANORM, RCOND
DOUBLE PRECISION D(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTCON([N], D, E, ANORM, RCOND, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: E
INTEGER :: N, INFO
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: D, WORK
```

```
SUBROUTINE PTCON_64([N], D, E, ANORM, RCOND, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: E
INTEGER(8) :: N, INFO
REAL(8) :: ANORM, RCOND
REAL(8), DIMENSION(:) :: D, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zptcon(int n, double *d, doublecomplex *e, double
           anorm, double *rcond, int *info);
```

```
void zptcon_64(long n, double *d, doublecomplex *e, double
              anorm, double *rcond, long *info);
```

PURPOSE

zptcon computes the reciprocal of the condition number (in the 1-norm) of a complex Hermitian positive definite tridiagonal matrix using the factorization $A = L*D*L^*H$ or $A = U^*H*D*U$ computed by ZPTTRF.

Norm(inv(A)) is computed by a direct method, and the reciprocal of the condition number is computed as
 $RCOND = 1 / (ANORM * norm(inv(A)))$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the factorization of A, as computed by ZPTTRF.

E (input) The (n-1) off-diagonal elements of the unit bidiagonal factor U or L from the factorization of A, as computed by ZPTTRF.

ANORM (input)
The 1-norm of the original matrix A.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(ANORM * AINVNM)$, where AINVNM is the 1-norm of inv(A) computed in this routine.

WORK (workspace)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The method used is described in Nicholas J. Higham, "Efficient Algorithms for Computing the Condition Number of a Tridiagonal Matrix", SIAM J. Sci. Stat. Comput., Vol. 7, No. 1, January 1986.

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NAME

zpteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using SPTTRF and then calling CBDSQR to compute the singular values of the bidiagonal factor

SYNOPSIS

```
SUBROUTINE ZPTEQR(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
DOUBLE COMPLEX Z(LDZ,*)  
INTEGER N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), WORK(*)
```

```
SUBROUTINE ZPTEQR_64(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
DOUBLE COMPLEX Z(LDZ,*)  
INTEGER*8 N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE PTEQR(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX(8), DIMENSION(:,*) :: Z  
INTEGER :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK
```

```
SUBROUTINE PTEQR_64(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX(8), DIMENSION(:,*) :: Z  
INTEGER(8) :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zpteqr(char compz, int n, double *d, double *e, doublecomplex *z, int ldz, int *info);

void zpteqr_64(char compz, long n, double *d, double *e, doublecomplex *z, long ldz, long *info);

```

PURPOSE

zpqr computes all eigenvalues and, optionally, eigenvectors of a symmetric positive definite tridiagonal matrix by first factoring the matrix using SPTTRF and then calling CBDSQR to compute the singular values of the bidiagonal factor.

This routine computes the eigenvalues of the positive definite tridiagonal matrix to high relative accuracy. This means that if the eigenvalues range over many orders of magnitude in size, then the small eigenvalues and corresponding eigenvectors will be computed more accurately than, for example, with the standard QR method.

The eigenvectors of a full or band positive definite Hermitian matrix can also be found if CHETRD, CHPTRD, or CHBTRD has been used to reduce this matrix to tridiagonal form. (The reduction to tridiagonal form, however, may preclude the possibility of obtaining high relative accuracy in the small eigenvalues of the original matrix, if these eigenvalues range over many orders of magnitude.)

ARGUMENTS

COMPZ (input)

= 'N': Compute eigenvalues only.
 = 'V': Compute eigenvectors of original Hermitian matrix also. Array Z contains the unitary matrix used to reduce the original matrix to tridiagonal form. = 'I': Compute eigenvectors of tridiagonal matrix also.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix. On normal exit, D contains the eigenvalues, in descending order.

E (input/output)

On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input) On entry, if COMPZ = 'V', the unitary matrix used in the reduction to tridiagonal form. On exit, if COMPZ = 'V', the orthonormal eigenvectors of the original Hermitian matrix; if COMPZ = 'I', the orthonormal eigenvectors of the tridiagonal

matrix. If INFO > 0 on exit, Z contains the eigenvectors associated with only the stored eigenvalues. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1, and if COMPZ = 'V' or 'I', LDZ >= max(1,N).

WORK (workspace)

dimension(4*N)

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

> 0: if INFO = i, and i is: <= N the Cholesky factorization of the matrix could not be performed because the i-th principal minor was not positive definite. > N the SVD algorithm failed to converge; if INFO = N+i, i off-diagonal elements of the bidiagonal factor did not converge to zero.

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NAME

zptrfs - improve the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZPTRFS(UPLO, N, NRHS, D, E, DF, EF, B, LDB, X,  
                 LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX E(*), EF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION D(*), DF(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZPTRFS_64(UPLO, N, NRHS, D, E, DF, EF, B, LDB,  
                    X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX E(*), EF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION D(*), DF(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PTRFS(UPLO, [N], [NRHS], D, E, DF, EF, B, [LDB],  
                X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: E, EF, WORK  
COMPLEX(8), DIMENSION(:,:) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: D, DF, FERR, BERR, WORK2
```

```
SUBROUTINE PTRFS_64(UPLO, [N], [NRHS], D, E, DF, EF, B,  
                   [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: E, EF, WORK  
COMPLEX(8), DIMENSION(:,:) :: B, X  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
```

```
REAL(8), DIMENSION(:) :: D, DF, FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zptrfs(char uplo, int n, int nrhs, double *d, doublecomplex *e, double *df, doublecomplex *ef, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *ferr, double *berr, int *info);
```

```
void zptrfs_64(char uplo, long n, long nrhs, double *d, doublecomplex *e, double *df, doublecomplex *ef, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *ferr, double *berr, long *info);
```

PURPOSE

zptrfs improves the computed solution to a system of linear equations when the coefficient matrix is Hermitian positive definite and tridiagonal, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

Specifies whether the superdiagonal or the subdiagonal of the tridiagonal matrix A is stored and the form of the factorization:

= 'U': E is the superdiagonal of A, and $A = U^*H^*D*U$;

= 'L': E is the subdiagonal of A, and $A = L^*D*L^*H$. (The two forms are equivalent if A is real.)

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

D (input) The n real diagonal elements of the tridiagonal matrix A.

E (input) The (n-1) off-diagonal elements of the tridiagonal matrix A (see UPLO).

DF (input)

The n diagonal elements of the diagonal matrix D from the factorization computed by ZPTTRF.

EF (input)

The (n-1) off-diagonal elements of the unit bidiagonal factor U or L from the factorization computed by ZPTTRF (see UPLO).

B (input) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq
max(1,N).

X (input/output)
On entry, the solution matrix X, as computed by
ZPTTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq
max(1,N).

FERR (output)
The forward error bound for each solution vector
X(j) (the j-th column of the solution matrix X).
If XTRUE is the true solution corresponding to
X(j), FERR(j) is an estimated upper bound for the
magnitude of the largest element in (X(j) - XTRUE)
divided by the magnitude of the largest element in
X(j).

BERR (output)
The componentwise relative backward error of each
solution vector X(j) (i.e., the smallest relative
change in any element of A or B that makes X(j) an
exact solution).

WORK (workspace)
dimension(N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

zptsv - compute the solution to a complex system of linear equations $A \cdot X = B$, where A is an N -by- N Hermitian positive definite tridiagonal matrix, and X and B are N -by- $NRHS$ matrices.

SYNOPSIS

```
SUBROUTINE ZPTSV(N, NRHS, D, E, B, LDB, INFO)
```

```
DOUBLE COMPLEX E(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
DOUBLE PRECISION D(*)
```

```
SUBROUTINE ZPTSV_64(N, NRHS, D, E, B, LDB, INFO)
```

```
DOUBLE COMPLEX E(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
DOUBLE PRECISION D(*)
```

F95 INTERFACE

```
SUBROUTINE PTVS([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: E  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: D
```

```
SUBROUTINE PTVS_64([N], [NRHS], D, E, B, [LDB], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: E  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zptsv(int n, int nrhs, double *d, doublecomplex *e,  
          doublecomplex *b, int ldb, int *info);
```

```
void zpstsv_64(long n, long nrhs, double *d, doublecomplex
               *e, doublecomplex *b, long ldb, long *info);
```

PURPOSE

zpstsv computes the solution to a complex system of linear equations $A \cdot X = B$, where A is an N -by- N Hermitian positive definite tridiagonal matrix, and X and B are N -by- $NRHS$ matrices.

A is factored as $A = L \cdot D \cdot L^* \cdot H$, and the factored form of A is then used to solve the system of equations.

ARGUMENTS

N (input) The order of the matrix A . $N \geq 0$.

$NRHS$ (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A . On exit, the n diagonal elements of the diagonal matrix D from the factorization $A = L \cdot D \cdot L^* \cdot H$.

E (input/output)

On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix A . On exit, the $(n-1)$ subdiagonal elements of the unit bidiagonal factor L from the $L \cdot D \cdot L^* \cdot H$ factorization of A . E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the $U \cdot H \cdot D \cdot U$ factorization of A .

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B . On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

$INFO$ (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, the leading minor of order i is not positive definite, and the solution has not been computed. The factorization has not been completed unless $i = N$.

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zptsvx - use the factorization $A = L*D*L^*H$ to compute the solution to a complex system of linear equations $A*X = B$, where A is an N-by-N Hermitian positive definite tridiagonal matrix and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE ZPTSVX(FACT, N, NRHS, D, E, DF, EF, B, LDB, X,  
                 LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT  
DOUBLE COMPLEX E(*), EF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION D(*), DF(*), FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZPTSVX_64(FACT, N, NRHS, D, E, DF, EF, B, LDB,  
                    X, LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT  
DOUBLE COMPLEX E(*), EF(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION D(*), DF(*), FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE PTVSX(FACT, [N], [NRHS], D, E, DF, EF, B, [LDB],  
                X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT  
COMPLEX(8), DIMENSION(:) :: E, EF, WORK  
COMPLEX(8), DIMENSION(:,:) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: D, DF, FERR, BERR, WORK2
```

```
SUBROUTINE PTVSX_64(FACT, [N], [NRHS], D, E, DF, EF, B,  
                   [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT
```

```

COMPLEX(8), DIMENSION(:) :: E, EF, WORK
COMPLEX(8), DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: D, DF, FERR, BERR, WORK2
C INTERFACE
#include <sunperf.h>

void zptsvx(char fact, int n, int nrhs, double *d, doublecomplex *e, double *df, doublecomplex *ef, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *rcond, double *ferr, double *berr, int *info);

void zptsvx_64(char fact, long n, long nrhs, double *d, doublecomplex *e, double *df, doublecomplex *ef, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zptsvx uses the factorization $A = L^*D^*L^{**}H$ to compute the solution to a complex system of linear equations $A^*X = B$, where A is an N-by-N Hermitian positive definite tridiagonal matrix and X and B are N-by-NRHS matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If FACT = 'N', the matrix A is factored as $A = L^*D^*L^{**}H$, where L is a unit lower bidiagonal matrix and D is diagonal. The factorization can also be regarded as having the form $A = U^{**}H^*D^*U$.
2. If the leading i-by-i principal minor is not positive definite, then the routine returns with INFO = i. Otherwise, the factored form of A is used to estimate the condition number of the matrix.
 - A. If the reciprocal of the condition number is less than machine precision, INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.
3. The system of equations is solved for X using the factored form of A.
4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error

estimates
for it.

ARGUMENTS

FACT (input)
Specifies whether or not the factored form of the matrix A is supplied on entry. = 'F': On entry, DF and EF contain the factored form of A. D, E, DF, and EF will not be modified. = 'N': The matrix A will be copied to DF and EF and factored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

D (input) The n diagonal elements of the tridiagonal matrix A.

E (input) The (n-1) subdiagonal elements of the tridiagonal matrix A.

DF (input or output)
If FACT = 'F', then DF is an input argument and on entry contains the n diagonal elements of the diagonal matrix D from the L^*D*L^{**H} factorization of A. If FACT = 'N', then DF is an output argument and on exit contains the n diagonal elements of the diagonal matrix D from the L^*D*L^{**H} factorization of A.

EF (input or output)
If FACT = 'F', then EF is an input argument and on entry contains the (n-1) subdiagonal elements of the unit bidiagonal factor L from the L^*D*L^{**H} factorization of A. If FACT = 'N', then EF is an output argument and on exit contains the (n-1) subdiagonal elements of the unit bidiagonal factor L from the L^*D*L^{**H} factorization of A.

B (input) On entry, the N-by-NRHS right hand side matrix B. Unchanged on exit.

LDB (input)
The leading dimension of the array B. $LDB \geq \max(1,N)$.

X (output)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)
The leading dimension of the array X. $LDX \geq \max(1,N)$.

RCOND (output)
The reciprocal condition number of the matrix A.

If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

The forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j).

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: the leading minor of order i of A is not positive definite, so the factorization could not be completed, and the solution has not been computed. RCOND = 0 is returned. = N+1: U is non-singular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

zpttrf - compute the L*D*L' factorization of a complex Hermitian positive definite tridiagonal matrix A

SYNOPSIS

```
SUBROUTINE ZPTTRF(N, D, E, INFO)
```

```
DOUBLE COMPLEX E(*)
INTEGER N, INFO
DOUBLE PRECISION D(*)
```

```
SUBROUTINE ZPTTRF_64(N, D, E, INFO)
```

```
DOUBLE COMPLEX E(*)
INTEGER*8 N, INFO
DOUBLE PRECISION D(*)
```

F95 INTERFACE

```
SUBROUTINE PTTRF([N], D, E, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: E
INTEGER :: N, INFO
REAL(8), DIMENSION(:) :: D
```

```
SUBROUTINE PTTRF_64([N], D, E, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: E
INTEGER(8) :: N, INFO
REAL(8), DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpttrf(int n, double *d, doublecomplex *e, int *info);
```

```
void zpttrf_64(long n, double *d, doublecomplex *e, long *info);
```

PURPOSE

zpttrf computes the L^*D^*L' factorization of a complex Hermitian positive definite tridiagonal matrix A. The factorization may also be regarded as having the form $A = U^*D^*U$.

ARGUMENTS

N (input) The order of the matrix A. $N \geq 0$.

D (input/output)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the L^*D^*L' factorization of A.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix A. On exit, the (n-1) subdiagonal elements of the unit bidiagonal factor L from the L^*D^*L' factorization of A. E can also be regarded as the superdiagonal of the unit bidiagonal factor U from the U^*D^*U factorization of A.

INFO (output)

= 0: successful exit

< 0: if INFO = -k, the k-th argument had an illegal value

> 0: if INFO = k, the leading minor of order k is not positive definite; if $k < N$, the factorization could not be completed, while if $k = N$, the factorization was completed, but $D(N) = 0$.

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NAME

zpttrs - solve a tridiagonal system of the form $A * X = B$ using the factorization $A = U'*D*U$ or $A = L*D*L'$ computed by ZPTTRF

SYNOPSIS

```
SUBROUTINE ZPTTRS(UPLO, N, NRHS, D, E, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX E(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
DOUBLE PRECISION D(*)
```

```
SUBROUTINE ZPTTRS_64(UPLO, N, NRHS, D, E, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX E(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
DOUBLE PRECISION D(*)
```

F95 INTERFACE

```
SUBROUTINE PTTRS(UPLO, [N], [NRHS], D, E, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: E  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: D
```

```
SUBROUTINE PTTRS_64(UPLO, [N], [NRHS], D, E, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: E  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
REAL(8), DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zpttrs(char uplo, int n, int nrhs, double *d, doublecomplex *e, doublecomplex *b, int ldb, int *info);

void zpttrs_64(char uplo, long n, long nrhs, double *d, doublecomplex *e, doublecomplex *b, long ldb, long *info);

```

PURPOSE

zpttrs solves a tridiagonal system of the form $A * X = B$ using the factorization $A = U * D * U$ or $A = L * D * L'$ computed by ZPTTRF. D is a diagonal matrix specified in the vector D, U (or L) is a unit bidiagonal matrix whose superdiagonal (subdiagonal) is specified in the vector E, and X and B are N by NRHS matrices.

ARGUMENTS

UPLO (input)

Specifies the form of the factorization and whether the vector E is the superdiagonal of the upper bidiagonal factor U or the subdiagonal of the lower bidiagonal factor L. = 'U': $A = U * D * U$, E is the superdiagonal of U
= 'L': $A = L * D * L'$, E is the subdiagonal of L

N (input) The order of the tridiagonal matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the factorization $A = U * D * U$ or $A = L * D * L'$.

E (input) If UPLO = 'U', the (n-1) superdiagonal elements of the unit bidiagonal factor U from the factorization $A = U * D * U$. If UPLO = 'L', the (n-1) subdiagonal elements of the unit bidiagonal factor L from the factorization $A = L * D * L'$.

B (input/output)

On entry, the right hand side vectors B for the system of linear equations. On exit, the solution vectors, X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value

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NAME

zptts2 - solve a tridiagonal system of the form $A * X = B$ using the factorization $A = U * D * U$ or $A = L * D * L'$ computed by ZPTTRF

SYNOPSIS

```
SUBROUTINE ZPTTS2(IUPLO, N, NRHS, D, E, B, LDB)
```

```
DOUBLE COMPLEX E(*), B(LDB,*)
INTEGER IUPLO, N, NRHS, LDB
DOUBLE PRECISION D(*)
```

```
SUBROUTINE ZPTTS2_64(IUPLO, N, NRHS, D, E, B, LDB)
```

```
DOUBLE COMPLEX E(*), B(LDB,*)
INTEGER*8 IUPLO, N, NRHS, LDB
DOUBLE PRECISION D(*)
```

F95 INTERFACE

```
SUBROUTINE ZPTTS2(IUPLO, N, NRHS, D, E, B, LDB)
```

```
COMPLEX(8), DIMENSION(:) :: E
COMPLEX(8), DIMENSION(:, :) :: B
INTEGER :: IUPLO, N, NRHS, LDB
REAL(8), DIMENSION(:) :: D
```

```
SUBROUTINE ZPTTS2_64(IUPLO, N, NRHS, D, E, B, LDB)
```

```
COMPLEX(8), DIMENSION(:) :: E
COMPLEX(8), DIMENSION(:, :) :: B
INTEGER(8) :: IUPLO, N, NRHS, LDB
REAL(8), DIMENSION(:) :: D
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zptts2(int iuplo, int n, int nrhs, double *d, doublecomplex *e, doublecomplex *b, int ldb);
```

```
void zptts2_64(long iuplo, long n, long nrhs, double *d,
```

doublecomplex *e, doublecomplex *b, long ldb);

PURPOSE

zptts2 solves a tridiagonal system of the form

$A * X = B$ using the factorization $A = U'D*U$ or $A = L*D*L'$ computed by ZPTTRF. D is a diagonal matrix specified in the vector D, U (or L) is a unit bidiagonal matrix whose superdiagonal (subdiagonal) is specified in the vector E, and X and B are N by NRHS matrices.

ARGUMENTS

IUPLO (input)

Specifies the form of the factorization and whether the vector E is the superdiagonal of the upper bidiagonal factor U or the subdiagonal of the lower bidiagonal factor L. = 1: $A = U'D*U$, E is the superdiagonal of U
= 0: $A = L*D*L'$, E is the subdiagonal of L

N (input) The order of the tridiagonal matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

D (input) The n diagonal elements of the diagonal matrix D from the factorization $A = U'D*U$ or $A = L*D*L'$.

E (input) If IUPLO = 1, the (n-1) superdiagonal elements of the unit bidiagonal factor U from the factorization $A = U'D*U$. If IUPLO = 0, the (n-1) subdiagonal elements of the unit bidiagonal factor L from the factorization $A = L*D*L'$.

B (input/output)

On entry, the right hand side vectors B for the system of linear equations. On exit, the solution vectors, X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

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NAME

zrot - apply a plane rotation, where the cos (C) is real and the sin (S) is complex, and the vectors X and Y are complex

SYNOPSIS

```
SUBROUTINE ZROT(N, X, INCX, Y, INCY, C, S)
```

```
DOUBLE COMPLEX S
DOUBLE COMPLEX X(*), Y(*)
INTEGER N, INCX, INCY
DOUBLE PRECISION C
```

```
SUBROUTINE ZROT_64(N, X, INCX, Y, INCY, C, S)
```

```
DOUBLE COMPLEX S
DOUBLE COMPLEX X(*), Y(*)
INTEGER*8 N, INCX, INCY
DOUBLE PRECISION C
```

F95 INTERFACE

```
SUBROUTINE ROT([N], X, [INCX], Y, [INCY], C, S)
```

```
COMPLEX(8) :: S
COMPLEX(8), DIMENSION(:) :: X, Y
INTEGER :: N, INCX, INCY
REAL(8) :: C
```

```
SUBROUTINE ROT_64([N], X, [INCX], Y, [INCY], C, S)
```

```
COMPLEX(8) :: S
COMPLEX(8), DIMENSION(:) :: X, Y
INTEGER(8) :: N, INCX, INCY
REAL(8) :: C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zrot(int n, doublecomplex *x, int incx, doublecomplex
          *y, int incy, double c, doublecomplex *s);
```

```
void zrot_64(long n, doublecomplex *x, long incx, doublecom-
           plex *y, long incy, double c, doublecomplex *s);
```

PURPOSE

zrot applies a plane rotation, where the cos (C) is real and the sin (S) is complex, and the vectors X and Y are complex.

ARGUMENTS

N (input)

The number of elements in the vectors X and Y.

X (input/output)

On input, the vector X. On output, X is overwritten with $C*X + S*Y$.

INCX (input)

The increment between successive values of X.

Y (input/output)

On input, the vector Y. On output, Y is overwritten with $-CONJG(S)*X + C*Y$.

INCY (input)

The increment between successive values of Y.

C (input)

S (input)

C and S define a rotation

$$\begin{bmatrix} C & S \\ -\text{conjg}(S) & C \end{bmatrix}$$
$$\begin{bmatrix} C & S \\ -\text{conjg}(S) & C \end{bmatrix}$$

where $C*C + S*CONJG(S) = 1.0$.

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NAME

zrotg - Construct a Given's plane rotation

SYNOPSIS

```
SUBROUTINE ZROTG(A, B, C, S)
```

```
DOUBLE COMPLEX A, B, S  
DOUBLE PRECISION C
```

```
SUBROUTINE ZROTG_64(A, B, C, S)
```

```
DOUBLE COMPLEX A, B, S  
DOUBLE PRECISION C
```

F95 INTERFACE

```
SUBROUTINE ROTG(A, B, C, S)
```

```
COMPLEX(8) :: A, B, S  
REAL(8) :: C
```

```
SUBROUTINE ROTG_64(A, B, C, S)
```

```
COMPLEX(8) :: A, B, S  
REAL(8) :: C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zrotg(doublecomplex *a, doublecomplex *b, double *c,  
          doublecomplex *s);
```

```
void zrotg_64(doublecomplex *a, doublecomplex *b, double *c,  
            doublecomplex *s);
```

PURPOSE

zrotg Construct a Given's plane rotation that will annih-

late an element of a vector.

ARGUMENTS

A (input/output)

On entry, A contains the entry in the first vector that corresponds to the element to be annihilated in the second vector. On exit, contains the nonzero element of the rotated vector.

B (input)

On entry, B contains the entry to be annihilated in the second vector. Unchanged on exit.

C (output)

On exit, C and S are the elements of the rotation matrix that will be applied to annihilate B.

S (output)

On exit, C and S are the elements of the rotation matrix that will be applied to annihilate B.

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NAME

zscal - Compute $y := \alpha * y$

SYNOPSIS

```
SUBROUTINE ZSCAL(N, ALPHA, Y, INCY)

DOUBLE COMPLEX ALPHA
DOUBLE COMPLEX Y(*)
INTEGER N, INCY

SUBROUTINE ZSCAL_64(N, ALPHA, Y, INCY)

DOUBLE COMPLEX ALPHA
DOUBLE COMPLEX Y(*)
INTEGER*8 N, INCY
```

F95 INTERFACE

```
SUBROUTINE SCAL([N], ALPHA, Y, [INCY])

COMPLEX(8) :: ALPHA
COMPLEX(8), DIMENSION(:) :: Y
INTEGER :: N, INCY

SUBROUTINE SCAL_64([N], ALPHA, Y, [INCY])

COMPLEX(8) :: ALPHA
COMPLEX(8), DIMENSION(:) :: Y
INTEGER(8) :: N, INCY
```

C INTERFACE

```
#include <sunperf.h>

void zscal(int n, doublecomplex *alpha, doublecomplex *y,
           int incy);

void zscal_64(long n, doublecomplex *alpha, doublecomplex
             *y, long incy);
```

PURPOSE

zscal Compute $y := \text{alpha} * y$ where alpha is a scalar and y is an n-vector.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * INCY). On entry, the incremented array Y must contain the vector y. On exit, Y is overwritten by the updated vector y.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. This routine returns immediately if INCY is less than or equal to zero. Unchanged on exit.

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NAME

zsctr - Scatters elements from x into y.

SYNOPSIS

```
SUBROUTINE ZSCTR(NZ, X, INDX, Y)

DOUBLE COMPLEX X(*), Y(*)
INTEGER NZ
INTEGER INDX(*)

SUBROUTINE ZSCTR_64(NZ, X, INDX, Y)

DOUBLE COMPLEX X(*), Y(*)
INTEGER*8 NZ
INTEGER*8 INDX(*)

F95 INTERFACE
SUBROUTINE SCTR([NZ], X, INDX, Y)

COMPLEX(8), DIMENSION(:) :: X, Y
INTEGER :: NZ
INTEGER, DIMENSION(:) :: INDX

SUBROUTINE SCTR_64([NZ], X, INDX, Y)

COMPLEX(8), DIMENSION(:) :: X, Y
INTEGER(8) :: NZ
INTEGER(8), DIMENSION(:) :: INDX
```

PURPOSE

ZSCTR - Scatters the components of a sparse vector x stored in compressed form into specified components of a vector y in full storage form.

```
do i = 1, n
  y(indx(i)) = x(i)
enddo
```

ARGUMENTS

NZ (input) - INTEGER

Number of elements in the compressed form.
Unchanged on exit.

X (input)

Vector containing the values to be scattered from
compressed form into full storage form. Unchanged
on exit.

INDX (input) - INTEGER

Vector containing the indices of the compressed
form. It is assumed that the elements in INDX are
distinct and greater than zero. Unchanged on exit.

Y (output)

Vector whose elements specified by indx have been
set to the corresponding entries of x. Only the
elements corresponding to the indices in indx have
been modified.

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NAME

zskymm - Skyline format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZSKYMM( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, PNTR, B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER          TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER          PNTR(*),  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)  
  
SUBROUTINE ZSKYMM_64( TRANSA, M, N, K, ALPHA, DESCRA,  
*                VAL, PNTR, B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8        TRANSA, M, N, K, DESCRA(5),  
*                LDB, LDC, LWORK  
INTEGER*8        PNTR(*),  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX  VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)
```

where NNZ = PNTR(K+1)-PNTR(1) (upper triangular)
 NNZ = PNTR(M+1)-PNTR(1) (lower triangular)
 PNTR() size = (K+1) (upper triangular)
 PNTR() size = (M+1) (lower triangular)

F95 INTERFACE

```
SUBROUTINE ZKYMM( TRANSA, M, [N], K, ALPHA, DESCRA, VAL,  
*                PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER          TRANSA, M, K  
INTEGER, DIMENSION(:) :: DESCRA, PNTR  
DOUBLE COMPLEX  ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C  
  
SUBROUTINE ZKYMM_64( TRANSA, M, [N], K, ALPHA, DESCRA, VAL,  
*                PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])  
INTEGER*8        TRANSA, M, K  
INTEGER*8, DIMENSION(:) :: DESCRA, PNTR
```

```

DOUBLE COMPLEX    ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: VAL
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>

void zskymm (int transa, int m, int n, int k, doublecomplex
*alpha, int *descra, doublecomplex *val, int *pntr,
doublecomplex *b, int ldb, doublecomplex *beta,
doublecomplex *c, int ldc);

void zskymm_64 (long transa, long m, long n, long k,
doublecomplex *alpha, long *descra, doublecomplex *val,
long *pntr, doublecomplex *b, long ldb, doublecomplex
*beta,
doublecomplex *c, long ldc);

```

DESCRIPTION

zskymm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where $\operatorname{op}(A)$ is one of

$\operatorname{op}(A) = A$ or $\operatorname{op}(A) = A'$ or $\operatorname{op}(A) = \operatorname{conjg}(A')$
(' indicates matrix transpose),

A is an M-by-K sparse matrix represented in the skyline format,
alpha and beta are scalars, C and B are dense matrices.

ARGUMENTS

TRANSA(input)	On entry, integer TRANSA specifies the form of $\operatorname{op}(A)$ to be used in the matrix multiplication as follows: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
M(input)	On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.
N(input)	On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.
K(input)	On entry, integer K specifies the number of columns in the matrix A. Unchanged on exit.
ALPHA(input)	On entry, ALPHA specifies the scalar alpha. Unchanged on exit.
DESCRA (input)	Descriptor argument. Five element integer array. DESCRA(1) matrix structure 0 : general (NOT SUPPORTED) 1 : symmetric (A=A')

```

2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input)    On entry, VAL is a scalar array consisting of the
              nonzeros of A in skyline profile form.
              Row-oriented if DESCRA(2) = 1 (lower triangular),
              column oriented if DESCRA(2) = 2 (upper triangular).
              Unchanged on exit.

PNTR (input)  On entry, INDX is an integer array of length
              M+1 (lower triangular) or K+1 (upper triangular)
              such that PNTR(I)-PNTR(1)+1 points to the
              location in VAL of the first element of the skyline
              profile in row (column) I. Unchanged on exit.

B (input)     Array of DIMENSION ( LDB, N ).
              Before entry with TRANSA = 0, the leading k by n
              part of the array B must contain the matrix B, otherwise
              the leading m by n part of the array B must contain the
              matrix B. Unchanged on exit.

LDB (input)   On entry, LDB specifies the first dimension of B as declared
              in the calling (sub) program. Unchanged on exit.

BETA (input)  On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION ( LDC, N ).
              Before entry with TRANSA = 0, the leading m by n
              part of the array C must contain the matrix C, otherwise
              the leading k by n part of the array C must contain the
              matrix C. On exit, the array C is overwritten by the matrix
              ( alpha*op( A )* B + beta*C ).

LDC (input)   On entry, LDC specifies the first dimension of C as declared
              in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

```

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN

Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

The SKY data structure is not supported for a general matrix structure (*DESCRA*(1)=0).

Also not supported:

1. lower triangular matrix A of size m by n where $m > n$
2. upper triangular matrix A of size m by n where $m < n$

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NAME

zskysm - Skyline format triangular solve

SYNOPSIS

```
SUBROUTINE ZSKYSM( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*      VAL, PNTR,
*      B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER  TRANSA, M, N, UNITD, DESCRA(5),
*      LDB, LDC, LWORK
INTEGER  PNTR(*),
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

SUBROUTINE ZSKYSM_64( TRANSA, M, N, UNITD, DV, ALPHA, DESCRA,
*      VAL, PNTR,
*      B, LDB, BETA, C, LDC, WORK, LWORK)
INTEGER*8  TRANSA, M, N, UNITD, DESCRA(5),
*      LDB, LDC, LWORK
INTEGER*8  PNTR(*),
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX DV(M), VAL(NNZ), B(LDB,*), C(LDC,*), WORK(LWORK)

where NNZ = PNTR(M+1)-PNTR(1)
      PNTR() size = (M+1)
```

F95 INTERFACE

```
SUBROUTINE SKYSM( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA, VAL,
*      PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER  TRANSA, M, UNITD
INTEGER, DIMENSION(:) :: DESCRA, PNTR
DOUBLE COMPLEX  ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C

SUBROUTINE SKYSM_64( TRANSA, M, [N], UNITD, DV, ALPHA, DESCRA,
*      VAL, PNTR, B, [LDB], BETA, C, [LDC], [WORK], [LWORK])
INTEGER*8  TRANSA, M, UNITD
INTEGER*8, DIMENSION(:) :: DESCRA, PNTR
```

```
DOUBLE COMPLEX    ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zskysm (int transa, int m, int n, int unitd,
doublecomplex *dv, doublecomplex *alpha, int *descra,
doublecomplex *val, int *pntr, doublecomplex *b, int ldb,
doublecomplex *beta, doublecomplex *c, int ldc);
```

```
void zskysm_64 (long transa, long m, long n, long unitd,
doublecomplex *dv, doublecomplex *alpha, long *descra,
doublecomplex *val, long *pntr, doublecomplex *b, long ldb,
doublecomplex *beta, doublecomplex *c, long ldc);
```

DESCRIPTION

zskysm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C, \quad C \leftarrow -\alpha D \operatorname{op}(A) B + \beta C,$$

$$C \leftarrow \alpha \operatorname{op}(A) D B + \beta C,$$

where alpha and beta are scalars, C and B are m by n dense matrices, D is a diagonal scaling matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the skyline format and op(A) is one of

op(A) = inv(A) or op(A) = inv(A') or op(A) = inv(conjg(A'))
(inv denotes matrix inverse, ' indicates matrix transpose).

ARGUMENTS

TRANSA(input) On entry, integer TRANSA specifies the form of op(A) to be used in the sparse matrix inverse as follows:

- 0 : operate with matrix
- 1 : operate with transpose matrix
- 2 : operate with the conjugate transpose of matrix.
- 2 is equivalent to 1 if matrix is real.

Unchanged on exit.

M(input) On entry, integer M specifies the number of rows in the matrix A. Unchanged on exit.

N(input) On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.

UNITD(input) On entry, integer UNITD specifies the type of scaling:

- 1 : Identity matrix (argument DV[] is ignored)
- 2 : Scale on left (row scaling)
- 3 : Scale on right (column scaling)
- 4 : Automatic row or column scaling (see section NOTES for further details)

Unchanged on exit.

DV(input) On entry, DV is an array of length M consisting of the diagonal entries of the scaling matrix D. If UNITD is 4, DV contains diagonal matrix by which the rows (columns) have been scaled (see section NOTES for further details). Otherwise, unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array.
DESCRA(1) matrix structure
0 : general (NOT SUPPORTED)
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper

DESCRA(3) main diagonal type
0 : non-unit
1 : unit

DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, VAL contains the nonzeros of A in skyline profile form. Row-oriented if DESCRA(2) = 1 (lower triangular), column oriented if DESCRA(2) = 2 (upper triangular). Unchanged on exit if UNITD is not 4. Otherwise, VAL contains entries of D*A or A*D (see section NOTES for further details).

PNTR (input) On entry, INDX is an integer array of length M+1 such that PNTR(I)-PNTR(1)+1 points to the location in VAL of the first element of the skyline profile in row (column) I. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
On entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
On entry, the leading m by n part of the array C must contain the matrix C. On exit, the array C is overwritten.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK.
On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least M.

For good performance, LWORK should generally be larger. For optimum performance on multiple processors, $LWORK \geq M * N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

2. If UNITD =4, the routine scales the rows of A if *DESCRA*(2)=1 (lower triangular), and the columns of A if *DESCRA*(2)=2 (upper triangular) such that their 2-norms are one. The scaling may improve the accuracy of the computed solution. Corresponding entries of VAL are changed only in this particular case. On exit, DV matrix stored as a vector contains the diagonal matrix by which the rows (columns) have been scaled. UNITD=2 if *DESCRA*(2)=1 and UNITD=3 if *DESCRA*(2)=2 should be used for the next calls to the routine with overwritten VAL and DV.

WORK(1)=0 on return if the scaling has been completed successfully, otherwise *WORK*(1) = -i where i is the row (column) number which 2-norm is exactly zero.

3. If *DESCRA*(3)=1 and UNITD < 4, the diagonal entries are each used with the mathematical value 1. The entries of the main diagonal in the skyline representation of a sparse matrix don't need to be referenced in this usage but they

need to be 1.0 if they are referenced. However if UNITD=4, the unit diagonal elements with the mathematical value 1 MUST be referenced in the skyline representation.

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NAME

zspcon - estimate the reciprocal of the condition number (in the 1-norm) of a complex symmetric packed matrix A using the factorization $A = U*D*U^{*T}$ or $A = L*D*L^{*T}$ computed by ZSPTRF

SYNOPSIS

```
SUBROUTINE ZSPCON(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION ANORM, RCOND
```

```
SUBROUTINE ZSPCON_64(UPLO, N, A, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE SPCON(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8) :: ANORM, RCOND
```

```
SUBROUTINE SPCON_64(UPLO, [N], A, IPIVOT, ANORM, RCOND, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT  
REAL(8) :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>

void zspcon(char uplo, int n, doublecomplex *a, int *ipivot,
            double anorm, double *rcond, int *info);
void zspcon_64(char uplo, long n, doublecomplex *a, long
               *ipivot, double anorm, double *rcond, long *info);
```

PURPOSE

zspcon estimates the reciprocal of the condition number (in the 1-norm) of a complex symmetric packed matrix A using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by ZSPTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U*D*U^{**T}$;
= 'L': Lower triangular, form is $A = L*D*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) Double complex array, dimension $(N*(N+1)/2)$ The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZSPTRF, stored as a packed triangular matrix.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by ZSPTRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{ANORM} * \text{AINVNM})$, where AINVNM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

Double complex array, dimension $(2*N)$

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zsprfs - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZSPRFS(UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX, FERR,
                 BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZSPRFS_64(UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX,
                   FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE SPRFS(UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X, [LDX],
                FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: A, AF, WORK
COMPLEX(8), DIMENSION(:, :) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE SPRFS_64(UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X, [LDX],
                  FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
```

```

COMPLEX(8), DIMENSION(:) :: A, AF, WORK
COMPLEX(8), DIMENSION(:, :) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zsprfs(char uplo, int n, int nrhs, doublecomplex *a,
            doublecomplex *af, int *ipivot, doublecomplex *b,
            int ldb, doublecomplex *x, int ldx, double *ferr,
            double *berr, int *info);

void zsprfs_64(char uplo, long n, long nrhs, doublecomplex
               *a, doublecomplex *af, long *ipivot, doublecomplex
               *b, long ldb, doublecomplex *x, long ldx, double
               *ferr, double *berr, long *info);

```

PURPOSE

zsprfs improves the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite and packed, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) Double complex array, dimension $(N*(N+1)/2)$ The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

AF (input)

Double complex array, dimension $(N*(N+1)/2)$ The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^*T$ or $A = L*D*L^*T$ as computed by ZSPTRF, stored as a packed triangular matrix.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by ZSPTRF.

B (input) Double complex array, dimension (LDB,NRHS) The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

X (input/output)
Double complex array, dimension (LDX,NRHS) On entry, the solution matrix X, as computed by ZSPTRS. On exit, the improved solution matrix X.

LDX (input)
The leading dimension of the array X. LDX >= max(1,N).

FERR (output)
Double precision array, dimension (NRHS) The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
Double precision array, dimension (NRHS) The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
Double precision array, dimension(2*N)

WORK2 (workspace)
Integer array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zpsv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZSPSV(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZSPSV_64(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SPSV(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SPSV_64(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zpsv(char uplo, int n, int nrhs, doublecomplex *ap,
          int *ipivot, doublecomplex *b, int ldb, int
          *info);
```

```
void zpsv_64(char uplo, long n, long nrhs, doublecomplex
             *ap, long *ipivot, doublecomplex *b, long ldb,
             long *info);
```

PURPOSE

zpsv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{*T}$, if UPLO = 'U', or

$A = L * D * L^{*T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;

= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

AP (input/output)

Double complex array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{*T}$ or $A = L*D*L^{*T}$ as computed by ZSPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (output)

Integer array, dimension (N) Details of the inter-

changes and the block structure of D, as determined by ZSPTRF. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged, and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

B (input/output)

Double complex array, dimension (LDB,NRHS) On entry, the N-by-NRHS right hand side matrix B. On exit, if INFO = 0, the N-by-NRHS solution matrix X.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when N = 4, UPLO = 'U':

Two-dimensional storage of the symmetric matrix A:

```
a11 a12 a13 a14
    a22 a23 a24
        a33 a34   (aij = aji)
            a44
```

Packed storage of the upper triangle of A:

```
AP = [ a11, a12, a22, a13, a23, a33, a14, a24, a34, a44 ]
```

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NAME

zspsvx - use the diagonal pivoting factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N-by-N symmetric matrix stored in packed format and X and B are N-by-NRHS matrices

SYNOPSIS

```
SUBROUTINE ZSPSVX(FACT, UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X, LDX,
                 RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER N, NRHS, LDB, LDX, INFO
INTEGER IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZSPSVX_64(FACT, UPLO, N, NRHS, A, AF, IPIVOT, B, LDB, X,
                    LDX, RCOND, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO
DOUBLE COMPLEX A(*), AF(*), B(LDB,*), X(LDX,*), WORK(*)
INTEGER*8 N, NRHS, LDB, LDX, INFO
INTEGER*8 IPIVOT(*)
DOUBLE PRECISION RCOND
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE SPSVX(FACT, UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X,
                [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX(8), DIMENSION(:) :: A, AF, WORK
COMPLEX(8), DIMENSION(:, :) :: B, X
INTEGER :: N, NRHS, LDB, LDX, INFO
INTEGER, DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
```

```

REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

SUBROUTINE ZSPSVX_64(FACT, UPLO, [N], [NRHS], A, AF, IPIVOT, B, [LDB], X,
    [LDX], RCOND, FERR, BERR, [WORK], [WORK2], [INFO])

CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX(8), DIMENSION(:) :: A, AF, WORK
COMPLEX(8), DIMENSION(:,:) :: B, X
INTEGER(8) :: N, NRHS, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zspsvx(char fact, char uplo, int n, int nrhs, doublecomplex *a, doublecomplex *af, int *ipivot, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *rcond, double *ferr, double *berr, int *info);

void zspsvx_64(char fact, char uplo, long n, long nrhs, doublecomplex *a, doublecomplex *af, long *ipivot, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zspsvx uses the diagonal pivoting factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ to compute the solution to a complex system of linear equations $A * X = B$, where A is an N -by- N symmetric matrix stored in packed format and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the diagonal pivoting method is used to factor A as

$$A = U * D * U^{**T}, \text{ if } UPLO = 'U', \text{ or}$$

$$A = L * D * L^{**T}, \text{ if } UPLO = 'L',$$

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices and D is symmetric and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than machine precision,

$INFO = N+1$ is returned as a warning, but the routine

still goes on
to solve for X and compute error bounds as described
below.

3. The system of equations is solved for X using the factored form
of A.

4. Iterative refinement is applied to improve the computed
solution
matrix and calculate error bounds and backward error
estimates
for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. A, AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) Double complex array, dimension $(N*(N+1)/2)$ The upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$. See below for further details.

AF (input or output)

Double complex array, dimension $(N*(N+1)/2)$ If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by ZSPTRF, stored as a packed triangular matrix in the same storage format as A.

If FACT = 'N', then AF is an output argument and on exit contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by ZSPTRF, stored as a packed triangular matrix in the same storage format as A.

IPIVOT (input or output)

Integer array, dimension (N) If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by ZSPTRF. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

If FACT = 'N', then IPIVOT is an output argument and on exit contains details of the interchanges and the block structure of D, as determined by ZSPTRF.

B (input) Double complex array, dimension (LDB,NRHS) The N-by-NRHS right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB >= max(1,N).

X (output)

Double complex array, dimension (LDX,NRHS) If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)

The leading dimension of the array X. LDX >= max(1,N).

RCOND (output)

The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)

Double complex array, dimension (NRHS) The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

Double complex array, dimension (NRHS) The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
 Double complex array, dimension(2*N)

WORK2 (workspace)
 Integer array, dimension(N)

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, and i is
 <= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

FURTHER DETAILS

The packed storage scheme is illustrated by the following example when N = 4, UPLO = 'U':

Two-dimensional storage of the symmetric matrix A:

```

a11 a12 a13 a14
  a22 a23 a24
    a33 a34   (aij = aji)
      a44
  
```

Packed storage of the upper triangle of A:

A = [a11, a12, a22, a13, a23, a33, a14, a24, a34, a44]

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NAME

zsptrf - compute the factorization of a complex symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE ZSPTRF(UPLO, N, AP, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZSPTRF_64(UPLO, N, AP, IPIVOT, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRF(UPLO, [N], AP, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SPTRF_64(UPLO, [N], AP, IPIVOT, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zsptrf(char uplo, int n, doublecomplex *ap, int
           *ipivot, int *info);

void zsptrf_64(char uplo, long n, doublecomplex *ap, long
              *ipivot, long *info);

```

PURPOSE

zsptrf computes the factorization of a complex symmetric matrix A stored in packed format using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U^{**T} \text{ or } A = L^*D^*L^{**T}$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)

Double complex array, dimension $(N*(N+1)/2)$ On entry, the upper or lower triangle of the symmetric matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array AP as follows: if UPLO = 'U', $AP(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $AP(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L, stored as a packed triangular matrix overwriting A (see below for further details).

IPIVOT (output)

Integer array, dimension (N) Details of the interchanges and the block structure of D. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged and $D(k,k)$ is a 1-by-1 diagonal block. If UPLO = 'U' and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns k-1 and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If UPLO = 'L' and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns k+1 and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an

illegal value
 > 0: if INFO = i, D(i,i) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

5-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where

$U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$,
 i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where

$L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$,
 i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIVOT(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

zsptri - compute the inverse of a complex symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^*T$ or $A = L^*D^*L^*T$ computed by ZSPTRF

SYNOPSIS

```
SUBROUTINE ZSPTRI(UPLO, N, AP, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), WORK(*)  
INTEGER N, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZSPTRI_64(UPLO, N, AP, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), WORK(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRI(UPLO, [N], AP, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP, WORK  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SPTRI_64(UPLO, [N], AP, IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP, WORK  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zsptri(char uplo, int n, doublecomplex *ap, int  
            *ipivot, int *info);
```

```
void zsptri_64(char uplo, long n, doublecomplex *ap, long
               *ipivot, long *info);
```

PURPOSE

zsptri computes the inverse of a complex symmetric indefinite matrix A in packed storage using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by ZSPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U^*D^*U^{**T}$;
= 'L': Lower triangular, form is $A = L^*D^*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

AP (input/output)

Double complex array, dimension $(N*(N+1)/2)$ On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZSPTRF, stored as a packed triangular matrix.

On exit, if INFO = 0, the (symmetric) inverse of the original matrix, stored as a packed triangular matrix. The j-th column of $\text{inv}(A)$ is stored in the array AP as follows: if UPLO = 'U', $\text{AP}(i + (j-1)*j/2) = \text{inv}(A)(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $\text{AP}(i + (j-1)*(2n-j)/2) = \text{inv}(A)(i,j)$ for $j \leq i \leq n$.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by ZSPTRF.

WORK (workspace)

Double complex array, dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

zspttrs - solve a system of linear equations $A \cdot X = B$ with a complex symmetric matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^{*T}$ or $A = L \cdot D \cdot L^{*T}$ computed by ZSPTRF

SYNOPSIS

```
SUBROUTINE ZSPTRS(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZSPTRS_64(UPLO, N, NRHS, AP, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SPTRS(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SPTRS_64(UPLO, [N], [NRHS], AP, IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zsptrs(char uplo, int n, int nrhs, doublecomplex *ap,
            int *ipivot, doublecomplex *b, int ldb, int
            *info);
```

```
void zsptrs_64(char uplo, long n, long nrhs, doublecomplex
               *ap, long *ipivot, doublecomplex *b, long ldb,
               long *info);
```

PURPOSE

zsptrs solves a system of linear equations $A \cdot X = B$ with a complex symmetric matrix A stored in packed format using the factorization $A = U \cdot D \cdot U^* \cdot T$ or $A = L \cdot D \cdot L^* \cdot T$ computed by ZSPTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U \cdot D \cdot U^* \cdot T$;
 = 'L': Lower triangular, form is $A = L \cdot D \cdot L^* \cdot T$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

AP (input)

Double complex array, dimension $(N \cdot (N+1) / 2)$ The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZSPTRF, stored as a packed triangular matrix.

IPIVOT (input)

Integer array, dimension (N) Details of the interchanges and the block structure of D as determined by ZSPTRF.

B (input/output)

Double complex array, dimension $(LDB, NRHS)$ On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)

= 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

zstedc - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method

SYNOPSIS

```
SUBROUTINE ZSTEDC(COMPZ, N, D, E, Z, LDZ, WORK, LWORK, RWORK, LRWORK,  
                IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 COMPZ  
DOUBLE COMPLEX Z(LDZ,*), WORK(*)  
INTEGER N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER IWORK(*)  
DOUBLE PRECISION D(*), E(*), RWORK(*)
```

```
SUBROUTINE ZSTEDC_64(COMPZ, N, D, E, Z, LDZ, WORK, LWORK, RWORK,  
                   LRWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 COMPZ  
DOUBLE COMPLEX Z(LDZ,*), WORK(*)  
INTEGER*8 N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER*8 IWORK(*)  
DOUBLE PRECISION D(*), E(*), RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEDC(COMPZ, [N], D, E, Z, [LDZ], [WORK], [LWORK], [RWORK],  
                [LRWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: Z  
INTEGER :: N, LDZ, LWORK, LRWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
REAL(8), DIMENSION(:) :: D, E, RWORK
```

```
SUBROUTINE STEDC_64(COMPZ, [N], D, E, Z, [LDZ], [WORK], [LWORK],  
                   [RWORK], [LRWORK], [IWORK], [LIWORK], [INFO])
```

```

CHARACTER(LEN=1) :: COMPZ
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: Z
INTEGER(8) :: N, LDZ, LWORK, LRWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8), DIMENSION(:) :: D, E, RWORK

```

C INTERFACE

```

#include <sunperf.h>
void zstedc(char compz, int n, double *d, double *e, doublecomplex *z, int ldz, int *info);

void zstedc_64(char compz, long n, double *d, double *e, doublecomplex *z, long ldz, long *info);

```

PURPOSE

zstedc computes all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the divide and conquer method. The eigenvectors of a full or band complex Hermitian matrix can also be found if CHETRD or CHPTRD or CHBTRD has been used to reduce this matrix to tridiagonal form.

This code makes very mild assumptions about floating point arithmetic. It will work on machines with a guard digit in add/subtract, or on those binary machines without guard digits which subtract like the Cray X-MP, Cray Y-MP, Cray C-90, or Cray-2. It could conceivably fail on hexadecimal or decimal machines without guard digits, but we know of none. See SLAED3 for details.

ARGUMENTS

COMPZ (input)

- = 'N': Compute eigenvalues only.
- = 'I': Compute eigenvectors of tridiagonal matrix also.
- = 'V': Compute eigenvectors of original Hermitian matrix also. On entry, Z contains the unitary matrix used to reduce the original matrix to tridiagonal form.

N (input) The dimension of the symmetric tridiagonal matrix.
N >= 0.

D (input/output)

On entry, the diagonal elements of the tridiagonal matrix. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)

On entry, the subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input) On entry, if COMPZ = 'V', then Z contains the

unitary matrix used in the reduction to tridiagonal form. On exit, if INFO = 0, then if COMPZ = 'V', Z contains the orthonormal eigenvectors of the original Hermitian matrix, and if COMPZ = 'I', Z contains the orthonormal eigenvectors of the symmetric tridiagonal matrix. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ \geq 1. If eigenvectors are desired, then LDZ \geq max(1,N).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If COMPZ = 'N' or 'I', or $N \leq 1$, LWORK must be at least 1. If COMPZ = 'V' and $N > 1$, LWORK must be at least N^2 .

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

RWORK (workspace)

dimension (LRWORK) On exit, if INFO = 0, RWORK(1) returns the optimal LRWORK.

LRWORK (input)

The dimension of the array RWORK. If COMPZ = 'N' or $N \leq 1$, LRWORK must be at least 1. If COMPZ = 'V' and $N > 1$, LRWORK must be at least $1 + 3*N + 2*N*\lg N + 3*N^2$, where $\lg(N)$ = smallest integer k such that $2^k \geq N$. If COMPZ = 'I' and $N > 1$, LRWORK must be at least $1 + 4*N + 2*N^2$.

If LRWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the RWORK array, returns this value as the first entry of the RWORK array, and no error message related to LRWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. If COMPZ = 'N' or $N \leq 1$, LIWORK must be at least 1. If COMPZ = 'V' or $N > 1$, LIWORK must be at least $6 + 6*N + 5*N*\lg N$. If COMPZ = 'I' or $N > 1$, LIWORK must be at least $3 + 5*N$.

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit.
< 0: if INFO = -i, the i-th argument had an illegal value.
> 0: The algorithm failed to compute an eigenvalue while working on the submatrix lying in rows and columns INFO/(N+1) through mod(INFO,N+1).

FURTHER DETAILS

Based on contributions by
Jeff Rutter, Computer Science Division, University of
California
at Berkeley, USA

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NAME

zstegr - Compute $T\text{-}\sigma_i = L_i D_i L_i^T$, such that $L_i D_i L_i^T$ is a relatively robust representation

SYNOPSIS

```
SUBROUTINE ZSTEGR(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M, W,  
  Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
DOUBLE COMPLEX Z(LDZ,*)  
INTEGER N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER ISUPPZ(*), IWORK(*)  
DOUBLE PRECISION VL, VU, ABSTOL  
DOUBLE PRECISION D(*), E(*), W(*), WORK(*)
```

```
SUBROUTINE ZSTEGR_64(JOBZ, RANGE, N, D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, LDZ, ISUPPZ, WORK, LWORK, IWORK, LIWORK, INFO)
```

```
CHARACTER * 1 JOBZ, RANGE  
DOUBLE COMPLEX Z(LDZ,*)  
INTEGER*8 N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER*8 ISUPPZ(*), IWORK(*)  
DOUBLE PRECISION VL, VU, ABSTOL  
DOUBLE PRECISION D(*), E(*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEGR(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL, M,  
  W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOBZ, RANGE  
COMPLEX(8), DIMENSION(:,:) :: Z  
INTEGER :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO  
INTEGER, DIMENSION(:) :: ISUPPZ, IWORK  
REAL(8) :: VL, VU, ABSTOL  
REAL(8), DIMENSION(:) :: D, E, W, WORK
```

```
SUBROUTINE STEGR_64(JOBZ, RANGE, [N], D, E, VL, VU, IL, IU, ABSTOL,  
  M, W, Z, [LDZ], ISUPPZ, [WORK], [LWORK], [IWORK], [LIWORK], [INFO])
```

```

CHARACTER(LEN=1) :: JOBZ, RANGE
COMPLEX(8), DIMENSION(:,:) :: Z
INTEGER(8) :: N, IL, IU, M, LDZ, LWORK, LIWORK, INFO
INTEGER(8), DIMENSION(:) :: ISUPPZ, IWORK
REAL(8) :: VL, VU, ABSTOL
REAL(8), DIMENSION(:) :: D, E, W, WORK

```

C INTERFACE

```

#include <sunperf.h>

void zstegr(char jobz, char range, int n, double *d, double
            *e, double vl, double vu, int il, int iu, double
            abstol, int *m, double *w, doublecomplex *z, int
            ldz, int *isuppz, int *info);

void zstegr_64(char jobz, char range, long n, double *d,
              double *e, double vl, double vu, long il, long iu,
              double abstol, long *m, double *w, doublecomplex
              *z, long ldz, long *isuppz, long *info);

```

PURPOSE

zstegr b) Compute the eigenvalues, λ_j , of $L_i D_i L_i^T$ to high relative accuracy by the dqds algorithm,

(c) If there is a cluster of close eigenvalues, "choose" σ_i close to the cluster, and go to step (a),

(d) Given the approximate eigenvalue λ_j of $L_i D_i L_i^T$, compute the corresponding eigenvector by forming a rank-revealing twisted factorization.

The desired accuracy of the output can be specified by the input parameter ABSTOL.

For more details, see "A new $O(n^2)$ algorithm for the symmetric tridiagonal eigenvalue/eigenvector problem", by Inderjit Dhillon, Computer Science Division Technical Report No. UCB/CSD-97-971, UC Berkeley, May 1997.

Note 1 : Currently ZSTEGR is only set up to find ALL the n eigenvalues and eigenvectors of T in $O(n^2)$ time

Note 2 : Currently the routine ZSTEIN is called when an appropriate σ_i cannot be chosen in step (c) above. ZSTEIN invokes modified Gram-Schmidt when eigenvalues are close.

Note 3 : ZSTEGR works only on machines which follow ieee-754 floating-point standard in their handling of infinities and NaNs. Normal execution of ZSTEGR may create NaNs and infinities and hence may abort due to a floating point exception in environments which do not conform to the ieee standard.

ARGUMENTS

JOBZ (input)
 = 'N': Compute eigenvalues only;

= 'V': Compute eigenvalues and eigenvectors.
 RANGE (input)
 = 'A': all eigenvalues will be found.
 = 'V': all eigenvalues in the half-open interval
 (VL,VU] will be found. = 'I': the IL-th through
 IU-th eigenvalues will be found.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)
 On entry, the n diagonal elements of the tridiagonal matrix T . On exit, D is overwritten.

E (input/output)
 On entry, the $(n-1)$ subdiagonal elements of the tridiagonal matrix T in elements 1 to $N-1$ of E ; $E(N)$ need not be set. On exit, E is overwritten.

VL (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

VU (input)
 If RANGE='V', the lower and upper bounds of the interval to be searched for eigenvalues. $VL < VU$. Not referenced if RANGE = 'A' or 'I'.

IL (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

IU (input)
 If RANGE='I', the indices (in ascending order) of the smallest and largest eigenvalues to be returned. $1 \leq IL \leq IU \leq N$, if $N > 0$; $IL = 1$ and $IU = 0$ if $N = 0$. Not referenced if RANGE = 'A' or 'V'.

ABSTOL (input)
 The absolute error tolerance for the eigenvalues/eigenvectors. IF JOBZ = 'V', the eigenvalues and eigenvectors output have residual norms bounded by ABSTOL, and the dot products between different eigenvectors are bounded by ABSTOL. If ABSTOL is less than $N \cdot \text{EPS} \cdot |T|$, then $N \cdot \text{EPS} \cdot |T|$ will be used in its place, where EPS is the machine precision and $|T|$ is the 1-norm of the tridiagonal matrix. The eigenvalues are computed to an accuracy of $\text{EPS} \cdot |T|$ irrespective of ABSTOL. If high relative accuracy is important, set ABSTOL to DLAMCH('Safe minimum'). See Barlow and Demmel "Computing Accurate Eigensystems of Scaled Diagonally Dominant Matrices", LAPACK Working Note #7 for a discussion of which matrices define their eigenvalues to high relative accuracy.

M (output)

The total number of eigenvalues found. $0 \leq M \leq N$. If RANGE = 'A', $M = N$, and if RANGE = 'I', $M = IU - IL + 1$.

W (output)

The first M elements contain the selected eigenvalues in ascending order.

Z (input) If JOBZ = 'V', then if INFO = 0, the first M columns of Z contain the orthonormal eigenvectors of the matrix T corresponding to the selected eigenvalues, with the i-th column of Z holding the eigenvector associated with W(i). If JOBZ = 'N', then Z is not referenced. Note: the user must ensure that at least $\max(1, M)$ columns are supplied in the array Z; if RANGE = 'V', the exact value of M is not known in advance and an upper bound must be used.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if JOBZ = 'V', $LDZ \geq \max(1, N)$.

ISUPPZ (output)

The support of the eigenvectors in Z, i.e., the indices indicating the nonzero elements in Z. The i-th eigenvector is nonzero only in elements ISUPPZ(2*i-1) through ISUPPZ(2*i).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal (and minimal) LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1, 18*N)$

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace/output)

On exit, if INFO = 0, IWORK(1) returns the optimal LIWORK.

LIWORK (input)

The dimension of the array IWORK. $LIWORK \geq \max(1, 10*N)$

If LIWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the IWORK array, returns this value as the first entry of the IWORK array, and no error message related to LIWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = 1, internal error in SLARRE, if
INFO = 2, internal error in CLARRV.

FURTHER DETAILS

Based on contributions by

Inderjit Dhillon, IBM Almaden, USA

Osni Marques, LBNL/NERSC, USA

Ken Stanley, Computer Science Division, University of
California at Berkeley, USA

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NAME

zstein - compute the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration

SYNOPSIS

```
SUBROUTINE ZSTEIN(N, D, E, M, W, IBLOCK, ISPLIT, Z, LDZ, WORK, IWORK,
                IFAIL, INFO)
```

```
DOUBLE COMPLEX Z(LDZ,*)
INTEGER N, M, LDZ, INFO
INTEGER IBLOCK(*), ISPLIT(*), IWORK(*), IFAIL(*)
DOUBLE PRECISION D(*), E(*), W(*), WORK(*)
```

```
SUBROUTINE ZSTEIN_64(N, D, E, M, W, IBLOCK, ISPLIT, Z, LDZ, WORK,
                    IWORK, IFAIL, INFO)
```

```
DOUBLE COMPLEX Z(LDZ,*)
INTEGER*8 N, M, LDZ, INFO
INTEGER*8 IBLOCK(*), ISPLIT(*), IWORK(*), IFAIL(*)
DOUBLE PRECISION D(*), E(*), W(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEIN([N], D, E, [M], W, IBLOCK, ISPLIT, Z, [LDZ], [WORK],
                [IWORK], IFAIL, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: Z
INTEGER :: N, M, LDZ, INFO
INTEGER, DIMENSION(:) :: IBLOCK, ISPLIT, IWORK, IFAIL
REAL(8), DIMENSION(:) :: D, E, W, WORK
```

```
SUBROUTINE STEIN_64([N], D, E, [M], W, IBLOCK, ISPLIT, Z, [LDZ],
                   [WORK], [IWORK], IFAIL, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: Z
INTEGER(8) :: N, M, LDZ, INFO
INTEGER(8), DIMENSION(:) :: IBLOCK, ISPLIT, IWORK, IFAIL
REAL(8), DIMENSION(:) :: D, E, W, WORK
```

C INTERFACE

```
#include <sunperf.h>

void zstein(int n, double *d, double *e, int m, double *w,
            int *iblock, int *isplit, doublecomplex *z, int
            ldz, int *ifail, int *info);
void zstein_64(long n, double *d, double *e, long m, double
               *w, long *iblock, long *isplit, doublecomplex *z,
               long ldz, long *ifail, long *info);
```

PURPOSE

zstein computes the eigenvectors of a real symmetric tridiagonal matrix T corresponding to specified eigenvalues, using inverse iteration.

The maximum number of iterations allowed for each eigenvector is specified by an internal parameter MAXITS (currently set to 5).

Although the eigenvectors are real, they are stored in a complex array, which may be passed to CUNMTR or CUPMTR for back transformation to the eigenvectors of a complex Hermitian matrix which was reduced to tridiagonal form.

ARGUMENTS

N (input) The order of the matrix. $N \geq 0$.

D (input) The n diagonal elements of the tridiagonal matrix T.

E (input) The (n-1) subdiagonal elements of the tridiagonal matrix T, stored in elements 1 to N-1; E(N) need not be set.

M (input) The number of eigenvectors to be found. $0 \leq M \leq N$.

W (input) The first M elements of W contain the eigenvalues for which eigenvectors are to be computed. The eigenvalues should be grouped by split-off block and ordered from smallest to largest within the block. (The output array W from SSTEBCZ with ORDER = 'B' is expected here.)

IBLOCK (input)
The submatrix indices associated with the corresponding eigenvalues in W; IBLOCK(i)=1 if eigenvalue W(i) belongs to the first submatrix from the top, =2 if W(i) belongs to the second submatrix, etc. (The output array IBLOCK from SSTEBCZ is expected here.)

ISPLIT (input)
The splitting points, at which T breaks up into

submatrices. The first submatrix consists of rows/columns 1 to ISPLIT(1), the second of rows/columns ISPLIT(1)+1 through ISPLIT(2), etc. (The output array ISPLIT from SSTEGBZ is expected here.)

Z (output)

The computed eigenvectors. The eigenvector associated with the eigenvalue W(i) is stored in the i-th column of Z. Any vector which fails to converge is set to its current iterate after MAXITS iterations. The imaginary parts of the eigenvectors are set to zero.

LDZ (input)

The leading dimension of the array Z. LDZ >= max(1,N).

WORK (workspace)

dimension(5*N)

IWORK (workspace)

dimension(N)

IFAIL (output)

On normal exit, all elements of IFAIL are zero. If one or more eigenvectors fail to converge after MAXITS iterations, then their indices are stored in array IFAIL.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, then i eigenvectors failed to converge in MAXITS iterations. Their indices are stored in array IFAIL.

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NAME

zsteqr - compute all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method

SYNOPSIS

```
SUBROUTINE ZSTEQR(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
DOUBLE COMPLEX Z(LDZ,*)  
INTEGER N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), WORK(*)
```

```
SUBROUTINE ZSTEQR_64(COMPZ, N, D, E, Z, LDZ, WORK, INFO)
```

```
CHARACTER * 1 COMPZ  
DOUBLE COMPLEX Z(LDZ,*)  
INTEGER*8 N, LDZ, INFO  
DOUBLE PRECISION D(*), E(*), WORK(*)
```

F95 INTERFACE

```
SUBROUTINE STEQR(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX(8), DIMENSION(:,*) :: Z  
INTEGER :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK
```

```
SUBROUTINE STEQR_64(COMPZ, [N], D, E, Z, [LDZ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: COMPZ  
COMPLEX(8), DIMENSION(:,*) :: Z  
INTEGER(8) :: N, LDZ, INFO  
REAL(8), DIMENSION(:) :: D, E, WORK
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zsteqr(char compz, int n, double *d, double *e, double  
            *z, int ldz, int *info);
```

```
void zsteqr_64(char compz, long n, double *d, double *e,  
doublecomplex *z, long ldz, long *info);
```

PURPOSE

zsteqr computes all eigenvalues and, optionally, eigenvectors of a symmetric tridiagonal matrix using the implicit QL or QR method. The eigenvectors of a full or band complex Hermitian matrix can also be found if CHETRD or CHPTRD or CHBTRD has been used to reduce this matrix to tridiagonal form.

ARGUMENTS

COMPZ (input)

= 'N': Compute eigenvalues only.
= 'V': Compute eigenvalues and eigenvectors of the original Hermitian matrix. On entry, Z must contain the unitary matrix used to reduce the original matrix to tridiagonal form. = 'I': Compute eigenvalues and eigenvectors of the tridiagonal matrix. Z is initialized to the identity matrix.

N (input) The order of the matrix. $N \geq 0$.

D (input/output)

On entry, the diagonal elements of the tridiagonal matrix. On exit, if INFO = 0, the eigenvalues in ascending order.

E (input/output)

On entry, the (n-1) subdiagonal elements of the tridiagonal matrix. On exit, E has been destroyed.

Z (input) On entry, if COMPZ = 'V', then Z contains the unitary matrix used in the reduction to tridiagonal form. On exit, if INFO = 0, then if COMPZ = 'V', Z contains the orthonormal eigenvectors of the original Hermitian matrix, and if COMPZ = 'I', Z contains the orthonormal eigenvectors of the symmetric tridiagonal matrix. If COMPZ = 'N', then Z is not referenced.

LDZ (input)

The leading dimension of the array Z. $LDZ \geq 1$, and if eigenvectors are desired, then $LDZ \geq \max(1, N)$.

WORK (workspace)

dimension($\max(1, 2*N-2)$) If COMPZ = 'N', then WORK is not referenced.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value
> 0: the algorithm has failed to find all the eigenvalues in a total of 30*N iterations; if INFO = i, then i elements of E have not converged to zero; on exit, D and E contain the elements of a symmetric tridiagonal matrix which is unitarily similar to the original matrix.

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NAME

zstsv - compute the solution to a complex system of linear equations $A * X = B$ where A is a symmetric tridiagonal matrix

SYNOPSIS

```
SUBROUTINE ZSTSV(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
DOUBLE COMPLEX L(*), D(*), SUBL(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE ZSTSV_64(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
DOUBLE COMPLEX L(*), D(*), SUBL(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE STSV([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: L, D, SUBL  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE STSV_64([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: L, D, SUBL  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zstsv(int n, int nrhs, doublecomplex *l, doublecomplex  
          *d, doublecomplex *subl, doublecomplex *b, int  
          ldb, int *ipiv, int *info);
```

```
void zstsv_64(long n, long nrhs, doublecomplex *l, doublecomplex *d, doublecomplex *subl, doublecomplex *b, long ldb, long *ipiv, long *info);
```

PURPOSE

zstsv computes the solution to a complex system of linear equations $A * X = B$ where A is a symmetric tridiagonal matrix.

ARGUMENTS

N (input)

The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides in B.

L (input/output)

COMPLEX array, dimension (N-1)

On entry, the n-1 subdiagonal elements of the tridiagonal matrix A. On exit, part of the factorization of A.

D (input/output)

REAL array, dimension (N)

On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the factorization of A.

SUBL (output)

COMPLEX array, dimension (N-2)

On exit, part of the factorization of A.

B (input/output)

The columns of B contain the right hand sides.

LDB (input)

The leading dimension of B as specified in a type or DIMENSION statement.

IPIV (output)

INTEGER array, dimension (N)

On exit, the pivot indices of the factorization.

INFO (output)

INTEGER

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular and division by zero will occur if it is used to solve a system of equations.

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NAME

zsttrf - compute the factorization of a complex symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE ZSTTRF(N, L, D, SUBL, IPIV, INFO)
```

```
DOUBLE COMPLEX L(*), D(*), SUBL(*)  
INTEGER N, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE ZSTTRF_64(N, L, D, SUBL, IPIV, INFO)
```

```
DOUBLE COMPLEX L(*), D(*), SUBL(*)  
INTEGER*8 N, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE STTRF([N], L, D, SUBL, IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: L, D, SUBL  
INTEGER :: N, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE STTRF_64([N], L, D, SUBL, IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: L, D, SUBL  
INTEGER(8) :: N, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zsttrf(int n, doublecomplex *l, doublecomplex *d, doublecomplex *subl, int *ipiv, int *info);
```

```
void zsttrf_64(long n, doublecomplex *l, doublecomplex *d, doublecomplex *subl, long *ipiv, long *info);
```

PURPOSE

zsttrf computes the L^*D^*L' factorization of a complex symmetric tridiagonal matrix A using the Bunch-Kaufman diagonal pivoting method.

ARGUMENTS

N (input) INTEGER
The order of the matrix A. $N \geq 0$.

L (input/output)
COMPLEX array, dimension (N-1)
On entry, the n-1 subdiagonal elements of the tridiagonal matrix A. On exit, part of the factorization of A.

D (input/output)
REAL array, dimension (N)
On entry, the n diagonal elements of the tridiagonal matrix A. On exit, the n diagonal elements of the diagonal matrix D from the factorization of A.

SUBL (output)
COMPLEX array, dimension (N-2)
On exit, part of the factorization of A.

IPIV (output)
INTEGER array, dimension (N)
On exit, the pivot indices of the factorization.

INFO (output)
INTEGER
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular and division by zero will occur if it is used to solve a system of equations.

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zsttrs - computes the solution to a complex system of linear equations $A * X = B$

SYNOPSIS

```
SUBROUTINE ZSTTRS(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
DOUBLE COMPLEX L(*), D(*), SUBL(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE ZSTTRS_64(N, NRHS, L, D, SUBL, B, LDB, IPIV, INFO)
```

```
DOUBLE COMPLEX L(*), D(*), SUBL(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE STTRS([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: L, D, SUBL  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE STTRS_64([N], [NRHS], L, D, SUBL, B, [LDB], IPIV, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: L, D, SUBL  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zsttrs(int n, int nrhs, doublecomplex *l, doublecomplex  
           *d, doublecomplex *subl, doublecomplex *b, int  
           ldb, int *ipiv, int *info);
```

```
void zsttrs_64(long n, long nrhs, doublecomplex *l, doub-
```

```
lecomplex *d, doublecomplex *subl, doublecomplex
*b, long ldb, long *ipiv, long *info);
```

PURPOSE

zsttrs computes the solution to a complex system of linear equations $A * X = B$, where A is an N -by- N symmetric tridiagonal matrix and X and B are N -by- $NRHS$ matrices.

ARGUMENTS

N (input) INTEGER
The order of the matrix A . $N \geq 0$.

NRHS (input)
INTEGER
The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

L (input) COMPLEX array, dimension $(N-1)$
On entry, the subdiagonal elements of L .

D (input) COMPLEX array, dimension (N)
On entry, the diagonal elements of D .

SUBL (input)
COMPLEX array, dimension $(N-2)$
On entry, the second subdiagonal elements of L .

B (input/output)
COMPLEX array, dimension $(LDB, NRHS)$
On entry, the N -by- $NRHS$ right hand side matrix B .
On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)
INTEGER
The leading dimension of the array B . $LDB \geq \max(1, N)$

IPIV (output)
INTEGER array, dimension (N)
Details of the interchanges and block pivot. If $IPIV(K) > 0$, 1 by 1 pivot, and if $IPIV(K) = K + 1$ an interchange done; If $IPIV(K) < 0$, 2 by 2 pivot, no interchange required.

INFO (output)
INTEGER
= 0: successful exit
< 0: if $INFO = -k$, the k -th argument had an illegal value

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zswap - Exchange vectors x and y.

SYNOPSIS

```
SUBROUTINE ZSWAP(N, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER N, INCX, INCY
```

```
SUBROUTINE ZSWAP_64(N, X, INCX, Y, INCY)
```

```
DOUBLE COMPLEX X(*), Y(*)  
INTEGER*8 N, INCX, INCY
```

F95 INTERFACE

```
SUBROUTINE SWAP([N], X, [INCX], Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER :: N, INCX, INCY
```

```
SUBROUTINE SWAP_64([N], X, [INCX], Y, [INCY])
```

```
COMPLEX(8), DIMENSION(:) :: X, Y  
INTEGER(8) :: N, INCX, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zswap(int n, doublecomplex *x, int incx, doublecomplex  
          *y, int incy);
```

```
void zswap_64(long n, doublecomplex *x, long incx, double-  
             lecomplex *y, long incy);
```

PURPOSE

zswap Exchange x and y where x and y are n-vectors.

ARGUMENTS

N (input)

On entry, N specifies the number of elements in the vector. N must be at least one for the subroutine to have any visible effect. Unchanged on exit.

X (input/output)

($1 + (n - 1) * \text{abs}(\text{INCX})$). On entry, the incremented array X must contain the vector x. On exit, the y vector.

INCX (input)

On entry, INCX specifies the increment for the elements of X. Unchanged on exit.

Y (input/output)

($1 + (n - 1) * \text{abs}(\text{INCY})$). On entry, the incremented array Y must contain the vector y. On exit, the x vector.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. Unchanged on exit.

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zsycon - estimate the reciprocal of the condition number (in the 1-norm) of a complex symmetric matrix A using the factorization $A = U^*D^*U^{**T}$ or $A = L^*D^*L^{**T}$ computed by ZSYTRF

SYNOPSIS

```
SUBROUTINE ZSYCON(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION ANORM, RCOND
```

```
SUBROUTINE ZSYCON_64(UPLO, N, A, LDA, IPIVOT, ANORM, RCOND, WORK,  
INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION ANORM, RCOND
```

F95 INTERFACE

```
SUBROUTINE SYCON(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8) :: ANORM, RCOND
```

```
SUBROUTINE SYCON_64(UPLO, [N], A, [LDA], IPIVOT, ANORM, RCOND, [WORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A
```

```
INTEGER(8) :: N, LDA, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: ANORM, RCOND
```

C INTERFACE

```
#include <sunperf.h>
void zsycon(char uplo, int n, doublecomplex *a, int lda, int
            *ipivot, double anorm, double *rcond, int *info);

void zsycon_64(char uplo, long n, doublecomplex *a, long
               lda, long *ipivot, double anorm, double *rcond,
               long *info);
```

PURPOSE

zsycon estimates the reciprocal of the condition number (in the 1-norm) of a complex symmetric matrix A using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by ZSYTRF.

An estimate is obtained for $\text{norm}(\text{inv}(A))$, and the reciprocal of the condition number is computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{norm}(\text{inv}(A)))$.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
= 'U': Upper triangular, form is $A = U*D*U^{**T}$;
= 'L': Lower triangular, form is $A = L*D*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZSYTRF.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by ZSYTRF.

ANORM (input)

The 1-norm of the original matrix A.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1 / (\text{ANORM} * \text{AINVM})$, where AINVM is an estimate of the 1-norm of $\text{inv}(A)$ computed in this routine.

WORK (workspace)

dimension(2*N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zsymm - perform one of the matrix-matrix operations $C := \alpha A * B + \beta C$ or $C := \alpha B * A + \beta C$

SYNOPSIS

```
SUBROUTINE ZSYMM(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                LDC)
```

```
CHARACTER * 1 SIDE, UPLO
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER M, N, LDA, LDB, LDC
```

```
SUBROUTINE ZSYMM_64(SIDE, UPLO, M, N, ALPHA, A, LDA, B, LDB, BETA, C,
                   LDC)
```

```
CHARACTER * 1 SIDE, UPLO
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 M, N, LDA, LDB, LDC
```

F95 INTERFACE

```
SUBROUTINE SYMM(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
               BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:,:) :: A, B, C
INTEGER :: M, N, LDA, LDB, LDC
```

```
SUBROUTINE SYMM_64(SIDE, UPLO, [M], [N], ALPHA, A, [LDA], B, [LDB],
                  BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:,:) :: A, B, C
INTEGER(8) :: M, N, LDA, LDB, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zsymm(char side, char uplo, int m, int n, doublecomplex
    *alpha, doublecomplex *a, int lda, doublecomplex
    *b, int ldb, doublecomplex *beta, doublecomplex
    *c, int ldc);
void zsymm_64(char side, char uplo, long m, long n, doub-
    lecomplex *alpha, doublecomplex *a, long lda,
    doublecomplex *b, long ldb, doublecomplex *beta,
    doublecomplex *c, long ldc);

```

PURPOSE

zsymm performs one of the matrix-matrix operations $C := \alpha A^*B + \beta C$ or $C := \alpha B^*A + \beta C$ where α and β are scalars, A is a symmetric matrix and B and C are m by n matrices.

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether the symmetric matrix A appears on the left or right in the operation as follows:

SIDE = 'L' or 'l' $C := \alpha A^*B + \beta C$,

SIDE = 'R' or 'r' $C := \alpha B^*A + \beta C$,

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the symmetric matrix A is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of the symmetric matrix is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of the symmetric matrix is to be referenced.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of the matrix C . $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of the matrix C . $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

COMPLEX*16 array of DIMENSION (LDA, ka), where ka is m when SIDE = 'L' or 'l' and is n otherwise.

Before entry with SIDE = 'L' or 'l', the m by m part of the array A must contain the symmetric matrix, such that when UPLO = 'U' or 'u', the leading m by m upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading m by m lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced.

Before entry with SIDE = 'R' or 'r', the n by n part of the array A must contain the symmetric matrix, such that when UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of A is not referenced, and when UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of A is not referenced.

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then LDA \geq max(1, m), otherwise LDA \geq max(1, n). Unchanged on exit.

B (input)

COMPLEX*16 array of DIMENSION (LDB, n). Before entry, the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. LDB \geq max(1, m). Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta. When BETA is supplied as zero then C need not be set on input. Unchanged on exit.

C (input/output)

COMPLEX*16 array of DIMENSION (LDC, n). Before entry, the leading m by n part of the array C must contain the matrix C, except when beta is zero, in which case C need not be set on entry. On exit, the array C is overwritten by the m by n updated matrix.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. LDC \geq max(1, m). Unchanged on exit.

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NAME

zsy2k - perform one of the symmetric rank 2k operations $C := \alpha A B' + \alpha B A' + \beta C$ or $C := \alpha A' B + \alpha B' A + \beta C$

SYNOPSIS

```
SUBROUTINE ZSYR2K(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA, C,
  LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER N, K, LDA, LDB, LDC
```

```
SUBROUTINE ZSYR2K_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, B, LDB, BETA,
  C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 N, K, LDA, LDB, LDC
```

F95 INTERFACE

```
SUBROUTINE SYR2K(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B, [LDB],
  BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:,*) :: A, B, C
INTEGER :: N, K, LDA, LDB, LDC
```

```
SUBROUTINE SYR2K_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], B,
  [LDB], BETA, C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA
COMPLEX(8) :: ALPHA, BETA
COMPLEX(8), DIMENSION(:,*) :: A, B, C
INTEGER(8) :: N, K, LDA, LDB, LDC
```

C INTERFACE

```

#include <sunperf.h>

void zsyr2k(char uplo, char transa, int n, int k, doublecom-
    plex *alpha, doublecomplex *a, int lda, doublecom-
    plex *b, int ldb, doublecomplex *beta, doublecom-
    plex *c, int ldc);
void zsyr2k_64(char uplo, char transa, long n, long k, doub-
    lecomplex *alpha, doublecomplex *a, long lda,
    doublecomplex *b, long ldb, doublecomplex *beta,
    doublecomplex *c, long ldc);

```

PURPOSE

zsyr2k performs one of the symmetric rank 2k operations $C := \alpha A^* B' + \alpha B^* A' + \beta C$ or $C := \alpha A^* B + \alpha B^* A + \beta C$ where α and β are scalars, C is an n by n symmetric matrix and A and B are n by k matrices in the first case and k by n matrices in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A^* B' + \alpha B^* A' + \beta C$.

TRANSA = 'T' or 't' $C := \alpha A^* B + \alpha B^* A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrices A and B ,

and on entry with `TRANSA = 'T' or 't'`, `K` specifies the number of rows of the matrices `A` and `B`. `K` must be at least zero. Unchanged on exit.

`ALPHA (input)`

On entry, `ALPHA` specifies the scalar `alpha`. Unchanged on exit.

`A (input)`

`COMPLEX*16` array of `DIMENSION (LDA, ka)`, where `ka` is `k` when `TRANSA = 'N' or 'n'`, and is `n` otherwise. Before entry with `TRANSA = 'N' or 'n'`, the leading `n` by `k` part of the array `A` must contain the matrix `A`, otherwise the leading `k` by `n` part of the array `A` must contain the matrix `A`. Unchanged on exit.

`LDA (input)`

On entry, `LDA` specifies the first dimension of `A` as declared in the calling (sub) program. When `TRANSA = 'N' or 'n'` then `LDA` must be at least `max(1, n)`, otherwise `LDA` must be at least `max(1, k)`. Unchanged on exit.

`B (input)`

`COMPLEX*16` array of `DIMENSION (LDB, kb)`, where `kb` is `k` when `TRANSA = 'N' or 'n'`, and is `n` otherwise. Before entry with `TRANSA = 'N' or 'n'`, the leading `n` by `k` part of the array `B` must contain the matrix `B`, otherwise the leading `k` by `n` part of the array `B` must contain the matrix `B`. Unchanged on exit.

`LDB (input)`

On entry, `LDB` specifies the first dimension of `B` as declared in the calling (sub) program. When `TRANSA = 'N' or 'n'` then `LDB` must be at least `max(1, n)`, otherwise `LDB` must be at least `max(1, k)`. Unchanged on exit.

`BETA (input)`

On entry, `BETA` specifies the scalar `beta`. Unchanged on exit.

`C (input/output)`

`COMPLEX*16` array of `DIMENSION (LDC, n)`.

Before entry with `UPLO = 'U' or 'u'`, the leading `n` by `n` upper triangular part of the array `C` must contain the upper triangular part of the symmetric matrix and the strictly lower triangular part of `C` is not referenced. On exit, the upper triangular part of the array `C` is overwritten by the upper triangular part of the updated matrix.

Before entry with `UPLO = 'L' or 'l'`, the leading `n` by `n` lower triangular part of the array `C` must contain the lower triangular part of the symmetric matrix and the strictly upper triangular part of `C` is not referenced. On exit, the

lower triangular part of the array C is overwritten by the lower triangular part of the updated matrix.

LDC (input)

On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. LDC must be at least $\max(1, n)$. Unchanged on exit.

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NAME

zsyrf5 - improve the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution

SYNOPSIS

```
SUBROUTINE ZSYRFS(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB, X,  
                LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX*),  
WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZSYRFS_64(UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B, LDB,  
                   X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX*),  
WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE SYRFS(UPLO, N, NRHS, A, [LDA], AF, [LDAF], IPIVOT, B, [LDB],  
                X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE SYRFS_64(UPLO, N, NRHS, A, [LDA], AF, [LDAF], IPIVOT, B,  
                   [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```

CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```

#include <sunperf.h>

void zsyrfb(char uplo, int n, int nrhs, doublecomplex *a,
            int lda, doublecomplex *af, int ldaf, int *ipivot,
            doublecomplex *b, int ldb, doublecomplex *x, int
            ldx, double *ferr, double *berr, int *info);

void zsyrfb_64(char uplo, long n, long nrhs, doublecomplex
               *a, long lda, doublecomplex *af, long ldaf, long
               *ipivot, doublecomplex *b, long ldb, doublecomplex
               *x, long ldx, double *ferr, double *berr, long
               *info);

```

PURPOSE

zsyrfb improves the computed solution to a system of linear equations when the coefficient matrix is symmetric indefinite, and provides error bounds and backward error estimates for the solution.

ARGUMENTS

UPLO (input)
 = 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)
 The leading dimension of the array A. $LDA \geq \max(1, N)$.

AF (input)
 The factored form of the matrix A. AF contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factori-

zation $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by ZSYTRF.

LDAF (input)

The leading dimension of the array AF. LDAF \geq max(1,N).

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by ZSYTRF.

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input/output)

On entry, the solution matrix X, as computed by ZSYTRS. On exit, the improved solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zsyrk - perform one of the symmetric rank k operations C
:= alpha*A*A' + beta*C or C := alpha*A'*A + beta*C

SYNOPSIS

```
SUBROUTINE ZSYRK(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(LDA,*), C(LDC,*)  
INTEGER N, K, LDA, LDC
```

```
SUBROUTINE ZSYRK_64(UPLO, TRANSA, N, K, ALPHA, A, LDA, BETA, C, LDC)
```

```
CHARACTER * 1 UPLO, TRANSA  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX A(LDA,*), C(LDC,*)  
INTEGER*8 N, K, LDA, LDC
```

F95 INTERFACE

```
SUBROUTINE SYRK(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA, C,  
[LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER :: N, K, LDA, LDC
```

```
SUBROUTINE SYRK_64(UPLO, [TRANSA], [N], [K], ALPHA, A, [LDA], BETA,  
C, [LDC])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA  
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER(8) :: N, K, LDA, LDC
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zsyrk(char uplo, char transa, int n, int k, doublecom-
```

```

plex *alpha, doublecomplex *a, int lda, doublecom-
plex *beta, doublecomplex *c, int ldc);

void zsyrrk_64(char uplo, char transa, long n, long k, doub-
lecomplex *alpha, doublecomplex *a, long lda,
doublecomplex *beta, doublecomplex *c, long ldc);

```

PURPOSE

zsyrrk performs one of the symmetric rank k operations $C := \alpha A^*A + \beta C$ or $C := \alpha A^*A + \beta C$ where α and β are scalars, C is an n by n symmetric matrix and A is an n by k matrix in the first case and a k by n matrix in the second case.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the upper or lower triangular part of the array C is to be referenced as follows:

UPLO = 'U' or 'u' Only the upper triangular part of C is to be referenced.

UPLO = 'L' or 'l' Only the lower triangular part of C is to be referenced.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $C := \alpha A^*A + \beta C$.

TRANSA = 'T' or 't' $C := \alpha A^*A + \beta C$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

N (input)

On entry, N specifies the order of the matrix C . N must be at least zero. Unchanged on exit.

K (input)

On entry with TRANSA = 'N' or 'n', K specifies the number of columns of the matrix A , and on entry with TRANSA = 'T' or 't', K specifies the number of rows of the matrix A . K must be at least zero. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar α . Unchanged on exit.

A (input)

COMPLEX*16 array of DIMENSION (LDA, ka),
where ka is k when TRANSA = 'N' or 'n', and is
n otherwise. Before entry with TRANSA = 'N' or
'n', the leading n by k part of the array A
must contain the matrix A, otherwise the leading
k by n part of the array A must contain the
matrix A. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A
as declared in the calling (sub) program.
When TRANSA = 'N' or 'n' then LDA must be at
least $\max(1, n)$, otherwise LDA must be at
least $\max(1, k)$. Unchanged on exit.

BETA (input)

On entry, BETA specifies the scalar beta.
Unchanged on exit.

C (input/output)

COMPLEX*16 array of DIMENSION (LDC, n).

Before entry with UPLO = 'U' or 'u', the lead-
ing n by n upper triangular part of the array C
must contain the upper triangular part of the
symmetric matrix and the strictly lower triangu-
lar part of C is not referenced. On exit, the
upper triangular part of the array C is overwrit-
ten by the upper triangular part of the updated
matrix.

Before entry with UPLO = 'L' or 'l', the lead-
ing n by n lower triangular part of the array C
must contain the lower triangular part of the
symmetric matrix and the strictly upper triangu-
lar part of C is not referenced. On exit, the
lower triangular part of the array C is overwrit-
ten by the lower triangular part of the updated
matrix.

LDC (input)

On entry, LDC specifies the first dimension of C
as declared in the calling (sub) program.
LDC must be at least $\max(1, n)$. Unchanged
on exit.

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NAME

zsysv - compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZSYSV(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK, LWORK,
                INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER N, NRHS, LDA, LDB, LWORK, INFO
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZSYSV_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, WORK,
                   LWORK, INFO)
```

```
CHARACTER * 1 UPLO
DOUBLE COMPLEX A(LDA,*), B(LDB,*), WORK(*)
INTEGER*8 N, NRHS, LDA, LDB, LWORK, INFO
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SYSV(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],
               [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B
INTEGER :: N, NRHS, LDA, LDB, LWORK, INFO
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SYSV_64(UPLO, [N], [NRHS], A, [LDA], IPIVOT, B, [LDB], [WORK],
                  [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B
INTEGER(8) :: N, NRHS, LDA, LDB, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void zsysv(char uplo, int n, int nrhs, doublecomplex *a, int
           lda, int *ipivot, doublecomplex *b, int ldb, int
           *info);
void zsysv_64(char uplo, long n, long nrhs, doublecomplex
              *a, long lda, long *ipivot, doublecomplex *b, long
              ldb, long *info);
```

PURPOSE

zsysv computes the solution to a complex system of linear equations

$A * X = B$, where A is an N-by-N symmetric matrix and X and B are N-by-NRHS matrices.

The diagonal pivoting method is used to factor A as

$A = U * D * U^{**T}$, if UPLO = 'U', or

$A = L * D * L^{**T}$, if UPLO = 'L',

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks. The factored form of A is then used to solve the system of equations $A * X = B$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, if INFO = 0, the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U * D * U^{**T}$ or $A = L * D * L^{**T}$ as computed by ZSYTRF.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D , as determined by ZSYTRF. If $IPIVOT(k) > 0$, then rows and columns k and $IPIVOT(k)$ were interchanged, and $D(k,k)$ is a 1-by-1 diagonal block. If $UPLO = 'U'$ and $IPIVOT(k) = IPIVOT(k-1) < 0$, then rows and columns $k-1$ and $-IPIVOT(k)$ were interchanged and $D(k-1:k,k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1,k:k+1)$ is a 2-by-2 diagonal block.

B (input/output)

On entry, the N -by- $NRHS$ right hand side matrix B .
On exit, if $INFO = 0$, the N -by- $NRHS$ solution matrix X .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1,N)$.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LWORK$.

LWORK (input)

The length of $WORK$. $LWORK \geq 1$, and for best performance $LWORK \geq N*NB$, where NB is the optimal blocksize for ZSYTRF.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $WORK$ array, returns this value as the first entry of the $WORK$ array, and no error message related to $LWORK$ is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $INFO = -i$, the i -th argument had an illegal value
> 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, so the solution could not be computed.

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NAME

zsysvx - use the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$,

SYNOPSIS

```
SUBROUTINE ZSYSVX(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT, B,  
                 LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
WORK(*)  
INTEGER N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER IPIVOT(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZSYSVX_64(FACT, UPLO, N, NRHS, A, LDA, AF, LDAF, IPIVOT,  
                   B, LDB, X, LDX, RCOND, FERR, BERR, WORK, LDWORK, WORK2, INFO)
```

```
CHARACTER * 1 FACT, UPLO  
DOUBLE COMPLEX A(LDA,*), AF(LDAF,*), B(LDB,*), X(LDX,*),  
WORK(*)  
INTEGER*8 N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER*8 IPIVOT(*)  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE SYSVX(FACT, UPLO, N, NRHS, A, [LDA], AF, [LDAF], IPIVOT,  
               B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK], [WORK2],  
               [INFO])
```

```
CHARACTER(LEN=1) :: FACT, UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, AF, B, X  
INTEGER :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```

SUBROUTINE ZSYSVX_64(FACT, UPLO, N, NRHS, A, [LDA], AF, [LDAF],
    IPIVOT, B, [LDB], X, [LDX], RCOND, FERR, BERR, [WORK], [LDWORK],
    [WORK2], [INFO])

```

```

CHARACTER(LEN=1) :: FACT, UPLO
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: A, AF, B, X
INTEGER(8) :: N, NRHS, LDA, LDAF, LDB, LDX, LDWORK, INFO
INTEGER(8), DIMENSION(:) :: IPIVOT
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zsysvx(char fact, char uplo, int n, int nrhs, doublecomplex *a, int lda, doublecomplex *af, int ldaf, int *ipivot, doublecomplex *b, int ldb, doublecomplex *x, int ldx, double *rcond, double *ferr, double *berr, int *info);

```

```

void zsysvx_64(char fact, char uplo, long n, long nrhs, doublecomplex *a, long lda, doublecomplex *af, long ldaf, long *ipivot, doublecomplex *b, long ldb, doublecomplex *x, long ldx, double *rcond, double *ferr, double *berr, long *info);

```

PURPOSE

zsysvx uses the diagonal pivoting factorization to compute the solution to a complex system of linear equations $A * X = B$, where A is an N -by- N symmetric matrix and X and B are N -by- $NRHS$ matrices.

Error bounds on the solution and a condition estimate are also provided.

The following steps are performed:

1. If $FACT = 'N'$, the diagonal pivoting method is used to factor A .

The form of the factorization is

$A = U * D * U^{*T}$, if $UPLO = 'U'$, or

$A = L * D * L^{*T}$, if $UPLO = 'L'$,

where U (or L) is a product of permutation and unit upper (lower)

triangular matrices, and D is symmetric and block diagonal with

1-by-1 and 2-by-2 diagonal blocks.

2. If some $D(i,i)=0$, so that D is exactly singular, then the routine

returns with $INFO = i$. Otherwise, the factored form of A is used

to estimate the condition number of the matrix A . If the reciprocal of the condition number is less than machine precision,

INFO = N+1 is returned as a warning, but the routine still goes on to solve for X and compute error bounds as described below.

3. The system of equations is solved for X using the factored form of A.

4. Iterative refinement is applied to improve the computed solution matrix and calculate error bounds and backward error estimates for it.

ARGUMENTS

FACT (input)

Specifies whether or not the factored form of A has been supplied on entry. = 'F': On entry, AF and IPIVOT contain the factored form of A. A, AF and IPIVOT will not be modified. = 'N': The matrix A will be copied to AF and factored.

UPLO (input)

= 'U': Upper triangle of A is stored;
= 'L': Lower triangle of A is stored.

N (input) The number of linear equations, i.e., the order of the matrix A. N >= 0.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. NRHS >= 0.

A (input) The symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

LDA (input)

The leading dimension of the array A. LDA >= max(1,N).

AF (input or output)

If FACT = 'F', then AF is an input argument and on entry contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ as computed by ZSYTRF.

If FACT = 'N', then AF is an output argument and on exit returns the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$.

LDAF (input)
The leading dimension of the array AF. LDAF \geq max(1,N).

IPIVOT (input or output)
If FACT = 'F', then IPIVOT is an input argument and on entry contains details of the interchanges and the block structure of D, as determined by ZSYTRF. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and D(k-1:k,k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIVOT(k) = IPIVOT(k+1) < 0, then rows and columns k+1 and -IPIVOT(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

If FACT = 'N', then IPIVOT is an output argument and on exit contains details of the interchanges and the block structure of D, as determined by ZSYTRF.

B (input) The N-by-NRHS right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB \geq max(1,N).

X (output)
If INFO = 0 or INFO = N+1, the N-by-NRHS solution matrix X.

LDX (input)
The leading dimension of the array X. LDX \geq max(1,N).

RCOND (output)
The estimate of the reciprocal condition number of the matrix A. If RCOND is less than the machine precision (in particular, if RCOND = 0), the matrix is singular to working precision. This condition is indicated by a return code of INFO > 0.

FERR (output)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LDWORK.

LDWORK (input)
The length of WORK. LDWORK $\geq 2*N$, and for best performance LDWORK $\geq N*NB$, where NB is the optimal blocksize for ZSYTRF.

If LDWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LDWORK is issued by XERBLA.

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, and i is
<= N: D(i,i) is exactly zero. The factorization has been completed but the factor D is exactly singular, so the solution and error bounds could not be computed. RCOND = 0 is returned. = N+1: D is nonsingular, but RCOND is less than machine precision, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of RCOND would suggest.

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NAME

zsytf2 - compute the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE ZSYTF2(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO  
INTEGER IPIV(*)
```

```
SUBROUTINE ZSYTF2_64(UPLO, N, A, LDA, IPIV, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIV(*)
```

F95 INTERFACE

```
SUBROUTINE SYTF2(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIV
```

```
SUBROUTINE SYTF2_64(UPLO, [N], A, [LDA], IPIV, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIV
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zsytf2(char uplo, int n, doublecomplex *a, int lda, int
```

```

        *ipiv, int *info);

void zsytf2_64(char uplo, long n, doublecomplex *a, long
        lda, long *ipiv, long *info);

```

PURPOSE

zsytf2 computes the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method:

$$A = U^*D^*U' \quad \text{or} \quad A = L^*D^*L'$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, U' is the transpose of U, and D is symmetric and block diagonal with 1-by-1 and 2-by-2 diagonal blocks.

This is the unblocked version of the algorithm, calling Level 2 BLAS.

ARGUMENTS

UPLO (input)

Specifies whether the upper or lower triangular part of the symmetric matrix A is stored:

= 'U': Upper triangular
 = 'L': Lower triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading n-by-n upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n-by-n lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIV (output)

Details of the interchanges and the block structure of D. If IPIV(k) > 0, then rows and columns k and IPIV(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIV(k) = IPIV(k-1) < 0, then rows and columns k-1 and -IPIV(k) were interchanged and D(k-1:k, k-1:k) is a 2-by-2 diagonal block. If UPLO = 'L' and IPIV(k) = IPIV(k+1) < 0, then rows and columns k+1 and

-IPIV(k) were interchanged and D(k:k+1,k:k+1) is a 2-by-2 diagonal block.

INFO (output)

= 0: successful exit
 < 0: if INFO = -k, the k-th argument had an illegal value
 > 0: if INFO = k, D(k,k) is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

1-96 - Based on modifications by J. Lewis, Boeing Computer Services Company

If UPLO = 'U', then $A = U^*D^*U'$, where $U = P(n)^*U(n)^* \dots *P(k)^*U(k)^* \dots$, i.e., U is a product of terms $P(k)^*U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and U(k) is a unit upper triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(1:k-1,k). If s = 2, the upper triangle of D(k) overwrites A(k-1,k-1), A(k-1,k), and A(k,k), and v overwrites A(1:k-2,k-1:k).

If UPLO = 'L', then $A = L^*D^*L'$, where $L = P(1)^*L(1)^* \dots *P(k)^*L(k)^* \dots$, i.e., L is a product of terms $P(k)^*L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks D(k). P(k) is a permutation matrix as defined by IPIV(k), and L(k) is a unit lower triangular matrix, such that if the diagonal block D(k) is of order s (s = 1 or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If s = 1, D(k) overwrites A(k,k), and v overwrites A(k+1:n,k). If s = 2, the lower triangle of D(k) overwrites A(k,k), A(k+1,k), and A(k+1,k+1), and v overwrites A(k+2:n,k:k+1).

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NAME

zsytrf - compute the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method

SYNOPSIS

```
SUBROUTINE ZSYTRF(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, LDWORK, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZSYTRF_64(UPLO, N, A, LDA, IPIVOT, WORK, LDWORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, LDWORK, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRF(UPLO, N, A, [LDA], IPIVOT, [WORK], [LDWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LDWORK, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SYTRF_64(UPLO, N, A, [LDA], IPIVOT, [WORK], [LDWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, LDWORK, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>

void zsytrf(char uplo, int n, doublecomplex *a, int lda, int
            *ipivot, int *info);

void zsytrf_64(char uplo, long n, doublecomplex *a, long
              lda, long *ipivot, long *info);
```

PURPOSE

zsytrf computes the factorization of a complex symmetric matrix A using the Bunch-Kaufman diagonal pivoting method. The form of the factorization is

$$A = U*D*U**T \quad \text{or} \quad A = L*D*L**T$$

where U (or L) is a product of permutation and unit upper (lower) triangular matrices, and D is symmetric and block diagonal with with 1-by-1 and 2-by-2 diagonal blocks.

This is the blocked version of the algorithm, calling Level 3 BLAS.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A is stored;
 = 'L': Lower triangle of A is stored.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the symmetric matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of A contains the upper triangular part of the matrix A, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of A contains the lower triangular part of the matrix A, and the strictly upper triangular part of A is not referenced.

On exit, the block diagonal matrix D and the multipliers used to obtain the factor U or L (see below for further details).

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (output)

Details of the interchanges and the block structure of D. If IPIVOT(k) > 0, then rows and columns k and IPIVOT(k) were interchanged and D(k,k) is a 1-by-1 diagonal block. If UPLO = 'U' and IPIVOT(k) = IPIVOT(k-1) < 0, then rows and columns k-1 and -IPIVOT(k) were interchanged and

$D(k-1:k, k-1:k)$ is a 2-by-2 diagonal block. If $UPLO = 'L'$ and $IPIVOT(k) = IPIVOT(k+1) < 0$, then rows and columns $k+1$ and $-IPIVOT(k)$ were interchanged and $D(k:k+1, k:k+1)$ is a 2-by-2 diagonal block.

WORK (workspace)

On exit, if $INFO = 0$, $WORK(1)$ returns the optimal $LDWORK$.

$LDWORK$ (input)

The length of $WORK$. $LDWORK \geq 1$. For best performance $LDWORK \geq N * NB$, where NB is the block size returned by $ILAENV$.

If $LDWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the $WORK$ array, returns this value as the first entry of the $WORK$ array, and no error message related to $LDWORK$ is issued by $XERBLA$.

INFO (output)

= 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value
 > 0: if $INFO = i$, $D(i,i)$ is exactly zero. The factorization has been completed, but the block diagonal matrix D is exactly singular, and division by zero will occur if it is used to solve a system of equations.

FURTHER DETAILS

If $UPLO = 'U'$, then $A = U * D * U'$, where

$$U = P(n) * U(n) * \dots * P(k) * U(k) * \dots,$$

i.e., U is a product of terms $P(k) * U(k)$, where k decreases from n to 1 in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by $IPIVOT(k)$, and $U(k)$ is a unit upper triangular matrix, such that if the diagonal block $D(k)$ is of order s ($s = 1$ or 2), then

$$U(k) = \begin{pmatrix} I & v & 0 &) & k-s \\ 0 & I & 0 &) & s \\ 0 & 0 & I &) & n-k \\ k-s & s & n-k & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(1:k-1, k)$. If $s = 2$, the upper triangle of $D(k)$ overwrites $A(k-1, k-1)$, $A(k-1, k)$, and $A(k, k)$, and v overwrites $A(1:k-2, k-1:k)$.

If $UPLO = 'L'$, then $A = L * D * L'$, where

$$L = P(1) * L(1) * \dots * P(k) * L(k) * \dots,$$

i.e., L is a product of terms $P(k) * L(k)$, where k increases from 1 to n in steps of 1 or 2, and D is a block diagonal matrix with 1-by-1 and 2-by-2 diagonal blocks $D(k)$. $P(k)$ is a permutation matrix as defined by $IPIVOT(k)$, and $L(k)$ is a unit lower triangular matrix, such that if the diagonal block $D(k)$ is of order s ($s = 1$ or 2), then

$$L(k) = \begin{pmatrix} I & 0 & 0 &) & k-1 \\ 0 & I & 0 &) & s \\ 0 & v & I &) & n-k-s+1 \\ k-1 & s & n-k-s+1 & & \end{pmatrix}$$

If $s = 1$, $D(k)$ overwrites $A(k,k)$, and v overwrites $A(k+1:n,k)$. If $s = 2$, the lower triangle of $D(k)$ overwrites $A(k,k)$, $A(k+1,k)$, and $A(k+1,k+1)$, and v overwrites $A(k+2:n,k:k+1)$.

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NAME

zsytri - compute the inverse of a complex symmetric indefinite matrix A using the factorization $A = U*D*U**T$ or $A = L*D*L**T$ computed by ZSYTRF

SYNOPSIS

```
SUBROUTINE ZSYTRI(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZSYTRI_64(UPLO, N, A, LDA, IPIVOT, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRI(UPLO, N, A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,) :: A  
INTEGER :: N, LDA, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SYTRI_64(UPLO, N, A, [LDA], IPIVOT, [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,) :: A  
INTEGER(8) :: N, LDA, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```

void zsytri(char uplo, int n, doublecomplex *a, int lda, int
           *ipivot, int *info);

void zsytri_64(char uplo, long n, doublecomplex *a, long
              lda, long *ipivot, long *info);

```

PURPOSE

zsytri computes the inverse of a complex symmetric indefinite matrix A using the factorization $A = U*D*U^{**T}$ or $A = L*D*L^{**T}$ computed by ZSYTRF.

ARGUMENTS

UPLO (input)

Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U*D*U^{**T}$;
 = 'L': Lower triangular, form is $A = L*D*L^{**T}$.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZSYTRF.

On exit, if INFO = 0, the (symmetric) inverse of the original matrix. If UPLO = 'U', the upper triangular part of the inverse is formed and the part of A below the diagonal is not referenced; if UPLO = 'L' the lower triangular part of the inverse is formed and the part of A above the diagonal is not referenced.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

IPIVOT (input)

Details of the interchanges and the block structure of D as determined by ZSYTRF.

WORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value
 > 0: if INFO = i, $D(i,i) = 0$; the matrix is singular and its inverse could not be computed.

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NAME

zsytrs - solve a system of linear equations $A \cdot X = B$ with a complex symmetric matrix A using the factorization $A = U \cdot D \cdot U^* \cdot T$ or $A = L \cdot D \cdot L^* \cdot T$ computed by ZSYTRF

SYNOPSIS

```
SUBROUTINE ZSYTRS(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO  
INTEGER IPIVOT(*)
```

```
SUBROUTINE ZSYTRS_64(UPLO, N, NRHS, A, LDA, IPIVOT, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO  
INTEGER*8 IPIVOT(*)
```

F95 INTERFACE

```
SUBROUTINE SYTRS(UPLO, N, NRHS, A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO  
INTEGER, DIMENSION(:) :: IPIVOT
```

```
SUBROUTINE SYTRS_64(UPLO, N, NRHS, A, [LDA], IPIVOT, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:,*) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO  
INTEGER(8), DIMENSION(:) :: IPIVOT
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zsytrs(char uplo, int n, int nrhs, doublecomplex *a,  
            int lda, int *ipivot, doublecomplex *b, int ldb,
```

```

        int *info);

void zsytrs_64(char uplo, long n, long nrhs, doublecomplex
              *a, long lda, long *ipivot, doublecomplex *b, long
              ldb, long *info);

```

PURPOSE

zsytrs solves a system of linear equations $A \cdot X = B$ with a complex symmetric matrix A using the factorization $A = U \cdot D \cdot U^* \cdot T$ or $A = L \cdot D \cdot L^* \cdot T$ computed by ZSYTRF.

ARGUMENTS

UPLO (input)
 Specifies whether the details of the factorization are stored as an upper or lower triangular matrix.
 = 'U': Upper triangular, form is $A = U \cdot D \cdot U^* \cdot T$;
 = 'L': Lower triangular, form is $A = L \cdot D \cdot L^* \cdot T$.

N (input) The order of the matrix A . $N \geq 0$.

NRHS (input)
 The number of right hand sides, i.e., the number of columns of the matrix B . $NRHS \geq 0$.

A (input) The block diagonal matrix D and the multipliers used to obtain the factor U or L as computed by ZSYTRF.

LDA (input)
 The leading dimension of the array A . $LDA \geq \max(1, N)$.

IPIVOT (input)
 Details of the interchanges and the block structure of D as determined by ZSYTRF.

B (input/output)
 On entry, the right hand side matrix B . On exit, the solution matrix X .

LDB (input)
 The leading dimension of the array B . $LDB \geq \max(1, N)$.

INFO (output)
 = 0: successful exit
 < 0: if $INFO = -i$, the i -th argument had an illegal value

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NAME

ztbcon - estimate the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE ZTBCON(NORM, UPLO, DIAG, N, KD, A, LDA, RCOND, WORK,  
                WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, KD, LDA, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZTBCON_64(NORM, UPLO, DIAG, N, KD, A, LDA, RCOND, WORK,  
                   WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, KD, LDA, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TBCON(NORM, UPLO, DIAG, [N], KD, A, [LDA], RCOND, [WORK],  
                [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, KD, LDA, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE TBCON_64(NORM, UPLO, DIAG, [N], KD, A, [LDA], RCOND,  
                   [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX(8), DIMENSION(:) :: WORK
```

```
COMPLEX(8), DIMENSION(:,:) :: A
INTEGER(8) :: N, KD, LDA, INFO
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>
void ztbcon(char norm, char uplo, char diag, int n, int kd,
            doublecomplex *a, int lda, double *rcond, int
            *info);

void ztbcon_64(char norm, char uplo, char diag, long n, long
              kd, doublecomplex *a, long lda, double *rcond,
              long *info);
```

PURPOSE

ztbcon estimates the reciprocal of the condition number of a triangular band matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

A (input)

The upper or lower triangular band matrix A, stored in the first $kd+1$ rows of the array. The j -th column of A is stored in the j -th column of the array A as follows: if $\text{UPLO} = 'U'$, $A(kd+1+i-j, j) = A(i, j)$ for $\max(1, j-kd) \leq i \leq j$; if $\text{UPLO} = 'L'$, $A(1+i-j, j) = A(i, j)$ for $j \leq i \leq \min(n, j+kd)$. If $\text{DIAG} = 'U'$, the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)
The leading dimension of the array A. LDA \geq
KD+1.

RCOND (output)
The reciprocal of the condition number of the
matrix A, computed as RCOND = $1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ztbmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$

SYNOPSIS

```
SUBROUTINE ZTBMV(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), Y(*)  
INTEGER N, K, LDA, INCY
```

```
SUBROUTINE ZTBMV_64(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), Y(*)  
INTEGER*8 N, K, LDA, INCY
```

F95 INTERFACE

```
SUBROUTINE TBMV(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, K, LDA, INCY
```

```
SUBROUTINE TBMV_64(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, K, LDA, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztbmv(char uplo, char transa, char diag, int n, int k,  
doublecomplex *a, int lda, doublecomplex *y, int  
incy);
```

```
void ztbmv_64(char uplo, char transa, char diag, long n,
              long k, doublecomplex *a, long lda, doublecomplex
              *y, long incy);
```

PURPOSE

ztbmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A)*x$ where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular band matrix, with $(k + 1)$ diagonals.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := \text{conjg}(A)*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

K (input)

On entry with UPLO = 'U' or 'u', K specifies the

number of super-diagonals of the matrix A. On entry with UPLO = 'L' or 'l', K specifies the number of sub-diagonals of the matrix A. K >= 0. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading (k + 1) by n part of the array A must contain the upper triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (k + 1) of the array, the first super-diagonal starting at position 2 in row k, and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer an upper triangular band matrix from conventional full matrix storage to band storage:

```
      DO 20, J = 1, N
        M = K + 1 - J
        DO 10, I = MAX( 1, J - K ), J
          A( M + I, J ) = matrix( I, J )
10     CONTINUE
20    CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer a lower triangular band matrix from conventional full matrix storage to band storage:

```
      DO 20, J = 1, N
        M = 1 - J
        DO 10, I = J, MIN( N, J + K )
          A( M + I, J ) = matrix( I, J )
10     CONTINUE
20    CONTINUE
```

Note that when DIAG = 'U' or 'u' the elements of the array A corresponding to the diagonal elements of the matrix are not referenced, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= (k + 1). Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the

elements of Y. INCY <> 0. Unchanged on exit.

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NAME

ztbrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix

SYNOPSIS

```
SUBROUTINE ZTBRFS(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B, LDB,  
X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, KD, NRHS, LDA, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZTBRFS_64(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B,  
LDB, X, LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, KD, NRHS, LDA, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TBRFS(UPLO, [TRANSA], DIAG, N, KD, NRHS, A, [LDA], B,  
[LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, B, X  
INTEGER :: N, KD, NRHS, LDA, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE TBRFS_64(UPLO, [TRANSA], DIAG, N, KD, NRHS, A, [LDA],  
B, [LDB], X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, B, X  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void ztbrfs(char uplo, char transa, char diag, int n, int
           kd, int nrhs, doublecomplex *a, int lda, doublecomplex
           *b, int ldb, doublecomplex *x, int ldx,
           double *ferr, double *berr, int *info);

void ztbrfs_64(char uplo, char transa, char diag, long n,
              long kd, long nrhs, doublecomplex *a, long lda,
              doublecomplex *b, long ldb, doublecomplex *x, long
              ldx, double *ferr, double *berr, long *info);
```

PURPOSE

ztbrfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular band coefficient matrix.

The solution matrix X must be computed by ZTBTRS or some other means before entering this routine. ZTBRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first kd+1 rows of the array. The j-th column of A is stored in the j-th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-$

$j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. LDA \geq KD+1.

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input) The solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ztbsv - solve one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A')*x = b$

SYNOPSIS

```
SUBROUTINE ZTBSV(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), Y(*)  
INTEGER N, K, LDA, INCY
```

```
SUBROUTINE ZTBSV_64(UPLO, TRANSA, DIAG, N, K, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), Y(*)  
INTEGER*8 N, K, LDA, INCY
```

F95 INTERFACE

```
SUBROUTINE TBSV(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, K, LDA, INCY
```

```
SUBROUTINE TBSV_64(UPLO, [TRANSA], DIAG, [N], K, A, [LDA], Y,  
[INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, K, LDA, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztbsv(char uplo, char transa, char diag, int n, int k,  
doublecomplex *a, int lda, doublecomplex *y, int  
incy);
```

```
void ztbsv_64(char uplo, char transa, char diag, long n,
             long k, doublecomplex *a, long lda, doublecomplex
             *y, long incy);
```

PURPOSE

ztbsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A)*x = b$ where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular band matrix, with $(k + 1)$ diagonals.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the equations to be solved as follows:

TRANSA = 'N' or 'n' $A*x = b$.

TRANSA = 'T' or 't' $A'*x = b$.

TRANSA = 'C' or 'c' $\text{conjg}(A)*x = b$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A .

N >= 0. Unchanged on exit.

K (input)

On entry with UPLO = 'U' or 'u', K specifies the number of super-diagonals of the matrix A. On entry with UPLO = 'L' or 'l', K specifies the number of sub-diagonals of the matrix A. K >= 0. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading (k + 1) by n part of the array A must contain the upper triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row (k + 1) of the array, the first super-diagonal starting at position 2 in row k, and so on. The top left k by k triangle of the array A is not referenced. The following program segment will transfer an upper triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = K + 1 - J
  DO 10, I = MAX( 1, J - K ), J
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Before entry with UPLO = 'L' or 'l', the leading (k + 1) by n part of the array A must contain the lower triangular band part of the matrix of coefficients, supplied column by column, with the leading diagonal of the matrix in row 1 of the array, the first sub-diagonal starting at position 1 in row 2, and so on. The bottom right k by k triangle of the array A is not referenced. The following program segment will transfer a lower triangular band matrix from conventional full matrix storage to band storage:

```
DO 20, J = 1, N
  M = 1 - J
  DO 10, I = J, MIN( N, J + K )
    A( M + I, J ) = matrix( I, J )
10  CONTINUE
20  CONTINUE
```

Note that when DIAG = 'U' or 'u' the elements of the array A corresponding to the diagonal elements of the matrix are not referenced, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= (k + 1). Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwrit-

ten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY \neq 0. Unchanged on exit.

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NAME

zbtbtrs - solve a triangular system of the form $A * X = B$,
 $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE ZBTBTRS(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B, LDB,  
INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE ZBTBTRS_64(UPLO, TRANSA, DIAG, N, KD, NRHS, A, LDA, B,  
LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, KD, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE TBTRS(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA], B,  
[LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER :: N, KD, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE TBTRS_64(UPLO, [TRANSA], DIAG, [N], KD, [NRHS], A, [LDA], B,  
[LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:, :) :: A, B  
INTEGER(8) :: N, KD, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zbtbtrs(char uplo, char transa, char diag, int n, int  
kd, int nrhs, doublecomplex *a, int lda, doub-  
lecomplex *b, int ldb, int *info);
```

```
void ztbtrs_64(char uplo, char transa, char diag, long n,
              long kd, long nrhs, doublecomplex *a, long lda,
              doublecomplex *b, long ldb, long *info);
```

PURPOSE

ztbtrs solves a triangular system of the form

$A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$

where A is a triangular band matrix of order N, and B is an N-by-NRHS matrix. A check is made to verify that A is non-singular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:

= 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose)

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

KD (input)

The number of superdiagonals or subdiagonals of the triangular band matrix A. $KD \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The upper or lower triangular band matrix A, stored in the first $kd+1$ rows of A. The j -th column of A is stored in the j -th column of the array A as follows: if UPLO = 'U', $A(kd+1+i-j,j) = A(i,j)$ for $\max(1,j-kd) \leq i \leq j$; if UPLO = 'L', $A(1+i-j,j) = A(i,j)$ for $j \leq i \leq \min(n,j+kd)$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq KD+1$.

B (input/output)

On entry, the right hand side matrix B. On exit, if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

> 0: if INFO = i, the i-th diagonal element of A is zero, indicating that the matrix is singular and the solutions X have not been computed.

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NAME

ztgevc - compute some or all of the right and/or left generalized eigenvectors of a pair of complex upper triangular matrices (A,B)

SYNOPSIS

```
SUBROUTINE ZTGEVC(SIDE, HOWMNY, SELECT, N, A, LDA, B, LDB, VL, LDVL,
                 VR, LDVR, MM, M, WORK, RWORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY
DOUBLE COMPLEX A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*),
WORK(*)
INTEGER N, LDA, LDB, LDVL, LDVR, MM, M, INFO
LOGICAL SELECT(*)
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZTGEVC_64(SIDE, HOWMNY, SELECT, N, A, LDA, B, LDB, VL,
                   LDVL, VR, LDVR, MM, M, WORK, RWORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY
DOUBLE COMPLEX A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*),
WORK(*)
INTEGER*8 N, LDA, LDB, LDVL, LDVR, MM, M, INFO
LOGICAL*8 SELECT(*)
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE TGEVC(SIDE, HOWMNY, SELECT, [N], A, [LDA], B, [LDB], VL,
                [LDVL], VR, [LDVR], MM, M, [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, VL, VR
INTEGER :: N, LDA, LDB, LDVL, LDVR, MM, M, INFO
LOGICAL, DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: RWORK
```

```
SUBROUTINE TGEVC_64(SIDE, HOWMNY, SELECT, [N], A, [LDA], B, [LDB],
                   VL, [LDVL], VR, [LDVR], MM, M, [WORK], [RWORK], [INFO])
```

```

CHARACTER(LEN=1) :: SIDE, HOWMNY
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, VL, VR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, MM, M, INFO
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>

void ztgevc(char side, char howmny, int *select, int n,
            doublecomplex *a, int lda, doublecomplex *b, int
            ldb, doublecomplex *vl, int ldvl, doublecomplex
            *vr, int ldvr, int mm, int *m, int *info);

void ztgevc_64(char side, char howmny, long *select, long n,
               doublecomplex *a, long lda, doublecomplex *b, long
               ldb, doublecomplex *vl, long ldvl, doublecomplex
               *vr, long ldvr, long mm, long *m, long *info);

```

PURPOSE

ztgevc computes some or all of the right and/or left generalized eigenvectors of a pair of complex upper triangular matrices (A,B).

The right generalized eigenvector x and the left generalized eigenvector y of (A,B) corresponding to a generalized eigenvalue w are defined by:

$$(A - wB) * x = 0 \quad \text{and} \quad y^{*H} * (A - wB) = 0$$

where y^{*H} denotes the conjugate transpose of y .

If an eigenvalue w is determined by zero diagonal elements of both A and B , a unit vector is returned as the corresponding eigenvector.

If all eigenvectors are requested, the routine may either return the matrices X and/or Y of right or left eigenvectors of (A,B), or the products $Z*X$ and/or $Q*Y$, where Z and Q are input unitary matrices. If (A,B) was obtained from the generalized Schur factorization of an original pair of matrices

$$(A0, B0) = (Q*A*Z^{*H}, Q*B*Z^{*H}),$$

then $Z*X$ and $Q*Y$ are the matrices of right or left eigenvectors of A .

ARGUMENTS

SIDE (input)

```

= 'R': compute right eigenvectors only;
= 'L': compute left eigenvectors only;
= 'B': compute both right and left eigenvectors.

```

HOWMNY (input)

```

= 'A': compute all right and/or left eigenvectors;
= 'B': compute all right and/or left eigenvectors,

```

and backtransform them using the input matrices supplied in VR and/or VL; = 'S': compute selected right and/or left eigenvectors, specified by the logical array SELECT.

SELECT (input)

If HOWMNY='S', SELECT specifies the eigenvectors to be computed. If HOWMNY='A' or 'B', SELECT is not referenced. To select the eigenvector corresponding to the j-th eigenvalue, SELECT(j) must be set to .TRUE..

N (input) The order of the matrices A and B. $N \geq 0$.

A (input) The upper triangular matrix A.

LDA (input)

The leading dimension of array A. $LDA \geq \max(1,N)$.

B (input) The upper triangular matrix B. B must have real diagonal elements.

LDB (input)

The leading dimension of array B. $LDB \geq \max(1,N)$.

VL (input/output)

On entry, if SIDE = 'L' or 'B' and HOWMNY = 'B', VL must contain an N-by-N matrix Q (usually the unitary matrix Q of left Schur vectors returned by CHGEQZ). On exit, if SIDE = 'L' or 'B', VL contains: if HOWMNY = 'A', the matrix Y of left eigenvectors of (A,B); if HOWMNY = 'B', the matrix $Q*Y$; if HOWMNY = 'S', the left eigenvectors of (A,B) specified by SELECT, stored consecutively in the columns of VL, in the same order as their eigenvalues. If SIDE = 'R', VL is not referenced.

LDVL (input)

The leading dimension of array VL. $LDVL \geq \max(1,N)$ if SIDE = 'L' or 'B'; $LDVL \geq 1$ otherwise.

VR (input/output)

On entry, if SIDE = 'R' or 'B' and HOWMNY = 'B', VR must contain an N-by-N matrix Q (usually the unitary matrix Z of right Schur vectors returned by CHGEQZ). On exit, if SIDE = 'R' or 'B', VR contains: if HOWMNY = 'A', the matrix X of right eigenvectors of (A,B); if HOWMNY = 'B', the matrix $Z*X$; if HOWMNY = 'S', the right eigenvectors of (A,B) specified by SELECT, stored consecutively in the columns of VR, in the same order as their eigenvalues. If SIDE = 'L', VR is not referenced.

LDVR (input)

The leading dimension of the array VR. $LDVR \geq \max(1,N)$ if SIDE = 'R' or 'B'; $LDVR \geq 1$ otherwise.

MM (input)

The number of columns in the arrays VL and/or VR.
MM \geq M.

M (output)

The number of columns in the arrays VL and/or VR actually used to store the eigenvectors. If HOWMNY = 'A' or 'B', M is set to N. Each selected eigenvector occupies one column.

WORK (workspace)

dimension(2*N)

RWORK (workspace)

dimension(2*N)

INFO (output)

= 0: successful exit.

< 0: if INFO = -i, the i-th argument had an illegal value.

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NAME

ztgexc - reorder the generalized Schur decomposition of a complex matrix pair (A,B), using an unitary equivalence transformation $(A, B) := Q * (A, B) * Z'$, so that the diagonal block of (A, B) with row index IFST is moved to row ILST

SYNOPSIS

```
SUBROUTINE ZTGEXC(WANTQ, WANTZ, N, A, LDA, B, LDB, Q, LDQ, Z, LDZ,
                 IFST, ILST, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
INTEGER N, LDA, LDB, LDQ, LDZ, IFST, ILST, INFO
LOGICAL WANTQ, WANTZ
```

```
SUBROUTINE ZTGEXC_64(WANTQ, WANTZ, N, A, LDA, B, LDB, Q, LDQ, Z, LDZ,
                    IFST, ILST, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), Q(LDQ,*), Z(LDZ,*)
INTEGER*8 N, LDA, LDB, LDQ, LDZ, IFST, ILST, INFO
LOGICAL*8 WANTQ, WANTZ
```

F95 INTERFACE

```
SUBROUTINE TGEXC(WANTQ, WANTZ, [N], A, [LDA], B, [LDB], Q, [LDQ], Z,
                [LDZ], IFST, ILST, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A, B, Q, Z
INTEGER :: N, LDA, LDB, LDQ, LDZ, IFST, ILST, INFO
LOGICAL :: WANTQ, WANTZ
```

```
SUBROUTINE TGEXC_64(WANTQ, WANTZ, [N], A, [LDA], B, [LDB], Q, [LDQ],
                   Z, [LDZ], IFST, ILST, [INFO])
```

```
COMPLEX(8), DIMENSION(:, :) :: A, B, Q, Z
INTEGER(8) :: N, LDA, LDB, LDQ, LDZ, IFST, ILST, INFO
LOGICAL(8) :: WANTQ, WANTZ
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztgexc(int wantq, int wantz, int n, doublecomplex *a,
           int lda, doublecomplex *b, int ldb, doublecomplex
           *q, int ldq, doublecomplex *z, int ldz, int *ifst,
           int *ilst, int *info);
```

```
void ztgexc_64(long wantq, long wantz, long n, doublecomplex
              *a, long lda, doublecomplex *b, long ldb, doublecomplex
              *q, long ldq, doublecomplex *z, long ldz, long *ifst, long
              *ilst, long *info);
```

PURPOSE

ztgexc reorders the generalized Schur decomposition of a complex matrix pair (A,B), using an unitary equivalence transformation $(A, B) := Q * (A, B) * Z'$, so that the diagonal block of (A, B) with row index IFST is moved to row ILST.

(A, B) must be in generalized Schur canonical form, that is, A and B are both upper triangular.

Optionally, the matrices Q and Z of generalized Schur vectors are updated.

$$Q(\text{in}) * A(\text{in}) * Z(\text{in})' = Q(\text{out}) * A(\text{out}) * Z(\text{out})'$$

$$Q(\text{in}) * B(\text{in}) * Z(\text{in})' = Q(\text{out}) * B(\text{out}) * Z(\text{out})'$$

ARGUMENTS

WANTQ (input)

WANTZ (input)

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the upper triangular matrix A in the pair (A, B). On exit, the updated matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the upper triangular matrix B in the pair (A, B). On exit, the updated matrix B.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

Q (input/output)

On entry, if WANTQ = .TRUE., the unitary matrix Q. On exit, the updated matrix Q. If WANTQ = .FALSE., Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. LDQ \geq 1; If
 WANTQ = .TRUE., LDQ \geq N.

Z (input/output)
 On entry, if WANTZ = .TRUE., the unitary matrix Z.
 On exit, the updated matrix Z. If WANTZ =
 .FALSE., Z is not referenced.

LDZ (input)
 The leading dimension of the array Z. LDZ \geq 1; If
 WANTZ = .TRUE., LDZ \geq N.

IFST (input/output)
 Specify the reordering of the diagonal blocks of
 (A, B). The block with row index IFST is moved to
 row ILST, by a sequence of swapping between adja-
 cent blocks.

ILST (input/output)
 See the description of IFST.

INFO (output)
 =0: Successful exit.
 <0: if INFO = -i, the i-th argument had an ille-
 gal value.
 =1: The transformed matrix pair (A, B) would be
 too far from generalized Schur form; the problem
 is ill- conditioned. (A, B) may have been par-
 tially reordered, and ILST points to the first row
 of the current position of the block being moved.

FURTHER DETAILS

Based on contributions by
 Bo Kagstrom and Peter Poromaa, Department of Computing
 Science,
 Umea University, S-901 87 Umea, Sweden.

[1] B. Kagstrom; A Direct Method for Reordering Eigenvalues
 in the
 Generalized Real Schur Form of a Regular Matrix Pair (A,
 B), in
 M.S. Moonen et al (eds), Linear Algebra for Large Scale
 and
 Real-Time Applications, Kluwer Academic Publ. 1993, pp
 195-218.

[2] B. Kagstrom and P. Poromaa; Computing Eigenspaces with
 Specified
 Eigenvalues of a Regular Matrix Pair (A, B) and Condi-
 tion
 Estimation: Theory, Algorithms and Software, Report
 UMINF - 94.04, Department of Computing Science, Umea
 University,
 S-901 87 Umea, Sweden, 1994. Also as LAPACK Working Note
 87.
 To appear in Numerical Algorithms, 1996.

[3] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK working Note 75. To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

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NAME

ztgsen - reorder the generalized Schur decomposition of a complex matrix pair (A, B) (in terms of an unitary equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the pair (A,B)

SYNOPSIS

```
SUBROUTINE ZTGSEN(IJOB, WANTQ, WANTZ, SELECT, N, A, LDA, B, LDB,
    ALPHA, BETA, Q, LDQ, Z, LDZ, M, PL, PR, DIF, WORK, LWORK, IWORK,
    LIWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK, INFO
INTEGER IWORK(*)
LOGICAL WANTQ, WANTZ
LOGICAL SELECT(*)
DOUBLE PRECISION PL, PR
DOUBLE PRECISION DIF(*)
```

```
SUBROUTINE ZTGSEN_64(IJOB, WANTQ, WANTZ, SELECT, N, A, LDA, B, LDB,
    ALPHA, BETA, Q, LDQ, Z, LDZ, M, PL, PR, DIF, WORK, LWORK, IWORK,
    LIWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), B(LDB,*), ALPHA(*), BETA(*),
Q(LDQ,*), Z(LDZ,*), WORK(*)
INTEGER*8 IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER*8 IWORK(*)
LOGICAL*8 WANTQ, WANTZ
LOGICAL*8 SELECT(*)
DOUBLE PRECISION PL, PR
DOUBLE PRECISION DIF(*)
```

F95 INTERFACE

```
SUBROUTINE TGSEN(IJOB, WANTQ, WANTZ, SELECT, N, A, [LDA], B, [LDB],
    ALPHA, BETA, Q, [LDQ], Z, [LDZ], M, PL, PR, DIF, [WORK], [LWORK],
```

```

        [IWORK], [LIWORK], [INFO])

COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, Q, Z
INTEGER :: IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER, DIMENSION(:) :: IWORK
LOGICAL :: WANTQ, WANTZ
LOGICAL, DIMENSION(:) :: SELECT
REAL(8) :: PL, PR
REAL(8), DIMENSION(:) :: DIF
SUBROUTINE TGSSEN_64(IJOB, WANTQ, WANTZ, SELECT, N, A, [LDA], B, [LDB],
    ALPHA, BETA, Q, [LDQ], Z, [LDZ], M, PL, PR, DIF, [WORK], [LWORK],
    [IWORK], [LIWORK], [INFO])

COMPLEX(8), DIMENSION(:) :: ALPHA, BETA, WORK
COMPLEX(8), DIMENSION(:, :) :: A, B, Q, Z
INTEGER(8) :: IJOB, N, LDA, LDB, LDQ, LDZ, M, LWORK, LIWORK,
INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8) :: WANTQ, WANTZ
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8) :: PL, PR
REAL(8), DIMENSION(:) :: DIF

```

C INTERFACE

```

#include <sunperf.h>

void ztgsen(int ijob, int wantq, int wantz, int *select, int
    n, doublecomplex *a, int lda, doublecomplex *b,
    int ldb, doublecomplex *alpha, doublecomplex
    *beta, doublecomplex *q, int ldq, doublecomplex
    *z, int ldz, int *m, double *pl, double *pr, dou-
    ble *dif, int *info);

void ztgsen_64(long ijob, long wantq, long wantz, long
    *select, long n, doublecomplex *a, long lda, doub-
    lecomplex *b, long ldb, doublecomplex *alpha,
    doublecomplex *beta, doublecomplex *q, long ldq,
    doublecomplex *z, long ldz, long *m, double *pl,
    double *pr, double *dif, long *info);

```

PURPOSE

ztgsen reorders the generalized Schur decomposition of a complex matrix pair (A, B) (in terms of an unitary equivalence transformation $Q' * (A, B) * Z$), so that a selected cluster of eigenvalues appears in the leading diagonal blocks of the pair (A,B). The leading columns of Q and Z form unitary bases of the corresponding left and right eigenspaces (deflating subspaces). (A, B) must be in generalized Schur canonical form, that is, A and B are both upper triangular.

ZTGSSEN also computes the generalized eigenvalues

$$w(j) = \text{ALPHA}(j) / \text{BETA}(j)$$

of the reordered matrix pair (A, B).

Optionally, the routine computes estimates of reciprocal condition numbers for eigenvalues and eigenspaces. These are $Difu[(A_{11}, B_{11}), (A_{22}, B_{22})]$ and $Difl[(A_{11}, B_{11}), (A_{22}, B_{22})]$, i.e. the separation(s) between the matrix pairs (A_{11}, B_{11}) and (A_{22}, B_{22}) that correspond to the selected cluster and the eigenvalues outside the cluster, resp., and norms of "projections" onto left and right eigenspaces w.r.t. the selected cluster in the (1,1)-block.

ARGUMENTS

IJOB (input)

Specifies whether condition numbers are required for the cluster of eigenvalues (PL and PR) or the deflating subspaces (Difu and Difl):
=0: Only reorder w.r.t. SELECT. No extras.
=1: Reciprocal of norms of "projections" onto left and right eigenspaces w.r.t. the selected cluster (PL and PR). =2: Upper bounds on Difu and Difl. F-norm-based estimate (DIF(1:2)).
=3: Estimate of Difu and Difl. 1-norm-based estimate (DIF(1:2)). About 5 times as expensive as IJOB = 2.
=4: Compute PL, PR and DIF (i.e. 0, 1 and 2 above): Economic version to get it all. =5: Compute PL, PR and DIF (i.e. 0, 1 and 3 above)

WANTQ (input)

WANTZ (input)

SELECT (input)

SELECT specifies the eigenvalues in the selected cluster. To select an eigenvalue $w(j)$, SELECT(j) must be set to

N (input) The order of the matrices A and B. $N \geq 0$.

A (input/output)

On entry, the upper triangular matrix A, in generalized Schur canonical form. On exit, A is overwritten by the reordered matrix A.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the upper triangular matrix B, in generalized Schur canonical form. On exit, B is overwritten by the reordered matrix B.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1, N)$.

ALPHA (output)

The diagonal elements of A and B, respectively, when the pair (A,B) has been reduced to generalized Schur form. ALPHA(i)/BETA(i) i=1,...,N are the generalized eigenvalues.

BETA (output)

See the description of ALPHA.

Q (input/output)

On entry, if WANTQ = .TRUE., Q is an N-by-N matrix. On exit, Q has been postmultiplied by the left unitary transformation matrix which reorder (A, B); The leading M columns of Q form orthonormal bases for the specified pair of left eigenspaces (deflating subspaces). If WANTQ = .FALSE., Q is not referenced.

LDQ (input)

The leading dimension of the array Q. LDQ >= 1. If WANTQ = .TRUE., LDQ >= N.

Z (input/output)

On entry, if WANTZ = .TRUE., Z is an N-by-N matrix. On exit, Z has been postmultiplied by the left unitary transformation matrix which reorder (A, B); The leading M columns of Z form orthonormal bases for the specified pair of left eigenspaces (deflating subspaces). If WANTZ = .FALSE., Z is not referenced.

LDZ (input)

The leading dimension of the array Z. LDZ >= 1. If WANTZ = .TRUE., LDZ >= N.

M (output)

The dimension of the specified pair of left and right eigenspaces, (deflating subspaces) 0 <= M <= N.

PL (output)

IF IJOB = 1, 4, or 5, PL, PR are lower bounds on the reciprocal of the norm of "projections" onto left and right eigenspace with respect to the selected cluster.

0 < PL, PR <= 1. If M = 0 or M = N, PL = PR = 1. If IJOB = 0, 2, or 3 PL, PR are not referenced.

PR (output)

See the description of PL.

DIF (output)

If IJOB >= 2, DIF(1:2) store the estimates of Dif_u and Dif_l.

If IJOB = 2 or 4, DIF(1:2) are F-norm-based upper bounds on

Dif_u and Dif_l. If IJOB = 3 or 5, DIF(1:2) are 1-norm-based estimates of Dif_u and Dif_l, computed using reversed communication with CLACON. If M = 0 or N, DIF(1:2) = F-norm([A, B]). If IJOB = 0 or 1, DIF is not referenced.

WORK (workspace)
If IJOB = 0, WORK is not referenced. Otherwise,
on exit, if INFO = 0, WORK(1) returns the optimal
LWORK.

LWORK (input)
The dimension of the array WORK. LWORK \geq 1. If
IJOB = 1, 2 or 4, LWORK \geq 2*M*(N-M). If IJOB = 3
or 5, LWORK \geq 4*M*(N-M).

If LWORK = -1, then a workspace query is assumed;
the routine only calculates the optimal size of
the WORK array, returns this value as the first
entry of the WORK array, and no error message
related to LWORK is issued by XERBLA.

IWORK (workspace/output)
If IJOB = 0, IWORK is not referenced. Otherwise,
on exit, if INFO = 0, IWORK(1) returns the optimal
LIWORK.

LIWORK (input)
The dimension of the array IWORK. LIWORK \geq 1. If
IJOB = 1, 2 or 4, LIWORK \geq N+2; If IJOB = 3 or
5, LIWORK \geq MAX(N+2, 2*M*(N-M));

If LIWORK = -1, then a workspace query is assumed;
the routine only calculates the optimal size of
the IWORK array, returns this value as the first
entry of the IWORK array, and no error message
related to LIWORK is issued by XERBLA.

INFO (output)
=0: Successful exit.
<0: If INFO = -i, the i-th argument had an illegal
value.
=1: Reordering of (A, B) failed because the
transformed matrix pair (A, B) would be too far
from generalized Schur form; the problem is very
ill-conditioned. (A, B) may have been partially
reordered. If requested, 0 is returned in DIF(*),
PL and PR.

FURTHER DETAILS

ZTGSEN first collects the selected eigenvalues by computing
unitary U and W that move them to the top left corner of (A,
B). In other words, the selected eigenvalues are the eigen-
values of (A11, B11) in

$$U'(A, B)W = \begin{pmatrix} (A11 & A12) & (B11 & B12) & n1 \\ (0 & A22) & (0 & B22) & n2 \\ n1 & n2 & n1 & n2 \end{pmatrix}$$

where $N = n1+n2$ and U' means the conjugate transpose of U.
The first $n1$ columns of U and W span the specified pair of
left and right eigenspaces (deflating subspaces) of (A, B).

If (A, B) has been obtained from the generalized real Schur
decomposition of a matrix pair $(C, D) = Q*(A, B)*Z'$, then
the reordered generalized Schur form of (C, D) is given by

$$(C, D) = (Q*U)*(U'*(A, B)*W)*(Z*W)',$$

and the first n1 columns of Q*U and Z*W span the corresponding deflating subspaces of (C, D) (Q and Z store Q*U and Z*W, resp.).

Note that if the selected eigenvalue is sufficiently ill-conditioned, then its value may differ significantly from its value before reordering.

The reciprocal condition numbers of the left and right eigenspaces spanned by the first n1 columns of U and W (or Q*U and Z*W) may be returned in DIF(1:2), corresponding to Difu and Difl, resp.

The Difu and Difl are defined as:

$$\text{ifu}[(A11, B11), (A22, B22)] = \text{sigma-min}(Zu)$$

and

where sigma-min(Zu) is the smallest singular value of the (2*n1*n2)-by-(2*n1*n2) matrix

$$u = \begin{bmatrix} \text{kron}(In2, A11) & -\text{kron}(A22', In1) \\ \text{kron}(In2, B11) & -\text{kron}(B22', In1) \end{bmatrix}.$$

Here, Inx is the identity matrix of size nx and A22' is the transpose of A22. kron(X, Y) is the Kronecker product between the matrices X and Y.

When DIF(2) is small, small changes in (A, B) can cause large changes in the deflating subspace. An approximate (asymptotic) bound on the maximum angular error in the computed deflating subspaces is $PS * \text{norm}((A, B)) / \text{DIF}(2)$,

where EPS is the machine precision.

The reciprocal norm of the projectors on the left and right eigenspaces associated with (A11, B11) may be returned in PL and PR. They are computed as follows. First we compute L and R so that P*(A, B)*Q is block diagonal, where

$$= \begin{pmatrix} I & -L \\ 0 & I \end{pmatrix} \begin{matrix} n1 \\ n2 \end{matrix} \quad \text{and} \quad \begin{matrix} Q = \begin{pmatrix} I & R \\ 0 & I \end{pmatrix} \begin{matrix} n1 \\ n2 \end{matrix} \\ n1 & n2 \end{matrix}$$

and (L, R) is the solution to the generalized Sylvester equation $l1*R - L*A22 = -A12$

Then $PL = (F\text{-norm}(L)**2+1)**(-1/2)$ and $PR = (F\text{-norm}(R)**2+1)**(-1/2)$. An approximate (asymptotic) bound on the average absolute error of the selected eigenvalues is $EPS * \text{norm}((A, B)) / PL$.

There are also global error bounds which valid for perturbations up to a certain restriction: A lower bound (x) on the smallest F-norm(E,F) for which an eigenvalue of (A11, B11) may move and coalesce with an eigenvalue of (A22, B22) under perturbation (E,F), (i.e. (A + E, B + F), is

$$x = \min(\text{Difu}, \text{Difl}) / ((1/(PL*PL) + 1/(PR*PR))**(1/2) + 2*\max(1/PL, 1/PR)).$$

An approximate bound on x can be computed from DIF(1:2), PL

and PR.

If $y = (F\text{-norm}(E,F) / x) \leq 1$, the angles between the perturbed (L', R') and unperturbed (L, R) left and right deflating subspaces associated with the selected cluster in the $(1,1)$ -blocks can be bounded as

```
max-angle(L, L') <= arctan( y * PL / (1 - y * (1 - PL *
PL)**(1/2))
max-angle(R, R') <= arctan( y * PR / (1 - y * (1 - PR *
PR)**(1/2))
```

See LAPACK User's Guide section 4.11 or the following references for more information.

Note that if the default method for computing the Frobenius-norm-based estimate DIF is not wanted (see CLATDF), then the parameter IDIFJB (see below) should be changed from 3 to 4 (routine CLATDF (IJOB = 2 will be used)). See ZTGSYL for more details.

Based on contributions by

Bo Kagstrom and Peter Poromaa, Department of Computing Science,
Umea University, S-901 87 Umea, Sweden.

References

=====

[1] B. Kagstrom; A Direct Method for Reordering Eigenvalues in the Generalized Real Schur Form of a Regular Matrix Pair (A, B) , in M.S. Moonen et al (eds), Linear Algebra for Large Scale and Real-Time Applications, Kluwer Academic Publ. 1993, pp 195-218.

[2] B. Kagstrom and P. Poromaa; Computing Eigenspaces with Specified Eigenvalues of a Regular Matrix Pair (A, B) and Condition Estimation: Theory, Algorithms and Software, Report UMINF - 94.04, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, 1994. Also as LAPACK Working Note 87.

To appear in Numerical Algorithms, 1996.

[3] B. Kagstrom and P. Poromaa, LAPACK-Style Algorithms and Software for Solving the Generalized Sylvester Equation and Estimating the Separation between Regular Matrix Pairs, Report UMINF - 93.23, Department of Computing Science, Umea University, S-901 87 Umea, Sweden, December 1993, Revised April 1994, Also as LAPACK working Note 75. To appear in ACM Trans. on Math. Software, Vol 22, No 1, 1996.

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NAME

ztgsja - compute the generalized singular value decomposition (GSVD) of two complex upper triangular (or trapezoidal) matrices A and B

SYNOPSIS

```
SUBROUTINE ZTGSJA(JOBU, JOBV, JOBQ, M, P, N, K, L, A, LDA, B, LDB,
  TOLA, TOLB, ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, NCYCLE,
  INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
DOUBLE COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*),
Q(LDQ,*), WORK(*)
INTEGER M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE, INFO
DOUBLE PRECISION TOLA, TOLB
DOUBLE PRECISION ALPHA(*), BETA(*)
```

```
SUBROUTINE ZTGSJA_64(JOBU, JOBV, JOBQ, M, P, N, K, L, A, LDA, B, LDB,
  TOLA, TOLB, ALPHA, BETA, U, LDU, V, LDV, Q, LDQ, WORK, NCYCLE,
  INFO)
```

```
CHARACTER * 1 JOBU, JOBV, JOBQ
DOUBLE COMPLEX A(LDA,*), B(LDB,*), U(LDU,*), V(LDV,*),
Q(LDQ,*), WORK(*)
INTEGER*8 M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE,
INFO
DOUBLE PRECISION TOLA, TOLB
DOUBLE PRECISION ALPHA(*), BETA(*)
```

F95 INTERFACE

```
SUBROUTINE TGSJA(JOBU, JOBV, JOBQ, [M], [P], [N], K, L, A, [LDA], B,
  [LDB], TOLA, TOLB, ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ],
  [WORK], NCYCLE, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, U, V, Q
INTEGER :: M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCYCLE,
INFO
REAL(8) :: TOLA, TOLB
```

```
REAL(8), DIMENSION(:) :: ALPHA, BETA
```

```
SUBROUTINE TGSJA_64(JOBV, JOBV, JOBQ, [M], [P], [N], K, L, A, [LDA],  
    B, [LDB], TOLA, TOLB, ALPHA, BETA, U, [LDU], V, [LDV], Q, [LDQ],  
    [WORK], NCYCLE, [INFO])
```

```
CHARACTER(LEN=1) :: JOBU, JOBV, JOBQ  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B, U, V, Q  
INTEGER(8) :: M, P, N, K, L, LDA, LDB, LDU, LDV, LDQ, NCY-  
CLE, INFO  
REAL(8) :: TOLA, TOLB  
REAL(8), DIMENSION(:) :: ALPHA, BETA
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztgsja(char jobv, char jobq, int m, int p,  
    int n, int k, int l, doublecomplex *a, int lda,  
    doublecomplex *b, int ldb, double tola, double  
    tolb, double *alpha, double *beta, doublecomplex  
    *u, int ldu, doublecomplex *v, int ldv, doublecom-  
    plex *q, int ldq, int *ncycle, int *info);
```

```
void ztgsja_64(char jobv, char jobq, long m, long  
    p, long n, long k, long l, doublecomplex *a, long  
    lda, doublecomplex *b, long ldb, double tola, dou-  
    ble tolb, double *alpha, double *beta, doublecom-  
    plex *u, long ldu, doublecomplex *v, long ldv,  
    doublecomplex *q, long ldq, long *ncycle, long  
    *info);
```

PURPOSE

ztgsja computes the generalized singular value decomposition (GSVD) of two complex upper triangular (or trapezoidal) matrices A and B.

On entry, it is assumed that matrices A and B have the following forms, which may be obtained by the preprocessing subroutine CGGSVP from a general M-by-N matrix A and P-by-N matrix B:

$$A = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} \\ \begin{matrix} K \\ L \\ M-K-L \end{matrix} & \begin{pmatrix} 0 & A12 & A13 \\ 0 & 0 & A23 \\ 0 & 0 & 0 \end{pmatrix} \end{array} \text{ if } M-K-L \geq 0;$$
$$A = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} \\ \begin{matrix} K \\ M-K \end{matrix} & \begin{pmatrix} 0 & A12 & A13 \\ 0 & 0 & A23 \end{pmatrix} \end{array} \text{ if } M-K-L < 0;$$
$$B = \begin{array}{ccc} & \begin{matrix} N-K-L & K & L \end{matrix} \\ \begin{matrix} L \\ P-L \end{matrix} & \begin{pmatrix} 0 & 0 & B13 \\ 0 & 0 & 0 \end{pmatrix} \end{array}$$

where the K-by-K matrix A12 and L-by-L matrix B13 are non-singular upper triangular; A23 is L-by-L upper triangular if

M-K-L >= 0, otherwise A23 is (M-K)-by-L upper trapezoidal.
 On exit,

$$U^*A*Q = D1*(0 R), \quad V^*B*Q = D2*(0 R),$$

where U, V and Q are unitary matrices, Z' denotes the conjugate transpose of Z, R is a nonsingular upper triangular matrix, and D1 and D2 are ``diagonal'' matrices, which are of the following structures:

If M-K-L >= 0,

$$D1 = \begin{matrix} & & K & L \\ & K & (I & 0) \\ & & L & (0 & C) \\ M-K-L & (0 & 0) \end{matrix}$$

$$D2 = \begin{matrix} & & K & L \\ L & (0 & S) \\ P-L & (0 & 0) \end{matrix}$$

$$(0 R) = \begin{matrix} & & N-K-L & K & L \\ K & (0 & R11 & R12) & K \\ L & (0 & 0 & R22) & L \end{matrix}$$

where

$$C = \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(K+L)),$$

$$S = \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(K+L)),$$

$$C^{**2} + S^{**2} = I.$$

R is stored in A(1:K+L,N-K-L+1:N) on exit.

If M-K-L < 0,

$$D1 = \begin{matrix} & & K & M-K & K+L-M \\ & K & (I & 0 & 0) \\ M-K & (0 & C & 0) \end{matrix}$$

$$D2 = \begin{matrix} & & K & M-K & K+L-M \\ M-K & (0 & S & 0) \\ K+L-M & (0 & 0 & I) \\ P-L & (0 & 0 & 0) \end{matrix}$$

$$\begin{matrix} & & N-K-L & K & M-K & K+L-M \\ M-K & (0 & 0 & R22 & R23) \\ K+L-M & (0 & 0 & 0 & R33) \end{matrix}$$

where

$$C = \text{diag}(\text{ALPHA}(K+1), \dots, \text{ALPHA}(M)),$$

$$S = \text{diag}(\text{BETA}(K+1), \dots, \text{BETA}(M)),$$

$$C^{**2} + S^{**2} = I.$$

R = (R11 R12 R13) is stored in A(1:M, N-K-L+1:N) and R33 is stored

$$(0 R22 R23)$$

in B(M-K+1:L,N+M-K-L+1:N) on exit.

The computation of the unitary transformation matrices U, V or Q is optional. These matrices may either be formed explicitly, or they may be postmultiplied into input

matrices U1, V1, or Q1.

ZTGSJA essentially uses a variant of Kogbetliantz algorithm to reduce min(L,M-K)-by-L triangular (or trapezoidal) matrix A23 and L-by-L matrix B13 to the form:

$$U1'*A13*Q1 = C1*R1; V1'*B13*Q1 = S1*R1,$$

where U1, V1 and Q1 are unitary matrix, and Z' is the conjugate transpose of Z. C1 and S1 are diagonal matrices satisfying

$$C1**2 + S1**2 = I,$$

and R1 is an L-by-L nonsingular upper triangular matrix.

ARGUMENTS

JOBU (input)

= 'U': U must contain a unitary matrix U1 on entry, and the product U1*U is returned; = 'I': U is initialized to the unit matrix, and the unitary matrix U is returned; = 'N': U is not computed.

JOBV (input)

= 'V': V must contain a unitary matrix V1 on entry, and the product V1*V is returned; = 'I': V is initialized to the unit matrix, and the unitary matrix V is returned; = 'N': V is not computed.

JOBQ (input)

= 'Q': Q must contain a unitary matrix Q1 on entry, and the product Q1*Q is returned; = 'I': Q is initialized to the unit matrix, and the unitary matrix Q is returned; = 'N': Q is not computed.

M (input) The number of rows of the matrix A. M >= 0.

P (input) The number of rows of the matrix B. P >= 0.

N (input) The number of columns of the matrices A and B. N >= 0.

K (input) K and L specify the subblocks in the input matrices A and B:

A23 = A(K+1:MIN(K+L,M),N-L+1:N) and B13 = B(1:L, N-L+1:N) of A and B, whose GSVD is going to be computed by ZTGSJA. See the Further Details section below.

L (input) See the description of K.

A (input/output)

On entry, the M-by-N matrix A. On exit, A(N-K+1:N,1:MIN(K+L,M)) contains the triangular matrix R or part of R. See Purpose for details.

LDA (input)

The leading dimension of the array A. LDA >= max(1,M).

B (input/output)

On entry, the P-by-N matrix B. On exit, if necessary, B(M-K+1:L,N+M-K-L+1:N) contains a part of R.

See Purpose for details.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,P)$.

TOLA (input)

TOLA and TOLB are the convergence criteria for the Jacobi-Kogbetliantz iteration procedure. Generally, they are the same as used in the preprocessing step, say $TOLA = \max(M,N) \cdot \text{norm}(A) \cdot \text{MACHEPS}$, $TOLB = \max(P,N) \cdot \text{norm}(B) \cdot \text{MACHEPS}$.

TOLB (input)

See the description of TOLA.

ALPHA (output)

On exit, ALPHA and BETA contain the generalized singular value pairs of A and B; $ALPHA(1:K) = 1$, $BETA(1:K) = 0$, and if $M-K-L \geq 0$, $ALPHA(K+1:K+L) = \text{diag}(C)$, $BETA(K+1:K+L) = \text{diag}(S)$, or if $M-K-L < 0$, $ALPHA(K+1:M) = C$, $ALPHA(M+1:K+L) = 0$, $BETA(K+1:M) = S$, $BETA(M+1:K+L) = 1$. Furthermore, if $K+L < N$, $ALPHA(K+L+1:N) = 0$, $BETA(K+L+1:N) = 0$.

BETA (output)

See the description of ALPHA.

U (input) On entry, if $JOB_U = 'U'$, U must contain a matrix U_1 (usually the unitary matrix returned by CGGSVP). On exit, if $JOB_U = 'I'$, U contains the unitary matrix U; if $JOB_U = 'U'$, U contains the product $U_1 \cdot U$. If $JOB_U = 'N'$, U is not referenced.

LDU (input)

The leading dimension of the array U. $LDU \geq \max(1,M)$ if $JOB_U = 'U'$; $LDU \geq 1$ otherwise.

V (input) On entry, if $JOB_V = 'V'$, V must contain a matrix V_1 (usually the unitary matrix returned by CGGSVP). On exit, if $JOB_V = 'I'$, V contains the unitary matrix V; if $JOB_V = 'V'$, V contains the product $V_1 \cdot V$. If $JOB_V = 'N'$, V is not referenced.

LDV (input)

The leading dimension of the array V. $LDV \geq \max(1,P)$ if $JOB_V = 'V'$; $LDV \geq 1$ otherwise.

Q (input) On entry, if $JOB_Q = 'Q'$, Q must contain a matrix Q_1 (usually the unitary matrix returned by CGGSVP). On exit, if $JOB_Q = 'I'$, Q contains the unitary matrix Q; if $JOB_Q = 'Q'$, Q contains the product $Q_1 \cdot Q$. If $JOB_Q = 'N'$, Q is not referenced.

LDQ (input)

The leading dimension of the array Q. $LDQ \geq \max(1,N)$ if $JOB_Q = 'Q'$; $LDQ \geq 1$ otherwise.

WORK (workspace)

dimension(2*N)

NCYCLE (output)

The number of cycles required for convergence.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value.

= 1: the procedure does not converge after MAXIT cycles.

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NAME

ztgsna - estimate reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B)

SYNOPSIS

```
SUBROUTINE ZTGSNA(JOB, HOWMNT, SELECT, N, A, LDA, B, LDB, VL, LDVL,  
                 VR, LDVR, S, DIF, MM, M, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOB, HOWMNT  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*),  
WORK(*)  
INTEGER N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO  
INTEGER IWORK(*)  
LOGICAL SELECT(*)  
DOUBLE PRECISION S(*), DIF(*)
```

```
SUBROUTINE ZTGSNA_64(JOB, HOWMNT, SELECT, N, A, LDA, B, LDB, VL,  
                   LDVL, VR, LDVR, S, DIF, MM, M, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 JOB, HOWMNT  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), VL(LDVL,*), VR(LDVR,*),  
WORK(*)  
INTEGER*8 N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO  
INTEGER*8 IWORK(*)  
LOGICAL*8 SELECT(*)  
DOUBLE PRECISION S(*), DIF(*)
```

F95 INTERFACE

```
SUBROUTINE TGSNA(JOB, HOWMNT, SELECT, [N], A, [LDA], B, [LDB], VL,  
                [LDVL], VR, [LDVR], S, DIF, MM, M, [WORK], [LWORK], [IWORK],  
                [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNT  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:,:) :: A, B, VL, VR  
INTEGER :: N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO  
INTEGER, DIMENSION(:) :: IWORK  
LOGICAL, DIMENSION(:) :: SELECT
```

```

REAL(8), DIMENSION(:) :: S, DIF

SUBROUTINE TGSNA_64(JOB, HOWMNT, SELECT, [N], A, [LDA], B, [LDB], VL,
    [LDVL], VR, [LDVR], S, DIF, MM, M, [WORK], [LWORK], [IWORK],
    [INFO])

CHARACTER(LEN=1) :: JOB, HOWMNT
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, VL, VR
INTEGER(8) :: N, LDA, LDB, LDVL, LDVR, MM, M, LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: S, DIF

```

C INTERFACE

```

#include <sunperf.h>

void ztgsna(char job, char howmnt, int *select, int n, doublecomplex
    *a, int lda, doublecomplex *b, int ldb, doublecomplex *vl, int ldvl,
    doublecomplex *vr, int ldvr, double *s, double *dif, int mm, int *m,
    int *info);

void ztgsna_64(char job, char howmnt, long *select, long n,
    doublecomplex *a, long lda, doublecomplex *b, long ldb, doublecomplex
    *vl, long ldvl, doublecomplex *vr, long ldvr, double *s, double *dif,
    long mm, long *m, long *info);

```

PURPOSE

ztgsna estimates reciprocal condition numbers for specified eigenvalues and/or eigenvectors of a matrix pair (A, B).

(A, B) must be in generalized Schur canonical form, that is, A and B are both upper triangular.

ARGUMENTS

JOB (input)
 Specifies whether condition numbers are required for eigenvalues (S) or eigenvectors (DIF):
 = 'E': for eigenvalues only (S);
 = 'V': for eigenvectors only (DIF);
 = 'B': for both eigenvalues and eigenvectors (S and DIF).

HOWMNT (input)
 = 'A': compute condition numbers for all eigenpairs;
 = 'S': compute condition numbers for selected eigenpairs specified by the array SELECT.

SELECT (input)
 If HOWMNT = 'S', SELECT specifies the eigenpairs for which condition numbers are required. To

select condition numbers for the corresponding j -th eigenvalue and/or eigenvector, `SELECT(j)` must be set to `.TRUE.`. If `HOWMNT = 'A'`, `SELECT` is not referenced.

`N` (input) The order of the square matrix pair (A, B). $N \geq 0$.

`A` (input) The upper triangular matrix A in the pair (A,B).

`LDA` (input)
The leading dimension of the array A. $LDA \geq \max(1,N)$.

`B` (input) The upper triangular matrix B in the pair (A, B).

`LDB` (input)
The leading dimension of the array B. $LDB \geq \max(1,N)$.

`VL` (input)
If `JOB = 'E'` or `'B'`, `VL` must contain left eigenvectors of (A, B), corresponding to the eigenpairs specified by `HOWMNT` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VL`, as returned by `ZTGEVC`. If `JOB = 'V'`, `VL` is not referenced.

`LDVL` (input)
The leading dimension of the array `VL`. $LDVL \geq 1$; and if `JOB = 'E'` or `'B'`, $LDVL \geq N$.

`VR` (input)
If `JOB = 'E'` or `'B'`, `VR` must contain right eigenvectors of (A, B), corresponding to the eigenpairs specified by `HOWMNT` and `SELECT`. The eigenvectors must be stored in consecutive columns of `VR`, as returned by `ZTGEVC`. If `JOB = 'V'`, `VR` is not referenced.

`LDVR` (input)
The leading dimension of the array `VR`. $LDVR \geq 1$; If `JOB = 'E'` or `'B'`, $LDVR \geq N$.

`S` (output)
If `JOB = 'E'` or `'B'`, the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. If `JOB = 'V'`, `S` is not referenced.

`DIF` (output)
If `JOB = 'V'` or `'B'`, the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. If the eigenvalues cannot be reordered to compute `DIF(j)`, `DIF(j)` is set to 0; this can only occur when the true value would be very small anyway. For each eigenvalue/vector specified by `SELECT`, `DIF` stores a Frobenius norm-based estimate of `Difl`. If `JOB = 'E'`, `DIF` is not referenced.

`MM` (input)

$$\text{Difl}[(a, b), (A22, B22)] = \text{sigma-min}(Z1)$$

where $\text{sigma-min}(Z1)$ denotes the smallest singular value of

$$Z1 = \begin{bmatrix} \text{kron}(a, I_{n-1}) & -\text{kron}(1, A22) \\ \text{kron}(b, I_{n-1}) & -\text{kron}(1, B22) \end{bmatrix}.$$

Here I_{n-1} is the identity matrix of size $n-1$ and X' is the conjugate transpose of X . $\text{kron}(X, Y)$ is the Kronecker product between the matrices X and Y .

We approximate the smallest singular value of $Z1$ with an upper bound. This is done by ZLATDF.

An approximate error bound for a computed eigenvector $VL(i)$ or $VR(i)$ is given by

$$\text{EPS} * \text{norm}(A, B) / \text{DIF}(i).$$

See ref. [2-3] for more details and further references.

Based on contributions by

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References

=====

[1] B. Kagstrom; A Direct Method for Reordering Eigenvalues in the Generalized Real Schur Form of a Regular Matrix Pair (A, B) , in M.S. Moonen et al (eds), Linear Algebra for Large Scale and Real-Time Applications, Kluwer Academic Publ. 1993, pp 195-218.

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NAME

ztgsyl - solve the generalized Sylvester equation

SYNOPSIS

```
SUBROUTINE ZTGSYL(TRANS, IJOB, M, N, A, LDA, B, LDB, C, LDC, D, LDD,
  E, LDE, F, LDF, SCALE, DIF, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 TRANS
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*), D(LDD,*),
E(LDE,*), F(LDF,*), WORK(*)
INTEGER IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,
INFO
INTEGER IWORK(*)
DOUBLE PRECISION SCALE, DIF
```

```
SUBROUTINE ZTGSYL_64(TRANS, IJOB, M, N, A, LDA, B, LDB, C, LDC, D,
  LDD, E, LDE, F, LDF, SCALE, DIF, WORK, LWORK, IWORK, INFO)
```

```
CHARACTER * 1 TRANS
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*), D(LDD,*),
E(LDE,*), F(LDF,*), WORK(*)
INTEGER*8 IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,
INFO
INTEGER*8 IWORK(*)
DOUBLE PRECISION SCALE, DIF
```

F95 INTERFACE

```
SUBROUTINE TGSYL(TRANS, IJOB, [M], [N], A, [LDA], B, [LDB], C, [LDC],
  D, [LDD], E, [LDE], F, [LDF], SCALE, DIF, [WORK], [LWORK], [IWORK],
  [INFO])
```

```
CHARACTER(LEN=1) :: TRANS
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, C, D, E, F
INTEGER :: IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF, LWORK,
INFO
INTEGER, DIMENSION(:) :: IWORK
REAL(8) :: SCALE, DIF
```

```

SUBROUTINE TGSYL_64(TRANS, IJOB, [M], [N], A, [LDA], B, [LDB], C,
  [LDC], D, [LDD], E, [LDE], F, [LDF], SCALE, DIF, [WORK], [LWORK],
  [IWORK], [INFO])

```

```

CHARACTER(LEN=1) :: TRANS
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: A, B, C, D, E, F
INTEGER(8) :: IJOB, M, N, LDA, LDB, LDC, LDD, LDE, LDF,
LWORK, INFO
INTEGER(8), DIMENSION(:) :: IWORK
REAL(8) :: SCALE, DIF

```

C INTERFACE

```
#include <sunperf.h>
```

```

void ztgsyl(char trans, int ijob, int m, int n, doublecom-
  plex *a, int lda, doublecomplex *b, int ldb, doub-
  lecomplex *c, int ldc, doublecomplex *d, int ldd,
  doublecomplex *e, int lde, doublecomplex *f, int
  ldf, double *scale, double *dif, int *info);

```

```

void ztgsyl_64(char trans, long ijob, long m, long n, doub-
  lecomplex *a, long lda, doublecomplex *b, long
  ldb, doublecomplex *c, long ldc, doublecomplex *d,
  long ldd, doublecomplex *e, long lde, doublecom-
  plex *f, long ldf, double *scale, double *dif,
  long *info);

```

PURPOSE

ztgsyl solves the generalized Sylvester equation:

$$\begin{aligned}
 A * R - L * B &= \text{scale} * C & (1) \\
 D * R - L * E &= \text{scale} * F
 \end{aligned}$$

where R and L are unknown m-by-n matrices, (A, D), (B, E) and (C, F) are given matrix pairs of size m-by-m, n-by-n and m-by-n, respectively, with complex entries. A, B, D and E are upper triangular (i.e., (A,D) and (B,E) in generalized Schur form).

The solution (R, L) overwrites (C, F). 0 <= SCALE <= 1 is an output scaling factor chosen to avoid overflow.

In matrix notation (1) is equivalent to solve $Zx = \text{scale} * b$, where Z is defined as

$$Z = \begin{bmatrix} \text{kron}(I_n, A) & -\text{kron}(B', I_m) \\ \text{kron}(I_n, D) & -\text{kron}(E', I_m) \end{bmatrix}, \quad (2)$$

Here I_x is the identity matrix of size x and X' is the conjugate transpose of X. $\text{Kron}(X, Y)$ is the Kronecker product between the matrices X and Y.

If TRANS = 'C', y in the conjugate transposed system $Z' * y = \text{scale} * b$ is solved for, which is equivalent to solve for R and L in

$$A' * R + D' * L = \text{scale} * C \quad (3)$$

$$R * B' + L * E' = \text{scale} * -F$$

This case (TRANS = 'C') is used to compute an one-norm-based estimate of $\text{Dif}[(A,D), (B,E)]$, the separation between the matrix pairs (A,D) and (B,E), using CLACON.

If IJOB \geq 1, ZTGSYL computes a Frobenius norm-based estimate of $\text{Dif}[(A,D), (B,E)]$. That is, the reciprocal of a lower bound on the reciprocal of the smallest singular value of Z.

This is a level-3 BLAS algorithm.

ARGUMENTS

TRANS (input)

= 'N': solve the generalized sylvester equation (1).
 = 'C': solve the "conjugate transposed" system (3).

IJOB (input)

Specifies what kind of functionality to be performed. =0: solve (1) only.
 =1: The functionality of 0 and 3.
 =2: The functionality of 0 and 4.
 =3: Only an estimate of $\text{Dif}[(A,D), (B,E)]$ is computed. (look ahead strategy is used). =4: Only an estimate of $\text{Dif}[(A,D), (B,E)]$ is computed. (CGECON on sub-systems is used). Not referenced if TRANS = 'C'.

M (input) The order of the matrices A and D, and the row dimension of the matrices C, F, R and L.

N (input) The order of the matrices B and E, and the column dimension of the matrices C, F, R and L.

A (input) The upper triangular matrix A.

LDA (input)

The leading dimension of the array A. LDA \geq max(1, M).

B (input) The upper triangular matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1, N).

C (input/output)

On entry, C contains the right-hand-side of the first matrix equation in (1) or (3). On exit, if IJOB = 0, 1 or 2, C has been overwritten by the solution R. If IJOB = 3 or 4 and TRANS = 'N', C holds R, the solution achieved during the computation of the Dif-estimate.

LDC (input)

The leading dimension of the array C. LDC \geq

max(1, M).

D (input) The upper triangular matrix D.

LDD (input)

The leading dimension of the array D. LDD \geq max(1, M).

E (input) The upper triangular matrix E.

LDE (input)

The leading dimension of the array E. LDE \geq max(1, N).

F (input/output)

On entry, F contains the right-hand-side of the second matrix equation in (1) or (3). On exit, if IJOB = 0, 1 or 2, F has been overwritten by the solution L. If IJOB = 3 or 4 and TRANS = 'N', F holds L, the solution achieved during the computation of the Dif-estimate.

LDL (input)

The leading dimension of the array F. LDL \geq max(1, M).

SCALE (output)

On exit SCALE is the reciprocal of a lower bound of the reciprocal of the Dif-function, i.e. SCALE is an upper bound of Dif[(A,D), (B,E)] = $\sigma_{\min}(Z)$, where Z as in (2). If IJOB = 0 or TRANS = 'C', SCALE is not referenced.

DIF (output)

On exit SCALE is the reciprocal of a lower bound of the reciprocal of the Dif-function, i.e. SCALE is an upper bound of Dif[(A,D), (B,E)] = $\sigma_{\min}(Z)$, where Z as in (2). If IJOB = 0 or TRANS = 'C', SCALE is not referenced.

WORK (workspace)

If IJOB = 0, WORK is not referenced. Otherwise, on exit, if INFO=0 then WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq 1. If IJOB = 1 or 2 and TRANS = 'N', LWORK \geq 2*M*N.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

IWORK (workspace)

If IJOB = 0, IWORK is not referenced.

INFO (output)

=0: successful exit
<0: If INFO = -i, the i-th argument had an illegal

value.
>0: (A, D) and (B, E) have common or very close eigenvalues.

FURTHER DETAILS

Based on contributions by
Bo Kagstrom and Peter Poromaa, Department of Computing
Science,
Umea University, S-901 87 Umea, Sweden.

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[2] B. Kagstrom, A Perturbation Analysis of the Generalized
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Appl., 15(4):1045-1060, 1994.

[3] B. Kagstrom and L. Westin, Generalized Schur Methods
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NAME

ztpcon - estimate the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE ZTPCON(NORM, UPLO, DIAG, N, A, RCOND, WORK, WORK2, INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER N, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZTPCON_64(NORM, UPLO, DIAG, N, A, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
DOUBLE COMPLEX A(*), WORK(*)  
INTEGER*8 N, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TPCON(NORM, UPLO, DIAG, [N], A, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER :: N, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE TPCON_64(NORM, UPLO, DIAG, [N], A, RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX(8), DIMENSION(:) :: A, WORK  
INTEGER(8) :: N, INFO  
REAL(8) :: RCOND
```

```
REAL(8), DIMENSION(:) :: WORK2
```

C INTERFACE

```
#include <sunperf.h>

void ztpcon(char norm, char uplo, char diag, int n, doublecomplex *a, double *rcond, int *info);
void ztpcon_64(char norm, char uplo, char diag, long n, doublecomplex *a, double *rcond, long *info);
```

PURPOSE

ztpcon estimates the reciprocal of the condition number of a packed triangular matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
= '1' or 'O': 1-norm;
= 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$

The upper or lower triangular matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. If DIAG = 'U', the diagonal elements of A are not referenced and are assumed to be 1.

RCOND (output)

The reciprocal of the condition number of the matrix A, computed as $\text{RCOND} = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)

COMPLEX*16 array, dimension $(2*N)$

WORK2 (workspace)

DOUBLE PRECISION array, dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ztpmv - perform one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$

SYNOPSIS

```
SUBROUTINE ZTPMV(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(*), Y(*)  
INTEGER N, INCY
```

```
SUBROUTINE ZTPMV_64(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(*), Y(*)  
INTEGER*8 N, INCY
```

F95 INTERFACE

```
SUBROUTINE TPMV(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: A, Y  
INTEGER :: N, INCY
```

```
SUBROUTINE TPMV_64(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: A, Y  
INTEGER(8) :: N, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztpmv(char uplo, char transa, char diag, int n, doublecomplex *a, doublecomplex *y, int incy);
```

```
void ztpmv_64(char uplo, char transa, char diag, long n, doublecomplex *a, doublecomplex *y, long incy);
```

PURPOSE

ztpmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A')*x$ where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular matrix, supplied in packed form.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the operation to be performed as follows:

TRANSA = 'N' or 'n' $x := A*x$.

TRANSA = 'T' or 't' $x := A'*x$.

TRANSA = 'C' or 'c' $x := \text{conjg}(A')*x$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

(($n*(n+1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper triangular matrix packed sequentially, column by column, so that $A(1)$ contains $a(1,1)$, $A(2)$ and $A(3)$ contain $a(1,2)$ and $a(2,2)$ respec-

tively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced, but are assumed to be unity. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

ztpfrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix

SYNOPSIS

```
SUBROUTINE ZTPRFS(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZTPRFS_64(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, X, LDX,  
    FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TPRFS(UPLO, [TRANSA], DIAG, [N], NRHS, A, B, [LDB], X, [LDX],  
    FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: A, WORK  
COMPLEX(8), DIMENSION(:, :) :: B, X  
INTEGER :: N, NRHS, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE TPRFS_64(UPLO, [TRANSA], DIAG, [N], NRHS, A, B, [LDB], X,  
    [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: A, WORK  
COMPLEX(8), DIMENSION(:, :) :: B, X  
INTEGER(8) :: N, NRHS, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void ztprfs(char uplo, char transa, char diag, int n, int
            nrhs, doublecomplex *a, doublecomplex *b, int ldb,
            doublecomplex *x, int ldx, double *ferr, double
            *berr, int *info);

void ztprfs_64(char uplo, char transa, char diag, long n,
              long nrhs, doublecomplex *a, doublecomplex *b,
              long ldb, doublecomplex *x, long ldx, double
              *ferr, double *berr, long *info);
```

PURPOSE

ztprfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular packed coefficient matrix.

The solution matrix X must be computed by ZTPTRS or some other means before entering this routine. ZTPRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$

The upper or lower triangular matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2n-j)/2) = A(i,j)$ for $j \leq i \leq n$. If DIAG = 'U', the diagonal elements of

A are not referenced and are assumed to be 1.

B (input) COMPLEX*16 array, dimension (LDB,NRHS)
The right hand side matrix B.

LDB (input)
The leading dimension of the array B. LDB >= max(1,N).

X (input) COMPLEX*16 array, dimension (LDX,NRHS)
The solution matrix X.

LDX (input)
The leading dimension of the array X. LDX >= max(1,N).

FERR (output) DOUBLE PRECISION array, dimension (NRHS)
The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output) DOUBLE PRECISION array, dimension (NRHS)
The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)
COMPLEX*16 array, dimension(2*N)

WORK2 (workspace)
DOUBLE PRECISION array, dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ztpsv - solve one of the systems of equations $Ax = b$, or $A^H x = b$, or $\text{conjg}(A^H)x = b$

SYNOPSIS

```
SUBROUTINE ZTPSV(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(*), Y(*)  
INTEGER N, INCY
```

```
SUBROUTINE ZTPSV_64(UPLO, TRANSA, DIAG, N, A, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(*), Y(*)  
INTEGER*8 N, INCY
```

F95 INTERFACE

```
SUBROUTINE TPSV(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: A, Y  
INTEGER :: N, INCY
```

```
SUBROUTINE TPSV_64(UPLO, [TRANSA], DIAG, [N], A, Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: A, Y  
INTEGER(8) :: N, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztpsv(char uplo, char transa, char diag, int n, doublecomplex *a, doublecomplex *y, int incy);
```

```
void ztpsv_64(char uplo, char transa, char diag, long n, doublecomplex *a, doublecomplex *y, long incy);
```

PURPOSE

ztpsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A)*x = b$ where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular matrix, supplied in packed form.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANS (input)

On entry, TRANS specifies the equations to be solved as follows:

TRANS = 'N' or 'n' $A*x = b$.

TRANS = 'T' or 't' $A'*x = b$.

TRANS = 'C' or 'c' $\text{conjg}(A)*x = b$.

Unchanged on exit.

TRANS is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

(($n*(n+1)$) / 2). Before entry with UPLO = 'U' or 'u', the array A must contain the upper

triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(1, 2) and a(2, 2) respectively, and so on. Before entry with UPLO = 'L' or 'l', the array A must contain the lower triangular matrix packed sequentially, column by column, so that A(1) contains a(1, 1), A(2) and A(3) contain a(2, 1) and a(3, 1) respectively, and so on. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced, but are assumed to be unity. Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

ztptri - compute the inverse of a complex upper or lower triangular matrix A stored in packed format

SYNOPSIS

```
SUBROUTINE ZTPTRI(UPLO, DIAG, N, A, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
DOUBLE COMPLEX A(*)  
INTEGER N, INFO
```

```
SUBROUTINE ZTPTRI_64(UPLO, DIAG, N, A, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
DOUBLE COMPLEX A(*)  
INTEGER*8 N, INFO
```

F95 INTERFACE

```
SUBROUTINE TPTRI(UPLO, DIAG, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER :: N, INFO
```

```
SUBROUTINE TPTRI_64(UPLO, DIAG, [N], A, [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX(8), DIMENSION(:) :: A  
INTEGER(8) :: N, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztptri(char uplo, char diag, int n, doublecomplex *a,  
            int *info);
```

```
void ztptri_64(char uplo, char diag, long n, doublecomplex  
               *a, long *info);
```

PURPOSE

ztptri computes the inverse of a complex upper or lower triangular matrix A stored in packed format.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output) COMPLEX*16 array, dimension $(N*(N+1)/2)$

On entry, the upper or lower triangular matrix A, stored columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*((2*n-j)/2)) = A(i,j)$ for $j \leq i \leq n$. See below for further details. On exit, the (triangular) inverse of the original matrix, in the same packed storage format.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, $A(i,i)$ is exactly zero. The triangular matrix is singular and its inverse can not be computed.

FURTHER DETAILS

A triangular matrix A can be transferred to packed storage using one of the following program segments:

UPLO = 'U':

```
      JC = 1
      DO 2 J = 1, N
        DO 1 I = 1, J
          A(JC+I-1) = A(I,J)
1      CONTINUE
      JC = JC + J
1
2 CONTINUE
```

UPLO = 'L':

```
      JC = 1
      DO 2 J = 1, N
        DO 1 I = J, N
          A(JC+I-J) =
1      CONTINUE
      JC = JC + N - J +
2 CONTINUE
```

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NAME

ztptrs - solve a triangular system of the form $A * X = B$,
 $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE ZTPTRS(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER N, NRHS, LDB, INFO
```

```
SUBROUTINE ZTPTRS_64(UPLO, TRANSA, DIAG, N, NRHS, A, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(*), B(LDB,*)  
INTEGER*8 N, NRHS, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE TPTRS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER :: N, NRHS, LDB, INFO
```

```
SUBROUTINE TPTRS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, B, [LDB], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: A  
COMPLEX(8), DIMENSION(:, :) :: B  
INTEGER(8) :: N, NRHS, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztptrs(char uplo, char transa, char diag, int n, int  
nrhs, doublecomplex *a, doublecomplex *b, int ldb,  
int *info);
```

```
void ztptrs_64(char uplo, char transa, char diag, long n,
```

```
long nrhs, doublecomplex *a, doublecomplex *b,  
long ldb, long *info);
```

PURPOSE

ztptrs solves a triangular system of the form
 $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$

where A is a triangular matrix of order N stored in packed format, and B is an N-by-NRHS matrix. A check is made to verify that A is nonsingular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) COMPLEX*16 array, dimension $(N*(N+1)/2)$

The upper or lower triangular matrix A, packed columnwise in a linear array. The j-th column of A is stored in the array A as follows: if UPLO = 'U', $A(i + (j-1)*j/2) = A(i,j)$ for $1 \leq i \leq j$; if UPLO = 'L', $A(i + (j-1)*(2*n-j)/2) = A(i,j)$ for $j \leq i \leq n$.

B (input/output) COMPLEX*16 array, dimension (LDB,NRHS)

On entry, the right hand side matrix B. On exit, if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. $LDB \geq \max(1,N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element of A is zero, indicating that the matrix is singular and the solutions X have not been computed.

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NAME

ztrans - transpose and scale source matrix

SYNOPSIS

```
SUBROUTINE ZTRANS(PLACE, SCALE, SOURCE, M, N, DEST)
```

```
CHARACTER * 1 PLACE  
DOUBLE COMPLEX SCALE  
DOUBLE COMPLEX SOURCE(*), DEST(*)  
INTEGER M, N
```

```
SUBROUTINE ZTRANS_64(PLACE, SCALE, SOURCE, M, N, DEST)
```

```
CHARACTER * 1 PLACE  
DOUBLE COMPLEX SCALE  
DOUBLE COMPLEX SOURCE(*), DEST(*)  
INTEGER*8 M, N
```

F95 INTERFACE

```
SUBROUTINE TRANS([PLACE], SCALE, SOURCE, M, N, [DEST])
```

```
CHARACTER(LEN=1) :: PLACE  
COMPLEX(8) :: SCALE  
COMPLEX(8), DIMENSION(:) :: SOURCE, DEST  
INTEGER :: M, N
```

```
SUBROUTINE TRANS_64([PLACE], SCALE, SOURCE, M, N, [DEST])
```

```
CHARACTER(LEN=1) :: PLACE  
COMPLEX(8) :: SCALE  
COMPLEX(8), DIMENSION(:) :: SOURCE, DEST  
INTEGER(8) :: M, N
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrans(char place, doublecomplex *scale, doublecomplex  
            *source, int m, int n, doublecomplex *dest);
```

```
void ztrans_64(char place, doublecomplex *scale, doublecom-
```

```
plex *source, long m, long n, doublecomplex
*dest);
```

PURPOSE

ztrans scales and transposes the source matrix. The $N_2 \times N_1$ result is written into SOURCE when PLACE = 'I' or 'i', and DEST when PLACE = 'O' or 'o'.

```
PLACE = 'I' or 'i': SOURCE = SCALE * SOURCE'
```

```
PLACE = 'O' or 'o': DEST = SCALE * SOURCE'
```

ARGUMENTS

PLACE (input)

Type of transpose. 'I' or 'i' for in-place, 'O' or 'o' for out-of-place. 'I' is default.

SCALE (input)

Scale factor on the SOURCE matrix.

SOURCE (input/output)

on input. Array of (N, M) on output if in-place transpose.

M (input)

Number of rows in the SOURCE matrix on input.

N (input)

Number of columns in the SOURCE matrix on input.

DEST (output)

Scaled and transposed SOURCE matrix if out-of-place transpose. Not referenced if in-place transpose.

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NAME

ztrcon - estimate the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm

SYNOPSIS

```
SUBROUTINE ZTRCON(NORM, UPLO, DIAG, N, A, LDA, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER N, LDA, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION WORK2(*)
```

```
SUBROUTINE ZTRCON_64(NORM, UPLO, DIAG, N, A, LDA, RCOND, WORK, WORK2,  
INFO)
```

```
CHARACTER * 1 NORM, UPLO, DIAG  
DOUBLE COMPLEX A(LDA,*), WORK(*)  
INTEGER*8 N, LDA, INFO  
DOUBLE PRECISION RCOND  
DOUBLE PRECISION WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TRCON(NORM, UPLO, DIAG, [N], A, [LDA], RCOND, [WORK], [WORK2],  
[INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO  
REAL(8) :: RCOND  
REAL(8), DIMENSION(:) :: WORK2
```

```
SUBROUTINE TRCON_64(NORM, UPLO, DIAG, [N], A, [LDA], RCOND, [WORK],  
[WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: NORM, UPLO, DIAG  
COMPLEX(8), DIMENSION(:) :: WORK
```

```

COMPLEX(8), DIMENSION(:,:) :: A
INTEGER(8) :: N, LDA, INFO
REAL(8) :: RCOND
REAL(8), DIMENSION(:) :: WORK2

```

C INTERFACE

```

#include <sunperf.h>
void ztrcon(char norm, char uplo, char diag, int n, double-
            lecomplex *a, int lda, double *rcond, int *info);

void ztrcon_64(char norm, char uplo, char diag, long n,
              doublecomplex *a, long lda, double *rcond, long
              *info);

```

PURPOSE

ztrcon estimates the reciprocal of the condition number of a triangular matrix A, in either the 1-norm or the infinity-norm.

The norm of A is computed and an estimate is obtained for $\text{norm}(\text{inv}(A))$, then the reciprocal of the condition number is computed as

$$\text{RCOND} = 1 / (\text{norm}(A) * \text{norm}(\text{inv}(A))).$$

ARGUMENTS

NORM (input)

Specifies whether the 1-norm condition number or the infinity-norm condition number is required:
 = '1' or 'O': 1-norm;
 = 'I': Infinity-norm.

UPLO (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

RCOND (output)
The reciprocal of the condition number of the matrix A, computed as $RCOND = 1/(\text{norm}(A) * \text{norm}(\text{inv}(A)))$.

WORK (workspace)
dimension(2*N)

WORK2 (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ztrevc - compute some or all of the right and/or left eigenvectors of a complex upper triangular matrix T

SYNOPSIS

```
SUBROUTINE ZTREVC(SIDE, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,
                 LDVR, MM, M, WORK, RWORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY
DOUBLE COMPLEX T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER N, LDT, LDVL, LDVR, MM, M, INFO
LOGICAL SELECT(*)
DOUBLE PRECISION RWORK(*)
```

```
SUBROUTINE ZTREVC_64(SIDE, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,
                    LDVR, MM, M, WORK, RWORK, INFO)
```

```
CHARACTER * 1 SIDE, HOWMNY
DOUBLE COMPLEX T(LDT,*), VL(LDVL,*), VR(LDVR,*), WORK(*)
INTEGER*8 N, LDT, LDVL, LDVR, MM, M, INFO
LOGICAL*8 SELECT(*)
DOUBLE PRECISION RWORK(*)
```

F95 INTERFACE

```
SUBROUTINE TREVC(SIDE, HOWMNY, SELECT, [N], T, [LDT], VL, [LDVL], VR,
                [LDVR], MM, M, [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY
COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:, :) :: T, VL, VR
INTEGER :: N, LDT, LDVL, LDVR, MM, M, INFO
LOGICAL, DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: RWORK
```

```
SUBROUTINE TREVC_64(SIDE, HOWMNY, SELECT, [N], T, [LDT], VL, [LDVL],
                   VR, [LDVR], MM, M, [WORK], [RWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, HOWMNY
```

```

COMPLEX(8), DIMENSION(:) :: WORK
COMPLEX(8), DIMENSION(:,:) :: T, VL, VR
INTEGER(8) :: N, LDT, LDVL, LDVR, MM, M, INFO
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: RWORK

```

C INTERFACE

```

#include <sunperf.h>
void ztrevc(char side, char howmny, int *select, int n,
            doublecomplex *t, int ldt, doublecomplex *vl, int
            ldvl, doublecomplex *vr, int ldvr, int mm, int *m,
            int *info);

void ztrevc_64(char side, char howmny, long *select, long n,
               doublecomplex *t, long ldt, doublecomplex *vl,
               long ldvl, doublecomplex *vr, long ldvr, long mm,
               long *m, long *info);

```

PURPOSE

ztrevc computes some or all of the right and/or left eigenvectors of a complex upper triangular matrix T.

The right eigenvector x and the left eigenvector y of T corresponding to an eigenvalue w are defined by:

$$T*x = w*x, \quad y'*T = w*y'$$

where y' denotes the conjugate transpose of the vector y.

If all eigenvectors are requested, the routine may either return the matrices X and/or Y of right or left eigenvectors of T, or the products Q*X and/or Q*Y, where Q is an input unitary matrix. If T was obtained from the Schur factorization of an original matrix $A = Q*T*Q'$, then Q*X and Q*Y are the matrices of right or left eigenvectors of A.

ARGUMENTS

SIDE (input)
 = 'R': compute right eigenvectors only;
 = 'L': compute left eigenvectors only;
 = 'B': compute both right and left eigenvectors.

HOWMNY (input)
 = 'A': compute all right and/or left eigenvectors;
 = 'B': compute all right and/or left eigenvectors, and backtransform them using the input matrices supplied in VR and/or VL; = 'S': compute selected right and/or left eigenvectors, specified by the logical array SELECT.

SELECT (input/output)
 If HOWMNY = 'S', SELECT specifies the eigenvectors

to be computed. If HOWMNY = 'A' or 'B', SELECT is not referenced. To select the eigenvector corresponding to the j-th eigenvalue, SELECT(j) must be set to .TRUE..

N (input) The order of the matrix T. $N \geq 0$.

T (input/output)
The upper triangular matrix T. T is modified, but restored on exit.

LDT (input)
The leading dimension of the array T. $LDT \geq \max(1,N)$.

VL (input/output)
On entry, if SIDE = 'L' or 'B' and HOWMNY = 'B', VL must contain an N-by-N matrix Q (usually the unitary matrix Q of Schur vectors returned by CHSEQR). On exit, if SIDE = 'L' or 'B', VL contains: if HOWMNY = 'A', the matrix Y of left eigenvectors of T; VL is lower triangular. The i-th column VL(i) of VL is the eigenvector corresponding to T(i,i). if HOWMNY = 'B', the matrix Q*Y; if HOWMNY = 'S', the left eigenvectors of T specified by SELECT, stored consecutively in the columns of VL, in the same order as their eigenvalues. If SIDE = 'R', VL is not referenced.

LDVL (input)
The leading dimension of the array VL. $LDVL \geq \max(1,N)$ if SIDE = 'L' or 'B'; $LDVL \geq 1$ otherwise.

VR (input/output)
On entry, if SIDE = 'R' or 'B' and HOWMNY = 'B', VR must contain an N-by-N matrix Q (usually the unitary matrix Q of Schur vectors returned by CHSEQR). On exit, if SIDE = 'R' or 'B', VR contains: if HOWMNY = 'A', the matrix X of right eigenvectors of T; VR is upper triangular. The i-th column VR(i) of VR is the eigenvector corresponding to T(i,i). if HOWMNY = 'B', the matrix Q*X; if HOWMNY = 'S', the right eigenvectors of T specified by SELECT, stored consecutively in the columns of VR, in the same order as their eigenvalues. If SIDE = 'L', VR is not referenced.

LDVR (input)
The leading dimension of the array VR. $LDVR \geq \max(1,N)$ if SIDE = 'R' or 'B'; $LDVR \geq 1$ otherwise.

MM (input)
The number of columns in the arrays VL and/or VR. $MM \geq M$.

M (output)
The number of columns in the arrays VL and/or VR actually used to store the eigenvectors. If

HOWMNY = 'A' or 'B', M is set to N. Each selected eigenvector occupies one column.

WORK (workspace)
dimension(2*N)

RWORK (workspace)
dimension(N)

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The algorithm used in this program is basically backward (forward) substitution, with scaling to make the code robust against possible overflow.

Each eigenvector is normalized so that the element of largest magnitude has magnitude 1; here the magnitude of a complex number (x,y) is taken to be $|x| + |y|$.

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NAME

ztrexc - reorder the Schur factorization of a complex matrix $A = Q^*T^*Q^{**H}$, so that the diagonal element of T with row index IFST is moved to row ILST

SYNOPSIS

```
SUBROUTINE ZTREXC(COMPQ, N, T, LDT, Q, LDQ, IFST, ILST, INFO)
```

```
CHARACTER * 1 COMPQ  
DOUBLE COMPLEX T(LDT,*), Q(LDQ,*)  
INTEGER N, LDT, LDQ, IFST, ILST, INFO
```

```
SUBROUTINE ZTREXC_64(COMPQ, N, T, LDT, Q, LDQ, IFST, ILST, INFO)
```

```
CHARACTER * 1 COMPQ  
DOUBLE COMPLEX T(LDT,*), Q(LDQ,*)  
INTEGER*8 N, LDT, LDQ, IFST, ILST, INFO
```

F95 INTERFACE

```
SUBROUTINE TREXC(COMPQ, [N], T, [LDT], Q, [LDQ], IFST, ILST, [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ  
COMPLEX(8), DIMENSION(:,*) :: T, Q  
INTEGER :: N, LDT, LDQ, IFST, ILST, INFO
```

```
SUBROUTINE TREXC_64(COMPQ, [N], T, [LDT], Q, [LDQ], IFST, ILST, [INFO])
```

```
CHARACTER(LEN=1) :: COMPQ  
COMPLEX(8), DIMENSION(:,*) :: T, Q  
INTEGER(8) :: N, LDT, LDQ, IFST, ILST, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrexc(char compq, int n, doublecomplex *t, int ldt,  
            doublecomplex *q, int ldq, int ifst, int ilst, int  
            *info);
```

```
void ztrexc_64(char compq, long n, doublecomplex *t, long  
              ldt, doublecomplex *q, long ldq, long ifst, long
```

```
ilst, long *info);
```

PURPOSE

ztrexc reorders the Schur factorization of a complex matrix $A = Q^*TQ^*H$, so that the diagonal element of T with row index IFST is moved to row ILST.

The Schur form T is reordered by a unitary similarity transformation $Z^*H^*T^*Z$, and optionally the matrix Q of Schur vectors is updated by postmultiplying it with Z .

ARGUMENTS

COMPQ (input)

= 'V': update the matrix Q of Schur vectors;
= 'N': do not update Q .

N (input) The order of the matrix T . $N \geq 0$.

T (input/output)

On entry, the upper triangular matrix T . On exit, the reordered upper triangular matrix.

LDT (input)

The leading dimension of the array T . $LDT \geq \max(1, N)$.

Q (input) On entry, if COMPQ = 'V', the matrix Q of Schur vectors. On exit, if COMPQ = 'V', Q has been postmultiplied by the unitary transformation matrix Z which reorders T . If COMPQ = 'N', Q is not referenced.

LDQ (input)

The leading dimension of the array Q . $LDQ \geq \max(1, N)$.

IFST (input)

Specify the reordering of the diagonal elements of T : The element with row index IFST is moved to row ILST by a sequence of transpositions between adjacent elements. $1 \leq IFST \leq N$; $1 \leq ILST \leq N$.

ILST (input)

See the description of IFST.

INFO (output)

= 0: successful exit
< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

ztrmm - perform one of the matrix-matrix operations $B := \alpha * \text{op}(A) * B$, or $B := \alpha * B * \text{op}(A)$ where alpha is a scalar, B is an m by n matrix, A is a unit, or non-unit, upper or lower triangular matrix and op(A) is one of op(A) = A or op(A) = A' or op(A) = conjg(A')

SYNOPSIS

```
SUBROUTINE ZTRMM(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
DOUBLE COMPLEX ALPHA
DOUBLE COMPLEX A(LDA,*), B(LDB,*)
INTEGER M, N, LDA, LDB
```

```
SUBROUTINE ZTRMM_64(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                   LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
DOUBLE COMPLEX ALPHA
DOUBLE COMPLEX A(LDA,*), B(LDB,*)
INTEGER*8 M, N, LDA, LDB
```

F95 INTERFACE

```
SUBROUTINE TRMM(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A, [LDA],
                B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
COMPLEX(8) :: ALPHA
COMPLEX(8), DIMENSION(:,:) :: A, B
INTEGER :: M, N, LDA, LDB
```

```
SUBROUTINE TRMM_64(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A,
                  [LDA], B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
COMPLEX(8) :: ALPHA
COMPLEX(8), DIMENSION(:,:) :: A, B
INTEGER(8) :: M, N, LDA, LDB
```

C INTERFACE

```
#include <sunperf.h>

void ztrmm(char side, char uplo, char transa, char diag, int
           m, int n, doublecomplex *alpha, doublecomplex *a,
           int lda, doublecomplex *b, int ldb);
void ztrmm_64(char side, char uplo, char transa, char diag,
              long m, long n, doublecomplex *alpha, doublecom-
              plex *a, long lda, doublecomplex *b, long ldb);
```

PURPOSE

ztrmm performs one of the matrix-matrix operations $B := \alpha * \text{op}(A) * B$, or $B := \alpha * B * \text{op}(A)$ where α is a scalar, B is an m by n matrix, A is a unit, or non-unit, upper or lower triangular matrix and $\text{op}(A)$ is one of $\text{op}(A) = A$ or $\text{op}(A) = A'$ or $\text{op}(A) = \text{conjg}(A')$

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether $\text{op}(A)$ multiplies B from the left or right as follows:

SIDE = 'L' or 'l' $B := \alpha * \text{op}(A) * B$.

SIDE = 'R' or 'r' $B := \alpha * B * \text{op}(A)$.

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the matrix A is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the form of $\text{op}(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n' $\text{op}(A) = A$.

TRANSA = 'T' or 't' $\text{op}(A) = A'$.

TRANSA = 'C' or 'c' $\text{op}(A) = \text{conjg}(A')$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of B. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of B. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. When alpha is zero then A is not referenced and B need not be set before entry. Unchanged on exit.

A (input)

COMPLEX*16 array of DIMENSION (LDA, k), where k is m when SIDE = 'L' or 'l' and is n when SIDE = 'R' or 'r'.

Before entry with UPLO = 'U' or 'u', the leading k by k upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced.

Before entry with UPLO = 'L' or 'l', the leading k by k lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced.

Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity.

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then $LDA \geq \max(1,M)$, when SIDE = 'R' or 'r' then $LDA \geq \max(1,N)$. Unchanged on exit.

B (input/output)

COMPLEX*16 array of DIMENSION (LDB, n). Before entry, the leading M by N part of the array B must contain the matrix B, and on exit is overwritten by the transformed matrix.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling subprogram. LDB must be at least $\max(1,M)$. Unchanged on exit.

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NAME

ztrmv - perform one of the matrix-vector operations $x := A^*x$, or $x := A'x$, or $x := \text{conjg}(A')x$

SYNOPSIS

```
SUBROUTINE ZTRMV(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), Y(*)  
INTEGER N, LDA, INCY
```

```
SUBROUTINE ZTRMV_64(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), Y(*)  
INTEGER*8 N, LDA, INCY
```

F95 INTERFACE

```
SUBROUTINE TRMV(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INCY
```

```
SUBROUTINE TRMV_64(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrmv(char uplo, char transa, char diag, int n, doublecomplex *a, int lda, doublecomplex *y, int incy);
```

```
void ztrmv_64(char uplo, char transa, char diag, long n,
```

```
doublecomplex *a, long lda, doublecomplex *y, long
incy);
```

PURPOSE

ztrmv performs one of the matrix-vector operations $x := A*x$, or $x := A'*x$, or $x := \text{conjg}(A)*x$ where x is an n element vector and A is an n by n unit, or non-unit, upper or lower triangular matrix.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANS (input)

On entry, TRANS specifies the operation to be performed as follows:

TRANS = 'N' or 'n' $x := A*x$.

TRANS = 'T' or 't' $x := A'*x$.

TRANS = 'C' or 'c' $x := \text{conjg}(A)*x$.

Unchanged on exit.

TRANS is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A . $N \geq 0$. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must

contain the upper triangular matrix and the strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. $LDA \geq \max(1, n)$. Unchanged on exit.

Y (input/output)

$(1 + (n - 1) * \text{abs}(\text{INCY}))$. Before entry, the incremented array Y must contain the n element vector x. On exit, Y is overwritten with the transformed vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. $\text{INCY} \neq 0$. Unchanged on exit.

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NAME

ztrrfs - provide error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix

SYNOPSIS

```
SUBROUTINE ZTRRFS(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER N, NRHS, LDA, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

```
SUBROUTINE ZTRRFS_64(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, X,  
  LDX, FERR, BERR, WORK, WORK2, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), B(LDB,*), X(LDX,*), WORK(*)  
INTEGER*8 N, NRHS, LDA, LDB, LDX, INFO  
DOUBLE PRECISION FERR(*), BERR(*), WORK2(*)
```

F95 INTERFACE

```
SUBROUTINE TRRFS(UPLO, [TRANSA], DIAG, N, NRHS, A, [LDA], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B, X  
INTEGER :: N, NRHS, LDA, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

```
SUBROUTINE TRRFS_64(UPLO, [TRANSA], DIAG, N, NRHS, A, [LDA], B, [LDB],  
  X, [LDX], FERR, BERR, [WORK], [WORK2], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: WORK  
COMPLEX(8), DIMENSION(:, :) :: A, B, X  
INTEGER(8) :: N, NRHS, LDA, LDB, LDX, INFO  
REAL(8), DIMENSION(:) :: FERR, BERR, WORK2
```

C INTERFACE

```
#include <sunperf.h>

void ztrrfs(char uplo, char transa, char diag, int n, int
            nrhs, doublecomplex *a, int lda, doublecomplex *b,
            int ldb, doublecomplex *x, int ldx, double *ferr,
            double *berr, int *info);

void ztrrfs_64(char uplo, char transa, char diag, long n,
              long nrhs, doublecomplex *a, long lda, doublecom-
              plex *b, long ldb, doublecomplex *x, long ldx,
              double *ferr, double *berr, long *info);
```

PURPOSE

ztrrfs provides error bounds and backward error estimates for the solution to a system of linear equations with a triangular coefficient matrix.

The solution matrix X must be computed by ZTRTRS or some other means before entering this routine. ZTRRFS does not do iterative refinement because doing so cannot improve the backward error.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
= 'N': $A * X = B$ (No transpose)
= 'T': $A^{**T} * X = B$ (Transpose)
= 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrices B and X. $NRHS \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper

triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. LDA \geq max(1,N).

B (input) The right hand side matrix B.

LDB (input)

The leading dimension of the array B. LDB \geq max(1,N).

X (input) The solution matrix X.

LDX (input)

The leading dimension of the array X. LDX \geq max(1,N).

FERR (output)

The estimated forward error bound for each solution vector X(j) (the j-th column of the solution matrix X). If XTRUE is the true solution corresponding to X(j), FERR(j) is an estimated upper bound for the magnitude of the largest element in (X(j) - XTRUE) divided by the magnitude of the largest element in X(j). The estimate is as reliable as the estimate for RCOND, and is almost always a slight overestimate of the true error.

BERR (output)

The componentwise relative backward error of each solution vector X(j) (i.e., the smallest relative change in any element of A or B that makes X(j) an exact solution).

WORK (workspace)

dimension(2*N)

WORK2 (workspace)

dimension(N)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

ztrsen - reorder the Schur factorization of a complex matrix $A = Q^*T^*Q^*H$, so that a selected cluster of eigenvalues appears in the leading positions on the diagonal of the upper triangular matrix T , and the leading columns of Q form an orthonormal basis of the corresponding right invariant subspace

SYNOPSIS

```
SUBROUTINE ZTRSEN(JOB, COMPQ, SELECT, N, T, LDT, Q, LDQ, W, M, S,  
                SEP, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ  
DOUBLE COMPLEX T(LDT,*), Q(LDQ,*), W(*), WORK(*)  
INTEGER N, LDT, LDQ, M, LWORK, INFO  
LOGICAL SELECT(*)  
DOUBLE PRECISION S, SEP
```

```
SUBROUTINE ZTRSEN_64(JOB, COMPQ, SELECT, N, T, LDT, Q, LDQ, W, M, S,  
                   SEP, WORK, LWORK, INFO)
```

```
CHARACTER * 1 JOB, COMPQ  
DOUBLE COMPLEX T(LDT,*), Q(LDQ,*), W(*), WORK(*)  
INTEGER*8 N, LDT, LDQ, M, LWORK, INFO  
LOGICAL*8 SELECT(*)  
DOUBLE PRECISION S, SEP
```

F95 INTERFACE

```
SUBROUTINE TRSEN(JOB, COMPQ, SELECT, [N], T, [LDT], Q, [LDQ], W, M,  
                S, SEP, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ  
COMPLEX(8), DIMENSION(:) :: W, WORK  
COMPLEX(8), DIMENSION(:, :) :: T, Q  
INTEGER :: N, LDT, LDQ, M, LWORK, INFO  
LOGICAL, DIMENSION(:) :: SELECT  
REAL(8) :: S, SEP
```

```
SUBROUTINE TRSEN_64(JOB, COMPQ, SELECT, [N], T, [LDT], Q, [LDQ], W,  
M, S, SEP, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, COMPQ  
COMPLEX(8), DIMENSION(:) :: W, WORK  
COMPLEX(8), DIMENSION(:, :) :: T, Q  
INTEGER(8) :: N, LDT, LDQ, M, LWORK, INFO  
LOGICAL(8), DIMENSION(:) :: SELECT  
REAL(8) :: S, SEP
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrsen(char job, char compq, int *select, int n, doublecomplex *t, int ldt, doublecomplex *q, int ldq, doublecomplex *w, int *m, double *s, double *sep, int *info);
```

```
void ztrsen_64(char job, char compq, long *select, long n, doublecomplex *t, long ldt, doublecomplex *q, long ldq, doublecomplex *w, long *m, double *s, double *sep, long *info);
```

PURPOSE

ztrsen reorders the Schur factorization of a complex matrix $A = Q^*T^*Q^{**H}$, so that a selected cluster of eigenvalues appears in the leading positions on the diagonal of the upper triangular matrix T, and the leading columns of Q form an orthonormal basis of the corresponding right invariant subspace.

Optionally the routine computes the reciprocal condition numbers of the cluster of eigenvalues and/or the invariant subspace.

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for the cluster of eigenvalues (S) or the invariant subspace (SEP):
= 'N': none;
= 'E': for eigenvalues only (S);
= 'V': for invariant subspace only (SEP);
= 'B': for both eigenvalues and invariant subspace (S and SEP).

COMPQ (input)

= 'V': update the matrix Q of Schur vectors;
= 'N': do not update Q.

SELECT (input)

SELECT specifies the eigenvalues in the selected cluster. To select the j-th eigenvalue, SELECT(j) must be set to .TRUE..

N (input) The order of the matrix T. $N \geq 0$.

T (input/output)
 On entry, the upper triangular matrix T. On exit, T is overwritten by the reordered matrix T, with the selected eigenvalues as the leading diagonal elements.

LDT (input)
 The leading dimension of the array T. $LDT \geq \max(1, N)$.

Q (input) On entry, if COMPQ = 'V', the matrix Q of Schur vectors. On exit, if COMPQ = 'V', Q has been postmultiplied by the unitary transformation matrix which reorders T; the leading M columns of Q form an orthonormal basis for the specified invariant subspace. If COMPQ = 'N', Q is not referenced.

LDQ (input)
 The leading dimension of the array Q. $LDQ \geq 1$; and if COMPQ = 'V', $LDQ \geq N$.

W (output)
 The reordered eigenvalues of T, in the same order as they appear on the diagonal of T.

M (output)
 The dimension of the specified invariant subspace. $0 \leq M \leq N$.

S (output)
 If JOB = 'E' or 'B', S is a lower bound on the reciprocal condition number for the selected cluster of eigenvalues. S cannot underestimate the true reciprocal condition number by more than a factor of \sqrt{N} . If $M = 0$ or N , $S = 1$. If JOB = 'N' or 'V', S is not referenced.

SEP (output)
 If JOB = 'V' or 'B', SEP is the estimated reciprocal condition number of the specified invariant subspace. If $M = 0$ or N , $SEP = \text{norm}(T)$. If JOB = 'N' or 'E', SEP is not referenced.

WORK (workspace)
 If JOB = 'N', WORK is not referenced. Otherwise, on exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. If JOB = 'N', $LWORK \geq 1$; if JOB = 'E', $LWORK = M*(N-M)$; if JOB = 'V' or 'B', $LWORK \geq 2*M*(N-M)$.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

ZTRSEN first collects the selected eigenvalues by computing a unitary transformation Z to move them to the top left corner of T. In other words, the selected eigenvalues are the eigenvalues of T11 in:

$$Z'^*T*Z = \begin{pmatrix} T11 & T12 \\ 0 & T22 \end{pmatrix} \begin{matrix} n1 \\ n2 \\ n1 & n2 \end{matrix}$$

where N = n1+n2 and Z' means the conjugate transpose of Z. The first n1 columns of Z span the specified invariant subspace of T.

If T has been obtained from the Schur factorization of a matrix A = Q*T*Q', then the reordered Schur factorization of A is given by A = (Q*Z)*(Z'*T*Z)*(Q*Z)', and the first n1 columns of Q*Z span the corresponding invariant subspace of A.

The reciprocal condition number of the average of the eigenvalues of T11 may be returned in S. S lies between 0 (very badly conditioned) and 1 (very well conditioned). It is computed as follows. First we compute R so that

$$P = \begin{pmatrix} I & R \\ 0 & 0 \end{pmatrix} \begin{matrix} n1 \\ n2 \\ n1 & n2 \end{matrix}$$

is the projector on the invariant subspace associated with T11. R is the solution of the Sylvester equation:

$$T11*R - R*T22 = T12.$$

Let F-norm(M) denote the Frobenius-norm of M and 2-norm(M) denote the two-norm of M. Then S is computed as the lower bound

$$(1 + F\text{-norm}(R)**2)**(-1/2)$$

on the reciprocal of 2-norm(P), the true reciprocal condition number. S cannot underestimate 1 / 2-norm(P) by more than a factor of sqrt(N).

An approximate error bound for the computed average of the eigenvalues of T11 is

$$EPS * \text{norm}(T) / S$$

where EPS is the machine precision.

The reciprocal condition number of the right invariant subspace spanned by the first n1 columns of Z (or of Q*Z) is returned in SEP. SEP is defined as the separation of T11 and T22:

$$\text{sep}(T11, T22) = \text{sigma-min}(C)$$

where $\text{sigma-min}(C)$ is the smallest singular value of the $n1*n2$ -by- $n1*n2$ matrix

$$C = \text{kprod}(I(n2), T11) - \text{kprod}(\text{transpose}(T22), I(n1))$$

$I(m)$ is an m by m identity matrix, and kprod denotes the Kronecker product. We estimate $\text{sigma-min}(C)$ by the reciprocal of an estimate of the 1-norm of $\text{inverse}(C)$. The true reciprocal 1-norm of $\text{inverse}(C)$ cannot differ from $\text{sigma-min}(C)$ by more than a factor of $\text{sqrt}(n1*n2)$.

When SEP is small, small changes in T can cause large changes in the invariant subspace. An approximate bound on the maximum angular error in the computed right invariant subspace is

$$\text{EPS} * \text{norm}(T) / \text{SEP}$$

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NAME

ztrsm - solve one of the matrix equations $op(A)X = \alpha B$, or $Xop(A) = \alpha B$

SYNOPSIS

```
SUBROUTINE ZTRSM(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
DOUBLE COMPLEX ALPHA
DOUBLE COMPLEX A(LDA,*), B(LDB,*)
INTEGER M, N, LDA, LDB
```

```
SUBROUTINE ZTRSM_64(SIDE, UPLO, TRANSA, DIAG, M, N, ALPHA, A, LDA, B,
                   LDB)
```

```
CHARACTER * 1 SIDE, UPLO, TRANSA, DIAG
DOUBLE COMPLEX ALPHA
DOUBLE COMPLEX A(LDA,*), B(LDB,*)
INTEGER*8 M, N, LDA, LDB
```

F95 INTERFACE

```
SUBROUTINE TRSM(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A, [LDA],
               B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
COMPLEX(8) :: ALPHA
COMPLEX(8), DIMENSION(:,*) :: A, B
INTEGER :: M, N, LDA, LDB
```

```
SUBROUTINE TRSM_64(SIDE, UPLO, [TRANSA], DIAG, [M], [N], ALPHA, A,
                  [LDA], B, [LDB])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANSA, DIAG
COMPLEX(8) :: ALPHA
COMPLEX(8), DIMENSION(:,*) :: A, B
INTEGER(8) :: M, N, LDA, LDB
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrsm(char side, char uplo, char transa, char diag, int
           m, int n, doublecomplex *alpha, doublecomplex *a,
           int lda, doublecomplex *b, int ldb);
```

```
void ztrsm_64(char side, char uplo, char transa, char diag,
              long m, long n, doublecomplex *alpha,
              doublecomplex *a, long lda, doublecomplex *b, long
              ldb);
```

PURPOSE

ztrsm solves one of the matrix equations $op(A)X = \alpha B$, or $Xop(A) = \alpha B$ where α is a scalar, X and B are m by n matrices, A is a unit, or non-unit, upper or lower triangular matrix and $op(A)$ is one of

$op(A) = A$ or $op(A) = A'$ or $op(A) = conjg(A')$.

The matrix X is overwritten on B .

ARGUMENTS

SIDE (input)

On entry, SIDE specifies whether $op(A)$ appears on the left or right of X as follows:

SIDE = 'L' or 'l' $op(A)X = \alpha B$.

SIDE = 'R' or 'r' $Xop(A) = \alpha B$.

Unchanged on exit.

UPLO (input)

On entry, UPLO specifies whether the matrix A is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the form of $op(A)$ to be used in the matrix multiplication as follows:

TRANSA = 'N' or 'n' $op(A) = A$.

TRANSA = 'T' or 't' $op(A) = A'$.

TRANSA = 'C' or 'c' $op(A) = conjg(A')$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

M (input)

On entry, M specifies the number of rows of B. $M \geq 0$. Unchanged on exit.

N (input)

On entry, N specifies the number of columns of B. $N \geq 0$. Unchanged on exit.

ALPHA (input)

On entry, ALPHA specifies the scalar alpha. When alpha is zero then A is not referenced and B need not be set before entry. Unchanged on exit.

A (input)

COMPLEX*16 array of DIMENSION (LDA, k), where k is m when SIDE = 'L' or 'l' and is n when SIDE = 'R' or 'r'.

Before entry with UPLO = 'U' or 'u', the leading k by k upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced.

Before entry with UPLO = 'L' or 'l', the leading k by k lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced.

Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity.

Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. When SIDE = 'L' or 'l' then $LDA \geq \max(1, M)$, when SIDE = 'R' or 'r' then $LDA \geq \max(1, N)$. Unchanged on exit.

B (input/output)

COMPLEX*16 array of DIMENSION (LDB, n). Before entry, the leading M by N part of the array

B must contain the right-hand side matrix B, and on exit is overwritten by the solution matrix X.

LDB (input)

On entry, LDB specifies the first dimension of B as declared in the calling subprogram. LDB \geq max(1,M). Unchanged on exit.

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NAME

ztrsna - estimate reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a complex upper triangular matrix T (or of any matrix $Q^*T^*Q^{**}H$ with Q unitary)

SYNOPSIS

```
SUBROUTINE ZTRSNA(JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR, LDVR,  
S, SEP, MM, M, WORK, LDWORK, WORK1, INFO)
```

```
CHARACTER * 1 JOB, HOWMNY  
DOUBLE COMPLEX T(LDT,*), VL(LDVL,*), VR(LDVR,*),  
WORK(LDWORK,*)  
INTEGER N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
LOGICAL SELECT(*)  
DOUBLE PRECISION S(*), SEP(*), WORK1(*)
```

```
SUBROUTINE ZTRSNA_64(JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR,  
LDVR, S, SEP, MM, M, WORK, LDWORK, WORK1, INFO)
```

```
CHARACTER * 1 JOB, HOWMNY  
DOUBLE COMPLEX T(LDT,*), VL(LDVL,*), VR(LDVR,*),  
WORK(LDWORK,*)  
INTEGER*8 N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
LOGICAL*8 SELECT(*)  
DOUBLE PRECISION S(*), SEP(*), WORK1(*)
```

F95 INTERFACE

```
SUBROUTINE TRSNA(JOB, HOWMNY, SELECT, [N], T, [LDT], VL, [LDVL], VR,  
[LDVR], S, SEP, MM, M, [WORK], [LDWORK], [WORK1], [INFO])
```

```
CHARACTER(LEN=1) :: JOB, HOWMNY  
COMPLEX(8), DIMENSION(:,:) :: T, VL, VR, WORK  
INTEGER :: N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO  
LOGICAL, DIMENSION(:) :: SELECT  
REAL(8), DIMENSION(:) :: S, SEP, WORK1
```

```
SUBROUTINE TRSNA_64(JOB, HOWMNY, SELECT, [N], T, [LDT], VL, [LDVL],
```

VR, [LDVR], S, SEP, MM, M, [WORK], [LDWORK], [WORK1], [INFO])

```
CHARACTER(LEN=1) :: JOB, HOWMNY
COMPLEX(8), DIMENSION(:,:) :: T, VL, VR, WORK
INTEGER(8) :: N, LDT, LDVL, LDVR, MM, M, LDWORK, INFO
LOGICAL(8), DIMENSION(:) :: SELECT
REAL(8), DIMENSION(:) :: S, SEP, WORK1
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrsna(char job, char howmny, int *select, int n, doublecomplex *t, int ldt, doublecomplex *vl, int ldvl, doublecomplex *vr, int ldvr, double *s, double *sep, int mm, int *m, int ldwork, int *info);
```

```
void ztrsna_64(char job, char howmny, long *select, long n, doublecomplex *t, long ldt, doublecomplex *vl, long ldvl, doublecomplex *vr, long ldvr, double *s, double *sep, long mm, long *m, long ldwork, long *info);
```

PURPOSE

ztrsna estimates reciprocal condition numbers for specified eigenvalues and/or right eigenvectors of a complex upper triangular matrix T (or of any matrix $Q^*T^*Q^{**H}$ with Q unitary).

ARGUMENTS

JOB (input)

Specifies whether condition numbers are required for eigenvalues (S) or eigenvectors (SEP):
= 'E': for eigenvalues only (S);
= 'V': for eigenvectors only (SEP);
= 'B': for both eigenvalues and eigenvectors (S and SEP).

HOWMNY (input)

= 'A': compute condition numbers for all eigenpairs;
= 'S': compute condition numbers for selected eigenpairs specified by the array SELECT.

SELECT (input)

If HOWMNY = 'S', SELECT specifies the eigenpairs for which condition numbers are required. To select condition numbers for the j-th eigenpair, SELECT(j) must be set to .TRUE.. If HOWMNY = 'A', SELECT is not referenced.

N (input) The order of the matrix T. N >= 0.

T (input) The upper triangular matrix T.

LDT (input)

The leading dimension of the array T. LDT >=

max(1,N).

VL (input)

If JOB = 'E' or 'B', VL must contain left eigenvectors of T (or of any $Q^*T*Q^{**}H$ with Q unitary), corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors must be stored in consecutive columns of VL, as returned by ZHSEIN or ZTREVC. If JOB = 'V', VL is not referenced.

LDVL (input)

The leading dimension of the array VL. LDVL \geq 1; and if JOB = 'E' or 'B', LDVL \geq N.

VR (input)

If JOB = 'E' or 'B', VR must contain right eigenvectors of T (or of any $Q^*T*Q^{**}H$ with Q unitary), corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors must be stored in consecutive columns of VR, as returned by ZHSEIN or ZTREVC. If JOB = 'V', VR is not referenced.

LDVR (input)

The leading dimension of the array VR. LDVR \geq 1; and if JOB = 'E' or 'B', LDVR \geq N.

S (output)

If JOB = 'E' or 'B', the reciprocal condition numbers of the selected eigenvalues, stored in consecutive elements of the array. Thus S(j), SEP(j), and the j-th columns of VL and VR all correspond to the same eigenpair (but not in general the j-th eigenpair, unless all eigenpairs are selected). If JOB = 'V', S is not referenced.

SEP (output)

If JOB = 'V' or 'B', the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array. If JOB = 'E', SEP is not referenced.

MM (input)

The number of elements in the arrays S (if JOB = 'E' or 'B') and/or SEP (if JOB = 'V' or 'B'). MM \geq M.

M (output)

The number of elements of the arrays S and/or SEP actually used to store the estimated condition numbers. If HOWMNY = 'A', M is set to N.

WORK (workspace)

dimension(LDWORK,N+1) If JOB = 'E', WORK is not referenced.

LDWORK (input)

The leading dimension of the array WORK. LDWORK \geq 1; and if JOB = 'V' or 'B', LDWORK \geq N.

WORK1 (workspace)

dimension(N) If JOB = 'E', WORK1 is not referenced.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The reciprocal of the condition number of an eigenvalue lambda is defined as

$$S(\text{lambda}) = |\mathbf{v}'\mathbf{u}| / (\text{norm}(\mathbf{u})\text{norm}(\mathbf{v}))$$

where u and v are the right and left eigenvectors of T corresponding to lambda; v' denotes the conjugate transpose of v, and norm(u) denotes the Euclidean norm. These reciprocal condition numbers always lie between zero (very badly conditioned) and one (very well conditioned). If n = 1, S(lambda) is defined to be 1.

An approximate error bound for a computed eigenvalue W(i) is given by

$$\text{EPS} * \text{norm}(\mathbf{T}) / S(i)$$

where EPS is the machine precision.

The reciprocal of the condition number of the right eigenvector u corresponding to lambda is defined as follows. Suppose

$$\mathbf{T} = \begin{pmatrix} \text{lambda} & c \\ 0 & \mathbf{T22} \end{pmatrix}$$

Then the reciprocal condition number is

$$\text{SEP}(\text{lambda}, \mathbf{T22}) = \text{sigma-min}(\mathbf{T22} - \text{lambda}*\mathbf{I})$$

where sigma-min denotes the smallest singular value. We approximate the smallest singular value by the reciprocal of an estimate of the one-norm of the inverse of $\mathbf{T22} - \text{lambda}*\mathbf{I}$. If n = 1, SEP(1) is defined to be abs(T(1,1)).

An approximate error bound for a computed right eigenvector VR(i) is given by

$$\text{EPS} * \text{norm}(\mathbf{T}) / \text{SEP}(i)$$

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NAME

ztrsv - solve one of the systems of equations $Ax = b$, or $A^Hx = b$, or $\text{conjg}(A^H)x = b$

SYNOPSIS

```
SUBROUTINE ZTRSV(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), Y(*)  
INTEGER N, LDA, INCY
```

```
SUBROUTINE ZTRSV_64(UPLO, TRANSA, DIAG, N, A, LDA, Y, INCY)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), Y(*)  
INTEGER*8 N, LDA, INCY
```

F95 INTERFACE

```
SUBROUTINE TRSV(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INCY
```

```
SUBROUTINE TRSV_64(UPLO, [TRANSA], DIAG, [N], A, [LDA], Y, [INCY])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:) :: Y  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INCY
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrsv(char uplo, char transa, char diag, int n, doublecomplex *a, int lda, doublecomplex *y, int incy);
```

```
void ztrsv_64(char uplo, char transa, char diag, long n,
```

```
doublecomplex *a, long lda, doublecomplex *y, long
incy);
```

PURPOSE

ztrsv solves one of the systems of equations $A*x = b$, or $A'*x = b$, or $\text{conjg}(A)*x = b$ where b and x are n element vectors and A is an n by n unit, or non-unit, upper or lower triangular matrix.

No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.

ARGUMENTS

UPLO (input)

On entry, UPLO specifies whether the matrix is an upper or lower triangular matrix as follows:

UPLO = 'U' or 'u' A is an upper triangular matrix.

UPLO = 'L' or 'l' A is a lower triangular matrix.

Unchanged on exit.

TRANSA (input)

On entry, TRANSA specifies the equations to be solved as follows:

TRANSA = 'N' or 'n' $A*x = b$.

TRANSA = 'T' or 't' $A'*x = b$.

TRANSA = 'C' or 'c' $\text{conjg}(A)*x = b$.

Unchanged on exit.

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

On entry, DIAG specifies whether or not A is unit triangular as follows:

DIAG = 'U' or 'u' A is assumed to be unit triangular.

DIAG = 'N' or 'n' A is not assumed to be unit triangular.

Unchanged on exit.

N (input)

On entry, N specifies the order of the matrix A .

N >= 0. Unchanged on exit.

A (input)

Before entry with UPLO = 'U' or 'u', the leading n by n upper triangular part of the array A must contain the upper triangular matrix and the strictly lower triangular part of A is not referenced. Before entry with UPLO = 'L' or 'l', the leading n by n lower triangular part of the array A must contain the lower triangular matrix and the strictly upper triangular part of A is not referenced. Note that when DIAG = 'U' or 'u', the diagonal elements of A are not referenced either, but are assumed to be unity. Unchanged on exit.

LDA (input)

On entry, LDA specifies the first dimension of A as declared in the calling (sub) program. LDA >= max(1, n). Unchanged on exit.

Y (input/output)

(1 + (n - 1) * abs(INCY)). Before entry, the incremented array Y must contain the n element right-hand side vector b. On exit, Y is overwritten with the solution vector x.

INCY (input)

On entry, INCY specifies the increment for the elements of Y. INCY <> 0. Unchanged on exit.

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NAME

ztrsyl - solve the complex Sylvester matrix equation

SYNOPSIS

```
SUBROUTINE ZTRSYL(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C, LDC,
  SCALE, INFO)
```

```
CHARACTER * 1 TRANA, TRANB
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER ISGN, M, N, LDA, LDB, LDC, INFO
DOUBLE PRECISION SCALE
```

```
SUBROUTINE ZTRSYL_64(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C,
  LDC, SCALE, INFO)
```

```
CHARACTER * 1 TRANA, TRANB
DOUBLE COMPLEX A(LDA,*), B(LDB,*), C(LDC,*)
INTEGER*8 ISGN, M, N, LDA, LDB, LDC, INFO
DOUBLE PRECISION SCALE
```

F95 INTERFACE

```
SUBROUTINE TRSYL(TRANA, TRANB, ISGN, [M], [N], A, [LDA], B, [LDB], C,
  [LDC], SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: TRANA, TRANB
COMPLEX(8), DIMENSION(:,*) :: A, B, C
INTEGER :: ISGN, M, N, LDA, LDB, LDC, INFO
REAL(8) :: SCALE
```

```
SUBROUTINE TRSYL_64(TRANA, TRANB, ISGN, [M], [N], A, [LDA], B, [LDB],
  C, [LDC], SCALE, [INFO])
```

```
CHARACTER(LEN=1) :: TRANA, TRANB
COMPLEX(8), DIMENSION(:,*) :: A, B, C
INTEGER(8) :: ISGN, M, N, LDA, LDB, LDC, INFO
REAL(8) :: SCALE
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrsyl(char trana, char tranb, int isgn, int m, int n,
           doublecomplex *a, int lda, doublecomplex *b, int
           ldb, doublecomplex *c, int ldc, double *scale, int
           *info);
```

```
void ztrsyl_64(char trana, char tranb, long isgn, long m,
              long n, doublecomplex *a, long lda, doublecomplex
              *b, long ldb, doublecomplex *c, long ldc, double
              *scale, long *info);
```

PURPOSE

ztrsyl solves the complex Sylvester matrix equation:

$$\begin{aligned} \text{op}(A)*X + X*\text{op}(B) &= \text{scale}*C \text{ or} \\ \text{op}(A)*X - X*\text{op}(B) &= \text{scale}*C, \end{aligned}$$

where $\text{op}(A) = A$ or A^{**H} , and A and B are both upper triangular. A is M -by- M and B is N -by- N ; the right hand side C and the solution X are M -by- N ; and scale is an output scale factor, set ≤ 1 to avoid overflow in X .

ARGUMENTS

TRANA (input)

Specifies the option $\text{op}(A)$:
 = 'N': $\text{op}(A) = A$ (No transpose)
 = 'C': $\text{op}(A) = A^{**H}$ (Conjugate transpose)

TRANB (input)

Specifies the option $\text{op}(B)$:
 = 'N': $\text{op}(B) = B$ (No transpose)
 = 'C': $\text{op}(B) = B^{**H}$ (Conjugate transpose)

ISGN (input)

Specifies the sign in the equation:
 = +1: solve $\text{op}(A)*X + X*\text{op}(B) = \text{scale}*C$
 = -1: solve $\text{op}(A)*X - X*\text{op}(B) = \text{scale}*C$

M (input) The order of the matrix A , and the number of rows in the matrices X and C . $M \geq 0$.

N (input) The order of the matrix B , and the number of columns in the matrices X and C . $N \geq 0$.

A (input) The upper triangular matrix A .

LDA (input)

The leading dimension of the array A . $LDA \geq \max(1, M)$.

B (input) The upper triangular matrix B .

LDB (input)

The leading dimension of the array B . $LDB \geq \max(1, N)$.

C (input/output)

On entry, the M-by-N right hand side matrix C. On exit, C is overwritten by the solution matrix X.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M)

SCALE (output)

The scale factor, scale, set ≤ 1 to avoid overflow in X.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an illegal value

= 1: A and B have common or very close eigenvalues; perturbed values were used to solve the equation (but the matrices A and B are unchanged).

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NAME

ztrti2 - compute the inverse of a complex upper or lower triangular matrix

SYNOPSIS

```
SUBROUTINE ZTRTI2(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE ZTRTI2_64(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE TRTI2(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE TRTI2_64(UPLO, DIAG, [N], A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrti2(char uplo, char diag, int n, doublecomplex *a,  
            int lda, int *info);
```

```
void ztrti2_64(char uplo, char diag, long n, doublecomplex  
               *a, long lda, long *info);
```

PURPOSE

ztrti2 computes the inverse of a complex upper or lower triangular matrix.

This is the Level 2 BLAS version of the algorithm.

ARGUMENTS

UPLO (input)

Specifies whether the matrix A is upper or lower triangular. = 'U': Upper triangular
= 'L': Lower triangular

DIAG (input)

Specifies whether or not the matrix A is unit triangular. = 'N': Non-unit triangular
= 'U': Unit triangular

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular matrix A. If UPLO = 'U', the leading n by n upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading n by n lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

On exit, the (triangular) inverse of the original matrix, in the same storage format.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -k, the k-th argument had an illegal value

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NAME

ztrtri - compute the inverse of a complex upper or lower triangular matrix A

SYNOPSIS

```
SUBROUTINE ZTRTRI(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
DOUBLE COMPLEX A(LDA,*)  
INTEGER N, LDA, INFO
```

```
SUBROUTINE ZTRTRI_64(UPLO, DIAG, N, A, LDA, INFO)
```

```
CHARACTER * 1 UPLO, DIAG  
DOUBLE COMPLEX A(LDA,*)  
INTEGER*8 N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE TRTRI(UPLO, DIAG, N, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, INFO
```

```
SUBROUTINE TRTRI_64(UPLO, DIAG, N, A, [LDA], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO, DIAG  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrtri(char uplo, char diag, int n, doublecomplex *a,  
           int lda, int *info);
```

```
void ztrtri_64(char uplo, char diag, long n, doublecomplex  
              *a, long lda, long *info);
```

PURPOSE

ztrtri computes the inverse of a complex upper or lower triangular matrix A.

This is the Level 3 BLAS version of the algorithm.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
= 'L': A is lower triangular.

DIAG (input)

= 'N': A is non-unit triangular;
= 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

A (input/output)

On entry, the triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1. On exit, the (triangular) inverse of the original matrix, in the same storage format.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, A(i,i) is exactly zero. The triangular matrix is singular and its inverse can not be computed.

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NAME

ztrtrs - solve a triangular system of the form $A * X = B$,
 $A^{**T} * X = B$, or $A^{**H} * X = B$,

SYNOPSIS

```
SUBROUTINE ZTRTRS(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB, INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE ZTRTRS_64(UPLO, TRANSA, DIAG, N, NRHS, A, LDA, B, LDB,  
INFO)
```

```
CHARACTER * 1 UPLO, TRANSA, DIAG  
DOUBLE COMPLEX A(LDA,*), B(LDB,*)  
INTEGER*8 N, NRHS, LDA, LDB, INFO
```

F95 INTERFACE

```
SUBROUTINE TRTRS(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:,:) :: A, B  
INTEGER :: N, NRHS, LDA, LDB, INFO
```

```
SUBROUTINE TRTRS_64(UPLO, [TRANSA], DIAG, [N], [NRHS], A, [LDA], B, [LDB],  
[INFO])
```

```
CHARACTER(LEN=1) :: UPLO, TRANSA, DIAG  
COMPLEX(8), DIMENSION(:,:) :: A, B  
INTEGER(8) :: N, NRHS, LDA, LDB, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztrtrs(char uplo, char transa, char diag, int n, int  
nrhs, doublecomplex *a, int lda, doublecomplex *b,  
int ldb, int *info);
```

```
void ztrtrs_64(char uplo, char transa, char diag, long n,
              long nrhs, doublecomplex *a, long lda, doublecom-
              plex *b, long ldb, long *info);
```

PURPOSE

ztrtrs solves a triangular system of the form
 $A * X = B$, $A^{**T} * X = B$, or $A^{**H} * X = B$

where A is a triangular matrix of order N, and B is an N-by-NRHS matrix. A check is made to verify that A is non-singular.

ARGUMENTS

UPLO (input)

= 'U': A is upper triangular;
 = 'L': A is lower triangular.

TRANSA (input)

Specifies the form of the system of equations:
 = 'N': $A * X = B$ (No transpose)
 = 'T': $A^{**T} * X = B$ (Transpose)
 = 'C': $A^{**H} * X = B$ (Conjugate transpose)

TRANSA is defaulted to 'N' for F95 INTERFACE.

DIAG (input)

= 'N': A is non-unit triangular;
 = 'U': A is unit triangular.

N (input) The order of the matrix A. $N \geq 0$.

NRHS (input)

The number of right hand sides, i.e., the number of columns of the matrix B. $NRHS \geq 0$.

A (input) The triangular matrix A. If UPLO = 'U', the leading N-by-N upper triangular part of the array A contains the upper triangular matrix, and the strictly lower triangular part of A is not referenced. If UPLO = 'L', the leading N-by-N lower triangular part of the array A contains the lower triangular matrix, and the strictly upper triangular part of A is not referenced. If DIAG = 'U', the diagonal elements of A are also not referenced and are assumed to be 1.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, N)$.

B (input/output)

On entry, the right hand side matrix B. On exit, if INFO = 0, the solution matrix X.

LDB (input)

The leading dimension of the array B. LDB \geq
max(1,N).

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value
> 0: if INFO = i, the i-th diagonal element of A is zero, indicating that the matrix is singular and the solutions X have not been computed.

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NAME

ztzrqf - routine is deprecated and has been replaced by routine CTZRZF

SYNOPSIS

```
SUBROUTINE ZTZRQF(M, N, A, LDA, TAU, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*)  
INTEGER M, N, LDA, INFO
```

```
SUBROUTINE ZTZRQF_64(M, N, A, LDA, TAU, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*)  
INTEGER*8 M, N, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE TZRQF([M], [N], A, [LDA], TAU, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, LDA, INFO
```

```
SUBROUTINE TZRQF_64([M], [N], A, [LDA], TAU, [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztzrqf(int m, int n, doublecomplex *a, int lda, doublecomplex *tau, int *info);
```

```
void ztzrqf_64(long m, long n, doublecomplex *a, long lda, doublecomplex *tau, long *info);
```

PURPOSE

ztzrqf routine is deprecated and has been replaced by routine CTZRZF.

CTZRQF reduces the M-by-N ($M \leq N$) complex upper trapezoidal matrix A to upper triangular form by means of unitary transformations.

The upper trapezoidal matrix A is factored as

$$A = \begin{pmatrix} R & 0 \end{pmatrix} * Z,$$

where Z is an N-by-N unitary matrix and R is an M-by-M upper triangular matrix.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq M$.

A (input/output)

On entry, the leading M-by-N upper trapezoidal part of the array A must contain the matrix to be factorized. On exit, the leading M-by-M upper triangular part of A contains the upper triangular matrix R, and elements M+1 to N of the first M rows of A, with the array TAU, represent the unitary matrix Z as a product of M elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

The factorization is obtained by Householder's method. The kth transformation matrix, $Z(k)$, whose conjugate transpose is used to introduce zeros into the $(m - k + 1)$ th row of A, is given in the form

$$Z(k) = \begin{pmatrix} I & 0 \\ 0 & T(k) \end{pmatrix},$$

where

$$T(k) = I - \tau u(k) u(k)', \quad u(k) = \begin{pmatrix} 1 \\ \end{pmatrix},$$

$$\begin{pmatrix} 0 \\ z(k) \end{pmatrix}$$

tau is a scalar and $z(k)$ is an $(n - m)$ element vector. tau and $z(k)$ are chosen to annihilate the elements of the kth row of X.

The scalar tau is returned in the kth element of TAU and the vector $u(k)$ in the kth row of A, such that the elements of $z(k)$ are in $a(k, m + 1), \dots, a(k, n)$. The elements of R are returned in the upper triangular part of A.

Z is given by

$$Z = Z(1) * Z(2) * \dots * Z(m).$$

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NAME

ztzrzf - reduce the M-by-N ($M \leq N$) complex upper trapezoidal matrix A to upper triangular form by means of unitary transformations

SYNOPSIS

```
SUBROUTINE ZTZRF(M, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, LDA, LWORK, INFO
```

```
SUBROUTINE ZTZRF_64(M, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE TZRF([M], [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,*) :: A  
INTEGER :: M, N, LDA, LWORK, INFO
```

```
SUBROUTINE TZRF_64([M], [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,*) :: A  
INTEGER(8) :: M, N, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void ztzrzf(int m, int n, doublecomplex *a, int lda, doublecomplex *tau, int *info);
```

```
void ztzrzf_64(long m, long n, doublecomplex *a, long lda, doublecomplex *tau, long *info);
```

PURPOSE

ztzrzf reduces the M-by-N ($M \leq N$) complex upper trapezoidal matrix A to upper triangular form by means of unitary transformations.

The upper trapezoidal matrix A is factored as

$$A = \begin{pmatrix} R & 0 \end{pmatrix} * Z,$$

where Z is an N-by-N unitary matrix and R is an M-by-M upper triangular matrix.

ARGUMENTS

M (input) The number of rows of the matrix A. $M \geq 0$.

N (input) The number of columns of the matrix A. $N \geq 0$.

A (input/output)

On entry, the leading M-by-N upper trapezoidal part of the array A must contain the matrix to be factorized. On exit, the leading M-by-M upper triangular part of A contains the upper triangular matrix R, and elements M+1 to N of the first M rows of A, with the array TAU, represent the unitary matrix Z as a product of M elementary reflectors.

LDA (input)

The leading dimension of the array A. $LDA \geq \max(1, M)$.

TAU (output)

The scalar factors of the elementary reflectors.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq \max(1, M)$. For optimum performance $LWORK \geq M * NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by

A. Petitot, Computer Science Dept., Univ. of Tenn., Knoxville, USA

The factorization is obtained by Householder's method. The kth transformation matrix, $Z(k)$, which is used to introduce zeros into the $(m - k + 1)$ th row of A, is given in the form

$$Z(k) = \begin{pmatrix} I & 0 \\ 0 & T(k) \end{pmatrix},$$

where

$$T(k) = I - \tau u(k)u(k)', \quad u(k) = \begin{pmatrix} 1 \\ 0 \\ z(k) \end{pmatrix},$$

τ is a scalar and $z(k)$ is an $(n - m)$ element vector. τ and $z(k)$ are chosen to annihilate the elements of the kth row of X.

The scalar τ is returned in the kth element of TAU and the vector $u(k)$ in the kth row of A, such that the elements of $z(k)$ are in $a(k, m + 1), \dots, a(k, n)$. The elements of R are returned in the upper triangular part of A.

Z is given by

$$Z = Z(1) * Z(2) * \dots * Z(m).$$

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NAME

zung2l - generate an m by n complex matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE ZUNG2L(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, INFO
```

```
SUBROUTINE ZUNG2L_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE UNG2L(M, [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, INFO
```

```
SUBROUTINE UNG2L_64(M, [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zung2l(int m, int n, int k, doublecomplex *a, int lda,  
           doublecomplex *tau, int *info);
```

```
void zung2l_64(long m, long n, long k, doublecomplex *a,  
              long lda, doublecomplex *tau, long *info);
```

PURPOSE

zung21 L generates an m by n complex matrix Q with orthonormal columns, which is defined as the last n columns of a product of k elementary reflectors of order m

$$Q = H(k) \dots H(2) H(1)$$

as returned by CGEQLF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.

A (input/output)

On entry, the (n-k+i)-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by CGEQLF in the last k columns of its array argument A. On exit, the m-by-n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGEQLF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

zung2r - generate an m by n complex matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE ZUNG2R(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, INFO
```

```
SUBROUTINE ZUNG2R_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE UNG2R(M, [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, INFO
```

```
SUBROUTINE UNG2R_64(M, [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zung2r(int m, int n, int k, doublecomplex *a, int lda,  
           doublecomplex *tau, int *info);
```

```
void zung2r_64(long m, long n, long k, doublecomplex *a,  
              long lda, doublecomplex *tau, long *info);
```

PURPOSE

zung2r R generates an m by n complex matrix Q with orthonormal columns, which is defined as the first n columns of a product of k elementary reflectors of order m

$$Q = H(1) H(2) \dots H(k)$$

as returned by CGEQRF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.

A (input/output)

On entry, the i-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by CGEQRF in the first k columns of its array argument A. On exit, the m by n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGEQRF.

WORK (workspace)

dimension(N)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

zungbr - generate one of the complex unitary matrices Q or P^*H determined by CGEBRD when reducing a complex matrix A to bidiagonal form

SYNOPSIS

```
SUBROUTINE ZUNGBR(VECT, M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT  
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE ZUNGBR_64(VECT, M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT  
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGBR(VECT, M, [N], K, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: VECT  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE UNGBR_64(VECT, M, [N], K, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
CHARACTER(LEN=1) :: VECT  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zungbr(char vect, int m, int n, int k, doublecomplex  
*a, int lda, doublecomplex *tau, int *info);
```

```

void zungbr_64(char vect, long m, long n, long k, doublecom-
plex *a, long lda, doublecomplex *tau, long
*info);

```

PURPOSE

zungbr generates one of the complex unitary matrices Q or P^{*H} determined by CGEBRD when reducing a complex matrix A to bidiagonal form: $A = Q * B * P^{*H}$. Q and P^{*H} are defined as products of elementary reflectors $H(i)$ or $G(i)$ respectively.

If $VECT = 'Q'$, A is assumed to have been an M -by- K matrix, and Q is of order M :
 if $m \geq k$, $Q = H(1) H(2) \dots H(k)$ and ZUNGBR returns the first n columns of Q , where $m \geq n \geq k$;
 if $m < k$, $Q = H(1) H(2) \dots H(m-1)$ and ZUNGBR returns Q as an M -by- M matrix.

If $VECT = 'P'$, A is assumed to have been a K -by- N matrix, and P^{*H} is of order N :
 if $k < n$, $P^{*H} = G(k) \dots G(2) G(1)$ and ZUNGBR returns the first m rows of P^{*H} , where $n \geq m \geq k$;
 if $k \geq n$, $P^{*H} = G(n-1) \dots G(2) G(1)$ and ZUNGBR returns P^{*H} as an N -by- N matrix.

ARGUMENTS

VECT (input)

Specifies whether the matrix Q or the matrix P^{*H} is required, as defined in the transformation applied by CGEBRD:
 = 'Q': generate Q ;
 = 'P': generate P^{*H} .

M (input) The number of rows of the matrix Q or P^{*H} to be returned. $M \geq 0$.

N (input) The number of columns of the matrix Q or P^{*H} to be returned. $N \geq 0$. If $VECT = 'Q'$, $M \geq N \geq \min(M,K)$; if $VECT = 'P'$, $N \geq M \geq \min(N,K)$.

K (input) If $VECT = 'Q'$, the number of columns in the original M -by- K matrix reduced by CGEBRD. If $VECT = 'P'$, the number of rows in the original K -by- N matrix reduced by CGEBRD. $K \geq 0$.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by CGEBRD. On exit, the M -by- N matrix Q or P^{*H} .

LDA (input)

The leading dimension of the array A . $LDA \geq M$.

TAU (input)

($\min(M,K)$) if VECT = 'Q' ($\min(N,K)$) if VECT = 'P'
TAU(i) must contain the scalar factor of the elementary reflector H(i) or G(i), which determines Q or P**H, as returned by CGEBRD in its array argument TAUQ or TAUP.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq $\max(1, \min(M,N))$. For optimum performance LWORK \geq $\min(M,N)*NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zunghr - generate a complex unitary matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N, as returned by CGEHRD

SYNOPSIS

```
SUBROUTINE ZUNGHR(N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER N, ILO, IHI, LDA, LWORK, INFO
```

```
SUBROUTINE ZUNGHR_64(N, ILO, IHI, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 N, ILO, IHI, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGHR([N], ILO, IHI, A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, ILO, IHI, LDA, LWORK, INFO
```

```
SUBROUTINE UNGHR_64([N], ILO, IHI, A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, ILO, IHI, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunghr(int n, int ilo, int ihi, doublecomplex *a, int  
lda, doublecomplex *tau, int *info);
```

```
void zunghr_64(long n, long ilo, long ihi, doublecomplex *a,  
long lda, doublecomplex *tau, long *info);
```

PURPOSE

zunghr generates a complex unitary matrix Q which is defined as the product of IHI-ILO elementary reflectors of order N, as returned by CGEHRD:

$$Q = H(\text{ilo}) H(\text{ilo}+1) \dots H(\text{ihi}-1).$$

ARGUMENTS

N (input) The order of the matrix Q. $N \geq 0$.

ILO (input)

ILO and IHI must have the same values as in the previous call of CGEHRD. Q is equal to the unit matrix except in the submatrix $Q(\text{ilo}+1:\text{ihi}, \text{ilo}+1:\text{ihi})$. $1 \leq \text{ILO} \leq \text{IHI} \leq N$, if $N > 0$; $\text{ILO}=1$ and $\text{IHI}=0$, if $N=0$.

IHI (input)

See the description of IHI.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by CGEHRD. On exit, the N-by-N unitary matrix Q.

LDA (input)

The leading dimension of the array A. $\text{LDA} \geq \max(1, N)$.

TAU (input)

$\text{TAU}(i)$ must contain the scalar factor of the elementary reflector $H(i)$, as returned by CGEHRD.

WORK (workspace)

On exit, if $\text{INFO} = 0$, $\text{WORK}(1)$ returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $\text{LWORK} \geq \text{IHI}-\text{ILO}$. For optimum performance $\text{LWORK} \geq (\text{IHI}-\text{ILO}) * \text{NB}$, where NB is the optimal blocksize.

If $\text{LWORK} = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if $\text{INFO} = -i$, the i-th argument had an illegal value

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NAME

zungl2 - generate an m-by-n complex matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE ZUNGL2(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, INFO
```

```
SUBROUTINE ZUNGL2_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGL2([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, INFO
```

```
SUBROUTINE UNGL2_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zungl2(int m, int n, int k, doublecomplex *a, int lda,  
           doublecomplex *tau, int *info);
```

```
void zungl2_64(long m, long n, long k, doublecomplex *a,  
             long lda, doublecomplex *tau, long *info);
```

PURPOSE

zungl2 generates an m-by-n complex matrix Q with orthonormal rows, which is defined as the first m rows of a product of k elementary reflectors of order n

$$Q = H(k)' \dots H(2)' H(1)'$$

as returned by CGELQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $M \geq K \geq 0$.

A (input/output)

On entry, the i-th row must contain the vector which defines the elementary reflector $H(i)$, for $i = 1, 2, \dots, k$, as returned by CGELQF in the first k rows of its array argument A. On exit, the m by n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by CGELQF.

WORK (workspace)

dimension(M)

INFO (output)

= 0: successful exit

< 0: if $INFO = -i$, the i-th argument has an illegal value

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NAME

zunglq - generate an M-by-N complex matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE ZUNGLQ(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE ZUNGLQ_64(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGLQ(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE UNGLQ_64(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunglq(int m, int n, int k, doublecomplex *a, int lda,  
doublecomplex *tau, int *info);
```

```
void zunglq_64(long m, long n, long k, doublecomplex *a,  
long lda, doublecomplex *tau, long *info);
```

PURPOSE

zunglq generates an M-by-N complex matrix Q with orthonormal rows, which is defined as the first M rows of a product of K elementary reflectors of order N

$$Q = H(k)' \dots H(2)' H(1)'$$

as returned by CGELQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. M >= 0.

N (input) The number of columns of the matrix Q. N >= M.

K (input) The number of elementary reflectors whose product defines the matrix Q. M >= K >= 0.

A (input/output)

On entry, the i-th row must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGELQF in the first k rows of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. LDA >= max(1,M).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGELQF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK >= max(1,M). For optimum performance LWORK >= M*NB, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit;
< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

zungql - generate an M-by-N complex matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE ZUNGQL(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE ZUNGQL_64(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGQL(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE UNGQL_64(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zungql(int m, int n, int k, doublecomplex *a, int lda,  
doublecomplex *tau, int *info);
```

```
void zungql_64(long m, long n, long k, doublecomplex *a,  
long lda, doublecomplex *tau, long *info);
```

PURPOSE

zungql generates an M-by-N complex matrix Q with orthonormal columns, which is defined as the last N columns of a product of K elementary reflectors of order M

$$Q = H(k) \dots H(2) H(1)$$

as returned by CGEQLF.

ARGUMENTS

- M (input) The number of rows of the matrix Q. $M \geq 0$.
- N (input) The number of columns of the matrix Q. $M \geq N \geq 0$.
- K (input) The number of elementary reflectors whose product defines the matrix Q. $N \geq K \geq 0$.
- A (input/output)
On entry, the (n-k+i)-th column must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by CGEQLF in the last k columns of its array argument A. On exit, the M-by-N matrix Q.
- LDA (input)
The first dimension of the array A. $LDA \geq \max(1, M)$.
- TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGEQLF.
- WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.
- LWORK (input)
The dimension of the array WORK. $LWORK \geq \max(1, N)$. For optimum performance $LWORK \geq N * NB$, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.
- INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

zungqr - generate an M-by-N complex matrix Q with orthonormal columns,

SYNOPSIS

```
SUBROUTINE ZUNGQR(M, N, K, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORKIN(*)  
INTEGER M, N, K, LDA, LWORKIN, INFO
```

```
SUBROUTINE ZUNGQR_64(M, N, K, A, LDA, TAU, WORKIN, LWORKIN, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORKIN(*)  
INTEGER*8 M, N, K, LDA, LWORKIN, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGQR(M, [N], [K], A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORKIN  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, LWORKIN, INFO
```

```
SUBROUTINE UNGQR_64(M, [N], [K], A, [LDA], TAU, [WORKIN], [LWORKIN],  
[INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORKIN  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, LWORKIN, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zungqr(int m, int n, int k, doublecomplex *a, int lda,  
doublecomplex *tau, int *info);
```

```
void zungqr_64(long m, long n, long k, doublecomplex *a,  
long lda, doublecomplex *tau, long *info);
```

PURPOSE

zungqr generates an M-by-N complex matrix Q with orthonormal columns, which is defined as the first N columns of a product of K elementary reflectors of order M

$$Q = H(1) H(2) \dots H(k)$$

as returned by CGEQRF.

ARGUMENTS

M (input) The number of rows of the matrix Q. M \geq 0.

N (input) The number of columns of the matrix Q. M \geq N \geq 0.

K (input) The number of elementary reflectors whose product defines the matrix Q. N \geq K \geq 0.

A (input/output)

On entry, the i-th column must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGEQRF in the first k columns of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. LDA \geq max(1,M).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGEQRF.

WORKIN (workspace)

On exit, if INFO = 0, WORKIN(1) returns the optimal LWORKIN.

LWORKIN (input)

The dimension of the array WORKIN. LWORKIN \geq max(1,N). For optimum performance LWORKIN \geq N*NB, where NB is the optimal blocksize.

If LWORKIN = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORKIN array, returns this value as the first entry of the WORKIN array, and no error message related to LWORKIN is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

zungr2 - generate an m by n complex matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE ZUNGR2(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, INFO
```

```
SUBROUTINE ZUNGR2_64(M, N, K, A, LDA, TAU, WORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGR2([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, INFO
```

```
SUBROUTINE UNGR2_64([M], [N], [K], A, [LDA], TAU, [WORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zungr2(int m, int n, int k, doublecomplex *a, int lda,  
           doublecomplex *tau, int *info);
```

```
void zungr2_64(long m, long n, long k, doublecomplex *a,  
              long lda, doublecomplex *tau, long *info);
```

PURPOSE

zungr2 generates an m by n complex matrix Q with orthonormal rows, which is defined as the last m rows of a product of k elementary reflectors of order n

$$Q = H(1)' H(2)' \dots H(k)'$$

as returned by CGERQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. $M \geq 0$.

N (input) The number of columns of the matrix Q. $N \geq M$.

K (input) The number of elementary reflectors whose product defines the matrix Q. $M \geq K \geq 0$.

A (input/output)

On entry, the (m-k+i)-th row must contain the vector which defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by CGERQF in the last k rows of its array argument A. On exit, the m-by-n matrix Q.

LDA (input)

The first dimension of the array A. $LDA \geq \max(1, M)$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGERQF.

WORK (workspace)

dimension(M)

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

zungrq - generate an M-by-N complex matrix Q with orthonormal rows,

SYNOPSIS

```
SUBROUTINE ZUNGRQ(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE ZUNGRQ_64(M, N, K, A, LDA, TAU, WORK, LWORK, INFO)
```

```
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 M, N, K, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGRQ(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: M, N, K, LDA, LWORK, INFO
```

```
SUBROUTINE UNGRQ_64(M, [N], [K], A, [LDA], TAU, [WORK], [LWORK],  
[INFO])
```

```
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: M, N, K, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zungrq(int m, int n, int k, doublecomplex *a, int lda,  
doublecomplex *tau, int *info);
```

```
void zungrq_64(long m, long n, long k, doublecomplex *a,  
long lda, doublecomplex *tau, long *info);
```

PURPOSE

zungrq generates an M-by-N complex matrix Q with orthonormal rows, which is defined as the last M rows of a product of K elementary reflectors of order N

$$Q = H(1)' H(2)' \dots H(k)'$$

as returned by CGERQF.

ARGUMENTS

M (input) The number of rows of the matrix Q. M \geq 0.

N (input) The number of columns of the matrix Q. N \geq M.

K (input) The number of elementary reflectors whose product defines the matrix Q. M \geq K \geq 0.

A (input/output)

On entry, the (m-k+i)-th row must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGERQF in the last k rows of its array argument A. On exit, the M-by-N matrix Q.

LDA (input)

The first dimension of the array A. LDA \geq max(1,M).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGERQF.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. LWORK \geq max(1,M). For optimum performance LWORK \geq M*NB, where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument has an illegal value

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NAME

zungtr - generate a complex unitary matrix Q which is defined as the product of n-1 elementary reflectors of order N, as returned by CHETRD

SYNOPSIS

```
SUBROUTINE ZUNGTR(UPLO, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER N, LDA, LWORK, INFO
```

```
SUBROUTINE ZUNGTR_64(UPLO, N, A, LDA, TAU, WORK, LWORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX A(LDA,*), TAU(*), WORK(*)  
INTEGER*8 N, LDA, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNGTR(UPLO, [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER :: N, LDA, LWORK, INFO
```

```
SUBROUTINE UNGTR_64(UPLO, [N], A, [LDA], TAU, [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A  
INTEGER(8) :: N, LDA, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zungtr(char uplo, int n, doublecomplex *a, int lda,  
           doublecomplex *tau, int *info);
```

```
void zungtr_64(char uplo, long n, doublecomplex *a, long
```

```
lda, doublecomplex *tau, long *info);
```

PURPOSE

zungtr generates a complex unitary matrix Q which is defined as the product of $n-1$ elementary reflectors of order N , as returned by CHETRD:

if UPLO = 'U', $Q = H(n-1) \dots H(2) H(1)$,

if UPLO = 'L', $Q = H(1) H(2) \dots H(n-1)$.

ARGUMENTS

UPLO (input)

= 'U': Upper triangle of A contains elementary reflectors from CHETRD; = 'L': Lower triangle of A contains elementary reflectors from CHETRD.

N (input) The order of the matrix Q . $N \geq 0$.

A (input/output)

On entry, the vectors which define the elementary reflectors, as returned by CHETRD. On exit, the N -by- N unitary matrix Q .

LDA (input)

The leading dimension of the array A . $LDA \geq N$.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector $H(i)$, as returned by CHETRD.

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. $LWORK \geq N-1$. For optimum performance $LWORK \geq (N-1)*NB$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit

< 0: if INFO = $-i$, the i -th argument had an illegal value

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NAME

zunmbr - VECT = 'Q', ZUNMBR overwrites the general complex M-by-N matrix C with SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE ZUNMBR(VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC,
                  WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT, SIDE, TRANS
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE ZUNMBR_64(VECT, SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC,
                    WORK, LWORK, INFO)
```

```
CHARACTER * 1 VECT, SIDE, TRANS
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMBR(VECT, SIDE, [TRANS], [M], [N], K, A, [LDA], TAU, C,
                [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, SIDE, TRANS
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:, :) :: A, C
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMBR_64(VECT, SIDE, [TRANS], [M], [N], K, A, [LDA], TAU,
                   C, [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: VECT, SIDE, TRANS
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:, :) :: A, C
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunmbr(char vect, char side, char trans, int m, int n,
```

```

int k, doublecomplex *a, int lda, doublecomplex
*tau, doublecomplex *c, int ldc, int *info);

void zunmbr_64(char vect, char side, char trans, long m,
long n, long k, doublecomplex *a, long lda, doublecomplex
*tau, doublecomplex *c, long ldc, long
*info);

```

PURPOSE

zunmbr VECT = 'Q', ZUNMBR overwrites the general complex M-by-N matrix C with

```

                SIDE = 'L'      SIDE = 'R'  TRANS = 'N':
Q * C          C * Q TRANS = 'C':    Q**H * C      C *
Q**H

```

If VECT = 'P', ZUNMBR overwrites the general complex M-by-N matrix C with

```

                SIDE = 'L'      SIDE = 'R'
TRANS = 'N':    P * C          C * P
TRANS = 'C':    P**H * C      C * P**H

```

Here Q and P**H are the unitary matrices determined by CGEBRD when reducing a complex matrix A to bidiagonal form: $A = Q * B * P^{*H}$. Q and P**H are defined as products of elementary reflectors H(i) and G(i) respectively.

Let nq = m if SIDE = 'L' and nq = n if SIDE = 'R'. Thus nq is the order of the unitary matrix Q or P**H that is applied.

If VECT = 'Q', A is assumed to have been an NQ-by-K matrix:
if nq >= k, Q = H(1) H(2) . . . H(k);
if nq < k, Q = H(1) H(2) . . . H(nq-1).

If VECT = 'P', A is assumed to have been a K-by-NQ matrix:
if k < nq, P = G(1) G(2) . . . G(k);
if k >= nq, P = G(1) G(2) . . . G(nq-1).

ARGUMENTS

VECT (input)

```

= 'Q': apply Q or Q**H;
= 'P': apply P or P**H.

```

SIDE (input)

```

= 'L': apply Q, Q**H, P or P**H from the Left;
= 'R': apply Q, Q**H, P or P**H from the Right.

```

TRANS (input)

```

= 'N': No transpose, apply Q or P;
= 'C': Conjugate transpose, apply Q**H or P**H.

```

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) If VECT = 'Q', the number of columns in the original matrix reduced by CGEBRD. If VECT = 'P', the number of rows in the original matrix reduced by CGEBRD. $K \geq 0$.

A (input) (LDA,min(nq,K)) if VECT = 'Q' (LDA,nq) if VECT = 'P' The vectors which define the elementary reflectors H(i) and G(i), whose products determine the matrices Q and P, as returned by CGEBRD.

LDA (input)
The leading dimension of the array A. If VECT = 'Q', $LDA \geq \max(1,nq)$; if VECT = 'P', $LDA \geq \max(1,\min(nq,K))$.

TAU (input)
TAU(i) must contain the scalar factor of the elementary reflector H(i) or G(i) which determines Q or P, as returned by CGEBRD in the array argument TAUQ or TAUP.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**H}C$ or C^*Q^{**H} or C^*Q or P^*C or $P^{**H}C$ or C^*P or C^*P^{**H} .

LDC (input)
The leading dimension of the array C. $LDC \geq \max(1,M)$.

WORK (workspace)
On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. If SIDE = 'L', $LWORK \geq \max(1,N)$; if SIDE = 'R', $LWORK \geq \max(1,M)$. For optimum performance $LWORK \geq N*NB$ if SIDE = 'L', and $LWORK \geq M*NB$ if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zunmhr - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE ZUNMHR(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C, LDC,  
                WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, ILO, IHI, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE ZUNMHR_64(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C,  
                   LDC, WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, ILO, IHI, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMHR(SIDE, [TRANS], [M], [N], ILO, IHI, A, [LDA], TAU, C,  
                [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER :: M, N, ILO, IHI, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMHR_64(SIDE, [TRANS], [M], [N], ILO, IHI, A, [LDA], TAU,  
                   C, [LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER(8) :: M, N, ILO, IHI, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunmhr(char side, char trans, int m, int n, int ilo,
```

```

int ihi, doublecomplex *a, int lda, doublecomplex
*tau, doublecomplex *c, int ldc, int *info);

void zunmhr_64(char side, char trans, long m, long n, long
ilo, long ihi, doublecomplex *a, long lda, doub-
lecomplex *tau, doublecomplex *c, long ldc, long
*info);

```

PURPOSE

zunmhr overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix of order nq, with nq = m
if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
product of IHI-ILO elementary reflectors, as returned by
CGEHRD:

$Q = H(i\text{lo}) H(i\text{lo}+1) \dots H(i\text{hi}-1).$

ARGUMENTS

SIDE (input)
= 'L': apply Q or Q**H from the Left;
= 'R': apply Q or Q**H from the Right.

TRANS (input)
= 'N': apply Q (No transpose)
= 'C': apply Q**H (Conjugate transpose)

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

ILO (input)
ILO and IHI must have the same values as in the
previous call of CGEHRD. Q is equal to the unit
matrix except in the submatrix
Q(i\text{lo}+1:i\text{hi},i\text{lo}+1:i\text{hi}). If SIDE = 'L', then $1 \leq$
 $ILO \leq IHI \leq M$, if $M > 0$, and $ILO = 1$ and $IHI =$
 0 , if $M = 0$; if SIDE = 'R', then $1 \leq ILO \leq IHI$
 $\leq N$, if $N > 0$, and $ILO = 1$ and $IHI = 0$, if $N = 0$.

IHI (input)
See the description of ILO.

A (input) (LDA,M) if SIDE = 'L' (LDA,N) if SIDE = 'R' The
vectors which define the elementary reflectors, as
returned by CGEHRD.

LDA (input)
The leading dimension of the array A. LDA >=
 $\max(1,M)$ if SIDE = 'L'; LDA >= $\max(1,N)$ if SIDE =
'R'.

TAU (input)
 (M-1) if SIDE = 'L' (N-1) if SIDE = 'R' TAU(i)
 must contain the scalar factor of the elementary
 reflector H(i), as returned by CGEHRD.

C (input/output)
 On entry, the M-by-N matrix C. On exit, C is
 overwritten by Q*C or Q**H*C or C*Q**H or C*Q.

LDC (input)
 The leading dimension of the array C. LDC >=
 max(1,M).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal
 LWORK.

LWORK (input)
 The dimension of the array WORK. If SIDE = 'L',
 LWORK >= max(1,N); if SIDE = 'R', LWORK >=
 max(1,M). For optimum performance LWORK >= N*NB
 if SIDE = 'L', and LWORK >= M*NB if SIDE = 'R',
 where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed;
 the routine only calculates the optimal size of
 the WORK array, returns this value as the first
 entry of the WORK array, and no error message
 related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an ille-
 gal value

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NAME

zunml2 - overwrite the general complex m-by-n matrix C with $Q * C$ if SIDE = 'L' and TRANS = 'N', or $Q' * C$ if SIDE = 'L' and TRANS = 'C', or $C * Q$ if SIDE = 'R' and TRANS = 'N', or $C * Q'$ if SIDE = 'R' and TRANS = 'C',

SYNOPSIS

```
SUBROUTINE ZUNML2(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
                 INFO)
```

```
CHARACTER * 1 SIDE, TRANS
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER M, N, K, LDA, LDC, INFO
```

```
SUBROUTINE ZUNML2_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
                    INFO)
```

```
CHARACTER * 1 SIDE, TRANS
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER*8 M, N, K, LDA, LDC, INFO
```

F95 INTERFACE

```
SUBROUTINE UNML2(SIDE, TRANS, [M], [N], [K], A, [LDA], TAU, C, [LDC],
                [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:,:) :: A, C
INTEGER :: M, N, K, LDA, LDC, INFO
```

```
SUBROUTINE UNML2_64(SIDE, TRANS, [M], [N], [K], A, [LDA], TAU, C,
                   [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:,:) :: A, C
INTEGER(8) :: M, N, K, LDA, LDC, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunml2(char side, char trans, int m, int n, int k,
            doublecomplex *a, int lda, doublecomplex *tau,
            doublecomplex *c, int ldc, int *info);
```

```
void zunml2_64(char side, char trans, long m, long n, long
               k, doublecomplex *a, long lda, doublecomplex *tau,
               doublecomplex *c, long ldc, long *info);
```

PURPOSE

zunml2 overwrites the general complex m-by-n matrix C with

where Q is a complex unitary matrix defined as the product of k elementary reflectors

$$Q = H(k)' \dots H(2)' H(1)'$$

as returned by CGELQF. Q is of order m if SIDE = 'L' and of order n if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q' from the Left
 = 'R': apply Q or Q' from the Right

TRANS (input)

= 'N': apply Q (No transpose)
 = 'C': apply Q' (Conjugate transpose)

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product defines the matrix Q. If SIDE = 'L', M >= K >= 0; if SIDE = 'R', N >= K >= 0.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The i-th row must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGELQF in the first k rows of its array argument A. A is modified by the routine but restored on exit.

LDA (input)

The leading dimension of the array A. LDA >= max(1,K).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGELQF.

C (input/output)

On entry, the m-by-n matrix C. On exit, C is

overwritten by Q*C or Q'*C or C*Q' or C*Q.

LDC (input)

The leading dimension of the array C. LDC \geq
max(1,M).

WORK (workspace)

(N) if SIDE = 'L', (M) if SIDE = 'R'

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

zunmlq - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE ZUNMLQ(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE ZUNMLQ_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMLQ(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMLQ_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunmlq(char side, char trans, int m, int n, int k,
```

```

doublecomplex *a, int lda, doublecomplex *tau,
doublecomplex *c, int ldc, int *info);

void zunmlq_64(char side, char trans, long m, long n, long
k, doublecomplex *a, long lda, doublecomplex *tau,
doublecomplex *c, long ldc, long *info);

```

PURPOSE

zunmlq overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C$ $C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
of k elementary reflectors

$$Q = H(k)' \dots H(2)' H(1)'$$

as returned by CGELQF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
= 'R': apply Q or Q^{*H} from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Conjugate transpose, apply Q^{*H} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
if SIDE = 'R', $N \geq K \geq 0$.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
i-th row must contain the vector which defines the
elementary reflector H(i), for $i = 1, 2, \dots, k$, as
returned by CGELQF in the first k rows of its
array argument A. A is modified by the routine
but restored on exit.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $\max(1, K)$.

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by CGELQF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**H}*C$ or $C*Q^{**H}$ or $C*Q$.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zunmql - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE ZUNMQL(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE ZUNMQL_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMQL(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMQL_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunmql(char side, char trans, int m, int n, int k,
```

```

doublecomplex *a, int lda, doublecomplex *tau,
doublecomplex *c, int ldc, int *info);

void zunmql_64(char side, char trans, long m, long n, long
k, doublecomplex *a, long lda, doublecomplex *tau,
doublecomplex *c, long ldc, long *info);

```

PURPOSE

zunmql overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
of k elementary reflectors

$$Q = H(k) \dots H(2) H(1)$$

as returned by CGEQLF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**H from the Left;
= 'R': apply Q or Q**H from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Transpose, apply Q**H.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', M >= K >= 0;
if SIDE = 'R', N >= K >= 0.

A (input) The i-th column must contain the vector which
defines the elementary reflector H(i), for i =
1,2,...,k, as returned by CGEQLF in the last k
columns of its array argument A. A is modified by
the routine but restored on exit.

LDA (input)

The leading dimension of the array A. If SIDE =
'L', LDA >= max(1,M); if SIDE = 'R', LDA >=
max(1,N).

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by CGEQLF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**H}*C$ or $C*Q^{**H}$ or $C*Q$.

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zunmqr - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE ZUNMQR(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE ZUNMQR_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMQR(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMQR_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunmqr(char side, char trans, int m, int n, int k,
```

```

doublecomplex *a, int lda, doublecomplex *tau,
doublecomplex *c, int ldc, int *info);

void zunmqr_64(char side, char trans, long m, long n, long
k, doublecomplex *a, long lda, doublecomplex *tau,
doublecomplex *c, long ldc, long *info);

```

PURPOSE

zunmqr overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
of k elementary reflectors

$$Q = H(1) H(2) \dots H(k)$$

as returned by CGEQRF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
= 'R': apply Q or Q^{*H} from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Conjugate transpose, apply Q^{*H} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
if SIDE = 'R', $N \geq K \geq 0$.

A (input) The i-th column must contain the vector which
defines the elementary reflector H(i), for $i = 1, 2, \dots, k$, as returned by CGEQRF in the first k
columns of its array argument A. A is modified by
the routine but restored on exit.

LDA (input)

The leading dimension of the array A. If SIDE =
'L', $LDA \geq \max(1, M)$; if SIDE = 'R', $LDA \geq$
 $\max(1, N)$.

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by CGEQRF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**H}C$ or C^*Q^{**H} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zunmr2 - overwrite the general complex m-by-n matrix C with $Q * C$ if SIDE = 'L' and TRANS = 'N', or $Q' * C$ if SIDE = 'L' and TRANS = 'C', or $C * Q$ if SIDE = 'R' and TRANS = 'N', or $C * Q'$ if SIDE = 'R' and TRANS = 'C',

SYNOPSIS

```
SUBROUTINE ZUNMR2(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
                 INFO)
```

```
CHARACTER * 1 SIDE, TRANS
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER M, N, K, LDA, LDC, INFO
```

```
SUBROUTINE ZUNMR2_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,
                    INFO)
```

```
CHARACTER * 1 SIDE, TRANS
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)
INTEGER*8 M, N, K, LDA, LDC, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMR2(SIDE, TRANS, [M], [N], [K], A, [LDA], TAU, C, [LDC],
                [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:,:) :: A, C
INTEGER :: M, N, K, LDA, LDC, INFO
```

```
SUBROUTINE UNMR2_64(SIDE, TRANS, [M], [N], [K], A, [LDA], TAU, C,
                   [LDC], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS
COMPLEX(8), DIMENSION(:) :: TAU, WORK
COMPLEX(8), DIMENSION(:,:) :: A, C
INTEGER(8) :: M, N, K, LDA, LDC, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunmr2(char side, char trans, int m, int n, int k,
            doublecomplex *a, int lda, doublecomplex *tau,
            doublecomplex *c, int ldc, int *info);
```

```
void zunmr2_64(char side, char trans, long m, long n, long
               k, doublecomplex *a, long lda, doublecomplex *tau,
               doublecomplex *c, long ldc, long *info);
```

PURPOSE

zunmr2 overwrites the general complex m-by-n matrix C with

where Q is a complex unitary matrix defined as the product of k elementary reflectors

$$Q = H(1)' H(2)' \dots H(k)'$$

as returned by CGERQF. Q is of order m if SIDE = 'L' and of order n if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q' from the Left
 = 'R': apply Q or Q' from the Right

TRANS (input)

= 'N': apply Q (No transpose)
 = 'C': apply Q' (Conjugate transpose)

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

K (input) The number of elementary reflectors whose product defines the matrix Q. If SIDE = 'L', M >= K >= 0; if SIDE = 'R', N >= K >= 0.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The i-th row must contain the vector which defines the elementary reflector H(i), for i = 1,2,...,k, as returned by CGERQF in the last k rows of its array argument A. A is modified by the routine but restored on exit.

LDA (input)

The leading dimension of the array A. LDA >= max(1,K).

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CGERQF.

C (input/output)

On entry, the m-by-n matrix C. On exit, C is

overwritten by Q*C or Q'*C or C*Q' or C*Q.

LDC (input)

The leading dimension of the array C. LDC \geq
max(1,M).

WORK (workspace)

(N) if SIDE = 'L', (M) if SIDE = 'R'

INFO (output)

= 0: successful exit

< 0: if INFO = -i, the i-th argument had an ille-
gal value

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NAME

zunmrq - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE ZUNMRQ(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE ZUNMRQ_64(SIDE, TRANS, M, N, K, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMRQ(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C, [LDC],  
[WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER :: M, N, K, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMRQ_64(SIDE, [TRANS], [M], [N], [K], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER(8) :: M, N, K, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunmrq(char side, char trans, int m, int n, int k,
```

```

doublecomplex *a, int lda, doublecomplex *tau,
doublecomplex *c, int ldc, int *info);

void zunmrq_64(char side, char trans, long m, long n, long
k, doublecomplex *a, long lda, doublecomplex *tau,
doublecomplex *c, long ldc, long *info);

```

PURPOSE

zunmrq overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C$ $C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
of k elementary reflectors

$$Q = H(1)' H(2)' \dots H(k)'$$

as returned by CGERQF. Q is of order M if SIDE = 'L' and of
order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
= 'R': apply Q or Q^{*H} from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Transpose, apply Q^{*H} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
if SIDE = 'R', $N \geq K \geq 0$.

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
i-th row must contain the vector which defines the
elementary reflector H(i), for $i = 1, 2, \dots, k$, as
returned by CGERQF in the last k rows of its array
argument A. A is modified by the routine but
restored on exit.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $\max(1, K)$.

TAU (input)

TAU(i) must contain the scalar factor of the ele-
mentary reflector H(i), as returned by CGERQF.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or $Q^{**H}C$ or C^*Q^{**H} or C^*Q .

LDC (input)

The leading dimension of the array C. LDC \geq max(1,M).

WORK (workspace)

On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)

The dimension of the array WORK. If SIDE = 'L', LWORK \geq max(1,N); if SIDE = 'R', LWORK \geq max(1,M). For optimum performance LWORK \geq N*NB if SIDE = 'L', and LWORK \geq M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zunmrz - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE ZUNMRZ(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, K, L, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE ZUNMRZ_64(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, K, L, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE ZUNMRZ(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A, C  
INTEGER :: M, N, K, L, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE ZUNMRZ_64(SIDE, TRANS, M, N, K, L, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER(LEN=1) :: SIDE, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: A, C  
INTEGER(8) :: M, N, K, L, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunmrz(char side, char trans, int m, int n, int k, int
            l, doublecomplex *a, int lda, doublecomplex *tau,
            doublecomplex *c, int ldc, int *info);
```

```
void zunmrz_64(char side, char trans, long m, long n, long
               k, long l, doublecomplex *a, long lda, doublecom-
               plex *tau, doublecomplex *c, long ldc, long
               *info);
```

PURPOSE

zunmrz overwrites the general complex M-by-N matrix C with
 TRANS = 'C': $Q^{*H} * C$ $C * Q^{*H}$

where Q is a complex unitary matrix defined as the product
 of k elementary reflectors

$$Q = H(1) H(2) \dots H(k)$$

as returned by CTZRZF. Q is of order M if SIDE = 'L' and of
 order N if SIDE = 'R'.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
 = 'R': apply Q or Q^{*H} from the Right.

TRANS (input)

= 'N': No transpose, apply Q;
 = 'C': Conjugate transpose, apply Q^{*H} .

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

K (input) The number of elementary reflectors whose product
 defines the matrix Q. If SIDE = 'L', $M \geq K \geq 0$;
 if SIDE = 'R', $N \geq K \geq 0$.

L (input) The number of columns of the matrix A containing
 the meaningful part of the Householder reflectors.
 If SIDE = 'L', $M \geq L \geq 0$, if SIDE = 'R', $N \geq L$
 ≥ 0 .

A (input) (LDA,M) if SIDE = 'L', (LDA,N) if SIDE = 'R' The
 i-th row must contain the vector which defines the
 elementary reflector H(i), for $i = 1, 2, \dots, k$, as
 returned by CTZRZF in the last k rows of its array
 argument A. A is modified by the routine but
 restored on exit.

LDA (input)

The leading dimension of the array A. $LDA \geq$
 $\max(1, K)$.

TAU (input)
 TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CTZRZF.

C (input/output)
 On entry, the M-by-N matrix C. On exit, C is overwritten by Q*C or Q**H*C or C*Q**H or C*Q.

LDC (input)
 The leading dimension of the array C. LDC >= max(1,M).

WORK (workspace)
 On exit, if INFO = 0, WORK(1) returns the optimal LWORK.

LWORK (input)
 The dimension of the array WORK. If SIDE = 'L', LWORK >= max(1,N); if SIDE = 'R', LWORK >= max(1,M). For optimum performance LWORK >= N*NB if SIDE = 'L', and LWORK >= M*NB if SIDE = 'R', where NB is the optimal blocksize.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
 = 0: successful exit
 < 0: if INFO = -i, the i-th argument had an illegal value

FURTHER DETAILS

Based on contributions by

A. Petitet, Computer Science Dept., Univ. of Tenn., Knoxville, USA

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NAME

zunmtr - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE ZUNMTR(SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC, WORK,  
LWORK, INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE ZUNMTR_64(SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC,  
WORK, LWORK, INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
DOUBLE COMPLEX A(LDA,*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, LDA, LDC, LWORK, INFO
```

F95 INTERFACE

```
SUBROUTINE UNMTR(SIDE, UPLO, [TRANS], [M], [N], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER :: M, N, LDA, LDC, LWORK, INFO
```

```
SUBROUTINE UNMTR_64(SIDE, UPLO, [TRANS], [M], [N], A, [LDA], TAU, C,  
[LDC], [WORK], [LWORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
COMPLEX(8), DIMENSION(:) :: TAU, WORK  
COMPLEX(8), DIMENSION(:,:) :: A, C  
INTEGER(8) :: M, N, LDA, LDC, LWORK, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zunmtr(char side, char uplo, char trans, int m, int n,
```

```

doublecomplex *a, int lda, doublecomplex *tau,
doublecomplex *c, int ldc, int *info);

void zunmtr_64(char side, char uplo, char trans, long m,
long n, doublecomplex *a, long lda, doublecomplex
*tau, doublecomplex *c, long ldc, long *info);

```

PURPOSE

zunmtr overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix of order nq, with nq = m
if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
product of nq-1 elementary reflectors, as returned by
CHETRD:

if UPLO = 'U', Q = H(nq-1) . . . H(2) H(1);

if UPLO = 'L', Q = H(1) H(2) . . . H(nq-1).

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q**H from the Left;
= 'R': apply Q or Q**H from the Right.

UPLO (input)

= 'U': Upper triangle of A contains elementary
reflectors from CHETRD; = 'L': Lower triangle of A
contains elementary reflectors from CHETRD.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Conjugate transpose, apply Q**H.

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. M >= 0.

N (input) The number of columns of the matrix C. N >= 0.

A (input) (LDA,M) if SIDE = 'L' (LDA,N) if SIDE = 'R' The
vectors which define the elementary reflectors, as
returned by CHETRD.

LDA (input)

The leading dimension of the array A. LDA >=
max(1,M) if SIDE = 'L'; LDA >= max(1,N) if SIDE =
'R'.

TAU (input)

(M-1) if SIDE = 'L' (N-1) if SIDE = 'R' TAU(i)
must contain the scalar factor of the elementary
reflector H(i), as returned by CHETRD.

C (input/output)
On entry, the M-by-N matrix C. On exit, C is overwritten by Q^*C or Q^*H^*C or C^*Q^*H or C^*Q .

LDC (input)
The leading dimension of the array C. $LDC \geq \max(1, M)$.

WORK (workspace)
On exit, if $INFO = 0$, $WORK(1)$ returns the optimal LWORK.

LWORK (input)
The dimension of the array WORK. If $SIDE = 'L'$, $LWORK \geq \max(1, N)$; if $SIDE = 'R'$, $LWORK \geq \max(1, M)$. For optimum performance $LWORK \geq N * NB$ if $SIDE = 'L'$, and $LWORK \geq M * NB$ if $SIDE = 'R'$, where NB is the optimal blocksize.

If $LWORK = -1$, then a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

INFO (output)
= 0: successful exit
< 0: if $INFO = -i$, the i-th argument had an illegal value

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NAME

zupgtr - generate a complex unitary matrix Q which is defined as the product of n-1 elementary reflectors H(i) of order n, as returned by CHPTRD using packed storage

SYNOPSIS

```
SUBROUTINE ZUPGTR(UPLO, N, AP, TAU, Q, LDQ, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), TAU(*), Q(LDQ,*), WORK(*)  
INTEGER N, LDQ, INFO
```

```
SUBROUTINE ZUPGTR_64(UPLO, N, AP, TAU, Q, LDQ, WORK, INFO)
```

```
CHARACTER * 1 UPLO  
DOUBLE COMPLEX AP(*), TAU(*), Q(LDQ,*), WORK(*)  
INTEGER*8 N, LDQ, INFO
```

F95 INTERFACE

```
SUBROUTINE UPGTR(UPLO, [N], AP, TAU, Q, [LDQ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP, TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: Q  
INTEGER :: N, LDQ, INFO
```

```
SUBROUTINE UPGTR_64(UPLO, [N], AP, TAU, Q, [LDQ], [WORK], [INFO])
```

```
CHARACTER(LEN=1) :: UPLO  
COMPLEX(8), DIMENSION(:) :: AP, TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: Q  
INTEGER(8) :: N, LDQ, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zupgtr(char uplo, int n, doublecomplex *ap, doublecom-  
plex *tau, doublecomplex *q, int ldq, int *info);
```

```
void zupgtr_64(char uplo, long n, doublecomplex *ap, doub-
```

```
lecomplex *tau, doublecomplex *q, long ldq, long
*info);
```

PURPOSE

zupgtr generates a complex unitary matrix Q which is defined as the product of n-1 elementary reflectors H(i) of order n, as returned by CHPTRD using packed storage:

```
if UPLO = 'U', Q = H(n-1) . . . H(2) H(1),
```

```
if UPLO = 'L', Q = H(1) H(2) . . . H(n-1).
```

ARGUMENTS

UPLO (input)

= 'U': Upper triangular packed storage used in previous call to CHPTRD; = 'L': Lower triangular packed storage used in previous call to CHPTRD.

N (input) The order of the matrix Q. N >= 0.

AP (input)

The vectors which define the elementary reflectors, as returned by CHPTRD.

TAU (input)

TAU(i) must contain the scalar factor of the elementary reflector H(i), as returned by CHPTRD.

Q (output)

The N-by-N unitary matrix Q.

LDQ (input)

The leading dimension of the array Q. LDQ >= max(1,N).

WORK (workspace)

dimension(N-1)

INFO (output)

= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zupmtr - overwrite the general complex M-by-N matrix C with
SIDE = 'L' SIDE = 'R' TRANS = 'N'

SYNOPSIS

```
SUBROUTINE ZUPMTR(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,  
INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
DOUBLE COMPLEX AP(*), TAU(*), C(LDC,*), WORK(*)  
INTEGER M, N, LDC, INFO
```

```
SUBROUTINE ZUPMTR_64(SIDE, UPLO, TRANS, M, N, AP, TAU, C, LDC, WORK,  
INFO)
```

```
CHARACTER * 1 SIDE, UPLO, TRANS  
DOUBLE COMPLEX AP(*), TAU(*), C(LDC,*), WORK(*)  
INTEGER*8 M, N, LDC, INFO
```

F95 INTERFACE

```
SUBROUTINE UPMTR(SIDE, UPLO, [TRANS], [M], [N], AP, TAU, C, [LDC],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
COMPLEX(8), DIMENSION(:) :: AP, TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: C  
INTEGER :: M, N, LDC, INFO
```

```
SUBROUTINE UPMTR_64(SIDE, UPLO, [TRANS], [M], [N], AP, TAU, C, [LDC],  
[WORK], [INFO])
```

```
CHARACTER(LEN=1) :: SIDE, UPLO, TRANS  
COMPLEX(8), DIMENSION(:) :: AP, TAU, WORK  
COMPLEX(8), DIMENSION(:, :) :: C  
INTEGER(8) :: M, N, LDC, INFO
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zupmtr(char side, char uplo, char trans, int m, int n,
```

```

doublecomplex *ap, doublecomplex *tau, doublecom-
plex *c, int ldc, int *info);

void zupmtr_64(char side, char uplo, char trans, long m,
long n, doublecomplex *ap, doublecomplex *tau,
doublecomplex *c, long ldc, long *info);

```

PURPOSE

zupmtr overwrites the general complex M-by-N matrix C with
TRANS = 'C': $Q^{*H} * C \quad C * Q^{*H}$

where Q is a complex unitary matrix of order nq, with nq = m
if SIDE = 'L' and nq = n if SIDE = 'R'. Q is defined as the
product of nq-1 elementary reflectors, as returned by CHPTRD
using packed storage:

if UPLO = 'U', $Q = H(nq-1) \dots H(2) H(1)$;

if UPLO = 'L', $Q = H(1) H(2) \dots H(nq-1)$.

ARGUMENTS

SIDE (input)

= 'L': apply Q or Q^{*H} from the Left;
= 'R': apply Q or Q^{*H} from the Right.

UPLO (input)

= 'U': Upper triangular packed storage used in
previous call to CHPTRD; = 'L': Lower triangular
packed storage used in previous call to CHPTRD.

TRANS (input)

= 'N': No transpose, apply Q;
= 'C': Conjugate transpose, apply Q^{*H} .

TRANS is defaulted to 'N' for F95 INTERFACE.

M (input) The number of rows of the matrix C. $M \geq 0$.

N (input) The number of columns of the matrix C. $N \geq 0$.

AP (input)

$(M*(M+1)/2)$ if SIDE = 'L' $(N*(N+1)/2)$ if SIDE =
'R' The vectors which define the elementary
reflectors, as returned by CHPTRD. AP is modified
by the routine but restored on exit.

TAU (input)

or (N-1) if SIDE = 'R' TAU(i) must contain the
scalar factor of the elementary reflector H(i), as
returned by CHPTRD.

C (input/output)

On entry, the M-by-N matrix C. On exit, C is
overwritten by $Q*C$ or $Q^{*H}*C$ or $C*Q^{*H}$ or $C*Q$.

LDC (input)
The leading dimension of the array C. LDC \geq
max(1,M).

WORK (workspace)
(N) if SIDE = 'L' (M) if SIDE = 'R'

INFO (output)
= 0: successful exit
< 0: if INFO = -i, the i-th argument had an illegal value

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NAME

zvrmm - variable block sparse row format matrix-matrix multiply

SYNOPSIS

```
SUBROUTINE ZVRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*              VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*              B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER       TRANSA, MB, N, KB, DESCRA(5), LDB, LDC, LWORK  
INTEGER       INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(KB+1),  
*              BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZVRMM_64( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*              VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*              B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8     TRANSA, MB, N, KB, DESCRA(5), LDB, LDC, LWORK  
INTEGER*8     INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(KB+1),  
*              BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE VBRMM(TRANSA, MB, [N], KB, ALPHA, DESCRA,  
*              VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*              B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER       TRANSA, MB, KB  
INTEGER, DIMENSION(:) :: DESCRA, INDX, BINDX  
INTEGER, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE VBRMM_64(TRANSA, MB, [N], KB, ALPHA, DESCRA,  
*              VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
*              B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8     TRANSA, MB, KB
```

```

INTEGER*8, DIMENSION(:) :: DESCRA, INDX, BINDX
INTEGER*8, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: VAL
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```

#include <sunperf.h>
void zvbrmm (int transa, int mb, int n, int kb,
doublecomplex *alpha, int *descra, doublecomplex *val, int
*indx, int *bindx, int *rpntr, int *cpntr, int *bpntrb, int
*bpntre, doublecomplex *b, int ldb, doublecomplex *beta,
doublecomplex *c, int ldc);

void zvbrmm_64 (long transa, long mb, long n, long kb,
doublecomplex *alpha, long *descra, doublecomplex *val,
long *indx, long *bindx, long *rpntr, long *cpntr, long
*bpntrb, long *bpntre, doublecomplex *b, long ldb,
doublecomplex *beta, doublecomplex *c, long ldc);

```

DESCRIPTION

zvbrmm performs one of the matrix-matrix operations

$$C \leftarrow \alpha \operatorname{op}(A) B + \beta C$$

where alpha and beta are scalars, C and B are dense matrices, A is a sparse M by K matrix represented in the variable block sparse row format and op(A) is one of

op(A) = A or op(A) = A' or op(A) = conjg(A').
(' indicates matrix transpose)

The number of rows in A and the number of columns in A are determined as follows

$$M = \text{RPNTR}(\text{MB}+1) - \text{RPNTR}(1), \quad K = \text{CPNTR}(\text{KB}+1) - \text{CPNTR}(1).$$

ARGUMENTS

TRANSA(input) TRANSA specifies the form of op(A) to be used in the matrix multiplication as follows:
0 : operate with matrix
1 : operate with transpose matrix
2 : operate with the conjugate transpose of matrix.
2 is equivalent to 1 if matrix is real.
Unchanged on exit.

MB(input) On entry, integer MB specifies the number of block rows in the matrix A. Unchanged on exit.

N(input) On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.

KB(input) On entry, integer KB specifies the number of block columns in the matrix A. Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha. Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:
DESCRA(1) matrix structure
0 : general
1 : symmetric (A=A')
2 : Hermitian (A= CONJG(A'))
3 : Triangular
4 : Skew(Anti)-Symmetric (A=-A')
5 : Diagonal
6 : Skew-Hermitian (A= -CONJG(A'))
DESCRA(2) upper/lower triangular indicator
1 : lower
2 : upper
DESCRA(3) main block diagonal type
0 : non-unit
1 : unit
DESCRA(4) Array base (NOT IMPLEMENTED)
0 : C/C++ compatible
1 : Fortran compatible
DESCRA(5) repeated indices? (NOT IMPLEMENTED)
0 : unknown
1 : no repeated indices

VAL(input) On entry, scalar array VAL of length NNZ consists of the block entries of A where each block entry is a dense rectangular matrix stored column by column where NNZ denotes the total number of point entries in all nonzero block entries of a matrix A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length BNNZ+1 where BNNZ is the number of block entries of the matrix A such that the I-th element of INDX[] points to the location in VAL of the (1,1) element of the I-th block entry. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ is the number block entries of the matrix A. Unchanged on exit.

RPNTR(input) On entry, RPNTR is an integer array of length MB+1 such that RPNTR(I)-RPNTR(1)+1 is the row index of the first point row in the I-th block row. RPNTR(MB+1) is set to M+RPNTR(1) where M is the number of rows in the matrix A. Thus, the number of point rows in the I-th block row is RPNTR(I+1)-RPNTR(I). Unchanged on exit.

CPNTR(input) On entry, CPNTR is an integer array of length KB+1 such that CPNTR(J)-CPNTR(1)+1 is the column index of the first point column in the J-th block column. CPNTR(KB+1) is set to K+CPNTR(1) where K is the number of columns in the matrix A. Thus, the number of point columns in the J-th block column is CPNTR(J+1)-CPNTR(J). Unchanged on exit.

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(I)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the I-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(I)-BPNTRB(1)points to location in BINDX of the last block entry of the I-th block row of A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N).
 Before entry with TRANSA = 0, the leading k by n
 part of the array B must contain the matrix B, otherwise
 the leading m by n part of the array B must contain the
 matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared
 in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N).
 Before entry with TRANSA = 0, the leading m by n
 part of the array C must contain the matrix C, otherwise
 the leading k by n part of the array C must contain the
 matrix C. On exit, the array C is overwritten by the matrix
 (alpha*op(A) * B + beta*C).

LDC (input) On entry, LDC specifies the first dimension of C as declared
 in the calling (sub) program. Unchanged on exit.

WORK (is not referenced in the current version)

LWORK (is not referenced in the current version)

SEE ALSO

Libsunperf SPARSE BLAS is fully parallel and compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

The routine is designed so that it provides a possibility to use just one sparse matrix representation of a general matrix A for computing matrix-matrix multiply for another sparse matrix composed by block triangles and/or the main block diagonal of A. The full description of the feature for block entry formats is given in section NOTES/BUGS for the cbcomm manpage.

NOTES/BUGS

1. For a general matrix (*DESCRA*(1)=0), array CPNTR can be different from RPNTR. For all other matrix types, RPNTR must equal CPNTR and a single array can be passed for both arguments.

2.It is known that there exists another representation of the variable block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of six array instead of the seven used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the array BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of variable block sparse row format the following calling sequence should be used

```
      SUBROUTINE ZVBRMM( TRANSA, MB, N, KB, ALPHA, DESCRA,  
*                      VAL, INDX, BINDX, RPNTR, CPNTR, IA, IA(2),  
*                      B, LDB, BETA, C, LDC, WORK, LWORK )
```

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NAME

zvbrsm - variable block sparse row format triangular solve

SYNOPSIS

```
SUBROUTINE ZVBRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER TRANSA, MB, N, UNITD, DESCRA(5), LDB, LDC, LWORK  
INTEGER INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(MB+1),  
* BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX DV(*), VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

```
SUBROUTINE ZVBRSM_64( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
* B, LDB, BETA, C, LDC, WORK, LWORK)  
INTEGER*8 TRANSA, MB, N, UNITD, DESCRA(5), LDB, LDC, LWORK  
INTEGER*8 INDX(*), BINDX(*), RPNTR(MB+1), CPNTR(MB+1),  
* BPNTRB(MB), BPNTRE(MB)  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX DV(*), VAL(*), B(LDB,*), C(LDC,*), WORK(LWORK)
```

F95 INTERFACE

```
SUBROUTINE VBRSM(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
* B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER TRANSA, MB, UNITD  
INTEGER, DIMENSION(:) :: DESCRA, INDX, BINDX  
INTEGER, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE  
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV  
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C
```

```
SUBROUTINE VBRSM_64(TRANSA, MB, [N], UNITD, DV, ALPHA, DESCRA,  
* VAL, INDX, BINDX, RPNTR, CPNTR, BPNTRB, BPNTRE,  
* B, [LDB], BETA, C,[LDC], [WORK], [LWORK])  
INTEGER*8 TRANSA, MB, UNITD  
INTEGER*8, DIMENSION(:) :: DESCRA, INDX, BINDX
```

```

INTEGER*8, DIMENSION(:) :: RPNTR, CPNTR, BPNTRB, BPNTRE
DOUBLE COMPLEX ALPHA, BETA
DOUBLE COMPLEX, DIMENSION(:) :: VAL, DV
DOUBLE COMPLEX, DIMENSION(:, :) :: B, C

```

C INTERFACE

```
#include <sunperf.h>
```

```

void zvbrsm (int transa, int mb, int n, int unitd,
doublecomplex *dv, doublecomplex *alpha, int *descra,
doublecomplex *val, int *indx, int *bindx, int *rpntr, int
*cpntr, int *bpntrb, int *bpntre, doublecomplex *b, int ldb,
doublecomplex *beta, doublecomplex *c, int ldc);

```

```

void zvbrsm_64 (long transa, long mb, long n, long unitd,
doublecomplex *dv, doublecomplex *alpha, long *descra,
doublecomplex *val, long *indx, long *bindx, long *rpntr,
long *cpntr, long *bpntrb, long *bpntre, doublecomplex *b,
long ldb, doublecomplex *beta, doublecomplex *c, long ldc);

```

DESCRIPTION

zvbrsm performs one of the matrix-matrix operations

```

C <- alpha op(A) B + beta C,      C <-alpha D op(A) B + beta C,
C <- alpha op(A) D B + beta C,

```

where alpha and beta are scalars, C and B are m by n dense matrices, D is a block diagonal matrix, A is a sparse m by m unit, or non-unit, upper or lower triangular matrix represented in the variable block sparse row format and op(A) is one of

```

op( A ) = inv(A) or op( A ) = inv(A') or op( A ) =inv(conjg( A' ))
(inv denotes matrix inverse, ' indicates matrix transpose).

```

The number of rows in A is determined as follows

```
m=RPNTR(MB+1)-RPNTR(1).
```

ARGUMENTS

TRANSA(input)	On entry, TRANSA indicates how to operate with the sparse matrix: 0 : operate with matrix 1 : operate with transpose matrix 2 : operate with the conjugate transpose of matrix. 2 is equivalent to 1 if matrix is real. Unchanged on exit.
MB(input)	On entry, integer MB specifies the number of block rows in the matrix A. Unchanged on exit.
N(input)	On entry, integer N specifies the number of columns in the matrix C. Unchanged on exit.
DV(input)	On entry, array DV contains the block entries of the block diagonal matrix D. The size of the J-th block is

RPNTR(J+1)-RPNTR(J) and each block contains matrix entries stored column-major. The total length of array DV is given by the formula:

$$\text{sum over J from 1 to MB:} \\ ((\text{RPNTR}(J+1)-\text{RPNTR}(J)) * (\text{RPNTR}(J+1)-\text{RPNTR}(J)))$$

Unchanged on exit.

ALPHA(input) On entry, ALPHA specifies the scalar alpha.
Unchanged on exit.

DESCRA (input) Descriptor argument. Five element integer array:

DESCRA(1) matrix structure

- 0 : general
- 1 : symmetric (A=A')
- 2 : Hermitian (A= CONJG(A'))
- 3 : Triangular
- 4 : Skew(Anti)-Symmetric (A=-A')
- 5 : Diagonal
- 6 : Skew-Hermitian (A= -CONJG(A'))

Note: For the routine, DESCRA(1)=3 is only supported.

DESCRA(2) upper/lower triangular indicator

- 1 : lower
- 2 : upper

DESCRA(3) main diagonal type

- 0 : non-identity blocks on the main diagonal
- 1 : identity diagonal blocks
- 2 : diagonal blocks are dense matrices

DESCRA(4) Array base (NOT IMPLEMENTED)

- 0 : C/C++ compatible
- 1 : Fortran compatible

DESCRA(5) repeated indices? (NOT IMPLEMENTED)

- 0 : unknown
- 1 : no repeated indices

VAL(input) On entry, scalar array VAL of length NNZ consists of the block entries of A where each block entry is a dense rectangular matrix stored column by column where NNZ denotes the total number of point entries in all nonzero block entries of the matrix A. Unchanged on exit.

INDX(input) On entry, INDX is an integer array of length BNNZ+1 where BNNZ is the number of block entries of the matrix A such that the I-th element of INDX[] points to the location in VAL of the (1,1) element of the I-th block entry. Unchanged on exit.

BINDX(input) On entry, BINDX is an integer array of length BNNZ consisting of the block column indices of the block entries of A where BNNZ is the number block entries of the matrix A. Block column indices MUST be sorted in increasing order for each block row. Unchanged on exit.

RPNTR(input) On entry, RPNTR is an integer array of length MB+1 such that RPNTR(I)-RPNTR(1)+1 is the row index of the first point row in the I-th block row. RPNTR(MB+1) is set to M+RPNTR(1) where M is the number of rows in the matrix A.

Thus, the number of point rows in the I-th block row is RPNTR(I+1)-RPNTR(I). Unchanged on exit.

NOTE: For the current version CPNTR must equal RPNTR and a single array can be passed for both arguments

CPNTR(input) On entry, CPNTR is integer array of length KB+1 such that CPNTR(J)-CPNTR(1)+1 is the column index of the first point column in the J-th block column. CPNTR(KB+1) is set to K+CPNTR(1) where K is the number of columns in the matrix A. Thus, the number of point columns in the J-th block column is CPNTR(J+1)-CPNTR(J). Unchanged on exit.

NOTE: For the current version CPNTR must equal RPNTR and a single array can be passed for both arguments

BPNTRB(input) On entry, BPNTRB is an integer array of length MB such that BPNTRB(I)-BPNTRB(1)+1 points to location in BINDX of the first block entry of the I-th block row of A. Unchanged on exit.

BPNTRE(input) On entry, BPNTRE is an integer array of length MB such that BPNTRE(I)-BPNTRB(1) points to location in BINDX of the last block entry of the I-th block row of A. Unchanged on exit.

B (input) Array of DIMENSION (LDB, N). Before entry with TRANSA = 0, the leading k by n part of the array B must contain the matrix B, otherwise the leading m by n part of the array B must contain the matrix B. Unchanged on exit.

LDB (input) On entry, LDB specifies the first dimension of B as declared in the calling (sub) program. Unchanged on exit.

BETA (input) On entry, BETA specifies the scalar beta. Unchanged on exit.

C(input/output) Array of DIMENSION (LDC, N). Before entry with TRANSA = 0, the leading m by n part of the array C must contain the matrix C, otherwise the leading k by n part of the array C must contain the matrix C. On exit, the array C is overwritten by the matrix $(\alpha * \text{op}(A) * B + \beta * C)$.

LDC (input) On entry, LDC specifies the first dimension of C as declared in the calling (sub) program. Unchanged on exit.

WORK(workspace) Scratch array of length LWORK. On exit, if LWORK= -1, WORK(1) returns the optimum size of LWORK.

LWORK (input) On entry, LWORK specifies the length of WORK array. LWORK should be at least $M = \text{RPNTR}(\text{MB}+1) - \text{RPNTR}(1)$. For good performance, LWORK should generally be larger. For optimum performance on multiple processors, $LWORK \geq M * N_CPUS$ where N_CPUS is the maximum number of processors available to the program.

If LWORK=0, the routine is to allocate workspace needed.

If LWORK = -1, then a workspace query is assumed; the routine only calculates the optimum size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued by XERBLA.

SEE ALSO

Libsunperf SPARSE BLAS is parallelized with the help of OPENMP and it is fully compatible with NIST FORTRAN Sparse Blas but the sources are different. Libsunperf SPARSE BLAS is free of bugs found in NIST FORTRAN Sparse Blas. Besides several new features and routines are implemented.

NIST FORTRAN Sparse Blas User's Guide available at:

<http://math.nist.gov/mcsd/Staff/KRemington/fspblas/>

Based on the standard proposed in

"Document for the Basic Linear Algebra Subprograms (BLAS) Standard", University of Tennessee, Knoxville, Tennessee, 1996:

<http://www.netlib.org/utk/papers/sparse.ps>

NOTES/BUGS

1. No test for singularity or near-singularity is included in this routine. Such tests must be performed before calling this routine.
2. If `DESCRA(3)= 0` , the lower or upper triangular part of each diagonal block is used by the routine depending on `DESCRA(2)`.
3. If `DESCRA(3)=1` , the diagonal blocks in the variable block row representation of A don't need to be the identity matrices because these block entries are not used by the routine in this case.
4. If `DESCRA(3) = 2` , diagonal blocks are considered as dense matrices and the LU factorization with partial pivoting is used by the routine. `WORK(1)=0` on return if the factorization for all diagonal blocks has been completed successfully, otherwise `WORK(1) = - i` where `i` is the block number for which the LU factorization could not be computed.
5. The routine is designed so that it checks the validity of each sparse block entry given in the sparse blas representation. Block entries with incorrect indices are not used and no error message related to the entries is issued.

The feature also provides a possibility to use the sparse matrix representation of a general matrix A for solving triangular systems with the upper or lower block triangle of A. But `DESCRA(1)` MUST be equal to 3 even in this case.

Assume that there is the sparse matrix representation a general matrix A decomposed in the form

$$A = L + D + U$$

where L is the strictly block lower triangle of A, U is the strictly block upper triangle of A, D is the block diagonal matrix. Let's I denotes the identity matrix.

Then the correspondence between the first three values of `DESCRA` and the result matrix for the sparse representation of A is

DESCRA(1)	DESCRA(2)	DESCRA(3)	RESULT
3	1	1	$\alpha * \text{op}(L+I) * B + \beta * C$
3	1	0	$\alpha * \text{op}(L+D) * B + \beta * C$
3	2	1	$\alpha * \text{op}(U+I) * B + \beta * C$
3	2	0	$\alpha * \text{op}(U+D) * B + \beta * C$

6. It is known that there exists another representation of the variable block sparse row format (see for example Y.Saad, "Iterative Methods for Sparse Linear Systems", WPS, 1996). Its data structure consists of six array instead of the seven used in the current implementation. The main difference is that only one array, IA, containing the pointers to the beginning of each block row in the array BINDX is used instead of two arrays BPNTRB and BPNTRE. To use the routine with this kind of variable block sparse row format the following calling sequence should be used

```

SUBROUTINE ZVBRSM( TRANSA, MB, N, UNITD, DV, ALPHA, DESCRA,
*                 VAL, INDX, BINDX, RPNTR, CPNTR, IA, IA(2),
*                 B, LDB, BETA, C, LDC, WORK, LWORK )

```

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NAME

zvmul - compute the scaled product of complex vectors

SYNOPSIS

```
SUBROUTINE ZVMUL(N, ALPHA, X, INCX, Y, INCY, BETA, Z, INCZ)
```

```
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX X(*), Y(*), Z(*)  
INTEGER N, INCX, INCY, INCZ
```

```
SUBROUTINE ZVMUL_64(N, ALPHA, X, INCX, Y, INCY, BETA, Z, INCZ)
```

```
DOUBLE COMPLEX ALPHA, BETA  
DOUBLE COMPLEX X(*), Y(*), Z(*)  
INTEGER*8 N, INCX, INCY, INCZ
```

F95 INTERFACE

```
SUBROUTINE VMUL([N], ALPHA, X, [INCX], Y, [INCY], BETA, Z, [INCZ])
```

```
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: X, Y, Z  
INTEGER :: N, INCX, INCY, INCZ
```

```
SUBROUTINE VMUL_64([N], ALPHA, X, [INCX], Y, [INCY], BETA, Z, [INCZ])
```

```
COMPLEX(8) :: ALPHA, BETA  
COMPLEX(8), DIMENSION(:) :: X, Y, Z  
INTEGER(8) :: N, INCX, INCY, INCZ
```

C INTERFACE

```
#include <sunperf.h>
```

```
void zvmul(int n, doublecomplex *alpha, doublecomplex *x,  
          int incx, doublecomplex *y, int incy, doublecom-  
          plex *beta, doublecomplex *z, int incz);
```

```
void zvmul_64(long n, doublecomplex *alpha, doublecomplex  
             *x, long incx, doublecomplex *y, long incy, doub-  
             lecomplex *beta, doublecomplex *z, long incz);
```

PURPOSE

zvmul computes the scaled product of complex vectors:
$$z(i) = \text{ALPHA} * x(i) * y(i) + \text{BETA} * z(i)$$
for $1 \leq i \leq N$.

ARGUMENTS

N (input)
Length of the vectors. $N \geq 0$. ZVMUL will return immediately if $N = 0$.

ALPHA (input)
Scale factor on the multiplicand vectors.

X (input) dimension(*)
Multiplicand vector.

INCX (input)
Stride between elements of the multiplicand vector X.

Y (input) dimension(*)
Multiplicand vector.

INCY (input)
Stride between elements of the multiplicand vector Y.

BETA (input)
Scale factor on the product vector.

Z (input/output) dimension(*)
Product vector. On exit, $z(i) = \text{ALPHA} * x(i) * y(i) + \text{BETA} * z(i)$.

INCZ (input)
Stride between elements of Z.